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(54) **A GUIDEWIRE**  
**FÜHRUNGSDRAHT**  
**UN FIL-GUIDE**

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## Description

### Technical Field

**[0001]** The present invention relates to the field of medical devices and more particularly to guidewires for vascular procedures.

### Background of the Invention

**[0002]** Medical guidewires for vascular procedures, such as angioplasty procedures, diagnostic and interventional procedures, percutaneous access procedures, or radiological and neuroradiological procedures in general, traditionally comprise an elongated core element with one or more tapered sections near the distal end thereof and a flexible helical coil disposed about the distal portion of the core element. The distal extremity of the core element or a separate safety ribbon which is secured to the distal extremity of the core element extends through the flexible coil and is secured to the distal end member of the guidewire, which is a rounded member at the distal end of the helical coil. Torquing means are provided on the proximal end of the core element to rotate and steer the guidewire while it is being advanced through a patient's vascular system.

**[0003]** The physician views the progress on a screen and makes the distal end of the guidewire enter and follow tortuous vascular vessels from the entry site through the various vascular branches to the target site by pushing and rotating the proximal end of the guidewire outside of the patient. In connection with the advancement of the guidewire or once the guidewire has been positioned at the desired site, a wide variety of medical devices may be directed to the target site along the guidewire by simply sliding the device over the guidewire and advance the device to the distal end of the guidewire. A typical medical device is a catheter, and very often a catheter and the guidewire are introduced in a common procedure where the guidewire is advanced a distance in front of the catheter, then the catheter is advanced over the guidewire, followed by a further advancement of the guidewire. Following placement of the catheter or other device, the guide wire can be removed if desired.

**[0004]** The flexible coil acts as a protective measure of a suitably large diameter, hindering the guidewire core in damaging the vascular wall. The above mentioned guidewire is known from U.S. Patent No. 4,619,274 to Morrison whose guidewire has a progressively attenuated diameter. An elongated core element extends from the proximal to the distal ends of the guidewire and has a decreasing cross sectional area in a direction towards the distal end member. A coil is carried by and secured to said core element and has proximal and distal ends. The coil has a diameter which decreases in a direction towards the distal end. The coil is formed of a single helical wound wire which has a diameter which decreases from one end to the other end with the larger diameter

beginning in a region closer to the proximal end and the smaller diameter wire ending in a region closer to the distal end.

**[0005]** U.S. Patent No. 5,001,825 to Halpern describes a fabrication process for a guidewire core where a solid metal wire is drawn down in several stages to have a stepwise decreasing diameter towards the distal end. The core is surrounded by a flexible coil having an outer diameter which decreases near the distal end. The coil consists of a single helical wound wire having a constant cross sectional area.

**[0006]** U.S. Patent No. 4,932,419 discloses a catheter-like, fluid-transmitting guidewire device having a ball tip element at the distal end, a shaft, inner and outer coils of helical cross-wound wires along the shaft to the distal end, a sheath surrounding the outer coil, and a movable and removable core within the lumen of the inner coil and with a proximal handle. The wires of the coils have a pitch angles of 75° or greater from transverse; the inner and outer coils are joined to each other at distal and proximal ends;

**[0007]** the outer coil may have four side-by-side wires wound at a 4:1 ratio, and the inner coil may have two flat wires of different widths and be wound at a 2:1 ratio.

**[0008]** It is an object of the present invention to provide a guidewire which in its distal area is highly flexible and yet capable of transferring torques applied to the proximal end of the guidewire to the distal end of the guidewire in a very precise manner even when the guidewire follows a loop-shaped course.

### Summary of the Invention

**[0009]** According to the present invention, there is provided a guidewire according to claim 1.

**[0010]** In a preferred embodiment, along a distance of at least 10 cm from the distal end member said at least one helical wound group of wires is the primary or the sole torque-transferring means between the shaft portion and the distal end member. Because the torque is transferred through the helical wound wires the central core can be given very feeble dimensions, thus increasing the flexibility of the distal portion, or it can be completely left out by making at least the most distal 10 cm of the guidewire without a torque-transferring solid metallic core inside said at least one group of wires. If desired there can be a safety ribbon inside the wound wires, connecting the rounded distal end member with a more proximal shaft portion, but such a ribbon will normally not be required.

