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(54) Title: COMPOSITIONS, METHODS AND SYSTEMS FOR EXTERNAL AND INTERNAL ENVIRONMENTAL SENSING

(57) Abstract: The present invention relates to compositions, methods and systems for environmental sensing. In particular, the present invention provides compositions, methods and systems for external and internal environmental sensing wherein the sensing provides ultrasonic wind detection sensing.

COMPOSITIONS, METHODS AND SYSTEMS FOR EXTERNAL AND INTERNAL ENVIRONMENTAL SENSING

FIELD OF THE INVENTION

The present invention relates to compositions, methods and systems for environmental sensing. In particular, the present invention provides compositions, methods and systems for external and internal environmental sensing wherein the sensing provides ultrasonic wind detection sensing.

BACKGROUND OF THE INVENTION

All shooters, whether they are police officers, soldiers, Olympic shooters, sportswomen and sportsmen, hunters, plinkers or weekend enthusiasts have one common goal: hitting their target accurately and consistently. Accuracy and consistency in shooting depend largely on the skill of the shooter and the construction of the firearm and projectile.

The accuracy of a firearm can be enhanced by the use of precisely-made components, including precisely-made ammunition, firearm components and target acquisition devices. It is well known in shooting that using ammunition in which the propellant weight and type, bullet weight and dimensions, and cartridge dimensions are held within very strict limits, can improve accuracy in shooting.

At very long ranges, in excess of 500 yards, however, the skill of the shooter and the consistency of the ammunition is often not enough to insure that the shooter will hit the target. As range increases, other factors can affect the flight of the bullet and the point of impact down range. One of these factors is "bullet drop". "Bullet drop" is caused by the influence of gravity on the moving bullet, and is characterized by a bullet path which curves toward earth over long ranges. Therefore to hit a target at long range, it is necessary to elevate the barrel of the weapon, and the aiming point, to adjust for bullet drop.

Other factors, such as wind, Magnus effect (i.e., a lateral thrust exerted by wind on a rotating bullet whose axis is perpendicular to the wind direction), projectile design, projectile spin, Coriolis effect, and the idiosyncrasies of the weapon or projectile can change the projectile's

path over long range. Such effects are generally referred to as "windage" effects. Therefore, for example, to hit a target at long range, it may be necessary to correct for windage by moving the barrel of the weapon slightly to the left or the right to compensate for windage effects. When shooting East and West the elevation will be effected. Shooting due East, the bullet impact will be high. Shooting due West, the bullet impact will be low. The elevation at extended range might change slightly up or down depending on the spin of the projectile in a right hand or left hand twist barrel. Thus, for example, in order to hit a target at long range, the shooter must see the target, accurately estimate the range to the target, estimate the effect of bullet drop and windage effects on the projectile, and use this information to properly position the barrel of the firearm prior to squeezing the trigger.

In addition, conventional telescopic target acquisition devices are not generally useful at long ranges in excess of 400-800 yards. At close ranges less than 100 yards conventional target acquisition devices generally fall short when extreme accuracy is desired. The cross-hairs of such target acquisition devices are typically located in the center of the field, with the vertical hair providing a central indicator for making a windage adjustment, and the horizontal hair providing a central indicator for making a bullet drop adjustment. Modifications to this basic system have not, thus far, enabled a skilled shooter firing at long ranges to acquire and hit a target quickly and reliably, regardless of the weapon used (assuming always that the firearm is capable of reaching a target at the desired long range).

For example, U.S. Pat. No. 1,190,121 to Critchett, discloses a reticle for use in a rifle scope containing a rangefinder having markings for finding a range with reference to the height of a man. Apparently because of the innate variation in the height of any given individual from that used to produce the reticle, and the resulting inaccuracy which that would produce at long ranges, Critchett's scope was only useful to 600 yards.

U.S. Pat. No. 3,948,587 to Rubbert discloses a reticle and telescope gunsight system having primary cross-hairs which intersect conventionally at the center of the field, and secondary horizontal cross-hairs spaced apart by different amounts to form a rangefinder and distinct aiming apertures and points, based upon a predetermined, estimated size of a target. Rubbert's preferred embodiment is constructed for use in shooting deer having an 18" chest depth. However, like Critchett, the usefulness of Rubbert for shooting other targets of varying size at long range is doubtful.

U.S. Pat. No. 3,492,733 to Leatherwood discloses a variable power scope having aiming cross-hairs and two upper cross-hairs for bracketing a target of known dimensions at a known distance. The scope is mounted to a gun barrel, and the position of the scope in relation to the gun barrel is adjustable up and down to compensate for bullet drop by covering the target with the bracketing cross-hairs, and rotating an adjustment ring to expand or contract the bracketing cross-hairs to bracket the target. Leatherwood's scope, like the others discussed above, has limited utility at long ranges because it is designed with a specific size target in mind, and would therefore be inaccurate when used with targets of widely varying size, and also because at long range the scope may not be able to move sufficiently in relation to the barrel (i.e., may be obstructed by the gun barrel).

U.S. Pat. No. 4,403,421 to Shepherd discloses a scope having a primary and secondary reticles, the secondary reticle being a polygonal reticle with different indicia on the different faces which can be rotated into position to compensate for bullet drop and determining target range for different sized targets. However, having to rotate a secondary reticle to locate an appropriate target shape in order to determine the range is time consuming and undesirable, since it takes the shooter's attention away from the target.

It should be noted that the range finding inaccuracies inherent in these prior art references may be resolved using a laser rangefinder or highly accurate optical rangefinder. However, since a laser rangefinder emits light, there is always the possibility that the beam from a laser rangefinder could be detected by an individual with special equipment, revealing the position of the shooter, causing a live target to move, or other undesirable consequences for the rifleman using the laser before the shot can be taken. Furthermore, a laser rangefinder includes complex electronics which must be handled with care. Laser rangefinders require a reflective target to achieve consistently accurate range. Finally, a laser rangefinder must be powered with electricity from a source which must be carried by the shooter. The additional weight is a burden, and the possibility exists that power source could fail or become exhausted through use, causing the rangefinder to cease working.

Accordingly, the need exists for a target acquisition device having a reticle which includes, for example, an optical rangefinder which permits a skilled shooter to rapidly and accurately identify the range to any target of known or estimable size, no matter how large or small, to

make fast and accurate adjustment for projectile drop and windage, using the shooter's knowledge and experience and without the need to move rings or make adjustments (i.e. through the elevation and windage knobs) to the target acquisition device, thus enabling the shooter to accurately hit targets at any range, depending upon the gun handling skills and eyesight of the shooter, and the maximum range of the selected firearm, and the selected ammunition. The shooter never has to take her or his eye off the target acquisition device from the time the shooter spots the target and determines range, using the proper grid line to accurately engage and hit the target. Reticles of the present invention allow the rifle to be zeroed, for example, at 100 yards, or 100 meters, or more, and yet be able to engage targets very accurately as close as 20 yards.

SUMMARY OF THE INVENTION

In one embodiment, the present invention provides ballistics calculator system for computing targeting information to hit a target, comprising a processor, the processor comprising: a ballistics computer program for analyzing information needed to accurately aim a firearm at a target using a target acquisition device with a reticle, the program using information regarding one or more of: a) external conditions; b) the firearm being used; c) the projectile being used; d) the target acquisition device and reticle being used; e) the shooter; f) the relation of the shooter and the target; g) the directional sensor being used; and h) the ballistics drag model and retardation coefficient being used, wherein the information regarding external conditions comprises wind speed information provided by an ultrasonic wind detector.

The present invention provides reticles that provide means for selecting secondary aiming points that accurately target an intended target at any desired range, including extreme distances. In particular, the reticles of the present invention provide markings or other indications that allow a user, for example, to associate a first aiming point of the reticle with an intended target (e.g., the aiming point created by the cross-section of primary vertical and horizontal cross-hairs), and to identify a second aiming point (e.g., identified by a generated aiming dot, an electronic aiming dot, or an aiming point created by secondary vertical and/or horizontal cross-hairs) that represents a point to insure an accurate shot to hit the target.

In one embodiment, the present invention provides a reticle for use in any target acquisition device, fixed power scope or a variable power telescopic gunsight, image amplification

device, or other aiming device. In some embodiments, the reticle comprises a substantially transparent disc, although the present invention is not limited to the use of disc shaped reticles, or to substantially transparent reticles, or to electronically generated reticles.

In some embodiments, the reticle has an optical center and an edge for mounting said reticle in a housing (for example, between an objective lens and the ocular lens of a scope), one or more aiming points positioned on said reticle, wherein the aiming points are formed by a primary vertical cross-hair intersecting the optical center of the reticle, a primary horizontal cross-hair intersecting said primary vertical cross-hair to form an upper right sector (e.g., quadrant), an upper left sector, a lower right sector, and a lower left sector, a plurality of secondary horizontal cross-hairs at a predetermined distance along said primary vertical cross-hair, and a plurality of secondary vertical cross-hairs at a predetermined distance along at least some of said secondary horizontal cross-hairs. The crosshairs may be of any length, width and may comprise contiguous lines or may have gaps. In some embodiments, the secondary horizontal and vertical crosshairs comprise intersecting continuous lines so as to form a grid.

In one embodiment, unique markings (for example, numbers) identify at least some of the secondary cross-hairs. In a further embodiment, the primary horizontal cross-hair intersects that primary vertical cross-hair at the optical center of the reticle. In another embodiment, the primary horizontal cross-hair intersects that primary vertical cross-hair below the optical center of the reticle. In a preferred embodiment, the primary horizontal cross-hair intersects that primary vertical cross-hair above the optical center of the reticle. In a yet further embodiment, the plurality of secondary horizontal cross-hairs are evenly spaced at a predetermined distance along the primary vertical cross-hair. In another embodiment, at least some of the secondary horizontal cross-hairs are unevenly spaced at a predetermined distance along the primary vertical cross-hair. In a still further embodiment, the plurality of secondary vertical cross-hairs are evenly spaced at a predetermined distance along at least some of the secondary horizontal cross-hairs. In another embodiment, at least some of the secondary vertical cross-hairs are unevenly spaced at a predetermined distance along the primary horizontal cross-hair. In yet another embodiment, the reticle additionally includes range-finding markings on the reticle. The range finding markings may be in one of the sectors formed by the primary vertical and horizontal cross-hairs, or may be on the primary vertical or horizontal cross-hairs. In some embodiments, the primary or secondary crosshairs

themselves are used as range-finder markings.

In still further embodiments, the reticle is optionally illuminated for day use, for twilight use, for night use, for use in low or absent ambient light, or for use with or without night vision. In yet a further embodiment, illuminated dots at, for example, even or odd Mil Radian spacing are separately illuminated in the shooter's field of vision.

In a preferred embodiment, the reticle of the present invention is constructed from an optically transparent wafer or electronically generated disc having an optical center that coincides with a center of a field of vision when the wafer is mounted in a scope. In one embodiment, a primary vertical cross-hair having a predetermined thickness bisects the disc, intersecting the optical center of the disc, or intersecting at a point offset from the optical center of the disc. In another embodiment, a primary horizontal cross-hair having a predetermined thickness intersects the primary vertical cross-hair, most preferably above the optical center of the disc, to form an upper right sector (for example, quadrant), an upper left sector, a lower right sector, and a lower left sector. A plurality of secondary horizontal cross-hairs having predetermined thickness are spaced along the primary vertical cross-hair. In a particularly preferred embodiment, at least some of these secondary horizontal cross-hairs are identified with a unique identifier, to aid the shooter in calibrating the horizontal cross-hairs by range, and in locating the appropriate horizontal cross-hair to use in selecting an aiming point. A plurality of secondary vertical cross-hairs having predetermined thickness are spaced along at least some of said secondary horizontal cross-hairs to aid in making accurate windage adjustments. In a further embodiment a separate range-finding means is positioned on the reticle to aid the shooter in determining the range to target. In a still further embodiment employing military reticles, the shooter uses the distance subtended by the vertical or horizontal lines to calculate the range to the target.

The reticles of the present invention may be made of any suitable material. The reticles may have any suitable markings that permit use as described above and elsewhere herein. The markings may be generated by any means, including, but not limited to, engravings, etchings, projections, digital or analog imaging, raised surfaces (for example, made of any desired material), etc. The reticles may be used in any type of device where there is use for secondary or multiple aiming points. The reticles may be used in conjunction with one or more additional components that facilitate or expand use (for example, ballistic calculators, devices

that measure exterior factors, meteorological instruments, azimuth indicators, compasses, chronographs, distance ranging devices, etc.).

In one embodiment, the present invention provides an improved target acquisition device using the reticle of the present invention. In some embodiments, the target acquisition device has one or more of a housing, a means for mounting the housing in a fixed, predetermined position relative to a gun barrel, an objective lens mounted in one end of the housing, and an ocular lens mounted in the opposite end of the housing. In some embodiments, the target acquisition device is a fixed power telescopic gunsight, or a variable power telescopic gunsight. When optics are mounted in the housing to permit the power to be varied along a predetermined range, the reticle is most preferably mounted between the objective lens and the variable power optics, although all configurations are contemplated by the present invention. The reticle may be configured in a target acquisition device in any desired focal plane (e.g., first focal plane, second focal plane, or a combination of both), or incorporated into a fixed power telescopic gunsight. In a further embodiment, the reticles of the present invention are incorporated for use in, for example, electronic target acquisition and aiming devices.

While the reticles of the present invention find particular use in long-range target acquisition devices they can be used with equal effectiveness at close and medium ranges. In one embodiment, the reticle of the present invention is adapted for use in a mid-range telescopic gunsight, or close range telescopic gunsight, or other device. A mid-range reticle, similar to the long-range reticle described above, is constructed in accordance with this invention. Since the mid-range reticle requires less lower field area, in some embodiments, the primary horizontal cross-hair can be conventionally positioned at the optical center of the reticle. The mid-range reticle can then be calibrated and used in the same manner as a long-range reticle.

In an additional embodiment, the reticle is provided with a circumscribing ring visible through the target acquisition device, to aid in centering the eye relative to the target acquisition device. This ring helps reduce shooting inaccuracy caused by the misalignment of the shooter's line of sight through the target acquisition device. The ring assures a repeatable check weld to the firearm that is beneficial to repeatable shooting. By providing a visual means to align the reticle within the target acquisition device, the shooter is able to produce more accurate and more repeatable results.

In one embodiment, the reticle is provided with an aiming dot. The aiming dot may be located at the optical center of the reticle for rapid acquisition of a target at extreme, medium and close range, and for aiding the shooter in centering her or his eye relative to the field of view. In a further embodiment, the aiming dot is projected on the reticle, for example, electronically from the ballistic calculator of the present invention, or for example, optically from a mirror, a split image, holographic image, or by other means such as an electronic grid plate. In a still further embodiment the projected aiming dot is a virtual aiming dot indicating correct barrel position to the shooter in the absence of a line of sight to the target.

In yet another embodiment, a portion of the primary vertical cross-hair or the primary horizontal cross-hair, or both, is provided with rangefinder markings to eliminate the need for a separate rangefinder means in one of the sectors formed by the intersection of the primary vertical and horizontal cross-hairs.

In one embodiment, the reticle markings are assigned range and distance values, for example, automatically by using a computing device containing a ballistics calculator program which receives information regarding external field conditions (for example, date, time, temperature, relative humidity, target image resolution, barometric pressure, wind speed, wind direction, hemisphere, latitude, longitude, altitude), firearm information (for example, rate and direction of barrel twist, internal barrel diameter, internal barrel caliber, and barrel length), projectile information (for example, projectile weight, projectile diameter, projectile caliber, projectile cross-sectional density, one or more projectile ballistic coefficients (as used herein, "ballistic coefficient" is as exemplified by William Davis, American Rifleman, March, 1989, incorporated herein by reference), projectile configuration, propellant type, propellant amount, propellant potential force, primer, and muzzle velocity of the cartridge), target acquisition device and reticle information (for example, type of reticle, power of magnification, first, second or fixed plane of focus, distance between the target acquisition device and the barrel, the positional relation between the target acquisition device and the barrel, the range at which the telescopic gunsight was zeroed using a specific firearm and cartridge), information regarding the shooter (for example, the shooter's visual acuity, visual idiosyncrasies, heart rate and rhythm, respiratory rate, blood oxygen saturation, muscle activity, brain wave activity, and number and positional coordinates of spotters assisting the shooter), and the relation between the shooter and target (for example, the distance between

the shooter and target, the speed and direction of movement of the target relative to the shooter, or shooter relative to the target (e.g., where the shooter is in a moving vehicle), and direction from true North), and the angle of the rifle barrel with respect to a line drawn perpendicularly to the force of gravity).

In one embodiment, the output of a ballistics program is selected to produce a targeting range data card for providing aiming point information for a specific target at a known range, or multiple targets at known or estimable ranges. In a further embodiment, the target acquisition device and reticle is a conventional telescopic gunsight and reticle in which the scope is adjusted to hit a target at range by rotating horizontal and vertical adjustment knobs a calculated number of "clicks". In a further embodiment, the telescopic gunsights and reticles include all varying designs of telescopic gunsights and reticles apparent to one skilled in the art, for example, telescopic gunsights manufactured and marketed by Leupold, Schmidt-Bender, Swarovski, Burris, Bushnell, Zeiss, Nikon, Kahles Optik, Nightforce, and reticles, for example the T. D. Smith reticle, Burris reticle, and Cabela's reticle. In a preferred embodiment, the telescopic gunsight contains a reticle of the present invention in which the specific aiming point for the target is identified by reference to the calibrated secondary horizontal and vertical cross-hairs. In some preferred embodiments, the calculator comprises means for unit conversion for any desired measurement.

In some embodiments, one or more components of the invention (for example, the ballistics calculator, target acquisition device, device for measuring external information) is contained in, or coated in, a material that shields the device from exterior interfering or damaging signals or forces (e.g., electromagnetic shielding, radiation shielding, shielding from conclusive forces, etc.). In another embodiment of the present invention, the ballistics calculator system includes a remotely controlled safety switch with ergonomic indicator to the shooter of switch status.

In one embodiment, the reticle of the present invention comprises a plurality of primary cross-hairs separated by predetermined distances, a plurality of secondary cross-hairs at predetermined distances along said plurality of primary cross-hairs, and a plurality of lead markings indicating rate of movement of the target along at least one said cross-hair. In one embodiment, the plurality of primary-cross-hairs comprises vertical cross-hairs. In another embodiment, the plurality of primary cross-hairs comprises horizontal cross-hairs. In yet

another embodiment, the plurality of primary cross-hairs comprises both vertical and horizontal cross-hairs. In a further embodiment, the plurality of secondary cross-hairs comprises vertical cross-hairs. In still further embodiment, the plurality of secondary cross-hairs comprises horizontal cross-hairs. In a preferred embodiment, the plurality of secondary cross-hairs comprises both vertical and horizontal cross-hairs. In a particularly preferred embodiment, the plurality of secondary cross-hairs comprises at least three secondary cross-hairs.

In one embodiment, the lead markings are along at least one of the primary cross-hairs. In another embodiment, the lead markings are along at least one of the secondary cross-hairs. In yet another embodiment, the lead markings are along at least one primary cross hair, and at least one secondary cross-hair. In a preferred embodiment, the plurality of lead markings comprises at least three lead markings. In a particularly preferred embodiment, the lead markings are secondary cross-hairs.

In one embodiment, at least one cross hair is a line. In another embodiment, the line is an uninterrupted line. In an additional embodiment, the line is a straight line. In yet another embodiment, the straight line is an uninterrupted straight line. In a further embodiment, the line is a predetermined thickness. In a still further embodiment, the predetermined thickness is a single thickness along the cross-hair. In some embodiments, the primary cross-hairs are evenly spaced. In other embodiments, the secondary cross-hairs are evenly spaced. In further embodiments, the lead markings are evenly spaced.

In one embodiment, the reticle of the present invention further comprises a substantially transparent disc having an optical center and an edge for mounting said disc, and a ring positioned optically between said optical center and said edge, said ring spaced from said edge and circumscribing said optical center and one or more aiming points, whereby said ring can be visually centered in a field of view for aiding users in aligning their line of sight through said target acquisition device.

In one embodiment, the reticle comprises rangefinder markings. In another embodiment, the reticle comprises markings for identification of one or more of the cross-hairs. In an additional embodiment, the reticle comprises markings for identification of one or more of the lead markings. In still another embodiment, the reticle comprises an aiming dot.

In one embodiment, the reticle is configured for use in day light illumination. In some embodiments the reticle is configured for use in low light illumination.

In one embodiment, the present invention provides a target acquisition device using the reticle of the present invention. In some embodiments, the target acquisition device has one or more of a housing, a means for mounting the housing in a fixed, predetermined position relative to a gun barrel, an objective lens mounted in one end of the housing, and an ocular lens mounted in the opposite end of the housing. In other embodiments, the target acquisition device is a fixed power telescopic gunsight. In still other embodiments, the target acquisition device is a variable power telescopic gunsight. When optics are mounted in the housing to permit the power to be varied along a predetermined range, the reticle is most preferably mounted between the objective lens and the variable power optics, although all configurations are contemplated by the present invention. The reticle may be configured in a target acquisition device in any desired focal plane (for example, the first focal plane, the second focal plane, or a combination of both), or incorporated into a fixed power telescopic gunsight. In a further embodiment, the reticles of the present invention are incorporated for use in, for example, electronic target acquisition and aiming devices.

In one embodiment, the present invention comprises a method for shooting a target comprising a target acquisition device, comprising a housing, a means for mounting said housing in a fixed, predetermined position relative to a firearm, an objective lens mounted in one end of said housing, an ocular lens, mounted in the opposite end of said housing; a reticle comprising a plurality of primary cross-hairs separated by predetermined distances, a plurality of secondary cross-hairs at predetermined distances along said plurality of primary cross-hairs, and a plurality of lead markings indicating rate of movement of the target along at least one said cross-hair; selecting an aiming point on said target acquisition device that accounts for the relation of the shooter to the target; and using said aiming point to aim said firearm so as to hit said target.

In one embodiment, the present invention comprises a method for shooting a target comprising a target acquisition device comprising a housing, a means for mounting the housing in a fixed, predetermined position relative to a firearm, an objective lens mounted in one end of said housing, and an ocular lens mounted in the opposite end of said housing; a

reticle comprising a plurality of primary cross-hairs separated by predetermined distances, a plurality of secondary cross-hairs at predetermined distances along said plurality of primary cross-hairs, and a plurality of lead markings indicating rate of movement of the target along at least one said cross-hair; a ballistics calculator system for computing targeting information to hit a target comprising a processor comprising a ballistics computer program for analyzing information needed to accurately aim a firearm at a target using a target acquisition device with a reticle, with the program using information regarding one or more of external conditions, the firearm being used, the projectile being used, the target acquisition device and reticle being used, the shooter, the relation of the shooter wherein said target can be greater than 1000 yards from the shooter, and the ballistics drag model and retardation coefficient being used, and selecting an aiming point on the target acquisition device that accounts for the relation of the shooter to the target, and using the targeting information displayed by the ballistics calculator system to aim the firearm so as to hit the target. In a preferred embodiment, the target is hit by holding the aiming point on the target. In a further embodiment the ballistics calculator system projects a reticle specific for information regarding one or more of the firearm being used, the projectile being used, and the target acquisition device being used.

In some embodiments, the present invention comprises a directional sensor for provision of, for example, azimuth and inclination of a firearm projectile's path of flight to a target. In certain embodiments, the path of flight does not comprise a line of sight. In preferred embodiments, the directional sensor is configured to be compatible with a firearm comprising, for example, a substance with a magnetic property.

Other embodiments will be evident from a consideration of the drawings taken together with the detailed description of the invention.

BRIEF DESCRIPTION OF THE DRAWINGS

A better understanding of the invention and its advantages will be apparent from the detailed description taken in conjunction with the accompanying drawings in which:

FIG. 1 is a diagram showing the optical components of a telescopic gunsight of the present invention;

FIG. 2 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, the spacing of the markings based upon a "shooter's minute of angle" or inch of angle" (IOA.TM.) scale;

FIG. 3 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at low power;

FIG. 4 is a partial side view of an example of a firearm showing a telescopic gunsight mounted on the barrel;

FIG. 5 is an example of 500 yard zero ballistic table created for a .50 Cal. Bolt Action Model M-93 Rifle having a 30 inch barrel built firing a .50 Cal Browning Machine Gun cartridge;

FIG. 6 is an example of a worksheet which can be used to calibrate the markings on a reticle in some embodiments of the present invention.

FIG. 7 is a completed worksheet based upon the table shown in FIG. 5;

FIG. 8 is an illustrative table providing data for determining an appropriate windage adjustment for the example;

FIG. 9 is an example of a reticle of the present invention based upon a "centimeter of angle" (COA.TM.) scale;

FIG. 10 is a front view of an example of a mid-range reticle of the present invention, the spacing of the markings based upon an "inch of angle" (IOA.TM.) scale;

FIG. 11 is a front view of a reticle of the present invention including a circumscribing ring, the spacing of the markings based upon an "inch of angle" (IOA.TM.) scale;

FIG. 12 is a front view of a reticle of the present invention including a circumscribing ring and an aiming dot located at the optical center, the spacing and the markings based upon an "inch of angle" (IOA.TM.) scale;

FIG. 13 is a front view of a reticle of the present invention in which the upper portion of the primary vertical cross-hair and the primary horizontal cross-hair have been provided with rangefinder markings of a United States Marine Corps Mil Radians scale, (where a circle equals 6,283 Mils/circle); or it may be calibrated in United States Army Mil scale (6,400 Mils/circle), or other Mil scale (e.g. 6000 mil/circle, 9000 mil/circle), or European, Russian, or other variations of the Mil scale.

FIG. 14 is a front view of a reticle of the present invention in which the upper portion of the primary vertical cross-hair and the primary horizontal cross-hair have been provided with rangefinder markings of an "inches of angle" (IOA.TM.) scale;

FIG. 15 is a front view of a reticle of the present invention in which a horizontal rangefinder bar intersects the primary vertical cross-hair at a position above the intersection with the primary horizontal cross-hair, and primary vertical cross-hair and horizontal rangefinder bar have been provided with rangefinder markings of any desirable scale;

FIG. 16a is a flow chart illustrating the data inputs relating to external conditions at the range required by the TRAG1S5 Ballistics Computer Program;

FIG. 16b is a flow chart illustrating the data inputs relating to weapon and ammunition required by, and outputs produced by, the TRAG1S5 Ballistics Computer Program;

FIG. 17a is a targeting grid generated by a personal computer running the TRAG1S5 Ballistics Program for calibrating the range of the secondary horizontal cross-hairs of a reticle of the present invention for stationary targets on a flat range and for calculating cross-wind horizontal offset information for each secondary horizontal cross-hair;

FIG. 17b is a targeting grid generated by a personal computer running the TRAG1S5 Ballistics Program for calibrating the range of the secondary horizontal cross-hairs for a reticle of the present invention for stationary targets on a sloped range and for calculating cross-wind horizontal offset information for each secondary horizontal cross-hair;

FIG. 17c is a targeting grid generated by a personal computer running the TRAG1S5

Ballistics Program for calibrating the range of the secondary horizontal cross-hairs for a reticle of the present invention on a flat range and for calculating lead information for a moving target and cross-wind offset information for each secondary horizontal cross-hair;

FIGS. 18a-18e illustrate handheld device data input screens for using a handheld device targeting program of the present invention;

FIGS. 18f-18g illustrate handheld device data output screens produced by the TRAG1S5 handheld device targeting program;

FIG. 18h illustrates input and output screens of the ballistics calculator system of the present invention in other embodiments.

FIGS. 19a-c illustrate changes in the aiming point produced by different conditions of target speed and direction relative to wind speed and direction;

FIG. 20 illustrates the uphill/downhill angle produced when a rifle barrel is used to shoot at targets located above or below the shooter;

FIG. 21 is a flow chart illustrating the data inputs to the Ballistics Computer Program;

FIG. 22 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power suitable for use, for example, in varmint and target shooting;

FIG. 23 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power suitable for use, for example, in varmint and target shooting;

FIG. 24 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power suitable for use, for example, in general hunting, military, and police applications.

FIG. 25 is a front view of a reticle of the present invention, showing the markings as viewed

through a zoom telescopic gunsight at high power suitable for use, for example, in general hunting, military, and police applications;

FIG. 26 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power suitable for use, for example, in general hunting, military, and police applications;

FIG. 27 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power with a ghost ring and rangefinder;

FIG. 28 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power with one or more primary horizontal cross-hairs vertically offset above optical center;

FIG. 29 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power with one or more primary horizontal cross-hairs vertically offset above optical center;

FIG. 30 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power with a rangefinder, and with the primary horizontal cross-hair intersecting the primary vertical cross-hair at optical center;

FIG. 31 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power with primary horizontal cross-hair intersecting the primary vertical cross-hair at optical center;

FIG. 32 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power;

FIG. 33 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power suitable for use, for example, in tactical, military, and police applications;

FIG. 34 is a front view of a reticle of the present invention, showing the markings as viewed

through a zoom telescopic gunsight at high power suitable for use, for example, in tactical, military, and police applications;

FIG. 35 is a front view of a two-part illuminated reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power suitable for use, for example, in mid-range, general purpose applications;

FIG. 35a is a front view of a two-part illuminated reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power under daylight conditions;

FIG. 35b is a front view of a two-part illuminated reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power when illuminated under low light conditions;

FIG. 36 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with the primary horizontal cross-hair intersecting the primary vertical cross-hair at optical center suitable for use, for example, in tactical, military, and police applications;

FIG. 37 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power and with the primary horizontal cross-hair intersecting the primary vertical cross-hair above optical center; suitable for use, for example, in tactical, military, and police applications;

FIG. 38 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power with a rangefinder, and with the primary horizontal cross-hair intersecting the primary vertical cross-hair at optical center, with a bold ghost ring suitable for use at close to mid-range;

FIG. 39a is a front view of a reticle of the present invention, showing the markings as viewed through an electronic reticle at high power calibrated in USMC Mil Radians, with the main cross-hairs subtending 0.2 inches, the small hack marks subtending 0.1 inches and all other markings subtending 0.14 inches at 100 yards;

FIG. 39b is a front view of a reticle of FIG. 39a, showing the markings as viewed through an electronic reticle at high power illuminated for use under low light conditions;

FIG. 39c is a front view of a reticle of the present invention, showing the markings as viewed through an electronic reticle at high power calibrated in USMC Mil Radians, with the main cross-hairs subtending 0.1 inches, the small hack marks subtending 0.05 inches and all other markings subtending 0.07 inches at 100 yards;

FIG. 39d is a front view of a reticle of FIG. 39c, showing the markings as viewed through an electronic reticle at high power illuminated for use under low light conditions;

FIG. 39e is a front view of a reticle of the present invention, showing the markings as viewed through an electronic reticle at high power calibrated in True Minute of Angle, with the main cross-hairs subtending 0.2 inches, the small hack marks subtending 0.1 inches and all other markings subtending 0.14 inches at 95.5 yards;

FIG. 39f is a front view of a reticle of FIG. 39e, showing the markings as viewed through an electronic reticle at high power illuminated for use under low light conditions;

FIG. 39g is a front view of a reticle of the present invention, showing the markings as viewed through an electronic reticle at high power calibrated in True Minute of Angle, with the main cross-hairs subtending 0.1 inches, the small hack marks subtending 0.05 inches and all other markings subtending 0.07 inches at 95.5 yards;

FIG. 39f is a front view of a reticle of FIG. 39e, showing the markings as viewed through an electronic reticle at high power illuminated for use under low light conditions;

FIG. 40 is a block diagram of an example of the ballistics calculator system of the present invention;

FIG. 41a illustrates a representative target for use of the reticle of the present, invention for a second shot correction of a missed first shot;

FIG. 41b illustrates a range call for using line #8 for drop compensation. For the first shot the target is placed on line #8 and the shot taken;

FIG. 41c illustrates that the shot taken in FIG. 41b misses the bullseye with an impact high and to the right of the target;

FIG. 41d illustrates that when the reticle of the target acquisition device is aligned so that the bullseye and original aiming point are aligned (at the central cross-hair of line #8), the actual bullet impact is at line #7, 2 hackmarks to the right;

FIG. 41e illustrates that line #7 2 hackmarks to the right is used for the main targeting cross-hair aligned with the bullseye for the second shot;

FIG. 41f illustrates that the second shot not impacts the bullseye using the impact point of the first shot on the reticle as the aiming point for the second shot;

FIG. 42 illustrates an example of the inputs and outputs integrated into a Ballistics Calculating System of the present invention;

FIG. 43a is an example of the electronic target acquisition device of the present invention using an objective lens and one or more additional lenses with a long, full focal length tube;

FIG. 43b is an example of the electronic target acquisition device of the present invention using an objective lens and one or more additional lenses with one or more mirrors or one or more prisms to reduce the tube length; and

FIG. 43c is an example of the electronic target acquisition device of the present invention using an objective lens and one or more additional lenses with one or more mirrors or one or more prisms to reduce the tube length.

FIG. 44a is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power in day light, with lead markers along the primary horizontal cross-hair suitable for use, for example, in tactical, military, and police applications.

FIG. 44b is a front view of a reticle of FIG. 44a, showing the markings as viewed through an electronic reticle at high power illuminated for use under low light conditions.

FIG. 45a is a front view of a reticle of the present invention, showing markings as viewed through a zoom telescopic gunsight at high power, with secondary vertical cross-hairs as lead markings on a primary and secondary horizontal cross-hair

FIG. 45b is a front view of a reticle of the present invention, showing markings as viewed through a zoom telescopic gunsight at high power, with arcs as lead markings along a primary and secondary horizontal cross-hair.

FIG. 45c is a front view of a reticle of the present invention, showing markings as viewed through a zoom telescopic gunsight at high power, with solid circles as lead markings along a primary and secondary horizontal cross-hair.

FIG. 45d is a front view of a reticle of the present invention, showing markings as viewed through a zoom telescopic gunsight at high power, with solid triangles as lead markings along a primary and secondary horizontal cross-hair.

FIG. 45e is a front view of a reticle of the present invention, showing markings as viewed through a zoom telescopic gunsight at high power, with solid triangles as lead markings along a primary and secondary horizontal cross-hair, with a circle as a ring for aiding users in aligning their line of sight.

FIG. 45f is a front view of a reticle of the present invention, showing markings as viewed through a zoom telescopic gunsight at high power, with solid triangles as lead markings along a primary and secondary horizontal cross-hair, with a rhombus as a ring for aiding users in aligning their line of sight.

FIG. 46a is a front view of a reticle of the present invention, showing markings as viewed through a zoom telescopic gunsight at high power, with secondary vertical cross-hairs as lead markings on a primary horizontal cross-hair, and secondary horizontal cross-hairs as lead markings along the secondary vertical cross hairs of unequal length, of use, for example, in

targeting a moving object.

FIG. 46b is a front view of a reticle of the present invention, showing markings as viewed through a zoom telescopic gunsight at high power, with secondary vertical cross-hairs as lead markings on a primary horizontal cross-hair, and secondary horizontal cross-hairs as lead markings along the secondary vertical cross hairs of equal length, of use, for example, in targeting a moving object.

FIG. 47 is a front view of a reticle of the present invention, showing markings as viewed through a zoom telescopic gunsight at high power, with secondary horizontal cross-hairs along secondary vertical cross-hairs, with markings for identification purposes, of use, for example, in targeting a moving object.

FIG. 48a is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along horizontal cross-hairs suitable for use, for example, in tactical, military, and police applications in targeting a moving object.

FIG. 48b is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along horizontal cross-hairs suitable for use, for example, in tactical, military, and police applications in targeting a moving object.

FIG. 49 is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along horizontal cross-hairs suitable for use, for example, in tactical, military, and police applications in targeting a moving object

FIG. 50a is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along horizontal cross-hairs suitable for use, for example, in tactical, military, and police applications.

FIG. 50b is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along horizontal cross-

hairs suitable for use, for example, in tactical, military, and police applications.

FIG. 51a is a front view of reticle markings of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power.

FIG. 51b is a front view of reticle markings of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power.

FIG. 51c is a front view of reticle markings of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power.

FIG. 52a is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along a primary horizontal cross-hair suitable for use, for example, in tactical, military, and police applications.

FIG. 52b is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along a primary horizontal cross-hair suitable for use, for example, in tactical, military, and police applications.

FIG. 52c is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along a primary horizontal cross-hair suitable for use, for example, in tactical, military, and police applications.

FIG. 52d is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along a primary horizontal cross-hair suitable for use, for example, in tactical, military, and police applications.

FIG. 52e is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along a primary horizontal cross-hair suitable for use, for example, in tactical, military, and police

applications.

FIG. 53a is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along horizontal cross-hairs with the intersection of a primary vertical and horizontal cross hair at the center of the reticle, suitable for use, for example, in tactical, military, and police applications.

FIG. 53b is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along horizontal cross-hairs with the intersection of a primary vertical and horizontal cross hair above the center of the reticle, suitable for use, for example, in tactical, military, and police applications.

FIG. 53c is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power, with lead markers along horizontal cross-hairs with the intersection of a primary vertical and horizontal cross hair above the center of the reticle, suitable for use, for example, in tactical, military, and police applications.

FIG. 54 shows the concept and exemplary components of the presently claimed precision indirect fire system.

FIG. 55 shows exemplary components provided for direct line-of-site fire to engage a target without detection.

FIG. 56 shows direct line-of-sight fire coupled to a ballistics calculator and reticle of the presently claimed invention.

FIG. 57 shows exemplary global positioning satellite (GPS) target location and acquisition.

FIG. 58 shows flight path azimuth and inclination of the projectile to the target.

FIG. 59 shows a virtual aiming point as a dot on a dome over a shooter providing a virtual flight path to a target.

FIG. 60 shows a directional sensor mounted on a firearm.

FIG. 61 shows exemplary relations between an aiming dot and a reticle of the presently claimed invention.

FIG. 62 shows exemplary components of a computing platform and software of a ballistics calculator system of the present invention.

FIG. 63 shows connectivity of a projectile source and a spotter using a ballistics calculator of the present invention to direct a projectile to a target.

FIG. 64 shows an exemplary directional sensor in a field of use.

FIG. 65 shows exemplary aiming system and display components of a ballistics calculator system of the present invention.

FIG. 66 shows a micro digital display and riflescope.

FIG. 67 shows firearms, projectile flight paths, obstructions and targets wherein a ballistics calculator system of the presently claimed invention is used to strike a target outside the line of sight.

FIG. 68 shows remote gun platforms comprising directional gun sensors, with distant display and control modules.

FIG. 69 shows features of the precision indirect fire ballistics calculator systems of the presently claimed invention.

FIG. 70 shows further features of the precision indirect fire ballistics calculator systems of the presently claimed invention.

FIG. 71a is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 71b is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 71c is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 71d is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 72a is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 72b is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 73a is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 73b is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 73c is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 73d is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 73e shows a rangefinder and range calculation method.

FIG. 73f is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 73g shows a second shot correction method using a reticle of the present application.

FIG. 74a is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 74b is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 74c is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 74d is a front view of a reticle of the present invention, showing the markings as viewed through a telescopic gunsight.

FIG. 74e shows a rangefinder and range calculation method.

FIG. 74f shows a rangefinder and range calculation method.

FIG. 74g shows a second shot correction method using a reticle of the present application.

FIG. 75 shows a nominal directional wind value system.

FIG. 76a shows an exemplary range card using a reticle and ballistic calculator of the present application.

FIG. 76b shows an exemplary range card using a reticle and ballistic calculator of the present application.

FIG. 77 shows a front view of a ballistics calculator of the present application.

FIG. 78a shows that as airflow wind passes through a channel which has ultrasonic transducers at either end a frequency shift is observed in in the received signal.

FIG. 78b shows that as airflow wind passes through a channel which has ultrasonic transducers at either end a frequency shift is observed in in the received signal.

FIG. 79 shows An electrical block diagram of an embodiment of the present invention with two ultrasonic transducers, switching, amplification, frequency counting, control, and wind speed calculation.

FIG. 80a shows an image of a handheld device of the present inventon.

FIG. 80b shows an image of a handheld device of the present invention.

FIG. 81 shows a front view of an embodiment of the present invention.

FIG. 82 shows an internval view of an embodiment of the present invention together with enclosure.

FIG. 83 shows a front internal view of an embodiment of the present invention.

FIG. 84 shows a back internal view of an embodiment of the present invention.

FIG. 85 shows a side internal view of an embodiment of the present invention.

FIG. 86 shows a front internal view of the keyboard of an embodiment of the present invention.

FIG. 87 shows a front view of an embodiment of the present invention.

FIG. 88 shows a front external view of a facing of an embodiment of the present invention.

FIG. 89 shows a side external view of an embodiment of the present invention.

FIG. 90 shows a front external view of an enclosure of an embodiment of the present invention.

FIG. 91 shows a front external view of an enclosure of an embodiment of the present invention.

FIG. 92 shows an internal view of a rear enclosure of an embodiment of the present invention.

FIG. 93 shows an external view of a rear enclosure of an embodiment of the present invention.

FIG. 94 shows an external view of a side of an embodiment of the present invention.

FIG. 95 shows an external view of a rear enclosure of an embodiment of the present invention.

FIG. 96 shows an external view of a rear enclosure of an embodiment of the present invention.

FIG. 97 shows an external view of a front image of an embodiment of the present invention.

FIG. 98 shows an internal view of a sensor channel of a handheld ultrasonic wind detector of an embodiment of the present invention.

DETAILED DESCRIPTION OF THE INVENTION

The present invention relates to compositions, methods and systems for environmental sensing. In particular, the present invention provides compositions, methods and systems for external and internal environmental sensing wherein the sensing provides ultrasonic wind detection sensing.

The present invention relates to target acquisition and related devices, and more particularly to telescopic gunsights and associated equipment used to achieve shooting accuracy at, for example, close ranges, medium ranges and extreme ranges at stationary and moving targets. Certain preferred and illustrative embodiments of the invention are described below. The present invention is not limited to these embodiments.

As used herein, the term "firearm" refers to any device that propels an object or projectile, for example, in a controllable flat fire, line of sight, or line of departure, for example, handguns,

pistols, rifles, shotgun slug guns, muzzleloader rifles, single shot rifles, semi-automatic rifles and fully automatic rifles of any caliber direction through any media. As used herein, the term "firearm" also refers to a remote, servo-controlled firearm wherein the firearm has auto-sensing of both position and directional barrel orientation. The shooter is able to position the firearm in one location, and move to a second location for target image acquisition and aiming. As used herein, the term "firearm" also refers to chain guns, belt-feed guns, machine guns, and Gattling guns. As used herein, the term firearm also refers to high elevation, and over-the-horizon, projectile propulsion devices, for example, artillery, mortars, canons, tank canons or rail guns of any caliber.

As used herein, the term "internal barrel caliber" refers to the diameter measured across the lands inside the bore, or the diameter of the projectile. As used herein, the term "internal barrel diameter" refers to a straight line passing through the center of a circle, sphere, etc. from one side to the other and the length of the line used in ballistics to describe the bore of the barrel.

As used herein, the term "cartridge" refers, for example, to a projectile comprising a primer, explosive propellant, a casing and a bullet, or, for example, to a hybrid projectile lacking a casing, or, for example, to a muzzle-loaded projectile, compressed gas or air-powered projectile, or magnetic attraction or repulsion projectile, etc. In one embodiment of the present invention, the projectile travels at subsonic speed. In a further embodiment of the present invention, the projectile travels at supersonic speed. In a preferred embodiment of the present invention, the shooter is able to shift between subsonic and supersonic projectiles without recalibration of the scope, with reference to range cards specific to the subsonic or supersonic projectile.

As used herein, the term "target acquisition device" refers to an apparatus used by the shooter to select, identify or monitor a target. The target acquisition device may rely on visual observation of the target, or, for example, on infrared (IR), ultraviolet (UV), radar, thermal, microwave, or magnetic imaging, radiation including X-ray, gamma ray, isotope and particle radiation, night vision, vibrational receptors including ultra-sound, sound pulse, sonar, seismic vibrations, magnetic resonance, gravitational receptors, broadcast frequencies including radio wave, television and cellular receptors, or other image of the target. The image of the target presented to the shooter by the target acquisition device may be unaltered,

or it may be enhanced, for example, by magnification, amplification, subtraction, superimposition, filtration, stabilization, template matching, noise reduction, image recognition, image edge detection, image enhancement, or other means finding use in the present invention. The target selected, identified or monitored by the target acquisition device may be within the line of sight of the shooter, or tangential to the sight of the shooter, or the shooter's line of sight may be obstructed while the target acquisition device presents a focused image of the target to the shooter. The image of the target acquired by the target acquisition device may be, for example, analog or digital, and shared, stored, archived, or transmitted within a network of one or more shooters and spotters by, for example, video, physical cable or wire, IR, radio wave, cellular connections, laser pulse, optical, 802.11b or other wireless transmission using, for example, protocols such as html, SML, SOAP, X.25, SNA, etc., Bluetooth.TM., Serial, USB or other suitable image distribution method. The image may also include a reticle overlay.

As used herein, the term "ballistics calculator system" as exemplified in FIG. 42 refers to a targeting system that may be, for example, analog or digital, which provides the shooter a solution for the trajectory of a projectile.

As exemplified in FIGS. 1 and 4, a target acquisition telescopic gunsight 10 (also referred to herein as a "scope") includes a housing 36 which can be mounted in fixed relationship with a gun barrel 38. Housing 36 is preferably constructed from steel or aluminum, but can be constructed from virtually any durable, substantially rigid material that is useful for constructing optical equipment. Mounted in housing 36 at one end is an objective lens or lens assembly 12. Mounted in housing 38 at the opposite end is an ocular lens or lens assembly 14.

As used herein, the term "lens" refers to an object by means of which light rays, thermal, sonar, infrared, ultraviolet, microwave or radiation of other wavelength is focused or otherwise projected to form an image. It is well known in the art to make lenses from either a single piece of glass or other optical material (such as transparent plastic) which has been conventionally ground and polished to focus light, or from two or more pieces of such material mounted together, for example, with optically transparent adhesive and the like to focus light. Accordingly, the term "lens" as used herein is intended to cover a lens constructed from a single piece of optical glass or other material, or multiple pieces of optical

glass or other material (for example, an achromatic lens), or from more than one piece mounted together to focus light, or from other material capable of focusing light. Any lens technology now known or later developed finds use with the present invention. For example, any lens based on digital, hydrostatic, ionic, electronic, magnetic energy fields, component, composite, plasma, adoptive lens, or other related technologies may be used. Additionally, moveable or adjustable lenses may be used. As will be understood by one having skill in the art, when the scope 10 is mounted to, for example, a gun, rifle or weapon 38, the objective lens (that is, the lens furthest from the shooter's eye) 12 faces the target, and the ocular lens (that is, the lens closest to the shooter's eye) 14 faces the shooter's eye.

Other optical components that may be included in housing 36 include variable power optical components 16 for a variable power scope. Such components 16 typically include magnifiers and erectors. Such a variable power scope permits the user to select a desired power within a predetermined range of powers. For example, with a 3-12.times.50 scope, the user can select a lower power (e.g., 3.times.50) or a high power (e.g., 12.times.50) or any power along the continuous spectrum in between.

Finally, a reticle assists the shooter in hitting the target. The reticle is typically (but not necessarily) constructed using optical material, such as optical glass or plastic, or similar transparent material, and takes the form of a disc or wafer with substantially parallel sides. The reticle may, for example, be constructed from wire, spider web, nano-wires, an etching, a chemical etching, etching and filling, a laser etching, differential illumination, a coating, coating and sputtering, metallic coating, AR coating, polishing, cementing of components, cementing and assembling, an organic light emitting diode (OLED), by machining, for example, machining of glass, by masks, by e-beams, by lithography, by photo-lithography, or may be analog or digitally printed, or may be projected (for example, on a surface) by, for example, a mirror, video, holographic projection, or other suitable means on one or more wafers of material. In one embodiment as exemplified in FIG. 35, illuminated reticles are etched, with the etching filled in with a reflective material, for example, titanium oxide, that illuminates when a light or diode powered by, for example, a battery, chemical or photovoltaic source, is rheostatically switched on compensating for increasing (+) or decreasing (-) light intensity. In a further embodiment, the illuminated reticle is composed of two or more wafers, each with a different image, for example, one image for daylight viewing (that is, a primary reticle), and one image for night viewing (that is, a secondary reticle). In a

still further embodiment, if the shooter finds it undesirable to illuminate an entire reticle, since it might compromise optical night vision, the secondary reticle illuminates a reduced number of dots or lines. In yet another embodiment, the illuminated primary and secondary reticles are provided in any color. In a preferred embodiment, the illuminated reticle of the shooter's aiming device is identical to one or more spotter target acquisition devices such that the spotting device independently illuminates one or both of the reticles.

In a particularly preferred embodiment, the illuminated reticles of the present invention are used in, for example, low light or no light environments using rheostat-equipped, stereoscopic adaptive binoculars. With one eye, the shooter looks through a target acquisition device equipped with an aiming reticle of the present invention. With the opposite eye, the shooter observes the target using a night vision device, for example, the PVS 14 device. When the reticle and night vision device of the binocular are rheostatically illuminated, and the binocular images are properly aligned, the reticle of the target acquisition device is superimposed within the shooter's field of vision upon the shooter's image of the target, such that accurate shot placement can be made at any range in low light or no light surroundings.

In one embodiment as exemplified in FIGS. 39a-f, the reticle of the present invention is electronically projected on a viewing screen comprising the shooter's image of the target. As used herein, the term "image" refers to data representation of a physical object or space. In another embodiment, an electronic image receptor receives an image from lenses made of, for example, plastic, glass or other clear material. In a further embodiment, the electronic image receptor is permanently affixed to the target acquisition device. In a preferred embodiment, two or more electronic image receptors are simultaneously or sequentially available to the shooter for acquisition of different spectral images including, for example, IR, thermal, visible light, ultra-violet light (UV), radiation including X-ray, gamma ray, isotope and particle radiation, microwave, night vision, radar, vibrational receptors including ultra-sound, sound pulse, sonar, seismic vibrations, magnetic resonance, gravitational receptors, broadcast frequencies including radio wave, television and cellular receptors, etc. In an additional embodiment, the electronic image receptor is a replaceable component of the target acquisition device.

In some embodiments, the reticle of the present invention is a thick or thin line-weight reticle of the present invention, for example, FIGS. 2, 3, 9-15, 22-38, or standard electronic reticle

(FIGS. 39a-h) of the present invention. In another embodiment, the reticle of the ballistics calculator system of the present invention is a conventional reticle, for example, a standard duplex or universal Mil-Dot reticle. In some embodiments, reticles of the present invention comprise reticles described, for example, in U.S. Patent Publication No. 20110132983, filed Mary 14, 2010, and U.S. Patent Application No. 13/800,078, filed March 13, 2013, herein incorporated by reference in their entirety.

In one embodiment, the electronic image is projected from the shooter's target image acquisition device to the ballistics calculator processing unit of the present invention by, for example, physical cable, IR, Bluetooth.TM., radio wave, cellular connections, laser pulse, optical, 802.11b or other wireless transmission using, for example, protocols such as html, SML, SOAP, X.25, SNA, etc., and may be encrypted for security. The processing unit may be any sort of computer, for example, ready-built or custom-built, running an operating system. In preferred embodiments, manual data is input to the processing unit through voice recognition, touch screen, keyboard, buttons, knobs, mouse, pointer, joystick, or analog or digital devices. In a further embodiment, the reticle of the present invention is electronically projected on a viewing screen comprising one or more spotter's image of the target. In a still further embodiment, the electronic image of the spotter's target image acquisition device is projected to the ballistics calculator by, for example, cable, IR, Bluetooth.TM., or other wireless transmission. In a particularly preferred embodiment, viewing screens of the ballistics calculator system comprising, for example, aiming dots, ghost rings and targeting data are projected on one or more shooter's and one or more spotter's viewing screens. In some embodiments the visual display includes LCD, CRT, holographic images, direct corneal projection, large screen monitors, heads up display, and ocular brain stimulus. In other embodiments, the display is mounted, for example, on the scope, in portable head gear, on glasses, goggles, eye wear, mounted on the firearm, or in a portable display standing apart from the firearm.

In some embodiments, the shooter is able to use the processing unit of the ballistics calculator system to electronically select the color of the reticle or image, and, through electronic enhancement of the target image, for example, to defeat mirage, to increase or decrease the brightness and contrast of the reticle, to increase or decrease the brightness and contrast resolution of the target image, to stabilize the image, to match the image with an electronic library of stored images, to electronically amplify the target image through pixel replication

or any other form of interpolation, to sharpen edge detection of the image, and to filter specific spectral elements of the image. In other embodiments, image types can be combined by the processing unit of the ballistic calculating system of the present invention to assist in resolving images, for example, performing digital combinations of visible spectrum with thermal imaging, overlapping ultraviolet images with X-ray images, or combining images from an IR scope with night optics. The processing unit of the present invention gathers all data on, for example, target size, angles and locations of spotters and shooters, and constructs an accurate position of the target in relation to the shooter. In a further embodiment, the ballistics calculator displays the electronic image observed by the shooter's or spotter's target image acquisition devices.

In some embodiments, the target acquisition device and processing unit of the ballistics calculating system of the present invention are provided in separate housings. In other embodiments, the electronic target image acquisition device and processing unit of the ballistics calculator system of the present invention are provided in a single housing. In a further embodiment, the housing is mounted on the firearm. In other embodiments, the housing is mounted, for example, on the side, back, top, or bottom of the target image acquisition device. In another embodiment, the housing is shielded, for example, from shock, water and humidity, radio frequency, magnetic, and radioactive interference. In a preferred embodiment, after the firearm is discharged the targeting grid of the electronic target image acquisition device and ballistics calculator system is adjusted so that the point of impact is matched to the targeting grid, thereby establishing a rapid zero aiming point. In yet another embodiment, firearm and telescopic aiming device are zeroed electronically.

In one embodiment, the target acquisition device is not mounted on a firearm. An advantage of not having the target acquisition device image receptor be mounted on the scope or firearm is that much larger, more powerful and more sensitive imaging components can be deployed, making it easier to acquire better images without burdening the shooter with additional bulk and weight. In addition, a stand-apart image receptor is not exposed to recoil from the firearm. In the stand-apart ballistics calculating system shooters, spotters and other interested parties view the target via a target image acquisition device, for example, a thermal imaging device, that projects an image on a video monitor or glasses, goggles, an eye-piece, a contact lens, a headset, or on the retina of the viewer. In some embodiments, the image receptor is in a spotting scope beside the firearm. In another embodiment, the image receptor is mounted on

a nearby firearm. In a preferred embodiment, the image receptor is at a separate location, or remote site. In a particularly preferred embodiment, the image receptor is in an airborne vehicle, drone, or satellite. In a further embodiment, the image is available as previously stored information. In another embodiment, the one or more shooters use multiple or composite image receptors.

Once a target is identified in the target image acquisition device, the reticle of the present invention is superimposed over the target using the ballistics calculator system of the present invention, for example the ATRAG program (Horus Vision, LLC). In a further embodiment, a green laser is fired at the target with a red laser showing the exact aiming point to affect the shot. The shooter using, for example, a standard riflescope target acquisition device with the aiming reticle of the present invention uses the green laser as a reference to the actual location of the target, and fires at the red dot projected by the red laser. In a preferred embodiment the shooter's target acquisition device is equipped with night vision. In another embodiment, a sighting laser is attached to the night vision thermal imaging device. Upon locating a target, a laser beam is fired at the target. In a preferred embodiment the electronic target acquisition device of the present invention is automatically calibrated, and its zero aiming point is matched with the night vision device which stands apart from the firearm. In yet further embodiment, the ballistics calculator system of the present invention comprising the thermal imaging device, laser, PDA (personal digital assistant) or handheld PC, are linked to a holographic projector to generate a holographically projected targeting grid in front of the firearm. In a preferred embodiment, the exact aiming point on the projected holographic grid is also projected. In another embodiment, the image acquired by the stand-apart image acquisition device is transmitted to other parties by, for example, wire, fiberoptic cable, IR, Bluetooth.TM, or radio frequency.

In another embodiment of the present invention, images including, for example, faces, objects, compound layouts, landscapes or any item that can be stored into a data base, are compared against the database, identified, and the object's identity is displayed alongside the image. In yet another embodiment, the processing unit of the present invention contains a database of common objects as seen from many perspectives. For example, a truck can be seen from the top, side, back, either side, from the front or in a combined image. Using object recognition, the computer of the ballistics calculating system recognizes a selected object, the aspect of its point of view, and is able to calculate its approximate physical size, thereby

providing an accurate range for the object. In still another embodiment, all of the functions of the processing unit are performed without user intervention through the use of expert system rules, or Artificial Intelligence means.

Output of the ballistics calculating system of the present invention may be communicated anywhere between any two or more components. In one embodiment, target image information is shared between the shooter, a remote station, and central command facility. In this fashion joint decisions may be realized or deferred. In another embodiment, output of the ballistics calculating system is stored, on, for example, VCR, DVD, hard disk, tape, FOBs or other portable storage device, analog or digital media. In a preferred embodiment, target image aiming representations are overlaid including, for example, simple cross-hairs, Mil-Dot cross-hairs, the reticles of the present invention, geometric symbols, bull's eyes, cursors, etc. In one embodiment, target image aiming representations are used for direct aiming, that is the shooter looks directly through the aiming device at the target, and compensates for corrections to the flight path by adjustments between the aiming device and the firearm. In a preferred embodiment, the firearm is indirectly aimed at a projected virtual dot in visual space instead of the target itself. Using the display image projected by the processing unit of the ballistics calculating system the virtual dot is placed where the cross-hair should center, rather than on the target. By aligning the firearm to the projected virtual dot, the bullet will follow a flight path that will take it accurately to the intended target. In another embodiment, the projected dot on the screen represents the virtual indirect aiming point that, with a cross-hair or other symbol, is used to align the firearm with the virtual point. As a consequence, with use of the ballistics calculating system of the present invention the shooter does not require direct sight of the target to accurately aim the firearm.

In one embodiment of the present invention, the reticle is projected on glasses, goggles, an eye-piece, a contact lens, a headset, or on the retina of the shooter. In another embodiment, the reticle is superimposed on any suitable image of the target, for example an optical image, a thermal image, an ultrasonic image, a sonar image, a radar image, a night vision image, a magnetic image, an infrared image, an enhanced image of any kind, or a holographic projected electronic image. In still further embodiment, the reticle is superimposed on the intended target and the aiming point is illuminated by a laser. Where the markings on a reticle are generated or moveable, in some embodiments, the markings may be modified to account for changes in the environment and/or desired function. For example, the position, size,

spacing of crosshairs, etc. may be automatically or manually adjusted to improve function.

In one embodiment, information regarding external conditions entered into the ballistics calculator system of the present invention includes data specific to the media through which the projectile travels including, for example, gaseous media (for example, air or other gas), fluid media (for example, fresh water, salt water or other fluid), solid media (for example, soil, stone or other solid), or a vacuous media (for example, near space within the solar system, or deep space beyond the solar system). In some embodiments, the data includes, for example, temperature, density, viscosity, ionization, specific gravity, elemental and molecular composition, hardness, ambient radiation, gravitational field, and the like of the media.

In a fixed power scope, in preferred embodiments, the reticle is mounted anywhere between the ocular lens 14 and the objective lens 12 of FIG. 1. In a variable power scope, the reticle is most preferably mounted between the objective lens 12 and the optical components 16. In this position, the apparent size of the reticle when viewed through the ocular lens will vary with the power; for example, compare FIG. 2 (high power) with FIG. 3 (low power). The reticle of the present invention may be mounted in a variable power target acquisition device, for example a variable power telescopic gunsight such as those manufactured by Schmidt & Bender GmbH & Co. KG of Biebertal, Germany, or U.S. Optics because of their excellent optics. The variable power scope may magnify over any suitable range and objective lens diameter, for example a 3-12.times.50, a 4-16.times.50, a 1.8-10.times.40, 3.2-17.times.44, 4-22.times.58 telescopic gunsight, etc.

When the reticle is mounted between the objective lens and the variable power optical components 16, the selected aiming point (as described in more detail below) on the reticle of the present invention does not vary as the shooter zooms the scope in and out to find the most desirable power for a particular shot. The reticle of the present invention is thus in the first focal plane so that the reticle markings scales are proportional to the image when viewed through the scope. Thus, a unit of measure is consistent no matter the magnification. In one embodiment, since magnification is proportional on a linear scale through the power range, when the reticle is in the second plane (that is, the markings stay the same size visually against a growing or shrinking image when the power changes (i.e. because the relationship is linear)), and when the power to which the scope is set is known, the scale value against the

image at a known distance when seen through the scope is calculated. In a further embodiment, a "click" stop at fixed intervals on the power ring assists the user's ability to set the power at a known stop. In a preferred embodiment, these calculations are performed by the ballistics calculator of the present invention.

For example, taking as input: 1. the power (P.sub.z) that the reticle pattern is "true" (i.e. 10.times.) 2. the value worth (V.sub.z) of the reticle pattern marks when "true" (i.e 1 Mil, or 10 cm at 100 meters) 3. the distance for the zero value (D.sub.z) (100 meters) 4. the current power (P.sub.c) setting (let's say 14) 5. the current distance (D.sub.t) of the object being viewed (let's say 600 yards) Expressed as:

(V.sub.z).times.(D.sub.t/D.sub.z).times.(P.sub.z/P.sub.c)=current drop

or, for example

(10 cm).times.(600 m/100 m).times.(10/14)=42.86 cm drop

The same calculation can be applied to range finding as well.

As shown in FIG. 2, a preferred reticle 18 of the present invention is formed from a substantially flat disc or wafer 19 formed from substantially transparent optical glass or other material suitable for manufacturing optical lenses. Disc 19 has two, substantially parallel, sides. A primary vertical cross-hair 20 is provided on one side of said disc 19 using conventional methods such as, for example, etching, printing, engraved by machine or burned by laser, or applying hairs or wires of known diameter. Etching is preferred. Primary vertical cross-hair 20 preferably bisects the disc 19 and intersects the optical center 21 of reticle 18. A primary horizontal cross-hair 22 is also provided, and most preferably intersects the primary vertical cross-hair at a position well above the optical center 21. Positioning the primary horizontal cross-hair in this way provides the necessary additional field of view necessary to shoot accurately at long ranges without reducing the magnifying power of the scope. Thus, the primary vertical cross-hair and the primary horizontal cross-hair form four sectors: an upper right sector (e.g., quadrant), an upper left sector, a lower left sector, and a lower right sector, when viewed through a scope properly mounted to a gun barrel as shown in FIG. 4.

A plurality of secondary horizontal cross-hairs 24 are provided along the primary vertical cross-hair 20, preferably both above and below the primary horizontal cross-hair 22 to aid in range adjustments and for locating an appropriate aiming point on the reticle with respect to the distance to the target. In one embodiment, the secondary, horizontal cross-hairs are evenly spaced. Some of these secondary, horizontal cross-hairs are provided with unique symbols 28 which are useful in quickly locating a particular horizontal cross-hair. Symbols 28 can be numbers, as shown in FIG. 2, letters or other symbols. Symbols 28 are used for identification purposes only. In one embodiment the at least some of the secondary, horizontal cross-hairs are evenly spaced. In a further embodiment, at least some of the secondary horizontal cross-hairs are unevenly spaced.

A plurality of secondary vertical cross-hairs or hash-marks 26 are provided on at least some of the secondary horizontal cross-hairs 24, to aid the shooter in making adjustments for windage and for locating an appropriate aiming point on the reticle with respect to both windage and range. In one embodiment the at least some of the secondary, vertical cross-hairs are evenly spaced. In a further embodiment, the at least some of the secondary, vertical cross-hairs are unevenly spaced.

Also provided on the reticle is a means for determining range. As shown in FIG. 2, the rangefinder 30 can be provided in one of the sectors formed by the primary vertical and horizontal cross-hairs, and can include a vertical arm 32 and an intersecting horizontal arm 34. Vertical arm 32 is provided with a plurality of evenly-spaced horizontal cross-hairs which intersect vertical arm 32; horizontal arm 34 is provided with a plurality of evenly-spaced, preferably downwardly extending cross-hairs. At least some of the range-finding cross-hairs are marked to correspond to a scale useful for determining range.

The spacing between the range-finding cross-hairs can be based upon a non-conventional scale, which can be referred to as the "inches of angle" (IOA.TM.) scale. An "inch of angle" is defined as the angle made (or the distance on the reticle) which covers, or subtends, exactly one inch at 100 yards--which is referred to as a "shooter's minute of angle" (SMOA.TM.). On the reticle shown in FIG. 2, an inch of angle is the distance between any two adjacent rangefinder cross-hairs. That is, the space between any two adjacent rangefinder cross-hairs will cover or exactly contain a one-inch target at 100 yards. A similar scale for metric shooters, which is called a "centimeters of angle" (COA.TM.) scale, can also be used, with a

centimeter of angle being the distance on the reticle that covers exactly one centimeter at 100 meters. Conventional scales, such as the "minute of angle" scale (true minute/angle) or Mil Radian scale (6,283 Mils/circle, 6,400 Mils/circle, or any other Mils/circle system), can also be used, although they are less intuitive to use and make the accurate estimation of long ranges more difficult.

In one embodiment, the spacings between secondary cross-hairs on the primary vertical and horizontal cross-hairs are also determined with reference to the scale used for the rangefinder. In a further embodiment, the spacings between secondary cross-hairs on the primary vertical and horizontal cross-hairs are independent with reference to the scale used for the rangefinder. In a preferred embodiment, the spacings between secondary cross-hairs on the primary vertical and horizontal cross-hairs are in USMC Mils, and the rangefinder is in IOA.TM.. For the reticle as shown in FIG. 2, it can be seen by reference to the rangefinder that the spacing between the secondary horizontal cross-hairs labeled 5 and 6 is 5 inches of angle. A shorter secondary horizontal cross-hair (or hash-mark) appears between horizontal cross-hairs 5 and 6, at a position 2.5 inches of angle from either secondary horizontal cross-hair 5 or 6. The secondary vertical cross-hairs 26, as shown in FIG. 2, are spaced apart by 5 inches of angle.

The thicknesses of the lines are also preferably determined with reference to the range-finding scale used. Line thickness may vary with intended use with a variety of thicknesses selected in accord with use. For example, in long-range varmint scopes line thickness may subtend only 0.1" at 100 yards. In the preferred embodiment shown in FIG. 2, the preferred thickness of the primary vertical cross-hair 20 and primary horizontal cross-hair 22 is 0.5 inches of angle and the preferred thickness of the secondary horizontal and vertical cross-hairs are 0.25 inches of angle. The rangefinder arms 32, 34 and the marked (5, 10, 15) rangefinder cross-hairs are preferably 0.25 inches of angle thick, and the intermediate range-finding cross-hairs are preferably 0.1 inches of angle thick. Line thicknesses may vary between reticles. In one embodiment, a single reticle may have a variety of line thicknesses.

As shown in FIGS. 13-15, the rangefinder can be positioned at any convenient site in the reticle. It is possible to use the primary vertical cross-hair 20 and/or primary horizontal cross-hair 22 as the rangefinder, obviating the need for additional lines in any sector formed by the intersecting primary vertical and horizontal cross-hairs. This is preferred because it provides

a less cluttered, and therefore less distracting, field of view. As shown in FIG. 13, the upper portion of the primary vertical cross-hair 20 can be provided with rangefinder markings of any scale to form a rangefinder vertical arm 32. Likewise, substantially the entire primary horizontal cross-hair 22 can be provided with rangefinder markings of any scale to form a rangefinder horizontal arm 34. Typical scales include the "inches of angle" or "centimeters of angle" scale introduced by the parent and grandparent applications from which this application claims priority, as well as conventional scales such as USMC Mil Radian scale, US Army Mil Radian scale, or minute of angle scales can also be used.

As shown in FIG. 14, the rangefinder horizontal arm 34 can be superimposed over only a portion of the primary horizontal cross-hair 22. Although FIG. 14 illustrates an example where the rangefinder horizontal arm 34 is located to the right of the intersection 21 between the primary vertical cross-hair 20 and the primary horizontal cross-hair 22, one skilled in the art will realize that the rangefinder horizontal arm 34 could just as easily be located to the left of intersection 21. The scale on the rangefinder markings can, if desired, be drawn to a different scale from that provided for the line thickness and spacing between the secondary vertical cross-hairs 26 and secondary horizontal cross-hairs 24. For example, an experienced shooter may be provided the rangefinder markings in an inches of angle scale to speed up the process of determining the range to target, and then have the spacing between the secondary horizontal cross-hairs 24 and secondary vertical cross-hairs 26 provided in a more conventional (and hence more familiar) scale that the experienced shooter can use to calibrate and shoot the weapon, such as, for example, a USMC Mil Radian scale.

In one embodiment, only one arm of the rangefinder is superimposed on either the primary vertical cross-hair 20, or the primary horizontal cross-hair 22. As shown in FIG. 15, the rangefinder vertical arm 32 can be superimposed over the primary vertical cross-hair 32 with a rangefinder horizontal arm 34 extending into an upper quadrant and intersecting the primary vertical cross-hair 20 at a position above intersection 21. Although FIG. 15 shows the rangefinder horizontal arm 34 extending into the upper left quadrant, it could just as easily be positioned in the upper right quadrant. Likewise, the rangefinder horizontal arm 34 could be superimposed over the primary horizontal cross-hair 22 and a rangefinder vertical arm 32 could intersect the primary horizontal cross-hair 22 at a position to the left or to the right of intersection 21 and extend upwards into the left or right sectors.

To use a target acquisition device and reticle of the present invention, it is preferred that the shooter becomes familiar with the characteristics of the firearm, projectile and ammunition to be used. The target acquisition device and reticle can be calibrated to work with almost any type of firearm, for example, handguns, pistols, rifles, shotgun slug guns, muzzleloader rifles, single shot rifles, semi-automatic rifles and fully automatic rifles of any caliber, air rifles, air pistols, chain guns, belt-feed guns, machine guns, and Gattling guns, to high elevation or over the horizon projectile devices, artillery, mortars, or canons or rail guns of any caliber. The target acquisition device and reticle can be calibrated to work with any type of ammunition, for example, a projectile comprising a primer, powder, a casing and a bullet, a hybrid projectile lacking a casing, a muzzle-loaded projectile, gas or air-powered projectile, or magnetic projectile.

Calibration of the Target Acquisition Device and Reticle

To calibrate the target acquisition device and reticle, in some preferred embodiments, the shooter first determines the ballistics based upon the characteristics of the weapon and ammunition to be used. Calibration for range and distance to target can follow many methods. For example, manual methods of calibration require no computer, involve trial and error by the shooter, and provide backup when higher technology-based methods fail or are not available. Computer-based calibration of the target acquisition device and reticle may be performed, for example, on desktop, laptop, and handheld personal computing systems.

The target acquisition devices and reticles of the present invention may also be calibrated using second shot methods without the shooter taking his or her eye off the target, or the rifle from the shoulder. For example, if the shooter misses on the first shot due to misjudgment of windage effect, range-to-target or other factors, the shooter may use the reticle's marked grid lines for second-shot correction to fire a quick second shot, putting the bullet on target without calculations, and without adjustment of the target acquisition device's windage or elevation knobs. Using this method, on taking the second shot the shooter repeats the first shot exactly with reference to shooting position, sight picture, and trigger control. The only difference will be the point of targeting on the reticle. After the first shot, the shooter must remember the elevation marker line employed for the first shot, the site held on the target for the first shot, and the point where the first bullet impacted in relation to the target on the first shot. Looking through the scope, the shooter then puts the cross-hairs on the original aiming

point, and notes where the bullet impacted in reference to the grid. That point of impact on the grid becomes the new targeting point for a quick and accurate second shot.

For example, as shown in FIGS. 41a-f, suppose the shooter is aiming at a long-range target, using dead center of Line 8 on the reticle of the present invention for drop compensation. After firing, and missing the bullseye, the shooter notes where the bullet impacted on the target. Looking through the scope, the shooter then puts the dead center of Line 8 on the target. Without moving off the target, the shooter notes on the grid where the bullet struck. Suppose, for example, the bullet struck on Line 7, and 2 hackmarks to the right of center. Line 7, 2 hackmarks to the right then becomes the new aiming point (cross-hair) for the second shot. Placing the target on Line 7-2 hackmarks to the right, the shooter squeezes the trigger and hits the aiming point.

After a range table is generated for a set of conditions, and a shot is taken based on the solution at a given distance at, for example, 5 horizontal marks down and 2 vertical marks to the right at 800 yards, but the shot misses two more marks down and one more mark right, instead of back tracking to find which input parameter may be in error, the shooter rapidly inputs this additional adjustment into the ballistics calculator, and the calculator will make the appropriate corrections across the entire range table based on the input.

Manual Calibration of the Target Acquisition Device and Reticle

For example, suppose the weapon to be used is a .50 caliber Bolt Action Rifle, Model M-93 with a 30 inch barrel built by Harris Gunworks in Phoenix, Ariz. The cartridge selected is .50 Cal Browning Machine Gun cartridge, each of which is constructed from a brass case (made by Winchester), primer (CCI #35); powder (218 grains ACC #8700 by Accurate Arms Powder), and bullet (750 grain AMAX Match bullet by Hornady, ballistic coefficient 0.750). Any conventional computer based ballistics program can then be used to determine bullet drop for this weapon/ammunition combination, such as, for example, the program written by W. R. Frenchu entitled "Ballistic V.4.0" which was copyrighted 1988 and is based upon Ingalls' table, or "Ballistic Explorer for Windows," sold by Oehler Research of Austin, Tex., and range values for secondary horizontal cross-hairs and cross-wind offset values for secondary vertical cross-hairs calculated manually.

The first step requires the user to zero the selected weapon by firing at a target of known size at a known distance from the muzzle of the gun. For example, if the user decides to zero the weapon at 500 yards, a target of known size is placed exactly 500 yards away (preferably using a measuring device, such as a steel tape, to be certain the distance is accurate), and typically 3-5 shots are fired at the target using the intersection of the primary horizontal and primary vertical cross-hairs as the aiming point. If a 5 inch (or smaller) group in the center of the target is produced, the rifle is zeroed. If the group is significantly larger, there may be a problem with the rifle, the ammunition, or existing weather conditions. If the group is correctly sized, but above, below, to the right or to the left of center of the bullseye, the windage and elevation knobs of the target acquisition device are adjusted and the process repeated until the group is centered as desired using the intersection of the primary horizontal and primary vertical cross-hairs as the aiming point. Once the target acquisition device and firearm has been zeroed, there will be no further need to change the windage and elevation knobs of the target acquisition device, since a user can simply select the correct aiming point for the range to a target by using the reticle markings.

Next, the shooter "calibrates" or assigns values to the cross-hair markings on the reticle. See, e.g., FIG. 5, which provides a table with a zero at 500 yards. Other tables can be calculated with zero values at other ranges. 500 yards has been selected here solely for the purposes of illustration. To assist the shooter in understanding how to manually "calibrate" the reticle, a worksheet, such as that illustrated in FIG. 6 can be used.

Next, the shooter can select the size of the bullseye (or target area) to be hit using a reticle of the present invention. For example, a selected bullseye could be 6 inches in diameter, 10 inches in diameter, 12 inches, 36 inches, 48 inches etc. A hit anywhere in the bullseye counts as a direct hit. For the purposes of this example, a 12 inch bullseye from a range of point blank to 1000 yards and a 36 inch bullseye from 1100 yards to 1650 yards were used.

When the shooter sees the reticle through the eyepiece, the secondary horizontal cross-hairs can be seen. In this example, the cross-hairs are evenly spaced 2.5 inches of angle apart. Thus, the spacing between the primary horizontal cross-hair 22 shown in FIG. 2, and the first secondary horizontal cross-hair below the primary horizontal cross-hair 22 is 2.5 inches of angle. The spacing between the primary horizontal cross-hair 22 and the secondary horizontal cross-hair labeled "5" is 15 inches of angle. This means that adjacent cross-hairs would span

a 2.5 inch target at 100 yards. The space between the primary horizontal cross-hair and the secondary horizontal cross-hair labeled "5" would cover a 15 inch target at 100 yards. At 200 yards, adjacent cross-hairs will span a target of 5 inches, and the space between the primary horizontal cross-hair and the secondary cross-hair labeled "5" would cover a 30 inch target. At 600 yards, adjacent cross-hairs will span a target of 15 inches, the space between the primary horizontal cross-hair and the secondary horizontal cross-hair labeled "5" would cover a 90 inch target, and so on. As can be seen, there is a linear relationship between the inches of angle scale and the range to the target in yards.

Using a table such as that shown in FIG. 5, and a worksheet, such as that shown in FIG. 6, the shooter can "calibrate" a target acquisition device of the present invention for the particular firearm and ammunition selected. For this example, a 500 yard zero table was selected for purposes of illustration. Therefore, the shooter marks the primary horizontal cross-hair 22 on the worksheet with the number 500 (e.g., if the target were exactly 500 yards down range, the shooter would select an aiming point along the primary horizontal cross-hair 22 to hit the target). The range value of the first secondary horizontal cross-hair below the primary horizontal cross-hair can then be calculated. Estimating a value of between 600 and 700 yards, the shooter can determine the closest value by calculating the inches of angle at 600 and 700 yards (which corresponds to bullet drop)

2.5 inches of angle 100 yards .times. 600 yards = 15.10 inches of angle 2.5 inches of angle 100 yards .times. 700 yards = 17.50 inches of angle

These calculated values are matched with the values shown in the selected Ingalls table (in this example, the 500 yard zero table shown in FIG. 5). The 600 yard range on the table shows a trajectory of 18.4 inches. The 700 yard range on the table shows a trajectory of -44.6 inches. Since the calculated bullet drop at the first secondary horizontal marker is 15.1 inches, and this most closely correlates with the trajectory shown in the Ingalls table for 600 yards (-18.4 inches), the first secondary horizontal cross-hair below the primary horizontal cross-hair is marked on the worksheet as 600 yards. Although the actual bullet impact should be 3.3 inches below the dead center of the 12 inch diameter bulls eye (18.4-15.1=3.3), this is close enough since a hit is considered to be anything within the 12 inch bulls eye.

The shooter can then repeat this process to calibrate the reticle for every secondary horizontal

cross-hair below the primary horizontal cross-hair. The results in this example, shown in FIG. 7, can be used to shoot at any target within a range up to 1700 yards. Longer ranges can also be calibrated using a zero table for a longer range (e.g., anything from a 600 yard zero table to a 2500 yard zero table). Once the worksheet is completed, it can be cut out and taped, for example, to the stock of the shooter's firearm or carried by the shooter for easy reference.

Alternatively, the shooter can locate the secondary horizontal cross-hair to use for an aiming point for a specific range. For example, using the same 500 yard zero chart found in FIG. 5, if the shooter wishes to hit a target at 1100 yards, she estimates two or three secondary horizontal cross-hairs which should bracket the correct secondary horizontal cross-hair to use as an aiming point. The shooter guesses the correct cross-hair is between the cross-hair identified as 6 and the cross-hair identified as 8. She then performs the same calculation:

20 inches of angle 100 yards .times. 1100 yards = 220 inches of angle Cross - hair #6 25 inches of angle 100 yards .times. 1100 yards = 275 inches of angle Cross - hair #7 30 inches of angle 100 yards .times. 1100 yards = 330 inches of angle Cross - hair #8

Looking at the 500 yard table, the bullet drop at 1100 yards is 247 inches. This looks fairly close to mid-way between. To double check this estimate, the shooter can run the calculation for the unlabeled secondary horizontal cross-hair between cross-hair 6 and cross-hair 7, which is located 22.5 inches of angle below the primary horizontal cross-hair:

22.5 inches of angle 100 yards .times. 1100 yards = 247.5 inches of angle

This value most closely approximates the trajectory according to the 500 yard zero Ingalls table used for this example, and, if used should correspond to a point exactly 0.5 inches off dead center.

Once the target acquisition device has been calibrated for the weapon and ammunition specified, the shooter can test the calculated values against actual performance at a range. The values generated using computer projections, ballistic tables and calculations are only a guide; however, they should be quite close to actual performance. It is preferred that the final range value assigned to each secondary horizontal cross-hair should be based on an actual line firing test of the selected weapon and ammunition at various ranges. A minimum of three

shots should be used for the final confirmation of the estimated values.

Computer Calibration of the Target Acquisition Device and Reticle

In comparison to manual calibration of the target acquisition device and reticle, it is easier, and therefore preferable to use a ballistics calculator programs of the present invention, for example the "TRAG1S program" family, the "ATRAG program" family, and other TRAG programs which are available from Horus Vision, LLC, 659 Huntington Ave, San Bruno, Calif. 94066, to calculate accurate values for the cross-hairs and all secondary lines of the reticle of the present invention or, for example, to identify a single firing solutions for a given target, using a personal computer, monitor and printer, firearm and cartridge, scope and reticle, and peripheral devices (for example, laser rangefinders, weather monitoring devices, global positioning systems, etc.), the combination of which is hereinafter refer to as a "ballistics calculator system." This program is a modified version of the Ballistics program written by William C. Davis of Tioga Engineering which has been adapted to directly calculate values for a reticle of the present invention, in addition to values for conventional reticles, and to run on any computational device, including Windows-based PC's or personal digital assistant ("PDA"). The program is preferably loaded into internal memory accessible by a device, such as, for example, by installing it on a hard drive. In one embodiment, the program is provided on a floppy disc, CD, DVD, ROM chip, or other similar device which is accessible by the controller. In a further embodiment, for handheld devices, the program is installed on internal memory, or stored on a plug-in device (such as an insertable ROM chip or memory stick).

As used herein, the terms "computer memory" and "computer memory device" refer to any storage media readable by a computer processor. Examples of computer memory include, but are not limited to, RAM, ROM, computer chips, digital video disc (DVDs), compact discs (CDs), hard disk drives (HDD), and magnetic tape.

As used herein, the term "computer readable medium" refers to any device or system for storing and providing information (e.g., data and instructions) to a computer processor. Examples of computer readable media include, but are not limited to, DVDs, CDs, hard disk drives, memory chip, magnetic tape and servers for streaming media over networks.

As used herein, the terms "processor" and "central processing unit" or "CPU" are used interchangeably and refer to a device that is able to read a program from a computer memory (e.g., ROM or other computer memory) and perform a set of steps according to the program.

In one embodiment, the process begins, as explained in detail above, by zeroing the weapon. In a further embodiment, the shooter may begin at any point in the program, or allow the program to determine the zero point. Once the weapon has been zeroed at a known range, the program is started. FIGS. 16a and 16b illustrate the data which is input, and the targeting information which is output, and which enables the calibration of the cross-hairs of a reticle of the present invention.

Information Regarding External Conditions

For the PC-based version of this Program, as shown in FIG. 16a, information regarding external factors are requested by the system and input by the user in response to each query as it appears on the monitor screen. In one embodiment, data is entered into the system using any conventional input device linked to the system, such as a keyboard, mouse, touch-screen and the like. In a further embodiment, a voice recognition system using a microphone and appropriate software for converting the spoken words to data is used to input data. In yet a further embodiment, cabled or wireless means from other measuring devices and sources is used to input data, for example Bluetooth.TM. In a preferred embodiment, instruments for data input, for example the Kestrel handheld device or similar handheld, laptop or desktop device, handheld global positioning system (GPS) or similar device, Leica Vector 4 rangefinder or similar device, and the like, are integrated with the computing device in such a way as to allow input data items to be made available to the ballistic program. In some embodiments, a direct connection is made between the external instruments and the calculator. In some embodiments, the information is passed via transmission, that is, partially or totally wireless (e.g., radio, satellite, etc.) or IR beaming. In some embodiments, the calculator is an integrated into the external device. The calculator and or any of the other associated devices may be provided in any form, including, but not limited to, computer, handheld device, traditional calculator, wristwatch, gun, visor, phone, video monitor, etc.

The first screen in this embodiment requests the user to select from four possibilities for atmospheric conditions: (1) "Army Standard Metro" sea-level atmosphere (temperature 59

degrees Fahrenheit, atmospheric pressure=29.53 inches of mercury, and relative humidity=78 percent); (2) "ICAO Standard" sea-level atmosphere (temperature=59 degrees Fahrenheit, atmospheric pressure=29.92 inches of mercury and relative humidity=zero); (3) actual altitude and temperature at the shooting site (if known); or (4) actual barometric pressure, relative humidity, and temperature at the shooting site (if known). The program is modifiable to request additional information, and to expand or contract the options. The most accurate information which can be provided by the shooter is the actual barometric pressure, relative humidity and temperature at the shooting site. Altitude and temperature at the shooting site are used by the program to estimate a barometric pressure and relative humidity, and may be more accurate than either of the two standard conditions choices.

The system next requests the user to input information regarding wind-speed in miles per hour, meters per second, kilometers per hour, or knots per hour. Once this information has been input, the system requests the user to input wind direction (the clock position from the line of fire). Thus, if the wind is perpendicular to the line of fire and traveling from the shooter's right to the shooter's left, the wind direction would be "3" for the 3 o'clock position. If traveling in the opposite direction, the wind direction would be "9" for the 9 o'clock position. In a further embodiment, wind direction data is input by a system based on a 360 degree circle, with the number of degrees increasing in a clockwise direction around the shooter. For example, if the wind is perpendicular to the line of fire and traveling from the shooter's right to the shooter's left, the wind direction would be 90 degrees. Wind speed and direction is used by the system to calculate the appropriate adjustment to the aiming point at any effective range (that is, the number of vertical cross-hairs from the primary vertical cross-hair the aiming point will be offset into to wind so that the bullet will hit the target when it travels downrange).

In some embodiments, the present invention provides a device for acquisition of information regarding external and internal conditions. In some embodiments, the device is handheld. In certain embodiments, the device comprises a handheld, waterproof unit with sensors/transducers, a digital signal processing microcontroller unit (MCU), a color LCD touch screen, a display with graphics library functions and back-lighting, and a keypad designed to aid the long range marksman, sportsman and worker, and to provide a portable weather and environmental measurement system. In some embodiments, the device comprises a lithium ion main battery. In other embodiments the device comprises AA or

AAA batteries for dual redundant and standby operation, for example, a third "keep alive" battery for the MCU (button cell 2032), and a fourth for the GPS for fast satellite capture (*i.e.,* a very small battery), and a battery monitor, and automatic switch-over to standby batteries with user warning in code. In some embodiments, battery voltage sensing is integrated with battery management control, and charging current control. Charging may be performed using the integrated USB communications connector. In some embodiments, the device further comprises a GPS receiver, and/or a Bluetooth module, for wireless communications. In some embodiments, the device is configured to withstand submersion in 2 meters of water for one minute, and then to operate normally (*i.e.*, once it is dried). In some embodiments, the device comprises a microphone and amplifier for use as a hearing enhancement device. In some embodiments, the device comprises a light with brightness under user control, so that a source of illumination is available. In further embodiments, a handheld device of the present invention comprises a USB port with IP67 connector, a 3.5 mm waterproof headset jack, a ballistic calculator MCU, two or more non-volatile memories (*e.g.*, 1 Gbit and 2 Mbit) for data storage, in addition to 512K in the MCU, with all capacities capable of IP67 rating. In some embodiments, the handheld device is powered by rechargeable batteries (*e.g.,* when plugged in via USB cable to a computer), and/or is provided in a "Faraday Cage".

In further embodiments, sensors and transducers for temperature, barometric pressure (for example, a Bosch BMP180 Digital Pressure Sensor), relative humidity (for example, a Honeywell HIH-5030/5031 Low Voltage Humidity Sensor, tilt (3-axis accelerometer, for example, an Analog Devices ADXL325 Accelerometer), 3-axis magnetic compass (for example, a Honeywell IC HMC5883L Three Axis Digital Compass), sensitive waterproof microphone, GPS, and ultrasonic wind speed are provided. In preferred embodiments a keypad with, for example, tactile switches with molded silicone keys in a membrane arrangement to prevent water from entering the unit is provided. In some embodiments, the device comprises a LCD touch screen with, for example, 262K colors, RGB, white LED backlight, 240 x 320 pixels, and 2.4 inch diagonal display area. In some embodiments, the device comprises a 4-wire resistive touch screen technology. In some embodiments, the device comprises one or more of: a waterproof microphone; a high gain preamplifier; a digital volume control (under user control); a headphone amplifier; a sound recording and playback system;, and/or synthesized speech output available for "coaching" with or without a headphone.

In some embodiments, a device of the present invention comprises USB connector multiplexing. In certain embodiments, the devices senses when a USB host is connected by sensing the VBUS line of the USB. Under these circumstances, the I/O lines may be switched from the USB connector to the USB I/O lines of the MCU. When the VBUS voltage is not present the device assumes that either nothing is plugged in, or that an RS232 serial device is connected. Under these circumstances the I/O lines switches to an RS232 receiver, thereby enabling use of the same connector for USB and RS232. Similar systems may be used in conventional equipment to switch from USB to audio lines for a headphone, but not to switch between USB and RS232 prior to the date of the present invention. In some embodiments, another level of detection and switching is added to the system to allow use of the USB connector for audio I/O as well.

In some embodiments, a device for acquisition of information regarding external conditions of the present invention comprises an ultrasonic wind speed detector comprising a Doppler-effect system. As air in motion passes through a channel comprising ultrasonic transducers at either end, the airflow causes a frequency shift in the received signal. In some embodiments of the present invention, the velocity of airflow is measured in one direction, and then is measured in the other direction, and the difference in the two measurements is used to calculate wind speed. (FIG. 78) An ultrasonic wind speed detector of the present invention provides a compact, channeled airflow, constant frequency shift method in, for example, a handheld device. In some embodiments the detector requires no moving parts, and is more robust than propeller, anemometer, or ducted impellor designs conventionally used for handheld device wind speed measurement. In some embodiments, the channel allows less than ½ wavelength of the waveform across the opening. This dimension allows minimal reflection and refraction of the wave-front as it propagates through the channel. In some embodiments, the detector is calibrated by providing a known airflow, and determining the frequency shift per mile per hour (or other unit) of wind velocity based on the calibration. Other units of distance, time, acceleration, and velocity are provided in still further embodiments. In some embodiments, ultrasonic wind speed detectors of the present invention comprise 40 KHz ultrasonic transducers (for example, a STEMiNC SMATr10H40X80 Piezo Transducer) with sealed piezo elements attached to the inner face of an aluminum enclosure, and tuned to 40KHz self-resonant frequency. In this configuration, the ultrasonic wind speed detector of the present invention with an empirically-configured

Venturi shape provides a 600Hz frequency shift with a 10 mph wind, and an accuracy of 0.0167 mph. The meter is zeroed in still air, and then exposed to a bilateral (*i.e.*, left and right) known fixed airflow to calibrate the slope for each wind direction.

In some embodiments, an ultrasonic wind speed detector of the present invention is provided with a Venturi shape to the channel to measure wind speed with greater accuracy. As a result of the velocity increase of the airflow through the Venturi which amplifies the frequency shift due to higher internal velocity of the airflow, greater accuracy is observed. In a straight tube configuration with about 2.75 inches between the transducers, and using 40 KHz transducers, a 400 Hz frequency shift is observed with a 10 mph wind speed. An empirically-configured Venturi shape increases this to about 600 Hz per 10 mph. A 400 Hz shift allows measurement of wind speed with an accuracy of, for example, 0.025 mph. A 600 Hz of shift allows accuracy of about 0.0167 mph. In some embodiments, use of the ultrasonic wind speed detector of the present invention is contemplated in applications in which hundredth mph (or other unit) resolution is preferred, for example, heating/ventilation/air conditioning (HVAC) measurements of cubic feet per minute (CFM) airflow through a duct. In experiments conducted in the course of development of the present invention wind speed measures with a resolution better than 0.1 MPH were observed.

FIG. 79 shows an exemplary electrical block diagram of one embodiment of a system that illustrates two ultrasonic transducers, switching, amplification, frequency counting, control, and wind speed calculation. FIG. 80 shows conceptual representations of a handheld device of the present invention.

In some embodiments of the present invention, two ultrasonic transducers are used. In preferred embodiments, time-of-flight technology is not employed. Similarly, ultrasonic wind speed detectors of the present invention do not rely on pulses to measure pulse travel between transducers. To the contrary, two transducers are used in a high-gain, self-oscillating configuration to measure continuous "Doppler" effects *i.e.*, a continuous wave method, not a pulsed ultrasonic method. In still air, ultrasonic wind speed detectors of the present invention oscillate at a fixed frequency, for example, the resonant frequency of the chosen transducers, for example, 40 KHz. Airflow passing through the channel causes a Doppler shift in the oscillation. By measuring bi-directionally, the difference in frequency of the two measurements may be used to determine the airflow speed, including cross-wind

components. Coupled with a magnetic compass, and using at least two measurements, wind speed and direction may be ascertained. A single measurement alone may be used to determine the crosswind component. A single measurement takes, for example, ½ second *i.e.*, 250 ms left to right, and 250 ms right to left. In some embodiments, a running average is used to increase accuracy and stability of the measurements, together with recordation of the highest, lowest and average wind speed values to more accurately quantify gusting conditions. In turn, ultrasonic wind speed detectors of the present invention measure frequency shift, not phase differences, do not require as great a distance between the transducers as time of flight methods, and are more robust than conventional technology, thereby enabling handheld applications. In some embodiments, ultrasonic wind speed detectors of the present invention comprise the unforeseen and surprising benefits of a combination of bi-directional sensing, Venturi modeling of channel shape and length, and optimization of channel dimensions. For example, ½ wavelength at operational frequency to preserve the shape of the ultrasonic wave-fronts travelling down the tube increases accuracy, reduces the drive power needed, and reduces the influence of external noise. In experimentation conducted in the course of development of embodiments of the present invention channel configurations with varying diameter and venture taper have been investigated. In preferred embodiments, signal amplitude and frequency shift is balanced at a channel measuring 8 mm at the middle compared to, for example channels measuring 6 mm or 12 mm. In some embodiments, larger input openings to the channel provide lower air velocity at the openings but increased velocity at the center. In certain embodiments, ultrasonic transducers are mounted in rubber. In other embodiments, the rubber does not extend to the top of the transducer. In further embodiments, transducers mountings are configured to prevent water from entering the electronics cavity but to be easy to wash and clean if clogged with foreign material such as mud, debris and the like. In some embodiments of the present invention, no "flip-flops" of circuitry are required to drive transducers, coordinate amplifiers, analog switching, microcontrollers, batteries and a display. In preferred embodiments, wind speed measurements are performed in 0.5 seconds or less. In some embodiments, a device for acquisition of information regarding external conditions comprises measuring laser interferometry fringing effects to provide a complete wind profile between a target and a shooter.

In further embodiments, a device for acquisition of information regarding external conditions comprises an acoustic (*e.g.*, gunshot) direction finder. In certain embodiments, the direction

finder is an accessory for a handheld unit using, for example, an array of microphones (*e.g.*, 5 microphones) mounted on a helmet or other gear. The unit measures the time difference for the arrival of the first wave-front from a sound source and then calculates the direction of that sound source. The distance between microphones and their relative positions are known and fixed. In order to provide the greatest accuracy the device, in some embodiments, comprises integral sensors comprising for example, tilt, magnetic compass, temperature, barometric pressure and humidity. Integration of these variables allows a user to calculate the air density and the speed of sound in air very accurately, as well as establishing angle and direction references for determining the location of the sound source. In some embodiments the data generated is used to identify the location of the sound source using a "heads-up" display. Such a display enables, for example, combat personnel and law enforcement personnel to immediately determine the location of an armed assailant. In some embodiments, the display is a visor or other easily viewable display.

In some embodiments, the device for acquisition of information regarding external conditions comprises soil and/or water temperature, and/or soil moisture, probes connected by USB, and coupled with GPS capacity to permit rapid and precise data collection with pertinent data and location. In further embodiments, the device comprises a black body radiant energy probe connected by USB to measure the impact of direct sunlight heating on living beings or equipment. The device may then determine, for example, heat stress or watts per unit area, and sun-induced heat rise on equipment. In other embodiments, the device comprises a firearm muzzle velocity and muzzle temperature probe to resolve the accuracy of ballistic calculation *via* improved prediction of ballistic curves. In some embodiments, wireless (Bluetooth) communication between the probe and a handheld device of the present invention is used. In some embodiments, the device comprises a unit clipped on the end of the barrel comprising two LEDs and two "photo pin diodes" to accurately measure muzzle velocity. The unit may be a tube or a half-tube in shape. Data from the unit is used to generate a thermal model of the gun barrel in code, and to calibrate a handheld device using the data from the clip-on. The unit enables accurate measurement of temperature-induced differences in muzzle velocity, and may do so automatically in "real-time". In some embodiments, temperature and muzzle velocity information allows the system to create a thermal profile for muzzle velocity, and a ballistics performance profile from muzzle temperature thereby providing highly accurate ballistics computations. In still further embodiments, the device comprises, one or more of an external high sensitivity directional microphone, a USB Geiger

counter wand, a USB chemical sniffer wand, USB metal detector wand or plate, a USB fish finder wand, a shot counter/ timer, a flexible camera wand, a suction cup microphone or wand for detecting sound through a window, a laser Doppler listening device for remote listening using a window pane as a target, and/or an angle camera attachment on the muzzle.

In further embodiments, the device for acquisition of information regarding external conditions comprises measurement of magnetic deviation at any point on earth. A user first travels a straight path of 100 to 200 meters. Then the user selects the "calibrate magnetic deviation" function of a handheld device of the present invention. The user next holds the device forward in the direction of travel and enters "capture". The device then calculates the bearing of the user's path from true north *via* changes in GPS readings. The user notes the magnetic compass direction, and the user or handheld device calculates the error in the magnetic reading based on the true north GPS reading. Civilian GPS may take several readings and a longer straight path to give accuracies in the +/- 2 degree range, but using, for example, GPS averaging techniques, or with the military version of GPS, the accuracy may be increased to +/- 1 degrees. In this fashion, a handheld device of the present invention may be used to accurately provide true local magnetic declination, without the large memory or programming requirements of other existing methods, including look-up tables, or earth magnetic model software.

Accordingly, the handheld device of the present invention provides a device that that eliminates the need to carry multiple devices. To the contrary, each of the integrated components may be used separately or, alternatively, may be used in combination with one another, comprising for example: a weather station capable of measuring ambient conditions equipped with a memory to review weather conditions that have already occurred in a pre-set period of time and capable of calculating factors such as dew point, wet bulb, heat stress index, wind chill, and the like; a sensitive hearing device a useful, for example, for hunters and birdwatchers; a GPS component capable of recording points (waypoints), going-to points, showing distances and headings; a magnetic and digital compass; a memory comprising dates and times of, for example, stellar and moon rise, stellar and moon set, duration of light or darkness, sun rise, sun set, duration of day, twilight, and darkness, and tides; a ballistic program configured for targeting including, for example, Taylor index, foot Lbs. of energy (or other unit), time of projectile flight, truing and the like, configured to interface with, for example, rangefinders (*e.g.*,Vectronix, L-3, NEW-COM), to provide a

firing solution and supplemental information, for example, GPS coordinates of a target. In preferred embodiments, the case is configured to provide features for tilt or cant sighting.

In some embodiments, handheld devices of the present invention are configured to link to, and function with, a diversity of peripheral instruments, devices and networks. For example, in certain embodiments handheld devices are configured to access digital or analog input from a laser light listening device with the capacity, in some embodiments, to detect vibrations on surfaces generated by voice or sound within. In further embodiments, handheld devices of the present invention are configured for integration with a laser light locator comprising one or more camera capable of detecting visible and non-visible light arising, for example, from a laser range finder apparatus. In preferred embodiments, a handheld device of the present invention uses this data to identify, calculate and display the source of the light and its location by, for example, GPS coordinates. In some embodiments, a laser light locator is integrated into a wearable garment, for example, a hat. In certain embodiments, the garment comprises one or more microphones, one or more cameras, and/or one or more laser light locators able to detect the flash and report of, for example, a rifle shot. In particularly preferred embodiments, handheld devices of the present invention use this data to identify, calculate and display the source of the shot and its location by, for example, GPS coordinates.

In other embodiments, handheld devices of the present invention are configured for integration with devices that display, analyze and interpret physiologic variables including, for example, electrocardiographic (EKG) data, electroencelphalographic (EEG) data, eletromyographic (EMG) data, transcutaneous oxygen saturation, end-tidal carbon dioxide concentration, ventilatory excursion, pupillary dilation, exhaled breath chemistry, body temperature, blood pressure, heart and breathing sounds, voice analysis, and the like. In certain embodiments, handheld devices of the present invention are configured for integration with one or more chemical sensors with the capacity, for example, to detect and measure the amount of physiologic gases, toxic gases (for example, ammonia, sarin, mustard gas, and other chemical warfare agents, carbon dioxide, oxygen, chlorine, combustible gases, etc.), and chemicals (*e.g.*, industrial chemicals, military chemicals including explosives, drugs, components of drug manufacture, etc.). Integration of this data with other capacities of handheld devices of the present invention *e.g.*, wind speed, wind direction, relative locations by GPS, etc. provide the user with the ability to plot and predict drift rates and exposure fields.

In other embodiments, handheld devices of the present invention are configured for integration with devices that detect the identity, speed and direction of movement of objects, animals or humans. For example, in some embodiments, handheld devices of the present invention are integrated with electronic eye instruments comprising an emitter, a detector and a continuous laser beam that is projected between the emitter and detector that, when interrupted, alerts the user to the presence of an intruder. Indicia of interruption of one or more beams signal the handheld unit of an intruder's rate of travel, direction of travel, and likely destination. In other embodiments, handheld devices of the present invention are configured for integration with underwater sensors, for example, underwater ultrasound sensors, radar sensors, video sensors, sound sensors and the like. In some embodiments, handheld devices are configured for the acquisition and analysis of data from devices providing information with regard to water depth, bottom composition and content, structures and obstructions together with water temperature, salinity, pH, presence or absence of chemical constituents or pollutants, radioactive waves and particles, density, pressure, and the like. In certain embodiments, handheld devices of the present invention are configured to measure and display ground moisture and composition.

In some embodiments, handheld devices of the present invention are provided with Horus A-TRAG Horus Ballistic Software installed without the need, for example, of an external device such as a chip, flash drive unit, CD or the like. An integrated handheld device of the present invention is capable of solving ballistic and/or targeting solutions once data has been inputted. In some embodiments, data is directly entered from, for example, weather sensors, internal or external GPS transducers, angle slope or inclination instruments, range or speed finding devices, and the like. In some embodiments, further variables specific to external conditions, the firearm being used, the projectile being used, the target acquisition device and reticle being used, the target, the shooter, the relation of the shooter and the target, and the ballistics drag model and ballistic coefficient are automatically entered, updated, and factored in a ballistic solution. In some embodiments, a device of the present claims is integrated into the body of an optical device including, for example, a riflescope, a spotting scope, a telescope, and the like. In some embodiments, aiming information is exported directly to a weapon. In certain embodiments, handheld device memory comprises image recognition databases and software, and or a camera or similar video capture device, configured, for example, for the identification of flora, fauna, friend and/or foe. In further embodiments,

handheld devices of the present invention provide breaching formulas in software with the capacity, for example, to provide a ballistic solution for generating a precision aperture in a barrier between a target and, for example, a shooter, and striking the target through the generated breach.

In some embodiments, a handheld device of the present invention enables acquisition of survey data, for example, of floral and faunal abundance.

In some embodiments, a handheld device of the present invention is 20 mm or less in thickness, with an equal to or greater than 320 x 240 pixel display, and 51 x 38 mm in dimension color touch screen. In certain embodiments, critical functions of the keypad are easily accessible from the tabs, with set-up type functions at the left thumb. In further embodiments, a handheld device of the present invention comprises an ESC key which may be used to exit a current field or menu, and return to a previous state. In some embodiments of the present invention, a touch screen is provided configured so that the user may navigate the keypad under challenging circumstances. The user can use the touch screen when it is easier, for example, when the user is not prevented from using the touch screen by gloves or environmental impediments. In some embodiments, a handheld device of the present invention comprises a cavity through the case at the top comprising a site for measurement of barometric pressure, temperature, relative humidity and the like, and is integrated with features of an ultrasonic wind speed detector.

In some embodiments, a handheld device of the present invention is configured for connection to a phone and/or internet or World Wide Web. In further embodiments, the device comprises hardware and software privacy protections including encryption, and cloud-based protections. In certain embodiments, the device is shielded from tracking. In some embodiments, the device is powered solely by batteries. In further embodiments the device is powered directly by solar and/or other energy sources. In preferred embodiments, the handheld device is shielded from external radio-frequency (RF) interference, and is shielded to not emit RF signals. Construction of the device from any suitable material is contemplated including aluminum, titanium, plastic, metallic and non-metallic composites, acrylic, polycarbonate, nylon, glass, and the like. In some embodiments, the device comprises a flip cover, a slip cover, a transparent cover and the like. In other embodiments, the handheld device of the present invention is provided with a hardened case.

In preferred embodiments, calculation of density altitude from barometric pressure, temperature, and relative humidity is provided. Further embodiments comprise a time-keeper, for example, a second, minute, hour, day, month and year time-keeper, a memory on readable media and memory cards, coupling mechanisms for communication with a personal computer, a main-frame computer, a laptop computer, a desktop computer and the like. In further embodiments, the handheld device of the present invention comprises a mathematic calculator. In some embodiments, handheld devices of the present invention comprise sound recognition data bases and algorithms to aid the user in identifying types of vehicles, or other sounds.

In some embodiments, the handheld device of the present invention provides an integrated menu of technologies in a single integrated, portable, pocket-sizes, device able to substantially assist the nature enthusiast, hunter, fisherperson, sportsperson, hiker, climber, sailor, birdwatcher, survivalist and/or others to enhance the safety and enjoyment of their indoor and outdoor experience. In some embodiments, users heading into the field need not face concerns about placing a handheld device of the present invention on a charger. AA and AAA batteries for the unit may be purchased worldwide, and/or are rechargeable. Using certain embodiments of the present invention, individuals who desire a personal device that is not, and cannot be, connected to the World Wide Web may avoid fees and payments for applications such as location determination, ballistic/targeting, birds-animal-fish identification, detail and number storage independent of the cloud if desired, including the capacity to capture and transfer sounds, and photo and video images, and transfer data to other electronic devices independent of the internet or Blue- tooth. Some embodiments of the present invention comprise 9-pin or multi-pin cable plug-ins, direct wire transfer, and/or IR transfer of data. Accordingly, operation of the handheld device of the present invention may be independent of utility companies, governments, solar disturbances, electro-magnetic pulses (EMPs), and the like that will not shut the device down. In certain embodiments, the handheld device of the present invention cannot be hacked or tracked.

In some embodiments, the handheld device of the present invention comprises a radiation detector able to detect and show, for example, the level alpha, beta, gamma, ingested or inhaled particle, and other radiation levels. In certain embodiments, highly sensitive microphone and amplification device provides the user with the ability to hear and enjoy the

soft, quite sounds of nature including, for example, a bird's singing or the mating calls of woodland, desert, or marine animals. In some embodiments, hearing impaired users are able to use the handheld device of the present invention as a substitute amplification instrument, especially when talking with the user's life partner or, for example, enjoying a night at the movies or opera using, for example, an ear-bud and hardware and software of the present invention.

Embodiments of the present invention find use in the activities of a diversity of users reliant on meteorological information including sportsmen, shooters, gardeners, aviators, farmers, and the like. With a touch of the display, or by pushing or scrolling, calculated answers for "dew-point", "wind-chill", "density altitude", and the like is displayed for the user. In some embodiments, units of measure are English, metric, binary, analog, and the like. In particular, users of embodiments of the handheld devices of the present invention will find navigation to destinations under trying conditions, including low light, limited visibility, uneven terrain, high latitude, and the like to be much easier. In some embodiments, a handheld device of the present invention comprises internal lighting for display illumination, and/or LED and/or similar lighting for external use, for example, lighting a path to a waypoint, comprising single or multiple lights selected from a listing of frequencies and intensities. In some embodiments, a handheld device of the present invention comprises a pulsing or strobe light for emergency identification.

In certain embodiments, a handheld device for acquisition of information regarding external conditions provides particular value to the hunting sportsman or sportswoman. For example, one of two hunters wins a sheep tag in a lottery draw. Because the terrain to be hunted begins at sea level and extends to the mountain tops, the two hunters realize they will require special equipment adapted to travel in inclement weather, wide elevation changes, and unfamiliar territory. Realizing that most sheep are taken at ranges between 200 to 500 yards complicates matters. A rifle shooting a light weight projectile that yields a flat trajectory is not practical since the hunters will be traveling in area endemic with grizzly and black bears. The hunter's rifles of choice are.375 H&H caliber. While traveling on foot in the bush, they load their rifles with 300 grain solid projectiles. This combination of rifle and projectile gives the hunters the knock down power and capacity to handle close and up-front encounters with a bear. Once they arrive in their hunt area the hunter with the lottery tag will switch from a 300 grain solid bullet to a flatter shooting, longer range projectile. This will allow the hunter with

the tag to make a long range shot at a sheep if necessary. The other hunter will keep his weapon loaded with heavy projectiles in the event they meet a bear.

Since the hunting trip presents unique challenges arising from weather, elevation changes, uphill/downhill shooting, bush trekking, and shooting ballistics, the hunters agree that they need items of equipment that will help facilitate a successful hunt. At the sporting goods store they purchase a handheld device comprising embodiments of the present invention that addresses issues arising from variable weather, navigation constraints, and shooting ballistics in locales where other electronic technology, for example, cell and satellite phones, may not function, and power is not available. The hunters purchase batteries to power the handheld device for the duration of the hunt. The hunters note that the ruggedized device comprises transducers for barometric pressure, temperature, relative humidity, and ultrasonic wind speed detection to provide accurate wind speed and direction values. The integrated GPS function provides assurances in the event that the hunters become disoriented, and cannot find their way. The touch screen allows rapid entry of location data and notes.

The hunters enter their firearm and projectile data before leaving home including, for example, rifle make and model, bullet weight, bullet construction, ballistic coefficient, barrel twist, muzzle velocity, zero, and the like. In certain embodiments the handheld device of the present invention comprises a rifle and projectile library. Once in the field, the hunters configure the handheld device for ambient conditions, and for the 2 different projectiles that they will be using with a push of a button, even with gloved hands in cold weather.

In shooting position, certain embodiments of the present invention comprise a precise inclinometer that allows the shooter to measure the uphill or downhill angle and slope. This data may be automatically entered to the ballistics solver software. The hunters further deploy their handheld device of the present invention to hear movement in the brush near their camp that may herald the arrival of a bear or other predator. Further in shooting position, the hunters are able to enter laser range-finding values to the handheld device to provide a ballistic aiming solution with elevation, windage and reticle in use projected on the screen with one or more aiming points, and the GPS coordinates of the target.

In certain embodiments, the handheld device for acquisition of information regarding external conditions provides particular value to officers of the peace. For example, a police officer is

assigned to patrol a challenging section of a city where multiple burglaries and sniper shootings have been reported. The senior sergeant issues the officer a handheld device comprising embodiments of the present invention, together with external components that may be connected to the handheld device *via* wire or Bluetooth.

Component 1 resembles a small, rounded dowel. When the call-in of a burglary is recorded, the officer travels to the scene, places an earphone of the handheld device of the present invention in his ear, and places the dowel-shaped wand against a window, door or wall. Laser Doppler or other types vibration transducers in the dowel-shaped wand serve as a sensitive microphone. This allows the officer to hear the sounds of events within the structure. In certain embodiment the officer may view the screen on the handheld device to monitor sound intensity levels. In further embodiments, sound recognition software is provided.

In preferred embodiments, the officer uses the handheld device to record sounds within the structure, to record ambient conditions at the time of recording, and to enter the GPS location data which may be of value at trial.

Component 2 resembles a standard police officers' helmet. Nevertheless, the helmet comprises multiple microphones embedded within a control package beneath the front emblem of the helmet. As the officer walks within his or her patrol area, he or she is instructed to wear the helmet, and carry an embodiment of the handheld devices of the present invention. If a sniper is operating and takes a shot in the vicinity of the officer, the officer immediately examines the display of the handheld device. In certain embodiments, the handheld device indicates the direction from which the shot is fired, the elevation (*e.g.*, ground level, 20 feet, or 80 feet, etc.). In addition, the handheld device indicates the sniper's GPS coordinates relative to the officer's location. The data is automatically archived in the memory of the handheld device of potential value in later criminal proceedings, and of immediate value in seeking back-up support in order to arrest the suspected perpetrator.

Information Regarding the Firearm Being Used:

The next query requests information for one or more of the rate and direction of barrel twist (that is, right or left), barrel length, internal barrel diameter, system vibrational analysis, and

internal barrel caliber. Spin drift is a force exerted on a spinning body traveling through the air due to uneven air pressure at the surface of the object due to its spinning. This effect causes a baseball to curve when a pitcher imparts a spin to the baseball as he hurls it toward a batter. To compensate for spin drift, the targeting program of the present invention can be modified to pose queries regarding the rifle twist characteristics, that is, the direction of twist in revolutions per unit barrel length, and the diameter of the bullet. In one embodiment, the firearm trigger is electronic and integrated with the ballistics calculator system.

Information Regarding the Cartridge Being Used

The next query requests textual information for identifying the type of projectile to be used. This information is not used in the calculations, but is printed out on the targeting grid so that the targeting grid for one projectile can be distinguished from subsequent targeting grids produced for other types of projectile. This information may be imported directly from a stored the gun list.

The next query, for example, requests the weight of the projectile in grains. This information is typically found on the box in which the ammunition or projectiles are packaged, or it can be found in ballistics manuals, by checking the projectile manufacturer's product literature, or by the shooter physically weighing the projectile. The program can be modified to accept any other unit of weight as well, and information, such as the weight of the projectile for standard cartridges can alternatively be stored in memory and automatically retrieved by the program when the user selects a standard, defined cartridge.

The next query requests the ballistic coefficient of the projectiles. In some embodiments, a query requests information regarding the projectile's form factor, cross-sectional area, cross-sectional density, and angle of departure. In a further embodiment, the program can be modified to accept 2 or more ballistic coefficients for the same projectile. The Ballistic Coefficient (BC) can be entered as a value provided by the projectile manufacturer, for example this information is typically found on the box in which the ammunition or projectiles are packaged. Or the BC may be available from directly from the manufacturer or with reference to a manual. In one embodiment, the ballistics calculator system may access this information through a bar code imprinted on the ammunition box, or directly on the ammunition. However, this value may not always be available. In this circumstance, the BC

can, for example, be determined by shooting the projectiles in known conditions and entering the observed impact of the bullet in relation to the point of aim. By taking the distance the gun is "zeroed" at, and measuring the "drop" of impact when shooting at another known distance, the values can be recalculated through algebra to derive the BC for the round used. The "drop" can, for example, be measured either by measuring the distance on the target directly with a ruler, or by observing and measuring through a reticle with known uniform hash marks. In a further embodiment, the information is stored in memory and automatically retrieved by the program when the user selects a standard, defined cartridge.

The next query requests the muzzle velocity of the projectile. Muzzle velocity (MV) is a function of the projectile's characteristics (for example, projectile weight, shape, composition, construction, design, etc.), the kind, quality and amount propellant used in the cartridge case, and the primer. Muzzle velocity is also a function of the barrel length of the firearm, such that the longer the barrel length, the greater the muzzle velocity. MV can, for example, be entered as a value provided by the projectile manufacturer typically found on the box in which the ammunition is packaged, or in the manufacturer's catalog, or for custom cartridges, standard cartridges, or to confirm the provided value, MV can, for example, be determined or checked experimentally using conventional equipment for measuring muzzle velocity.

The ballistic calculator of the present invention compensates for changing MV in relation to ambient air temperature by allowing entry of corresponding temperature/MV pairs into a numeric table. Using this data table, the ballistic calculator system is able to interpret the closest MV for the currently measured air temperature. Current air temperatures between any two pairs is interpolated proportionally between the corresponding MVs. Air temperatures outside of the lowest and highest temperature entries in the table is interpolated by extending the value slope of the last two end-points of the table. In a further embodiment, the information is stored in memory and automatically retrieved by the program when the user selects a standard, defined cartridge.

Information Regarding the Target Acquisition Device and Reticle Being Used

As shown in FIG. 16b, once the external factors have all been entered, the system queries the user to enter information regarding the target acquisition device and reticle used. The first query requests the user to input the height of the target acquisition device above the bore of

the gun. This is typically the distance between the optical center of the target acquisition device and the center of the gun barrel. The program can, for example, be modified to accept inputs in inches, centimeters, or any other conventional unit of measure. In one embodiment, the user inputs the type of target acquisition device and reticle, power of magnification, and plane of function. The final query requests the user to enter the range in yards, meters or other measure of distance at which the target acquisition device was zeroed for use with a specific firearm and projectile (i.e., the range at which the target acquisition device was "sighted" at zero for a specific firearm and cartridge). In one embodiment of the present invention, the target acquisition device of the present invention, and target acquisition devices used by spotters assisting the shooter, are for example, gyroscopically or electronically stabilized, collectively or independently, for image quality.

