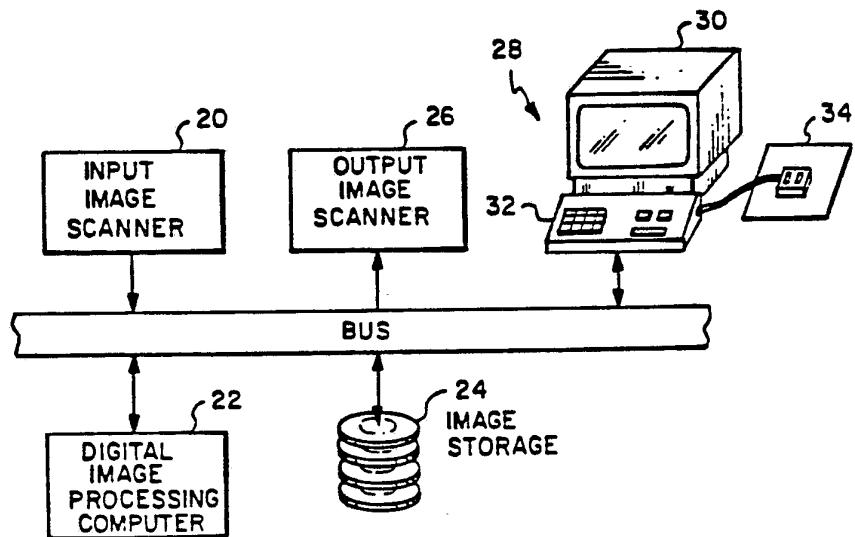




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(54) Title: DIGITAL IMAGE SHARPENING METHOD USING SVD BLOCK TRANSFORM



## (57) Abstract

A block transform image sharpening method employs singular value decomposition to boost texture and edge detail while not boosting shaded (uniform) areas of the image characterized by a lower signal-to-noise ratio while at the same time reducing noise in other areas of the same image not containing much edge detail or texture.

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DIGITAL IMAGE SHARPENING METHOD  
USING SVD BLOCK TRANSFORM

5 Related Applications

This application contains subject matter related to PCT Patent Application Serial No.

US88/00519 entitled "DIGITAL IMAGE NOISE SUPPRESSION METHOD USING SVD BLOCK TRASNFORM" filed February 22,  
10 1988.

TECHNICAL FIELD OF THE INVENTION

The invention relates to block transform digital image processing methods for increasing the sharpness of a digital image.

15 Background of the Invention

The invention includes a noise suppression algorithm and a sharpening algorithm. The sharpening algorithm of the present invention is closely related to the noise suppression algorithm 20 of the invention, since the success of these algorithms depends upon their ability to separate image detail from noise. Uniformly blurring the image (as in the prior art) achieves noise suppression, but unfortunately it also blurs image detail. Simple unsharp masking (as in the prior 25 art) sharpens image detail but it also boosts noise. Hence, one goal of the invention is to distinguish image detail from noise while intelligently controlling the image components so as 30 to perform both noise suppression and sharpening in the same image. The goal of the noise suppression algorithm of the invention is to suppress noise while leaving image detail untouched. The goal of the sharpening algorithm of the invention is to 35 sharpen the image detail without boosting the noise.

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In the present invention, the method used for noise suppression to discriminate image detail from noise is also employed to do the image sharpening, with appropriate modifications. A

- 5 singular value decomposition (SVD) block transformation method has been shown in the related application referenced above to discriminate between image detail and noise, and is consequently used in the present invention to perform noise suppression.
- 10 The same SVD noise suppression algorithm is employed in the invention with appropriate modifications to sharpen the image as well. For image sharpening, the invention does not need to work with the large block sizes disclosed in the related application.
- 15 It is sufficient to use smaller block sizes (5x5 or 7x7 kernels).

Another embodiment of the invention includes the application of a non-linear gain function which will be described in detail later.

20 SUMMARY OF THE INVENTION

The present invention is a block transform image sharpening process. In arriving at the present invention, we found it helpful to consider the statistical properties of the noise being removed from an image, and the statistical properties of the image details such as texture and edges that were to be preserved in the processed image. In particular, we examined the statistical properties of the noise, and image detail in the transformed coordinate space. For a spatial transformation of the Walsh-Hadamard type, a transform coefficient of the noise is characterized by a Gaussian-like distribution around a mean value of zero. This is shown by Curve 10 in Fig. 2. The transform coefficients of the picture detail,

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including edges and texture, form a Lapacian-like distribution, also centered about zero (shown by Curve 12 in Fig. 2.)

- The transform coefficients from the picture detail have generally higher amplitude in absolute terms than the ones from the noise. Noise suppression is achieved by thresholding the transform coefficients or by modifying them through a non-linear gain function. This will remove most of the noise but unfortunately it will remove the low amplitude transform coefficients from the image detail which will create artifacts. The artifacts are most noticeable and objectionable in low contrast fine textured area.
- We also examined the variance distributions of the image components such as noise, texture, and edges, and noted that there was a much better separation of the statistics of the image components when plotted against variance of small regions.
- Fig. 3 is a graph showing variance plotted against distribution (number of occurrences) for film grain noise (Curve 14), texture (Curve 16), and edge detail (Curve 18) for a typical digital image produced by scanning a photograph.
- It will be appreciated from a comparison of Fig. 2 with Fig. 3, that a noise reduction technique that discriminates based upon the variances of image detail will have a much better chance of reducing noise without affecting texture extensively. We also came to realize that there exists an image transformation called singular value decomposition (SVD) that decomposes an image into a set of singular vectors and singular values that are closely analogous to the concept of principal component analysis in statistics. This can be

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appreciated from the following analysis:

- If an  $m \times n$  matrix is treated as a set of  $n$   $m$ -dimensional column vectors and the mean column vector is set to zero by subtracting it from every 5 column vector of the matrix, then the singular values of the resulting matrix are the square roots of the variances of the  $m$  vector components in a rotated space. The rotated space is such that there is no correlation between any two components of the 10 sample vectors in the rotated space. The distribution of the singular values for noise is a slowly decreasing function when they are ordered in decreasing order. The distribution of the singular values for the picture detail will be quite 15 different from the noise. Also, the singular values for the picture detail will be much higher than those of the noise. And as mentioned above, discrimination of the noise from the picture detail will be much better.
- 20 According to the method of the present invention, a digital image is processed in a computer to increase sharpness by performing the following steps. First a non-linear gain function is produced, based upon the measured statistics of 25 the singular values of the noise in the image. A detail image, and a low pass filtered image are produced from the digital image to be processed. The detail image is divided into blocks and the blocks are transformed into singular vectors and a 30 diagonal array of singular values. The non-linear gain function is applied to the singular values to produce an array of singular values which have been modified so as to boost those regions of the detail image containing "edges" and characterized by a 35 higher signal-to-noise ratio than other regions. An

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inverse SVD transform is performed on the singular vectors and the modified singular values to produce blocks of processed detail image values. Finally, the processed detail image is added to the low pass 5 image to generate a sharpened image.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a schematic diagram showing a digital image processing system suitable for practicing the method of the present invention;

10 Fig. 2 is a graph useful in describing the statistics of image features processed according to the prior art;

15 Fig. 3 is a graph useful in describing the statistical features of an image processed according to the present invention;

Fig. 4 is a block diagram illustrating the method of digital image processing according to the present invention;

20 Fig. 5 is a block diagram illustrating the step of generating the table of factors described in Fig. 4;

Fig. 6 is a graph showing the values of a typical table of factors generated according to the steps shown in Fig. 5;

25 Fig. 7 is a block diagram showing a block overlap method of processing a digital image according to the present invention;

Fig. 8 is a diagram useful for describing the image processing method shown in Fig. 7;

30 Fig. 9 is a block diagram showing a digital image processing method according to the present invention;

Figs. 10a-10c are diagrams showing the values of the coefficients employed in the digital 35 filter shown in Fig. 9;

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Fig. 11 is a diagram showing a digital image processing method according to the present invention employing block overlap and a spatial frequency band pass image signal;

5 Fig. 12 is a diagram showing a mode of practicing the invention including means for processing diagonal edge information; and

Fig. 13 is a diagram useful in describing the operation of the digital image processing method  
10 shown in Fig. 12.

#### MODES OF CARRYING OUT THE INVENTION

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15 owner has no objection to the facsimile reproduction by anyone of the patent document or the patent disclosure as it appears in the Patent and Trademark Office patent file or records, but reserves all other rights whatsoever.

20 The digital image signal referred to in the following description is generated by scanning and sampling an original image. For purposes of describing the preferred embodiments, the input signal is generated from a photographic negative or  
25 transparency. The digital image signal represents a variety of spatial components of the image, including an average brightness level, fine detail such as lines and textures, intermediate detail such as small features, and coarse details such as  
30 shading on smooth surfaces and other gradually varying features. In addition, the signal includes a noise component affecting most of the spatial components of the image to some degree.

With a photographic negative or  
35 transparency, much of the noise is film grain

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noise. While the invention will be described in connection with sampled data from a photograph, it should be understood that the input signal can represent other information or data such as would be  
5 derived from directly scanning an object, from a composite video signal or from image information stored in optical or magnetic storage media. In such cases, the noise may originate in other characteristics of the image signal generating  
10 system. Since the singular values mentioned above measure correlations, the method of the invention can discriminate noise originating from a wide variety of noise sources so as to selectively sharpen "edge" features in the image while avoiding  
15 any "sharpening" of noise.

Fig. 1 is a schematic diagram showing a digital image processing facility useful for practicing the present invention. The digital image processing facility includes an input image scanner 20, such as a CCD scanner or a graphic arts flat bed or drum scanner. A digital image signal generated by an input scanner 20 is processed by the digital image processing computer 22. The digital image processing computer 22 can be a general purpose  
25 digital computer, or a special purpose computer specifically designed for processing images (e.g., a parallel multi-processor computer with 16 micro-processors and local memory). The original digital image from the scanner, and/or the processed  
30 digital image may be stored in a mass image storage memory 24, comprising for example magnetic or optical disk storage media.

The original and/or processed image may be displayed by means of an output image scanner 26, such as a CRT or laser film scanner. The system is  
35

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controlled by an operator from a work station 28 such as the Sun work station manufactured and sold by Sun Microsystems Inc. The work station includes a CRT 30 for temporarily displaying an image, a 5 keyboard 32, and graphics input device such as a mouse and graphics tablet 34.

Fig. 4 is a block diagram showing the major steps implemented by the image processing computer 22 in carrying out one mode of digital image 10 processing according to the present invention. A low pass digital filter (e.g. a 11x11 pixel Gaussian Filter) is applied (36) to the digital image signal Z to produce a low pass digital image signal G. The low pass digital image signal G is subtracted (38) 15 from the suitably delayed digital image signal Z to produce a detail image signal H. The detail image signal H is processed, employing SVD transformation (40), as described in detail below to produce a selectively sharpened detail signal H'.

20 In the SVD process the detail image signal H is block SVD transformed (44), employing the well known SVD computer program listed in Appendix F attached hereto and described on pages 229 to 235 of the book: Computer Methods for Mathematical 25 Computations by G. E. Forsythe, M. A. Malcolm, and C. B. Moler published by Prentice-Hall Inc., Englewood Cliffs, N.J., 1977, to produce singular vector matrices  $U, V^T$ , and a diagonal matrix D of singular values  $d_i$  arranged in order of descending 30 amplitude where:

$$H = UDV^T \quad (1)$$

where: H is an nxn sub block (e.g. 5x5 pixels) of the image,

U contains the eigenvectors of  $HH^T$ ,

35 D is a diagonal matrix which contains

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singular values  $d_1 d_2 \dots d_n$  in  
order of descending amplitude, and  
 $V$  contains the eigenvectors of  $H^T H$ .

The singular values in the diagonal matrix  
5 (array)  $D$  are modified in a non-linear fashion (46)  
by respective individual factors  $f_i$  stored in  
look-up table (LUT) 48 to produce an array  $D'$  of  
modified singular values. The generation of the  
factors stored in the look-up table 48 will be  
10 described in more detail below. The array of  
modified singular values  $D'$  and singular vectors  
 $U, V^T$  are inversely transformed (50) to produce a  
selectively boosted detail signal  $H'$  which is then  
added to the low-pass filtered image  $G$  to produce a  
15 sharpened image  $Z'$ . It is the generation of the  
factors  $f_i$  which is the key to selectively  
boosting just those regions of the detail image  
containing edges or characterized by a higher  
signal-to-noise ratio than the other regions of the  
20 detail image.

The generation of the factors  $f_i$  from a  
non-linear gain function (52 in Fig. 4) will now be  
described with reference to Fig. 5. A digital noise  
image  $N$  generated for example by scanning a  
25 uniformly exposed and developed film is low pass  
filtered (54) for example by a 11 x 11 pixel  
Gaussian digital filter, to produce a low pass  
filtered noise image  $L$ .

The low pass filtered noise image  $L$  is  
30 subtracted (56) from the suitably delayed noise  
image  $N$  to produce a noise detail image signal. The  
noise detail image signal is block SVD transformed  
(58) to produce singular vectors and arrays of  
singular values  $d_i$  for the noise image blocks.  
35 The singular values  $d_i$  from each block of the

-10-

transformed noise detail image are accumulated and the means  $\mu_i$  and standard deviations  $\sigma_i$  of the singular values in the respective positions of the array are calculated (60) as follows:

5

$$\mu_i = \frac{1}{n} \sum_{j=1}^n d_{i,j}; \quad (2)$$

10

$$\sigma_i = \sqrt{\frac{1}{n} \sum_{j=1}^n (d_{i,j} - \mu_i)^2} \quad (3)$$

where  $i$  is an index for the order of singular values, and  $j$  is an index for different blocks.

A factor  $f_i$  for each singular value  $d_i$  is then generated (62) by considering the following facts. The singular values of the noise will be centered at  $\mu_i$  with standard deviation  $\sigma_i$ . The singular values of the shading areas of the image (where little or no sharpening is desired) will have slightly higher values than those of the areas dominated by noise. The singular values of the textured areas of the image (where some sharpening is desired) will have even higher values depending on the texture. The singular values of the edges in the image (where the greatest sharpening is desired) will have much higher values than those of the noise.

Considering the above, each singular value  $d_i$ , is multiplied by a factor  $f_i$  through a 30 non-linear function  $F(d_i, \mu_i, \sigma_i)$  defined as below to produce the output singular value  $d'_i$ .

$$d'_i = f_i * d_i,$$

where

$$f_i = F(d_i, \mu_i, \sigma_i).$$

35

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$$\begin{aligned}
 F(d_i, \mu_i, \sigma_i) &= f_{\min} \\
 &\quad + (f_{\max} - f_{\min}) * (1 - \exp[-a * (\frac{d_i - \mu_i - thl * \sigma_i}{\sigma_i})^p]), \\
 &\quad \text{if } d_i > (\mu_i + thl * \sigma_i); \\
 5 &\quad = f_{\min}, \text{ if } d_i < (\mu_i + thl * \sigma_i). \quad (4)
 \end{aligned}$$

$f_{\max}$  is a constant chosen for image sharpening and has a value (for example) in the range of one to three.  $f_{\min}$  is a constant chosen for the desired noise discrimination, which has a value between zero and one. The parameters  $a$ ,  $p$ , and  $thl$  are determined such that a good noise discrimination in the shading and textured area is achieved. The parameter  $thl$  controls a threshold level. The parameters  $a$  and  $p$  control the transition between  $f_{\max}$  and  $f_{\min}$ .

For noise suppression, one would have  $f_{\min} = 0$  and  $f_{\max} = 1$ . For sharpening,  $f_{\min} = 1$  and  $f_{\max} = 3$ , a choice which leaves noise as it is while boosting the image detail. By combining both features, for example selecting  $f_{\min} = 0$  and  $f_{\max} = 3$ , one achieves sharpening with noise suppression. The noise suppression is not as good as that achieved using larger sized blocks or kernels (as disclosed in the above-referenced related application) but it does provide a second advantage in an algorithm which performs both noise suppression and sharpening simultaneously in the same image.

30 The formula mentioned above is only one form of many possible formulas that can be used as a factor for sharpening. From equation 4, the resulting behavior of  $f_i$  as a function of  $d_i$  is illustrated as a curve in Fig. 6. The effect is to 35 threshold the noise, reduce the singular values for

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shading area, and boost those singular values corresponding to texture and edges. The selection of thresholding level and curve shape depends on the artifacts one might tolerate.

5       The values  $f_i$  of the non-linear gain functions  $F(d_i, \mu_i, \sigma_i)$  are calculated for each singular value  $d_i$  to produce a table of factors  $f_i$  for each singular value. The factors  $f_i$  are digitized in the form of look up tables and  
10      stored in look up table 48 shown in Fig. 4.

A Fortran program for implementing, in a general purpose digital computer, the basic SVD digital image processing method described with reference to Figs. 4 and 5 is listed in List 1 with  
15      reference to the attached appendices.

---

LIST 1

---

This is a basic version of the method which is  
20      described in Figs. 4 and 5.

1. Get a low pass filter ---filter.for....APPENDIX A
  2. Convolve with a filter ---convol.for...APPENDIX B
  3. Get a band-passed image---imgn.for.....APPENDIX C
  - 25 4. Get SVD noise data     ---svdnoi.for....APPENDIX D
  5. Basic version of SVD    ---svd\_basic.for APPENDIX E
  6. Subroutines for above programs  
                           ---svd\_util.for..APPENDIX F
- 

30

According to the presently preferred mode of practicing the invention, the block SVD processing is performed using a moving average technique employing block overlap to reduce the  
35      appearance of blocking artifacts. Fig. 7 is a

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schematic block diagram showing the major steps involved in the block overlap SVD processing.

- For the purpose of simplifying the description, processing incorporating a 4 x 4 pixel 5 block, with a 2 pixel step in the horizontal and vertical directions will be described. Such a block overlap pattern is shown in Fig. 8. In the actual practice, a 5 x 5 pixel block is employed with 1 or more pixel steps, depending on the tolerance of the 10 blocking artifacts. Referring to Fig. 7, an image detail signal H, generated as shown in Fig. 4, is processed by a block SVD process 40 (as shown in Fig. 4) to produce a processed image detail signal H<sub>1</sub>'. Simultaneously, the image detail signal H is 15 delayed by 2 pixels (64) and block SVD processed 40' to produce a processed image detail signal H<sub>2</sub>'. The 2 pixel delay has the effect of shifting the blocks that are processed by 2 pixels, as shown by the blocks of pixels labeled 66 and 68 in Fig. 8. 20 The image detail signal is similarly delayed by 2 lines (70), and 2 lines plus 2 pixels (72) and block SVD processed (40") and (40''') to produce processed image detail signals H<sub>3</sub>' and H<sub>4</sub>' respectively. The 2 line and 2 line plus 2 pixel delays have the 25 effect of shifting the blocks as shown by the blocks of pixels labelled (74) and (76) respectively in Fig. 8. The processed detail signals H<sub>1</sub>', H<sub>2</sub>', H<sub>3</sub>' and H<sub>4</sub>' are registered, summed, and averaged (78) to produce the processed image detail signal 30 H'. The processed image detail signal H' is added to the low pass filtered image signal G to produce the processed image signal Z' as shown in Fig. 4. It will be readily apparent that the processing method may be extended to larger blocks with 35 different amounts of block overlap. A moving

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average SVD Fortran program for implementing the processing method described with reference to Fig. 7 in a general purpose digital computer, is listed in List 2 with reference to the attached appendices.

5

---

**LIST 2**

---

This version of the method includes the block moving average described in Fig. 7.

10

1. SVD with moving average---svd\_move.for..APPENDIX G
  2. Subroutines.....---svd\_util.for..APPENDIX F
- 

15

Multistage processing is not necessary, although on a more complicated scheme one might want to boost different frequency bands differently. A processed image with only a single stage (as shown in Fig. 4) shows good results for most applications.

20

The SVD processing method according to the present invention can be extended to a processing method of the type disclosed in U.S. Patent No. 4,442,454 issued April 10, 1984 to Powell, wherein the processing employs a detail signal representing

25 a pass band of spatial frequencies. The processed digital image signal is obtained, whereby noise from certain spatial frequency content is effectively removed from the image. As shown in Fig. 9 an input digital image Z is filtered through a 3 x 3 pixel

30 low pass filter 80 to obtain the low pass filtered image S. S is subtracted from Z (82) to obtain the difference image Z-S which is a bandpass filtered version of image Z. The difference image signal Z-S is a bandpass version of the original image Z. The

35 bandpass image is processed by the SVD process 40 to

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determine the amount of image sharpening in each area of the image before being combined (92) with the low pass filtered image L to produce the sharpened Z'. The low pass filter coefficients used  
5 to produce the digital filters 80, 84 and 86 are shown in Fig. 10.

A Fortran program for implementing the multi-stage SVD digital image processing method described with reference to Fig. 9 in a general  
10 purpose digital computer, is listed in List 3 with reference to the attached appendices.