**[0011]** Due to the very high flexibility, pushability and torquability and the ability of the guidewire to maintain each of these three characteristics even when set in a very tortuous pattern involving two or more tight loops the guidewire can be of use in very small and distant vessels. In order to further enhance use of the guidewire in vessels with small lumen the at least one helical wound group of wires has a smaller outer diameter at the distal

end than at said position on the shaft portion.

**[0012]** If the group of wound wires is secured to the shaft, which for example can be of traditional type with a core member or can be another group of wires of larger dimensions, such as by soldering or welding the proximal end of the group onto the shaft the guidewire can be prone to kinking at the transition between the flexible group of wires and the remainder of the shaft. With a view to avoiding this, the said at least one helical wound group of wires preferably extends into the shaft portion towards the proximal end, and even more preferably it extends along a guidewire length at least in the range of 20-50 cm from the distal end. The additional stiffness caused by the attachment of the wire is less disturbing the longer it occurs from the distal end of the guidewire. It is possible to let the group or groups of helical wound wires extend to a position at the proximal end of the guidewire, so that they span the entire guidewire. It is preferred that the wires in said at least one group have a separation from one wire to the next in the group of less than the diameter of the wire. Normally, the wires in the group are placed so close they touch each other.

**[0013]** In a preferred embodiment the at least one group of wires is made of from 2 to 8 helically wound wires. A number of the wires are placed next to each other and wound in the same direction. By using several wires their aggregate breadth can be adapted to correspond to the desired pitch distance. As an alternative to winding all wires in the same direction some, such as one half of the number of wires, can be wound in one direction while others, such as the other half, can be wound in the opposite direction. Such winding can be effected in separate rounds resulting in a coil of two layers of wires with mutual opposite handedness.

**[0014]** In the preferred embodiment the guidewire is made without a solid or hollow metallic core inside the at least one coil. By dispensing with the metallic core the flexibility of the guidewire is increased, and the manufacturing of the guidewire is simplified.

**[0015]** The cross-section of said wires in said at least one helical wound group is a circular shape in the proximal end of the wire, and in the distal portion of the wire the cross-section has the shape of a circular segment which has a straight line facing radially outwards. Such a variation of the cross-sectional shape can be the result of grinding of relatively long portion with the full diameter and a relatively short portion with a quickly reduced diameter, or a guidewire for neuroradiological use via the femoral route, which requires a gentle reduction in diameter over a relatively long distance and a long and soft distal portion, it is a simple matter to adjust the grinding process to the desired guidewire.

**[0016]** The method can be adjusted to grind the elongate distal portion of the guide wire to have a substantially continuously diminishing outer diameter which results in a gradual increase of bending flexibility of the guidewire.

**[0017]** It is further possible to adjust the method to grind the elongate distal portion of the guide wire to have a

substantially stepwise diminishing outer diameter which is often preferable in case of very long distal portions. Further, the method can be so that elongate distal portions of the guide wire are ground to have areas with diminishing outer diameters mixed with areas having substantially constant outer diameters.

#### Brief Description of the Drawings

**[0018]** Examples of the invention will now be described in more detail with reference to the highly schematical drawings, in which:

Fig. 1 depicts a sketch of a guidewire according to the invention when following an example of a course in the vascular system;

Fig. 2 illustrates a partial, longitudinal section through an embodiment of the guidewire;

Fig. 3 depicts a partial, longitudinal sections through helical wound wires in an embodiments of the guidewire; and

Figs. 4-7 depict partial, longitudinal views of embodiments with a radiopaque marker in the distal end.

#### Detailed Description

**[0019]** In the following description of the embodiments a helical wound wire is ground on its outside to provide a circular segment with the purpose of reducing the diameter of the helical wound wire in its distal portion. The circular segment has less cross-sectional area than the corresponding full circular, shape, and the reduced cross-sectional area greatly increases the bending flexibility of the helical wound wire without sacrificing its ability to transfer torque.

**[0020]** Embodiments of the invention comprise a guidewire comprising a distal end, a shaft portion and a proximal end, wherein the shaft portion comprises at least one helical wound group of at least two wires having a pitch angle in the range of 35° -76° , and said at least one helical wound group of wires having said pitch angle extends to the distal end of the guidewire. With this guidewire the above mentioned advantages are achieved.

