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DESCRIPTION

Background of the Invention:

[0001] This invention relates generally to the offshore laying of pipe and cable and more particularly concerns equipment used in the preparation and trenching of the seabed to receive the pipe or cable and in the backfilling of the trench once the pipe or cable has been laid.

[0002] Present pipe laying methods include a few basic seabed trenching tasks performed using long-accepted, time-consuming, budget-eating practices and equipment.

[0003] One problem is that sometimes, before trenching can begin, it may be necessary to clear the seabed of boulders on, or partially buried in, the intended pipeline path. Presently, the boulder removal process involves dragging the boulders, one at a time, at cables-end from a transport/towing vessel. In some boulder fields, this can be a lengthy and tedious process. It always requires one or more divers, a remotely operated vehicle (ROV), or other boulder handling mechanisms to connect the cable to the boulder.

[0004] Another problem is that, when the time for trench cutting arrives, a trench cutting plow must be lowered to the seabed. Launching a trench cutting plow typically requires a large vessel carrying a crane and supporting equipment to lift the plow from the vessel, to swing the plow clear of the deck and to lower the plow into the sea. After its final trench cutting pass, retrieval of the trench cutting plow from the seabed to its storage area on the towing vessel again requires use of the crane and supporting equipment. In operation on the seabed, known trench cutting plows have additional problems. For example, many require skids which straddle the width of the trench being cut, so the number of possible passes that can be made and the depth of the trench that can be cut is limited.

[0005] Similar problems are experienced in the backfilling of the trench to cover the pipe. First, a heavy backfill plow must be lowered to the seabed. As with launching trench cutting plows, launching known backfill plows typically requires a large vessel and a crane and supporting equipment to raise the plow from the vessel, to swing the plow clear of the deck and to lower the plow into the sea. After its final pass the backfill plow must be retrieved from the seabed and returned to its place on the towing vessel by use of the crane and supporting equipment. In operation of the backfill plow on the seabed, one or more passes of the plow are necessary to cover the pipeline and fill the trench. Typical known backfill plows have chasses with front skids which travel in the trench and straddle the pipeline, followed by moldboards which are angled forwardly and away from the chassis to collect the spoil in their path and deposit it in the trench to the sides of the pipeline. Since the skids ride in the trench in close proximity to the pipeline, there is significant risk that contact with the skids will compromise the integrity of the pipe. Also, since the mixture of seawater and spoil, which is more dense than the hollow pipe, is pushed by the moldboards to the outer limits of the trench and discharged to the sides of the

pipe, there is a significant risk that, as the spoil settles, the pipe will "float," resulting in inadequate burial of the pipeline.

[0006] Much of the seabed trenching task equipment and operating methods are, in terms of time and money, very inefficient and beg for improvement. But the inadequacy of the individual plows and their operating methods is dwarfed by the need for a large, heavily equipped vessel to transport, launch and retrieve these plows instead of a much smaller vessel which could otherwise be used for operating purposes. Typically, the cost of known trench cutting and backfill plows is in a range of \$8,000,000 each. The cost of the transport/towing vessel with the crane and supporting equipment is in a range of \$500,000,000. The rental fee for the vessel and plows ranges from \$150,000 to \$600,000 per day.

[0007] A known seabed trenching plough is disclosed in GB2285821 and is suitable for forming a trench in two or more successive passes. It comprises a share for cutting and lifting soil; support means mounted forward of the share and adjustable to vary the depth of cut of the share; and a mouldboard to divert lifted soil laterally, the mouldboard also being adjustable upwardly.

[0008] Accordingly, it is an object of this invention to reduce the weight and cost and increase the efficiency of the plows, equipment and vessels used in the offshore laying of pipe and cable.

Summary of the Invention:

Single and Multi-Mode Chasses

[0009] In accordance with the invention, a seabed-plow chassis is provided in which an elongated member is adapted for mounting a skid on one of its ends to support that end above the seabed and is adapted for mounting one or more tools on its other end to perform a variety of seabed trenching tasks.

[0010] According to the present invention, the tool consists of moldboards used in a method for clearing boulders which are initially pushed by the skid outward of the path traveled by the skid further outward from the path as the skid leads the moldboards along the seabed.

[0011] In a second mode of operation (not forming part of the present invention) in which the chassis is a part of a trench cutting plow, the tool consists of a plow share and moldboards for sequentially cutting and moving spoil to create a trench as the skid leads the plow share and moldboards along the seabed.

[0012] In a third mode of operation (not forming part of the present invention) in which the

chassis is a part of a backfill plow, the tool consists of a blade and moldboards which cooperate as the blade and moldboards lead the skid along the seabed to sequentially collect, funnel inward and release downward into the trench spoil lying outside of the trench.

[0013] Different chasses can be adapted to accommodate each of the modes or the same chassis can be adapted to interconnect any of the tools with the skid according to the desired mode of operation.

[0014] The elongated member of the chassis may have one or more permanent transition surfaces or one or more attachments providing transition surfaces. The transition surfaces are configured to extend between the skid and the various tools which may be mounted on the chassis. The transition surface contours are shaped and located so that the appropriate transition surface makes contact with and pivots about a fulcrum on the stern of a plow transporting/towing vessel as the plow crosses that fulcrum during its release from the vessel into the sea and during its retrieval from the sea onto the vessel. The shapes and locations of the transition surfaces and the weight of the elongated member are coordinated so as to resist roll of the chassis about a transition axis as the plow moves on the deck or across the fulcrum.

[0015] Preferably, the vertical longitudinal cross-sections of the transition surfaces are concave, the fulcrum is a roller and the paths defined by continuous symmetrically opposite points of the transition surfaces are contoured to maintain contact with the roller as the plow crosses the roller.

[0016] In a preferred embodiment of the chassis for use in more than one mode of operation, a first transition surface is configured to extend between the skid and the tool in the first/boulder clearing and third/backfill modes and a second transition surface is configured to extend between the skid and the tool in the second/trench cutting mode.

Boulder Clearing Plow and Methods

[0017] For clearing boulders from a seabed, the plow includes the chassis, a skid mounted on and supporting one end of the chassis above the seabed and moldboards mounted on and oriented in angular relationship to the other end of the chassis. The trailing moldboards clear boulders initially pushed outwardly by the leading skid further outward as the skid leads the moldboards along the seabed.

[0018] In a preferred embodiment of the boulder clearing plow, a head is mounted on a leading end of the skid. The head has leading faces angled rearward from a vertical, longitudinal center plane of the skid and tapered rearward from its top edges, enabling the head to torque boulders partially buried in the seabed away from the skid. The chassis transition surface extends between the skid and the moldboards and is contoured to maintain contact with and pivot about the fulcrum/roller on the stern of the vessel as the plow crosses the fulcrum during launch and recovery.

[0019] The boulder clearing plow may also include keel plates, at least one keel plate extending under each moldboard. The keel plates' primary function is to ensure the lateral stability of the plow during operation by resisting departure of the plow from its intended path even when the plow encounters seabed obstructions or uneven amounts of spoil.

[0020] The plow components are, in weight and in their contact surfaces with the fulcrum, coordinated to resist roll of the plow about a launch and recovery transition axis of the boulder clearing plow.

[0021] Pulling points for connection of a pulling line to the boulder clearing plow are symmetrically arranged in relation to the longitudinal axis of the chassis and are displaced from the bottom of the boulder clearing plow by a height less than a radius of the vessel roller to facilitate passage of the plow contact surface over the vessel roller.

[0022] The method of clearing boulders from a path on the seabed includes the steps of positioning the plow bow-forward in the direction of an initial seabed path and then propelling the plow along the initial seabed path to push boulders lying in the initial seabed path to the port and starboard sides of the plow. After the initial path is cleared the method continues, if a wider path is necessary, with the step of repositioning the plow bow-forward in a direction opposite the initial seabed path direction and on a second seabed path along one of the port and starboard sides of the initial seabed path. Once so repositioned, the method continues with the step of propelling the plow along the second seabed path to push boulders from the second seabed path further to one of the starboard and port sides of the plow, respectively. After the second path is cleared the method continues, if an even wider path is necessary, with the step of repositioning the plow bow-forward in the direction of the initial seabed path and on a third seabed path along the other of the starboard and port sides of the initial seabed path. Once so repositioned, the method continues with the step of propelling the plow along the third seabed path to push boulders from the third seabed path further to the other of the starboard and port sides of the plow, respectively. If a still wider path is necessary, the method can further include repeating the above widening steps in relation to the path resulting from the contiguity of the initial, second and third paths. The method anticipates repeating these steps for successively contiguous paths until a single path of desired width has been cleared along the seabed.

[0023] For the over-the-stern boulder clearing plow herein disclosed, the method of clearing boulders from the seabed path is preceded by the steps of propelling the plow on the deck of the vessel toward and across the fulcrum on the stern of the vessel, allowing the plow to rotate about the fulcrum as the plow crosses the fulcrum and is released from the fulcrum into the sea and lowering the released plow at tow-line end toward the seabed. Furthermore, the method of clearing boulders from the seabed path is followed by the steps of raising the plow at tow-line end toward the fulcrum on the stern of the vessel at the other end of the tow line and pulling the plow across the fulcrum onto the deck of the vessel.

Backfill Plow and Methods

[0024] For backfilling spoil into a seabed trench, the plow includes the chassis, a skid supporting the aft end of the chassis above the seabed, moldboards mounted on the chassis forward of the skid and a blade mounted on and spanning the bottom edges of the moldboards. The blade collects the spoil in its path as the plow travels forward on the seabed. The moldboards are sized and oriented to span the trench and funnel the collected spoil toward the center of the blade as the plow travels forward on the seabed. The blade has a passage at its rear apex which is configured to dispense the collected and funneled spoil onto the top of a pipe disposed in the trench below the passage.

[0025] In a preferred embodiment, the backfill plow further includes a flapper board aft of the passage which fragments spoil discharged through the passage. The flapper board consists of a plate swinging below a horizontal shaft with a weight biasing the plate toward a vertical orientation.

[0026] The skid is configured to straddle the trench and includes a crossbar mounted on the rear end of the chassis, a pair of skid posts, one on each end of the crossbar, and a pair of skis, one on the bottom of each post. The front surface of the crossbar may be adapted to the level spoil which has been discharged into the trench.

[0027] The backfill plow may also include at least two keel plates spaced apart under the blade. The primary function of the keel plates is to ensure the lateral stability of the plow during operation by resisting departure of the backfill plow from its intended path even when the plow encounters seabed obstructions or uneven amounts of spoil.

[0028] The plow has at least one transition surface between the skid and the moldboards which is contoured to contact and pivot about the fulcrum on the stern of a vessel as the backfill plow crosses the fulcrum during launch and retrieval of the backfill plow from and to the vessel.

[0029] The plow components are, in weight and in contact surfaces with the fulcrum, coordinated to resist roll of the backfill plow about the transition axis of the plow.

[0030] Pulling points for connection of a pulling line to the backfill plow are symmetrically arranged in relation to the longitudinal axis of the chassis and are displaced from the bottom of the backfill plow by a height less than the radius of the roller to facilitate passage of the plow contact surfaces over the roller.

[0031] The method of backfilling spoil into a seabed trench includes the steps of propelling the blade to travel forward on the seabed and collect spoil along the sides of the trench, funneling the collected spoil toward a rear apex of the blade and allowing the funneled spoil to be

discharged through an opening in the blade apex and onto a top surface of a pipe disposed in the trench. The method may further include one or both of the steps of fragmenting the discharged spoil before the discharged spoil reaches the pipe and/or leveling the spoil after it is discharged into the trench.

[0032] For the over-the-stern backfill plow herein disclosed, the method of backfilling spoil into the trench is preceded by the steps of propelling the backfill plow on the deck of the vessel toward and across the fulcrum on the stern of the vessel, allowing the backfill plow to rotate about the fulcrum as the plow crosses the fulcrum and is released from the fulcrum into the sea and lowering the released plow at tow-line end to the seabed. Furthermore, the method of backfilling spoil into the trench can be followed by the steps of raising the backfill plow at tow-line end toward the fulcrum on the stern of the vessel at the other end of the tow line and pulling the plow across the fulcrum onto the deck of the vessel.

[0033] As a result of the above plow structures and methods, the vessels needed for transport, launch, recovery and operation of the plows are smaller and presently plentiful. They are available to the user at rental fees ranging from \$10,000 to \$100,000 per day. This is a huge savings in comparison to the \$150,000 to \$600,000 per day rental fees presently paid for vessels required by the old plow structures and methods.

