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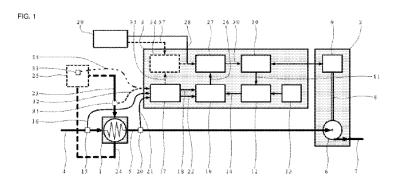
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(57) Abstract: A heat exchanger (1) controlled by the device has its primary inlet (4) of a primary heat-transport liquid mounted with a first temperature sensor (15); and its primary outlet (5) of the primary heat-transport liquid mounted with a second temperature sensor (20), where this primary outlet (5) is piped to a pump (2), comprising a pump impeller (6) connected to a motor (9), from where the primary heat-transport liquid is piped by a plumbing (7) to a heat source and from there back to the primary inlet (4). At the same time, there is a control unit (3) connected to the heat exchanger (1) and the pump (2) and contains a motor control unit (10) bi- directionally connected to the motor (9). The heat exchanger (1) also has a secondary inlet (23) for a secondary heat-transport liquid and a secondary outlet (24) ducted to a temperature zone (25) and back to the secondary inlet (23). The control unit (3) also has a temperature module (17), whose first input is connected by a communication channel (16) to an output of the temperature sensor (15), and whose second input is connected by a communication channel (21) to an output of the second temperature sensor (20). The temperature module (17) has its output (18) - a primary inlet temperature - connected to one input of a power calculation module (19), and its output (22) - a primary outlet temperature - connected to other input of the power calculation module (19). The third in put (14) of the power calculation module (19) is connected to a flow estimation module (12). The flow estimation module has one input connected to an output of a memory unit (13), and the other input connected by a bus (11) to an output of the motor control unit (10). At the same time, there is an output (26) - a heat flow estimate - of the power calculation module (19) connected to one in put of a heat flow controller (27), whose other input (28) - a heat flow demand - is connected to an output of an operator unit (29), and whose output (30) is connected to an input of the motor control unit (10).

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HEAT EXCHANGER CONTROL AND DIAGNOSTIC APPARATUS

Field of the invention

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Heat transfer control is a necessary technology for many industrial processes and is a must in residential heating. Heat from a heat source is transported through a distribution network into terminal heat exchangers, where it is delivered. Power output control of the terminal heat exchangers is then important for temperature control in adjacent processes or thermal zones. Online diagnostics plays a major role in a correct and long-term heat exchanger operation.

Background of the invention

There is a solution, described in documents EP1752852B1, EP2778546A1, US5443207A, US5622221A, US4629116, US20100163221, US7648347B2, where there is a pump connected to a heat exchanger. A liquid mass flow through the pump is controlled directly by a temperature difference between either a heat-transfer liquid temperature or a thermal zone temperature and their respective setpoints. This solution uses only one temperature - the heat-transfer liquid of the thermal zone temperature. A disadvantage of this solution is the fact that a power output of the heat exchanger is not independent of inlet stream temperature changes. This solution does not yield a heat delivery control independent of temperature changes on the heat-transport liquid entering a heat exchanger.

An actual absolute heat exchanger power (a heat flow between primary and secondary heat-transfer liquid) is calculated from an actual volumetric flow of at least one heat-transport liquid and its temperature difference across the heat exchanger. There is a solution US20140222218, where there is a temperature sensor mounted on a primary stream inlet and outlet, and there is a flowmeter measuring flow rate of the primary stream. These sensor data are communicated to a control unit, where an actual absolute power is calculated. The flow rate in this solution is regulated by a motorized valve controlled by the control unit. The disadvantage of this solution is the necessity to use a flow meter to measure the flow rate. The flow meter usage dramatically increases the price of such a device and reduces reliability. This solution uses inlet and outlet primary stream temperature sensors and a flow meter.

The actual volumetric flow rate may also be inferred from an operation conditions of a pump; this solution is described for example in US8714934. The solution uses pump revolutions reading, pump electric power use, and a temperature sensor mounted to a pump motor stator coil to infer the flow rate. These sensor data are communicated to a microprocessor which,

using previously stored pump power characteristics, calculates the actual flow rate through the pump. This method had, however, been published before the US8714934 priority date (2 Nov. 2007) in the article Ganapathy, V. "Check pump performance from motor data." CHEMICAL ENGINEERING 93.19 (1986): 91-92. The referred patent for this solution also does not cover an independent heat flow control.

