



(12)

Oversættelse af  
europæisk patentskriftPatent- og  
Varemærkestyrelsen(51) Int.Cl.: **A 61 G 3/06 (2006.01)**(45) Oversættelsen bekendtgjort den: **2019-08-05**(80) Dato for Den Europæiske Patentmyndigheds  
bekendtgørelse om meddelelse af patentet: **2019-05-08**(86) Europæisk ansøgning nr.: **13761896.3**(86) Europæisk indleveringsdag: **2013-03-14**(87) Den europæiske ansøgnings publiceringsdag: **2015-01-21**(86) International ansøgning nr.: **US2013031716**(87) Internationalt publikationsnr.: **WO2013138661**(30) Prioritet: **2012-03-16 US 201261611793 P**(84) Designerede stater: **AL AT BE BG CH CY CZ DE DK EE ES FI FR GB GR HR HU IE IS IT LI LT LU LV MC MK MT NL NO PL PT RO RS SE SI SK SM TR**(73) Patenthaver: **Ricon Corp., 7900 Nelson Road, Panorama City, CA 91402, USA**(72) Opfinder: **DELEO, Dante, V., 28551 Curtis Alan Place, Santa Clarita, California 91350, USA**  
**SU, Haur, Tsu, 1301 E. Herring Avenue, West Covina, California 91790, USA**(74) Fuldmægtig i Danmark: **Chas. Hude A/S, H.C. Andersens Boulevard 33, 1780 København V, Danmark**(54) Benævnelse: **Løftearrangement til rullestole og med et lastaffølingssystem**

(56) Fremdragne publikationer:

**EP-A2- 1 582 404****WO-A2-2011/116032****US-A1- 2003 021 666****US-A1- 2003 213 653****US-A1- 2005 077 111****US-A1- 2007 071 569****US-B1- 6 179 545****US-B1- 7 500 818**

DK/EP 2825145 T3

# DESCRIPTION

**[0001]** The invention relates to a wheelchair lift arrangement in accordance with the preamble of claim 1.

## BACKGROUND OF THE INVENTION

**[0002]** The present invention relates generally to access systems and wheelchair lift arrangements, for example wheelchair lift arrangements for use in connection with a vehicle, and, in particular, to a load sensing system and arrangement for use in connection with such access systems and wheelchair lift arrangements. Prior art document EP1582404A2 discloses a safety device for extracting vehicle access ramps, particularly intended for being installed in ramps assembled on the vehicles themselves for facilitating access for people with reduced mobility.

**[0003]** As is known in the art, access systems and wheelchair lift arrangements are provided to permit access, entry, exit, ingress, egress, and the like, from a variety of structures and environments. For example, many vehicles are fitted or configured to interact with a wheelchair lift arrangement to allow a wheelchair (or other limited mobility) user to enter and exit the vehicle. A typical wheelchair lift arrangement for a vehicle includes a bridging plate assembly which, during operation, bridges the gap between the lift platform and the floor of the vehicle or the base plate.

**[0004]** Based upon recent regulations directed to such vehicle-based wheelchair lift arrangements, it is now a requirement for public wheelchair lift arrangements to be equipped with a load detection system for the bridging plate assembly. As discussed, the bridging plate assembly acts as a bridge between the lift platform and the vehicle floor or base plate (when the wheelchair lift arrangement is at floor level). When the wheelchair lift arrangement lowers below floor level, the bridging plate moves to a raised position and acts as an inboard barrier to the platform. If there is a load of about 11,34 kg (25 pounds) applied to the bridging plate while the lift is at floor level, the lift platform must be disabled from lowering and raising the bridging plate.

**[0005]** Due to certain irregularities in the flatness of the mounting structures, the sensitivity of this load detection system may be compromised. For example, many wheelchair lift arrangements tend to be sensitive to the flatness of the floor to which they are mounted, which can cause bowing of the base plate.

## SUMMARY OF THE INVENTION

**[0006]** Accordingly, there exists a need in the art to provide an improved load sensing system for a vehicle-based wheelchair lift arrangement.

**[0007]** According to the invention a wheelchair lift in accordance with claim 1 is provided. Generally, provided is a load sensing system for a wheelchair lift arrangement that addresses and/or overcomes some or all of the drawbacks and deficiencies that exist in current access systems and/or wheelchair lift arrangements. Preferably, provided is a load sensing system for a wheelchair lift arrangement that is useful in connection with vehicle-based wheelchair lift arrangements. Preferably, provided is a load sensing system for a wheelchair lift arrangement that complies with certain regulations governing the installation, operation, and/or use of specified public wheelchair lift arrangements.

**[0008]** Therefore, in one preferred and non-limiting embodiment, provided is a load sensing system for a wheelchair lift arrangement that detects a specified load on a bridge plate assembly and is not substantially subject to any distortions of a base plate mounted on a non-flat vehicle floor. In another preferred and non-limiting embodiment, provided is a load sensing system for a wheelchair lift arrangement that utilizes a minimal vertical transition for a wheelchair user to overcome while traversing onto the lift platform from the vehicle. In a still further preferred and non-limiting embodiment, provided is a load sensing system for a wheelchair lift arrangement that minimizes the effort for entry to the wheelchair lift platform.

**[0009]** In accordance with one embodiment of the present invention, a load sensing system for a wheelchair lift arrangement having a bridge plate is provided. The load sensing system includes an elongated member extending along a longitudinal axis between a first end and a second end and rotatable about the longitudinal axis between an unloaded position and a loaded position; at least one contact member disposed on the elongated member between the first end and the second end, the contact member connected to the elongated member and configured to contact the bridge plate; and a switch assembly operatively connected to the elongated member and configured to be activated to prevent operation of the wheelchair lift arrangement when the elongated member is in the loaded position.

