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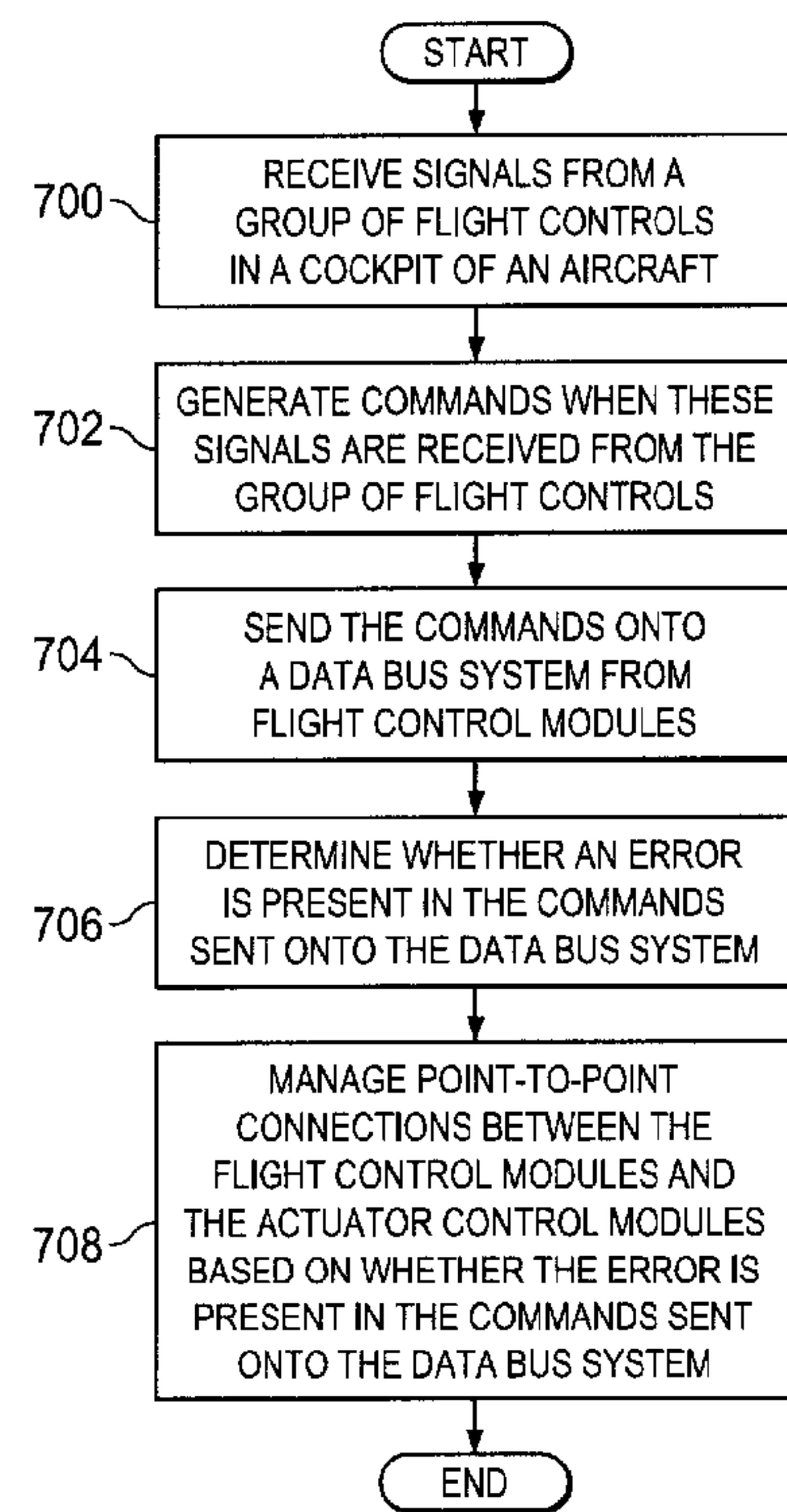
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(57) Abrégé/Abstract:

A method and apparatus for controlling flight control surfaces on an aircraft. Commands are sent onto a data bus system from flight control modules. The flight control modules and actuator control modules determine whether an error is present in the commands sent onto the data bus system. Point-to-point connections between the flight control modules and the actuator control modules are managed based on whether the error is present in the commands sent onto the data bus system.

ABSTRACT

A method and apparatus for controlling flight control surfaces on an aircraft. Commands are sent onto a data bus system from flight control modules. The flight 5 control modules and actuator control modules determine whether an error is present in the commands sent onto the data bus system. Point-to-point connections between the flight control modules and the actuator control modules are managed based on whether the error is present in the commands sent onto the data bus system.

INPUT CONGRUENCE SYSTEM FOR FLIGHT CONTROL SURFACES

BACKGROUND

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[0001] The present disclosure relates generally to aircraft and, in particular, to controlling movement of the aircraft. Still more particularly, the present disclosure relates to a method and apparatus for controlling the position of flight control surfaces on an aircraft to control movement of the aircraft.

10 **[0002]** A fly-by-wire (FBW) system for an aircraft is a system that replaces the conventional manual flight controls of an aircraft with an electronic interface. The flight controls in the cockpit are not connected to the flight control surfaces, engines, or other systems by cables, linkages, or other mechanical systems, as with more conventional aircraft. Instead, the movements of flight controls are converted to
15 electronic signals transmitted by wires, optical fibers, over an air-interface, or some combination thereof.

20 **[0003]** For example, flight control computers in a fly-by-wire system use these signals to identify how to move the actuators for each flight control surface to provide the response to the movement of the flight controls. Further, the flight control computers also may perform functions without input from a pilot. For example, the flight control computers may automatically help stabilize the flight aircraft without needing input from the pilot. The flight control computers generate commands to control flight control surfaces, an engine, or other devices that control movement of the aircraft.

25 **[0004]** An aircraft with a fly-by-wire system can be lighter in weight than when using conventional controls. Also, the electronic systems in a fly-by-wire system require less maintenance as compared to mechanical systems and hydraulic systems.

[0005] Redundancy is present in fly-by-wire systems for aircraft. Multiple flight control modules in the fly-by-wire system are used to generate commands in

response to receiving signals from the movement of flight control-external sensing devices. The redundancy takes into account that a flight control module may not always perform as desired.

5 [0006] The different components in a fly-by-wire system may communicate with each other using different types of communications architectures. For example, some fly-by-wire systems use wires that connect the components directly to each other. In this example, multiple wires can be used to provide redundant connections between the components.

10 [0007] In other examples, a fly-by-wire system may use a data bus, such as those used in computer systems. The data bus may reduce the amount of wiring between components. Depending on the amount of traffic on the data bus, commands may reach intended components later than desired. This situation is a timing issue in which commands sent to a component, such as an actuator control module, may not reach the component within a desired amount of time. As a result, the fly-by-wire 15 system may not provide for a desired level of performance in the aircraft.

[0008] For example, the delays in inputs to control an engine may result in lower than desired fuel efficiency. Delays in inputs for controlling a flight control surface result in degraded human-machine handling quality and the aircraft generating greater noise than desired or lower passenger comfort.

20 [0009] Therefore, it would be desirable to have a method and apparatus that take into account at least some of the issues discussed above, as well as other possible issues. For example, it would be desirable to have a method and apparatus that reduce issues that may be caused by inputs having delays in reaching components.

SUMMARY

[0010] In one illustrative embodiment, an apparatus comprises a data bus system in an aircraft, actuator control modules connected to the data bus system, and flight control modules connected to the data bus system. An actuator control module in the actuator control modules controls positioning of a group of flight control surfaces on the aircraft using commands on the data bus system that are directed to the actuator control module. The flight control modules generate and send the commands onto the data bus system to control the flight control surfaces on the aircraft. The commands for a flight control surface are directed towards a group of the actuator control modules assigned to the flight control surfaces. The actuator control modules and the flight control modules determine whether an error is present in the commands sent onto the data bus system by the flight control modules.

[0011] In another illustrative embodiment, a flight control system comprises a data bus system in an aircraft, actuator control modules connected to the data bus system, and flight control modules connected to the data bus system. An actuator control module in the actuator control modules controls positioning of a group of flight control surfaces on the aircraft using commands on the data bus system directed to the actuator control module. Each of the flight control modules generates and sends the commands onto the bus system to control the flight control surfaces on the aircraft. Commands for a flight control surface are directed towards the actuator control modules assigned to the flight control surface. The actuator control modules and the flight control modules determine whether an error is present in the commands sent onto the data bus system and manage point-to-point connections between the flight control modules and the actuator control modules based on the error identified in the commands.

[0012] In yet another illustrative embodiment, a method for controlling flight control surfaces on an aircraft is presented. Commands are sent onto a data bus system from flight control modules. The flight control modules and actuator control modules

determine whether an error is present in the commands sent onto the data bus system. Point-to-point connections between the flight control modules and the actuator control modules are managed based on whether the error is present in the commands sent onto the data bus system.

5 [0012a] In yet another illustrative embodiment there is provided an apparatus including a data bus system in an aircraft, actuator control modules connected to the data bus system, and an actuator control module, in the actuator control modules, configured to control a position of a flight control device. The actuator module is further configured to control movement of the aircraft, based upon commands on the

10 data bus system directed to the actuator control module. The apparatus further includes flight control modules connected to the data bus system and configured to generate the commands that control the flight control device. The commands are directed towards a group of actuator control modules assigned to the flight control device. The flight control modules are further configured to: send the commands, to

15 the flight control device, via point-to-point connection mappings designated by the flight control modules; determine whether an error is present in the commands sent onto the data bus system by the flight control modules; and, responsive to a determination of the error, designate an alternate point-to-point connection mapping for subsequent commands, such that, via alternate point-to-point connection

20 mapping, the subsequent commands reach the flight control device error free.

[0012b] In yet another illustrative embodiment there is provided a flight control system including: a data bus system in an aircraft; actuator control modules connected to the data bus system; and an actuator control module, in the actuator control modules, configured to control a position of a flight control device and further configured to control movement of the aircraft, based upon commands on the data bus system directed to the actuator control module. The flight control system further includes flight control modules connected to the data bus system and configured to generate the commands that control the flight control device on the aircraft. The commands are directed towards actuator control modules assigned to the flight

control device. The flight control modules are further configured to: send the commands to the flight control device via point-to-point connection mappings designated by the flight control modules; determine whether an error is present in the commands sent onto the data bus system; and, responsive to a determination of 5 the error, designate an alternate point-to-point connection mapping for subsequent commands to reach the flight control device error free.

[0012c] In yet another illustrative embodiment there is provided a method for controlling a flight control device on an aircraft. The method involves a flight control module determining a point-to-point connection mapping for sending a command to 10 an actuator control module, sending commands onto a data bus system from the flight control module, and determining, by the flight control module and actuator control module, whether an error is present in the commands sent onto the data bus system. The method further involves using a determination of the error, the flight control module determining an alternative point-to-point connection mapping 15 between the flight control module and the actuator control module, such that the commands reach the actuator control module error free via the alternative point-to-point connection mapping.

[0013] The features and functions can be achieved independently in various embodiments of the present disclosure or may be combined in yet other 20 embodiments in which further details can be seen with reference to the following description and drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

[0014] The features believed characteristic of the illustrative embodiments are set forth in the appended claims. The illustrative embodiments, however, will best be understood by reference to the following detailed description of an illustrative embodiment of the present disclosure when read in conjunction with the accompanying drawings, wherein:

[0015] **Figure 1** is an illustration of an aircraft in accordance with an illustrative embodiment;

10 [0016] **Figure 2** is an illustration of a block diagram of a flight control environment in accordance with an illustrative embodiment;

[0017] **Figure 3** is an illustration of a block diagram of a message in accordance with an illustrative embodiment;

15 [0018] **Figure 4** is an illustration of a block diagram of information used by flight control modules and actuator control modules in the processing of commands in accordance with an illustrative embodiment;

[0019] **Figures 5A and 5B** are illustrations of a flowchart of a process for processing commands in a flight control environment in accordance with an illustrative embodiment;

[0020] **Figure 6** is an illustration of a block diagram of components of a flight control environment in accordance with an illustrative embodiment;

[0021] **Figure 7** is an illustration of a flowchart of a process for controlling flight control surfaces on an aircraft in accordance with an illustrative embodiment;

5 [0022] **Figure 8** is an illustration of a flowchart of a process for processing signals from a flight control in accordance with an illustrative embodiment;

[0023] **Figure 9** is an illustration of a flowchart of a process for processing commands in accordance with an illustrative embodiment;

10 [0024] **Figure 10** is an illustration of a flowchart of a process for determining whether an error is present in commands received in messages from flight control modules in accordance with an illustrative embodiment;

[0025] **Figure 11** is an illustration of a flowchart of a process for processing commands in accordance with an illustrative embodiment;

15 [0026] **Figures 12A and 12B** are illustrations of a flowchart of a process for identifying whether errors are present in a flight control system in accordance with an illustrative embodiment;

[0027] **Figure 13** is an illustration of a block diagram of an aircraft manufacturing and service method in accordance with an illustrative embodiment; and

20 [0028] **Figure 14** is an illustration of a block diagram of an aircraft in which an illustrative embodiment may be implemented.

DETAILED DESCRIPTION

[0029] The illustrative embodiments recognize and take into account one or more 25 different considerations. For example, the illustrative embodiments recognize and take into account that the use of buses, such as those used in computers, is becoming more common in aircraft. For example, flight control modules may send commands to actuator control modules to control devices in the aircraft. Actuator control modules may control, for example, a flight control surface, an engine, or

some other suitable device in the aircraft. With these types of buses, the timing of when commands sent from a flight control module are received by an actuator control module for processing may not always occur as quickly as desired.

5 [0030] The illustrative embodiments recognize and take into account that a bus may be a parallel bus or a serial bus. When a parallel bus is used, units of data, such as a word, may be carried on multiple paths in the bus. Depending on the traffic and other conditions, the time needed for a unit of data to reach an actuator control module may take more time than desired.

10 [0031] As a result, a command from one flight control module may arrive later than a command from another flight control module for the same flight control surface. This type of delay results in a lack of congruency in the inputs to the actuator control module. The illustrative embodiments recognize and take into account that commands received in the inputs to the actuator control module may not provide a desired performance in the aircraft when the timing issues are present.

15 [0032] The illustrative embodiments recognize and take into account that when multiple flight control modules send commands to an actuator control module, the actuator control module may receive the command from each of the flight control modules at different times. Thus, the illustrative embodiments provide a method and apparatus for controlling flight control surfaces on an aircraft. In one illustrative 20 embodiment, an apparatus comprises a data bus system, actuator control modules, and flight control modules. The data bus system is located in an aircraft. The actuator control modules are connected to the data bus system. An actuator control module in the actuator control modules controls positioning of a group of flight control surfaces on the aircraft using commands on the data bus system that are 25 directed to the actuator control module. The flight control modules are connected to the data bus system. The flight control modules generate and send the commands onto the bus system to control the flight control surfaces on the aircraft. The commands for a flight control surface are directed towards a group of actuator control modules assigned to the flight control surfaces. The actuator control

modules and the flight control modules determine whether an error is present in the commands sent onto the data bus system by the flight control modules.

