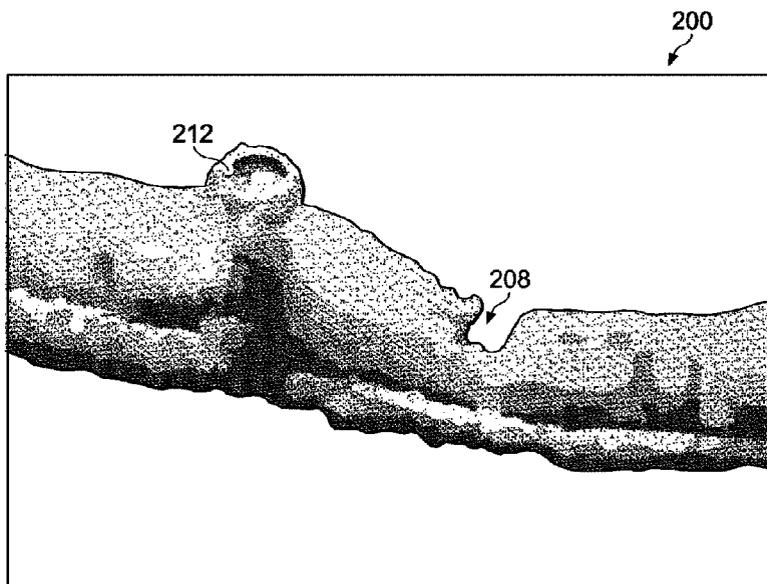




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(54) **Titre : SYSTEME D'IMAGERIE OPHTHALMIQUE A DETECTION AUTOMATIQUE DE CARACTERISTIQUE RETINIENNE**  
 (54) **Title: OPHTHALMIC IMAGING SYSTEM WITH AUTOMATIC RETINAL FEATURE DETECTION**



(57) **Abrégé/Abstract:**

A method of automatically detecting a retinal feature using an ophthalmic imaging system can include: acquiring an optical coherence tomography (OCT) image of a retina; segmenting the OCT image; generating a metric based on the segmented OCT image; detecting the retinal feature based on the metric; and providing an indication of the detected retinal feature to a user. An ophthalmic imaging system can include: an OCT system configured to acquire an image of a retina; a computing device coupled to the OCT system and configured to segment the image, generate a metric based on the segmented image, and detect a retinal feature based on the metric; and an audio/visual/tactile device in communication with the computing device and configured to provide at least one of an audio, visual, and tactile indication of the detected retinal feature to a user.

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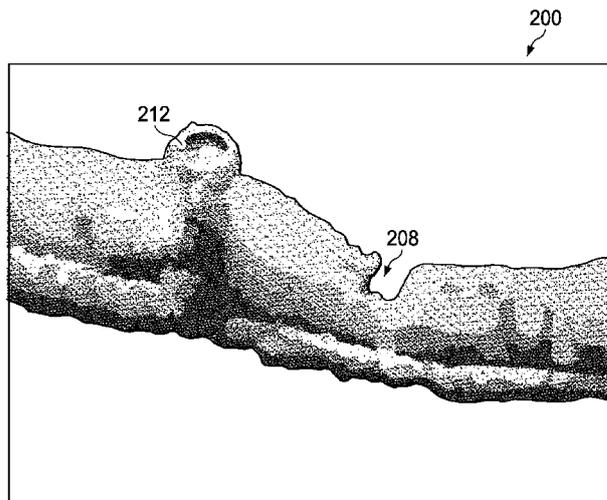
(54) **Title:** OPHTHALMIC IMAGING SYSTEM WITH AUTOMATIC RETINAL FEATURE DETECTION

Fig. 2a

(57) **Abstract:** A method of automatically detecting a retinal feature using an ophthalmic imaging system can include: acquiring an optical coherence tomography (OCT) image of a retina; segmenting the OCT image; generating a metric based on the segmented OCT image; detecting the retinal feature based on the metric; and providing an indication of the detected retinal feature to a user. An ophthalmic imaging system can include: an OCT system configured to acquire an image of a retina; a computing device coupled to the OCT system and configured to segment the image, generate a metric based on the segmented image, and detect a retinal feature based on the metric; and an audio/visual/tactile device in communication with the computing device and configured to provide at least one of an audio, visual, and tactile indication of the detected retinal feature to a user.

# Ophthalmic Imaging System with Automatic Retinal Feature Detection

## **BACKGROUND**

### **5 Technical Field**

Embodiments disclosed herein are related to ophthalmic imaging systems. More specifically, embodiments described herein relate to automatically detecting structural features of the retina, such as retinal breaks, using optical coherence tomography (OCT).

### **Related Art**

10 Structural defects in a patient's eye can lead to vision loss. For example, a retinal break can be a full-thickness defect in the neurosensory retina. A retinal break can be associated with rhegmatogenous retinal detachment, which can induce severe loss of vision. Moreover, undetected retinal breaks are the most prevalent reason for failure in retinal detachment surgery.

15 Conventionally, retinal breaks have been detected through careful fundus examination by a surgeon during a surgical procedure, such as vitreo-retinal surgery. This can involve en face visualization and examination using a surgical microscope. The conventional approach can be limited in its ability to detect relatively small retinal breaks. Thus, a surgeon can continue or finish a surgical procedure without appreciating the presence and/or position of a retinal break.

20 Some attempts have been made to increase the visibility of retinal breaks. For example, a dye-extrusion technique can involve injection of trypan blue dye into the subretinal space. Such techniques, however, can complicate the surgical procedure and are not commonly used.

Optical coherence tomography (OCT) can be a noninvasive, high resolution cross-sectional imaging modality. Some efforts have been made to visualize the retina using OCT. However, these efforts have not involved automatic detection of retinal breaks.

Accordingly, there remains a need for improved devices, systems, and methods that improve the ability to automatically detect structural features of the retina during a surgical procedure by addressing one or more of the needs discussed above.

### SUMMARY

5           The presented solution fills an unmet medical need with a unique solution to provide automatic detection of structural defects of the retina by using OCT images to analyze one or more retinal layers. A surgeon can be alerted upon detection of a retinal break or other feature during a surgical procedure.

10           Consistent with some embodiments, a method of automatically detecting a retinal feature using an ophthalmic imaging system includes: acquiring an OCT image of a retina; segmenting the OCT image; generating a metric based on the segmented OCT image; detecting the retinal feature based on the metric; and providing an indication of the detected retinal feature to a user.

15           Consistent with some embodiments, an ophthalmic imaging system includes: an OCT system configured to acquire an image of a retina; a computing device coupled to the OCT system and configured to segment the image, generate a metric based on the segmented image, and detect a retinal feature based on the metric; and an audio/visual/tactile device in communication with the computing device and configured to provide at least one of an audio, visual, and tactile indication of the detected retinal feature to a user.