---

**LIST 3**

---

15 The basic SVD method applied to the multi-stage processing method described in Figs. 9 and 10.

1. Get the low pass filter

---sml\_filter.for APPENDIX H

20 2. Convolve with a filter ---convol.for...APPENDIX B  
3. Get a band-passed image---imgn.for.....APPENDIX C  
4. Get SVD noise data ---svdnoi.for....APPENDIX D  
5. SVD with moving average---basic.version

of.svd\_for....APPENDIX E

25 6. Subroutines for above

programs

---svd\_util.for..APPENDIX F

---

The moving average technique can be  
30 employed with the multi-stage method described with reference to Fig. 9 as follows. Instead of processing the Z-S image through SVD process 40, the bandpass image can be processed through the block-overlap SVD processing as described above with  
35 reference to Figures 7 and 8. The flow chart of

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this combined processing is shown in Fig. 11. Referring to Fig. 11, a filter and difference amplifier 94 is employed to generate the bandpass image Z-S and a low pass image L from image Z as was 5 described in Fig. 9. A block-overlap SVD process 96, as shown in Fig. 11, is applied to the bandpass signal Z-S to produce a processed bandpass image (Z-S)'. The processed bandpass image is summed (98) with low pass image L to produce processed image Z'.  
10 A Fortran program for implementing the multi-stage, moving average SVD digital image processing method described with reference to Fig. 11, in a general purpose digital computer, is listed in List 4 with reference to the attached appendices.  
15

---

LIST 4

---

This SVD method with the block moving average apply to multi-stage processing method described in Fig. 20 11.

1. Get the low pass filters (s, m, and l)  
---sml\_filter.for APPENDIX H
  2. Convolve with a filter ---convol.for...APPENDIX B
  - 25 3. Get a band-passed image---imgn.for.....APPENDIX C
  4. Get SVD noise data ---svdnoi.for....APPENDIX D
  5. SVD with moving average---svd\_move.for..APPENDIX G
  6. Subroutines for above  
programs  
30 ---svd\_util.for..APPENDIX F
- 

To improve the response to diagonal edges having  $\pm 45^\circ$  orientation, the image blocks are sampled in a trapezoidal pattern as shown in Fig. 35 13. In this figure, we show by example how (for

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- example) a  $4 \times 4$  block of pixels  $P_{n,m}$  can be sampled in three different grid orientations,  $-45^\circ$  (shown by dotted lines),  $0^\circ$  (shown by solid lines), and  $+45$  degrees (shown by dashed lines). Note that
- 5 the three differently oriented sampling patterns have a sub-block of 4 common pixels ( $P_{4,2} P_{5,2} P_{4,3}$  and  $P_{5,3}$ ) in the center. As shown in Fig. 12, the SVD transform is performed on each of the three blocks of different orientations.
- 10 The image detail signal  $H$ , generated as shown in Fig. 4, is processed by a  $0^\circ$  block SVD transform  $44$ ,  $+45^\circ$  block SVD transform  $44'$ , and a  $-45^\circ$  block SVD transform  $44''$ , to produce sets of singular vector matrices  $U$  and  $V^T$  and singular values  $d_i$ .
- 15 The singular values  $d_i$  are noise normalized (100, 102, 104) according to:

$$z_i = (d_i - \mu_i) / \sigma_i \quad (5)$$

- 20 where  $i = 1, 2, \dots, n$ ; and  $\mu_i$  and  $\sigma_i$  are the mean and standard deviations, respectively of the noise singular values  $d_i$ , generated for each block orientation ( $0^\circ$ ,  $45^\circ$ , and  $-45^\circ$ ) as described previously with reference to Fig. 5. The block
- 25 orientation most closely corresponding to the orientation of an edge is selected (106) on the basis of the values of the noise normalized singular value  $z_i$ . Generally, if the orientation of the SVD blocks transform corresponds to the orientation
- 30 of an edge in the image, its noise normalized singular values  $z_i$  decrease faster as the index  $i$  increases, and the first few values  $z_1$  and  $z_2$  are higher than those of blocks not oriented with an edge.
- 35 The selection is performed as follows.

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- Starting from  $i=1$ ,  $z_i$  from each block is compared with the noise level say  $3.5\sigma_i$  for the block orientation. The lowest index  $i$  where the normalized singular value falls within the noise level is noted and denoted  $i_n$ . If  $i_n$  for all 3 block orientations (i.e.,  $0^\circ$ ,  $45^\circ$  and  $-45^\circ$ ) are each different, the block orientation with the lowest  $i_n$  is selected. If the lowest  $i_n$  is the same for two orientations, then the orientation with the largest value of  $(z_1 + z_2)$  is selected. If  $i_n$  is identical for all three orientations, and  $i_n$  is 1, then the region is most likely dominated by noise, and the  $0^\circ$  orientation is selected. If  $i_n$  is the same for all three orientations and  $i_n$  is equal to 2, then the orientation with the largest value of  $z_1$  is selected. If  $i_n$  is the same for all three orientations and  $i_n$  is greater than 2, then an orientation with the largest  $(z_1 + z_2)$  is selected.
- An orientation chosen in this way provides the best representation of the local image detail. A look up table 48 of factors  $f_i$  for modifying the singular values is prepared as was described with reference to Fig. 5 for each block orientation. The appropriate factors  $f_i$  are applied (46) to the singular values  $d_i$  from the block having the selected orientation to produce modified singular values  $d_i'$ . The modified singular values  $d_i'$  and singular vector matrices  $U$  and  $V^T$  are inverse transformed (50) to produce a sharpened image detail signal. The 4 pixels ( $P_{4,2}, P_{5,2}, P_{4,3}$  and  $P_{5,3}$ ) common to all three block orientations are extracted from each processed block to produce the sharpened image detail signal  $H'$ . Finally, the sharpened image detail signal  $H'$  is added back to

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the low pass image signal G to form the processed image signal Z' as shown in Fig. 4. Although the diagonal block SVD processing method was described with reference to 4 x 4 block of pixels for ease of 5 description, the presently preferred block size is 5 x 5 pixels.

The diagonal block SVD processing method is preferably implemented using the multi-stage block overlap technique described with reference to Fig. 10 11, and the center common block portion of 4 pixels 11, and the center common block portion of 4 pixels is extracted from the SVD processed block of that orientation.

A Fortran program for implementing in a general purpose digital computer, the diagonal block 15 SVD processing method described with reference to Fig. 12 is listed in List 5 with reference to the attached appendices.

---

LIST 5

---

20

This version of the method includes the block moving average and 3-orientation described in Fig. 12.

1. Get the low pass filter---filter.for....APPENDIX A
- 25 2. Convolve with a filter ---convol.for....APPENDIX B
3. Get a band-passed image---imgn.for.....APPENDIX C
4. Get SVD noise data ---svdnoi.for....APPENDIX D
5. SVD with moving average and  
and 3-orientations ---svd\_move\_3ori.

30

for.....APPENDIX I

6. Subroutines for above  
programs

---svd\_util.for..APPENDIX F

---

35

The method of the present invention can be

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applied to processing digital color images in a variety of ways. In one mode, the digital color image is separated into red, green, and blue color separation images, and each color separation image  
5 is processed using a block SVD transform method as described above. In the preferred mode of practicing the invention with a color image, the red, green, and blue color image is transformed into a luminance Y (e.g.  $Y = 3/8 R + 4/8 G + 1/8 B$ ) and  
10 two color difference components (R-Y and B-Y). Each of these images is processed using any one of the SVD block transform methods described above to produce processed luminance and color difference signals. The processed luminance and color  
15 difference signals are recombined to produce the processed color image. In an alternative method, the red, green, blue color images are transformed into a luminance (Y), and two color difference components (R-Y and B-Y). Only the luminance image  
20 Y is processed using the block SVD transform method and the processed luminance image is recombined with the color difference components to produce a processed color image. This approach reduces the processing time compared with the method discussed  
25 immediately above.

#### Industrial Applicability and Advantages

The image processing method according to the present invention is useful in graphic arts digital image processing and photographic digital  
30 image processing. The method has the advantages of producing a sharpened image, having reduced noise, and free from undesirable artifacts in areas of texture. The method has the further advantage that image detail is not perceptibly degraded by the  
35 sharpening process.

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APPENDIX A

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```
5   c      filter.for
c      generate filter(mask) file

c      oct-26-87
c      link with svd_util.for
10
      character*32 text,fname,fname2
      dimension table(0:999)

      data ir,iw/5,6/
15      data iu,iu2/99,98/

      write(iw,10)
10      format(/, ' filter: generates filter file',/)

20      c      input

      text='filter file'
      call ascnam(ir,iw,text,fname)
      call blksiz(ir,iw,nbe,nbl)
25      call smplxy(ir,iw,ixsmpl,iysmpl)

      write(iw,32)
32      format(' mode options:'
      1,/,14x,'0:gauss'
      2,/,14x,'1:exp'
      3,/,14x,'2:uniform'
      4,/,14x,'3:user input'
      5,/,14x,'4:input from disk, ascii file'
      1,,' mode, sigma_x,sigma_y')
35      read(ir,*) mode,sigmax,sigmay
```

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```
34      format(1,2f)

      c      user input mask

      5      if(mode.eq.3) then
              write(iw,112)
      112    format(' type line by line: max 10x10 by hand
                  input')
              do 801 j=0,nbl-1
      10     write(iw,114) j
      114    format(lx,i5,' th line ?')
              read(ir,*) (table(j*nbe+1),i=0,nbe-1)
      116    format(10f)
      801    continue
      15     c      enddo    loop j

      else if(mode.eq.4) then
      call clrasc(32,text)
      text='user input disk file'
      20     call ascnam(ir,iw,text, fname2)
              open(unit=iu2,file=fname2,status='old')
              read(iu,*) nbe,nbl,ixsmpl,iysmpl
      216    format(4i)
              do 802 j=0,nbl-1
      25     read(iu,*) (table(j*nbe+1),i=0,nbe-1)
      218    format(10f)
      802    continue
      c      enddo    loop j

      30     else if(mode.eq.0.or.mode.eq.1.or.mode.eq.2)
              then

              xc=(nbe-1)/2.
              yc=(nbl-1)/2.
```

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```
do 803 iy=0,nbl-1
do 804 ix=0,nbe-1

      x=float(ix)-xc
5      y=float(iy)-yc

c      gaussian, exponential, and uniform masks

      if(mode.eq.0) then
10     table(iy*nbe+ix)=gauss(x,sigmax)*gauss
            (y,sigmay)
      else if(mode.eq.1) then
        table(iy*nbe+ix)=exp(-abs(x)/sigmax)*
            exp(-abs(y)/sigmay)
15     else if(mode.eq.2) then
        table(iy*nbe+ix)=1.
      endif
c      mode

20 804 continue
c      enddo    loop ix
803 continue
c      enddo    loop iy

25      endif
c      mode

c      output
open (unit=iu,file=filename,status='new')
30
      write(iu,102) nbe,nbl,ixsmpl,iysmpl,sigmax,
            sigmay
102      format(1x,4i5,2e15.5)
      do 805 i=0,nbe*nbl-1
35      write(iu,104) i,table(i)
```

-24-

```
104      format(lx,i5,e15.5)
805      continue
c      enddo

5          close(iu)

end

10      function gauss(x,sigma)

data pi/3.1415926535/

if(sigma.eq.0.) then
15          if(x.eq.0.) then
                  gauss=1.
                  else if(x.ne.0.) then
                          gauss=0.
                  endif
20          else if(sigma.ne.0.) then
                  arg=(x**2)/(2.*sigma**2)
                  gauss=exp(-arg)/(sqrt(2.*pi)*sigma)
              endif

25      return
end
```

30

35

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APPENDIX B

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```
5   c      convol.for
     c      convolution of an image with a mask(filter)

     c      oct-26-87
     c      link with svd_util.for
10   c      assumes picture is one layer

     character*1 com
     character*32 fnamel,fmask, fname3
15   character*32 text

     dimension bufi(0.99999)
     dimension bufo(0:1999)
     dimension work1(0:2100),work2(0:2100)
20   dimension lp(0:59)
     dimension wt(0:899)

     data ir,iw/5,6/
     data iul,iu2,iu3/51,52,53/
25   c      ne: number of pixels per line (max:2000
           pixels)
     c      nl: number of lines of the image
     c      nbe: # of elements per block (block size in x)
30   c      nbl: # of lines per block (block size in y)

           write(iw,10)
10   format(/, ' convol: makes a convolution of an
           image',/)
```

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```
call picsiz(ir,iw,'i',nc,ne,nl)
call recsiz(ir,iw,ne,lform,lrec)
call winsiz(ir,iw,ne,nl,ixl,ixh,iyl,iyh)
call picnam(ir,iw,l,'i',fnamel)
5      call picopn(iul,fnamel,lrec,'old',' ')
c      input file seqeuntial

text='convolution mask file'

10     call ascopn(iu2,fmask,'old',' ')
c      readonly

call picnam(ir,iw,l,'o',fname3)
call picopn(iu3,fname3,lrec,'new',' ')
15     write(iw,52)
52     format(' normalization by sum of masks
(y:d/n) ?')
read(ir,54) com
20   54   format(al)

read(iu2,*) nbe,nbl,ixsmpl,iysmpl,dum,dum
114   format(lx,4i5,2e15.5)
do 801 j=0,nbl-1
25       do 802 i=0,nbe-1
k=j*nbe+1
read(iu2,116) iorder,wt(k)
write(iw,118) iorder,wt(k)
116   format(lx,i5,e15.5)
30   118   format(ix,i5,'th weight = ',e15.5)
802   continue
c      enddo    loop i
801   continue
c      enddo        loop j
35
```

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```
      close(iu2)

      sum=0.

      5      do 803 k=0,nbe*nbl-1
             sum=sum+wt(k)
803      continue
      c      enddo      loop k

     10     nbec=(nbe-1)*ixsmpl/2
             !center of nbe
             nbcl=(nbl-1)*iysmpl/2
             !center of nbl
             msizz=ixsmpl*(nbe-1)+1
15      msizy=iysmpl*(nbl-1)+1
             nbsizz=ixsmpl*nbe
             nbsizy=iysmpl*nbl

             write(iw,202) ix0,iy0,ixsmpl,iysmpl
20      1,msizz,msizy,nbsizz,nbsizy
202      format(' main: ix0,iy0 = ',2i8
             1,' main: ixsmpl,iysmpl = ',2i8
             1,' main: support size = ',2i8
             1,' main: nbe*ixsmpl,nbl*iysmpl = ',2i8)
25      write(iw,*) 'ok'

      c      let's take care of the border area here

     30     do 810 iy=1,jy0+nbcl
             c      do not bother to do (jy0+nbcl-1) lines
             irec=iy
             read(iul,rec=irec) (bufi(i),i=0,ne-1)
             write(iu3,rec=irec) (bufi(i),i=0,ne-1)
35     c      same one back
```

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```
810    continue
c      enddo    loop iy

          lextra=0
5       do 811 iys=0,iysmpl-1
          jy0=iy0+iys
          nytry=(nl-jy0-(nbl-1)*iysmpl)/iysmpl
c      number of loops in y direction

10      ll=nl-nytry*iysmpl-jy0-nblc
c          remaining extra lines
          if(ll.gt.lextra) lextra=ll
811    continue
c      enddo    loop iys
15
c      write out remaining lines

          if(lextra.gt.0) then
              line3=nl-lextra+1
20
c      starting line for lextra
          do 812 iy=0,lextra-1
              irec=line3+iy
              read(iul,rec=irec) (bufi(i),i=0,ne-1)
25
c      write(iu3,rec=irec) (bufi(i),i=0,ne-1)
812    continue
c          enddo    loop iy
          endif
c      lextra
30
c      ok now run the engine

          do 820 iys=0,iysmpl-1
          jy0=iy0+iys
35
          jx0=ix0
```

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```
mseq=iys

      call engine(ir,iw,iul,iu3,ne,nl,nbe,nbl,
5                  ixsmpl,iysmpl
1,bufi,bufo,lp,work1,work2
2,jx0,jy0,mseq,wt,nbsizz,nbsizy,nbec,nblc,lrec)

820    continue
10   c    enddo  loop iys

c      normalize by the sum of weights

if(com.eq.'n'.or.com.eq.'N') then
15      write(iw,*) ' as you chose, the normalization
                   was not done. '
      else
      denom=sum
      call dskdiv(iu3,iu3,lrec,bufi,ne,nl,denom)
20      endif
      c      !com

      close(iul)
      close(iu3)
25      end

C-----
```

30 subroutine engine(ir,iw,iul,iu3,ne,nl,nbe,nbl,
 ixsmpl,iysmpl
1,bufi,bufo,lp,work1,work2
2,jx0,jy0,mseq,wt,nbsizz,nbsizy,nbec,nblc,lrec)

35 dimension bufi(0:ne\*nbl-1)

-30-

```
c      for nbl lines
dimension bufo(0:ne-1)
      output buffer
dimension lp(0:nbl-1)
5      dimension work1(0:ne+nbe-2)
      dimension work2(0:ne-1)
      dimension wt(0:nbe*nbl-1)

      if(mseq.eq.0) then
10     write(iw,802) nbe,nbl,ixsmpl,iysmpl
      format(' engine: nbe,nbl,ixsmpl,iysmpl=',4i5)
      write(iw,804)
      format(' weights:')
      do 901 k=0,nbe*nbl-1
15     write(iw,806) k,wt(k)
      806   format(lx,i5,e15.5)
      901   continue
c      enddo    loop k

20     endif

nytry=(nl-jy0-(nbl-1)*iysmpl)/iysmpl
c      number of loops in y direction

25     write(iw,800) jx0,jy0,nytry
      800   format(/,' engine: jx0,jy0,nytry:',3i5)

      call ptr0(nbl,lp)
c      initialize pointer lp(k)
30
c      initially read in nbl lines
      do 910 j=0,nbl-1
      linei=jy0+j*iysmpl+1
c          irec starts from 1
      35   read(iul,rec=linei)
```

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(bufi(ne\*lp(j)+i), i=0, ne-1)

```
6      910    continue
      c    enddo    loop j
      5
      linel=jy0+(nbl-1)*iysmpl+1
      c          offset for input line
      linell=jy0+nblc+1
      c          offset for output line
      10
      do 911 iy=0,nytry-1

      linei=linel+iy*iysmpl
      c      !iysmpl
      15
      if(iy.ne.0) then
      read(iul,rec=linei) (bufi(ne*lp(nbl-1)+i),
                           i=0,ne-1)
      c          always read into lp(nbl-1)
      endif
      20  c      iy

      do 912 ixs=0,ixsmpl-1
      ixoff=jx0+ixs
      nxtry=(ne-jx0-ixs)/ixsmpl
      25  c      number of data in x

      c-----beginning of convolution calculation

      call clr(nxtry+nbe-1,work1)
      30  c      clear working area
      call clr(nxtry,work2)
      c      temporary place to hold sampled result

      nbec=(nbe-1)/2
      35  do 913 j=0,nbl-1
```

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```
call movxs(nxtry,ixsmpl,bufi(ne*lp(j)+ixoff),
           workl(nbec))

      c      get data into the working area with offset
      5       nbec
              do 914 i=0,nbe-1
              k=j*nbe+1
              wtij=wt(k)
              call mulcy(nxtry,wtij,workl(i),work2)
      10
      c          accumulate result in work2
      914    continue
      c          enddo    loop i

      15      call movxsi(nxtry,ixsmpl,work2,buf0(ixoff))
      c          get sampled output from the
                  convolution result

      913    continue
      20      c      enddo    loop j

c-----end of convolution calculation

      912    continue
      25      c      enddo    loop ixs

              lineo=linell+iy*iysmpl
              write(iu3,rec=lineo) (buf0(i),i=0,ne-1)

      30      call ptr(nbl,lp)
      c      update pointer

      911    continue
      c      enddo    loop iy
```

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return  
end

5

10

15

20

25

30

35

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APPENDIX C

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```
5   c      imgn.for
      c      arithmetic operations:(add/subtract,multiply,
              and divide)
      c      in n image layers

10  c      sep-2-87
      c      link with iutil.for

      c      assumes picture is a one layer image.

15      character*1 com
            character*32 fname(0:9)

            dimension buf(0:3999,0:9)
            dimension iu(0:9)
20            dimension f(0:9)

            data ir,iw/5,6/
            data iu0/50/
      c      starting unit number
25            c      ne: number of pixels per line
            c      nl: number of lines of the image
            c      n:  number of input files

30            write(iw,10)
10            format(/, ' imgn: arithmetic in n image
              layers',/)
            call picsiz(ir,iw,'i',nc,ne,nl)
            call recsiz(ir,iw,ne,lform,lrec)
35            call winsiz(ir,iw,ne,nl,ixl,ixh,iyl,iyh)
```

-35-

```
        write(iw,22)
22      format(' how many images as an input (max=9)
           ?')
5       read(ir,") n
24      format(i)

          do 801 ifile=0,n
          iu(ifile)=iu0+ifile
10     801  continue
c       assign unit number

          call picnam(ir,iw,n,'i',fname(1))

15     c       read n input file names starting fname(1)

          do 803 ifile=1,n
          call picopn(iu(ifile),fname(ifile),
                     lrec,'old',' ')
20     803  continue
c       enddo      loop ifile

          call picnam(ir,iw,1,'o',fname(0))
c       output file
25

          call picopn(iu(0),fname(0),lrec,'new',' ')

        write(iw,52)
52      format(' a(add),m(mul),d(div) ?')
30
30      read(ir,54) com
54      format(al)

          do 804 i=1,n
          write(iw,56) i
35     56      format(lx,i5,' th factor (real) ?')
```

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```
      read(ir,*) f(i)
58      format(f)
804      continue

