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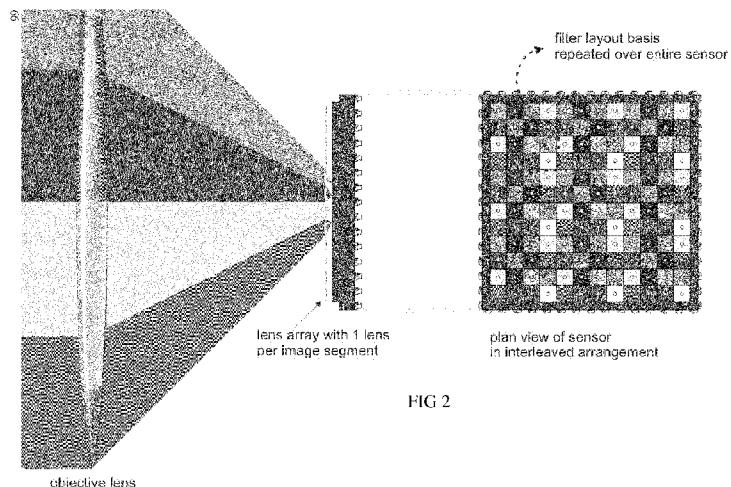


FIG 2

(57) Abstract: A spectral camera has an objective lens (10), an array of lenses (25) for producing optical copies of segments of the image, an array of filters (30) for the different optical channels and having an interleaved spatial pattern and a sensor array to detect the copies of the image segments. Detected segment copies of spatially adjacent optical channels have different passbands and represent overlapping segments of the image, and detected segment copies of the same passband on spatially non-adjacent optical channels represent adjacent segments of the image which fit together. Having segments of the image copied can help enable better optical quality for a given cost. Having an interleaved pattern of the filter bands with overlapping segments enables each point of the image to be sensed at different bands to obtain the spectral output for many bands simultaneously to provide better temporal resolution.

**SPECTRAL CAMERA WITH OVERLAPPING SEGMENTS OF IMAGE COPIES
INTERLEAVED ONTO SENSOR ARRAY**

FIELD OF THE INVENTION

5 The present invention relates to spectral cameras, to methods of configuring such cameras, and to methods of operating such cameras.

BACKGROUND

Spectral cameras are known and some are referred to as multi spectral or hyperspectral imaging systems:

10 Hyperspectral imaging refers to the imaging technique of collecting and processing information from across the electromagnetic spectrum. Whereas the human eye only can see visible light, a hyperspectral imaging system can see visible light as well as from the ultraviolet to infrared. Hyperspectral sensors thus look at objects using a larger portion of the electromagnetic spectrum, as has been described at:

http://en.wikipedia.org/wiki/Hyperspectral_imaging

15 Certain objects leave unique 'fingerprints' across this portion of the electromagnetic spectrum. These 'fingerprints' are known as spectral signatures and enable identification of the materials that make up a scanned object. The hyperspectral capabilities of such imaging system enable to recognize different types of objects, all of which may appear as the same color to the human eye.

Whereas multispectral imaging deals with several images at discrete and somewhat narrow bands, 20 hyperspectral imaging deals with imaging narrow spectral bands over a contiguous spectral range. It can produce the spectra for all pixels in the scene. While a sensor with 20 discrete bands covering the VIS, NIR, SWIR, MWIR, and LWIR would be considered multispectral, another sensor with also 20 bands would be considered hyperspectral when it covers the range from 500 to 700 nm with 20 10-nm wide bands.

25 Hyperspectral sensors collect information as a set of 'images'. Each image represents a range of the electromagnetic spectrum and is also known as a spectral band. These images' each have two spatial dimensions and if images of a series of different spectral bands are effectively stacked to form a cube, then the third dimension can be a spectral dimension. Such a three dimensional hyperspectral cube is a useful representation for further image processing and analysis. The precision of these sensors is typically measured in spectral resolution, which is the width of each band of the spectrum that is captured. If the 30 scanner picks up on a large number of fairly narrow frequency bands, it is possible to identify objects even if said objects are only captured in a handful of pixels. However, spatial resolution is a factor in addition to spectral resolution. If the pixels are too large, then multiple objects are captured in the same pixel and become difficult to identify. If the pixels are too small, then the energy captured by each sensor-segment is 35 low, and the decreased signal-to-noise ratio reduces the reliability of measured features.

Current hyperspectral cameras produce a hyperspectral datacube or image cube, consisting of a stack of 2D images in the x-y plane of the scene in which each image of the stack contains information from a different frequency or spectral band. The spectral range that is captured is not limited to visual light, but can also span Infra Red (IR) and/or Ultra Violet (UV). The 3D Image Cube is captured by a hyperspectral imager,

using an array of sensors that is inherently a 2D sensor. Therefore some form of scanning can be used, so that the cube is assembled over a number of frame periods.

Line scanners or pushbroom systems thus capture a single line of the 2D scene in all spectral bands in parallel. To cover all spatial pixels of the scene, this type of system then scans different lines over time, for example by relative movement of the scanner and the scene. Starers or staring systems capture the complete scene in a single spectral band at a time with a 2D array of sensors and scan over different spectral bands in order to produce the 3D hyperspectral image cube.

It is known from Mathews' 'Design and fabrication of a low-cost, multispectral imaging system" to provide optical duplication onto an array of sensors. Cross talk between image copies is limited by a physical barrier which covers some of the sensor elements. This was available at:

<http://faculty.cua.edu/mathewss/journals/Appl%20Opt%20V47%20N28%202008.pdf>. Another known device using such optical duplication is a 'miniature snapshot multispectral imager' by Infotonics technology center. Again this avoids cross talk by having walls between the image copies on the sensor array.

15

SUMMARY OF THE INVENTION

An object of the invention is to provide improved apparatus or methods.

A first aspect provides an integrated circuit for an imaging system as set out in independent claim 1. This provides a spectral camera for producing a spectral output and having an objective lens for producing an image, an array of lenses for producing optical copies of segments of the image on different optical channels, an array of filters aligned with the different optical channels and having an interleaved spatial pattern of different passbands across the array, and one or more sensor arrays arranged to detect the copies of the image segments on the different filtered optical channels, the interleaved spatial pattern of the array of filters being arranged so that detected segment copies of spatially adjacent optical channels have different passbands and represent segments of the image which at least partially overlap each other, and so that at least some of the detected segment copies of the same passband on spatially non-adjacent optical channels represent segments of the image which are adjacent and fit together.

A benefit of having optical channels for segments of the image rather than for the complete image is that there is an increase in the number of optical channels, and a corresponding decrease in the size of optical components in the channels. This can enable better optical quality for a given cost. Having an interleaved pattern of the filter bands with overlapping segments enables each point of the image to be sensed at different bands to obtain the spectral output for many bands simultaneously to provide better temporal resolution for example, compared to cameras relying on scanning different bands in successive frame periods. This is useful for applications where low latency is needed or where there is relative motion between the camera and the subject for example.

The sensor array can be arranged to detect the copies of the segments of the image simultaneously.

The interleaved spatial pattern and the overlapping of the segments can be arranged to provide a spatially uniform spectral detection for all of the image. This can enable a consistent image cube to be generated.

The interleaved spatial pattern can comprise a two dimensional repeating pattern of the passbands. This is a convenient way to achieve the uniform spectral sampling, though others are conceivable.

40

The interleaved spatial pattern and the overlapping of the segments can be arranged to provide a non uniform spectral detection, having variation in any one or more of: which passbands are detected at different parts of the image, spectral range at different parts of the image, spectral resolution, spatial resolution at different parts of the image, and spatial resolution at different passbands. This can be useful to

5 enable different spectral ranges or different spectral resolutions to be covered, to provide more or less detail in parts of the image cube.

The interleaved spatial pattern can comprise a two dimensional repeating pattern of groups of the passbands, the groups at different parts of the image having a different selection of the passbands. This is a convenient way to achieve such non uniform spectral sampling, though others are conceivable.

10 At least part of the interleaved spatial pattern can comprise segments of width of at least N1 filters and height of at least N2 filters and the overlap of spatially adjacent channels in this part of the interleaved spatial pattern is arranged to be by a factor of 1-1/N1 in a width direction and by a factor of 1-1/N2 in a height direction. A benefit of such a repeating pattern is that the segments for each passband can be fitted together relatively easily to reassemble the image all the passbands and the multiple optical channels can be

15 aligned conveniently onto the sensor array.

The array of filters can be integrated on the sensor array. This can enable reduced cross talk as there is effectively no cavity between the filters and the sensors.

The array of filters can comprise thin films acting as fabry perot cavities having a thickness of half the wavelength of the desired transmission wavelength. This can enable first order operation giving better

20 narrowband spectral shape, better reflection control, and less dependence on angle of incidence for example.

At least some parts of the interleaved spatial pattern can have a superimposed finer pattern of the passbands at a finer granularity than that of the interleaved spatial pattern.

This provides more flexibility by making the spatial positioning of the filters less dependent on the spatial

25 arrangement of the optical channels. This can enable for example balancing of optical quality of pixel position with filter response characteristics, or can even out positional variabilities across all bands.

The spectral camera can have a post processing part for electrically processing the detected segment copies for a given passband to stitch them together. This can enable more contiguous images to be output without gaps.

30 Having different magnifications in the lenses helps enable different resolutions or image sizes.

The array of filters is reconfigurable in use by swapping the array of filters to use a different array of filters. This enables adapting to different applications needing different spectral bands or different spatial arrangement of the filters

The objective lens can have a hexagonal stop and the arrays of lenses and filters can be arranged to give the

35 segment copies a hexagonal outline. This can enable vignetting problems to be reduced. And it can improve telecentricity and thereby spectral resolution, as well spatial resolution. The passbands can be selected to enable part of the sensor array to detect an unwanted higher or lower order spectral response of another part of the sensor array. This can enable such leakage to be compensated later, to enable more accurate spectral detection performance, or to enable the other filters to have more relaxed specifications or

40 tolerances, to reduce costs for example.

Another aspect of the invention provides a method of using a spectral camera for producing a spectral output and having an objective lens for producing an image, an array of lenses for producing optical copies of segments of the image on different optical channels, an array of filters aligned with the different optical channels for passing a selected band of the optical spectrum, the array of optical filters having an interleaved spatial pattern of different passbands across the array, and one or more sensor arrays arranged to detect the copies of the image segments on the different filtered optical channels, the interleaved spatial pattern of the array of filters being arranged so that detected segment copies of spatially adjacent optical channels have different passbands and represent segments of the image which at least partially overlap each other, and so that at least some of the detected segment copies of the same passband on spatially non-adjacent optical channels represent segments of the image which are adjacent and fit together, the method having the step of processing the detected segment copies for a given passband to stitch them together, and to align the stitched copies for the different passbands.

There can be an additional step of swapping during use the array of filters to use an array of filters having a different interleaved pattern.

Another aspect of the invention provides a method of configuring a spectral camera during manufacture, the spectral camera being for producing a spectral output and having an objective lens for producing an image, an array of lenses for producing optical copies of segments of the image on different optical channels, an array of filters aligned with the different optical channels for passing a selected band of the optical spectrum, the array of optical filters having an interleaved spatial pattern of different passbands across the array, and one or more sensor arrays arranged to detect the copies of the image segments on the different filtered optical channels, the method having the steps of selecting the passbands and the interleaved spatial pattern of the array of filters so that detected segment copies of spatially adjacent optical channels have different passbands and represent segments of the image which at least partially overlap each other, and so that at least some of the detected segment copies of the same passband on spatially non-adjacent optical channels represent segments of the image which are adjacent and fit together, and manufacturing the array of filters according to the selected passbands and their spatial arrangement.

The selecting of the lenses, the passbands and their spatial arrangement can be such that there is a variation in any one or more of: which passbands are detected at different parts of the image, a spectral resolution, a spatial resolution of the detection at different parts of the image, and spatial resolution of the detection at different passbands.

Any of the additional features can be combined together and combined with any of the aspects. Other advantages will be apparent to those skilled in the art, especially over other prior art. Numerous variations and modifications can be made without departing from the claims of the present invention. Therefore, it should be clearly understood that the form of the present invention is illustrative only and is not intended to limit the scope of the present invention.

Brief Description of the Drawings:

How the present invention may be put into effect will now be described by way of example with reference to the appended drawings, in which:

Figure 1 shows a schematic view of a spectral camera according to an embodiment,

Figures 2 and 3 shows a schematic views of a spectral camera according to another embodiment, Figure 4 shows a view of image segment copies on the sensor array with different passbands, Figure 5 shows a schematic view of a spectral camera according to another embodiment with a processor for restitching, and a database for the image cube,

5 Figure 6 shows a schematic view of a spectral camera according to another embodiment with a swappable sensor array with integrated filters

Figure 7 shows a view of hexagon shaped image copies,

Figures 8 to 12 show views of different arrangements of overlapping image segment copies on the sensor array with different arrangements of passbands,

10 Figures 14 to 16 show projected image copies with other arrangements of filters according to embodiments, Figures 13 and 14 show steps in methods of operation of the cameras,

Figures 15 and 16 show steps in methods of configuring such cameras during manufacture, and

Figure 17 shows a cross section view of a sensor array integrated with an array of Fabry Perot filters.

15 **Detailed Description:**

The present invention will be described with respect to particular embodiments and with reference to certain drawings but the invention is not limited thereto but only by the claims. The drawings described are only schematic and are non-limiting. In the drawings, the size of some of the elements may be exaggerated and not drawn on scale for illustrative purposes.

20 Where the term "comprising" is used in the present description and claims, it does not exclude other elements or steps. Where an indefinite or definite article is used when referring to a singular noun e.g. "a" or "an", "the", this includes a plural of that noun unless something else is specifically stated.

The term "comprising", used in the claims, should not be interpreted as being restricted to the means listed thereafter; it does not exclude other elements or steps.

25 Elements or parts of the described receivers may comprise logic encoded in media for performing any kind of information processing. Logic may comprise software encoded in a disk or other computer-readable medium and/or instructions encoded in an application specific integrated circuit (ASIC), field programmable gate array (FPGA), or other processor or hardware.

References to software can encompass any type of programs in any language executable directly or indirectly by a processor.

