

(43) International Publication Date
6 November 2014 (06.11.2014)

(51) International Patent Classification: Not classified

(21) International Application Number:
PCT/EP2014/058835(22) International Filing Date:
30 April 2014 (30.04.2014)

(25) Filing Language: English

(26) Publication Language: English

(30) Priority Data:
1350546-6 3 May 2013 (03.05.2013) SE

(71) Applicant: ATLAS COPCO INDUSTRIAL TECHNIQUE AB [SE/SE]; S-105 23 Stockholm (SE).

(72) Inventors: KARLSSON, Karl PETER; Siljansvägen 8, S-120 55 Årsta (SE). KJELLQVIST, Lars PETER Johan; Sågårtorp, S-150 21 Mölnbo (SE). SIGRAND, Sven MARTIN; Solviksstrand 10, S-142 66 Trångsund (SE).

(74) Agent: EKEBERG, Lars; ATLAS COPCO INDUSTRIAL TECHNIQUE AB, Patent Department, S-10523 Stockholm (SE).

(81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM,

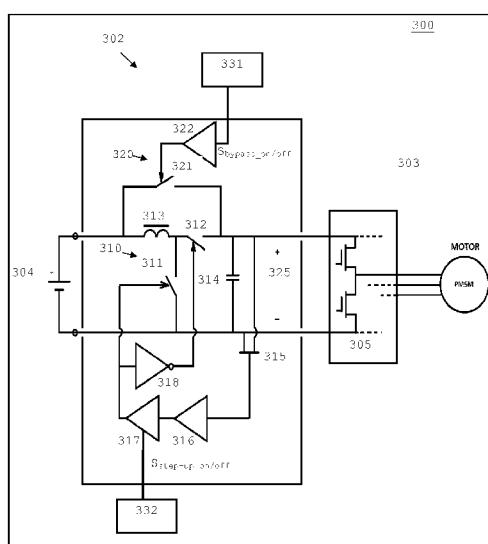
AO, AT, AU, AZ, BA, BB, BG, BH, BN, BR, BW, BY, BZ, CA, CH, CL, CN, CO, CR, CU, CZ, DE, DK, DM, DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IR, IS, JP, KE, KG, KN, KP, KR, KZ, LA, LC, LK, LR, LS, LT, LU, LY, MA, MD, ME, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PA, PE, PG, PH, PL, PT, QA, RO, RS, RU, RW, SA, SC, SD, SE, SG, SK, SL, SM, ST, SV, SY, TH, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.

(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LR, LS, MW, MZ, NA, RW, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, RU, TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV, MC, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK, SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, KM, ML, MR, NE, SN, TD, TG).

Published:

— without international search report and to be republished upon receipt of that report (Rule 48.2(g))

(54) Title: POWER TOOL WITH STEP-UP CONVERTER



(57) **Abstract:** A power tool including an electrical motor unit that is connectable to a battery unit is disclosed. According to the invention, the power tool includes a step-up converter that is connectable between the battery unit and the electrical motor unit, which is arranged for converting, when enabled, a battery voltage U_{battery} that is provided to the step-up converter to a higher step-up voltage $U_{\text{step-up}}$; $U_{\text{step-up}} > U_{\text{battery}}$. The step-up voltage $U_{\text{step-up}}$ is then provided to the electrical motor unit as an output voltage U_{output} ; $U_{\text{output}} = U_{\text{step-up}}$. The power tool also includes a bypass circuit that is arranged in parallel with the step-up converter. The bypass circuit connects, when enabled, the battery unit to the electrical motor unit, thereby providing battery voltage U_{battery} to the electrical motor unit as an output voltage U_{output} ; $U_{\text{output}} = U_{\text{battery}}$. At least one control unit is arranged for controlling the step-up converter and the bypass circuit such that the output voltage U_{output} may be switched between the battery voltage U_{battery} and the step-up voltage $U_{\text{step-up}}$.

Fig. 3

POWER TOOL WITH STEP-UP CONVERTER**Field of the invention**

The present invention relates to a power tool as defined in the preamble of claim 1.

5 The present invention also relates to a method for providing an electrical motor unit of a power tool with an output voltage U_{output} , as defined in the preamble of claim 24.

The present invention also relates to a computer program and to a computer program product.

10 **Related art and background of the invention**

Power tools including an electrical motor unit are often provided with electrical power from a battery unit. Figure 1 schematically shows an example of such a power tool 100. The power tool 100 includes a body/housing 101 and a shaft/spindle 102. An electrical motor unit is used for driving the shaft 102. The electrical motor is driven by a battery unit 104. The battery unit 104 can be mounted at a handle 103 of the power tool, as shown in figure 1, but can also be mounted on other parts of the power tool 100. However, the battery unit 104 can also be located separated from the power tool 100, and the electrical power can then be provided to the electrical motor unit by one or more cables that are connected between the external battery unit and the power tool 100. The power tool 100 further includes a number of parts not shown in figure 1, 15 as is understood by a skilled person.

Power tools of today, such as nut-runners, generally have problems relating to the size and weight of the power tool. There is generally a demand for reducing the size and/or the weight of the power tools, since a small and lightweight power

tool is very useful for the consumer, because it is easy to transport and also practical to use, since it is not too heavy to hold and handle.

Power tools include a number of parts adding to the size and/or weight of the tool. One part having a big influence on the both the size and the weight of the tool is the battery unit. The performance of the power tool is today directly related to the power being supplied by the battery unit, and is thereby also directly related to the size and weight of the battery unit. For example, both the run-down speed and the torque provided by a nut-runner are directly related to a voltage level of the battery unit. Therefore an efficient and high performing nut-runner today has to be provided with a large and heavy battery pack.

In order to try to adapt the power tool to a current performance demand, while minimizing the size and/or weight of the tool, some prior art solutions have utilized a set of different battery units or batteries having different powers and/or voltages. Thus, depending on the needed performance of the power tool, the user has the possibility to choose a suitable battery unit or battery from this set to be connected to the power tool. Hereby, the size and weight of the power tool can be adapted to the performance demand. Handling of a very powerful power tool, which also is very heavy and large, when a much less powerful, and also much smaller and lighter, tool would have been sufficient can hereby be avoided.

However, the set of battery units that can be used in the power tool must still be carried along with the power tool by a user to achieve adaptability of performance and size of the tool. Also, all battery units have to be charged for the user to be able to adapt the battery supply during work with the

tool, which makes this solution not very practical. Also, battery units and/or batteries having different powers and/or voltages are today often provided with different connection interfaces. Thus, a first battery having a first voltage/power

5 may be directly connectable to the power tool while a second battery having a second voltage/power is often not directly connectable to the power tool. It might therefore be difficult to efficiently interchange the batteries, at least without the use of one or more battery adapters.

10 **Aim and most important features of the invention**

It is an object of the present invention to provide a power tool that at least partly solves one or more of the above stated problems.

15 The present invention aims to provide a more compact and lightweight power tool than the power tools known in the background art.

The object is achieved by the above mentioned power tool according to the characterizing portion of claim 1.

20 The object is also achieved by the above mentioned method for providing an electrical motor unit of a power tool with an output voltage U_{output} , according to the characterizing portion of claim 24.

The object is also achieved by the above mentioned computer program and computer program product.

25 The power tool and method according to the present invention are characterized in that an output voltage U_{output} that is provided to an electrical motor unit in the tool may be switched between a battery voltage U_{battery} and a higher step-up voltage $U_{\text{step-up}}$. This switchable output voltage U_{output} is

according to the claimed invention achieved by a step-up converter, a bypass circuit, and at least one control unit controlling the step-up converter and the bypass circuit.

The step-up converter is connectable between a battery unit and the electrical motor unit and is arranged for converting, when enabled, a battery voltage $U_{battery}$ being provided to the step-up converter by the battery unit to a higher step-up voltage $U_{step-up}$; $U_{step-up} > U_{battery}$. This step-up voltage $U_{step-up}$ is then provided to the electrical motor unit as an output voltage U_{output} ; $U_{output}=U_{step-up}$.

The bypass circuit is arranged in parallel with the step-up converter, thereby connecting, when enabled, the battery unit directly to the electrical motor unit and providing the battery voltage $U_{battery}$ to the electrical motor unit as an output voltage U_{output} ; $U_{output}=U_{battery}$.

At least one control unit is arranged for controlling the step-up converter and the bypass circuit in order to switch the output voltage U_{output} between the battery voltage $U_{battery}$ and the step-up voltage $U_{step-up}$. This controlled switching can be achieved by generating a bypass enabling/disabling signal $S_{bypass_on/off}$ and a step-up enabling/disabling signal $S_{step-up_on/off}$, and by proving these enabling/disabling signals to the bypass circuit and the step-up converter, respectively.

