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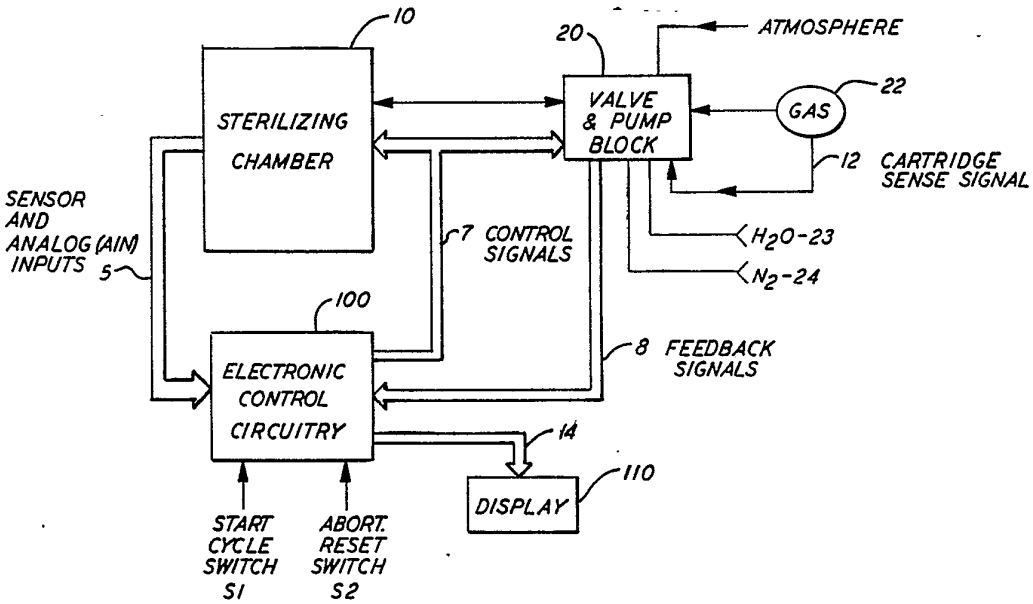

(57) Abstract

A system for treating articles, preferably with a sterilizing gas. The system includes a chamber (10) into which the articles are received and valves (V2, V1) for supplying the sterilizing gas to the chamber and for removing the gas from the chamber after a predetermined time period. The sterilizing gas is generated on site from at least two components, thus minimizing problems in the transportation of the gas to the location. The sterilizing gas generated on site is preferably chlorine dioxide and the two components may be chlorine gas and sodium chlorite. The system includes a progammed microprocessor controller (100) for controlling the valves executing a predetermined sequence of instructions. The predetermined sequence of instructions define a state diagram for the system having a plurality of successive states. In order to provide for system safety, the controller preferably employs a plurality of abort states to which the system returns in the event of a failure. Depending on the nature of the failure, the system automatically moves to the proper abort state.

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GAS STERILANT SYSTEM

BACKGROUND OF THE INVENTION

This application is related to copending applications Serial Nos. 435,331 filed October 19, 1982 and 601,443, filed April 18, 1984, the disclosures of which are hereby incorporated herein by reference.

The present invention relates to systems for delivering a gas to a confined chamber and to systems for sterilizing substances and articles and particularly to systems using a sterilizing gas to sterilize articles, for example medical apparatus such as utensils and instruments which may have been contaminated by foreign substances. The system of the present invention can also be used to sterilize non-medical articles and substances, as required. The system of the present invention relates particularly to a gas sterilizing system wherein two components which react to provide sterilizing amounts of a gas are combined in the field by the apparatus of the present invention. This allows the components which react to form the sterilizing gas to be shipped separately, which minimizes the possibility of accidents.

In particular, the present invention relates to a system using chlorine dioxide as the sterilizing gas. Chlorine dioxide gas is both unstable and toxic to humans. For

example, chlorine dioxide gas, will, over time, decompose into its constituent parts and accordingly, it cannot be transported easily. It is therefore undesirable to transport chlorine dioxide gas. Moreover, chlorine dioxide gas is somewhat explosive and also has a propensity to undergo catalytic decomposition. The components which react to form chlorine dioxide gas (e.g., sodium chlorite and chlorine gas), however, may be transported relatively easily and reacted on site to provide the sterilizing gas chlorine dioxide.

Prior systems have typically used ethylene oxide gas as a sterilant. For example, the castle 4040 ethylene oxide sterilizer manufactured by Sybron Corporation, Medical Products Division, is an example of such a prior system. Although ethylene oxide has been used as a sterilizing gas in the prior systems, chlorine dioxide is a preferred sterilant.

Furthermore, the systems used in the past have typically been of rather simple design and have not included advanced means for maintaining the reliability of the devices and safeguarding against accidents. Additionally, these systems have not provided a great deal of redundancy so that if a component of the system failed, manual intervention or service personnel was required to correct the failure before the sterilizing process could continue.

SUMMARY OF THE INVENTION

It is an object of the present invention to provide a sterilizing system which uses a gas having bacteriocidal, sporicidal, fungicidal and/or viricidal properties to sterilize articles.

It is a further object of the invention to provide a

sterilizing system in which at least two components which react to provide a sterilizing gas are reacted on site within the apparatus of the present invention to provide effective amounts of the sterilizing gas.

It is yet a further object of the present invention to provide a sterilizing system wherein the sterilant is chlorine dioxide gas.

It is still a further object of the present invention to provide a gas sterilizing system having built-in redundancy and means for maintaining the reliability and safety of the system.

It is still yet another object of the present invention to provide a gas sterilizing system which is versatile and which is controlled by a programmed microprocessor.

According to one embodiment of the invention, these and other objects of the present invention are achieved by a system for treating articles with a gas comprising first means for receiving a first component, second means for receiving a second component, the first and second components, when reacted together, forming the gas, means for reacting the two components together for forming the gas, valve means for supplying the gas to the chamber means to treat the article in the chamber means, means for removing the gas from the chamber means, electronic controller means for controlling the means for reacting, means for supplying and means for removing, comprising computer means executing a predetermined sequence of steps so as to cycle the apparatus through a series of successive states defining a cycle in which the article is treated by the gas and wherein the gas is thereafter removed from the chamber means so as to render the atmosphere in the chamber means within acceptable standards of safety.

According to another embodiment of the invention, a system for treating articles with a gas is provided comprising chamber means for receiving articles to be treated, means for supplying the gas to the chamber means comprising valve means coupled to the chamber means for supplying the gas to the chamber means, means for removing the gas from the chamber means after a predetermined time interval, electronic control means receiving a plurality of electrical signals associated with ones of measured parameters from the chamber means for controlling the valve means and the means for removing, the electronic control means comprising computer means for cycling the apparatus through a plurality of states in accordance with a predetermined sequence of instructions, the computer means including means for aborting the operation of the apparatus to one of a plurality of defined failure states in response to a failure of the apparatus, the selected failure state dependent on the state in the cycle in which the failure occurred.

According to still another embodiment of the invention, a system for treating articles with a gas is provided comprising chamber means for receiving articles to be treated, means for supplying the gas to the chamber means comprising valve means coupled to the chamber means for supplying the gas to the chamber means, means for removing the gas from the chamber means after a predetermined time interval, electronic control means receiving a plurality of elecrical signals associated with ones of measured parameters from the chamber means for controlling the valve means and the means for removing, the electronic control means comprising computer means for cycling the apparatus through a pluality of states in accordance with a predetermined sequence of instructions, the computer means including memory means, and further comprising means for receiving

input signals from the valve means indicative of the closed or open condition of the valve means and means for transmitting output signals to the valve means to selectively open or close the valve means, image signals of the input and output signals being stored in the memory means, mask means being stored in the memory means, the computer means comparing the image signals of the input and output signals and generating an alarm signal if the input and output image signals do not agree in response to the setting of a bit in the mask means.

Other objects, features and advantages of the present invention will be apparent from the description which follows.

BRIEF DESCRIPTION OF THE DRAWINGS

The present invention will be described in greater detail with reference to the accompanying drawings in which:

FIG. 1 is a block diagram of the overall gas sterilant system according to the invention;

FIG. 2 is a block diagram of the sterilizing chamber and the valve and pump block of the gas sterilant system according to the present invention;

FIG. 3 is a block diagram of the electronic control circuitry of the gas sterilant system;

FIG. 3A is a table of addresses used in the electronic controller of FIG. 3 and the corresponding components or signals controlled by the addresses;

FIG. 4 is a block diagram showing how various system clock frequencies and the system interrupt are derived;

FIG. 5 is a front view of one embodiment of a control panel for the gas sterilant system showing the controller display lights and control switches;

FIG. 6 is a state diagram for the gas sterilant system according to the present invention;

FIG. 7 is a state output matrix corresponding to the state diagram of FIG. 6 for the gas sterilant system according to the present invention;

FIGS. 7A and 7B are flowcharts for the sequencing program for implementing the state diagram of FIG. 6;

FIG. 8 is a block diagram of the safety interlock arrangement for the gas sterilant system according to the present invention;

FIG. 9 is a functional flow diagram for the software resident in the memory of the electronic controller of the gas sterilant system according to the present invention;

FIG. 10 is a flow diagram for timed functions of the software for the gas sterilant system;

FIG. 11 is a flow diagram for one of the timed functions of the software for the gas sterilant system;

FIG. 12 is a memory map of the data memory of the electronic control circuitry for the gas sterilant system according to the present invention;

FIG. 13 is a flowchart for another of the timed functions of the software of the electronic control circuitry for the gas sterilant system according to the present invention;

FIG. 14 is a flowchart of another of the timed functions of the software for the gas sterilant system according to the present invention;

FIG. 15 is a flowchart for another of the timed functions of the software for the gas sterilant system according to the present invention;

FIG. 16 is a flowchart for a program implemented in the control unit for resetting the control unit timed functions;

FIG. 17 is a flowchart for a program implemented in the control unit for reading in input data from the system according to the invention;

FIG. 18 is a flowchart for a program implemented in the control unit for providing a timeout alarm in the event of a component failure;

FIG. 19 is a flowchart for a program implemented in the control unit for providing an additional alarm in the event of a component failure;

FIG. 20 is a flowchart for a program implemented in the control unit for writing out data to the controlled components of the system;

FIG. 21 is a flowchart for a program implemented in the control unit for reading in analog input data from the controlled system;

FIG. 22 is a general flowchart for a program implemented in the control unit for providing the various timed functions of the system;

FIG. 23 is a flowchart for part of the program of FIG.

22; and

FIG. 24 is a flowchart for a program implemented in the control unit for controlling the system outputs.

DETAILED DESCRIPTION

Overall System

With reference now to the drawing figures, FIG. 1 shows the overall gas sterilant system. The system comprises a sterilizing chamber 10, electronic control circuitry 100 which is preferably microprocessor controlled, valve and pump block 20 and displays 110. Sensor inputs 5 including signals generated by appropriate sensors in chamber 10 and related to temperature, pressure, humidity and sterilizing gas concentration in the chamber 10 are fed from the sterilizing chamber 10 to control circuitry 100. The sensor inputs include both analog signals relating to the above measured chamber parameters and certain digital signals, e.g., a signal indicative of when the temperature in the chamber has reached a desired value, to be explained in more detail below. A START CYCLE switch S1 initiates operation of the system and an ABORT-RESET switch S2, as described in more detail later, is used to recycle the system states to a defined condition if an abort mode is attained, i.e., if a failure or alarm condition occurs. The operation of valve and pump block 20 will be described in more detail below, and includes a source of chlorine dioxide gas 22 which is produced on location from separated components, water vapor 23 and nitrogen 24. The valve and pump block is also vented to the atmosphere, as shown. Valve and pump block 20 includes a number of sequenced and controlled valves and a vacuum pump for providing the necessary conditions in the sterilizing chamber at the appropriate times. Because of the instability and potential toxicity of chlorine dioxide, the preferred sterilizing gas, it is preferable

to transport components, which when reacted, form the chlorine dioxide gas. For example, the components may be sodium chlorite, Na_2ClO_2 and chlorine gas, Cl_2.

Appropriate control signals 7 are fed by the electronic control circuitry 100 to the valve and pump block 20 and chamber 10 for controlling components of the system. Furthermore, feedback signals 8 from the controlled components are fed back to the control circuitry 100 so that the controller can monitor the state of the system and signals 14 are coupled to display panel 110 for informing the operator of the status of the system.

Additionally, a cartridge sense signal 12 is fed from the attached gas cartridge (Cl_2 component cartridge) to indicate that a gas component cartridge has been coupled into the system.

General Functions

FIG. 2 shows the arrangement of valve and pump block 20 in more detail. Valve and pump block 20 includes a series of valves V1, V2, V3, V4, V4a, V5, V6, V7, V8, V9 and V10, pumps P1 and P2, air filter 13, a detoxifier 22 for detoxifying the evacuated chlorine dioxide gas, which may be implemented as explained in the above copending patent applications, and appropriate sources of water vapor, nitrogen, Cl_2 gas, air, and sodium chlorite. As shown in FIG. 2, some of the valves are merely sequenced, while others are controlled in response to selected ones of the values of the measured process variables, e.g., gas concentration, humidity level and pressure. For safety reasons, each valve (V) is fitted with two limit switches (LS) to indicate the open (e.g. LS2o) or closed condition (e.g. LS2c) of the valve. In the attached software listing, the open limit switches are referred to by the designation LSOx and the closed limit switches by the designation LSCx. Both

switches must be in their proper positions at the proper times during the entire cycle in order that the cycle not be aborted. In addition, a number of lights are provided on a display panel, as shown in FIG. 5, which indicate the progress of the sterilization cycle or the occurrence of possible fault conditions. A cycle can be started by the operator, after the chamber door 11 is closed, by momentarily depressing the START-CYCLE (S1) switch. See FIG. 1. Thereafter the cycle proceeds automatically according to a program stored in the microprocessor memory of the electronic controller 100. This process will be described in more detail below.

Furthermore, in order to provide redundancy, a number of manually controlled valves, e.g. valves V_9 and V_{10}, are provided in case valves V_3 and V_8 do not open. These valves can be manually operated by service personnel so that potentially toxic gases can be removed via detoxifier 22 in the event valves V_3 and V_8 fail to open when sterilizing gas is in the chamber. An auxiliary vacuum pump is also provided so that the gas can be drawn out via the manually operated valves.

Sterilization Cycle

The sterilization cycle is an interlocked sequence of events and consequent actions under microprocessor control. The steps of this sequence are detailed in the state diagram of FIG. 6 and state output matrix of FIG. 7. These steps are performed by a sequencing program, the flowchart for which is shown in FIGS. 7A and 7B and the details of which are disclosed in the program listing contained in the appendix. Two types of events occur during the sequence, independent and dependent events. Some independent events are external events and include contact input signals to the controller from the controlled valves (e.g., the limit switches), and are referred to by the symbols XOx to X3x in FIG. 3. Each

contact input signal is one bit of an eight bit word and the collection of such control input signals shall be referred to herein generally as digital inputs (DIN). Independent events also include the reception of signals corresponding to measured or analog process values (AIN), such as pressure, temperature, humidity and sterilizing gas concentration. The measured value signals are associated with logical comparison operations performed by the controller. Other independent events are internally declared, and these typically result in the illumination of an indicator light on the display panel, shown in FIG. 5. The controller evaluates the dependent events, which are logical combinations of independent events, to single TRUE or FALSE results. When the dependent event becomes true, a corresponding action is performed, i.e. the control system moves to a new process state, defined by the state output matrix of FIG. 7. If the dependent event is not true, the controller holds the process state in its memory and waits for a period of 50 milliseconds before reevaluating the dependent event. In the case of a system failure, the system automatically transfers to an appropriate ABORT state immediately, as will be described in greater detail below. This process continues until the cycle has been completed or aborted.

Safety Considerations

The sterilization system is provided with a number of checks to insure correct operation of the various valves and other components. As will be described in more detail below, interlock software implemented by the controller main timing program confirms the correct position of all valves every 6250 microseconds. An alarm condition is declared any time a valve is not in its commanded state. The operation of these interlocks differs from typical relay logic, or programmable logic controllers, in that interlock checking continues after

valve actuation has taken place and can lead to different failure programming (ABORT states) at each process stage. The correct status of a valve is latched into memory after actuation is confirmed, and this latched condition is checked every 6250 microseconds. FIG. 8 is a block diagram of the safety-interlock components necessary to perform this checking routine. Failure to pass either an initial event-timeout condition following actuation or any subsequent status check will result in abnormal termination of the sterilization cycle. A sequence of control actions for safe termination of the cycle is defined for every point in the sterilization cycle, and is initiated immediately in the event of any abnormal (ALARM) process condition. This intensive status checking according to the invention prevents deliberate bypassing of the interlock switches in the field, since if a limit switch is bypassed, at some point in the system cycle the switch will be determined to be in an improper position, thus causing the system to enter an ABORT state.

As shown in FIG. 8, the safety interlock system includes a Sequencing Program 120 stored in internal memory (ROM) of the electronic controller. Sequencing program 120 is identified in a listing of the program resident in memory attached hereto, as SEQ and the flowchart for this program is shown in FIGS. 7A and 7B. Also stored in memory is a Contact Status Check program 122 and a series of masks 124 which are determined by the particular point in the sequence program. The Contact Status Check program is identified in the appendix as CSC and a flowchart therefor is shown in FIGS. 18 and 19. Inputs 126, which are images stored in memory of actual input signals from both "open" limit switch contacts 127 (closed when a valve is open and open when a valve is closed) and "closed" contacts 129 (closed when a valve is closed and open when a valve is open) are provided, as well as inputs from other components, such as the sterilizing chamber 10 door 11. A series of contact outputs 125 are also provided by the particular state of the sequencing program. The Contact

Status Check program 122 compares the contact inputs with the contact outputs 125. Whenever an input differs from the desired value, as established by the output, an alarm condition is declared if, and only if, a corresponding bit is turned on in the Mask 124. This safety feature detects any incorrect valve position immediately. A hardware implemented watchdog timer 132 is utilized to provide an extra level of safety by disabling all outputs to the valves 130 by opening electronic switches 134 when the timer times out if the microprocessor controller should fail, thereby preventing energization of any of the valves in the valve and pump block 20 in the event of a computer failure.

FIGS. 7A and 7B are a flowchart for the sequencing program SEQ. The sequencing program is entered from another program, called the Main Dispatching Program, which essentially checks for flags generated at appropriate time intervals and which determines when specific functions should be performed. As shown in FIG. 7A, when the sequencing program is entered, the current state of the system is retrieved from memory, as shown at 180. The current state is stored in a register 210a in internal CPU RAM, as shown in FIG. 12. The organization of internal CPU RAM will be discussed in more detail in connection with FIG. 12 later. At 182, a check is made to determine if the state exceeds the maximum state number. If it does, an ABORT state, state 31, to be discussed in more detail in connection with FIG. 6, is entered at 184. Otherwise, the conditions for the next state are performed at 186 by entering the program ST, the flowchart for which is shown in FIG. 7B.

As shown in FIG. 7B, program ST first evaluates each dependent event to a single true or false result, as shown at 188 and 189. Each dependent event is a logical combination of a number of independent events, each of which must be specified if the dependent event is true. If the dependent event is not true, a hold flag (FØ) in a memory location in the

microprocessor internal RAM (see FIG. 12) is set at 190. Otherwise, the next state is set at 192 and a new ABORT state, if a new ABORT state is required, is set, but not entered, at 193.

At 194, the timeout for the previous event must be disabled so that the timeout will not cause an alarm condition to be generated, which could cause an ABORT state to be reached. Timeouts are provided by program implemented timers, which monitor for the occurrence of a specified action, e.g. the movement of a valve, within a preset time defined by the timer. If the specified action has occurred, the timeout must be disabled because the timer continues to run. In order to disable the timeout, as shown in FIG. 18, a flag in the Timer Counter Enable Register (TCEN) 207 in internal RAM (FIG. 12) is cleared. In this way, when the flag for the timer is set into the Timer Counter Flag Register (TCFL) 206 (FIG. 12) when the timer runs out, no alarm will be generated. If a timeout alarm is generated, a bit TMOF is set in the STATUS register, as shown in FIG. 18.

At 195, the masks are cleared, i.e., bits corresponding to the particular events which are to take place are set to a "don't care" condition, so that the change of the corresponding bits in the contact outputs do not set off an alarm condition by the contact status check program. At this point, the action may be performed, as shown at 196. Subsequently, the timeout count for the action is loaded into the appropriate one of the timer registers 200 (FIG. 12) as will be explained in more detail later. The action timeout flag is then enabled to monitor for the timely occurrence of the current monitored action as shown at 197. The hold flag FØ is then cleared at 198 and a return is made to the flowchart of FIG. 7A, to the point denoted SEQR.

At 200a, a test is performed to determine if an alarm or timeout condition has occurred. If an alarm or timeout has

occurred, the current state is set to the current ABORT state at 201 immediately. Then, the hold flag FØ is checked at 202 to determine if it has been set. If it has, a return is then made to the background or main dispatching program from which all subroutines are entered. If flag FØ has not been set, the system remains in the sequencing program to continue to the next state and only exits once flag FØ is set.

FIG. 19 shows the contact status check program in more detail. As shown, the contact input status corresponding to the contact inputs are stored in appropriate locations in the internal RAM of the system microprocessor. The memory locations are as indicated. See FIG. 12. The same is done for the contact output status bits, which specify the events to occur for a particular state. The Masks MSK0-MSK3, also stored in internal RAM, are evaluated by the contact status check program. If the contact inputs vary from the contact outputs, an alarm condition is generated by setting a bit in the status register 204, which is a location in RAM (see FIG. 12), but this is only done if the corresponding bit in the Mask is turned on. If the bit is off, indicating that a change of the corresponding output is to be allowed to occur, no alarm will be generated, and the contact outputs will be written into an output buffer, to be described in more detail below, to actuate the appropriate controlled or sequenced component, e.g., a valve or pump, without operating an alarm.

Additional safety features are also provided for in the system. As discussed above, manually actuable valves V9 and V10, operated by service personnel, and auxiliary pump P2 are provided in the event valves V8 and V3 and main pump P1 do not operate properly, thus providing a degree of redundancy. Furthermore, as shown in FIG. 2, safety features are provided to prevent the possibility of excessive temperatures and pressures in the sterilizing chamber 10. A thermally activated switch 11a is provided in series with heater HTØ1 in the chamber to detect excessive temperature. For example,

should the heater HTØ1 fail to turn off, the thermostatic switch 11a will sense an excessive temperature and interrupt the circuit.

Additionally, should excessive pressures develop in the chamber, a pressure relief valve 9 is provided for venting gases in chamber 10 through a second detoxifier 22a to the atmosphere.

Also provided is a check valve 15 in series with valve V4 which supplies sterilizing chlorine gas to the system. Check valve 15 prevents the possibility of nitrogen gas from the nitrogen cannister pressurizing the chlorine gas cannister should valves V4 and V4a fail to close. Check valve 15 only allows chlorine gas to flow out of the chlorine gas cannister and prevents nitrogen gas from flowing into the chlorine gas cannister if valves V4 and V4a fail to close.

Operator Interactions

The apparatus and sterilization cycle of the system according to the invention provide for minimal operator intervention and maximum safety. FIG. 5 shows an embodiment of a display panel for the invention showing the various display lights. Certain lights are provided but not used, for expansion purposes. The sterilization cycle cannot be initiated until the chamber 10 door 11 has been properly closed. The DOOR-OPEN light (LTI) will then be extinguished, as shown by LT01 changing state from a "1" state in state 1 to a "0" state in state 2 of FIG. 7, and the READY-FOR-CYCLE light (LT11) will be illuminated. See also FIG. 5. To start the cycle, the operator merely presses the START-CYCLE (S1) switch (see FIG. 1) when ready. Thereafter, no operator intervention is required until the cycle ends, with illumination of the REMOVE-LOAD light (LT17), or until an alarm condition has halted the cycle. In the latter eventuality, one of the alarm lights indicating the failure will be on. The operator notes which lights are on,

takes the necessary action and then presses the ABORT-RESET (S2) switch when ready to cycle the system back to a defined condition and to avoid the failure condition, if possible. For example, if the PURGE-FAIL light (LT5) is on, due to the possibility of an empty nitrogen tank, the tank should be replaced before pressing the S2 switch. Similarly for other failure modes, an attempt should be made to diagnose and remedy the failure condition before pressing switch S2. The subsequent actions to abort the cycle are then predetermined and automatic. No further operator intervention is necessary. Furthermore, redundancy has been provided in the system so that if a component fails, another component, e.g., a pump or valve, can take the place of the failed component so that the system can be brought out of its failure state.

Control Circuitry Design

The overall design of the electronic control circuitry 100 is shown in FIG. 3. The controller is microprocessor controlled, and preferably utilizes a type 8031, 8051 or 8751 microprocessor CPU 102 manufactured by Intel Corp., because of the ability of these processors to perform Boolean arithmetic on bit addressable data. The CPU 102 includes self contained Random Access Memory (RAM) and Read Only Memory (ROM). Furthermore, the controller may include external ROM 104 and a non-volatile Shadow RAM (SRAM) 106 which may be a type X2210 manufactured by XICOR Inc. and which, as discussed heretofore, stores critical data after power-down. The controller also includes a clock crystal 108, input latch 113 receiving Digital INputs (DIN), an A/D Converter 114 and filter 114a for Analog INputs (AIN), an output latch 117 for Digital OUtputs (DOU), and a WatchDog Timer 112 (WDT). The latter timer is arranged to disable all outputs to the valves to their denergized state upon failure of the microprocessor, as described above with reference to FIG. 8. Analog to digital converter 114 and analog filter 114a, convert the analog inputs from the measured gas concentration, temperature,

humidity and pressure parameters to digital data.

Central processor 102 is coupled to an address/data bus 116, which also couples RAM 106, ROM 104 and a bus tranceiver 105. An address latch 103 is enabled by a line 107 from the CPU/102, and latches addresses to a further bus 109, the Read/Write and Address Bus. Bus 109 allows the DIN Latch 113, A/D converter 114, a time stamp clock 119 and DOU latch 117 to be addressed at the appropriate times during execution of the sterilization sequence program, i.e., when CPU 102 calls for input data from the various valve limit switches, DIN latch 113 is addressed. At other times the A/D converter 114 or DOU latch 117 will be addressed.

Two decoders, a read enable decoder 120 and a write enable decoder 122 are coupled to bus 109 and allow latches 113 and 117 and A/D converter 114 to be either read from or written to. Appropriate read/write commands are coupled on lines 126 for controlling the decoders.

Furthermore, a data bus 124 is also provided for reading data from or to the input and output latches and A/D converter.

Several additional control lines are also employed, including a data bus enable 125 and RAM command lines 127. Line 125 enables bus transceiver 105 only for very short intervals and only during input/output (I/O) subroutines (e.g., subroutines WCO (Write Contact Outputs), RCI (Read Contact Inputs) and RAI (Read Analog Inputs), see appendix), when input and output operations are being performed, e.g., writing output information to DOU latch 117 for controlling the valves. In this way, data on the data bus 124 for actuating the various valves of the valve and pump block cannot be transmitted to the valves except under limited circumstances. This provides an additional degree of system safety. Furthermore, bus transceiver XCVR 105 is bi-directional and the direction of data transfer is controlled by one of the read and write

lines, as shown.

RAM command lines 127 issue signals to shadow RAM 106 so that failures can be logged permanently and other critical data can be stored in the event of a power failure.

A reset line 129 is also provided between the Write enable decoder 122 and watchdog timer 112 and an enable line 130 is provided between timer 112 and DOU latch 117. As previously indicated, timer 112 monitors CPU 102 for proper system operation. Normally, CPU 102 constantly resets the watchdog timer via line 129. In the event of a CPU malfunction, the reset signal will fail to appear in time and the timer 112 times out and removes the output enable signal on line 130. The removal of this signal disables all DOU latch 117 outputs, thus preventing valve energization in the event of a CPU failure. Accordingly, a still further degree of safety has been provided in the system described.

Since the elements of the controller are coupled to data buses 116 and 124, as shown in FIG. 3, they have been assigned memory addresses through which they can be accessed by the microprocessor. FIG. 3A shows one arrangement of these addresses, for reference. As indicated above, certain of the devices, such as the SRAM 106 and DOU latch 117, are provided so that the data they contain can only be changed when bits of the microprocessor port lines are sequenced properly. This is a safety feature which prevents some microprocessor failure modes from causing undesired changes in memory contents or valve positions.

All processor and program timing is derived from the basic clock oscillator 108, which preferably has a frequency of 5.9904 MHz. FIG. 4 illustrates the relationship between the various frequencies used. As indicated in FIG. 3, provision may also be made to add a precision clock 119 to the system, which can be read by way of the data/address bus or via a

serial data communications line 118 to provide a clock-calendar for time-stamping the process data.

As shown in FIG. 4, basic processor timing is provided by the CPU internal crystal controlled clock 108. The clock 108 frequency is divided by twelve by CPU internal counter stages 130 and 132 to provide the CPU Address Latch Enable (ALE) signal of 499,200 HZ. The ALE signal is used to strobe address latch 103 so that addresses can be placed on bus 109 and further controls the operation of A/D converter 114.

Signal ALE is also coupled to further internal divider stages 134 and 136. Divider stage 134 provides a signal designated TIMER 1, which is further divided by an internal counter stage 138 into a 1200 bit/sec signal for serial data transfer, which optionally may be provided to transmit system data to remote locations via serial line 118.

Counter stage 136 provides an interrupt, TIMERO. TIMERO provides a transition every 6250 usecs and allows the main timed function program, TMRO, to read all contact inputs and analog inputs and write all contact outputs every 6250 usecs. The operation of this program and other programs of the operating system will be described in more detail later.

The TIMERO interrupt is then further divided by program TMRO software counter stages 142, 144 and 146, to provide the respective program execution signals designated as TIC, SEC and MIN, which occur at period of 50 msecs, 1 sec and 1 min, respectively. These will be discussed in further detail below.

FIG. 3A details the assignment of addresses on address bus 109. As shown, the bus 109 is a 16 bit bus. Internal CPU RAM is assigned address space 00-FF and bits A0 to A7 on the bus 109 identify the RAM locations. Internal ROM is identified by bits A_0 to A_{15}, with bits A_{12}-A_{15} always being O's, as

shown. Addresses from 0000 to 0FFF are used. The other components, external ROM 104, external RAM 106, clock 119, A/D converter 114, DIN latch 113, DOU latch 117 and watchdog timer 112 are assigned the addresses indicated in FIG. 3A. As shown, the DIN and DOU latches each are capable of latching 4 eight bit words, the DIN latches from the various limit switches and other contact inputs and the DOU latches to the various valves, pumps, etc. Digital inputs DIN and digital outputs DOU are each subdivided into four words of 8 bits each, and all eight bits of each group are accessed at one time by the respective addresses indicated in FIG. 3A.

As shown in FIG. 3, the analog pressure, temperature, humidity and chlorine dioxide gas concentration parameters are fed from respective sensors 114c to respective amplifiers 114d, e, f and g. In order to provide an additional degree of system safety when sterilizing chlorine dioxide gas is being evacuated from the sterilizing chamber, it is important that the chlorine dioxide gas concentration levels be accurately measured. Accordingly, amplifier 114g for the gas concentration signal is switched into a high gain mode by a control signal Y37 during the time when the sterilizing chamber is being evacuated. In this way, A/D converter 114 will compare the input concentration analog signal with a greater number of quantizing levels, thus providing a more accurate indication of the actual concentration. At all other times, amplifier 114g will remain in a low gain mode. For example, when chlorine dioxide levels are being measured in the chamber for purposes of determining an adequate sterilizing concentration, much higher concentration levels are being measured, and accordingly, A/D converter 114 provides an accurate digital signal corresponding to the analog concentration level. Therefore, amplifier 114g can remain in a low gain mode. Amplifier 114g may be switched to a high gain mode by signal Y37 changing from a "0" to a "1".

The system data-base may be thought of as being divided into

external and internal sections. The external data-base contains the Contact inputs (CCI), which are comprised of the digital inputs DIN; the Contact Outputs (CCO), which comprise the digital outputs DOU; and the Analog INputs (AIN). Images of the external data-base are maintained in an internal data base comprising locations in internal RAM by subroutines of the TIMERO program (TMRO), which is invoked every 6250 microseconds. That is, every 6250 microseconds, all contact inputs and analog measurements are read and stored in the controller internal data-base and images of the contact outputs loaded in the DOU latch. With reference to FIG. 12, which is a memory map for the internal data RAM of CPU 102, images of the contact inputs are stored as the variables CCIO through CCI3, and the filtered analog inputs are stored as the variables ADIO through ADI7. The contact outputs are stored as variables CC00-CC03. Programs using the input data retrieve it only from these locations, and not from the input devices directly. Hence, the programs only operate on images of the inputs and outputs. In addition, the internal data-base includes a number of register banks, RBØ-RB3. In RBØ, a number of timers 205 are provided including a 50 msec timer TICK (50 msec), a second timer TSEC (1 sec) and a minute timer TMIN (1 min). These timers provide timed function intervals for scheduling functions implemented at those intervals by the system main dispatching program. The TICK timer times out after 50 msecs and sets a flag TICF in STATUS register 204 to be used by the main dispatching program to initiate all 50 msec timed functions, including a number of timers 200 in register bank RB3 which are invoked every 50 msecs, TTMx. These timers are preferably invoked for monitoring timeout conditions for the system valves, for example.

