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Thatcher et al.

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[45] **July 8, 1975**

[54] **COMPUTER CONTROLLED SONIC FUEL SYSTEM**

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[73] Assignee: **Arthur K. Thatcher**, Merritt Island, Fla.

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[52] **U.S. Cl.** ..... **123/119 R**; 123/32 EA

[51] **Int. Cl.** **F02b 33/00**

[58] **Field of Search** ..... 123/32 EA, 119 R

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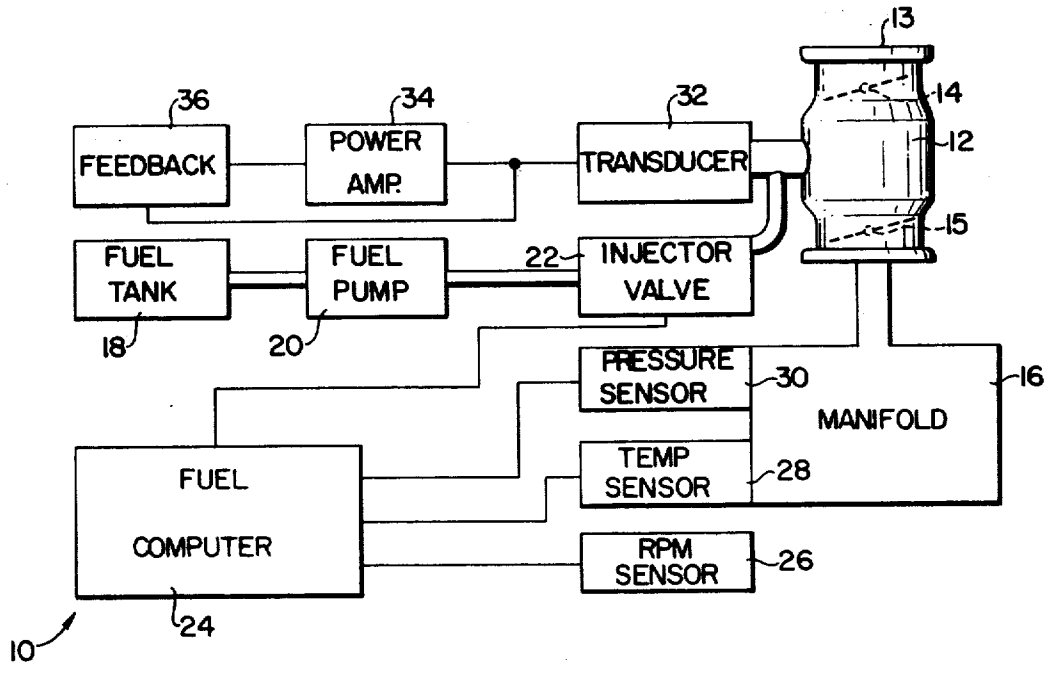
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Primary Examiner—Charles J. Myhre
Assistant Examiner—Joseph Cangelosi
Attorney, Agent, or Firm—Gardiner, Sixbey, Bradford & Carlson

[57] **ABSTRACT**

The computer controlled sonic fuel system employs a fuel computer to convert engine manifold pressure, temperature and RPM into variable fuel pulses which are directed onto the active surface of a sonic fuel dispersion unit. This sonic dispersion unit converts pulses of fuel into a substantially nonpulsating fuel-air mixture having a fuel-air ratio which remains substantially constant regardless of variations in engine manifold pressure, temperature and RPM.

41 Claims, 16 Drawing Figures



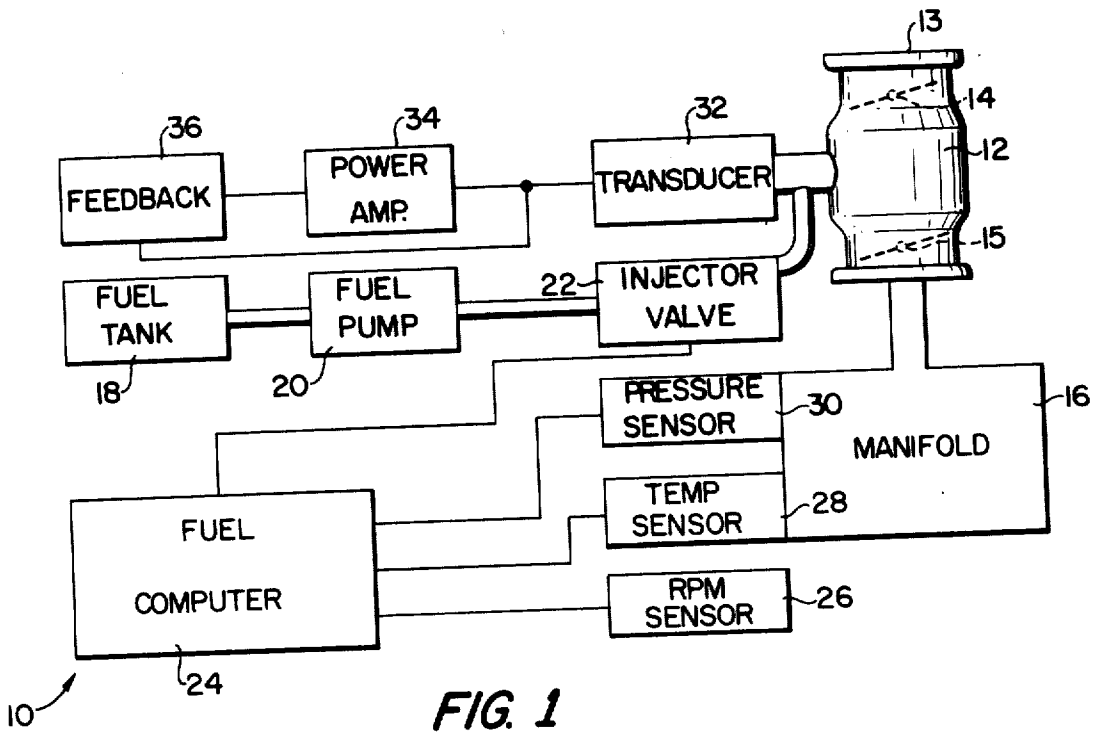
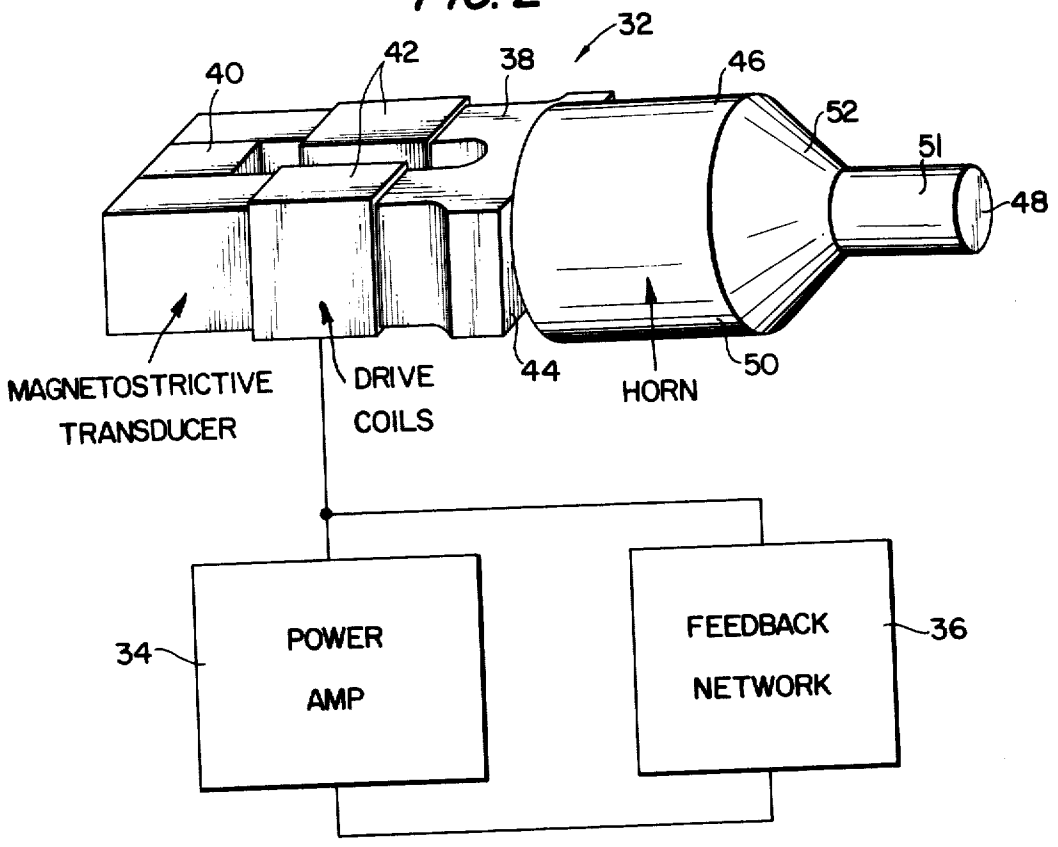

13
14
12
15
36
34
32
FEEDBACK
POWER AMP.
TRANSDUCER
FUEL TANK
FUEL PUMP
22
INJECTOR VALVE
18
20
PRESSURE SENSOR
30
MANIFOLD
16
TEMP SENSOR
28
FUEL COMPUTER
RPM SENSOR
26
24
10