5   c      enddo    loop i

60      write(iw,62)
62      format(' overall normalizationn factor
                  (real) ?')
10      read(ir,*) f(0)
64      format(f)
      if(f(0).eq.0.) go to 60

      call engine(ir,iw,iu,lrec, fname
15      l,ne,nl,ixl,ixh,ihl,iyh,buf,n,f,com)

      do 821 ifile=0,n
      close(iu(ifile))
821      continue
20   c      enddo    !loop ifile

      end

c-----
25

      subroutine engine(ir,iw,iu,lrec, fname
1,ne,nl,ixl,ihx,ihl,iyh,buf,n,f,com)

      character*1 com
30      character*32 fname(0:n)
      dimension buf (0:ne-1,0:n),iu(0:n),f(0:n)

      write(iw,12) com,n
12      format(' engine: com,n =',al,i5)
35
```

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```
      do 801 i=1,n
      write(iw,14) f(i)
14      format(9x,'f(i) = ',t35,e15.5)
      continue
801
      5  c    enddo   loop i

      write(iw,16) f(0)
      16     format(9x,'overall normalization = ',e15.5)
      write(iw,705) ixl,ixh,iyl,iyh
10    705     format(' ixl,ixh,iyl,iyh = ',4i5)

      do 802 iy=iyl+1,iyh+1
      c      since irec starts from 1

15      do 803 ifile=1,n
      read(iu(ifile),rec=iy) (buf(i,ifile),i=0,ne-1)
      803     continue
      c      enddo   loop ifile

20      do 804 ix=ixl,ixh
      buf(ix,0)=f(1)*buf(ix,1)
      804     continue
      c      enddo   !loop ix

25      do 805 ifile=2,n
      if(com.eq.'l'.or.com.eq.'A') then
          do 811 ix=ixl,ixh
          buf(ix,0)=buf(ix,0)+f(ifile)*buf
              (ix,ifile)
30    811     continue
      c      enddo   loop ix
      else if(com.eq.'m'.or.com.eq.'M') then
          do 812 ix=ixl,ixh
          buf(ix,0)=buf(ix,0)*f(ifile)*buf
              (ix,ifile)
35
```

-38-

```
812      continue
c          enddo    loop ix
else if(com.eq.'d'.or.com.eq.'D') then
      do 813 ix=ixl,ixh
      5      if(f(ifile)*buf(ix,ifile).ne.0.)
              then
                  buf(ix,0)=buf(ix,0)/(f(ifile)*buf
                  (ix,ifile))
              endif
10     c      divide by zero ?

813      continue
c          enddo    loop ix
      endif
15     c      com

805      continue
c          enddo    !loop ifile

20      do 806 ix=ixl,ixh
            buf(ix,0)=buf(ix,0)/f(0)
806      continue
c          enddo    loop ix

25      write(iu(0),rec=iy) (buf(ix,0),ix=0,ne-1)

802      continue
c          enddo    loop iy

30      return
end
```

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APPENDIX D

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```
5   c      svdnoi.for
      c      calculate svd distribution for a noise patch
      c      oct-26-87
      c      link with svd_util.for
10   c      this program includes the mode options
      c      get a random block starting (ix0,iy0)
      c      input band-pass noise patch (random file)
15   c      output : block size,ixsmpl,iysmpl
      c              order,mean svd,sigma svd,ratio
      c      block size up to 40x40
20   character*32 text,fnamel, fname2
      dimension buf(0:1999,0:39)
      dimension a(0:39,0:39),u(0:39,0:39),
              v(0:39,0:39)
25   data ir,iw/5,6/
      data iul,iu2/51,52/
      c      nbe: # of elements per block (block size)
30   c      ne: number of pixels per linbe (e.g. 400
              pixels, or 1136 pixels)
      c      nl: number of linbes of the image
      write(iw,10)
35  10    format(/' svdnoi: calculate svd distribution
```

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for a noise patch'')

```
call picsiz(ir,iw,'i',nc,ne,nl)
call recsiz(ir,iw,ne,lform,lrec)
5   call picnam(ir,iw,l,'i',fnamel)
    call picopn(iul,fnamel,lrec,'old',' ')
    call blksiz(ir,iw,nbe,nbl)
    call smplxy(ir,iw,ixsmpl,iysmpl)
10  nbsize=nbe*ixsmpl

text='output mean svd file'
call ascnam(ir,iw,text, fname2)
call ascopn(iu2, fname2, 'new', ' ')
15

      write (iw,122)
122  format(' mode'
           1.,t25,'0: 0 degree or 90 degree'
           2.,t25,'1: 45 degree'
20   3.,t25,'2: 135 degree')
      write(iw,110)
110  format(' mode ?')
      read(ir,*) mode
111  format(i)

25

      write(iw,140)
140  format(' ix0,iy0,nxtry,nytry ?')
      read(ir,*) ix0,iy0,nxtry,nytry
142  format(4i)

30

      call hui(ir,iw,iul,lrec,buf,nc,ne,nl,a,u,v
1,nbe,ixsmpl,iysmpl,nbsize,ix0,iy0,nxtry,nytry,
           mode 2,iu2,fnamel,fname2)

35  close(iul)
```

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close(iu2)

end

5

5   c-----  
      subroutine hui(ir,iw,iul,lrec,buf,nc,ne,nl,  
                  a,u,v  
          l,nbe,ixsmpl,iysmpl,nbsize,ix0,iy0,nxtry,nytry,  
10                 mode  
          2,iu2,fnamel, fname2)

c     this subroutine does all the actual  
          processing.

15 c     main program just sets up array sizes for a  
          given picture.

character\*32 fnamel, fname2

20   dimension buf(0:ne-1,0:nbe-1)  
      dimension a(0:nbe-1,0:nbe-1)  
      dimension u(0:nbe-1,0:nbe-1),v(0:nbe-1,  
                  0:nbe-1)

25   dimension work(100)  
      dimension sigma(0:39),id(0:39)  
      dimension fmean(0:39),fsigma(0:39),  
                 ratio(0:39)

30   dimension fsum1(0:39),fsum2(0:39)

c     parameters for svd subroutine

n=nbe

m=nbe

35   nm=nbe

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```

ftot=nxtry*nytry
ftot=ftot*ixsmpl*iysmpl

5      call clrx(nbe+1,fmean)

c      last of nbe for sum of singular values
call clrx(nbe+1,fsigma)
call clrx(nbe+1,fsuml)
10     call clrx(nbe+1,fsum2)

        write(iw,800) mode,ix0,iy0,nxtry,nytry
        1,nbe,ixsmpl,iysmpl,nbsize
800    format(' hui: mode,ix0,iy0,nxtry,nytry =
15          ',5i5,
        1,6x,'nbe,ixsmpl,iysmpl,nbsize = ',4i5)

        ln=iy0

20  c      skip (iy0-1) lines

        do 901 iy=0,nytry-1
c      number of loops in y direction
        linel=iy0+iy*nbsize+1
25

        do 902 iys=0,iysmpl-1
        line2=linel+iys

            do 903 j=0,nbe-1
30  c      read nbe linbes
            irec=line2+j*iysmpl
            read(iul,rec=irec) (buf(i,j),i=0,
            ne-1)
c      just read ne elements
35  903    continue

```

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```
c           enddo      loop nbe
do 904 ix=0,nxtry-1
      number of loops in x direction
5
ixoffl=ix0+nbsize*ix
if(mode.eq.1) then
    ixoffl=ixoffl+nbsize/2
else if(mode.eq.2) then
10          ixoffl=ixoffl=nbsize/2
endif

do 905 ixs=0,ixsmpl-1
ixoff2=ixoffl+ixs
15

do 906 j=0,nbe-1
c     get a block into a(k,j)
      do 907 k=0,nbe-1
      kk=ixoff2+k*ixsmpl
20      if(mode.eq.0)then
          a(k,j)=buf(kk,j)
c     straight
          else if(mode.eq.1)then
              a(k,j)=buf(kk-j,j)
25 c     45 degree slant
          else if(mode.eq.2)then
              a(k,j)=buf(kk+j,j)
c     135 degree slant
          endif
30 c     mode?
907 continue
906 continue
c           end of loop j
c           end of loop k
```

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```
call svd(nm,m,n,a,sigma,.false.,u,.false.,
         v,ierr,work)
c      no need to calculate U and V matrix. so the
         input is .false.
5
if(ierr.ne.0) write(iw,20) ierr,line2,ixoff2
20  format(' trouble. ierr= ',i4,' at line2,ixoff2
         = ',2i5)

10   call sort(nbe,sigma,id)
c      sort in descending order

c      sigma(i,l(id)): ith singular value

15   toteig=0.
c      sum of eigen values
do 911 l=1,nbe-1
      toteig=toteig+sigma(l)
911  continue
20  c      end of loop 1

do 912 l=0,nbe
if(l.eq.nbe) then
fsuml(l)=fsuml(l)+toteig
25  fsum2(l)=fsum2(l)+toteig**2
else
fsuml(l)=fsuml(l)+sigma(l)
fsum2(l)=fsum2(l)+sigma(l)**2
endif
30  912  continue
c      end of loop 1

905  continue
c      end of loop ixs
35  904  continue
```

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```
c      end of loop ix

902    continue
c      end of loop iys
5  901    continue
c      end of loop iy

ok now calculate statistics

10      write(iw,100)
100     format(3x,1,10x,'fmean',10x,'fsigma')

do 913 l=0,nbe
fmean(l)=fsum1(l)/ftot
15      fsigma(l)=fsum2(l)/ftot-fmean(l)**2
          if(fsigma(l).lt.0.) then
          write(5,105) l,fmean(l),fsigma(l)
          fsigma(l)=0.
          endif
20      105     format(' l,fmean(l),fsigma(l) = ',i5,2e15.5)

fsigma(l)=sqrt(fsigma(l))

if(fsigma(l).eq.0.) then
25      ratio(l)=0.
else
          ratio(l)=fmean(l)/fsigma(l)
endif
c      fsigma(l) ?
30
913    continue
c      end of loop l

35      108     write(iu2,108) nbe,ixsmpl,iysmpl
format(1x,3i10)
```

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```
      do 921 l=0,nbe
c      write final result
      if(l.eq.nbe) then
 5       write(iw,110) fmean(l),fsigma(l),ratio(l)
         write(iu2,110) fmean(l),fsigma(l),ratio(l)
110     format(//,6x,3e15.5)
      else
         write(iw,120) l,fmean(l),fsigma(l),ratio(l)
10       write(iu2,120) l,fmean(l),fsigma(l),ratio(l)
120     format(1x,i5,3e15.5)
      endif
921     continue
c      enddo
15
      write(iu2,130) fname2,fnamel
130     format(/' svd noise file name = ',a32
           1,' from data file: ',a32)

20      write(iu2,140) nc,ne,nl
140     format(//,' input parameters were: nc,ne,nl =
           ',3i5)
      write(iu2,150) nbe,ixsmpl,iysmpl,mode,ix0,iy0,
           nxtry,nytry
25 150     format(' nbe,ixsmpl,iysmpl = ',3i5
           1,' mode,ix0,iy0,nxtry,nytry = ',5i5)

      return
      end
30
```

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APPENDIX E  
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5           C     SHARPENING AND NOISE SUPPRESSION BY SINGULAR  
              VALUE DECOMPOSITION

10          C     SVD\_BASIC.FOR -- BASIC VERSION

10          C     link with svd\_util.for

15          C     DEC-20-88

15          C     maximum svd block size : 0x40

20          C     dimension BUFI(0:1999,0:39)  
              dimension BUFO(0:1999,0:39)  
              dimension A(0:39,0:39),U(0:39,0:39),  
              V(0:39,0:39)  
              dimension WT(0:39)  
              dimension FC(0:39),DFC(0:39),RATIO(0:39)

25          C     data IR,IW/5,6/

25          C     data iui,iuo,iun/51,52,53/  
              data iuw/61/  
              data a,u,v/1600\*0.,1600\*0.,1600\*0./,  
              data wt/40\*0./

30          C     data fc,dfc,ratio/40\*0.,40\*0.,40\*0./

35          C     NBE: # of elements per block (BLOCK SIZE)  
              C     NE: number of pixels per line(e.g. 500 pixels)  
              C     NL: number of lines of the image  
              35    C     ixsmpl,iysmpl : sampling in x and y directions

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C INPUT

c define image size : nc,ne,nl  
5 call picsiz (ir,iw,'I',nc,ne,nl)

c define image record size  
call recsiz (ir,iw,ne,lform,lrec)

10 c open input image file  
call ifile (ir,iw,iui,lform,lrec)

c read noise data file  
call nfile (ir,iw,iun,nbe,ixsmpl,iysmpl,fc,  
15 dfc,ratio)

c open output image file  
call ofile (ir,iw,iuo,lform,lrec)

20 c get pre/post processing weights  
call wfile (ir,iw,iuw,modew,nbe,wt,sum )  
  
write (iw,122)  
122 format (' Starting pixel position: IX0,IY0 ?')  
25 read (ir,\*) ix0,iy0

c block orientation mode = 0 (0 or 90 degree)  
  
modeb=0  
30  
write (iw,151)  
151 format (' Boost formula'  
3,/, ' 6: THRESHOLD1 ,EXP(-A\*X\*\*4) AND FMIN,FMAX')

35 write (iw,152)

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```
152      format (' Boost formula(I) ?')
           read (ir,*) iform

*
           write (iw,162)
5  162      format (' THRSH1(R),POWER(R),FMIN,FMAX,
                  COEFF(FOR 6:) ?')
           read (ir,*) thrsh1,power,fmin,fmax,coeff

10      msize = ixsmpl*(nbe-1)+1
           nbsize = ixsmpl*nbe

           write (iw,202) nbe,ix0,iy0,ixsmpl,iysmpl,
                  msize,nbsize
202      format (' MAIN: NBE,IX0,IY0 = ',T30,3I8
15      1,' MAIN: IXSMPL,IYSMPL = ',T30,2I8
2,' MAIN: SUPPORT SIZE = ',T30,I8
3,' MAIN: NBE*IXSMPL = ',T30,I8)
204      format (' MODEW, SUM OF WEIGHTS = ',I5,E15.5)

20      if (modew.ne.0) then
           write (iw,204) modew,sum
        endif

25      jy0 = iy0
           jx0 = ix0

           call hui (ir,iw,iui,iuo,nc,ne,nl,nbe,
                  ixsmpl,iysmpl
1           ,bufi,bufo,a,u,v,fc,dfc,ratio
2           ,iform,thrsh1,coeff,power,fmin,fmax
3           ,jx0,jy0,modew,wt,lrec)

           if (modew.eq.1.or.modew.eq.2) then
             denom = (sum*sum)/(nbe*nbe)
35           call dskdiv (iuo,iuo,lrec,bufo,ne,nl,denom)
```

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```
        endif  
c      close (iui)  
c      close (iuo)  
  
5       end  
  
c-----  
  
10      subroutine hui(ir,iw,iui,iuo,nc,ne,nl,nbe,  
           ixsmpl,iysmpl  
1       ,bufi,bufo,a,u,v,fc,dfc,ratio  
2       ,iform,thrsh1,coeff,power,fmin,fmax  
3       ,jx0,jy0,modew,wt,lrec)  
  
15  C   THIS SUBROUTINE DOES ALL THE ACTUAL PROCESSING.  
C   MAIN PROGRAM JUST SETS UP ARRAY SIZES FOR A  
     GIVEN PICTURE.  
  
20      dimension bufi(0:ne-1,0:nbe-1)  
dimension bufo(0:ne-1,0:nbe-1)  
dimension a(0:nbe-1,0:nbe-1)  
dimension u(0:nbe-1,0:nbe-1),  
           v(0:nbe-1,0:nbe-1)  
dimension work(100)  
25      dimension fc(0:39),dfc(0:39),ratio(0:39)  
dimension id(0:39),sigma(0:39)  
dimension wt(0:nbe-1)  
  
30      n      = nbe  
m      = nbe  
nm    = nbe  
nbrxs = nbe*ixsmpl  
  
35      nxtry = (ne-jx0-nbe)/nbrxs-1  
nytry = (nl-jy0-nbe)/nbrxs
```

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```
if (((nytry-1)*nbrxs +nbe).gt.nl) then
    nytry = nytry-1
endif
lexttra = nl-nytry*nbrxs-jy0
5
      write (iw,802) nbe,ixsmpl,iysmpl
      1 ,iform,thrshl,power,fmin,fmax,coeff
802   format(' HUI: nbe,ixsmpl,iysmpl= ',3i5,/
      1 ' boost formula,thrshl,power,fmin,fmax,
10     coeff = '
      2 ,/,lx,I5,5E15.5)
      write (iw,835) jx0,jy0,nxtry,nytry
835   format (/, ' HUI: jx0,jy0,nxtry,nytry',4i5)

15  c      skip jy0 lines

      if (jy0.ge.1)then
          do 840, iy = 0,jy0 -1
          irec = iy+1
20      read (iui,rec=irec) (bufi(i,0),i=0,ne-1)
          write (iu0,rec=irec) (bufi(i,0),i=0,ne-1)
840      continue
      endif
      c      processing the input image block by block
25
      do 910, iy = 0,nytry-1
          line1 = jy0+l+iy*nbrxs

      do 910, iys = 0,iysmpl-1
30      line2 = line1+iys

      c      read in nbe lines from the input image into
            bufi
      do 850, j = 0,nbe-1
35      linei = line2+j *iysmpl
```

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```
      read (iui,rec=linei) (bufi(i,j),i=0,ne-1)

      c     initialize the output buffer -- bufo

      5       do 845, jj = 0,nbe-1
              do 845, ii = 0,ne-1
                  bufo(ii,jj) = 0.
      845       continue
      850       continue

      10      c     set up array A(i,j)

              do 900, ix = 0,nxtry-1
                  ixoff1 = jx0 +nbrxs*ix
      15      do 900, ixs = 0,ixsmpl-1
                  ixoff2 = ixoff1+ixs+(nbe/2)*ixsmpl
                      do 860, j = 0,nbe-1
                      do 860, i = 0,nbe-1
      20          ii = ixoff2+i*ixsmpl
                      a(i,j) = bufi(ii,j)
                      continue
                      call svd (nm,m,n,a,sigma,.true.,u,
                                .true.,v,ierr,work)
      25      if (ierr.ne.0) then
                      write (iw,20) ix,iy,ierr
      20          format (' TROUBLE. IX,IY,IERR= ',3I6)
                      do 865, l = 0,nbe-1
                          write (iw,22) l,sigma(l)
      30          format (lx,i3,'th singular value =
                                ',E15.5)
      22          continue
      865          do 866 i=0,ierr-1
                      sigma(i)=0.
      35
```

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```
866      continue
        endif
*
5       C      sort sigma(==singular values) in descending
           order
*
           call sort (nbe,sigma,id)
*
10      C      SIGMA(I,L(ID)): Ith SINGULAR VALUE
           C      COMPUTE NEW A(I,J) ACCORDING TO CORING
           C      FORMULAR(IFORM) FROM SIGMA, U, AND V.
           call newaij (ir,iw,nbe,id,a,sigma,u,v,fc,
                         dfc,ratio
15      l      ,iform,thrshl,coeff,power,fmin,fmax)
*
           if (modew.eq.-1) then
               do 885, j = 0,nbe-1
               do 885, i = 0,nbe-1
20           a(i,j) = a(i,j)/wt(i)/wt(j)
           continue
885
           else if (modew.eq.1) then
               do 890, j = 0,nbe-1
               do 890, i = 0,nbe-1
25           a(i,j) = a(i,j)*wt(i)*wt(j)
           continue
890
           endif
*
C      UPDATE OUTPUT BUFFER : BUFO
30
           do 895, j = 0,nbe-1
           jj =j
           do 895, i = 0,nbe-1
           ii =ixoff2+i*ixsmp1
35           bufo(ii,jj) = bufo(ii,jj)+a(i,jj)
```

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```
895      continue

900      continue

5   C      WRITE LINES OUT TO DISK (AFTER NN LINES, MM
           BLOCKS ARE PROCESSED)

           do 905, j =0,nbe-1
           lineo = line2+j*iysmpl
10          write (iuo,rec=lineo) (bufo(i,j),
           i=0,ne-1)
905      continue

910      continue
15   C      WRITE OUT REMAINING LINES

           if (lextra.gt.0) then
           line3 = nl-lextra+1
           do 915, iy = 0,lextra-1
20          irec = line3+iy
           read (iui,rec=irec) (bufi(i,0),i=0,ne-1)
           write (iuo,rec=irec) (bufi(i,0),i=0,ne-1)
915      continue
           endif
25          return
           end

C-----  
30
           subroutine newaij (ir,iw,nbe,id,a,sigma,u,v,
           fc,dfc,ratio
           1,iform,thrshl,coeff,power,fmin,fmax)

35      logical first
```

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```
dimension a(0:nbe-1,0:nbe-1)
dimension sigma(0:nbe-1),id(0:nbe-1)
dimension u(0:nbe-1,0:nbe-1),v(0:nbe-1,
      0:nbe-1)
5      dimension fc(0:39),dfc(0:39),ratio(0:39)

      data first/.true./

      if(first) then
10      write (iw,8888) iform,thrshl,power,fmin,
            fmax,coeff
      8888      format (' newaij: iform,tl,p,t2,c = ',
            i5,4f6.2)
      first=.false.
15      endif

      do 100, j = 0,nbe-1
      do 100, i = 0,nbe-1
      a(i,j) = 0.
20  100      continue

      c      determine threshold formula

      if(iform.eq.6) then
25      call iform6(ir,iw,nbe,id,a,sigma,u,v,fc,
            dfc,ratio
      l,iform,thrshl,coeff,power,fmin,fmax)
      endif

      30      return
      end

      c-----  
c      Boost formula 6
35
```

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```
subroutine iform6 (ir,iw,nbe,id,a,sigma,u,v,
      fc,dfc,ratio
      l,iform,shrshl,coeff,power,fmin,fmax)

      dimension a(0:nbe-1,0:nbe-1)
      dimension sigma(0:nbe-1),id(0:nbe-1)
      dimension u(0:nbe-1,0:nbe-1),v(0:nbe-1,
      0:nbe-1)
      dimension fc(0:39),dfc(0:39),ratio(0:39)
10    do 120, l = 0,nbe-1

      c      depending on IFORM choose threshold level

15    ff = 1.

      if (sigma(l).ge.0.) then
        zz = (sigma(l)-fc(l))/dfc(l)

20    if (zz.le.thrshl) then
        ff = fmin
      else if (zz.gt.thrshl) then
        arg = coeff*((zz-thrshl)**power)
        if (arg.le.0.000000001) then
          delf = delf*(1.+arg)
        else if (arg.gt.0.000000001.and.arg.
25      le.10.) then
          delf = delf*(1.-exp(-arg))
        else if (arg.gt.10.) then
          delf = delf
        endif
      c      end of arg ?

30      ff = fmin + delf
      endif
```

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```
      enf of (zz...
else if(sigma(1).eq.0.) then
ff=l.

