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### (54) MULTI-CHANNEL FIBER-OPTIC ROTARY JOINT

MULTIKANAL FASER-OPTISCHE DREHGELENKKUPPLUNG

RACCORD TOURNANT POUR FIBRES OPTIQUES MULTI-CANAUX

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## Description

[0001] This invention relates to a multi-channel fiber-optic rotary joint and, more particularly, to a rotary joint, as aforesaid, wherein an adjustment mechanism is provided for optimizing the signal strength transmitted through the rotary joint from one set of fiber strands in an bundle to another set of fiber strands in a separate bundle disposed axially from the first bundle.

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## BACKGROUND OF THE INVENTION

[0002] Multi-channel fiber-optic rotary joints are known in the art and one example thereof is described in U.S. Patent No. 5 271 076. As is explained in this patent, the extreme tolerances associated with multi-channel rotary joints exhibit high optical loss and variation of that loss with rotation.

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[0003] Accordingly, it is an object of this invention to provide a multi-channel fiber-optic rotary joint which is capable of effecting an optimization of signal strength through the rotary joint and rendering the signal strength essentially constant during rotation of one end of the rotary joint with respect to the other end.

[0004] EP A 0 111 390 discloses a multi-channel fiber-optic rotary joint.

[0005] Another form of multi-channel fiber-optic rotary joint is disclosed in US-A-5442721.

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[0006] A multi-channel fiber-optic rotary joint according to the present invention is defined by the features set out in claim 1.

## SUMMARY OF THE INVENTION

[0007] Other objects and purposes of this invention will be apparent to persons acquainted with apparatus of this general type upon reading the following specification and inspecting the accompanying drawings, in which:

Figure 1 is an isometric view of a multi-channel fiber-optic rotary joint embodying the invention;

Figure 2 a fragmentary isometric view of a fragment of the aforesaid rotary joint;

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Figure 3 is an isometric view of a prism stage;

Figure 4 is a isometric sectional view of the prism stage;

Figure 5 is a side view of the control mechanism utilized for rotatively linking the respective ends of the rotary joint;

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Figure 6 is an end view of a hollow shaft containing a plurality of fiber optic strands therein; and

Figures 7 and 8 are schematic illustrations of related gear arrangements disclosed herein.

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## DETAILED DESCRIPTION

[0008] Certain terminology will be used in the following description for convenience and reference only and will not be limiting. The words "up", "down", "right" and "left" will designate directions in the drawings to which reference is made. The words "in" and "out" will refer to directions toward and away from, respectively, the geometric center of the device and designated parts thereof. Such terminology will include derivatives and words of similar import.

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[0009] A multi-channel fiber-optic rotary joint 10 is illustrated in Figure 1. It includes a housing 11 having an elongate passageway 12 extending axially therethrough. The housing 11 consists of two housing parts 11A and 11B that are coupled together by a plurality of screws (not illustrated). When the housing parts 11A and 11B are assembled, a cylindrical housing is defined with an axially extending passageway 12 extending therethrough.

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[0010] The left end of the housing illustrated in Figure 1 includes a support section 13 for rotatably supporting a hollow shaft 14 in plural coaxially oriented bearings 16. A spur gear 17 is oriented between the bearing sets 16 as illustrated in Figure 1 and projects through a gap 18 in the support section 13. The left end of the hollow shaft 14 terminates in a radial flange 19, which flange can be used for securing the hollow shaft 14 to either a fixed or rotatable member not illustrated.

[0011] The right end of the housing 11 includes a support section 21 rotatably supporting a hollow shaft 22 on sets of bearings 23 supported on the support section 21. A spur gear 24 identical in size and having an equal number of teeth as the spur gear 17 is mounted on the hollow shaft 22 and oriented between the sets of bearings 23 as illustrated in Figure 1. The axis of rotation 26 of the hollow shaft 14 is coaxial with the axis of rotation 27 of the hollow shaft 22. A radial flange 25 is mounted on the hollow shaft 22 in a manner similar to the radial flange 19 on the hollow shaft 14. As with the radial flange 19, the radial flange 25 also provides facilitation of a mounting to either a fixed or rotatable member.

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[0012] As shown in Figure 1, the leftmost bearing 23 has a radially outwardly extending flange 23A which is received in a groove 23B in the support section 21. A load ring 23C is threadedly engaged with the support section 21 immediately to the right of the rightmost bearing 23 and, when turned, effects an application of an axial force on the

rightmost bearing and directed toward the radial flange 23A to compress the bearings 23 and the hub for the spur gear 24 therebetween. This axially applied force also removes any unwanted radial play or clearance in the bearings 23 so as to keep the position of the axis of the shaft 22 from varying in the support structure 13.

[0013] A similar construction exists for the bearings 16. Here, the rightmost bearing 16 has a radially outwardly extending flange 16A thereon received in a not illustrated groove in the support section 13, which is similar to the groove 23B in the support section 21. A load ring 16B is threadedly secured to the support section 13 to effect, when turned, an application of an axial force toward the radial flange 16A to compress the bearings 16 and the hub for the spur gear 17 therebetween to accomplish the same objective as was done with the bearings 23.

[0014] A plurality of fiber optic strands 28 and 29 forming a bundle 30 are oriented in each of the hollow shafts 14 and 22. In this particular embodiment, the central fiber optic strand 28 of the fiber optic bundle 30 in each of the hollow shafts 14 and 22 is oriented centrally of the hollow shaft whereas the remaining, here six, fiber optic strands 29 are oriented circumferentially thereof as illustrated in Figure 6. Thus, there are present in the disclosed invention a 7-channel rotary joint, each channel being designated by a single fiber optic strand.

