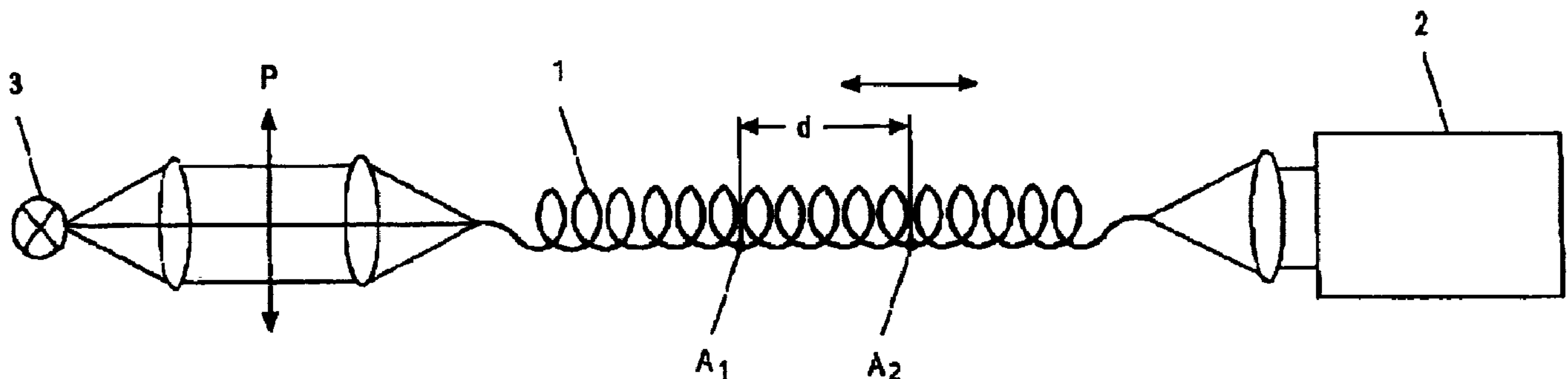




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(54) Titre : DETECTEUR ET PROCEDE POUR DETECTER DES VARIATIONS DE DISTANCE
(54) Title: SENSOR AND METHOD FOR DETECTING CHANGES IN DISTANCE



(57) Abrégé/Abstract:

The present invention is directed to a sensor for detecting changes in the distance between a first and a second location, having at least one substantially helically coiled optical fiber, which is able to be mechanically connected to at least one of the locations, and having a light transmitter and a detecting device for optical signals, the detecting device being able to generate an output signal, which is dependent upon the polarization state of the optical signal transmitted via the optical fiber. The present invention is also directed to a method for detecting the changes in distance between a first and a second location, having the following features: at least one of the locations is mechanically coupled to a substantially helically coiled optical fiber; an optical signal having a known polarization state is launched into the optical fiber; following transmission over the connecting line, this is detected in such a way that information is obtained with respect to its polarization state; from this information, the change in distance is determined.

Abstract

The present invention is directed to a sensor for detecting changes in the distance between a first and a second location, having at least one substantially helically coiled optical fiber, which is able to be mechanically connected to at least one of the locations, and having a light transmitter and a detecting device for optical signals, the detecting device being able to generate an output signal, which is dependent upon the polarization state of the optical signal transmitted via the optical fiber. The present invention is also directed to a method for detecting the changes in distance between a first and a second location, having the following features: at least one of the locations is mechanically coupled to a substantially helically coiled optical fiber; an optical signal having a known polarization state is launched into the optical fiber; following transmission over the connecting line, this is detected in such a way that information is obtained with respect to its polarization state; from this information, the change in distance is determined.

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PCT/EP99/09845

DESCPAMD

Translation of German revised pages 1, 2, 2a**SENSOR AND METHOD FOR DETECTING CHANGES IN DISTANCE****Field of the Invention**

5 The present invention relates to a sensor, as well as to a method for detecting changes in the distance between a first and a second location, on the basis of optics.

Background of the Invention

10 Many methods are known for measuring changes in the distance between movable objects. For example, one knows of sensors, such as strain gauges, which are based on electrical methods. Changes in electric capacitance, as well as in magnetic flux are utilized when working with small changes in length. The advantage of optical methods to determine linear variations is
15 that there is no need for an electrically conductive connection between the points whose change in distance is to be measured. Customary are interferometers for small and average distances of about 1 μm to 1 m, moiré systems, as well as transit-time measurements of light pulses. Interferometer
20 systems may be very precise, but they have the drawback of being mechanically extremely sensitive. Also, their operation entails substantial outlay for adjustments. For that reason, they must be set up as substantially vibrationless systems, so that they are not simple to use, especially for detecting
25 changes in the distance moving objects. Moiré systems are likewise precise, but, in a measuring range beyond a few centimeters, they can only be implemented at a considerable expense; transit-time measurements of optical pulses and/or measurements of frequency shifts produced by the Doppler
30 effect are only accurate for large distances and require

costly measuring electronics.