Brief Description of the Drawings:

[0034] Other objects and advantages of the invention will become apparent upon reading the following detailed description and upon reference to the drawings in which:

Figure 1 is a top, left, rear perspective view illustrating a chassis adapted for use in any of boulder clearing, trench cutting and backfill modes;

Figure 2 is a bottom, right, front perspective view of the chassis of Figure 1;

Figure 3 is a side elevation view of the chassis of Figure 1;

Figure 4 is a top plan view of the chassis of Figure 1;

Figure 5 is a bottom plan view of the chassis of Figure 1;

Figure 6 is a top, left, front perspective view of a transition attachment for use with the chassis of Figure 1;

Figure 7 is a bottom, left, front perspective view of the transition attachment of Figure 6;

Figure 8 is a top plan view of the transition attachment of Figure 6;

Figure 9 is a side elevation view of the transition attachment of Figure 6;

Figure 10 is a top, left, front perspective view illustrating a skid configured for use in the

boulder clearing mode and the first pass of a plow in trench cutting plow mode;

Figure 11 is a top, left, front perspective view illustrating a crossbeam usable to convert two skids as seen in Figure 10 into a skid configured for use in the backfill plow mode;

Figure 12 is a front elevation view illustrating a skid configured for use in the second and subsequent passes of a plow in the trench cutting plow mode;

Figure 13 is a top, right, rear perspective view illustrating the chassis of Figure 1 used in the boulder clearing plow mode;

Figure 14 is a bottom, right, front perspective view of the boulder clearing plow of Figure 13;

Figure 15 is a top plan view of the boulder clearing plow of Figure 13;

Figure 16 is a side elevation view of the boulder clearing plow of Figure 13;

Figure 17 is a front elevation view of the boulder clearing plow of Figure 13;

Figure 18 is a top, left rear perspective view of a typical keel plate for use with the boulder clearing plow of Figure 13 and the backfill plow of Figure 37;

Figure 19 is a side elevation view of the boulder clearing plow of Figure 13 during release from/retrieval to a vessel with the plow skid pivoting on the stern of a vessel;

Figure 20 is a side elevation view of the boulder clearing plow of Figure 13 during release from/retrieval to a vessel with the plow chassis angled portion pivoting on the stern of a vessel;

Figure 21 is a side elevation view of the boulder clearing plow of Figure 13 during release from/retrieval to a vessel with the plow transition attachment pivoting on the stern of a vessel;

Figure 22 is a side elevation view of the boulder clearing plow of Figure 13 during release from/retrieval to a vessel with the plow keel plates pivoting on the stern of a vessel;

Figure 23 is a top plan view illustrating the boulder clearing plow of Figure 13 positioned to clear a path through a field of boulders;

Figure 24 is a graphic representation of a typical boulder clearance route pattern of the boulder clearing plow of Figure 13;

Figure 25 is a side elevation view of the boulder clearing plow of Figure 13 in operation;

Figure 26 is a top, left, rear perspective view illustrating the chassis of Figure 1 used in the trench cutting plow mode;

Figure 27 is a top plan view of the trench cutting plow of Figure 26;

Figure 28 is a side elevation view of the trench cutting plow of Figure 26;

Figure 29 is a front elevation view of the trench cutting plow of Figure 26;

Figure 30 is a top, left, front perspective view of a detachable share for use with the trench cutting plow of Figure 26;

Figure 31 is a bottom, right, rear perspective view of the detachable share of Figure 30;

Figure 32 is a vertical, longitudinal, center cross-sectional view of the detachable share of Figure 30;

Figure 33 is a side elevation view of the trench cutting plow of Figure 26 during release from/retrieval to a vessel with the skid post passing over the stern of a vessel;

Figure 34 is a side elevation view of the trench cutting plow of Figure 26 during release from/retrieval to a vessel with the chassis angled portion passing over the stern of a vessel;

Figure 35 is a side elevation view of the trench cutting plow of Figure 26 during release from/retrieval to a vessel with the chassis transition surface and share attachment plates passing over the stern of a vessel;

Figure 36 is a side elevation view of the trench cutting plow of Figure 26 during release from/retrieval to a vessel with the moldboards passing over the stern of a vessel;

Figure 37 is a top, left, front perspective view illustrating the chassis of Figure 1 used in the backfill plow mode;

Figure 38 is a top plan view of the backfill plow of Figure 37;

Figure 39 is a side elevation view of the backfill plow of Figure 37;

Figure 40 is a front elevation view of the backfill plow of Figure 37;

Figure 41 is a top, left, rear perspective view illustrating a spoil collecting blade for use with the backfill plow of Figure 37;

Figure 42 is a top, right, rear perspective view illustrating a flapper board for use with the backfill plow of Figure 37;

Figure 43 is a side elevation view of the backfill plow of Figure 37 during release from/retrieval to a vessel with the plow skid pivoting on the stern of a vessel;

Figure 44 is a side elevation view of the backfill plow of Figure 37 during release from/retrieval to a vessel with the chassis angled portion pivoting on the stern of a vessel;

Figure 45 is a side elevation view of the backfill plow of Figure 37 during release from/retrieval to a vessel with the plow transition attachment pivoting on the stern of a vessel;

Figure 46 is a side elevation view of the backfill plow of Figure 37 during release from/retrieval to a vessel with the plow keel plates pivoting on the stem of a vessel.

Figure 47 is a top plan view of the backfill plow of Figure 37 in operation;

Figure 48 is a side elevation view of the backfill plow of Figure 37 in operation;

Figure 49 is a top plan view illustrating the boulder clearing plow of Figure 13 positioned to backfill a wide trench on a typical wide trench backfill route pattern; and

Figure 50 is a side elevation view illustrating a plow suspended below the stern roller of a vessel.

[0035] While the invention will be described in connection with preferred embodiments thereof, it will be understood that it is not intended to limit the invention to those embodiments or to the details of the construction or arrangement of parts illustrated in the accompanying drawings.

Detailed Description:

Single Mode and Multi-Mode Chasses

[0036] Turning first to Figures 1-5, a seabed-plow chassis 10 for use as a component of various seabed plows has an elongated member 11 adapted for mounting a skid on one of its ends 13 and one or more tools on its other end 15.

[0037] As seen in Figures 13-17, the chassis 10 is used in a first mode of operation as part of a boulder clearing plow 100. In the first mode 100, boulders B on or partially buried in the seabed are initially pushed by the skid 40 outward of the path P traveled by the skid 40. The tool includes moldboards 90 which push the boulders B initially pushed away by the skid 40 and other boulders B in the path of the moldboards 90 further outward as the skid 40 leads the moldboards 90 along the seabed S.

[0038] As seen in Figures 26-29, the chassis 10 is used in a second mode of operation as part of a trench cutting plow 200. In the second mode 200, the tool includes a plow share 210 and moldboards 90 which sequentially cut and move spoil M to create a trench T as the skid 40 leads the plow share 210 and the moldboards 90 along the seabed S.

[0039] As seen in Figures 37-40, the chassis 10 is used in a third mode of operation as part of a backfill plow 300. In the third mode 300, the tool includes a blade 310 and moldboards 90 which cooperate, as the blade 310 and moldboards 90 lead the skid 40 along the seabed S, to sequentially collect spoil M lying outside of the trench, funnel the collected spoil M inward, and release the funneled spoil M downward into the trench T.

[0040] The chassis 10 is uniquely configured to facilitate over-the-stern launch and retrieval of a plow 100, 200 or 300 from and to, respectively, the deck D of a vessel V and to and from,

respectively, the seabed S. The movement of the plow 100, 200 or 300 from or to a resting place on the deck D of the vessel V to or from a point at which all contact of the plow 100, 200 or 300 with the vessel V is terminated is herein referred to as "transition." Looking at Figures 15, 27 and 38, the plows 100, 200 or 300 described herein have longitudinal axes 101, 201 and 301, respectively. As shown, the longitudinal axes 101, 201 and 301 are aligned in parallel with their anticipated directions of movement on the seabed S. Looking at Figures 19-22, 33-36 and 43-46, the plow axes 103, 203 and 303 are aligned in the direction of "transition" of the plows 100, 200 and 300, respectively, on the deck D. As shown, the longitudinal axes 101, 201, and 103 of Figures 15, 27 and 38 are aligned with the transition axes 103, 203, and 303 of Figures 19-22, 33-36 and 42-46, respectively. The plows 100, 200 and 300 need not, however, be aligned on the deck D in the same orientation they assume in operation on the seabed S. Therefore, as used herein, a "transition" axis" is any axis, longitudinal or not, which extends through a plow 100, 200 or 300 in a direction parallel to the anticipated direction of movement 39 of the plow during launch or retrieval.

[0041] It is preferred that the plows 100, 200 or 300 will have their weight distribution and the location of their surfaces which contact the deck D and the fulcrum/roller R on the stern of the vessel V during release or retrieval so coordinated as to resist roll of the plows 100, 200 or 300 about their respective transition axes 103, 203 and 303, respectively. As shown and described, the chassis 10, skid 40 and skid posts 45, transition attachment 70, moldboards 90 and keel plates 110 and 370 have various surfaces contoured to support their plows in sliding contact with the deck D and to pivot about the fulcrum/roller R on the stern of the vessel V as the plow 100, 200 or 300 crosses the fulcrum/roller R during release/retrieval of the plow. Other components can be used or specially added for the purpose.

Chassis Structure

[0042] Returning to Figures 1-5, a preferred embodiment of the chassis 10 can be used in any of the plow modes 100, 200 and 300 seen in Figures 13, 26 and 37, respectively. As best seen in Figures 1 and 2, in the preferred embodiment of the chassis 10, the skid and tool ends 13 and 15 of the elongated member 19 are substantially horizontal and joined by a midsection 27 which angles down from the skid end 13 to the tool end 15. A post receptacle 19 extends vertically through the skid end 13. Fork lift receptacles 21 extend widthwise across the top of the tool end 15 of the elongated member 11. One receptacle 21 is at the junction of the tool end 15 with the angled portion 17 of the elongated member 11. The other receptacle 21 is further to the rear of the elongated member 11 and immediately in front of a spaced pair of share connection plates 23 which extend above the elongated member 11.

[0043] A transition member 25 extends above the tool end 15 of the elongated member 11 between the fork lift receptacles 21. As best seen in Figure 3, the top surfaces of the receptacles 21, the share connection plates 23 and the transition member 25 form a substantially continuous transition surface 27 useful for launch and recovery purposes as hereinafter explained in relation to the second/trench cutting mode 200.

[0044] Side extension plates 29 taper downwardly from the tool end 15 and a back flange plate 31 caps the tool end 15 of the elongated member 11. A share connection slot 33 extends through the bottom of the tool end 15 of the elongated member 11 between the share connection plates 23.

[0045] Looking at Figures **13-17**, **26-29** and **37-40**, each of the plows 100, 200 and 300 has pulling points 65, as shown on tow bars 67 extending laterally from the skid end 13 of the elongated member 11, for connection of a pulling line L to the plow 100, 200 and 300. Preferably, the pulling points 65 are symmetrically arranged in relation to the central longitudinal axes 101, 201 and 301 of the plows 100, 200 and 300 and are displaced from the points of contact of the plows 100, 200 and 300 with the deck D or roller R by a height less than a radius of the roller R to facilitate passage of the points of contact across the roller R.

Transition Attachment

[0046] Turning to Figures **6-9**, a transition attachment 70 is configured to extend between the skid and tool ends 13 and 15 on the bottom of the elongated member 11 of the chassis 10 when the chassis is used in either of its first/boulder clearing or third/trench cutting modes 100 or 300 as seen in Figures **13**, **26** and **37**.

[0047] As shown in Figures **6-9**, the transition attachment 70 extends in a generally horizontal wishbone shape with its tines 71 opening from its front to its rear ends 73 and 75. The top surface 77 of the transition attachment 70 is contoured to mate against the bottom surface 31 of the elongated member 11 of the chassis 10 against which the transition attachment 70 will be secured by pinning the transition member 25 of the chassis 10 between the transition clevis plates 83, as is best seen in Figures **16** and **39**. The bottom surface 79 of the transition attachment 70 is contoured to make contact with and pivot about fulcrum R on the stern of a plow transporting/towing vessel V, seen in Figures **21** and **22** and **44** and **45**, as the plow 100 or 300 crosses the fulcrum/roller R during its release from the vessel into the sea and during its retrieval from the sea onto the vessel.

[0048] The shape of the attachment bottom surface 79 and the weight of the elongated member 11 and attachment 70 are coordinated so as to resist roll of the chassis 11 about the plow transition axis 103 or 303 as the plow 100 or 300 moves on the deck D toward or away from the fulcrum R.

[0049] Preferably, the fulcrum R is a roller and, as best seen in Figure **9**, the vertical longitudinal cross-sections of the attachment bottom surface 79 are concave. Looking at Figures **16**, **39** and **50**, the radius of the concavity 79 is greater than the radius of the fulcrum R so as to facilitate passage of the transition attachment 70 across the fulcrum R during release and retrieval of the plows 100 and 300. Looking at Figure **8**, the concavity 79 is symmetric about a longitudinal vertical plane centered on the attachment 70. The surface 79

can have any shape as long as it provides paths which facilitate the over-the-stern release and retrieval of the plow 100 or 300. The paths may be linear or planar and are preferably symmetrically defined by continuous opposite points of the attachment bottom surface 79.

[0050] As shown, the front end 73 of the attachment 70 has a leading face 81 which is angled to smooth the transition to and from the skid end 13 of the elongated member 11 of the chassis 10. Back plates 85 are provided on the ends of the tines 71 for connection to the moldboards 90. The gap 87 between the tines 71 functions as a passageway for debris in the third/backfill mode 300, as is hereinafter explained.

Skid

[0051] Turning to Figures 10 and 11, a preferred embodiment of the skid 40 is adaptable for use in any of the plow modes 100, 200 and 300 seen in Figures 13, 26 and 37, respectively.