FIG. 1

FIG. 2


32
40
42
38
46
52
51
48
MAGNETOSTRICTIVE TRANSDUCER
DRIVE COILS
44
HORN
50
34
POWER AMP
FEEDBACK NETWORK
36

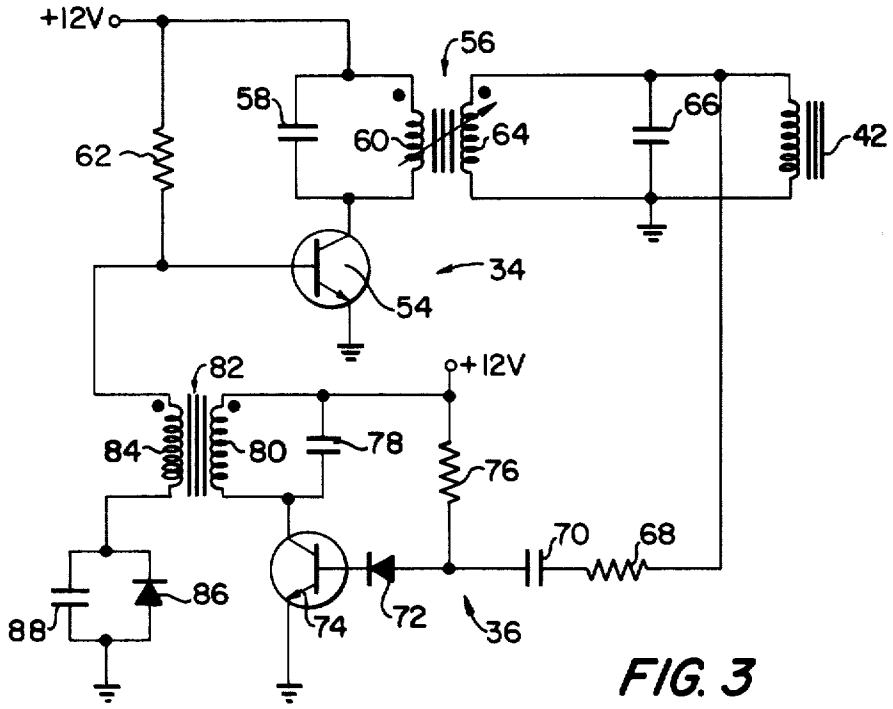


FIG. 3

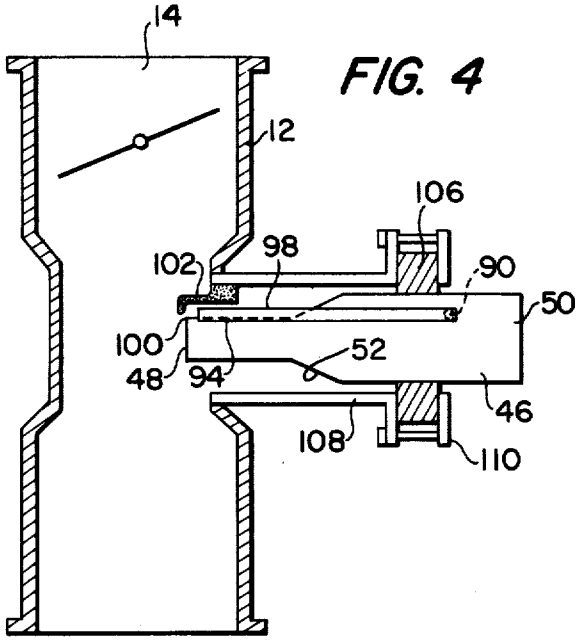
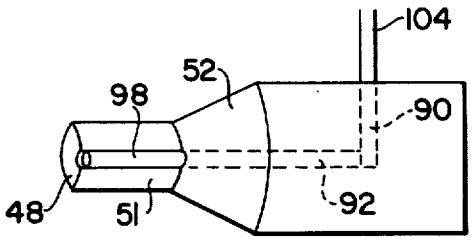


FIG. 4

FIG. 5



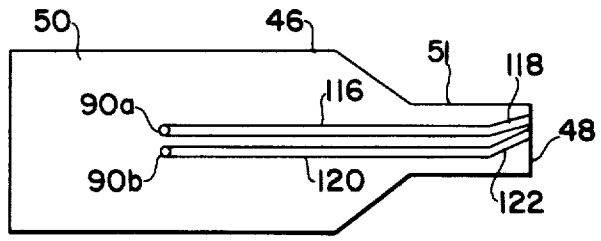


FIG. 6

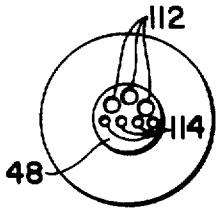
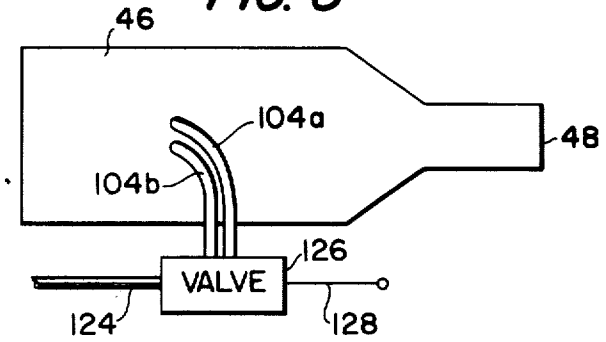


FIG. 7

FIG. 8



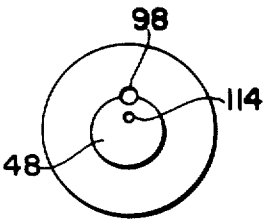


FIG. 9

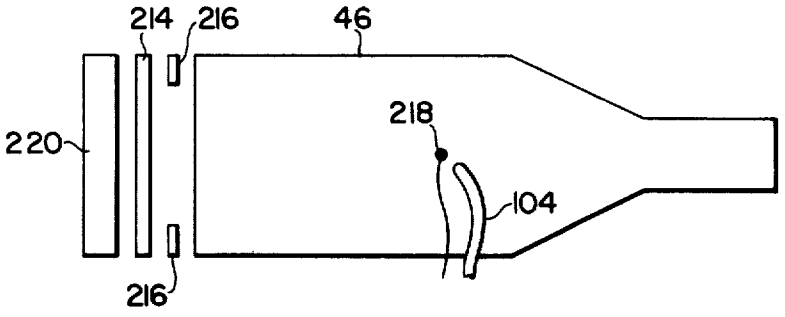


FIG. 15

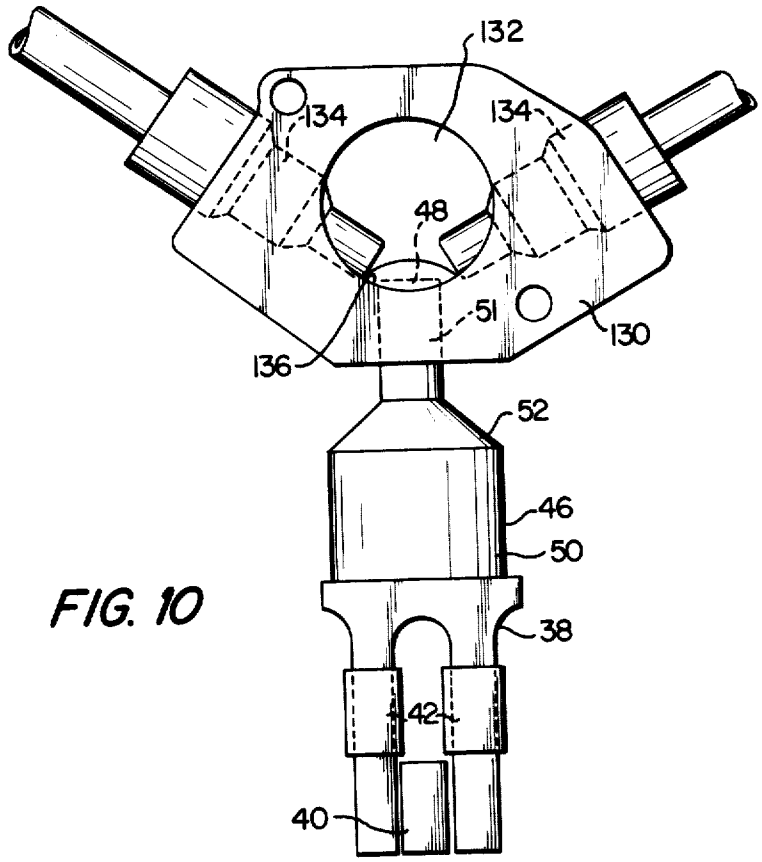

132
134
134
48
51
130
136
52
46
50
38
42
40

FIG. 10

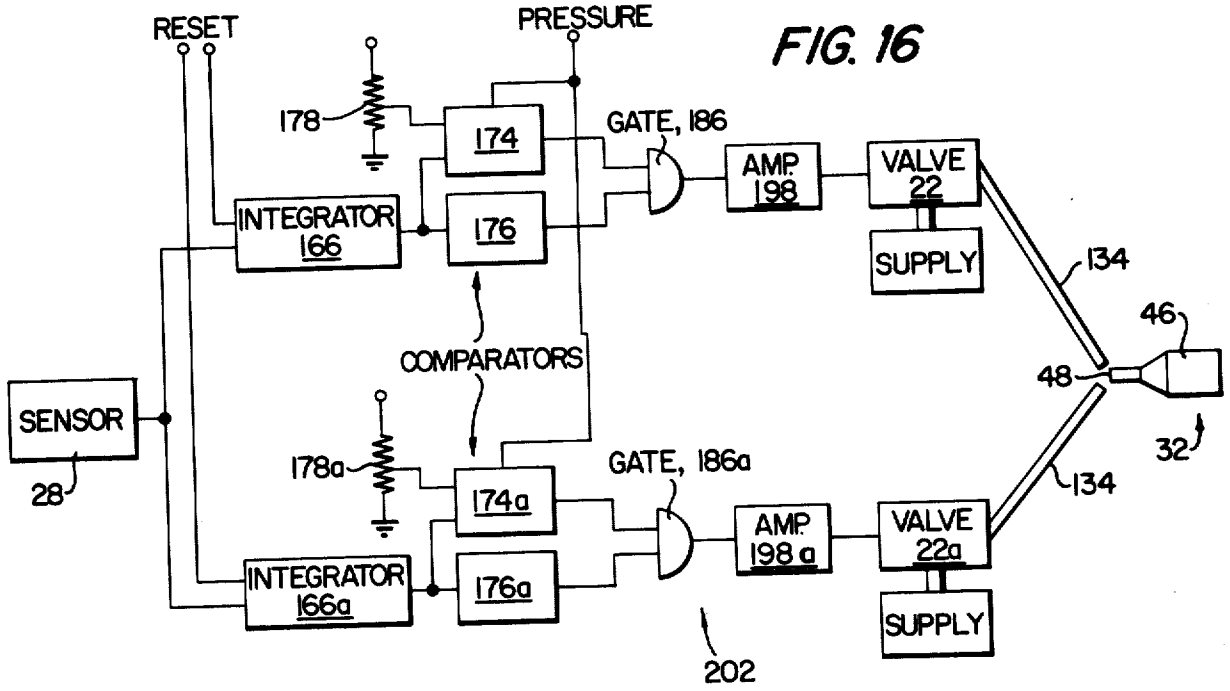
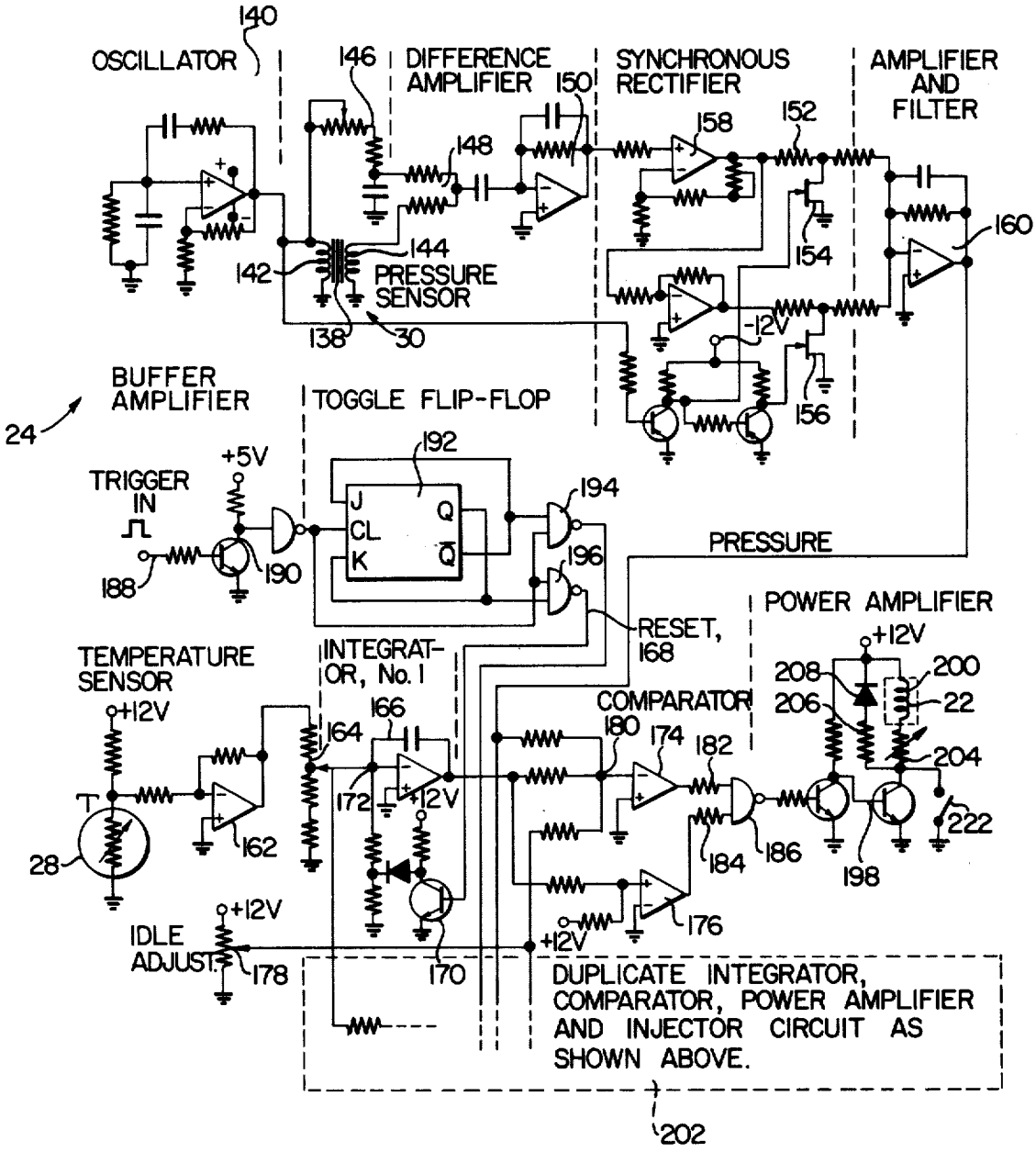