20           Certain exemplary embodiments can provide a system, comprising: an optical coherence tomography (OCT) imaging system configured to acquire an OCT image of a retina; a non-transitory computer-readable medium storing instructions that, when executed, cause a processor to: segment the OCT image to identify a neurosensory retina and an inner limiting membrane; generate a plurality of metrics based on the segmented OCT image, wherein the plurality of metrics includes: a thickness of the neurosensory retina in a first area of the retina and a second  
25           area of the retina; and a radius of curvature of the inner limiting membrane in the first area of the retina and the second area of the retina; wherein the first and the second areas of the retina are adjacent; compare the thickness of the neurosensory retina and the radius of curvature of the inner limiting membrane in the first area with the thickness of the neurosensory retina and the radius of curvature of the inner limiting membrane in the second area; determine that the thickness of the

neurosensory retina in the first area differs from the thickness of the neurosensory retina in the second area and the radius of curvature of the inner limiting membrane in the first area differs from the radius of curvature of the inner limiting membrane in the second area; and based on the determination, indicate a location of a probable retinal break to a user.

5 Certain exemplary embodiments can provide a system, comprising: an optical coherence tomography (OCT) imaging system configured to acquire an OCT image of a retina; and a non-transitory computer-readable medium storing instructions that, when executed, cause a processor to: segment the OCT image to identify a neurosensory retina and an inner limiting membrane; generate a plurality of metrics based on the segmented OCT image, wherein the plurality of  
10 metrics includes: a thickness of the neurosensory retina in a first area of the retina and a second area of the retina; and a radius of curvature of the inner limiting membrane in the first area of the retina and the second area of the retina; wherein the first and the second areas of the retina are adjacent; compare the thickness of the neurosensory retina and the radius of curvature of the inner limiting membrane in the first area with the thickness of the neurosensory retina and the  
15 radius of curvature of the inner limiting membrane in the second area; determine that a difference in the thickness of the neurosensory retina in the first area and the second area meets or exceeds a first threshold and a difference in the radius of curvature of the inner limiting membrane in the first area and the second area meets or exceeds a second threshold; and based on the determination, indicate a location of a probable retinal break to a user.

20 Certain exemplary embodiments can provide a method, comprising: acquiring an OCT image of a retina with an optical coherence tomography (OCT) imaging system of an ophthalmic surgical system; segmenting the OCT image by an image processor of the ophthalmic surgical system to identify a neurosensory retina and an inner limiting membrane; generating, by the image processor, a plurality of metrics based on the segmented OCT image, wherein the plurality  
25 of metrics includes: a thickness of the neurosensory retina in a first area of the retina and a second area of the retina; and a radius of curvature of the inner limiting membrane in the first area of the retina and the second area of the retina; wherein the first and the second areas of the retina are adjacent; determining, by the image processor, at least one of the following: the thickness of the neurosensory retina in the first area is less than the thickness of the neurosensory  
30 retina in the second area and the radius of curvature of the inner limiting membrane in the first

area is greater than the radius of curvature of the inner limiting membrane in the second area; and a difference in the thickness of the neurosensory retina in the first area and the second area meets or exceeds a first threshold and a difference in the radius of curvature of the inner limiting membrane in the first area and the second area meets or exceeds a second threshold; and based  
5 on the determination, providing at least one of an audio, visual, and tactile indicator to indicate a location of a probable retinal break to a user.

Additional aspects, features, and advantages of the present disclosure will become apparent from the following detailed description.

### **BRIEF DESCRIPTION OF THE DRAWINGS**

10 **FIG. 1** is a flow diagram illustrating a method of automatically detecting a retinal feature using an ophthalmic imaging system.

**FIG. 2a** is a two-dimensional OCT image of a retina.

**FIG. 2b** is a three-dimensional OCT image of a retina.

**FIG. 3a** is a two-dimensional OCT image of a retina.

15 **FIG. 3b** is a three-dimensional OCT image of a retina.

**FIG. 4** is a chart illustrating a thickness profile of a retina.

**FIG. 5a** is a two-dimensional OCT image of a retina.

**FIG. 5b** is a fundus image of a retina.

**FIG. 5c** is a pseudo color map representative of a likelihood of a retinal feature.

20 **FIG. 6** is a diagram illustrating an ophthalmic imaging system.

In the drawings, elements having the same designation have the same or similar functions.

## DETAILED DESCRIPTION

In the following description specific details are set forth describing certain embodiments. It will be apparent, however, to one skilled in the art that the disclosed embodiments may be practiced without some or all of these specific details. The specific embodiments presented are  
5 meant to be illustrative, but not limiting. One skilled in the art may realize other material that, although not specifically described herein, is within the scope of this disclosure.

The present disclosure describes devices, systems, and methods for automatically detecting a retinal feature using quantitative image analysis of a retinal OCT image. One or more retinal layers, such as the inner limiting membrane (ILM) and the retinal pigment  
10 epithelium (RPE), can be identified when the OCT image is segmented. A metric or retinal layer parameter describing the geometry of one or more retinal layers (thickness of the neurosensory retina, concavity/convexity of the ILM, radius of curvature of the ILM, etc.) can be generated based on the segmented OCT image. The retinal feature can be detected using the metric or retinal layer parameter. A retinal break can be detected when the thickness of the neurosensory  
15 retina is less than a threshold, when the ILM is concave in the area of the retinal feature, and when the radius of curvature of the ILM in the area of the retinal feature is less than a threshold. An audio, visual, and/or tactile indication can be provided to the surgeon during the surgical procedure when the retinal feature is detected.

The devices, systems, and methods of the present disclosure provide numerous  
20 advantages, including: (1) reducing the surgeon's burden in searching for retinal defects; (2) reducing surgical procedure failures by minimizing undetected retinal defects; (3) improving surgical procedure outcomes by automatically detecting retinal defects and allowing for those defects to be addressed; and (4) increasing surgical procedure efficiency by automatically alerting the surgeon to a detected retinal defect.

**FIG. 1** provides a flow diagram of a method 100 of automatically detecting a retinal  
25 feature using an ophthalmic imaging system. The method 100 can include acquiring an OCT image of a retina (step 102). The method 100 can include segmenting the OCT image (step 104). The method 100 can include generating a metric based on the segmented OCT image (step 106). The method 100 can include detecting the retinal feature based on the metric (step 108). The

method 100 can include providing an indication of the detected retinal feature to a user (step 110). The steps of method 100 can be performed by one or more components of an ophthalmic imaging system (e.g., ophthalmic imaging system 600 of **FIG. 6**).

Method 100 can include, at step 102, acquiring an OCT image of the retina. An OCT system (e.g., OCT system 620 of **FIG. 6**) can acquire data associated with the OCT image. The OCT system can include an imaging probe configured to penetrate a portion of a patient's eye and image the interior of the patient's eye, including the retina. An external OCT system can be configured to image the eye, including the retina, while positioned external relative to the patient's eye. A computing device (e.g., computing device 610 of **FIG. 6**) can process the data acquired by the OCT system to generate the OCT image.

