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(54) **Throttle control method and device for operating internal combustion engines**

Verfahren und Vorrichtung zur Drosselsteuerung für den Betrieb von Brennkraftmaschinen

Procédé et dispositif pour commander l'étranglement lors du fonctionnement de moteurs à combustion interne

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Description

This invention relates to a throttle control method and device for operating internal combustion engines and, more particularly, but not exclusively, internal combustion engines installed in motor vehicles and, still more particularly, heavy duty motor vehicles.

Still more particularly the invention relates to throttle control which is aimed at diminishing the adverse effects of manipulating the throttle control mechanism or accelerator in an undesirable or highly uneconomic manner. The adverse effect of particular interest is poor fuel consumption, as well as the increased wear and tear associated with poor or abusive throttle control.

The invention is most particularly concerned with diesel powered engines but the same principles generally apply to other engines and the scope hereof is intended to include such other engines.

In this specification the term "manual" or "manually" will be used to mean by human effort irrespective of whether a hand or foot is used. Thus the term "manually operable" includes foot operable.

Diesel engines are widely used in many different applications. Probably the most common of these is in motor transport vehicles but numerous other applications include agricultural tractors; earth working machines such as bulldozers, front end loaders, mechanical shovels and the like; fork lift trucks, cranes and locomotives as well as mechanical coal picks; and, stationary applications such as air compressors and the like.

In most of these applications the engine is required to accommodate varying loads and to provide maximum power at times, and regularly, for significant periods of time, after which reduced power, or in fact no power, may be demanded for other periods of time.

Irrespective of the sophistication of the throttle control means for such diesel engines, at least in the vast majority of instances, when such an engine is operated at maximum or near maximum throttle to achieve maximum or near maximum power from the engine, a correspondingly large amount of fuel is injected into the cylinders of such an engine. This invariably manifests itself in a significant amount of fuel being wasted in the form of partly burnt fuel emitted as black smoke. The emission of such black smoke very often continues for so long as the throttle control mechanism is at or near full throttle settings.

It is generally accepted that the provision of a substantially rich fuel mixture in the cylinders is desirable for providing maximum power as and when required. Furthermore, as the engine speed increases, less fresh air is introduced into the cylinders at each stroke although, applicant believes, there is not a corresponding reduction in the amount of fuel introduced into the cylinders.

Whatever the cause or rationale of the factors set out above, there is a significant amount of fuel wastage associated with the present throttle operating method and in consequence of presently employed control devices.

It follows that the manner in which the throttle controlling the supply of fuel to an internal combustion engine is manipulated determines, to a substantial extent, the fuel efficiency with which the internal combustion engine operates and, also, to at least some extent, the wear and tear inflicted on the engine. Whilst these comments apply also to stationary internal combustion engines, the problem is, for the most part, most serious in internal combustion engines of motor vehicles, and in particular, heavy duty motor vehicles.

Simply as an example, applicant believes that it is undesirable, or at best uneconomical, to move the accelerator pedal of a motor vehicle too rapidly to open the throttle (usually evidenced by a puff of smoke from the exhaust); to "pump" or repeatedly move the accelerator pedal to open and close the throttle, in particular from a fully closed to a fully open position; or, to maintain the throttle fully open, or nearly so, for extended periods of time. Such operation of the throttle will be termed "undesirable" in this specification.

All these ways of manipulating a throttle control mechanism or accelerator result in considerable wastage of fuel and also unnecessary wear and tear on the engine.

In an initial attempt to combat the wastage of fuel consequent on such "undesirable" manner of manipulating a throttle control mechanism, I disclosed in my South African Patent No. 81/4519 a device which "sensed" when a throttle control mechanism was in a position corresponding to an undesirably open throttle, and issued an audible signal in the form of a "bleep" to warn the driver to correct the situation. If the driver did not correct the situation within a predetermined period of time, of the order of a few seconds, a "driving fault" would be recorded against the driver. At the same time, the throttle control mechanism, which included a lost motion linkage, would be automatically operated to render it impossible for the driver to use full throttle until the accelerator pedal had been fully released, at which stage the lost motion mechanism would be reset.

Whilst the device proposed in my earlier patent had a generally beneficial effect, it suffers from certain deficiencies, particularly in that the lost motion mechanism may become operative when the driver is in a critical stage of driving and requires the additional power corresponding to a fully or near fully open throttle condition.

Other lost motion linkage assemblies are known in the art for the control of engine and road speeds. See U S Patent Nos. 2188704; 3520380 and 3952714.

Also, substantial additional research and development as well as extensive tests, have revealed certain throttle control effects and highly unexpected results which can be achieved by the use of a lost motion linkage, of the general nature described have been achieved.

It is accordingly the object of this invention to pro-

vide a throttle control method and assembly of the general type envisaged in my said earlier patent, but wherein the realities of the necessity of requiring full or nearly full throttle at certain times during which driving is taking place are taken into consideration and which, more importantly do not detract from the practical use of the vehicle or engine.

In accordance with one aspect of this invention there is provided a method of operating an internal combustion engine of the type having a manually operable throttle operating mechanism operatively connected to fuel supply control means for the internal combustion engine; the method comprising, each time full or near full throttle is demanded by the operation of the throttle operating mechanism, allowing the fuel supply control means to adopt a corresponding full or near full throttle condition for a period of time, following which the fuel supply control means is moved to the reduce fuel flow to the internal combustion engine; the method being characterised in that the extent to which the fuel supply control means is moved to reduce fuel flow to the engine is chosen such that, at constant load, in spite of the reduction in fuel flow to the engine, the speed of rotation of the engine remains substantially unaffected at the prevailing load.

A particularly important further feature of this aspect of the invention provides for the fuel supply control means to be automatically moved to reduce fuel flow to the internal combustion engine irrespective of the fact that the manually operable throttle operating mechanism remains in a position corresponding to full or near full throttle; and, in such a case, for full throttle operation of the fuel supply control means to be allowed again only subsequent to the manually operable throttle operating mechanism having been moved to a predetermined extent towards a position corresponding to a closed condition of the throttle.

Further features of the invention provide for a linkage which selectively provides for lost motion to be included in the throttle operating mechanism in which case movement of the fuel supply control means to reduce fuel flow to the engine is brought about by activating or de-activating the linkage to provide for said lost motion; for the degree of said lost motion to be adjustable so that the extent of reduction of fuel flow to the engine can be set so as not to significantly affect the engine speed under the prevailing load as required by this invention; and for said reduction in fuel flow to range between 5 and 50% depending on engine characteristics, operating conditions and the like.

The invention also provides a control assembly for operating an internal combustion engine and for controlling the operation of fuel supply control means associated with an internal combustion engine and wherein the fuel supply control means is activated by a manually operable throttle operating mechanism, the control assembly including reduction means for reducing fuel flow to the engine by way of the fuel supply control means when the manually operable throttle operating mechanism is in a full or near full throttle condition, said control assembly including delay means allowing full throttle condition of the fuel supply control means for a predetermined period of time (a first condition of the control assembly) following which said control assembly is operable to reduce the fuel supply to the engine with the manually operable operating means remaining in a condition corresponding to full or near full throttle (a second condition of the control assembly); said control assembly being adjustable such that the extent to which fuel flow to the engine is reduced can be set to provide a fuel flow reduction having substantially no affect on the engine speed under a prevailing constant load.

Further features of the invention provide for reduction means to be a throttle limiting unit having a first condition in which full operation of a throttle is allowed, and a second condition in which somewhat restricted operation of the throttle is available so as to prevent full throttle opening in which case a controller (forming part of the control assembly) is adapted to select which of the two conditions prevail at any particular time; for sensing means to be provided for detecting the extent of throttle opening or position of the throttle operating mechanism at any time; for the delay means to be embodied in the controller; for the internal combustion engine to be that of a motor vehicle, in particular a diesel engine of a heavy duty motor vehicle; and for the throttle limiting unit to be linkage which selectively provides for lost motion in a throttle linkage in said second condition.

Still further features of the invention provide for the controller to embody a micro-processor which is adapted to enable the controller operation to be set, selectively, according to signals received from the sensing means, between two different sets of parameters, one corresponding to "city" driving conditions, and one corresponding to "country" driving conditions; for the controller to be adapted to determine the rate of change of position of the throttle mechanism and, under "city" driving conditions, to cause the throttle limiting unit to adopt the second condition in the event that the throttle operating mechanism is moved excessively rapidly; for the controller to be adapted to count the number of accelerator movements within a predetermined time interval corresponding to normal acceleration of a vehicle through the gears and to cause the throttle limiting unit to adopt the second condition when in excess of a predetermined number of throttle operations has been detected within such time interval; for the said period of time to be substantially longer in the "country" driving mode than in the "city" driving mode to provide maximum safety during long overtaking movements; for the controller to be adapted to sense the difference between "city" driving conditions and "country" driving conditions in consequence of the time period during which the throttle is maintained in certain positions corresponding to town or country driving behaviour; and for the rate of change of the position of the throttle operating mecha-

nism to be rendered ineffective in the "country" driving condition.

