



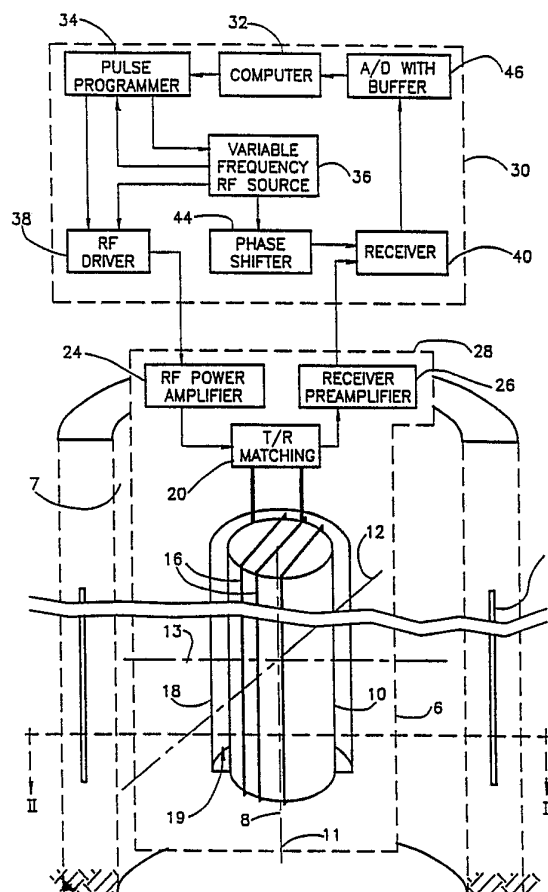
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(54) Title: APPARATUS AND TECHNIQUE FOR NMR DIFFUSION MEASUREMENT

(57) Abstract

A method for conducting borehole NMR measurements comprising the steps of providing a magnetic field and a magnetic field gradient (G) at a desired location along a borehole (107); carrying out at least one NMR experiment in the presence of the magnetic field gradient (G); sensing the diffusion effect on the decay of at least the first echo; and determining therefrom the diffusion coefficient (32).



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APPARATUS AND TECHNIQUE FOR
NMR DIFFUSION MEASUREMENT

FIELD OF THE INVENTION

The present invention relates to borehole
measurements and more particularly to borehole
5 measurements employing nuclear magnetic resonance.

BACKGROUND OF THE INVENTION

There are known in the patent literature
various techniques for carrying out borehole
10 measurements employing NMR. Particularly useful
techniques and apparatus for carrying out such
techniques are described in U.S. Patents 4,710,713 and
4,717,878 of the present assignee. U.S. Patent
4,933,638 describes a technique which is based
15 thereon.

It is known to carry out laboratory tests of
the self-diffusion coefficient, i.e., the rate at
which molecules of a material randomly travel within
20 the bulk of the same material, on cores. Providing
the cores for testing is a very expensive and time
consuming process and is not suitable for sampling a
large extent of a borehole.

A representative listing of relevant
25 publications in this field is set forth hereinbelow:

J.H. Simpson and H.Y. Carr, Diffusion and
Nuclear Spin Relaxation in Water, The Physical Review,
111, No. 5, Sept 1, 1958, p 1201 ff.

D.C. Douglass and D.W. McCall, Diffusion in
30 Paraffin Hydrocarbons, Journal of Physical Chemistry,
62, 1102 (1958);

D.E. Woessner, N.M.R. Spin Echo Self
Diffusion Measurements on Fluids Undergoing
Restricted Diffusion, Journal of Physical Chemistry,
35 87, 1306 (1963);

R.C. Wayne and R. M. Cotts, Nuclear Magnetic Resonance Study of Self-Diffusion in a Bounded Medium, Physical Review, 151, No. 1, 4 November, 1964;

E. O. Stejskal and J.E. Tanner, Spin
5 Diffusion Measurements: Spin Echoes in the Presence of
a Time Dependent Field Gradient, The Journal of
Chemical Physics, Vol. 42, No. 1, 288-292, 1 January,
1965.

K.J. Packer and C. Rees, Pulsed NMR Studies
10 of Restricted Diffusion, Journal of Colloid and
Interface Science, Vol. 40, No. 2, August, 1972;

C.H. Neuman, Spin echo of spins diffusing in
a bounded medium, The Journal of Chemical Physics,
Vol. 60, No. 11, 1 June, 1974;

15 W.D. Williams, E.F.W. Seymour and R. M.
Cotts, A Pulsed Gradient Multiple-Spin Echo NMR
Technique for Measuring Diffusion in the Presence of
Background Magnetic Field Gradients, Journal of
Magnetic Resonance 31, 271 - 282, (1978);

20 U.S. Patent 4,719,423 describes NMR imaging
of materials for transport properties including
diffusion coefficients. This patent relates to
imaging of core samples and not in situ;

P.T. Callaghan, D. Macgowan, K.J. Packer and
25 F.O. Zelaya, High Resolution q-space Imaging in Porous
Structure, submitted for publication in the Journal of
Magnetic Resonance, 1990;

U.S. Patent 4,350,955 of J.A. Jackson et al.
and other publications of J.A. Jackson on the same
30 general subject.

SUMMARY OF THE INVENTION

The present invention seeks to provide a
technique and apparatus for conducting borehole NMR
35 measurements of self-diffusion coefficient and the
intrinsic transverse relaxation time.

There is thus provided in accordance with a preferred embodiment of the present invention a technique for conducting borehole NMR measurements including the steps of providing a magnetic field gradient at a desired location along a borehole, carrying out at least one and preferably two or more NMR experiments in the presence of the magnetic field gradient, sensing the diffusion effect on the decay of at least the first echo and determining therefrom the diffusion coefficient.

In accordance with one embodiment of the invention, the magnetic field gradient is constant over time. Alternatively a switched magnetic field gradient may be provided.

In accordance with one embodiment of the invention the step of carrying out at least one NMR experiment includes carrying out two NMR experiments such that they differ in at least one of the following parameters: 1. the time the molecules are allowed to diffuse, 2. the magnitude of the magnetic field gradient and 3. the time over which the pulses are applied if magnetic field gradient pulses are used.

