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(54) **SIDE CAMERA FOR VEHICLE AND METHOD OF CONTROLLING THE SAME**

SEITENKAMERA FÜR EIN FAHRZEUG UND STEUERVERFAHREN DAFÜR

CAMÉRA LATÉRALE POUR VÉHICULE ET SON PROCÉDÉ DE COMMANDE

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Description

TECHNICAL FIELD

[0001] The present disclosure relates to a side camera for a vehicle and a method of controlling the same.

BACKGROUND

[0002] The content described in this section merely provides background information about the present disclosure and does not constitute the related art.

[0003] Side mirrors are installed at left-hand and right-hand sides of a vehicle in preparation for a situation in which it is necessary to monitor a rear side of the vehicle while driving. However, since the side mirrors protrude greatly from both sides of the vehicle, the side mirrors cause difficulties in parking or increase air resistance during driving to generate wind noise and reduce fuel efficiency of the vehicle. In addition, due to the structure of the side mirror, a blind spot, which is difficult to check with only a driver's field of view, occurs, and such a blind spot is one of the major causes of traffic accidents.

[0004] In order to solve such problems of existing side mirrors, there are conventional technologies for replacing the side mirror for a vehicle with a side camera. When a side mirror is replaced with a side camera, a free space at a side surface of a vehicle is increased during parking, and the side camera receives less wind resistance aerodynamically than the side mirror during driving of the vehicle so that fuel efficiency is improved. However, the conventional technologies are focused only on widening an angle of view of a rear side of the vehicle by replacing the existing side mirror with the camera, and thus, when the camera is disabled, it is difficult to secure a rear side field of view of the vehicle. A fatal accident may occur when a rear side field of view cannot be secured during driving of a vehicle. Therefore, it should be possible to secure a rear side field of view of a vehicle even when a camera is disabled. From US 2017/161566 A1) a side camera for a vehicle according to the preamble of claim 1 is derivable. US 2013/265431 A1 discloses a monitor system for a vehicle. WO 2016/178190 A1 describes a vehicle vision system.

SUMMARY

[0005] The present disclosure is directed to providing a rear side field of view to a user even when a blind-spot view camera or a blind-spot view monitor, which replaces a side mirror, is disabled.

[0006] In accordance with the present disclosure, there is provided a side camera for a vehicle, comprising: a main body disposed at a left-hand side and/or a right-hand side of the vehicle; a blind-spot view camera of which at least a portion is accommodated in the main body and which is configured to photograph a view in a lateral and rearward directions of the vehicle; a surround

view camera (SVC) of which at least a portion is accommodated in the main body and which is configured to photograph a view in a lateral direction of the vehicle; and a blind-spot view monitor disposed inside the vehicle to transmit an image captured by the blind-spot view camera, wherein, when the blind-spot view camera fails, an image transformation process is performed based on an image captured by the SVC and transmitted to the blind-spot view monitor, and when the blind-spot view monitor fails, an image captured by the blind-spot view camera is transmitted to another display device in the vehicle other than the blind-spot view monitor, wherein in the image transformation process, a portion of the image captured by the SVC, which corresponds to a photographable range of the blind-spot view camera, is set as a region of interest (ROI), and an undistortion process and a perspective transform process are performed upon the portion set as the ROI for correction thereof and a corrected image is transmitted to the blind-spot view monitor, the undistortion process and the perspective transform process being performed using a pre-stored look-up table (LUT) based on mounting positions of the blind-spot view camera and the SVC and a corresponding lens distortion ratio.

[0007] In accordance with the present disclosure, there is provided a method for controlling a side camera for a vehicle which is switched to an emergency system when a blind-spot view camera or a blind-spot view monitor fails, the method comprising: a failure detecting operation of detecting whether the side camera fails; a notifying operation of, notifying an operator that the side camera for a vehicle is switched to the emergency system when it is determined that the side camera for a vehicle fails; a failure determining operation of determining whether the blind-spot view monitor fails; and a correction outputting operation of, performing a connection to another display device other than the blind-spot view monitor in a vehicle when it is determined that the blind-spot view monitor fails, and transforming an image by using an image captured by a surround view camera (SVC) disposed in a main body of the side camera for a vehicle and then outputting a corrected image to the blind-spot view monitor when it is determined that the blind-spot view monitor is not failed, further comprising setting a portion of the image captured by the SVC, which corresponds to a photographable range of the blind-spot view camera, as a region of interest (ROI); and performing an undistortion operation and a perspective transform operation on the portion set as the ROI to correct and transmit the image to the blind-spot view monitor, the undistortion operation and the perspective transform operation being performed using a pre-stored look-up table (LUT) based on mounting positions of the blind-spot view camera (20) and the SVC (30) and a corresponding lens distortion ratio.

BRIEF DESCRIPTION OF THE DRAWINGS

[0008]

FIG. 1 is a perspective view of a vehicle on which a side camera for a vehicle is mounted according to one embodiment of the present disclosure.

FIG. 2 is a perspective view of the side camera for a vehicle according to one embodiment of the present disclosure.

FIG. 3 is a block diagram of the side camera for a vehicle according to one embodiment of the present disclosure.

FIG. 4 is a view for describing fields of view (FOVs) of a blind-spot view camera and a surround view camera (SVC) disposed in the side camera for a vehicle.

FIG. 5 shows images for describing a process of correcting an image captured by the SVC.

FIG. 6 is a flowchart of a method of controlling a side camera for a vehicle according to one embodiment of the present disclosure.

DETAILED DESCRIPTION

[0009] Some embodiments of the present disclosure will now be described in detail with reference to the illustrative drawings. It should be noted that, when reference numerals are added to the components in each drawing, the same components have the same numerals as possible, even if they are shown on different drawings. In the description of the present disclosure, a detailed description of a related known configuration or function is omitted when it is determined that the gist of the disclosure can be made.