In accordance with another aspect of this invention there is provided sensing means suitable for use in a device as defined above and comprising two parts each adapted for connection directly or indirectly one to a movable part of a throttle operating mechanism, and one to a part which is stationary relative thereto, and wherein the one part comprises a coil and the other part comprises a magnetic substance, the relationship being such that movement of the magnetic substance relative to the coil causes changes in the inductance of the coil with a consequent change in frequency of a signal applied thereto.

Further features of this aspect of the invention provide for the magnetic member to be in the form of an elongate member movable into and out of a hollow core of the coil; for the coil to be energised by a suitable oscillator; and for the elongate magnetic member to be in the form of a rod, in particular a ferrite rod.

The invention still further provides for the throttle limiting unit to be maintained in said first condition by means of an electromagnetic coil in which case the invention provides that, preferably, the polarity of the electrical supply to the electromagnetic coil is reversed at the instant when it is required that the second condition of the throttle limiting unit be adapted. Most conveniently the throttle limiting unit is a linear link of the general type described in my European Patent Application No. 93307446.0 filed 21 September 1993.

The invention still further provides for the controller to be programmable as to the exact conditions under which the throttle limiting unit assumes the second condition; in particular the number of accelerator operations allowed in a predetermined time period; the time period for which the accelerator can remain in a fully or excessively depressed condition both in the "town" and "country" driving modes; for the controller to embody an EPROM which renders it programmable; for the programming to be effected by way of a releasable separate programmer unit; and for the programmer unit to assume two different forms, one sophisticated form for effecting major programming at a factory or major installation centre; and, a small unit for effecting minor programming after installation of the control assembly in a vehicle.

In order that the invention may be more fully understood an expanded description thereof, and a description of various embodiments and aspects of the invention, will now follow with reference being made to the accompanying drawings.

In the drawings:-

Fig. 1 is a schematic illustration of a motor vehicle diesel fuel injection pump and accelerator assembly with which is associated a control assembly according to one embodiment of this invention;

FIG. 2 is an enlarged sectional elevation of one form of linear link providing selectively for lost motion and which may be embodied in the throttle linkage arrangement;

FIG. 3 is a schematic sectional elevation of a sensor constituting the sensing means of this embodiment of the invention;

FIG. 4 is a block diagram of the controller circuitry;

FIG. 5 is a graph illustrating a typical set of power versus engine speed; torque versus engine speed, and fuel consumption versus engine speed curves;

FIG. 6 is a schematic illustration of a diesel pump and simple accelerator linkage adapted to operate according to this invention; and,

FIG. 7 is a longitudinal sectional elevation of an alternative form of linkage providing for an effective reduction in its length.

In the embodiment of the invention illustrated in the drawings the throttle control assembly provided by this invention is associated with a diesel pump 1 having the usual throttle control arm 2 rotatable about a pivot 3. Various extents of rotation of the arm are illustrated in Fig. 1 as being 100%, 98%, and 75% of full opening and the three positions are indicated by numerals 3, 4, and 5 respectively. The significance of this will become more apparent later.

The throttle control lever 2 is illustrated as being moved by a simple, single, axially movable rod 6 embodying within its length a linear link lost motion unit 7 which forms the throttle limiting unit identified above. The rod is shown, for simplicity, as being operated directly by an accelerator pedal 8 whereas, as will be known by those skilled in the art, various different mechanisms are used to convey the motion of an accelerator pedal to the throttle control lever.

The linear link 7 is more fully described in my aforementioned European Patent No. 93307446.0 and the description in that complete patent application is included herein by reference. Basically, the linear link comprises two telescopically movable units which are lockable, by means of a solenoid latching mechanism, in a relatively extended position whilst the solenoid is energised and, when the solenoid is de-energised, are allowed to move relative to each other to collapse the length of the linear link to an adjustable extent and provide for lost motion between the accelerator pedal and throttle control arm.

A number of different detailed embodiments of linear link are described in my earlier patent and reference can be had to the specification of that patent for the various arrangements. For the purpose of the present pat-

ent application only one embodiment will be described herein simply in order to make the disclosure in this specification comprehensive. This linear link will now be described with reference to Fig. 2.

In the arrangement illustrated in Fig. 2, the linear link is of a nature adapted to be in compression when the accelerator pedal is depressed in order to increase fuel flow to the engine. It will be understood by those skilled in the art that there are numerous arrangements in which a linear link of this -nature may be in tension in order to open the throttle of an engine and, in such a case, the linear link would be modified as described in my said earlier patent. As illustrated, the linear link 7 comprises basically a composite outer member 8 having a longitudinal bore therethrough and within which is a telescopically movable inner member 9 in the form of a rod.

The inner member has, at its one end, a first coupling member 10 secured thereto by means of a screw-threaded spigot 11 extending into a complimentarily screw-threaded socket 12 on the first coupling member 10. At the other end of the inner member, is a screw-threaded zone 13 on which is located a complimentarily screw-threaded stop member 14 which is axially adjustable in position. In the absence of the arrangement hereinafter described, the outer member is freely movable between a position in which the first coupling member 10 abuts the adjacent end 15 of the outer member and a position in which an inwardly directed flange 16 prevents the stop member 14 from moving further into the outer member.

The extent of this free movement is therefore adjustable, firstly by adjusting the position of the screw-threaded stop member 14 at the one end of the rod and, secondly, by adjusting the extent to which the other screw-threaded end 11 of the rod projects into the screw-threaded socket 12. The stop member 14 is releasably locked in position by means of a lock nut 17 whilst the socket 12 is locked to the screw-threaded spigot 11 by means of a grub screw 18 engaging on suitable flat surfaces 19 provided on the screw threaded spigot.

The two members are spring biased by means of a compression spring 20 acting between the stop member 14 and a blind end 21 to a tubular second coupling member 22 secured at its open end 23 to the outer member 8 and having at its closed end a screw-threaded spigot 24 extending therefrom.

Carried on the outside of the outer member is a coaxial solenoid coil 25. Axially adjacent to the solenoid coil, the wall of the outer member is provided with four equally angularly spaced perforations 26 each of which serves to locate a steel catch element in the form of a spherical ball 27. These balls are held captive by an inner truncated conical surface 28 of an axially movable retainer member 29. The truncated conical surface is directed with the larger end towards the solenoid coil and a light spring 30 urges the retainer member towards the solenoid coil.

In the telescopically extended condition of the linear link as illustrated in Fig. 2, the inner member has a circumferential groove 31 in its outer surface in a position exactly opposite the steel balls 27. The retainer member thus urges the steel balls into engagement with the groove.

This arrangement is such that when the solenoid is de-energised, the strength of the spring 30 is insufficient to prevent the axial compression in the linear link from moving the balls out of the groove and accordingly providing for free movement of the rod within the outer member to the extent allowed by the first coupling 10. A predetermined amount of lost motion, which is adjustable, is therefore provided.

Accordingly, with the balls engaged in the groove 31 in the rod and the solenoid energised, the linear link acts as an incompressible compression member whereas, with the solenoid de-energised, the degree of lost motion indicated is provided.

From the above it will be understood that, when the linear link 7 is in the first condition with the solenoid energised, and the link is fully extended, 100% of the possible movement of the throttle control arm 2 can be achieved by movement of the accelerator pedal.

However, when the linear link is in a collapsed condition (ie. the second condition described above and when the solenoid is de-energised) there is lost motion in the movement of the accelerator pedal and throttle control lever so that only a proportion of the maximum movement of the throttle control lever can be achieved. It is this degree of lost motion that will give rise to the different extents of possible movement of the throttle control lever indicated by arcs numeral 4 and 5 which corresponds to 98% and 75% of full movement respectively. These arcs of movement correspond to the maximum economic movement of the throttle control lever and will vary from vehicle to vehicle the figures of 98% and 75% simply being arbitrary examples. The exact extent of rotational movement of the control lever which is allowed is adjustable by means of adjustable stop 14 and first coupling 10 provided on the linear link.

The position of the accelerator pedal which corresponds to the maximum throttle opening in the second condition will, for ease of description, be termed the "latch" position of the accelerator.

Reverting now to the supply of electrical energy to the solenoid, this is controlled by a controller 40 and the electrical energy for both the controller and the solenoid are obtained from the motor vehicle battery 41.

The controller is also connected to a sensor unit 42 which has a linearly movable member 43 connected to the throttle control arm 2, or any other suitable part which moves in unison with accelerator pedal 8. Conveniently, the linearly movable member can be the inner of a Bowden cable 44.

