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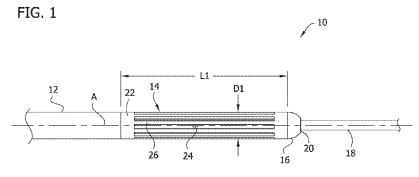
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(54) Title: TISSUE-REMOVING CATHETER WITH ADJUSTABLE CROSS-SECTIONAL DIMENSION



(57) Abstract: A tissue-removing catheter includes a drive shaft (12) and a tissue-removing head (14). The tissue-removing head is at the distal end of the drive shaft and is configured to rotate about a longitudinal axis of the drive shaft. The tissue-removing head is selectively adjustable from an initial cross-sectional dimension (D1) to an expanded cross-sectional dimension larger than the initial cross-sectional dimension.





TISSUE-REMOVING CATHETER WITH ADJUSTABLE CROSS-SECTIONAL DIMENSION

CROSS-REFERENCE TO RELATED APPLICATIONS

[0001] The present application claims the benefit of U.S. Provisional Application Serial No. 62/184,489, filed June 25, 2015, the entirety of which in incorporated by reference.

FIELD OF THE DISCLOSURE

[0002] The present disclosure generally relates to a tissue-removing catheter with a rotatable tissue-removing head having an adjustable cross-sectional dimension.

BACKGROUND

[0003] The patency of a body lumen may be affected by the build-up of tissue or other material in the body lumen. A variety of methods for cutting or dislodging occlusive material and removing such material from a body lumen, such as a blood vessel, have been proposed. For example, tissue-removing catheters may be used to restore the patency of a body lumen. These catheters are intended to cut or excise material from the body lumen and may employ a rotatable tissue-removing element which can be advanced into or past the occlusive material in order to cut and separate such material from the body lumen.

[0004] Although these catheters have proven very successful in restoring the patency of body lumens, problems may arise when the tissue-removing element has a smaller diameter than the occlusive tissue. If the tissue-removing element does not maintain contact with the occlusion or lumen wall, the efficacy of the tissue-removing element is reduced.

SUMMARY

[0005] In one aspect, a tissue-removing catheter includes a tissue-removing head that is selectively adjustable from an initial cross-sectional dimension to an expanded cross-sectional dimension larger than the initial cross-sectional dimension.

[0006] Other features will be in part apparent and in part pointed out hereinafter.

BRIEF DESCRIPTION OF THE DRAWINGS

[0007] FIG. 1 is an enlarged, partial perspective of an embodiment of a tissue-removing catheter, a tissue-removing head of the device being in an initial configuration;

[0008] FIG. 2 is similar to FIG. 1, illustrating the tissue-removing head in an expanded configuration;

[0009] FIG. 3 is schematic of the tissue-removing catheter with the tissue-removing head in the initial configuration, illustrating an abrasive exterior surface of the tissue-removing catheter; [0010] FIG. 4 is similar to FIG. 3, but with the tissue-removing head in the expanded configuration;

- [0011] FIG. 5 is a schematic of one embodiment of an expanding mechanism, illustrating a balloon inflated to expand the tissue-removing head;
- [0012] FIG. 6 is a schematic of another embodiment of an expanding mechanism, illustrating a wire, ball, and elastomer used to expand the tissue-removing head; and
- [0013] FIG. 7 is a schematic of another embodiment of an expanding mechanism, illustrating a tube fixed at one end for use in expanding the tissue-removing head.
- [0014] Corresponding reference characters indicate corresponding parts throughout the drawings.