A system of runtime heat exchanger diagnostics is known, for example, from US5615733. Here the heat exchanger is fitted with temperature sensors on an inlet and outlet of a hot stream, inlet and outlet of a cold stream and there is a flow meter mounted on the hot stream. These sensor data are communicated to a microprocessor, which calculates an overall heat exchange coefficient of the heat exchanger. The calculated heat exchange coefficient is then used to calculate a degree of fouling. A disadvantage of this solution is the need of a flowmeter.

Heat-use measuring is known, for example, from the solution US4245501. Two temperature sensors are attached to an inlet and outlet pipe of a heat exchanger, and there is a flowmeter mounted to this pipe. An analog electronic computation device then calculates an actual heat-use from a temperature difference across the heating terminal and a actual flow rate. A disadvantage of this solution is the need to use a flowmeter. There is also a solution US 2013/0259083 A1, which uses the same temperature measurements as the latter and an ultrasonic flowmeter. Sensor data are communicated to a microprocessor, and the actual heat-use is calculated there. A disadvantage of this solution is the utilization of a flowmeter.

20 Summary of the invention

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The new invention comprises a device and a method of a heat exchange control of heat exchangers of, for example, a water-to-air type and a system of diagnostics of such heat exchangers.

In this solution, there is a first temperature sensor mounted to an inlet of a primary stream of a heat exchanger and a second temperature sensor mounted to an outlet of the primary stream from the heat exchanger. Primary outlet is fastened to a pump impeller housing, connected to an electric motor, which is from the other end connected by piping to a heat source, from where the pipes are connected back to the heat exchanger primary inlet closing the primary circuit. The pump, comprising an impeller and motor, is appended with a control unit. The control unit contains a motor control unit connected bi-directionally with the pump motor. Simultaneously, the heat exchanger has a secondary inlet to where a secondary heat-transport liquid enters the

heat exchanger and a secondary outlet where it leaves to go to a thermal zone, from where it is ducted back to the secondary inlet. The key difference of the new device is that the control unit contains a temperature module whose first input is connected by the first communication channel with the output of the first temperature sensor and whose second input is connected by the second communication channel to the output of the second temperature sensor. Temperature module has primary inlet temperature output connected the first input of a power calculation module and has the primary outlet temperature output connected to the second input of the power calculation module. The third input to the power calculation module is connected to the flow estimation module. The flow estimation module has one input connected to the output of a memory unit and the other input with an output of a motor control unit. The output of the power calculation module — the heat flow estimate — is connected to one input of a heat flow controller whose other input — the heat flow demand — is connected to an output of an operator unit. The heat flow controller output is connected with the motor control unit sending a motor speed setting.

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In one advantageous implementation, there is a third temperature sensor mounted to the secondary inlet of the heat exchanger and it the sensor data are sent through a third communication channel which connects the sensor to the third input of the temperature module in the control unit. The temperature module has its zone temperature output connected to one input of a temperature controller. The temperature controller has its other input – the temperature setpoint – connected to the second output of the operator unit and its output is connected to the heat flow demand input of the heat flow controller.

In other advantageous implementation, there is the third sensor on the secondary heat exchanger inlet replaced with a fourth sensor placed in the thermal zone. The data from the fourth temperature sensor and sent through a fourth communication channel to the third input of the temperature module of the control unit.

The control unit can be augmented by a diagnostics module, whose first input is connected to the primary inlet temperature output of the temperature module and whose second input is connected to the zone temperature output of the temperature module and whose third input is connected to the heat flow estimate output of the power calculation module. The output of the diagnostics module sending out diagnostic information is connected by a communication channel to the operator unit.

The control unit can also be augmented by a heat-use module, whose first input is connected to the heat flow estimate output of the power calculation module and whose output with the heatuse information is connected to the operator unit.