[0052] In Figure 10, the skid 40 is shown configured for use in the first/boulder clearing and second/trench cutting modes 100 and 200, seen in Figures 13 and 26, respectively. When used in the first/boulder clearing or second/trench cutting mode 100 or 200, the parallel outer skis 41 of the skid 40 are in close proximity to each other, bolted on opposite sides of a center ski 43. In this bolted configuration, a head 51 can be mounted on the front of the skis 41 and 43 in either the first/boulder clearing mode or for a first pass, the second/trench cutting mode 100 or 200. Alternatively, as shown in Figure 12, the outer skis 41 can be pivotally mounted on the center ski 43 using linkages 48 so that the outer skis 41 can be canted laterally upward from the center ski 43, provided the head 51 is not attached to the skis 41 and 43. The use of canted outer skis 41 is specially applicable to second and subsequent passes in this second/trench cutting mode 200, enabling the canted skis 41 to conform to the side walls of the trench T and facilitating the deepening of the trench T by a second and subsequent passes of the trench cutting plow 200. Thus, deeper trenches can be cut without need for a larger trenching plow.

[0053] In of the above bolted or pivotal configurations for the outer skis 41, whether or not the head 51 is used, a post 45, which is pinned in a receptacle 47 in the center ski 43, extends upward to a top 49 which is convex from front to back. As shown, the outer skis 41 have receptacles 47 which are the same as the center ski receptacles 47. When used in the first/boulder clearing mode 100, the boulder clearing head 51 is preferably added to the leading end of the skid 40 across the fronts of the skis 41 and 43. As shown, the leading faces 53 of the head 51 are angled rearward from a vertical, longitudinal center plane of the skid 40 and are tapered rearward from their top edges 55. The angled and tapered faces 53 will torque partially buried boulders out of the seabed and away from the skid 40 and, if necessary, allow the plow 200 to ride over a boulder B which strikes the head 51 below its top edges 55.

[0054] When used in the second/trench cutting mode 200, either the bolted configuration of the skis 41 or the pivotal configuration of the skis 41 in an uncanted condition can be used,

preferably with the head 51 in place for the first pass of the plow 200. For subsequent passes, it is preferred that the pivotal configuration of the skis 41 be used in the canted condition without the head 51. In the second/trench cutting mode 200, trenches up to 25 meters wide can be cut using multiple passes.

[0055] In Figure 11, a crossbeam 57 is shown for converting the outer skis 41 of the skid 40 shown in Figure 10 for use in the third/backfill mode 300. In the backfill mode 300, a crossbeam 57 spaces a pair of open ended receptacles 63 apart from a center post 59 extending upward from the midpoint of the crossbeam 57. As seen in Figure 37, two posts 45 are seated, one in each of the receptacles 47 of the two outer skis 41 as shown in Figure 10. The posts 45 extend up from their respective outer skis 41, pass through their respective open ended receptacles 63 in the crossbeam 57 and are pinned with the skis 41 at the desired distance below the crossbeam 57. The crossbeam center post 59 is pinned in the chassis post receptacle 19 to set the desired height of the chassis 10 above the skis 41. The crossbeam 57 as shown has a front surface 61 configured to also serve as a spoil leveler in the backfill mode 300.

Boulder Clearing Plow and Methods

[0056] Looking at Figures 13-17, the boulder clearing plow 100 includes the chassis 10, the skid 40, the transition attachment 70 and the moldboards 90. The skid 40, in the configuration shown in Figure 10 with the head 51 is mounted on and supports the skid end 13 of the chassis 10 above the seabed S. The moldboards 90 include primary, secondary and tertiary moldboards 91, 93 and 95 mounted on the tool end 15 of the chassis 10. The transition attachment 70 is mounted under the chassis 10 between the skid 40 and the primary moldboards 91.

[0057] As best seen in Figure 13, in the first/boulder clearing mode 100 the chassis 10 is oriented upside down in comparison to its orientation as shown in Figures 1 and 2. That is, in the boulder clearing plow 100, the skid end 13 is lower than the tool end 15 of the elongated member 11 and the skid post 45 extends upward through the receptacle 19 in the skid end 13 of the chassis 10.

[0058] As seen in Figures 13-17, the primary moldboards 91, which may be permanently or detachably mounted on the tool end 15 of the chassis 10, are angled outward and rearward from the tool end 15 of the chassis 10 and the transition attachment 70. The secondary moldboards 93 are mounted below the primary moldboards 91 and the transition attachment 70 to increase the overall depth of the moldboards 91. The tertiary moldboards 95 are used when wider paths are to be cleared of boulders B. They are mounted at the free ends of the primary and secondary moldboards 91 and 93 and increase the length of the moldboards 90 for the full depth of the combined primary and secondary moldboards 91 and 93.

[0059] As best seen in Figures 13-15, when the tertiary moldboards 95 are used, a chassis

extension 33 is connected by its front flange 35 to the back flange plate 31 of the chassis 10. A supporting structure 37 of beams and struts connects the chassis extension 33 to the tertiary moldboards 95. Recovery fins 97 are appended to the free ends of the moldboards 90. The fins 97 have divergingly arcuate ends 99 for contact with the roller R during launch and recovery.

[0060] The boulder clearing plow 100 may also include keel plates 110, shown in detail in Figure 18. The keel plates 110 have a vertical center plate 111 and horizontal base plates 113 which extend laterally from the center plate 111. The base plates 113 and the center plates 111 support a vertical mounting plate 115 at an angle complementary to the angle of the moldboards 90. This structure is reinforced by small and large vertical support plates 117 and 119. At least one keel plate 110 mounted on the front of and extending under each set of moldboards 90. As best seen in Figures 14, 15, 17 and 18, the keel plates 110 are mounted in parallel at the junctions of the secondary and tertiary moldboards 93 and 95. The primary function of the keel plates 110 is to steady the path of the boulder clearing plow 100 as the head 51 and moldboards 90 encounter boulders B, spoil M and/or other obstacles on the seabed S.

[0061] Turning to Figures 19-22 and 50, the over-the stern release (Figures 19-22) and retrieval (Figures 22-19) of the boulder clearing plow 100 from a vessel V to the seabed S or from the seabed S onto a vessel V, respectively, are illustrated. During release, the plow 100 is preferably and as shown initially positioned on the deck D with its moldboards 90 aft and the longitudinal axis 101 of the plow 100 aligned on the transition axis 103 of the plow 100. The skid 40 and keel plates 110 provide the initial contact points or surfaces of the plow 100 with the deck D. As seen in Figure 19, as the plow 100 is propelled, by winch or other suitable push/pull equipment (not shown), along the deck D of the vessel V toward and across the fulcrum/roller R at the stern of the vessel V, when the keel plates 110 have cleared the fulcrum/roller R, the plow 100 drops onto the moldboard 90 and slides on the moldboards to the concave surface of the transition attachment 70, at which point the moldboards slide to the transition attachment 70 and the the skid 40 begins to rise from the deck D. All contact between the plow 100 and the vessel V has transferred to the transition attachment 70 and the fulcrum/roller R of the vessel V. Looking at Figure 20, as the transition attachment 70 travels travel sternward beyond the fulcrum/roller R, all contact between the plow 100 and the vessel V remains on the concave transition surface 79 of the attachment 70 and the fulcrum/roller R of the vessel V and the plow 100 continues to tip toward the sea and the skid 40 continues to rise. As seen in Figure 21, as the attachment 70 travels further sternward on the fulcrum/roller R, all contact between the plow 100 and the vessel V is still between the transition attachment 70 and the fulcrum/roller R but the skid 40 is nearly vertical. Looking at Figure 22, as the plow 100 continues to rotate on and travel across the fulcrum/roller R, the buoyancy of the sea water and the travel speed of the vessel V limit rotation of the plow 100. As the transition attachment 70 slides off the fulcrum/roller R, the skid 40 becomes the final contact with the fulcrum/roller R until the plow 100 is fully released at the end of a pulling line L to the seabed S.

[0062] Retrieval of the boulder clearing plow 100 at the end of the pulling line L from the

seabed S is accomplished by reversal of the release method. As seen in Figure 22, as the plow 100 is raised at the end of the line L toward the fulcrum/roller R on the stern of the vessel V, the skid 40 will first contact the fulcrum/roller R. As noted above, the pulling points 65 of the plow 100 are located so as to assure that the head 51 and skis 41 and 43 of the sled 40 will not hang-up on the fulcrum/roller R. Further contact with the fulcrum/roller R transfers sequentially to the transition surface 79 of the transition attachment 70 as seen in Figure 21, the concave portion of the attachment transition surface 79 as seen in Figure 20 and then along the bottom of the moldboards 90, as seen in Figure 19, until they contact the keel plates 110 and the plow 100 has been pulled fully across the fulcrum/roller R and comes to rest with the skid 40 and keel plates 110 as the contact points on the deck D of the vessel V.

[0063] Turning to Figure 23-25, the use of the boulder clearing plow 100 to clear boulders B from a path P on the seabed is illustrated. As seen in Figure 24, the plow 100 is positioned with the plow 100 bow-forward in the direction of an initial seabed path P_1 which will be at the center of the intended final path P. The pattern of the final path P spirals out from the initial path P_1 . The plow 100 is then propelled, perhaps at the end of the pulling line L, powered by a winch or by the travel of the vessel, along the initial path P_1 to clear boulders B from the initial path P_1 to the port and starboard sides of the plow 100. After the initial path P_1 is cleared, boulder clearing continues, if a wider path P is necessary, by repositioning the plow 100 bow-forward, for travel in a direction opposite the initial seabed path direction, on a second seabed path P_2 along, as shown, the starboard side of the initial path P_1 . The plow 100 is then propelled along the second path P_2 to clear boulders in the second path P_2 further away from the path P_1 . After the second path P_2 is cleared, boulder clearing continues, if a wider path P is necessary, by repositioning the plow 100 bow-forward, for travel in the direction of the initial seabed path direction, on a third seabed path P_3 along the port side of the initial path P_1 . The plow 100 is then propelled along the third path P_3 to clear boulders from the third path P_3 further away from the first path P_1 . If a still wider path P is necessary, boulder clearing can further include repeating the widening along the path P resulting from the contiguity of the initial, second and third paths P_1 , P_2 and P_3 , as shown along paths P_4 and P_5 . The boulder clearing process anticipates repetition of the widening steps to widen successively contiguous paths P until a single path P of desired width has been cleared along the seabed.

[0064] Looking at Figure 25, as the head 51 strikes one or more boulders B in its initial path P_1 , the boulders B will be torqued out of the seabed and around the port or starboard side of the head 51, depending on which side of the head 51 strikes the boulders B. The trailing moldboards 90 will torque and push the boulders B further to port or starboard away from the plow 100. On ensuing paths P_{2-n} , only the outside of the head 51 and the outside moldboards 90 are on a path to strike the boulders B, pushing them further away from the initial path P_1 . As seen in Figure 22, boulders B which have been pushed aside will be deposited in a small spoil heap H created aft of the plow 100 by the partial penetration of the seabed by the moldboards 90.

Trench Cutting Plow and Methods

[0065] Looking at Figures 26-29, the trench cutting plow 200 includes the chassis 10, the skid 40, the moldboards 90 and the share 210. The skid 40, in the configuration shown in Figure 10, is mounted on and supports the skid end 13 of the chassis 10 above the seabed. The moldboards 90 initially include only the primary moldboards 91 mounted on the tool end 15 of the chassis 10. If more than one pass of a trench cutting plow 200 is to be performed, the secondary and tertiary moldboards 93 and 95 can be added. Wedges (not shown) can be positioned between the chassis 10 and the moldboards 90 to angle the moldboards at a desired angle upward and rearward from the chassis 10 for second and subsequent passes of the plow. The transition attachment 70 is not used. As shown, the head 51 may optionally be attached to the skid 40 in the first pass of the second/trench cutting mode 200.

[0066] As best seen in Figure 20, in the second/trench cutting mode 200 the chassis 10 is oriented right-side up as shown in Figures 1 and 2. That is, in the trench cutting plow 200, the skid end 13 is higher than the tool end 15 of the elongated member 11 and the skid post 45 extends upward through the receptacle 19 in the skid end 13 of the chassis 10.

[0067] The plow share 210 may be permanently or detachably mounted on the chassis 10. A preferred embodiment of the share 210 shown in Figures 26-32 includes a shoe box 211 joining the bottoms of center ribs 213 and side plates 215 which support the parting plates 217 of the share 210. A vertical plate 219 aligned with the shoe box 211 extends upwardly above the parting plates 217 and is inserted between the share connection plates 23 on the chassis 10. A pin 221 inserted through a boss 223 on the vertical plate 219 and the connection plates 23 secures the share 210 to the chassis 10.