The TSEC timer similarly times out after 1 sec and sets a flag (SECF) in STATUS register 204, to be used by the main dispatching program to initiate all 1 second timed functions, including a number of timers 200 in RB3 which are invoked every second, STMx. Similarly, the TMIN timer times out after

a minute and sets a flag (MINF) in STATUS register 204 to be used by the main dispatching program to initiate the 1 minute timed functions, including a number of timers 200 in RB3 which are invoked every minute, MTMx. The data memory also includes registers in RB2 for keeping track of the current state and ABORT state used by the sequence program. Also included are the sequence status register 204, TCEN and TCFL registers 207 and 208, already discussed, for the timers, and a control register CTRL for enabling a control calculation to open or close a valve. 4 bits of the control register, as shown, are used for controlling the four control loops of the system, corresponding to the measured temperature, humidity, pressure and gas concentration parameters. An array of bit masks 260 is provided in the internal data-base to permit "don't care" conditions when comparing contact input and output status. Further descriptions of the data elements are found in the controller program source listing in the appendix to this specification.

More particularly, internal RAM of CPU 102 may be organized as follows. The 256 (FF) memory locations are organized into 50 msec, one sec and one minute timers in the timed function registers (memory locations 00 to 07); optional communications program registers (memory locations 08 to 0F) for controlling a receive buffer RBUF and transmit buffer TBUF; main dispatching program registers (memory locations 10 to 17); timers 200 which are implemented at 50 msec, one second and one minute intervals by timers 205 (18 to 1D); (counters 1E and 1F); a status byte 204 (20); a control byte 206 (21); a timer enable byte TCEN (22); a timer flag byte TCFL (23); a series of masks 260 for the inputs; (24-27); the contact output images CC00-CC03 (28-2B); contact input images CCI0 CCI3 (2C-2F); analog inputs ADI0-ADI7 (30-37); and set points for the measured process variables, such as temperature, pressure, concentration and humidity (38-3B). The remainder of the internal RAM is assigned to the communications buffers (4Ø to 5F), the system stack (6Ø to 7F) and internal

microprocessor registers and storage (8Ø to FF), the use of which is known to those skilled in the art. Refer to Microcontroller User's Manual, published by Intel Corp., May 1982, document No. 210359-001. Although the entire system program is contained in internal ROM of the CPU 102, an external ROM may also be provided so as to allow additional programming capabilities. Alongside FIG. 12, the contents of the STATUS, CTRL, TCEN and TCFL registers by bit are shown.

State Sequence

The progress of the sterilization cycle can be determined from the PROGRESS lights on the display panel, shown in FIG. 5. During a normal cycle the failure lights should never be on. Whether normal or aborted, both cycle and failure data will be maintained in a non-volatile random access memory or shadow RAM (SRAM). For example, after a designated number of cycles, e.g. three cycles, the gas cartridges will be discharged and must be replaced. The data concerning the number of cycles in which a cartridge has been used is stored in this memory. Also, after a predetermined number of cycles, or repeated failures, the system will be disabled until maintenance has been performed. This is a safety feature which cannot be bypassed in the field, and this data is also stored in the non-volatile memory.

As discussed, FIG. 6 is a state diagram which defines the operation of the sequencing program of the sterilant system. FIG. 7 identifies the condition of the components identified in FIG. 2 as well as the display lamps shown in FIG. 5 for the various process states. The operation of the system may now be described in further detail.

The system always begins in an initialization state, state 0. During this state, all output lines of the microprocessor in control circuitry 100 are set so as to initially deenergize all valves in the valve and pump block 20. After a short time

delay, valve V7 is opened to allow air into the chamber, as shown by a "1" appearing opposite VV07 for state 0 in FIG. 7. Furthermore, during this state, the control circuitry 100 stores in memory the state of all output ports of the microprocessor.

In states 0 and 1, the door to the sterilizing chamber 10 is in its open position. Once the door is closed, state 2 is entered. As indicated in FIG. 6, this means that the system is ready to begin its cycle. As further indicated in FIG. 7, in state 2, valves V1-V6 are closed, valve V7 remains open and valve V8 is closed. Display lights LT1-LT6 are off, light LT11 (READY FOR CYCLE) is on and lights LT12-LT17 are off. The corresponding limit switches (LS) are in a position determined by the condition of the associated valve, e.g., for valve V2, which is closed, limit switch LS2o is open while limit switch LS2c is made. As indicated above, two limit switches are provided on each valve, one for the open position and one for the closed position, in order to insure the safety of the system. Both limit switches must be in their proper position, otherwise a failure will occur.

When the door to the chamber 10 is open, the system is in state 1, once the initialization state has been passed. Accordingly, only LT1 is on and the other lights are off, as shown in FIG. 7.

Assuming the chamber door has been closed and the system is in state 2, if the START CYCLE switch S1 is pressed, the system moves to state 3. At this point valve V7 closes, as indicated by the "0" appearing in the column for state 3 in FIG. 6 and light LT12, CYCLE IN PROGRESS, turns on. As indicated in FIG. 2, valve V7 vents the chamber 10 via a filter 13 to the atmosphere when open. Thus, the flow of filtered external air into the chamber is stopped when valve V7 closes.

If the door is opened in state 2, an immediate return to state

1 is made.

Once in state 3, and, if V7 is closed, as indicated by the closed state of limit switch LS7c and open state of limit switch LS7o, state 4 will be entered. If valve V7 does not close within a certain time, as determined by a timeout implemented by one of the TIC timers TTMx in RB3 of the data memory, state 29, ABORT-1 will be entered. Furthermore, if an alarm condition occurs, such as the opening of a valve which should be closed, an alarm condition will be generated and the point of failure indicated on the display panel, indicating to the operator that a malfunction has occurred.

Once in state 3, if the chamber door is opened, the cycle will be aborted, as shown in FIG. 6.

Assuming V7 has closed and state 4 has been entered, the chamber heater HTØ1 is turned on, as indicated by the "1" in the column for state 4 opposite HTØ1. If the temperature within the chamber increases to a sufficient level within a time-out period, state 5 can be entered. If not, ABORT-1, state 29, is entered and a return to state 2 is thereafter made when switch S2 is depressed. A safe operating temperature is reached when temperature switch T1 (FIG. 2) is actuated by the temperature of the atmosphere in the chamber reaching the desired temperature. After this occurs, the temperature in the chamber is controlled by turning the heater on and off as required during the cycle, as indicated by the notation "C" in the columns of FIG. 7 opposite "HTØ1".

Once state 5 is entered, valve V1 is opened, in preparation for starting vacuum pump P1 so that the atmospheric contents of chamber 10 can be evacuated. Again, if valve V1 does not open within a timeout period, ABORT-1, state 29 is entered.

State 6 is entered when vacuum valve V1 opens within the timeout interval. At this point, the vacuum pump P1 is

started and light LT13 indicates that evacuation is in process. A timer is started which determines the length of time that the pump remains on.

Once in state 6, the chamber door 11 can no longer be opened, because, at this point in the cycle, the chamber is under a vacuum.

In state 6, the pressure in the chamber is checked to determine if it has been reduced sufficiently so that it is less than or equal to a nominal value, defined as PEVAC. If the pressure is less than PEVAC, then state 7 is entered and valve V1 is closed.

Should the pressure within the chamber be greater than PEVAC after the evacuation time has passed, indicating a less than adequate vacuum level, state 29 is entered. Similarly, if valve V1 does not close within a specified time, state 29 is entered from state 7.

After the valve V1 has been closed in state 7, a leak-hold test is commenced in state 8. If the pressure after a leak-hold time is less than a nominal value PLEAK, state 9 is entered. If not, abort state 29 is entered.

In state 9, water vapor is allowed to enter the chamber, i.e., valve V6 is placed in a controlled open state, as indicated by "C" in FIG. 6, and a determination is made whether the humidity has reached a specified level in a certain time. Should a nominal humidity HNOM not be reached within the specified time, state 30, ABORT-2, will be entered. Since evacuation has been completed, light LT13 is turned off and light LT14, which indicates a FILL IN PROGRESS, is turned on. By FILL is meant the supply of non-sterilizing gases into the chamber, e.g., steam and nitrogen gas. At this point, the system enters a new point in the state diagram wherein malfunctions allow the system to return to a different abort

state, state 30. The state of the various valves and displays for ABORT-2 (state 30) is indicated in FIG. 7.

In state 9, the humidity timer times out. If the humidity level is greater than a nominal value HNOM, state 10 is entered. Otherwise, state 30 is entered and the cycle is aborted.

In state 10, a humidity hold test is performed wherein the humidity level is monitored for a predetermined time period. If the humidity level is not maintained for the predetermined time, state 30 is entered. Otherwise, state 11 is entered. Valves V2 and V8 are opened and valve V5, along with valve V6, is then controlled on.

Valve V5 allows nitrogen to enter the system. At this point, even though valve V2 is open, chlorine dioxide cannot enter the chamber because valves V4 and V4A, which are controlled together, are closed.

In state 11, valve V2 is checked to determine that it has opened. If it has not opened withing a specified time, state 30 is entered. If valve V2 has opened in time, state 12 is entered, and valves V4 and V4A are controlled on, allowing chlorine dioxide to enter the chamber. A timer is started during which time the chlorine dioxide gas concentration levels in the chamber are measured. As explained previously, chlorine dioxide may be generated by the reaction of two components, Cl_2 gas and sodium chlorite, Na_2ClO_3, on site. Chlorine gas is contained in a canister which can be coupled to the system via a connecting port, as known in the art. A container of sodium chlorite is coupled into the system between valve V2 and valve V4, as shown in FIG. 2. In state 12, LT14 is turned off and LT15, STERILIZATION IN PROGRESS, is turned on.

Once the gas concentration measured in state 12 has reached a

concentration greater than or equal to a nominal concentration CNOM within a preset time period, state 13 is entered. An acceptable sterilizing gas concentration might be, e.g., 1.0 mg/L to about 300 mg/L. Otherwise a new abort state, ABORT-3, state 31, is entered. This new abort state is necessary because new conditions are now present in the sterilization chamber, since sterilizing chlorine dioxide gas is now present in the chamber. This requires a different set of procedures to be followed in the event of a failure, and accordingly, a new abort state is provided.

In state 13, a gas-hold test is commenced. If the gas concentration is greater than or equal to CNOM for a predetermined time period GTMR, state 14 is entered. Otherwise, state 31 is entered and the cycle is aborted.

In state 14, the temperature in the chamber is measured. If it is greater than a minimum temperature TMIN but not higher than a maximum temperature TMAX, state 15 is entered and a sterilization timer is started. If the temperature is not adequate, state 31 is entered and an abort occurs. A typical operating temperature is approximately 30˜C.

During state 15, sterilization is in progress. Valve V6, for humidity control, is still controlled open, and valves V4 and V4A are also controlled open. Should an alarm condition occur, e.g., if any condition changes, i.e., a valve does not remain in its proper state, state 31 is entered. State 16 is entered only after a sterilization time STMR has elapsed, which typically might be several hours.

In state 16, valves V4, V4A and V6 are closed (if they do not close in the required timeout period, state 31 is entered), valve V3 is in a controlled state and valve V8 is still open. In state 17, light LT15 is turned off and light LT16 is turned on. Light LT15 is turned off when the sterilization timer has timed out and valves V4, V4A have closed. Light LT16

indicates that a purge is in progress. During state 17, the gases in the chamber are removed via valves V3 and V8 and detoxifier 22, labelled DUMP 22 in FIG. 2, which converts the chlorine dioxide into a harmless substance. The detoxification may be accomplished as explained in the above copending patent application S.N. 601,443, by passing the evacuated chlorine dioxide gas through a reducing agent, e.g., sodium thiosulfate. The detoxified gases are removed via valve V8 by vacuum pump P1. Should valves V3 and V8 fail to open within a timeout period, ABORT-3, state 31, is entered. During state 17, an evacuation timer is started which controls the amount of time during which chamber 10 is evacuated. State 18 is entered only if both valves V3 and V8 have opened in a predetermined time interval.

In state 18, once the evacuation timer has timed out past a time ETMR, state 19 is entered and valves V3 and V8 are closed. State 20 is entered when valves V3 and V8 close.

As shown in FIG. 6, should an alarm condition occur or should valves V3 or V8 fail to close within a specific time, state 31 is entered.

In state 20, valve V5 is in a controlled state. This allows nitrogen gas to enter the system as required and also prepares the system for the removal of any remaining sterilizing gases behind valve V2 via detoxifier 22 once valve V3 is reopened in state 22. In state 20, the pressure is checked. If it is greater than a maximum pressure PMAX, valve V5 is closed in state 21, turning off the nitrogen supply. If the pressure is less than PMAX, a new abort state, ABORT-4, state 32, is entered.

In state 21, valve V5 is checked to determine that it has closed within a prescribed timeout period. If it has not, state 32 is entered and the cycle is aborted. In state 22, the remaining sterilizing gases in the system are detoxified

via detoxifier 22 and reopened valves V3 and V8 and the gases removed. Once valves V3 and V8 have opened for a sufficient period of time, state 23 is entered but only if valves V3 and V8 have opened. In state 23, another timer, denoted the DESORB timer, is activated. This allows sterilizing gases which have been absorbed into the materials in the chamber to be removed or desorbed over a time period DTMR.

Should valves V3 and V8 fail to open, ABORT-5, state 33, is entered. In this circumstance, the operator will be instructed to manually activate valves V9 and/or V10 so that sterilizing gas can be removed from the system. The manually operable nature of valves V9 and V10 is indicated in FIG. 2 by a T above the valve symbols. If valves V9 and V10 are manually opened, state 33, ABORT-5 will automatically be entered.

If state 23 is successfully reached and the DESORB timer times out after a time DTMR, state 24 will be entered. At this point, valves V2, V3 and V8 are closed and a check is made to determine that these valves are closed. Then, state 25 is entered, during which a low-gas-hold test is performed. If the gas concentration is less than or equal to an acceptable value CMIN within a time period GHTM, state 26 is entered. An acceptable level of safety might be, for example, less than .5 ppm of chlorine dioxide. Otherwise, a dummy state 35 is entered, before a return is made to state 20 by operation of switch S2. This provides a delay time in which to open valves.

In state 25, the gain of amplifier 14g (See FIG. 3) is changed so that the amplifier is placed in a high gain mode during the measurement of chlorine dioxide gas concentration levels during evacuation. This is indicated by the "1" in state 25 opposite GC1 (gain change control). This provides more accurate measurement of concentration levels during evacuation, providing an extra degree of system safety, as

discussed previously. Also, in state 25, a counter CNT (see RB3 of FIG. 12) is decremented. This counter forces the system to cycle through states 25, 20, 21, 22, 23 and 24 via state 35 for a specified number of times determined by the initial count in the counter CNTØ. Accordingly, state 35 will be entered whenever the concentration level CMIN has not been reached within time GHTM or if the counter CNT has not reached Ø. State 26 will be entered from state 25 when both the concentration is less than CMIN and CNTØ is Ø. This is provided to insure system safety in the event the concentration sensor in the sterilizing chamber should fail. By going through a number of cycles via state 35, the gas concentration will be decreased, thus insuring that, even if the concentration sensor indicates the gas concentration levels are below CMIN, the system will automatically cycle through a number of times necessary to reduce the concentration to acceptable safety levels. This is important, because if the concentration sensor failed and this additional safety feature was not provided, the system might indicate that the gas concentration level was within acceptable levels of safety although it actually might not be.

In state 26, a counter is checked which is incremented each time the system cycles at least to step 26. If, e.g., the count is less than 3, a jump is made to state 28. If greater than or equal to 3, state 27 is entered. In state 28, valve V5 is controlled on, and the count is then incremented. This allows nitrogen gas to enter the chamber.

If the cycle count is greater than or equal to 3, then state 27 is entered directly. In state 27, valves V2, V3, V4 and V8 are opened, and all remaining gas is dumped from the system and the Cl_2 gas in the cartridge is also dumped. Once sufficient time has elapsed, i.e., the Dump Hold time DHTM has elapsed, state 28 is entered. From state 28, the system enters state 37, during which the pressure in the chamber is monitored until it is within 5% of atmospheric pressure. At

this point light LT17, REMOVE LOAD, is turned on. At this point, state 38 is entered, light LT11 is turned on and actuation of switch S2 enables a return to state 1. The operator will be notified to replace the gas cartridge if the system has gone through state 27.

As indicated in FIGS. 6 and 7, after ABORT states 29 and 30 are entered, a return is made to state 2 after switch S2 is depressed and state 2 conditions are set.

In ABORT state 31 a return is made to state 20 and state 20 conditions are set once switch S2 is depressed. In ABORT state 32, return is made to state 19, and state 19 conditions are set. In ABORT states 33, 34, and 36, return is made to states 23, 25 and 37, respectively. If state 38 is reached, the operator receives an indication that the cycle is complete and light LT17 is turned on. To allow the chamber door to be opened, switch S2 is actuated, and state 1 is entered. If any ABORT state is reached, the appropriate failure light is illuminated. When a return is made to states 20, 23, or 26 from an ABORT state, the system then proceeds to cycle through the states which normally follow in the sequence.

General Software Functions

The sequencing program has already been described. Generally, software for the sterilization system controller is interrupt driven. Until an interrupt occurs a background task is always running via the main dispatching program. Upon interrupt, from any of several possible event sources, software control is passed to the appropriate interrupt handling program. This is illustrated in FIG. 9.

In FIG. 9, the main dispatching program 300 is shown. This program can also be found under this heading in the program listing attached hereto. Essentially, this program monitors for the occurrence of a timer flag indicating 50 msec, 1 sec

or 1 minute functions must be performed. These flags are stored in the status register (STAT) 204 of FIG. 12. When a flag occurs, the program 300 jumps to the appropriate timer program 318, 300 or 322. The timer programs are performed on a priority basis such that one minute functions are performed first and 50 msec (T50) functions last.

There are four sources of interrupting events: power-up, timer, communications, and power-down. Power-up, power-down and communications are external hardware interrupts, while the timer interrupt, TMRO, is an internal hardware interrupt under program control. Except for power-up, each interrupt handling program saves the running processor context in the CPU stack before starting its task function, and the context is restored before resumption of the interrupted program. The timer interrupt handler (TMRO) sequences all other non-interrupt programming functions. As discussed, it accomplishes this by passing one or more flags (MINF 312, SECF 314, TICF 316), signifying which of the timed tasks is to run, through the STATUS register 204 of FIG. 12. The main dispatching program 300 tests the flags and will cause the selected functions to be executed as shown by 318-322. This method permits further interrupt action while lower priority functions are being completed. Some of the functions performed at one minute, one second and 50 msec (TIC) intervals are as indicated in FIG. 9 at 318, 320 and 322, respectively. The descriptions to follow will explain the tasks to be performed under each category of interrupt event in greater detail.

Main Dispatching Program

Essentially, the main dispatching program looks for timer flags and when one is found, calls the appropriate subroutine. See FIG. 9. The main dispatching program may be found in the attached program listing.

Power Up

Upon power-up as shown at 310, the processor stack, register bank, and other functions must be initialized. This interrupt function does not require saving of the processor context. Instead, previous process information will be read from the electrically reprogrammable memory SRAM 106, the clock 119 is reset and the process will resume from whichever state has been prescribed. The watchdog timer will be reset, and control will then pass back to the main dispatching program 300.

The power-up routine is found in the program listing under the program title INIT.

Power Fail

A power fail program is preferably implemented. One embodiment for this program, as shown in FIG. 9, stores critical memory contents at 312 into the SRAM 106, where the data will be preserved until power is restored. The power-fail interrupt may be designed to occur whenever the 5 volt logic line drops below 4.55 volts, and recovery to 4.75 volts may be utilized for power-up. The power fail program can be found in the attached program listing.

Communications

A communications feature (COM) may optionally be provided in the system according to the invention. The communications program is activated every time a character is removed from a serial output buffer or enters a serial input buffer. The function of this program is to feed characters to the transmit buffer as they are sent and to remove characters from the receive buffer as they are received. Two FIFO queues may be provided to hold the input and output data streams. The communications program tests the input and output data streams

for the presence of termination or control characters. Flags are set in the event of termination characters. Programs, well known in the art, may be provided for processing control characters for typical serial interface devices connected to the control circuitry. For example, it may be desirable to transmit information for recording purposes over telephone lines to a printer or display device. Other programs, known in the art, can be employed to handle the standard modem control functions, e.g., RS232C commands. Hardware I/O lines may be provided for the necessary modem control signals. The communications program saves and restores the processor context.

Timed Functions

Timed functions in the controller occur on four levels as follows: functions triggered by the TIMER0 timer (every 6250 microseconds), functions initiated every 50 milliseconds (TICS), functions started every second, and functions which run every minute. Data is exchanged between these levels through defined data areas in the microprocessor data-base, as indicated more clearly in FIG. 10. The TMRO program also accesses the input and output devices connected to the controller. The control function (CTR), which is activated every second, transmits valve commands to the upper four bits of the CTRL register when enabled by the lower four bits of the CTRL register on a bit by bit basis, as shown in FIG. 24.

As shown in FIG. 4, timer interrupts (TMRO) occur at intervals of 6250 microseconds (6.25 milliseconds). At each interrupt, the TMRO program is entered, and all timed functions are scheduled. As the basic cycle time of the processor is approximately two microseconds, 3120 instruction cycles will elapse before the next such interrupt. Some of this time is used at each timer interrupt to perform data gathering and interlock functions, e.g. the analog inputs and data inputs are read and stored in CPU internal RAM. This is indicated at

330 in FIG. 9. Immediately following a timer interrupt the processor context will be saved in the appropriate registers. The interrupting timer, TIMER0, will then be reset and restarted. Program functions which are to occur at intervals of 50 msec., 1 sec., and 1 min. will be scheduled as shown at 332, by passing flags, as discussed, whenever the respective time interval has elapsed. Data inputs, status checks, and outputs are performed next. Finally, the previous program context is restored, and an interrupt return is executed. If any timed events are to occur, they will be performed in sequence by the main dispatching program. Otherwise the main disptaching program will be resumed.

The basic timer program, which is executed for each timer, is shown in the flowchart of FIG. 22. As shown, the timer is first decremented and a check is made to determine if the timer has timed out, i.e., reached a count of 0. If so, the corresponding timer flag is set in TCFL register 208 shown in FIG. 12. If not, the corresponding flag is cleared. Then the program is executed for the next timer, and once all timers have been completed, a return is then made to the main dispatching program.

The decrement timer function is shown in FIG. 23. As shown, when a timer is decremented, a flag is set in the TCFL register if the time has timed out, and the current count is then stored in the appropriate timer register 200.

1. TIMERO Timer (TMR0)

The lowest level timed function, occurring every 6250 microseconds, is initiated by the interrupt TIMER0. This is indicated in the uppermost portion of FIG. 10, which is a flowchart for the various timed functions. After saving the processor context, the first function of the TMRO interrupt program is to reset and restart the timer as indicated at 400. This is performed by a subroutine RRT. In FIG. 10, the

corresponding program for implementing the desired function is indicated above the flowchart symbol, and can be found in the listing in the appendix. The TMRO program is a time-critical function. Once the timer has been restarted, all of the contact inputs to the controller are read into their corresponding memory images, CCI0 - CCI3 as shown at 410 and 412. These images reside in a portion of the microcomputer memory which is bit addressable. This greatly facilitates logical processing. The subroutine for implementing this function is shown in FIG. 17 and is also shown in the attached program listing as subroutine RCI. The contact output information is also located in this memory, at CCO0 - CCO3 and is indicated in FIG. 10 at 425. The interrupt program next performs a masked comparison of the contact input and output status bits, using bit masks 415 also stored in this memory area. This is shown at 420. If any bits do not match their corresponding desired outputs, when masked for "don't care" conditions, an alarm condition is set by setting a bit in the STATUS register 204 (FIG. 12), as shown at 430.

Timeout alarms are also implemented by the TMRO program. A subroutine CSC2, as shown in FIG. 18 and the attached program listing, shows how timeouts are determined. When a timer times out, e.g., a timer for determining whether a valve has closed or opened in time, a flag will be set in the timer flag register TCFL. If the setting of the flag requires an abort upon failure, e.g., if the failure of a valve to close in time is to cause an abort condition, then a flag must be set in the timer enable register TCEN. This informs the timeout alarm program that an alarm condition should be set, which will cause the alarm condition to be loaded into the STATUS register. This will cause transfer to an ABORT state by the sequencing program.

Next the current contact output status is loaded from its memory image into the output contact latch by program WCO, as shown at 435. Finally, as shown at 440 and 445, the current

analog input data 445 is read (RAI), exponentially filtered (FILTER), and stored in the correct memory locations outside the bit addressable space. See FIG. 21. Eight timer interrupts take 50 milliseconds. Thus, a well-filtered analog input scan of all eight analog inputs (only four need be used for the four control loops corresponding to gas concentration, pressure, temperature and humidity) will be available each time the 50-millisecond program is entered. Therefore, every 50 msecs, the RAI program obtains 64 input samples, 8 for each channel, the eight samples for each channel then being averaged to obtain a single analog value for each channel. A return is then made to the main dispatching program. The TIMER0 program is summarized in the flowchart of FIG. 11.

2. TIC Timer (T50)

The TIC functions are those which are performed every 50 milliseconds, and include the performance of the sequencing (SEQ) program. The first function performed is that of resetting the watchdog timer as shown at 500, because if this timer is not reset in time, all valve outputs will be disabled as described with reference to FIG. 8. Next, all tick timers (TTM) are decremented at 510, their counts stored at 512, and their corresponding status flags set or cleared at 520 in register TCFL 208 of FIG. 12. The setting of the timeout flags in the TCFL register 208 (See FIG. 12) also requires that the status of a corresponding bit be determined in the Timer Counter Enable Register (TCEN) 207 by the sequencing program, as shown. In this way, if the corresponding TCEN bit is not set, this informs the controller not to enter an ABORT state when the timer flag comes on. For example, when the sterilization timer times out (approximately after 4 hours), an ABORT state should not be entered. For valve time-outs however, it is desired to abort if the timer times out and the valve has not opened or closed in time, and accordingly, the corresponding TCEN bit will be set by the sequencing program, thus allowing an alarm to be generated. If the valve closes

in time, its corresponding TCEN bit will be disabled, and no alarm will be generated. Once the TICK timers have been decremented, the main sequencing logic 515 (SEQ), which controls the progression from one state to the next described hereinabove, is performed until it cannot progress further, due to a hold for a specified status condition not yet present. Then, the outputs are loaded into the contact output image in memory (CCO) at 530, e.g., the output data for the appropriate valves or heater to be controlled are stored in memory. Then, the TMRO program subroutine WCO will write the output images to the controlled devices on its next pass. The TIC function program is summarized in the flowchart of FIG. 13.

3. Second Timer (T1S)

Every second all one-second timers are decremented at step 550, the count stored at 552, and their corresponding status bits set or cleared (555). This includes the setting of flag bits (TCFL) and appropriate Timer Counter Enable bits (TCEN) depending on whether an ABORT is to occur at the occurrence of the timer flag. Finally, the control program 559 (CTR), accepting setpoints (557) from the sequencing program 515, loads the new output status for the controlled devices into the CONTROL register for subsequent loading into the contact output registers of internal RAM. During the next pass through the TMRO program, these outputs are fed to the controlled devices. As shown in FIG. 8, the timed functions occur in the order MIN, SEC and TICK. A flowchart for the one second program, T1S, is shown in FIG. 14.

As shown in FIG. 14, the first function for the one second timer program includes the clearing of the one second flag (SECF) in the STATUS register (see FIG. 12) . All one second timers are then decremented, as shown in FIG. 23 and at 600 in FIG. 14. Program TIS then obtains the loop status from the sequencing program at 602, and determines if the corresponding

control bit in the CONTROL register 206 for the particular loop has been enabled at 604. Each loop corresponds to one of the four measured analog process variables, pressure, temperature, humidity and gas concentration. This is also shown in FIG. 24. As indicated, the lower four bits of the CONTROL register 206 correspond to the status of the four loops. If the loop is enabled, a value is determined by subtracting a measured input value, e.g., gas concentration or pressure, from a stored set point value from the sequencing program, as shown at 606. If this value is greater than 0, a corresponding one of the four upper bits in the CTRL register is set at 607. If the CTRL register bit is 0, then the corresponding CONTROL register bit is cleared, as shown at 608.

At 610, the program gets the next loop and repeats steps A-X for that loop. Then the next two loops are obtained and steps A-X repeated sequentially for those two loops. When all four loops have been performed, a return is made to the main dispatching program.

The interrelationship between the analog input data, set points, control register, control program (CTR), output loading program (CTL) and contact outputs CCO are shown in FIG. 24. As shown, program CTR retrieves analog input data ADI, setpoints SP and the control register (CTRL) status from memory. The new status for the control register is then determined in accordance with the flowchart of FIGS. 14 and the new status loaded into the CTRL register. Program CTL then loads the appropriate outputs for controlling the valves and heater into the appropriate contact output register in memory. During the TMRO program these outputs are then coupled to the controlled devices by the program WCO. See FIGS. 10 and 20.

4. Minute Timer (T1M)

At one-minute intervals, an optional batch time clock 119 may be updated as shown at 610. This clock may be used to initiate the display of process conditions by an appropriate printing or display device. All one-minute timers are decremented at 620, and their corresponding status bits are set or cleared at 630. The T1M program is summarized in the flowchart of FIG. 15.