RESET
PRESSURE
178
174
GATE, 186
AMP. 198
VALVE 22
INTEGRATOR 166
176
SUPPLY
134
46
COMPARATORS
48
SENSOR
28
178a
174a
GATE, 186a
32
134
AMP. 198 a
VALVE 22a
INTEGRATOR 166a
176a
SUPPLY
202

FIG. 16

FIG. 11


140
OSCILLATOR
146
DIFFERENCE AMPLIFIER
150
SYNCHRONOUS RECTIFIER
158
152
AMPLIFIER AND FILTER
160
148
144
142
PRESSURE SENSOR
138
30
154
-12V
156
BUFFER AMPLIFIER
24
TOGGLE FLIP-FLOP
192
+5V
TRIGGER IN
188
190
J
CL
K
Q
194
196
PRESSURE
RESET, 168
POWER AMPLIFIER
+12V
208
200
206
22
204
222
198
TEMPERATURE SENSOR
+12V
28
162
INTEGRATOR, No. 1
166
164
172
+12V
COMPARATOR
180
174
182
184
186
176
+12V
IDLE ADJUST
178
170
DUPLICATE INTEGRATOR, COMPARATOR, POWER AMPLIFIER AND INJECTOR CIRCUIT AS SHOWN ABOVE.
202

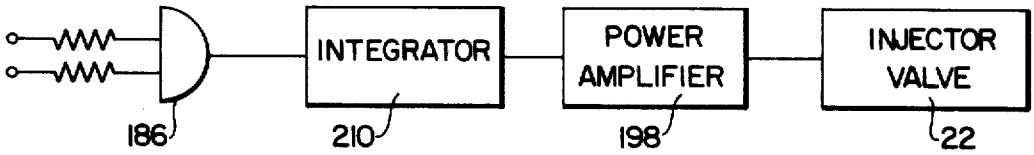


FIG. 12

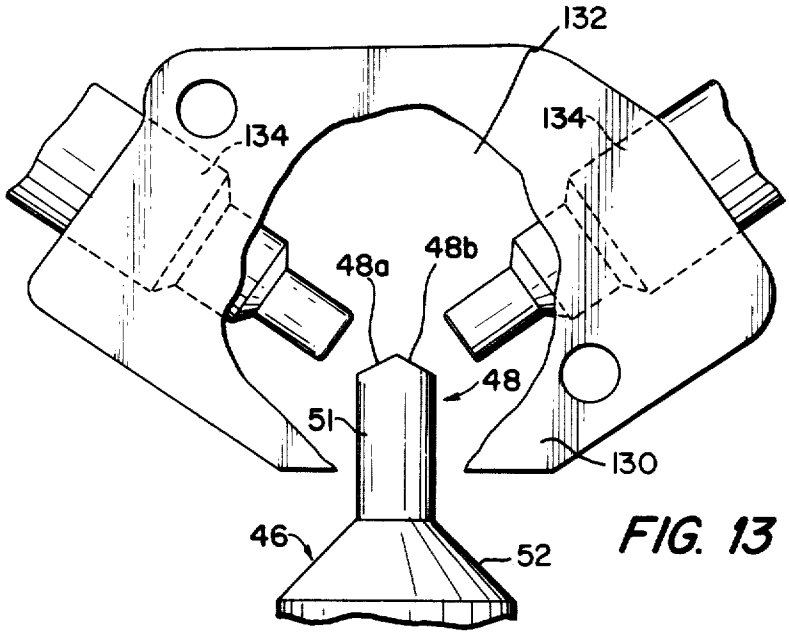


FIG. 13

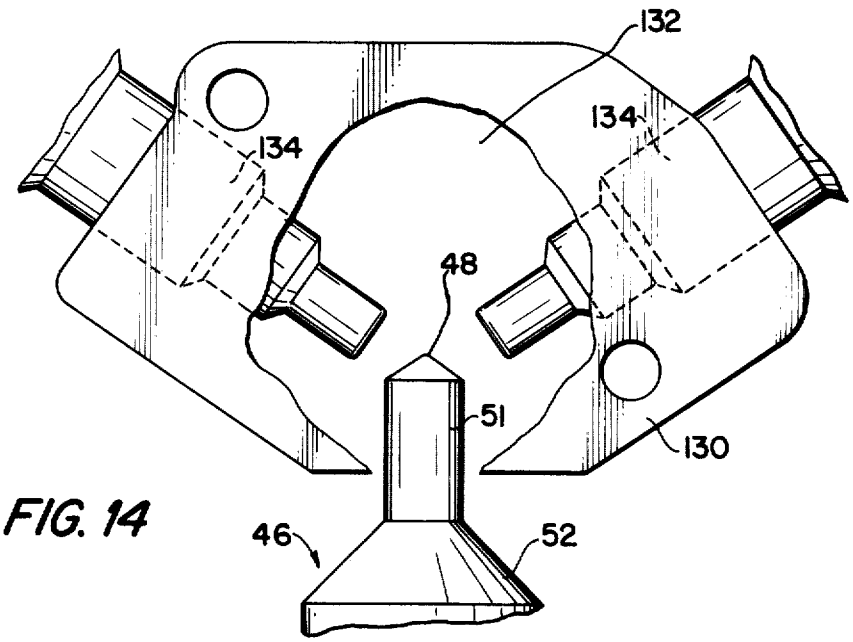


FIG. 14

COMPUTER CONTROLLED SONIC FUEL SYSTEM

BACKGROUND OF THE INVENTION

Conventional carburetor systems for internal combustion engines are unable to produce consistant molecular suspensions or emulsions of fuel molecules in the air stream drawn into the carburetor, and large droplets of fuel carried by the air stream into the engine cause inefficient and incomplete fuel combustion within the engine. Therefore numerous attempts have been made to develop fuel feed systems and carburetor systems which effectively feed liquid fuel at all engine speeds while maintaining a desirable air-fuel ratio. Such attempts have resulted in the development of sonic and ultrasonic carburetor systems to achieve intensive atomization of fuel and therefore an even dispersion of liquid fuel in the combustion air stream. However, previous sonic or ultrasonic mechanisms have failed to operate effectively within the varying conditions present in the carburization system of an internal combustion engine.

In an attempt to compensate for the variations in engine operation, fuel injection systems controlled by fuel computers have been developed to inject fuel in accordance with actual engine conditions. However, these injector systems operate in an impulse mode to provide a pulsating fuel supply which is not conducive to uniform fuel-air mixtures.

One conventional fuel computer controlled injection system injects fuel directly into the engine cylinders thereby requiring a plurality of injectors which must withstand high temperatures and pressures. A second fuel injection system injects fuel near the engine intake valve. It is obvious that both of these conventional systems have a minimum distance in which to achieve a proper fuel-air mixture and provide for surface evaporation of fuel particles.

It is a primary object of the present invention to provide a novel computer controlled sonic fuel system which effectively combines the advantages of a fuel computer and a sonic fuel dispersion mechanism to provide a more uniform feeding of fuel and a proper fuel-air mixture for all engine operating conditions.

Another object of the present invention is to provide a novel computer controlled sonic fuel system which eliminates the requirement for a plurality of fuel injectors and the need for injectors capable of withstanding high temperatures and pressures.

A further object of the present invention is to provide a novel and improved computer controlled sonic fuel system adapted to provide a uniform quantity of fuel to each engine cylinder by providing a relatively long path for an air-fuel mixing action.

Another object of the present invention is to provide a novel computer controlled sonic fuel system which combines fuel feed control in accordance with engine operating conditions with sonic induced dispersion of fuel to achieve a substantially constant fuel-air ratio and enhanced fuel combustion.

A further object of the present invention is to provide a novel computer controlled sonic fuel system which incorporates an improved sonic transducer and horn to provide an enhanced fuel-air dispersion.

A still further object of the present invention is to provide a novel and improved computer controlled sonic fuel system which may be effectively and economically incorporated in existing internal combustion engines.