More particularly, the two experiments may differ only in the echo spacing. In such case, the T_2 (transverse relaxation time) and D (diffusion coefficient) can be extracted from the measured amplitudes and decay rates.

Alternatively, when the gradients are constant and are themselves a function of the magnetic field strength, the two experiments may differ in the applied RF frequency. The difference in frequency is accompanied by a change in the magnetic field gradient strength.

In an extension of the above-described technique, more than two such experiments can be conducted. Results of repeated experiments can then be integrated and averaged to enhance the

signal-to-noise ratio and the two or more different experiments may be used for calculating the Diffusion Coefficient and the transverse relaxation time T_2 .

In another extension, several such
5 experiments might all be combined into a single experiment by acquiring all the required data from the signals of a single excitation. This can be accomplished by changing the above mentioned parameters during a single sequence. As an
10 illustrative example: the first few echoes are spaced by one fixed time interval, the next few by another, and so on.

A single experiment with fixed parameters such as echo spacing, magnetic field gradient
15 magnitude and duration may be carried out to give an upper bound to the diffusion coefficient value, a lower bound to T_2 or either T_2 or D when one of them is known a priori.

In accordance with a preferred embodiment of
20 the present invention, the diffusion coefficient D can be employed to determine at least one of the following petrophysical parameters:

Water/hydrocarbon discrimination;
Water and hydrocarbon saturation levels;
25 Permeability;
Pore size and pore size distribution;
Oil viscosity;
Formation form factor F , which is a measure of the average increase in electrical resistance due
30 to the formation tortuosity; and
q-space imaging of the formation.

There is also provided in accordance with an embodiment of the present invention apparatus for
conducting borehole NMR measurements comprising:
35 apparatus for providing a magnetic field gradient at a desired location along a borehole;

apparatus for carrying out at least one NMR experiment in the presence of the magnetic field gradient;

apparatus for sensing the diffusion effect
5 on the decay of at least the first echo; and

apparatus for determining therefrom the diffusion coefficient.

There is also provided in accordance with an embodiment of the invention apparatus for conducting
10 borehole NMR measurements comprising:

apparatus for applying a static magnetic field to polarize the nuclear spins in the material at a given region of the borehole, thus creating bulk magnetization at the region of interest;

15 apparatus for applying an RF field to the region of interest at a preselected frequency, duration and magnitude in order to cause at least part of the magnetization to lie in a horizontal plane, defined relative to the plane of the borehole;

20 apparatus for applying a fixed magnetic field gradient to the region of interest, thereby causing the atoms and molecules of the material in the region of interest to diffuse;

apparatus for applying a refocusing RF pulse
25 to the region of interest;

apparatus for again applying a fixed magnetic field gradient to the region of interest, thereby causing the atoms and molecules of the material in the region of interest to diffuse;

30 apparatus for acquiring the NMR spin echo; and

apparatus for deriving the diffusion coefficient D or the spin echo decay T_2 from the echo amplitudes.

35 There is also provided in accordance with an embodiment of the invention apparatus for conducting borehole NMR measurements comprising:

apparatus for applying a static magnetic field to polarize the nuclear spins in the material at a given region of the borehole, thus creating bulk magnetization at the region of interest;

5 apparatus for applying an RF field to the region of interest at a preselected frequency, duration and magnitude in order to cause at least part of the magnetization to lie in a horizontal plane, defined relative to the plane of the borehole;

10 apparatus for applying a time switched magnetic field gradient to the region of interest, thereby causing the atoms and molecules of the material in the region of interest to diffuse;

 apparatus for applying a refocusing RF pulse
15 to the region of interest;

 apparatus for again applying a fixed magnetic field gradient to the region of interest, thereby causing the atoms and molecules of the material in the region of interest to diffuse;

20 apparatus for acquiring the NMR spin echo;
and

 apparatus for deriving the diffusion coefficient D or the spin echo decay T_2 from the echo amplitudes.

25 The methods described hereinabove are suitable for use in environments other than borehole environments and with materials other than those found in boreholes. The methods have the advantage that the material being tested may be located outside the
30 testing apparatus.

BRIEF DESCRIPTION OF THE DRAWINGS

 The present invention will be understood and appreciated more fully from the following detailed
35 description, taken in conjunction with the drawings in which:

Fig. 1A is a block diagram illustration of apparatus for carrying out borehole diffusion coefficient determinations in accordance with a preferred embodiment of the present invention, wherein
5 the magnetic field gradient is constant over time;

Fig. 1B is a block diagram illustration of apparatus for carrying out borehole diffusion coefficient determinations in accordance with an alternative embodiment of the present invention,
10 wherein the magnetic field gradient is pulsed.

Figs. 2A and 2B are illustrations of RF pulses and echoes and Magnetic Field Gradient Sequences respectively which are employed in accordance with one embodiment of the present
15 invention;

Figs. 3A and 3B are illustrations of RF pulses and echoes and Magnetic Field Gradient Sequences respectively which are employed in accordance with one embodiment of the present
20 invention.

DETAILED DESCRIPTION OF A PREFERRED EMBODIMENT

Reference is now made to Fig. 1A, which illustrates, in relatively general form, apparatus for
25 carrying out NMR borehole diffusion coefficient determinations in accordance with a preferred embodiment of the present invention. The apparatus includes a first portion 6, which is arranged to be lowered into a borehole 7 having a borehole
30 longitudinal axis 8 in order to examine the nature of materials in the vicinity of the borehole lying in a region 9 of generally cylindrical configuration spaced from and surrounding the borehole.

The first portion 6 preferably comprises a
35 generally cylindrical permanent magnet 10, preferably having a circular cross section and arranged along a permanent magnet longitudinal axis 11 which is

preferably coaxial with the longitudinal axis 8 of the borehole. According to an alternative embodiment of the invention a plurality of permanent magnets 10 may be employed. Through the specification, the one or
5 more permanent magnets 10 will be considered together and referred to as permanent magnet 10 and their common longitudinal axis will be identified as longitudinal axis 11.