Information Regarding the Shooter

In one embodiment, the ballistics calculator system queries the user to input the shooter's eyesight acuity and idiosyncrasies, heart rate and rhythm (e.g, as measured by the electrocardiogram), respiratory rate, blood oxygen saturation, muscle activity (e.g., as measured by the electromyogram), and brain wave activity (e.g., as measured by the electroencephalogram), or other physiologic variable. Input of this information may be automatic by continuous transducers affixed to the surface area of the shooter and integrated with the ballistics calculator by wire or in a wireless format. In this fashion, the ballistics calculator system indicates to the shooter the time to shoot with optimal accuracy taking into account, for example, movement artifact from ventilation, cardiac performance, or tremor from excitement or fatigue. In one embodiment, movement artifact of the shooter is corrected by the ballistics calculator system using stabilization of the target acquisition device. In a preferred embodiment, the ballistics calculator system of the present invention uses an indirect or, for example, electronic, trigger, wherein the shot is not taken immediately after the shooter pulls the trigger, or otherwise indicates readiness to take the shot, but firing is delayed until the system, using Artificial Intelligence, integrates information regarding the shooter and other target alignment information to optimize the probability of success in striking the target.

In a further embodiment, the ballistics calculator system queries the user for the number and positional coordinates of third person spotters (i.e., other than the shooter and a target). In an

additional embodiment, the ballistics calculator system automatically queries other units to determine the number, location and type of third person spotters and devices. In another embodiment, one or more spotters assisting one or more shooters use target acquisition devices with reticles of the present invention, with the spotter's target acquisition device not attached to the shooter's firearm. The spotting target acquisition device can, for example, be used in conjunction with the target acquisition device on the firearm, or it can, for example, be used independently. In one embodiment, the shooter and spotters use identical target acquisition device reticles. The target acquisition devices and reticles used by shooters and spotters may be fixed or variable power. In a preferred embodiment, the spotting information and aiming points are projected on reticles shared by the shooter and spotters. In yet another embodiment, multiple shooters and spotters share optical or electronically linked target acquisition devices and reticles.

Information Regarding the Relation of the Shooter and the Target

In one embodiment, the ballistics calculator system queries the user for information regarding the range or distance from the shooter to the target. For example, the shooter may enter a distance estimated by reference to a rangefinder on the reticle of the present invention. In a further embodiment, the distance from the shooter to the target is provided by a peripheral device, for example a laser rangefinder. In another embodiment, the distance from the shooter to the target is provided by spotters assisting the shooter, by the use of a topographic map, or by triangulation.

The next query asks the user to input any slope information, that is, the angle from 0 to 90 degrees up or down between the shooter and target, that is, the vertical angle when the shooter is shooting uphill or downhill. This information is used to adjust the downrange aiming point based on the projectile's flight through space from the point of firing to target. As can be appreciated, the distance to a target at a sloped angle is somewhat longer than the horizontal distance to a target the same distance from the shooter at the same level at the same level, and typically requires the shooter to raise or lower the barrel of the firearm relative to an axis perpendicular to the force of gravity. As shown in FIG. 20, a shooter aiming downhill lowers the barrel 38 relative to the perpendicular axis 50 forming an angle .alpha., which is the "downhill" angle. As will be understood, when the shooter raises the barrel 38 above the perpendicular axis 50 (for example, when shooting at a target located

above the shooter), the angle formed between the perpendicular axis 50 and the barrel 38 will be an "uphill" angle. The "uphill" or "downhill" angle can, for example, be measured using a clinometer, a simple protractor, a Leica Vector 4 or similar device which provides the up or down angle to the target in degrees, or it can, for example, be estimated by a skilled shooter.

For very long range shooting (e.g., from 1000 to 3000 yards or more), it may be desirable to modify the targeting program to compensate for Coriolis effect and spin drift. The Coriolis effect is caused by the rotation of the earth. The Coriolis effect is an inertial force described by the 19th-century French engineer-mathematician Gustave-Gaspard Coriolis in 1835. Coriolis showed that, if the ordinary Newtonian laws of motion of bodies are to be used in a rotating frame of reference, an inertial force--acting to the right of the direction of body motion for counterclockwise rotation of the reference frame or to the left for clockwise rotation--must be included in the equations of motion. The effect of the Coriolis force is an apparent deflection of the path of an object that moves within a rotating coordinate system. The object does not actually deviate from its path, but it appears to do so because of the motion of the coordinate system. While the effect of the earth's movement while a bullet is in flight is negligible for short and medium range shots, for longer range shots the Coriolis effect may cause the shooter to miss. To compensate for Coriolis Effect, the targeting program of the present invention ca, for example, be modified to additionally pose queries regarding the hemisphere in which the shooter is located Northern or Southern), the latitude of the firearm, the longitude of the firearm, or the direction of fire in degrees clockwise from true North. The latitude of the gun and hemisphere can, for example, be determined manually using a topographic map of the area in which the shooter is located, or automatically using a GPS device. With these inputs, and the range to target, the offset required by the Coriolis effect is factored in by the ballistics program when determining the aiming point for hitting the target.

Finally, the system queries the user to indicate whether the target is moving or not relative to the shooter, or whether the shooter is moving. If the target is moving, the system asks the user to indicate the target's direction of travel, and then to estimate the speed of the target. This information is used to calculate a lead adjustment in the aiming point so that the user can hold the correct aiming point on the moving target so as to discharge the bullet towards the place where the target will be when the bullet arrives (assuming the target does not unexpectedly change direction or speed). For example, the speed of a moving target can be estimated, or

the speed of a moving target can be calculated using the ballistics calculator system, and entered into the ballistic calculator by a skilled shooter. Or the speed can, for example, be estimated by taking inputs of known range of observed object, number of uniform hash marks within a reticle, the estimated linear worth of each individual hash mark at the distance of the observed object, and the number of seconds the observed object takes to transverse the number of hack marks, and using algebra to derive an approximate speed of the observed object expressed in distance traveled over time.

In some embodiments, the user's movement is measured or input into the calculator. Such information can be tracked, for example, by a GPS or related device. Likewise, where the user is in a vehicle (car, helicopter, plane, etc.), information about the speed, direction, acceleration, deceleration, position, etc. of the vehicle may be entered or directly input from the vehicle to the calculator.

Computer Calculation of Targeting Grid for Cross-Hairs

Once the inputs are complete, the program computes solutions which, for example, are in the form of an electronic range card which provides a calibration for the horizontal cross-hairs of a reticle of the present invention for range, and provides the necessary off-set information for cross-wind and/or target movement. The range of a target may be derived from knowing the approximate size of the target, and measuring it with known uniform hash marks within a reticle. Geometry can, for example, be mentally calculated by an experienced shooter and entered into the ballistic calculator, or the values may be entered into the ballistic calculator itself and an estimated range will be automatically computed. In one embodiment, this computation compensates for viewing the target at an angle as the size of an observed object when viewed from an angle is skewed as opposed to viewing the same object directly. In some embodiments, a pattern recognition program is used to determine the identity of the target and directly input size or distance information into the calculator. In other embodiments, size and distance information of the target is determined by a pattern recognition program used to look up a common object size table. In alternative embodiments, the nature of the target (e.g., type of animal) is selected from a menu and the calculator determines distance by estimating the size of the target based on a database of average sizes for the selected target and image information obtained from the target acquisition device (e.g., boundaries of the target and device settings).

In one embodiment, the targeting grid is displayed conventionally on a computer display screen. In a further embodiment the targeting grid is transmitted to other devices. In a still further embodiment, the targeting grid is printed out and taken by the shooter to the range.

For example, the targeting grid shown in FIG. 17a was produced in response to the following inputs:

Altitude=1500 (ft above sea level)

Temperature=82 (degrees F.)

Windspeed=10 (mph)

Wind Direction=3 (o'clock)

Slope=0 degrees (a horizontal shot wherein the shooter an target are at the same level)

Target Moving=no

Height of sight above bore=1.9 (inches, center-to-center)

Cartridge information=.300 Win Mag Federal Gold Medal

Bullet Weight=190 (grains)

Ballistic Coefficient=0.533

Muzzle velocity=2960 (feet per second)

Sight-in range=100 (yards)

As can be seen from FIG. 17a, the range for each horizontal cross-hair from the primary horizontal cross-hair is identified, as is the amount of horizontal adjustment to be made at

each horizontal cross-hair to compensate for cross-wind at that range, to the left or the right (as appropriate) from the primary vertical cross-hair.

A more complex situation is illustrated by FIG. 17b, which is the same example as shown in FIG. 17a except that now information regarding the slope of the area over which the bullet will travel has been input (15 degrees). As can be seen, the program has adjusted the range values for each horizontal cross-hair to compensate for the bullet's travel at a sloped angle (the hypotenuse of a triangle) as opposed to level sighted flight (the base of a triangle). Thus, horizontal cross-hair 5 of FIG. 17a has been assigned a range of 789 yards for a flat shot, while horizontal cross-hair 5 of FIG. 17b (15 degree slope) has been assigned a range of 805 yards.

FIG. 17c illustrates an example in which all inputs are the same as shown for FIG. 17a, except information regarding a moving target has been input. In this example, the target is moving an estimated 4 miles per hour. The lead adjustment has been calculated by the program for each horizontal cross-hair, and is shown in tabular form in the far left column of FIG. 17c. The final adjustment is determined by the user by adding the wind adjustment to the lead adjustment if the wind and target are moving in opposite directions (i.e., the target is moving into the wind), or by subtracting the wind from the lead adjustment if the wind and target are moving in the same direction (i.e., target moving with the wind). Thus, for example, if the target is spotted at a range of 962 yards, and the wind is traveling from right to left and the target is traveling from left to right, the wind adjustment is added to the lead adjustment, to obtain the aiming point identified as "AP1". If the wind and target are moving together (i.e., wind and target both moving from right to left), the wind adjustment is subtracted from to the lead adjustment to obtain the aiming point identified as "AP2".

As noted above, for example, once the targeting grid has been created and displayed by the system, the user is again presented with options: (1) print out the targeting grid; (2) enter new atmospheric data; (3) identify a specific aiming point on the reticle for a target at a specific range; or (4) quit. For example, in one embodiment with present software, if the user decides to print out the targeting grid, the only remaining option is to quit. If it is desired to create additional targeting grids, the program can be started again. However, in one embodiment, the user is able to modify the software to allow the user to go back after printing out a targeting grid and exercise any of the other options. If the user enters new atmospheric data

based upon a new shooting position, the data regarding the weapon and ammunition is retained in the calculations. If the option to identify the aiming point is selected, for example, the user is queried to input the range to a specific target. Once the range is input, an image of the reticle is displayed by the computer with the suggested aiming point marked (see, e.g., FIGS. 19a-19c). The user can, for example, then select the option to find another aiming point (for a new target at a different range), or can, for example, quit the program. In one embodiment, the output is in the form of digital words played through a speaker. In a preferred embodiment, multiple shooting solutions are stored in computer readable media, and the solutions presented back to the shooter in the order the shooter chooses. This makes for rapid target engagement without having to reenter various combinations of information inputs between shots.

As can be seen from FIGS. 17a, 17b and 17c for example, the targeting grid software has greatly simplified the process of calibrating a scope containing a reticle of the present invention for specific conditions at the range or field, and for the firearm. The primary disadvantage of this system is that personal computers are not very portable. Many shooters do not wish to lug even small laptops around while shooting, where they can be subjected to harsh conditions of weather, accidents, and dust. Accordingly, the data compiled before the user goes to the range to shoot may change by the time the shooter arrives at the range. If external conditions change during the interim, the predicted ranges correlated to the horizontal cross-hairs may not be as accurate as they would be if external conditions were measured and input at the range just prior to shooting.

Previous efforts to integrate a firearm, a target acquisition device and a ballistics calculator system have met with failure. For example, as described in the article "The Long Range Rifle System That Never Was", published in Tactical Shooter, February, 2000, pages 28-33, Jim Schatz describes Heckler & Koch's efforts to construct the Weitreichendes Scharfschutzengewehr 2000 (WSG2000), a weapon easy to shoot, user friendly, and providing a computerized sighting system that could reduce the potential for aiming errors due to the effects of range and weather, thereby increasing the probability of hitting long range targets with a single round at distances beyond 2000 meters, more than 11/4 miles away. Although full-scale prototypes were assembled at great cost, the project "died on the drawing table." Schatz concludes: "As recently 1990, and even today (i.e., February, 2000), a sighting system does not yet exist that can do all that was required of the WSG-2000 sighting

system, in a small, portable and cost effective package for a "man portable" sniper rifle." (Tactical Shooter, February, 2000, page 32).

Accordingly, in some embodiments, the present invention provides modified ballistics software to adapt it for use with a Personal Digital Assistant (PDA) type, hand-held computing device, such as, for example, the Palm Pilot (Palm Pilot is a registered trademark of Palm, Inc.), Compaq, Hewlett-Packard, Casio, Sony, Motorola, or Nokia devices. These low cost, simple-to-use devices are particularly useful because, unlike a Windows PC, the device can be turned off while the program is active, and when the device is turned back on, the user is returned to the screen that was active at the time the device was turned off. This enables the user to make inputs and turn the device off while moving to a new location. In addition, handheld devices are presently available which incorporate cellular modem technology which enable remote access to email and the internet, and infrared reception and transmission capability to enable the remote exchange of data between similar devices, or between the handheld device and another device capable of receiving or sending data to the handheld device via an IR beam. handheld device s also communicate with each other and other devices using IR and other wireless technology using, for example, radio frequency (RF), Bluetooth.TM., USB, or Serial. Such devices enable the user to access accurate meteorological and other data from the Internet, or from other devices remotely (e.g., from the range, without the need for cabling). Accordingly, the term "PDA" or "Personal Digital Assistant" or “handheld device” as used herein means any small, portable computing device which can be programmed to receive the necessary data inputs and calculate the targeting information described herein, regardless of whether, for example, such devices are viewed commercially as cellular telephones with computing capability, or as hand-held computers with cellular capability. In some embodiments, handheld devices for external and internal environmental sensing of the present invention are integrated into other equipment including but not limited to clothing, packs, belts and slings, protective-wear (*e.g.*, helmets, vests, cladding, visors), sensory enhancement equipment (*e.g.,* eyeglasses, goggles, hearing aids), weapons, telescopic gunsights, spotting scopes, transportation equipment (*e.g.*, bicycles, motorcycles, automobiles, trucks, armor, unmanned aerial vehicle (UAV) platforms), and the like. In further embodiments of the present invention, devices for external and internal environmental sensing are miniaturized. In some embodiments, devices for external and internal environmental sensing of the present invention are voice operated. In other embodiments, devices for external and internal environmental sensing of the present

invention are operated by eye movement. In some embodiments, devices for external and internal environmental sensing of the present invention are privacy-protected, by for example, password, encryption, or physiologic variable, for example, retinogram.

In one embodiment, the handheld device s of the present invention are powered by a rechargeable battery. In other embodiments, the handheld device s of the present invention are powered by other sources for generating the necessary power for the device, including photovoltaic panels, commercially available alkaline and similar batteries, manually driven generators, and chemical cells. In a further embodiment, the ballistic calculator systems of the present invention are shielded from electromagnetic frequency radiation. The handheld device targeting program has also been adapted for use in conjunction with a reticle of the present invention as well as for use with conventional reticle/target acquisition device combinations which are conventionally adjusted for a specific shot by turning elevation and windage knobs a specified number of clicks. The handheld device targeting program preferably allows the user to select inputs and displayed aiming information to be in English or Metric units, or both with use of the "Delta Feature". In a preferred embodiment, data on standard target sizes to be used as a reference for target range estimation is stored in memory, and used to assist the shooter in determining the range to the target. In further embodiments, data on standard munitions and their specific performance characteristics are stored in memory and made retrievable by the targeting program or by the user.

As before, it is desired to zero the weapon at a predetermined range and to adjust the target acquisition device so that the primary cross-hair is the aiming point for the "sight-in" range. Once this has been done, and the user has verified that the firearm is producing satisfactory groups of shots at selected sight-in range, the handheld device targeting program can, for example, be activated.

In one embodiment, the targeting program is selected by tapping the targeting program icon on the "home" screen. The user chooses the type of target acquisition device/measurement system being used (conventional scopes with range/windage adjustments, or a target acquisition device fitted with a reticle of the present invention), or the program can be provided as a dedicated program for use with a particular target acquisition device/measurement system. If a conventional scope is selected, the output will identify the number of "clicks" needed to adjust the elevation and windage knobs on the scope to properly

position the cross-hair of the conventional scope to hit the target. If a target acquisition device using a reticle of the present invention is selected, the output will identify the position of the aiming point on the reticle. In one embodiment, the aiming information provided is numerical. In a further embodiment, aiming information is provided as a graphical depiction of the reticle being used with the exact aiming point identified, as is presently possible with the TRAG1S5 version for windows-based PCs. In a preferred embodiment, the screen allows the user to select inputs and displayed information in English or Metric units.

Once the type of target acquisition device has been identified, the handheld device targeting program asks for five parameters as shown in FIG. 18a: (1) bore height (the distance between the firearm barrel and the target acquisition device, center-to-center in inches); (2) projectile weight (in grains); (3) projectile ballistic coefficient(s); (4) sight-in range (the range at which the target acquisition device and firearm were zeroed, in yards); and (5) projectile muzzle velocity. The program positions the blinking cursor in the field where the first number is to be entered. The numbers, a period, an "enter" key and a "quit" key are displayed below the four queries. The bore height is entered by tapping the appropriate number and tapping the "enter" key on the display. The blinking cursor then appears in the second field (or the user taps the second field to position the cursor there), and the number corresponding to the projectile weight is tapped and the "enter" key tapped. The blinking cursor then appears in the third field and then the fourth field (or the user taps the third or fourth field to position the cursor there), and the number corresponding to the ballistic coefficient and sight-in range is tapped and the "enter" key is tapped. Finally, the blinking cursor appears in the fifth field (or the user taps the fourth field to position the cursor there), and the number corresponding to the muzzle velocity is tapped and the "enter" key is tapped. All five parameters are displayed and an "OK" button is displayed. The user can then review the five parameters, and if they are correct, the "OK" button is tapped. If the parameters are not correct, the "QUIT" button is tapped, the user can start over by reentering the correct parameters.

When the "OK" button is tapped, a second screen, shown in FIG. 18b is displayed by the handheld device which allows the user to select the kind of atmospheric data to be input using four choices: (1) "Army Standard Metro" sea-level atmosphere; (2) "ICAO Standard" sea-level atmosphere; (3) altitude and temperature at the shooting site; or (4) actual barometric pressure, temperature and relative humidity at the shooting site (if known). As described in more detail above, the fourth option produces the most accurate result. While it is clearly

possible to provide other choices, such as the standard conditions offered in the PC-based TRAG1S5 program described above, the small size of the handheld device screen makes it desirable to keep each screen as compact as possible, consistent with obtaining reasonably accurate results. When the appropriate selection is made, another screen is displayed which allows the user to input the selected atmospheric data. If the user chooses "altitude and temperature," the altitude is entered in feet above sea level, and temperature is entered in degrees Fahrenheit. If the user chooses "barometric pressure, temperature, and relative humidity," the screen shown in FIG. 18c appears and the unadjusted barometric pressure is preferably input as inches of mercury, temperature is preferably input in degrees Fahrenheit, and relative humidity is preferably input as a percentage. In a further embodiment, barometric pressure, temperature and relative humidity are entered in metric units. Conventional hand-held weather meters, such as, for example, the KESTREL.RTM. Pocket Weather Tracker manufactured by the Nielsen-Kellerman Co., Inc., and similar devices, can measure temperature, humidity, barometric pressure, altitude, density altitude, wind-speed, etc. Such hand-held meters may be modified to allow them to be electronically linked (either by cable or by conventional wireless means, IR or microwave, etc.) to the handheld device to allow for automatic measurement and input of these elements as needed. Such devices can, for example, be integrated as well with wristwatches with GPS units and similar devices.

Muzzle velocity found on the cartridge box, or measured in the field by use of a chronograph, or in the manufacturer's manuals, can be adjusted, if desired, based on temperature to produce a more accurate result. Since a projectile typically travels faster than the speed of sound, it creates a shock wave which induces drag on the bullet. Because the air is denser at low temperatures, and less dense at high temperatures, induced drag is higher at low temperatures, and lower at high temperatures. Accordingly, if it feels very cold to the shooter at the range, the published muzzle velocity of some types of cartridges can be reduced significantly, and if it feels very hot to the shooter at the range or in the field, the published muzzle velocity of some types of cartridges can be increased significantly. Muzzle velocity and temperature are entered by tapping MV in the first screen generating, for example, the display:

“TABLE-US-00001 Temp (degrees Fahrenheit) MV (feet per second) 40 2510 59 2610 106 2810”

Again, the atmospheric inputs are displayed, and the user clicks the "OK" button if all are

correct and the user is ready to continue.

As shown in FIG. 18d, the user can then input information on wind speed (in miles, knots or kilometers per hour, or meters per second at the muzzle), the wind direction (in clock position from line of firing or in degrees based on a 360 degree reference circle, for example, 3 o'clock equals 90 degrees), slope the projectile will travel between shooter and target (in degrees), and the target speed (in miles per hour, kilometers per hour, meters per second or feet per second). Once the data is entered, an "OK" button appears which the user can tap once the data is checked and verified for correctness.

As shown in FIG. 18e, the user is now ready to enter the range to any target. At this point, the user can turn off the handheld device until a target is acquired. Once the target is acquired, the range can be determined using the rangefinder on the reticle of the target acquisition device or using any other desired method, such as by using an electronic rangefinder or GPS device. The handheld device is turned on, and the screen shown in FIG. 18e appears. The user simply taps in the distance to the target in either English or metric units, and taps "enter". In a further embodiment, the ballistics program accepts range information automatically from an electronic rangefinder which is either connected to the handheld device via cable, IR, or linked using conventional wireless techniques.

As shown in FIG. 18f, if a conventional telescopic gunsight was initially selected, the handheld device displays the number of clicks the elevation and windage knobs on the scope needed to turned so that the intersection between the vertical and horizontal cross-hairs can be used as the aiming point to hit the target. As shown in FIG. 18g, if a target acquisition device employing a reticle of the present invention was initially selected, the exact position of the aiming point for this target on the reticle is identified: horizontal cross-hair is 6.93 (just above the horizontal cross-hair marked "7"); windage adjustment is 1.89 secondary vertical cross-hairs to the left of the primary vertical cross-hair (cross-wind is blowing from 3 o'clock (right to left)) if the target is stationary. If the target is moving from right to left (with the wind), the correct aggregate windage/lead adjustment would be 2.78 right (lead)-1.89 left (wind)=0.89 right (or almost one vertical mark to the right of the primary vertical cross-hair). (See FIG. 19a). If the target is moving from left to right (against the wind) the correct aggregate windage/lead adjustment would be 2.78 left+1.89 left=4.67 vertical cross-hairs to the left of the primary vertical cross-hair. (See FIG. 19b) See FIG. 19a for the reticle showing

the correct aiming point when the target is moving to the left with a right to left wind, FIG. 19b for the correct aiming point when the target is moving to the right with the same right to left wind, and FIG. 19c for the correct aiming point when the target is stationary, again with the same right to left wind.

While the method for inputting data into a handheld device is typically done by tapping a touch-screen (or connecting the handheld device to a PC and inputting data using various input devices for a PC such as keyboard, mouse, touch-screen, and the like), data can be transferred into the handheld device remotely (*i.e.*, without a hard wire connection) using cellular technology, Bluetooth.TM., or infrared beam. In one embodiment, the handheld device s are equipped with microphones, speakers or earphones, and voice-recognition and voice-generation technology to enable inputs and outputs to be spoken, thus eliminating the need to tap a touch screen, leaving the user's hands free to control the firearm. In another embodiment the handheld device is linked to receive positioning information from the Global Positioning Satellite using a GPS device, or to receive information regarding the azimuth to target in degrees clockwise from true north, slope of the angle of the barrel between the shooter and the target, as well as altitude, temperature and barometric pressure, and range to target by data transmission by a cable link or remote means (such as IR Beam or radio transmitter) from a laser range-finding device equipped to measure these factors,

Another advantage of using a handheld device -based targeting system such as that described above, is the ability to input and save the parameters and targeting output for several targets (for example, sets of data) for instant recall. This will enable the shooter to determine aiming point information for each one of a group of targets, save the information, for example, on a range card constructed for general use, and then use the information to quickly and accurately shoot each target in rapid succession without having to stop and calculate the aiming point information before each shot. This feature can be particularly useful when the shooter is working with a partner, for example a spotter, who can, for example, call out aiming point information for each target and then use a spotting scope to watch the flight of the bullet and determine if the aiming point should be adjusted. In one embodiment, multiple aiming dots are determined and stored in RAM before firing. In an additional embodiment, multiple aiming dots are displayed in the target acquisition device, but the appropriate dot illuminates as directional sensors in the target acquisition device detect that the target acquisition device is pointing to the particular target represented by a specific dot. In yet another embodiment,

the target acquisition device and ballistics calculator system of the present invention provide a real-time, mobile aiming dot that automatically adjusts for all known factors for the target at the center of the cross-hairs. In a further embodiment, teams of shooters and spotters are electronically networked through a shared reticle and aiming points.

As noted above, whether the shooter creates a targeting grid or range card manually, or uses the PC-based TRAG1S5 program described above, or uses the handheld device -based TRAG1S5, TRAG2P OR TRAGMP targeting programs to calibrate a reticle of the present invention, the targeting information should be verified for accuracy by shooting at a range.

Once the reticle has been calibrated as described above, it can be used in the field to acquire and hit targets of all sizes at long ranges. While the preferred range for the preferred embodiment is at least 500 yards to 2500 yards (assuming the firearm/ammunition combination selected are capable of accurately hitting a target at these ranges), a target acquisition device of the present invention can be used to hit targets very accurately at shorter ranges, for example 25 to 100 yards, as well as longer ranges, limited only by the capacity of the firearm and the eyesight of the shooter.

A rangefinder, such as that shown in FIG. 2, can, for example, be used to accurately determine the range to a target whose size is known or can be estimated. For example, for a 36 inch bull's-eye target placed at an unknown distance from the shooter, the shooter need only align the right edge of the target with the vertical arm 32 of the rangefinder so that the horizontal arm 34 of the rangefinder appears to pass through the center of the bull's-eye target. If, for example, the left edge of the target extends to the cross-hair corresponding to 6 inches of angle, then the observed size of the target is 6 inches of angle, and the range to target is calculated to be:

Range (yards) = target ` s actual size (inches) .times. 100 observed inches of angle on rangefinder

or, in this example,

Range (yards) = 36 .times. 100 6 = 3600 6 = 600 yards

As a further example, suppose that the shooter observes a moose in the distance, eating vegetables from a garden near a house. From a comparison with a door in the house, the shooter estimates the size of the moose to be 6 feet at the shoulder. Upon viewing this target in the reticle, the shooter aligns the horizontal arm 34 of the rangefinder with the ground level upon which the moose is standing, and the vertical arm 32 of the rangefinder with the moose's shoulder. The shooter determines that the moose's shoulder touches the cross-hair marked 5. The range can then be calculated as follows:

Range=72/5.times.100=1440 yards

Once range has been determined, the shooter can then determine and select the appropriate aiming point on the calibrated reticle, without the need for taking his eye off the target, and without the need of making any adjustments to the target acquisition device.

As windage problems downrange, particularly over long ranges, may not be accurately predicted, even with the help of a handheld device -based targeting system such as that described above, the experienced shooter can always use the reticle of the present invention to correct after a shot is observed to drift. As noted above, the secondary vertical cross-hairs may be, for example, evenly spaced at 1 Mil (which equals 3.6" at 100 yards), which provides a scale for adjusting a second shot towards the target. In a further embodiment, the reticle of the present invention uses a grid calibrated at 100 USMC Mils. For example, a 50 cal. bullet is fired at a target 1500 yards away. The intersection between the primary vertical cross-hair and the secondary horizontal cross-hair identified by number 11 is the selected aiming point. The bullet was observed to drift approximately two secondary vertical cross-hairs to the right of center. To correct for this drift, the shooter need only shift the aiming point to the intersection between the second vertical cross-hair to the right of the primary vertical cross-hair and the horizontal cross-hair identified by number 11, effectively moving the barrel of the weapon left the appropriate distance to compensate for windage. Likewise, if the bullet passes the target too high or too low, the shooter can use the secondary horizontal markings to adjust for range. For example, if the bullet is observed to pass two secondary horizontal markings above the selected aiming point when it passes the target, the shooter can quickly adjust by shifting his aiming point up two secondary horizontal cross-hairs, thus depressing the barrel of the firearm.

If it is not possible to visually determine projectile drift, and if the shooter does not have access to the output of either the PC-based TRAG1S5 program or the handheld device -based TRAG1S5 Targeting Program, the shooter can use a table which takes into account local conditions, the firearm, and ammunition to determine the amount of deflection over a selected range. See FIG. 8 for an illustrative table. With the conditions as stated in FIG. 8, and for a wind crossing from the left of the shooter to the right, the expected deflection of the bullet at 1000 yards would be 54.1 inches to the right. The aiming point for windage can be easily calculated:

inches of angle on horizontal cross - hair 100 yards .times. 1000 yards = 54.1 inches inches of angle on horizontal cross - hair = 54.1 inches .times. 100 yards 1000 yards = 5.41

Thus, the shooter can manually correct for windage on a first shot by choosing the intersection between the correct secondary horizontal cross-hair for 1000 yards, and the first secondary vertical cross-hair to the right of the primary vertical cross-hair (which, as indicated above for a preferred embodiment, is spaced 5 inches of angle away from the primary vertical cross-hair).

In addition to a long-range reticle, the present invention can be adapted for use in mid-range application. For the purpose of this application, "mid-range" is defined as about 50 to about 1000 yards from the muzzle of the weapon. A mid-range reticle can, for example, be manufactured, calibrated, and used in a target acquisition device in the same manner as the long-range reticle described above. Although the two reticles are calibrated and used in the same fashion, slight variations can exist in their reticle markings. These slight differences stem from their different range applications. Recall that the primary horizontal cross-hair 22 in the long-range reticle was preferably located above the optical center 21 to allow for additional field of view necessary for long ranges. As shown in FIG. 10, the primary horizontal cross-hair 22' of a mid-range reticle 40 does not need to be above the optical center 21. Since the mid-range reticle is used for shorter distances, less of the lower field of view is needed. Accordingly, for a mid-range reticle, the primary horizontal cross-hair 22' is preferably centered to intersect the primary vertical cross-hair 20 at the optical center 21. Since this provides more room in the top sectors of the reticle, the rangefinder 30 of the mid-range reticle is preferably located in the upper left sector rather than the lower left sector.

The mid-range embodiment 40 of the present invention is used in the same manner as the long-range version. The target acquisition device and reticle can, for example, be calibrated to work with almost any type of firearm. To calibrate the target acquisition device and reticle, the shooter can follow the same procedure detailed above for a long-range reticle with the reticle preferably zeroed for mid-range yardage.

Once the target acquisition device has been calibrated for the firearm and specified ammunition, the shooter can test the calculated values against actual performance at a range. It is preferred that the final range value assigned to each secondary horizontal cross-hair should be based on an actual line firing test of the selected firearm and ammunition at various ranges. At least three shots are preferably used for the final confirmation of the estimated values.

Once the reticle has been calibrated, it can be used in the field to acquire and hit targets of all sizes at mid-range distances. The rangefinder can be used to determine the range to the target as explained above with respect to the long-range reticle. Also, compensation for windage can likewise be determined as detailed above. A target acquisition device of the present invention could be used to hit targets at shorter ranges, as well as longer ranges, limited only by the capacity of the firearm and the skills of the shooter.

More accurate results can be achieved if a shooter centers the reticle while looking through the target acquisition device. However, aligning the user's eye with the optical center of the target acquisition device is not always easy. The present invention can also be provided with a "ghost ring" 41 as depicted in FIG. 11. The ghost ring 41 is a visible ring which has as its center the optical center 21 of the scope, and which circumscribes that markings on the reticle. Ghost ring 41 aids shooters by helping them align their sight with respect to the target acquisition device and reticle. By insuring that the ghost ring 41 is centered within the field of view of the target acquisition device, the reticle will likewise be centered. As shown in FIG. 12, an aiming dot 42 can, for example, be included as an aid for rapid acquisition of moving targets, and for centering the shooter's eye in the field of view of the scope. Dot 42 can be any diameter, but is most preferably about 5 inches of angle in diameter, and is superimposed over the optical center of the reticle. Dot 42 shown is most preferably circular, but it may also be other shapes such as square, rectangular, oval, and the like. The aiming dot 42 can be a predetermined size that covers a predetermined area of the target at a given range

according to a scaling of the reticle, such as inches of angle, centimeters of angle, or conventional scaling means as mentioned previously. The preferred arrangement of ghost ring 41 in combination with aiming dot 42 enhances the eye's natural tendency to center the ring 41 in the center of the field of view of the target acquisition device. By looking directly along the target acquisition device, the shooter is more likely to have accurate and repeatable shooting. The ghost ring 41 and dot 42 can be part of the reticle. Preferably ring 41 and dot 42 are etched onto one side of the disc 19. However, ring 41 and dot 42 can, for example, also be provided using other conventional methods such as, for example, printing, etching, or applying hairs or wires to disc 19, or to other optical components of the target acquisition device. In one embodiment, the etched rings and dots are filled with luminescent material such that the rings and dots may be illuminated if desired. Preferably aiming marking 42 is etched onto one side of the disc 19, but it can also be provided using other conventional methods such as, for example, printing or applying hairs or wires to disc 19 or to other optical components of the scope. In a further embodiment, the ghost ring is projected and mobile on the reticle, thereby preserving rapid aiming properties while not fixed only to the center of the reticle.

As exemplified in FIG. 44a, one embodiment of the present invention comprises a reticle, for example, for rapid target acquisition and threat elimination comprised of a ring that is centered in the riflescope's optical or electronics field of view. FIG. 44a is a front view of a reticle of the present invention, showing the markings as viewed through a zoom telescopic gunsight at high power in day light, with lead markers along the primary horizontal cross-hair suitable for use, for example, in tactical, military, and police applications on stationary and moving targets. In one embodiment, the reticle of the present invention further comprises a substantially transparent disc having an optical center and an edge for mounting said disc, and a ring positioned optically between said optical center and said edge, said ring spaced from said edge and circumscribing said optical center and one or more aiming points, whereby said ring can be visually centered in a field of view for aiding users in aligning their line of sight through said target acquisition device. In some embodiments, the ring-equipped reticle allows the shooter to rapidly discriminate the ring in the target acquisition device's field of view. The shooter thereby naturally and subconsciously focuses on the center of the ring. In further embodiments, a central dot is used for finer or more precise targeting as time allows. As used herein, a "central dot" refers to any geometric shape, for example, a circle, a square, a cross, or a diamond. In some embodiments, the central dot is solid. In other

embodiments, the central dot is hollow. In further embodiments, the central dot is indicated by interrupted lines.

In additional embodiments, the ring-equipped reticle gives the shooter the ability to rapidly acquire and engage targets at very close distances to plus or minus 300 yards. When a target is spotted, and time is of the essence, the central ring that encases all or part of the reticle gives the shooter the ability to quickly discriminate the object to be targeted. When speed is an essential factor, the reticle of the present invention gives the shooter a safety factor equated in time. Whether beast or man, she who sees first wins. The ring-equipped reticle of the present invention allows the shooter to strike the target first, thereby dramatically increasing her or his odds of survival. In some embodiments, for extended range targets up to 1000 yards and beyond, the shooter uses the targeting grid of the present invention contained wholly or partially within all or part of the ring.

In some embodiments the ring is designed with a thick line, for example a line that subtends, or covers, 5 MOA at 100 yards. In other embodiments, a thinner line is employed compatible with, for example, specific target acquisition devices, preferred magnification powers, weapons of choice, or assigned missions. In some embodiments, the area subtended by the ring is selected depending on targeting and weapon requirements. In preferred embodiments, the area of the ring on an electronic reticle is selected by programming the ballistics calculator system.

In some embodiments, the ring is partitioned into 4 equal quadrants by horizontal and vertical cross-hairs. In other embodiments, the quadrants bounded by horizontal and vertical cross-hairs are unequal in area. In another embodiment, the ring is a geometric shape, for example an oval or diamond, positioned at the center of the optical field of view. In other embodiments, the ring is a geometric shape, for example an oval or a diamond, located at the point that the horizontal and vertical crosshairs physically intersect. In still other embodiments, the ring is a geometric shape, for example an oval or a diamond, located at the point that interrupted horizontal and vertical crosshairs intersect if linearly projected. In some embodiments, the geometric shape of the ring subtends 5 MOA at exactly 100 yards. In one embodiment, the geometric shape of the ring is continuous. In another embodiment, the geometric shape of the ring is interrupted. In yet further embodiments, the size and shape of the ring is selected depending on the mission, weapon and type of ammunition.

As shown in FIG. 44a, in one embodiment, the reticle is configured for use in day light illumination. As shown in FIG. 44b, in another embodiment, the reticle is configured for use under low light conditions. FIG. 44b is a front view of a reticle of FIG. 44a, showing the markings as viewed through an electronic reticle at high power illuminated for use under low light conditions. In some embodiments, all or parts of the reticle may be illuminated to aid the rifleman in twilight viewing, or in high contrast situations. In preferred embodiments, the intensity of reticle illumination may be increased or decreased by an electronic target acquisition device.

As shown in FIG. 44a, in some embodiments markings along a horizontal cross-hair are used to indicate the hold points for the shooter to use when leading or engaging moving targets. In further embodiments, the markings are, for example hack-marks, dots, ovals, triangles, circles, or numbers.

In additional embodiments, the reticle of the present invention comprises lead markings. As exemplified in FIG. 45, in some embodiments, lead markings on the reticle are used to aid the shooter in determining the direction and rate of movement of the target in relation to the shooter in order to target a moving object. As used herein, "rate of movement" refer to a unit of distance traveled per unit time. Any unit of distance and any unit of time are suitable for indicating rate of movement. In some embodiments, units of distance include, for example, inches, feet, yards, miles, centimeters, meters, or kilometers. In some embodiments, units of time include, for example, milliseconds, seconds, minutes, hours, days, weeks, months or years. Lead markings may occupy any position in relation to primary and secondary vertical or horizontal cross-hairs. In some embodiments, lead markings occupy positions, for example, above a cross-hair, below a cross-hair, upon a cross-hair, between cross-hairs, or at the end of a cross-hair.

In one embodiment, lead markings are evenly spaced. In other embodiments, lead markings are unevenly spaced. In further embodiments, lead markings are spaced according to average rates of movement. In preferred embodiments, lead markings are projected on the reticle by a ballistics calculator system. In particularly preferred embodiments, projected lead markings are spaced on the reticle by a ballistics calculator system to account, for example, for the target's distance from the shooter, the target's direction of movement, the target's velocity of

movement, the target's rate of acceleration, the reaction time of the shooter, or the lock time of the firearm.

As used herein, "lead markings" may take any shape or configuration. In some embodiments, lead markings may be, for example, triangles, circles, squares, straight lines, curved lines, arcs, dots, numbers, solid shapes, or shapes in silhouette. Lead markings may be any color, in some embodiments, for example, black, white, red or blue in color. In other embodiments lead markings serve more than one purpose serving, for example, as identification markings or rangefinding markings as well as lead markings. In one embodiment, the lead markings are along at least one of the primary cross-hairs. In another embodiment, the lead markings are along at least one of the secondary cross-hairs. In yet another embodiment, the lead markings are along at least one primary cross-hair, and at least one secondary cross-hair. In a preferred embodiment, the plurality of lead markings comprises at least three lead markings. As shown in FIG. 45a, in a particularly preferred embodiment, the lead markings are secondary vertical cross-hairs on a primary and secondary horizontal cross-hair. As shown in FIG. 45b, in one embodiment, lead markings are arcs along a primary and secondary horizontal cross-hair. As shown in FIG. 45c, in another embodiment, lead markings are solid circles along a primary and secondary horizontal cross-hair. As shown in FIG. 45d, in still another embodiment, lead markings are solid triangles along a primary and secondary horizontal cross-hair. In yet another embodiment, as shown in FIG. 45e, lead markings are located along a primary and secondary horizontal cross-hair in a reticle equipped with a circle as a ring for aiding users in aligning line of sight. In a further embodiment, as shown in FIG. 45f, lead markings are located along a primary and secondary horizontal cross-hair in a reticle equipped with a diamond as a ring for aiding users in aligning line of sight.

FIG. 46 exemplifies a reticle of the present invention that excels when engaging moving targets. As shown in FIG. 46a, in one embodiment, the reticle of the present invention comprises a plurality of primary cross-hairs separated by predetermined distances, a plurality of secondary cross-hairs at predetermined distances along said plurality of primary cross-hairs, and a plurality of lead markings indicating rate of movement of the target along at least one said cross-hair. In one embodiment, the plurality of primary-cross-hairs comprises vertical cross-hairs. In another embodiment, the plurality of primary cross-hairs comprises horizontal cross-hairs. In yet another embodiment, the plurality of primary cross-hairs comprises both vertical and horizontal cross-hairs. In a further embodiment, the plurality of

secondary cross-hairs comprises vertical cross-hairs. In still further embodiment, the plurality of secondary cross-hairs comprises horizontal cross-hairs. In a preferred embodiment, the plurality of secondary cross-hairs comprises both vertical and horizontal cross-hairs. In one embodiment, secondary vertical cross-hairs are positioned along a primary horizontal cross-hair. In another embodiment, secondary vertical cross-hairs are positioned off a primary horizontal cross-hair. In a particularly preferred embodiment, the plurality of secondary cross-hairs comprises at least three secondary cross-hairs.

FIG. 46a is a front view of a reticle of the present invention, showing markings as viewed through a zoom telescopic gunsight at high power, with secondary vertical cross-hairs as lead markings on a primary horizontal cross-hair, and secondary horizontal cross-hairs as lead markings along the secondary vertical cross hairs of unequal length, of use, for example, in targeting a moving object. In one embodiment, the primary horizontal crosshair on both sides of the primary vertical crosshair is physically, or by linear projection, intersected by secondary vertical cross-hairs located at predetermined distances from the primary vertical crosshair. In some embodiments, spacing of the secondary vertical cross-hairs represents hold points for leading a horizontally moving target. In other embodiments, at least one secondary vertical cross-hair is subdivided by at least one hack-mark used for elevation holdover. In still other embodiments, at least one secondary vertical cross-hair is subdivided by a hack-mark used for leading a vertically moving target. In yet other embodiments, at least one secondary vertical cross-hair is subdivided by at least one hack-mark used for leading a target moving both horizontally and vertically. The spacing of the secondary vertical and secondary horizontal cross-hairs may be calibrated, for example, in MOA, Mil Radian, COA or other calibration system. As shown in FIG. 46b, in a further embodiment, the reticle of the present invention comprises secondary vertical cross-hairs as lead markings on a primary horizontal cross-hair, and secondary horizontal cross-hairs as lead markings along the secondary vertical cross hairs of equal length, of use, for example, in targeting a moving object.

As shown in FIG. 47, in one embodiment, reticles of the present invention comprise secondary horizontal cross-hairs along secondary vertical cross-hairs, with markings for identification purposes, of use, for example, in targeting a moving object. In a preferred embodiment, the secondary horizontal cross-hairs are evenly spaced. In a particularly preferred embodiment, the secondary vertical cross hairs are angled from the primary vertical cross-hair. In some embodiments, the angled secondary vertical cross-hairs are evenly

spaced. In further embodiments, the angled secondary vertical cross-hairs are unevenly spaced. In still further embodiments, spacing between secondary vertical cross-hairs varies along the length of the secondary vertical cross-hairs.

As exemplified in FIG. 48, in one embodiment, the reticle of the present invention comprises primary and secondary horizontal cross-hairs of unequal length. In some embodiments, as shown in reticle 45a, reticles of the present invention comprises a central aiming point marked, for example, by a cross or solid aiming dot suitable for use, for example, in tactical, military, and police applications in targeting a moving object. As exemplified in FIG. 49, in one embodiment, the reticle of the present invention comprises secondary horizontal cross-hairs of equal length of use, for example, in tactical, military, and police applications in targeting a moving object. As shown in FIG. 49, in some embodiments, no central aiming point is marked. In further embodiments, as shown in FIG. 48 and FIG. 49, reticles of the present invention comprise markings for identification of cross-hairs comprising numbers located, for example, at the end of at least one horizontal cross-hair, between at least two horizontal cross-hairs, along at least one horizontal cross hair, or numbers alternating with geometric figures, for example, dots. As exemplified in FIG. 50a, in one embodiment, a reticle of the present invention comprises horizontal cross-hairs of unequal length, identification markings of unequal size along, between and at the end of horizontal and vertical cross-hairs, and no aiming dot. As shown in FIG. 50b, in another embodiment, a reticle of the present invention comprises horizontal cross-hairs of unequal length, identification markings of unequal size along, between and at the end of horizontal and vertical cross-hairs, and an aiming dot.

Reticles of the present invention, whether etched on glass, projected, or generated by computer over time in response to learned behavior by the shooter, or selected preferences of the shooter, may have a diversity of markings and features. FIGS. 51a, 51b demonstrate some exemplary features, any one or more of which can be applied to a given reticle. As exemplified in FIG. 51a, in one embodiment, reticles of the present invention comprise cross-hairs that are, for example, lines, straight lines, uninterrupted lines and interrupted lines. In other embodiments, cross-hairs that are interrupted lines are interrupted, for example, by spaces of equal length, by spaces of unequal length, or by lines of shorter length. The present invention is not limited by the nature of the cross-hairs. Numerous cross-hairs are known in the art, for example, U.S. Pat. No. 3,948,587 to Rubbert, U.S. Pat. No. 1,190,121 to Critchett,

U.S. Pat. No. 3,492,733 to Leatherwood, U.S. Pat. No. 4,403,421 to Shepherd, U.S. Pat. No. 4,263,719 to Murdoch, herein incorporated by reference. In some embodiments, cross-hairs are interrupted at least once. In further embodiments, interrupted cross-hairs would intersect if segments of the interrupted cross-hairs were linearly connected along their lengths. In still further embodiments, the intersection is located, for example, at the optical center of the reticle, above the optical center of the reticle, below the optical center of the reticle, at the optical periphery of the reticle, or both the optical center and the optical periphery of the reticle.

As exemplified in FIG. 51a, in some embodiments, reticles of the present invention comprise cross-hairs that are of a predetermined thickness, for example a single thickness, a thickness increasing along the length of the cross-hair, or a thickness decreasing along the length of the cross-hair. As shown in FIG. 51b, in some embodiments, a reticle of the present invention comprises cross-hairs of single unequal thicknesses. In other embodiments, as shown in FIG. 51b, a reticle of the present invention comprises cross hairs that vary in thickness along their length in steps. As shown in FIG. 51a and FIG. 51b, in still other embodiments, reticles of the present invention comprise solid cross-hairs of varying thickness. In further embodiments, as shown in FIG. 51c, in some embodiments reticles of the present invention comprise hollow cross-hairs of varying thickness.

As exemplified in FIGS. 51a, 51b and 51c, in some embodiments, reticles of the present invention comprise cross-hairs that are evenly spaced. In other embodiments, reticles of the present invention comprise cross-hairs that are unevenly spaced.

In one embodiment, the reticle of the present invention comprises rangefinder markings. In another embodiment, the reticle comprises markings for identification of one or more of the cross-hairs. As used herein, "markings for identification" refers to, for example, numbers, letters, symbols, words, geometric shapes, hollow shapes, or solid shapes, located, for example on a cross-hair, above a cross-hair, below a cross-hair, at end of a cross-hair, or upon a cross-hair. In some embodiments, markings for identification vary along the same cross-hair. As shown in FIG. 51a, in some embodiments, identification markings are, for example, above a cross-hair, at the end of a cross-hair or superimposed upon a cross-hair. In other embodiments, as shown in FIG. 51b, reticles of the present invention comprise identification markings between cross-hairs. In one embodiment, as shown in FIG. 51a, identification

markings are numbers. In other embodiments, as exemplified by FIG. 51c, identification markings are, for example, a letter, a word or a symbol. As shown in FIG. 51a, identification markings in some embodiments comprise solid dots. As shown in FIG. 51b, identification markings in other embodiments comprising solid dots vary in size. In other embodiments as shown in FIG. 51c, identification markings comprise hollow dots located, for example, at the end of at least one cross-hair.

As exemplified in FIGS. 71a, 71b, 71c and 71d, in some embodiments, reticles of the present invention comprise circles that are unevenly spaced. In other embodiments, reticles of the present invention comprise circles that are evenly spaced. In some embodiments, elements of reticles shown in FIGS. 71a, 71b, 71c and 71d are combined with elements of reticles described elsewhere herein. In particular embodiments, reticles shown in FIGS. 71a, 71b, 71c and 71d are configured for use by an entry level marksman, a designated marksman, or a sniper marksman.

As exemplified in FIGS. 73a, 73b, 73c, 73d, and 73f, in some embodiments, reticles of the present invention comprise a partial aiming ring configured for use by an entry level marksman, a designated marksman, or a sniper marksman. In some embodiments, for example, for the entry level marksman, the reticles comprise lead markings up to 60 miles per hour to engage fast walkers up to vehicles, an inner ring for man-sized targets, an outer ring for alignment in contrasting and low light conditions, a hold point at the bottom of an inner circle for 400 meter aiming, and markings for proper alignment to assure cheek weld and hold. In some embodiments, as further configured for a designated marksman, the outer heavy partial ring disappears at high magnification while other features are retained. The reticle further provides a rangefinder, slanting broken line wind holds, for 10 to 20 mile per hour wind velocity and 3 to 9 o'clock wind direction, pre-calculated moving target lead holds, and elevation holds within the inner circle. In other embodiments as configured for the sniper marksman, reticles of the present application further provide markings for second shot correction and long distance aiming.

As exemplified in FIGS. 73a, 73b, 73c, 73d, and 73f, in some embodiments, reticles of the present invention comprise one or more of horizontal lines, vertical lines, interrupted lines, slanted lines, closed circles, open circles, ovals, lines that are not perpendicular or horizontal, lines of different lengths, lines of different weight lines, and/or lines comprising dots, and

pluses (+). As exemplified in FIGS. 73a, 73b, 73c, 73d, and 73f, in some embodiments, reticles of the present invention are used in a first or second focal plane of an optical device, or a fixed power device, and/or in a digital or optical electric device that can increase or not increase the image size of the reticle. In some embodiments, the reticles comprise a circle or circles and ovals for point and shoot aiming. In other embodiments, the reticles comprise ovals or polygonal drawings drawn, for example, to represent a specific target when viewed at a specific distance. In some embodiments, drawings are placed at a specific location on a reticle so that a drawing ballistically matches the target size and distance from the weapon with the ballistics of the projectile. In other embodiments, the reticles comprise slanted, non-perpendicular lines that are ballistically calculated to match a projectile's performance when wind or air motion is a factor. In further embodiments, the reticles comprise a line that is slanted that is ballistically calculated to match the intercept point for an object traveling at 4mph. In other embodiments, the reticle is calibrated to perform in Mils, TMOA, SMOA, metric, and English units, and the like. In some embodiments the reticles comprise a separate rangefinder. In certain embodiments, the reticles are illuminated or not illuminated. In some embodiments, the reticles comprise a central targeting circle for point and shoot aiming, and to center the reticle in the field of view. In further embodiments, the reticles comprise a heavy line weight horizontal cross-hair. In other embodiments, the reticles comprise an open or closed circle of heavy line weight. Reticles of the present invention perform, for example, at high and at low magnification. In some embodiments, reticles comprise aiming points on one or more horizontal cross-hairs that mark leads for one or more moving objects.

In some embodiments, reticles of the present invention provide a single reticle and rifle scope configured for the use of shooters with tiered skill levels: for example, Entry Level Infantry Riflemen; Designated Marksmen; and trained Snipers. Multiple regions of the reticles may be configured to fit the ballistic performance of a specific cartridge or cartridges, so that the reticles may have ballistic reference points for hold over and windage, which allow a shooter to point and shoot, with an infantry effective range point blank to 300 meters, and a designated marksman effective range point blank to 600 meters. In some embodiments, ovals of varying sizes are provided to match the size of a 12 inch target when viewed through an optical instrument at selected ranges. In some embodiments, ovals are placed on ballistically pre-calculated cross-hairs of the reticles. The combination of oval size and placement on the reticle yields accurate shot placement at extended ranges.

In some embodiments, reticles are used in a 2nd Focal Plane variable power riflescope, with the entry level portion configured for use at lowest magnification, and designated marksman portions configured for use at higher magnification. In some embodiments, reticles of the present invention comprise wind hold lines. In other embodiments, reticles of the present invention are configured to engage moving targets at any magnification. In certain embodiments, the reticles comprise a 4 mph lead hold line that may also be provided in meters, kilometers and similar units of distance per unit time. In further embodiments, reticles of the present application provide multiple sighting circles within the field of view. In some embodiments, a center circle designates a target zone from point blank range to longer range. In further embodiments, reticles of the present invention comprise accurate, passive range finding markings that eliminate the need to provide additional range finding equipment. The range finder may be calibrated in any unit of distance within military MIL-SYSTEM markings or within a main targeting grid. Reticles of the present invention may be configured for use with any cartridge or grouping of cartridges with markings that, in some embodiments, overlay generic markings.

As exemplified in FIGS. 73a, 73b, 73c, 73d, and 73f, reticles of the present invention are configured for military and recreational use. For example, reticles configured for the NATO 7.62x51 (308 Win) cartridge and the NATO 5.56 (Remington 223) 77gr cartridge are described.
As exemplified in FIGS. 73a, 73b, 73c, 73d, and 73f, a single reticle is able to accommodate three levels of use: #1. The Entry Level Infantry Rifleman, #2. the Designated Marksman, and #3. The Trained Sniper.

To accommodate the entry level user who has little or no knowledge of using a riflescope and its reticle to hit and dispatch targets, features of reticles described herein as exemplified in FIGS. 73a, 73b, 73c, 73d, and 73f are pre-calculated ballistically to match military cartridges. Pre-calculated ballistic manufacture enables very fast point and shoot engagements, yet assures high accuracy. The entry level rifleman need only use a portion of the reticles of the present invention (for example, Figs. 73a and 73b) to engage targets from point blank to effective ranges. The average shooter may learn the skills to understand/use the reticle in less than 1 day with at least 60 rounds of ammo on the range to obtain a gross level of proficiency. With minimal training, the entry level shooter is able to engage targets with

confidence from point blank to effective range. Engagements of moving targets are simplified by using mile per hour (MPH) markers or hold points on the primary horizontal crosshair. Once a weapon and rifle scope are initially zeroed, the shooter does not have to make any further adjustments of the elevation and windage turrets.

To accommodate the 2nd tier of military advanced rifleman, "The Designated Marksman (DM)". se of the embedded special features allows the DM to accurately engage targets from point blank out to 600 meters. Pre calculated ballistic design features allow the DM to execute shots without the aid of a "ballistic calculating device (i.e., IPAC handheld device or Trimble handheld device, KESTREL, Phone or Ipads). To determine range and elevation hold point, the DM places the "head" of the enemy combatant into the appropriate oval that matches in size and presses the trigger of the weapon. If a wind is blowing, the DM can obtain the proper hold by using the slanted dashed wind lines to obtain a windage hold. Horizontal holds for walking targets or moving vehicles are provided.

To accommodate the most advance military rifleman, reticles as exemplified in Fig 73f provide elements needed for long range accuracy to place the projectile on target using targeting/ballistic software to calculate hold over and windage.

For example, an entry level soldier has completed 8 months of training after enlisting in the Army and is given an M-14 rifle equipped with 3.5x21 variable power, first focal plane riflescope featuring a reticle of the present invention designed to accommodate the entry level marksman. Using 60 rounds of 175grain 7.62x51 ammo the soldier's first task is to obtain a 100 meter zero. After adjusting the scopes windage and elevation knobs, the soldier achieves a 100 meter zero by only expanding 10 rounds of ammo, and is told that it is no longer necessary to adjust the windage and elevation knobs on the scope. As the soldier engages a variety of targets from very close to infantry effective range (300 meters), he notes how the dark, horse shoe shaped ring and the lighter inner ring help focus rapidly on the targets, and assure correct cheek weld and proper hold of his M-14 rifle. Rings enable use of a first focal plane riflescope/reticle at the lowest power wherein the reticle is otherwise very small and difficult to use. At high magnification (16x plus) or at the lowest power (3.5x), the soldier does not have to use crosshairs. He simply has to place the target in the center of the inner circle. Use of a circle as the aiming point, reticles of the present invention resolve the problem of finding the crosshair aiming point because the eye centers a target within the

circle. The outer heavy horseshoe shaped ring assists in contrasting and /twilight conditions, and helps the eye center the target within the inner ring.

When shooting beyond "infantry effective range" (300 meters) at moving targets the shooter. uses "OVALS" on the vertical crosshair for extended range shots. To hit a target at 165 yards the soldier centers the target within the reticle's inner circle. To hit a second target in a doorway at 90 meters , the issue of contrasting light is resolved because of the thick horse shoe shaped ring that makes target placement within the inner ring straightforward. To engage a target in a truck at approximately 109 meters distance traveling from the left to right at approx. 40 mph. the soldier uses the leads on the main horizontal crosshair on the 40 mph indicator lead mark of the left side. If the bullet impacts on the dirt road slightly ahead of the truck, the soldier adusts his aiming point to a position on the reticle between the 30 mph and the 40 mph lead indicator on the right side.

The designated marksman is issued an M-24 bolt action rifle with a variable (3.5x to 21x) first focal plane riflescope with a reticle of the present invention. The rifle is chambered for the 7.62 x 51 cartridge. For "DM effective range" (600 meters), the soldier learns that when employed at DM effective range the reticle can be used as a stand-alone device not requiring a separate range finder, Kestrel weather unit or a ballistic calculator. Using the "OVALS" located on the main vertical cross-hair of a reticle of the present invention, the solider identifies the appropriate "OVAL" that allows the target to match the size of the OVAL. Use of the ballistic/range appropriate "OVALS, precludes use of any type of a rangefinder. By using the "OVALS", the soldier is provided a pre-calculated elevation hold point. The soldier also has the option of using the rangefinder on a reticle of the present invention. With the wind at 10 mph blowing from the left to the right, the soldier uses the reticle's hold point located horizontally from the "OVAL that matches the *target*size for proper windage hold. For windage the soldier moves his aim point horizontally until it intersects on the 10 mph wind line on the right side. In the event the soldier misses the target, he can rapidly correct his shot by employing "Horus's 2nd Shot Correction". The soldier observes a target walking from right to left, at an estimated range of 200 meters. He centers the target within the inner ring of the reticle then moves his hold along the main horizontal cross hair to the intersection with the right edge of the inner circle. The edge of the inner circle gives the the lead he needs to engage a target that is moving at approx. 4 mph.

A sniper is issued an M-24 Bolt Action Rifle equipped with a variable (3.5 to 21x) 1st focal plane riflescope that shoots a 7.62 x 51 NATO cartridge, with a reticle of the present invention, A-TRAG Ballistic Software by Horus, a Kestrel weather unit, and active and passive range finding. The soldier takes a position on the roof of a 5 story building with his spotter, who is using a Leupold 12-40x 50 spotting scope with a H-32 Horus reticle. The spotter identifies a target. Another target approaches the first target. The shooter has the 2 individuals in his field of view. The spotter using a PLRF 15 rangefinder by Vectronix determines thee range to be 901 meters. The PLRF is connected directly via cable to the Trimble Recon handheld device loaded with A-TRAG military software. A Recon handheld device generates an immediate firing solution of 11.1 MILS elevation. Since the air is still, the shooter does not need to enter windage information. The shooter holds on the vertical crosshair exactly 11.1 MILS down from the main horizontal crosshair for target #1. The spotter identifies Target #2 at 2:00 O'clock from Target#1 approximately 30 meters further out. The shooter asks the spotter to spot for a SECOND SHOT CORRECTION shot. The shooter shoots at Target#2 using an 11.0 MIL hold. The spotter using the reticle in the spotting scope noted the bullet hits 1.0 MIL low and relayed that data to the shooter. The shooter places Target #2 on the vertical crosshair, exactly 12.0MILS down from the main horizontal crosshair. The shooter identifies Target #3, walking toward Target #1. The shooter holds his horizontal hold to the right until he reaches the continuous 4 MPH walking man line. Elevation is11.0 MILS down from the main horizontal cross hair.

The shooter and spotter team are assigned to a position on a high ridge overlooking a small trail along the base of an adjacent steep rock formation. The shooter uses his Kestrel weather unit to update his atmospheric data on his NOMAD unit by TRIMBLE. The spotter uses his Leupold Spotting Scope to scan for targets hidden among the rocks opposite to their position. The shooter uses an integrated connector cable connected to the NOMAD ballistic computer with TRAG 4.0 software and a Leica Vector 4 laser Range finding 7 x 50 binoculars.
After 5 hours of glassing the trail the shooter identifies a group of 6 targets making their way along the trail. With his spotting scope, the spotter identifies an additional target. The team decides to wait until the Targets 1- 7 7 are at a position closer to the team. Since Targets 1 thru 6 are traveling close to each other and Target #7 is trailing behind by several hundred meters, the shooter plans to engage Targets 1 - 6. Calculating elevation and windage holds for a firing position located at a steep angle upward from the trail that Targets 1- 7 are using is difficult. The Vector 4 unit in combination with the TRAG 4.0 software loaded in a

NOMAD unit yields a solution. As Targets 1-6 are getting closer, they stop. Using the Vector 4 unit, the spotter identifies and lasers Targets #1 & #2. The spotter calls the firing solution.

DATA PREVIOUSLY INPUTTED AND DATA FROM VECTOR 4 UNIT
Temp…..50 F
Bar. P……21.5 Hg Range….. 837 Meters Target speed 0
Rel. Hum .. 60% Angle In…45 degrees
Wind Left to right--- Full value 5MPH
The Vector Unit provides the range, angle of inclination, and direction of fire and inputs the data directly to the NOMAD unit which provides a firing solution at 5 MPH full value wind i.e., 5.37 MILS on elevation and 0.97 MILS on the right for windage.

The shooter now focuses on Target #7. The spotter calls a firing solution immediately after lasering the Target.

Range……..1056 meters Target speed…..approx 6MPH
Angle IN. …34 degrees Target moving directly towards HIDE (no lead)
Wind Speed 5 MPH
Wind 2:00 O:clock (left to right)
The vector unit handled the Angle In., Range, Direction of Fire, and feed data to the NOMAD handheld device which gave a firing solution. Wind and Target speed and direction was manually inputted.

The spotter relays the firing solution to the shooter of 9.71 MILS of Elevation and 0.77 MILS on the right side of the main vertical horizontal crosshair. No lead value is provided since the Target #7 is running directly towards the team's position. The shooter holds 9.71 MILS directly below the main horizontal crosshair and 0.77 MILS right for windage.

As exemplified in FIGS. 74a, 74b, 74c, 74d, and 74g, in some embodiments, reticles of the present invention comprise heavy line thickness of value in contrasting light conditions and

brush cover, and use of ghost rings for use at close range. In some embodiments, reticles of the present invention comprise frequent holds for popular cartridges and calibers, proper centering to assure cheek weld and weapon hold, an inner ring for targets within 200 yards, and block markings for targets within 300 yards. In some embodiments, reticles of the present invention provide range finder markings. In other embodiments, markings for second shot correction are provided. In certain embodiments, A-TRAG software is used to provide range cards (Figs.76a and 76b) for use with reticles of the present invention.

In one embodiment, the present invention comprises a method for shooting a target comprising a target acquisition device comprising a housing, a means for mounting the housing in a fixed, predetermined position relative to a firearm, an objective lens mounted in one end of said housing, and an ocular lens mounted in the opposite end of said housing; a reticle comprising a plurality of primary cross-hairs separated by predetermined distances, a plurality of secondary cross-hairs at predetermined distances along said plurality of primary cross-hairs, and a plurality of lead markings indicating rate of movement of the target along at least one said cross-hair; a ballistics calculator system for computing targeting information to hit a target comprising a processor comprising a ballistics computer program for analyzing information needed to accurately aim a firearm at a target using a target acquisition device with a reticle, with the program using information regarding one or more of external conditions, the firearm being used, the projectile being used, the target acquisition device and reticle being used, the shooter, the relation of the shooter and the target, wherein the target can be greater than 1000 yards from the shooter, the ballistics drag model and retardation coefficient being used (for example, G1, G5, G6, G7, GI, GS (Round ball), GL, RA, Ingalls, and custom drag models based upon the actual bullet being used), and selecting an aiming point on the target acquisition device that accounts for the relation of the shooter to the target, and using the targeting information displayed by the ballistics calculator system to aim the firearm so as to hit the target. In some embodiments of the present invention, the ballistics calculator enables the user to match projectile shape to standard or custom drag models. In some embodiments, the user selects an exterior ballistic calculation method from a menu, including, for example, the Siacci analytical method of solution, numerical integration solutions using the drag models developed by Maievski, Ingalls, the Gavr s Commission and the British 1909 Commission, point-mass numerical integration using standard reference projectiles, point-mass numerical integration using Robert L. McCoy's McDrag algorithm, modified point-mass models, and 6-Degrees-Of-Freedom (6DOF) models. In other

embodiments, the ballistics calculator of the present invention calculates the adjusted coefficient of drag for a projectile that may or may not be different from the standard sea-level ballistics coefficient. The ballistics calculator of the present invention is able, as an option, to convert the coefficient of drag to custom drag models and ballistics coefficients for any drag model using velocity or bullet dimension. In further embodiments, the ballistics calculator of the present invention calculates vertical and horizontal cant error at zero range for the entire projectile path. In some embodiments, for high elevation firing, the user selects, for example, one coefficient of drag for a range of less than or equal to, for example, 1000 yards, a second coefficient of drag for 1000 to 1500 yards, a third for greater than 1500 yards, and an optional fourth coefficient of drag for use at very high altitudes. In a preferred embodiment, the target is hit by holding the aiming point on the target.

In a particularly preferred embodiment, the ballistics calculator system of the present invention takes account the reaction time of the shooter in targeting a moving object. As used herein, "reaction time of the shooter" refers to the time elapsed between the decision to shoot is made and an indication of the decision is provided to the firearm or ballistics calculator system. In some embodiments, the indication of the decision is transduced by, for example, shooter movement or voice. In other embodiments, the indication of the decision to shoot is transduced by a physiologic variable of the shooter, for example, electroencephalogram, electromyogram, or evoked surface potential. In further embodiments the reaction time of the shooter is measured and entered into the ballistics calculator system. In other embodiments, the reaction time of the shooter is estimated, for example, to be rapid, intermediate, or slow and entered into the ballistics calculator system.

In other embodiments, the ballistics calculator system of the present invention takes into account the lock time of the firearm in targeting a moving object. As used herein, "lock time of the firearm" refers to the time elapsed between receipt of the signal indicating the decision to fire, and discharge of the firearm. In some embodiments, the lock time of the firearm incorporates transduction by, for example, mechanical, chemical, electronic or optical means. In other embodiments, the lock time of the firearm is measured and entered into the ballistics calculator system. In other embodiments, the lock time of the firearm is estimated, for example, to be rapid, intermediate, or slow, and entered into the ballistics calculator system. In preferred embodiments, the ballistics calculator system takes into account both the reaction time of the shooter and the lock time of the firearm in targeting a moving object.

In one embodiment, the reticle and ballistics calculator system of the present invention is used to target an object moving in 3 dimensions. For example, in one embodiment, the reticle and ballistics calculator system acquires (for example, visual, IR, or radar) images, stores and digitally compares moving images on the reticle at distinct points in time, using the change in image dimensions to calculate the rate of travel in three axes. This data is then used to calculate the directional vector, velocity and acceleration of the target, and provide an aiming solution. In a further embodiment, calculation of rate of travel in three axes is integrated with continuous laser or other tracking.

In one embodiment of the present invention, a method for shooting a target is provided in which the shooter superimposes an aiming dot projected on the reticle over the moving target as the ballistics calculator system of the present invention aligns the barrel so that the target is hit. In this embodiment, the shooter strikes the target by dynamically tracking the target in alignment with the aiming dot projected on the reticle as compensatory aiming adjustments are made to the alignment of the firearm so as to strike the target. In a further embodiment of the present invention, a method is provided for shooting a target in which the shooter aligns a fixed point on the reticle to an aiming point projected by the ballistics calculator system (which may not be superimposed on the target image) so that the target is hit. In this embodiment the shooter does not track the target with an aiming dot, but rather the shooter aligns a fixed point on the reticle with an aiming point projected by the ballistics calculator which accounts for the position of the target in relation to the shooter at the moment of impact and calculates an aiming solution.

In one embodiment of the present invention, a method of shooting a target is provided in which serial range data is used by the ballistics calculator system to customize a projected reticle specific for the combination of one or more of the firearm, the projectile, the target acquisition device in use and the target. In this fashion, the ballistics calculator system of the present invention is used to create a projected reticle that is customized for the specific internal, external and terminal ballistics of the firearm, target acquisition device, and projectile being used, as well as the target. In some embodiments, the shooter begins with a generic projected reticle before modification with automated entry of actual range data using the specific system. In these embodiments the generic projected reticle incorporates incremental range data after each shot is fired, and its point of impact is correlated with the

aiming point. In further embodiments, the user may optionally delete or edit actual range firing data. In still further embodiments, the user may select features of the projected reticle (for example, line spacing, width, and secondary markings) as detailed elsewhere in this Specification.

For example, in some embodiments, after deployment in a combat zone a soldier is ordered back to a training center to evaluate products that provide integration with military products in combat use including riflescopes in the first focal plane with a power range of 3.5 to 25 powers, and reticles described herein (as shown, for example, in FIGS. 71a, 71b, 71c and 71d) configured, in some embodiments, to illuminate a "hold point" to rapidly dispatch a target. The riflescope comprises several means to transfer data from, for example, a Horus Recon or Nomad unit using, in some embodiments, a cell phone to upload targeting data as an alternative to handheld device-based equipment. The shooter's first task was to gain a firm understanding of Horus Vision's Multi-targeting A-TRAG 4.0 Software. The soldier uploads Multi-zone Multi-targeting software for use in combat that encompasses, for example, 8 zones in 360 degrees of coverage or, for example, zones that can be made up of lesser degrees of coverage that a shooter determines depending on the area/terrain where his operating position is located. For example, the soldier names up to 12 individual targets at various ranges in ZONE B along a northern road that takes a southern course from his position. The soldier creates a further zone for example, ZONE C and again independently targets up to 12 targets in Zone C.

To achieve ease of use, efficacy and integration with other equipment, the shooter inter-links, for example, a weather station (for example, Kestrel, or ultrasonic wind direction and velocity detector), a GPS (for example, Garmin), a night vision module, a thermal unit (for example, FLIR) a rangefinder (for example, Vectronix), and/or a video inter-link.. Each component may be linked directly to a handheld device, computer, telephone, or other device by hardwire, IR, Bluetooth, microwave, manual input, and the like to yield an instant firing solution after data and a target are selected. For example, after installation of a Trimble Nomad unit with upgraded chip the soldier activates a single use impromptu target function. A 7.62x51, 175gr. cartridge is selected for further testing . Inter-faced with a Kestrel weather-station, Vectronix PLRF 15 rangefinder, and ballistics calculator described herein the soldier selects an area with a 360 degree field of view with distances in some regions extending to several thousand meters. In some embodiments, the solider uses a spotting

scope with High Definition Video embedded, 3 Horus Riflescopes responsive to TRAG 4.0 software that illuminate specific targeting hold points on the reticle with embedded high definition capacity to send and to receive video data activated, in some embodiments, by voice or thought.

The soldier establishes 8 zones of unequal size. The number of targets per zone varies from 4 to 12 independent targets. All distances are verified with a steel survey tape. The first test uses a conventional army issue ballistic computer (for example, Recon by Trimble with Horus 3.83 software). The solider assigns a letter to each zone (i.e., A—B—C—etc). He then assigns a nominal designation to each target (B—4 or Bridgeman) . Using voice and target recognition software, in some embodiments the soldier or his spotter may call out "B—4" or "Bridgeman". The Hold Point for that target would is, in some embodiments, illuminated on a reticle as described, for example, in FIGS. 71a, 71b, 71c and 71d along with the high and low wind holds for the shot. Targeting data is shown on the device that is involved with the computation. In a further embodiment, a firing solution is projected in the field of view of the spotter's spotting scope.

Upon returning to a combat zone, for example, the soldier and spotter test comparable equipment and components. In addition to a M-24 7.62x51 bolt action rifle, the soldier also employs a bolt action 50 BMG Rifle (for example, by G. Mc Millian, Phoenix, Arizona) and a bolt action 338 Lapua by Remington with a 9 twist barrel, equipped with a Mil-spec Picatinney rail. The soldier and spotter establish a position on the roof of a tall building that affords a 360 degree view. Since the building is centrally located in the city, a clear view of at least 2500 meters is offered of both a North road at 005 degrees and a South road at 175 degrees. An Eastern road at 096 degrees is clear for approximately 1250 meters. There is also an extensively damaged building at 031 degrees that the soldier believes to be an enemy sniper hide presently or in the future. The soldier locates another building on the South road at 174 degrees comprising an architecture of interest that could also be concealed sniper position. With his Army-issued cell phone, the soldier enters data. With a TRAG 4.0 Multi-Targeting Software, the soldier identifies the following zones:

ZONE "A": NORTH ROAD
ZONE "B": EASTERN ROAD
ZONE "C": SOUTHERN ROAD

ZONE "D": SMALL DAMAGED BUILD. 031 DEGREES

ZONE "E": BUILD. ON SOUTHERN ROAD "VERY HIGH PRIORITY"

The soldier and spotter survey each zone to establish individual targets of interest within each zone. Using a Vectronix PLFR 15C Unit and issued GPS Unit linked to a cell phone, targeting ID information combined with targeting aim point data is entered:

North road (ZONE "A") upon careful glassing had at least 5 prime possible

Target Position #1	Damaged Home	321 meters	A-1
Target Position #2	Drainage Ditch	540 meters	A-2
Target Position #3	Bridge	839 meters	A-3
Target Position #4	Burned out Truck	1000 meters	A-4
Target Position #5	Ridge (200 ft off Road)	1678 meters	A-5

South road (ZONE "C"):

Target Position #1	Butcher Shop	687 meters	C-1
Target Position #2	Torn-up ROAD	903 meters	C-2
Target Position #3	Ditch	487 meters	C-3
Target Position #4	Road S		
plit Right	1245 meters	C-4	

East road (ZONE "B"):

Target #1	White Junk Car	276 meters	B—1
Target #2	Road Railing	188 meters	B—2
Target #3	Wall	243 meters	B—3

Small Damaged Building at 031 degrees (ZONE "D").

Target #1	Damaged Building	643 meters	D—1

South Road Building at 175 degrees (ZONE "E")

Target #1	Sniper Hide	1065 meters	E—1

The soldier enters data for the M-24, caliber 308 rifle using 175 grain match ammo, Remington, caliber 338 Lapua rifle using 260 grain Ruag's Swiss P Armour Piercing Ammo, and McMillian, caliber 50 BMG using 750 grain HSM A-MAX Super Match T-Coat Ammo. The soldier may verbally or he could manually select input of the weapon. To back-up data in the soldier's cell phone, it is down-loaded to the spotters Trimble Recon unit that comprises TRAG 4.0. All connections between the computing device, spotting scope, riflescope, range finding equipment, etc. are tested for integrity and accuracy.

The spotter examining the area around ZONE "D", the damaged building that was heavily damaged, identifies a small reflection from the 4th story window of "Target #1". The shooter focuses the Horus riflescope on the Remington 338 Lapua on the window. The shooter notes "338***ZONE "D"***TARGET #1", thereby illuminating an aiming dot on the reticle indicating the firing solution.

Carefully observing road repair activity the spotter activates a high definition camera imbedded in the spotting scope which shows real-time images on a lap top computer for a second shooter and spotter team to view the area. The spotter notes two men exiting a taxi carrying what an artillery shell. The spotter ranges them with the Vector IV unit. Using a McMillian 50 caliber rifle with A-Max 750 grain Super Match ammunition, the spotter provides a new range of 951 meters verbally into the cell phone unit for Target Position #2. The shooter comments "***50***ZONE "C"***TARGET #2***" on his cell phone to trigger calculation of a precise firing solution, which is downloaded to the riflescope. An illuminated dot appears on the reticle that indicates the firing solution. The second shooter and spotter team identifies a man at a butcher shop hiding behind a hanging carcass with a pair of binoculars looking down the South Road at the approaching repair vehicles. He appears to have a cell phone in his hand suggesting a hidden IED. The shooter comments "***50***ZONE "C"***TARGET #1***" on his cell phone. An illuminated dot appears on the reticle that indicates the firing solution.

In some embodiments compositions of the present invention provide portable, hand-held devices configured to perform multiple tasks. In some embodiments, the devices can be

encased in one or more materials, for example, metallic, non-metallic, plastic, acrylic, polycarbonate, glass magnetic, conducting, or non-magnetic, non-conducting materials. In some embodiments, the devices comprise a keyboard, a display, or visual scrolling features. In some embodiments, the devices require an electrical energy source, for example, solar, battery, wind, or heat source of energy. In some embodiments, the devices are configured to calculate, for example, to calculate an aiming solution with an embedded formula and inputted data. In some embodiments, the devices support externally loaded memory gathering devices including, for example such, a chip, a thumb, a CD, a DVD, or other computer readable media. In some embodiments, the devices are shielded from internet or external sources of data and energy. In some embodiments, the devices are enclosed in a Faraday cage or enclosure. In some embodiments, the devices comprise sensors to measure meteorological data. In some embodiments, the devices support ballistic and/or targeting data. In some embodiments, the devices are configured to capture and record electronic and/or digital data including, for example, digital audio, visual, or other sensory data. In some embodiments, the devices are protected from in hardware and software from hacking, tracking, or compromise by electronic external devices. In some embodiments, the devices calculate and predict meteorological data, for example, dew point, density altitude and the like. In some embodiments, the devices have ports to transfer and download data via cable or other physical interface. In some embodiments, the devices comprise a display screen to depict data or images. The screen may be illuminated with a single or multiple lights of different frequencies. In some embodiments, the devices are GPS capable including, for example, navigation, time, lunar, solar, planetary and stellar data. In some embodiments, the devices comprise embedded illumination that may be used, for example as a strobe. In some embodiments, the illumination can be varied in intensity or in frequency. In some embodiments, the devices comprise radiation detection circuits including, for example, circuits that detect and display ambient radiation levels. In some embodiments, the devices comprise sound amplification devices. In some embodiments, the devices capture and record sound. In some embodiments, the device is configured to adjust the intensity, frequency and content of auditory input and output. In some embodiments, the devices are connected to a multiple distinct devices via cable or electronic transfer. In some embodiments, data that is imported can be used to calculate solutions to problems. In some embodiments, data is shown on the device display.

In some embodiments, devices of the present invention integrate multiple technologies in a single portable, pocketsize or smaller, low cost, robust device of utility to, for example, the nature enthusiast, hunter, fisherman, hiker, birdwatcher, survivalists, and the like to enhance and protect their experience in the outdoors or indoors. Using the devices of the present invention, a user wishing to head into the field doesn't have to worry about placing the device on a charger. An AA battery which can be purchased anywhere in the world suffices, with additional space provided in the unit for a separate battery. In some embodiments, users are provided a personal device that is not, and cannot be, connected to the World Wide Web with its attendant fees and payments for special applications including, for example, location applications (ABS), ballistic/targeting, birds-animal-fish identification, ability to store details and numbers without a "cloud", ability to capture photos/video and transfer data to another electronic device all without the Web or Blue tooth. Devices of the present invention comprise a unit with a port for UBS, hearing jack, and 9-pin or multi pin cable plug ins. Transfer of data is assured by direct wire transfer or IR transfer. The convenience of not being connected or dependent on the Web provides liberty and privacy from, for example, utility companies, governments, energy disruption (*e.g.*, solar disturbance, electro-magnetic pulse) that may shut down other devices. Devices of the present invention are configured to not be hacked, or to have their location trackable. In some embodiments, a handheld device of the present invention cannot be hacked nor can its location be tracked via any signature.

Because weather plays a substantial role to those venturing afield, for example, the shooter who relies on ballistics, home gardeners, aviators, farmers, and the like the devices of the present invention have sensors to depict ambient meteorological data. Readings for barometric pressure, temperature, relative humidity, and wind speed can be shown on the device's viewing screen. With a touch of the display, or by pushing or scrolling, calculated answers for "Dewpoint", "Windchill", "Density Altitude", "Heat Stress" and the like may be displayed in English, metric or other units as preferred by the user. GPS location capacity to target sites of interest, hours of sunrise and sunset, moonrise and moonset, and times that are legal for hunting and fishing in minutes, hours, days, weeks, months and years are provided, together with built-in screen illumination. In some embodiments, an LED is built into the devices of the present invention that may be used as a flashlight. In case of an emergency, the LED flashlight can be made to pulse like a strobe which to facilitate rescue.

For personal safety, devices of the present invention comprise, in some embodiments, a radiation sensor configured to detect and depict radiation levels of varying kinds and intensities. In some embodiments, devices of the present invention may be used, for example, to screen food for radiation safety. In further embodiments, an embedded, sensitive microphone and amplification device enables the user of devices of the present invention, to hear and identify quite sounds of nature such as a birds singing or the mating calls of forest animals. For those who may have forgotten their hearing-aids, devices of the present invention provide a substitute implement useful, for example, to speak with a significant other or enjoying a night a night at the movies or symphony. Auditory amplification components require only that the user places the plug-in ear- bud properly, and press the appropriate button. If desired, recordings of conversation, music, video images etc. may also be made. In some embodiments, devices of the present invention are configured to monitor physical variables of the user, for example, blood pressure, temperature, heart rate and rhythm, oxygen saturation, carbon dioxide secretion, blood and urine chemistry, transcutaneous chemistry, and the like. In some embodiments, devices of the present invention comprise a camera, a mathematics calculator, a statistics calculator, a calendar, or an actuarial calendar. In further embodiments, devices of the present invention comprise a high definition camera with, for example, night vision capacity using, for example, thermal/light amplification.

For sportsman and non-military uses, devices of the present invention may be encased in inert, robust, impregnable material including, for example, plastic, nylon, acrylic, metal and the like. Military and special purpose devices of the present invention may be enclosed in a Faraday Cage to eliminate both internal and external RF leaving or entering the device. Elimination of RF precludes detection and location by hostile combatants, and hacking and tracking of users. In some embodiments, devices of the present invention are impervious to an EMP or large amounts of external energy that may alter performance of the unit, or destroy circuitry. In some embodiments, devices of the present invention comprise stand-alone, ruggedized units configured for use in extreme environment, for example, high and low heat, high and low humidity, high and low radiation, high and low magnetism, high and low pressure, vacuum and the like.

In some embodiments, devices of the present invention are configured to connect to range finders of various makes and manufactures, for example, the Vectronix PLRF 15c. In

operational mode, devices of the present invention calculate data input from a rangefinder, target GPS position, ambient weather, angle of inclination, compass, ballistic and firearm information and the like to yield a ballistic targeting solution.

In some embodiments, devices of the present invention comprise a ballistics calculator configured for the shooter to track, and display solutions for multiple targets. Multiple targeting solutions are provided in some embodiments in tabular form comparable to a spreadsheet *i.e.,* a customized range card compared to conventional equal-increment. Devices of the present invention are configured for users to assign custom names to targets such as "tree", "big rock", "stream" and the like. Because targets do not enter a field of opportunity at equal increments and distances, targets can appear anywhere. Instead of calculating an actual solution between predetermined solutions, devices of the present invention enable users to customize a range card so that a target that wanders into, for example, a field near a big-rock already has an exact solution associated with it on the customized range card. Devices comprising ballistics calculators or the present invention, organize targets into zones via compass angles, for example 0°-50° may be zone A, 90°-123° may be zone B, etc. The zones may be defined in equally distributed degrees (10°-20°, 20°-30°, 30°-40°, etc.) or custom defined by user. The zones may also be assigned names such as: "down the valley", "west trail", "tree path" and the like. The combination of targets organized by zones provides the capacity to define and control a full field of opportunity with hold-over and windage solutions without the user having to flip back and forth between notes or re-inputting data. Instead, the user looks up "stream" in "down the valley", and the solution is immediately available.

Conventional ballistic calculators and ballistic calculator devices require the user to manually input parameters gathered from other instruments manually. In some embodiments, devices, software, processors, controllers and computer readable media of the present invention connect to other instruments via, for example, direct wire, BlueTooth TM, optical, radio, infrared or other communication channels and hardware, thereby automatically accessing information needed to derive ballistics solutions. For example, devices of the present invention may take, atmospheric and wind data from weather meters and anemometers or web or radio, distance information from Laser Range Finders (LRF), etc., cant and angle of fire information from inclinometers, direction of fire or compass heading information from compasses, or astral-orientation, current position information from GPS or other location

means, or projectile properties and speeds from measuring and tracking instruments (for example, Doppler data, chronographic data, etc.). As well, conventional ballistic calculators and ballistic calculator devices presume a static shooting position. In some embodiments, devices, software, processors, controllers and computer readable media of the present invention provide tracking of shooters and targets via geo-location data (for example, GPS, latitude-longitude data, etc). In this fashion, the user may "tag" and track multiple targets 360° around the shooting position producing, for example, a shooting solution to each target. The user moves or changes position, relative locations to the target, and shooting solutions to each target, are recalculated to reflect current position of shooter. Third parties, for example, spotters and second shooters, may input locations other than a given target's current solution and have all targets/solutions adjust relative to the input position. Thus a user can calculate solutions for another shooter in a different location using the devices of the present invention. Conventional ballistic calculators and ballistic calculator devices derive aiming solutions for stationary shooters and targets. Devices of the present invention take data for moving targets and calculate solutions thereof, and provide further solutions when the shooter is also moving. In this fashion, devices of the present invention provide real-time aiming solutions for a dynamic environment. In some embodiments, devices of the present invention are configured to be communications "black box" hubs that assemble, accumulate and constantly update all data available and transmit the data in any format to any receiver via any means. The receiver can therefore obtain information pertaining to atmospherics, target(s) location and movement, and shooting solutions to targets particularly in relation to a relative shooter's position.

All publications and patents mentioned in the above specification are herein incorporated by reference. Various modifications and variations of the described compositions and methods of the invention will be apparent to those skilled in the art without departing from the scope and spirit of the invention. One skilled in the art will recognize at once that it would be possible to construct the present invention from a variety of materials and in a variety of different ways. Although the invention has been described in connection with specific preferred embodiments, it should be understood that the invention should not be unduly limited to such specific embodiments. While the preferred embodiments have been described in detail, and shown in the accompanying drawings, it will be evident that various further modification are possible without departing from the scope of the invention as set forth in the appended claims. Indeed, various modifications of the described modes for carrying out the

invention which are obvious to those skilled in marksmanship, computers or related fields are intended to be within the scope of the following claims.

CLAIMS

What is claimed is:

1. A ballistics calculator system for computing targeting information to hit a target, comprising a processor, said processor comprising: a ballistics computer program for analyzing information needed to accurately aim a firearm at a target using a target acquisition device with a reticle, said program using information regarding one or more of: a) external conditions; b) the firearm being used; c) the projectile being used; d) the target acquisition device and reticle being used; e) the shooter; f) the relation of the shooter and the target; g) the directional sensor being used; and h) the ballistics drag model and retardation coefficient being used, wherein said information regarding external conditions comprises wind speed information from an ultrasonic wind detector.

2. The ballistics calculator or claim 1, further comprising a display screen.

3. The ballistics calculator of claim 1, wherein said information regarding said reticle being used comprises a reticle comprising:

a) a primary horizontal cross-hair;

b) a primary vertical cross-hair that intersects said primary horizontal cross-hair;

c) two or more vertical lead markings upon said primary horizontal cross-hair;

d) two or more horizontal line rangefinder markings above said vertical lead markings to the left of said primary vertical cross-hair and two or more horizontal line rangefinder markings above said vertical lead markings to the right of said primary vertical cross-hair;

e) two or more evenly spaced simultaneously visible straight line secondary horizontal cross-hairs on said primary vertical cross-hair below said primary horizontal cross-hair; and

f) two or more simultaneously visible straight line secondary vertical cross-hairs on said simultaneously visible straight line secondary horizontal cross-hairs below said primary horizontal cross-hair, wherein an intersection of at least one of said two or more simultaneously visible straight line secondary vertical cross-hairs and at least one of said two or more simultaneously visible straight line secondary horizontal cross-hairs provides an aiming point.

4. The ballistics calculator of claim 1, wherein said primary horizontal cross-hair is an interrupted straight line and wherein said primary vertical cross-hair is an interrupted straight line, further comprising an aiming dot at an interrupted intersection of said primary horizontal cross-hair and said primary vertical cross-hair.

5. The ballistics calculator of claim 1, wherein two or more of said secondary horizontal cross hairs are of equal length, and two or more of said secondary horizontal cross-hairs are of unequal length.

6. The ballistics calculator of claim 1, wherein said reticle comprises an aiming point at an intersection of said primary vertical cross-hair and said primary horizontal cross-hair, wherein said ballistics computer program provides an output on said display of a number of clicks an elevation knob and a windage knob should be turned to adjust a position of said target acquisition device relative to said firearm such that said intersection of said primary vertical cross-hair and said primary horizontal cross-hair is the aiming point for striking said target.

7. The ballistics calculator of claim 2, wherein said ballistics computer program directs said processor to display an image of said reticle on said display screen.

8. The ballistics calculator of claim 1, wherein said ballistics computer program is configured to receive input information regarding said external conditions, said firearm, said projectile, said target acquisition device, said shooter, said relation of said shooter to said target, wherein said target can be greater than 1000 yards from said shooter, and said ballistics drag model and ballistic coefficient.

9. The ballistics calculator of claim 1, wherein:

a) said information regarding said external conditions is selected from one or more of temperature, barometric pressure, relative humidity, wind-speed, wind direction, hemisphere, latitude, azimuth and altitude;

b) said information regarding said firearm is selected from one or more of the rate and direction of barrel twist;

c) said information regarding said projectile is selected from one or more of projectile weight, projectile caliber, and the muzzle velocity of said projectile;

d) said information regarding said target acquisition device is selected from one or more of type of reticle, power of magnification, focal plane of function, the elevation between said target acquisition device and said firearm, elevation unit, lead unit, and the range at which said target acquisition device was zeroed using said firearm and said projectile;

e) said information regarding said relation between said shooter and said target is selected from one or more of the distance between said shooter and said target, and the speed and direction of movement of said target relative to said shooter; and

f) said ballistics drag model and ballistic coefficient.

10. The ballistics calculator of claim 1, wherein said ballistics calculator is a device comprising a Global Position System (GPS) device.

11. The ballistics calculator of claim 1, wherein said ballistics calculator is a telephone.

12. A method for using a ballistics calculator system, comprising:

a) providing a ballistics calculator system of claim 1;

b) providing a database on a computer readable medium;

c) inputting acquired information and/or information stored on said database regarding one or more of external conditions, the firearm being used, the projectile being used, the target acquisition device and reticle being used, the shooter, the target, and the relation of the shooter to the target;

d) selecting one or more aiming points on said ballistics calculator system; and

e) using the aiming point information displayed by the said ballistics calculator system to aim the firearm so as to hit the target.

13. The ballistics calculator system of claim 1, wherein said reticle is configured in a first focal plane.

14. The ballistics calculator system of claim 1, wherein said reticle is configured in the second focal plane.

15. The ballistics calculator system of claim 1, wherein said reticle is configured in a combination of the first focal plane and the second focal plane.

16. The ballistics calculator system of claim 1, wherein said reticle is configured in a fixed power target acquisition device.

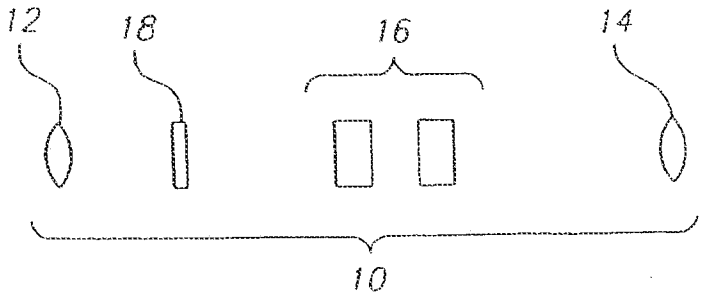


FIG. 1

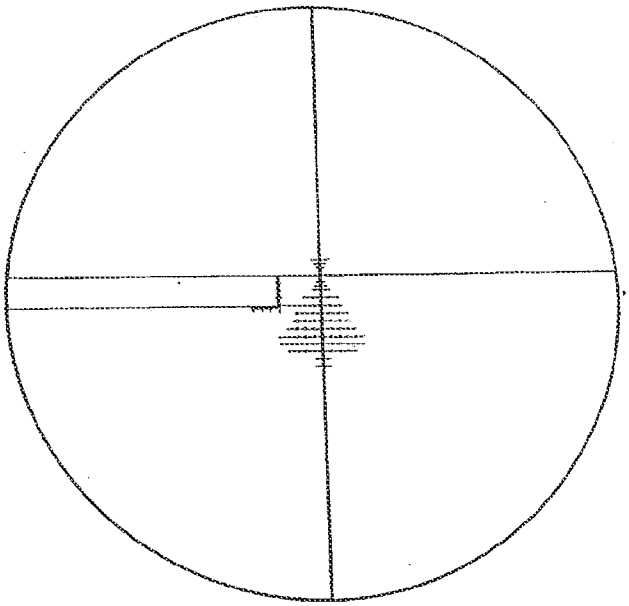


FIG. 3

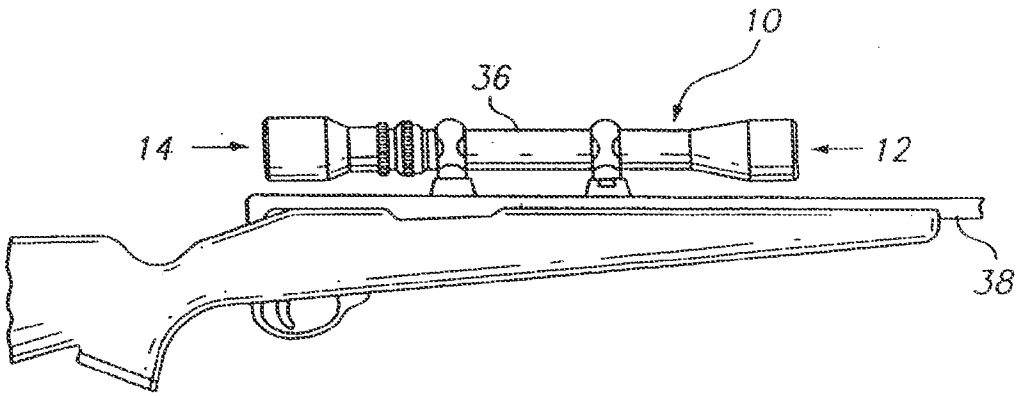


FIG. 4

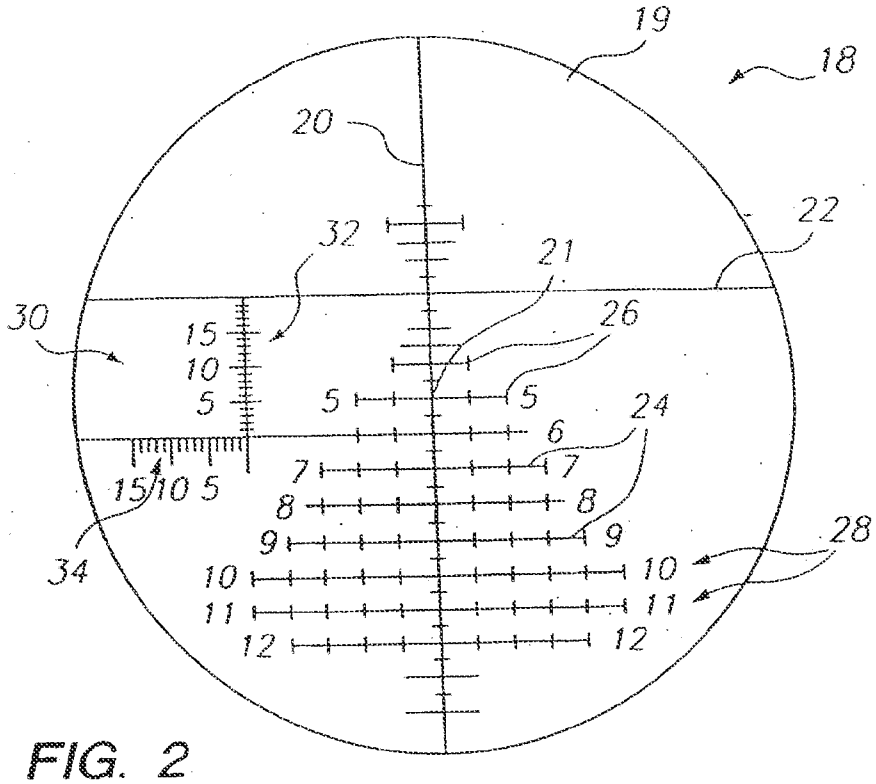

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FIG. 2

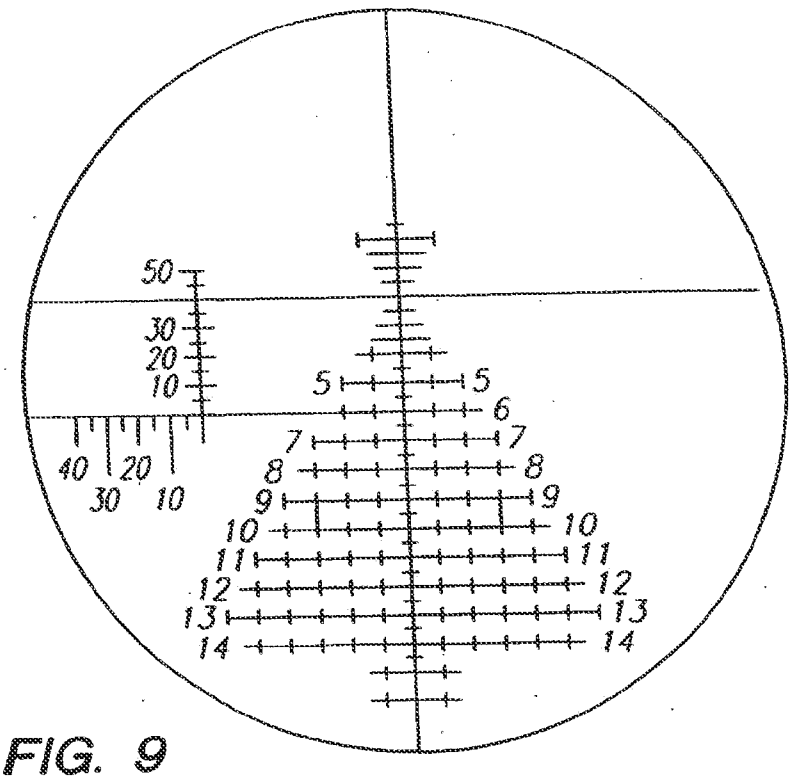

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FIG. 9

Sights on at 500 yards. Sights are 3.00 inches above bore.
Angle of Departure = 0.21 deg. (Firing angle = 0 deg.)

Range (yds)	50	100	150	200	250	300	350	400	450	500
Traj. (in.)	3.3	8.3	12.2	14.8	16.1	16.0	14.4	11.2	6.5	0.0
Traj. (MOA)	6.2	8.0	7.8	7.1	6.2	5.1	3.9	2.7	1.4	0.0
Range (yds)	550	600	650	700	750	800	850	900	900	1000
Traj. (in.)	-8.2	-18.4	-30.5	-44.6	-61.0	-79.7	-101	-124	-151	-180
Traj. (MOA)	-1.4	-2.9	-4.5	-6.1	-7.8	-9.5	-11.3	-13.2	-15.1	-17.2
Range (yds)	1050	1100	1150	1200	1250	1300	1350	1400	1450	1500
Traj. (in.)	-212	-247	-286	-328	-374	-424	-477	-535	-598	-665
Traj. (MOA)	-19.3	-21.5	-23.7	-26.1	-28.6	-31.1	-33.8	-36.5	-39.4	-42.4
Range (yds)	1550	1600	1650	1700	1750	1800	1850	1900	1950	2000
Traj. (in.)	-738	-816	-899	-989	-1085	-1187	-1295	-1411	-1533	-1662
Traj. (MOA)	-45.5	-48.7	-52.1	-55.6	-59.2	-63.0	-66.9	-70.9	-75.1	-79.4
Range (yds)	2050	2100	2150	2200	2250	2300	2350	2400	2450	2500
Traj. (in.)	-1799	-1942	-2093	-2252	-2418	-2592	-2774	-2965	-3163	-3370
Traj. (MOA)	-83.8	-88.3	-93.0	-97.8	-102.6	-107.6	-112.8	-118.0	-123.3	-128.7

FIG. 5

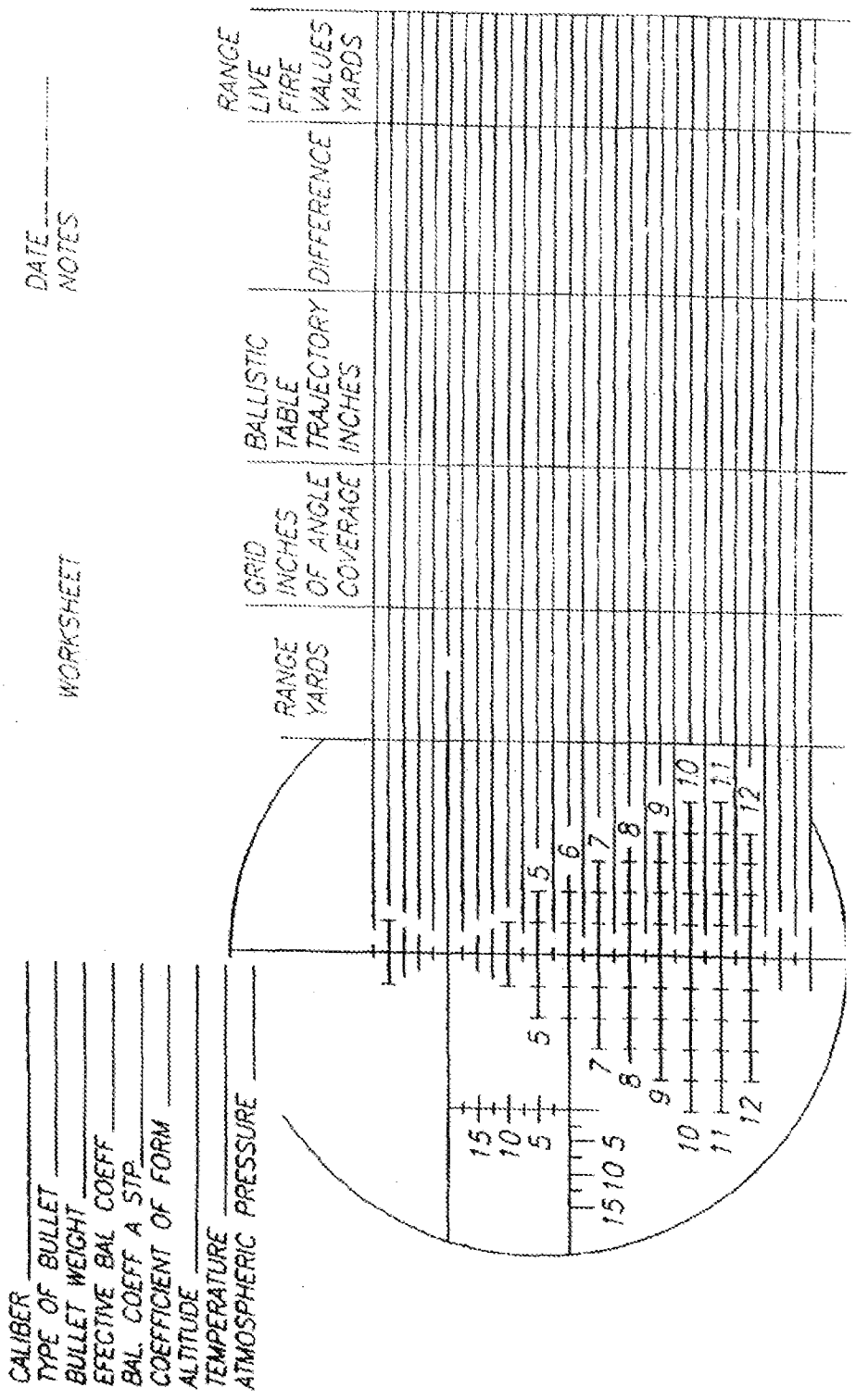

CALIBER
TYPE OF BULLET
BULLET WEIGHT
EFECTIVE BAL COEFF
BAL. COEFF A STP
COEFFICIENT OF FORM
ALTITUDE
TEMPERATURE
ATMOSPHERIC PRESSURE
WORKSHEET
DATE
NOTES
RANGE YARDS
GRID INCHES OF ANGLE COVERAGE
BALLISTIC TABLE TRAJECTORY INCHES
DIFFERENCE
RANGE LIVE FIRE VALUES YARDS
15 10 5
15 10 5
5 6 7 8 9 10 11 12
5 7 8 9 10 11 12

FIG. 6

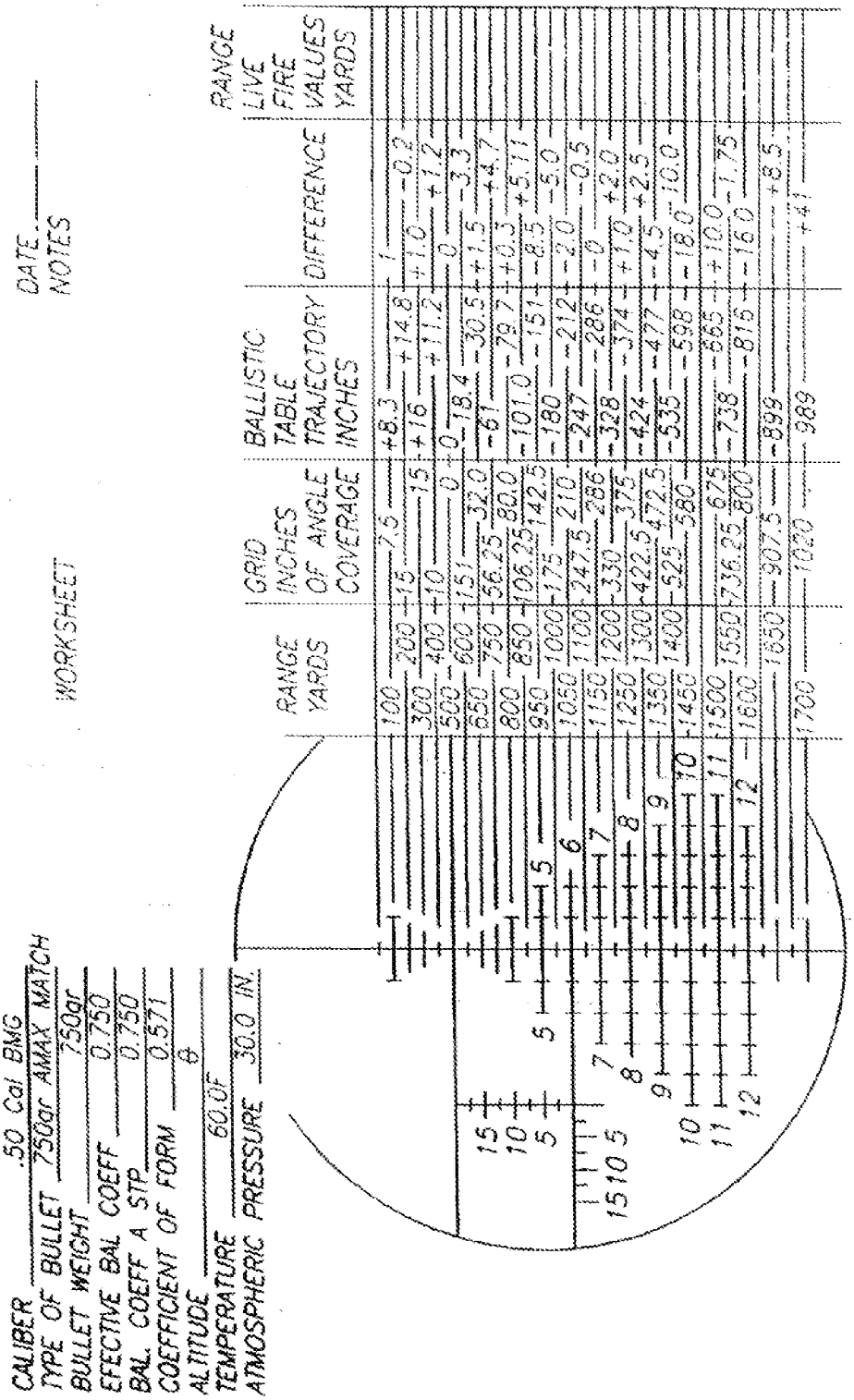

CALIBER .50 Cal BMG
TYPE OF BULLET 750gr AMAX MATCH
BULLET WEIGHT 750gr
EFFECTIVE BAL COEFF 0.750
BAL. COEFF A STP 0.750
COEFFICIENT OF FORM 0.571
ALTITUDE 0
TEMPERATURE 60.0F
ATMOSPHERIC PRESSURE 30.0 IN.
WORKSHEET
DATE
NOTES
RANGE YARDS
GRID INCHES OF ANGLE COVERAGE
BALLISTIC TABLE TRAJECTORY INCHES
DIFFERENCE
RANGE LIVE FIRE VALUES YARDS
100 200 300 400 500 600 650 750 800 850 950 1000 1050 1100 1150 1200 1250 1300 1350 1400 1450 1500 1550 1600 1650 1700
7.5 15 15 10 15 32.0 56.25 80.0 106.25 142.5 175 210 247.5 286 330 375 422.5 472.5 525 580 675 736.25 800 907.5 1020
+8.3 +14.8 +16 +11.2 0 -18.4 -30.5 -61 -79.7 -101.0 -151 -180 -212 -247 -286 -328 -374 -424 -477 -535 -598 -665 -738 -815 -899 -989
1 +1.0 0 -3.3 +1.5 +0.3 -8.5 -2.0 -0 +1.0 -4.5 -18.0 +10.0 -16.0 +8.5 +4.1
-0.2 +1.2 +1.2 +4.7 +5.11 -5.0 -0.5 +2.0 +2.5 -10.0 -1.75
15 10 5 5 6 7 8 9 10 11 12
15 10 5 7 8 9 10 11 12

FIG. 7

FIG. 8A

Hunting Shack 750 Gr AMAX Match .50 BMG
(Calculated using Ingalls' table)

Bullet Weight .....750 grains
Sectional Density 0.429
Effective Bal. Coeff 0.750
Cross wind .....10.0 m.p.h.
Atmospheric pressure ..30.00 in.