References to logic, hardware, processor or circuitry can encompass any kind of logic or analog circuitry, integrated to any degree, and not limited to general purpose processors, digital signal processors, ASICs, FPGAs, discrete components or transistor logic gates and so on.

30 References to optical are intended to encompass at least wavelengths within the human visible wavelength range and also infra red wavelengths, and shorter wavelengths, extending into the ultra violet bands, where the sensitivity to manufacturing variations in thickness of the optical filter are even more pronounced. In some embodiments, the optical filters and optical sensors can be limited to a range which is any subset of these wavelengths, for example visible wavelengths only, or visible and shorter wavelengths.

35 References to arrays of optical filters or arrays of optical sensors are intended to encompass 2-dimensional arrays, rectangular or non rectangular arrays, irregularly spaced arrays, and non planar arrays for example.

References to integrated circuits are intended to encompass at least dies or packaged dies for example having the array of optical filters monolithically integrated onto the array of sensors, or devices in which the array of optical filters is manufactured separately and added later onto the die or into the same integrated circuit package.

5 References to a spectrum of wavelengths are intended to encompass a continuous spectrum or a range of nearly adjacent discrete bands for example.

Furthermore, the terms first, second, third and the like in the description and in the claims, are used for distinguishing between similar elements and not necessarily for describing a sequential or chronological order. It is to be understood that the terms so used are interchangeable under appropriate circumstances and

10 that the embodiments of the invention described herein are capable of operation in other sequences than described or illustrated herein.

Moreover, the terms top, bottom, over, under and the like in the description and the claims are used for descriptive purposes and not necessarily for describing relative positions. It is to be understood that the terms so used are interchangeable under appropriate circumstances and that the embodiments of the

15 invention described herein are capable of operation in other orientations than described or illustrated herein.

Reference throughout this specification to “one embodiment” or “an embodiment” means that a particular feature, structure or characteristic described in connection with the embodiment is included in at least one embodiment of the present invention. Thus, appearances of the phrases “in one embodiment” or “in an embodiment” in various places throughout this specification are not necessarily all referring to the 20 same embodiment, but may. Furthermore, the particular features, structures or characteristics may be combined in any suitable manner, as would be apparent to one of ordinary skill in the art from this disclosure, in one or more embodiments.

Similarly it should be appreciated that in the description of exemplary embodiments of the invention, various features of the invention are sometimes grouped together in a single embodiment, figure, 25 or description thereof for the purpose of streamlining the disclosure and aiding in the understanding of one or more of the various inventive aspects. This method of disclosure, however, is not to be interpreted as reflecting an intention that the claimed invention requires more features than are expressly recited in each claim. Rather, as the following claims reflect, inventive aspects lie in less than all features of a single foregoing disclosed embodiment. Thus, the claims following the detailed description are hereby expressly

30 incorporated into this detailed description, with each claim standing on its own as a separate embodiment of this invention.

Furthermore, while some embodiments described herein include some but not other features included in other embodiments, combinations of features of different embodiments are meant to be within the scope of the invention, and form different embodiments, as would be understood by those in the art. For 35 example, in the following claims, any of the claimed embodiments can be used in any combination.

In the description provided herein, numerous specific details are set forth. However, it is understood that embodiments of the invention may be practiced without these specific details. In other instances, well-known methods, structures and techniques have not been shown in detail in order not to obscure an understanding of this description.

40 The invention will now be described by a detailed description of several embodiments of the

invention. It is clear that other embodiments of the invention can be configured according to the knowledge of persons skilled in the art without departing from the technical teaching of the invention, the invention being limited only by the terms of the appended claims.

Introduction to some issues addressed by the embodiments.

5 Hyperspectral imaging systems or cameras can consist of different discrete components, e.g. the optical sub-system for receiving the incoming electromagnetic spectrum, the array of filters for creating the different bands within the received spectrum and the image sensor array for detecting the different bands. The optical sub-system can consist of a single or a combination of different lenses, apertures and/or slits. The array of filters can consist of one or more prisms, gratings, optical filters, acousto-optical tunable filters, liquid crystal tunable filters etc or a combination of these.

10 A feature of spectral imaging is that, because an entire spectrum is acquired at each point, the operator needs no prior knowledge of the sample, and post-processing allows all available information from the dataset to be mined. Disadvantages are cost and complexity. Fast computers, sensitive detectors, and large data storage capacities are needed for analyzing hyperspectral data. Significant data storage capacity is necessary since hyperspectral cubes are large multi-dimensional datasets, potentially exceeding hundreds of megabytes.

15 Sensing spectral information is typically achieved either using dispersive optical elements or spectral filters. Dispersive optical elements such as prisms or gratings have limited light throughput and require time-consuming spatial scanning over multiple frames, as they sense only 1 spectral and 1 spatial dimension at a time. Spectral filters capture only 2 spatial dimensions (width W and height H) at one wavelength and thus require spectral scanning over multiple frames, requiring significant amounts of time due to the large switching overhead.

20 In order to capture NB wavelengths using standard optics, the scene still needs to be scanned spatially in front of the sensor over NB frames such that each position is sensed using NB different filters. Acquiring the full cube in one frame period thus requires mapping all 3 dimensions of the cube on the 2 dimensions of the sensor, or likewise, each spatial point should somehow be duplicated NB times over the sensor array, such that the NB different spectral samples are sensed.

Fig 1, spectral camera according to an embodiment

25 Embodiments as described below can now enable higher-speed acquisition of the 3D HSI cube to enable snapshot imaging, by mapping each point in the WxHxNB-sized cube (where NB is the number of passbands) to a sensor element on the sensor array more efficiently. Each of the WxH spatial points sensed in the scene is optically duplicated NB times on the sensor array, by subdividing each of the NB spectral subimages in a number of segments, and interleaving these segments alongside each other on the 2D sensor. Due to the limited space on the sensor array, there will usually be a trade-off between spatial and spectral resolution.

35 The optical duplication is realized by carefully positioning the objective lens and its image relative to the optical channels on the sensor array and their respective lenses in such a way that each spatial point is duplicated in a group of $\sqrt{NB} \times \sqrt{NB}$ overlapping segments, e.g. in 3x3 image segments for example.

This is achieved by forcing the lenses to operate at an inverse magnification of \sqrt{NB} , which is ensured by

tuning the distance between the lenses and the objective image. The lenses should be positioned at a distance of $(M+/-1).f_{lens}$, depending on the system configuration. M represents the inverse magnification and is determined based on the number of spectral bands.

Figure 1 shows a schematic view of a camera according to an embodiment. An objective lens 10 is followed by an array of lenses 25 for providing multiple image segment copies projected onto a sensor array 40. An array of filters 30 is integrated on the sensor array. There are typically many more than NB optical channels, each created by one of the lenses in the array. Each channel is arranged consisting of 1 (single or compound) lens system. The NB lens (systems) can be judiciously placed to ensure the correct positioning of the NB duplicated scene copies on to the NB filter tiles.

Image segment copies on the sensor array are interleaved, so that those of the same passband are spaced apart so that they represent adjacent segments of the image and are interleaved with overlapping segment copies of different passbands. All detected segments each corresponding to one specific band can be stitched together to produce one plane of the image cube. The size of the segments is a design parameter, and determines the corresponding maximal size of its lens and the number of segments. Since the resulting segments and lenses can be significantly smaller than those of the tiled imager, (smaller) microlenses may be used. This improves the lens' optical performance and resolution. However, compared to the tiled imager, producing a spectral slice out of the cube requires stitching together the segments of that band.

Light throughput is likely to be higher for the interleaved imager, due the positioning of the (micro)lenses near to the objective image. Crosstalk can be avoided by either matching the objective speed to the microlens speed and using the objective aperture as a field stop, resulting in trade-off between system light throughput and vignetting inside the segments, or by adding (micro)baffles between the segments, enabling both high-light throughput and crosstalk segmentation.

It is desirable to have the array of filters integrated with the image sensor array. This integrated component or module can be combined with an optical sub-system to form a complete camera system. The sensor array is typically an integrated circuit with a monolithically integrated array of filters, and can be referred to as a spectral unit. The problem of long acquisition time can be partially overcome using high light throughput integrated filters formed for example by a HSI wedge technology as set out in patent application WO2011064403 by IMEC. Practical commercial implementations of such cameras should be compact, be capable of manufacture at low cost, and be reconfigurable. In certain aspects, process technology aspects are combined with the system integration and image processing techniques to alleviate the integrated circuit manufacturing process requirements.

Figure 2 spectral camera according to another embodiment,

Figure 2 shows a schematic view of a spectral camera according to another embodiment, similar to that of figure 1 and showing a particular implementation with more detailed representation of the light paths and the effects of a set of lenses 25 for carrying out the optical duplication. There is also a plan view of the image segment copies on the sensor array from where they can be detected, read out and stored as an image cube in a data buffer. As before there is an objective lens 10 followed by an array of lenses 25, arranged so that the incoming light from the objective lens is divided into optical channels, so there is one lens per image segment. The plan view of the image segment copies shows that there is a regular pattern of passbands in the form of a 4x4 block which is repeated over the sensor array.

Some practical effects of the arrangement shown are as follows:

The objective lens can enable zooming and refocusing flexibility, if objective lens speed remains fixed (or more precisely, matched to that of the microlenses)

It is compatible with standard lens mounts

5 Full sensor usage is theoretically possible using tuned field stop and lens system positioning.

Good optical performance (high resolution, wide FOV, high light throughput) is possible using stock lens components, due to reduced lens sizes owing to the interleaving.

Standard mounting of (compound) lenses is possible.

Stitching (combined with vignetting, lens sheet defects,...) required to reconstruct spectral tiles.

10 **Figure 3, magnified view of part of the spectral camera**

Figure 3 shows a magnified view of part of the camera of figure 2. This shows a side view of the lenses and the sensor array with integrated filters. There is a filter of a particular band for each lens. Hence only the light of a given colour will be detected for each lens. Hence although the image shows coloured beams on the left of the lens, this is not intended to be realistic, as all colours would reach the filters from the left, and 15 just one colour would pass through to reach the detectors. For each lens, light from one segment of the image reaches a block of sensor elements as shown in the plan view of the sensor array. Each block of sensor elements corresponds to one of the lenses (which can be microlenses if the block is small enough).

Figure 4, plan view of image segment copies with different passbands,

Figure 4 shows a more detailed view of another example of an arrangement of the overlapping image

20 segments, seen in plan view as the image segments are projected on the sensor array. At top left is a representation of a part of the pattern which repeats. This shows there are nine bands and the nine corresponding filters are arranged in a three by three grid, a top row having bands 1,2 and 3, a second row having bands 4,5,6 and a bottom row having bands 7, 8, and 9. The different colours of the bands are represented by levels of shading. Each band repeats every three blocks. Each block can have many sensor 25 elements, and a corresponding number of image pixels. As can be seen in the plan view, the blocks each represent image segments with a certain fixed amount of overlap of the segment of the image between adjacent blocks, in this case the overlap is 66% for an adjacent block. This means that there is 33% overlap with blocks that have one intervening block, and no overlap with blocks that have two intervening blocks. This means that if all the blocks of the same passband are taken, there is no overlap and they can be 30 stitched together to recreate the original image. The repeat is uniform in both spatial directions in this case though more complex examples with variations are set out in other figures.

Figure 5, processor for restitching,

Figure 5 shows a schematic view of a spectral camera according to another embodiment similar to that of figure 1 with the addition of a processor 200 for restitching, after read out of the sensor array. The

35 processor can be incorporated into the camera or can be part of an external image processing system for example. This could be used to restitch the parts of the images for each band read out from the sensor array for the arrangement of filters represented in figure 4. The processor can be implemented in the form of an address generator for a data buffer, arranged so that as the sensor array is read out into the data buffer, suitable addresses are generated to store the parts of the image for one band in addresses corresponding to a 40 single frame, as if it had been restitched.

Figure 6 swappable sensor array to change integrated filters,

Figure 6 shows a schematic view of a spectral camera according to another embodiment similar to that of figure 1 and with a swappable sensor array 42 with integrated filters. In this case the swapping can be implemented by rotating the swappable sensor array about a pivot 41, so that it takes the position of the

5 original sensor array 40. In principle other arrangements are conceivable. For example the optical path could be moved to the swappable sensor array rather than moving the sensor array, or the swappable array could be slid rather than rotated. Any number of different sensor arrays could be fixed to the pivot. In some cases, if needed, the optical duplicator such as a lens array could also be swapped if needed, so that the layout of image copies or their magnifications could be changed. In some cases the field stop might also

10 need to be changed, though this could be implemented as a separate mechanism.

Figure 7 hexagon shaped image copies,

Figure 7 shows a view of hexagon shaped image copies on hexagon shaped filters. This shows three complete hexagon shaped image copies 230, 240, and 250, and a number of half image copies, 260, 270, 280, and 290. The half copies as well as the corner segments could be restitched to make complete images

15 at different bands.

Figures 8 to 12, other examples of image segment arrangements and passband patterns

Figure 8 shows an example similar to that of figure 4 except that the repeat in the pattern is four blocks by four blocks. There are seven bands in this case, and bands 1,2 and 3 appear four times in the repeat while bands 4,5,6 and 7 appear only once. Hence as can be seen, for any of bands 1,2 and 3, they occur again

20 with only one intervening block, while the other bands occur with three intervening blocks between adjacent ones of those bands. Hence in order to obtain full image coverage at bands 4,5,6 and 7, these bands should have lower magnification. This can be achieved by designing the lenses of the lens array to provide that level of magnification for particular ones of the lenses located corresponding to the bands 4,5,6 and 7. Some parts of the picture show this difference in magnification as the image features are shown

25 smaller. This means the spatial resolution at these bands will drop, assuming the pitch between sensor elements is constant.

Figure 9 shows another example similar to that of figure 4 except that in this case the bands have been selected to give a variation in spectral resolution for different bands. The difference between adjacent bands is 50nm except for bands 4,5,6,7 and 8 where the difference between adjacent bands is 15nm or less for

30 example. This gives better spectral resolution in this part of the spectrum.

Figure 10 shows another example similar to that of figure 4 except that in this case the bands selected for segments at the periphery of the image are bands 1,2,3,4,5,6,7,8,9, while different bands are chosen for the central part of the image. So this is an example of variation of bands selected at different parts of the image.

