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(54) **LOW VOLTAGE CRYSTAL OSCILLATOR (XTAL) DRIVER WITH FEEDBACK CONTROLLED DUTY CYCLING FOR ULTRA LOW POWER**

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CPC **H03B 5/364** (2013.01); **H03B 2200/0046** (2013.01); **H03B 2200/0082** (2013.01)

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USPC 331/116 R, 116 FE, 158, 160
See application file for complete search history.

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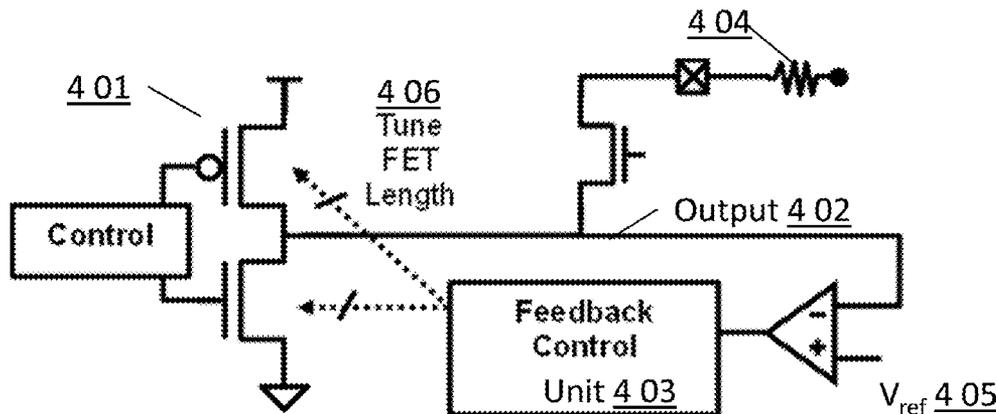
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(57) **ABSTRACT**

A low voltage crystal oscillator (XTAL) driver with feedback controlled duty cycling for ultra low power biases an amplifier for an XTAL in the sub-threshold operating regime. A feedback control scheme can be used to bias the amplifier for an XTAL biased in the sub-threshold operating regime. The amplifier of a XTAL oscillator can be duty cycled to save power, e.g., the XTAL driver can be turned off to save power when the amplitude of the XTAL oscillation reaches a maximum value in range; but be turned back on when the amplitude of the XTAL oscillation starts to decay, to maintain the oscillation before it stops. In addition or alternatively, a feedback control scheme to duty cycle the amplifier of a XTAL oscillator can be used to monitor the amplitude of the oscillation.