DETAILED DESCRIPTION OF THE DISCLOSURE

[0015] Referring to FIGS. 1-3, an embodiment of a tissue-removing catheter for removing tissue from a body lumen is generally indicated at reference numeral 10. The illustrated tissueremoving catheter 10 is particularly suitable for removing an atheroma (e.g., plague) from a blood vessel, although the catheter may be used to remove other occlusions from other body lumens. [0016] The tissue-removing catheter 10 comprises a drive shaft 12, a tissue-removing head, generally indicated at 14, disposed at a distal end of the drive shaft, and a distal cap 16 disposed at a distal end of the tissue-removing head. The drive shaft 12 is operable to rotate the tissueremoving head 14 and the distal cap 16 about an axis A to remove tissue from a lesion or obstruction in a body lumen. The drive shaft 12, head 14, and cap 16 define a guide wire lumen 19 to receive a guide wire 18. The cap 16 includes a distal opening 20 through which the guide wire 18 extends. The tissue-removing catheter 10 is configured for use as an over-wire device (i.e., over the guide wire 18). However, other configurations are within the scope of the present invention, and it is understood that the guide wire 18 may be omitted within the scope of the present invention. As shown in FIGS, 1-3 and other drawings, the illustrated cap 16 has a generally conical or dome-shape that tapers distally and is suitable for boring through tissue (e.g., plaque) occluding a body lumen. A specialty wire may be used in conjunction with the tissueremoving catheter 10 to facilitate coring through total or near total occlusions. [0017] The tissue-removing head 14 includes a generally tubular body 22 having

circumferentially spaced longitudinal slots 24 separating fingers 26. The longitudinal slots 24 permit the head 14 to expand circumferentially, as described below. The head 14 is made of Nitinol, spring steel, or any other suitable material. A proximal end of the head 14 is fixedly attached to the drive shaft 12 such that the drive shaft imparts rotation of the head. The drive

shaft 12 may be formed separately from the head 14, or may be integrally formed therewith. A proximal end of the cap 16 is fixedly attached to a distal end of the head 14 opposite the drive shaft 12. The cap 16 is attached to the head 14 such that the cap moves (e.g., rotates) with the head. The cap 16 may be formed separately from the head 14, or may be integrally formed therewith. At least a portion of the cap 16 and/or at least a portion of the head 14 has an abrasive exterior surface for abrading a lesion in a body lumen. For example, an abrasive material or grit 28 may be applied to at least a portion of the exterior surface of the cap 16 or the head 14, or the exterior surface may otherwise be formed to be abrasive. In one embodiment, a portion of the cap 16 and/or a portion of the head 14 is coated with an abrasive coating or grit 28. In the illustrated embodiment, the exterior surfaces of both the cap 16 and the head 14 are coated with grit 28. The grit 28 abrades and removes tissue from a body lumen as the catheter rotates about the axis A. The grit can be diamond grit or other suitable material for use on a rotary head for removing tissue.

[0018] The tissue-removing head 14 has an initial or minimum cross-sectional dimension D1 (see FIG. 1) and a first longitudinal length L1. The head 14 is expandable circumferentially to increase the cross-sectional dimension to an expanded or maximum cross-sectional dimension D2 (FIGS. 2 and 4), which is larger than the initial cross-sectional dimension D1. As illustrated, the initial cross-sectional dimension D1 is about the same as a cross-sectional dimension of the drive shaft 12 and the expanded cross-sectional dimension D2 is larger than the cross-sectional dimension of the drive shaft, although other configurations are within the scope of the present invention. In the expanded configuration, the fingers 26 of the head 14 flex or bend outward to increase the cross-sectional dimension of the head, which, in turn, shortens the tissue-removing head to a second longitudinal length L2. Thus, as the cross-sectional dimension of the head 14 can be expanded and contracted to have any cross-sectional dimension in the range between the initial cross-sectional dimension D1 and a maximum expanded cross-sectional dimension D2.

[0019] The illustrated tissue-removing catheter 10 includes an expansion mechanism for use in circumferentially expanding the head 14. In the embodiment illustrated in FIG. 5, the device 10 includes a balloon 30 positioned in the interior of the head 14. The balloon 30 is inflated and deflated to control the cross-sectional dimension of the head 14. The balloon 30 rotates with the drive shaft 12, the head 14, and the cap 16. The balloon 30 is disposed on a balloon shaft having a lumen for use in inflating the balloon. The balloon 30 is inflated or deflated by a rotating pressure port (not shown) on a proximal end of the tissue-removing catheter. As the balloon 30 is inflated, it pushes the fingers 26 of the head 14 radially outward to expand the circumference of the head. When the balloon 30 is deflated, the head 14 returns to its initial cross-sectional

dimension. The head 14 is adjustable to different cross-sectional dimensions based on the amount the balloon 30 is inflated.