The first portion 6 also comprises one or
10 more coil windings 16 which preferably are arranged on the permanent magnet surface such that each coil turn lies in a plane substantially parallel to a plane containing permanent magnet magnetization axis 12 and longitudinal axis 11. Specifically, the axis 13 of
15 the coil windings 16 is substantially perpendicular to both longitudinal axis 11 of the borehole and axis 12 of the permanent magnet magnetization.

The permanent magnet 10 and coil windings 16 are preferably housed in a non-conductive,
20 non-ferromagnetic protective housing 18. The housing and its contents hereinafter will be referred to as a probe 19.

The coil windings 16, together with a transmitter/receiver (T/R) matching circuit 20 define
25 a transmitter/receiver (T/R) circuit. T/R matching circuit 20 typically includes a resonance capacitor, a T/R switch and both to-transmitter and to-receiver matching circuitry and is coupled to a RF power amplifier 24 and to a receiver preamplifier 26.

30 All of the elements described hereinabove are normally contained in a housing 28 which is passed through the borehole. Alternatively some of the above elements may not be contained in the housing 28 and may be located above ground.

35 Indicated by block 30 is control circuitry for the logging apparatus including a computer 32, which provides a control output to a pulse programmer

34 which receives an RF input from a variable frequency RF source 36. Pulse programmer 34 controls the operation of the variable frequency RF source 36 as well as an RF driver 38, which receives an input
5 from variable frequency RF source 36 and outputs to RF power amplifier 24.

The output of RF receiver preamplifier 26 is supplied to an RF receiver 40 which receives an input from a phase shifter 44. Phase shifter 44 receives an
10 input from variable frequency RF source 36. Receiver 40 outputs via an A/D converter with a buffer 46 to computer 32 for providing desired well logging output data for further use and analysis.

Some or all of the elements described
15 hereinabove as being in block 30 are preferably disposed downhole. Alternatively such elements may be disposed in an above-ground housing.

Reference is now made to Fig. 1B, which illustrates, in relatively general form, apparatus for
20 carrying out NMR borehole diffusion coefficient determinations in accordance with an alternative preferred embodiment of the present invention. The apparatus includes a first portion 106, which is arranged to be lowered into a borehole 107 in order to
25 examine the nature of materials in the vicinity of the borehole.

The first portion 106 comprises a magnet or a plurality of magnets 108 which generate a preferably substantially uniform static magnetic field in a
30 volume of investigation 109. The first portion 106 also comprises an RF antenna coil 116 which produces an RF magnetic field at the volume of investigation 109 which field is substantially perpendicular to the static magnetic field.

35 A magnetic field gradient coil, or plurality of coils, 110 generates a magnetic field gradient at the volume of investigation 109. This additional

contribution to the magnetic field has a field direction preferably collinear with the substantially uniform field and has a substantially uniform magnetic field gradient, which may or may not be switched on
5 and off by switching the dc current flowing through the coil or coils 110. The magnet or magnets 108, antenna 116 and the gradient coil 110 constituting portion 106 are also referred to as a probe.

The antenna together with a
10 transmitter/receiver (T/R) matching circuit 120 typically include a resonance capacitor, a T/R switch and both to-transmitter and to-receiver matching circuitry and are coupled to an RF power amplifier 124 and a receiver preamplifier 126.

15 A power supply 129 provides the dc current required for the magnetic field gradient generating coils 110.

All the elements described hereinabove are normally contained in a housing 128 which is passed
20 through the borehole. Alternatively, some of the above elements may be located above ground.

Indicated in a block 130 is control circuitry for the logging apparatus which may be generally identical to that described above with
25 reference to block 30 in connection with the embodiment of Fig. 1A, with the addition of a pulse programmer 146.

Pulse programmer 146 controls the gradient coil power supply 129 enabling and disabling the flow
30 of current, and hence the generation of field gradients, according to the commands of the computer 32.

Some or all of the elements described hereinabove as being disposed in an above-ground
35 housing, may instead be disposed below ground.

Reference is now made to Figs. 2A and 2B which illustrate RF pulses and echoes and Magnetic

Field Gradient Sequences respectively which are employed in accordance with one embodiment of the present invention. In this embodiment of the invention, the following operational steps take place:

5 1. A static magnetic field is applied to polarize the nuclear spins in the material at a given region of the borehole, thus creating bulk magnetization at the region of interest. The field and the collinear magnetization thus produced define a
10 vertical direction.

 2. A magnetic field gradient is applied at the region of interest. This gradient field might or might not be part of the static magnetic field of the first step.

15 3. An RF field is applied to the region of interest at a preselected frequency, duration and magnitude in order to cause at least part of the magnetization to lie in a horizontal plane, defined relative to the vertical axis.

20 4. A time interval t through which atoms and molecules of the material in the region of interest may diffuse within a fixed magnetic gradient field.

 5. A refocusing RF pulse is applied to the
25 region of interest.

 6. Step 4 is repeated.

 7. The NMR spin echo is acquired.

 8. The diffusion coefficient D or an upper
30 bound thereof, or the spin echo decay T_2 , or a lower bound thereof is derived from the echo amplitude.

 9. Steps 1 through 7 are repeated at least once, with different t or magnetic field gradient strength.

35 10. D and/or T_2 are derived from echo amplitudes of some or all of the experiments.

It is appreciated that steps 4 through 7 may be repeated multiple times successively in order

to obtain a sufficiently long echo amplitude train, from which the transverse relaxation time may more meaningfully be derived.

It is further appreciated that step 8 is not required if both D and T_2 are unknown and neither could be considered as dominating the decay rate. Steps 9 and 10 are not required if either D or T_2 is known. In that case, the unknown T_2 or D can be derived from a single experiment. Likewise, no more than one experiment is required when either D or T_2 is known to substantially dominate the decay of the echo amplitude.

The advantage of repeating the experiment and integrating the measurement readings in order to obtain statistically valid and meaningful results is also appreciated.

It is also recognized that step 5 might alternatively be replaced by application of two or more pulses whose combined effect is the refocusing of the nuclear spins yielding a stimulated echo at step 7 and allowing more time for diffusion in between these pulses.

