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(54) Title: ACOUSTICAL FLUID CONTROL MECHANISM

(57) Abstract: An acoustical fluid control mechanism and a method of controlling fluid flow of a working fluid with the acoustical fluid control mechanism are provided. The mechanism comprises a resonance chamber that defines a cavity. The resonance chamber has a port. The cavity is sealed from the ambient but for the port for enabling oscillatory flow of a working fluid into and out of the cavity upon exposure of the resonance chamber to an acoustic signal containing a tone at a frequency that is substantially similar to a particular resonance frequency of the resonance chamber. The mechanism further includes a rectifier for introducing directional bias to the oscillatory flow of the working fluid through the port. The rectifier has an inlet connected to the port and an outlet for transmitting the directional flow of the working fluid away from the cavity. The outlet is in fluid communication with the port of the resonance chamber at least during transmission of the directional flow of the working fluid therethrough.



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ACOUSTICAL FLUID CONTROL MECHANISM

Cross-Reference to Related Applications

[0001] This application claims priority to and all the advantages of U.S. Provisional Patent Application No. 61/199,290, filed on November 14, 2008.

Government Licensing Rights

[0002] This invention was made with government support under grant number AI049541 awarded by the National Institute of Health. The government has certain rights in the invention.

Background of the Invention

1. Field of the Invention

[0003] The instant invention generally relates to a fluid control mechanism by which the frequency constituents within an acoustic signal are converted to a useful working output. More specifically, the instant invention relates to a fluid control mechanism including a resonance chamber that produces oscillatory flow of a working fluid in response to exposure to an acoustic signal.

2. Description of the Related Art

[0004] A wide variety of actuating technologies have been developed for use in miniaturized systems for the life sciences including integrated microfluidic system. For example, the integrated microfluidic systems may be used to produce microgradients of liquid reagents and samples. The microgradients of the liquid reagents and samples may be utilized for understanding many of nature's developmental processes.

[0005] Control and transport of the liquid reagents and samples are difficulties that are often encountered with the integrated microfluidic systems. Most known integrated microfluidic systems rely heavily upon external liquid or air pressure to

transport the liquid reagents and samples between dedicated fluidic unit operations in the systems. Use of the external liquid or air pressure often requires the use of extensive external control equipment, and difficulties with control of fluid flow often arise due to the use of multiple pumps dedicated to each fluidic unit.

[0006] Manipulation or control of discrete fluid droplets has been performed using air pressure with careful attention paid to a magnitude of the pressure gradient as most pressure regulators are not configured or designed to output minute pressure differences that are needed for precise in vivo droplet control. A related approach to droplet control employs intermittent pulsing of a coarsely regulated pressure source to precisely position droplets. Another approach that has been taken with regard to distributed pressure control utilizes micro-machined Venturi pressure regulators. Hybrid schemes employing both displacement and direct pressure are also possible, most notably, for use in serial deflection of elastomeric membranes. With this approach, multiplexed pressure control is feasible, but the number of external connections and control equipment required to operate a reasonably complex integrated microfluidic system is prohibitively large in size, and such an approach also requires high power actuation schemes.

[0007] The dependence on external liquid or air pressure is becoming increasingly problematic with the push towards integrated microfluidic systems, which can include thousands of independent pressure regulators. Additionally, the lack of low power actuation schemes has, in part, hindered the use of the systems for various applications.

[0008] Fluid control schemes that utilize acoustics are known in areas ranging from fluid transport, mixing, separations, and droplet levitation. Two relevant fluid control schemes utilizing acoustics are acoustic streaming and surface acoustic waves (SAW).

Acoustic streaming, also known as quartz wind, is a phenomenon by which a steady momentum flux is imparted to a fluid due to the impingement of high amplitude acoustic waves. Bulk motion of the fluid results from a build up of a non-linear viscous Reynolds stress. However, due to an intolerance to back pressure, microfluidic applications using acoustic streaming have thus far been limited primarily to driving closed-loop fluid circuits. SAWs, on the other hand, operate principally on an open planar surface rather than within a closed channel. Surface confined acoustic waves can be launched within piezoelectric substrates by applying resonant frequencies to sets of interdigitated electrodes with the resonance frequencies determined by electrode spacing. SAWs are launched perpendicular to the electrodes and decay rapidly with substrate depth but decay negligibly in the direction of propagation. Surface bound droplets in the path of a SAW undergo a rolling motion due to acoustic streaming that occurs at a leading pinned meniscus of the droplet. As such, SAWs can be used to position droplets arbitrarily along lines of intersecting electrode paths.

[0009] One limitation to the use of SAWs, in addition to potential limitations introduced from use of an open platform (such as reagent and sample storage, evaporation losses, contamination), is fabricating the numbers of electrodes necessary for precise droplet placement.

[0010] Another type of fluid control scheme that utilizes acoustics is an acoustic compressor. In acoustic compressors, the exposure of a resonance chamber to an acoustic signal containing a tone at a frequency that is substantially similar to the resonance frequency of the resonance chamber creates pressure oscillations within a gas-filled cavity of the resonance chamber. These pressure oscillations have been typically converted into compression and flow by reed valves that are attached to the

resonance chamber. The gas oscillates back and forth in the cavity, alternately compressing and rarifying the gas. The displacement of this gas can be changed by varying the power input, thus resulting in variable pumping capacity. However, the acoustic compressors require an inlet and an outlet to the resonance chamber to avoid buildup of pressure in the resonance chamber. Further, the acoustic compressors generally require a large size of the cavity to keep the operating frequencies within the range of practical reed valves. As such, acoustic compressors tend to be physically large for a given pumping capacity, when compared to other types of compressors, which is especially detrimental for microfluidic systems.

[0011] Due to the deficiencies of known schemes used to control fluid flow in integrated microfluidic systems, there is an opportunity to develop new schemes that overcome such deficiencies.

Summary of the Invention and Advantages

[0012] The subject invention provides an acoustical fluid control mechanism and a method of controlling fluid flow of a working fluid with the acoustical fluid control mechanism. The mechanism comprises a resonance chamber that defines a cavity. The resonance chamber has a port. The cavity is sealed from the ambient but for the port for enabling oscillatory flow of a working fluid into and out of the cavity upon exposure of the resonance chamber to an acoustic signal containing a tone at a frequency that is substantially similar to a particular resonance frequency of the resonance chamber. The mechanism further includes a rectifier for introducing directional bias to the oscillatory flow of the working fluid through the port. The rectifier has an inlet connected to the port of the resonance chamber for receiving the oscillatory flow of the working fluid from the port. The rectifier further includes an outlet for transmitting the directional flow of the working fluid away from the cavity.

The outlet is in fluid communication with the port of the resonance chamber at least during transmission of the directional flow of the working fluid therethrough.

[0013] The method of controlling fluid flow of the working fluid with the acoustical fluid control mechanism includes the step of exposing the resonance chamber to an acoustic signal containing a tone at a particular frequency of the resonance chamber to produce oscillatory flow of the working fluid into and out of the cavity of the resonance chamber through the port, with the rectifier thereby introducing directional bias to the oscillatory flow of the working fluid through the port. As a result of the rectifier introducing directional bias to the oscillatory flow of the working fluid, the directional flow of the working fluid is transmitted away from the cavity and through the outlet of the rectifier.

[0014] The mechanism provided herein presents many advantages. For example, the resonance chamber has a particular resonance frequency at which oscillatory flow of the working fluid is maximized. In this regard, the directional flow of the working fluid transmitted through the outlet of the rectifier connected thereto can be precisely controlled by providing an acoustic signal containing a tone at a frequency that is either substantially similar to or substantially different than the resonance frequency of the resonance chamber. Further, a bank of resonance chambers can be provided, with each resonance chamber having a sufficiently different resonance frequency to enable precise control of the conditions under which directional flow of the working fluid is transmitted through the outlets of rectifiers connected to the respective resonance chambers by simply controlling tones contained in the acoustic signal. Because each resonance chamber has a particular resonance frequency near which oscillatory flow of the working fluid can be maximized, directional flow attributable to a particular resonance chamber can be effectuated while substantially eliminating

directional flow that would be attributable to other resonance chambers by controlling the frequency and amplitude of a particular tone or combination of tones contained by the acoustic signal at any point in time.

