

(19) World Intellectual Property Organization  
International Bureau



(43) International Publication Date  
11 April 2002 (11.04.2002)

PCT

(10) International Publication Number  
WO 02/28592 A1

- (51) International Patent Classification<sup>7</sup>: B23Q 1/01
- (21) International Application Number: PCT/IT01/00067
- (22) International Filing Date: 15 February 2001 (15.02.2001)
- (25) Filing Language: Italian
- (26) Publication Language: English
- (30) Priority Data:  
PCT/IT00/00394 3 October 2000 (03.10.2000) IB
- (71) Applicant (for all designated States except US): CAMOZZI HOLDING S.P.A. [IT/IT]; Via Eritrea, 20/I, I-25126 Brescia (IT).
- (74) Agents: SIMINO, Massimo et al.; Jacobacci & Partners S.p.A., Via Senato, 8, I-20121 Milano (IT).
- (81) Designated States (national): AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BY, BZ, CA, CH, CN, CR, CU, CZ, DE, DK, DM, DZ, EE, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NO, NZ, PL, PT, RO, RU, SD, SE, SG, SI, SK, SL, TJ, TM, TR, TT, TZ, UA, UG, US, UZ, VN, YU, ZA, ZW.
- (84) Designated States (regional): ARIPO patent (GH, GM, KE, LS, MW, MZ, SD, SL, SZ, TZ, UG, ZW), Eurasian patent (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European patent (AT, BE, CH, CY, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE, TR), OAPI patent (BF, BJ, CF, CG, CI, CM, GA, GN, GW, ML, MR, NE, SN, TD, TG).

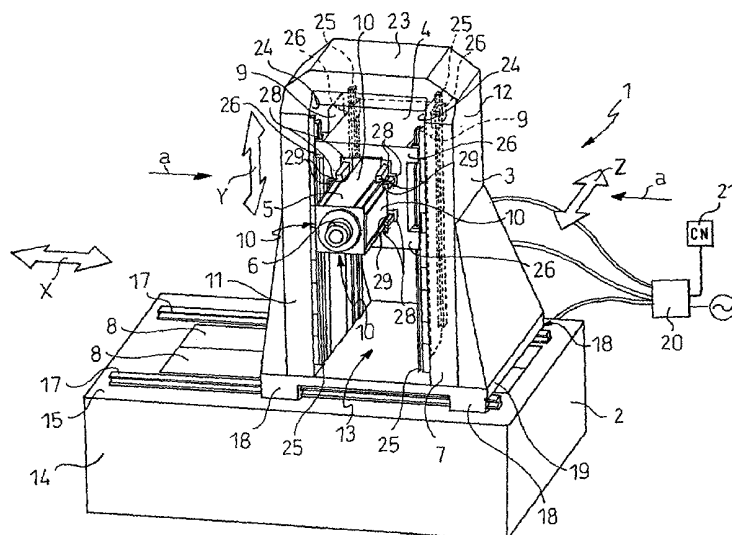
- (72) Inventors; and
- (75) Inventors/Applicants (for US only): CAMOZZI, Attilio [IT/IT]; Camozzi Holding S.p.A., Via Eritrea, 20/I, I-25126 Brescia (IT). CAMOZZI, Ettore [IT/IT]; Camozzi Holding S.p.A., Via Eritrea, 20/I, I-25126 Brescia (IT).

**Published:**

— with international search report

For two-letter codes and other abbreviations, refer to the "Guidance Notes on Codes and Abbreviations" appearing at the beginning of each regular issue of the PCT Gazette.

(54) Title: MULTI-AXIS LINEAR MOTOR MACHINE TOOL



(57) Abstract: A machine tool (1) driven by linear motors (8, 9, 10) along a plurality of axes (X, Y, Z) and unusually robust and rigid, comprises a bed (2) which defines at least a first axis (X), at least one column (3) operably connected and supported only at one of its ends (7) by said bed (2), for its guided movement along the first axis (X), said at least one column (3) extending away from the bed (2) to define a second axis (Y), at least one saddle mount (4), for its guided movement along a third axis (Z) and supporting a spindle (6) for the movement of a tool, wherein said at least one column (3) comprises a portal structure having a first shoulder (11) opposed to a second shoulder (12) such as to define a window (13) within which the saddle mount (4) is arranged, and wherein, between said opposed shoulders (11, 12) and the saddle mount (4), linear motors (9) are interposed such as to move the saddle mount (4) along said second axis (Y), producing an effect of attraction of the shoulders (11, 12) towards the saddle mount (4).



WO 02/28592 A1

## DESCRIPTION

**"Multi-axis linear motor machine tool"**

The present invention relates to a machine tool  
5 according to the preamble of claim 1.

More particularly, the subject of the invention is  
a machine tool of the type having three axes, wherein  
the tool, for example a chip removing tool, such as a  
milling cutter, is moved along a feed path at high speed  
10 by the use of linear motors.

The requirement to be fulfilled with this type of  
machine is to succeed in moving the tool rapidly and  
with high accelerations, even of 0.5 G, while at the  
same time guaranteeing the precision of the machining to  
15 be carried out. This involves the need for having a  
structure designed so that it is strong enough not to be  
distorted during the machining and at the same time to  
be rigid in the sense of not starting to vibrate either  
because of the effect of operation of the motors or the  
20 effect of the dynamic stresses which develop during the  
machining.

Generally, these machines comprise a column,  
extending in a vertical direction (Y axis), which column  
is slidingly supported by horizontal guides (X axis) of  
25 a bed. Along the column extend vertical guides on which

.2.

a saddle mount is operably connected and supported. The  
aforesaid saddle mount is provided in its turn with  
horizontal guides which serve to slidingly support a  
main saddle, for its guided movement along a third axis  
5 (Z axis). The main saddle then serves to support a  
spindle for the movement of the tool.

A machine having the aforesaid characteristics is  
known from the document US 5,368425.

The machine tool referred to in US Patent 5,368425  
10 has the drawback that the aforesaid requirement can be  
fulfilled only by the use of a very heavy and bulky  
structure, also with regard to the parts of the dynamic  
structure thereof, or the parts of the machine tool  
which are intended to be moved during the machining,  
15 above all the column constituting the Y axis of the  
machine. It is obvious that the presence of large  
dynamic masses to be moved at high accelerations is an  
extremely undesirable drawback, involving significant  
problems with regard to the design and dimensioning of  
20 the parts of the machine tool. In fact, this is  
manifested in an increase in the costs of the machine  
and an increase in the overall weight thereof.

The problem on which the present invention is based  
is that of devising a machine tool of the type specified  
25 which allows the aforesaid requirement to be fulfilled

.3.

while at the same time obviating the drawbacks that have been mentioned with reference to the machine tools of the prior art.

This problem is solved by a machine tool according to claim 1.

The present invention also relates to a machining centre according to claim 42.

