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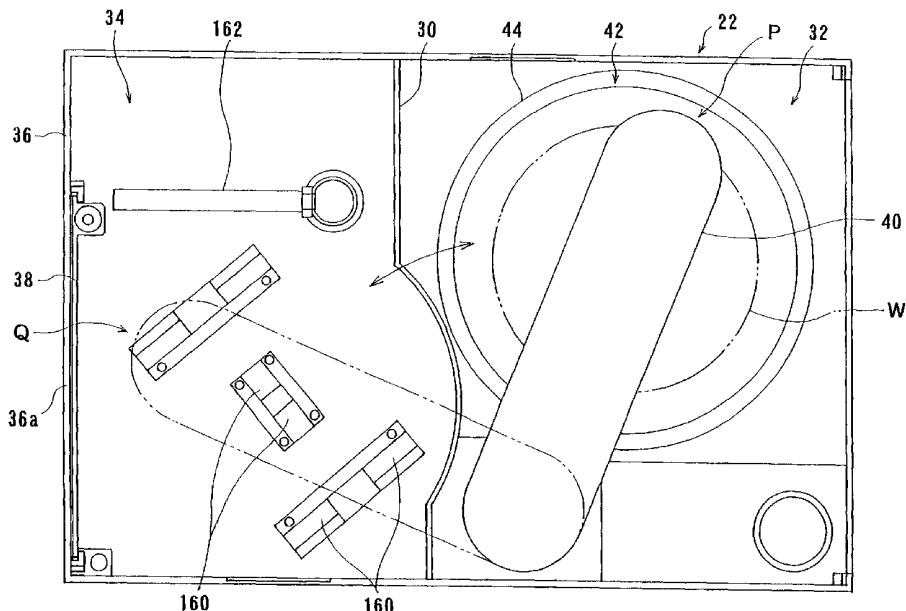
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(54) Title: SUBSTRATE PROCESSING APPARATUS



(57) Abstract: A substrate processing apparatus comprises a plating section (32) having a plating bath (44) for holding a plating liquid therein, and a head assembly (42) for holding a substrate (W) and immersing the substrate (W) in the plating bath (44). A plated film is formed on a surface of the substrate (W) in the plating liquid. The substrate processing apparatus further comprises a cleaning section (34) for cleaning a peripheral edge of the plated substrate (W) and a substrate contact portion (112) held in contact with the substrate (W), and a drive mechanism (170) for moving the head assembly (42) between the plating section (32) and the cleaning section (34).

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DESCRIPTION
SUBSTRATE PROCESSING APPARATUS

Technical Field

5 The present invention relates to a substrate processing apparatus for processing a substrate, and more particularly to a substrate processing apparatus for filling a metal such as copper or the like in interconnection recesses defined in a semiconductor 10 substrate.

Background Art

Recently, in order to fill minute interconnection trenches or via holes defined in a 15 surface of a substrate, it has been customary to use a substrate processing apparatus (plating apparatus) for plating a substrate such as a semiconductor substrate with a metal such as copper, which has a smaller electric specific resistance than aluminum or aluminum-based 20 materials, to form embedded interconnections in the trenches or via holes.

FIG. 1 is a schematic view showing a conventional arrangement of a facedown plating apparatus. As shown in FIG. 1, the conventional facedown plating 25 apparatus comprises an upwardly opened cylindrical plating bath 312 for holding a plating liquid 310 therein, and a head 314 for detachably holding a substrate W such as a semiconductor substrate thereon in such a state that the surface of the substrate W faces 30 downwardly. The head 314 is positioned so as to cover an upper opened end of the plating bath 312. In the plating bath 312, a flat anode plate 316 is horizontally disposed and immersed in the plating liquid 310. The anode plate

316 serves as an anode electrode. The substrate W held by the head 314 has a peripheral edge connected to a cathode electrode via an electrode contact provided on the head 314. The anode plate 316 is made of a porous 5 material or a mesh-like material.

The center of the bottom in the plating bath 312 is connected to a plating liquid ejection pipe 318 for forming an upward flow of the plating liquid in the plating bath 312. An upper portion of the plating bath 10 312 is surrounded by a plating liquid reservoir 320 for receiving the plating liquid that has overflowed the plating bath 312. The plating liquid ejection pipe 318 is connected to a plating liquid supply pipe 328 extending from a plating liquid regulating tank 322. The 15 plating liquid supply pipe 328 has a pump 324 and a filter 326 connected thereto. The plating liquid regulating tank 322 is connected to a plating liquid return pipe 330 extending from the plating liquid reservoir 320.

20 The conventional plating apparatus operates as follows: The substrate W is held by the head 314 in such a state that the surface of the substrate W faces downwardly, and introduced downwardly into the plating bath 312 to be immersed in the plating liquid 310 in the 25 plating bath 312. While a certain voltage is being applied between the anode plate 316 (anode electrode) and the substrate W (cathode electrode), the plating liquid in the plating liquid regulating tank 322 is ejected upwardly from the bottom of the plating bath 312 via the 30 plating liquid ejection pipe 318 and applied as a jet vertically to the lower surface (the surface to be plated) of the substrate W. In this manner, a plated film is formed on the lower surface of the substrate W

while a current is flowing between the anode plate 316 and the substrate W. The plating liquid 310 that has overflowed the plating bath 312 at this time is recovered by the plating liquid reservoir 320 and returned to the 5 plating liquid regulating tank 322 via the plating liquid return pipe 330.

As described above, the substrate is immersed in the plating liquid in the plating bath. In the case where the peripheral edge of the substrate is connected 10 to the cathode electrode provided on the head in a dry state, it is desirable that the electrode contact connected to the peripheral edge of the substrate be completely sealed from the plating liquid. Therefore, the electrode contact is sealed from the plating liquid 15 by a sealing member. However, when the plating process is continuously performed, a residue of the plating liquid tends to be deposited and crystallized on the sealing member. The crystallized residue of the plating liquid on the sealing member is liable to reduce the 20 sealing capability of the sealing member, resulting in deteriorated electric conduction between the substrate and the cathode electrode. Furthermore, immediately after the substrate has been plated, an oxide film is likely to be formed on the surface of the substrate by 25 the remaining plating liquid thereon. Therefore, after the substrate has been plated, the substrate and the sealing member need to be immediately cleaned with pure water or the like to replace the remaining plating liquid with the pure water or the like.

30 In the conventional jet plating apparatus, the substrate to be plated is held horizontally and lowered into the plating bath to bring the lower surface of the substrate into contact with the surface (overflow

surface) of the plating liquid, and then further lowered until the entire lower surface of the substrate is immersed in the plating liquid. Therefore, when the substrate is immersed in the plating liquid, air bubbles 5 tend to remain on the lower surface of the substrate because of downwardly overhung portions of components including the electrode contact and the sealing member, i.e., a substrate contact portion. The remaining air bubbles prevent a plated film from normally being formed 10 on the surface of the substrate, and tend to produce defects such as voids in the plated film.

Disclosure of Invention

The present invention has been made in view of 15 the above drawbacks. It is therefore an object of the present invention to provide a substrate processing apparatus which can efficiently clean a substrate and a substrate contact portion held in contact with the substrate to remove a plating liquid therefrom, and can 20 improve the tendency for the substrate to contact the plating liquid to perform a high-quality process.

To achieve the above object, according to an aspect of the present invention, there is provided a substrate processing apparatus for processing a 25 substrate, comprising: a head assembly for holding a substrate; and a plurality of substrate processing sections for performing respective processes on the substrate held by the head assembly; wherein the head assembly is movable between the substrate processing sections while holding the substrate, and the respective processes on the substrate are successively performed in 30 the respective substrate processing sections.

Preferably, one of the substrate processing

sections comprises a plating section for plating the substrate, and another one comprises a cleaning section for cleaning the substrate. Specifically, a substrate processing apparatus (plating apparatus) comprises: a 5 plating section having a plating bath for holding a plating liquid therein; a head assembly for holding a substrate and immersing the substrate in the plating liquid in the plating bath to form a plated film on a surface of the substrate; a cleaning section for cleaning 10 a peripheral edge of the plated substrate and a substrate contact portion held in contact with the substrate; and a drive mechanism for moving the head assembly between the plating section and the cleaning section.

With this arrangement, since it is possible to 15 clean the lower surface of the substrate and the substrate contact portion in such a state that the substrate is held by the head assembly, the plating liquid attached to the substrate and the substrate contact portion is effectively prevented from being 20 crystallized. Therefore, the durability of the substrate contact portion is increased, and a high-quality plating process can be performed while high electric conductivity is maintained.

The cleaning section may comprise an air blower 25 for applying a clean gas, e.g., nitrogen, to dry the cleaned substrate. Alternatively, the cleaning section may rotate the substrate at a high speed to dry the substrate. With this arrangement, not only the cleaning process but also the drying process can be performed in 30 one unit. Therefore, the substrate processing apparatus has a compact structure. Moreover, the substrate contact portion can be kept dry at all times.

The head assembly may comprise a tilting

mechanism for tiltably supporting the substrate. With this arrangement, the surface, to be plated, of the substrate can be brought into contact with the overflow surface of the plating liquid in such a state that the 5 substrate is tilted with respect to the horizontal plane. Therefore, the tendency for the substrate to contact the plating liquid can be improved, so that the plating liquid can smoothly be brought into contact with the substrate and air bubbles can be prevented from remaining 10 on the surface, to be plated, of the substrate. Moreover, since the substrate can be tilted through a large angle while the rotational shaft of the head assembly is being kept vertical, the substrate can easily be controlled for its tilting action and can be tilted 15 under a reduced load.

The sections may be housed in a single cover. A mist tends to be produced around the plating bath, and a highly corrosive environment is developed around the plating bath. The cover is effective to prevent the mist 20 from being scattered. If the drive mechanism is disposed outside of the cover, then particles produced by the drive mechanism are prevented from entering the plating section and other sections, and a mist produced in the plating process is prevented from adversely affecting the 25 drive mechanism, so that the durability of the drive mechanism is increased. Furthermore, if the plating section and the cleaning section are separated from each other, then the cleaning liquid is not mixed with the plating liquid in the plating bath. Therefore, the 30 concentration of the plating liquid is not changed by the mixed cleaning liquid. Inasmuch as the plating section and the cleaning section can be incorporated with each other, the overall substrate processing apparatus has a

compact structure.

The above and other objects, features, and advantages of the present invention will become apparent from the following description when taken in conjunction with the accompanying drawings which illustrate preferred embodiments of the present invention by way of example.

Brief Description of Drawings

FIG. 1 is a vertical cross-sectional view showing a conventional plating apparatus;

FIG. 2 is a plan view showing a substrate processing apparatus according to an embodiment of the present invention;

FIG. 3 is a plan view showing a plating unit in the substrate processing apparatus shown in FIG. 2;

FIG. 4 is a front view of the plating unit shown in FIG. 3;

FIG. 5 is a side view of the plating unit shown in FIG. 3;

FIG. 6 is a vertical cross-sectional view showing a plating section in the plating unit shown in FIG. 3;

FIG. 7 is a vertical cross-sectional view showing a swing arm and a head assembly of the plating unit shown in FIG. 3;

FIG. 8 is a plan view showing a substrate holding arm assembly of the plating unit shown in FIG. 3;

FIG. 9 is a cross-sectional view taken along a line IX-IX in FIG. 8;

FIG. 10 is an enlarged cross-sectional view showing a substrate contact portion shown in FIG. 9;

FIG. 11 is an enlarged cross-sectional view showing a region where a rotational shaft of the head

assembly and the substrate holding arm assembly shown in FIG. 7 are connected to each other;

FIG. 12 is a front view showing a cleaning section in the plating unit shown in FIG. 3;

5 FIG. 13 is a plan view showing a drive mechanism in the plating unit shown in FIG. 3;

FIG. 14 is a side view of the drive mechanism shown in FIG. 13;

10 FIG. 15 is a cross-sectional view taken along a line XV-XV in FIG. 13;

FIG. 16 is a cross-sectional view taken along a line XVI-XVI in FIG. 13;

FIG. 17 is a plan view showing a plating unit according to another embodiment of the present invention;

15 FIG. 18 is a plan view of an example of a substrate plating apparatus;

FIG. 19 is a schematic view showing airflow in the substrate plating apparatus shown in FIG. 18;

20 FIG. 20 is a cross-sectional view showing airflows among areas in the substrate plating apparatus shown in FIG. 18;

FIG. 21 is a perspective view of the substrate plating apparatus shown in FIG. 18, which is placed in a clean room;

25 FIG. 22 is a plan view of another example of a substrate plating apparatus;

FIG. 23 is a plan view of still another example of a substrate plating apparatus;

30 FIG. 24 is a plan view of still another example of a substrate plating apparatus;

FIG. 25 is a view showing a plan constitution example of the semiconductor substrate processing apparatus;

FIG. 26 is a view showing another plan constitution example of the semiconductor substrate processing apparatus;

5 FIG. 27 is a view showing still another plan constitution example of the semiconductor substrate processing apparatus;

FIG. 28 is a view showing still another plan constitution example of the semiconductor substrate processing apparatus;

10 FIG. 29 is a view showing still another plan constitution example of the semiconductor substrate processing apparatus;

FIG. 30 is a view showing still another plan constitution example of the semiconductor substrate 15 processing apparatus;

FIG. 31 is a view showing a flow of the respective steps in the semiconductor substrate processing apparatus illustrated in FIG. 30;

20 FIG. 32 is a view showing a schematic constitution example of a bevel and backside cleaning unit;

FIG. 33 is a view showing a schematic constitution of an example of an electroless plating apparatus;

25 FIG. 34 is a view showing a schematic constitution of another example of an electroless plating apparatus;

FIG. 35 is a vertical sectional view of an example of an annealing unit; and

30 FIG. 36 is a transverse sectional view of the annealing unit.

Best Mode for Carrying Out the Invention

A substrate processing apparatus according to an embodiment of the present invention will be described below with reference to FIGS. 2 through 16. FIG. 2 is a 5 plan view showing a substrate processing apparatus according to an embodiment of the present invention.

A substrate processing apparatus according to an embodiment of the present invention serves as a plating apparatus for plating a surface of a substrate 10 with a metal such as copper or the like. As shown in FIG. 2, the substrate processing apparatus is placed in a rectangular housing 1, in which a plurality of substrates such as semiconductor substrates are successively plated. The substrate processing apparatus (plating apparatus) 15 comprises a pair of loading/unloading units 10 each for storing a plurality of substrates, a pair of bevel etching/chemical cleaning/drying units 16 for cleaning a plated substrate with a chemical liquid, a pair of substrate stages 18 for holding a substrate thereon and 20 inverting the substrate, and four plating units 22 for plating a substrate and cleaning the plated substrate. The housing 1 has therein a first transfer device 24 for transferring a substrate between the loading/unloading units 10, the bevel etching/chemical cleaning/drying 25 units 16, and the substrate stages 18, and a second transfer device 28 for transferring a substrate between the substrate stages 18 and the plating units 22.

Substrates are accommodated within a cassette in such a state that the face side (the surface on which 30 semiconductor devices are formed, or the surface to be processed) of each of the substrate faces upwardly. The cassette accommodating the substrates is placed on one of the loading/unloading units 10. The first transfer

device 24 takes up a substrate from the cassette, transfers it to one of the substrate stages 18, and places it on the substrate stage 18. On the substrate stage 18, the substrate is turned upside down, i.e., 5 inverted so that its face side faces downwardly, by an inverter provided in the substrate stage 18. Then, the inverted substrate is transferred from the substrate stage 18 to the second transfer device 28. The second transfer device 28 transfers the substrate to a head 10 assembly (described later on) of one of the plating units 22, in which the plating process of the substrate is performed.

The plating units 22 of the plating apparatus according to the present embodiment will be described 15 below. Since all the four plating units 22 are identical in structure, only one of them will be described in detail below. FIG. 3 is a plan view showing the plating unit 22 according to the present embodiment, FIG. 4 is a front view of the plating unit 22 shown in FIG. 3, and 20 FIG. 5 is a side view of the plating unit 22 shown in FIG. 3.

As shown in FIGS. 3 through 5, the plating unit 22 is divided by a partition wall 30 into two substrate processing sections, i.e., a plating section 32 for 25 plating a substrate W and a cleaning section 34 for cleaning a plated substrate W. The cleaning section 34 has functions of receiving and transferring a substrate W, and pre-treating a substrate W, and cleaning and drying a plated substrate W.

30 The plating section 32 and the cleaning section 34 are covered with a cover 36. The cover 36 has an opening 36a defined in a side panel thereof near the cleaning section 34, and a shutter 38 capable of opening

and closing the opening 36a is disposed in the opening 36a. When the shutter 38 closes the opening 36a to seal the interior of the plating unit 22, a mist generated in the plating unit 22 during the plating process is 5 prevented from being scattered out of the plating unit 22.

The plating unit 22 has a swing arm 40 disposed therein for swinging movement about its pivoted end between the plating section 32 and the cleaning section 10 34. The swing arm 40 has a free end connected to a head assembly 42 suspended therefrom, which holds a substrate W. When the swing arm 40 is angularly moved about its pivoted end, the head assembly 42 is angularly moved between a plating position P in the plating section 32 15 and a cleaning position Q in the cleaning section 34.

The plating unit 22 may alternatively have a linearly movable mechanism, rather than the swing arm 40, for translating the head assembly 42 between the plating position P in the plating section 32 and the cleaning 20 position Q in the cleaning section 34.

FIG. 6 is a vertical cross-sectional view showing a main part of the plating section 32 in the plating unit 22. As shown in FIG. 6, the plating section 32 has a plating bath 44 in the substantially cylindrical 25 form for holding a plating liquid therein, and a cylindrical inner weir member 46 and a cylindrical outer weir member 48 which are disposed within the plating bath 44. The inner weir member 46 defines an upwardly opened plating chamber 50 in the plating bath 44, and an anode 30 52 is disposed at the bottom of the plating chamber 50.

A plurality of plating liquid ejection nozzles 54 horizontally projecting toward the center of the plating chamber 50 are provided on the inner

circumferential wall of the inner weir member 46 at equal intervals along the circumferential direction. The plating liquid ejection nozzles 54 are communicated with plating liquid supply passages 56 extending vertically 5 through the interior of the inner weir member 46. A plating liquid is supplied to the plating liquid ejection nozzles 54 from a plating liquid regulating tank (not shown) via the plating liquid supply passages 56. Control valves 58 for supplying the plating liquid at a 10 constant rate are disposed between the plating liquid supply passages 56 and the plating liquid regulating tank.

First plating liquid discharge ports 62 for withdrawing the plating liquid in the plating chamber 50 15 are defined in the peripheral portion of the bottom of the plating chamber 50. Second plating liquid discharge ports 64 for discharging the plating liquid overflowing the outer weir member 48 are defined radially around the outer weir member 48. Third plating liquid discharge 20 ports 66 for discharging the plating liquid overflowing the inner weir member 46 are defined between the inner weir member 46 and the outer weir member 48.

Each of the first plating liquid discharge ports 62 is connected to a reservoir (not shown). A flow 25 controller 68 is disposed between the first plating liquid discharge ports 62 and the reservoir. Each of the second plating liquid discharge ports 64 and each of the third plating liquid discharge ports 66 are connected directly to the reservoir. The plating liquid fed into 30 the reservoir is supplied to the plating liquid regulating tank from the reservoir by a pump. The plating liquid regulating tank has a temperature controller (not shown) for controlling the temperature of

the plating liquid in the plating liquid regulating tank, and a plating liquid analyzing device (not shown) for extracting and analyzing a sample from the plating liquid in the plating liquid regulating tank.

5 In the present embodiment, baffle plates (stream regulating plates) 60 are disposed above the anode 52 in the plating chamber 50. The baffle plates 60 produce a downflow of plating liquid directed toward the anode 52, and this downflow of plating liquid is
10 discharged from the first plating liquid discharge ports 62. The baffle plates 60 serve to prevent the jet of the plating liquid ejected from the plating liquid ejection nozzles 54 from directly flowing over the surface of the anode 52, for thereby preventing a black film formed on
15 the surface of the anode 52 from being peeled away from the anode 52 by the jet of the plating liquid.

FIG. 7 is a vertical cross-sectional view showing a main part of the swing arm 40 and the head assembly 42. As shown in FIG. 7, the swing arm 40 is fixed to the upper end of a rotatable hollow support post 74 so as to be horizontally moved upon rotation of the support post 74. A rotational shaft 78 rotatably supported by a bearing 76 is inserted through the support post 74 so as to be rotated relative to the support post
20 74. An upper rotational shaft pulley 80 is fixed to the upper end of the rotational shaft 78.
25

The head assembly 42 is fixedly mounted on the swing arm 40. As shown in FIG. 7, the head assembly 42 comprises an outer tube 82 fixed to the swing arm 40, a rotational shaft 84 extending vertically through the outer tube 82, a substrate holding arm assembly 86 for holding a substrate W on its lower surface, and a movable member 96 vertically movable relatively to the outer tube
30

82. The substrate holding arm assembly 86 is connected to the lower end of the rotational shaft 84 by a pin 88.

The rotational shaft 84 is rotatably supported on the outer tube 82 by bearings 90 so as to be rotated 5 relative to the outer tube 82. A head assembly pulley 92 is fixed to the upper end of the rotational shaft 84. The head assembly pulley 92 is operatively connected to the upper rotational shaft pulley 80 via a timing belt 94. Therefore, when the rotational shaft 78 in the 10 support post 74 is rotated about its own axis, the rotational shaft 84 is rotated together with the substrate holding arm assembly 86.

A hermetically sealed space 98 is defined between the movable member 96 and the outer tube 82 by a 15 sealing members 97, and communicates with an air supply passage 99. When air is selectively supplied to and discharged from the hermetically sealed space 98 through the air supply passage 99, the movable member 96 is vertically moved relatively to the outer tube 82. The 20 movable member 96 has a plurality of downwardly extending pressing rods 100 mounted on an outer peripheral edge thereof and a plurality of air cylinders 104 for vertically moving respective pushers 102.

FIG. 8 is a plan view showing the substrate holding arm assembly 86, and FIG. 9 is a cross-sectional view taken along a line IX-IX shown in FIG. 8. As shown in FIG. 8, the substrate holding arm assembly 86 comprises a centrally positioned base 86a and six arms 86b extending radially outwardly from the base 86a. Of 25 the six arms 86b, three alternate arms support on their radially outer ends respective vertically movable rods 106 (see FIG. 9) extending vertically through the outer peripheral edge of the arms 86b. Nuts 108 are mounted

respectively on the upper ends of the vertically movable rods 106 in such a state that helical compression springs 110 are interposed between the nuts 108 and the arms 86b, respectively. A ring-shaped substrate contact portion 112 projecting radially inwardly is fixed to the lower ends of the vertically movable rods 106. When the pressing rods 100 on the movable member 96 are brought into abutment against the nuts 108 on the upper ends of the vertically movable rods 106 and then lowered to move the vertically movable rods 106 downwardly against the bias of the helical compression springs 110, the substrate contact portion 112 is downwardly moved from the substrate holding arm assembly 86 as indicated by the dotted lines in FIG. 9.

FIG. 10 is an enlarged cross-sectional view showing the substrate contact portion 112. As shown in FIG. 10, a ring-shaped sealing member 114 is mounted on the substrate contact portion 112. The ring-shaped sealing member 114 extends radially inwardly and has an upwardly projecting tip on its radially inner end. The substrate holding arm assembly 86 has a presser 116 projecting downwardly near the upwardly projecting tip of the ring-shaped sealing member 114. The helical compression springs 110 are selected to have such spring properties that when the substrate contact portion 112 is lifted relatively to a substrate W which is held by chucking mechanisms, the sealing member 114 is pressed against the peripheral edge of the substrate W to reliably seal the pressed peripheral edge of the substrate W. A cathode electrode contact 118 connected to an electrode is disposed above the sealing member 114. The cathode electrode contact 118 is brought into electric contact with the substrate W when the sealing

member 114 is pressed against the peripheral edge of the substrate W.

The three alternate arms 86b also have respective chucking mechanisms 120 spaced at equal 5 angular intervals. As shown in FIG. 9, each of the chucking mechanisms 120 comprises a base 122 mounted on an upper surface of the arm 86b, a rod 124 vertically movably mounted on the base 122, and a claw 128 angularly movable about a pivot shaft 126. Nuts 130 are mounted on 10 the upper end of the rod 124, and a helical compression spring 132 is interposed between the nut 130 and the base 122.

As shown in FIG. 9, the claw 128 is connected to the rod 124 by a horizontally movable pin 134. 15 Accordingly, when the rod 124 moves upwardly, the claw 128 is angularly moved radially inwardly about the pivot shaft 126, and when the rod 124 moves downwardly, the claw 128 is angularly moved radially outwardly about the pivot shaft 126. When the air cylinders 104 on the 20 movable member 96 are actuated to press the pushers 102 against the nuts 130 for pushing the rods 124 downwardly, the rods 124 are moved downwardly against the bias of the helical compression springs 132 for thereby angularly moving the claws 128 radially outwardly about the pivot 25 shafts 126. When the actuation of the air cylinders 104 is stopped, the rods 124 are lifted under the bias of the helical compression springs 132 to angularly move the claws 128 radially inwardly about the pivot shafts 126. Thus, the peripheral edge of the substrate W can be 30 gripped by the chucking mechanisms 120. Specifically, the peripheral edge of the substrate W is positioned and gripped by the three chucking mechanisms 120 (claws 128), so that the substrate W is held on the lower surface of

the substrate holding arm assembly 86.

FIG. 11 is an enlarged cross-sectional view showing a region where the rotational shaft 84 of the head assembly 42 and the substrate holding arm assembly 5 86 shown in FIG. 7 are connected to each other. As shown in FIG. 11, a disk-shaped upper member 140 is attached to the lower end of the rotational shaft 84 of the head assembly 42, and a disk-shaped lower member 142 is attached to the upper surface of the substrate holding 10 arm assembly 86. The upper and lower members 140, 142 are coupled to each other by a horizontal pin 88 to constitute a tilting mechanism for tiltably supporting the substrate holding arm assembly 86 by tilting the lower member 142 and the substrate holding arm assembly 15 86 about the pin 88. A helical compression spring 144 is interposed between peripheral sides of the upper and lower members 140, 142 for normally biasing the peripheral sides apart from each other, and a stopper bolt 146 is fixed to a peripheral side of the lower 20 member 142 at a position diametrically opposite to the helical compression spring 144. The stopper bolt 146 has an upper end which is brought into abutment against the lower surface of the upper member 140. When the upper end of the stopper bolt 146 is brought into abutment 25 against the lower surface of the upper member 140, the substrate holding arm assembly 86 is horizontally positioned. An L-shaped hook 148 is mounted on the substrate holding arm assembly 86.

As shown in FIGS. 8 and 11, an air cylinder 150 30 is mounted on the outer tube 82 of the head assembly 82, and a pusher 152 is connected to the air cylinder 150 so as to be vertically moved upon actuation of the air cylinder 150. When the air cylinder 150 is actuated, the

pusher 152 is lowered into abutment against the upper end of the hook 148 to thus lower the hook 148. Accordingly, the hook 148 and the substrate holding arm assembly 86 are tilted downwardly about the pin 88 against the bias 5 of the helical compression spring 144. When the actuation of the air cylinder 150 is stopped, the hook 148 and the substrate holding arm assembly 86 are tilted back under the bias of the helical compression spring 144, and finally the upper end of the stopper bolt 146 is 10 brought into abutment with the lower surface of the upper member 140 so that the substrate holding arm assembly 86 is horizontally positioned.