Bullet Caliber 0.500
Coefficient of Form 0.571
Bal. Coeff at STP 0.750
Altitude .....0 Ft.
Temperature .....60.0 F

Range yards	Velocity f.p.s.	Energy ft-lb.	Momentum lb.-sec.	Mx. Ord. in.	Defl. in.	Drop in.	Lead in./mph	Time sec.
0	2800	13054.6	9.3247	0.0	0.0	0.0	0.0	0.000
50	2736	12468.5	9.1130	0.1	0.1	0.6	1.0	0.054
100	2674	11903.1	8.9040	0.6	0.4	2.3	1.9	0.110
150	2612	11357.7	8.6976	1.3	1.0	5.2	2.9	0.166
200	2551	10833.0	8.4943	2.4	1.8	9.4	4.0	0.225
250	2491	10329.2	8.2945	3.9	2.8	15.0	5.0	0.284
300	2432	9845.5	8.0979	5.7	4.1	21.9	6.1	0.345
350	2374	9381.1	7.9046	8.0	5.7	30.4	7.2	0.407
400	2317	8935.5	7.7146	10.7	7.5	40.3	8.3	0.471
450	2260	8508.0	7.5278	13.9	9.6	51.9	9.5	0.537
500	2205	8098.0	7.3442	17.6	12.0	65.2	10.6	0.604
550	2151	7705.0	7.1637	21.8	14.7	80.2	11.8	0.673
600	2098	7328.3	6.9864	26.7	17.7	97.2	13.1	0.744
650	2046	6967.3	6.8122	32.1	21.1	116.1	14.4	0.816
700	1994	6621.6	6.6410	38.2	24.7	137.1	15.7	0.890
750	1944	6290.6	6.4729	45.1	28.7	160.3	17.0	0.966
800	1894	5973.7	6.3078	52.7	33.0	185.7	18.4	1.045
850	1845	5670.5	6.1456	61.2	37.7	213.6	19.8	1.125
900	1798	5380.5	5.9864	70.5	42.8	244.1	21.2	1.207
950	1751	5104.6	5.8309	80.7	48.2	277.2	22.7	1.292
1000	1705	4842.8	5.6794	92.0	54.1	313.2	24.3	1.379
1050	1661	4594.5	5.5319	104.4	60.3	352.2	25.8	1.468

FIG. 8

FIG. 8A
FIG. 8B

1100	1618	4358.9	5.3882	117.9	67.0	394.3	27.4			1.559
1150	1576	4135.4	5.2482	132.6	74.1	439.7	29.1			1.653
1200	1535	3923.3	5.1119	148.6	81.7	488.7	30.8			1.750
1250	1495	3722.1	4.9791	166.1	89.7	541.3	32.5			1.849
1300	1456	3531.3	4.8498	185.0	98.1	597.8	34.3			1.950
1350	1418	3350.2	4.7238	205.4	107.1	658.3	36.2			2.055
1400	1382	3178.4	4.6011	227.6	116.5	723.2	38.0			2.162
1450	1346	3016.8	4.4826	251.5	126.4	792.6	40.0			2.272
1500	1312	2867.1	4.3700	277.4	136.9	866.9	42.0			2.385
1550	1280	2728.4	4.2629	305.4	147.8	946.3	44.0			2.500
1600	1249	2599.4	4.1610	335.5	159.3	1031.1	46.1			2.619
1650	1220	2479.7	4.0640	367.9	171.2	1121.4	48.2			2.741
1700	1193	2371.7	3.9745	402.8	183.7	1217.7	50.4			2.865
1750	1169	2274.7	3.8924	440.2	196.6	1320.3	52.7			2.992
1800	1146	2187.0	3.8166	480.5	210.0	1429.2	54.9			3.122
1850	1125	2107.4	3.7465	523.7	223.8	1544.7	57.3			3.254
1900	1105	2034.6	3.6812	569.8	238.1	1666.9	59.6			3.388
1950	1087	1967.8	3.6203	618.7	252.7	1795.9	62.0			3.525
2000	1070	1906.2	3.5632	670.5	267.8	1931.9	64.5			3.664
2050	1054	1849.2	3.5095	725.3	283.2	2075.0	67.0			3.805
2100	1039	1796.3	3.4590	783.0	299.0	2225.5	69.5			3.949
2150	1024	1747.1	3.4112	843.8	315.2	2383.3	72.1			4.094
2200	1011	1701.0	3.3660	907.7	331.7	2548.7	74.7			4.242
2250	998	1657.9	3.3231	974.8	348.6	2721.9	77.3			4.391
2300	986	1617.5	3.2822	1045.0	365.8	2902.8	79.9			4.542
2350	974	1579.4	3.2433	1118.4	383.3	3091.8	82.6			4.695
2400	963	1543.4	3.2062	1195.0	401.2	3289.0	85.4			4.850
2450	952	1508.7	3.1699	1274.8	419.3	3494.2	88.1			5.007

FIG. 8B

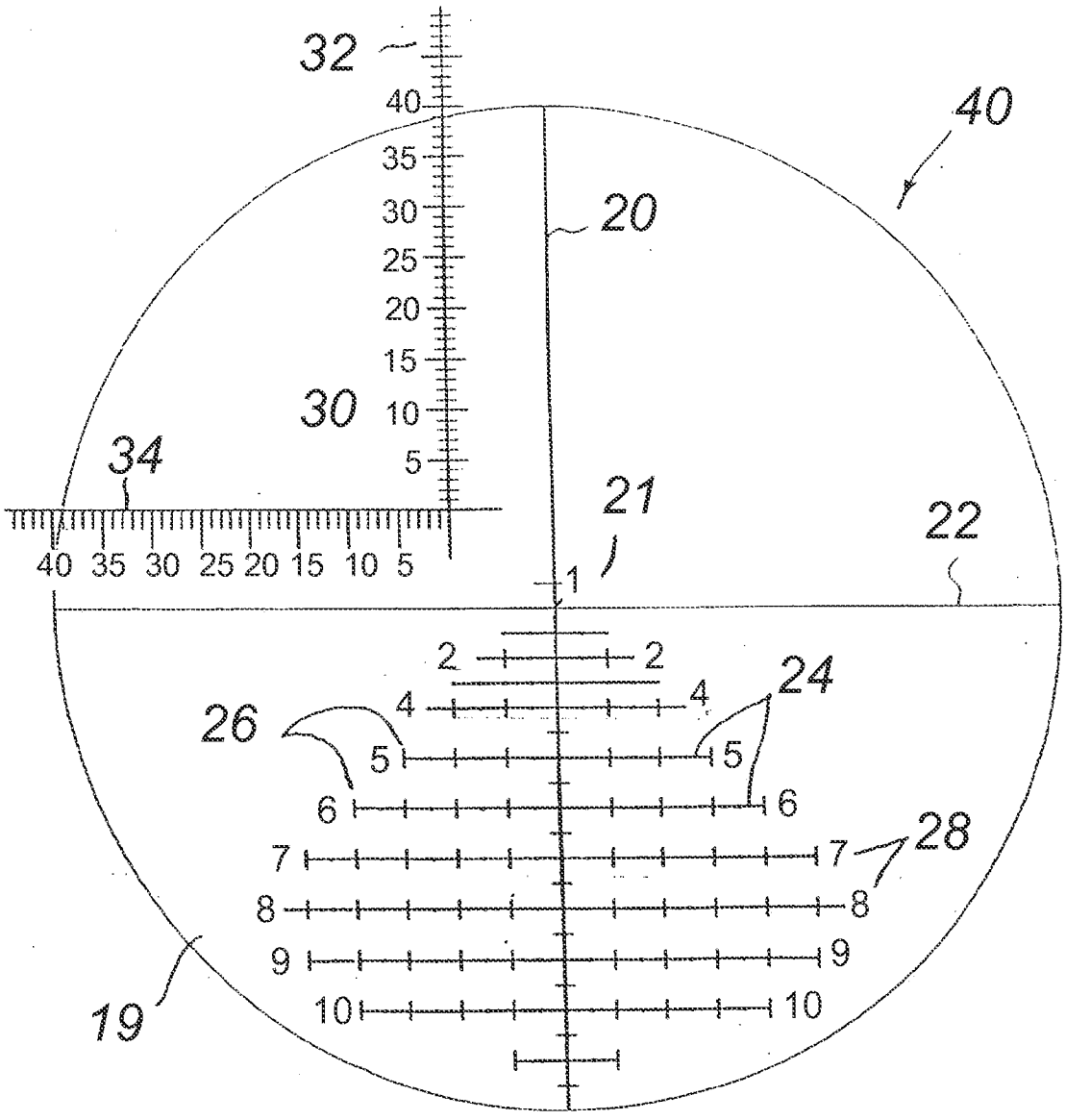

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FIG. 10

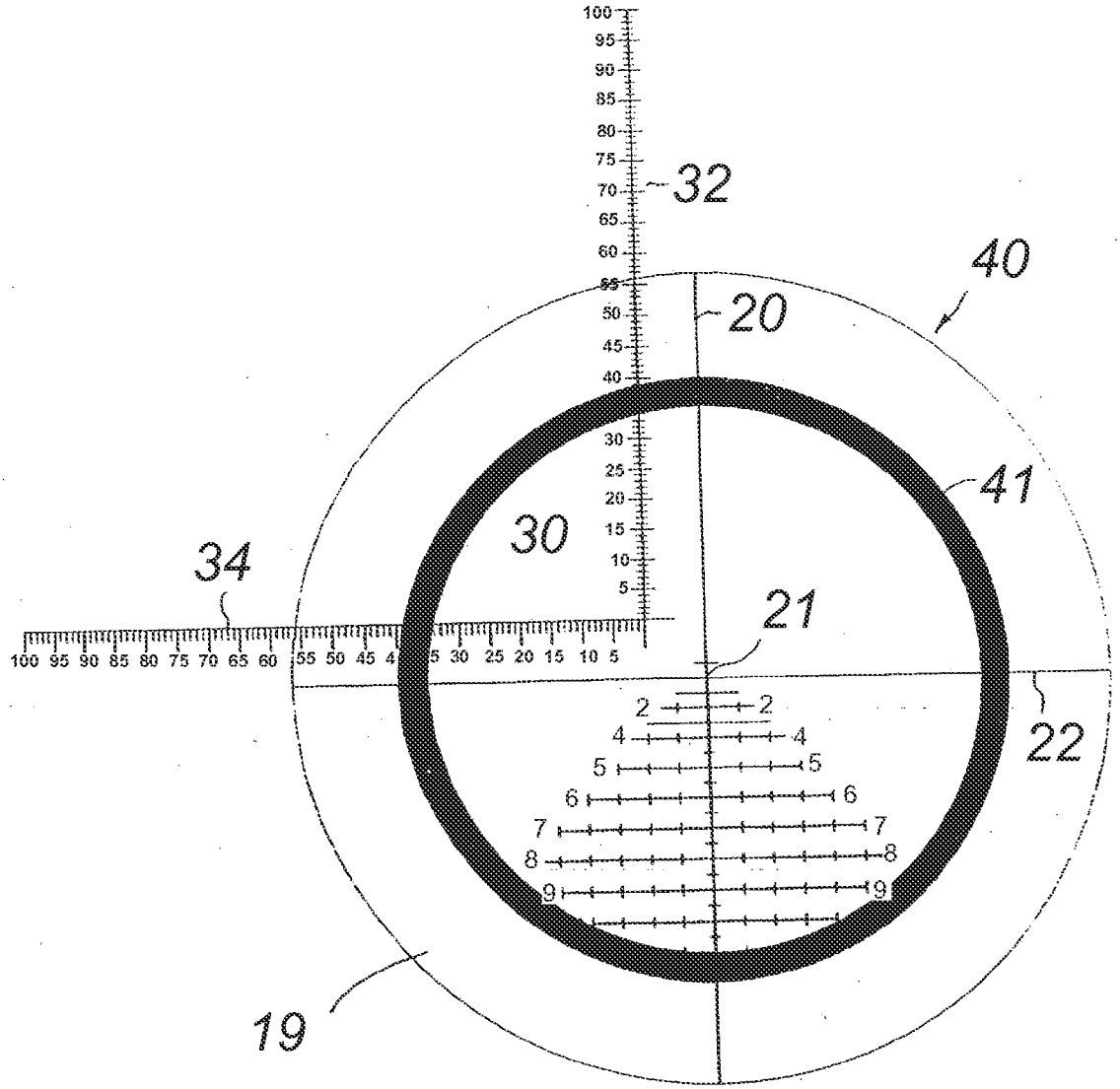


FIG. 11

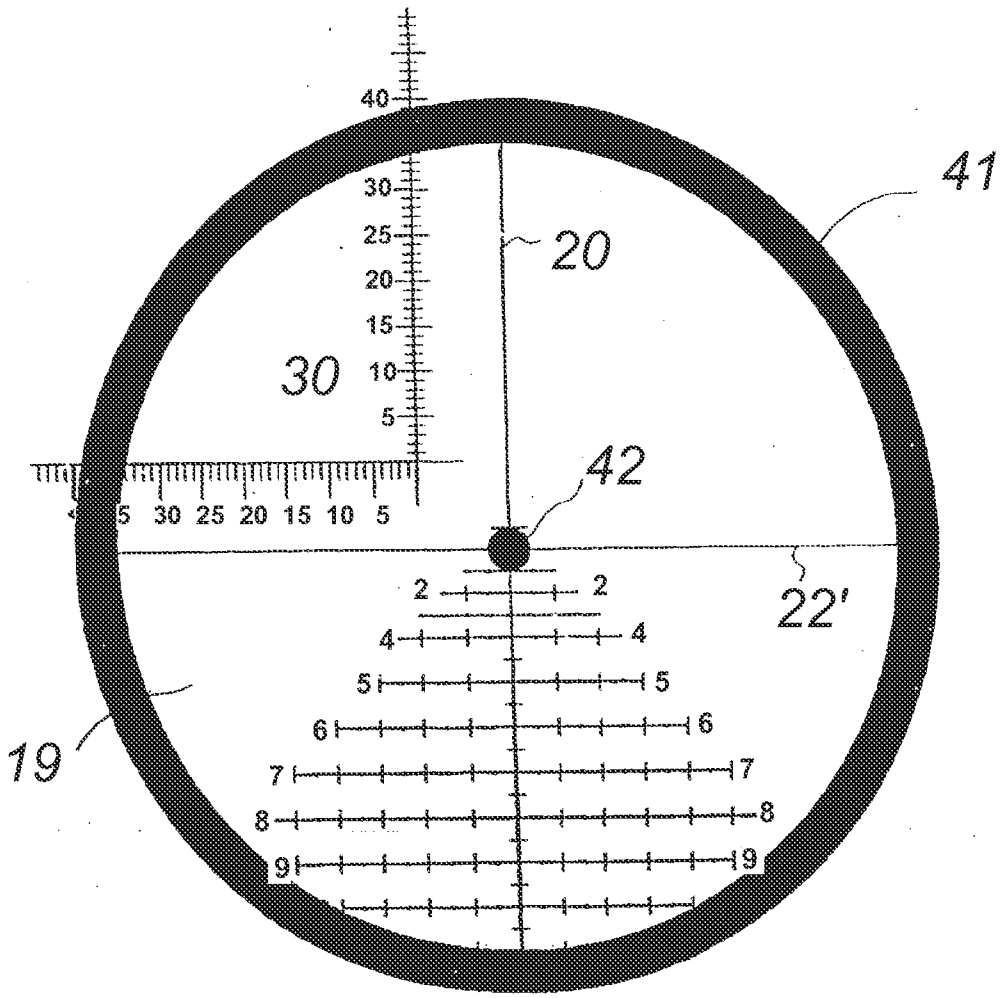

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42
22'
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5 30 25 20 15 10 5
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FIG. 12

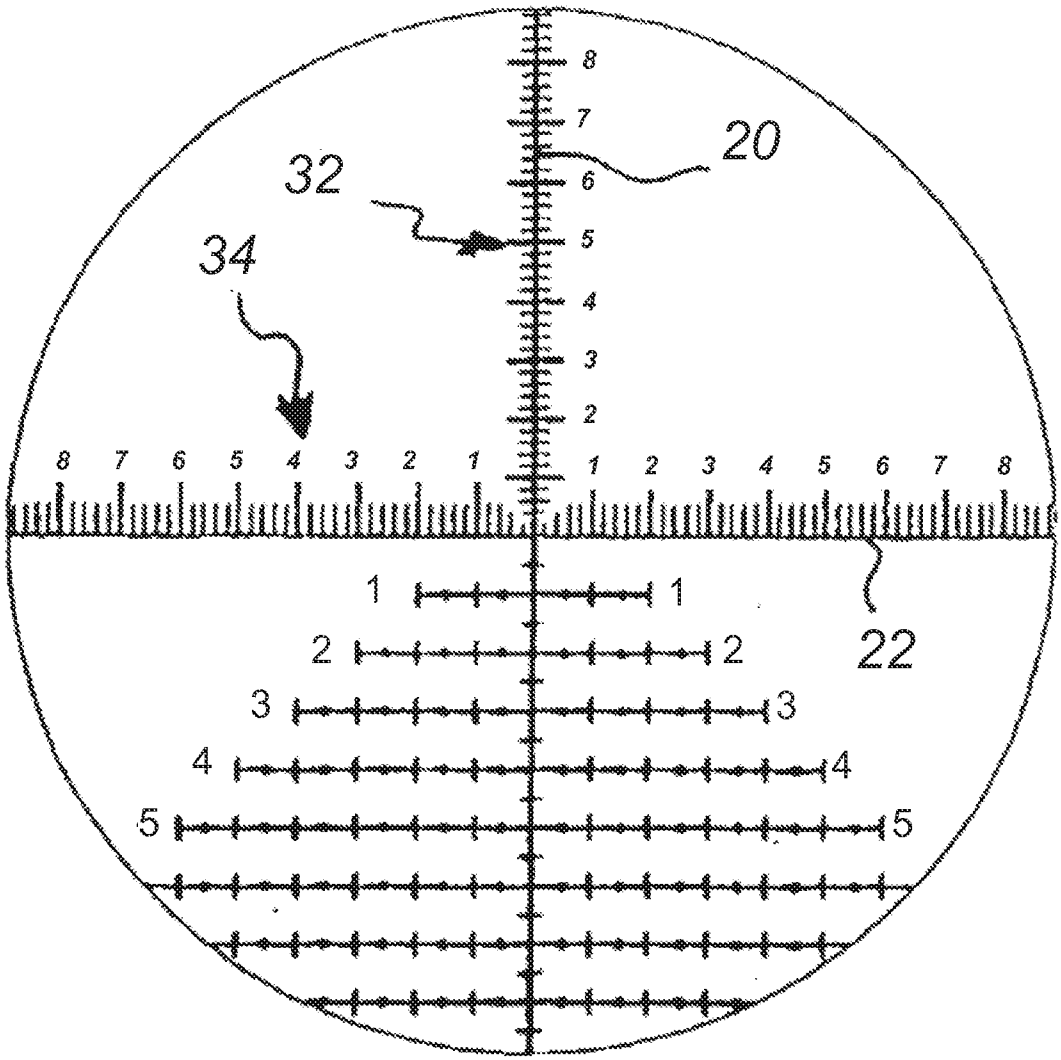


FIG. 13

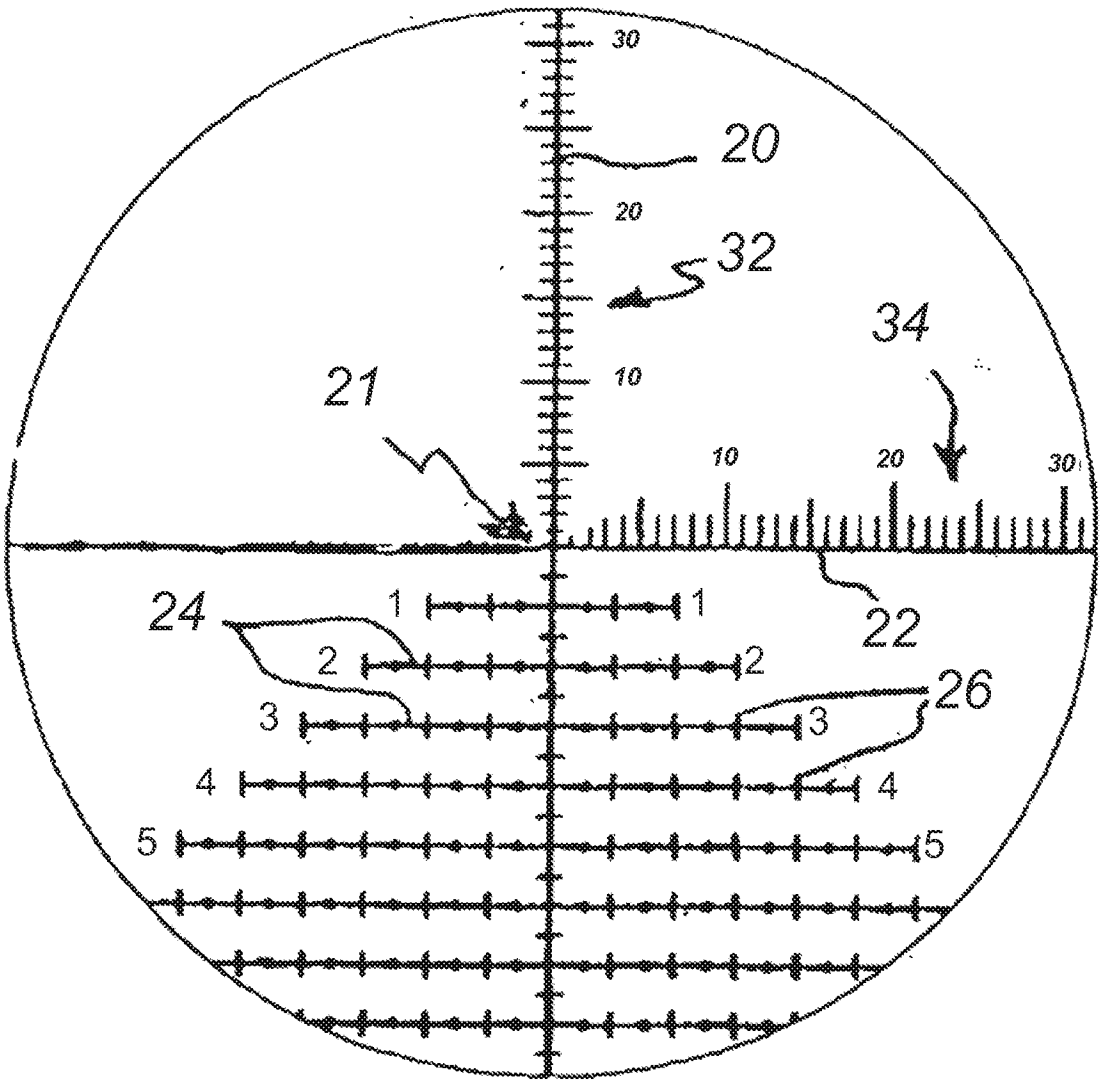


FIG. 14

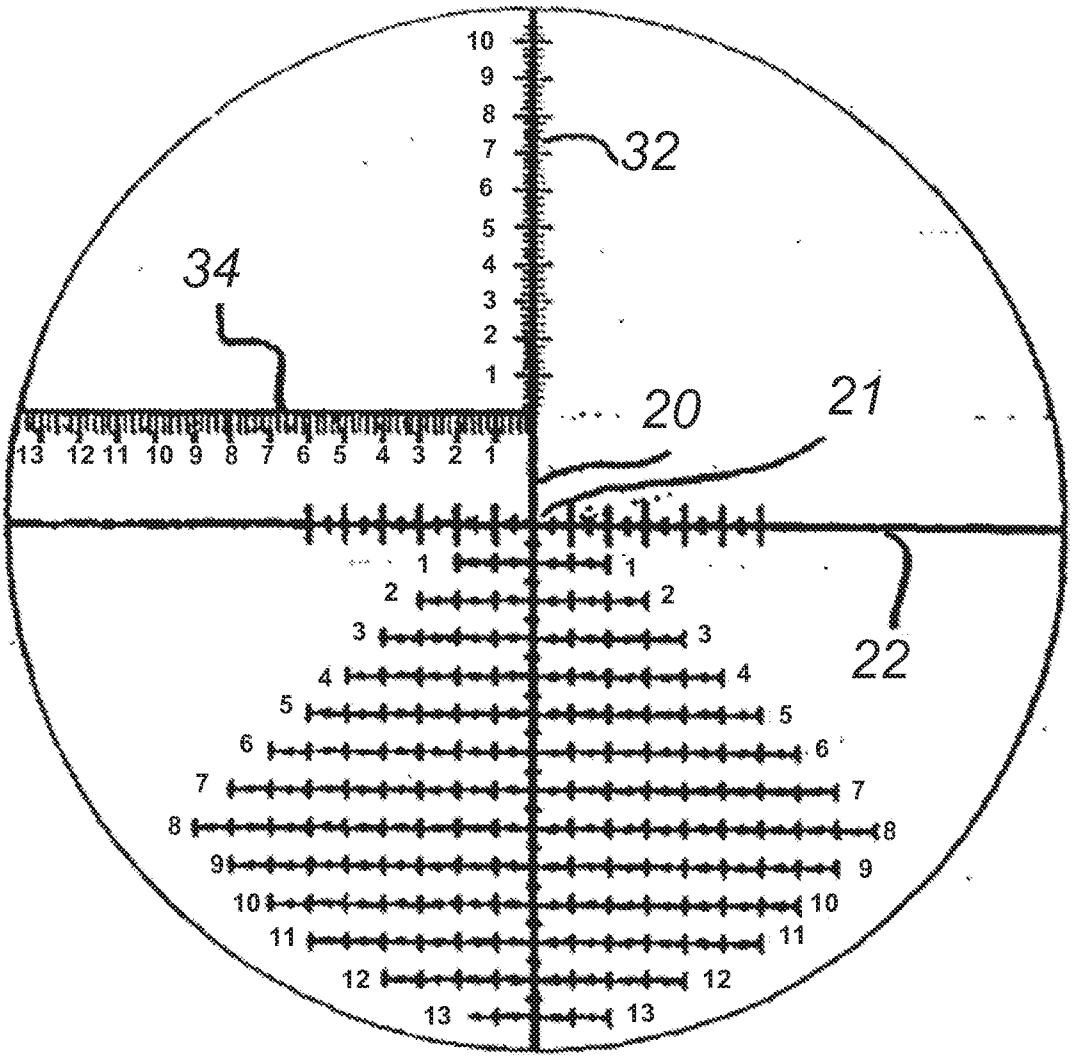

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3
2
1
32
34
13 12 11 10 9 8 7 6 5 4 3 2 1
20
21
22
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3
4
5
6
7
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FIG. 15

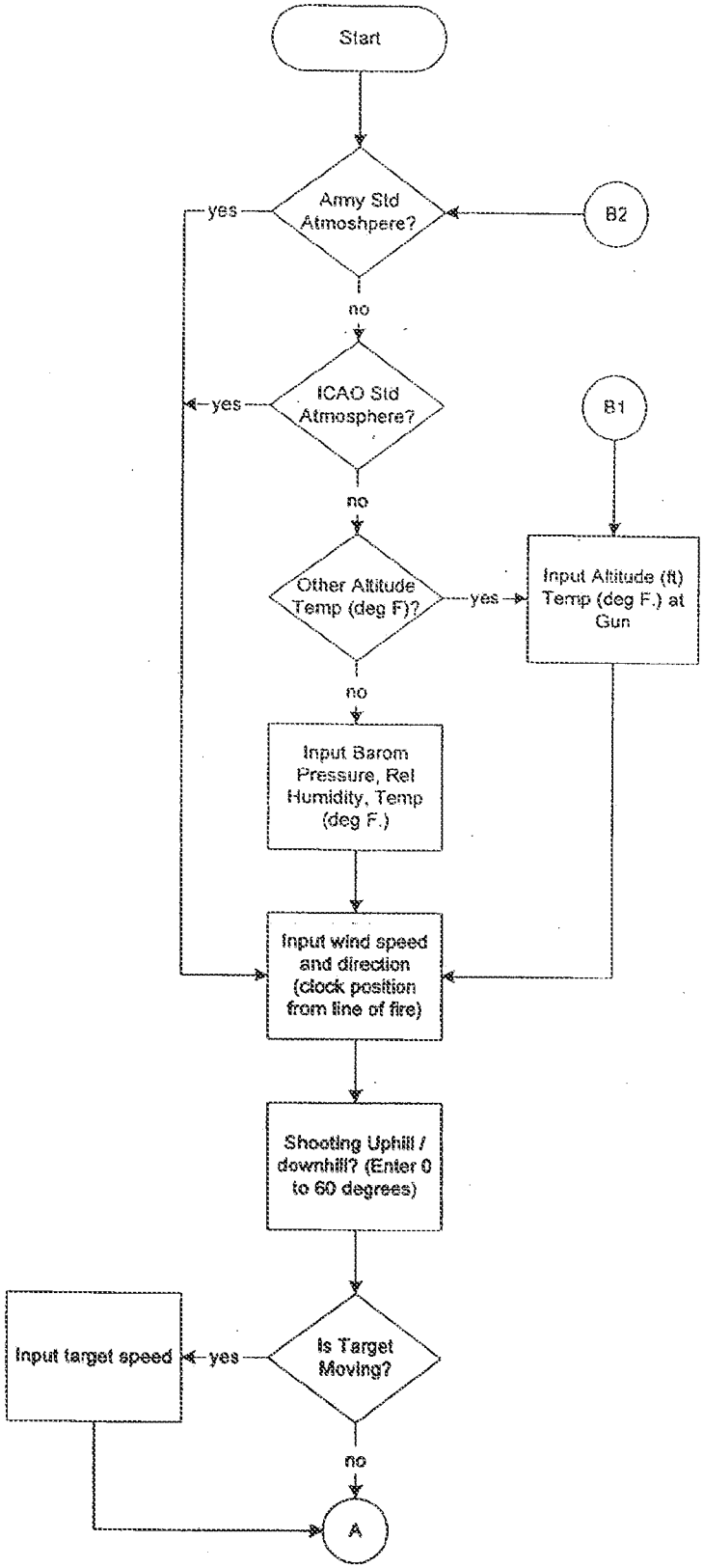
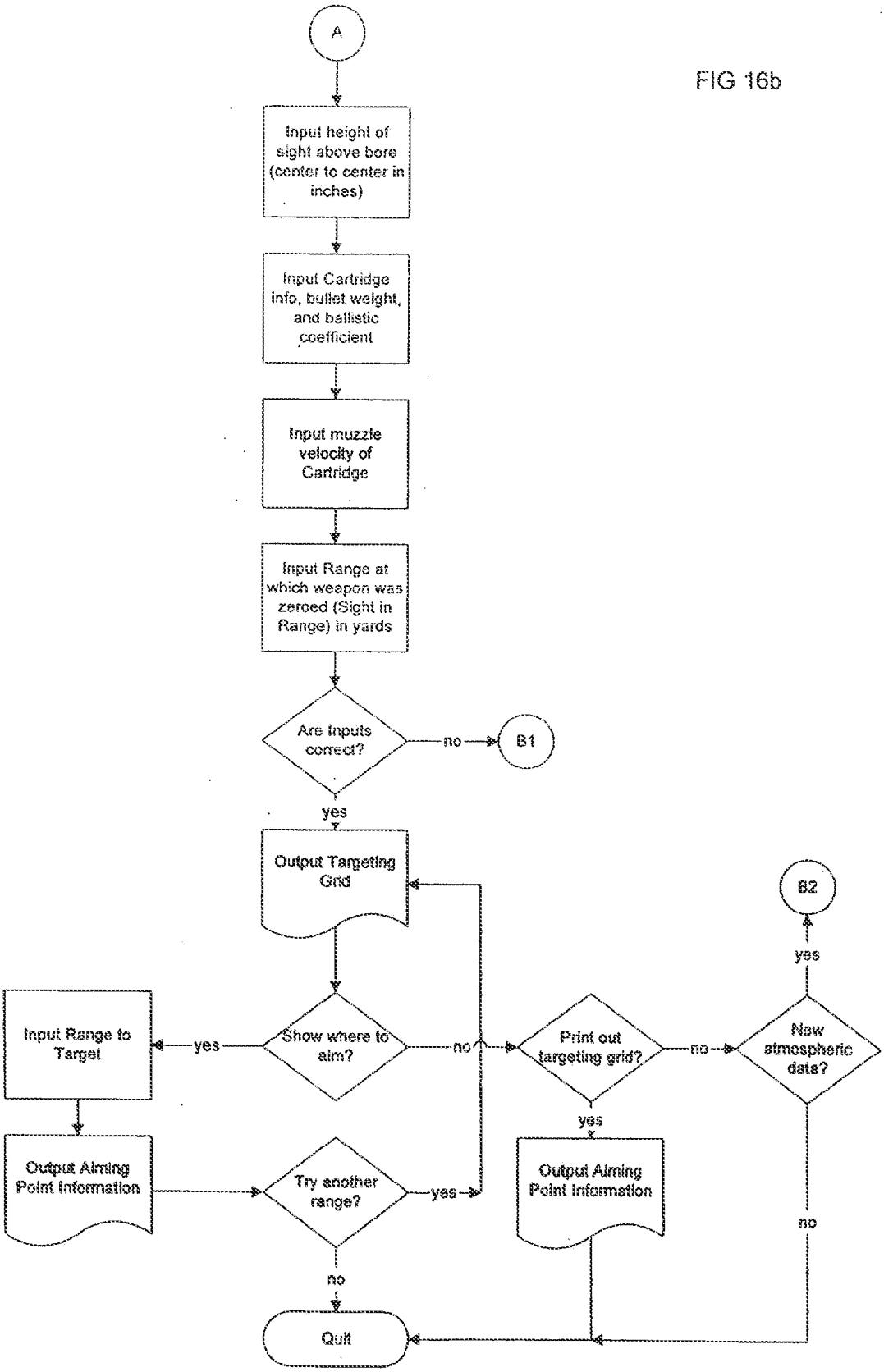

Start
Army Std Atmoshpere?
yes
B2
no
ICAO Std Atmosphere?
yes
B1
no
Other Altitude Temp (deg F)?
yes
Input Altitude (ft) Temp (deg F.) at Gun
no
Input Barom Pressure, Rel Humidity, Temp (deg F.)
Input wind speed and direction (clock position from line of fire)
Shooting Uphill / downhill? (Enter 0 to 60 degrees)
Is Target Moving?
yes
Input target speed
no
A

FIG 16a

FIG 16b


A
Input height of sight above bore (center to center in inches)
Input Cartridge info, bullet weight, and ballistic coefficient
Input muzzle velocity of Cartridge
Input Range at which weapon was zeroed (Sight in Range) in yards
Are Inputs correct?
no
B1
yes
Output Targeting Grid
B2
yes
Input Range to Target
yes
Show where to aim?
no
Print out targeting grid?
no
New atmospheric data?
yes
Output Aiming Point Information
Try another range?
yes
Output Aiming Point Information
no
no
Quit

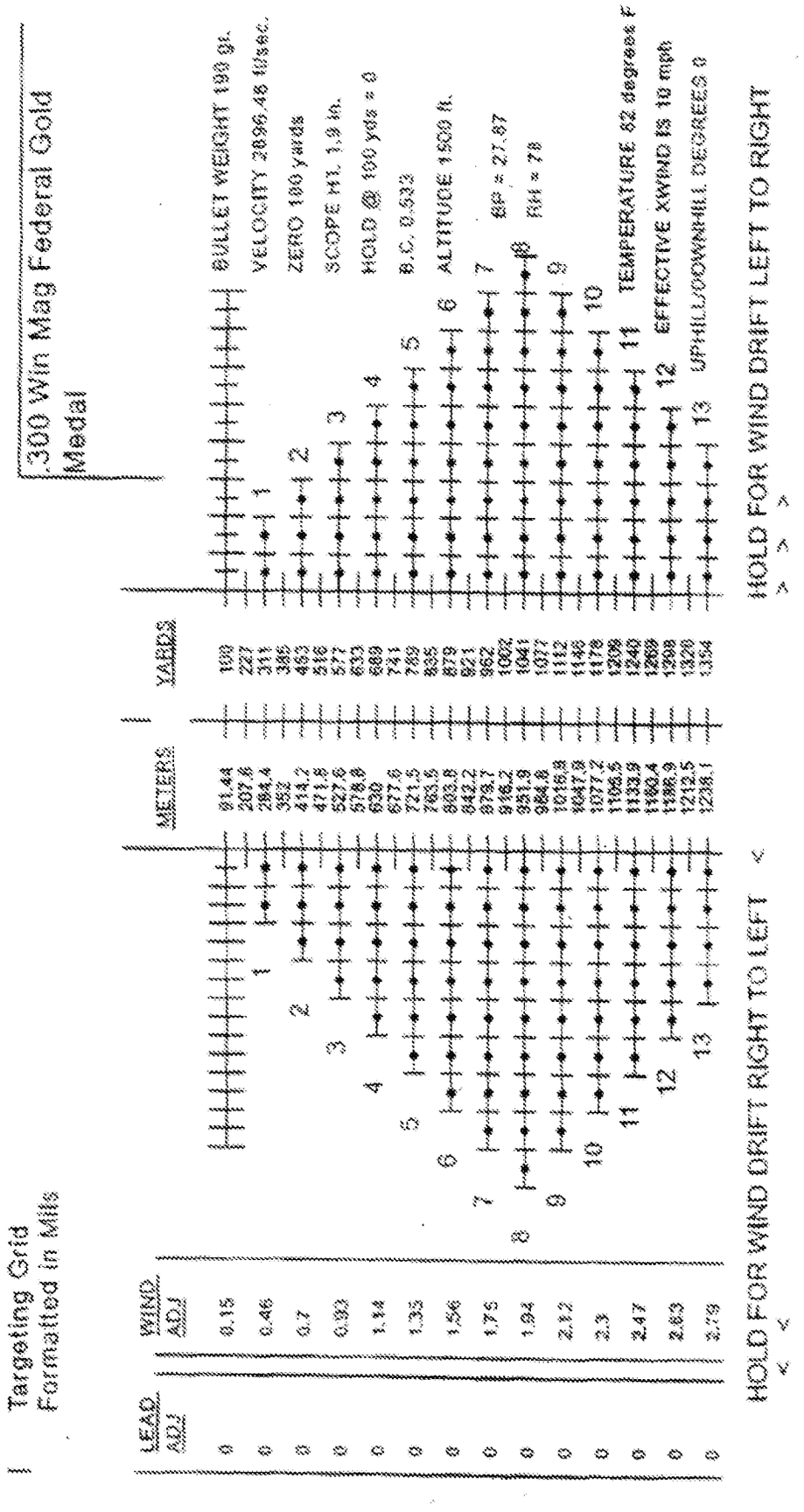

Targeting Grid
Formatted in Mils
.300 Win Mag Federal Gold Medal
METERS
YARDS
LEAD ADJ
WIND ADJ
HOLD FOR WIND DRIFT RIGHT TO LEFT
HOLD FOR WIND DRIFT LEFT TO RIGHT
BULLET WEIGHT 190 gr.
VELOCITY 2896.48 ft/sec.
ZERO 100 yards
SCOPE HT. 1.9 in.
HOLD @ 100 yds = 0
B.C. 0.532
ALTITUDE 1500 ft.
BP = 27.87
RH = 78
TEMPERATURE 62 degrees F
EFFECTIVE XWIND IS 10 mph
UPHILL/DOWNHILL DEGREES 0

FIG. 17A

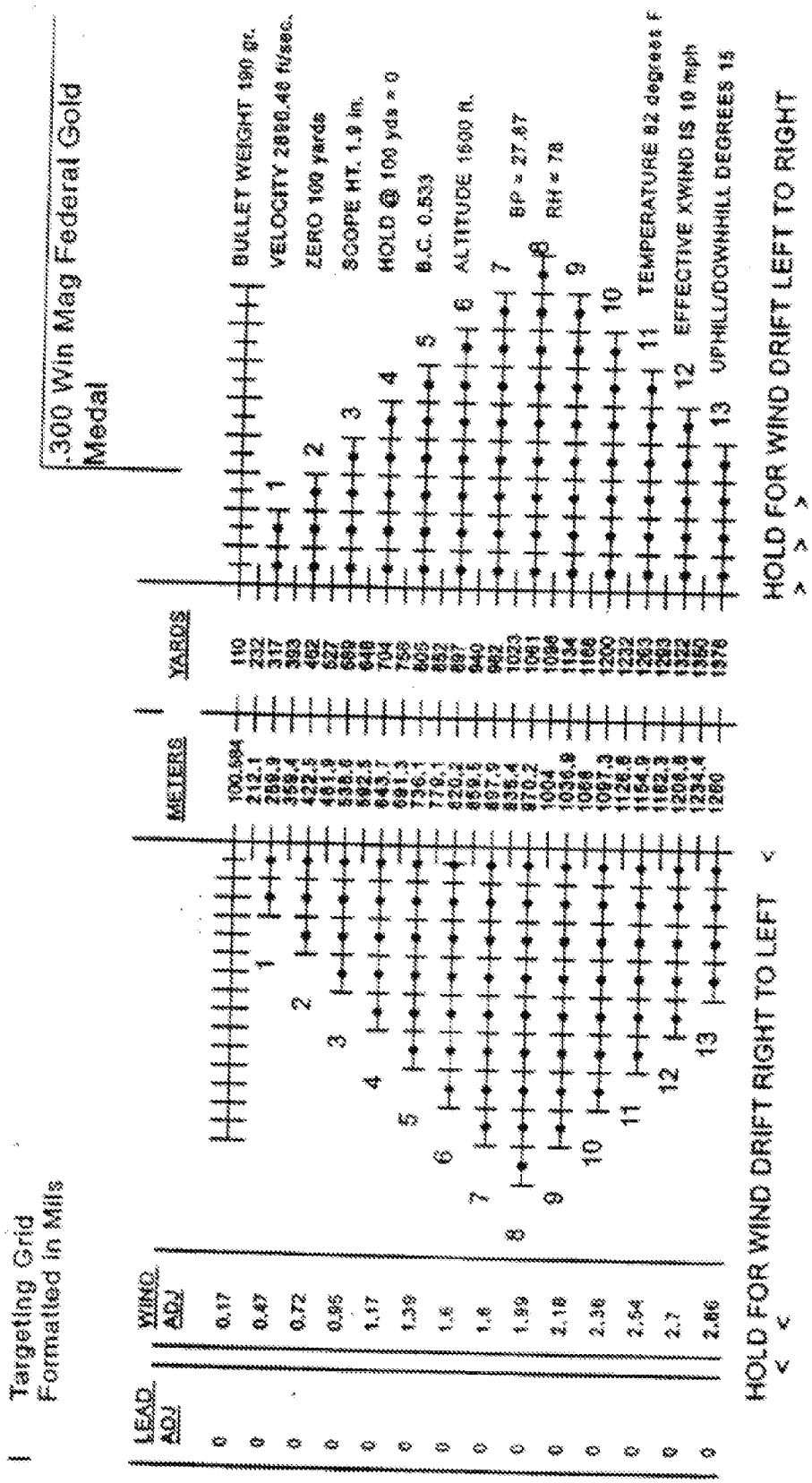

Targeting Grid
Formatted in Mils
LEAD ADJ
WIND ADJ
METERS
YARDS
300 Win Mag Federal Gold Medal
BULLET WEIGHT 190 gr.
VELOCITY 2880.46 ft/sec.
ZERO 100 yards
SCOPE HT. 1.9 in.
HOLD @ 100 yds = 0
B.C. 0.533
ALTITUDE 1600 ft.
BP = 27.87
RH = 78
TEMPERATURE 82 degrees F
EFFECTIVE XWIND IS 10 mph
UPHILL/DOWNHILL DEGREES 15
HOLD FOR WIND DRIFT RIGHT TO LEFT
HOLD FOR WIND DRIFT LEFT TO RIGHT

FIG. 17B

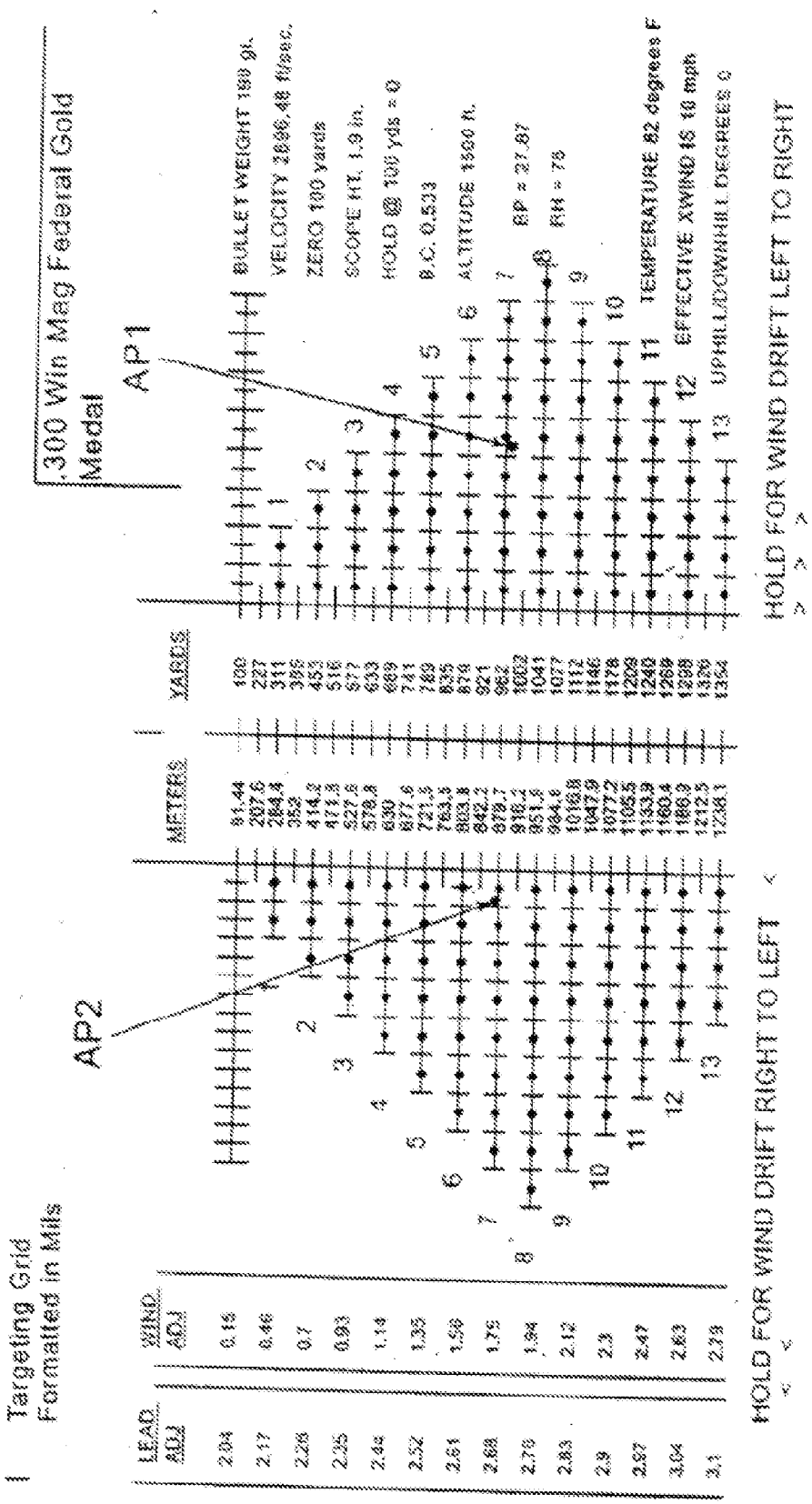

Targeting Grid
Formatted in Mils
LEAD ADJ
WIND ADJ
AP2
METERS
YARDS
AP1
300 Win Mag Federal Gold Medal
BULLET WEIGHT 190 gr.
VELOCITY 1696.48 ft/sec.
ZERO 100 yards
SCOPE HT. 1.9 in.
HOLD @ 100 yds = 0
B.C. 0.533
ALTITUDE 1560 ft.
BP = 27.87
RH = 78
TEMPERATURE 82 degrees F
EFFECTIVE XWIND 15 10 mph
UPHILL/DOWNHILL DEGREES 0
HOLD FOR WIND DRIFT RIGHT TO LEFT
HOLD FOR WIND DRIFT LEFT TO RIGHT

FIG. 17C

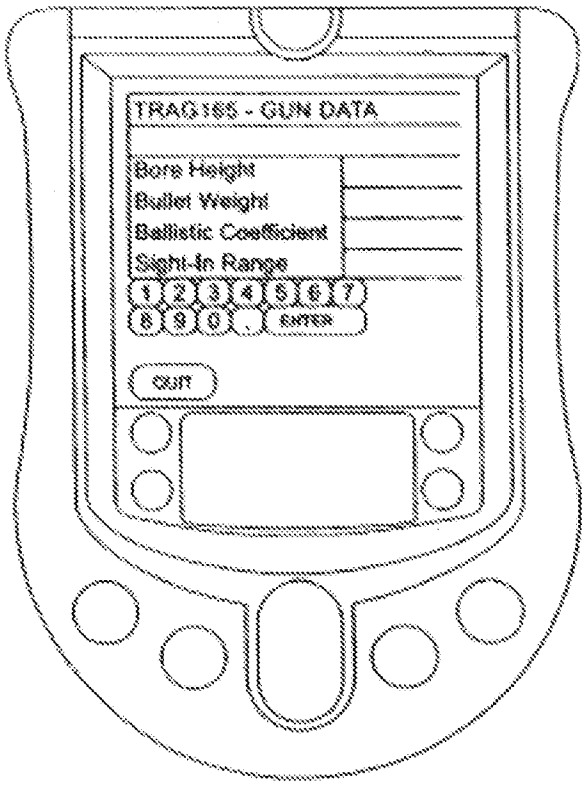

TRAG 165 - GUN DATA
Bore Height
Bullet Weight
Ballistic Coefficient
Sight-In Range
1 2 3 4 5 6 7
8 9 0 . ENTER
GUN

FIG. 18A

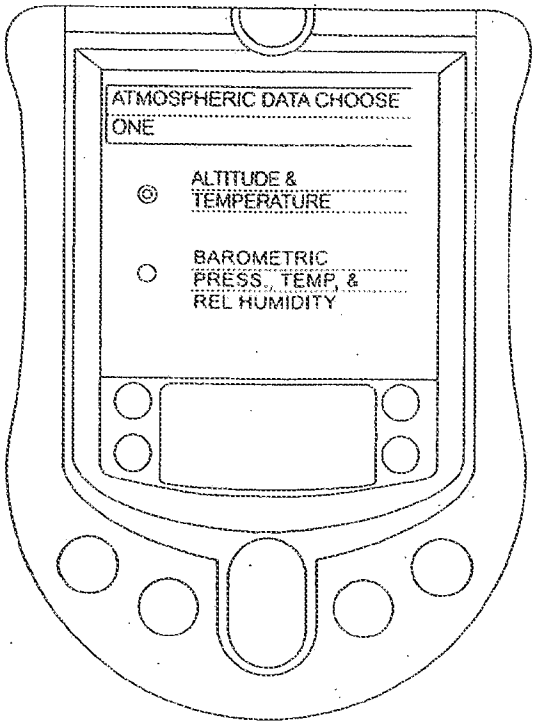


FIG. 18B

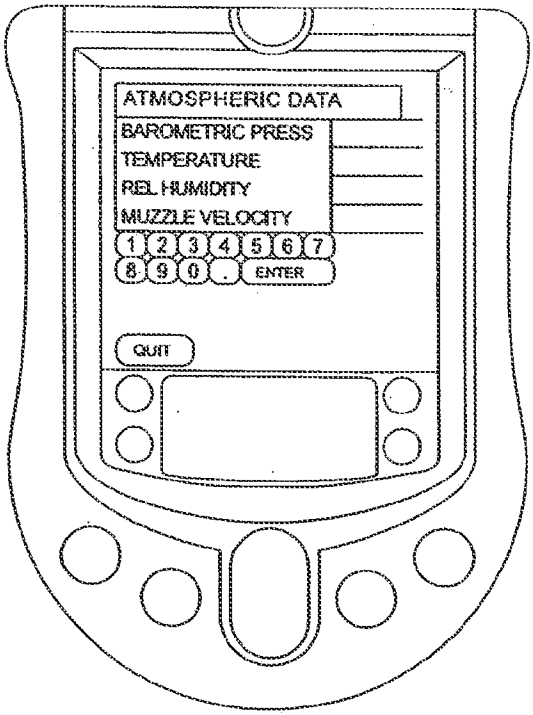


FIG. 18C

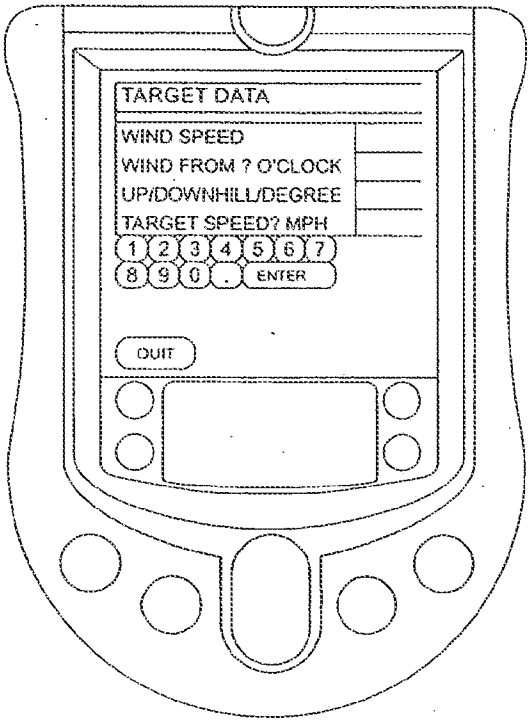


FIG. 18D

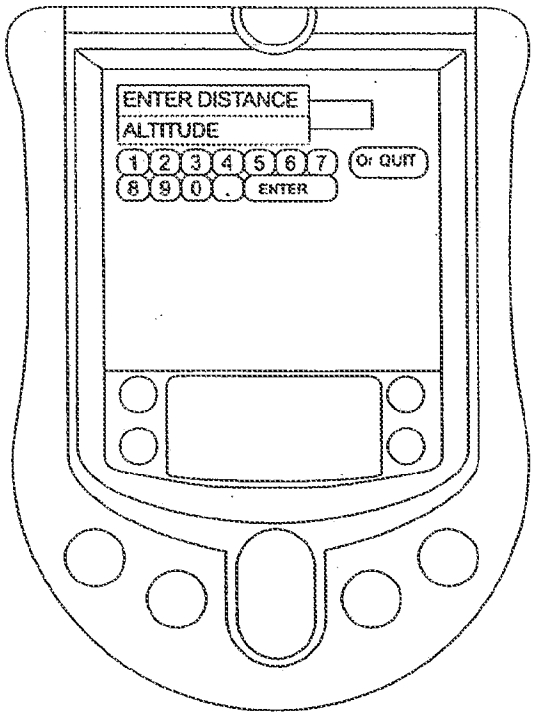


FIG. 18E

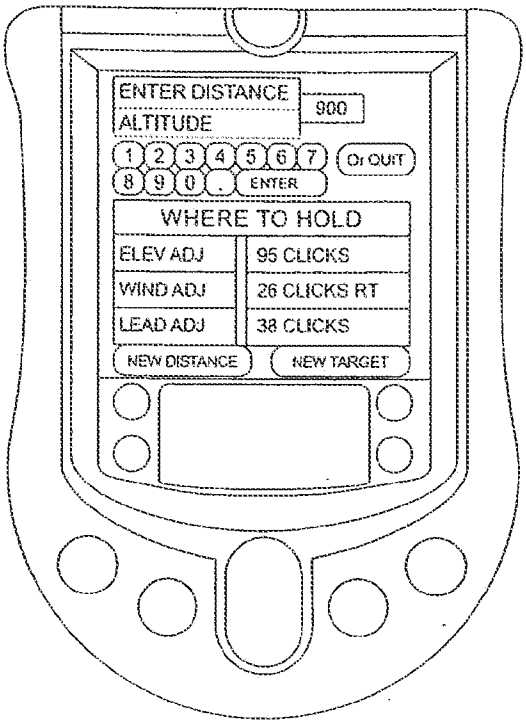


FIG. 18F

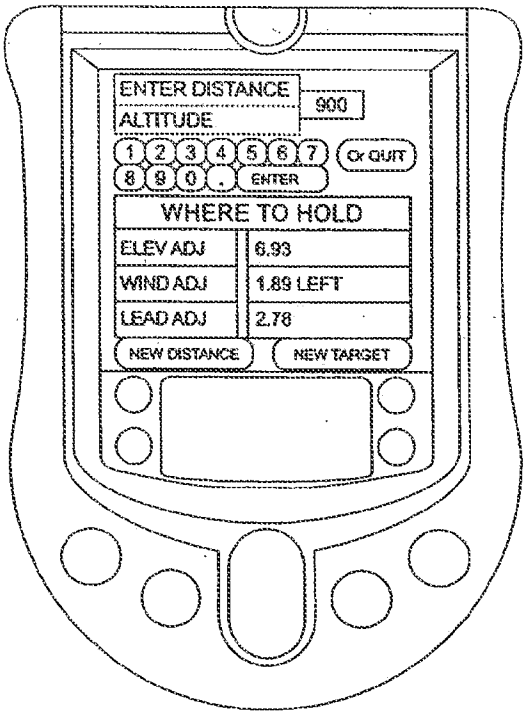


FIG. 18G

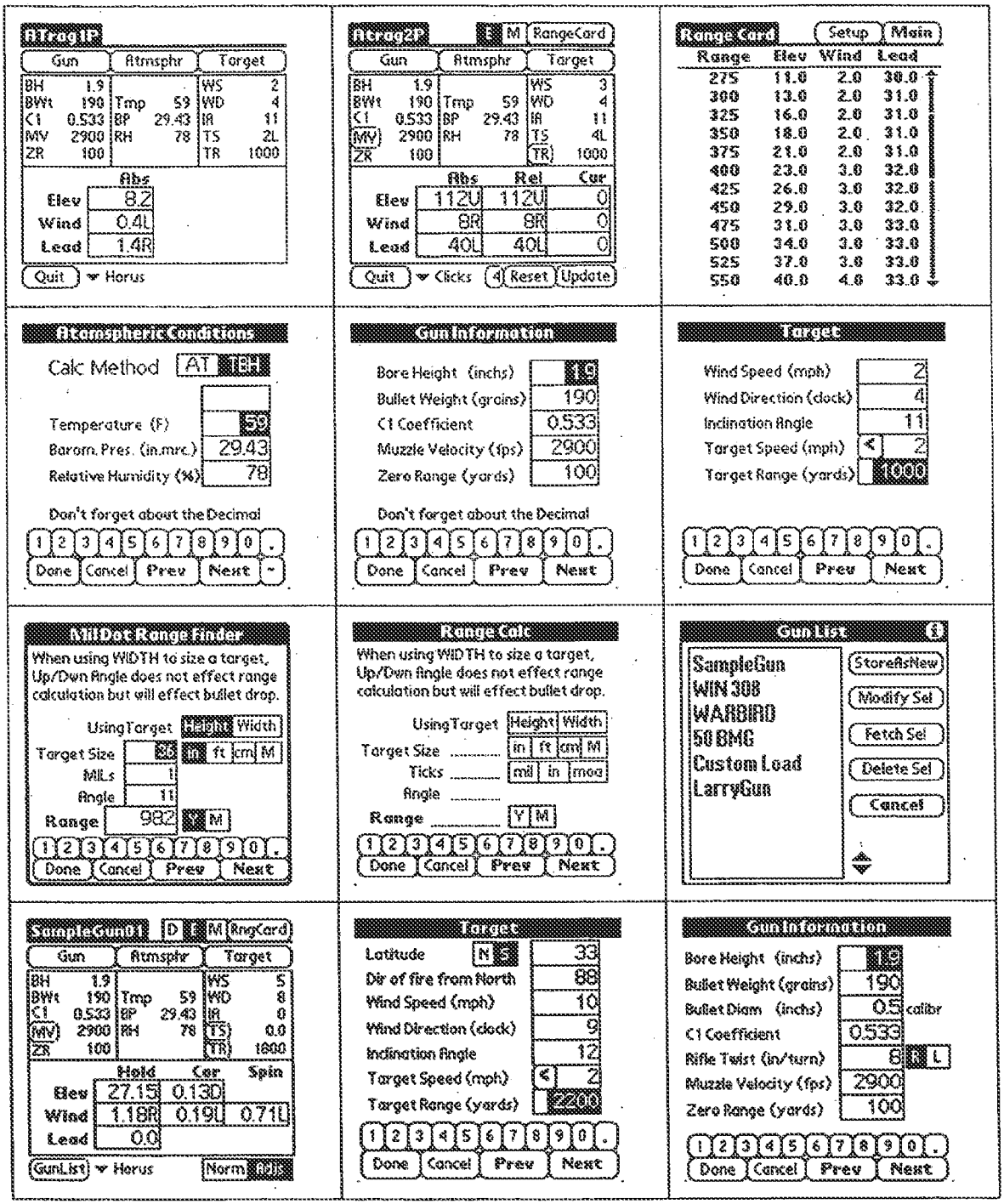

ATrag1P
Gun
Atmsphr
Target
BH 1.9
BWt 190
Cl 0.533
MV 2900
ZR 100
Tmp 59
BP 29.43
RH 78
WS 2
WD 4
IR 11
TS 2L
TR 1000
Abs
Elev 8.2
Wind 0.4L
Lead 1.4R
Quit
Horus
ATrag2P
E M RangeCard
Gun
Atmsphr
Target
BH 1.9
BWt 190
Cl 0.533
MV 2900
ZR 100
Tmp 59
BP 29.43
RH 78
WS 3
WD 4
IR 11
TS 4L
TR 1000
Abs Rel Cur
Elev 112U 112U 0
Wind 8R 8R 0
Lead 40L 40L 0
Quit
Clicks
4
Reset
Update
Range Card
Setup
Main
Range Elev Wind Lead
275 11.0 2.0 30.0
300 13.0 2.0 31.0
325 16.0 2.0 31.0
350 18.0 2.0 31.0
375 21.0 2.0 31.0
400 23.0 3.0 32.0
425 26.0 3.0 32.0
450 29.0 3.0 32.0
475 31.0 3.0 33.0
500 34.0 3.0 33.0
525 37.0 3.0 33.0
550 40.0 4.0 33.0
Atmospheric Conditions
Calc Method AT TH
Temperature (F) 59
Barom. Pres. (in.mrc.) 29.43
Relative Humidity (%) 78
Don't forget about the Decimal
1 2 3 4 5 6 7 8 9 0 .
Done Cancel Prev Next -
Gun Information
Bore Height (inchs) 1.9
Bullet Weight (grains) 190
Cl Coefficient 0.533
Muzzle Velocity (fps) 2900
Zero Range (yards) 100
Don't forget about the Decimal
1 2 3 4 5 6 7 8 9 0 .
Done Cancel Prev Next
Target
Wind Speed (mph) 2
Wind Direction (clock) 4
Inclination Angle 11
Target Speed (mph) < 2
Target Range (yards) 1000
1 2 3 4 5 6 7 8 9 0 .
Done Cancel Prev Next
Mil Dot Range Finder
When using WIDTH to size a target, Up/Dwn Angle does not effect range calculation but will effect bullet drop.
Using Target Height Width
Target Size 48 in ft cm M
MILs 1
Angle 11
Range 982 Y M
1 2 3 4 5 6 7 8 9 0 .
Done Cancel Prev Next
Range Calc
When using WIDTH to size a target, Up/Dwn Angle does not effect range calculation but will effect bullet drop.
Using Target Height Width
Target Size in ft cm M
Ticks mil in moa
Angle
Range Y M
1 2 3 4 5 6 7 8 9 0 .
Done Cancel Prev Next
Gun List
SampleGun
WIN 308
WARBIRD
50 BMG
Custom Load
LarryGun
StoreAsNew
Modify Sel
Fetch Sel
Delete Sel
Cancel
SampleGun1
D E M RngCard
Gun
Atmsphr
Target
BH 1.9
BWt 190
Cl 0.533
MV 2900
ZR 100
Tmp 59
BP 29.43
RH 78
WS 5
WD 8
IR 0
TS 0.0
TR 1800
Hold Cor Spin
Elev 27.15 0.13D
Wind 1.18R 0.19L 0.71L
Lead 0.0
GunList
Horus
Norm Opt
Target
Latitude N S 33
Dir of fire from North 88
Wind Speed (mph) 10
Wind Direction (clock) 9
Inclination Angle 12
Target Speed (mph) < 2
Target Range (yards) 2280
1 2 3 4 5 6 7 8 9 0 .
Done Cancel Prev Next
Gun Information
Bore Height (inchs) 1.9
Bullet Weight (grains) 190
Bullet Diam (inchs) 0.5 caliber
Cl Coefficient 0.533
Rifle Twist (in/turn) 8 R L
Muzzle Velocity (fps) 2900
Zero Range (yards) 100
1 2 3 4 5 6 7 8 9 0 .
Done Cancel Prev Next

FIG. 18H

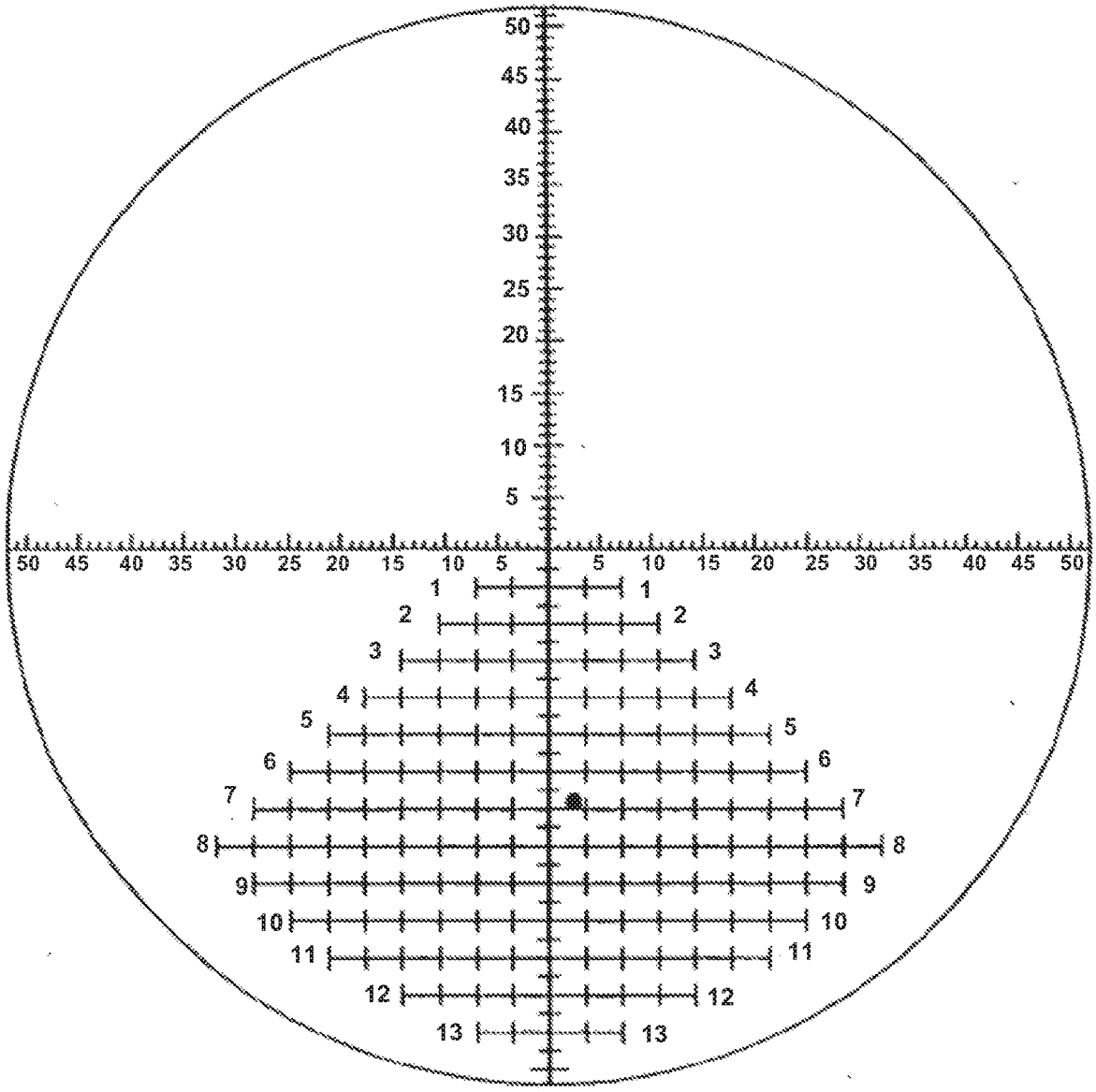

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10
5
50 45 40 35 30 25 20 15 10 5 5 10 15 20 25 30 35 40 45 50
1
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11
12
13

FIG. 19A

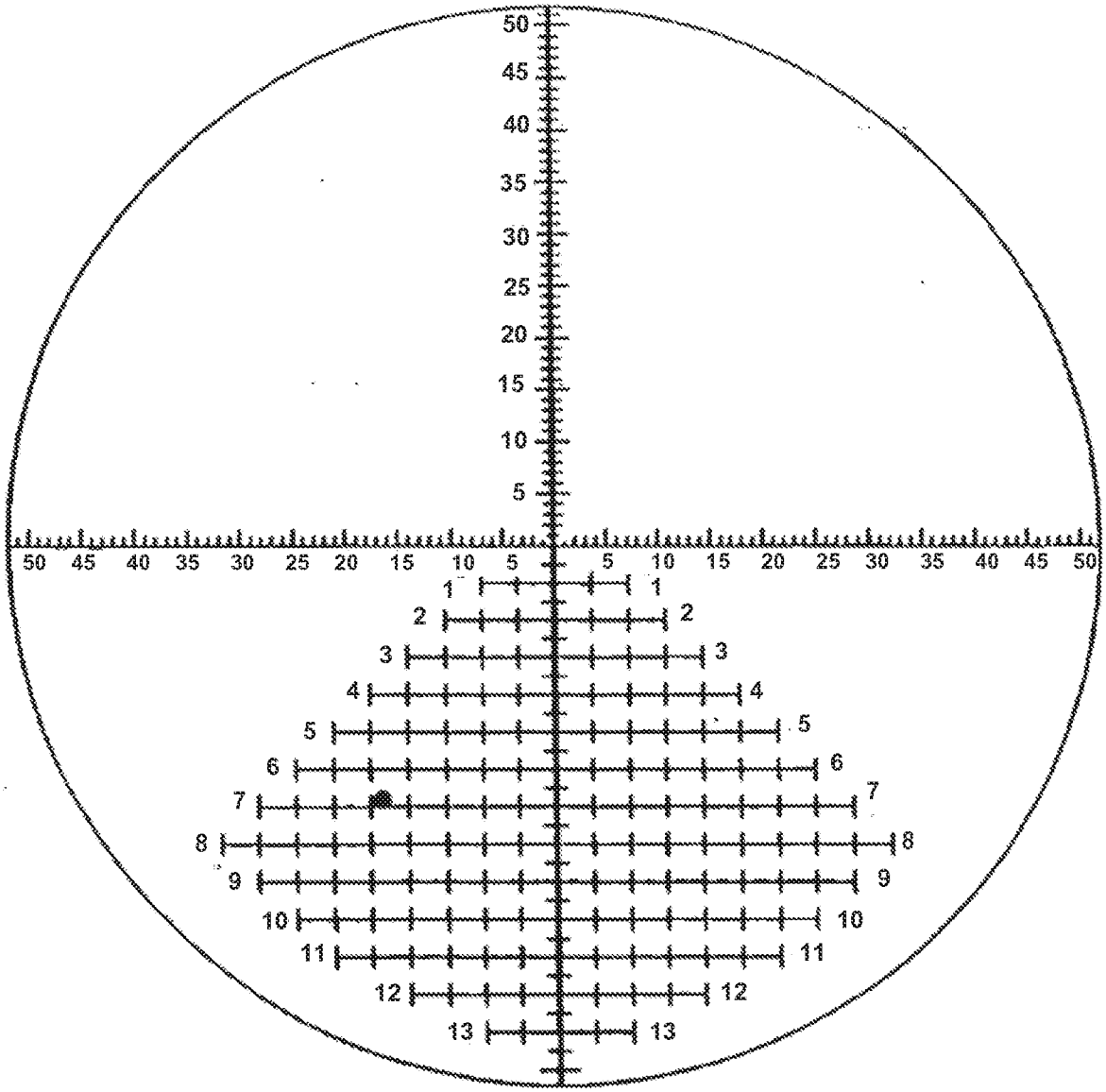

50
45
40
35
30
25
20
15
10
5
50 45 40 35 30 25 20 15 10 5 5 10 15 20 25 30 35 40 45 50
1 1
2 2
3 3
4 4
5 5
6 6
7 7
8 8
9 9
10 10
11 11
12 12
13 13

FIG. 19B

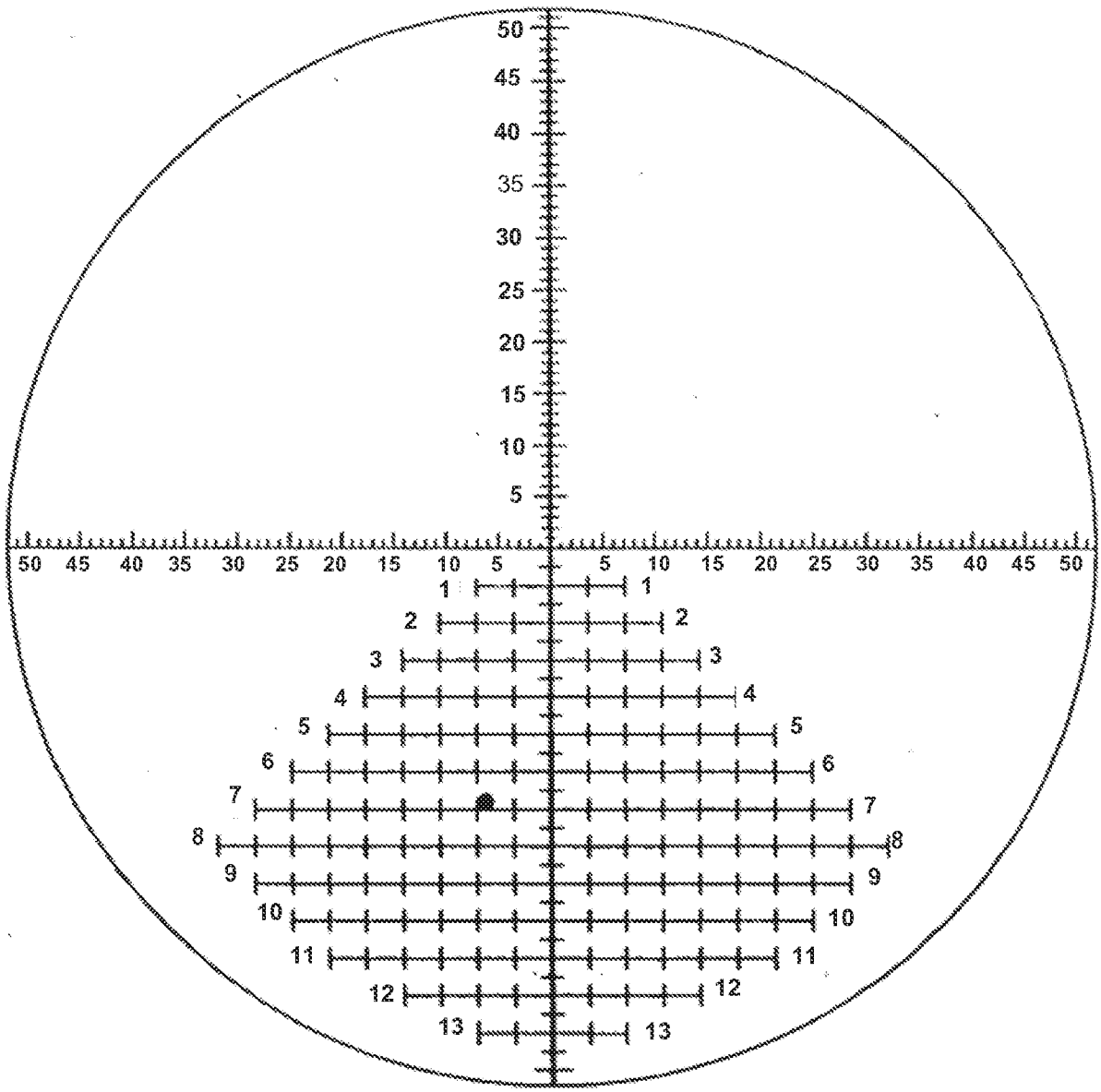

50
45
40
35
30
25
20
15
10
5
50 45 40 35 30 25 20 15 10 5 5 10 15 20 25 30 35 40 45 50
1
2
3
4
5
6
7
8
9
10
11
12
13

FIG. 19C

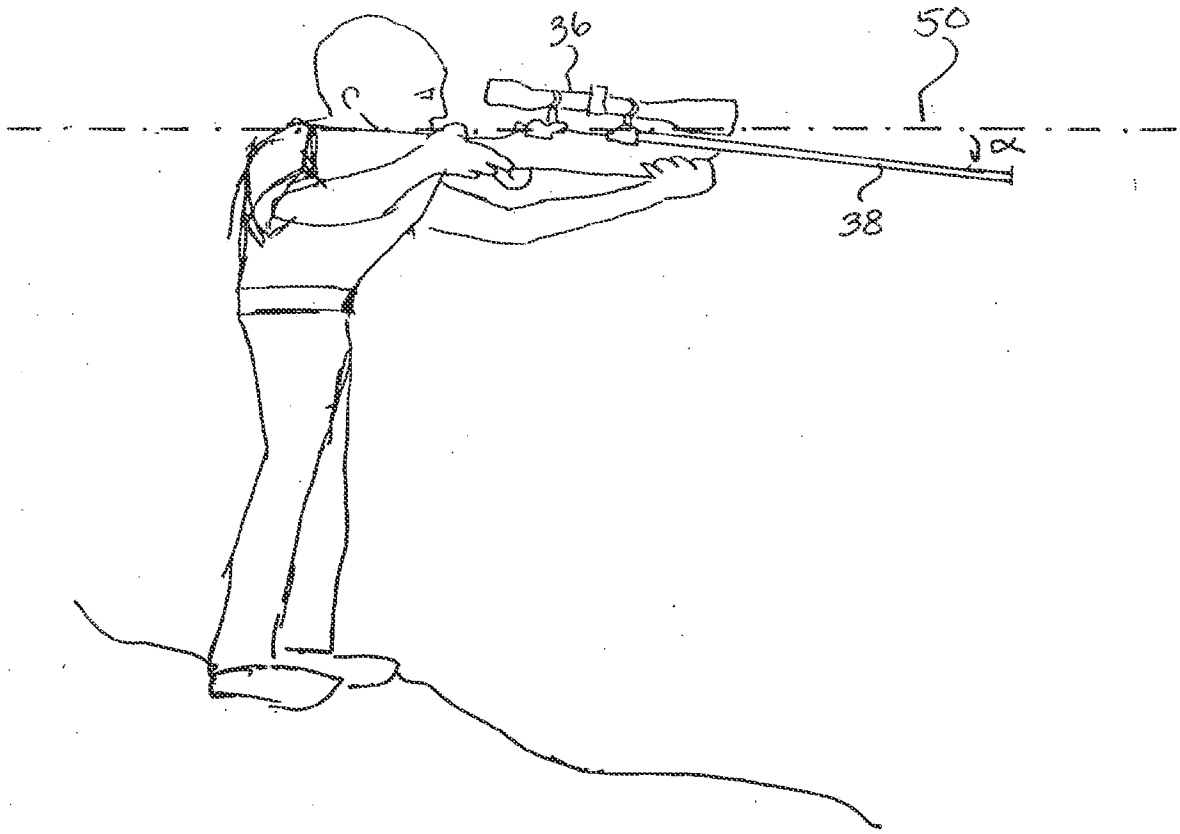


FIG. 20

FIG. 21

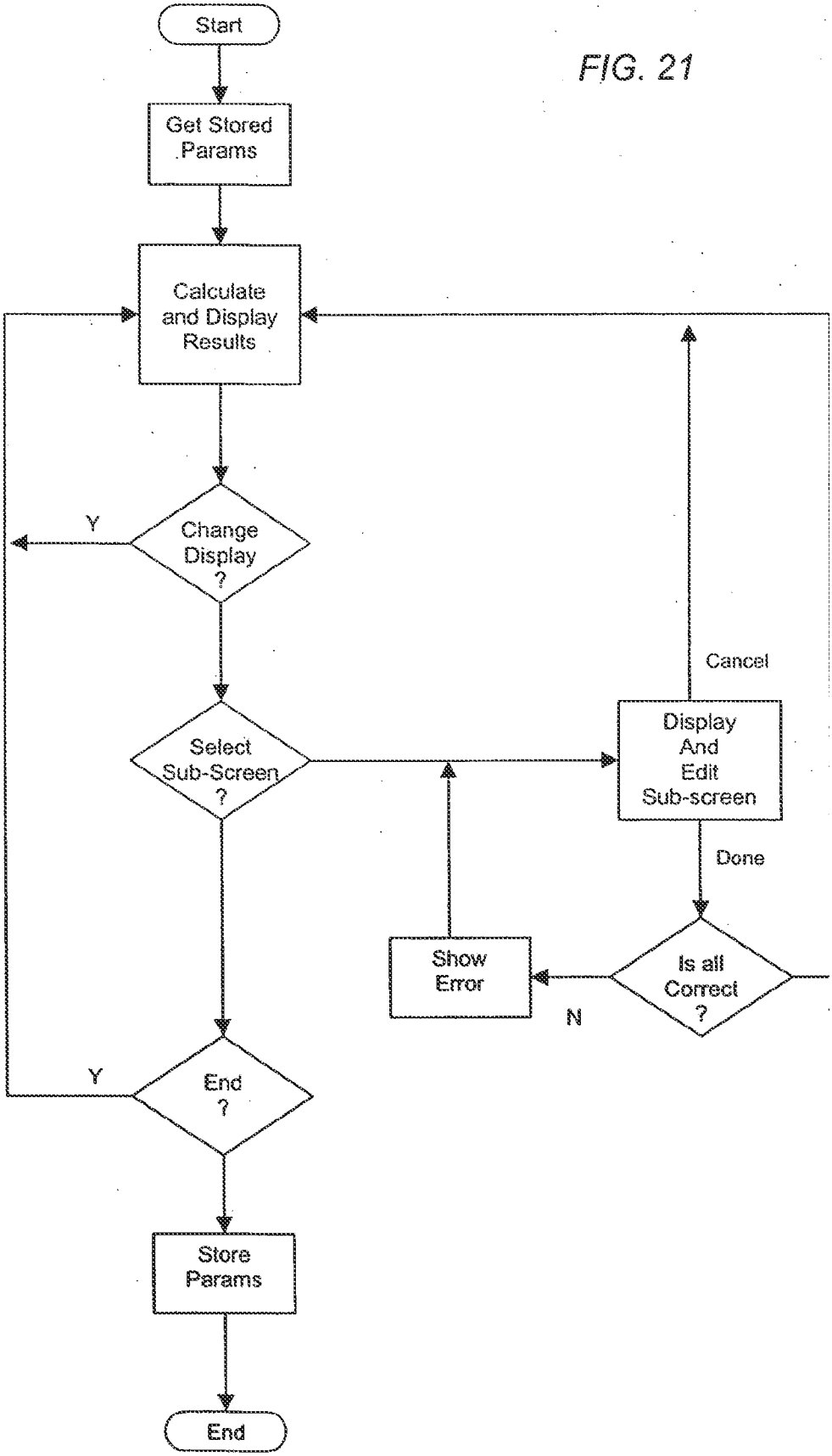
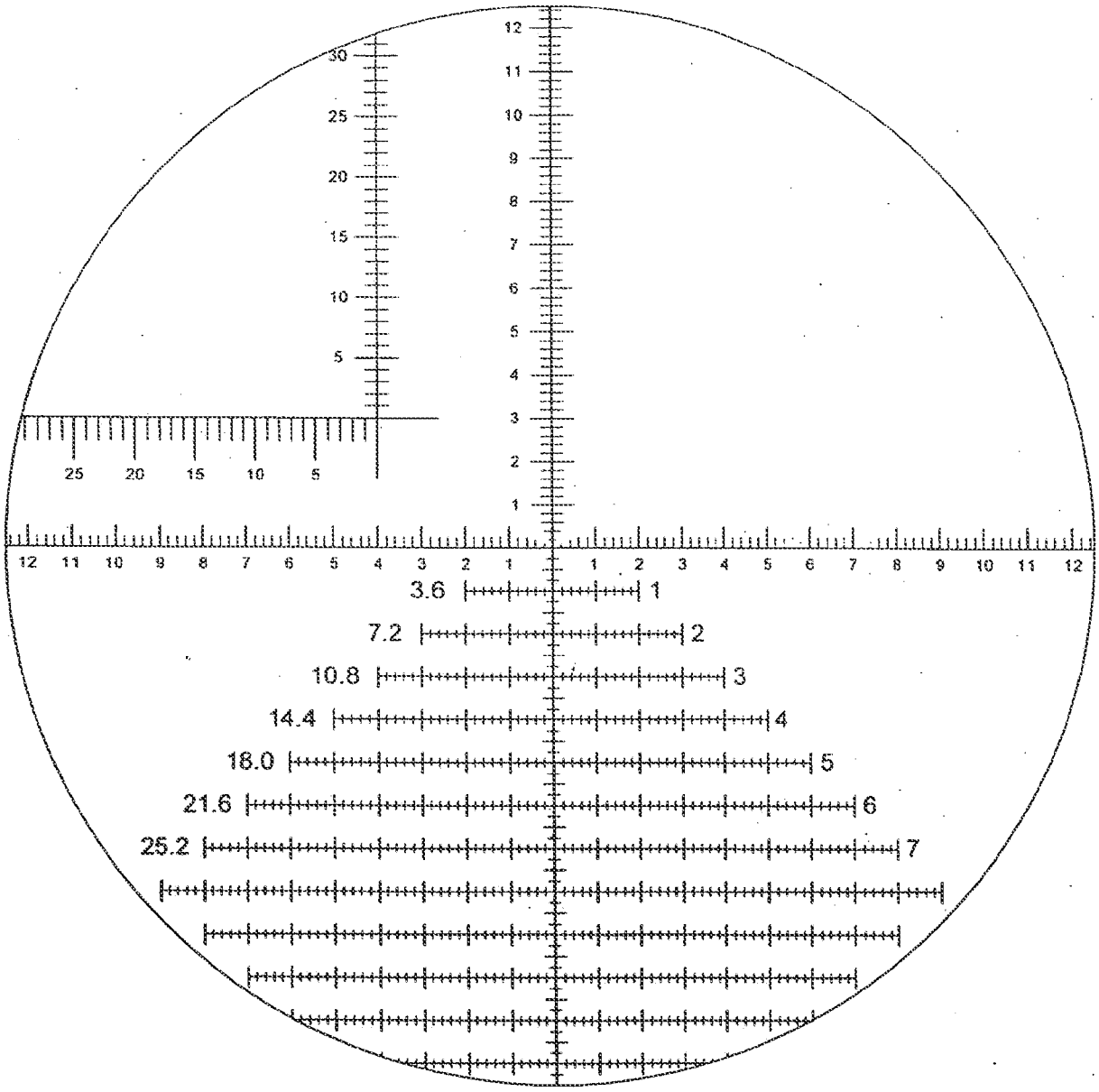
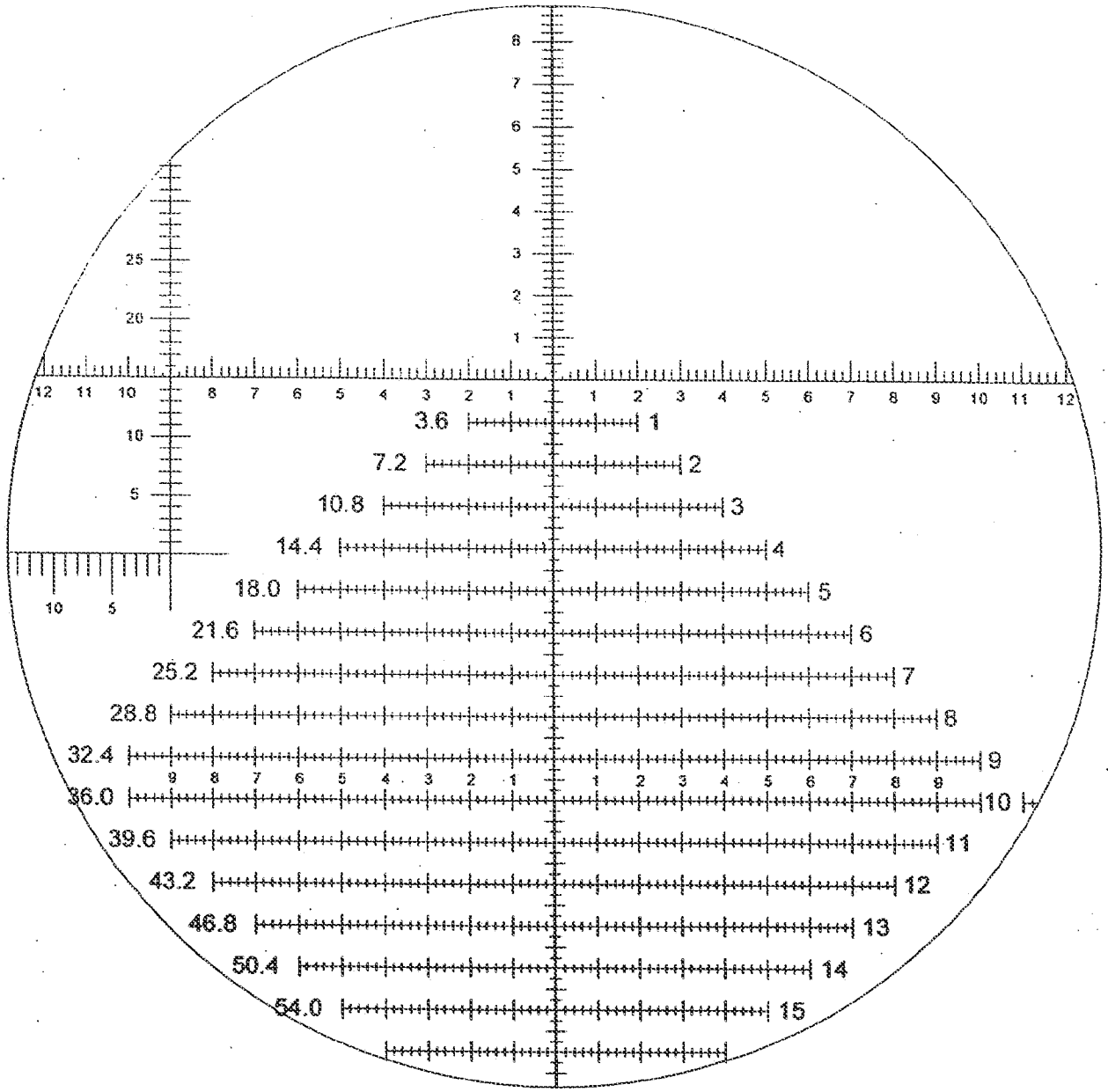

Start
Get Stored Params
Calculate and Display Results
Change Display ?
Y
Select Sub-Screen ?
Cancel
Display And Edit Sub-screen
Done
Is all Correct ?
N
Show Error
End ?
Y
Store Params
End

FIG. 22


12 11 10 9 8 7 6 5 4 3 2 1
1 2 3 4 5 6 7 8 9 10 11 12
30 25 20 15 10 5
25 20 15 10 5
3.6 1
7.2 2
10.8 3
14.4 4
18.0 5
21.6 6
25.2 7

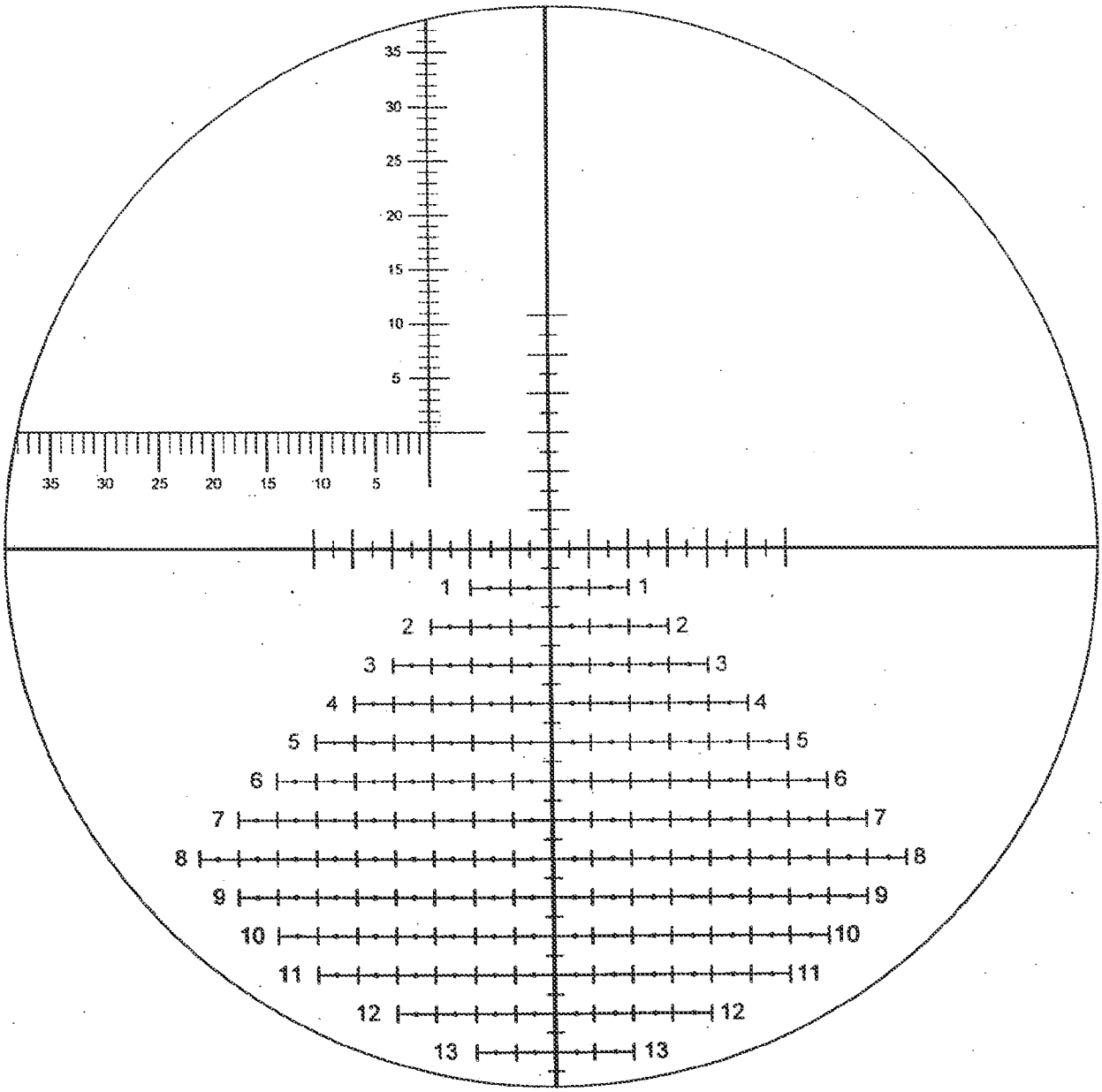
H-1

FIG. 23


3.6
7.2
10.8
14.4
18.0
21.6
25.2
28.8
32.4
36.0
39.6
43.2
46.8
50.4
54.0
1
2
3
4
5
6
7
8
9
10
11
12
13
14
15

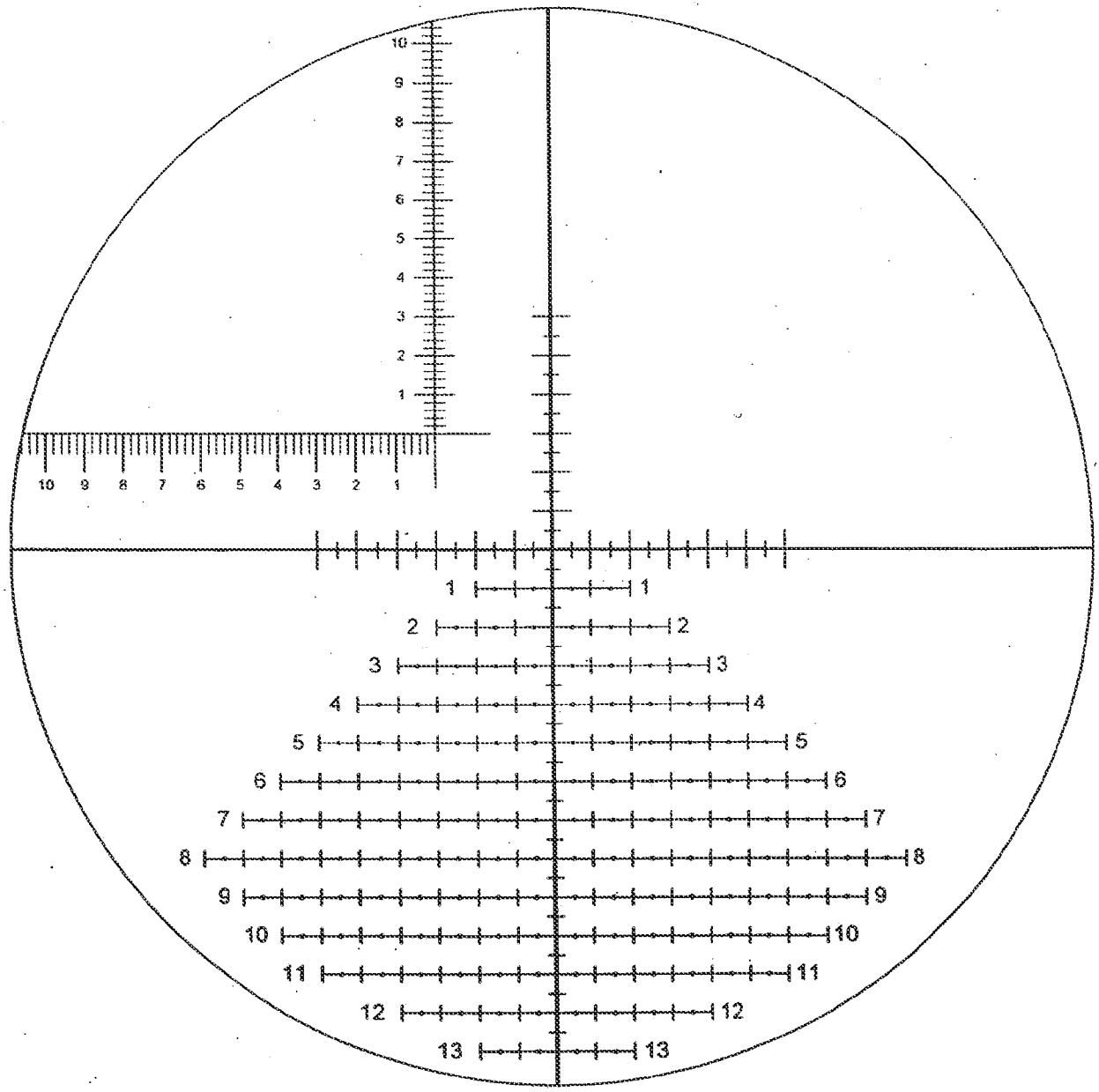
H-2

FIG. 24


35
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25
20
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10
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35 30 25 20 15 10 5
1 1
2 2
3 3
4 4
5 5
6 6
7 7
8 8
9 9
10 10
11 11
12 12
13 13

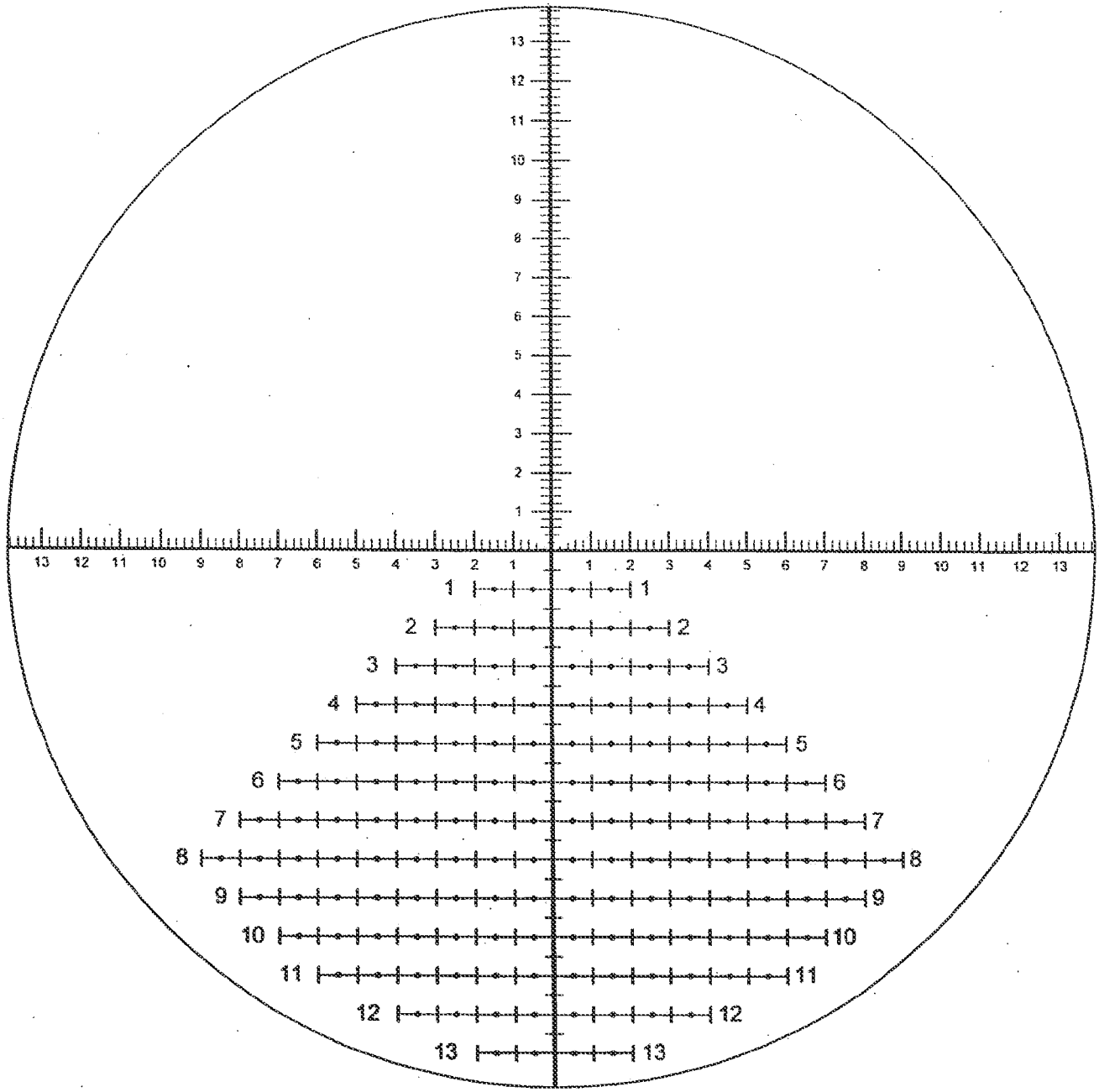
H-3

FIG. 25


10
9
8
7
6
5
4
3
2
1
10 9 8 7 6 5 4 3 2 1
1 1
2 2
3 3
4 4
5 5
6 6
7 7
8 8
9 9
10 10
11 11
12 12
13 13

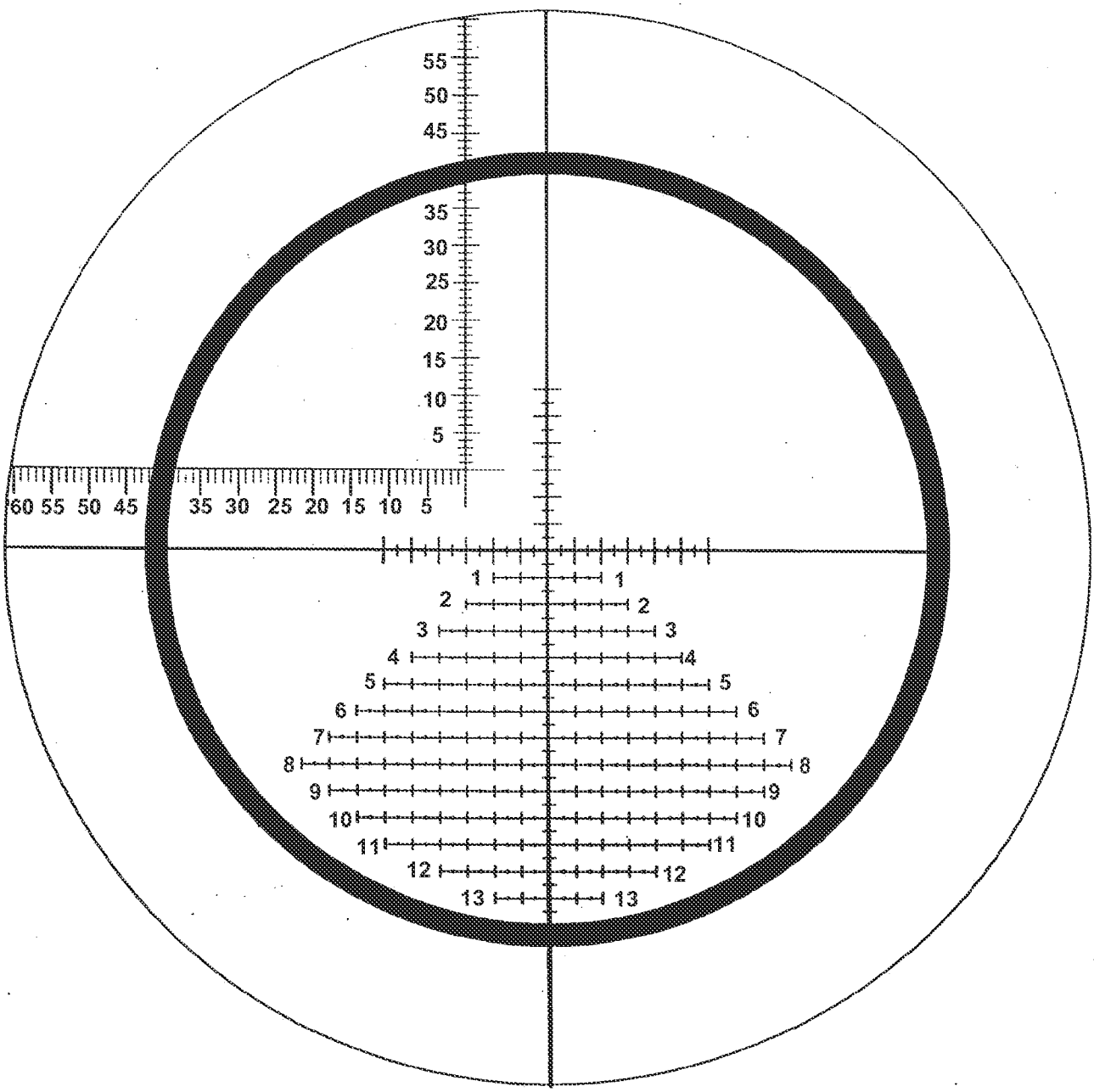
H-4

FIG. 26


13 12 11 10 9 8 7 6 5 4 3 2 1
1 2 3 4 5 6 7 8 9 10 11 12 13
1 1
2 2
3 3
4 4
5 5
6 6
7 7
8 8
9 9
10 10
11 11
12 12
13 13

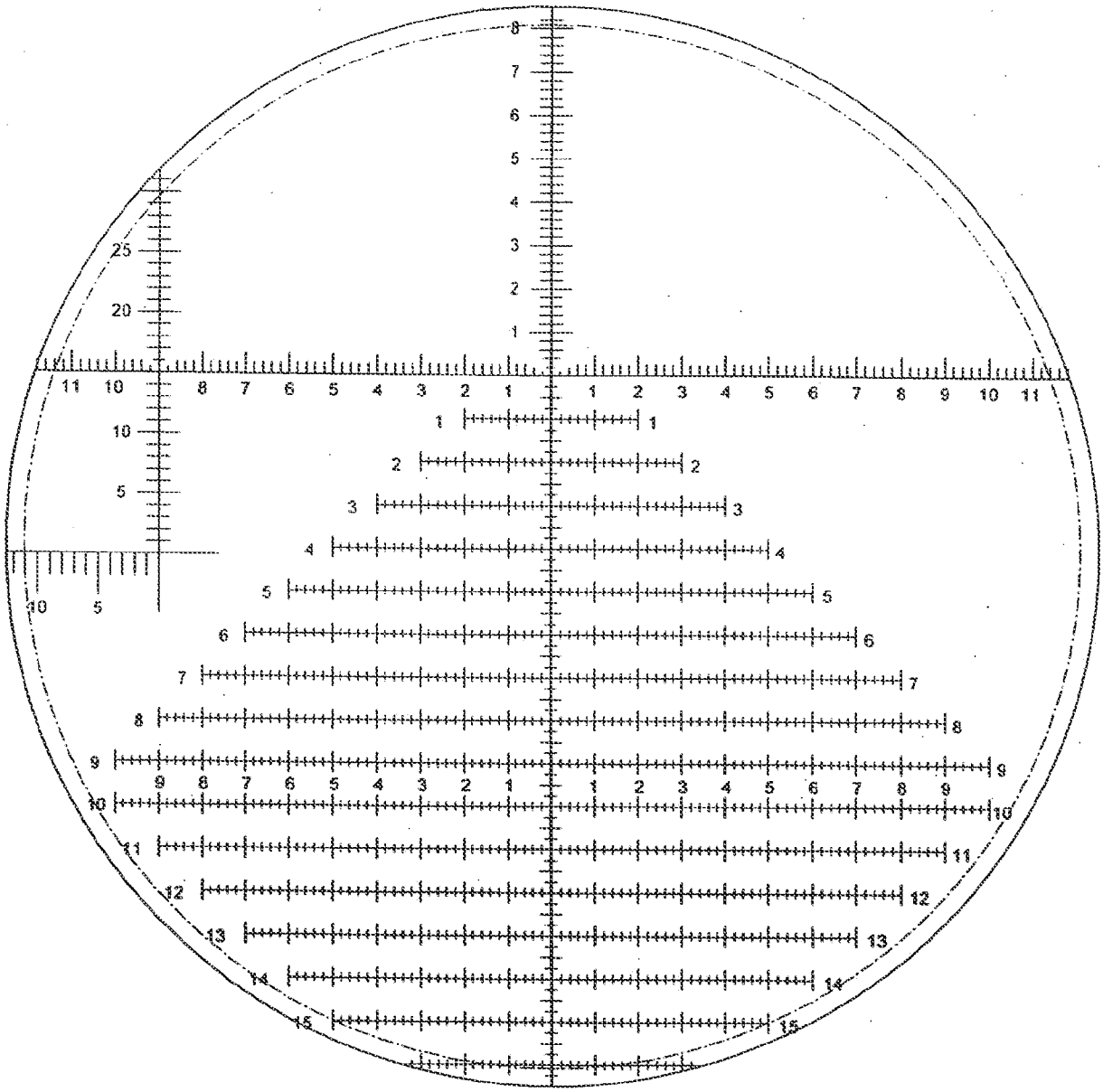
H-5

FIG. 27


55
50
45
35
30
25
20
15
10
5
60 55 50 45
35 30 25 20 15 10 5
1
2
3
4
5
6
7
8
9
10
11
12
13

H-6

FIG. 28



H-11

FIG. 29

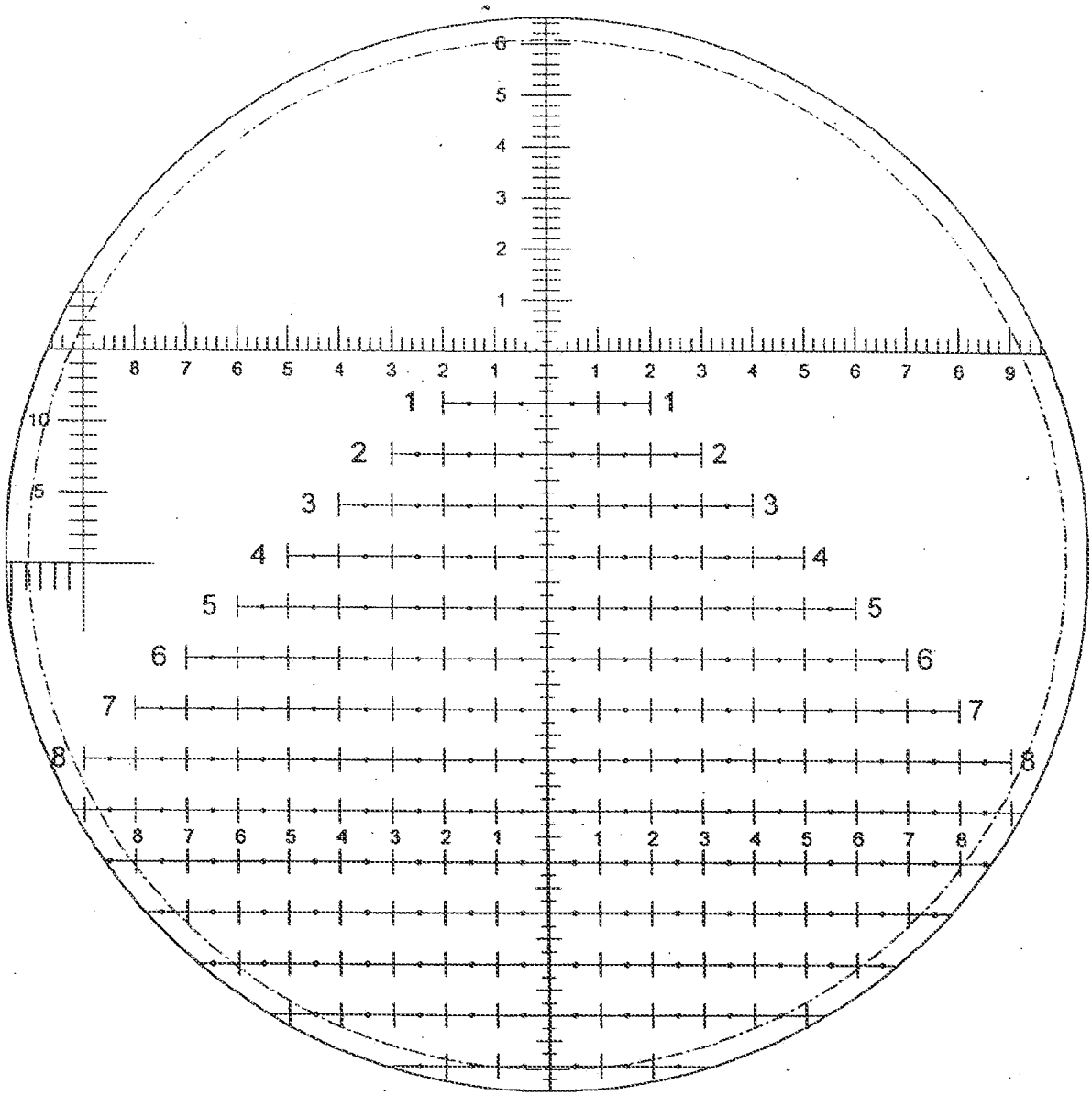
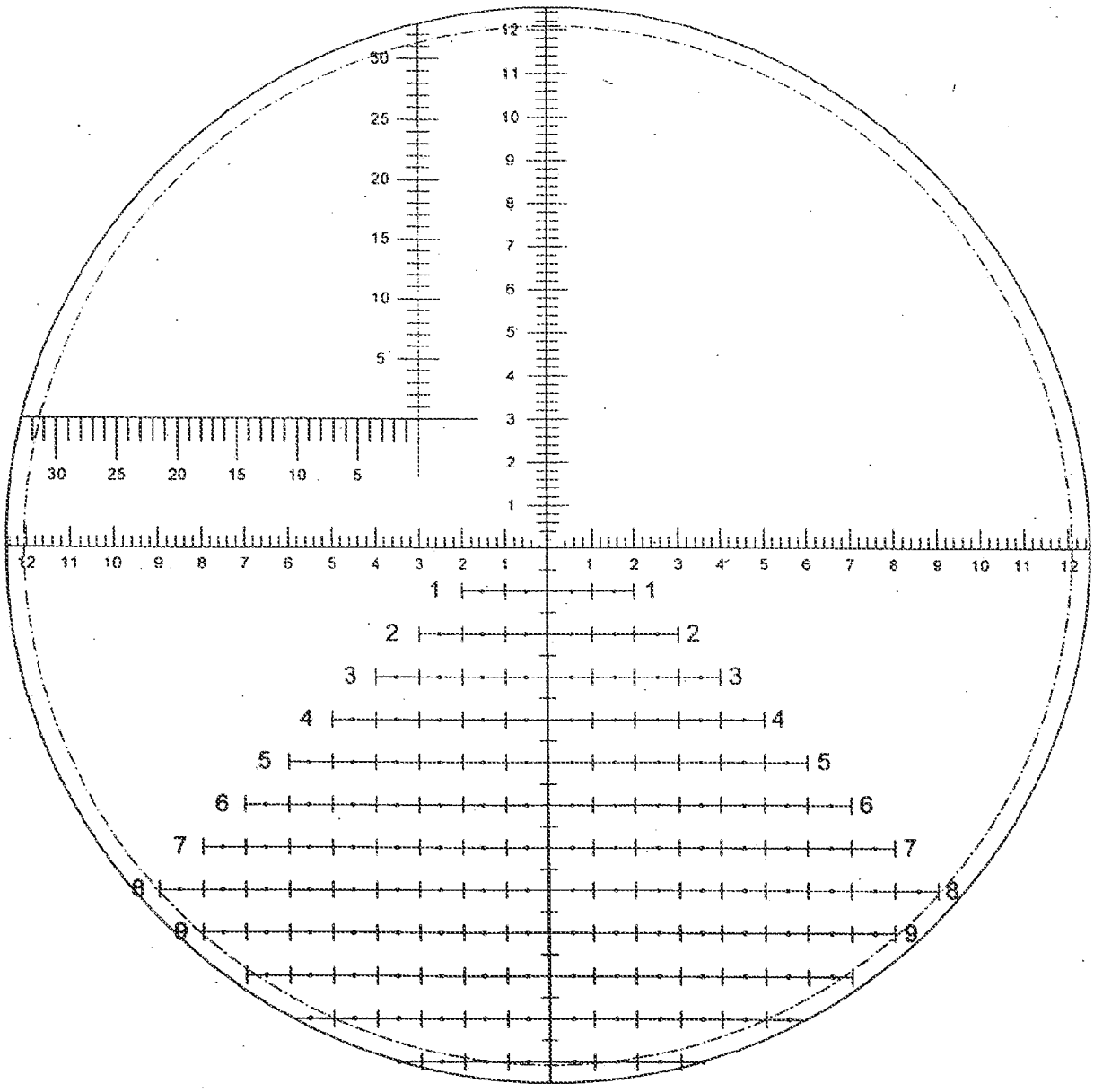
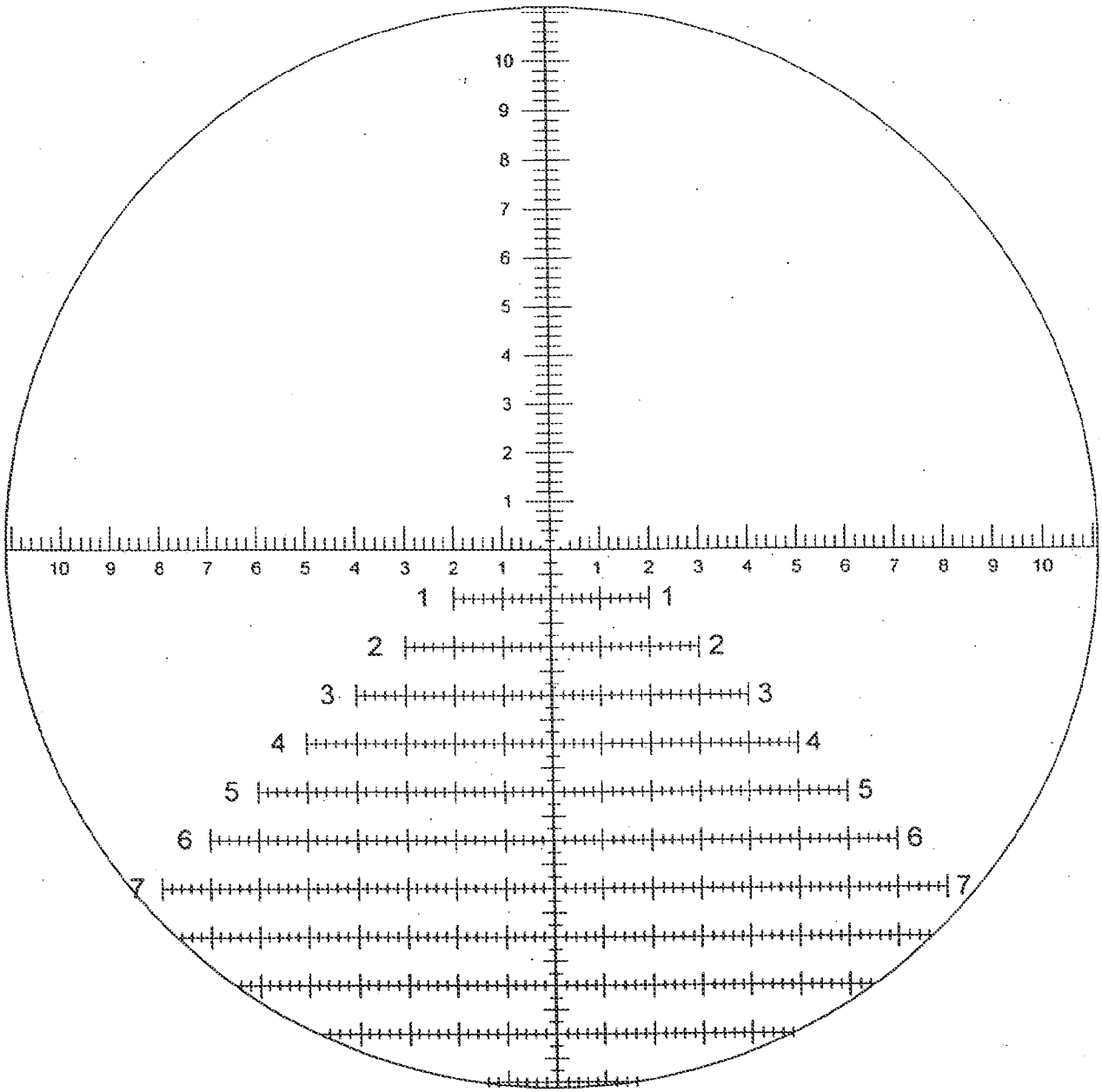


