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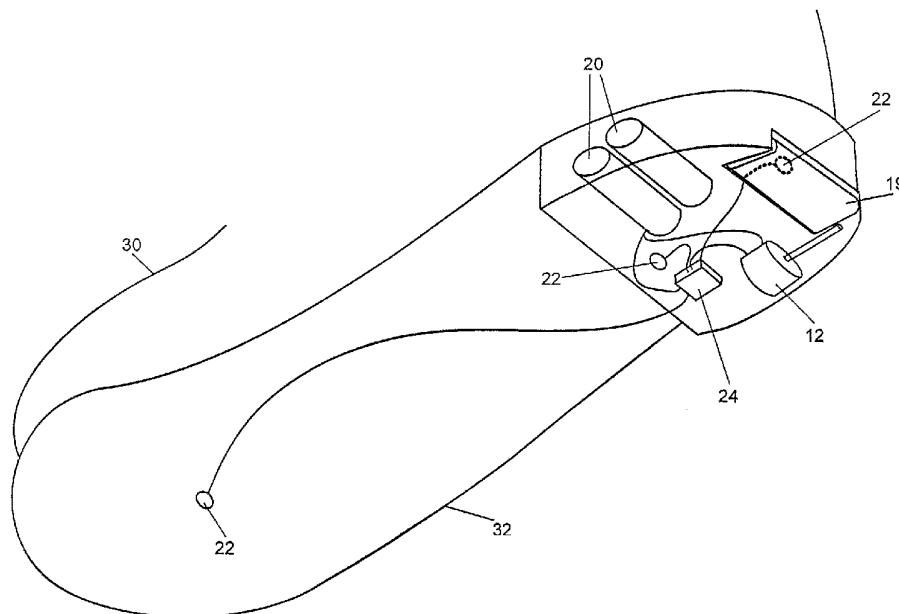
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ning of each regular issue of the PCT Gazette.

(54) Title: DEVICE AND METHOD FOR REGAINING BALANCE



(57) Abstract: A device and method for assisting a user in regaining his balance is disclosed. The device comprises: at least one sensor for sensing changes in weight distribution on any of the feet of the user; at least one propulsion unit to be coupled to any of the feet of the user for displacing a foot of the user when a change in the weight distribution on that foot reaches a predetermined condition; and a controller for receiving signals from the sensor indicative of the predetermined condition and activating the propulsion unit. When the predetermined condition is determined the propulsion unit displaces a foot of the user mechanically in a direction that results in the repositioning of the support area of the user beneath the center of mass of the user, thus allowing the user to regain balance.

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DEVICE AND METHOD FOR REGAINING BALANCE

FIELD OF THE INVENTION

[0001] The present invention relates to device and method for assisting a person in regaining his or hers balance, while walking or standing. The invention is particularly useful for old people, disabled people, and any other group of people with gait and standing difficulties.

BACKGROUND OF THE INVENTION

[0002] People may lose their balance for many reasons. Some may trip over an obstacle, lose their balance and fall. Others may lose their balance sensation, so that they can no longer stand or walk safely. Old people, in particular, may be slow in responding to changes in their balance; consequently they may have difficulties in regaining balance, when encountering sudden weight shifts (forward, backwards or sideways). By the time they react and try to move a foot, to regain balance, the fall process has already progressed beyond prevention. Some old people use a walking cane or a four-legged support device that provides them with a stabilizing moment to support any sway of their body weight. Such supporting devices are cumbersome, heavy to carry, and some are reluctant to use them because they view these devices as degrading.

[0003] Typically, a person is said to be in balance, when his center of mass is positioned over his support area.

[0004] The support area of each foot is the contact area of that foot with the surface below, and if a person is standing with one foot up (in a stationary position) his center of mass would have to be over the support area of the foot which is in contact with the ground. If a person is standing stationary, then his center of mass lies within the combined support area of his both feet, which is the area physically covered by the feet and the area between them.

[0005] When a person walks, his center of mass (together with his inertial momentum) shifts in position between both his feet. This is a dynamic state that evolves during the gait of the person (see Figure 7d, that illustrates the shift in the center of mass in normal

gait, and Figure 7e, that illustrates the shift in the center of mass in typical elderly people).

[0006] The present invention addresses situations of loss of balance, both in static cases (when a person is stationary) and dynamic cases (when a person is walking).

[0007] The problem of falling is related to the mechanism in which a standing person maintains his balance. The sensory elements of the brain interpret, any shift of the body's center of weight, relative to both feet, by sensing the distribution of weight of the body over the support area of the feet. A shift of body weight forward or backward can be detected by sensing the weight distribution between the front and back areas of the foot. A shift of body weight sideways can be detected by sensing the weight distribution between the two legs.

[0008] In a standing position, when the body feels any imbalance toward the back it tries to counter it by moving more weight support to the heels. This creates a forward torque that returns the center of body weight forward, above the feet. When the body feels imbalance toward the front, it gives more support to the front of the foot, pushing the body center to the back. When the body experiences weight imbalance to one of the sides it shifts more support to that side. If a person is too slow to respond the center of weight may move over the heels, toes or over one of his legs, and balance may be regained only by displacing the foot and executing a step. For older people who may be weak and slow to response, the foot movement may come too late, thus a fall may be inevitable.

[0009] A main object of the present invention is to provide a device and method for assisting the user in regaining balance, by moving his foot in the desired direction, such that the center of body weight is returned over the support area

[0010] Automatic servo walking tools have been demonstrated before. They are based on the mechanism of walking by shifting the legs position in steps. They have never become practical in use because of the large electric motors necessary to assist the human body walking mechanism, and the lack of low weight power source in the form of electric batteries. Another aim of the present invention, is to facilitate a shift of the body weight with a burst of power that is needed only for intermittent periods, thus

assisting the user in regaining his balance. Using only power bursts for regaining balance enables the device to be based on a simple low cost battery to power a motor.

SUMMARY OF THE INVENTION

[0011] There is thus provided, in accordance with some preferred embodiments of the present invention, a device for assisting a user in regaining his balance, the device comprising:

[0012] at least one sensor for sensing changes in weight distribution on any of the feet of the user;

[0013] at least one propulsion unit to be coupled to any of the feet of the user for displacing a foot of the user when a change in the weight distribution on that foot reaches a predetermined condition;

[0014] a controller for receiving signals from said at least one sensor indicative of the predetermined condition and activating the propulsion unit,

[0015] whereby, when the predetermined condition is determined the propulsion unit displaces a foot of the user mechanically in a direction that results in the repositioning of the support area of the user beneath the center of mass of the user, thus allowing the user to regain balance.

[0016] Furthermore, according to some preferred embodiments of the present invention, the propulsion unit comprises a motor coupled to a revolving element.

[0017] Furthermore, according to some preferred embodiments of the present invention, the revolving element comprises at least one wheel.

[0018] Furthermore, according to some preferred embodiments of the present invention, the revolving element is a belt.

[0019] Furthermore, according to some preferred embodiments of the present invention, the propulsion unit is provided with a surface of enhanced friction.

[0020] Furthermore, according to some preferred embodiments of the present invention, the propulsion unit is powered by at least one battery.

[0021] Furthermore, according to some preferred embodiments of the present invention, said at least one sensor is selected from the group consisting of: weight activated mechanical switches, strain gauges, piezoelectric sensors, electronic sensors.

[0022] Furthermore, according to some preferred embodiments of the present invention, the device is incorporated in at least one shoe

[0023] Furthermore, according to some preferred embodiments of the present invention, the device is integrated in at least one shoe.

[0024] Furthermore, according to some preferred embodiments of the present invention, the device is further provided with a communication unit for communicating information to or from an external unit.

[0025] Furthermore, according to some preferred embodiments of the present invention, the device also includes a receiver for receiving information from a communication unit associated with other foot of the user.

[0026] Furthermore, according to some preferred embodiments of the present invention, the propulsion unit provides propulsion for displacing the foot of the user along one axis.

[0027] Furthermore, according to some preferred embodiments of the present invention, the propulsion unit provides propulsion for displacing the foot of the user along more than one axis.

[0028] Furthermore, according to some preferred embodiments of the present invention, there is provided a method for assisting a user in regaining his balance, the method comprising:

[0029] providing at least one sensor for sensing changes in weight distribution on any of the feet of the user;

[0030] providing at least one propulsion unit to be coupled to any of the feet of the user for displacing a foot of the user when a change in the weight distribution on that foot reaches a predetermined condition;

[0031] providing a controller for receiving signals from said at least one sensor indicative of the predetermined condition and activating the propulsion unit,

[0032] sensing changes in weight distribution on any of the feet of the user and

[0033] displacing a foot of the user mechanically using the propulsion unit, when a change in the weight distribution on that foot reaches a predetermined condition, in a direction that results in the repositioning of the support area of the user beneath the center of mass of the user, thus allowing the user to regain balance.

[0034] Furthermore, according to some preferred embodiments of the present invention, the foot is moved along one axis.

[0035] Furthermore, according to some preferred embodiments of the present invention, the foot is moved along more than one axis.

[0036] Furthermore, according to some preferred embodiments of the present invention, the method further comprises providing communication unit for communicating information to or from an external unit.

[0037] Furthermore, according to some preferred embodiments of the present invention, information is communicated the communication unit and a communication unit associated with other foot of the user.

BRIEF DESCRIPTION OF THE DRAWINGS

[0038] In order to better understand the present invention, and appreciate its practical applications, the following Figures are provided and referenced hereafter. It should be noted that the Figures are given as examples only and in no way limit the scope of the invention. Like components are denoted by like reference numerals.

[0039] **Figure 1** is a diagram of a device for regaining balance, in accordance with a preferred embodiment of the present invention.

[0040] **Figure 2a** is a schematic illustration of a propulsion unit of a device for regaining balance, in accordance with a preferred embodiment of the present invention.

[0041] **Figure 2b** is a schematic illustration of another design for a propulsion unit for a device for regaining balance, in accordance with a preferred embodiment of the present invention.

[0042] **Figure 3a** illustrates a side view of a device for regaining balance, according to a preferred embodiment of the present invention, incorporated in the heel section of a sole of a shoe.

[0043] **Figure 3b** illustrates a side view of another preferred embodiment of a device for regaining balance, incorporated in the heel section of a shoe, with a pair of wheels.

[0044] **Figure 3c** illustrates a side view of another preferred embodiment of a device for regaining balance, incorporated in the heel section of a shoe, with a rotating belt.

[0045] **Figure 4** illustrates a bottom view of a device for regaining balance, incorporated in the heel section of a shoe, with a rotating belt, showing a suggested sensor positioning scheme.