[0020] In another embodiment, illustrated in FIG. 6, an elastomer 40 is positioned in the interior of the head 14. A movable cone or ball 44 (broadly, an actuator) is attached to a distal end of a wire 42 which extends proximally through the drive shaft 12. A user pushes or pulls the wire 42 to move the ball 44 against the elastomer 40, thereby causing the elastomer to compress and bulge radially outward. As the elastomer 40 bulges radially outward, it pushes the fingers 26 of the head 14 radially outward to expand the circumference of the head. Alternatively, a threaded rod or other device used to impart movement of the ball relative to the elastomer can be used in place of the wire 42.

[0021] In yet another embodiment, illustrated in FIG. 7, an inner tube 50 is fixedly attached at one end to the head 14 at attachment points 52. The inner tube 50 is movable relative to the drive shaft 12. As the inner tube 50 is moved, the distal end of the head 14 moves with the inner tube because of the attachment of the inner tube to the head. Longitudinal movement in the direction of arrows B of the inner tube 50 causes the fingers 26 of the head 14 to bow outward or inward to reduce or increase the length of the head, thereby increasing or decreasing the cross-sectional dimension of the head. Other suitable mechanisms for expanding and contracting the cross-sectional dimension of the head 14 are within the scope of the present invention.

[0022] Although not illustrated, a control handle or other control device operatively connects to the tissue-removing catheter 10. The control handle includes a housing and at least one actuator in the housing for driving rotation of the driveshaft. In one example, the control handle may include a rotary actuator for rotating the driveshaft about the axis A. The control handle can also include an actuator for adjusting the cross-sectional dimension of the head 14 (e.g., to adjust inflation of balloon 30, move wire 42, move tube 50, or other suitable mechanism for adjusting the cross-sectional dimension of the head).

[0023] In one embodiment of a tissue-removing operation, the tissue-removing catheter 10 is advanced in a body lumen over the guide wire 18 to a target site (e.g., a lesion in the body lumen). At the target site, the tissue-removing catheter 10 can be activated using the control handle, such as by activating a control lever, button, or other device to activate the at least one actuator. Upon activating the tissue-removing catheter 10, the drive shaft 12 rotates about the axis A, causing rotation of the head 14 and the cap 16. The head 14 and/or the cap 16 abrades the lesion, thereby removing tissue. The cross-sectional dimension of the head 14 can be expanded (e.g., by using the control handle to inflate the balloon 30) to enlarge an existing lumen by abrading and removing additional tissue from the lesion.

[0024] The tissue-removing catheter 10 may also be used without a guide wire. In one embodiment, the cap 16 is used to bore through a near total or total occlusion. The tissue-removing catheter 10 may also be used without imparting rotation of the tissue-removing head. In one embodiment, the tissue-removing head 14 is used to center the tissue-removing catheter 10 in the true lumen (i.e., in the space remaining between occlusions in the body lumen). The tissue-removing head 14 can be expanded circumferentially to contact the outer limits of the true lumen, thereby centering the tissue-removing catheter 10 in the true lumen. With the catheter 10 centered in the true lumen, a wire (e.g., guide wire 18) can be advanced beyond the cap 16 to bore through tissue occluding the body lumen. In one embodiment, the tissue-removing head 14 can be advanced in the initial configuration to a target site, and then expanded circumferentially at the target site to engage the occlusion to cut or tear the occlusion without rotating the tissue-removing head. In one embodiment, the tissue-removing head 14 can be advanced beyond a target site, then expanded circumferentially and pulled back over the target site to remove tissue. An aspiration catheter (not shown) can be positioned near that tissue-removing head to collect debris removed by the tissue-removing head.