FIG. 30



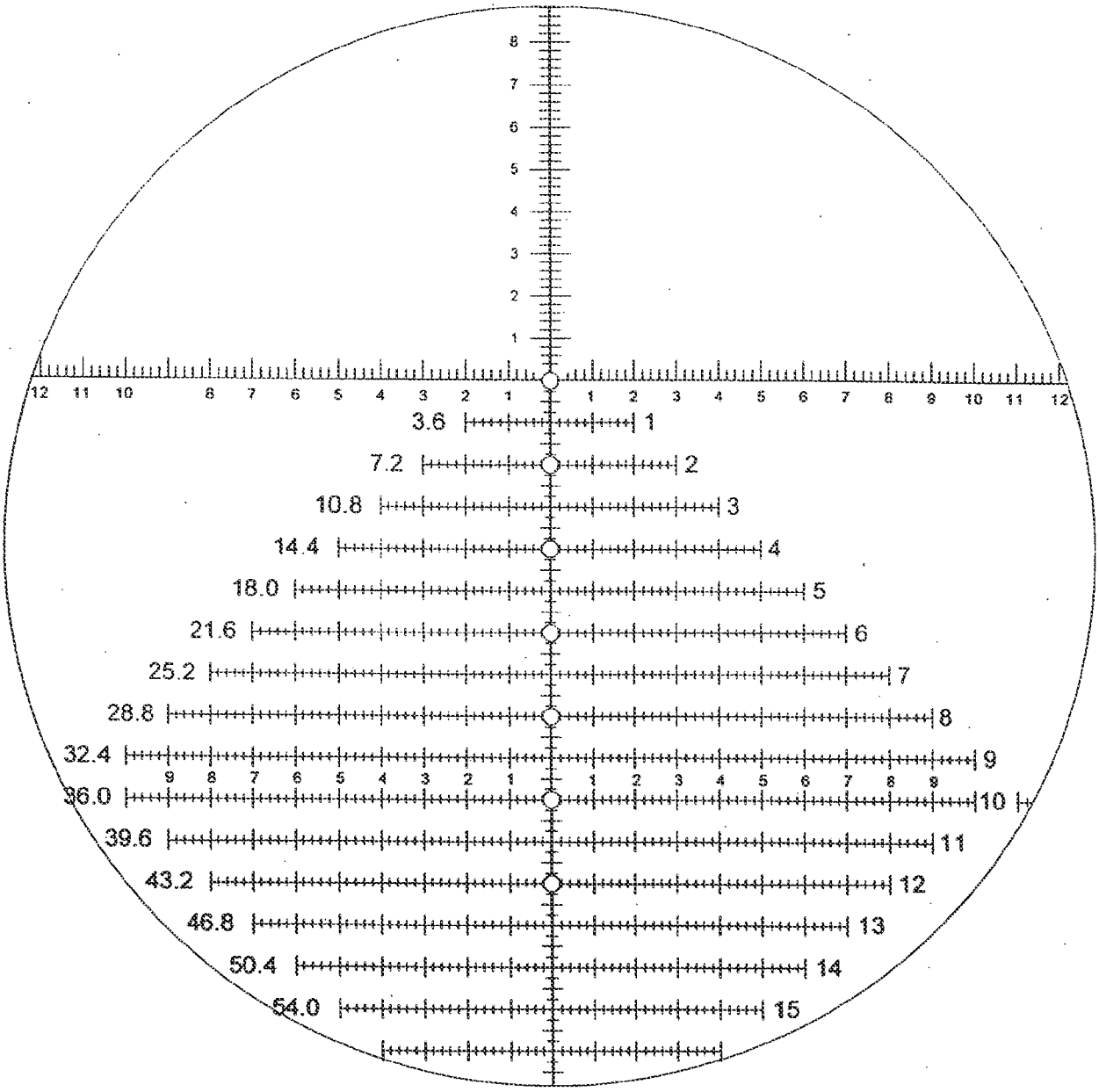
H-13

FIG. 31



H-14

FIG. 32



H-15

FIG. 33

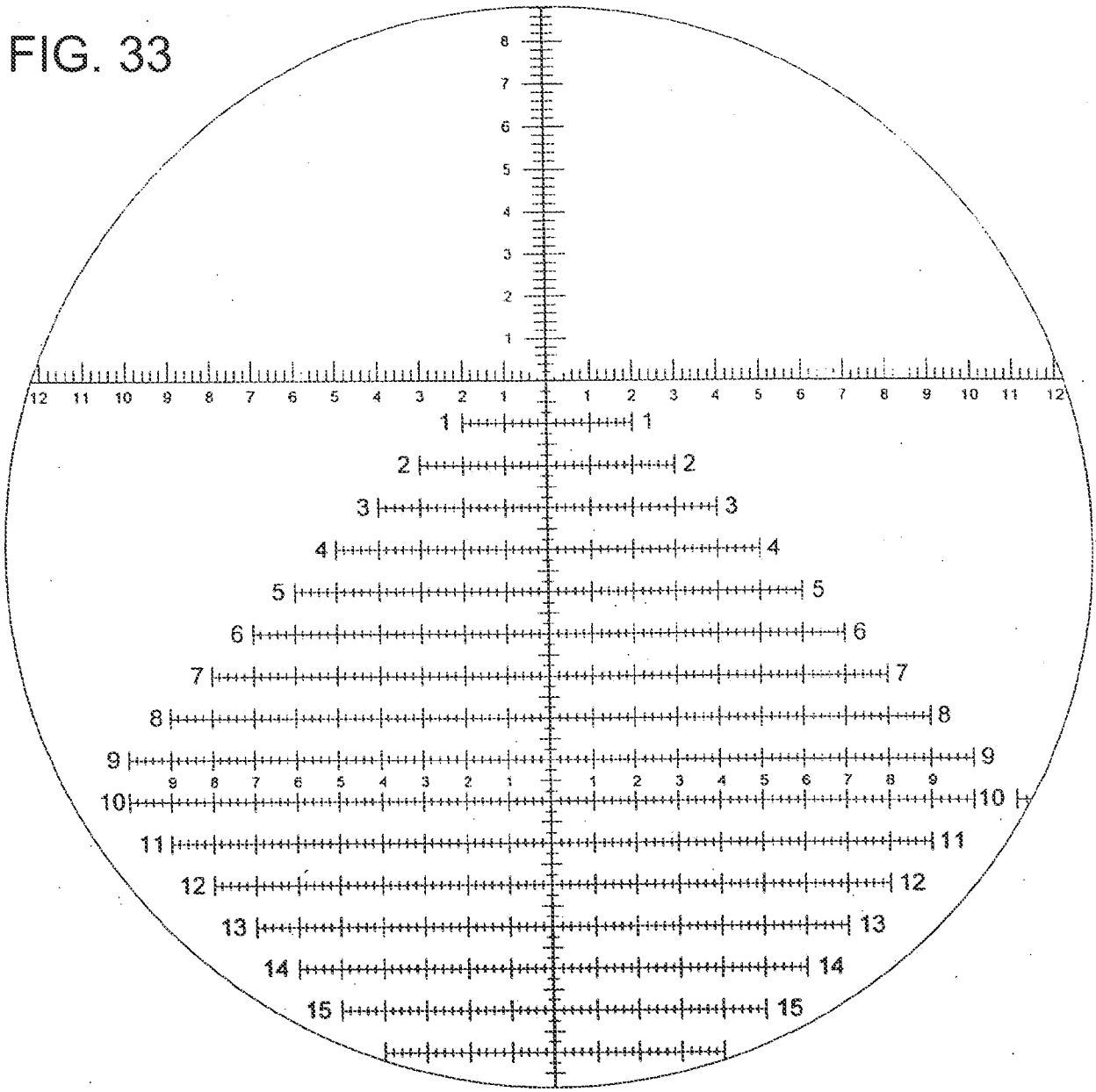
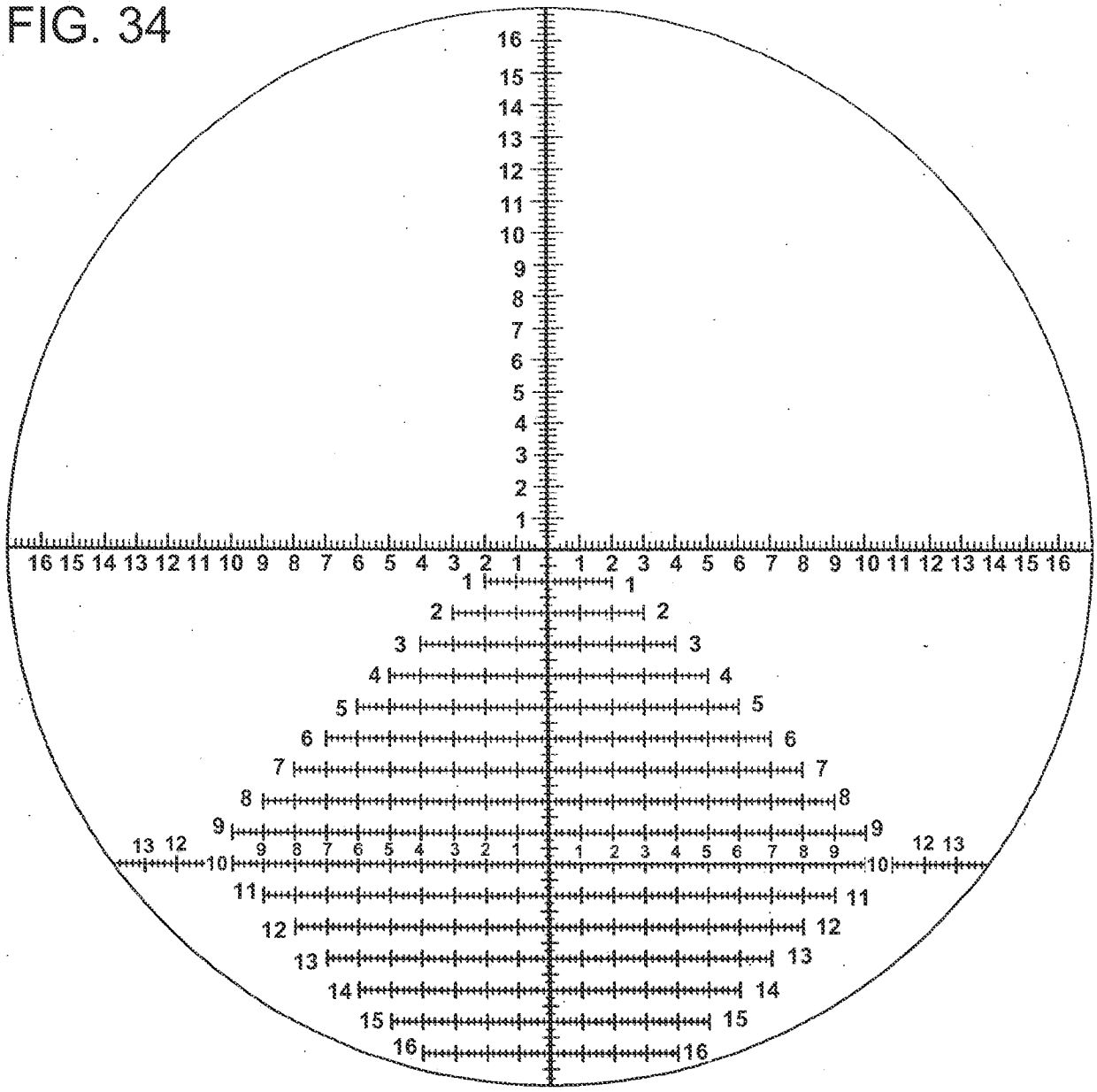
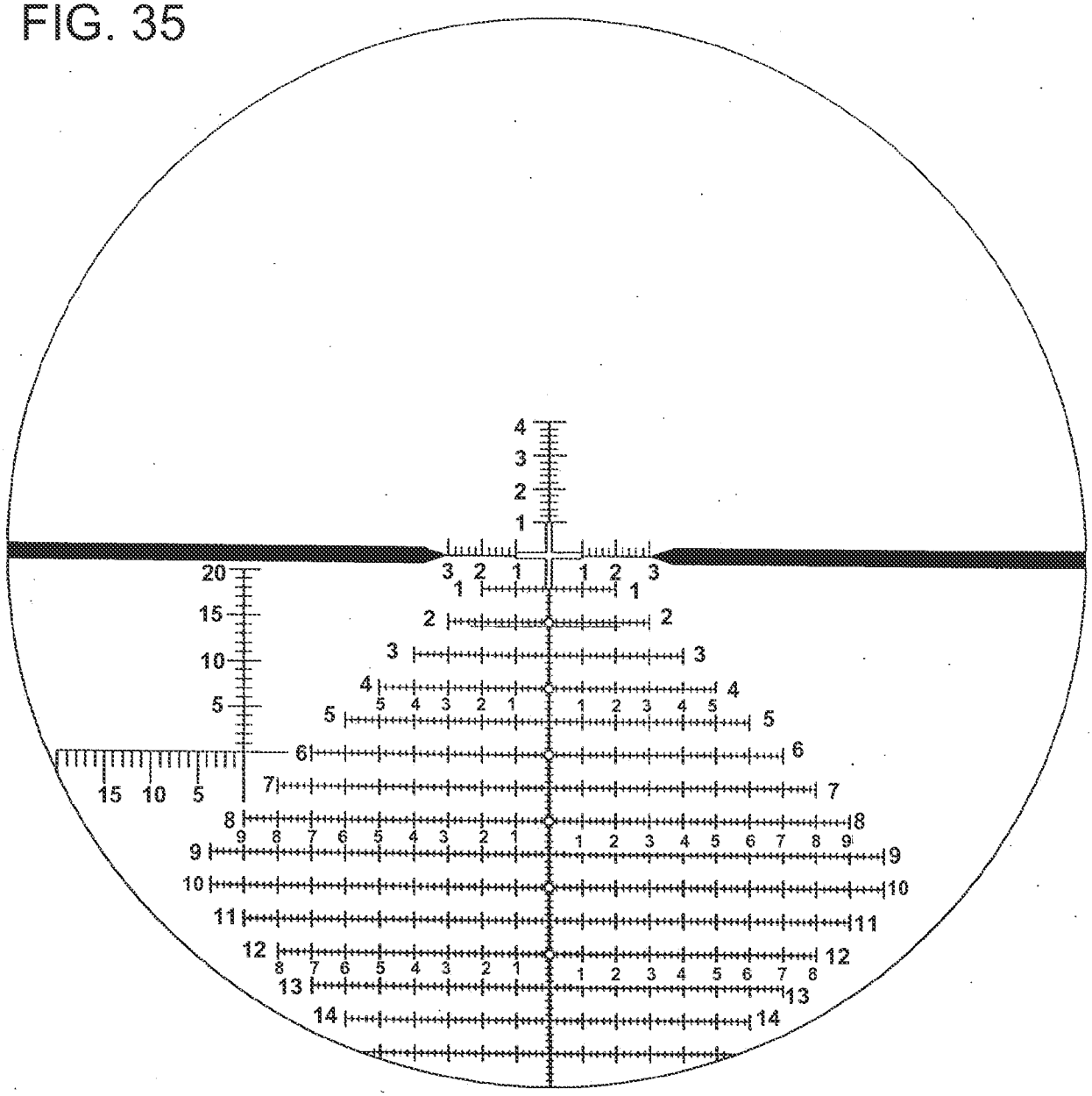


FIG. 34


16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16
13 12 11 10 9 8 7 6 5 4 3 2 1
1 2 3 4 5 6 7 8 9 10 11 12 13

H-21

FIG. 35


4
3
2
1
3 2 1 1 2 3
1 1
2 2
3 3
4 4
5 4 3 2 1 1 2 3 4 5
5 5
6 6
7 7
8 8
9 8 7 6 5 4 3 2 1 1 2 3 4 5 6 7 8 9
9 9
10 10
11 11
12 12
8 7 6 5 4 3 2 1 1 2 3 4 5 6 7 8
13 13
14 14
20
15
10
5
15 10 5

H-25

FIG. 35a

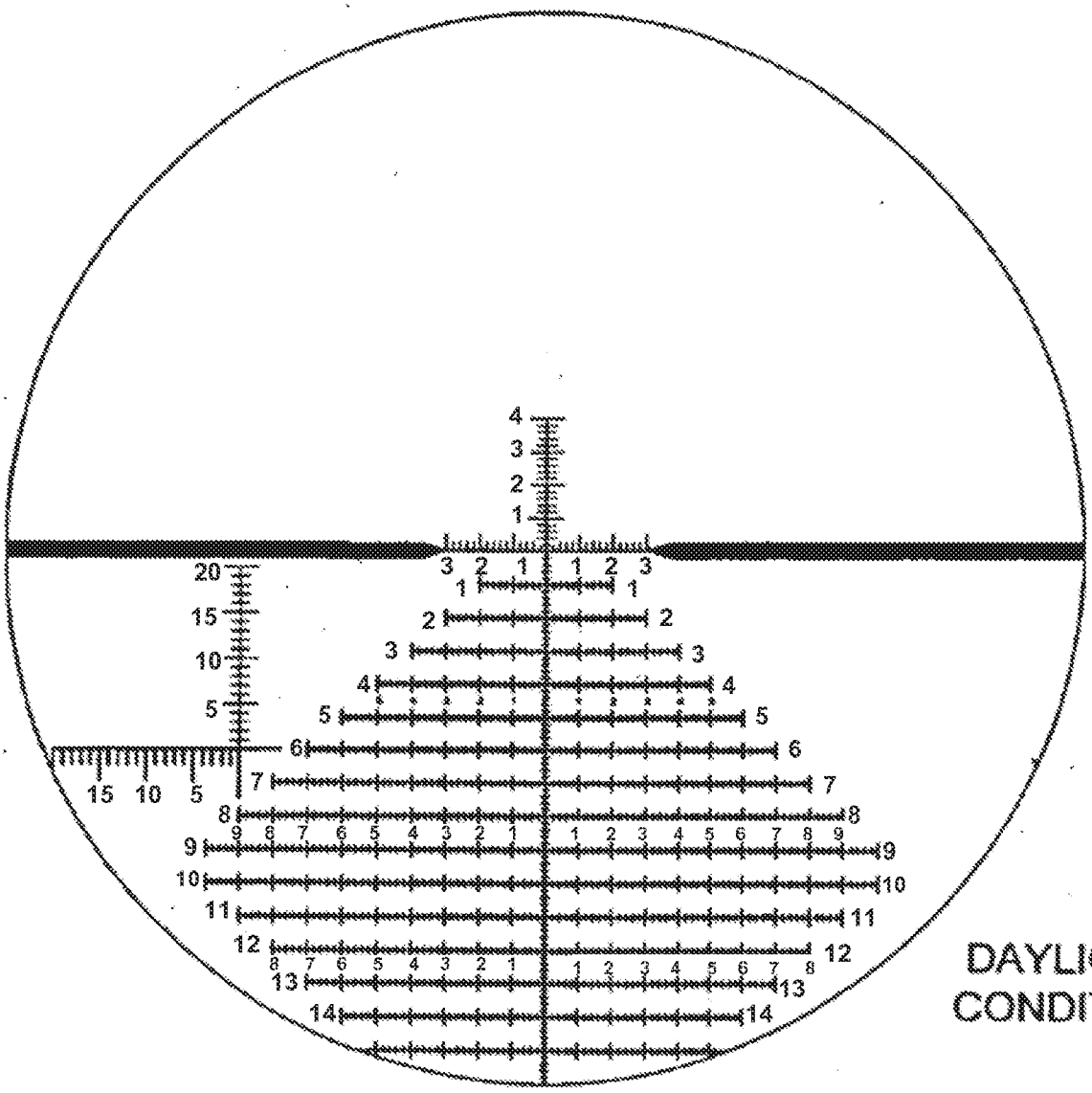


FIG. 35b

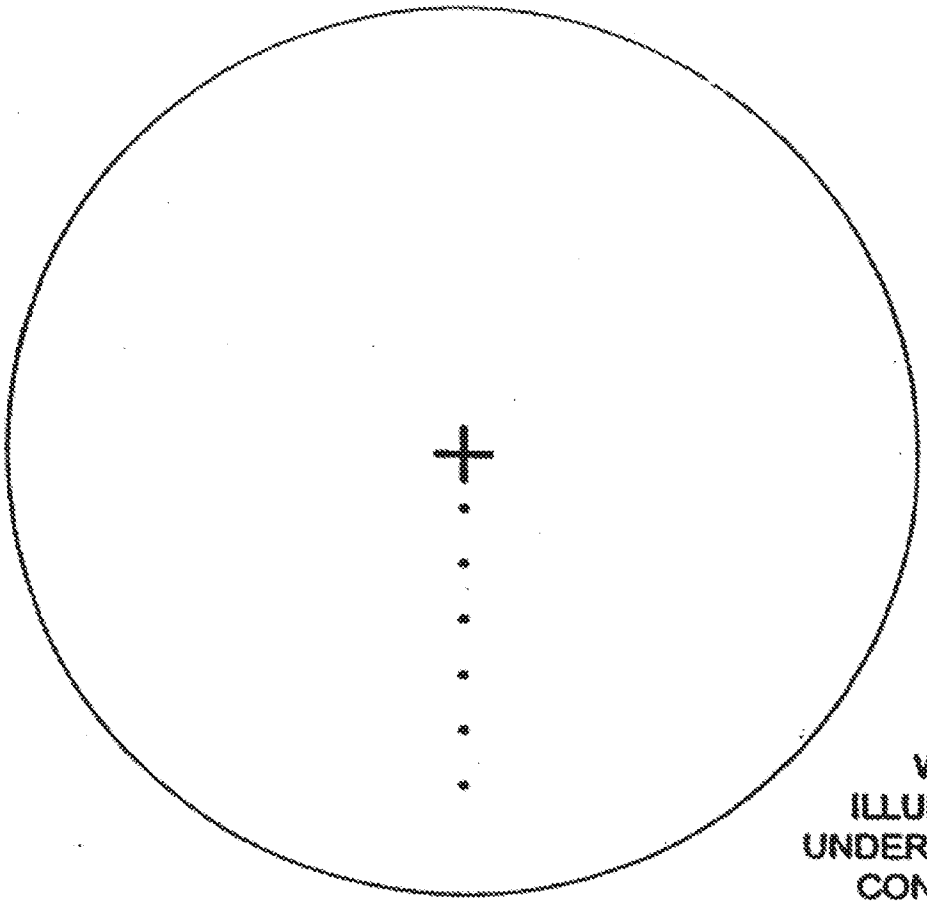
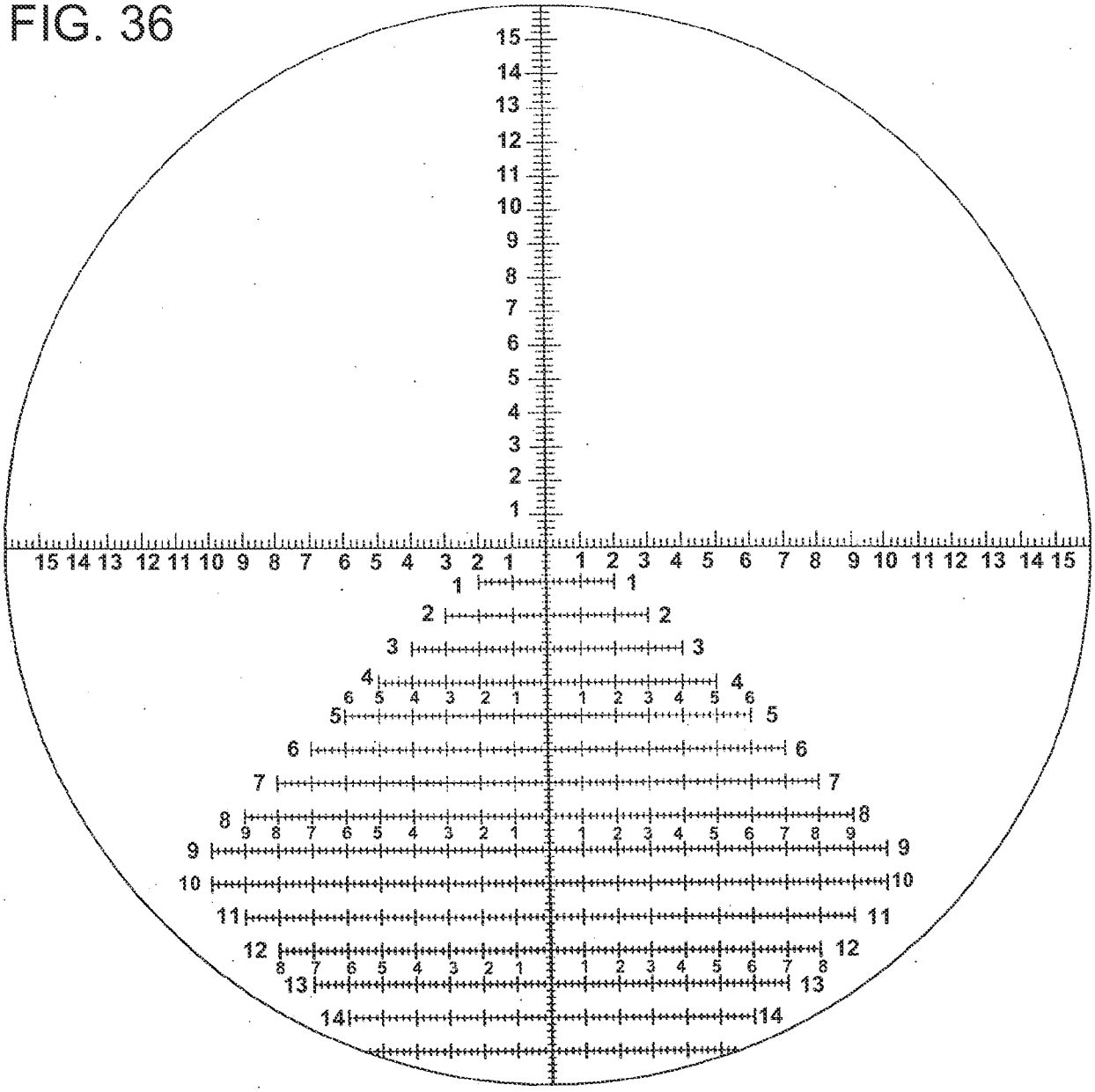
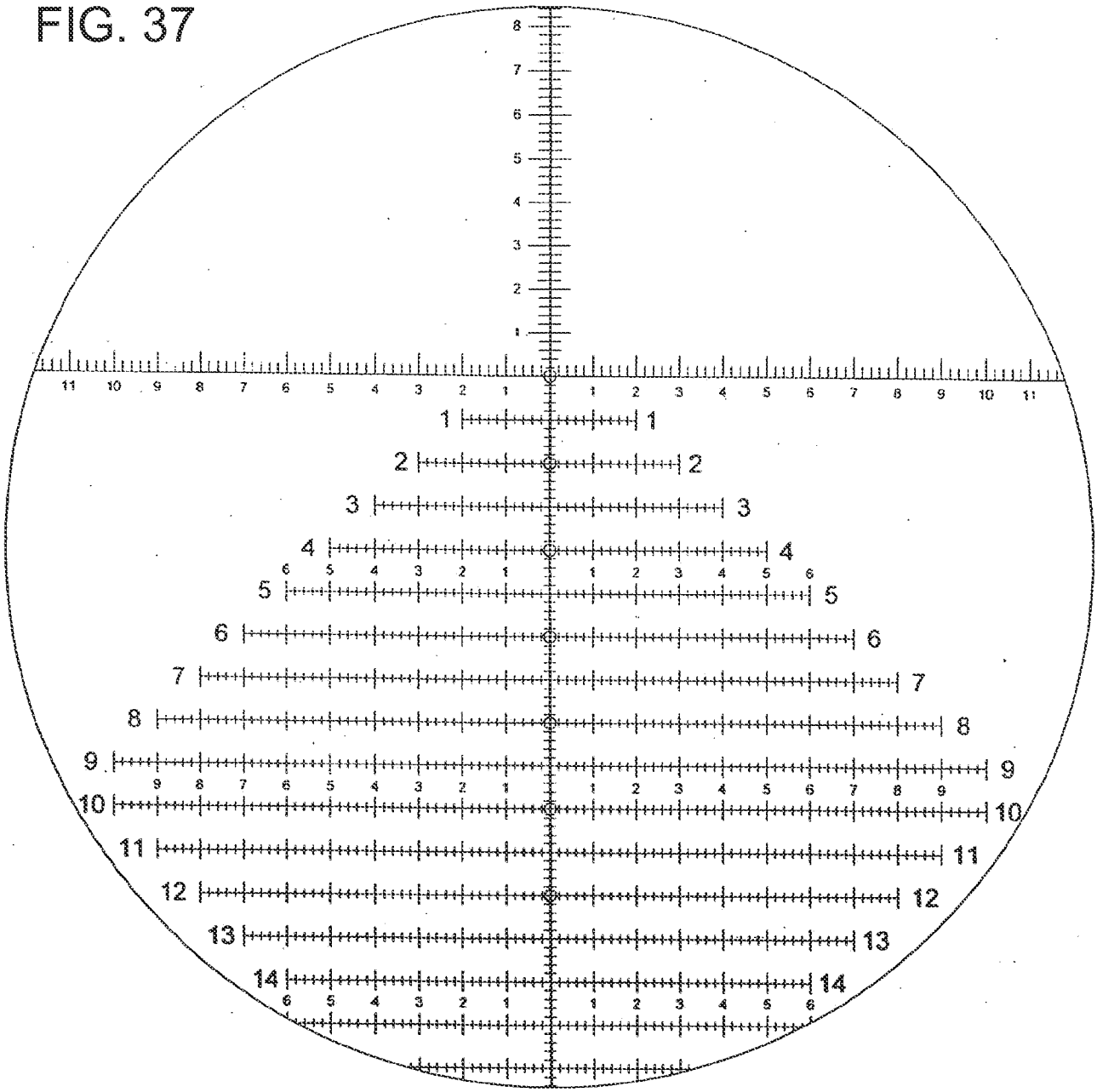


FIG. 36



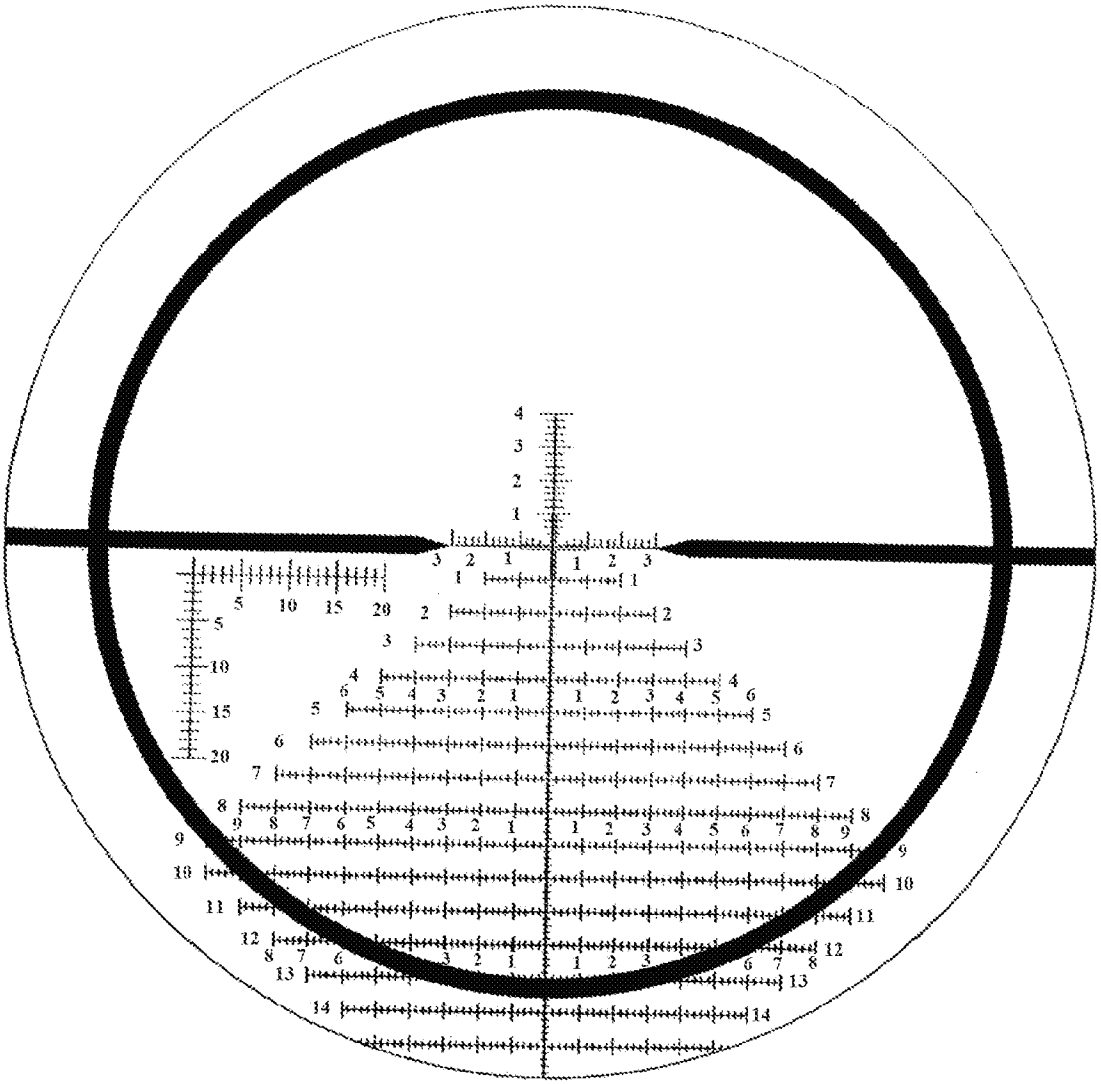
H-31

FIG. 37

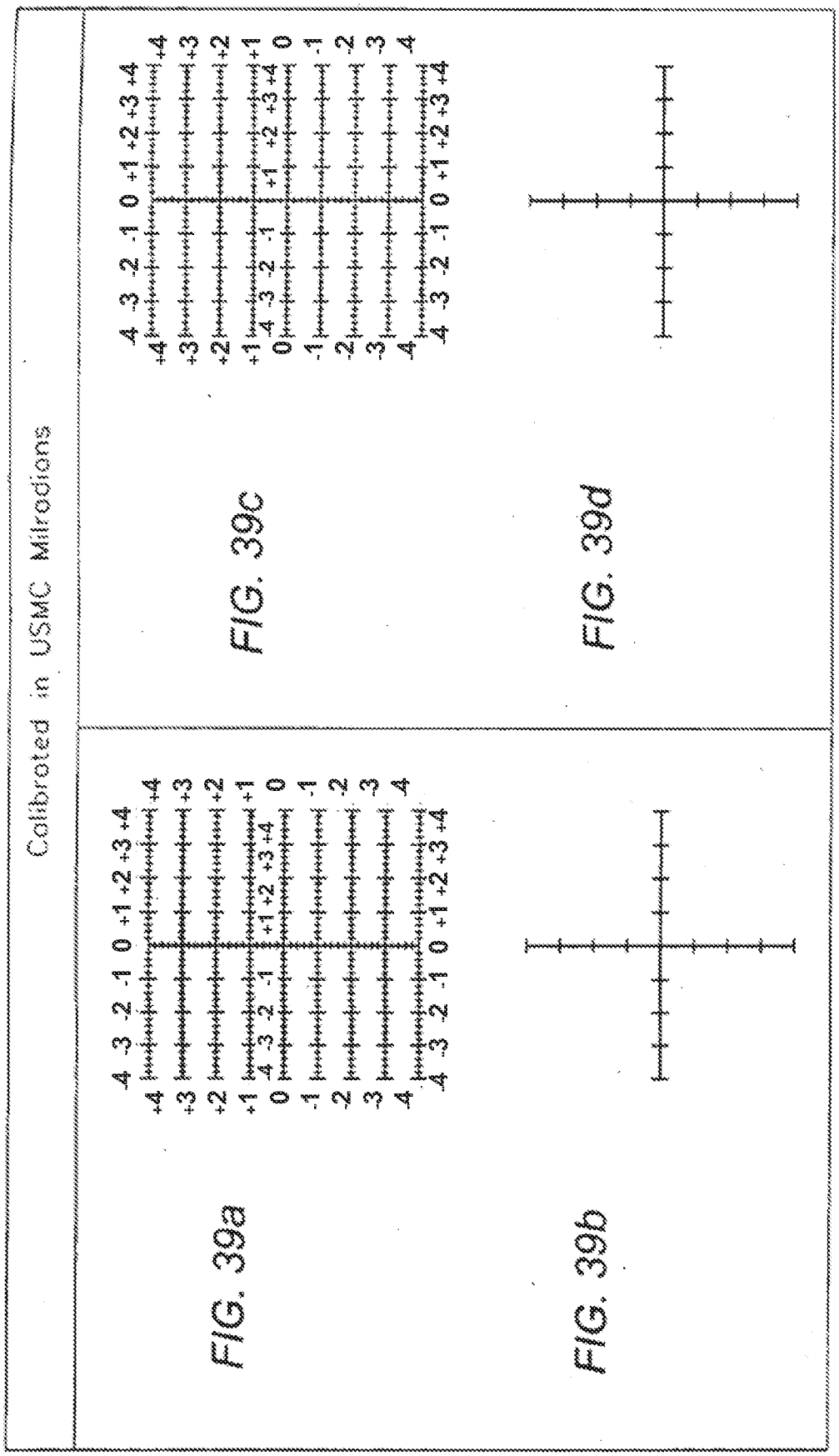


H-39

FIG. 38



H-45


Calibrated in USMC Milradians
FIG. 39a
FIG. 39b
FIG. 39c
FIG. 39d
Reticle can be used in 1st or 2nd plane

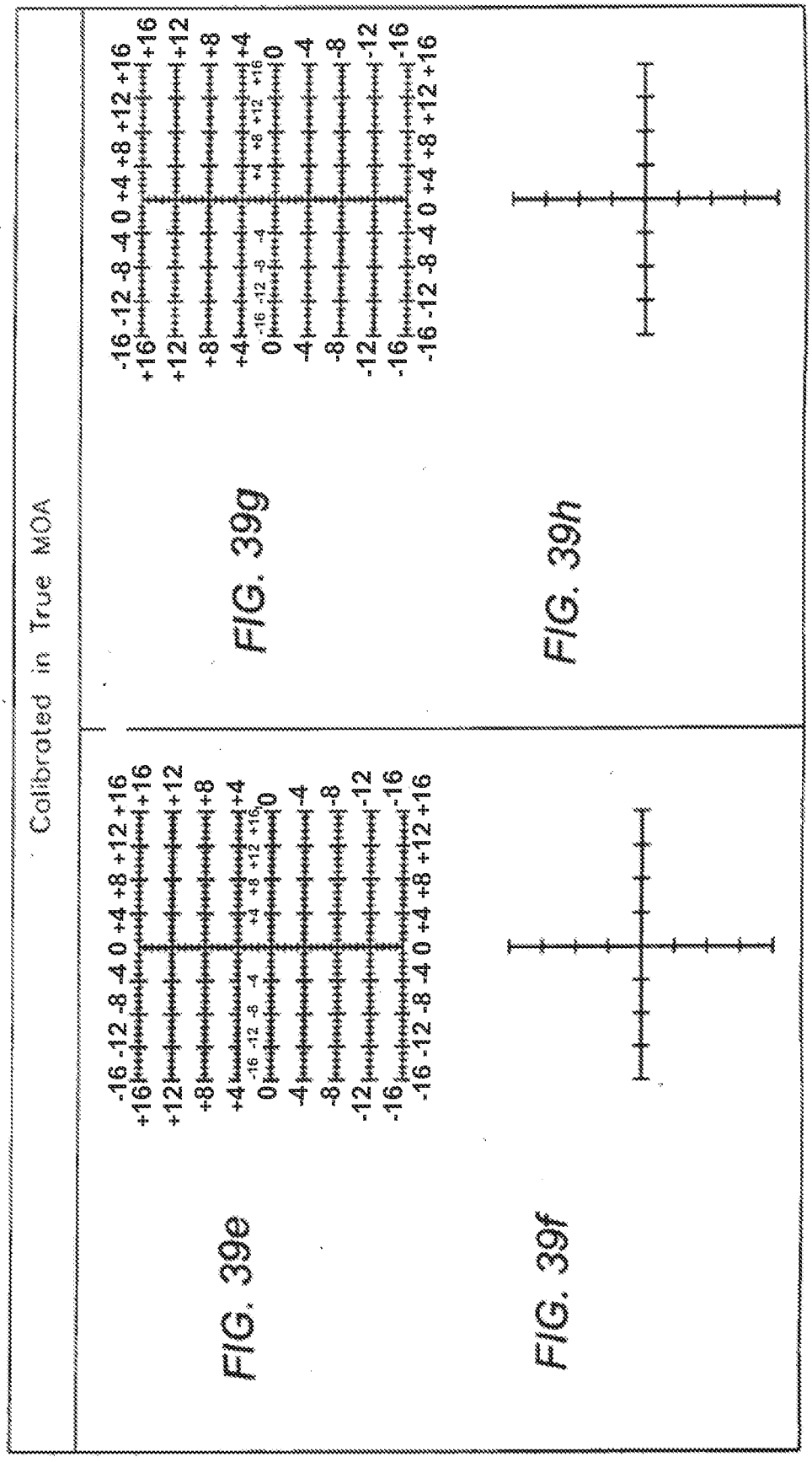


FIG. 39e

FIG. 39f

FIG. 39g

FIG. 39h

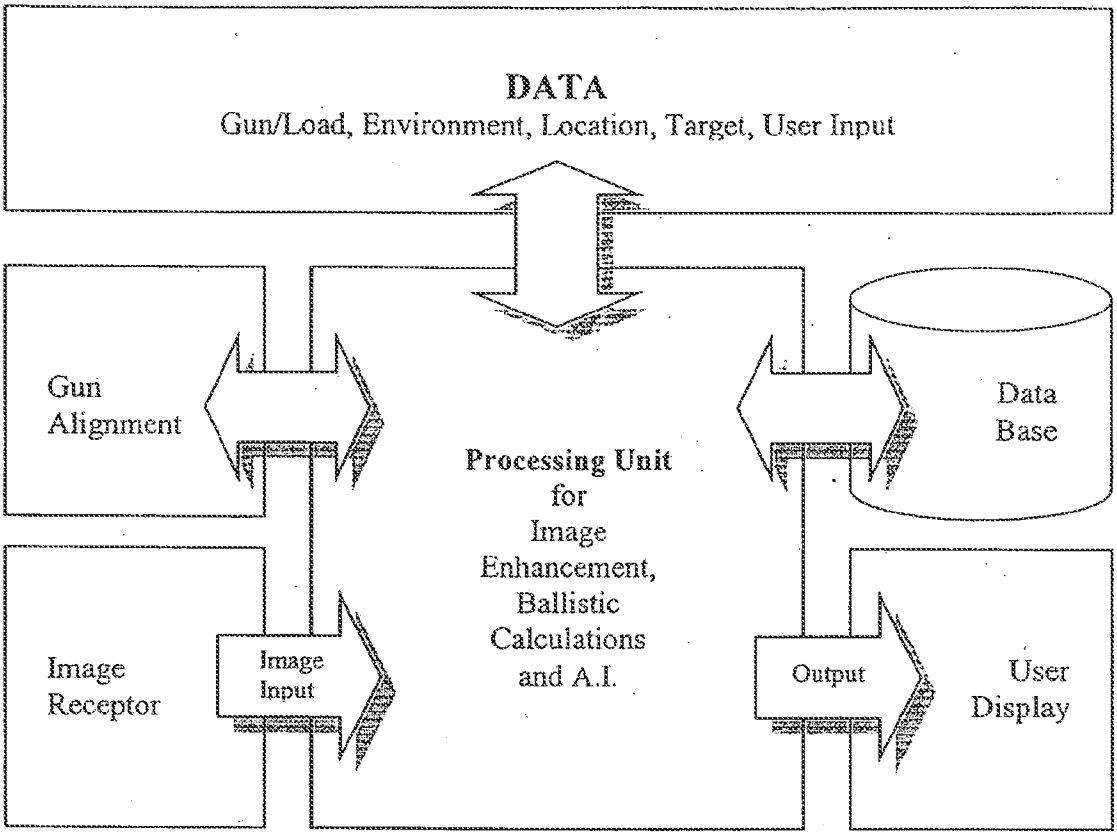

DATA
Gun/Load, Environment, Location, Target, User Input
Gun Alignment
Processing Unit for Image Enhancement, Ballistic Calculations and A.I.
Data Base
Image Receptor
Image Input
Output
User Display

FIG. 40

FIG. 41a

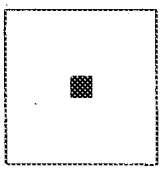


FIG. 41b

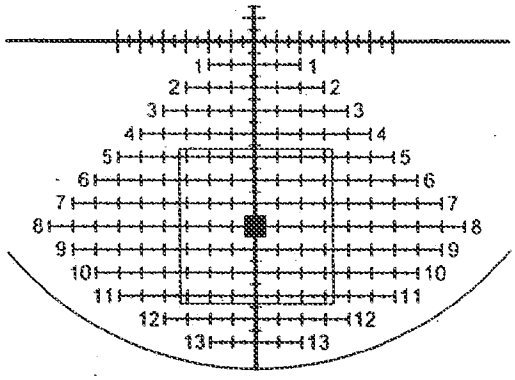


FIG. 41c

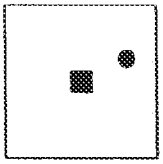


FIG. 41d

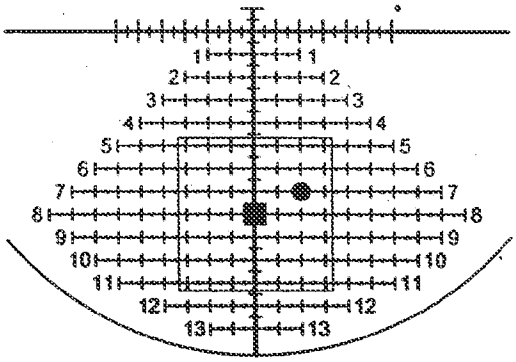


FIG. 41e

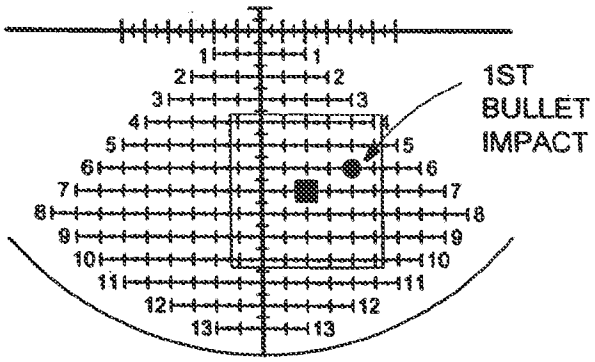


FIG. 41f

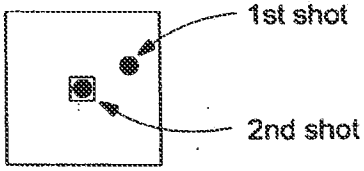
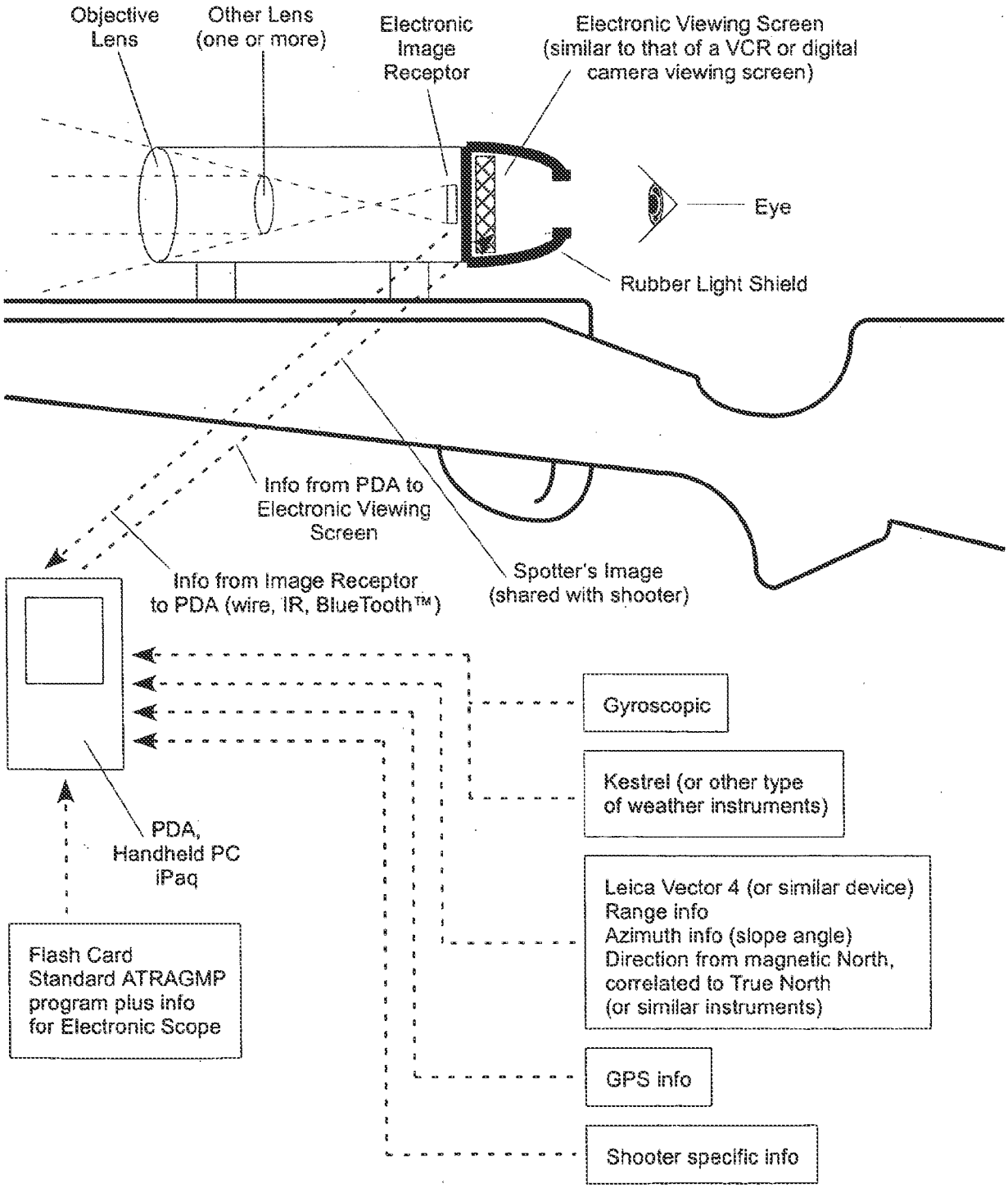


FIG. 42

Overview



Electronic Target Acquisition Device

FIG. 43a

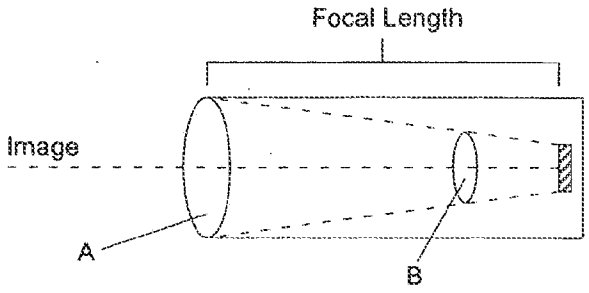


FIG. 43b

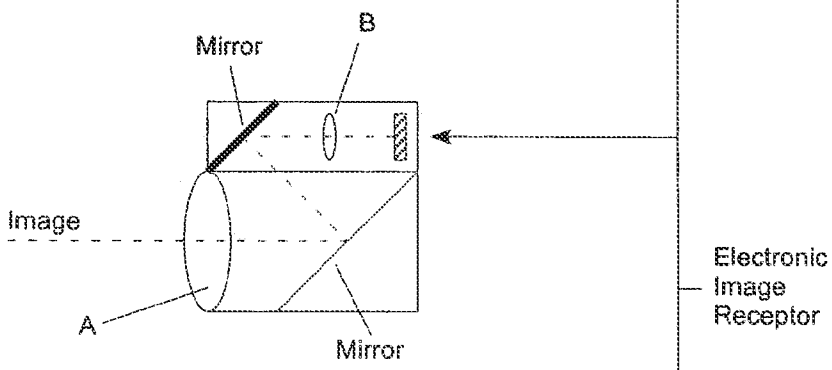
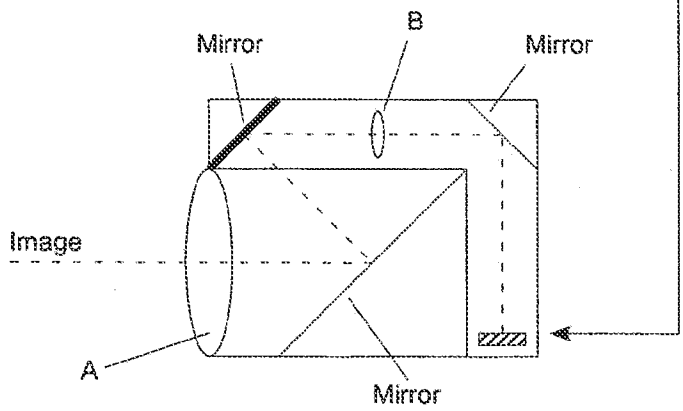


FIG. 43c



A = Objective lens

B = Additional lenses (one or more)

FIG. 43a = Full focal length (long length tube)

FIG. 43b & FIG. 43c = Mirrors or prisms to reduce scope length

FIG. 44a

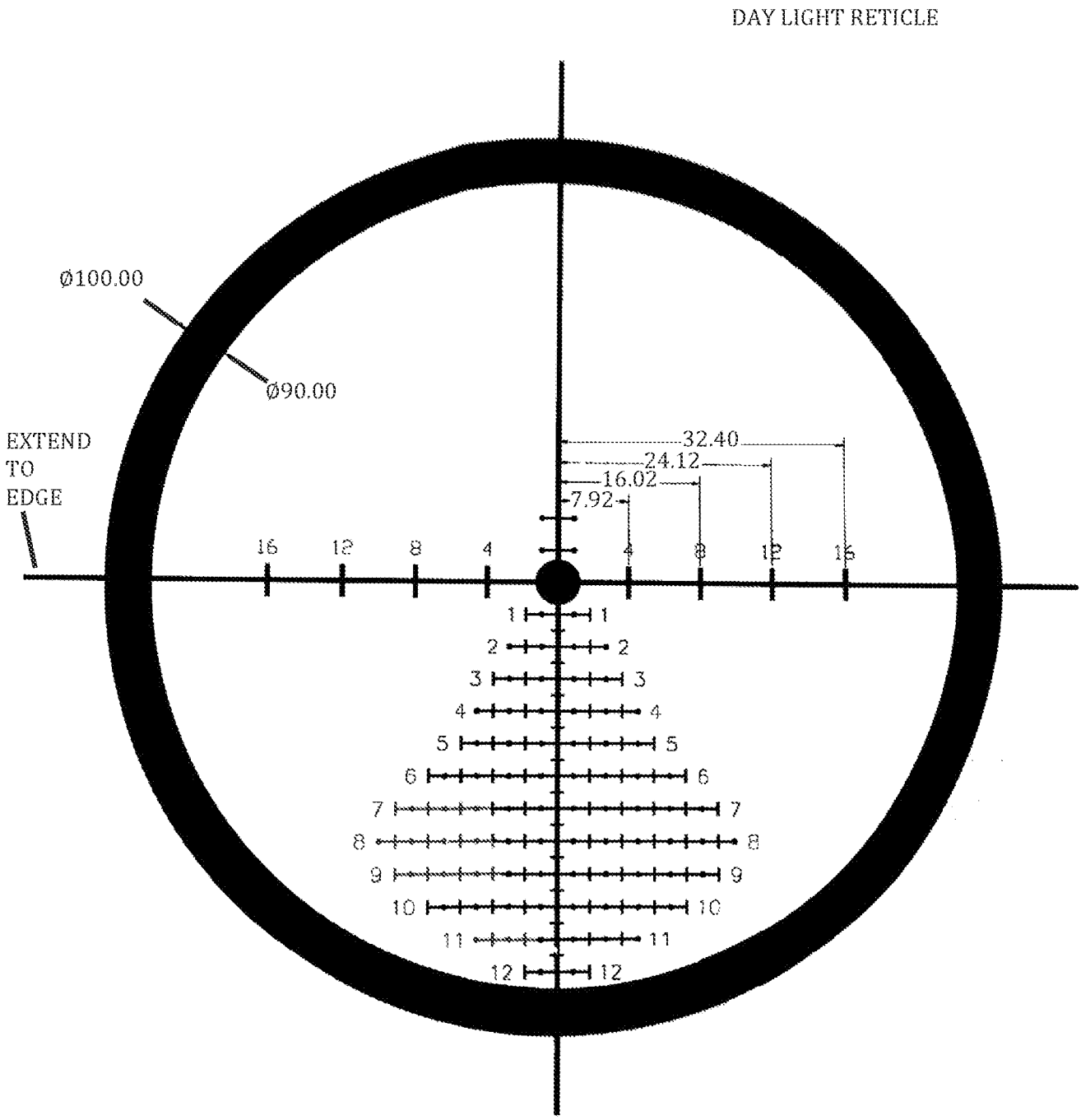

DAY LIGHT RETICLE
Ø100.00
Ø90.00
EXTEND
TO
EDGE
32.40
24.12
16.02
7.92
16
12
8
4
4
8
12
16
1
2
3
4
5
6
7
8
9
10
11
12
SHOWN AT X4 POWER

FIG. 44b

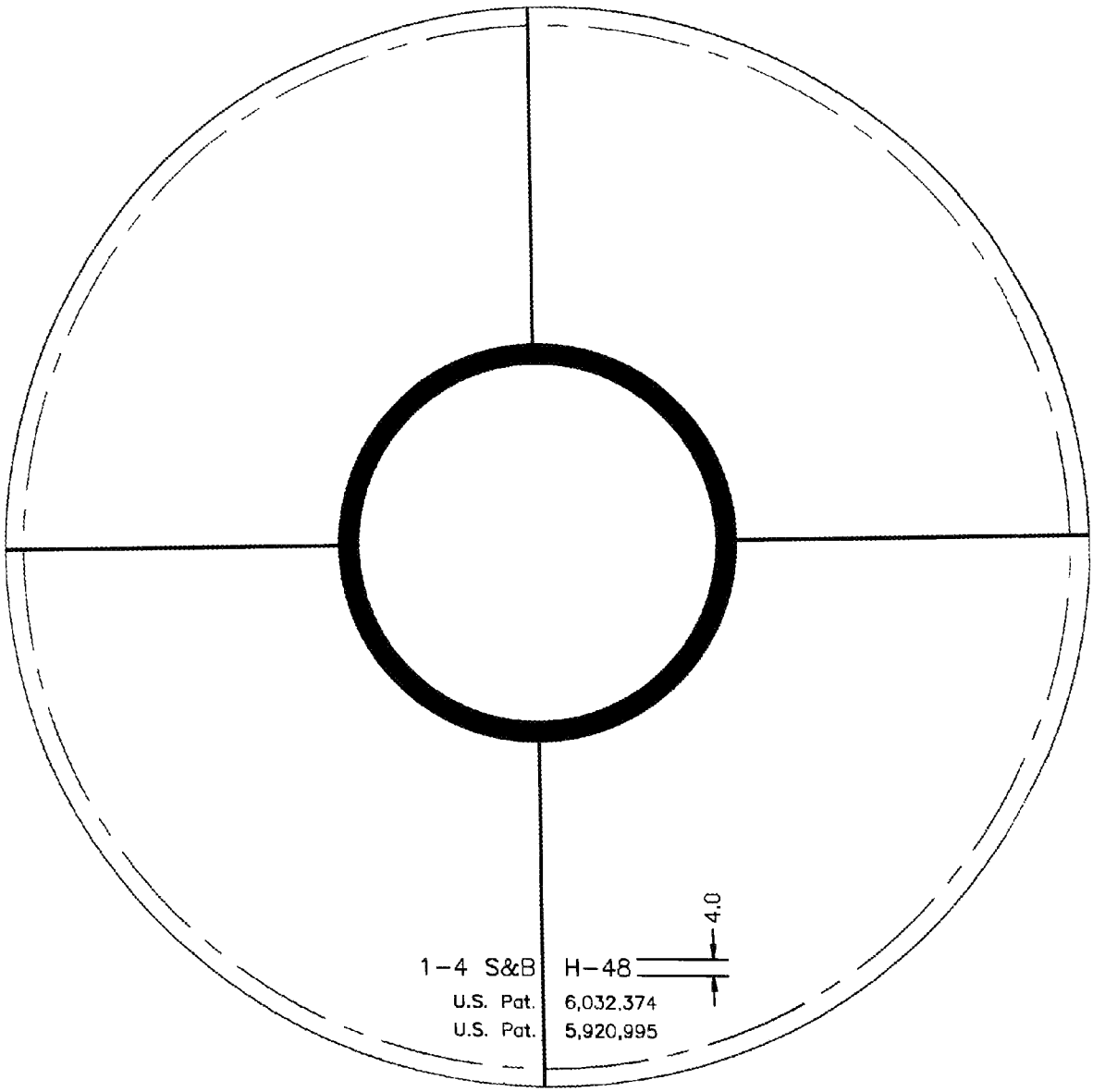


FIG. 44c

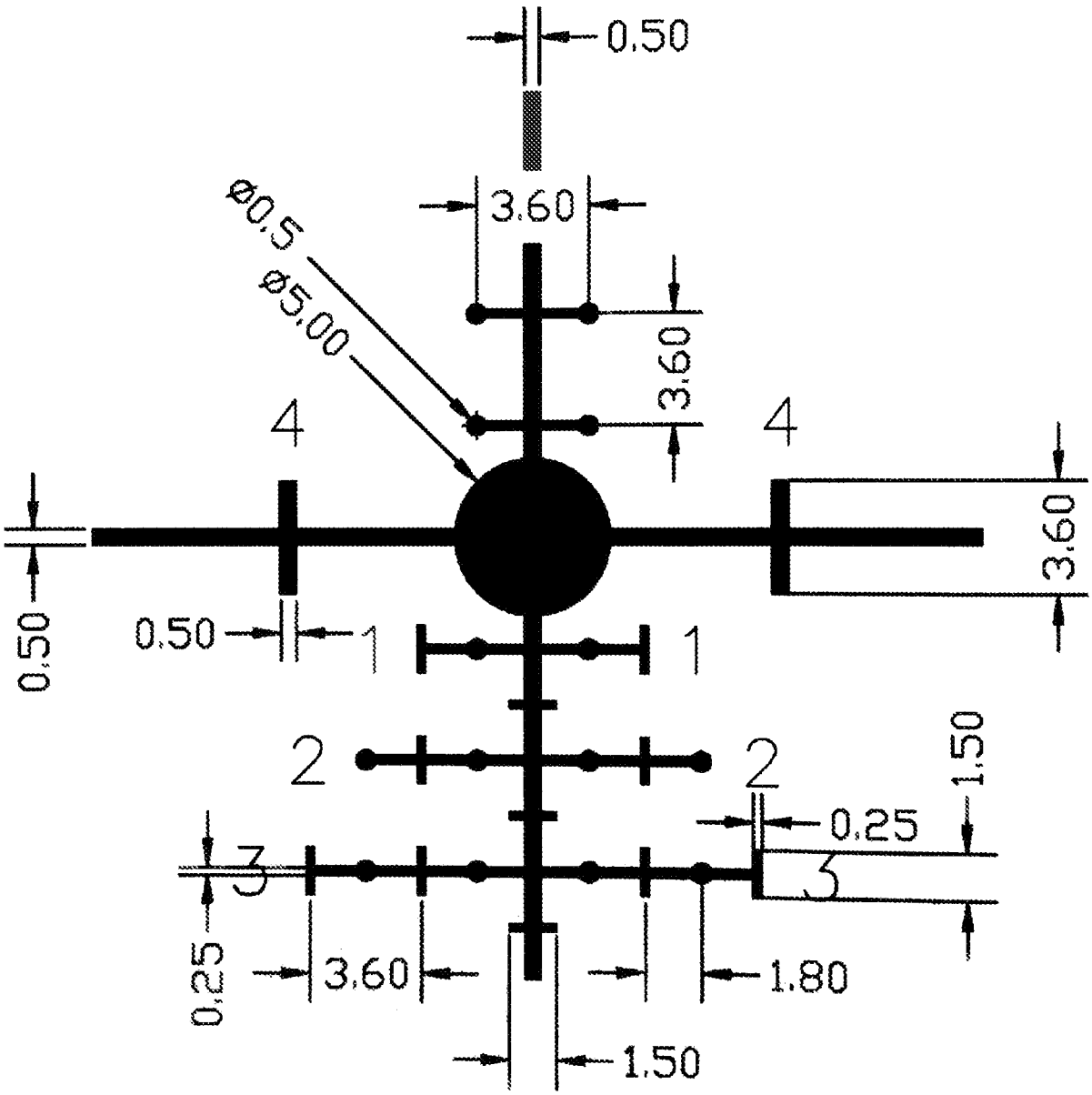

0.50
3.60
Ø0.5
Ø5.00
3.60
4
4
3.60
0.50
0.50
1
1
2
2
1.50
0.25
3
3
0.25
3.60
1.80
1.50

FIG. 44d

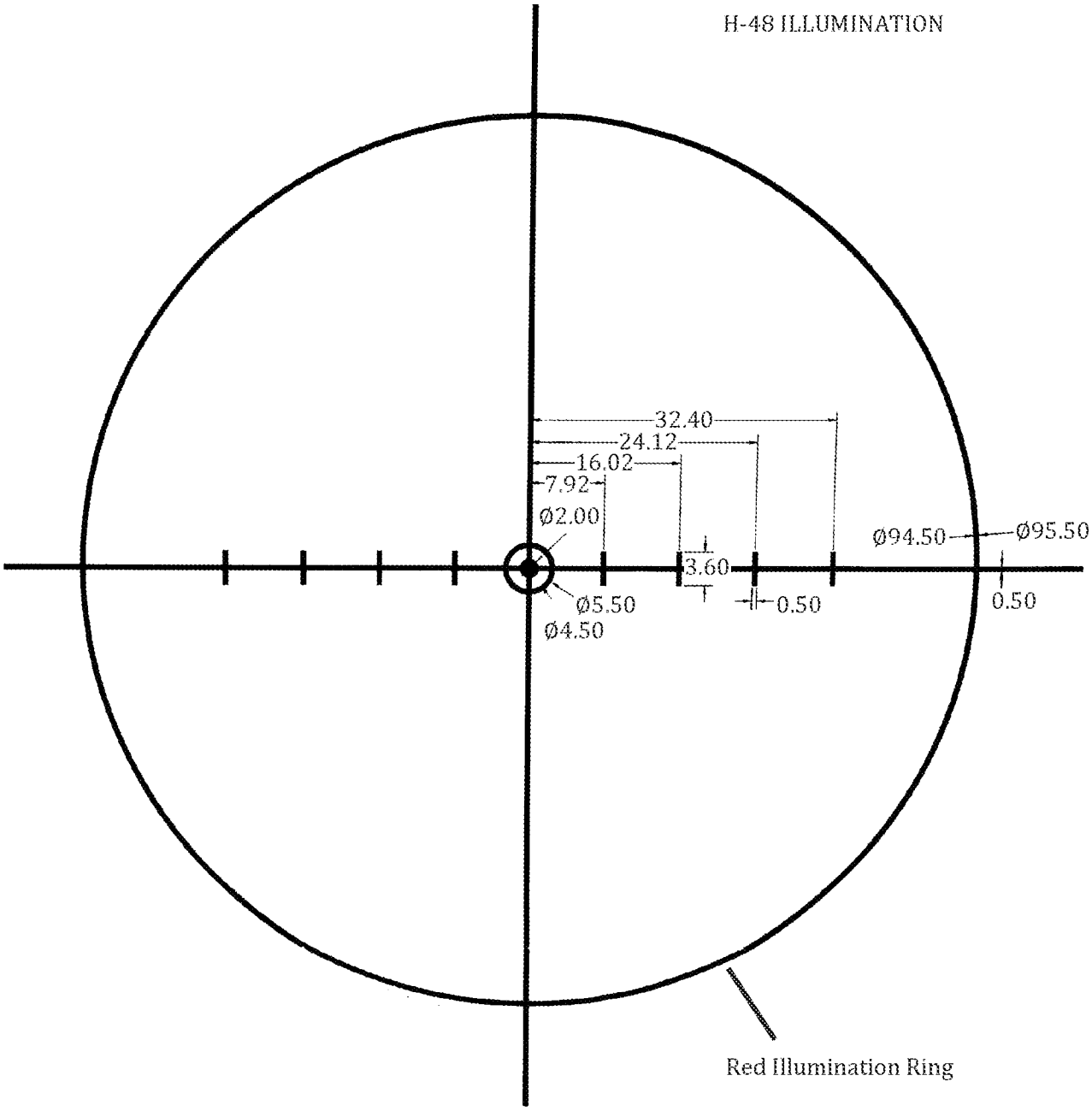
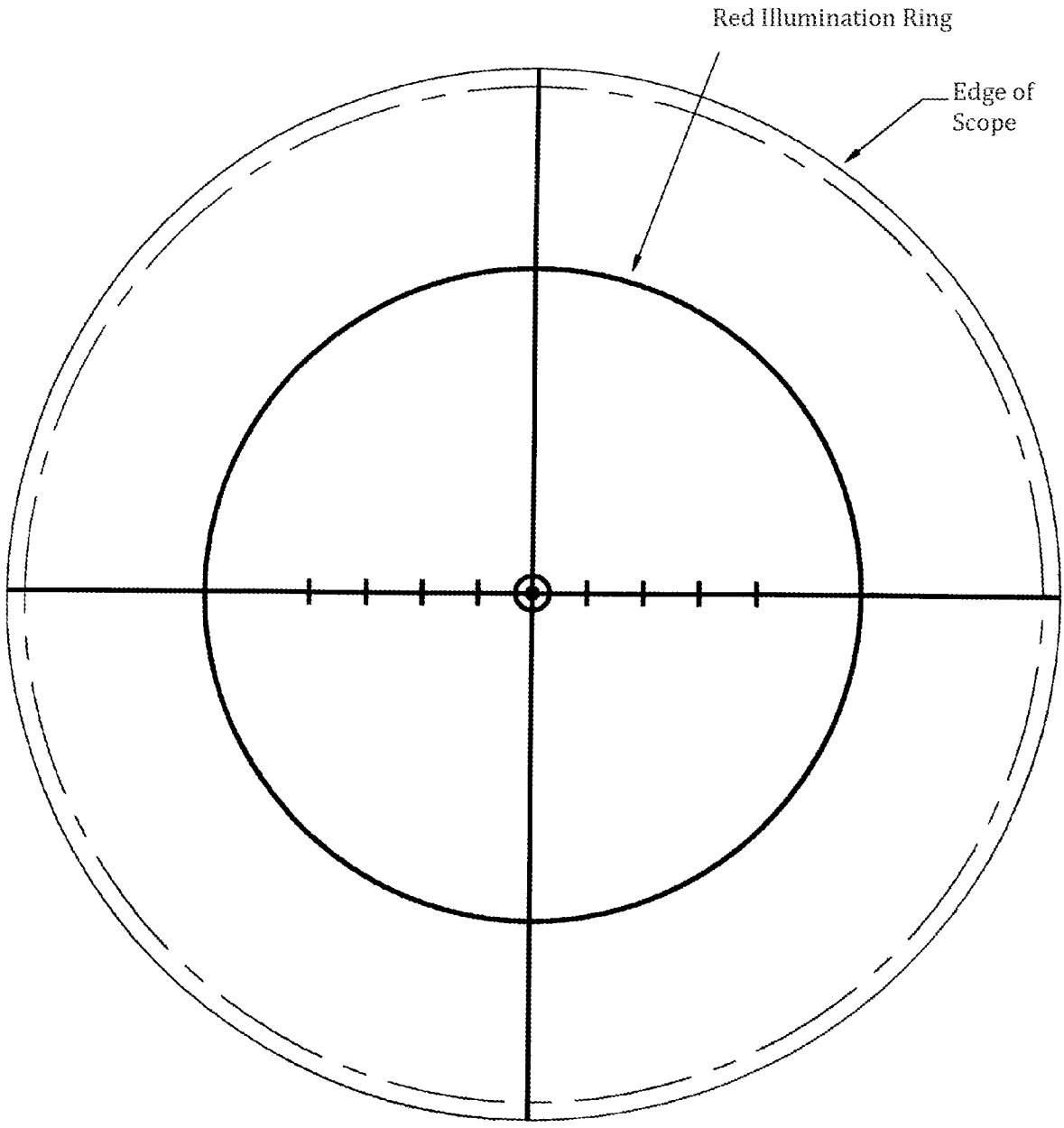

H-48 ILLUMINATION
32.40
24.12
16.02
7.92
Ø2.00
Ø5.50
Ø4.50
3.60
0.50
Ø94.50
Ø95.50
0.50
Red Illumination Ring

FIG. 44e



ILLUMINATION OVERVIEW
SHOWN NOT TO SCALE

FIG. 45a

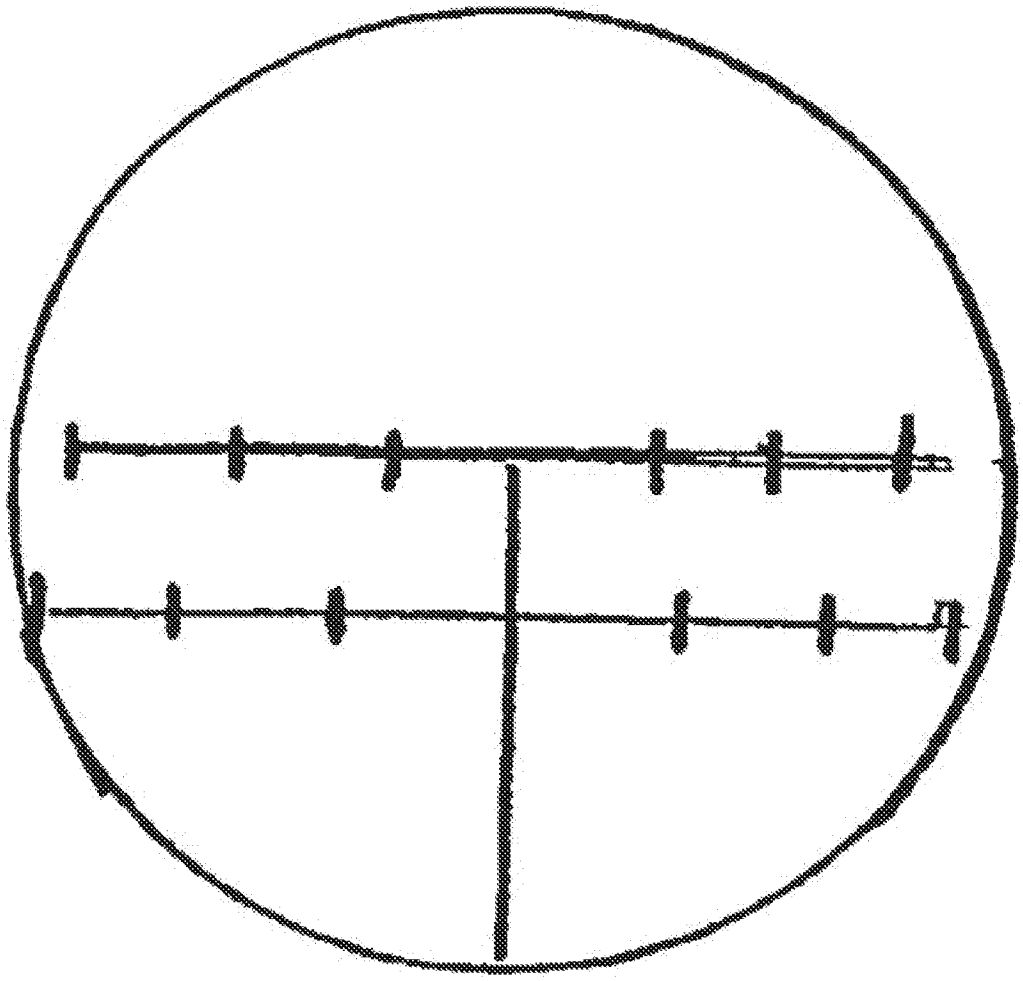


FIG. 45b

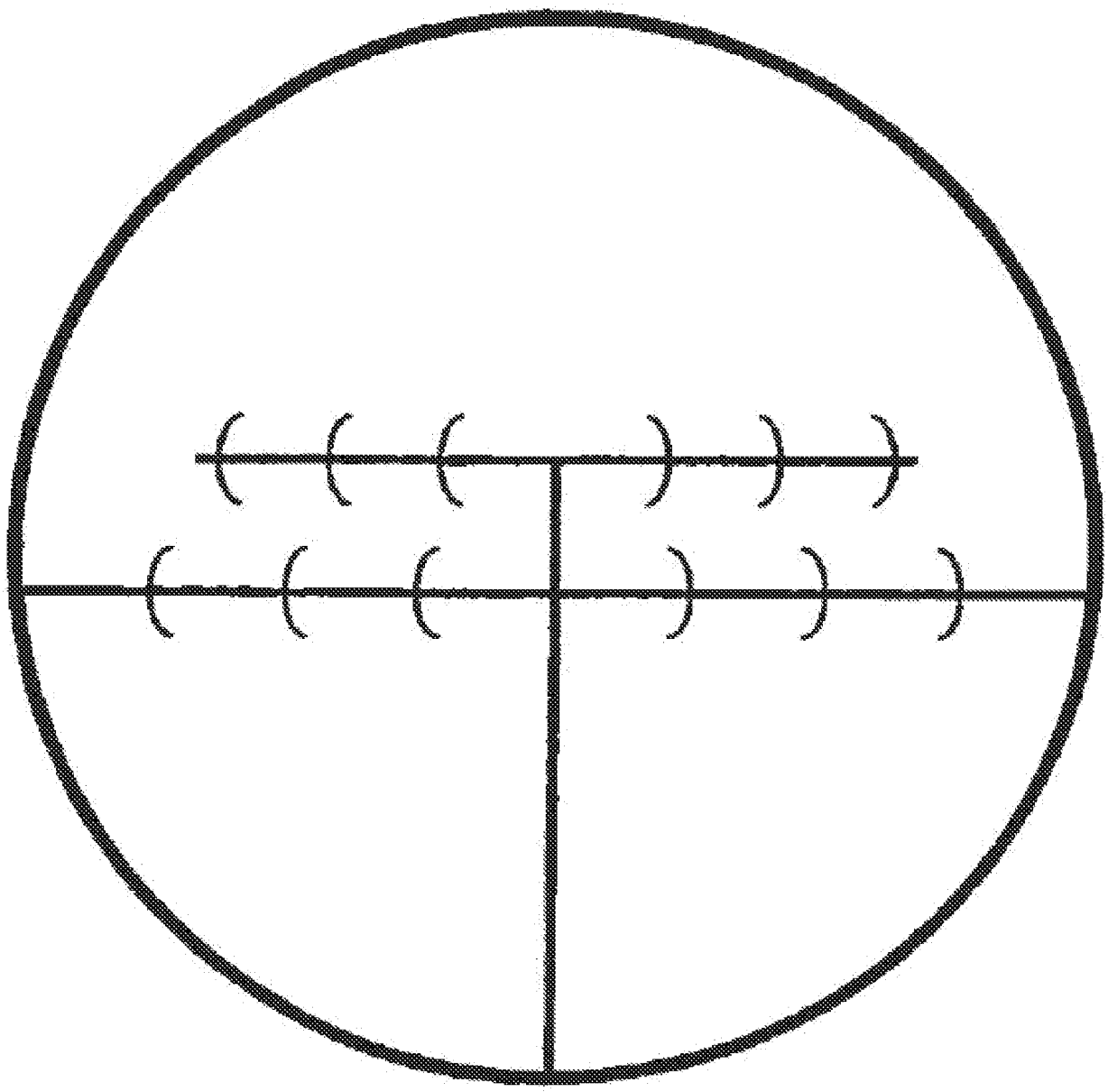


FIG. 45c

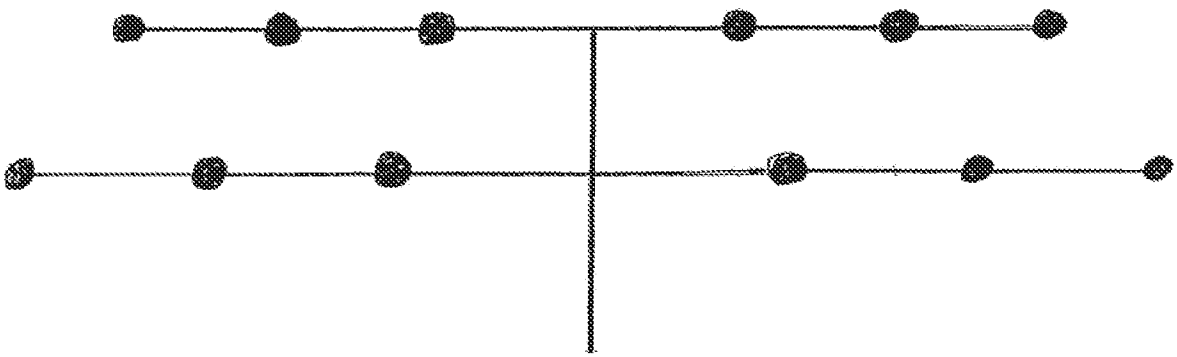


FIG. 45d

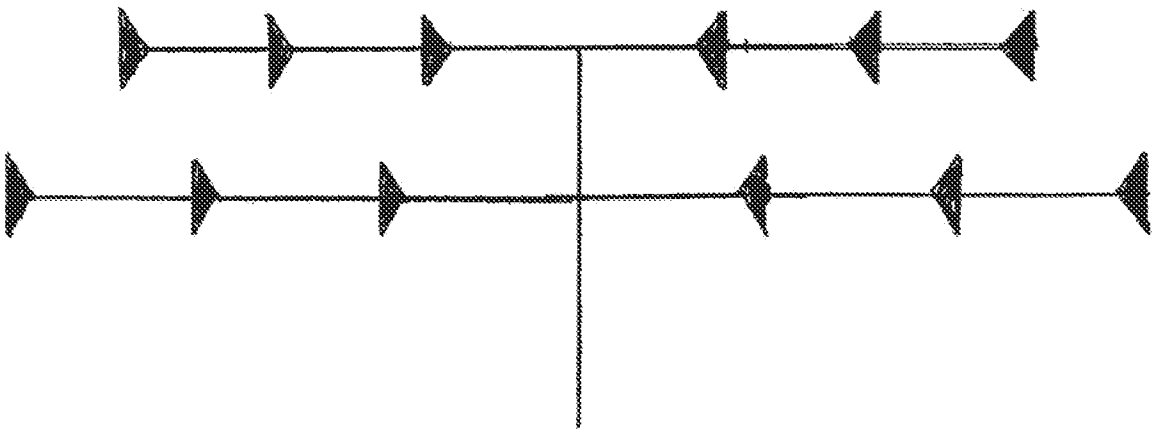
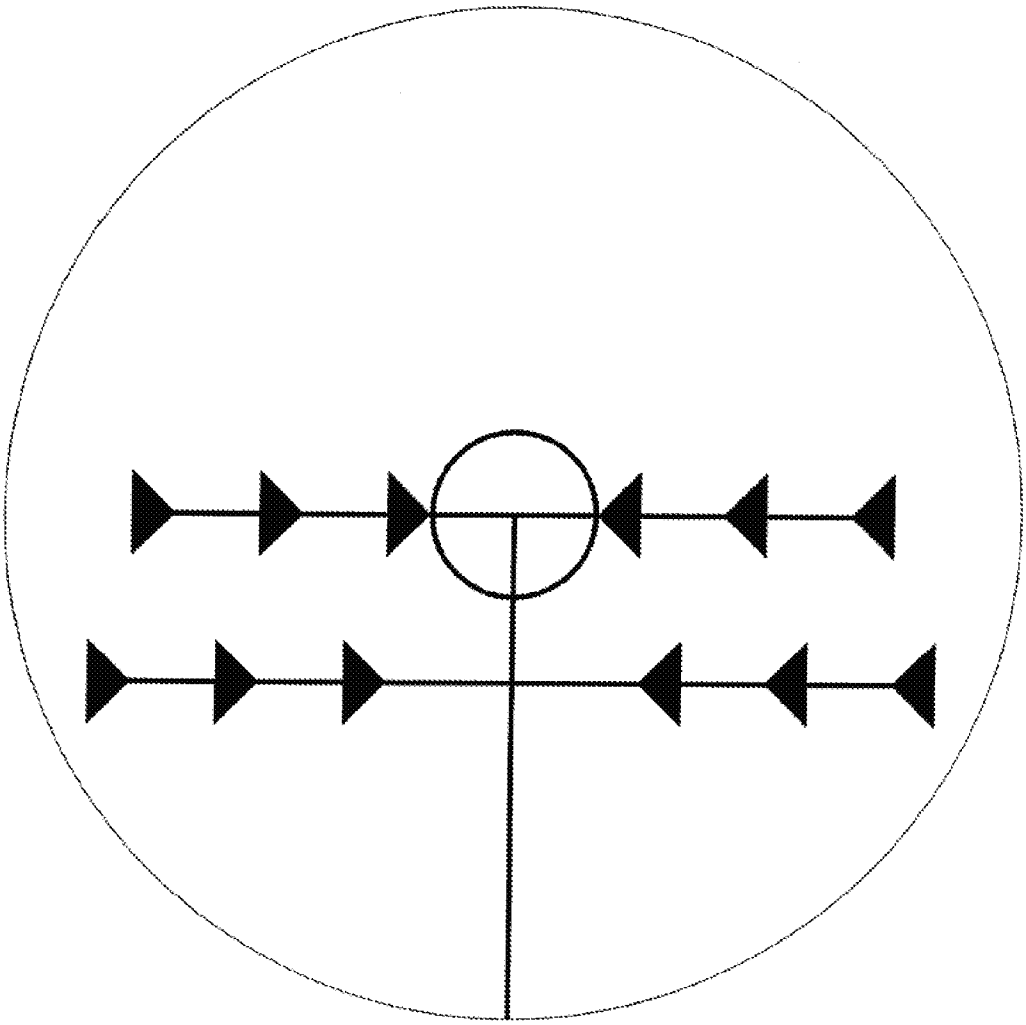
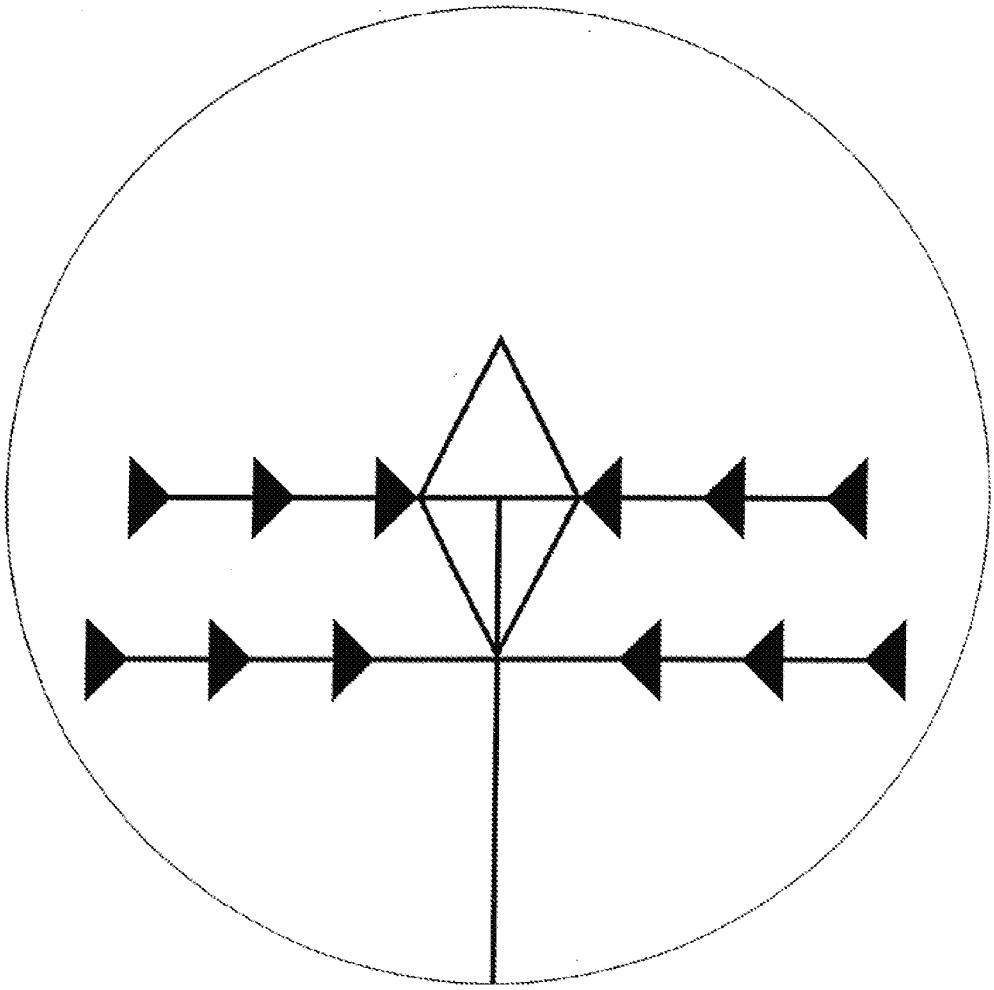