[0068] Turning to Figures 33-36, the over-the stern release (Figures 36-33) and retrieval (Figures 33-36) of the trench cutting plow 200 from the vessel V to the seabed S and from the seabed S onto the vessel V, respectively, are illustrated. During release, the plow 200 herein described is initially positioned upside down on the deck D with moldboards 90 aft and the longitudinal axis 201 of the plow 200 aligned on the plow's transition axis 203. The arcuate top 49 of the skid post 45 and the free ends of the moldboards 90 provide the initial contact points or surfaces with the deck D. As seen in Figure 36, as the plow 200 is propelled, by winch or other suitable push/pull equipment (not shown), along the deck D of the vessel V toward and across the fulcrum/roller R at the stern of the vessel V, only the moldboards 90 and the arcuate top 49 of the post 45 will remain in contact with the fulcrum/roller R until the share connection plates 23 reach the fulcrum/roller R. As seen in Figure 35, as the plow 200 continues sternward travel, only the tops of the share connection plates 23 followed by the trailing top or transition surface 27 of the transition member 25 and the arcuate top 49 of the post 45 will remain in contact with the fulcrum/roller R. As seen in Figure 34, as the center of gravity of the plow 200 has passed the fulcrum/roller R, the cantilevered weight of the plow 200 causes the plow 200 to pivot on the transition surface 27 of the transition member 25, allowing the

moldboards 90 to drop toward the seabed S and the skid post 45 to rise from the deck D. At this point in transition, all contact between the plow 200 and the vessel V transfers to the angled portion 17 of the chassis elongated member 11 and the fulcrum/roller R of the vessel V. Looking at Figure 33, after the angled portion 17 of the chassis elongated member 11 has travelled sternward beyond the fulcrum/roller R, the plow 200 will have rotated further toward the seabed S and all further contact between the plow 200 and the vessel V will have transferred to the arcuate top 49 of the skid post 45 and the fulcrum/roller R of the vessel V. The arcuate top 49 of the skid post 45 provides the final contact with the fulcrum/roller R as the plow 200 is fully released at the end of a pulling line L to the seabed S.

[0069] Retrieval of the trench cutting plow 200 at the end of the pulling line L from the seabed S is accomplished by reversal of the release method. As seen in Figure 33, as the plow 200 is raised at the end of the line L toward the fulcrum/roller R on the stern of the vessel V, the arcuate top 49 of the skid post 45 will first contact the fulcrum/roller R. As noted above, the pulling points 65 of the plow 110 are located so as to assure that the post 45 will not hang up on the fulcrum/roller R. Further contact with the fulcrum/roller R transfers sequentially to the angled portion 17 of the chassis elongated member 11 as seen in Figure 34, to the transition surface 27 as seen in Figure 35, and to the tops of the share connection plates 23 as seen in Figure 36. When the plow 200 has been pulled fully across the fulcrum/roller R, it will come to rest with the arcuate top 49 of the skid post 45 and the tops of the free ends of the moldboards 90 as the contact points on the deck D of the vessel V.

Backfill Plow and Methods

[0070] Turning to Figures 37-40, for backfilling spoil into a seabed trench, the backfill plow 300 includes the chassis 10, the skid 40 configured to straddle the trench being backfilled, the moldboards 90 mounted on the chassis 10 forward of the skid 40 and the blade 310 mounted on and spanning the bottom edges of the moldboards 90.

[0071] As best seen in Figure 37, in the third/backfill mode 300, the chassis 10 is oriented upside down in comparison to its orientation as shown in Figures 1 and 2. That is, in the backfill plow 300, the skid end 13 is lower than the tool end 15 of the elongated member 11, as in the first/boulder clearing mode 100 shown in Figure 13, and the crossbeam center post 59 extends upward through the receptacle 19 in the skid end 13 of the chassis 10, similar to the post 45 in the first/boulder clearing mode 100 shown in Figure 13. However, the chassis 10 is oriented in reverse in comparison to the first/boulder clearing mode 100 shown in Figure 13, so that the skid 40 is at the trailing end of the backfill plow 300. In comparison to the first/boulder clearing mode 100, the skis 41 are also reversed in the third/boulder clearing mode 300 for forward travel in a trailing position.

[0072] As seen in Figures 37-40, in the third/backfill mode, the moldboards 90, including the primary moldboards 91, the secondary moldboards 93 and the tertiary moldboards 95, are mounted on the chassis 10 in the same way as described in relation to the first/boulder

clearing mode 100 of Figures 13-17 by use of the chassis extension 33 and supporting structure 37. The transition attachment 70 is also mounted to the chassis 10 in the same manner as described in relation to the first/boulder clearing mode 100 of Figures 13-17. The recovery fins 97 are appended to the free ends of the tertiary moldboards 95 as described in relation to the first/boulder clearing mode 100 of Figures 13-17.

[0073] Looking at Figure 41, the blade 310 has a passage 311 at its rear apex 313. The passage 311 is configured to dispense the spoil collected by the blade 310 and funneled by the moldboards 90 onto the top of a pipe or cable C disposed in the trench T below the passage 311. The side edges of the blade 310 are secured to the lower portions of their respective moldboards 90 by use of side plates 315 and to the chassis extension 33 by use of an upright mounting structure 317. The mounting structure 317 is centered on the leading edge 319 of the blade 310 and, as shown, extends from the blade edge 319 to the passage 311. The blade 310 may be stiffened by ribs 321. As shown, the passage 311 is slightly greater than semi-circular with a diameter 323 parallel to the blade leading edge 319. The stiffening ribs 321 fan out from points along the passage circumference 325 to respective points along the blade leading edge 319.

[0074] Looking at Figure 42, the backfill plow 300 preferably further includes a flapper board 340 aft of the passage 311. The flapper board 340 includes a plate 341 fixed to and swinging below a horizontal shaft 343. The shaft 343 is journalled to reciprocate on an axis parallel to the passage diameter 323. A weight 345 biases the plate 341 toward a vertical orientation. The slapping action of the flapper board 340 fragments spoil discharged through the blade passage 311. Large and small stiffeners 347 and 349 reinforce the plate 341. The reciprocating swing of the plate 341 on its shaft 343 is caused as water and spoil discharging through the passage 311 swings the plate 341 toward the rear and the weight 345 causes the plate 341 to swing back toward vertical.

[0075] The backfill plow 300 may also include keel plates 370, at least one keel plate 370 extending on opposite sides of the spoil passage 311. The keel plates 110, shown in Figure 18 for use in the first/boulder clearing mode 100, can be used in the third/backfill mode 300 except that, in the backfill mode 300, they are mounted on the front of the moldboards 90 and extend under the blade 310. As seen in Figures 38-40, the keel plates 370 are mounted in parallel at the junctions of the secondary and tertiary moldboards 93 and 95. The primary function of the keel plates 370 is to steady the path of the backfill plow 300 as the blade 310 and moldboards 90 encounter and collect spoil M on the seabed S.

[0076] Turning to Figures 43-46, the over-the stern release (Figures 46-43) and retrieval (Figures 43-46) of the backfill plow 300 from a vessel V to the seabed S or from the seabed S onto a vessel V, respectively, are illustrated. During release, the plow 300 described herein is initially positioned on the deck D with moldboards 90 aft and the longitudinal axis 301 of the plow 300 aligned on the transition axis 303 of the plow 300. The skid 40 and bottoms of the keel plates 370 provide the initial contact points with the deck D. As seen in Figure 46, as the plow 300 is propelled, by winch or other suitable push/pull equipment (not shown), along the

deck D of the vessel V toward and across the fulcrum/roller R at the stern of the vessel V, the keel plates 370 clear the fulcrum/roller R, allowing the moldboards 90 to drop toward the seabed S. The plow begins to pivot on the transition surface 79 and the skid 40 begins to rise from the deck D. At this point in transition, all contact between the plow 300 and the vessel V has transferred to the transition attachment 70 and the fulcrum/roller R of the vessel V. Looking at Figure 45, as the plow 300 travels further sternward across the fulcrum/roller R, all contact between the plow 300 and the vessel V has transferred to the concave portion of the transition surface 79 of the attachment 70 and the fulcrum/roller R of the vessel V. As seen in Figure 44, as the attachment 70 has travelled sternward beyond the fulcrum/roller R, all contact between the plow 300 and the vessel V remains on the angled portion 17 of the chassis elongated member 11 and the fulcrum/roller R of the vessel V. The plow 300 has tipped so that the skid 40 nears vertical. Looking at Figure 43, as the plow 300 continues to rotate on and travel across the fulcrum/roller R, the buoyancy of the sea water and the travel speed of the vessel V limit rotation of the plow 300 as the transition attachment 70 slides off the fulcrum/roller R. The shape of the attachment 70 affords a smooth transition from the transition surface 79 to the skid 40. The skid 40 becomes the final contact with the fulcrum/roller R until the plow 100 is fully released at the end of a pulling line L to the seabed S.

[0077] Retrieval of the backfill plow 300 at the end of the pulling line L from the seabed S is accomplished by reversal of the release method. As seen in Figure 43, as the plow 300 is raised at the end of the line L toward the fulcrum/roller R on the stern of the vessel V, the skid 40 will first contact the fulcrum/roller R. As noted above, the pulling points 65 of the plow 300 are located so as to assure that the head 51 and skis 41 and 43 of the sled 40 will not hang up on the fulcrum/roller R. Further contact with the fulcrum/roller R transfers sequentially to the angled portion 17 of the chassis elongated member 11 as seen in Figure 44, to the attachment transition surface 79 as seen in Figure 45 and to the bottom of the keel plates 370 as seen in Figure 46. When the plow 300 has been pulled fully across the fulcrum/roller R, it will come to rest with the skid 40 and keel plates 370 as the contact points on the deck D of the vessel V.

[0078] Turning to Figures 47 and 48, in backfilling spoil M to cover a pipe P laid in a seabed trench T, the backfill plow 300, with the blade 310 forward, is propelled to travel on the seabed S and collect spoil M along the sides of the trench T. The moldboards 90 funnel the collected spoil M toward the rear apex 313 of the blade 310 and the funneled spoil M is discharged through the passage 311 in the blade apex 313 and onto the top surface of the pipe P disposed in the trench T. Preferably, the discharged spoil M is fragmented, as shown by the flapper board 340, before the discharged spoil M reaches the pipe P and the spoil M discharged onto the pipe P and into the trench T is leveled by the front surface 61 of the skid crossbar 57. The use of the passage 311 to discharge the spoil M directly onto, rather than to the sides of, the pipe P reduces the likelihood that the more dense spoil M will lift the pipe P in the trench T during backfilling.

[0079] Turning to Figure 49, for trenches wider than the widest span of the moldboards 90, the boulder clearing plow 100 seen in Figure 13 can be used to narrow the width of the trench T. This is accomplished by aligning the longitudinal axis 101 of the plow 100 outside of the spoil M

one side of the trench T, as shown with only the starboard moldboards 90 pushing the spoil M. On the first pass P_a the spoil M in the path of the starboard moldboards will be pushed toward or into the trench T. When the first pass P_a is completed, the plow 100 is aligned on the other side of the trench T, as shown again with only the starboard moldboards 90 pushing the spoil M. On the second pass P_b , the spoil M in the path of the starboard moldboards will be pushed toward or into the trench T. When the second pass P_b is completed, the process can be repeated for passes P_n until the trench T is filled or until the trench T is sufficiently filled to complete backfilling using the backfill plow 300.

[0080] Turning to Figure 50, the plows 100, 200 or 300 can be retrieved by use of the tow line L connected to the retrieval fins 97. Depending on which of the plows 100, 200 or 300 is retrieved, the orientation of the plow 100; 200 or 300 can be rotated 180° about the axis of the tow line L to a suitable retrieval position. In either 180° orientation, the arcuate ends 99 of the fins 97 will enable the plow 100, 200 or 300 to pass over the fulcrum/roller R.

[0081] The plows 100, 200 and 300 are made using steel plates which are welded, bolted or pinned, depending on the intended permanency or detachability of the components being connected. The same chassis 10, skids 40, transition attachment 70, moldboards 90, and keel plates 1 10 can be configured into three different modes of operation and the share 210 and blade 3 10 added as needed for their respective modes. The need for a large vessel, cranes and supporting equipment is eliminated since the plow modes 100, 200 and 300 are all capable of over-the-stern launch and recovery.

[0082] While the convention apparatus and methods have been described in relation to laying pipe, it is also applicable to laying cable. Furthermore, all of the plows 100, 200 and 300 can be adapted for use with a remotely operated vehicle (ROV) which can "dock" on the plow to provide additional mechanical functionality such as skid height adjustment or electrical functionality such as cameras, lights, and load measurement.

[0083] Thus, it is apparent that there has been provided, in accordance with the invention, a multi-mode seabed plow and plow release, operation and retrieval methods that fully satisfy the objects, aims and advantages set forth above. While the invention has been described in conjunction with specific embodiments thereof, it is evident that many alternatives, modifications and variations will be apparent to those skilled in the art in light of the foregoing description. Accordingly, it is intended to embrace all such alternatives, modifications and variations as fall within the scope of the appended claims.

REFERENCES CITED IN THE DESCRIPTION

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Patent documents cited in the description

- GB2285821A [0007]

Patentkrav

1. Fremgangsmåde til at rydde store sten (B) fra en rute (P) på en havbund (S) omfattende trinnene:

at placere en plov (100) med boven forrest i en retning af en initial havbundsroute

5 (P₁), idet ploven omfatter et plovstel (10) og har:

et forreste støtteben (40) monteret på og som støtter en forreste ende af nævnte plovstel på en bund af havbunden (S); og

bagbords- og styrbordsmuldfjæle (90) monteret på og orienteret i forhold til en agterende af nævnte plovstel på bunden af havbunden; og

10 at drive ploven langs den initiale havbundsroute for at forårsage, at muldfjælene rydder store sten fra den initiale havbundsroute til bagbords- og styrbordssiderne af ploven.