**[0010]** In accordance with another embodiment of the present invention, a wheelchair lift arrangement for attachment to a floor surface positioned at a floor surface level is provided. The arrangement includes a lift platform having a base plate and movable between a lowered position and a raised position, wherein the base plate is positioned at the floor surface level; a bridge plate assembly including a bridge plate extending between the floor surface and the base plate of the lift platform when the lift platform is in the raised position; and a load sensing system. The load sensing system includes an elongated member extending along a longitudinal axis between a first end and a second end and rotatable about the longitudinal axis between an unloaded position and a loaded position; at least one contact member disposed on the elongated member between the first end and the second end, the contact member connected to the elongated member and configured to contact the bridge plate; and a switch assembly operatively connected to the elongated member and configured to be activated to prevent operation of the wheelchair lift arrangement when the elongated member is in the

loaded position.

**[0011]** In accordance with yet another embodiment of the present invention, a method of regulating movement of a lift platform of a wheelchair lift arrangement is provided. The method includes the step of providing a wheelchair lift arrangement for attachment to a floor surface positioned at a floor surface level. The wheelchair lift arrangement includes a lift platform having a base plate; a bridge plate assembly including a bridge plate; and a load sensing system. The load sensing system includes an elongated member extending along a longitudinal axis between a first end and a second end and rotatable about the longitudinal axis between an unloaded position and a loaded position; at least one contact member disposed on the elongated member between the first end and the second end, the contact member connected to the elongated member and configured to contact the bridge plate; and a switch assembly operatively connected to the elongated member. The method further includes the steps of: moving the lift platform from a lowered position to a raised position, wherein the base plate is positioned at the floor surface level; extending the bridge plate from the floor surface to the base plate and contacting the bridge plate with the at least one contact member; applying a load to the bridge plate and actuating the at least one contact member to cause the elongated member to rotate to the loaded position; and activating the switch assembly to prevent operation of the wheelchair lift arrangement moving the base plate from the floor surface level.

**[0012]** These and other features and characteristics of the present invention, as well as the methods of operation and functions of the related elements of structures, and the combination of parts and economies of manufacture will become more apparent upon consideration of the following description and with reference to the accompanying drawings, all of which form a part of this specification, wherein like reference numerals designate corresponding parts in the various figures. It is to be expressly understood, however, that the drawings are for the purpose of illustration and description only, and are not intended as a definition of the limits of the invention. As used in the specification and the claims, the singular form of "a", "an", and "the" include plural referents unless the context clearly dictates otherwise.

#### **BRIEF DESCRIPTION OF THE DRAWINGS**

#### **[0013]**

FIG. 1 depicts a perspective schematic view of a wheelchair lift arrangement incorporating a load sensing system in accordance with an embodiment of the present invention;

FIG. 2 depicts a detailed perspective schematic view of a portion of the wheelchair lift arrangement and load sensing system of FIG. 1;

FIG. 3 depicts a detailed perspective view of the load sensing system of FIG. 1;

FIG. 4 depicts a perspective view of the load sensing system of FIG. 1 in an unloaded state; and

FIG. 5 depicts a perspective view of the load sensing system of FIG. 1 in a loaded state.

## DETAILED DESCRIPTION OF THE INVENTION

**[0014]** For purposes of the description hereinafter, the terms "end", "upper", "lower", "right", "left", "vertical", "horizontal", "top", "bottom", "lateral", "longitudinal", and derivatives thereof shall relate to the invention as it is oriented in the drawing figures. However, it is to be understood that the invention may assume various alternative variations and step sequences, except where expressly specified to the contrary. It is also to be understood that the specific devices and processes illustrated in the attached drawings, and described in the following specification, are simply exemplary embodiments of the invention. Hence, specific dimensions and other physical characteristics related to the embodiments disclosed herein are not to be considered as limiting.

**[0015]** With reference to FIGS. 1 and 2, a wheelchair lift arrangement 10 is shown in accordance with an embodiment of the present invention. The arrangement 10 is attached to a floor surface 20 positioned at a floor surface level and includes a lift platform 50. According to one embodiment, the floor surface 20 is defined by the floor of a vehicle (not shown), such as a van or a bus. Alternatively, the floor surface 20 is formed by the mounting structure attaching the wheelchair lift arrangement 10 to the floor and/or frame of the vehicle. In another aspect of the invention, the floor surface 20 is any surface that is raised with respect to a portion of its surroundings such that a person in a wheelchair requires assistance to access or leave the surface. The lift platform 50 is a portion of a wheelchair lift system mounted and installed in the vehicle or raised structure for lifting a disabled person confined to a wheelchair into and out of the vehicle or on and off the raised structure. Such lift systems are well known to those having ordinary skill in the art. It is to be appreciated that the wheelchair lift arrangement 10 and a load sensing system 100, to be discussed in further detail below, are compatible with any one of a number of wheelchair lift systems constructed in a manner consistent with the principles of operation described below. The lift platform 50 includes a base plate 51, which defines the movable surface intended for lifting or lowering a passenger between a ground level or lowered surface and the raised floor surface 20. In particular, the lift platform 50 is movable between a lowered position and a raised position, wherein the base plate 51 is positioned at the floor surface level, as is shown in FIGS. 1 and 2. The base plate 51 may also include a recessed portion or area 52 upon which the load sensing system 100 may be disposed, as will be discussed in further detail below.

**[0016]** The wheelchair lift arrangement 10 also includes a bridge plate assembly 30. The bridge plate assembly 30 includes a bridge plate 31 that extends from the floor surface 20 to the base plate 51 of the lift platform 50 when the lift platform 50 is in the raised position. Accordingly, the bridge plate 31 of the bridge plate assembly 30 functions as a transfer plate that allows a passenger in a wheelchair to move from the base plate 51 of the lift platform 50 to

the floor surface 20. The bridge plate assembly 30 may further include a mounting/hinge assembly 32 for securely and pivotably connecting the bridge plate 31 to the floor surface 20. When the lift platform 50 is in the lowered position or below the floor surface level, the bridge plate 31 is raised by a mechanized automatic or manual system about the hinge assembly 32 to a substantially vertical position, and acts as an inboard barrier to the floor surface 20. Accordingly, in the raised position, the bridge plate assembly 30 provides safety to the user and minimizes or eliminates the chance that the wheelchair will move off of the floor surface 20 during operation.