FIG. 45e



H-45e

FIG. 45f



H-45f

FIG. 46a

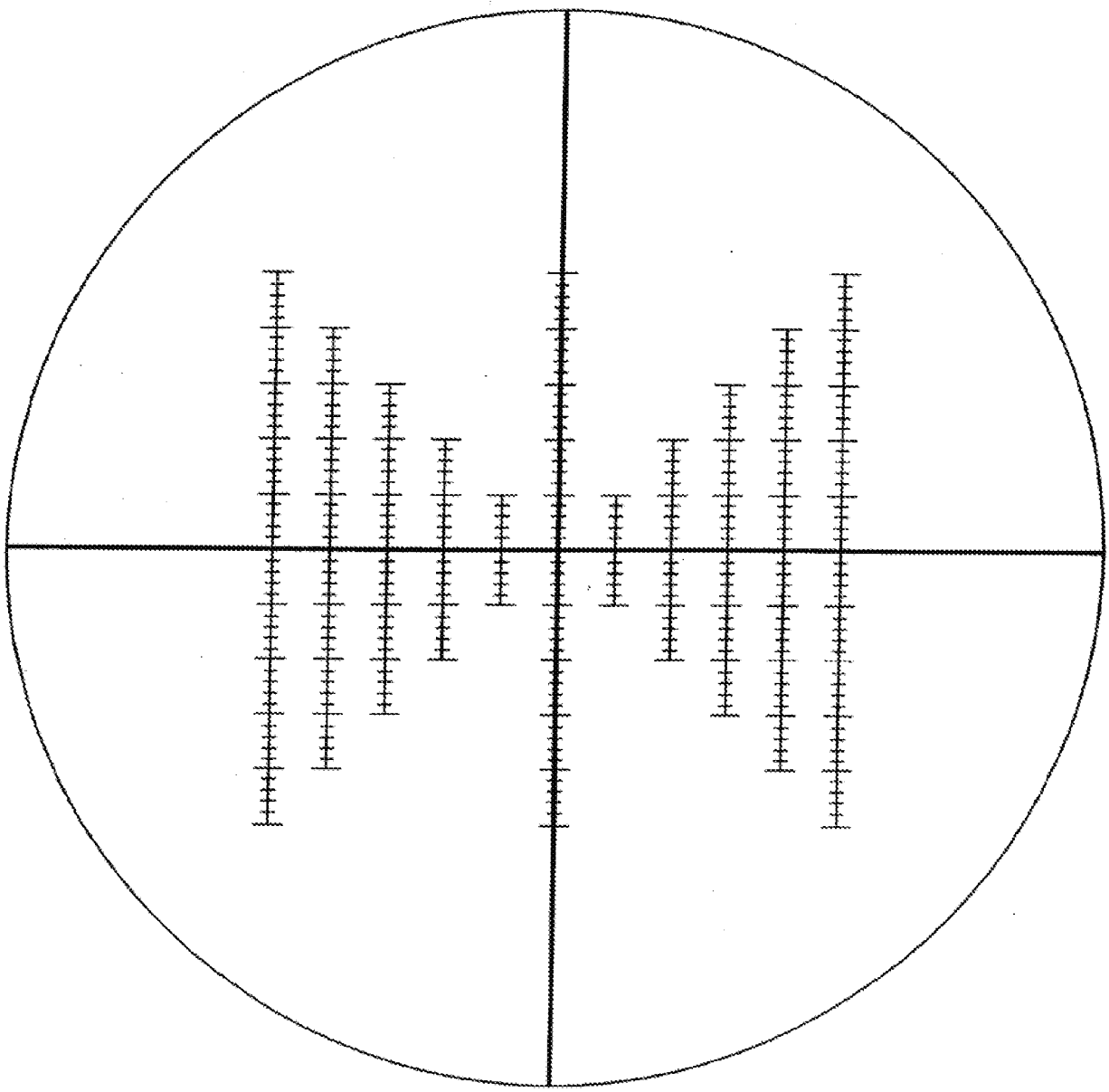


FIG. 46b

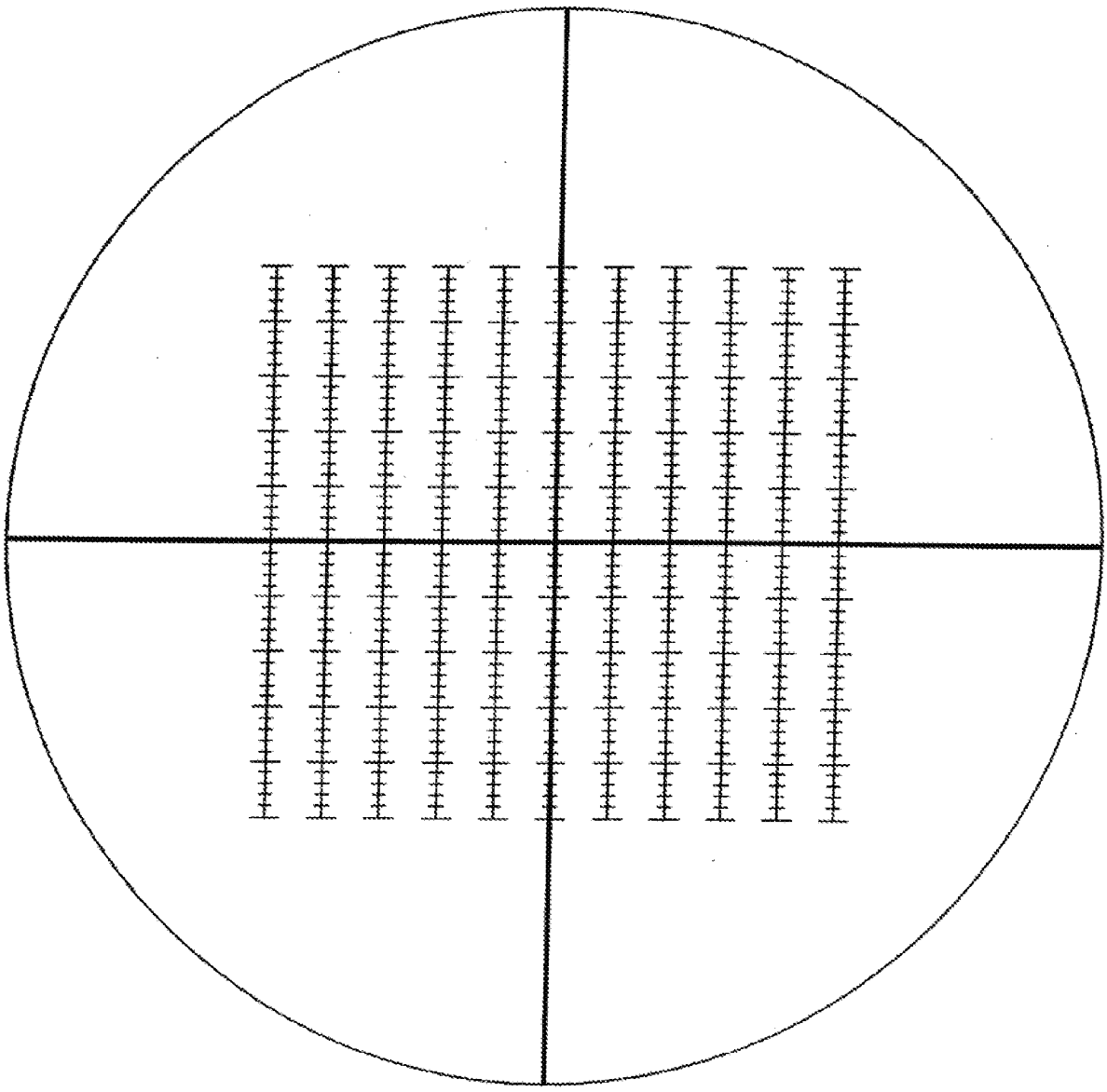


FIG. 47

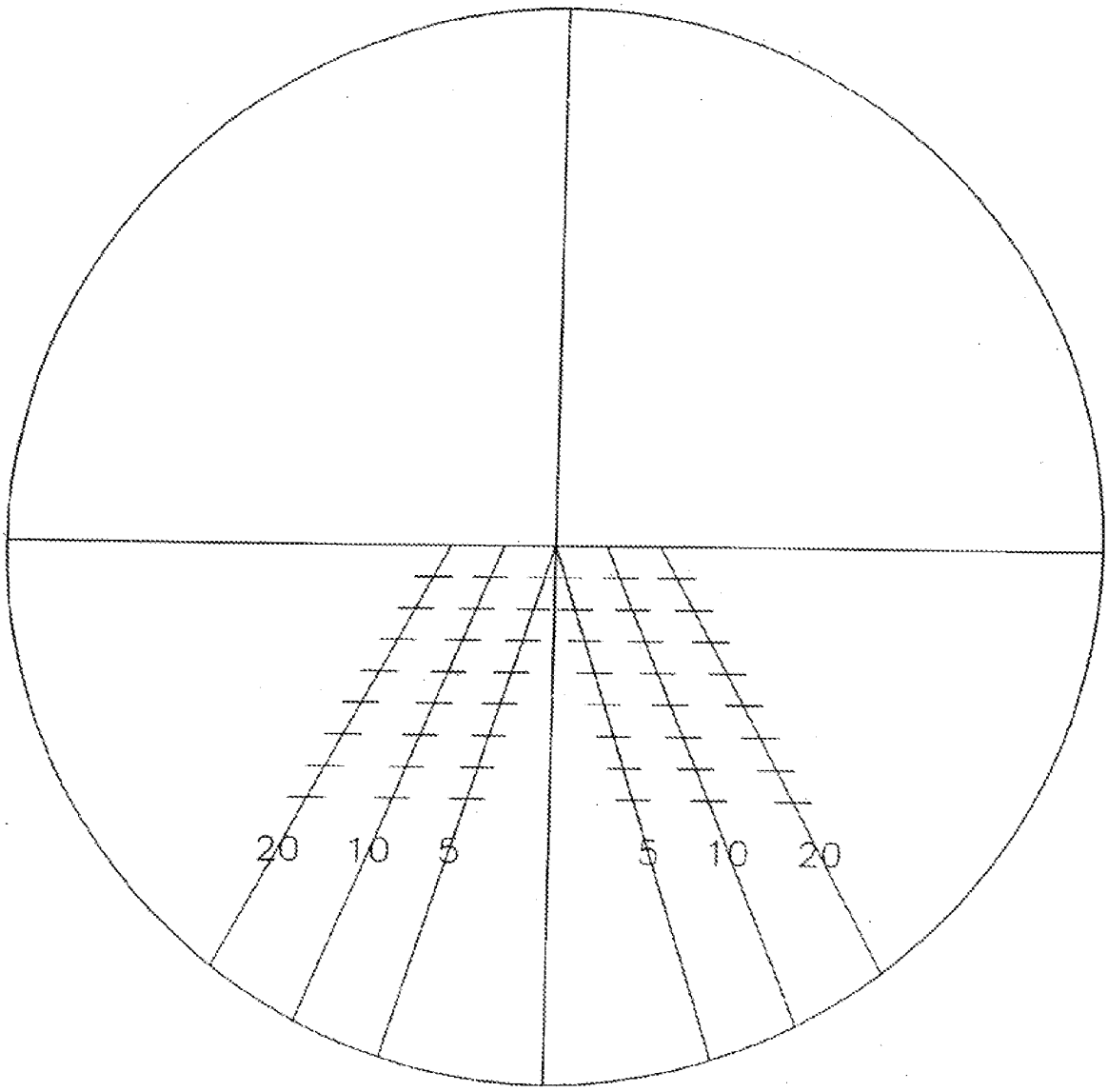


FIG. 48a

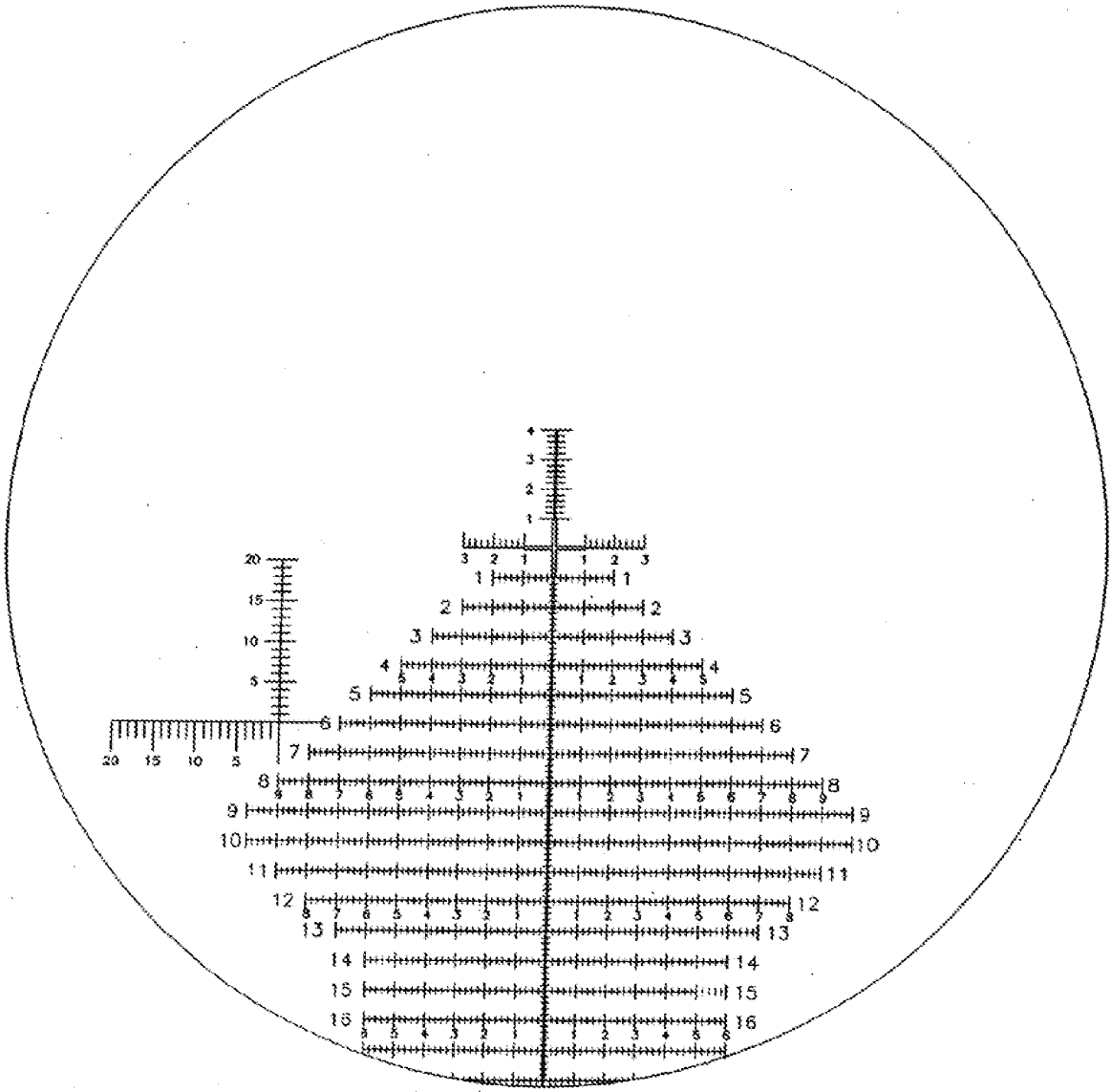


FIG. 48b

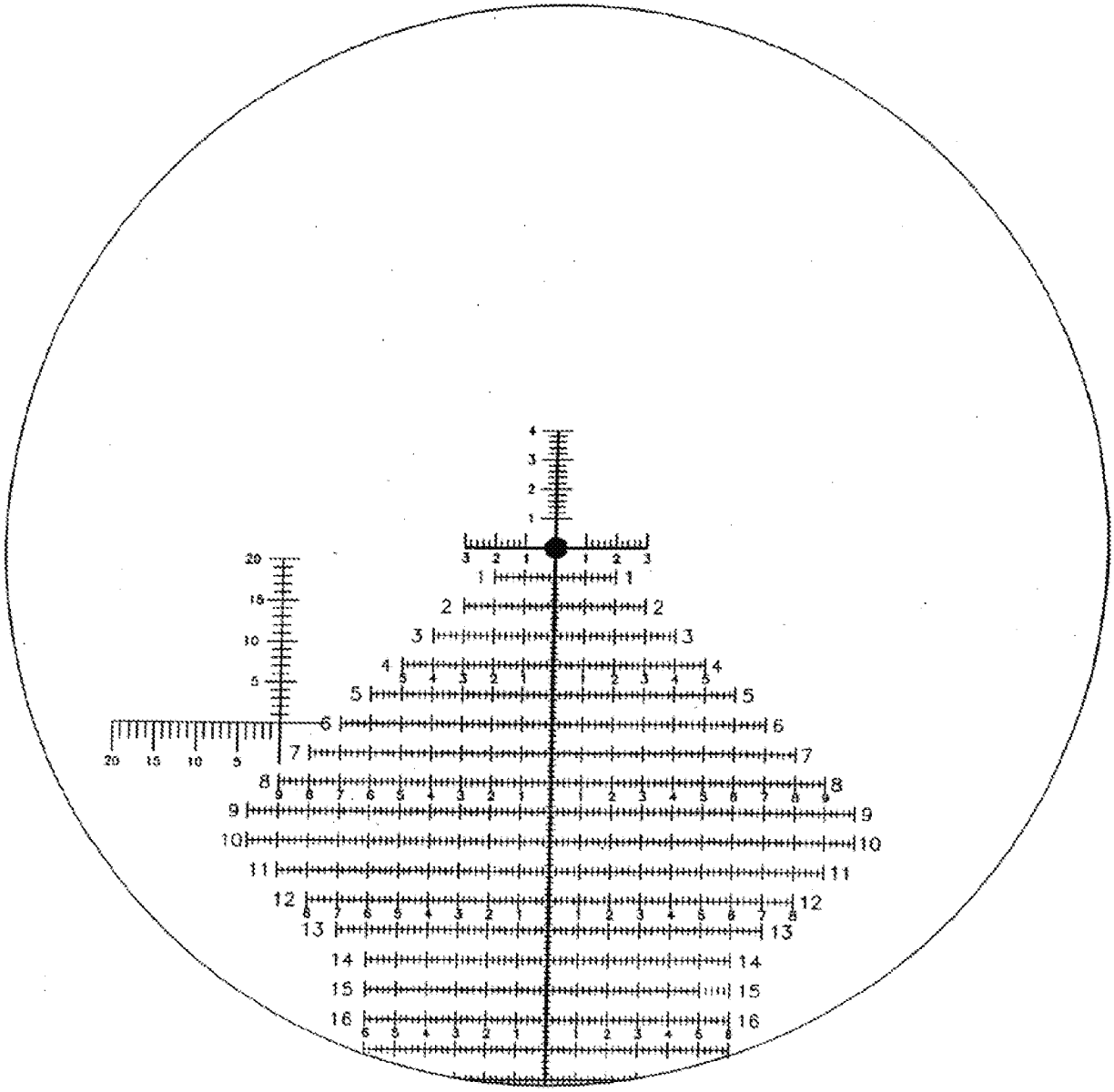


FIG. 49

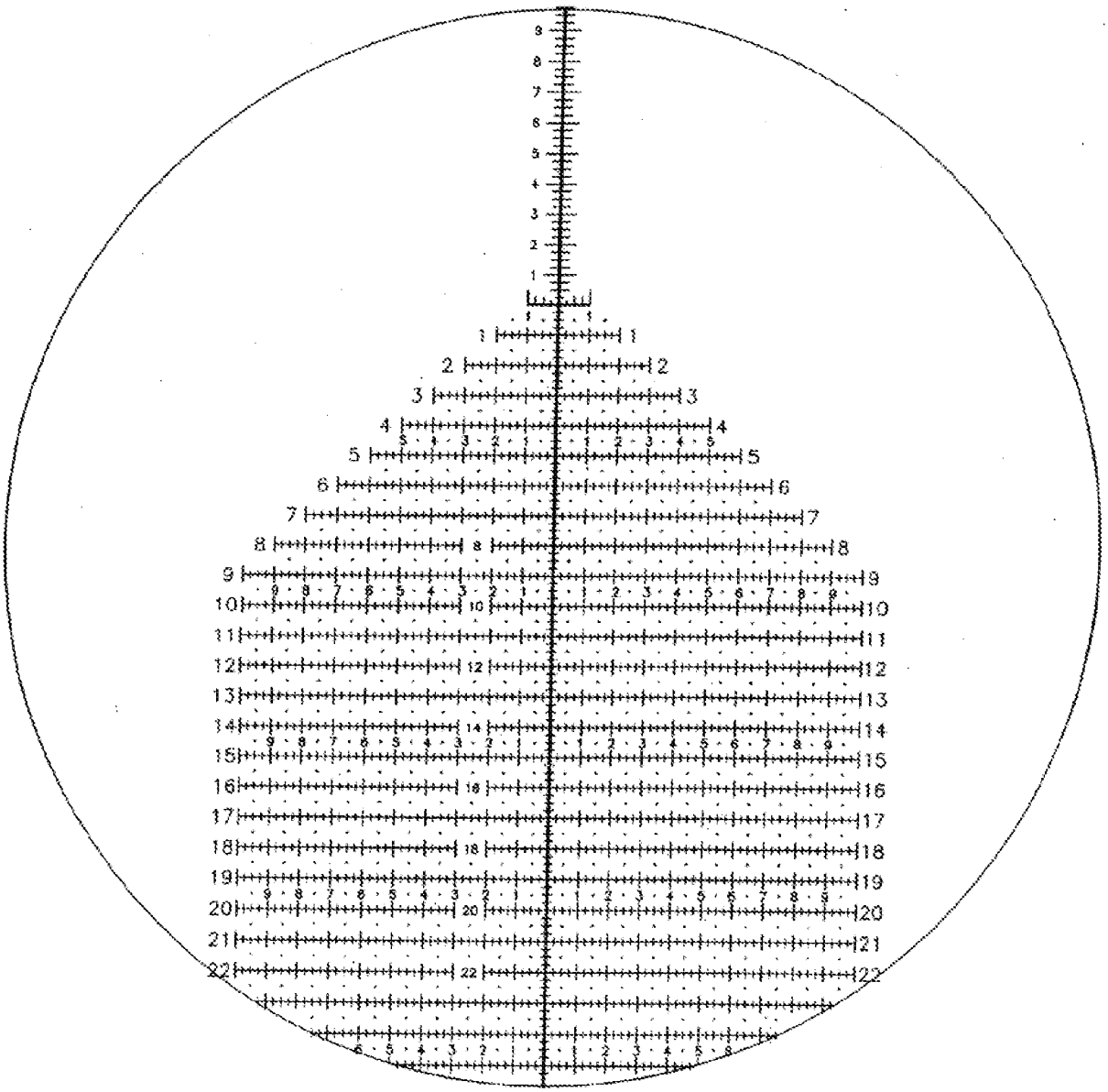


FIG. 50a

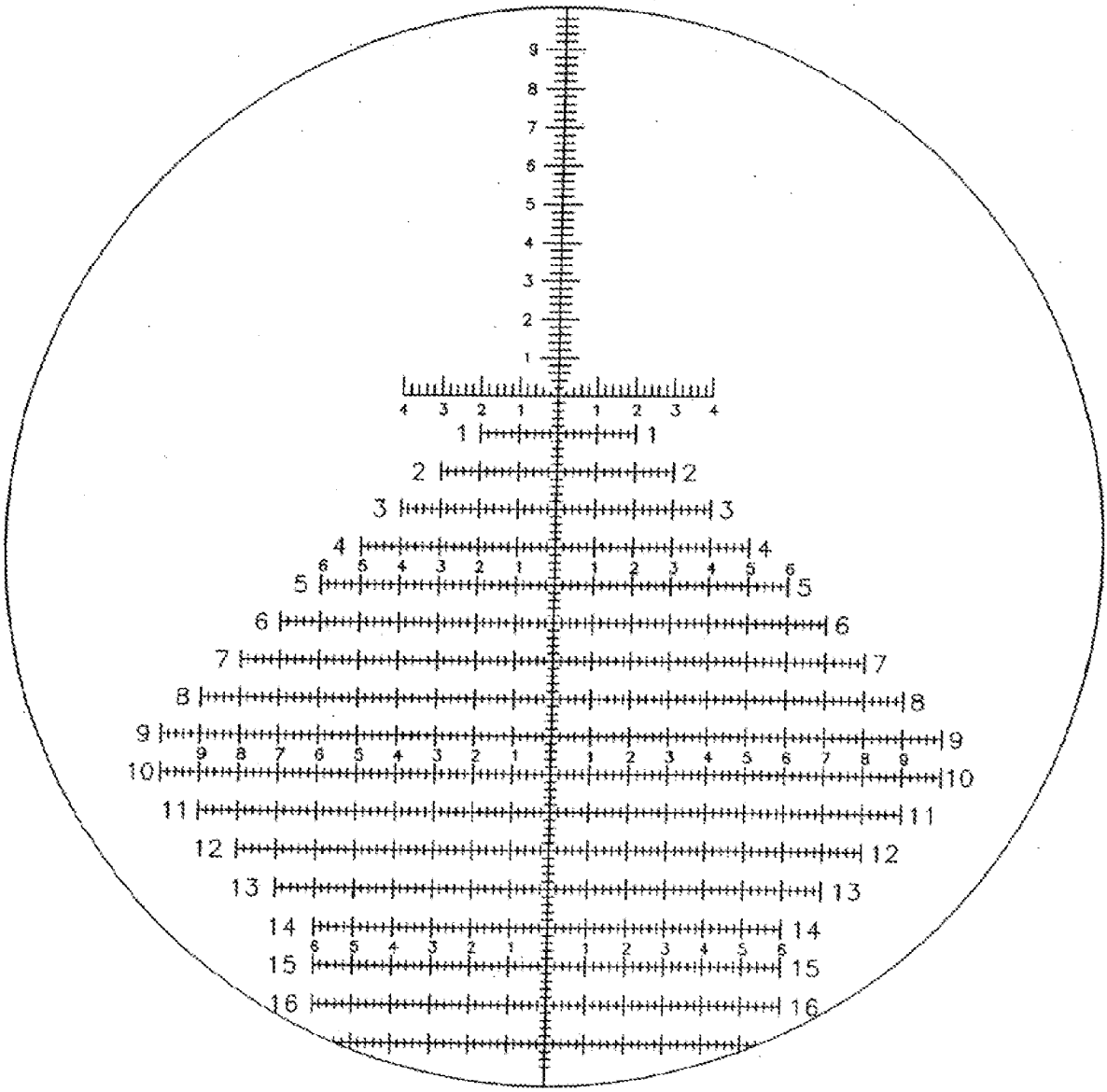


FIG. 50b

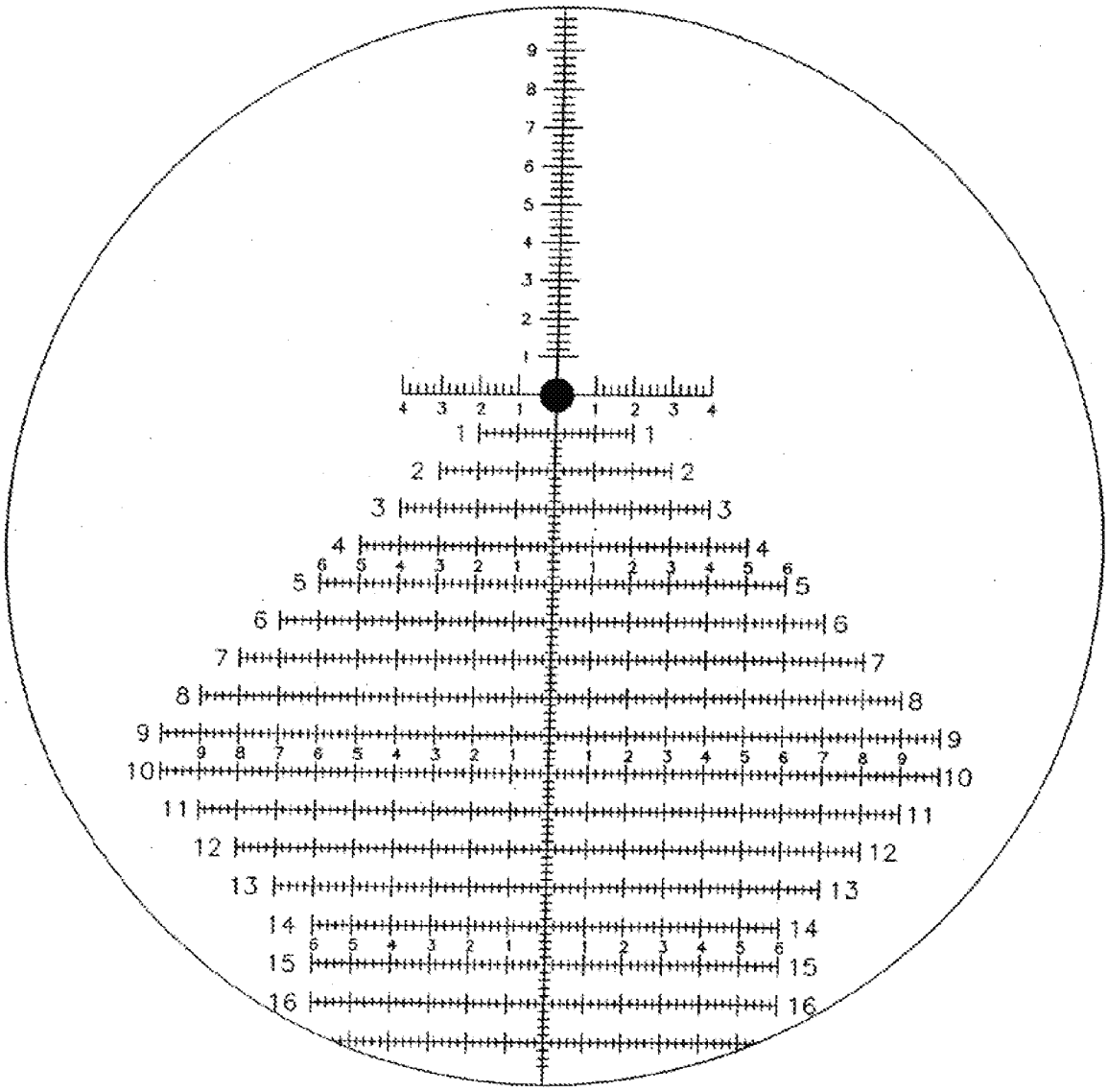


FIG. 51a

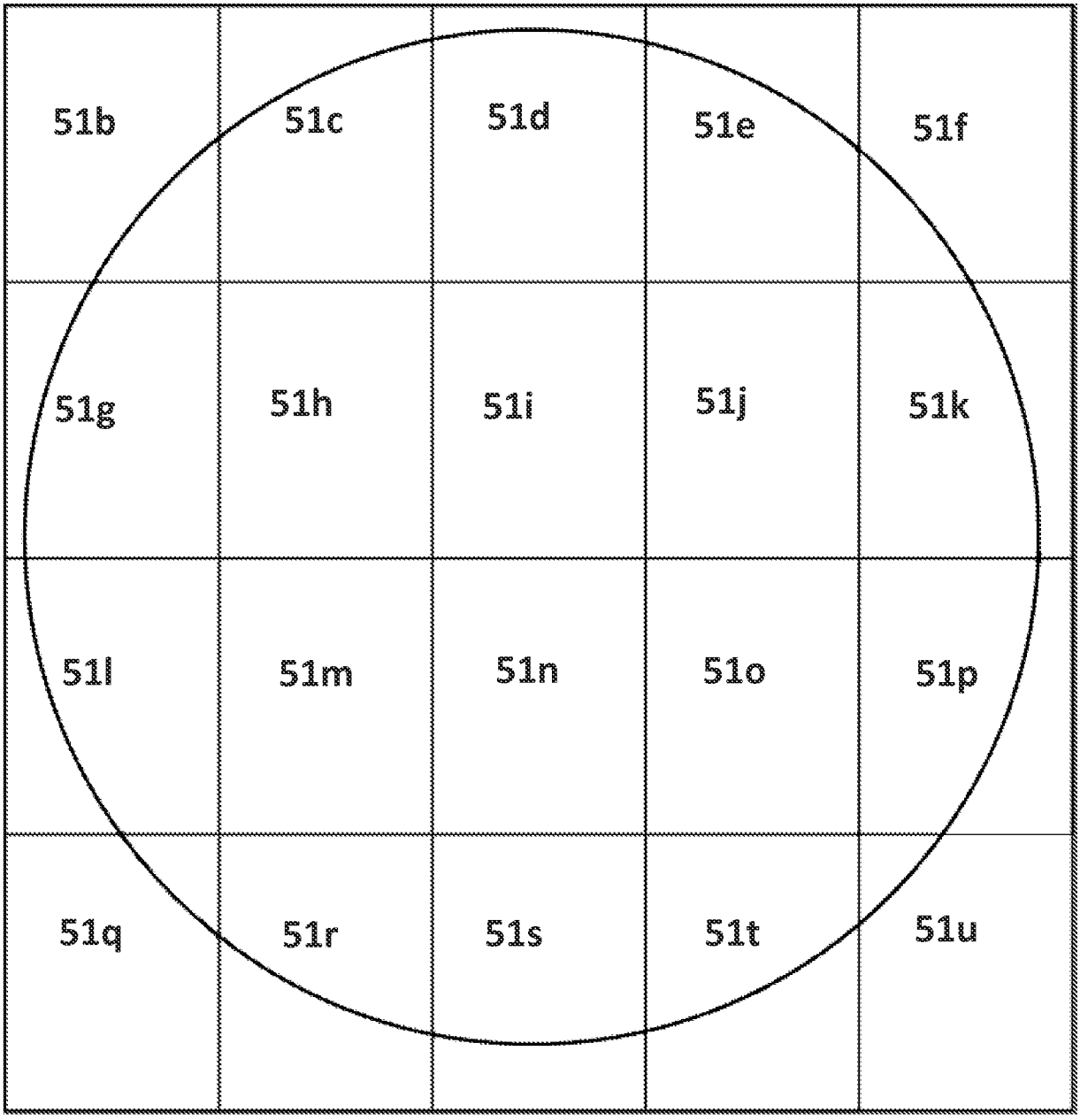

51b
51c
51d
51e
51f
51g
51h
51i
51j
51k
51l
51m
51n
51o
51p
51q
51r
51s
51t
51u

FIG. 51b

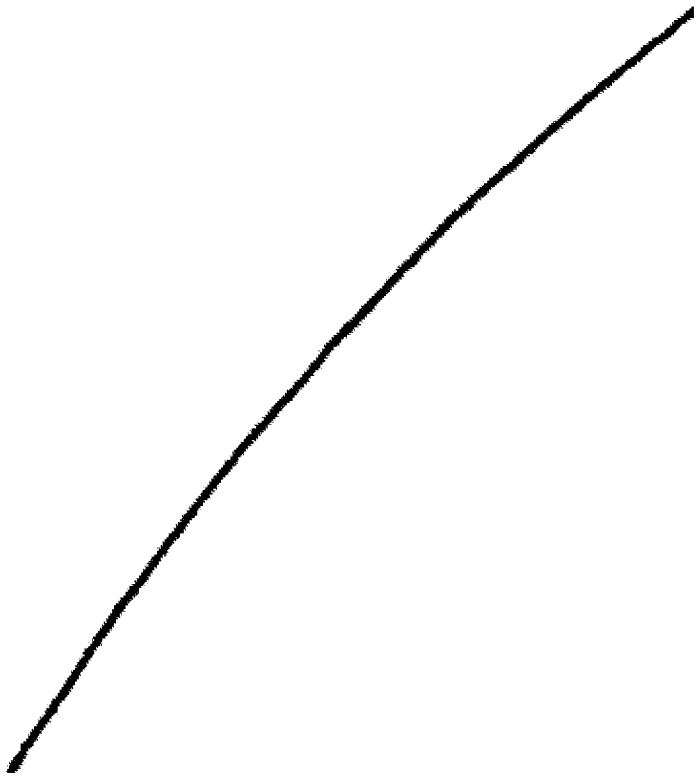


FIG. 51c

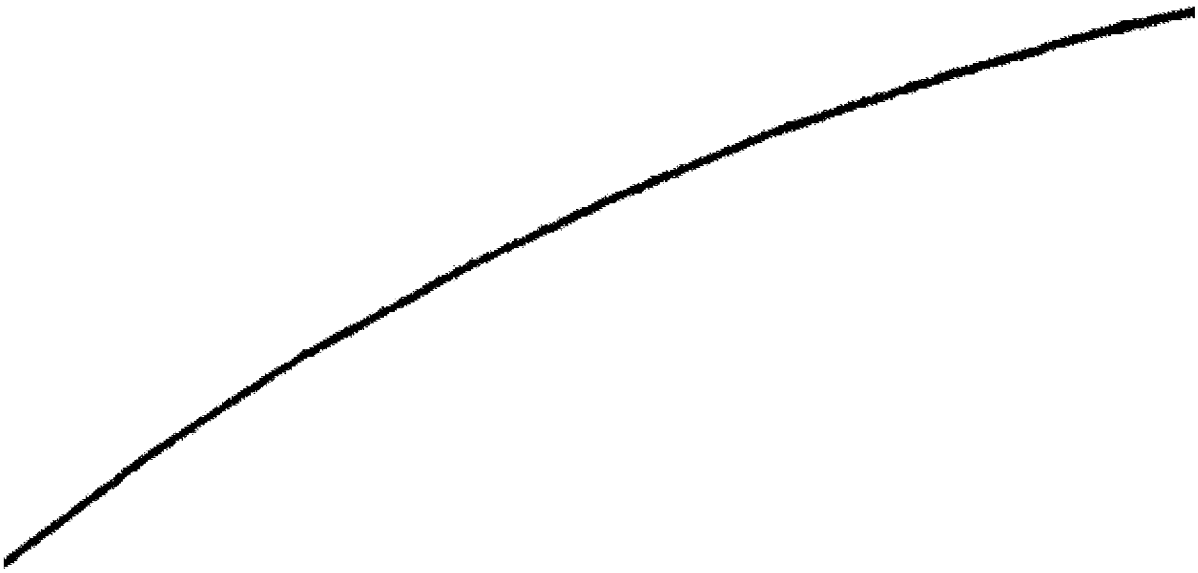


FIG. 51d

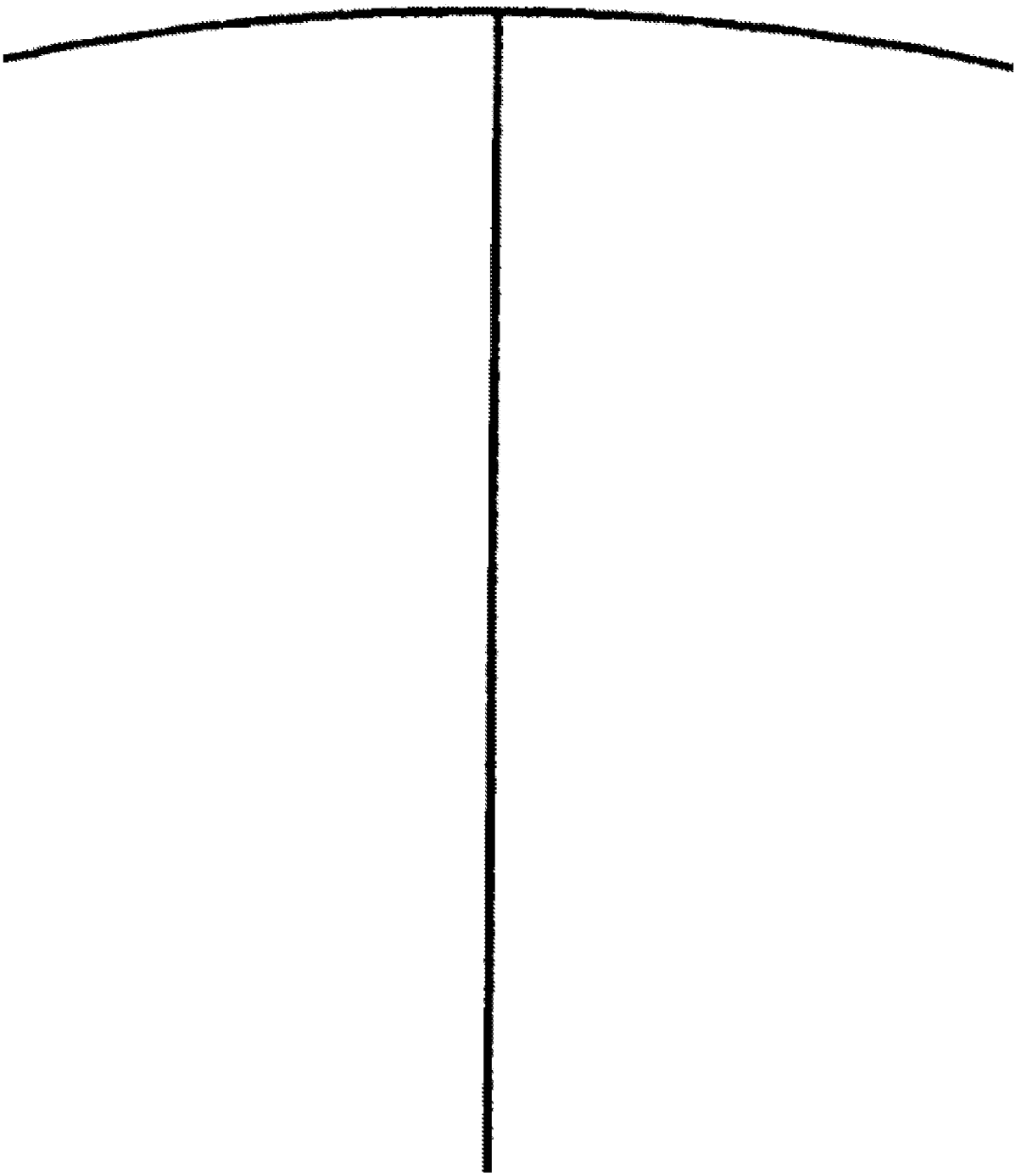


FIG. 51e

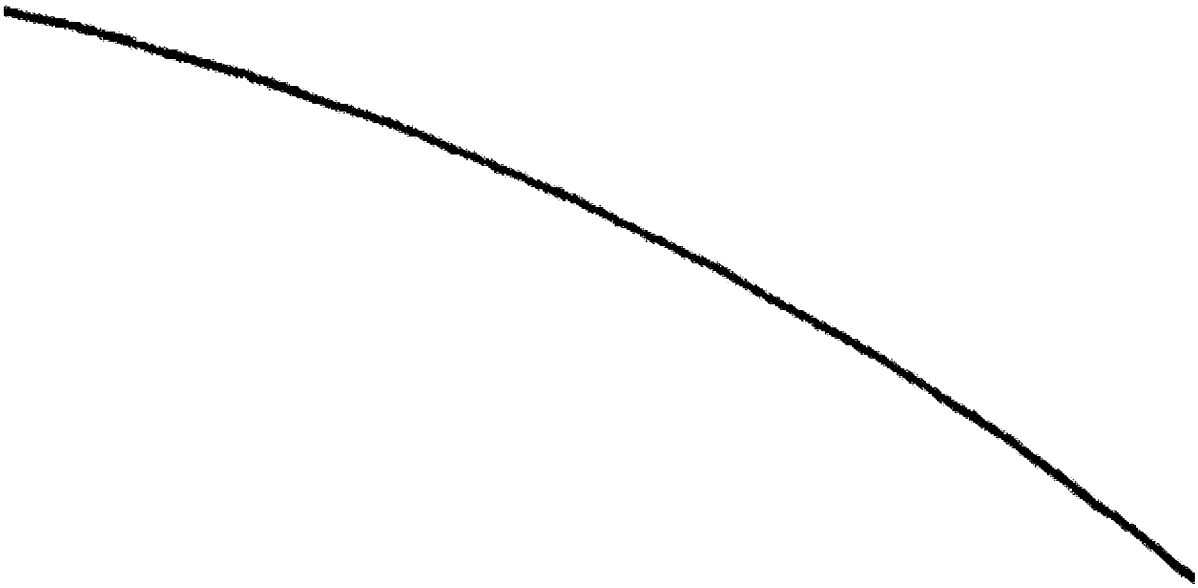


FIG. 51f

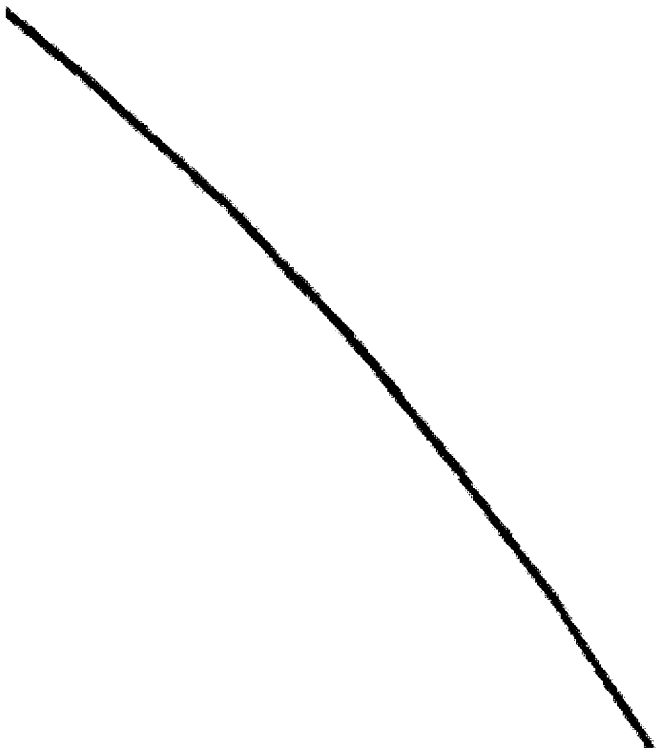


FIG. 51g

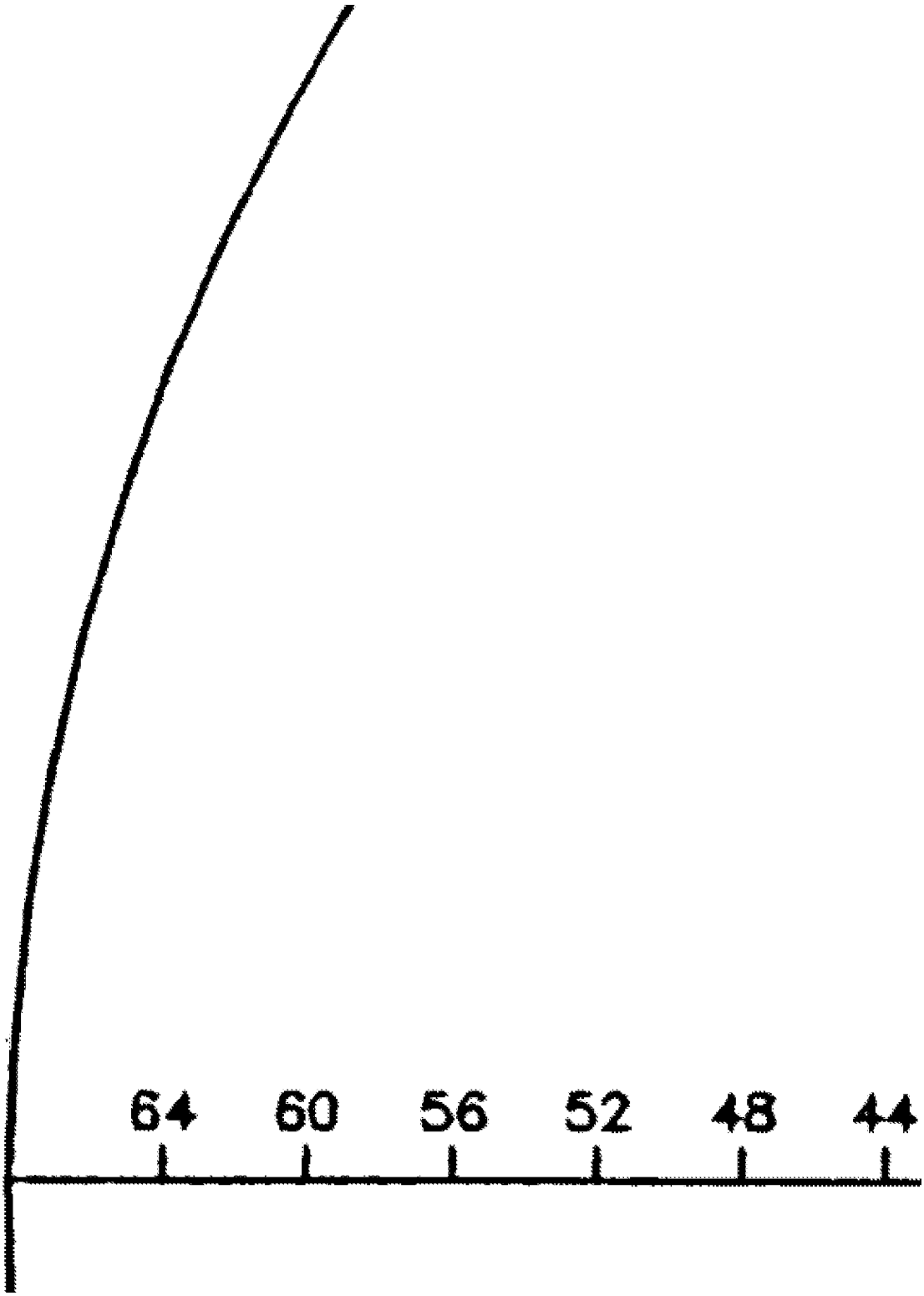


FIG. 51h



FIG. 51i

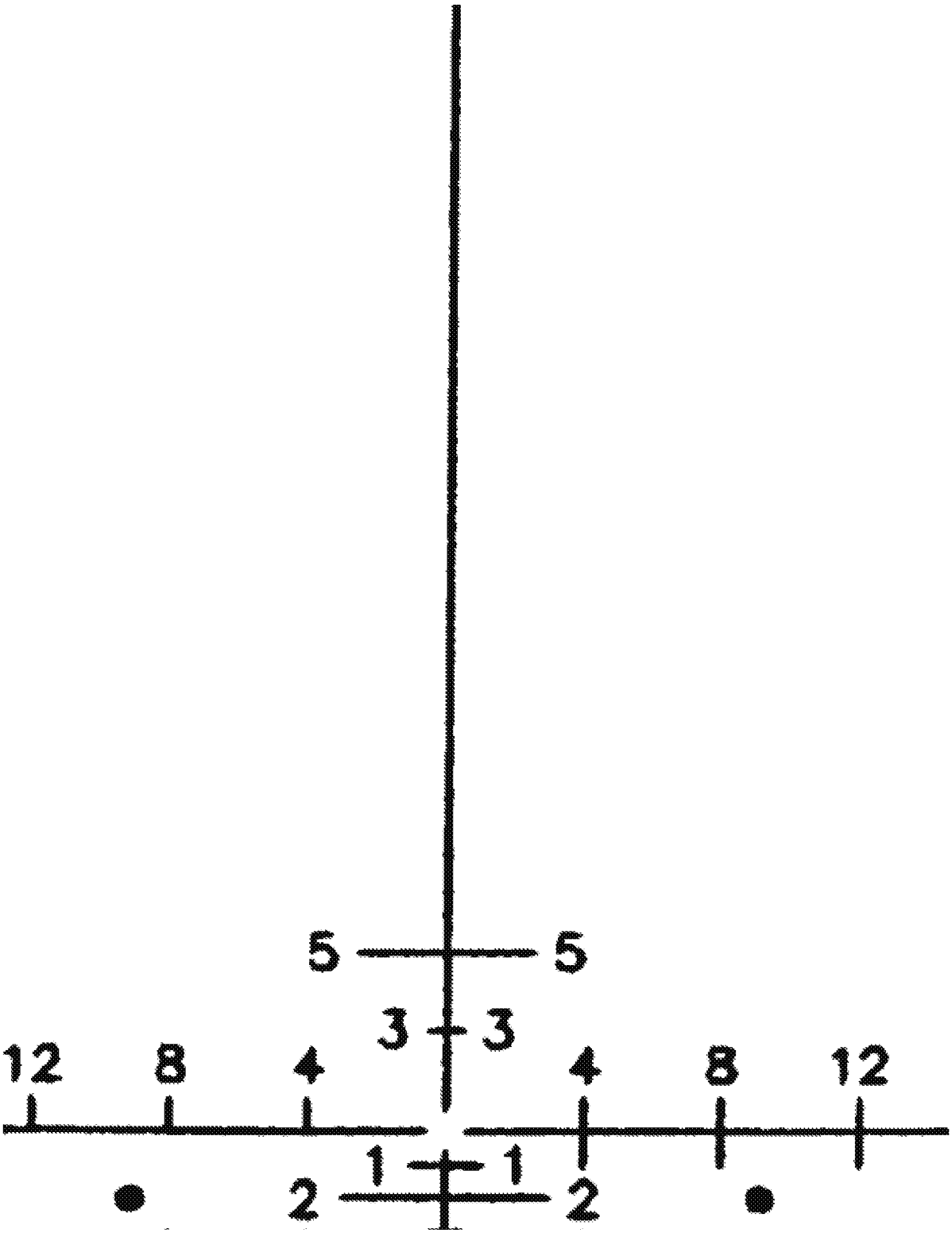


FIG. 51j

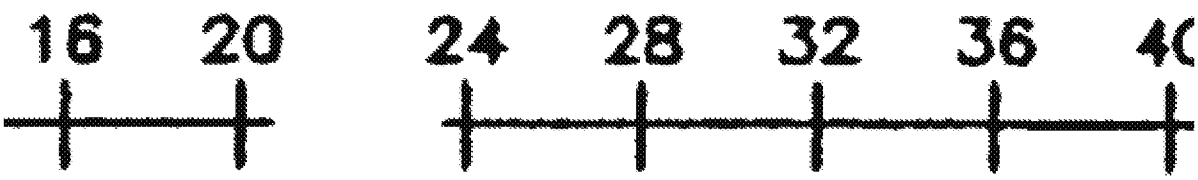


FIG. 51k

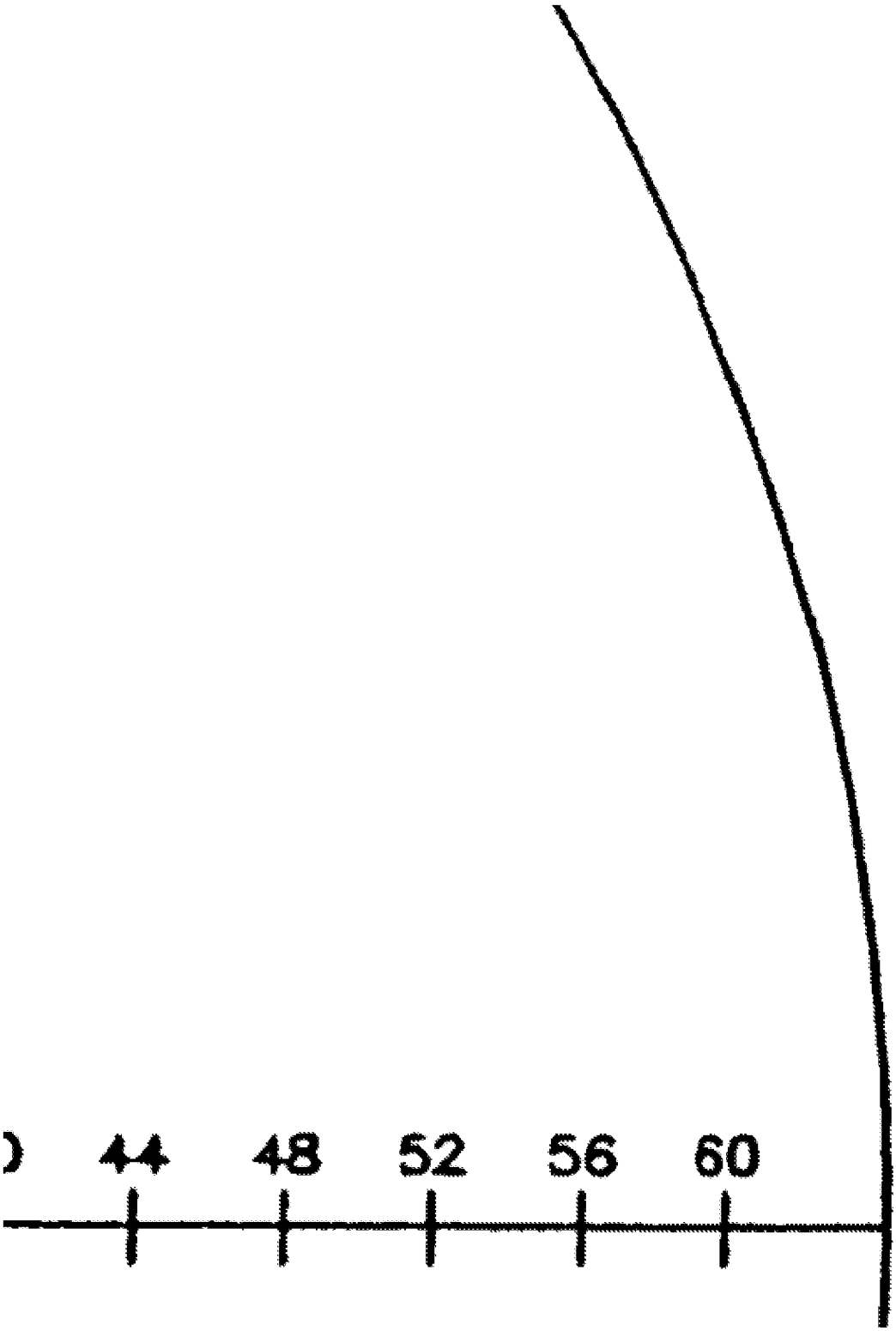


FIG. 51l

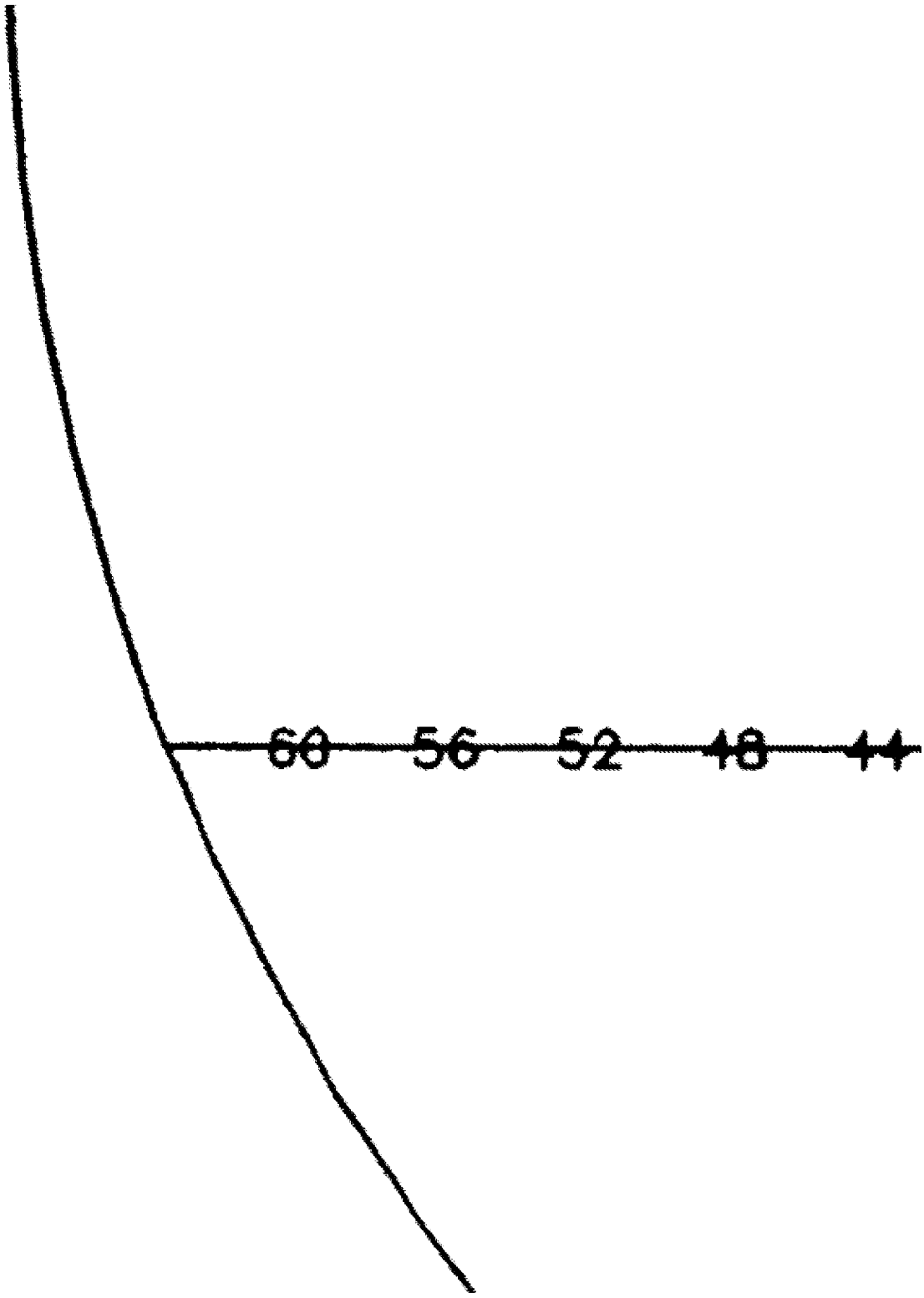


FIG. 51m

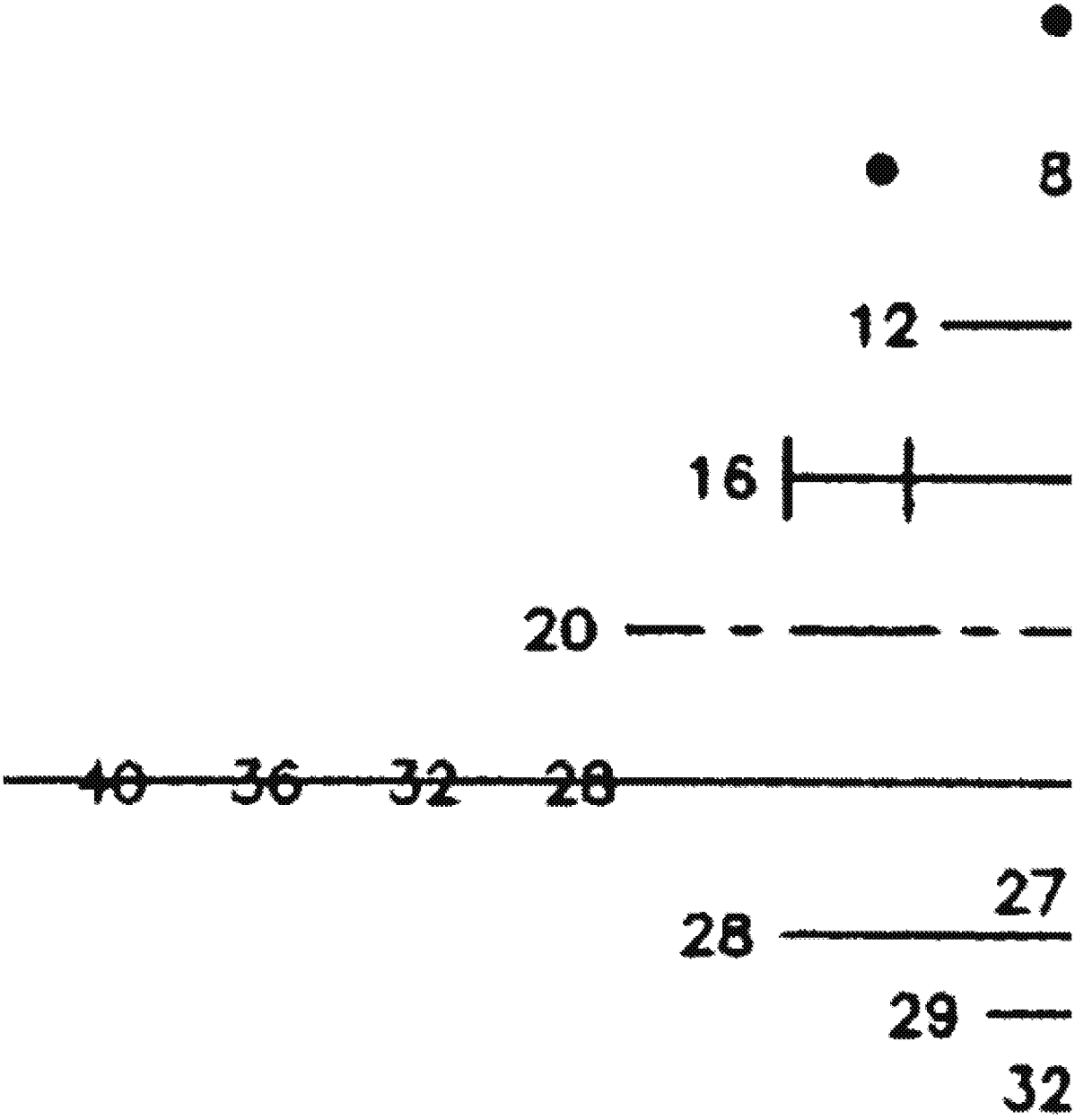


FIG. 51n

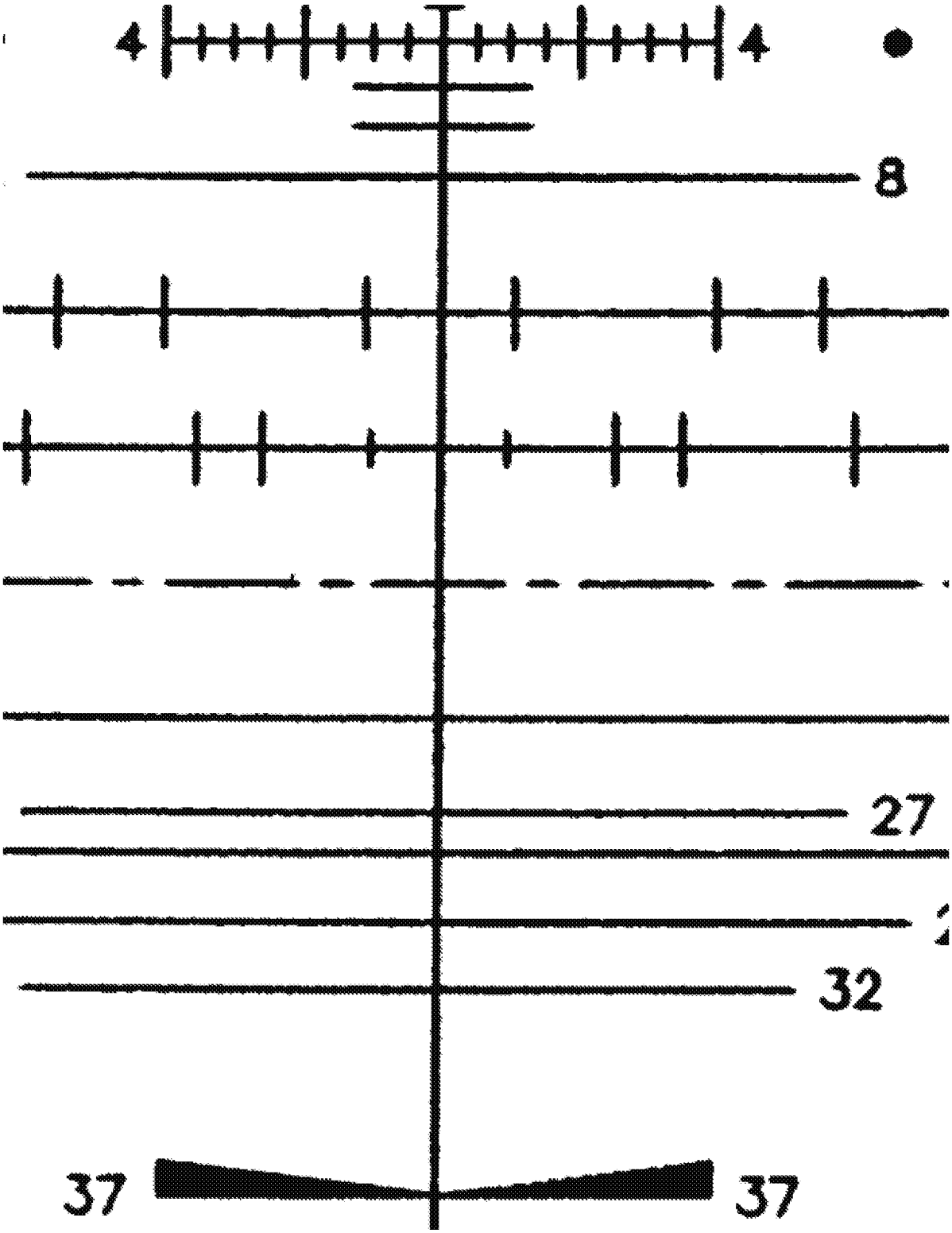


FIG. 51o

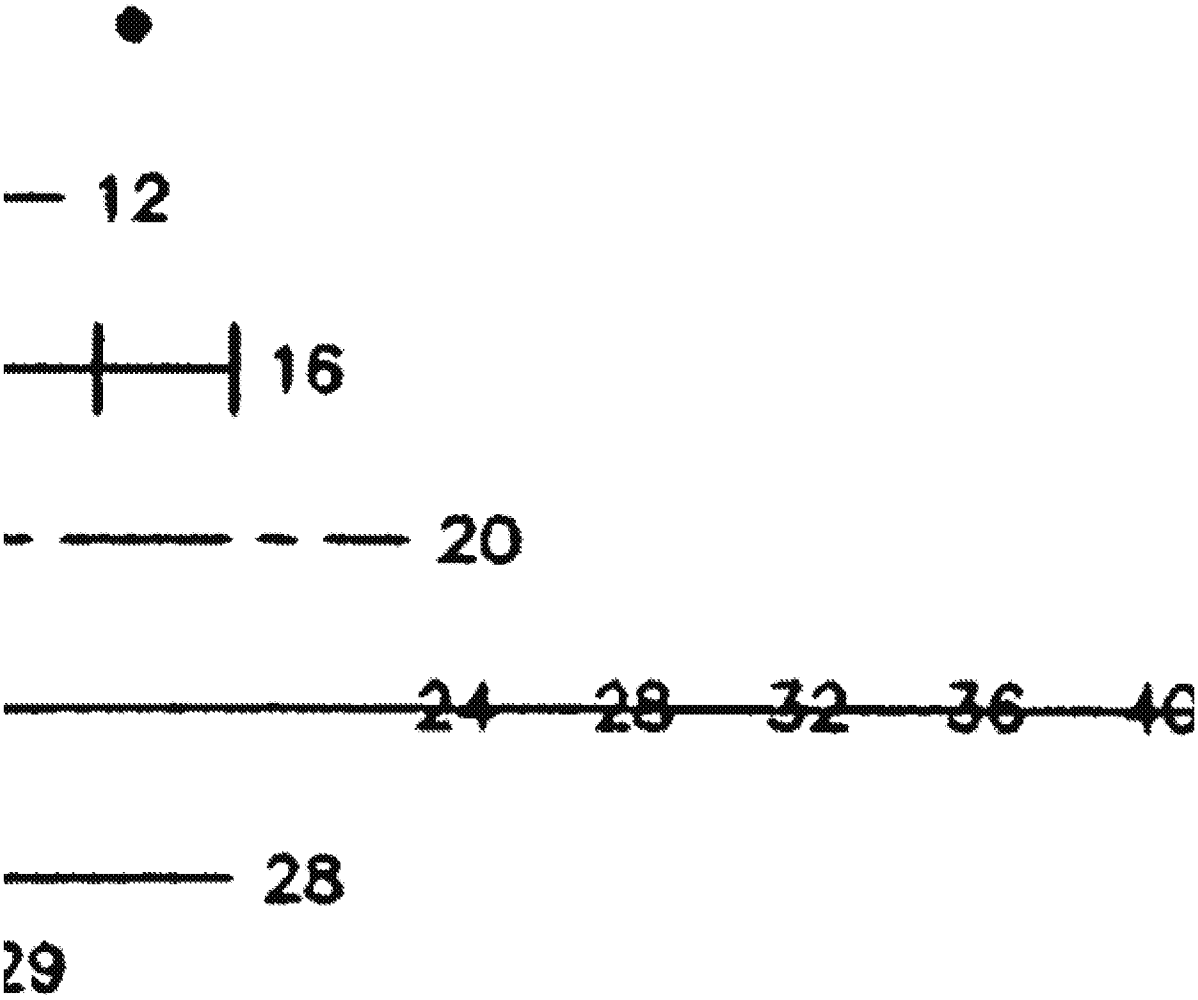


FIG. 51p

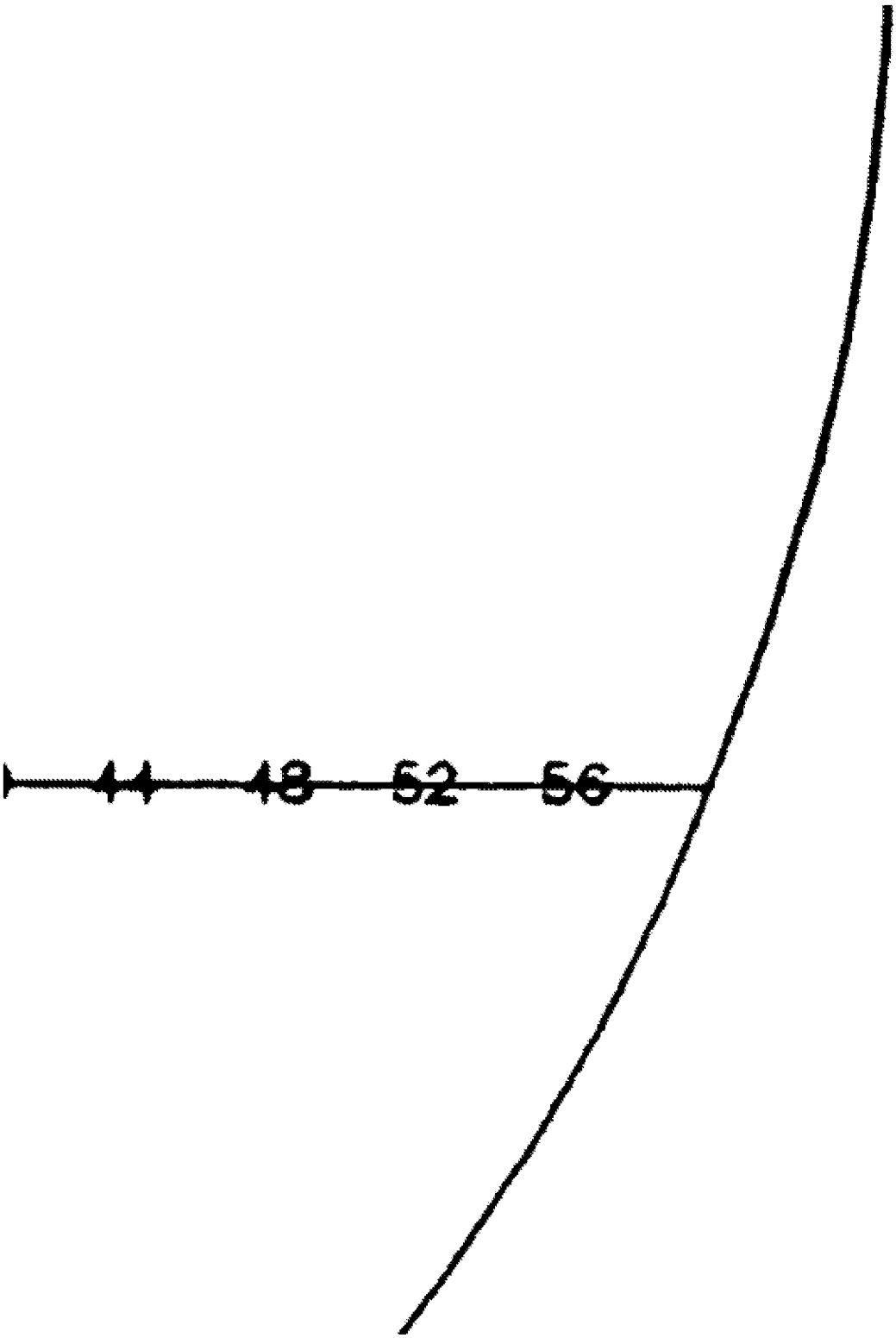


FIG. 51q

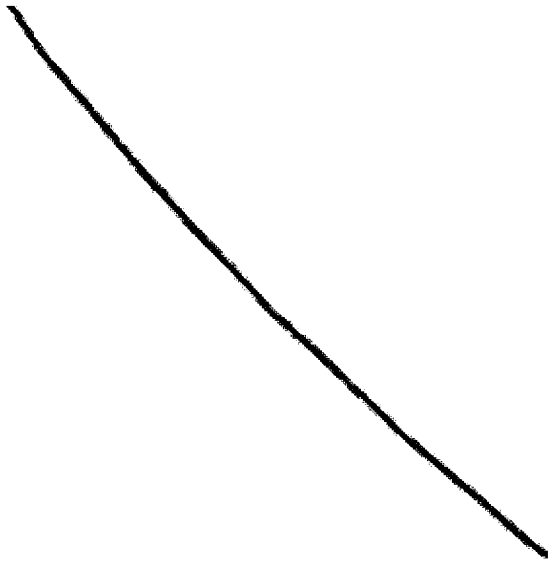


FIG. 51r

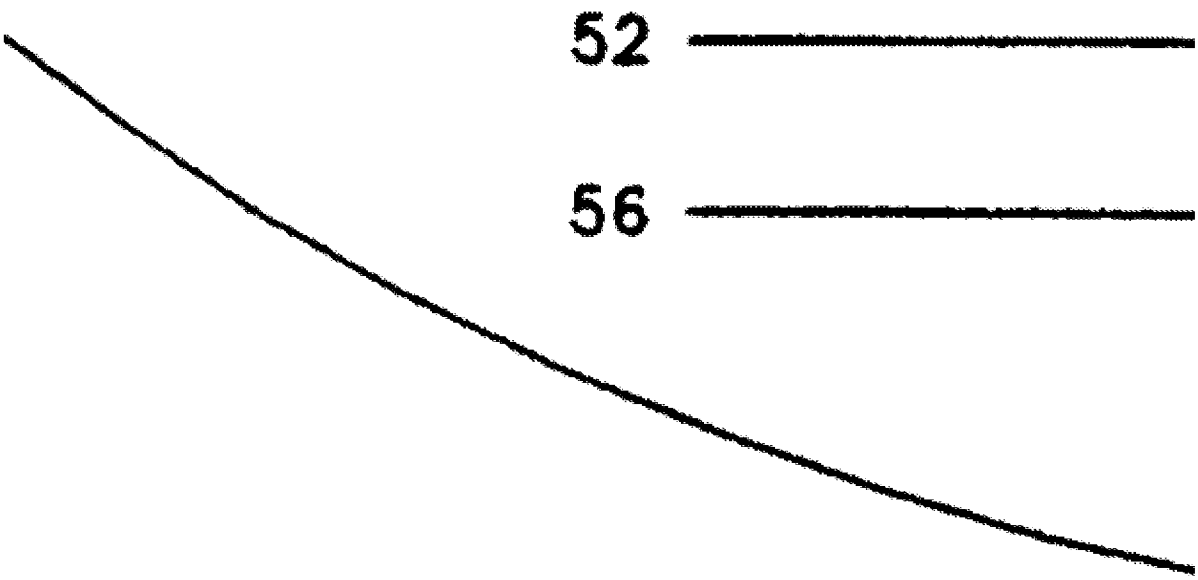


FIG. 51s

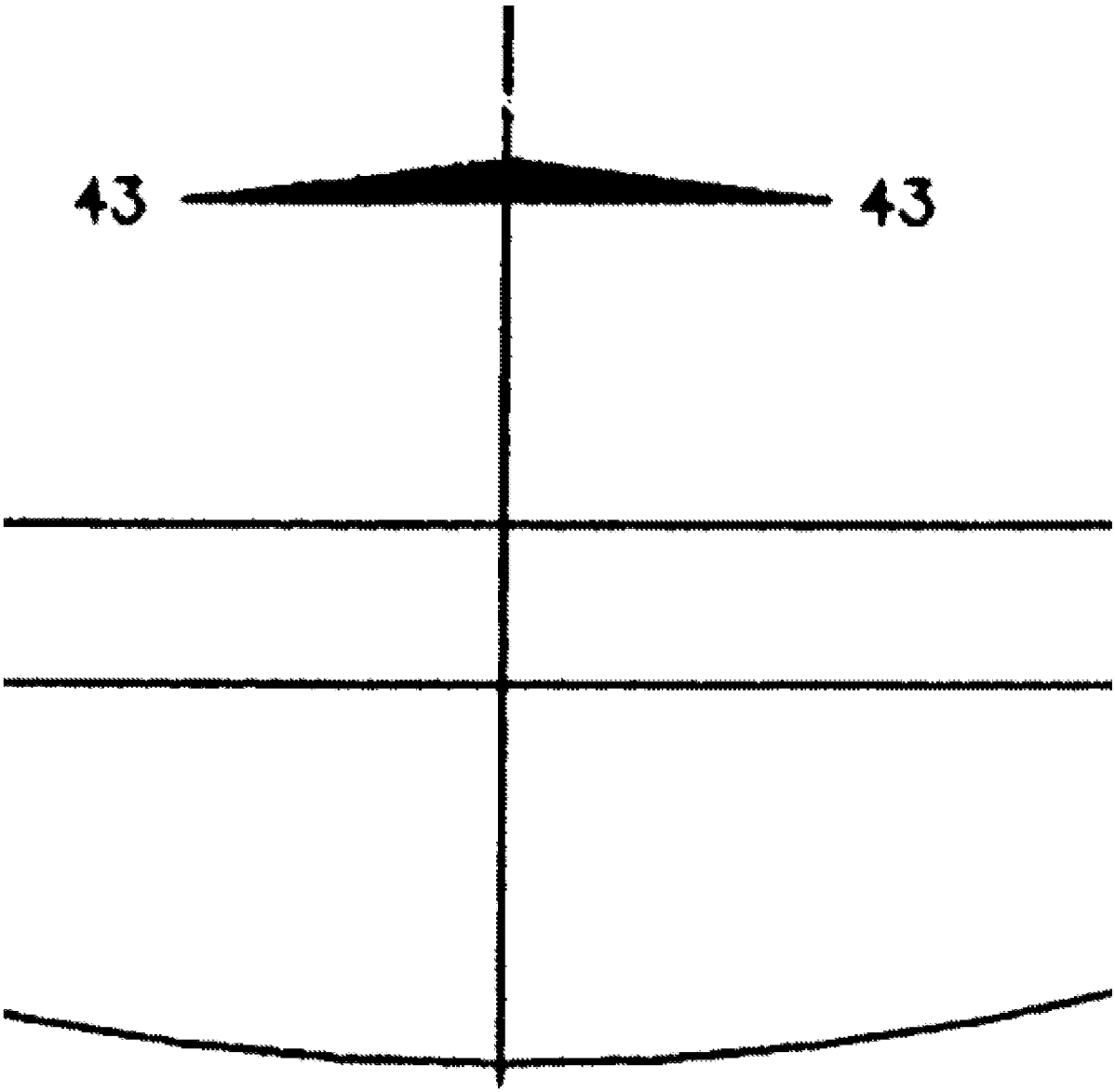


FIG. 51t

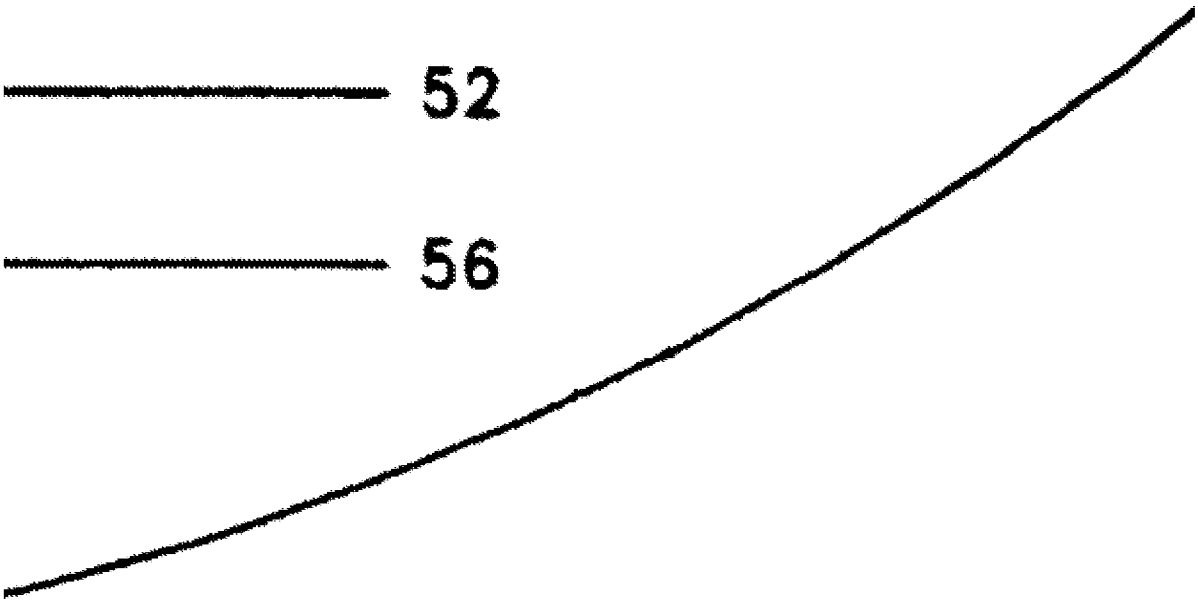


FIG. 51u

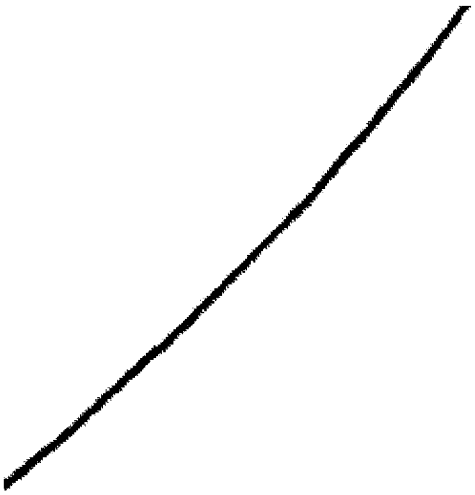


FIG. 51v

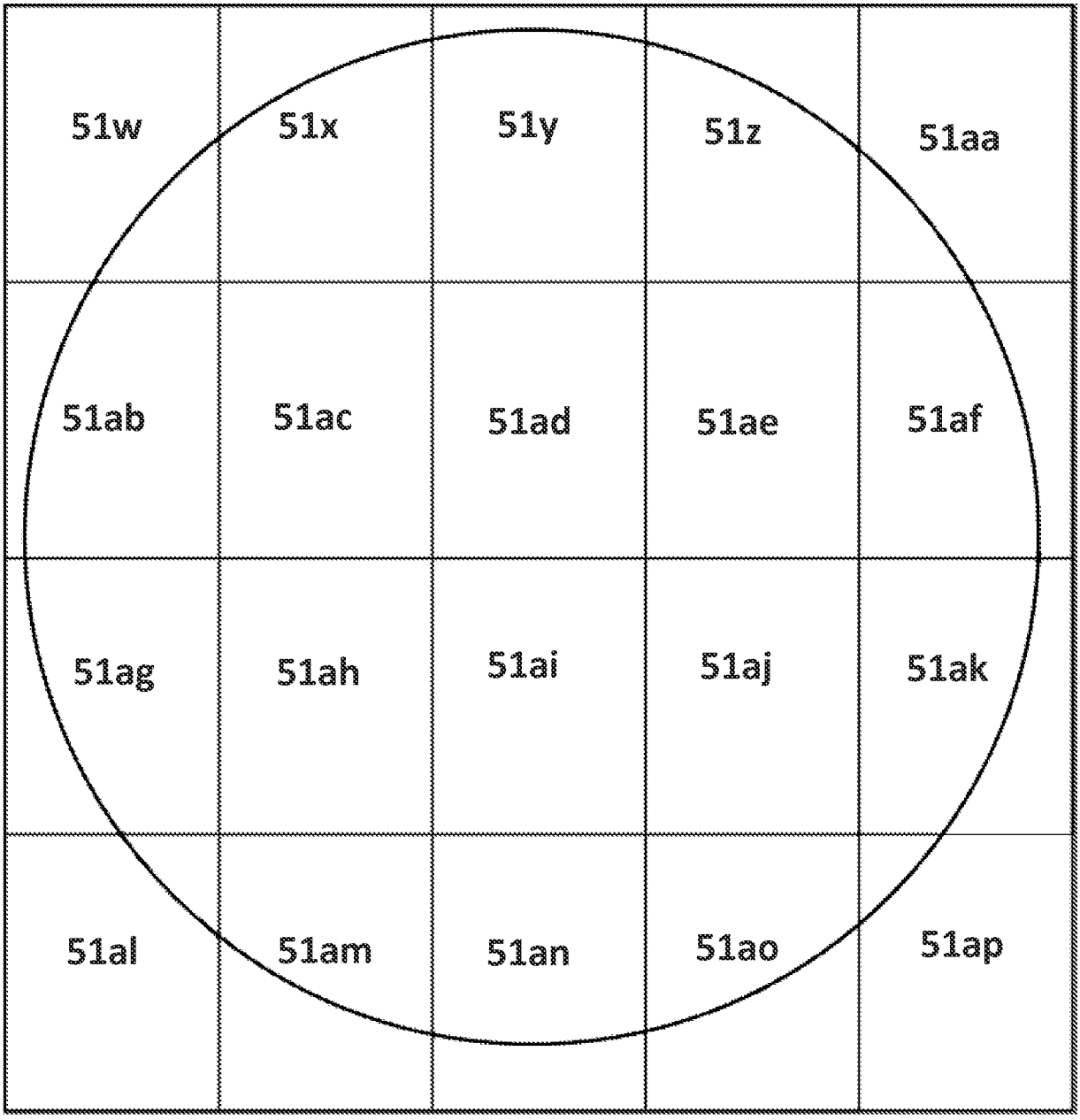

51w
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FIG. 51w

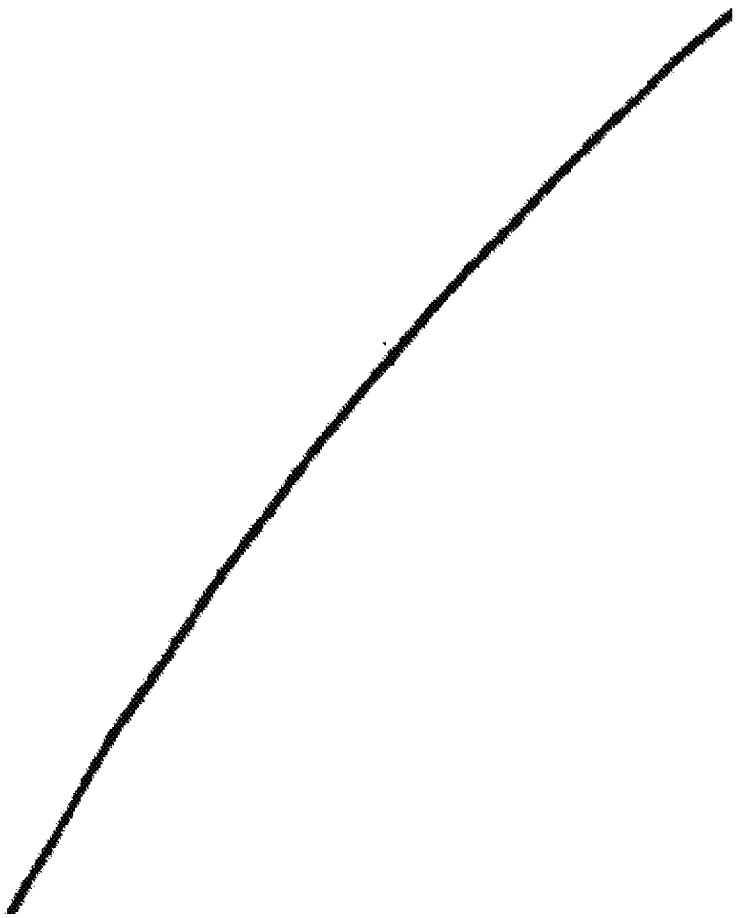


FIG. 51x

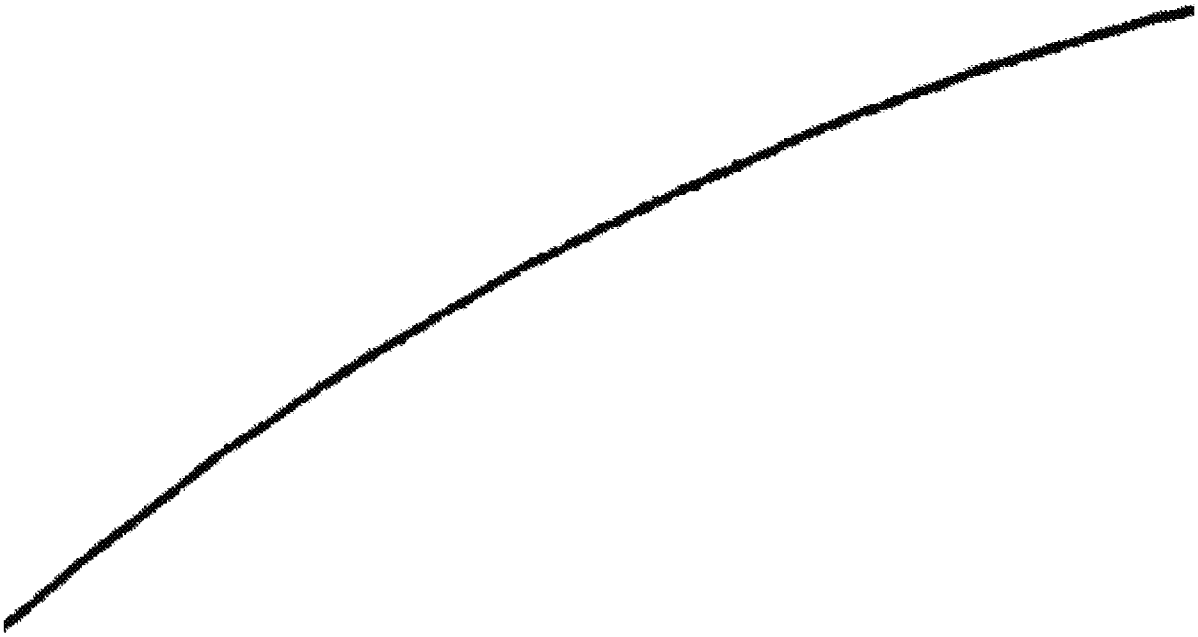


FIG. 51y



FIG. 51z

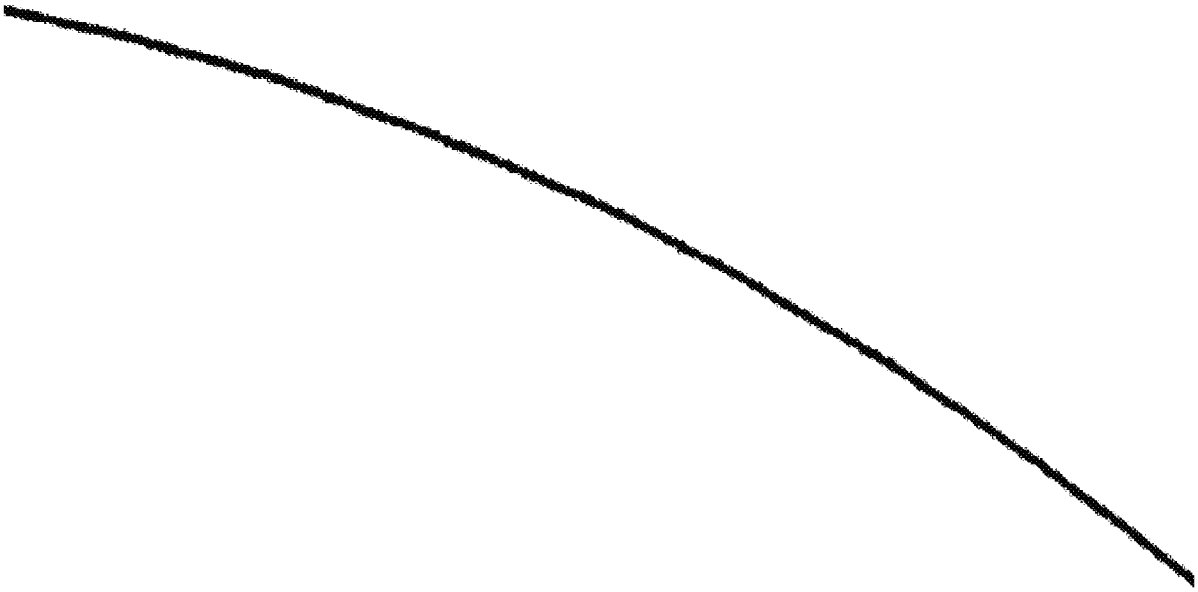


FIG. 51aa

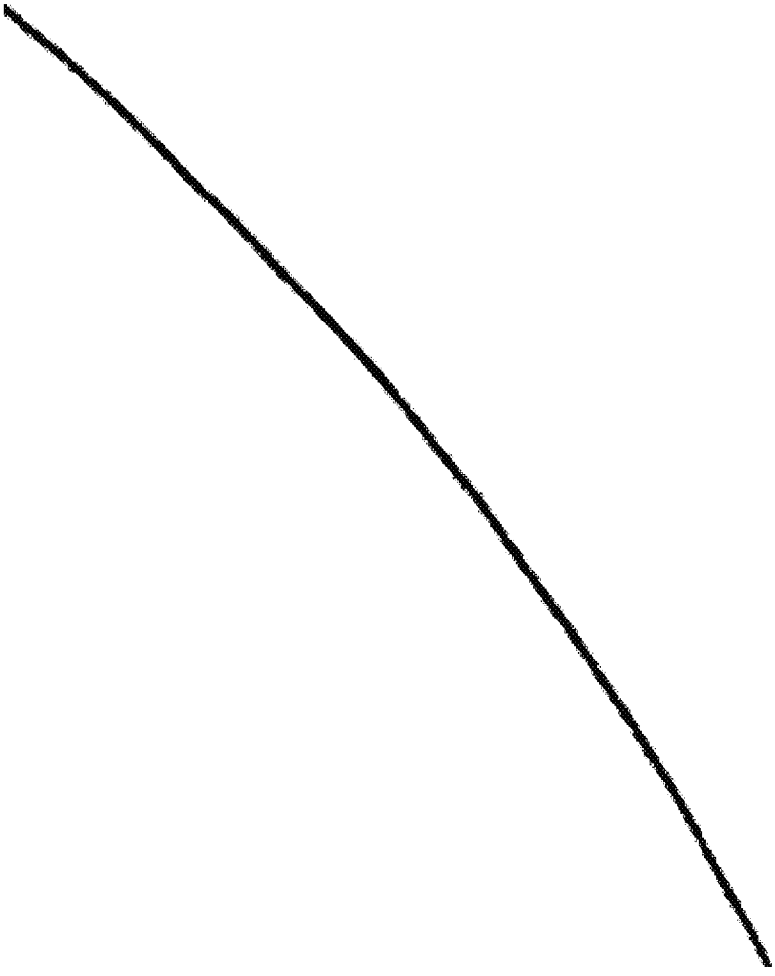


FIG. 51ab

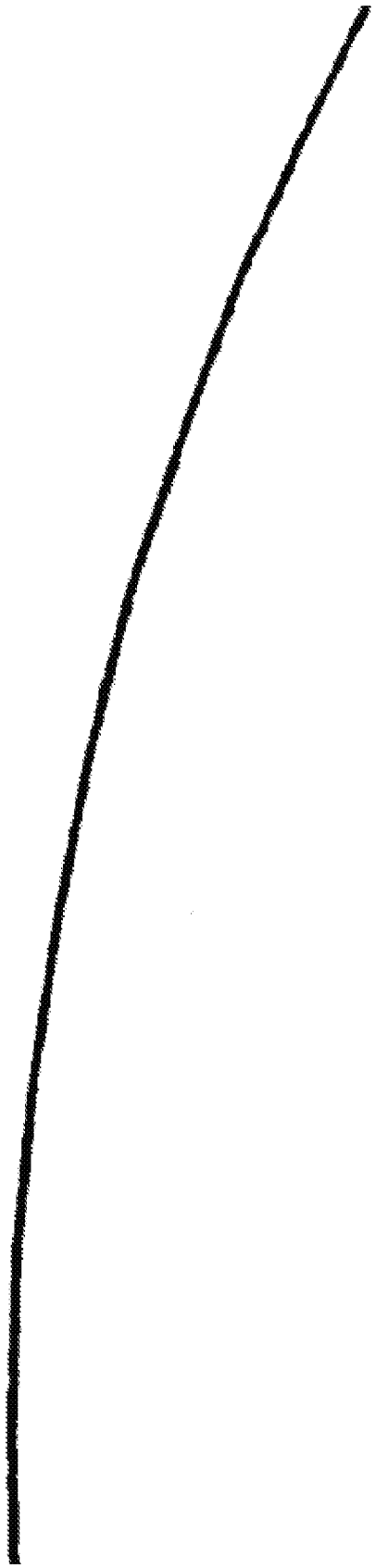


FIG. 51ac



FIG. 51ad

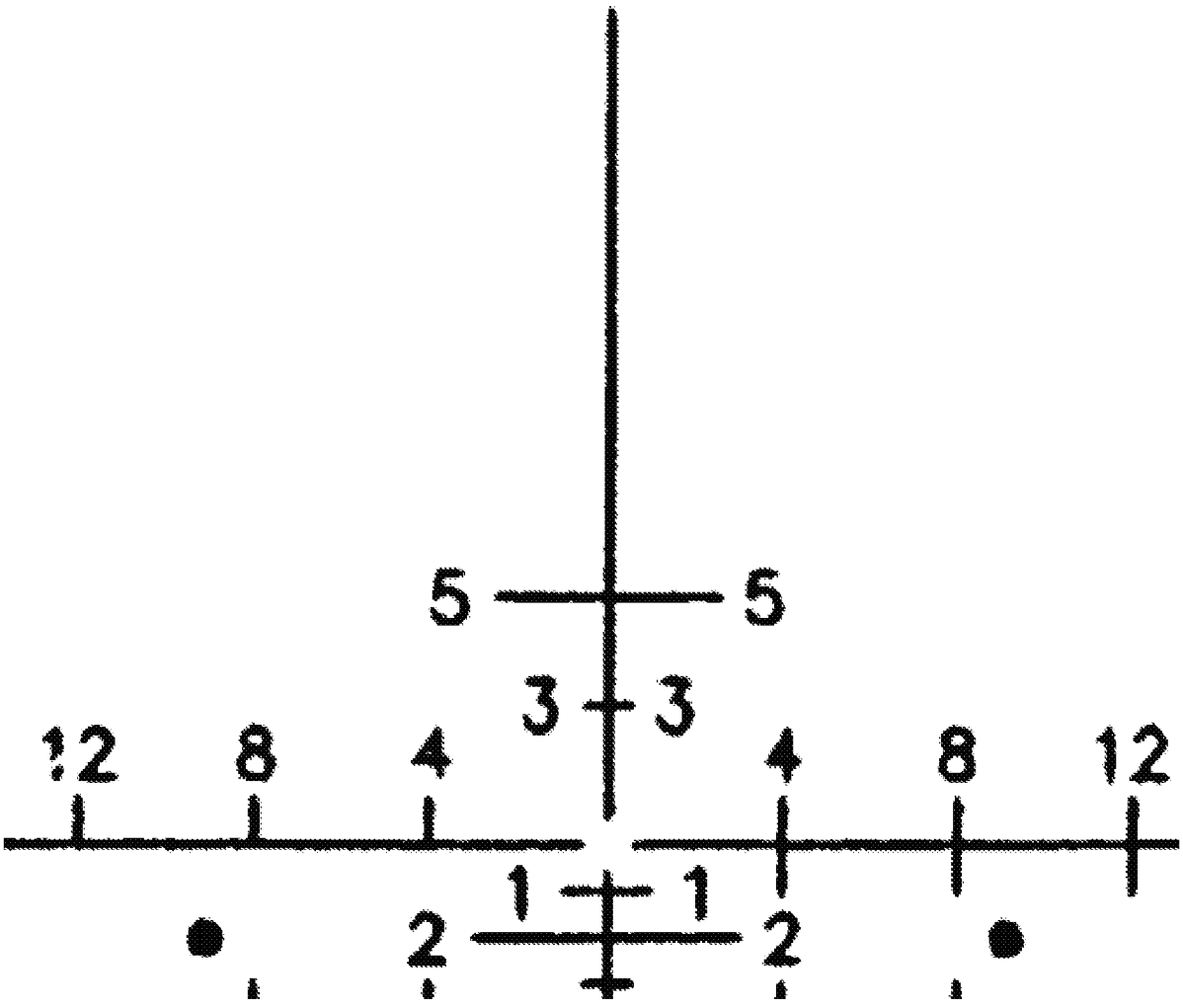


FIG. 51ae

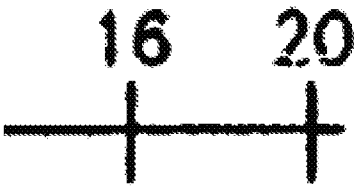


FIG. 51af

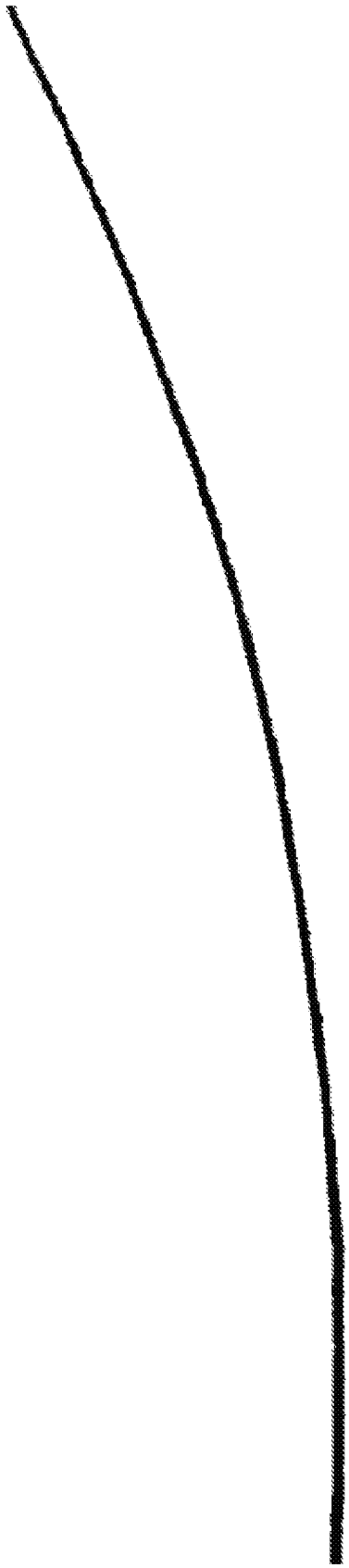


FIG. 51ag

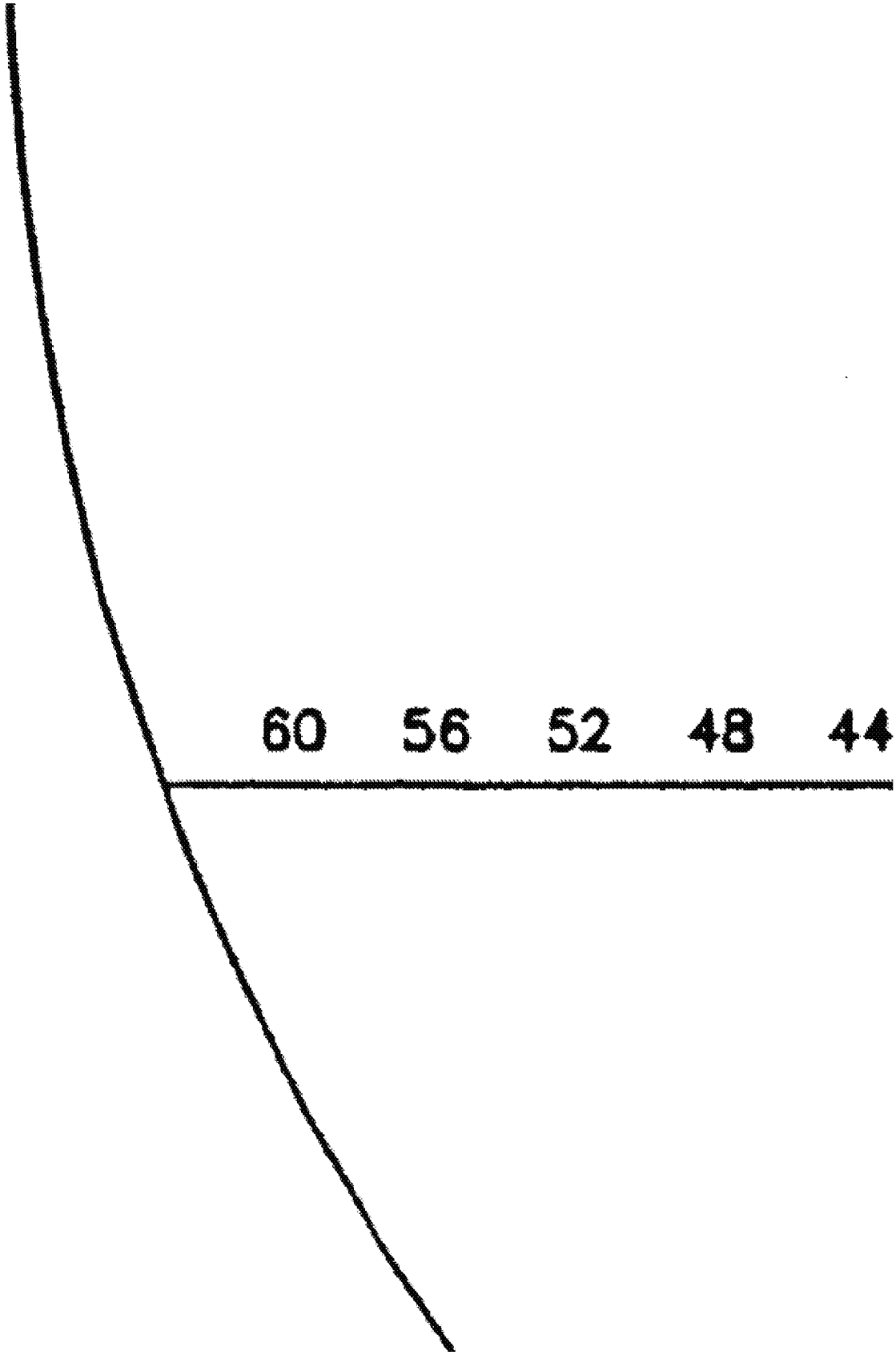


FIG. 51ah

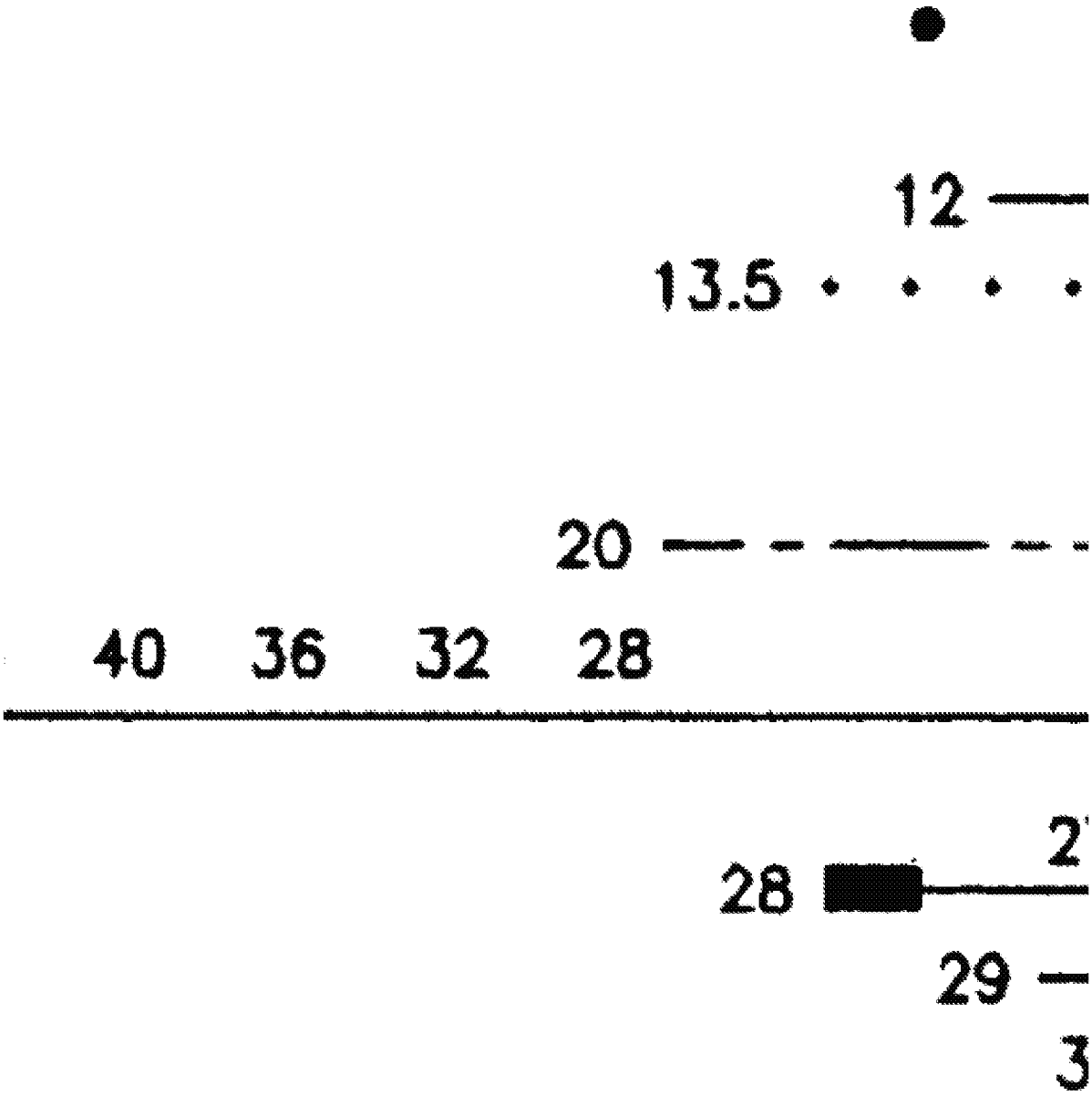


FIG. 51ai

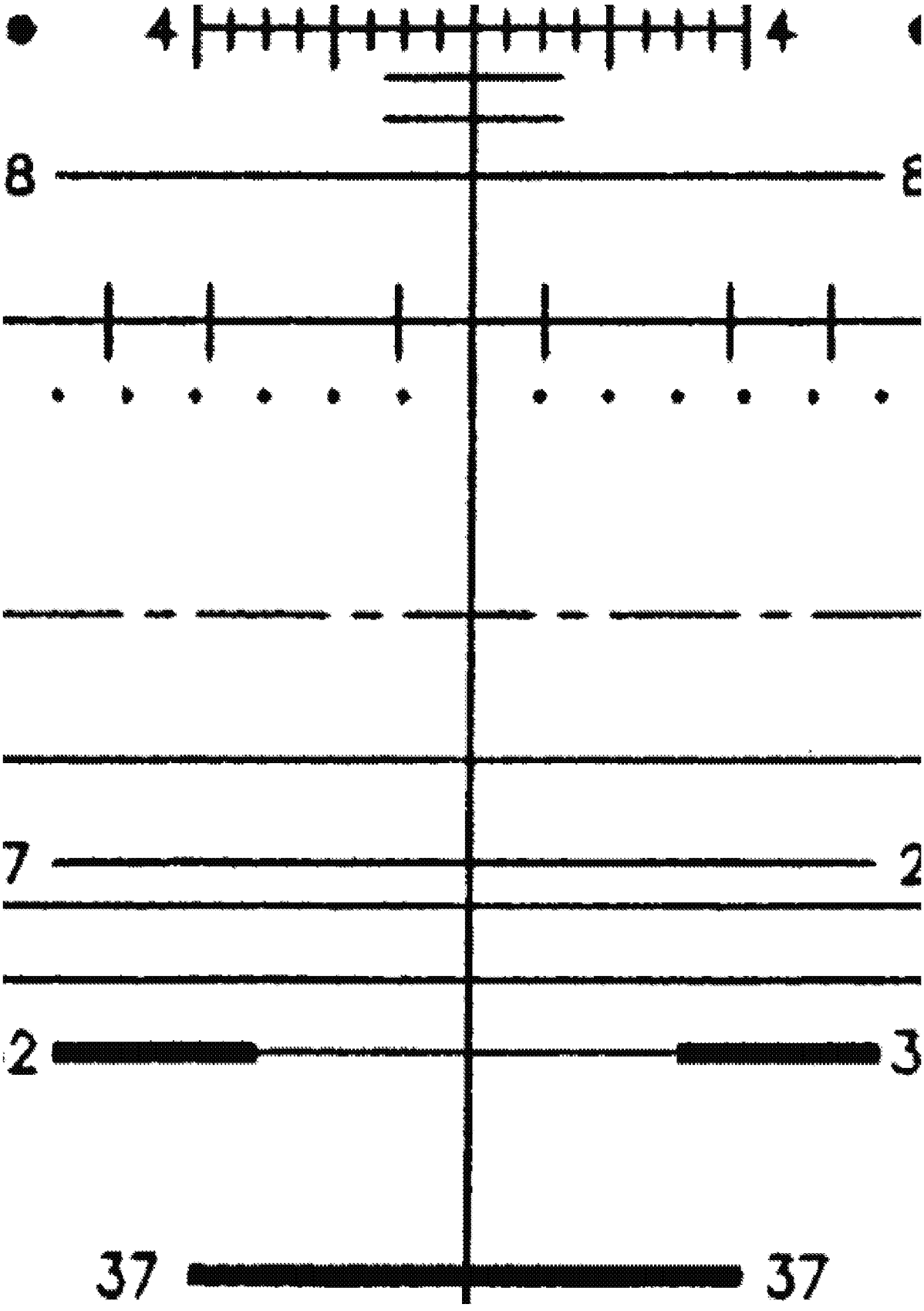


FIG. 51aj

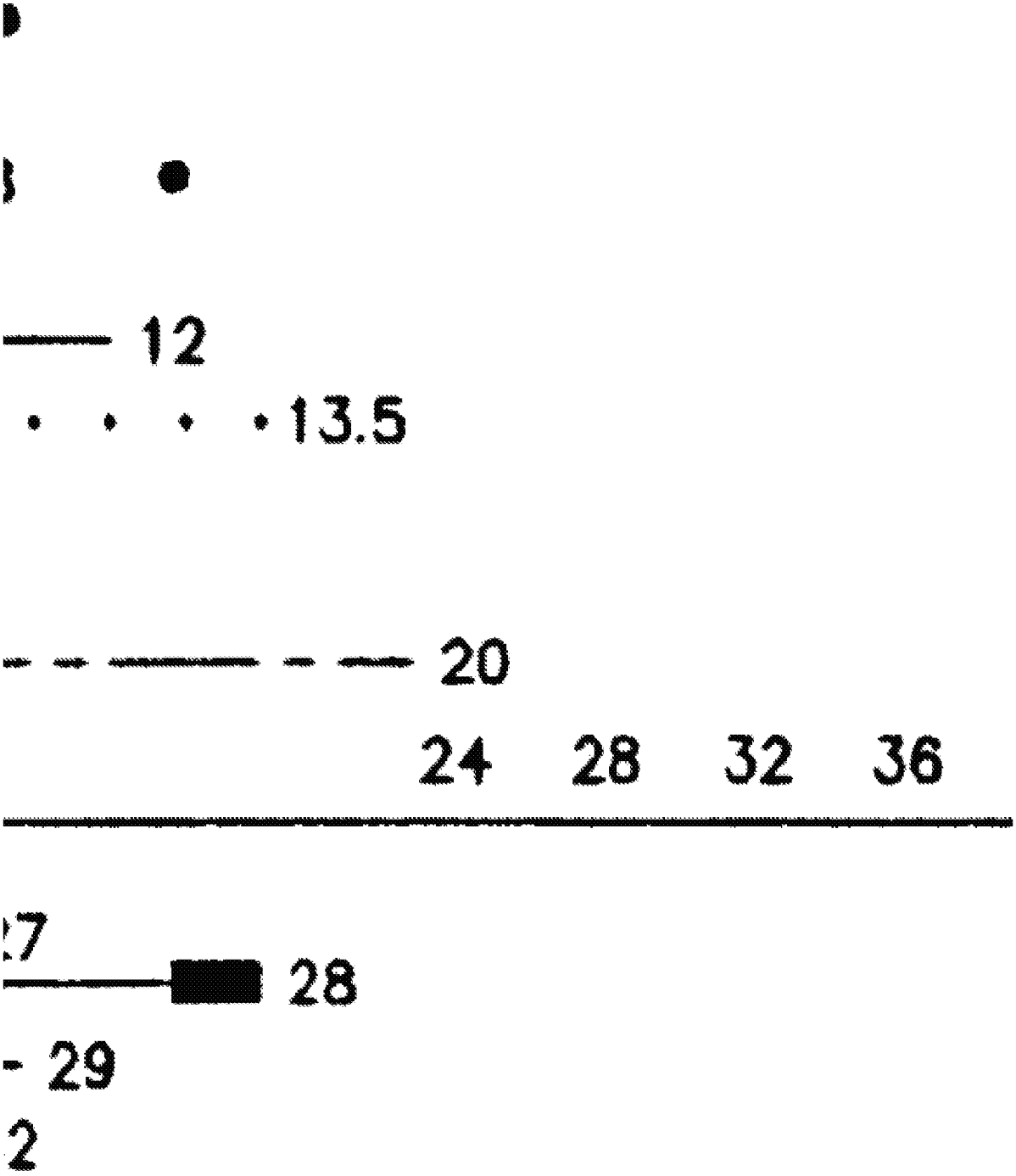


FIG. 51ak

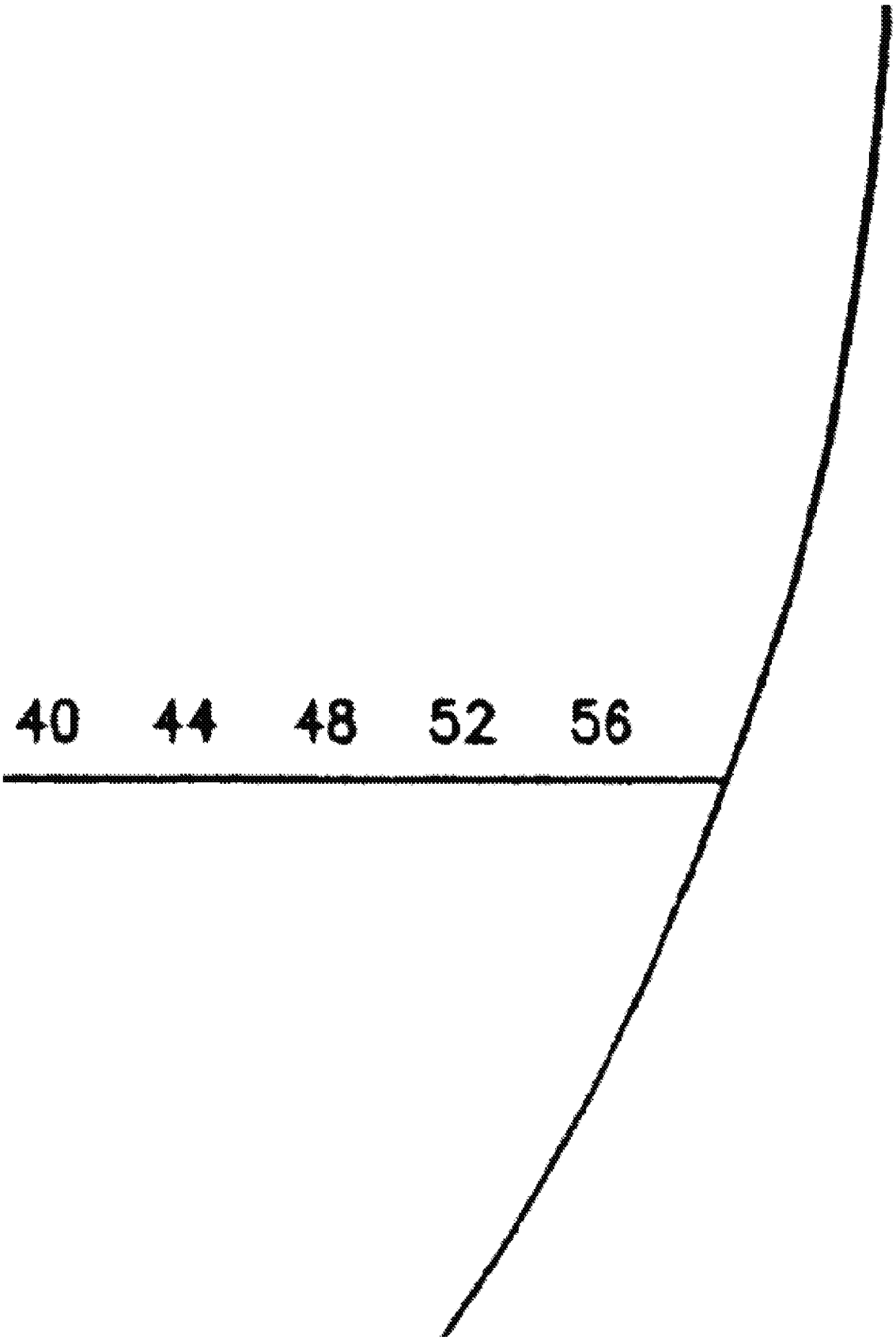


FIG. 51al

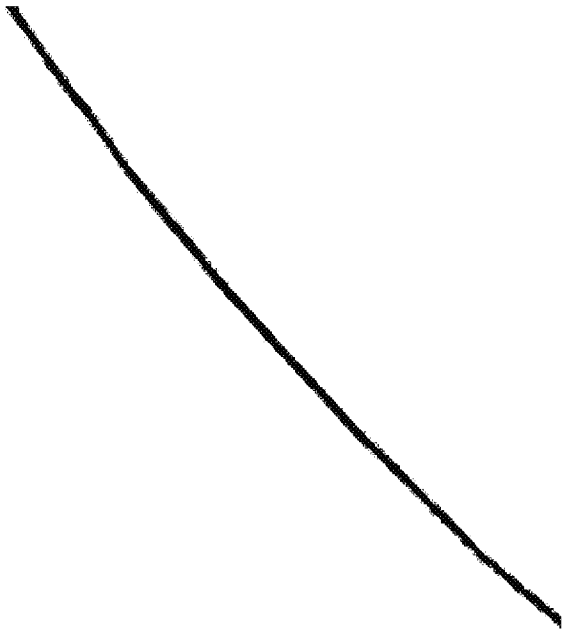


FIG. 51am

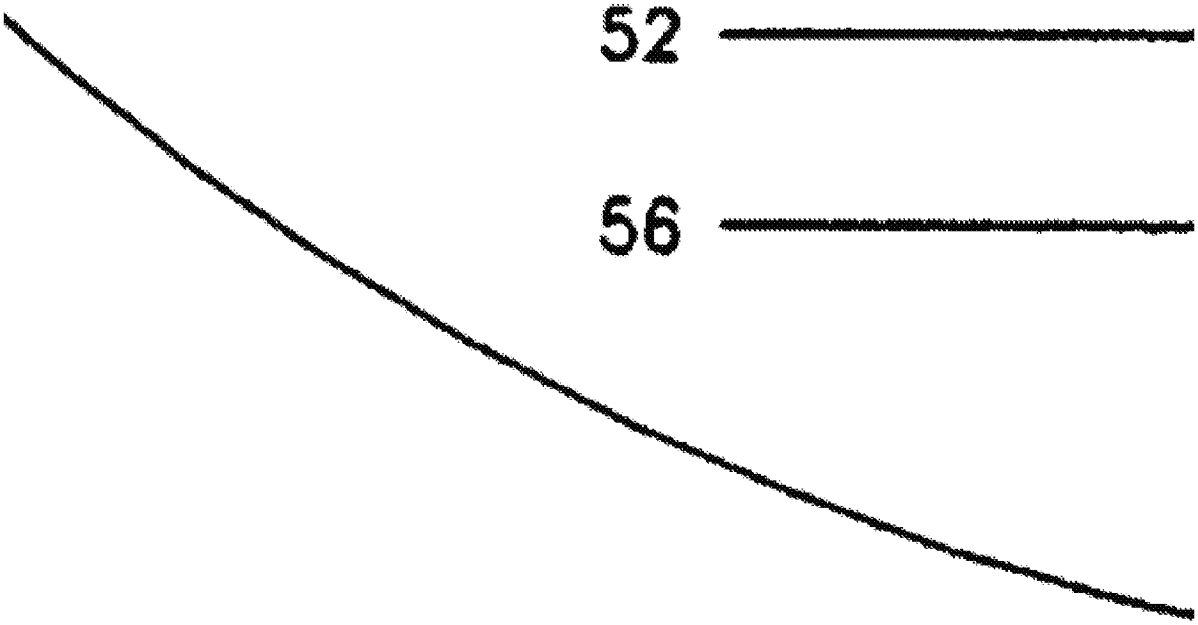


FIG. 51an

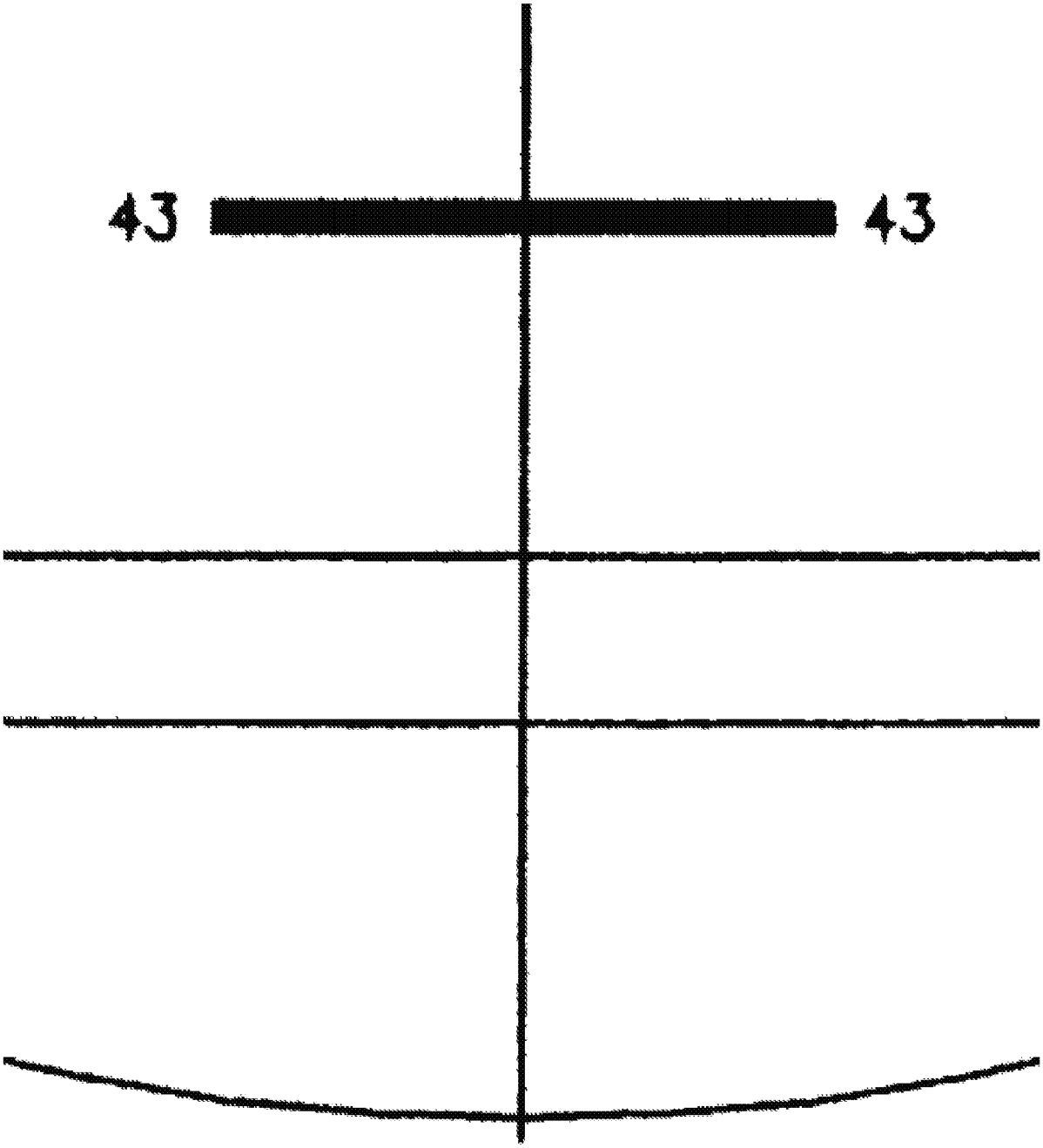


FIG. 51ao

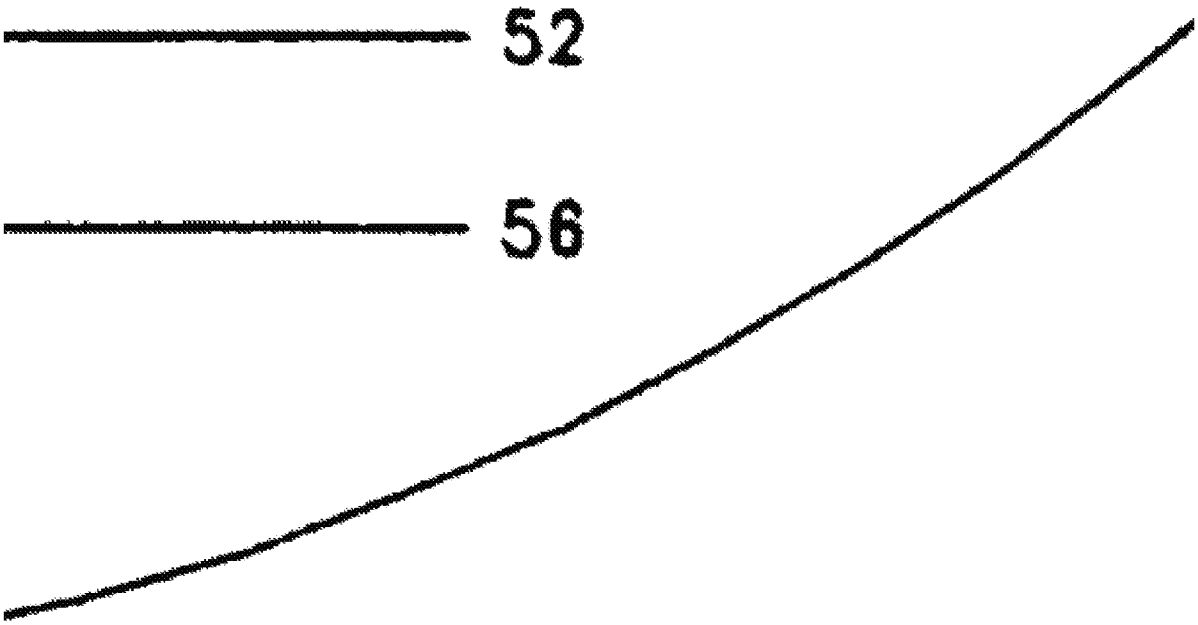


FIG. 51ap

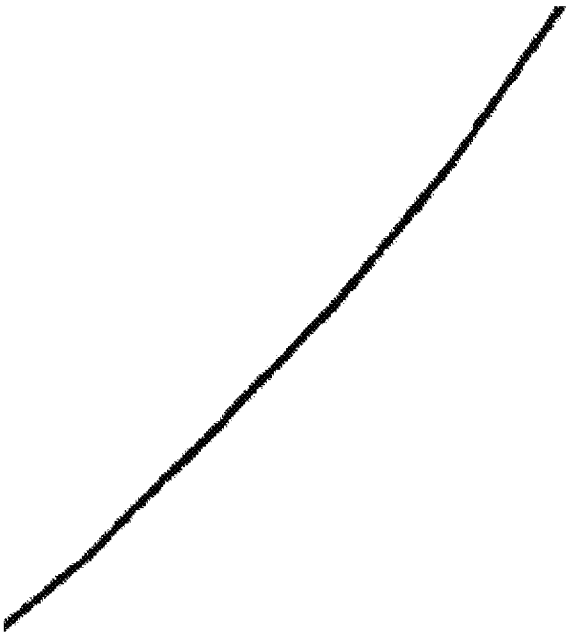


FIG. 51aq

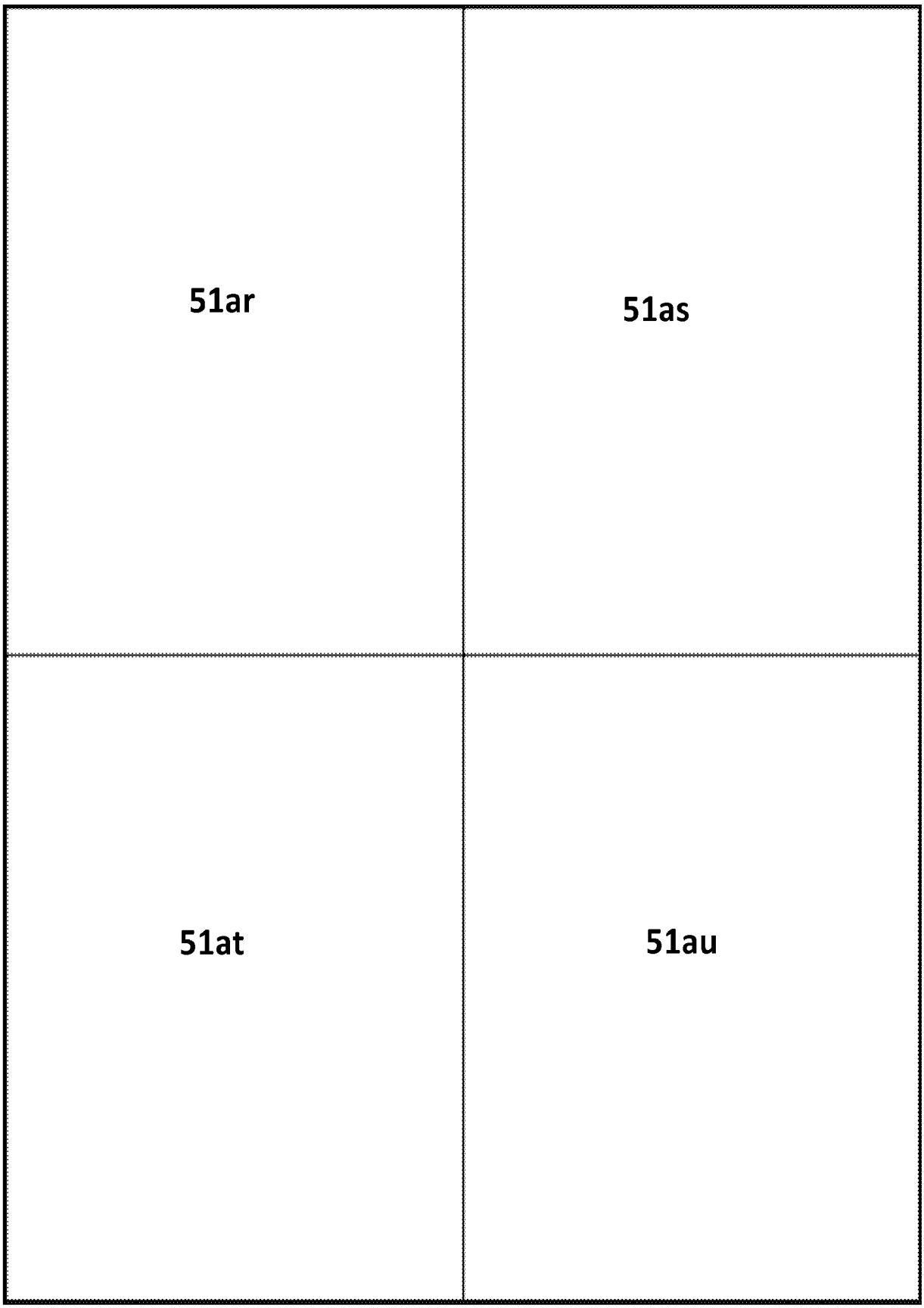


FIG. 51ar

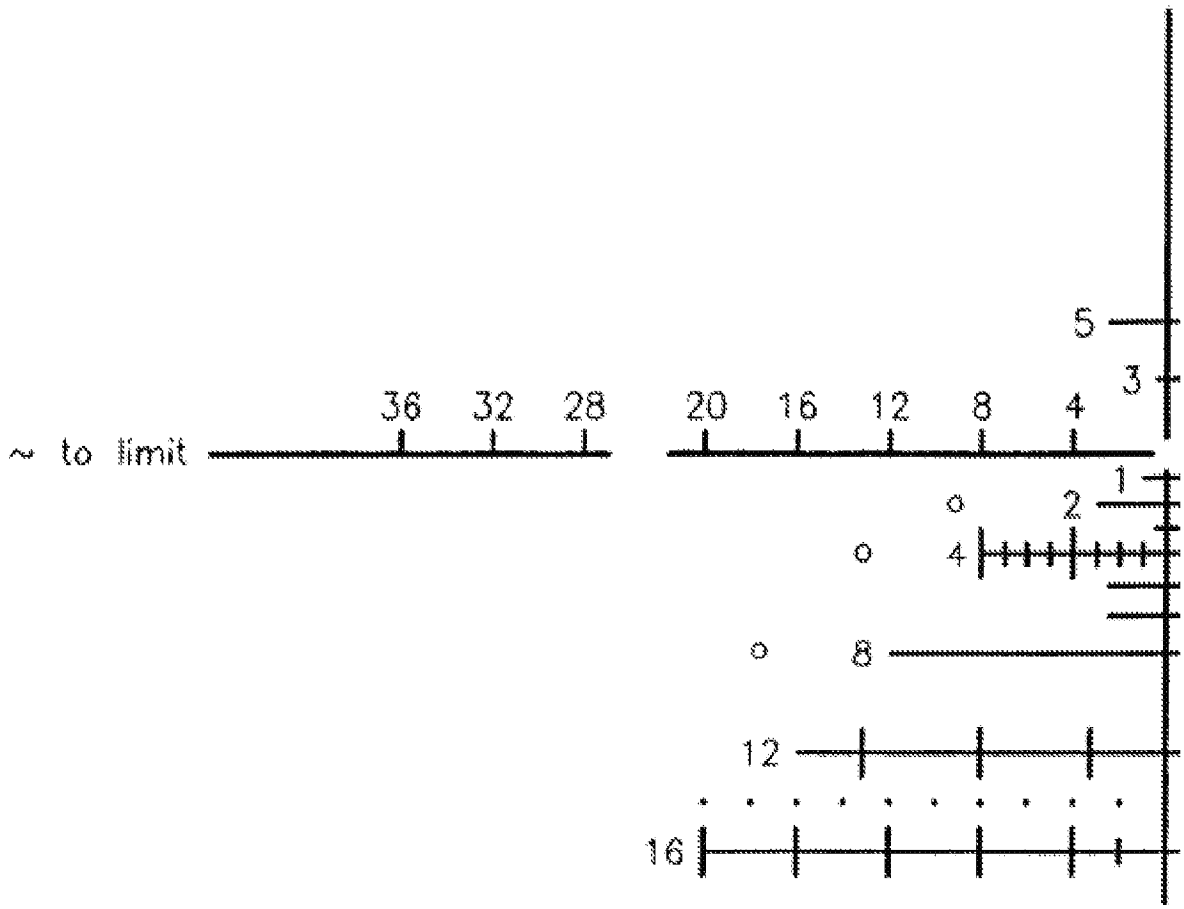


FIG. 51as

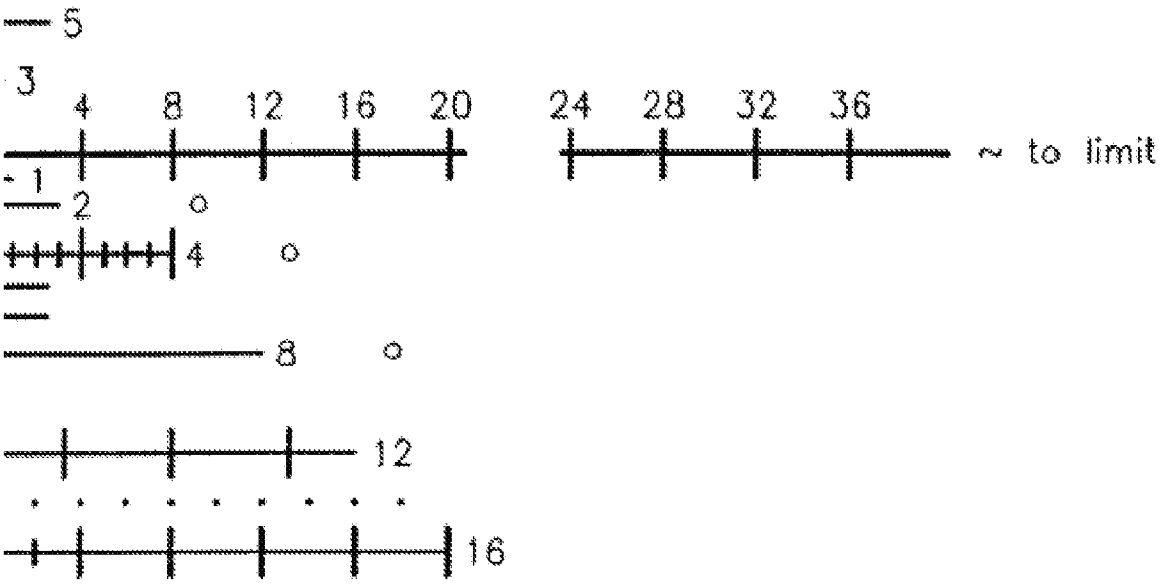


FIG. 51at

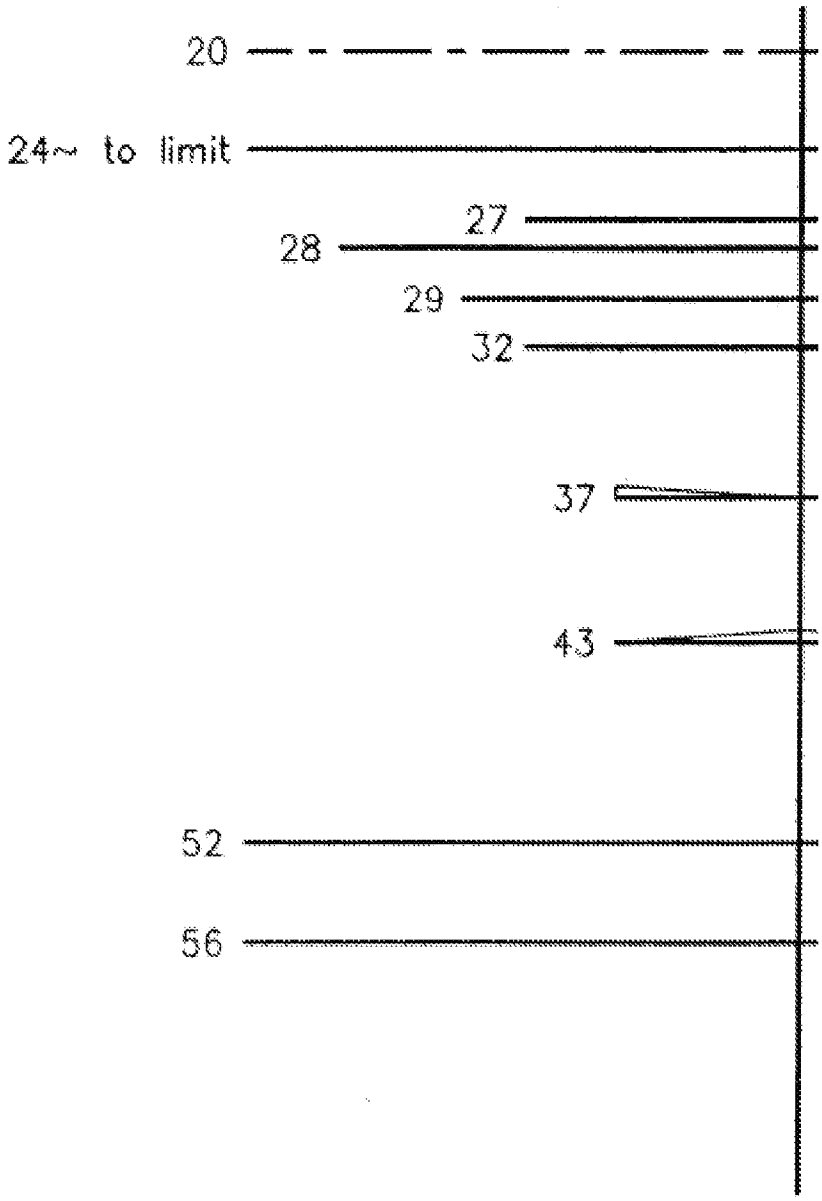


FIG. 51au

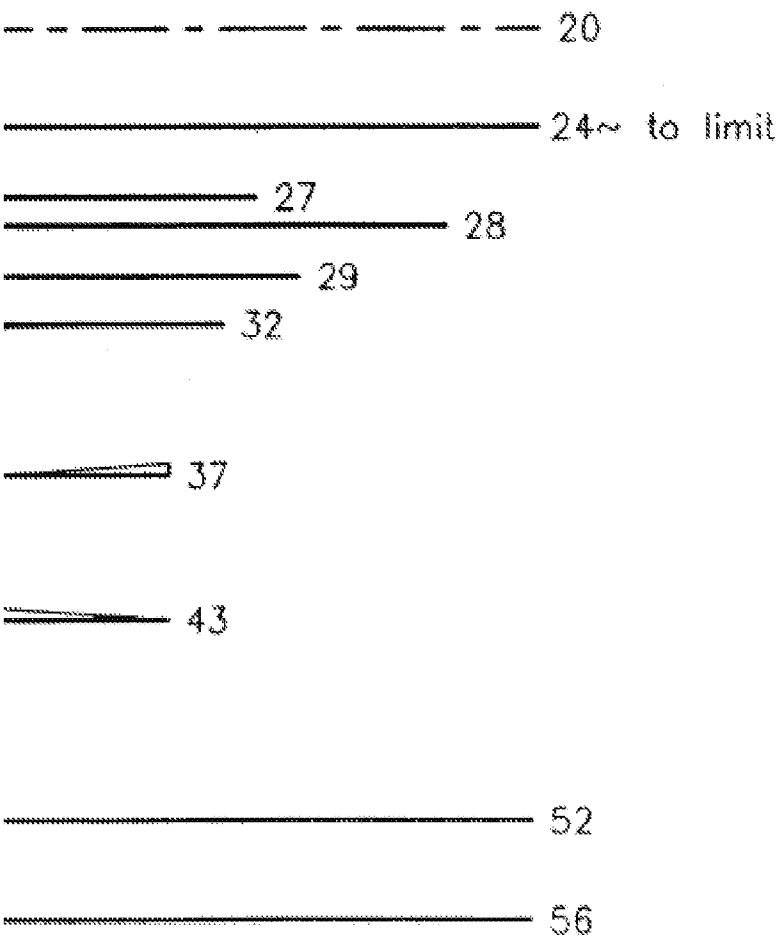


FIG. 52a

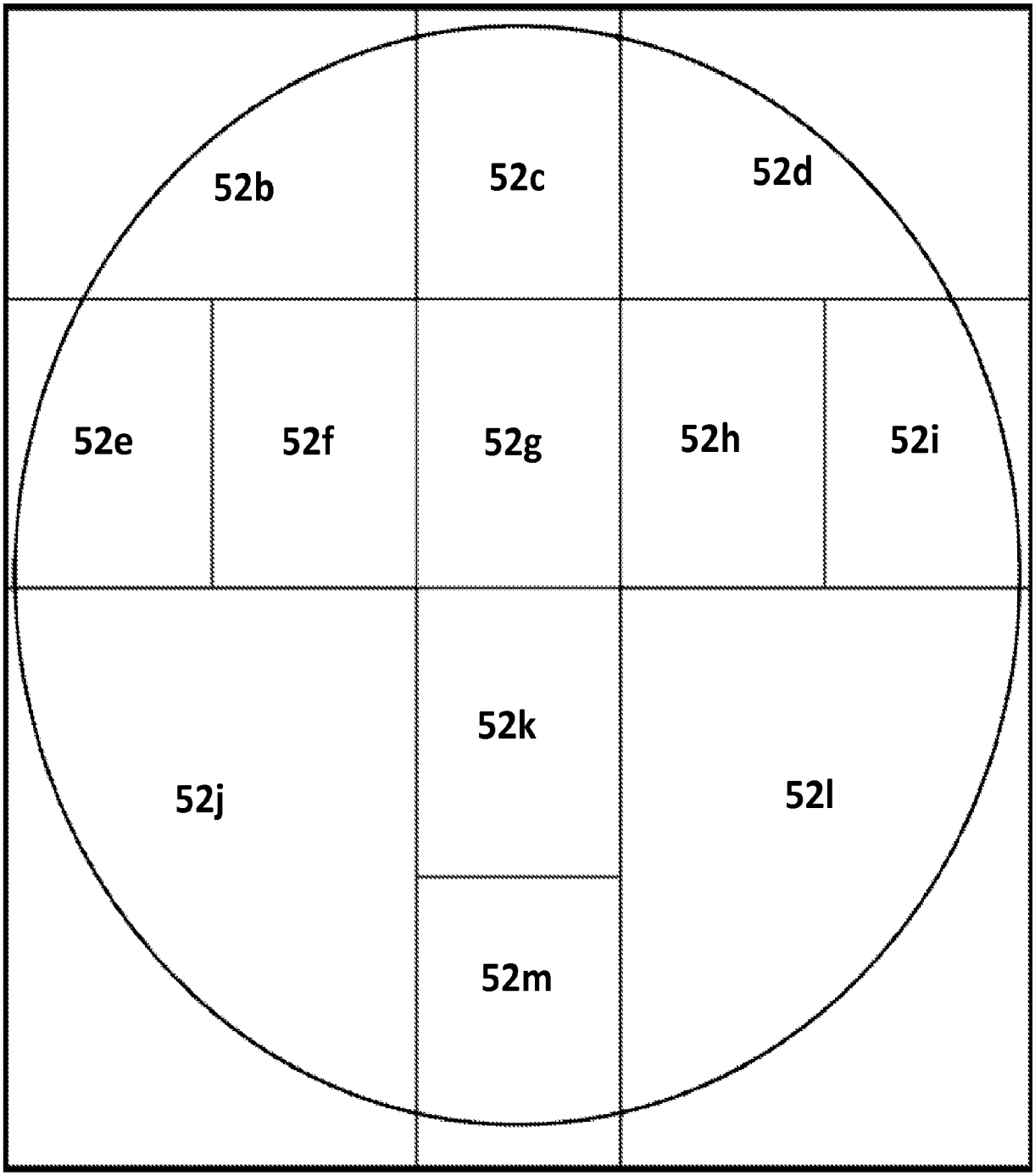


FIG. 52b

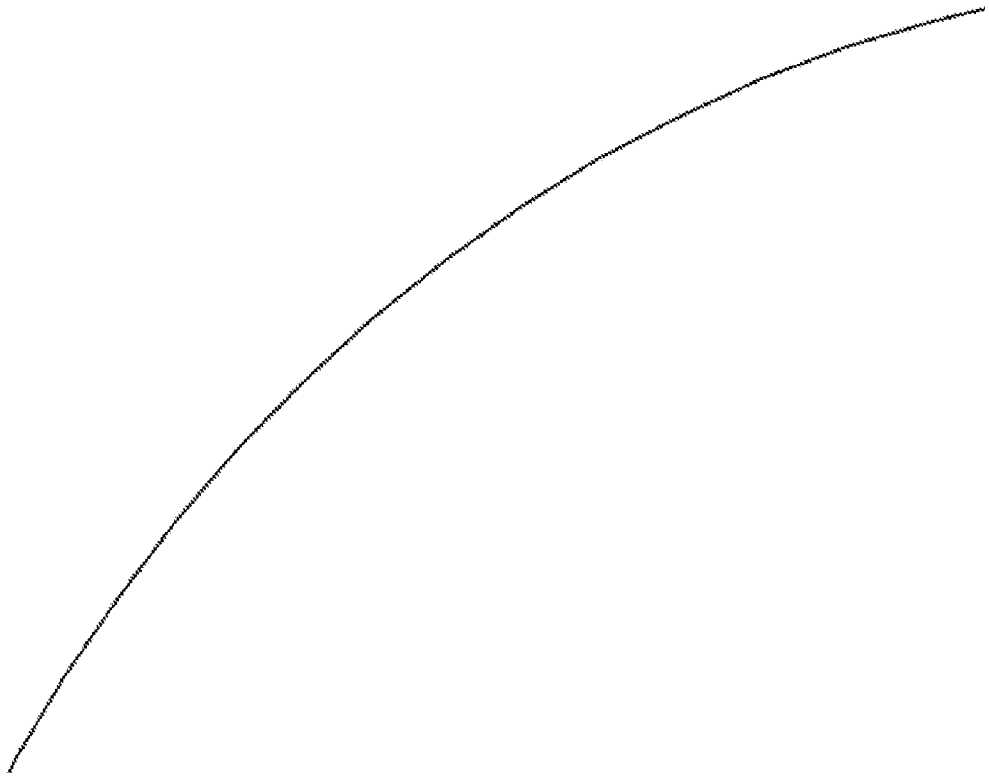


FIG. 52c

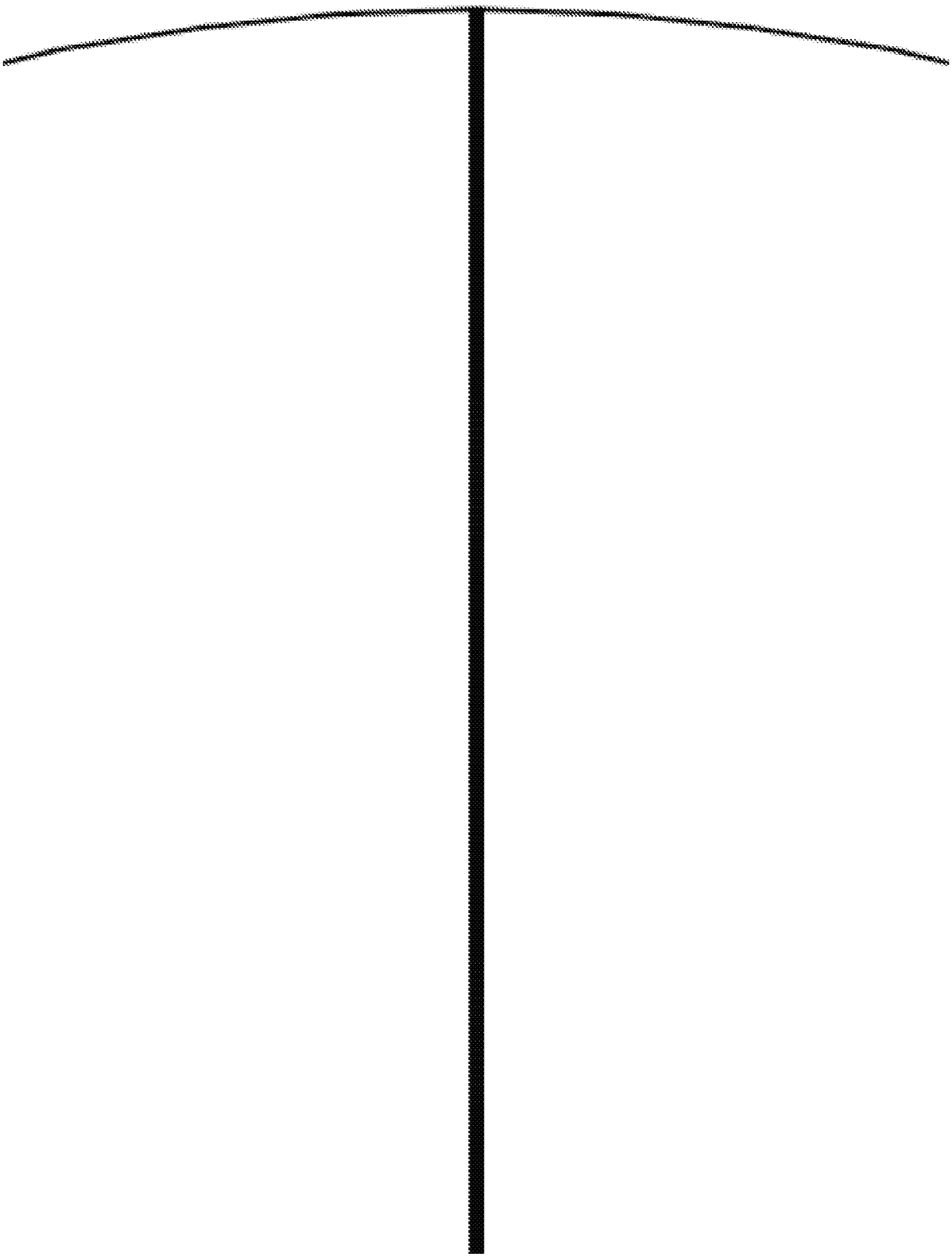


FIG. 52d

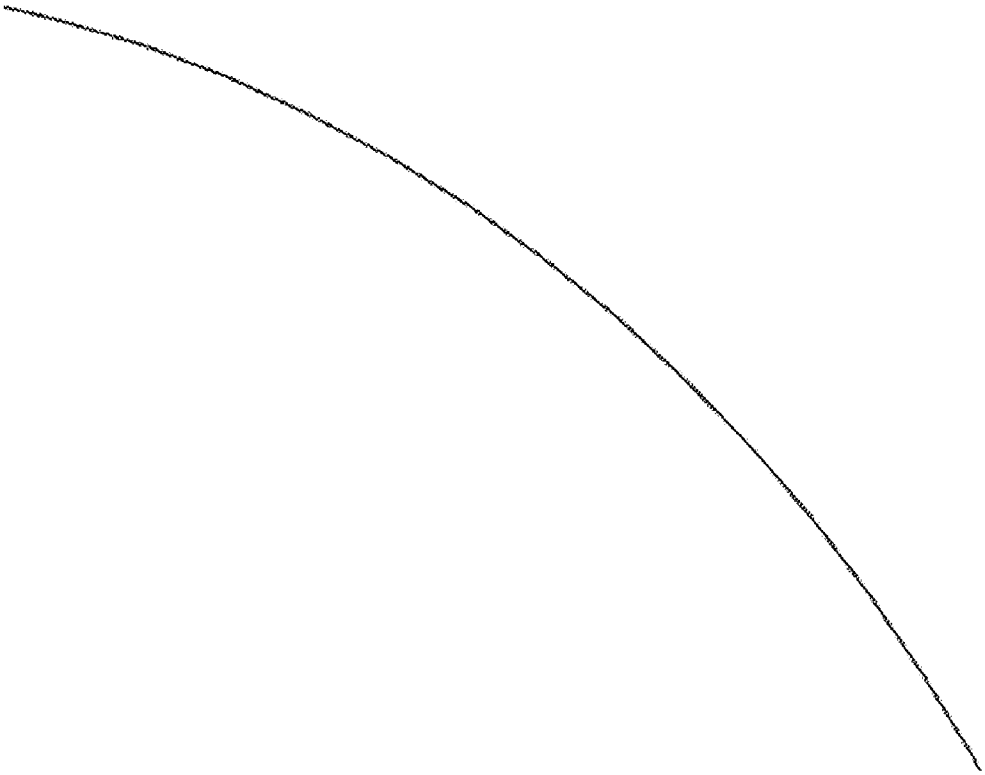


FIG. 52e

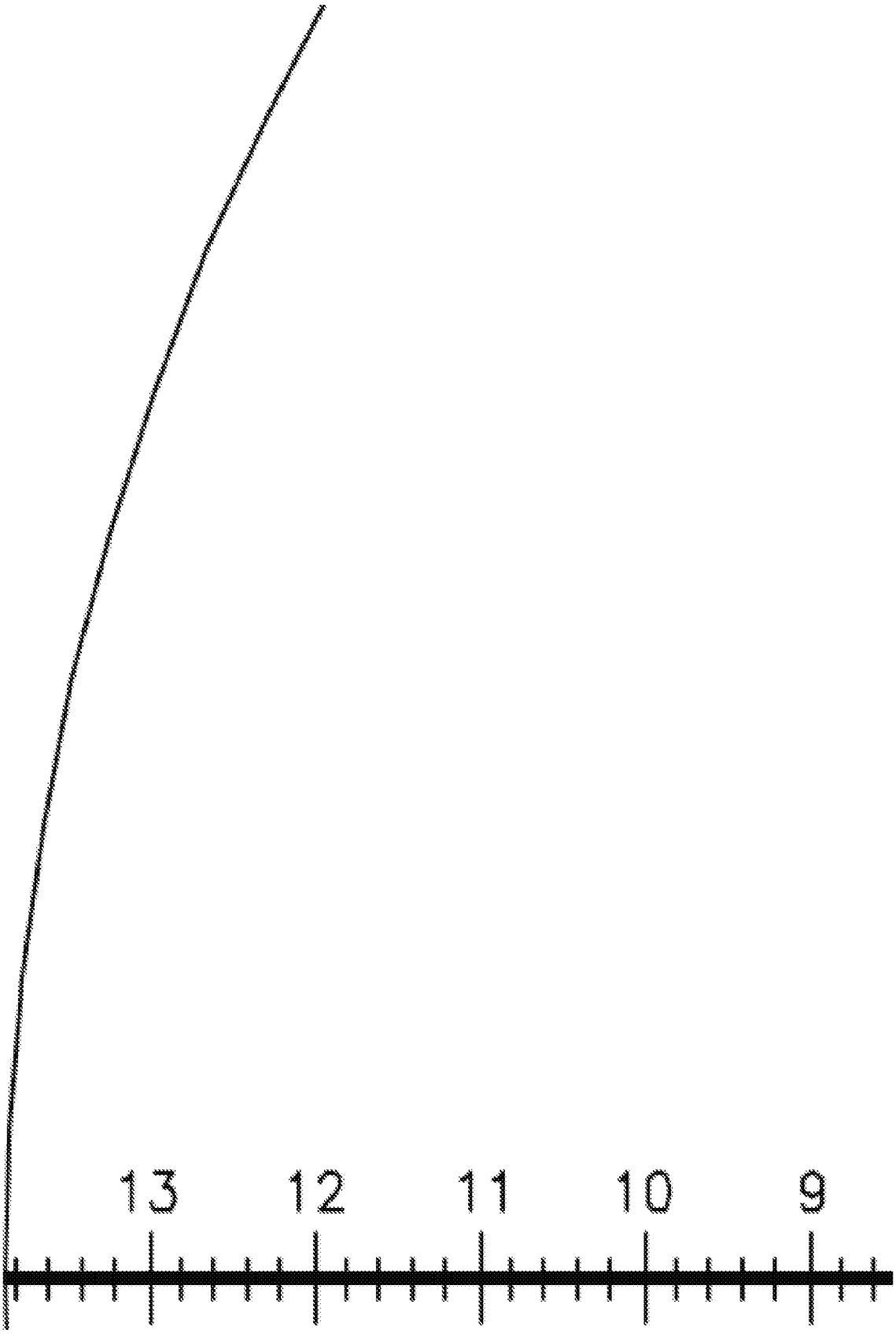


FIG. 52f

