

DECLARATION IN SUPPORT OF A
CONVENTION APPLICATION FOR A PATENT

In support of the Convention Application made for a
patent for an invention entitled:
Automatic Speed Changing Apparatus for Vehicle

Title of Invention

Full name(s) and
address(es) of
Declarant(s)

I/We Tetsuya Katada, President

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do solemnly and sincerely declare as follows:-

Full name(s) of
Applicant(s)

1. ~~XX~~

(or, in the case of an application by a body corporate)

1. I am/We are authorised by Kabushiki Kaisha Komatsu Seisakusho

the applicant(s) for the patent to make this declaration on
its/their behalf.

2. The basic application(s) as defined by Section 141 of the
Act was/were made

Basic Country(ies)

in Japan

Priority Date(s)

on January 29, 1988

Basic Applicant(s)

by Kabushiki Kaisha Komatsu Seisakusho

Full name(s) and
address(es) of
inventor(s)

3. ~~XX~~
~~XX~~

(or where a person other than the inventor is the applicant)

3. Masao FUKUDA

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(respectively)

is/are the actual inventor(s) of the invention and the facts upon
which the applicant(s) is/are entitled to make the application are
as follows:

Set out how Applicant(s)
derive title from actual
inventor(s) e.g. The
Applicant(s) is/are the
assignee(s) of the
invention from the
inventor(s)

assignment which took place on December 23, 1988
whereby the actual inventor assigned the invention
to the said applicant.

4. The basic application(s) referred to in paragraph 2 of this
Declaration was/were the first application(s) made in a Convention
country in respect of the invention(s) the subject of the application.

Declared at Tokyo this 28th day of August 1989
KABUSHIKI KAISHA KOMATSU SEISAKUSHO

Tetsuya Katada
Signature of Declarant(s)
Tetsuya KATADA, President

To: The Commissioner of Patents

11/81

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AUTOMATIC TRANSMISSION FOR VEHICLES

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(56) Prior Art Documents
AU 582988 71941/87 B60K 41/02
AU 591666 56993/86 B60K 41/06
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(57) Claim

1. An automatic speed changing apparatus for a vehicle including at least an actuating lever for shifting movement of said vehicle from forward movement to rearward movement and vice versa so that when said actuating lever is actuated to either of forward movement and rearward movement, a speed stage of the vehicle is automatically selected to match the movement speed of the vehicle at this time point, said automatic speed changing apparatus comprising;

switch means adapted to be actuated independently of the actuating lever and

controlling means for storing and maintaining control data on the speed stage automatically selected at this time

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point in response to actuation of said switch means to an ON side and then automatically maintaining the selected speed stage with the use of stored and maintained control data until the switch means is actuated to an OFF side.

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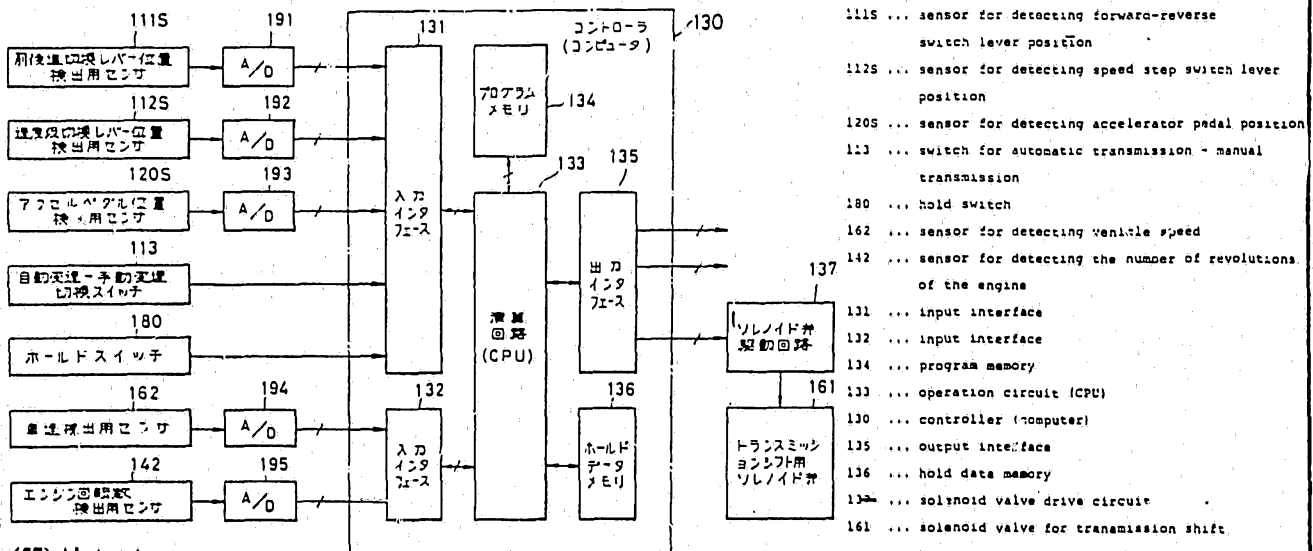
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This document contains the amendments made under Section 49 and is correct for printing

(54) Title: AUTOMATIC TRANSMISSION FOR VEHICLES

(54) 発明の名称 車両の自動変速装置



(57) Abstract

An automatic transmission for a vehicle which automatically carries out transmission control in relation to the running of the vehicle. In addition to an operation lever (111, 112) such as a select lever, a hold switch (180) is provided for informing an automatic transmission controller (130) of the need for a hold operation to automatically hold the currently selected gear position (speed step) of the transmission (160). The hold operation is executed by the controller depending upon the operation of the hold switch. When the forward-reverse switching is effected after the hold switch is operated, furthermore, the transmission at the time of start is once switched (shifted) to the second speed step for, bly. As the desired speed step that is held is reached accompanying the rise of the vehicle speed, this speed step is automatically held as a result of the hold operation. Therefore, even vehicles for construction machinery such as wheel loaders are permitted to execute the operation efficiently and smoothly.

(57) 要約

車両走行に関する変速制御を自動的に行う車両の自動変速装置であって、ここでは特に、セレクトレバー等の操作レバー（１１１、１１２）とは別途に、自動変速装置コントローラ（１３０）に対してホールド処理、すなわちトランスミッション（１６０）のその時点で選択されているギア位置（速度段）を自動保持する処理、の実行の要否を指定するためのホールドスイッチ（１８０）を設け、このホールドスイッチの操作に応じて、上記コントローラにホールド処理を実行させるようにしている。また更には、上記ホールドスイッチが操作された後に前進－後進の切換えが行われた場合には、その発進の際、トランスミッションを一旦強制的に２速段に切替え制御（シフトチェンジ）し、その後の車速の上昇に伴って上記ホールドされた所望の速度段に達したとき、上記ホールド処理としてこの速度段を自動保持させるようにもしている。これにより、ホイールローダ等の建設機械車両にあっても、能率良くかつ円滑に作業の遂行を図ることができるようになる。

情報としての用途のみ

PCTに基づいて公開される国際出願のパンフレット第１頁にPCT加盟国を同定するために使用されるコード

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TG トーゴ
US 米国

SPECIFICATION

AUTOMATIC SPEED CHANGING APPARATUS FOR VEHICLE

TECHNICAL FIELD

5 The present invention relates generally to an automatic speed changing apparatus for a vehicle wherein speed changing in connection with movement of the vehicle is automatically controlled and more particularly to
10 improvement of an automatic speed changing apparatus preferably employable for a transmission mounted on a tire type construction machine such as a wheel loader or the like vehicle.

BACKGROUND ART

15 Fig. 1 schematically illustrates a technical concept representing a conventional automatic speed changing apparatus which has been employed for a passenger car, a truck or the like vehicle.