The power tool according to the present invention can utilize enabling/disabling of the bypass circuit and the step-up converter, respectively, to alter the output voltage U_{output} that is provided to the motor unit such that a temporally increased rotational speed of the electrical motor unit is achieved. Hereby the productivity of the power tool is increased.

Alternatively, a smaller and lighter battery unit, and thereby a more compact and less heavy power tool, as compared to prior art power tools, can be provided by the present invention. A compact and lightweight power tool is easily handled and therefore the usage of the power tool is improved by the present invention.

According to an embodiment of the present invention, the power tool can be particularly adapted to perform certain activations of the tool, such as tightening and/or loosening of nuts, during which the speed and/or torque should change during the activation to achieve optimal performance. For example, when tightening of a nut, the step-up converter can be enabled and the bypass circuit can be disabled during a first phase of the tool activation. During a second phase, the bypass circuit can be enabled and the step-up converter can be disabled. *Hereby, a high rotational speed and low torque is provided by the power tool during the first phase, followed by a lower rotational speed and higher torque during the second phase.* This gives an optimal performance for e.g. a nut-runner when tightening a nut, where a high speed but not too much moment of force is needed during the first phase, and much more moment of force is needed during the second phase.

According to the invention, this optimal performance is achievable with a compact and lightweight power tool.

When loosening a nut, the first phase can instead provide a high torque T and low rotational speed, and the second phase can provide a high rotational speed and a low torque. This is achieved by enabling the bypass circuit and disabling the step-up converter during the first phase of the activation, followed by enabling the step-up converter and disabling the bypass circuit during the second phase. This gives an optimal performance to e.g. a compact and lightweight nut-runner when

loosening a nut, where much rotational force is needed during the first phase, and much less rotational force is needed during the second phase.

Detailed exemplary embodiments and advantages of the power tool and the method according to the invention will now be described with reference to the appended drawings illustrating some preferred embodiments.

Brief description of the drawings

Fig. 1 shows a power tool.

Fig. 2 shows a power tool according to the present invention.

Fig. 3 shows a power tool according to the present invention.

Fig. 4 shows a tool activation diagram for a tool according to an embodiment of the invention.

Fig. 5 shows a flowchart of an activation method for a tool according to an embodiment of the invention.

Detailed description of preferred embodiments

According to the present invention, the power tool includes a step-up converter, a bypass circuit, and at least one control unit as will be explained in detail below. Figure 2

schematically shows such a power tool 200. In figure 2, the step-up converter, the bypass circuit, and the one or more control units are illustrated as a step-up/bypass module 202 being connectable between a battery unit 204 and an electrical motor unit 203 located within the body 201 of the tool 200.

According to one embodiment of the invention, the step-up module 202, i.e. the step-up converter, the bypass circuit, and the one or more control units, is arranged integrated

within the body 201 of the power tool 200, and is connected to the electrical motor unit 203 and to the battery unit 203.

According to another embodiment of the invention, the step-up/bypass module 202 is integrated with the battery unit 204.

5 Here the integrated battery and step-up/bypass module 202, 204 is connectable to the motor unit 203 of the tool 200.

According to another embodiment of the invention, the step-up/bypass module 202 is arranged separately, i.e. as a separate unit, between the battery unit 204 and the motor unit 10 203. The separately arranged step-up/bypass module 202 is here thus connectable to both the battery unit 204 and to the motor unit 203.

Figure 3 schematically shows a power tool 300 according to the present invention. In figure 3, the power tool 300 is

15 schematically illustrated as including the battery unit 304 and the step-up/bypass module 302. However, as stated above, the battery unit 304 and/or the step-up/bypass unit 302 and/or the one or more control units 331, 332 can also be arranged separately from the power tool 300, i.e. external from the 20 body of the power tool.

The power tool 300 includes an electrical motor unit 303, which is connectable to the battery unit 304 via the step-up/bypass module 302. In figure 3, an inverter 305 is included in the electrical motor unit 303. However, depending on the 25 construction of the electrical motor unit 303 and/or of the step-up/bypass module 302, the inverter 305 may be omitted in the power tool 300.

The step-up/bypass module 302 includes a step-up converter 310 and a bypass circuit 320. The step-up converter 310 is 30 connectable between the battery unit 304 and the electrical

motor unit 303. The step-up converter 310 can be enabled and disabled, and is arranged for converting, when enabled, a battery voltage $U_{battery}$ being provided to the step-up converter 310 by the battery unit 304. The step-up converter 310 thereby converts the battery voltage $U_{battery}$ to a higher step-up voltage $U_{step-up}$; $U_{step-up} > U_{battery}$. This higher step-up voltage $U_{step-up}$ is then provided to the electrical motor unit 303 as an output voltage U_{output} on the output DC bus 325, i.e. $U_{output}=U_{step-up}$. Thus, the electrical motor unit 303 is provided with the higher step-up voltage $U_{step-up}$ when the step-up converter 310 is enabled.

The bypass circuit 320 is arranged in parallel with the step-up converter 310, and is thus also connectable between the battery unit 304 and the electrical motor unit 303. When the bypass circuit 320 is enabled, the battery unit 304 is connected to the electrical motor unit 303 through the bypass circuit 320. The bypass circuit is thus arranged for providing the battery voltage $U_{battery}$ to the electrical motor unit 303, as an output voltage U_{output} on the output DC bus 325, i.e. $U_{output}=U_{battery}$.

The power tool can also be equipped with a brake chopper arranged for protecting the battery unit 304 by preventing the output voltage U_{output} on the output DC bus 325 to reach too high levels when the electrical motor unit 325 is braked/decelerated. Generally, energy is created by the electrical motor unit 303 when a user lets go of the tool trigger, whereby the rotational speed of the power tool is reduced, especially if the higher step-up voltage $U_{step-up}$ has been provided to the electrical motor unit before braking the electrical motor unit is initiated. The brake chopper can be arranged at the output DC bus 325, between the step-up/bypass module 302 and the electrical motor unit 303. For example, the

brake chopper can be implemented as a resistance coupled in series with a switch, such as a MOSFET (Metal Oxide Semiconductor Field Effect Transistor), over the output DC bus 325, and with a diode coupled in parallel with the resistance.

5 Hereby, the energy that is created by the electrical motor unit 303 during its deceleration can be consumed by the resistance, which reduces the output voltage U_{output} on the output DC bus 325 in order to protect the battery unit 304.

10 The power tool 300 according to the present invention further includes at least one control unit 331, 332. The at least one control unit 331, 332 is arranged for controlling the step-up converter 310 and the bypass circuit 320 by enabling/disabling the step-up converter 310 and the bypass circuit 320. The output voltage U_{output} on the output DC bus 325 may hereby be 15 switched between the battery voltage U_{battery} and the step-up voltage $U_{\text{step-up}}$. Thus, by controlling the enabling/disabling of the step-up converter 310 and the bypass circuit 320, respectively, the output voltage U_{output} on the output DC bus 325 can be toggled between the lower battery voltage U_{battery} and 20 the higher step-up voltage $U_{\text{step-up}}$; $U_{\text{battery}} \leq U_{\text{output}} \leq U_{\text{step-up}}$.

25 The power tool 300 according to the present invention can thus temporally increase the rotational speed of the electrical motor unit 303 by providing the temporally increased step-up voltage $U_{\text{step-up}}$ to the electrical motor unit 303. Hereby the productivity of the power tool 300 is increased.

30 Alternatively, the same rotational motor speed as was used in prior art solutions can be achieved by use of a battery unit having a lower voltage $U_{\text{battery_invention}}$ than was possible for the battery voltage $U_{\text{battery_prior art}}$ in the prior art solutions; $U_{\text{battery_invention}} < U_{\text{battery_prior art}}$; since the increased step-up voltage $U_{\text{step-up}}$ by the invention temporally can be high enough

to match the prior art voltage $U_{\text{step-up}} = U_{\text{battery_prior art}}$. Hereby a smaller and lighter battery unit 304, and thereby a more compact and less heavy power tool 300, is provided by the present invention. A compact and lightweight power tool 300 is easily handled, and therefore easier more attractive usage of the power tool 300 is facilitated by the invention.

Also, the step-up and bypass module 302 can be made compact and lightweight according to the solution of the present invention. This is due to the use of the bypass circuit 320 according to the invention. When the motor 303 provides a high effect during heavy load, the bypass circuit 320 is enabled and the step-up converter 310 is disabled, whereby the battery unit 304 is directly coupled to the motor unit 303, possibly including an inverter 305. Hereby, the components of the step-up converter 310 only have to be able to cope with a limited power, since the step-up converter 310 is bypassed when a maximum power is provided from the battery unit 304 to the motor unit 303. Thus, since these components only have to cope with a relatively low electrical power, the step-up and bypass module 302 can be designed to be compact and lightweight, which also reduces the total size and weight of the power tool 300.