Next, the cleaning section 34 of the plating unit 22 will be described below. FIG. 12 is a front view 15 showing the cleaning section 34 shown in FIG. 3.

As shown in FIGS. 3 and 12, the cleaning section 34 has six cleaning nozzles 160 for cleaning a substrate W which has been plated, particularly, the peripheral portion of a plated substrate W and the 20 substrate contact portion 112. The cleaning nozzles 160 are connected to a cleaning liquid supply (not shown), and a cleaning liquid, e.g., pure water, is ejected toward the lower surface of the substrate W from the cleaning nozzles 160. The cleaning section 34 also has 25 an arm-shaped air blower 162 for drying the substrate W which has been cleaned. The air blower 162 is connected to an air supply (not shown) via an air supply passage 164, and a dry gas such as dry air or nitrogen is ejected toward the lower surface of the substrate W from the air 30 blower 162. The air blower 162 is rotatable about one end thereof which is connected to the upper end of the air supply passage 164.

As described above, the support post 74 is

vertically movable and rotatable about its own axis, and the rotational shaft 78 disposed in the support post 74 is rotatable with respect to the support post 74. Next, a drive mechanism for vertically moving and rotating the support post 74 and also rotating the rotational shaft 78 will be described below with reference to FIGS. 13 through 16. FIG. 13 is a plan view showing the drive mechanism, FIG. 14 is a side view of the drive mechanism, FIG. 15 is a cross-sectional view taken along a line XV-XV in FIG. 13, and FIG. 16 is a cross-sectional view taken along a line XVI-XVI in FIG. 13. As shown in FIGS. 4 and 5, the drive mechanism 170 is disposed outside of the cover 36. Therefore, particles produced by the drive mechanism 170 are prevented from entering the plating section 32 and other sections, and a mist produced in the plating process is prevented from adversely affecting the drive mechanism 170, so that the durability of the drive mechanism 170 is increased.

As shown in FIGS. 13 through 16, the drive mechanism 170 basically comprises a fixed base 172 fixedly mounted on a frame of the plating unit 22, and a vertically movable base 174 vertically movably mounted on the fixed base 172. The fixed base 172 supports a lifting/lowering motor 176 thereon, and the vertically movable base 174 supports a rotational motor 178 and a swinging motor 180 thereon.

As shown in FIG. 16, a vertically extending screw shaft 182 is rotatably mounted on the fixed base 172 by bearings 184. A nut 186 mounted on the vertically movable base 174 is held in engagement with the screw shaft 182. A screw shaft pulley 188 is mounted on a lower end of the screw shaft 182, and operatively connected via a timing belt 190 to a lifting/lowering

motor pulley 192 mounted on the shaft of the lifting/lowering motor 176. The vertically movable base 174 has a slider 196 (see FIG. 15) which is vertically guided by a slider support 194 mounted on the fixed base 172. When the lifting/lowering motor 176 is energized, the screw shaft 182 is rotated about its own axis to vertically move the nut 186 and the vertically movable base 174 while the slider 196 is being guided by the slider support 194 mounted on the fixed base 172.

The support post 74 is supported on the vertically movable base 174 by bearings 198, and a support post pulley 200 is fixed to the lower end of the support post 74. The support post pulley 200 is operatively connected via a timing belt 202 to a swinging motor pulley 204 mounted on the shaft of the swinging motor 180 (see FIG. 14). When the swinging motor 180 is energized, the support post 74 is rotated about its own axis to angularly move the swing arm 40 fixed to the support post 74.

As shown in FIG. 15, a lower rotational shaft pulley 206 is mounted on the lower end of the rotational shaft 78 inserted in the support post 74. The lower rotational shaft pulley 206 is operatively connected via a timing belt 208 to a rotational motor pulley 210 mounted on the shaft of the rotational motor 178. When the rotational motor 178 is energized, the rotational shaft 78 is rotated about its own axis to rotate the head assembly pulley 92 connected to the upper rotational shaft pulley 80, for thereby rotating the rotational shaft 84 of the head assembly 42.

A plating process for plating a substrate such as a semiconductor substrate with the substrate processing apparatus (plating apparatus) according to the

present embodiment will be described below.

Substrates are accommodated within a cassette in such a state that the face side (the surface on which semiconductor devices are formed, or the surface to be processed) of each of the substrate faces upwardly. The cassette accommodating the substrates is placed on one of the loading/unloading units 10. The first transfer device 24 takes up a substrate from the cassette, transfers it to one of the substrate stages 18, and places it on the substrate stage 18. On the substrate stage 18, the substrate is turned upside down, i.e., inverted so that its face side faces downwardly, by the inverter provided in the substrate stage 18. Then, the inverted substrate is transferred from the substrate stage 18 to the second transfer device 28. The shutter 38 of one of the plating units 22 is opened, and the second transfer device 28 transfers the substrate into the plating unit 22 through the opening 36a in the cover 36.

For transferring the substrate to the plating unit 22, the swinging motor 180 of the drive mechanism 170 is energized to turn the support post 74 through a certain angle about its own axis, for thereby moving the head assembly 42 to the cleaning position Q. Then, the movable member 96 is lowered to bring the pressing rods 100 into abutment against the nuts 108 on the upper ends of the vertically movable rods 106 and to push down the vertically movable rods 106 against the bias of the helical compression springs 110. Accordingly, the substrate contact portion 112 is downwardly moved from the substrate holding arm assembly 86.

Then, the air cylinders 104 on the movable member 96 are actuated to bring the pushers 102 into

abutment against the nuts 130 of the chucking mechanisms 120. Consequently, the rods 124 are lowered against the helical compression springs 132 to angularly move the claws 128 radially outwardly.

5 The hand of the second transfer device 28, which has been inserted into the plating unit 22, is lifted to bring the upper surface (reverse side) of the substrate W into abutment against the presser 116 of the substrate holding arm assembly 86. In this state, the 10 actuation of the air cylinders 104 is stopped for releasing the pushers 102 to thus move the claws 128 of the chucking mechanisms 120 radially inwardly. Thus, the substrate W is positioned and gripped by the claws 128. Then, the hand of the second transfer device 28 is 15 withdrawn from the plating unit 22, and the shutter 38 is closed.

When the above transfer of the substrate W is completed, the movable member 96 is upwardly moved to lift the substrate contact portion 112. When the 20 substrate contact portion 112 is thus lifted, the peripheral edge of the substrate W is brought into electric contact with the cathode electrode contact 118, and sealed by the sealing member 114 for protection against immersion in the plating liquid. Thereafter, the 25 substrate W may be pre-treated (pre-coated) by a chemical liquid which is ejected from the cleaning nozzles 160 in the cleaning section 34 toward the lower surface of the substrate W.

Then, the swinging motor 180 of the drive 30 mechanism 170 is energized to turn the support post 74 through a given angle for thereby moving the head assembly 42 which holds the substrate W into the plating position P. The air cylinder 150 of the head assembly 42

is actuated to bring the pusher 152 into engagement with the hook 148 of the substrate holding arm assembly 86, and to lower the hook 148 for thereby tilting the substrate holding arm assembly 86 through an angle 5 ranging from 1° to 3°. With the substrate holding arm assembly 86 being thus tilted, the lifting/lowering motor 176 of the drive mechanism 170 is energized to lower the support post 74 by a predetermined distance until the substrate W held on the lower surface of the substrate holding arm assembly 86 is immersed in the plating liquid 10 in the plating bath 44.

When the substrate W is thus tilted and immersed in the plating liquid, the surface of the substrate W is progressively brought into contact with the overflow surface of the plating liquid as the substrate W is lowered. The contact area of the surface of the substrate W with the plating liquid is thus progressively spread while removing air bubbles from the surface of the substrate W. Therefore, the tendency for 15 the substrate W to contact the plating liquid can be improved. Since only the substrate holding arm assembly 86 can be tilted while the rotational shaft 84 of the head assembly 42 is being kept vertical, the head assembly 42 and the swing arm 40 do not need to be 20 tilted. Therefore, the substrate W can be tilted through a large angle, and hence the substrate W can easily be 25 controlled for its tilting action and can be tilted under a reduced load. The substrate holding arm assembly 86 may be lowered in its horizontal attitude without being 30 tilted.

After the substrate W is immersed in the plating liquid, the actuation of the air cylinder 150 is stopped for returning the substrate holding arm assembly

86 to its horizontal position. Thereafter, the rotational motor 178 of the drive mechanism 170 is energized to rotate to the rotational shaft 84 of the head assembly 42 via the rotational shaft 78 in the 5 support post 74, for thereby rotating the substrate W at an intermediate rotational speed of about several tens revolutions per minute. A current is supplied between the anode 52 and the substrate W to form a plated film on the surface of the substrate W.

10 After the plating process is completed, the rotation of the substrate W is stopped. The air cylinder 150 is actuated to bring the pusher 152 into engagement with the hook 148 and to lower the hook 148 for tilting the substrate holding arm assembly 86 through an angle 15 ranging from 1° to 3°. Therefore, a residue of the plating liquid attached to the lower surface of the substrate W can easily drop off the substrate W by gravity. With the substrate holding arm assembly 86 being thus tilted, the lifting/lowering motor 176 is 20 energized to lift the support post 74 and the head assembly 42 by a predetermined distance. Thereafter, the actuation of the air cylinder 150 is stopped for returning the substrate holding arm assembly 86 to its horizontal position.

25 Then, the swinging motor 180 of the drive mechanism 170 is energized to turn the support post 74 about its own axis through a given angle, for thereby moving the head assembly 42 which holds the substrate W to the cleaning position Q. The lifting/lowering motor 30 176 is energized to lower the support post 74 by a predetermined distance. Then, the rotational motor 178 is energized to rotate the substrate holding arm assembly 86 at a rotational speed of 100 rpm, for example, and at

the same time a cleaning liquid, e.g., pure water, is ejected from the cleaning nozzles 160 toward the lower surface of the substrate W to clean the plated substrate W and the substrate contact portion 112. Since it is 5 possible to clean the lower surface of the substrate W and the substrate contact portion 112 of the head assembly 42 in such a state that the substrate W is held by the substrate holding arm assembly 86, no plating liquid will be left on the tip of the sealing member 114 10 of the substrate contact portion 112 when the substrate W is released. Therefore, according to the present invention, the sealing capability and the electric conductivity can be prevented from being deteriorated by the crystallization of the remaining plating liquid.

15 Thereafter, the rotational speed of the substrate holding arm assembly 86 is increased to 300 rpm, for example, to spin off the cleaning liquid. At the same time, air is applied from the air blower 162 to the substrate W to dry the substrate W. If a spin drying 20 process were employed, the substrate would usually need to be rotated at 2000 rpm while being dried. According to the present invention, since air is applied to the substrate W from the air blower 162, the substrate W is not required to be rotated at such a high speed.

25 After the cleaning liquid is removed from the substrate W and the substrate W is dried, the movable member 96 is lowered to bring the pressing rods 100 into abutment against the nuts 108 on the upper ends of the vertically movable rods 106 and to lower the vertically 30 movable rods 106 against the bias of the helical compression springs 110, for thereby downwardly moving the substrate contact portion 112 relatively to the substrate W.

Subsequently, the shutter 38 of the plating unit 22 is opened, and the hand of the second transfer device 28 is inserted through the opening 36a in the cover 36 into the plating unit 22. Then, the hand of the 5 second transfer device 28 is lifted to a position capable of receiving the substrate W. Then, the air cylinders 104 on the movable member 96 are actuated to bring the pushers 102 into abutment against the nuts 130 of the chucking mechanisms 120 and to lower the rods 124 against 10 the bias of the helical compression springs 132, for thereby angularly moving the claws 128 radially outwardly. The substrate W is released and placed onto the hand of the second transfer device 28. Thereafter, the hand of the second transfer device 28 with the 15 substrate W placed thereon is withdrawn from the plating unit 22, and the shutter 38 is closed.

The second transfer device 28 which has received the substrate W transfers the substrate W to one of the bevel etching/chemical cleaning/drying units 16. 20 In the bevel etching/chemical cleaning/drying unit 16, the plated substrate W is cleaned with a chemical liquid, a thin copper film formed on the bevel portion of the substrate W is etched away, and the substrate W is cleaned with water and dried. After the substrate W is 25 thus processed in the bevel etching/chemical cleaning/drying unit 16, the substrate W is returned to the cassette in the loading/unloading unit 10 by the first transfer device 10. A series of plating process is thus performed.

30 While the present invention has been described in detail with reference to the preferred embodiment thereof, it would be apparent to those skilled in the art that many modifications and variations may be made

therein without departing from the spirit and scope of the present invention. Next, some possible variations of the embodiment will be described below.

A tank for immersing a substrate W in a processing liquid may be installed in the cleaning section 34. In this case, the substrate W can be pre-treated, e.g., pre-dipped or pre-plated, in the plating unit 22. A pre-dipping process is a process of coating a uniform film of a pre-treatment liquid (pre-dipping liquid), which includes a constituent of the plating liquid, on the surface of the substrate on which a barrier layer and a seed layer have successively been deposited, for improving the adhesive properties of plating liquid to the substrate. A pre-plating process is a process of pre-plating the surface of the substrate on which a barrier layer and a seed layer have successively been deposited, for reinforcing the incomplete seed layer.

FIG. 17 is a plan view showing a plating unit according to another embodiment of the present invention. As shown FIG. 17, the plating unit has a plurality of substrate processing sections including a pre-plating section 250, a pre-treatment/post-treatment/cleaning section 251, and a secondary plating section 252, disposed around the support post 74 to which the swing arm 40 is fixed. Thus, with a plurality of substrate processing sections, different processes on a substrate can be performed in the single plating unit 22.

As described above, according to the present invention, since it is possible to clean the lower surface of the substrate and the substrate contact portion in such a state that the substrate is held by the head assembly, the plating liquid which may have remained

on and been attached to the substrate contact portion is effectively prevented from being crystallized. Therefore, the durability of the substrate contact portion is increased, and a high-quality plating process 5 can be performed while high electric conductivity is maintained.

Furthermore, since the plating section and the cleaning section are separated from each other, the cleaning liquid is not mixed with the plating liquid in 10 the plating bath. Therefore, the concentration of the plating liquid is not changed by the mixed cleaning liquid.

Since the substrate processing sections are covered by one cover, a mist produced in the cover is 15 prevented from being scattered out of the cover. Further, since the drive mechanism is disposed outside of the cover, particles produced by the drive mechanism are prevented from entering the plating section and other sections. A mist produced in the plating process is 20 prevented from adversely affecting the drive mechanism, so that the durability of the drive mechanism is increased. Inasmuch as various components can be incorporated with each other, the overall substrate processing apparatus has a compact structure.

25 Furthermore, according to the present invention, the surface, to be plated, of the substrate can be brought into contact with the overflow surface of the plating liquid in such a state that the substrate is tilted with respect to the horizontal plane. Therefore, 30 the tendency for the substrate to contact the plating liquid can be improved, so that the plating liquid can smoothly be brought into contact with the substrate and air bubbles can be prevented from remaining on the

surface, to be plated, of the substrate. Moreover, since the substrate can be tilted through a large angle while the rotational shaft of the head assembly is being kept vertical, the substrate can easily be controlled for its 5 tilting action and can be tilted under a reduced load.

FIG. 18 is a plan view of an example of a substrate plating apparatus. The substrate plating apparatus shown in FIG. 18 comprises a loading/unloading area 520 for housing substrate cassettes which 10 accommodate semiconductor substrates, a processing area 530 for processing semiconductor substrates, and a cleaning and drying area 540 for cleaning and drying plated semiconductor substrates. The cleaning and drying area 540 is positioned between the loading/unloading area 15 520, and the processing area 530. A partition 521 is disposed between the loading/unloading area 520, and the cleaning and drying area 540. And a partition 523 is disposed between the cleaning and drying area 540, and the processing area 530.

20 The partition 521 has a passage (not shown) defined therein for transferring semiconductor substrates therethrough between the loading/unloading area 520, and the cleaning and drying area 540, and supports a shutter 522 for opening and closing the passage. The partition 25 523 has a passage (not shown) defined therein for transferring semiconductor substrates therethrough between the cleaning and drying area 540, and the processing area 530, and supports a shutter 524 for opening and closing the passage. The cleaning and drying area 540 and the processing area 530 can independently be supplied with and discharge air.

30 The substrate plating apparatus shown in FIG. 18 is placed in a clean room, which accommodates

semiconductor fabrication facilities. The pressures in the loading/unloading area 520, the processing area 530, and the cleaning and drying area 540 are selected as follows:

5 The pressure in the loading/unloading area 520
> the pressure in the cleaning and drying area 540 > the
pressure in the processing area 530.

10 The pressure in the loading/unloading area 520
is lower than the pressure in the clean room. Therefore,
air does not flow from the processing area 530 into the
cleaning and drying area 540, and air does not flow from
the cleaning and drying area 540 into the
loading/unloading area 520. Furthermore, air does not
flow from the loading/unloading area 520 into the clean
15 room.

20 The loading/unloading area 520 houses a loading
unit 520a and an unloading unit 520b, each accommodating
a substrate cassette for storing semiconductor
substrates. The cleaning and drying area 540 houses two
water cleaning units 541 for cleaning plated
semiconductor substrates with water, and two drying units
542 for drying plated semiconductor substrates. Each of
the water cleaning units 541 may comprise a pencil-shaped
cleaner with a sponge layer mounted on a front end
25 thereof or a roller with a sponge layer mounted on an
outer circumferential surface thereof. Each of the
drying units 542 may comprise a drier for spinning a
semiconductor substrate at a high speed to dehydrate and
dry. The cleaning and drying area 540 also has a
30 transfer unit (transfer robot) 543 for transferring
semiconductor substrates.

 The processing area 530 houses a plurality of
pretreatment chambers 531 for pretreating semiconductor

substrates prior to being plated, and a plurality of plating chambers 532 for plating semiconductor substrates with copper. The processing area 530 also has a transfer unit (transfer robot) 543 for transferring semiconductor substrates.

FIG. 19 shows in side elevation air flows in the substrate plating apparatus. As shown in FIG. 19, fresh air is introduced from the exterior through a duct 546 and forced through high-performance filters 544 by 10 fans from a ceiling 540a into the cleaning and drying area 540 as downward clean air flows around the water cleaning units 541 and the drying units 542. Most of the supplied clean air is returned from a floor 540b through a circulation duct 545 to the ceiling 540a, from which 15 the clean air is forced again through the filters 544 by the fans into the cleaning and drying area 540. Part of the clean air is discharged from the substrate cleaning units 541 and the drying units 542 through a duct 552 out of the cleaning and drying area 540.

20 In the processing area 530 which accommodates the pretreatment chambers 531 and the plating chambers 532, particles are not allowed to be applied to the surfaces of semiconductor substrates even though the processing area 530 is a wet zone. To prevent particles 25 from being applied to semiconductor substrates, downward clean air flows around the pretreatment chambers 531 and the plating chambers 532. Fresh air is introduced from the exterior through a duct 539 and forced through high-performance filters 533 by fans from a ceiling 530a into 30 the processing area 530.

If the entire amount of clean air as downward clean air flows introduced into the processing area 530 were always supplied from the exterior, then a large

amount of air would be required to be introduced into and discharged from the processing area 530 at all times. According to this embodiment, air is discharged from the processing area 530 through a duct 553 at a rate 5 sufficient enough to keep the pressure in the processing area 530 lower than the pressure in the cleaning and drying area 540, and most of the downward clean air introduced into the processing area 530 is circulated through circulation ducts 534, 535. The circulation duct 10 534 extends from the cleaning and drying area 540 and is connected to the filters 533 over the ceiling 530a. The circulation duct 535 is disposed in the cleaning and drying area 540 and connected to the pipe 534 in the cleaning and drying area 540.

15 The circulating air that has passed through the processing area 530 contains a chemical mist and gases from solution bathes. The chemical mist and gases are removed from the circulating air by a scrubber 536 and mist separators 537, 538 which are disposed in the pipe 20 534 that is connected to the pipe 535. The air which circulates from the cleaning and drying area 540 through the scrubber 536 and the mist separators 537, 538 back into the circulation duct 534 over the ceiling 530a is free of any chemical mist and gases. The clean air is 25 then forced through the filters 533 by the fans to circulate back into the processing area 530.

Part of the air is discharged from the processing area 530 through the duct 53 connected to a floor 530b of the processing area 530. Air containing a 30 chemical mist and gases is also discharged from the processing area 530, through the duct 553. An amount of fresh air which is commensurate with the amount of air discharged through the duct 553 is supplied from the duct

539 into the plating chamber 530 under the negative pressure developed therein with respect to the pressure in the clean room.

As described above, the pressure in the 5 loading/unloading area 520 is higher than the pressure in the cleaning and drying area 540 which is higher than the pressure in the processing area 530. When the shutters 522, 524 (see FIG. 18) are opened, therefore, air flows successively through the loading/unloading area 520, the 10 cleaning and drying area 540, and the processing area 530, as shown in FIG. 20. Air discharged from the cleaning and drying area 540 and the processing area 530 flows through the ducts 552, 553 into a common duct 554 (see FIG. 21) which extends out of the clean room.

15 FIG. 21 shows in perspective the substrate plating apparatus shown in FIG. 18, which is placed in the clean room. The loading/unloading area 520 includes a side wall which has a cassette transfer port 555 defined therein and a control panel 556, and which is 20 exposed to a working zone 558 that is compartmented in the clean room by a partition wall 557. The partition wall 557 also compartments a utility zone 559 in the clean room in which the substrate plating apparatus is installed. Other sidewalls of the substrate plating 25 apparatus are exposed to the utility zone 559 whose air cleanliness is lower than the air cleanliness in the working zone 558.

As described above, the cleaning and drying area 540 is disposed between the loading/unloading area 30 520, and the processing area 530. The partition 521 is disposed between the loading/unloading area 520, and the cleaning and drying area 540. The partition 523 is disposed between the cleaning and drying area 540, and

the processing area 530. A dry semiconductor substrate is loaded from the working zone 558 through the cassette transfer port 555 into the substrate plating apparatus, and then plated in the substrate plating apparatus. The 5 plated semiconductor substrate is cleaned and dried, and then unloaded from the substrate plating apparatus through the cassette transfer port 555 into the working zone 558. Consequently, no particles and mist are applied to the surface of the semiconductor substrate, 10 and the working zone 558 which has higher air cleanliness than the utility zone 557 is prevented from being contaminated by particles, chemical mists, and cleaning solution mists.

In the embodiment shown in FIGS. 18 and 19, the 15 substrate plating apparatus has the loading/unloading area 520, the cleaning and drying area 540, and the processing area 530. However, an area accommodating a chemical mechanical polishing unit may be disposed in or adjacent to the processing area 530, and the cleaning and 20 drying area 540 may be disposed in the processing area 530 or between the area accommodating the chemical mechanical polishing unit and the loading/unloading area 520. Any of various other suitable area and unit layouts 25 may be employed insofar as a dry semiconductor substrate can be loaded into the substrate plating apparatus, and a plated semiconductor substrate can be cleaned and dried, and thereafter unloaded from the substrate plating apparatus.

In the embodiment described above, the present 30 invention is applied to the substrate plating apparatus for plating a semiconductor substrate. However, the principles of the present invention are also applicable to a substrate plating apparatus for plating a substrate

other than a semiconductor substrate. Furthermore, a region on a substrate plated by the substrate plating apparatus is not limited to an interconnection region on the substrate. The substrate plating apparatus may be 5 used to plate substrates with a metal other than copper.

FIG. 22 is a plan view of another example of a substrate plating apparatus. The substrate plating apparatus shown in FIG. 22 comprises a loading unit 601 for loading a semiconductor substrate, a copper plating 10 chamber 602 for plating a semiconductor substrate with copper, a pair of water cleaning chambers 603, 604 for cleaning a semiconductor substrate with water, a chemical mechanical polishing unit 605 for chemically and mechanically polishing a semiconductor substrate, a pair 15 of water cleaning chambers 606, 607 for cleaning a semiconductor substrate with water, a drying chamber 608 for drying a semiconductor substrate, and an unloading unit 609 for unloading a semiconductor substrate with an interconnection film thereon. The substrate plating 20 apparatus also has a substrate transfer mechanism (not shown) for transferring semiconductor substrates to the chambers 602, 603, 604, the chemical mechanical polishing unit 605, the chambers 606, 607, 608, and the unloading unit 609. The loading unit 601, the chambers 602, 603, 25 604, the chemical mechanical polishing unit 605, the chambers 606, 607, 608, and the unloading unit 609 are combined into a single unitary arrangement as apparatus.

The substrate plating apparatus operates as follows: The substrate transfer mechanism transfers a 30 semiconductor substrate W on which an interconnection film has not yet been formed from a substrate cassette 601-1 placed in the loading unit 601 to the copper plating chamber 602. In the copper plating chamber 602,

a plated copper film is formed on a surface of the semiconductor substrate W having an interconnection region composed of an interconnection trench and an interconnection hole (contact hole).

5 After the plated copper film is formed on the semiconductor substrate W in the copper plating chamber 602, the semiconductor substrate W is transferred to one of the water cleaning chambers 603, 604 by the substrate transfer mechanism and cleaned by water in one of the
10 water cleaning chambers 603, 604. The cleaned semiconductor substrate W is transferred to the chemical mechanical polishing unit 605 by the substrate transfer mechanism. The chemical mechanical polishing unit 605 removes the unwanted plated copper film from the surface
15 of the semiconductor substrate W, leaving a portion of the plated copper film in the interconnection trench and the interconnection hole. A barrier layer made of TiN or the like is formed on the surface of the semiconductor substrate W, including the inner surfaces of the
20 interconnection trench and the interconnection hole, before the plated copper film is deposited.

Then, the semiconductor substrate W with the remaining plated copper film is transferred to one of the water cleaning chambers 606, 607 by the substrate transfer mechanism and cleaned by water in one of the water cleaning chambers 607, 608. The cleaned semiconductor substrate W is then dried in the drying chamber 608, after which the dried semiconductor substrate W with the remaining plated copper film serving
25 as an interconnection film is placed into a substrate cassette 609-1 in the unloading unit 609.

FIG. 23 shows a plan view of still another example of a substrate plating apparatus. The substrate

plating apparatus shown in FIG. 23 differs from the substrate plating apparatus shown in FIG. 22 in that it additionally includes a copper plating chamber 602, a water cleaning chamber 610, a pretreatment chamber 611, a protective layer plating chamber 612 for forming a protective plated layer on a plated copper film on a semiconductor substrate, water cleaning chamber 613, 614, and a chemical mechanical polishing unit 615. The loading unit 601, the chambers 602, 603, 604, 614, the chemical mechanical polishing unit 605, 615, the chambers 606, 607, 608, 610, 611, 612, 613, and the unloading unit 609 are combined into a single unitary arrangement as an apparatus.

The substrate plating apparatus shown in FIG. 23 operates as follows: A semiconductor substrate W is supplied from the substrate cassette 601-1 placed in the loading unit 601 successively to one of the copper plating chambers 602, 602. In one of the copper plating chamber 602, 602, a plated copper film is formed on a surface of a semiconductor substrate W having an interconnection region composed of an interconnection trench and an interconnection hole (contact hole). The two copper plating chambers 602, 602 are employed to allow the semiconductor substrate W to be plated with a copper film for a long period of time. Specifically, the semiconductor substrate W may be plated with a primary copper film according to electroless plating in one of the copper plating chamber 602, and then plated with a secondary copper film according to electroplating in the other copper plating chamber 602. The substrate plating apparatus may have more than two copper plating chambers.