[0046] **Figure 5** illustrates a bottom view of the device shown in Figure 4, showing additional components.

[0047] **Figure 6a** is a schematic sideways illustration of the forces acting on a balanced standing person.

[0048] **Figure 6b** is a schematic sideways illustration of the forces acting on a person on the verge of losing balance backwards.

[0049] **Figure 6c** is a schematic sideways illustration of the forces acting on a person regaining balance by moving his foot backwards.

[0050] **Figure 7a** is a schematic frontal illustration of the forces acting on a balanced standing person.

[0051] **Figure 7b** is a schematic frontal illustration of the forces acting on a person losing balance toward his left side.

[0052] **Figure 7c** is a schematic frontal illustration of the forces acting on a person regaining balance by moving his foot to his left.

[0053] **Figure 7d** is a schematic illustration of the shifting of the center of mass during typical gait, and the regaining of balance after momentary loss of balance.

[0054] **Figure 7e** is a schematic illustration of the shifting of the center of mass during gait of a person with a balance disability or slow responses, and the regaining of balance after momentary loss of balance.

[0055] **Figure 7f** is a schematic illustration of the shifting of the center of mass during gait, and the regaining of balance imparted by a device for regaining balance, in accordance with a preferred embodiment of the present invention.

[0056] **Figure 8a** is an illustration of a typical installation of a backward driving wheel in the sole of a shoe, according to a preferred embodiment of the present invention.

[0057] **Figure 8b** is an illustration of a typical installation of a backward driving belt in the sole of a shoe, according to a preferred embodiment of the present invention.

[0058] **Figure 8c** is an illustration of a typical installation of three backward driving wheels in the sole of a shoe, according to a preferred embodiment of the present invention.

[0059] **Figure 9** is an illustration of a typical installation of driving wheels in the shoe sole for displacing the foot of the wearer of the shoe either backwards or sideways.

[0060] **Figure 10a** is an illustration of a typical installation of driving wheels in the shoe sole for displacing the foot of the wearer of the shoe sideways.

[0061] **Figure 10b** is an illustration of a typical installation of driving wheels in the shoe sole for displacing the foot of the wearer of the shoe sideways (substantially perpendicular to the direction of gait).

[0062] **Figure 10c** is an illustration of a typical installation of driving wheels in the shoe sole for displacing the foot of the wearer of the shoe sideways (diagonally to the direction of gait).

[0063] **Figure 10d** is an illustration of a typical installation of driving wheels in the shoe sole for displacing the foot of the wearer of the shoe sideways (with pairs of wheels).

[0064] **Figure 10e** is an illustration of a typical installation of driving wheels in the shoe sole for displacing the foot of the wearer of the shoe sideways (with rotating belts).

DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS

[0065] A typical device for regaining balance, in accordance with a preferred embodiment of the present invention includes a propulsion unit for displacing the foot of the user, when a change in the weight distribution on that foot reaches a predetermined condition; a controller, which receives signals from at least one weight distribution sensor, and activates the propulsion unit, when the predetermined condition is met. In a preferred embodiment, the propulsion unit comprises of a motor coupled to

a revolving element, which may, for example be a wheel, a set of wheels, or a revolving belt.

[0066] **Figure 1** is a diagram of a device for regaining balance (10), in accordance with a preferred embodiment of the present invention. The device is comprised of at least the following components: At least one (in this embodiment two) load sensor element (22) that produces electric signals reflecting the weight pressure imposed on it. The sensor elements can comprise mechanical switches activated by weight, strain gauge or piezoelectric sensing devices or any other mechanism that produces an electric signal reflecting changes in the distribution of weight of the person. The weight load sensors are connected to a controller, which can be, for example, a central processor (24). The processor samples the signal, from which it interprets the temporal load imposed on the sensors. The processor compares the loads to other loads or to any calculated threshold. It may also perform any type of logical calculations, to adjust the response to a sequence of events, which include standing and walking. The processor produces an electric command, which activates a propulsion unit (14). The propulsion unit (14) includes an electric motor (12) and a wheel (18). In the drawing of Figure 1 the electric motor (14), a brake unit (13) and the gear (16) are confined within the wheel assembly to optimize the volume occupied by the system, but other arrangements are possible too. At least one battery (20) is used to power the propulsion unit and the processing unit. The system may also include a transceiver unit (26), which can receive and transmit information from and to the central processing unit. The transceiver may be used to communicate between the CPUs of two shoes equipped with a device in accordance with the present invention or to communicate with an external unit. Such an external unit can be placed, for example, at a doctor's clinic for monitoring the balance of a patient along a period of time. In yet another preferred embodiment, instead of using a transceiver, a separate transmitter or receiver may be used.

[0067] In another preferred embodiment the controller executes a logical algorithm that detects when the person is leaning to the back and load is released from the front of the foot and shifted to the back, and differentiate it from walking where the heel touches the ground before the front of the foot and load is shifted from the back to the front.

[0068] In another preferred embodiment the controller executes a logical algorithm that detects when a person is walking or standing and the pace of walking according to the sequence of load change between front and back of the foot, and synchronizes the activation of the propulsion unit to the timing of the foot placing on the ground.

[0069] In another preferred embodiment the controller executes a logical algorithm that detects when a person is seating according to the amount of load on the foot and avoid activating the propulsion unit when the person is not standing or walking.

[0070] In another preferred embodiment, the electric motor can be installed outside the wheel assembly. In another preferred embodiment the gear may also be installed outside the wheel assemble. The selected configuration depends on specific design parameters such as the dimensions of the electric motor and gear vs. the desired wheel dimensions.

[0071] A basic configuration of a device according to the present invention provides motion to the shoe in one direction. A system that provides motion in more than one direction includes two or more sets of wheels. The same motor, central processor and the same battery can serve to power the motion in all directions. Some of the sensors may be used to activate more than one set of wheels. In some configurations sensors can serve as load detectors for monitoring balance in more than one direction.

[0072] Figures 2a and 2b present specific implementations of the propulsion unit (14). Figure 2a presents a propulsion unit (14), wherein the electric motor (12) and the gear (16) are installed inside the wheel (18). The motor typically rotates at high speed that can reach as much as 10,000RPM and more. It drives a planetary gear (16). The gear reduces the rotational speed for the drive wheel, to provide the desired linear motion of the shoe on the ground, at a typical velocity of about 10 cm/sec. The gear also provides the high torque required to move the shoe under the weight of a person. The gear is preferably designed to prevent rotation of the wheel under external forces. This may be achieved by the brake that prevents the wheels from rotating when not activated. This prevents the sole from inadvertently sliding on the ground under the person weight or any externally exerted forces. The wheel may be provided with an enhanced friction surface, like rubber or any other such material, to increase the grip of the shoe to the ground.

[0073] In cases where the electric motor is not powerful enough to drive the wheel a spring motor (15) can be used. Figure 2b presents a particular embodiment of a spring motor mechanism installed inside the wheel assembly. The spring can provide high torque with a limited number of rotations. The spring (15) is loaded by an external electric motor (12) when the system is activated. The spring is connected to a gear mechanism (16) to reduce the rotational speed. An electric actuator releases the gear by receiving an electrical command signal from the central processor unit (24). The actuator releases the spring and allows it to drive the wheel via the gear. Once the spring is unloaded the electric motor reloads the spring for the next event.

[0074] Figure 3a present a preferred embodiment of the invention, where a single wheel (18) is integrated in a shoe (30). The wheel (18) is located at the back of the shoe sole (32), in the heel area. The wheel is closely leveled with the sole bottom and extends to the sole back end, such that it does not protrude outside the sole (32). When the person leans backward his weight is shifted onto the wheel at the back. Any rotation of the wheel will then move the sole on the ground. The wheel level, relative to the sole bottom, is designed such that most of his weight rests on the wheel when the sole flexes as the person leans to the back of the heel.

[0075] In another preferred embodiment, as presented in figure 3b, a second wheel (18) is mounted in parallel to the first wheel (18). The second wheel may include a drive motor and gear that operate together with the motor of the first wheel, or it may serve to support weight only. The second wheel provides flat support of the drive system on the ground and thus better traction.

[0076] Yet in another preferred embodiment, as presented in figure 3c, a belt (19) is installed between two wheels (18). The belt provides a larger area of support and better grip to the ground.

[0077] The weight distribution along a single foot and between the user's feet can be sensed using one or more sensors, which can comprise a strain gauge, piezoelectric or any other kind of sensor that produces an electric signal that indicates changes in the distribution of weight. The sensors can also be made of mechanical switches that produce a signal under a predetermined load. In a preferred embodiment, the sensors are installed inside a flexible sole, such that they are protected from the ground but feel the

weight load. The sensors may also be installed inside the shoe below the insole of the foot. Sensors are installed for the detection of weight distribution in any desired direction. An example of sensor location in the shoe, designed to measure the weight shift toward the back and front, is presented in Figure 4. Two sensors, or a single differential sensor that measure load difference between two sections of the sensor in any given direction, (22) are installed in the posterior (back) of the sole (32) (around the heel). The first sensor is installed at the base of the driving belt (19). The sensor may be installed between the belt assembly and the sole body to measure the weight load on the belt. A second sensor (22) is installed at the heel area, in front of the first sensor. The weight distribution between the two elements reflects the weight distribution inside the heel. A third sensor is installed in the anterior section of the sole (32). The weight distribution between the third sensor and the first two sensors reflect the weight distribution in the foot along the forward-backward axis.

[0078] An example of one embodiment, wherein the device is integrated in a single shoe (30) is presented in Figure 5. The example shows a device (10) designed with a single belt (19) at the back-end of the sole (heel area), for backward imbalance assistance. The system includes a belt assembly (19), an external motor (12); a central processor (24) and two batteries (20), all installed inside the heel area of the sole (32). Three sensors (22) are installed one above the belt assembly, a second in the heel and a third in the front sole. All are connected by embedded electric wires to the central processor (24). The complete system can be installed in the sole (32) and can be completely sealed to water and protected from wear and shock. The batteries can be mounted in housing that allows replacement or can be fixed permanently. Since the system uses power in short bursts, during emergency events, the capacity of a single charge may last for long usable hours.

[0079] To better understand how the device assists in cases of loss of balance, one has to understand the balancing mechanism and the sequence of events associated with a fall of a person. Figure 6a presents the forces acting on the feet to keep a standing person in balance posture, and preventing him from falling forward or backward. The body center of weight is countered by the forces acting on the heels and on the front section of the foot. Most of the weight is supported by the heel while the force on the

front section of the foot serves mostly for balance. When the center of weight moves forward more force is exerted on the front section of the foot to push the body backward. When the center of weight moves backwards more force is exerted on the heel to move the body forward.