The OCT system can be configured to split an imaging light received from a light source into an imaging beam that is directed onto target biological tissue (e.g., by the imaging probe) and a reference beam that can be directed onto a reference mirror. The OCT system can be a Fourier domain (e.g., spectral domain, swept-source, etc.) or a time domain system. The OCT system can be further configured to receive the imaging light reflected from the target biological tissue (e.g., captured by the imaging probe, the external OCT system, etc.). The interference pattern between the reflected imaging light and the reference beam is utilized to generate images of the target biological tissue. Accordingly, the OCT system can include a detector configured to detect the interference pattern. The detector can include Charge-Coupled Detectors (CCDs), pixels, or an array of any other type of sensor(s) that generate an electric signal based on detected light. Further, the detector can include a two-dimensional sensor array and a detector camera.

The OCT image can be two-dimensional or three-dimensional. For example, **FIG. 2a** provides a two-dimensional OCT image 200 of a portion of the retina, and **FIG. 2b** provides a three-dimensional OCT image 250 of a portion of the retina. A retinal break 208 can be seen on the right side of **FIGS. 2a** and **2b**. The retinal break 208 can be automatically detected using the systems, methods, and devices described herein. A blood vessel 212 can be seen on the left side of **FIGS. 2a** and **2b**.

Method 100 includes, at step 104, segmenting the OCT image. The computing device can identify one or more retinal layers using the data associated with the OCT image.

Segmenting the OCT image includes identifying an inner limiting membrane (ILM), a nerve fiber layer, a ganglion cell layer, an inner plexiform layer, an inner nuclear layer, an outer plexiform layer, an outer nuclear layer, an external limiting membrane, a layer of rods and cones, a retinal pigment epithelium (RPE), and other retinal layer(s). **FIG. 3a** provides the two-dimensional OCT image 200 with boundaries of an ILM layer 202 and an RPE layer 204 identified. Similarly, **FIG. 3b** provides the three-dimensional OCT image 250 with boundaries of the ILM layer 202 and the RPE layer 204 identified.

Method 100 includes, at step 106, generating a metric based on the segmented OCT image. The metric is a retinal layer parameter that objectively represents a geometry of one or more retinal layers using, for example, one or more numerical values. The retinal layer parameter is a thickness, an intensity, a phase, a speckle size, a vascular density, a size, a concavity/convexity, and a radius of curvature of one or more retinal layers. Generating the metric includes determining a numerical representation of the concavity/convexity of the ILM. A radius of curvature of the ILM in the area of the retinal feature is determined. The retinal layer parameter can be determined using any one, two, three, four, or more retinal layers. Generating the metric includes determining a thickness of the neurosensory retina using the ILM and RPE. The thickness of the neurosensory retina can include a distance between the ILM and RPE. A numerical representation of the thickness can be used as the metric. The retinal layer parameter can be determined using one retinal layer and a strip of predefined thickness that surrounds the one retinal layer. Two or more metrics can be generated and utilized to evaluate the retina.

Method 100 includes, at step 108, detecting a retinal break based on the generated metric. The detected retinal feature is a structural aspect of the retina that is indicative of a defect. The retinal feature can be a break, a hole, a tear, a dialysis, a growth, a protrusion, a depression, a region with subretinal fluid, etc. Multiple retinal features and/or types of retinal features can be detected. The retinal feature(s) can be detected using one or more of the metrics. The thickness of the neurosensory retina and the concavity/convexity of the ILM is utilized. Utilizing more than one metric can advantageously increase the certainty of retinal feature detection.

Detecting the retinal feature includes comparing the retinal layer parameter to the threshold. As the generated metric (step 106) includes the thickness of the neurosensory retina,

detecting the retinal feature includes comparing the thickness to a threshold thickness. The retinal feature can be detected when the retinal layer parameter, such as thickness of the neurosensory retina, among others, is greater than or less than the threshold. A retinal break or a retinal hole can be detected when the thickness is less than the threshold. On the other hand, a growth or a protrusion of the retina can be detected when the thickness is greater than the threshold. The threshold thickness can be in the range of, for example, 50 microns to 300 microns, 75 microns to 300 microns, 100 microns to 250 microns, or other suitable range. Thickness varies along the retina (e.g., at or near the fovea, peripheral retina, etc.), and the threshold can be selected based on a position along the retina where the retinal feature is located.

Detecting the retinal feature using the generated metric (step 106) includes analyzing whether the ILM, among others, has a concave or convex shape and/or the degree of the concavity/convexity (the radius of curvature). An ILM in the area of the retinal feature that is concave can be indicative of a retinal break or a retinal hole, whereas an ILM that is convex can be indicative of a growth or a protrusion in the retina. In that regard, detecting the retinal feature includes comparing a radius of curvature of the ILM in the area of the retinal feature to a threshold radius of curvature indicative of the presence of the retinal feature. A retinal feature can be detected when the radius of curvature is greater than or less than the threshold. For example, a retinal break or a retinal hole can be detected when a concave portion of the ILM has a radius of curvature less than the threshold. The threshold radius of curvature for detecting a retinal break can be in the range of, for example, between about 0.1 mm and about 12 mm, between about 1.0 mm and about 6 mm, or between about 2.0 mm and about 4.0 mm, including values such as 10 mm, 9 mm, 8 mm, 7 mm, 6 mm, 5 mm, 4 mm, 3 mm, 2 mm, 1 mm, or other suitable value. A combination of the concavity/convexity and the corresponding radius of curvature can be utilized to detect the retinal feature.

The threshold(s) used in detecting the retinal feature can be adaptive or patient-specific. For example, a threshold can be a percentage difference in the neurosensory retina thickness compared to adjacent areas. Thus, a retinal feature can be detected when an area of the patient's neurosensory retina has a thickness greater than or less than, e.g., 50% of the thickness of adjacent areas. Similarly, a retinal feature can be detected when the radius of curvature of the ILM in the area of the retinal feature is greater than or less than, e.g., 50% of the radius of

curvature of adjacent areas. The threshold can be between, for example, 1%-100%, 1%-75%, 1%-50%, 1%-25%, etc. The one or more thresholds can be selected based on empirical data. For example, a collection or database of patients can be used to determine a fixed, normal range of neurosensory retina thickness for patients with similar characteristics. Thus, a retinal feature can be detected when an area of the patient's neurosensory retina has a thickness outside of (e.g., greater than or less than) the fixed, normal range expected for the patient. Such empirical data can be used to determine a default threshold value, which may be adjusted based on patient specific characteristics. While this discussion specifically mentions thickness of the neurosensory retina, it is understood that the concavity/convexity, radius of curvature, and/or other metrics can be similarly patient-specific or more generally applicable.

**FIG. 4** provides a chart 400 that is representative of a thickness profile of the neurosensory retina. The data associated with the chart 400 can be based on the segmented OCT image. The x-axis of the chart 400 can represent the position along the neurosensory retina in units of pixels. The y-axis can represent the thickness of the neurosensory retina in units of pixels. A curve 206 can represent the distance of the ILM from the RPE along the retina. The neurosensory retina thickness depicted in chart 400 can be the metric used to detect the retinal break 208. The retinal break 208 can be an area along the neurosensory retina with a thickness that is significantly different from adjacent areas (e.g., less than 50%) and/or an area with a thickness less than a fixed, normal range. While this discussion specifically mentions thickness of the neurosensory retina, it is understood that the concavity/convexity, radius of curvature, and/or other metrics can be similarly used to detect the retinal break or other retinal feature.