Referring now more particularly to Fig. 3, the sensing unit comprises a circular cross-sectioned elongate

coil 45 fixed relative to a housing 46 and wherein the linearly movable member 43 is attached to a ferrite core 47 movable axially into and out of the hollow core of the coil 45. The ferrite core 47 is biased by means of a compression spring 48 to the inner position and the linearly movable member 43 is adapted to pull the ferrite core out of the coil according to movement of the throttle control lever and thus the accelerator pedal. The arrangement is such that the axial position of the core relative to the coil dictates the frequency of a signal applied to the coil in consequence of the varying inductance of the coil.

The controller co-operates with the sensor unit so that information concerning the position of the core within the coil, or the rate of movement of the core into or out of the coil, can be determined by the controller 40.

Turning now more particularly to Fig. 4, the various functional circuits of the controller are shown in block form. The controller comprises basically a microprocessor 49 connected to a non-volatile EPROM memory 50 which stores the required programmable information. The micro-processor operates, by way of a pulse width modulator controller 51, a linear link controller 52 which controls the power supply to the solenoid of the linear link. The linear link controller is adapted to apply a reverse polarity to the solenoid momentarily at the instant of de-energisation of the solenoid to ensure proper disengagement of the retainer. A feedback circuit 53 is provided from the linear link controller.

The input, which is basically a frequency input 54 from the sensor, is fed to the microprocessor. Also a power fail detection circuit 55 for the purpose of indicating if the power was removed from the controller is provided.

Any required LED indicators can be provided and, in particular, an LED indicator may especially be provided to indicate whether or not the unit has been tampered with, in particular whether or not the power supply to the unit has been tampered with. Further, if no activity is detected within the microprocessor whilst the motor vehicle ignition is on, the tamper light will be ignited.

Another LED may be installed in the drivers vision to indicate, for example by a slow flash, that the linear link is de-latched and by a fast flash that the controller has detected a full or near full throttle condition of the accelerator.

As indicated above, the microprocessor is programmable and the following is an outline of the items which can be programmed or made adjustable as may be required.

The microprocessor is programmed such that the following activities are allowed or cause de-activation of the solenoid of the linear link to thereby cause the linear link to collapse or adopt the second condition described above.

(i) The accelerator is depressed past the latch position for greater than a preset period of time. The time period is sufficiently large to accommodate the normal period of time for which a vehicle is in any gear during a normal series of gear changes to accelerate, for example, from a stand-still. The latter situation exists in the "city" driving mode. However, in the "country" driving mode this time period is substantially greater and is sufficient to allow any normal overtaking to be done with the accelerator past the latch position in order to maintain maximum power and, accordingly, maximum safety.

(ii) The microprocessor counts the number of times that the accelerator pedal is depressed past the latch position in a certain time interval. This number is programmable according to the number of gears which the vehicle has, and the manner in which gear changes are achieved. Depressing of the accelerator in excess of the preset number of times will cause the linear link to de-latch and the lost motion to limit the movement of the throttle lever arm 2.

(iii) The microprocessor also records the rate of movement of the accelerator pedal, at least in the "city" driving mode and, if the accelerator pedal is depressed at a speed in excess of a suitable speed, the linear link is de-latched and the throttle limiting unit assumes the second condition in which throttle opening is limited. The rate of movement of the accelerator to the open position is rendered irrelevant in the "country" driving mode in order that a driver can accelerate as fast as possible in order to avoid a possibly dangerous situation.

(iv) The number of occasions on which the linear link de-latches is also monitored by the controller and, in the event that de-latching occurs in excess of a predetermined number of times in a predetermined time period de-latching will occur for a prolonged period of time for example 15 minutes, as a sanction to the driver.

(v) The microprocessor detects when the accelerator has been depressed to an appreciable extent for a duration of time commensurate with "country" driving behaviour and automatically switches over to the "country" driving mode. It automatically reverts to "city" driving mode when the accelerator is substantially released for a short time period.

It will be understood that with the set of variables described, the microprocessor can be programmed so that all normal and necessary driving behaviour, insofar as the accelerator is concerned, is accommodated, and the linear link does not become de-activated, and therefore operative to limit the extent to which the throttle can be opened, whilst satisfactory driving of a vehicle is taking place.

The variables are programmable into the micro-

processor and associated EPROM by means of a comprehensive programming unit 56 which has an input keyboard and other necessary switches to programme the controller for the type of vehicle with which it is to be used and to include various other variables. This comprehensive programmer unit is simply plugged into the controller as and when required.

In addition, a simple and inexpensive programmer unit 57 can also be plugged into the controller and this programmer unit simply enables the controller, once set for a particular type of vehicle, to be set for the individual vehicle in which it is mounted. This programmer unit enables the controller to be set according to the output from the sensor unit in the idle position of the accelerator pedal; in the 100% depressed condition of the accelerator pedal; and in the selected percentage position of the accelerator pedal chosen according to the vehicle performance figures and set manually on the adjustment nuts of the linear link.

In the latter regard, and referring to Fig. 5, it has been established that the most efficient operating engine speed of a diesel engine is in a predetermined range on the fuel consumption graph being indicated by numeral 58. The percentage of full throttle permitted in the de-latched position (second condition) is chosen such that the engine speed is at or just below the minimum fuel consumption point on the curve as indicated by numeral 58 so that, with the accelerator pedal fully depressed, the engine will be operating at approximately maximum efficiency. As indicated above, the setting of the exact position mechanically is achieved by adjustment nuts or the like associated with the linear link whilst the electrical limits are set using the small or large programmer.

The embodiment of the invention described above is aimed at transport vehicles. However, it may well be that a very much simplified arrangement can be used in other applications, such as agricultural tractors and such an embodiment is described with reference to Fig. 6.

In this case the control arm 60 of the diesel fuel pump 61 is attached, by means of a connection element 62 to a simple switch 63. The switch is connected to a controller 64 which embodies a simple timer, and the apparatus is powered by the motor vehicle battery 65.

In this case a linear link 66 providing for lost motion, and substantially as described above, is included in the linkage 67 connecting the fuel control arm 60 with the accelerator pedal 68.

The linear link 66 is arranged such that lost motion is provided when the solenoid is de-energised through the action of the controller 64 and switch 63.

The switch 63 is such that it is closed when the fuel control arm 60 is in a full throttle or near full throttle condition, and this causes a timer in the controller to operate. After the expiry of the predetermined time, the solenoid is de-energised to provide for lost motion in the linear link, and a corresponding reduction in the fuel supplied to the associated engine, by virtue of the fact that the control arm moves towards a closed position, by a predetermined extent.

In the case of an agricultural tractor working the lands, it has been found that a time period of about 6 - 10 seconds is adequate to enable the tractor to accelerate to working speed, and to adapt to the load of the ground working or other implement attached thereto, with full fuel flow being provided during this time period. After the lapse of the predetermined time period of between 6 and 10 seconds the solenoid in the linear link is de-energised and the lost motion is introduced. Accordingly, the fuel supply is diminished by a predetermined extent.

The extent of the lost motion is, as indicated above, adjusted so that when the fuel supply becomes diminished there is substantially no loss in engine speed. Practical tests conducted on a agricultural tractor fitted with a linear link as described above have indicated that the only noticeable difference in performance is the absence of black smoke in the exhaust emission. Also the agricultural tractor fitted with the device operating according to the invention operated at a more consistent engine speed than an identical agricultural tractor run co-temporaneously but not fitted with the device.

The time period of 6 to 10 seconds may be made to apply only in the "working" gears as those used in the field. In higher gears, used for "driving" or towing, the time period of 6 to 10 seconds may need to be extended.

It is envisaged that exactly the same principles and advantages will pertain to application of the invention to air compressors, or other earth working machinery, indeed diesel engines wherever they are accelerated and decelerated periodically as and when they are placed under load for various periods of time.

It is, however, envisaged that the invention will not be applicable to diesel engines which are placed under constant load for prolonged periods of time and wherein the effects of varying fuel supply to the engine are not of interest as the engine can be tuned to operate at its most efficient settings.

It is to be understood that the manner in which the reduced fuel supply is achieved after it has been at substantially full flow rate can be varied widely.

In particular, as illustrated in Fig. 7, a pneumatic or hydraulic piston and cylinder assembly could be employed in which an inlet-outlet 70 on one side of a piston 71 and an inlet-outlet 72 on the opposite side are simply controlled by means of a valve assembly 73, conveniently electrically operated, in consequence of the operation of a controller as described above. Screw-threaded adjustment nuts 74 and 75 enable the extent of the fuel supply reduction to be adjusted as required

Claims

1. A method of operating an internal combustion en-

gine of the type having a manually operable throttle operating mechanism (6, 67) operatively connected to fuel supply control means (2, 60) for the internal combustion engine; the method comprising, each time full or near full throttle is demanded by the operation of the throttle operating mechanism, allowing the fuel supply control means to adopt a corresponding full or near full throttle condition for a period of time, following which the fuel supply control means is moved to reduce the fuel flow to the internal combustion engine; the method being characterised in that the extent to which the fuel supply control means is moved to reduce fuel flow to the engine is chosen such that, at constant load, in spite of the reduction in fuel flow to the engine, the speed of rotation of the engine remains substantially unaffected at the prevailing load.