According to an embodiment of the present invention, the step-up converter 310 is a synchronous step-up converter, which is arranged for creating the higher step-up voltage $U_{\text{step-up}}$, said step-up converter including at least one step-up transistor 311, at least one inductor 313, and at least one step-up switch 312. The at least one step-up transistor 311 and/or the at least one step-up switch 312 can typically be switched at a relatively high frequency, e.g. at a frequency in the kilohertz (kHz) range. As illustrated in figure 3, the inductor 313 is coupled in series with the battery unit 304

and the step-up switch 312. The step-up transistor 311 is coupled in parallel with the battery unit 304 and in parallel with an output capacitor 314 that is coupled over the output DC bus 325.

5 The step-up converter can further include a step-up control circuitry being arranged for controlling the at least one step-up transistor 311 and/or the at least one step-up switch 312, where the step-up switch 312 can be used for connecting the step-up converter 310 to the output DC bus 325, i.e. to
10 the electrical motor unit 303, when enabled. The step-up control circuitry includes a voltage regulation circuitry 316 and a PWM (Pulse Width Modulation) circuit 317. The voltage regulation circuitry 316, which can be implemented as an amplifier, is arranged for controlling the level of the higher
15 step-up voltage $U_{\text{step-up}}$ towards its target voltage U_{target} by controlling the PWM circuit 317. The voltage regulation circuitry 316 has the output DC bus 325 as an input 315.

The PWM circuit 317 also includes an overload limiting function, which limits/reduces the step-up voltage $U_{\text{step-up}}$ if
20 the step-up converter 310 is overloaded. The PWM circuit 317 also has an input receiving a control signal $S_{\text{step-up_on/off}}$ being provided from a control unit 332 as an input signal. The function of the at least one step-up transistor 311 and the at least one step-up switch 312 is thus controlled by the step-up control circuitry, and in particular by the PWM circuit 317.
25 The control signal that is used for controlling the step-up transistor 311 is provided directly by the PWM circuit 317. The control signal that is used for controlling the step-up switch 312 is an amplified and inverted version of the control signal provided by the PWM circuit 317, where the amplification and inversion are performed by the amplifier/inverter 318.
30

According to an embodiment of the present invention, the bypass circuit 320 includes a bypass switch 321, which is controllable by a control unit 331 providing a bypass control signal $S_{bypass_on/off}$. Thus, the bypass switch 321 is switched at a very low frequency, e.g. twice per activation of the tool, as will be described more in detail below. An amplifier 322 can be used for amplifying the bypass control signal $S_{bypass_on/off}$ from the control unit 331 before providing the amplified control signal to the bypass switch 321.

10

In figure 3, for illustrative reasons, the control units 331, 332 providing the control signals $S_{bypass_on/off}$ and $S_{step-up_on/off}$ are illustrated as two separate control units. However, as is clear for a skilled person, both of these control signals $S_{bypass_on/off}$ and $S_{step-up_on/off}$ can also be provided by a single control unit, essentially including the above and/or below described functions of both of these control units 331, 332.

15

20

25

According to an embodiment of the present invention, one or more of the at least one step-up switch 311, the step-up switch 312, and the at least one bypass switch 321 are implemented as an N-channel MOSFET (Metal Oxide Semiconductor Field Effect Transistor), an P-channel MOSFET (Metal Oxide Semiconductor Field Effect Transistor), or another suitable controllable switching device.

30

According to an embodiment of the present invention, at least one of the step-up switch 312 and the at least one bypass switch 321 are implemented as power diodes, which are especially suitable for lower power applications.

According to an embodiment of the present invention, the step-up converter 310 is a multi-phase converter that is adapted to

convert the battery voltage U_{battery} to a higher step-up voltage $U_{\text{step-up}}$. The multi-phase converter can be a boost type converter, being controllable by the control signal $S_{\text{step-up_on/off}}$.

5

According to an embodiment, the step-up converter 310 is implemented as including two step-up transistor circuits that is operated in mutually opposite phases. Hereby, a smooth output step-up voltage $U_{\text{step-up}}$ can be provided by the step-up converter 310, since a voltage/current ripple on the output DC bus 325 can be reduced by the opposite phase coupled transistor configuration.

According to an embodiment of the invention, the battery unit 304 includes at least one super capacitor. Super capacitors have a very high capacitance value per unit volume and a very high energy density. The super capacitors can thus be utilized as a reliable energy source, as an alternative to a conventional battery. The super capacitors are also very lightweight, much lighter than a corresponding conventional battery energy source. One problem with super capacitors is that they lose their power after a while. However, it is possible to very quickly recharge them again. By the use of the present invention, the output voltage of the super capacitor can be boosted when needed, e.g. when the super capacitor has lost some of its power. For example, the power tool according to the invention, e.g. including a super capacitor in the battery unit, can be used in an assembly line, where the tool could be used for sequential relatively short time periods and could be recharged between these short time periods. By the use of super capacitors, a very compact and light power tool can be provided by implementation of the present invention.

10

15

20

25

30

Thus, the at least one control unit 331, 332 is, according to the invention, arranged for providing the bypass circuit 320 with a bypass enabling/disabling signal $S_{bypass_on/off}$. The bypass circuit 320 is arranged for enabling/disabling the bypass, 5 i.e. for connecting/disconnecting the battery unit 304 to the electrical motor unit 303 based on the bypass enabling/disabling signal $S_{bypass_on/off}$.

Correspondingly, the at least one control unit 331, 332 is arranged for providing the step-up converter 310 with a step-up enabling/disabling signal $S_{step-up_on/off}$. Here, the step-up converter 310 is arranged for enabling/disabling the voltage conversion of the step-up converter 310 based on that step-up enabling/disabling signal $S_{step-up_on/off}$.
10

According to an embodiment of the present invention, the bypass enabling/disabling signal $S_{bypass_on/off}$ and the step-up enabling/disabling signal $S_{step-up_on/off}$ are complementary signals. Thus, the bypass enabling/disabling signal $S_{bypass_on/off}$ and the step-up enabling/disabling signal $S_{step-up_on/off}$ have 15 inverse values. In other words, the bypass enabling/disabling signal $S_{bypass_on/off}$ is an inverse/negated version of the step-up enabling/disabling signal $S_{step-up_on/off}$.
20

Thus, the at least one control unit 331, 332 can preferably be utilized for toggling the output DC bus 325 between the battery voltage $U_{battery}$ and the higher step-up voltage $U_{step-up}$, 25 thereby providing a power tool 300 having the above mentioned advantages of the present invention. A compact and lightweight power tool having high productivity is thus provided by the invention.

As described above, the voltage on the output DC bus 325 can 30 be switched between the battery voltage $U_{battery}$ and the higher step-up voltage $U_{step-up}$ based on an step-up enabling/disabling

signal $S_{\text{step-up_on/off}}$ that is provided to the PWM circuit 317 by the at least one control unit 331, 332 and/or based on a bypass enabling/disabling signal $S_{\text{bypass_on/off}}$ that is provided to the bypass switch 321 by the at least one control unit 331, 332.

The step-up enabling/disabling signals $S_{\text{step-up_on/off}}$ and the bypass enabling/disabling signals $S_{\text{bypass_on/off}}$ are thus created in the at least one control unit 331, 332. The form of these step-up enabling/disabling signals $S_{\text{step-up_on/off}}$ and bypass enabling/disabling signals $S_{\text{bypass_on/off}}$ can be determined by the at least one control unit based on a number of different parameters, either based on single parameter values taken alone, or on two or more parameters in combination.

According to an embodiment of the invention, the at least one control unit is arranged to base the step-up $S_{\text{step-up_on/off}}$ and/or bypass $S_{\text{bypass_on/off}}$ enabling/disabling signals on a relation between the output voltage U_{output} on the output DC bus 325 and a voltage threshold $U_{\text{threshold}}$. Here, a step-up enabling signal $S_{\text{step-up_on}}$ and a bypass disabling signal $S_{\text{bypass_off}}$ are generated by the at least one control unit 331, 332 when the output voltage U_{output} is equal to or higher than the voltage threshold $U_{\text{threshold}}$; $U_{\text{output}} \geq U_{\text{threshold}}$. The embodiment is described more in detail below.