These and other objects of the present invention will become readily apparent upon a consideration of the following specification and claims taken in conjunction with the accompanying drawings in which:

FIG. **1** is a block diagram of the computer controlled sonic fuel system of the present invention;

FIG. **2** is a perspective view of a sonic unit adapted for use with the system of FIG. **1**;

FIG. **3** is a schematic diagram of the electrical driving circuit for the sonic unit of FIG. **1**;

FIG. **4** is a sectional view of a second embodiment of a sonic unit of the present invention;

FIG. **5** is a plan view of the sonic unit of FIG. **4**;

FIG. **6** is a sectional view of a third embodiment of a sonic unit of the present invention;

FIG. **7** is an end view of the sonic unit of FIG. **6**;

FIG. **8** is a side view of the sonic unit of FIG. **6**;

FIG. **9** is an end view of a fourth embodiment of a sonic unit of the present invention;

FIG. **10** is a plan view of a fifth embodiment of a sonic unit of the present invention;

FIG. **11** is a schematic diagram of the fuel computer of FIG. **1**;

FIG. **12** is a block diagram of the output section of the fuel computer of FIG. **11** modified to provide variable amplitude control pulses;

FIG. **13** is a plan view of a sixth embodiment of a sonic unit of the present invention;

FIG. **14** is a plan view of a seventh embodiment of a sonic unit of the present invention;

FIG. **15** is an exploded view of a piezoelectric sonic unit for use with the present invention; and

FIG. **16** is a block diagram of a modification of the fuel computer of FIG. **11**.

Basically, the computer controlled sonic fuel system of the present invention indicated generally at **10** in FIG. **1** includes a fuel computer which receives indications of engine manifold pressure, manifold temperature, and engine RPM. Since the volume of air supplied to an engine is proportional to the pressure and engine speed and inversely proportional to the temperature of the air, the fuel computer is adapted to convert these sensed variables into an electrical control signal which determines the amount of fuel fed to a sonic fuel dispersion unit. The sonic unit provides an effective lengthening of each impulse since, as the fuel strikes the sonic surface, atomization commences immediately and is sustained over a finite period of time, depending upon the size of the control impulse. This tends to give a more uniform feeding of fuel and, when accomplished in an engine at a position in advance of the branching point in the engine intake manifold where the manifold branches out to each cylinder, allows a relatively long path for the air-fuel mixing action.

The computer controlled sonic fuel system **10** may be employed with practically any conventional carburetor **12**, such as for example one adapted to provide air from an air intake **13** under the control of a butterfly valve **14** for mixture with fuel to be supplied in response to a conventional throttle plate **15** to an engine manifold **16**. This fuel is provided from a fuel supply **18** by a constant pressure fuel pump **20** and is metered by an injector valve **22**. The injector valve is operated by a fuel computer **24** which provides a control signal derived from engine RPM, manifold temperature, and

manifold pressure, these engine variables being supplied by an RPM sensor **26**, a temperature sensor **28**, and a pressure sensor **30**.

The injector valve **22** provides fuel to a sonic fuel dispersion unit **32** which is adapted to introduce the fuel as minute droplets into the air stream passing to the manifold **16**. As will be subsequently described in greater detail, the unit **32** may introduce the fuel directly into the carburetor **12** or may be positioned above the carburetor or beneath the carburetor in the carburetor mounting, as for example beneath the throttle plate. Location of the sonic unit in the carburetor mounting is often quite advantageous if the computer controlled sonic fuel system **10** is to be installed in an existing internal combustion engine fuel system, for with this mounting location, there is no need to modify the existing carburetor to receive the sonic unit.

The sonic unit **32** is driven by an electrical system including a power amplifier network **34** and a feedback network **36**. it should be noted that all electrical systems included within the computer controlled sonic fuel system **10** are designed to be powered by a conventional automotive battery.

SONIC SYSTEM

Referring now to FIG. **2**, the sonic unit **32** basically consists of a sonic transducer **38** which, as illustrated, may consist of a conventional magnetostrictive transducer having a biasing magnet **40** between the two legs thereof and electrical drive coils **42** for driving the transducer at sonic frequencies. The transducer **38** includes an active surface **44** which drives a power concentrator or horn **46** bonded thereto.

The horn **46** is specifically designed to provide maximum sonic energy at the horn active surface **48**. This horn combines the advantages of the conventional tapered horn with those achieved with a stepped horn, and in so doing, eliminates many of the disadvantages of both. This is accomplished ideally by constructing the horn as a one half wave length composite horn with substantially one quarter wavelength sections with relation to the resonant frequency of the transducer **38**. The horn includes a first enlarged cylindrical portion **50**, a second small cylindrical portion **51** which terminates at the active surface **48**, and a tapered or conical section **52** joining the large and small cylindrical portions **50** and **51**. The large and small cylindrical sections are of constant diameter and both are of greater length than the intermediate tapered section **52**. It may also be possible to design the sections of the composite horn to other lengths which are multiples of the wave length of the resonant frequency of the transducer **38**, but for fuel system applications, a composite one half wave length is preferred.

The active surface **48** should be no more than one half the area of the area of a cross section of the enlarged portion **50**, and the tapered section **52** may be formed to any configuration sufficient to accomplish this purpose. It is noteworthy that this horn configuration provides the advantages of a stepped horn without the sonic stresses occasioned in such stepped horns by the radical change in the external configuration thereof provided by the step. However, like the stepped horns, the change in horn diameter occurs at a fraction of the operating wave length; in this case, one quarter wave length. The horn may be formed of solid aluminum, or other suitable known material.

Although the horn **46** may be mounted upon a piezoelectric transducer, a magnetostrictive transducer similar to that disclosed in FIG. **2** has been found ideal for engine fuel system applications. This is due to the fact that with the magnetostrictive transducer, a constant resonant frequency is achieved and this controls the frequency of the horn. With thin piezoelectric transducers, the mass of the horn holds the frequency of the transducer down, and the transducer is constantly attempting to increase in vibrational frequency, thereby adding stress to the bond between the transducer active surface and the horn. Also, with magnetostrictive transducers, the cooling requirements are not as severe as with piezoelectric transducers.

The transducer **38** is driven by a power circuit which receives power from a **12** volt automotive battery, or similar power source. As illustrated in FIG. **3**, this power circuit includes a power amplifier **34** and a feedback circuit **36**, the power amplifier including a power transistor **54** which is connected through a transformer **56** to drive the transducer **38**. A tank circuit consisting of a capacitor **48** and a primary winding **60** for the transformer **56** is connected in the collector circuit of the power transistor **54**, and is variably tuned to the approximate resonant frequency of the transducer **38**. A resistor **62** is connected between the power source and the base of the power transistor **54** to place an initial bias current to the base to aid in starting oscillation.

As the power transistor **54** conducts, the top side of a secondary winding **64** for the transformer **56** becomes positive and causes current to flow in the drive coils **42** for the transducer **38**. A capacitor **66** connected across the secondary winding **64** and the drive coils **42** tunes the transducer to eliminate some of the higher harmonics.

The positive going voltage from the drive coils **42** during conduction of the power transistor **54** is coupled by the feedback circuit **36** including a resistor **68**, a capacitor **70**, and a diode **72** to the base of a transistor **74**. A base resistor **76** connected between the power supply and the diode **72** is used to provide an initial bias current to the base of the transistor **74** to aid in initiating oscillation thereof and to provide a leakage path for the base current. A positive voltage to the base of the transistor **74** initiates conduction of the transistor which brings the collector voltage thereof to near zero volts. The collector circuit for this transistor includes a tank circuit consisting of a capacitor **78** and the primary winding **80** of a variable transformer **82**. As the collector voltage of the transistor **74** goes to near zero volts, a secondary winding **84** of the transformer **82**, which is connected to the base of the power transistor **54**, causes a positive voltage to be applied to the base of the power transistor and increases conduction thereof until saturation is reached. As the power transistor saturates, the conduction of the transistor **74** decreases thereby decreasing the conduction of the power transistor, and this process continues until both the power transistor and transistor **74** are turned off. The oscillatory nature of the tank circuits coupled to the collectors of the power transistor and the transistor **74** with the oscillatory nature of the transducer **38** causes this process to repeat, thereby driving the transducer at its resonant frequency. The power transistor **54** and the transistor **74** normally operate in a Class C mode.

A diode **86** and a capacitor **88** connected between the secondary winding **84** and ground provide a return

path for the base current for the power transistor **54** while providing a high impedance for the bias current supplied through the resistor **62.** Since the magnetostrictive transducer **38** is operable at several resonant frequencies, the tank circuit (**78** and **80**) in the feedback system **36** provides additional tuning to insure that the circuit operates at the predominant resonant frequency.

The basic horn **46** is quite adaptable to modification to facilitate enhanced fuel dispersion. For example, fuel may be fed through the horn to the active surface **48** as illustrated in FIGS. **4** and **5.** To accomplish such internal fuel feed, the horn is not a solid horn of the type illustrated in FIG. **2,** but instead includes a fuel inlet **90** which extends substantially perpendicular to the longitudinal axis of the horn. Fuel inlet **90** is formed in the enlarged portion **50** of the horn and communicates with the internal end of a fuel conduit **92** which extends longitudinally of the enlarged portion of the horn and exits through the tapered portion **52** thereof. Coextensive with the conduit **92** is a groove or channel **94** which extends along the top of small cylindrical horn section **51** and terminates at the active surface **48.** The conduit **92** and channel **94** receive a length of tubing **98** which is inserted into the conduit **92** so as to communicate with the inlet **90.** The tubing **98** must be formed of a non-sound absorbing material such as Teflon, so as not to interfere with the operation of the horn **46,** and the end of the tubing adjacent the active surface **48** must terminate a short distance inwardly from the end of the channel **94** as indicated at **100.** It has been found that enhanced dispersion of fuel as minute droplets occurs only if a thin film of fuel is maintained across the extent of the active surface **48.** Fuel must be provided to the active surface in a manner which will permit the fuel to pass across the extent of the active surface from one outer extremity to the opposite outer extremity thereof as a thin film. It has been noted that if the tubing **98** terminates at a point which is even with the active surface **48,** large droplets of fuel conducted by the tubing tend to "skate" across the thin film of fuel formed upon the active surface and are thrown into the carburetor air stream. These large droplets are not properly dispersed and therefore reduce the efficiency of fuel combustion.

By positioning the tube **98** within the channel **94** inwardly from the active surface **48,** fuel spreads across the active surface to form an effective thin film and large droplets thereof are not permitted to skate across the active surface. To prevent the air stream passing through the carburetor from driving the fuel from the active surface **48** before adequate atomization thereof, a shroud **102** is secured above the active surface to divert the carburetor air stream. It should be noted that this shroud may be mounted upon the housing of the carburetor **12** or the shroud may be mounted directly on the horn **46.** If the shroud is mounted on the horn, it must be formed of material which will not interfere with the sonic activity of the horn.

The horn **46** must be securely mounted in a manner which will not interfere with the sonic activity of the horn. This is accomplished by making all mounting and fuel connections to the horn in an area of the enlarged section **50** thereof where a sonic null occurs. In the area of this sonic null, the inlet **90** may be formed and a fuel supply tube **104** connected to provide fuel to the inlet. This fuel supply tube should be formed of non-sound absorbing material and may be secured to the horn in any suitable known manner so as not to interfere with the sonic characteristics of the horn. Since the supply tube is connected to the horn in the vicinity of a sonic null point, the connection between the horn and the supply tube will not be subjected to sonic energy which would tend to break the connection.

The mounting of the horn should also occur at the sonic null point and requires that a non-sound absorbing material be the only mounting material in contact with the surface of the horn. Thus, mounting may be achieved by employing an O-ring **106** of non-sound absorbing material which encircles the enlarged portion of the horn at the null point and which is compressed between a mounting bracket **108** and a clamp **110.** Compression of the "O" ring causes the O-ring to securely grip the horn to provide an effective mounting therefore which will not affect the sonic activity of the horn.