20 As shown in Fig. 1, the automatic speed changing apparatus is usually constructed such that the content of actuations of a select lever device 10 and an acceleration pedal 20 is inputted into a controller 30 comprising computers 31 and 32, and a rotational speed of an engine 40,
25 a manner of turning on or off a clutch 50 and a manner of



shifting gears in a transmission 60 are controlled to match the content of actuations of the select lever device 10 and the acceleration pedal 20.

Here, the select lever device 10 is such that a select lever signal representative of the content corresponding to the actuation position is outputted in response to shifting actuation of a select lever 11 in the direction of an arrow mark F1 in the drawing. For example, when the select lever 11 is actuated to a "R (reverse)" position, a select lever signal representative of "rearward movement of a vehicle (movement of the vehicle in the rearward direction)" is outputted, when it is actuated to a "N (neutral)" position, a select lever signal representative of "parking and initiating of engine start" is outputted and when it is actuated to a "D (drive)" position, a select lever signal representative of "forward movement" is outputted from the select lever device 10. Particularly, when the select lever 11 is located at the position "D" representing "forward movement", the engine 40 (precisely speaking, an electronic governor 41 incorporated in the engine 40) and the transmission 60 (precisely speaking, a solenoid valve 61 usable for the purpose of shifting gears) are controlled via the controller 30 so that automatic speed changing is effected within the range of, e.g., second speed to fifth speed.



When the select lever 11 is actuated to a position representing "HOLD", a select lever signal representing "maintaining the gear position in the transmission 60 at this time point" is outputted from the select lever device 10. In this case, the gear position which has been selected via the solenoid valve 61 at this time point is maintained in the transmission 60. Namely, the vehicle is then caused to move while a constant speed stage which has been selected is maintained.

In addition, when the select lever 11 is actuated to the position "HOLD", actuation of the select lever 11 in the direction of an arrow mark F2 in the drawing makes it possible to perform a manual speed changing operation. If the select lever 11 is actuated in the direction of, e.g., "DOWN", a select lever signal representing "manual shift down" is outputted from the select lever device 10, whereby the transmission 60 is brought in meshing engagement with speed reduction gears. If the select lever 11 is actuated in the direction of "UP", a select lever signal representing "manual shift up" is outputted from the select lever device 10, whereby the transmission 60 is brought in meshing engagement with speed increase gears.

In connection with the select lever device 10, reference numeral 13 designates an inching switch for commanding movement of the vehicle at a very low speed by a



depressing operation without actuation of an acceleration pedal, reference numeral 14 does an "ECON (economy)" switch for commanding so-called economic movement of the vehicle by a depressing operation, reference numeral 15 does a "PWR (power)" switch for commanding so-called powerful movement of the vehicle (movement of the vehicle with high output) by a depressing operation and reference numeral 16 does a "1st (first)" switch for commanding start of movement of the vehicle at a first speed at the "D" position of the select lever 11 by a depressing operation.

Fig. 2 is a flowchart which summarily illustrates a manner of performing the aforementioned controlling operation in relation to the hold processing of the automatic speed changing apparatus (particularly, the controller 30), i.e., a processing to be performed when the select lever 11 is actuated to the "HOLD" position.

As shown in Fig. 2, with the automatic speed changing apparatus as described above, the hold processing is executed under conditions that speed changing is controlled unless the select lever 11 is actuated to the "HOLD" position and the select lever 11 is actuated by no means in the direction of the arrow mark F2 once it has been actuated to the "HOLD" position. The hold processing permits the current speed stage of the transmission 60 (which has been selected at this time point) to be maintained, as mentioned



above.

When the select lever 11 is shifted to the "R" position during the hold processing, i.e., when movement of the vehicle is shifted from F (forward movement) to R (rearward movement), the hold processing is naturally canceled, whereby automatic speed changing is performed while the "rearward movement" state is maintained, unless the select lever 11 is actuated to the "HOLD" position again.

When the select lever 11 is actuated further in the direction of the arrow mark F2 while it is actuated to the "HOLD" position, "manual speed changing" is performed in the direction of shift-down or in the direction of shift-up in correspondence to the direction of actuation of the select lever 11, as mentioned above.

Since the automatic speed changing apparatus assures that movement of the vehicle can excellently be stabilized by virtue of the hold function provided in that way and moreover fatigue of a driver (operator) can be minimized, the automatic speed changing apparatus is very significant for a passenger car, a truck or the like vehicle of which movement is comparatively few shifted from forward movement to rearward movement and vice versa but employment of the automatic speed changing apparatus is still problematical for a construction machine such as a wheel loader or the like which is designed and constructed in the form of a



vehicle having tires used therefor in the same manner as the
aforementioned vehicles.

Specifically, since a construction machine such as a
wheel loader or the like is such that its movement is often
5 shifted from F (forward movement) to R (rearward movement)
and vice versa, as will be apparent from consideration of
its utilization, employment of the automatic speed changing
apparatus for the construction machine leads to the
following malfunctions. Accordingly, a work can not be
10 conducted at a high efficiency in spite of employment of the
automatic speed changing apparatus.

1) Although the automatic speed changing apparatus can be
held at a specific speed stage suitable for conducting a
certain work, this hold state should be canceled soon (per
15 every shifting operation from F to R and vice versa).

2) Once the hold state is canceled, it is required that
movement of the vehicle is once shifted up to the preceding
speed stage and then a hold processing (representing a
processing of actuating the select lever 11 to the "HOLD"
20 position) is performed again in order that the automatic
speed changing apparatus is held at the preceding speed
stage again.

3) A holding processing to be repeatedly performed per
every shifting operation from F to R and vice versa is very
25 complicated and incorrect operation is liable to occur.



The present invention has been made with the foregoing background in mind and its object resides in providing an automatic speed changing apparatus for a vehicle in the form of a construction machine such as a wheel loader or the like which assures that a hold processing can always be executed at a high efficiency while a load to be carried by an operator (driver) is reduced.

DISCLOSURE OF THE INVENTION

According to the present invention, switch means, i.e., a hold switch for making a designation as to whether a hold processing should be executed or not is provided for a controller of the automatic speed changing apparatus independently of actuation levers in the form of a select lever or the like so that the controller executes a hold processing, i.e., a processing of automatically holding a gear position (speed stage) in the transmission which has been selected at this time point.

Consequently, once a required speed stage has been held by actuating the hold switch, movement of a vehicle can immediately be achieved in an automatic manner at the required speed stage merely by shifting movement of the vehicle from forward movement to rearward movement and vice versa. This enables an operation to be performed at a high efficiency using a construction machine such as a wheel



loader or the like vehicle.

Further, according to the present invention, in case where movement of the vehicle is shifted from forward movement to rearward movement and vice versa after the hold switch is actuated, when it is automatically shifted to the required speed stage which has been held in that way, i.e., when the vehicle starts its movement in accordance with a "hold" mode irrespective of forward movement or rearward movement, the transmission is once forcibly shifted to a second speed stage (representative of a shift change), and thereafter when movement of the vehicle reaches the required speed stage which has been held as the vehicle speed is increased, the hold processing is executed so as to automatically hold this speed stage.

Consequently, when the vehicle moves at the required speed stage after movement of the vehicle is shifted from forward movement to rearward movement and vice versa, shifting to the required speed stage can always be achieved stably and smoothly.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a view schematically illustrating by way of system diagram a conventional automatic speed changing apparatus employable for a vehicle, Fig. 2 is a flowchart illustrating performing a plurality of processings,



particularly a hold processing using the automatic speed
changing apparatus shown in Fig. 1, Fig. 3 is a perspective
view illustrating an actuating section and a section to be
controlled in the automatic speed changing apparatus for a
5 vehicle in accordance with an embodiment of the present
invention, Fig. 4 is a view schematically illustrating a
manner of arranging a variety of sensors in case where the
automatic speed changing apparatus is employed for a wheel
loader, Fig. 5 is a block diagram illustrating by way of
10 example the electrical structure of portions relating mainly
to a hold processing to be performed by the automatic speed
changing apparatus, Fig. 6 is a flowchart illustrating a
manner of performing mainly a hold processing ("hold" mode
processing") in the automatic speed changing apparatus and
15 Fig. 7 is a view schematically illustrating an automatic
speed changing apparatus in accordance with other embodiment
of the present invention in case where the present invention
is applied to the conventional apparatus (system) as shown
in Fig. 1.