Reference is now made to Figs. 3A and 3B which illustrate RF pulses and echoes and Magnetic Field Gradient Sequences respectively, which are employed in accordance with another embodiment of the present invention. In this embodiment of the invention, the following operational steps take place:

1. Step 1 described above.
2. Step 3 described above.
3. A time switched magnetic field gradient pulse is applied through which the atoms and molecules of the material in the region of interest may diffuse. Typical pulse amplitude, duration and frequency are 0.1-30 G/cm for 0.1-10 ms.
4. Step 5 described above.
5. Repeat step 3.

6. Step 7 described above.

7. Derive the diffusion coefficient D , or an upper bound thereof, or the spin echo decay T_2 or a lower bound thereof, from the echo amplitudes.

5 8. Repeat steps 1 through 6 with a different value for at least one of the following variables: magnetic field gradient strength of steps 3 and 5; magnetic field gradient duration of steps 3 and 5; timing of steps 3, 4, 5 and 7.

10 9. Derive the diffusion coefficient and/or T_2 from the acquired NMR data.

It is appreciated that steps 3 through 6 may be repeated multiple times successively in order to obtain a sufficiently long echo amplitude train, from
15 which the transverse relaxation time may more meaningfully be derived.

It is further appreciated that step 7 is not required if both D and T_2 are unknown and neither could be considered as dominating the decay rate. Steps 8
20 and 9 are not required if either D or T_2 is known. In that case, the unknown T_2 or D can be derived from a single experiment. Likewise, no more than one experiment is required when either D or T_2 is known to substantially dominate the decay of the echo
25 amplitude.

It is further appreciated that time dependency of the magnetic field gradient other than the square pulse of Fig. 3B may be used. Specifically, when the pulsed gradient is switched
30 off, the gradient strength should not necessarily diminish and sinusoidal and other dependencies might be employed.

The advantage of repeating the experiment and integrating the measurement readings in order to
35 obtain statistically valid and meaningful results is also appreciated.

It is also recognized that step 4 might alternatively be replaced by application of two or more pulses whose combined effect is the refocusing of the nuclear spins yielding a stimulated echo at step 6 and allowing more time for diffusion in between these pulses.

The deviation of the diffusion coefficient D may be carried out using the following equations for the constant gradient case:

$$a_n = A e^{-n t_e / T_2 + D (\Gamma G t_e)^2 / 12}$$

or for the pulsed gradient:

$$a_n = A e^{-n (t_e / T_2 + D (\Gamma G \delta)^2 (\delta t_e - \delta / 2))}$$

where:

A is the magnitude of the signal at $t_e \rightarrow 0$ or zero time. A might or might not be known;

n is the echo number;

a_n is its measured amplitude;

t_e is the inter echo spacing applied by the experimenter;

T₂ is the intrinsic transverse relaxation time of the liquid at the in situ physical and chemical conditions; T₂ might or might not be known prior to the measurement;

D is the diffusion coefficient of the fluid at the in situ conditions. D might or might not be known prior to the measurement;

Γ is the gyromagnetic ratio of the isotope studied ($2\pi \times 4.26$ KHz/Gauss for hydrogen);

G is the magnitude of the magnetic field gradient imposed at the volume of investigation by the experimental setup. G is known;

δ is the duration of the magnetic field gradient pulse; and

δt_e is the time between the two magnetic field gradient pulses which precede each echo.

Four cases are treated;

1. Two out of the three parameters of the liquid in the volume of investigation - A, T2 and D - are known. The third might then be derived from the above equations. For example, if A and T2 are known and the first echo amplitude, a_1 is measured, then for a constant gradient

$$D = [-te/T2 - \ln(a_1/A)] * 12/(\Gamma G)^2 te^3$$

More echoes, as well as repeated measurements, may improve the statistical validity of this result.

2. The amplitude A is known, neither T2 nor D are known but only an upper bound for D and/or lower bound for T2 is sought for. An upper bound for D is obtained from the above mentioned equations by replacing the $te/T2$ term by zero. A lower bound for T2 is obtained by setting $D = 0$. Such bounds may be very useful in various cases, e.g. in discriminating hydrocarbon from water on the basis of either D or T2, or in discriminating light from heavy oil.

3. A is either known or unknown but of no interest. Several echoes are recorded and the apparent decay rate is calculated. As an example, for the constant gradient case, the apparent transverse relaxation time is:

$$T2^{(app)} = [1/T2 + D(\Gamma G te)^2/12]^{-1}$$

It is derived from a best fit procedure of the measure of echo amplitudes, a_n , to their representation

$$a_n = Ae^{-nC}$$

where $C = te/T2^{(app)}$

in which $T2^{(app)}$ is a fitting parameter.

Alternatively, by dividing all of the amplitudes by one of the echo amplitudes, for example,

a_1 , the obtained ratios are to be represented by the right hand of

$$a_n/a_1 = \exp [-(n t_e - t_e)/T_2^{(app)}]$$

5 A is factored out and D, T2 or either of their bounds can be derived from the above mentioned equation relating $T_2^{(app)}$, T2 and D. Once again, the upper D bound is obtained by setting $1/T_2$ to zero and
10 solving for D, and the lower T2 bound is obtained by setting D to zero.

 Alternatively, T2 or D or either of their bounds can be derived from repetition of the same
15 experiment at least twice, varying one or more of the following parameters: t_e , G, delta or δ .

4. If both D and T2 are unknown and the
20 above mentioned bounds are insufficient approximations, the apparent relaxation time should be calculated at least twice for two experiments differing in at least one of the following parameters:
25 t_e , G, delta or δ . In cases such as that of a preferred embodiment of this invention, for which the gradient G is also a function of the field strength
30 are hence a function of the resonance frequency, two or more experiments differing in the resonance frequency are sufficient.

 It is convenient, though not necessary, to
35 rewrite the relation between $T_2^{(app)}$, T2 and D in terms of
of $R_2^{(app)} = 1/T_2^{(app)}$

and

$$R_2 = 1/T_2.$$

The equation for R_2 and D is a linear equation, e.g.:

5
$$R_2^{(app)} = R_2 + D(\Gamma G t e^2)/12$$

for the fixed gradient embodiment. The two or more distinct experiments yield a set of two or more linear equations for T_2 and D having different values of $R_2^{(app)}$.