The advantage of the described solution is that the absolute heat flow within the heat exchanger is regulated independently of changes in the primary circuit liquid pressure, independently of primary inlet temperature changes and further independently of secondary inlet temperature changes and the secondary volumetric flow. If the device is used to control the thermal zone temperature, then the disturbances, mentioned above, do not propagate to the temperature of the zone. This mechanism enables for better zone temperature control quality.

The next advantage is the possibility to use the diagnostics module and get run-time diagnostic information. That enables for an early alert of a degrading efficiency or a malfunction of the heat exchanger. Maintenance or repair can be therefore done without any unnecessary delay.

The next advantage is the possibility to utilize the heat-use module that provides information about the heat usage during a certain period. It is beneficial in, for example, energy billing between consumers connected to one common heat supply.

Brief description of the drawings

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- The particular examples of the technical solution are schematically depicted in the enclosed figures.
 - FIG. 1 shows a scheme of the connections between the pump, heat exchanger and the control unit with a temperature sensor mounting positions marked, and with an interconnection of the module allowing for heat flow control and zone temperature control.
- 25 FIG. 2 shows the extension of the control unit by the diagnostics module.
 - FIG. 3 shows the extension of the control unit by the heat-use module.
 - FIG. 4 shows flow-to-power characteristics of a pump.

The figures show particular examples of the technical solution and by no means limit the protection given by the definition.

Detailed description of the invention

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The device depicted in FIG.1 comprises the heat exchanger $\underline{1}$, the pump $\underline{2}$ and the control unit $\underline{3}$. The heat exchanger $\underline{1}$ has the primary inlet $\underline{4}$ of the primary heat-transport liquid having the first temperature sensor $\underline{15}$ mounted on and the primary outlet $\underline{5}$, where the primary heat-transport liquid leaves, with the second temperature sensor $\underline{20}$ mounted on. The primary outlet $\underline{5}$ is piped into the pump impeller housing $\underline{6}$, connected to the motor $\underline{9}$, from where it is piped by plumbing $\underline{7}$ to the heat source and back to the primary inlet $\underline{4}$. The heat exchanger $\underline{1}$ also has a secondary inlet $\underline{23}$ of the secondary heat-transport liquid and secondary outlet $\underline{24}$ connected through the thermal zone $\underline{25}$ back to the secondary inlet $\underline{23}$.

The control unit $\underline{3}$ is connected to the heat exchanger $\underline{1}$ and the pump $\underline{2}$. The control unit includes a temperature module $\underline{17}$, whose first input is connected by the first communication channel $\underline{16}$ to the output of the first temperature sensor $\underline{15}$, and whose second input is connected by the communication channel $\underline{21}$ to the output of the second temperature sensor. The temperature module $\underline{17}$ has its primary inlet temperature output $\underline{18}$ connected to the one input of the power calculation module $\underline{19}$ and its primary outlet output $\underline{22}$ connected to other input of the power calculation module $\underline{19}$. The last input $\underline{14}$ of the power calculation module $\underline{19}$ is connected to the output of the flow estimation module $\underline{12}$ is by one of its inputs connected to the output of the memory unit $\underline{13}$ and by other of its inputs connected, through a bus $\underline{11}$, to the output of the motor control unit $\underline{10}$. The control unit $\underline{10}$, which is bi-directionally connected to the motor $\underline{9}$ of the pump $\underline{2}$. The heat flow estimate output $\underline{26}$ of the power calculation module $\underline{19}$ is connected to the input of the heat flow controller $\underline{27}$, the other input of which – the heat flow demand $\underline{28}$ – is connected to the first output of the motor control unit $\underline{10}$. The output $\underline{30}$ of the heat flow controller $\underline{27}$ is connected to the input of the motor control unit $\underline{10}$.