Method 100 includes, at step 110, providing an indication of the detected retinal feature to a user. For example, an audio, visual, and/or tactile indication can be provided using an audio/visual/tactile device (e.g., audio/visual/tactile device 630 of **FIG. 6**). The indication can alert the surgeon, during the surgical procedure, as to the presence and/or position of the detected retinal feature. As shown in **FIG. 5a**, an indication 210 of the detected retinal break 208 can be a geometrical object (e.g., a square, a circle, a polygon, an ellipse, etc.) positioned around the retinal break 208. The indication 210 can be overlaid on and/or otherwise combined with the OCT image 200, and the combined OCT image can be output to the audio/visual/tactile device.

As shown in **FIG. 5b**, the indication 210 can be shaped based on the detected retinal break 208. As also shown in **FIG. 5b**, the indication 210 can be overlaid on and/or otherwise combined with a fundus image 260 of the eye (e.g., instead of the two-dimensional OCT image 200) and the combined fundus image can be output to the audio/visual/tactile device.

5 As shown in **FIG. 5c**, a pseudo color map 270 can be generated based on the detected retinal break 208. The pseudo color map 270 can be representative of the likelihood of the presence of a retinal feature at a given location of the retina. The indication 210 can be an area of the pseudo color map 270 that illustrates a high likelihood of the retinal feature being positioned in the area. The pseudo color map can be output to the audio/visual/tactile device.

10 Generally, the indication 210 can include text, one or more other shapes or symbols, and/or other visual alerts. The indication 210 can be variously positioned relative to the retinal feature. The indication 210 can include an audible signal to alert the user/surgeon to the presence and/or position of a detected retinal feature. The indication 210 can include tactile and/or haptic feedback to the surgeon.

15 **FIG. 6** provides a block diagram of an ophthalmic imaging system 600. The imaging system 600 includes an OCT system 620 that is configured to acquire an image of the retina. The imaging system 600 includes a computing device 610 that is configured to segment the image, generate a metric based on the segmented image, and detect a retinal break based on evaluation of the generated metric. The computing device 610 and the OCT system 620 can be  
20 configured to perform features similar to those described above. The imaging system 600 includes an audio/visual/tactile device 630 in communication with the computing device 610 and configured to provide at least one of an audio, visual, and tactile indication of the detected retinal feature. The audio/visual/tactile device 630 can be a standalone device and/or a component that is part of the computing device 610 or the OCT system 620. For example, the  
25 audio/visual/tactile device 630 can be a display device with integrated speakers.

Embodiments as described herein can provide devices, systems, and methods that facilitate automatic detection of structural defects in the retina by analyzing retinal OCT images. The devices, systems, and methods described herein can be used with any imaging modality in which the position, geometry, and/or contour of one or more retinal layers can be identified. The

examples provided above are exemplary only and are not intended to be limiting. One skilled in the art may readily devise other systems consistent with the disclosed embodiments which are intended to be within the scope of this disclosure. As such, the application is limited only by the following claims.

**CLAIMS:**

1. A system, comprising:
  - an optical coherence tomography (OCT) imaging system configured to acquire an OCT  
5 image of a retina;
  - a non-transitory computer-readable medium storing instructions that, when executed,  
cause a processor to:
    - segment the OCT image to identify a neurosensory retina and an inner limiting  
membrane;
    - 10 generate a plurality of metrics based on the segmented OCT image, wherein the  
plurality of metrics includes:
      - a thickness of the neurosensory retina in a first area of the retina and a  
second area of the retina; and
      - a radius of curvature of the inner limiting membrane in the first area of the  
15 retina and the second area of the retina;
    - wherein the first and the second areas of the retina are adjacent;
    - compare the thickness of the neurosensory retina and the radius of curvature of  
the inner limiting membrane in the first area with the thickness of the neurosensory retina  
and the radius of curvature of the inner limiting membrane in the second area;
    - 20 determine that the thickness of the neurosensory retina in the first area differs  
from the thickness of the neurosensory retina in the second area and the radius of  
curvature of the inner limiting membrane in the first area differs from the radius of  
curvature of the inner limiting membrane in the second area; and
    - based on the determination, indicate a location of a probable retinal break to a  
25 user.
2. The system according to claim 1, wherein the system comprises:
  - a display; and
  - wherein the non-transitory computer-readable medium stores instructions that, when  
30 executed, cause the processor to:

generate a combined image comprising a visual indicator overlaid on the OCT image or a fundus image; and  
provide the combined image to the display.

5 3. The system according to claim 1, wherein the system comprises:  
a display; and

wherein the non-transitory computer-readable medium stores instructions that, when executed, cause the processor to:

10 generate a pseudo color map representative of a probability of the location of the retinal break; and  
provide the pseudo color map to the display.

4. The system according to any one of claims 1 to 3, wherein the system comprises a tactile device configured to provide tactile or haptic feedback indicating the location of at least one of  
15 the first area and the second area based on the tactile indicator generated by the instructions.

5. The system according to any one of claims 1 to 4, wherein the OCT imaging system is configured to acquire a three-dimensional OCT image.

20 6. A system, comprising:

an optical coherence tomography (OCT) imaging system configured to acquire an OCT image of a retina; and

a non-transitory computer-readable medium storing instructions that, when executed, cause a processor to:

25 segment the OCT image to identify a neurosensory retina and an inner limiting membrane;

generate a plurality of metrics based on the segmented OCT image, wherein the plurality of metrics includes:

30 a thickness of the neurosensory retina in a first area of the retina and a second area of the retina; and

a radius of curvature of the inner limiting membrane in the first area of the retina and the second area of the retina;

wherein the first and the second areas of the retina are adjacent;

5 compare the thickness of the neurosensory retina and the radius of curvature of the inner limiting membrane in the first area with the thickness of the neurosensory retina and the radius of curvature of the inner limiting membrane in the second area;

10 determine that a difference in the thickness of the neurosensory retina in the first area and the second area meets or exceeds a first threshold and a difference in the radius of curvature of the inner limiting membrane in the first area and the second area meets or exceeds a second threshold; and

based on the determination, indicate a location of a probable retinal break to a user.

7. The system according to claim 6, wherein at least one of the first threshold and the second threshold is configurable by the user.

8. The system according to claim 6 or 7, wherein the non-transitory computer-readable medium stores instructions that, when executed, cause the processor to adjust at least one of the first threshold and the second threshold based on patient-specific characteristics.

9. The system according to any one of claims 6 to 8, wherein the system comprises:  
a display; and

20 wherein the non-transitory computer-readable medium stores instructions that, when executed, cause the processor to:

25 generate a combined image comprising a visual indicator overlaid on the OCT image or a fundus image; and  
provide the combined image to the display.

10. The system according to any one of claims 6 to 8, wherein the system comprises:  
30 a display; and

wherein the non-transitory computer-readable medium stores instructions that, when executed, cause the processor to:

generate a pseudo color map representative of a probability of the location of the retinal break; and

5 provide the pseudo color map to the display.