From the publication, "Berry's phase analysis of polarization rotation in helicoidal fibers" that appeared in June 1998 in Applied Optics, vol. 37, no. 18, by F. Wassmann and A. Ankiewicz, a method is known for calculating the rotation of the polarization of light, which propagates through a helically wound optical fiber. The rotation of the polarization can be utilized for implementing an optical fiber sensor which can be used to determine the size [extent] of a displacement.

From the publication "Two-dimensional HiBi fiber-optic coil strain sensor" that appeared in July 1997 in Acta Photonica Sinica, vol. 26, no. 7, pp. 618-622, XP 000884999, by Y. Libo and A. Farhad, it is known, with the aid of a wound optical fiber, to measure mechanical strains, the influence of the mechanical strain on the polarization state of the light being utilized, which propagates through the optical fiber.

From U.S. Patent 5,201,015, a sensor is known for measuring mechanical strains with the aid of an optical fiber. The optical fiber has concentric windings. When a mechanical tensile stress is exerted on the sensor, the windings are elastically stretched, causing the peripheral path of the windings and, thus, also the optical path length of the light to increase [lengthen] in the optical fiber. The increase in the optical path length is utilized as a measure of the externally acting mechanical strain.

From U.S. Patent 4,389,090, a device is known for producing specific polarization states of light in an optical fiber. At least one region of the optical fiber is formed as a winding or coil. The polarization state of the light can be adjusted and changed by varying the spatial orientation of the winding or coils, as well as by twisting the optical fiber.

Object of the Invention

The object of the present invention is, therefore, to provide a sensor for detecting changes in distance, which is
5 technically simple and inexpensive to implement, does not require any special mechanical stability, and which can be used to precisely determine small positional changes. A further object of the present invention is to provide a method for detecting changes in distance which is simple to
10 implement.

Summary of the Invention

The objective is achieved by a sensor for detecting changes in
15 the distance between a first and a second location, having at least one substantially helically coiled optical fiber, which is able to be mechanically connected to at least one of the locations, and having a light transmitter and a detector for optical signals. In this context, the detecting device is able
20 to generate an output signal, which is dependent upon the polarization state of the optical signal transmitted via the optical fiber. In addition, a reference optical fiber path is provided, which simulates the optical fiber and over which a second optical signal is transmitted, the optical signals
25 transmitted over both paths being detected in a shared or in separate detecting devices so as to enable differences in the polarization state to be determined.

Procedurally, the objective is achieved by a method for
30 detecting distance variations between a first and a second location, where:

- a) at least one of the locations is mechanically coupled to a substantially helically coiled optical fiber;
- b) one optical signal having a known polarization state is
35 coupled into the optical fiber;
- c) the optical signal transmitted over the connecting line is recorded in such a way that information pertaining to its

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polarization state is acquired;

d) the change in distance is determined from the information on the polarization state of the transmitted signal;

5 e) the polarization state of the optical signal following the transmission is compared to that prior to the transmission and/or to a reference polarization state.

In accordance with one aspect of this invention, there is provided a sensor for detecting a change in a
10 distance between a first location and a second location, comprising: at least one substantially helically coiled optical fiber for being mechanically connected to at least one of the first and second locations; a light transmitter; a detecting device for detecting optical signals and for
15 generating an output signal dependent upon a polarization state of a first optical signal transmitted via the at least one substantially helically coiled optical fiber; and a reference optical fiber path for simulating the at least one substantially helically coiled optical fiber and over which
20 a second optical signal is transmittable; wherein the first and second optical signals are detectable in one of (i) the detecting device and (ii) the detecting device and another detecting device, for determining any difference in polarization states of the first and second optical signals.

25 In accordance with another aspect of this invention, there is provided a method for detecting a change in a distance between a first location and a second location, the method comprising the steps of: mechanically coupling at least one of the first and second locations to a
30 substantially helically coiled optical fiber; coupling an optical signal having a known polarization state into the

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substantially helically coiled optical fiber; recording the optical signal transmitted over a connecting line for acquiring information pertaining to a polarization state of the optical signal; determining the change in the distance
5 from the information pertaining to the polarization state of the optical signal; and comparing the polarization state of the optical signal transmitted with at least one of another polarization state of the optical signal before its transmission and a reference polarization state.

10 The present invention is based on the principle of the polarization of light changing in helically wound optical fibers in response to a change in the helical parameters. The polarization of the light at the output of a simple, helically coiled, optical fiber line is sensitive
15 to movement, in particular to accordion-like movements of the fiber. This dependency of the polarization on the form of the three-dimensional curve of the fiber can be used directly to measure the form, e.g. the length of the accordion of the fiber windings. Thus, the distance between
20 any two locations can be determined by connecting them using a movable, helically wound, elastic optical fiber line.