A sample listing of the software for the gas sterilant system according to the invention is appended below.

```
$TITLE(PROGRAM FOR SC1 STERILIZATION CONTROLLER)
;
;
;*****************************************************************
;*       CONSTANT DEFINITIONS                                    *
;*                                                               *
;*****************************************************************
MCHAN    EQU      07H                ;MAX A/D CHAN NUMBER
CHMSK    EQU      07H                ;A/D CHANNEL MASK
BNK0     EQU      00H                ;RB0
BNK1     EQU      08H                ;RB1
BNK2     EQU      10H                ;RB2
BNK3     EQU      18H                ;RB3
STATE    EQU      R6                 ;CURRENT STATE
ABORT    EQU      R7                 ;ABORT STATE
SSTA     EQU      0                  ;SRAM OFFSET FOR STATE
SABO     EQU      2                  ;SRAM OFFSET FOR ABORT
SCNT     EQU      4                  ;SRAM OFFSET FOR COUNT
SMAX     EQU      38                 ;MAX. VALID STATE
VDLY     EQU      8                  ;VALVE DELAY (400 MSEC.)
HDLY     EQU      2                  ;HEATER DELAY (2 MIN)
TVAC     EQU      30                 ;EVAC TIME (30 MIN)
LKHT     EQU      5                  ;LEAK HOLD TIME (5 MIN)
PVAC     EQU      242                ;EVAC PRESSURE (95% FS)
PRLK     EQU      223                ;PRESS. LEAK LIM. (80% FS)
HUMT     EQU      30                 ;HUMIDIF. TIME (30 MIN.)
HNOM     EQU      207                ;NOM. HUM. LEVEL (81% FS)
HUMH     EQU      90                 ;HUM. HOLD TIME (90 MIN.)
TLOW     EQU      0                  ;MIN. STERIL. TEMP.(0% FS)
TMAX     EQU      255                ;MAX. STERIL. TEMP.(100%)
CNCT     EQU      15                 ;CONC. TIME (15 MIN.)
CNOM     EQU      64                 ;NOM. STERIL. CONC.
CONH     EQU      100                ;GAS HOLD TIME (100 MIN)
TSTR     EQU      200                ;STERIL. TIME (200 MIN)
TEVC     EQU      30                 ;EVAC. TIME (30 MIN.)
PN2T     EQU      15                 ;N2 PRESS. TIME (15 MIN)
DSRB     EQU      30                 ;DESORB. TIME (30 MIN)
TLGH     EQU      15                 ;LOW GAS HOLD TIME (15)
CNTM     EQU      5                  ;MIN. NO. OF PURGE CYCLES
CMIN     EQU      25                 ;MIN. CONCENTRATION (10%)
PATM     EQU      12                 ;ATM PRESS. (5% FS)
PMAX     EQU      28                 ;MAX OPER. PRESS. (11% FS)
TDMP     EQU      15                 ;DUMP HOLD TIME (15 MIN)
PSP1     EQU      60                 ;PRESSURE SETPOINT
TSP1     EQU      60                 ;TEMPERATURE SETPOINT
HSP1     EQU      60                 ;HUMIDITY SETPOINT
CSP1     EQU      60                 ;CONCENTRATION SETPOINT
;
;
```

```
;*****************************************************************
;*        EXTERNAL DEVICE ADDRESSES
;*
;*****************************************************************
;*        EXTERNAL SHADOW RAM
SRAM      XDATA     2000H                ;SHADOW RAM ADDRESS
;
;*        ANALOG INPUTS
IN0       XDATA     6000H                ;CHAN-0 ADDRESS (PRESS.)
IN1       XDATA     6001H                ;CHAN-1 ADDRESS (TEMP.)
IN2       XDATA     6002H                ;CHAN-2 ADDRESS (HUM.)
IN3       XDATA     6003H                ;CHAN-3 ADDRESS (CONC.)
IN4       XDATA     6004H                ;CHAN-4 ADDRESS
IN5       XDATA     6005H                ;CHAN-5 ADDRESS
IN6       XDATA     6006H                ;CHAN-6 ADDRESS
IN7       XDATA     6007H                ;CHAN-7 ADDRESS
;
;*        CLOCK PORT
CLK       XDATA     4000H                ;CLOCK ADDRESS
;
;*        CONTACT INPUTS
X0        XDATA     0C000H               ;CCI-0  ADDRESS
X1        XDATA     0C001H               ;CCI-1  ADDRESS
X2        XDATA     0C002H               ;CCI-2  ADDRESS
X3        XDATA     0C003H               ;CCI-3  ADDRESS
;
;*        SWITCHES
SW1       XDATA     0C004H               ;SWITCH ADDRESS
;
;*        CONTACT OUTPUTS
Y0        XDATA     0E000H               ;CCO-0  ADDRESS
Y1        XDATA     0E001H               ;CCO-1  ADDRESS
Y2        XDATA     0E002H               ;CCO-2  ADDRESS
Y3        XDATA     0E003H               ;CCO-3  ADDRESS
;
;*        WATCHDOG TIMER
WDT       XDATA     0E004H               ;WATCHDOG RESET ADDRESS
```

```
;*****************************************************************
;*        DATA-BASE ALLOCATIONS
;*
;*****************************************************************
        DSEG
        ORG     05H
TICK    DS      1       ;TIME COUNTERS
TSEC    DS      1       ;TICK COUNT
TMIN    DS      1       ;SEC. COUNT
        ORG     0CH     ;MIN. COUNT
RPUT    DS      1       ;SIO BUFFER POINTERS
RTAK    DS      1       ;RCV PUT POINTER
TPUT    DS      1       ;RCV TAKE POINTER
TTAK    DS      1       ;XMT PUT POINTER
        ORG     18H     ;XMT TAKE POINTER
TTM0    DS      1       ;TIC TIMERS
TTM1    DS      1       ;TTIMER-0
        ORG     1AH     ;TTIMER-1
STM0    DS      1       ;SECOND TIMERS
STM1    DS      1       ;STIMER-0
        ORG     1CH     ;STIMER-1
MTM0    DS      1       ;MINUTE TIMERS
MTM1    DS      1       ;MTIMER-0
        ORG     1EH     ;MTIMER-1
CNT0    DS      1       ;COUNTERS
CNT1    DS      1       ;COUNTR-0
        BSEG            ;COUNTR-1
        ORG     20H
STAT    DATA    20H     ;INTERNAL BIT SPACE
CTRL    DATA    21H     ;STATUS BYTE
TCEN    DATA    22H     ;CONTROL BYTE
TCFL    DATA    23H     ;TIMER/COUNTER ENABLES
MSK0    DATA    24H     ;TIMER/COUNTER FLAGS
MSK1    DATA    25H     ;OUTPUT MASK REGISTER
MSK2    DATA    26H     ;OUTPUT MASK REGISTER
MSK3    DATA    27H     ;OUTPUT MASK REGISTER
        ORG     28H     ;OUTPUT MASK REGISTER
CCO0    DATA    28H     ;IMAGED I/O BITS
CCO1    DATA    29H     ;OUTPUT PORT 1
CCO2    DATA    2AH     ;OUTPUT PORT 1
CCO3    DATA    2BH     ;OUTPUT PORT 2
CCI0    DATA    2CH     ;OUTPUT PORT 3
CCI1    DATA    2DH     ;INPUT PORT 0
CCI2    DATA    2EH     ;INPUT PORT 1
CCI3    DATA    2FH     ;INPUT PORT 2
        DSEG            ;INPUT PORT 3
        ORG     30H
ADI0    DS      1       ;ANALOG DATA IMAGE
ADI1    DS      1       ;PRESS. INPUT
ADI2    DS      1       ;TEMP. INPUT
ADI3    DS      1       ;HUM. INPUT
ADI4    DS      1       ;CONC. INPUT
ADI5    DS      1       ;CHANNEL 4 INPUT
ADI6    DS      1       ;CHANNEL 5 INPUT
ADI7    DS      1       ;CHANNEL 6 INPUT
                        ;CHANNEL 7 INPUT
```

```
        ORG     38H
STPO    DS      1       ;INTERNAL DATA AREA
STP1    DS      1       ;PRESS. SETPOINT
STP2    DS      1       ;TEMP. SETPOINT
STP3    DS      1       ;HUM. SETPOINT
        ORG     3CH     ;CONC. SETPOINT
TIME    DS       1      ;BATCH TIME CLOCK
;                       ;BATCH TIME
```

```
;*****************************************************************
;*      DATA DEFINITIONS
;*
;*      [STATUS & CONTROL]
;*
;*****************************************************************
;       STATUS
TICF    BIT     STAT.0      ;TICK FLAG
SECF    BIT     STAT.1      ;SECOND FLAG
MINF    BIT     STAT.3      ;MINUTE FLAG
RCVF    BIT     STAT.4      ;RCV FLAG
XMTF    BIT     STAT.5      ;XMT FLAG
TMOF    BIT     STAT.6      ;TIMEOUT FLAG
ALMF    BIT     STAT.7      ;ALARM FLAG
;
;       CTRL
CEN0    BIT     CTRL.0      ;PRESS. LOOP ENABLE
CEN1    BIT     CTRL.1      ;TEMP. LOOP ENABLE
CEN2    BIT     CTRL.2      ;HUM. LOOP ENABLE
CEN3    BIT     CTRL.3      ;CONC. LOOP ENABLE
CTR0    BIT     CTRL.4      ;PRESS. LOOP OUTPUT
CTR1    BIT     CTRL.5      ;TEMP. LOOP OUTPUT
CTR2    BIT     CTRL.6      ;HUM. LOOP OUTPUT
CTR3    BIT     CTRL.7      ;CONC. LOOP OUTPUT
;       TCEN
TEN0    BIT     TCEN.0      ;TT0 ENABLE
TEN1    BIT     TCEN.1      ;TT1 ENABLE
TEN2    BIT     TCEN.2      ;ST0 ENABLE
TEN3    BIT     TCEN.3      ;ST1 ENABLE
TEN4    BIT     TCEN.4      ;MT0 ENABLE
TEN5    BIT     TCEN.5      ;MT1 ENABLE
TEN6    BIT     TCEN.6      ;MT2 ENABLE
TEN7    BIT     TCEN.7      ;MT3 ENABLE
;
;       TCFL
TFL0    BIT     TCFL.0      ;TT0 TIMEOUT
TFL1    BIT     TCFL.1      ;TT1 TIMEOUT
TFL2    BIT     TCFL.2      ;ST0 TIMEOUT
TFL3    BIT     TCFL.3      ;ST1 TIMEOUT
TFL4    BIT     TCFL.4      ;MT0 TIMEOUT
TFL5    BIT     TCFL.5      ;MT1 TIMEOUT
TFL6    BIT     TCFL.6      ;CT0 UNDERFLOW
TFL7    BIT     TCFL.7      ;CT1 UNDERFLOW
;
```

```
;*****************************************************************
;*      DATA DEFINITIONS
;*
;*      [OUTPUT PORTS]
;*
;*****************************************************************
;       OPORT_0
LT01    BIT     CC00.0      ;DOOR-OPEN
LT02    BIT     CC00.1      ;EVAC-FAIL
LT03    BIT     CC00.2      ;FILL-FAIL
LT04    BIT     CC00.3      ;STERIL-FAIL
LT05    BIT     CC00.4      ;PURGE-FAIL
LT06    BIT     CC00.5      ;LOAD-UNSTERILE
LT07    BIT     CC00.6      ;SPARE
LT08    BIT     CC00.7      ;TEST-FAIL
;
;       OPORT-1
LT11    BIT     CC01.0      ;READY-FOR-CYCLE
LT12    BIT     CC01.1      ;CYCLE-IN-PROGRESS
LT13    BIT     CC01.2      ;EVAC-IN-PROGRESS
LT14    BIT     CC01.3      ;FILL-IN-PROGRESS
LT15    BIT     CC01.4      ;STERIL-IN-PROGRESS
LT16    BIT     CC01.5      ;PURGE-IN-PROGRESS
LT17    BIT     CC01.6      ;REMOVE-LOAD
LT18    BIT     CC01.7      ;SPARE
;
;       OPORT_2
VV01    BIT     CC02.0      ;OPEN-MAIN-VAC-VALVE
VV02    BIT     CC02.1      ;OPEN-MAIN-GAS-VALVE
VV03    BIT     CC02.2      ;OPEN-MAIN-DUMP-VALVE
VV04    BIT     CC02.3      ;OPEN-GAS-CTRL-VALVE
VV05    BIT     CC02.4      ;OPEN-N2-CTRL-VALVE
VV06    BIT     CC02.5      ;OPEN-STEAM-CTRL-VALVE
VV07    BIT     CC02.6      ;OPEN-BREAK-VALVE
VV08    BIT     CC02.7      ;OPEN-DUMP-VAC-VALVE
;
;       OPORT_3
PP01    BIT     CC03.0      ;TURN-P1-ON
HT01    BIT     CC03.1      ;TURN-H1-ON
SPR1    BIT     CC03.2      ;SPARE
SPR2    BIT     CC03.3      ;SPARE
SPR3    BIT     CC03.4      ;SPARE
SPR4    BIT     CC03.5      ;SPARE
ADZC    BIT     CC03.6      ;A/D ZERO CALIB.
LGG1    BIT     CC03.7      ;CONC. HIGH GAIN SWITCH
```

```
;*****************************************************************
;*      DATA DEFINITIONS
;*
;*      [INPUT PORTS]
;*
;*****************************************************************
;       IPORT_0
LSC1    BIT     CCI0.0      ;V1-CLOSED
LSC2    BIT     CCI0.1      ;V2-CLOSED
LSC3    BIT     CCI0.2      ;V3-CLOSED
LSC4    BIT     CCI0.3      ;V4-CLOSED
LSC5    BIT     CCI0.4      ;V5-CLOSED
LSC6    BIT     CCI0.5      ;V6-CLOSED
LSC7    BIT     CCI0.6      ;V7-CLOSED
LSC8    BIT     CCI0.7      ;V8-CLOSED
;
;       IPORT_1
LSO1    BIT     CCI1.0      ;V1-OPEN
LSO2    BIT     CCI1.1      ;V2-OPEN
LSO3    BIT     CCI1.2      ;V3-OPEN
LSO4    BIT     CCI1.3      ;V4-OPEN
LSO5    BIT     CCI1.4      ;V5-OPEN
LSO6    BIT     CCI1.5      ;V6-OPEN
LSO7    BIT     CCI1.6      ;V7-OPEN
LSO8    BIT     CCI1.7      ;V8-OPEN
;
;       IPORT_2
DSC1    BIT     CCI2.0      ;DOOR-SW-CLOSED
TSC1    BIT     CCI2.1      ;TEMP-SW-CLOSED
SWC1    BIT     CCI2.2      ;MAN-SW1-CLOSED
SWC2    BIT     CCI2.3      ;MAN-SW2-CLOSED
SI01    BIT     CCI2.4      ;SPARE
SI02    BIT     CCI2.5      ;SPARE
SI03    BIT     CCI2.6      ;SPARE
SI04    BIT     CCI2.7      ;SPARE
;
;       IPORT_3
SI05    BIT     CCI3.0      ;SPARE
SI06    BIT     CCI3.1      ;SPARE
SI07    BIT     CCI3.2      ;SPARE
SI08    BIT     CCI3.3      ;SPARE
SI09    BIT     CCI3.4      ;SPARE
SI10    BIT     CCI3.5      ;SPARE
SI11    BIT     CCI3.6      ;SPARE
SI12    BIT     CCI3.7      ;SPARE
;
```

```
;*****************************************************************
;*      MASK BIT DEFINITIONS
;*
;*****************************************************************
;       MASK-REG-0
MVC1    BIT     MSK0.0    ;V1-CLOSED-MASK
MVC2    BIT     MSK0.1    ;V2-CLOSED-MASK
MVC3    BIT     MSK0.2    ;V3-CLOSED-MASK
MVC4    BIT     MSK0.3    ;V4-CLOSED-MASK
MVC5    BIT     MSK0.4    ;V5-CLOSED-MASK
MVC6    BIT     MSK0.5    ;V6-CLOSED-MASK
MVC7    BIT     MSK0.6    ;V7-CLOSED-MASK
MVC8    BIT     MSK0.7    ;V8-CLOSED-MASK
;
;       MASK-REG-1
MVO1    BIT     MSK1.0    ;V1-OPEN-MASK
MVO2    BIT     MSK1.1    ;V2-OPEN-MASK
MVO3    BIT     MSK1.2    ;V3-OPEN-MASK
MVO4    BIT     MSK1.3    ;V4-OPEN-MASK
MVO5    BIT     MSK1.4    ;V5-OPEN-MASK
MVO6    BIT     MSK1.5    ;V6-OPEN-MASK
MVO7    BIT     MSK1.6    ;V7-OPEN-MASK
MVO8    BIT     MSK1.7    ;V8-OPEN-MASK
;
;       MASK-REG-2
MDC1    BIT     MSK2.0    ;DS-CLOSED-MASK
MTC1    BIT     MSK2.1    ;TS-CLOSED-MASK
MSC1    BIT     MSK2.2    ;SW1-CLOSED-MASK
MSC2    BIT     MSK2.3    ;SW2-CLOSED-MASK
;
```

```
;*************************************************************************
;*        INTERRUPT VECTORS
;*
;*************************************************************************
          CSEG
          ORG       0000H
RSTV:     LJMP      INIT                    ;RESET VECTOR
;
          ORG       000BH
TINT:     LJMP      TMR0                    ;TIMER0 VECTOR
;
          ORG       0013H
PINT:     LJMP      PWRF                    ;PWR FAIL VECTOR
;
          ORG       001BH
TM1V:     RETI                              ;TIMER1 VECTOR
;
          ORG       0023H
SIOV:     LJMP      SIOHND                  ;SERIAL DATA VECTOR
;
;*************************************************************************
;         POWER FAIL HANDLER
;
;*************************************************************************
PWRF:     CLR       P1.6                    ;STORE SRAM DATA
          SETB      P1.6                    ;DISABLE STORE
          RETI                              ;INTERRUPT RETURN
;
```

```
;*****************************************************************
;*        TIMER INTERRUPT HANDLER
;*
;*****************************************************************
          ORG       0030H
TMR0:     PUSH      PSW                    ;SAVE PROC. STATUS
          PUSH      ACC                    ;SAVE ACCUMULATOR
          PUSH      DPL                    ;SAVE DP(L)
          PUSH      DPH                    ;SAVE DP(H)
          MOV       PSW,#BNK0              ;USE RB0
          CLR       EA                     ;DISABLE INTERRUPTS
          ACALL     RRT                    ;RESET AND RESTART TIMERS
          ACALL     RCI                    ;READ CONTACT INPUTS
          ACALL     CSC                    ;CONTACT STATUS CHECK
          ACALL     WCO                    ;WRITE CONTACT OUTPUTS
          ACALL     RAI                    ;READ ANALOG INPUTS
          SETB      EA                     ;RESTORE INTERRUPTS
TRTN:     POP       DPH                    ;RESTORE DP(H)
          POP       DPL                    ;RESTORE DP(L)
          POP       ACC                    ;RESTORE ACCUMULATOR
          POP       PSW                    ;RESTORE PROC. STATUS
          RETI                             ;RETURN FROM TIMER0 INT.
;
```

```
;*****************************************************************
;*        TMR0 SUBROUTINES
;*
;*****************************************************************
RRT:    CLR     TR0                     ;STOP TIMER0
        MOV     A,#LOW(-3120+7)         ;LOAD COUNT(L)
        ADD     A,TL0                   ;CORRECT FOR OVERRUN
        MOV     TL0,A                   ;RELOAD COUNTER(L)
        MOV     A,#HIGH(-3120+7)        ;REPEAT FOR COUNT(H)
        ADDC    A,TH0                   ;GET CORRECTED HIGH BYTE
        MOV     TH0,A                   ;LOAD COUNTER(H)
        SETB    TR0                     ;RESTART TIMER
CLOCK:  DJNZ    TICK,CLK3               ;IF 50-MSEC
        MOV     TICK,#8                 ;  RELOAD TICK COUNT
        SETB    TICF                    ;  SET 50-MSEC FLAG
        DJNZ    TSEC,CLK2               ;  IF 1-SEC
        MOV     TSEC,#20                ;    RELOAD TSEC COUNT
        SETB    SECF                    ;    SET 1-SEC FLAG
        DJNZ    TMIN,CLK1               ;    IF 1-MIN
        MOV     TMIN,#60                ;      RELOAD TMIN COUNT
        SETB    MINF                    ;      SET 1-MIN FLAG
        SJMP    CLK4                    ;      END
CLK1:   CLR     MINF                    ;    ELSE, CLR MIN. FLAG
        SJMP    CLK4                    ;      END
CLK2:   CLR     SECF                    ;  ELSE, CLR SEC. FLAG
        SJMP    CLK4                    ;    END
CLK3:   CLR     TICF                    ;ELSE, CLR TIC. FLAG
CLK4:   NOP                             ;  END
        RET                             ;RETURN FROM TIMER PROG.
```

```
RCI:    MOV     DPTR,#X0        ;POINT CONTACT INPUTS
        MOV     R0,#CCI0        ;POINT DATA-BASE IMAGE
        MOV     R4,#4           ;FOR R4:=4 DOUNTO 0 DO
CI1:    CLR     P1.4            ;  ENABLE I/O
        MOVX    A,@DPTR         ;  GET INPUT
        SETB    P1.4            ;  DISABLE I/O
        MOV     @R0,A           ;  STORE IT IN DATA-BASE
        INC     DPTR            ;  POINT NEXT INPUT
        INC     R0              ;  POINT NEXT STORAGE
        DJNZ    R4,CI1          ;  END
        RET                     ;RETURN
;
CSC:    CLR     ALMF            ;CLEAR ALARM FLAG
        MOV     A,CCO2          ;GET VALVE OUTPUTS
        XRL     A,CCI1          ;COMPARE WITH LSO INPUTS
        ANL     A,MSK1          ;MASK OFF VO DON'T CARES
        MOV     R2,A            ;SAVE PARTIAL RESULT
        MOV     A,CCO2          ;GET VALVE OUTPUTS
        CPL     A               ;MAKE CLOSED NORMAL
        XRL     A,CCI0          ;COMPARE WITH LSC INPUTS
        ANL     A,MSK0          ;MASK OFF VC DON'T CARES
        ORL     A,R2            ;ADD PREV. RESULT
        JZ      CSC2            ;  IF MISMATCH
        SETB    ALMF            ;     SET ALARM FLAG
CSC2:   NOP                     ;     END
        MOV     A,TCFL          ;GET TIMEOUTS
        ANL     A,TCEN          ;TEST IF ENABLED
        JZ      CSC4            ;IF (TMO.AND.TEN)
        SETB    TMOF            ;  SET TIMEOUT FLAG
        SJMP    CSC5            ;  END
CSC4:   CLR     TMOF            ;ELSE, CLEAR TIMEOUT FLAG
CSC5:   NOP                     ;  END
        RET                     ;RETURN
;
UCO:    MOV     DPTR,#Y0        ;POINT CONTACT OUTPUTS
        MOV     R0,#CCO0        ;POINT DATA-BASE IMAGE
        MOV     R4,#4           ;FOR R4:=4 DOUNTO 0 DO
CO1:    MOV     A,@R0           ;  GET OUTPUT DATA
        CPL     A               ;  INVERT IT FOR OUTPUT
        CLR     P1.4            ;  ENABLE I/O
        MOVX    @DPTR,A         ;  LOAD OUTPUT LATCH
        SETB    P1.4            ;  DISABLE I/O
        INC     DPTR            ;  POINT NEXT OUTPUT
        INC     R0              ;  POINT NEXT DATA
        DJNZ    R4,CO1          ;  END
        RET                     ;RETURN
```

```
RAI:    MOV     DPTR,#IN0       ;POINT FIRST ANALOG CHAN.
        MOV     R0,#ADI0        ;POINT FIRST ANALOG DATA
        MOV     R4,#8           ;FOR R4:=8 DOUNTO 0 DO
RA1:    CLR     P1.4            ;  ENABLE I/O
        MOVX    A,@DPTR         ;  GET ANALOG DATA
        SETB    P1.4            ;  DISABLE I/O
        ACALL   FILTER          ;  FILTER ANALOG DATA
        MOV     @R0,A           ;  LOAD IT INTO DATA BASE
        INC     DPTR            ;  POINT NEXT CHANNEL
        INC     R0              ;  POINT NEXT DATA
        DJNZ    R4,RA1          ;  END
        RET                     ;RETURN
;
FILTER: MOV     B,#020H         ;LOAD FILT. CONST, CB
        MUL     AB              ;B,A:=0.125*R(I)
        PUSH    B               ;SAVE PROD(H)
        PUSH    ACC             ;SAVE PROD(L)
        MOV     B,#0E0H         ;LOAD (1-CB) CONST.
        MOV     A,@R0           ;GET X(I-1)
        MUL     AB              ;B,A:=0.875*X(I-1)
        MOV     R2,B            ;SAVE HIGH BYTE
        POP     B               ;LOAD PROD(L)
        ADD     A,B             ;ADD LOW BYTES
        XCH     A,R2            ;GET HIGH BYTE
        POP     B               ;LOAD PROD(H)
        ADDC    A,B             ;A,R2 IS FILTERED DATA
        RET                     ;RETURN
;
```

```
;*****************************************************************
;       SCHEDULED TIME FUNCTIONS
;
;*****************************************************************
T50:    CLR     TICF                    ;CLEAR TICK FLAG
        MOV     PSW,#BNK2               ;USE RB2
        ACALL   RWT                     ;RESET WATCHDOG TIMER
        ACALL   DTT                     ;DECREMENT TICK TIMERS
        ACALL   SEQ                     ;PERFORM SEQUENCE LOGIC
        ACALL   CTL                     ;LOAD CONTROL OUTPUTS
        RET                             ;RETURN TO DISPATCHING
;
T1K:    CLR     SECF                    ;CLEAR 1-SEC FLAG
        MOV     PSW,#BNK2               ;USE RB2
        ACALL   DST                     ;DECREMENT SECOND TIMERS
        ACALL   CTR                     ;PERFORM CONTROL ACTIONS
        RET
;
T1M:    CLR     MINF                    ;CLEAR 1-MIN FLAG
        MOV     PSW,#BNK2               ;USE RB2
        ACALL   UBC                     ;UPDATE BATCH CLOCK
        ACALL   DMT                     ;DECREMENT MINUTE TIMERS
        RET
;
```

```
RWT:    MOV     DPTR,#WDT       ;POINT WATCHDOG TIMER
        CLR     A               ;CLEAR ACCUMULATOR
        CLR     P1.4            ;ENABLE I/O
        MOVX    @DPTR,A         ;RESET WATCHDOG TIMER
        SETB    P1.4            ;DISABLE I/O
        RET
;
UBC:    MOV     R0,#TIME        ;POINT TIME(L)
        CLR     C               ;CLEAR CARRY
        XCH     A,@R0           ;GET TIME(L)
        INC     A               ;INCREMENT IT
        XCH     A,@R0           ;UPDATE TIME(L)
        INC     R0              ;POINT TIME(H)
        XCH     A,@R0           ;GET TIME(H)
        ADDC    A,#0            ;PROPAGATE CARRY
        XCH     A,@R0           ;UPDATE TIME(H)
        RET
;
```

```
;*****************************************************************
;*        CONTROL CALCULATIONS
;*
;*****************************************************************
CTR:    MOV     R0,#STP0            ;POINT SETPOINT
        MOV     R1,#ADI0            ;POINT DATA
        CLR     C                   ;CLEAR CARRY
        MOV     A,@R0               ;GET PRESS. SETPOINT
        SUBB    A,@R1               ;SUBTRACT MEAS. PRESS.
        JNC     CT2                 ;IF MV>SP
        SETB    CTR0                ;  INCREASE OUTPUT
        SJMP    CT3                 ;  END
CT2:    CLR     CTR0                ;ELSE, DECR. OUTPUT
CT3:    NOP                         ;  END
        INC     R0                  ;POINT NEXT SETPOINT
        INC     R1                  ;POINT NEXT MEASUREMENT
        CLR     C                   ;CLEAR CARRY
        MOV     A,@R0               ;GET TEMP. SETPOINT
        SUBB    A,@R1               ;SUBTRACT MEAS. TEMP.
        JNC     CT4                 ;IF MV>SP
        CLR     CTR1                ;  DECREASE OUTPUT
        SJMP    CT5                 ;  END
CT4:    SETB    CTR1                ;ELSE, INCR. OUTPUT
CT5:    NOP                         ;  END
        INC     R0                  ;POINT NEXT SETPOINT
        INC     R1                  ;POINT NEXT MEASUREMENT
        CLR     C                   ;CLEAR CARRY
        MOV     A,@R0               ;GET HUM. SETPOINT
        SUBB    A,@R1               ;SUBTRACT HUM. MEAS.
        JNC     CT6                 ;IF MV>SP
        CLR     CTR2                ;  DECREASE OUTPUT
        SJMP    CT7                 ;  END
CT6:    SETB    CTR2                ;ELSE, INCREASE OUTPUT
CT7:    NOP                         ;  END
        INC     R0                  ;POINT NEXT SETPOINT
        INC     R1                  ;POINT NEXT MEASUREMENT
        CLR     C                   ;CLEAR CARRY
        MOV     A,@R0               ;GET CONC. SETPOINT
        SUBB    A,@R1               ;SUBTRACT CONC. MEAS.
        JNC     CT8                 ;IF MV>SP
        CLR     CTR3                ;  DECREASE OUTPUT
        SJMP    CT9                 ;  END
CT8:    SETB    CTR3                ;ELSE, INCR. OUTPUT
CT9:    NOP                         ;  END
        RET                         ;RETURN
;
```

```
;*****************************************************************
;*        SOFTWARE TICK TIMERS (50 MSEC)
;*
;*****************************************************************
DTT:    MOV     R0,#TTM0        ;POINT FIRST TICK TIMER
        MOV     A,@R0           ;GET LAST COUNT
        JZ      TT1             ;IF COUNT<>0
        DEC     A               ;  DECREMENT ACC.
        MOV     @R0,A           ;  UPDATE COUNT
        JZ      TT1             ;  IF NOT TIMEOUT
        CLR     TFL0            ;    CLEAR FLAG
        SJMP    TT2             ;    END
TT1:    SETB    TFL0            ;  ELSE, SET FLAG
TT2:    NOP                     ;  END
;
        MOV     R0,#TTM1        ;POINT SECOND TICK TIMER
        MOV     A,@R0           ;GET LAST COUNT
        JZ      TT4             ;IF COUNT<>0
        DEC     A               ;  DECREMENT ACC.
        MOV     @R0,A           ;  UPDATE COUNT
        JZ      TT4             ;  IF NOT TIMEOUT
        CLR     TFL1            ;    CLEAR FLAG
        SJMP    TT5             ;    END
TT4:    SETB    TFL1            ;  ELSE, SET FLAG
TT5:    NOP                     ;  END
        RET                     ;RETURN
;
;*****************************************************************
;*        SOFTWARE SECOND TIMERS
;*
;*****************************************************************
DST:    MOV     R0,#STM0        ;POINT FIRST SEC. TIMER
        MOV     A,@R0           ;GET LAST COUNT
        JZ      ST1             ;IF COUNT<>0
        DEC     A               ;  DECREMENT ACC.
        MOV     @R0,A           ;  UPDATE COUNT
        JZ      ST1             ;  IF NOT TIMEOUT
        CLR     TFL2            ;    CLEAR FLAG
        SJMP    ST2             ;    END
ST1:    SETB    TFL2            ;  ELSE, SET FLAG
ST2:    NOP                     ;  END
;
        MOV     R0,#STM1        ;POINT NEXT SECOND TIMER
        MOV     A,@R0           ;GET LAST COUNT
        JZ      ST4             ;IF COUNT<>0
        DEC     A               ;  DECREMENT ACC.
        MOV     @R0,A           ;  UPDATE COUNT
        JZ      ST4             ;  IF NOT TIMEOUT
        CLR     TFL3            ;    CLEAR FLAG
        SJMP    ST5             ;    END
ST4:    SETB    TFL3            ;  ELSE, SET FLAG
ST5:    NOP                     ;  END
        RET                     ;RETURN
;
```

```
;*****************************************************************
;*      SOFTWARE MINUTE TIMERS
;*
;*****************************************************************
DMT:    MOV     R0,#MTM0        ;POINT FIRST MIN. TIMER
        MOV     A,@R0           ;GET LAST COUNT
        JZ      MT1             ;IF COUNT<>0
        DEC     A               ;  DECREMENT ACC.
        MOV     @R0,A           ;  UPDATE COUNT
        JZ      MT1             ;  IF NOT TIMEOUT
        CLR     TFL4            ;    CLEAR FLAG
        SJMP    MT2             ;    END
MT1:    SETB    TFL4            ;  ELSE, SET FLAG
MT2:    NOP                     ;  END
;
        MOV     R0,#MTM1        ;POINT SECOND MIN. TIMER
        MOV     A,@R0           ;GET LAST COUNT
        JZ      MT4             ;IF COUNT<>0
        DEC     A               ;  DECREMENT ACC.
        MOV     @R0,A           ;  UPDATE COUNT
        JZ      MT4             ;  IF NOT TIMEOUT
        CLR     TFL5            ;    CLEAR FLAG
        SJMP    MT5             ;    END
MT4:    SETB    TFL5            ;  ELSE, SET FLAG
MT5:    NOP                     ;  END
        RET                     ;RETURN
;*****************************************************************
;*      SOFTWARE COUNTERS
;*
;*****************************************************************
DCT0:   MOV     R0,#CNT0        ;POINT FIRST COUNTER
        MOV     A,@R0           ;GET LAST COUNT
        JZ      DC1             ;IF COUNT<>0
        DEC     A               ;  DECREMENT ACC.
        MOV     @R0,A           ;  UPDATE COUNT
        JZ      DC1             ;  IF NOT ZERO
        CLR     TFL6            ;    CLEAR FLAG
        SJMP    DC2             ;    END
DC1:    SETB    TFL6            ;  ELSE, SET FLAG
DC2:    NOP                     ;  END
        RET                     ;RETURN
;
DCT1:   MOV     R0,#CNT1        ;POINT SECOND COUNTER
        MOV     A,@R0           ;GET LAST COUNT
        JZ      DC3             ;IF COUNT<>0
        DEC     A               ;  DECREMENT ACC.
        MOV     @R0,A           ;  UPDATE COUNT
        JZ      DC3             ;  IF NOT ZERO
        CLR     TFL7            ;    CLEAR FLAG
        SJMP    DC4             ;    END
DC3:    SETB    TFL7            ;  ELSE, SET FLAG
DC4:    NOP                     ;  END
        RET                     ;RETURN
;
```

```
;*****************************************************************
;*      CONTROL OUTPUTS
;*
;*****************************************************************
CTL:    MOV     C,CTR0          ;GET OUTPUT-0
        ANL     C,CEN0          ;ALLOW IF ENABLED
        MOV     VV05,C          ;OUTPUT TO V5
;
        MOV     C,CTR1          ;GET OUTPUT-1
        ANL     C,CEN1          ;ALLOW IF ENABLED
        MOV     HT01,C          ;OUTPUT TO H1
;
        MOV     C,CTR2          ;GET OUTPUT-2
        ANL     C,CEN2          ;ALLOW IF ENABLED
        MOV     VV06,C          ;OUTPUT TO V6
;
        MOV     C,CTR3          ;GET OUTPUT-3
        ANL     C,CEN3          ;ALLOW IF ENABLED
        MOV     VV04,C          ;OUTPUT TO V4
;
        RET
;
```

```
;*****************************************************************
;*        POWER-ON INITIALIZATION
;*
;*****************************************************************
INIT:     MOV       SP,#060H            ;INITIALIZE STACK POINTER
          MOV       PSW,#BNK0           ;USE RB0
          CLR       A                   ;CLEAR ACCUMULATOR
          MOV       R0,#2               ;POINT LOWEST RAM LOC.
          MOV       R1,#126             ;FOR R1:=126 DOWNTO 0 DO
ILP:      MOV       @R0,A               ;  CLEAR MEMORY LOC.
          INC       R0                  ;  POINT NEXT LOCATION
          DJNZ      R1,ILP              ;  END
          MOV       TICK,#8             ;INITIALIZE TICK COUNT
          MOV       TSEC,#20            ;INITIALIZE SEC. COUNT
          MOV       TMIN,#60            ;INITIALIZE MIN. COUNT
          MOV       PSW,#BNK1           ;USE RB1
          MOV       RPUT,#40H           ;INITIALIZE RPUT POINTER
          MOV       RTAK,#40H           ;INITIALIZE RTAK POINTER
          MOV       TPUT,#50H           ;INITIALIZE TPUT POINTER
          MOV       TTAK,#50H           ;INITIALIZE TTAK POINTER
          MOV       PSW,#BNK2           ;USE RB2
          MOV       STATE,#0            ;STATE:=0
          MOV       ABORT,#0            ;ABORT:=0
          MOV       SCON,#052H          ;SET SERIAL PORT BITS
          MOV       TMOD,#061H          ;SET TIMER MODES
          MOV       87H,#00H            ;SET SMOD:=0 IN PCON
          MOV       IP,#002H            ;SET INTERRUPT PRIORITIES
          MOV       IE,#096H            ;ENABLE INTERRUPTS
          MOV       TL0,#LOW(-3120)     ;LOAD COUNT(L)
          MOV       TH0,#HIGH(-3120)    ;LOAD COUNT(H)
          MOV       TH1,#-13            ;SET BAUD RATE (1200)
          MOV       A,#0FFH             ;SET ACCUM. ALL 1'S
          CLR       P1.4                ;ENABLE I/O
          MOV       DPTR,#Y0            ;POINT Y0 OUTPUTS
          MOVX      @DPTR,A             ;CLEAR Y0
          MOV       DPTR,#Y1            ;POINT Y1 OUTPUTS
          MOVX      @DPTR,A             ;CLEAR Y1
          MOV       DPTR,#Y2            ;POINT Y2 OUTPUTS
          MOVX      @DPTR,A             ;CLEAR Y2
          MOV       DPTR,#Y3            ;POINT Y3 OUTPUTS
          MOVX      @DPTR,A             ;CLEAR Y3
          SETB      P1.4                ;DISABLE I/O
          ACALL     RWT                 ;RESET WATCHDOG TIMER
          MOV       TIME,#0             ;CLEAR TIME(L)
          MOV       TIME+1,#0           ;CLEAR TIME(H)
          SETB      TR1                 ;START BAUD CLOCK
          SETB      TR0                 ;START TIMER
          SJMP      MAIN                ;START MAIN PROGRAM
;
TEST:     RET                           ;TEST COMPUTER FUNCTIONS
```

```
;*****************************************************************
;*      SEQUENCING PROGRAM
;*
;*****************************************************************
SEQ:    NOP                             ;REPEAT
        MOV     PSW,#BNK2               ;  USE RB2
        MOV     A,STATE                 ;  GET CURRENT STATE
        ADD     A,#NOT(SMAX)            ;  COMPARE MAX. STATE
        JNC     SQ1                     ;  IF INVALID STATE
        MOV     A,#31                   ;    TAKE STATE #31
        MOV     STATE,A                 ;    SET STATE TO #31
        SJMP    SQ2                     ;    END
SQ1:    MOV     A,STATE                 ;  ELSE, USE CURRENT STATE
SQ2:    NOP                             ;    END
        RL      A                       ;  MAKE IT 4-BYTE-
        RL      A                       ;  ADDRESS OFFSET
        MOV     DPTR,#JMPTBL            ;  OFFSET IN JUMP TABLE
        JMP     @A+DPTR                 ;  PERFORM STATE
SEQR:   MOV     C,ALMF                  ;  GET ALARM FLAG
        ORL     C,TMOF                  ;  OR WITH TIMEOUT FLAG
        JNC     SQ3                     ;  IF (ALM.OR.TMO)
        MOV     A,ABORT                 ;    GET ABORT STATE
        MOV     STATE,A                 ;    SET STATE TO ABORT
        CLR     F0                      ;    CLEAR HOLD FLAG
SQ3:    NOP                             ;    END
        JNB     F0,SEQ                  ;UNTIL HOLD
        RET                             ;RETURN
```

```
;*****************************************************************
;*       MAIN DISPATCHING PROGRAM
;*
;*****************************************************************
MAIN:     NOP                              ;DO FOREVER
          JNB       MINF,MN1               ;  IF 1-MIN TIME
          LCALL     T1M                    ;    DO 1-MIN FUNCTIONS
MN1:      JNB       SECF,MN2               ;  IF 1-SEC TIME
          LCALL     T1K                    ;    DO 1-SEC FUNCTIONS
MN2:      JNB       TICF,MN3               ;  IF TICK TIME
          LCALL     T50                    ;    DO TICK FUNCTIONS
MN3:      JNB       RCVF,MN4               ;  IF RCV TIME
          LCALL     RCV                    ;    DO RCV FUNCTIONS
MN4:      JNB       XMTF,MN5               ;  IF XMT TIME
          LCALL     XMT                    ;    DO XMT FUNCTIONS
MN5:      LCALL     TEST                   ;  ELSE, PERFORM TESTS
          SJMP      MAIN                   ;END
;
GTCT:     MOV       A,$1                   ;READ SRAM
          RET
RCV:      CLR       RCVF                   ;RESET RCV FLAG
          RET
XMT:      CLR       XMTF                   ;RESET XMT FLAG
          RET
SIOHND:   RET                              ;SERIAL I/O HANDLER

 $INCLUDE(STATES.SRC)
 ;
           END
```

```
;*****************************************************************
;*       STATE JUMP TABLE
;*
;*****************************************************************
JMPTBL:  LJMP      STATE0
         DB        0
         LJMP      STATE1
         DB        0
         LJMP      STATE2
         DB        0
         LJMP      STATE3
         DB        0
         LJMP      STATE4
         DB        0
         LJMP      STATE5
         DB        0
         LJMP      STATE6
         DB        0
         LJMP      STATE7
         DB        0
         LJMP      STATE8
         DB        0
         LJMP      STATE9
         DB        0
         LJMP      STATE10
         DB        0
         LJMP      STATE11
         DB        0
         LJMP      STATE12
         DB        0
         LJMP      STATE13
         DB        0
         LJMP      STATE14
         DB        0
         LJMP      STATE15
         DB        0
         LJMP      STATE16
         DB        0
         LJMP      STATE17
         DB        0
         LJMP      STATE18
         DB        0
         LJMP      STATE19
         DB        0
         LJMP      STATE20
         DB        0
         LJMP      STATE21
         DB        0
         LJMP      STATE22
         DB        0
         LJMP      STATE23
         DB        0
         LJMP      STATE24
         DB        0
         LJMP      STATE25
```

```
        DB      0
        LJMP    STATE26
        DB      0
        LJMP    STATE27
        DB      0
        LJMP    STATE28
        DB      0
        LJMP    STATE29
        DB      0
        LJMP    STATE30
        DB      0
        LJMP    STATE31
        DB      0
        LJMP    STATE32
        DB      0
        LJMP    STATE33
        DB      0
        LJMP    STATE34
        DB      0
        LJMP    STATE35
        DB      0
        LJMP    STATE36
        DB      0
        LJMP    STATE37
        DB      0
        LJMP    STATE38
        DB      0
```

```
;
STATE0:  MOV     STATE,#1          ;
         MOV     ABORT,#1          ;STATE:=1
         MOV     STAT,#00H         ;ABORT:=1
         MOV     CTRL,#00H         ;RESET STATUS
         MOV     TCEN,#00H         ;RESET CONTROLS
         MOV     TCFL,#00H         ;RESET ALARMS
         MOV     MSK0,#00H         ;RESET TIMEOUT FLAGS
         MOV     MSK1,#00H         ;RESET CLOSED MASKS
         MOV     MSK2,#00H         ;RESET OPEN MASKS
         MOV     MSK3,#00H         ;RESET MISC. MASKS
         MOV     CC00,#00H         ;RESET MISC. MASKS
         MOV     CC01,#00H         ;RESET ALARM LIGHTS
         MOV     CC02,#40H         ;RESET RUN LICHTS
         MOV     CC03,#00H         ;RESET ALL VALVES