[0033] A “group of,” as used herein with reference to items, means one or more items. For example, a group of actuator control modules is one or more actuator 5 control modules.

[0034] With reference now to the figures, and in particular, with reference to **Figure 1**, an illustration of an aircraft is depicted in accordance with an illustrative embodiment. In this illustrative example, aircraft **100** has wing **102** and wing **104** attached to body **106**. Aircraft **100** includes engine **108** attached to wing **102** and 10 engine **110** attached to wing **104**.

[0035] Body **106** has tail section **112**. Horizontal stabilizer **114**, horizontal stabilizer **116**, and vertical stabilizer **118** are attached to tail section **112** of body **106**.

[0036] Aircraft **100** is an example of an aircraft in which a flight control system may be implemented in accordance with an illustrative embodiment. The flight control 15 system may control flight control surfaces on aircraft **100**. For example, the flight control system may control the position of flap **120**, rudder **122**, or some other flight control surface on aircraft **100**. The flight control system also may control the operation of engine **108** and engine **110**.

[0037] Turning next to **Figure 2**, an illustration of a block diagram of a flight control 20 environment is depicted in accordance with an illustrative embodiment. In this depicted example, flight control environment **200** includes aircraft **202**. Flight control system **204** in aircraft **202** controls the movement of aircraft **202**. Flight control system **204** controls the operation of flight control surfaces **206**.

[0038] In this illustrative example, flight control system **204** is a fly-by-wire system. 25 As depicted, flight control system **204** includes data bus system **208**, actuator control modules **210**, and flight control modules **212**.

[0039] Data bus system **208** is a group of buses. As depicted, data bus system **208** facilitates communication between actuator control modules **210** and flight control modules **212** that are connected to data bus system **208**. Data bus system **208** may

use any suitable architecture. For example, data bus system **208** may use architectures employed in computers. Data bus system **208** may provide communications to line replaceable units in addition to actuator control modules **210** and flight control modules **212**. In this illustrative example, data bus system **208** provides a medium for sending information in parallel.

5 [0040] In the illustrative example, actuator control modules **210** are connected to data bus system **208**. As depicted, actuator control module **214** in actuator control modules **210** controls positioning of a group of flight control surfaces **206** using commands **216** on data bus system **208** that are directed to actuator control module 10 **214**.

[0041] In other words, each of actuator control modules **210** may be used to control the positioning of one or more flight control surfaces **206**. Further, a plurality of actuator control modules **210** are assigned to each of flight control surfaces **206**. By assigning two or more of actuator control modules **210** redundancy is provided to 15 control flight control surfaces **206**.

[0042] For example, actuator control modules **210** send signals **218** to actuators **220**. Actuators **220** in turn move flight control surfaces **206** to desired positions.

[0043] In the illustrative example, flight control modules **212** are connected to data bus system **208**. Each of flight control modules **212** generates and sends 20 commands **216** onto data bus system **208** to control flight control surfaces **206** on aircraft **202**. Each of flight control modules **212** may generate commands **216** for all of flight control surfaces **206**.

[0044] In the illustrative example, commands **216** for flight control surface **222** are directed towards actuator control modules **210** assigned to flight control surface **222**. 25 In other words, commands **216** are processed by actuator control modules **210** to move flight control surface **222** to a desired position.

[0045] Actuator control modules **210** and flight control modules **212** communicate over data bus system **208** using point-to-point connections **224**. For example, flight

control modules **212** send commands **216** onto data bus system **208** for use by one or more of actuator control modules **210**.

[0046] As depicted, actuator control modules **210** and flight control modules **212** determine whether error **226** is present in commands **216** sent onto data bus system

5 **208** by flight control modules **212**. In these illustrative example, actuator control module **214** determines whether error **226** is present in commands **216** that are directed to actuator control module **214** for flight control surface **222**. Other ones of actuator control modules **210** also may determine whether error **226** is present in commands **216** that are directed to actuator control module **214**.

10 [0047] Error **226** may take different forms. Error **226** may occur through timing issues. The timing issues may be present when commands **216** are received late, out of sequence, or not received at all by actuator control module **214** when compared to the receipt of commands **216** from different ones of flight control modules **212**. For example, error **226** may be present if the timing between 15 commands **216** sent onto data bus system **208** by flight control modules **212** are received at different times in which those times are far enough apart to be undesired.

20 [0048] For example, if a command to move a control surface is received later than desired, moving the control surface at that time may cause undesired movement of aircraft **202**. As a result, that command is considered to be error **226** because of the timing of when the command was received.

25 [0049] In one example, a window may start when the first command is received from a flight control module and have a selected period of time. If other commands to control the flight control surface received from other flight control modules are outside of the window, those commands may be considered to have error **226**. In another illustrative example, error **226** may be present if a difference is present in values identified in commands for positions of an actuator, an amount of movement identified in commands for the actuator are different, or the difference is greater than

a threshold between commands **216** sent to actuator control module **214** from flight control modules **212**.

[0050] The results of the determinations made by actuator control modules **210** may be returned in responses **228**. For example, actuator control modules **210** send 5 responses **228** to commands **216** indicating whether error **226** has been identified as being present in commands **216** by actuator control modules **210**. In the illustrative example, flight control modules **212** determine whether error **226** is present in commands **216** sent onto data bus system **208** based on at least one of commands **216** sent onto data bus system **208** or responses **228** to commands **216** sent by 10 actuator control modules **210**.

[0051] As used herein, the phrase "at least one of," when used with a list of items, means different combinations of one or more of the listed items may be used and only one of each item in the list may be needed. In other words, at least one of means any combination of items and number of items may be used from the list but 15 not all of the items in the list are required. The item may be a particular object, thing, or a category.

[0052] For example, without limitation, "at least one of item A, item B, or item C" may include item A, item A and item B, or item B. This example also may include item A, item B, and item C or item B and item C. Of course, any combinations of these 20 items may be present. In other examples, "at least one of" may be, for example, without limitation, two of item A; one of item B; and ten of item C; four of item B and seven of item C; or other suitable combinations.

[0053] In this illustrative example, flight control modules **212** receive responses **228** and may use responses **228** to determine whether error **226** is present. Further, 25 flight control modules **212** also make their own determinations from examining commands **216** as to whether error **226** is present in addition to or in place of examining responses **228**.

[0054] As depicted, communications between flight control modules **212** and actuator control modules **210** are managed based on error **226** identified as being

present in commands **216** sent onto data bus system **208** by a group of flight control modules **212** when error **226** is identified in commands **216**. In particular, the use of point-to-point connections **224** is managed based on the identification of error **226**. Analysis of error **226** may indicate that point-to-point connection **230** in point-to-point

5 connections **224** results in the receipt of errors that are greater than desired.

[0055] For example, flight control modules **212** determine whether to continue to use point-to-point connection **230** between particular flight control module **232** in flight control modules **212** and actuator control module **214** based on error **226** identified. In this illustrative example, the absence of point-to-point connection **230** may also

10 result in particular flight control module **232** being unused by actuator control module **214** that communicates with particular flight control module **232** over point-to-point connection **230** having a greater than desired error level.

[0056] The management of point-to-point connections **224** may occur as group decision **234**. For example, group decision **234** may be performed by flight control

15 modules **212**.

[0057] Flight control modules **212** may perform group decision **234** using various mechanisms. As one example, majority voting may be used by flight control modules **212**. For example, flight control modules **212** may each evaluate received responses **228** from actuator control modules **210** over point-to-point connections

20 **224** that identify whether error **226** is identified in commands **216**. In this example, when error **226** is identified, each flight control module in flight control modules **212** may then make an individual vote regarding which point-to-point connection in point-to-point connections **224** caused error **226**. Further in this example, group decision **234** as to the cause of error **226** may be based on majority vote of the flight control

25 modules **212**. As used herein, majority vote is at least one of greater than fifty (50) percent of the votes, or some other suitable percentage.

[0058] Thus, when errors are absent in the received commands, the commands are in congruence. As used herein, congruence of received commands means the commands were received within a desired period of time, no differences are present

between the commands, and no other types of errors are present in the commands. For example, congruence between commands received in messages from flight control modules means the commands are received in the messages within the period of time for receiving the commands from the flight control modules, no 5 differences are present between the received commands, and no other types of errors are present in the messages received from the flight control modules. In this manner, flight control system **204** may be an input congruence system for flight control surfaces **206** on aircraft **202**.

[0059] Actuator control modules **210** and flight control modules **212** may be 10 implemented in software, hardware, firmware or a combination thereof. When software is used, the operations performed by actuator control modules **210** and flight control modules **212** may be implemented in program code configured to run on hardware, such as a processor unit. When firmware is used, the operations performed by actuator control modules **210** and flight control modules **212** may be 15 implemented in program code and data and stored in persistent memory to run on a processor unit. When hardware is employed, the hardware may include circuits that operate to perform the operations in actuator control modules **210** and flight control modules **212**.

[0060] In the illustrative examples, the hardware for the processor units may take the 20 form of a circuit system, an integrated circuit, an application specific integrated circuit (ASIC), a programmable logic device, or some other suitable type of hardware configured to perform a number of operations. With a programmable logic device, the device may be configured to perform the number of operations. The device may be reconfigured at a later time or may be permanently configured to perform the 25 number of operations. Examples of programmable logic devices that may be used for processor units include, for example, a programmable logic array, a programmable array logic, a field programmable logic array, a field programmable gate array, and other suitable hardware devices. Additionally, the processes may be implemented in organic components integrated with inorganic components and may

be comprised entirely of organic components excluding a human being. For example, the processes may be implemented as circuits in organic semiconductors.

5 [0061] As depicted, each of flight control modules **212** is comprised of processor units that are dissimilar to each other and each of actuator control modules **210** is comprised of processor units that are dissimilar to each other. For example, one processor unit in the module may be implemented using a computer microprocessor while the other processor in the module may be implemented using a digital signal processor. As another example, two computer microprocessors may be used having different processor architectures.

10 [0062] The illustration of flight control environment **200** in **Figure 2** is not meant to imply physical or architectural limitations to the manner in which an illustrative embodiment may be implemented. Other components in addition to or in place of the ones illustrated may be used. Some components may be unnecessary. Also, the blocks are presented to illustrate some functional components. One or more of 15 these blocks may be combined, divided, or combined and divided into different blocks when implemented in an illustrative embodiment.

10 [0063] For example, a portion of flight control system **204** may use conventional controls in addition to the fly-by-wire system. Further, flight control system **204** may control other types of devices other than flight control surfaces **206**. For example, 20 flight control system **204** also may control the engines on aircraft **202**.

20 [0064] As yet another example, a network may be used in addition to or in place of data bus system **208** to provide communications between actuator control modules **210** and flight control modules **212**. In still yet another example, group decision **234** may also be performed using actuator control modules **210** and flight control 25 modules **212**. Further, some number of flight control modules **212** may be used rather than all the modules in some illustrative examples.

[0065] In the illustrative example, only actuator control modules **210** send responses **228** to flight control modules **212**. As another example, flight control modules **212**

also may send responses 228 from making a determination as to whether error 226 is present in commands 216 sent to actuator control modules 210.

[0066] With reference next to **Figure 3**, an illustration of a block diagram of a message is depicted in accordance with an illustrative embodiment. As depicted,

5 message 300 is an example of a message sent from a flight control module to an actuator control module that includes command 302. Command 302 in message 300 is an example of a command in commands 216 in **Figure 2**. For example, command 302 may include value 304 identified in a signal from a flight control to send to actuator 306 to control a flight control surface. Actuator 306 is an example 10 of an actuator in actuators 220 in **Figure 2**.

[0067] In this illustrative example, message 300 includes a number of different fields. As depicted, message 300 includes command 302, message counter 310, flight control module identifier 312, actuator control module identifier 314, and cyclic redundancy check value 308.

15 [0068] Message counter 310 counts the number of messages that have been sent from a flight control module as identified by flight control module identifier 312 when message 300 is generated and sent by the flight control module. Actuator control module identifier 314 identifies an actuator control module that message 300 is being sent to. For example, actuator control module identifier 314 may be a final 20 destination of message 300 where message 300 will be received.

[0069] As depicted, cyclic redundancy check (CRC) value 308 is used to ensure no errors are present in message 300 received by the actuator control module. Cyclic redundancy check value 308 is set before message 300 is sent over a connection between the flight control module and the actuator control module.

25 [0070] Turning to **Figure 4**, an illustration of a block diagram of information used by flight control modules and actuator control modules in the processing of commands is depicted in accordance with an illustrative embodiment. As depicted, information 400 includes a number of different fields for processing commands in flight control environment 200.

[0071] As depicted, information **400** includes a group of mappings of flight control modules to actuator control modules **402**, a group of flight control module message counters **404**, and a group of mappings of actuator control modules to actuators **406**. The group of mappings of flight control modules to actuator control modules **402** identifies connections between multiple flight control modules and actuator control modules. When an error is present in commands sent using a connection identified by a mapping, the mapping is changed to exclude the connection. This change is present until maintenance can be performed in this illustrative example. Similarly, the group of mappings of actuator control modules to actuators **406** identifies connections between actuator control modules and actuators that control flight control surfaces.

[0072] In this illustrative example, the group of flight control module message counters **404** is used in messages sent between flight control modules and actuator control modules. The group of flight control module message counters **404** are used to indicate the sequence of messages sent from the flight control module.

[0073] Turning next to **Figures 5A** and **5B**, an illustration of a flowchart of a process for processing commands in a flight control environment is depicted in accordance with an illustrative embodiment. The process illustrated in **Figures 5A** and **5B** may be implemented by flight control modules **212**, actuator control modules **210**, data bus system **208**, and actuators **220** in flight control environment **200** in **Figure 2**.

[0074] For example, flight control module **502**, flight control module **504**, and flight control module **506** are an example of multiple flight control modules in flight control modules **212** in **Figure 2** that receive signals from a flight control for controlling a flight control surface. Data bus system **508** is an example of data bus system **208** in **Figure 2**. Actuator control module **510**, actuator control module **512**, actuator control module **514**, and actuator control module **516** are an example of actuator control modules **210** in **Figure 2**. Actuator **518** is an example of an actuator in actuators **220** in **Figure 2**.