 The main reason for the form dependency of the polarization state at the output end of an optical fiber is the considerable dependency of the fiber's optical activity
25 upon the exact form of its helical windings. In the first approximation, this effect is achromatic and does not result in any polarization mode dispersion. It is caused by one of the so-called optical Berry phases, the spin redirection phase. This Berry phase or geometric phase is a phase
30 effect produced by the structure of the fiber's space curve and not by a difference in the optical path length, as is the case with the normal dynamic phase of light.

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Nevertheless, geometric phases lead to the same interference effects of the light as do normal dynamic phases.

The size of the spin redirection phase in a helically wound fiber is equivalent to the solid angle Ω that the k vector (k corresponds to the propagation constant β in the technical literature) wraps around on the sphere of the light propagation orientations in the counter-clockwise direction when the light in the fiber is directed through a helical winding.

For that reason, it is important that light be coupled with a defined polarization state into the coiled optical fiber and that the transmitted optical signal be detected in a manner such that inferences can be drawn with respect to its polarization state or individual polarization components after propagating through the optical fibers. From the change in the parameters of the optical signal prior to and following the transmission, or from a comparison to a reference from a calibration measurement or a concurrent reference measurement, inferences can be drawn with respect to the form or the change in the form of the wound optical fiber and, thus, also with respect to changes in the distance between locations connected thereto.

For example, polarized light can be coupled into the fiber, and its polarization state or the strength of a specific polarization component can be measured, once it has propagated through the optical fiber, using a polarimeter or a detector having a series-connected analyzer. From knowledge of the polarizations or of individual polarization components prior to and subsequent to the transmission, conclusions can be drawn with respect to the change in polarization caused by the form and, thus, with respect to the deformation of the coils.

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If the transmission signal is compared to a reference, then precise knowledge of the polarization state prior to the transmission is not absolutely necessary. It suffices if a defined initial basic situation is always at
5 hand. The reference is constituted, for example, of a series of measured values which were acquired during a calibration measurement using the optical fibers and which specify the output signal at specific distances between the first and second location. Alternatively, a reference
10 signal can also be produced during the measurement in that a reference path, which preferably simulates the wound optical fiber, likewise receives a defined optical signal, and the two transmission signals are compared to one another. For this, they are either analyzed separately

and both intensities are compared to one another. The actual transmission signal can also be brought into interference, however, with the reference transmission signal and subsequently be detected in a shared detector.

5

The benefits provided by the present invention of eliminating the need for specular surfaces or for a special mechanical stability of the system, are virtually universally applicable. The launching the optical signal into the fiber should, in fact, be mechanically stable, but it can be set up separately from the system to be measured. In addition, without entailing substantial technical outlay, the sensor can be assembled from individual, inexpensive components.

10

15 Brief description of the drawing, whose figures show:
Figure 1 a sensor according to the present invention having a helical optical fiber;
Figure 2 a detail of a helical optical fiber;
Figure 3 a sensor according to the present invention for
20 measuring changes in the length of a telescope arm.

20

Ways for Executing the Present Invention

The lower part of Figure 1A shows a sensor according to the present invention having a helical optical fiber 1. Here, the optical fiber has a fixed winding direction. Generally, in the case of an arbitrarily bent fiber, it suffices when one winding direction predominates.

25

30 In addition, the optical fiber has a cladding which holds the fiber in its helically bent form and is capable of elastically following movements, in particular those along the longitudinal axis of the coil. For this, the coils, as such, can also be embedded in an elastic substrate material, for example in an elastic cylinder or the like.

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The sensor also includes a light source 3, which is preferably

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5 a laser. Linearly polarized light emanating from light source 3 is launched into fiber coil 1. In the case that the light source does not emit fully polarized light, a polarizer P is positioned at the fiber input end to produce the defined polarization state. At the output end of the fiber coil, the polarization state of the transmitted optical signal is measured using a polarimeter 2. Alternatively, one can use a simple detector having a series-connected analyzer to measure the intensity of a defined polarization component.

10 Figure 1B schematically depicts a polarization ellipse to represent the polarization state of the light once it has propagated through the transmission route. X and y denote the vibration directions of the electric field vector. In the most general case, the field vector describes an ellipse having the main axes a and b, which is rotated by the angle ϕ in relation to the axes x and y.