When the horn **46** is designed to conduct fuel to the active surface **48,** it is important that the fuel supply conduits be designed so that a thin film of fuel is maintained across the active surface of the horn. The fuel supply to such active surface should be provided adjacent one extremity thereof so that the fuel is caused to pass across substantially the entire extent of the active surface. Very large fuel outlets in the center of the active surface of the horn have been found to destroy some of the sonic effectiveness provided by the horn, for the greatest area of sonic activity is found at the center of the active surface. Fuel provided at the center of the active surface of the horn undergoes incomplete atomization and very large droplets may be thrown off the air stream by high flow rates.

Once a thin film of fuel has been formed across the active surface of the horn, it is desirable to prevent large droplets of fuel from skating across the film and being thrown off into the air stream to the intake manifold before proper atomization occurs. It has been found that a radical change in flow rate, as for example, from idle speed to the running speed, may tend to cause large droplets of fuel to be thrown from the horn into the intake manifold air stream unless some type of fuel feed control is provided. A horn system designed to provide fuel feed control as the engine operation changes from an idle condition to a running speed condition is illustrated in FIGS. **6–9.** This horn will provide effective control when direct fuel feed from a fuel pump is employed and will provide very effective control when employed in combination with the fuel computer **24.**

With no external fuel control system, when fuel is conducted through the horn **46** to a single fuel opening or a plurality of fuel openings of equal size, the fuel flow will change as the engine changes from an idle condition to a running condition. Thus, if the fuel opening at the active surface is relatively large, high engine RPM during a running condition will prevent fuel from shooting out beyond the active surface and a fuel film will be maintained across the active surface to achieve effective atomization. However, with the same relatively large fuel openings, when the engine slows to idle, fuel in the horn and line will fall from the end of the horn into the air stream.

If the fuel openings in the active surface **48** of the horn are relatively small, an effective fuel film will be maintained across the active surface during engine idle.

However, when the engine is in a running speed condition, the increased air flow and fuel pressure will cause fuel to shoot from the small openings at the active surface outwardly into the air stream without properly contacting the active surface. To prevent these conditions which may become prevalent when no external fuel control is employed, a dual fuel feed for the horn **46** of the type illustrated in FIG. **6–9** may be used.

Referring to FIGS. **6** and **7**, it will be noted that the active surface **48** of the horn **46** is provided with a plurality of large fuel openings **112** and a plurality of small fuel openings **114**. Since the large fuel openings will supply larger droplets of fuel, these fuel openings are positioned closer to the outer extremity of the active surface **58** than are the smaller fuel openings. However, both the fuel openings **112** and **114** should be positioned as close as possible to the outer extremity of the active surface which is the up stream extremity with relation to the flow of air to the engine intake manifold, and may be much smaller than depicted, for illustration purposes, in FIG. **5–9**.

To supply fuel to the fuel openings **112** and **114**, the horn **46** includes two separate fuel conducting paths. The fuel conducting path for the larger fuel openings includes fuel inlet **90***a* extending into the horn in the null area of the enlarged portion **50** thereof to communicate with a longitudinally extending fuel conduit **116**. The fuel conduit **116** extends to the smaller portion **51** of the horn and terminates in a plurality of branch conduits **118** which supply the fuel apertures **112**.

Similarly, a fuel inlet **90***b* extends to a second longitudinal fuel conduit **120** which terminates in a plurality of branch conduits **122** connected to supply fuel to the individual small fuel apertures **114**. For ease of construction, the branch conduits **118** and **122** may be eliminated and the main conduits **116** and **120** may extend directly to separate fuel supply channels behind the fuel openings **112** and **114**.

To alternate the fuel paths to the active surface **48** from a supply line **124** connected to the fuel pump **20**, a control valve **126** may be employed. This control valve may constitute any suitable known control valve which is operative in response to either an electrical or mechanical control input to switch the fuel flow from the line **124** to either the input line **104***a* or **104***b*. The fuel input line **104***a* is connected to the fuel inlet **90***a* while the fuel input line **104***b* is connected to the fuel inlet **90***b*.

For purposes of illustration, the valve **126** is shown in FIG. **8** as an electrically controlled valve which operates in response to an electrical signal on the electrical input line **128**. Thus, when the engine which is to receive fuel from the horn **46** is at idle, the valve **126** supplies fuel to the line **104***b*, while when the engine changes to running speed, the valve **126** supplies fuel to the line **104***a*. The control signal on the line **128** for the valve **126** may be derived from an RPM sensor, from a microswitch connected mechanically to the accelerator system for the engine, or from any other sensor adapted to indicate a shift from an idle to a running speed condition. Conceivably, this sensor could also constitute a pressure sensor adapted to sense manifold pressure.

Although plural fuel outlets in the active surface **48** of the horn **46** are desirable, these could be replaced by a single large outlet **112** combined with a single small outlet **114**. Also, the fuel supply tube **98** of FIG. **5** could be employed in combination with a small fuel outlet **114** as illustrated in FIG. **9** or a plurality of small fuel outlets **114** of the type shown in FIG. **7**. With all of these embodiments, the fuel flow control system of FIG. **8** would be employed.

With the horn embodiments of FIGS. **6–9**, fuel will be supplied from the small fuel openings **114** when the engine receiving the fuel supply is at idle and the fuel velocity is low, and therefore large droplets of fuel will not be permitted to drop over the active surface **48**. The fuel from the openings **114** will spread out around the openings to form an effective fuel film, for the pressure differential created by the intake manifold at idle is not of sufficient magnitude to cause the fuel to jet from the openings **114** away from the active surface. When the engine shifts to running speed, fuel will be provided from the larger openings **112** or the single large opening **98** (FIG. **9**) and will again be caused to spread across the active surface **48**. These larger fuel openings are of sufficient size to prevent fuel from jetting away from the active surface under the influence of the increased air velocity at running speed, but this increased velocity of air flow will drive the fuel against the active surface of the horn. Also the larger volume of fuel requires additional surface contact for complete atomization, and thus the fuel openings **112** are closest to the outer extremity of the active surface **48**.

Fuel fed directly through the horn **46** has the desirable advantages of providing inherent cooling for the horn as well as a unitary fuel supply and sonic system. However, the added expense of providing fuel channels in the horn structure may not be necessary in instances where an external fuel computer is employed. In these situations, the solid horn of FIG. **2** combined with separate fuel injectors as illustrated by FIG. **10** may be utilized.

The sonic fuel injector system of FIG. **10** is designed for use with conventional internal combustion engine carburetor systems without requiring carburetor modification. This system is a low profile system which may be mounted in the space beneath the conventional automotive or truck carburetor between the carburetor and the intake manifold. For this purpose, a special carburetor plate **130** may be employed which is provided with an opening **132** for the air flow from the carburetor plus suitable mounting means for one or more fuel injector nozzles **134**. Also the mounting plate **130** may be provided with an opening to receive the small end **51** of the horn **46**, the remainder of the horn being suitably mounted as illustrated in FIG. **4**. Also, a shroud **136** to protect the active surface **48** of the horn from the air stream may be mounted on the mounting plate **130** or may be secured directly to the horn as previously described.

In the system illustrated by FIG. **10**, fuel flow controlled by an external fuel computer is provided to the injector nozzle **134** which then directs the fuel on to the active surface **48**. This causes the fuel to form a film across the extent of the active surface between the upstream and downstream extremities thereof. When two fuel injector nozzles are employed as illustrated in FIG. **10**, both nozzles are positioned to direct fuel against the upstream outer extremity of the active surface and fuel is alternatively provided through such injector nozzles at slow engine speeds. As the engine speed increases, both injector nozzles will simultaneously apply fuel to the active surface for a portion of the pulse pe-

riod. This period of simultaneous injection increases as engine speed increases.

FUEL COMPUTER

The fuel computer indicated generally at **24** (FIG. **11**) is a hybrid circuit designed to meter the proper amount of fuel to the active surface **48** of the horn **46.** The active surface atomizes the fuel for more uniform mixing with air to minimize combustion pollution products due to an overly rich or overly lean mixture. To produce an optimum combustion, the air-fuel ratio should be such that the fuel is completely burned with a minimum of carbon monoxide due to incomplete combustion and a minimum of unburned hydrocarbons being emitted in the combustion by-products.

To satisfy the above criteria in an internal combustion engine, the air-fuel ratio should be maintained at a given level for all operating conditions of the engine. The volume of air required by the engine is proportional to the intake manifold pressure and engine speed and inversely proportional to the air temperature. As the air temperature increases, the quantity of air in a given volume decreases, while as the engine speed increases, the volume of air increases proportionately assuming the intake manifold pressure and air temperature remain constant.

The fuel computer **24** of FIG. **11** may be employed with any of the sonic horn systems disclosed by FIGS. **4–10.** In the systems of FIGS. **4–9,** the fuel computer operates a single injector valve which controls the flow of fuel to the horn. In FIGS. **4** and **5,** this single injector valve will be placed in the line **104** while in the control system of FIG. **8,** the injector valve would be placed in the line **124.** In the system of FIG. **10,** a single injector valve would again be used if only one fuel injector nozzle **134** is employed, but in the case of multiple fuel injector nozzles, an injector valve will be utilized for each nozzle.

The fuel injector valve **22** may constitute a solenoid operated valve, and with a constant pressure on the fuel supply to the valve, the fuel delivered thereby is proportional to the length of time that the valve remains open. Thus, the fuel computer **24** is designed to supply an electrical control pulse to the injector valve **22** having a duration which is proportional to the intake manifold pressure and inversely proportional to the absolute temperature of the air with a repetition rate which is proportional to the engine RPM. Operating under these conditions, the fuel computer **24** will effectively maintain a substantially constant air-fuel ratio to the intake manifold.

The fuel computer **24** includes a pressure sensor **30** having an electrical transformer **138** with a coupling between the primary and secondary windings thereof which is varied in accordance with sensed pressure. An oscillator **140,** which may constitute a Wein Bridge oscillator, is coupled to drive the primary winding **142** of the transformer **138** at a constant frequency and amplitude. The secondary winding **144** of the transformer is polarized so that a secondary voltage is developed which is **180°** out of phase with that in the primary winding.

A portion of the primary voltage from the winding **142** is coupled through a variable zeroing circuit **146** to a resistive summing circuit **148.** The summing circuit is also connected to receive the secondary voltage from the secondary winding **144,** so that a portion of the primary voltage is added to the secondary voltage and the difference is amplified in a difference amplifier **150.** The zeroing circuit **146** is provided to adjust the difference between the primary and secondary voltage to zero at a predetermined vacuum (i.e. **20** inches of vacuum) present during engine idle conditions.

The output of the difference amplifier **150** is connected to a synchronous rectifier **152.** It will be noted that the synchronous rectifier is also connected to receive the output of the oscillator **140,** so that the synchronous rectifier rectifies the output from the difference amplifier in synchronization with the oscillator output. This is accomplished by driving two field effect transistors **154** and **156** alternatively with the oscillator output signal so as to short to ground the difference signal supplied from the difference amplifier **150** through an amplifier **158** to a respective one of the field effect transistors when such field effect transistor is conducting.