[0010] In describing the components of the embodiments according to the present disclosure, reference numerals such as first, second, i), ii), a), and b) may be used. Such symbols are only for distinguishing the components from other components, and the nature or order of the components is not limited by the symbols. When a portion in the specification is referred to as "comprising" or "including" a component, it means that the component may further comprise other components rather than excluding other components unless explicitly stated to the contrary.

[0011] FIG. 1 is a perspective view of a vehicle on which a side camera for a vehicle according to one embodiment of the present disclosure is mounted. FIG. 2 is a perspective view of the side camera for a vehicle according to one embodiment of the present disclosure. FIG. 3 is a block diagram of the side camera for a vehicle according to one embodiment of the present disclosure. FIG. 4 is a view for describing fields of view (FOVs) of a blind-spot

view camera and a surround view camera (SVC) disposed in the side camera for a vehicle. FIG. 5 shows images for describing a process of correcting an image captured by the SVC.

[0012] Referring to FIGS. 1 to 3, the side camera for a vehicle includes all or some of a main body 10, a blind-spot view camera 20, an SVC 30, a blind-spot view monitor 40, and a controller 50.

[0013] The main body 10 includes a housing space therein and is installed at each of left-hand and right-hand sides of a vehicle. The main body 10 may be formed as a streamlined type to minimize air resistance during traveling.

[0014] At least a portion of the blind-spot view camera 20 is accommodated in the main body 10 and configured to photograph a view in a lateral direction behind the vehicle. For example, as shown in FIG. 2, the blind-spot view camera 20 may be accommodated inside the main body 10. In order for the blind-spot view camera 20 to photograph a view in a lateral direction behind the vehicle, a lens of the blind-spot view camera 20 may be provided to face the rear side of the vehicle.

[0015] FIG. 4 shows angles of view of the blind-spot view camera 20 and the SVC 30. A horizontal field of view (HFOV) A of the blind-spot view camera 20 is in a range of 50° to 80°, and a vertical field of view (VFOV) thereof is in a range of 20° to 40°. Since the blind-spot view camera 20 is used to replace an existing side mirror, a rear side range, which is checkable by a driver during traveling, is increased about two-fold or more.

[0016] The SVC 30 is disposed in the main body 10 and designed to photograph an entire range of both views in a lateral direction from the vehicle. The SVC 30 may be disposed in the main body 10 to face a direction perpendicular to a longitudinal direction of the vehicle. Here, an HFOV B of the SVC 30 is in a range of 180° to 200°, and a VFOV thereof is in a range of 120° to 160°. The SVC 30 may photograph an entire range of a view in a lateral direction from the vehicle using a wide FOV. The SVC 30 is generally used to detect obstacles when parking a vehicle or traveling along a narrow road.

[0017] The blind-spot view monitor 40 is a display device which displays information about an image captured by the blind-spot view camera 20. That is, the blind-spot view monitor 40 and the blind-spot view camera 20 replace existing side mirrors for a vehicle. One blind-spot view monitor 40 is disposed at each of front left-hand and right-hand sides inside the vehicle to display an image captured by the blind-spot view camera 20 disposed at each of both sides of the vehicle.

[0018] The controller 50 is disposed inside the vehicle and is also referred to as an electronic control unit (ECU). The controller 50 includes a hardware processor and a memory, and commands for executing the controller 50 and a look-up table (LUT) are stored in the memory. However, the present disclosure is not limited thereto, and all configurations for controlling overall operations of the vehicle may be included. The controller 50 performs

control to process an image captured by the blind-spot view camera 20 and transmit a screen to the blind-spot view monitor 40 and detects whether one or more of the blind-spot view camera 20 and the blind-spot view monitor 40 have failed. When a failure occurs in one or more of the blind-spot view camera 20 and the blind-spot view monitor 40, the controller 50 performs backup control using another display device other than the blind-spot monitor in the vehicle or the SVC 30 so as to secure a rear side field of view of the vehicle.

[0019] The controller 50 may include a failure detector 51 and an image processor 52. The failure detector 51 periodically detects a failure state of the blind-spot view camera 20 and the blind-spot view monitor 40. While an ignition of the vehicle is turned on, the failure detector 51 checks whether the blind-spot view camera 20 and the blind-spot view monitor 40 have failed at preset time intervals. When the failure detector 51 detects that one or more of the blind-spot view camera 20 and the blind-spot view monitor 40 have failed, the failure detector 51 transmits a failure detection signal to notify the image processor 52 of the failure. In addition, when the failure detector 51 detects a failure, a signal is transmitted to each device to notify a driver that the side camera for a vehicle is switched to an emergency system using a display device or a speaker device in the vehicle. The switch to the emergency system is performed by the image processor 52 to be described below. Although the blind-spot view monitor 40 is illustrated in FIG. 1 as being separately disposed at each of left-hand and right-hand sides in the vehicle, the present disclosure is not limited thereto, and the blind-spot view monitor 40 may be disposed anywhere as long as the driver can view the blind-spot view monitor 40 without any difficulty during driving.

[0020] The image processor 52 normally performs a calculation to process an image based on an image signal captured by the blind-spot view camera 20 and transmit a screen to the blind-spot view monitor 40. When the image processor 52 receives the failure detection signal of the blind-spot view camera 20 or the blind-spot view monitor 40 from the failure detector 51, the image processor 52 performs image processing in response to the failure detection signal.

[0021] When it is determined that the blind-spot view monitor 40 has failed, the image processor 52 transmits a screen of an image captured by the blind-spot view camera 20 to another display device other than the blind-spot view monitor 40 within a driver's field of view instead of the blind-spot view monitor 40.