[0075] The process begins with flight control module **502**, flight control module **504**, and flight control module **506** generating and sending commands in messages to data bus system **508** (operation **520**). In the illustrative example, each message sent in operation **520** includes a command generated by the flight control module 5 based on a signal received at the flight control module. The messages may also include a flight control module identifier and an actuator control module identifier. For example, flight control module **502** may send a message that includes an actuator control module identifier that identifies actuator control module **510** and another message that identifies actuator control module **512**.

10 [0076] The process receives the commands in the messages from data bus system **508** at actuator control module **510**, actuator control module **512**, actuator control module **514**, and actuator control module **516** (operation **522**). For example, actuator control module **510** may receive messages from data bus system **508** that have actuator control module **510** as a destination of the message. In this example, 15 actuator control module identifiers in the received messages point to actuator control module **510**. Further in this depicted example, the commands received in the messages at actuator control module **510** include an actuator identifier of an actuator assigned to actuator control module **510** in a group of mappings of actuator control modules to actuators.

20 [0077] The process next identifies whether errors are present in the commands based on the received messages (operation **524**). For example, the process may determine whether an error is present in a command in operation **524** based on at least one of a difference between the command and other commands received in other messages, a cyclic redundancy value in the message is not correct, a 25 message counter in the message is out of sequence, or some other suitable rule or standard for determining whether an error is present in a command.

[0078] The process then generates a signal at actuator control module **510** and sends the signal from actuator control module **510** to actuator **518** (operation **526**). The process generates the signal at actuator control module **510** based on the

commands in the messages received at actuator control module **510** including the actuator identifier of actuator **518** assigned to actuator control module **510** in the group of mappings of actuator control modules to actuators. The process next receives the signal at actuator **518** and operates the flight control surface based on 5 the received signal (operation **528**).

[0079] The process generates and sends replies for the messages the actuator control modules received to data bus system **508** (operation **530**). The replies generated in operation **530** identify the flight control modules that sent the messages as final destinations of the replies and include any errors that the actuator control 10 module may have identified in operation **524**. The process next receives the replies at flight control module **502**, flight control module **504**, and flight control module **506** based on the final destinations identified in the replies (operation **532**).

[0080] The process identifies errors included in the replies (operation **534**). As depicted, after the process identifies errors included in the replies, the process next 15 sends the identified errors included in the replies to other flight control modules in flight control module **502**, flight control module **504**, and flight control module **506** using data bus system **508** (operation **536**). The process then receives the errors included in the replies from data bus system **508** at the other flight control modules (operation **538**).

20 [0081] The process next generates and sends replies from the other flight control modules to data bus system **508** that include the errors the other flight control modules received from data bus system **508** (operation **540**). The process receives the replies from data bus system **508** at flight control module **502**, flight control module **504**, and flight control module **506** (operation **542**).

25 [0082] The process then identifies errors in the replies received from data bus system **508** (operation **544**). The process next sends identified errors in the replies to the other flight control modules using data bus system **508** (operation **546**). The process receives the replies at flight control module **502**, flight control module **504**, and flight control module **506** from data bus system **508** (operation **548**).

[0083] The process then determines whether to continue to use point-to-point connections with actuator control modules based on identified errors in replies sent from ACMs and identified errors in the replies sent from FCMs (operation 550). When an error is identified in a point-to-point connection between a flight control 5 module and an actuator control module, the identification of the error may be used to update mappings of flight control modules to actuator control modules. For example, the connection may be removed in the mappings for the duration of a flight of the aircraft.

[0084] With reference next to **Figure 6**, an illustration of a block diagram of 10 components of a flight control environment is depicted in accordance with an illustrative embodiment. As depicted, flight control environment **600** is an example of flight control environment **200** in **Figure 2**.

[0085] In this illustrative example, flight control environment **600** includes data bus system **602**. Data bus system **602** is an example of data bus system **208** in **Figure 15 2**. Data bus system **602** is used for communications between flight control modules **606** and actuator control modules **608** in this illustrative example. Data bus system **602** is also used for communications between flight control modules **606** and other flight control modules in flight control modules **606** in this illustrative example.

[0086] As depicted, processor unit A **618** and processor unit B **620** form a plurality of 20 processor units in flight control module **616**. In the illustrated example, processor unit A **618** generates and sends commands to actuator control modules **608**, and processor unit B **620** processes monitoring messages. For example, a monitoring message may be a reply sent from an actuator control module after receiving a command from flight control module **616**.

[0087] In this illustrative example, processor unit C **624** and processor unit D **626** 25 form a plurality of processor units in actuator control module **622**. In the illustrated example, processor unit C **624** processes commands received from flight control modules **606**, and processor unit D **626** identifies whether errors exist in commands and sends replies to flight control modules **606**.

[0088] As depicted, flight control modules **606** include flight control module **616**, flight control module **628**, and flight control module **630**. As also depicted, actuator control modules **608** include actuator control module **622**, actuator control module **632**, actuator control module **634**, and actuator control module **636**. In this 5 illustrative example, actuator control module **622** is assigned to send signals to actuator **638**; actuator control module **632** is assigned to send signals to actuator **640**; actuator control module **634** is assigned to send signals to actuator **642**; and actuator control module **636** is assigned to send signals to actuator **644**.

[0089] Arrows **646** are a logical representation of point-to-point connections in data 10 bus system **602**, in this illustrative example. Arrows **646** do not show all of the connections used in data bus system **602** and also do not show all of the directions of flow of commands, replies, and other types of messages sent over connections in data bus system **602**. Other arrows for the connections and other connections may also be included in data bus system **602**.

15 [0090] Turning next to **Figure 7**, an illustration of a flowchart of a process for controlling flight control surfaces on an aircraft is depicted in accordance with an illustrative embodiment. The process illustrated in **Figure 7** may be implemented in flight control system **204** in **Figure 2**

[0091] The process begins by receiving signals from a group of flight controls in a 20 cockpit of an aircraft (operation **700**). These signals may be analog signals, digital signals, or some combination thereof. These signals may be generated from flight controls such as a flight stick, rudder pedals, a throttle, or some other suitable type of control. As depicted, these flight controls may be controls operated by a pilot. In other illustrative examples, the flight controls may be devices sending sensor data or 25 other information needed in the flight control modules to provide automatic adjustments to the flight of aircraft without input from the pilots.

[0092] The flight control modules generate commands when these signals are received from the group of flight controls (operation **702**). The flight control modules

then send the commands onto a data bus system from flight control modules (operation **704**).

[0093] The flight control modules and the actuator control modules determine whether an error is present in the commands sent onto the data bus system 5 (operation **706**). The process manages point-to-point connections between the flight control modules and the actuator control modules based on whether the error is present in the commands sent onto the data bus system (operation **708**), with the process terminating thereafter.

[0094] Turning now to **Figure 8**, an illustration of a flowchart of a process for 10 processing signals from a flight control is depicted in accordance with an illustrative embodiment. The process illustrated in **Figure 8** may be implemented by flight control modules **212** in flight control system **204** in **Figure 2**.

[0095] The process begins by creating point-to-point connections between flight control modules and actuator control modules, and between the flight control 15 modules (operation **800**). In this illustrative example, the point-to-point connections are similar to those in a data bus system in a computer using a point-to-point protocol. For example, a transmitter and a receiver of a flight control module may be used for sending and receiving messages over the data bus system using the point-to-point connections, and for creating the point-to-point connections.

20 [0096] The process receives signals from a flight control-external sensing device (operation **802**). The signals received are for controlling a flight control surface. The process next generates commands and other information using the signals (operation **804**). The other information may be selected from at least one of a cyclic redundancy check (CRC) value for the command, an identifier, or other suitable 25 information. For example, the identifier may be a flight control module message counter indicating a sequence of commands sent in messages by a flight control module to an actuator control module. In this illustrative example, the flight control module message counter is incremented with each command sent in a message by the flight control module to the actuator control module.

[0097] The process sends the commands and the other information to the actuator control modules over the point-to-point connections (operation **806**). For example, a flight control module may send the command and other information in messages to each of the actuator control modules that the flight control module has a point-to-point connection with.

[0098] The process then receives reply messages sent from the actuator control modules over the point-to-point connections (operation **808**), with the process terminating thereafter. A received reply from an actuator control module indicates whether that actuator control module received the command sent by the flight control module and whether that actuator control module determined that an error is present in the command in the message that it received. Operations **802-808** may be repeated any number of times to process additional signals received from the flight control.

[0099] Turning now to **Figure 9**, an illustration of a flowchart of a process for processing commands is depicted in accordance with an illustrative embodiment. The process illustrated in **Figure 9** may be implemented by actuator control module **214** in flight control system **204** in **Figure 2**. For example, the process illustrated in **Figure 9** may be implemented by a processor unit in actuator control module **214**.

[0100] The process begins by receiving commands in messages from flight control modules over point-to-point connections with the flight control modules (operation **900**). The received commands may be a portion of the commands sent by the flight control modules in operation **808** in **Figure 8**. For example, there may be a problem with one of the point-to-point connections.

[0101] The process determines whether errors are present in the commands (operation **902**). For example, the process may determine whether an error is present in a received command based on a difference between the received command and other received commands.

[0102] The process next generates replies for the commands that indicate whether errors are present in the commands (operation **904**). The process then

sends the replies over the point-to-point connections to the flight control modules (operation **906**), with the process terminating thereafter. The replies are received by flight control modules in operation **808** in **Figure 8**. Operations **900-906** may be repeated any number of times to process additional commands received from flight 5 control modules.

[00103] Turning now to **Figure 10**, an illustration of a flowchart of a process for determining whether an error is present in commands received in messages from flight control modules is depicted in accordance with an illustrative embodiment. The process illustrated in **Figure 10** may be implemented by actuator control module 10 **214** in flight control system **204** in **Figure 2**. The operations in this process are an example of operations to perform operations **900-904** in **Figure 9**.

[00104] The process begins by identifying flight control modules to receive commands in messages from (operation **1000**). For example, the flight control modules to receive commands in messages from may be based on a group of 15 mappings of flight control modules to actuator control modules.

[00105] The process receives a command in a message from at least one of the flight control modules over point-to-point connections with the flight control modules (operation **1002**). The process adds the received message to a group of messages (operation **1004**).

[00106] The process next determines whether the group of messages includes a message from all of the flight control modules identified to receive commands from (operation **1006**). As depicted, when the group of messages does not include a message from all of the flight control modules identified to receive commands from, the process next determines whether a period of time has passed for receiving 25 commands in messages from the flight control modules (operation **1008**).

[00107] As depicted, when the period of time has not passed for receiving commands in messages from the flight control modules, the process determines whether additional commands to process are present (operation **1009**). As depicted,

when additional commands are present for processing, the process continues to operation **1002**. Otherwise, the process continues to operation **1008**.

[00108] Further, when the group of messages include a message from all of the flight control modules identified to receive commands from in operation **1006** or 5 when the period of time has passed for receiving commands in messages from the flight control modules in operation **1008**, the process then identifies commands and other information in the group of messages for determining whether an error is present in the commands (operation **1010**). The other information may include cyclic redundancy check values, message counters, and other suitable types of 10 information for use in determining whether errors are present in the command.

[00109] The process then selects an unprocessed command in the identified commands (operation **1012**). The process determines whether an error is present in the command (operation **1014**). The error is present when at least one of a cyclic redundancy check value in the other information for the command is incorrect, the 15 counter in the other information for the command is out of sequence, or other suitable reasons.

[00110] For example, the process may calculate cyclic redundancy check values for the group of messages and compare the calculated cyclic redundancy check values to the identified cyclic redundancy check values to determine whether 20 an error is present in the commands. As another example, the process may compare the identified message counters with flight control module message counters.

[00111] As another example, the messages may be encoded using encoding schemes selected from at least one of parity bits, Manchester encoding, or other 25 suitable encoding schemes. In this example, when the message is decoded using the selected encoding scheme, the decoding process of the encoding scheme identifies any errors that may have occurred in transmission of the message.

[00112] As depicted, when no errors are present in the command, the process generates a reply for the flight control module that sent the command that indicates

an error is not present in the command received from the flight control module (operation 1016). When errors are present in the command, the process generates a reply for the flight control module that sent the command that includes the errors present in the command received from the flight control module (operation 1018).

5 [00113] The process next determines whether an unprocessed command is present in the identified commands (operation 1020). When an unprocessed command is present in the identified commands, the process returns to operation 1012. The process terminates when the identified commands have been processed.

10 [00114] Turning now to **Figure 11**, an illustration of a flowchart of a process for processing commands is depicted in accordance with an illustrative embodiment. The process illustrated in **Figure 11** may be implemented by actuator control module 214 in flight control system 204 in **Figure 2**. For example, the process illustrated in **Figure 11** may be implemented by a processor unit in actuator control module 214.

15 [00115] The process begins by receiving commands in messages from flight control modules over point-to-point connections with the flight control modules (operation 1100). The process selects an unprocessed command in the received commands (operation 1102). The process also identifies an actuator in the command and a value to send to the actuator in the command (operation 1104).

20 [00116] The process next determines whether the actuator control module is assigned to send signals to the actuator (operation 1106). For example, the process may determine whether the actuator control module is assigned to send signals to the actuator control module based on a group of mappings of actuator control modules to actuators. When the actuator control module is not assigned to send signals to the actuator identified in the command, the process continues to operation 25 1112.

[00117] As depicted, when the actuator control module is assigned to send signals to the actuator, the process next determines if an error is present in the command (operation 1108). For example, the processor unit implementing

operation **1108** may use the determinations from another processor unit in the actuator control module that implemented operation **902** in **Figure 9**.

[00118] As also depicted, when the process determines no errors are present in the command and the actuator control module is assigned to send signals to the actuator identified in the command, the process next generates and sends a signal to the actuator based on the value identified in the received command (operation **1110**). The process then determines whether more unprocessed commands are in the received commands (operation **1112**). As depicted, when all of the received commands have not been processed, the process continues to operation **1102**.
5 When all of the received commands have been processed, the process terminates.
10 Operations **1100-1112** may be repeated any number of times to process additional commands received from flight control modules.

[00119] Turning now to **Figures 12A** and **12B**, an illustration of a flowchart of a process for identifying whether errors are present in a flight control system is depicted in accordance with an illustrative embodiment. The process illustrated in **Figures 12A** and **12B** is implemented by flight control modules **212** in flight control system **204** in **Figure 2**. For example, the process illustrated in **Figures 12A** and **12B** may be implemented by processor units in flight control modules **212**. In this example, the processor units in flight control modules **212** may execute the operations in **Figures 12A** and **12B** in parallel. The operations in **Figures 12A** and **12B** are described from the point of view of a flight control module of multiple flight control modules that process signals from a flight control for a flight control surface.
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[00120] The process begins by receiving replies from actuator control modules over point-to-point connections the flight control module has with the actuator control modules (operation **1200**). Each reply indicates whether that actuator control module received a command in a message sent by the flight control module and whether that actuator control module determined that an error is present in the command that it received from the flight control module.
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[00121] The process next makes determinations of whether errors are present for the point-to-point connections with the actuator control modules based on the replies received from the actuator control modules (operation 1202). The determination of whether errors are present in the point-to-point connection with an actuator control module involves all of the components of the point-to-point connection. These components include at least one of a transmitter of the flight control module, the data bus system, a receiver of the actuator control module, a transmitter of the actuator control module, or other suitable types of components of the point-to-point connection. The error is present when at least one of the replies is not received from the actuator control module over the point-to-point connection, the reply includes the determination that an error is present in the command the actuator control module received, or when another type of error is received indicating the point-to-point connection is bad.