19 Claims, 13 Drawing Sheets



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FIG. 1

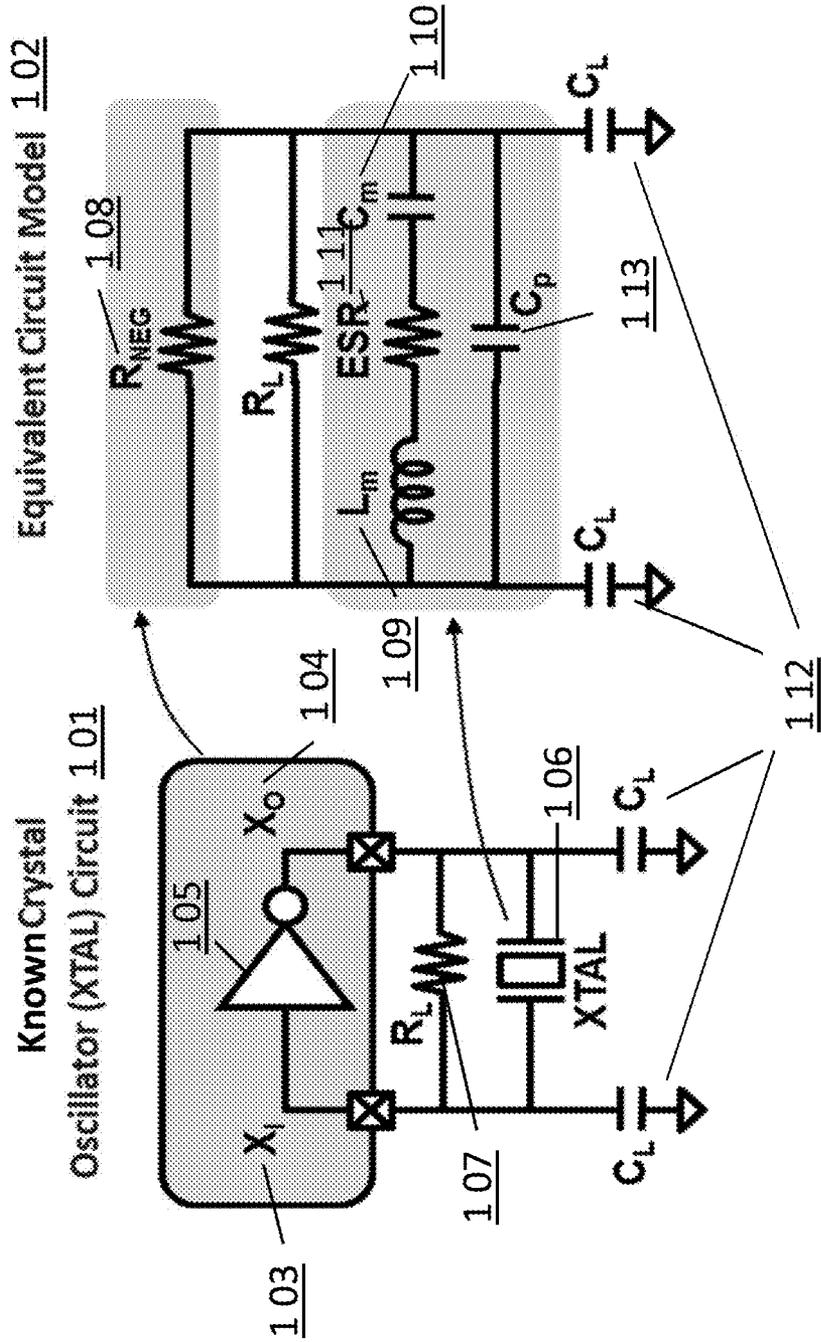


FIG. 2

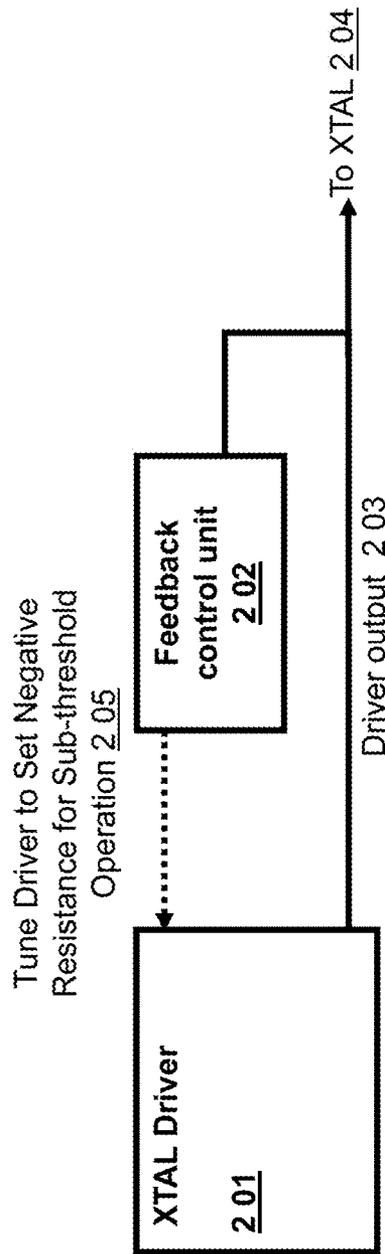


FIG. 3

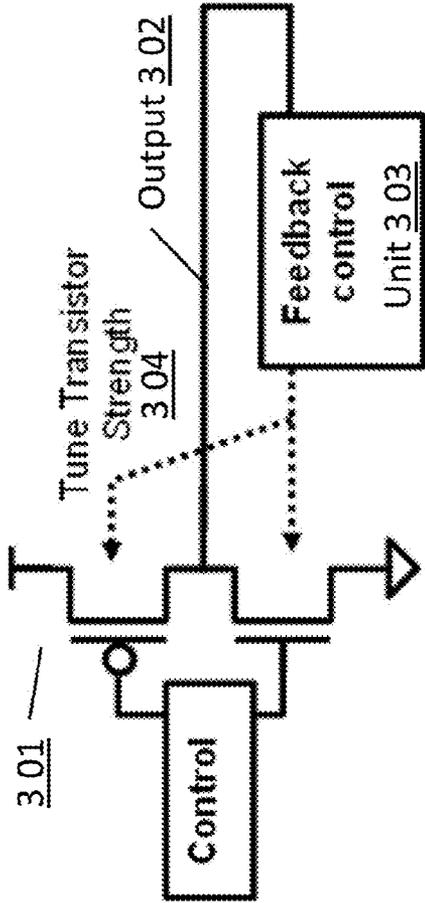


FIG. 4