[0022] When it is determined that the blind-spot view camera 20 has failed, the image processor 52 receives image information from the SVC 30 rather than the blind-spot view camera 20, extracts only information about a rear side from the image information of the SVC 30, and transforms and transmits the extracted information to the blind-spot view monitor 40. The SVC 30 is a wide angle camera, and thus, distortion of an image thereof occurs.

In order for the driver to actually view a rear side of the vehicle with the blind-spot view camera 20, an undistortion process and a perspective transform process are required.

[0023] Referring to FIG. 5, a difference between an image of the blind-spot view camera 20 and an image of the SVC 30 can be confirmed. Part (a) of FIG. 5 is an image acquired by photographing a view in a lateral direction behind the vehicle with the blind-spot view camera 20, and part (b) of FIG. 5 is an image acquired by photographing an entire range of a view in a lateral direction from the vehicle with the SVC 30. Referring to part (b) of FIG. 5, the image is distorted so as to cover the entire range of the view in the lateral direction, and a rear side is a portion of the distorted image. When the distorted image is transmitted to a screen without any change, the driver cannot easily grasp information about the rear side during driving. Therefore, a rear side portion of the image captured by the SVC 30 is set as a region of interest (ROI), and an undistortion process and a perspective transform process are required for the set portion. After the image processor 52 completes such an image transformation process, an image is transformed as shown in FIG. 5. The image processor 52 transmits the transformed image to the blind-spot view monitor 40 to allow the driver to view the rear side of the vehicle even when the blind-spot view camera 20 has failed, thereby allowing the driver to avoid the risk of an accident. When the image processor 52 performs the undistortion process and the perspective transform process, a volume of operation processing is increased, and thus, a high-performance hardware processor is required. Therefore, the image processor 52 may be designed such that the preset LUT is stored in the memory of the controller 50 to transform an image based on the LUT. The LUT differs according to a mounting position of the blind-spot view camera 20 and the SVC 30 installed on the vehicle and a lens distortion ratio, and thus, a separate LUT should be set for each vehicle type.

[0024] FIG. 6 is a flowchart of a method of controlling a side camera for a vehicle according to one embodiment of the present disclosure.

[0025] When an ignition of the vehicle is turned on, a controller 50 periodically detects whether a CMS has failed (S61). Here, the CMS is an abbreviation of camera monitoring system and refers to a system designed such that a driver may use a blind-spot view camera 20 and a blind-spot view monitor 40 to monitor a situation of a rear side of a vehicle.

[0026] When the failure of the CMS is not detected, the controller 50 does not proceed to a subsequent operation and periodically repeats operation S61 to detect whether the CMS has failed.

[0027] When the failure of the CMS is detected, the controller 50 first notifies the driver that a side camera for a vehicle is switched to an emergency system (S62). The switch to the emergency system may be visually or audibly notified using a display device or a speaker

device within a driver's field of view in the vehicle. Operation S62 is not an operation that is necessarily performed after operation S61 and may be performed after operation S63 to be described below.

[0028] After the driver is notified of the switch to the emergency system, the controller 50 determines whether the blind-spot view monitor 40 has failed (S63). When the controller 50 determines that the blind-spot view monitor 40 has failed, a rear side image of the vehicle is transmitted to another display device other than the blind-spot view monitor in the vehicle rather than the blind-spot view monitor (S64). Here, another display device other than the blind-spot view monitor in the vehicle is a display device disposed within a driver's field of view. For example, another display device other than the blind-spot view monitor in the vehicle may be a digital cluster or a navigation display device disposed in a center fascia.

[0029] When the controller 50 determines that the blind-spot view monitor 40 has not failed, the controller 50 determines that a failure has occurred in the same place as the blind-spot view camera 20 rather than the blind-spot view monitor 40, corrects an image using an image of the SVC 30 rather than an image captured by the blind-spot view camera 20, and then, performs replacement to display the corrected image on the blind-spot view monitor 40 (S65). Since an FOV of the SVC 30 is greater than an FOV of the blind-spot view camera 20 and distortion occurs in an image captured by the SVC 30, a correction process should be performed. As described above, in an image captured by the SVC 30, a portion related to a rear side of the vehicle is set as an ROI, and the image captured by the SVC 30 is subjected to an undistortion process and a perspective transform process and transformed to look like an image captured by the blind-spot view camera 20. Since many calculations are required for the undistortion process and the perspective transform process, in order to reduce the cost of a hardware processor, an LUT may be stored in a memory to correct the image captured by the SVC 30. Since transformation coordinates are calculated in advance in the LUT, an image can be corrected through coordinate transformation only with information of the LUT without calculation.

[0030] After the setting for securing a driver's rear side field of view of the vehicle using operation S64 or S65 is completed, the present algorithm is ended.

[0031] Although operations are illustrated in FIG. 6 as being sequentially performed, this is merely an exemplary description of the technical idea of one embodiment of the present disclosure. In other words, those skilled in the art to which one embodiment of the present disclosure belongs may appreciate that various modifications and changes can be made without departing from essential characteristics of one embodiment of the present disclosure, that is, the sequence illustrated in FIG. 6 can be changed and one or more operations of the operations can be performed in parallel. Thus, FIG. 6 is not limited to the temporal order.

[0032] As described above, according to the present embodiment, in a side camera for a vehicle and a method of controlling the same, when a blind-spot view camera has failed, an image captured by an SVC is transformed and transmitted to a blind-spot view monitor, or when the blind-spot view monitor has failed, an image captured by the blind-spot view camera is transmitted to another display device other than the blind-spot view monitor in the vehicle, thereby safely securing a driver's a rear side field of view during driving.