2. A method as claimed in claim 1 characterised in that the fuel supply control means is moved automatically to reduce such flow to the internal combustion engine irrespective of the fact that the manually operable throttle operating mechanism remains in a position corresponding to full or near full throttle.

3. A method as claimed in claim 2 characterised in that subsequent full throttle operation of the fuel supply control means is allowed again only subsequent to the manually operable throttle operating mechanism having been moved to a predetermined extent towards a position corresponding to a closed condition of the throttle.

4. A method as claimed in any one of the preceding claims characterised in that the movement of the fuel supply control means to reduce the fuel flow to the internal combustion engine is achieved by means of a linkage (7, 66) in the throttle operating mechanism which provides selectively for lost motion between the manually operable throttle operating mechanism and the fuel supply control means.

5. A method as claimed in claim 4 characterised in that the degree of lost motion is adjustable to adjust the extent of reduction of fuel flow to comply with the parameter of substantially not affecting the engine speed at a constant load when the reduction in fuel supply takes place.

6. A method as claimed in any one of the preceding claims characterised in that said period of time is adjustable or selectable according to engine operation conditions, or both.

7. A control assembly for operating an internal combustion engine and for controlling the operation of fuel supply control means (1) associated with an internal combustion engine and wherein the fuel supply control means is activated by a manually operable throttle operating mechanism (6), the control assembly including reduction means (7) for reducing fuel flow to the engine by way of the fuel supply control means when the manually operable throttle operating mechanism is in a full or near full throttle condition, said control assembly being characterised in that it includes delay means (40) allowing full throttle condition of the fuel supply control means for a predetermined period of time following which said control assembly is operable to reduce the fuel supply to the engine with the manually operable operating means remaining in a condition corresponding to full or near full throttle; said control assembly being in use adjustable such that the extent to which fuel flow to the engine is reduced can be set to provide a fuel flow reduction having substantially no affect on the engine speed under a prevailing constant load.

8. A control assembly as claimed in claim 7 characterised in that the reduction means is a throttle limiting unit (7) having a first condition in which full operation of the throttle is allowed and a second condition in which somewhat restricted operation of the throttle is available so as to prevent full throttle opening and a controller forming part of the control assembly is adapted to select which of the two conditions prevail at any particular time.

9. A control assembly is claimed in claim 8 characterised in that the delay means is embodied in the controller and sensing means (42) for detecting the throttle opening or position of the throttle operating mechanism are provided and connected to the controller to give a signal to the controller.

10. A control assembly as claimed in claim 9 characterised in that the controller embodies a micro-processor (49) which is adapted to enable the controller operation to be set to initiate said second condition of the control assembly according to signals received from the sensing means.

11. A control assembly as claimed in claim 10 characterised in that the engine is a motor vehicle engine and two different sets of parameters associated with "undesirable" driving operations are selectable, in the alternative, one such set corresponding to "city" driving conditions and one corresponding to "country" driving conditions.

12. A control assembly as claimed in claim 11 characterised in that the micro-processor is programmed to select "city" or "country" driving conditions according to signals received from the sensing means which are characteristic of "city" or "country" driving, as the case may be.

13. A control assembly as claimed in claim 12 characterised in that the characteristic of "city" or "country" driving determined by the controller to be the fact that in "country" driving mode the throttle is significantly open for prolonged periods of time.

14. A control assembly as claimed in any one of claims 8 to 13 characterised in that the controller is adapted to sense the rate of change of position of the throttle mechanism and to cause the throttle limiting unit to adopt said second condition if such rate of change of positions is excessive.

15. A control assembly as claimed in claim 14 together with claim 14 characterised in that the said rate of change of position is rendered inactive in the "country" driving mode.

16. A control assembly as claimed in any one of claims 8 to 15 characterised in that the controller is adapted to bring about said second condition of the control assembly in the event of the number of throttle mechanism operations sensed in a predetermined time period exceeds a preset maximum number.

17. A control assembly as claimed in claim 16 characterised in that the preset maximum number is based on the number of gears of a vehicle in which the control assembly is fitted.

18. A control assembly as claimed in any one of claims 11 to 15 or 17 characterised in that the said predetermined time period from which the full throttle condition is provided is substantially longer in the country driving mode than in the city driving mode.

19. A control assembly as claimed in any one of claims 9 to 13 characterised in that the sensing means (42) comprises two parts (45, 47) each adapted for connection, directly or indirectly, one to a movable part (2) of a throttle operating mechanism and one to a part stationary relative thereto, and wherein the one part (45) comprises a coil and the other part (47) comprises a magnetic substance, the relationship being such that movement of the magnetic substance relative to the coil causes changes in the inductance of the coil with a consequent change in frequency of a signal applied thereto.

20. A control assembly as claimed in any one of claims 8 to 13 or 19 characterised in that the throttle limiting unit (7) is a linear link providing for lost motion in said second condition, the link being installed as a linkage in the throttle operating mechanism.

Patentansprüche

1. Verfahren zum Betreiben einer Brennkraftmaschine von der Art mit einem manuell zu betätigendem Drosselbetätigungsmechanismus (6, 67), der wirkungsmäßig mit Kraftstoffzufuhrsteuerungsmitteln (2, 60) für die Brennkraftmaschine verbunden ist, wobei das Verfahren umfaßt, daß jedesmal, wenn durch Betätigung des Drosselbetätigungsmechanismus Vollgas oder beinahe Vollgas angefordert wird, es zugelassen wird, daß die Kraftstoffzufuhrsteuerungsmittel für eine Zeitperiode einen entsprechenden Vollgaszustand oder einen Zustand von nahezu Vollgas annehmen, wonach die Kraftstoffzufuhrsteuerungsmittel bewegt werden, um den Kraftstoffzufluß zur Brennkraftmaschine zu reduzieren, wobei das Verfahren dadurch gekennzeichnet ist, daß der Grad, um den die Kraftstoffzufuhrsteuerungsmittel bewegt werden, um den Kraftstoffzufluß zum Motor zu reduzieren, so gewählt ist, daß, bei konstanter Last, trotz der Reduzierung des Kraftstoffzufluß zum Motor die Drehzahl des Motors bei der vorherschenden Last im wesentlichen unbeeinflußt bleibt.

2. Verfahren nach Anspruch 1, dadurch gekennzeichnet, daß die Kraftstoffzufuhrsteuerungsmittel automatisch bewegt werden, um den Zufluß zur Brennkraftmaschine zu reduzieren unabhängig von der Tatsache, daß der manuell zu betätigende Drosselbetätigungsmechanismus in einer Position entsprechend Vollgas oder nahezu Vollgas bleibt.

3. Verfahren nach Anspruch 2, dadurch gekennzeichnet, daß nach Vollgas die Betätigung der Kraftstoffzufuhrsteuerungsmittel nur wieder zugelassen wird, nachdem der manuell zu betätigende Drosselbetätigungsmechanismus in vorgegebenem Maße in Richtung einer Position bewegt worden ist, die einem Zustand geschlossenen Drossel entspricht.

4. Verfahren nach einem der vorhergehenden Ansprüche, dadurch gekennzeichnet, daß die Bewegung der Kraftstoffzufuhrsteuerungsmittel zum Reduzieren des Kraftstoffzuflusses zu der Brennkraftmaschine durch eine Kopplung (7, 66) in dem Drosselbetätigungsmechanismus erreicht wird, die für einen selektiven Totgang zwischen dem manuell betätigbaren Drosselbetätigungsmechanismus und den Kraftstoffzufuhrsteuerungsmitteln sorgt.

5. Verfahren nach Anspruch 4, dadurch gekennzeichnet, daß die Größe des Totgangs einstellbar ist, um den Grad der Reduzierung der Kraftstoffzufuhr einzustellen, um sich auf den Parameter einzustellen, die Motorgeschwindigkeit bei konstanter Belastung im wesentlichen nicht zu beeinträchtigen, wenn die Reduzierung in der Kraftstoffzufuhr vorgenommen

wird.

6. Verfahren nach einem der vorhergehenden Ansprüche, dadurch gekennzeichnet, daß die Zeitperiode einstellbar oder auswählbar gemäß Motorbetriebsbedingungen oder beides ist.