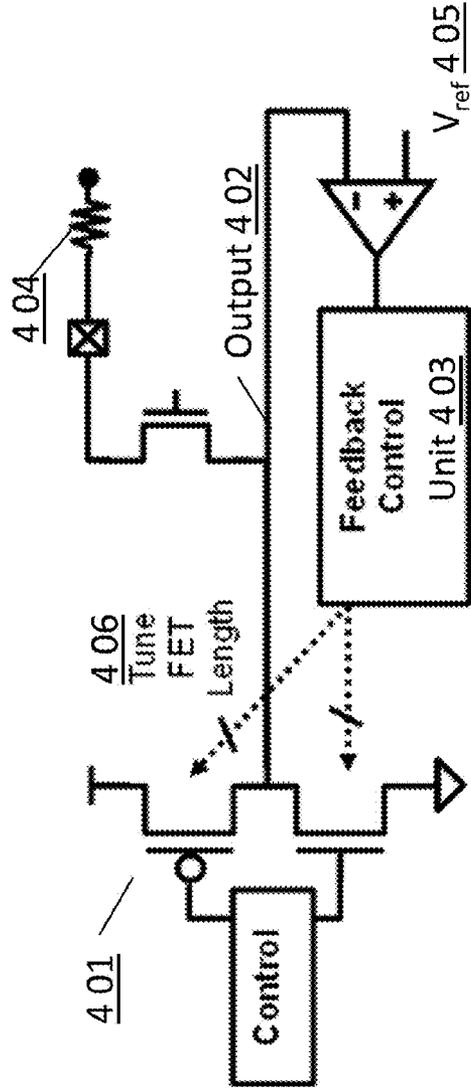


FIG. 5

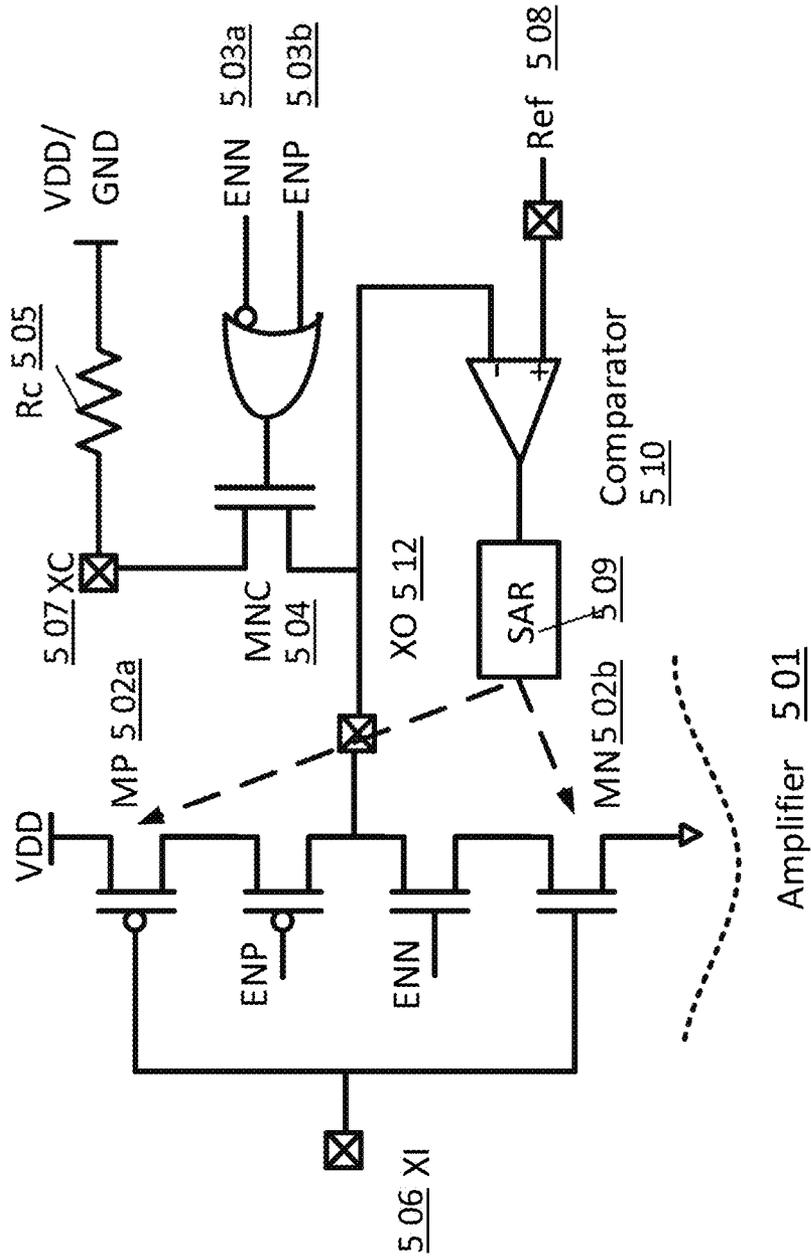


FIG. 6

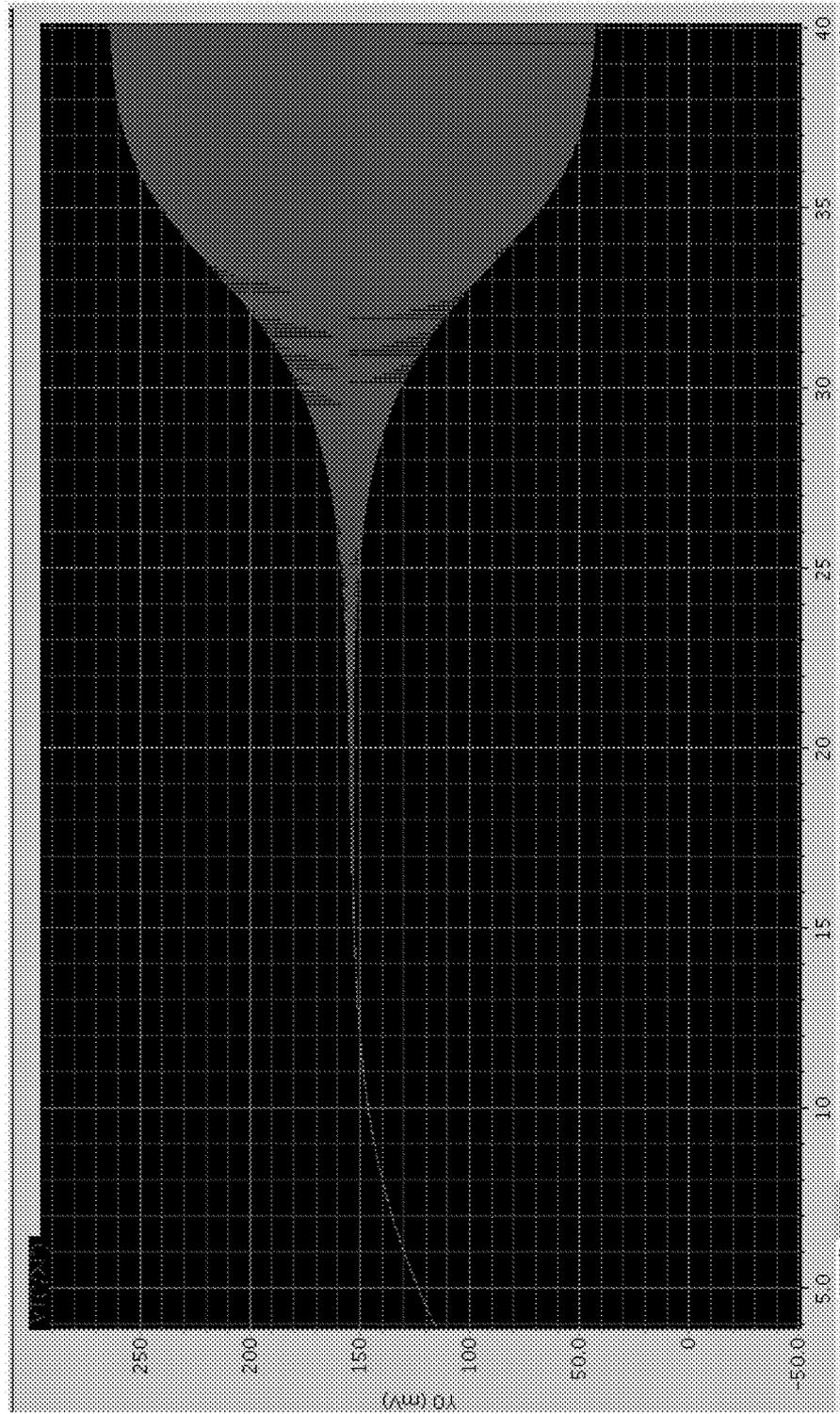


FIG. 7

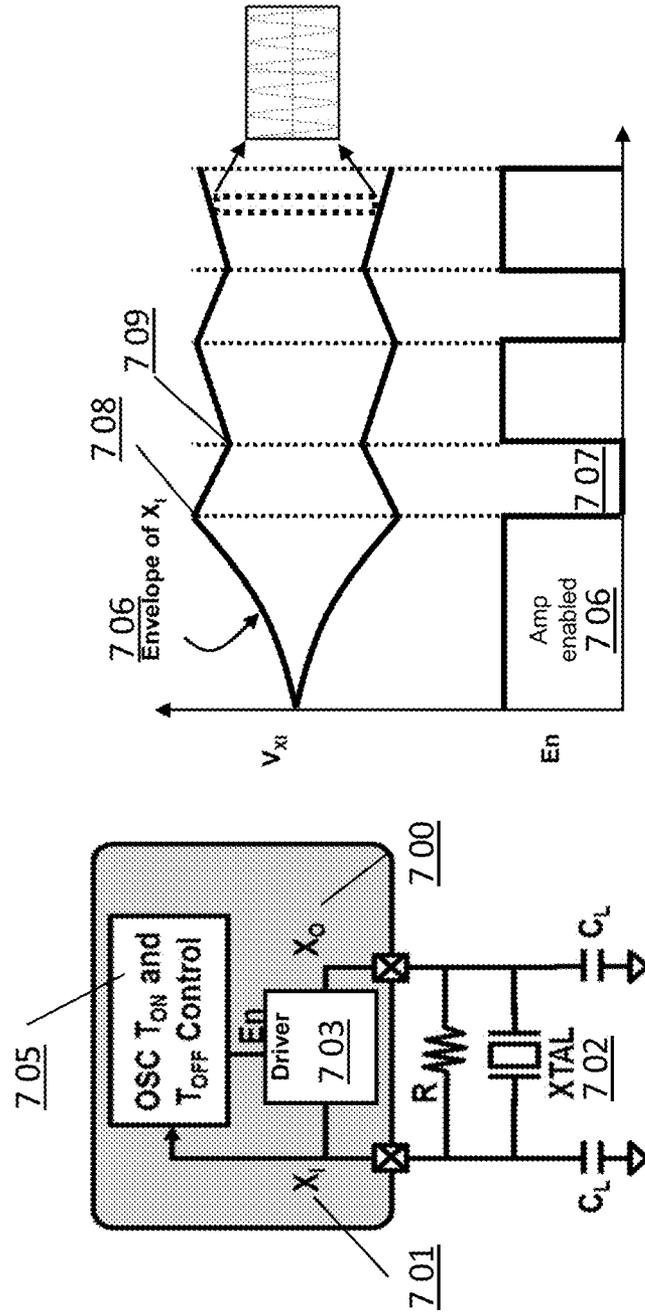


FIG. 8

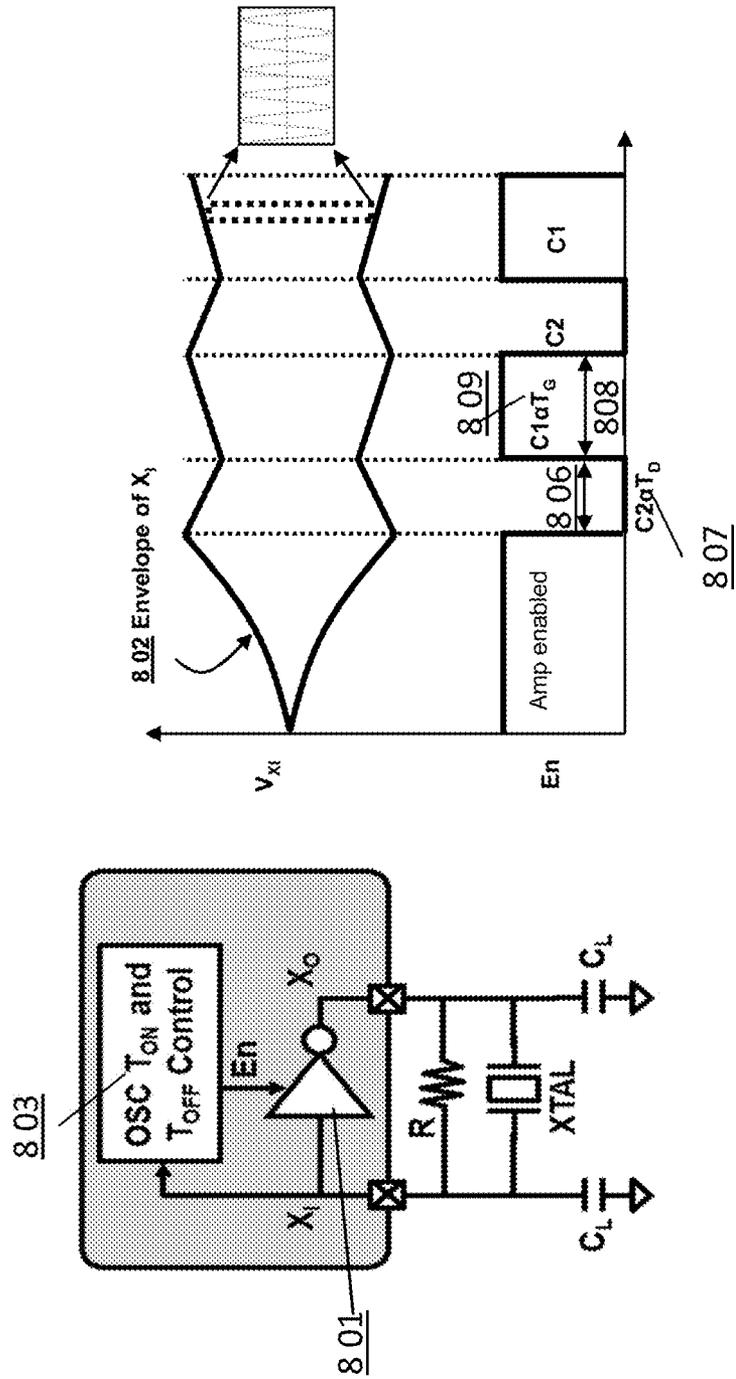


FIG. 9

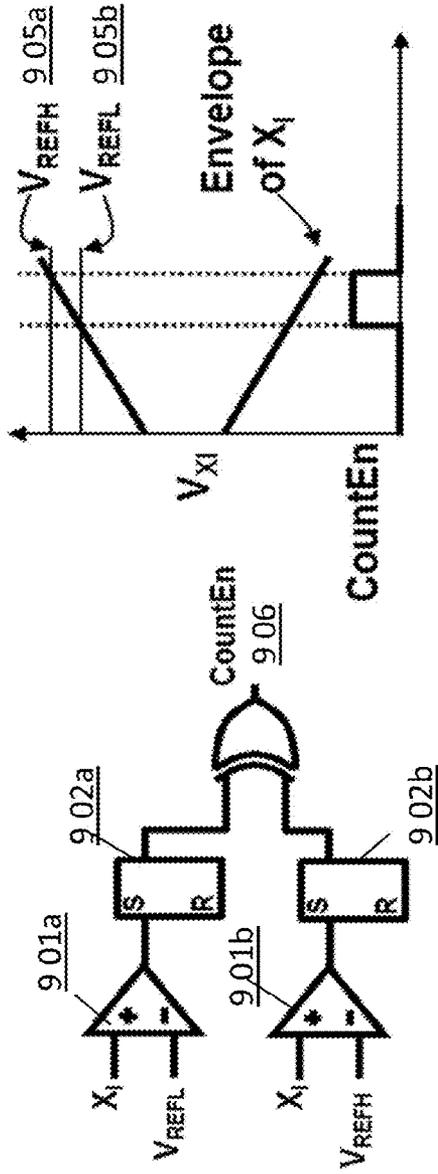