[0033] Various embodiments of systems and techniques described herein can be realized with digital electronic circuits, integrated circuits, field programmable gate arrays (FPGAs), application specific integrated circuits (ASICs), computer hardware, firmware, software, and/or combinations thereof. The various embodiments can include implementation with one or more computer programs that are executable on a programmable system. The programmable system includes at least one programmable processor, which may be a special purpose processor or a general purpose processor, coupled to receive and transmit data and instructions from and to a storage system, at least one input device, and at least one output device. Computer programs (also known as programs, software, software applications, or code) include instructions for a programmable processor and are stored in a "computer-readable recording medium."

[0034] The computer-readable recording medium may include all types of storage devices on which computer-readable data can be stored. The computer-readable recording medium may be a non-volatile or non-transitory medium such as a read-only memory (ROM), a random access memory (RAM), a compact disc ROM (CD-ROM), magnetic tape, a floppy disk, or an optical data storage device. In addition, the computer-readable recording medium may further include a transitory medium such as a data transmission medium. Furthermore, the computer-readable recording medium may be distributed over computer systems connected through a network, and computer-readable program code can be stored and executed in a distributive manner.

[0035] Various embodiments of systems and techniques described herein can be realized by a programmable computer. Here, the computer includes a programmable processor, a data storage system (including a volatile memory, a non-volatile memory, another type of storage system, or a combination thereof), and at least one communication interface. For example, the programmable computer may be one of a server, a network device, a set-top box, an embedded device, a computer expansion module, a personal computer, a laptop, a personal data assistant (PDA), a cloud computing system, and a mobile device.

Claims

1. A side camera for a vehicle, comprising:

a main body (10) disposed at a left-hand side and/or a right-hand side of the vehicle;
 a blind-spot view camera (20) of which at least a portion is accommodated in the main body (10) and being configured to photograph a view in a lateral and rearward directions of the vehicle;
 a surround view camera, SVC (30), of which at least a portion is accommodated in the main body (10) and being configured to photograph a view in a lateral direction of the vehicle; and
 a blind-spot view monitor (40) disposed inside the vehicle to transmit an image captured by the blind-spot view camera (20),
 wherein, when the blind-spot view camera (20) fails, an image transformation process is performed based on an image captured by the SVC (30) and transmitted to the blind-spot view monitor (40), and
 when the blind-spot view monitor (40) fails, an image captured by the blind-spot view camera (20) is transmitted to another display device in the vehicle other than the blind-spot view monitor (40),
 wherein in the image transformation process, a portion of the image captured by the SVC (30), which corresponds to a photographable range of the blind-spot view camera (20), is set as a region of interest, ROI, and an undistortion process and a perspective transform process are performed upon the portion set as the ROI for correction thereof and a corrected image is transmitted to the blind-spot view monitor (40),

characterized in that the undistortion process and the perspective transform process being performed using a pre-stored look-up table, LUT, based on mounting positions of the blind-spot view camera (20) and the SVC (30) and a corresponding lens distortion ratio..

2. The side camera of claim 1, further comprising:

a failure detector (51) that periodically detects a failure state of the blind-spot view camera (20) and the blind-spot view monitor (40); and
 an image processor (52) that performs a calculation to process an image based on an image signal captured by the blind-spot view camera (20) and transmit a processed image to the blind-spot view monitor (40).

3. The side camera of claim 1, wherein, when a fail in one or more of the blind-spot view camera (20) and the blind-spot view monitor (40) is detected, an operator of the vehicle is notified that the side camera is switched to an emergency system through at least one of a display device and a speaker device in the vehicle.

4. The side camera of claim 1, wherein a horizontal field of view, HFOV, of the blind-spot view camera (20) is in a range of 50° to 80°, and an HFOV of the SVC is in a range of 180° to 200°.

5. The side camera of claim 1, wherein a vertical field of view, VFOV, of the blind-spot view camera (20) is in a range of 20° to 40°, and a VFOV of the SVC is in a range of 120° to 160°.

6. The side camera of claim 1, wherein said another display device other than the blind-spot view monitor (40) is at least one of a digital cluster and a navigation display device.

7. A method of controlling a side camera for a vehicle which is switched to an emergency system when a blind-spot view camera (20) or a blind-spot view monitor (40) fails, the method comprising:

a failure detecting operation of detecting whether the side camera fails;

a notifying operation of notifying an operator that the side camera for a vehicle is switched to the emergency system when it is determined that the side camera for a vehicle fails;

a failure determining operation of determining whether the blind-spot view monitor (40) fails; and

a correction outputting operation of performing a connection to another display device other than the blind-spot view monitor (40) in a vehicle when it is determined that the blind-spot view monitor (40) fails, and transforming an image by using an image captured by a surround view camera, SVC (30), disposed in a main body (10) of the side camera for a vehicle and then outputting a corrected image to the blind-spot view monitor (40) when it is determined that the blind-spot view monitor (40) is not failed, wherein the correcting of the image includes:

setting a portion of the image captured by the SVC (30), which corresponds to a photographable range of the blind-spot view camera, as a region of interest, ROI; and

performing an undistortion operation and a perspective transform operation on the portion set as the ROI to correct and transmit the image to the blind-spot view monitor (40), **characterized in that**

the undistortion operation and the perspective transform operation being performed using a pre-stored look-up table, LUT, based on mounting positions of the blind-spot view camera (20) and the SVC (30) and a corresponding lens distortion ratio.

8. The method of claim 7, wherein the notifying operation includes visually and audibly notifying the operator of the vehicle that the side camera for a vehicle is switched to the emergency system using at least one of a display device and a speaker device in the vehicle.