Further characteristics and advantages of the machine tool and of the machining centre according to the invention will become clear from the following description of some preferred embodiments, provided by way of non-limiting example, with reference to the appended drawings, in which:

Figure 1 illustrates axonometrically a diagrammatic view of a machine tool according to the present invention;

Figure 2 illustrates axonometrically a machining centre including the machine in Figure 1;

Figure 3 illustrates a front view of the machining centre in Figure 2;

Figure 4 illustrates a side view of the machining centre in Figure 2;

Figure 5 illustrates a view from above of the machining centre in Figure 2.

With reference to the aforesaid drawings, a machine

.4.

tool is indicated as a whole by 1. The machine tool 1 comprises a bed 2 which supports at least one column 3 on which at least one saddle mount 4 can slide. In said saddle mount 4 there is provided a main saddle 5 adapted to support a spindle 6 for the movement of a tool.

Said bed 2 defines at least a first axis (X) arranged longitudinally to the bed 2. For example, said first axis (X) is arranged horizontally. To said first axis (X) said at least one column 3 is operably connected such that it is supported by the bed only by one of its ends 7 and can be guided along said first axis (X). The at least one column 3 extends away from the bed 2, defining a second axis (Y). For example, said second axis (Y) is arranged orthogonally to the first axis (X) and, in particular, vertically. The at least one saddle mount 4 is supported on the at least one column 3 so as to be guided along said second axis (Y). The at least one saddle mount in its turn defines a third axis (Z), for example arranged orthogonally to the first and second axis (X, Y) and, in particular, horizontally. Said saddle mount 4 supports the main saddle 5 so that it is guided along said third axis (Z). In the main saddle 5 the spindle 6 is received so that its operative end can receive the tang of a tool (Figure 1).

Said axes are driven by means of linear motors 8, 9

.5.

and 10, so as to permit the tool, supported by the spindle, to reach any point whatever of a working volume facing the machine 1 and having dimensions equal to the strokes that can be executed by the column 3, by the saddle mount 4 and respectively by the main saddle 5 along said first, second and third axis (X, Y and Z).

Advantageously, said at least one column comprises a portal structure having a first shoulder 11 opposed to a second shoulder 12. Said shoulders 11, 12 define or bound a window 13 within which is arranged the saddle mount 4 operably connected to the second axis (Y).

Between the shoulders 11, 12 and the saddle mount 4 are interposed the linear motors 9, which permit the movement of the saddle mount 4 along said second axis (Y) and have an effect of attraction (a) of the shoulders 11, 12 towards the saddle mount 4.

To further advantage, the column 3 has a symmetrical structure and is equipped with identical and opposed linear motors 9. Said linear motors 9 move the flanks of the saddle mount so as to exert an identical but opposed effect of attraction (a) of the shoulders 11, 12 towards the saddle mount 4. In other words, both the column 3 and the saddle mount 4 are subjected to an action, balanced overall, which does not alter the structural symmetry of the portal column but, unusually,

.6.

increases its robustness and rigidity.

According to one embodiment, the bed 2 comprises a box-type structure reinforced by stiffening ribs. Said box-type structure is advantageously filled with material suitable for damping the vibrations induced by the movement of the machine and by the machining operations. For example, the box-type structure of the bed 2 is filled with polymeric cement. The box-type structure of the bed 2 is, in particular, bounded by a front wall 14 facing towards the working volume of the machine tool 1, and also by an upper wall 15 bounded by a horizontal upper surface having longitudinal edges. Underneath, the bed 2 is adapted to bear on a foundation to which it is fixed, for example, by means of self-levelling bolts 16 (Figures 2, 3, 4).

Integral with the surface of the upper wall 15, a pair of linear guides 17 is provided, defining the first of said axes (X). Preferably, the linear guides 17 of the pair of guides are spaced from each other. In particular, each of said linear guides 17 is fixed to the bed 2 in proximity to its longitudinal edges. According to one embodiment, each of said linear guides 17 has a cross-section provided with undercut flanks or, in other words, re-entrant flanks having a recumbent V-shape. Said flanks define pairs of tracks for the

.7.

sliding of balls or, preferably, rollers, having oblique and crossed normals to one another.

Between the pair of linear guides 17, groups of stator elements of linear motors are provided, for example, groups of permanent magnets. Advantageously, said groups of stator elements constitute stator elements of a pair of linear motors arranged between the spaced linear guides 17 to constitute a traction bed.

According to one embodiment, the linear motors of said pair are arranged side by side with each other and, for example, cover substantially the entire distance provided between the linear guides. In particular, the linear motors of the pair of linear motors are arranged to be electromagnetically aligned with one another, in other words, so as to exert on the column an action which is balanced and aligned in the direction of the axis (X), avoiding or limiting the development of thrusts on the column such as to cause reactions transverse to the linear guides.

The linear guides 17 defining the first axis (X) have associated with them sliding blocks 18 integral with a carriage 19. Said carriage 19 is provided with an upper surface, a lower surface facing the bed 2, longitudinal edges directed along the first axis (X) and transverse edges, for example orthogonal to the first

.8.

axis (X). Advantageously, said sliding blocks 18 are preloaded for their movement along the guides 17 without play. To further advantage, said sliding blocks are sliding blocks with recirculating rollers, for example, of the lubricated type, acting on the tracks of the linear guides 17 of the bed 2. According to one embodiment, the sliding blocks 18 are four in number and arranged below and in proximity to the vertices of the carriage 19.

Below the carriage, and facing the groups of stator elements of the bed 2, groups of driven elements of linear motors are provided, advantageously a pair of groups of driven elements, for example, groups of coil packs. Said pair of groups of driven elements are operably coupled to the pair of groups of stator elements so as to move the carriage along said linear guides 17 defining the first axis (X).

According to one embodiment, first groups of driven elements, constituting an element of a first linear motor, are placed alongside a second group of driven elements, constituting a second linear motor. Said first and second groups of driven elements are electromagnetically aligned with one another so as to exert on the column the balanced and aligned actions described above.

.9.

According to a further embodiment, said driven groups can be positioned below the carriage so as to be adjustable in the direction of the axis (X), so as to align the action of the linear motors on the column. For example, at least one of the coil packs of the first or second linear motor is connected to the carriage by way of bolts received in slots which extend in the direction of the axis (X). Owing to the provision of the adjustable connections it is possible to align the electromagnetic effect generated by the linear motors arranged side by side at the expense of the geometric alignment thereof.

The groups of coil packs are operably connected to a drive device 20 controlled by a control unit 21. Advantageously, said drive is operated in a controlled manner also owing to a series of feedbacks, for example, in current and in velocity, as well as in position. In particular, the position feedback is effected by means of the operable connection of the control unit 21 with a position transducer 22, such as, for example, a linear position transducer, for example of the magnetic, optical (optical rule) or laser type. Said transducer 22 is for example provided on the bed in proximity to the linear guides 17 (Figure 2).