[0080] The greatest "fear of fall" of elderly people is associated with a backward fall. This happens when the center of weight moves all the way back such that all the weight is supported by the heels, see Figure 6b. At this stage a person has to move one foot backwards to prevent tripping backwards. Elderly people are slower to respond. When they reach this dangerous condition, presented in figure 6b, they may be too slow to lift their foot and move it backwards. As a result they are in danger of losing their balance and falling. At this point the device of the present invention actively intervenes as illustrated in Figure 6c. The device detects the imbalance condition, and activates the drive and the wheels, resulting in a movement of the foot backwards. This backward movement compensates for the person's inability to respond quickly enough, and intentionally move his foot backwards in time. The device of the present invention uses a person's instinctive reaction in imbalance situation such as presented in figure 6b. In this situation, a person instinctively leans to the back towards his heels, in an effort to move the support force as further back as possible. When he does so, most of the weight is concentrated on the wheel and on the rear weight sensor (Figure 4). When the device senses these conditions it activates the propulsion unit, which moves the foot backwards. A short distance movement of the foot is enough to regain balance. Since the foot is displaced in the direction the person would have liked the foot to be placed, it does not conflict with the person's natural balancing process

[0081] While standing or walking, a person can also lose balance and fall sideways. Figures 7a-7c present the balancing mechanism in such a situation. Figure 7a presents the forces acting on a person, standing in balance. The person's weight is distributed between his two legs. For each leg the weight is distributed evenly across the horizontal axis of his foot- the forces acting on the outer edge and inner edge of the foot are about equal. To balance the body the person moves his weight from one leg to the other. If the weight shifts too much toward one leg, a person tries instinctively to lean outward, thus exerting more force on the outer edge of the foot. A normal person, at this

situation, will execute a cross over step with the other foot followed by a second sideway correction step with the first foot to regain balance. An old person will try a quick step with the free leg followed by a correction side step at a fast pace. He may be too slow to react and move his foot on time, thus he may lose his balance and fall. The device detects the imbalance in the foot supports. It then activates the side wheel set, which effectively moves the support area of the foot sideways as presented in Figure 7c. This action results in the person regaining his balance. A person's natural balancing mechanisms for each leg are independent of each other; therefore there is no need for the device for regaining balance to synchronize its activity between the two shoes. However, communication and synchronization may be desired and can be incorporated in a device of the present invention when used on two feet. When a person walks, he shifts his weight from one foot to the other. When he loses his balance to one side, he tends to shift weight towards the outer edge of the foot on that side. The device detects this weight shift, and can react in a similar way, as in the standing conditions. The need, to assist the foot in moving and reposition itself, is critical only, when the weight shifts to the outward side of the foot. Imbalance to the inside is easily compensated by the second foot support.

[0082] **Figure 7d** is a schematic illustration of the shifting of the center of mass during typical gait, and the regaining of balance after momentary loss of balance. At first a person steps a series of balanced steps (1, 2, 3), at either sides of the imaginary line representing the progress of the center of mass of that person, until he missteps his (step 4), placing his right foot right below his center of mass with no ability to counter weight shift over the right foot to the side. Instinctively he crosses over with his left foot (5) followed by placing the right foot to the side to counter the center of weight shift and continues an almost uninterrupted gait (6).

[0083] **Figure 7e** is a schematic illustration of the shifting of the center of mass during gait of a person with a balance disability or slow responses, and the regaining of balance after momentary loss of balance. Here after a series of balanced steps (1,2,3) a misstep (4) of the right foot occurs. The slowly responding person will then performs an additional short step with his left foot (5) followed by additional right step placed well to the side (6) to counter the weight shift, and then regain walking by normal left step

(7). In several cases the extra left step followed by a side place right step may lead to loss of balance during gait resulting in a fall.

[0084] **Figure 7f** is a schematic illustration of the shifting of the center of mass during gait, and the regaining of balance imparted by a device for regaining balance, in accordance with a preferred embodiment of the present invention. Here as the misstep occurs (4) the device of the present invention slides the same foot sideways to the right, thus maintaining the center of mass over the support area of the person, helping him to regain balance and continue normal walking.

[0085] An example of the installation and operation of the device with a drive wheel (18) is demonstrated in Figure 8a. The wheel (18) is installed at the back edge of the heel, in the sole (32), in a way that it does not protrude to the back or from the sole bottom. When a person shifts his weight backwards (for any reason) most of the weight is supported by the wheel. The sensors detect this change of weight distribution, thus the wheel is rotated by the motor, and the shoe moves backwards. Figure 8b presents another preferred embodiment of the device, where the wheel is replaced by a belt drive (19), which is supported by two or more wheels (see also Figure 3b).

[0086] Figure 8c is an illustration of a typical installation of three backward driving wheels in the sole of a shoe, according to a preferred embodiment of the present invention.

[0087] Another preferred embodiment is detailed in Figure 9. In this embodiment three sets of wheels (18) are installed in the sole of the shoe (32). The additional wheels are aimed at assisting in sideways imbalance situations. The additional, side drive wheel, can be installed in the heel area, in the area of the front section of the foot, or in both. However, moving the heel sideways may be less comfortable than moving the front section of the foot, a movement which is more natural to the body. Thus a wheel in the front section of the foot may be more comfortable for the user. If parallel sideways movement is required, two wheels are preferably used. One at the back of the sole (heel area) and another in the front of the sole (toes area).

[0088] In yet another embodiment, when diagonal movement is required, the wheels maybe installed at an angle to the main axis of the shoe.

[0089] **Figure 10a** is an illustration of a typical installation of driving wheels in the shoe sole for displacing the foot of the wearer of the shoe sideways.

[0090] **Figure 10b** is an illustration of a typical installation of driving wheels in the shoe sole for displacing the foot of the wearer of the shoe sideways (substantially perpendicular to the direction of gait).

[0091] **Figure 10c** is an illustration of a typical installation of driving wheels in the shoe sole for displacing the foot of the wearer of the shoe sideways (diagonally to the direction of gait).

[0092] **Figure 10d** is an illustration of a typical installation of driving wheels in the shoe sole for displacing the foot of the wearer of the shoe sideways (with pairs of wheels).

[0093] **Figure 10e** is an illustration of a typical installation of driving wheels in the shoe sole for displacing the foot of the wearer of the shoe sideways (with rotating belts).

[0094] It should be clear that the description of the embodiments and attached Figures set forth in this specification serves only for a better understanding of the invention, without limiting its scope.

[0095] It should also be clear that a person skilled in the art, after reading the present specification could make adjustments or amendments to the attached Figures and above described embodiments that would still be covered by the present invention.

CLAIMS

1. A device for assisting a user in regaining his balance, the device comprising:
at least one sensor for sensing changes in weight distribution on any of the feet
of the user;
at least one propulsion unit to be coupled to any of the feet of the user for
displacing a foot of the user when a change in the weight distribution on
that foot reaches a predetermined condition;
a controller for receiving signals from said at least one sensor indicative of the
predetermined condition and activating the propulsion unit,
whereby, when the predetermined condition is determined the propulsion unit displaces
a foot of the user mechanically in a direction that results in the repositioning of the
support area of the user beneath the center of mass of the user, thus allowing the user to
regain balance.
2. The device of claim 1, wherein the propulsion unit comprises a motor coupled to
a revolving element.
3. The device of claim 2, wherein the revolving element comprises at least one
wheel.
4. The device of claim 2, wherein the revolving element is a belt.
5. The device of claim 1, wherein the propulsion unit is provided with a surface of
enhanced friction.
6. The device of claim 1, wherein the propulsion unit is powered by at least one
battery.
7. The device of claim 1, wherein said at least one sensor is selected from the
group consisting of: weight activated mechanical switches, strain gauges, piezoelectric
sensors, electronic sensors.
8. The device of claim 1, incorporated in at least one shoe.
9. The device of claim 1, integrated in at least one shoe.

10. The device of claim 1, further provided with a communication unit for communicating information to or from an external unit.
11. The device of claim 10, wherein the device also includes a receiver for receiving information from a communication unit associated with other foot of the user.
12. The device of claim 1, wherein the propulsion unit provides propulsion for displacing the foot of the user along one axis.
13. The device of claim 1, wherein the propulsion unit provides propulsion for displacing the foot of the user along more than one axis.
14. A method for assisting a user in regaining his balance, the method comprising:
 - providing at least one sensor for sensing changes in weight distribution on any of the feet of the user;
 - providing at least one propulsion unit to be coupled to any of the feet of the user for displacing a foot of the user when a change in the weight distribution on that foot reaches a predetermined condition;
 - providing a controller for receiving signals from said at least one sensor indicative of the predetermined condition and activating the propulsion unit,
 - sensing changes in weight distribution on any of the feet of the user and
 - displacing a foot of the user mechanically using the propulsion unit, when a change in the weight distribution on that foot reaches a predetermined condition, in a direction that results in the repositioning of the support area of the user beneath the center of mass of the user, thus allowing the user to regain balance.
15. The method of claim 14, wherein the foot is moved along one axis.
16. The method of claim 15, wherein the foot is moved along more than one axis.
17. The method of claim 14, further comprising providing communication unit for communicating information to or from an external unit.
18. The method of claim 5, wherein information is communicated the communication unit and a communication unit associated with other foot of the user.