Patentansprüche

1. Seitenkamera für ein Fahrzeug, welche aufweist:

einen Hauptkörper (10), der auf einer linken oder einer rechten Seite des Fahrzeugs angeordnet ist;
 eine Totwinkelkamera (20), von welcher zumindest ein Teil in dem Hauptkörper (10) aufgenommen ist und welche dazu ausgebildet ist, eine Sicht in seitlicher und rückwärtiger Richtung des Fahrzeugs zu fotografieren;
 eine Rundumsichtkamera, SVC (30), von welcher zumindest ein Bereich in dem Hauptkörper (10) aufgenommen ist und welche dazu ausgebildet ist, eine Sicht in seitlicher Richtung des Fahrzeugs zu fotografieren; und
 einen Totwinkelmonitor (40), der in dem Fahrzeug angeordnet ist, um ein von der Totwinkelkamera (20) aufgenommenes Bild zu übertragen, wobei, wenn die Totwinkelkamera (20) ausfällt, ein Bildtransformationsprozess basierend auf einem Bild durchgeführt wird, das von der SVC (30) aufgenommen wurde und an den Totwinkelmonitor (40) übertragen wird, und wenn der Totwinkelmonitor (40) ausfällt, ein von der Totwinkelkamera (20) aufgenommenes Bild an eine andere, von dem Totwinkelmonitor (40) verschiedene Anzeigevorrichtung in dem Fahrzeug übertragen wird, wobei bei dem Bildtransformationsprozess ein Teil des von der SVC (30) aufgenommenen Bilds, welcher einem fotografierbaren Bereich der Totwinkelkamera (20) entspricht, als ein interessierender Bereich, ROI, vorgegeben wird, und ein Verzeichnungskorrekturprozess und ein Perspektiventransformationsprozess an dem als ROI vorgegebenen Bereich zur Korrektur desselben durchgeführt werden, und ein korrigiertes Bild an den Totwinkelmonitor (40) übertragen wird, **dadurch gekennzeichnet, dass** der Verzeichnungskorrekturprozess und ein Perspektiventransformationsprozess unter Verwendung einer vorab gespeicherten Look-up-Tabelle, LUT, basierend auf Montagepositionen der Totwinkelkamera (20) und der SVC (30) und einem entsprechenden Linsenverzeichnungsverhältnis durchgeführt werden.

2. Seitenkamera nach Anspruch 1, ferner mit:

einem Ausfalldetektor (51), der periodisch einen Ausfallzustand der Totwinkelkamera (20) und des Totwinkelmonitors (40) erkennt; und
 einem Bildprozessor (52), der eine Berechnung durchführt, um ein Bild basierend auf einem von der Totwinkelkamera (20) aufgenommenen Bildsignal zu berechnen und ein verarbeitetes Bild an den Totwinkelmonitor (40) zu übertragen.

3. Seitenkamera nach Anspruch 1, bei welcher, wenn ein Ausfall der Totwinkelkamera (20) und/oder der Totwinkelmonitor (40) erkannt wird, ein Bediener des Fahrzeugs durch eine Anzeigevorrichtung und/oder eine Lautsprechervorrichtung in dem Fahrzeug informiert wird, dass die Seitenkamera auf ein Not-System umgeschaltet ist.

4. Seitenkamera nach Anspruch 1, bei welcher ein horizontales Sichtfeld, HFOV, der Totwinkelkamera (20) im Bereich von 50° bis 80° liegt, und ein HFOV der SVC in einem Bereich von 180° bis 200° liegt.

5. Seitenkamera nach Anspruch 1, bei welcher ein vertikales Sichtfeld, VFOV, der Totwinkelkamera (20) in einem Bereich von 20° bis 40° liegt, und ein VFOV der SVC in einem Bereich von 120° bis 160° liegt.

6. Seitenkamera nach Anspruch 1, bei welcher die andere, von dem Totwinkelmonitor (40) verschiedene Anzeigevorrichtung eine Digital-Cluster- und/oder eine Navigationsanzeigevorrichtung ist.

7. Verfahren zum Steuern einer Seitenkamera für ein Fahrzeug, welche auf ein Not-System umgeschaltet wird, wenn eine Totwinkelkamera (20) oder ein Totwinkelmonitor (40) ausfällt, wobei das Verfahren die folgenden Schritte aufweist:

eine Ausfallerkennungsoperation zum Erkennen, ob die Seitenkamera ausgefallen ist;
 eine Mitteilungsoperation zum Informieren eines Betreibers, dass die Seitenkamera für ein Fahrzeug auf das Notfallsystem umgeschaltet wird, wenn festgestellt wird, dass die Seitenkamera für ein Fahrzeug ausgefallen ist;
 eine Ausfallerkennungsoperation zum Erkennen, ob der Totwinkelmonitor (40) ausgefallen ist; und
 eine Korrekturausgabeoperation zum Durchführen einer Verbindung mit einer anderen, von dem Totwinkelmonitor (40) verschiedenen Anzeigevorrichtung in einem Fahrzeug, wenn festgestellt wird, dass der Totwinkelmonitor (40) ausgefallen ist, und zum Transformieren eines

Bildes unter Verwendung eines Bildes, welches von einer in einem Hauptkörper (10) der Seitenkamera für ein Fahrzeug angeordneten Rundumkamera, SVC (30), aufgenommen wurde, und zum anschließenden Ausgeben eines korrigierten Bilds an den Totwinkelmonitor (40), wenn festgestellt wird, dass der Totwinkelmonitor (40) nicht ausgefallen ist, wobei das Korrigieren des Bildes die folgenden Schritte aufweist:

Vorgeben eines Bereichs des von der SVC (30) aufgenommenen Bildes, welcher einem fotografierbaren Bereich der Totwinkelkamera entspricht, als einen interessierenden Bereich, ROI; und
Durchführen einer Verzeichnungskorrekturoperation und einer Perspektivkorrekturoperation an dem als ROI vorgegebenen Bereich, um das Bild zu korrigieren und an den Totwinkelmonitor (40) zu übertragen, **dadurch gekennzeichnet, dass** die Verzeichnungskorrekturoperation und die Perspektivkorrekturoperation unter Verwendung einer vorab gespeicherten Look-up-Tabelle, LUT, basierend auf Montagepositionen der Totwinkelkamera (20) und der SVC (30) und einem entsprechenden Linsenverzeichnungsverhältnis durchgeführt werden.