Transversely to the first axis (X), from the

.10.

carriage 19, away from the bed 2 and preferably in a vertical direction, rise up the two shoulders 11, 12 which are identical and opposed to each other. According to one embodiment, the shoulders 11, 12 are alongside  
5 the longitudinal edge of the carriage facing the working volume of the machine tool 1. Said shoulders 11, 12 are reinforced at the rear owing to the provision of ribs or reinforcing plates which connect an end of the shoulders which is fixed to the carriage, or base of the  
10 shoulders, to the carriage itself. Further ribs or reinforcing plates are also provided which are arranged externally to the shoulders 11, 12, opposed to one another and arranged in the direction of the first axis (X) for further reaction for the stresses induced on the  
15 shoulders by the acceleration of the carriage in the direction of said first axis (X). The ends of the shoulders 11, 12 remote from the bed 2, or free ends of the shoulders, are firmly fixed to each other by means of a cross-member 23, which with the shoulders 11, 12  
20 defines the portal column 3.

Together with the carriage 19, the shoulders 11, 12 and the cross-member 23 constitute a closed structure defining a symmetrical ring with opposed parallel sides. Said portal column 3 bounds the window 13 within which  
25 the saddle mount 4 is arranged.

.11.

The structure of the shoulders 11, 12 and of the cross-member 23 is advantageously of the box type, preferably provided with cellular internal reinforcements. According to one embodiment, said box-type structure comprises a shell of thin metallic material which includes ribs or a self-supporting structure with reinforcing baffles, as well as a framework. Advantageously, the spaces bounded by the box-type structure are filled with damping material which is at the same time light, such as, for example, polymeric resin in which light, rigid fillers are embedded.

The side of the shoulders which faces towards the window 13 is bounded by facing walls 24 having longitudinal edges, for example arranged vertically. On each of said facing walls 24 is provided a pair of linear guides 25 opposed to each other. On each of the shoulders 11, 12, the guides 25 of said pair of linear guides are arranged so as to be spaced from each other, for example, in proximity to the longitudinal edges of the facing walls 24. Said opposed pairs of linear guides 25 define the second of said axes (Y axis). Said second axis is advantageously orthogonal to the first axis (X) and is, for example, vertical. Analogously to the linear guides 17 defining the first axis (X), each of said

.12.

guides 25 of the column 3 has a cross-section provided with undercut flanks or, in other words, with re-entrant flanks having a recumbent V-shape. Said flanks define pairs of tracks for the sliding of balls or, preferably, 5 rollers, having oblique and crossed normals to one another.

On each of the facing walls 24 are provided groups of stator elements of linear motors 9, for example coil packs. Said groups are arranged between the guides 25 of 10 the pairs of linear guides of the shoulders 11, 12 so as to face one another.

According to one embodiment, the facing groups of stator elements are adjustably connected to the walls in order to be able to align the action exerted by the 15 linear motors on the saddle mount.

The guides 25 of the column 3 defining the second axis (Y) have associated with them sliding blocks 26 integral with the saddle mount 4. According to one embodiment, the saddle mount 4 comprises a box-type 20 symmetrical structure provided with flanks facing the shoulders 11, 12. In particular, said box-type structure comprises a closed section which defines internally a support and guide seat for the main saddle 5. Said seat constitutes a through aperture bounded by a polygonal 25 shell having surfaces which are preferably horizontal

.13.

and transverse to said first and second axis (X, Y). According to one embodiment, the sliding blocks 26 are provided in proximity to the eight vertices of said box-type structure, so as to be associated with the  
5 respective linear guides 25 of the facing pairs of guides of the shoulders 11, 12. Said sliding blocks 26 are preloaded and of the type with recirculating lubricated rollers, and have characteristics analogous to those described above for the coupling of the sliding  
10 blocks 18 to the guides 17 defining the first axis (X).

Associated with the flanks of the saddle mount 4, groups of driven elements of linear motors 9, for example permanent magnets, are provided. Said groups of driven elements are operably coupled to the groups of  
15 stator elements provided on the shoulders 11, 12. As for the linear motors 8 of the first axis (X), the pair of motors associated with the flanks of the saddle mount 4 are also operated in a controlled manner, by means of a drive 20 controlled by a control unit 21. In particular,  
20 the linear motors 9 acting on the flanks of the saddle mount 4 are operated so as to be synchronised with one another for movement of the saddle mount 4 along said guides 25 of the second axis (Y).

Analogously to the first axis (X), the drive 20 and  
25 the control unit 21 of the linear motors 9 are operated

.14.

with feedback, in particular with a saddle mount position transducer, for example a linear transducer of the magnetic, optical 27 or laser type (Figure 2).

5 With the saddle mount 4 there is advantageously interlocked a device for balancing its weight, for example a device with balancing cylinder and piston with hydraulic or pneumatic drive.

10 Associated with the polygonal shell bounding the seat for the main saddle 5, sliding blocks 28 are provided. Preferably, pairs of sliding blocks 28 are provided at the eight vertices of the polygonal shell. In other words, sixteen sliding blocks 28 are associated with both the walls bounding the eight vertices of the polygonal shell. Analogously to the first and second 15 axis (X, Y), said sliding blocks 28 are preloadable and with, for example, recirculation of lubricated rollers.

Between said sliding blocks 28 and at each wall of the polygonal shell, groups of stator elements of linear motors 10 are provided.

20 In said internal seat of the box-type structure of the saddle mount 4, the main saddle 5 is received such that four pairs of linear guides 29 fixed to the main saddle 5 are associated with the eight pairs of sliding blocks 28 of the saddle mount 4 to define said third 25 axis (Z).

.15.

Said main saddle 5 comprises a box-type structure having a polygonal outer surface and a front portion facing towards the working volume of the machine tool 1. Said linear guides 29 are fixed to the outer polygonal surface so as to be spaced from one another, for example, in proximity to the longitudinal edges of the main saddle 5, so as to receive between them groups of driven elements of linear motors 10 fixed to the main saddle 5 such as to be operably coupled to said groups of stator elements provided in the saddle mount, for movement of the main saddle along the guides 29 defining said third axis (Z).

As for the linear motors 8, 9 of the first and second axis (X, Y), the four motors associated with the polygonal outer surface of the main saddle 5 are also adjustably connected to that surface in order to align the actions exerted by the linear motors on the main saddle 5. Said motors are further operated in a controlled manner, by means of a drive 20 operated by a control unit 21. In particular, the linear motors acting on the main saddle 5 are operated so as to be synchronised with one another for movement of the main saddle 5 along said guides 29 of the third axis (Z). Analogously to the first and second axis (X, Y), the drive 20 and the control unit 21 for the linear motors

.16.

10 are operated with feedback, in particular with a main saddle position transducer, for example a linear transducer of the magnetic, optical or laser type.

The main saddle 5 firmly comprises the spindle 6  
5 adapted for the controlled movement of a machining tool. Said spindle 6 is firmly fixed to the main saddle so that the operative end thereof extends from the front portion of the main saddle, projecting into the working volume.

10 In other words, owing to the drive, operated in a controlled manner, of the linear motors interlocked with the three axis (X, Y, Z), the main saddle reaches with its front portion a predefined position of the working volume of the machine tool 1, following the desired  
15 trajectory and law of motion (time law).