According to another embodiment of the invention, the at least one control unit 331, 332 is arranged to base the step-up $S_{\text{step-up_on/off}}$ and/or $S_{\text{bypass_on/off}}$ bypass enabling/disabling signals on a relation between an output current I_{output} that is provided to the motor unit 325 on the output DC bus 325 and a current threshold $I_{\text{threshold}}$. Here, a step-up disabling signal $S_{\text{step-up_off}}$ and a bypass enabling signal $S_{\text{bypass_on}}$ are generated by the at least one control unit 331, 332 when the output current I_{output}

is equal to or higher than the current threshold $I_{threshold}$; $I_{output} \geq I_{threshold}$. The embodiment is described more in detail below.

According to an embodiment of the invention, the at least one control unit 331, 332 is arranged to base the step-up $S_{step-up_on/off}$ and/or bypass $S_{bypass_on/off}$ enabling/disabling signals on a relation between a rotational speed ω_{motor} of the motor unit 303 multiplied with a torque T that is provided by the tool 300; $\omega_{motor} \cdot T$; and a speed and torque threshold $\omega T_{threshold}$. Thus, the rotational speed ω_{motor} and the torque T that is provided by the shaft/spindle 102 of the power tool is here compared with the speed and torque threshold $\omega T_{threshold}$. A step-up enabling signal $S_{step-up_on}$ and a bypass disabling signal S_{bypass_off} is according to the embodiment generated by the at least one control unit 331, 332 when the rotational speed ω_{motor} multiplied with the torque T ; $\omega_{motor} \cdot T$; is lower than the speed and torque threshold $\omega T_{threshold}$; $\omega_{motor} \cdot T < \omega T_{threshold}$. The embodiment is described more in detail below.

According to an embodiment of the invention, the at least one control unit 331, 332 is arranged to base the step-up $S_{step-up_on/off}$ and/or bypass $S_{bypass_on/off}$ enabling/disabling signals on a relation between an output power P_{output} that is provided to the electrical motor unit 303 on the output DC bus 325 and a power threshold $P_{threshold}$. Here, a step-up enabling signal $S_{step-up_on}$ and a bypass disabling signal S_{bypass_off} are generated by the at least one control unit 331, 332 when the output power P_{output} on the output DC bus 325 is lower than the power threshold $P_{threshold}$; $P_{output} < P_{threshold}$. The embodiment is described more in detail below.

According to an aspect of the present invention, a method for providing an electrical motor unit 304 of a power tool 300

with an output voltage U_{output} is presented. According to the method, at least one control unit 331, 332 is used for controlling the step-up converter 310 and the bypass circuit 320, as described above, such that the output voltage U_{output} on the output DC bus 325 may be switched between the battery voltage U_{battery} and the step-up voltage $U_{\text{step-up}}$; $U_{\text{battery}} \leq U_{\text{output}} \leq U_{\text{step-up}}$. This toggling output voltage is achieved by converting, when the step-up converter 310 is enabled, the battery voltage U_{battery} that is provided to the step-up converter 310 by the battery unit 304 to the higher step-up voltage $U_{\text{step-up}}$; $U_{\text{step-up}} > U_{\text{battery}}$. This step-up voltage $U_{\text{step-up}}$ is then provided to the electrical motor unit 303 as an output voltage U_{output} ; $U_{\text{output}} = U_{\text{step-up}}$. The toggling output voltage is also achieved by connecting, when the bypass circuit 320 is enabled, the battery unit 304 to the electrical motor unit 303, whereby the battery voltage U_{battery} is provided to the electrical motor unit 303 as an output voltage U_{output} ; $U_{\text{output}} = U_{\text{battery}}$.

By use of the method according to the present invention, the power tool 300 can be made compact in size and light in weight at the same time as it is possible to provide a high productivity when using the tool.

The at least one control unit 331, 332 thus controls the output voltage U_{output} on the output DC bus 325 to switch between the battery voltage U_{battery} and the step-up voltage $U_{\text{step-up}}$; $U_{\text{battery}} \leq U_{\text{output}} \leq U_{\text{step-up}}$. The at least one control unit can determine the suitable output voltage U_{output} based on a number of parameters.

One such parameter is the level of the output voltage U_{output} itself, whereby the at least one control unit 331, 332 disables the step-up converter 310 and enables the bypass circuit 320 when the output voltage U_{output} is lower than a

voltage threshold $U_{threshold}$; $U_{output} < U_{threshold}$. As described above, the PWM circuit 317 can include an overload limiting function, which reduces the step-up voltage $U_{step-up}$ if the step-up converter 310 is overloaded. Thus, also low output voltage values; $U_{output} < U_{threshold}$; resulting from such step-up converter overload and the following step-up voltage $U_{step-up}$ reduction, can be utilized as a parameter to base control of the step-up converter 310 and/or bypass circuit 320 on.

Another such parameter is the output current I_{output} , whereby the at least one control unit 331, 332 disables the step-up converter 310 and enables the bypass circuit 320 when the output current I_{output} is higher than or equal to a current threshold $I_{threshold}$; $I_{output} \geq I_{threshold}$. The output current I_{output} can here (and in table 1 below) either correspond to the current on the output DC bus 325, or to a motor current I_{motor} , that is provided to, and measured at, the motor, i.e. between the inverter 305 and the motor. The motor current I_{motor} is normally already measured in power tools of today. Therefore, it adds very little complexity to use the motor current I_{motor} as the output current I_{output} parameter, since this parameter is today already available in power tools.

The motor current I_{motor} and the current on the output DC bus 325 can differ, since the motor current I_{motor} is dependent on the torque T that is provided by the tool, whereas the current on the output DC bus 325 is dependent on the electrical power that is provided to the inverter 305.

Some examples of the parameters and the conditions for the enabling/disabling signals for the step-up converter $S_{step-up_on/off}$ and/or for the bypass circuit $S_{bypass_on/off}$ based on different values for these parameters are shown in table 1.

In tables 1, 2 and 3 below, and in this document, $S_{bypass_on/off} = 1$ means that the bypass circuit 320 is enabled (S_{bypass_on}) and $S_{bypass_on/off} = 0$ means that the bypass circuit 320 is disabled (S_{bypass_off}). Correspondingly, $S_{step-up_on/off} = 1$ means that the 5 step-up converter 310 is enabled ($S_{step-up_on}$) and $S_{step-up_on/off} = 0$ means that the step-up converter 310 is disabled ($S_{step-up_off}$). Also, the tool trigger signal has the value 1 when the tool motor unit 303 is running and the value 0 when the motor unit 303 is not running. Thus, tool trigger = 0 means that the 10 motor unit is off and tool trigger = 1 means that the motor unit is on/activated.

$S_{bypass_on/off}$	$S_{step-up_on/off}$	U_{output}	I_{output}	Tool trigger
0	1	$U_{output} \geq U_{threshold}$	$I_{output} < I_{threshold}$	1
1	0	$U_{output} < U_{threshold}$	$I_{output} < I_{threshold}$	1
1	0	$U_{output} > U_{threshold}$	$I_{output} \geq I_{threshold}$	1
1	0	$U_{output} < U_{threshold}$	$I_{output} \geq I_{threshold}$	1
1	0	Ignored	Ignored	0

Table 1

15 The U_{output} and I_{output} values in the tables correspond to the voltage and current values on the output DC bus 325. Alternatively, the I_{output} values may correspond to the above mentioned motor current I_{motor} , as described above. As can be seen in table 1, one or more of these values U_{output} , I_{output} can 20 e.g. be used as conditions for triggering the one or more control units 331, 332 to enable the bypass circuit S_{bypass_on} and to disable the step-up converter $S_{step-up_off}$ when the output

voltage U_{output} on the DC-bus 325 drops below a preset value $U_{\text{threshold}}$ while the tool trigger is in condition on, i.e. when the tool 300 is activated. Also, the one or more control units 331, 332 can be triggered to enable the bypass circuit $S_{\text{bypass_on}}$ and disable the step-up converter $S_{\text{step-up_off}}$ when the output current I_{output} on the DC-bus 325 is higher than or equal to a preset value $I_{\text{threshold}}$ while the tool trigger is in condition on.

Another such parameter is the rotational speed ω_{motor} and torque T that is provided by the power tool 300, whereby the at least one control unit 331, 332 enables the step-up converter 310 and disables the bypass circuit 320 when the rotational speed ω_{motor} of the motor unit 303 multiplied with a torque T that is provided by the power tool 300; $\omega_{\text{motor}}*T$; is lower than the speed and torque threshold $\omega T_{\text{threshold}}$; $\omega_{\text{motor}}*T < \omega T_{\text{threshold}}$.