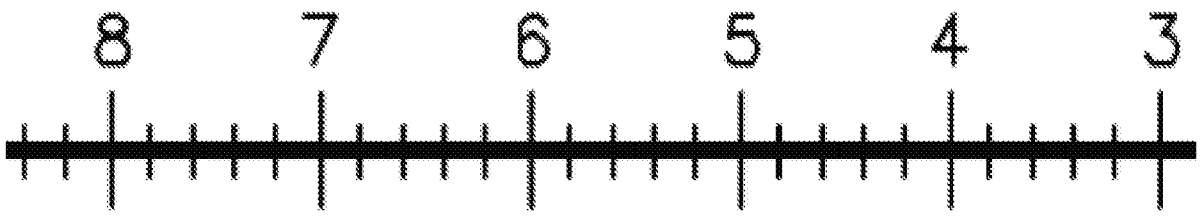


FIG. 52g

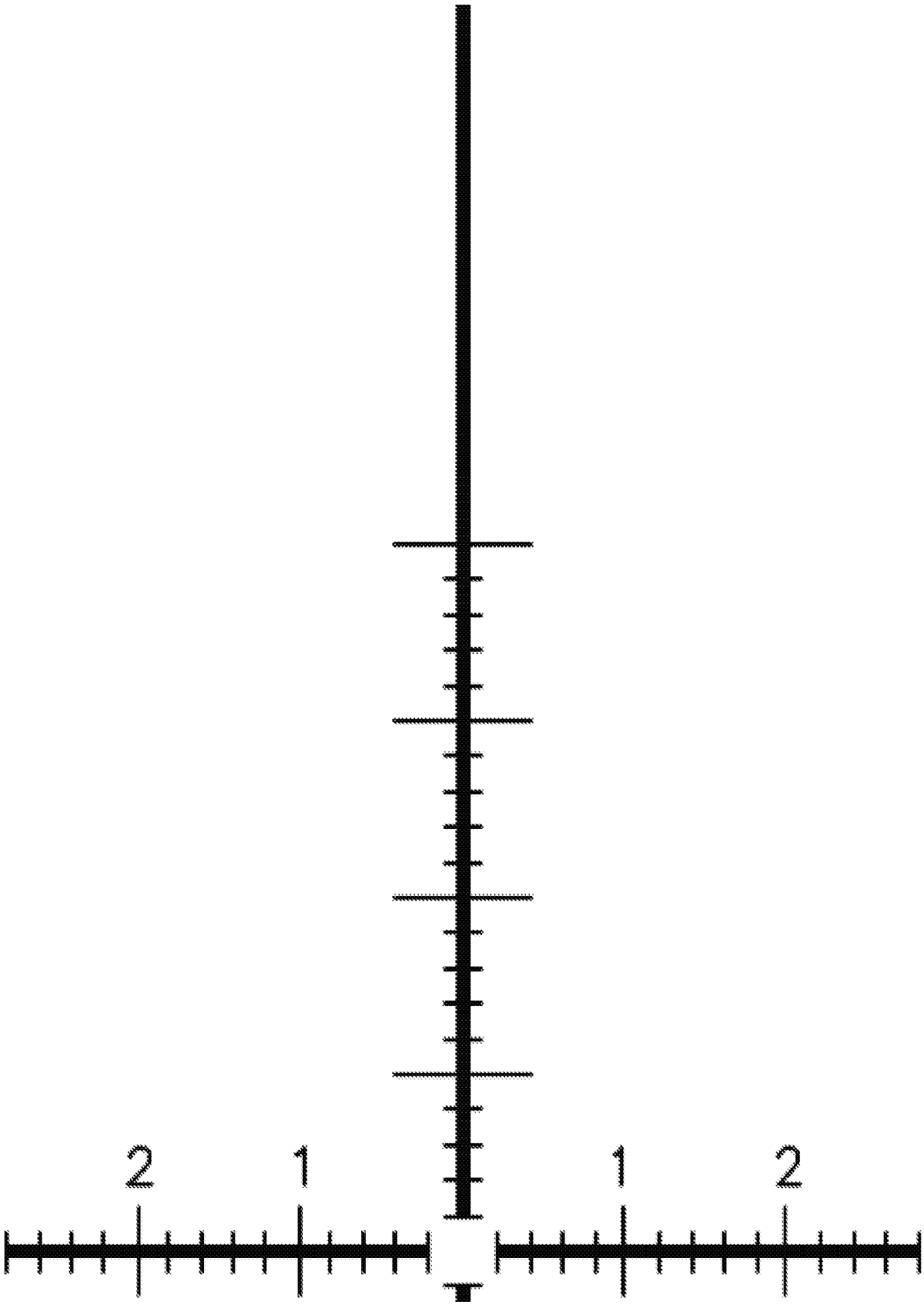


FIG. 52h

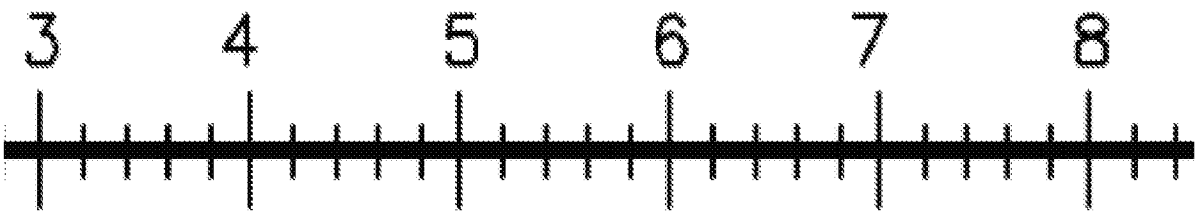


FIG. 52i

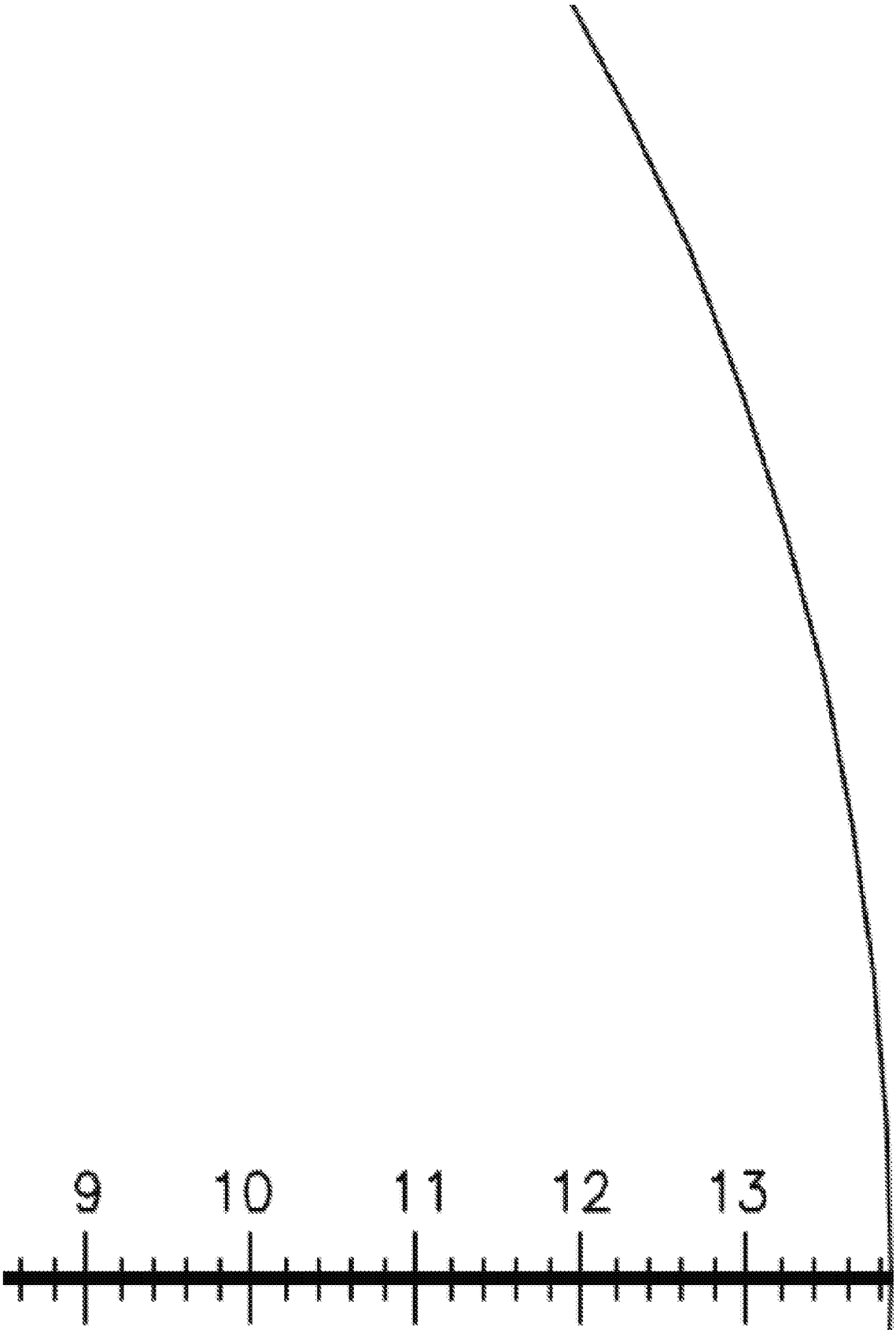


FIG. 52j

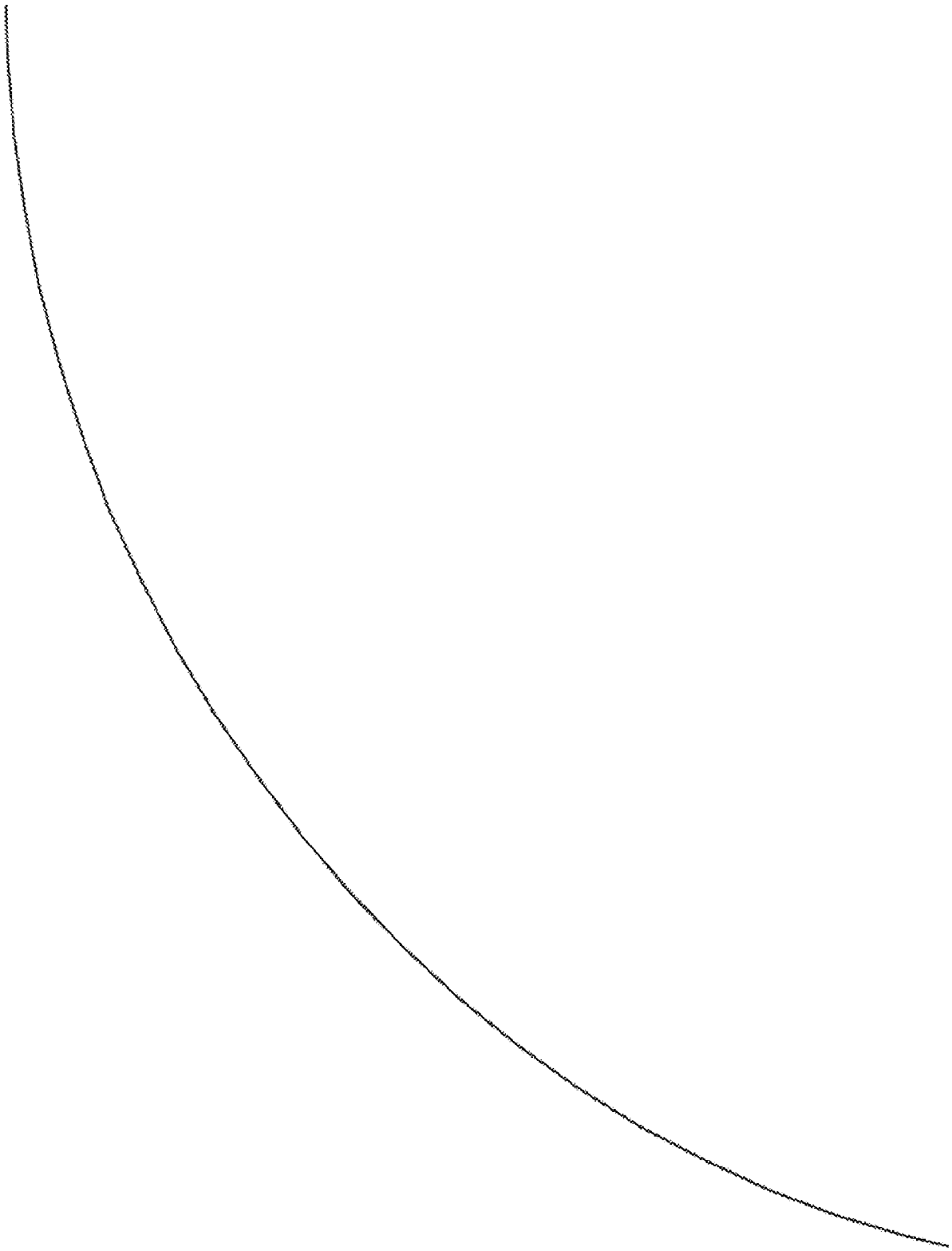


FIG. 52k

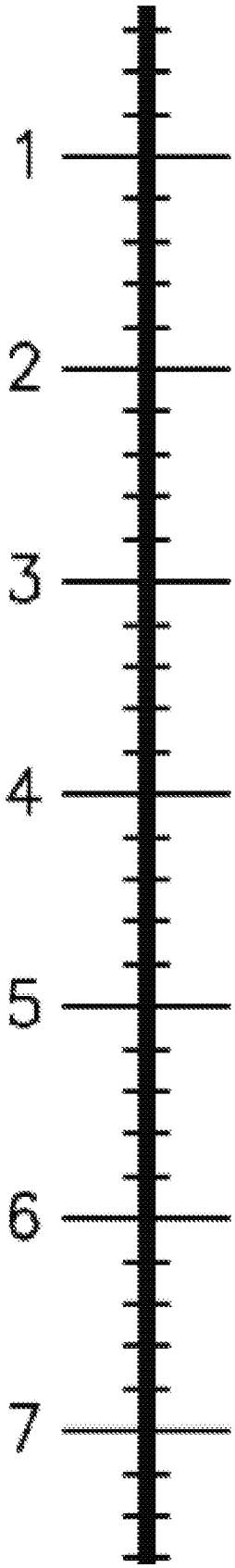


FIG. 52I

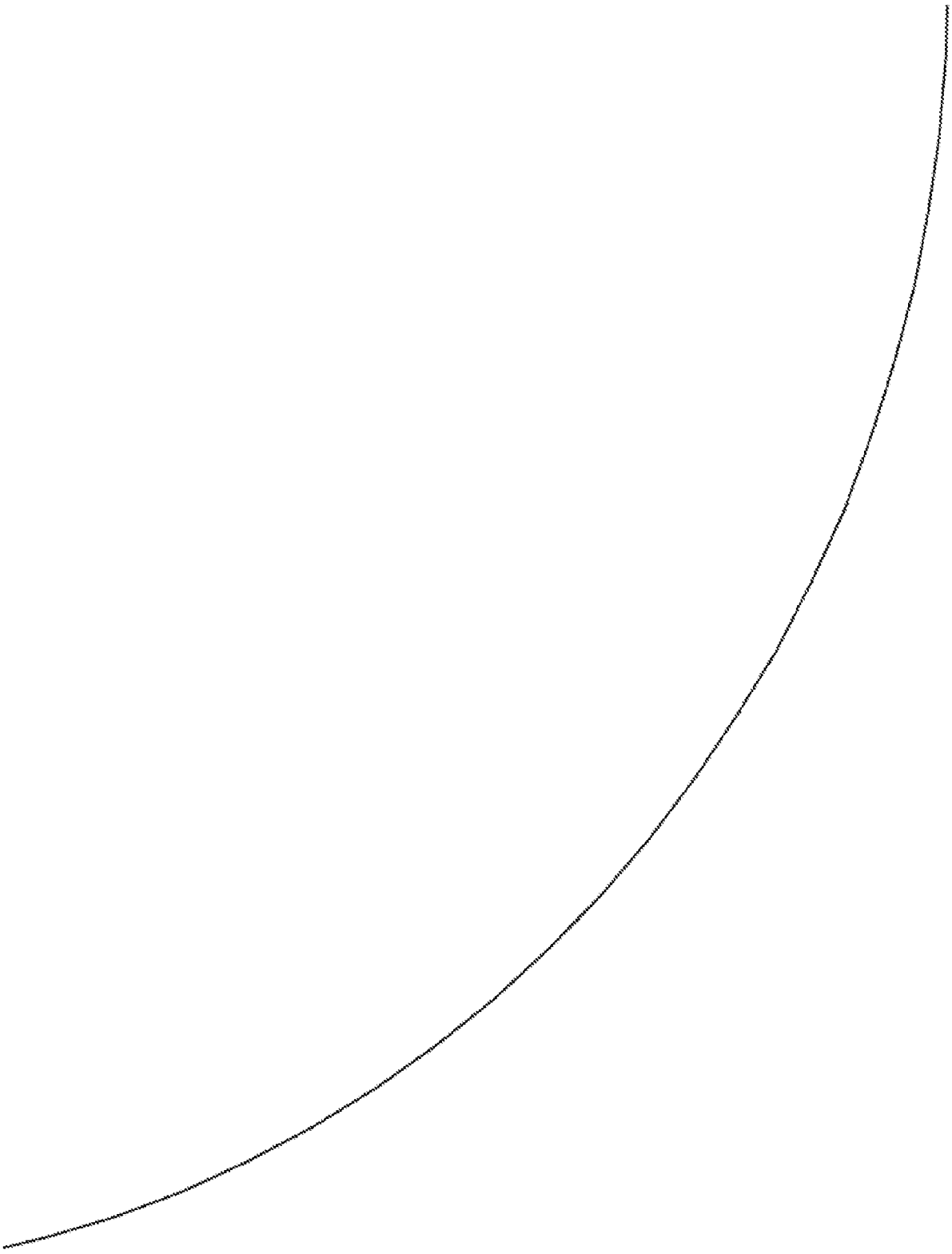


FIG. 52m

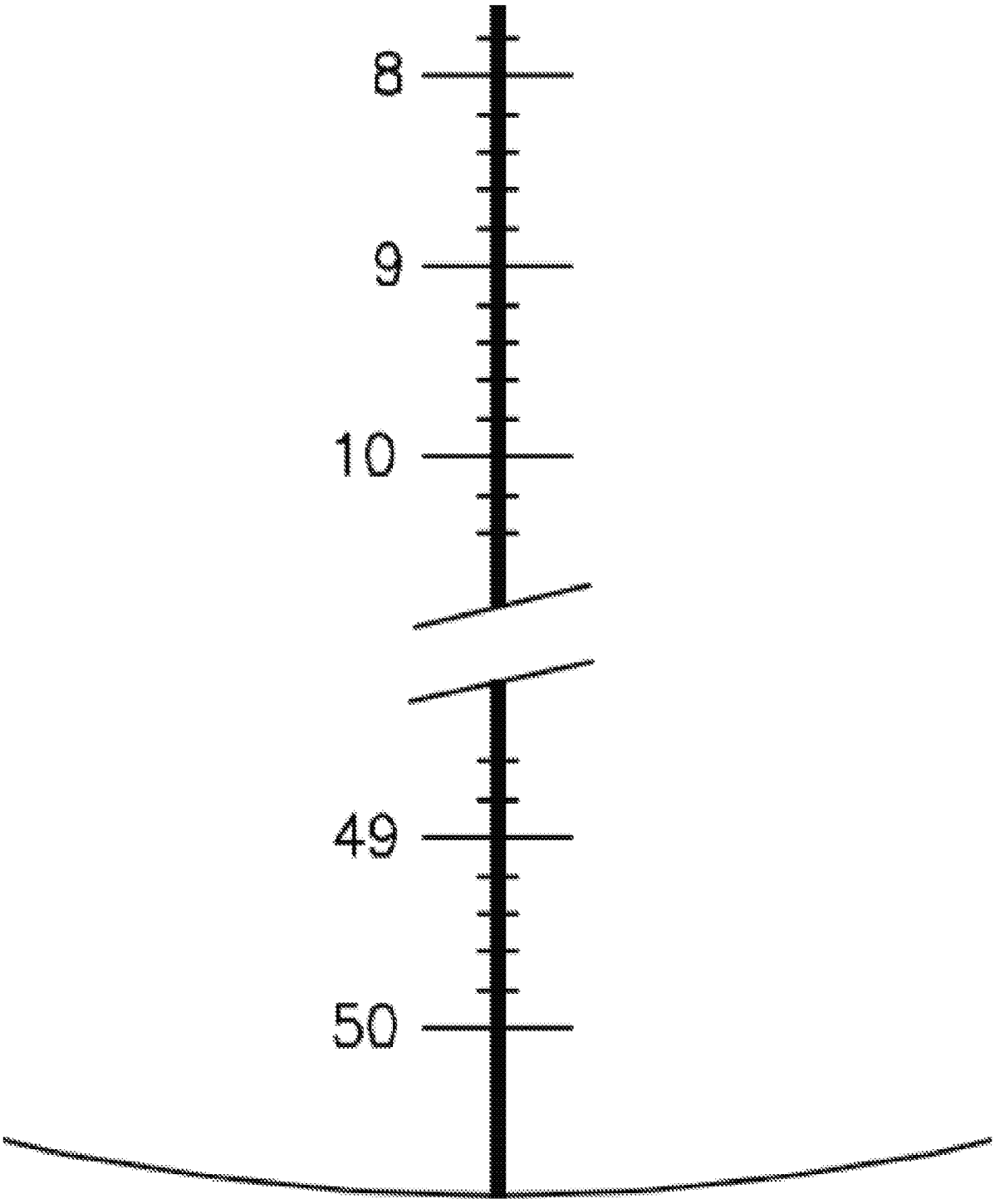


FIG. 52n

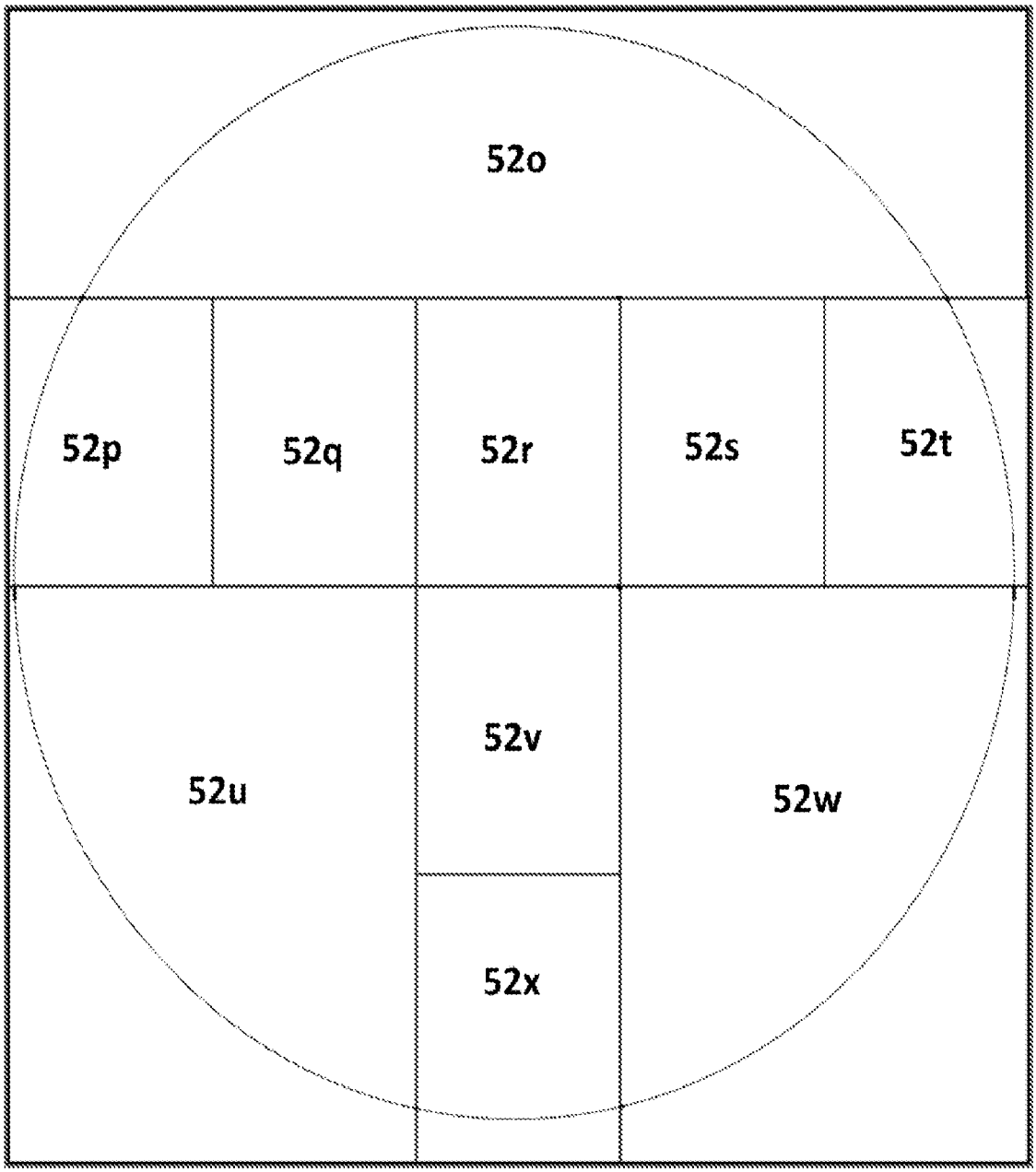


FIG. 52o

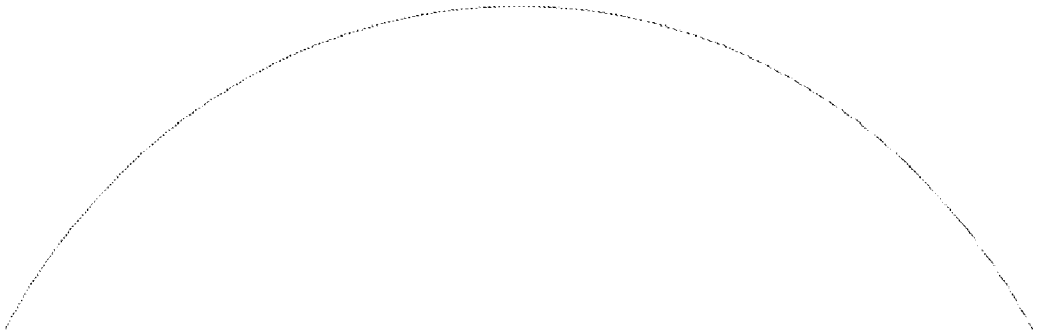


FIG. 52p

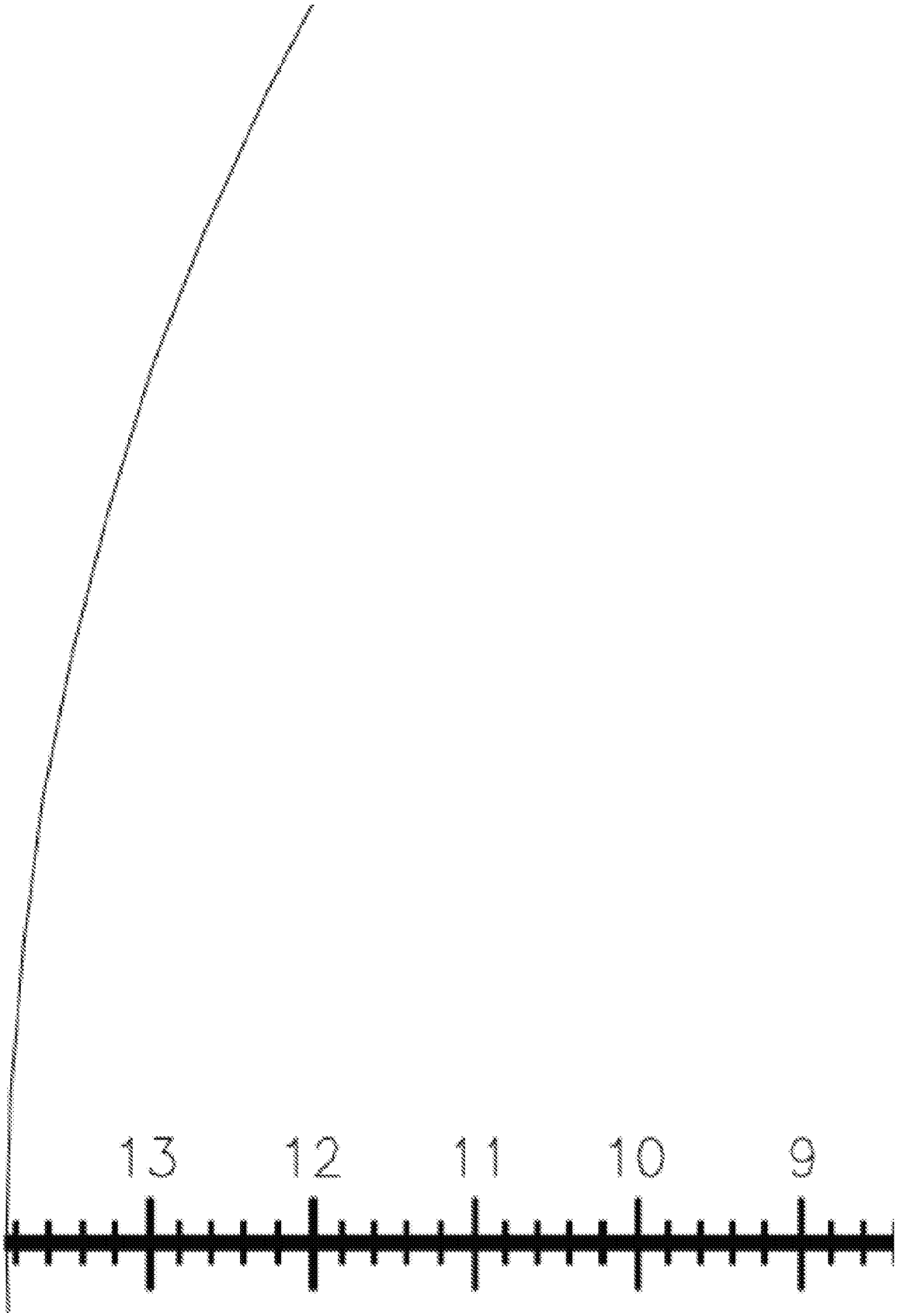


FIG. 52q

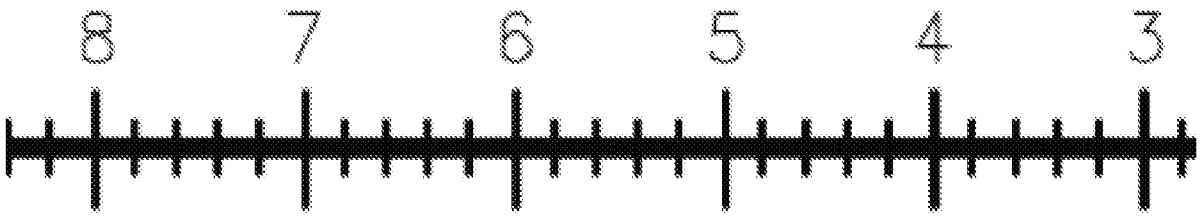


FIG. 52r

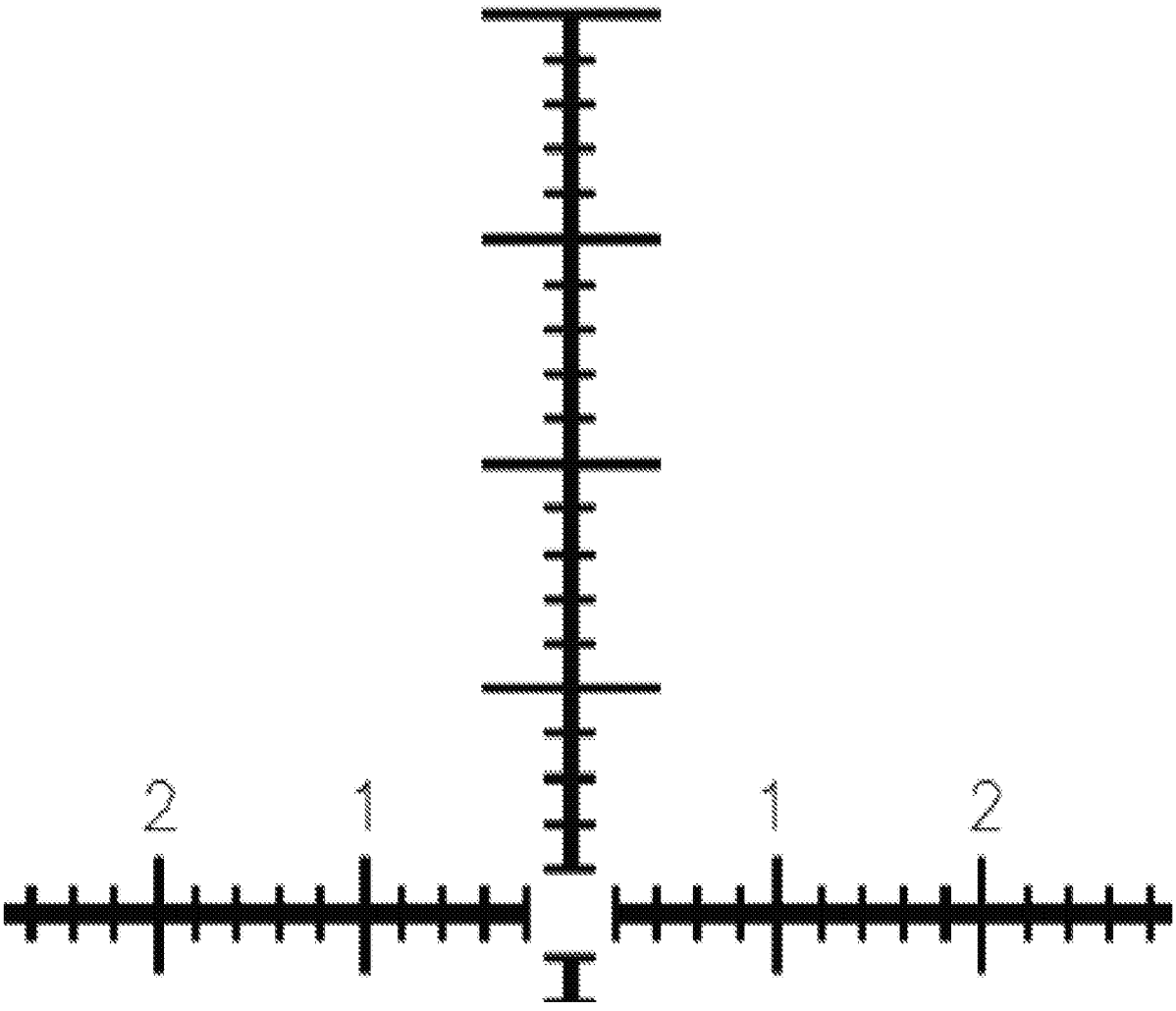


FIG. 52s

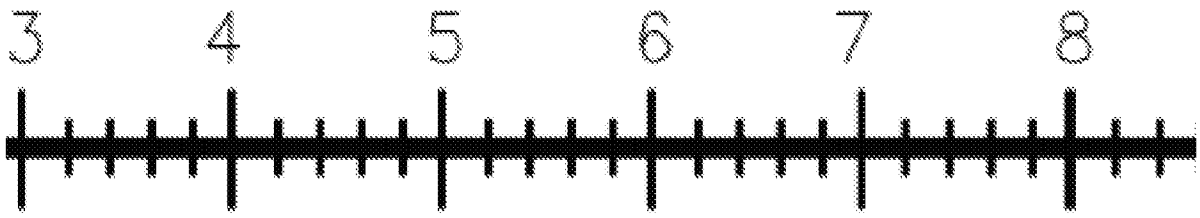


FIG. 52t

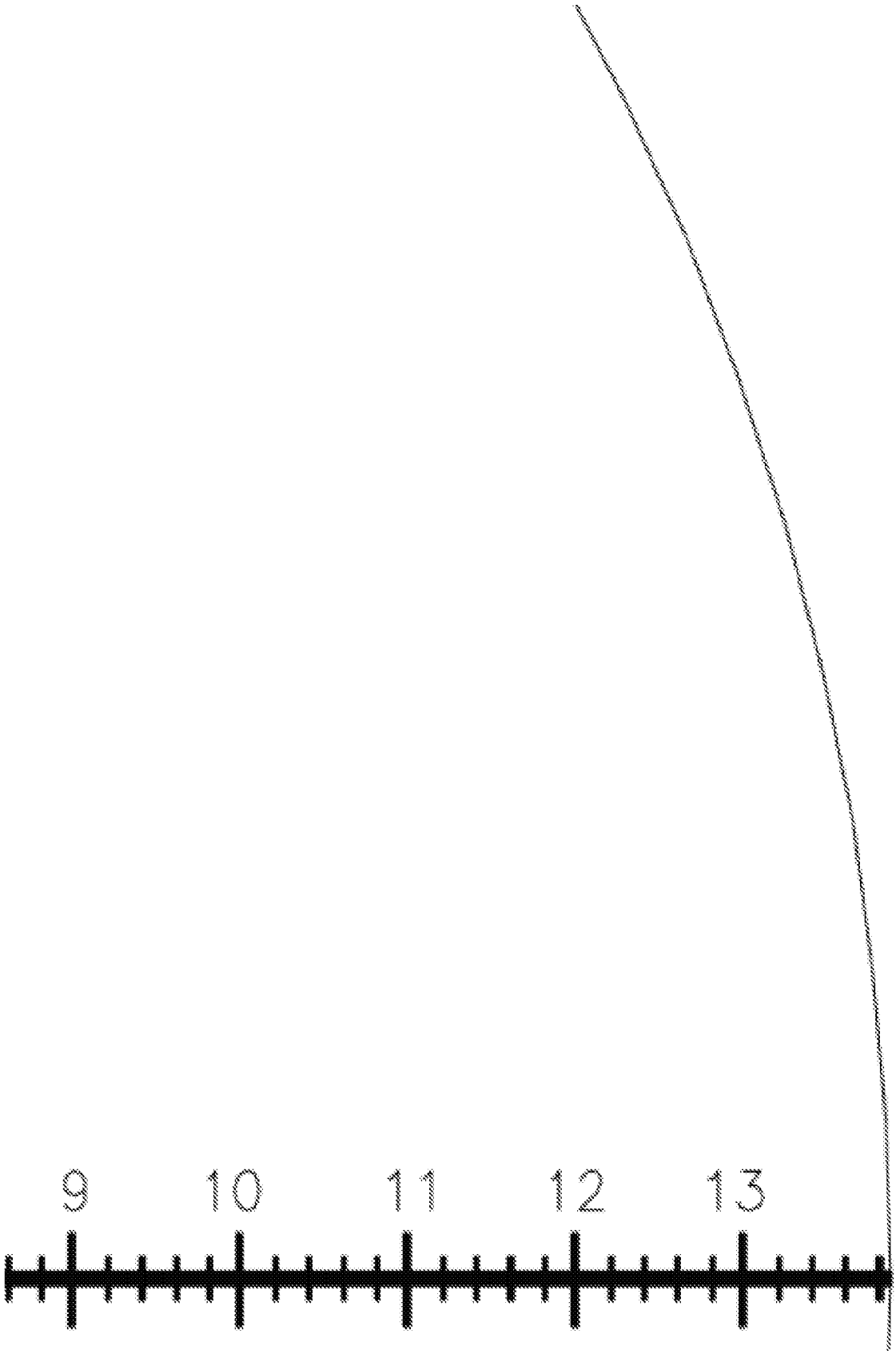


FIG. 52u

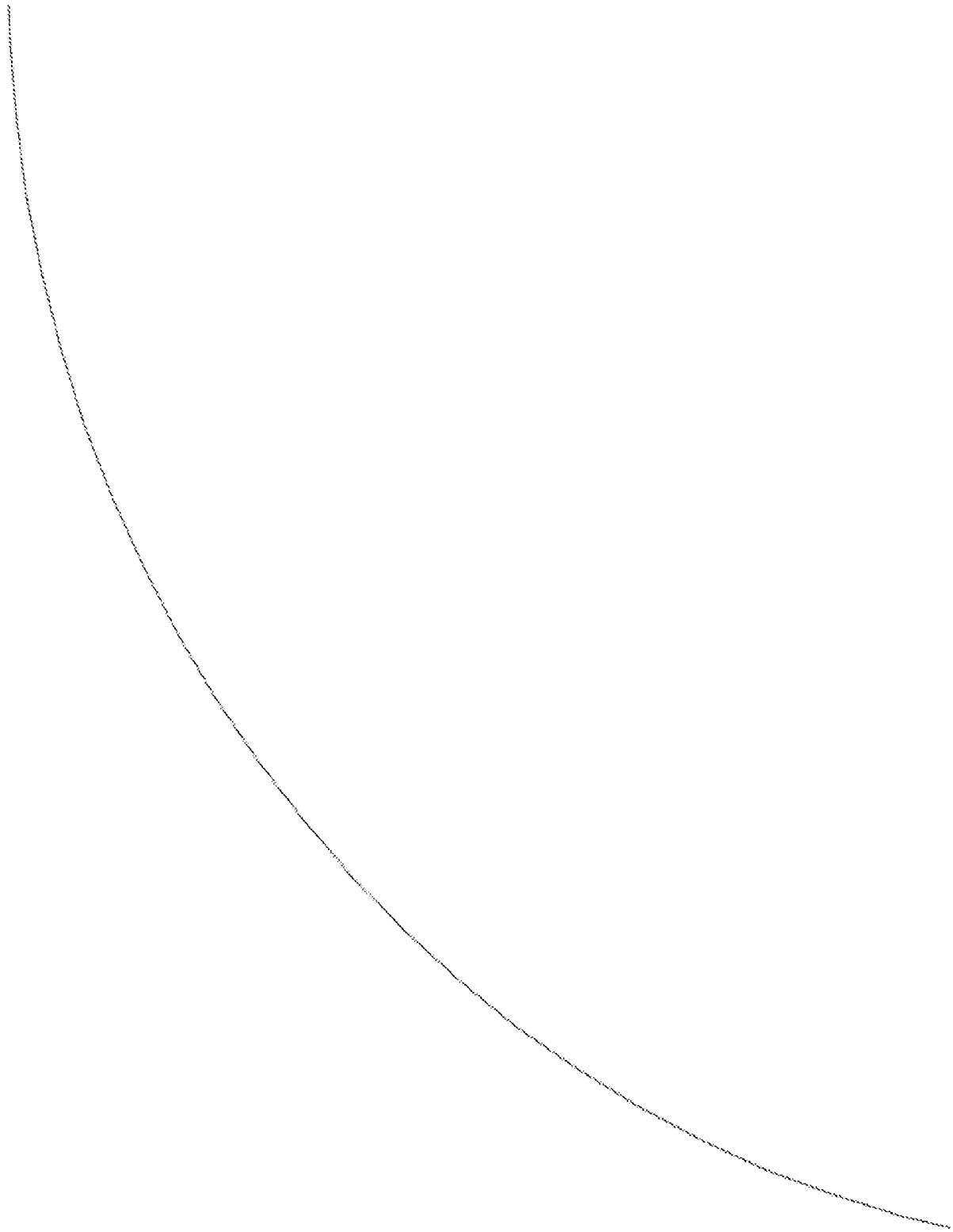


FIG. 52v

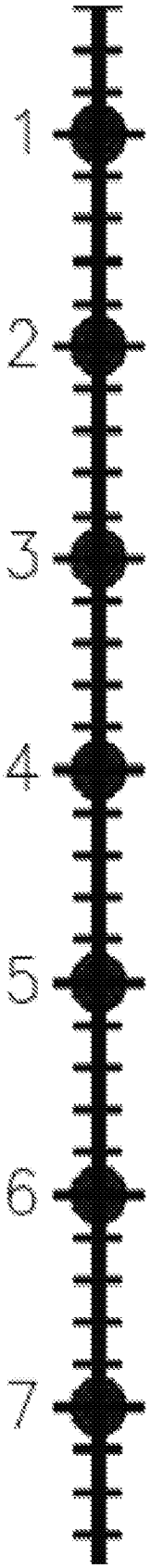


FIG. 52w

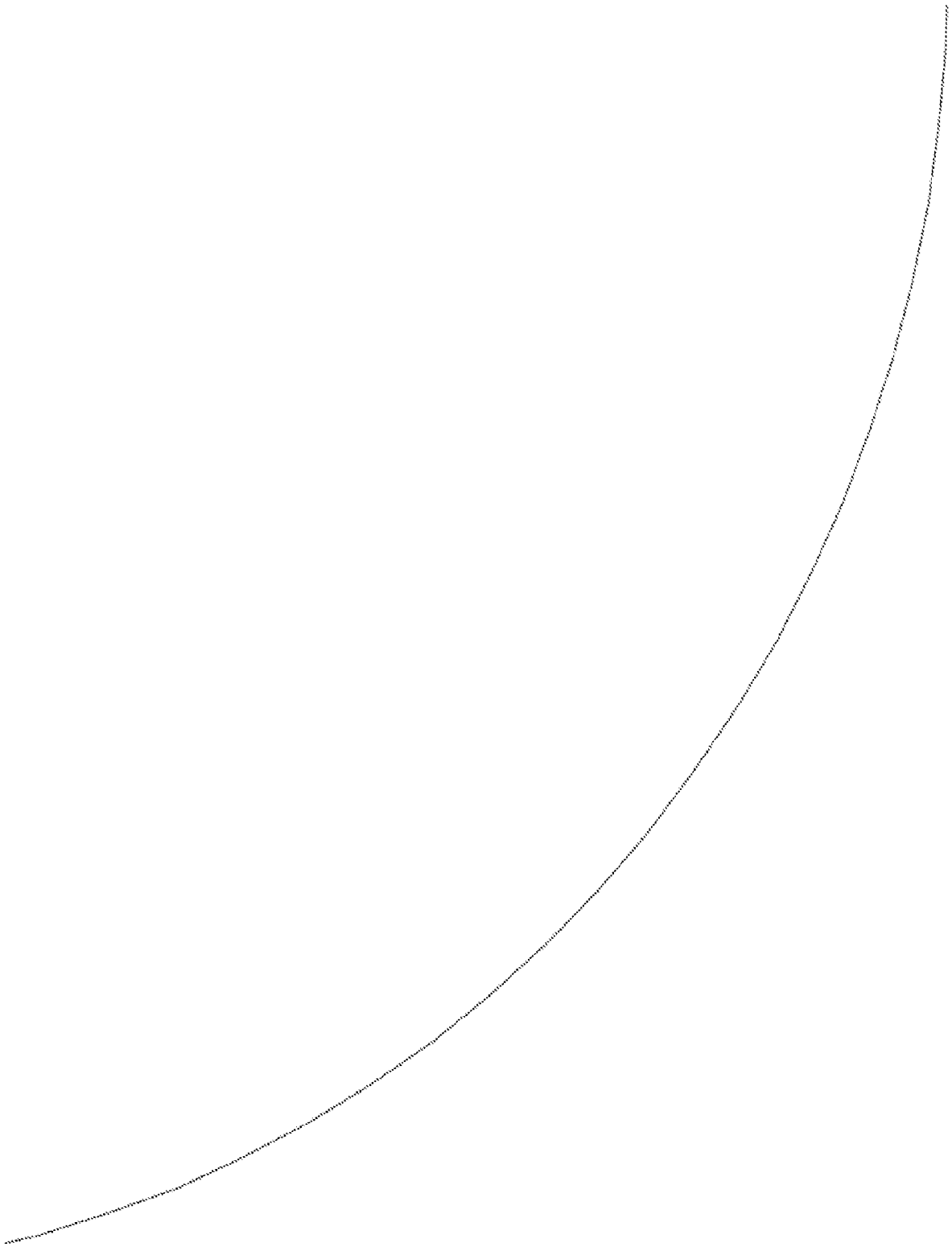


FIG. 52x

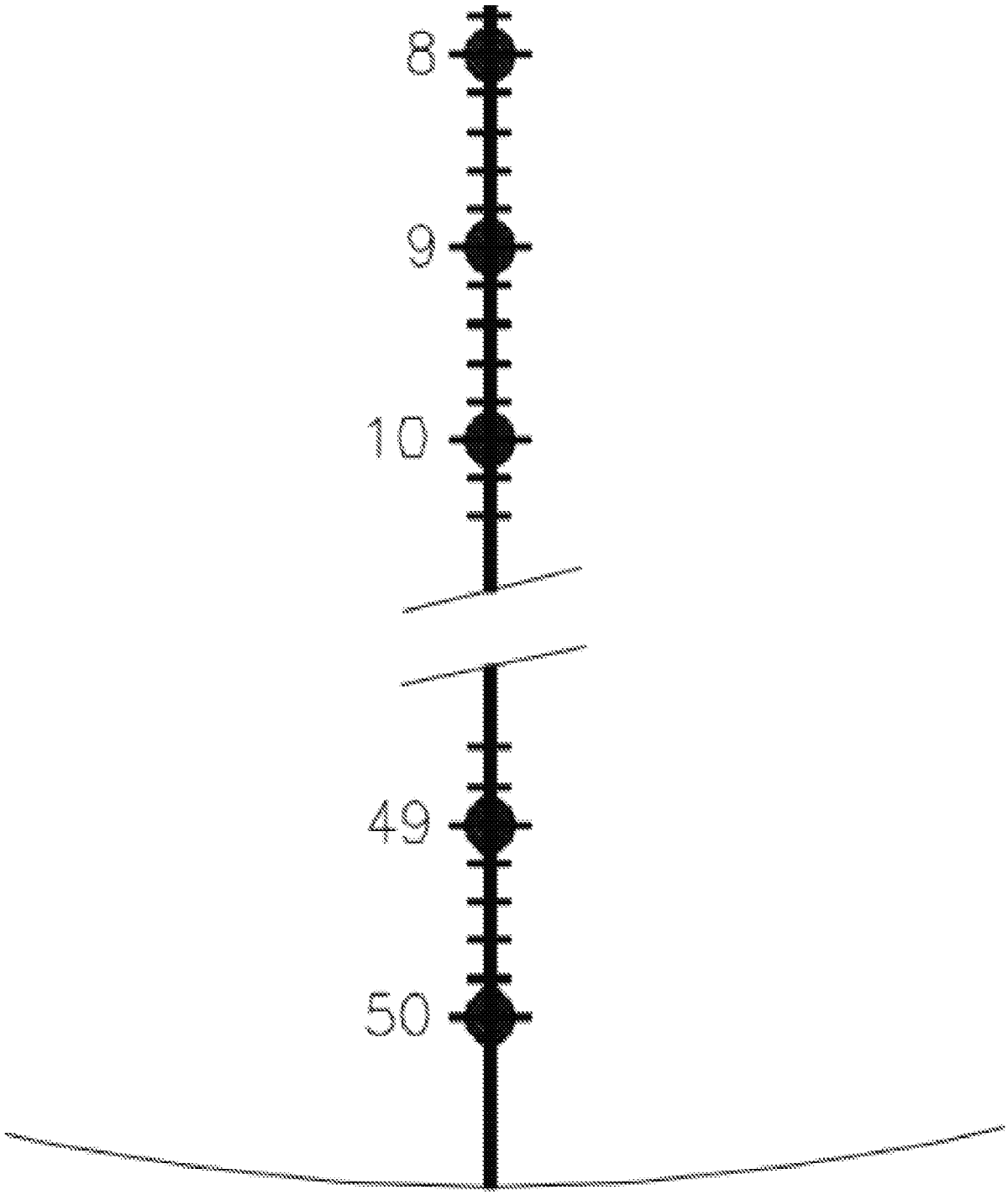


FIG. 52y

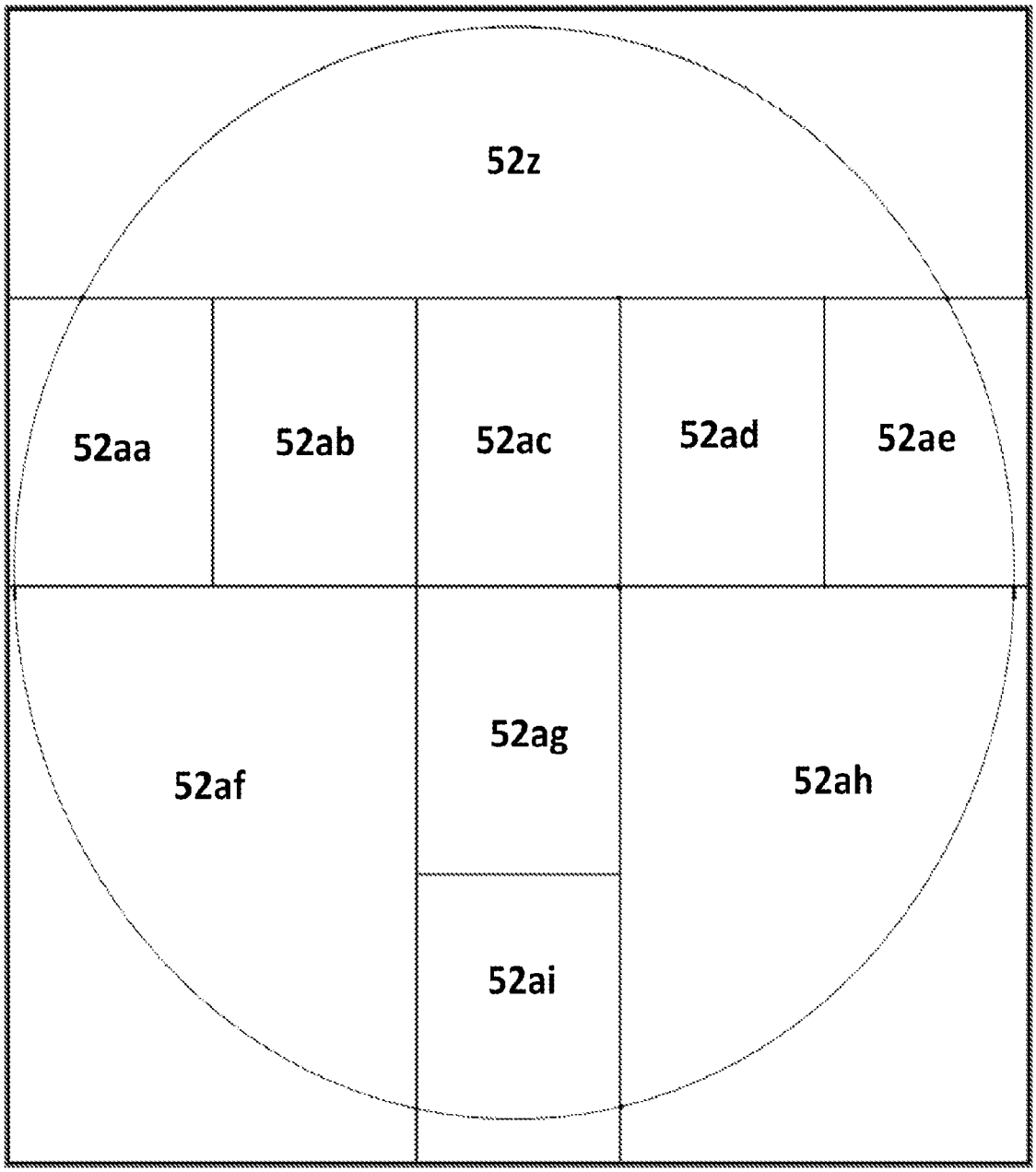


FIG. 52z

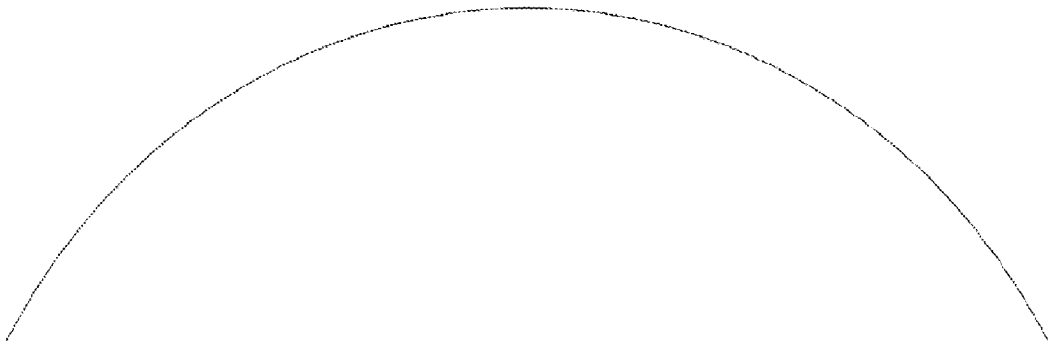


FIG. 52aa

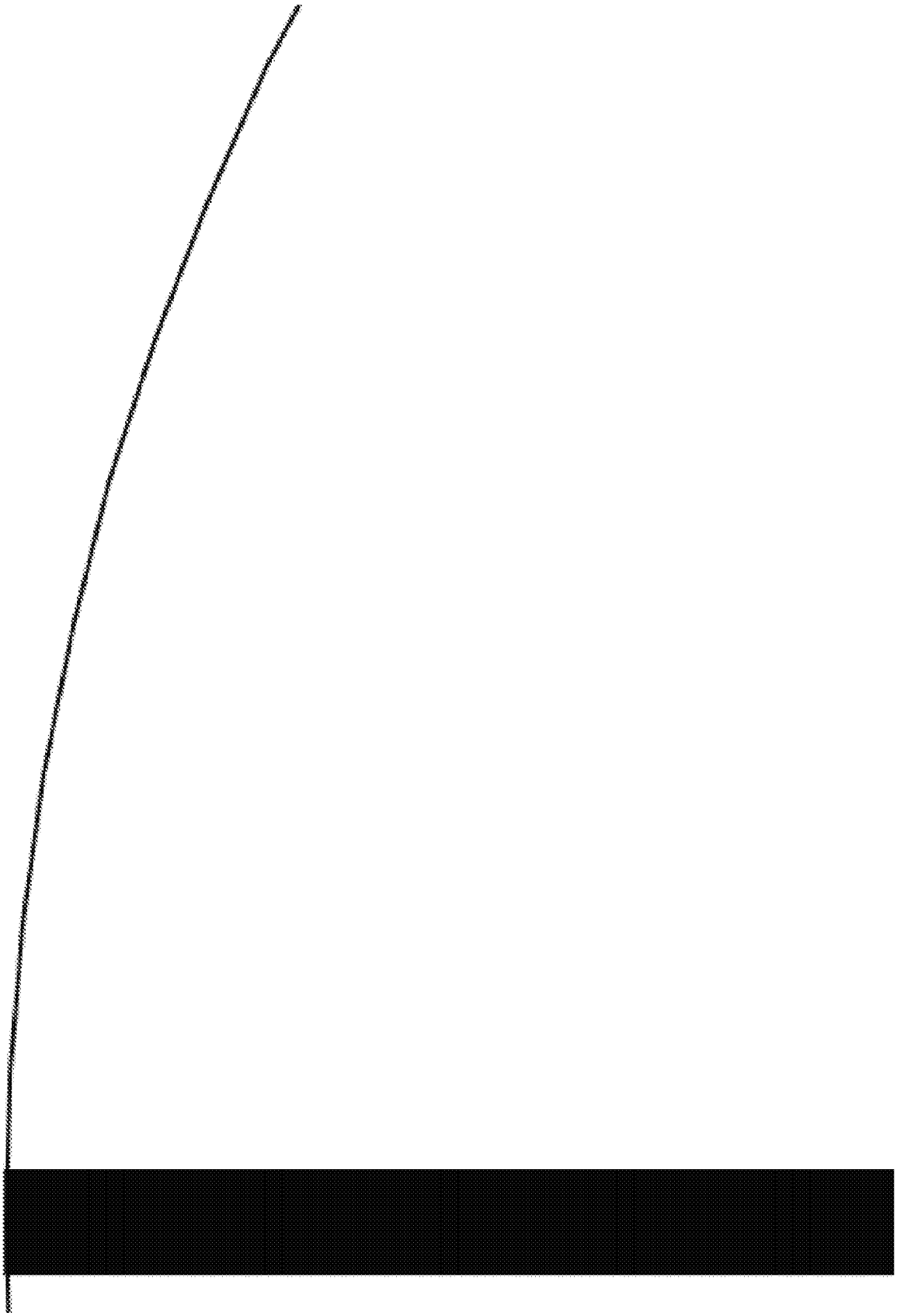


FIG. 52ab



FIG. 52ac

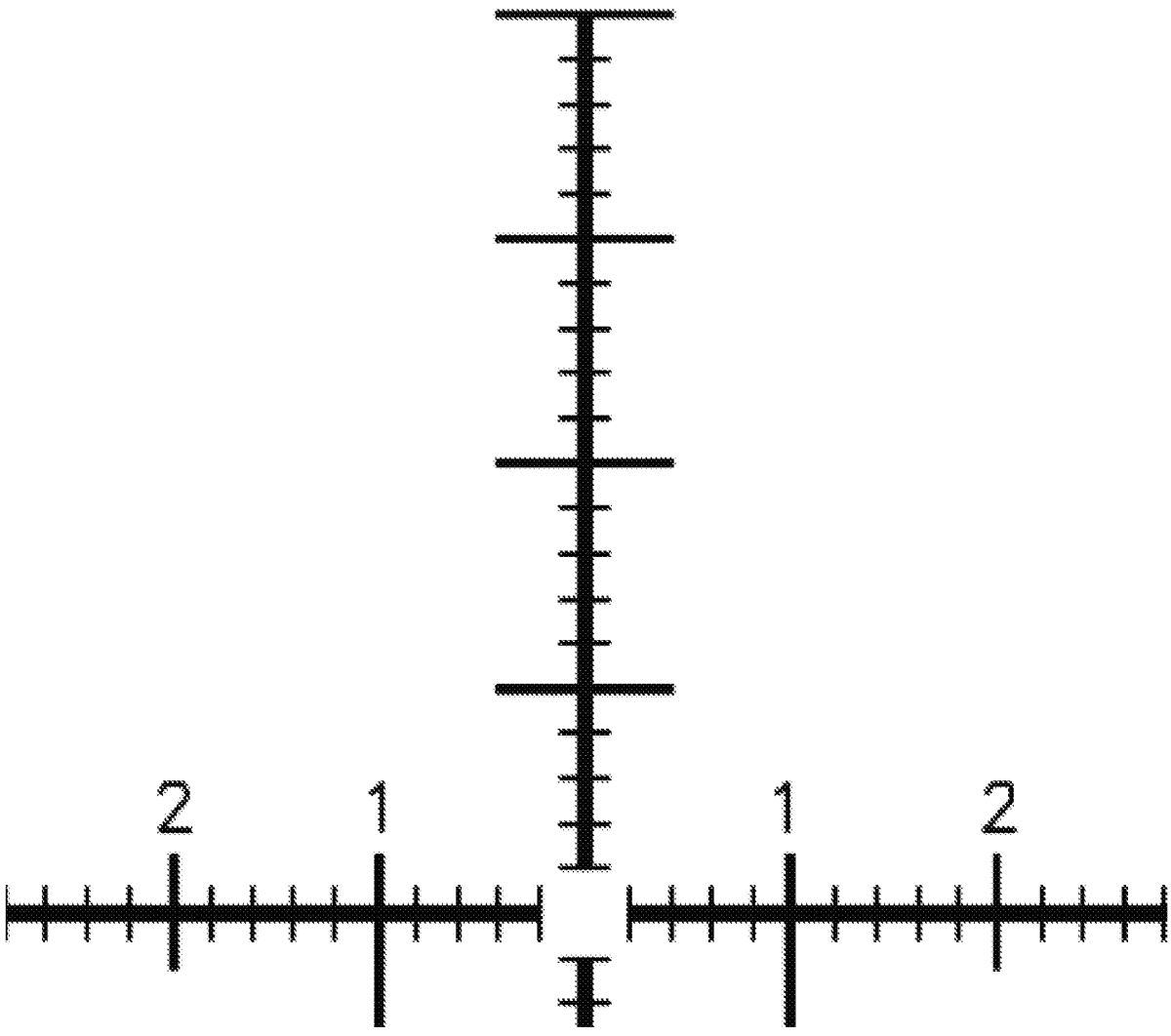


FIG. 52ad



FIG. 52ae

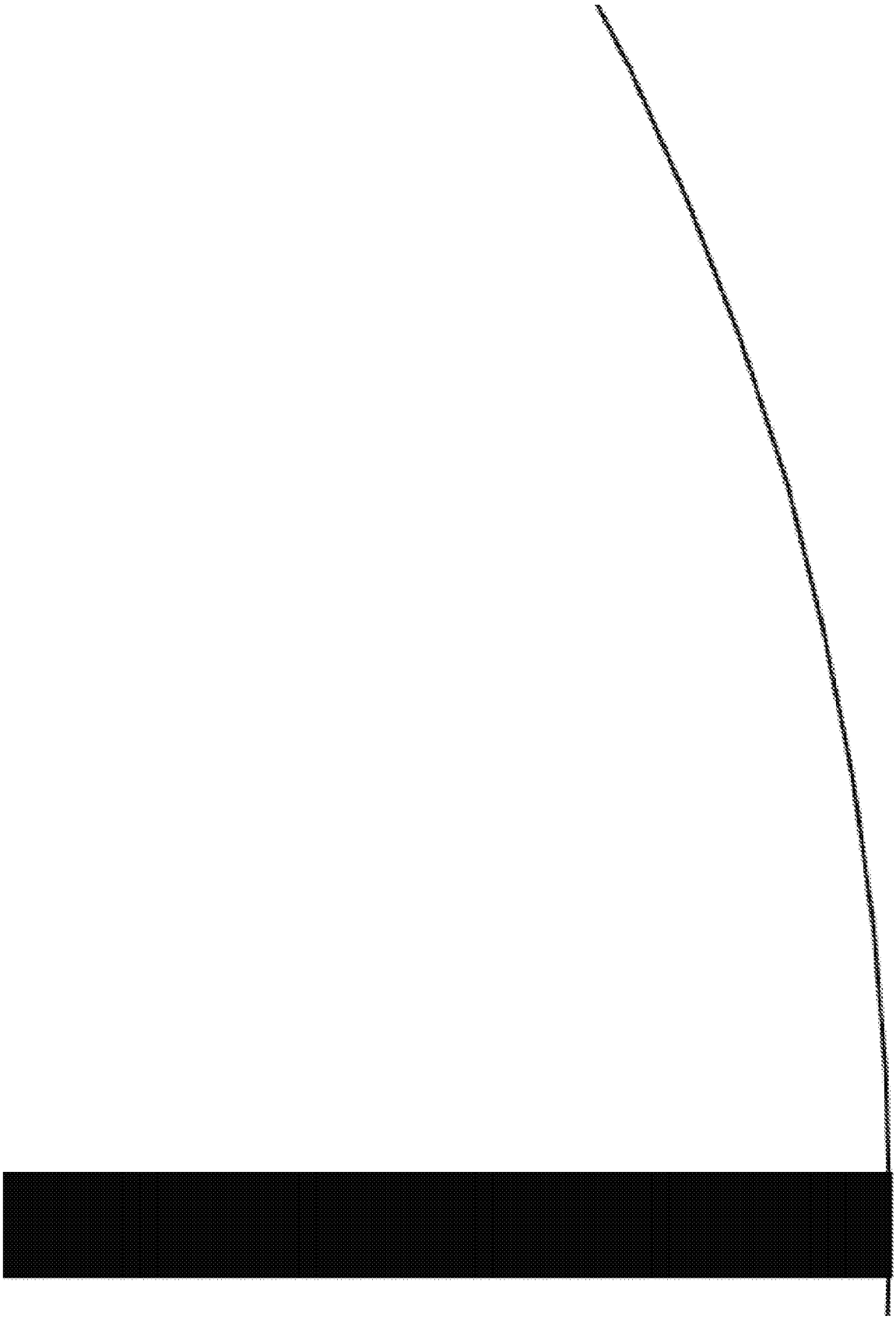


FIG. 52af

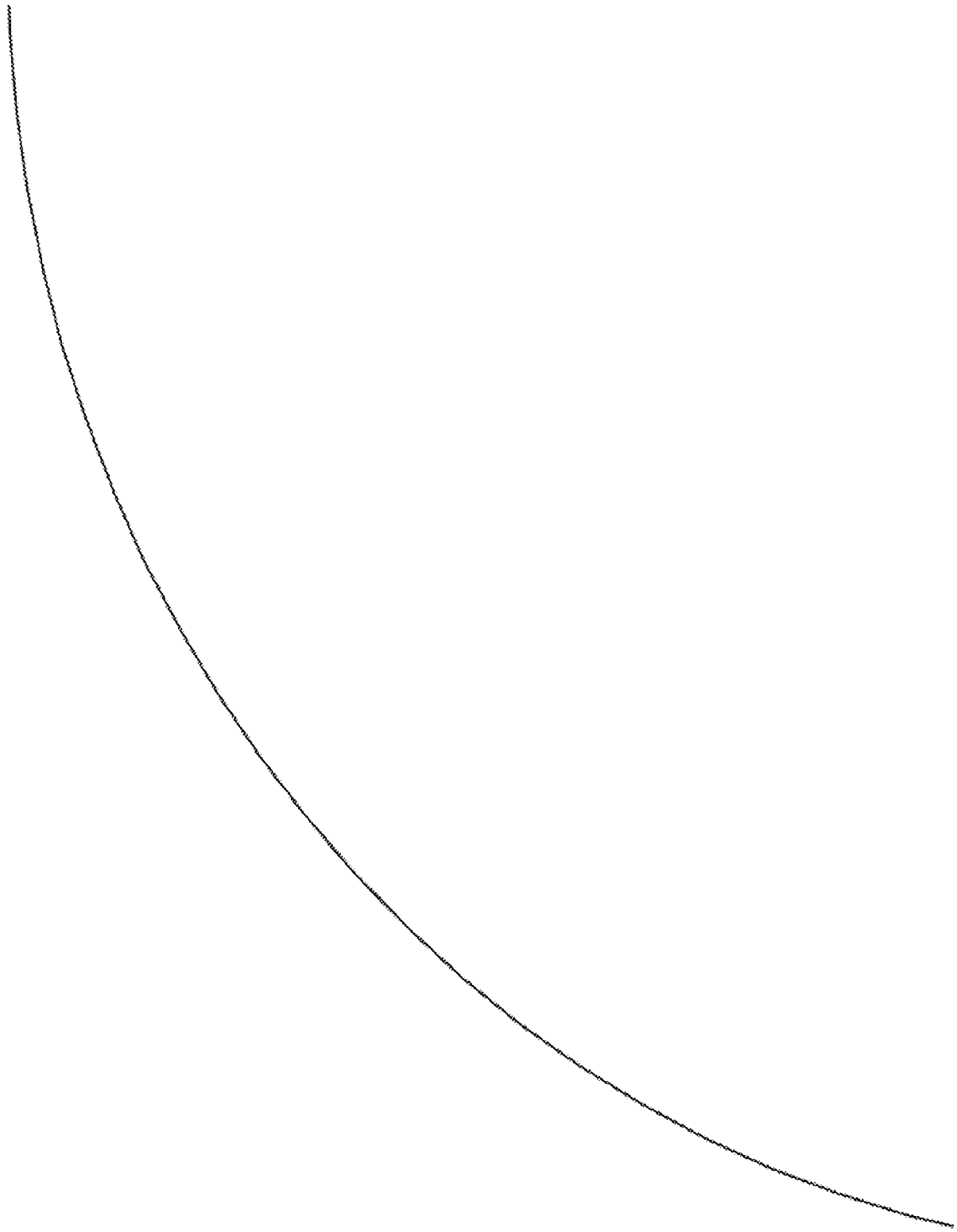


FIG. 52ag

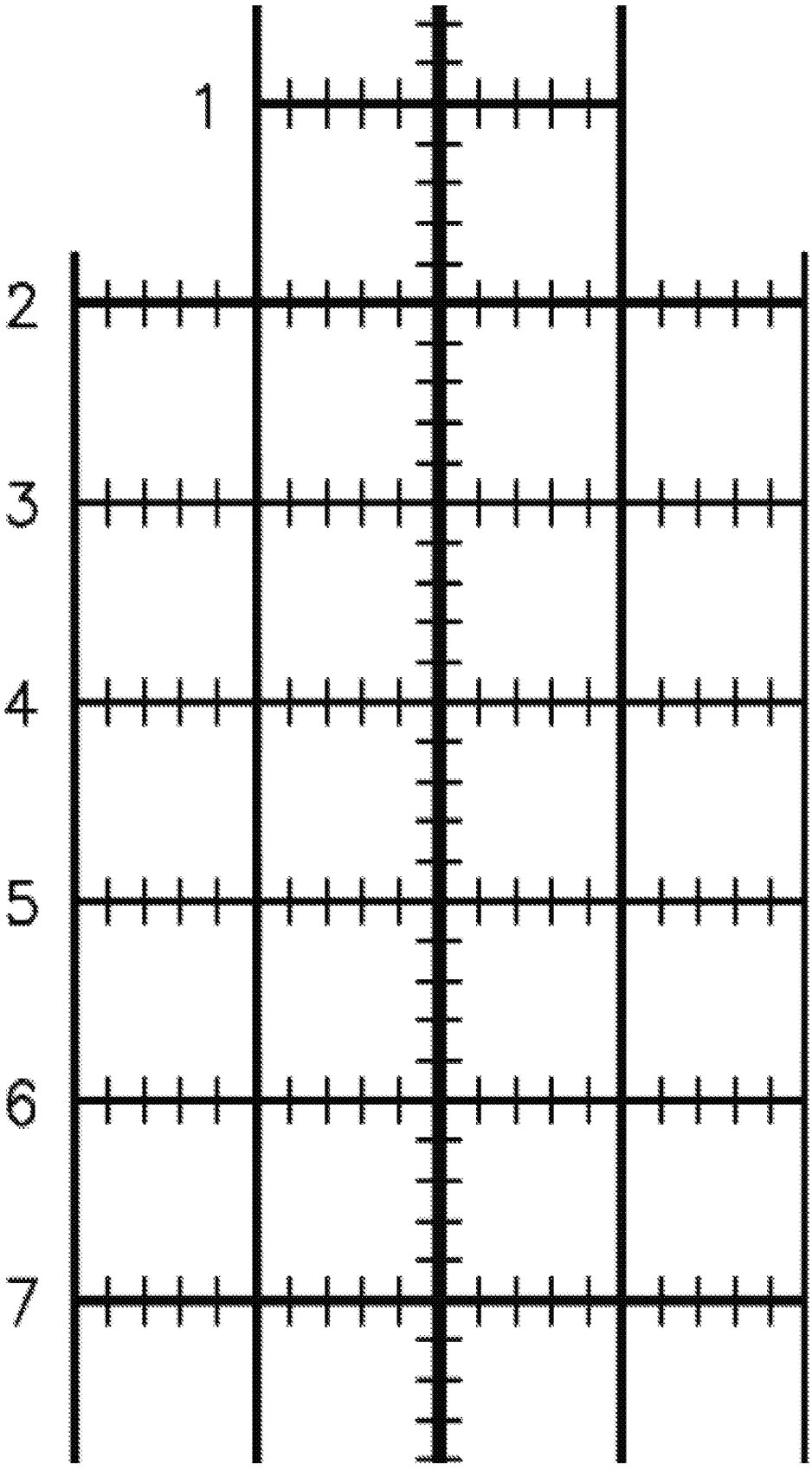


FIG. 52ah

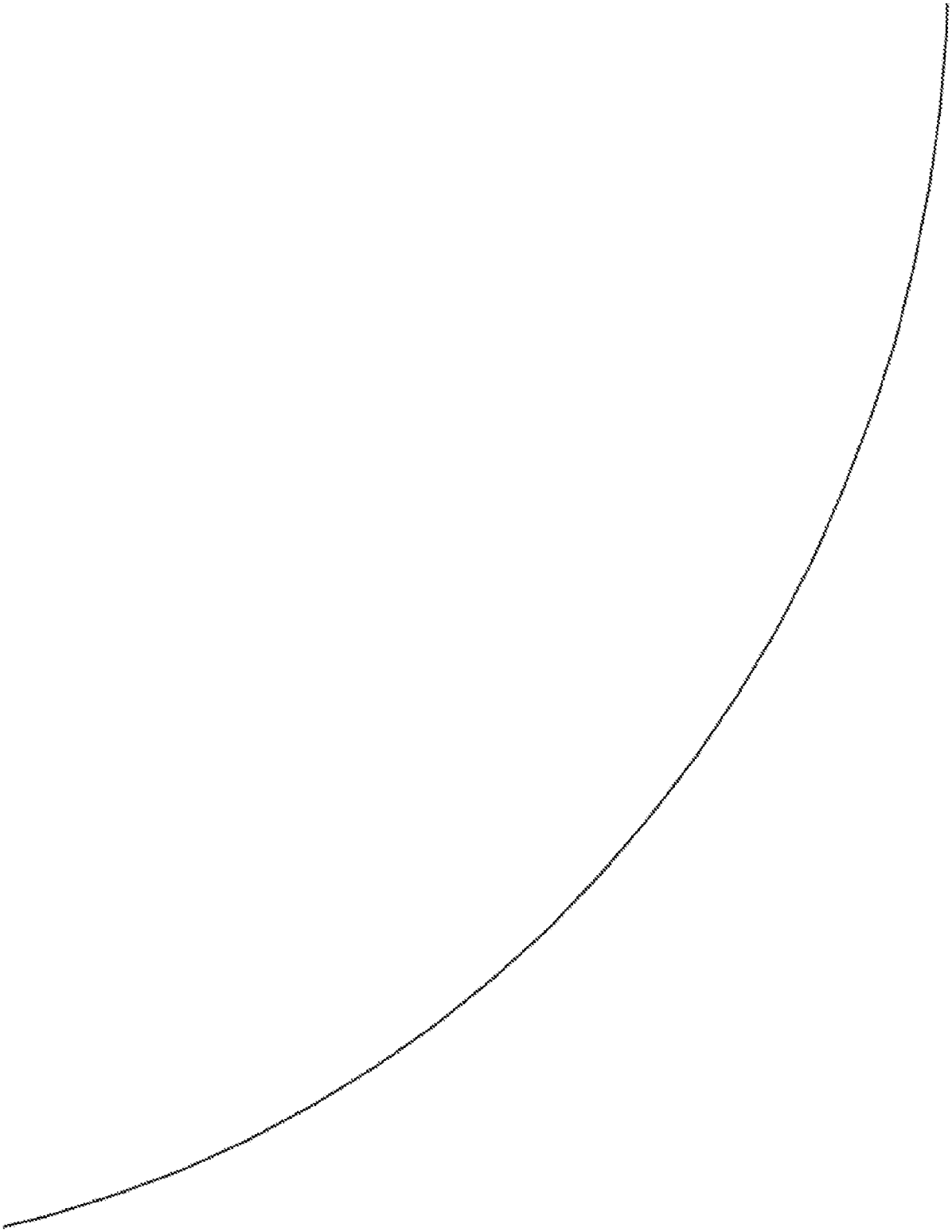


FIG. 52ai

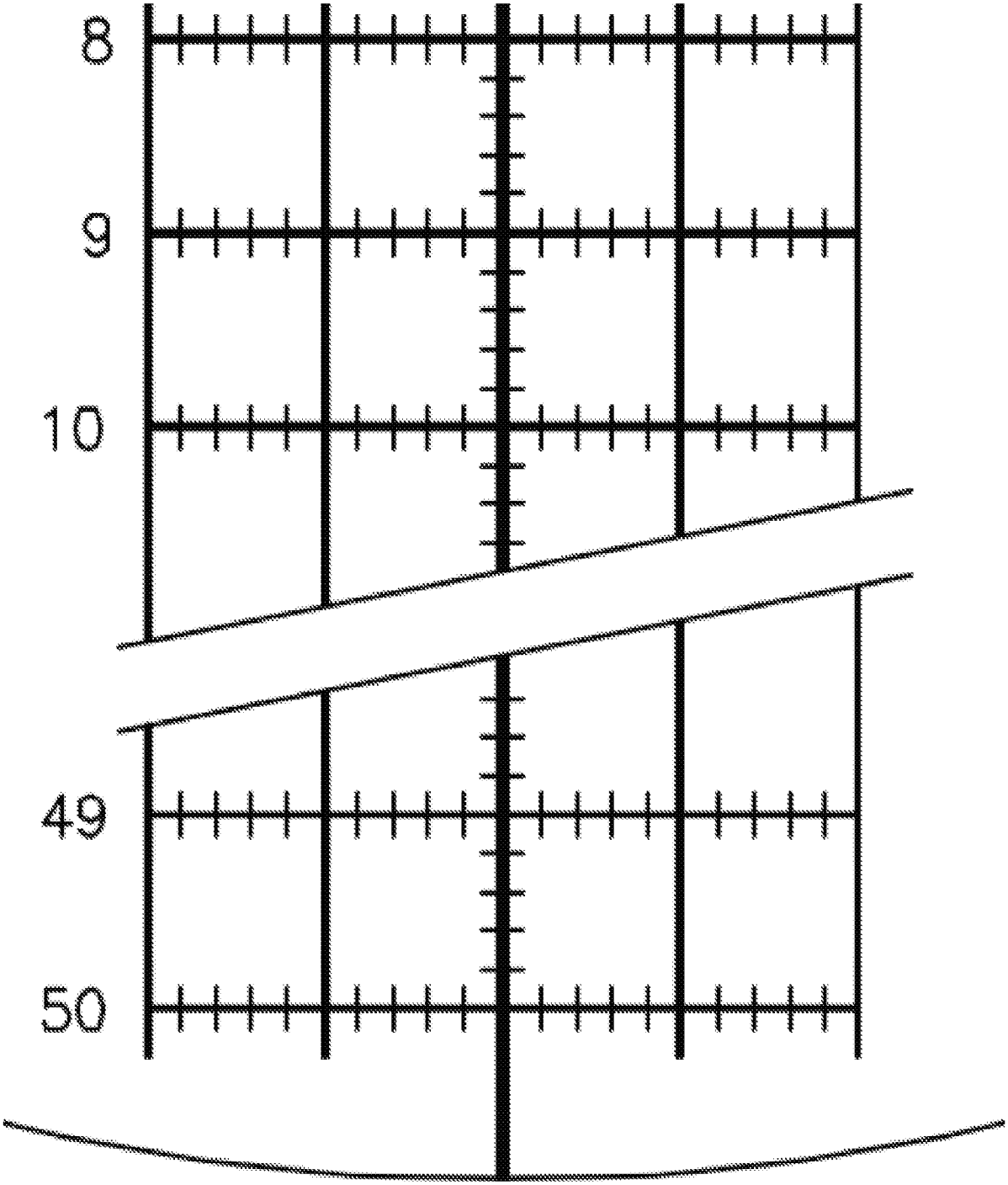


FIG. 52aj

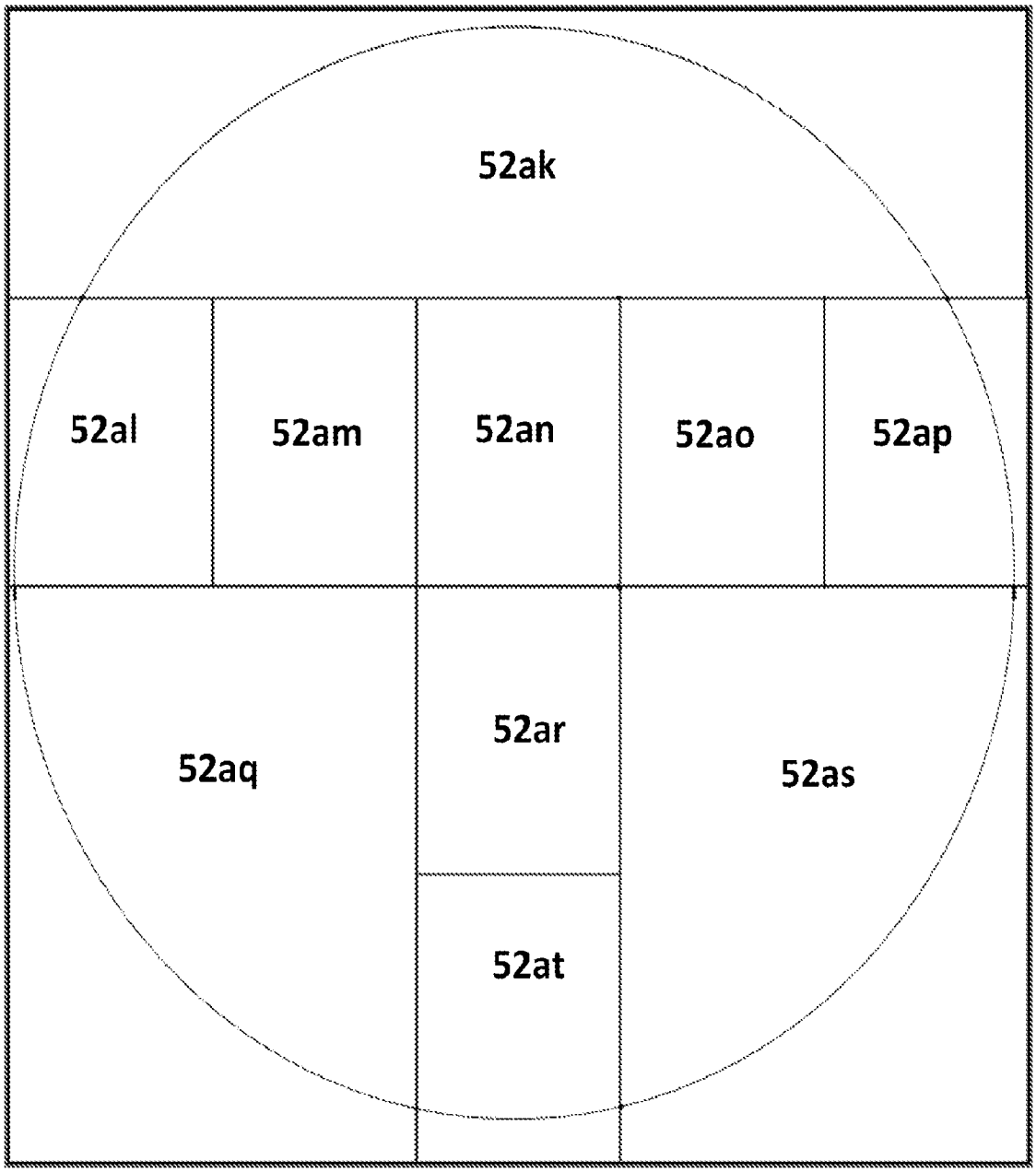


FIG. 52ak

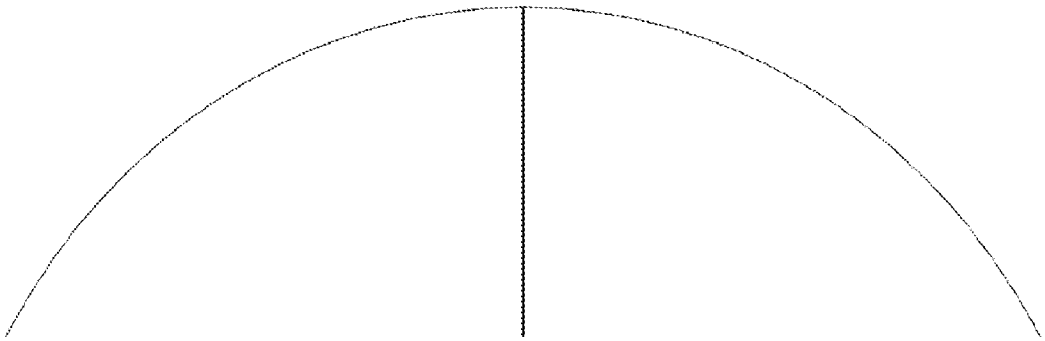


FIG. 52al

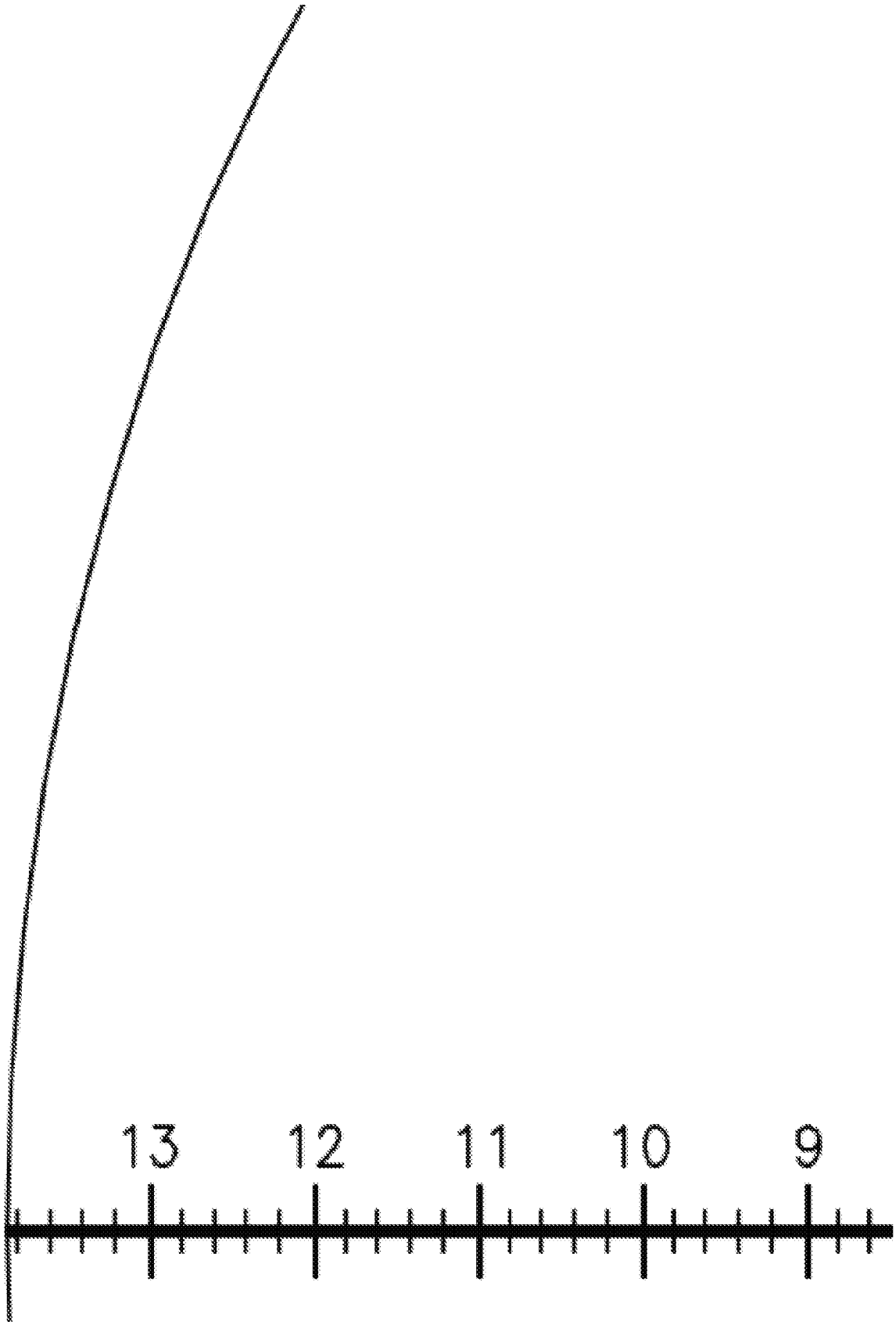


FIG. 52am

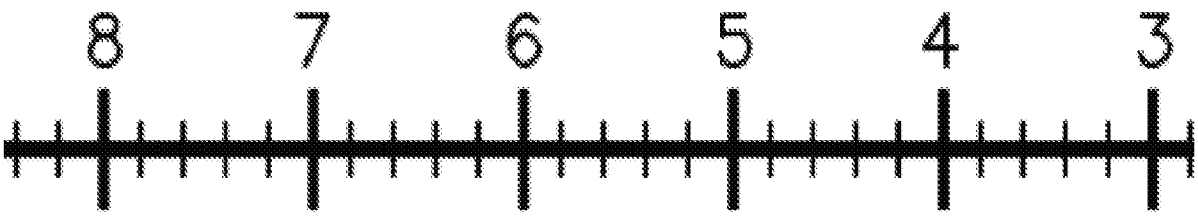


FIG. 52an

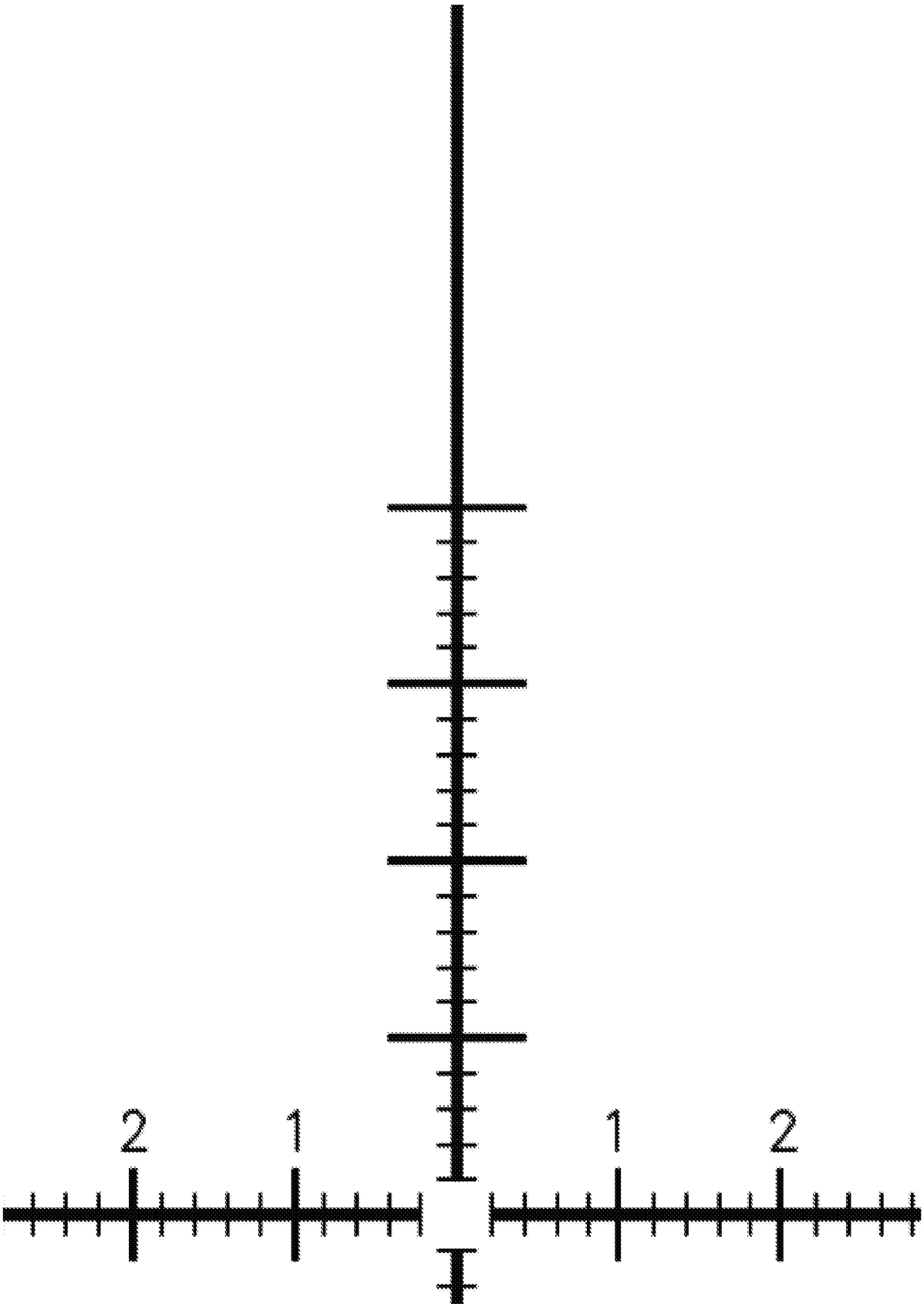


FIG. 52ao

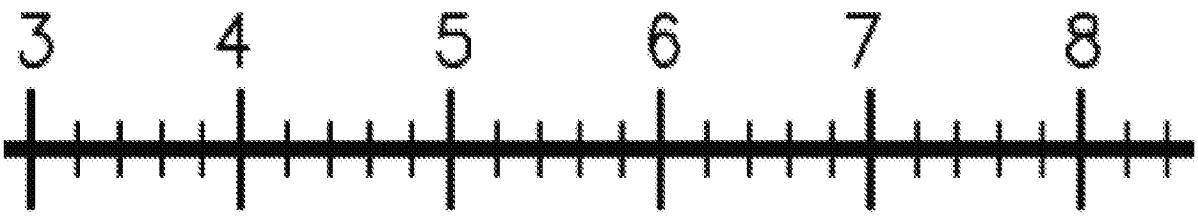


FIG. 52ap

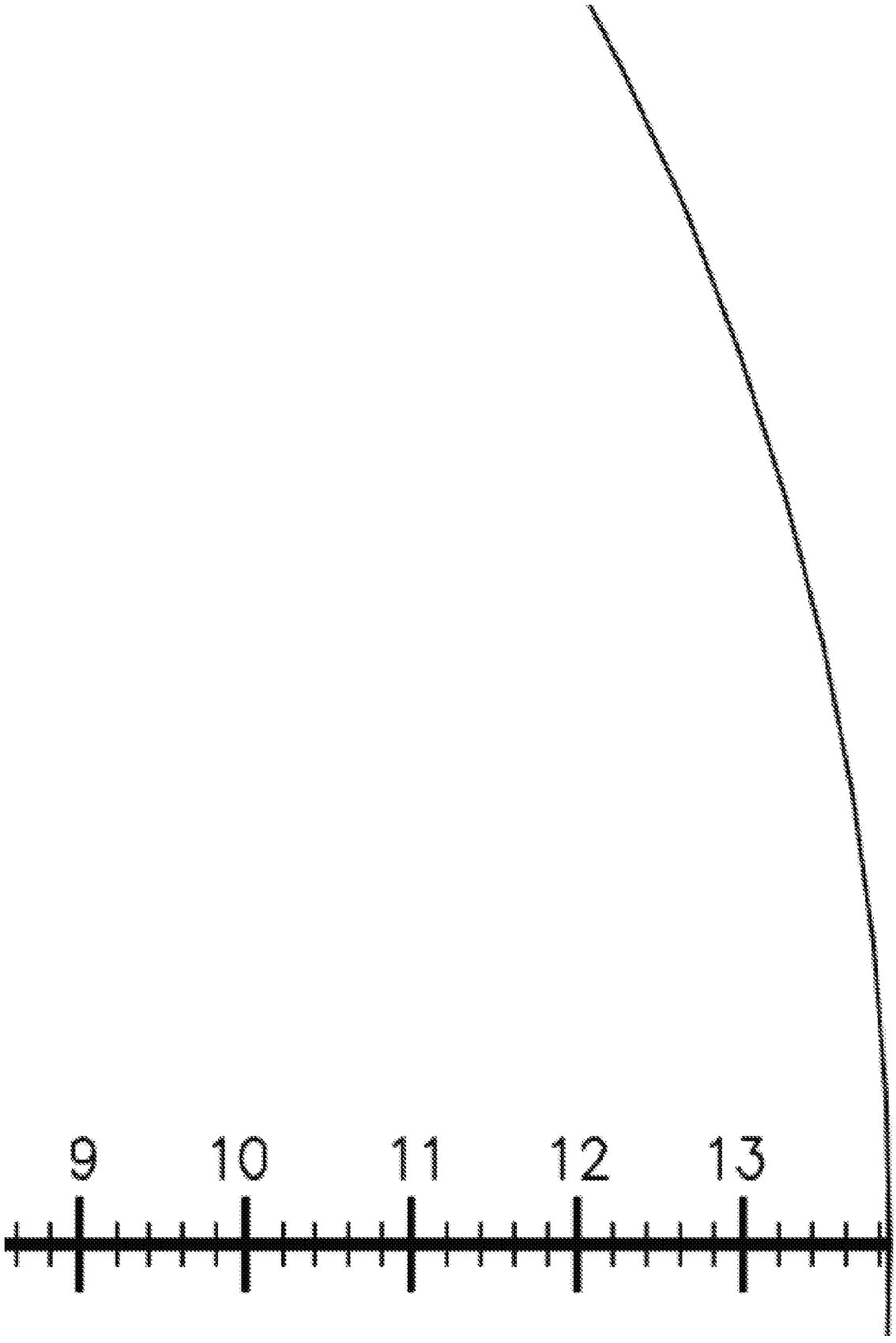


FIG. 52aq

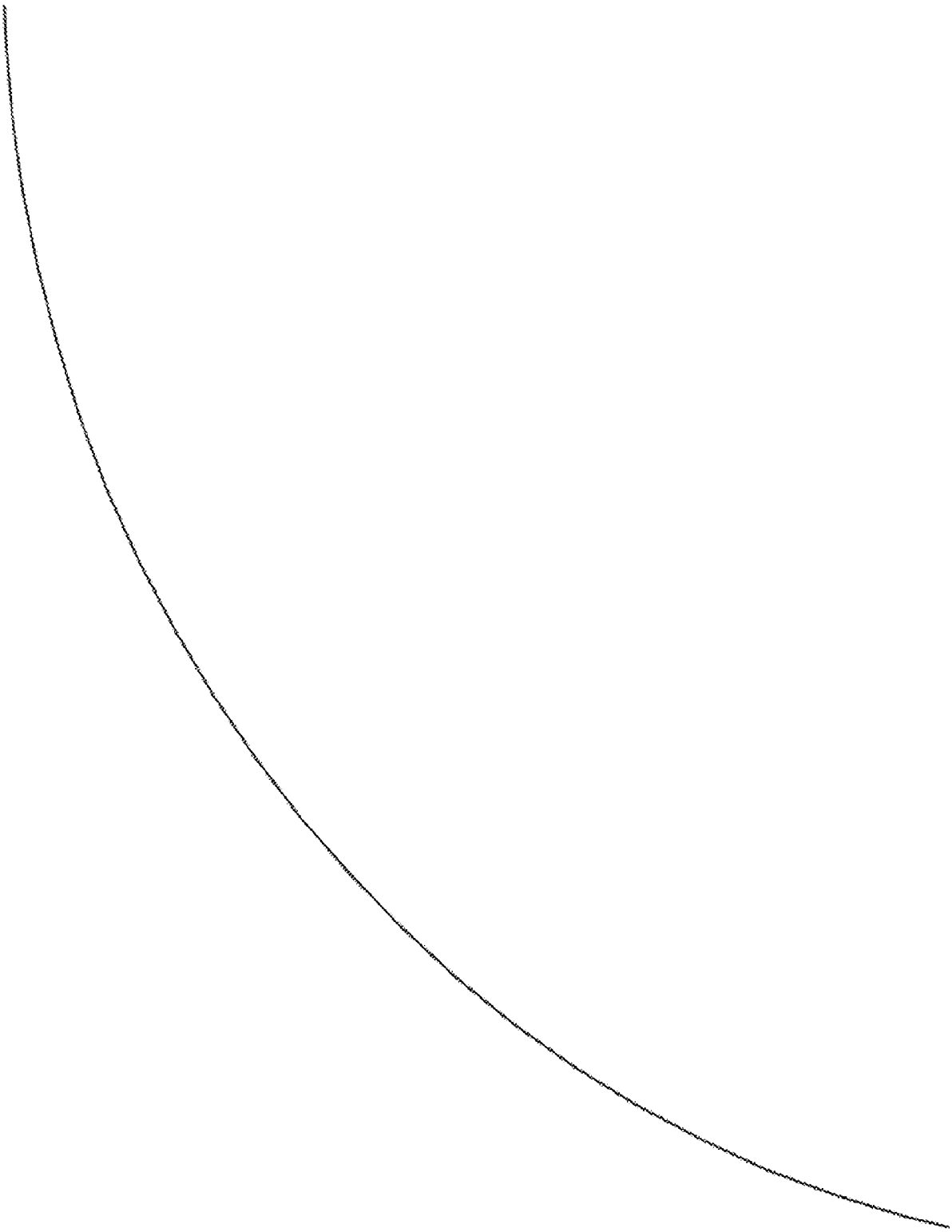


FIG. 52ar

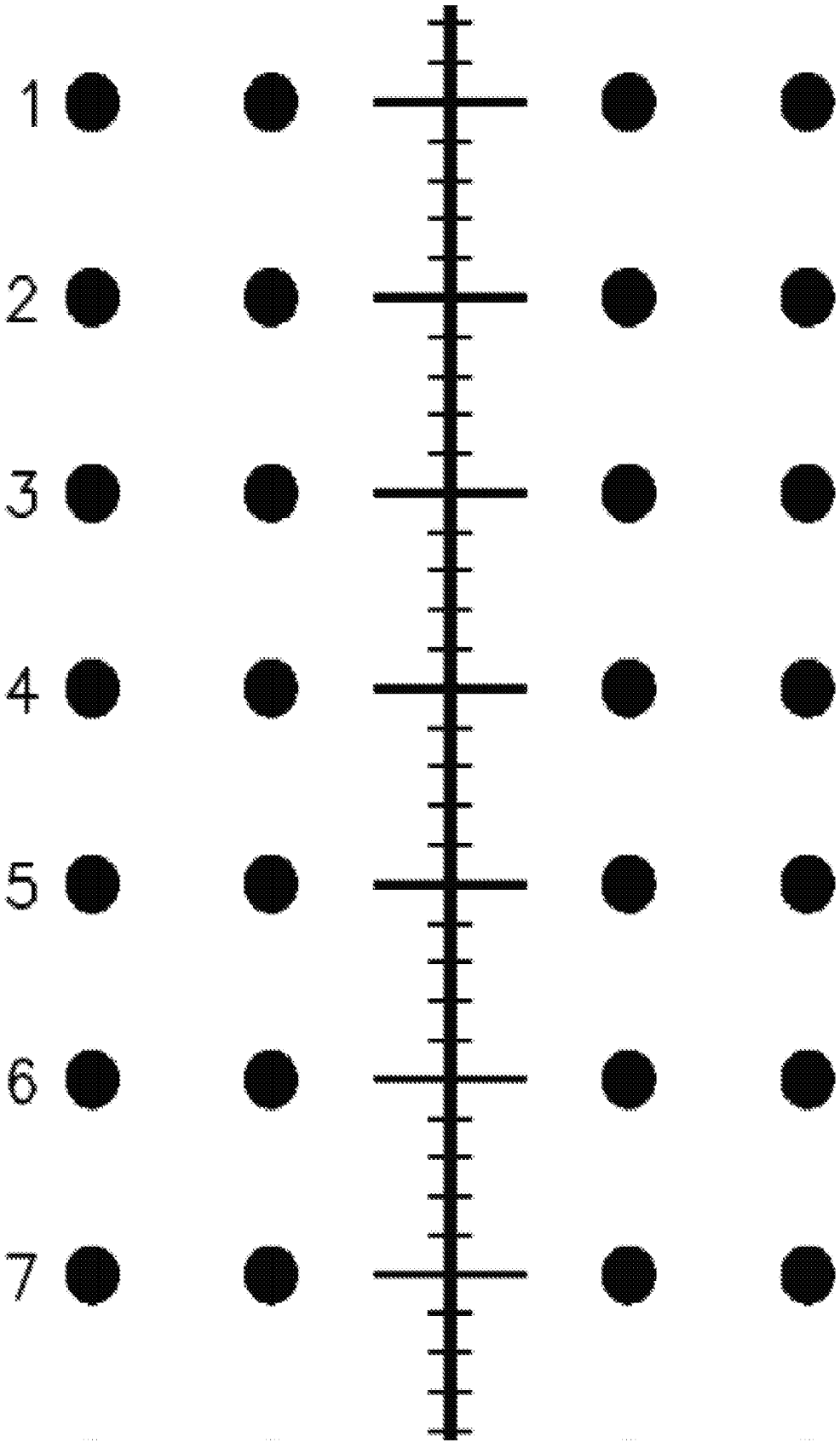


FIG. 52as

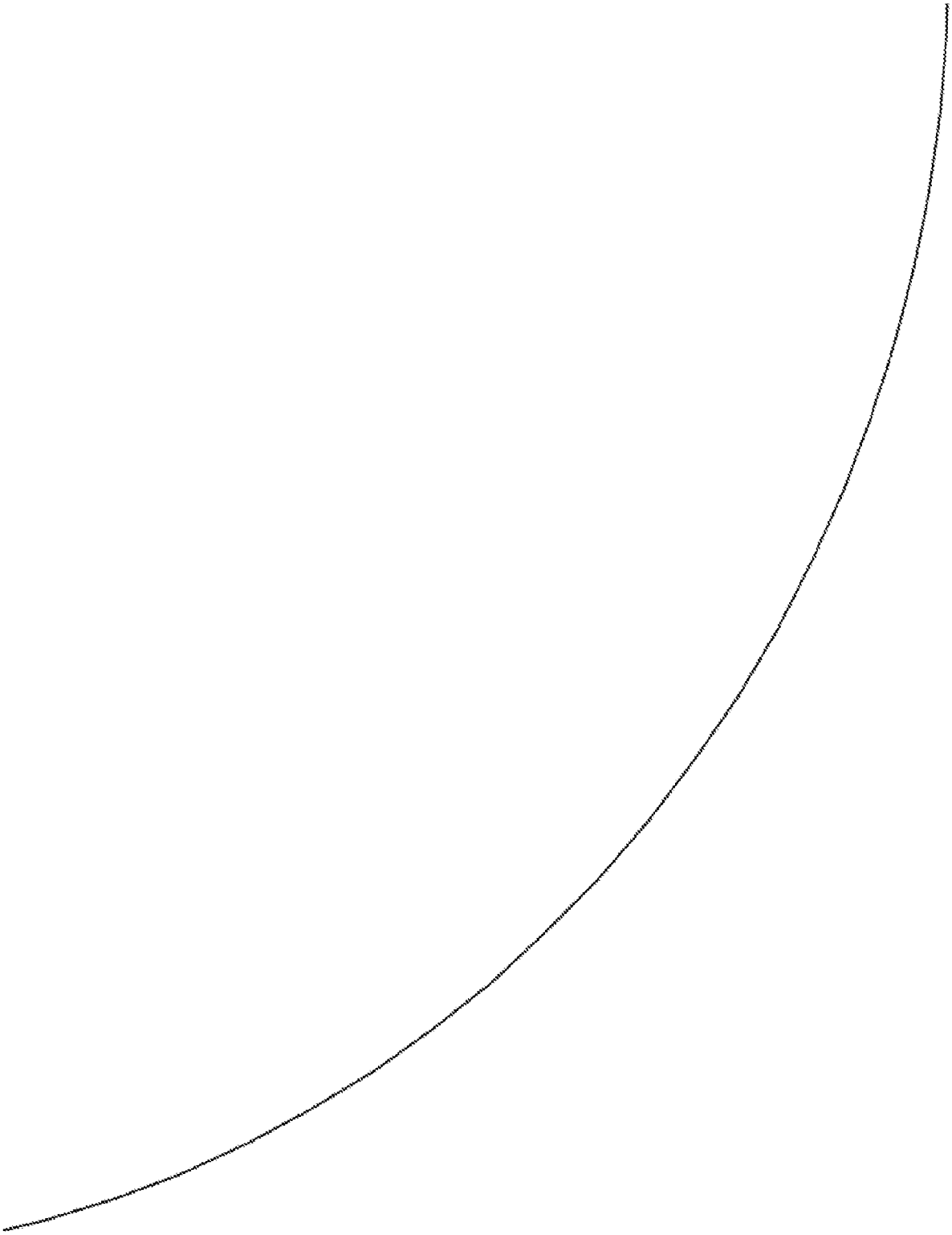
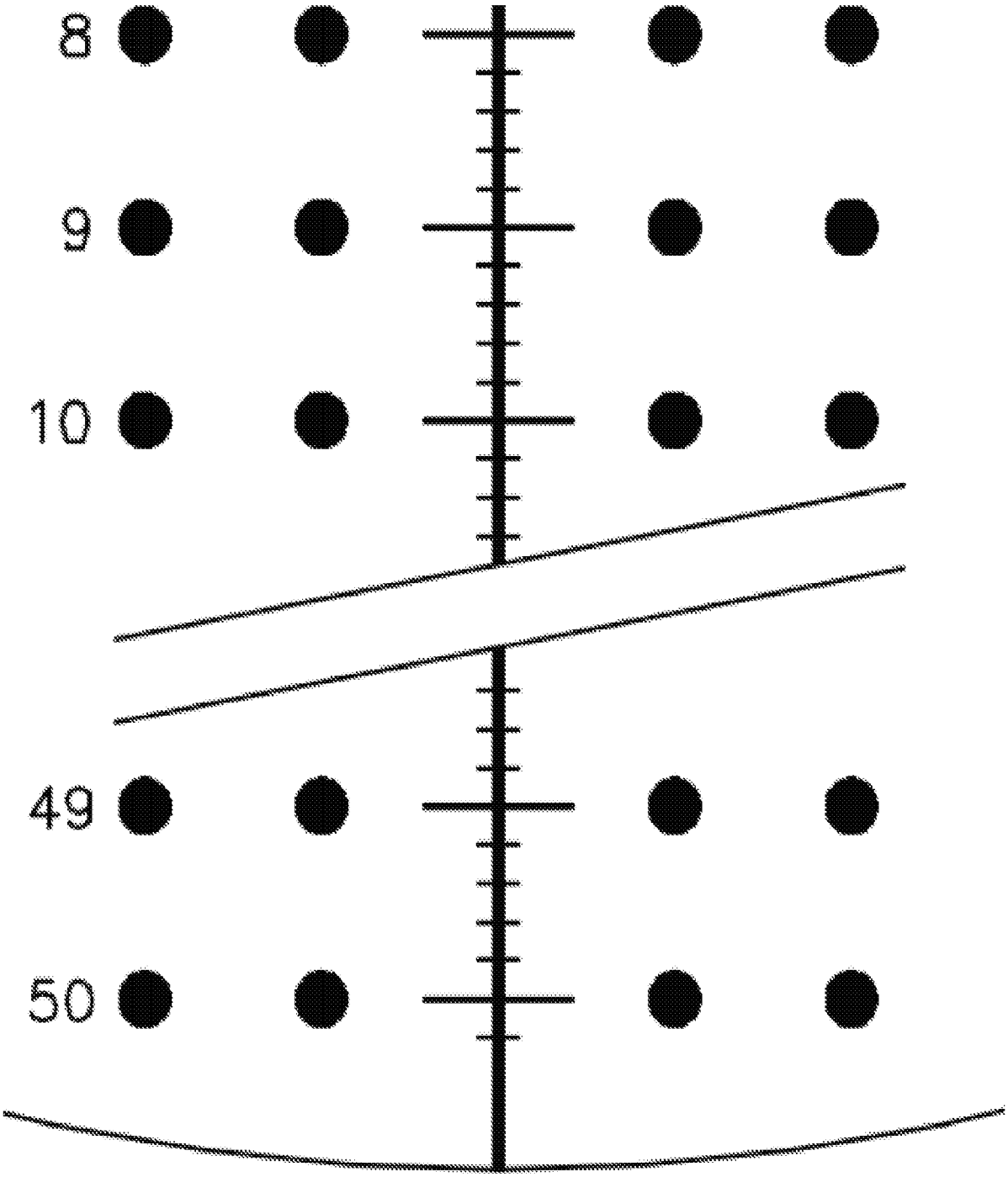


FIG. 52at



52au

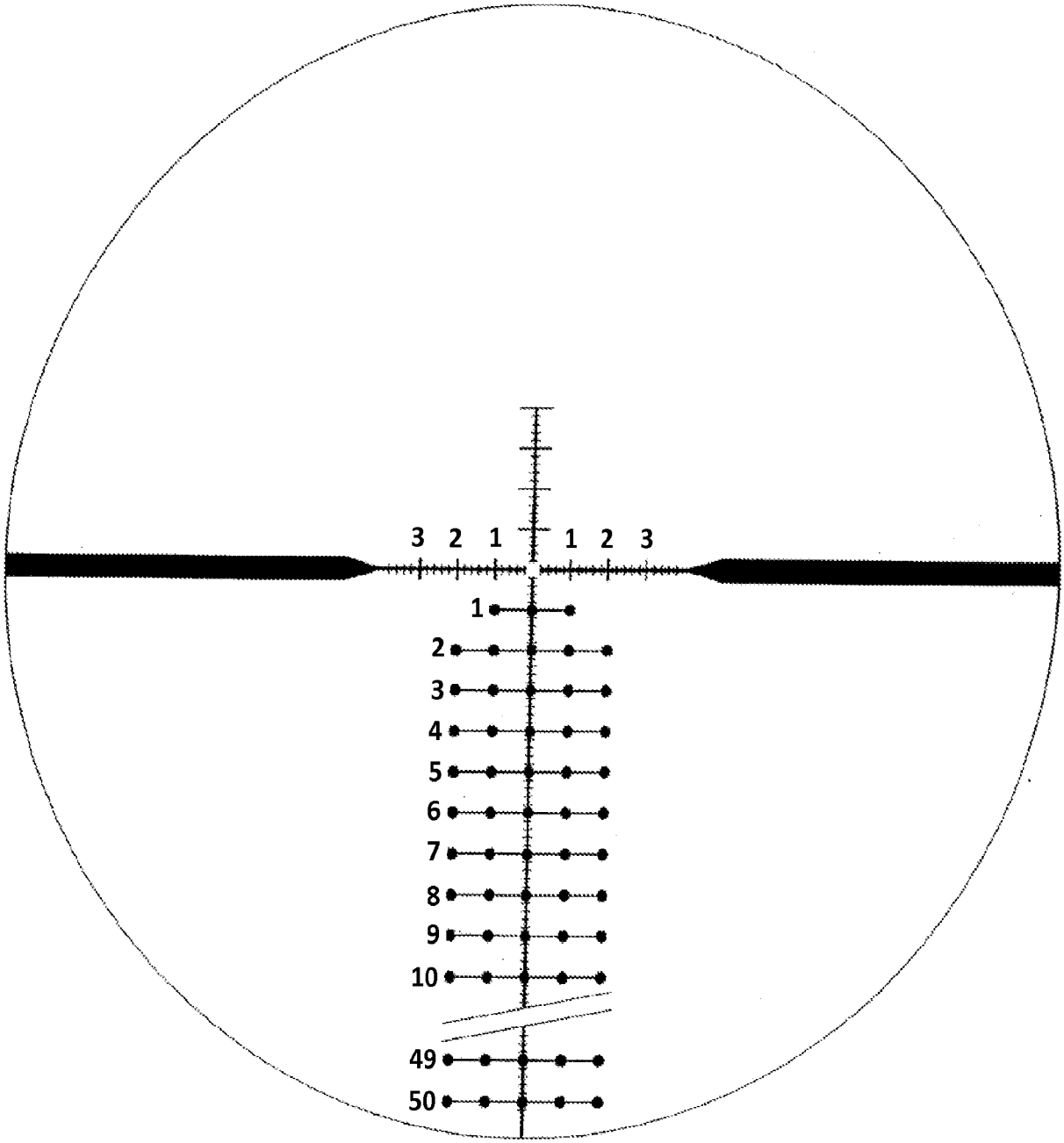


FIG. 53a

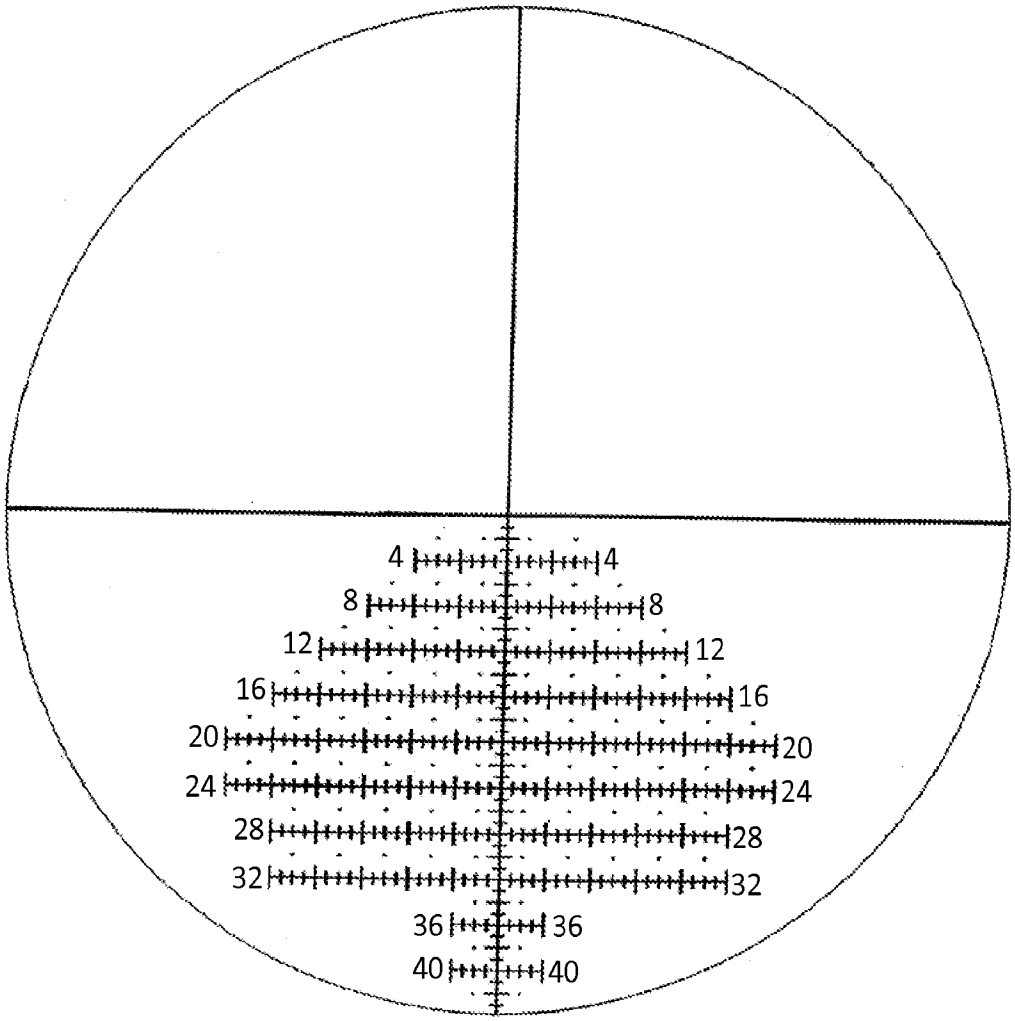


FIG. 53b

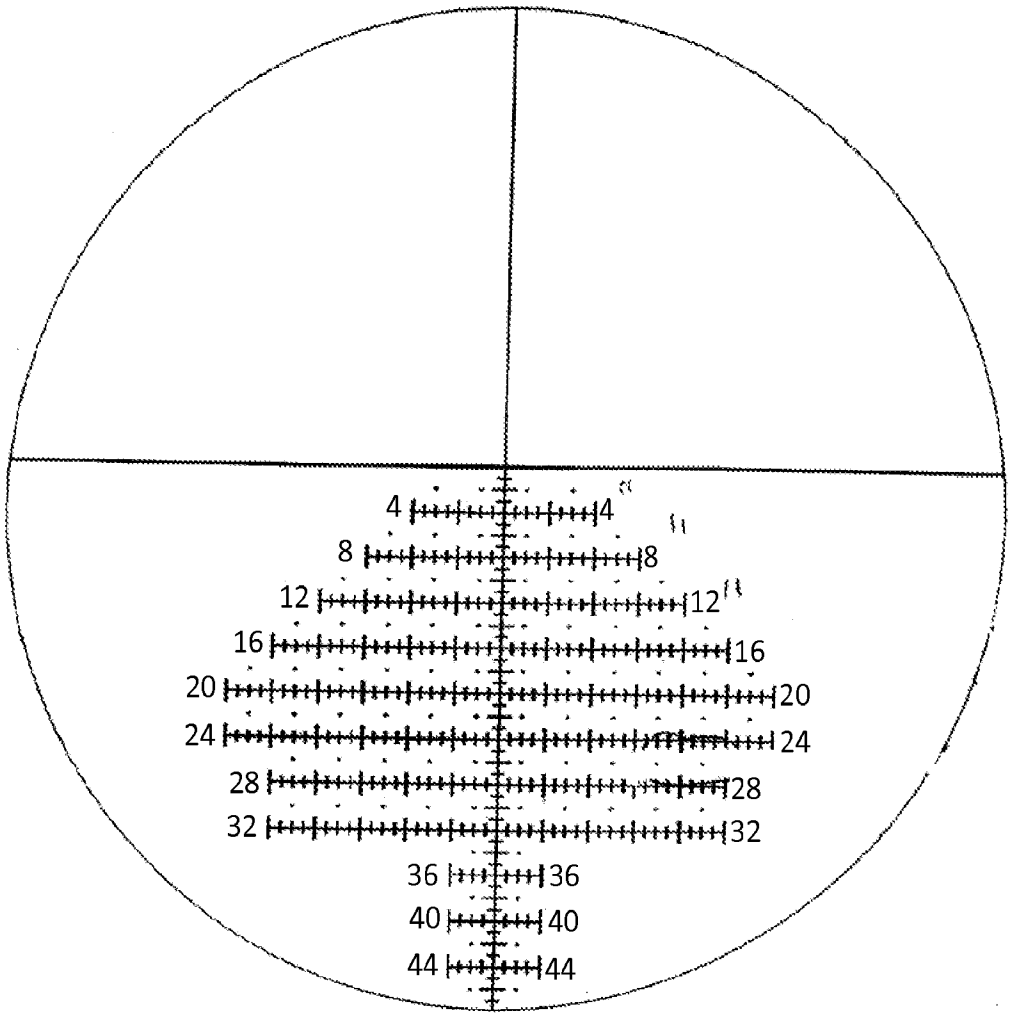
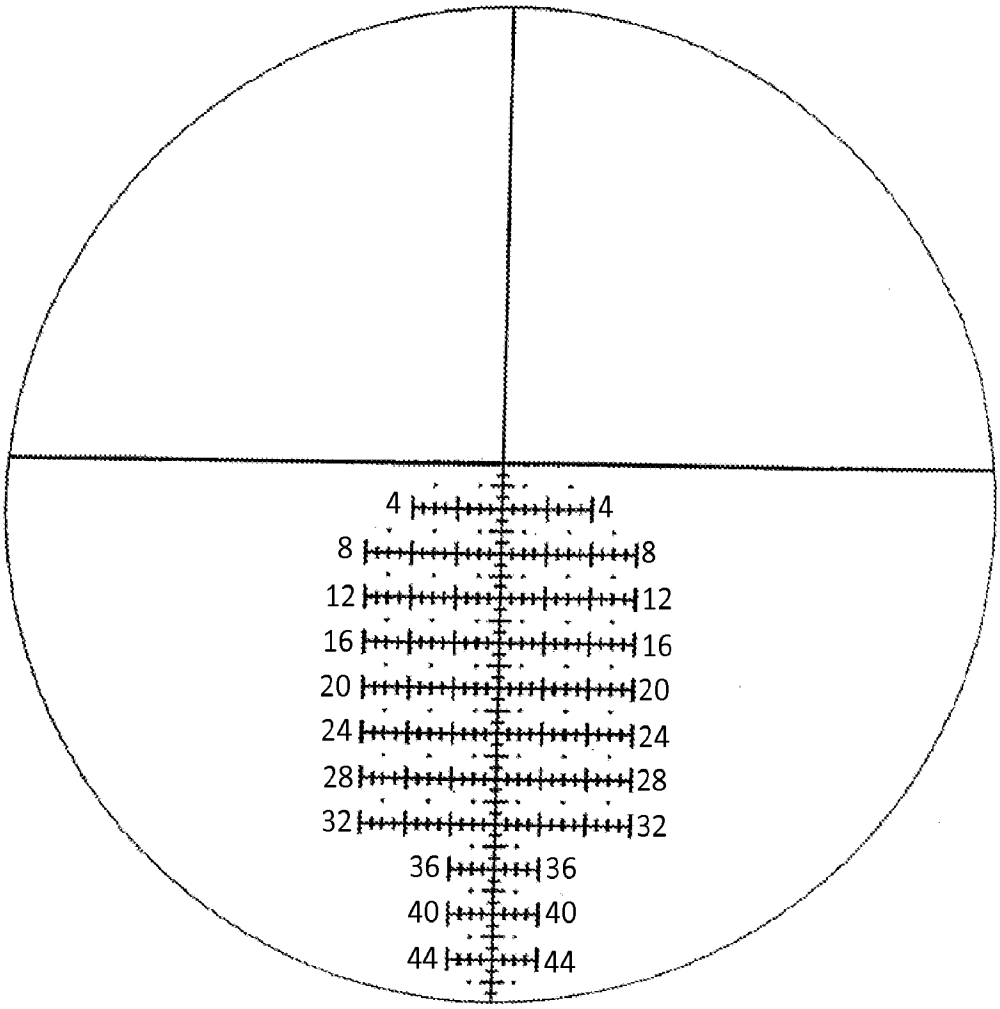


FIG. 53c



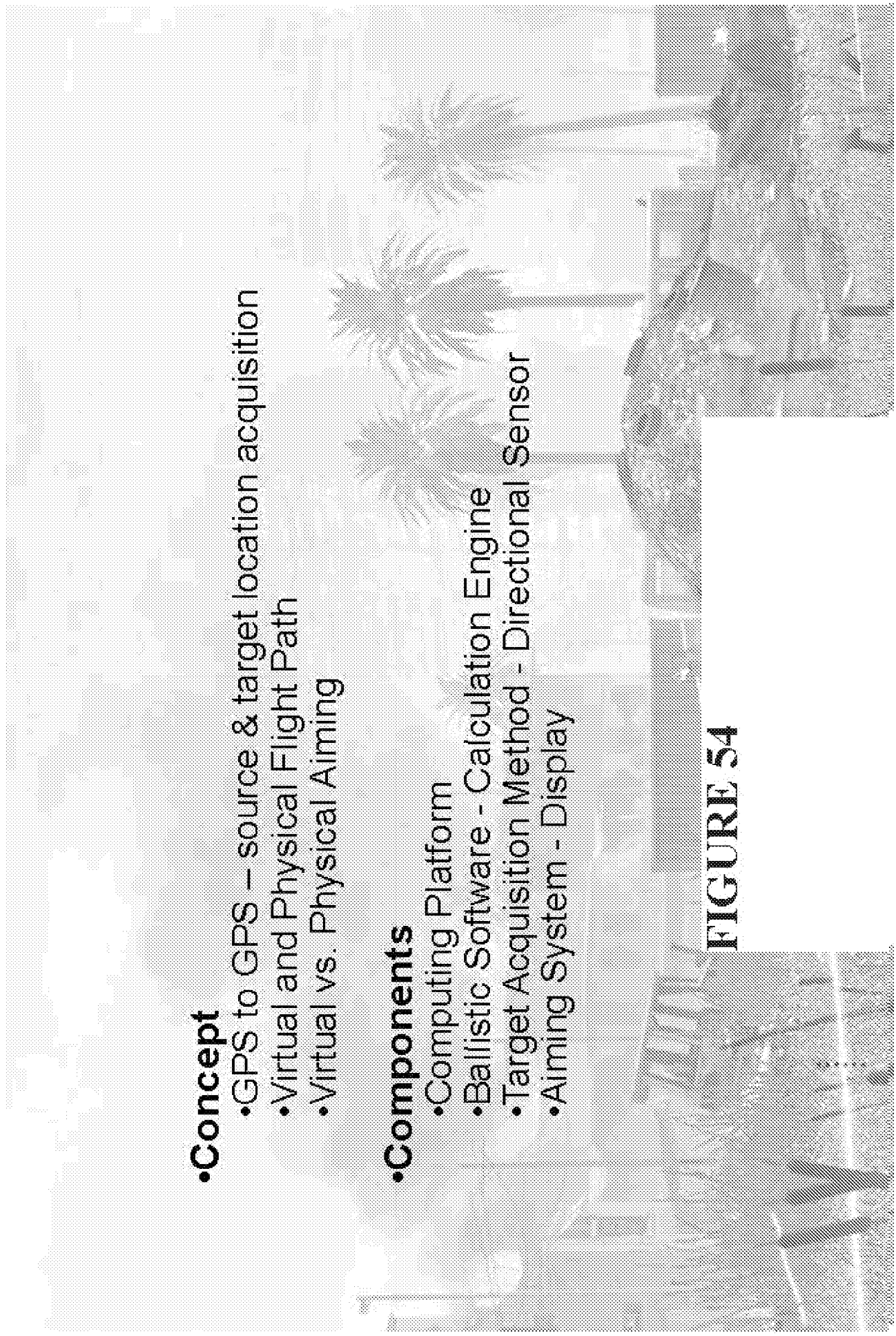

•Concept
•GPS to GPS – source & target location acquisition
•Virtual and Physical Flight Path
•Virtual vs. Physical Aiming
•Components
•Computing Platform
•Ballistic Software - Calculation Engine
•Target Acquisition Method - Directional Sensor
•Aiming System - Display

FIGURE 54

As the need for direct-line-of-site for precise small arms fire diminishes it is possible to **effectively engage without detection.**
• Ballistic Calculator
• GPS co-ord gathering and firing solutions
• Directional detecting instrumentation
• Digital Micro Display
• Improved rifle scopes and reticles

FIGURE 55

Concept
•Direct Fire – line of sight
•Aided by ballistic technology
•Elev = 16
•Wind = 5

FIGURE 56

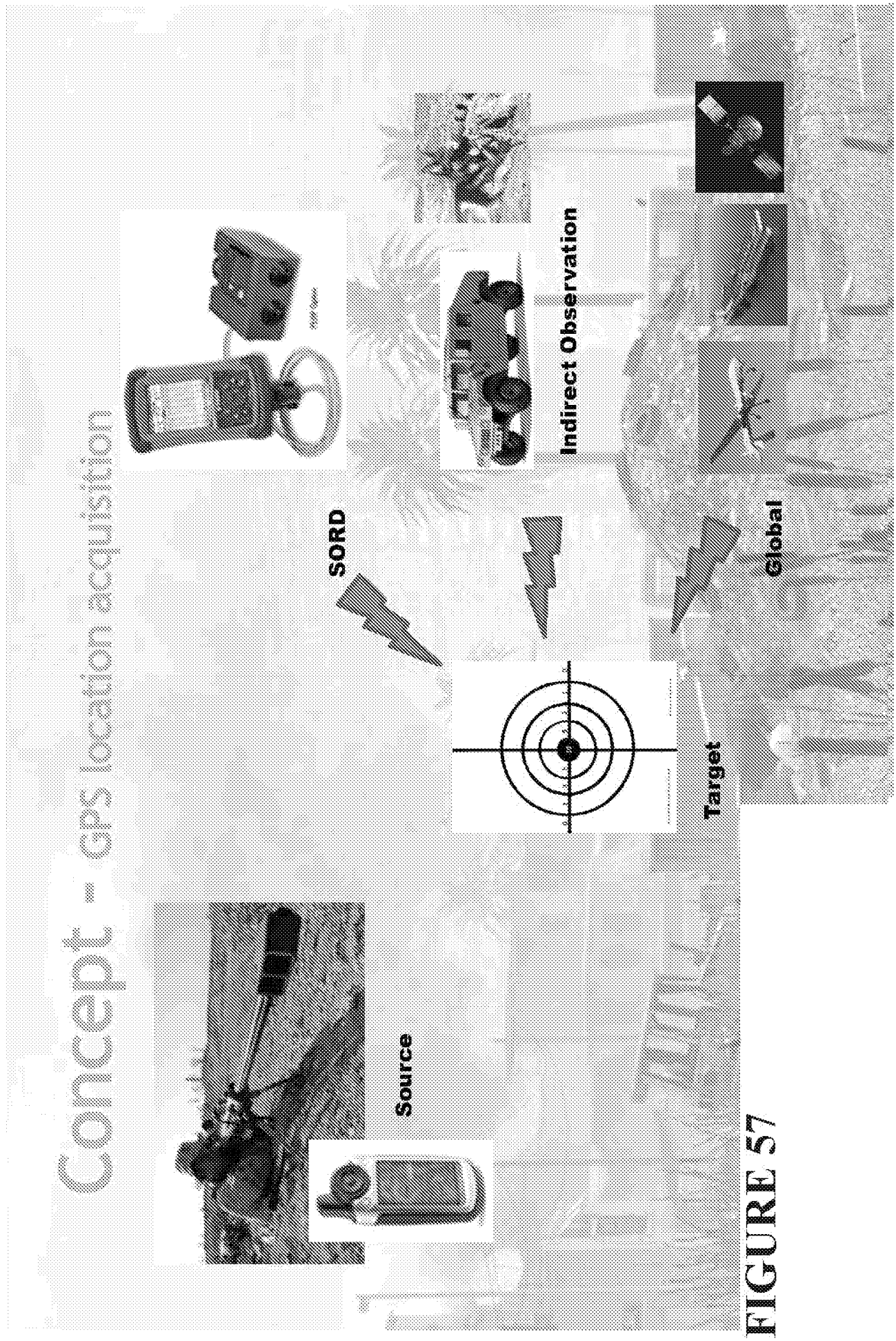

Concept - GPS location acquisition
Source
SORD
Indirect Observation
Target
Global

FIGURE 57

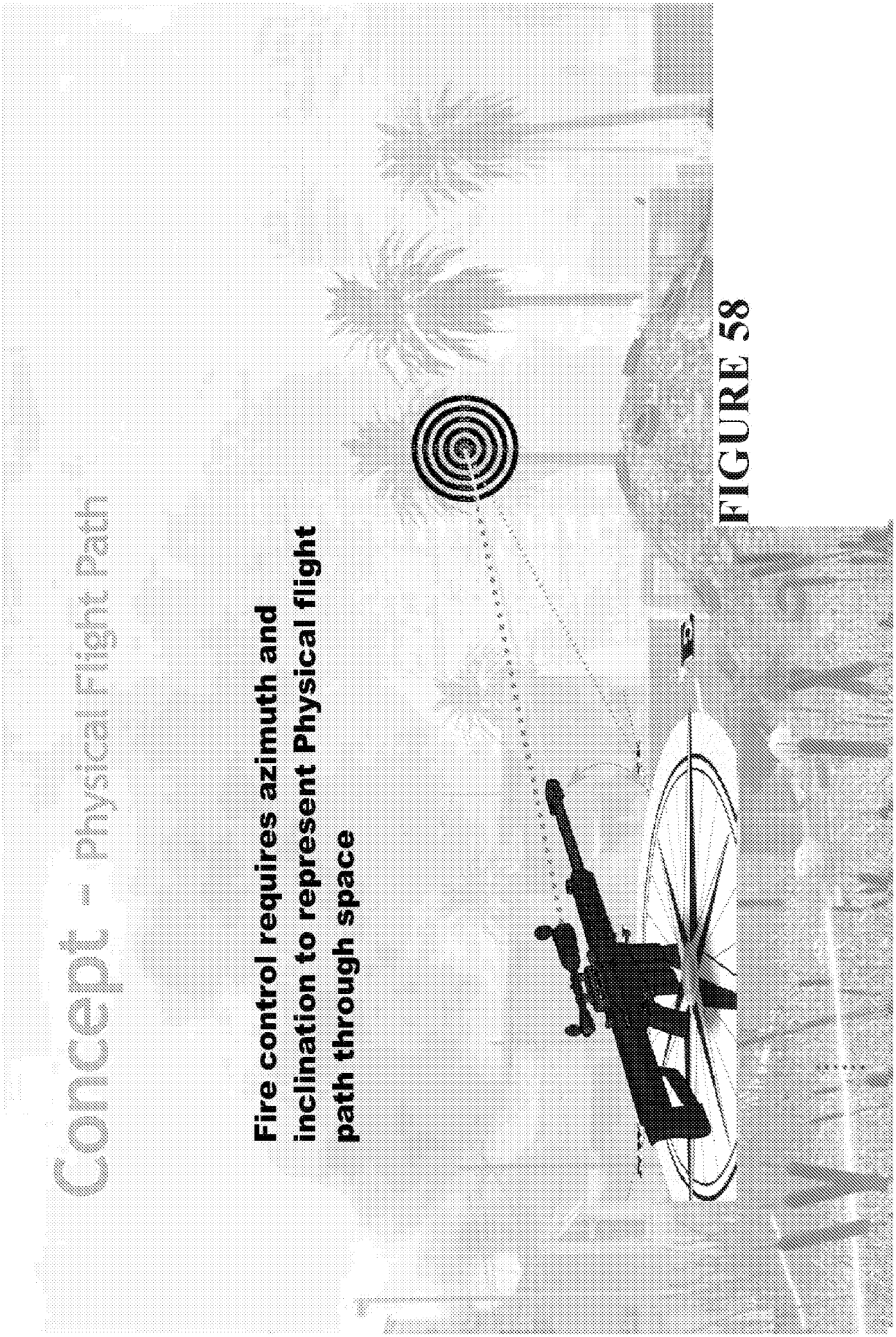

Concept - Physical Flight Path