From the drawings it is further possible to observe a machining centre including a machine tool 1 of the type described above (Figures 2, 3, 4 and 5).

According to one embodiment, the machine tool 1 has  
20 associated with it a frame structure 30 which permits free movement of the machine along its axes (X, Y, Z) and at the same time makes it possible to interlock with the machine service devices, such as, for example, a tool change device 31, for rapid and automatic  
25 substitution of the tool supported by the spindle 6, as

.17.

well as an automatic device for feeding the tools to the tool change device, operably connected to a tool magazine. Said frame structure further makes it possible to interlock with the machine tool 1 a cutting fluid feed device, as well as a chip removal device. In particular, said frame structure makes it possible to support panels which constitute protective barriers enclosing the machine and its working volume.

From the above it will be appreciated how providing the column with portal structure within which the saddle mount is supported and guided, together with the provision of linear motors interposed between shoulders of the column and flanks of the saddle mount, producing an effect of attraction of the shoulders towards the saddle mount, allows the drawbacks of the prior art to be obviated.

Advantageously, said interaction of the portal structure and the attraction effect of the linear motors makes it possible to produce a machine tool and a machining centre of low weight and bulk while maintaining an equal working volume. In particular, the solution proposed makes it possible to obtain a light structure which is unusually robust and rigid to the point of allowing accelerations of the axes even greater than 1 G, for example from 1 G to 2 G and preferably of

.18.

1.1 G. A further advantage of the solution proposed lies in its unusual structural simplicity, which makes it possible to produce the machine and the machining centre at a contained cost and also obtain easier assembly of  
5 the machine.

For greater understanding of the solution proposed, emphasis is placed on the simplicity of control, described above, of the movement of the axes (X, Y, Z) and in particular of the first axis (X). The solution  
10 proposed makes it possible to obtain a column of particular robustness and rigidity which in the prior art can be obtained only by way of the much more complicated known production techniques such as a gantry, where the column is supported and guided from  
15 both ends. With the solution proposed it is possible to obtain a high degree of robustness and rigidity while avoiding the complex and costly task of supporting and moving synchronously the two ends of the column.

Advantageously, the provision between the column  
20 and the bed of preloaded roller guides and a bed of linear motors allows connection between the latter which is rigid and at the same time capable of rapid responses to movement commands issued by the drive (increased readiness).

25 A person skilled in the art, in order to fulfil

.19.

contingent and specific requirements, may apply to the preferred embodiment of the machine tool described above many modifications, adaptations and substitutions of elements with other functionally equivalent elements, 5 without thereby departing from the scope of the following claims.

\*\*\* \* \*\*\*

.20.

### C L A I M S

- 1 A machine tool driven by linear motors along a plurality of axes, comprising
- 5 - a bed which defines at least a first axis (X),
- at least one column operably connected and supported only at one of its ends by said bed, for its guided movement along the first axis (X), said at least one column extending away from the bed to define a
- 10 second axis (Y),
- at least one saddle mount operably connected and supported by the at least one column, for its guided movement along the second axis (Y),
- at least one main saddle supported by the
- 15 saddle mount, for its guided movement along a third axis (Z) and supporting a spindle for the movement of a tool, characterized in that
- said at least one column comprises a portal structure having a first shoulder opposed to a second
- 20 shoulder such as to define a window within which the saddle mount is arranged, and that
- between said opposed shoulders and the saddle mount, linear motors are interposed such as to move the saddle mount along said second axis (y) while producing
- 25 an effect of attraction of the shoulders towards the

.21.

saddle mount.

2 A machine according to claim 1, wherein said at least one column comprises a symmetrical structure.

3 A machine according to claim 1 or 2, wherein  
5 said at least one column comprises a box-type body structure with internal reinforcements in a cellular arrangement.

4 A machine according to any one of claims 1 to 3, wherein said at least one column comprises a  
10 structure which widens out from a free end thereof to an end connected to the bed.

5 A machine according to claim 4, wherein the at least one column comprises reinforcing plates in proximity to a base by which it is connected to the bed.

15 6 A machine according to any one of claims 1 to 5, wherein the shoulders of the at least one portal column are joined mechanically at their free end by means of a cross-member.

7 A machine according to any one of claims 1 to  
20 6, wherein the at least one column is supported at a carriage to form a closed ring structure within which the saddle mount is received.

8 A machine according to any one of the preceding claims, wherein said first, second and third  
25 axis (X, Y, Z) are orthogonal to one another.

.22.

9 A machine according to any one of the preceding claims, wherein each axis (X; Y; Z) is driven by means of at least one linear motor.

10 A machine according to any one of the preceding claims, wherein each linear motor is operably connected to a drive and control unit with feedback.

11 A machine according to claim 10, wherein said drive and control unit is provided with feedback at least by means of a position transducer interlocked with each axis.

12 A machine according to claim 11, wherein said transducer is a linear transducer.

13 A machine according to claim 12, wherein said transducer is a magnetic type transducer.

15 14 A machine according to claim 12, wherein said transducer is an optical type transducer.

15 A machine according to any one of the preceding claims, wherein each linear motor comprises a group of stator elements and a group of driven elements.

20 16 A machine according to claim 15, wherein said group of stator elements is provided in the bed, while said group of driven elements is provided in the at least one column.

25 17 A machine according to claim 15, wherein said group of stator elements is provided in the shoulders of

.23.

the at least one column, while said group of driven elements is provided in the saddle mount.

18 A machine according to claim 15, wherein said group of stator elements is provided in the saddle mount, while said group of driven elements is provided in the main saddle.

19 A machine according to any one of the preceding claims, wherein the first axis (X) is defined by at least one pair of linear guides, integral with the bed, on which travel sliding blocks integral with the at least one column.

20 A machine according to claim 19, wherein the guides of said at least one pair of linear guides are arranged in proximity to longitudinal edges of the bed.

21 A machine according to claim 20, wherein at least one pair of linear motors, adapted to move the at least one column, is provided between the guides.

22 A machine according to any one of claims 19 to 21, wherein the sliding blocks have roller recirculation.

23 A machine according to claim 22, wherein the rollers of the sliding blocks with roller recirculation act on tracks, provided on the guides, in oblique and crossed directions.

24 A machine according to any one of claims 19 to

.24.

23, wherein said sliding blocks are coupled to the guides with preloading.

25 A machine according to any one of the preceding claims, wherein the second axis (Y) is defined  
5 by at least two opposed pairs of linear guides, integral with the shoulders, on which travel sliding blocks integral with the saddle mount.

26 A machine according to claim 25, wherein the sliding blocks are at least eight in number and are  
10 arranged in proximity to the vertices of the structure of the saddle mount.

27 A machine according to claim 25 or 26, wherein the guides of each of said at least two pairs of linear guides are arranged in proximity to the longitudinal  
15 edges of the shoulders.

28 A machine according to claim 27, wherein between the guides of each shoulder at least one linear motor is provided, adapted to move the saddle mount and exerting opposed and balanced effects of attraction of  
20 the shoulders towards the saddle mount.