The rectified signal output from the synchronous rectifier **152** provides a negative voltage to the input of an amplifier and filter circuit **160** if the sensed pressure is greater than the zero setting set by the zeroing circuit **146** (i.e. **20** inches of vacuum). Also, in this case, the value of the negative input voltage to the amplifier and filter circuit is proportional to pressure.

If the pressure sensed is less than the zero setting set by the zeroing circuit **146** (less than **20** inches of vacuum) the input voltage to the amplifier and filter circuit will become positive and will be proportional to the pressure deviation from the zero setting. The amplifier and filter circuit operates to amplify and invert the input voltage thereto as well as to filter the ripple caused by the oscillator frequency.

The temperature sensor **28** may consist of a thermistor having a resistance which varies inversely in response to the sensed temperature. This temperature sensor may be mounted at any point within the engine where accurate sensing of engine air temperature may be achieved. The thermistor is connected to the voltage supply which may constitute an automotive **12** volt battery, and thus the voltage across the thermistor varies inversely with temperature. This thermistor voltage is amplified by an amplifier **162** and fed to a potentiometer **164** which provides the supply signal to an integrator **166.** This integrator is designed to range from minimum to maximum output voltage over a nominal time interval of ten milliseconds, and during this relatively short interval, temperature is assumed to remain constant since it is a slowly varying function. A reset pulse is provided by a line **168** to a reset transistor **170** which operates, in response to the reset pulse, to connect a positive voltage to the input junction **172** of the integrator. This drives the integrator output to a maximum negative value in a relatively short time period (less than 1 millisecond), and at the end of the reset pulse, the integrator output starts to increase in a positive direction at a rate depending upon the sensed temperature and the setting of the potentiometer **164.** This output from the integrator is fed simultaneously to a first comparator **174** and a second comparator **176;** the first comparator also receiving the output from the amplifier and filter **160.**

As the integrator output voltage passes a first voltage level (i.e. minus **8.75** volts), the output from the second comparator **176** changes from a full negative to a full positive output signal. The first comparator **174** will

switch from a maximum positive to a maximum negative output signal as the integrator output voltage passes a second more positive value. This second more positive value at which the output from the comparator **174** will switch to a full negative value depends upon the amplitude of the pressure signal obtained from the amplifier and filter **160** and the setting of an idle adjust potentiometer **178** which provides a reference voltage for combination with the pressure output signal and the temperature output signal from the integrator at a summing point **180.** This idle adjust potentiometer operates similar to a conventional choke, and may be manually or automatically adjusted to adjust the fuel input to the engine.

The outputs from the comparators **174** and **176** are fed to inputs **182** and **184** respectfully of a NAND gate **186** which operates in response thereto to provide pulses having a width which is proportional to pressure and inversely proportional to the temperature. The timing of the pulse output from the NAND gate is dependent upon a trigger signal applied to an input **188.** This trigger signal is derived from the RPM sensor **26** which provides pulses directly from the engine ignition system with a pulse repetition rate which is directly proportional to engine speed, so that a pulse occurs for each intake stroke. These pulses may be obtained from the ignition breaker points or from another suitable device such as a tachometer. The trigger pulse from the input **188** is coupled through a buffer amplifier **190** to a JK flip flop **192.** Each input pulse from the buffer amplifier causes the flip flop to change binary state in a known manner so that the output of the flip flop repeats for each alternate input pulse. The outputs from the flip flop **192** are connected to NAND gates **194** and **196** respectively, and these NAND gates also receive the reset pulse from the buffer amplifier **190.** It will be noted that the output from the NAND gate **196** provides the reset pulse for the integrator **166,** and thus provides the timing for the pulses at the output of the NAND gate **186.** Since these reset pulses are derived from the ignition system, the pulse repetition rate of the pulses at the output of the NAND gate **186** is directly proportional to engine speed.

The output pulses from the NAND gate **186** are connected to a power amplifier **198** which provides an amplified drive pulse to the solenoid coil **200** of the solenoid operated injector valve **22.** The time duration during which the drive pulse from power amplifier **198** energizes the solenoid coil **200** to open the solenoid injector valve determines the amount of fuel which is fed either to the horn fuel inlet of FIGS. **4–9** or to an injector nozzle **134** of FIG. **10.** In the single valve systems of FIGS. **4–9** and in the event that only a single injector nozzle is employed in connection with the system of FIG. **10,** the flip flop and NAND gates **194** and **196** may be eliminated and the output from the amplifier **190** is then directly fed as a reset pulse to the reset transistor **170.** This will result in one pulse of fuel being provided by the injector valve **22** for each intake stroke of the engine.

In systems similar to that illustrated in FIG. **10** wherein two injector nozzles are employed, the output of the NAND gate **194** is applied as a reset pulse to a duplicate integrator, comparator, power amplifier and injector system **202** which is identical to that illustrated in detail in FIG. **11.** Since the reset pulses from the NAND gates **194** and **196** are provided alternatively, the injector valve **22** and that of alternate system **202** in FIG. **11** are driven in an alternative manner so that fuel is provided to the injection nozzles in FIG. **10** alternatively. This mode of operation also gives one pulse of fuel for each intake stroke of the engine and allows pulses to overlap if required.

Pulses will overlap at higher engine speeds, so that as the engine speed increases, both injector nozzles in FIG. **10** will simultaneously supply fuel to the active surface **48** for longer time periods. The ultrasonic atomization does not occur instantaneously, so that the pulses of fuel are atomized over a longer period of time, thereby providing a more uniform fuel-air mixture than can be obtained without the atomization.

The power amplifier **198** is designed to delay the opening of the injector valves **22** for a set delay period (i.e. **1.5** milliseconds) after a pulse is received from the NAND gate **186** and to delay the closing of the injector valve to achieve closing thereof for an equal delay period after the input pulse from the NAND gate **186** ceases. With this delay in the opening of the injector valves, the fuel may be completely shut off automatically when the intake manifold vacuum exceeds a desired point (i.e. **25** inches of vacuum). This condition exists when the engine RPM is relatively high (greater than **1500** RPM) and the throttle is closed. The advantage of shutting off the fuel at this point is to eliminate the emission of unburned hydrocarbons during engine deceleration and to achieve downhill engine braking.

The power amplifier delay system includes a variable resistor **204** connected in the output circuit of the amplifier **198** and in series with the solenoid coil **200.** This resistor may be adjusted to vary the time required for the current from the amplifier **198** to reach an amplitude sufficient to open the solenoid injector valve.

Similarly, when the pulse output from the amplifier **198** is terminated, the inductance of the coil **200** and the resistance of the variable resistor **204** in series with a resistor **206** determines the time required for the coil current to decay through a diode **208.** It will therefore be apparent that at high engine RPM when the throttle is closed, the pulse width from the amplifier **198** will decrease into the delay period set by the variable resistor **204,** and thus the solenoid coil **200** will never be energized to open the solenoid valve. The duration of the delay period may be adjusted by adjusting the variable resistor **204.**

It will be obvious that the conventional engine control mechanisms will vary the engine condition sensed by the fuel computer **24** to cause a responsive variation in fuel flow. For example, the throttle plate **15** which moves under the control of a conventional throttle mechanism alters the pressure sensed by the pressure sensor **30.**

For some applications, it may be desirable to mix several distinct substances in a controlled manner through the use of the fuel computer **24** and an associated sonic fuel dispersion unit **32.** For purposes of description, the substances to be mixed will be considered to be fuel substances, although it is obvious that any liquid substance, and also some powdered substances could be similarly mixed. In the case of two liquid fuels to be mixed, a unit similar to that illustrated by FIGS. **10** and **11** could be employed with separate fuel injector nozzles **134** being adapted to conduct individual components of the ultimate mixture to the active surface **48** of the horn **46.** In the case of a two substance mixture,

one injector nozzle **134** would be controlled by the injector valve **22** and the solenoid coil **200** while the second injector nozzle would be controlled by the injector valve in the duplicate integrator, comparator, power amplifier and injector system **202.** The injector valve **22** would be inserted in a line between a supply for the first fuel substance and the associated injector nozzle **134** while the injector valve in the duplicate system **202** would be inserted in a separate line between the supply for a separate fuel substance and the associated injector nozzle **134.** Thus two separate substances could be conducted and mixed at the active surface **48.**

If two separate fuel substances are to be mixed under the control of the fuel computer **24,** it may be desirable to mix these substances in some predetermined ratio. To accomplish this, the idle adjust potentiometer **178** would be connected only to the summing point **180,** and a separate idle adjust potentiometer would be connected in an identical manner to the duplicate system **202.** (See FIG. **16**). In FIG. **16,** the components of duplicate **202** are designated by the reference numerals of FIG. **11** plus "a". With this structure, the duplicate system **202** could be caused to provide a different volume of a fuel substance to the active surface **48** of the horn **46** by setting the idle potentiometer **178***a* for the duplicate system at a setting different from that set on the idle adjust potentiometer **178.** In this manner, the ratio of fuel components issuing from the fuel injector nozzles **134** could be varied. Also the reset pulses to the integrators **166** and **166***a* might alternate if they originate at the JK flip flop **192** (FIG. **11**) or such pulses may pass simultaneously to the integrators **166** and **166***a* if the JK flip flop is eliminated as previously described.

It is obvious that the fuel computer **24** may be employed to operate in response to a wide variety of sensed conditions other than temperature, pressure, and engine RPM. The temperature, pressure, and RPM sensors disclosed in FIG. **1** and **11** could be replaced by any known transducer adapted to provide an electrical signal which is a function of a sensed condition, and thus the fuel computer is adaptable for universal use. For example, the fuel computer could be employed in combination with the sonic unit **32** to provide fuel to a furnace. In this case, temperature and pressure sensors would probably be used in connection with a pulse input which, instead of RPM, would indicate some furnace condition, such as the speed of the furnace blower. In this instance, a variable oscillator of some type might be employed to provide the pulse input to the fuel computer **24,** but for other applications, a fixed oscillator or pulse generator could be used.

It may not always be desirable for the fuel computer **24** to provide a variable pulse width output to open and close the injector valve **22** for a predetermined time. As an alternative, the fuel computer is easily modified to provide a variable pulse amplitude output which would vary the amount that the injector valve **22** would open, thereby varying the volume of fuel or other material passing through the valve. This variable amplitude output signal may be easily provided by inserting any well known pulsewidth to pulse amplitude converter either between the output of the NAND gate **186** and the input to the power amplifier **198** or, between the output of the power amplifier **198** and the input to the solenoid coil **200.** For example, as illustrated in FIG. **12,** an integrator **210** could be employed between the NAND gate **186** and the power amplifier **198** to convert the variable width pulses from the NAND gate into variable amplitude pulses which would vary the amount that the injector valve **22** is permitted to open.