7. Steuerungsvorrichtung zum Betreiben einer Brennkraftmaschine und zum Steuern des Betriebs von Kraftstoffzufuhrsteuerungsmitteln (1), die zu einer Brennkraftmaschine gehören und die durch einen manuell betätigbaren Drosselbetätigungsmechanismus (6) aktiviert werden, wobei die Steuervorrichtung eine Reduzierungseinrichtung (7) zum Reduzieren des Kraftstoffzuflusses zur Maschine mittels der Kraftstoffzufuhrsteuerungsmittel, wenn der manuell betätigbare Drosselbetätigungsmechanismus sich in einem Vollgaszustand oder einem Zustand nahe Vollgas befindet, umfaßt, wobei die Steuerungsvorrichtung dadurch gekennzeichnet ist, daß sie eine Verzögerungseinrichtung (40) enthält, die den Vollgaszustand der Kraftstoffzufuhrsteuerungsmittel für eine vorgegebene Zeitperiode zuläßt, worauf folgend die Steuerungsvorrichtung betreibbar ist, um den Kraftstoffzufluß zur Maschine zu reduzieren, wobei die manuell betätigbaren Drosselbetätigungsmittel in einem Zustand entsprechend Vollgas oder nahezu Vollgas bleiben, wobei die Steuerungsvorrichtung im Betrieb so einstellbar ist, daß der Grad, bis zu dem der Kraftstoffzufluß zur Maschine reduziert wird, eingestellt werden kann, um eine Kraftstoffzuflußreduzierung zu erreichen, die im wesentlichen keine Auswirkung auf die Maschinengeschwindigkeit bei einer vorherrschenden konstanten Last hat.

8. Steuerungsvorrichtung nach Anspruch 7, dadurch gekennzeichnet, daß die Reduzierungseinrichtung eine Drosselbegrenzungseinheit (7) ist mit einem ersten Zustand, in dem die volle Funktion der Drossel zugelassen ist, und einem zweiten Zustand, in dem eine in gewissem Umfang eingeschränkte Funktion der Drossel zur Verfügung steht, um so eine vollständige Drosselöffnung zu verhindern, und daß eine Steuereinheit, die ein Teil der Steuerungsvorrichtung ist, dazu ausgelegt ist, auszuwählen, welcher der beiden Zustände zu jedem bestimmten Zeitpunkt vorherrschen soll.

9. Steuerungsvorrichtung nach Anspruch 8, dadurch gekennzeichnet, daß die Verzögerungseinrichtung in der Steuereinheit vorgesehen ist und daß Sensormittel (42) zum Detektieren der Drosselöffnung oder der Stellung des Drosselbetätigungsmechanismus vorgesehen sind und mit der Steuereinheit verbunden sind, um ein Signal an die Steuereinheit zu geben.

10. Steuerungsvorrichtung nach Anspruch 9, dadurch gekennzeichnet, daß die Steuereinheit einen Mikroprozessor (49) umfaßt, der dazu ausgelegt ist, um die Funktion der Steuereinheit zu ermöglichen, nach Maßgabe der von den Sensormitteln empfangenen Signale den zweiten Zustand der Steuerungsvorrichtung einzuleiten.

11. Steuerungsvorrichtung nach Anspruch 10, dadurch gekennzeichnet, daß die Maschine ein Kraftfahrzeugmotor ist und daß zwei verschiedene Sätze von Parametern verbunden mit "unerwünschten" Fahrbetriebszuständen als Alternativen auswählbar sind, wobei ein solcher Satz "Stadt"-Fahrbedingungen und ein Satz "Land"-Fahrbedingungen entspricht.

12. Steuerungsvorrichtung nach Anspruch 11, dadurch gekennzeichnet, daß der Mikroprozessor dazu programmiert ist, "Stadt"- oder "Land"-Fahrbedingungen nach Maßgabe von von den Sensormitteln empfangenen Signalen auszuwählen, die charakteristisch für "Stadt"- oder "Land"-Fahren sind, je nachdem, was der Fall ist.

13. Steuerungsvorrichtung nach Anspruch 12, dadurch gekennzeichnet, daß die Charakteristik für "Stadt"- oder "Land"-Fahren durch die Steuereinheit durch die Tatsache bestimmt wird, daß im "Land"-Fahrbetrieb die Drossel für längere Zeiträume erheblich geöffnet ist.

14. Steuerungsvorrichtung nach einem der Ansprüche 8 bis 13, dadurch gekennzeichnet, daß die Steuereinheit dazu ausgelegt ist, die Rate von Stellungswechseln des Drosselmechanismus zu detektieren und die Drosselbegrenzungseinheit dazu zu veranlassen, den zweiten Zustand anzunehmen, wenn diese Rate von Stellungswechseln zu groß ist.

15. Steuerungsvorrichtung nach Anspruch 14, zusammen mit Anspruch 14, dadurch gekennzeichnet, daß die Rate von Stellungswechseln im "Land"-Fahrbetrieb deaktiviert ist.

16. Steuerungsvorrichtung nach einem der Ansprüche 8 bis 15, dadurch gekennzeichnet, daß die Steuereinheit dazu ausgelegt ist, den zweiten Zustand der Steuerungsvorrichtung in dem Fall einzustellen, daß die Anzahl von Drosselmechanismusbetätigungen, die in einer vorgegebenen Zeitperiode detektiert werden, eine vorgegebene Maximalzahl überschreitet.

17. Steuerungsvorrichtung nach Anspruch 16, dadurch gekennzeichnet, daß die vorgegebene Maximalzahl auf der Anzahl der Gänge des Kraftfahrzeugs basiert, in das die Steuerungsvorrichtung einge-

baut ist.

18. Steuerungsvorrichtung nach einem der Ansprüche 11 bis 15 oder 17, dadurch gekennzeichnet, daß die vorgegebene Zeitperiode, in der der Vollgaszustand geleistet wird, im Land-Fahrbetrieb wesentlich länger ist als im Stadt-Fahrbetrieb.

19. Steuerungsvorrichtung nach einem der Ansprüche 9 bis 13, dadurch gekennzeichnet, daß die Sensormittel (42) zwei Teile (45, 47) aufweisen, die beide zur Anbringung, direkt oder indirekt, ausgelegt sind, eines an einem beweglichen Teil (2) des Drosselbetätigungsmechanismus und eines an einem Teil, das relativ dazu feststehend ist, und wobei das eine Teil (45) eine Spule und das andere Teil (47) magnetisches Material aufweist, die so zueinander in Beziehung stehen, daß die Bewegung des magnetischen Materials relativ zur Spule Änderungen in der Induktivität der Spule mit daraus resultierender Änderung in der Frequenz eines daran angelegten Signals bewirken.

20. Steuerungsvorrichtung nach einem der Ansprüche 8 bis 13 oder 19, dadurch gekennzeichnet, daß die Drosselbegrenzungseinheit (7) ein Lineargelenk ist, das im zweiten Zustand für Totgang sorgt, wobei das Gelenk als Gestänge in dem Drosselbetätigungsmechanismus eingebaut ist.

Revendications

1. Procédé pour faire fonctionner un moteur à combustion interne du type ayant un mécanisme d'actionnement d'étrangleur (6, 67), pouvant être actionné manuellement, relié de manière opérationnelle à des moyens de commande d'alimentation en carburant (2, 60) du moteur à combustion interne, le procédé consistant, à chaque fois qu'il est demandé que l'étrangleur soit complètement ou pratiquement complètement ouvert par l'actionnement du mécanisme d'actionnement d'étrangleur, à permettre aux moyens de commande d'alimentation en carburant d'adopter un état d'étrangleur entièrement ou pratiquement entièrement ouvert correspondant sur une période de temps, après quoi les moyens de commande d'alimentation en carburant sont déplacés pour réduire l'écoulement de carburant vers le moteur à combustion interne, le procédé étant caractérisé en ce que l'étendue sur laquelle les moyens de commande d'alimentation en carburant sont déplacés pour réduire l'écoulement de carburant vers le moteur est choisie de telle sorte qu'à charge constante, en dépit de la réduction de l'écoulement de carburant vers le moteur, la vitesse de rotation du moteur reste pratiquement insensible à la charge prédominante.

2. Procédé selon la revendication 1, caractérisé en ce que les moyens de commande d'alimentation en carburant sont déplacés automatiquement pour réduire un tel écoulement vers le moteur à combustion interne indépendamment du fait que le mécanisme d'actionnement d'étrangleur pouvant être actionné manuellement reste dans une position correspondant à un étrangleur entièrement ou pratiquement entièrement ouvert.

3. Procédé selon la revendication 2, caractérisé en ce que l'actionnement ultérieur d'étrangleur entièrement ouvert des moyens de commande d'alimentation en carburant est permis à nouveau uniquement après que le mécanisme d'actionnement d'étrangleur pouvant être actionné manuellement ait été déplacé sur une étendue prédéterminée en direction d'une position correspondant à un état d'étrangleur fermé.

4. Procédé selon l'une quelconque des revendications précédentes, caractérisé en ce que le déplacement des moyens de commande d'alimentation en carburant pour réduire l'écoulement de carburant vers le moteur à combustion interne est obtenu par l'intermédiaire d'une biellette (7, 66) du mécanisme d'actionnement d'étrangleur qui fournit de manière sélective une course morte entre le mécanisme d'actionnement d'étrangleur pouvant être actionné manuellement et les moyens de commande d'alimentation en carburant.