The semiconductor substrate W with the plated copper film formed thereon is cleaned by water in one of

the water cleaning chambers 603, 604. Then, the chemical mechanical polishing unit 605 removes the unwanted portion of the plated copper film from the surface of the semiconductor substrate W, leaving a portion of the 5 plated copper film in the interconnection trench and the interconnection hole.

Thereafter, the semiconductor substrate W with the remaining plated copper film is transferred to the water cleaning chamber 610, in which the semiconductor 10 substrate W is cleaned with water. Then, the semiconductor substrate W is transferred to the pretreatment chamber 611, and pretreated therein for the deposition of a protective plated layer. The pretreated semiconductor substrate W is transferred to the 15 protective layer-plating chamber 612. In the protective layer plating chamber 612, a protective plated layer is formed on the plated copper film in the interconnection region on the semiconductor substrate W. For example, the protective plated layer is formed with an alloy of 20 nickel (Ni) and boron (B) by electroless plating.

After semiconductor substrate is cleaned in one of the water cleaning chamber 613, 614, an upper portion of the protective plated layer deposited on the plated copper film is polished off to planarize the protective 25 plated layer, in the chemical mechanical polishing unit 615.

After the protective plated layer is polished, the semiconductor substrate W is cleaned by water in one of the water cleaning chambers 606, 607, dried in the 30 drying chamber 608, and then transferred to the substrate cassette 609-1 in the unloading unit 609.

FIG. 24 is a plan view of still another example of a substrate plating apparatus. As shown in FIG. 24,

the substrate plating apparatus includes a robot 616 at its center which has a robot arm 616-1, and also has a copper plating chamber 602, a pair of water cleaning chambers 603, 604, a chemical mechanical polishing unit 605, a pretreatment chamber 611, a protective layer plating chamber 612, a drying chamber 608, and a loading/unloading station 617 which are disposed around the robot 616 and positioned within the reach of the robot arm 616-1. A loading unit 601 for loading 10 semiconductor substrates and an unloading unit 609 for unloading semiconductor substrates is disposed adjacent to the loading/unloading station 617. The robot 616, the chambers 602, 603, 604, the chemical mechanical polishing unit 605, the chambers 608, 611, 612, the 15 loading/unloading station 617, the loading unit 601, and the unloading unit 609 are combined into a single unitary arrangement as an apparatus.

The substrate plating apparatus shown in FIG. 24 operates as follows:

20 A semiconductor substrate to be plated is transferred from the loading unit 601 to the loading/unloading station 617, from which the semiconductor substrate is received by the robot arm 616-1 and transferred thereby to the copper plating chamber 25 602. In the copper plating chamber 602, a plated copper film is formed on a surface of the semiconductor substrate which has an interconnection region composed of an interconnection trench and an interconnection hole. The semiconductor substrate with the plated copper film 30 formed thereon is transferred by the robot arm 616-1 to the chemical mechanical polishing unit 605. In the chemical mechanical polishing unit 605, the plated copper film is removed from the surface of the semiconductor

substrate W, leaving a portion of the plated copper film in the interconnection trench and the interconnection hole.

The semiconductor substrate is then transferred 5 by the robot arm 616-1 to the water-cleaning chamber 604, in which the semiconductor substrate is cleaned by water. Thereafter, the semiconductor substrate is transferred by the robot arm 616-1 to the pretreatment chamber 611, in which the semiconductor substrate is pretreated therein 10 for the deposition of a protective plated layer. The pretreated semiconductor substrate is transferred by the robot arm 616-1 to the protective layer plating chamber 612. In the protective layer plating chamber 612, a protective plated layer is formed on the plated copper 15 film in the interconnection region on the semiconductor substrate W. The semiconductor substrate with the protective plated layer formed thereon is transferred by the robot arm 616-1 to the water cleaning chamber 604, in which the semiconductor substrate is cleaned by water. 20 The cleaned semiconductor substrate is transferred by the robot arm 616-1 to the drying chamber 608, in which the semiconductor substrate is dried. The dried semiconductor substrate is transferred by the robot arm 616-1 to the loading/unloading station 617, from which 25 the plated semiconductor substrate is transferred to the unloading unit 609.

FIG. 25 is a view showing the plan constitution of another example of a semiconductor substrate processing apparatus. The semiconductor substrate processing apparatus is of a constitution in which there 30 are provided a loading/unloading section 701, a plated Cu film forming unit 702, a first robot 703, a third cleaning machine 704, a reversing machine 705, a

reversing machine 706, a second cleaning machine 707, a second robot 708, a first cleaning machine 709, a first polishing apparatus 710, and a second polishing apparatus 711. A before-plating and after-plating film thickness 5 measuring instrument 712 for measuring the film thicknesses before and after plating, and a dry state film thickness measuring instrument 713 for measuring the film thickness of a semiconductor substrate W in a dry state after polishing are placed near the first robot 10 703.

The first polishing apparatus (polishing unit) 710 has a polishing table 710-1, a top ring 710-2, a top ring head 710-3, a film thickness measuring instrument 710-4, and a pusher 710-5. The second polishing 15 apparatus (polishing unit) 711 has a polishing table 711-1, a top ring 711-2, a top ring head 711-3, a film thickness measuring instrument 711-4, and a pusher 711-5.

A cassette 701-1 accommodating the semiconductor substrates W, in which a via hole and a trench for interconnect are formed, and a seed layer is 20 formed thereon is placed on a loading port of the loading/unloading section 701. The first robot 703 takes out the semiconductor substrate W from the cassette 701-1, and carries the semiconductor substrate W into the plated Cu film forming unit 702 where a plated Cu film is 25 formed. At this time, the film thickness of the seed layer is measured with the before-plating and after-plating film thickness measuring instrument 712. The plated Cu film is formed by carrying out hydrophilic treatment of the face of the semiconductor substrate W, and then Cu plating. After formation of the plated Cu 30 film, rinsing or cleaning of the semiconductor substrate W is carried out in the plated Cu film forming unit 702.

When the semiconductor substrate W is taken out from the plated Cu film forming unit 702 by the first robot 703, the film thickness of the plated Cu film is measured with the before-plating and after-plating film thickness measuring instrument 712. The results of its measurement are recorded into a recording device (not shown) as record data on the semiconductor substrate, and are used for judgment of an abnormality of the plated Cu film forming unit 702. After measurement of the film thickness, the first robot 703 transfers the semiconductor substrate W to the reversing machine 705, and the reversing machine 705 reverses the semiconductor substrate W (the surface on which the plated Cu film has been formed faces downward). The first polishing apparatus 710 and the second polishing apparatus 711 perform polishing in a serial mode and a parallel mode. Next, polishing in the serial mode will be described.

In the serial mode polishing, a primary polishing is performed by the polishing apparatus 710, and a secondary polishing is performed by the polishing apparatus 711. The second robot 708 picks up the semiconductor substrate W on the reversing machine 705, and places the semiconductor substrate W on the pusher 710-5 of the polishing apparatus 710. The top ring 710-2 attracts the semiconductor substrate W on the pusher 710-5 by suction, and brings the surface of the plated Cu film of the semiconductor substrate W into contact with a polishing surface of the polishing table 710-1 under pressure to perform a primary polishing. With the primary polishing, the plated Cu film is basically polished. The polishing surface of the polishing table 710-1 is composed of foamed polyurethane such as IC1000, or a material having abrasive grains fixed thereto or

impregnated therein. Upon relative movements of the polishing surface and the semiconductor substrate W, the plated Cu film is polished.

After completion of polishing of the plated Cu film, the semiconductor substrate W is returned onto the pusher 710-5 by the top ring 710-2. The second robot 708 picks up the semiconductor substrate W, and introduces it into the first cleaning machine 709. At this time, a chemical liquid may be ejected toward the face and backside of the semiconductor substrate W on the pusher 710-5 to remove particles therefrom or cause particles to be difficult to adhere thereto.

After completion of cleaning in the first cleaning machine 709, the second robot 708 picks up the semiconductor substrate W, and places the semiconductor substrate W on the pusher 711-5 of the second polishing apparatus 711. The top ring 711-2 attracts the semiconductor substrate W on the pusher 711-5 by suction, and brings the surface of the semiconductor substrate W, which has the barrier layer formed thereon, into contact with a polishing surface of the polishing table 711-1 under pressure to perform the secondary polishing. The constitution of the polishing table is the same as the top ring 711-2. With this secondary polishing, the barrier layer is polished. However, there may be a case in which a Cu film and an oxide film left after the primary polishing are also polished.

A polishing surface of the polishing table 711-1 is composed of foamed polyurethane such as IC1000, or a material having abrasive grains fixed thereto or impregnated therein. Upon relative movements of the polishing surface and the semiconductor substrate W, polishing is carried out. At this time, silica, alumina,

ceria, on the like is used as abrasive grains or a slurry. A chemical liquid is adjusted depending on the type of the film to be polished.

Detection of an end point of the secondary 5 polishing is performed by measuring the film thickness of the barrier layer mainly with the use of the optical film thickness measuring instrument, and detecting the film thickness which has become zero, or the surface of an insulating film comprising SiO_2 shows up. Furthermore, a 10 film thickness measuring instrument with an image processing function is used as the film thickness measuring instrument 711-4 provided near the polishing table 711-1. By use of this measuring instrument, measurement of the oxide film is made, the results are 15 stored as processing records of the semiconductor substrate W, and used for judging whether the semiconductor substrate W in which secondary polishing has been finished can be transferred to a subsequent step or not. If the end point of the secondary polishing is 20 not reached, repolishing is performed. If over-polishing has been performed beyond a prescribed value due to any abnormality, then the semiconductor substrate processing apparatus is stopped to avoid next polishing so that defective products will not increase.

25 After completion of the secondary polishing, the semiconductor substrate W is moved to the pusher 711-5 by the top ring 711-2. The second robot 708 picks up the semiconductor substrate W on the pusher 711-5. At this time, a chemical liquid may be ejected toward the 30 face and backside of the semiconductor substrate W on the pusher 711-5 to remove particles therefrom or cause particles to be difficult to adhere thereto.

The second robot 708 carries the semiconductor

substrate W into the second cleaning machine 707 where cleaning of the semiconductor substrate W is performed. The constitution of the second cleaning machine 707 is also the same as the constitution of the first cleaning 5 machine 709. The face of the semiconductor substrate W is scrubbed with the PVA sponge rolls using a cleaning liquid comprising pure water to which a surface active agent, a chelating agent, or a pH regulating agent is added. A strong chemical liquid such as DHF is ejected 10 from a nozzle toward the backside of the semiconductor substrate W to perform etching of the diffused Cu thereon. If there is no problem of diffusion, scrubbing cleaning is performed with the PVA sponge rolls using the same chemical liquid as that used for the face.

15 After completion of the above cleaning, the second robot 708 picks up the semiconductor substrate W and transfers it to the reversing machine 706, and the reversing machine 706 reverses the semiconductor substrate W. The semiconductor substrate W which has 20 been reversed is picked up by the first robot 703, and transferred to the third cleaning machine 704. In the third cleaning machine 704, megasonic water excited by ultrasonic vibrations is ejected toward the face of the semiconductor substrate W to clean the semiconductor 25 substrate W. At this time, the face of the semiconductor substrate W may be cleaned with a known pencil type sponge using a cleaning liquid comprising pure water to which a surface active agent, a chelating agent, or a pH regulating agent is added. Thereafter, the semiconductor 30 substrate W is dried by spin-drying.

As described above, if the film thickness has been measured with the film thickness measuring instrument 711-4 provided near the polishing table 711-1,

then the semiconductor substrate W is not subjected to further process and is accommodated into the cassette placed on the unloading port of the loading/unloading section 771.

5 FIG. 26 is a view showing the plan constitution of another example of a semiconductor substrate processing apparatus. The substrate processing apparatus differs from the substrate processing apparatus shown in FIG. 25 in that a cap plating unit 750 is provided 10 instead of the plated Cu film forming unit 702 in FIG. 25.

A cassette 701-1 accommodating the semiconductor substrates W formed plated Cu film is placed on a load port of a loading/unloading section 701. 15 The semiconductor substrate W taken out from the cassette 701-1 is transferred to the first polishing apparatus 710 or second polishing apparatus 711 in which the surface of the plated Cu film is polished. After completion of polishing of the plated Cu film, the semiconductor 20 substrate W is cleaned in the first cleaning machine 709.

After completion of cleaning in the first cleaning machine 709, the semiconductor substrate W is transferred to the cap plating unit 750 where cap plating is applied onto the surface of the plated Cu film with 25 the aim of preventing oxidation of plated Cu film due to the atmosphere. The semiconductor substrate to which cap plating has been applied is carried by the second robot 708 from the cap plating unit 750 to the second cleaning unit 707 where it is cleaned with pure water or deionized 30 water. The semiconductor substrate after completion of cleaning is returned into the cassette 701-1 placed on the loading/unloading section 701.

FIG. 27 is a view showing the plan constitution

of still another example of a semiconductor substrate processing apparatus. The substrate processing apparatus differs from the substrate processing apparatus shown in FIG. 26 in that an annealing unit 751 is provided instead 5 of the third cleaning machine 709 in FIG. 26.

The semiconductor substrate W, which is polished in the polishing unit 710 or 711, and cleaned in the first cleaning machine 709 described above, is transferred to the cap plating unit 750 where cap plating 10 is applied onto the surface of the plated Cu film. The semiconductor substrate to which cap plating has been applied is carried by the second robot 732 from the cap plating unit 750 to the first cleaning unit 707 where it is cleaned.

15 After completion of cleaning in the first cleaning machine 709, the semiconductor substrate W is transferred to the annealing unit 751 in which the substrate is annealed, whereby the plated Cu film is alloyed so as to increase the electromigration resistance 20 of the plated Cu film. The semiconductor substrate W to which annealing treatment has been applied is carried from the annealing unit 751 to the second cleaning unit 707 where it is cleaned with pure water or deionized water. The semiconductor substrate W after completion of 25 cleaning is returned into the cassette 701-1 placed on the loading/unloading section 701.

FIG. 28 is a view showing a plan layout constitution of another example of the substrate processing apparatus. In FIG. 28, portions denoted by 30 the same reference numerals as those in FIG. 25 show the same or corresponding portions. In the substrate processing apparatus, a pusher indexer 725 is disposed close to a first polishing apparatus 710 and a second

polishing apparatus 711. Substrate placing tables 721, 722 are disposed close to a third cleaning machine 704 and a plated Cu film forming unit 702, respectively. A robot 23 is disposed close to a first cleaning machine 5 709 and the third cleaning machine 704. Further, a robot 724 is disposed close to a second cleaning machine 707 and the plated Cu film forming unit 702, and a dry state film thickness measuring instrument 713 is disposed close to a loading/unloading section 701 and a first robot 703.

10 In the substrate processing apparatus of the above constitution, the first robot 703 takes out a semiconductor substrate W from a cassette 701-1 placed on the load port of the loading/unloading section 701. After the film thicknesses of a barrier layer and a seed 15 layer are measured with the dry state film thickness measuring instrument 713, the first robot 703 places the semiconductor substrate W on the substrate placing table 721. In the case where the dry state film thickness measuring instrument 713 is provided on the hand of the first robot 703, the film thicknesses are measured 20 thereon, and the substrate is placed on the substrate placing table 721. The second robot 723 transfers the semiconductor substrate W on the substrate placing table 721 to the plated Cu film forming unit 702 in which a 25 plated Cu film is formed. After formation of the plated Cu film, the film thickness of the plated Cu film is measured with a before-plating and after-plating film thickness measuring instrument 712. Then, the second robot 723 transfers the semiconductor substrate W to the 30 pusher indexer 725 and loads it thereon.

[Serial mode]

In the serial mode, a top ring head 710-2 holds the semiconductor substrate W on the pusher indexer 725

by suction, transfers it to a polishing table 710-1, and presses the semiconductor substrate W against a polishing surface on the polishing table 710-1 to perform polishing. Detection of the end point of polishing is 5 performed by the same method as described above. The semiconductor substrate W after completion of polishing is transferred to the pusher indexer 725 by the top ring head 710-2, and loaded thereon. The second robot 723 takes out the semiconductor substrate W, and carries it 10 into the first cleaning machine 709 for cleaning. Then, the semiconductor substrate W is transferred to the pusher indexer 725, and loaded thereon.

A top ring head 711-2 holds the semiconductor substrate W on the pusher indexer 725 by suction, 15 transfers it to a polishing table 711-1, and presses the semiconductor substrate W against a polishing surface on the polishing table 711-1 to perform polishing. Detection of the end point of polishing is performed by the same method as described above. The semiconductor 20 substrate W after completion of polishing is transferred to the pusher indexer 725 by the top ring head 711-2, and loaded thereon. The third robot 724 picks up the semiconductor substrate W, and its film thickness is measured with a film thickness measuring instrument 726. 25 Then, the semiconductor substrate W is carried into the second cleaning machine 707 for cleaning. Thereafter, the semiconductor substrate W is carried into the third cleaning machine 704, where it is cleaned and then dried by spin-drying. Then, the semiconductor substrate W is 30 picked up by the third robot 724, and placed on the substrate placing table 722.

[Parallel mode]

In the parallel mode, the top ring head 710-2

or 711-2 holds the semiconductor substrate W on the pusher indexer 725 by suction, transfers it to the polishing table 710-1 or 711-1, and presses the semiconductor substrate W against the polishing surface 5 on the polishing table 710-1 or 711-1 to perform polishing. After measurement of the film thickness, the third robot 724 picks up the semiconductor substrate W, and places it on the substrate placing table 722.

The first robot 703 transfers the semiconductor 10 substrate W on the substrate placing table 722 to the dry state film thickness measuring instrument 713. After the film thickness is measured, the semiconductor substrate W is returned to the cassette 701-1 of the loading/unloading section 701.

15 FIG. 29 is a view showing another plan layout constitution of the substrate processing apparatus. The substrate processing apparatus is such a substrate processing apparatus which forms a seed layer and a plated Cu film on a semiconductor substrate W having no seed layer formed thereon, and polishes these films to 20 form interconnects.

In the substrate polishing apparatus, a pusher indexer 725 is disposed close to a first polishing apparatus 710 and a second polishing apparatus 711, 25 substrate placing tables 721, 722 are disposed close to a second cleaning machine 707 and a seed layer forming unit 727, respectively, and a robot 723 is disposed close to the seed layer forming unit 727 and a plated Cu film forming unit 702. Further, a robot 724 is disposed close 30 to a first cleaning machine 709 and the second cleaning machine 707, and a dry state film thickness measuring instrument 713 is disposed close to a loading/unloading section 701 and a first robot 702.

The first robot 703 takes out a semiconductor substrate W having a barrier layer thereon from a cassette 701-1 placed on the load port of the loading/unloading section 701, and places it on the 5 substrate placing table 721. Then, the second robot 723 transports the semiconductor substrate W to the seed layer forming unit 727 where a seed layer is formed. The seed layer is formed by electroless plating. The second robot 723 enables the semiconductor substrate having the 10 seed layer formed thereon to be measured in thickness of the seed layer by the before-plating and after-plating film thickness measuring instrument 712. After measurement of the film thickness, the semiconductor substrate is carried into the plated Cu film forming unit 15 702 where a plated Cu film is formed.

After formation of the plated Cu film, its film thickness is measured, and the semiconductor substrate is transferred to a pusher indexer 725. A top ring 710-2 or 711-2 holds the semiconductor substrate W on the pusher 20 indexer 725 by suction, and transfers it to a polishing table 710-1 or 711-1 to perform polishing. After polishing, the top ring 710-2 or 711-2 transfers the semiconductor substrate W to a film thickness measuring instrument 710-4 or 711-4 to measure the film thickness. 25 Then, the top ring 710-2 or 711-2 transfers the semiconductor substrate W to the pusher indexer 725, and places it thereon.

Then, the third robot 724 picks up the semiconductor substrate W from the pusher indexer 725, 30 and carries it into the first cleaning machine 709. The third robot 724 picks up the cleaned semiconductor substrate W from the first cleaning machine 709, carries it into the second cleaning machine 707, and places the

cleaned and dried semiconductor substrate on the substrate placing table 722. Then, the first robot 703 picks up the semiconductor substrate W, and transfers it to the dry state film thickness measuring instrument 713 in which the film thickness is measured, and the first robot 703 carries it into the cassette 701-1 placed on the unload port of the loading/unloading section 701.

In the substrate processing apparatus shown in FIG. 29, interconnects are formed by forming a barrier layer, a seed layer and a plated Cu film on a semiconductor substrate W having a via hole or a trench of a circuit pattern formed therein, and polishing them.

The cassette 701-1 accommodating the semiconductor substrates W before formation of the barrier layer is placed on the load port of the loading/unloading section 701. The first robot 703 takes out the semiconductor substrate W from the cassette 701-1 placed on the load port of the loading/unloading section 701, and places it on the substrate placing table 721. Then, the second robot 723 transports the semiconductor substrate W to the seed layer forming unit 727 where a barrier layer and a seed layer are formed. The barrier layer and the seed layer are formed by electroless plating. The second robot 723 brings the semiconductor substrate W having the barrier layer and the seed layer formed thereon to the before-plating and after-plating film thickness measuring instrument 712 which measures the film thicknesses of the barrier layer and the seed layer. After measurement of the film thicknesses, the semiconductor substrate W is carried into the plated Cu film forming unit 702 where a plated Cu film is formed.

FIG. 30 is a view showing plan layout constitution of another example of the substrate

processing apparatus. In the substrate processing apparatus, there are provided a barrier layer forming unit 811, a seed layer forming unit 812, a plated film forming unit 813, an annealing unit 814, a first cleaning unit 815, a bevel and backside cleaning unit 816, a cap plating unit 817, a second cleaning unit 818, a first aligner and film thickness measuring instrument 841, a second aligner and film thickness measuring instrument 842, a first substrate reversing machine 843, a second substrate reversing machine 844, a substrate temporary placing table 845, a third film thickness measuring instrument 846, a loading/unloading section 820, a first polishing apparatus 821, a second polishing apparatus 822, a first robot 831, a second robot 832, a third robot 833, and a fourth robot 834. The film thickness measuring instruments 841, 842, and 846 are units, have the same size as the frontage dimension of other units (plating, cleaning, annealing units, and the like), and are thus interchangeable.

In this example, an electroless Ru plating apparatus can be used as the barrier layer forming unit 811, an electroless Cu plating apparatus as the seed layer forming unit 812, and an electroplating apparatus as the plated film forming unit 813.

FIG. 31 is a flow chart showing the flow of the respective steps in the present substrate processing apparatus. The respective steps in the apparatus will be described according to this flow chart. First, a semiconductor substrate taken out by the first robot 831 from a cassette 820a placed on the load and unload unit 820 is placed in the first aligner and film thickness measuring unit 841, in such a state that its surface, to be plated, faces upward. In order to set a reference

point for a position at which film thickness measurement is made, notch alignment for film thickness measurement is performed, and then film thickness data on the semiconductor substrate before formation of a Cu film are 5 obtained.

Then, the semiconductor substrate is transported to the barrier layer forming unit 811 by the first robot 831. The barrier layer forming unit 811 is such an apparatus for forming a barrier layer on the 10 semiconductor substrate by electroless Ru plating, and the barrier layer forming unit 811 forms an Ru film as a film for preventing Cu from diffusing into an interlayer insulator film (e.g. SiO_2) of a semiconductor device. The semiconductor substrate discharged after cleaning and 15 drying steps is transported by the first robot 831 to the first aligner and film thickness measuring unit 841, where the film thickness of the semiconductor substrate, i.e., the film thickness of the barrier layer is measured.

20 The semiconductor substrate after film thickness measurement is carried into the seed layer forming unit 812 by the second robot 832, and a seed layer is formed on the barrier layer by electroless Cu plating. The semiconductor substrate discharged after 25 cleaning and drying steps is transported by the second robot 832 to the second aligner and film thickness measuring instrument 842 for determination of a notch position, before the semiconductor substrate is transported to the plated film forming unit 813, which is 30 an impregnation plating unit, and then notch alignment for Cu plating is performed by the film thickness measuring instrument 842. If necessary, the film thickness of the semiconductor substrate before formation

of a Cu film may be measured again in the film thickness measuring instrument 842.

The semiconductor substrate which has completed notch alignment is transported by the third robot 833 to the plated film forming unit 813 where Cu plating is applied to the semiconductor substrate. The semiconductor substrate discharged after cleaning and drying steps is transported by the third robot 833 to the bevel and backside cleaning unit 816 where an unnecessary Cu film (seed layer) at a peripheral portion of the semiconductor substrate is removed. In the bevel and backside cleaning unit 816, the bevel is etched in a preset time, and Cu adhering to the backside of the semiconductor substrate is cleaned with a chemical liquid such as hydrofluoric acid. At this time, before transporting the semiconductor substrate to the bevel and backside cleaning unit 816, film thickness measurement of the semiconductor substrate may be made by the second aligner and film thickness measuring instrument 842 to obtain the thickness value of the Cu film formed by plating, and based on the obtained results, the bevel etching time may be changed arbitrarily to carry out etching. The region etched by bevel etching is a region which corresponds to a peripheral edge portion of the substrate and has no circuit formed therein, or a region which is not utilized finally as a chip although a circuit is formed. A bevel portion is included in this region.

The semiconductor substrate discharged after cleaning and drying steps in the bevel and backside cleaning unit 816 is transported by the third robot 833 to the substrate reversing machine 843. After the semiconductor substrate is turned over by the substrate

reversing machine 843 to cause the plated surface to be directed downward, the semiconductor substrate is introduced into the annealing unit 814 by the fourth robot 834 for thereby stabilizing a interconnection portion. Before and/or after annealing treatment, the semiconductor substrate is carried into the second aligner and film thickness measuring unit 842 where the film thickness of a copper film formed on the semiconductor substrate is measured. Then, the semiconductor substrate is carried by the fourth robot 834 into the first polishing apparatus 821 in which the Cu film and the seed layer of the semiconductor substrate are polished.

At this time, desired abrasive grains or the like are used, but fixed abrasive may be used in order to prevent dishing and enhance flatness of the face. After completion of primary polishing, the semiconductor substrate is transported by the fourth robot 834 to the first cleaning unit 815 where it is cleaned. This cleaning is scrub-cleaning in which rolls having substantially the same length as the diameter of the semiconductor substrate are placed on the face and the backside of the semiconductor substrate, and the semiconductor substrate and the rolls are rotated, while pure water or deionized water is flowed, thereby performing cleaning of the semiconductor substrate.

After completion of the primary cleaning, the semiconductor substrate is transported by the fourth robot 834 to the second polishing apparatus 822 where the barrier layer on the semiconductor substrate is polished. At this time, desired abrasive grains or the like are used, but fixed abrasive may be used in order to prevent dishing and enhance flatness of the face. After

completion of secondary polishing, the semiconductor substrate is transported by the fourth robot 834 again to the first cleaning unit 815 where scrub-cleaning is performed. After completion of cleaning, the 5 semiconductor substrate is transported by the fourth robot 834 to the second substrate reversing machine 844 where the semiconductor substrate is reversed to cause the plated surface to be directed upward, and then the semiconductor substrate is placed on the substrate 10 temporary placing table 845 by the third robot.