BEST MODE FOR CARRYING OUT THE INVENTION

Now, the present invention will be described in detail
below with reference to the accompanying drawings,
particularly, Figs. 3 to 6 which illustrate an embodiment
25 thereof.



This embodiment will be described below on the assumption that a wheel loader is employed as a vehicle to which the present invention is applied. For the reason, an automatic speed changing apparatus according to the
5 illustrated embodiment will be described hereinafter as an apparatus for automatically controlling a speed changing operation in relation to a speed of movement of the wheel loader.

Fig. 3 is a perspective view which schematically
10 illustrates the structure of a driver seat section and objects to be controlled in a wheel loader, i.e., a transmission section to be controlled by the automatic speed changing apparatus of the present invention. In Fig. 3, numeral 101 designates a steering handle, reference numeral
15 110 does a lever device, reference numeral 111 does a forward/rearward shifting lever arranged on the lever device 110 to perform a shifting operation of shifting from F (forward movement) to R (rearward movement) of a vehicle and vice versa as represented by arrow marks in the drawing,
20 reference numeral 112 does a speed stage shifting lever likewise arranged on the lever device 110 to perform a shifting operation of shifting to a required speed stage for the vehicle as represented by arrow marks in the drawing, reference numeral 113 does an automatic speed
25 changing manual speed changing shifting lever provided at



the fore end of the speed stage shifting lever 112 to perform a shifting operation from an "automatic speed changing" mode to a "manual speed changing" mode and vice versa in response to an ON-OFF actuation of the speed stage shifting lever 112, reference numeral 120 does an acceleration pedal, reference numeral 120S does an acceleration pedal position detecting sensor for detecting a position assumed by the acceleration pedal 120, reference symbol ST does a driver's seat, reference numeral 170 does a working machine actuating lever arranged in the proximity of the driver's seat ST and reference numeral 180 does a hold switch arranged likewise in the proximity of the seat ST to issue a command to a controller (precisely speaking, a solenoid valve driving circuit) to be described later in response to the ON-OFF actuation of the speed stage shifting lever 112 as to whether the hold mode processing, i.e., a processing of automatically holding the gear position (representative of the speed stage) which has been selected at this time point by a transmission 160 as shown in Fig. 3 should be executed or not. Incidentally, reference numeral 161 designates a solenoid valve mounted on the transmission 160 to shift the gear position (speed stage) in the transmission 160. The forward movement/rearward movement shifting lever 111 is provided with a sensor 111S for detecting the current shifted position and the speed stage



shifting lever 112 is provided with a sensor 112S for detecting the current shifted position (in practice, these sensors 111S and 112S being incorporated in the lever device 110), although they are not shown in Fig. 3. Specifically,
5 the speed stage shifting lever 112 is used for both modes, i.e., "automatic speed changing" mode and "manual speed changing" mode, and in case where the speed stage shifting lever 112 is actuated to, e.g., a position "3", an automatic speed changing operation can be performed within the range
10 comprising a first speed stage, a second speed state and a third speed stage depending upon a quantity of depressing operation of the acceleration pedal 120, while in case where the speed stage shifting lever 112 is actuated to, e.g., a position "2", an automatic speed changing operation can be
15 performed within the range comprising a first speed stage and a second speed stage depending upon a quantity of depressing operation of the acceleration pedal 120. Similarly, in case where the speed stage shifting lever 112 is actuated to other position, the range in which an
20 automatic speed changing operation is performed can be set in the same manner in conformity with the aforementioned rule.

Fig. 4 schematically illustrates how essential components inclusive these various sensors and switches
25 constituting the automatic speed changing apparatus are



arranged in the wheel loader and how they are operatively associated with each other.

In Fig. 4, reference numeral 130 designates a controller, reference numeral 137 does a solenoid valve driving circuit to be controlled by the controller 130, reference numeral 140 does an engine, reference numeral 142 does an engine speed detecting sensor for detecting the current engine speed, reference numeral 150 does a clutch and reference numeral 162 does a vehicle speed detecting sensor for detecting the current speed of movement of the wheel loader. Other components and units have been already described above.

Fig. 5 illustrates a structure of the automatic speed changing apparatus by showing how the aforementioned components and units are electrically connected to each other and Fig. 6 illustrates by way of flowchart a manner of performing operations in connection with the aforementioned hold mode processing. Structure and operations of the automatic speed changing apparatus will be described below with reference to Figs. 5 and 6.

Informations on detected positions derived from the forward movement/rearward movement shifting lever position detecting sensor 111S, the speed stage shifting lever position detecting sensor 112S and the acceleration pedal position detecting sensor 120S are converted into digital

signals by A/D (analogue/digital) converters 191, 192 and 193 so that they are inputted into the controller (computer) 130. Additionally, the content of actuations of the automatic speed changing/manual speed changing shifting switches 113 and the hold switch 180 is likewise inputted into the controller 130 in the form of a binary signal. The controller 130 is operated such that these inputted signals are introduced into an arithmetic circuit (CPU) 133 via a first input interface 131.

On the other hand, detected informations derived from the vehicle speed detecting sensor 162 and the engine speed detecting sensor 142 are converted into digital signals by A/D converters 194 and 195 so that they are inputted into the controller 130. The controller 130 is operated such that these inputted signals are introduced into the arithmetic circuit 133 via a second input interface 132.

The arithmetic circuit (CPU) 133 is a circuit in which a variety of signals inputted via the input interfaces 131 and 132 in accordance with a processing program previously stored in a program memory 134 are processed as required and the solenoid valve driving circuit 137 for driving the transmission shift solenoid 161, an electronic governor (not shown) for controlling a rotational speed of the engine 140, a solenoid valve (not shown) for turning on and off the clutch 150 and other associated components are controlled so



as to match the content of actuations of the levers 111 and 112, the pedal 120 and the switches 113 and 180 executed by an operator. Control signals outputted from the arithmetic circuit 133 are transmitted via an output interface 135 to
5 respective circuit to be controlled.

A hold data memory 136 incorporated in the controller 133 is a memory in which when the hold switch 180 is shifted to an ON side, control data to be given to the solenoid valve driving circuit 137 from the arithmetic circuit 133 at
10 this time point, i.e., a speed stage command to be issued at this time point is stored. While the hold switch 180 is shifted to the ON side in that way, the subsequent controlling and processing are executed in the arithmetic circuit 133 in accordance with the manner as represented by
15 a step 5 and subsequent steps in a flowchart shown in Fig. 6.
6.

Specifically, as shown in Fig. 6, in case where the automatic speed change/manual speed change shifting switch 113 is shifted to, e.g., an OFF side so that "manual speed
20 changing" is designated, the arithmetic calculating circuit 133 makes a determination that the automatic speed changing has been designated (step 1 in Fig. 6) so that controlling and processing are executed in accordance with a hitherto known "manual speed changing" mode in response to detection
25 of an actuation position of the speed stage shifting lever



112 (step 2 in Fig. 6). In case where the hold switch 180 is shifted to the OFF side while the switch 113 is shifted to the ON side to designate "automatic speed change" (step 1 in Fig. 6), the arithmetic circuit 133 makes a determination
5 that the hold switch 180 has been shifted to the OFF side (step 3 in Fig. 6), controlling and processing are executed in accordance with "automatic speed changing" mode on the basis of the automatic speed change range designated and set by the speed stage shifting lever 112 in the above-described
10 manner in response to detection of a depressing position of the acceleration pedal 120 (step 4 in Fig. 6). However, in the case where the hold switch 180 is shifted to the ON side in that way while the switch 113 has been already shifted to the ON side, the arithmetic circuit 133 stores in the hold
15 data memory 136 control data (speed stage command) to be given to the solenoid valve driving circuit 137 at this time point and then controls the solenoid valve driving circuit 137 in conformity with control data to be later stored in the hold data memory 136. This permits a speed stage
20 selected in accordance with the current mode, i.e., "automatic speed changing" mode at this time point to be maintained in the transmission 160 (step 5 in Fig. 6).