BRIEF DESCRIPTION OF THE FIGURES

[0015] Other advantages of the present invention will be readily appreciated, as the same becomes better understood by reference to the following detailed description when considered in connection with the accompanying drawings wherein:

[0016] Figure 1 is a perspective schematic view of the acoustical fluid control mechanism comprising a resonance chamber and a rectifier connected thereto;

[0017] Figure 2 provides two graphs that illustrate exemplary resonance properties of the acoustical fluid control mechanism. Figure 2(a) is an acoustic resonance spectrograph representing the acoustic response of various resonance chambers when exposed to an acoustic signal containing tones at a steadily ramped frequency at constant amplitude. Resonance chambers 1-4 have a resonance frequency at 404 Hz, 484 Hz, 532 Hz and 654 Hz respectively. Figure 2(b) illustrates two-dimensional FEM results for a resonance chamber having a resonance frequency at 860 Hz, illustrating the effect of radiation loss on the quality of resonance, Q , for aspect ratios of a diameter of the resonance chamber to a diameter of the port of 2.3, 4.6, 7.7, 11.5, and 23;

[0018] Figure 3 illustrates various embodiments of rectifiers in accordance with the instant invention, with each rectifier having an intersecting junction with an inlet, an outlet, and a pair of vents meeting at the intersecting junction and with the inlet and outlet disposed opposite to each other across the intersecting junction;

[0019] Figure 4 provides a graph illustrating directional asymmetry of the rectifier shown in Figure 3a; known pressure loads were applied to the inlet of the rectifier, outlet flow rate versus inlet pressure shows the marked asymmetry, as shown by the shaded rectangles, across zero gauge pressure. The vertically tiled images on the right side of Figure 4 are pictorial representations of two-dimensional incompressible flow simulation results illustrating rectifier asymmetry in terms of a difference in flow field. The top two images show a reversible viscous dominant flow field for a pressure load of $1e^{-6}$ kPa. The bottom two images, illustrating an inertial dominant flow field, reflect the emergence of an asymmetry in the flow field already well established at a pressure load of 0.01 kPa. Asymmetry results from flow separation and jetting due the build up of adverse pressure at a mouth of the inlet into an intersecting junction;

[0020] Figure 5 provides a graph illustrating the results of three-dimensional transient simulation of accumulated directional flow through the outlet of a rectifier having a ratio of inlet diameter to outlet diameter of 0.5, with a 500 micron depth, with an inlet pressure amplitude of 1 kPa at a frequency of 1 kHz;

[0021] Figure 6 is an exploded perspective schematic view of an embodiment of the acoustical fluid control mechanism comprising an acoustic source, a common air chamber, a vented cover plate, and four resonance chambers with rectifiers attached thereto;

[0022] Figure 7 illustrates exemplary resonance frequencies for four different resonance chambers mapped onto the chromatic scale. The chromatic scale is based on A4 at 440 Hz;

[0023] Figure 8 presents a set of graphs representing a looped acoustic signal containing a sequence of tones and an inset (top) illustrating programmed droplet

motion experiments corresponding to the acoustic signal. The inset (top) presents three images depicting droplet motion at different points in the looped acoustic signal. The middle graph represents the looped acoustic signal by approximate frequency positions on the chromatic scale. The bottom graph represents induced droplet velocity as a function of time and illustrates programmed actuation of specific droplets in response to exposure of the various resonance chambers to the acoustic signal containing the tones shown in the chromatic scale of the middle graph. Droplets are actuated singly or in concert, based on the tones contained in the acoustic signal.

Detailed Description of the Invention

[0024] Referring to the Figures, wherein like numerals indicate like or corresponding parts, an acoustical fluid control mechanism **10** is generally shown at 10 in Figure 1. The acoustical fluid control mechanism **10** of the instant invention includes a resonance chamber **12** and, more typically, includes a bank of resonance chambers **12** as shown in Figure 6. Each resonance chamber **12** defines a cavity **14**. The resonance chamber **12** (or bank of resonance chambers **12**) is designed using principles of resonance and has a geometry that corresponds to a particular resonance frequency. For example, the resonance chamber(s) **12** can be designed using principles of standing wave resonance or Helmholtz resonance, both of which are known in the art. As also known in the art, “resonance frequency” refers to a frequency at which a system tends to oscillate at a larger amplitude than at other frequencies, and typically represents the frequency or frequencies at which maximum oscillation of the system occurs due to principles of standing wave resonance. When the bank of acoustic resonance chamber **12** is used, the resonance chambers **12** have different resonance frequencies, with differences between the resonance frequencies of the various

resonance chambers **12** engineered to avoid peak overlap. In one embodiment, a peak resonance frequency of any of the resonance chambers **12** is different by at least 10 Hz from a peak resonance frequency of any other of the resonance chambers **12**. Typically, the resonance chambers **12** used in accordance with the instant invention are quarter-wavelength resonance chambers **12**, which have a resonance frequency at a wavelength that is equal to four times an axial length of the cavity **14** (in metric units) in the resonance chamber **12**. The resonance frequency of the resonance chambers **12** is not limited to any particular value or range, with useful resonance frequencies dependent upon factors such as size constraints of the resonance chamber **12** required for a given application. However, in one example, the resonance chamber(s) **12** has/have a resonance frequency in a range of from about 400 to about 1250 Hz. When the bank of resonance chambers **12** is used, each resonance chamber **12** typically responds to exactly one narrow non-overlapping band of frequencies within a range of resonance frequencies. For example, when the range of resonance frequencies is from about 400 to about 1250 Hz as set forth above, the resonance chambers **12** may have resonance frequencies having an average peak width of about 21 +/- 10 Hz, with differences in peak resonance frequencies between any of the resonance chambers **12** typically being at least 10 Hz. The spacing of the non-overlapping band of frequencies determines, for a limited frequency range, the number of possible independent pressure lines that can be controlled. For example, by using an average peak width of 21 +/- 10 Hz, the number of resonance chambers **12** that can theoretically be controlled within the range of resonance frequencies set forth above is 38 +/- 18. As such, the bank of resonance chambers **12** that operate within the band of frequencies of from about 400 to about 1250 Hz may include up to about 56 individual resonance chambers **12**.

[0025] The resonance chambers **12** may be in the form of cylinders, but it is possible that the resonance chambers **12** can have other shapes, such as a rectangular box shape, depending upon the intended use of the acoustical fluid control mechanism **10**. Material used to form the resonance chambers **12** is somewhat insignificant. However, the resonance chambers **12** are typically formed from a relatively rigid material such as glass, silicon, or rigid polymeric materials that will reflect and not attenuate incident sound waves. In one specific example, the resonance chambers **12** may be formed from borosilicate glass. The resonance chambers **12** are not limited to any particular size. However, it is notable that the resonance chambers **12** are useful in microfluidic systems and, therefore, may have relatively small sizes. For example, in accordance with specific embodiments of the acoustical fluid control mechanism **10** of the instant invention, the resonance chambers **12** may be formed from 47 mm ID, 51 mm OD, borosilicate tube stock cut to 192 mm, 156 mm, 141 mm, and 111 mm respectively (for a mechanism **10** in which the bank of resonance chambers **12** are utilized as shown in Figure 6). It is also to be appreciated that the resonance chambers **12** can be scaled down for use in the microfluidic systems.

[0026] Each resonance chamber **12** has a port **16**, with the cavity **14** sealed from the ambient but for the port **16** for enabling oscillatory flow of a working fluid, such as a gas or liquid, into and out of the cavity **14** upon exposure of the resonance chamber **12** to an acoustic signal **18** containing a tone at a particular frequency that is substantially similar to the resonance frequency of the resonance chamber **12**. The acoustic signal **18**, as used herein, is a mechanical vibration propagated through a medium and need not be audible to the human ear. The frequency of the tone is dependent upon the resonance frequency of the corresponding resonance chamber **12**. Thus, for the example provided above in which the resonance chamber(s) **12** has/have

resonance frequencies within the range of about 400 to about 1250 Hz, the acoustic signal **18** contains the tone or tones within the frequency range of from about 400 to about 1250 Hz. For purposes of the instant application, a frequency that is “substantially similar” to the resonance frequency of a particular resonance chamber **12** refers to a frequency that is sufficient to effectuate oscillation of the working fluid into and out of the port **16** of the resonance chamber **12**. Typically, the “substantially similar” frequency refers to a frequency within about 5 +/- Hz of the peak resonance frequency of the resonance chamber **12**. However, it is to be appreciated that the frequency of the tone that is necessary to effectuate oscillation may be dependent upon various factors, such as quality of resonance. Quality of resonance is described in further detail below.