FIG. 10

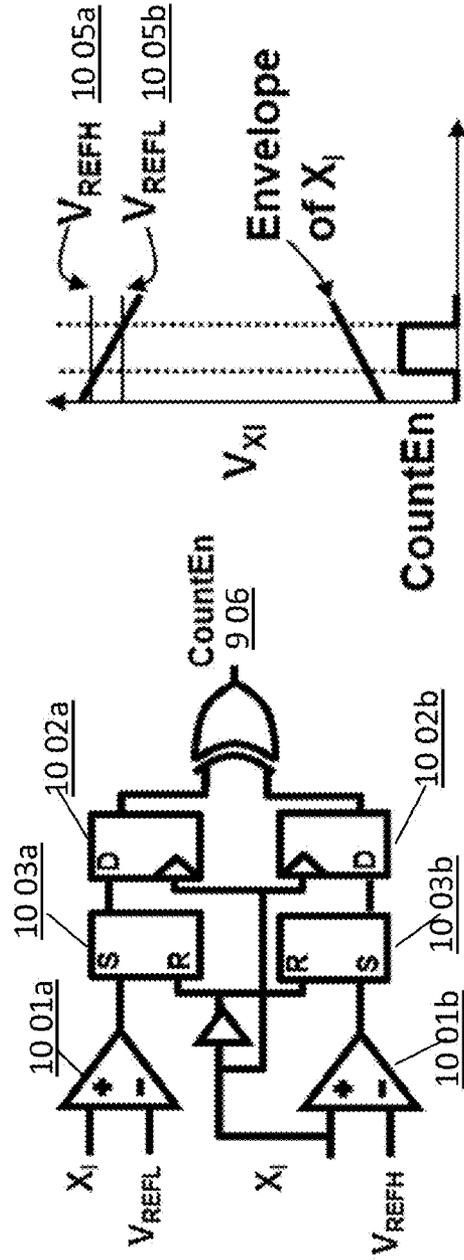


FIG. 12

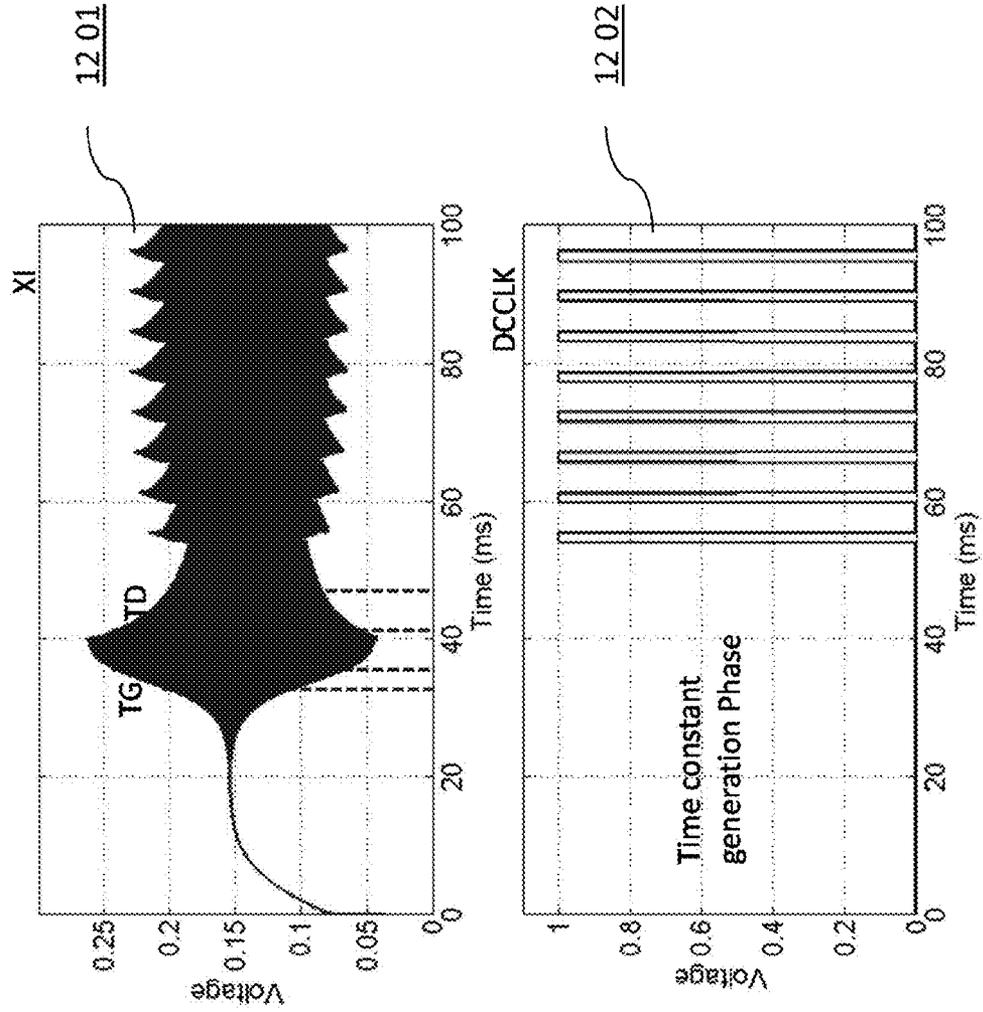


FIG. 13

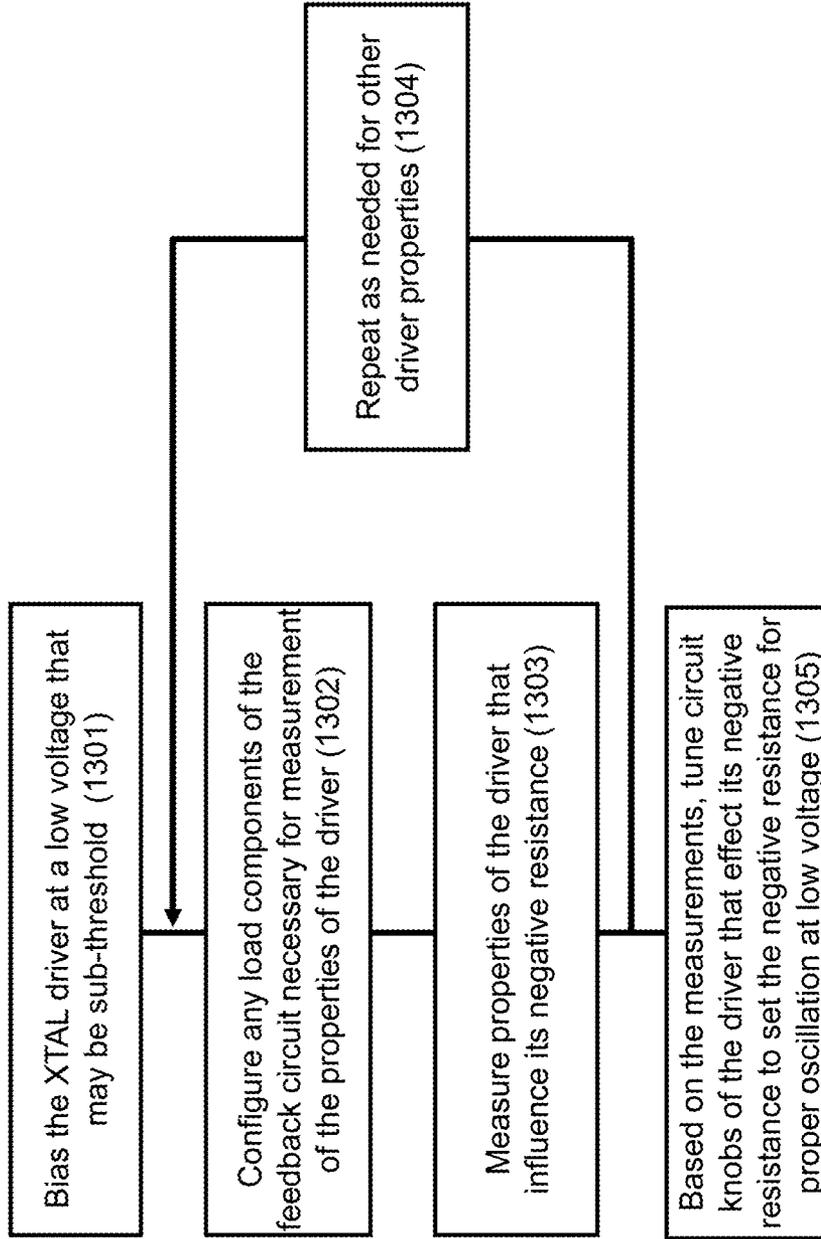


FIG. 14

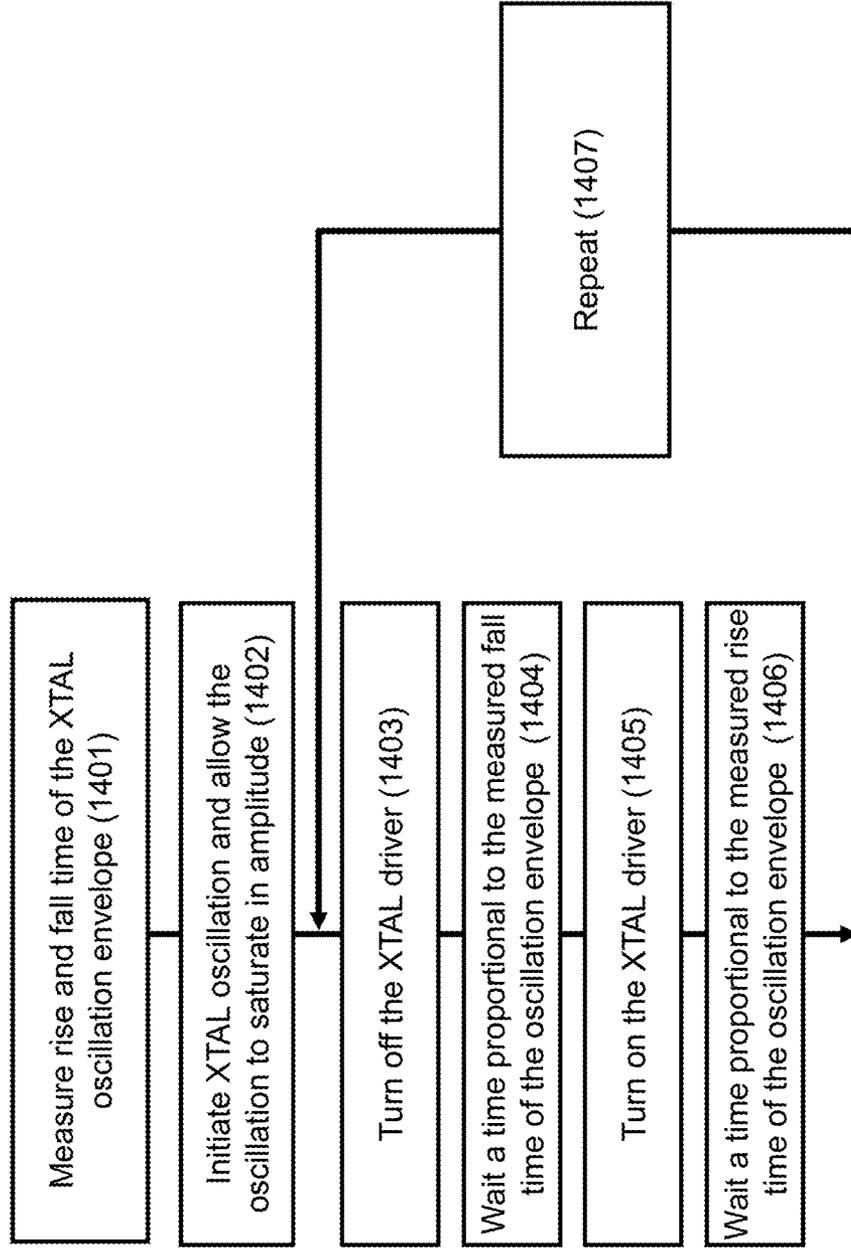
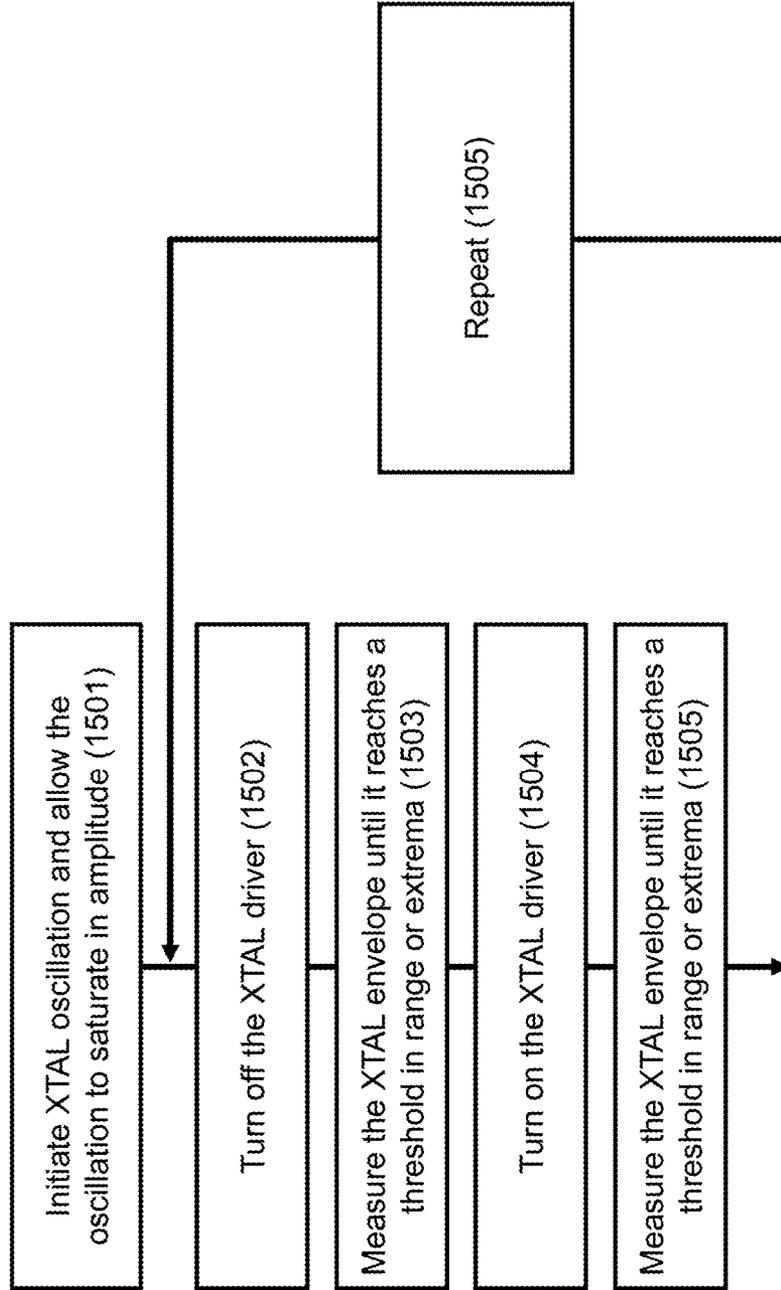