**[0021]** A method of manufacturing a guidewire, is also disclosed, wherein

at least one helical wound wire is subjected to grinding reducing the outer diameter of said distal guidewire portion in relation to a proximal portion of the guide wire.

Grinding is an advantageous manner of manufacturing the above mentioned guidewires because it is very easy to adapt the grinding process to the specific guidewire to be produced, and a wide variety of guidewires can be premanufactured as wound guidewire bodies having an even outer diameter along their entire length. When the specific use of the guidewire is specified, such as a guidewire for accessing a kidney in an adult via the femoral route, which requires a guidewire having the same

reference numerals are used for features of the same type.

**[0022]** A guidewire seen in Fig. 1 is generally denoted by 1 and has a distal end 2 capable of being advanced to a target site in the vascular system and a proximal end 3 that is kept outside the patient's body. A shaft portion 4 extends from the proximal end towards the distal end and carries near the proximal end a handle 5 releasably secured to the guidewire. The guidewire can typically have a length in the range of 50-300 cm and a maximum outer diameter in the range of 0.204-1.072 mm (0.008-0.042 inches). It can also include several segments where the proximal segment has a larger diameter than one or more intermediate segments which has/have larger diameters than the distal segment. When such a guidewire follows a tortuous vessel path involving several sharp bends, loops and the like, it is desirable that a turning of handle 5 results in a similar turning of the distal end 2.

**[0023]** The shaft portion 4 can include a solid shaft which is of a metallic material such as medical grade stainless steel or Nitinol. In that case a coiled distal portion 6 is fixed onto and in extension of the shaft portion. However, in the preferred embodiment the coiled portion continues from the distal to the proximal ends, and the use of a solid shaft is made superfluous. The coiled portion ends distally at the distal end member 2, which is a member having a soft front end termination, such as a rounded front or a front of very flexible material or very flexible configuration. End member 2 can be a solder, or a sphere that can be laser welded, for example, onto the distal end of the coiled portion. Further, end member 2 can also include a soft coil of radiopaque material. In the embodiment depicted in Fig. 2 three wires 7, 8 and 9 have been placed next to each other and have been wound in a common operation into a wound group of three wires 10 with a pitch angle  $\alpha$  of the individual wire of about 40°. The pitch angle is the included angle between the longitudinal axis of the guidewire and the center axis of the relevant wire 7, 8 or 9. The size of the pitch angle depends on the diameter of the wire, the diameter of the guidewire, and of the number of wires in a group. If the pitch angle is smaller than 35° the desired torquability is lost, and if the pitch angle becomes larger than 76° it also becomes difficult to transfer the torque to the distal end. The most preferred pitch angle is in the range of 50 to 70°. A pitch angle in the ranges of 35-50° or 70-76° is also very useful and allows certain modifications to be made to the properties of the guidewire. If the pushability is the most important criteria the pitch angle can be chosen at for example 38°, and if the bending flexibility is most important the pitch angle can be chosen at 75°, for example. However, the combination of torque transferral, pushability and transverse flexibility is normally well-balanced for pitch angles in the range of 50-68°. The pitch or pitch distance is indicated by b and is the distance in the longitudinal direction of the guidewire from the first wire in one turn of the group to

the same first wire in the next turn of the group.

**[0024]** The wire 7, 8 or 9 is of a linear elastic material, such as stainless steel, titanium or tantalum, or it is made of a superelastic alloy, such as Nitinol. The diameter d of the wire is in the range of 0.06-0.45 mm, and preferably in the range of 0.15 - 0.35 mm. In case the wire is of stainless steel it has preferably an ultimate tensile strength in the range of 1800-2700 N/mm<sup>2</sup> but lower or higher values are also possible. The guidewire is made by placing a group of from two, to eight wires in a row next to each other, such as according to the desired pitch angle, where after the group of wires is wound about a mandrel. Then the mandrel with the coiled wires can be subjected to heat treatment in order to remove residual stresses from the wires. As an example, the heat treatment can last for about two hours in an oven at a temperature of about 500°C. After the heat treatment the mandrel is removed from the wires.