Fire control requires azimuth and inclination to represent Physical flight path through space

FIGURE 58

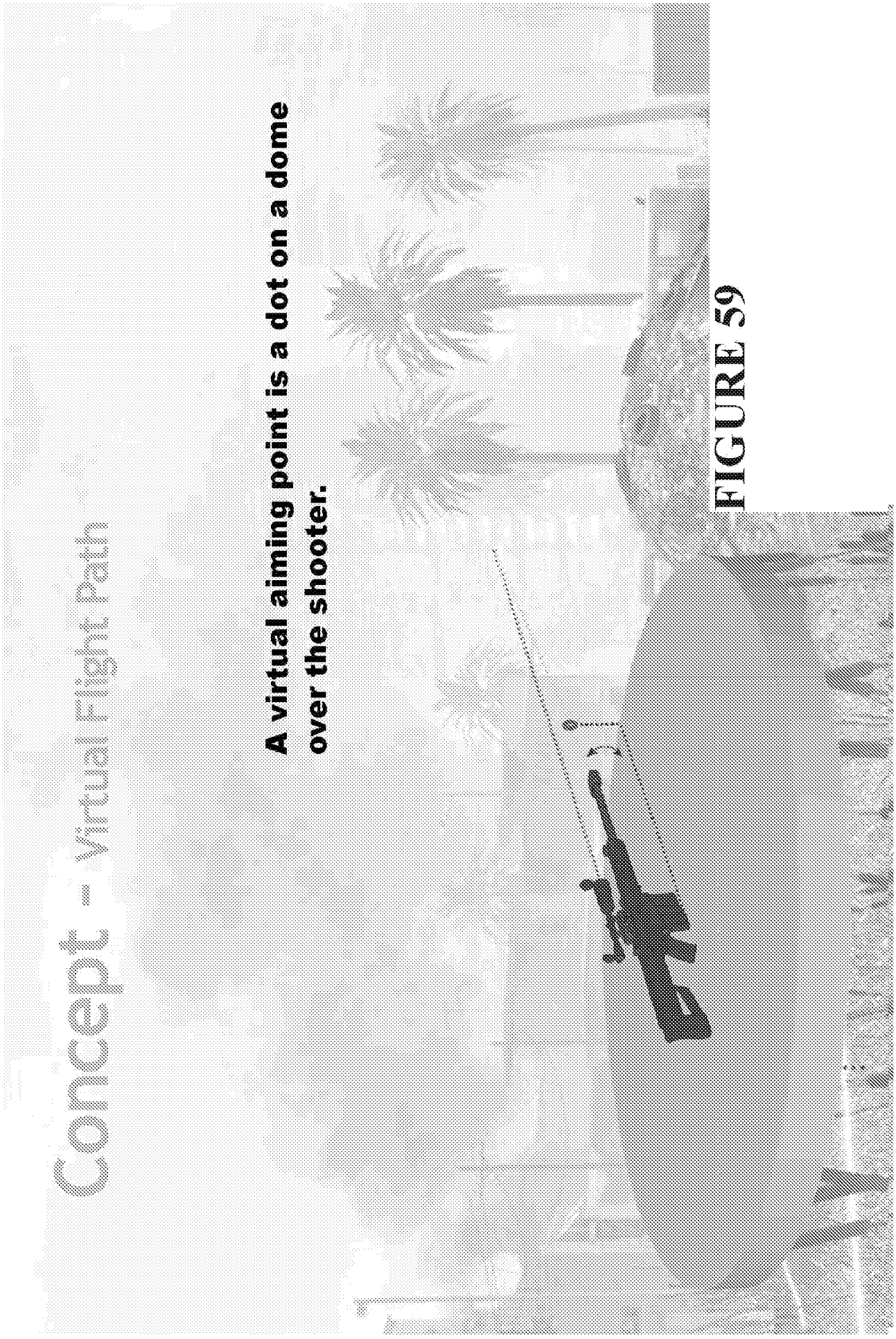

Concept - Virtual Flight Path
A virtual aiming point is a dot on a dome over the shooter.

FIGURE 59

Concepts - Directional Sensor
Directional Sensor mounted to gun and oriented to barrel (for example, Picatinny 1913 rail).

FIGURE 60

Concepts – Display
Simple Dot & Circle with arrow indicator.
Dot not in FOV
Dot in FOV
On target

FIGURE 61


Components - Computing Platform / Software
GPS
Display
Laptop
•PDA / PC-Laptop
•ATrag v4.0
Directional
Sensor

FIGURE 62

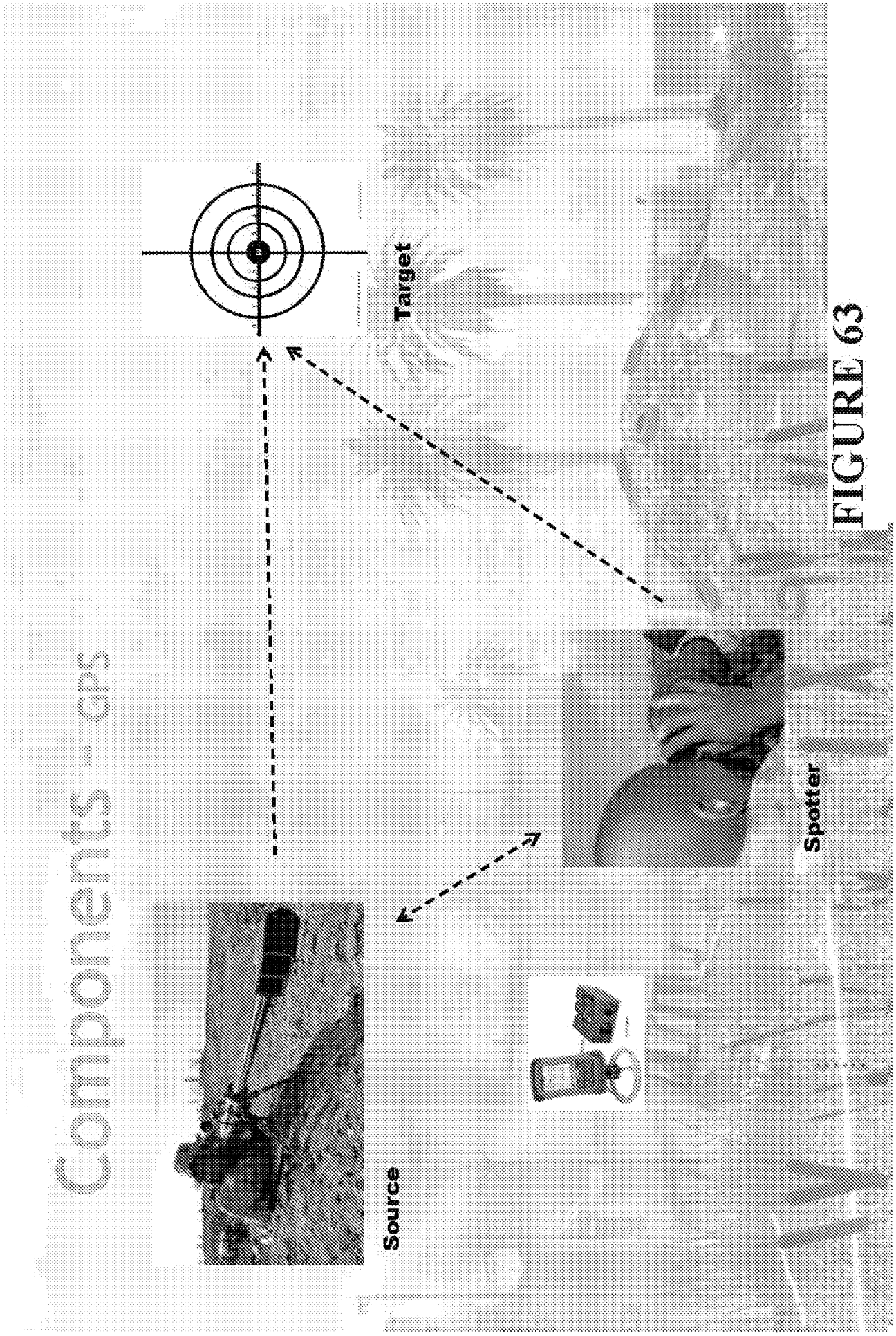


FIGURE 63

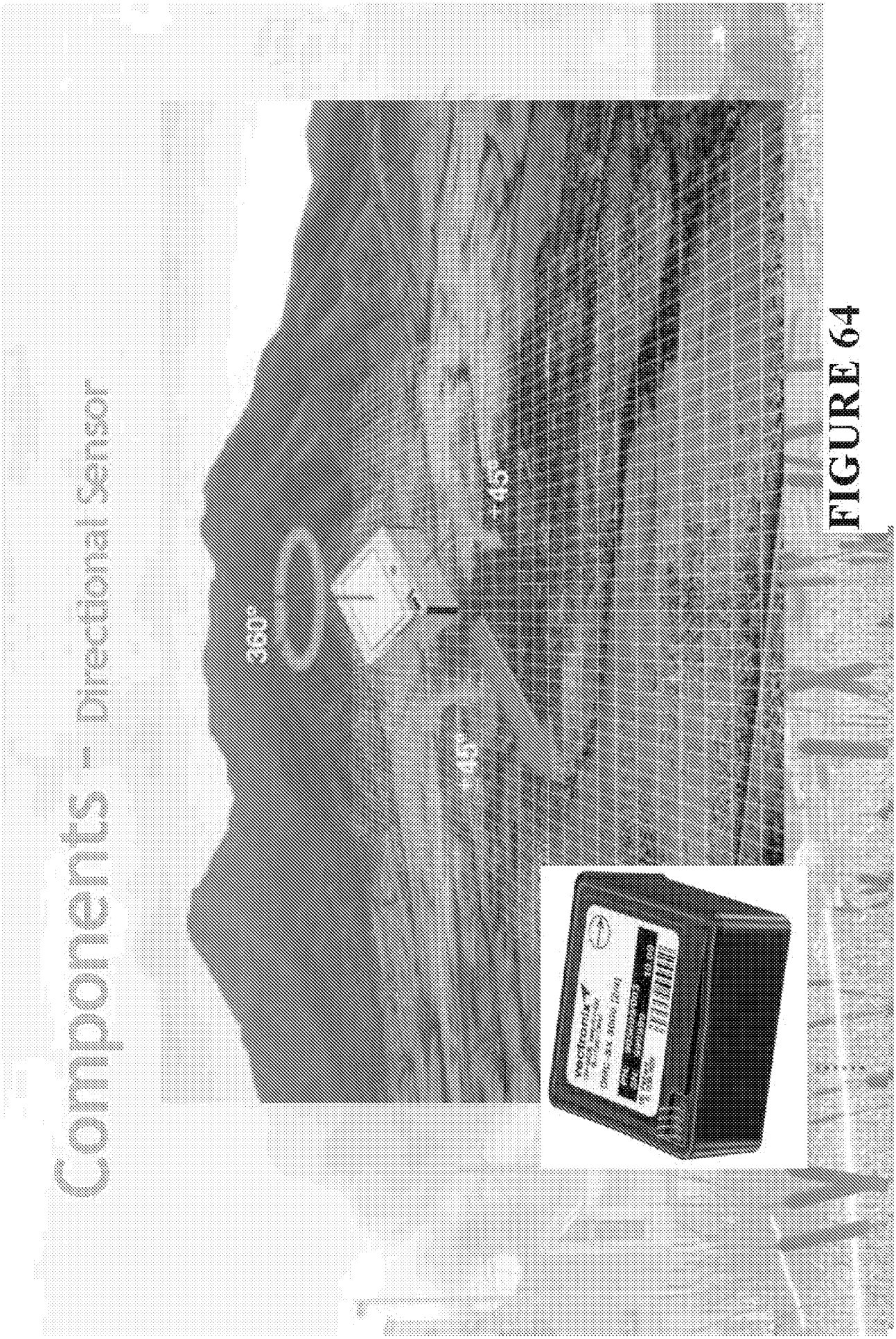


FIGURE 64

Components - Aiming System / Display
Disassemble COTS and remount the display on riflescope
• Vuxiz
• Zetronix

FIGURE 65

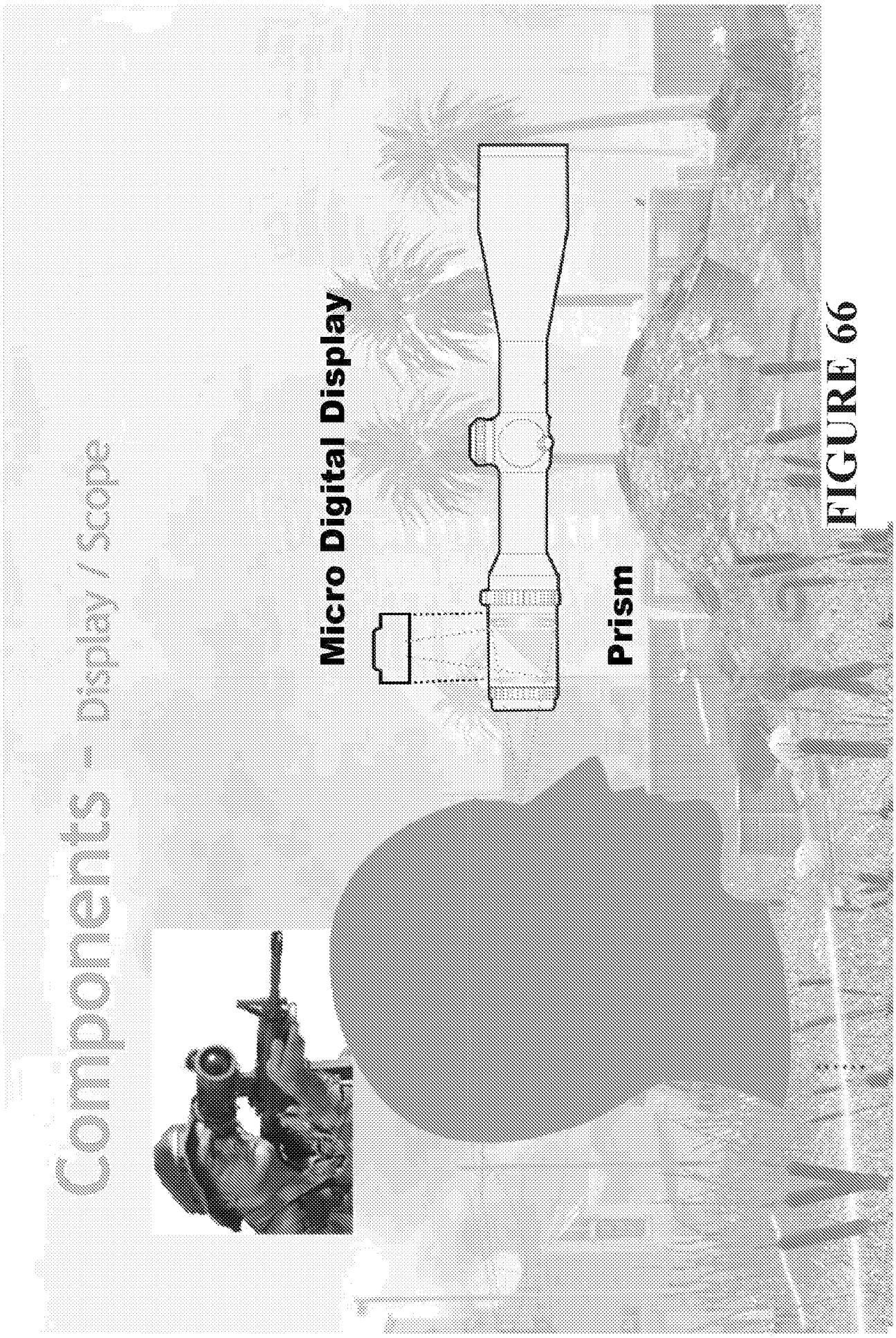


FIGURE 66

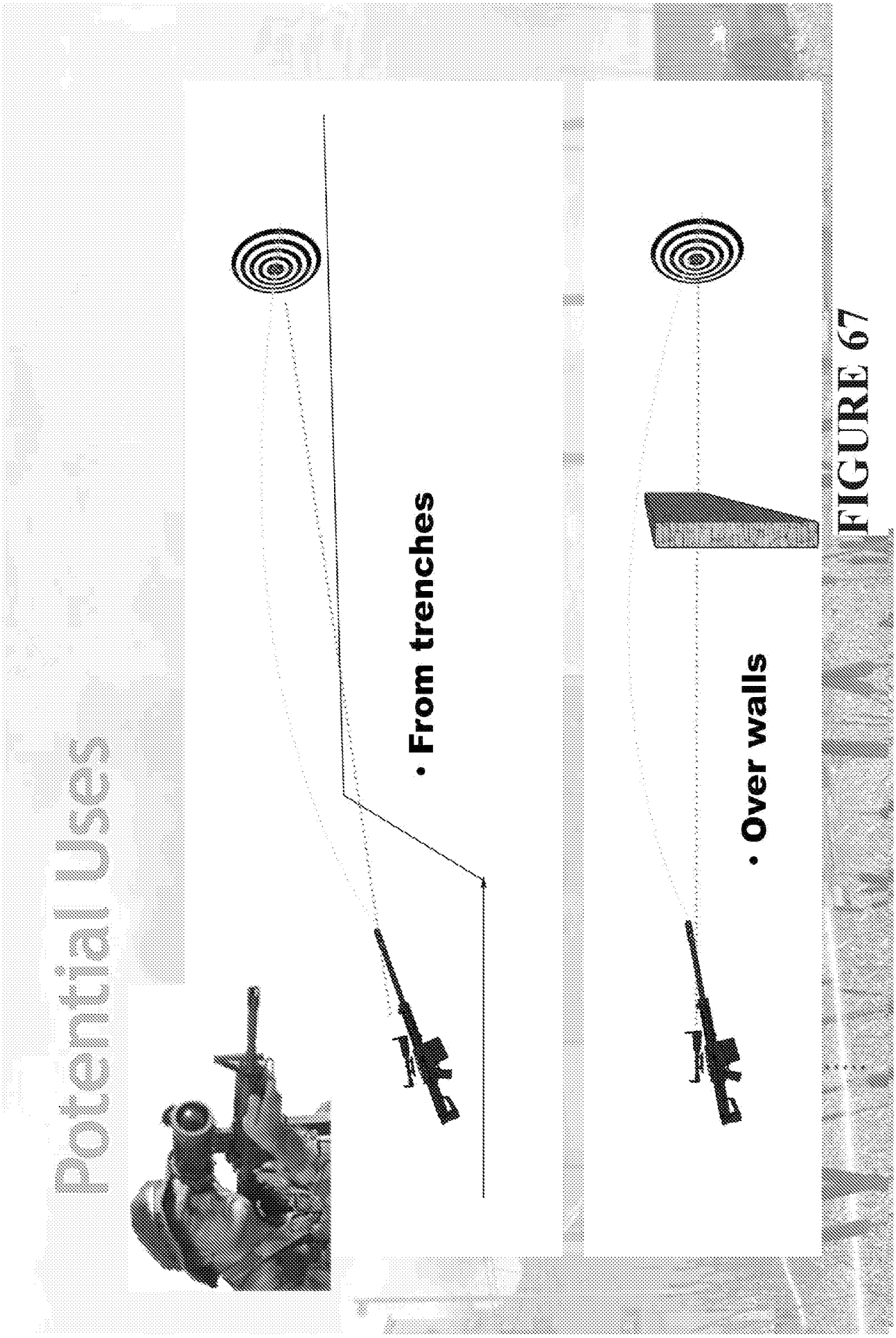


FIGURE 67

Potential Uses
• Remote Gun Platforms
• directional sensor on barrel
• display and controls are miles away

FIGURE 68

Features
1. Undetected engagement form concealed positions
2. Greater distances
3. Remote, unmanned shooting platforms
4. COTS items
5. Light weight
6. Connectivity

FIGURE 69

Additional Features
1) Through-the-lens, single aperture, LRF for target acquisition.
2) Video input through the lens, performing image processing on the feed and redisplaying the image via the MDM with correction or augmentation of the following:
a. Eliminate mirage for observation
b. Object recognition, face recognition in images
c. Image sharing between shooter and spotter
d. Auto sizing and ranging of objects in image
e. Auto sensing of wind and movement
3) Through the lens data availability: 1) shooting solutions self, 2) shooting solutions others 3) environmental, 4) location (self and others), 5) instructions & timing, 6) alerts, 7) bio feedback, 8) equipment statuses
4) Integrated ballistic calculations into the weather meter, breeching calculations, bio feedback for stress tracking/recording, bio feedback for better body control for sniping, GPS for location tracking

FIGURE 70

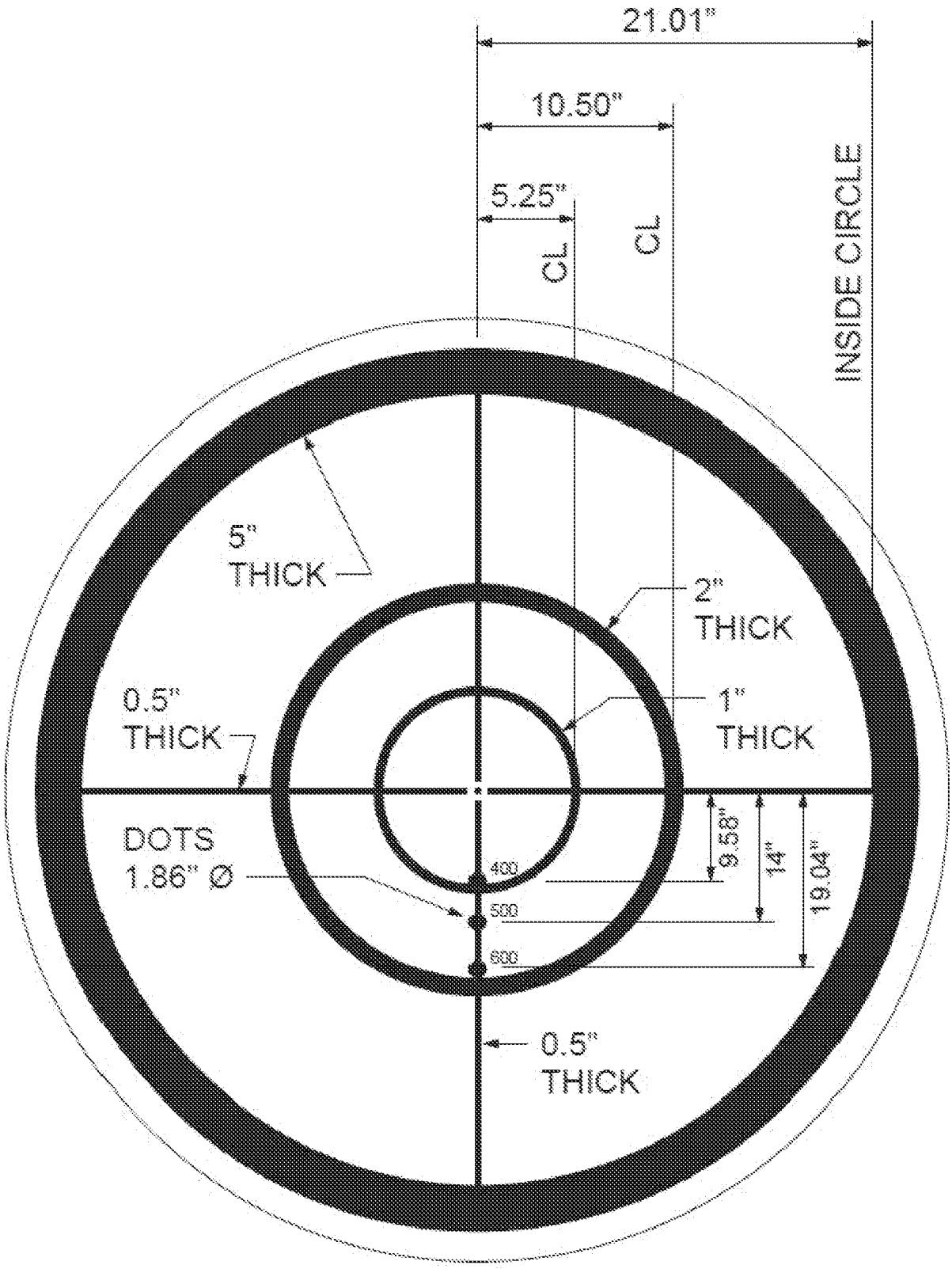

21.01"
10.50"
5.25"
CL
CL
INSIDE CIRCLE
5"
THICK
2"
THICK
0.5"
THICK
1"
THICK
DOTS
1.86" Ø
400
500
600
9.58"
14"
19.04"
0.5"
THICK

Fig. 71A

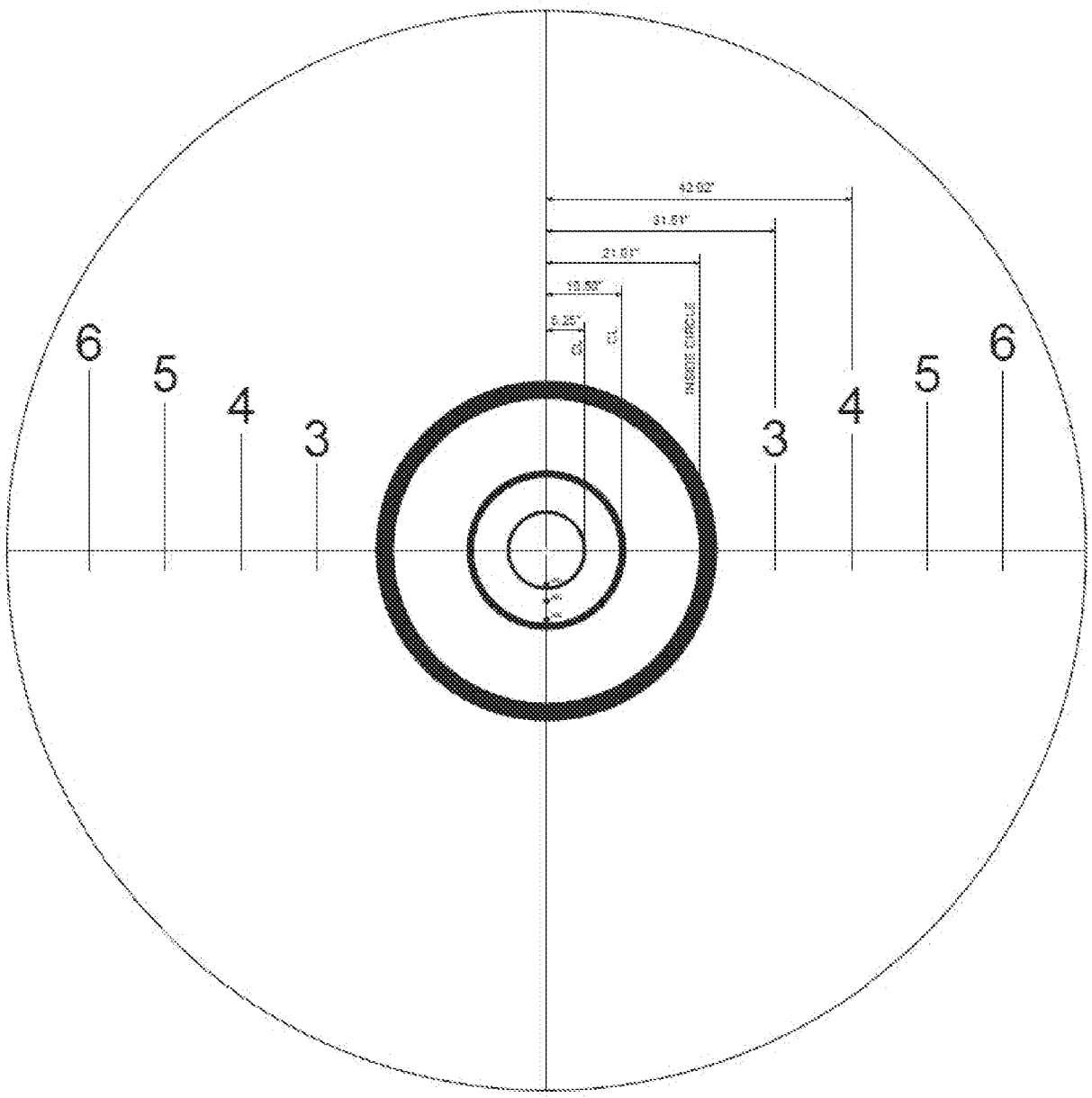


Fig. 71B

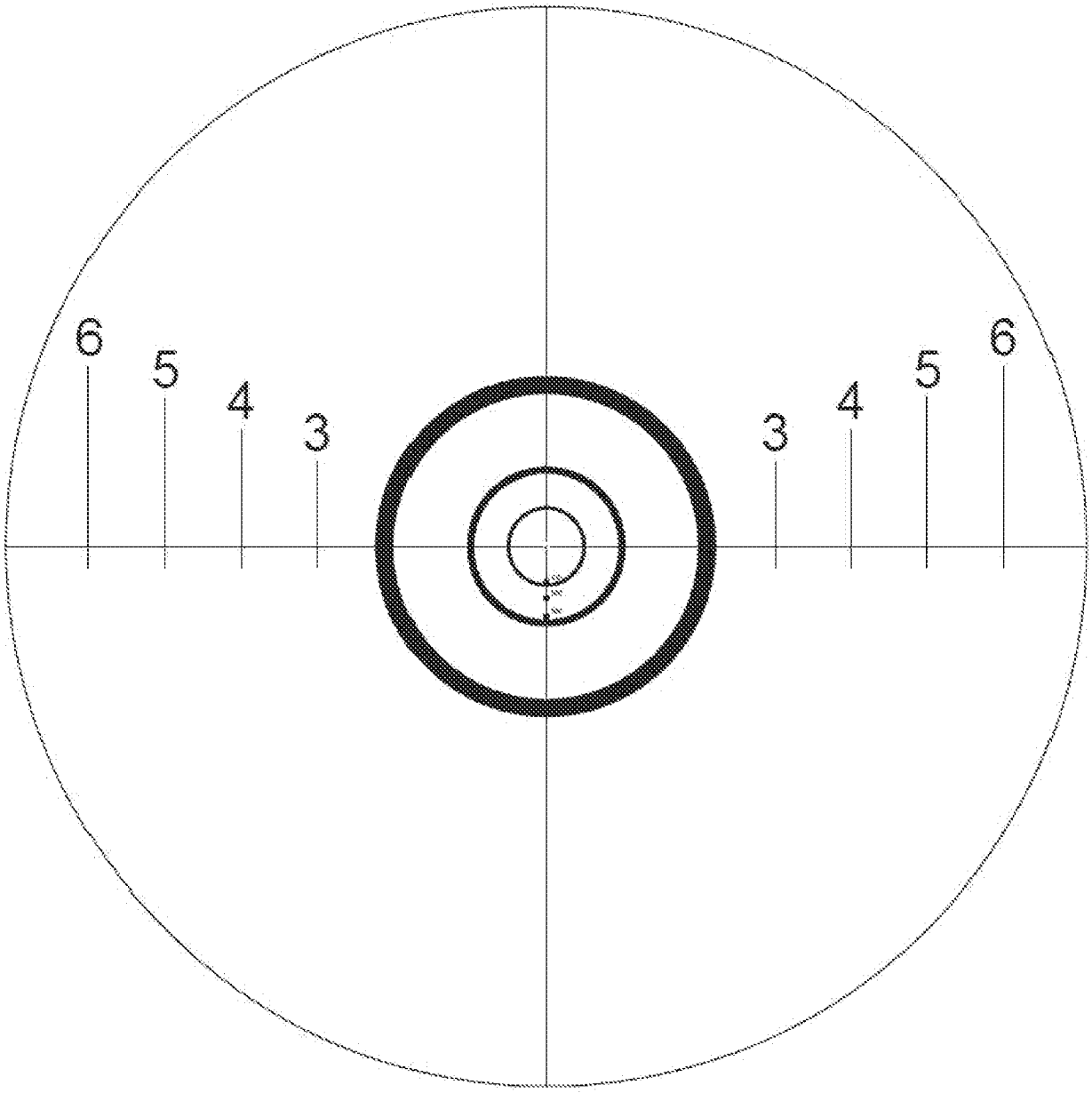


Fig. 71C

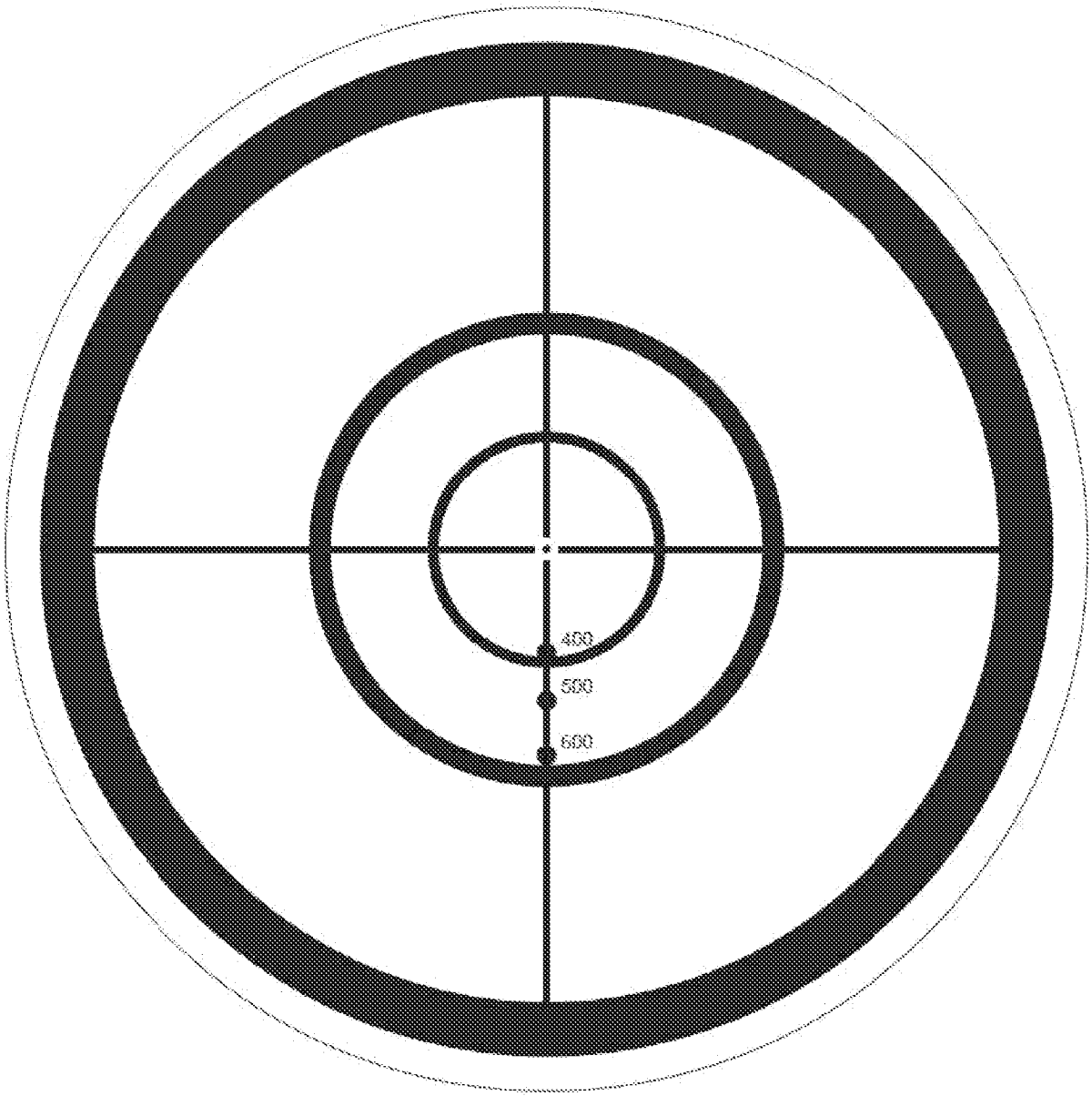


Fig. 71D

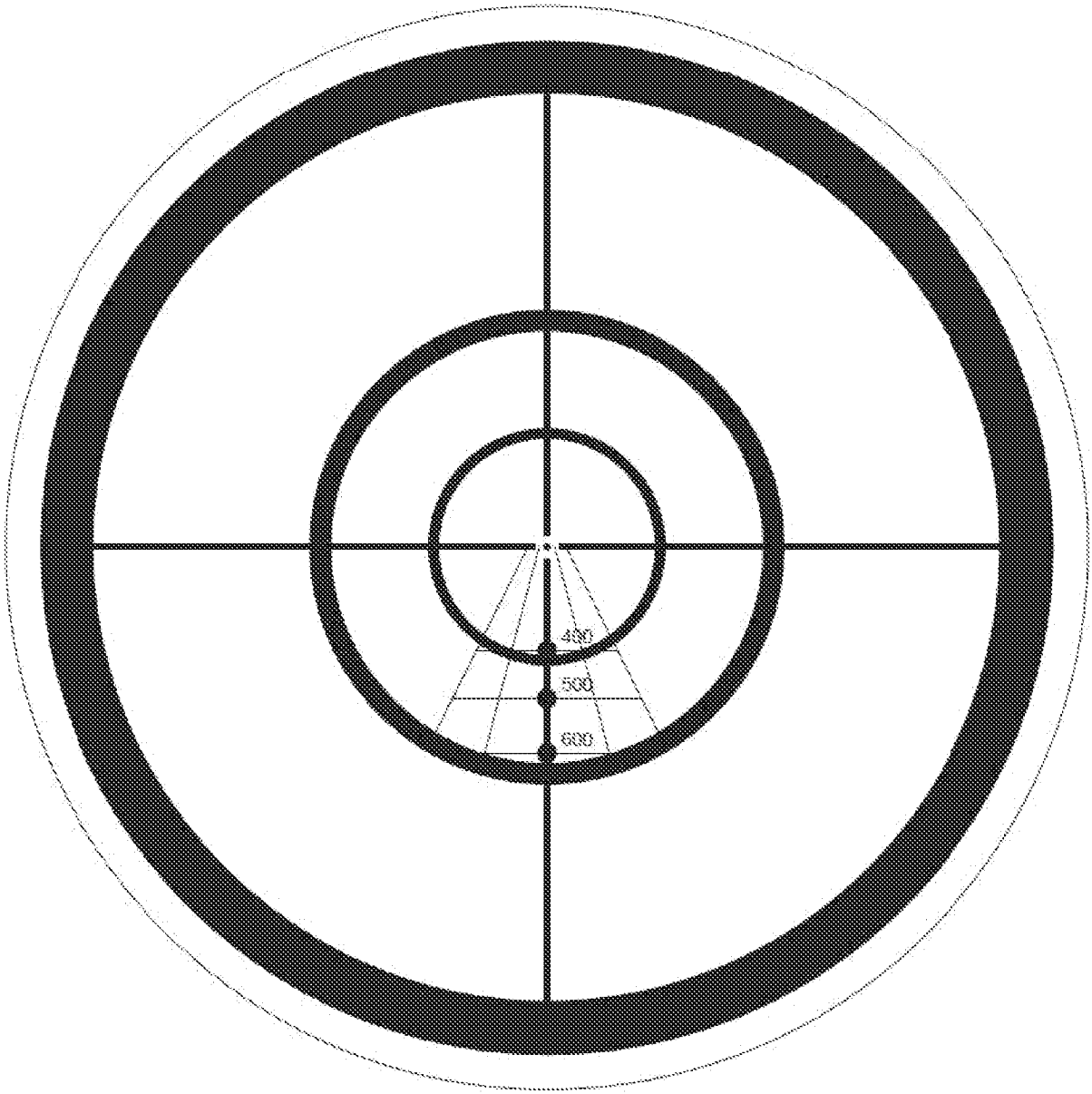


Fig. 72A

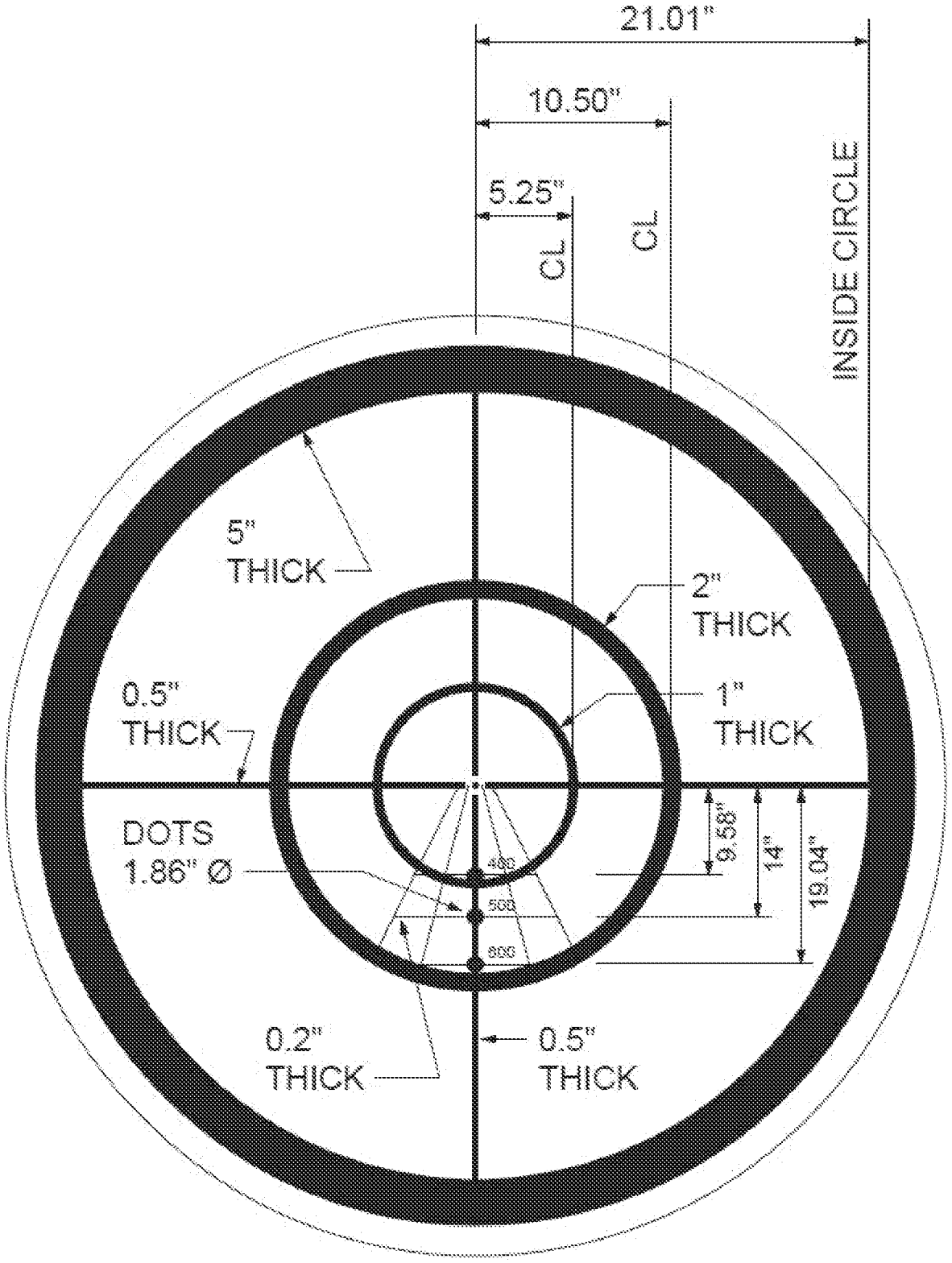

21.01"
10.50"
5.25"
CL
CL
INSIDE CIRCLE
5"
THICK
2"
THICK
0.5"
THICK
1"
THICK
DOTS
1.86" Ø
9.58"
14"
19.04"
400
500
600
0.2"
THICK
0.5"
THICK

Fig. 72B

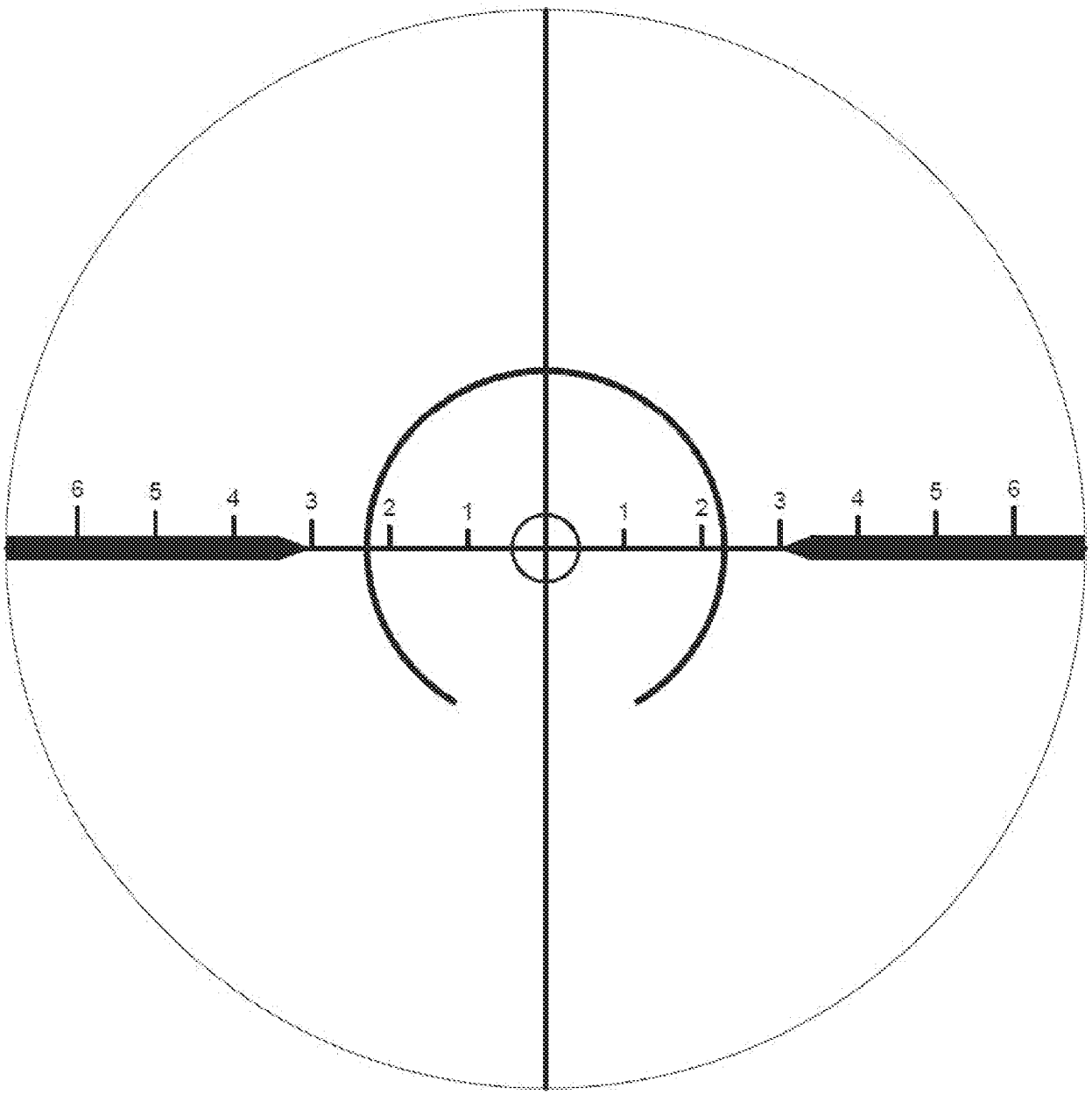


Fig. 73A

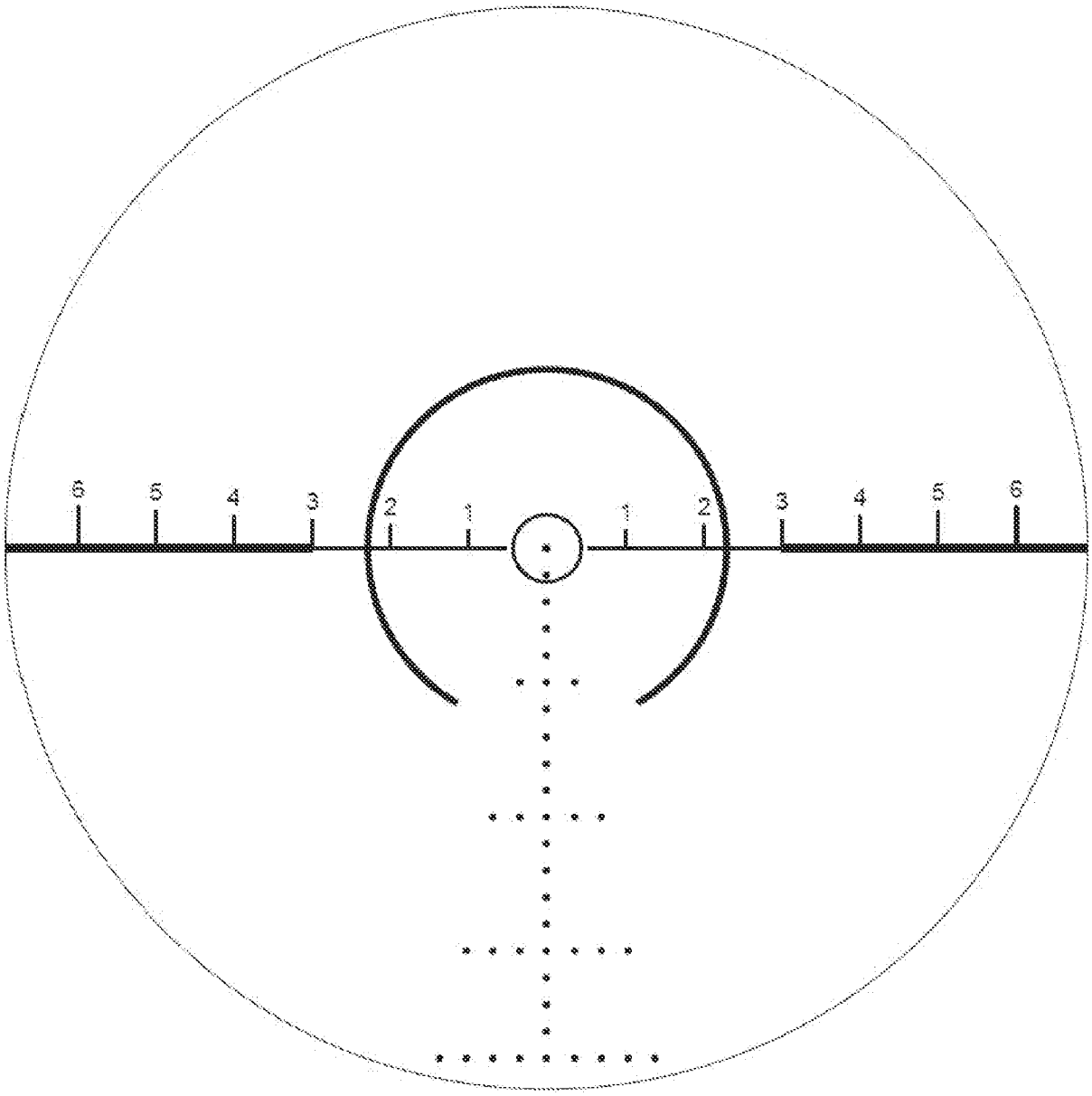


Fig. 73B

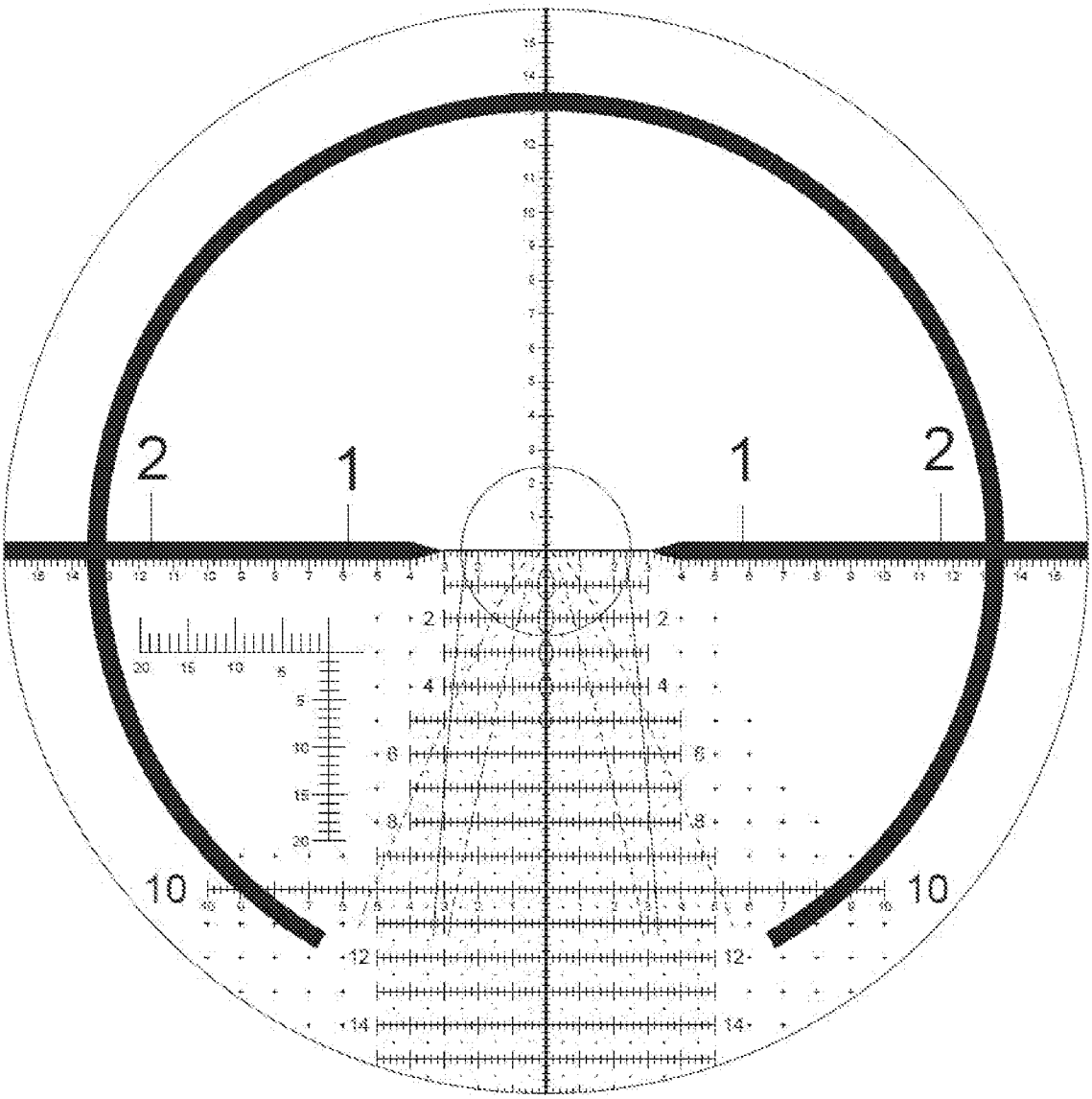


Fig. 73C

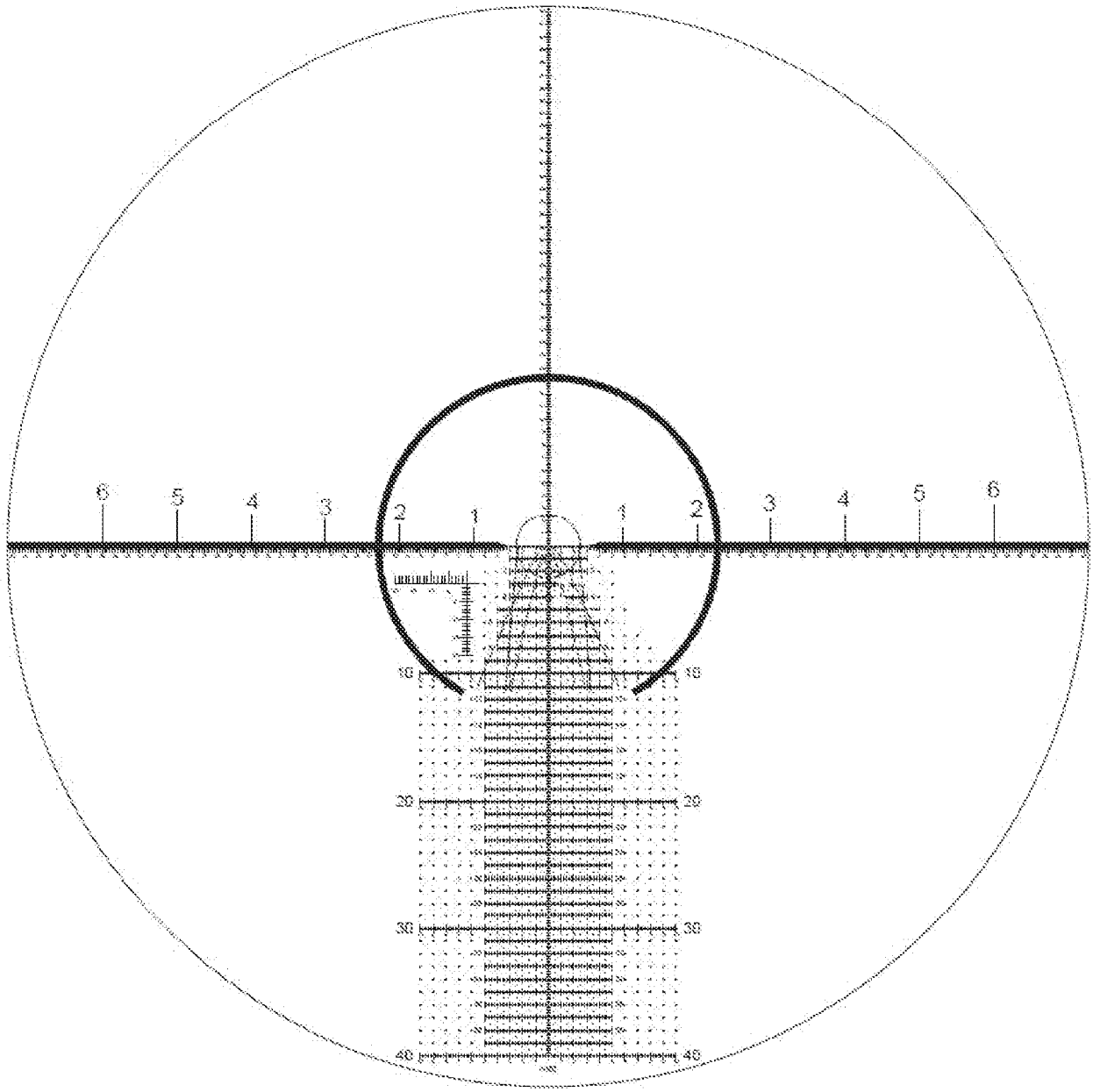
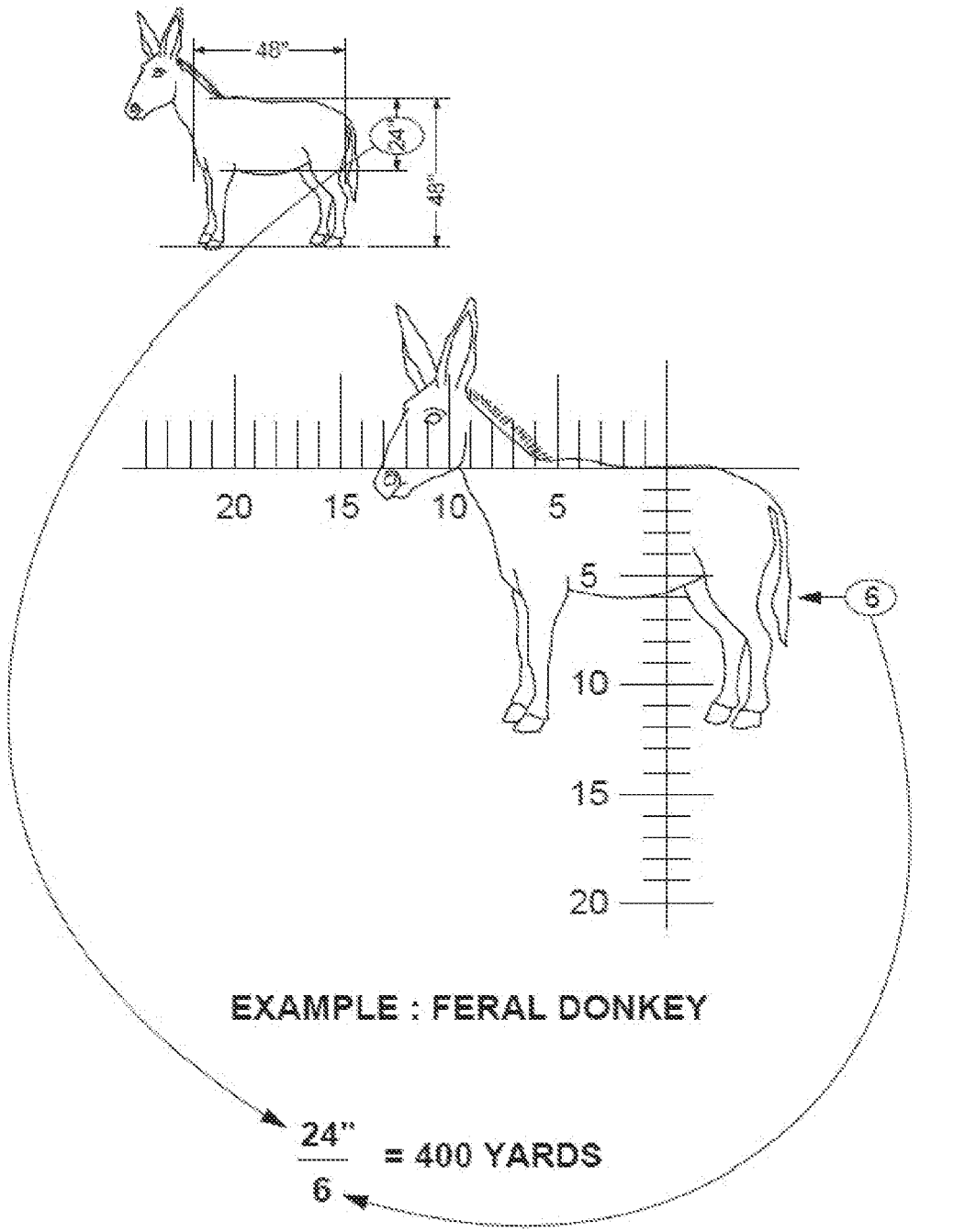


Fig. 73D



ANIMAL CHEST HEIGHT (24")
RANGEFINDER MEASUREMENT (6) X 100 = 400 YARDS

Fig. 73E

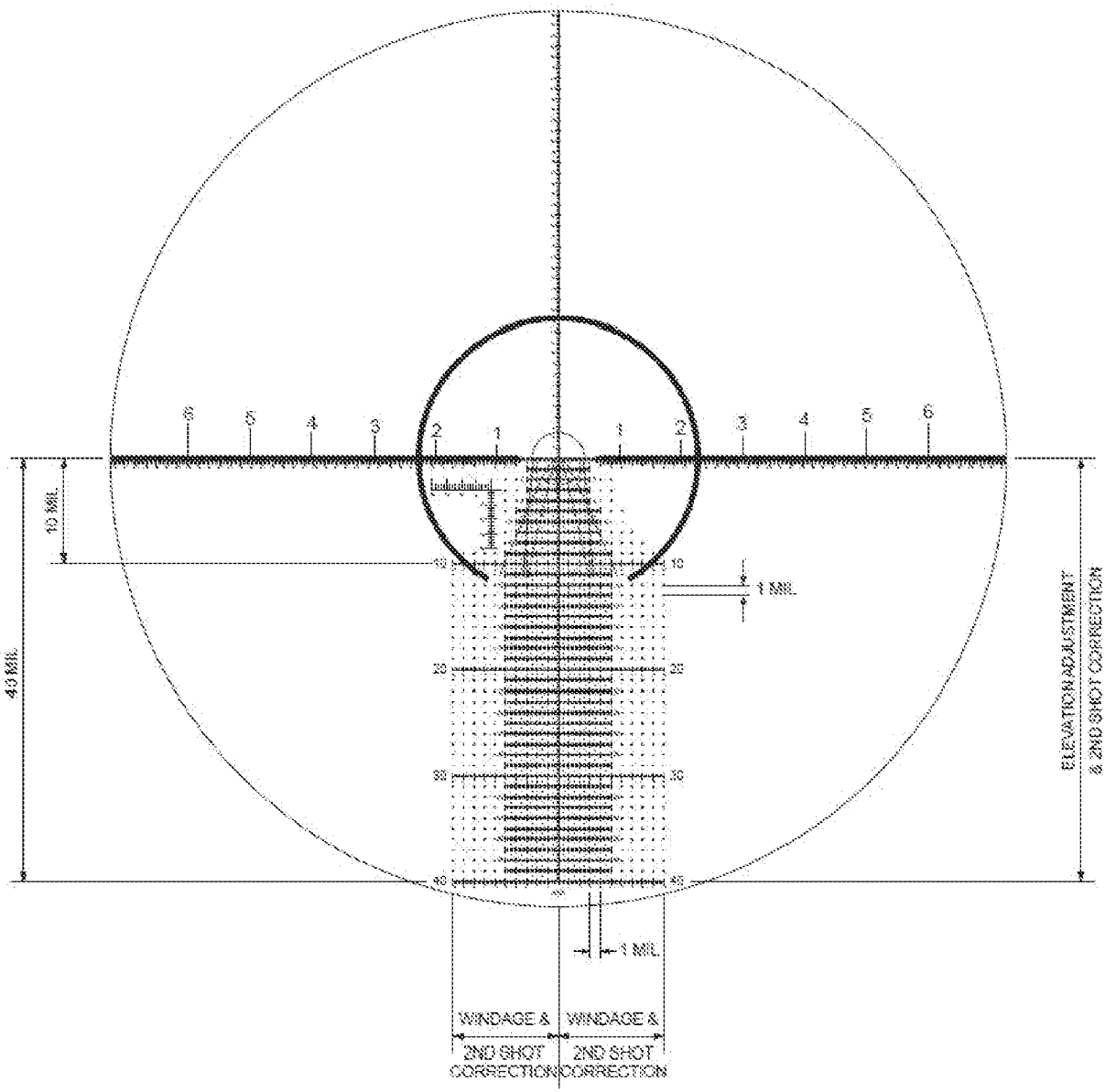

6
5
4
3
2
1
1
2
3
4
5
6
10 MIL
40 MIL
1 MIL
1 MIL
WINDAGE &
2ND SHOT
CORRECTION
WINDAGE &
2ND SHOT
CORRECTION
ELEVATION ADJUSTMENT
& 2ND SHOT CORRECTION