The primary heat-transport liquid enters the heat exchanger $\underline{1}$ by the primary inlet $\underline{4}$, from where it leaves through the primary outlet $\underline{5}$, which pipes it into the housing of the pump impeller $\underline{6}$, from where it is piped by the plumbing $\underline{7}$ to the heat source and back to the primary inlet $\underline{4}$; this completes the primary circuit. The primary liquid is pumped through the primary circuit by the pump impeller $\underline{6}$ that is by a force link $\underline{8}$ driven by the motor $\underline{9}$. Electric current through the coils of the motor $\underline{9}$ is controlled by the motor control unit $\underline{10}$. The actual current value, driving

electric source voltage and motor revolutions are communicated from the motor control unit $\underline{10}$ by the bus $\underline{11}$ into the flow estimation module $\underline{12}$. The flow estimation module $\underline{12}$ calculates the estimate of the flow through the primary circuit from information from the bus $\underline{11}$ and the flow-power characteristics, depicted in FIG. 4 and stored in the memory unit $\underline{13}$, and sends the information to the third input $\underline{14}$ of the power calculation module $\underline{19}$.

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The memory module $\underline{13}$ stores the flow-power characteristics of the pump $\underline{2}$ for any admissible revolutions of the pump impeller $\underline{6}$ in the revolutions range of the pump $\underline{2}$.

The primary inlet temperature sensor $\underline{15}$ mounted to the primary inlet $\underline{4}$ sends the temperature information through the first communication channel $\underline{16}$, by cable or wirelessly, to the temperature module $\underline{17}$, which transforms the information into the primary inlet temperature $\underline{18}$ that is further communicated to the power calculation module $\underline{19}$. The primary outlet temperature sensor $\underline{20}$ is mounted on the primary outlet $\underline{5}$ and sends its temperature information through the communication channel $\underline{21}$, by cable or wirelessly, to the temperature module $\underline{17}$. The temperature module $\underline{17}$ transforms the information into the primary outlet temperature $\underline{22}$ which is further communicated to the power calculation module $\underline{19}$.

The secondary heat-transport liquid enters the heat exchanger $\underline{1}$ through the secondary inlet $\underline{23}$. It exchanges heat with the primary heat-transport liquid and is outputted through the secondary outlet $\underline{24}$, from where it is ducted to the thermal zone $\underline{25}$ and ducted back to the secondary inlet $\underline{23}$.

The power calculation module <u>19</u> calculates the actual estimated heat flow between the primary and secondary liquid in the heat exchanger <u>1</u>. The heat flow estimate is communicated by the heat flow estimate output <u>26</u> to the heat flow controller <u>27</u>. Heat flow controller <u>27</u> has its second input – the heat flow demand <u>28</u> – connected to the first output of the operator unit <u>29</u>. Heat flow controller <u>27</u> regulates by its output <u>30</u> the motor control unit <u>10</u>, and consequently the pump impeller <u>6</u> revolutions, so that the heat flow estimate <u>26</u> asymptotically reaches the heat flow demand <u>28</u>.

Alternatively, there may be a third temperature sensor 31 mounted to the secondary inlet 23. This third temperature sensor 31 sends its temperature information through the third communication channel 32, by cable or wirelessly, to the third input of the temperature module 17. The temperature module 17 transforms the information into a zone temperature 35 that is communicated to the temperature controller 36. The second input of the temperature controller

36 – the temperature setpoint 37 – is connected to the second output of the operator unit 29. The output of the temperature controller 36 is connected to the second input – the heat flow demand 28 – of the heat flow controller 27.

The zone temperature <u>35</u> can be alternatively obtained from the fourth temperature sensor <u>33</u> placed in the thermal zone <u>25</u>. The sensor <u>35</u> sends its temperature information through the fourth communication channel <u>34</u>, by cable or wirelessly, to the temperature module <u>17</u>. The fourth communication channel <u>34</u> replaces the channel <u>32</u> in its connection to the third input to the temperature module <u>17</u>.

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The temperature controller $\underline{36}$ controls the heat demand input of the heat flow controller in such a way that the zone temperature $\underline{35}$ asymptotically reaches the temperature setpoint $\underline{37}$ communicated from the second output of the operator unit $\underline{29}$.