[00122] The process generates a message that includes the determinations of whether errors are present in the point-to-point connections with the actuator control modules (operation 1204). The process sends the message generated to other flight control modules in the flight control system using point-to-point connections between the flight control modules (operation 1206). The flight control module and the other flight control modules are multiple flight control modules that process signals from a flight control for a flight control surface.

[00123] The process next receives messages generated by the other flight control modules that include the determinations that the other flight control modules made of whether errors are present in the point-to-point connections between the other flight control modules and the actuator control modules (operation 1208). The process sends replies to each of the messages that the flight control module received from the other flight control modules (operation 1210).

[00124] The process then makes determinations of whether errors are present in the point-to-point connections with the other flight control modules (operation 1212). The determination of whether errors are present in a point-to-point

connection with another flight control module involves all of the components used to send and receive a message over the point-to-point connection. These components include at least one of a transmitter of the flight control module, the data bus system, a receiver of the flight control module, a transmitter of the other flight control module,
5 a receiver of the other flight control module, or other suitable types of the point-to-point connection. An error is present in a point-to-point connection with another flight control module when at least one of the reply message is not received from the other flight control module over the point-to-point connection or when another type of error is received indicating the point-to-point connection is bad.

10 [00125] The process generates and sends messages that include the determinations of whether errors are present in the point-to-point connections with the other flight control modules (operation 1214). The process next receives messages sent from the other flight control modules that include the determinations made by the other flight control modules of whether errors are present in the point-
15 to-point connections between the flight control modules (operation 1216).

[00126] The process makes subsequent determinations of whether errors are present in the point-to-point connections between the flight control modules and the actuator control modules based on the determinations of whether errors are present in the point-to-point connections with the actuator control modules and the
20 determinations made by the flight control modules of whether errors are present in the point-to-point connections between the flight control modules (operation 1218). The process generates and sends messages that include the subsequent determinations of whether errors are present in the point-to-point connections between the flight control modules and the actuator control modules to the other
25 flight control modules (operation 1220).

[00127] The process then identifies errors in the point-to-point connections between the flight control modules and the actuator control modules based on the subsequent determinations of whether errors are present in the point-to-point connections between the flight control modules and the actuator control modules

(operation 1222), with the process terminating thereafter. When an error is identified in a point-to-point connection between a flight control module and an actuator control module, the error may be used to update mappings of flight control modules to actuator control modules. For example, the point-to-point connection may be 5 removed in the mappings for the duration of a flight of the aircraft.

[00128] The flowcharts and block diagrams in the different depicted embodiments illustrate the architecture, functionality, and operation of some possible implementations of apparatuses and methods in an illustrative embodiment. In this regard, each block in the flowcharts or block diagrams may represent at least one of 10 a module, a segment, a function, or a portion of an operation or step. For example, one or more of the blocks may be implemented as program code, in hardware, or a combination of the program code and hardware. When implemented in hardware, the hardware may, for example, take the form of integrated circuits that are manufactured or configured to perform one or more operations in the flowcharts or 15 block diagrams. When implemented as a combination of program code and hardware, the implementation may take the form of firmware.

[00129] In some alternative implementations of an illustrative embodiment, the function or functions noted in the blocks may occur out of the order noted in the figures. For example, in some cases, two blocks shown in succession may be 20 executed substantially concurrently, or the blocks may sometimes be performed in the reverse order, depending upon the functionality involved. Also, other blocks may be added in addition to the illustrated blocks in a flowchart or block diagram.

[00130] The illustrative embodiments of the disclosure may be described in the context of aircraft manufacturing and service method 1300 as shown in **Figure 13** 25 and aircraft 1400 as shown in **Figure 14**. Turning first to **Figure 13**, an illustration of a block diagram of an aircraft manufacturing and service method is depicted in accordance with an illustrative embodiment. During pre-production, aircraft manufacturing and service method 1300 may include specification and design 1302 of aircraft 1400 in **Figure 14** and material procurement 1304.

[00131] During production, component and subassembly manufacturing 1306 and system integration 1308 of aircraft 1400 in **Figure 14** takes place. Thereafter, aircraft 1400 in **Figure 14** may go through certification and delivery 1310 in order to be placed in service 1312. While in service 1312 by a customer, aircraft 1400 in 5 **Figure 14** is scheduled for routine maintenance and service 1314, which may include modification, reconfiguration, refurbishment, and other maintenance or service.

[00132] Each of the processes of aircraft manufacturing and service method 1300 may be performed or carried out by a system integrator, a third party, an 10 operator, or some combination thereof. In these examples, the operator may be a customer. For the purposes of this description, a system integrator may include, without limitation, any number of aircraft manufacturers and major-system subcontractors; a third party may include, without limitation, any number of vendors, subcontractors, and suppliers; and an operator may be an airline, a leasing 15 company, a military entity, a service organization, and so on.

[00133] With reference now to **Figure 14**, an illustration of a block diagram of an aircraft is depicted in which an illustrative embodiment may be implemented. In this example, aircraft 1400 is produced by aircraft manufacturing and service method 1300 in **Figure 13** and may include airframe 1402 with plurality of systems 1404 and 20 interior 1406. Examples of systems 1404 include one or more of propulsion system 1408, electrical system 1410, hydraulic system 1412, and environmental system 1414. Any number of other systems may be included. Although an aerospace example is shown, different illustrative embodiments may be applied to other industries, such as the automotive industry.

[00134] The apparatuses and methods embodied herein may be employed 25 during at least one of the stages of aircraft manufacturing and service method 1300 in **Figure 13**. One or more apparatus embodiments, method embodiments, or a combination thereof may be utilized during production stages, such as component and subassembly manufacturing 1306 and system integration 1308 in **Figure 13**.

One or more apparatus embodiments, method embodiments, or a combination thereof may be utilized while aircraft 1400 is in service 1312, during maintenance and service 1314 in **Figure 13**, or both. The use of a number of the different illustrative embodiments may substantially expedite the assembly of aircraft 1400, reduce the 5 cost of aircraft 1400, or both expedite the assembly of aircraft 1400 and reduce the cost of aircraft 1400.

[00135] Thus, the illustrative embodiments provide a method and apparatus for managing commands for flight control surfaces. One or more illustrative embodiments may use fly-by-wire systems for aircraft. The flight control system 10 implemented in accordance with an illustrative embodiment may provide input data congruency with respect to commands that are processed in a flight control system.

[00136] The description of the different illustrative embodiments has been presented for purposes of illustration and description, and is not intended to be exhaustive or limited to the embodiments in the form disclosed. Many modifications 15 and variations will be apparent to those of ordinary skill in the art. Further, different illustrative embodiments may provide different features as compared to other desirable embodiments. The embodiment or embodiments selected are chosen and described in order to best explain the principles of the embodiments, the practical application, and to enable others of ordinary skill in the art to understand the 20 disclosure for various embodiments with various modifications as are suited to the particular use contemplated.

EMBODIMENTS IN WHICH AN EXCLUSIVE PROPERTY OR PRIVILEGE IS CLAIMED ARE DEFINED AS FOLLOWS:

1. An apparatus comprising:

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a data bus system in an aircraft;

actuator control modules connected to the data bus system;

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an actuator control module, in the actuator control modules, configured to control a position of a flight control device, configured to control movement of the aircraft, based upon commands on the data bus system directed to the actuator control module; and

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flight control modules connected to the data bus system and configured to:

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generate the commands that control the flight control device, the commands being directed towards a group of actuator control modules assigned to the flight control device;

send the commands, to the flight control device, via point-to-point connection mappings designated by the flight control modules;

25

determine whether an error is present in the commands sent onto the data bus system by the flight control modules; and

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responsive to a determination of the error, designate an alternate point-to-point connection mapping for subsequent commands, such that, via alternate point-to-point connection mapping, the subsequent commands reach the flight control device error free.

2. The apparatus of claim 1, wherein communications between the flight control modules and the actuator control modules are managed based on the error identified as being present in the commands sent onto the data bus system by a group of the flight control modules.
5
3. The apparatus of claim 1 or 2, wherein the flight control modules are further configured to determine whether to continue to use a point-to-point connection between two flight control modules based on the error.
10
4. The apparatus of any one of claims 1 to 3, further comprising the point-to-point connection mappings configured to comprise the data bus system.
15
5. The apparatus of any one of claims 1 to 4, wherein the actuator control modules send responses to the commands indicating whether the error has been identified, by the actuator control modules, as being present in the commands.
20
6. The apparatus of claim 5, wherein the flight control modules are configured to determine whether the error is present in the commands sent onto the data bus system based on at least one of the commands sent onto the data bus system and the responses to the commands sent by the actuator control modules.
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7. The apparatus of any one of claims 1 to 6, further comprising the actuator control modules configured to send signals to actuators that move the flight control device and wherein a plurality of actuator control modules are assigned to the flight control device.
30
8. The apparatus of any one of claims 1 to 7, wherein:

each of the flight control modules comprises processor units that are dissimilar to any processor unit in any flight control module in the flight control modules; and

5 each actuator control module of the actuator control modules comprises a processor unit dissimilar to a processor unit in any of the actuator control modules.

9. The apparatus of claim 8, wherein any processor unit is selected from one of a 10 microprocessor, a digital signal processor, a circuit system, an integrated circuit, an application specific integrated circuit (ASIC), a programmable logic device, a programmable logic array, a programmable array logic, a field programmable logic array, and a field programmable gate array.

15 10. A flight control system comprising:

a data bus system in an aircraft;

actuator control modules connected to the data bus system;

20 an actuator control module, in the actuator control modules, configured to control a position of a flight control device, configured to control movement of the aircraft, based upon commands on the data bus system directed to the actuator control module; and

25 flight control modules connected to the data bus system and configured to:

30 generate the commands that control the flight control device on the aircraft, the commands being directed towards actuator control modules assigned to the flight control device;

send the commands to the flight control device via point-to-point connection mappings designated by the flight control modules;

5 determine whether an error is present in the commands sent onto the data bus system; and

10 responsive to a determination of the error, designate an alternate point-to-point connection mapping for subsequent commands to reach the flight control device error free.

11. The flight control system of claim **10** further comprising:

15 actuators that move the flight control device based upon signals sent to the actuators from the actuator control modules and wherein a plurality of actuator control modules are assigned to each of the flight control device.

20 12 The flight control system of any one of claims **10** or **11**, wherein the actuator control modules send responses to the commands indicating whether the error has been identified, by the actuator control modules, as being present in the commands by the actuator control modules.

25 13. The flight control system of claim **12**, wherein the flight control modules determine whether the error is present in the commands sent onto the data bus system based on at least one of: the commands sent onto the data bus, and the responses to the commands sent by the actuator control modules.

30 14. The flight control system of any one of claims **11** to **13**,

wherein each of the flight control modules is comprised of processor units that are dissimilar to each other and each of the actuator control modules is comprised of processor units that are dissimilar to each other; and

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further comprising the point-to-point connection mappings configured to comprise the data bus system using point-to-point connections.

10 **15.** A method for controlling a flight control device on an aircraft, the method comprising:

a flight control module determining a point-to-point connection mapping for sending a command to an actuator control module;

15 sending commands onto a data bus system from the flight control module;

20 determining, by the flight control module and actuator control module, whether an error is present in the commands sent onto the data bus system; and

25 using a determination of the error, the flight control module determining an alternative point-to-point connection mapping between the flight control module and the actuator control module, such that the commands reach the actuator control module error free via the alternative point-to-point connection mapping.

16. The method of claim **15** further comprising:

30 controlling, by the actuator control modules, positioning of a group of flight control devices on the aircraft based on whether the error is

present in the commands as determined by the flight control modules and the actuator control modules.

17. The method of claim **15** or **16** further comprising:

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determining whether to continue to use a point-to-point connection between a particular flight control module and a different flight control module in the flight control modules based on the error.

10 18. The method of claim **17** further comprising:

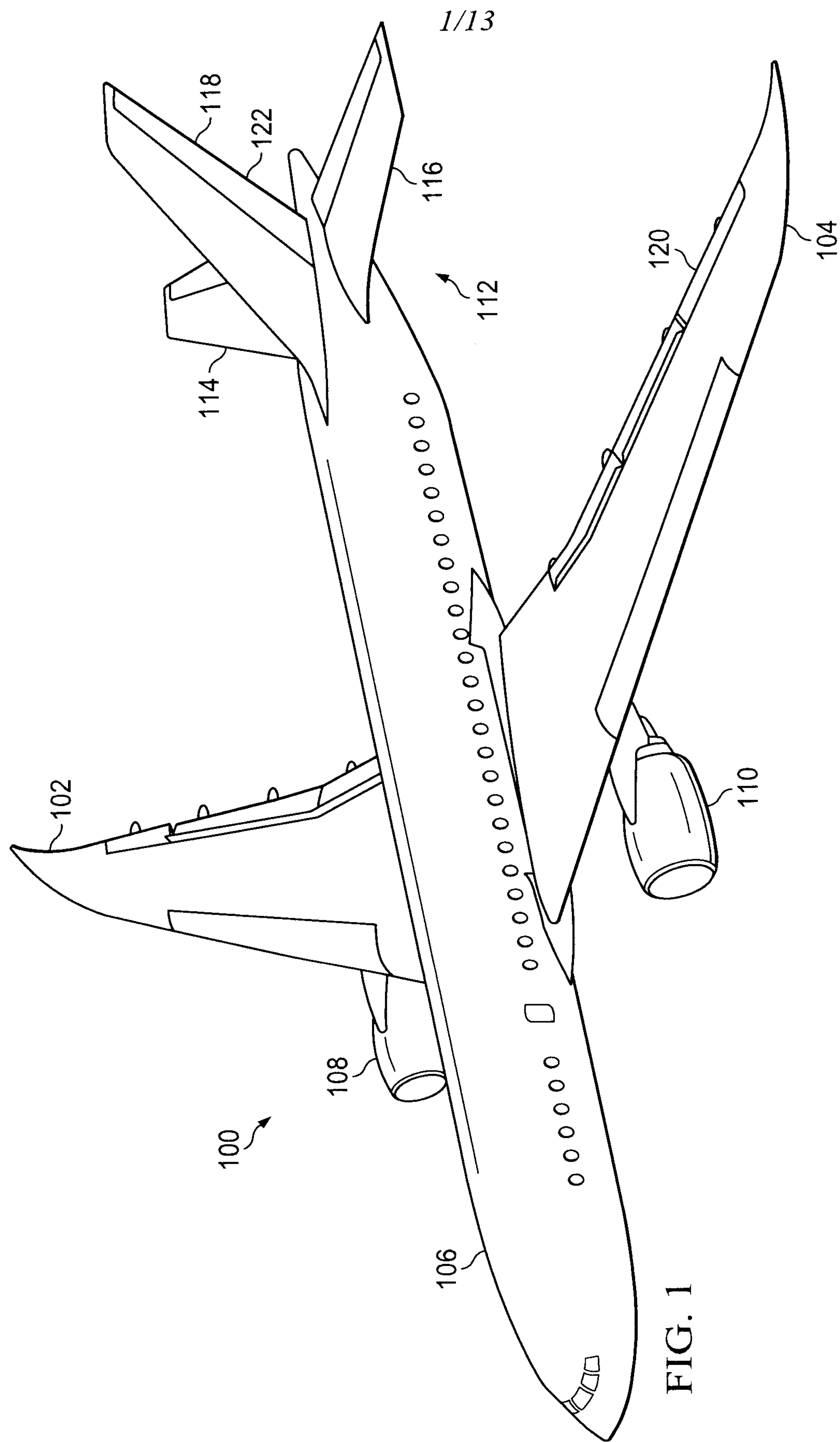
determining whether to continue to use the point-to-point connection between the flight control module and the actuator control module based on analysis, from a plurality of flight control modules, of the error.