15 The present invention utilizes that the orientation angle ϕ of the polarization ellipse at the output end of the fiber path is proportional to the so-called geometric phase introduced in the coil between the right hand and left hand circular component of the injected, linearly polarized light. Since the geometric phase changes with the coil shape, the orientation angle ϕ is a measure of the coil shape. In this manner, the distance d between two points A1 and A2 can be measured on the coil and, thus, also the distance and/or the change in the distance between two locations rigidly connected by points A1 and A2.

20 In the special cases described in the following and elucidated on the basis of Figure 2, the geometric spin redirection phase and, thus, the coil form can be determined quite simply. Each complete winding of the optical fiber on a cylinder Z of radius r, having pitch St, for which the lead angle θ is the same at the beginning A and end E of the winding, produces a rotation ϕ of the injected, linearly polarized light. The

angle of rotation φ is given by

$$(1) \quad \varphi = \int_0^{2\pi} [1 - \cos\Theta(\Phi)] d\Phi$$

5 In this context, φ is the azimuth angle of cylinder Z; see Figure 2. For the case of a uniformly wound spiral, Θ is a constant, and one obtains:

$$(2) \quad \varphi(\Theta = \text{const.}) = 2\pi(1 - \cos\Theta) \text{ and } \cos\Theta = \frac{St}{L}$$

10

Thus, if one couples a linearly polarized light at angle α into the helix, then at the end E, it has a polarization rotated by the angle φ thus $\alpha + \varphi$. The operational sign of angle of rotation φ depends on the helicity of the coil. L is the length of the fiber helix. At this point, in response to a change in pitch St of the helix, the helix angle Θ and, thus, the polarization direction at fiber end E change. If one installs a linear analyzer at end E and then permits the light to strike a detector, then this registers an intensity I

20

$$(3) \quad I = I_0 \cos^2[\gamma - (\alpha \pm \varphi)]$$

25 When γ is the orientation angle of the analyzer, and I_0 is the intensity of the linearly polarized light emerging from the fiber. The assumption here is that lossless conditions prevail and that the light in the fiber ideally remains linearly polarized.

30 For all other cases, I likewise depends on helix angle Θ and, thus, on the distance between points AE, although in complicated fashion. The correlation is preferably determined through calibration or by measuring the parameters of equation (1), as well the various losses. At the detector, one obtains

a signal which is dependent upon distance St to be measured and can be brought into a suitable measuring range by parameters r , γ and α .

5 It is not necessary that only one single winding of the fiber be used as a distance indicator. It is likewise possible to use many windings, as in Figure 1, as well as non-whole numbers of windings. In the case of an integral number of turns N between A and E and given the same helix angles at A and E, it is possible to calculate the angle of rotation ϕ in accordance with equation (1), it being necessary to extend the upper integration limit to $2\pi N$. Given a number of turns N that is not whole and non-uniform windings, a calibration is more advantageous than the calculation, which can no longer be performed in accordance with the simple equation (1).

To fabricate a uniform coil form having constant helix angles, spindles are mounted at points A and E at the beginning and end of the winding about which the fiber can rotate freely with respect to angle θ . These spindles are disposed perpendicularly to the cylinder axis of the winding. The fiber is mounted on an elastic carrier, which has a pivot at A and E enabling it to rotate about the spindles. Since, in this case, the uniform helix adjusts itself automatically as a geodesic curve between points A and E on the cylinder, equation (3) can be applied for all pitches St of the helix, for whose formation the total length of the fiber suffices.

Generally, an optical fiber does not retain the (linear) polarization; i.e., when it emerges from the fiber, the light is no longer polarized as it originally was upon its entry into the fiber. This effect is produced, on the one hand, by deviations in the fiber core from circular symmetry and, on the other hand, by birefringence induced by the bending of the fiber. In so-called weakly birefringent fibers, which also feature a low polarization mode dispersion, an orientation distribution of the asymmetry of the fiber core is achieved in

all spatial directions, for example through rapid rotation of the preform when drawing the fibers. Therefore, fibers of this kind are especially suited for manufacturing a length-measuring sensor in accordance with the present invention.

To avoid stress-induced birefringence in the bent fiber, the bending radius of the fiber should not be too small. An estimation of the birefringence in bent fibers is given by L. Jeunhomme, Single-Mode Fiber Optics, N.Y. 1983, p. 60. It is ideal when the wound fiber helix has a phase lag of less than $\lambda/10$, λ being the operating wavelength. On the other hand, even higher strain birefringence values do not substantially interfere with the measuring principle, since, even in the case of elliptically polarized light at the output end of the fiber, the helix deformation causes changes in the orientation angle ϕ , which can be taken as a measure of the change in length. Large bending radii of the fibers can be achieved both by increasing the helix radius, as well as by enlarging the helical pitch.