Fig. 73F

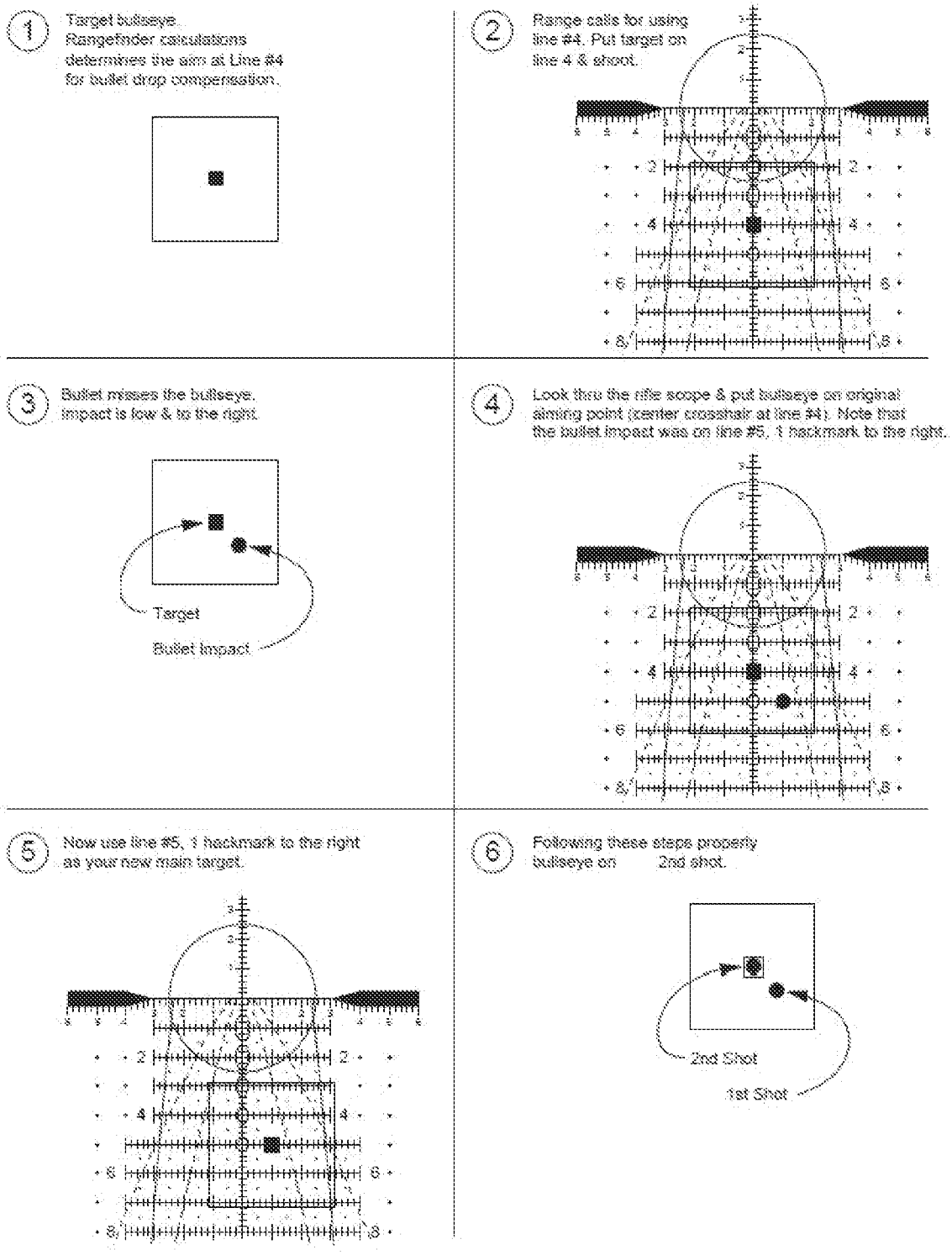

1
Target bullseye.
Rangefinder calculations
determines the aim at Line #4
for bullet drop compensation.
2
Range calls for using
line #4. Put target on
line 4 & shoot.
3
Bullet misses the bullseye.
Impact is low & to the right.
Target
Bullet Impact
4
Look thru the rifle scope & put bullseye on original
aiming point (center crosshair at line #4). Note that
the bullet impact was on line #5, 1 hackmark to the right.
5
Now use line #5, 1 hackmark to the right
as your new main target.
6
Following these steps properly
bullseye on 2nd shot.
2nd Shot
1st Shot

Fig. 73G

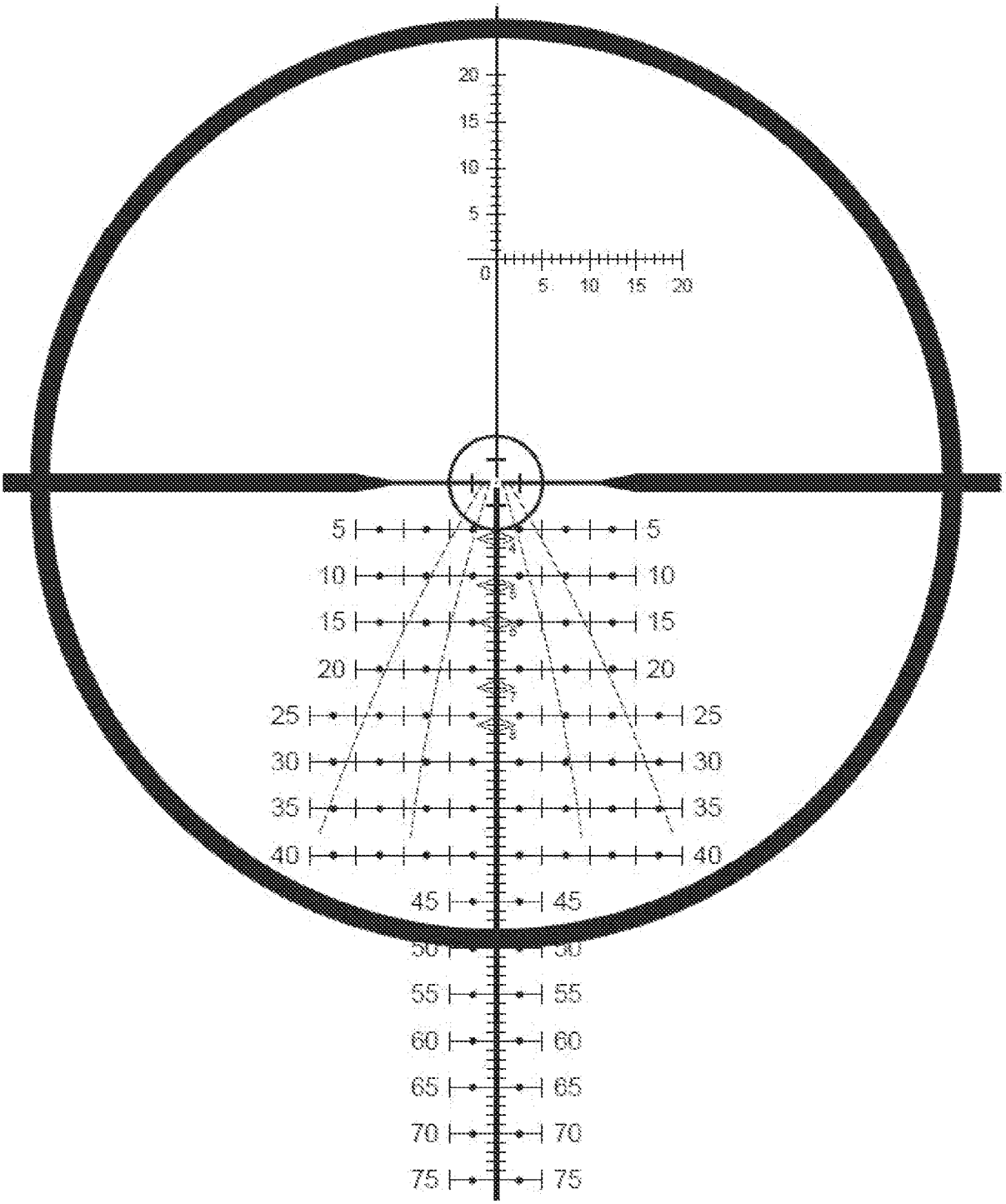


Fig. 74A

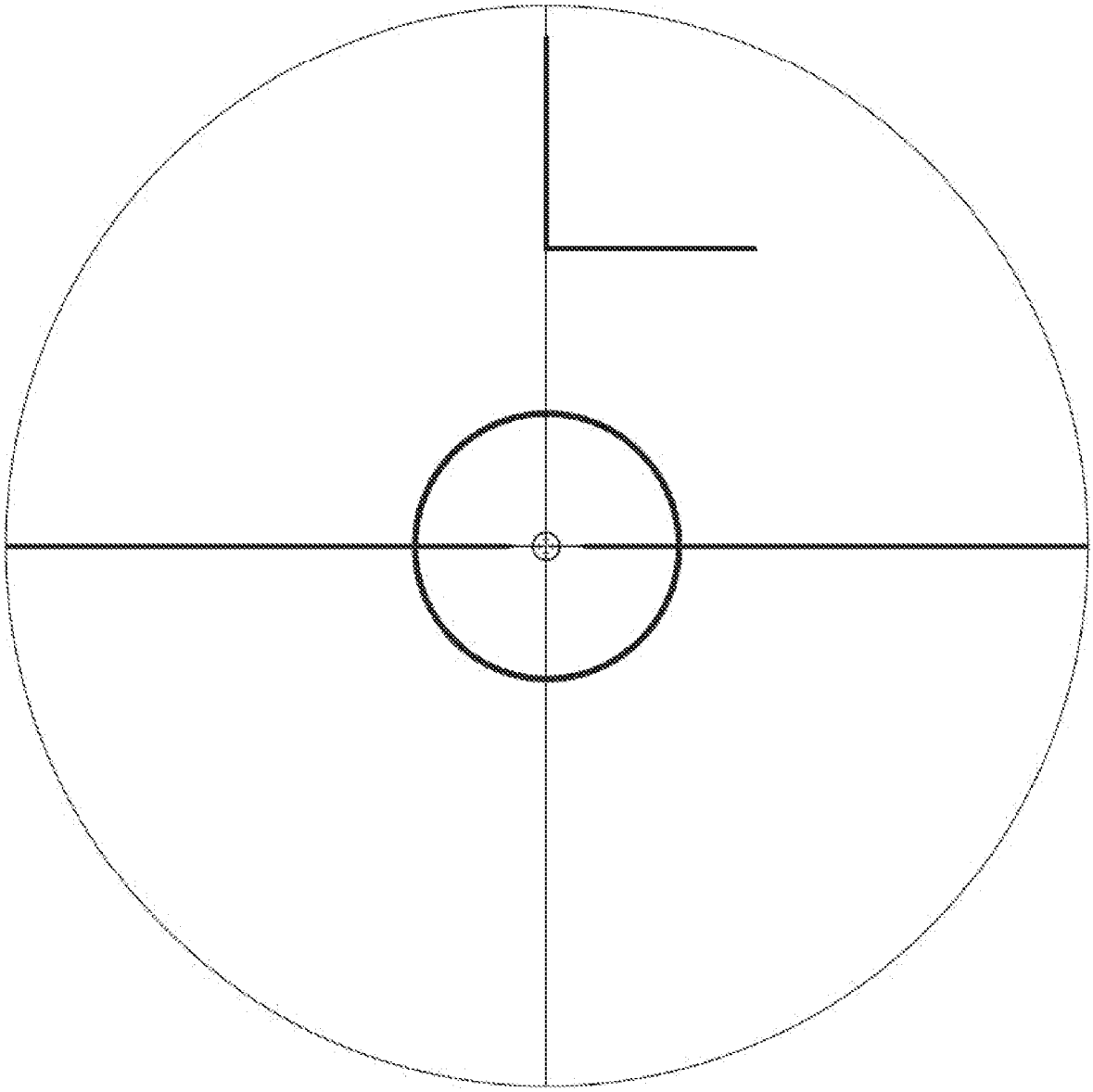


Fig. 74B

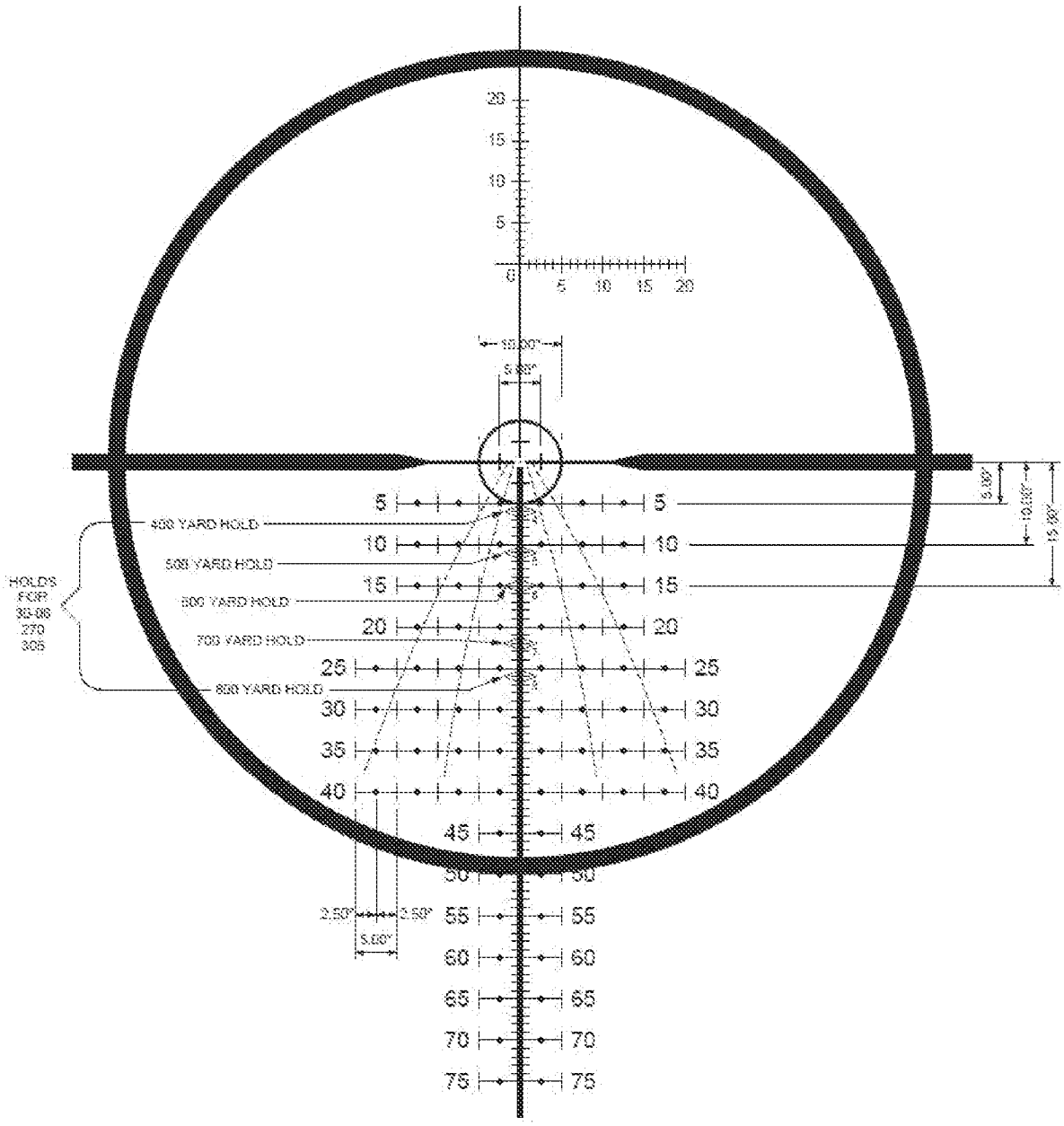

20
15
10
5
0
5 10 15 20
5
10
15
20
25
30
35
40
45
50
55
60
65
70
75
400 YARD HOLD
500 YARD HOLD
600 YARD HOLD
700 YARD HOLD
800 YARD HOLD
HOLDS
FOR
MOA
270
308
2.50"
5.00"

Fig. 74C

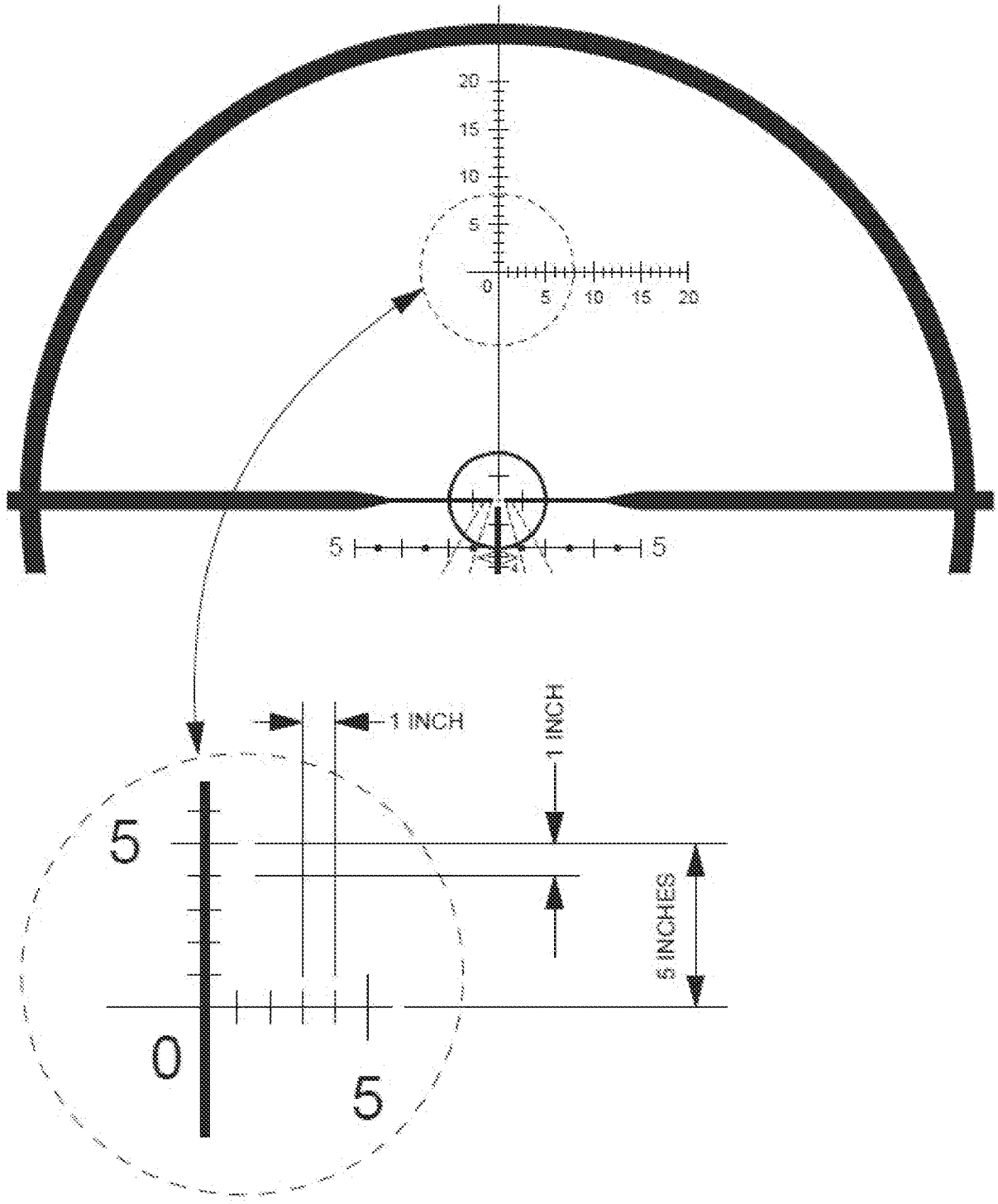
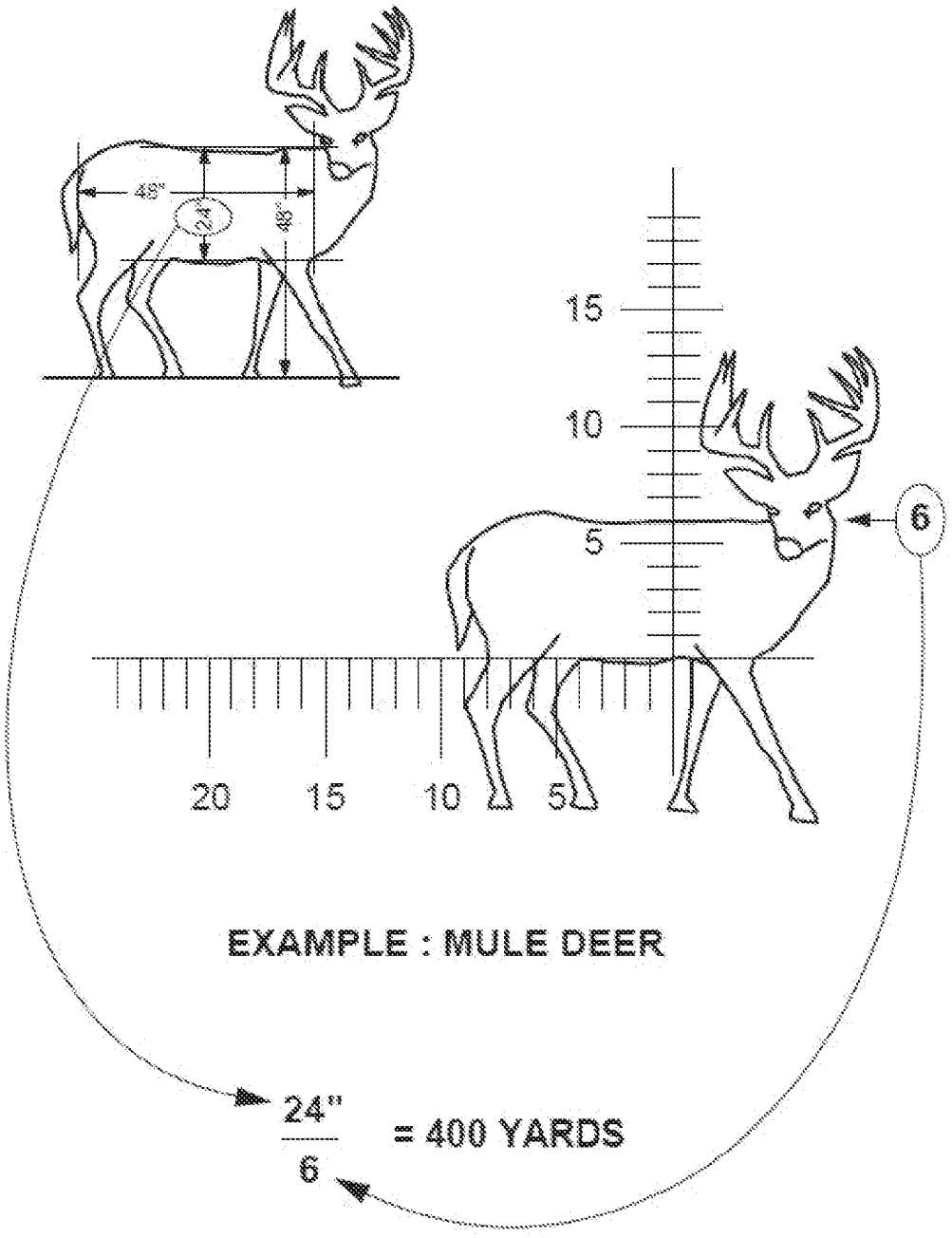
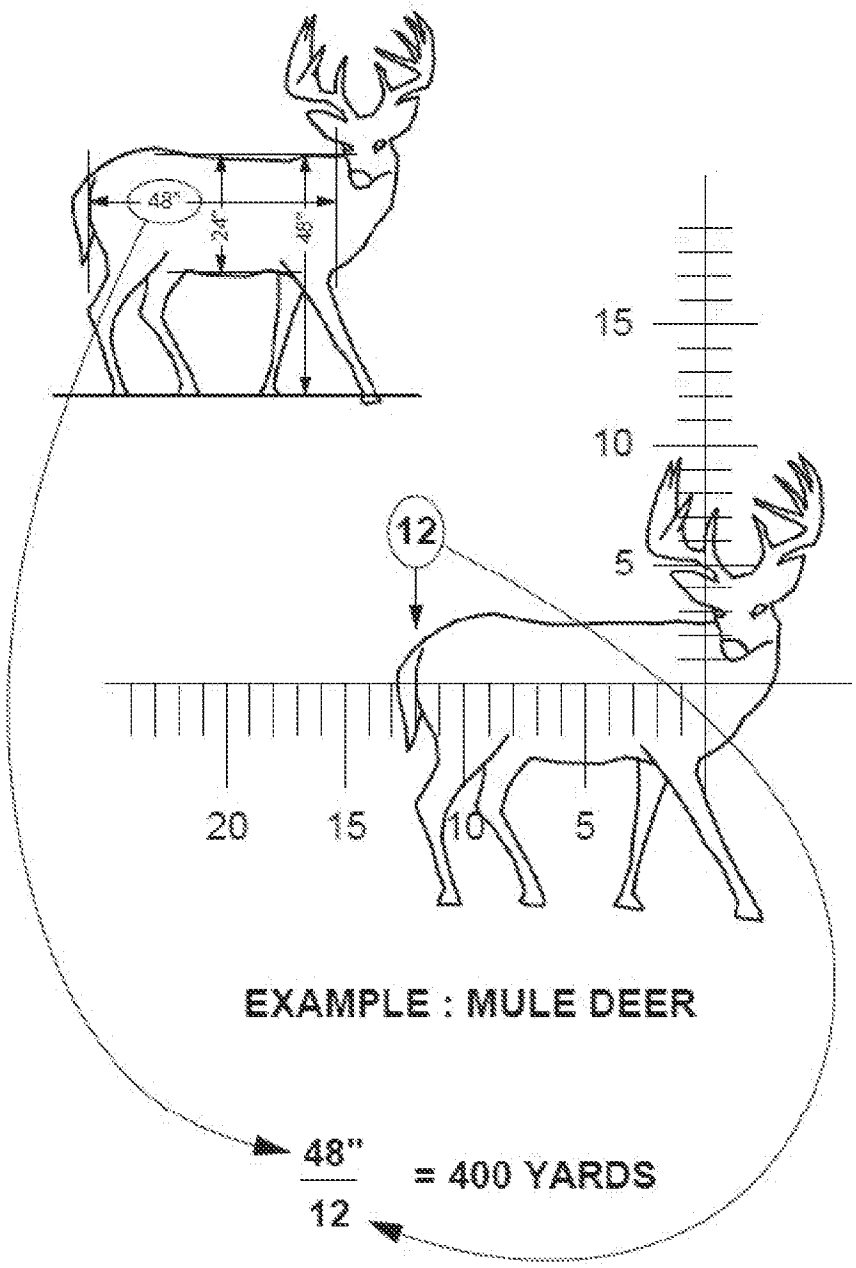


Fig. 74D



ANIMAL CHEST HEIGHT (24")
RANGEFINDER MEASUREMENT (6)
X 100 = 400 YARDS

Fig. 74E



ANIMAL CHEST HEIGHT (48")

RANGEFINDER MEASUREMENT (12) X 100 = 400 YARDS

Fig. 74F

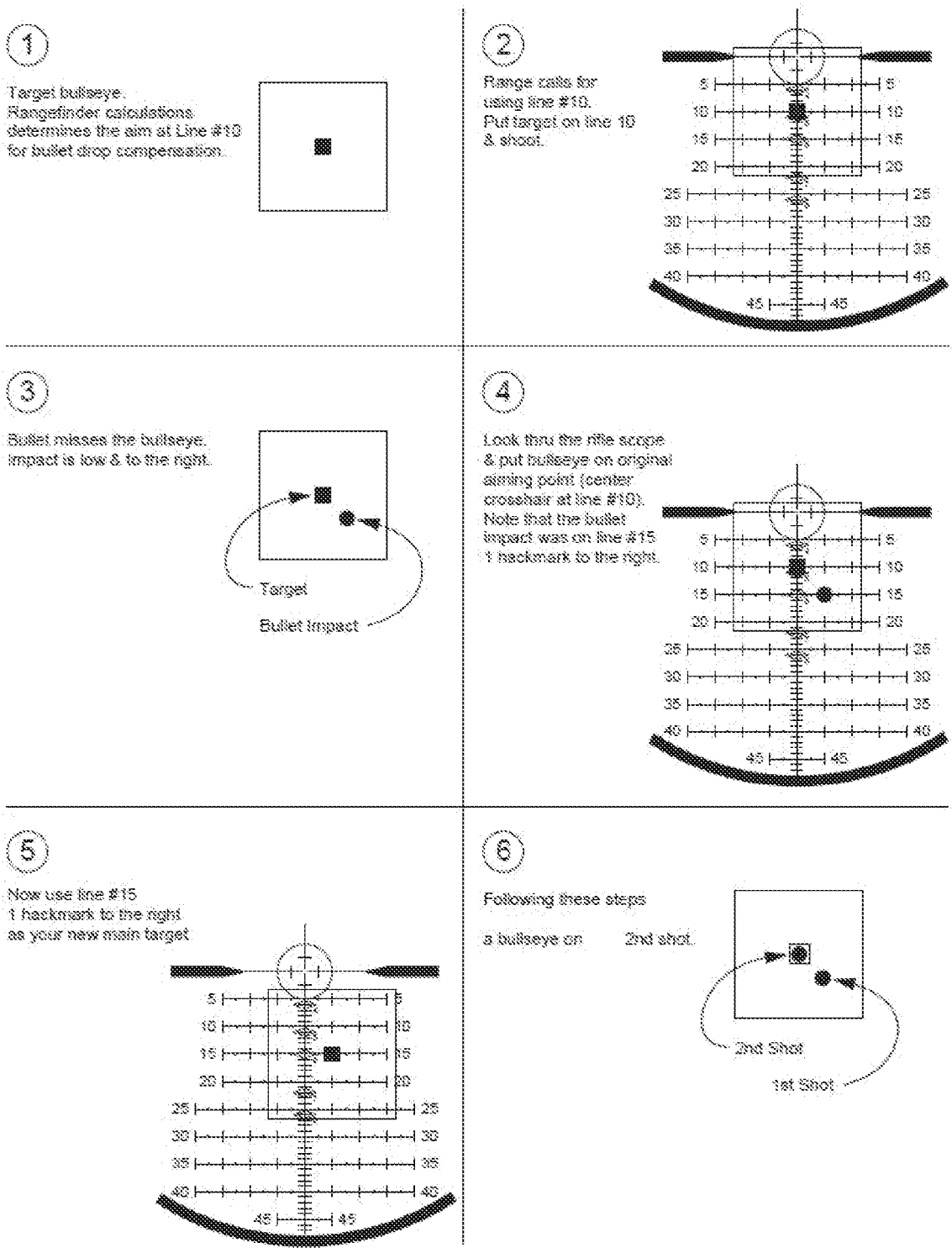

1
Target bullseye.
Rangefinder calculations
determines the aim at Line #10
for bullet drop compensation.
2
Range calls for
using line #10.
Put target on line 10
& shoot.
3
Bullet misses the bullseye.
Impact is low & to the right.
Target
Bullet Impact
4
Look thru the rifle scope
& put bullseye on original
aiming point (center
crosshair at line #10).
Note that the bullet
impact was on line #15
1 hackmark to the right.
5
Now use line #15
1 hackmark to the right
as your new main target
6
Following these steps
a bullseye on 2nd shot.
2nd Shot
1st Shot

Fig. 74G

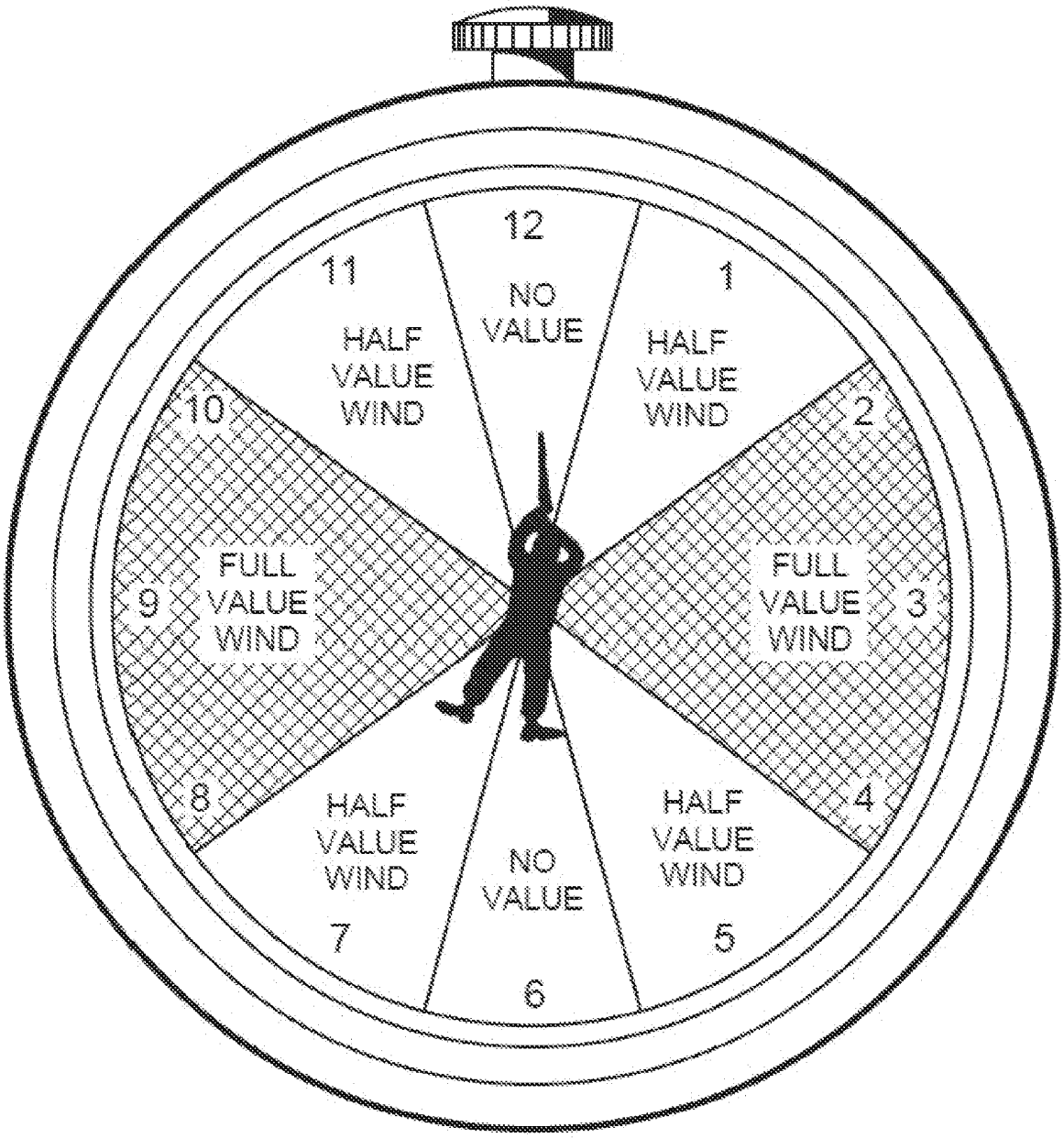

12
NO VALUE
1
HALF VALUE WIND
2
FULL VALUE WIND
3
4
HALF VALUE WIND
5
6
NO VALUE
7
HALF VALUE WIND
8
FULL VALUE WIND
9
10
HALF VALUE WIND
11

Fig. 75

Info: 308 WIN (7.62) 175 gr. MATCH
B.C. .498 @ 2600 FT/SEC
Full Value Wind 10MPH

Distance Yards	Elevation Inches	Wind Inches
100	0.00	0.60
150	0.80	1.00
200	2.00	1.50
250	3.50	1.90
300	5.00	2.30
350	6.70	2.80
400	8.40	3.20
450	10.30	3.60
500	12.40	4.20
550	14.60	4.20
600	16.90	4.70
650	19.30	5.20
700	21.90	5.80
750	24.60	6.30
800	27.50	6.90
850	30.00	7.50
900	34.00	8.10
950	37.40	8.80
1000	41.20	9.40
1050	45.20	10.10
1100	49.40	11.50
1150	53.80	12.20
1200	58.50	12.80

Info: 223 rem (5.56) 77 gr. MATCH
B.C. .372 @ 3500 FT/SEC
Full Value Wind 10MPH

Distance Yards	Elevation Inches	Wind Inches
100	0.00	0.90
150	0.20	1.30
200	1.00	1.70
250	2.10	2.20
300	3.30	2.80
350	4.70	3.30
400	6.30	3.80
450	8.00	4.40
500	9.80	5.50
550	11.90	5.70
600	14.10	6.40
650	16.50	7.10
700	19.10	7.80
750	21.90	8.60
800	25.00	9.50
850	28.40	10.30
900	32.00	11.10
950	36.00	12.00
1000	40.30	12.90
1050	44.80	13.80
1100	49.70	14.70
1150	54.80	15.50
1200	60.20	16.40

Fig. 76A

Info: 30-06 WIN SST 180 gr.
B.C. .501 @ 2800 FT/SEC
Full Value Wind 10MPH

Distance Yards	Elevation Inches	Wind Inches
100	0.00	0.70
150	0.60	1.00
200	1.50	1.30
250	2.70	1.70
300	4.00	2.10
350	5.40	2.50
400	6.90	2.90
450	8.50	3.30
500	10.20	3.70
550	11.90	4.10
600	13.90	4.60
650	15.30	5.10
700	18.10	5.60
750	20.40	6.10
800	22.80	6.70
850	25.40	7.20
900	28.10	7.80
950	31.00	8.40
1000	34.20	9.00
1050	37.40	9.60
1100	40.90	10.20
1150	44.70	10.90
1200	48.60	11.50

Info: 300 WIN MAG 200 gr. Nosler P.
B.C. .461 @ 2850 FT/SEC
Full Value Wind 10MPH

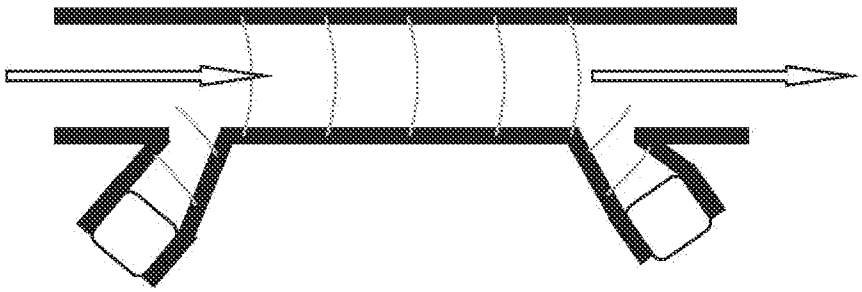
Distance Yards	Elevation Inches	Wind Inches
100	0.00	0.70
150	0.50	1.00
200	1.50	1.40
250	2.60	1.70
300	3.80	2.10
350	5.20	2.50
400	6.70	2.90
450	8.20	3.30
500	9.90	3.80
550	11.60	4.20
600	13.50	4.70
650	15.60	5.20
700	17.70	5.80
750	20.00	6.30
800	22.40	6.80
850	24.90	7.40
900	27.70	8.00
950	30.60	8.60
1000	33.80	9.30
1050	37.10	9.90
1100	40.70	10.60
1150	44.40	11.20
1200	48.50	11.90

Fig. 76B



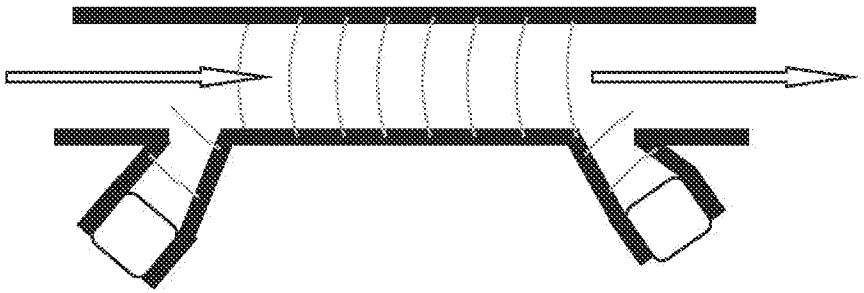
Fig. 77

Fig. 78



Measure from left to right

Fig. 78A



Measure from right to left

Fig. 78B

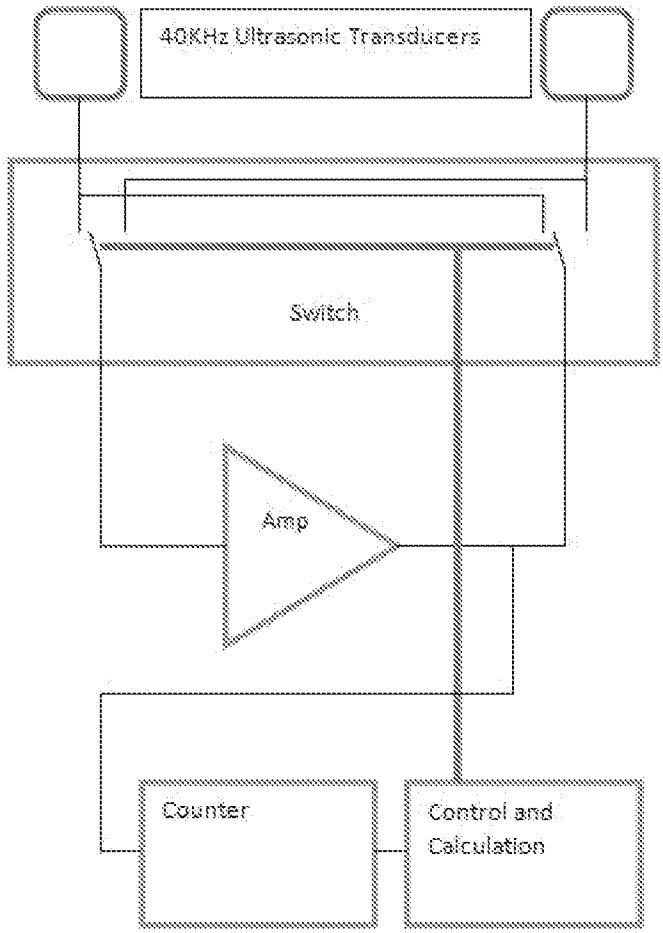

40KHz Ultrasonic Transducers
Switch
Amp
Counter
Control and
Calculation

Fig. 79

Fig. 80



Fig. 80A



Fig. 80B

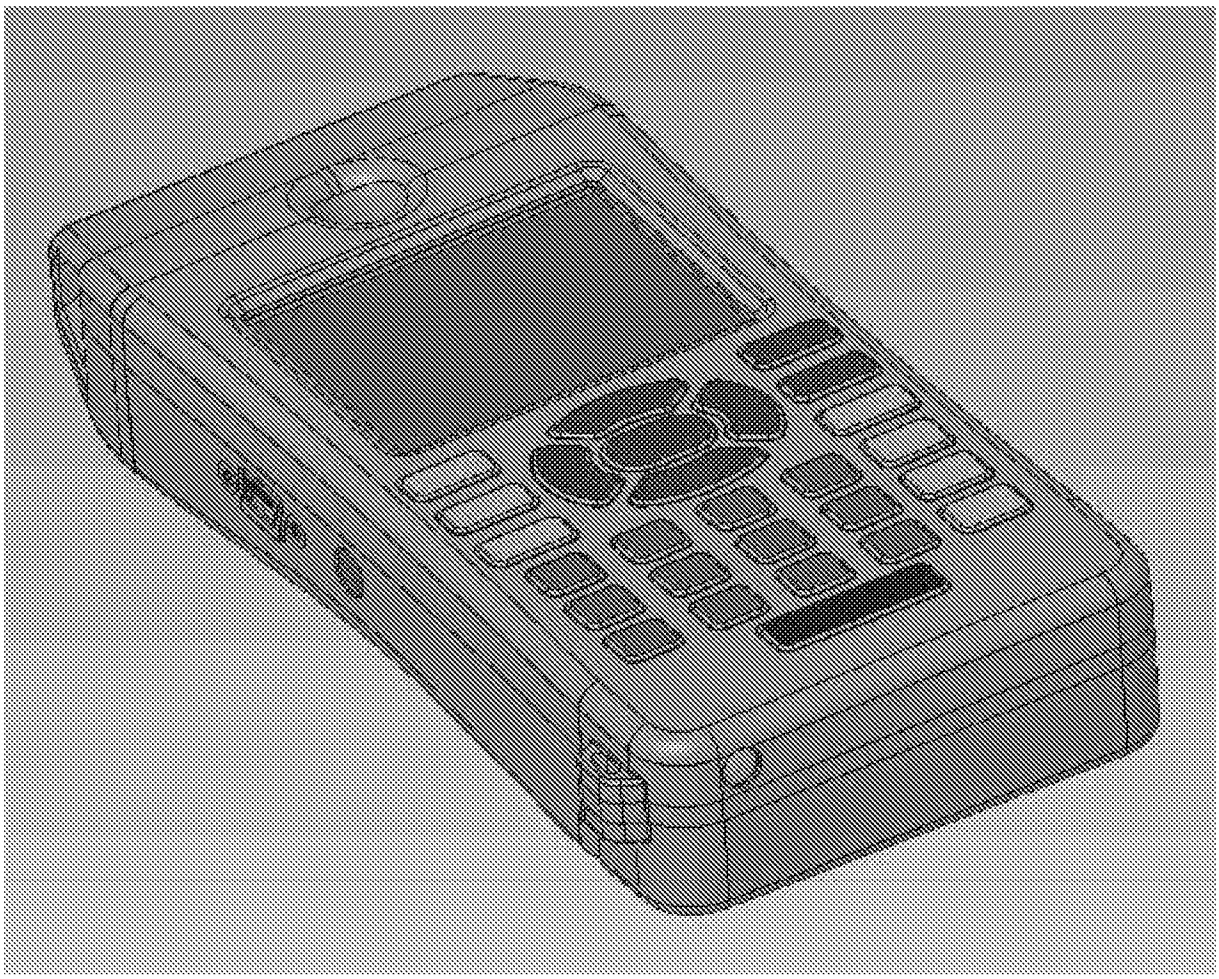


Fig. 81

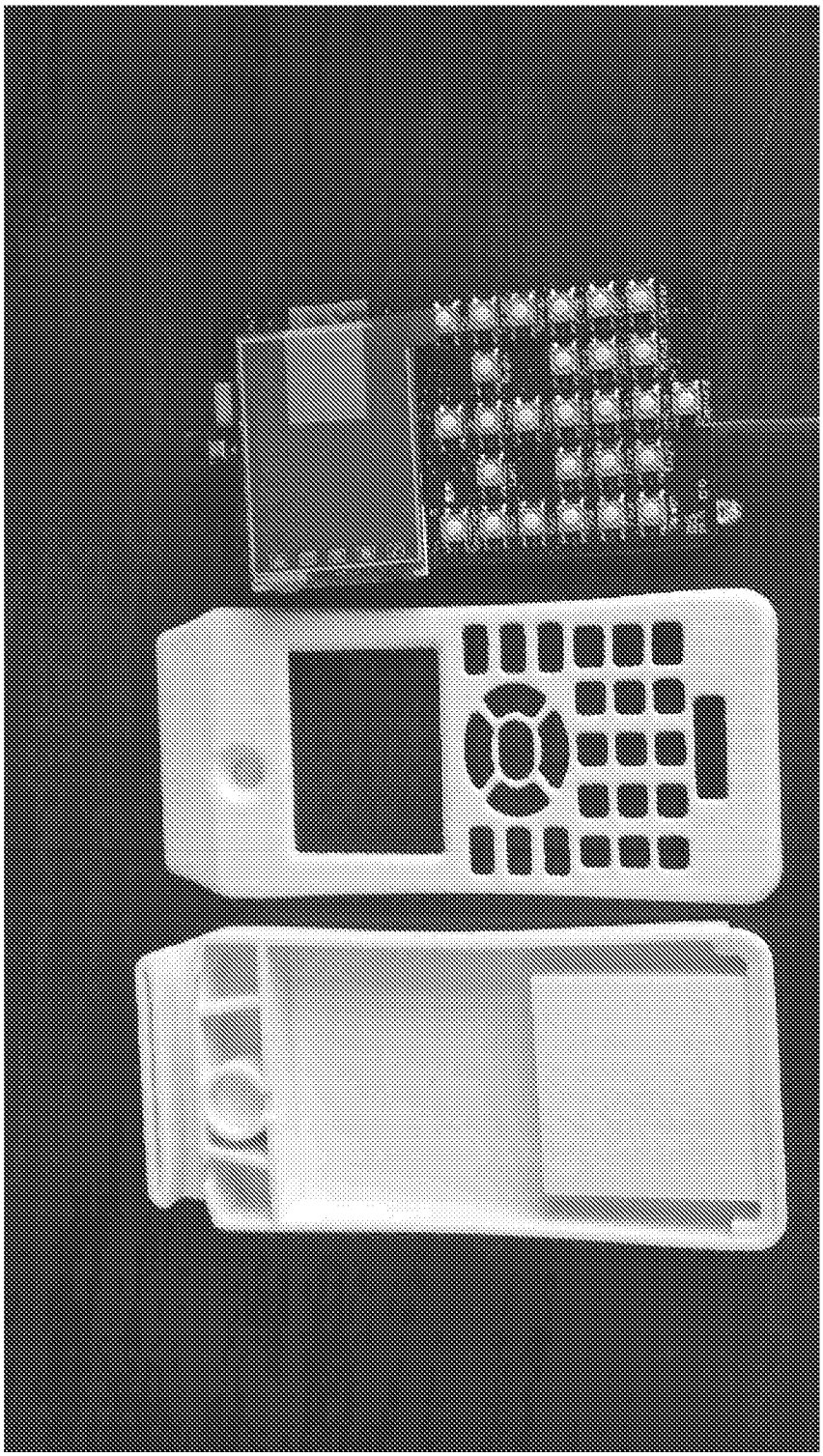


Fig. 82

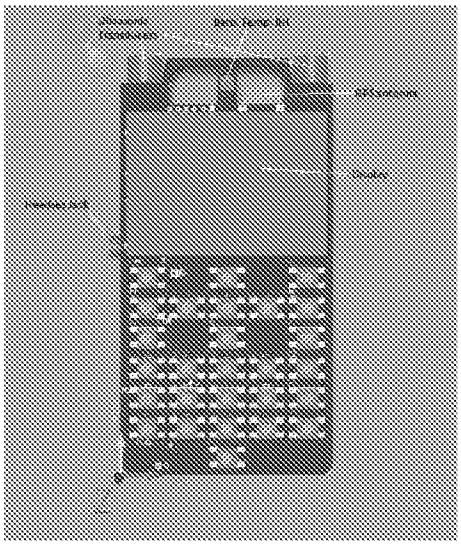


Fig. 83

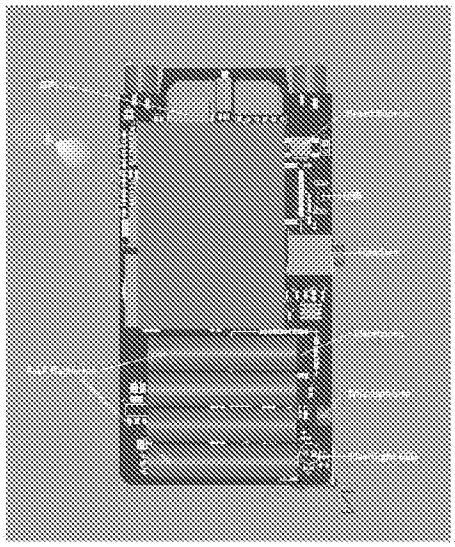


Fig. 84

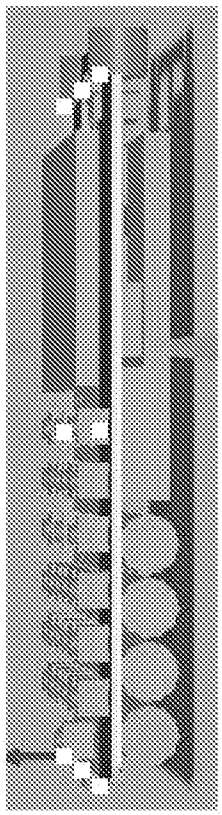


Fig. 85

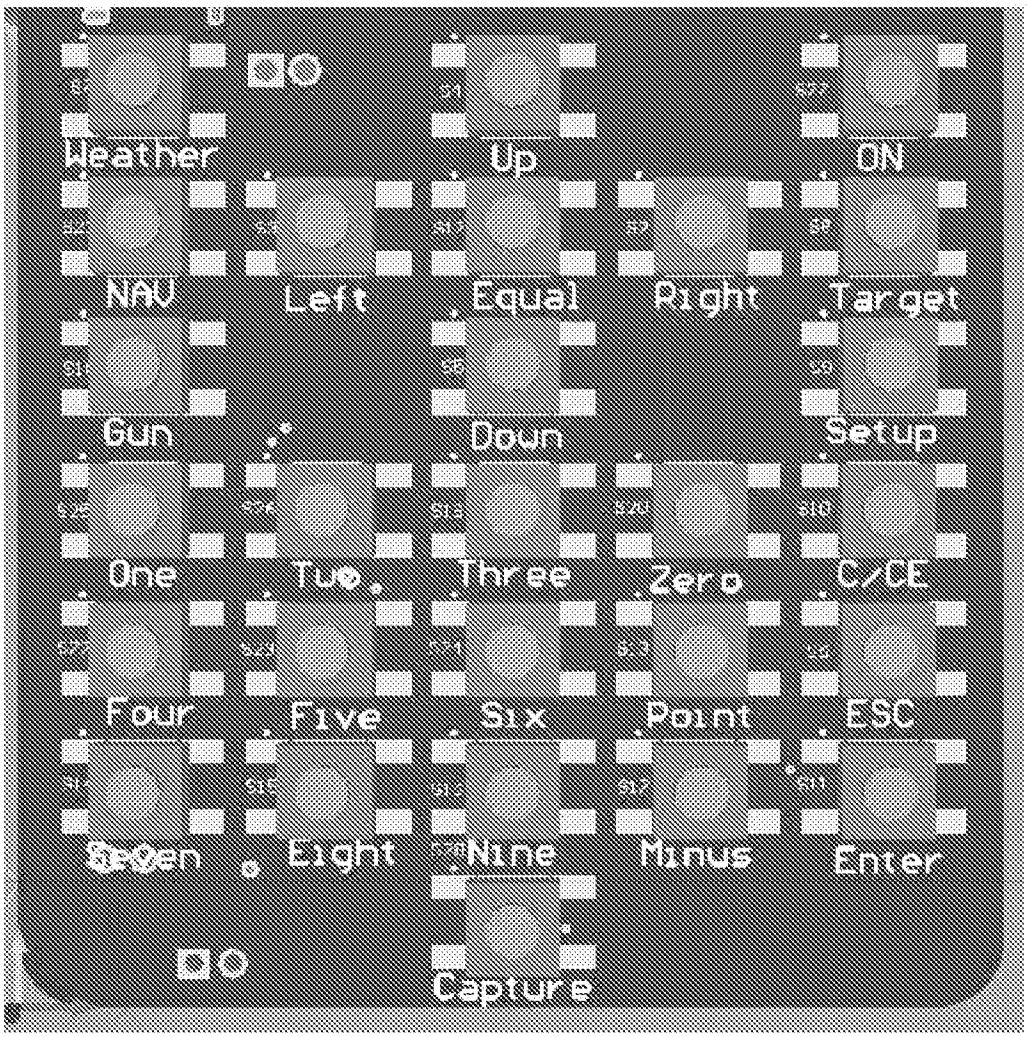

Weather
Up
ON
NAV
Left
Equal
Right
Target
Gun
Down
Setup
One
Two
Three
Zero
C/CE
Four
Five
Six
Point
ESC
Seven
Eight
Nine
Minus
Enter
Capture

Fig. 86



Fig. 87

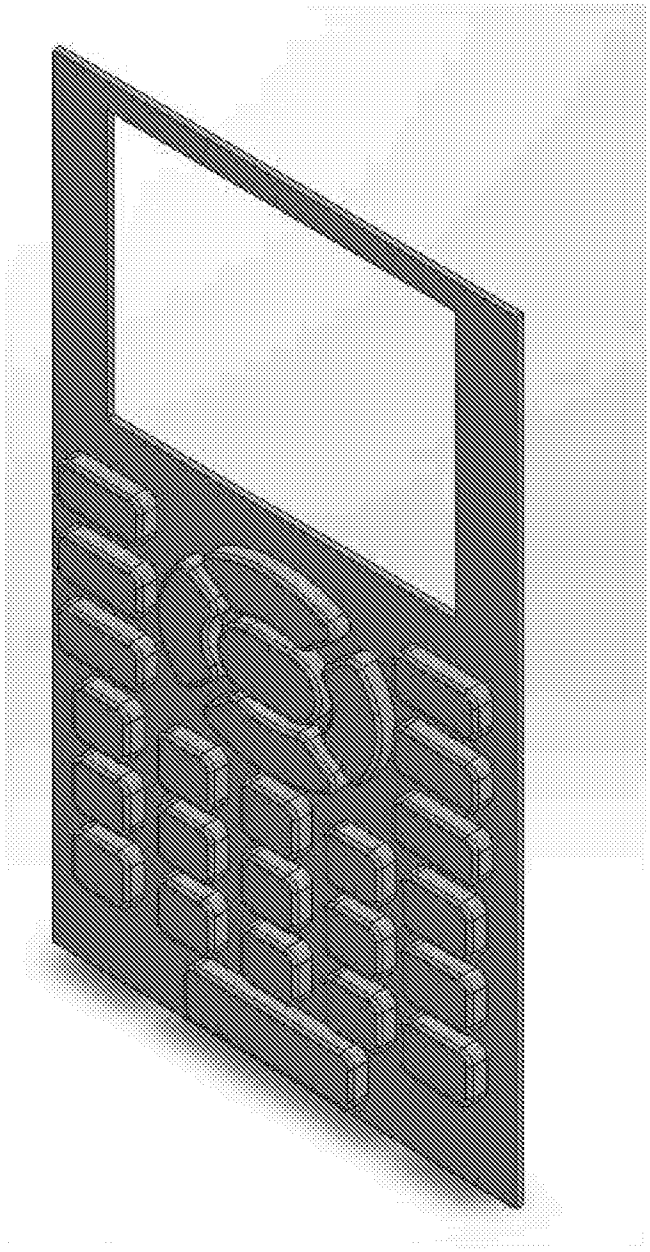


Fig. 88

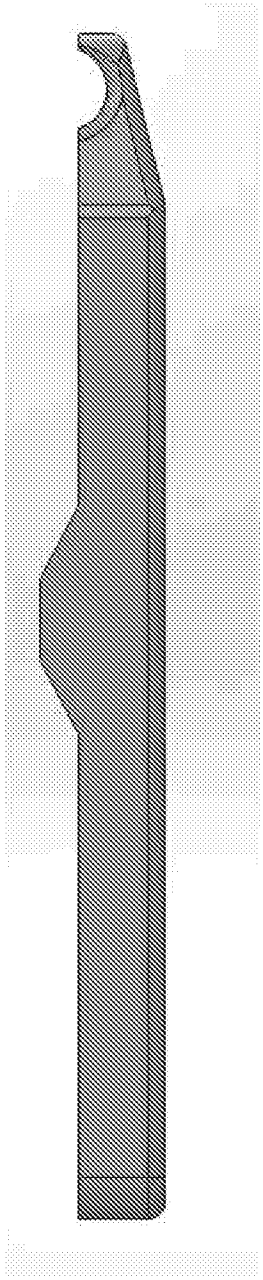


Fig. 89

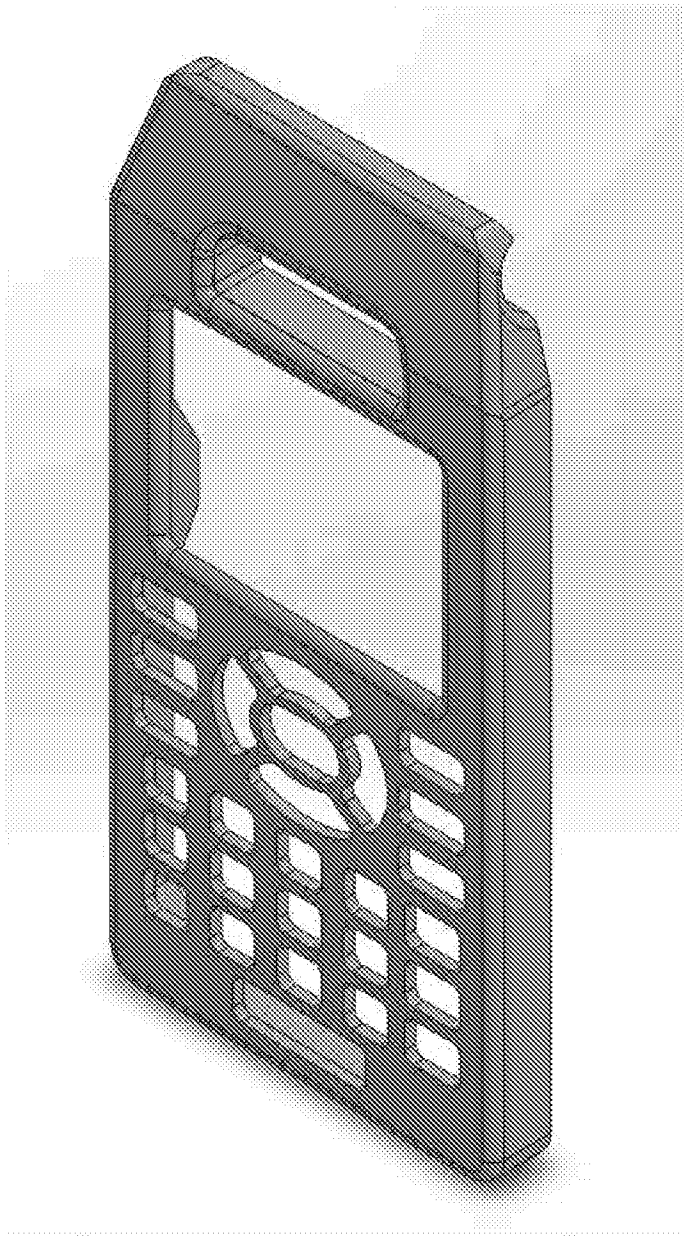


Fig. 90



Fig. 91

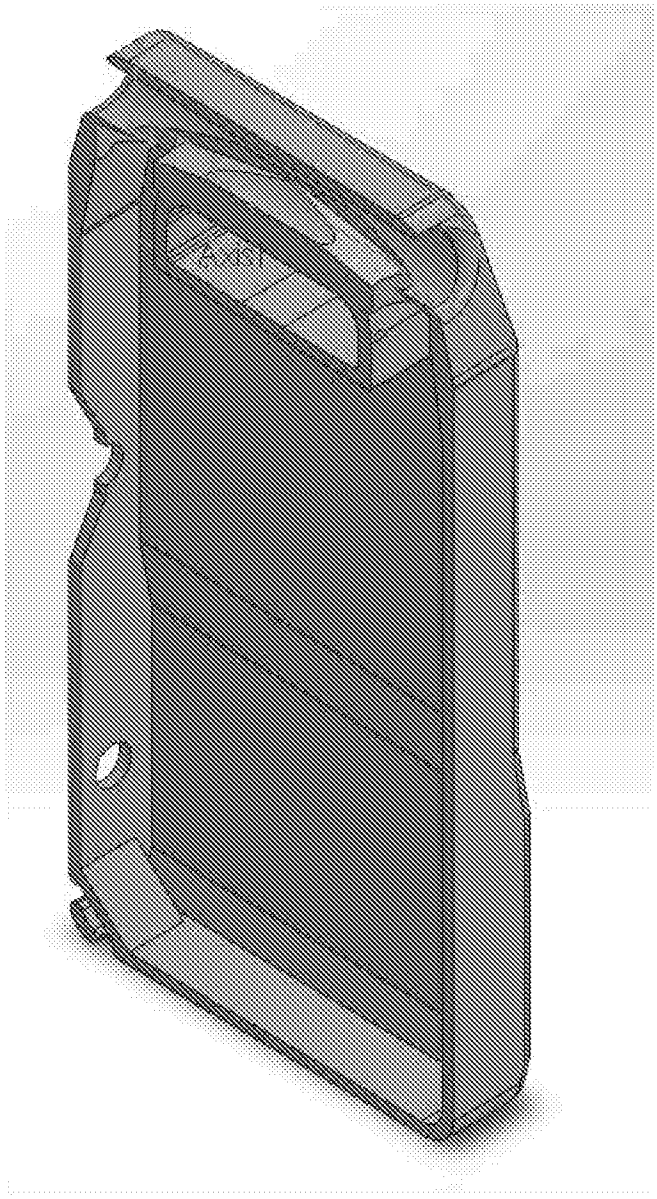


Fig. 92

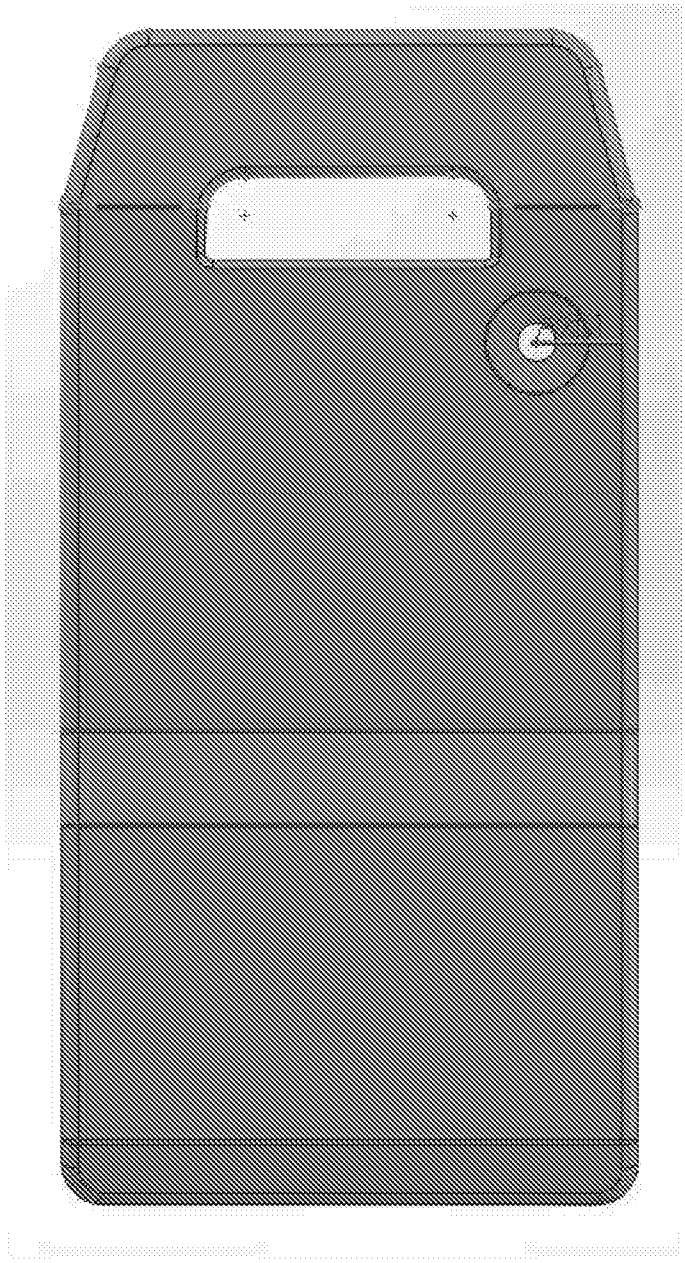


Fig. 93

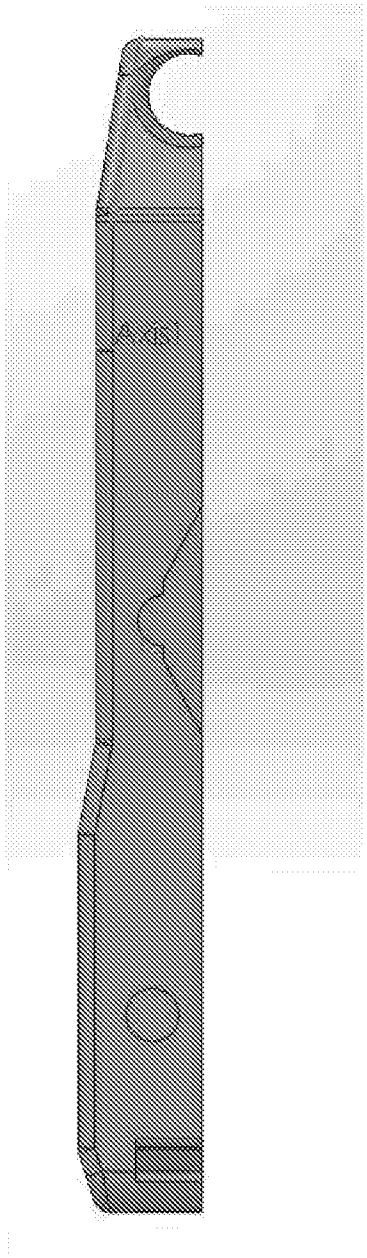


Fig. 94

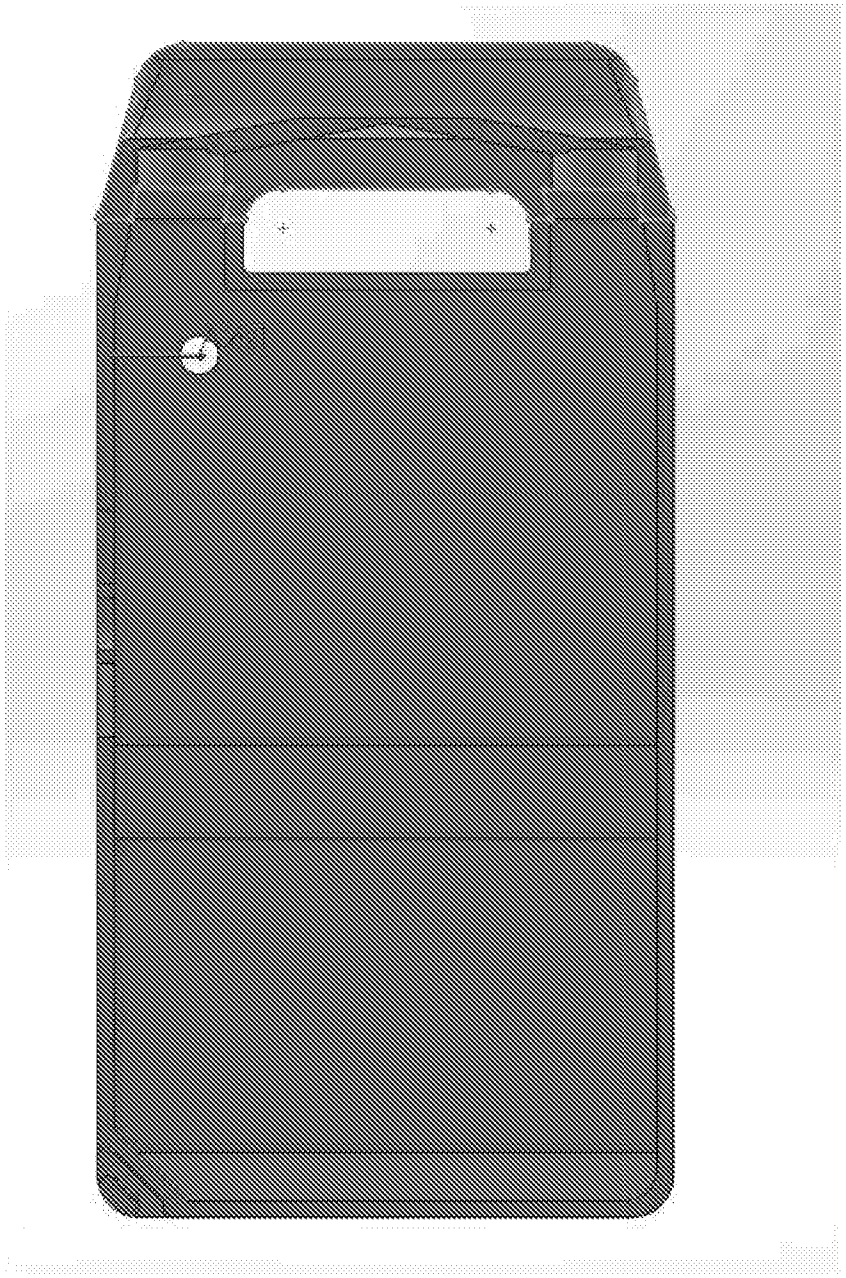


Fig. 95

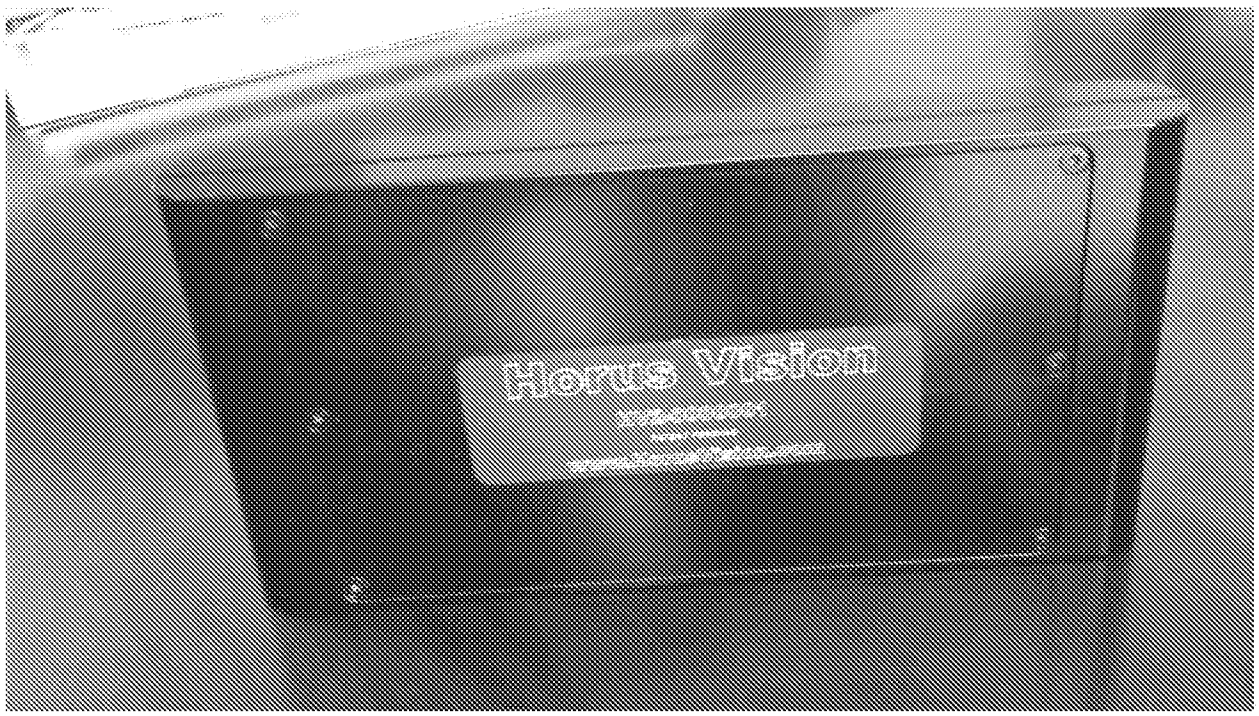


Fig. 96

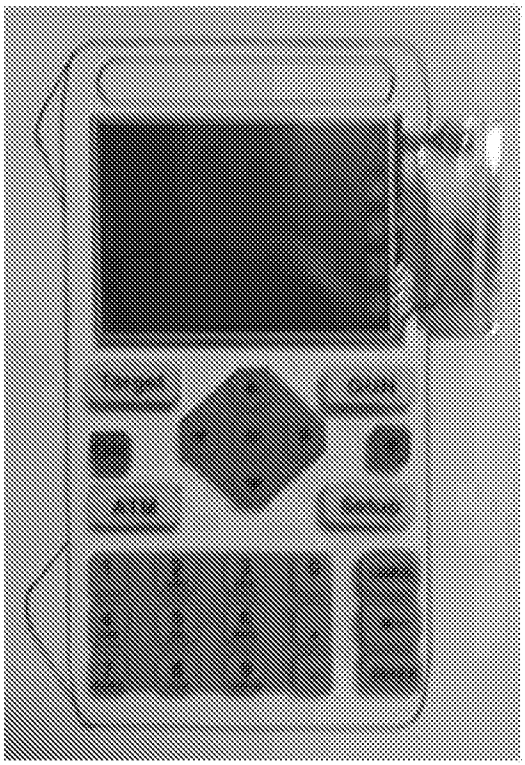


Fig. 97

Fig. 98

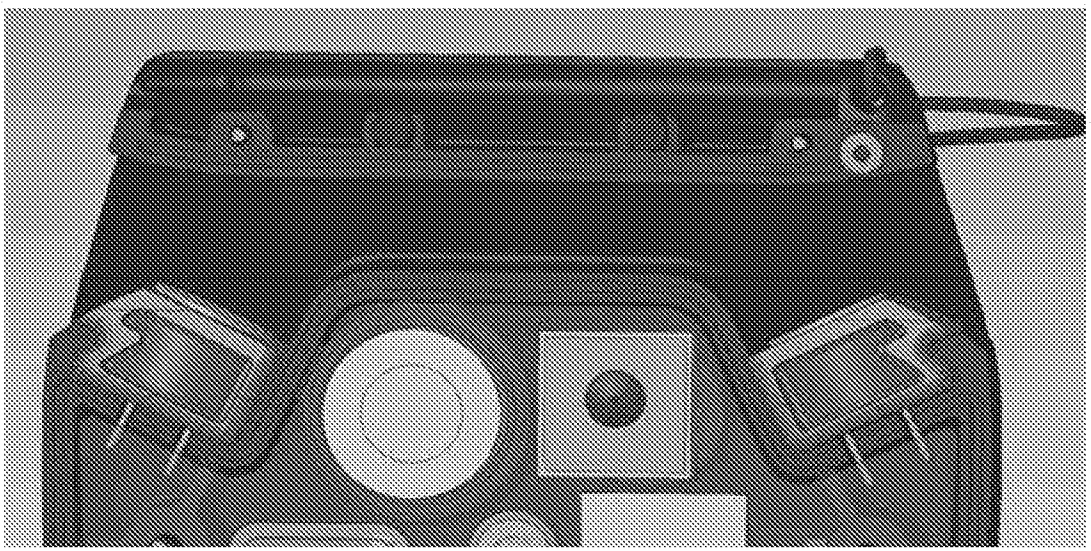
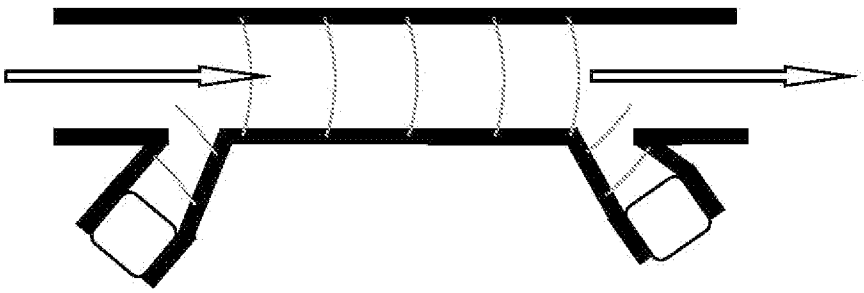
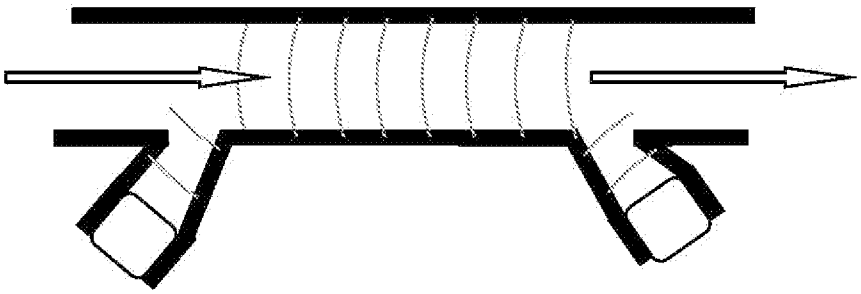


Fig. 78



Measure from left to right

Fig. 78A



Measure from right to left

Fig. 78B

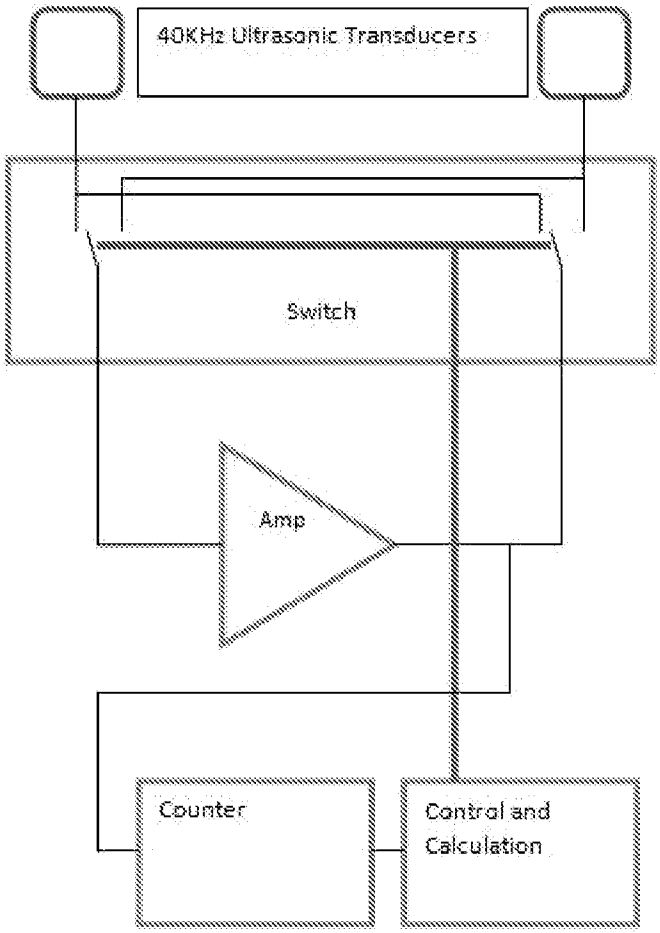

40KHz Ultrasonic Transducers
Switch
Amp
Counter
Control and
Calculation

Fig. 79

Fig. 80



Fig. 80A



Fig. 80B

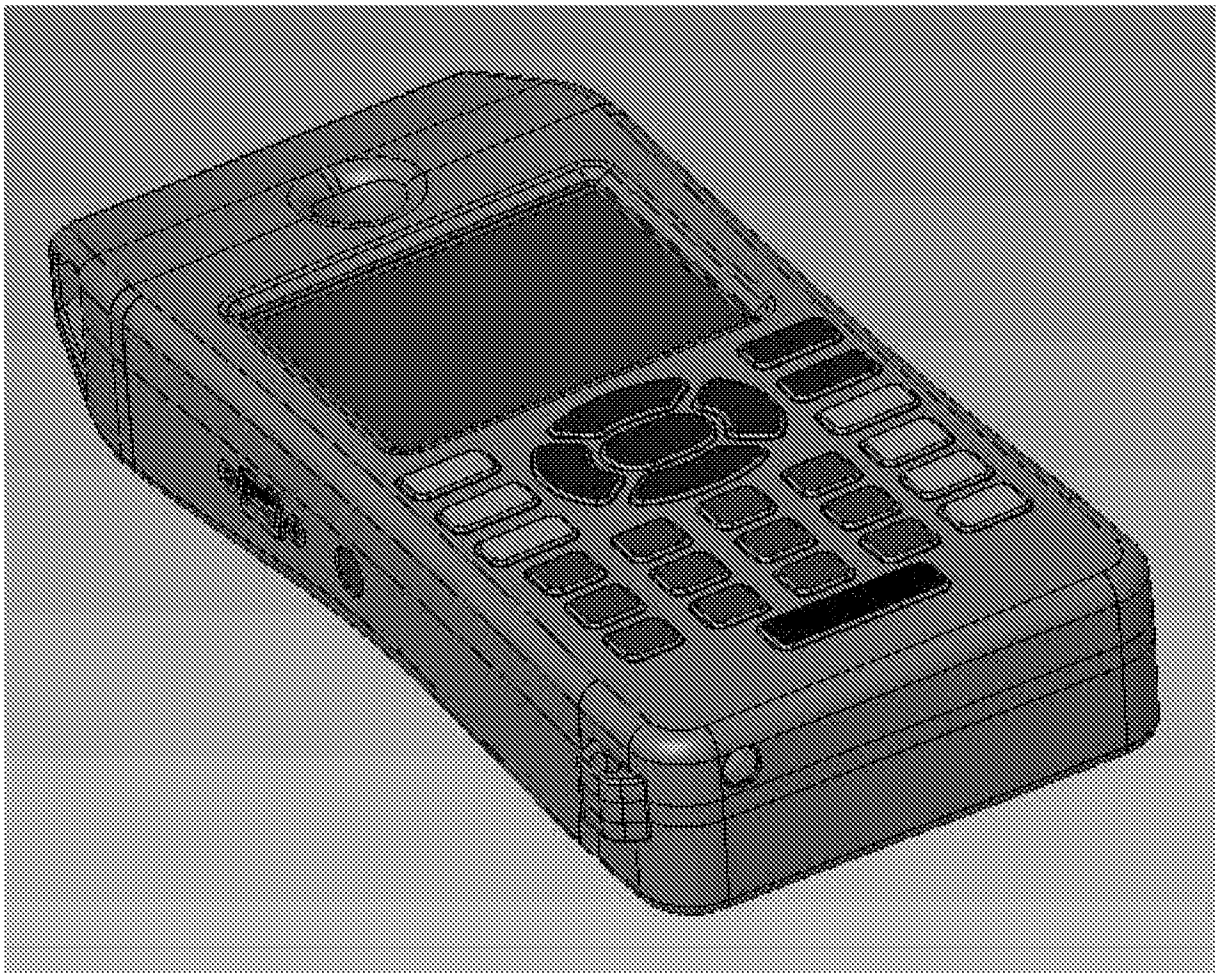


Fig. 81

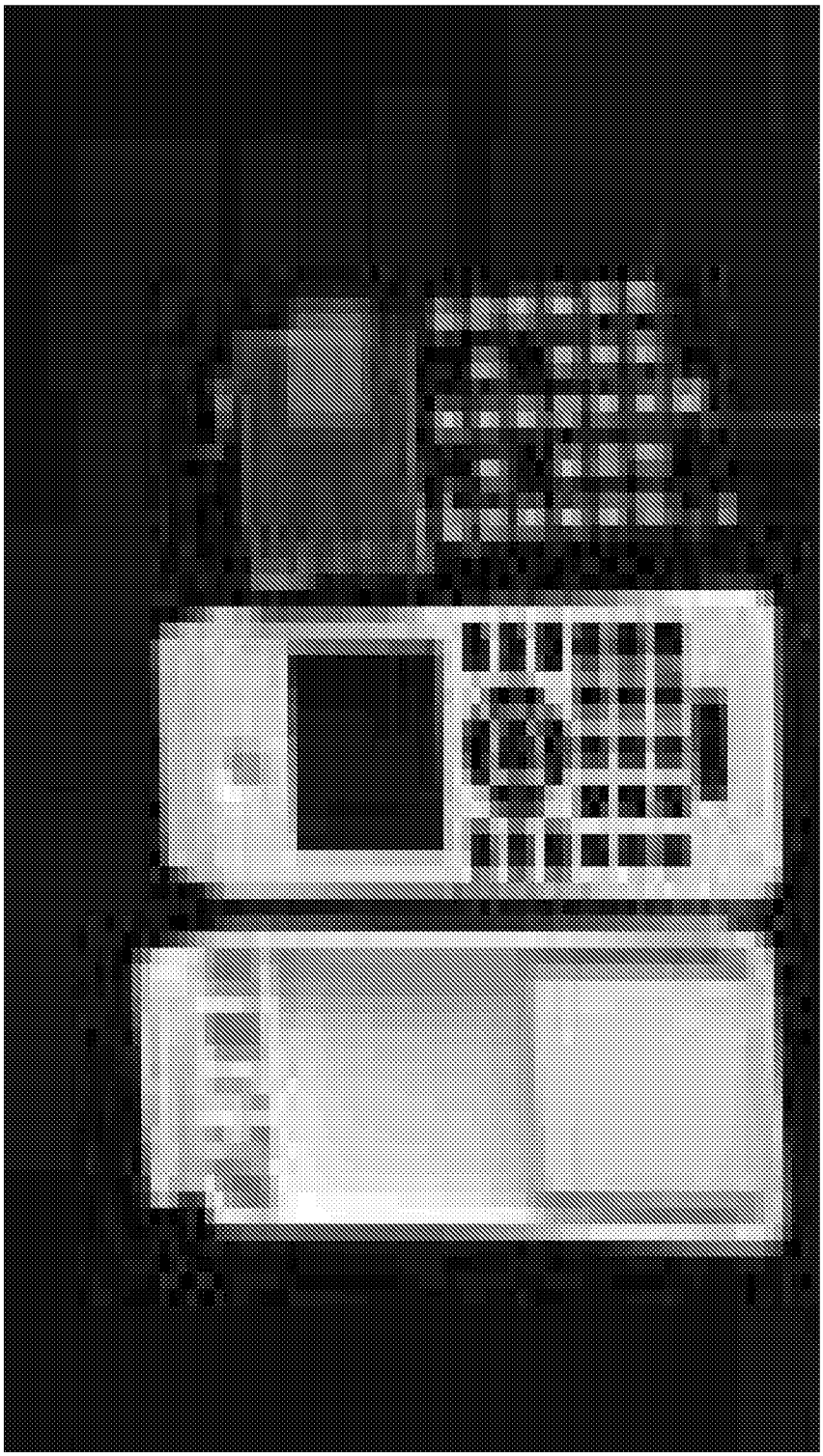


Fig. 82

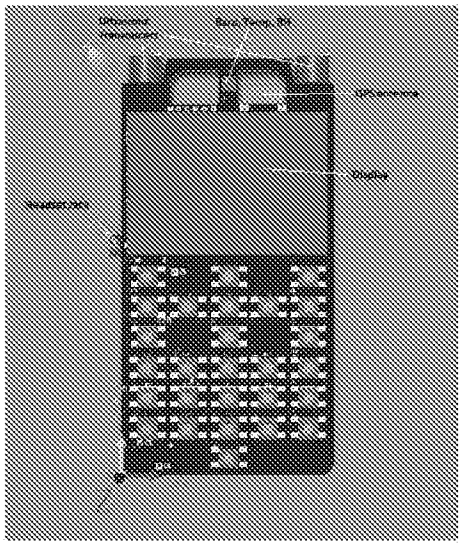


Fig. 83

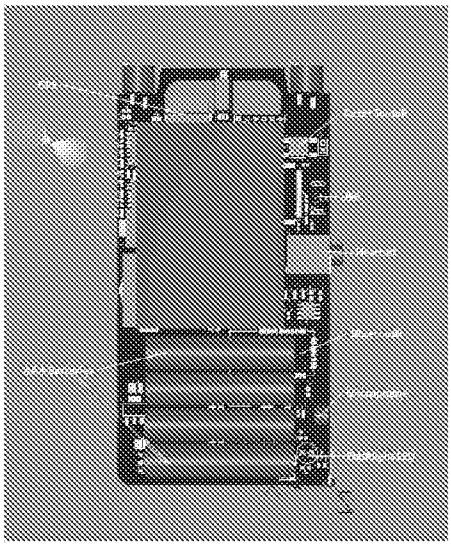


Fig. 84

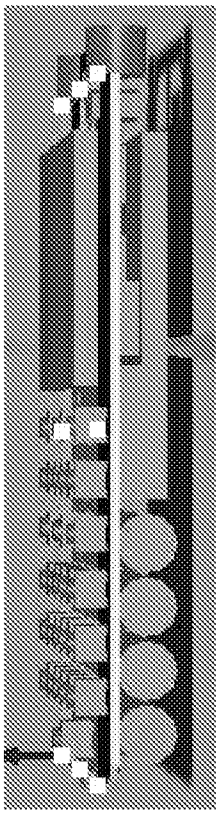


Fig. 85

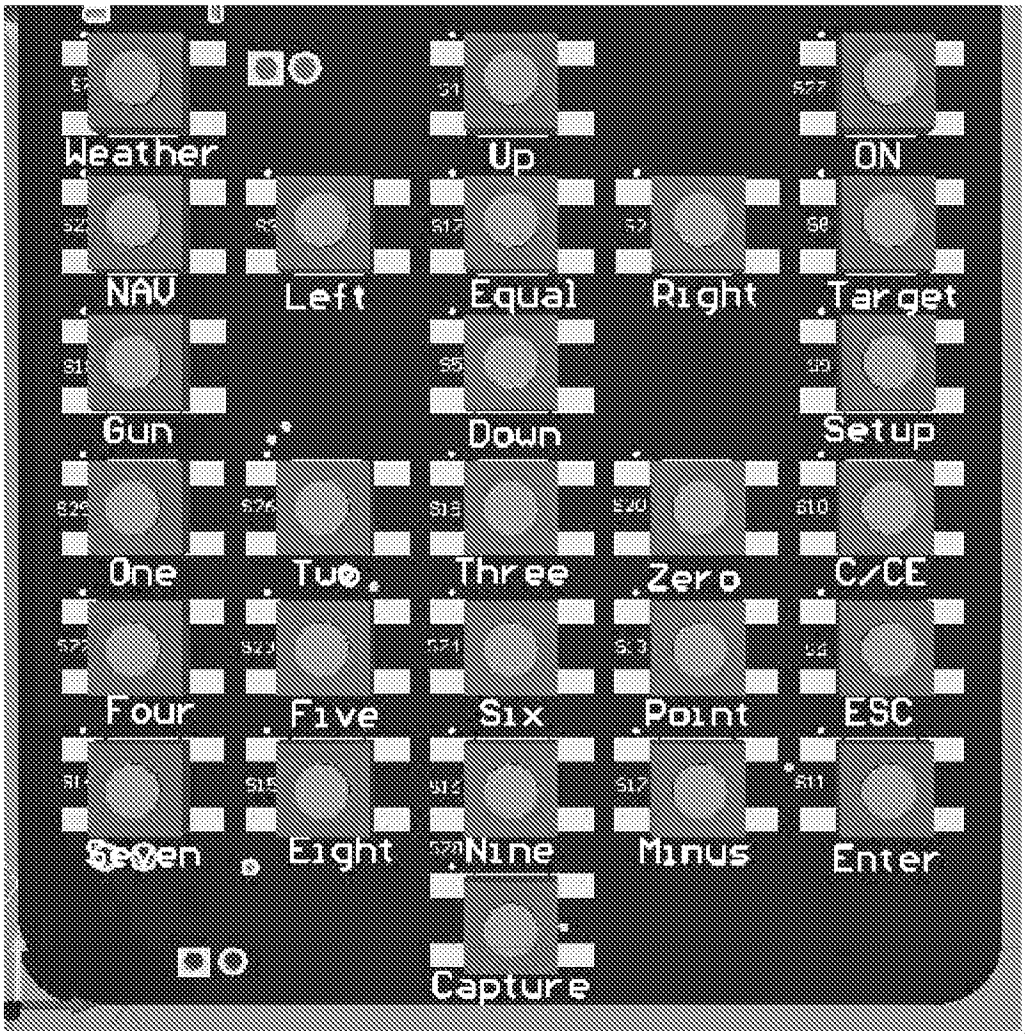

Weather
Up
ON
NAV
Left
Equal
Right
Target
Gun
Down
Setup
One
Two
Three
Zero
C/CE
Four
Five
Six
Point
ESC
Seven
Eight
Nine
Minus
Enter
Capture

Fig. 86



Fig. 87

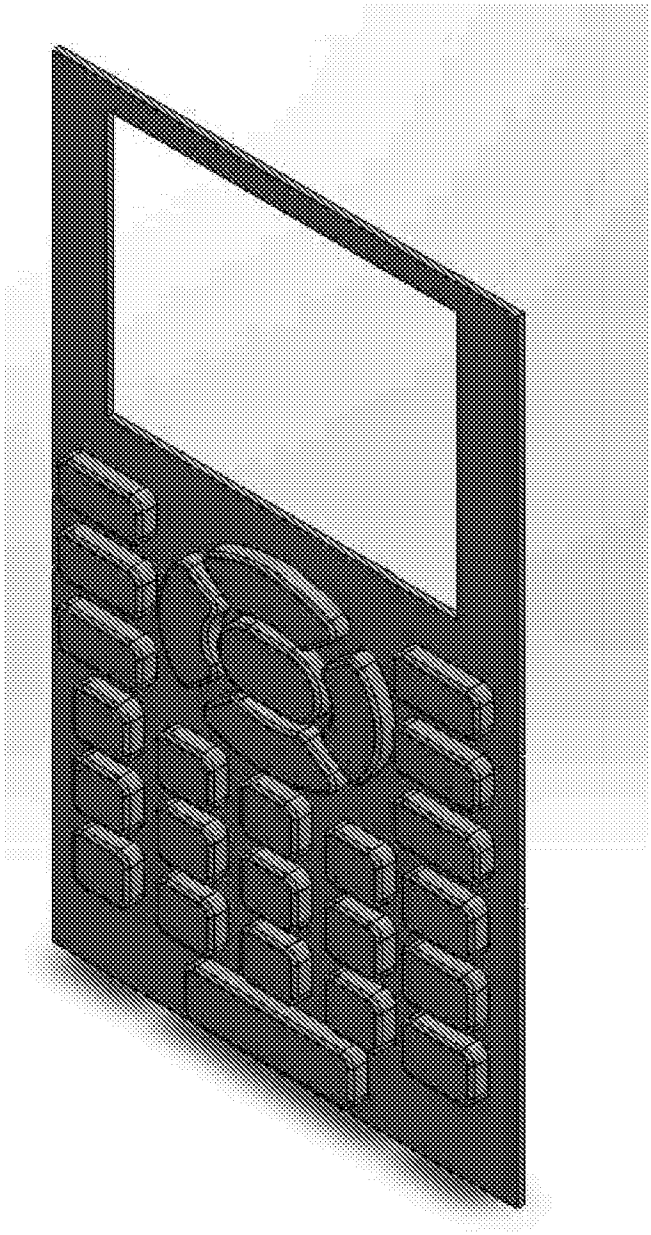


Fig. 88

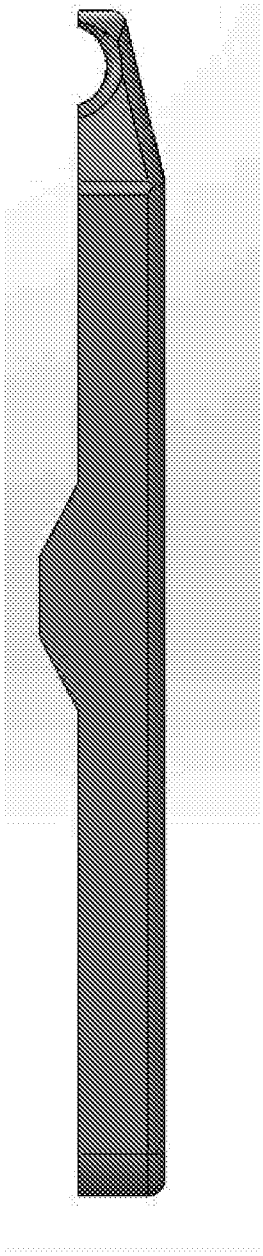


Fig. 89

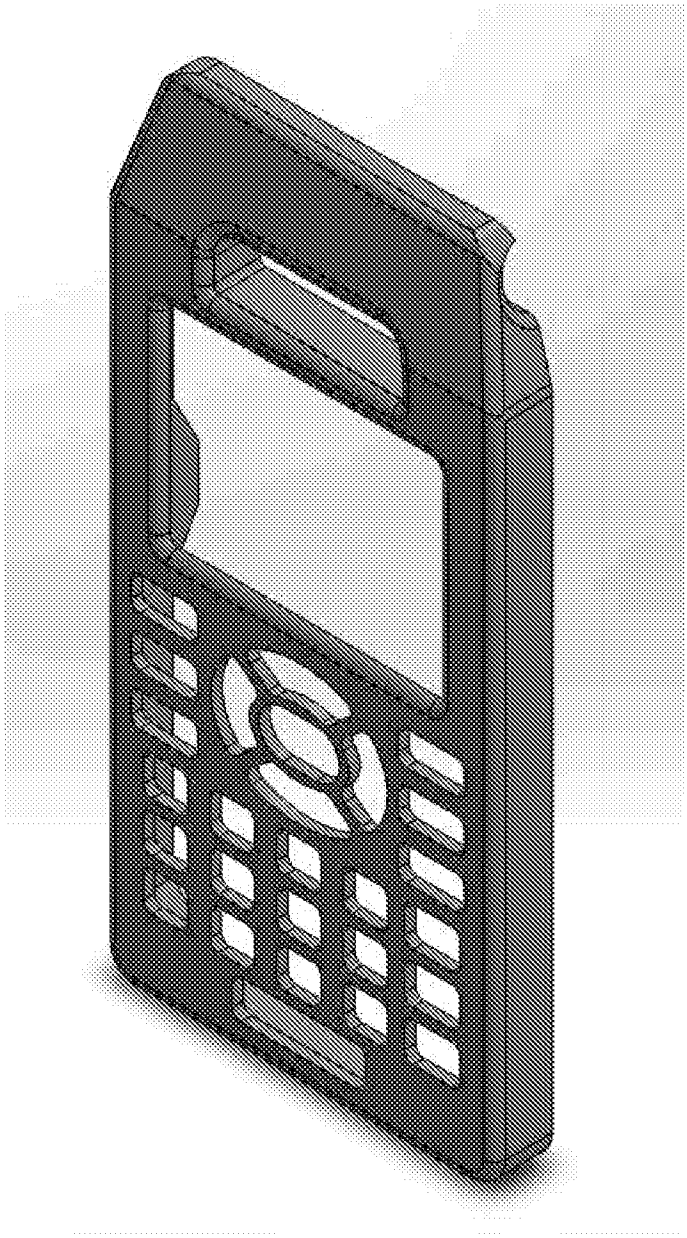


Fig. 90



Fig. 91

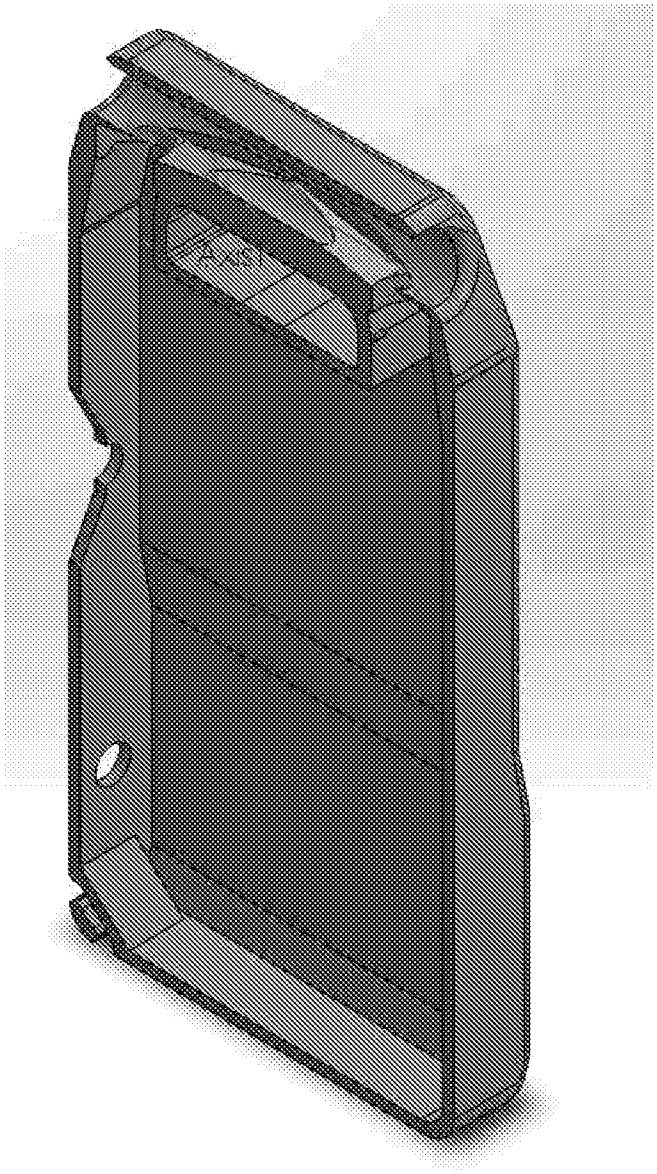


Fig. 92

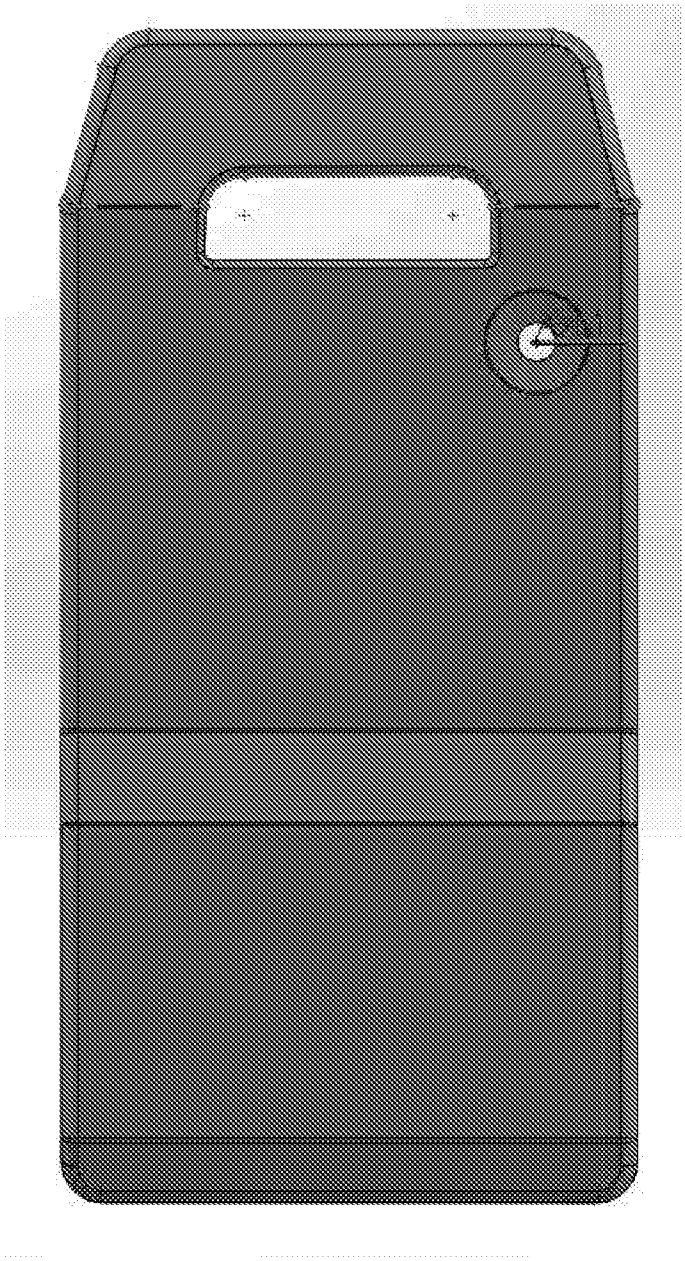


Fig. 93

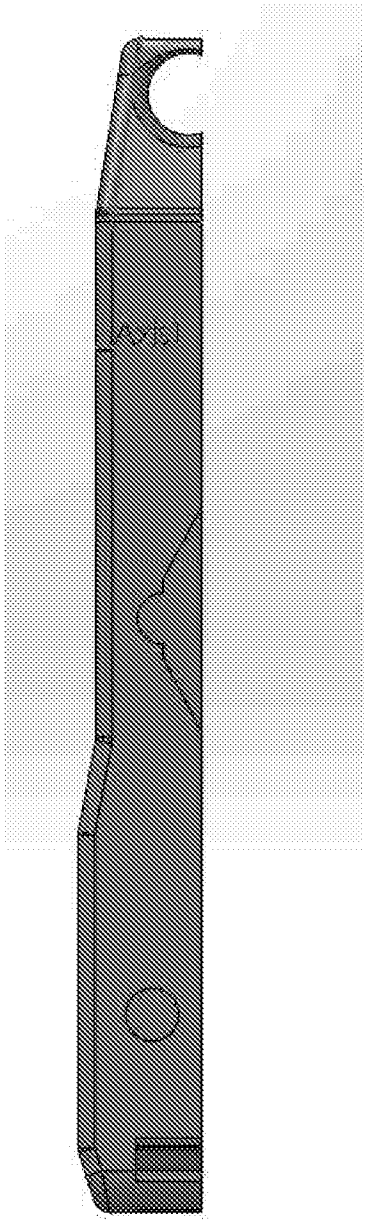


Fig. 94

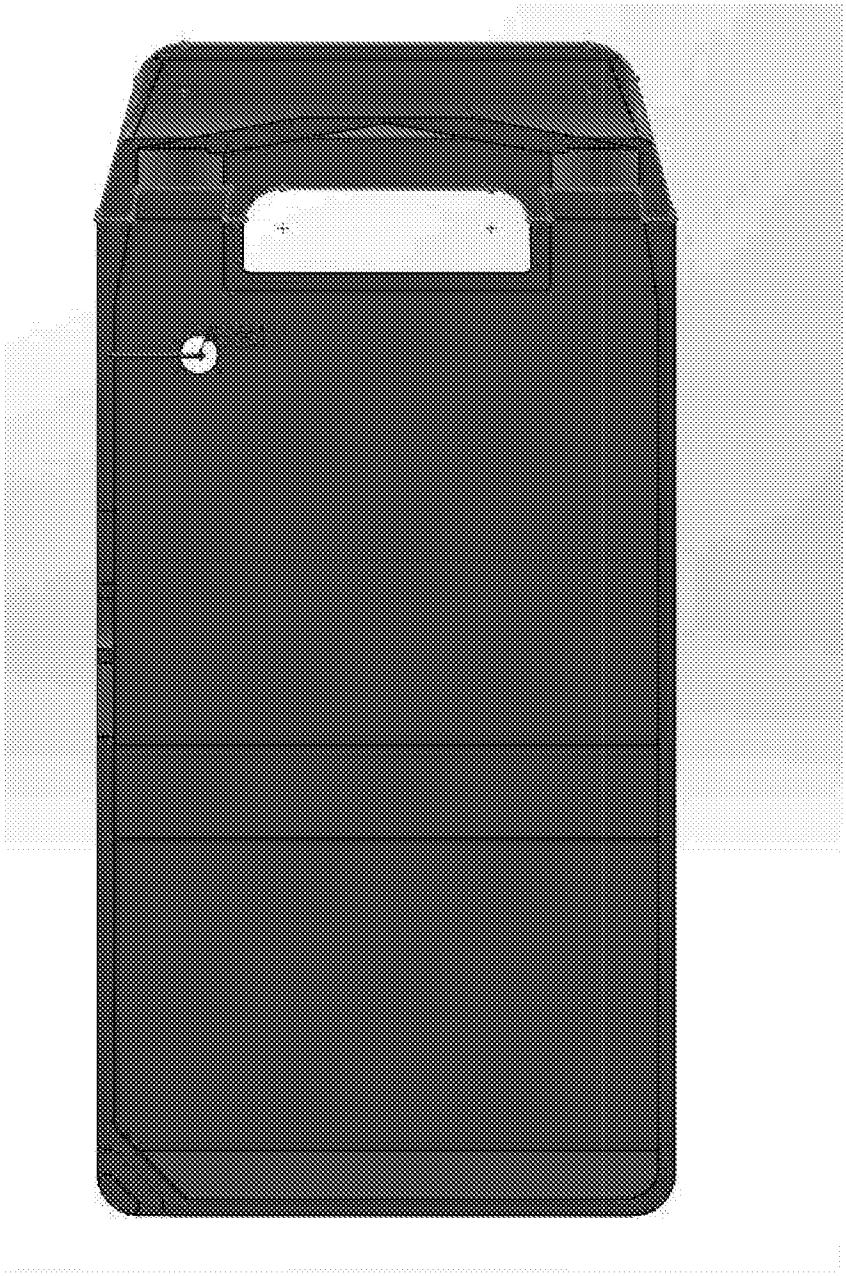


Fig. 95

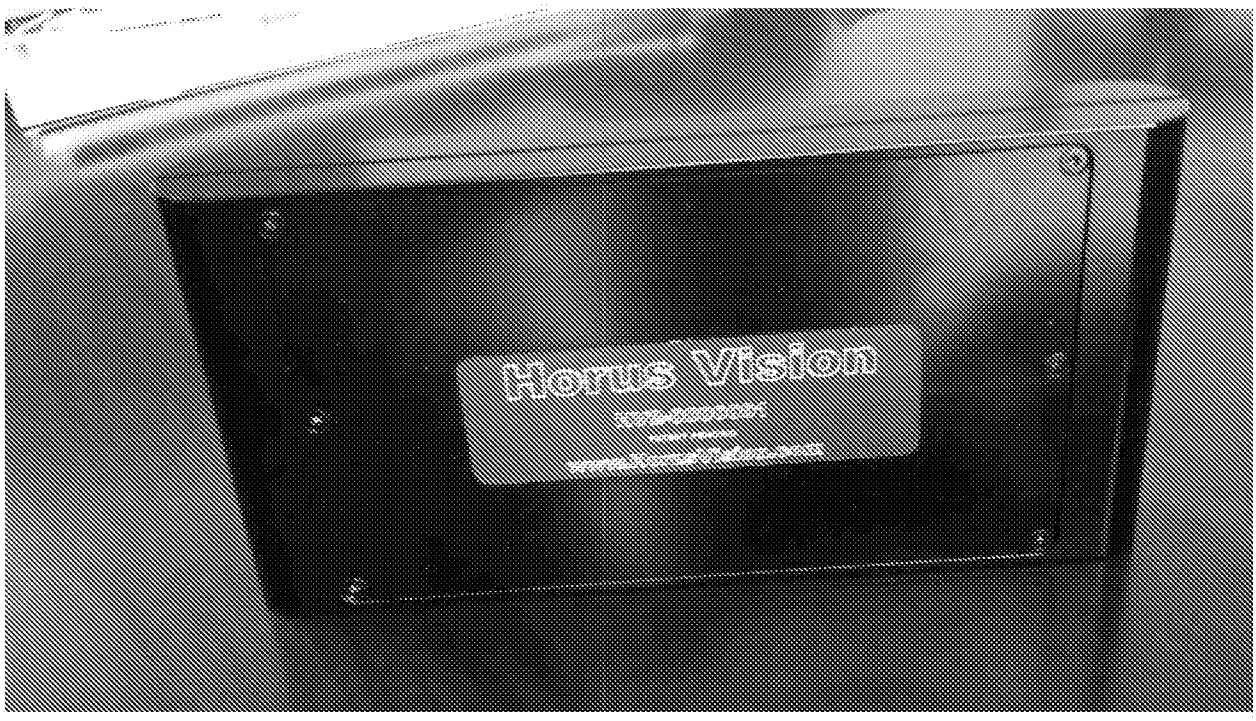


Fig. 96

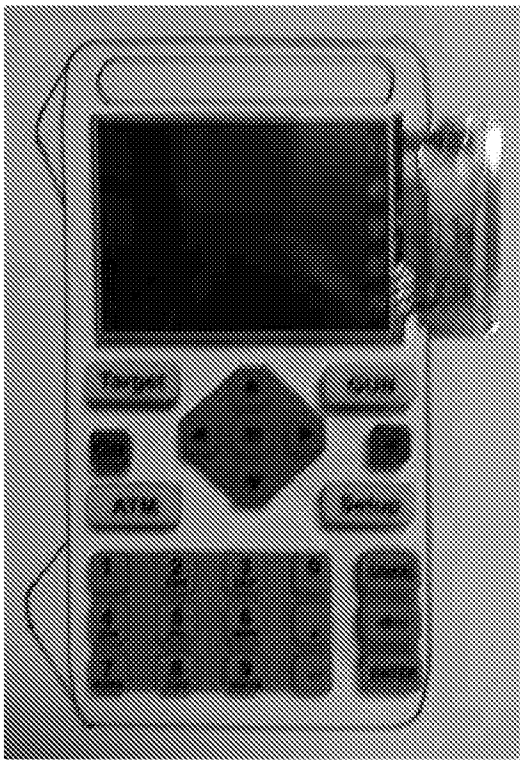


Fig. 97

Fig. 98