**[0017]** As shown in FIGS. 1-5, and in one preferred and non-limiting embodiment, the wheelchair lift arrangement 10 further includes a load sensing system 100. The load sensing system 100 includes an elongated member 101, which may be a stiff or substantially rigid rod, and which extends along a longitudinal axis L between a first end 102 and a second end 103. The elongated member 101 is rotatable about the longitudinal axis L between an unloaded position (shown in FIG. 4) and a loaded position (shown in FIG. 5). A biasing member 104, which may be a torsion spring disposed alongside the elongated member 101, engages the elongated member 101 and biases the elongated member toward the unloaded position.

**[0018]** At least one contact member 105 is disposed on the elongated member 101 between the first end 102 and the second end 103. The at least one contact member 105 is connected to the elongated member 101 such that movement of the elongated member 101 causes movement of the at least one contact member 105 and vice versa. In one particular aspect of the invention, the at least one contact member 105 is fixedly connected to the elongated member 101, though it is to be appreciated that the contact member 105 may be connected to the elongated member 101 in any manner that allows for rotational movement of the contact member 105 to be transmitted to the elongated member 101 and vice versa. For instance, the at least one contact member 105 may engage a stop or similar element extending from the elongated member 101. In one embodiment, the at least one contact member 105 is configured to extend from the elongated member 101 and engage the bridge plate 31 when the bridge plate 31 is extended from the floor surface 20 to the base plate 51 of the lift platform 50, as is shown in FIGS. 1 and 2. As shown in FIGS. 1, 4, and 5, the load sensing system 100 includes a plurality of, particularly three, contact members 105 spaced across the length of the elongated member 101 between the first end 102 and the second end 103. It is to be appreciated, though, that there may be as few as one and as many as five or six contact members 105 spaced along the elongated member 101 depending upon the size and configuration of the wheelchair lift arrangement 10. Each contact member 105 may be formed as a lever that is disposed around and connected to the elongated member 101 and extends outwardly and upwardly from the elongated member 101 to contact or engage the extended bridge plate 31 above the load sensing system 100. As such, the lever of the contact member 105 will extend upwardly with respect to the elongated member 101 when the elongated member 101 is in the unloaded position, as is shown in FIG. 4. Likewise, the lever of the contact member 105 will be rotatably depressed by the bridge plate 31 about the longitudinal axis L when a load is applied to the bridge plate 31, which causes the bridge plate 31 engaging the at least one contact member 105 to be pressed downward with respect to the floor surface

20 and the base plate 51 of the lift platform 50, as shown in FIGS. 3 and 5.

**[0019]** As shown in FIGS. 1-5, the load sensing system 100 also includes at least one guide block 106 that rotatably receives the elongated member 101. The at least one guide block 106 is fixedly connected to the recessed portion 52 of the base plate 51 by a fastener, such as a screw, or by some other mechanism, such as welding, known to be suitable to those having ordinary skill in the art. The guide block 106, therefore, serves to connect the elongated member 101 to the base plate 51 while allowing the elongated member 101 to rotate with respect to the longitudinal axis L. As shown in FIGS. 1, 4, and 5, the load sensing system 100 includes a plurality of, particularly four, guide blocks 106 spaced along the length of the elongated member 101. The fourth guide block 106 may overlap the second end 103 of the elongated member 101 in order to secure the second end 103. It is to be appreciated that there may be as few as one or two guide blocks 106 and as many as five or six guide blocks 106 provided to the load sensing system 100 depending on the size and configuration of the wheelchair lift arrangement 10.

**[0020]** The load sensing system 100 further includes a switch assembly 110 that is operatively connected to the first end 102 of the elongated member 101 such that rotation of the elongated member 101 about the longitudinal axis L causes activation of the switch assembly 110, as will be described in further detail below. The switch assembly 110 is activated by rotation of the elongated member 101 to prevent operation of the wheelchair lift arrangement 10 when the elongated member 101 is moved to the loaded position. As shown in FIGS. 2 and 3, the switch assembly 110 includes an adjustable switch actuator 111 connected to the first end 102 of the elongated member 101 and a limit switch 112, which may be in the form of a micro-switch. The adjustable switch actuator 111 rotates with the elongated member 101 as the elongated member 101 moves between the loaded and unloaded positions in order to engage the limit switch 112 when the elongated member 101 is in the loaded position and to disengage the limit switch 112 when the elongated member 101 moves from the loaded position to the unloaded position. Accordingly, the adjustable switch actuator 111 engages the limit switch 112 to actuate the limit switch 112 and activate the switch assembly 110 when the elongated member 101 is in the loaded position.

**[0021]** The switch assembly 110 further includes wiring 113 and a connector 114, which connects the switch assembly 110 to a controller (not shown) of the wheelchair lift system such that the switch assembly 110 is able to transmit a signal to the controller to prevent operation of the wheelchair lift arrangement 10 when the elongated member 101 is in the loaded position and the switch assembly 110 is activated. The switch assembly 110 is also provided with a housing 115, which surrounds and protects the actuator 111 and the limit switch 112 from damage. The housing 115 may be fastened or otherwise connected to the base plate 51 in the same manner as the guide blocks 106, as discussed above. The housing 115 may be provided with a removable cover 116 to allow for access to the actuator 111 and the limit switch 112 to allow for replacement or adjustment of the actuator 111 and the limit switch 112.