FIG. 15



**LOW VOLTAGE CRYSTAL OSCILLATOR
(XTAL) DRIVER WITH FEEDBACK
CONTROLLED DUTY CYCLING FOR ULTRA
LOW POWER**

PRIORITY CLAIMS

The instant application is a non-provisional of and claims priority under 35 U.S.C. §119 to U.S. Provisional Application Ser. No. 61/926,014, entitled "A Low Voltage Crystal Oscillator (XTAL) Driver With Feedback Controlled Duty Cycling For Ultra Low Power," filed Jan. 10, 2014, which is herein expressly incorporated by reference.

FIELDS

Some embodiments generally relate to low power circuit designs, and more particularly, relate to a low voltage XTAL driver with feedback controlled duty cycling for ultra low power.

BACKGROUND

Portable systems that operate from a battery and/or from power harvested from the environment typically need to consume small amounts of energy to prolong the system lifetime for a given amount of available energy. The energy budget for a portable system is increasingly important in a widening set of applications due to a combination of requirements for smaller size (less battery volume, so less energy available), longer lifetimes (make energy last longer), and/or more functionality (do more with the same amount of energy).

Many portable electronic devices such as wireless sensor nodes further typically spend a large fraction of their time in sleep modes waiting for external or internal stimuli to awaken them. During these sleep (or standby) modes, many devices use a stable clock source for keeping time to reduce the cost of re-synchronizing to other radios, among other reasons. During active modes, an accurate timing reference is used for bias precise data sampling, RF modulation, and synchronous digital computation, among other reasons.

One known approach to provide an accurate clock source includes using a crystal oscillator (XTAL). XTAL-based oscillators can consume an appreciable portion of available system power, especially during standby modes. For example, an energy harvesting body sensor network (BSN) SoC (system on a chip) having a 200 kHz XTAL consumes 19 μ W while measuring ECG, extracting heart rate, and sending RF packets every few seconds. F. Zhang, Y. Zhang, J. Silver, Y. Shakhsheer, M. Nagaraju, A. Klinefelter, J. Pandey, J. Boley, E. Carlson, A. Shrivastava, B. Otis, and B. H. Calhoun, "A Battery-less 19 μ W MICS/ISM-Band Energy Harvesting Body Area Sensor Node SoC," ISSCC Dig. Tech. Papers, pp. 298-299, 2012, which is incorporated by reference. In this example, over 2 μ W of the total power consumption is consumed by the 200 kHz XTAL. Id.

Thus, a need exists for a method to produce an accurate clock signal from a XTAL oscillator at much lower power levels that are compatible with miniaturized ultra low power electronics.

SUMMARY

Systems, methods, and apparatus for operating a crystal oscillator (XTAL) at very low voltage, e.g., even into the sub-threshold operating regime of the metal-oxide-semiconductor (MOS) transistors, are described. In some embodi-

ments, a calibration scheme optimizes the XTAL driver for operation at low voltages. To achieve further power savings, the XTAL driver can include a feedback-controlled mode that duty cycles the XTAL while maintaining a stable output clock. Some embodiments disclosed herein include an apparatus that has a XTAL driver, which has an amplifier with MOS transistors. The XTAL driver is configured to produce an operating signal to operate a XTAL while the MOS transistors are operated at a sub-threshold operating regime. The apparatus also includes a feedback control unit that is operatively coupled to the XTAL driver. The feedback control unit is configured to receive the operating signal from the XTAL driver, the feedback control unit configured to generate an adjustment signal based on the operating signal. The XTAL driver is further configured to adjust circuit level properties of the XTAL driver in response to the adjustment signal such that a negative resistance of the amplifier of the XTAL driver is calibrated to a value for operation of the MOS transistors at the sub-threshold operating regime.

Some embodiments disclosed herein include an apparatus that has a XTAL, which is configured to operate at a sub-threshold operating regime of MOS transistors to generate an oscillation. The apparatus further includes a XTAL driver communicatively coupled to the XTAL, which is configured to generate a duty cycle signal to modulate an envelope of the oscillation. The apparatus further includes a feedback control unit communicatively coupled to the XTAL driver and the XTAL, which is configured to use feedback from the oscillation to repeatedly turn on the XTAL driver when an amplitude of the envelope of the oscillation decays to a minimum value and turn off the XTAL driver when the amplitude of the envelope of the oscillation reaches a maximum value.

Some embodiments disclosed herein include a method for duty cycling a XTAL. The method performs the following: obtaining measurements of a rise time and a fall time of a XTAL oscillation envelope; sending an initiation signal to the XTAL to initiate an XTAL oscillation that is configured to reach a maximum amplitude; and repeatedly performing sending a first signal to turn off the XTAL driver for a first time proportional to the fall time of the XTAL oscillation envelope, and sending a second signal to turn on the XTAL driver for a second time proportional to the rise time of the XTAL oscillation envelope. The first time and the second time are relative to growing and decaying delays of the XTAL oscillation envelope such that the XTAL oscillation is preserved.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a diagram showing a known XTAL circuit and its equivalent circuit schematic.

FIG. 2 shows a block diagram of a feedback scheme that uses information from the output of a XTAL driver operating at low voltage, including into the sub-threshold region, according to an embodiment.

FIG. 3 is a block diagram of a system that can use a calibration method to size the XTAL driver for operation at very low supply voltages, according to an embodiment.

FIG. 4 is a block diagram of a system that can use a calibration circuit that sizes the XTAL driver for operation at very low supply voltages, according to an embodiment.

FIG. 5 shows a circuit diagram of an example of the calibration circuit that sizes the XTAL driver for operation at very low supply voltages, according to an embodiment.

FIG. 6 is an example of simulation result that shows proper startup of one instantiation of a low voltage XTAL driver with a supply voltage of 300 mV.

FIG. 7 shows a system block diagram for a XTAL driver and feedback control scheme that uses feedback from the oscillating signal(s) X_I and/or X_O to turn on and off the driver for saving power, and a timing diagram showing how duty cycling can modulate the envelope of X_I (and X_O) without stopping oscillation if the duty cycle is controlled relative to the amplitude of the X_I envelope, according to an embodiment.

FIG. 8 shows a system block diagram for a system that can control the duty cycle of the XTAL driver by turning it on and off and a timing diagram showing how duty cycling can modulate the envelope of X_I without stopping oscillation if the duty cycle is controlled relative to the growing and decaying delays (T_G and T_D , respectively) of the X_I envelope, according to an embodiment.

FIG. 9 shows a block diagram of a circuit to measure the rising delay, T_G , of the oscillation envelope of X_I , according to an embodiment.

FIG. 10 shows a block diagram showing a circuit to measure the falling delay, T_D , of the oscillation envelope of X_I , according to an embodiment.

FIG. 11 shows a circuit schematic of an example of the complete XTAL oscillator system.

FIG. 12 shows an example of simulations results of the X_O waveform showing the envelope during duty cycled operation and the enable signal waveform.

FIG. 13 shows a flowchart for calibrating an XTAL driver for operation at low voltage including the sub-threshold region, according to an embodiment.

FIG. 14 shows a flowchart for duty cycling the driver for an XTAL while persevering oscillation, according to an embodiment.

FIG. 15 shows a flowchart for duty cycling an XTAL while persevering oscillation, according to another embodiment.

DETAILED DESCRIPTION

The low voltage crystal oscillator (XTAL) driver with feedback controlled duty cycling for ultra low power bias an amplifier for an XTAL in the sub-threshold operating regime. Alternatively, a feedback control scheme can be used to bias the amplifier for an XTAL biased in the sub-threshold operating regime.

In some embodiments, the amplifier of a XTAL oscillator can be duty cycled to save power. For example, a XTAL driver (e.g., the amplifier **105**, which includes metal-oxide-semiconductor (MOS) transistors) can be turned off to save power when the amplitude of the XTAL oscillation reaches a maximum value in range but be turned back on when the amplitude of the XTAL oscillation starts to decay. This allows the XTAL oscillator to maintain the oscillation before it stops. In addition or alternatively, a feedback control scheme to duty cycle the amplifier of a XTAL oscillator can be used to monitor the amplitude of the oscillation.