A calibration of the sensor also includes changes in intensity in the detector at the fiber end, resulting from bending of the fiber in response to a change in the distance AE. A length measurement obtained by comparing the instantaneously measured values to values determined in a calibration measurement is advantageous for the practical application of the sensor, since it makes it possible to eliminate any influences on the polarization state of the light that are not caused by the change in the length of the wound optical fiber.

Figure 3 illustrates one practical specific embodiment of the present invention. An elastic fiber carrier D, for example a steel, bronze or plastic wire, is provided with two mounting supports HA, HE, which can be fitted on spindles at A and E enabling them to freely rotate. In the described example, the spindles at points A, E are connected to two tubes of a

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telescope arm, whose change in length needs to be measured. In the described example, a helical optical fiber having one single winding is used, which is embedded in fiber carrier D.

5 Disposed upstream from holder HA is a light source LQ, which can also be mechanically connected to holder HA to assure stable coupling conditions. Light source LQ, which preferably produces linearly polarized light, is, for example, a
10 coupled via a lens L1 into the optical fiber, whose input end is positioned at holder HA. The fiber is secured on or in elastic fiber carrier D. In the case that the light source emits unpolarized light, linear polarizer PA must also be installed between the light source and the start of the fiber.

15 At the end E of the winding is holder HE, to which a lens L2 and the fixed or rotatable linear analyzer PE is secured. The lens images light from the fiber onto detector DE. Light
20 source LQ and detector DE are connected via easily movable electric conductors to corresponding network and recording devices N and R, respectively. To avoid interference effects, the light source, detector, and glass fiber are obscured in light-proof manner from the outside world.

25 Industrial Applicability

The present invention can be advantageously used in industrial applications to precisely detect changes in length and distance in a multiplicity of systems, such as in robot arms.

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CLAIMS:

1. A sensor for detecting a change in a distance between a first location and a second location, comprising:

at least one substantially helically coiled
5 optical fiber for being mechanically connected to at least one of the first and second locations;

a light transmitter;

a detecting device for detecting optical signals and for generating an output signal dependent upon a
10 polarization state of a first optical signal transmitted via the at least one substantially helically coiled optical fiber; and

a reference optical fiber path for simulating the at least one substantially helically coiled optical fiber
15 and over which a second optical signal is transmittable;

wherein the first and second optical signals are detectable in one of (i) the detecting device and (ii) the detecting device and another detecting device, for determining any difference in polarization states of the
20 first and second optical signals.

2. The sensor of claim 1, wherein the detecting device is one of a polarimeter and a detector having a series-connected analyzer.

3. The sensor of claim 1, wherein the at least one
25 substantially helically coiled optical fiber is flexible in a helix direction and is for following changes in the distance between the first location and the second location.

4. The sensor of claim 1, wherein the at least one substantially helically coiled optical fiber is joined to an

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elastic carrier material, which permits a change in form in response to mechanical loading of the at least one substantially helically coiled optical fiber, and which retains the at least one substantially helically coiled optical fiber in an initial curved form in response to no mechanical loading.

5 5. The sensor of claim 1, wherein the at least one substantially helically coiled optical fiber is wound around an at least one elongated carrier element.

10 6. The sensor of claim 1, wherein the at least one substantially helically coiled optical fiber is secured to a carrier element so that the at least one substantially helically coiled optical fiber is movable in a wound form but remains stabilized on the carrier element.

15 7. The sensor of claim 1, wherein one winding direction predominates in the at least one substantially helically coiled optical fiber.

 8. The sensor of claim 1, wherein at least one of the following is satisfied: the light source produces linearly polarized light; and a linear polarizer is situated at least one of on and at an input end of the at least one substantially helically coiled optical fiber.

 9. A method for detecting a change in a distance between a first location and a second location, the method comprising the steps of:

 mechanically coupling at least one of the first and second locations to a substantially helically coiled optical fiber;

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coupling an optical signal having a known polarization state into the substantially helically coiled optical fiber;

5 recording the optical signal transmitted over a connecting line for acquiring information pertaining to a polarization state of the optical signal;

determining the change in the distance from the information pertaining to the polarization state of the optical signal; and

10 comparing the polarization state of the optical signal transmitted with at least one of another polarization state of the optical signal before its transmission and a reference polarization state.

10. The method of claim 9, wherein the step of
15 determining the change in distance includes comparing a detected signal and at least one individual parameter of the detected signal with a value determined in a calibration measurement corresponding to a specific distance.

11. The method of claim 9, wherein the step of
20 determining the change in the distance is performed using a detected signal, at least one individual parameter of the detected signal and a form of a three-dimensional curve of the substantially helically coiled optical fiber.

12. The method of claim 9, wherein the reference
25 polarization state is a polarization state of the optical signal determined following propagation of the optical signal through a communication link in a mechanical idle state.