**[0022]** Therefore, when a load is applied to the bridge plate 31 contacting or engaging the

lever of the at least one contact member 105, the lever will be actuated by the bridge plate 31, possibly such that it will be rotatably pressed downwardly about the longitudinal axis L, thus causing the elongated member 101 to also rotate about the longitudinal axis L from the unloaded position to the loaded position, which, in turn, causes the adjustable switch actuator 111 to engage and actuate the limit switch 112 in order to activate the switch assembly 110. When the load is removed from the bridge plate 31, the bias applied by the biasing member 104 will cause the elongated member 101 to rotate about the longitudinal axis L towards the unloaded position, thus causing the at least one contact member 105 to rotate upwardly and causing the adjustable switch actuator 111 to disengage the limit switch 112, thereby deactivating the switch assembly 110 and allowing for operation of the wheelchair lift arrangement 10.

**[0023]** With reference to FIGS. 1-5, in accordance with an embodiment of the present invention, a method of regulating movement of a lift platform 50 of a wheelchair lift arrangement 10 includes the step of providing a wheelchair lift arrangement. The wheelchair lift arrangement 10 includes a floor surface 20 positioned at a floor surface level; a lift platform 50 having a base plate 51; a bridge plate assembly 30, the bridge plate assembly 30 including a bridge plate 31; and a load sensing system 100. The load sensing system 100 includes an elongated member 101 extending along a longitudinal axis L between a first end 102 and a second end 103, the elongated member 101 being rotatable about the longitudinal axis L between an unloaded position and a loaded position; at least one contact member 105 disposed on the elongated member 101 between the first end 102 and the second end 103, the contact member 105 being fixedly connected to the elongated member 101 and being configured to extend from the elongated member 101 and contact the bridge plate 31; and a switch assembly 110 operatively connected to the first end 102 of the elongated member 101. The method also includes the steps of moving the lift platform 50 from a lowered position to a raised position, wherein the base plate 51 is positioned at the floor surface level; extending the bridge plate 31 from the floor surface 20 to the base plate 51 and contacting the bridge plate 31 with the at least one contact member 105; applying a load to the bridge plate 31 and actuating the at least one contact member 105 to cause the elongated member 101 to rotate about the longitudinal axis L from the unloaded position to the loaded position; and activating the switch assembly 110 to prevent operation of the wheelchair lift arrangement 10 moving the base plate 51 from the floor surface level. The method may also include the steps of removing the load from the bridge plate 31 to allow the elongated member 101 to rotate to the unloaded position due to the bias of the biasing member 104; and deactivating the switch assembly 110 to allow operation of the wheelchair lift arrangement 10 moving the base plate 51 from the floor surface level.

**[0024]** With reference to FIGS. 1 and 2, according to another aspect of the invention, the load sensing system 100 is connected to the recessed portion 52 of the base plate 51 of the lift platform 50 and is engaged by the bridge plate 31 when the base plate 51 is moved to the raised position, and the bridge plate 31 is extended from the floor surface 20 to the base plate 51 such that there is minimal vertical transition between the base plate 51 and the bridge plate 31. The load sensing system 100 is also disposed on the recessed portion 52 of the base plate

51 such that the elongated rod 101 and the at least one contact member 105 are situated at or below the level of the base plate 51. As such, the load sensing system 100 provides a low-profile feature, which allows for a specified or a minimal or no vertical transition between the base plate 51 of the lift platform 50 and the bridging plate 31. In particular and based upon the unique configuration, the bridging plate assembly 30 according to this embodiment of the present invention does not include overlapping plates. Other existing arrangements and systems use such overlapping plates to detect a load on the bridging plate, thus creating a vertical transition from one plate to the other. This vertical transition, such as a 4,76-6,35mm (3/16-1/4 inch) transition, represents an obstacle and/or (potentially unsafe) nuisance that a user of a wheelchair must encounter and traverse to enter and exit the wheelchair lift arrangement. However, in this preferred and non-limiting embodiment of the present invention, this obstacle (i.e., vertical transition or "bump") is minimized or eliminated, representing another benefit of the present invention.

**[0025]** Another benefit of the load sensing system 100 of the present invention is that it is less sensitive to distortions in the floor surface 20, particularly when the floor surface 20 is defined by a mounting plate bolted to a vehicle floor. While an actuator switch assembly having a single contact point at or near the center of the base plate of the lift platform has been previously contemplated, this type of load detection is limited. In particular, if the base plate of the lift platform or the mounting plate were to be distorted, the edge of the bridging plate could make contact with the base plate of the lift platform and the switching mechanism would not detect the load. While adding more switches on or in operable engagement with the base plate of the lift platform may lead to a decrease in the occurrence of this potential operational flaw, the increased locations require a full set of components and complex wiring, which lead to a drastic increase in cost. It is further envisioned that the size, position, configuration, or function of any of the above-discussed components of the load sensing system 100 are adjustable in order to be modified to fit a variety of wheelchair lift arrangements 10 and/or a variety of environments and applications.

**[0026]** In this manner, the load sensing system 100 of the present invention is particularly useful in connection with a vehicle-based wheelchair lift arrangement 10. Further, the load sensing system 100 of the present invention complies with certain regulations governing the installation, operation, and/or use of specified, public wheelchair lift arrangements.

**[0027]** It is to be understood that the invention may assume various alternative variations and step sequences, except where expressly specified to the contrary. It is also to be understood that the specific devices and processes illustrated in the attached drawings, and described in the specification, are simply exemplary embodiments of the invention. Although the invention has been described in detail for the purpose of illustration based on what is currently considered to be the most practical and preferred embodiments, it is to be understood that such detail is solely for that purpose and that the invention is not limited to the disclosed embodiments, but, on the contrary, is intended to cover modifications and equivalent arrangements that are within the scope of the appended claims. For example, it is to be understood that the present invention contemplates that, to the extent possible, one or more

features of any embodiment can be combined with one or more features of any other embodiment.

## REFERENCES CITED IN THE DESCRIPTION

This list of references cited by the applicant is for the reader's convenience only. It does not form part of the European patent document. Even though great care has been taken in compiling the references, errors or omissions cannot be excluded and the EPO disclaims all liability in this regard.