[0027] Oscillation of the resonance chamber **12** results in oscillatory flow into and out of the cavity **14** through the port **16** due to pressure differentials created by the oscillation of the resonance chamber **12**. While the port **16** is typically located along a center axis of the resonance chamber **12** in the direction of a longest dimension thereof, the instant invention is not limited to a particular location of the port **16**. A size of the port **16** is dependent upon the size of the resonance chamber **12**, and the operative metric is generally a ratio of a cross-sectional area of the resonance chamber **12** to a cross-sectional area of the port **16**. The “cross-sectional area” refers to the cross-sectional area of the portions of the resonance chamber **12** and the port **16** bound by inner surfaces thereof. In other words, the “cross-sectional area of the resonance chamber **12**” effectively refers to the cross-sectional area of the cavity **14** that is defined by the resonance chamber **12**. Figure 2 illustrates the significance of the ratio of the cross-sectional area of the resonance chamber **12** to the cross-sectional area of the port **16** as it relates to normalized port **16** pressure during oscillatory flow

therethrough, with higher ratios corresponding to higher normalized pressures out of the port **16**. Resonance spectrographs, shown in Figure 2a, were created to identify the location of the resonance frequency of sample resonance chambers **12**. The emergence of highly amplified spikes in outlet **24** flow corresponds to a standing wave resonance event **26** unique to each resonance chamber **12**. Figure 2(b) illustrates the results of two-dimensional finite element analysis (FEM) based upon the variables “a” and “b”, which correspond to the diameters of the resonance chamber **12** and the port **16**, assuming perfectly circular shapes for both the resonance chamber **12** and the port **16**. The ratio of the cross-sectional area of the resonance chamber **12** to the cross-sectional area of the port **16** has an effect on quality of resonance, Q , as illustrated in the inset of Figure 2(b). As known in the art, higher Q values correlates to a lower rate of energy loss relative to the stored energy of the resonance chamber **12** during oscillation thereof; the oscillations die out more slowly. As such, higher Q values correlate to sharp resonance peaks and a requirement of less power of the acoustic signal **18** to achieve oscillation in the resonance chamber **12**. Therefore, high Q values contribute to enhanced performance of the acoustical fluid control mechanism **10**, which may be a particularly important consideration when the acoustical fluid control mechanism **10** is used in microfluidic systems. The ratio of the cross-sectional area of the resonance chamber **12** to the cross-sectional area of the port **16** is typically at least 4.0:1, more typically from about 4.6 to about 25, for purposes of maximizing the Q value. In one specific example, such as for the specific resonance chambers **12** set forth above having an inner diameter of 47 mm, the port **16** may have an inner diameter of about 2 mm and an outer diameter of about 6 mm, which results in a high ratio of “a” to “b” of about 23.5..

[0028] Referring to Figure 1, the acoustical fluid control mechanism **10** also includes a rectifier **20** for introducing directional bias to the oscillatory flow of the working fluid through the port **16**. The rectifier **20** has an inlet **22** connected to the port **16** of the resonance chamber **12** for receiving the oscillatory flow of the working fluid from the port **16** to form a resonance chamber **12**-rectifier **20** pair. The “port **16**”, as referred to herein and as shown in the Figures, refers to an opening defined in the resonance chamber **12**, while the “inlet **22**”, as referred to herein and as shown in the Figures, generally refers to external structures that extend from the resonance chamber **12**. However, it is to be appreciated that the resonance chamber **12** may include external structures that facilitate connection of the inlet **22** of the rectifier **20** to the port **16** of the resonance chamber **12**, such as the schematic structure shown in the inset of Figure 2(b). The rectifier **20** also has an outlet **24** for transmitting the directional flow of the working fluid away from the cavity **14**. The directional bias is the result of the imposition of less hydraulic resistance to the oscillatory flow of the working fluid in one direction, such as in the direction away from the cavity **14** in the context of the instant invention, to thereby introduce the directional bias to the oscillatory flow of the working fluid. The directional bias can be introduced either mechanically, such as through use of a check or flap valve (not shown), or by utilizing physical properties of the working fluid. Regardless of how the directional bias is imposed, the outlet **24** is in fluid communication with the port **16** of the resonance chamber **12** at least during transmission of the directional flow of the working fluid therethrough. In other words, directional flow of the working fluid through the outlet **24** is not the result of oscillatory actuation of a diaphragm, but rather the directional flow of the working fluid represents propagation of the fluid flow from the port **16** of the resonance chamber **12** through the rectifier **20**.

[0029] Referring primarily to Figure 3, in one embodiment the rectifier **20** is further defined as an inertial fluidic rectifier **20**, in which hydraulic resistance is reduced by way of a vent **26**. More specifically, in this embodiment, the rectifier **20** includes an intersecting junction **28** with the inlet **22**, the outlet **24**, and the vent **26** meeting at the intersecting junction **28**. The vent **26** is typically open to the ambient for enabling free flow of the working fluid into and out of the rectifier **20**. While Figures 3a through 3d each illustrate the rectifier **20** as having two vents **26**, it is to be appreciated that the rectifier **20** may include a single vent **26** without compromising operation thereof. In the embodiments of Figures 3a through 3d, the inlet **22** and outlet **24** are disposed opposite to each other across the intersecting junction **28**, and the two vents **26** are also disposed opposite each other across the junction **28**. Referring to Figure 3a, in one embodiment, the inlet **22** of the rectifier **20** has a smaller cross-sectional area than the outlet **24**, which results in higher Q values under some circumstances. However, it is to be appreciated that the inlet **22** may have the same cross-sectional area as the cross-sectional area of the outlet **24** as shown in Figure 3b. In any event **26**, a ratio of cross-sectional area of the inlet **22** to cross-sectional area of the outlet **24** is typically from about 0.1:1 to about 1:1, alternatively from about 0.5:1 to about 1:1. The inlet **22** typically has the same cross-sectional area as the port **16**, and typically has a constant cross-sectional area along the length thereof. However, it is to be appreciated that the inlet **22** may be tapered in some embodiments, as shown in Figure 3c. In one specific example, the inlet **22** may have a constant cross-sectional area with an inner diameter of about 2 mm which extends slightly into the confluence of a three way intersecting junction **28** formed from fusing three lengths of 4mm ID, 6 mm OD glass tubing, with the three lengths of 4 mm ID tubing forming two vents **26** and the outlet **24**.

[0030] While there are no particular limitations as to the size or dimensions of the vent **26**, a cross-sectional area of a mouth **30** of the vent **26** that opens to the intersecting junction **28** is typically about equal to the cross-sectional area of the outlet **24**. However, as shown in Figures 3c and 3d, it is to be appreciated that the cross-sectional area of the mouth **30** of the vent **26** can be smaller than the cross-sectional area of the outlet **24**. Typically, a ratio of cross-sectional area of the mouth **30** of the vent **26** to cross-sectional area of the outlet **24** is from about 0.1:1 to about 1:1. When lower ratios of cross-sectional area of the mouth **30** of the vent **26** to cross-sectional area of the outlet **24** are employed, the amount of accumulated flow transferred to the outlet **24** of the rectifier **20** during oscillatory flow is lessened as more of the working fluid during the expansion portion of the oscillatory cycle is supplied by the outlet **24** port **16**. As such, it is desirable to maximize the cross-sectional area of the mouth **30** of the vent **26** to the cross-sectional area of the outlet **24**, while ensuring that the ratio is not so high as to prevent **26** the working fluid from flowing into the outlet **24**, which flow dynamics are described in further detail below.

[0031] Resistance to flow of the working fluid from the inlet **22** into the intersecting junction **28** is minimized by providing the vent **26** and the outlet **24** having the cross-sectional area that is at least equal to the cross-sectional area of the inlet **22**. As such, the working fluid flows relatively easily into the intersecting junction **28** from the inlet **22** as compared to flow of the working fluid from the outlet **24** into the intersecting junction **28**. More specifically, upon compression of the resonance chamber **12**, the working fluid is forced out of the cavity **14** through the port **16** and into the inlet **22** of the rectifier **20**. During expansion of the resonance chamber **12**, the working fluid is pulled back into the cavity **14** of the resonance chamber **12** through the inlet **22** and the port **16**. Due to the presence of the vent **26**, working fluid

is available to the inlet **22** from both the vent **26** and the outlet **24** during expansion of the resonance chamber **12**, resulting in less working fluid flowing into the inlet **22** from the outlet **24** as compared to fluid flowing into the outlet **24** from the inlet **22** during compression of the resonance chamber **12**. Such flow dynamics are exploited to result in accumulated flow toward the outlet **24**, thereby introducing the directional bias to the oscillatory flow of the working fluid into and out of the cavity **14**.

[0032] Due to the presence of the vent **26**, fluid flow of the working fluid is engineered to direct flow of the working fluid into the outlet **24** across the intersecting junction **28** instead of into the vent **26**. In this regard, the relative positions of the inlet **22**, outlet **24**, and vent **26** are relevant. To explain, oscillatory flow of the working fluid may have an inertial dominant flow field based upon a number of factors including dimensions of the resonance chamber **12** and inlet **22** of the rectifier **20**, as well as the strength of the acoustic signal **18**. The inertial dominant flow field may be quantified by a Reynold's number, which is indicative of a ratio of the inertial forces compared to viscous forces. The inertial dominant flow field typically has a high Reynold's number of at least 1, alternatively at least 10, alternatively at least 100. The inertial dominant flow field has a unique property in that it resists turning corners. As such, when the inlet **22** and outlet **24** are disposed opposite to each other across the intersecting junction **28**, the inertia of the working fluid flowing through the inlet **22** at the high Reynold's number forms a synthetic jet of the working fluid across the intersecting junction **28** and into the outlet **24**, while bypassing the vent **26** or vents **26**. Such phenomenon can be observed in the bottom vertically tiled image on the right side of Figure 4.

[0033] Both experimental (represented by the graph on the left side of Figure 4) and simulated performance (represented by the vertically tiled images on the right side of

Figure 4) of the inertial fluidic rectifier **20** is illustrated in terms of fluid outflow rate from the rectifier **20** when subjected to equidistant pressures on either side of zero gauge pressure (the term “pressure swing” will henceforth be used to describe such a pair of pressures equidistant from zero gauge pressure). For positive gauge pressures, air may be supplied through the vent **26(s)** using a mass flow controller (MKS, 11598B-05000SV). For negative gauge pressure, a vacuum may be applied through the vent **26(s)** using a two stage vacuum regulator in conjunction **28** with a vacuum source **32**. In each case, pressure of the working fluid at the inlet **22** may be monitored with a strain gauge (Omega, DP-25B-S) extending from a T-junction **28** (not shown) just prior to the inlet **22** of the rectifier **20**, and the resulting flow rate of the working fluid through the outlet **24** may be measured using a hot wire anemometer.