5. Procédé selon la revendication 4, caractérisé en ce que le degré de course morte peut être ajusté pour ajuster l'amplitude de la réduction de l'écoulement de carburant pour satisfaire le paramètre consistant à ne pratiquement pas affecter la vitesse du moteur à charge constante lorsque la réduction d'alimentation en carburant est réalisée.

6. Procédé selon l'une quelconque des revendications précédentes, caractérisé en ce que ladite période de temps peut être ajustée ou peut être choisie conformément aux conditions de fonctionnement du moteur, ou les deux.

7. Ensemble de commande pour faire fonctionner un moteur à combustion interne et pour commander l'actionnement de moyens de commande d'alimentation en carburant (1) associés au moteur à combustion interne et dans lequel les moyens de commande d'alimentation en carburant sont activés par un mécanisme d'actionnement d'étrangleur pouvant être actionné à la main (6), l'ensemble de commande comportant des moyens de réduction (7) pour réduire l'écoulement de carburant vers le moteur par l'intermédiaire des moyens de commande d'alimentation en carburant lorsque le mécanisme

d'actionnement d'étrangleur pouvant être actionné manuellement est dans un état d'étrangleur entièrement ouvert ou pratiquement entièrement ouvert, ledit ensemble de commande étant caractérisé en ce qu'il comporte des moyens de retard (40) permettant l'état d'étrangleur entièrement ouvert des moyens de commande d'alimentation en carburant sur une période de temps prédéterminée, après quoi ledit ensemble de commande peut être actionné pour réduire l'alimentation en carburant vers le moteur, les moyens d'actionnement pouvant être actionnés manuellement restant dans un état correspondant à l'étrangleur entièrement ouvert ou pratiquement entièrement ouvert, ledit ensemble de commande pouvant être ajusté en utilisation de telle sorte que l'amplitude sur laquelle l'écoulement de carburant vers le moteur est réduit peut être établie pour fournir une réduction d'écoulement de carburant n'ayant pratiquement aucun effet sur la vitesse du moteur sous une charge prédominante constante.

8. Ensemble de commande selon la revendication 7, caractérisé en ce que les moyens de réduction comportent une unité de limitation d'étrangleur (7) ayant un premier état dans lequel le fonctionnement pleinement ouvert de l'étrangleur est autorisé et un second état dans lequel un fonctionnement quelque peu restreint de l'étrangleur est disponible de manière à empêcher l'ouverture complète de l'étrangleur et un dispositif de commande formant une partie de l'ensemble de commande est adapté pour sélectionner lequel des deux états prédomine à tout moment particulier.

9. Ensemble de commande selon la revendication 8, caractérisé en ce que les moyens de retard sont réalisés dans le dispositif de commande et des moyens de détection (42) destinés à détecter l'ouverture de l'étrangleur ou la position du mécanisme d'actionnement d'étrangleur sont agencés et reliés au dispositif de commande pour fournir un signal au dispositif de commande.

10. Ensemble de commande selon la revendication 9 caractérisé en ce que le dispositif de commande comporte un microprocesseur (49) qui est adapté pour valider le fonctionnement du dispositif de commande pour qu'il soit établi pour initialiser ledit second état de l'ensemble de commande conformément aux signaux reçus en provenance des moyens de détection.

11. Ensemble de commande selon la revendication 10 caractérisé en ce que le moteur est un moteur de véhicule à moteur et deux ensembles différents de paramètres associés à des opérations de conduite "indésirables" peuvent être sélectionnés, alternativement, un tel ensemble correspondant à des conditions de conduite "en ville" et un correspondant à des conditions de conduite "en campagne".

12. Ensemble de commande selon la revendication 11 caractérisé en ce que le microprocesseur est programmé pour choisir des conditions de conduite "en ville" ou "en campagne" conformément à des signaux reçus en provenance des moyens de détection, qui sont caractéristiques d'une conduite "en ville" ou "en campagne", selon les cas.

13. Ensemble de commande selon la revendication 12 caractérisé en ce que la caractéristique de conduite "en ville" ou "en campagne" est déterminée par le dispositif de commande comme étant le fait que dans le mode de conduite "en campagne" l'étrangleur est, de manière significative, ouvert pendant des périodes de temps prolongées.

14. Ensemble de commande selon l'une quelconque des revendications 8 à 13, caractérisé en ce que le dispositif de commande est adapté pour détecter la vitesse de changement de position du mécanisme d'étrangleur et pour amener l'unité de limitation d'étrangleur à adopter ledit second état si une telle vitesse de changement de position est excessive.

15. Ensemble de commande selon la revendication 14 en combinaison avec la revendication 13, caractérisé en ce que ladite vitesse de changement de position est rendue inactive dans le mode de conduite "en campagne".

16. Ensemble de commande selon l'une quelconque des revendications 8 à 15, caractérisé en ce que le dispositif de commande est adapté pour amener audit second état de l'ensemble de commande dans le cas où le nombre d'opérations du mécanisme d'étrangleur, détecté dans une période de temps prédéterminée, dépasse un nombre maximum préétabli.

17. Ensemble de commande selon la revendication 16 caractérisé en ce que le nombre maximum préétabli est basé sur le nombre de vitesses d'un véhicule dans lequel l'ensemble de commande est agencé.

18. Ensemble de commande selon l'une quelconque des revendications 8 à 15 ou 17, caractérisé en ce que ladite période de temps prédéterminée à partir de laquelle l'état étrangleur entièrement ouvert est fourni est nettement plus grande dans le mode de conduite en campagne que dans le mode de conduite en ville.

19. Ensemble de commande selon l'une quelconque des revendications 9 à 13, caractérisé en ce que

les moyens de détection (42) comportent deux parties (45, 47) adaptées chacune pour être reliées directement ou indirectement, l'une à une partie mobile d'un mécanisme d'actionnement d'étrangleur et l'une à une partie stationnaire par rapport à celui-ci, et dans lequel la première partie (45) est constituée d'une bobine et l'autre partie (47) est constituée d'une substance magnétique, la relation étant telle qu'un déplacement de la substance magnétique par rapport à la bobine entraîne des changements d'inductance de la bobine avec un changement en conséquence de la fréquence d'un signal appliqué à celle-ci.

20. Ensemble de commande selon l'une quelconque des revendications 8 à 13 ou 19, caractérisé en ce que l'unité de limitation d'étrangleur (7) est une biellette linéaire fournissant une course morte dans ledit second état, la biellette étant installée en tant que liaison dans le mécanisme d'actionnement d'étrangleur.