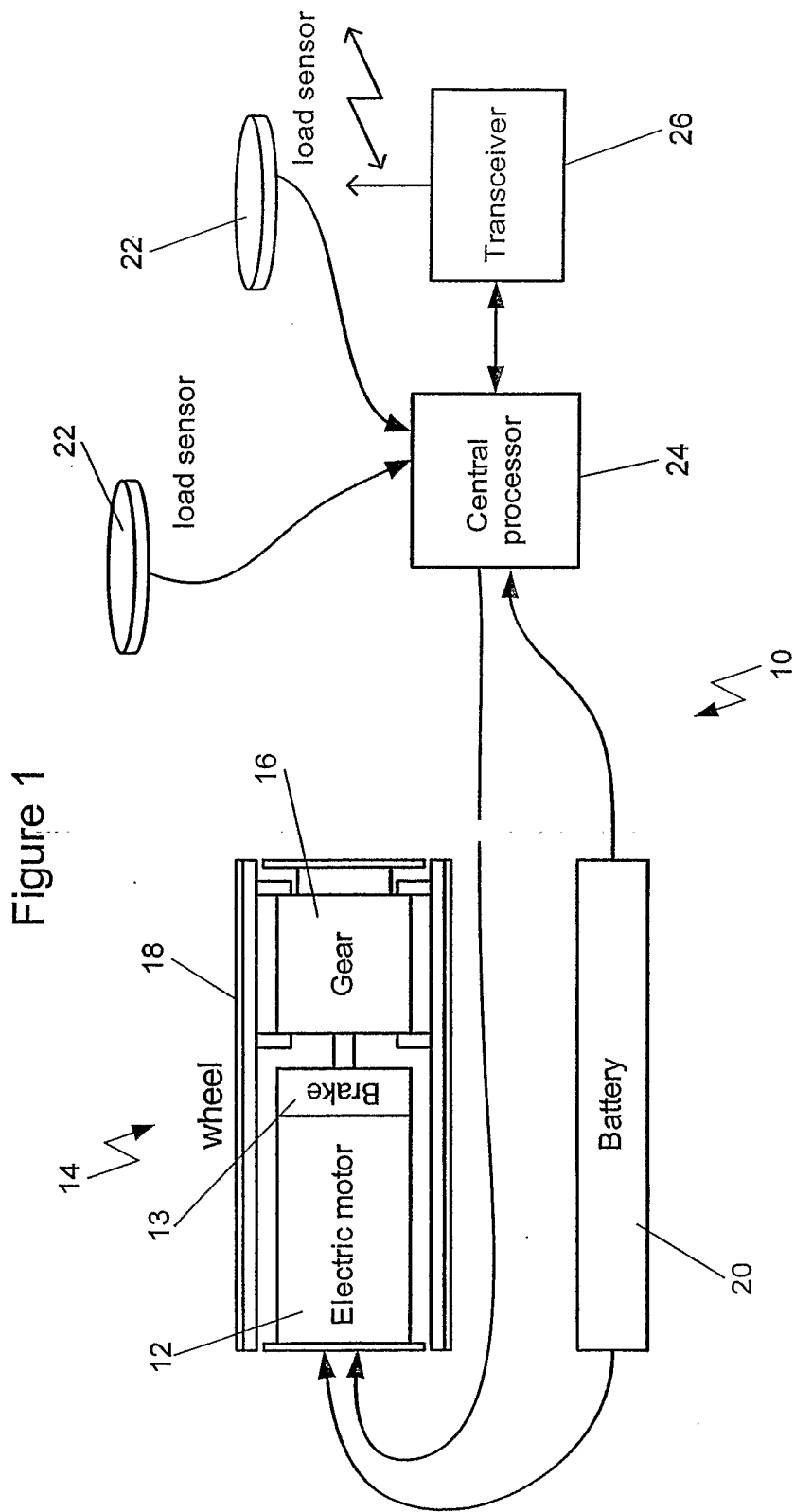


Figure 2b

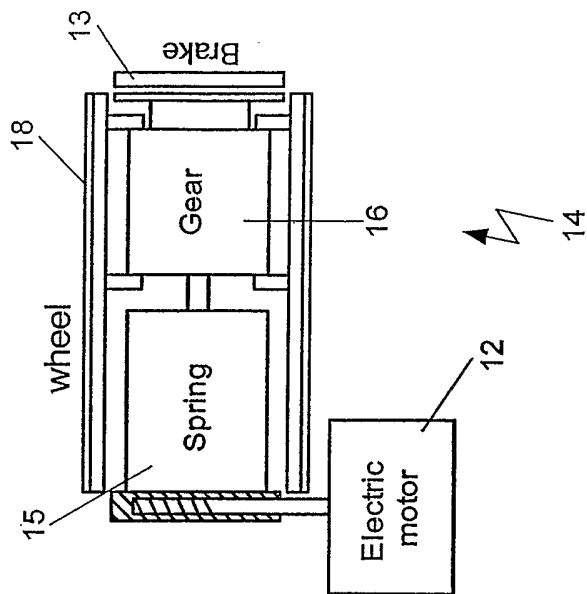
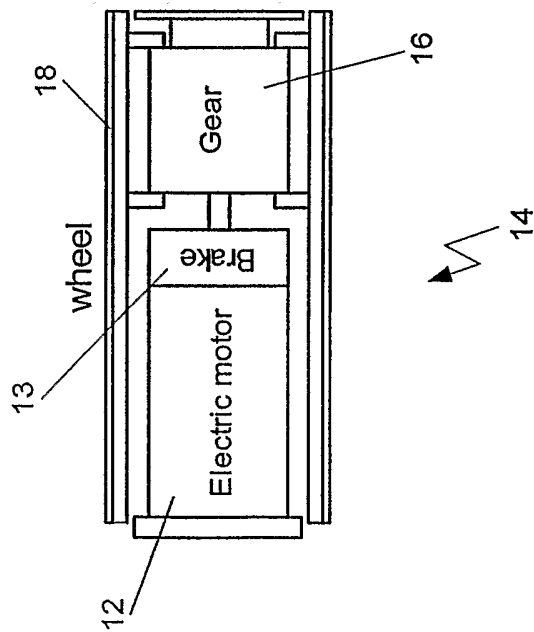