5      else if (sigma(1).lt.0.) then
write (iw,505) ix,iy,l,sigma(1)
505    format (' ix,iy,l,sigma(1)',3i5,e15.5)
ff = l.
endif
10   c   end of (sigma(1)...

      do 110, j = 0,nbe-1
      do 110,i = 0,nbe-1
      a(i,j) = a(i,j)+ff*sigma(1)*u(i,id(1))*v(j,id(1))
15
110    continue

120    continue
      return
20
20      end
```

C-----

```
25      subroutine nfile(ir,iw,iun,nbe,ixsmpl,
      , iysmpl,fc,dfc,ratio)

      character*32      text, fname

      dimension fc(0:nbe-1),dfc(0:nbe-1),
30      , ratio(0:nbe-1)

      text='svd noise file for      0 degree'
      call ascnam(ir,iw,text,fname)
      call ascopn(iun,fname,'old',' ')
35
```

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```
      read(iun,*) nbe,ixsmpl,iysmpl  
  
      write(iw,115) fname  
115      format(' noise file:',a32,/br/>5       l 1x,'order',10x,' mean',10x,'sigma',10x,  
           'ratio')  
  
      do 802 l=0,nbe-1  
      read(iun,*) iorder,fc(l),dfc(l),ratio(l)  
10      write(iw,116) iorder,fc(l),dfc(l),ratio(l)  
116      format(1x,i5,3e15.5)  
802      continue  
C      enddo          !loop 1  
      close(unit=iun)  
15  
  
      return  
      end
```

20

25

30

35

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APPENDIX F  
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```

5      c     svd_util.for
c     subroutines called by :
c           filter.for, convol.for, ingn.for
c           svd_basic.for, svd_move.for
10    c           svdnoi.for, and svd_move_3ori.for
c
c     OCT-26-87
c-----
c     subroutine svd(nm,m,n,a,w,matu,u,matv,v,
15      ierr,rvl)
c                                     compute svd
c     sort(n,s,id)                 sort svd
c     ifile(ir,iw,iui,lform,
c           lrec)                   open input picture
c                                     file
20    c     ofile(ir,iw,iuo,lform,
c           lrec)                   open output picture
c                                     file
c     wfile(ir,iw,iuw,modew,
c           nbe,wt,sum)            get pre/post
c                                     processing weights
c     picsiz(ir,iw,mode,nc,
c           ne,nl)                 asks picture size
25    c     recsiz(ir,iw,ne,lform,
c           lrec)                  asks record size
c     winsiz(ir,iw,ne,nl,ixl,
c           iyl,ixh,iyh)          asks window size
30    c     boxesiz(ir,iw,ix0,iy0,
c           nx,ny)                 asks box size
c     xyorig(ir,iw,ix0,iy0)    asks xy origin
c     blksiz(ir,iw,nbe,nbl)    asks block size
c     smplxy(ir,iw,ixsmpl,
c           iysmpl)                asks sampling steps
35

```

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```

c      dirnam(ir,iw,dname)      asks directory name
c      picnam(ir,iw,nfiles,
5       mode, fname)           asks file names
c      picopn(iu, fname, lrec,
c              status, com)       opens a picture file
c      ascopn(iu, fname, status,
c              com)                opens an ascii file
c      ascnam(ir,iw,text,
c              fname)              asks an ascii file
10     c      clrasc(n, text)      name
c      rdlin(iu, n, buf, com,
c              irec)               clears an ascii array
c      wrlin(iu, n, buf, com,
c              irec)               read a line
c      ptr0(n, lp)              write a line
15     c      pointer            pointer
c      ptr(n, lp)              initialization
c      clr(n, z)               update a line pointer
c      movxs(n, ixs, buf, pic)
20      c      z(i)=0             z(i)=0
c      pic(i) gets sampled
c      buf(i)                 buf(i)
c      movxsi(n, ixs, pic, buf) inverse of movxs
c      mulcy(n, c, y, z)        z(i)=z(i)+c*y(i)
c      dskdiv(iuil, iu2, lrec,
c              buf, ne, nl, fdiv)
25     c      read a line, div by const and write
c              back
c-----
c
30      subroutine svd(nm,m,n,a,w,matu,u,matv,v,ierr,
c                      rvl)
integer i,j,k,l,m,n,ii,il,kk,kl,ll,nn,mn,nm,
its,ierr
real a(nm,n),w(n),u(nm,n),v(nm,n),rvl(n)
real c,f,g,h,s,x,y,z,scal,anorm
35     logical matu,matv

```

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c  
c this subroutine is from the book "computer methods  
c for mathematical computations" by g.e. forsythe,  
c m.a. malcolm, and c.b. moler, 1977. prentice-hall,  
5 c inc., englewood cliffs, new jersey 07632. pp. 229-  
c 235.  
c  
c this subroutine determines the singular value  
c decomposition  
10 c t  
c a=usv of a real m by n rectangular matrix.  
c householder  
c bidiagonalization and a variant of the qr  
c algorithm are used.  
15 c  
c on input:  
c nm must be set to the row dimension of two-  
c dimensional array  
c parameters as declared in the calling program  
20 c dimension statement.  
c note that nm must be at least as large as the  
c maximum of m and n.  
c  
c m is the number of rows of a (and u).  
25 c n is the number of columns of a (and u) and the  
c order of v.  
c a contains the rectangular array to be  
c decomposed.  
c  
30 c matu should be set to .true. if the u matrix in  
c the decomposition is desired, and to .false.  
c otherwise.  
c  
c matv should be set to .true. if the v matrix in  
35 c the decomposition is desired, and to .false.

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otherwise.

c on output:

c a is unaltered (unless overwritten by u or v).

c

5 c w contains the n (non-negative) singular values  
c of a (the diagonal elements of s). they are  
c unordered. if an error exit is made, the  
c singular values should be correct for indices  
c ierr+1, ierr+2, ..., n.

10 c

c u contains the matrix u (orthogonal column  
c vectors of the decomposition if matu has been  
c set to .true. otherwise, u is used as a  
c temporary array. u may coincide with a. if an  
15 c error exit is made, the columns of u  
c corresponding to indices of correct singular  
c values should be correct.

c

c v contains the matrix v (orthogonal) of the  
20 c decomposition if matu has been set to .true.  
c otherwise, v is not referenced. v may also  
c coincide with a if u is not needed. if an  
c error exit is made, the columns of v  
c corresponding to indices of correct singular  
25 c values should be correct.

c

c ierr is set to

c zero for normal return

c k if the k-th singular values has not

30 c been determined after 30 iterations.

c

c rvl is a temporary storage array.

c

ierr=0

35 do 100 j=1,n

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```
      do 100 i=1,m
      u(i,j)=a(i,j)
100      continue
c   householder reduction to bidiagonal form
5       g=0.0
         scale=0.0
         anorm=0.0
c
         do 300 i=1,n
10      l=i+1
         rvl(i)=scale*g
         g=0.0
         s=0.0
         scale=0.0
15      if(i.gt.m) goto 210
c
         do 120 k=i,m
120      scale=scale+abs(u(k,i))
c
20      if(scale.eq.0.0) goto 210
c
         do 130 k=i,m
         u(k,i)=u(k,i)/scale
         s=s+u(k,i)**2
25      130      continue
c
         f=u(i,i)
         g=-sign(sqrt(s),f)
         h=f*g-2
30      u(i,i)=f-g
         if(i.eq.n) goto 190
c
         do 150 j=1,n
         s=0.0
35      c
```

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```
      do 140 k=i,m
          s=s+u(k,i)*u(k,j)
c
      f=s/h
5   c
      do 150 k=i,m
          u(k,j)=u(k,j)+f*u(k,i)
150    continue
c
10   190      do 200 k=i,m
200    u(k,i)=scale*u(k,i)
c
210    w(i)=scale*g
      g=0.0
15
      s=0.0
      scale=0.0
      if(i.gt.m.or.i.eq.n) goto 290
c
      do 220 k=l,n
20   220      scale=scale+abs(u(i,j))
c
      if(scale.eq.0.0) goto 290
c
      do 230 k=l,n
25
      u(i,k)=u(i,k)/scale
      s=s+u(i,k)**2
230    continue
c
      f=u(i,l)
30
      g=-sign(sqrt(s),f)
      h=f*g-s
      u(i,l)=f-g
c
      do 240 k=l,n
35   240      rvl(k)=u(i,k)/h
```

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```
c
      if(i.eq.m) goto 270
c
      do 260 j=1,m
5      s=0.0
c
      do 250 k=1,n
250      s=s+u(j,k)*u(i,k)
c
10     do 260 k=1,n
        u(j,k)=u(j,k)+s*rvl(k)
260     continue
c
270     do 280 k=1,n
15 280     u(i,k)=scale*u(i,k)
c
290     anormamaxl(anorm,abs(w(i))+abs(rvl(i)))
300     continue
c ... accumulation of right-hand transformation .....
20     if(.not.matv) goto 410
c ... for i=n step -1 until 1 do .....
      do 400 ii=1,n
        i=n+1-ii
        if(i.eq.n) goto 390
25     if(g.eq.0.0) goto 360
c
      do 320 j=1,n
c ... double division avoids possible underflow .....
320     v(j,i)=(u(i,j)/u(i,1))/g
30 c
      do 350 j=1,n
        s=0.0
c
      do 340 k=1,n
35 340     s=s+u(i,k)*v(k,j)
```

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c  
do 350 k=1,n  
v(k,j)=v(k,j)+s\*v(k,i)  
350 continue  
5 c  
360 do 380 j=1,n  
v(i,j)=0.0  
v(j,i)=0.0  
380 continue  
10 c  
390 v(i,i)=1.0  
g=rvl(i)  
l=i  
400 continue  
15 c ... accumulation of left-hand transformations ...  
410 if(.not.matu) goto 510  
c ... for i=min(m,n) step -1 until l do ...  
mn=n  
if(m.lt.n) mn=m  
20 c  
do 500 ii=1,mn  
i=mn+l-ii  
l=i+1  
g=w(i)  
25 if(i.eq.n) goto 430  
c  
do 420 j=1,n  
420 u(i,j)=0.0  
c  
30 430 if(g.eq.0.0) goto 475  
if(i.eq.mn) goto 460  
c  
do 450 j=1,n  
s=0.0  
35 c

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```
      do 440 k=l,m
440          s=s+u(k,i)*u(k,j)
      c ... double division avoids possible underflow
          f=(s/u(i,i))/g
5  c
      do 450 k=i,m
      u(k,j)=u(k,j)+f*u(k,i)
450          continue
      c
10 460          do 470 j=i,m
470          u(j,i)=u(j,i)/g
      c
      goto 490
      c
15 475          do 480 j=i,m
480          u(j,i)=0.0
      c
490          u(i,i)=u(i,i)+1.0
500          continue
20  c
      c   diagonalization of the bidiagonal form ...
      c   for k=n step -1 until 1 do ...
510          do 700 kk=1,n
          kl=n-kk
25          k=kl+1
          its=0
      c   test for splitting
      c   for l=k step -1 until 1 do ...
520          do 530 ll=1,k
30          ll=k-ll
          l=ll+1
          if(abs(rvl(l))+anorm.eq.anorm) goto 565
      c   rvl(l) is always zero, so there is no exit
      c   through the bottom of the loop ...
35          if(abs(w(ll))+anorm.eq.anorm) goto 540
```

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```
530      continue
c   cancellation of rvl(l) if l greater than 1 ...
540      c=0.0
         s=1.0
5   c
         do 560 i=l,k
         f=s*rvl(i)
         rvl(i)=c*rvl(i)
         if(abs(f)+anorm.eq.anorm) goto 565
10
         g=w(i)
         h=sqrt(f*f+g*g)
         w(i)=h
         c=g/h
         s=-f/h
15
         if(.not.matu) goto 560
         c
         do 550 j=l,m
         y=u(j,l1)
         z=u(j,i)
20
         u(j,l1)=y*c+z*s
         u(j,i)=-y*s+z*c
         550      continue
         c
         560      continue
25   c   test for convergence ..
565      z=w(k)
         if(l.eq.k) goto 650
         c   shift from bottom 2x2 minor ...
         if(its.eq.30) goto 1000
30
         its=its+1
         x=w(l)
         y=w(kl)
         g=rvl(kl)
         h=rvl(k)
35
         f=((y-z)*(y+z)+(g-h)*(g+h))/(2.0*h*y)
```

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```

g=sqrt(f*f+1.0)
f=((x-z)*(x+z)+h*(y/(f+sign(g,f))-h))/x
c    next qr transformation ...
c=1.0
5      s=1.0
c
do 600 il=1,k1
i=il+1
g=rvl(i)
10     y=w(i)
h=s*g
g=c*g
z=sqrt(f*f+h*h)
rvl(il)=z
c=f/z
s=h/z
f=x*c+g*s
g=-x*s+g*c
h=y*s
20     y=y*c
if(.not.matv) goto 575
do 570 j=1,n
x=v(j,il)
z=v(j,i)
25     v(j,il)=x*c+z*s
v(j,i)=-x*s+z*c
570     continue
c
575     z=sqrt(f*f+h*h)
30     w(il)=z
c    rotation can be arbitrary if z is zero ...
if(z.eq.0.0) goto 580
c=f/z
s=h/z
35 580     f=c*g+s*y

```

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```
x=-s*g+c*y
if(.not.matu) goto 600
c
do 590 j=1,m
5      y=u(j,i1)
      z=u(j,i)
      u(j,i1)=y*c+z*s
      u(j,i)=-y*s+z*c
590      continue
10      c
600      continue
c
rvl(l)=0.0
rvl(k)=f
15      w(k)=x
      goto 520
c      convergence ...
650      if(z.ge.0.0) goto 700
c      w(k) is made non-negative ...
20      w(k)=-z
      if(.not.matv) goto 700
c
do 690 j=1,n
690      v(j,k)=-v(j,k)
25      c
700      continue
c
      goto 1001
c      set error .. no convergence to a singular value
30      c                  after 30 iterations ...
1000      ierr=k
1001      return
      end
35      c-----
```

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```
      subroutine sort(n,s,id)
      dimension s(0:49),id(0:49)
      c
      5   c      array id contains index of array s after
              sorting permutation
      c
      do 20 i=0,n-1
          id(i)=i
10    20      continue

      do 30 j=1,n-1
          v=s(j)
          idv=id(j)
15    do 40 i=0,j-1
          if(v.lt.s(i)) goto 40
          do 50 k=i,j-1
              il=j+i-k
              i2=il-1
20    s(il)=s(i2)
              id(il)=id(i2)
      50      continue
              s(i)=v
              id(i)=idv
25    go to 30
40    continue
30    continue
      return
      end
30

C-----
```

subroutine ifile(ir,iw,iui,lform,lrec)

35 character\*32 fnamei

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```
call picnam(ir,iw,l,'i',fnamei)
call picopn(iui,fnamei,lrec,'old',' ')
c      !readonly
5
      return
end

C-----10
10
      subroutine ofile(ir,iw,iuo,lform,lrec)

      character*32          fnameo

15      call picnam(ir,iw,l,'o',fnameo)
      call picopn(iuo,fnameo,lrec,'new',' ')

      return
end

20
C-----25
25
      subroutine wfile(ir,iw,iuw,modew,nbe,wt,sum)

      character*32 text,wname

      dimension wt(0:nbe-1)

      write(iw,402)
30  402      format(' weight option(-1:2)'
     1,' -1: pre weighting'
     1,' 0: no weighting'
     1,' 1: post weighting'
     1,' 2: pre and post weighting'
     1,' weight mode ?')
35
```

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```
      read(ir,*) modew
c408      format(i)

      if(modew.ne.0) then
5
      text='l-dim weight file'
      call ascnam(ir,iw,text,wname)
      call ascopn(iuw,wname,'old',' ')
      read(iuw,*) nbew,idum,idum,idum,gsigma,dummy
      if(nbew.ne.nbe) then
      write(iw,*) 'nbe.ne.nbew'
      stop
      endif
15      do 801 i=0,nbe-1
      read(iuw,*) iorder,wt(i)
      c424      format(lx,i5,e15.5)
      801      continue
      c      enddo      !loop i
20
      sum=0.
      do 802 i=0,nbe-1
      sum=sum+wt(i)
      802      continue
25      c      enddo      !loop i

      endif
      c      !modew ?

30      return
      end

C-----
```

35 subroutine picsiz(ir,iw,mode,nc,ne,nl)

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```
character*1 mode

      if(mode.eq.'i'.or.mode.eq.'I') then
 5   1       write(iw,2)
      2       format(' input image size: colors,
                  elements,lines ?')
      else if(mode.eq.'o'.or.mode.eq.'O') then
      write(iw,4)
 10  4       format(' output image size: colors,
                  elements,lines ?')
      endif

      read(ir,*) nc,ne,nl
 15

      write(iw,20) nc,ne,nl
 20      format(' picsiz: nc,ne,nl = ',3i7)

      return
 20      end
```

C-----

```
subroutine recsiz(ir,iw,ne,lform,lrec)

 25  1       write(iw,10)
 10      format(' format 69 or 81 or 99(sun) or 77
                  (cray) (i) ?')
      read(ir,*) lform

 30      if(lform.eq.69) then
      lrec=ne
      else if(lform.eq.77) then
      lrec=ne*8
      else if(lform.eq.99) then
 35      lrec=ne*4
```

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```
c      !since sun recordlength is in bytes
      else if(lform.eq.81) then
      lrec=((ne*4-1)/512+1)*512/4
c      !(ne*4) bytes
5       endif
      write(iw,20) lform,lrec
20      format(' recsiz: lform = ',i5,' lrec =
                  ',i5)

10      return
      end
```

C-----

```
15      subroutine winsiz(ir,iw,ne,nl,ixl,ixh,iyl,iyh)

10      write(iw,12)
12      format(' window size: ixl,ixh,iyl,iyh ?')
      read(ir,*) ixl,ixh,iyl,iyh
20
      if(ixl.eq.0.and.ixh.eq.0) then
      ixl=0
      ixh=ne-1
      endif
25  c      !ixl,ixh

      if(iyl.eq.0.and.iyh.eq.0) then
      iyl=0
      iyh=nl-1
30      endif
      c      !iyl,iyh

      write(iw,20) ixl,ixh,iyl,iyh
20      format(' window: ixl,ixh,iyl,iyh = ',4i5)
35
```

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return

end

C-----

5 subroutine boxesiz(ir,iw,ix0,iy0,nx,ny)

write(iw,10)

10 format(' ix0,iy0,nx,ny ?')

read(ir,\*) ix0,iy0,nx,ny

10

write(iw,20) ix0,iy0,nx,ny

20 format(' boxesiz: ix0,iy0,nx,ny = ',4i5)

return

15 end

C-----

20 subroutine xyorig(ir,iw,ix0,iy0)

write(iw,10)

10 format(' ix0,iy0 ?')

read(ir,\*) ix0,iy0

25 write(iw,20) ix0,iy0

20 format(' xyorig: ix0,iy0 = ',2i5)

return

end

30

C-----

subroutine blksiz(ir,iw,nbe,nbl)

write(iw,10)

35 10 format(' block size nbe,nbl ?')