[0015] As is illustrated in Figure 1, the terminal ends of the fiber optic strands 28 and 29 of the two bundles 30 in each of the hollow shafts 14 and 22 oppose one another through the passageway 12 in the housing 11. An adjustable prism apparatus 31 is oriented in the signal path transitioning between the terminal ends of the fiber optic strands 28 and 29 in both bundles. The adjustable prism apparatus 31 includes a prism stage 32 best illustrated in Figures 2-4. The prism stage 32 includes an elongated base wall 33 and a pair of upstanding and parallel sidewalls 34 and 36 upstanding from the lateral edges of the base wall 33. The sidewall 36 has a reduced thickness section 37 in which is housed a leaf spring 38 bowing inwardly into the lateral space between the sidewalls 34 and 36. As is illustrated in Figure 4, the bottom wall 33 has an opening 39 in generally the central region thereof adjacent the right end. The bottom wall also includes a laterally extending groove 41 adjacent the left end. The groove 41 opens through the bottom portion of the sidewall 36 as at 42. A pin 43 is received into the opening 42 and the groove 41 so that the upper surface thereof projects above the surface of the bottom wall 33 as illustrated in Figure 3.

[0016] The upstanding wall 34 has at the end thereof adjacent the hole 39 an upstanding groove 44 adapted to receive therein a pin 46 as illustrated in Figure 2. A hole 47 is provided in the upstanding sidewall 34 adjacent the groove 41. The aforesaid holes 39 and 47 are adapted to receive a threaded set screw for applying respective forces onto the prism yet to be described.

[0017] A post 48 depends downwardly from the underside of the base wall 33. The base wall is also provided with upstanding stops 49 adjacent the longitudinal ends thereof.

[0018] To accommodate the prism stage 32 in the housing 11, a region between the terminal ends of the fiber optic strands 28 and 29 of the bundles 30 in the respective hollow shafts 14 and 22 includes a recess 51 having upstanding sidewalls, only one sidewall 52 being illustrated in Figure 2, end walls 53 and 54 and a bottom wall 56. The bottom wall 56 includes a pocket 57, polygonal in cross section, with a hole 58 extending from the bottom wall thereof. The hole 58 is adapted to receive an externally threaded set screw.

[0019] The prism stage 32 is inserted into the recess 51 with the post 48 being slidably received into the pocket 57. The sidewalls 34 and 36 of the prism stage 32 slidably engage the sidewall 52 of the recess 51. The post 48 has a polygonal cross section and corresponds to the polygonal cross section of the pocket 57 so as to prevent the prism stage from pivoting about an upright axis defined by the longitudinal axis of the post 48.

[0020] A dove prism 61 is received in the space between the sidewalls 34 and 36 of the prism stage 32 as illustrated in Figures 1 and 2. Dove prisms are also known as reversion prisms. The entry and exit faces are inclined and are anti-reflection coated. The width of the dove prism is slightly less than the spacing between the upstanding sidewalls 34 and 36 of the prism stage 32 so that the spring 38 will urge the dove prism against the sidewall 34 while maintaining a small space between the sidewall of the dove prism and the sidewall 36 of the prism stage. As a result, a turning of a set screw in the hole 47 will apply a force  $F_1$  to the corresponding side of the dove prism 61 to cause the dove prism 61 to pivot about a vertically upright axis defined by the pin 46. Similarly, the turning of a set screw in the hole 58 will apply a force  $F_2$  to the bottom end of the post 48 to raise and lower the prism stage 32. Turning of a set screw in the hole 39 will generate a force  $F_3$  on one end of the dove prism 61 to cause the dove prism 61 to tilt about the axis defined by the pin 43. A spring 62, schematically illustrated in Figure 2 applies a downwardly directed force  $F_4$  onto the top surface of the dove prism 61 so that when the respective set screws in the holes 39 and 58 are backed-off, the spring force  $F_4$  will be sufficient to return the dove prism 61 to an original position thereof. Similarly, a backing off of the set screw in the hole 47 will enable the spring 38 to return the dove prism laterally to the original position thereof about the upright pivot axis defined by the pin 46. The stops 49 retain the dove prism 61 therebetween and prevent a longitudinal shifting of the dove prism 61 relative to the housing 11.

[0021] Utilizing the adjustment features on the prism stage 32, a signal  $S_1$  exiting the central fiber optic strand 28 in the hollow shaft 14 can be adjusted so that the output signal  $S_2$  from the dove prism 61 will be optimized into the central fiber optic strand 28 oriented in the hollow shaft 22. Once this has been accomplished, the signal strength from the outer fiber optic strands 29 oriented in the hollow shaft 14 now need to be optimized into the fiber optic strands 29 oriented in the hollow shaft 22. The following structure accomplishes that objective.

[0022] As is illustrated in Figure 1, the thickness of the wall of the housing part 11A is reduced as at 62 and 63 so that the spur gears 17 and 24 project through their respective gaps 18, 20 into the regions 62 and 63. Three longitudinally extending holes are cut lengthwise through the wall thickness of the housing part 11A, only two of the holes 64 and 66 being illustrated in Figure 1. The third not illustrated hole is immediately adjacent the hole 64. All three holes open into the respective regions 62 and 63.

[0023] Turning now to Figure 5, the hole 66 receives therein an elongate shaft 67 rotatably supported on spaced bearings 68. A spur gear 69 is secured to the end of the shaft 67 adjacent the exposed portion of the spur gear 17 projecting through the gap 18.