The augmentation of the control unit $\underline{3}$ by the heat exchanger run-time diagnostics is depicted in FIG. 2. The control unit $\underline{3}$ includes the diagnostics module $\underline{39}$, whose first input is connected to the primary inlet temperature output $\underline{18}$, and whose second input is connected to the zone temperature output $\underline{35}$ of the temperature module $\underline{17}$, and whose third input is connected to the heat flow estimate output $\underline{26}$ of the power calculation module $\underline{19}$. Diagnostic information is communicated through the output $\underline{39}$ to the operator unit $\underline{29}$.

The augmentation of the control unit $\underline{3}$ by the heat-use module is depicted in FIG. 3. The control unit $\underline{3}$ includes the heat-use module $\underline{41}$, whose first input is connected to the heat flow estimate output $\underline{26}$. The module calculates the actual heat use and sends it using the output $\underline{42}$ to the operator unit $\underline{29}$.

From the above mentioned it is apparent that the pump $\underline{2}$ is connected to the primary circuit near the heat exchanger $\underline{1}$. The temperature sensors $\underline{15}$, $\underline{20}$ and $\underline{31}$ or $\underline{33}$ are mounted so that they measure the temperature of the primary heat-transport unit on the inlet and outlet of the heat exchanger $\underline{1}$ and the temperature in the zone $\underline{25}$. These temperature measurements are realized either by cable temperature sensors or wireless temperature sensors. The control unit $\underline{3}$ contains a microprocessor in which there is, by an algorithm, realized the flow estimation module $\underline{12}$, memory module $\underline{13}$, power calculation module $\underline{19}$ and heat flow controller $\underline{27}$. These modules altogether with a motor control unit $\underline{10}$ ensure the heat flow control. Next microprocessor algorithm realizes the temperature controller $\underline{36}$ controlling the temperature in

the zone $\underline{25}$. Diagnostics module $\underline{39}$ and the heat-use module $\underline{41}$ are also realized algorithmically.

The control unit $\underline{3}$ further contains the motor control unit $\underline{10}$ and temperature module $\underline{17}$ which are standalone electronic units.

5 The heat flow control method is based on the heat flow equation

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$$Q_p = \dot{m}_p c_{p,p} (T_{p,\text{inlet}} - T_{p,\text{outlet}}),$$

where $Q_p[W]$ is, in steady state, the absolute heat flow from the primary liquid, $\dot{m}_p[kg/s]$ is the mass flow of the primary liquid, $c_{p,p}[J/kg\,K]$ is the mass specific heat capacity of the primary liquid and $(T_{p,\text{inlet}} - T_{p,\text{outlet}})[K]$ is the temperature difference in the primary liquid across the heat exchanger 1. The mass flow \dot{m}_p is estimated by an algorithm, realizing the flow estimation module 12, in the microprocessor of the control unit 3 from the run-time parameters of the pump 2. Specific heat capacity is a constant know the physics and the temperature difference $(T_{p,\text{inlet}} - T_{p,\text{outlet}})$ is measured by the temperature sensors 15 and 20. The power calculation module 19 calculated by the above-mentioned equation the heat flow estimate and the heat flow controller 27 then controls the mass flow so that the heat flow estimate 26 reaches the heat flow demand 28. The heat flow demand 28 is communicated from the operator unit 29 or the temperature controller 36 when it is used.

The device and the control algorithms assure that the actual heat flow in the heat exchanger 1 is, when it is physically plausible, regulated to the heat demand value independently of the pressure changes on the primary stream, the changes in the primary inlet temperature, the changes in the secondary inlet temperature and the secondary liquid volumetric flow.

The run-time diagnostics of the heat exchanger $\underline{1}$, realized in module $\underline{39}$, is based on the effectivity method (NTU) and the equation

$$Q_s = \varepsilon \dot{V}_s c_{V,s} (T_{p,inlet} - T_{s,inlet}),$$

where $Q_s[W]$ is the steady state heat flow to the secondary liquid, $\varepsilon[.]$ is the effectivity of the heat transfer, $\dot{V}_s[m^3/s]$ is the volumetric flow of the secondary liquid, $c_{V,s}[J/m^3K]$ is the volumetric specific heat capacity of the secondary liquid know from the physics and $(T_{p,inlet} - T_{s,inlet})[K]$ is the temperature difference between the primary inlet temperature and the secondary inlet temperature. The secondary inlet temperature is the zone temperature 35.