Figure 11 shows another example similar to that of figure 8 except that in this case one of the blocks, labeled as corresponding to band 5, has a finer granularity pattern of different bands. This means the

35 spectral resolution within this block rises and the spatial sampling therefore will drop. In case this causes aliasing, then some optical aliasing may be needed. And this is achieved by selecting the arrangement of filters without needing different lenses. As the spatial resolution drops, there should be some blurring or spreading applied to provide an anti-aliasing effect to ensure that the sensor elements in a cluster corresponding to one image pixel and filtered at different bands, do not detect different parts of the image.

For an interleaved system there is an extra degree of freedom by modifying individual subimage lens properties, e.g. magnification, but also focusing: by defocusing a lens, spatial resolution within that subimage reduces, and spectral resolution may be increased. The latter idea notably allows regular imaging to be interleaved with a pattern of high-resolution spectroscopy content.

5 Figure 12 shows another example which is a hybrid similar to that of figure 10. In this case, like in figure 10, different bands (2,5,6 and 8) have been selected for the central part of the image. At the periphery, bands 1 to 9 are used. Unlike figure 10, the spatial resolution shows variation at different parts of the image. This is indicated by the fact that the repeat in the centre is for 2 x 2 blocks, whereas it is for 3 x 3 blocks at the periphery of the image. In this case, different magnification by the lenses will be needed.

10 **Design for optical fall-off and module sensitivity**

When designing the integrated module, consisting of both the image sensor array and the filter structure, cross-component optimizations can be done. For modules targeting low-cost and/or compact systems, lower quality optics can be expected. One effect which can be tackled in this context, is vignetting. Vignetting is a reduction of an image's brightness or saturation at the periphery compared to the image center. When this effect is coupled to the wavelength dependent efficiency of the Fabry-Perot filter and image sensor, both effects can be co-optimized in order to flatten the wavelength dependent behavior, instead of strengthening it.

15 Vignetting causes the light intensity to drop from the center towards the sides of the image. The effect of the intensity fall-off can be compensated for by the illumination, as is known to those skilled in the art, by the use of so-called illumination profiles. Both effects, vignetting and sensor sensitivity, affect the efficiency of the module for a certain arrangement of the filters. In order to flatten the sensitivity and overcome this additive behavior of both effects, a suitable choice of arrangement of the filters and the design of the array of lenses can be made that takes both effects into account. This can be combined with illumination profiles, if needed, and when the application permits.

20 25 As has already been discussed in the foregoing paragraphs, one part of the design of the hyperspectral imaging module, is the arrangement of the different filters over the image sensor array. In general, the design process can be split into the following parts:

1. selection of the targeted wavelength ranges,
2. selection of an image sensor array for that range,
3. selection of the targeted spectral sampling (and spectral resolution),
4. design of the image copies by designing the array of lenses, and
5. design of the different Fabry-Perot filters and their arrangement in the array.

Figures 13 and 14 steps in methods of operation of the cameras,

30 Figures 13 and 14 show steps in methods of operation of the cameras. In figure 13, a first step 400 is preliminary registration to set outlines of the image copies, for example by mechanical adjustment of the objective lens or other optical component, or of the location of the sensor array. Step 410 is the read out from the sensor array of the detection signals of the projected image copies at the different passbands, in one frame time. Step 420 is storing these signals as values in a database to represent the image cube for that instant, or for a number of instants. Figure 14 is similar to figure 13 with the addition of the step 430 of 35 40 swapping the sensor array for one with a different array of filters.

With any of the embodiments described, there can be additional sampling over multiple frame times if a spatial scanning mechanism is used to change the field of view or the angular position of the view in consecutive frame periods. This can extend the image cube or make it more dense in the spatial directions.

Figures 15 and 16 methods of configuring cameras during manufacture,

5 Figure 15 shows steps in methods of configuring such cameras during manufacture, with step 500 showing a first step of selecting how many image copies to provide and how to arrange them on the sensor array. Step 510 shows selecting passbands and selecting the spatial arrangement of the passbands on the image copies. Step 520 shows manufacturing the layers of the integrated filters according to the passbands and their spatial arrangement. Figure 16 is similar to figure 15 except that step 510 is replaced by step 515 in
10 which the selection of passbands and their spatial arrangement is such as to have some variation of which passbands are detected in different parts of the image cube, or variation of spatial or spectral resolution of the detection in different parts of the image cube. This may involve the spatial pattern having a finer granularity than the image copies, so for a part of the array of filters for a respective one of the image copies there is a spatial pattern of multiple different ones of the passbands.

15 **Figure 17 integrated Fabry Perot filters.**

Figure 17 shows a cross section view of a sensor array 40 integrated with an array of Fabry Perot filters 31. This has a top semi mirror coating 33 and a bottom semi mirror coating 32. Although gaps are shown between the parts, this is for clarity and in practice there would be no gaps. More details of examples of this part are now set out.

20 **Semiconductor processing**

The array of filters can be integrated with the image sensor array using semiconductor process technology, i.e. the spectral unit is post processed on the substrate comprising the image sensor array using semiconductor process technology and process steps. Examples of such semiconductor technology are Complementary-Metal-Oxide-Semiconductor (CMOS) processing, whereby the image sensor array is a
25 CMOS sensor, and Charge-Coupled-Device (CCD) processing, whereby the image sensor array is a CCD sensor. These manufacturing techniques are ideally suited for producing integrated electronic circuits. Such monolithic integration allows manufacturing at low cost while offering a higher performance as no interface layers are needed to attach the spectral unit to the substrate. Hence stray light effects are considerably reduced.

30 Given the large range of technology generations, one can choose to manufacture the sensor in a lower cost technology having a large critical dimension (CD), e.g. 130nm, resulting a larger pixels and smaller spatial resolution of the image sensor array. Alternatively one can choose to manufacture the image sensor array in a state in a higher cost technology having a smaller critical dimension (CD), e.g. 45nm, resulting a smaller pixels and higher spatial resolution of the image sensor array.

35 The image sensor array can be a front-illuminated sensor, whereby the array of filters is post processed on top of the substrate comprising the sensor. Optionally this substrate is thinned afterwards thereby removing the bulk of the substrate and leaving a thin slice containing the image sensor array and the spectral unit monolithically integrated therewith. Alternatively the image sensor array can be a back-illuminated sensor, whereby first the substrate comprising the sensor is thinned from the backside onwards. On backside the
40 thinned substrate the spectral unit is then post processed.

Although any order of Fabry-Pérot filters can be manufactured and used, preferably only 1st order Fabry-Pérot filters are formed on the image sensor array thereby reducing the complexity for removing and/or blocking higher order components. A monolithically integrated hyperspectral imaging system with a 1st order Fabry-Pérot filter array typically doesn't require a focusing lens in the optical subsystem.

5 Examples of complete hyperspectral imaging systems comprising the optical subsystem and the monolithically integrated array of filters and image sensor array are disclosed. These complete imaging systems exploit from the benefits of the monolithically integration to allow freedom in designing the optical subsystem.

The design of the filters, e.g. the thickness which defines the cavity length of the filters, can take into account the location of the particular filter on the chip to reduce the dependency on variations in the incident angle of the incoming electromagnetic spectrum.

The filter is post-processed on top of an image sensor array and every filter is aligned with the rows or columns of the image sensor array.

The filters can be monolithically integrated, meaning that the filter structures are directly post-processed on top of the image sensor. This integration has very important advantages and some consequences, compared to filter structures that are separately produced and then assembled with the imager later. Advantages of monolithic integration are cost reduction through standard CMOS production steps, reduction in stray light, allow design for first order and avoid the need for a focusing lens.

When compared to a hybrid integration, in which the filter structures are separately produced and then assembled with the image sensor into the hyperspectral module, there are some advantages to a monolithic integration. Firstly, the combination of both production sequences into one combined flow leads to an overall simplification and cost reduction in the production, when compared to a hybrid integration of the filter structures that are separately produced and then later assembled with the sensor into the module. This is especially the case for this filter, as the post-production of the filter structures requires only CMOS

25 compatible fabrication steps, like deposition, patterning and etching. By adding these steps to the normal production flow of the image sensor, expensive, error prone and labor intensive assembly steps are prevented. E.g for a filter with 3 layers of oxide and amorphous silicon in a Bragg stack and 127 different thicknesses in the cavity, around 50 lot-turns are needed, giving an additional cost of more or less 20% with respect to standard CMOS imagers. The number of lot turns for the deposition of the top and bottom mirror

30 layers can even be reduced if the different layers can be deposited, one after the other, in the same tool.

Secondly by manufacturing the filter structure directly on top of the pixels of the imager, photons can pass directly from the filter into the pixel below. In the case of front side illuminated sensors, photons will first pass through the metallization layers and some dielectric layers. When the filter structure is produced separately and stacked on top of the image sensor, there will always be a non-functional layer or gap in 35 between both structures.

Even when the filter and substrate combination is flipped and the filter is located in between the supporting substrate and the image sensor, the light will pass through the substrate first, then through the filter and finally through a thin air or glue gap, before it hits the image sensor photodiodes. When a filter structure is combined with an image sensor, be it stacked on top of each-other with air or glue between the different

layers, this extra substrate between the filter structure and the underlying rows of pixels will always give rise to a certain amount of performance degradation because of:

1. cross talk

Photons that exit the filter structure above a certain pixel can cross the gap and fall onto a neighboring pixel. This effect will be heavily reduced when the gap is reduced or completely removed by a direct postprocessing of the filter onto the pixels. There can still be some cross-talk as a result of the thickness of the filter itself however, as a photon that enters the filter above one pixel can still propagate through the filter and fall onto a neighboring pixel. This is reduced by designing thinner filters and by controlling the angle of incidence.

10 2. stray light

The extra non-functional layer gives rise to extra reflections on its boundaries if the refractive indices are not matched and therefore to extra stray light on top of the cross-talk discussed above. By reducing the effective distance S between the filter and the pixel array of the image sensor for different incident angles stray light is reduced. For a smaller distance S , e.g. 1nm, the distance that is traveled by the stray light (D) is well within normal pixel dimensions (e.g. 1 to 15 μm). This is not the case for more macroscopic integration distances, e.g. 1 mm substrate, in which case the distance of the traveled light D ranges over tens to hundreds of pixels, leading to a severe deterioration of the spatial and spectral resolution. In some cases, the distance D can become so large, an additional focus lens is required to focus the light back onto the pixel.

20 3. parasitic Fabry-Perot arising because of the stray light:

Additionally, as indicated in the previous item, the dielectric stack and metals on top of the photodiodes reflect part of the light. Together with the gap because of the heterogeneous integration and the bottom mirror of the cavity, this forms a parasitic Fabry-Perot interfering with the actual one. This process can be optimized with the monolithic integration as the dielectric layers in the imager 25 become part of the bottom Bragg stack, made in similar materials (e.g. oxide) and which is not very sensitive to the width of these layers.

One important reason why the hybrid filter structures that are post-production assembled onto the image sensors suffer from this problem, is the fact that the construction of very thin filter structures separately, 30 requires the additional insertion of a (transparent) support structure to mechanically support the filters and enable the stacking. When this layer is placed between the filter and the image sensor, the non-functional gap consists of this layer and an additional air or glue gap in between the support layer and the image sensor. When the support structure is placed on top, it can also generate additional reflections and should be optimized separately (e.g. by adding anti-reflective coatings), but still there will be an air or glue layer in 35 between the filter and the image sensor. All of this can be made redundant by post-processing the filter structures directly on top of the image sensor, as has been discussed above.

A third advantage is that the monolithic integration, combined with very precise CMOS fabrication techniques, enables the construction of filter structures with much smaller thicknesses. As discussed later, the Fabry-Perot filter structure is designed to select a certain wavelength by tuning the cavity length.

40 Thinner filters are less sensitive to the incident angle, as the internal reflections in the filters cover less

distance for non-perpendicular incidence. A thicker filter will suffer from a larger displacement D of the transmitted beams, ranging well over 10 mm. This leads to a severe reduction in spatial and spectral resolution, as the light that passes through the filters will fall onto other rows or columns of pixels. This macroscopic filter hence requires a focusing lens. The thin filters are much less sensitive to this and the displacement D stays in most cases below the pixel dimensions, i.e. preferably in the 1 to 10nm range, for all but the largest angles of incidence and the smallest pixels sizes. Traditional production techniques, in combination with hybrid integration of the filter structure and the image sensor, can not reach the required accuracy to fabricate Fabry-Perot filters of the first order. Hence, higher order Fabry-Perot structures have to be used. In that case, additional dichroic or other filters have to be added to the module, in order to select the required order only. This gives rise to additional energy loss, additional costs and hence reduced overall system optimality.

Finally, when a Fabry-Perot filter is placed some distance away from the image sensor, the output of the filter exhibits phase differences that, when focused by a lens, take on the form of concentric circles. The concentric circles are a result of the different interfering waves where you have at different locations 15 constructive and destructive interference. The focusing lens is needed for macroscopic filters because of the large distances covered by reflections inside the filter and in order to focus all these reflections back onto one pixel. In the disclosed integrated imaging module, the distance between the filter structure and the image sensor is very small and as the filter is designed for the first order, there is no need for a focusing lens. Thin filters don't need this focusing lens, because internal reflections cover much smaller distances 20 and in the case of the proposed filter, all light still falls in one pixel (after a very large number of internal reflections, the energy that is left in the light ray that exceeds the size of a single pixels is negligible). The concentric circles that are the result of the phase difference, will still be there, but will all be focused inside the same pixel and their effect is all integrated in the output of that pixel.

The direct post-processing of the filter structure on top of an active IC, in this case the image sensor, should 25 be compatible with the contamination, mechanical, temperature and other limitations of that IC. This means that e.g. none of the steps used in the fabrication of the filter can use materials or processing steps that would damage the image sensor below.

As will be discussed below, one of the most important limitations is the restriction on the available materials, taking into account the CMOS production environment. In the proposed filter, the material 30 selection has been done such that standard materials have been used, that are fully compatible with standard processing. Using some materials is not possible, e.g. Au or Ag, as they tend to diffuse into the different layers and into the tools and thereby negatively affect the yield of the current and even future processing steps. In some cases, such a layer can still be acceptable as a final step (top layer), when the deposition is done outside of the normal processing line and when the tool is only used for that purpose. This can only be 35 done as a final step, as the wafer can not enter the normal flow after this operation. Another limitation, related to the material selection, is the temperature budget or the temperature window that is still available for processing. In order to perform the post-processing without damaging the image sensor. To prevent damage, the maximal temperature of the processing steps should not exceed a certain maximum, e.g. 400 degrees C. This also restricts the choice of materials and crystallization that is available for the design.