13. The method of claim 9, wherein the optical signal
30 and a reference signal are detected.

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14. The method of claim 9, further comprising the steps of:

launching a linearly polarized light into the substantially helically coiled optical fiber; and

5 detecting a light having a defined linear polarization.

15. The sensor of claim 5, wherein the at least one elongated carrier element is at least one of a cylinder and flexible.

10 16. The sensor of claim 1, wherein the at least one substantially helically coiled optical fiber has only one winding direction.

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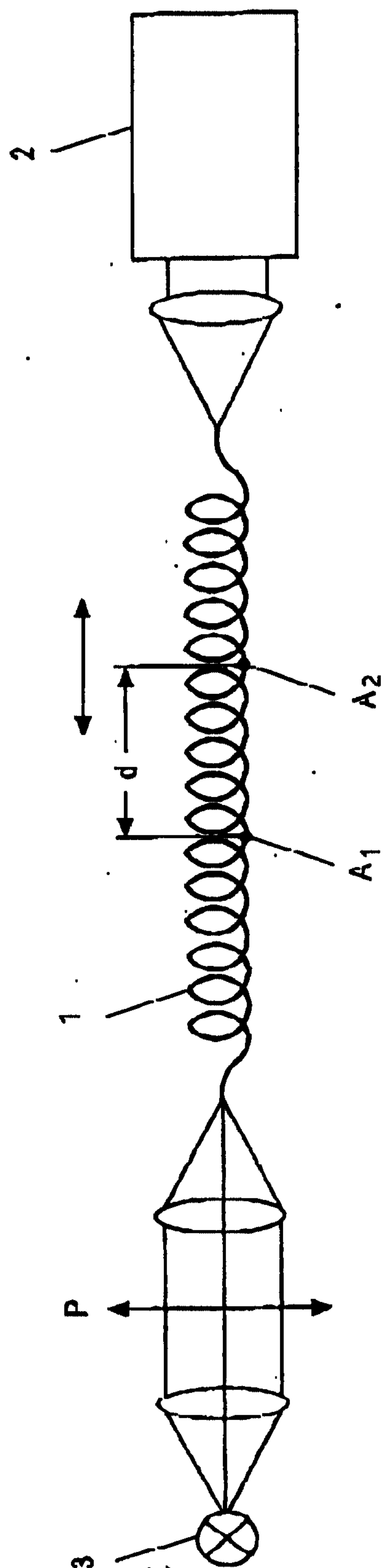