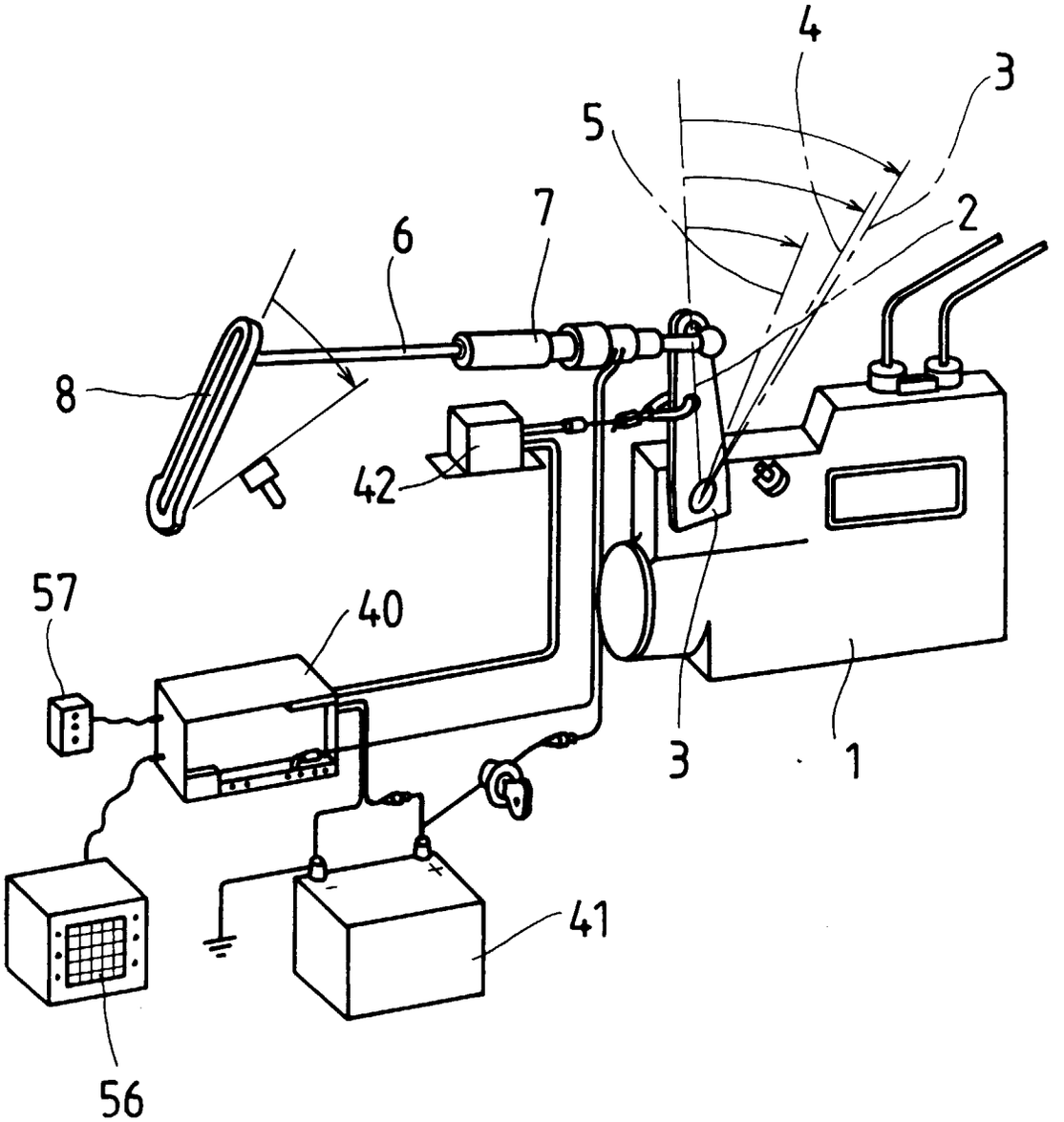
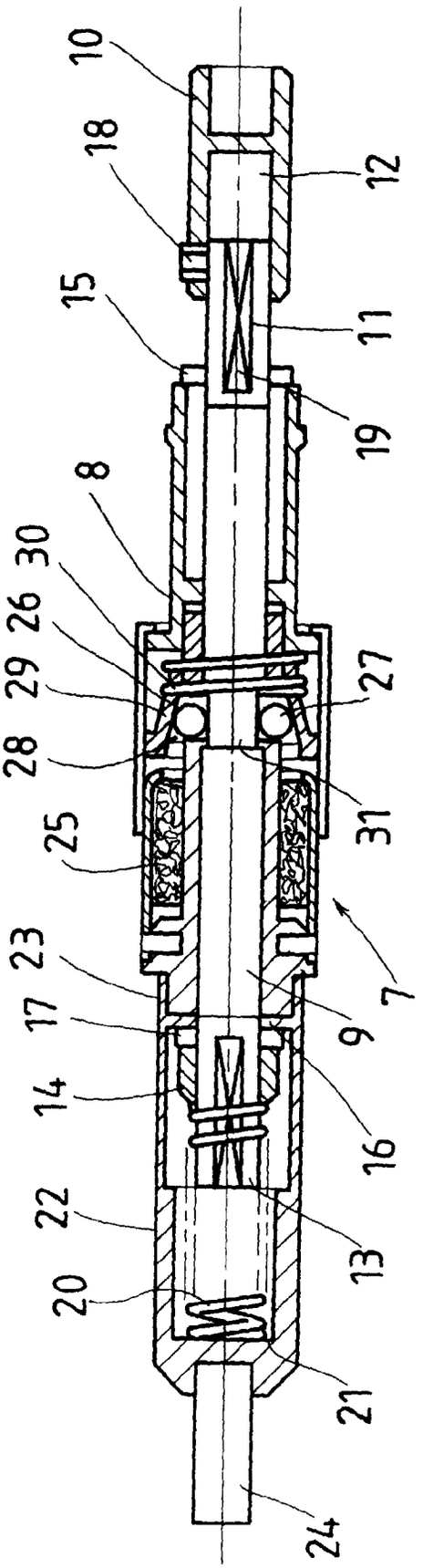


FIG. 1


10
18
12
15
11
19
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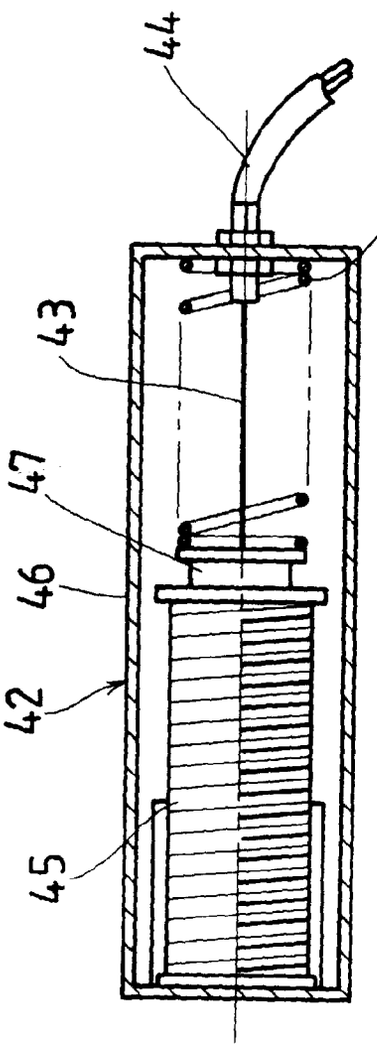
20
21
24

FIG. 2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48
43
47
46
42
45

FIG. 3

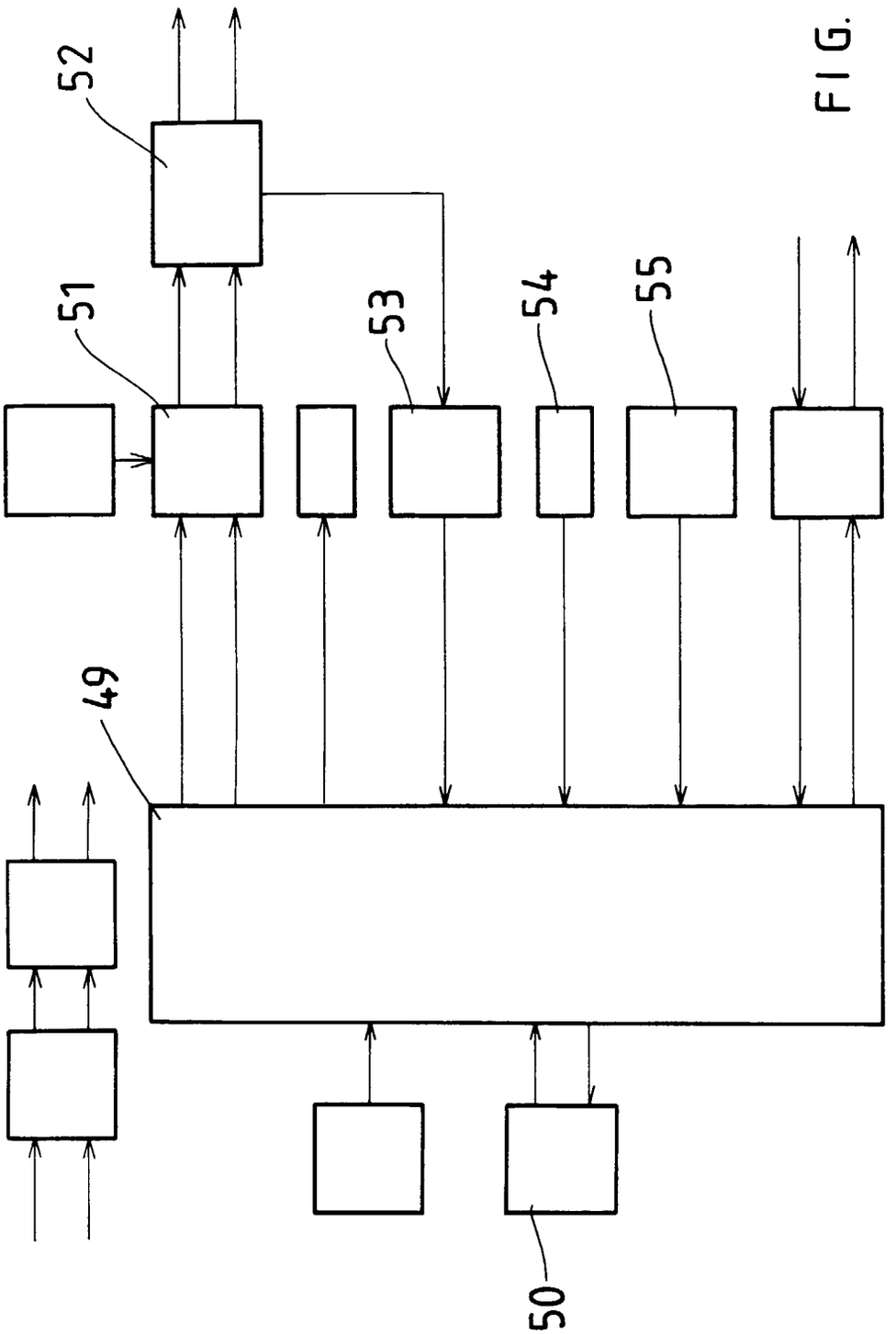
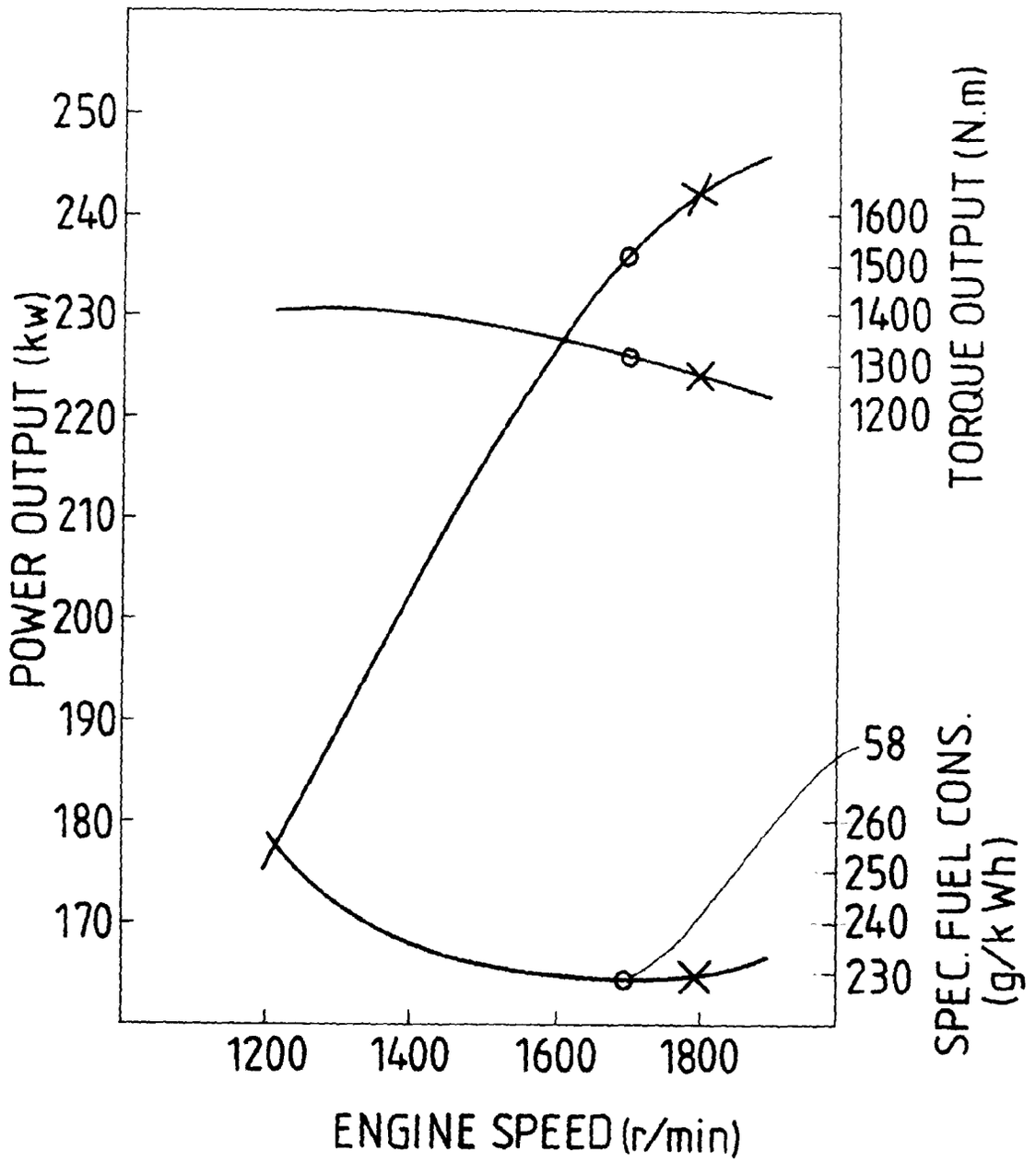