40 With respect to a hybrid approach, where the image sensor and a separately produced filter structure are

assembled into a module later, there is less freedom here. In case of a monolithic design, the restrictions have to be taken into account throughout the design. If certain design choices can be made during the design of the image sensor itself, to relax the constraints on the processing of the filter (e.g. to raise the allowed temperature for post-processing), this can be taken into account too. This then leads to an 5 optimization problem at the module level, instead of for the image sensor and the filter structures separately. The restriction on the filter structures always apply, as it is processed later and on top of the image sensor.

Fabry-Perot Filter:

Every pixel of the image sensor can have its own optical filter, sensitive to one specific wavelength. The 10 organization of different optical filters on the sensor depends on its usage. Different types of filters exist which can be integrated, such as dichroic filters. The type that is used in the examples described is the Fabry-Perot Interferometer.

A Fabry-Perot filter is made of a transparent layer (called cavity) with two reflecting surfaces at each side of that layer. Fabry-Pérot wavelength selection involves multiple light rays within the cavity being 15 reflected, which results in constructive and destructive interference, based on the wavelength of the light, on the distance l between the semi-mirrors and on the incident angle θ . (b) Higher orders are also selected, which results in an order selection problem. The filter operation is based on this well-known Fabry-Pérot principle, in which the height of each filter is selected to be tuned to the desired passband. Each filter is formed by a resonant cavity of which the resonance frequency is determined by the height of the filter. On 20 the top and bottom of the cavity, a semi-transparent mirror is placed to partially reflect the light ray. Because of the reflections, an optical path difference is introduced resulting in destructive and constructive interference (depending on the incoming wavelength). More details of the principles and characteristics of such filters are set out in above mentioned patent application WO2011064403.

Design of the Optical Filter

25 Reflecting surfaces:

The design and performance of the reflecting surfaces on both sides of the cavity are crucial to the performance of a Fabry Perot optical filter. A Fabry-Perot optical filter with high finesse, and thus good spectral resolution, can only be obtained by using highly reflective mirrors. A second important parameter of the mirrors is their absorption, as this will determine the efficiency of the filter. If a full range of Fabry- 30 Perot optical filters has to be constructed over a certain wavelength range, it is beneficial that these two parameters (reflectivity and absorption) stay as constant as possible over this spectral range. In that case, the wavelength range can be covered/sampled by varying only the cavity length of the Fabry- Perot filters and the materials and mirror layers can be kept constant. The selected wavelength range has to match the sensitivity of the selected image sensor, which is the second component of the module

35 Current solutions proposing monolithic Integration use specific non-standard sensor designs, increasing the cost or decreasing the speed. Switching to CMOS compatible processing steps on CMOS sensors raises integration issues as it has consequences on e.g. the material selection, due to contamination and temperature budget. Metals like Ag for the bottom mirror can't be used. State of the art Fabry-Perot filters needs to use Al, causing a serious decrease of the filter quality or optical throughput (speed). Dielectric 40 stacks are preferred but the contamination level and temperature budget limits the material selection.

Process compliant materials needed having the correct combination of n/k to obtain the needed spectral range in the selected frequency range. An example of these dielectric materials having low n material is SiO₂, possibly tuned to decrease n even further. An example of a high-n material is amorphous silicon, with reduced absorption index because of process parameter tuning, e.g. temperature and hydrogen content.

5 Hard oxides have better tolerances but cannot be used because of the need for higher temperatures than allowed by standard CMOS processing.

An example of such alternative mirror system is a (distributed) Bragg stack, which is formed by combining two types of dielectrics into an alternating stack of two or more materials: one with a low refractive index and one with a high refractive index. A first characteristic of a Bragg stack is its bandwidth, as given by

10 equation 1, i.e. the spectral range $\Delta\lambda_0$ over which the reflectivity is more or less constant.

$$\Delta\lambda_0 = \frac{4\lambda_0}{\pi} \arcsin\left(\frac{n_2 - n_1}{n_2 + n_1}\right) \quad (1)$$

From this equation, it can be seen that the bandwidth $\Delta\lambda_0$ depends on both the central wavelength λ and the refractive indices n_1 , n_2 of the selected materials. To be able to cover a wide spectral range, around a certain central wavelength (e.g. 600 nm spectral range around 700 nm), a big difference between n_1 and n_2 is

15 needed. From the list of materials that are used in standard semiconductor processing, SiO₂ has one of the lowest refractive indices (1:46) and a very low absorption coefficient. Both parameters are stable over a very large spectral range. For a spectral range of 600nm around a central wavelength of 700nm (the VNIR range), this means that the second material in the Bragg stack will ideally need to have refractive index equal to 6:4, in addition to an absorption coefficient as close as possible to 0. There is no such ideal material available in the standard IC processing materials, compatible with the process flow, and adapting existing materials for a better refractive index and lower absorption is needed. The refractive index of SiO₂ can be lowered by making it porous (mix it with air, which has a refractive index of 1). This results in a need for better manufacturable refractive index equal to 5 for the same spectral range and central wavelength. Another example of material engineering is lowering the absorption index of amorphous 20 silicon by changing process (deposition) parameters, like temperature, concentration of hydrogen, etc.

$$R = \left[\frac{n_0(n_2)^{2N} - n_s(n_1)^{2N}}{n_0(n_2)^{2N} + n_s(n_1)^{2N}} \right]^2 \quad (2)$$

As indicated by Equation 2, the reflectivity R of such a Bragg mirror is easily controlled by the number of pairs of dielectric layers. The more layers, the higher the reflectivity and the higher the finesse of the Fabry-Perot filter that will be built with that particular mirror. In Equation 2, n_0 is the refractive index of

30 the surrounding medium, n_s is the refractive index of the substrate, n_1 is the refractive index of the first material, n_2 is the refractive index of the second material and N is the number of pairs in the Bragg stack. One instantiation of a distributed Bragg stack is a combination of SiO₂ and engineered amorphous Silicon for a central wavelength around 700nm and a range from 540 nm to 1000 nm. A second instantiation is a combination of SiO₂ and SiGe for a central wavelength of 1500 nm and a bandwidth of 1000 nm, in casu

from 1000 nm to 2000 nm. A consequence of using Bragg stacks for the mirror layers is an additional phase shift during the reflection of the light.

In use, the appearance of second order leakage is the result of the fact that a Fabry-Perot filter which is designed for wavelength λ_j also passes incoming wavelengths that are a multiple of λ_j , called higher orders.

5 However, only those higher order wavelengths that fall in the wavelength range for which both the Fabry-Perot filter and the underlying image sensor have a reasonable efficiency should be considered.

Manufacturing

Fabrication methods for manufacturing 1D or 2D Fabry-Perot filters can include successive patterning and etching steps, requiring a large number of processing steps in order to produce k different thicknesses.

10 **Planarity of the image sensor**

In order to start with a well controlled state, it is important that the image sensor is planarized before the filter structure is built up. This can be done using a deposition step, followed by a CMP (Chemical Mechanical Polishing) step to remove all topography. By doing this, the rest of the processing does not depend anymore on the exact BEOL arrangements. The thickness and the material of this planarization 15 layer can to some extent be taken into account during the design of the filter structure. However, this layer is not a part of the active filter structure and does not have a large effect on the filter itself, as long as the correct material transition (important for the refractive index) is correctly taken into account. As the Fabry-Perot filter will be deposited on top of this planarization layer, variation in this layer will be not propagated up, as long as the variation is sufficiently slow across the wafer (e.g. no sharp edges). As CMP is able to 20 generate a surface with across wafer flatness and variations at the nanometer scale, this requirement can be fulfilled.

Deposition tolerances and other variations

A variation in deposited thicknesses in the components of the Fabry-Perot filters, in casu the layers of the Bragg stack and the thickness of the cavity, will result in a mismatch between the designed filter and the 25 produced filter. The effect of the variations on the thickness of the cavity is that: the thickness of all filters will be changed by more or less an equal amount, causing a shift of the spectral range to the right of the left of the theoretical design. This global shift in the selected wavelengths, either up or down, with respect to the designed filter location, can be tolerated if it is a small proportion of the spectral width of the passbands, which can be one of the design parameters.

30 In addition to the wafer-wide deposition tolerance, there can be etch tolerances and other intra-die variations as well as inter-die variations. Traditionally this is mitigated by binning, selecting certain devices for certain wavelength ranges.

In case the etch processes that are being used to define are non-directional processes, the sharp edges that form the transition between one filter and the next one, can show rounding. In some embodiments, the 35 width of each filter can cover multiple columns of sensor elements, in other cases just one or two sensor elements, in which case such corner rounding may have more effect on the passband..

Alignment tolerances

When using standard IC processing techniques, alignment of filter structures on top of rows/columns of pixels with dimension of several microns per pixels is well within the possibilities of the state of the art.

40 Therefore, alignment at the top level is not very critical.

Processing Hardware:

Some of the method steps discussed above for image processing for example, may be implemented by logic in the form of hardware or, for example, in software using a processing engine such as a microprocessor or a programmable logic device (PLD's) such as a PLA (programmable logic array), PAL (programmable array logic), FPGA (field programmable gate array).

An example of a circuit with an embedded processor may be constructed as a VLSI chip around an embedded microprocessor which may be synthesized onto a single chip with the other components. Alternatively other suitable processors may be used and these need not be embedded, e.g. a Pentium processor as supplied by Intel Corp. USA. A zero wait state SRAM memory may be provided on-chip as well as a cache memory for example. Typically I/O (input/output) interfaces are provided for accessing external storage e.g. via data networks. FIFO buffers may be used to decouple the processor from data transfer through these interfaces. The interface can provide network connections, i.e. suitable ports and network addresses, e.g. the interfaces may be in the form of network cards.

Software:

Software programs may be stored in an internal ROM (read only memory) and/or on any other non-volatile memory, e.g. they may be stored in an external memory. Access to an external memory may be provided by conventional hardware which can include an external bus interface if needed, with address, data and control busses. Features of the method and apparatus of the present invention may be implemented as software to run on a processor. In particular image processing in accordance with the present invention may

be implemented by suitable programming of the processor. The methods and procedures described above may be written as computer programs in a suitable computer language such as C and then compiled for the specific processor in the embedded design. For example, the software may be written in C and then compiled using a known compiler and known assembler. The software has code, which when executed on a processing engine provides the methods and image processor for the present invention. The software programs may be stored on any suitable machine readable medium such as magnetic disks, diskettes, solid state memory, tape memory, optical disks such as CD-ROM or DVD-ROM, etc. Other variations can be envisaged within the claims.

Claims:

1. A spectral camera for producing a spectral output and having an objective lens (10) for producing an image, an array of lenses (25) for producing optical copies of segments of the image on different optical channels, an array of filters (30) for the different optical channels and having an interleaved spatial pattern

5 of different passbands across the array, and one or more sensor arrays (40) arranged to detect the copies of the image segments on the different filtered optical channels, the interleaved spatial pattern of the array of filters being arranged so that detected segment copies of spatially adjacent optical channels have different passbands and represent segments of the image which at least partially overlap each other, and so that at least some of the detected segment copies of the same passband on spatially non-adjacent optical channels

10 represent segments of the image which are adjacent and fit together.

2. The spectral camera of claim 1, the sensor array being arranged to detect the copies of the segments of the image simultaneously.

15 3. The spectral camera of claim 1 or 2, the interleaved spatial pattern and the overlapping of the segments being arranged to provide a spatially uniform spectral detection for all of the image.

4. The spectral camera of any preceding claim, the interleaved spatial pattern comprising a two dimensional repeating pattern of the passbands.

20 5. The spectral camera of claim 1, 2, or 4, the interleaved spatial pattern and the overlapping of the segments being arranged to provide a non uniform spectral detection, having variation in any one or more of: which passbands are detected at different parts of the image, spectral range at different parts of the image, spectral resolution, spatial resolution at different parts of the image, and spatial resolution at

25 different passbands.

30 6. The spectral camera of any preceding claim, at least part of the interleaved spatial pattern comprising segments of width of at least N1 filters and height of at least N2 filters and the overlap of spatially adjacent channels in this part of the interleaved spatial pattern is arranged to be by a factor of 1-1/N1 in a width direction and by a factor of 1-1/N2 in a height direction.

7. The spectral camera any preceding claim, the array of filters being integrated on the sensor array.

35 8. The spectral camera any preceding claim, the array of filters comprising thin films acting as fabry perot cavities having a thickness of half the wavelength of the desired transmission wavelength.

40 9. The spectral camera of any preceding claim, at least some parts of the interleaved spatial pattern having a superimposed finer pattern of the passbands at a finer granularity than that of the interleaved spatial pattern.

10. The spectral camera of any preceding claim, having a post processing part for electrically processing the detected segment copies for a given passband to stitch them together.

5 11. The spectral camera of any preceding claim, arranged such that the array of filters is reconfigurable in use by swapping the array of filters to use a different array of filters.

12. The spectral camera of any preceding claim, the objective lens having a hexagonal stop and the arrays of lenses and filters being arranged to give the segment copies a hexagonal outline.

10

13. The spectral camera of any preceding claim, the passbands being selected to enable part of the sensor array to detect an unwanted higher or lower order spectral response of another part of the sensor array.

15

14. A method of using a spectral camera for producing a spectral output and having an objective lens (10) for producing an image, an array of lenses (25) for producing optical copies of segments of the image on different optical channels, an array of filters (30) for the different optical channels for passing a selected band of the optical spectrum, the array of optical filters having an interleaved spatial pattern of different passbands across the array, and one or more sensor arrays (40) arranged to detect the copies of the image segments on the different filtered optical channels, the interleaved spatial pattern of the array of filters being arranged so that detected segment copies of spatially adjacent optical channels have different passbands and represent segments of the image which at least partially overlap each other, and so that at least some of the detected segment copies of the same passband on spatially non-adjacent optical channels represent segments of the image which are adjacent and fit together, the method having the step of processing the detected segment copies for a given passband to stitch them together, and to align the stitched copies for the different passbands.