Figure 2a



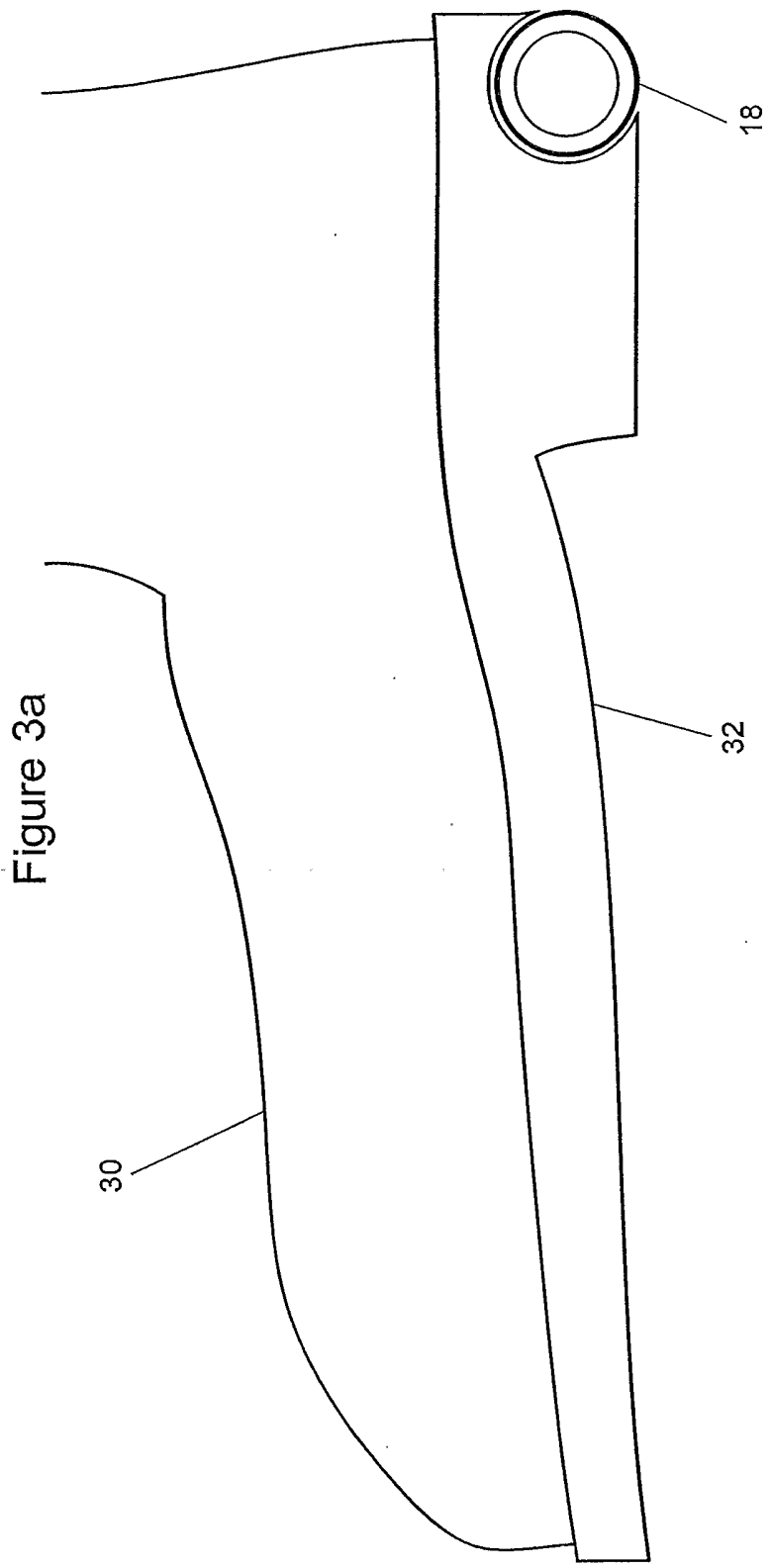
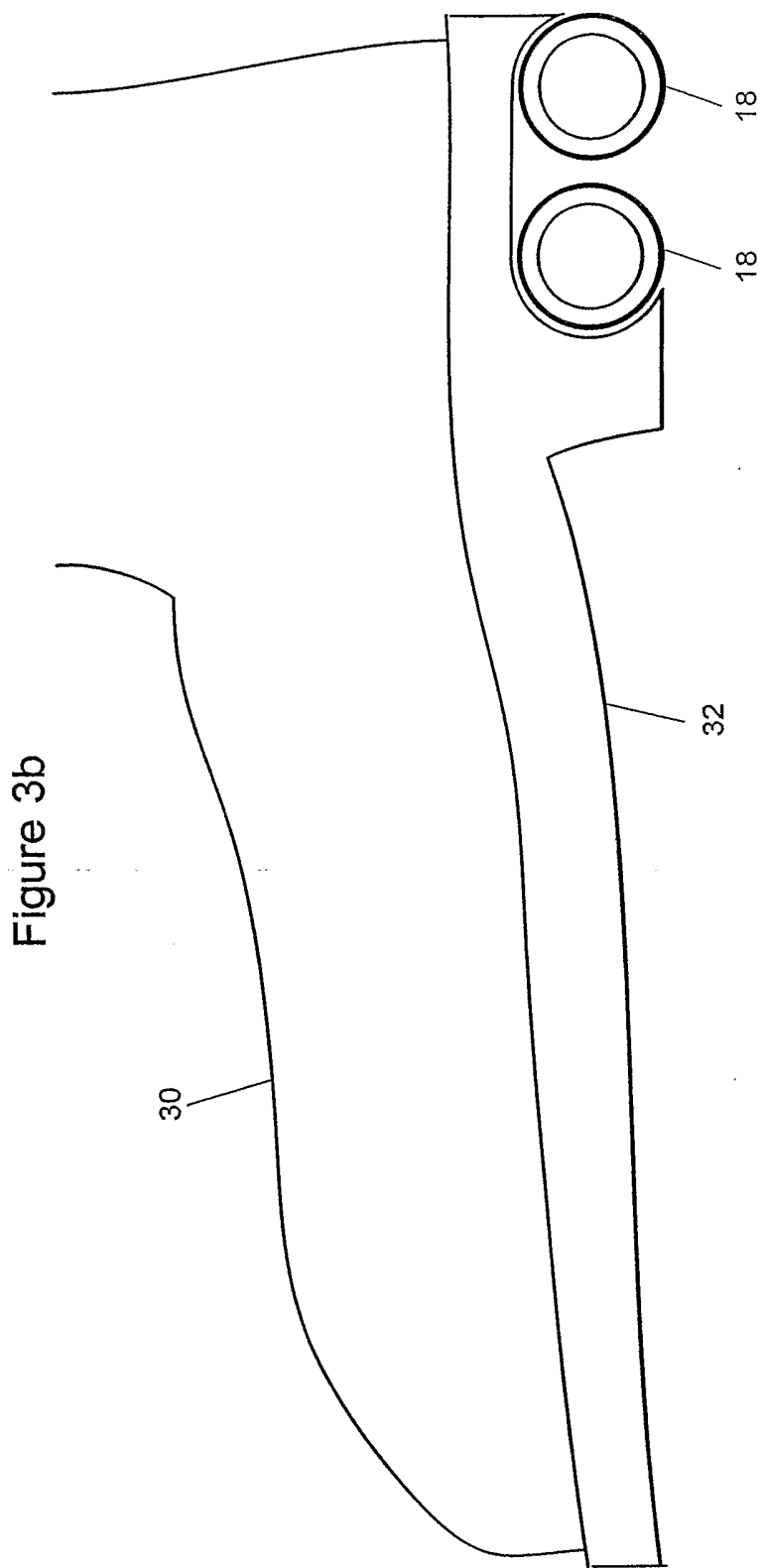
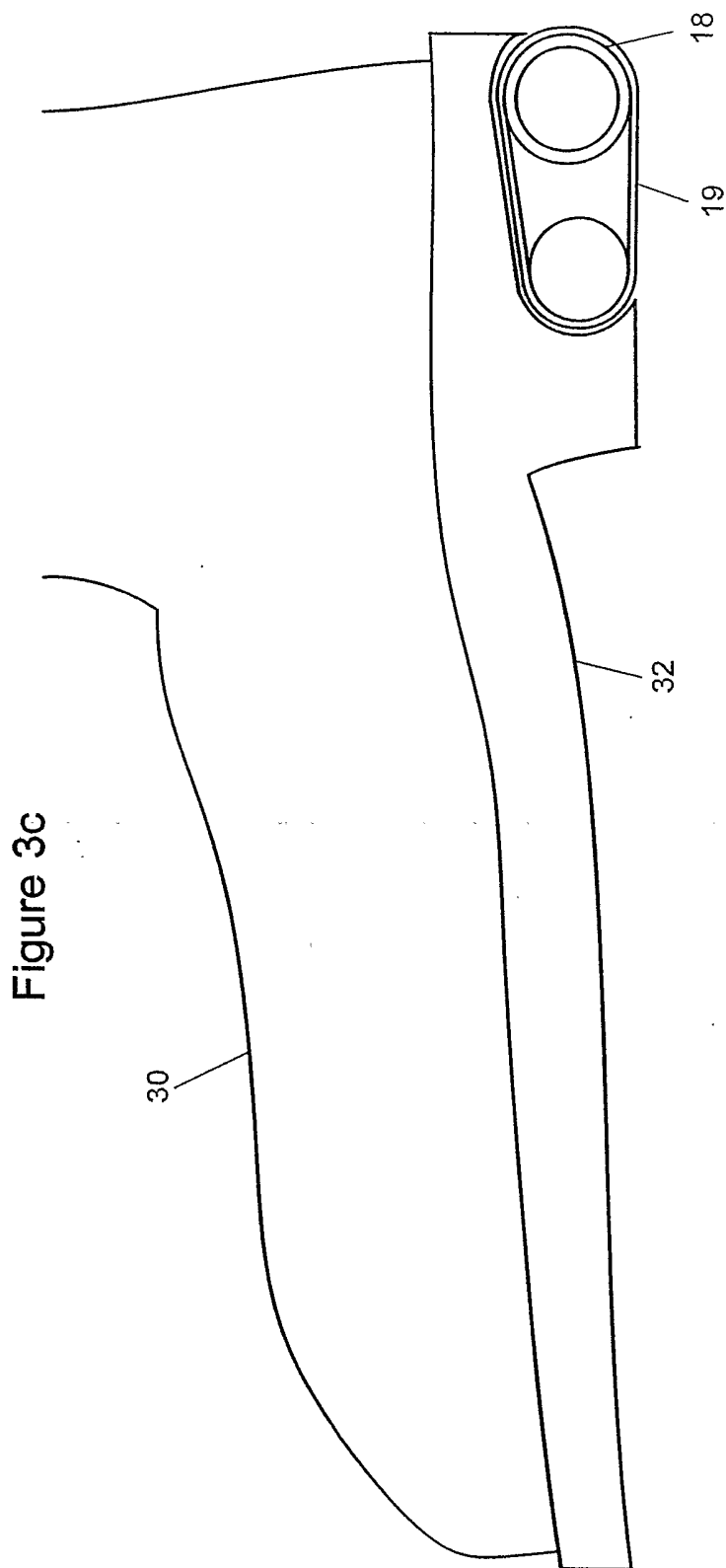