11. The system according to any one of claims 6 to 10, wherein the system comprises a tactile device configured to provide tactile or haptic feedback indicating the location of at least one of the first area and the second area based on the tactile indicator generated by the  
10 instructions.

12. The system according to any one of claims 6 to 11, wherein the OCT imaging system is configured to acquire a three-dimensional OCT image.

15 13. A method, comprising:

acquiring an OCT image of a retina with an optical coherence tomography (OCT) imaging system of an ophthalmic surgical system;

segmenting the OCT image by an image processor of the ophthalmic surgical system to identify a neurosensory retina and an inner limiting membrane;

20 generating, by the image processor, a plurality of metrics based on the segmented OCT image, wherein the plurality of metrics includes:

a thickness of the neurosensory retina in a first area of the retina and a second area of the retina; and

25 a radius of curvature of the inner limiting membrane in the first area of the retina and the second area of the retina;

wherein the first and the second areas of the retina are adjacent;

determining, by the image processor, at least one of the following:

30 the thickness of the neurosensory retina in the first area is less than the thickness of the neurosensory retina in the second area and the radius of curvature of the inner limiting membrane in the first area is greater than the radius of curvature of the inner limiting membrane in the second area; and

a difference in the thickness of the neurosensory retina in the first area and the second area meets or exceeds a first threshold and a difference in the radius of curvature of the inner limiting membrane in the first area and the second area meets or exceeds a second threshold; and

5 based on the determination, providing at least one of an audio, visual, and tactile indicator to indicate a location of a probable retinal break to a user.

14. The method according to claim 13, wherein the method comprises:  
adjusting at least one of the first threshold and the second threshold based on patient-  
10 specific characteristics.

15. The method according to claim 13 or 14, wherein the method comprises:  
generating, by the ophthalmic surgical system, a combined image comprising the visual  
indicator overlaid on the OCT image or a fundus image; and  
15 providing the combined image to a display.

16. The method of claim 13 or 14, wherein the method comprises:  
generating, by the ophthalmic surgical system, a pseudo color map representative of a  
probability of the location of the retinal break; and  
20 providing the pseudo color map to a display.

17. The method according to any one of claims 13 to 16, wherein the method comprises  
providing tactile or haptic feedback indicating the location of the probable retinal break.