**[0025]** In the embodiment shown in Fig. 2 the distal portion 6 has a plurality of sections 13, 12 and 11 having sequentially smaller outer diameters D1, D2 and D3 towards distal end member 2 with tapered sections 14 and 15 connecting the smaller diameter sections with larger diameter sections. The sections with reduced diameter have been manufactured by grinding the distal portion in a centerless grinding machine. The inner diameter of the sections 11-13 is preferably constant.

**[0026]** In the ground portions, wires 7, 8, 9 have a cross-section that deviates from a circular shape and have the shape of circular segment which has a straight line 16 facing radially outwards. In the shaft portion the guidewire has a diameter D1 corresponding to the diameter of coil 10 prior to its grinding where the wires 7, 8 and 9 have their full cross-sectional area. This diameter is present along the length 15.

**[0027]** The three wires placed in a group side by side are identical. The grinding procedure produces the tapered section 15 in which the outer diameter diminishes to diameter D2, and the tapered section 14 in which the outer diameter of the guidewire diminishes to diameter D3. Due to the smaller outer diameters sections 12 and 11 have considerably larger transverse flexibility and higher softness, but torque is nevertheless surprisingly transferred fully to the distal end.

**[0028]** The guidewire can in part or along the entire length include two rows of wires placed one outside the other as illustrated Fig. 3. The inner row 17 includes a group of wires wound in the opposite direction than the group of wires in the outer row 18. In case the proximal portion of the guidewire is to have a large stiffness in order to be able to be directed through large vessel over long distances it can be an advantage to utilize at least two rows of wires in the proximal portion and less rows or a single row in the intermediate and/or distal portions of the guidewire.

**[0029]** In order to make the tip portion of the guidewire more visible on a screen it is desirable to use some kind of radiopaque material, such as platinum which in itself

lacks the desirable high strength properties provided by the use of stainless steel, Nitinol or another material of high strength and large flexibility and elasticity. In the embodiment illustrated in Fig. 4 by a sectional view of the distal portion, one wire 20 or strand out of a group of three is of the radiopaque material and the remaining two 21 are out of the high strength material. The wire 20 can have a relatively short length and be fixed in distal extension of, a wire of the same type as wires 21.

**[0030]** As an alternative, a guidewire distal portion 16 of the type shown in Fig. 5 can be provided with a coil 22 of radiopaque wire which has a very small wire diameter, such as 0.05-0.35 mm. The coil has a pitch distance corresponding to the diameter of the wire, and consequently coil 22 is unable to transfer torque and is very flexible so that the desired properties of the distal guidewire portion are not impaired by adding coil 22 to the guidewire. Another embodiment according to the invention is outlined in Fig. 6 where tip 2 is of radiopaque material and includes a thread or a ribbon 23 of similar material that extends centrally into the hollow inner space in the guidewire to a free end. Further it is possible to position a distal tip member designed as a very soft coil 24 of radiopaque material in extension of wires 7, 8, 9 as outlined in Fig. 7. Such a coil can for example have a length 16 of about 35 mm. Apart from making the tip visible it can also serve as a very soft and pliable tip member.

**[0031]** The guidewire can be made with a uniform diameter throughout its length. In case the guidewire has diminishing diameter towards the distal end a prefabricated guidewire of uniform diameter can be ground to the desired dimensions as described above.

**[0032]** In the following, some examples of guidewires made according to the invention are described.

#### EXAMPLE 1:

**[0033]** Wires of stainless steel grade AISI 304 and an outer diameter  $d=0.014"$  (0.35 mm) were used for making guidewires. Two lengths of wires were placed side by side in a group which was wound about a mandril resulting in a guidewire which had an outer diameter of  $D=0.042"$  (1.07 mm), where after the mandril was removed. The same was repeated with groups of three, four and five wire lengths placed side by side and wound in a common movement around the mandril. The resulting wires were placed in loop-shape with a number of loops having an approximate loop diameter of 2 cm and the ability to transfer torque from one end of the wire to the other was visually examined. Then the pitch angle was visually determined under 50 times magnification. This manner of determining the angle is somewhat inaccurate but provides a rough estimate of the angle. There was also made a coil of a single wire. The single wire coil had a pitch angle of about  $80^\circ$  and it was unable to transfer torque when it had two loops. The guidewire made of a group of two wires had a pitch angle of about  $72^\circ$ , and it could transfer torque when set with two loops and three loops.