When forward movement/rearward movement is shifted via the forward movement/rearward movement shifting lever 111
25 while such "hold" mode is maintained, the arithmetic circuit



133 makes a determination that the forward movement/rearward movement has been shifted in that way (step 6 in Fig. 6). Then, when the vehicle starts its movement (either of forward movement and rearward movement), the transmission shifting solenoid valve 161 is first controlled via the solenoid valve driving circuit 137 so that the transmission 160 is forcibly shifted and changed to a second stage (step 7 in Fig. 6). Thereafter, controlling is executed for acceleration and selection of speed stage in accordance with "automatic speed changing" mode in correspondence to an extent of depressing of the acceleration pedal 120 until a control command value to be given to the solenoid valve driving circuit 137 reaches the command value (control data) stored in the hold data memory 136 (step 8 in Fig. 6). When the control command value to be given to the solenoid valve driving circuit 137 reaches the command value stored in the hold data memory 136, the arithmetic circuit 133 makes a determination that the control command value has reached the command value stored in the hold data memory 135 and thereafter the program automatically goes to the processing at the step 5, i.e., a processing of controlling the solenoid valve driving circuit 137 in accordance with the control data (control command value) stored in the hold data memory 136. Such processing to be executed by the arithmetic circuit 133 continues until the hold switch 180



is disconnected, i.e., until the hold switch 180 is shifted to the OFF side.

Thus, with the automatic speed changing apparatus as constructed according to the embodiment, a hold processing is brought in such a state that it automatically continues in response to actuation of the hold switch 180. Thereafter, speed of the vehicle is automatically changed to the movement speed at a required speed stage which has been held in that way, when movement of the vehicle is shifted from forward movement to rearward movement and vice versa. Consequently, with the automatic speed changing apparatus of the present invention, any operation can be performed at a high efficiency with an operator's load reduced remarkably using a vehicle such as the illustrated wheel loader or the like of which movement is often shifted from forward movement to rearward movement and vice versa.

Further, with the automatic speed changing apparatus of the present invention, in case where movement of the vehicle is shifted from forward movement to rearward movement and vice versa after the hold switch 180 is actuated, shift control (shift change) is once forcibly carried out to a second speed stage, when the current speed stage is automatically shifted to a required speed stage which has been held in that way, i.e. when the vehicle starts its movement in accordance with the "hold" mode irrespective of



forward movement or rearward movement. Thereafter, when the speed stage reaches a required speed stage which has been held in that way as the vehicle speed is increased, the speed stage is automatically maintained at the above
5 required speed stage by executing the hold processing. Consequently, when vehicle movement is attained at the required speed stage after the vehicle movement is shifted from forward movement to rearward movement and vice versa, shifting to the required speed stage can always be performed
10 stably and smoothly.

Incidentally, this embodiment has been described above with respect to an automatic speed changing apparatus on the assumption that a rotational speed of the engine 140 is controlled by means of an electronic governor but the
15 present invention should not be limited only this. Alternatively, the engine may be controlled by employing other suitable method. Further, it should of course be understood that the present invention should not be limited only to the foregoing unit.

20 According to the embodiment, detection is made by the acceleration pedal position detecting sensor 120S as to whether the vehicle is held at the moving state or not but such detection can practically be made by monitoring the rotational speed of the engine 140. In case where
25 recognition is additionally made on the basis of a detection



signal generated by the engine speed detecting sensor 142, the automatic speed changing apparatus may be constructed with the acceleration pedal position detecting sensor 120S and the A/D converter 193 removed therefrom.

5 For the convenience of description, structure and operation of the automatic speed changing apparatus have been described above as to the case where the embodiment of the present invention is applied to the existent steering apparatus as well as the existent automatic speed changing
10 apparatus employable for a wheel loader or the like vehicle. However, the present invention can likewise be applied to the automatic speed changing apparatus as shown in Fig. 1. One example will be shown in Fig. 7.

Specifically, with the automatic speed changing
15 apparatus shown in Fig. 7, a select lever device 10' is a device adapted to issue a command as to one of "R (rearward movement)", "N (neutral)" and "D (forward movement)" as well as "automatic speed changing" mode or "manual speed
20 changing" mode in the same manner as the select lever device 10 in Fig. 1, when the vehicle starts its movement. A difference point from the select lever device 10 shown in Fig. 1 consists in that the select lever device 10' does not have a function of commanding a hold processing as mentioned above. A command as to whether a hold processing is
25 required or not is issued in response to actuation of a hold



switch 180 arranged separately. In the case of the select lever device 10', it is assumed that only a command for the "manual speed changing" mode is issued, when a select lever 11 is shifted to a "MANU" position (representing a manual position).

In Fig. 7, reference numeral 170 designates a working machine actuating lever as described hereinbefore. The working machine actuating lever 170 is removed from the automatic speed changing apparatus in case where the vehicle is a passenger car, a truck or the like.

In this automatic speed changing apparatus, a controller 30' has functions equal to those of the controller 30 according to the preceding embodiment shown in Fig. 5 so that when a "hold" mode is designated via the hold switch 180, a step 6 and subsequent steps as shown in Fig. 6 which represents a flowchart are repeatedly executed in the same manner as in the preceding embodiment.

Accordingly, also with the automatic speed changing apparatus shown in Fig. 7, an operation can be performed at a high efficiency with an operator's load remarkably reduced using a vehicle such as a wheel loader or the like of which movement is often shifted from forward movement to rearward movement and vice versa. When the vehicle moves at a required speed stage which has been previously held, shifting to the required speed stage can always be effected



stably and smoothly.

With respect to each of the aforementioned embodiments, a position where the hold switch 180 is located and a manner of arranging the hold switch 180 can be determined
5 arbitrarily. Provided that the position and the manner are determined such that the hold switch 180 can be actuated independently of other actuating levers, the hold switch 180 may be arranged at any position in accordance with any manner.

10 The foregoing embodiments have been described above as to the case where a computer is used as a controller and a series of controlling operations for automatic speed changing inclusive a hold processing are executed using the computer. Alternatively, the computer may, of course, be
15 constructed in the form of a so-called hardware circuit so that the same controlling operations for automatic speed changing as mentioned above are executed using the hardware circuit.

20 INDUSTRIAL APPLICABILITY

As will be apparent from the above description, according to the present invention, movement of a vehicle can immediately be achieved in any case in an automatic manner at a required speed stage which has been previously
25 determined. Thus, a work can be performed at a high



efficiency using a construction machine such as a wheel loader or the like of which movement is repeatedly shifted from forward movement to rearward movement and vice versa.

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CLAIMS

1. An automatic speed changing apparatus for a vehicle including at least an actuating lever for shifting movement of said vehicle from forward movement to rearward movement and vice versa so that when said actuating lever is actuated to either of forward movement and rearward movement, a speed stage of the vehicle is automatically selected to match the movement speed of the vehicle at this time point, said automatic speed changing apparatus comprising;

switch means adapted to be actuated independently of the actuating lever and

controlling means for storing and maintaining control data on the speed stage automatically selected at this time point in response to actuation of said switch means to an ON side and then automatically maintaining the selected speed stage with the use of stored and maintained control data until the switch means is actuated to an OFF side.