29 A machine according to any one of claims 25 to 28, wherein the sliding blocks have roller recirculation.

30 A machine according to claim 29, wherein the  
25 rollers of the sliding blocks with roller recirculation

.25.

act on tracks, provided on the guides, in oblique and crossed directions.

5       **31**   A machine according to any one of claims 25 to 30, wherein said sliding blocks are coupled to the guides with preloading.

**32**   A machine according to any one of the preceding claims, wherein the saddle mount comprises a box-type structure of closed section which defines internally a support and guide seat for the main saddle.

10       **33**   A machine according to any one of the preceding claims, wherein the third axis (Z) is defined by at least four opposed pairs of linear guides, integral with the main saddle, on which travel sliding blocks integral with the saddle mount.

15       **34**   A machine according to claim 33, wherein the sliding blocks are at least sixteen in number and are arranged in proximity to the vertices of the seat for the main saddle provided in the saddle mount.

**35**   A machine according to claim 33 or 34, wherein  
20 the guides of each of said at least four pairs of linear guides are arranged in proximity to the longitudinal edges of the main saddle.

**36**   A machine according to claim 35, wherein  
25 between each pair of guides at least one linear motor adapted to move the main saddle is provided.

.26.

37 A machine according to any one of claims 33 to 36, wherein the sliding blocks have roller recirculation.

38 A machine according to claim 37, wherein the  
5 rollers of the sliding blocks with roller recirculation act on tracks, provided on the guides, in oblique and crossed directions.

39 A machine according to any one of claims 33 to 38, wherein said sliding blocks are coupled to the  
10 guides with preloading.

40 A machine according to any one of the preceding claims, wherein material capable of damping the vibrations is provided in the bed.

41 A machine according to claim 41, wherein  
15 polymeric cement is provided in the bed.

42 A machine according to any one of the preceding claims, wherein the column comprises a box-type structure having a thin shell which includes reinforcing ribs.

20 43 A machine according to any one of the preceding claims, wherein the column comprises a box-type structure containing damping material.

44 A machine according to any one of the preceding claims, wherein the column comprises a box-  
25 type structure containing polymeric resin incorporating

.27.

light and rigid fillers.

45 A machine according to any one of the preceding claims, wherein, associated with each axis (X, Y, Z), a position transducer of the laser type is  
5 provided.

46 A machine according to any one of the preceding claims, wherein each pair of linear motors associated with the same axis (X; Y; Z) is adjustably connected to the structure of the machine to balance and  
10 align the action exerted by the linear motors on the axis.

47 A machining centre comprising a machine as described in any one of the preceding claims.

48 A machining centre according to claim 47,  
15 wherein an automatic tool change is included.

49 A machining centre according to claim 48, wherein an automatic tool feeding device which is operably connected to a tool magazine is interlocked with said tool change.