The guidewire made of a group of three wires had a pitch angle of about  $64^\circ$  and it transferred perfectly the torque in a 1:1 relationship even when set with three or more loops (ten loops functioned). The guidewire made of a group of four wires had a pitch angle of about  $53^\circ$  and turned out to have the same excellent properties as the one with a group of three wires. The guidewire made of a group of five wires had a pitch angle of about  $40^\circ$  and turned out to have the same excellent properties as the one with a group of three wires. The higher number of wires provides the shaft less flexibility and larger pushability, which can be desirable for guidewires used for passing long distances through larger vessels.

#### 15 EXAMPLE 2:

**[0034]** With wire lengths having a diameter of  $d = 0.008"$  (0.20 mm) a group of four wires was wound around a mandril as described above, and a pitch angle of about  $52^\circ$  was determined in the resulting guidewire which had an outer diameter of  $D=0.63$  mm (0.025"). The guidewire was tested like mentioned above and it showed excellent properties. Torque could be transferred even when the guidewire was set with more than 10 loops.

#### 25 EXAMPLE 3:

**[0035]** With wire lengths having a diameter of  $d = 0.003"$  (0.075 mm) groups of two and three wires were wound around a mandril as described above, and pitch angles of about  $66^\circ$  for the three wire group and about  $76^\circ$  for the two wire group were determined in the resulting guidewire which had an outer diameter of 0.010" (0.25 mm). The guidewires were tested like mentioned above, and the one with the two wire group could transfer torque, but not as well as in Example 2, and the one with the three wire group could without problems transfer torque when set with three loops.

#### 40 EXAMPLE 4:

**[0036]** With wire lengths having a diameter of  $d = 0.006"$  (0.15 mm) a group of four wires was wound around a mandril as described above, and a pitch angle of about  $50^\circ$  was determined in the resulting guidewire which had an outer diameter of  $D = 0.018"$  (0.45 mm). The guidewire was tested like mentioned above and it showed excellent properties. Torque could be transferred even when the guidewire was set with more than 10 loops. The various embodiments can be combined into other embodiments within the scope of the present invention. Other modifications are possible, such as using a core member within the coiled wires, which core member can extend along the proximal and any intermediate portions but not along the distal portion. The core member can have a cross-sectional area that diminishes gradually or stepwise at increasing distance from the proximal end of the guidewire.

## Claims

1. A guidewire comprising a distal end member (2) and a shaft portion (4) extending in a longitudinal direction from a proximal end (3) towards the distal end member, the shaft portion including a wire helix section (13, 12, 11) extending from a position at the shaft portion to the distal end member, the wire helix section having a smaller outer diameter at the distal end than at said position on the shaft portion, **characterised in that** the wire helix section comprises a group of at least two helically-wound wires (7, 8, 9) extending side by side, the group having a pitch angle in the range 35° to 76°, and the cross-section of each wire has the form of a circle with a diameter d along its length, and with portions removed from each wire to leave a cross-section with the shape of a circular segment defining a straight line facing radially outwards to provide said smaller outer diameter of the wire helix section at the distal end.
 

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2. A guidewire according to claim 1, wherein along a distance of at least 10cm from the distal end member (2) said wire helix section (13, 12, 11) is the primary or the sole torque transferring means to the distal end member.
 

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3. A guidewire according to claim 1, wherein at least the most distal 10cm of the guidewire is made without a torque-transferring solid metallic core inside said wire helix section (13, 12, 11).
 

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4. A guidewire according to claim 1, wherein said wire helix section (13, 12, 11) extends towards the proximal end along a guidewire length at least in the range 20-50cm from the distal end.
 

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5. A guidewire according to claim 4, wherein said wire helix section (13, 12, 11) extends to a position at the proximal end of the guidewire.
 

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6. A guidewire according to any preceding claim wherein the wire helix section has a plurality of sub-sections (13, 12, 11) with sequentially smaller outer diameters (D1, D2, D3) towards said distal end member (2), said sub-sections (13, 12, 11) being interconnected by tapered sub-sections (14, 15).
 