10 Out of this set of two or more equations, T_2 and D may be derived by either explicit solution of the two linear equations yielding the values of the two unknowns, or best fit (such as least squares) for a
15 set of three or more distinct experiments.

It is appreciated that several experiments of the type described above may be combined into a
20 single experiment by acquiring all the required data from the signals of a single excitation. This can be accomplished by changing the above mentioned parameters during a single sequence. As an
25 illustrative example: the first few echoes are spaced by one fixed time interval, the next few by another, and so on.

It will be appreciated by persons skilled in
30 the art that the present invention is not limited by what has been particularly shown and described hereinabove. Rather the scope of the present
35 invention is defined only by the claims which follow.

CLAIMS

1. A method for conducting borehole NMR measurements comprising the steps of:
 - 5 providing a magnetic field and a magnetic field gradient at a desired location along a borehole;
 - carrying out at least one NMR experiment in the presence of the magnetic field gradient;
 - 10 sensing the diffusion effect on the decay of at least the first echo; and
 - determining therefrom the diffusion coefficient.
- 15 2. A method according to claim 1 and wherein said step of carrying out includes the steps of carrying out at least two NMR experiments.
- 20 3. A method according to claim 1 and wherein said magnetic field gradient is constant over time.
4. A method according to claim 2 and
25 wherein said magnetic field gradient is constant over time.
5. A method according to claim 1 and wherein said magnetic field gradient is a switched
30 magnetic field gradient.
6. A method according to claim 2 and wherein said magnetic field gradient is a switched
35 magnetic field gradient.
7. A method according to claim 2 and wherein said two NMR experiments such that they

differ in at least one of the following parameters: 1. the time the molecules are allowed to diffuse, 2. the magnitude of the magnetic field gradient, 3. the duration the magnetic field gradient is applied, 4. echo spacing and 5. the applied RF frequency.

8. A method according to claim 1 and wherein at least one of the following parameters is changed during a given NMR experiment: 1. the time the molecules are allowed to diffuse, 2. the magnitude of the magnetic field gradient, 3. the duration the magnetic field gradient is applied, 4. echo spacing.

9. A method according to claim 1 and also comprising the step of employing the diffusion coefficient D to determine at least one of the following petrophysical parameters:

Water/hydrocarbon discrimination;

Water and hydrocarbon saturation levels;

Permeability;

Pore size and pore size distribution;

Oil viscosity;

Formation form factor F, which is a measure of the average increase in electrical resistance due to the formation tortuosity.

q-space imaging of the formation.

10. A method according to claim 2 and also comprising the step of employing the diffusion coefficient D to determine at least one of the following petrophysical parameters:

Water/hydrocarbon discrimination;

Water and hydrocarbon saturation levels;

Permeability;

5 Pore size and pore size distribution;

Oil viscosity;

Formation form factor F, which is a measure
of the average increase in electrical resistance due
10 to the formation tortuosity.

q-space imaging of the formation.

11. A method for conducting borehole NMR
measurements comprising the steps of:

15

1. applying a static magnetic field
to polarize the nuclear spins in the material at a
given region of the borehole, thus creating bulk
20 magnetization at the region of interest;

2. applying an RF field to the region
of interest at a preselected frequency, duration and
magnitude in order to cause at least part of the
25 magnetization to lie in a horizontal plane, defined
relative to the plane of the borehole;

3. applying a fixed magnetic field
gradient to the region of interest, thereby allowing
30 the atoms and molecules of the material in the region
of interest to diffuse in a gradient field;

4. applying a refocusing RF pulse to
35 the region of interest;

5. repeating step 3;

6. acquiring an NMR spin echo; and

7. deriving the diffusion coefficient D and/or the spin echo decay T2 from the echo amplitude.

5 12. A method according to claim 11 and also comprising repeating the steps 3 - 6 in order to acquire a plurality of echoes and to derive T2 and/or D therefrom.

10 13. A technique for conducting borehole NMR measurements comprising the steps of:

1. applying a static magnetic field to polarize the nuclear spins in the material at a
15 given region of the borehole, thus creating bulk magnetization at the region of interest;

2. applying an RF field to the region
20 of interest at a preselected frequency, duration and magnitude in order to cause at least part of the magnetization to lie in a horizontal plane, defined relative to the plane of the borehole;

25 3. applying a time switched magnetic field gradient to the region of interest, thereby allowing the atoms and molecules of the material in the region of interest to diffuse in a gradient field;

30 4. applying a refocusing RF pulse to the region of interest;

5. repeating step 3;

35 6. acquiring an NMR spin echo; and

7. deriving the diffusion coefficient D and/or the spin echo decay T2 from the echo amplitude.

5 14. A method according to claim 13 and also comprising repeating the steps 3 - 6 in order to acquire a plurality of echoes and to derive T2 and/or D therefrom.

10 15. Apparatus for conducting borehole NMR measurements comprising:

 means for providing a magnetic field gradient at a desired location along a borehole;

15 means for carrying out at least one NMR experiment in the presence of the magnetic field gradient;

20 means for sensing the diffusion effect on the decay of at least the first echo; and

 means for determining therefrom the diffusion coefficient.

25 16. Apparatus according to claim 15 and wherein said means for carrying out includes means for carrying out at least two NMR experiments.

30 17. Apparatus according to claim 16 and wherein said means for carrying out at least two NMR experiments include means for varying at least one experimental parameter during an experimental
35 sequence.

18. Apparatus according to claim 15 and wherein said magnetic field gradient is constant over time.

5 19. Apparatus according to claim 15 and wherein said magnetic field gradient is a switched magnetic field gradient.

20 20. Apparatus according to claim 16 and wherein said two NMR experiments differ in at least one of the following parameters: 1. the time the molecules are allowed to diffuse, 2. the magnitude of the magnetic field gradient, 3. the duration the
15 magnetic field gradient is applied, 4. the echo spacing and 5. the applied RF frequency.

21. Apparatus according to claim 15 and
20 also comprising means for employing the diffusion coefficient D to determine at least one of the following petrophysical parameters:

Water/hydrocarbon discrimination;
25 Water and hydrocarbon saturation levels;
Permeability;
Pore size and pore size distribution;
Oil viscosity;
30 Formation form factor F, which is a measure of the average increase in electrical resistance due to the formation tortuosity;
35 q-space imaging of the formation.