The semiconductor substrate is transported by the second robot 832 from the substrate temporary placing table 845 to the cap plating unit 817 where cap plating is applied onto the Cu surface with the aim of preventing 15 oxidation of Cu due to the atmosphere. The semiconductor substrate to which cap plating has been applied is carried by the second robot 832 from the cover plating unit 817 to the third film thickness measuring instrument 146 where the thickness of the copper film is measured. 20 Thereafter, the semiconductor substrate is carried by the first robot 831 into the second cleaning unit 818 where it is cleaned with pure water or deionized water. The semiconductor substrate after completion of cleaning is returned into the cassette 820a placed on the 25 loading/unloading section 820.

The aligner and film thickness measuring instrument 841 and the aligner and film thickness measuring instrument 842 perform positioning of the notch portion of the substrate and measurement of the film 30 thickness.

The seed layer forming unit 182 may be omitted. In this case, a plated film may be formed on a barrier layer directly in a plated film forming unit 817.

The bevel and backside cleaning unit 816 can perform an edge (bevel) Cu etching and a backside cleaning at the same time, and can suppress growth of a natural oxide film of copper at the circuit formation portion on the surface of the substrate. FIG. 32 shows a schematic view of the bevel and backside cleaning unit 816. As shown in FIG. 32, the bevel and backside cleaning unit 816 has a substrate holding portion 922 positioned inside a bottomed cylindrical waterproof cover 920 and adapted to rotate a substrate W at a high speed, in such a state that the face of the substrate W faces upwardly, while holding the substrate W horizontally by spin chucks 921 at a plurality of locations along a circumferential direction of a peripheral edge portion of the substrate; a center nozzle 924 placed above a nearly central portion of the face of the substrate W held by the substrate holding portion 922; and an edge nozzle 926 placed above the peripheral edge portion of the substrate W. The center nozzle 924 and the edge nozzle 926 are directed downward. A back nozzle 928 is positioned below a nearly central portion of the backside of the substrate W, and directed upward. The edge nozzle 926 is adapted to be movable in a diametrical direction and a height direction of the substrate W.

The width of movement L of the edge nozzle 926 is set such that the edge nozzle 926 can be arbitrarily positioned in a direction toward the center from the outer peripheral end surface of the substrate, and a set value for L is inputted according to the size, usage, or the like of the substrate W. Normally, an edge cut width C is set in the range of 2 mm to 5 mm. In the case where a rotational speed of the substrate is a certain value or higher at which the amount of liquid migration from the

backside to the face is not problematic, the copper film within the edge cut width C can be removed.

Next, the method of cleaning with this cleaning apparatus will be described. First, the semiconductor substrate W is horizontally rotated integrally with the substrate holding portion 922, with the substrate being held horizontally by the spin chucks 921 of the substrate holding portion 922. In this state, an acid solution is supplied from the center nozzle 924 to the central portion of the face of the substrate W. The acid solution may be a non-oxidizing acid, and hydrofluoric acid, hydrochloric acid, sulfuric acid, citric acid, oxalic acid, or the like is used. On the other hand, an oxidizing agent solution is supplied continuously or intermittently from the edge nozzle 926 to the peripheral edge portion of the substrate W. As the oxidizing agent solution, one of an aqueous solution of ozone, an aqueous solution of hydrogen peroxide, an aqueous solution of nitric acid, and an aqueous solution of sodium 20 hypochlorite is used, or a combination of these is used.

In this manner, the copper film, or the like formed on the upper surface and end surface in the region of the peripheral edge portion C of the semiconductor substrate W is rapidly oxidized with the oxidizing agent solution, and is simultaneously etched with the acid solution supplied from the center nozzle 924 and spread on the entire face of the substrate, whereby it is dissolved and removed. By mixing the acid solution and the oxidizing agent solution at the peripheral edge portion of the substrate, a steep etching profile can be obtained, in comparison with a mixture of them which is produced in advance being supplied. At this time, the copper etching rate is determined by their

concentrations. If a natural oxide film of copper is formed in the circuit-formed portion on the face of the substrate, this natural oxide is immediately removed by the acid solution spreading on the entire face of the 5 substrate according to rotation of the substrate, and does not grow any more. After the supply of the acid solution from the center nozzle 924 is stopped, the supply of the oxidizing agent solution from the edge nozzle 926 is stopped. As a result, silicon exposed on 10 the surface is oxidized, and deposition of copper can be suppressed.

On the other hand, an oxidizing agent solution and a silicon oxide film etching agent are supplied simultaneously or alternately from the back nozzle 928 to 15 the central portion of the backside of the substrate. Therefore, copper or the like adhering in a metal form to the backside of the semiconductor substrate W can be oxidized with the oxidizing agent solution, together with silicon of the substrate, and can be etched and removed 20 with the silicon oxide film etching agent. This oxidizing agent solution is preferably the same as the oxidizing agent solution supplied to the face, because the types of chemicals are decreased in number. Hydrofluoric acid can be used as the silicon oxide film 25 etching agent, and if hydrofluoric acid is used as the acid solution on the face of the substrate, the types of chemicals can be decreased in number. Thus, if the supply of the oxidizing agent is stopped first, a hydrophobic surface is obtained. If the etching agent 30 solution is stopped first, a water-saturated surface (a hydrophilic surface) is obtained, and thus the backside surface can be adjusted to a condition which will satisfy the requirements of a subsequent process.

In this manner, the acid solution, i.e., etching solution is supplied to the substrate to remove metal ions remaining on the surface of the substrate W. Then, pure water is supplied to replace the etching 5 solution with pure water and remove the etching solution, and then the substrate is dried by spin-drying. In this way, removal of the copper film in the edge cut width C at the peripheral edge portion on the face of the semiconductor substrate, and removal of copper 10 contaminants on the backside are performed simultaneously to thus allow this treatment to be completed, for example, within 80 seconds. The etching cut width of the edge can be set arbitrarily (to 2 mm to 5 mm), but the time required for etching does not depend on the cut 15 width.

Annealing treatment performed before the CMP process and after plating has a favorable effect on the subsequent CMP treatment and on the electrical characteristics of interconnection. Observation of the 20 surface of broad interconnection (unit of several micrometers) after the CMP treatment without annealing showed many defects such as microvoids, which resulted in an increase in the electrical resistance of the entire interconnection. Execution of annealing ameliorated the 25 increase in the electrical resistance. In the absence of annealing, thin interconnection showed no voids. Thus, the degree of grain growth is presumed to be involved in these phenomena. That is, the following mechanism can be speculated: Grain growth is difficult to occur in thin 30 interconnection. In broad interconnection, on the other hand, grain growth proceeds in accordance with annealing treatment. During the process of grain growth, ultrafine pores in the plated film, which are too small to be seen

by the SEM (scanning electron microscope), gather and move upward, thus forming microvoid-like depressions in the upper part of the interconnection. The annealing conditions in the annealing unit 814 are such that 5 hydrogen (2% or less) is added in a gas atmosphere, the temperature is in the range of 300°C to 400°C, and the time is in the range of 1 to 5 minutes. Under these conditions, the above effects were obtained.

FIGS. 35 and 36 show the annealing unit 814. 10 The annealing unit 814 comprises a chamber 1002 having a gate 1000 for taking in and taking out the semiconductor substrate W, a hot plate 1004 disposed at an upper position in the chamber 1002 for heating the semiconductor substrate W to e.g. 400°C, and a cool plate 15 1006 disposed at a lower position in the chamber 1002 for cooling the semiconductor substrate W by, for example, flowing a cooling water inside the plate. The annealing unit 1002 also has a plurality of vertically movable elevating pins 1008 penetrating the cool plate 1006 and 20 extending upward and downward therethrough for placing and holding the semiconductor substrate W on them. The annealing unit further includes a gas introduction pipe 1010 for introducing an antioxidant gas between the semiconductor substrate W and the hot plate 1004 during 25 annealing, and a gas discharge pipe 1012 for discharging the gas which has been introduced from the gas introduction pipe 1010 and flowed between the semiconductor substrate W and the hot plate 1004. The pipes 1010 and 1012 are disposed on the opposite sides of 30 the hot plate 1004.

The gas introduction pipe 1010 is connected to a mixed gas introduction line 1022 which in turn is connected to a mixer 1020 where a N₂ gas introduced

through a N_2 gas introduction line 1016 containing a filter 1014a, and a H_2 gas introduced through a H_2 gas introduction line 1018 containing a filter 1014b, are mixed to form a mixed gas which flows through the line 5 1022 into the gas introduction pipe 1010.

In operation, the semiconductor substrate W, which has been carried in the chamber 1002 through the gate 1000, is held on the elevating pins 1008 and the elevating pins 1008 are raised up to a position at which 10 the distance between the semiconductor substrate W held on the lifting pins 1008 and the hot plate 1004 becomes e.g. 0.1-1.0 mm. In this state, the semiconductor substrate W is then heated to e.g. 400°C through the hot plate 1004 and, at the same time, the antioxidant gas is 15 introduced from the gas introduction pipe 1010 and the gas is allowed to flow between the semiconductor substrate W and the hot plate 1004 while the gas is discharged from the gas discharge pipe 1012, thereby annealing the semiconductor substrate W while preventing 20 its oxidation. The annealing treatment may be completed in about several tens of seconds to 60 seconds. The heating temperature of the substrate may be selected in the range of 100-600°C.

After the completion of the annealing, the 25 elevating pins 1008 are lowered down to a position at which the distance between the semiconductor substrate W held on the elevating pins 1008 and the cool plate 1006 becomes e.g. 0-0.5 mm. In this state, by introducing a cooling water into the cool plate 1006, the semiconductor 30 substrate W is cooled by the cool plate to a temperature of 100°C or lower in e.g. 10-60 seconds. The cooled semiconductor substrate is sent to the next step.

A mixed gas of N_2 gas with several % of H_2 gas

is used as the above antioxidant gas. However, N₂ gas may be used singly.

The annealing unit may be placed in the electroplating apparatus.

5 FIG. 33 is a schematic constitution drawing of the electroless plating apparatus. As shown in FIG. 33, this electroless plating apparatus comprises holding means 911 for holding a semiconductor substrate W to be plated on its upper surface, a dam member 931 for 10 contacting a peripheral edge portion of a surface to be plated (upper surface) of the semiconductor substrate W held by the holding means 911 to seal the peripheral edge portion, and a shower head 941 for supplying a plating liquid to the surface, to be plated, of the semiconductor 15 substrate W having the peripheral edge portion sealed with the dam member 931. The electroless plating apparatus further comprises cleaning liquid supply means 951 disposed near an upper outer periphery of the holding means 911 for supplying a cleaning liquid to the surface, 20 to be plated, of the semiconductor substrate W, a recovery vessel 961 for recovering a cleaning liquid or the like (plating waste liquid) discharged, a plating liquid recovery nozzle 965 for sucking in and recovering the plating liquid held on the semiconductor substrate W, 25 and a motor M for rotationally driving the holding means 911. The respective members will be described below.

The holding means 911 has a substrate placing portion 913 on its upper surface for placing and holding the semiconductor substrate W. The substrate placing portion 30 913 is adapted to place and fix the semiconductor substrate W. Specifically, the substrate placing portion 913 has a vacuum attracting mechanism (not shown) for attracting the semiconductor substrate W to a backside

thereof by vacuum suction. A backside heater 915, which is planar and heats the surface, to be plated, of the semiconductor substrate W from underside to keep it warm, is installed on the backside of the substrate placing 5 portion 913. The backside heater 915 is composed of, for example, a rubber heater. This holding means 911 is adapted to be rotated by the motor M and is movable vertically by raising and lowering means (not shown).

The dam member 931 is tubular, has a seal 10 portion 933 provided in a lower portion thereof for sealing the outer peripheral edge of the semiconductor substrate W, and is installed so as not to move vertically from the illustrated position.

The shower head 941 is of a structure having 15 many nozzles provided at the front end for scattering the supplied plating liquid in a shower form and supplying it substantially uniformly to the surface, to be plated, of the semiconductor substrate W. The cleaning liquid supply means 951 has a structure for ejecting a cleaning 20 liquid from a nozzle 953.

The plating liquid recovery nozzle 965 is adapted to be movable upward and downward and swingable, and the front end of the plating liquid recovery nozzle 965 is adapted to be lowered inwardly of the dam member 25 931 located on the upper surface peripheral edge portion of the semiconductor substrate W and to suck in the plating liquid on the semiconductor substrate W.

Next, the operation of the electroless plating apparatus will be described. First, the holding means 30 911 is lowered from the illustrated state to provide a gap of a predetermined dimension between the holding means 911 and the dam member 931, and the semiconductor substrate W is placed on and fixed to the substrate

placing portion 913. An 8 inch substrate, for example, is used as the semiconductor substrate W.

Then, the holding means 911 is raised to bring its upper surface into contact with the lower surface of 5 the dam member 931 as illustrated, and the outer periphery of the semiconductor substrate W is sealed with the seal portion 933 of the dam member 931. At this time, the surface of the semiconductor substrate W is in an open state.

10 Then, the semiconductor substrate W itself is directly heated by the backside heater 915 to render the temperature of the semiconductor substrate W, for example, 70°C (maintained until termination of plating). Then, the plating liquid heated, for example, to 50°C is 15 ejected from the shower head 941 to pour the plating liquid over substantially the entire surface of the semiconductor substrate W. Since the surface of the semiconductor substrate W is surrounded by the dame member 931, the poured plating liquid is all held on the 20 surface of the semiconductor substrate W. The amount of the supplied plating liquid may be a small amount which will become a 1 mm thickness (about 30 ml) on the surface of the semiconductor substrate W. The depth of the plating liquid held on the surface to be plated may be 25 10 mm or less, and may be even 1 mm as in this embodiment. If a small amount of the supplied plating liquid is sufficient, the heating apparatus for heating the plating liquid may be of a small size. In this example, the 30 temperature of the semiconductor substrate W is raised to 70°C, and the temperature of the plating liquid is raised to 50°C by heating. Thus, the surface, to be plated, of the semiconductor substrate W becomes, for example, 60°C, and hence a temperature optimal for a plating reaction in

this example can be achieved.

The semiconductor substrate W is instantaneously rotated by the motor M to perform uniform liquid wetting of the surface to be plated, and then 5 plating of the surface to be plated is performed in such a state that the semiconductor substrate W is in a stationary state. Specifically, the semiconductor substrate W is rotated at 100 rpm or less for only 1 second to uniformly wet the surface, to be plated, of the 10 semiconductor substrate W with the plating liquid. Then, the semiconductor substrate W is kept stationary, and electroless plating is performed for 1 minute. The instantaneous rotating time is 10 seconds or less at the longest.

15 After completion of the plating treatment, the front end of the plating liquid recovery nozzle 965 is lowered to an area near the inside of the dam member 931 on the peripheral edge portion of the semiconductor substrate W to suck in the plating liquid. At this time, 20 if the semiconductor substrate W is rotated at a rotational speed of, for example, 100 rpm or less, the plating liquid remaining on the semiconductor substrate W can be gathered in the portion of the dam member 931 on the peripheral edge portion of the semiconductor 25 substrate W under centrifugal force, so that recovery of the plating liquid can be performed with a good efficiency and a high recovery rate. The holding means 911 is lowered to separate the semiconductor substrate W from the dam member 931. The semiconductor substrate W 30 is started to be rotated, and the cleaning liquid (ultrapure water) is jetted at the plated surface of the semiconductor substrate W from the nozzle 953 of the cleaning liquid supply means 951 to cool the plated

surface, and simultaneously perform dilution and cleaning, thereby stopping the electroless plating reaction. At this time, the cleaning liquid jetted from the nozzle 953 may be supplied to the dam member 931 to 5 perform cleaning of the dam member 931 at the same time. The plating waste liquid at this time is recovered into the recovery vessel 961 and discarded.

Then, the semiconductor substrate W is rotated at a high speed by the motor M for spin-drying, and then 10 the semiconductor substrate W is removed from the holding means 911.

FIG. 34 is a schematic constitution drawing of another electroless plating. The electroless plating apparatus of FIG. 34 is different from the electroless plating apparatus of FIG. 33 in that instead of providing the backside heater 915 in the holding means 911, lamp heaters 917 are disposed above the holding means 911, and the lamp heaters 917 and a shower head 941-2 are integrated. For example, a plurality of ring-shaped lamp 15 heaters 917 having different radii are provided concentrically, and many nozzles 943-2 of the shower head 941-2 are open in a ring form from the gaps between the lamp heaters 917. The lamp heaters 917 may be composed of a single spiral lamp heater, or may be composed of 20 other lamp heaters of various structures and arrangements.

Even with this constitution, the plating liquid can be supplied from each nozzle 943-2 to the surface, to be plated, of the semiconductor substrate W substantially 25 uniformly in a shower form. Further, heating and heat retention of the semiconductor substrate W can be performed by the lamp heaters 917 directly uniformly. The lamp heaters 917 heat not only the semiconductor

substrate W and the plating liquid, but also ambient air, thus exhibiting a heat retention effect on the semiconductor substrate W.

Direct heating of the semiconductor substrate W by the lamp heaters 917 requires the lamp heaters 917 with a relatively large electric power consumption. In place of such lamp heaters 917, lamp heaters 917 with a relatively small electric power consumption and the backside heater 915 shown in FIG. 32 may be used in combination to heat the semiconductor substrate W mainly with the backside heater 915 and to perform heat retention of the plating liquid and ambient air mainly by the lamp heaters 917. In the same manner as in the aforementioned embodiment, means for directly or indirectly cooling the semiconductor substrate W may be provided to perform temperature control.

The cap plating described above is preferably performed by electroless plating process, but may be performed by electroplating process.

Although certain preferred embodiments of the present invention have been shown and described in detail, it should be understood that various changes and modifications may be made therein without departing from the scope of the appended claims.

25

Industrial Applicability

A substrate processing apparatus according to the present invention is suitably used for filling a metal such as copper or the like in interconnection recesses defined in a semiconductor substrate.

CLAIMS

1. A substrate processing apparatus for processing a substrate, comprising:

5 a head assembly for holding a substrate; and a plurality of substrate processing sections for performing respective processes on said substrate held by said head assembly;

10 wherein said head assembly is movable between said substrate processing sections while holding said substrate, and said respective processes on said substrate are successively performed in said respective substrate processing sections.

15 2. A substrate processing apparatus according to claim 1, wherein at least one of said substrate processing sections comprises a plating section for plating said substrate.

20 3. A substrate processing apparatus according to claim 1, wherein at least one of said substrate processing sections comprises a cleaning section for cleaning said substrate.

25 4. A substrate processing apparatus according to claim 3, wherein said cleaning section comprises an air blower for applying a gas to dry the cleaned substrate.

30 5. A substrate processing apparatus according to claim 1, wherein said head assembly comprises a tilting mechanism for tiltably supporting said substrate.

6. A substrate processing apparatus for processing a substrate, comprising:

a plating section having a plating bath for holding a plating liquid therein;

5 a head assembly for holding a substrate and immersing said substrate in said plating liquid in said plating bath to form a plated film on a surface of said substrate;

10 a cleaning section for cleaning a peripheral edge of said plated substrate and a substrate contact portion held in contact with said substrate; and

a drive mechanism for moving said head assembly between said plating section and said cleaning section.

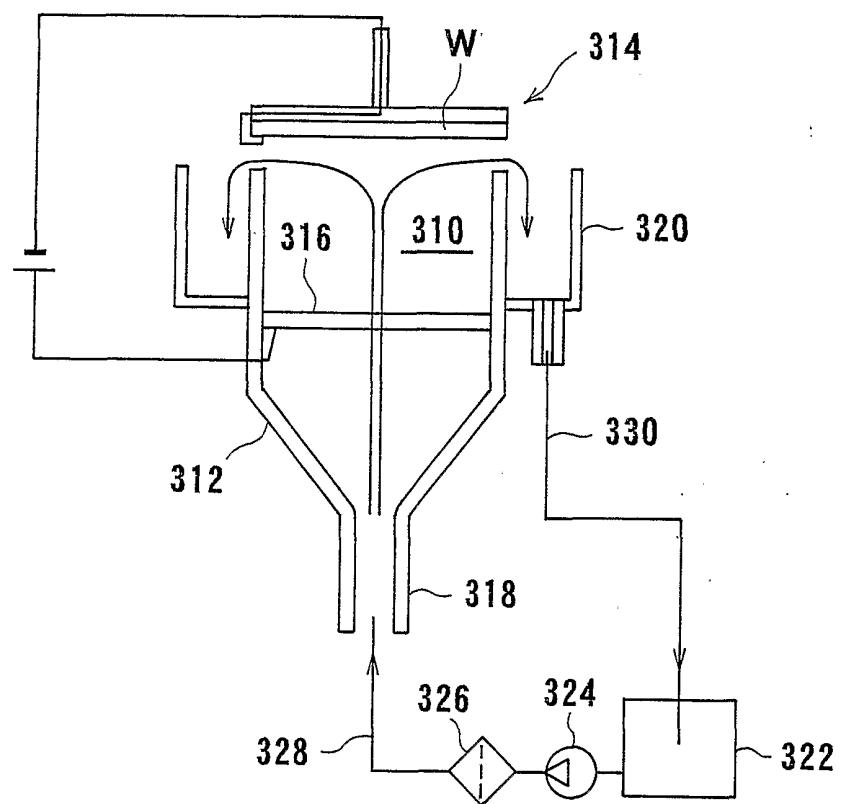
15 7. A substrate processing apparatus according to claim 6, further comprising a cover for covering said plating section and said cleaning section.

20 8. A substrate processing apparatus according to claim 7, wherein said drive mechanism is disposed outside of said cover.

25 9. A substrate processing apparatus according to claim 6, wherein said plating section and said cleaning section are separated from each other.

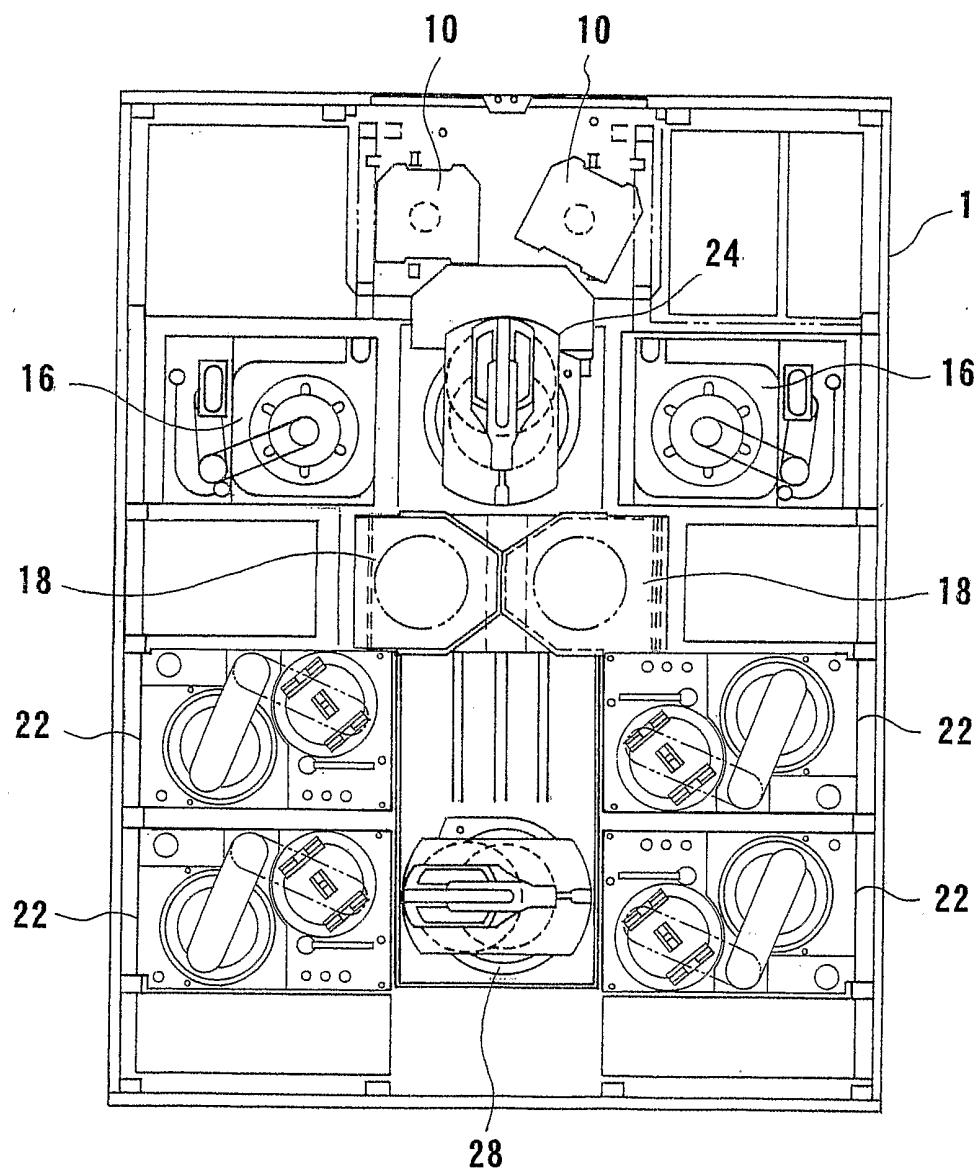
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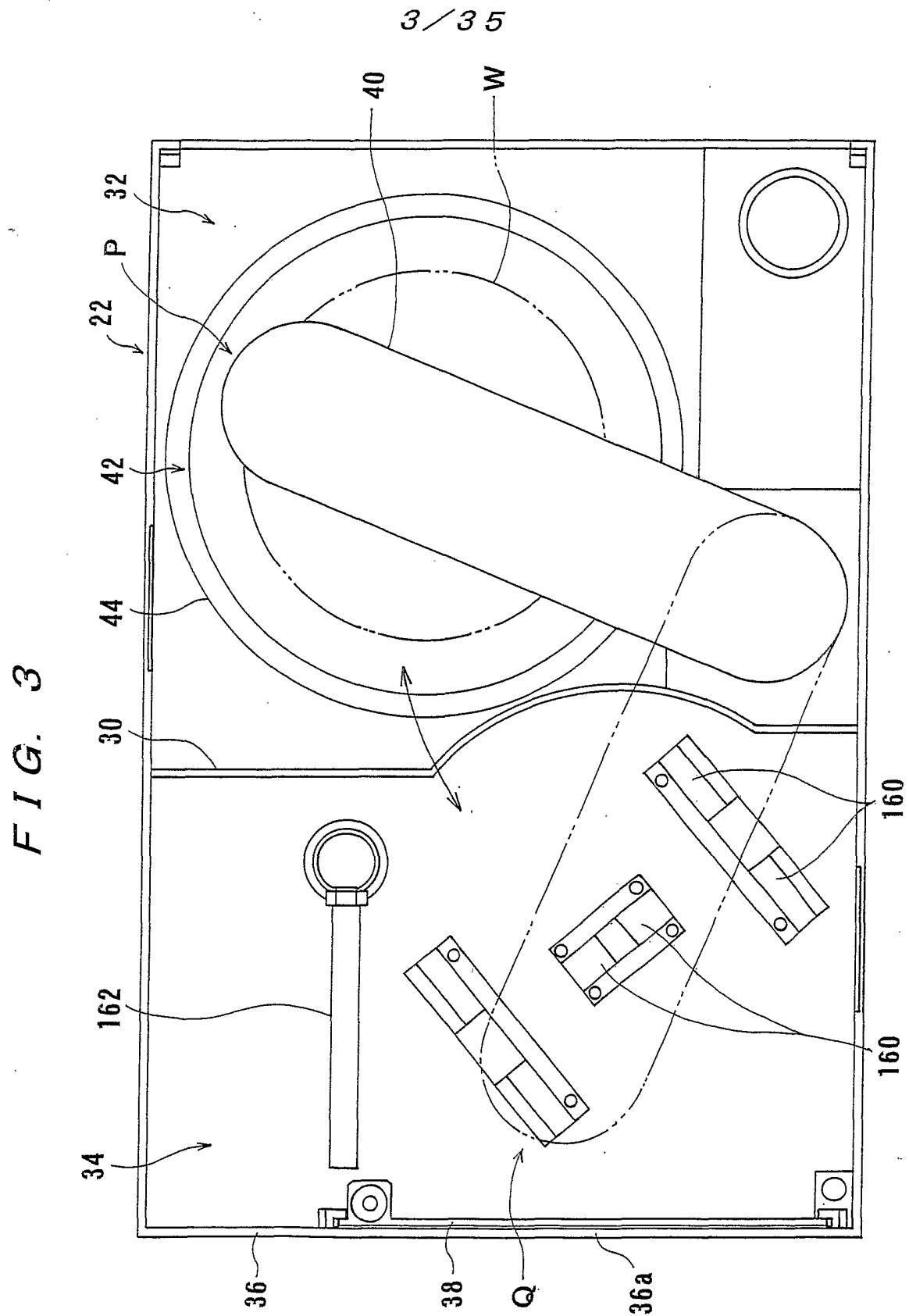
FIG. 1