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7. A guidewire according to any preceding claim, wherein the inner diameter of the wire helix section (13, 12, 11) is constant.
 

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distalen Endelement hin erstreckt, wobei der Schaftabschnitt einen Drahtwendelabschnitt (13, 12, 11) aufweist, der sich von einer Position am Schaftabschnitt bis zum distalen Endelement hin erstreckt, wobei der Drahtwendelabschnitt am distalen Ende einen kleineren Außendurchmesser aufweist als an der Position auf dem Schaftabschnitt, **dadurch gekennzeichnet, dass** der Drahtwendelabschnitt eine Gruppe aus mindestens zwei spiralförmig gewickelten Drähten (7, 8, 9) aufweist, die sich Seite an Seite erstrecken, wobei die Gruppe einen Steigungswinkel im Bereich von 35° bis 76° aufweist, und wobei der Querschnitt jedes Drahts die Form eines Kreises mit einem Durchmesser d über seine Länge aufweist, und wobei Teile von jedem Draht entfernt sind, um einen Querschnitt in Form eines kreisförmigen Segments zu lassen, das eine gerade Linie definiert, die radial nach außen weist, um den kleineren Außendurchmesser des Drahtwendelabschnitts am distalen Ende bereitzustellen.

2. Führungsdraht nach Anspruch 1, worin der Drahtwendelabschnitt (13, 12, 11) über eine Strecke von mindestens 10 cm vom distalen Endelement (2) das primäre oder alleinige Drehmoment übertragende Mittel zum distalen Endelement ist.
3. Führungsdraht nach Anspruch 1, worin mindestens die äußerst distal liegenden 10 cm des Führungsdrahts ohne einen Drehmoment übertragenden festen Metallkern im Drahtwendelabschnitt (13, 12, 11) hergestellt sind.
4. Führungsdraht nach Anspruch 1, worin der Drahtwendelabschnitt (13, 12, 11) sich zum proximalen Ende über eine Führungsdrahtlänge mindestens im Bereich von 20-50 cm vom distalen Ende erstreckt.
5. Führungsdraht nach Anspruch 4, worin der Drahtwendelabschnitt (13, 12, 11) sich bis zu einer Position am proximalen Ende des Führungsdrahts erstreckt.
6. Führungsdraht nach einem der vorhergehenden Ansprüche, worin der Drahtwendelabschnitt eine Vielzahl von Unterabschnitten (13, 12, 11) mit sequenziell kleineren Außendurchmessern (D1, D2, D3) zum distalen Endelement (2) hin aufweist, wobei die Unterabschnitte (13, 12, 11) durch verjüngte Unterabschnitte (14, 15) miteinander verbunden sind.
7. Führungsdraht nach einem der vorhergehenden Ansprüche, worin der Innendurchmesser des Drahtwendelabschnitts (13, 12, 11) konstant ist.

## Patentansprüche

1. Führungsdraht mit einem distalen Endelement (2) und einem Schaftabschnitt (4), der sich in einer Längsrichtung von einem proximalen Ende (3) zum