22. Apparatus for conducting borehole NMR measurements comprising:

means for applying a static magnetic field to polarize the nuclear spins in the material at a given region of the borehole, thus creating bulk magnetization at the region of interest;

means for applying an RF field to the region of interest at a preselected frequency, duration and magnitude in order to cause at least part of the magnetization to lie in a horizontal plane, defined relative to the plane of the borehole;

means for applying a fixed magnetic field gradient to the region of interest, thereby causing the atoms and molecules of the material in the region of interest to diffuse;

means for applying a refocusing RF pulse to the region of interest;

means for again applying a fixed magnetic field gradient to the region of interest, thereby causing the atoms and molecules of the material in the region of interest to diffuse;

means for acquiring the NMR spin echo; and
means for deriving the diffusion coefficient D or the spin echo decay T_2 from the echo amplitudes.

23. Apparatus for conducting borehole NMR measurements comprising:

means for applying a static magnetic field to polarize the nuclear spins in the material at a

given region of the borehole, thus creating bulk magnetization at the region of interest;

means for applying an RF field to the region
5 of interest at a preselected frequency, duration and magnitude in order to cause at least part of the magnetization to lie in a horizontal plane, defined relative to the plane of the borehole;

10 means for applying a time switched magnetic field gradient to the region of interest, thereby causing the atoms and molecules of the material in the region of interest to diffuse;

15 means for applying a refocusing RF pulse to the region of interest;

means for again applying a fixed magnetic
20 field gradient to the region of interest, thereby causing the atoms and molecules of the material in the region of interest to diffuse;

means for acquiring the NMR spin echo; and
25 means for deriving the diffusion coefficient D or the spin echo decay T2 from the echo amplitudes.

24. A method for conducting NMR measurements of a material comprising the steps of:
30 providing a magnetic field gradient at a desired location in the material from a magnet spaced externally with respect to the material;
35 carrying out at least one NMR experiment in the presence of the magnetic field gradient, which experiment produces at least a first echo;

sensing the diffusion effect on the decay of
at least the first echo; and

determining therefrom the diffusion
5 coefficient.

25. A method for conducting NMR
measurements comprising the steps of:

1. applying a static magnetic field
10 to polarize the nuclear spins in a material at a
given region of interest exterior to the source of the
static magnetic field, thus creating bulk
magnetization at the region of interest;

15 2. applying an RF field to the region
of interest at a preselected frequency, duration and
magnitude in order to cause at least part of the
20 magnetization to lie in a plane perpendicular to the
direction of the static magnetic field;

3. applying a fixed magnetic field
gradient to the region of interest, thereby allowing
25 the atoms and molecules of the material in the region
of interest to diffuse in a gradient field;

4. applying a refocusing RF pulse to
the region of interest;

30 5. repeating step 3;

6. acquiring an NMR spin echo; and

7. deriving the diffusion coefficient

35 D and/or the spin echo decay T2 from the echo
amplitude.

26. A method according to claim 25 and also comprising repeating the steps 3 - 6 to acquire multiple echoes and deriving the diffusion coefficient
5 D and/or the spin echo decay T2 from the echo amplitudes.

27. A method for conducting NMR measurements comprising the steps of:

10 1. applying a static magnetic field to polarize the nuclear spins in the material at a given region of interest exterior to the source of the static magnetic field, thus creating bulk
15 magnetization at the region of interest;

2. applying an RF field to the region of interest at a preselected frequency, duration and
20 magnitude in order to cause at least part of the magnetization to lie in a plane perpendicular to the direction of the static magnetic field;

3. applying a time switched magnetic
25 field gradient to the region of interest, thereby allowing the atoms and molecules of the material in the region of interest to diffuse in a gradient field;

4. applying a refocusing RF pulse to
30 the region of interest;

5. repeating step 3;

6. acquiring the NMR spin echo; and

35 7. deriving the diffusion coefficient D and/or the spin echo decay T2 from the echo amplitudes.

28. A method according to claim 27 and also comprising repeating the steps 3 - 6 to acquire multiple echoes and deriving the diffusion coefficient
5 D and/or the spin echo decay T2 from the echo amplitudes.

29. Apparatus for conducting NMR measurements comprising:

10 means for providing a magnetic field gradient at a desired location in a material located externally of the source of the magnetic field gradient;

15 means for carrying out at least one NMR experiment in the presence of the magnetic field gradient, producing at least a first echo;

20 means for sensing the diffusion effect on the decay of at least the first echo; and

means for determining therefrom the diffusion coefficient.