[0034] The experimentally obtained flow bias, for a pressure swing of 0.1 kPa, which correlates to a Reynold’s number of about 100 for the system shown in Figure 4, is illustrated for the inertial fluidic rectifier **20** by a pair of dissimilar blue shaded rectangles overlayed on the graph on the left side of Figure 4 where the larger rectangle, for the case of positive applied pressure, represents the preferred flow direction. The vertically tiled images on the right side of Figure 4 provide finite element method (FEM) simulation results for a simplified two-dimensional rectifier **20** of the same dimensions as the rectifier **20** whose simulated performance is illustrated in the graph of Figure 4, and suggest the cause of the directional bias to be a difference in the resulting flow field for positive and negative inlet **22** pressures. For extremely low inlet **22** pressure swings, which correspond to working fluid flow having low Reynold’s numbers of less than 1, the flow field is viscous dominant and perfectly reversible. Such flow is illustrated in the top two simulated images on the

right side of Figure 4, in which the Reynold's number is about 0.001, and is undesirable as no jet is formed with the flow of the working fluid from the inlet **22** into the outlet **24**. Conversely, for higher inlet **22** pressures, which correspond to working fluid flow having high Reynold's numbers of at least 1, the flow field is inertial dominant, which leads to the formation of the synthetic jet of fluid flowing from the inlet **22** of the rectifier **20** toward the outlet **24**. Such fluid flow is illustrated in the bottom two simulated images on the right side of Figure 4. Over the course of multiple pressure cycles, the flow asymmetry when higher inlet **22** pressures, and thus higher Reynold's numbers of at least 1, are used produces a net accumulation of fluid flow at the outlet **24** of the rectifier **20**. Figure 5 provides an exemplary illustration of the accumulation profile of fluid flow at the outlet **24** of the rectifier **20**. These results imply that by modulating pressure at the inlet **22** of the rectifier **20**, made possible in this case by imposing the condition of resonance to the particular resonance chamber **12**, fluid flow can be switched on and off at the outlet **24** of the rectifier **20**. More specifically, during operation of the acoustical fluid control mechanism **10**, the oscillating air pressure within the resonance chamber **12** serves as the input pressure to the rectifier **20**, and the jet produced at the intersecting junction **28** creates a net positive flow at the outlet **24** of the rectifier **20**.

[0035] As alluded to above, the directional bias can be introduced to the oscillatory flow of the working fluid through the port **16** either mechanically or by utilizing physical properties of the working fluid. For the embodiments of the rectifier **20** shown in Figures 3a-3d, as well as for the rectifier **20** that was used to generate the results shown in Figure 4, the rectifier **20** is free from moving parts, e.g. valves, and relies upon physical properties of the working fluid for introducing the directional bias to the oscillatory flow of the working fluid. However, it is to be appreciated that

the rectifier **20** may include additional mechanical features to assist with introducing the directional bias to the oscillatory flow of the working fluid.

[0036] The acoustical fluid control mechanism **10** may further comprise an acoustic source **32** for providing the acoustic signal **18** to the resonance chamber **12**. When the bank of resonance chambers **12** is used, the acoustic source **32** may provide the acoustic signal **18** to the bank of resonance chambers **12**. In this regard, a single acoustic source **32** may provide the acoustic signal **18** to the bank of resonance chambers **12**. However, it is to be appreciated that the acoustic source **32** may be an external component that is not necessarily part of the acoustical fluid control mechanism **10**. For example, a resonance chamber **12**-rectifier **20** pair or bank of resonance chamber **12**-rectifier **20** pairs may be provided as the entire acoustical fluid control mechanism **10**, with an external acoustic source **32** used to effectuate operation of the acoustical fluid control mechanism **10**.

[0037] Referring to Figure 6, the acoustic source **32** may include an audio amplifier and a mid-range audio speaker. For purposes of scaling the acoustical fluid control mechanism **10** down for use in microfluidic systems, the acoustic source **32** may include a miniature diaphragm driver or a piezoelectric material (both not shown). In any event **26**, the acoustic source **32** is capable of delivering an acoustic signal **18** containing a tone at a frequency that is substantially similar to the resonance frequency of the resonance chamber **12** at issue for purposes of effectuating oscillatory flow through the port **16**, and is typically capable of delivering a composite acoustic signal **18** containing multiple different tones of different frequencies, i.e., chords, for purposes of simultaneously controlling the directional flow of the working fluid from multiple resonance chambers **12** when the bank of resonance chambers **12** is used. Further, the acoustic source **32** is capable of providing the acoustic signal **18**

with sufficient strength to result in the resonance chamber **12** producing working fluid flow having an inertial dominant flow field. Those of skill in the art can readily determine an amplitude for the acoustic signal **18** to produce fluid flow having the desired Reynold's number.

[0038] When the bank of resonance chambers **12** is used, the acoustic signal **18** provided by the acoustic source **32** may be encoded to provide a sequence of tones for controlling fluid flow from the bank of resonance chambers **12**, thereby enabling control of fluid flow from multiple resonance chambers **12** through the single encoded acoustic signal **18**. In this regard, the tone contained in the acoustic signal **18** may be varied to independently control the directional flow of the working fluid from different resonance chambers **12**. In one exemplary embodiment, the acoustic signal **18** may be controlled on a desktop PC using a LabVIEW virtual instrument package. In this embodiment, generation of an analog output signal **18** may be done using a National Instruments analog IO board (PCI-6031E). The analog output signal **18** from the IO board may be amplified using the audio amplifier such as an AMP100 from AudioSource **32**. The amplified signal **18** may then be sent to a standard mid range audio speaker (e.g., a Pyle PDMW6 woofer) to thereby generate the acoustic signal **18** to which the resonance chamber(s) **12** is/are exposed. Components of the final assembled mechanism **10** may be bonded using an off the shelf RTV sealant.

[0039] Referring to Figure 6, a common air chamber **34** that defines an air cavity **36** may be disposed between the audio amplifier and the bank of resonance chambers **12** for purposes of uniting the acoustic source **32** and the resonance chambers **12**. However, it is to be appreciated that the common air chamber **34** may also be used when the acoustical fluid control mechanism **10** only includes a single resonance chamber **12**. The common air chamber **34** provides an air reservoir that each

resonance chamber **12** shares, and may be formed from glass. In one specific example, the common air chamber **34** may be formed from a 0.155 m segment of 0.152 m ID thick-walled glass. A cover plate **38** is typically disposed between the common air chamber **34** and resonance chamber(s) **12** to unite the same. In one specific embodiment, the cover plate **38** may be fabricated from a 0.155 m diameter, 0.01 m thick acrylic disc. Holes **40** may be formed in the cover plate **38** for mounting the resonance chamber(s) **12**, with the holes **40** having a diameter about equal to the outer diameter of the resonance chamber(s) **12**. Additionally, the cover plate **38** may define at least one vent hole **42** therein for preventing pressure buildup in the air cavity **36** of the common air chamber **34**. The vent holes **42** may also minimize pressure cross talk between the resonance chambers **12** when the bank of resonance chambers **12** is used. In one specific example, as shown in Figure 6, the cover plate **38** defines multiple vent holes **42**, which are typically smaller than the holes **40** for mounting the resonance chamber(s) **12**.

[0040] A method of controlling fluid flow of the working fluid with the acoustical fluid control mechanism **10** includes the step of exposing the resonance chamber **12** to the acoustic signal **18** containing the tone at about a particular resonance frequency of the resonance chamber **12** to produce oscillatory flow of the working fluid into and out of the cavity **14** of the resonance chamber **12** through the port **16**. The frequency of the tone is typically equal to the particular resonance frequency of the resonance chamber **12**. However, slight differences between the frequency of the tone and the particular resonance frequency of the resonance chamber **12** are acceptable so long as directional bias can be imparted to the resulting oscillatory flow of the working fluid by the rectifier **20**. Typically, a maximum difference between the frequency of the tone contained in the acoustic signal **18** and the particular resonance frequency of the

resonance chamber **12** to be exposed to the acoustic signal **18** is about 10 Hz. However, it is to be appreciated that the difference is highly dependent upon numerous factors, including strength of the acoustic signal **18**, proximity of the acoustic source **32** to the resonance chamber **12**, etc.

[0041] When the acoustical fluid control mechanism **10** includes the bank of resonance chambers **12**, the acoustical fluid control mechanism **10** is capable of converting the composite or encoded acoustic signal **18** into multiple buffered pressure outputs, similar to what occurs in fiber optic electronic communication, for simultaneously or sequentially controlling the directional flow of the working fluid from multiple resonance chambers **12**. Unlike known fluid control schemes, the acoustical fluid control mechanism **10** that includes the bank of resonance chambers **12** can independently regulate multiple output pressures from a single acoustic signal **18**.