15

19. The method of any one of claims **15** to **18** further comprising:

20 sending responses to the commands from the actuator control modules onto the data bus system, wherein the responses indicate whether the error has been identified as being present in the commands by the actuator control modules.

25 20. The method of any one of claims **15** to **19**, wherein each of the flight control modules in the flight control modules is comprised of processor units that are dissimilar to each other and each of the actuator control modules is comprised of processor units that are dissimilar to each other.



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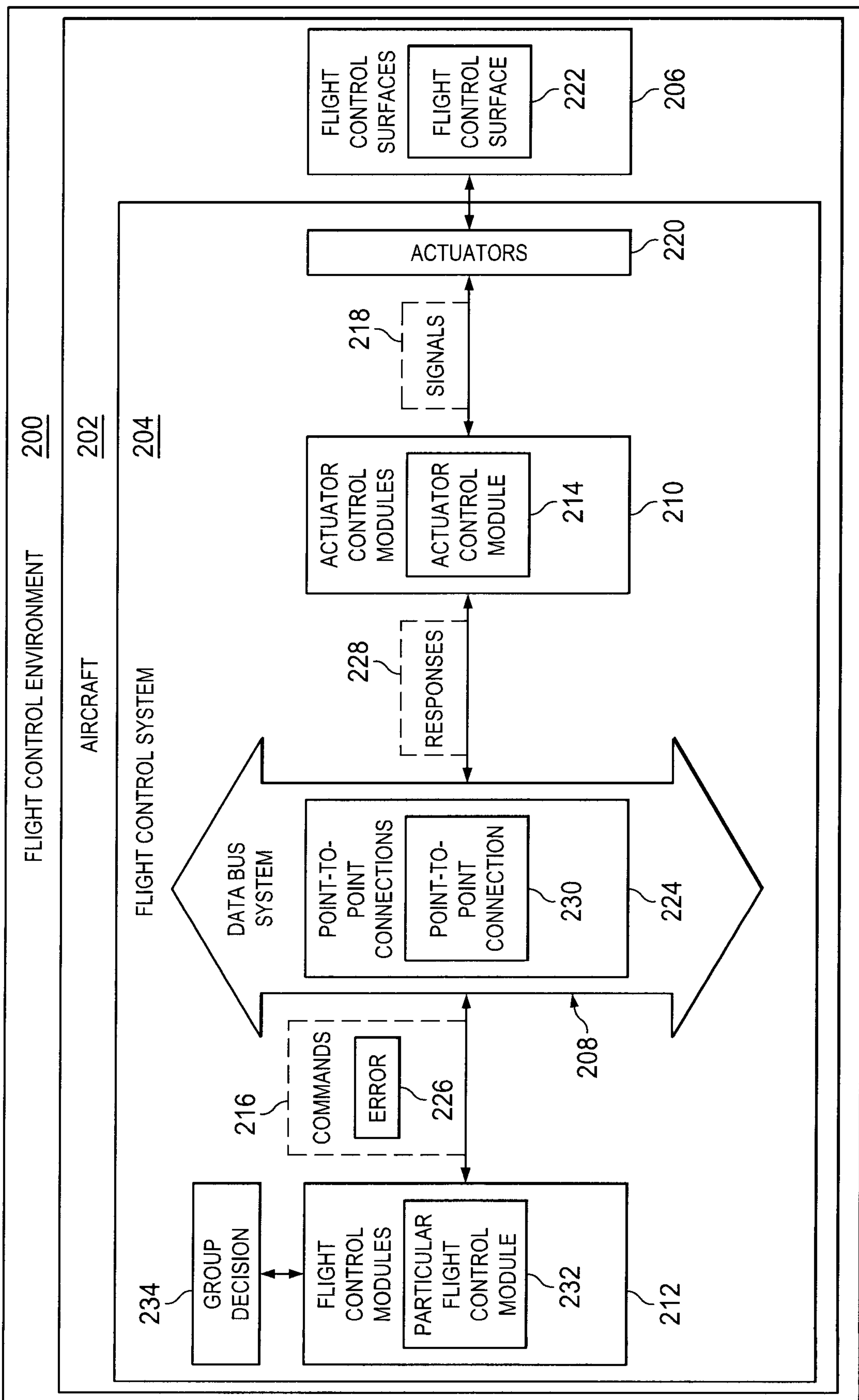


FIG. 2

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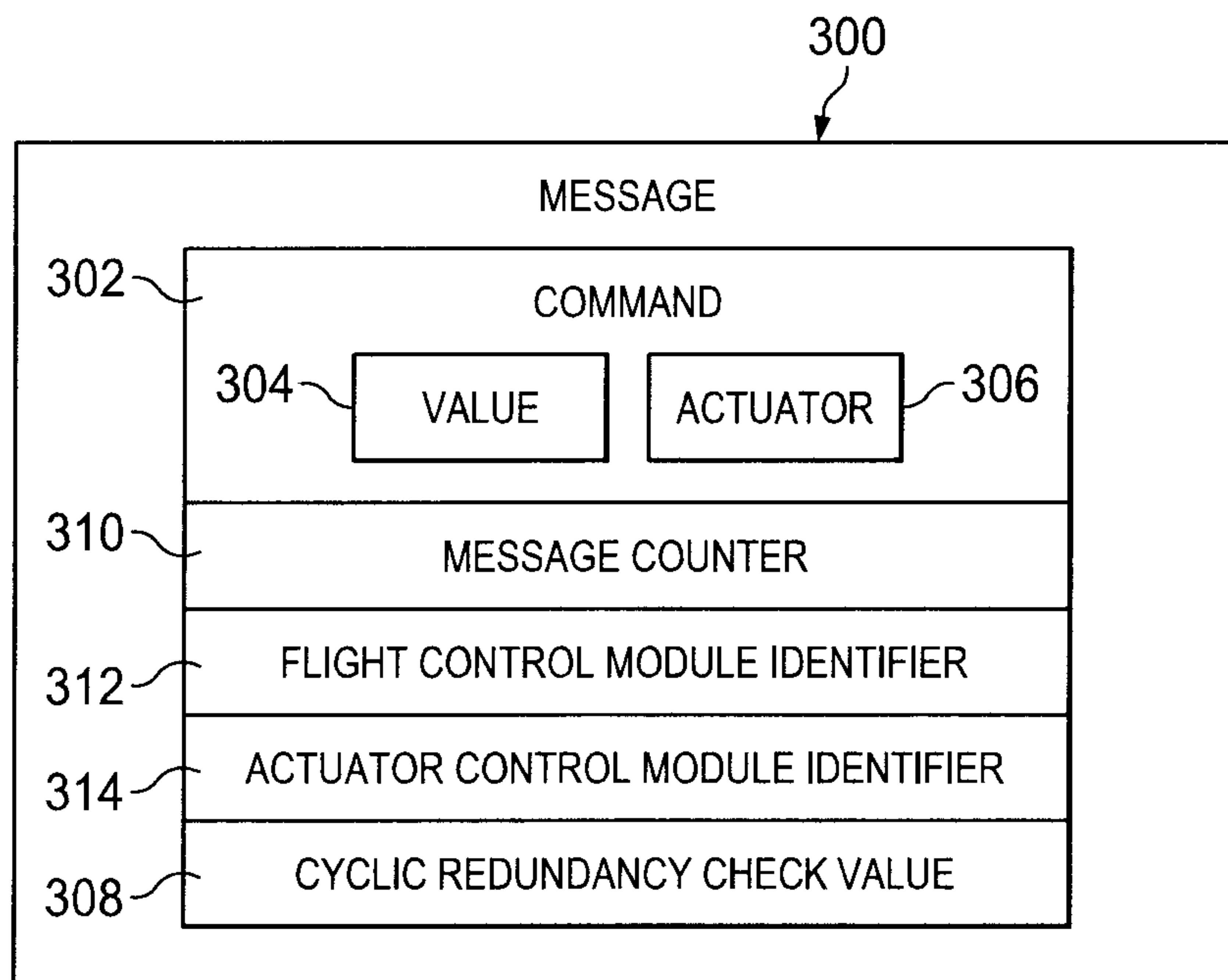