FIG. 1 shows the architecture (e.g., **101**) and equivalent circuit (e.g., **102**) for a known XTAL implementation for oscillation in parallel mode. In parallel mode, the crystal oscillator XTAL **106** appears as an inductor **109** and oscillates with the load capacitors C_L **112**. The equivalent circuit of the XTAL itself is a series RLC circuit with a parallel parasitic capacitance C_p **113**. The quality factor (Q) of a crystal oscillator is in the range of **50,000**, which provides a precise frequency output. The inverting amplifier **105** presents a negative resistance **108** to the applied ac current to overcome the damping effect of crystal's equivalent series resistance (ESR) **111** in the RLC circuit of FIG. 1. To oscillate, the circuit can meet the Barkhausen criteria of oscillation by

making the negative resistance **108** of the amplifier greater than the ESR **111** of the crystal. The value of the negative resistance **108** is a function of frequency. The ESR **111** of the crystal represents an energy dissipating component, and the amplifier **105** compensates for this dissipation through its negative resistance **108** by supplying/replenishing the dissipated energy in the crystal.

The power consumption of the XTAL circuit is determined by the XTAL **106** and the design of the amplifier **105**. The energy dissipating component in crystal oscillator **106** represented by is the crystal's ESR **111**. ESR **111** represents the dissipation of energy in the form of heat loss and is given by I^2R , where R is the value of resistance of the crystal's ESR **111**, and I is the RMS (Root Mean Square) current flowing into the crystal. This loss is directly proportional to the amplitude of oscillation. To reduce the loss and hence to reduce the power consumption of the crystal oscillator **106**, often the amplitude of oscillation is reduced. This can be done by operating the amplifier **105** in sub-threshold region. E. Vittoz, and J. Fellarath, "CMOS Analog Integrated Circuits Based on Weak Inversion Operations," IEEE Journal of Solid State Circuits, vol. 12 no. 3 pp 224-231 June 1977; and W. Thommen, "An improved Low Power Crystal Oscillator," IEEE European Solid State Circuits Conference, 1999; each of which is incorporated by reference. Known circuit techniques reduce the amplitude of oscillation by using a delay locked loop (DLL) or by simply quenching the oscillation amplitude. D. Yoon, D. Sylvester, and D. Blaauw, "A 5.58 nW 32.768 kHz DLL-Assisted XO for Real-Time Clocks in Wireless Sensing Applications" IEEE International Solid State Circuits Conference, 2012; W. Thommen, "An improved Low Power Crystal Oscillator," IEEE European Solid State Circuits Conference, 1999; each of which is incorporated by reference. These techniques have reduced the power consumption of 32 kHz crystal oscillator to 5.58 nW making it possible to use the crystal oscillator for wireless sensors, where a lower power clock is desired.

In contrast to these known circuit techniques, described herein are systems, methods, and apparatus for operating a crystal oscillator (XTAL) at very low voltage, even into the sub-threshold operating regime of the MOS transistors (of the amplifier **105** for example). In some embodiments, calibration scheme optimizes the XTAL driver (e.g., the amplifier **105**) for operation at low voltages. To achieve further power savings, the XTAL driver can include a feedback controlled mode (not shown in FIG. 1; see **202** in FIG. 2, **303** in FIG. 3, **403** in FIG. 4, etc.) that duty cycles the XTAL **106** while maintaining a stable output clock.

As discussed further below, a compensated amplifier can maintain oscillation at low voltage and a feedback controlled duty cycling scheme can reduce power.

The amplifier **105** for the XTAL **106** can meet the Barkhausen oscillation criterion at low voltage to ensure oscillation of the XTAL. Various inverting amplifier architectures can be used to implement the amplifier. A simple push-pull inverter (a digital inverter) with a big bias resistor **107** shown in FIG. 1 can be used: for example, it is single stage and consumes less power. W. Thommen, "An improved Low Power Crystal Oscillator," IEEE European Solid State Circuits Conference, 1999. Sizing the driver to maintain the correct negative resistance at low supply voltage can be a challenge. At lower driver strength (smaller sizes for nMOS and pMOS), the negative resistance **108** of the amplifier **105** is lower and cannot meet the oscillation criterion. Increasing the driver transistor sizes increases the negative resistance, but the negative resistance starts decreasing again at some

point with increasing size because of the self-loading in the inverter. Also, increasing the size of the inverter increases the power consumption.

Open loop sizing of the amplifier **105** is unlikely to produce a functioning XTAL circuit **101** with high yield in sub-threshold regime due to the impact of process variations, which have an exponential impact on the transistor resistance in this operating region. To support operation at low voltage, some embodiments disclosed herein use a calibration method to address this variation. FIG. 2 shows a block diagram of a feedback scheme that uses information from the output of a XTAL driver **201** (the XTAL **204** may or may not be attached and oscillating) operating at low voltage, including into the sub-threshold regime, to adjust the circuit level properties of the XTAL driver **201** such that its negative resistance is calibrated to the correct (or desired or predefined) value. For example, the feedback circuit includes a feedback control unit **202** that receives the driver output **203** from the XTAL driver **201**. The driver output **203** can be used by the feedback control unit **202** to determine the current status of the oscillation, e.g., amplitudes of the oscillation, power consumption, etc. The feedback control unit **202** can then send a signal to the XTAL driver **201** to tune the XTAL driver **201** to set negative resistance for sub-threshold operation of the XTAL **204**, e.g., at **205**.

FIG. 3 shows a block diagram of circuit implementation of a feedback system using the calibration scheme shown in FIG. 2 for sub-threshold operation regime of a XTAL, according to an embodiment. As shown in FIG. 3, the output **302** of the inverter **301** can be sent to a feedback control unit **303** (e.g., which could be the equivalent of **202** in FIG. 2) used to set or generate a feedback control signal that tunes the MOS transistor strength to adjust the resistance of the inverter, e.g., at **304**.

FIG. 4 shows a system block diagram of an alternative circuit implementation of the feedback system for sub-threshold operation of a XTAL as shown in FIG. 2, e.g., by connecting the inverter output **402** to an off-chip resistor **404** with a reference value of resistance, according to an embodiment. The inverter output **402** is compared to a voltage reference **405** and the result is used by the feedback control unit **403** (e.g., equivalent to **202** in FIG. 2) to set (or generate) a control signal that adjusts the effective lengths of the MOS transistors of the inverter **401**, e.g., at **406**. A similar scheme could use an on-chip resistance for calibration.

FIG. 5 shows a more detailed circuit schematic of an example of the calibration scheme shown in FIG. 4 to set the drive strength of the amplifier transistors MP **502a** and MN **502b**. The amplifier **501** is enabled when ENP (**503b**)=0 and ENN (**503a**)=1. For calibration of MN **502b** to a given drive strength, ENN **503a** and ENP **503b** are set to one. This enables the calibration circuit and connects MN **502b** to an external resistor Rc **505** through the switch MNC **504**. Oscillating signal XI **506** (e.g., equivalent to **103** in FIG. 1) to the amplifier **501** is connected to Ref **508**, which is selected to be at $V_{DD}/2$ to tune for a balanced inverter voltage transfer characteristic. The size of transistor MN **502b** is changed using the successive approximation register (SAR) **509** logic and the comparator **510** in the feedback loop. This can happen in the following way. Oscillating signal XI **506** and Ref **508** are set to $V_{DD}/2$, and the pull-down path is enabled while the pull-up path is disabled. The external resistor Rc **505** is connected to V_{DD} . If the size of MN **502b** is very big, then it will pull down the XO node **512** below Ref **508**, which will cause the comparator output to go low. This low signal causes the SAR logic **509** to reduce the size of the transistor MN **502b**. The size of MN **502b** is successively approximated by turning

on or off different fingers of the transistor MN **502b** that are binary weighted in size. In this embodiment, the process takes **5** clock cycles, and the algorithm effectively performs a binary search for the right drive strength of the transistor MN **502b** set by the external resistor Rc **505**. This calibrates MN **502b** to the right drive strength, compensating for process variation. Similarly MP **502a** is sized by setting ENN **503a** and ENP **503b** to zero and connecting the external resistor Rc **505** to ground. The size of the external resistor Rc **505** can be used so that the amplifier **501** can be sized to supply 5-20 nA of bias current, which provides enough drive strength to meet Barkhausen criteria for oscillation.

FIG. 6 shows a simulation result of an example of the oscillator after calibration (as implemented in various embodiments illustrated in FIGS. 3-5), confirming that it can oscillate at a V_{DD} of 0.3V at a power consumption of ~2 nW.

As discussed below, in addition to or alternative to biasing the amplifier for sub-threshold operation, a feedback controlled duty cycling of the oscillator can be used to measure traits of the XTAL to maintain the oscillation while reducing power. The energy of a crystal oscillator is stored in its equivalent inductor and capacitor. After the saturation of oscillation, the stored energy in crystal's equivalent inductor and capacitor is saturated. If the amplifier is disabled in this condition, the oscillation will start decaying. The power consumption becomes negligible when the oscillator is disabled. The oscillation does not die right away but instead decays with a time constant given by ESR (e.g., **111** in FIG. 1) and L_m (series inductance, e.g., **109** in FIG. 1) of the crystal. The output of the crystal oscillator is still useful and can be used to provide clock when the output of the crystal oscillator is decaying because the frequency of the output of the crystal oscillator does not drift while the amplitude decays. Therefore, power consumption of crystal oscillator can be further reduced by switching off the amplifier. If the amplitude of the crystal oscillator output is allowed to decrease too far, the oscillation stops, so the amplifier can be turned back on before the oscillation decays too far.