[0024] An elongate shaft 71 is received into the hole 64 and is rotatably supported thereon by axially spaced bearings 72. A spur gear 73 identical to the spur gear 69 is secured to the right end of the shaft 71 and is oriented adjacent the exposed portion of the spur gear 24 projecting through the gap 20. A spur gear 74 is secured to the end of the shaft 71 adjacent both of the spur gears 17 and 69 and has a sufficient width to enable the teeth thereof to mesh with the teeth of the spur gears 17 and 69. A spring 76, schematically illustrated in Figure 5, applies a force  $F_5$  on the bearing 72 to urge the spur gear 74 into tight engagement with the teeth on both of the spur gears 17 and 69 so as to eliminate any backlash that might be present therebetween.

[0025] A unique feature of the gear 74 is that it is secured to a collet mechanism 77 which supports the gear 74 for rotation with respect to the shaft 71. The gear 74 can be rendered fixed to the shaft 71 by tightening the screw 78 on the collet mechanism 77. In other words, a loosening of the screw 78 will enable the collet to slip with respect to the shaft 71 thereby enabling the gear 74 to freely rotate with respect to the shaft 71.

[0026] An elongate shaft 79 is received into the hole 65 (Figure 5), namely, that hole which is behind the shaft 64 illustrated in Figure 1, and is rotatably supported in the hole 65 by axially spaced bearings 81. A gear 82 identical to the gear 74 is fixedly secured to the end of the shaft 79 adjacent the exposed portion of the spur gear 24 projecting through the gap 20 and the spur gear 73. In fact, the teeth on the spur gear 82 are meshed with the teeth on the spur gears 24 and 73. A spring 83, schematically illustrated in Figure 5, applies a force  $F_6$  onto the bearing 81 adjacent the spur gear 82 so as to effect an urging of the teeth of the spur gear 82 into a tightly meshed relation with the teeth on the spur gears 24 and 73 in order to eliminate any backlash that may be present therebetween.

[0027] Figure 7 shows very schematically the loading scheme for achieving an antibacklash condition for all three gears. This loading scheme applies to gears of differing diameters as long as the pitch of the teeth is the same. Note that gears 17, 24 and 69, 73 are not in the same plane and do not mesh. Gears 74, 82 are long enough (into the page) to mesh with both gears 17, 24 and 69, 73. Gears 17, 24 and 69, 73 have fixed rotation centers. Thus, gears 74, 82 cannot have a fixed rotation center since small eccentricities in manufacture would cause very high stresses in the gear teeth that would cause high friction, yield in the metal tooth face, or both. The gears and their respective shafts are simply too rigid to allow for even small eccentricities in the gears.

[0028] A lateral load is supplied by a spring which is designed to be compliant enough not to yield while supplying enough load to maintain two tooth contact between gears 17, 24 and gears 74, 82 and gears 69, 73 and gears 74, 82.

[0029] Figure 8 shows the effect of this arrangement. The pitch circle of gears 74, 82 rides in the v-angle formed by the two tangent lines of contact. Traditionally, antibacklash is achieved by using two gears in a scissors arrangement, but this type of antibacklash device cannot maintain the antibacklash effect between two gears simultaneously. The device presented here can. It also has an advantage in that the spring used to provide the lateral load can be designed independently of the gear set. Thus, the spring load can be corrected to an appropriate setting without starting from scratch on the gear set.

[0030] Since the adjustable prism apparatus 31 described above has facilitated an optimization of the signal strength transfer between the central fiber optic strand 28 in the fiber optic bundle 30 oriented in the hollow shaft 14 to or from the central fiber optic strand 28 in the fiber optic bundle 30 oriented in the hollow shaft 22, the next adjustment that needs to occur is an optimization of the signal strength transfer between the outer fiber optic strands 29 in both bundles. This adjustment is accomplished in the following manner. The screw 78 is loosened so that the collet mechanism 77 facilitates the free rotation of the spur gear 74 relative to the shaft 71. As a result, the spur gear 24 can now be rotated relative to the spur gear 17 until signal strength optimization occurs with the outer fiber optic strands 29. Once signal strength optimization has occurred, the screw 78 is again tightened to lock the spur gear 74 to the shaft 71. Any relative rotative movement between the hollow shafts 14 and 22 will not negatively affect the aforesaid obtained signal strength optimization. Thus, if the radial flange 25 is secured to a rotating object and the flange 19 is secured to a fixed object, data can be effectively transmitted from the respective fiber optic bundles without any loss of signal optimization. During a relative rotation between the respective radial flanges 19 and 25, it is to be understood that the housing 11 is also rotating about the axes 26 and 27. This rotation of the housing 11 is caused by the spur gear 24 rotating relative to the spur gear 17 to cause the spur gears 82 and 73 to transmit a rotative force through the shaft 71 to the spur gear 74 to the teeth on the fixed spur gear 17. As a result, the rotating spur gear 74 will effect a rotative drive of the housing 11 in a direction of rotation that is the same as that of the spur gear 24 but half as fast.

[0031] Although a particular preferred embodiment of the invention has been disclosed in detail for illustrative purposes, it will be recognized that variations or modifications of the disclosed apparatus, including the rearrangement of parts, lie within the scope of the appended claims.