FIG. 3

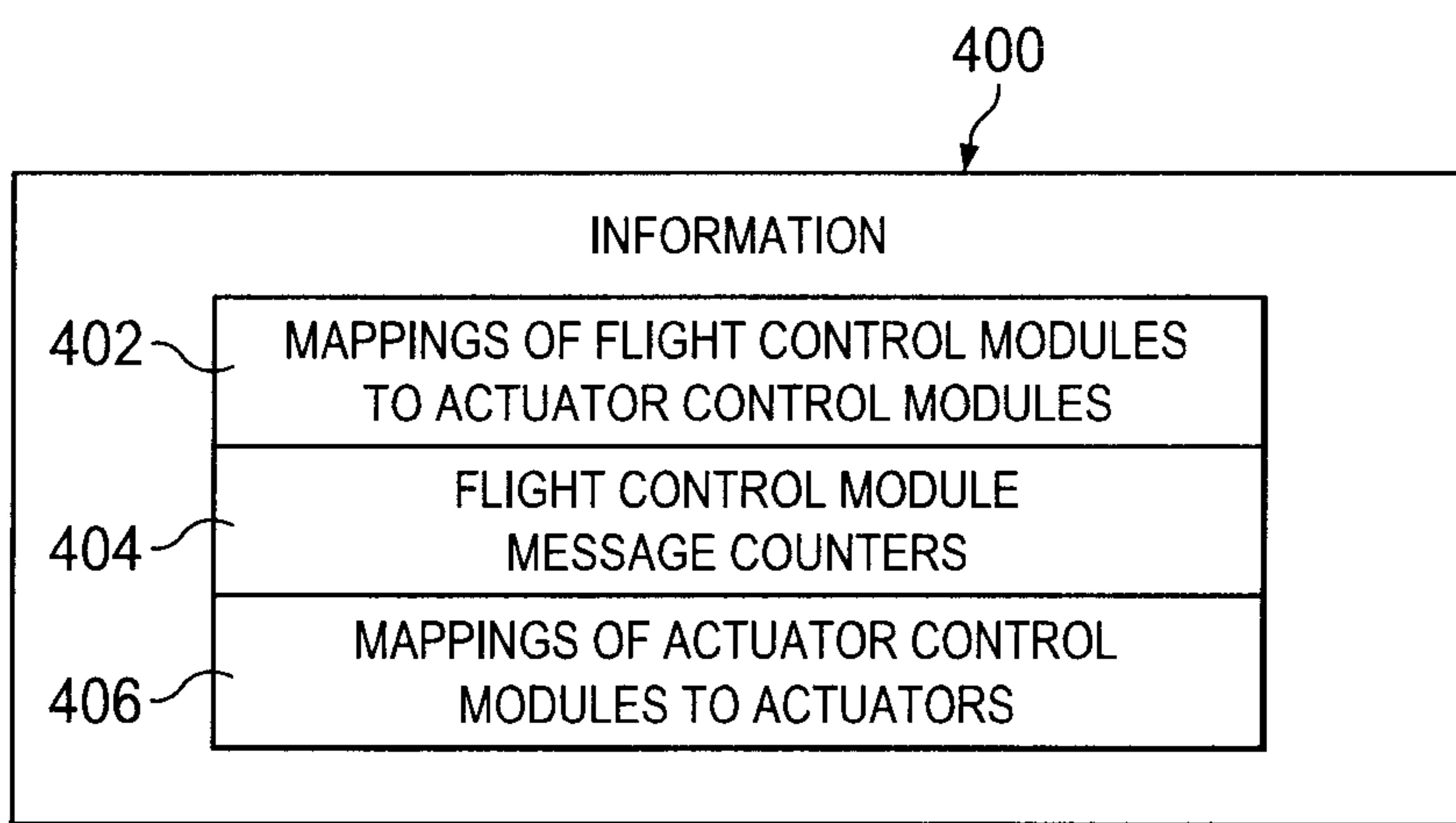


FIG. 4

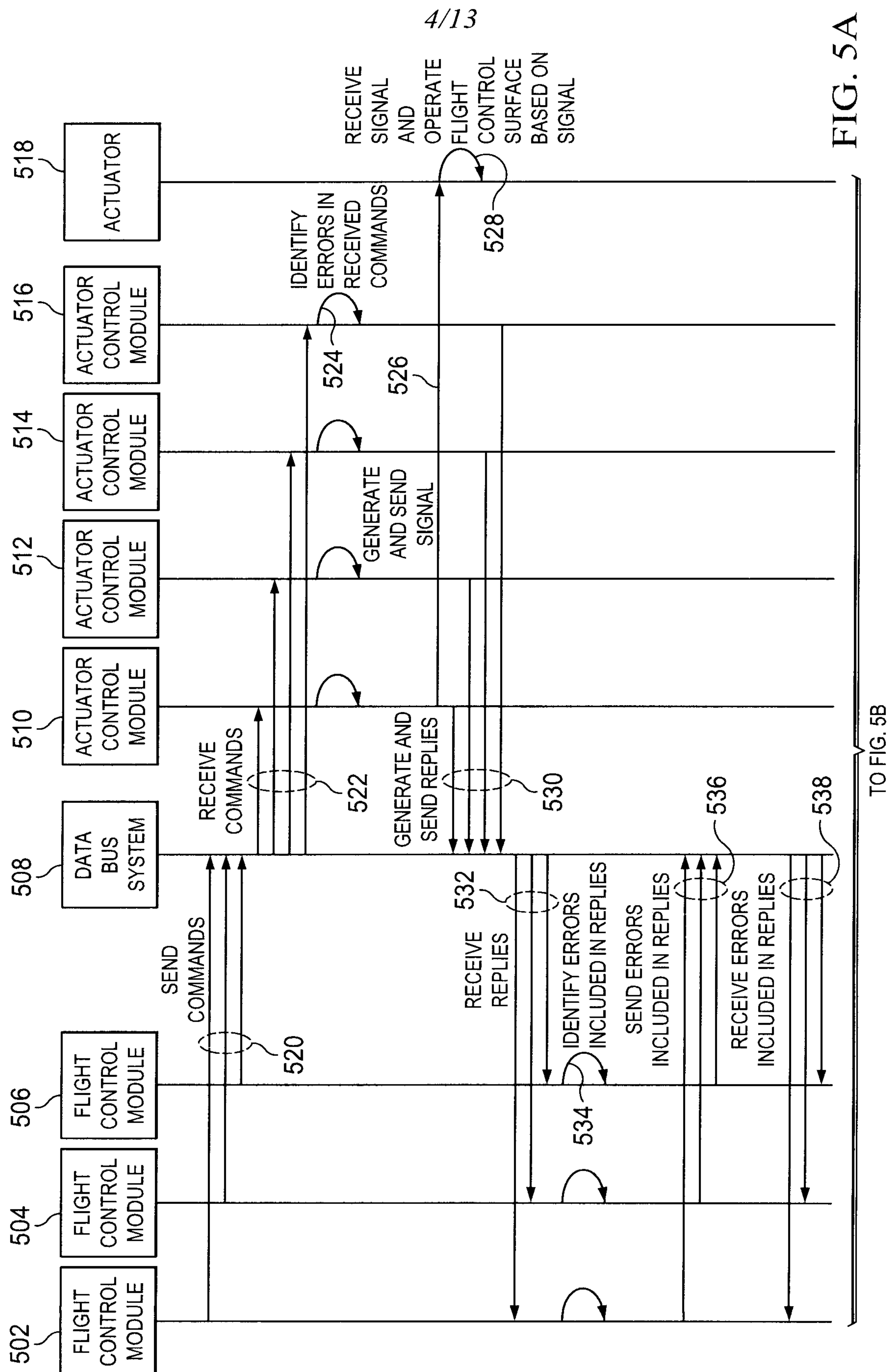
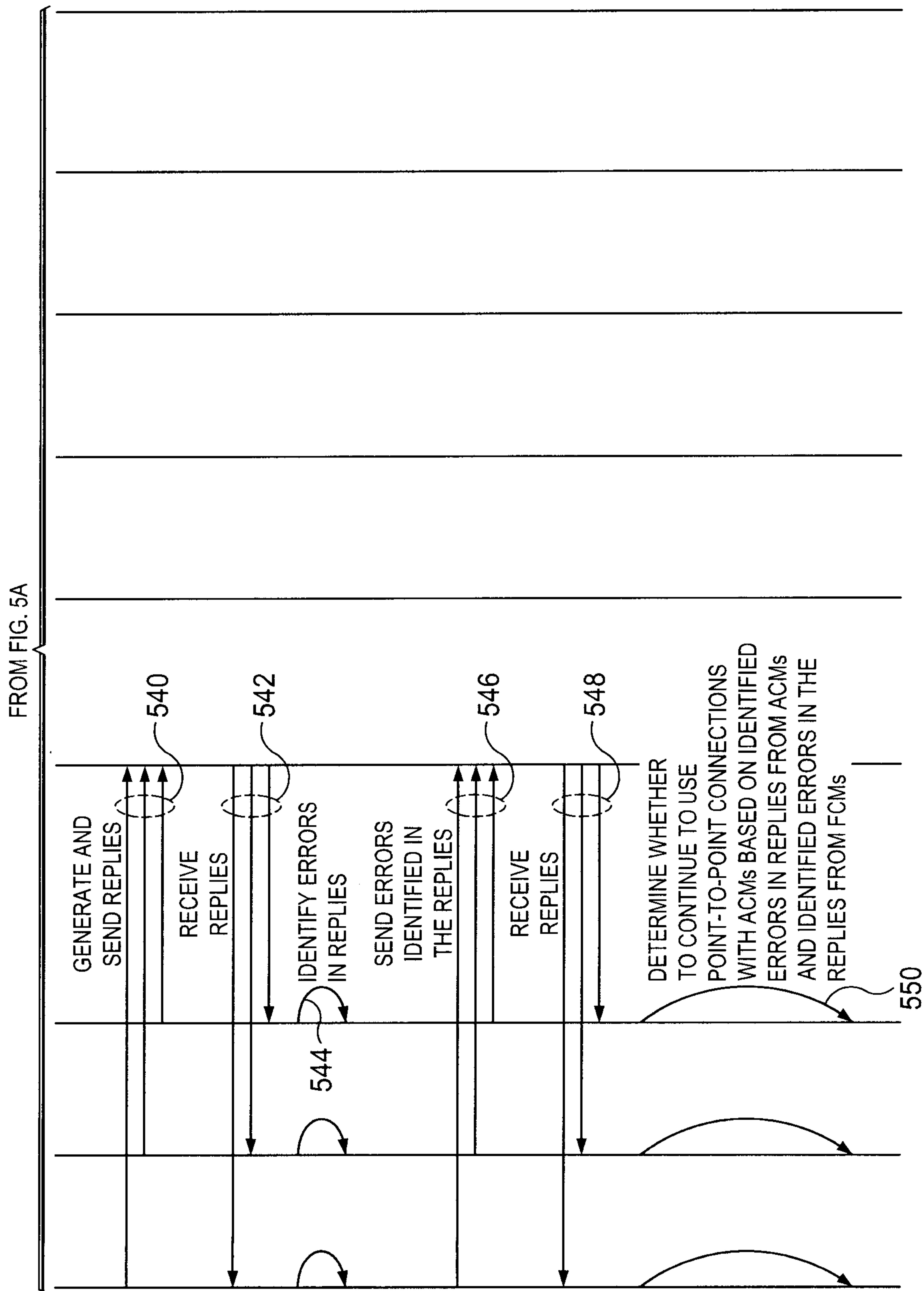


FIG. 5A

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FIG. 5B



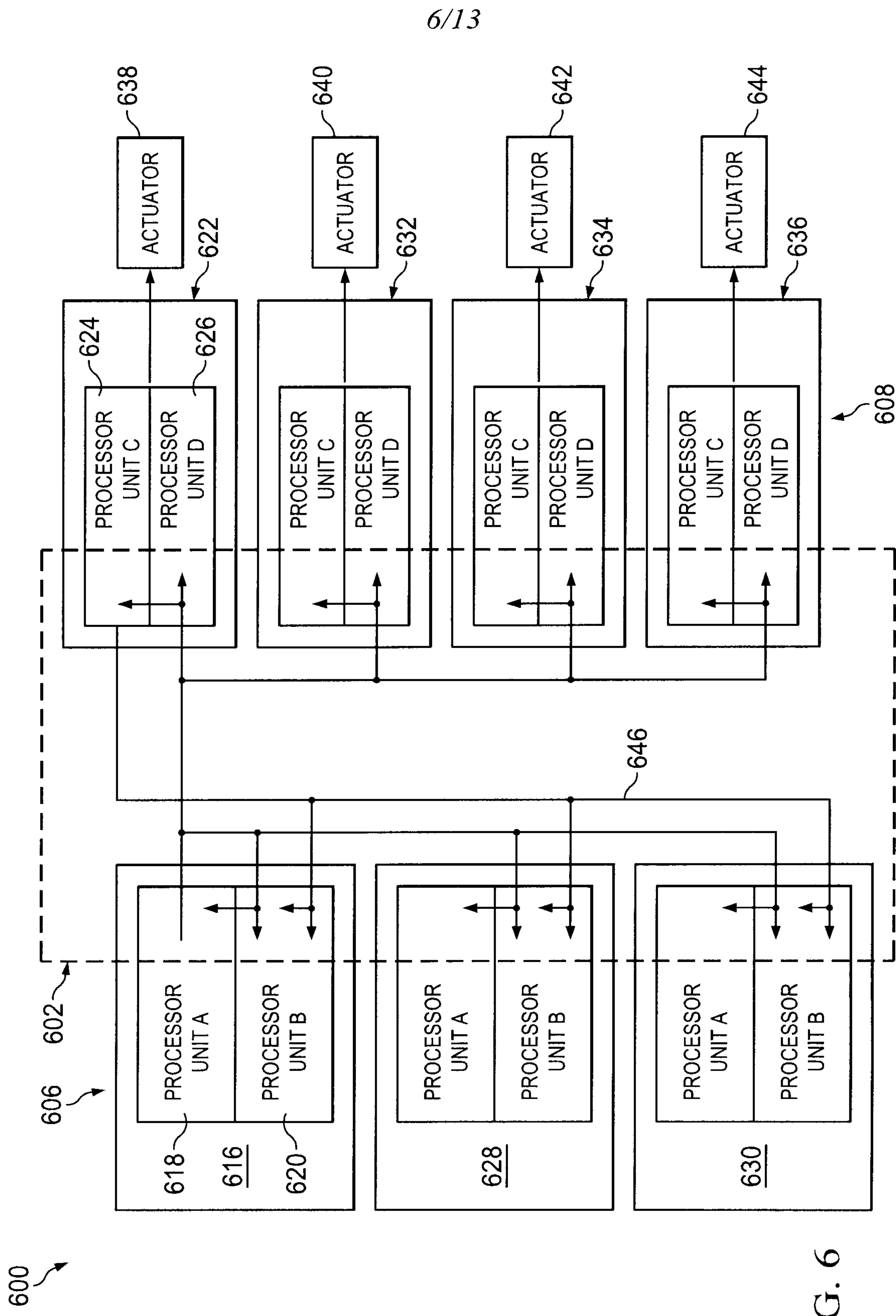


FIG. 6

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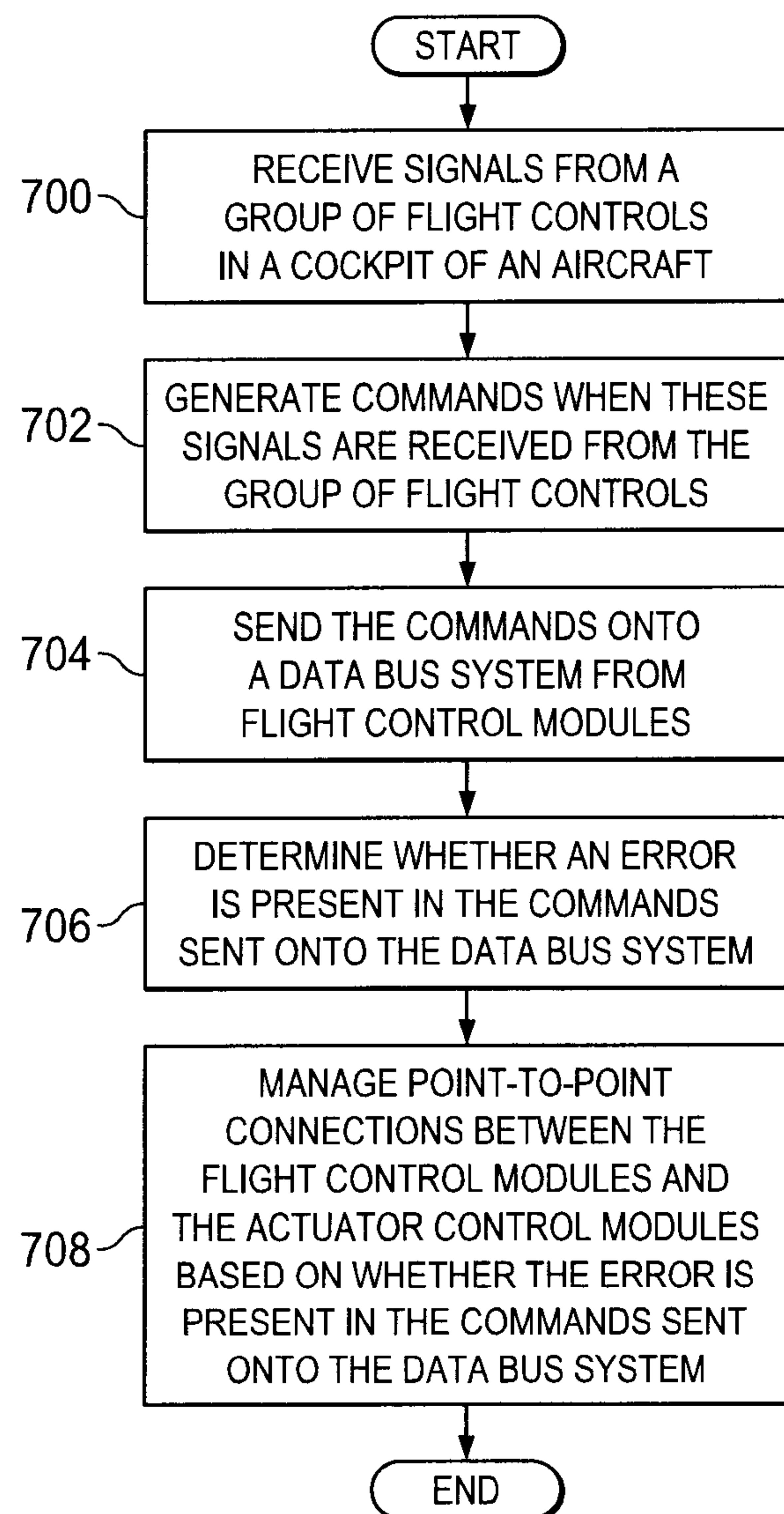