FIG. 7 shows a system block diagram for a XTAL driver **703** and an oscillation control **705** (e.g., similar to the feedback control unit **202** in FIG. 2) that uses feedback from the oscillating signal(s) X_I **701** and/or X_O **700** to turn on and off the driver **703** for saving power. The feedback The XTAL driver **703** generates a duty cycle signal to modulate an envelope of the oscillation at XTAL **702**; and an oscillation control unit **705** uses feedback from the oscillation X_I **701** and/or X_O **700** to periodically turn on and/or off the XTAL driver **703** such that the XTAL driver can be turned off to save power but to be turned on in time before the oscillation stops. For example, as shown in FIG. 7, when the amplifier/driver is enabled (e.g., at **706**), the amplitude of the envelope of the oscillation **706** increases; and when the amplifier/driver is disabled (e.g., at **707**), the amplitude of the oscillation envelope **706** decreases. Thus, to both save power and sustain the oscillation, the oscillation control unit **705** uses feedback information related to the amplitude of the oscillating signal envelope (e.g., **701** and **700**) to ensure the XTAL driver **703** turns back on in time to preserve oscillation, e.g., turning on the amplifier/XTAL driver **703** when the amplitude of the envelope of the oscillation decays to a minimum value (e.g., **709**) and turning off the amplifier/XTAL driver **703** when the amplitude of the envelope of the oscillation reaches a maximum value (e.g., **708**). In this way, the amplitudes of the envelope of the XTAL oscillation may oscillate between the minimum value **709** and the maximum value **708** so that the XTAL oscillation can be maintained.

FIG. 8 shows a system block diagram and a timing diagram for a system and scheme that uses feedback to duty cycle the XTAL amplifier for power savings while ensuring that the oscillation remains intact, according to an embodiment. The amplifier **801** is switched periodically while keeping the amplitude of oscillation high enough for the receiver circuit to detect oscillation. When the amplifier **801** is disabled (e.g., at **806**), the oscillation at X_i , **802** will decay with a time constant (T_D) **807**, which is determined by the ESR (e.g., **111** in FIG. 1) and L_m (e.g., **109** in FIG. 1). When the amplifier **801** is enabled again during **808**, the amplitude of the XTAL oscillation grows with a time constant (T_G) **809**, which is determined by R_N -ESR and L_m . A. Shrivastava, R. Yadav, and P. K. Rana, "Fast Start-up Crystal Oscillator," U.S. Pat. No. 8,120,439, which is incorporated by reference. For optimal power savings, the amplifier **801** should be disabled for time proportional to T_D **807** and enabled for time proportional to T_G **809** as shown in FIG. 8. Other control scheme embodiments are possible, including direct comparison of the oscillation envelope amplitude or maximum/minimum values with voltage references.

The feedback control unit (labeled "OSC T_{ON} and T_{OFF} Control") **803** in FIG. 8 measures T_G and T_D . A counter running based on the oscillator output frequency is enabled when the amplitude of the crystal oscillator (XTAL) output crosses a set threshold. The counter counts until C1 and stops when the amplitude of the crystal oscillator output crosses a higher threshold. This results in a digital output pulse proportional to T_G . Similarly, a pulse with width C2 proportional to T_D can be obtained. The feedback circuit can produce a clock with the period (C1+C2), with C1 as the high phase width and C2 as the low phase width, as shown in FIG. 8. The proposed technique enables a calibrated switching of the amplifier **801** of the crystal oscillator XTAL and reduces the power to near 1 nW or below.

FIG. 9 shows a circuit to measure T_G (e.g., the circuit implementation may be part of the oscillation control unit **803** in FIG. 8) and a timing diagram showing the growing amplitude of the envelope of XTAL oscillation, according to an embodiment. The circuit includes comparators **901a-b** and SR flip-flops **902a-b**. Threshold voltages V_{REFH} **905a** (e.g., 220 mV for $V_{DD}=0.3V$) and V_{REFL} **905b** (e.g., 200 mV for $V_{DD}=0.3V$) are applied at the negative terminal of the respective comparator, while X_i is applied at the positive terminal of each comparator. Once the oscillation's amplitude goes above V_{REFL} , the output of the upper comparator **901a** goes high, and the corresponding SR flip-flop **902a** is set. This sets CountEn **906** to high. A counter (not shown) is enabled using this signal, and the counter starts counting. The amplitude of oscillation continues increasing. Once the oscillation crosses V_{REFH} **905a**, the lower comparator **901b** goes high, the corresponding SR flip-flop **902b** is set and sets CountEn **906** to zero. This stops the counter and sets the value of the counter, which is proportional to the growth of oscillation. The value of the counter is digital and is stored, while the circuit in FIG. 9 is disabled to save power. The proposed circuit consumes power only when the count value is needed.

FIG. 10 shows the circuit implementation for obtaining T_D for the oscillator (e.g., the circuit implementation may be part of the oscillation control unit **803** in FIG. 8) and a timing diagram showing the decaying amplitude of the envelope of XTAL oscillation, according to an embodiment. The circuit in FIG. 10 is very similar to the circuit used for obtaining T_G shown in FIG. 9, except that two additional D flip-flops **1002a-b** are included to capture negative triggers. For example, when the oscillation's amplitude decays below V_{REFH} (**1005a**), the output of the lower comparator **1001b**

goes low, and the corresponding SR flip-flop **1003b** is set and thus the D flip-flop **1002a** is set high. This sets CountEn **906** to high to enable a counter to start counting. When the amplitude of oscillation continues decaying and crosses V_{REFL} **1005b**, the upper comparator **1001a** goes low, and thus the corresponding SR flip-flop **1003a** is set, and the D flip-flop **1002a** has a same output value as that of **1002b**. This way, CountEn **906** is set to zero. This stops the counter and sets the value of the counter, which is proportional to the decay of oscillation.

It also enables a counter that counts when X_i is between V_{REFH} **1005a** and V_{REFL} **1005b**. While T_G (e.g., **809** in FIG. 8) is obtained when the amplifier (e.g., **801** in FIG. 8) is enabled, T_D (e.g., **807** in FIG. 8) is obtained when the amplifier (e.g., **801** in FIG. 8) is disabled. Both T_G and T_D are stored digitally and their corresponding circuits are disabled to save power. After obtaining T_G and T_D , the oscillator control (e.g., **803** in FIG. 8) turns on the amplifier (e.g., **801** in FIG. 8) for a time proportional to T_D and turns it off for a time proportional to T_G . This duty cycling of the amplifier saves power, and the feedback scheme protects the oscillation and ensures the oscillation remains intact. The total power consumption can be, for example, goes below 1 nW.

FIG. 11 shows the complete circuit diagram of an example of the proposed crystal oscillator circuit (e.g., a circuit implementation of the XTAL circuit shown in FIGS. 7-8). First, the calibration of the amplifier (e.g., **801** in FIG. 8) is performed at a calibration circuit **1101**. The calibration of the amplifier can be performed once after manufacturing or more often to compensate for environmental changes, for example. The calibration circuit **1101** sets the drive strength of the amplifier and compensates for process variations or other variations. After calibration, the time constant generation circuit **1102** obtains the time of growth T_G and time of decay T_D of the oscillator. These time constants are used to configure the clock, DCCLK **1103**, to switch the amplifier on and off. The duty cycle of DCCLK **1103** is determined by T_G and T_D with high time= T_G and low time= T_D . Once the DCCLK **1103** is configured, the time constant generation circuit **1102** is disabled. Similarly, calibration circuit **1101** is disabled after calibration, and all the digital bits are stored. This eliminates the power overhead of the calibration circuit **1101** or time constant generation circuit **1102**. The power consumption is given by the amplifier with duty cycling. A clock buffer **1105** is used to level convert the clock to higher voltage if needed.

FIG. 12 shows an example of the simulated results of the XTAL driver, e.g., showing duty cycling of the XTAL amplifier, leading to the saw toothed envelope for the oscillating signal output and saving power. The example XTAL driver in FIG. 12 was implemented in a 130 nm commercial CMOS process and fabricated. The waveform shows successful operation of the circuit at an average power consumption of less than 1 nW and a frequency of 32.768 kHz. For example, chart **1201** shows oscillation with duty cycling of the amplitude, and chart **1202** shows periodic enabling signal (e.g., DCCLK **1103** in FIG. 11) for the XTAL amplifier during oscillation duty cycling.

FIG. 13 shows a flowchart for calibrating an XTAL driver for operation at low voltage including the sub-threshold region (e.g., as performed by the feedback control unit **202** in FIG. 2), according to an embodiment. A feedback control unit can be included in the XTAL circuit to bias the XTAL driver at a low voltage that may be sub-threshold at **1301**, e.g., see the feedback control unit **202** in FIG. 2. The feedback control unit can configure any load components of the feedback circuit (e.g., see FIG. 2) that are used for measurement of the properties of the XTAL driver, at **1302**, and then measure

circuit properties of the XTAL driver that influence the negative resistance, at **1303**, e.g., voltage, current, and/or the like. The feedback control unit may repeat as needed for other driver properties, at **1304**, steps **1302-1303** to obtain different driver properties, e.g., amplitudes of the oscillation, etc. Based on the measurements, the control feedback unit can tune the XTAL driver that effects its negative resistance to set the negative resistance for proper oscillation at low voltage, at **1305**.