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## Revendications

1. Fil-guide comportant un organe d'extrémité distale (2) et une portion de tige (4) s'étendant dans un sens axial depuis une extrémité proximale (3) vers l'organe d'extrémité distale, la portion de tige comprenant une section hélicoïdale de fil (13, 12, 11) s'étendant depuis une position au niveau de la portion de tige jusqu'à l'organe d'extrémité distale, la section hélicoïdale de fil ayant un diamètre extérieur plus petit au niveau de l'extrémité distale qu'au niveau de ladite position sur la portion de tige, **caractérisé en ce que** la section hélicoïdale de fil comporte un groupe d'au moins deux fils enroulés en hélice (7, 8, 9) s'étendant l'un à côté de l'autre, le groupe ayant un angle de pas de l'ordre de 35 à 76°, et la section transversale de chaque fil a la forme d'un cercle avec un diamètre  $d$  sur sa longueur, et avec des portions enlevées de chaque fil pour laisser une section transversale qui a la forme d'un segment circulaire définissant une ligne droite dirigée dans le sens radial vers l'extérieur pour fournir ledit diamètre extérieur plus petit de la section hélicoïdale de fil au niveau de l'extrémité distale. 5  
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2. Fil-guide selon la revendication 1, dans lequel le long d'une distance d'au moins 10 cm depuis l'organe d'extrémité distale (2) ladite section hélicoïdale de fil (13, 12, 11) est le moyen principal ou le seul moyen de transfert d'une force de torsion à l'organe d'extrémité distale. 30
3. Fil-guide selon la revendication 1, dans lequel au moins les 10 cm des plus distaux du fil-guide sont fabriqués sans âme métallique solide transférant la force de torsion à l'intérieur de ladite section hélicoïdale de fil (13, 12, 11). 35
4. Fil-guide selon la revendication 1, dans lequel ladite section hélicoïdale de fil (13, 12, 11) s'étend vers l'extrémité proximale sur une longueur de fil-guide au moins de l'ordre de 20 à 50 cm depuis l'extrémité distale. 40
5. Fil-guide selon la revendication 4, dans lequel ladite section hélicoïdale de fil (13, 12, 11) s'étend à un endroit au niveau de l'extrémité proximale du fil-guide. 45
6. Fil-guide selon l'une quelconque des revendications précédentes dans lequel la section hélicoïdale de fil a une pluralité de sous-sections (13, 12, 11) avec des diamètres extérieurs plus petits les uns à la suite des autres (D1, D2, D3) vers ledit organe d'extrémité distale (2), lesdites sous sections (13, 12, 11) étant reliées entre elles par des sous-sections coniques (14, 15). 50  
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7. Fil-guide selon l'une quelconque des revendications précédentes, dans lequel le diamètre intérieur de la section hélicoïdale de fil (13, 12, 11) est constant.

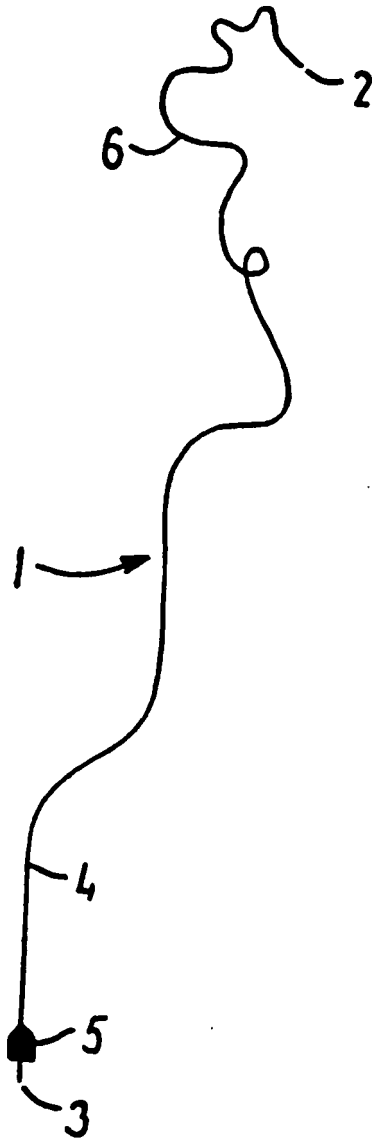
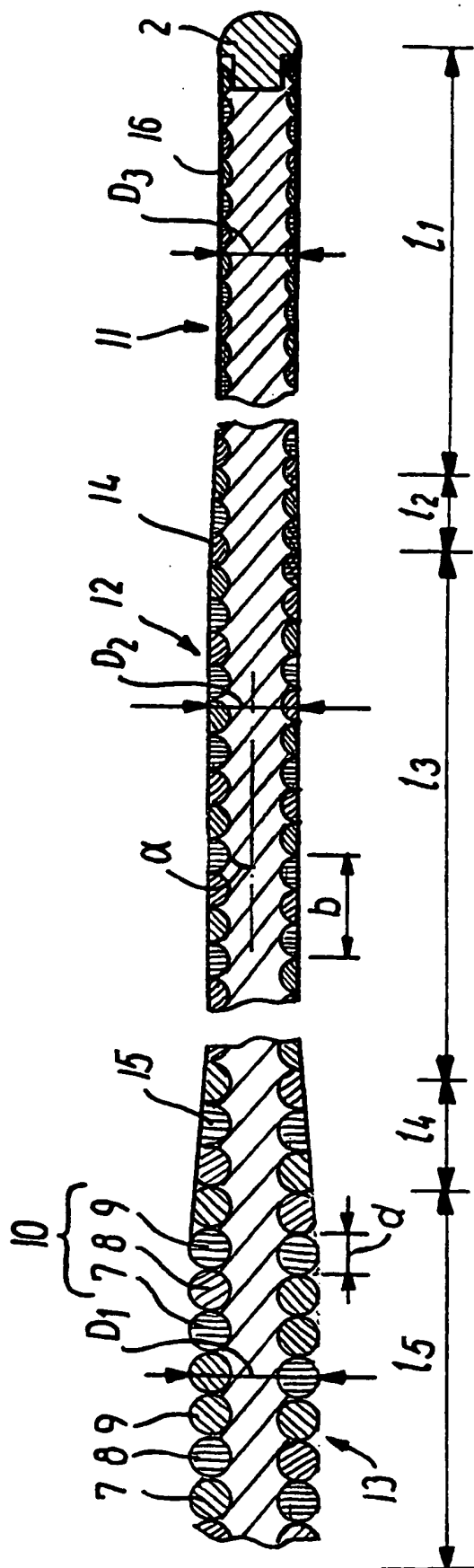