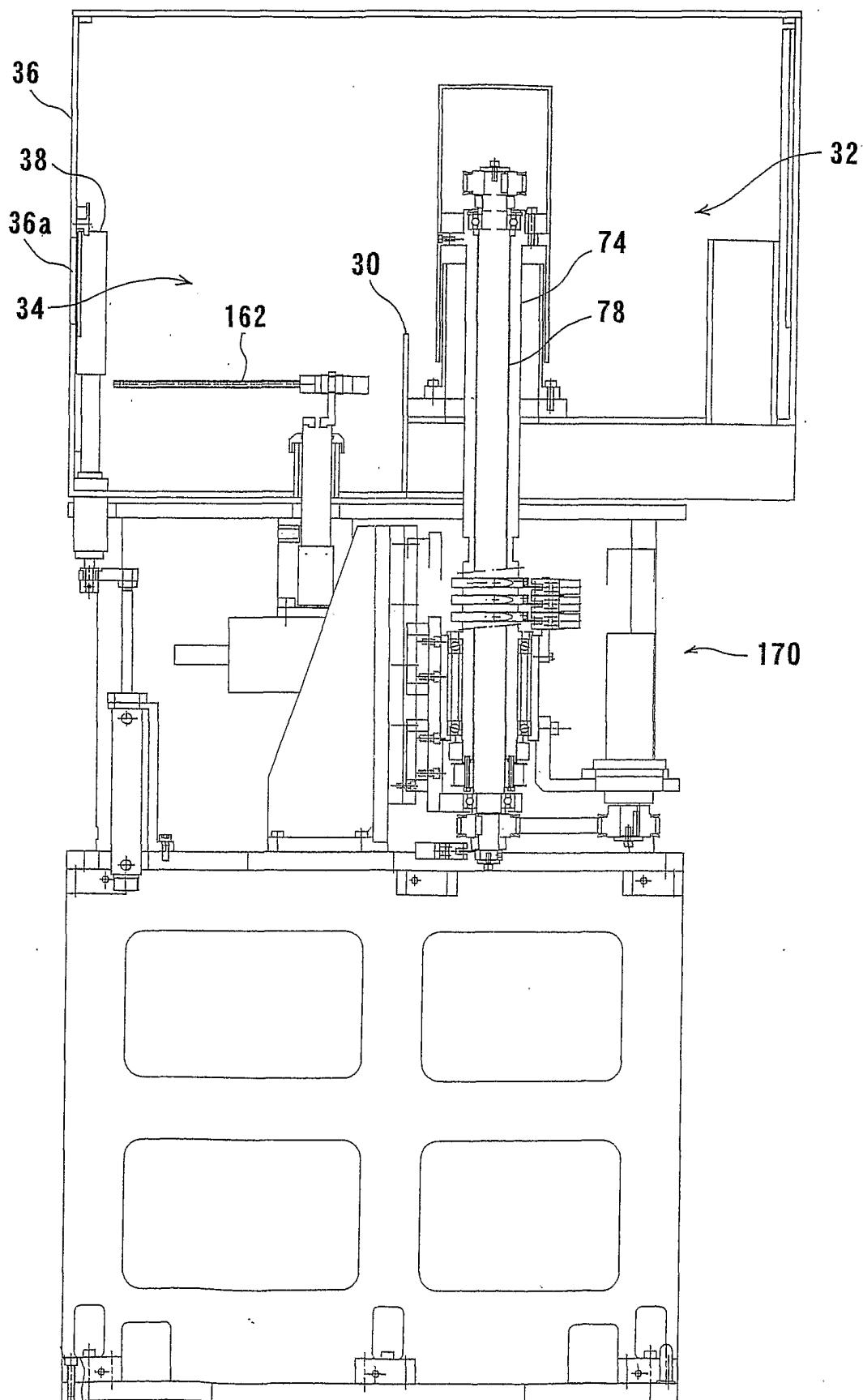
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FIG. 2





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FIG. 4



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FIG. 5

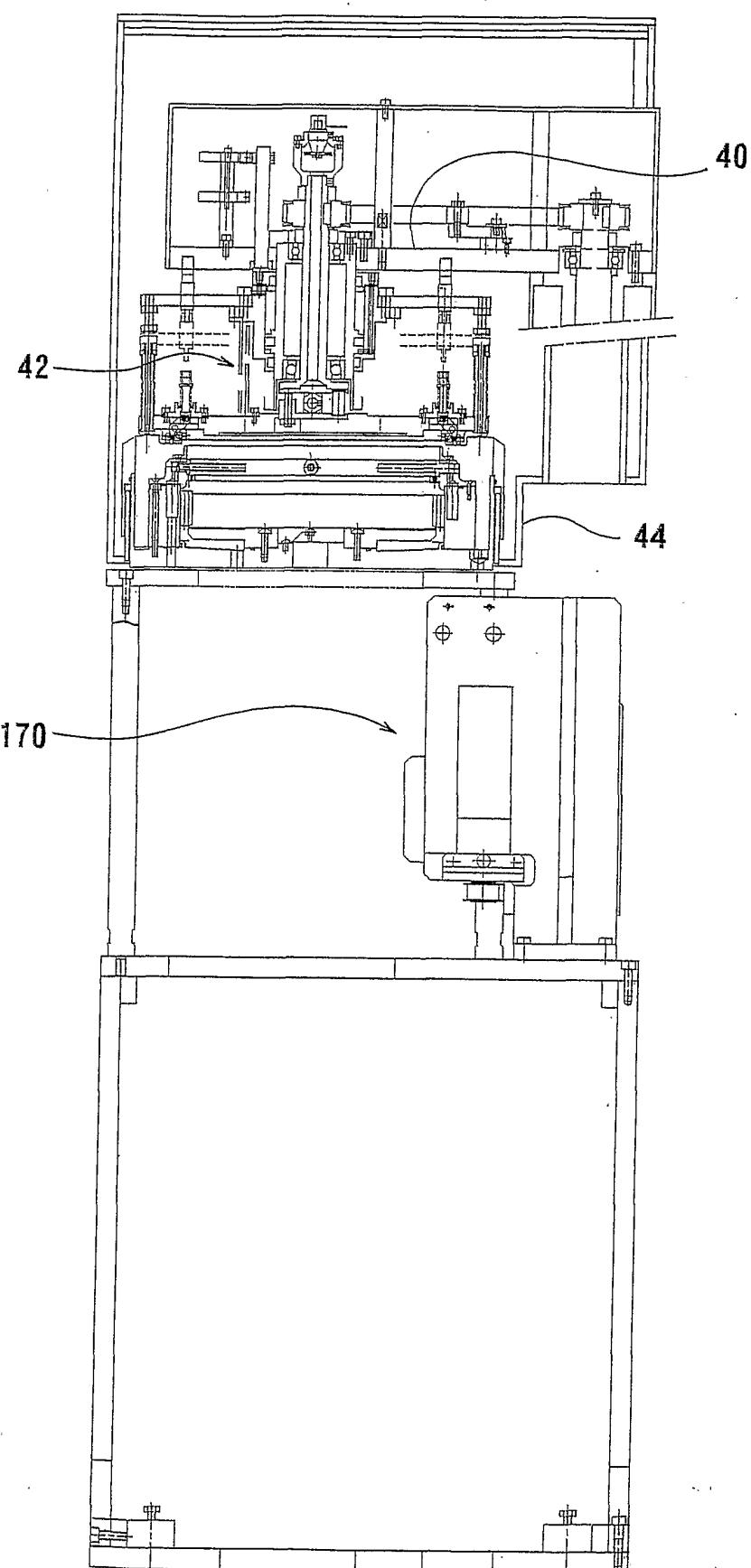


FIG. 6

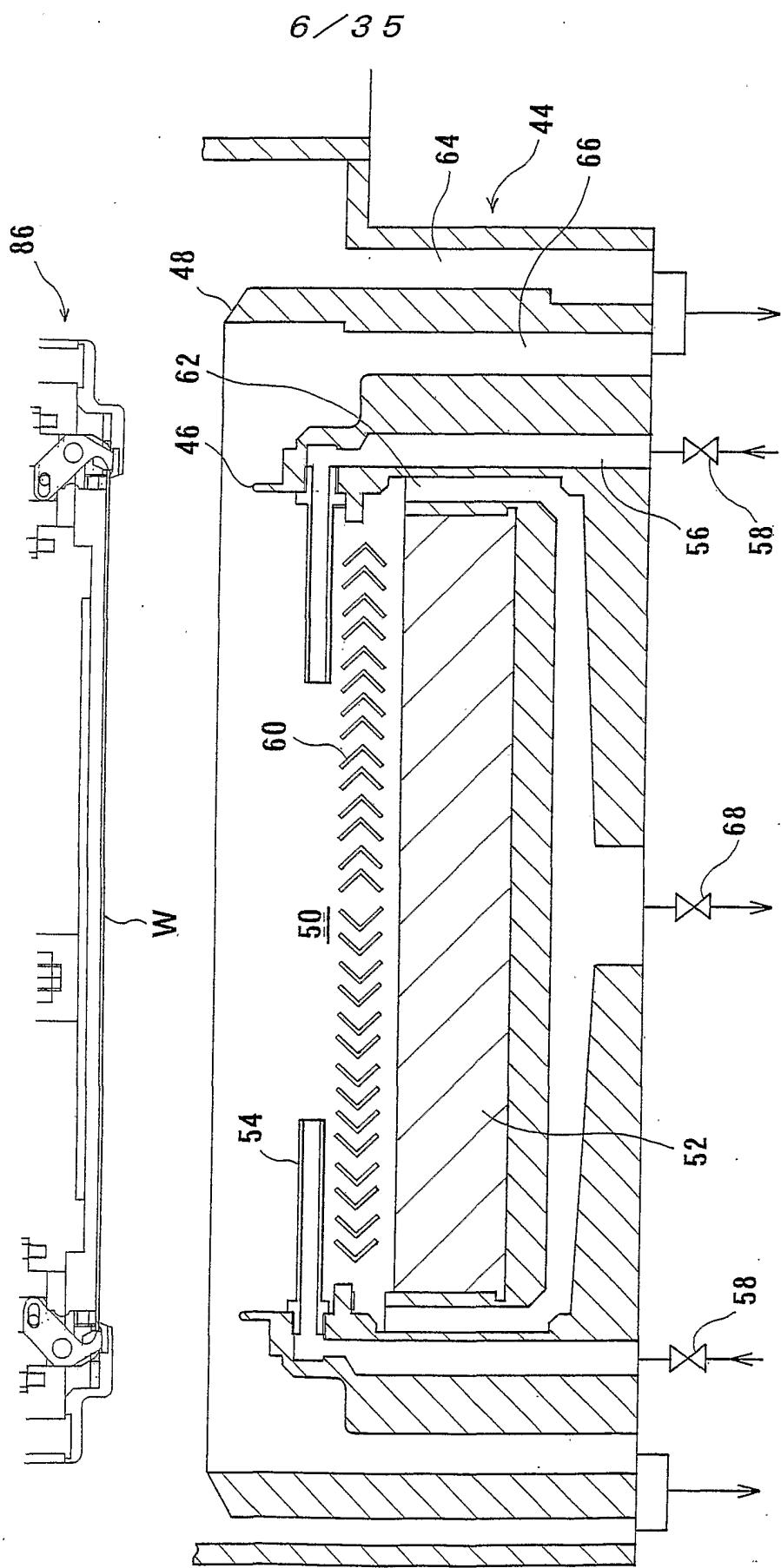
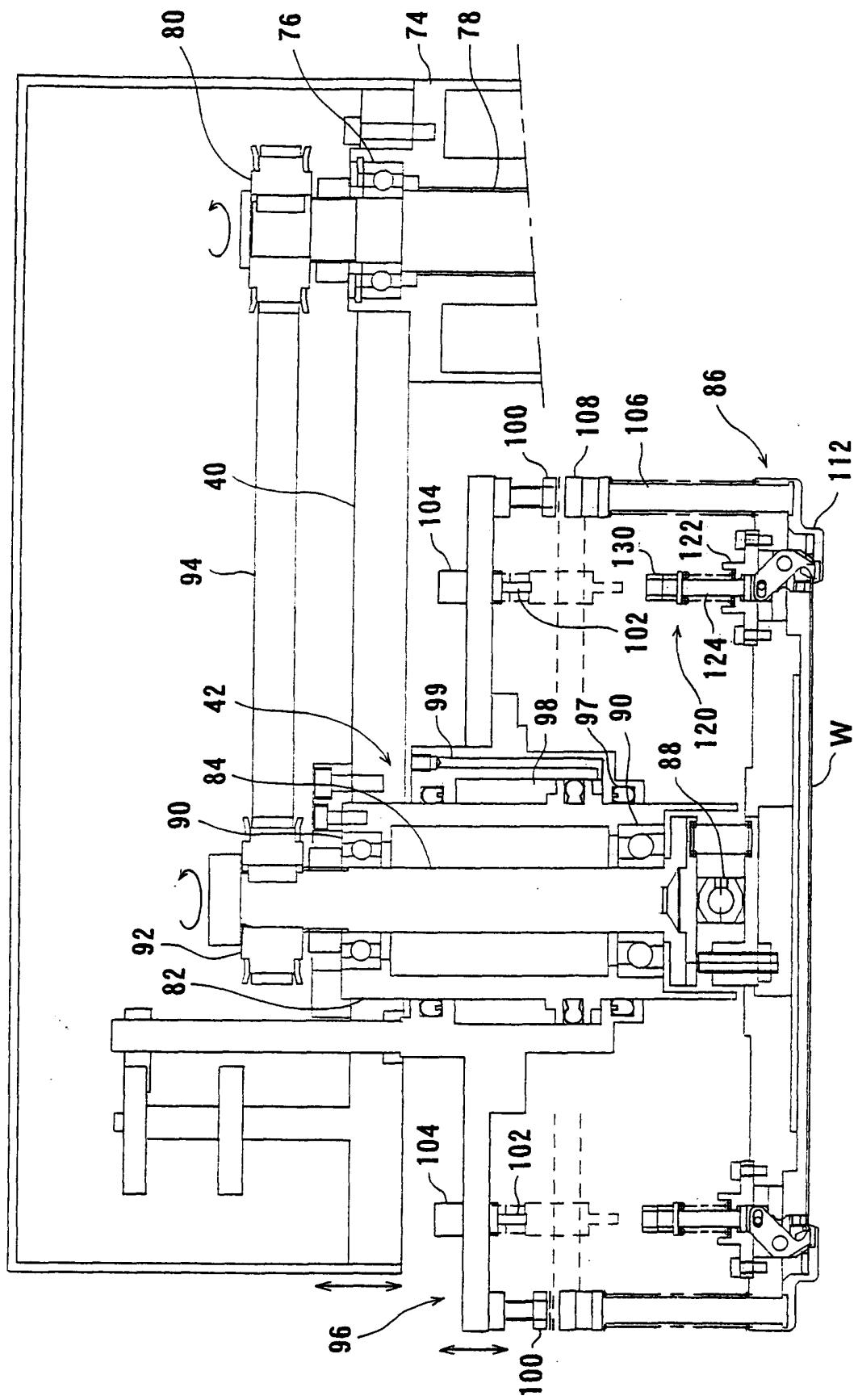


FIG. 7

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FIG. 8

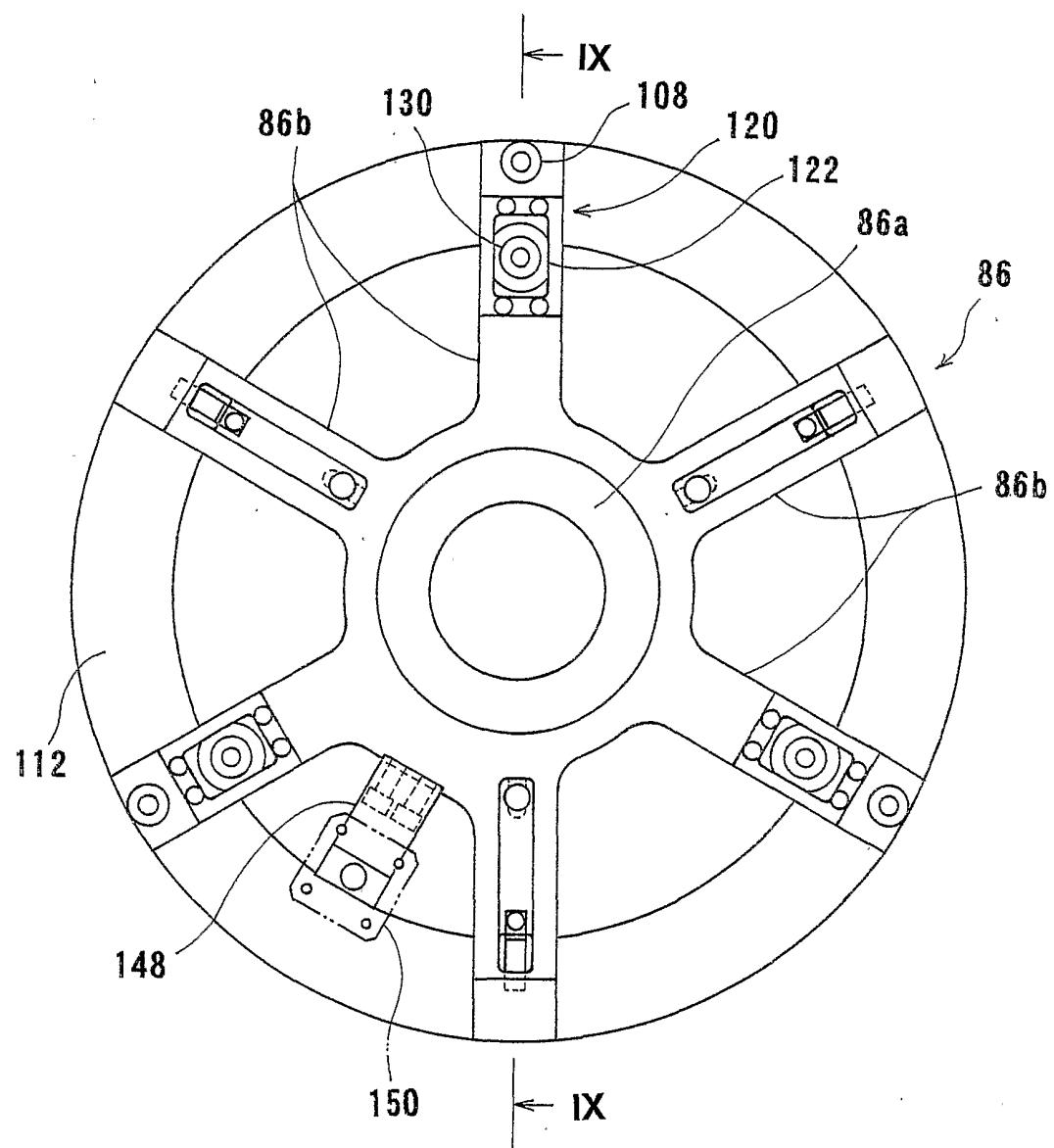
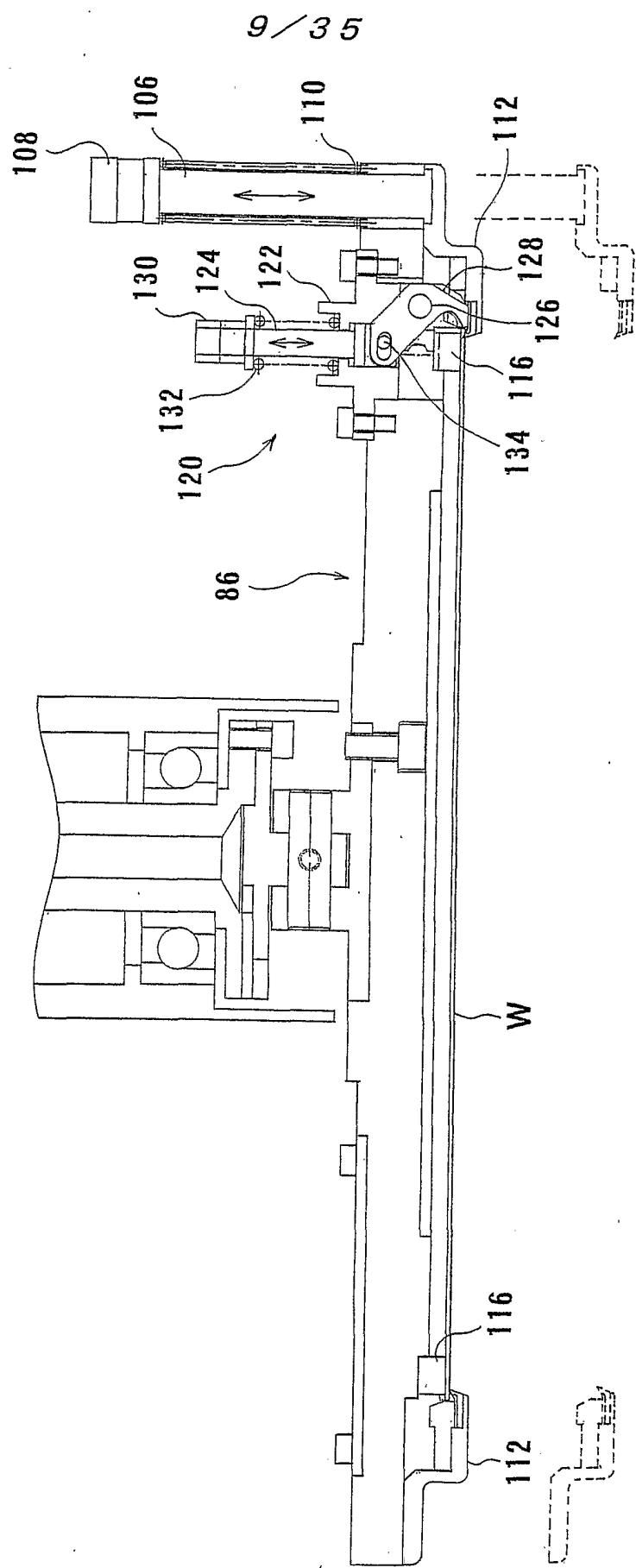
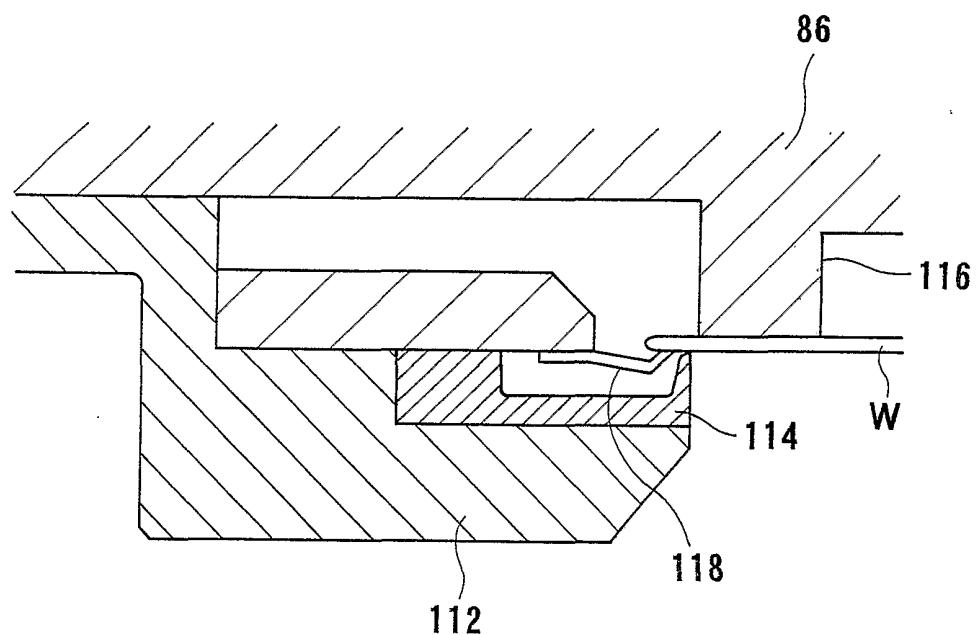


FIG. 9



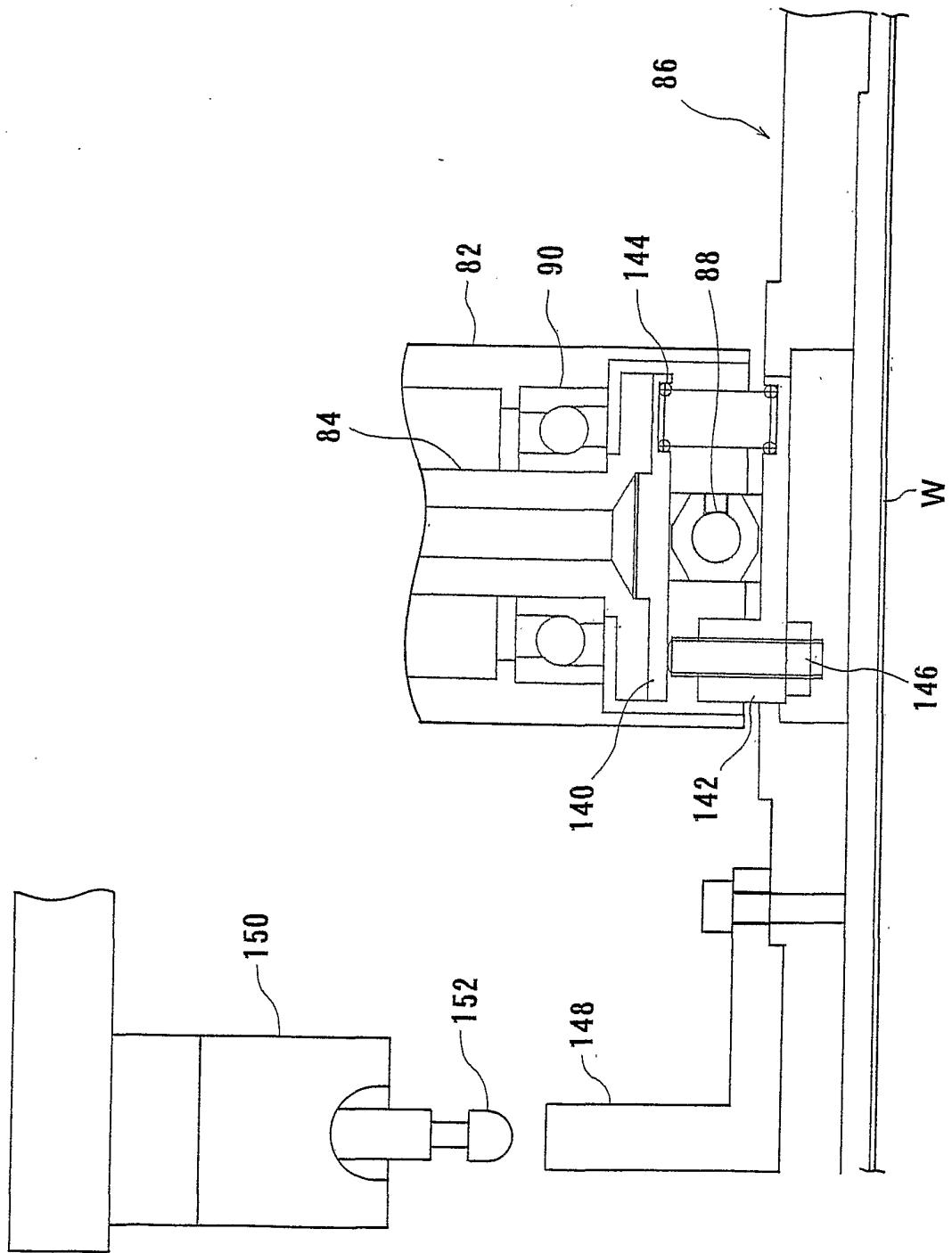
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FIG. 10