### Patent documents cited in the description

- EP1582404A2 [0002]

**Patentkrav**

1. Løftearrangement (10) til rullestole, og som kan fastgøres til en gulvflade (20), og som er anbragt i gulvfladeniveau, hvilket arrangement omfatter:

5

en løfteplatform (50), som har en basisplade (51), og som kan bevæges mellem en sænket stilling og en hævet stilling, og hvor basispladen (51) er anbragt ved gulvfladeniveau,

10 en bropladeindretning (30), som indeholder en broplade (31) og strækker sig mellem gulvfladen (20) og basispladen (51) på løfteplatformen, når løfteplatformen (50) er i den hævede stilling, **kendetegnet ved**, at arrangementet omfatter:

en belastningsaffølingsindretning (100), som omfatter:

15 en aflang del (101), der strækker sig langs en længdeakse (L) mellem en første ende (102) og en anden ende (103), og hvor den aflange del kan drejes omkring længdeaksen (L) mellem en ubelastet stilling og en belastet stilling,

mindst en kontaktdel (105), som er forbundet med den aflange del (101);  
20 og

en omskifterindretning (110), som er operativt forbundet med den aflange del (101), og som er således udformet, at den kan aktiveres, så at den kan forhindre rullestol-løftearrangementet i at fungere, når den aflange del (101) befinder sig i belastet stilling, og hvor den mindst ene kontaktdel (105) er anbragt på den aflange del (101) mellem den første ende (102) og den anden ende (103), og er således udformet, at den kan berøre bropladen (31).

2. Løftearrangement (10) til rullestole ifølge krav 1, hvor belastningsaffølingsindretningen (100) yderligere omfatter en aktiveringsdel (104), som ligger an mod den aflange del (101), og som er således udformet, at den kan påvirke den aflange del (101) hen mod den ubelastede stilling.

3. Løftearrangement (10) til rullestole ifølge krav 1 eller 2, hvor aktiveringsdelen (104) omfatter en torsionsfjeder.
4. Løftearrangement (10) til rullestole ifølge krav 1, 2 eller 3, hvor den mindst 5 ene kontaktdel (105) er således udformet, at den kan aktiveres af bropladen (31), når belastningen påføres bropladen (31) - og dette for at få den aflange del (101) til at dreje omkring sin længdeakse (L) fra ubelastet stilling til belastet stilling og til at aktivere omskifterindretningen (110).
- 10 5. Løftearrangement (10) til rullestole ifølge krav 4, hvor den mindst ene kontaktdel (105) omfatter et antal kontaktdele (105), som er fordelt over et stykke af den aflange del (101) mellem nævnte første ende (102) og nævnte anden ende (103), og hvor den største dimension af den aflange del (101) findes i længdeak- sen (L).
- 15 6. Løftearrangement (10) til rullestole ifølge krav 4 eller 5, hvor den mindst ene kontaktdel (105) omfatter en vægtstang, som er forbundet med den aflange del (101) og strækker sig udad fra nævnte aflange del (101).
- 20 7. Løftearrangement (10) til rullestole ifølge krav 6, hvor vægtstangen er an- bragt på den aflange del (101), så at nævnte vægtstang strækker sig opad, når den aflange del (101) befinder sig i ubelastet stilling.
- 25 8. Løftearrangement (10) til rullestole ifølge krav 6 eller 7, hvor vægtstangen er således udformet, at den kan nedtrykkes af brodelen (31), når en belastning på- føres bropladen (31).
- 30 9. Løftearrangement (10) til rullestole ifølge ethvert af kravene 1 - 8, og som yderligere omfatter mindst en føringsblok (106), som, idet den kan dreje, kan op- tage den aflange del (101), og desuden er således udformet, at den kan forbinde den aflange del (101) med basispladen (51).

10. Løftearrangement (10) til rullestole ifølge krav 9, hvor den mindst ene føringssblok (106) omfatter et antal føringssblokke (106).
11. Løftearrangement (10) til rullestole ifølge ethvert af kravene 1 - 10, hvor om-skifterindretningen (110) omfatter et justerbart omskifter-aktiveringsorgan (111) og en grænseomskifter (112), og hvor det justerbare omskifter-aktiveringsorgan (111) kan rotere sammen med den aflange del (101), så at det justerbare omskifter-aktiveringsorgan (111) kan aktivere en grænseomskifter (112), således at sidstnævnte kan aktivere omskifterindretningen (110), når den aflange del (101) 10 befinder sig i den belastede stilling.
12. Løftearrangement (10) til rullestole ifølge ethvert af kravene 1 - 11, hvor den mindst ene kontaktdel (106) omfatter en vægtstang, som er forbundet med den aflange del (101) og strækker sig udad fra denne aflange del (101), og hvor vægtstangen er således anbragt på den aflange del (101), at vægtstangen strækker sig opad, når den aflange del (101) befinder sig i den ubelastede stilling, og vægtstangen er nedtrykket af bropladen (31), når belastningen er påført bropladen (31). 15
- 20 13. Løftearrangement (10) til rullestole ifølge ethvert af kravene 1 - 12, hvor belastningsaffølingsindretningen (100) er forbundet med en basisplade (51) på løfteplatformen (50) og således udformet, at den kan kontaktes af bropladen (31), når basispladen (51) bevæges hen til sin hævede stilling, og bropladen (31) strækker sig fra gulvfladen (20) til basispladen (51), således at der er en speciel 25 lodret overgang mellem basispladen (51) og bropladen (31).
- 30 14. Fremgangsmåde til regulering af bevægelsen af en løfteplatform (50) i et løftearrangement (10) til en rullestol, og som kan fastgøres på en gulvflade (20), som er anbragt i et gulvfladeniveau, hvilket løftearrangement (10) til rullestolen omfatter:
  - en løfteplatform (50), som har en basisplade (51);
  - et bropladearrangement (30), som omfatter en broplade (31); og

en belastningsaffølingsindretning (100), som omfatter:

- en aflang del (101), som strækker sig langs en længdeakse (L) mellem en første ende (102) og en anden ende (103) og er drejelig omkring en længdeakse (L) mellem en ubelastet stilling og en belastet stilling;
- 5 mindst en kontaktdel (105), som er anbragt på den aflange del (101) mellem den første ende (102) og den anden ende (103), idet kontaktdelen (105) er forbundet med den aflange del (101) og således udformet, at den kan berøre bropladen (31); og
- 10 en omskifterindretning (110), som er operativt forbundet med den aflange del (101); og
- at løfteplatformen (50) kan bevæges fra en sænket stilling til en hævet stilling, hvor basispladen (51) er anbragt i gulvfladeniveau;
- 15 at bropladen (31) kan udstrækkes fra gulvfladen (20) til basispladen (51) og kontakte bropladen (31) med den mindst ene kontaktdel (106);
- at det gælder at man kan påføre en belastning på bropladen (31) og aktivere den mindst ene kontaktdel (105) til, at denne får den aflange del (101) til at rotere hen i den belastede stilling; og
- 20 at det desuden gælder at omskifterindretningen (110) kan aktiveres til at forhindre en drift af rullestol-løftearrangementet (10), hvor basispladen (51) bevæges fra gulvflade-niveau under anvendelse af rullestol-løftearrangementet (10) ifølge ethvert af kravene 1 - 13.

## DRAWINGS

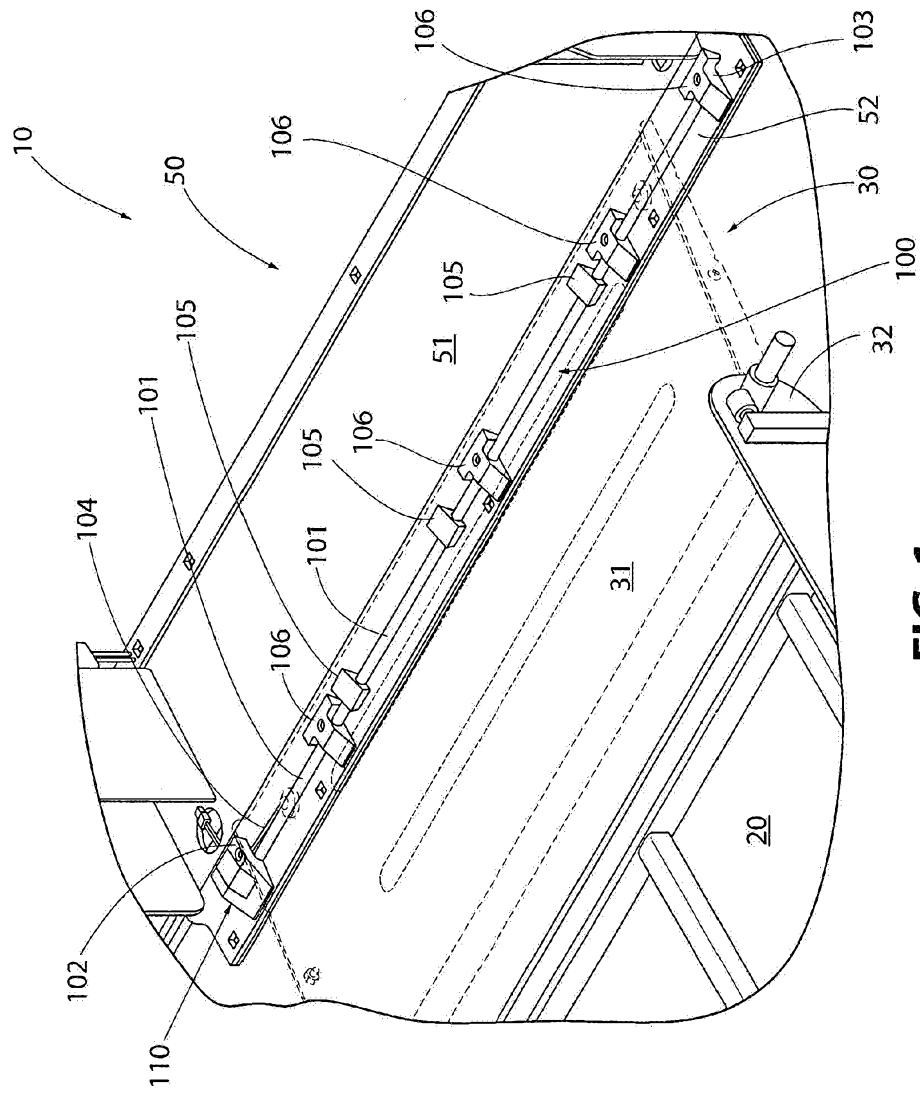
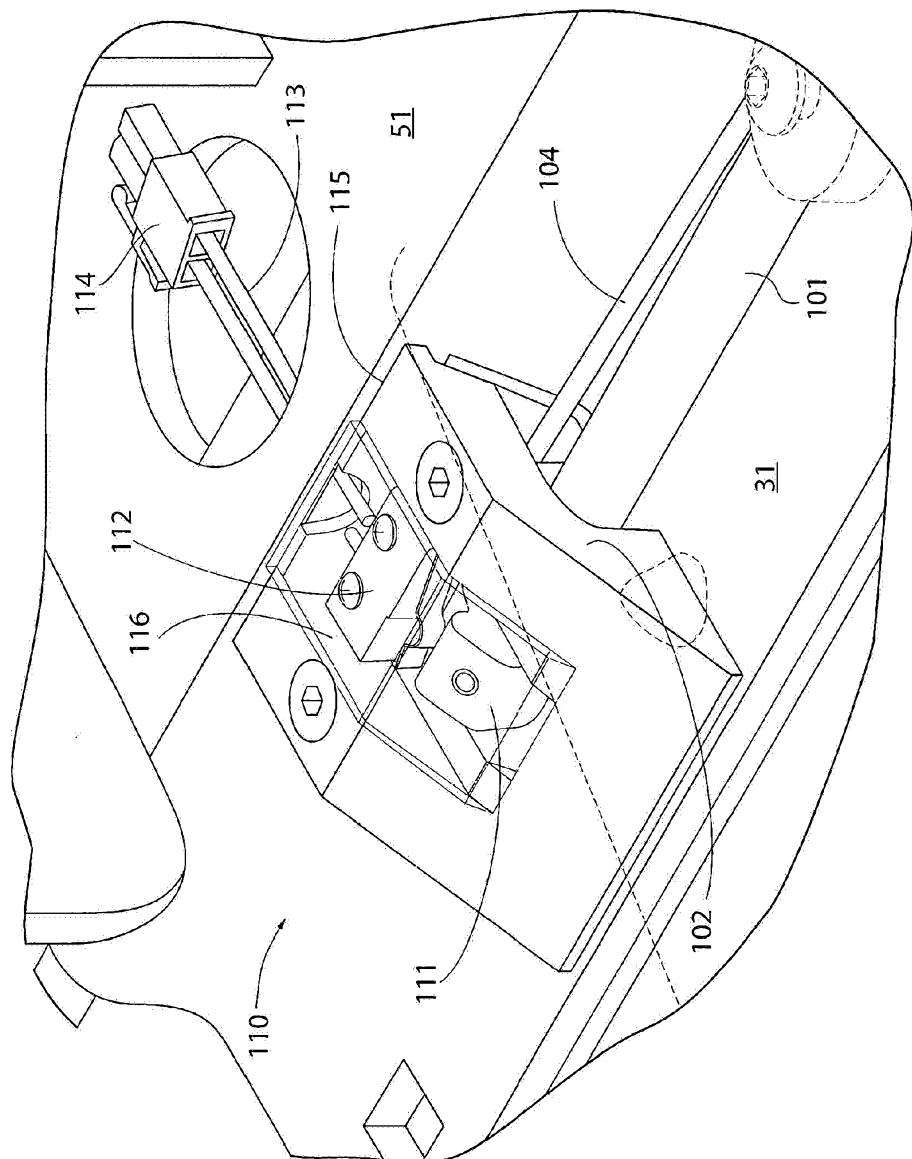