FIG.1





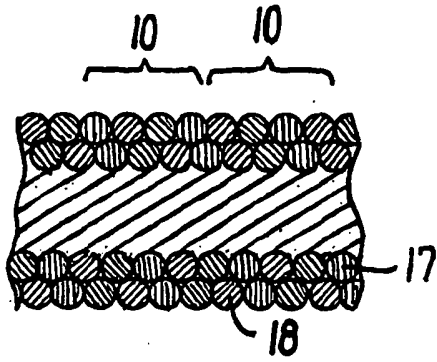


FIG. 3

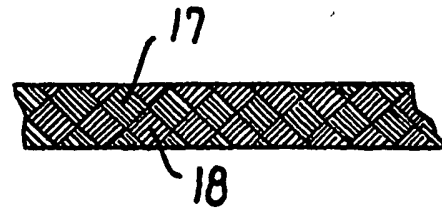


FIG. 4

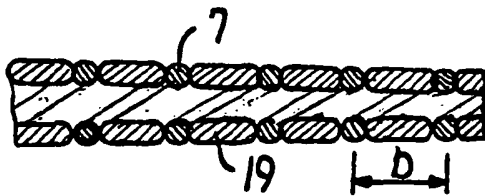


FIG. 5

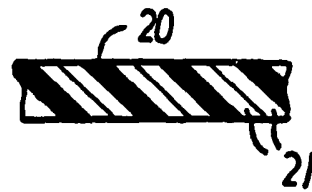


FIG. 6

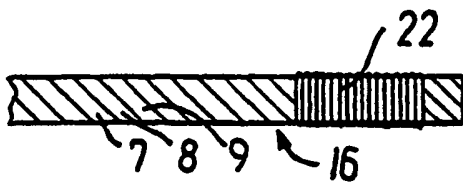


FIG. 7

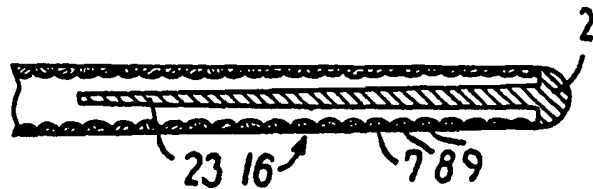


FIG. 8

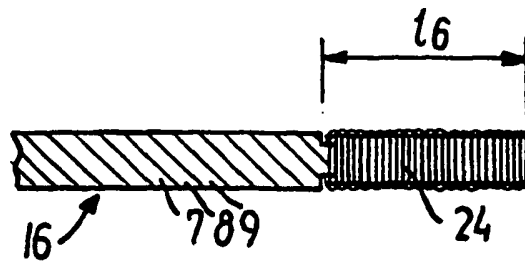


FIG. 9

**REFERENCES CITED IN THE DESCRIPTION**

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**Patent documents cited in the description**

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