[0025] The tissue-removing catheter 10 facilitates creation of a larger lumen diameter. The head 14 can increase in cross-sectional dimension to continue to enlarge an existing lumen (e.g., by using multiple passes over the same lesion), treat multiple vessels in the same patient, or treat vessels that have slight to moderate aneurysmal pockets. Because the head 14 can decrease in cross-sectional dimension after it has been expanded, it may allow a practitioner to retrieve a stuck head or treat disease that is distal to a treatment barrier such as a stent. The variable cross-sectional dimension head 14 reduces the need for using different size heads to treat multiple diameters or vessels, resulting in decreased costs. It also does not rely on centrifugal force (and thus, require a high-speed, well controlled motor) to maintain contact between the head 14 and the lesion, but rather expands the head to contact the lesion which may result in further cost savings. [0026] Modifications and variations of the disclosed embodiments are possible without departing from the scope of the invention defined in the appended claims.

[0027] When introducing elements of the present invention or the embodiment(s) thereof, the articles "a", "an", "the" and "said" are intended to mean that there are one or more of the elements. The terms "comprising", "including" and "having" are intended to be inclusive and mean that there may be additional elements other than the listed elements.

[0028] As various changes could be made in the above constructions, products, and methods without departing from the scope of the invention, it is intended that all matter contained in the above description and shown in the accompanying drawings shall be interpreted as illustrative and not in a limiting sense.

- 1. A tissue-removing catheter comprising:
- a drive shaft having opposite proximal and distal ends and configured for rotation about a longitudinal axis; and
- a tissue-removing head at the distal end of the drive shaft, wherein the tissue-removing head is configured to rotate about the longitudinal axis, and wherein the tissue-removing head is selectively adjustable from an initial cross-sectional dimension to an expanded cross-sectional dimension larger than the initial cross-sectional dimension.
- 2. The tissue-removing catheter set forth in claim 1, further comprising an expansion mechanism configured to selectively adjust the tissue-removing head from the initial cross-sectional dimension to the expanded cross-sectional dimension.
- 3. The tissue-removing catheter set forth in claim 2, wherein the expansion mechanism includes an elastically deformable member disposed inside the tissue-removing head, wherein the elastically deformable member is selectively elastically compressible to increase a cross-sectional dimension of the elastically deformable member from an initial cross-sectional dimension to an expanded cross-sectional dimension larger than the initial cross-sectional dimension to selectively adjust the tissue-removing head from the initial cross-sectional dimension to the expanded cross-sectional dimension.
- 4. The tissue-removing catheter set forth in claim 3, wherein the expansion mechanism includes an actuator configured to elastically compress the elastically deformable member.
- 5. The tissue-removing catheter set forth in claim 4, wherein actuator is disposed in the tissue-removing head.
- 6. The tissue-removing catheter set forth in claim 5, wherein the actuator is selectively movable axially within the tissue-removing head to elastically compress the elastically deformable member.
- 7. The tissue-removing catheter set forth in claim 6, wherein the expansion mechanism includes a wire extending along the drive shaft, the wire being selectively moveable axially

relative to the drive shaft and the tissue-removing head, wherein the actuator is secured to the distal end of the wire.

- 8. The tissue-removing catheter set forth in claim 7, wherein the wire is disposed in an axial lumen extending along the drive shaft.
- 9. The tissue-removing catheter set forth in claim 7, wherein the wire is selectively movable proximally relative to the drive shaft to move the actuator proximally relative to the tissue-removing head to elastically compress the elastically deformable member.
- 10. The tissue-removing catheter set forth in claim 7, wherein the wire is selectively movable distally relative to the drive shaft to move the actuator distally relative to the tissue-removing head to elastically compress the elastically deformable member.
- 11. The tissue-removing catheter set forth in claim 5, wherein the actuator comprises a cone or ball member.
- 12. The tissue-removing catheter set forth in claim 3, wherein the tissue-removing head comprises an abrasive exterior surface configured to abrade tissue as the tissue-removing head rotates about its longitudinal axis.
- 13. The tissue-removing catheter set forth in claim 12, wherein the tissue-removing head comprises a generally tubular body including longitudinal fingers spaced apart from one another circumferentially about the longitudinal axis of the tissue-removing head to define a plurality of circumferentially spaced longitudinal slots.
- 14. The tissue-removing catheter set forth in claim 2, wherein the expansion mechanism includes an inflatable balloon disposed inside the tissue-removing head.
 - 15. A method of debulking a body lumen, the method comprising:

delivering a distal end of a tissue-removing catheter to a target site within the body lumen, the tissue-removing catheter including