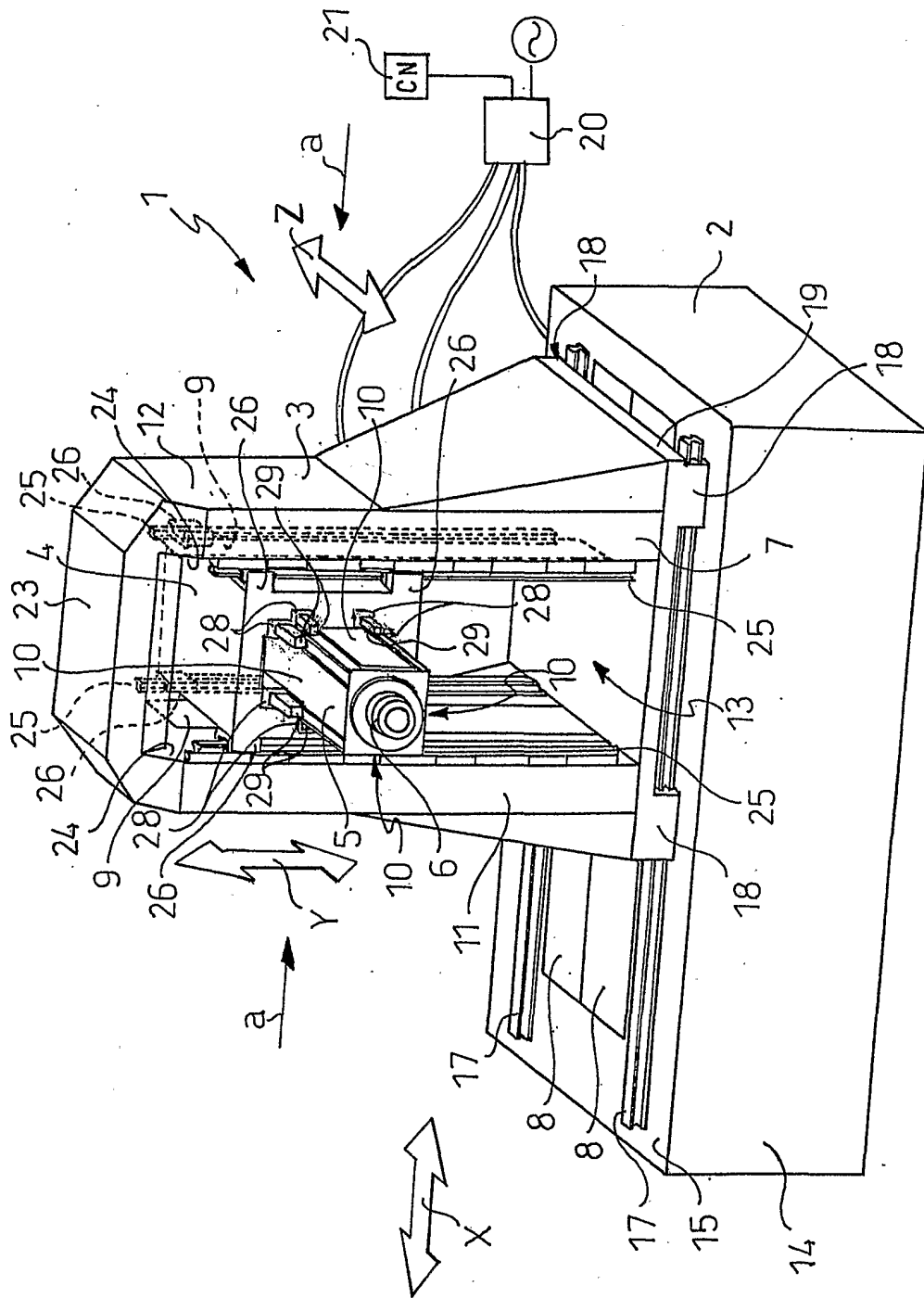


FIG.1

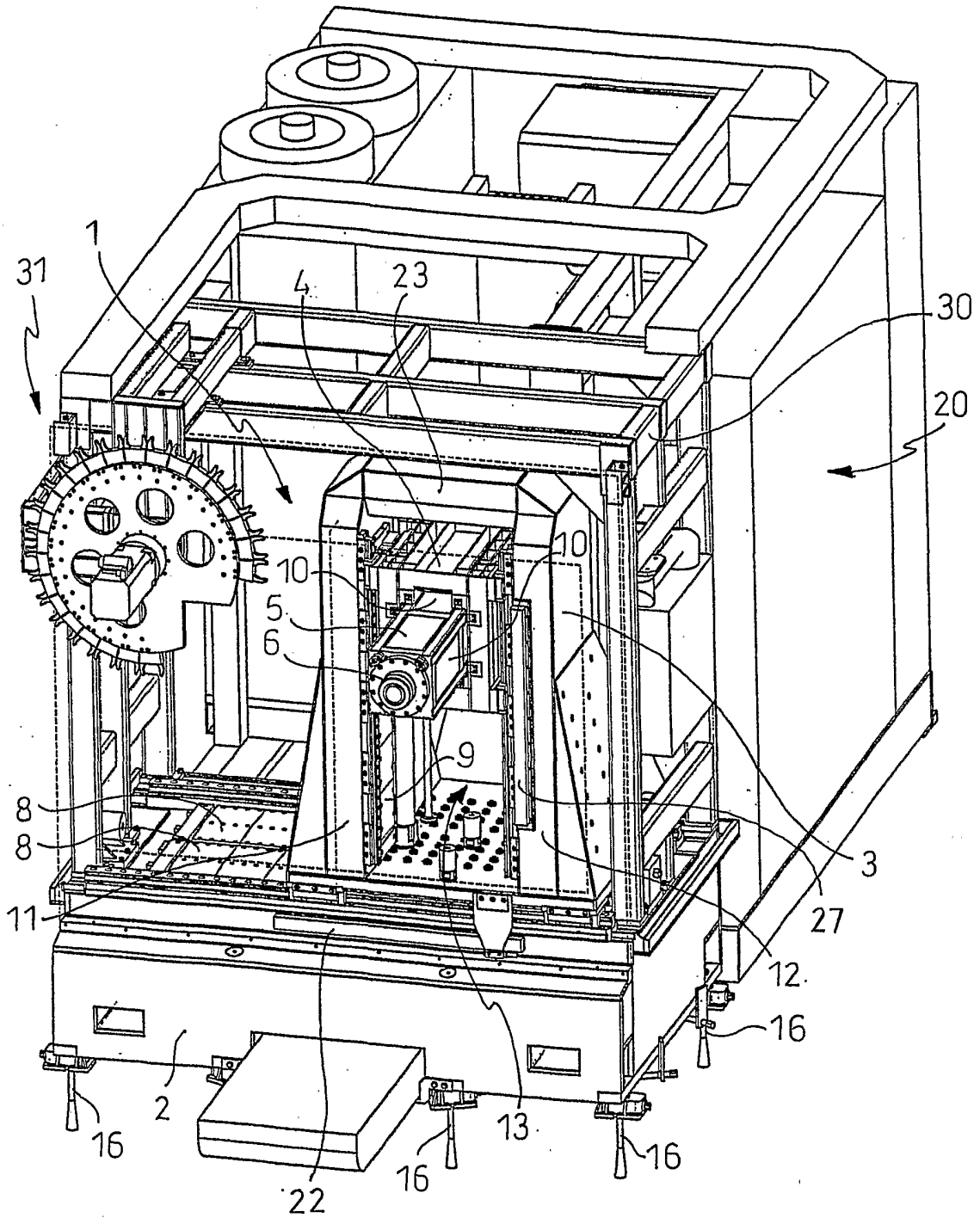