FIG. 1



**FIG. 2**

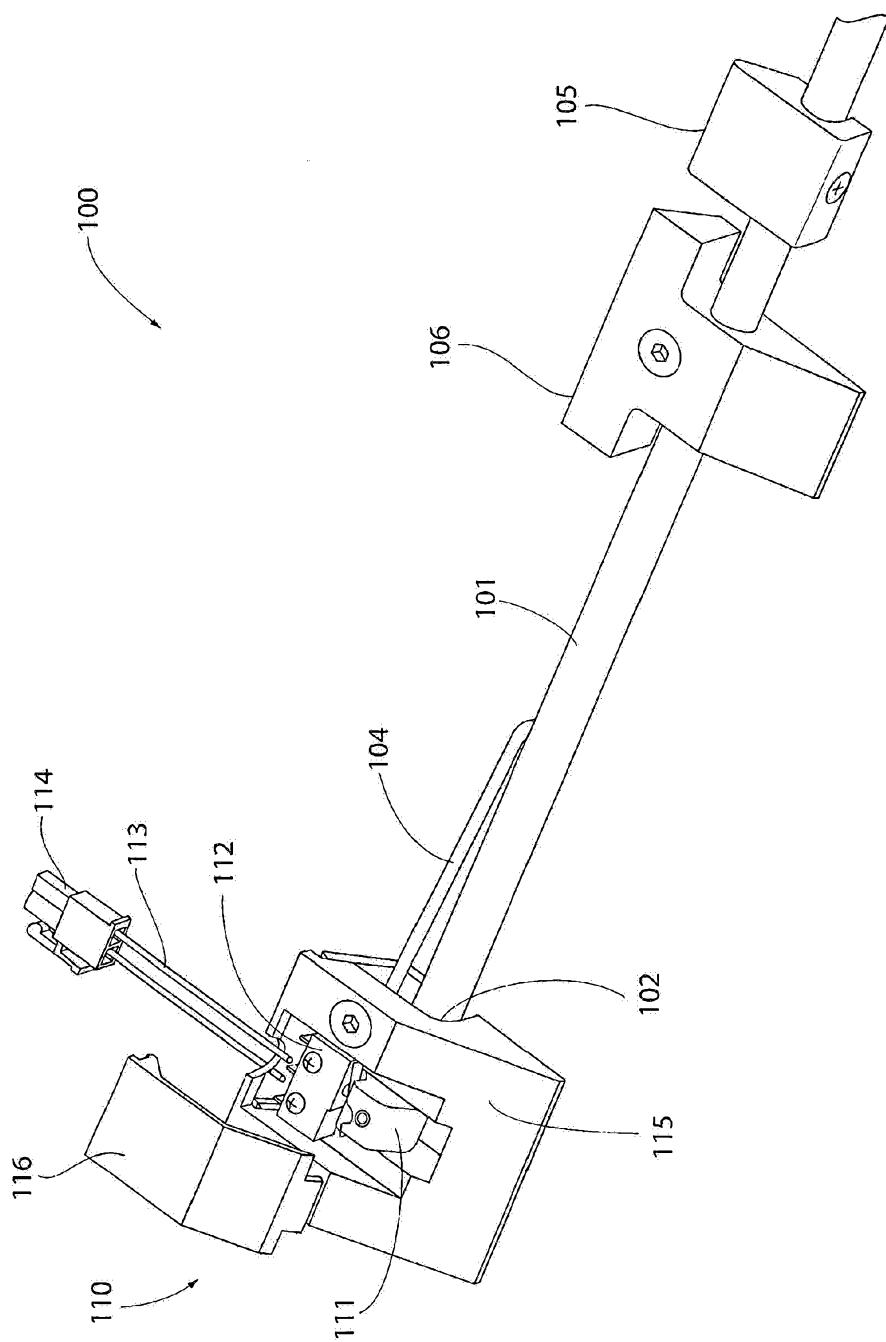


FIG. 3