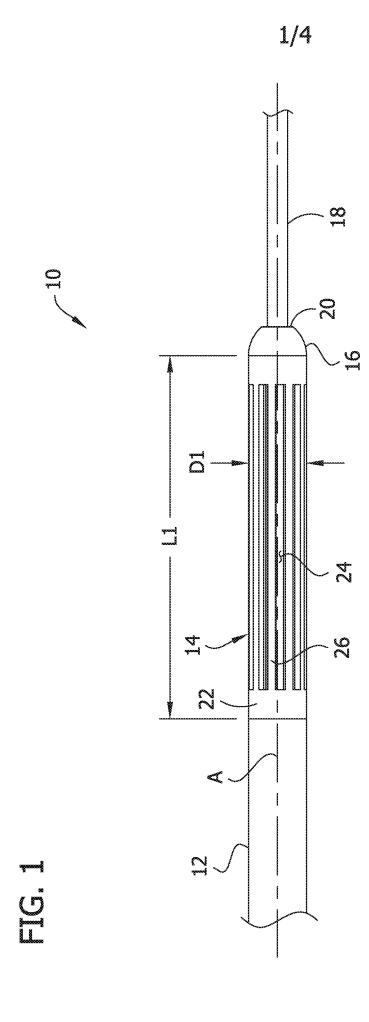
a drive shaft having opposite proximal and distal ends and configured for rotation about a longitudinal axis, and

a tissue-removing head at the distal end of the drive shaft, wherein the tissueremoving head is configured to rotate about the longitudinal axis, and wherein the tissueremoving head is selectively adjustable from an initial cross-sectional dimension to an expanded cross-sectional dimension larger than the initial cross-sectional dimension;

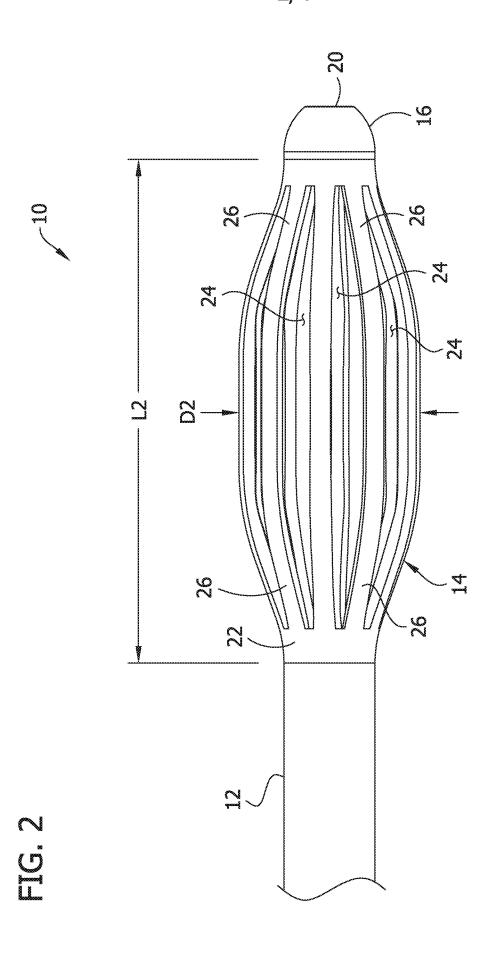
adjusting the tissue-removing head from the initial cross-sectional dimension to the expanded cross-sectional dimension;