8. Verfahren nach Anspruch 7, bei welchem die Mitteilungsoption aufweist, den Bediener des Fahrzeugs unter Verwendung einer Anzeigevorrichtung und/oder einer Lautsprechervorrichtung in dem Fahrzeug darüber zu informieren, dass die Seitenkamera für ein Fahrzeug auf das Notsystem umgeschaltet wurde.

Revendications

1. Kamera laterale pour un véhicule, comprenant :

un corps principal (10) disposé sur le côté gauche et/ou le côté droit du véhicule ;
une caméra d'angle mort (20) dont au moins une partie est logée dans le corps principal (10) et qui est configurée pour photographier une vue dans les directions latérale et arrière du véhicule ;
une caméra à vision panoramique, SVC (30), dont au moins une partie est logée dans le corps principal (10) et qui est configurée pour photographier une vue dans une direction latérale du véhicule ; et
un moniteur d'angle mort (40) disposé à l'intérieur du véhicule pour transmettre une image capturée par la caméra d'angle mort (20),

dans lequel, lorsque la caméra d'angle mort (20) est défaillante, un processus de transformation d'image est exécuté sur la base d'une image capturée par la SVC (30) et transmise au moniteur d'angle mort (40), et

lorsque le moniteur d'angle mort (40) est défaillant, une image capturée par la caméra d'angle mort (20) est transmise à un autre dispositif d'affichage dans le véhicule que le moniteur d'angle mort (40),

dans lequel, dans le cadre du processus de transformation d'image, une partie de l'image capturée par la SVC (30), qui correspond à une plage photographiable de la caméra d'angle mort (20), est définie comme une région d'intérêt, ROI, et un processus de déformation et un processus de transformation de perspective sont exécutés sur la partie définie comme ROI pour la corriger et une image corrigée est transmise au moniteur d'angle mort (40), **caractérisé en ce que** le processus de déformation et le processus de transformation de la perspective sont exécutés à l'aide d'une table de recherche préenregistrée, LUT, en fonction des positions de montage de la caméra d'angle mort (20) et de la SVC (30) et d'un rapport de distorsion de lentille correspondant.

2. Kamera laterale selon la revendication 1, comprenant en outre :

un détecteur de défaillance (51) qui détecte périodiquement un état de défaillance de la caméra d'angle mort (20) et du moniteur d'angle mort (40) ; et

un processeur d'image (52) qui effectue un calcul pour traiter une image en fonction d'un signal d'image capturé par la caméra d'angle mort (20) et transmet une image traitée au moniteur d'angle mort (40).

3. Kamera laterale selon la revendication 1, dans laquelle, lorsqu'une défaillance est détectée dans une ou plusieurs caméras d'angle mort (20) et dans le moniteur d'angle mort (40), un opérateur du véhicule est informé que la caméra laterale est commutée vers un système d'urgence par l'intermédiaire d'au moins un dispositif d'affichage et d'un haut-parleur dans le véhicule.

4. Kamera laterale selon la revendication 1, dans laquelle le champ de vision horizontal (HFOV) de la caméra d'angle mort (20) est compris entre 50° et 80°, et un HFOV de la SVC est compris entre 180° et 200°.

5. Kamera laterale selon la revendication 1, dans laquelle le champ de vision vertical (VFOV) de la

caméra d'angle mort (20) est compris entre 20° et 40°, et
un VFOV de la SVC est compris entre 120° et 160°.

6. Caméra latérale selon la revendication 1, dans laquelle le dispositif d'affichage autre que le moniteur d'angle mort (40) est au moins l'un parmi un groupe numérique et un dispositif d'affichage de navigation.
7. Procédé de commande d'une caméra latérale pour un véhicule qui est commutée sur un système d'urgence lorsqu'une caméra d'angle mort (20) ou un moniteur d'angle mort (40) est défaillant(e), le procédé comprenant :

une opération de détection des défaillances consistant à déterminer si la caméra latérale est défaillante ;
une opération de notification consistant à informer un opérateur que la caméra latérale d'un véhicule est commutée sur le système d'urgence lorsqu'il est déterminé que la caméra latérale d'un véhicule est défaillante ;
une opération de détermination de la défaillance consistant à déterminer si le moniteur d'angle mort (40) est défaillant ; et
une opération de sortie de correction consistant à effectuer une connexion à un autre dispositif d'affichage que le moniteur d'angle mort (40) dans un véhicule lorsqu'il est déterminé que le moniteur d'angle mort (40) est défaillant, et à transformer une image en utilisant une image capturée par une caméra à vision panoramique, SVC (30), disposée dans un corps principal (10) de la caméra latérale d'un véhicule, puis à sortir une image corrigée vers le moniteur d'angle mort (40) lorsqu'il est déterminé que le moniteur d'angle mort (40) n'est pas défaillant, dans lequel la correction de l'image comprend :

la définition d'une partie de l'image capturée par la SVC (30), qui correspond à une zone photographiable de la caméra d'angle mort, comme une région d'intérêt, ROI ; et
l'exécution d'une opération de déformation et d'une opération de transformation de la perspective sur la partie définie comme ROI pour corriger et transmettre l'image au moniteur d'angle mort (40), **caractérisé en ce que** l'opération de déformation et l'opération de transformation de la perspective sont exécutées à l'aide d'une table de recherche préenregistrée, LUT, en fonction des positions de montage de la caméra d'angle mort (20) et de la SVC (30) et d'un rapport de distorsion de lentille correspondant.