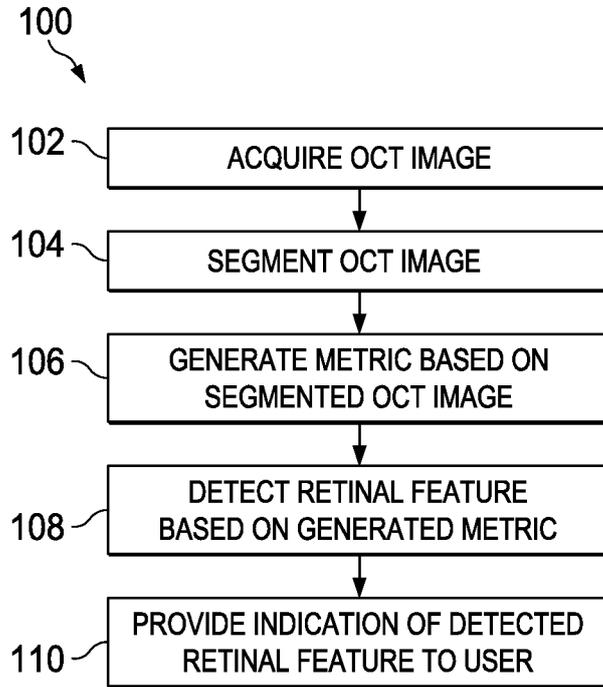


Fig. 1

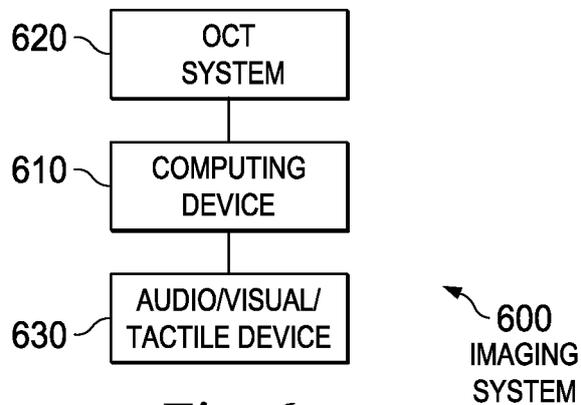


Fig. 6

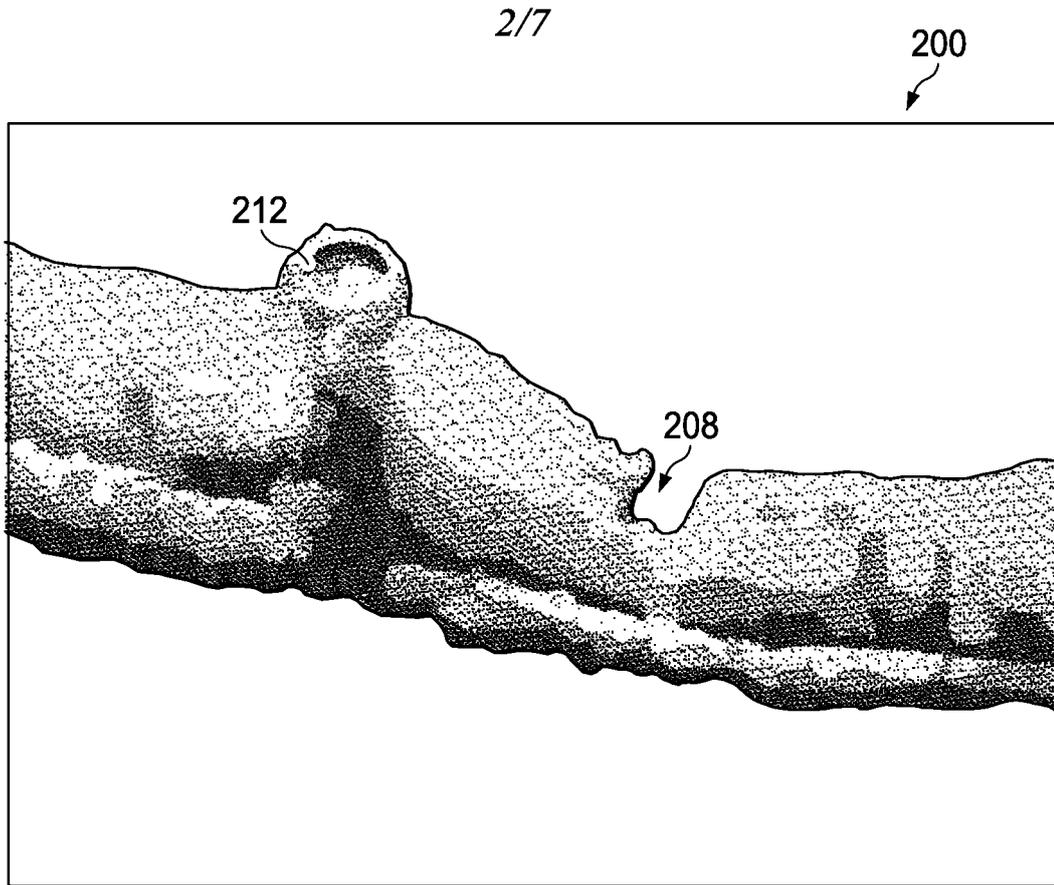


Fig. 2a