Fig. 1A

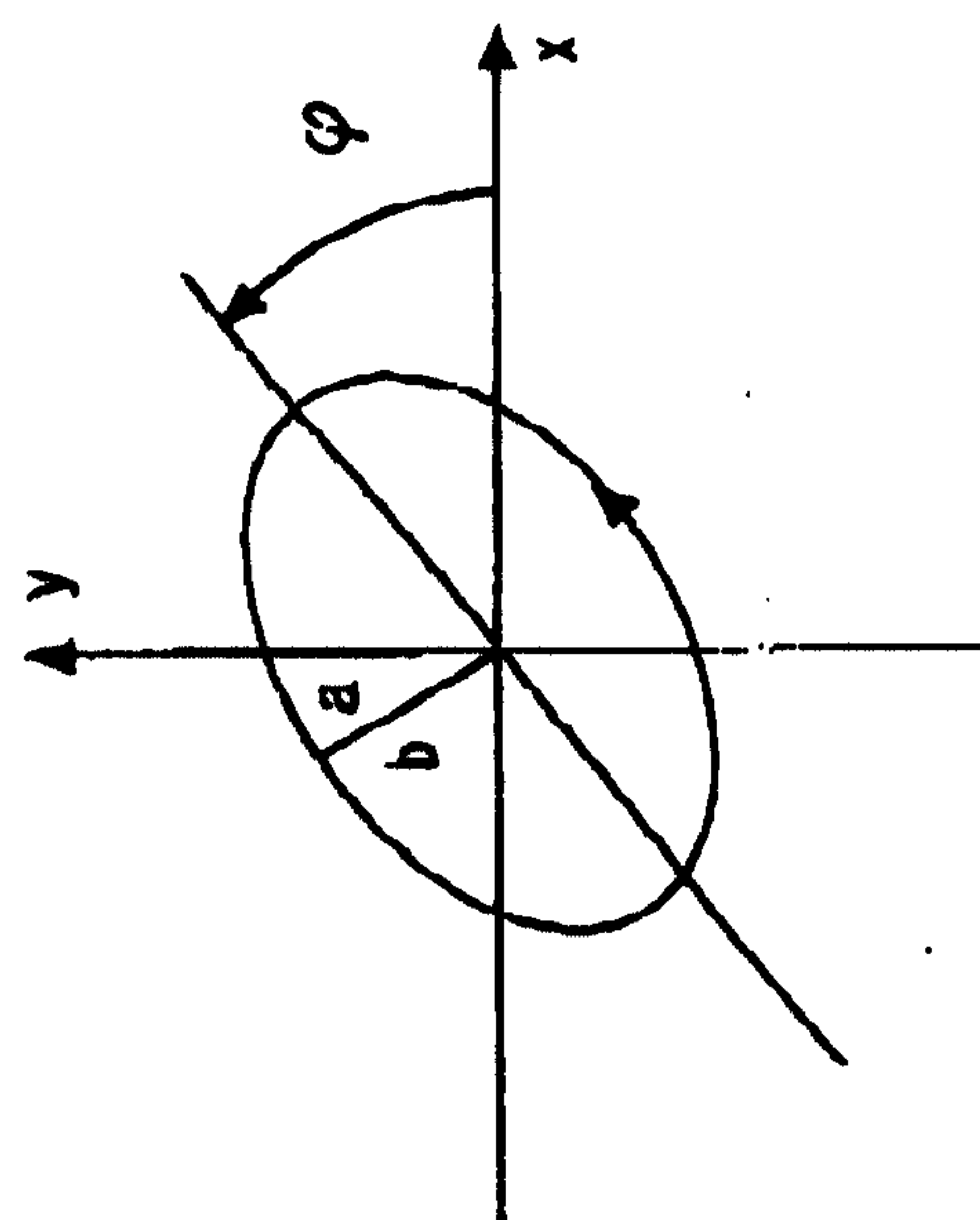


Fig. 1B

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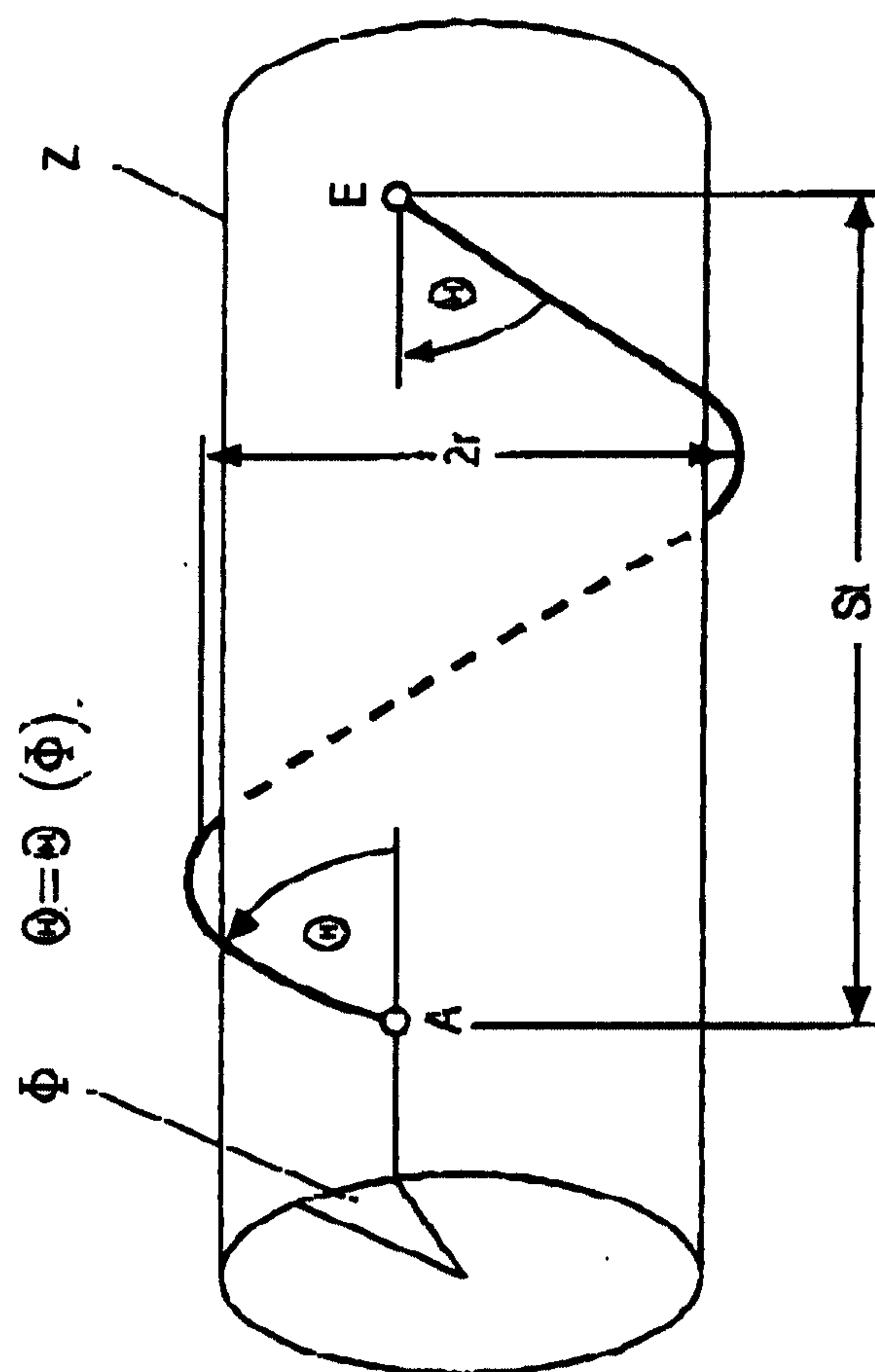