20

15. The method of claim 13 having the step of swapping during use the array of filters to use an array 30 of filters having a different interleaved pattern.

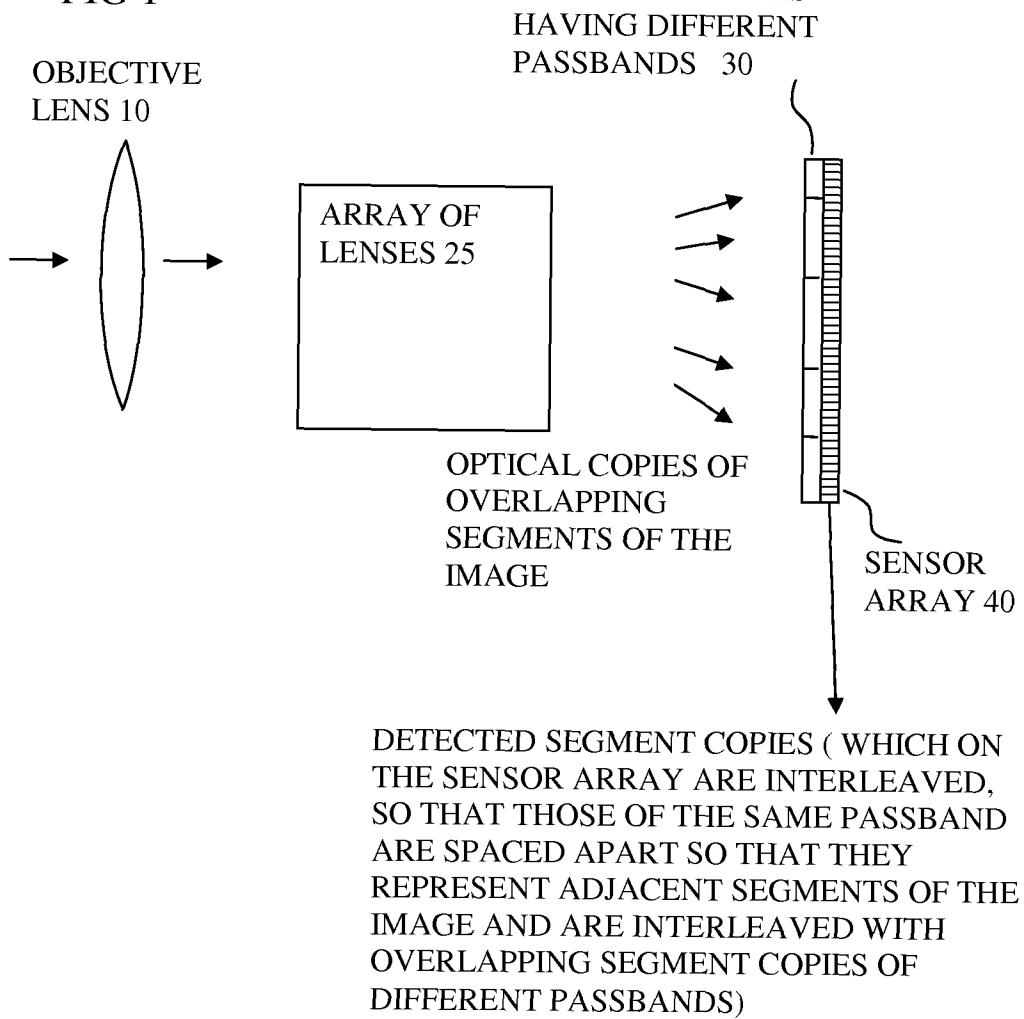
25

16. A method of configuring a spectral camera during manufacture, the spectral camera being for producing a spectral output and having an objective lens (10) for producing an image, an array of lenses (25) for producing optical copies of segments of the image on different optical channels, an array of filters (30) for the different optical channels for passing a selected band of the optical spectrum, the array of optical filters having an interleaved spatial pattern of different passbands across the array, and one or more sensor arrays (40) arranged to detect the copies of the image segments on the different filtered optical channels, the method having the steps of selecting the passbands and the interleaved spatial pattern of the array of filters so that detected segment copies of spatially adjacent optical channels have different passbands and represent segments of the image which at least partially overlap each other, and so that at 40

least some of the detected segment copies of the same passband on spatially non-adjacent optical channels represent segments of the image which are adjacent and fit together, and manufacturing (520) the array of filters according to the selected passbands and their spatial arrangement.

5 17. The method of claim 15, the selecting (515) of the passbands and their spatial arrangement being such that there is a variation in any one or more of: which passbands are detected at different parts of the image, a spectral resolution, a spatial resolution of the detection at different parts of the image, and spatial resolution of the detection at different passbands.