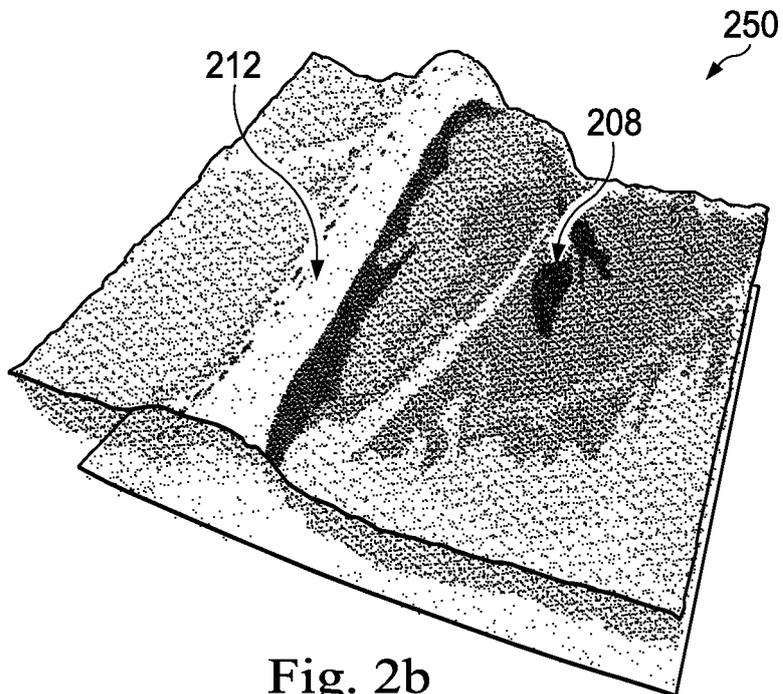


Fig. 2b

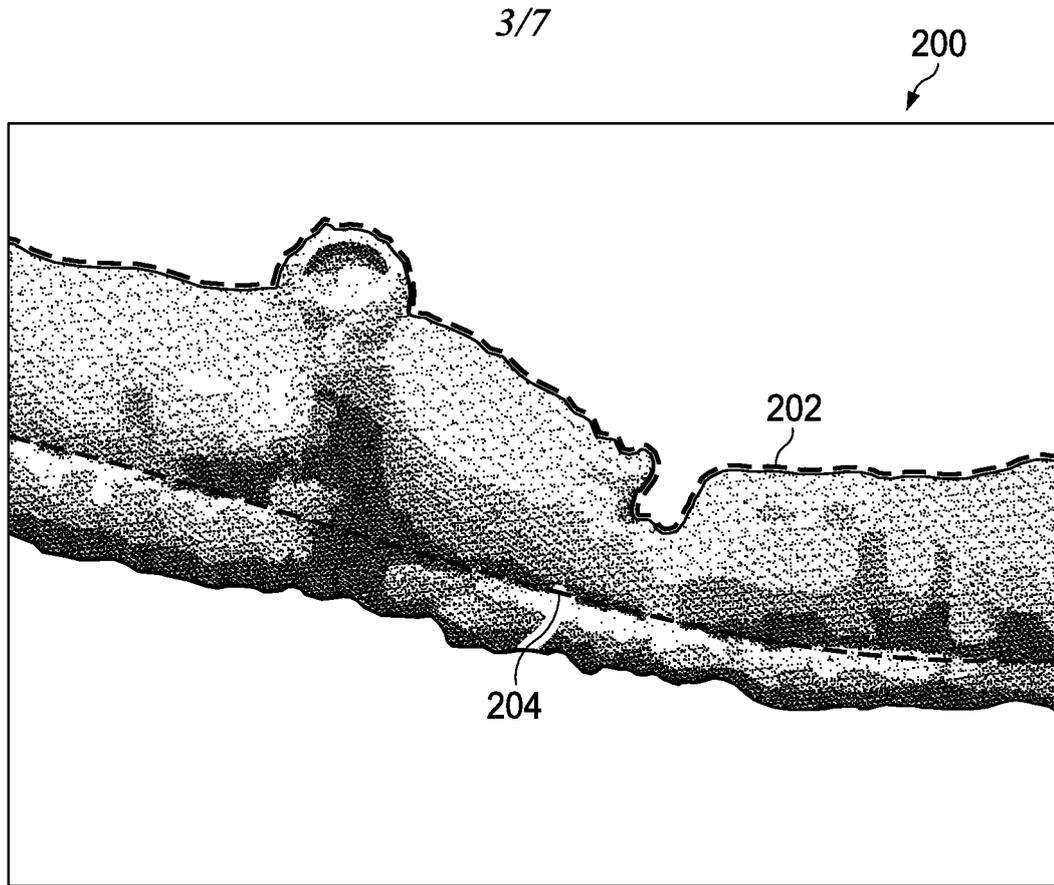


Fig. 3a

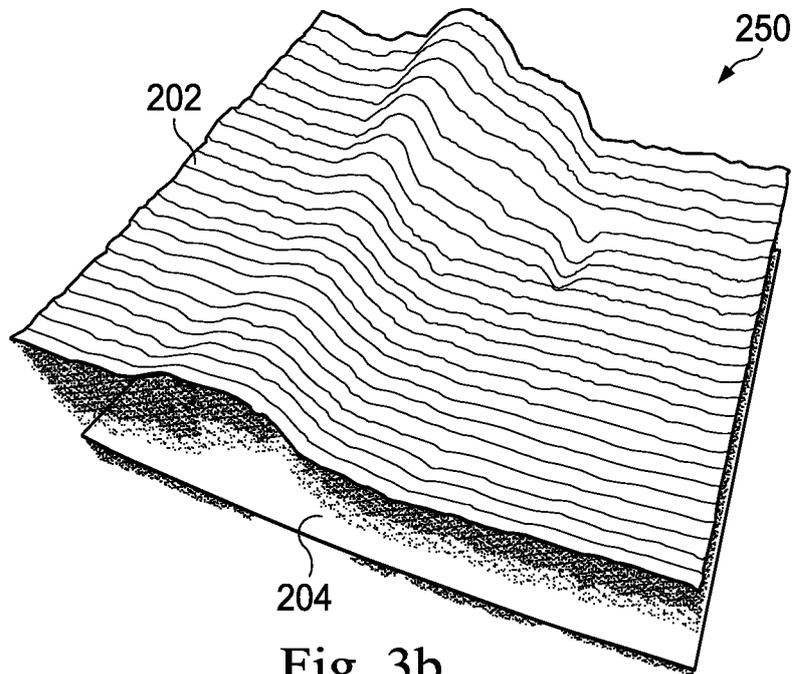


Fig. 3b

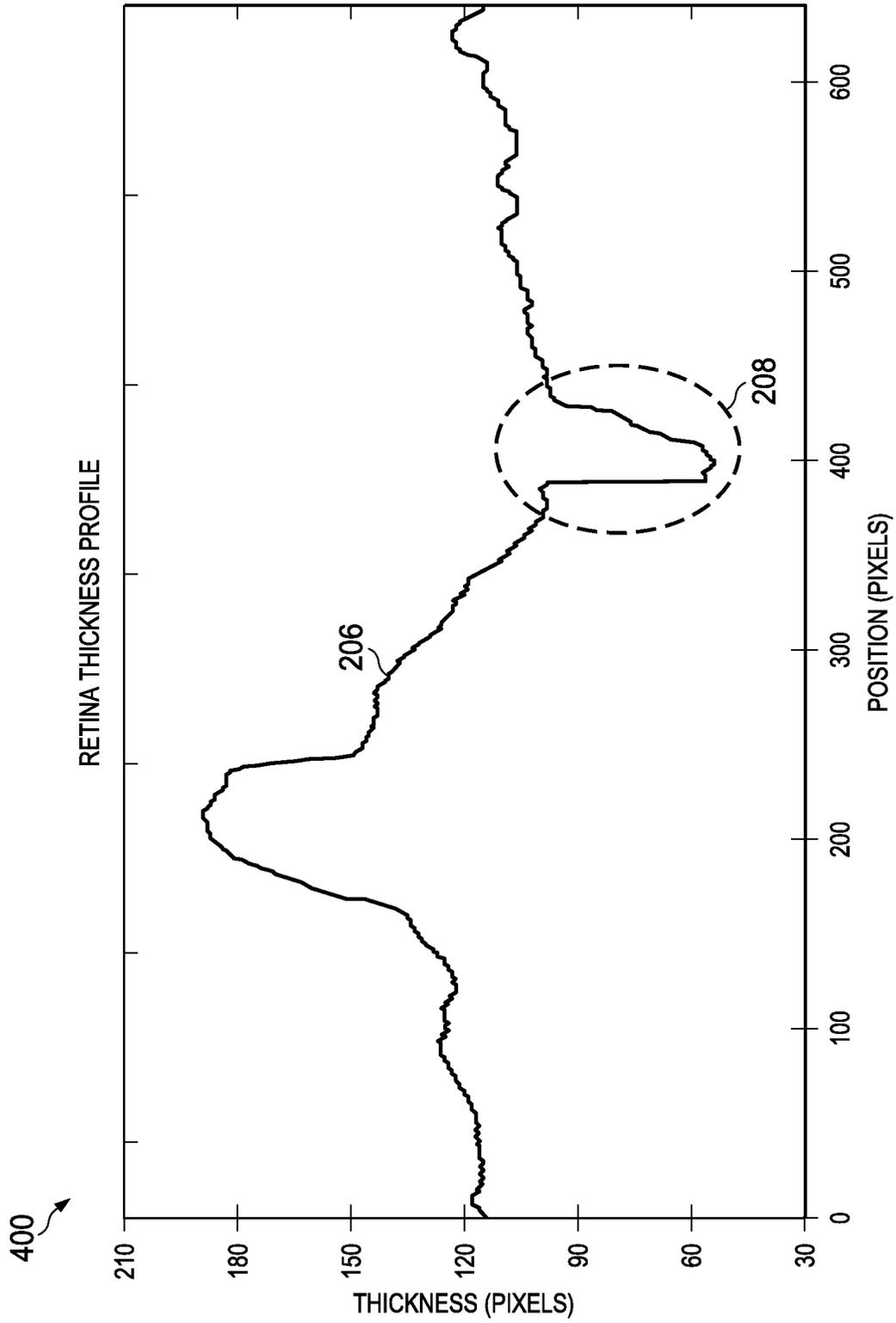