FIG. 2

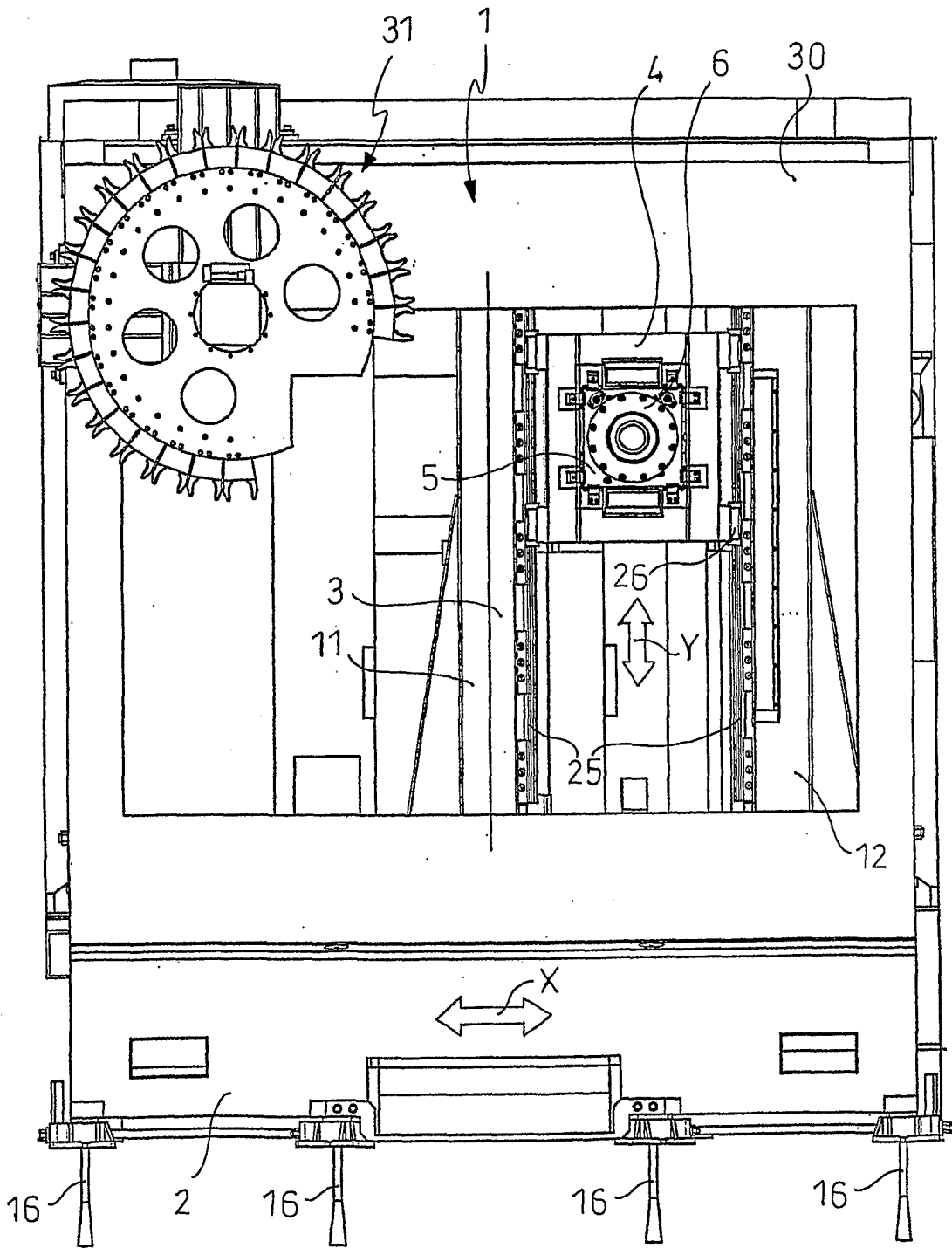
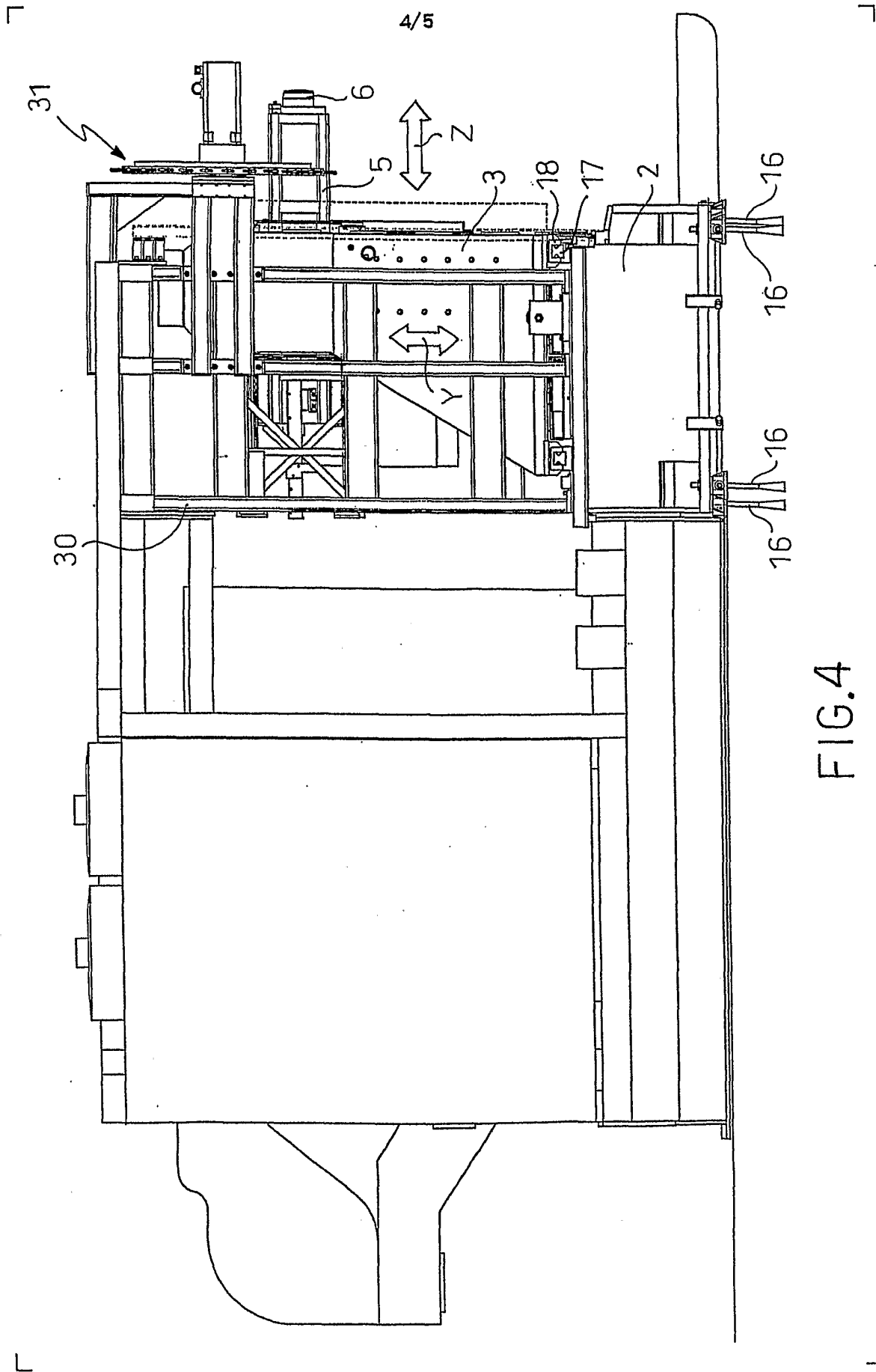