[0042] In one specific application for which the acoustical fluid control mechanism **10** of the instant invention can be used, the outlet **24** of the rectifier **20** is connected to a fluidic channel containing a droplet **44** of liquid, and the directional flow of the working fluid from the outlet **24** of the rectifier **20** is used to actuate the droplet **44** contained in the fluidic channel. In this regard, the acoustical fluid control mechanism **10** of the instant invention can selectively actuate the droplet **44** in the fluidic channel using the acoustic signal **18** to control motion of the droplet **44** by way of the directional flow of the working fluid. When the bank of resonance chamber **12** is used, selective actuation of the droplets **44** may be accomplished using the composite or encoded acoustic signal **18** as described above. In one specific embodiment, the tones can be roughly correlated to notes on the chromatic scale as shown in Figure 7, effectively enabling a musical sequence to be used as the

composite or encoded acoustic signal **18**. The composite or encoded acoustic signal **18** is delivered to the bank of resonance chambers **12**, with each resonance chamber **12** including the rectifier **20** attached thereto. The resonance chamber **12**-rectifier **20** pairs decode the composite or encoded signal **18** into a set of discrete pneumatic signals **18**. For example, as shown in Figure 8, the composite or encoded acoustic signal **18** containing the sequence of tones, illustrated on the chromatic scale, is delivered to the resonance chamber **12**-rectifier **20** pairs using the computer and audio amplifier. The bank of resonance chambers **12** having different resonance frequencies (in this specific example, four cavities having resonance frequencies at 404 Hz, 484 Hz, 532 Hz and 654 Hz, respectively) is exposed to the composite or encoded acoustic signal **18**, and the outlet **24** flow rate of fluid from each resonance chamber **12**-rectifier **20** pair is monitored using a hot-wire anemometer (not shown). Even though all resonance chambers **12** are exposed to the same signal **18**, individual resonance chambers **12** selectively amplify the tones having the frequency that corresponds to the particular resonance frequency of the resonance chamber **12**. The rectifiers **20** attached to the respective resonance chambers **12** then introduce directional bias to the oscillatory flow of the working fluid, resulting in the transmission of directional flow of the working fluid through the outlet **24** of the rectifier **20**. The resonance chambers **12** are insensitive to the presence of other competing tones having frequencies different than the particular resonance frequency thereof, thereby enabling selective control of droplets **44** in different fluidic channels that are connected to different resonance chambers **12**.

[0043] As shown in the top images of Figure 8, the directional flow of the working fluid through the outlet **24** of the rectifier **20** for any particular resonance chamber **12**-rectifier **20** pair can be exploited to actuate the droplet **44** contained in the fluidic

channel. For the purpose of graphical clarity in Figure 8, as well as to demonstrate the flow control capabilities of the acoustical fluid control mechanism **10** of the instant invention, the output flow rate of each resonance chamber **12**-rectifier **20** pair was set to the same value in this specific example. In the Example illustrated by Figure 8, four resonance chamber **12**-rectifier **20** pairs were connected to four separate fluidic channels, respectively, with each fluidic channel having 1 mm inner diameter capillary channels. Each fluidic channel contained a droplet **44** of a liquid with a volume of about 3 micro liters. The liquid was water with added color, and there was no appreciable change in the viscosity of the water due to the added color. The droplets **44** were actuated by delivering the composite or encoded acoustic signal **18** comprising the sequence of tones to the resonance chamber **12**-rectifier **20** pairs, each tone having a frequency generally correlated to the resonance frequency of one of the resonance chambers **12** as shown in Figure 7 and, thus, responsible for the motion of one droplet **44**. The sequence of notes was played, with monotonic or chord notes contained in the sequence of notes as shown in Figure 8. The sequence of notes only produced motion of droplets **44** in fluidic channels attached to resonance chamber **12**-rectifier **20** pairs having a resonance frequency correlated to the frequency of the particular notes played. Additionally, movement of the droplets **44** was nearly instantaneous in response to changes in the composite or encoded acoustic signal **18** as the sequence of notes was played. Tone durations in this experiment were relatively brief (less than about 0.5 seconds), amounting to droplet **44** displacements on the order of half a millimeter per pulse. However, computerized waveform construction allows for full customization of the composite or encoded acoustic signal **18**, thereby allowing a droplet **44** to be moved over a longer distance in a shorter period of time by increasing the amplitude of the corresponding tone and

thus increasing the acoustic pressure within the cavity **14** of the resonance chamber **12** of interest. It is notable that for notes played as chords, droplet **44** velocities are higher than velocities produced from notes played monotonically. These phenomena can be controlled by adjusting tone amplitudes.

[0044] The acoustical fluid control mechanism **10** presented herein may be scaled down to develop an on-chip version thereof and thereby enable the operation of complex lab-on-a-chip (LOC) devices using minimal external control hardware. The acoustical fluid control mechanism **10** may be readily integrated into existing microfluidic designs or coupled to existing devices through an intermediate routing layer. Decrease in the length scale of the resonance chambers **12** will cause a proportional increase in resonance frequency and a four-fold increase in hydraulic resistance. Due to the increased power demands imposed by hydraulic resistance, higher pressures in the resonance chambers **12** may be useful to achieve the inertial dominant flow that is desirable for operation of the acoustical fluid control mechanisms **10**. Piezoelectric bi-morph materials are excellent candidates for on-chip acoustic sources **32** as they are powerful (i.e. have large mechanical impedance), can be fabricated in various sizes and shapes, and have a wide range of customizable performance characteristics such as driving voltage, strain, displacement, and dynamic range. Delivery of the acoustic signal **18** to the resonance chambers **12** in on-chip versions of the acoustical fluid control mechanisms **10** could be accomplished by direct displacement of a flexible microcavity volume using the piezoelectric bi-morph materials. Alternatively, the acoustic signal **18** could be transported through a working fluid (i.e., liquid or gas) to the chip. In either case, it is desirable to minimize radiation losses of the resonance chambers **12** and acoustic source **32** to prevent **26** attenuation of the acoustic signal **18**.

[0045] The invention has been described in an illustrative manner, and it is to be appreciated that the terminology which has been used is intended to be in the nature of words of description rather than of limitation. Obviously, many modifications and variations of the present invention are possible in view of the above teachings. It is, therefore, to be appreciated that within the scope of the claims the invention may be practiced otherwise than as specifically described, and that the reference numerals are merely for convenience and are not to be in any way limiting.

Claims

1. An acoustical fluid control mechanism comprising:

a resonance chamber defining a cavity and having a port with the cavity sealed from the ambient but for said port for enabling oscillatory flow of a working fluid into and out of the cavity upon exposure of said resonance chamber to an acoustic signal containing a tone at a frequency that is substantially similar to a particular resonance frequency of said resonance chamber; and

a rectifier for introducing directional bias to the oscillatory flow of the working fluid through said port, said rectifier having an inlet connected to said port of said resonance chamber for receiving the oscillatory flow of the working fluid from said port and an outlet for transmitting the directional flow of the working fluid away from said cavity, wherein said outlet is in fluid communication with said port of said resonance chamber at least during transmission of the directional flow of the working fluid therethrough.
2. An acoustical fluid control mechanism as set forth in claim 1 wherein said rectifier comprises an intersecting junction with said inlet, said outlet, and a vent meeting at said intersecting junction.
3. An acoustical fluid control mechanism as set forth in any preceding claim wherein said inlet of said rectifier has a smaller cross-sectional area than said outlet.
4. An acoustical fluid control mechanism as set forth in any preceding claim wherein said inlet and outlet are disposed opposite to each other across said intersecting junction.
5. An acoustical fluid control mechanism as set forth in any preceding claim wherein said rectifier is free from moving parts.

6. An acoustical fluid control mechanism as set forth in any preceding claim wherein a ratio of a cross-sectional area of said resonance chamber to a cross-sectional area of said port is at least 4.0:1.
7. An acoustical fluid control mechanism as set forth in any preceding claim further comprising an acoustic source for providing the acoustic signal to said resonance chamber.
8. An acoustical fluid control mechanism as set forth in any preceding claim comprising a bank of said resonance chambers each having a different resonance frequency with a rectifier connected to said port of each resonance chamber.
9. An acoustical fluid control mechanism as set forth in claim 8 wherein a peak resonance frequency of any of said resonance chambers is different by at least 10 Hz from a peak resonance frequency of any other of said resonance chambers.
10. An acoustical fluid control mechanism as set forth in any of claims 8 or 9 wherein a single acoustic source provides the acoustic signal to said bank of resonance chambers.
11. An acoustical fluid control mechanism as set forth in any of claims 8-10 further comprising a common air chamber defining an air cavity disposed between said acoustic source and said bank of resonance chambers.
12. An acoustical fluid control mechanism as set forth in claim 11 further comprising a cover plate disposed between said common air chamber and said bank of resonance chambers to unite the same.
13. An acoustical fluid control mechanism as set forth in claim 12 wherein said cover plate defines at least one vent hole therein for preventing pressure buildup in the air common air chamber.