         CLR     F0                ;RESET MISC. OUTPUTS
         LJMP    SEQR              ;CLEAR HOLD FLAG
;                                  ;RETURN
STATE1:  JNB     DSC1,S11          ;IF DOOR CLOSED
         MOV     STATE,#2          ;  STATE:=2
         MOV     ABORT,#29         ;  ABORT:=29
         CLR     LT01              ;  DOOR-OPEN(OFF)
         SETB    LT11              ;  READY-FOR-CYCLE(ON)
         CLR     F0                ;  CLEAR HOLD FLAG
         SJMP    S12               ;  END
S11:     SETB    LT01              ;ELSE, DOOR-OPEN(ON)
         CLR     LT11              ;  READY-FOR-CYCLE(OFF)
         SETB    F0                ;  SET HOLD FLAG
S12:     NOP                       ;  END
         LJMP    SEQR              ;RETURN
;
STATE2:  JNB     SUC1,S21          ;IF START-CYCLE(PUSHED)
         MOV     STATE,#3          ;  STATE:=3
         MOV     ABORT,#29         ;  ABORT:=29
         CLR     LT11              ;  READY-FOR-CYCLE(OFF)
         SETB    LT12              ;  CYCLE-IN-PROGRESS(ON)
         MOV     CNT0,#CNTM        ;  LOAD MIN. COUNT
         CLR     TFL6              ;  CLEAR COUNT FLAG
         CLR     MVC7              ;  CLEAR VC7 MASK
         CLR     MV07              ;  CLEAR V07 MASK
         CLR     VV07              ;  CLOSE-BREAK-VALVE
         MOV     TTM0,#VDLY        ;  LOAD TIMEOUT DELAY
         CLR     TFL0              ;  RESET TIMEOUT FLAG
         SETB    TEN0              ;  ENABLE TIMEOUT ALARM
         CLR     F0                ;  CLEAR HOLD FLAG
         SJMP    S23               ;  END
S21:     JB      DSC1,S22          ;ELSE, IF DOOR-OPEN
         MOV     STATE,#1          ;    STATE:=1
         MOV     ABORT,#29         ;    ABORT:=29
         CLR     F0                ;    CLEAR HOLD FLAG
         SJMP    S23               ;    END
S22:     SETB    F0                ;  ELSE, SET HOLD FLAG
S23:     NOP                       ;    END
         LJMP    SEQR              ;RETURN
;
```

```
STATE3:  JNB     LSC7,S31          ;IF V7 CLOSED
         MOV     STATE,#4          ;  STATE:=4
         MOV     ABORT,#29         ;  ABORT:=29
         CLR     TEN0              ;  CLEAR TIMEOUT ENABLE
         SETB    MVC7              ;  SET VC7 MASK
         SETB    MVO7              ;  SET VO7 MASK
         SETB    HT01              ;  TURN HEATER ON
         MOV     MTM0,#HDLY        ;  LOAD HEATER TIMEOUT
         CLR     TFL4              ;  RESET TIMEOUT FLAG
         SETB    TEN4              ;  ENABLE TIMEOUT ALARM
         CLR     F0                ;  CLEAR HOLD FLAG
         SJMP    S33               ;  END
S31:     JB      DSC1,S32          ;ELSE, IF DOOR OPEN
         MOV     A,ABORT           ;     GET ABORT STATE
         MOV     STATE,A           ;     STATE:=ABORT-1
         SETB    LT01              ;     DOOR-OPEN(ON)
         CLR     F0                ;     CLEAR HOLD FLAG
         SJMP    S33               ;     END
S32:     SETB    F0                ;  ELSE, SET HOLD FLAG
S33:     NOP                       ;     END
         LJMP    SEQR              ;RETURN
;
```

```
STATE4:  JNB     TSC1,S41        ;
                                 ;IF HEATER ON
         MOV     STATE,#5        ;  STATE:=5
         MOV     ABORT,#29       ;  ABORT:=29
         CLR     TEN4            ;  CLEAR TIMEOUT ENABLE
         SETB    MTC1            ;  SET TEMP SU MASK
         MOV     STP1,#TSP1      ;  LOAD TEMP. SETPOINT
         SETB    CEN1            ;  ENABLE TEMP. CONTROL
         CLR     MVC1            ;  CLEAR VC1 MASK
         CLR     MVO1            ;  CLEAR VO1 MASK
         SETB    VV01            ;  OPEN V1
         MOV     TTM0,#VDLY      ;  LOAD TIMEOUT DELAY
         CLR     TFL0            ;  RESET TIMEOUT FLAG
         SETB    TEN0            ;  ENABLE TIMEOUT ALARM
         CLR     F0              ;  CLEAR HOLD FLAG
         SJMP    S43             ;  END
S41:     JB      DSC1,S42        ;ELSE, IF DOOR OPEN
         MOV     A,ABORT         ;     GET ABORT STATE
         MOV     STATE,A         ;     STATE:=ABORT-1
         SETB    LT01            ;     DOOR-OPEN(ON)
         CLR     F0              ;     CLEAR HOLD FLAG
         SJMP    S43             ;     END
S42:     SETB    F0              ;  ELSE, SET HOLD FLAG
S43:     NOP                     ;     END
         LJMP    SEQR            ;RETURN
;
STATE5:  JNB     LSO1,S51        ;IF VAC VALVE OPEN
         MOV     STATE,#6        ;  STATE:=6
         MOV     ABORT,#29       ;  ABORT:=29
         CLR     TEN0            ;  CLEAR TIMEOUT ENABLE
         SETB    MVC1            ;  SET VC1 MASK
         SETB    MVO1            ;  SET VO1 MASK
         SETB    PP01            ;  TURN P1 ON
         SETB    LT13            ;  EVAC-IN-PROGRESS(ON)
         MOV     MTM0,#TVAC      ;  LOAD EVAC TIME
         CLR     TFL4            ;  RESET TIMEOUT FLAG
         CLR     F0              ;  CLEAR HOLD FLAG
         SJMP    S53             ;  END
S51:     JB      DSC1,S52        ;ELSE, IF DOOR OPEN
         MOV     A,ABORT         ;     GET ABORT STATE
         MOV     STATE,A         ;     STATE:=ABORT-1
         SETB    LT01            ;     DOOR-OPEN(ON)
         CLR     F0              ;     CLEAR HOLD FLAG
         SJMP    S53             ;     END
S52:     SETB    F0              ;  ELSE, SET HOLD FLAG
         NOP                     ;     END
S53:     LJMP    SEQR            ;RETURN
;
STATE6:  JNB     TFL4,S62        ;IF EVAC TIME
         CLR     C               ;  CLEAR CARRY
         MOV     A,AD10          ;  GET PRESSURE
         SUBB    A,#PVAC         ;  SUBTRACT PRESS. LIMIT
         JC      S61             ;  IF P.LE.PVAC
         MOV     STATE,#7        ;    STATE:=7
         MOV     ABORT,#29       ;    ABORT:=29
         CLR     MVC1            ;    CLEAR VC1 MASK
```

```
        CLR     MVO1            ;    CLEAR VO1 MASK
        CLR     VVO1            ;    CLOSE V1
        MOV     TTMO,#VDLY      ;    LOAD TIMEOUT
        CLR     TFLO            ;    RESET TIMEOUT FLAG
        SETB    TENO            ;    ENABLE TIMEOUT ALARM
        CLR     F0              ;    CLEAR HOLD FLAG
        SJMP    S63             ;    END
S61:    SETB    LTO2            ;  ELSE, EVAC-FAIL(ON)
        MOV     A,ABORT         ;    GET ABORT STATE
        MOV     STATE,A         ;    STATE:=ABORT-1
        CLR     F0              ;    CLEAR HOLD FLAG
        SJMP    S63             ;    END
S62:    SETB    F0              ;ELSE, SET HOLD FLAG
S63:    NOP                     ;  END
        LJMP    SEQR            ;RETURN
;
```

```
STATE7:  JNB     LSC1,S71          ;IF V1 CLOSED
         MOV     STATE,#8          ;  STATE:=8
         MOV     ABORT,#29         ;  ABORT:=29
         CLR     TEN0              ;  DISABLE TIMEOUT
         SETB    MVC1              ;  SET VC1 MASK
         SETB    MVO1              ;  SET VO1 MASK
         MOV     MTM0,#LKHT        ;  LOAD LEAK HOLD TIME
         CLR     TFL4              ;  RESET TIMEOUT FLAG
         CLR     F0                ;  CLEAR HOLD FLAG
         SJMP    S72               ;  END
S71:     SETB    F0                ;ELSE, SET HOLD FLAG
         NOP                       ;  END
S72:     LJMP    SEQR              ;RETURN
;
STATE8:  JNB     TFL4,S82          ;IF LEAK HOLD TIME
         CLR     C                 ;  CLEAR CARRY
         MOV     A,ADI0            ;  GET PRESSURE
         SUBB    A,#PRLK           ;  SUBTRACT LEAK LIMIT
         JC      S81               ;  IF P.LE.PRLK
         MOV     STATE,#9          ;    STATE:=9
         MOV     ABORT,#30         ;    ABORT:=30
         MOV     STP2,#HSP1        ;    GET HUM. SETPOINT
         CLR     MVO6              ;    CLEAR VO6 MASK
         CLR     MVC6              ;    CLEAR VC6 MASK
         SETB    CEN2              ;    ENABLE HUM. LOOP (V6)
         MOV     MTM0,#HUMT        ;    LOAD HUM. TIMER
         CLR     TFL4              ;    RESET TIMEOUT FLAG
         CLR     LT13              ;    EVAC-IN-PROGRESS(OFF)
         SETB    LT14              ;    FILL-IN-PROGRESS(ON)
         CLR     F0                ;    CLEAR HOLD FLAG
         SJMP    S83               ;    END
S81:     SETB    LT02              ;  ELSE, EVAC-FAIL(ON)
         MOV     A,ABORT           ;    GET ABORT STATE
         MOV     STATE,A           ;    STATE:=ABORT-1
         CLR     F0                ;    CLEAR HOLD FLAG
         SJMP    S83               ;    END
S82:     SETB    F0                ;ELSE, SET HOLD FLAG
S83:     NOP                       ;  END
         LJMP    SEQR              ;RETURN
;
STATE9:  JNB     TFL4,S92          ;IF HUM. TIME
         CLR     C                 ;  CLEAR CARRY
         MOV     A,ADI3            ;  GET HUMIDITY
         SUBB    A,#HNOM           ;  SUBTRACT HUM. LEVEL
         JC      S91               ;  IF HUM.GE.HNOM
         MOV     STATE,#10         ;    STATE:=10
         MOV     ABORT,#30         ;    ABORT:=30
         MOV     MTM0,#HUMH        ;    LOAD HUM. HOLD TIMER
         CLR     TFL4              ;    RESET TIMEOUT FLAG
         CLR     F0                ;    CLEAR HOLD FLAG
         SJMP    S83               ;    END
S91:     SETB    LT03              ;  ELSE, FILL-FAIL(ON)
         MOV     A,ABORT           ;    GET ABORT STATE
         MOV     STATE,A           ;    STATE:=ABORT-2
         SJMP    S93               ;    END
```

```
S92:      SETB      F0                  ;ELSE, SET HOLD FLAG
S93:      NOP                           ;  END
          LJMP      SEQR                ;RETURN
;
STATE10:  JNB       TFL4,S101           ;IF HUM. HOLD TIME
          MOV       STATE,#11           ;  STATE:=11
          MOV       ABORT,#30           ;  ABORT:=30
          CLR       MVC2                ;  CLEAR VC2 MASK
          CLR       MVO2                ;  CLEAR VO2 MASK
          SETB      VVO2                ;  OPEN V2
          CLR       MVC8                ;  CLEAR VC8 MASK
          CLR       MVO8                ;  CLEAR VO8 MASK
          SETB      VV08                ;  OPEN V8
          MOV       TTM0,#VDLY          ;  LOAD VALVE TIMEOUT
          CLR       TFL0                ;  RESET TIMEOUT FLAG
          SETB      TEN0                ;  ENABLE TIMEOUT ALARM
          MOV       STP0,#PSP1          ;  GET PRESS. SETPOINT
          CLR       MVO5                ;  CLEAR VO5 MASK
          CLR       MVC5                ;  CLEAR VC5 MASK
          SETB      CEN0                ;  ENABLE PRESS. LOOP (V5)
          CLR       F0                  ;  CLEAR HOLD FLAG
          SJMP      S102                ;  END
S101:     SETB      F0                  ;ELSE, SET HOLD FLAG
S102:     NOP                           ;    END
          LJMP      SEQR                ;RETURN
;
```

```
STATE11: MOV     C,LSO2          ;TEST V2 OPEN-
         ANL     C,LSO8          ;AND V8 OPEN
         JNC     S111            ;IF (V2.AND.V8) OPEN
         MOV     STATE,#12       ;  STATE:=12
         MOV     ABORT,#31       ;  ABORT:=31
         CLR     TEN0            ;  DISABLE TIMEOUT FLAG
         SETB    MVC2            ;  SET VC2 MASK
         SETB    MVO2            ;  SET VO2 MASK
         SETB    MVC8            ;  SET VC8 MASK
         SETB    MVO8            ;  SET V08 MASK
         MOV     STP3,#CSP1      ;  GET CONC. SETPOINT
         CLR     MVO4            ;  CLEAR VO4 MASK
         CLR     MVC4            ;  CLEAR VC4 MASK
         SETB    CEN3            ;  ENABLE CONC. LOOP (V4)
         MOV     MTM0,#CNCT      ;  LOAD CONC. TIMER
         CLR     TFL4            ;  RESET TIMEOUT FLAG
         CLR     LT14            ;  FILL-IN-PROGRESS(OFF)
         SETB    LT15            ;  STERIL-IN-PROGRESS(ON)
         CLR     F0              ;  CLEAR HOLD FLAG
         SJMP    S112            ;  END
S111:    SETB    F0              ;  ELSE, SET HOLD FLAG
S112:    NOP                     ;    END
         LJMP    SEQR            ;RETURN
;
STATE12: JNB     TFL4,S122       ;IF CONC. TIME
         CLR     C               ;  CLEAR CARRY
         MOV     A,ADI3          ;  GET CONC.
         SUBB    A,#CNOM         ;  SUBTRACT CONC. LEVEL
         JC      S121            ;  IF CONC.GE.CNOM
         MOV     STATE,#13       ;    STATE:=13
         MOV     ABORT,#31       ;    ABORT:=31
         MOV     MTM0,#CONH      ;    LOAD CONC. HOLD TIMER
         CLR     TFL4            ;    RESET TIMEOUT FLAG
         CLR     F0              ;    CLEAR HOLD FLAG
         SJMP    S123            ;    END
S121:    SETB    LT04            ;  ELSE, STERIL-FAIL(ON)
         MOV     A,ABORT         ;    GET ABORT STATE
         MOV     STATE,A         ;    STATE:=ABORT-3
         CLR     F0              ;    CLEAR HOLD FLAG
         SJMP    S123            ;    END
S122:    SETB    F0              ;ELSE, SET HOLD FLAG
S123:    NOP                     ;  END
         LJMP    SEQR            ;RETURN
;
STATE13: JNB     TFL4,S132       ;IF GAS HOLD TIME
         CLR     C               ;  CLEAR CARRY
         MOV     A,ADI3          ;  GET CONC.
         SUBB    A,#CNOM         ;  SUBTRACT CONC. LEVEL
         JC      S131            ;  IF CONC.GE.CNOM
         MOV     STATE,#14       ;    STATE:=14
         MOV     ABORT,#31       ;    ABORT:=31
         CLR     F0              ;    CLEAR HOLD FLAG
         SJMP    S133            ;    END
S131:    SETB    LT04            ;  ELSE, STERIL-FAIL(ON)
         MOV     A,ABORT         ;    GET ABORT STATE

         MOV     STATE,A         ;    STATE:=ABORT-3
         CLR     F0              ;    CLEAR HOLD FLAG
         SJMP    S133            ;    END
S132:    SETB    F0              ;ELSE, SET HOLD FLAG
S133:    NOP                     ;  END
         LJMP    SEQR            ;RETURN
;
```

```
STATE14: CLR     C                ;CLEAR CARRY
         MOV     A,ADI1           ;GET TEMP.
         SUBB    A,#TLOW          ;SUBTRACT MIN. TEMP.
         JC      S141             ;IF TEMP.GE.TMIN
         CLR     C                ;  CLEAR CARRY
         MOV     A,#TMAX          ;  GET MAX. TEMP LEVEL
         SUBB    A,ADI1           ;  SUBTRACT TEMP.
         JC      S141             ;  IF TEMP.LE.TMAX
         MOV     STATE,#15        ;    STATE:=15
         MOV     ABORT,#31        ;    ABORT:=31
         MOV     MTM0,#TSTR       ;    LOAD STERIL. TIMER
         CLR     TFL4             ;    RESET TIMEOUT FLAG
         CLR     F0               ;    CLEAR HOLD FLAG
         SJMP    S142             ;    END
S141:    SETB    LT04             ;ELSE, STERIL-FAIL(ON)
         MOV     A,ABORT          ;  GET ABORT STATE
         MOV     STATE,A          ;  STATE:=ABORT-3
         CLR     F0               ;  CLEAR HOLD FLAG
S142:    NOP                      ;  END
         LJMP    SEQR             ;RETURN
;
STATE15: JNB     TFL4,S151        ;IF STERIL. TIME
         MOV     STATE,#16        ;  STATE:=16
         MOV     ABORT,#31        ;  ABORT:=31
         CLR     CEN0             ;  PRESS. LOOP (OFF)
         CLR     CEN2             ;  HUM. LOOP (OFF)
         CLR     CEN3             ;  GAS LOOP (OFF)
         CLR     CTR0             ;  PRESS. OUTPUT (OFF)
         CLR     CTR2             ;  HUM. OUTPUT (OFF)
         CLR     CTR3             ;  GAS OUTPUT (OFF)
         CLR     VV06             ;  CLOSE V6
         CLR     VV05             ;  CLOSE V5
         CLR     VV04             ;  CLOSE V4
         MOV     TTM0,#VDLY       ;  LOAD TIMEOUT DELAY
         CLR     TFL0             ;  RESET TIMEOUT FLAG
         SETB    TEN0             ;  ENABLE TIMEOUT ALARM
         CLR     F0               ;  CLEAR HOLD FLAG
         SJMP    S152             ;  END
S151:    SETB    F0               ;ELSE, SET HOLD FLAG
S152:    NOP                      ;  END
         LJMP    SEQR             ;RETURN
;
STATE16: MOV     C,LSC4           ;TEST V4 CLOSED
         ANL     C,LSC5           ;AND V5 CLOSED
         ANL     C,LSC6           ;AND V6 CLOSED
         JNC     S161             ;IF (V4,V5,& V6) CLOSED
         MOV     STATE,#17        ;  STATE:=17
         MOV     ABORT,#31        ;  ABORT:=31
         CLR     TEN0             ;  DISABLE TIMEOUT ALARM
         SETB    MVC4             ;  SET VC4 MASK
         SETB    MV04             ;  SET V04 MASK
         SETB    MVC5             ;  SET VC5 MASK
         SETB    MV05             ;  SET V05 MASK
         SETB    MVC6             ;  SET VC6 MASK
         SETB    MV06             ;  SET V06 MASK
```

```
            CLR     MVC3                ; CLEAR VC3 MASK
            CLR     MVO3                ; CLEAR VO3 MASK
            SETB    VV03                ; OPEN V3
            CLR     LT15                ; STERIL-IN-PROGRESS(OFF)
            SETB    LT16                ; PURGE-IN-PROGRESS(ON)
            MOV     TTM0,#VDLY          ; LOAD TIMEOUT DELAY
            CLR     TFL0                ; RESET TIMEOUT FLAG
            SETB    TEN0                ; ENABLE TIMEOUT ALARM
            CLR     F0                  ; CLEAR HOLD FLAG
            SJMP    S162                ; END
S161:       SETB    F0                  ;ELSE, SET HOLD FLAG
S162:       NOP                         ; END
            LJMP    SEQR                ;RETURN
;
STATE17:    MOV     C,LS03              ;TEST V3 OPEN-
            ANL     C,LS08              ;AND V8 OPEN
            JNC     S171                ;IF (V3.AND.V8) OPEN
            MOV     STATE,#18           ; STATE:=18
            MOV     ABORT,#31           ; ABORT:=31
            CLR     TEN0                ; DISABLE TIMEOUT ALARM
            SETB    MVC3                ; SET VC3 MASK
            SETB    MVO3                ; SET VO3 MASK
            SETB    MVC8                ; SET VC8 MASK
            SETB    MVO8                ; SET VO8 MASK
            MOV     MTM0,#TEVC          ; LOAD EVAC. TIMER
            CLR     TFL4                ; RESET TIMEOUT FLAG
            CLR     F0                  ; CLEAR HOLD FLAG
            SJMP    S172                ; END
S171:       SETB    F0                  ;ELSE, SET HOLD FLAG
S172:       NOP                         ; END
            LJMP    SEQR                ;RETURN
;
```

```
STATE18: JNB     TFL4,S181          ;IF EVAC. TIME
         MOV     STATE,#19          ;  STATE:=19
         MOV     ABORT,#31          ;  ABORT:=31
         CLR     MVC3               ;  CLEAR VC3 MASK
         CLR     MVO3               ;  CLEAR VO3 MASK
         CLR     VV03               ;  CLOSE V3
         CLR     MVC8               ;  CLEAR VC8 MASK
         CLR     MVO8               ;  CLEAR VO8 MASK
         CLR     VV08               ;  CLOSE V8
         MOV     TTM0,#VDLY         ;  LOAD VALVE TIMER
         CLR     TFL0               ;  RESET TIMEOUT FLAG
         SETB    TEN0               ;  ENABLE TIMEOUT ALARM
         CLR     F0                 ;  CLEAR HOLD FLAG
         SJMP    S182               ;  END
S181:    SETB    F0                 ;ELSE, SET HOLD FLAG
S182:    NOP                        ;  END
         LJMP    SEQR               ;RETURN
;
STATE19: MOV     C,LSC3             ;TEST V3 CLOSED-
         ANL     C,LSC8             ;AND V8 CLOSED
         JNC     S191               ;IF (V3.AND.V8) CLOSED
         MOV     STATE,#20          ;  STATE:=20
         MOV     ABORT,#32          ;  ABORT:=32
         CLR     TEN0               ;  DISABLE TIMEOUT ALARM
         SETB    MVC8               ;  SET VC8 MASK
         SETB    MVO8               ;  SET VO8 MASK
         MOV     STP0,#PSP1         ;  GET PRESS. SETPOINT
         CLR     MVO5               ;  CLEAR VO5 MASK
         CLR     MVC5               ;  CLEAR VC5 MASK
         SETB    CEN0               ;  ENABLE PRESS. CONTROL (V5)
         MOV     MTM0,#PN2T         ;  LOAD N2 PRESS. TIMER
         CLR     TFL4               ;  RESET TIMEOUT FLAG
         CLR     F0                 ;  CLEAR HOLD FLAG
         SJMP    S192               ;  END
S191:    SETB    F0                 ;ELSE, SET HOLD FLAG
S192:    NOP                        ;  END
         LJMP    SEQR               ;RETURN
;
STATE20: JNB     TFL4,S202          ;IF REPRESS. TIME
         CLR     C                  ;  CLEAR CARRY
         MOV     A,#PMAX            ;  GET MIN.PRESS. LEVEL
         SUBB    A,AD10             ;  SUBTRACT PRESSURE
         JC      S201               ;  IF PRESS.GE.PMAX
         MOV     STATE,#21          ;    STATE:=21
         MOV     ABORT,#32          ;    ABORT:=32
         CLR     CEN0               ;    N2 LOOP (OFF)
         CLR     CTR0               ;    N2 OUTPUT (OFF)
         CLR     VV05               ;    CLOSE N2 VALVE
         MOV     TTM0,#VDLY         ;    LOAD VALVE TIMEOUT
         CLR     TFL0               ;    RESET TIMEOUT FLAG
         SETB    TEN0               ;    ENABLE TIMEOUT ALARM
         CLR     F0                 ;    CLEAR HOLD FLAG
         SJMP    S202               ;    END
S201:    SETB    LT05               ;  ELSE, PURGE-FAIL(ON)
         MOV     A,ABORT            ;    GET ABORT STATE

         MOV     STATE,A            ;    STATE:=ABORT-4
         CLR     F0                 ;    CLEAR HOLD TIMER
         SJMP    S203               ;    END
S202:    SETB    F0                 ;ELSE, SET HOLD TIMER
S203:    NOP                        ;  END
         LJMP    SEQR               ;RETURN
;
```

```
STATE21: JNB     LSC5,S211          ;IF V5 CLOSED
         MOV     STATE,#22          ;  STATE:=22
         MOV     ABORT,#33          ;  ABORT:=33
         CLR     TEN0               ;  DISABLE TIMEOUT ALARM
         SETB    MVC5               ;  SET VC5 MASK
         SETB    MVO5               ;  SET VO5 MASK
         CLR     MVC3               ;  CLEAR VC3 MASK
         CLR     MVO3               ;  CLEAR VO3 MASK
         SETB    VV03               ;  OPEN V3
         CLR     MVC8               ;  CLEAR VC8 MASK
         CLR     MVO8               ;  CLEAR VO8 MASK
         SETB    VV08               ;  OPEN V8
         MOV     TTM0,#VDLY         ;  LOAD TIMEOUT DELAY
         CLR     TFL0               ;  RESET TIMEOUT FLAG
         SETB    TEN0               ;  ENABLE TIMEOUT ALARM
         CLR     F0                 ;  CLEAR HOLD FLAG
         SJMP    S212               ;  END
S211:    SETB    F0                 ;ELSE, SET HOLD FLAG
S212:    NOP                        ;  END
         LJMP    SEQR               ;RETURN
;
STATE22: MOV     C,LS03             ;TEST V3 OPEN-
         ANL     C,LS08             ;AND V8 OPEN
         JNC     S221               ;IF (V3.AND.V8) OPEN
         MOV     STATE,#23          ;  STATE:=23
         MOV     ABORT,#33          ;  ABORT:=33
         CLR     TEN0               ;  DISABLE TIMEOUT ALARM
         SETB    MVC3               ;  SET VC3 MASK
         SETB    MVO3               ;  SET VO3 MASK
         SETB    MVC8               ;  SET VC8 MASK
         SETB    MVO8               ;  SET VO8 MASK
         MOV     MTM0,#DSRB         ;  LOAD DESORB TIMER
         CLR     TFL4               ;  RESET TIMEOUT FLAG
         CLR     F0                 ;  CLEAR HOLD FLAG
         SJMP    S222               ;  END
S221:    SETB    F0                 ;  ELSE, SET HOLD FLAG
S222:    NOP                        ;    END
         LJMP    SEQR               ;RETURN
;
STATE23: JNB     TFL4,S231          ;IF DESORB TIME
         MOV     STATE,#24          ;  STATE:=24
         MOV     ABORT,#34          ;  ABORT:=34
         CLR     MVC3               ;  CLEAR VC3 MASK
         CLR     MVO3               ;  CLEAR VO3 MASK
         CLR     VV03               ;  CLOSE V3
         CLR     MVC8               ;  CLEAR VC8 MASK
         CLR     MVO8               ;  CLEAR VO8 MASK
         CLR     VV08               ;  CLOSE V8
         CLR     MVC2               ;  CLEAR VC2 MASK
         CLR     MVO2               ;  CLEAR VO2 MASK
         CLR     VV02               ;  CLOSE V2
         MOV     TTM0,#VDLY         ;  LOAD TIMEOUT DELAY
         CLR     TFL0               ;  RESET TIMEOUT FLAG
         SETB    TEN0               ;  ENABLE TIMEOUT ALARM
         CLR     F0                 ;  CLEAR HOLD FLAG

         SJMP    S232
S231:    SETB    F0                 ;  END
S232:    NOP                        ;ELSE, SET HOLD FLAG
         LJMP    SEQR               ;  END
;                                   ;RETURN
```

```
STATE24: MOV     C,LSC3          ;TEST V3 CLOSED-
         ANL     C,LSC8          ;AND V8 CLOSED-
         ANL     C,LSC2          ;AND V2 CLOSED
         JNC     S241            ;IF (V2,V3,V8 CLOSED)
         MOV     STATE,#25       ;  STATE:=25
         MOV     ABORT,#35       ;  ABORT:=35
         CLR     TEN0            ;  DISABLE TIMEOUT MASK
         SETB    MVC3            ;  SET VC3 MASK
         SETB    MVO3            ;  SET VO3 MASK
         SETB    MVC8            ;  SET VC8 MASK
         SETB    MVO8            ;  SET VO8 MASK
         SETB    MVC2            ;  SET VC2 MASK
         SETB    MVO2            ;  SET VO2 MASK
         SETB    LGG1            ;  SWITCH TO HIGH GAIN
         MOV     MTM0,#TLGH      ;  START LOW GAS HOLD
         LCALL   DCT0            ;  DECREMENT PURGE COUNT
         CLR     TFL4            ;  RESET TIMEOUT FLAG
         CLR     F0              ;  CLEAR HOLD FLAG
         SJMP    S242            ;  END
S241:    SETB    F0              ;ELSE, SET HOLD FLAG
S242:    NOP                     ;  END
         LJMP    SEQR            ;RETURN
;
STATE25: JNB     TFL4,S252       ;IF LOW-HOLD TIME
         CLR     C               ;  CLEAR CARRY
         MOV     A,#CMIN         ;  GET MAX. LEVEL
         SUBB    A,ADI3          ;  SUBTRACT CONC.
         ORL     C,/TFL6         ;  OR CARRY WITH COUNT FLAG
         JC      S251            ;  IF (CONC.LE.CMIN).AND.TFL6=1
         MOV     STATE,#26       ;    STATE:=26
         MOV     ABORT,#36       ;    ABORT:=36
         CLR     CEN1            ;    DISABLE TEMP. CTRL
         CLR     PP01            ;    TURN PUMP OFF
         CLR     HT01            ;    TURN HEATER OFF
         CLR     LGG1            ;    SET LOW GAIN
         CLR     F0              ;    CLEAR HOLD FLAG
         SJMP    S253            ;    END
S251:    MOV     A,ABORT         ;  ELSE, GET ABORT STATE
         MOV     STATE,A         ;    STATE:=35
         CLR     F0              ;    CLEAR HOLD FLAG
         SJMP    S253            ;    END
S252:    SETB    F0              ;ELSE, SET HOLD FLAG
S253:    NOP                     ;  END
         LJMP    SEQR            ;RETURN
;
STATE26: LCALL   GTCT            ;DECREMENT & GET CYCLE CNT
         JNZ     S261            ;IF LAST RUN
         MOV     STATE,#27       ;  STATE:=27
         MOV     ABORT,#36       ;  ABORT:=36
         CLR     MVC2            ;  CLEAR VC2 MASK
         CLR     MVO2            ;  CLEAR VO2 MASK
         SETB    VV02            ;  OPEN V2
         CLR     MVC3            ;  CLEAR VC3 MASK
         CLR     MVO3            ;  CLEAR VO3 MASK
         SETB    VV03            ;  OPEN V3
```

```
        CLR     MVC4                ; CLEAR VC4 MASK
        CLR     MVO4                ;  CLEAR VO4 MASK
        SETB    VV04                ; OPEN V4
        CLR     MVC8                ;  CLEAR VC8 MASK
        CLR     MVO8                ;  CLEAR VO8 MASK
        SETB    VV08                ;  OPEN V8
        MOV     MTM0,#TDMP          ;  LOAD DUMP TIMER
        CLR     TFL4                ;  RESET TIMEOUT FLAG
        CLR     F0                  ;  CLEAR HOLD FLAG
        SJMP    S262                ;  END
S261:   MOV     STATE,#28           ;ELSE, STATE:=28
        MOV     ABORT,#36           ;  ABORT:=36
        CLR     F0                  ;  CLEAR HOLD FLAG
S262:   NOP                         ;  END
        LJMP    SEQR                ;RETURN
```

```
STATE27: JNB     TFL4,S271      ;IF DUMP-TIME
         MOV     STATE,#28      ;  STATE:=28
         MOV     ABORT,#36      ;  ABORT:=36
         CLR     VV02           ;  CLOSE V2
         CLR     VV03           ;  CLOSE V3
         CLR     VV04           ;  CLOSE V4
         CLR     VV08           ;  CLOSE V8
         CLR     F0             ;  CLEAR HOLD FLAG
         SJMP    S272           ;  END
S271:    SETB    F0             ;ELSE, SET HOLD FLAG
S272:    NOP                    ;  END
         LJMP    SEQR           ;RETURN
;
STATE28: MOV     STATE,#37      ;STATE:=37
         MOV     ABORT,#36      ;ABORT:=36
         CLR     MV05           ;CLR V05 MASK
         CLR     MVC5           ;CLR VC5 MASK
         SETB    CEN0           ;PRESS. CONTROL(ON)
         MOV     STP0,#PATM     ;SET ATM. SETPOINT
         CLR     F0             ;CLEAR HOLD FLAG
         LJMP    SEQR           ;RETURN
;
STATE29: MOV     C,LSC1         ;TEST V1 CLOSED-
         ANL     C,LSC2         ;AND V2 CLOSED-
         ANL     C,LSC3         ;AND V3 CLOSED-
         ANL     C,LSC4         ;AND V4 CLOSED-
         ANL     C,LSC5         ;AND V5 CLOSED-
         ANL     C,LSC6         ;AND V6 CLOSED-
         ANL     C,LSO7         ;AND V7 OPEN-
         ANL     C,LSC8         ;AND V8 CLOSED-
         ANL     C,SWC2         ;AND SW2 PUSHED
         JNC     S291           ;IF RESET
         MOV     STATE,#2       ;  STATE:=2
         MOV     ABORT,#0       ;  ABORT:=0
         MOV     STAT,#00H      ;  RESET STATUS
         MOV     CC00,#00H      ;  RESET ALARM LIGHTS
         MOV     CC01,#01H      ;  RESET RUN LIGHTS
         CLR     F0             ;  CLEAR HOLD FLAG
         SJMP    S292           ;  END
S291:    MOV     CTRL,#00H      ;ELSE, RESET CONTROLS
         MOV     TCEN,#00H      ;  RESET ALARMS
         MOV     MSK0,#00H      ;  RESET CLOSED MASKS
         MOV     MSK1,#00H      ;  RESET OPEN MASKS
         MOV     MSK2,#00H      ;  RESET MISC. MASKS
         MOV     CC02,#40H      ;  RESET VALVES
         MOV     CC03,#00H      ;  RESET MISC. OUTPUTS
         MOV     CC01,#00H      ;  TURN CYCLE LIGHTS OFF
         SETB    LT02           ;  EVAC-FAIL(ON)
         SETB    F0             ;  SET HOLD FLAG
S292:    NOP                    ;  END
         LJMP    SEQR           ;RETURN
;
```

```
STATE30: MOV     C,LSC1          ;TEST V1 CLOSED-
         ANL     C,LSC2          ;AND V2 CLOSED-
         ANL     C,LSC3          ;AND V3 CLOSED-
         ANL     C,LSC4          ;AND V4 CLOSED-
         ANL     C,LSC5          ;AND V5 CLOSED-
         ANL     C,LSC6          ;AND V6 CLOSED-
         ANL     C,LSO7          ;AND V7 OPEN-
         ANL     C,LSC8          ;AND V8 CLOSED-
         ANL     C,SWC2          ;AND SW2 PUSHED
         JNC     S301            ;IF RESET
         MOV     STATE,#2        ;  STATE:=2
         MOV     ABORT,#0        ;  ABORT:=0
         MOV     STAT,#00H       ;  RESET STATUS
         MOV     CCO0,#00H       ;  RESET ALARM LIGHTS
         MOV     CCO1,#01H       ;  RESET RUN LIGHTS
         CLR     F0              ;  CLEAR HOLD FLAG
         SJMP    S302            ;  END
S301:    MOV     CTRL,#00H       ;ELSE, RESET CONTROLS
         MOV     TCEN,#00H       ;  RESET ALARMS
         MOV     MSK0,#00H       ;  RESET CLOSED MASKS
         MOV     MSK1,#00H       ;  RESET OPEN MASKS
         MOV     MSK2,#00H       ;  RESET MISC. MASKS
         MOV     CCO2,#40H       ;  RESET VALVES
         MOV     CCO3,#00H       ;  RESET MISC. OUTPUTS
         MOV     CCO1,#00H       ;  TURN CYCLE LIGHTS OFF
         SETB    LT03            ;  FILL-FAIL(ON)
         SETB    F0              ;  SET HOLD FLAG
S302:    NOP                     ;  END
         LJMP    SEQR            ;RETURN
```

```
STATE31: MOV     C,LSC1          ;TEST V1 CLOSED-
         ANL     C,LSO2          ;AND V2 OPEN-
         ANL     C,LSC3          ;AND V3 CLOSED
         ANL     C,LSC4          ;AND V4 CLOSED-
         ANL     C,LSC6          ;AND V6 CLOSED-
         ANL     C,LSC7          ;AND V7 CLOSED-
         ANL     C,LSC8          ;AND V8 CLOSED-
         ANL     C,SWC2          ;AND SW2 PUSHED
         JNC     S311            ;IF RESET
         MOV     STATE,#20       ;  STATE:=20
         MOV     ABORT,#31       ;  ABORT:=32
         MOV     STAT,#00H       ;  RESET STATUS
         MOV     MSK0,#0EFH      ;  SET ALL CLOSED MASKS
         MOV     MSK1,#0EFH      ;  SET ALL OPEN MASKS
         MOV     MSK2,#001H      ;  SET MISC. MASKS
         MOV     CCO0,#00H       ;  RESET ALARM LIGHTS
         MOV     CCO1,#22H       ;  RESET RUN LIGHTS
         CLR     F0              ;  CLEAR HOLD FLAG
         SJMP    S312            ;  END
S311:    MOV     CTRL,#03H       ;ELSE, RESET CONTROLS
         MOV     TCEN,#00H       ;  RESET ALARMS
         MOV     MSK0,#00H       ;  RESET CLOSED MASKS
         MOV     MSK1,#00H       ;  RESET OPEN MASKS
         MOV     MSK2,#00H       ;  RESET MISC. MASKS
         MOV     CCO2,#02H       ;  RESET ALL VALVES
         MOV     CCO3,#01H       ;  RESET MISC. OUTPUTS
         SETB    LT04            ;  STERIL-FAIL(ON)
         SETB    F0              ;  SET HOLD FLAG
S312:    NOP                     ;  END
         LJMP    SEQR            ;RETURN
;
STATE32: MOV     C,LSC5          ;TEST V5 CLOSED
         ANL     C,SWC2          ;AND SW2
         JNC     S321            ;IF (V5 CLOSED & SW2 PUSHED)
         MOV     STATE,#19       ;  STATE:=19
         MOV     ABORT,#32       ;  ABORT:=32
         CLR     F0              ;  CLEAR HOLD FLAG
         SJMP    S322            ;  END
S321:    MOV     CCO2,#02H       ;ELSE, RESET ALL VALVES
         SETB    F0              ;  SET HOLD FLAG
S322:    NOP                     ;  END
         LJMP    SEQR            ;RETURN
;
STATE33: MOV     C,SWC2          ;TEST SW2
         JNC     S331            ;IF PUSHED
         MOV     STATE,#23       ;  STATE:=23
         MOV     ABORT,#33       ;  ABORT:=34
         CLR     F0              ;  CLEAR HOLD FLAG
         SJMP    S332            ;  END
S331:    SETB    F0              ;ELSE, SET HOLD FLAG
S332:    NOP                     ;  END
         LJMP    SEQR            ;RETURN
;
STATE34: MOV     C,SWC2          ;TEST SW2
         JNC     S341            ;IF PUSHED

         MOV     STATE,#25       ;  STATE:=25
         MOV     ABORT,#35       ;  ABORT:=35
         LCALL   DCT0            ;  DECREMENT PURGE COUNT
         CLR     F0              ;  CLEAR HOLD FLAG
         SJMP    S342            ;  END
S341:    SETB    F0              ;ELSE, SET HOLD FLAG
S342:    NOP                     ;  END
         LJMP    SEQR            ;RETURN
```

```
STATE35: MOV     C,LSC1          ;TEST V1 CLOSED-
         ANL     C,LSO2          ;AND V2 OPEN-
         ANL     C,LSC3          ;AND V3 CLOSED-
         ANL     C,LSC4          ;AND V4 CLOSED-
         ANL     C,LSC5          ;AND V5 CLOSED-
         ANL     C,LSC6          ;AND V6 CLOSED-
         ANL     C,LSC7          ;AND V7 CLOSED-
         ANL     C,LSC8          ;AND V8 CLOSED-
         JNC     S351            ;IF RESET
         MOV     STATE,#20       ;  STATE:=20
         MOV     ABORT,#32       ;  ABORT:=32
         MOV     STAT,#00H       ;  RESET STATUS
         MOV     MSK0,#0EFH      ;  SET ALL CLOSED MASKS
         MOV     MSK1,#0EFH      ;  SET ALL OPEN MASKS
         MOV     MSK2,#001H      ;  SET MISC. MASKS
         MOV     CCO0,#00H       ;  RESET ALARM LIGHTS
         MOV     CCO1,#22H       ;  RESET RUN LIGHTS
         MOV     STP0,#PSP1      ;  LOAD PRESS. SETPOINT
         SETB    CEN0            ;  ENABLE PRESSURE CONTROL
         MOV     MTM0,#PN2T      ;  SET PRESSURE TIMER
         CLR     TFL4            ;  CLEAR TIMER FLAG
         CLR     F0              ;  CLEAR HOLD FLAG
         SJMP    S352            ;  END
S351:    MOV     CTRL,#03H       ;ELSE, RESET CONTROLS
         MOV     TCEN,#00H       ;  RESET ALARMS
         MOV     MSK0,#00H       ;  RESET CLOSED MASKS
         MOV     MSK1,#00H       ;  RESET OPEN MASKS
         MOV     MSK2,#00H       ;  RESET MISC. MASKS
         MOV     CCO2,#02H       ;  RESET ALL VALVES
         MOV     CCO3,#01H       ;  RESET MISC. OUTPUTS
         SETB    F0              ;  SET HOLD FLAG
S352:    NOP                     ;  END
         LJMP    SEQR            ;RETURN
;


STATE36: MOV     C,SWC2          ;TEST SW2
         JNC     S361            ;IF PUSHED
         MOV     STATE,#26       ;  STATE:=26
         MOV     ABORT,#37       ;  ABORT:=37
         CLR     F0              ;  CLEAR HOLD FLAG
         SJMP    S362            ;  END
S361:    SETB    F0              ;ELSE, SET HOLD FLAG
S362:    NOP                     ;  END
         LJMP    SEQR            ;RETURN
;
```

```
STATE37: CLR     C              ;CLEAR CARRY
         MOV     A,#PATM        ;GET ATM SETPOINT
         SUBB    A,AD10         ;SUBTRACT PRESSURE
         JC      S371           ;IF PRESS.GT.ATM
         MOV     STATE,#38      ;  STATE:=38
         MOV     ABORT,#0       ;  ABORT:=0
         CLR     MVC7           ;  CLEAR VC7 MASK
         CLR     MV07           ;  CLEAR V07 MASK
         CLR     CEN0           ;  N2 LOOP(OFF)
         CLR     CTR0           ;  N2 OUTP(OFF)
         CLR     VV05           ;  CLOSE N2 VALVE
         SETB    VV07           ;  OPEN V7
         CLR     LT16           ;  PURGE-IN-PROGRESS(OFF)
         SETB    LT17           ;  REMOVE-LOAD(ON)
         CLR     F0             ;  CLEAR HOLD FLAG
         SJMP    S372           ;  END
S371:    SETB    F0             ;ELSE, SET HOLD FLAG
S372:    NOP                    ;  END
         LJMP    SEQR           ;RETURN
;
STATE38: JNB     SWC2,S381      ;IF SW2 PUSHED
         MOV     STATE,#0       ;  STATE:=0 (RESET)
         MOV     ABORT,#0       ;  ABORT:=0
         CLR     F0             ;  CLEAR HOLD FLAG
         SJMP    S382           ;  END
S381:    SETB    F0             ;ELSE, SET HOLD FLAG
S382:    NOP                    ;  END
         LJMP    SEQR           ;RETURN
;
```