15 **2.** Fremgangsmåde ifølge krav 1 yderligere omfattende trinnene:

at repositionere ploven (100) med boven forrest i en retning modstående

den initiale havbundsroutesretning og på en anden havbundsroute langs en af bagbords- og styrbordssiderne af den initiale havbundsroute; og

at drive ploven langs den anden havbundsroute for at forårsage, at

20 muldfjælet rydder store sten fra den anden havbundsroute og længere fra den første havbundsroute.

3. Fremgangsmåde ifølge krav 2 yderligere omfattende trinnene:

25 at repositionere ploven (100) med boven forrest i retningen af den initiale havbundsroute og på en tredje havbundsroute langs en anden af bagbords- og styrbordssiderne af den initiale havbundsroute; og

at drive ploven langs den tredje havbundsroute for at forårsage, at

muldfjælet rydder store sten fra den tredje havbundsroute længere og

30 længere fra den første havbundsroute.

4. Fremgangsmåde ifølge krav 3 yderligere omfattende at gentage trinnene af kravene 2 og 3 langs en rute, som følger af et grænsefællesskab af den initiale,

anden og tredje rute.

5. Fremgangsmåde ifølge krav 4 yderligere omfattende at gentage trinnene af krav 4 for successive sammenhængende ruter, indtil en enkelt rute af ønsket bredde er ryddet langs havbunden.

6. Fremgangsmåde ifølge krav 1 forudgået af trinnet:

at drive ploven (100,) med muldfjælene først på dækket af et skib mod og henover et drejningspunkt på en agterstævn af skibet;

10 at tillade den drevne plov at rotere omkring drejningspunktet, mens ploven krydser drejningspunktet og frigives fra drejningspunktet ned i havet; og at sænke den frigivne plov ved slæbelinjeende mod havbunden.

15 **7.** Fremgangsmåde ifølge krav 1 efterfulgt af trinnene:

at hæve ploven (100) med støttebenet først ved slæbelinjeende mod et drejningspunkt på en agterstævn af et skib; og

at trække den hævede plov henover drejningspunktet op på et dæk af skibet.