## Claims

1. A multi-channel fiber-optic rotary joint comprising first and second pluralities of optical fiber strands having their terminal ends facing each other, the two pluralities being supported for relative rotation about an axis in an elongate housing (11), a dove prism (61) oriented between the terminal ends of the two pluralities of optical fibers arranged to transmit optical signals between corresponding terminal ends of the two pluralities in all relative rotational positions of the two pluralities, the dove prism being (61) is elongate and having its longitudinal axis generally coaxial with the said axis, and control means (17, 24, 69, 71, 73, 74, 82) for counter-rotatively linking the pluralities relatively to the prism, wherein

each plurality of optical fiber strands is mounted in a respective hollow shaft (14, 22) to form a bundle, the hollow shafts (14, 22) are rotatably supported in a passageway (12) extending axially through the elongate housing (11),

each bundle includes a single central first optical fiber strand (28), the central longitudinal axis of each first optical fiber strand being coaxial with the axis of rotation,

second optical fiber strands (29) in each bundle are disposed peripherally around the central first fiber strand, and adjusting means are provided for the prism for tilting the prism about two axes and for moving the prism orthogonally to the longitudinal axis of the prism for optimizing signal strength transmitted between the first optical fiber strands (28) of the two bundles and

the control means (17, 24, 69, 71, 73, 74, 82) include angular adjustment means (78) for optimizing signal strength in said plural second fiber strands (29) in said bundles.

2. The multi-channel fiber-optic rotary joint according to claim 1, wherein said control means (17, 24, 69, 71, 73, 74, 82) includes a first gear (17) fixed to said first hollow shaft (14), a second gear (24) fixed to said second hollow shaft (22) and an elongate shaft (71) rotatably supported on said housing (11) and having a third gear (73) fixed thereto and rotatable therewith and engaged with a rotatably supported fourth gear (82) engaged with said second gear (24), a fifth gear (74) rotatably supported on said elongate shaft (71) and engaged with said first gear (17), and selective locking means (77, 78) for selectively locking and unlocking said fifth gear (74) to said elongate shaft (71).
3. The multi-channel fiber-optic rotary joint according to claim 2, wherein when said selective locking means (77, 78) is unlocked, said second hollow shaft (22) and said second bundle (28, 29) therein is free to rotate about said second axis of rotation relative to said first hollow shaft (14) and said first bundle (28, 29) therein to facilitate an optimizing of signal strength in said plural fiber strands in said first and second bundles.
4. The multi-channel fiber-optic rotary joint according to claim 2 or 3, wherein anti-backlash means (76, 83) is provided for limiting relative angular movement between said first and second gears (17, 24) when said selective locking means is locked.
5. The multi-channel fiber-optic rotary joint according to claim 4, wherein said control means includes a rotatably supported sixth gear (69) engaged to said first gear (17).
6. The multi-channel fiber-optic rotary joint according to claim 5, wherein anti-backlash means (76, 89) further includes said fourth gear (82) and said fifth gear (74) being floatingly supported to accommodate manufacturing tolerance variations in said first (17), second (24), third (73) and sixth gears (69).

#### Patentansprüche

1. Drehbare Mehrkanal-Lichtwellenleiterverbindung, umfassend eine erste und eine zweite Mehrzahl von Lichtwellenleiterfasern, deren Abschlussenden einander zugekehrt sind, wobei die zwei Mehrzahlen zum relativen Drehen um eine Achse in einem **gleichen** Gehäuse (11) gelagert sind, ein zwischen den Abschlussenden der zwei Mehrzahlen von Lichtwellenleitern ausgerichtetes Dove-Prisma (61), das zum **Übertragen** von optischen Signalen zwischen entsprechenden Abschlussenden der zwei Mehrzahlen in allen relativen Drehungspositionen der zwei Mehrzahlen angeordnet ist, wobei das Dove-Prisma (61) **möglich** ist und seine **Längsachse** mit der genannten Achse **allgemein** **koaxial** ist, und Steuermittel (17, 24, 69, 71, 73, 74, 82) zum **gegendrehungsweisen** Verbinden der Mehrzahlen relativ zu dem Prisma, wobei

jede Mehrzahl von Lichtwellenleiterfasern in einer jeweiligen hohen Welle (14, 22) montiert ist, um ein **Bündel** zu bilden, wobei die hohen Wellen (14, 22) drehbar in einem Durchgang (12) gelagert sind, der axial durch das **gleiche** Gehäuse (11) verläuft,

jedes **Bündel** eine einzelne zentrale erste Lichtwellenleiterfaser (28) hat, wobei die zentrale **Längsachse** jeder ersten Lichtwellenleiterfaser mit der Drehachse **koaxial** ist,

zweite Lichtwellenleiterfasern (29) in jedem **Bündel** peripher um die zentrale erste einzelne Einzelfaser herum angeordnet sind und

Einstellungsmitte **für** das Prisma zum Neigen des Prismas um zwei Achsen und zum Bewegen des Prismas **orthogonal** zur **Längsachse** des Prismas bereitgestellt sind zum Optimieren der zwischen den ersten Lichtwellenleiterfasern (28) der zwei **Bündel** **Übertragenen** Signalstärke und

die Steuermittel (17, 24, 69, 71, 73, 74, 82) Winkeleinstellungsmitte (78) zum Optimieren der Signalstärke in den genannten mehreren zweiten Einzelfasern (29) in den genannten **Bündeln** aufweisen.