Examples of the parameters and the conditions for the enabling/disabling signals for the step-up converter $S_{\text{step-up_on/off}}$ and/or for the bypass circuit $S_{\text{bypass_on/off}}$ based on different values for this parameter are shown in table 2.

$S_{\text{bypass_on/off}}$	$S_{\text{step-up_on/off}}$	$\omega_{\text{motor}}*T$	Tool trigger
0	1	$\omega*T < \omega T_{\text{threshold}}$	1
1	0	$\omega*T \geq \omega T_{\text{threshold}}$	1
1	0	Ignored	0

Table 2

In table 2, ω is the rotational speed of the tool in rad/s and T is the torque in Nm that is provided by the tool.

As can be seen in table 2, the parameter values for $\omega_{\text{motor}}*T$ can be used as conditions for triggering the one or more control units 331, 332 to enable the bypass circuit $S_{\text{bypass_on}}$ and to

disable the step-up converter $S_{\text{step-up_off}}$ when $\omega^*T \geq \omega T_{\text{threshold}}$ while the tool trigger is in condition on, i.e. when the tool 300 is activated. Also, the one or more control units 331, 332 can be triggered to disable the bypass circuit $S_{\text{bypass_off}}$ and 5 enable the step-up converter $S_{\text{step-up_on}}$ when $\omega^*T < \omega T_{\text{threshold}}$ while the tool trigger is in condition on.

Another such parameter is the output power P_{output} on the output DC bus 325, whereby the at least one control unit 331, 332 10 enables the step-up converter 310 and disables the bypass circuit 320 when the output power P_{output} that is provided to said electrical motor unit 303 is lower than a power threshold $P_{\text{threshold}}$; $P_{\text{output}} < P_{\text{threshold}}$.

Examples of the parameters and the conditions for the 15 enabling/disabling signals for the step-up converter $S_{\text{step-up_on/off}}$ and/or for the bypass circuit $S_{\text{bypass_on/off}}$ based on different values for this parameter are shown in table 3.

$S_{\text{bypass_on/off}}$	$S_{\text{step-up_on/off}}$	P_{output}	Tool trigger
0	1	$P_{\text{output}} < P_{\text{threshold}}$	1
1	0	$P_{\text{output}} \geq P_{\text{threshold}}$	1
1	0	Ignored	0

Table 3

20

Here, the output power P_{output} on the output DC bus 325 can be calculated as $P_{\text{output}} = I_{\text{output}} * U_{\text{output}}$ on the output DC bus 325.

As can be seen in table 3, the parameter values for the output 25 power P_{output} can be used as conditions for triggering the one or more control units 331, 332 to enable the bypass circuit $S_{\text{bypass_on}}$ and to disable the step-up converter $S_{\text{step-up_off}}$ when $P_{\text{output}} \geq P_{\text{threshold}}$ while the tool trigger is in condition on. Also, the one or more control units 331, 332 can be triggered

to disable the bypass circuit S_{bypass_off} and enable the step-up converter $S_{step-up_on}$ when $P_{output} < P_{threshold}$ while the tool trigger is in condition on.

5 According to an embodiment, the at least one control unit 331, 332 can base the enabling/disabling signals for the step-up converter $S_{step-up_on/off}$ and/or for the bypass circuit $S_{bypass_on/off}$ on a combination of two or more of these parameters, i.e. on two or more of the output voltage U_{output} , the output current 10 I_{output} , the rotational speed ω_{motor} and torque T , and the output power P_{output} .

15 Figure 4 schematically illustrates a non-limiting example describing a possible use of the present invention, which could correspond e.g. to a tool use including tightening of a nut. Figure 5 shows a flow sheet diagram for the corresponding 20 method according to an embodiment of the invention.

In a first step 501 of the method, the power tool 300 is activated, i.e. the tool trigger has the value 1. In figure 4, 25 this happens at the position "Tool trigger" along the time axis.

In a second step 502, the step-up converter 310 is enabled $S_{step-up_on/off} = 1$ and the bypass circuit 320 is disabled $S_{bypass_on/off} = 0$. The first phase of the tool activation is thereby started, wherein the higher step-up voltage $U_{step-up}$ is provided to the electrical motor unit 303 as an output voltage U_{output} on the output DC bus 325 (curve 2 in figure 4); $U_{output}=U_{step-up}$. Hereby, the rotational speed ω_{motor} of the motor unit 303 is increased (curve 1 in figure 4) as a result of the higher step-up voltage $U_{step-up}$ that is input to the motor unit 303. Also, the output current I_{output} and/or the torque T (curve 30 3 in figure 4) is slightly increased. Thus, during the first

phase, where the step-up converter is enabled /turned on, an increased rotational speed ω_{motor} can be achieved by the present invention, which means that the nut can be quickly tightened during a phase where not too much torque is needed for the

5 tightening.

In a third step 503, the bypass circuit 320 is enabled $S_{bypass_on/off} = 1$ and the step-up converter 310 is disabled $S_{step-up_on/off} = 0$ during the second phase of the activation. The

10 battery voltage $U_{battery}$ is thereby provided to the electrical motor unit 303 as an output voltage U_{output} (curve 2 in figure 4); $U_{output}=U_{battery}$. Hereby, the rotational speed ω_{motor} of the motor unit 303 is decreased (curve 1 in figure 4) as a result of the lower battery voltage $U_{battery}$ that is input to the motor

15 unit 303, and also due to the increased resistance of the nut because of the higher torque needed. Also, the output current I_{output} and/or the torque T (curve 3 in figure 4) is increased. Thus, during the second phase, where the bypass circuit is

20 enabled, an increased torque can be achieved by the present invention during the second phase where a high torque T is needed for the tightening.

According to another embodiment of the present invention, the power tool 300 is arranged for providing a high torque T during a first activation phase, and a high rotational speed ω_{motor} during a second activation phase. This embodiment can be particularly useful e.g. for loosening of nuts, where a high torque T is needed for the first actual loosening phase and a high speed ω_{motor} and low torque T is needed for the second

25 phase, when the nut is already loosened. This embodiment is achieved by enabling the bypass circuit 320 $S_{bypass_on/off} = 1$ and disabling the step-up converter 310 $S_{step-up_on/off} = 0$ during the first phase of the activation. The battery voltage $U_{battery}$ is

thereby provided to the electrical motor unit 303 as an output voltage U_{output} , whereby high torque T and low speed ω_{motor} is provided.

Thereafter, the step-up converter 310 is enabled $S_{\text{step-up_on/off}} = 1$ and the bypass circuit 320 is disabled $S_{\text{bypass_on/off}} = 0$ during the second phase, whereby the higher step-up voltage $U_{\text{step-up}}$ is provided to the electrical motor unit 303 as an output voltage U_{output} on the output DC bus 325. Thus, a low torque T and high speed ω_{motor} is provided during the second phase.

According to another embodiment of the present invention, the bypass circuit 320 is enabled and the step-up converter 310 is disabled during retardation, i.e. deceleration, of the rotational speed of the power tool. Thus, when the rotational speed of the electrical motor unit 303 is quickly slowing

down, the electrical motor unit 303 is coupled directly to the battery unit 304 and not to the step-up converter 310. Hereby, the rotational energy of the electrical motor unit 303 and of the spindle/shaft 102, that is set free during the retardation, can be converted to electrical energy and can be utilized for charging the battery unit 304. For example, when the battery unit 304 includes one or more super capacitors, the electrical energy that is extracted from the rotational energy made free during the retardation can be used for charging the super capacitors.

The power tool of the invention can be adapted to perform any of the steps of the method of the invention. The different steps of the method of the invention described above can be combined or performed in any suitable order.

The method of the invention can implemented by a computer program, having code means, which when run in a computer causes the computer to execute the steps of the method. The

computer program is included in a computer readable medium of a computer program product. The computer readable medium may consist of essentially any memory, such as a ROM (Read-Only Memory), a PROM (Programmable Read-Only Memory), an EPROM 5 (Erasable PROM), a Flash memory, an EEPROM (Electrically Erasable PROM), or a hard disk drive.

The power tool and the methods according to the invention may be modified by those skilled in the art, as compared to the exemplary embodiments described above.

10 As is obvious for a skilled person, a number of other implementations, modifications, variations and/or additions can be made to the above described exemplary embodiments. It is to be understood that the invention includes all such other implementations, modifications, variations and/or additions 15 which fall within the scope of the claims.