20

DRAWINGS

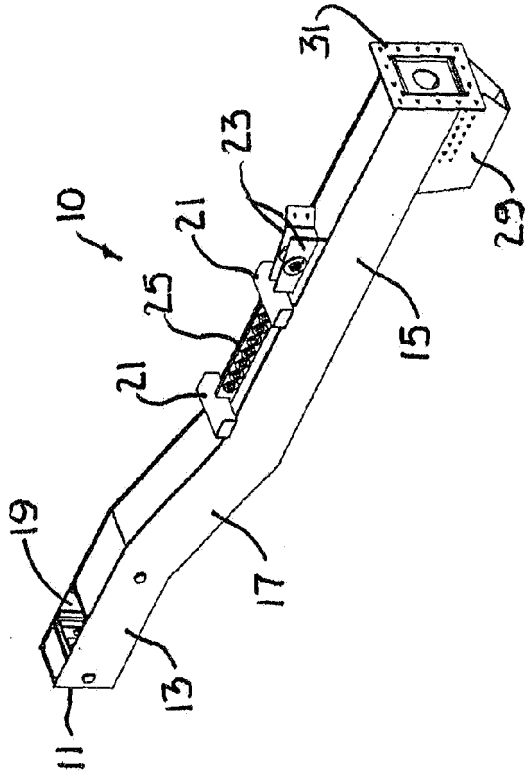


Fig. 1

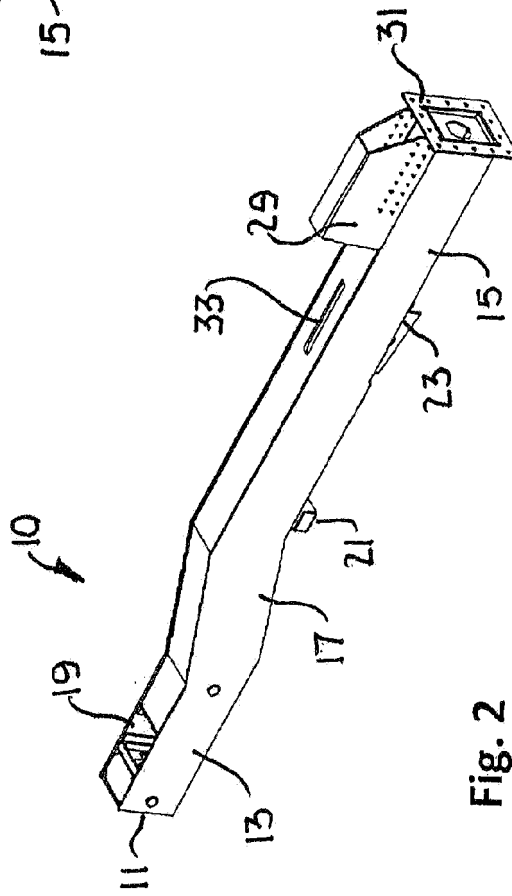


Fig. 2

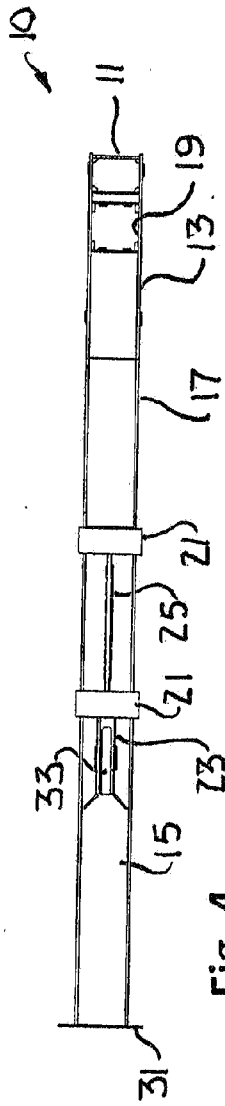


Fig. 4

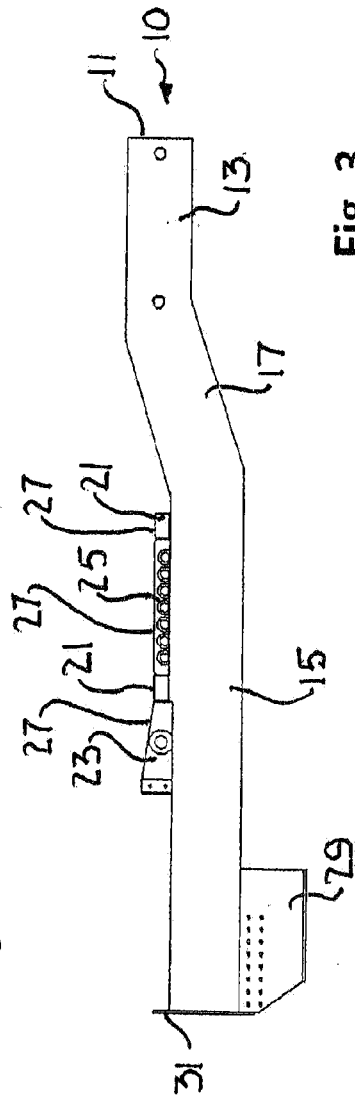


Fig. 3

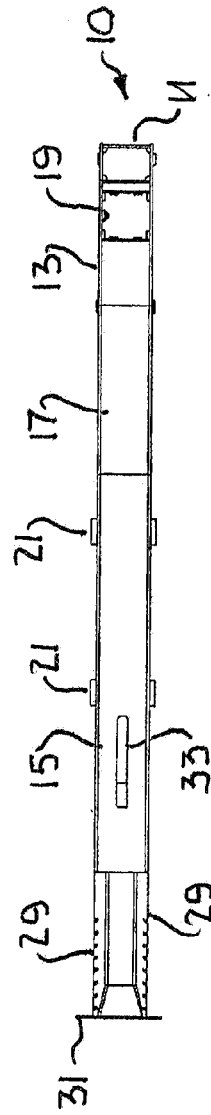


Fig. 5

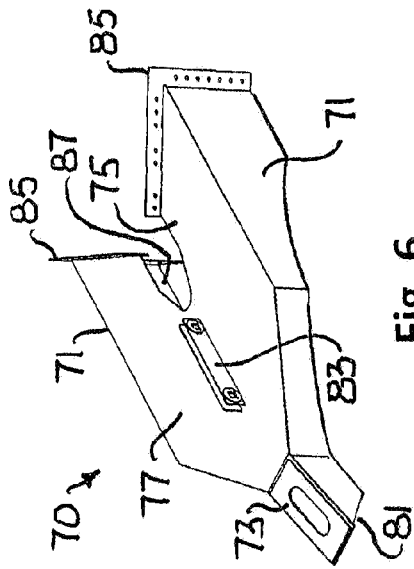


Fig. 6

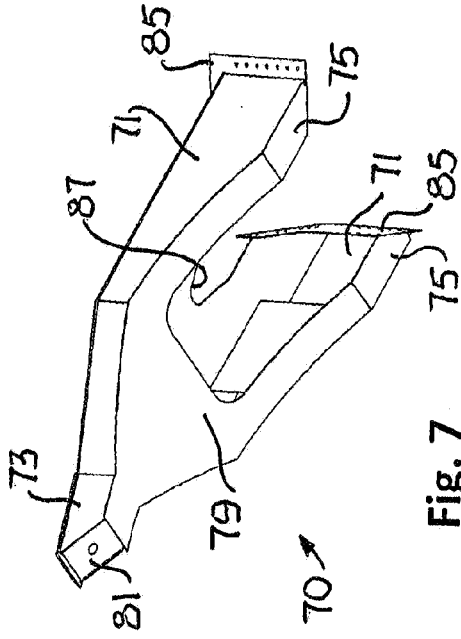


Fig. 7

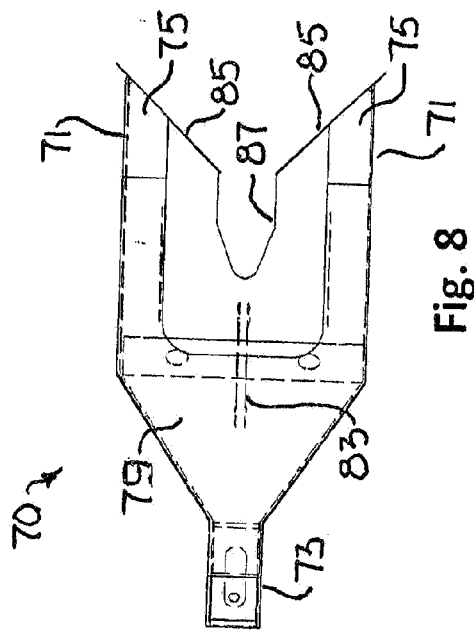


Fig. 8

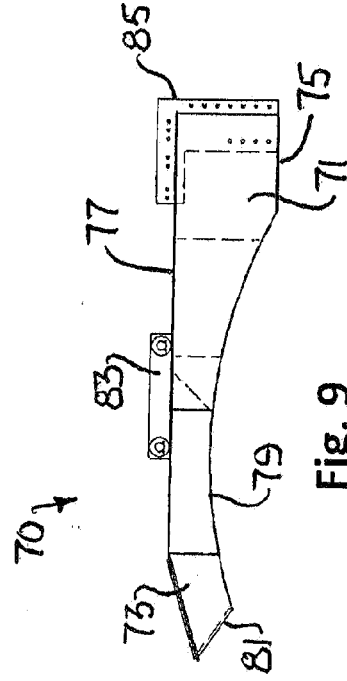


Fig. 9

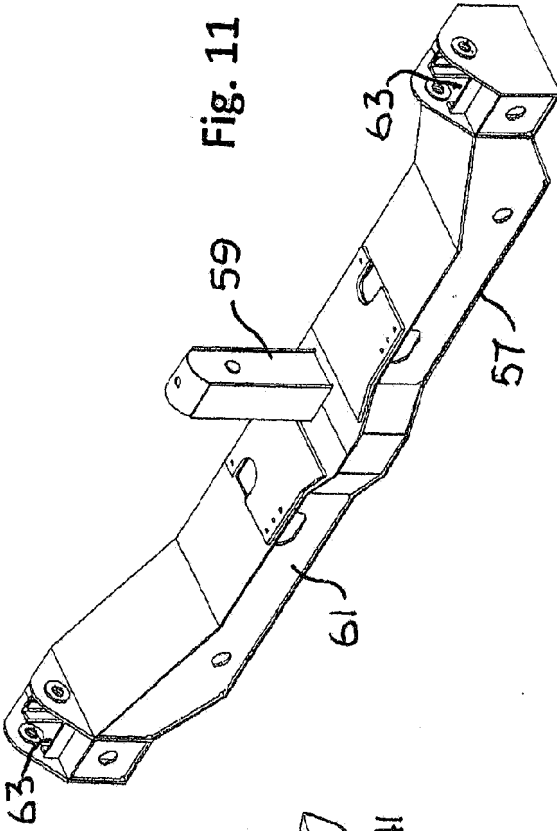


Fig. 10

Fig. 11

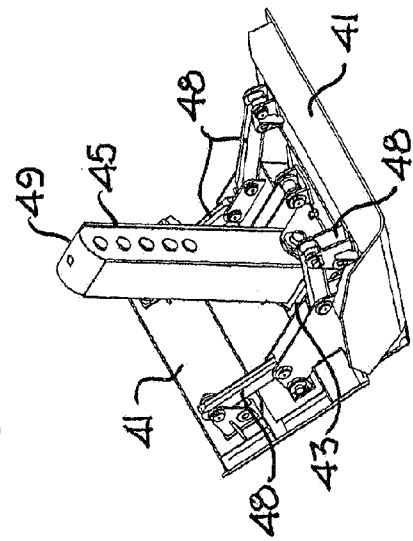


Fig. 12

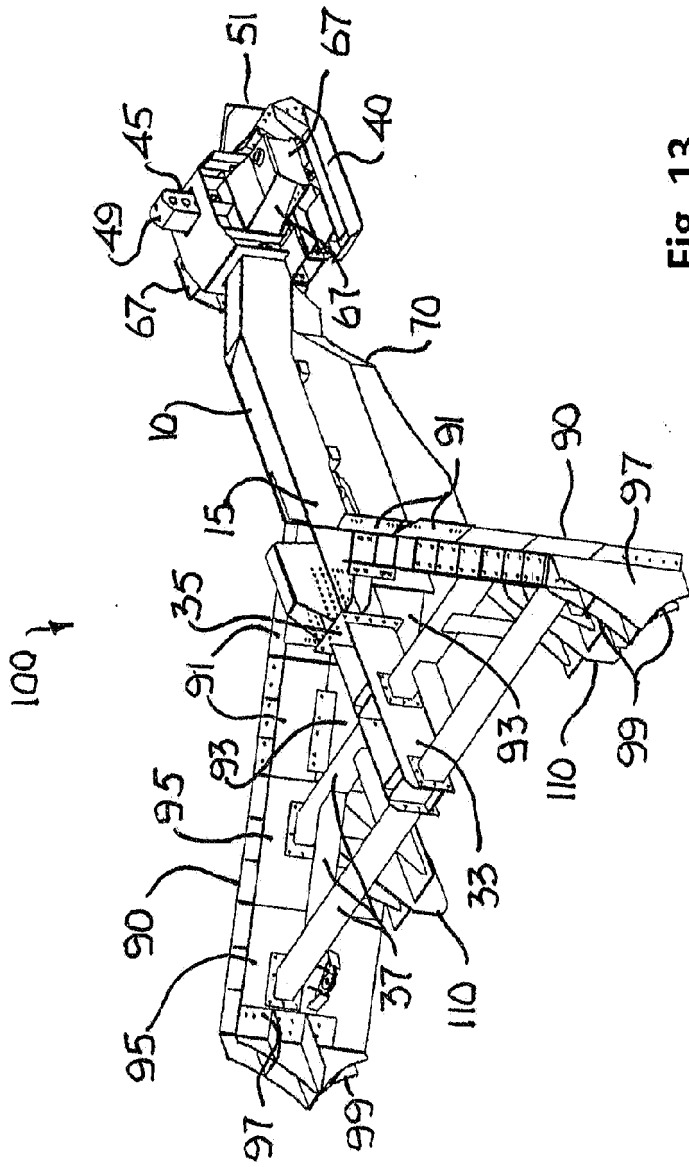


Fig. 13

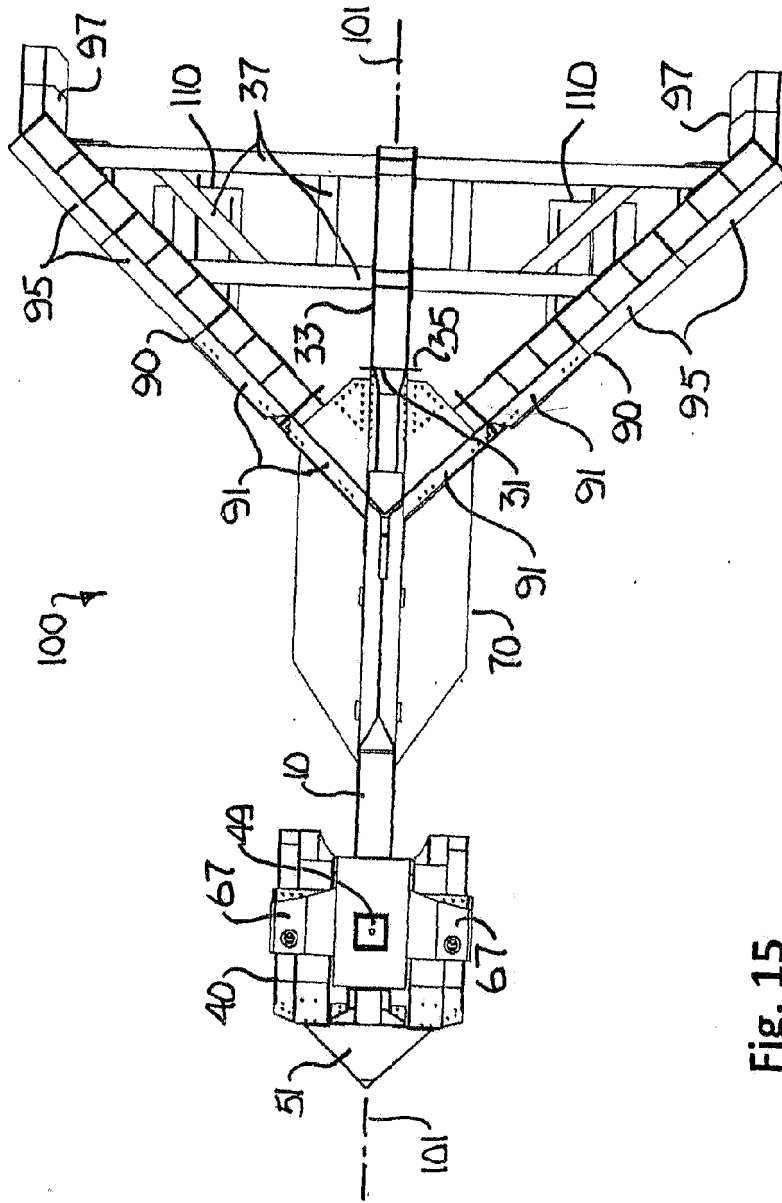
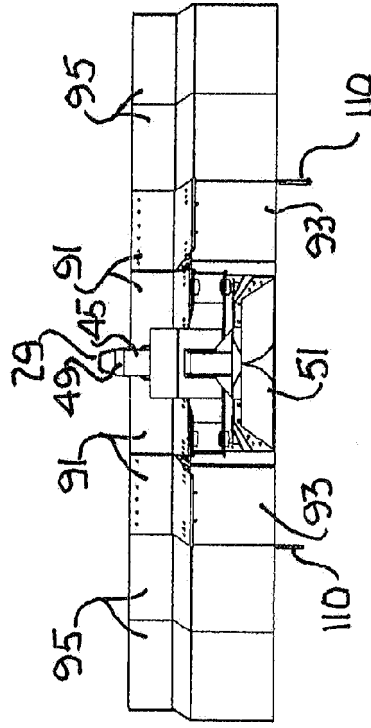
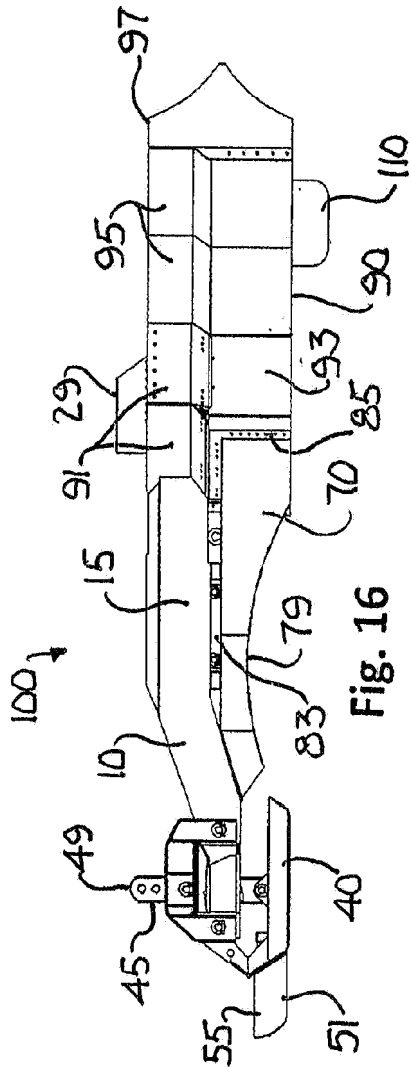