In the foregoing specification, the invention has been described with reference to a specific exemplary embodiment thereof. It will, however, be evident that various modifications and changes may be made thereunto without parting from the broader spirit and scope of the invention as set forth in the appended claims. For example, as will be appreciated by those of ordinary skill in the art familiar with this specification, the apparatus

disclosed herein may be suitable for use in connection with various types of gaseous treatment systems, such as those which employ toxic gases, e.g., without limitation, bleaching gases, fumigants, sterilants, etc. The specification and drawings are, accordingly, to be regarded in an illustrative rather than a restrictive sense.

WHAT IS CLAIMED IS:

1. Apparatus for treating articles with a gas comprising:

chamber means for receiving an article to be treated;

means for supplying the gas to the chamber means comprising valve means coupled to the chamber means for supplying the gas to the chamber means, means for removing the gas from the chamber means after a predetermined time interval, electronic control means receiving a plurality of electrical signals associated with ones of measured parameters from said chamber means for controlling said valve means and said means for removing, said electronic control means comprising computer means for cycling said apparatus through a plurality of states in accordance with a predetermined sequence of instructions, said computer means including means for aborting the operation of said apparatus to one of a plurality of defined failure states in response to a failure of said apparatus, said selected failure state dependent on the state in said cycle in which the failure occurred.

2. The apparatus recited in claim 1 wherein said gas is a sterilizing gas, whereby said article is sterilized by said gas.

3. The apparatus recited in claim 2, wherein said sterilizing gas is generated from at least two component parts, and further including first means for receiving a first component part of the gas, second means for receiving a second component part of the gas, means for allowing said first and second component parts to react with each other to generate said sterilizing gas, said means for allowing being controlled by said computer means in response to the measurement of selected ones of said plurality of measured parameters.

4. The apparatus recited in claim 3, further comprising valve means for supplying a relatively stable gas to said chamber means.

5. The apparatus recited in claim 3, further comprising valve means for supplying filtered air to said chamber means.

6. The apparatus recited in claim 3, further comprising valve means for supplying water vapor to said chamber means to affect the humidity level in said chamber.

7. The apparatus recited in claim 3 wherein said plurality of measured parameters include the temperature, pressure and humidity in said chamber means and the concentration of said sterilizing gas in said chamber means.

8. The apparatus recited in claim 2 wherein said sterilizing gas comprises chlorine dioxide.

9. The apparatus recited in claim 3 wherein said sterilizing gas comprises chlorine dioxide and said first component comprises chlorine gas and said second component comprises sodium chlorite.

10. The apparatus recited in claim 2 wherein said means for removing comprises vacuum pump means and additional valve means.

11. The apparatus recited in claim 2, wherein said valve means comprises first and second switch means, said first switch means indicating when said valve means is open and said second switch means indicating when said valve means is closed, said first and second switch means being in opposite states such that when said first switch means is closed, said second switch means is open.

12. The apparatus recited in claim 2, wherein said electronic control means comprises memory means, and further comprising means for receiving input signals from said valve means indicative of the closed or open condition of said valve means and means for transmitting output signals to said valve means to selectively open or close said valve means, image signals of said input and output signals being stored in said memory means.

13. The apparatus recited in claim 12, further comprising means for disabling said output signals from being transmitted to said valve means except when an enabling signal is issued by said computer means.

14. The apparatus recited in claim 2, further comprising means for monitoring for proper operation of said computer means, said monitoring means issuing a disabling signal to prevent actuation of said valve means in the event of a failure of said computer means.

15. The apparatus recited in claim 12, further comprising mask means stored in said memory means, said computer means comparing said image signals of said input and output signals and generating an alarm signal if said input and output image signals do not agree in response to the setting of a bit in said mask means.

16. The apparatus recited in claim 11, further comprising means for monitoring the state of said first and second switch means, and further comprising means for generating an alarm signal if said first and second switch means are not in the proper states.

17. The apparatus recited in claim 2, wherein said valve means moves between a first state and a second state in response to instructions from said computer means, and further comprising timer means for generating an alarm

signal if said valve means does not move from said first to second state in a predetermined time interval.

18. The apparatus recited in claim 2, further comprising means for cycling said apparatus to a further defined state once one of said defined failure states is reached.

19. Apparatus for treating articles with a gas comprising:

first means for receiving a first component;

second means for receiving a second component, said first and second components, when reacted together, forming said gas;

means for reacting said two components together for forming said gas;

first valve means for supplying said gas to said chamber means to treat said article in said chamber means;

means for removing said gas from said chamber means;

electronic controller means for controlling said means for reacting, means for supplying and means for removing comprising computer means executing a predetermined sequence of steps so as to cycle said apparatus through a series of successive states defining a cycle in which said article is treated by said gas and wherein said gas is thereafter removed from said chamber means so as to render said chamber means within acceptable standards of safety.

20. The apparatus recited in claim 19 wherein said gas is a sterilizing gas, whereby said article is sterilized by said gas.

21. The apparatus recited in claim 20 wherein said computer means comprises means for receiving a plurality of electrical signals associated with ones of measured parameters from said chamber means for controlling the operation of said means for reacting, means for supplying

and means for removing.

22. The apparatus recited in claim 21, wherein said means for reacting comprises second valve means for allowing said first and second components to react with each other to generate said sterilizing gas, said second valve means being controlled by said computer means in response to the measurement of selected ones of said plurality of measured parameters.

23. The apparatus recited in claim 22, further comprising valve means for supplying a relatively stable gas to said chamber means.

24. The apparatus recited in claim 22, further comprising valve means for supplying filtered air to said chamber means.

25. The apparatus recited in claim 22, further comprising valve means for supplying water vapor to said chamber means to affect the humidity level in said chamber.

26. The apparatus recited in claim 22 wherein said plurality of measured parameters include the temperature, pressure and humidity in said chamber means and the concentration of said sterilizing gas in said chamber means.

27. The apparatus recited in claim 20 wherein said sterilizing gas comprises chlorine dioxide.

28. The apparatus recited in claim 27 wherein said sterilizing gas comprises chlorine dioxide and said first component comprises chlorine gas and said second component comprises sodium chlorite.

29. The apparatus recited in claim 20 wherein said means for removing comprises vacuum pump means and additional valve

means.

30. The apparatus recited in claim 20, wherein said valve means comprises first and second switch means, said first switch means indicating when said valve means is open and said second switch means indicating when said valve means is closed, said first and second switch means being in opposite states such that when said first switch means is closed, said second switch means is open.

31. The apparatus recited in claim 20, wherein said electronic control means comprises memory means, and further comprising means for receiving input signals from said valve means indicative of the closed or open condition of said valve means and means for transmitting output signals to said valve means to selectively open or close said valve means, images of said input and output signals being stored in said memory means.

32. The apparatus recited in claim 31, further comprising means for disabling said output signals from being transmitted to said valve means except when an enabling signal is issued by said computer means.

33. The apparatus recited in claim 20, further comprising means for monitoring for proper operation of said computer means, said monitoring means issuing a disabling signal to prevent actuation of said valve means in the event of a failure of said computer means.

34. The apparatus recited in claim 31, further comprising mask means stored in said memory means, said computer means comparing said images of said input and output signals and generating an alarm signal if said input and output images do not agree in response to the setting of a bit in said mask means.

35. The apparatus recited in claim 30, further comprising means for monitoring the state of said first and second switch means, and further comprising means for generating an alarm signal if said first and second switch means are not in the proper states.

36. The apparatus recited in claim 20, wherein said valve means moves between a first state and a second state in response to instructions from said computer means, and further comprising timer means for generating an alarm signal if said valve means does not move from said first to second state in a predetermined time interval.

37. The apparatus recited in claim 20, wherein said computer means includes means for aborting the operation of said apparatus to one of a plurality of defined failure states in response to a failure of said apparatus, said selected failure state dependent on the state in said cycle in which the failure occurred.

38. The apparatus recited in claim 37, further comprising means for resetting said apparatus to a further defined state once one of said defined failure states is reached.

39. Apparatus for treating articles with a gas comprising:

chamber means for receiving articles to be treated;

means for supplying the gas to the chamber means comprising valve means coupled to the chamber means for supplying the gas to the chamber means, means for removing the gas from the chamber means after a predetermined time interval, electronic control means receiving a plurality of electrical signals associated with ones of measured parameters from said chamber means for controlling said valve means and said means for removing, said electronic control means comprising computer means for cycling said apparatus through a plurality of states in accordance with a predetermined

sequence of instructions,

said computer means including memory means, and further comprising means for receiving input signals from said valve means indicative of the closed or open condition of said valve means and means for transmitting output signals to said valve means to selectively open or close said valve means, image signals of said input and output signals being stored in said memory means,

mask means being stored in said memory means, said computer means comparing said image signals of said input and output signals and generating an alarm signal if said input and output image signals do not agree in response to the setting of a bit in said mask means.

40. The apparatus recited in claim 39, wherein said gas is a sterilizing gas, whereby said article is sterilized by said gas.

41. The apparatus recited in claim 40, wherein said sterilizing gas is generated from at least two component parts, and further including first means for receiving a first component part of the gas, second means for receiving a second component part of the gas, means for allowing said first and second component parts to react with each other to generate said sterilizing gas, said means for allowing being controlled by said computer means in response to the measurement of selected ones of said plurality of measured parameters.

42. The apparatus recited in claim 41, further comprising valve means for supplying a relatively stable gas to said chamber means.

43. The apparatus recited in claim 41, further comprising valve means for supplying filtered air to said chamber means.

44. The apparatus recited in claim 41, further comprising valve means for supplying water vapor to said chamber means to affect the humidity level in said chamber.

45. The apparatus recited in claim 41, wherein said plurality of measured parameters include the temperature, pressure and humidity in said chamber means and the concentration of said sterilizing gas in said chamber means.

46. The apparatus recited in claim 40 wherein said sterilizing gas comprises chlorine dioxide.

47. The apparatus recited in claim 41 wherein said sterilizing gas comprises chlorine dioxide and said first component comprises chlorine gas and said second component comprises sodium chlorite.

48. The apparatus recited in claim 40 wherein said means for removing comprises vacuum pump means and additional valve means.

49. The apparatus recited in claim 40, wherein said valve means comprises first and second switch means, said first switch means indicating when said valve means is open and said second switch means indicating when said valve means is closed, said first and second switch means being in opposite states such that when said first switch means is closed, said second switch means is open.

50. The apparatus recited in claim 40, further comprising means for disabling said output signals from being transmitted to said valve means except when an enabling signal is issued by said computer means.

51. The apparatus recited in claim 40, further comprising means for monitoring for proper operation of said computer means, said monitoring means issuing a disabling

signal to prevent actuation of said valve means in the event of a failure of said computer means.

52. The apparatus recited in claim 49, further comprising means for monitoring the state of said first and second switch means, and further comprising means for generating an alarm signal if said first and second switch means are not in the proper states.

53. The apparatus recited in claim 40, wherein said valve means moves between a first state and a second state in response to instructions from said computer means, and further comprising timer means for generating an alarm signal if said valve means does not move from said first to second state in a predetermined time interval.

54. The apparatus recited in claim 40, wherein said computer means further comprises means for aborting the operation of said apparatus to one of a plurality of defined failure states in response to a failure of said apparatus, said selected failure state dependent on the state in said cycle in which the failure occurred.

55. The apparatus recited in claim 39, further comprising means for cycling said apparatus to a further defined state once one of said defined failure states is reached.

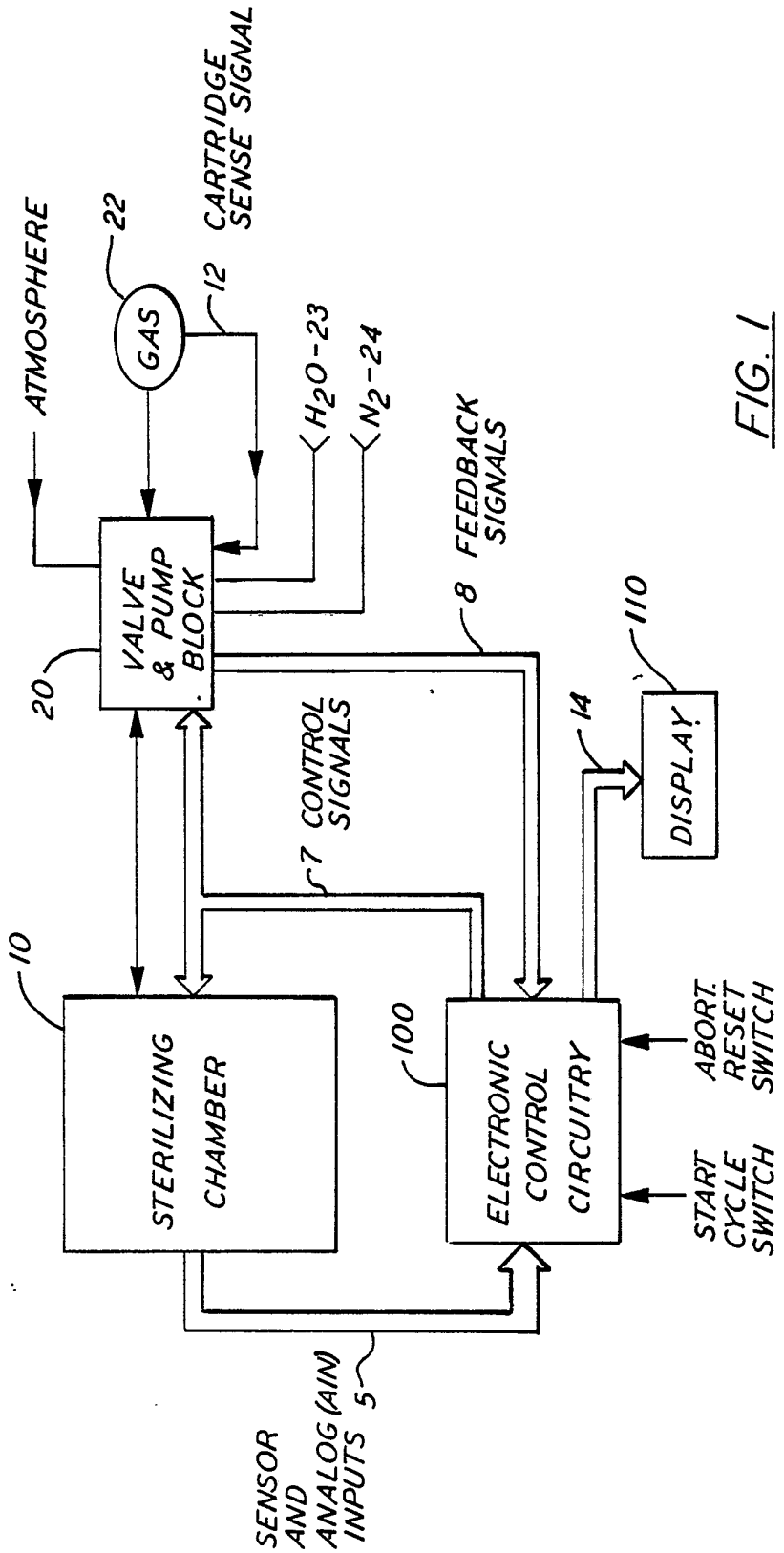

ATMOSPHERE
22
GAS
CARTRIDGE SENSE SIGNAL
12
H_2O-23
N_2-24
FEEDBACK SIGNALS
8
VALVE & PUMP BLOCK
20
110
DISPLAY
14
CONTROL SIGNALS
7
10
STERILIZING CHAMBER
100
ELECTRONIC CONTROL CIRCUITRY
ABORT. RESET SWITCH S2
START CYCLE SWITCH S1
SENSOR AND ANALOG (AIN) INPUTS 5