-77-

```
      read(ir,*) nbe,nbl  
  
      write(iw,20) nbe,nbl  
20       format(' blksiz: nbe,nbl = ',2i5)  
5  
      return  
      end  
  
C-----  
10  
      subroutine smplxy(ir,iw,ixsmpl,iysmpl)  
  
      write(iw,10)  
10       format(' sampling ixsmpl,iysmpl ?')  
15       read(ir,*) ixsmpl,iysmpl  
  
      write(iw,20) ixsmpl,iysmpl  
20       format(' smplxy: ixsmpl,iysmpl = ',2i5)  
  
20       return  
      end  
  
C-----  
25  
      subroutine picnam(ir,iw,nfiles,mode,fname)  
  
      character*1 mode  
      character*32 fname(0:nfiles-1)  
  
30  
      do 1 ifile=0,nfiles-1  
  
      if(mode.eq.'i'.or.mode.eq.'I') then  
      write(iw,22) ifile  
22       format(1x,i3,'th input picture file  
35           (a32) ?')
```

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```
    else if (mode.eq.'o'.or.mode.eq.'O') then
      write(iw,24) ifile
      24      format(lx,i3,'th output picture file
                           (a32) ?')
      5       endif
      C       !mode?

      read(ir,25) fname(ifile)
      25      format(a32)
      10   I     continue

      return
      end

      15   C-----
```

---

```
subroutine picopn(iu,fname,lrec,status,com)

      character*1 com
      20      character*3 status
      character*32 fname
      data iw/6/

      if(com.eq.'s'.or.com.eq.'S') then
      25      open(unit=iu,file=fname,access='sequential',
                           recl=lrec)
      else
      open(unit=iu,file=fname,access='direct',
                           recl=lrec)
      30      endif

      write(iw,30) fname
      30      format(' picopn: file = ',a32)

      35      return
```

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end

C-----

```
5      subroutine ascopn(iu, fname, status, com)
       character*1 com
       character*3 status
       character*32 fname
10     data iw/6/
       open(unit=iu, file=fname)
       write(iw,30) fname
15   30      format(' ascopn: file = ',a32)
       return
       end

20   C-----
```

subroutine ascnam(ir,iw, text, fname)

character\*32 text, fname

25

write(iw,10) text

10 format(1x,a32, ' name (a32) ?')

read(ir,12) fname

12 format(a32)

30

return

end

C-----

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```
subroutine clrasc(n,text)

character*1 text(0:n-1)

5      do 1 i=0,n-1
         text(i)=' '
1      continue

       return
10     end

c-----  
c      read and write routines
c-----  
15

subroutine rdlin(iu,n,buf,com,irec)

character*1 com
dimension buf(0:0)
20

if(com.eq.'s'.or .com.eq.'S') then
read(iu) (buf(i),i=0,n-1)
else
read(iu),rec=irec) (buf(i),i=0,n-1)
endif

       return
end

30 c-----  
subroutine wrlin(iu,n,buf,com,irec)

character*1 com
35 dimension buf(0:0)
```

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```
      if(com.eq.'s'.or .com.eq.'S') then
        write(iu) (buf(i),i=0,n-1)
      else
 5       write(iu,rec=irec) (buf(i),i=0,n-1)
      endif

      return
    end
```

10

c-----

```
      subroutine ptr0(n,lp)

 15     dimension lp(0:0)

      do 1 i=0,n-1
        lp(i)=i
      1     continue
 20 c      !loop i
```

```
      return
    end
```

25 c-----

```
      subroutine ptr(n,lp)
```

```
      c      rotate the pointer by one
 30 c      lp(0) will have the oldest data
      c      lp(n-1) will have the newest data
      c      first  lp(0)=0, lp(1)=1,lp(2)=2,lp(3)=3,....
      c      then   lp(0)=1,lp(1)=2,lp(2)=3,lp(3)=4,....
```

35 dimension lp(0:0)

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```
    ll=lp(0)
c      !save

5      do l i=0,n-2
        lp(i)=lp(i+1)
1      continue
c      !enddo      !loop i

10     lp(n-1)=ll

      return
      end

15   c-----  
c      arithmetic operation
c-----  
  
      subroutine addc(n,c,z)
20
      dimension z(0:n-1)

      do l i=0,n-1
        z(i)=z(i)+c
25   l      continue
c      !enddo

      return
      end

30
c-----  
  
      subroutine clr(n,z)
35
      dimension z(0:0)
```

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```
      do 1 i=0,n-1
      z(i)=0.
      continue
5
      return
end

C-----
```

10 subroutine movxs(n,ixs,buf,pic)

dimension buf(0:0),pic(0:0)

if(ixs.eq.1) then
15 do 1 i=0,n-1
 pic(i)=buf(i)
1 continue
else
C !sample buf and put into pic
20 do 2 i=0,n-1
 pic(i)=buf(i\*ixs)
2 continue
endif

25 return
end

```
C-----
```

30 subroutine movxsi(n,ixs,pic,buf)

dimension pic(0:0),buf(0:0)

if(ixs.eq.1) then
35 do 1 i=0,n-1

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```
buf(i)=pic(i)
1    continue
else
5     c          !put pic into sampled buf
      do 2 i=0,n-1
      buf(i*ixs)=pic(i)
2     continue
      endif

10   return
end
```

c-----

```
15   subroutine mulcy(n,c,y,z)

dimension y(0:0),z(0:0)

do 1 i=0,n-1
20   z(i)=z(i)+c*y(i)
1     continue
c     !loop z

return
25   end
```

c-----

```
30   subroutine clrx(n,data)

dimension data(0:0)

do 1 i=0,n-1
      data(i)=0.
35   1     continue
```

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```
c      loop i

      return
      end

5
C-----
```

subroutine dskdiv(iul,iu2,lrec,buf,ne,nl,  
 fdiv)

10 c read a direct access file,  
 c divide each pixel by fdiv and  
 c write back

15 dimension buf(0:0)

do 1 irec=1,nl
read(iul,rec=irec) (buf(i),i=0,ne-1)
 do 2 i=0,ne-1
20 buf(i)=buf(i)/fdiv
 continue
c loop i
 write(iu2,rec=irec)
(buf(i),i=0,ne-1)231 continue
25 c loop irec

 return
 end

30

35

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APPENDIX G  
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5 C SHARPENING AND NOISE SUPPRESSION BY SINGULAR  
VALUE DECOMPOSITION

C SVD\_MOVE.FOR -- SVD WITH MOVING AVERAGE

10 C link with svd\_util.f

C DEC-20-88

C maximum svd block size: 40x40

15

dimension bufi(0:1999,0:39)  
dimension bufo(0:1999,0:39)  
dimension a(0:39,0:39),u(0:39,0:39),  
v(0:39,0:39)

20 dimension wt(0:39)

dimension fc(0:39,dfc(0:39),ratio(0:39))

data ir,iw/5,6/

25

data iui,iuo,iun/51,52,53/  
data iuw/61/  
data a,u,v/1600\*0.,1600\*0.,1600\*0./  
data wt/40\*0./

30 data fc,dfc,ratio/40\*0.,40\*0.,40\*0./

C NBE: # of elements per block (BLOCK SIZE)  
C NE: number of pixels per line (e.g. 500  
pixels)

35 C NL: number of lines of the image

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```
c      ixsmpl,iysmpl : sampling in x and y directions
c      INPUT
5   c      define image size : nc,ne,nl
      call picsiz (ir,iw,'I',nc,ne,nl)
c      define image record size
      call recsiz (ir,iw,ne,lform,lrec)
10  c      open input image file
      call ifile (ir,iw,iui,lform,lrec)
c      read noise data file
15   c      call nfile (ir,iw,iun,nbe,ixsmpl,iysmpl,fc,
      dfc,ratio)
c      open output image file
      call ofile (ir,iw,iuo,lform,lrec)
20   c      get pre/post processing weights
      call wfile (ir,iw,iuw,modew,nbe,wt,sum)
      write (iw,122)
25   122  format (' Starting IX0,IY0 ?')
      read (ir,*) ix0,iy0
c      block orientation mode = 0 (0 or 90 degree)
      modeb=0
30   *
      write (iw,140)
140  format(' idx,idy: No. of pixels to be moved '
      1,'in X and Y directions')
      read (ir,*)idx,idy
35
```

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```
      write (iw,151)
151  format (' Boost formula'
3,' 6: THRESHOLD1 ,EXP(-A*X**4) AND FMIN,
      FMAX')
5
      write (iw,152)
152  format (' Boost FORMULA(I) ?')
      read (ir,*) iform

10   write (iw,162)
162  format (" THRSH1(R),POWER(R),FMIN,FMAX,
      COEFF(FOR 6:) ?")
      read (ir,*) thrsh1,power,fmin,fmax,coeff

15   msize = ixsmpl*(nbe-1)+1
      nbsize = ixsmpl*nbe
      nbsiz2 = ixsmpl*nbe/2
      nxmove = nbsize/idx
     nymove = nbsize/idy
20
      write (iw,202)nbe,ix0,iy0,ixsmpl,iysmpl
1           ,msize,nbsize,idx,idy,nxmove,nymove

      if (mode.ne.0) then
25   write (iw,204) modew,sum
      endif

202  format (' MAIN: NBE,IXO,IYO = ',T30,3I8
1,' MAIN: IXSMPL,IYSMPL = ',T30,2I8
30   2,' MAIN: SUPPORT SIZE = 'T30,I8
3,' MAIN: NBE*IXSMPL = ',T30,I8
4,' MAIN: IDX,IDX = ',T30,2I8
5,' MAIN: NX ,NY = ',T30,2I8)
204  format (' MODEW, SUM OF WEIGHTS = ',I5,E15.5)
35
```

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```
do 305, mj = 0,nymove-1
      jy0 = iy0+mj*idy
      do 305, mi = 0,nxmove-1
          jx0 = ix0+mi*idx
5       mseq = mj*nxmove+mi
      call hui (nsvd,ir,iw,iui,iuo,nc,ne,nl,nbe,
                 ixsmpl,iysmpl
1       ,bufi,bufo,a,u,v,fc,dfc,ratio
2       ,iform,thrshl,coeff,power,fmin,
10      fmax
3       ,jx0,jy0,idx,idy,mseq,modew,wt,
                 lrec)

      if (mseq.eq.mseq/10*10) then
15     write (iw,304) mi,mj
304     format (1X,' MAIN: BLOCK X,Y = ',2I5,'
                 DONE')
      endif
305     continue
20     write(iw,333)nsvd
333     format(lx,' *** total number of svd called :
                 ',i10)
      C     ALL THE SUM IS ACCUMULATED IN OUTPUT FILE
      READ IT AND DIVIDE BY NXMOVE*NMOVE
25
      denom = float(nxmove*nymove)
      if (modew.eq.1.or.modew.eq.2) then
          denom = (sum*sum*denom)/(nbe*nbe),
      endif
30
      call dskdiv (iuo,iuo,lrec,bufo,ne,nl,denom)

      close (iui)
      close (iuo)
35
```

-90-

end

C-----

5 subroutine hui(nsvd,ir,iw,iui,iuo,nc,ne,nl,  
nbe,ixsmpl,iysmpl

1 ,bufi,buf0,a,u,v,fc,dfc,ratio  
2 ,iform,thrshl,coeff,power,fmin,fmax  
10 3 ,jx0,jy0,idx,idy,mseq,modew,wt,lrec)

C GIVEN JXO,JYO(STARTING POINT), IT WILL MAKE  
IXSMPL\*IYSMPL

C MOVES OF BLOCK TRANSFORM

15

C THIS SUBROUTINE DOES ALL THE ACTUAL  
PROCESSING

C MAIN PROGRAM JUST SETS UP ARRAY SIZES FOR A  
GIVEN PICTURE.

20

dimension bufi(0:ne-1,0:nbe-1)  
dimension buf0(0:ne-1,0:nbe-1)  
dimension a(0:nbe-1,0:nbe-1)  
dimension u(0:nbe-1,0:nbe-1),  
25 v(0:nbe-1,0:nbe-1)  
dimension work(100)  
dimension fc(0:39),dfc(0:39),ratio(0:39)  
dimension id(0:39),sigma(0:39)  
dimension wt(0:nbe-1)

30

n = nbe  
m = nbe  
nm = nbe  
nbrxs = nbe\*ixsmpl

35

```
      -91-
nxtry    = (ne-jx0-nbe)/nbrxs-1
nytry    = (nl-jy0-nbe)/nbrxs
if  (((nytry-1)*nbrxs+nbe).gt.nl) then
    nytry = nytry-1
5
endif
lextre = nl-nytry*nbrxs-jy0

if (mseq.eq.0) then
    write (iw,802) nbe,ixsmpl,iysmpl,
10   1      iform,thrshl,power,fmin,fmax,coeff
802   format (' HUI:nbe,ixsmpl,iysmpl=',3i5,/
1      , ' boost formula, thrshl,power,fmin,fmax,
           coeff = '
2      //,1x,I5,5E15.5)
15
endif

c      skip jy0 lines
if (jy).ge.1)then
20   do 840, iy = 0,jy0-1
    irec = iy+1
    read (iui,rec=irec) (bufi(i,0),i=0,ne-1)
    write (iuo,rec=irec) (bufi(i,0),i=0,ne-1)
840   continue
25
endif

c      processing the input image block by block

do 910, iy = 0,nytry-1
30   linel = jy0+1+iy*nbrxs

do 910, iys = 0,iysmpl-1
     line2 = linel+iys

35 c      read in nbe lines from the input image into
```

-92-

```
bufi

      do 850, j = 0,nbe-1
      linei = line2+j*iysmpl
5       read (iui,rec=linei) (bufi(i,j),i=0,ne-1)

      c   if it is a first path :
      c       initialize the output buffer -- bufo
      c   otherwise : read in output buffer -- bufo
10

      if (mseq.eq.0) then
          do 845, jj = 0,nbe-1
          do 845,ii = 0,ne-1
          bufo(ii,jj) = 0.
15  845      continue
      else if (mseq.ne.0) then
          read (iuo,rec=linei) (bufo(i,j),i=0,ne-1)
          endif
850      continue
20

      c   set up array a(i,j)

      do 900, ix = 0,nxtry-1
      ixoff1 = jx0+nbrxs*ix
25

      do 900, ixs = 0,ixsmpl-1
      ixoff2 = ixoff1+ixs+(nbe/2)*ixsmpl
      do 860, j = 0,nbe-1
      do 860, i = 0,nbe-1
30      ii = ixoff2+i*ixsmpl
      a(i,j) = bufi(ii,j)
      860      continue

      call svd (nm,m,n,a,sigma,.true.,u,.true.,v,
35      ierr,work)
```

-93-

```

nsvd=nsvd+1

      if (ierr.ne.0) then
          write (iw,20) ix,iy,ierr
5   20      format (' TROUBLE. IX,IY,IERR= ',3I6)
          do 865, l = 0,nbe-1
              write (iw,22) l,sigma(l)
22      format (1x,i3,'th singular value =
                  ',E15.5)
10   865      continue
          do 866 i=0,ierr-1
              sigma(i)=0.
866      continue
          endif
15

c      sort sigma(==singular values) in descending
      order

      call sort (nbe,sigma,id)
20  c
      c      SIGMA(I,L(ID)): Ith SINGULAR VALUE

      c      COMPUTE NEW A(I,J) ACCORDING TO CORING FORMULA
      c      (IFORM) FROM
25  c      SIGMA, U, AND V.

      call newaij (ir,iw,nbe,id,a,sigma,u,v,
                  fc,dfc,ratio
1      ,iform,thrshl,coeff,power,fmin,fmax)
30

      if (modew.eq.-1) then
          do 885, j = 0,nbe-1
              do 885, i = 0,nbe-1
                  a(i,j) = a(i,j)/wt(i)/wt(j)
35   885      continue

```

-94-

```
      else if (modew.eq.1) then
        do 890, j = 0,nbe-1
          do 890, i = 0,nbe-1
            a(i,j) = a(i,j)*wt(i)*wt(j)
5   890      continue
      endif
```

C UPDATE OUTPUT BUFFER : BUFO

```
10      do 895, j = 0,nbe-1
        jj = j
        do 895, i = 0,nbe-1
          ii = ixoff2+l*ixsmpl
          bufo(ii,jj) = bufo(ii,jj)+a(i,j)
15   895      continue
```

900 continue

C WRITE LINES OUT TO DISK (AFTER NN LINES, MM
20 BLOCKS ARE PROCESSED)

```
do 905, j = 0,nbe-1
  lineo = line2+j*iysmpl
  write (iuo,rec+lineo) (bufo(i,j),i=0,ne-1)
25   905      continue
```

910 continue

C WRITE OUT REMAINING LINES

```
30      if (lextra.gt.0) then
        line3 = nl-lextra+1
        do 915, iy = 0,lextr-1
          irec = line3+iy
          read (uii,rec=irec) (bufi(i,0),i=0,ne-1)
35
```

-95-

```
915      write (iuo,rec=irec) (bufi(i,0),i=0,ne-1)
         continue
         endif

5       return
end
```

C-----

```
10      subroutine newaij (ir,iw,nbe,id,a,sigma,u,v,
           fc,dfc,ratio
           l,iform,thrshl,coeff,power,fmin,fmax)

           logical first
15      dimension a(0:nbe-1,0:nbe-1)
           dimension sigma(0:nbe-1,id(0:nbe-1))
           dimension u(0:nbe-1,0:nbe-1),v(0:nbe-1,
           0:nbe-1)
           dimension fc(0:39),dfc(0:39),ratio(0:39)
20      data first/.true./

           if(first) then
               write (iw,8888) iform,thrshl,power,fmin,
25             fmax,coeff
               8888     format (' newaij: iform,t1,p,t2,c =
                   ',i5,4f6.2)
               first=.false.
               endif
30
           do 100, j = 0,nbe-1
               do 100, i = 0,nbe-1
                   a(i,j) = 0.
100      continue
35
```

-96-

```
c      determine threshold formula

      if(iform.eq.6) then
      call iform6(ir,iw,nbe,id,a,sigma,u,v,fc,
5          dfc,ratio
      l,iform,thrshl,coeff,power,fmin,fmax)
      endif

      return
10     end

c-----
c      Boost formula 6

15     subroutine iform6 (ir,iw,nbe,id,a,sigma,u,v,
      fc,dfc,ratio
      l,iform,thrshl,coeff,power,fmin,fmax)

      dimension a(0:nbe-1,0:nbe-1)
20     dimension sigma(0:nbe-1),id(0:nbe-1)
      dimension u(0:nbe-1,0:nbe-1),v(0:nbe-1,
          0:nbe-1)
      dimension fc(0:39),dfc(0:39),ratio(0:39)

25     do 120, l = 0,nbe-1

c      depending on IFORM choose threshold level

      ff = l.

30     if (sigma(l).ge.0.) then
      zz = (sigma(l)-fc(l))/dfc(l)

      if (zz.le.thrshl) then
35     ff = fmin
```

-97-

```
else if (zz.gt.thrshl) then
    arg = coeff*((zz-thrshl)**power)
    if (arg.le.0.000000001) then
        delf = delf*(1.+arg)
5      else if (arg.gt.0.000000001.and.arg.
           le.10.) then
        delf = delf*(1.-exp(-arg))
    else if (arg.gt.10.) then
        delf = delf
10     endif
c         end of arg ?

ff = fmin + delf
endif
15 c         end of (zz...

else if(sigma(1)eq.0.) then
ff=1.

20     else if (sigma(1).lt.0.) then
      write (iw,505) ix,iy,l,sigma(1)
505     format (' ix,iy,l,sigma(1)',3i5,e15.5)
      ff = 1.
      endif
25 c         end of (sigma(1)...

do 110, j = 0,nbe-1
  do 110, i = 0,nbe-1
    a(i,j) = a(i,j)+ff*sigma(l)*u(i,id(l))*v(j,id(l))
30
110     continue

120     continue
      return
35     end
```

-98-

C-----

```
      subroutine nfile(ir,iw,iun,nbe,ixsmpl,
5          iysmpl,fc,dfc,ratio)

10         character*32          text, fname

           dimension fc(0:nbe-1),dfc(0:nbe-1),
           ratio(0:nbe-1)

15         text='svd noise file for      0 degree'

           call ascnam(ir,iw,text,fname)
           call ascopn(iun,fname,'old',' ')
           read(iun,*) nbe,ixsmpl,iysmpl

20   115         write(iw,115) fname
           format(' noise file:',a32,/
1 5x,'order',5x,' mean',5x,'sigma',5x,'ratio')

           do 802 l=0,nbe-1
           read(iun,*) iorder,fc(l),dfc(l),ratio(l)
25           write(iw,116) iorder,fc(l),dfc(l),ratio(l)
           116         format(1x,i5,3e15.5)
           802         continue
           C           end of loop 1
           close(unit=iun)
30
           return
           end
```

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APPENDIX H  
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```
5   c      sml_filter.for
c      generate s,m and l low-pass filters
c      output filter file names: s.msk -- 3x3
c                                m.msk -- 5x5
c                                l.msk -- 7x7
10
c      OCT-26-87

15
character*32 fname(0:2)
dimension s(0:8),ixsmpl(0:2),iysmpl(0:2)

20
data ir,iw/5,6/
data iu,iu2/99,98/
data s/1.,2.,1.,2.,4.,2.,1.,2.,1./
data fname/'s.msk','m.msk','l.msk'/
data ixsmpl/1,2,4/
data iysmpl/1,2,4/

25
write(iw,10)
10  format(/, ' : generates s.msk, m.msk and
     l.msk '
     1 , 'low pass filter files',/)

30
c      input

30  sigmax=0.
      sigmay=0.
      nbe=3
      nbl=3

35  c      output
```

-100-

```
do 90 l=0,2

      open (unit=iu,file=fname(l))

5        write(iu,102) nbe,nbl,ixsmpl(l),iySmpl(l),
                     sigmax,sigmay
102      format(lx,4i5,2e15.5)
         do 50 i=0,nbe*nbl-1
10        write(iu,104) i,s(i)
104      format(lx,i5,e15.5)
50        continue
         close(iu)
90        continue
15
      end
```

20

25

30

35.

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APPENDIX I  
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5 C SHARPENING AND NOISE SUPPRESSION BY SINGULAR  
VALUE DECOMPOSITION

C SVD\_MOVE\_3ORI.F -- SVD WITH MOVING AVERAGE  
and 3 ORIENTATIONS

10 C link with svd\_util.f

C DEC-20-88

15 C maximum svd block size : 40x40

C WITH THREE MODES:0--STRAIGHT  
C 1-45 DEGREE SLANT  
C 2-135 DEGREE SLANT

20 C MOVING BLOCK AVERAGE  
C WITH SAMPLING IXSMPL,IYSMPL  
C IXO,IYO,AND SCALE FACTOR FOR NOISE  
C MAXIMUM BLOCK SIZE 40x40

25 dimension bufi(0:1999,0:39)  
dimension bufo(0:1999,0:39)  
dimension a(0:39,0:39),u(0:39,0:39),  
v(0:39,0:39)  
dimension wt(0:39)

30 dimension iun(0:2)  
dimension fc(0:39,0:2),dfc(0:39,0:2),  
ratio(0:39,0:2)

35 data ir,iw/5,6/

-102-