2. An automatic speed changing apparatus for a vehicle including at least an actuating lever for shifting movement of said vehicle from forward movement to rearward movement and vice versa so that when said actuating lever is actuated to either of forward movement and rearward movement, a speed stage of the vehicle is automatically selected to match the movement speed of the vehicle at this time point, said automatic speed changing apparatus comprising;



switch means adapted to be actuated independently of the actuating lever,

first controlling means for storing and holding control data on the speed stage automatically selected at this time point in response to actuation of said switch means to an ON side and then automatically maintaining the selected speed stage with the use of stored and maintained control data until the switch means is actuated to an OFF side and

second controlling means wherein when the actuating lever is shifted to other side while the switch means is shifted to the ON side, the speed stage is first forcibly controlled to a second speed stage and thereafter when the vehicle speed is accelerated, the speed stage is shifted up to a speed stage adapted to be automatically held by said first controlling means as time elapses.

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ABSTRACT

An automatic speed changing apparatus for a vehicle for automatically controlling speed change in connection with movement of the vehicle, wherein a hold switch (180) for making a designation as to whether a hold processing, i.e., a processing of automatically holding the gear position (speed stage) of a transmission (160) selected at this time point should be executed or not is provided for a controller (130) for the automatic transmission apparatus independently of actuating levers (111, 112) in the form of a select lever or the like so that the controller executes the hold processing in response to actuation of a hold switch. In case where movement of the vehicle is shifted from forward movement to rearward movement and vice versa after the hold switch is actuated, the transmission is once forcibly shifted to a second speed stage (representative of a shift change) when the vehicle starts its movement, and thereafter when the vehicle speed is increased to reach a required speed stage which has been held, the required speed stage is automatically maintained as a result of the hold processing. With this construction, the automatic speed changing apparatus permits a work to be smoothly conducted at a high efficiency for a construction machine such as a wheel loader or the like vehicle.



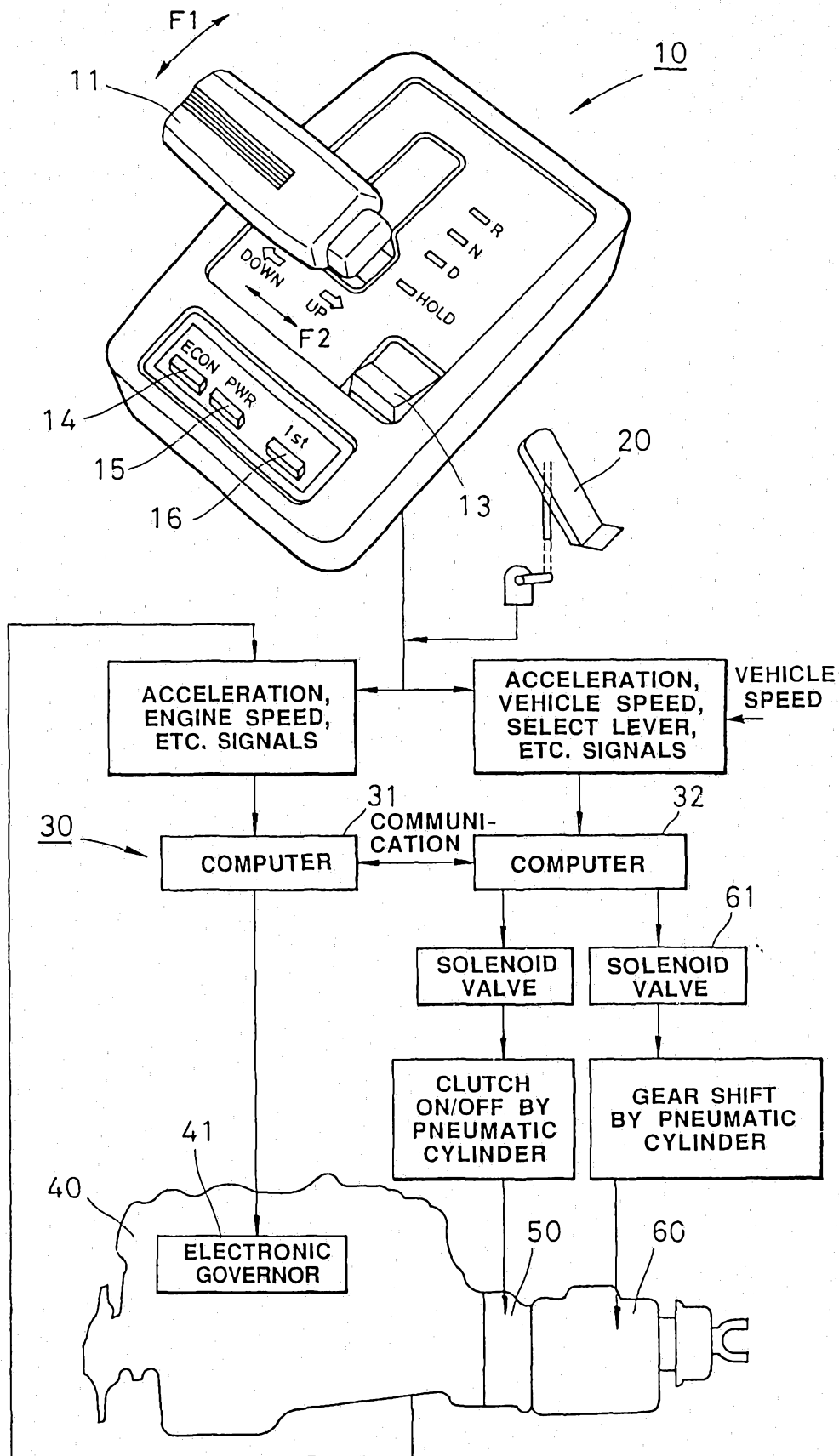
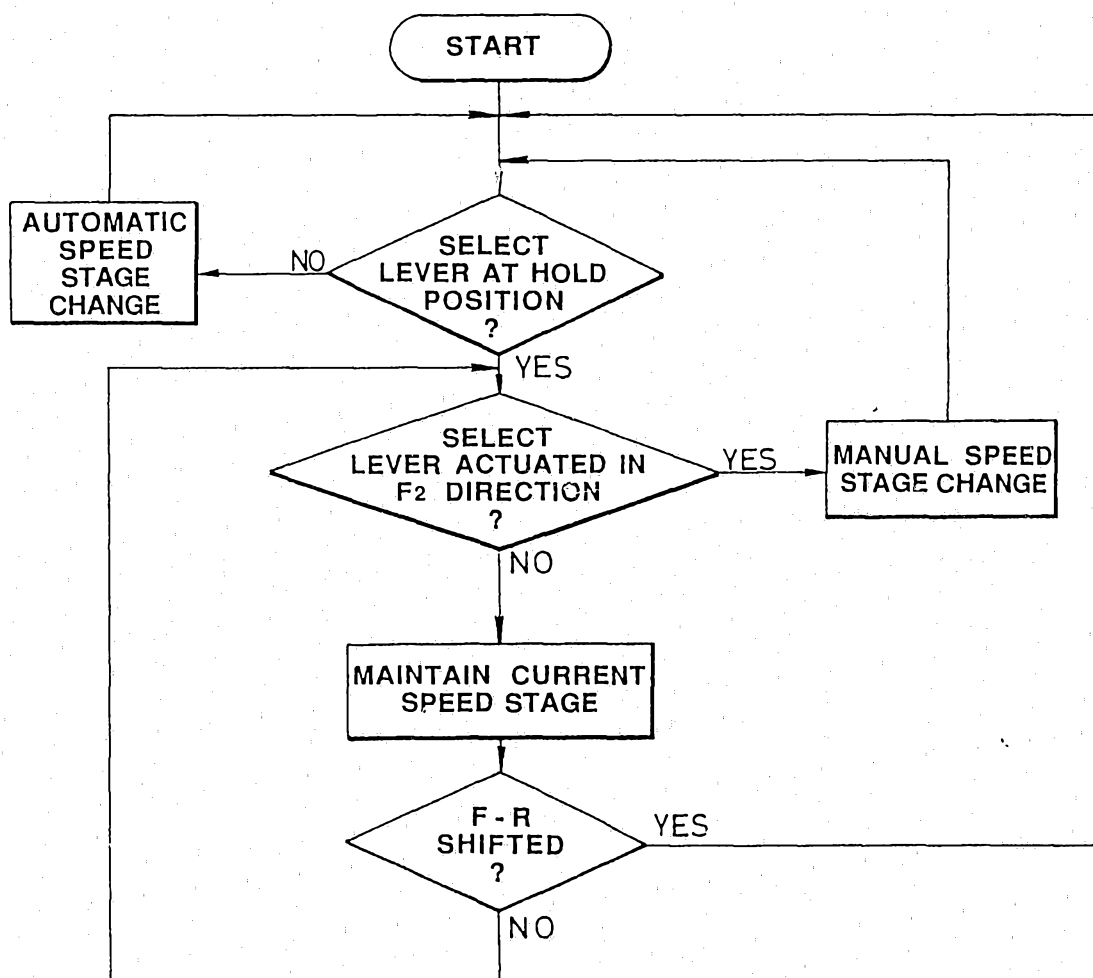