FIG. 1

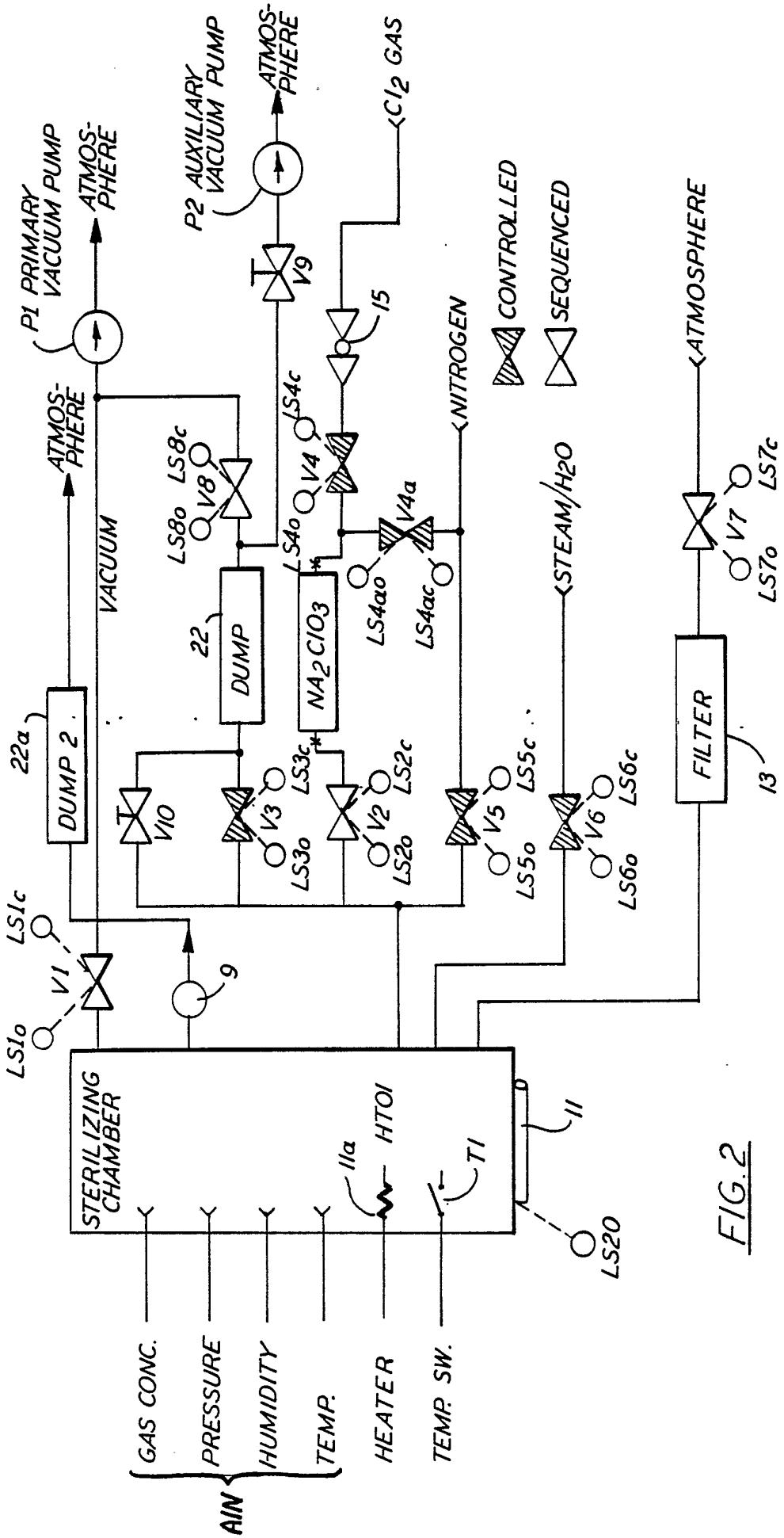

P1 PRIMARY VACUUM PUMP
ATMOS-PHERE
P2 AUXILIARY VACUUM PUMP
ATMOS-PHERE
Cl2 GAS
NITROGEN
CONTROLLED
SEQUENCED
ATMOSPHERE
STEAM/H2O
VACUUM
22
DUMP
NA2 ClO3
22a
DUMP 2
FILTER
13
15
V1
V2
V3
V4
V4a
V5
V6
V7
V8
V9
V10
LS1c
LS1o
LS2c
LS2o
LS3c
LS3o
LS4c
LS4o
LS4ac
LS4ao
LS5c
LS5o
LS6c
LS6o
LS7c
LS7o
LS8c
LS8o
9
STERILIZING CHAMBER
11
11a
HTOI
T1
LS20
GAS CONC.
PRESSURE
HUMIDITY
TEMP.
HEATER
TEMP. SW.
AIN

FIG. 2

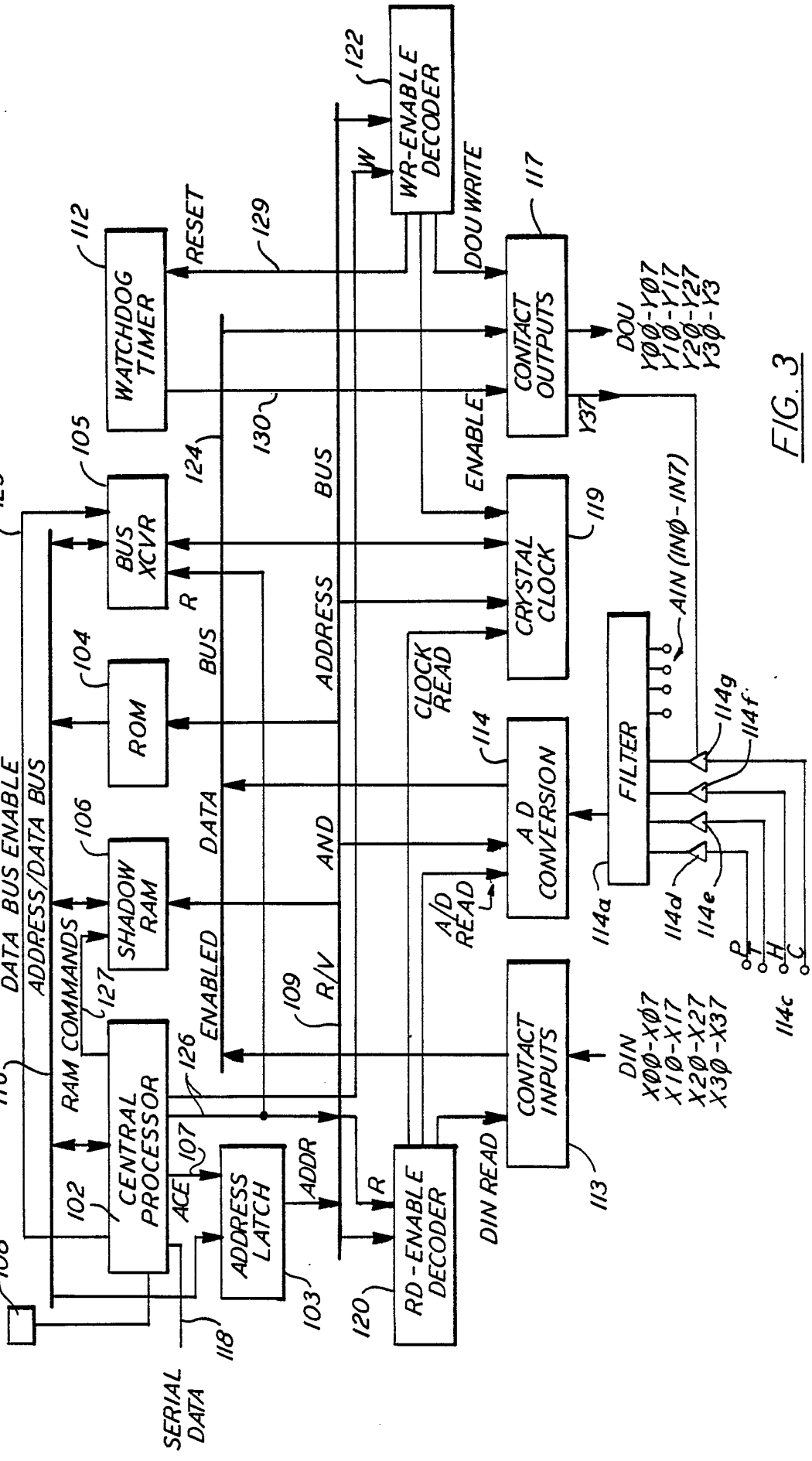

WATCHDOG TIMER
112
RESET
129
WR-ENABLE DECODER
122
W
DOU WRITE
117
CONTACT OUTPUTS
DOU Y00-Y07 Y10-Y17 Y20-Y27 Y30-Y3
Y37
ENABLE
BUS XCVR
105
125
124
130
BUS
R
ADDRESS
CRYSTAL CLOCK
119
AIN (IN0-IN7)
ROM
104
BUS
CLOCK READ
114
A D CONVERSION
FILTER
114g
114f
DATA BUS ENABLE
ADDRESS/DATA BUS
SHADOW RAM
106
DATA
AND
A/D READ
114a
114d
114e
P
H
C
114c
RAM COMMANDS
127
ENABLED
109
R/V
CENTRAL PROCESSOR
116
126
CONTACT INPUTS
DIN X00-X07 X10-X17 X20-X27 X30-X37
102
107
ACE
ADDRESS LATCH
ADDR
R
DIN READ
113
108
103
120
RD-ENABLE DECODER
118
SERIAL DATA

FIG. 3

ADDRESS	DESCRIPTION	A_{15} A_{14} A_{13} A_{12}
ØØ-FF	INTERNAL RAM	
ØØØØ-ØFFF	INTERNAL ROM	Ø Ø Ø Ø
1ØØØ-1FFF	EXTERNAL ROM	Ø Ø Ø 1
2ØØØ-2Ø3F	EXTERNAL SRAM	Ø Ø 1 Ø
4ØØØ-4ØØF	CLOCK	Ø 1 Ø Ø
6ØØØ-6ØØ7	A/D READ	Ø 1 1 Ø
CØØØ	XØØ-XØ7 } DIN	1 1 Ø Ø
CØØ1	X1Ø-X17 } DIN	1 1 Ø Ø
CØØ2	X2Ø-X27 } DIN	1 1 Ø Ø
CØØ3	X3Ø-X37 } DIN	1 1 Ø Ø
EØØØ	YØØ-YØ7 } DOU	1 1 1 Ø
EØØ1	Y1Ø-Y17 } DOU	1 1 1 Ø
EØØ2	Y2Ø Y27 } DOU	1 1 1 Ø
EØØ3	Y3Ø Y37 } DOU	1 1 1 Ø
EØØ4	WATCHDOG - RESET	1 1 1 Ø

FIG. 3A(a)

FIG. 3A(a)	FIG. 3A(b)

FIG. 3A

ADDRESS BUS BITS

	A_{11} A_{10} A_9 A_8	A_7 A_6 A_5 A_4	A_3 A_2 A_1 A_ϕ
	———	A_7 A_6 A_5 A_4	A_3 A_2 A_1 A_ϕ
	A_{11} A_{10} A_9 A_8	A_7 A_6 A_5 A_4	A_3 A_2 A_1 A_ϕ
	A_{11} A_{10} A_9 A_8	A_7 A_6 A_5 A_4	A_3 A_2 A_1 A_ϕ
	ϕ ϕ ϕ ϕ	ϕ ϕ A_5 A_4	A_3 A_2 A_1 A_ϕ
	ϕ ϕ ϕ ϕ	ϕ ϕ ϕ ϕ	A_3 A_2 A_1 A_ϕ
	ϕ ϕ ϕ ϕ	ϕ ϕ ϕ ϕ	ϕ A_2 A_1 A_ϕ
	ϕ ϕ ϕ ϕ	ϕ ϕ ϕ ϕ	ϕ ϕ ϕ ϕ ϕ ϕ ϕ 1 ϕ ϕ 1 ϕ ϕ ϕ 1 1
	ϕ ϕ ϕ ϕ	ϕ ϕ ϕ ϕ	ϕ ϕ ϕ ϕ ϕ ϕ ϕ 1 ϕ ϕ 1 ϕ ϕ ϕ 1 1
	ϕ	ϕ	ϕ 1 ϕ ϕ

FIG. 3A(b)

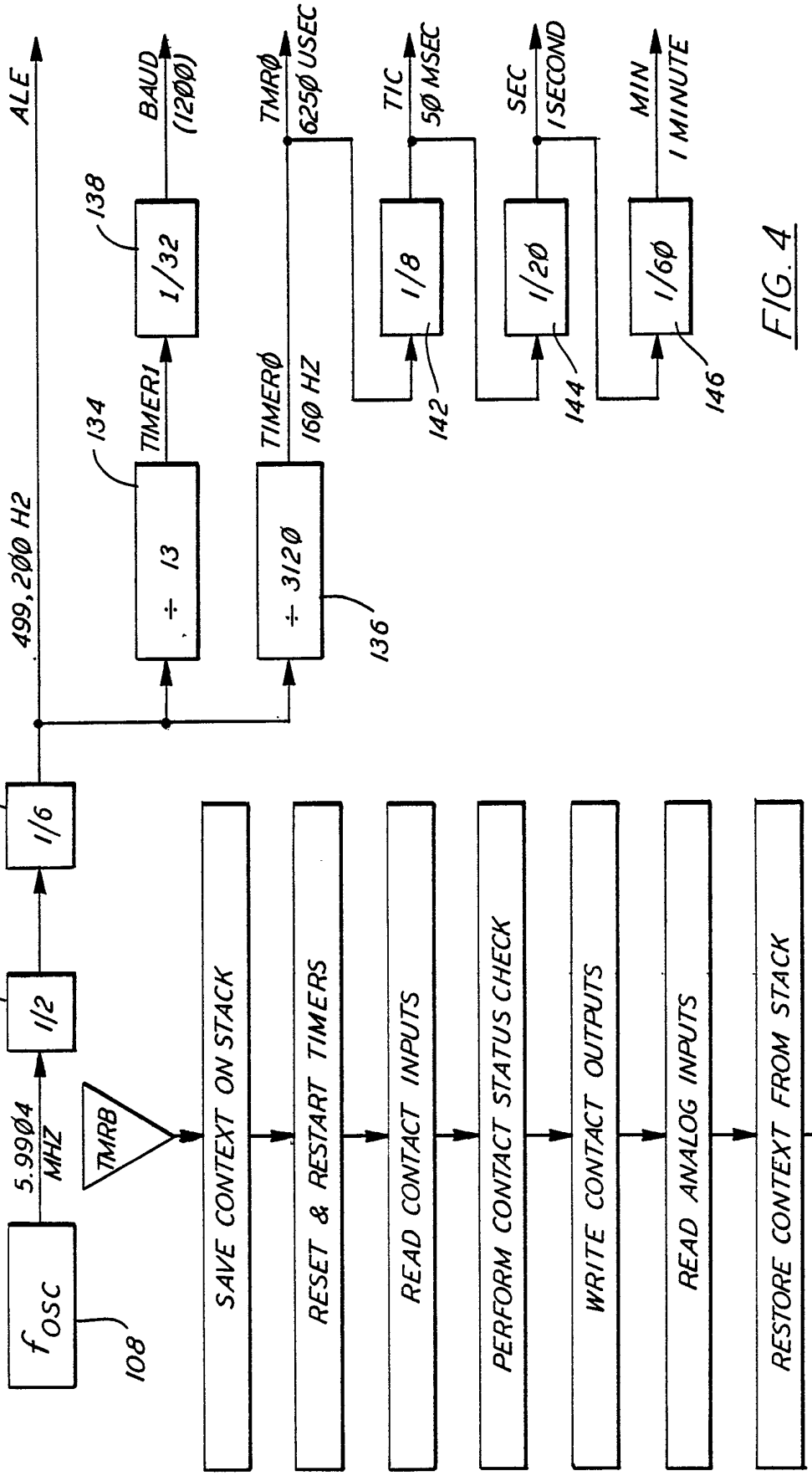

f_{OSC}
108
5.9904 MHZ
1/2
130
1/6
132
499,200 H2
ALE
÷ 13
134
TIMER1
1/32
138
BAUD (1200)
÷ 3120
136
TIMER0
160 HZ
TMR0
625Ø USEC
1/8
142
TIC
5Ø MSEC
1/20
144
SEC
1 SECOND
1/60
146
MIN
1 MINUTE
TMRB
SAVE CONTEXT ON STACK
RESET & RESTART TIMERS
READ CONTACT INPUTS
PERFORM CONTACT STATUS CHECK
WRITE CONTACT OUTPUTS
READ ANALOG INPUTS
RESTORE CONTEXT FROM STACK
RET1

FIG. 4

FIG. 11

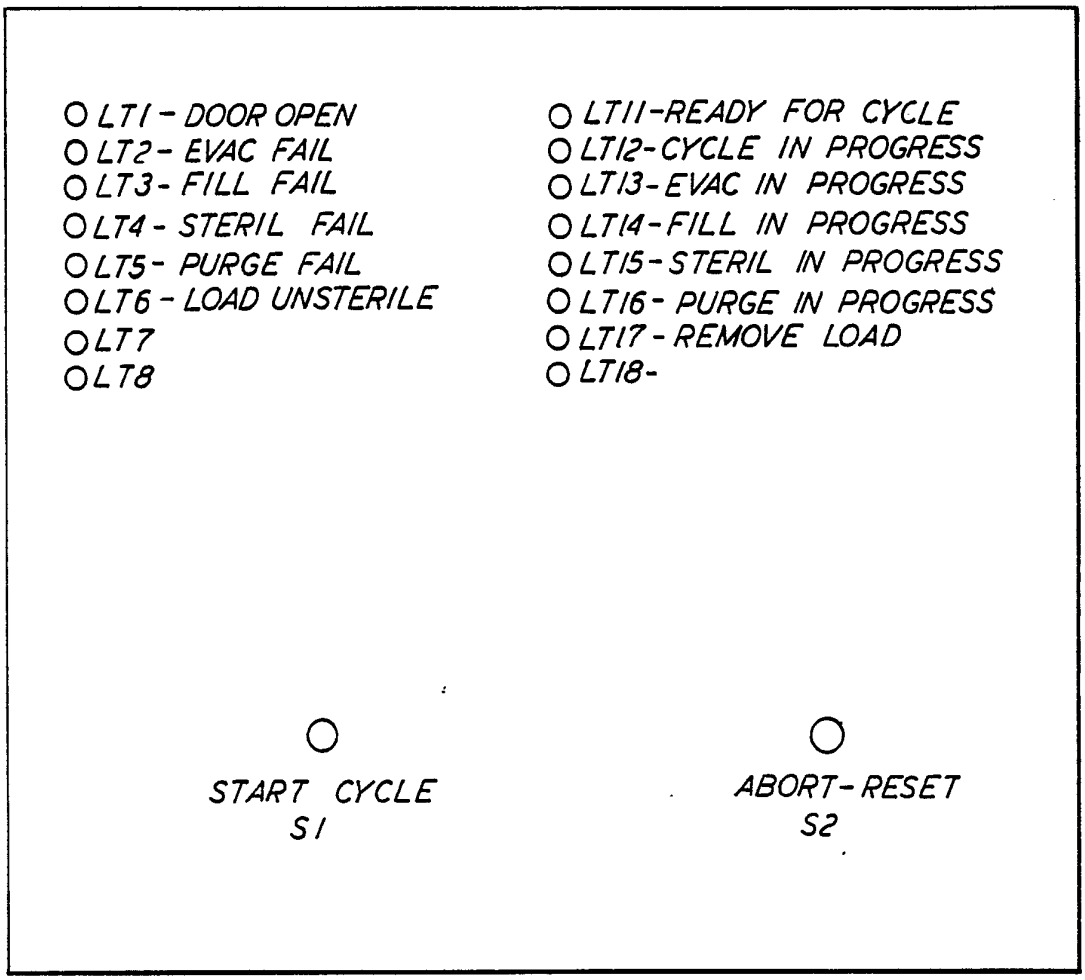

LT1 - DOOR OPEN
LT2 - EVAC FAIL
LT3 - FILL FAIL
LT4 - STERIL FAIL
LT5 - PURGE FAIL
LT6 - LOAD UNSTERILE
LT7
LT8
LT11 - READY FOR CYCLE
LT12 - CYCLE IN PROGRESS
LT13 - EVAC IN PROGRESS
LT14 - FILL IN PROGRESS
LT15 - STERIL IN PROGRESS
LT16 - PURGE IN PROGRESS
LT17 - REMOVE LOAD
LT18 -
START CYCLE
S1
ABORT - RESET
S2

FIG. 5

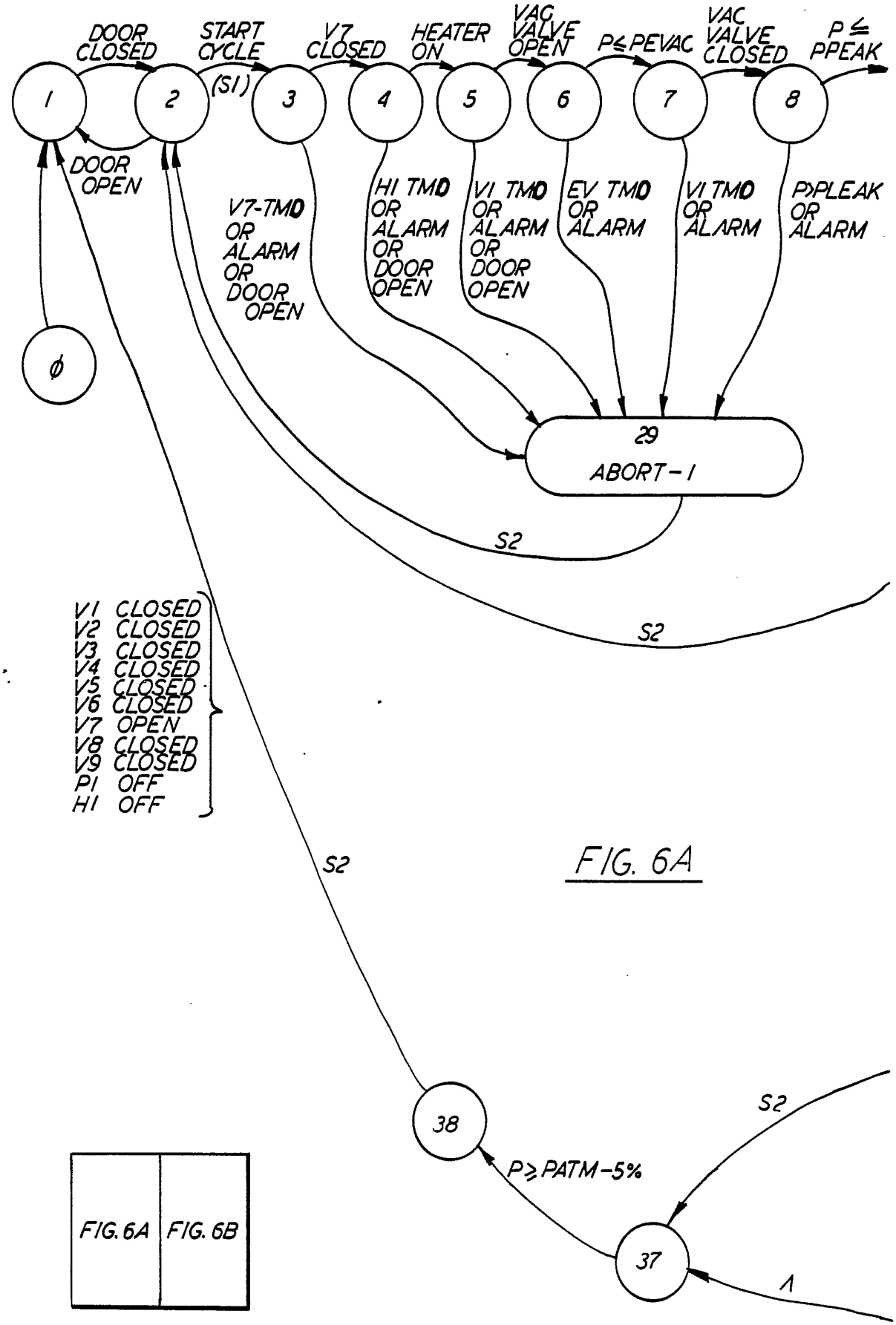

DOOR CLOSED
START CYCLE (S1)
V7 CLOSED
HEATER ON
VAC VALVE OPEN
P≤PEVAC
VAC VALVE CLOSED
P≤ PPEAK
1
2
3
4
5
6
7
8
DOOR OPEN
V7-TMO OR ALARM OR DOOR OPEN
HI TMO OR ALARM OR DOOR OPEN
VI TMO OR ALARM OR DOOR OPEN
EV TMO OR ALARM
VI TMO OR ALARM
P>PLEAK OR ALARM
ϕ
29
ABORT-1
S2
S2
V1 CLOSED
V2 CLOSED
V3 CLOSED
V4 CLOSED
V5 CLOSED
V6 CLOSED
V7 OPEN
V8 CLOSED
V9 CLOSED
PI OFF
HI OFF
S2
38
P≥PATM-5%
S2
37
1

FIG. 6A

FIG. 6A
FIG. 6B

FIG. 6

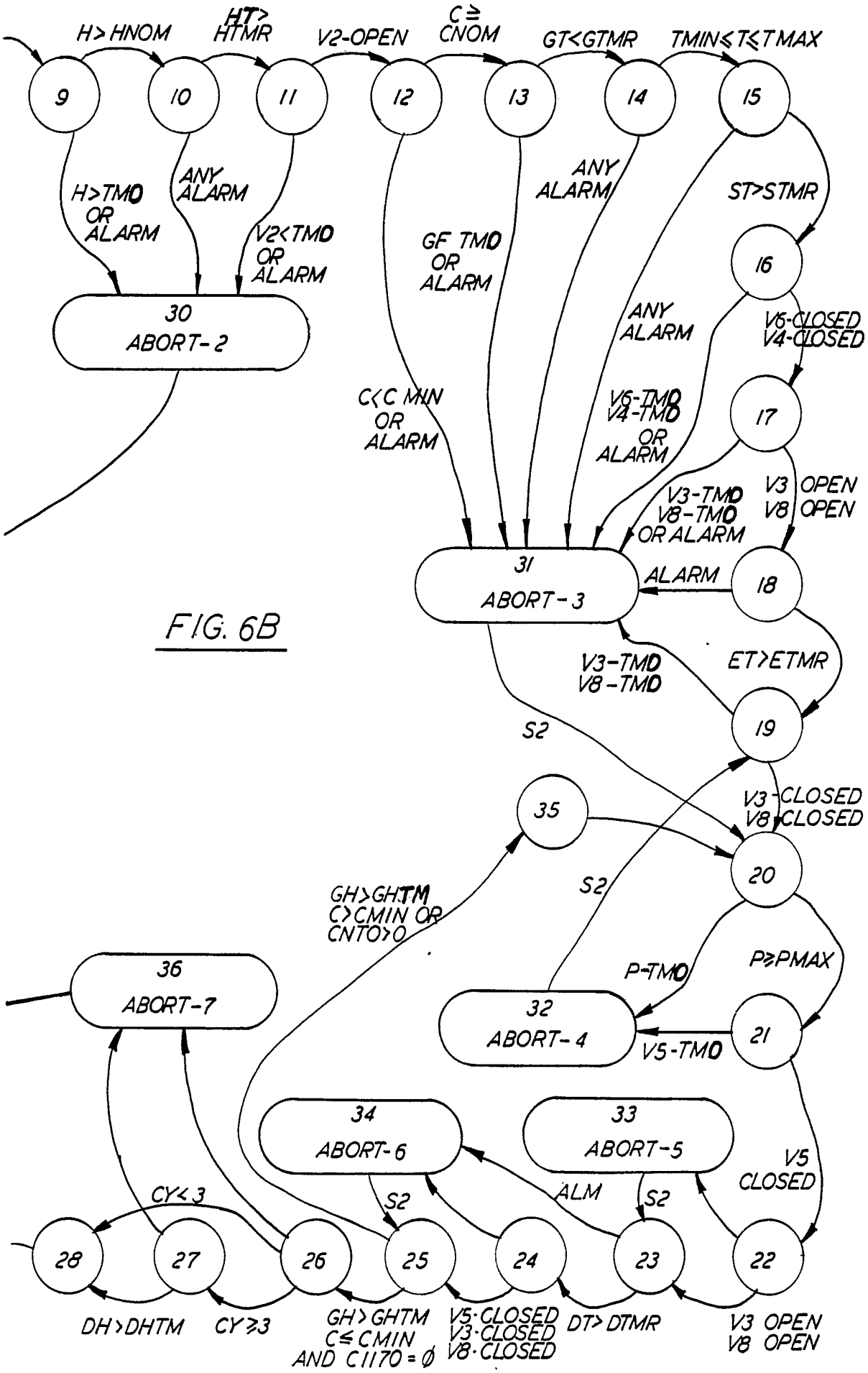

H>HNOM
HT>HTMR
V2-OPEN
C≥CNOM
GT<GTMR
TMIN≤T≤TMAX
9
10
11
12
13
14
15
H>TMO OR ALARM
ANY ALARM
V2<TMO OR ALARM
GF TMO OR ALARM
ANY ALARM
ST>STMR
16
30 ABORT-2
ANY ALARM
V6-CLOSED V4-CLOSED
C<C MIN OR ALARM
V6-TMO V4-TMO OR ALARM
17
V3-TMO V8-TMO OR ALARM
V3 OPEN V8 OPEN
31 ABORT-3
ALARM
18
V3-TMO V8-TMO
ET>ETMR
19
S2
35
V3 CLOSED V8 CLOSED
20
S2
GH>GHTM C>CMIN OR CNTO>0
P-TMO
P≥PMAX
36 ABORT-7
32 ABORT-4
V5-TMO
21
34 ABORT-6
33 ABORT-5
V5 CLOSED
ALM
S2
S2
CY<3
28
27
26
25
24
23
22
DH>DHTM
CY≥3
GH>GHTM C≤CMIN AND C1170=Ø
V5·CLOSED V3·CLOSED V8·CLOSED
DT>DTMR
V3 OPEN V8 OPEN

FIG. 6B

FIG. 7a	FIG. 7b

FIG. 7

			PROCESS 29									30			31							
			0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
DISPLAYS	DOOR OPEN	LTØ1	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	EVAC FAIL	LTØ2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	FILL FAIL	LTØ3 C	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	STERIL FAIL	LTØ4 C	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	PURGE FAIL	LTØ5 O	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	LOAD MASTER	LTØ6 Ø	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
		LTØ7	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
		LTØ8	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	READY	LT11	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	CYCLE	LT12	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
	EVAC	LT13 C	0	0	0	0	0	0	1	1	1	0	0	0	0	0	0	0	0	0	0	0
	FILL	LT14 C	0	0	0	0	0	0	0	0	0	1	1	1	0	0	0	0	0	0	0	0
	STERIL	LT15 O	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	0	0	0
	PURGE	LT16 1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1
	ROM LOAD	LT17	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
		LT18	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
VALVES	MAIN VAC	VVØ1	0	0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0
	GAS ENABLE	VVØ2	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1	1
	VAC CTRL	VVØ3 C	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	0
	GAS CTRL	VVØ4 C	0	0	0	0	0	0	0	0	0	0	0	0	C	C	C	C	0	0	0	0
	N2 CTRL	VVØ5 O	0	0	0	0	0	0	0	0	0	0	0	C	C	C	C	C	0	0	0	0
	H_2O CTRL	VVØ6 2	0	0	0	0	0	0	0	0	0	C	C	C	C	C	C	C	0	0	0	0
	ATM VENT	VVØ7	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	VAC VLV.	VVØ8	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1	0
	VAC PUMP	PPO1 C	0	0	0	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1
	HEATER	HTO1 C O	0	0	0	0	1	C	C	C	C	C	C	C	C	C	C	C	C	C	C	C
	GAIN CHG.	GC1 3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

