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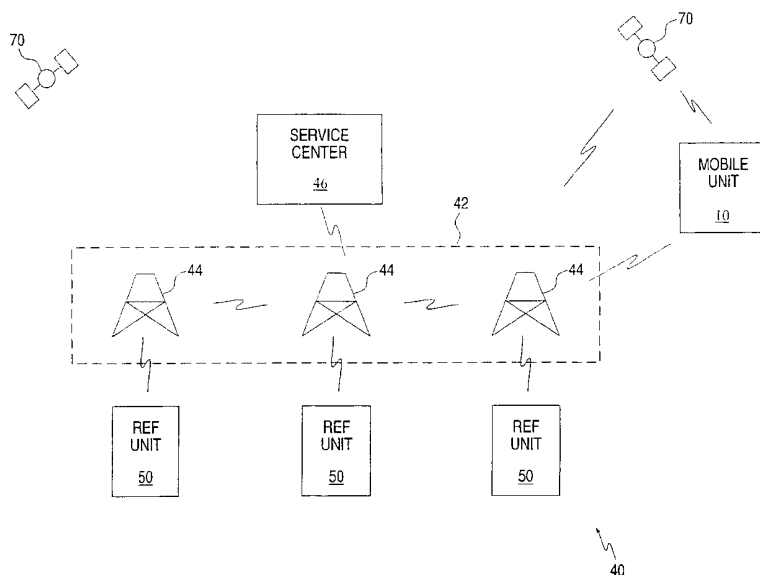
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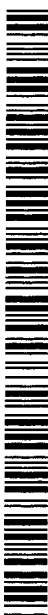
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[Continued on next page]

(54) Title: LOCATING A MOBILE UNIT USING SATELLITE SIGNAL



(57) Abstract: A method and system for finding the position of a mobile unit (10) with respect to the satellites (70) of a satellite network such as the Global Positioning System and with respect to the base stations (Figure 2) of a wireless communications network. Each satellite transmits a signal that consists of a series of frames of a pseudonoise sequence. The frames of a signal received from the satellite network by the mobile unit are arranged as columns of a matrix and are processed coherently to provide estimated pseudoranges and estimated rates of change of pseudoranges for in view satellites. The coherent processing includes performing an orthogonal transform on the rows of the matrix, multiplying the elements of the matrix by Doppler compensation factors, and then, for each satellite in view, convolving the columns of the matrix with the pseudonoise sequence of that satellite.



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Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 5,399,957 A (LOOMIS) 04 MAY 1999 (04/05/99) NOTE ABSTRACT, COLUMN 1, LINE 55, COLUMN 2, LINE 2, COLUMN 10, LINE 63, COLUMN 13, LINE 56, COLUMN 8, LINES 26-36, AND COLUMN 19, LINES 1-10.	1-97
X	US 5,774,829 A (CISNEROS ET AL) 30 JUNE 1998 (30/06/98) NOTE COLUMN 12, LINE 36, COLUMN 34, LINE 40, KALMAN FILTER 670, AND COLUMN 4, LINE 28.	1-97

Further documents are listed in the continuation of Box C. See patent family annex.

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"O" document referring to an oral disclosure, use, exhibition or other means		
"P" document published prior to the international filing date but later than the priority date claimed		

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