FIG.1

**FIG.2**

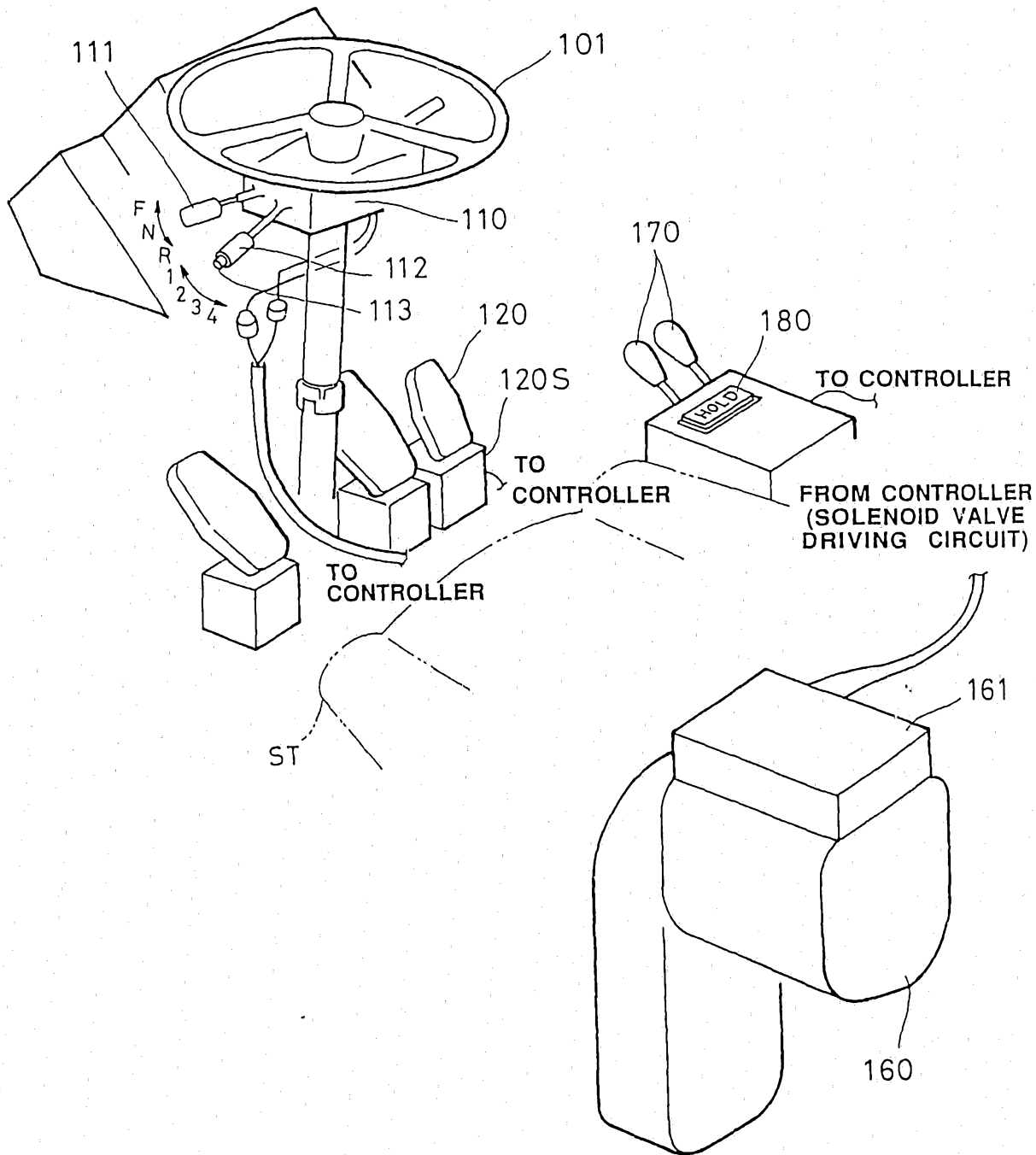


FIG. 3

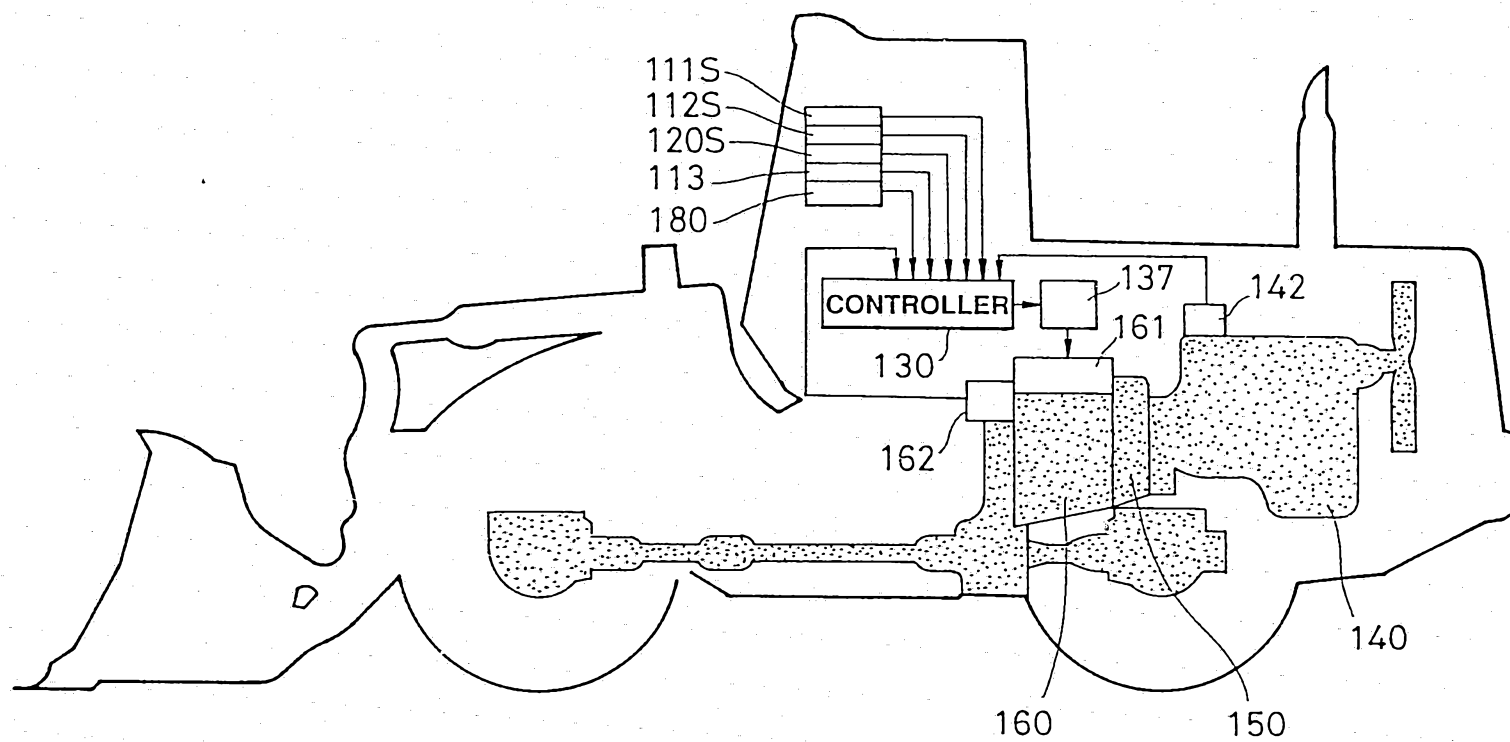