```
      data iui,iuo,iun/51,52,53,54,55/
      data iuw/61/
      data a,u,v/1600*0.,1600*0.,1600*0./
5       data wt/40*0./
      data fc,dfc,ratio/120*0.,120*0.,120*0./

      C   NBE: # of elements per block (BLOCK SIZE)
      C   NE: number of pixels per linbe (e.g. 400
10      pixels, or 1136 pixels)
      C   NL: number of linbes of the image

      C   INPUT

15  C   define image size : nc,ne,nl
      call picsiz (ir,iw,'I',nc,ne,nl)

      C   define image record size
      call recsiz (ir,iw,ne,lform,lrec)
20

      C   open input image file
      call ifile (ir,iw,iui,lform,lrec)

      C   read noise data files
25      call nfile (ir,iw,iun,nbe,ixsmpl,iysmpl,fc,
                  dfc,ratio)

      C   open output image file
      call ofile (ir,iw,iuo,lform,lrec)
30

      C   get pre/post processing weights
      call wfile (ir,iw,iuw,modew,nbe,wt,sum)

      write (iw,l22)
35  122  format (' Starting IX0,IY0 ?')
```

-103-

```
      read (ir,*) ix0, iy0

      *
      write (iw,140)
140    format ('NBR: No. of pixels to be replaced in
      5           the block'
      1/' IDX,IDX: No. of pixels to be moved in X
           and Y directions')

      write (iw,142)
10   142  format (' NBR,IDX,IDX ?')
      read (ir,*) nbr, idx, idy

      c     get block orientation mode
      write (iw,171)
15   171  format (' Block selection mode:'
      1,' 0:      0 degree'
      1,' 1:      45 degree'
      1,' 2:      135 degree'
      1,' 3:      best of the above three'
      20   171  1,' MODEB ?')
      read (ir,*) modeb

      write (iw,151)
151   format (' Boost formula'
25     1,' 6: THRESHOLD1 , EXP(-A*X**4) AND
           FMIN,FMAX')

      write (iw,152)
152   format (' Boost FORMULA(I) ?')
30     read (ir,*) iform

      *
      write (iw,162)
162   format ('THRSHL(R),POWER(R),FMIN,FMAX,
           COEFF(FOR 6:) ?')
35     read (ir,*) thrshl, power, fmin, fmax, coeff
```

-104-

```
      msize = ixsmpl*(nbe-1)+1
      nbsize = ixsmpl*nbe
      nbsiz2 = ixsmpl*nbe/2
5       nxmove = nbsize/idx
     nymove = nbsize/idy

      write (iw,202) nbr,ix0,iy0,ixsmpl,iysmpl
1           ,msize,nbsize, idx,idy,nxmove,
10          nymove

      if (modew.ne.0) then
         write (iw,204) modew,sum
      endif
15

204     format (' MAIN: NBR,IX0,IY0, = ',%30,3I8
1.,,' MAIN: IXSMPL,IYSMPL = ',T30,2I8
1.,,' MAIN: SUPPORT SIZE = ',T30,I8
1.,,' MAIN: NBE*IXSMPL = T30,I8
20      1.,,' MAIN: IDX,IDX = ',T30,2I8)
2.,,' MAIN: NX ,NY = 'T30,2I8)
204     format (' MODEW, SUM OF WEIGHTS = ',I5,E15.5)

      do 305, mj = 0,nymove-1
25      jy0 = iy0+mj*idy
      do 305, mi = 0,nxmove-1
         jx0 = ix0+mi*idx
         mseq = mj*nxmove+mi
         call hui (nsvd,ir,iw,iui,iuo,nc,ne,nl,
30             nbe,ixsmpl,iysmpl
1             ,bufi,bufo,lp,a,u,v,fc,dfc,
             ratio
2             ,iform,thrshl,coeff,power,fmin,
             fmax
35            ,jx0,jy0, idx,idy,mseq,nbr,modew,
```

-105-

```
        wt,lrec,modeb)

*
      if (mseq.eq.mseq/10*10) then
        write (iw,304) mi,mj
5   304      format (1X' MAIN: BLOCK X,Y = '2I5,
                           'DONE')
        endif
305      continue

10      write(iw,333)nsvd
333      format(lx," *** total number of svd called :
                           ',i10)

C      ALL THE SUM IS ACCUMULATED IN OUTPUT FILE
15 C      READ IT AND DIVIDE BY NXMOVE*NYMOVE

denom = float(nxmove*nymove)
if (modew.eq.1.or.modew.eq.2) then
  denom = (sum*sum*denom)/(nbe*nbe)
20      endif

call dskdiv (iuo,iuo,lrec,buf0,ne,nl,denom)

close (iui)
25      close (iuo)
end

C-----
```

30 subroutine hui(nsvd,ir,iw,iui,iuo,nc,ne,nl,
 nbe,ixsmpl,iysmpl
1 ,bufi,buf0,lp,a,u,v,fc,dfc,
 ratio
2 ,iform,thrshl,coeff,power,
35 fmin,fmax

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```
3           ,jx0,jy0,idx,idy,mseq,nbr,
               modew,wt,lrec,modeb)

C   GIVEN JX0,JY0(STARTING POINT), IT WILL MAKE
5     IXSMPL*IYSMPL
C   MOVES OF BLOCK TRANSFORM

C   THIS SUBROUTINE DOES ALL THE ACTUAL
      PROCESSING.

10  C   MAIN PROGRAM JUST SETS UP ARRAY SIZES FOR A
      GIVEN PICTURE.

dimension bufi(0:ne-1,0:nbe-1)
dimension bufo(0:ne-1,0:nbe-1)
15 dimension a(0:nbe-1,0:nbe-1)
dimension u(0:nbe-1,0:nbe-1),v(0:nbe-1,
      0:nbe-1)
dimension temps(0:39,0:2),tempu(0:39,0:39,
      0:2)
20 dimension tempv(0:39,0:39,0:2),idtemp(0:39,
      0:2)
dimension work(100)
dimension fc(0:39,0:2),dfc(0:39,0:2),
      ratio(0:39,0:2)
25 dimension id(0:39,sigma(0:39)
dimension wt(0:nbe-1)

n      = nbe
m      = nbe
30 nm     = nbe
nbr2   = (nbe-nbr)/2
nbr3   = nbr2+nbr
nbrxs  = nbr*ixsmpl

35 nxtry = (ne-jx0-nbe)/nbrxs-1
```

```
      -107-
      nytry = (nl-jy0-nbe)/nbrxs
      if (((nytry-1)*nbrxs+nbe).gt.nl) then
          nytry = nytry-1
      endif
      5      lextra = nl-nytry*nbrxs-jy0+nbr2

      if (mseq.eq.0) then
          write (iw,802) modeb,nbe,nbr,ixsmpl,iysmpl,
1           iform,thrshl,power,fmin,fmax,coeff
10     802      format ('HUI: modeb,nbe,nbr,ixsmpl,iysmpl=
           ',5i5,/
1           , 'boost formula,thrshl,power,fmin,
           fmax,coeff = '
2 ,/,lx,I5,5E15.5)
15      write (iw,804) lrec,ir,iw,iui,iuo
804      format (' hui: lrec,ir,iw,iui,iuo = ',5i5)

      endif

20  c      skip jy0 lines

      if ((jy0+nbr2).ge.1)then
          do 840, iy = 0,jy0+nbr2-1
          irec = iy+1
25      read (iui,rec=irec) (bufi(i,0),i=0,ne-1)
          write (iuo,rec=irec) (bufi(i,0),i=0,ne-1)
840      continue
      endif

30  c      processing the input image block by block

      do 910 iy = 0,nytry-1
          linel = jy0+l+iy*nbrxs

35      do 910, iys = 0,iysmpl-1
```

-108-

```
line2 = linel+iyS  
c      read in nbe lines from the input image into  
bufi  
5  
do 850, j = 0,nbe-1  
linei = line2+j*iySmpl  
read (ui,rec=linei) (bufi(i,j),i=0,ne-1)  
10 c      if it is a first path :  
c          initialize the output buffer -- bufo  
c      otherwise: read in output buffer -- bufo  
  
if (mseq.eq.0) then  
15    do 845, jj = 0,nbe-1  
      do 845, ii = 0,ne-1  
        bufo(ii,jj) = 0.  
845     continue  
else if (mseq.ne.0) then  
20     read (uo,rec=linei) (bufo(i,j),i=0,  
      ne-1)  
      endif  
850     continue  
  
25 c      set up array a(i,j)  
  
do 900, ix = 0,nxtry-1  
ixoff1 = jx0+nbrxs*ix  
  
30     do 900, ixs = 0,ixsmpl-1  
ixoff2 = ixoff1+ixs  
  
if (modeb.eq.3) then  
35     modell = 0  
model2 = 2
```

-109-

```
else
    modell = modeb
    model2 = modeb
endif
5
do 875, mode = modell, model2

C      COMPUTE SVD FOR 3 MODES:
C      0 : STRAIGHT BLOCK
10 C      1 : 45 DEG SLANT
C      2 : 135 DEG SLANT

if (mode.eq.0) ixoff3 = ixoff2+
    (nbe/2)*ixsmpl
15 if (mode.eq.1) ixoff3 = ixoff2+
    nbe*ixsmpl
if (mode.eq.2) ixoff3 = ixoff2
C
if (mode.eq.0) then
20
    do 860, j = 0,nbe-1
    do 860, i = 0,nbe-1
    ii = ixoff3+i*ixsmpl
    a(i,j) = bufi(ii,j)
25 860    continue

    else if (mode.eq.1) then
    do 861, j = 0,nbe-1
    do 861, i = 0,nbe-1
    ii = ixoff3+i*ixsmpl
    a(i,j) = bufi(ii-j,j)
30 861    continue

    else if (mode.eq.2) then
    do 862, j = 0,nbe-1
    do 862, i = 0,nbe-1
    ii = ixoff3+i*ixsmpl
35
```

```
          -110-
862      a(i,j) = bufi(ii+j,j)
          continue
          endif

5         call svd (nm,m,n,a,sigma,.true.,u,
           .true.,v,ierr,work)
nsvd=nsvd+1

10        if (ierr.ne.0) then
20          write (iw,20) ix,iy,ierr
           format (' TROUBLE. IX,IY,IERR=
           ',3I6)
           do 865, l = 0,nbe-1
             write (iw,22) l,sigma(l)
             format (1x,i3,'th singular value =
           ',E15.5)
15 22       sigma(i)=0.
           continue
           do 866 i=0,ierr-1
20 866       continue
           endif

C     sort sigma(==singular values) in descending
25       order
           call sort (nbe,sigma,id)

           do 870, i = 0,nbe-1
30           temps(i,mode) = sigma(i)
           idtemp(i,mode) = id(i)
870         continue
           do 871, i = 0,nbe-1
             do 871, J = 0,NBE-1
               tempv(i,j,mode) = v(i,j)
               tempu(i,j,mode) = u(i,j)
35
```

-111-

871        continue

C

C        SIGMA(I,L(ID)): Ith SINGULAR VALUE

5

875        continue

if (modeb.eq.0.or.modeb.eq.1.or.modeb.  
eq.2) then

10           kmode = modeb

else if (modeb.eq.3) then

call bmode(iw,nbe,tempo,fc,dfc,kmode)  
else

write (iw,\*) ' HUI;MODEB IS NOT RIGHT'

15           stop

endif

do 880, i = 0,nbe-1

sigma(i) = tempo(i,kmode)

20           id(i) = idtemp(i,kmode)

do 880, j = 0,nbe-1

u(i,j) = tempu(i,j,kmode)

v(i,j) = tempv(i,j,kmode)

25    880        continue

C        COMPUTE NEW A(I,J) ACCORDING TO CORING  
FORMULAR(IFORM) FROM

C        SIGMA, U, AND V.

30

call newaij (ir,iw,nbe,id,a,sigma,u,v,  
fc,dfc,ratio

1        ,iform,thrshl,coeff,power,fmin,  
fmax,kmode)

35

```

      -112-
      if (modew.eq.-1) then
        do 885, j = 0,nbe-1
        do 885, i = 0,nbe-1
          a(i,j) = a(i,j)/wt(i)/wt(j)
5   885    continue

      else if (modew.eq.1) then
        do 890, j = 0,nbe-1
        do 890, i = 0,nbe-1
          a(i,j) = a(i,j)*wt(i)*wt(j)
10  890    continue
      endif

C     UPDATE OUTPUT BUFFER : BUFO
C     REPLACE NBR LINES AND ELEMENTS.
15

C     NBR2 = (NBE-NBR)/2, NBR3=NBR2+NBR

      if(nbr.le.nbe/2) then
        ixoff4 = ixoff2+(nbe/2)*ixsmpl+nbr2*
20           ixsmpl
        if (kmode.eq.0) then
          do 895, j = 0,nbr-1
            jj = nbr2+j
            do 895, i = 0,nbr-1
25           ii = ixoff4+i*ixsmpl
              bufo(ii,jj) = bufo(ii,jj)+
                a(nbr2+i,jj)
            continue
895

      else if (kmode.eq.1) then
30       do 896, j = 0,nbr-1
         jj = nbr2+j
         do 896, i = 0, nbr-1
           ii = ixoff4+i*ixsmpl
             bufo(ii,jj) = bufo(ii,jj)+
               a(nbe/2-nbr+i+j,jj)
35

```

-113-

```
896      continue
          else if (kmode.eq.2) then
do 897, j = 0,nbr-1
      jj = nbr2+j
      do 897, i = 0,nbr-1
          ii = ixoff4+i*ixsmpl
          bufo(ii,jj) = bufo(ii,jj)+a(nbe/2+i-j,jj)
897      continue
10       endif
c         end of kmode ?

else if(nbr.eq.nbe) then
    if (kmode.eq.0) then
15       ixoff4=ixoff2+(nbe/2)*ixsmpl
        do 995, j = 0,nbr-1
            jj = nbr2+j
            do 995, i = 0,nbr-1
                ii = ixoff4+i*ixsmpl
                bufo(ii,jj) = bufo(ii,jj)+a(i,j)
995      continue
20       else if (kmode.eq.1) then
            ixoff4=ixoff2+nbe*ixsmpl
            do 996, j = 0,nbr-1
                jj = nbr2+j
                do 996, i = 0,nbr-1
                    ii = ixoff4+i*ixsmpl
                    bufo(ii-j,jj) = bufo(ii-j,jj)+a(i,j)
996      continue
25       else if (kmode.eq.2) then
            ixoff4=ixoff2
            do 997, j = 0,nbr-1
                jj = nbr2+j
                do 997, i = 0,nbr-1
                    ii = ixoff4+i*ixsmpl
30
35
```

-114-

```
997      bufo(ii+j,jj) = bufo(ii+j,jj)+a(i,j)
         continue
         endif
C       end of kmode ?
5        else
         write(iw,*) ' nbr should be .le.(nbe/2).
                      or .eq.nbe'
         stop
         endif
10       C      end of nbr ?

900      continue

C      WRITE LINES OUT TO DISK (AFTER NN LINES, MM
15       BLOCKS ARE PROCESSED)

do 905, j = nbr2,nbr3-1
lineo = line2+j*iysmpl
write (iuo,rec=lineo) (bufo(i,j),
20           i=0,ne-1)
905      continue

910      continue

25       C      WRITE OUT REMAINING LINES

if (lextra.gt.0) then
line3 = nl-lextra+1
do 915, iy = 0,lextra-1
30       irec = line3+iy
read (uii,rec=irec) (bufi(i,0),i=0,ne-1)
write (iuo,rec=irec) (bufi(i,0),i=0,ne-1)
915      continue
endif
```

-115-

return

end

C-----

5

```
subroutine newaij (ir,iw,nbe,id,a,sigma,u,v,
                   fc,dfc,ratio
                   l,iform,thrshl,coeff,power,fmin,fmax,kmode)
```

10 logical first

dimension a(0:nbe-1,0:nbe-1)

dimension sigma(0:nbe-1),id(0:nbe-1)

dimension u(0:nbe-1,0:nbe-1),

v(0:nbe-1,0:nbe-1)

15 dimension fc(0:39,0:2),dfc(0:39,0:2),
 ratio(0:39,0:2)

data first/.true./

20 if(first) then

```
write (iw,8888) iform,thrshl,power,fmin,
                  fmax,coeff,kmode
```

8888 format (' newaij: iform,t1,p,t2,c,
 kmode = ',i5,4f6.2,i5)

25 first=.false.

endif

do 100, j = 0,nbe-1

do 100, i = 0,nbe-1

30 a(i,j) = 0.

100 continue

\* if(iform.eq.6) then

```
call iform6(ir,iw,nbe,id,a,sigma,u,v,
            fc,dfc,ratio
```

35

```
-116-
```

```
    l,iform,thrshl,coeff,power,fmin,fmax,kmode)
      endif

      return
5
    end

C-----
```

```
10   subroutine iform6 (ir,iw,nbe,id,a,sigma,u,v,
      fc,dfc,ratio
    l,iform,thrshl,coeff,power,fmin,fmax,kmode)

      dimension a(0:nbe-1,0:nbe-1)
      dimension sigma(0:nbe-1),id(0:nbe-1)
      dimension u(0:nbe-1,0:nbe-1),v(0:nbe-1,
15      0:nbe-1)
      dimension fc(0:39,0:2),dfc(0:39,0:2),
      ratio(0:39,0:2)

      delf = fmax - fmin
20
      do 120, l = 0,nbe-1

C      depending on IFORM choose boost level

25      ff = 1.

      if (sigma(l).gt.0.) then
        zz = (sigma(l)-fc(l,kmode))/dfc(l,kmode)

30      if (zz.le.thrshl) then
        ff = fmin
      else if (zz.gt.thrshl) then
        arg = coeff*((zz-thrshl)**power)
        if (arg.le.0.00000001) then
          delf = delf*(1.-arg)
35
```

```
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```

```
    else if (arg.gt.0.00000001.and.arg.
              le.10.) then
        delf = delf*exp(-arg)
    else if (arg.gt.10.) then
      5      delf = delf
    endif
    c      end of arg ?

          ff = fmin + delf
 10      endif
    c      end of (zz...

    else if(sigma(1).eq.0.) then
ff=1.
 15

    else if(sigma(1).lt.0.) then
        write (iw,505) ix,iy,l,sigma(1)
 505      format (' ix,iy,l,sigma(1)',3i5,e15.5)
        f = 1.
 20      endif
    c      end of (sigma(1)...


    do l10, j = 0,nbe-1
        do l10, i = 0,nbe-1
 25      a(i,j) = a(i,j)+ff*sigma(1)*u(i,id(1))*v(j,id(1))
        l10      continue
        l20      continue
        return
 30      end
 40      c-----
```

---

```
    subroutine bmode (iw,nbe,temp,fc,dfc,kmode)

 35  C      SELECT THE MODE WHICH IS THE BEST
```

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```
dimension temps(0:39,0:2)
dimension fc(0:39,0:2),dfc(0:39,0:2)
dimension lzero(0:2),modeid(0:2)
5      dimension zval(0:2)

C      GET THE ORDER WHICH IS CLOSE TO NOISE VALUE

do 110, mode = 0,2
10     lzero(mode) = 0
      do 100, l = 0,nbe-1
            zz = (temps(l,mode)-fc(l,mode))/dfc(l,mode)
            if (abs(zz).lt.3.5) then
15           lzero(mode) = l
            go to 110
            endif
110     continue
110     continue
20

C      DETERMINE THE MODE WHICH HAS THE LOWEST ORDER
C      SEE IF ANY OF THE TWO ARE THE SAME

lmin = nbe-1
25     do 120, mode = 0,2
            if (lzero(mode).le.lmin) then
                lmin = lzero(mode)
            endif
120     continue
30

lflag = 0
      do 130, mode = 0,2
            if (lzero(mode).eq.lmin) then
                modeid(lflag) = mode
            lflag = lflag+1
35
```

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```
        endif
130    continue

        if (lflag.eq.1) then
5         kmode = modeid(0)

        else if (lflag.eq.2) then
            call clrx(2,zval)
            do 140, k = 0,1
10           kk = modeid(k)
            do 140, i = 0,1
                zval(k) = zval(k)+temps(i,kk)-
                           fc(i,kk))/dfc(i,kk)
140       continue
15
        kmode = modeid(0)
        if (zval(1).gt.zval(0)) kmode = modeid(1)

        else if (lflag.eq.3) then
20
        if (modeid(0).eq.0) then
            kmode = 0

        else if (modeid(0).eq.1) then
25         zmax = -999.
            kmode = -1
            do 150, k = 0,2
                zz = (temps(0,k)-fc(0,k))/dfc(0,k)
                if (zz.gt.zmax) then
30           kmode = k
                endif
            150   continue

        else
35         call clrx(3,zval)
```

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```
      do 160, k = 0,2
        do 160, l = 0,1
          zval(k) = zval(k)+(temps(l,k)-fc(l,k))/dfc(l,k)
5   160      continue

          zmax = -999.
          kmode = -1
          do 165, k = 0,2
            if (zval(k).gt.zmax) then
              kmode = k
            endif
10   165      continue

15      endif

          if (kmode.eq.-1) then
            write (iw,170) (zval(k),k = 0,2)
170      format (' WARNING !!! BMODE: LFLAG = 3,
20                  ZVAL =',3F10.2)
            kmode = 0
          endif

          endif
25      return
      end

C-----
30
      subroutine norm(ne,nl,buf,denom)

      dimension buf(0:ne-1,0:nl-1)

35      do 1 j=0,nl-1
```

```
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```