2. Drehbare Mehrkanal-Lichtwellenleiterverbindung nach Anspruch 1, bei der das genannte Steuermittel (17, 24, 69, 71, 73, 74, 82) ein erstes Getrieberad (17), das an der genannten ersten hohen Welle (14) befestigt ist, ein zweites Getrieberad (24), das an der genannten zweiten hohen Welle (22) befestigt ist, und eine **gleiche** Welle (71) hat, die drehbar an dem genannten Gehäuse (11) gelagert ist und ein daran befestigtes und mit ihm drehbares drittes Getrieberad (73), das mit einem drehend gelagerten vierten Getrieberad (82) in Eingriff ist, das mit dem genannten zweiten Getrieberad (24) in Eingriff ist, ein drehbar auf der genannten **gleichen** Welle (71) gelagertes und mit dem

genannten ersten Getrieberad (17) in Eingriff befindliches f ftes Getrieberad (74) und Selektivarretierungsmittel (77, 78) zum selektiven Arretieren und L sen des genannten f ften Getrieberads (74) an der genannten l glichen Welle (71) hat.

3. Drehbare Mehrkanal-Lichtwellenleiterverbindung nach Anspruch 2, bei der, wenn das genannte Selektivarretierungsmittel (77, 78) gel st ist, die genannte zweite hohle Welle (22) und das genannte zweite B del (28, 29) darin sich frei um die genannte zweite Drehachse relativ zu der genannten ersten hohlen Welle (14) und dem genannten ersten B del (28, 29) darin drehen k nnen, um eine Optimierung der Signalst ke in den genannten mehreren Einzelfasern in dem genannten ersten und zweiten B del zu erleichtern.
4. Drehbare Mehrkanal-Lichtwellenleiterverbindung nach Anspruch 2 oder 3 mit einem Spielausgleichmittel (76, 83) zum Begrenzen der relativen Winkelbewegung zwischen dem genannten ersten und zweiten Getrieberad (17, 24), wenn das genannte Selektivarretierungsmittel arretiert ist.
5. Drehbare Mehrkanal-Lichtwellenleiterverbindung nach Anspruch 4, bei der das genannte Steuermittel ein drehbar gelagertes sechstes Getrieberad (69) hat, das mit dem genannten ersten Getrieberad (17) in Eingriff ist.
- 10 6. Drehbare Mehrkanal-Lichtwellenleiterverbindung nach Anspruch 5, bei der das Spielausgleichmittel (76, 89) ferner das genannte vierte Getrieberad (82) und das genannte f fte Getrieberad (74) beinhaltet, die schwimmend gelagert sind, um Fertigungstoleranzvariationen in dem genannten ersten (17), zweiten (24), dritten (73) und sechsten (69) Getrieberad auszugleichen.

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## Revendications

1. Joint tournant pour fibres optiques ?canaux multiples comprenant des premi re et deuxi me pluralit  de brins de fibre optique dont les extr mit es terminales se font face, les deux pluralit s  tant support s pour tourner relativement autour d'un axe dans un logement allong (11), un prisme de Dove (61) orient entre les extr mit es terminales des deux pluralit s de fibres optiques agenc pour transmettre des signaux optiques entre des extr mit es correspondantes des deux pluralit s dans toutes les positions rotationnelles relatives des deux pluralit s, le prisme de Dove (61)  tant allong et ayant son axe longitudinal g alement coaxial audit axe, et un moyen de commande (17, 24, 69, 71, 73, 74, 82) pour joindre en contre-rotation les pluralit s relativement au prisme, dans lequel  
chaque pluralit  de brins de fibre optique est mont  dans un arbre creux respectif (14, 22) afin de former un faisceau, les arbres creux (14, 22) sont support s en rotation dans un passage (12) qui s' tend axialement ?travers le logement allong (11),  
chaque faisceau comporte un premier brin de fibre optique central unique (28), l'axe longitudinal central de chaque premier brin de fibre optique  tant coaxial avec l'axe de rotation,  
des deuxi mes brins de fibre optique (29) dans chaque faisceau sont dispos s en p iph sie autour du premier brin de fibre optique central, et  
des moyens de r glage sont fournis pour le prisme pour incliner le prisme autour de deux axes et pour d splacer le prisme orthogonalement ?l'axe longitudinal du prisme pour optimiser la force de signal transm e entre les premiers brins de fibre optique (28) des deux faisceaux et le moyen de commande (17, 24, 69, 71, 73, 74, 82) comportent un moyen de r glage angulaire (78) pour optimiser la force de signal dans lesdits plusieurs deuxi mes brins de fibre optique (29) dans lesdits faisceaux.
2. Joint tournant pour fibres optiques ?canaux multiples selon la revendication 1, dans lequel ledit moyen de commande (17, 24, 69, 71, 73, 74, 82) comporte un premier engrenage (17) fix audit premier arbre creux (14), un deuxi me engrenage (24) fix audit deuxi me arbre creux (22) et un arbre allong (71) support en rotation sur ledit logement (11) et ayant un troisi me engrenage (73) fix sur celui-ci et pouvant tourner avec celui-ci et engag avec un quatri me engrenage support en rotation (82) engag avec ledit deuxi me engrenage (24), un cinqui me engrenage (74) support en rotation sur ledit arbre allong (71) et engag avec ledit premier engrenage (17), et un moyen de verrouillage s lectif (77, 78) pour verrouiller et d sverrouiller s lectivement ledit cinqui me engrenage (74) sur ledit arbre allong (71).
3. Joint tournant pour fibres optiques ?canaux multiples selon la revendication 2, dans lequel quand ledit moyen de verrouillage s lectif (77, 78) est d sverrouill  ledit deuxi me arbre creux (22), et ledit deuxi me faisceau (28, 29) dans celui-ci, est libre de tourner autour dudit deuxi me axe de rotation par rapport audit premier arbre creux (14), et audit premier faisceau (28, 29) dans celui-ci, afin de faciliter une optimisation de la force de signal dans lesdits plusieurs brins de fibre dans lesdits premier et deuxi me faisceaux.
4. Joint tournant pour fibres optiques ?canaux multiples selon la revendication 2 ou 3, dans lequel un moyen anti-jeu (76, 83) est fourni pour limiter le d placement angulaire relatif entre lesdits premier et deuxi me engrenages (17, 24) quand ledit moyen de verrouillage s lectif est verrouill .
5. Joint tournant pour fibres optiques ?canaux multiples selon la revendication 4, dans lequel ledit moyen de

commande comporte un sixième engrenage support en rotation (69) engagé avec ledit premier engrenage (17).