FIG. 4

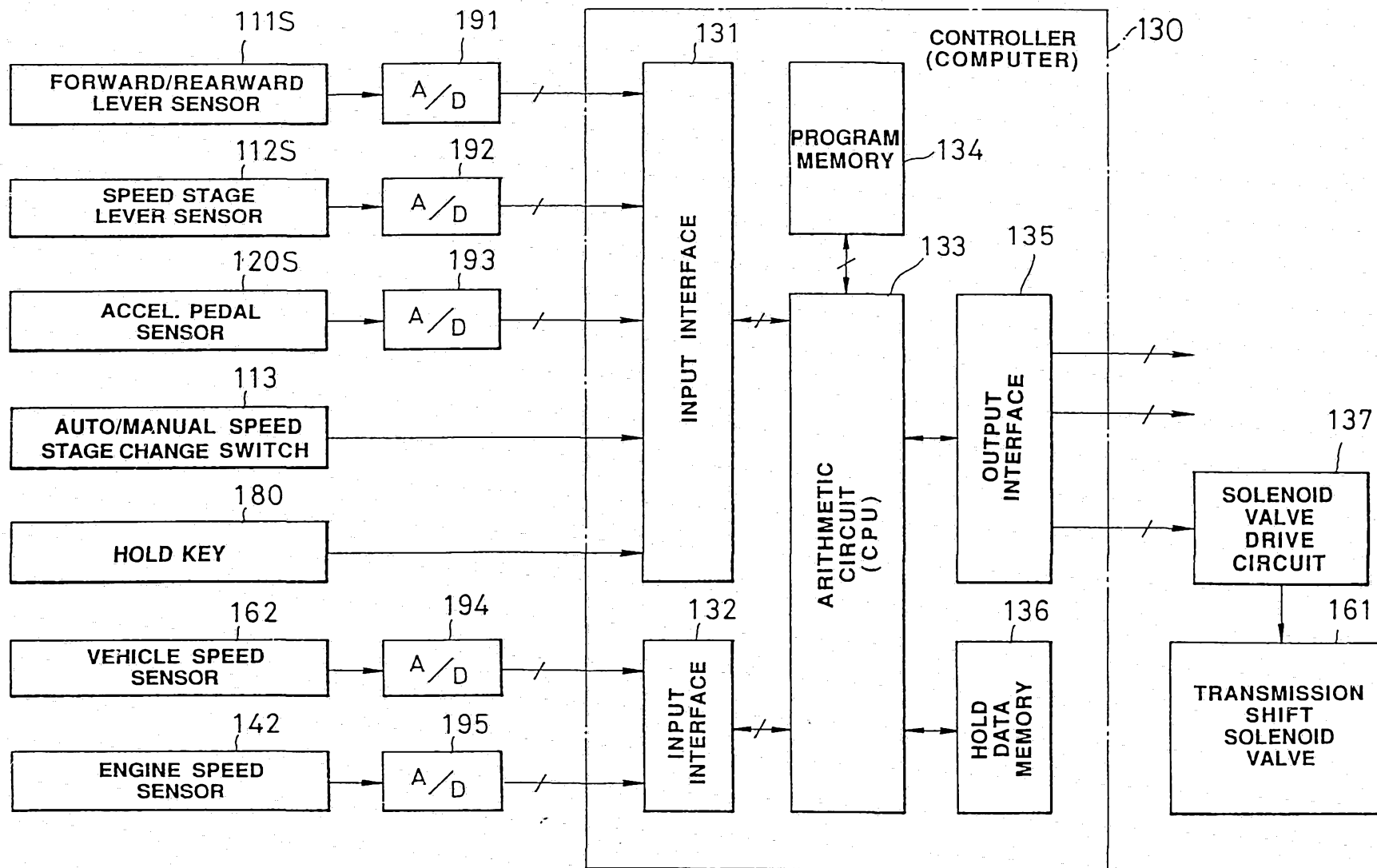
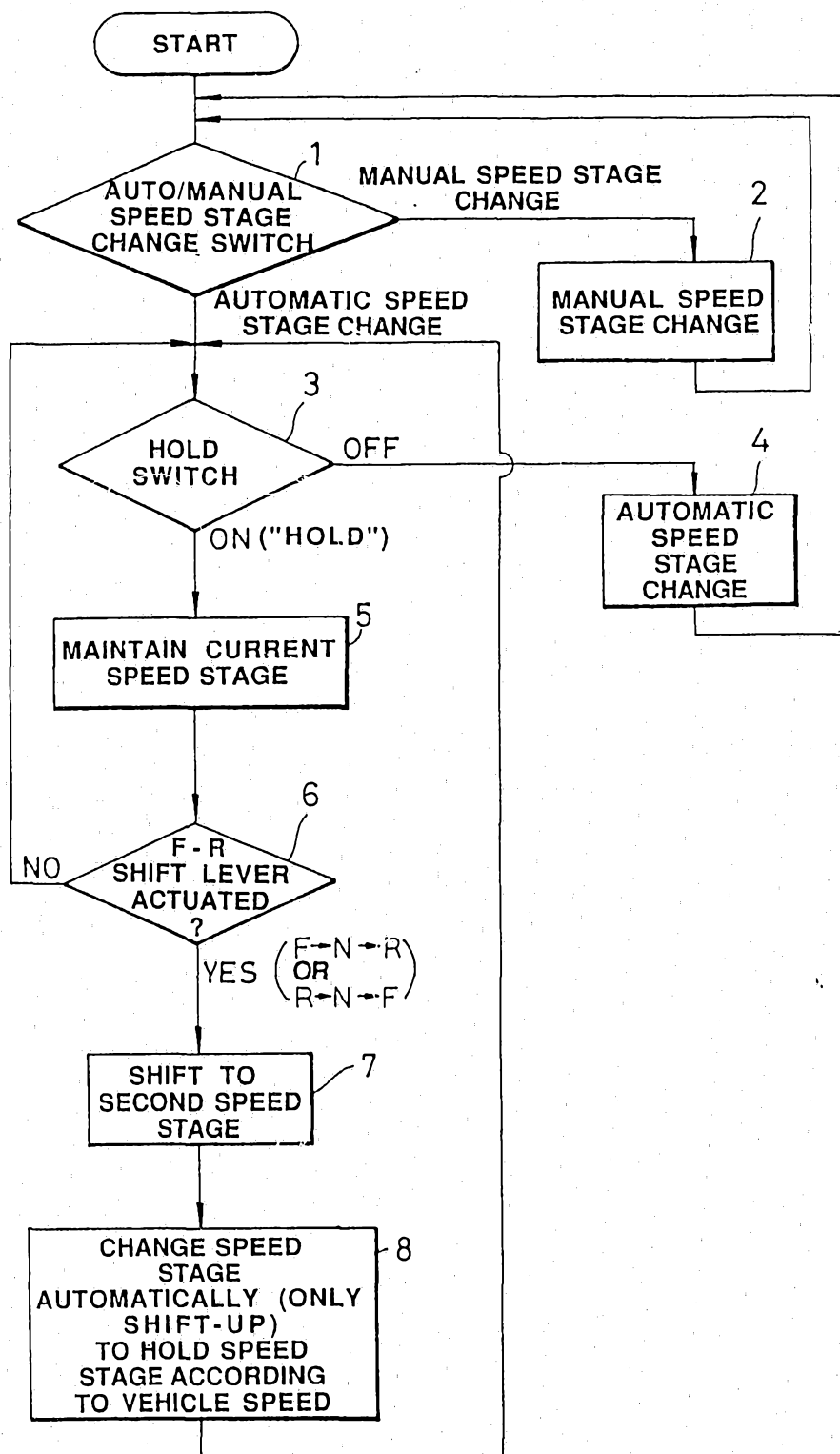