14. A method of controlling fluid flow of a working fluid with the acoustical fluid control mechanism as set forth in claim 1, said method comprising the step of exposing the resonance chamber to an acoustic signal containing a tone at a frequency that is substantially similar to a particular resonance frequency of the resonance chamber to produce oscillatory flow of the working fluid into and out of the cavity of the resonance chamber through the port with the rectifier thereby introducing directional bias to the oscillatory flow of the working fluid through the port and resulting in transmission of directional flow of the working fluid away from the cavity and through the outlet of the rectifier.

15. A method as set forth in claim 14 wherein the outlet of the rectifier is connected to a fluidic channel containing a droplet of liquid and wherein the method further comprises the step of actuating the droplet contained in the fluidic channel with the directional flow of the working fluid from the outlet of the rectifier.

16. A method as set forth in any of claims 14 or 15 wherein the acoustical fluid control mechanism comprises a bank of the resonance chambers each having a different resonance frequency with a rectifier connected to the port of each resonance chamber, and wherein each resonance chamber is exposed to the same acoustic signal.

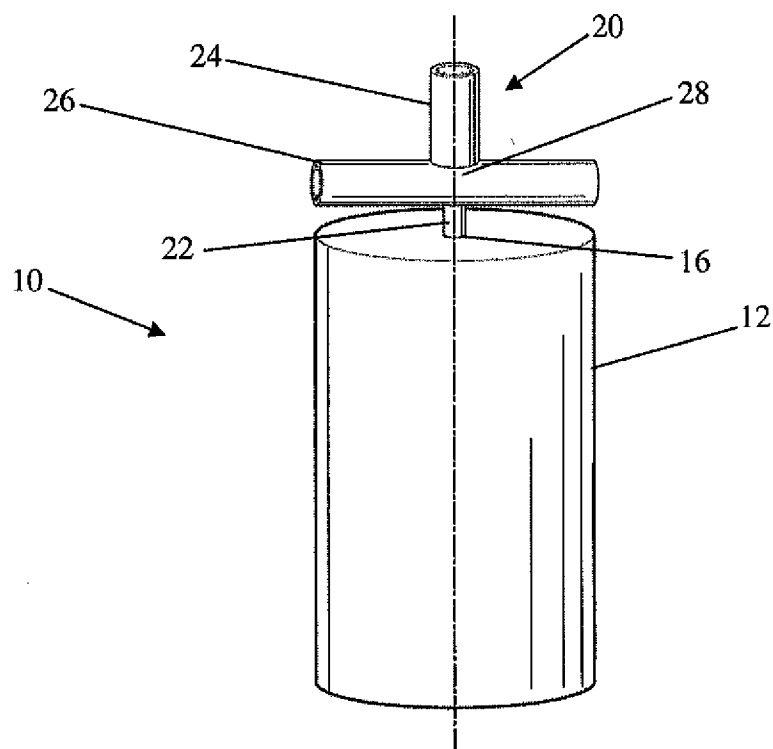
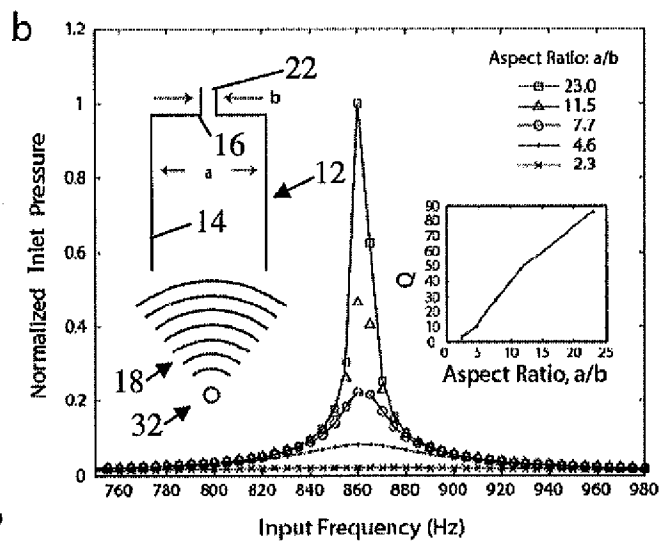
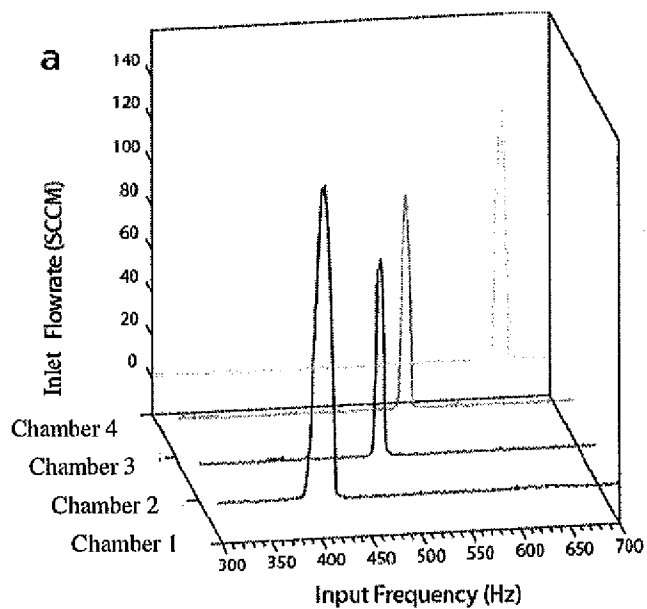
17. A method as set forth in claim 16 further comprising the step of exposing the bank of resonance chambers to the same acoustic signal.

18. A method as set forth in claim 17 further comprising the step of varying the tone contained in the acoustic signal to independently control the directional flow of the working fluid from different resonance chambers.

19. A method as set forth in any of claims 16-18 wherein the acoustic signal is further defined as a composite acoustic signal containing multiple different tones for

simultaneously controlling the directional flow of the working fluid from multiple resonance chambers.

20. A method as set forth in any of claims 14-19 wherein the oscillatory flow of the working fluid has an inertial dominant flow field.