Fig. 4

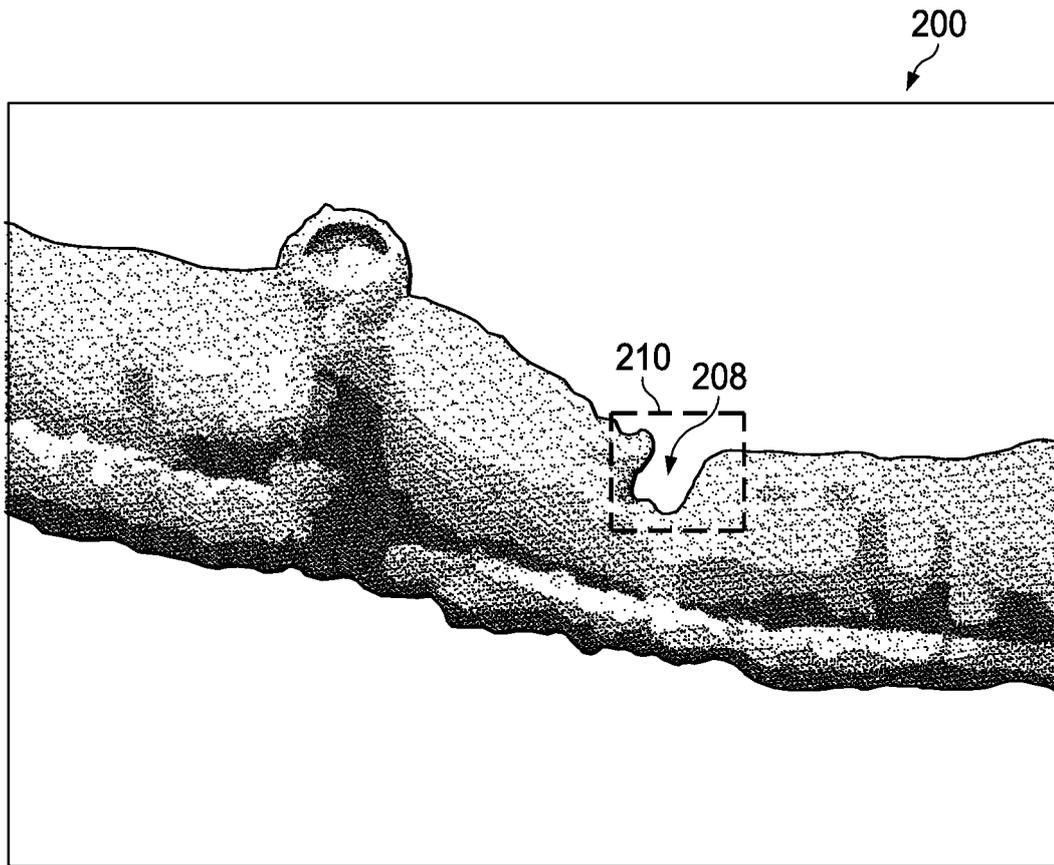


Fig. 5a

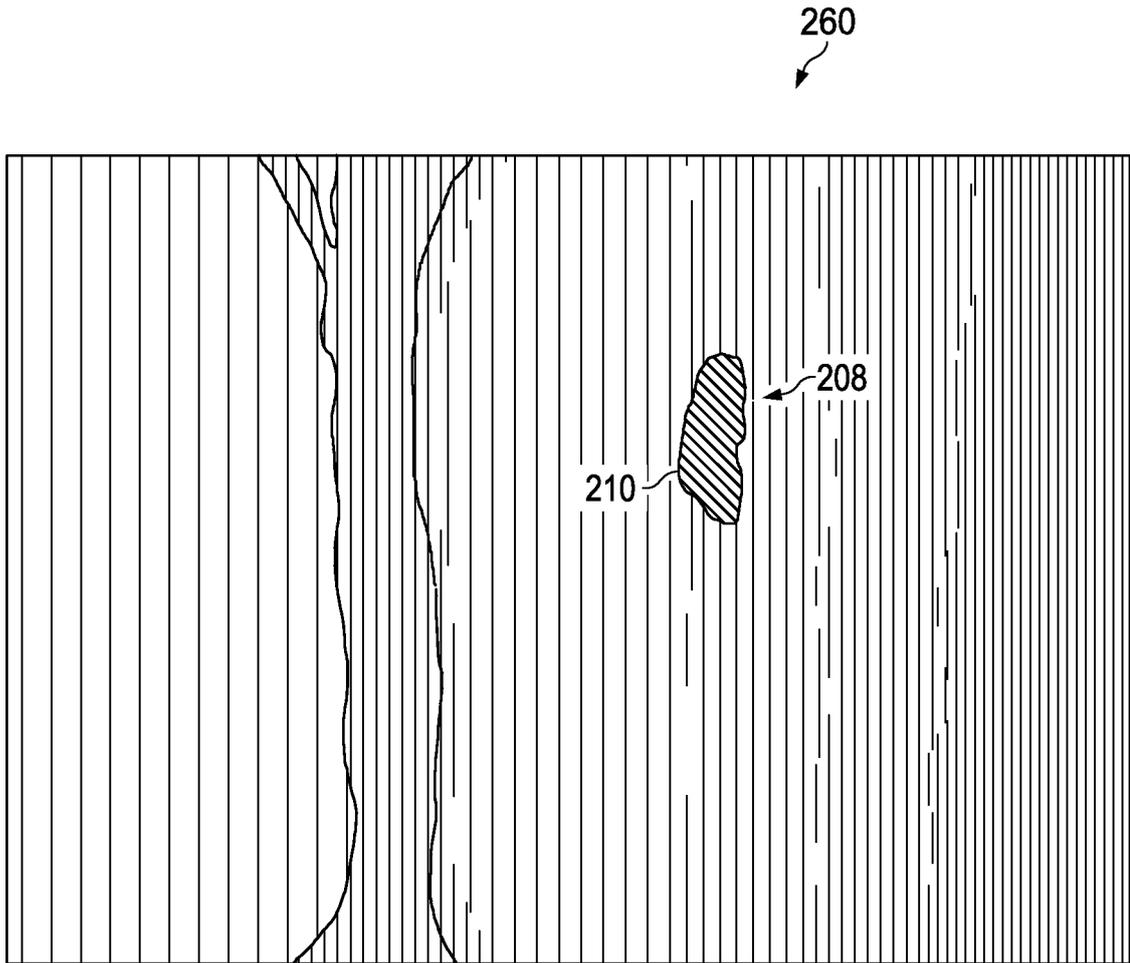


Fig. 5b

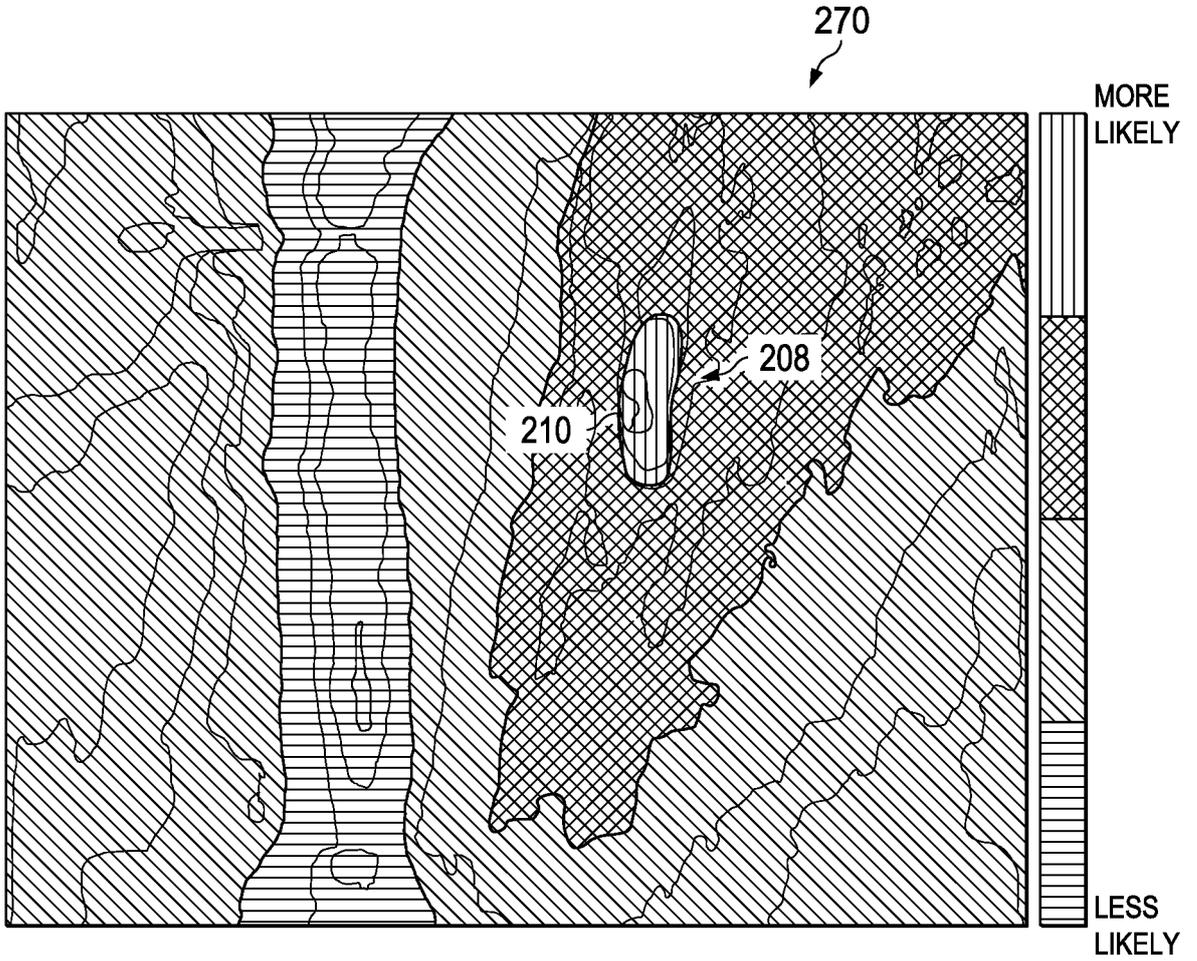


Fig. 5c

200