FIG 1



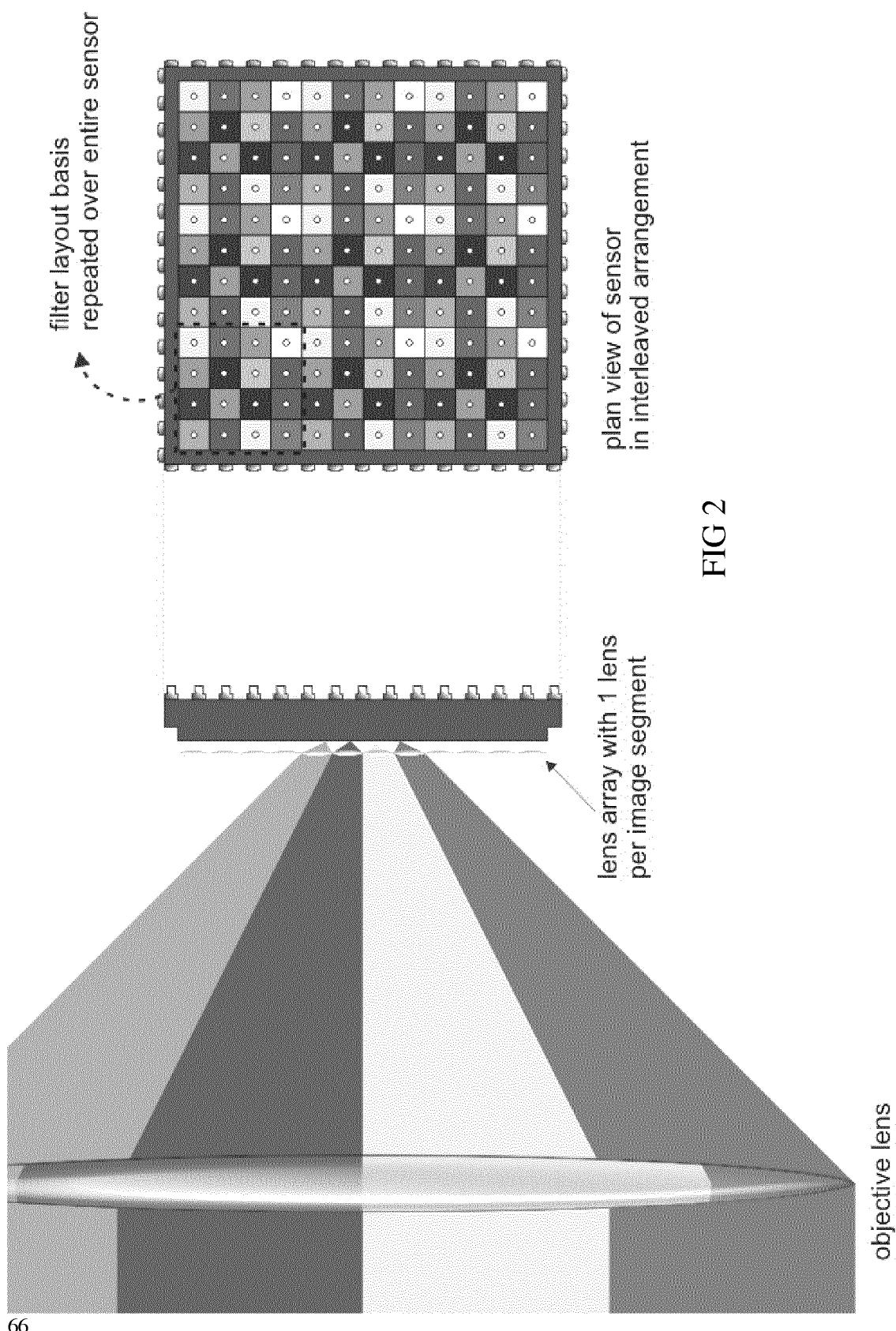


FIG 2

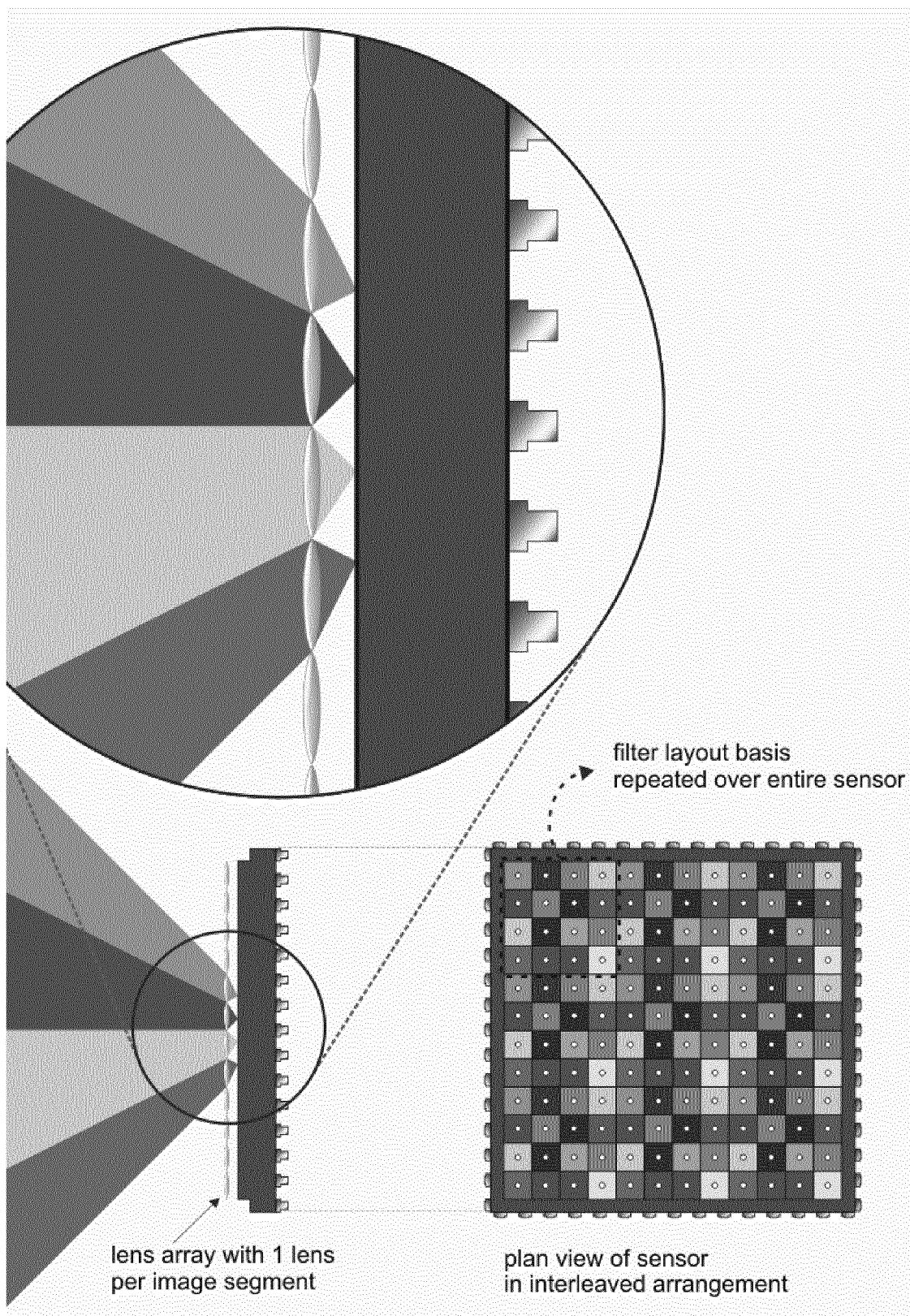


FIG 3

Layout basis
repeated over sensor

2	3
5	• → 6
8	• → 9

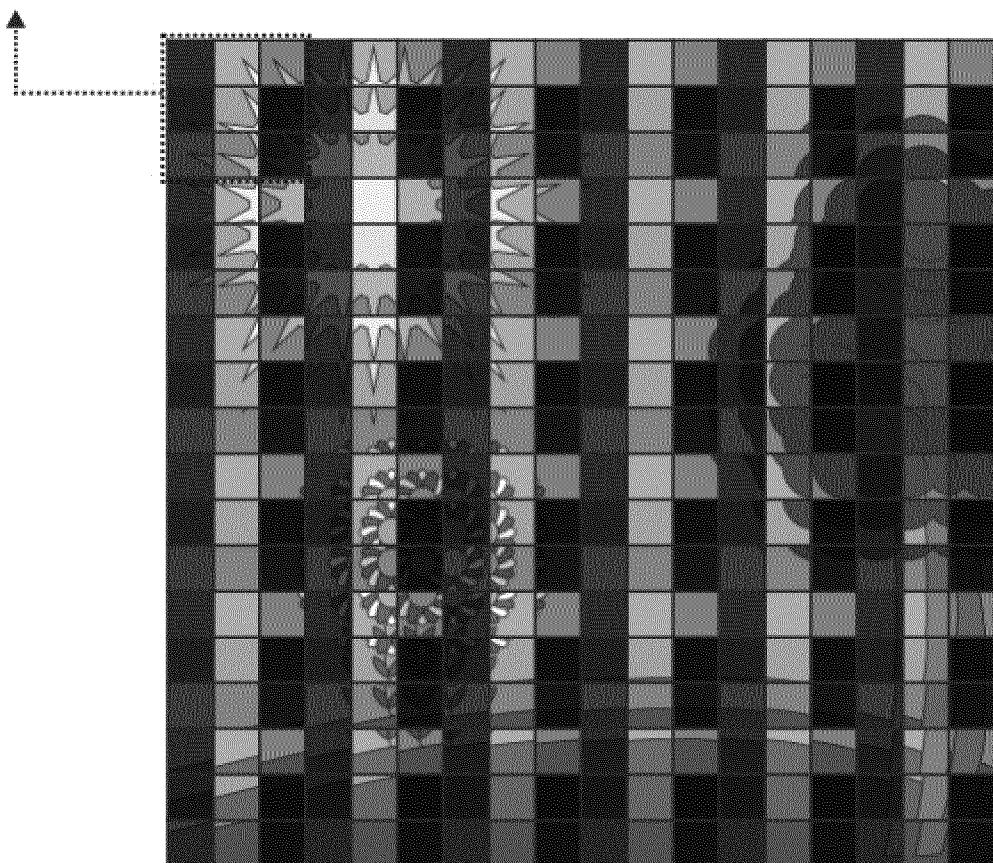


FIG 4

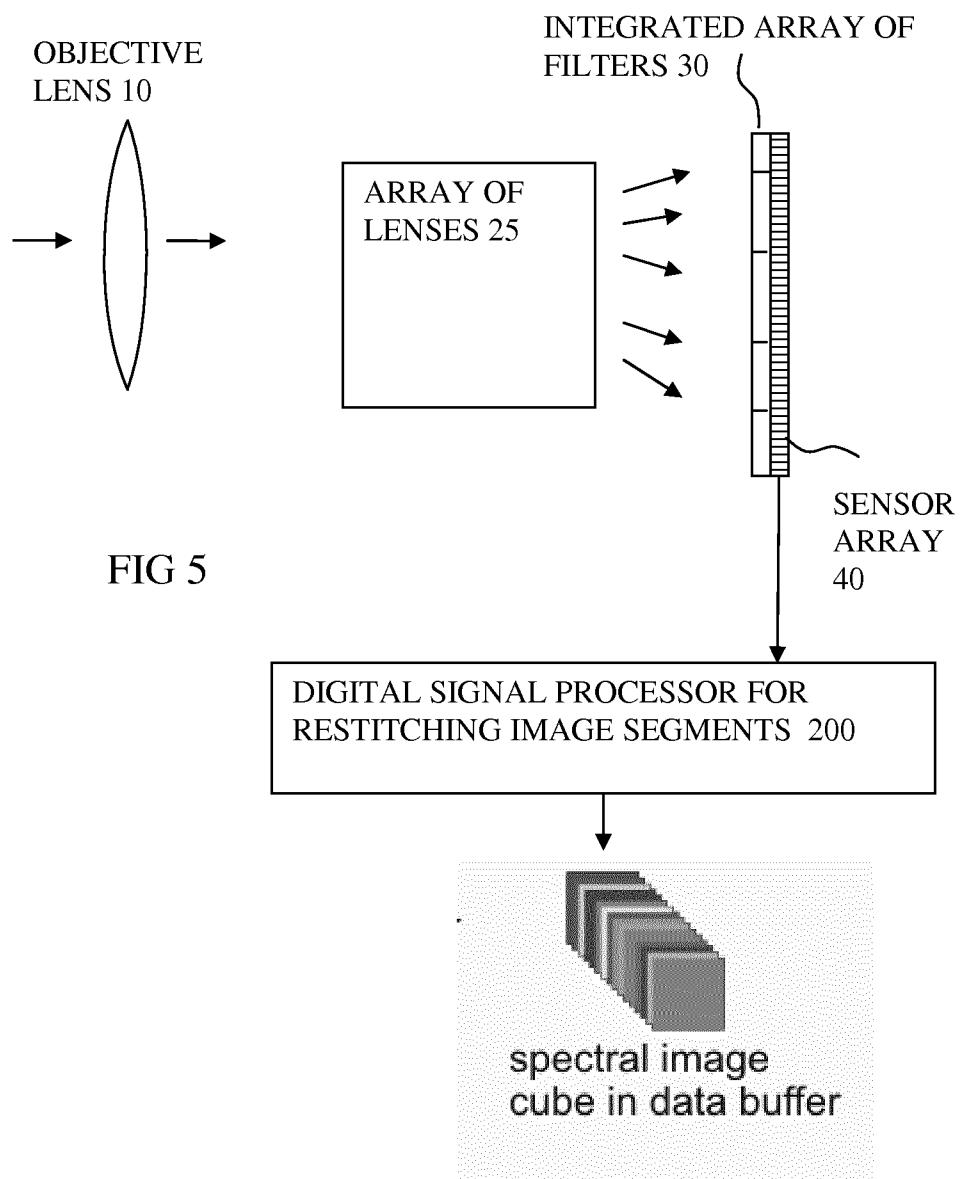


FIG 6

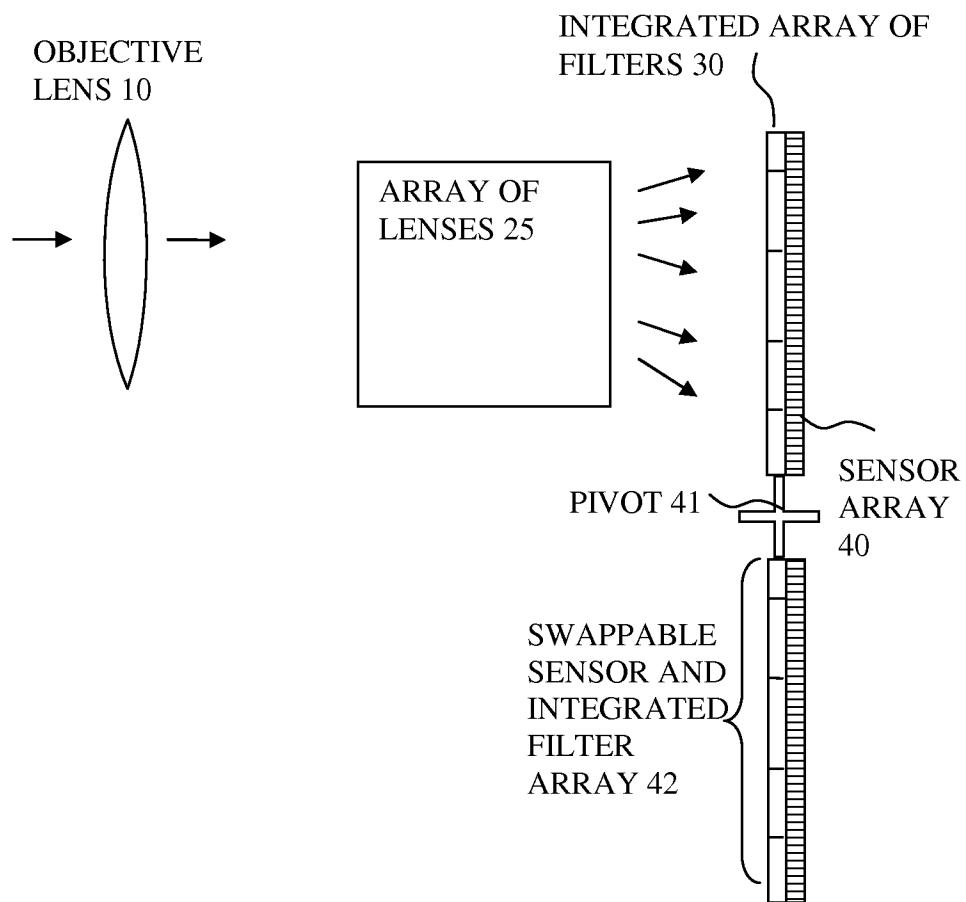
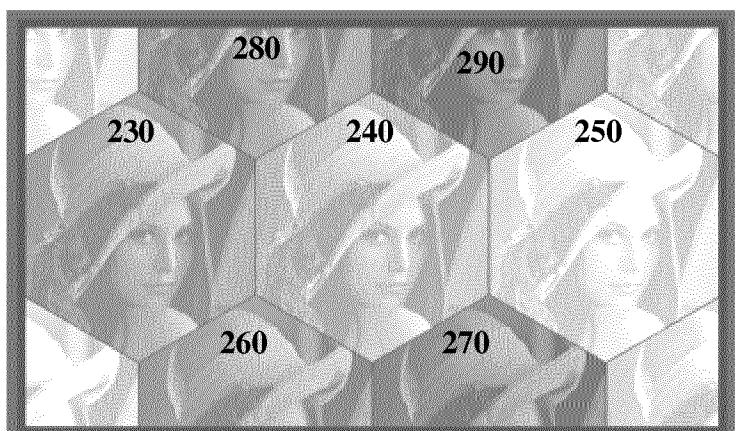


FIG 7



(shown without illustrating overlapping segments)