FIG.3



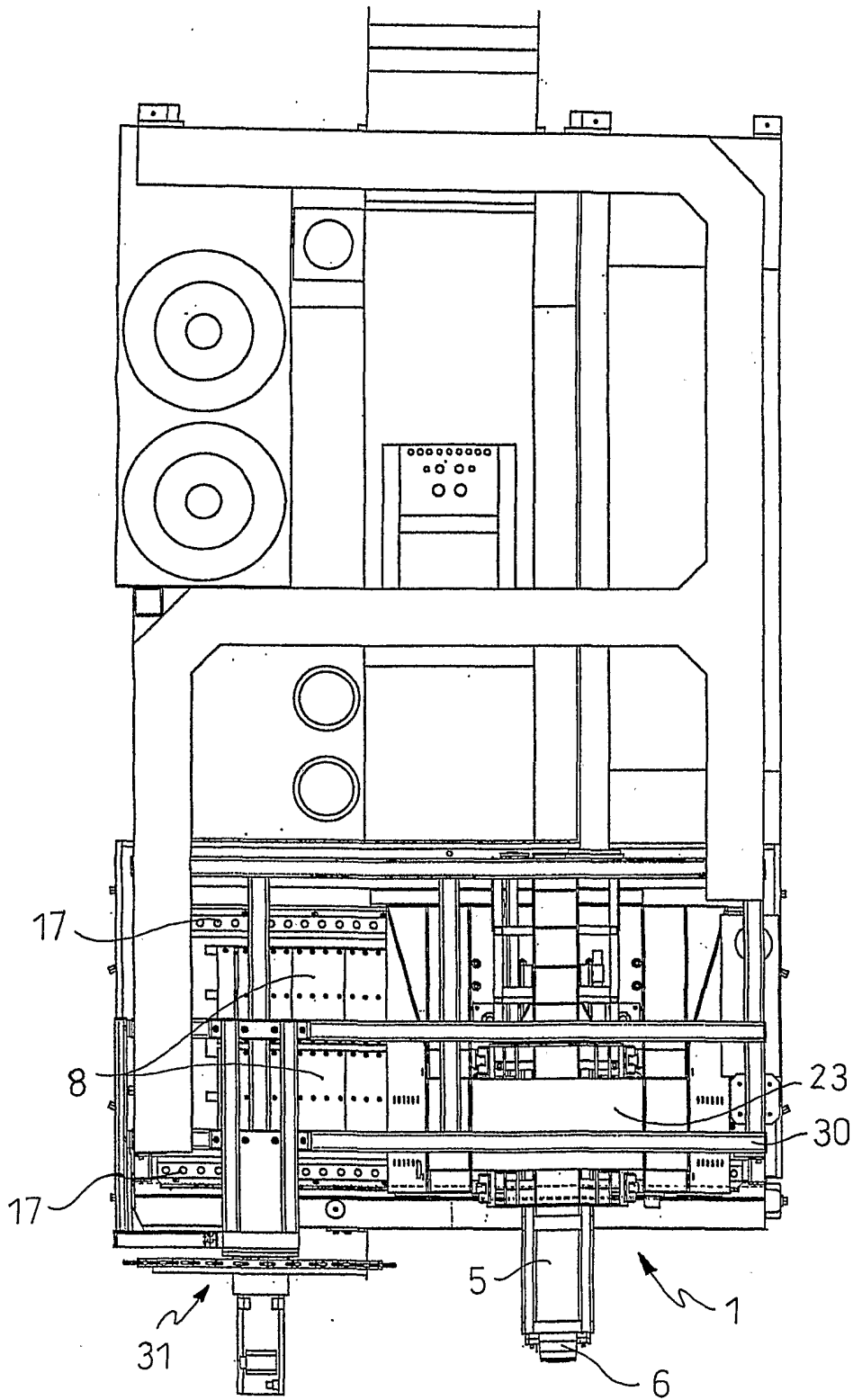


FIG. 5

# INTERNATIONAL SEARCH REPORT

Int'l      onal Application No  
PCT/IT 01/00067

<b>A. CLASSIFICATION OF SUBJECT MATTER</b> IPC 7    B23Q1/01				
According to International Patent Classification (IPC) or to both national classification and IPC				
<b>B. FIELDS SEARCHED</b>				
Minimum documentation searched (classification system followed by classification symbols) IPC 7    B23Q				
Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched				
Electronic data base consulted during the international search (name of data base and, where practical, search terms used) EPO-Internal, PAJ				
<b>C. DOCUMENTS CONSIDERED TO BE RELEVANT</b>				
Category °	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.		
A	US 5 368 425 A (MILLS DANIEL M ET AL) 29 November 1994 (1994-11-29) cited in the application claim 1 ---	1-49		
A	EP 0 583 085 A (FORD WERKE AG ;FORD FRANCE (FR); FORD MOTOR CO (GB)) 16 February 1994 (1994-02-16) column 4, paragraphs 3,5; figure 3 ---	1-49		
A	EP 0 893 196 A (TOYODA MACHINE WORKS LTD) 27 January 1999 (1999-01-27) claim 1 ---	1-49		
A	JP 2000 218443 A (SODICK CO LTD) 8 August 2000 (2000-08-08) figures 1-7 ---	1-49		
-/--				
<input checked="" type="checkbox"/> Further documents are listed in the continuation of box C.				
<input checked="" type="checkbox"/> Patent family members are listed in annex.				
° Special categories of cited documents :				
<table style="width: 100%; border: none;"> <tr> <td style="width: 50%; border: none; vertical-align: top;"> <ul style="list-style-type: none"> <li>*A* document defining the general state of the art which is not considered to be of particular relevance</li> <li>*E* earlier document but published on or after the international filing date</li> <li>*L* document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)</li> <li>*O* document referring to an oral disclosure, use, exhibition or other means</li> <li>*P* document published prior to the international filing date but later than the priority date claimed</li> </ul> </td> <td style="width: 50%; border: none; vertical-align: top;"> <ul style="list-style-type: none"> <li>*T* later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention</li> <li>*X* document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone</li> <li>*Y* document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.</li> <li>*Z* document member of the same patent family</li> </ul> </td> </tr> </table>			<ul style="list-style-type: none"> <li>*A* document defining the general state of the art which is not considered to be of particular relevance</li> <li>*E* earlier document but published on or after the international filing date</li> <li>*L* document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)</li> <li>*O* document referring to an oral disclosure, use, exhibition or other means</li> <li>*P* document published prior to the international filing date but later than the priority date claimed</li> </ul>	<ul style="list-style-type: none"> <li>*T* later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention</li> <li>*X* document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone</li> <li>*Y* document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.</li> <li>*Z* document member of the same patent family</li> </ul>
<ul style="list-style-type: none"> <li>*A* document defining the general state of the art which is not considered to be of particular relevance</li> <li>*E* earlier document but published on or after the international filing date</li> <li>*L* document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)</li> <li>*O* document referring to an oral disclosure, use, exhibition or other means</li> <li>*P* document published prior to the international filing date but later than the priority date claimed</li> </ul>	<ul style="list-style-type: none"> <li>*T* later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention</li> <li>*X* document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone</li> <li>*Y* document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.</li> <li>*Z* document member of the same patent family</li> </ul>			
Date of the actual completion of the international search  <p style="text-align: center;">18 June 2001</p>	Date of mailing of the international search report  <p style="text-align: center;">25/06/2001</p>			
Name and mailing address of the ISA European Patent Office, P.B. 5818 Patentlaan 2 NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Tx. 31 651 epo nl, Fax: (+31-70) 340-3016	Authorized officer  <p style="text-align: center;">De Gussem, J</p>			

# INTERNATIONAL SEARCH REPORT

International Application No  
PCT/IT 01/00067

C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT		
Category °	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	JP 09 262727 A (MORI SEIKI CO LTD;TOSHIBA MACH CO LTD; MITSUBISHI HEAVY IND LTD; OSAKA) 7 October 1997 (1997-10-07) figures 1-12 -----	1-49
A	JP 08 309641 A (TOYODA MACH WORKS LTD) 26 November 1996 (1996-11-26) figures 1-6 -----	1-49
A	JP 2000 237923 A (TOYODA MACH WORKS LTD) 5 September 2000 (2000-09-05) figures 1-4 -----	1-49
A	JP 05 104332 A (FANUC LTD) 27 April 1993 (1993-04-27) figures 1-4 -----	1-49

# INTERNATIONAL SEARCH REPORT

Information on patent family members

International Application No

PCT/IT 01/00067

Patent document cited in search report	Publication date	Patent family member(s)	Publication date		
US 5368425 A	29-11-1994	CA 2101402 A	01-02-1994		
		DE 4324918 A	03-02-1994		
		GB 2269123 A,B	02-02-1994		
		GB 2295976 A,B	19-06-1996		
		JP 6079562 A	22-03-1994		
EP 0583085 A	16-02-1994	US 5314397 A	24-05-1994		
		CA 2101406 A	01-02-1994		
		DE 69321674 D	26-11-1998		
		DE 69321674 T	18-03-1999		
		EP 0819499 A	21-01-1998		
		JP 6155203 A	03-06-1994		
		MX 9304376 A	31-03-1994		
		US 5379509 A	10-01-1995		
		EP 0893196 A	27-01-1999	JP 11033856 A	09-02-1999
				JP 11216633 A	10-08-1999
US 6161995 A	19-12-2000				
JP 2000218443 A	08-08-2000	NONE			
JP 09262727 A	07-10-1997	NONE			
JP 08309641 A	26-11-1996	NONE			
JP 2000237923 A	05-09-2000	NONE			
JP 05104332 A	27-04-1993	NONE			