FIG. 7

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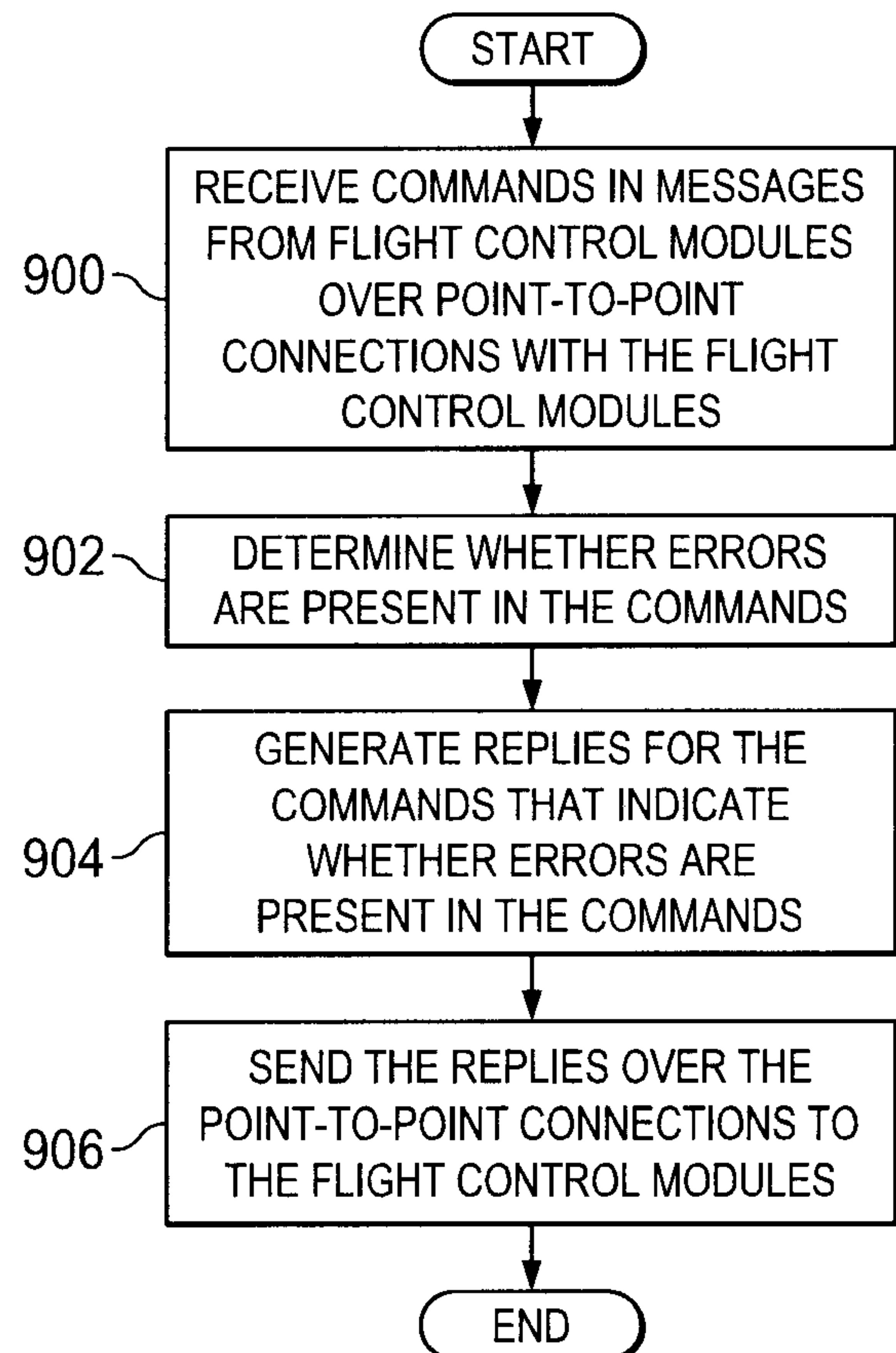
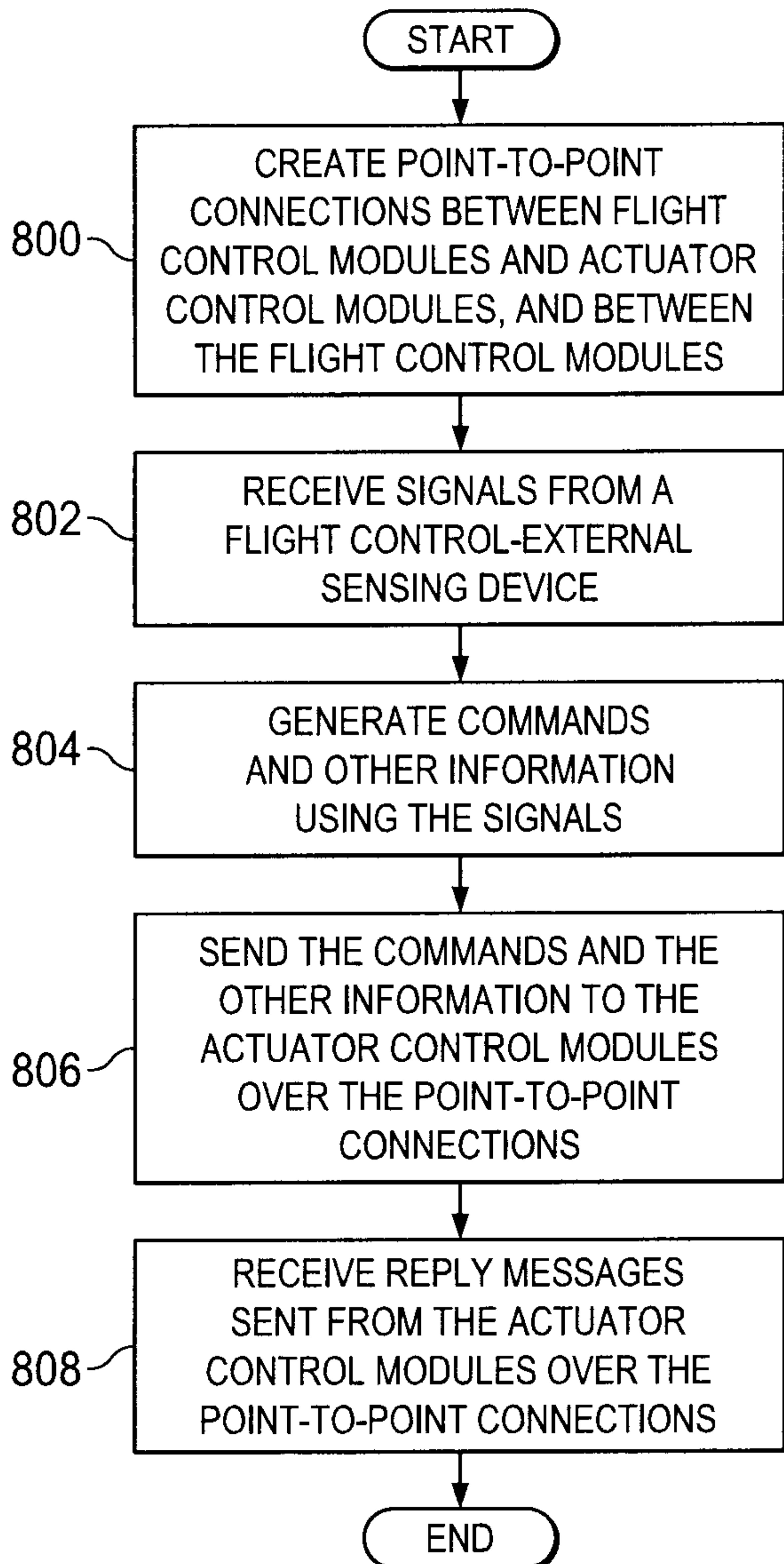


FIG. 9

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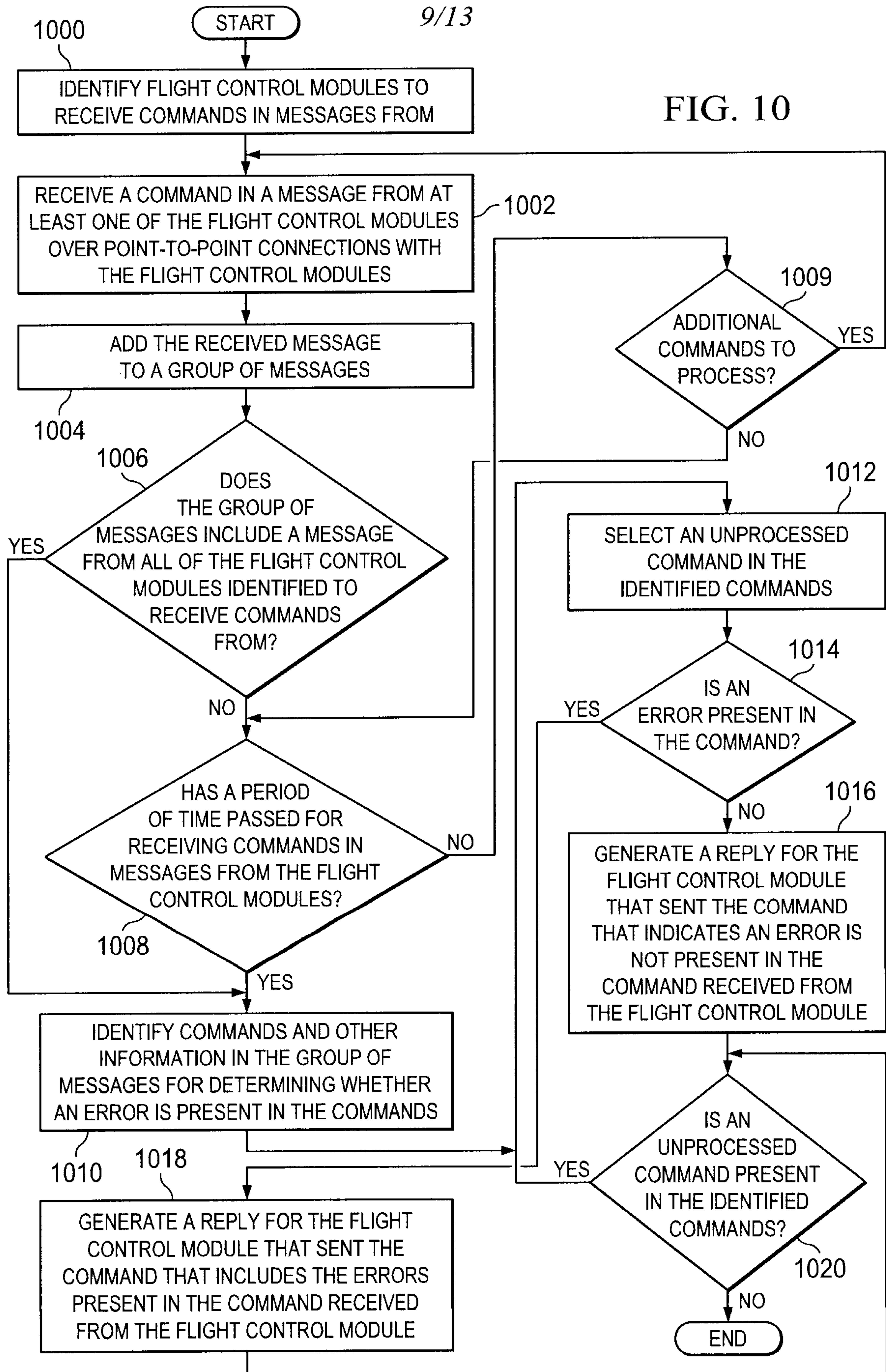


FIG. 10

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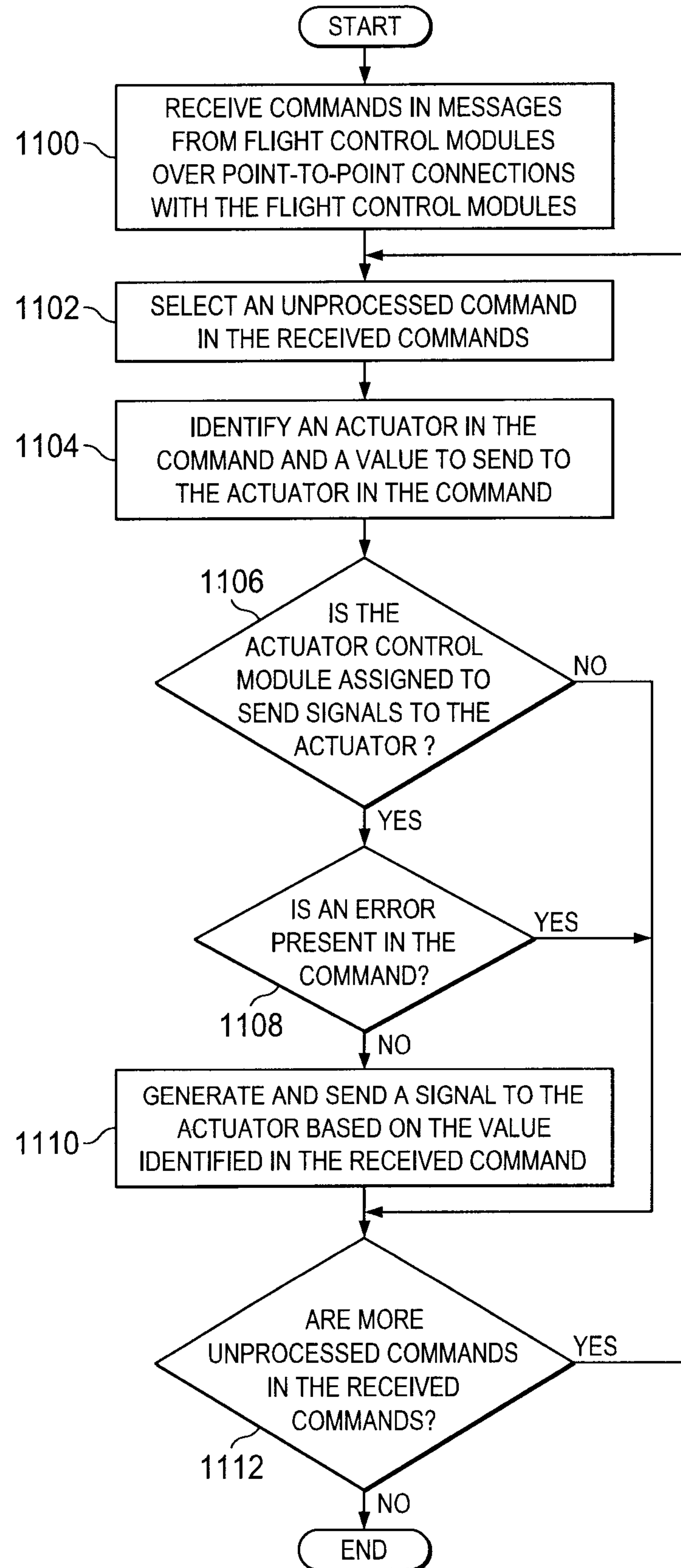
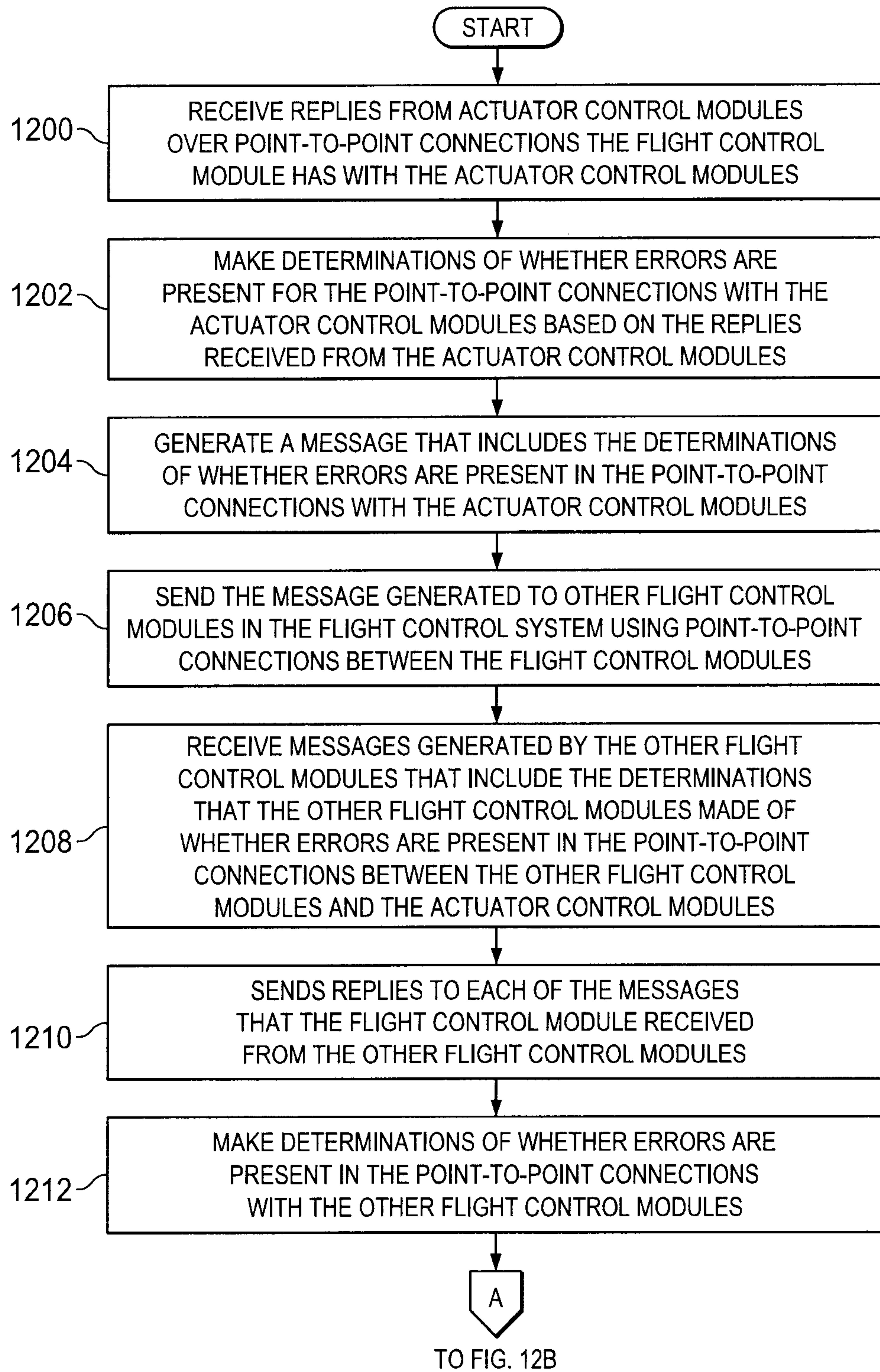