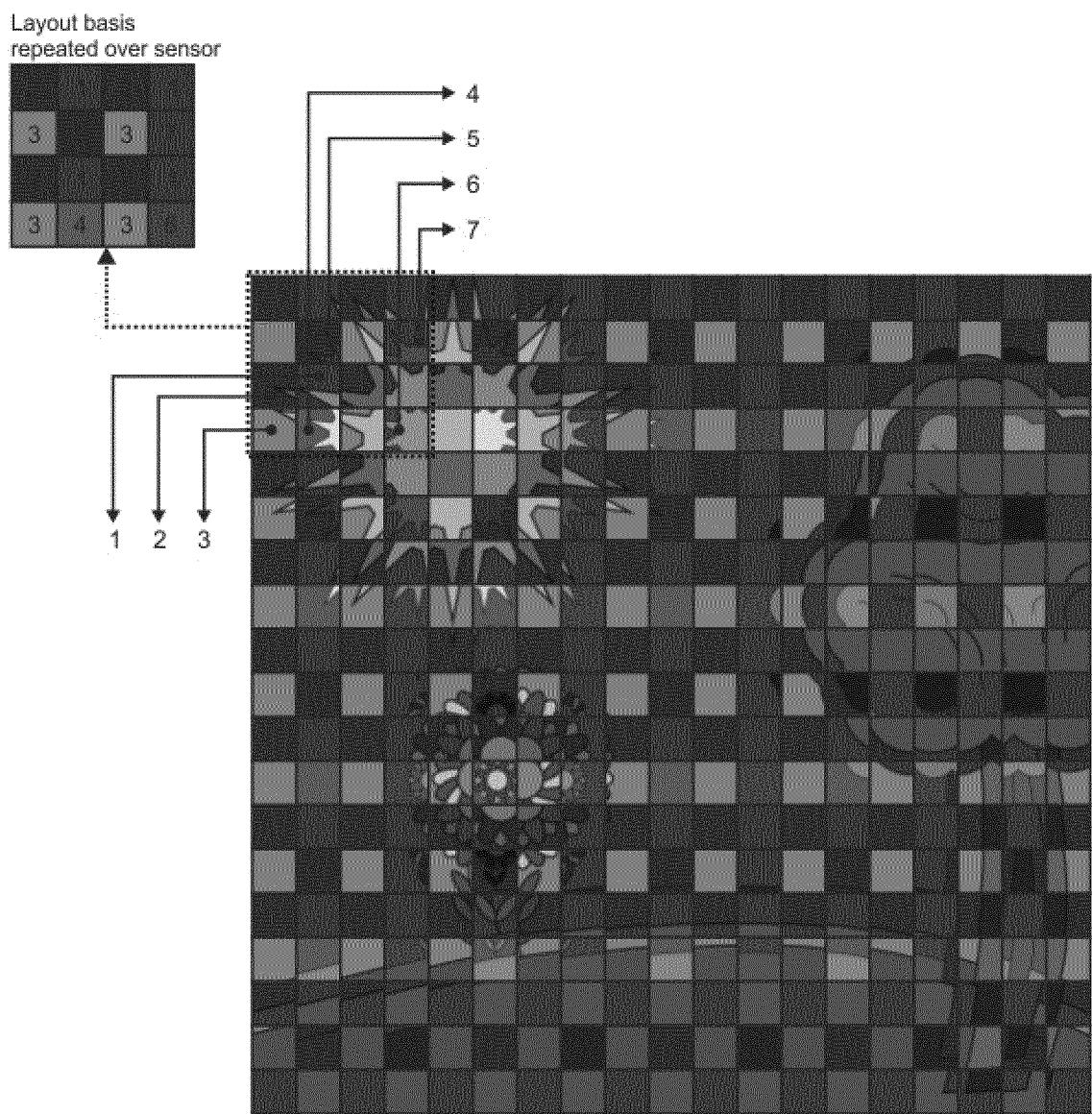


FIG 8

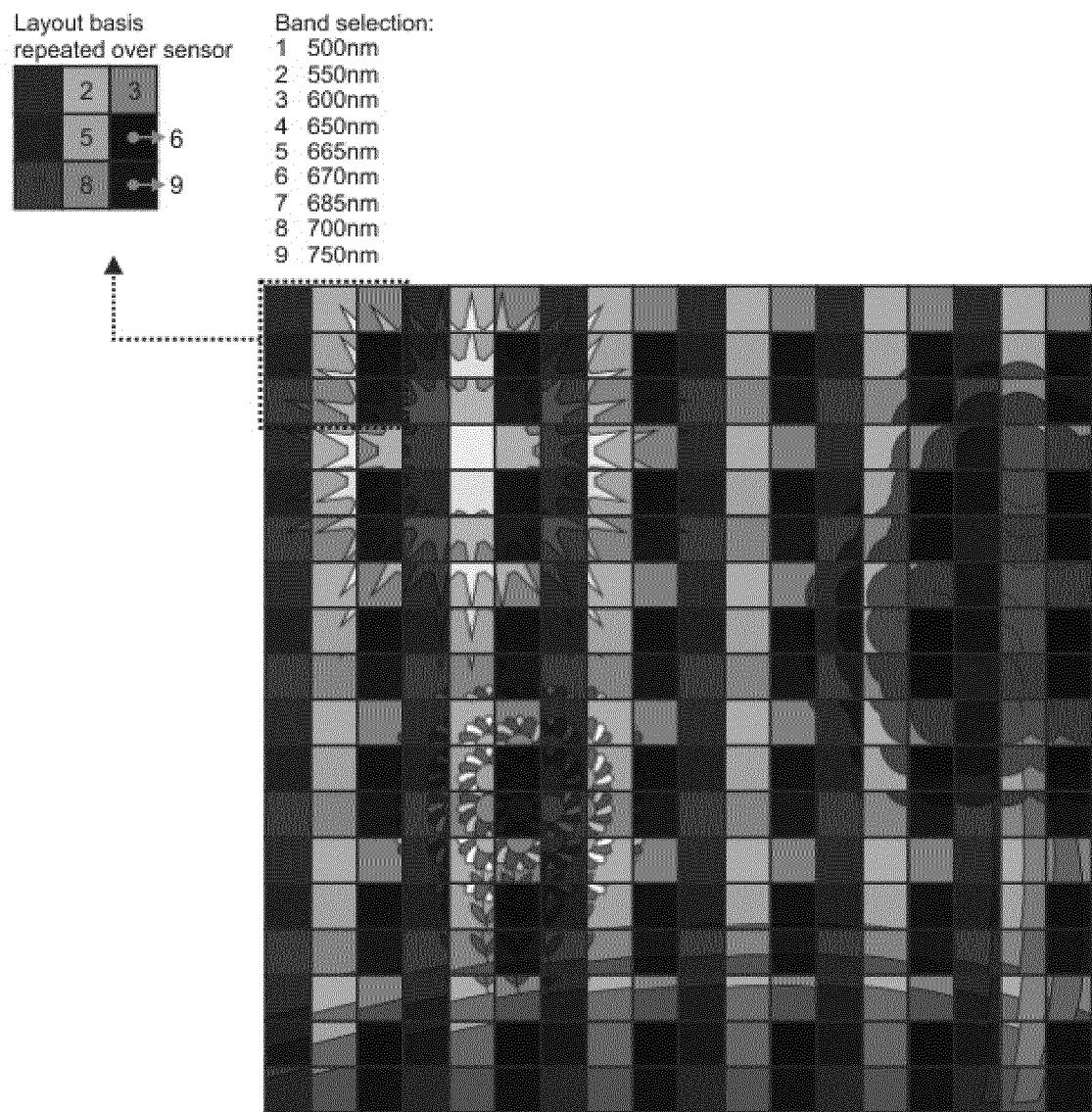


FIG 9

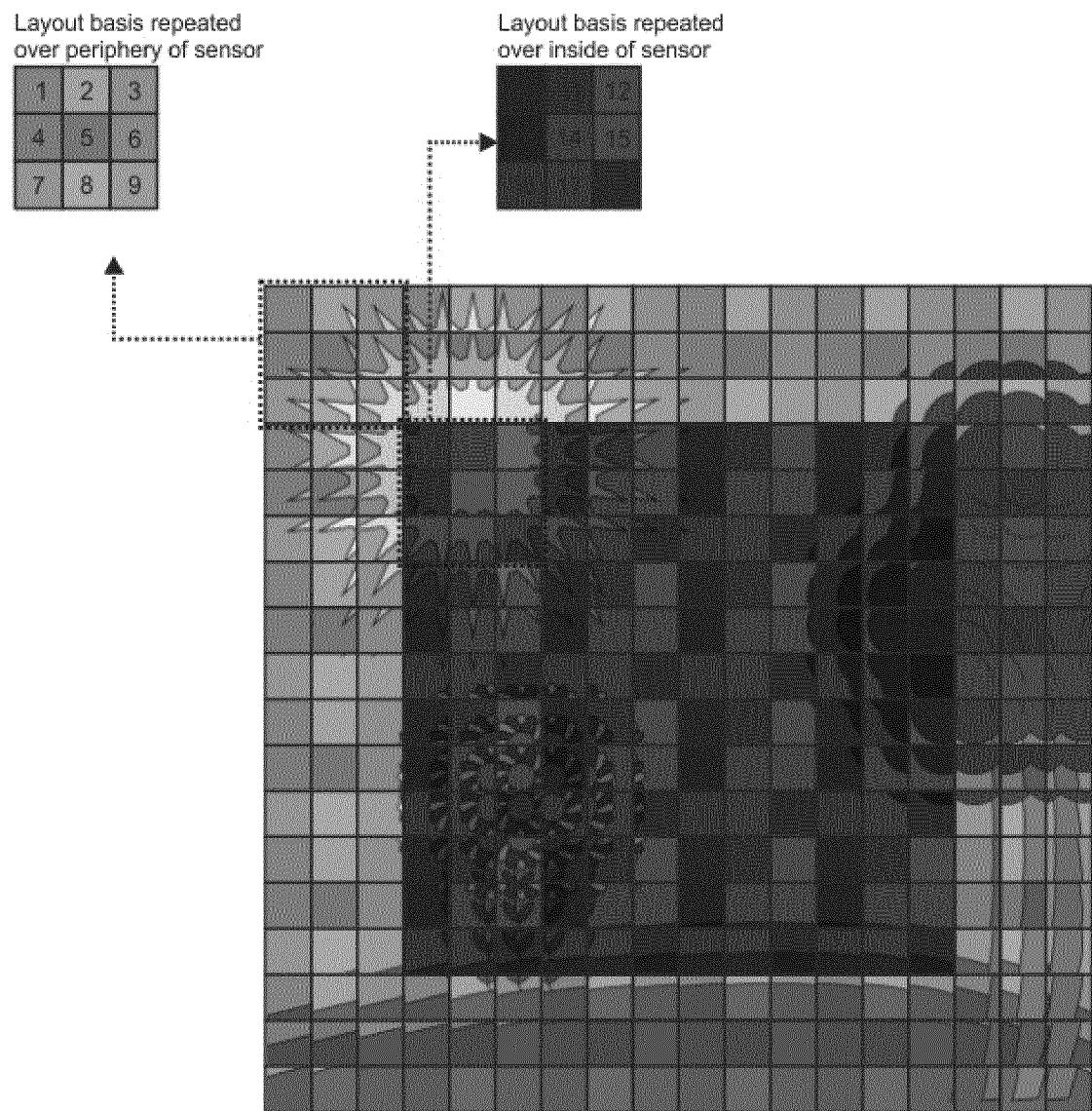


FIG 10

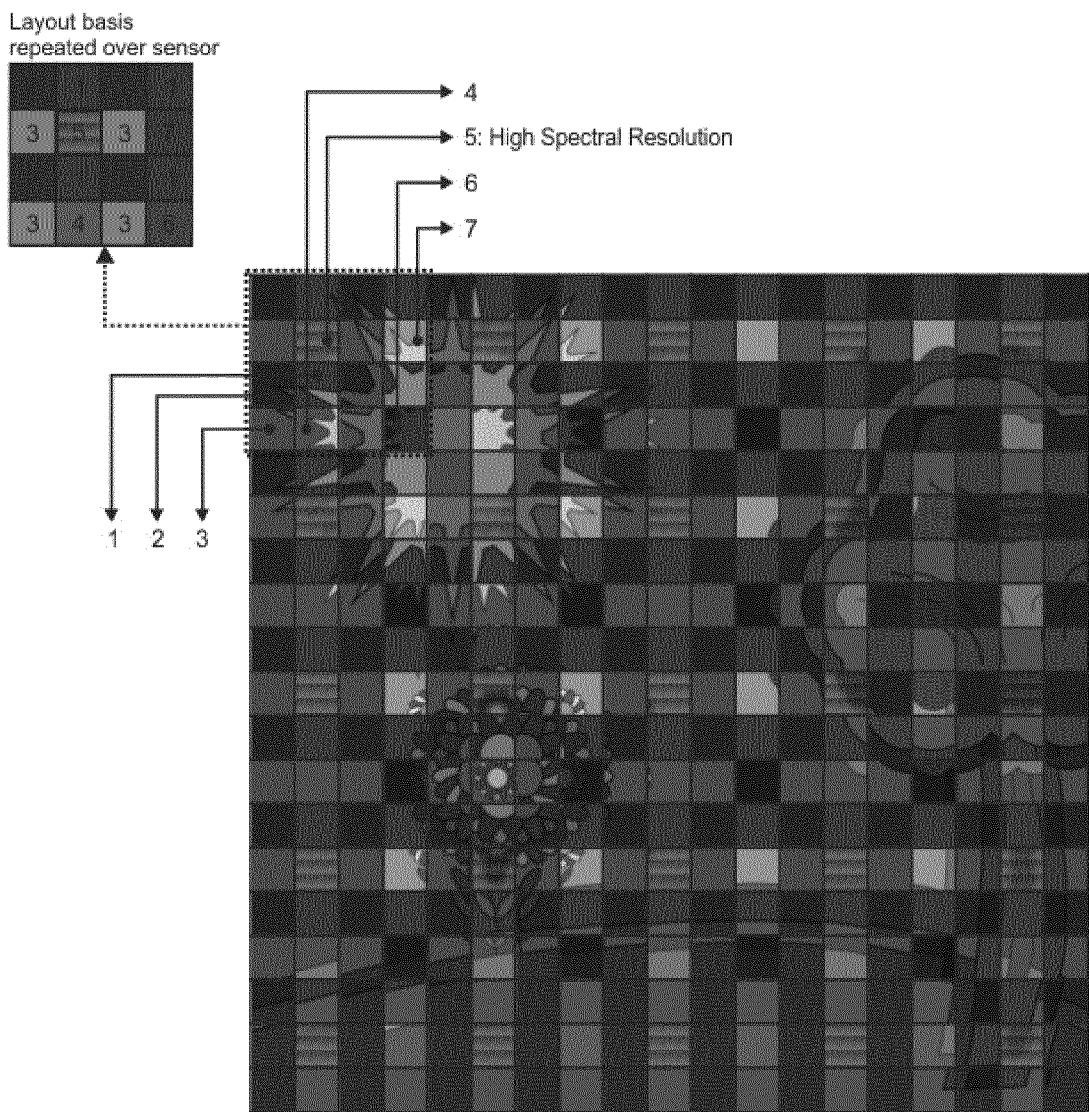


FIG 11

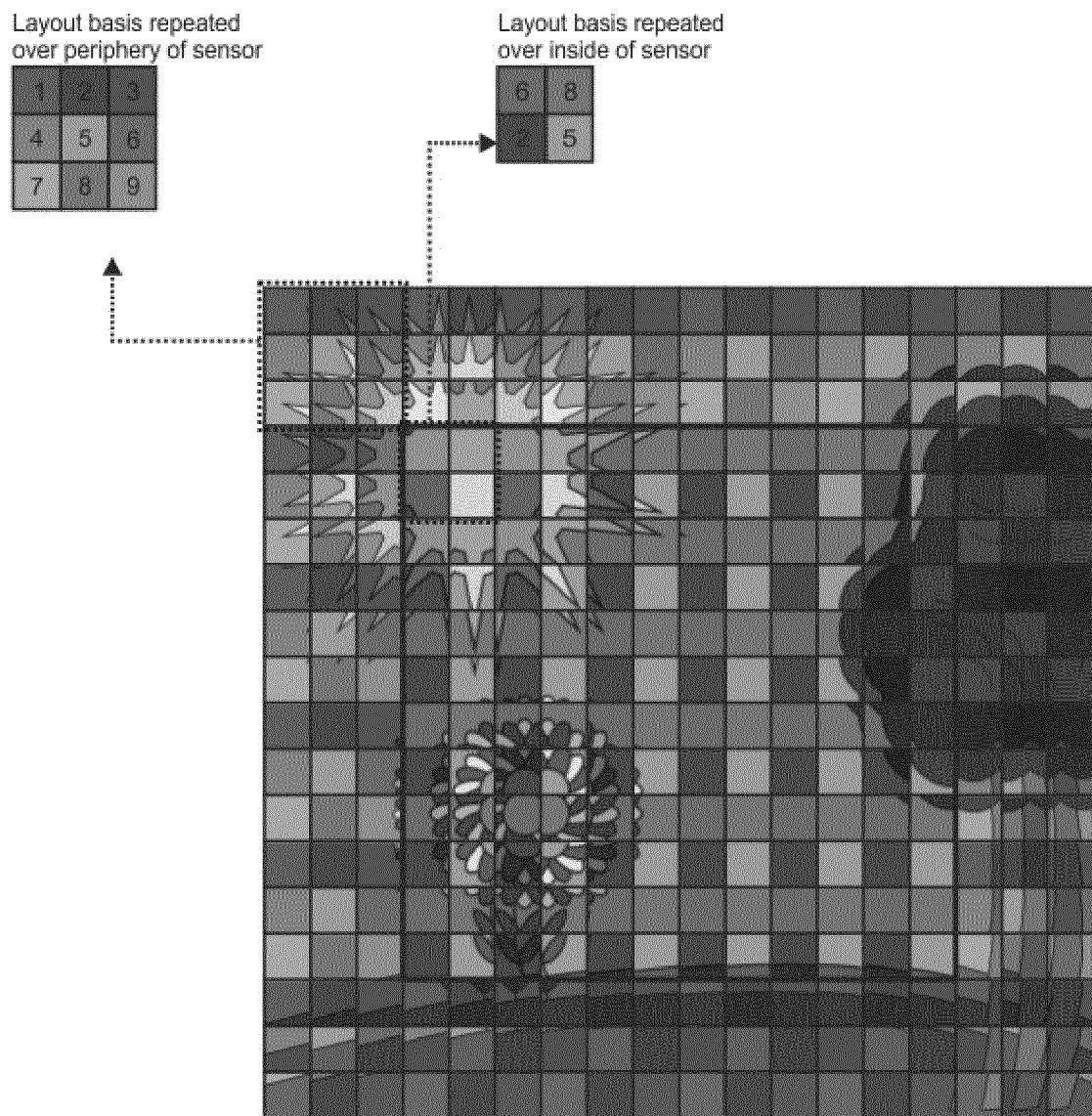


FIG 12

FIG 13

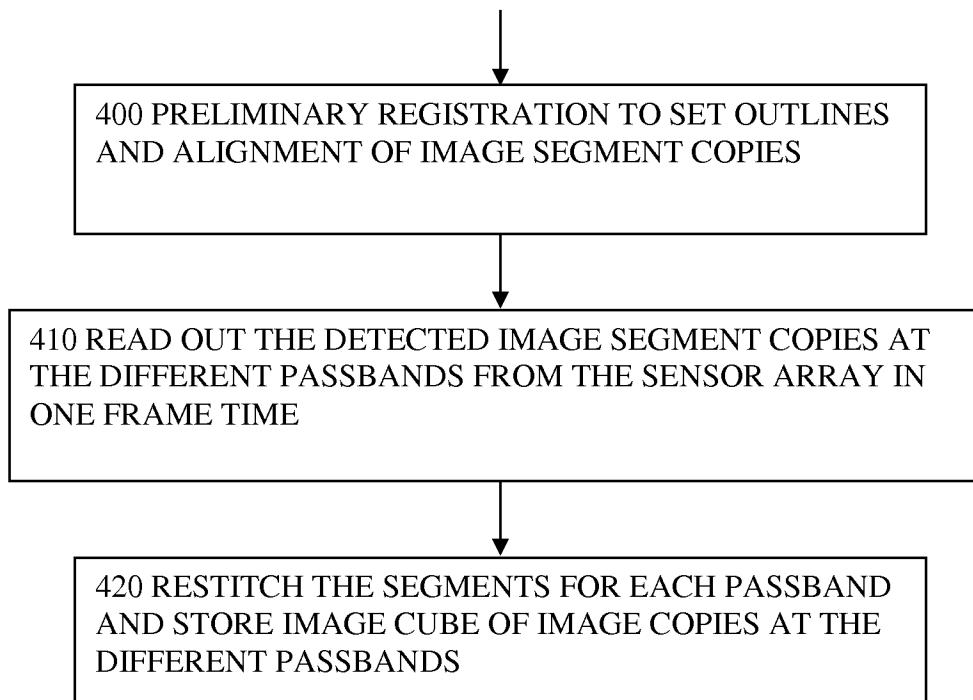


FIG 14

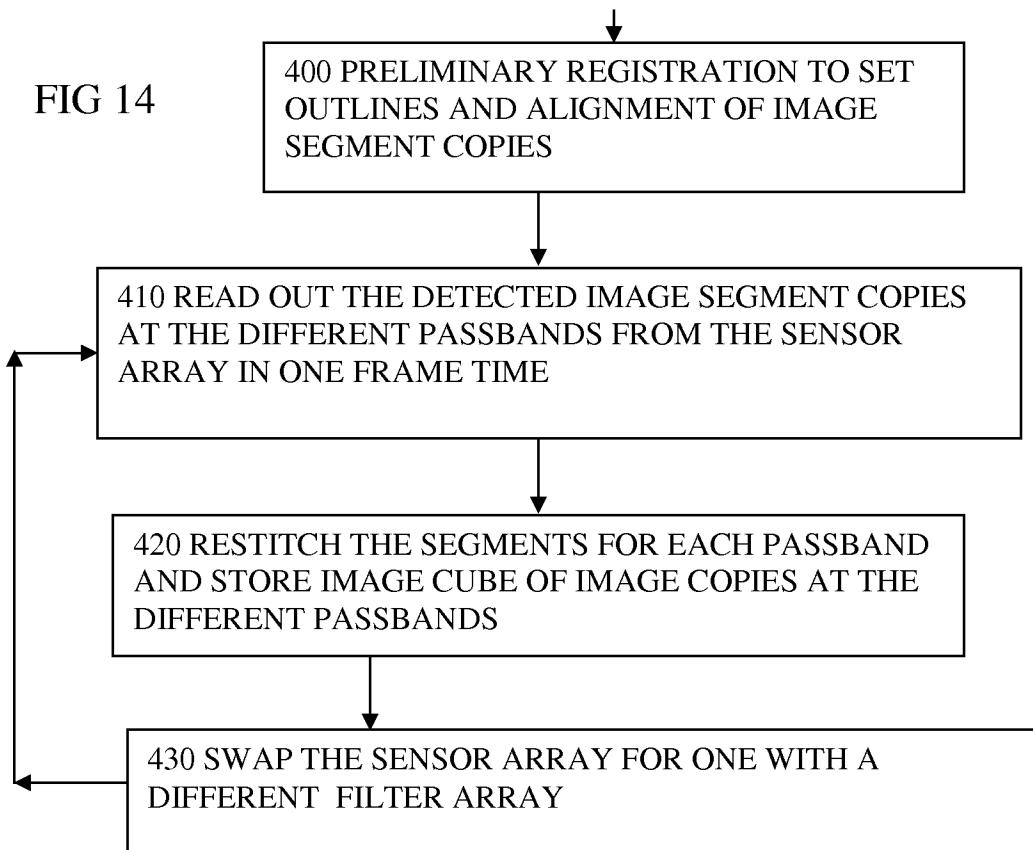


FIG 15

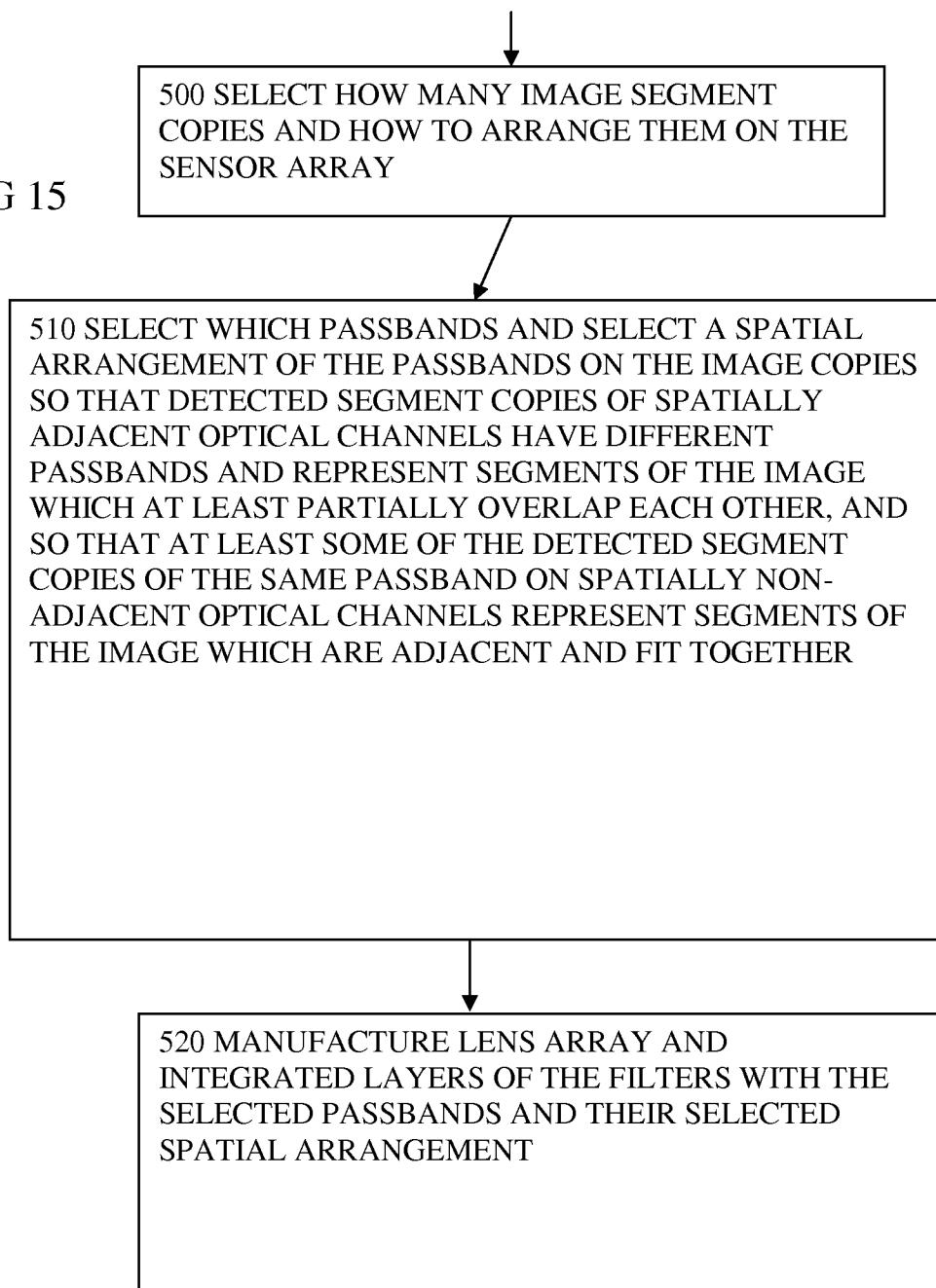


FIG 16

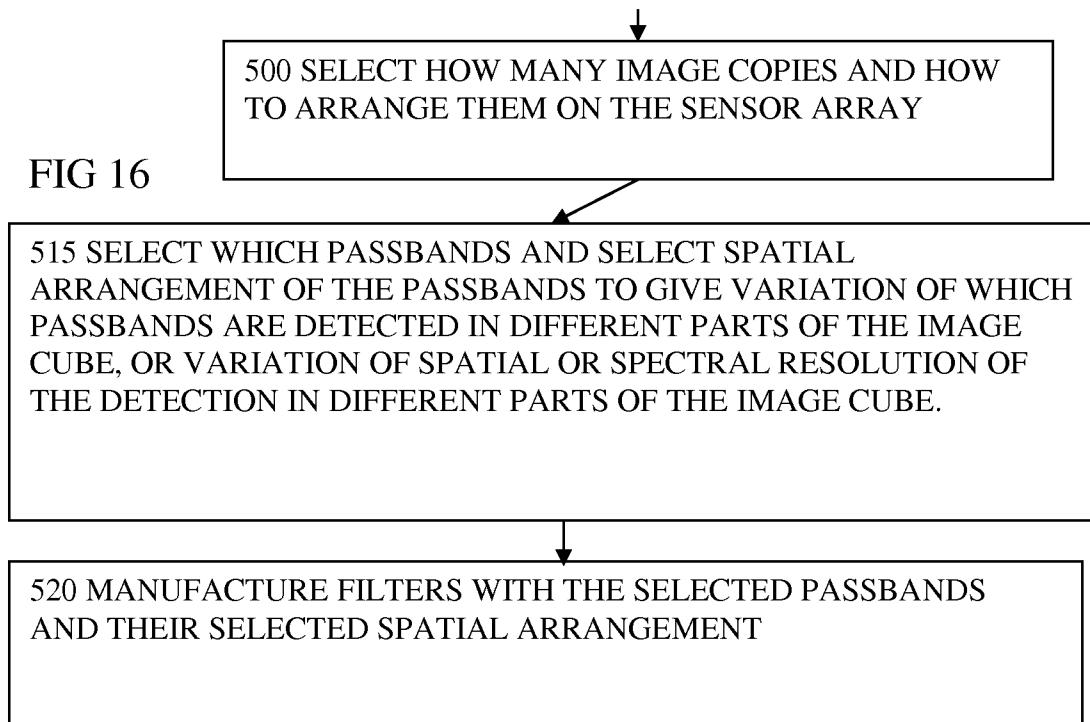
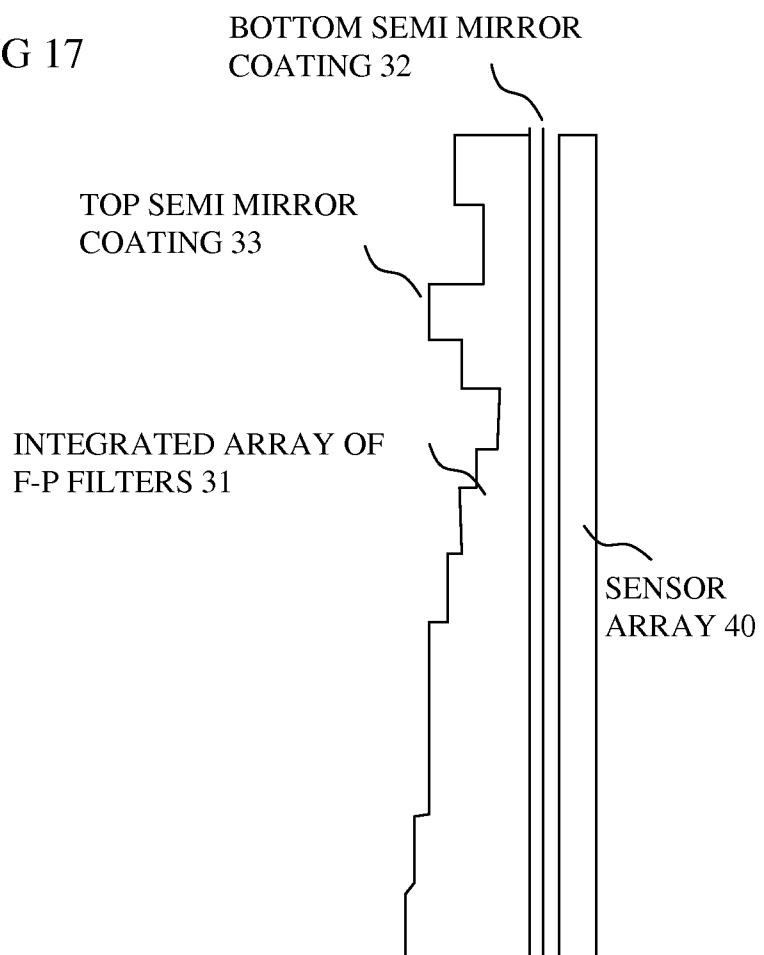


FIG 17



INTERNATIONAL SEARCH REPORT

International application No
PCT/EP2012/071506

A. CLASSIFICATION OF SUBJECT MATTER

INV. G01J3/28 G01J3/51 G01J3/02 H01L27/146
ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

G01J H04N H01L

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
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Y	column 2, line 43 - column 3, line 10; figures 3,6,7 column 6, line 1 - line 5 -----	5,6,8,9, 11,12, 15,17
X	WO 2010/019711 A1 (DIGITAL FUSION INC [US]; PHILIPS DAME J [US]; JONES MICHAEL W [US]) 18 February 2010 (2010-02-18)	1-4,7, 10,13, 14,16
Y	paragraph [0055] - paragraph [0058]; figures 3-5, 7-9 ----- -/-	5,6,8,9, 11,12, 15,17



Further documents are listed in the continuation of Box C.



See patent family annex.

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"&" document member of the same patent family

Date of the actual completion of the international search

Date of mailing of the international search report

27 February 2013

15/03/2013

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Authorized officer

Schmidt, Charlotte

INTERNATIONAL SEARCH REPORT

International application No
PCT/EP2012/071506

C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

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