Figure 3a





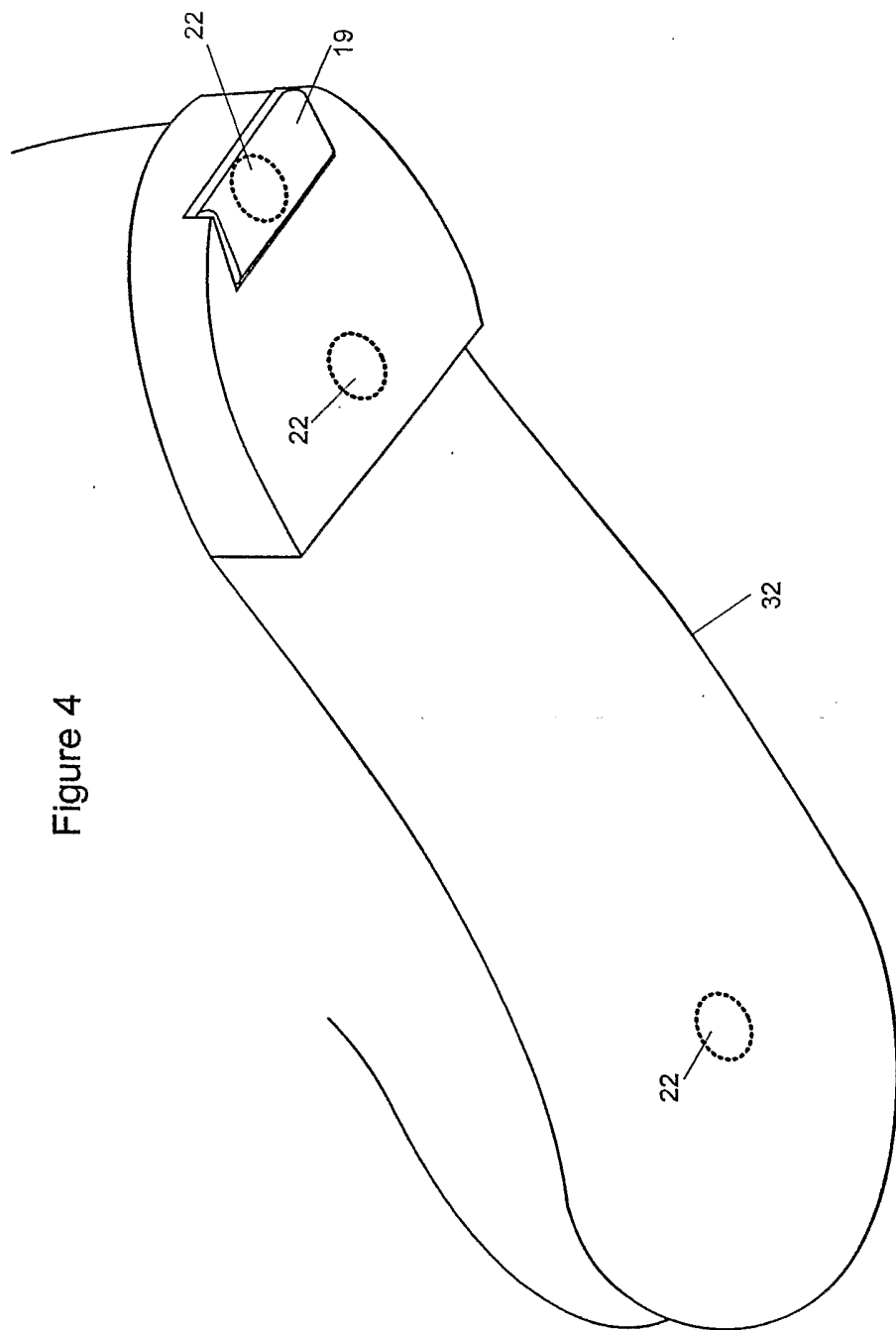


Figure 4

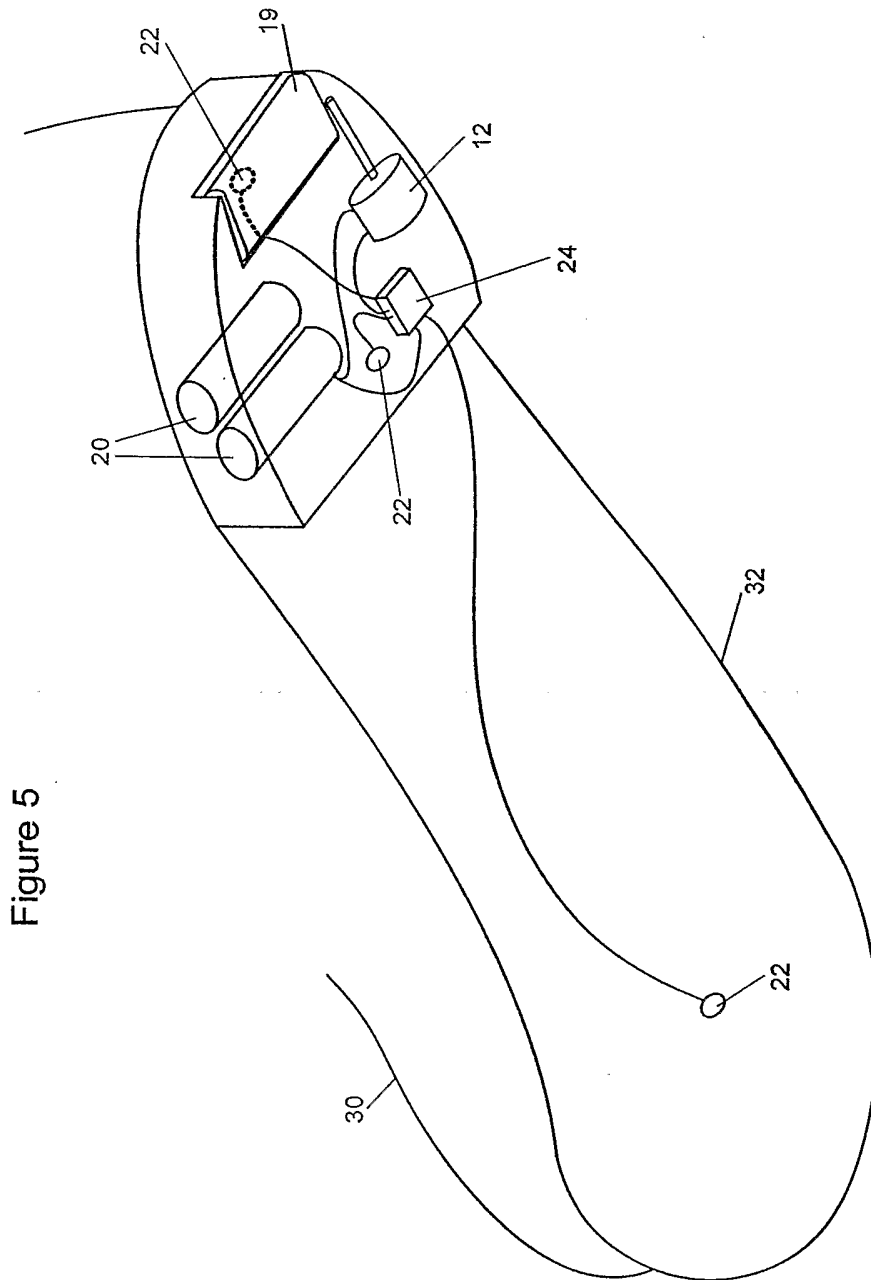


Figure 5

Figure 6c

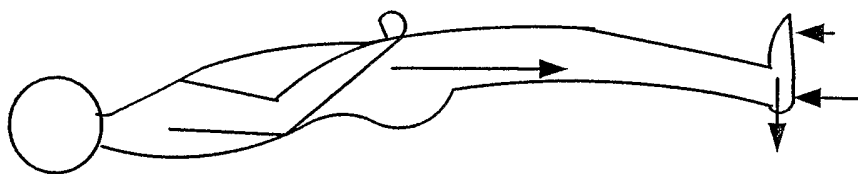


Figure 6b

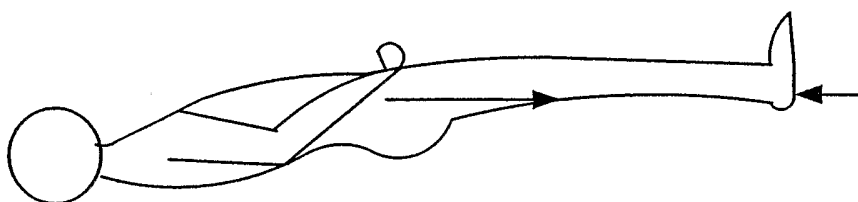


Figure 6a

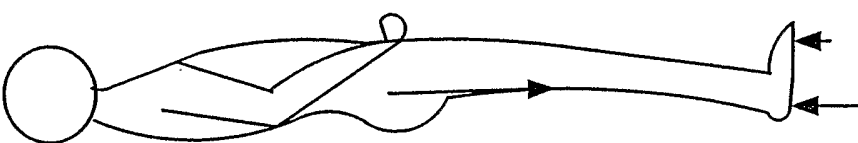


Figure 7c

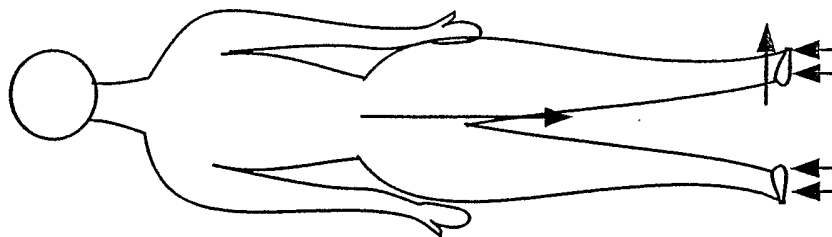


Figure 7b

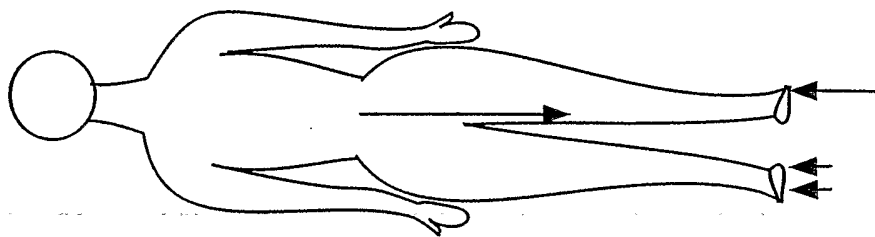


Figure 7a

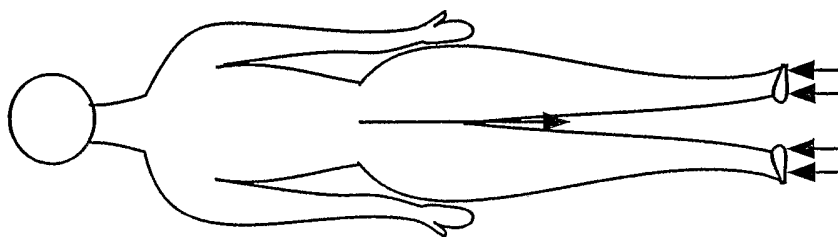


Figure 7e

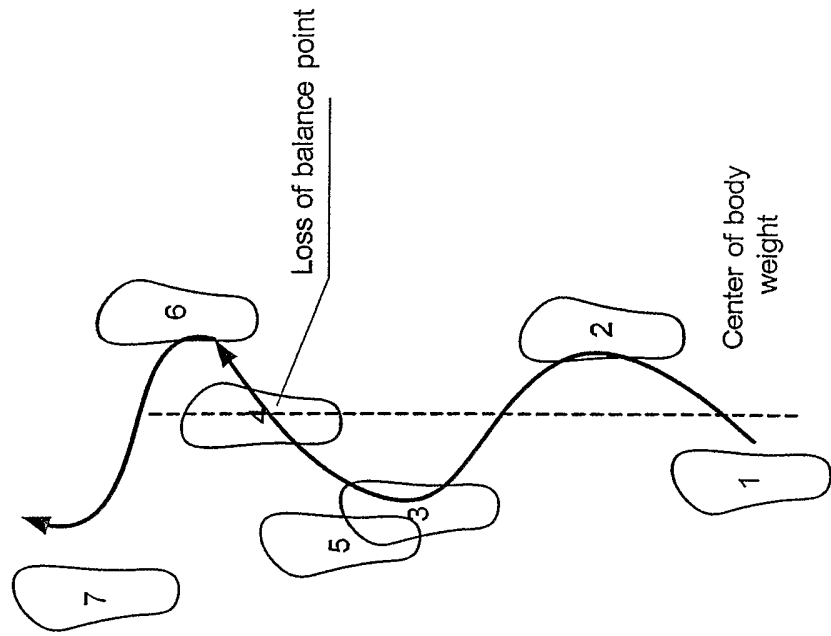


Figure 7d

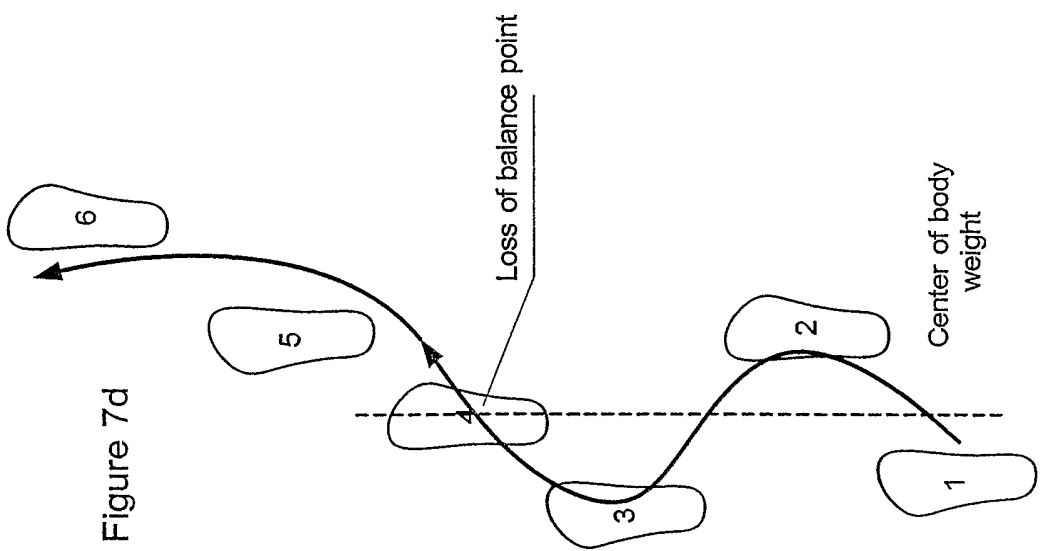
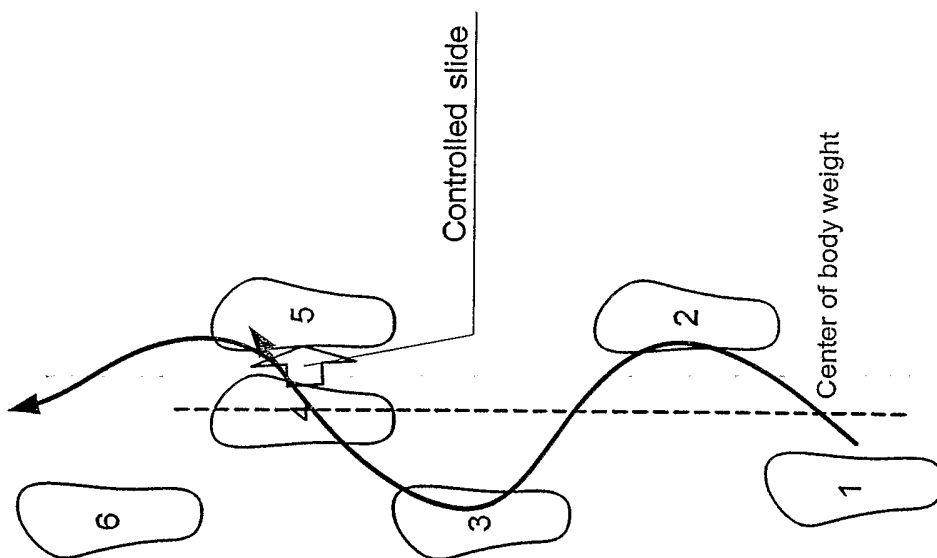