With the use of the dual injector system of FIG. **10,** several modifications in the structure of the horn **46** are possible. For example, as illustrated in FIG. **13,** the active surface **48** of the horn may be divided into two subsections **48***a* and **48***b*, one for each fuel injector nozzle. These active surface subsections constitute flat surfaces formed at the end of the small cylindrical horn section **51** and angled to provide an apex at the center of the small cylindrical horn section at the terminus thereof. The flat subsection **48***a* is positioned to receive fuel ejected from one fuel ejector nozzle while the flat subsection **48***b* receives fuel ejected from the remaining fuel injector nozzle. It has been found that the fuel injector nozzles **134** may be placed at a number of angles with respect to an associated active surface subsection **48***a* or **48***b*, so that the force of the fuel impinging upon the subsection plus the drawing force provided by the sonic vibration of the horn **46** causes the fuel to be drawn along the active surface subsection and over the apex point at the end of the small cylindrical horn section **51.** The horn configuration of FIG. **13** is quite advantageous, for the complete active surface causes each fuel impulse to be atomized and directed toward the center of the airstream instead of one side alternately as does the horn of FIG. **10.**

In FIG. **14,** another modification of the sonic horn **46** is illustrated wherein the active surface **48** constitutes a conical area forming the terminus of the small cylindrical horn section **51** and having an apex at the center of the small cylindrical horn section. With this conical active surface **48,** fuel from the injectors **134** spreads to form a thin film of fuel over the entire active surface and the fuel is drawn off at the apex end thereof. This active surface configuration provides more surface area for the atomization of fuel.

As previously indicated, the sonic transducer **38** may constitute a piezoelectric transducer unit rather than a magnetostrictive transducer of the type disclosed in FIG. **2.** With reference to FIG. **15,** a piezoelectric transducer is bonded to the base of the horn **46** by a bonding material which will not materially affect the sonic capabilities of the combination but which will form a secure bond in the operating environment for the combination. For example, epoxy resin may be employed in some instances to bond the transducer to the horn, and in high temperature applications, a bonding material which will not soften in response to high temperatues must be employed. Positioned between the transducer and the horn are a plurality of spaced, thin shims **216** which contact both the base of the horn and the transducer. These shims may be located **120°** apart and perform two important functions. First, the shims are made to correspond to the desired thickness of the bond between the transducer and the horn. For example, if the bond is to be three one-thousandths of an inch in thickness, the shims are formed to this thickness to ensure a good uniform bond. Secondly, the shims are made of electrically conductive material and operate to conduct energizing current from the horn to the ceramic transducer. The horn is also formed of electrically conductive material so that electrical connection to an outside conductor may be made at **218** at the sonic null point on the horn. The electrical current for this electrical connection is then transmitted by the

body of the horn and the shims **216** to contact points on the ceramic transducer **214.**

Bonded to a surface of the ceramic transducer **214** opposite the horn **46** is a backup mass **220** which is preferably formed of a material which is denser than the material forming the horn and which operates to increase the efficiency of the sonic unit.

It will be readily apparent that the novel computer controlled sonic fuel system of the present invention offers a number of unique advantages not provided by conventional fuel systems. The present system requires only one fuel injector and accomplishes fuel injection before the intake manifold branches to the engine cylinders or, in the case of engines of other types, before the ccombustion area thereof, thus allowing a relatively long path for the air-fuel mixing action. The injector combined with a novel sonic system reduces fuel droplet sizes to provide droplets that may be carried in the air stream around corners and bends encountered in the intake manifold. This produces a more uniform quantity of fuel to each cylinder as compared to a conventional carburetor system or a single injector without atomization. Increased droplet sizes produced by such conventional systems have a greater mass and require more force to produce a given acceleration around a corner. In addition to the more uniform quantity of fuel to each cylinder, the fuel mixture produced by the subject system includes extremely small fuel droplets which have a much larger surface area for evaporation. Since the sonic system provides an effective lengthening of each fuel impulse provided by the respective injector valve, a more uniform feeding of fuel is obtained than can be obtained with conventional injector systems.

By employing computer controlled injection of fuel at a point between a carburetor air inlet and the point where an engine intake manifold branches to the individual engine cylinders, a relatively fail-safe fuel system is provided. For example, should the sonic unit **32** malfunction, this unit may be shut down while the fuel computer **24** still operates effectively to meter fuel through the sonic horn **46** of FIGS. **4–9** and **15** or through the injector nozzles **134** of FIGS. **10, 13,** and **14.** With the sonic unit deactivated, the sonic horn **46** operates effectively as a conventional fuel nozzle for the carburetor **12.**

Even more effective with the sonic unit **32** deactivated is the injector system of FIGS. **10, 13** and **14.** Here the active surface **48** of the horn **46** still functions to some extent as a passive fuel dispersion unit to disperse fuel into the airstream through the engine manifold. The pressure of the fuel issuing from the injector nozzles **134** against the now passive active surface **48** of the deactivated sonic unit, causes the fuel to spread across the active surface and disperse into the airstream. The effectiveness of this fuel dispersion by impingement of fuel against a passive dispersion surface may be controlled by varying the fuel pressure provided by the fuel pump **20.**

Should the fuel computer **24** malfunction, the fuel system of the present invention will operate effectively either with or without the sonic unit **32.** Thus, the computer may be deactivated, and fuel may still be provided by the fuel pump **20** to the horn **46** of FIGS. **4–9** and **15** or through the injector nozzles **134** of FIGS. **10,** 13 and **14** to the active surface **48.** Operation with the computer **24** deactivated may be accomplished in a number of ways. For example, a switch **222** (FIG. **11**) might be provided to close a power circuit for the injector valve **22** when the computer is deactivated. This shunt power circuit would cause the injector valve to remain open and pass fuel to the sonic unit **32.** Obviously, a bypass system for the injector valve **22** provided with a bypass valve actuated upon deactivation of the computer could be employed to provide fuel to the horn **46** or the injector nozzles **134.**

We claim:

1. In an internal combustion engine having an intake manifold, an air source for providing an airstream for entry into said intake manifold and a fuel source for said internal combustion engine, a computer controlled sonic fuel system for providing fuel from said fuel source to the airstream entering the intake manifold comprising sonic transducer means having an active surface mounted for receiving fuel and providing a fuel dispersion to said airstream to cause a fuel-air dispersion to be present at the entrance to said intake manifold, fuel computer means connected to receive fuel from said fuel source and to provide a fuel output which varies as a function of variations in the operating condition of said internal combustion engine, and fuel input means for delivering the fuel output from said fuel computer means to the active surface of said sonic transducer means, said fuel computer means operating to maintain a substantially constant fuel-air ratio to said intake manifold for all operating conditions of said internal combustion engine.

2. A computer controlled fuel system for providing fuel from a fuel source to an internal combustion engine comprising fuel input means connectable to supply fuel from said fuel source to said engine, said fuel input means including fuel control means to control the flow of fuel from said fuel source to said engine and fuel computer means connected to control the operation of said fuel control means to provide a fuel flow to said engine which varies as a function of variations in the operating condition of said engine, said fuel computer means including sensing means to sense engine RPM, temperature and manifold pressure, said sensing means operating to provide electrical engine speed pulses which are a function of engine RPM, a first electrical signal which is a function of manifold pressure, and a second electrical signal which is a function of engine temperature, and control signal generating means connected to receive and combine said electrical engine speed pulses and first and second electrical signals to provide an electrical control pulse output of electrical pulses having a pulse duration which is proportional to the intake manifold pressure and inversely proportional to the engine temperature with a repetition rate which is proportional to engine RPM, said electrical control pulse output being provided to control the operation of said fuel control means, said control signal generating means includes pressure circuit means to receive said first electrical signal and to provide a pressure output electrical signal which is a function thereof, reset circuit means operative to provide reset pulses in response to said electrical speed pulses, electrical integrator means connected to receive said second electrical signal and operative to provide an integrator output electrical signal which increases in amplitude above a reset point at a rate dependent upon the amplitude of said second electrical signal, said electrical integrator means being connected to receive said reset pulses and

operating in response thereto to return said integrator output electrical signal to the reset point and comparator circuit means connected to receive said pressure output electrical signal and integrator output electrical signal, said comparator means operating to provide said electrical control pulse output.

3. The computer controlled fuel system of claim 2 wherein said fuel control means includes electrically controlled valve means connected to receive fuel from said fuel source and control the flow thereof to said internal combustion engine, said electrically controlled valve means operating in response to said electrical control pulse output.

4. The computer controlled sonic fuel system of claim 3 wherein said electrically controlled valve means includes first and second injector valves, said fuel computer means operating to provide alternate electrical control pulses to said first and second injector valves.

5. The computer controlled fuel system of claim 4 wherein said reset circuit means is operative to provide a reset pulse for each intake stroke of said internal combustion engine in response to said electrical engine speed pulses, said reset circuit means operating alternatively to provide alternating reset pulses on first and second reset output lines, said integrator means including a first integrator means and a second integrator means connected to receive said second electrical signal and each being operative to provide said integrator electrical output signal, said first and second integrator means being connected to said first and second reset output lines respectively and operating respectively in response to reset pulses on the reset output line connected thereto to terminate the increasing integrator output electrical signal therefrom and return said integrator output electrical signal to said reset point, and said comparator circuit means includes first and second comparator circuit means connected to receive the integrator output signals from said first and second integrator means respectively and said pressure output electrical signal, said first and second comparator circuit means operating to provide said alternate electrical control pulses to said first and second injector valves respectively.

6. The computer controlled fuel system of claim 2 wherein said comparator circuit means includes a first comparator means connected to receive said integrator output electrical signal and operative to switch from a negative to a positive electrical output signal when said integrator output electrical signal reaches a first signal level, a second comparator means connected to receive said integrator electrical output signal and said pressure output electrical signal and operative to switch from a positive to a negative electrical output signal when the combined pressure and integrator output electrical signals reach a second signal level, and a gate circuit connected to receive the electrical output signals from said first and second comparator means.

7. The computer controlled fuel system of claim 6 wherein said second comparator means includes variable bias means connected thereto, said variable bias means being operative to vary said second signal level.

8. The computer controlled fuel system of claim 2 wherein said sensing means includes variable zeroing circuit means connected to receive said first electrical signal and operative to provide a difference output indicative of the difference between a reference signal and said first electrical signal, said variable zeroing circuit means being operative to adjust said difference output to zero at a predetermined idle pressure condition of said internal combustion engine and pressure output signal generating means connected to receive said difference output and to provide said pressure output electrical signal, said pressure output signal generating means operating to provide a pressure output electrical signal of a first voltage sense which is proportional to the sensed manifold pressure when said sensed manifold pressure exceeds said predetermined idle pressure condition and to provide a pressure output electrical signal of a second voltage sense which is opposite to said first voltage sense and is proportional to the manifold pressure deviation from said predetermined idle pressure condition when said sensed manifold pressure is less than said predetermined idle pressure condition.