Fig. 15



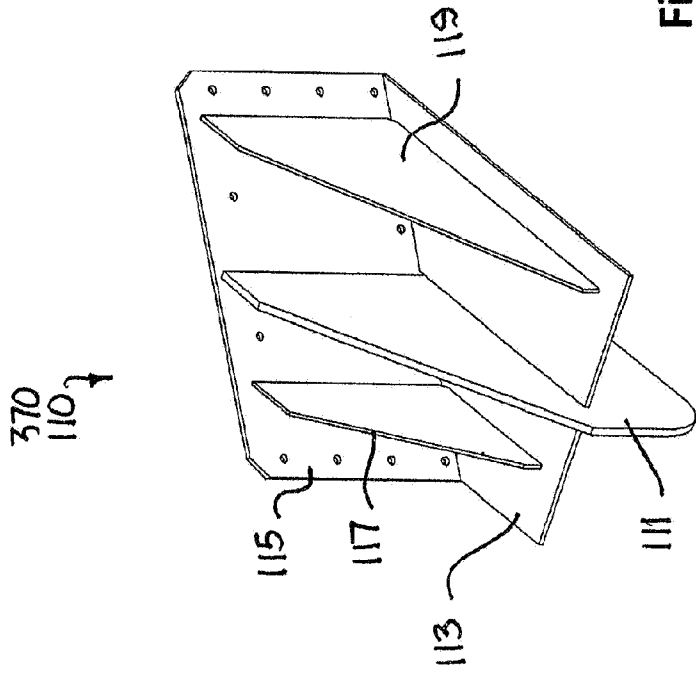


Fig. 18

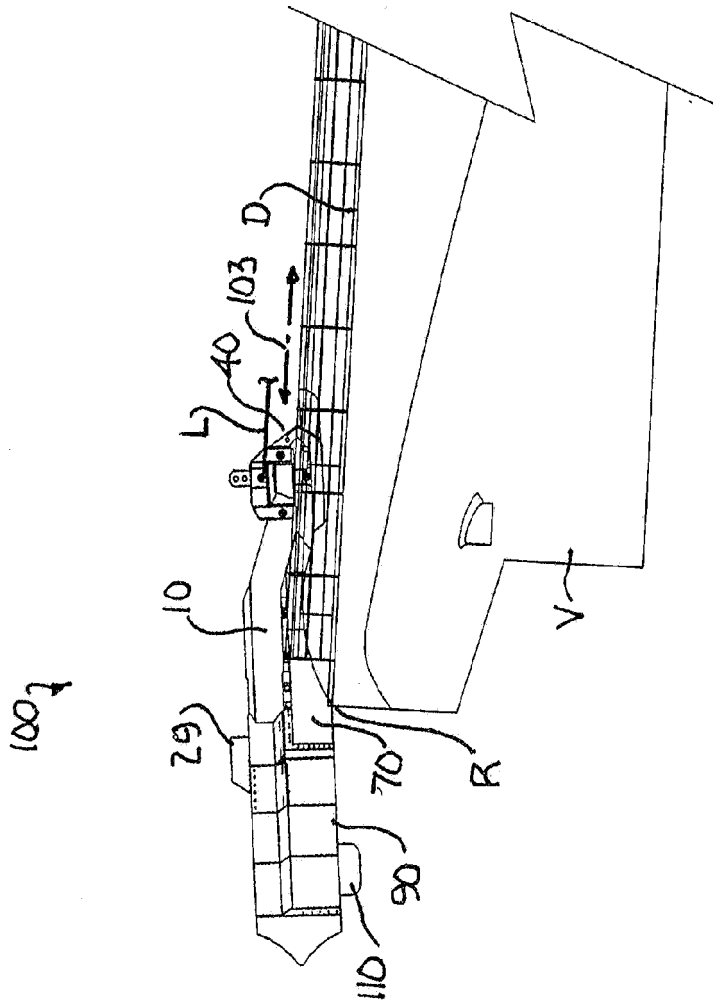


Fig. 19

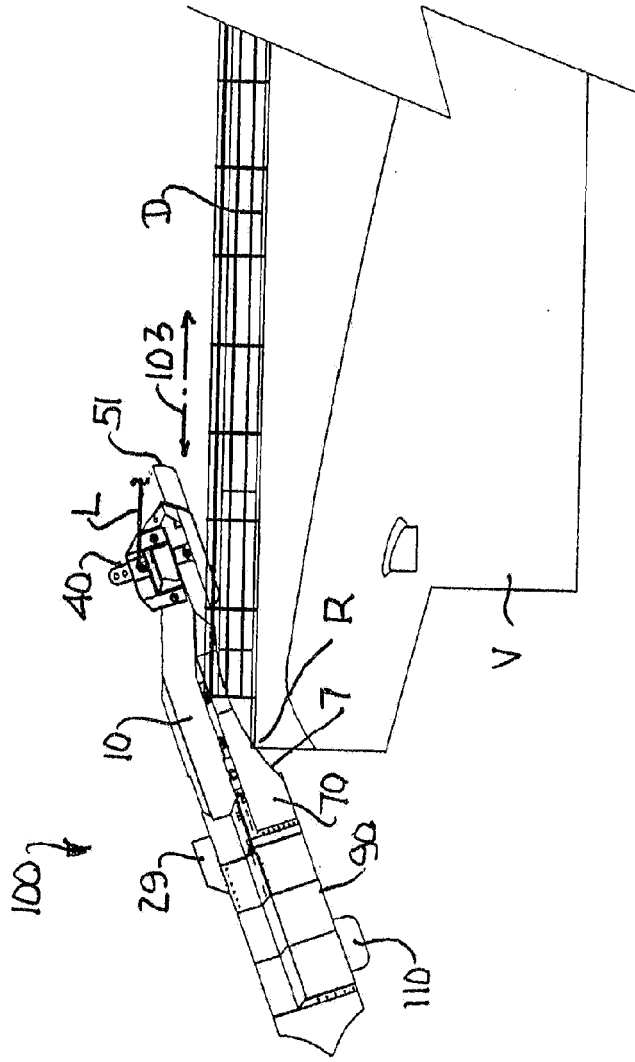


Fig. 20

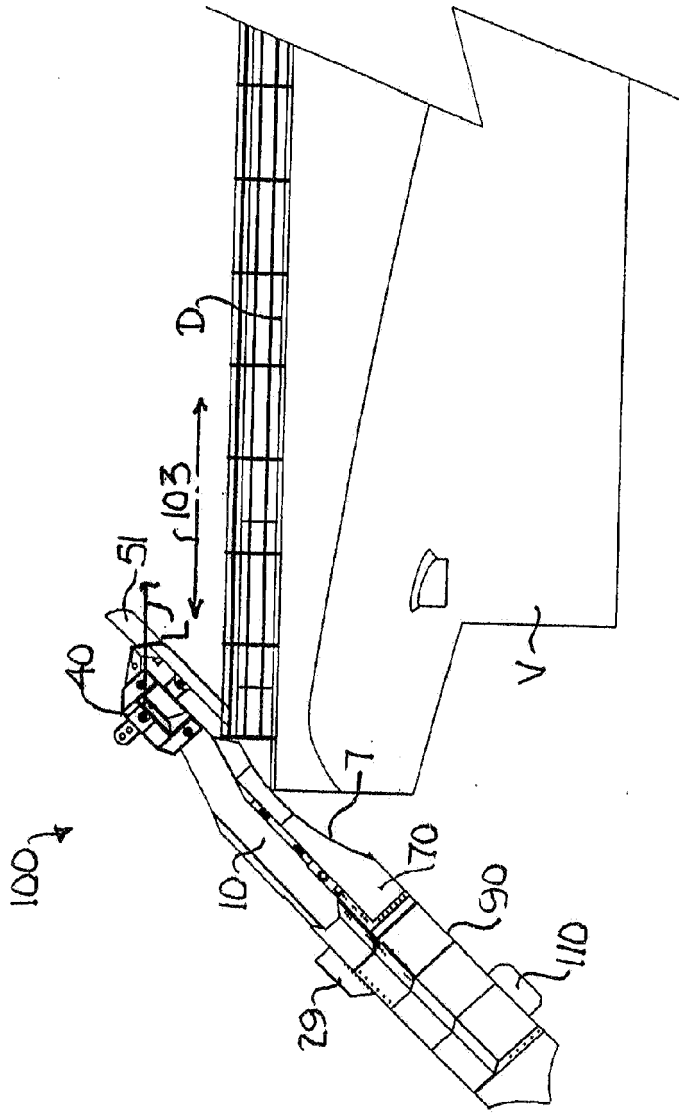


Fig. 21

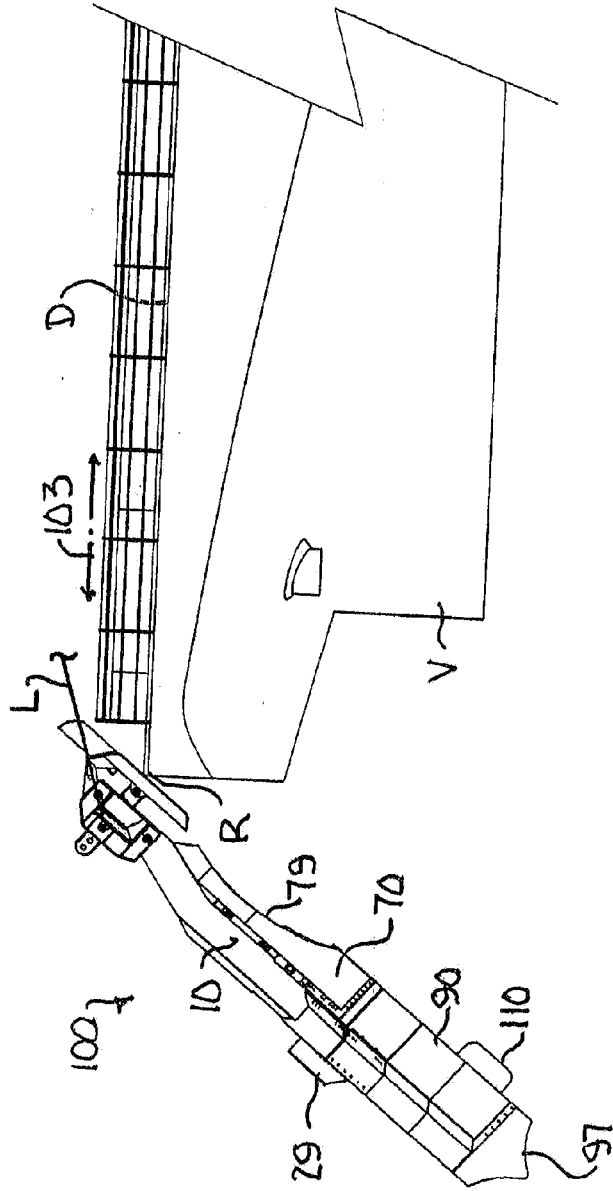


Fig. 22

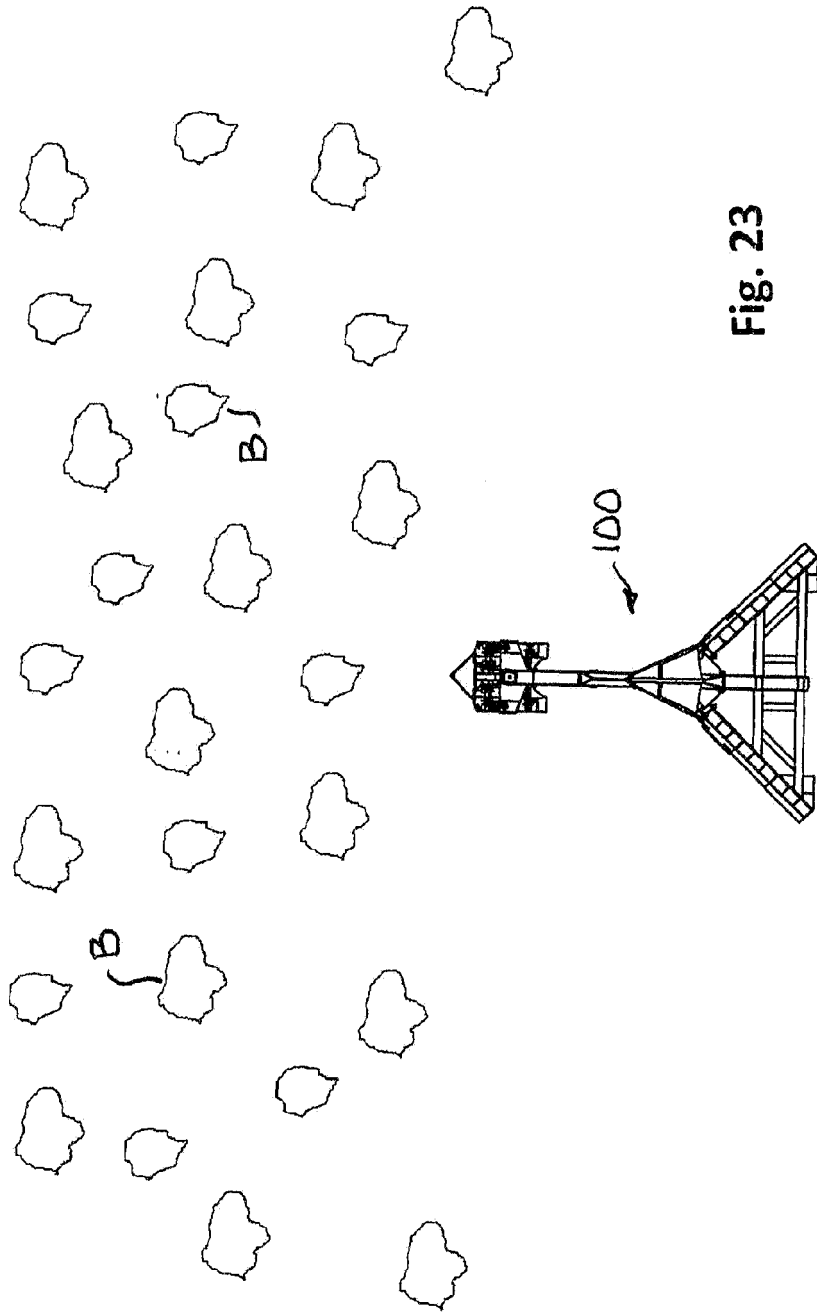


Fig. 23

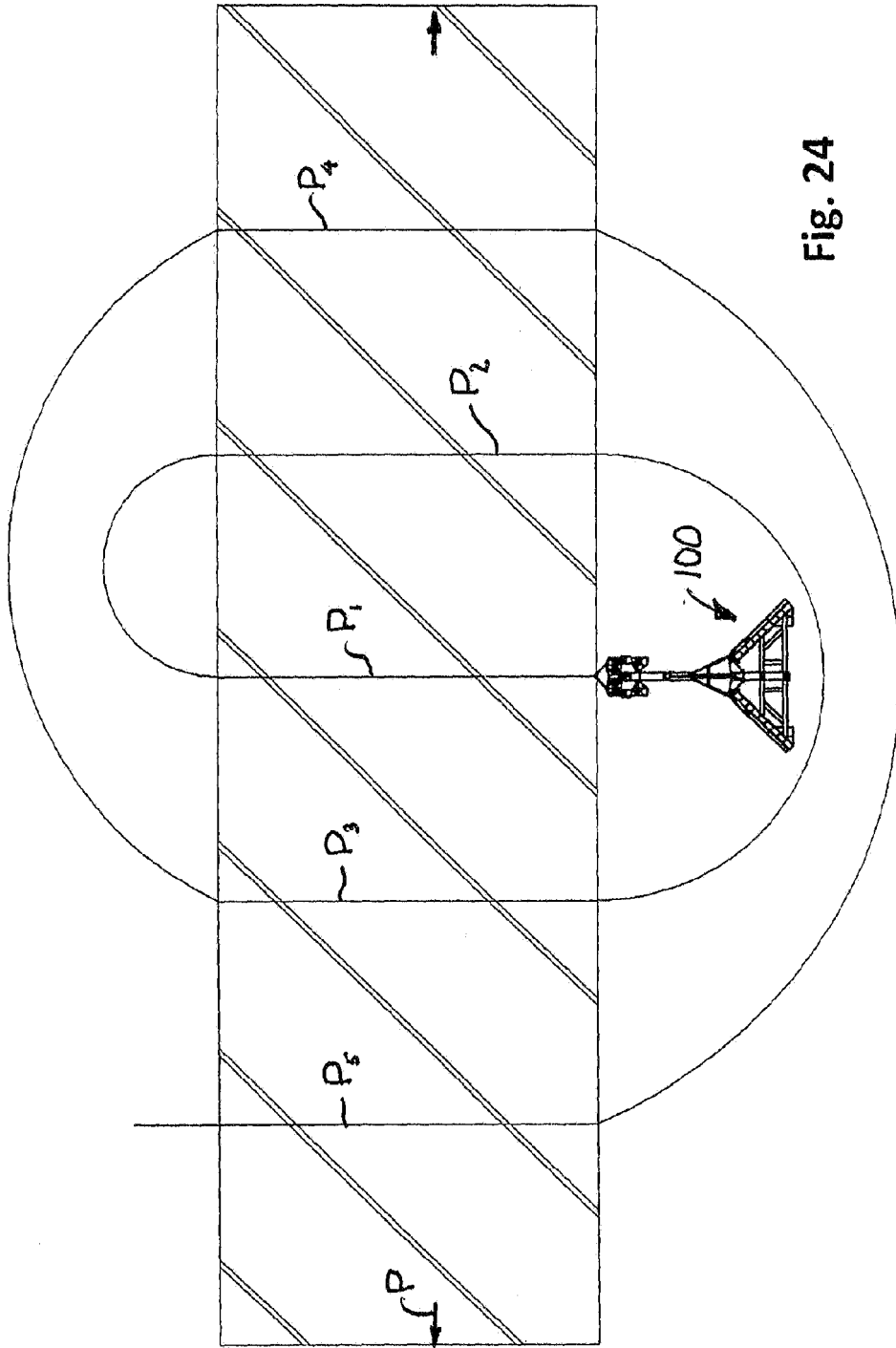


Fig. 24