25

30

35

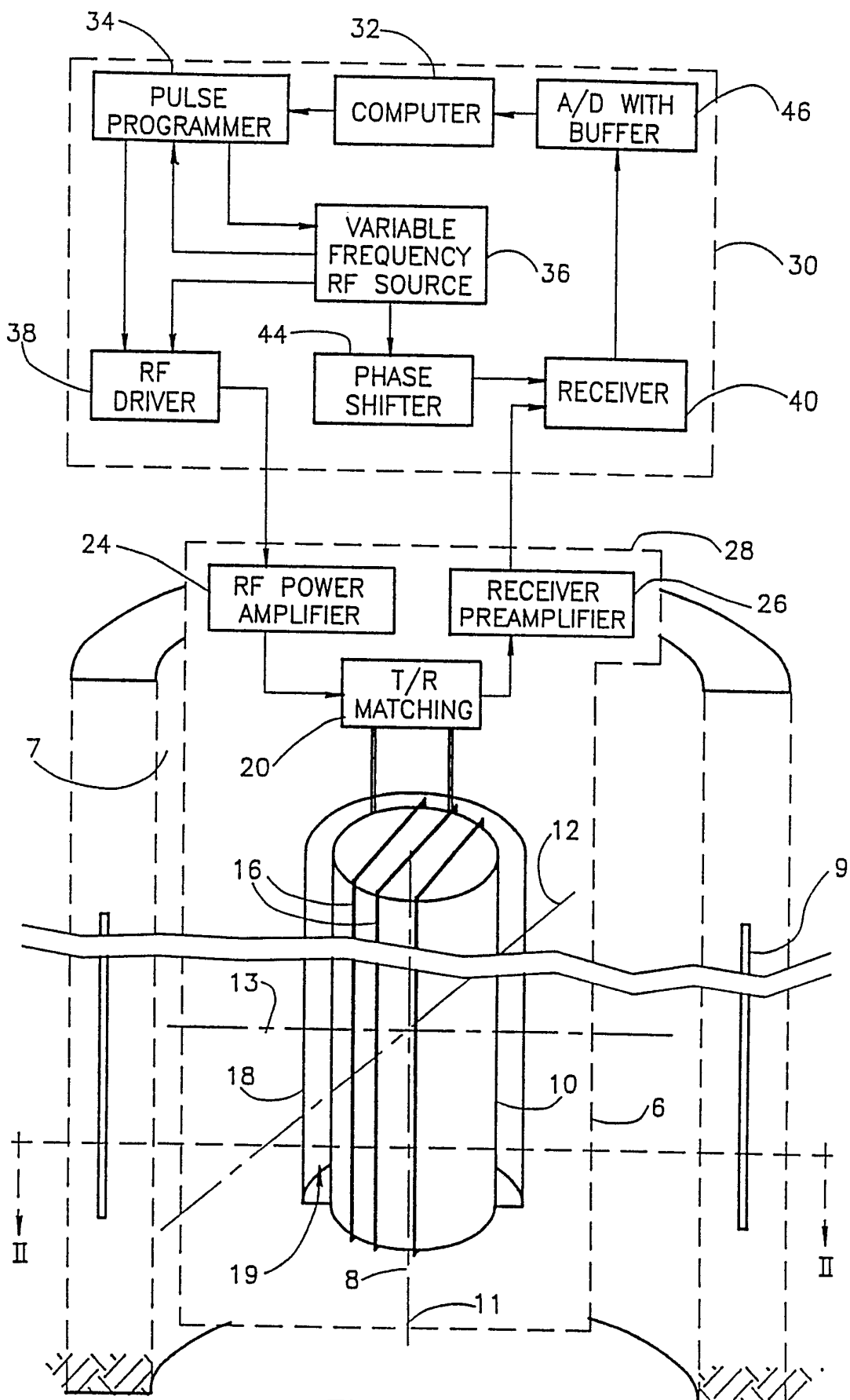


FIG.1A

SUBSTITUTE SHEET

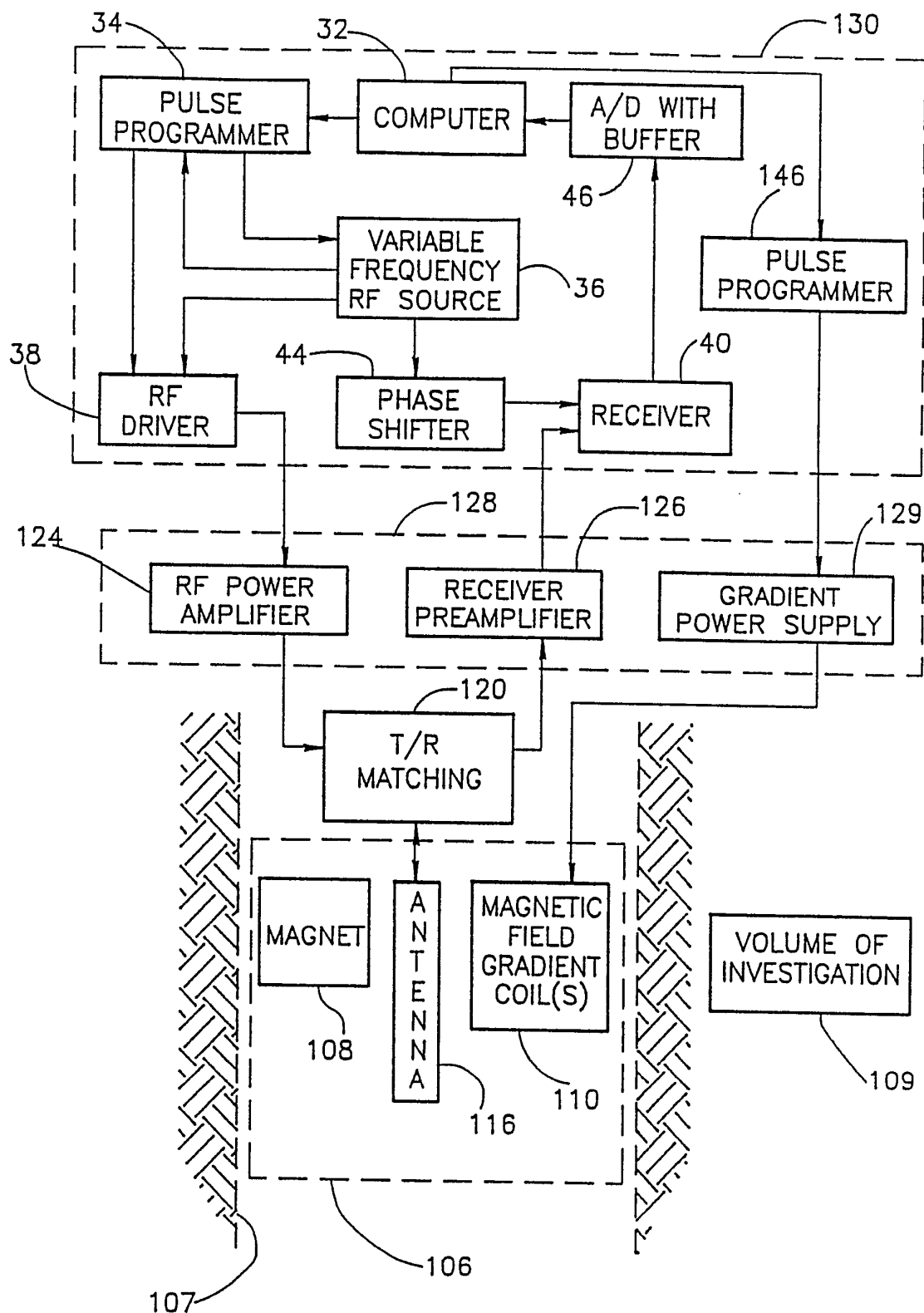


FIG. 1B

FIG.2A

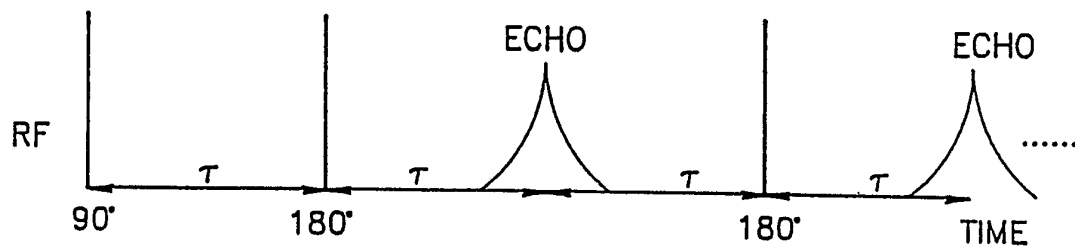


FIG.2B

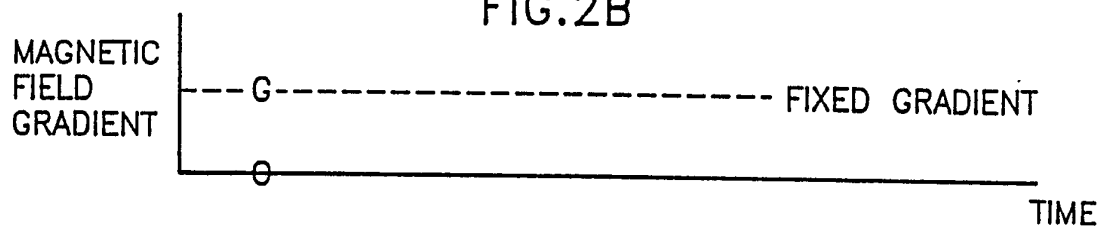


FIG.3A

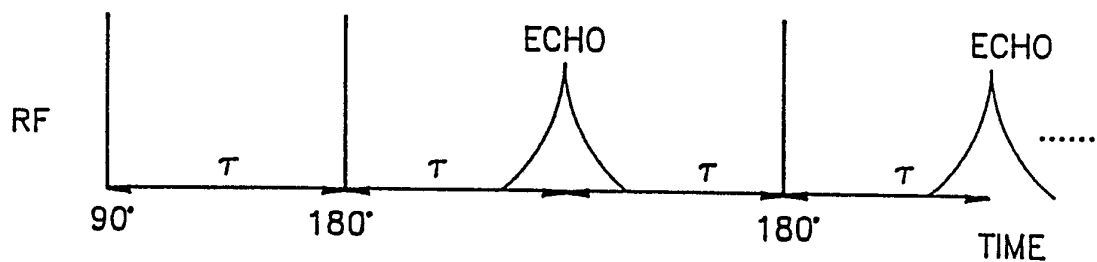
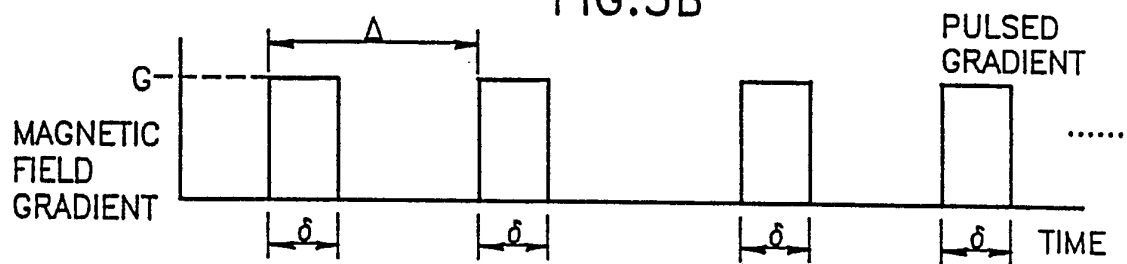


FIG.3B



INTERNATIONAL SEARCH REPORT

International Application No. PCT/US91/09045

I. CLASSIFICATION OF SUBJECT MATTER (if several classification symbols apply, indicate all) ³		
According to International Patent Classification (IPC) or to both National Classification and IPC IPC (5): G01R 33/20 US CL : 324/303		
II. FIELDS SEARCHED		
Minimum Documentation Searched ⁴		
Classification System	Classification Symbols	
U.S.	324/300, 303, 307, 318, 322	
Documentation Searched other than Minimum Documentation to the extent that such Documents are included in the Fields Searched ⁵		
III. DOCUMENTS CONSIDERED TO BE RELEVANT ¹⁴		
Category*	Citation of Document, ¹⁶ with indication, where appropriate, of the relevant passages ¹⁷	Relevant to Claim No. ¹⁸
Y	US, A, 4,719,423 (Vinegar et al) 12 January 1988, See the entire abstract.	1-29
Y	US, A, 4,717,878 (Taicher et al) 05 January 1988, See abstract.	1-29
Y	US, A, 4,710,713 (Strikman) 01 December 1987 See abstract.	1-29
Y	US, A, 4,424,487 (Lauffer) 03 January 1984 See abstract.	1-29
<div style="display: flex; justify-content: space-between;"> <div style="width: 45%;"> <p>* Special categories of cited documents:¹⁵</p> <p>"A" document defining the general state of the art which is not considered to be of particular relevance</p> <p>"E" earlier document but published on or after the international filing date</p> <p>"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)</p> <p>"O" document referring to an oral disclosure, use, exhibition or other means</p> <p>"P" document published prior to the international filing date but later than the priority date claimed</p> </div> <div style="width: 45%;"> <p>"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention</p> <p>"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step</p> <p>"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art</p> <p>"&" document member of the same patent family</p> </div> </div>		
IV. CERTIFICATION		
Date of the Actual Completion of the International Search ²		Date of Mailing of this International Search Report ²
06 April 1992		16 APR 1992
International Searching Authority ¹		Signature of Authorized Officer ²⁰
ISA/US		<i>Michael J. Tokar</i> Michael J. Tokar