9. In an internal combustion engine having an intake manifold, an air source for providing an airstream for entry into said intake manifold and a fuel source for said internal combustion engine, a computer controlled sonic fuel system for providing fuel from said fuel source to the airstream entering the intake manifold comprising a single sonic transducer means having an active surface mounted for receiving fuel and providing a fuel dispersion to said airstream to cause a fuel-air dispersion to be present at the entrance to said intake manifold, fuel computer means connected to receive fuel from said fuel source and to provide a pulsed fuel output including variable fuel pulses which vary as a function of variations in the operating condition of said internal combustion engine, and fuel input means for delivering the variable fuel pulses from said fuel computer means to the active surface of said sonic transducer means, said sonic transducer means operating to convert said variable fuel pulses into a substantially non-pulsating fuel-air mixture.

10. The computer controlled sonic fuel system of claim 9 wherein said variable fuel pulses are of substantially constant amplitude and of varying duration.

11. The computer controlled sonic fuel system of claim 9 wherein said variable fuel pulses are of varying amplitudes.

12. The computer controlled sonic fuel system of claim 9 wherein said fuel computer means provides an output fuel pulse for each intake stroke of said internal combustion engine.

13. The computer controlled sonic fuel system of claim 9 wherein said fuel computer means includes sensing means to sense engine RPM, temperature and manifold pressure, said fuel computer means operating to provide fuel pulses having a repetition rate which is proportional to engine RPM and a duration which is proportional to intake manifold pressure and inversely proportional to engine temperature.

14. The computer controlled sonic fuel system of claim 13 wherein said sensing means operates to provide electrical engine speed pulses which are a function of engine RPM, a first electrical signal which is a function of manifold pressure and a second electrical signal which is a function of engine temperature, said fuel computer means operating to combine said electrical speed pulses and first and second electrical signals to provide an electrical control pulse having a duration which is proportional to the intake manifold pressure and inversely proportional to the engine temperature

with a repetition rate which is proportional to engine RPM.

15. The computer controlled sonic fuel system of claim 14 wherein said fuel computer means includes electrically controlled valve means connected to receive fuel from said fuel source and control the flow thereof to said fuel input means, said electrically controlled valve means operating in response to said electrical control pulses.

16. The computer controlled sonic fuel system of claim 15 wherein said electrically controlled valve means includes first and second injector valves, said fuel computer means operating to provide alternate electrical control pulses to said first and second injector valves.

17. In an internal combustion engine having an intake manifold, an air source for providing an airstream for entry into said intake manifold and a fuel source for said internal combustion engine, a computer controlled fuel system for providing fuel from said fuel source to the airstream for the intake manifold at a point before said intake manifold reaches the combustion area for said engine comprising fuel input means connected to supply fuel from said fuel source to said airstream at a point before said intake manifold reaches the combustion area of said engine, said fuel input means including fuel dispersion means having at least one fuel receiving surface for receiving fuel and providing a fuel dispersion to said airstream, said fuel dispersion means being mounted at a point adjacent the path of said airstream, means for directing fuel onto said fuel receiving surface said fuel receiving surface being formed to redirect said fuel toward the center of the airstream, fuel control means to control the flow of fuel from said fuel source to said fuel directing means and fuel receiving surface, and fuel computer means connected to control the operation of said fuel control means to provide a fuel flow to said fuel receiving surface which varies as a function of variations in the operation of said internal combustion engine.

18. The computer controlled fuel system of claim 17 wherein said fuel input means includes injector means which operates to direct fuel under pressure against said fuel receiving surface to cause dispersion of fuel from said fuel receiving surface, said fuel receiving surface being static.

19. The computer controlled fuel system of claim 17 wherein said fuel input means provides fuel under pressure from said fuel source to said fuel directing means, said fuel directing means operating to direct fuel under pressure against said fuel receiving surface.

20. The computer controlled fuel system of claim 19 wherein said fuel receiving surface is conical in configuration with an apex extending toward said airstream.

21. The computer controlled fuel system of claim 19 wherein said fuel directing means includes at least two fuel injector nozzles positioned to direct fuel onto said fuel dispersion means, said fuel dispersion means including a first flat surface section to receive fuel from a first of said fuel injector nozzles and a second flat surface section to receive fuel from a second of said fuel injector nozzles, said first and second flat surface sections being inclined to form a central apex extending toward said airstream.

22. The computer controlled fuel system of claim 17 which includes shroud means mounted above said fuel dispersion means to divert the airstream relative to said fuel dispersion means.

23. The computer controlled fuel system of claim 17 wherein said fuel source includes a first section for containing a first component and a second section for containing a second component, said fuel input means including a first input system for conducting said first component from said first section to said fuel dispersion means, said first input system including first control means to control the flow of said first component from said first section, and a second input system for conducting said second component from said second section to said fuel dispersion means, said second input system including second control means to control the flow of said second component from said second section to said fuel dispersion means, said fuel computer means operating to control said first and second control means to control the mixture of said first and second components at said fuel dispersion means.

24. The computer controlled fuel system of claim 23 wherein said fuel computer means includes ratio circuit means operative to vary the control of said first and second control means to fix and maintain a predetermined ratio between the first and second components at said fuel dispersion means.

25. The computer controlled fuel system of claim 17 wherein said fuel receiving surface is spaced laterally from the center of said airstream to direct fuel toward the center of said airstream at an angle relative to the direction of flow of said airstream.

26. The computer controlled fuel system of claim 17 wherein said fuel dispersion means includes sonic transducer means having an active vibrating surface which forms the fuel receiving surface, and said fuel directing means directs fuel under pressure onto said fuel receiving surface, said fuel receiving surface being formed to redirect fuel received from said fuel directing means toward the center of said airstream when said active vibrating surface is in either a vibrating or a static condition.

27. The computer controlled fuel system of claim 17 wherein said fuel receiving surface is spaced laterally from the center of said airstream to direct fuel toward the center of said airstream at an angle relative to the direction of flow of said airstream and shroud means are mounted above said fuel receiving surface to divert the airstream relative to said fuel receiving surface.

28. The computer controlled fuel system of claim 17 wherein said fuel dispersion means includes sonic transducer means having an active vibrating surface which forms the fuel receiving surface, and said fuel input means operates to separately provide first and second fuel components from said fuel source to the active vibrating surface of said sonic transducer means.

29. The computer controlled fuel system of claim 28 wherein said computer means operates to fix and maintain a predetermined ratio between the first and second components at said active vibrating surface.

30. The computer controlled fuel system of claim 17 wherein said fuel computer means operates to maintain a substantially constant fuel-air ratio to said intake manifold for all operating conditions of said internal combustion engine.

31. The computer controlled fuel system of claim 17 wherein said fuel dispersion means includes sonic transducer means having an active vibrating surface which forms said fuel receiving surface, said fuel re-

ceiving surface being spaced laterally from the center of said airstream and formed to reflect fuel received from said fuel directing means toward the center of the airstream at an angle relative to the direction of flow of the airstream when said active vibrating surface is in either a vibrating or static condition.

32. The computer controlled fuel system of claim **31** wherein said fuel computer means includes sensing means to sense RPM of said engine, engine temperature and manifold pressure, said fuel computer means operating to provide fuel pulses having a repetition rate which is proportional to engine RPM and a duration which is proportional to intake manifold pressure and inversely proportional to engine temperature.

33. The computer controlled fuel system of claim **32** wherein said fuel directing means includes at least two fuel injector nozzles positioned to direct fuel onto said fuel receiving surface, said fuel computer means operating to cause said fuel control means to alternately provide said fuel pulses to said fuel injector nozzles.

34. The computer controlled fuel system of claim **17** wherein said fuel computer means includes sensing means operative to provide electrical signals indicative of the operating condition of said engine, control signal generating means connected to receive said electrical signals from said sensing means and operative to provide electrical control pulses to control the operation of said fuel control means and deceleration control means operative to terminate fuel flow through said fuel control means upon deceleration of said engine from above a predetermined speed, said deceleration control means including delay means to delay said electrical control pulses.

35. The computer controlled full system of claim **34** wherein said control signal generating means provides electrical control pulses having a pulse duration which varies as a function of the operating condition of said engine.

36. The computer controlled fuel system of claim **17** wherein said fuel input means includes a fuel pump for supplying fuel under pressure from said fuel source to said fuel directing means and auxilliary control means connected to said fuel control means and operative to cause said fuel control means to pass fuel to said fuel directing means.

37. The computer controlled fuel system of claim **36** wherein said fuel dispersion means includes sonic transducer means having an active vibrating surface which forms said fuel receiving surface, said fuel receiving surface being formed to redirect fuel received from said fuel directing means toward the center of said airstream when said active vibrating surface is in either a vibrating or static condition.

38. The computer controlled fuel system of claim **17** wherein said fuel input means includes mounting means for said fuel directing means and fuel dispersion means secured between the entrance to said intake manifold and a source for the airstream to the intake manifold, said mounting means including an open ended chamber extending between said airstream source and the intake manifold for receiving the airstream from the source thereof and directing the airstream to the entrance to said intake manifold, said fuel dispersion means being mounted by said mounting means with said fuel receiving surface positioned within the chamber at a point adjacent the path of the airstream therethrough.

39. In an internal combustion engine having an intake manifold, an air source for providing an airstream for entry into said intake manifold and a fuel source for said internal combustion engine, a computer controlled fuel system for providing fuel from said fuel source to the airstream for the intake manifold at the entrance to the intake manifold before said intake manifold reaches the combustion area for said engine comprising fuel input means connected to supply fuel from said fuel source to said airstream at a point before said intake manifold reaches the combustion area of said engine, said fuel input means including fuel dispersion means having at least one fuel receiving surface for receiving fuel and providing a fuel dispersion to said airstream, said fuel dispersion means being mounted at a point adjacent the path of said airstream, means for directing fuel under pressure against said fuel receiving surface, said fuel receiving surface being formed to redirect fuel received from said fuel directing means toward the center of said airstream, fuel control means to control the flow of fuel from said fuel source to said fuel directing means, and fuel computer means connected to control the operation of said fuel control means to provide a fuel flow to said fuel receiving surface which varies as a function of variations in the operation of said internal combustion engine, said fuel computer means causing said control means to provide a pulsed fuel output including variable fuel pulses to said fuel directing means while operating to maintain a substantially constant fuel-air ratio to said intake manifold for all operating conditions of said internal combustion engine, said fuel dispersion means operating to convert said variable fuel pulses into a substantially nonpulsating fuel-air mixture at the entrance to said intake manifold.

40. The computer controlled fuel system of claim **39** wherein said fuel input means includes mounting means for said fuel directing means and fuel dispersion means secured between the entrance to said intake manifold and the source for said airstream to the intake manifold, said mounting means including an open ended chamber extending between said airstream source and the intake manifold for receiving the airstream from the source thereof and directing the airstream to the entrance of said intake manifold, said fuel dispersion means being mounted by said mounting means with said fuel receiving surface positioned within the chamber at a point adjacent the path of the airstream therethrough.

41. The computer controlled fuel system of claim **40** wherein said mounting means is formed by a substantially flat plate, said chamber being defined by an opening formed in said plate and extending therethrough, and air diversion means mounted upon said plate above said fuel receiving surface to divert the airstream through said chamber relative to the fuel receiving surface.

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