FIG. **14** shows a flowchart for duty cycling the driver for an XTAL while persevering oscillation (e.g., as performed by the oscillation control unit **705** in FIG. **7**, or **803** in FIG. **8**), according to an embodiment. As shown in FIG. **14**, an oscillation feedback control unit (e.g., **705** in FIG. **7**; **803** in FIG. **8**) may measure the rise and the fall times of the XTAL oscillation envelope, at **1401** (e.g., see the rise and the fall of the oscillation envelope in FIGS. **7-8**). The oscillation feedback control unit may initiate the XTAL oscillation and allow the oscillation to increase in amplitude at **1402**, e.g., by reaching a maximum oscillation amplitude (e.g., see **708** in FIG. **7**). The feedback control unit may then turn off the XTAL driver at **1403**, so as to save power; and wait a time proportional to the measured fall time of the oscillation envelope at **1404** before turning on the XTAL driver again at **1405**. In this way, the feedback control unit keeps the oscillation before the oscillation stops (e.g., before the amplitude of the oscillation diminishes to zero, or to a sufficiently small value such that a receiver circuit cannot detect the oscillation, etc.). The control unit may then wait a time proportional to the measured rise time of the oscillation envelope, at **1406**, to wait for the amplitude of the oscillation envelope to reach a maximum value. The turning on and off of the XTAL driver may be performed periodically in a repeated manner at **1407**, so as to form a duty cycle to save power and preserve the oscillation.

FIG. **15** shows a flowchart for duty cycling an XTAL while persevering oscillation (e.g., as performed by the oscillation control unit **705** in FIG. **7**, or **803** in FIG. **8**), according to another embodiment. Similar to the work flow described in FIG. **14**, a feedback control unit may initiate the XTAL oscillation and allow the oscillation to increase in amplitude at **1501**, and may turn off the XTAL driver at **1502** to save power. The control unit may then measure the XTAL envelope until the XTAL oscillation envelope reaches a threshold in range or extrema at **1503**, e.g., the minimum value **709** in FIG. **7**, and then turn on the XTAL driver at **1504**. The control unit may then measure the XTAL envelope until it reaches a maximum threshold in range or extrema, at **1505**, e.g., the maximum value **708** in FIG. **7**. The control unit may then monitor the XTAL oscillation and repeatedly turn off/on the XTAL driver as in steps **1502-1505**.

In sum, in some embodiments, the amplifier for an XTAL is biased in the sub-threshold operating regime. In addition or alternatively, a feedback control scheme can be used to bias an amplifier for an XTAL biased in the sub-threshold operating regime.

In some embodiments, the amplifier of a XTAL oscillator can be duty cycled to save power while the amplitude of the XTAL oscillation starts to decay but the amplifier can be turned back on to maintain the oscillation before it stops. In addition or alternatively, a feedback control scheme to duty cycle the amplifier of a XTAL oscillator can be used to save power while the amplitude of the XTAL oscillation starts to decay and the amplifier can be turned back on to maintain the oscillation before it stops.

It is intended that some of the methods and apparatus described herein can be performed by software (stored in memory and executed on hardware), hardware, or a combi-

nation thereof. For example, the control circuits discussed above can alternatively be control modules or control devices implemented in or including such software and/or hardware. Hardware modules may include, for example, a general-purpose processor, a field programmable gate array (FPGA), and/or an application specific integrated circuit (ASIC). Software modules (executed on hardware) can be expressed in a variety of software languages (e.g., computer code), including C, C++, Java™, Ruby, Visual Basic™, and other object-oriented, procedural, or other programming language and development tools. Examples of computer code include, but are not limited to, micro-code or micro-instructions, machine instructions, such as produced by a compiler, code used to produce a web service, and files containing higher-level instructions that are executed by a computer using an interpreter. Additional examples of computer code include, but are not limited to, control signals, encrypted code, and compressed code.

Some embodiments described herein relate to a computer storage product with a non-transitory computer-readable medium (also can be referred to as a non-transitory processor-readable medium) having instructions or computer code thereon for performing various computer-implemented operations. The computer-readable medium (or processor-readable medium) is non-transitory in the sense that it does not include transitory propagating signals per se (e.g., a propagating electromagnetic wave carrying information on a transmission medium such as space or a cable). The media and computer code (also can be referred to as code) may be those designed and constructed for the specific purpose or purposes. Examples of non-transitory computer-readable media include, but are not limited to, magnetic storage media such as hard disks, floppy disks, and magnetic tape; optical storage media such as Compact Disc/Digital Video Discs (CD/DVDs), Compact Disc-Read Only Memories (CD-ROMs), and holographic devices; magneto-optical storage media such as optical disks; carrier wave signal processing modules; and hardware devices that are specially configured to store and execute program code, such as Application-Specific Integrated Circuits (ASICs), Programmable Logic Devices (PLDs), Read-Only Memory (ROM) and Random-Access Memory (RAM) devices.

While various embodiments have been described above, it should be understood that they have been presented by way of example only, and not limitation. Where methods and steps described above indicate certain events occurring in certain order, the ordering of certain steps may be modified. Additionally, certain steps may be performed concurrently in a parallel process when possible, as well as performed sequentially as described above. Although various embodiments have been described as having particular features and/or combinations of components, other embodiments are possible having any combination or sub-combination of any features and/or components from any of the embodiments described herein.

What is claimed is:

1. An apparatus, comprising:
 - a crystal oscillator (XTAL) driver having an amplifier with metal-oxide-semiconductor (MOS) transistors, the XTAL driver configured to produce an operating signal to operate a XTAL while the MOS transistors are operated at a sub-threshold operating regime; and
 - a feedback control unit operatively coupled to the XTAL driver, the feedback control unit configured to receive an output from the XTAL driver, the feedback control unit configured to generate an adjustment signal based on a comparison of the output and a voltage reference to

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adjust effective lengths of the MOS transistors, the feedback control unit configured to send the adjustment signal to the XTAL driver;

the XTAL driver configured to adjust circuit properties of the XTAL driver in response to the adjustment signal such that a negative resistance of the amplifier of the XTAL driver is calibrated to a value for operation of the MOS transistors at the sub-threshold operating regime.

2. The apparatus of claim 1, wherein the feedback control unit is configured to bias the amplifier to be operated at the sub-threshold operating regime.

3. The apparatus of claim 1, wherein the amplifier includes an inverter having the MOS transistors.

4. The apparatus of claim 1, wherein: the amplifier includes an inverter, the negative resistance of the amplifier is calibrated by tuning a transistor strength of the inverter based on the output as feedback control.

5. The apparatus of claim 1, further comprising: an off-chip resistor with a reference value of resistance and operatively coupled to the XTAL driver, the XTAL driver configured to maintain a voltage reference based on the reference value of the off-chip resistor.

6. The apparatus of claim 1, wherein the value is sufficient to satisfy a condition for XTAL oscillation.

7. An apparatus, comprising: a crystal oscillator (XTAL) configured to generate an oscillation; a XTAL driver communicatively coupled to the XTAL, the XTAL driver configured to generate a duty cycle signal to modulate an envelope of the oscillation; and a feedback control unit communicatively coupled to the XTAL driver and the XTAL, the feedback control unit configured to generate an adjustment signal to adjust effective lengths of metal-oxide-semiconductor (MOS) transistors of the XTAL driver, the feedback control unit configured to use feedback from the oscillation to repeatedly turn on the XTAL driver when an amplitude of the envelope of the oscillation decays to a minimum value and turn off the XTAL driver when the amplitude of the envelope of the oscillation reaches a maximum value.

8. The apparatus of claim 7, wherein the XTAL is configured to operate at a sub-threshold operating regime of metal-oxide-semiconductor (MOS) transistors.

9. The apparatus of claim 7, wherein: the XTAL driver is configured to modulate the envelope of the oscillation without stopping the oscillation during a duty cycle, and the feedback control unit turns the XTAL driver on in time to sustain oscillation when the amplitude of the envelope of the oscillation decreases.

10. The apparatus of claim 7, wherein the XTAL driver comprises an amplifier, the amplifier configured to be

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switched repeatedly while maintaining the amplitude of the envelope of the oscillation above a minimum value.

11. The apparatus of claim 7, wherein the XTAL driver is configured to be turned off for a time proportional to a fall time of the XTAL oscillation.

12. The apparatus of claim 7, wherein the XTAL driver is configured to be turned on for a time proportional to a rise time of the XTAL oscillation.

13. A method for duty cycling a XTAL, comprising: obtaining measurements of a rise time and a fall time of a XTAL oscillation envelope; sending an initiation signal to the XTAL to initiate an XTAL oscillation that is configured to reach a maximum amplitude; and repeatedly performing the following: sending a first signal to turn off the XTAL driver for a first time proportional to the fall time of the XTAL oscillation envelope, and sending a second signal to turn on the XTAL driver for a second time proportional to the rise time of the XTAL oscillation envelope; the first time and the second time being relative to growing and decaying delays of the XTAL oscillation envelope such that the XTAL oscillation is preserved.

14. The method of claim 13, wherein the measurements of the rise time and the fall time of the XTAL oscillation envelope are obtained via a measurement circuit, the measurement circuit having a first comparator configured to set a high value for a counter to start counting when the amplitude of the XTAL oscillation increases, a second comparator configured to set a zero value for the counter to stop counting when the amplitude of the XTAL oscillation decreases.

15. The method of claim 13, further comprising: monitoring and controlling the first time and the second time relative to the growing and the decaying delays of the XTAL oscillation envelope.

16. The method of claim 13, wherein the XTAL driver operates the XTAL at a sub-threshold operating regime of MOS transistors of the XTAL driver.

17. The method of claim 13, wherein the XTAL driver modulates the XTAL oscillation envelope without stopping the XTAL oscillation during a duty cycle.

18. The method of claim 13, further comprising using feedback from the XTAL oscillation to periodically turn on and off the XTAL driver.

19. The method of claim 13, further comprising: turning off the XTAL driver until the XTAL oscillation envelope reaches a minimum value; turning on the XTAL driver until the XTAL oscillation envelope reaches a maximum value; and repeatedly turning on and off the XTAL driver such that the XTAL oscillation is preserved.

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