FIG. 5

**FIG. 6**

7/7

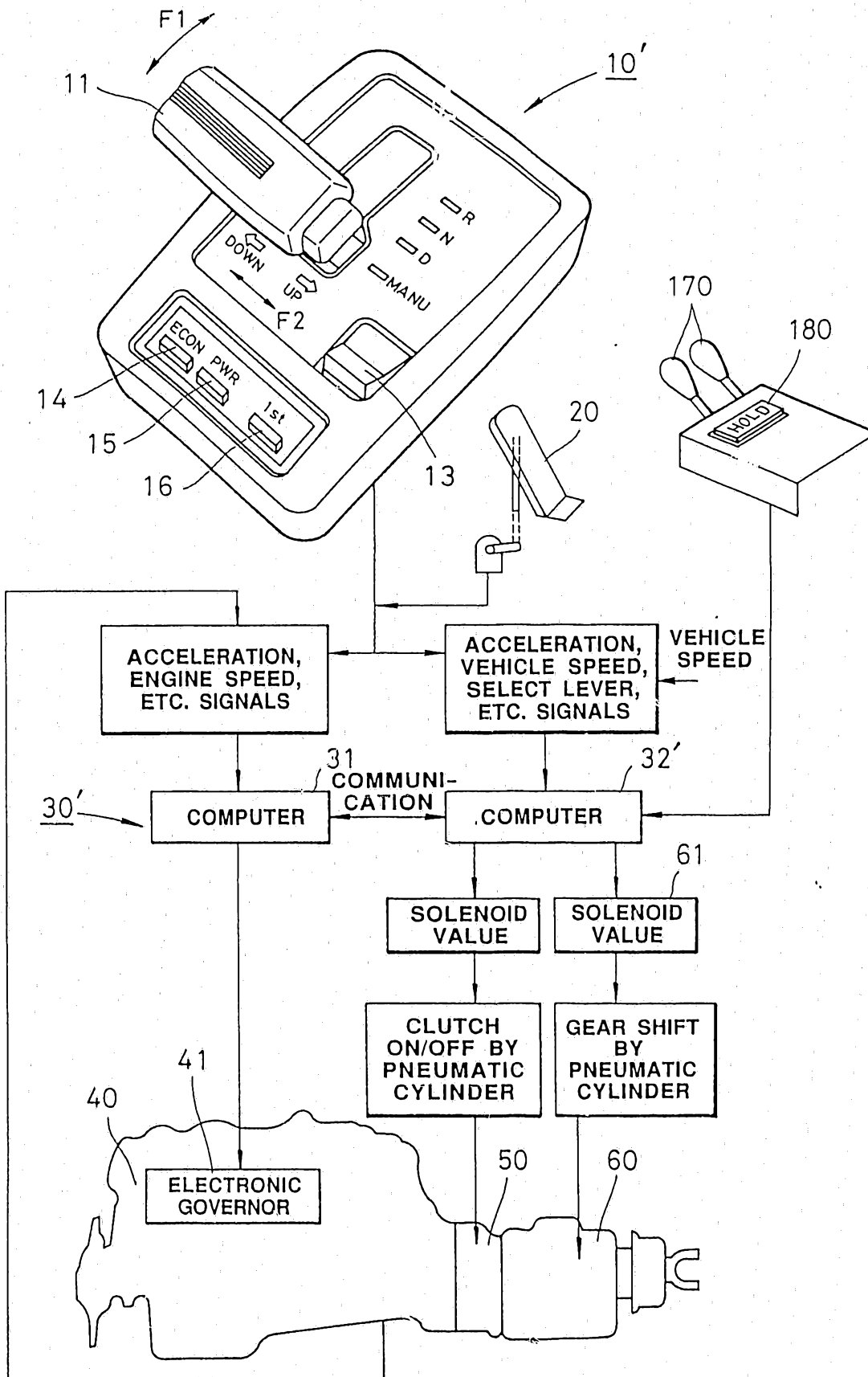


FIG. 7

INTERNATIONAL SEARCH REPORT

International Application No PCT/JP89/00079

I. CLASSIFICATION OF SUBJECT MATTER (If several classification symbols apply, indicate all) ⁶		
According to International Patent Classification (IPC) or to both National Classification and IPC		
Int.Cl ⁴	B60K20/00, 23/00, 41/04, 41/06, 41/08, 41/10, 41/12, 41/14, 41/16	
II. FIELDS SEARCHED		
Minimum Documentation Searched ⁷		
Classification System	Classification Symbols	
IPC	B60K20/00, 23/00, 41/04-16	
Documentation Searched other than Minimum Documentation to the Extent that such Documents are Included in the Fields Searched ⁸		
Jitsuyo Shinan Koho		1972 - 1988
Kokai Jitsuyo Shinan Koho		1971 - 1988
III. DOCUMENTS CONSIDERED TO BE RELEVANT ⁹		
Category ⁹	Citation of Document, ¹¹ with Indication, where appropriate, of the relevant passages ¹²	Relevant to Claim No. ¹³
A	JP, A, 61-41628 (Toyoda Automatic Loom Works, Ltd.) 28 February 1986 (28. 02. 86) Column 5, lines 3 to 19 (Family: none)	1-2
A	JP, A, 61-103044 (Toyoda Automatic Loom Works, Ltd.) 21 May 1986 (21. 05. 86) Column 4, lines 1 to 14 (Family: none)	1-2
¹⁰ Special categories of cited documents: "A" document defining the general state of the art which is not considered to be of particular relevance "E" earlier document but published on or after the International filing date "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "O" document referring to an oral disclosure, use, exhibition or other means "P" document published prior to the International filing date but later than the priority date claimed "T" later document published after the International filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art "A" document member of the same patent family		
IV. CERTIFICATION		
Date of the Actual Completion of the International Search March 15, 1989 (15. 03. 89)		Date of Mailing of this International Search Report March 27, 1989 (27. 03. 89)
International Searching Authority Japanese Patent Office		Signature of Authorized Officer

国 際 調 査 報 告

国際出願番号PCT/JP 89/00079

I. 発明の属する分野の分類		
国際特許分類 (IPC) Int. Cl. ⁴ B 60 K 20 / 00, 23 / 00, 41 / 04, 41 / 06, 41 / 08, 41 / 10, 41 / 12, 41 / 14, 41 / 16		
II. 国際調査を行った分野		
調 査 を 行 っ た 最 小 限 資 料		
分 類 体 系	分 類 記 号	
IPC	B 60 K 20 / 00, 23 / 00, 41 / 04-16	
最小限資料以外の資料で調査を行ったもの		
日本国実用新案公報 1972-1988年 日本国公開実用新案公報 1971-1988年		
III. 関連する技術に関する文献		
引用文献の カテゴリー ※	引用文献名 及び一部の箇所が関連するときは、その関連する箇所の表示	請求の範囲の番号
A	JP, A, 61-41628 (株式会社 豊田自動織機製作 所) 28. 2月. 1986 (28. 02. 86) 第5欄, 第3行-第19行 (ファミリーなし)	1-2
A	JP, A, 61-103044 (株式会社 豊田自動織機製作 所) 21. 5月. 1986 (21. 05. 86) 第4欄, 第1行-第14行 (ファミリーなし)	1-2
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IV. 認 証		
国際調査を完了した日 15. 03. 89	国際調査報告の発送日 27. 03. 89	
国際調査機関 日本国特許庁 (ISA/JP)	権限のある職員 特許庁審査官 岸 本 芳 也	3 D 8 1 0 8