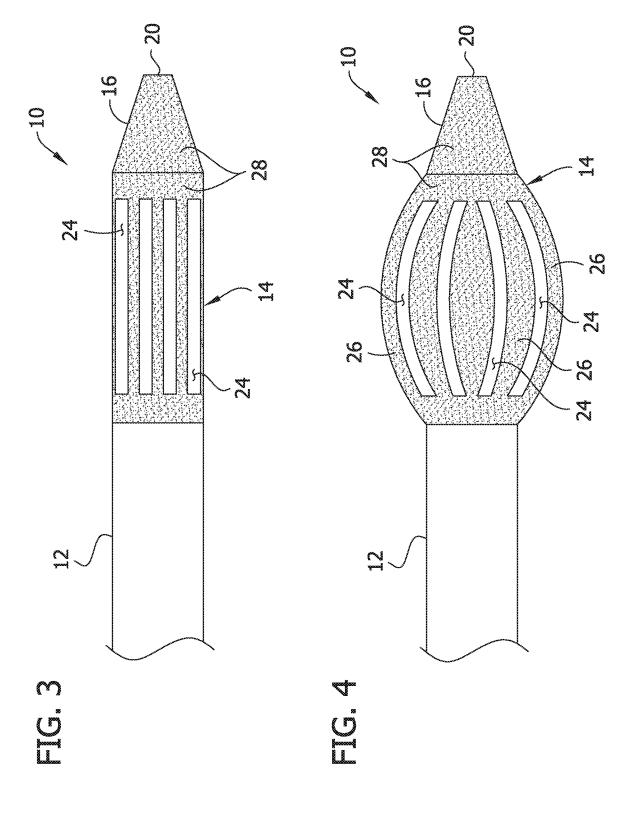
rotating the drive shaft about its longitudinal axis to impart rotation of the tissue-removing head, wherein the rotating tissue-removing head removes tissue from a wall of the body lumen at the target site.

- 16. The method of debulking a body lumen set forth in claim 15, wherein the tissue-removing head includes an abrasive exterior surface, wherein the rotating tissue-removing head abrades tissue from the wall of the body lumen.
- 17. The method of debulking a body lumen set forth in claim 16, wherein said adjusting the tissue-removing head comprises elastically compressing an elastically deformable member disposed inside the tissue-removing head to increase a cross-sectional dimension of the elastically deformable member from an initial cross-sectional dimension to an expanded cross-sectional dimension larger than the initial cross-sectional dimension to selectively adjust the tissue-removing head from the initial cross-sectional dimension to the expanded cross-sectional dimension.
- 18. The method of debulking a body lumen set forth in claim 17, wherein said adjusting the tissue-removing head comprises axially moving an actuator within the tissue-removing head to elastically compress the elastically deformable member.
- 19. The method of debulking a body lumen set forth in claim 18, wherein said axially moving an actuator comprises moving the actuator proximally.
- 20. The method of debulking a body lumen set forth in claim 18, wherein said axially moving an actuator comprises moving the actuator distally.









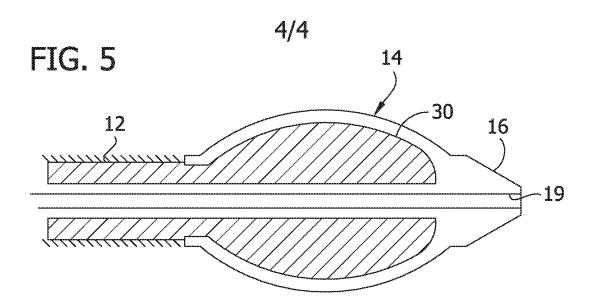


FIG. 6

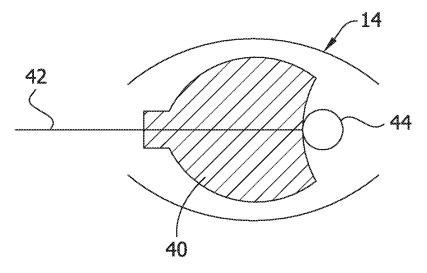
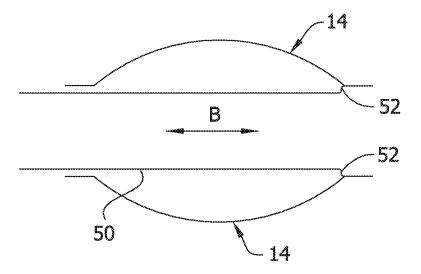