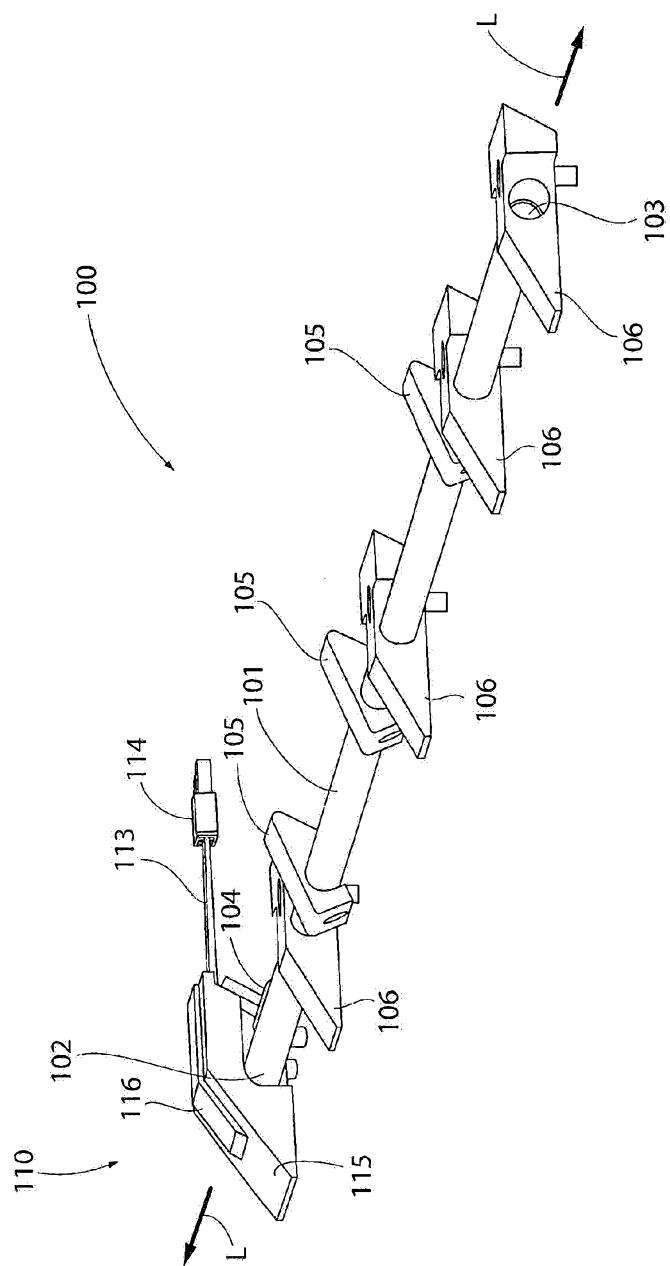
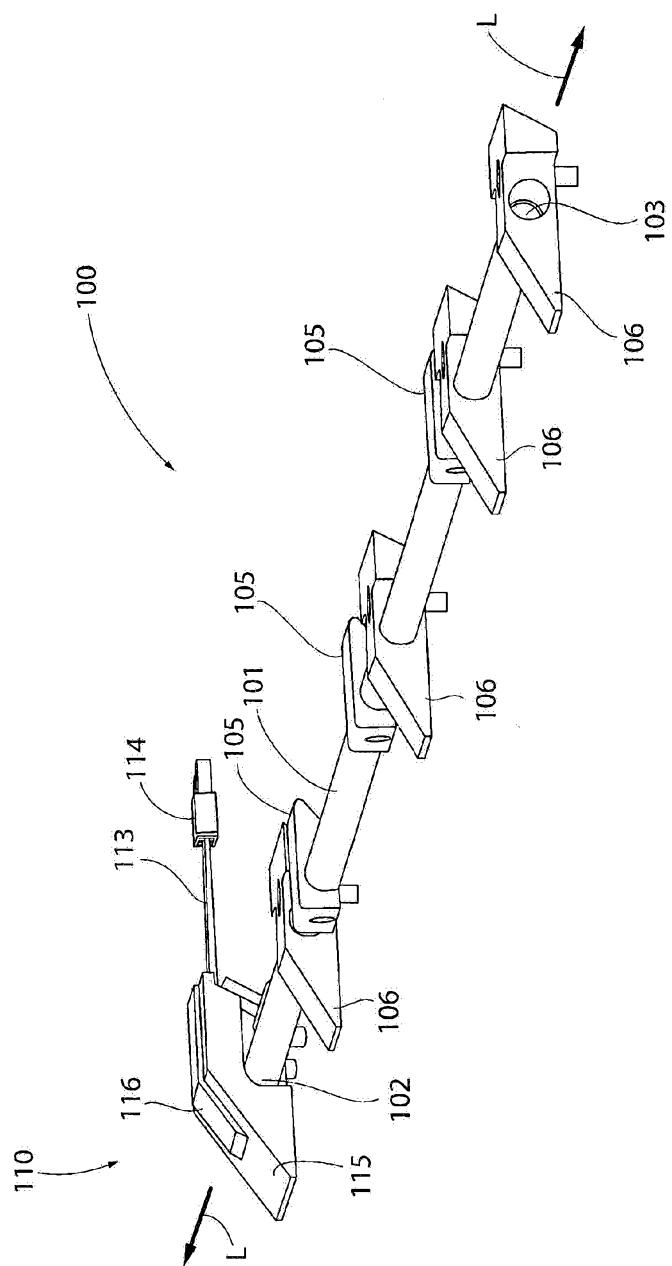


FIG. 4



5  
E