```
      do 1 i=0,ne-1
      buf(i,j)=buf(i,j)/denom
1      continue

5      return
end

C-----
```

```
subroutine nfile(ir,iw,iun,nbe,ixsmpl,iysmpl,
10          fc,dfc,ratio)

character*32      text, fname(0:2)

dimension fc(0:nbe-1,0:2), dfc(0:nbe-1,0:2),
15          ratio(0:nbe-1,0:2)
dimension iun(0:2)
C      dimension mode(0:2)

text='svd noise file for      0 degree'
20      call ascnam(ir,iw,text,fname(0))
call ascopn(iun(0),fname(0),'old',' ')
      text='svd noise file for      45 degree'
25      call ascnam(ir,iw,text,fname(1))
call ascopn(iun(1),fname(1),'old',' ')
      text='svd noise file for    135 degree'
30      call ascnam(ir,iw,text,fname(2))
call ascopn(iun(2),fname(2),'old',' ')
      do 801 ifile = 0,2
      read(iun(ifile),*) nbe,ixsmpl,iysmpl
C114      format(3i)
      write(iw,115) fname(ifile)
35  115      format(' noise file:',a32,/
```

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1 5x,'order',5x,' mean',10x,'sigma',5x,'ratio')

```
      do 802 l=0, nbe-l
      read(iun(ifile),*) iorder
5       l,fc(l,ifile),dfc(l,ifile),ratio(l,ifile)
      write(iw,116) iorder,fc(l,ifile),dfc(l,ifile),
                     ratio(l,ifile)
116      format(lx,i5,3e15.5)
802      continue
10      c           end of loop l
      close(unit=iun(ifile))