Claims

1. A power tool (300) comprising an electrical motor unit (303) that is connectable to a battery unit (304);

characterized in that

5 - a step-up converter (310) is connectable between said battery unit (304) and said electrical motor unit (303), which is arranged for converting, when enabled, a battery voltage $U_{battery}$ that is provided to said step-up converter (310) by said battery unit (304) to a higher step-up voltage $U_{step-up}$; $U_{step-up} > U_{battery}$; said step-up voltage $U_{step-up}$ being provided to said

10 electrical motor unit (303) as an output voltage U_{output} ; $U_{output}=U_{step-up}$;

- a bypass circuit (320) is arranged in parallel with said step-up converter (310) and connects, when enabled, said

15 battery unit (304) to said electrical motor unit (303) and provides said battery voltage $U_{battery}$ to said electrical motor unit (303) as an output voltage U_{output} ; $U_{output}=U_{battery}$; and

- at least one control unit (331, 332) is arranged for controlling said step-up converter (310) and said bypass

20 circuit (320) such that said output voltage U_{output} may be switched between said battery voltage $U_{battery}$ and said step-up voltage $U_{step-up}$.

2. Power tool (300) as claimed in claim 1, wherein said

25 step-up converter (310) is a synchronous step-up converter

including at least one step-up transistor (311), at least one inductor (313), and at least one step-up switch (312).

3. Power tool (300) as claimed in claim 2, wherein said

step-up converter (310) includes a step-up control circuitry (316, 317) being arranged for controlling said at least one

30 step-up transistor (311) and said at least one step-up switch

(312) connecting said step-up converter (310) to said electrical motor unit (303) when being enabled.

4. Power tool (300) as claimed in claim 3, wherein said step-up control circuitry (316, 317) includes a voltage regulation circuitry (316) being arranged for controlling said higher voltage $U_{\text{step-up}}$ towards a target voltage U_{target} and having an output (325) of said step-up converter (310) as an input.

5 5. Power tool (300) as claimed in anyone of claims 1-4, wherein said bypass circuit (320) includes a bypass switch 10 (321) being controlled by said at least one control unit (331).

10 6. Power tool (300) as claimed in claims 3 or 5, wherein one or more of said at least one step-up switch (312), said step-up transistor 311, and said bypass switch (321) are 15 implemented as anyone in the group of: -
an N-channel MOSFET (Metal Oxide Semiconductor Field Effect Transistor); and -
an P-channel MOSFET (Metal Oxide Semiconductor Field Effect Transistor).

20 7. Power tool (300) as claimed in anyone of claims 1-6, wherein said at least one control unit (331, 332) is arranged for providing said bypass circuit (320) with a bypass enabling/disabling signal $S_{\text{bypass_on/off}}$, said bypass circuit (320) being arranged for enabling/disabling the connection of said 25 battery unit (304) to said electrical motor unit (303) based on said bypass enabling/disabling signal $S_{\text{bypass_on/off}}$.

30 8. Power tool (300) as claimed in anyone of claims 1-7, wherein said at least one control unit (331, 332) is arranged for providing said step-up converter with a step-up enabling/disabling signal $S_{\text{step-up_on/off}}$, said step-up converter

(310) being arranged for enabling/disabling the voltage conversion of said step-up converter (310) based on said step-up enabling/disabling signal $S_{\text{step-up_on/off}}$.

9. Power tool (300) as claimed in claims 7 or 8, wherein said at least one control unit (331, 332) is arranged to base said step-up enabling/disabling signal $S_{\text{step-up_on/off}}$ and/or said bypass enabling/disabling signal $S_{\text{bypass_on/off}}$ on a relation between said output voltage U_{output} and a voltage threshold $U_{\text{threshold}}$.

10. Power tool (300) as claimed in claim 9, wherein said at least one control unit (331, 332) is arranged for generating a step-up enabling signal $S_{\text{step-up_on}}$ and a bypass disabling signal $S_{\text{bypass_off}}$ when said output voltage U_{output} is equal to or higher than said voltage threshold $U_{\text{threshold}}$; $U_{\text{output}} \geq U_{\text{threshold}}$.

15. Power tool (300) as claimed in claims 7 or 8, wherein said at least one control unit (331, 332) is arranged to base said step-up enabling/disabling signal $S_{\text{step-up_on/off}}$ and/or said bypass enabling/disabling signal $S_{\text{bypass_on/off}}$ on a relation between an output current I_{output} being provided to said motor unit (303) and a current threshold $I_{\text{threshold}}$.

20. Power tool (300) as claimed in claim 11, wherein said at least one control unit (331, 332) is arranged for generating a step-up disabling signal $S_{\text{step-up_off}}$ and a bypass enabling signal $S_{\text{bypass_on}}$ when said output current I_{output} is equal to or higher than said current threshold $I_{\text{threshold}}$; $I_{\text{output}} \geq I_{\text{threshold}}$.

25. Power tool (300) as claimed in claims 7 or 8, wherein said at least one control unit (331, 332) is arranged to base said step-up enabling/disabling signal $S_{\text{step-up_on/off}}$ and/or said bypass enabling/disabling signal $S_{\text{bypass_on/off}}$ on a relation between a rotational speed ω_{motor} of said motor unit (303)

multiplied with a torque T being provided by said tool (300); $\omega_{motor} \cdot T$; and a speed and torque threshold $\omega T_{threshold}$.

14. Power tool (300) as claimed in claim 13, wherein said at least one control unit (331, 332) is arranged for generating a step-up enabling signal $S_{step-up_on}$ and a bypass disabling signal S_{bypass_off} when said rotational speed ω_{motor} multiplied with said torque T ; $\omega_{motor} \cdot T$; is lower than said speed and torque threshold $\omega T_{threshold}$; $\omega_{motor} \cdot T < \omega T_{threshold}$.

15. Power tool (300) as claimed in claims 7 or 8, wherein said at least one control unit (331, 332) is arranged to base said step-up enabling/disabling signal $S_{step-up_on/off}$ and/or said bypass enabling/disabling signal $S_{bypass_on/off}$ on a relation between an output power P_{output} being provided to said electrical motor unit (303) and a power threshold $P_{threshold}$.

16. Power tool (300) as claimed in claim 15, wherein said at least one control unit (331, 332) is arranged for generating a step-up enabling signal $S_{step-up_on}$ and a bypass disabling signal S_{bypass_off} when said output power P_{output} is lower than said power threshold $P_{threshold}$; $P_{output} < P_{threshold}$.

17. Power tool (300) as claimed in anyone of claims 7-16, wherein said bypass enabling/disabling signal $S_{bypass_on/off}$ and said step-up enabling/disabling signal $S_{step-up_on/off}$ are complementary signals.

18. Power tool (300) as claimed in anyone of claims 1-17, wherein said step-up converter (310) includes two step-up transistor circuits being operated in mutually opposite phases.

19. Power tool (300) as claimed in any one of claims 1-18, wherein said step-up converter (310) and said bypass circuit (320) are arranged integrated within a body of said power tool

(300), said step-up converter (310) and said bypass circuit (320) being connected to said motor unit (303) and being connectable to said battery unit (304).

20 Power tool (300) as claimed in any one of claims 1-18
5 wherein said step-up converter (310) and said bypass circuit (320) are arranged integrated with and connected to said battery unit (304), and are connectable to said motor unit (303).

10 21. Power tool (300) as claimed in any one of claims 1-18,
wherein said step-up converter (310) and said bypass circuit (320) are arranged separately between said battery unit (304) and said motor unit (303), said step-up converter (310) and said bypass circuit (320) being connectable to said battery unit (304) and to said motor unit (303).

15 22. Power tool (300) as claimed in any one of claims 1-21,
wherein said battery unit (304) includes at least one super capacitor.

20 23. Power tool (300) as claimed in any one of claims 1-22,
wherein said power tool (300) includes a brake chopper arranged for consuming energy provided by said electrical motor unit (303) when a rotational speed of said electrical motor unit (303) is reduced.

25 24. Method for providing an electrical motor unit (303) of a power tool (300) with an output voltage U_{output} ; **characterized**

by

- converting, when a step-up converter (310) that is connectable between a battery unit (304) and said electrical motor unit (304) is enabled, a battery voltage U_{battery} that is provided to said step-up converter (310) by said battery unit (304) to a higher step-up voltage $U_{\text{step-up}}$; $U_{\text{step-up}} > U_{\text{battery}}$; and

providing said step-up voltage $U_{\text{step-up}}$ to said electrical motor unit (303) as an output voltage U_{output} ; $U_{\text{output}}=U_{\text{step-up}}$;

- connecting, when a bypass circuit (320) that is arranged in parallel with said step-up converter (310) is enabled, said battery unit (304) to said electrical motor unit (303), and providing said battery voltage U_{battery} to said electrical motor unit (303) as an output voltage U_{output} ; $U_{\text{output}}=U_{\text{battery}}$; and

- controlling, by use of at least one control unit (331, 332), said step-up converter (310) and said bypass circuit (320) such that said output voltage U_{output} may be switched between said battery voltage U_{battery} and said step-up voltage $U_{\text{step-up}}$.