8. Procédé selon la revendication 7, dans lequel l'opération de notification comporte la notification visuelle et sonore à l'opérateur du véhicule que la caméra latérale d'un véhicule est commutée sur le système d'urgence à l'aide d'au moins un dispositif d'affichage et d'un haut-parleur dans le véhicule.

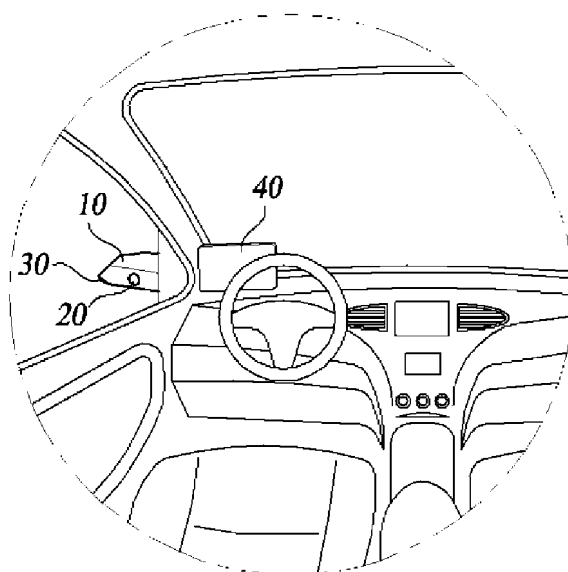


FIG. 1

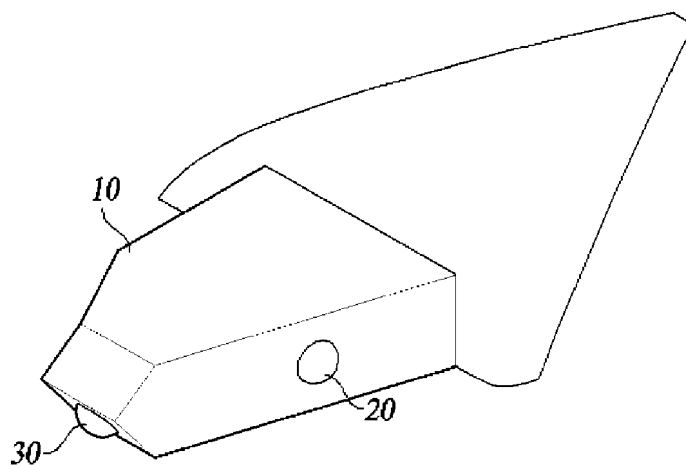