Figure 7f



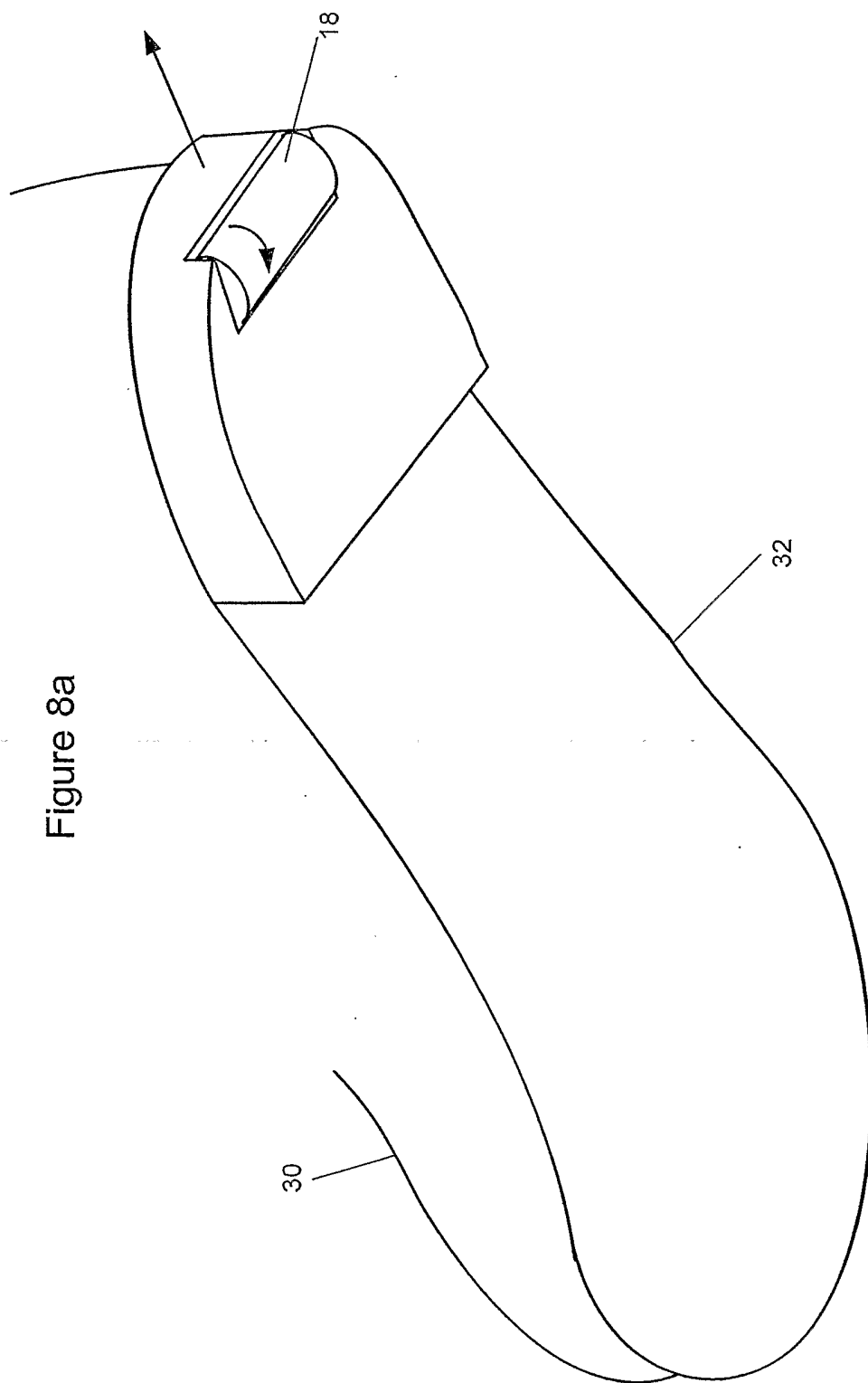


Figure 8a

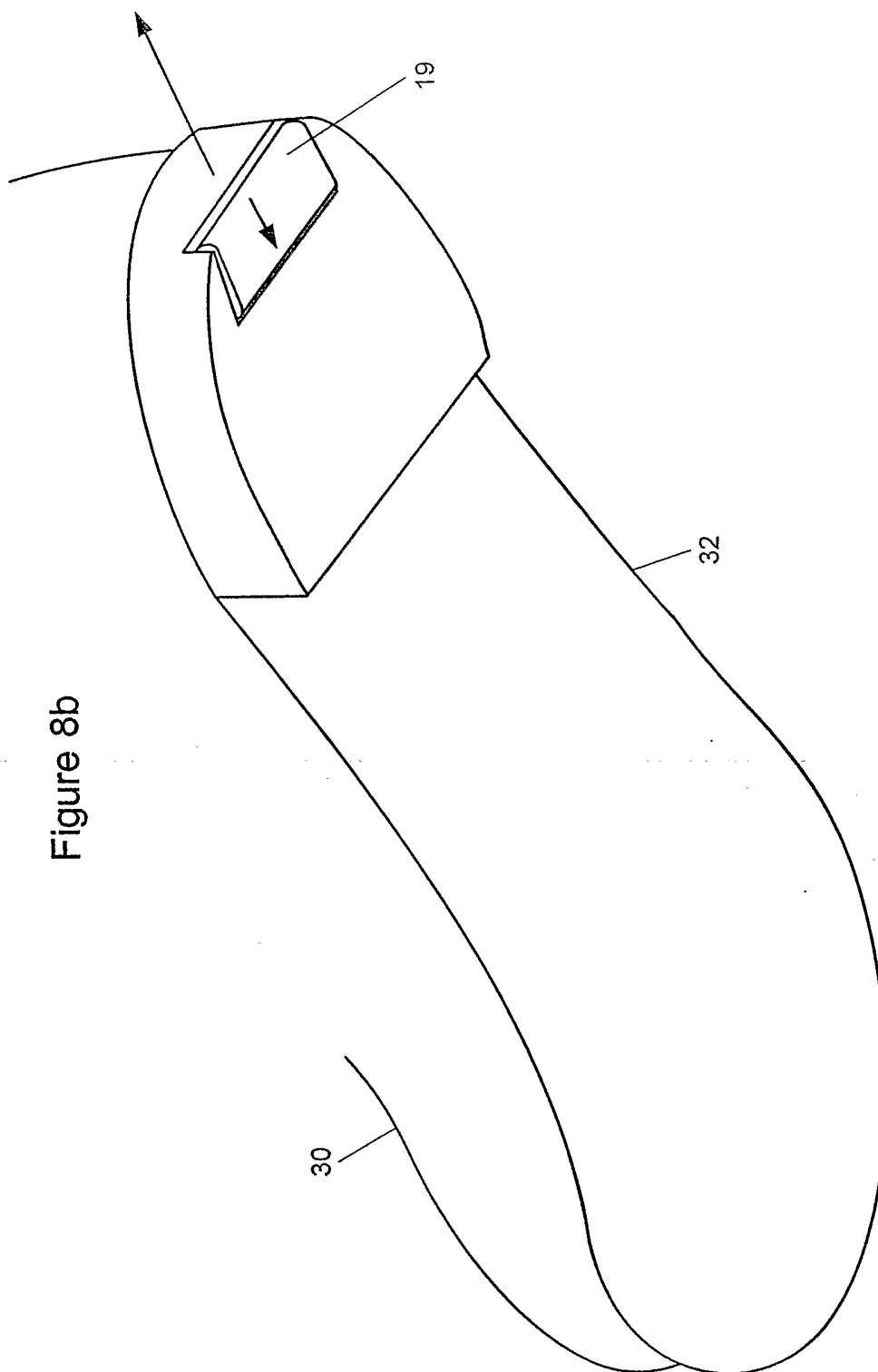


Figure 8b

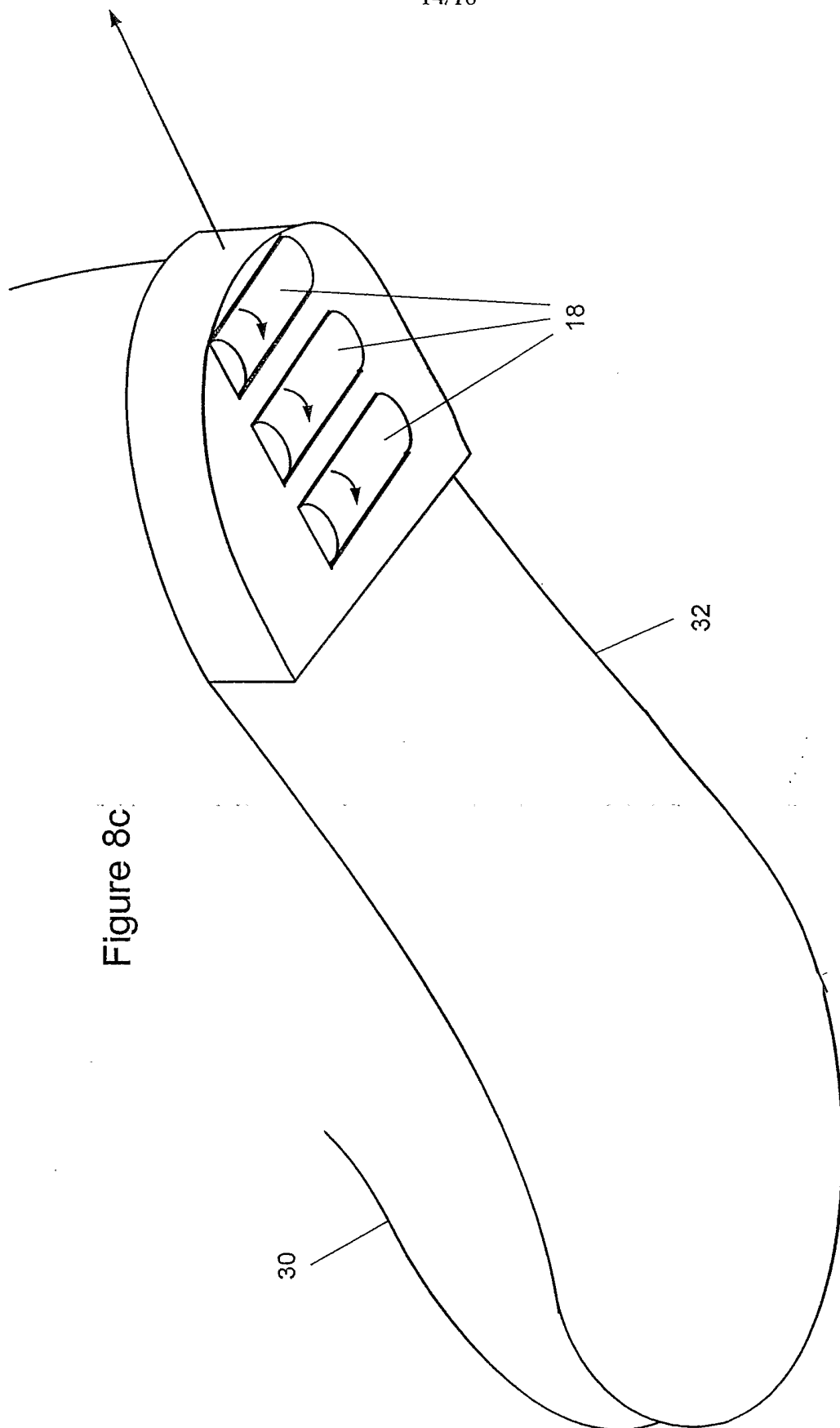


Figure 8c