25. Method as claimed in claim 24, wherein said at least one control unit (331, 332) disables the step-up converter (310) and enables said bypass circuit (320) when said output voltage U_{output} is lower than a voltage threshold $U_{\text{threshold}}$; $U_{\text{output}} < U_{\text{threshold}}$.

26. Method as claimed in claim 24, wherein said at least one control unit (331, 332) disables said step-up converter (310) and enables said bypass circuit (320) when an output current I_{output} is higher than or equal to a current threshold $I_{\text{threshold}}$; $I_{\text{output}} \geq I_{\text{threshold}}$.

27. Method as claimed in claim 24, wherein said at least one control unit (331, 332) enables said step-up converter (310) and disables said bypass circuit (320) when a rotational speed ω_{motor} of said motor unit (303) multiplied with a torque T that is provided by said power tool (300); $\omega_{\text{motor}} \cdot T$; is lower than said speed and torque threshold $\omega T_{\text{threshold}}$; $\omega_{\text{motor}} \cdot T < \omega T_{\text{threshold}}$.

28. Method as claimed in claim 24, wherein said at least one control unit (331, 332) enables said step-up converter (310) and disables said bypass circuit (320) when an output power

P_{output} that is provided to said electrical motor unit (303) is lower than a power threshold $P_{threshold}$; $P_{output} < P_{threshold}$.

29. Method as claimed in anyone of claims 24-28, wherein an activation of said power tool (300) includes:

- 5 - enabling said step-up converter (310) and disabling said bypass circuit (320) during a first phase of said activation, thereby providing said step-up voltage $U_{step-up}$ to said electrical motor unit (303) as an output voltage U_{output} ; $U_{output}=U_{step-up}$; whereby a rotational speed ω_{motor} of said motor unit (303) is increased as a result of the higher step-up voltage $U_{step-up}$;
- 10 - enabling said bypass circuit (320) and disabling said step-up converter (310) during a second phase of said activation, thereby providing said battery voltage $U_{battery}$ to said electrical motor unit (303) as an output voltage U_{output} ; $U_{output}=U_{battery}$; whereby said rotational speed ω_{motor} of said motor unit (303) is decreased as a result of the lower battery voltage $U_{battery}$.

30. Computer program, characterized in code means, which when run in a computer causes the computer to execute the method according to any of the claims 24-29.

31. Computer program product including a computer readable medium and a computer program according to claim 30, wherein said computer program is included in the computer readable medium.

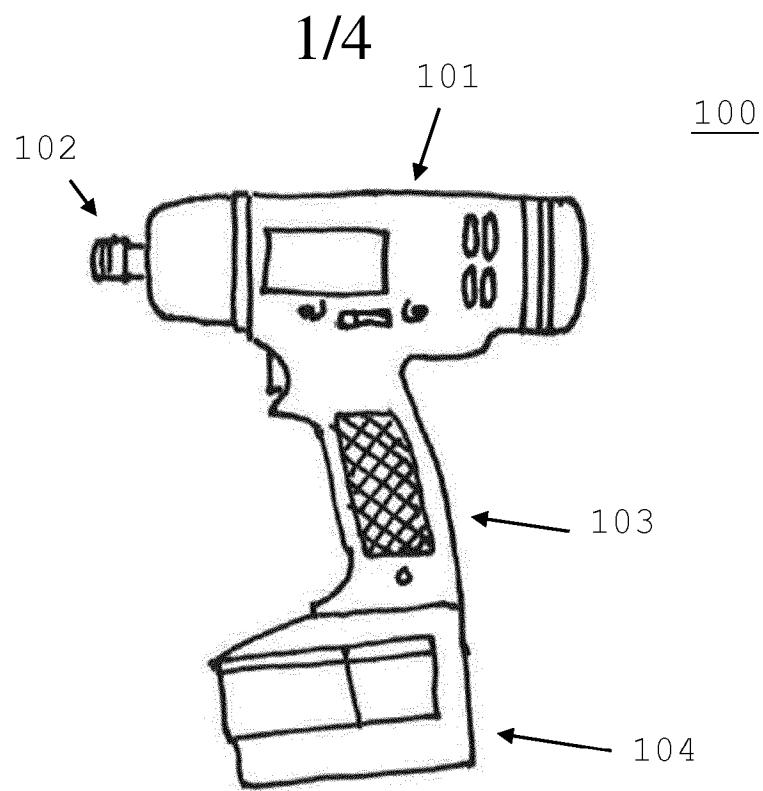


Fig. 1 (Prior Art)