FIG. 7a

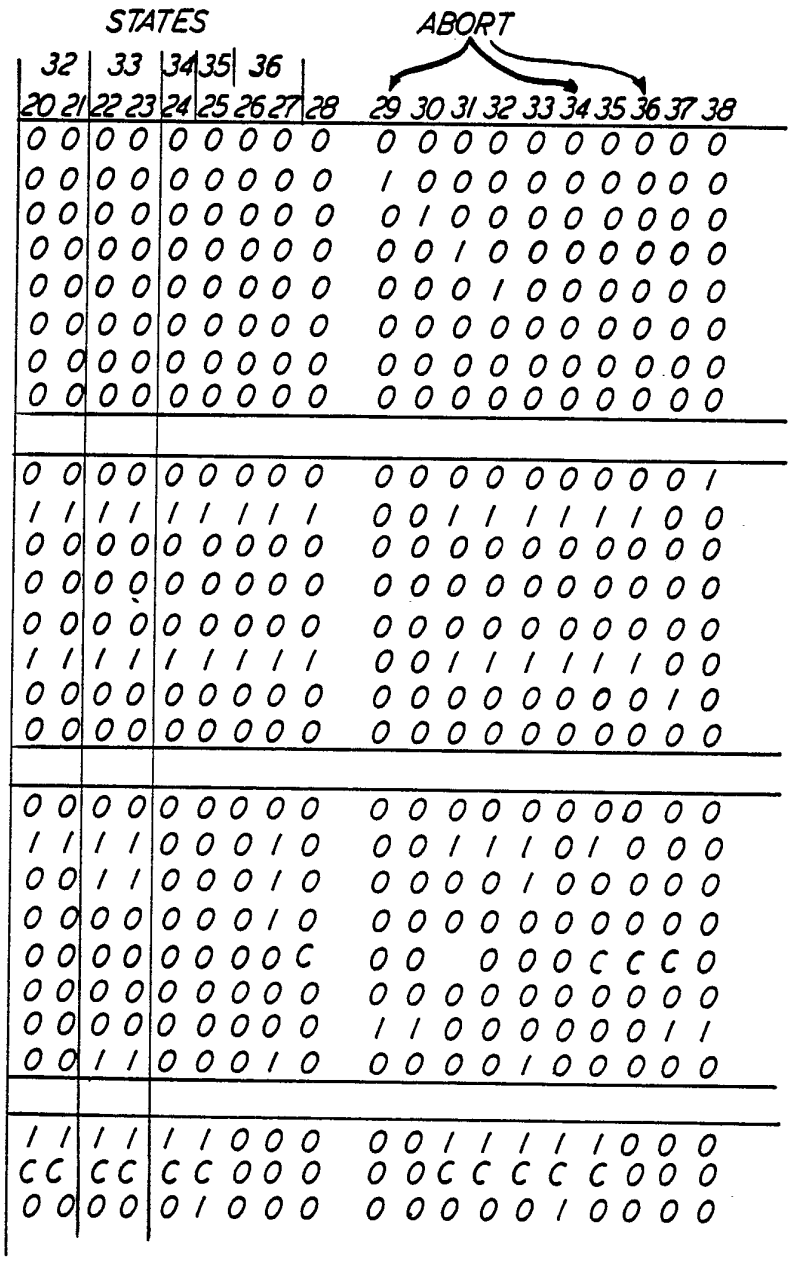

STATES
ABORT
32
33
34
35
36
20 21 22 23 24 25 26 27 28
29 30 31 32 33 34 35 36 37 38

FIG. 7b

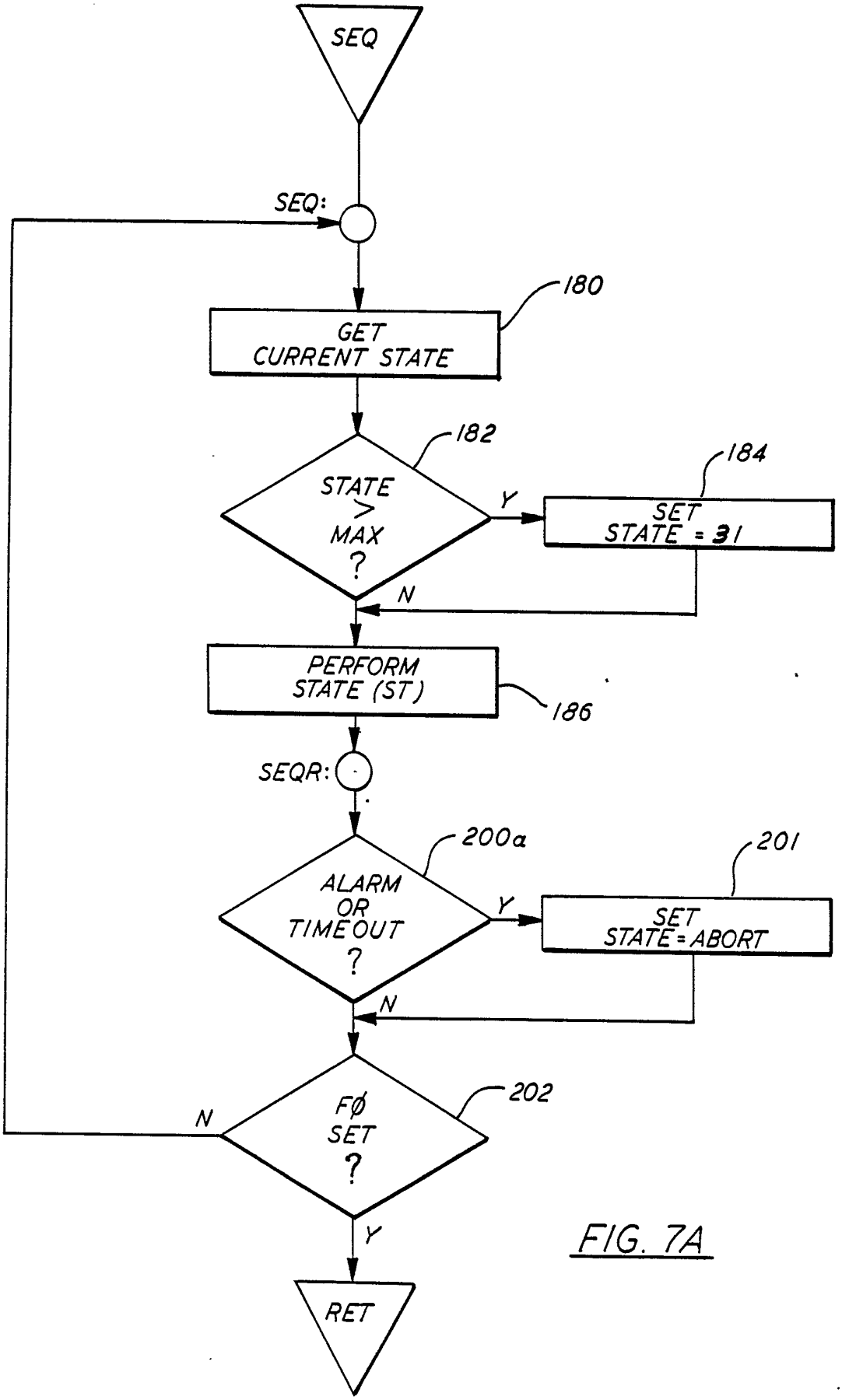

SEQ
SEQ:
180
GET
CURRENT STATE
182
STATE
>
MAX
?
Y
184
SET
STATE = 31
N
PERFORM
STATE (ST)
186
SEQR:
200a
ALARM
OR
TIME OUT
?
Y
201
SET
STATE = ABORT
N
FØ
SET
?
202
N
Y
RET

FIG. 7A

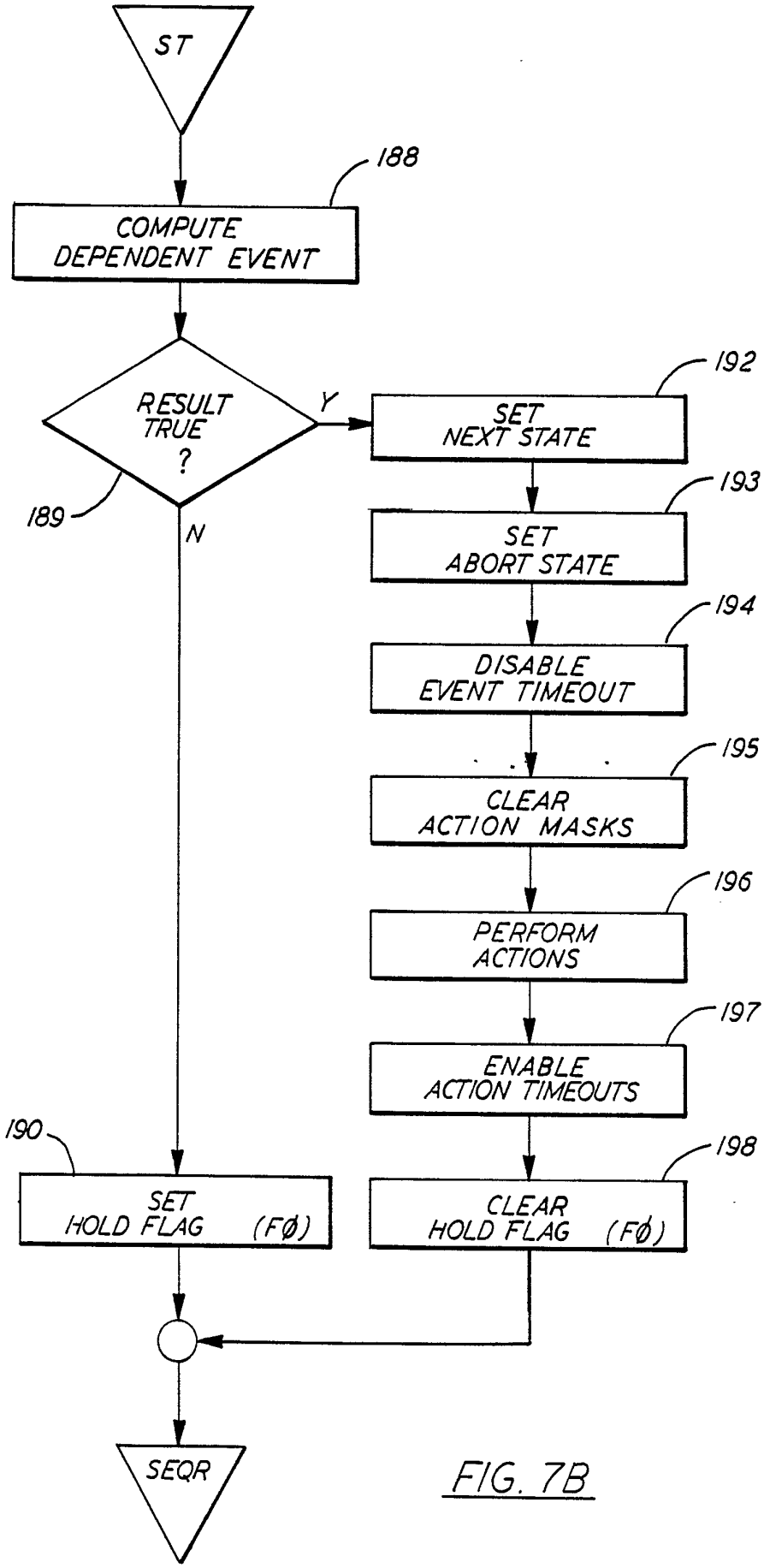

ST
188
COMPUTE DEPENDENT EVENT
RESULT TRUE ?
Y
N
189
192
SET NEXT STATE
193
SET ABORT STATE
194
DISABLE EVENT TIMEOUT
195
CLEAR ACTION MASKS
196
PERFORM ACTIONS
197
ENABLE ACTION TIMEOUTS
198
CLEAR HOLD FLAG (FØ)
190
SET HOLD FLAG (FØ)
SEQR

FIG. 7B

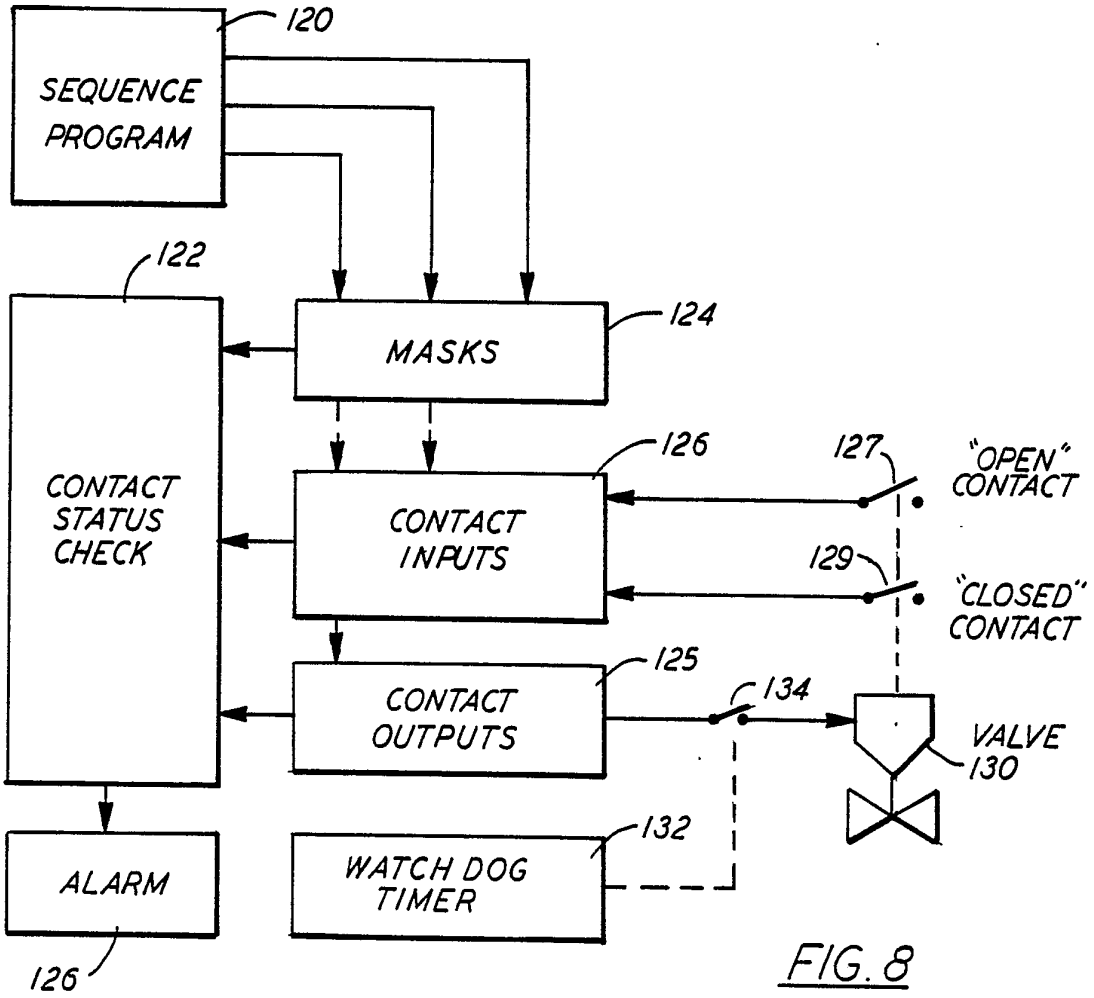

120
SEQUENCE PROGRAM
122
CONTACT STATUS CHECK
MASKS
124
126
CONTACT INPUTS
127
"OPEN" CONTACT
129
"CLOSED" CONTACT
125
CONTACT OUTPUTS
134
VALVE 130
ALARM
126
132
WATCH DOG TIMER

FIG. 8

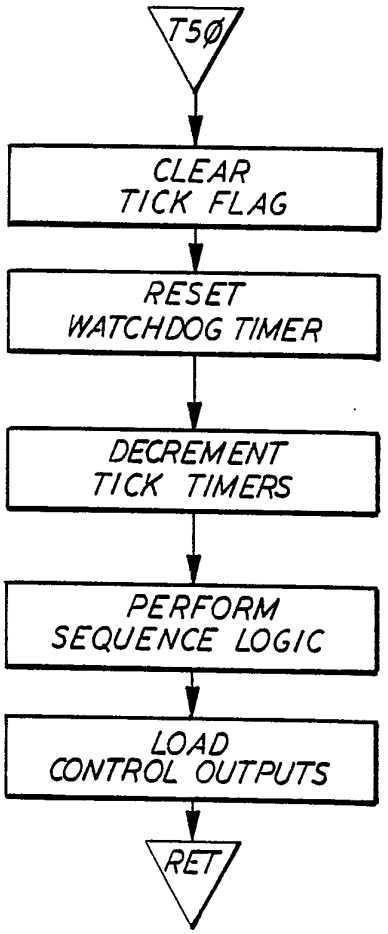

T5Ø
CLEAR TICK FLAG
RESET WATCHDOG TIMER
DECREMENT TICK TIMERS
PERFORM SEQUENCE LOGIC
LOAD CONTROL OUTPUTS
RET

FIG. 13

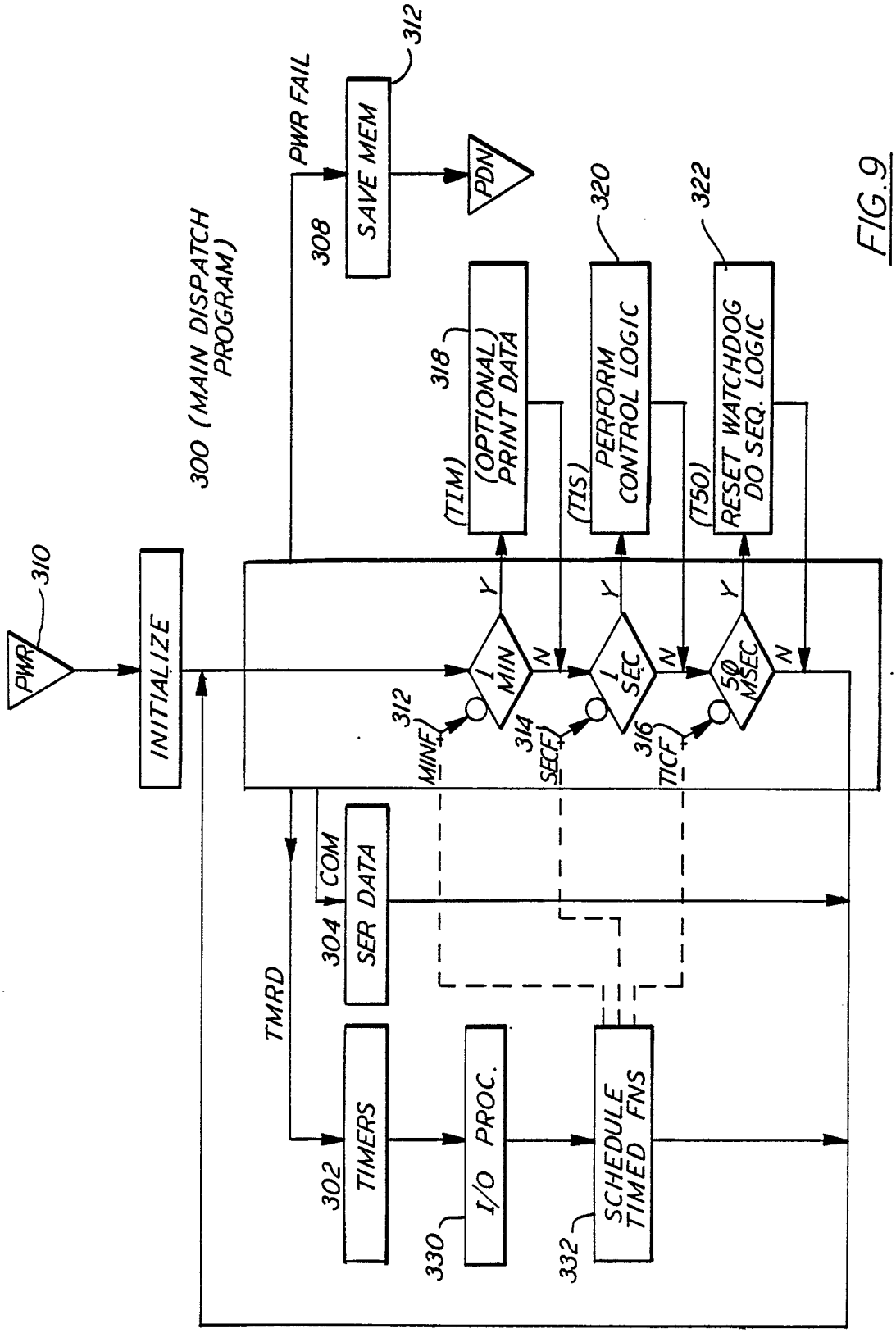
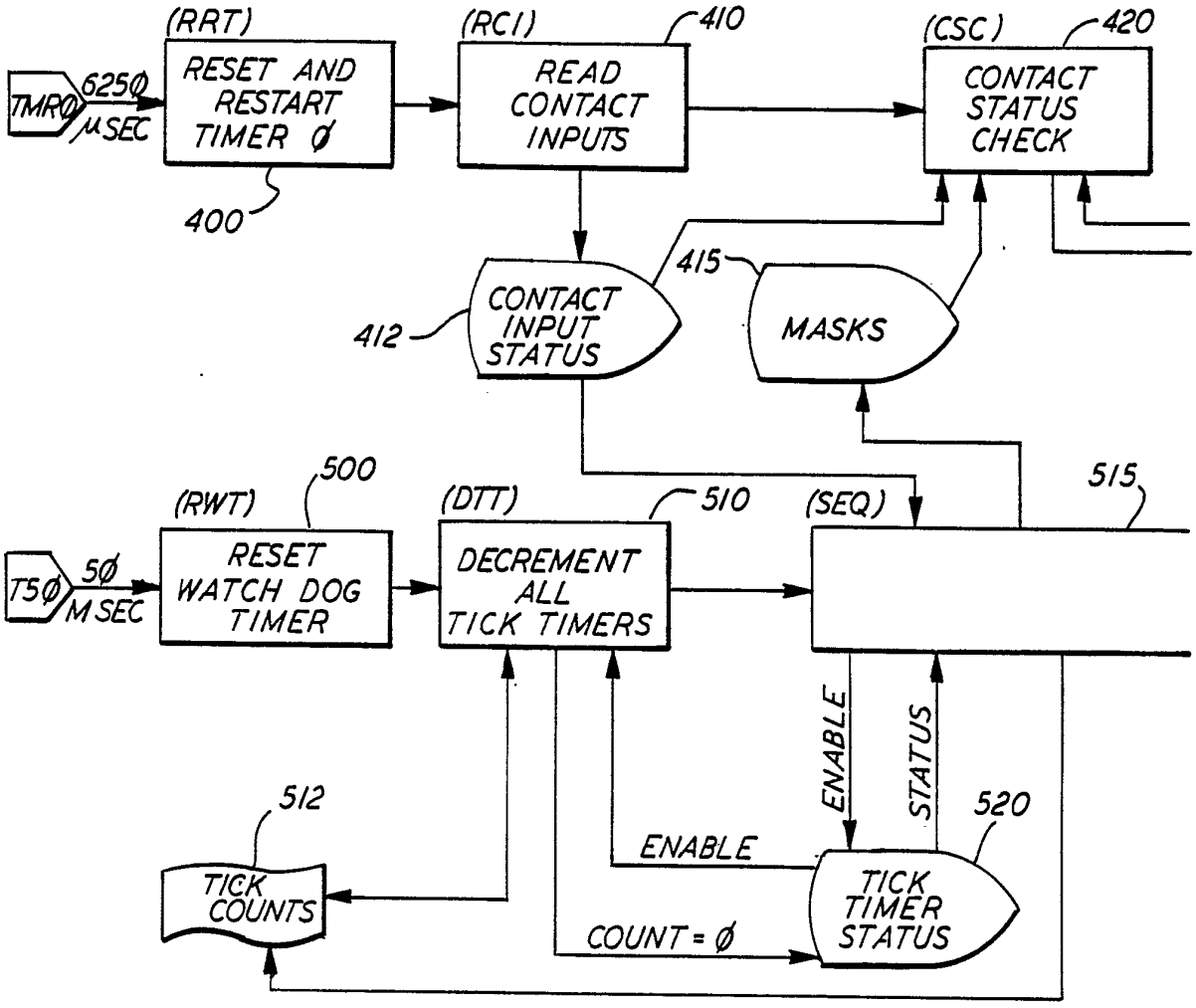

PWR
310
INITIALIZE
300 (MAIN DISPATCH PROGRAM)
PWR FAIL
SAVE MEM
308
312
PDN
(TIM)
(OPTIONAL) PRINT DATA
318
(TIS)
PERFORM CONTROL LOGIC
320
(T50)
RESET WATCHDOG DO SEQ. LOGIC
322
1 MIN
1 SEC
50 MSEC
Y
N
MINF
SECF
TICF
312
314
316
COM
SER DATA
304
TMRD
TIMERS
302
I/O PROC.
330
SCHEDULE TIMED FNS
332

FIG. 9


(RRT)
RESET AND RESTART TIMER Ø
400
TMRØ
625Ø μSEC
(RCI)
READ CONTACT INPUTS
410
(CSC)
CONTACT STATUS CHECK
420
CONTACT INPUT STATUS
412
MASKS
415
(RWT)
RESET WATCH DOG TIMER
500
T5Ø
5Ø MSEC
(DTT)
DECREMENT ALL TICK TIMERS
510
(SEQ)
515
ENABLE
STATUS
520
TICK COUNTS
512
ENABLE
COUNT = Ø
TICK TIMER STATUS

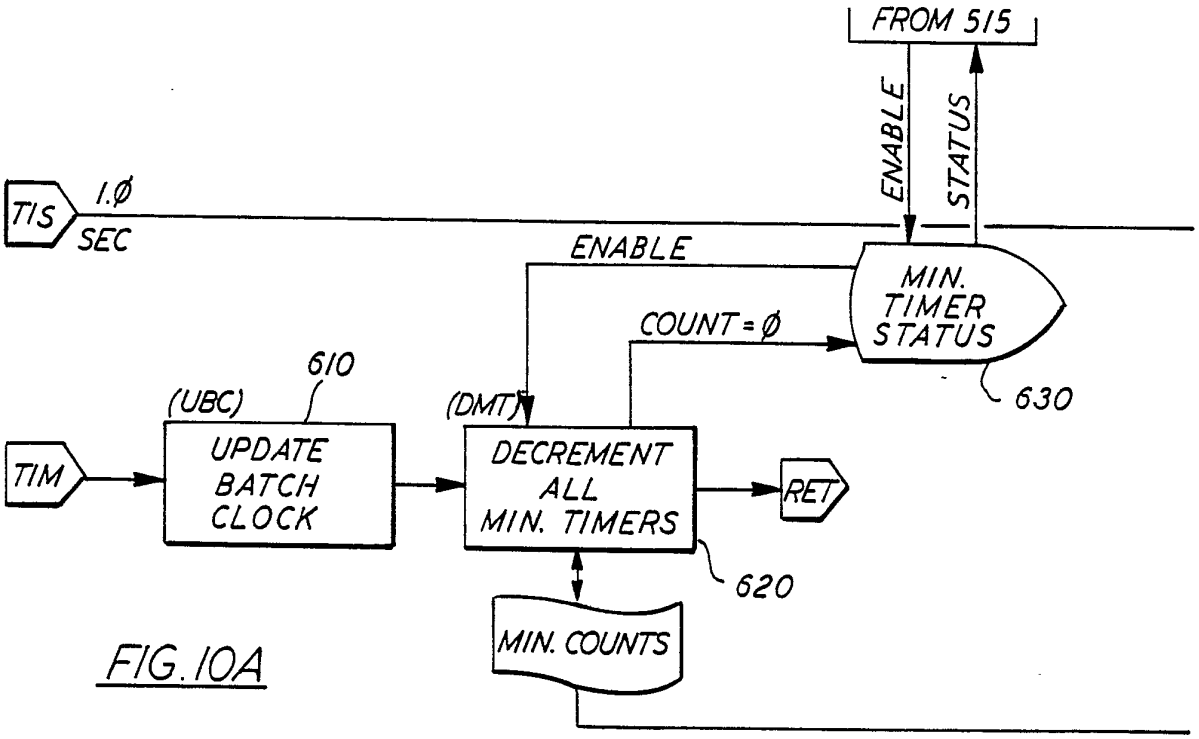

FROM 515
ENABLE
STATUS
TIS
1.Ø SEC
ENABLE
COUNT = Ø
MIN. TIMER STATUS
630
610
(UBC)
UPDATE BATCH CLOCK
(DMT)
DECREMENT ALL MIN. TIMERS
620
TIM
RET
MIN. COUNTS