**FIG. 1****FIG. 2**

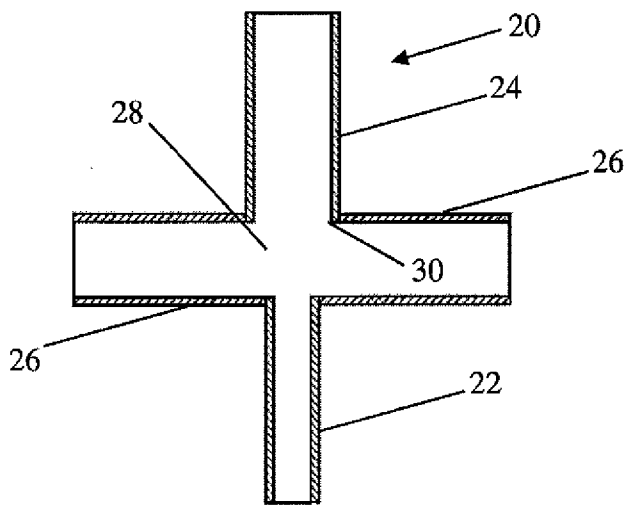


FIG. 3A

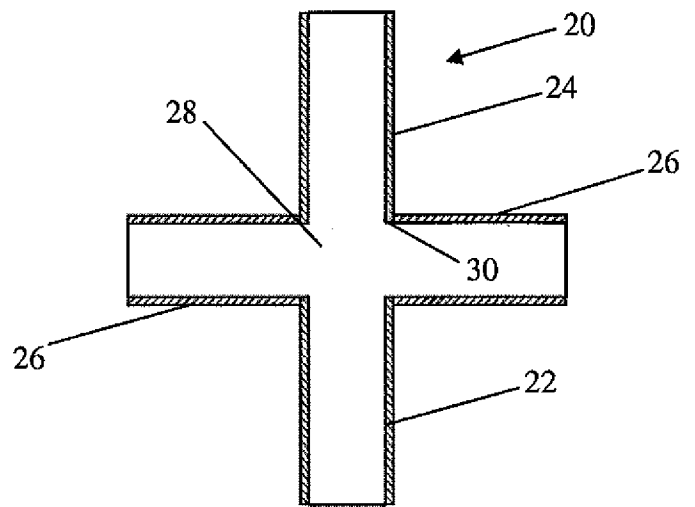


FIG. 3B

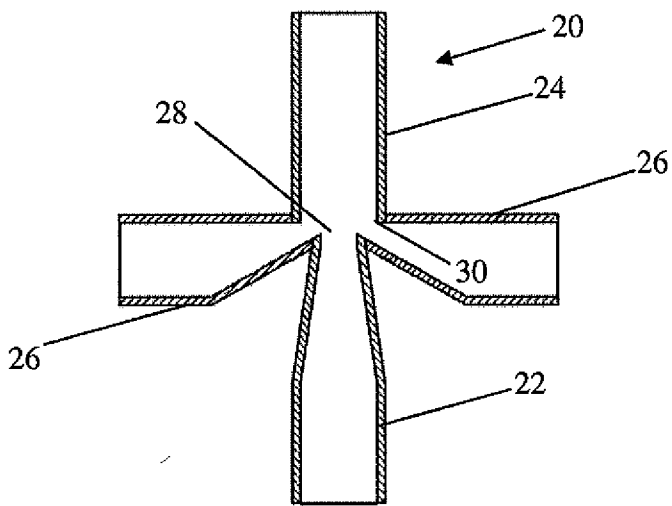


FIG. 3C

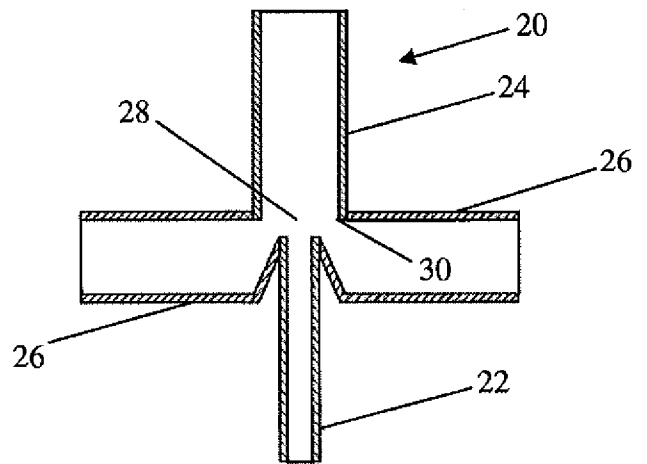


FIG. 3D

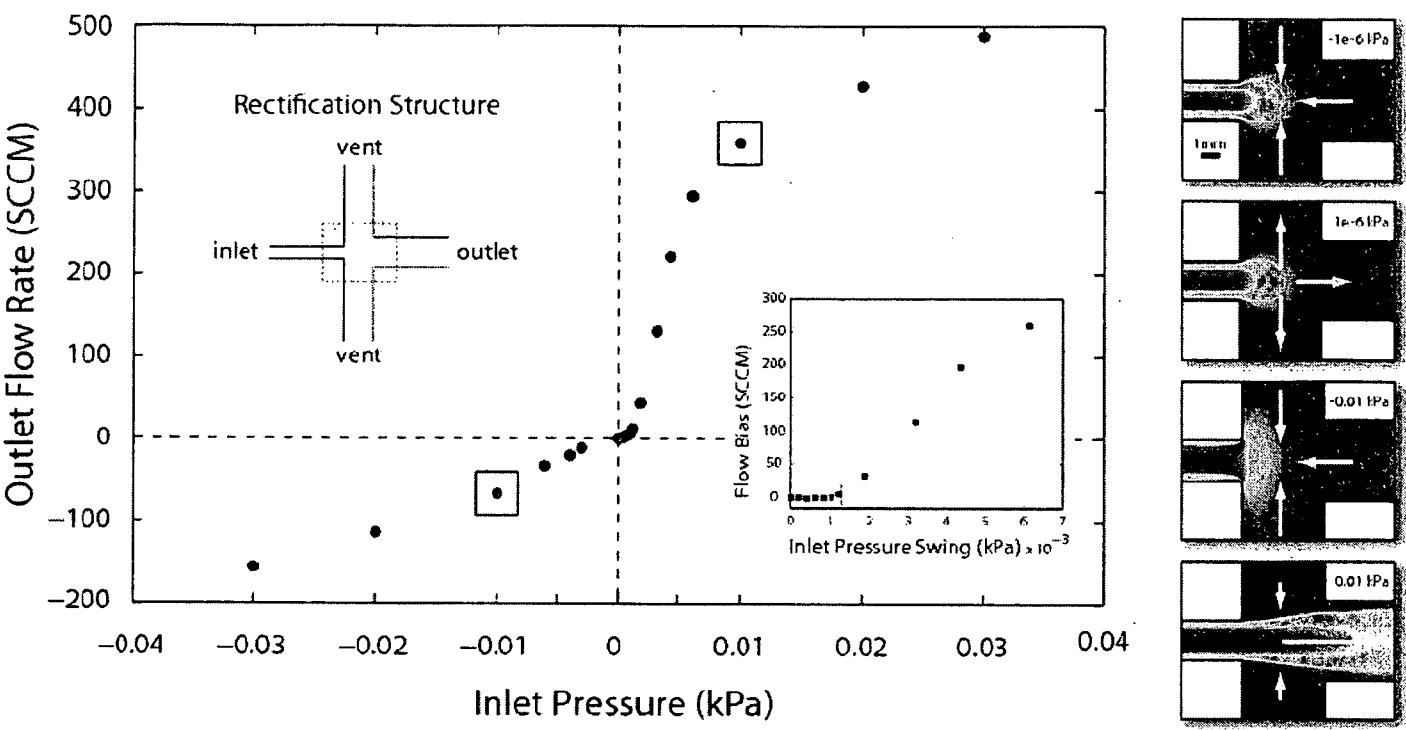


FIG. 4

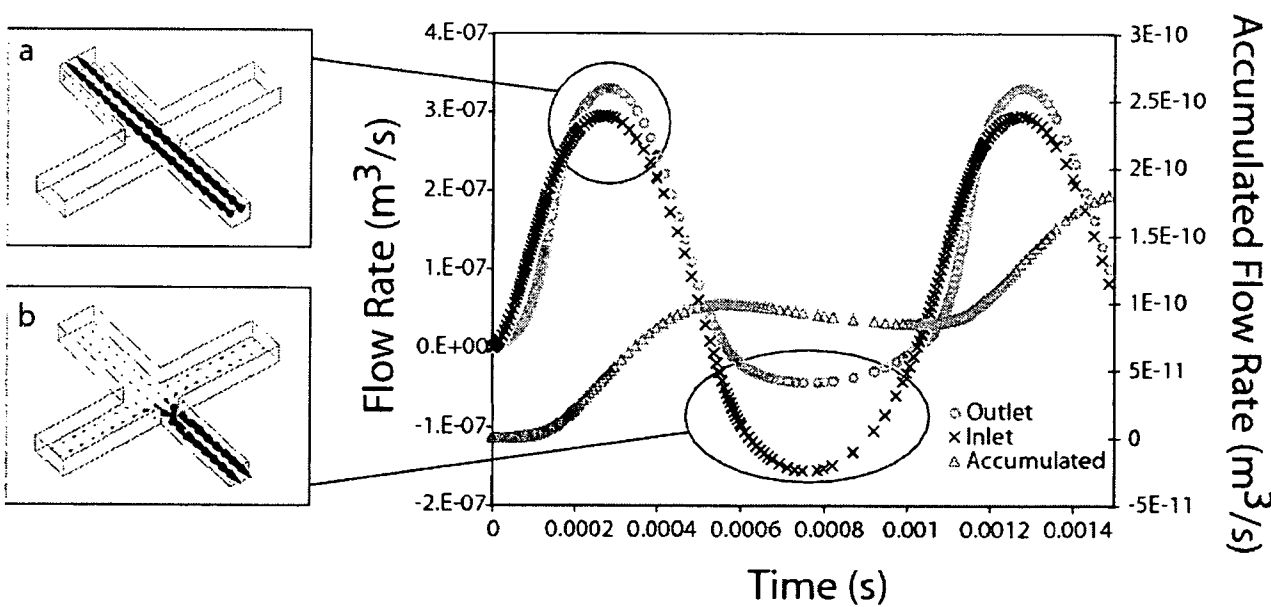
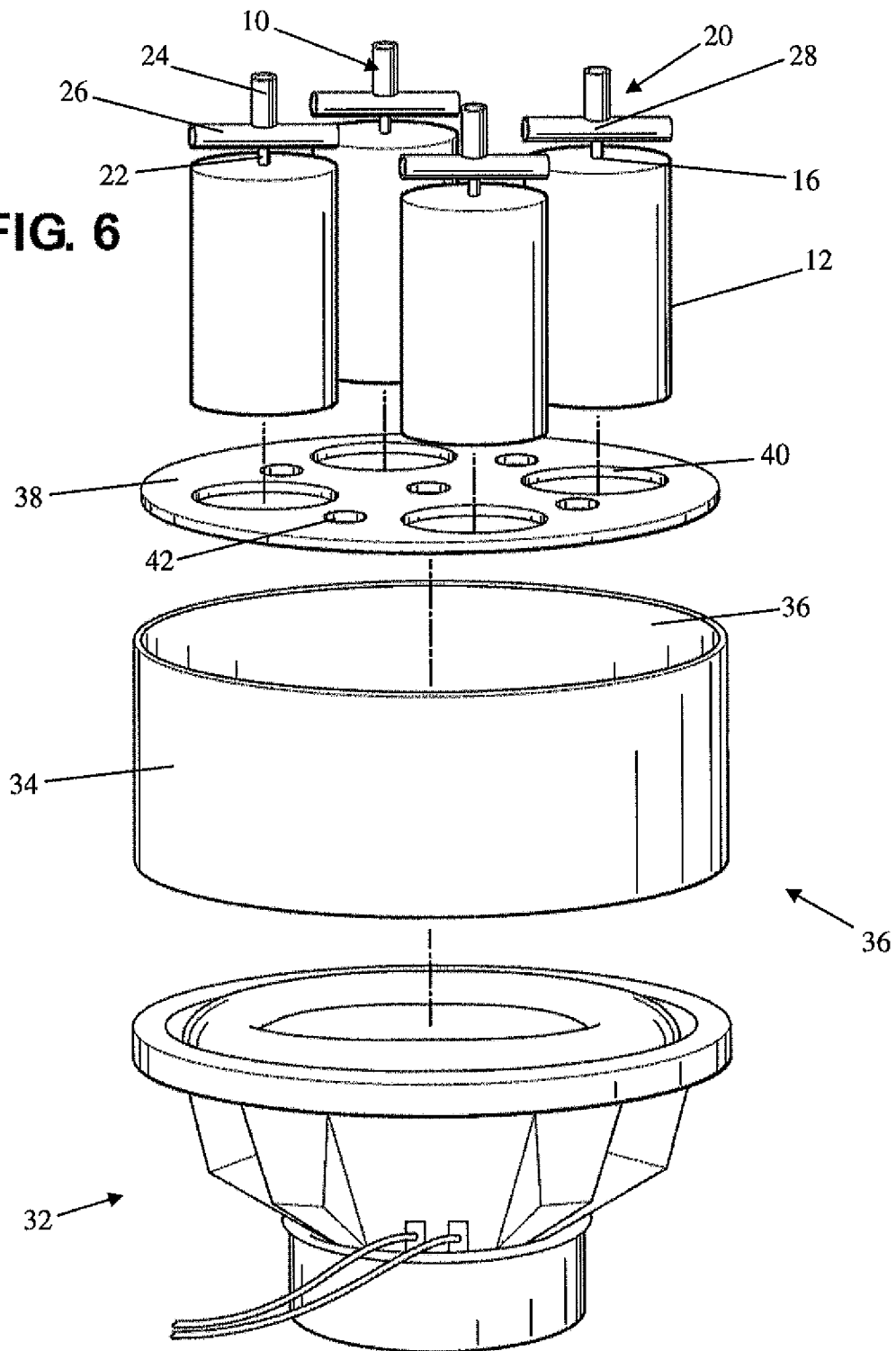