6. Joint tournant pour fibres optiques ?canaux multiples selon la revendication 5, dans lequel le moyen anti-jeu (76, 89) comporte en outre ledit quatrième engrenage (82) et ledit cinquième engrenage (74) supporté de manière flottante pour accepter les variations de tolérance de fabrication dans lesdits premier (17), deuxième (24), troisième (73) et sixième (69) engrenages.

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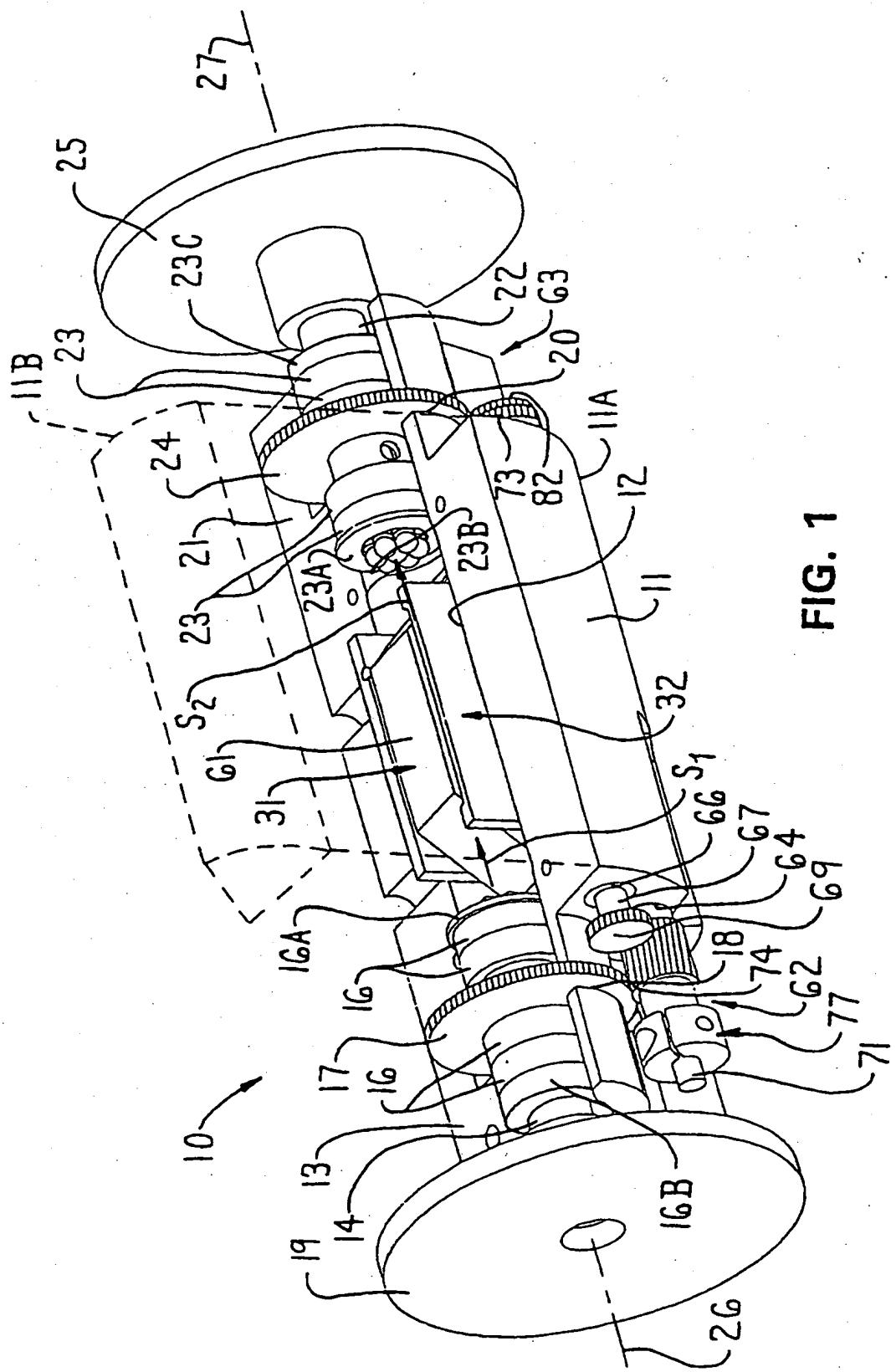