FIG. 7



INTERNATIONAL SEARCH REPORT

International application No PCT/US2016/039072

a. classification of subject matter INV. A61B17/3207

ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

A61B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT				
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.		
Х	US 5 176 693 A (PANNEK JR EDWARD J [US]) 5 January 1993 (1993-01-05)	1,2,14		
Υ	column 4, line 12 - column 5, line 22; figures 1-4b	3-13		
Υ	US 5 108 413 A (MOYERS ROBERT E [US]) 28 April 1992 (1992-04-28) column 1, line 46 - column 2, line 6; figures 1-3	3-13		
X	WO 2005/030061 A1 (JOHNSON AND JOHNSON KABUSHIKI [JP]; NAKAO MASAYUKI [JP]) 7 April 2005 (2005-04-07) abstract; figures 1, 2, 5, 6, 9 page 12, line 1 - line 10	1,2		
	-/			

Further documents are listed in the continuation of Box C.	X See patent family annex.
"A" document defining the general state of the art which is not considered to be of particular relevance "E" earlier application or patent but published on or after the international filing date "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "O" document referring to an oral disclosure, use, exhibition or other means "P" document published prior to the international filing date but later than the priority date claimed	"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art "&" document member of the same patent family
Date of the actual completion of the international search	Date of mailing of the international search report
30 August 2016	15/09/2016
Name and mailing address of the ISA/ European Patent Office, P.B. 5818 Patentlaan 2 NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Fax: (+31-70) 340-3016	Authorized officer Moers, Roelof

INTERNATIONAL SEARCH REPORT

International application No
PCT/US2016/039072

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 5 030 201 A (PALESTRANT AUBREY [US]) 9 July 1991 (1991-07-09) abstract; figures 1-18	1,2
X	9 July 1991 (1991-07-09) abstract; figures 1-18 EP 0 442 137 A1 (ANGIOMED AG [DE]) 21 August 1991 (1991-08-21) abstract; figures 1, 2	1,2

International application No. PCT/US2016/039072

INTERNATIONAL SEARCH REPORT

Box No. II Observations where certain claims were found unsearchable (Continuation of item 2 of first sheet)
This international search report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:
1. X Claims Nos.: 15-20 because they relate to subject matter not required to be searched by this Authority, namely: Rule 39.1(iv) PCT - Method for treatment of the human or animal body by surgery
2. Claims Nos.: because they relate to parts of the international application that do not comply with the prescribed requirements to such an extent that no meaningful international search can be carried out, specifically:
3. Claims Nos.: because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a).
Box No. III Observations where unity of invention is lacking (Continuation of item 3 of first sheet)
This International Searching Authority found multiple inventions in this international application, as follows:
As all required additional search fees were timely paid by the applicant, this international search report covers all searchable claims.
2. As all searchable claims could be searched without effort justifying an additional fees, this Authority did not invite payment of additional fees.
3. As only some of the required additional search fees were timely paid by the applicant, this international search report covers only those claims for which fees were paid, specifically claims Nos.:
4. No required additional search fees were timely paid by the applicant. Consequently, this international search report is restricted to the invention first mentioned in the claims; it is covered by claims Nos.:
The additional search fees were accompanied by the applicant's protest and, where applicable, the payment of a protest fee. The additional search fees were accompanied by the applicant's protest but the applicable protest fee was not paid within the time limit specified in the invitation. No protest accompanied the payment of additional search fees.

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No
PCT/US2016/039072

Patent document cited in search report		Publication date	Patent family member(s)		Publication date
US 5176693	A	05-01-1993	NONE		
US 5108413	Α	28-04-1992	NONE		
WO 2005030061	A1	07-04-2005	NONE		
US 5030201	Α	09-07-1991	NONE		
EP 0442137	A1	21-08-1991	AT EP ES JP JP	134123 T 0442137 A1 2085880 T3 2549084 Y2 H0488919 U	15-02-1996 21-08-1991 16-06-1996 24-09-1997 03-08-1992