FIG. 11

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FIG. 12A



TO FIG. 12B

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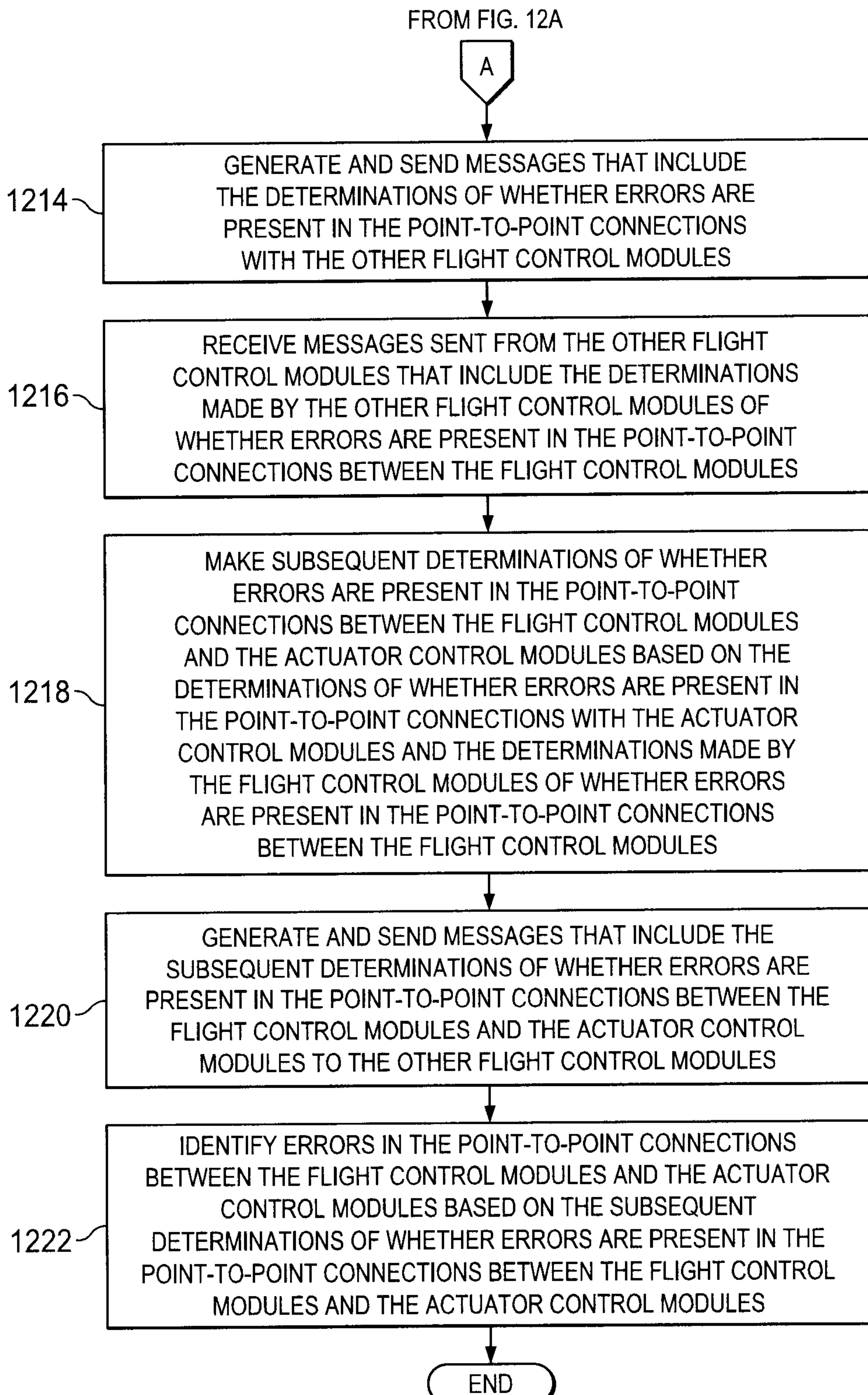


FIG. 12B

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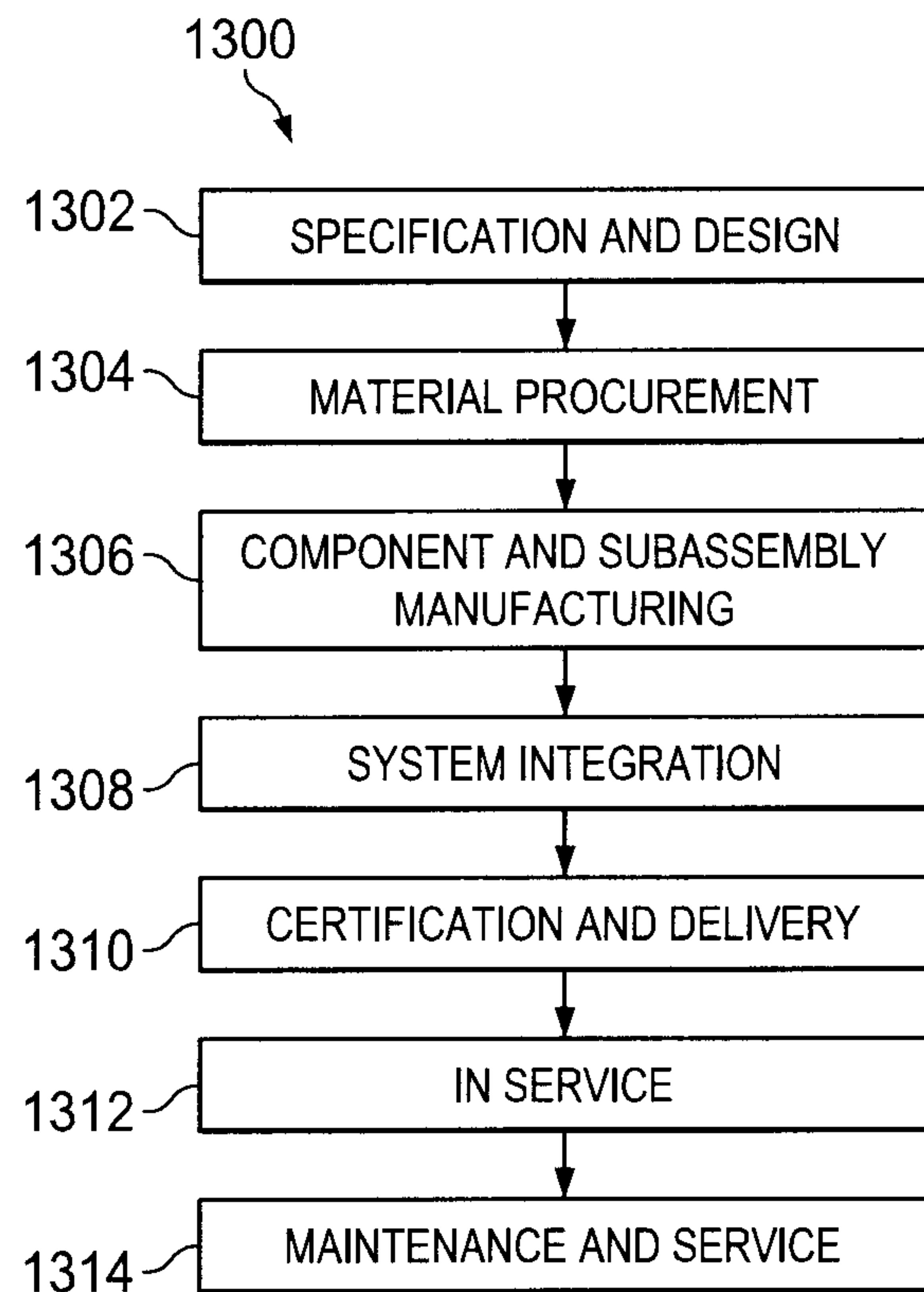


FIG. 13

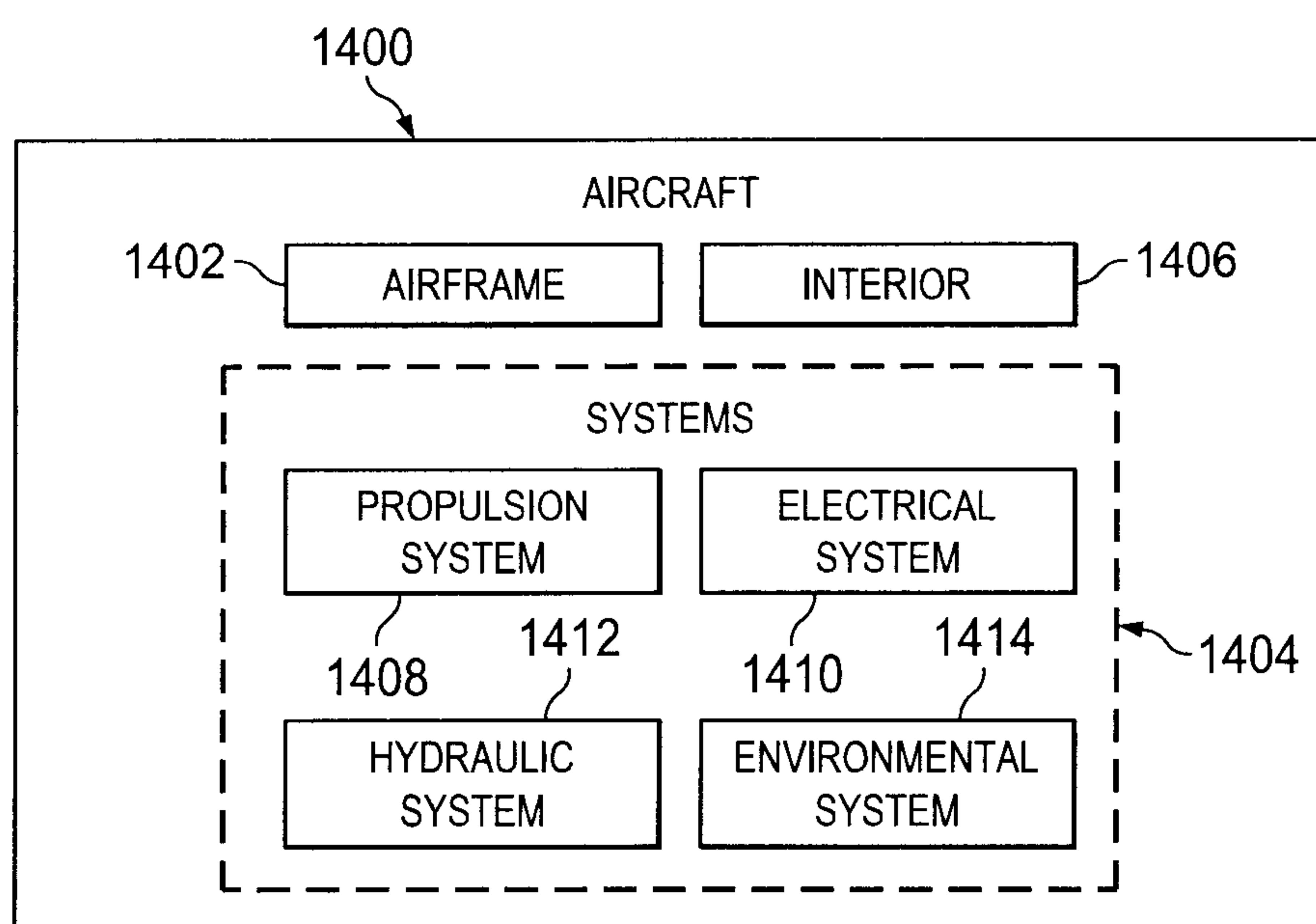


FIG. 14