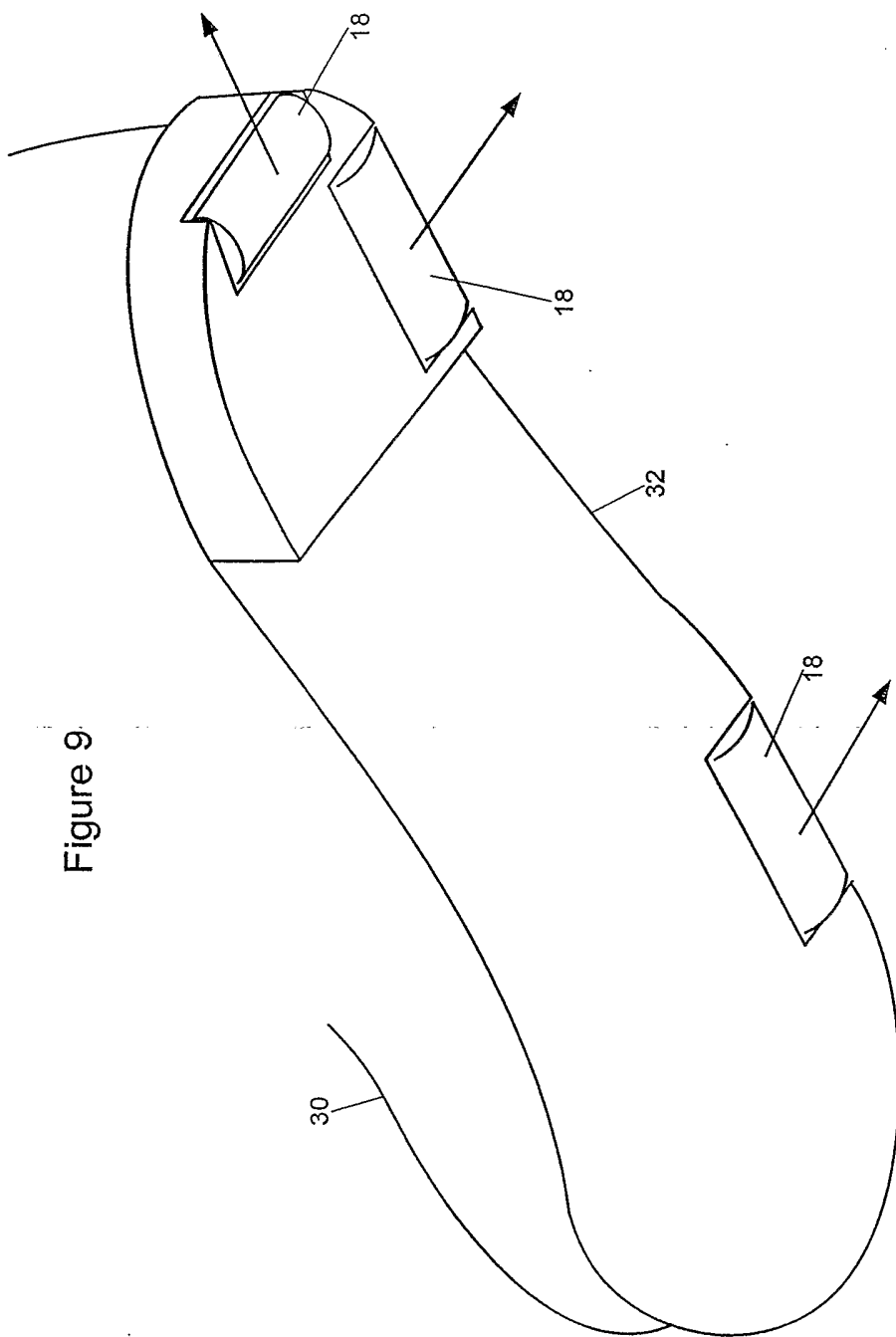


Figure 9.

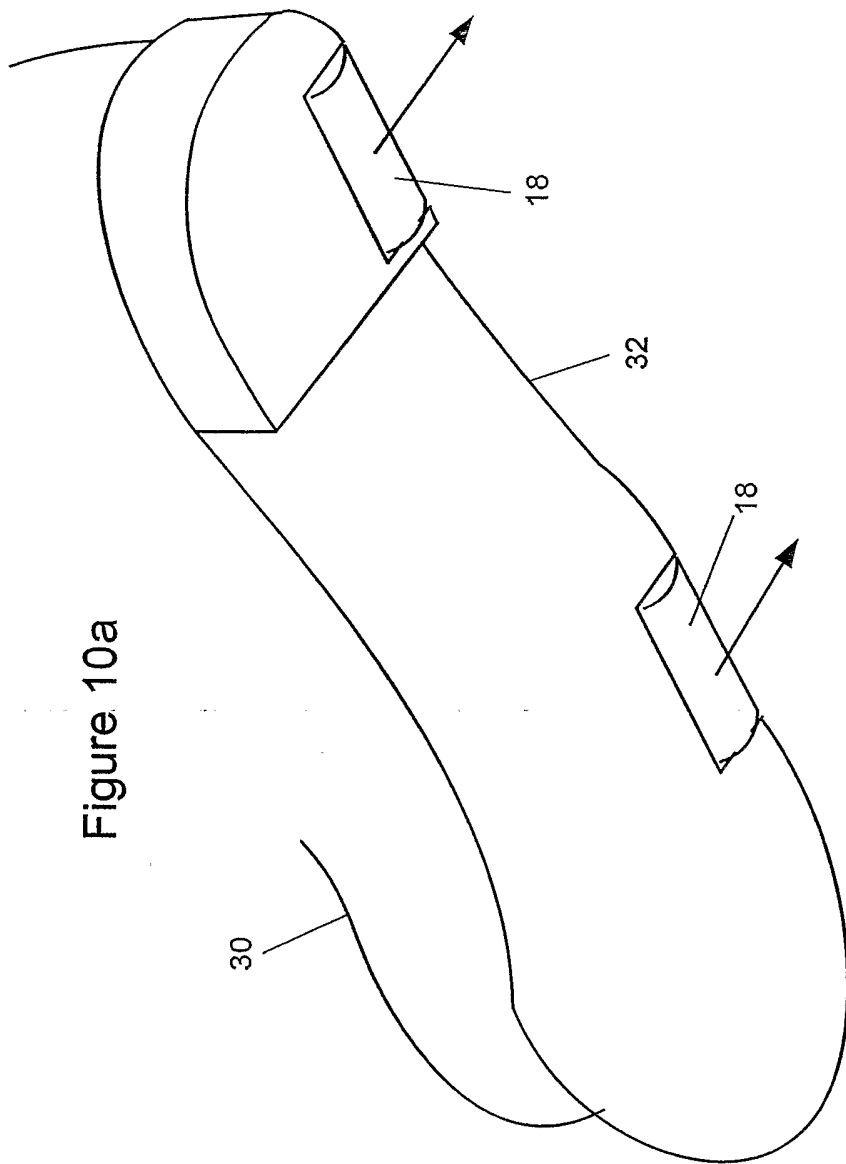


Figure 10a

Figure 10c

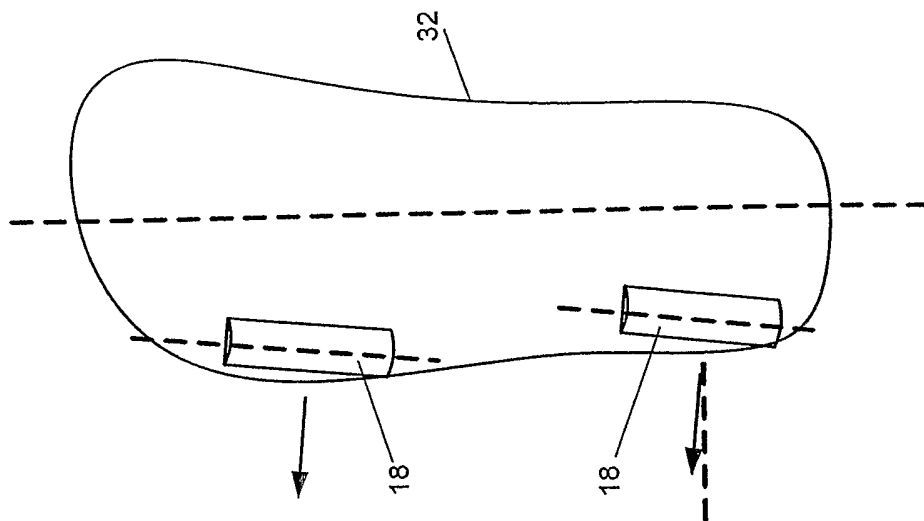


Figure 10b