FIG. 4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240
230
220
210
200
190
180
170
POWER OUTPUT (kw)
1600
1500
1400
1300
1200
TORQUE OUTPUT (N.m)
58
260
250
240
230
SPEC. FUEL CONS. (g/k Wh)
1200
1400
1600
1800
ENGINE SPEED (r/min)

FIG. 5

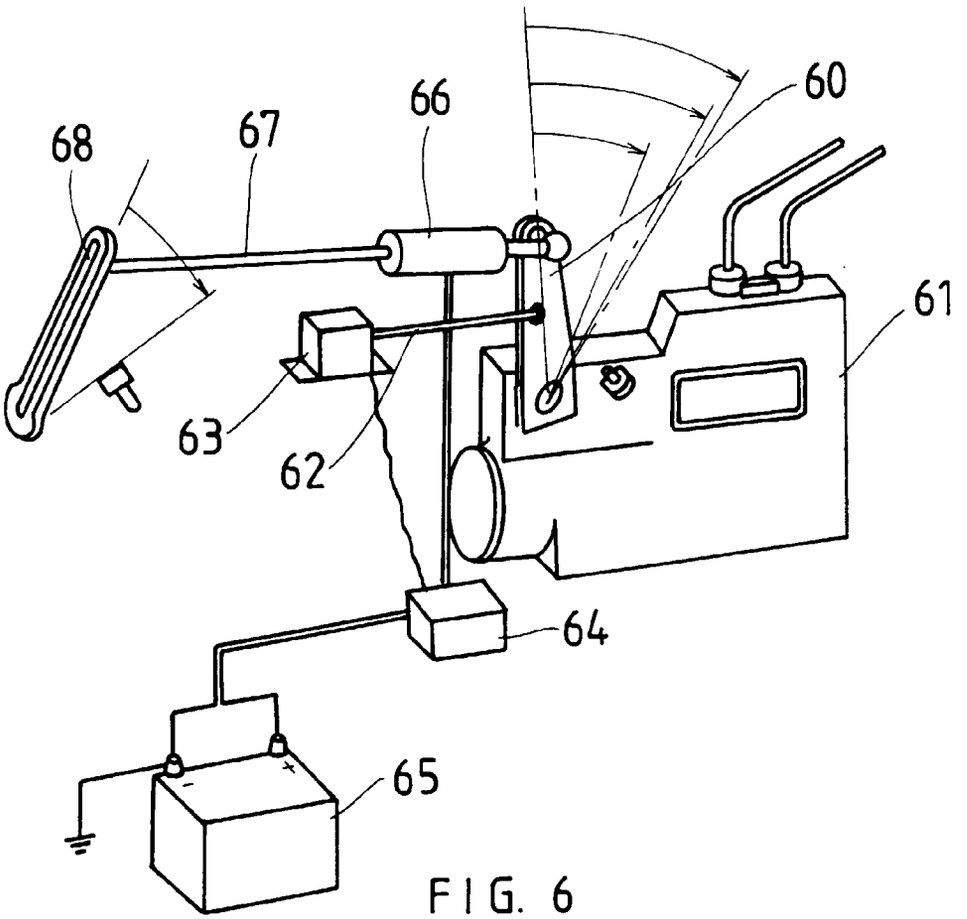

FIG. 6

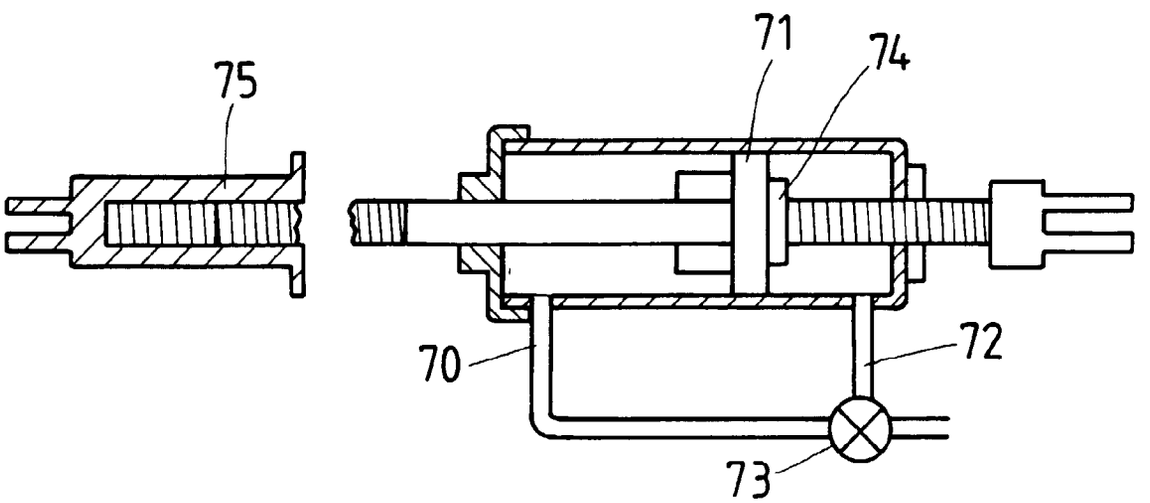

FIG. 7