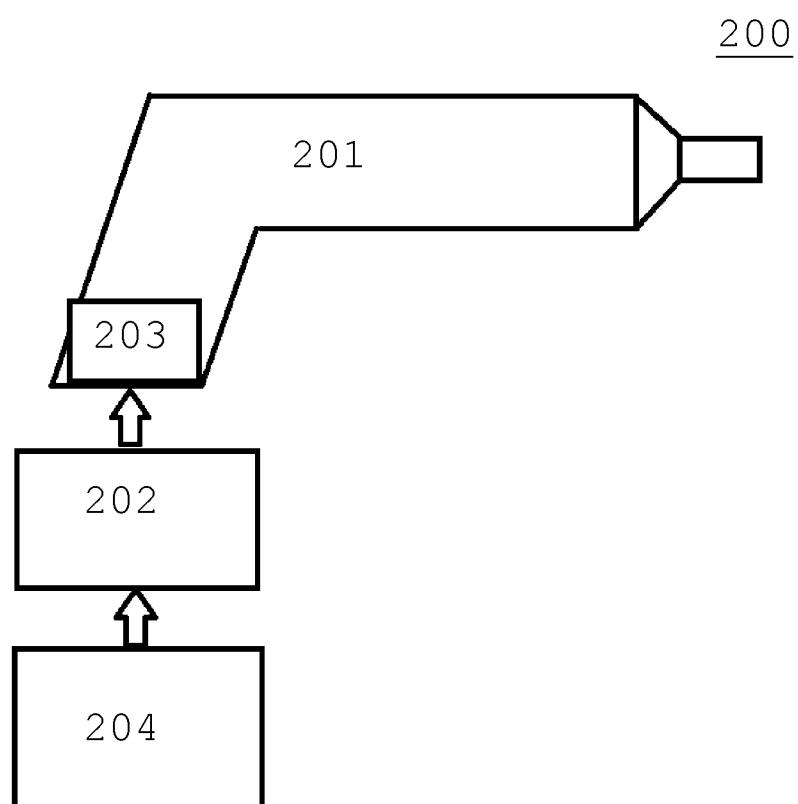


Fig. 2

2/4

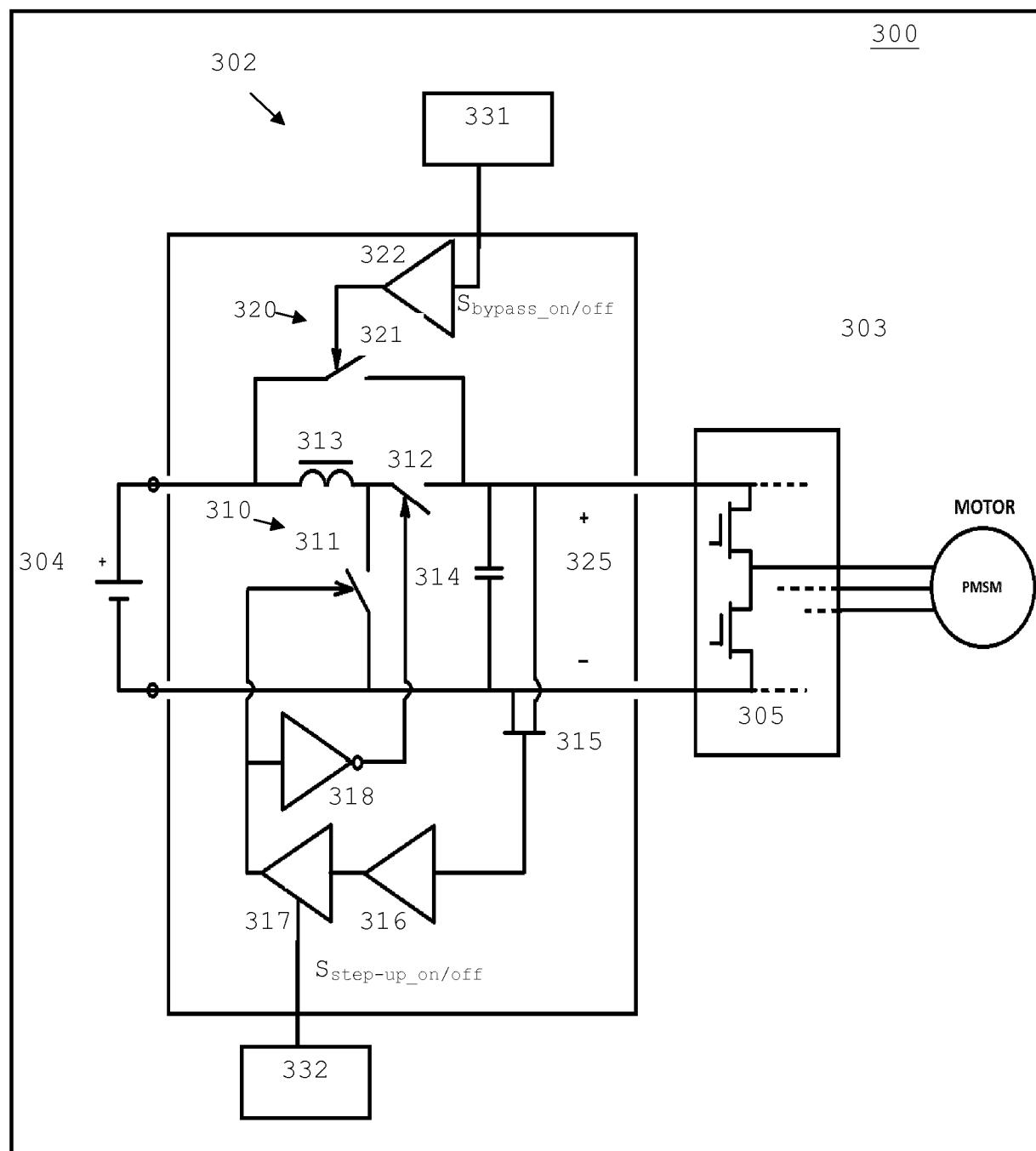


Fig. 3

3/4

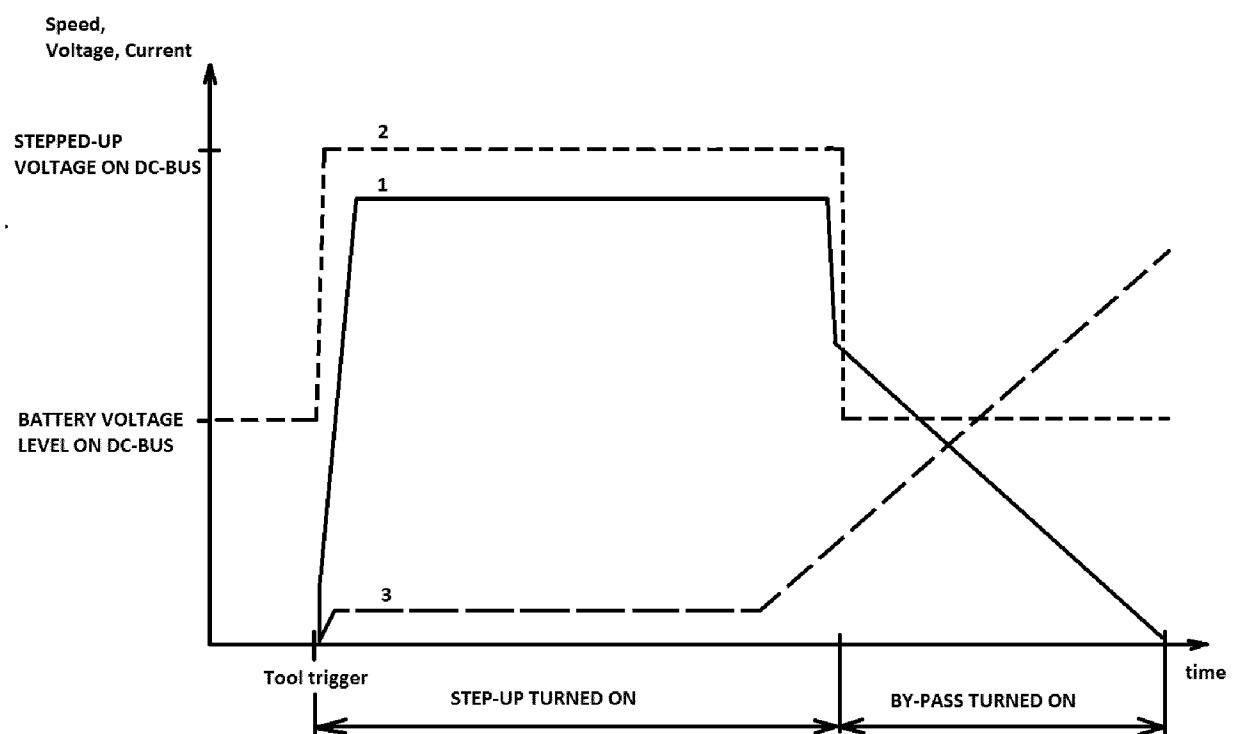


Fig. 4

4/4

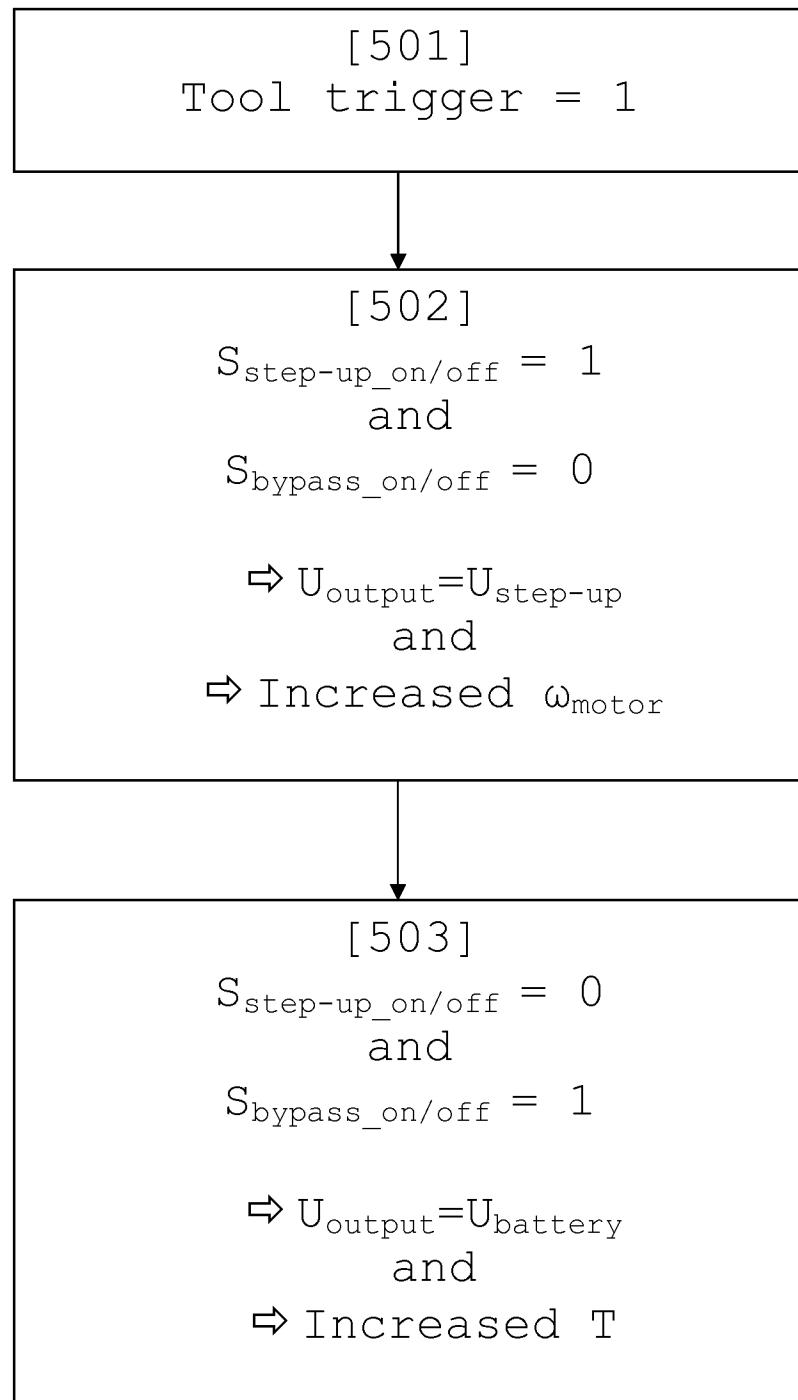


Fig. 5