When the heat exchanger settles into a steady state, i.e. no dynamic thermal processes occur in the heat exchanger body, then the heat flow from the primary liquid equals to the heat flow to the secondary liquid $Q_p = Q_s$. Since the temperature differences are measured, the specific capacities are known constant, and the volumetric flow of the secondary liquid is considered constant - set for example by constant fan setting – the efficiency of the heat transfer in the heat exchanger 1 may be computed.

The efficiency values are stored in the memory unit <u>13</u> and analyzed in a long-term to reveal deterioration of the efficiency caused by fouling. In short-term, the efficiency may indicate a malfunction or other system changes.

The device may also act as a heat meter by use of the heat-use module <u>41</u>. The absolute actual heat flow in the heat exchanger <u>1</u> is known from the heat flow estimate <u>26</u>. Integration of the heat flow over a specified time period results in the heat-use over that period. The calculation may by for example be realized by the following equation

$$ST(t) = T_m \sum_{k=t-T_{ST}}^{t} Q_p(k),$$

where ST(t)[W] is the heat-use over the period $T_{ST}[s]$ and $T_m[s]$ is the heat flow measurement period.

Utility of the patent

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The device according to the realization described above is intended to be used to control the power of heat exchangers independently of the primary liquid pressure and temperature changes and secondary liquid temperature and flow changes. It may further be used to control a temperature in a connected thermal zone, diagnose the heat exchanger and measure heat transferred from the primary liquid to the secondary liquid.

PATENT CLAIMS

- 1. Heat exchanger control and diagnostic apparatus where a heat exchanger (1) has its primary inlet (4) of a primary heat-transport liquid mounted with a first temperature sensor (15); and its primary outlet (5) of the primary heat-transport liquid mounted with a second temperature sensor (20), where this primary outlet (5) is piped to a pump (2), comprising a pump impeller 5 (6) connected to a motor (9), from where the primary heat-transport liquid is piped by a plumbing (7) to a heat source and from there back to the primary inlet (4); where at the same time there is a control unit (3) connected to the heat exchanger (1) and the pump (2) and contains a motor control unit (10) bi-directionally connected to the motor (9); where at the same time 10 the heat exchanger (1) has a secondary inlet (23) for a secondary heat-transport liquid and a secondary outlet (24) ducted to a temperature zone (25) and back to the secondary inlet (23), wherein the improvement comprises the control unit (3) augmented by a temperature module (17), whose first input is connected by a communication channel (16) to an output of the temperature sensor (15), and whose second input is connected by a communication channel (21) to an output of the second temperature sensor (20); where at the same time the temperature 15 module (17) has its output (18) – a primary inlet temperature – connected to one input of a power calculation module (19), and an output (22) – a primary outlet temperature – connected to other input of the power calculation module (19), whose third input (14) is connected to a flow estimation module (12), whose one input is connected to an output of a memory unit (13), and whose other input is connected by a bus (11) to an output of the motor control unit (10); 20 where at the same time an output (26) – a heat flow estimate – of the power calculation module (19) is connected to one input of a heat flow controller (27), whose other input (28) – a heat flow demand – is connected to an output of an operator unit (29), and whose output (30) is connected to an input of the motor control unit (10).
- 252. The apparatus of Claim 1, **further comprising** a third temperature sensor mounted to the heat exchanger secondary inlet (23), which is connected by a communication channel (32) to a third input of the temperature module (17), which has an output (35) a zone temperature connected to one input of a temperature controller (36), whose other input (37) a temperature setpoint is connected to a second output of the operator unit (29) and whose output is connected to the second input (28) the heat demand of the heat flow controller (27).
 - 3. The apparatus of Claim 1, **further comprising** a fourth temperature sensor (33) placed in the thermal zone (25) connected by a communication channel (34) to the third input of the temperature module (17), which has an output (35) a zone temperature connected to one