Fig. 2

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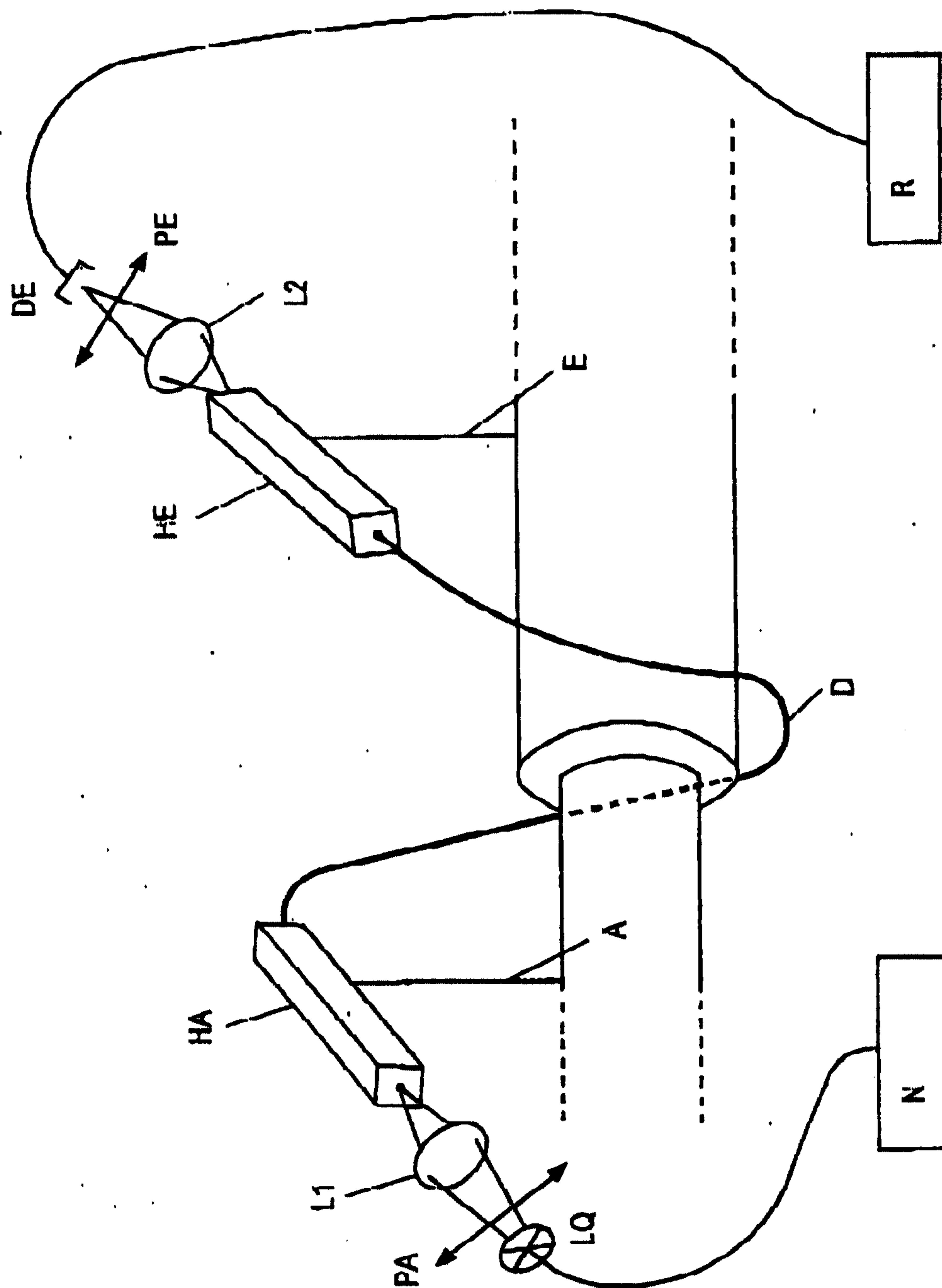


Fig. 3