FIG. 1

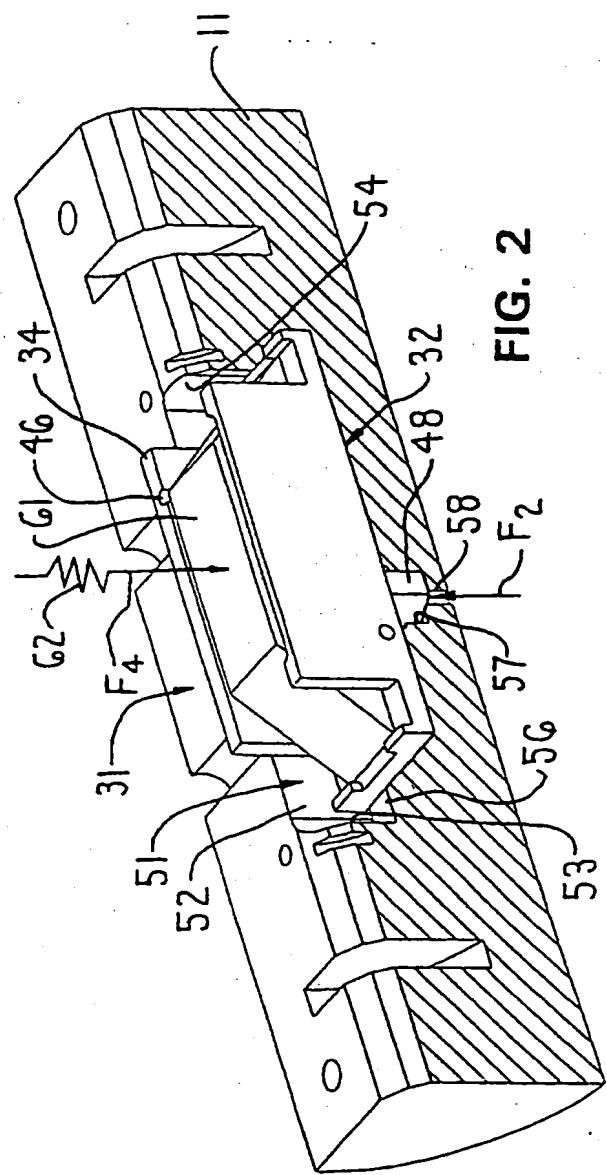


FIG. 2

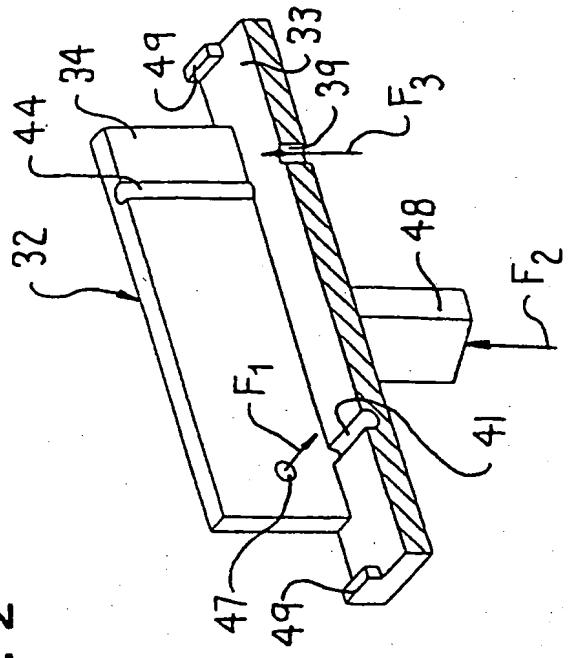


FIG. 4

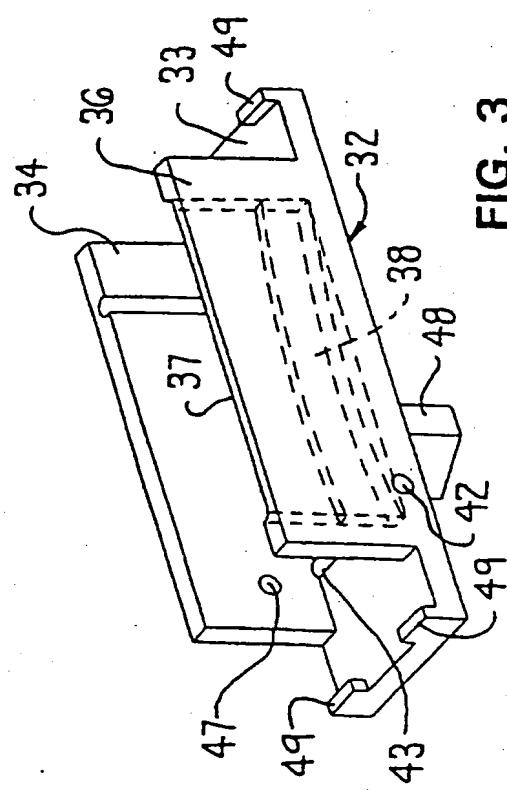
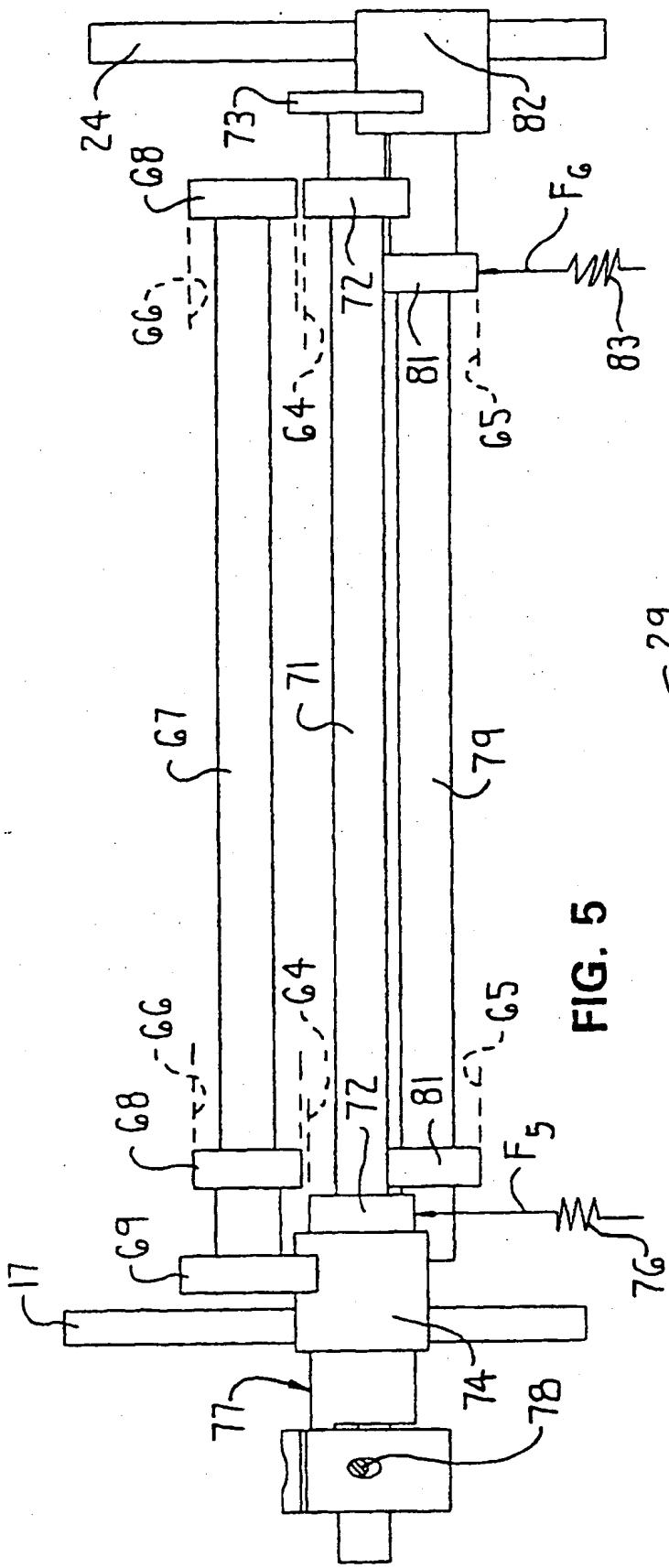