FIG. 5

FIG. 6

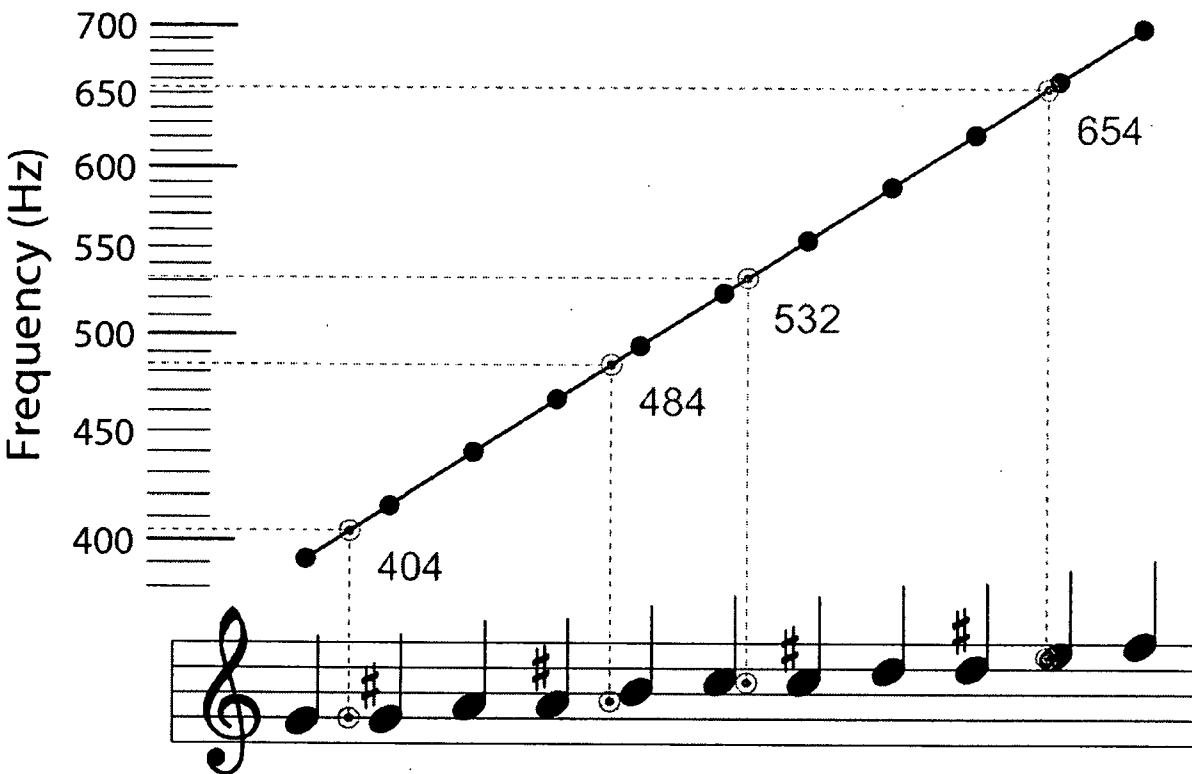


FIG. 7

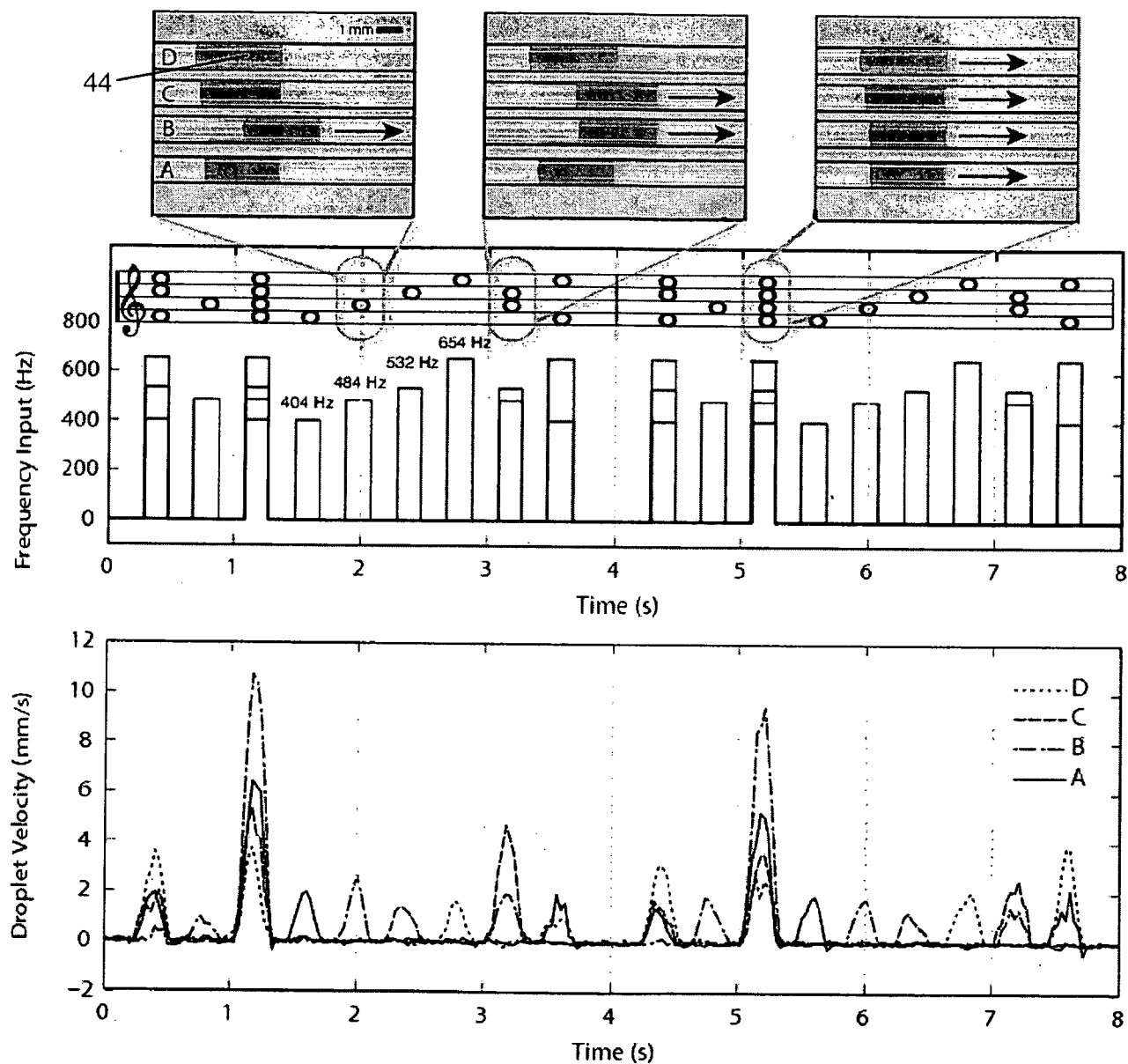


FIG. 8