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FIG. 11



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FIG. 12

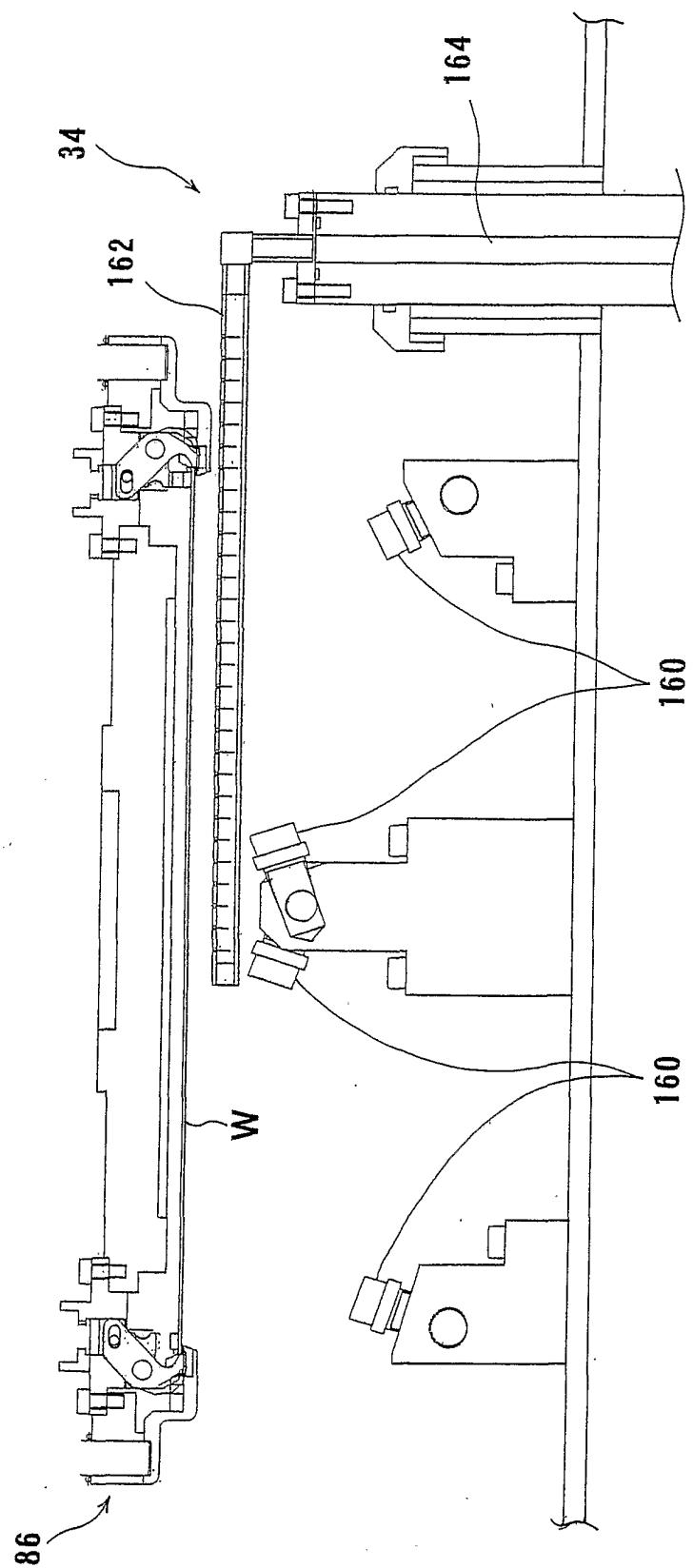
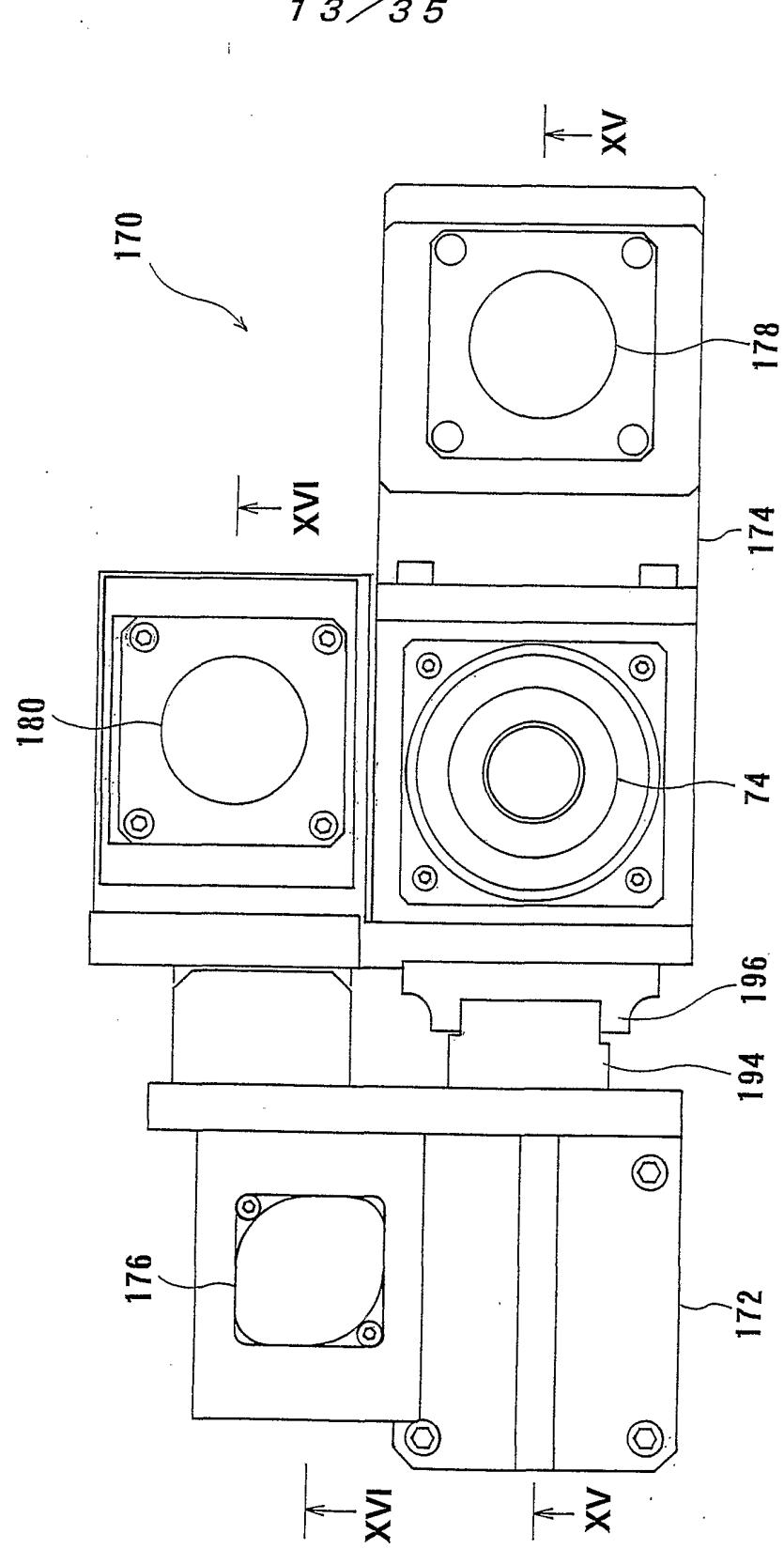
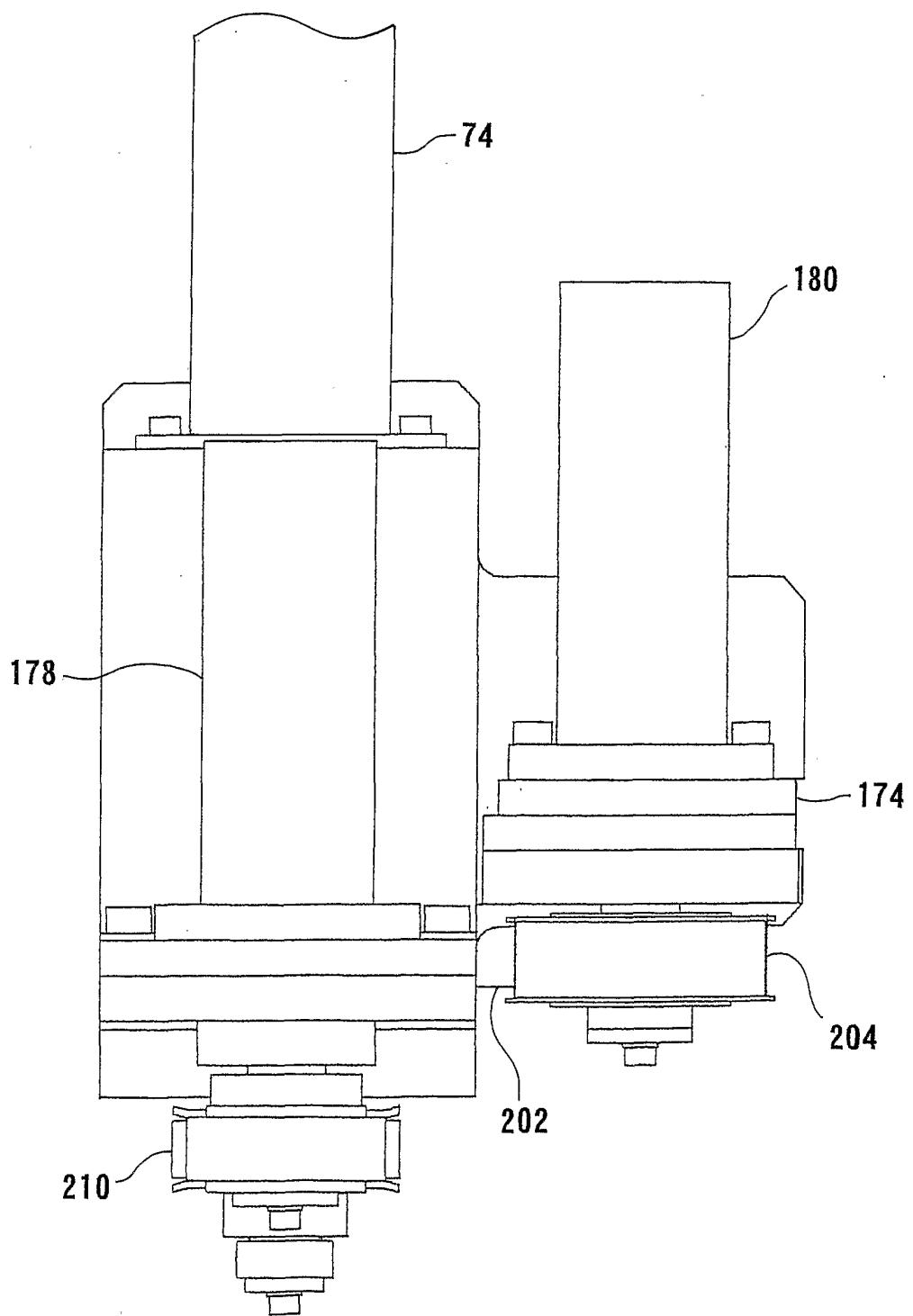


FIG. 13



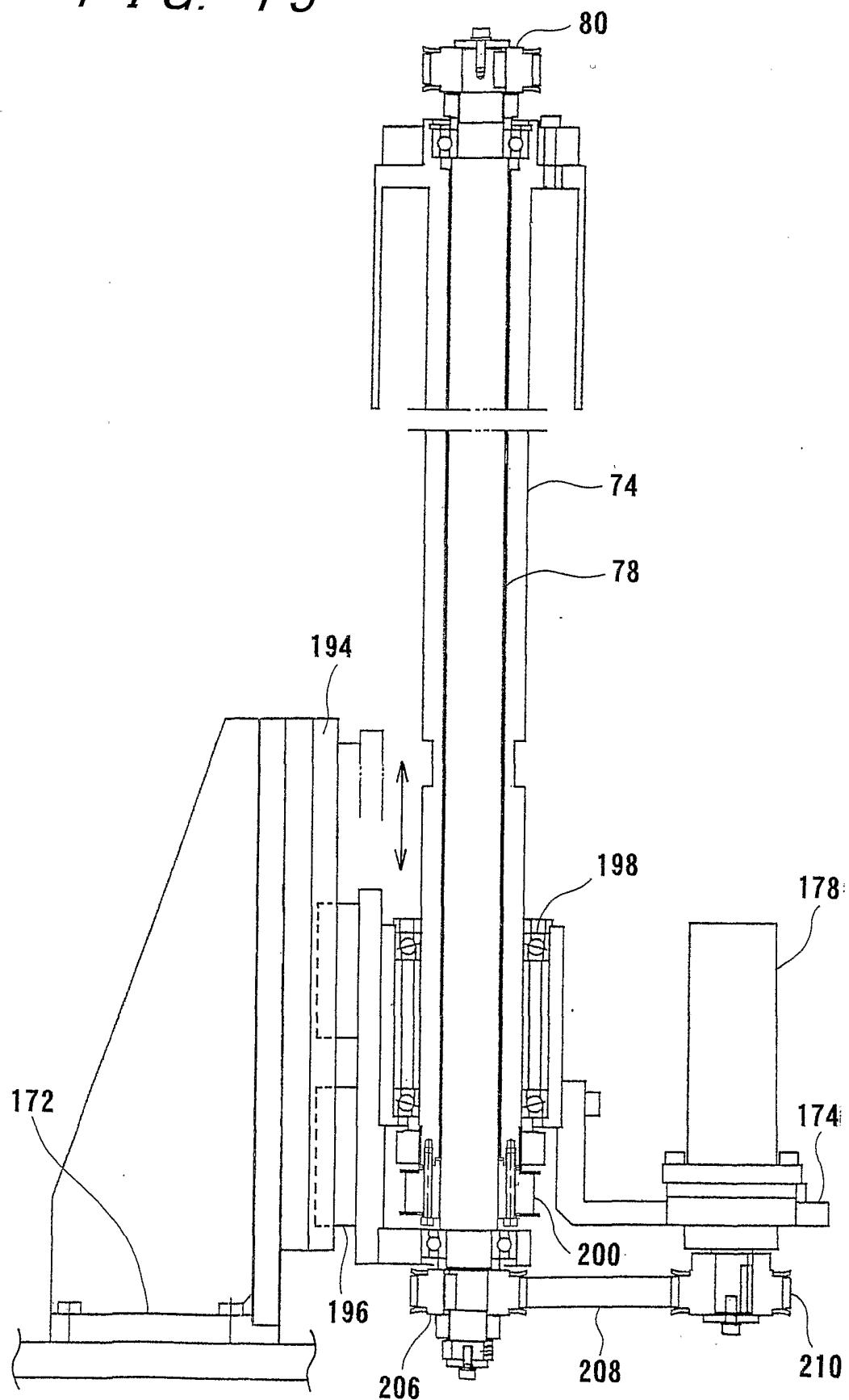
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FIG. 14



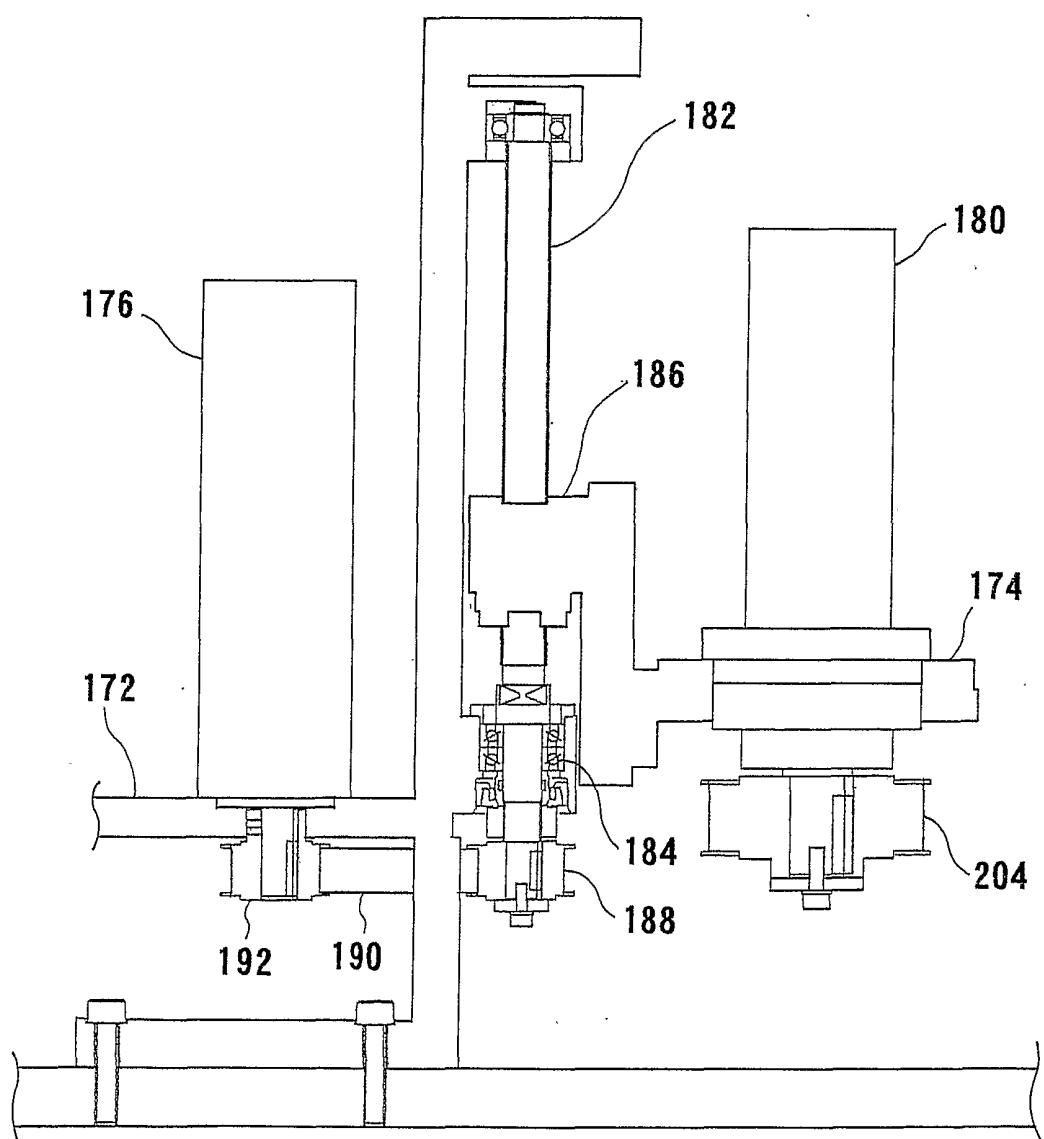
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FIG. 15



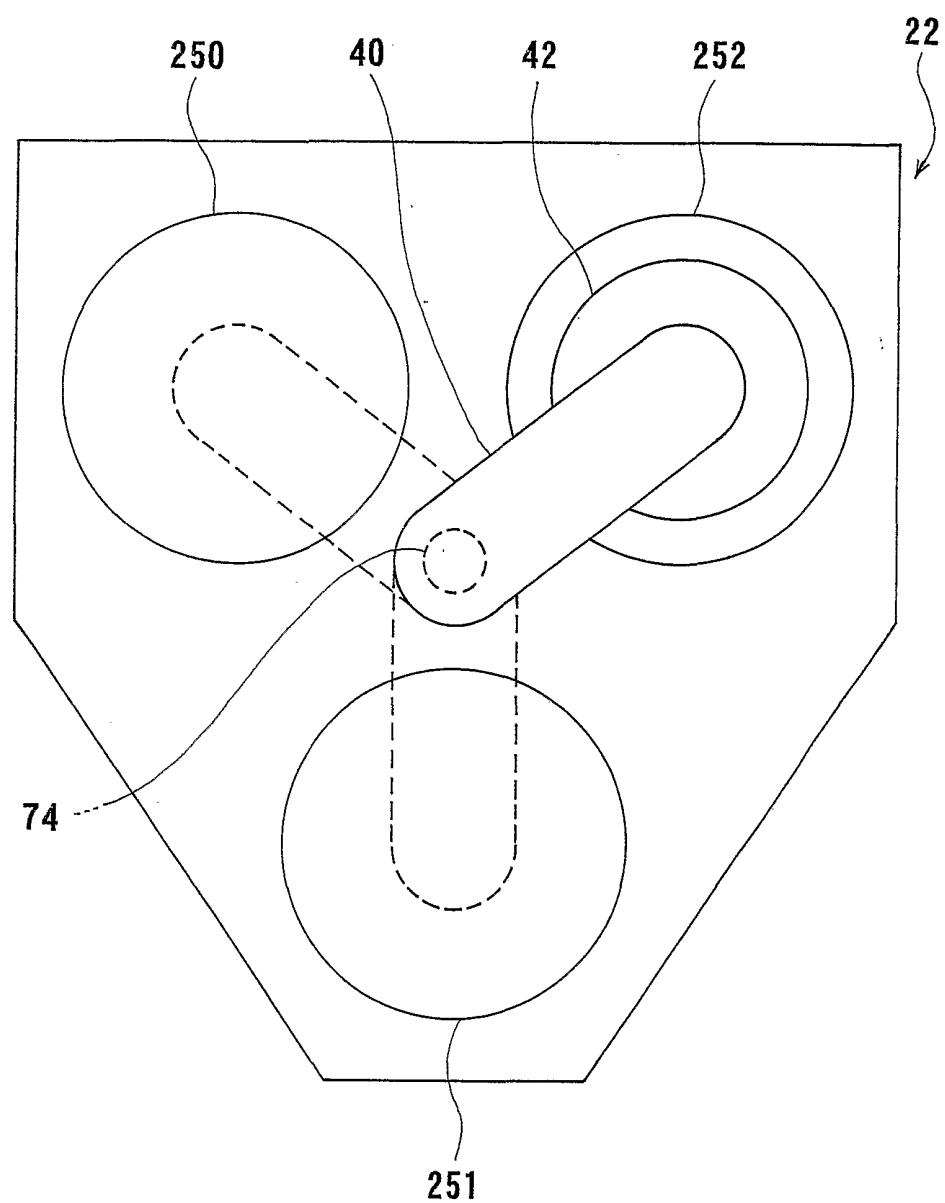
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FIG. 16



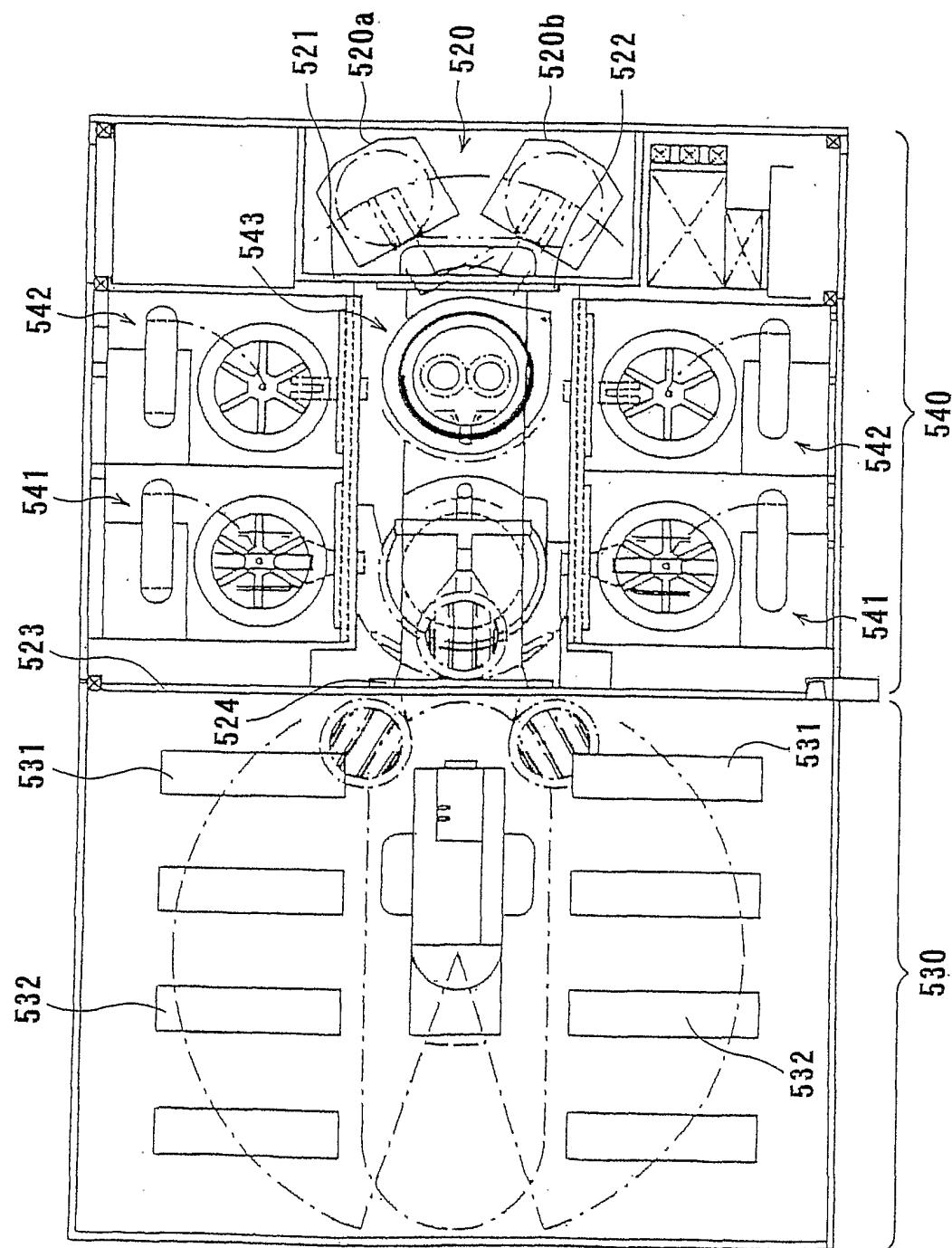
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FIG. 17