FIG. 3



5  
EIG

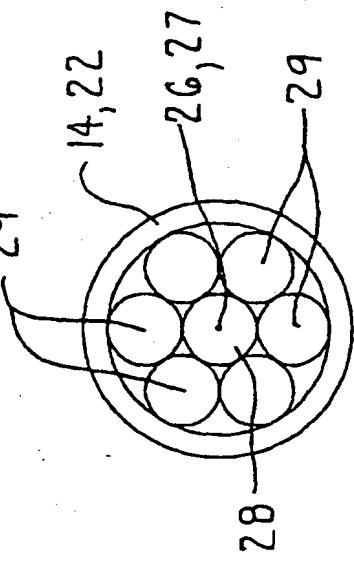
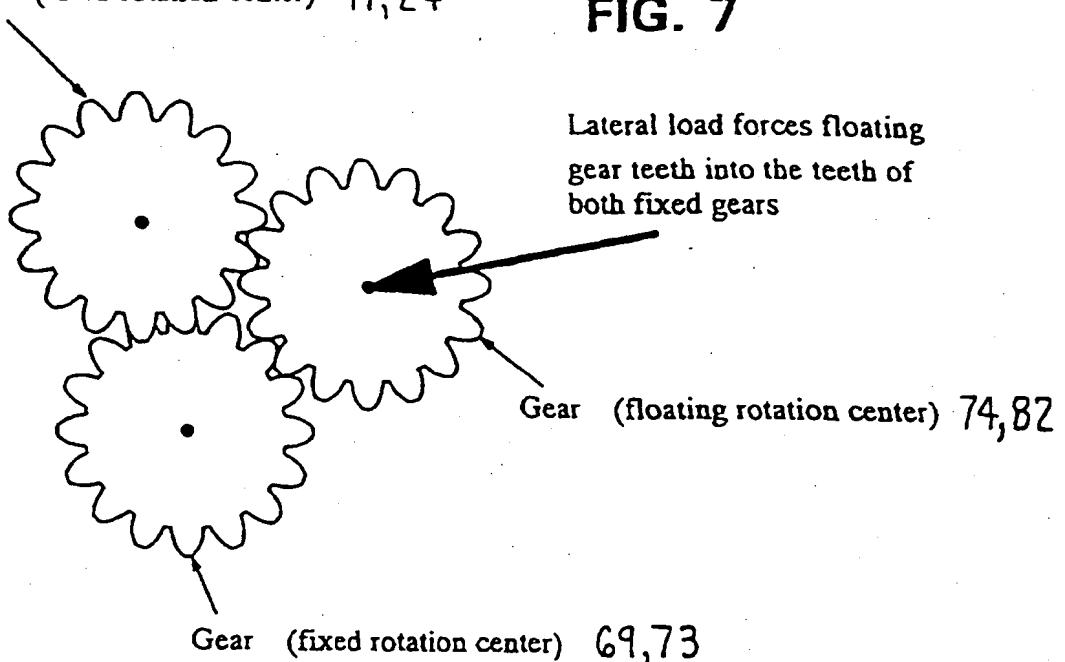


FIG. 6

Gear (fixed rotation center) 17,24

**FIG. 7**



Pitch circle for gear 17,24

**FIG. 8**