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- input of a temperature controller (36), whose other input (37) a temperature setpoint is connected to a second output of the operator unit (29) and whose output is connected to the second input (28) the heat demand of the heat flow controller (27).
- 4. The apparatus as in any of Claims 2 or 3, **further comprising** the control unit (3) extended by a diagnostics module (39), whose first input is connected to the output (18) the primary inlet temperature, and whose second input is connected to the output (35) the zone temperature of the temperature module (17), and whose third input is connected to the output (26) the heat flow estimate, and whose output (40) diagnostic information is connected to the operator unit (29).
- 105. The apparatus as in any of the preceding claims **in which** the control unit (3) is extended by a heat-use module (41), whose first input is connected to the output (26) the heat flow estimate, and whose output (42) a heat-use value is connected to the operator unit (29).

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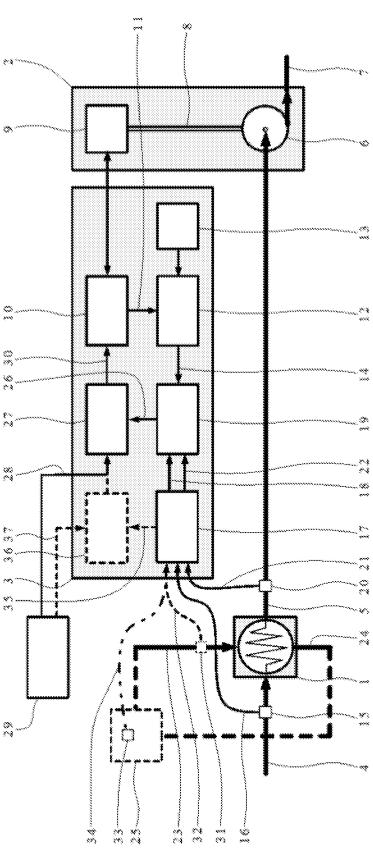


FIG. 1

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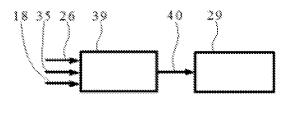


FIG. 2

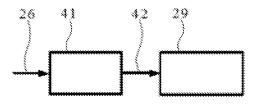


FIG. 3

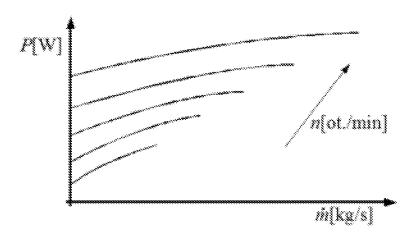


FIG. 4

INTERNATIONAL SEARCH REPORT

International application No PCT/CZ2016/050018

A. CLASSIFICATION OF SUBJECT MATTER INV. F24D19/10 G05D23/19 ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

F24D G05D

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	WO 2005/106375 A1 (SIEMENS AG [DE]; KIRCHBERG KARL-HEINZ [DE]) 10 November 2005 (2005-11-10) page 4, paragraph 1 - page 11, paragraph 2; figure 1	1-5
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Α	DE 43 12 150 A1 (HENNEL EWALD [DE]; SCHROEDER WALTER H [DE]) 15 December 1994 (1994-12-15) the whole document	1-5

Further documents are listed in the continuation of Box C.	X See patent family annex.	
"A" document defining the general state of the art which is not considered to be of particular relevance "E" earlier application or patent but published on or after the international filing date "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "O" document referring to an oral disclosure, use, exhibition or other means "P" document published prior to the international filing date but later than the priority date claimed	"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art "&" document member of the same patent family	
Date of the actual completion of the international search	Date of mailing of the international search report	
21 October 2016	28/10/2016	
Name and mailing address of the ISA/ European Patent Office, P.B. 5818 Patentlaan 2 NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Fax: (+31-70) 340-3016	Authorized officer Hoffmann, Stéphanie	

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