FIG. 10A

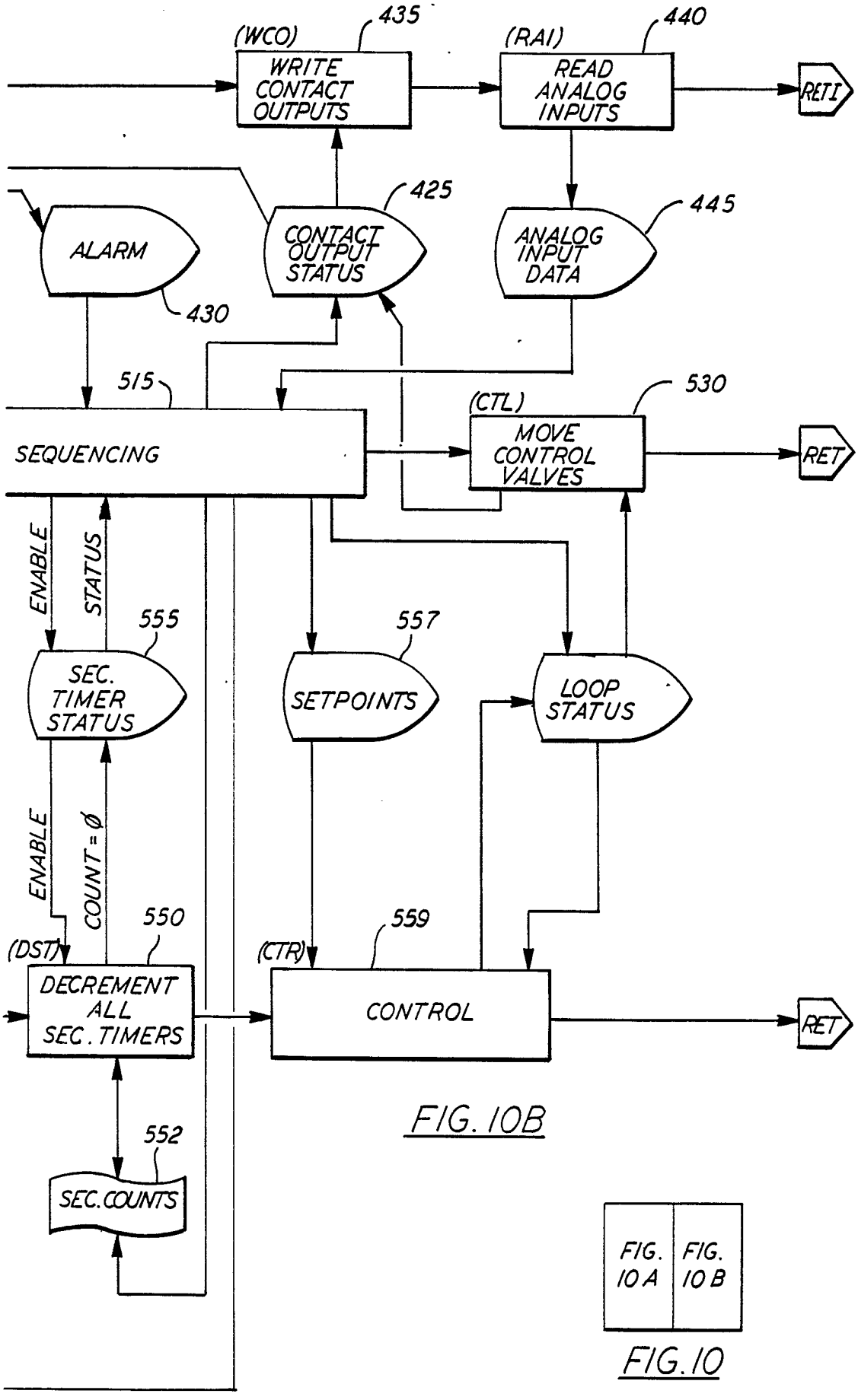


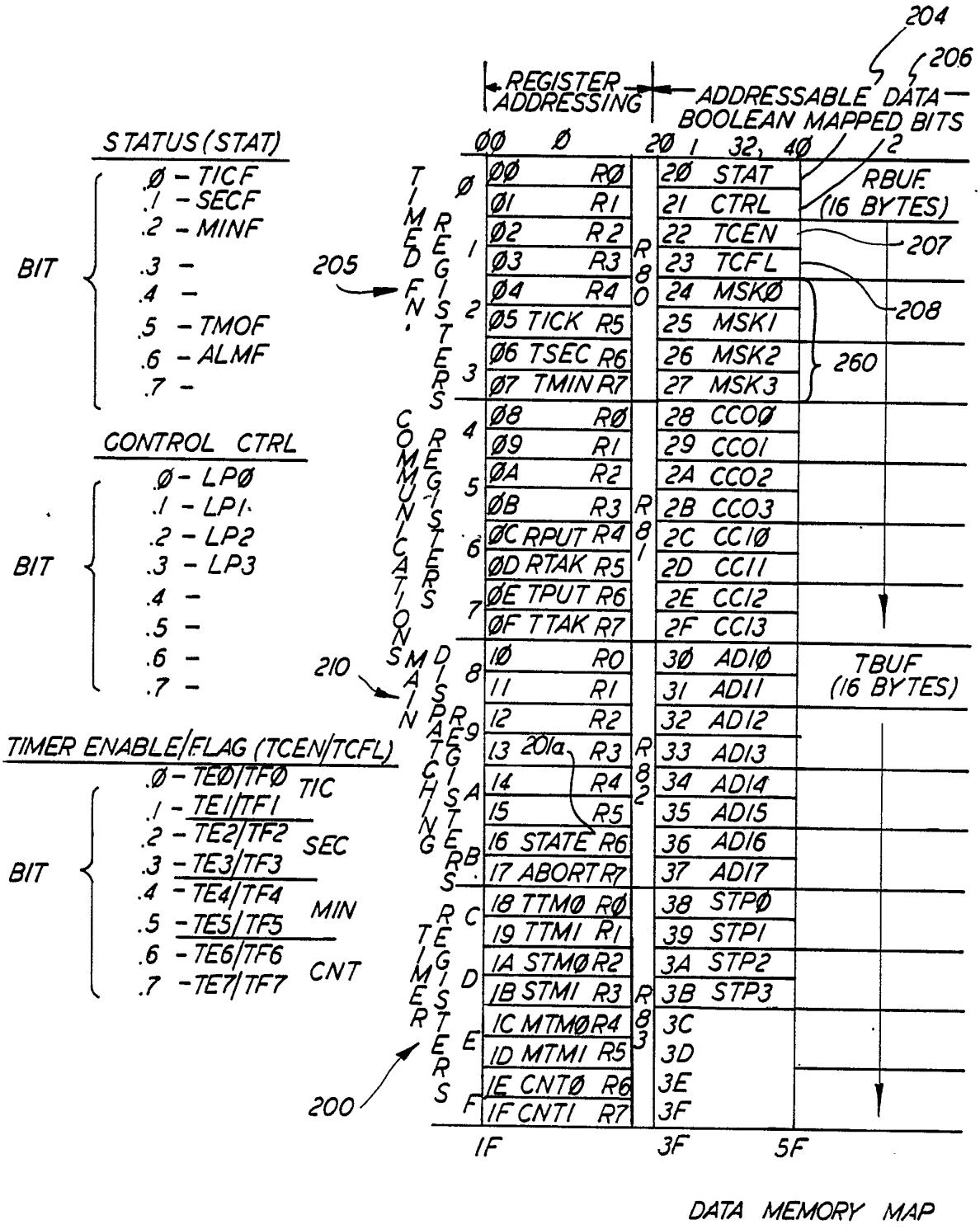
FIG. 10B

FIG. 10 A	FIG. 10 B

FIG. 10

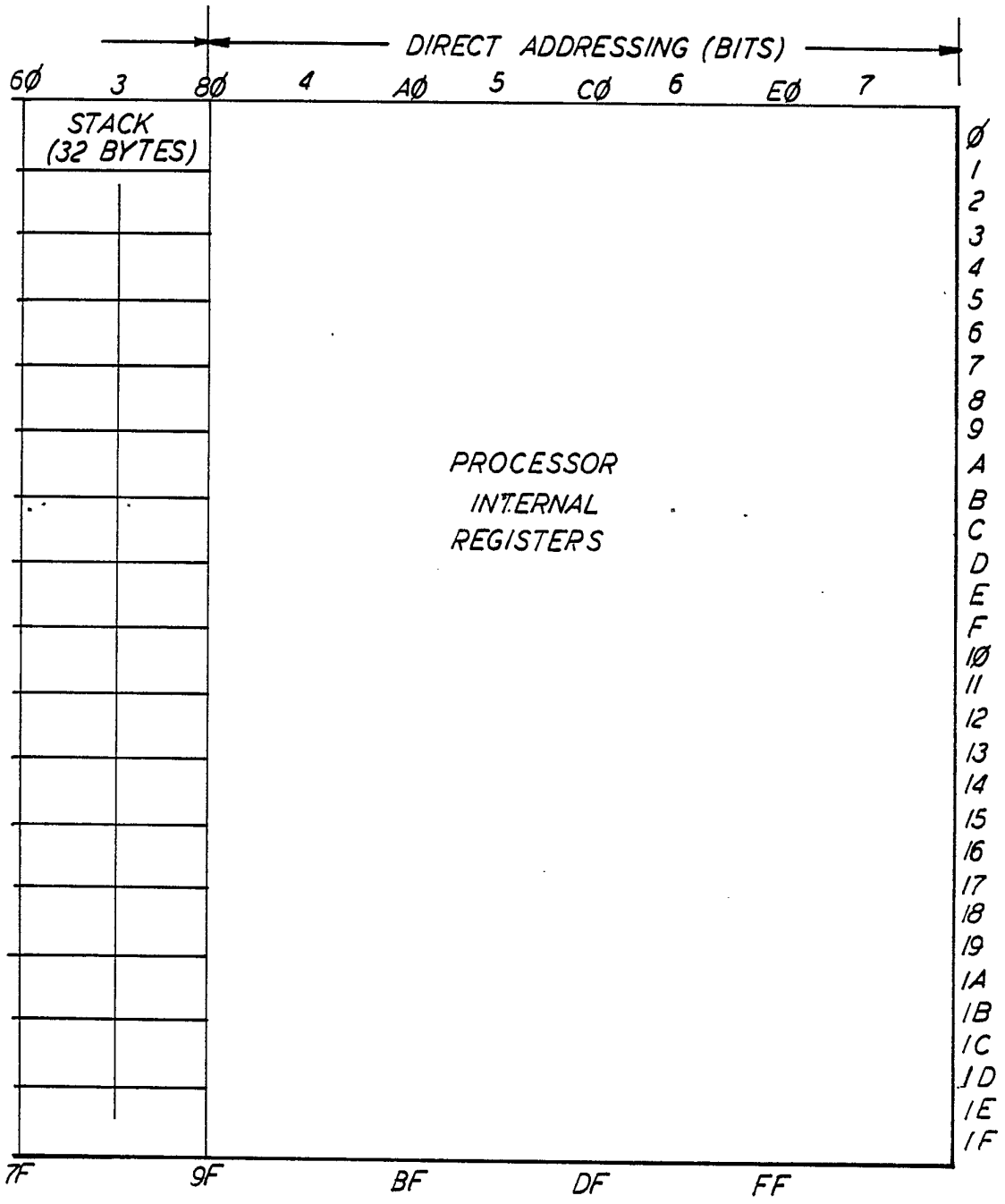
FIG.12A | FIG.12B

FIG. 12



DATA MEMORY MAP

FIG. 12A



DATA MEMORY MAP

FIG. 12B

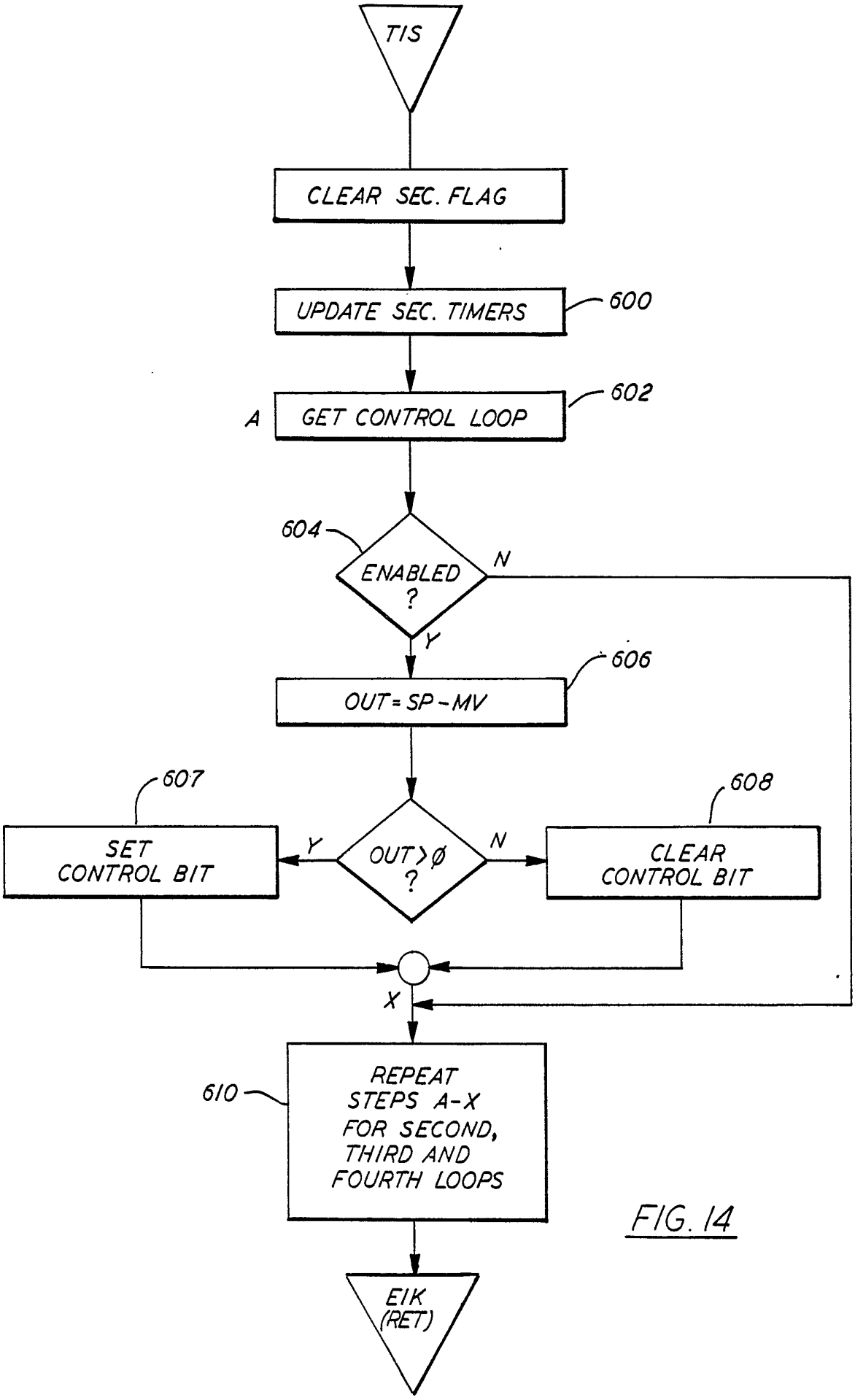

TIS
CLEAR SEC. FLAG
UPDATE SEC. TIMERS
600
A
GET CONTROL LOOP
602
604
ENABLED ?
N
Y
606
OUT = SP - MV
607
SET CONTROL BIT
Y
OUT > Ø ?
N
608
CLEAR CONTROL BIT
X
610
REPEAT STEPS A-X FOR SECOND, THIRD AND FOURTH LOOPS
EIK (RET)

FIG. 14

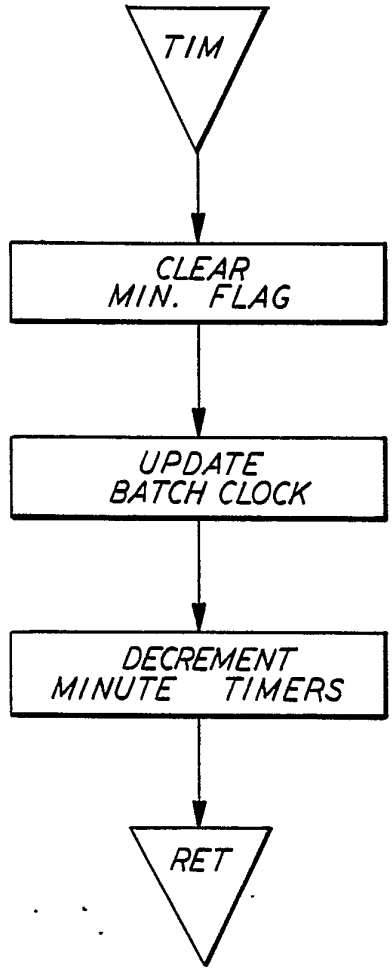

TIM
CLEAR MIN. FLAG
UPDATE BATCH CLOCK
DECREMENT MINUTE TIMERS
RET

FIG. 15

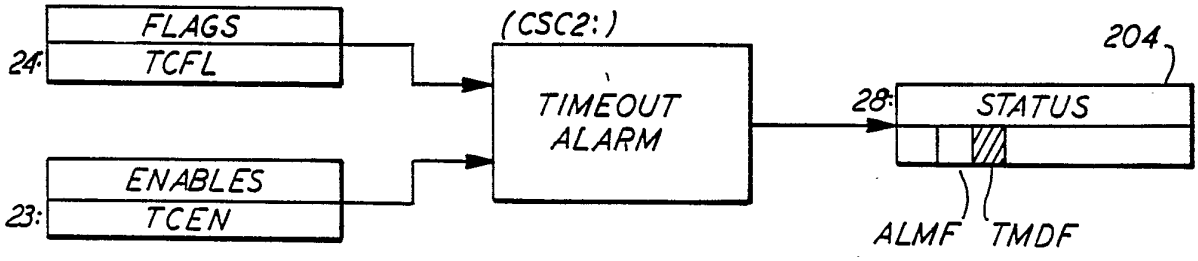

FLAGS
24: TCFL
ENABLES
23: TCEN
(CSC2:)
TIMEOUT ALARM
204
28: STATUS
ALMF
TMDF

FIG. 18

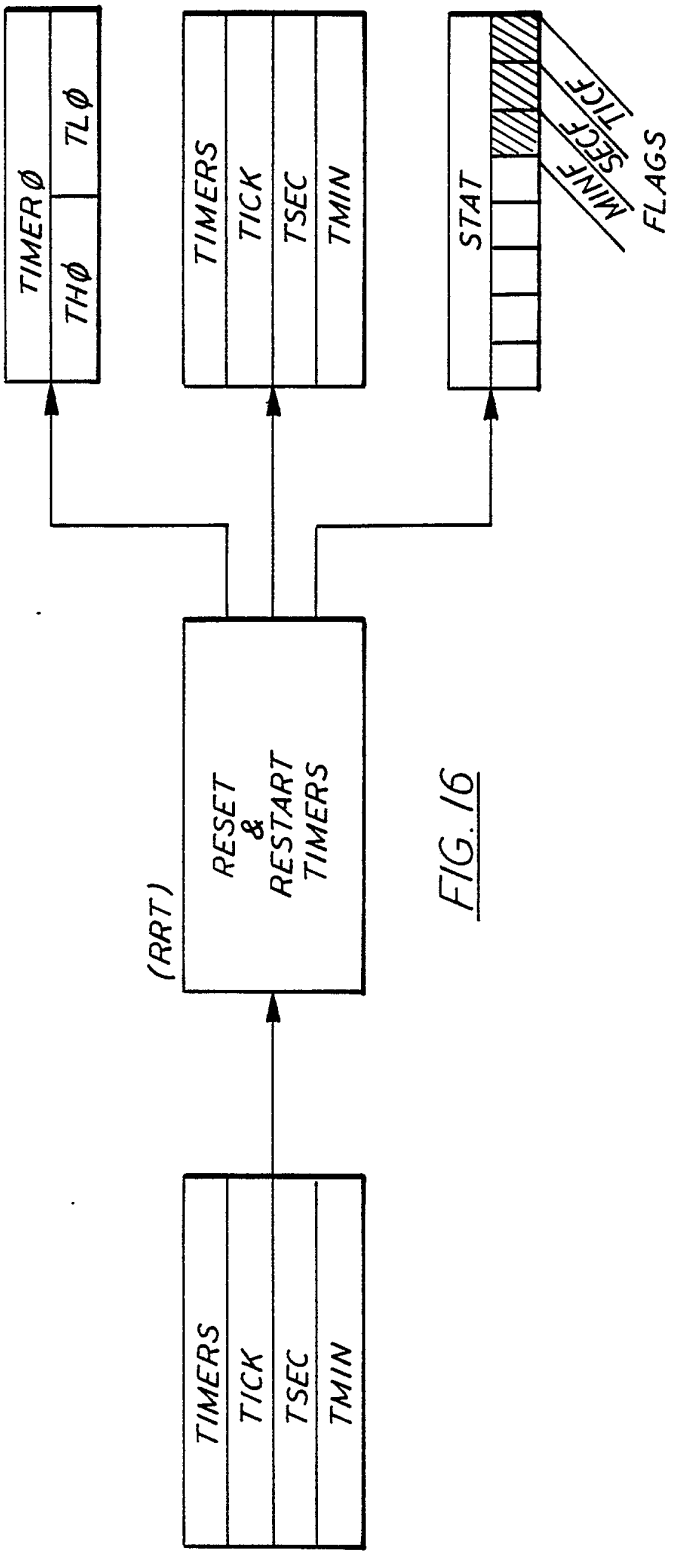

TIMER Ø
TH Ø
TL Ø
TIMERS
TICK
TSEC
TMIN
STAT
MIN SEC TICF
FLAGS
(RRT)
RESET & RESTART TIMERS
TIMERS
TICK
TSEC
TMIN

FIG. 16

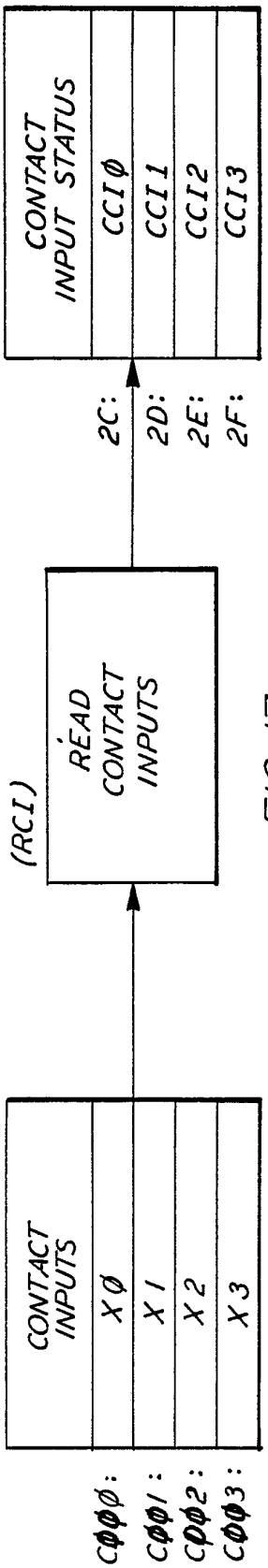

CONTACT INPUT STATUS
CCI Ø
CCI 1
CCI2
CCI3
2C:
2D:
2E:
2F:
(RCI)
READ CONTACT INPUTS
CONTACT INPUTS
X Ø
X 1
X 2
X 3
CØØ:
CØ1:
CØ2:
CØ3:

FIG. 17

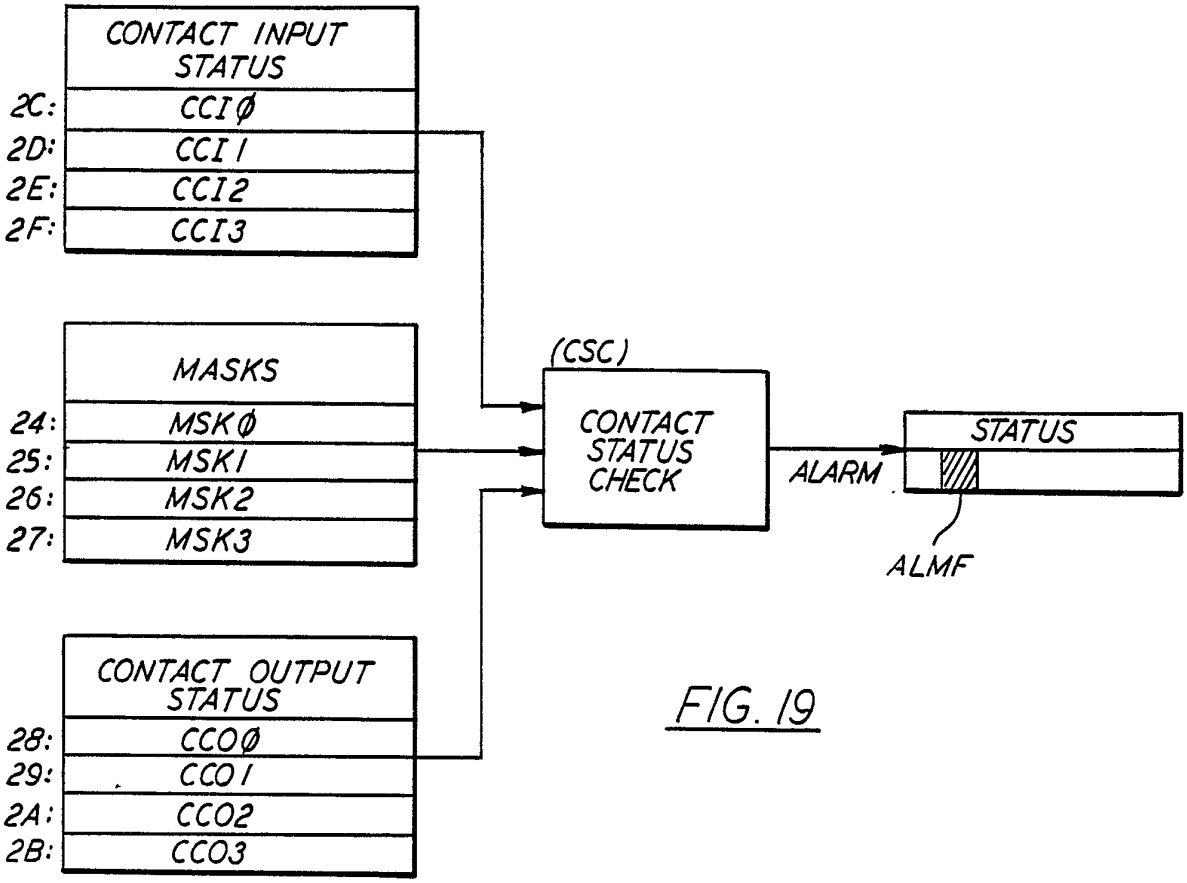

CONTACT INPUT STATUS
2C: CCIØ
2D: CCI1
2E: CCI2
2F: CCI3
MASKS
24: MSKØ
25: MSK1
26: MSK2
27: MSK3
CONTACT OUTPUT STATUS
28: CCOØ
29: CCO1
2A: CCO2
2B: CCO3
(CSC)
CONTACT STATUS CHECK
ALARM
STATUS
ALMF

FIG. 19

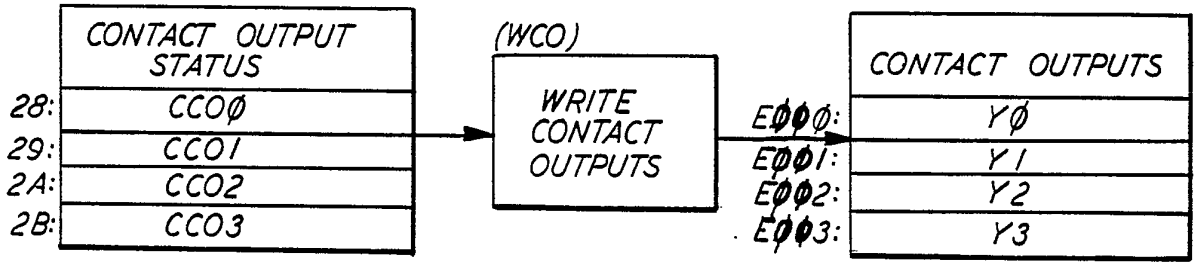

CONTACT OUTPUT STATUS
28: CCOØ
29: CCO1
2A: CCO2
2B: CCO3
(WCO)
WRITE CONTACT OUTPUTS
EØØØ: YØ
EØØ1: Y1
EØØ2: Y2
EØØ3: Y3
CONTACT OUTPUTS

FIG. 20

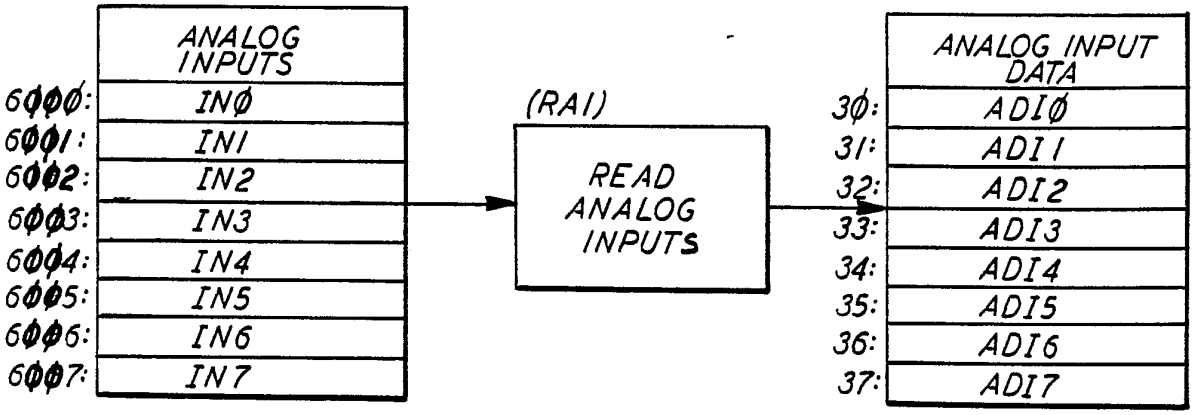

ANALOG INPUTS
6ØØØ: INØ
6ØØ1: IN1
6ØØ2: IN2
6ØØ3: IN3
6ØØ4: IN4
6ØØ5: IN5
6ØØ6: IN6
6ØØ7: IN7
(RAI)
READ ANALOG INPUTS
ANALOG INPUT DATA
3Ø: ADIØ
31: ADI1
32: ADI2
33: ADI3
34: ADI4
35: ADI5
36: ADI6
37: ADI7

FIG. 21

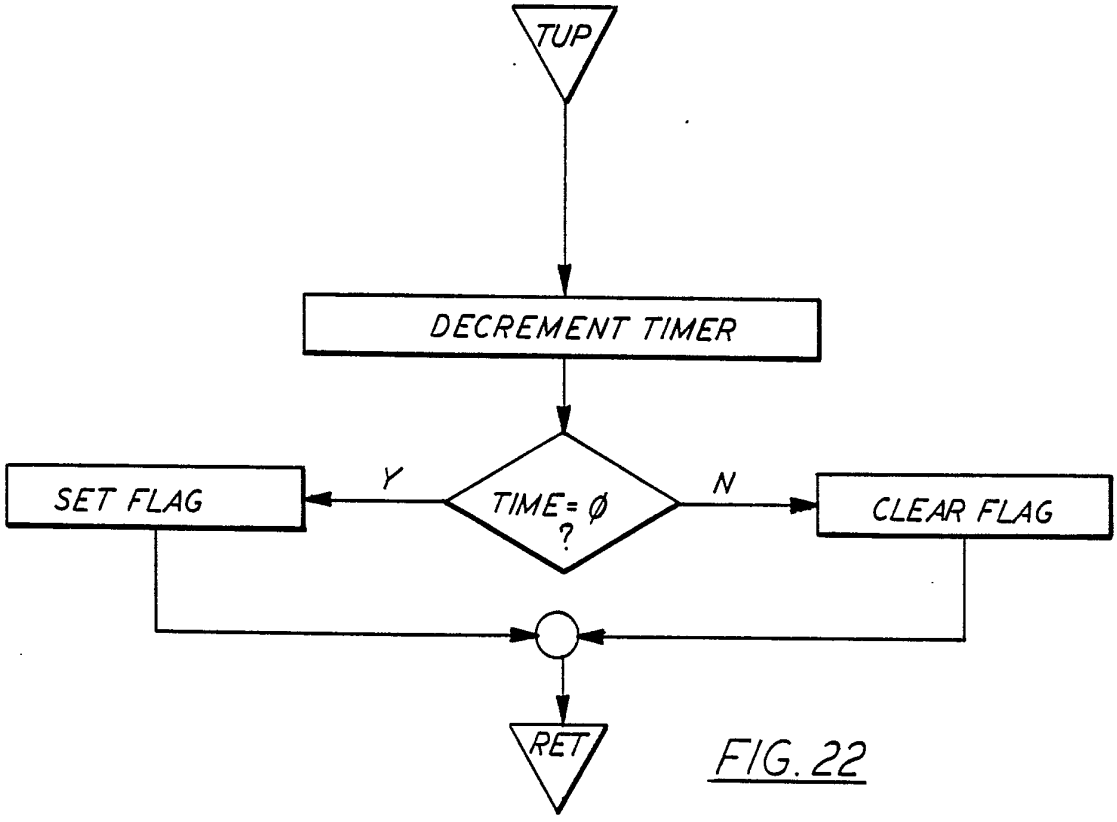

TUP
DECREMENT TIMER
TIME = Ø ?
Y
N
SET FLAG
CLEAR FLAG
RET

FIG. 22

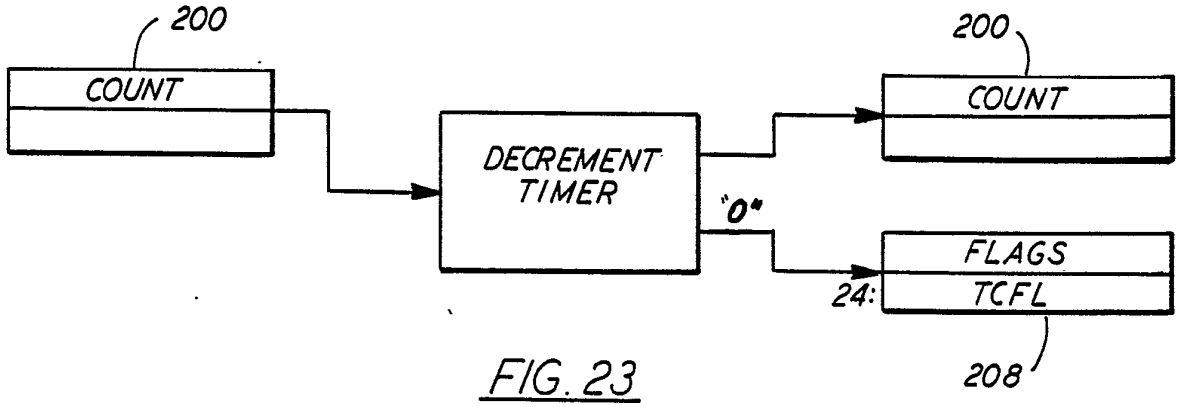

200
COUNT
DECREMENT TIMER
"0"
200
COUNT
FLAGS
24: TCFL
208

FIG. 23

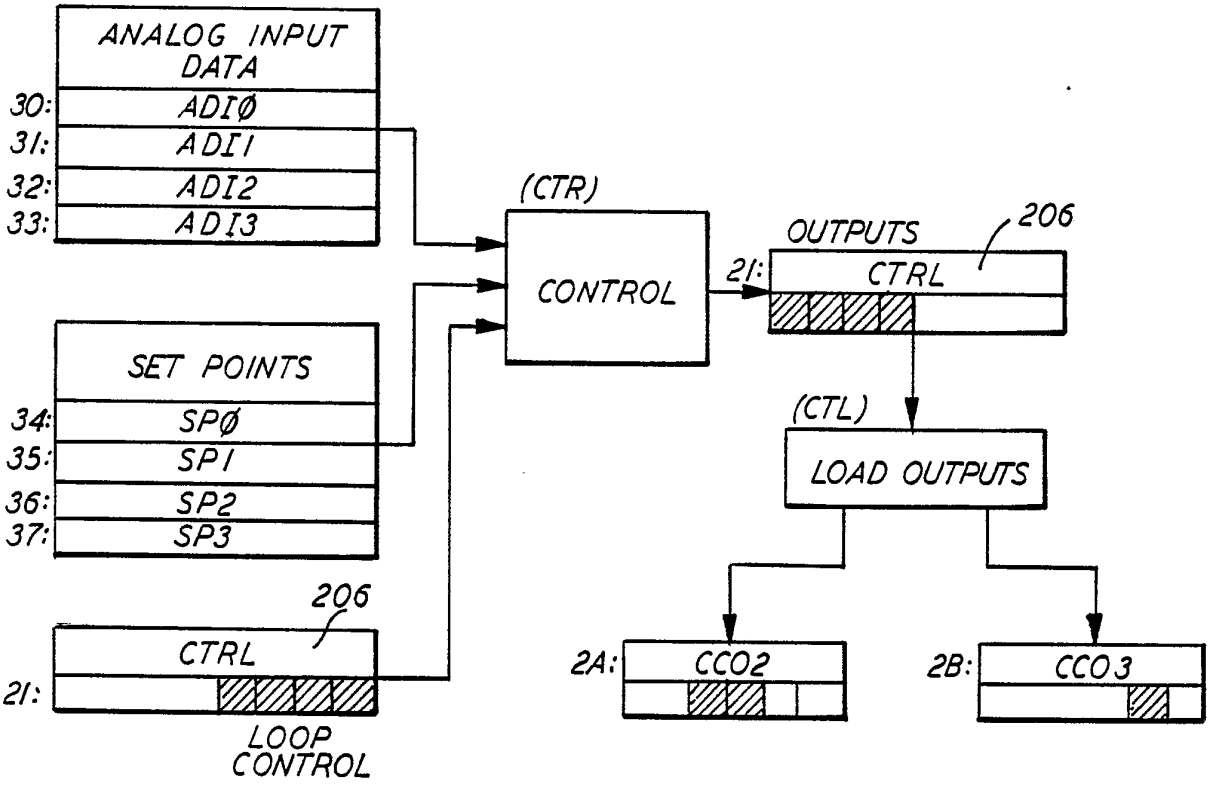

ANALOG INPUT DATA
30: ADIØ
31: ADI1
32: ADI2
33: ADI3
SET POINTS
34: SPØ
35: SP1
36: SP2
37: SP3
206
CTRL
21:
LOOP CONTROL
(CTR)
CONTROL
OUTPUTS
206
21: CTRL
(CTL)
LOAD OUTPUTS
2A: CCO2
2B: CCO3

FIG. 24

INTERNATIONAL SEARCH REPORT

International Application No PCT/US86/00258

I. CLASSIFICATION OF SUBJECT MATTER (if several classification symbols apply, indicate all) [3]

According to International Patent Classification (IPC) or to both National Classification and IPC

IPC (4): G05D 7/06
U.S. Cl. 422/111

II. FIELDS SEARCHED

Minimum Documentation Searched [4]

Classification System	Classification Symbols
U.S.	422/3, 27, 28, 29, 34, 37, 110, 111, 114, 116, 295, 305; 364/413, 499, 500

Documentation Searched other than Minimum Documentation to the Extent that such Documents are Included in the Fields Searched [5]

III. DOCUMENTS CONSIDERED TO BE RELEVANT [14]

Category *	Citation of Document, [16] with indication, where appropriate, of the relevant passages [17]	Relevant to Claim No. [18]
X / Y	US, A, 4,067,691, (McGady et al), 10 January 1978, See the entire document.	1, 2, 14 / 3-13, 15-55
Y,P	US, A, 4,504,442, (Rosenblatt et al.), 12 March 1985, See column 3, lines 27-47; column 4, lines 55-60; and column 5, lines 5-46.	3-10, 19-38, 41-48
Y	US, A, 3,982,893, (Joslyn), 28 September 1976, See column 2, lines 35-38 and 57-69 and column 3, lines 1-13.	7, 21-26 41-45, 47
Y	US, A, 4,431,159, (Stubbs), 14 February 1984, See column 4, lines 4-7.	11-13, 15-17 30-32, 34-36 39-55
Y	US, A, 4,404,651, (Grudowski), 13 September 1983, See column 2, lines 36-60 and column 3, lines 32-36.	12, 13, 15, 31, 32, 34, 39-55
Y	US, A, 3,910,761, (Hopkins), 07 October 1975, See column 10, lines 1-5.	18, 38, 55

* Special categories of cited documents: [15]

"A" document defining the general state of the art which is not considered to be of particular relevance

"E" earlier document but published on or after the international filing date

"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)

"O" document referring to an oral disclosure, use, exhibition or other means

"P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step

"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.

"&" document member of the same patent family

IV. CERTIFICATION

Date of the Actual Completion of the International Search [2]	Date of Mailing of this International Search Report [2]
22 April 1986	06 MAY 1986
International Searching Authority [1]	**Signature of Authorized Officer [20]**
ISA/US	Brion P. Heaney

Form PCT/ISA/210 (second sheet) (October 1981)

III. DOCUMENTS CONSIDERED TO BE RELEVANT (CONTINUED FROM THE SECOND SHEET)

Category *	Citation of Document, [16] with indication, where appropriate, of the relevant passages [17]	Relevant to Claim No [18]
A	GB, A, 2,052,800, (Cook et al.), 28 January 1981, See entire document.	1-55
A	US, A, 4,164,538, (Young et al.), 14 August 1979, See entire document.	1-55
A	US, A, 4,239,731, (Gillis et al.), 16 December 1980, See entire document.	1-55
A	US, A, 4,261,950, (Bainbridge et al.), 14 April 1981, See entire document.	1-55
A	US, A, 4,294,804, (Baran), 13 October 1981, See entire document.	1-55
A	US, A, 4,372,916, (Chamberlain et al.), 08 February 1983, See entire document.	1-55
A	US, A, 4,447,399, (Runnells et al.), 08 May 1984, See entire document.	1-55
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