FIG. 2

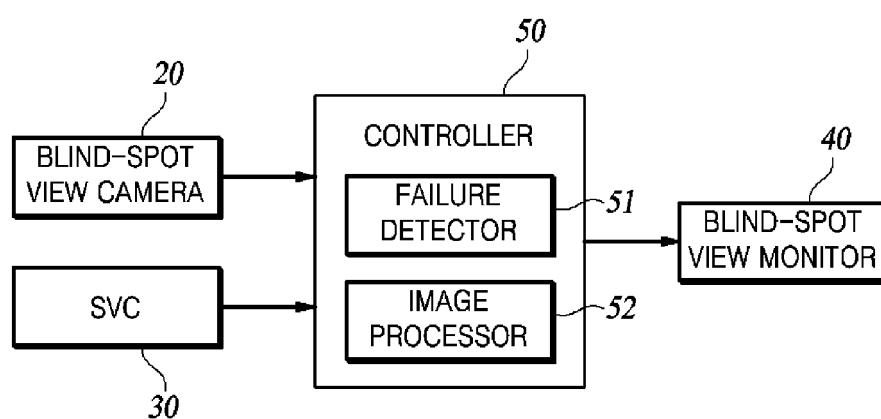


FIG. 3

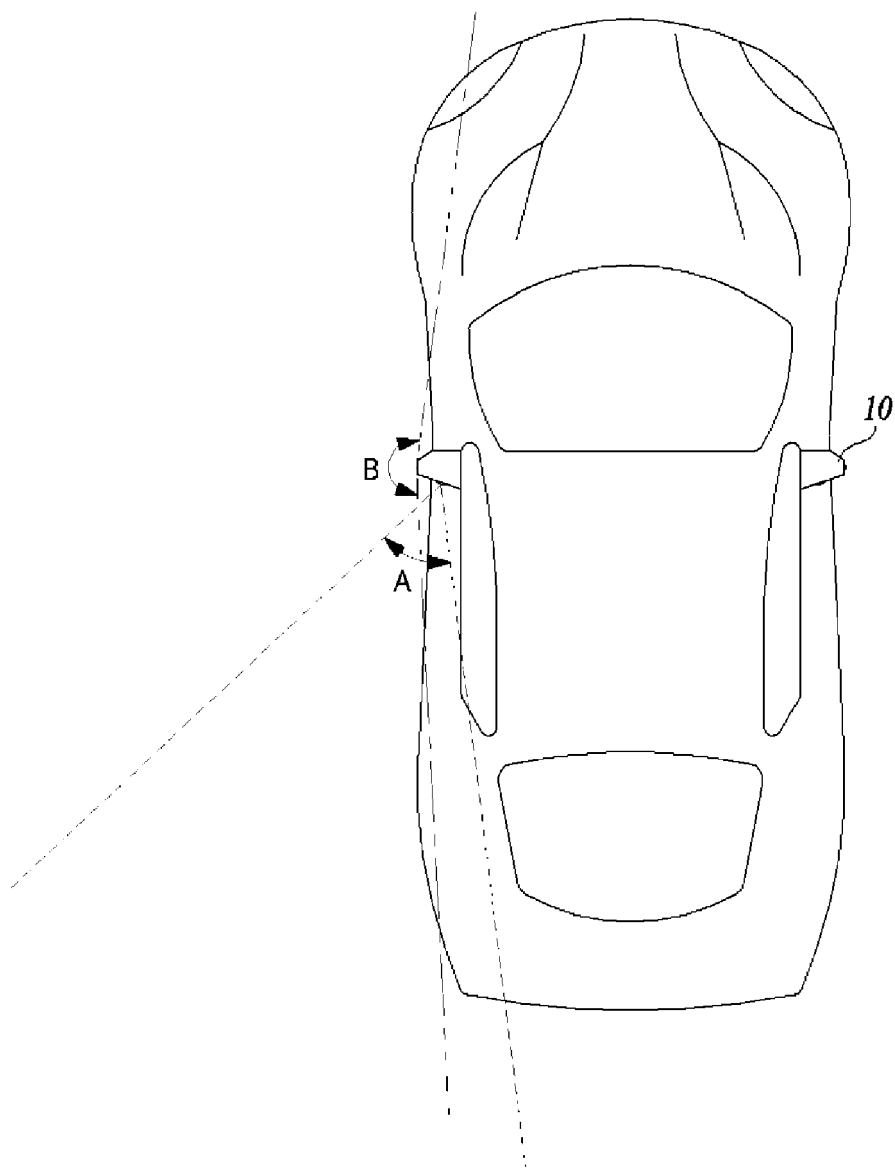
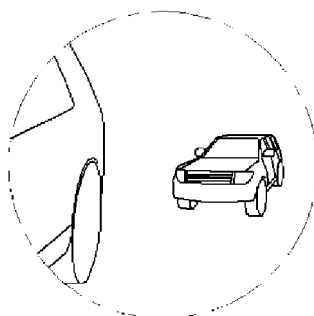
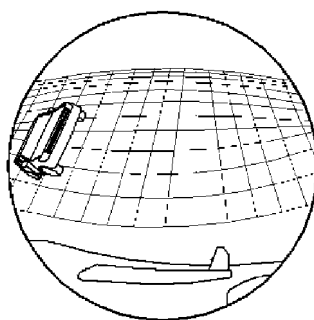


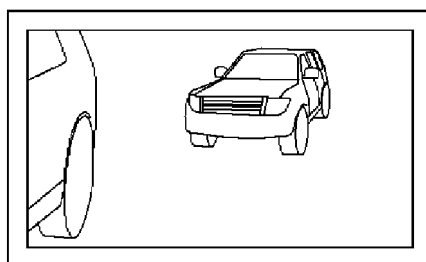
FIG. 4



(a)

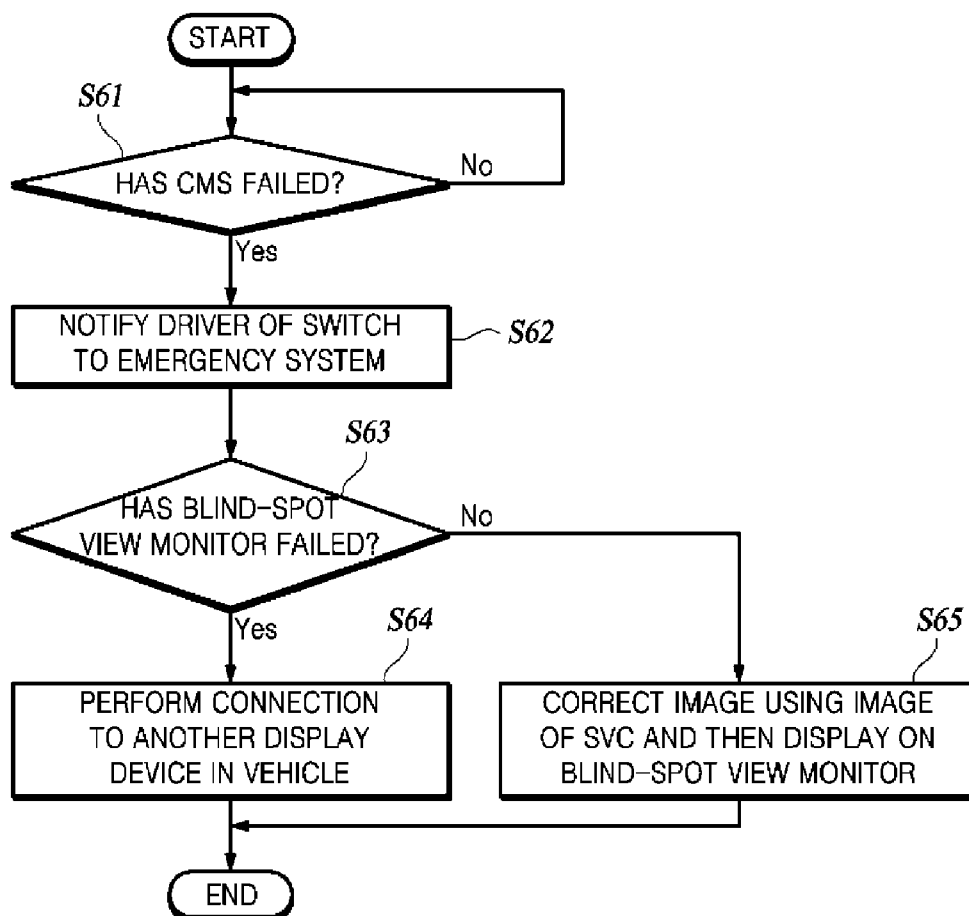


(b)



(c)

FIG. 5

**FIG. 6**

REFERENCES CITED IN THE DESCRIPTION

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