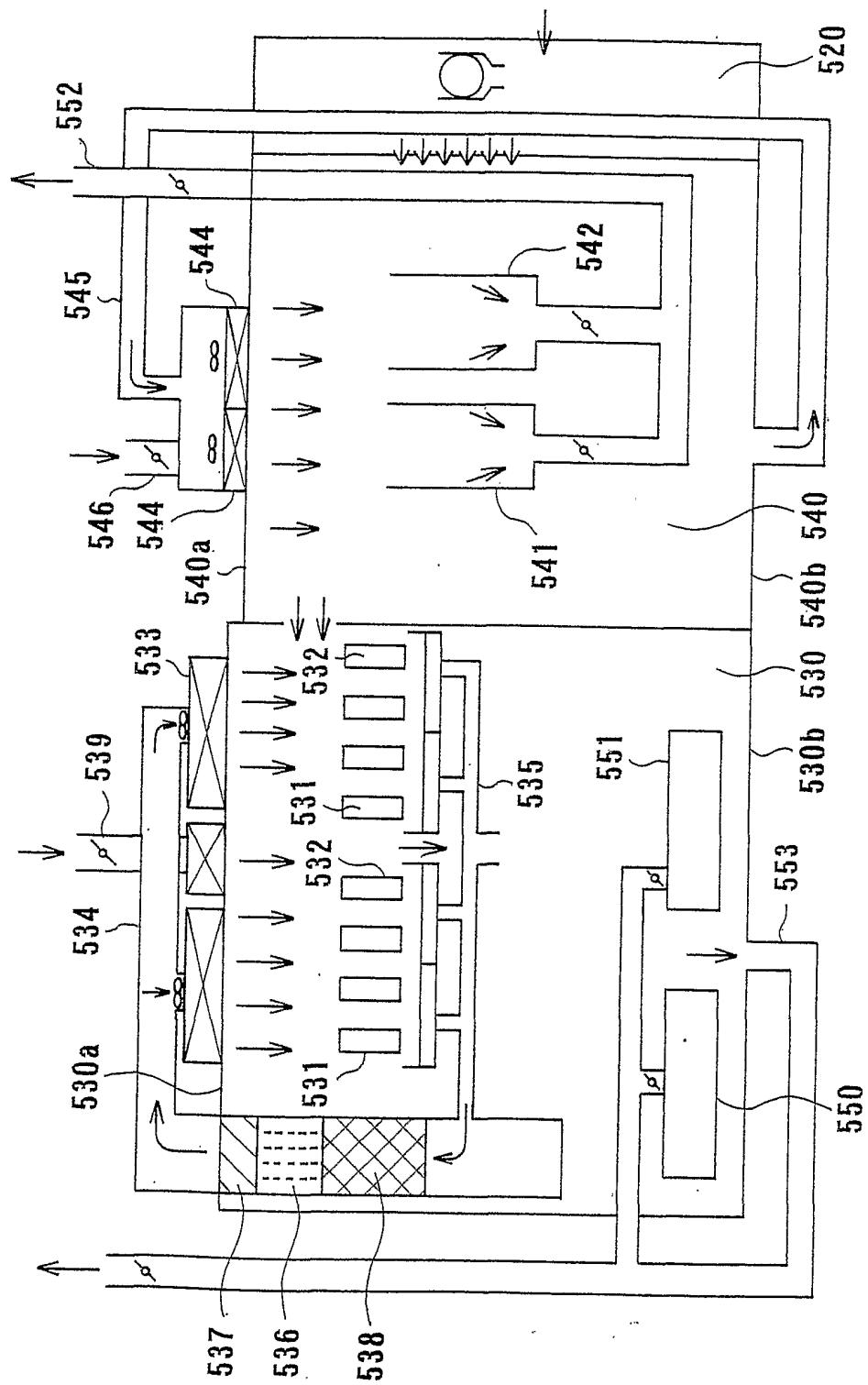
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FIG. 18



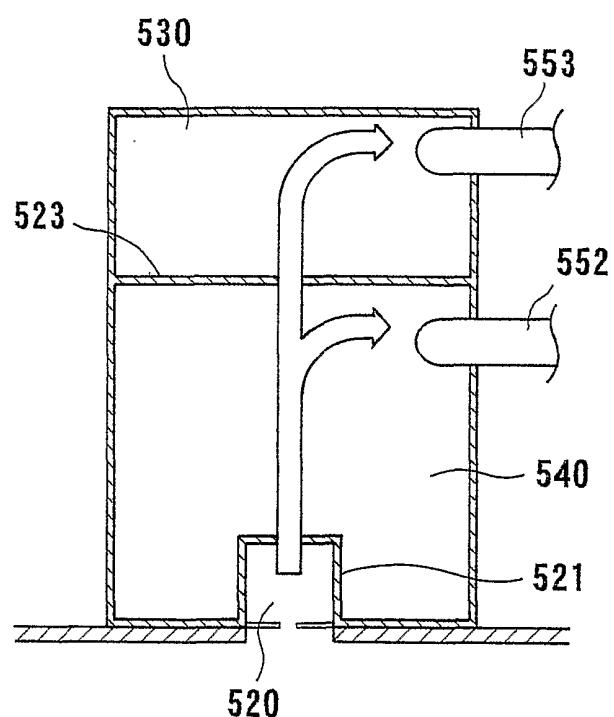
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FIG. 19



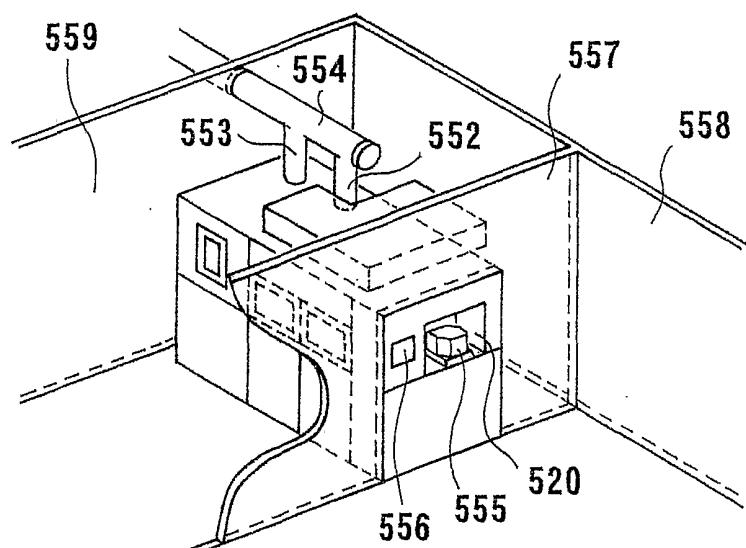
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FIG. 20



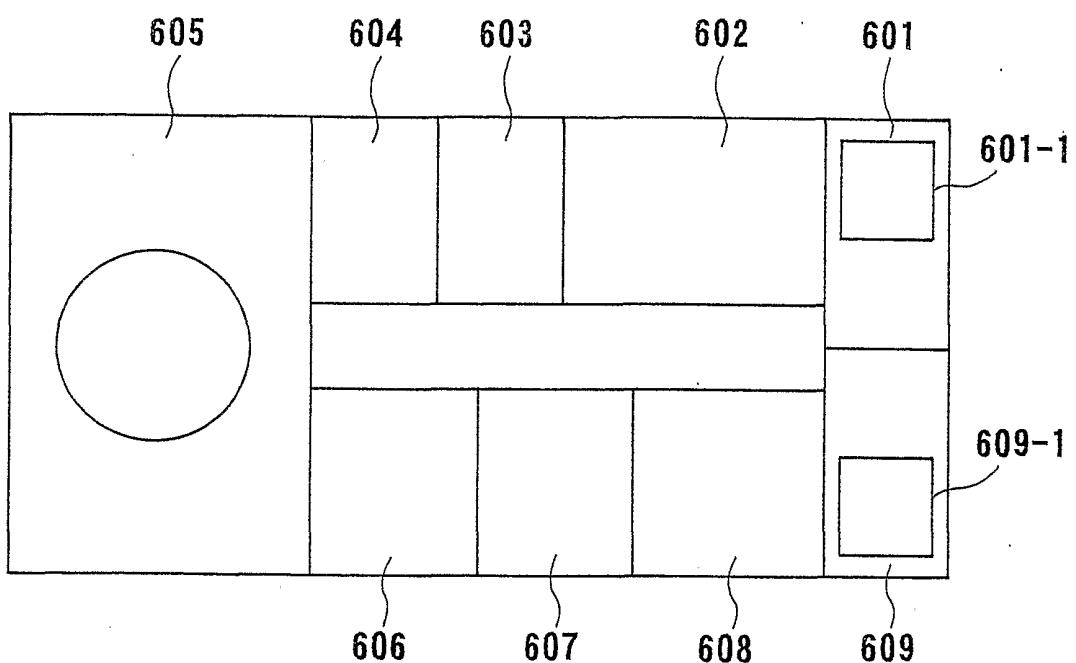
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FIG. 21



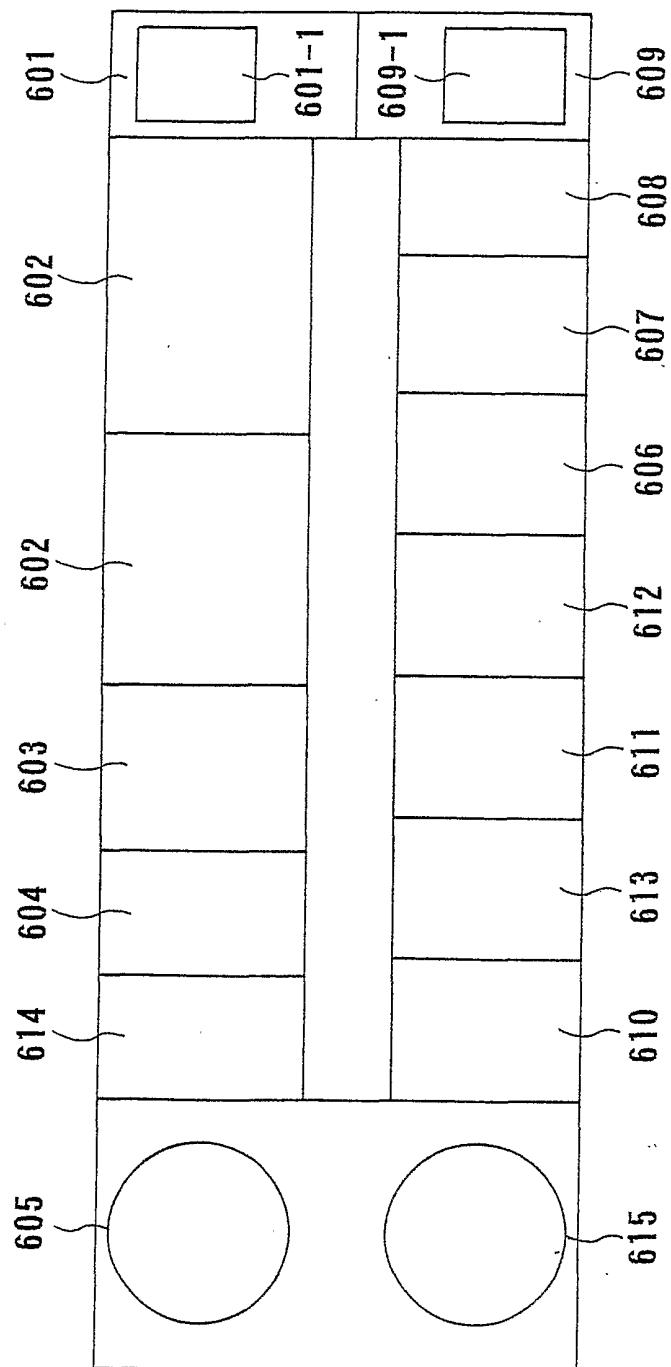
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FIG. 22



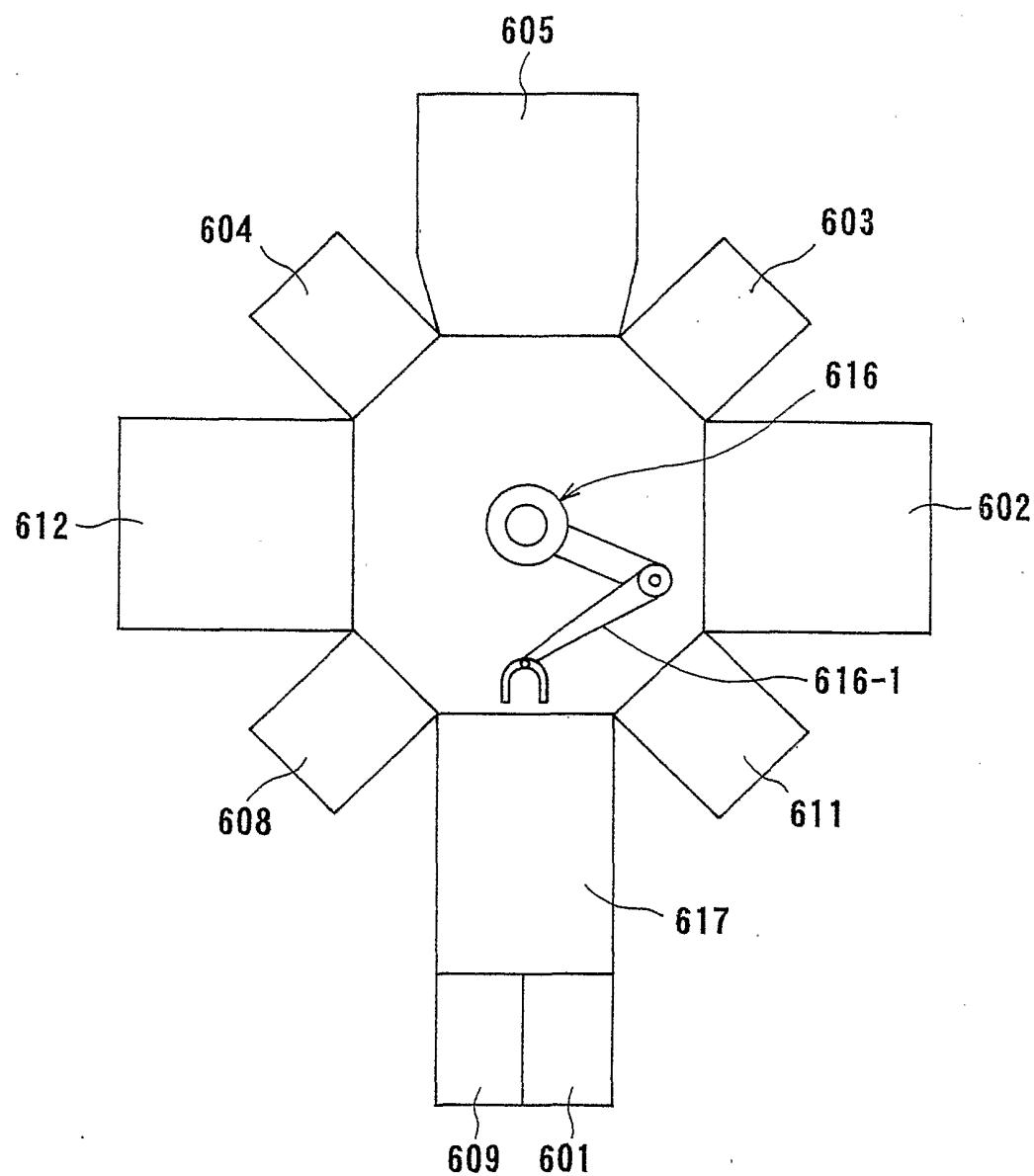
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FIG. 23



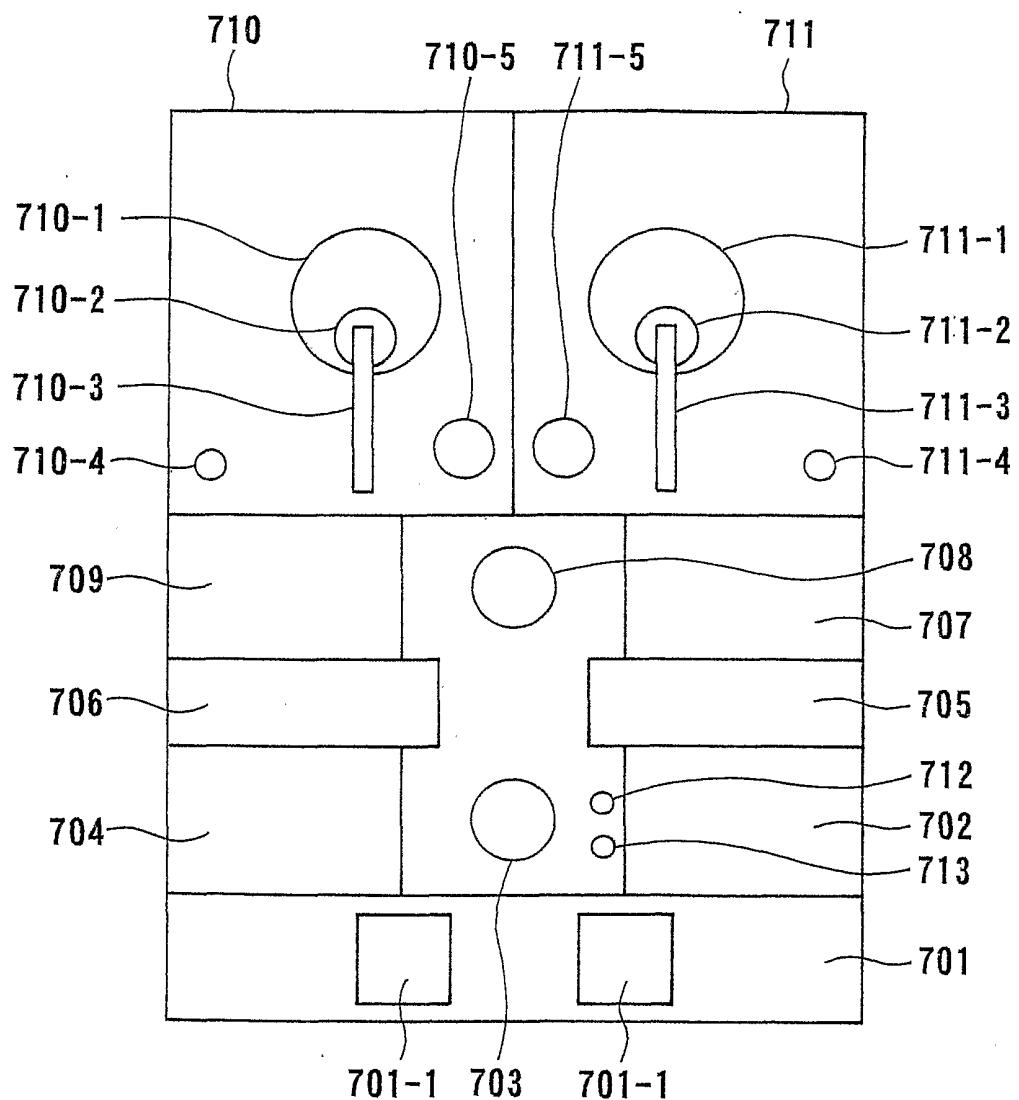
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FIG. 24



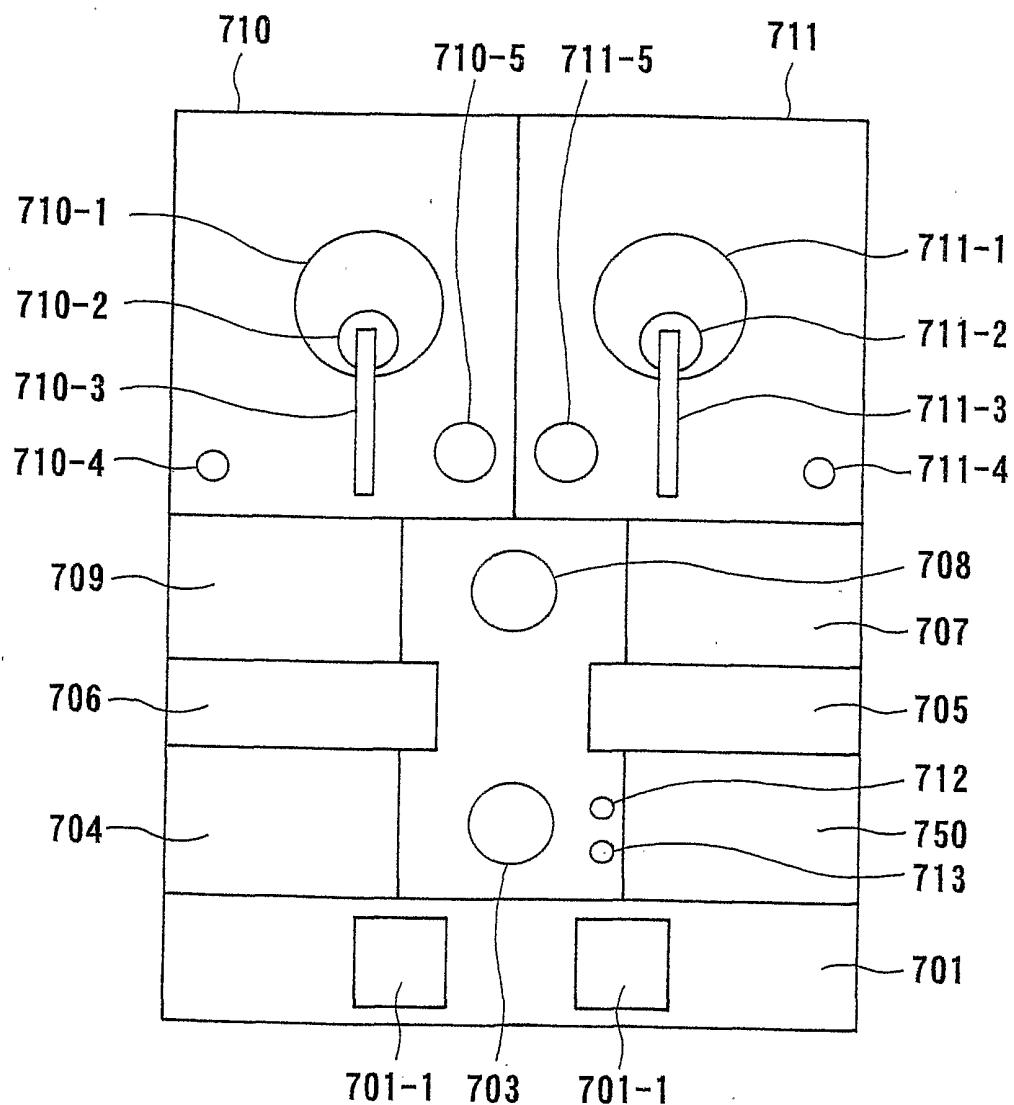
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FIG. 25



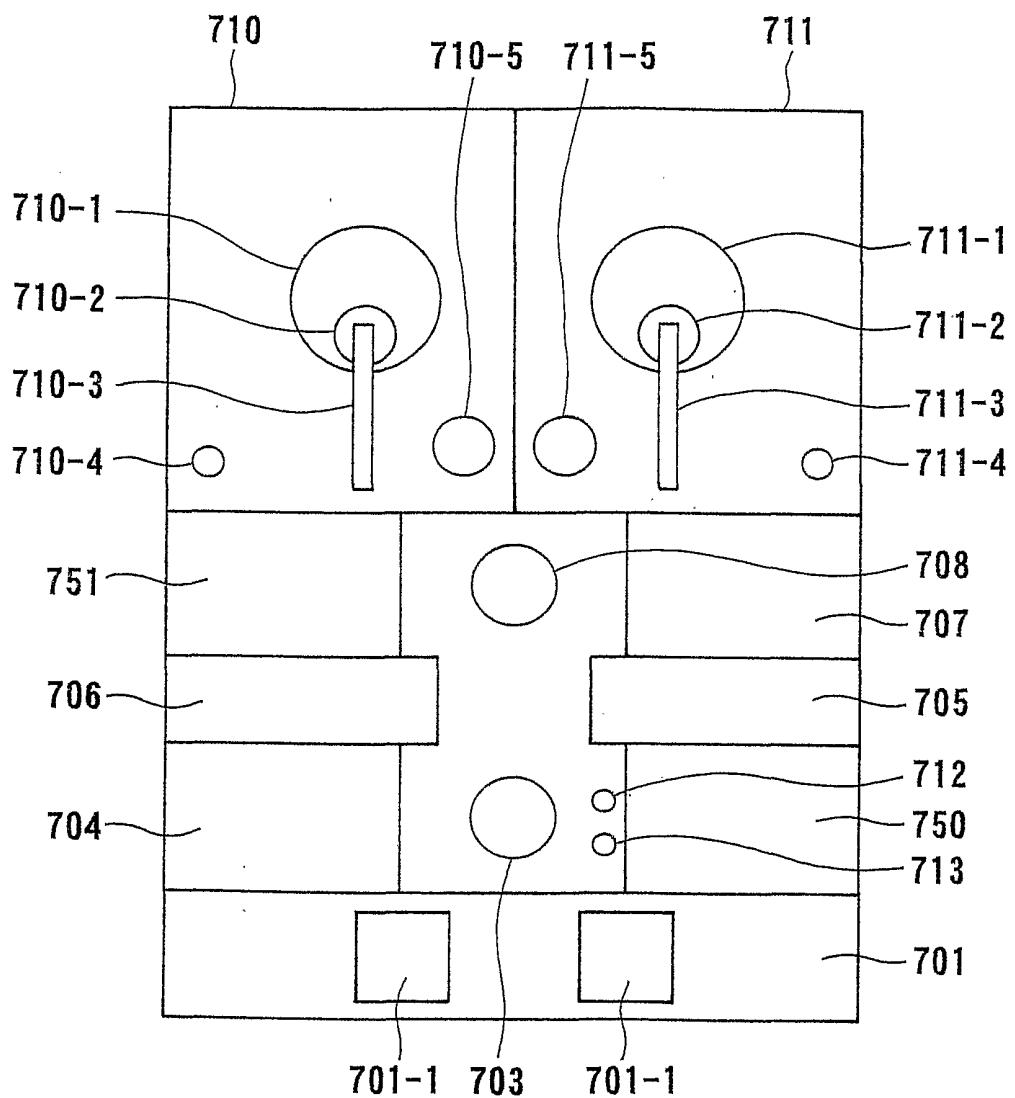
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FIG. 26