801      continue
c           end of loop ifile
15
      return
      end
```

20

25

30

35

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CLAIMS:

1. A method of processing an image in a digital computer for sharpening the image, comprising the steps of:
  - 5       a. generating a non-linear gain function based upon the measured statistics of the SVD singular values for image noise, said non-linear gain function being characterized by boosting factors applicable wherever there is a high signal-to-noise ratio;
  - 10      b. filtering the digital image to produce a detail image and a low pass filtered image;
  - c. dividing the detail image into blocks;
  - d. transforming the blocks employing an SVD transformation to produce singular vectors and arrays of singular values;
  - 15      e. applying the non-linear gain function to the arrays of singular values to produce arrays of modified singular values whereby to boost those singular values corresponding to a higher signal-to-noise ratio;
  - 20      f. performing an inverse SVD on the singular vectors with modified singular values to produce blocks of processed detail image values;
  - 25      g. combining the processed image detail values with the low pass filtered image values to produce a sharpened digital image.
2. The method of processing a digital image claimed in claim 1, wherein said step of generating a non-linear gain function comprises the steps of:
  - 30      a. producing a noise digital image having only a noise component;
  - b. filtering the noise digital image to produce a noise detail image and a low pass filtered

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noise image;

c. dividing the noise detail image into a plurality of blocks;

5 d. performing an SVD transformation on the blocks of the noise detail image to produce singular vectors and an array of singular values for each block;

10 e. calculating the means and standard deviations for respective singular values of the blocks;

f. generating a non-linear gain function for each of the singular values based upon the respective means and standard deviations.

15 3. The method of processing a digital image claimed in claim 1, further including the steps of:

a. operating the method in a plurality of stages, wherein each stage employs blocks overlapping with blocks of another stage;

20 b. generating the processed digital image from the average values of the processed image values from the overlapping blocks, whereby the processed image is generated without visible block structure.

25 4. The method of processing a digital image claimed in claim 1, further including the steps of:

a. operating the method in a stage, wherein said stage employs an image detail signal representing a certain pass band of spatial frequencies, and generating the process digital image from the processed detail signal from said stage, whereby noise from different sources characterized by certain spatial frequency content 35 is effectively removed from the image.

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5. The method of processing a digital image claimed in claim 4, further including the steps of:

5 a. operating the method in a plurality of stages, wherein each stage employs blocks overlapping with blocks of another stage; and

10 b. generating the processed digital image from the average values of the processed image values from the overlapping blocks, whereby the 10 processed image is generated without a visible block-like structure.

6. The method of processing a digital image claimed in claim 1, further including the steps of:

15 a. dividing the detail image into blocks having diagonally oriented edges;

b. performing the SVD transform on the diagonally oriented blocks;

20 c. employing the blocks having the highest singular values for processing the image.

7. The method of processing a digital image claimed in claim 1, wherein the digital image is a color digital image, and wherein the method is applied to each color component of the digital image 25 to produce a processed color digital image.

8. The method of processing a digital image claimed in claim 1, wherein the image is a color digital image having a luminance component and two color components, wherein the method is applied 30 to the luminance component of the digital image to produce a processed color digital image.

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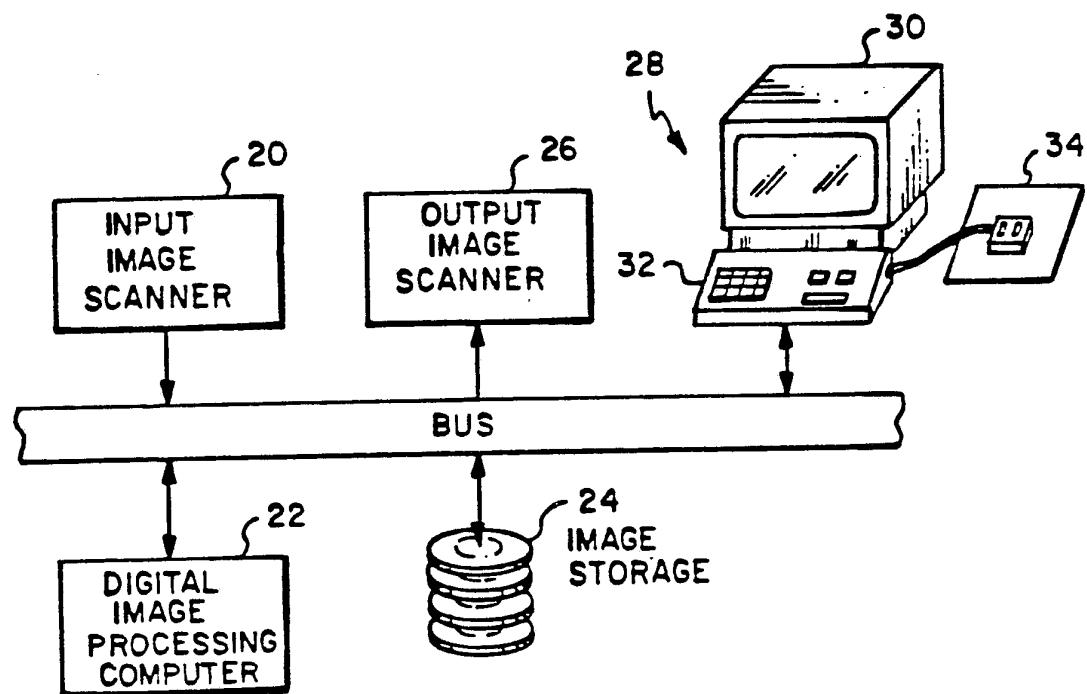


FIG. 1

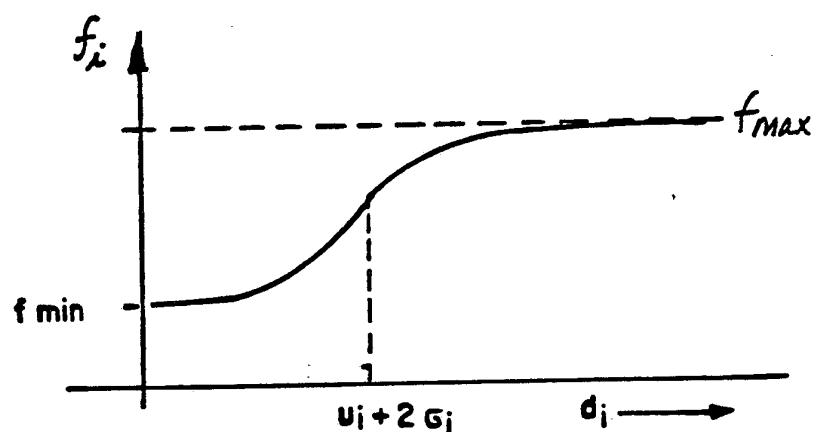
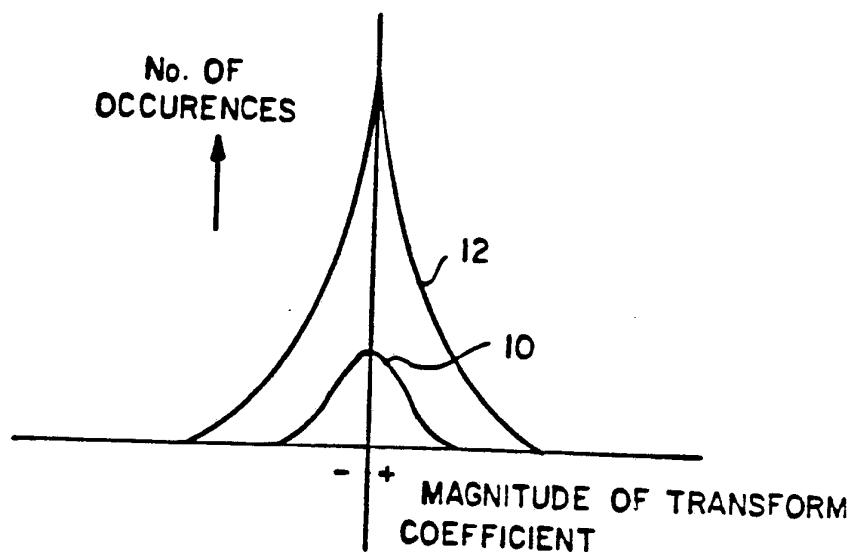
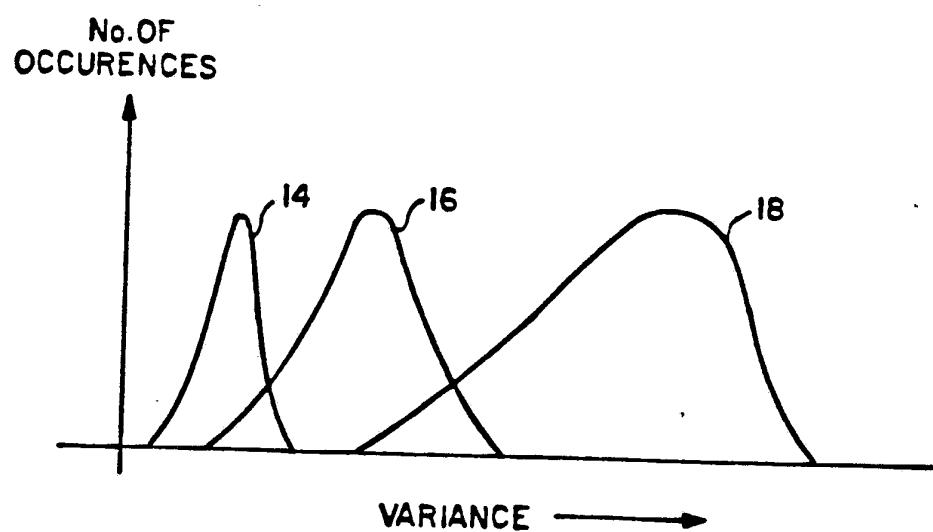


FIG. 6



PRIOR ART

**FIG. 2**



**FIG. 3**

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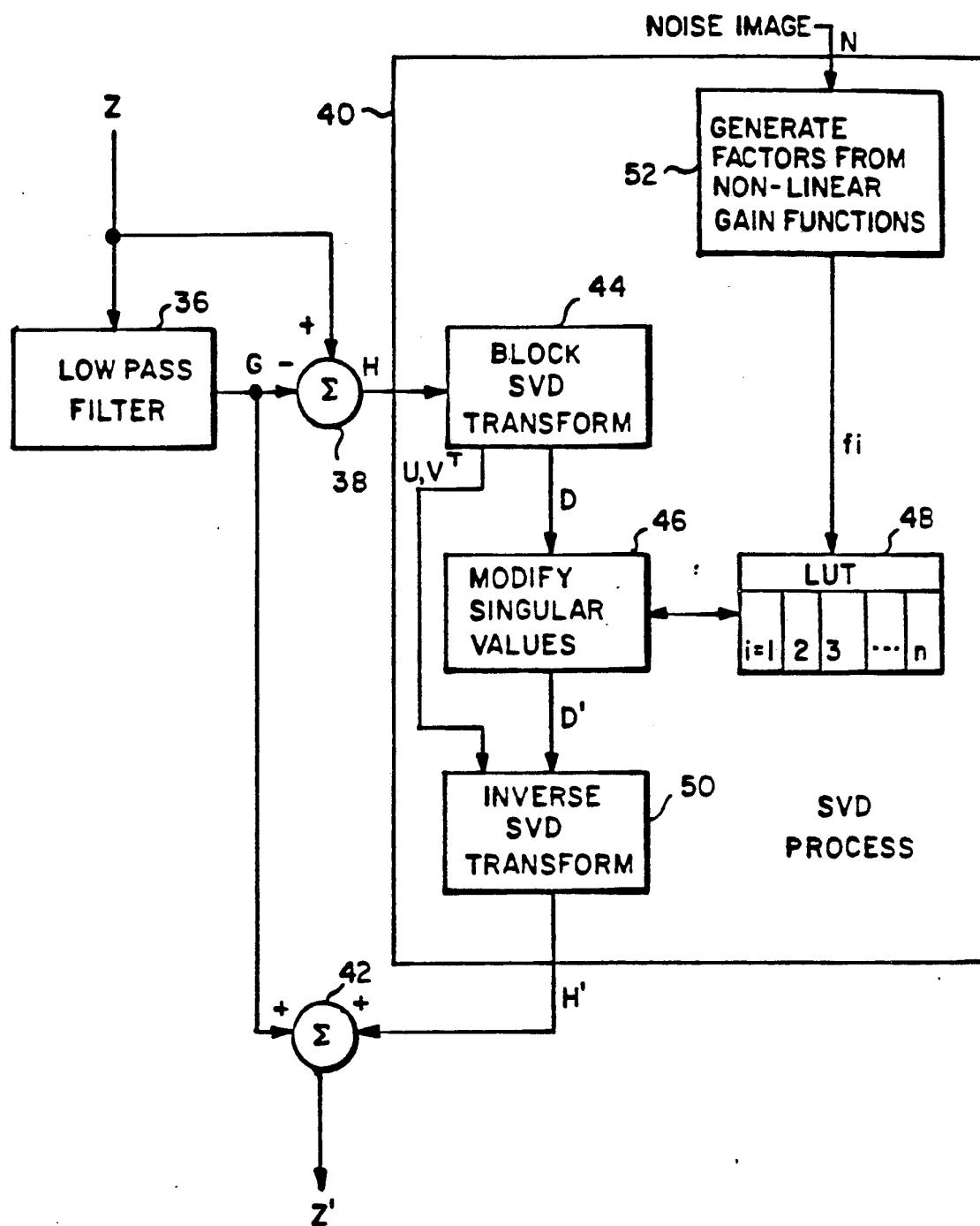
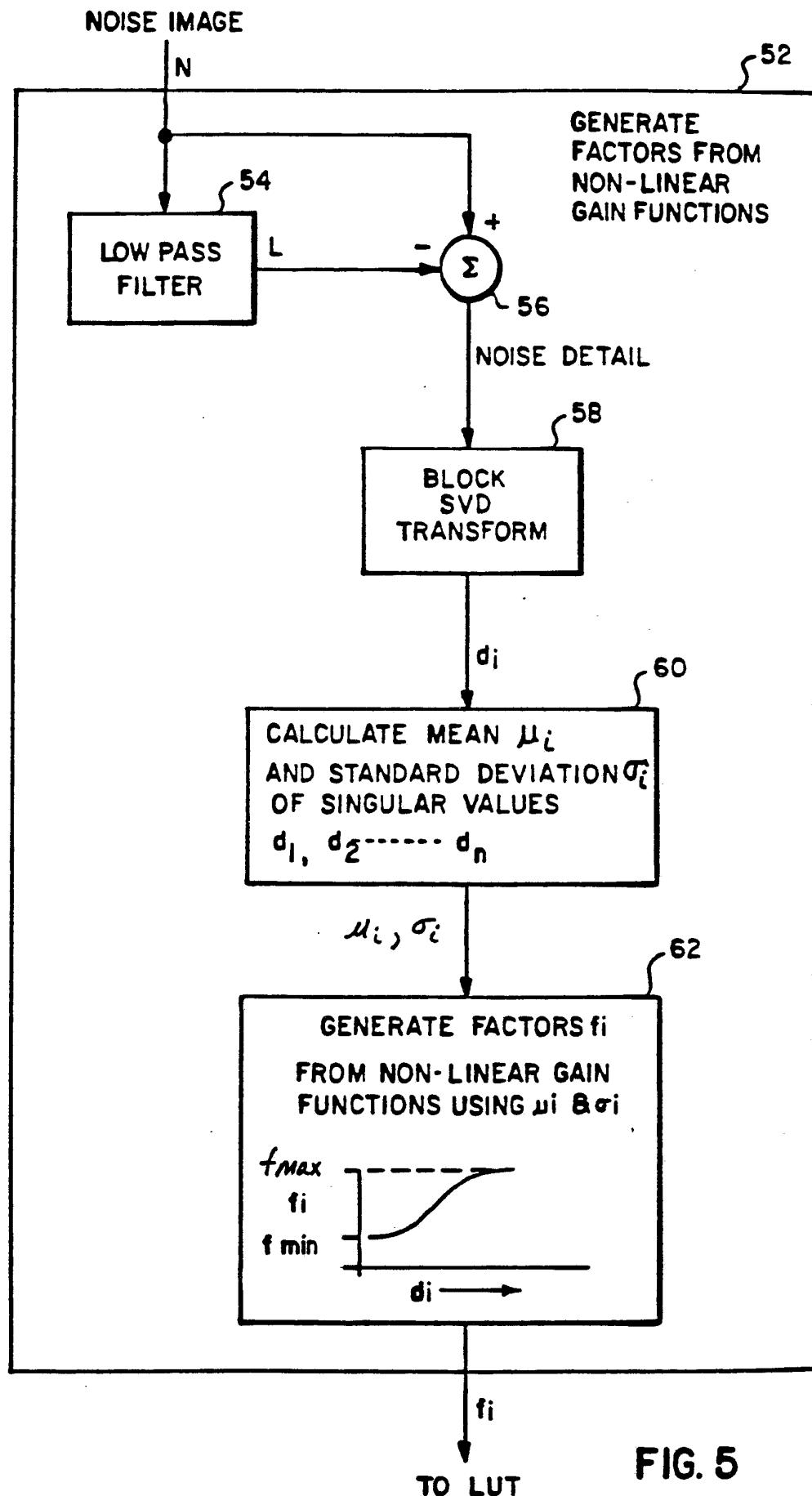


FIG. 4



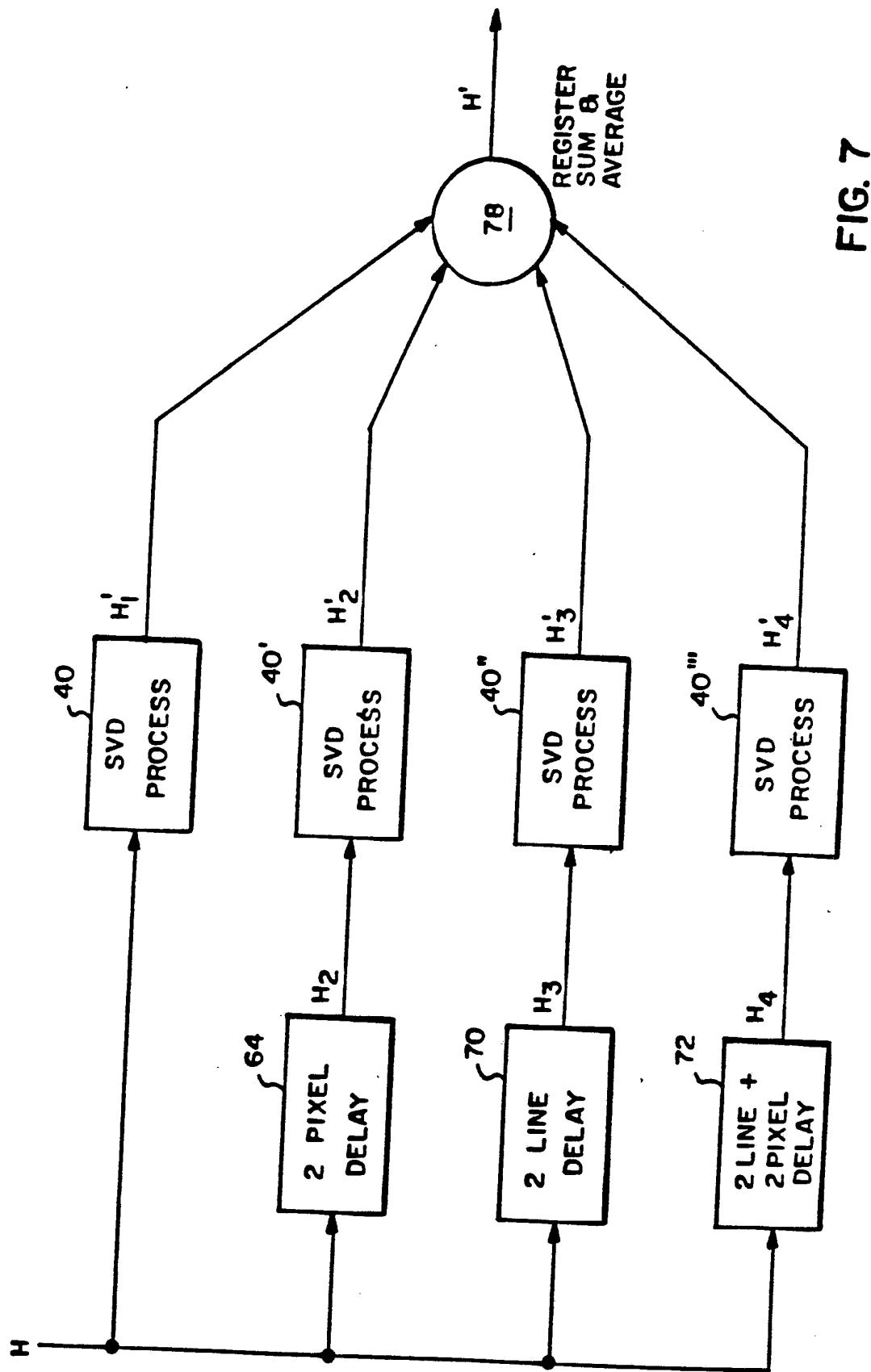


FIG. 7

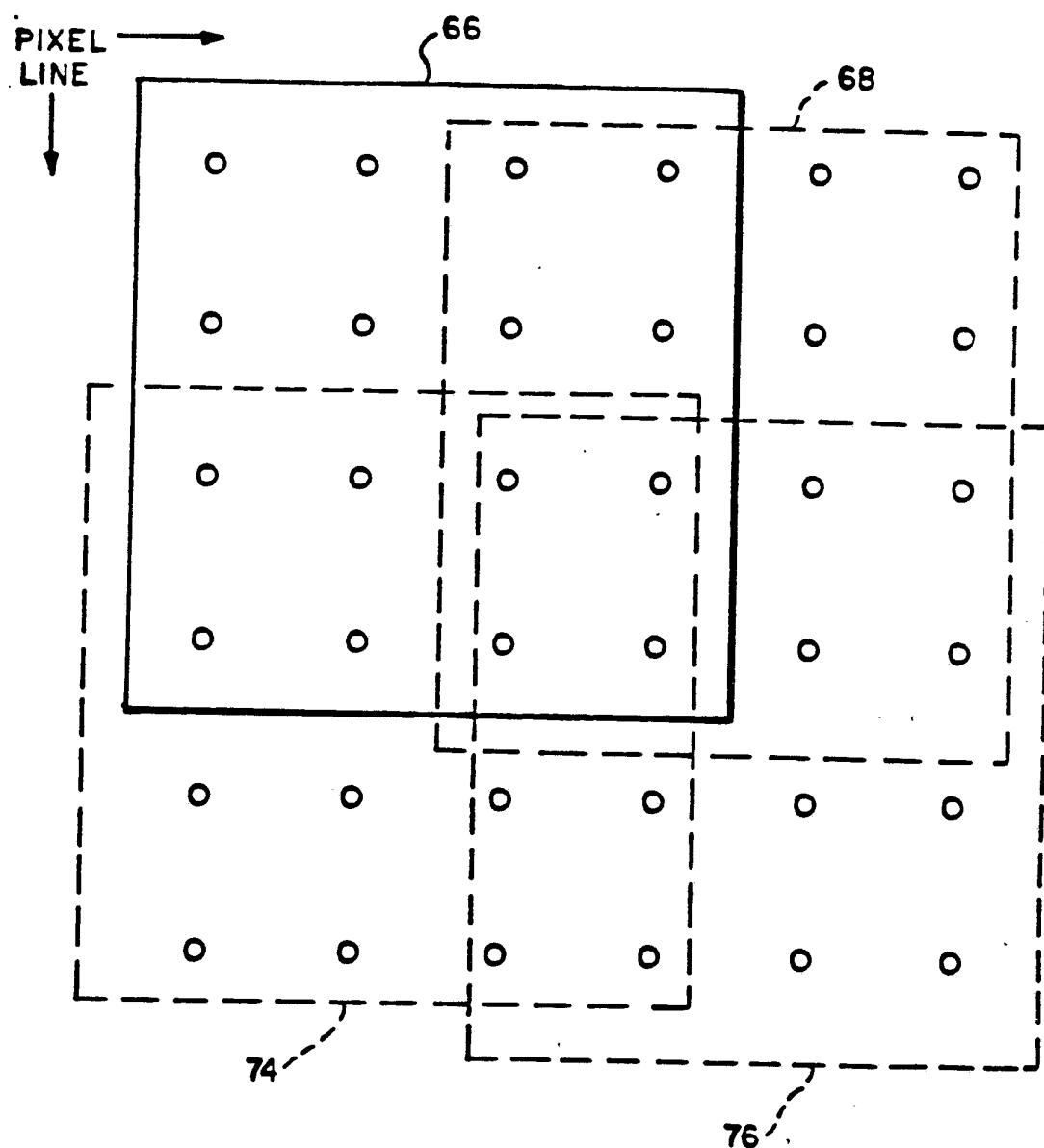


FIG. 8

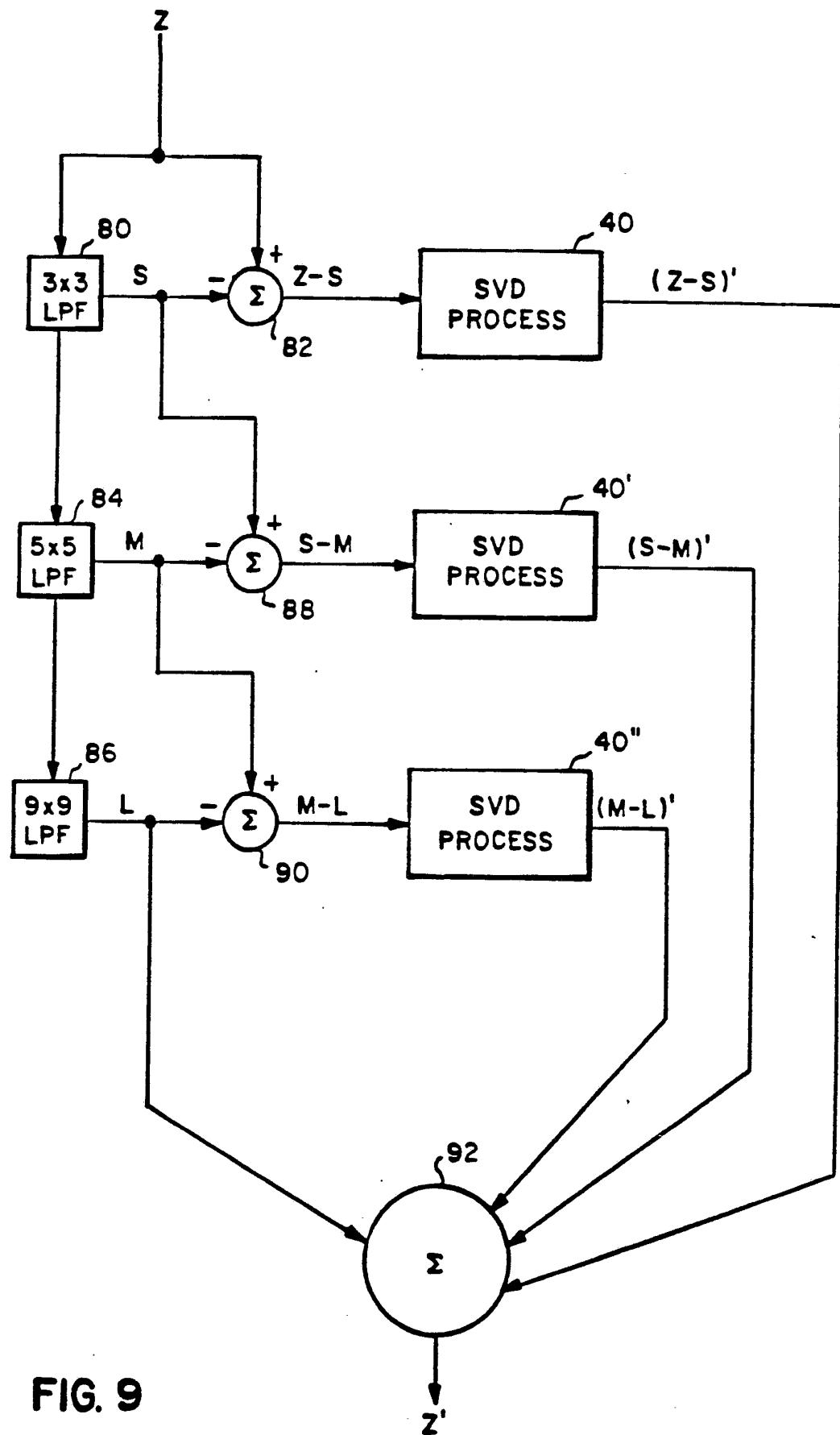


FIG. 9

1	2	1
2	4	2
1	2	1

FIG. 10a

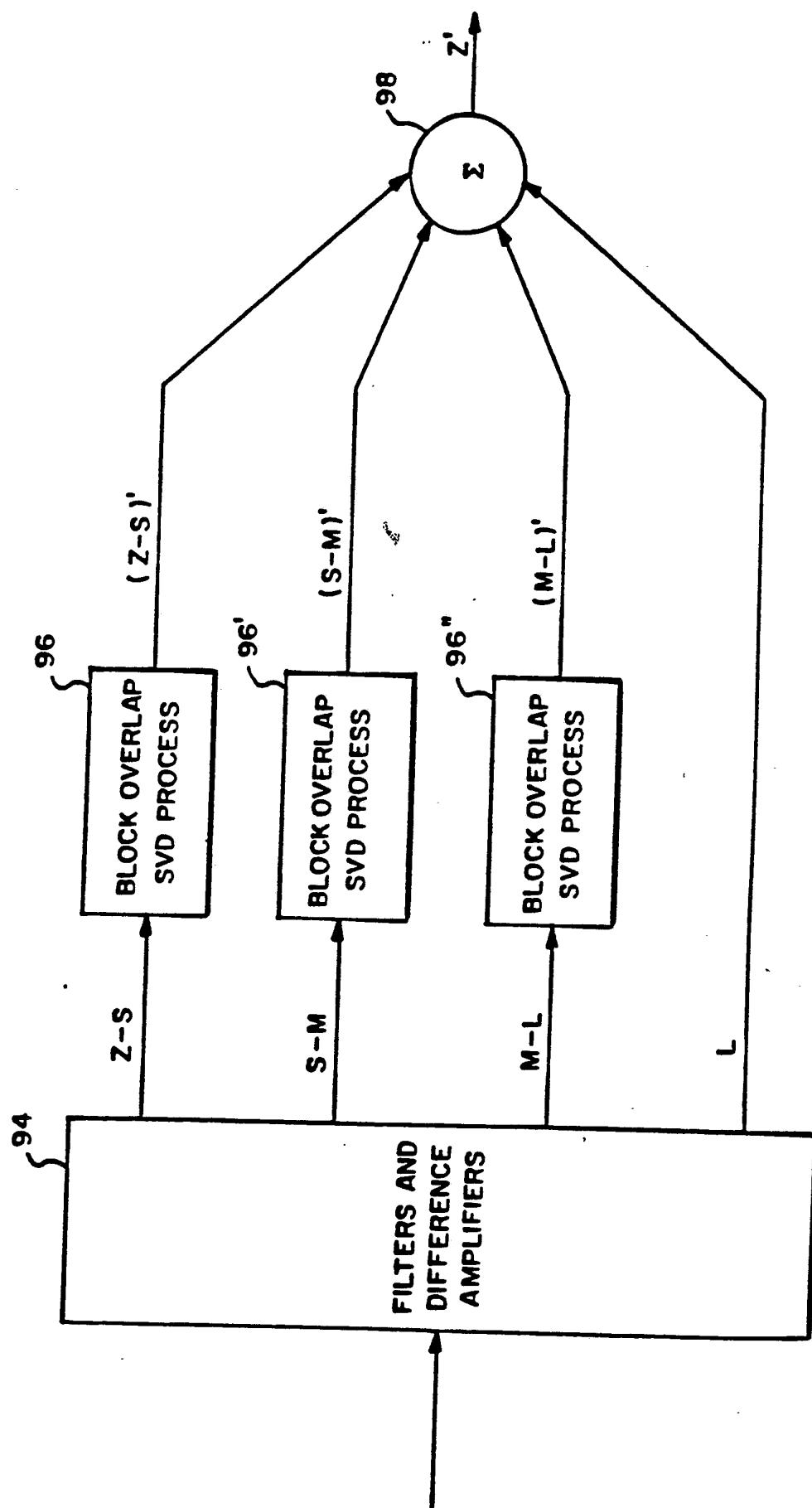
1	0	2	0	1
0	0	0	0	0
2	0	4	0	2
0	0	0	0	0
1	0	2	0	1

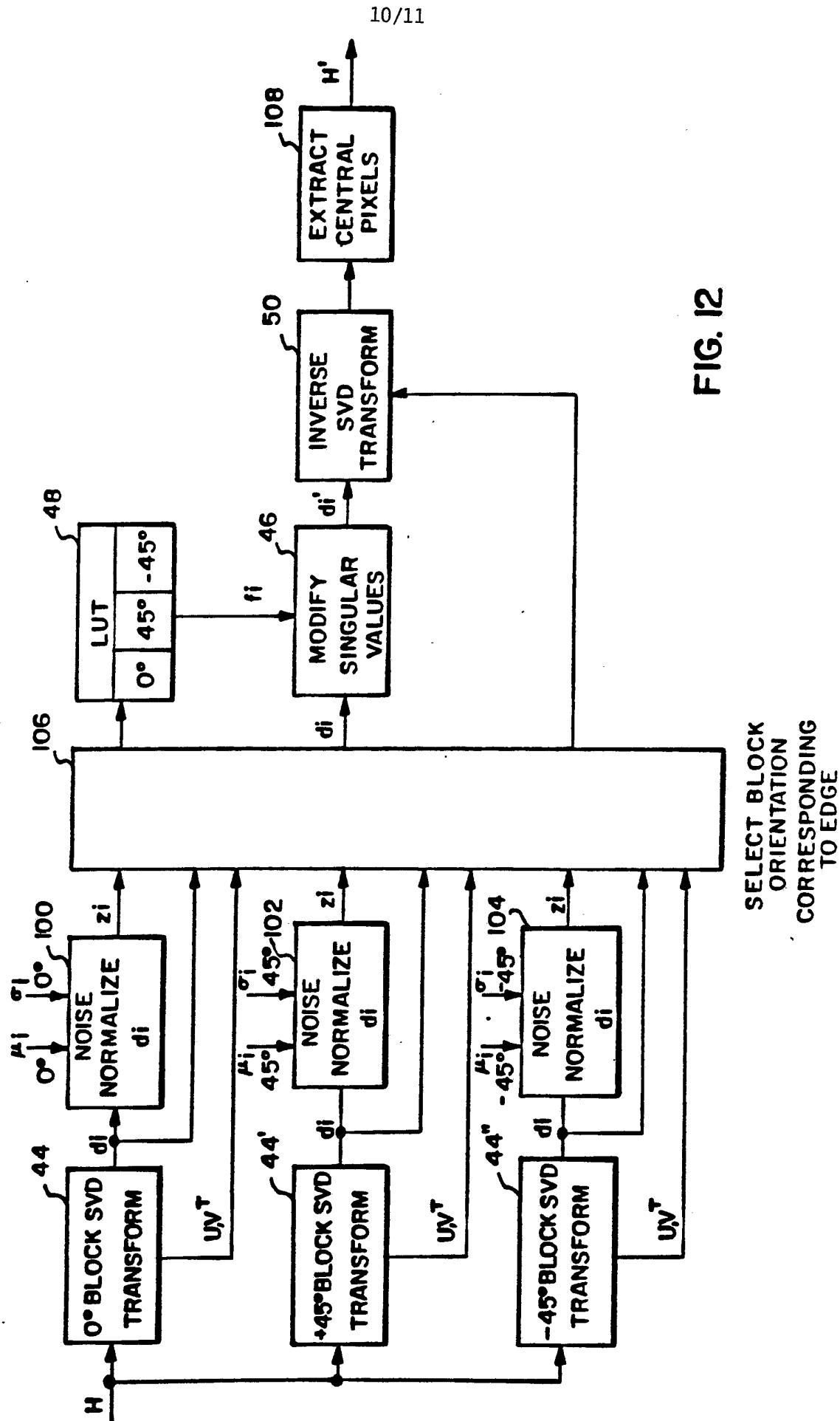
FIG. 10b

1	0	0	0	0	2	0	0	0	1
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
2	0	0	0	4	0	0	0	2	
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
1	0	0	0	2	0	0	0	1	

FIG. 10c

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**FIG. II**



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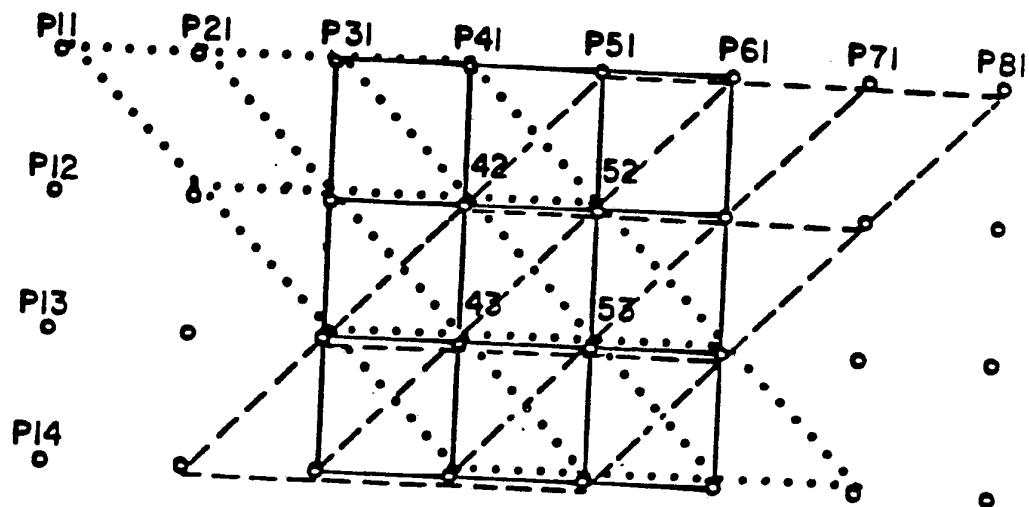


FIG. 13

# INTERNATIONAL SEARCH REPORT

International Application No PCT/US 89/05701

## I. CLASSIFICATION OF SUBJECT MATTER (if several classification symbols apply, indicate all) <sup>6</sup>

According to International Patent Classification (IPC) or to both National Classification and IPC

IPC<sup>5</sup>: G 06 F 15/68

## II. FIELDS SEARCHED

Classification System	Minimum Documentation Searched <sup>7</sup>	
		Classification Symbols
IPC <sup>5</sup>	G 06 F	
Documentation Searched other than Minimum Documentation to the Extent that such Documents are Included in the Fields Searched <sup>8</sup>		

## III. DOCUMENTS CONSIDERED TO BE RELEVANT\*

Category *	Citation of Document, <sup>11</sup> with indication, where appropriate, of the relevant passages <sup>12</sup>	Relevant to Claim No. <sup>13</sup>
A	US, A, 4672437 (LAWRENCE A. CASPER) 9 June 1987 see column 3, line 38 - column 4, line 31 --	1
A	WO, A, 85/00907 (EASTMAN KODAK COMPANY) 28 February 1985 see pages 1-12 --	1-8
A	IEEE Transactions on Pattern Analysis and Machine Intelligence PAMI-9, No. 1, January 1987, IEEE, (New York, US), Ari Nieminen et al.: "A new class of detail-preserving filters for image processing", pages 74-90 see the whole document	1

- \* Special categories of cited documents: <sup>10</sup>
- "A" document defining the general state of the art which is not considered to be of particular relevance
- "E" earlier document but published on or after the international filing date
- "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)
- "O" document referring to an oral disclosure, use, exhibition or other means
- "P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step

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## IV. CERTIFICATION

Date of the Actual Completion of the International Search

21st April 1990

Date of Mailing of this International Search Report

30.05.90

International Searching Authority

EUROPEAN PATENT OFFICE

Signature of Authorized Officer

E.W. HECK

**ANNEX TO THE INTERNATIONAL SEARCH REPORT  
ON INTERNATIONAL PATENT APPLICATION NO.**

US 8905701  
SA 33764

This annex lists the patent family members relating to the patent documents cited in the above-mentioned international search report. The members are as contained in the European Patent Office EDP file on 15/05/90. The European Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

Patent document cited in search report	Publication date	Patent family member(s)		Publication date
US-A- 4672437	09-06-87	None		
WO-A- 8500907	28-02-85	US-A- 4553165 EP-A, B 0151614 JP-T- 60502023	12-11-85 21-08-85 21-11-85	