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 (57) Abstract:

A remote demolition robot (10) comprising a controller (17), drive means (14), an arm member (11) movably arranged on a tower (10a) rotatably arranged on a body (10a,10b) of the remote demolition robot (10) and a remote control (22) for providing commands, that are interpreted by the controller (17) causing the controller (17) to control the operation of the remote demolition robot (10), wherein the remote control (22) comprises a first joystick (24a) and a second joystick (24b), wherein the remote control (22) is **characterized in that** each joystick (24) is provided with a thumb control switch (26).