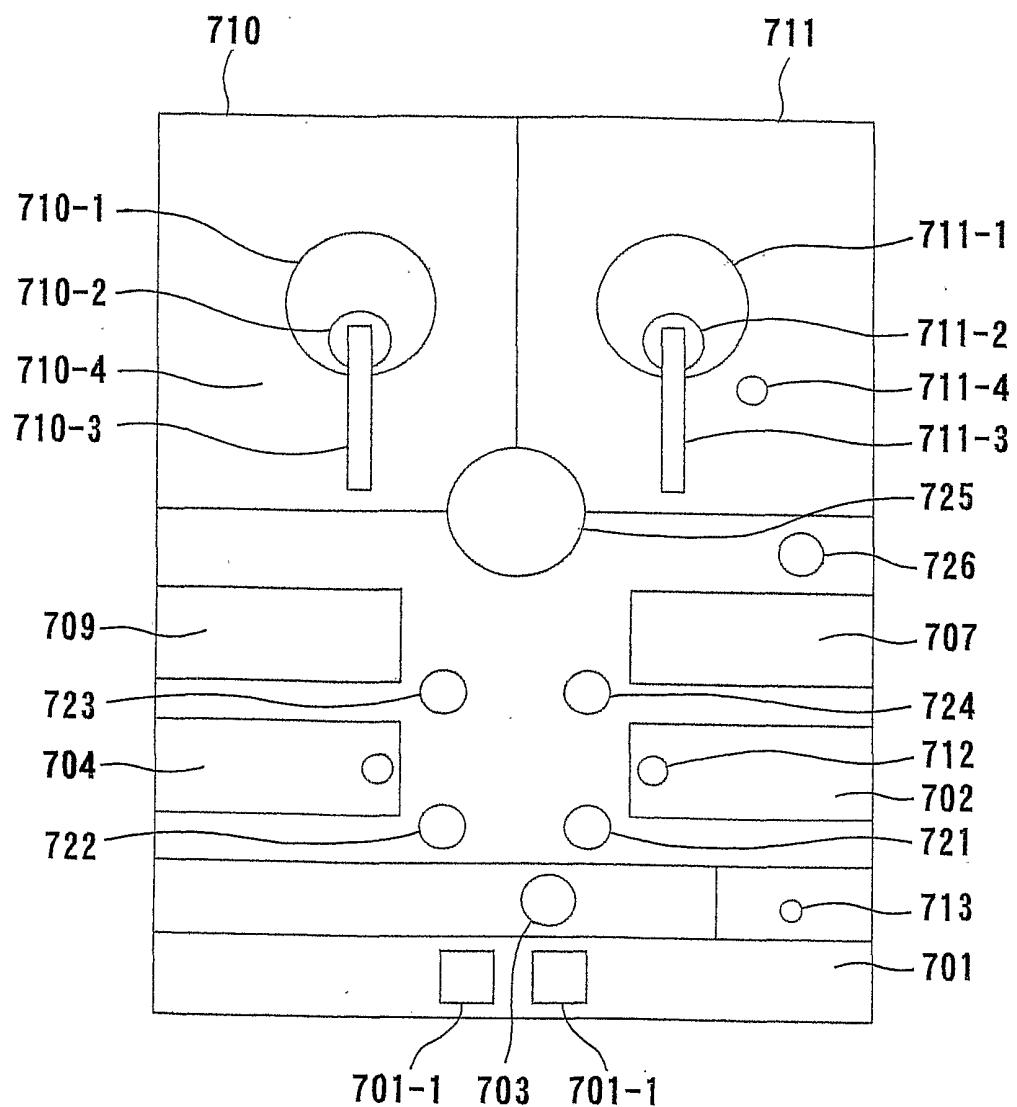
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FIG. 27



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FIG. 28



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FIG. 29

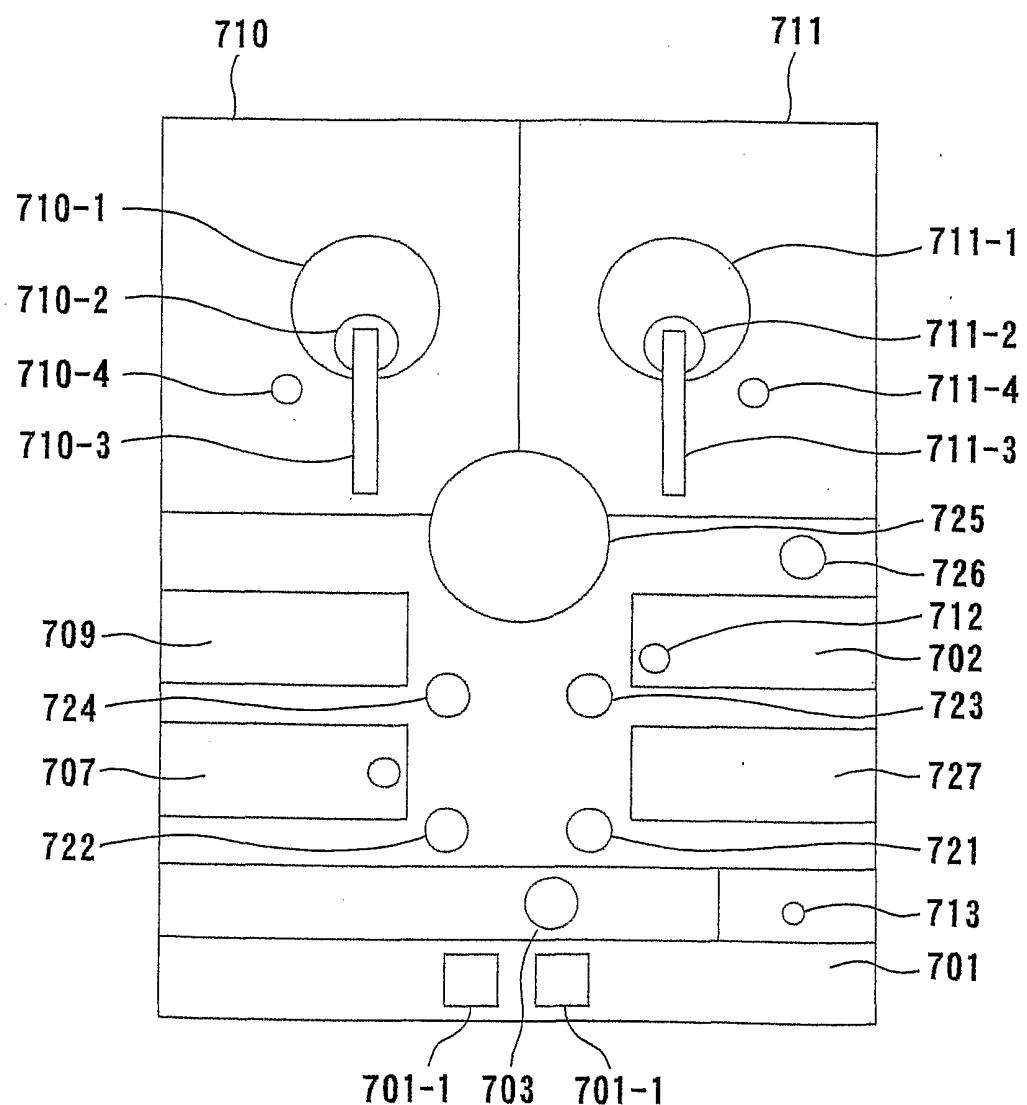
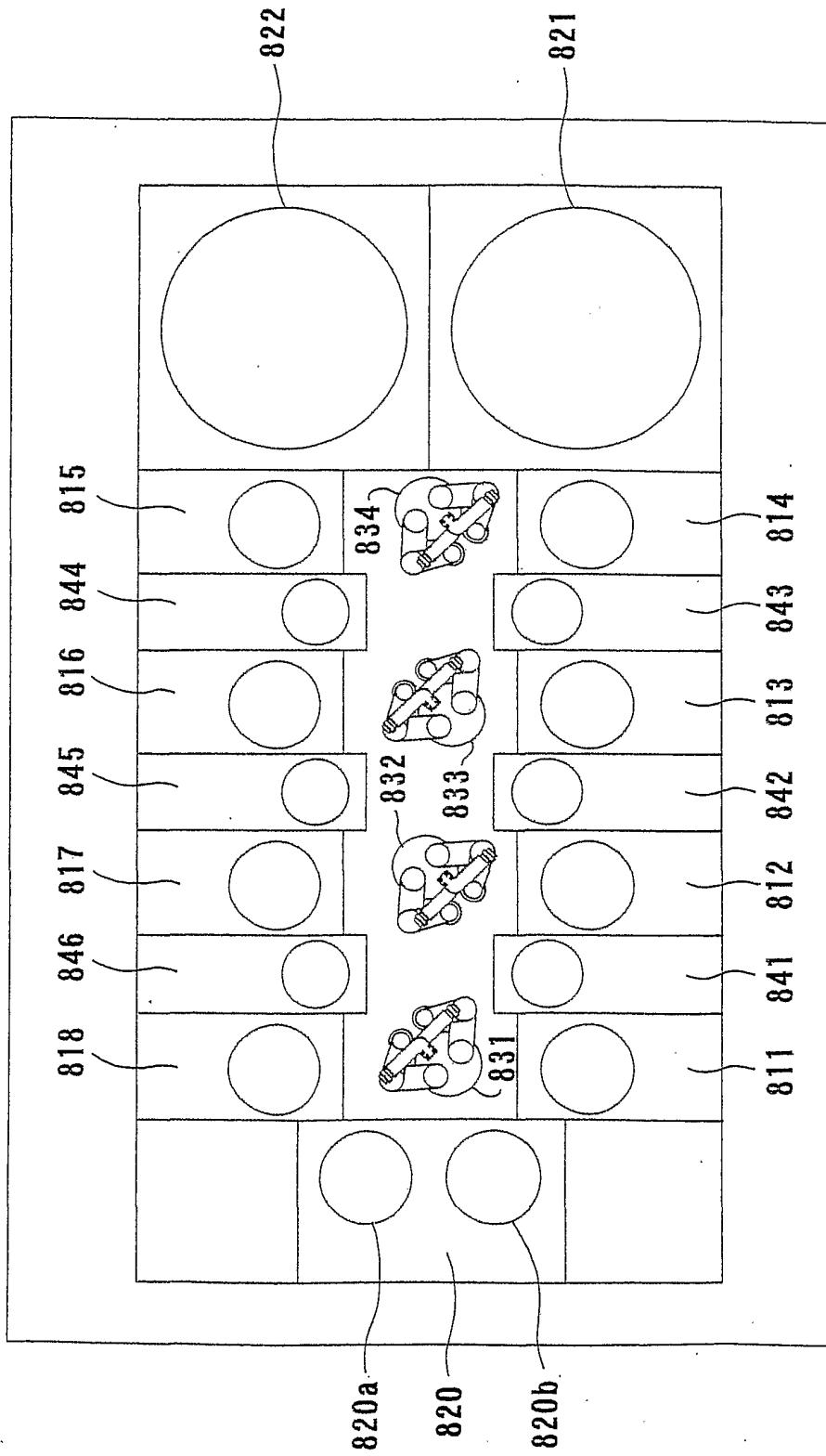


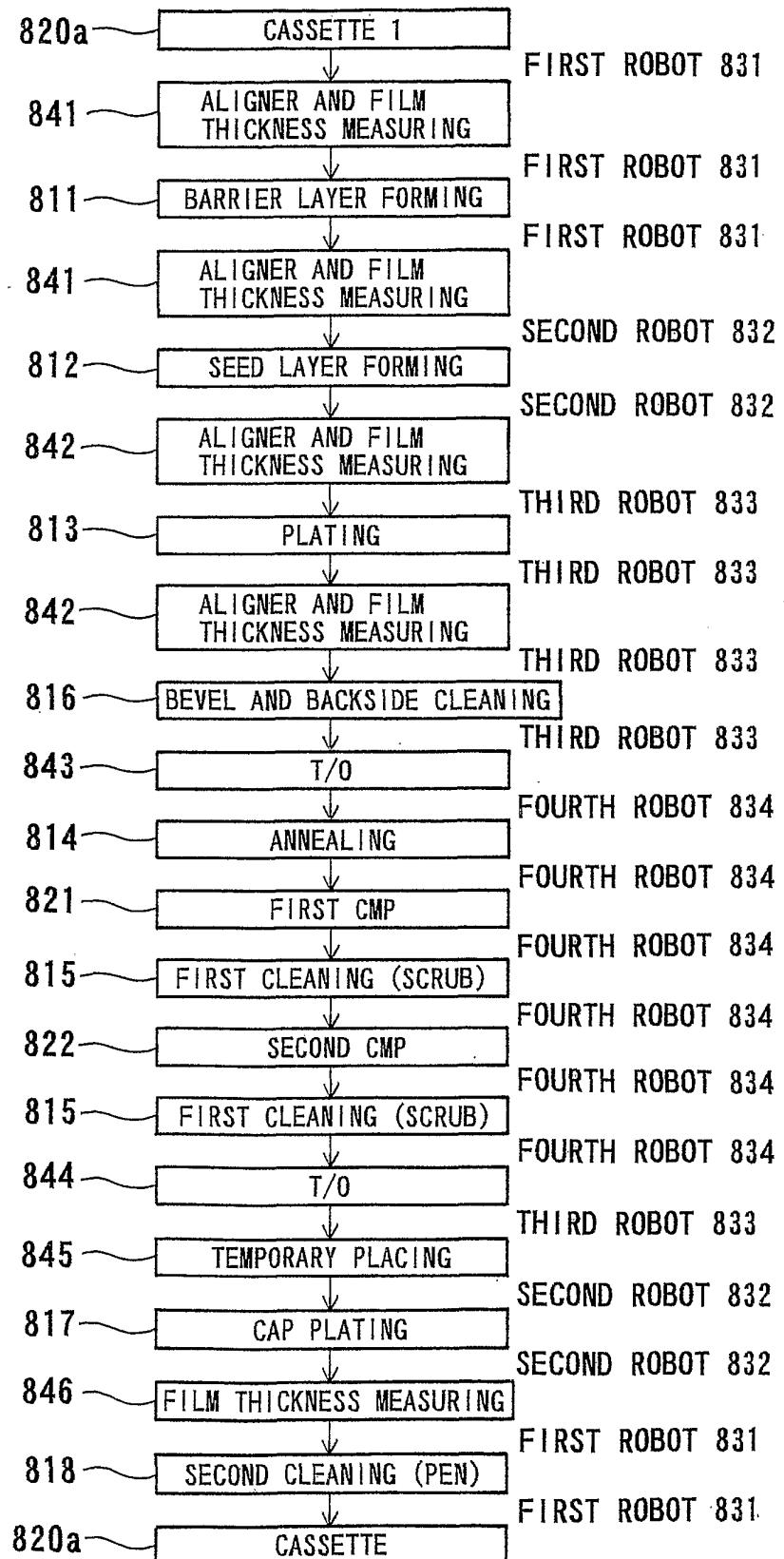
FIG. 30

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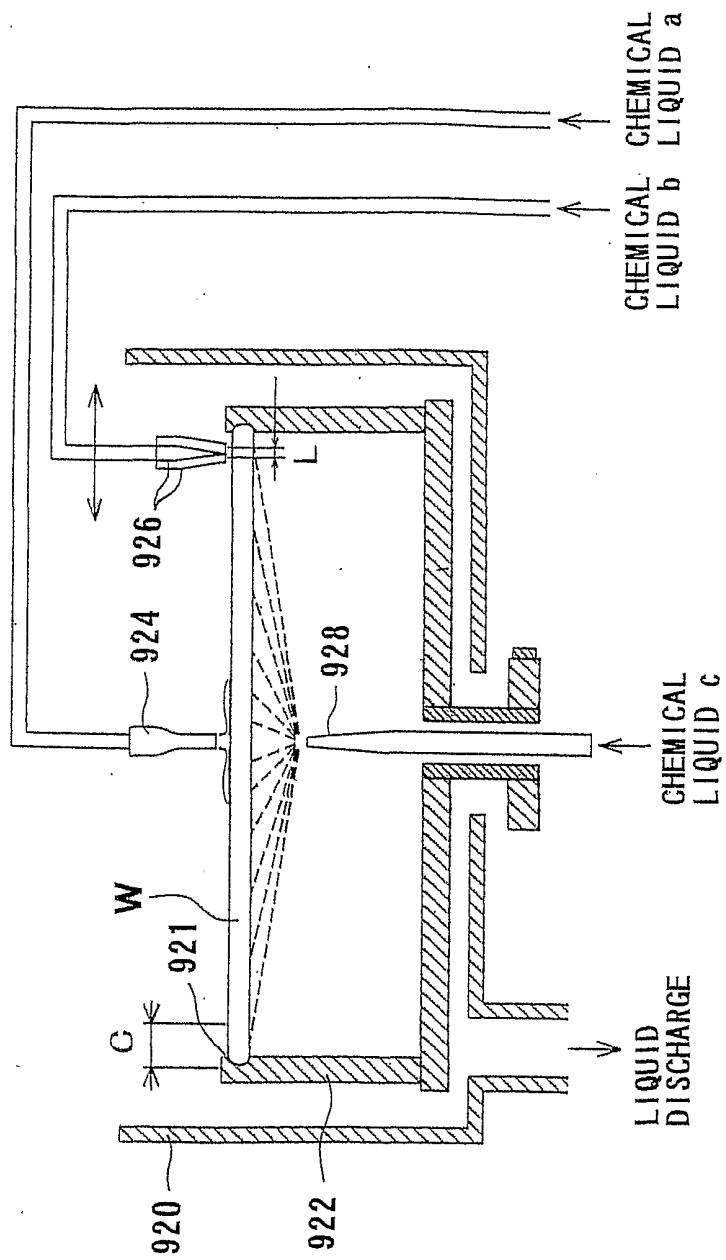
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FIG. 31



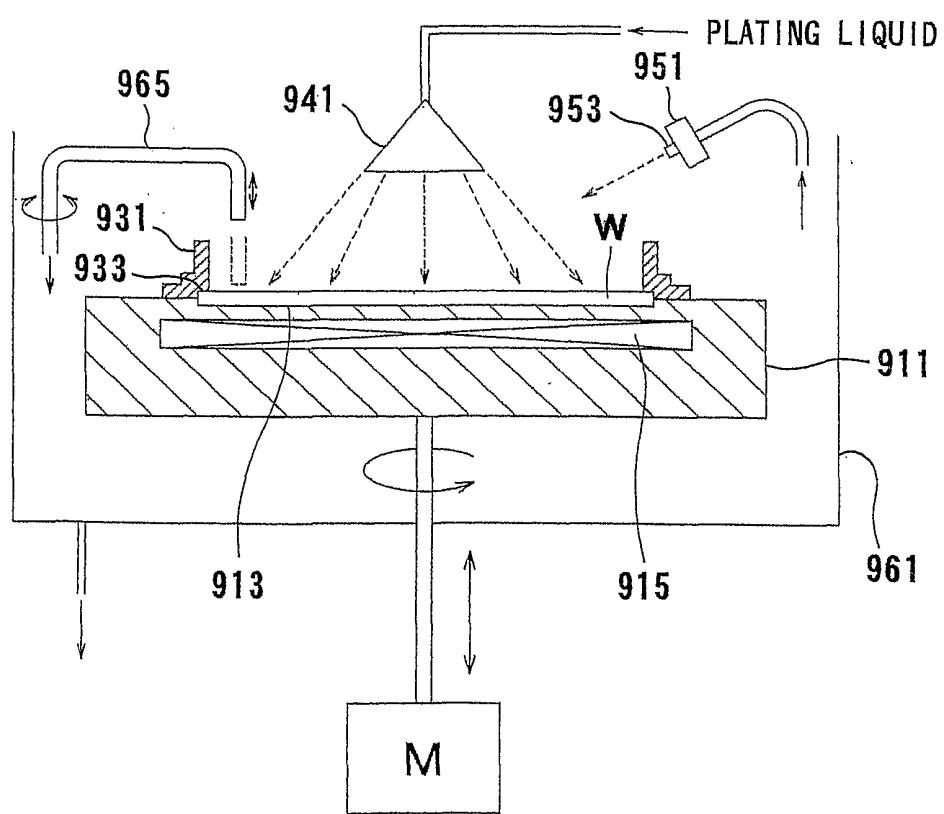
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FIG. 32



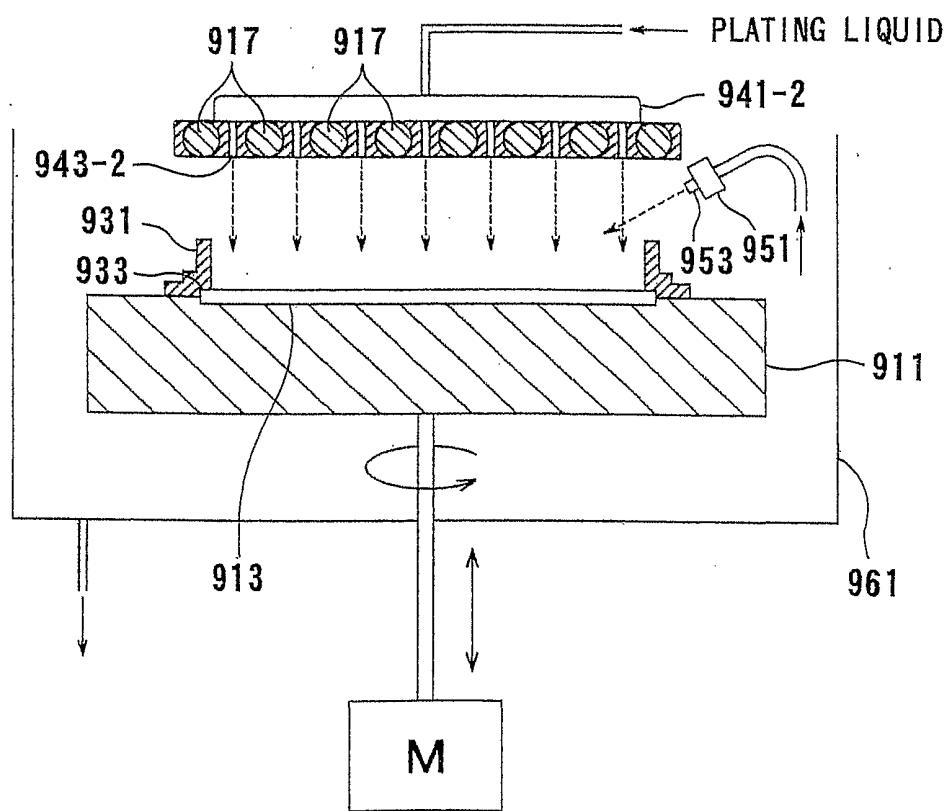
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FIG. 33



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FIG. 34



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FIG. 35

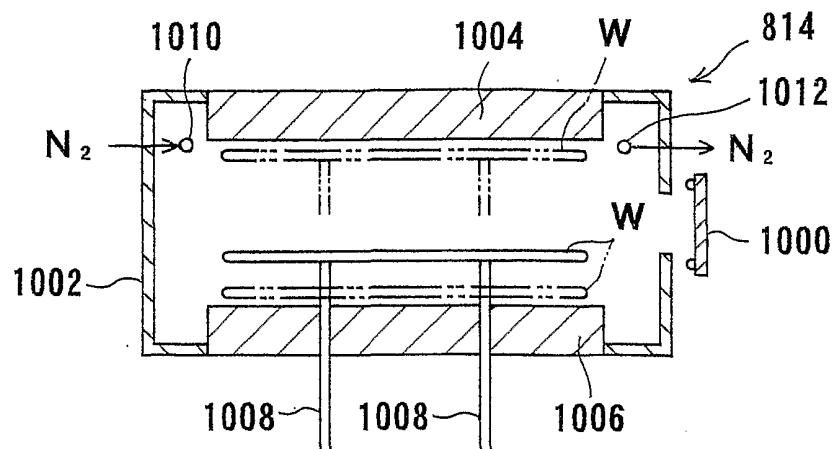
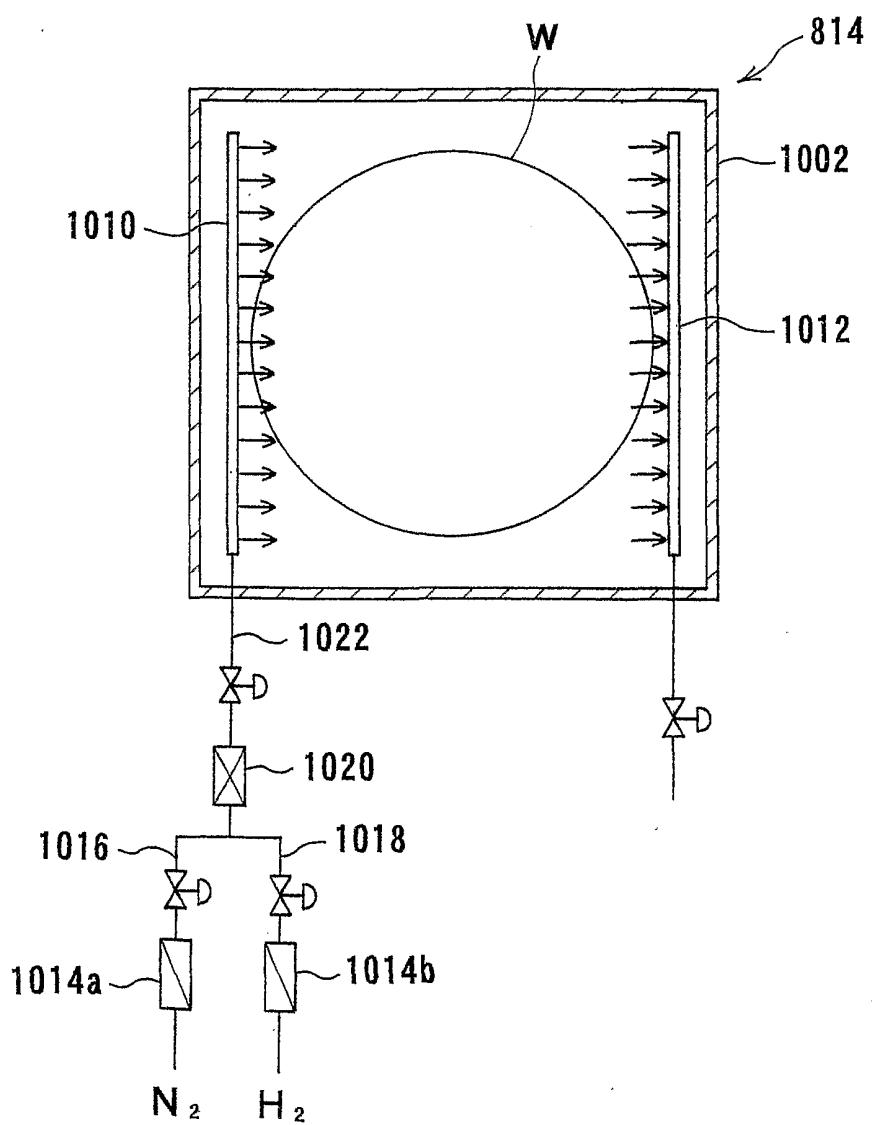


FIG. 36



INTERNATIONAL SEARCH REPORT

International Application No

PCT/JP 02/00235

A. CLASSIFICATION OF SUBJECT MATTER
 IPC 7 H01L21/00 C25D7/12

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC 7 H01L C25D

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

EPO-Internal, WPI Data, PAJ

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category [°]	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 5 092 975 A (YAMAMURA ET AL.) 3 March 1992 (1992-03-03) abstract; figures 2,12 column 3, line 28-45 column 4, line 24-48 column 6, line 24-52	1-3,6-9
Y	---	5
X	US 6 077 412 A (TING ET AL.) 20 June 2000 (2000-06-20) abstract; figures 5,6 column 7, line 28-45	1-4,6,7, 9
X	US 5 024 746 A (STIERMAN ET AL.) 18 June 1991 (1991-06-18) column 3, line 49-63	1-3,6,9
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Further documents are listed in the continuation of box C.

Patent family members are listed in annex.

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X document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

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Date of the actual completion of the international search

24 June 2002

Date of mailing of the international search report

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International Application No

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C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT

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A	---	1, 6
A	WO 00 32835 A (APPLIED MATERIALS) 8 June 2000 (2000-06-08) abstract; figure 5	1-3, 6, 7, 9
X, P	WO 01 45144 A (NUTOOL) 21 June 2001 (2001-06-21) page 4, line 28-34 page 7, line 14-32	1-3
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INTERNATIONAL SEARCH REPORT

Information on patent family members

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