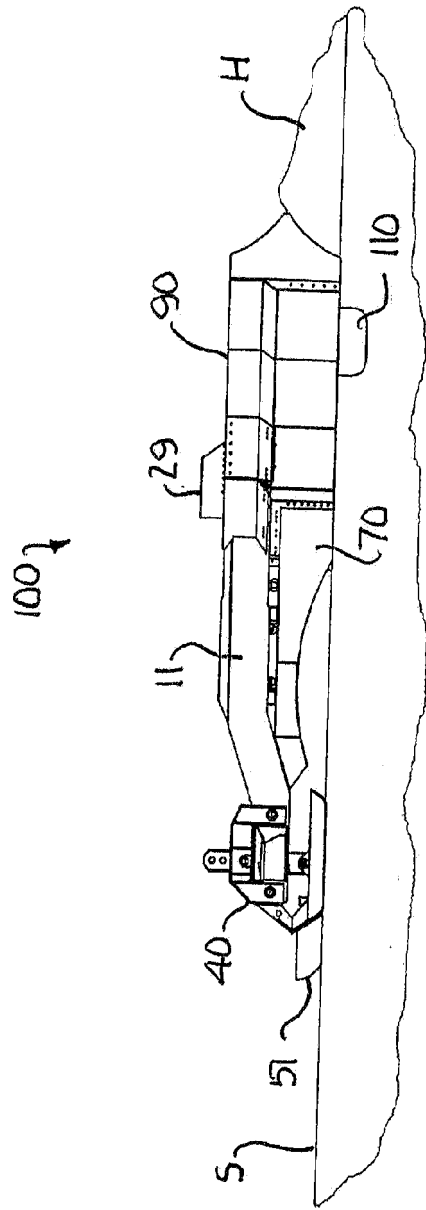


Fig. 25

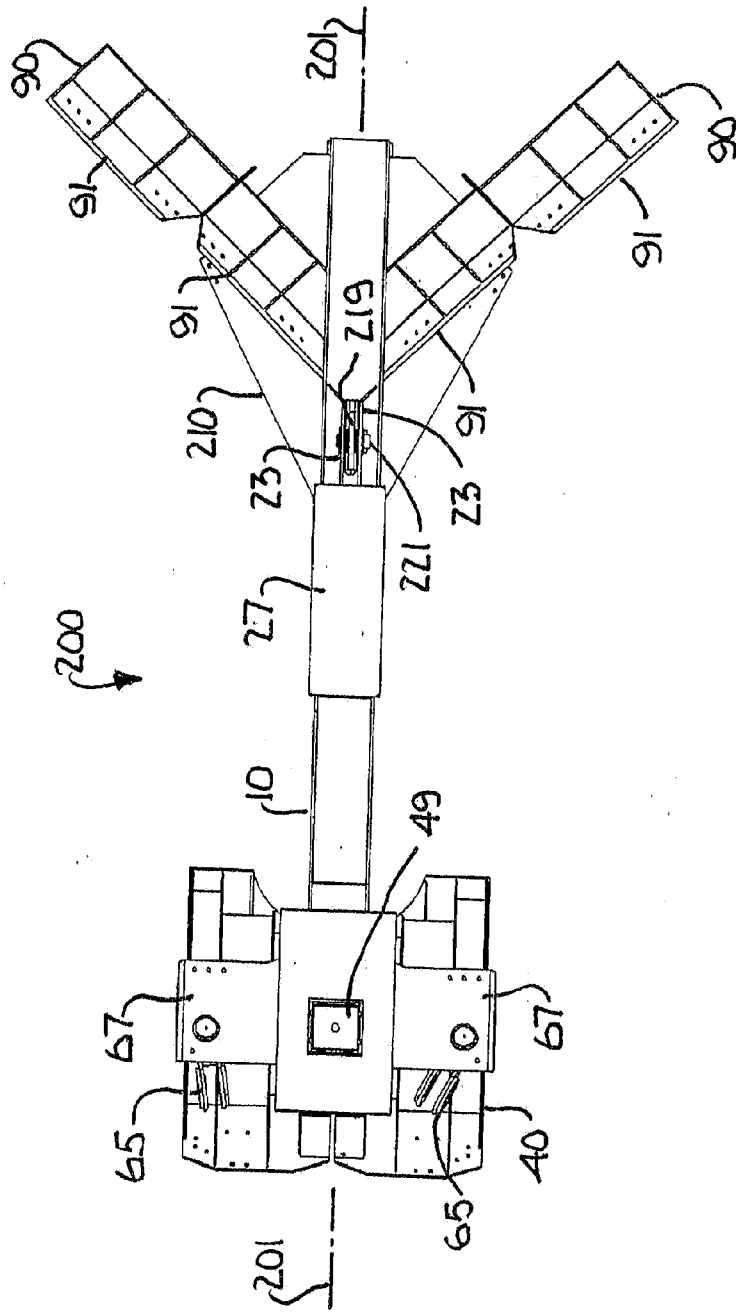


Fig. 27

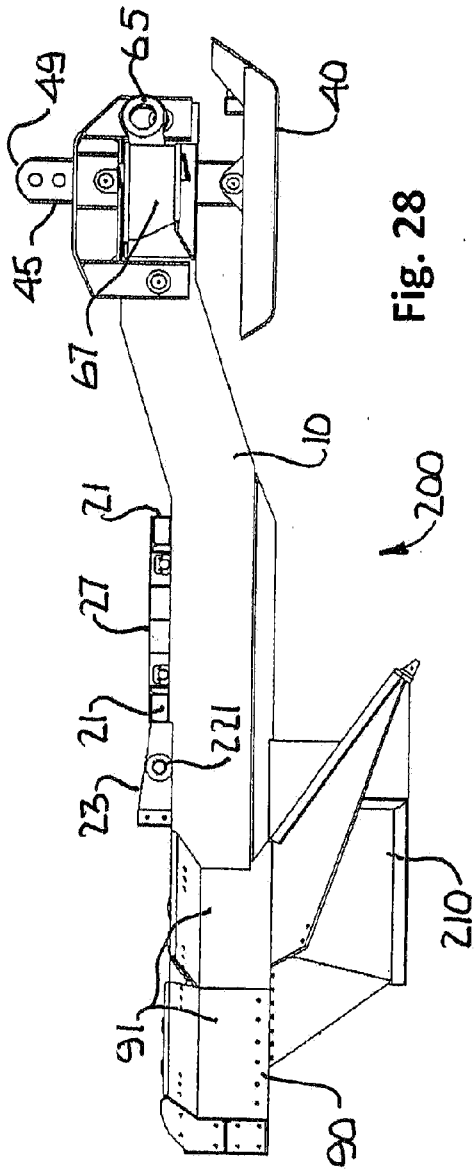


Fig. 28

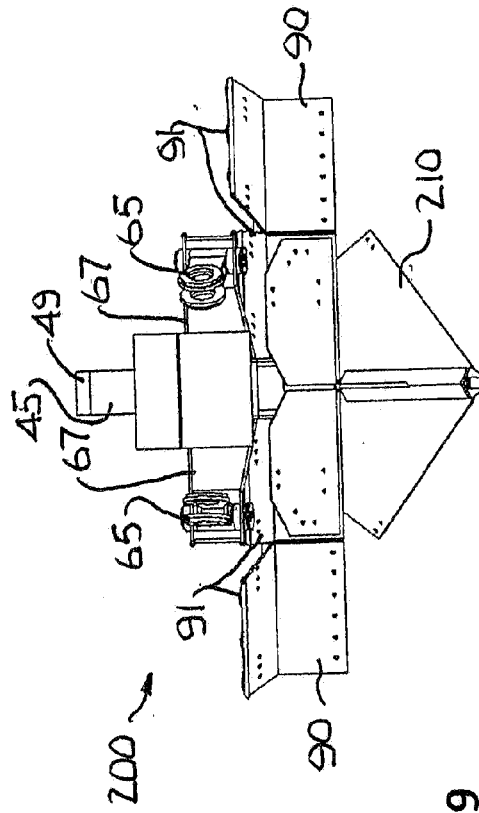
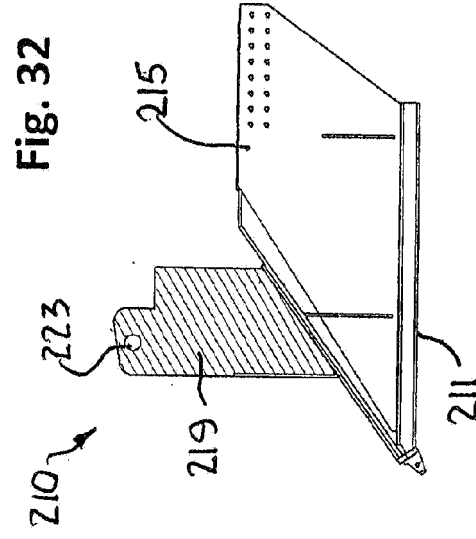
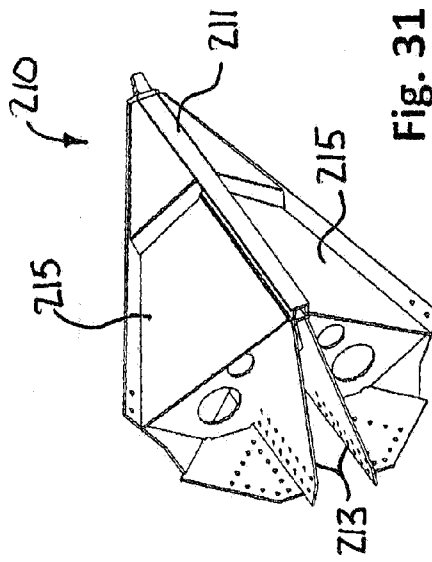
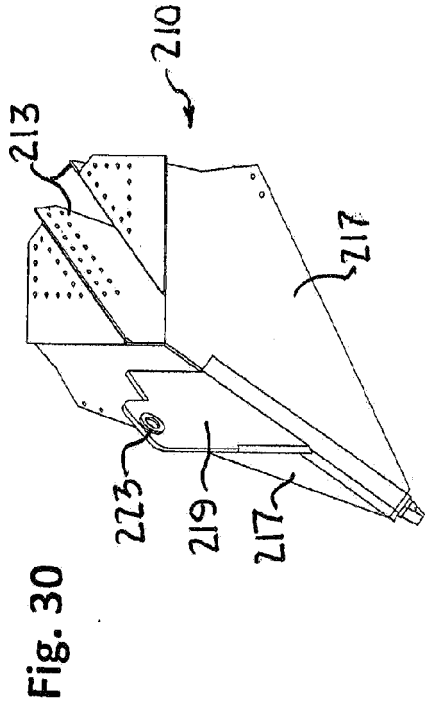


Fig. 29



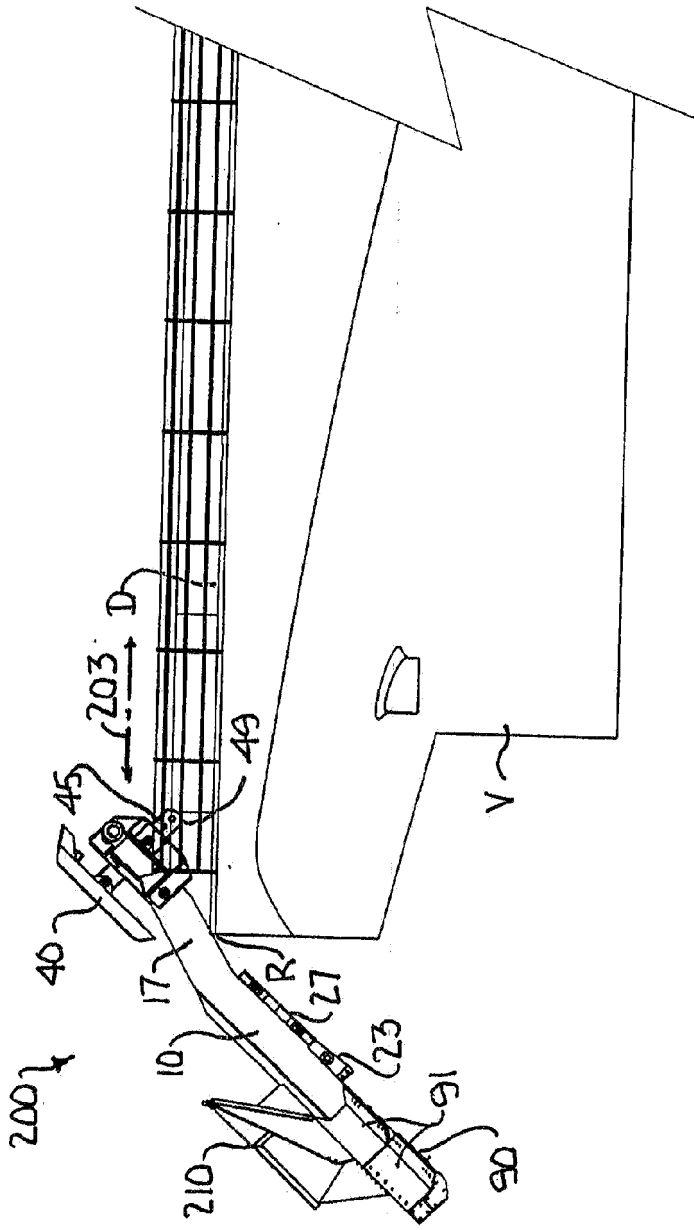


Fig. 34

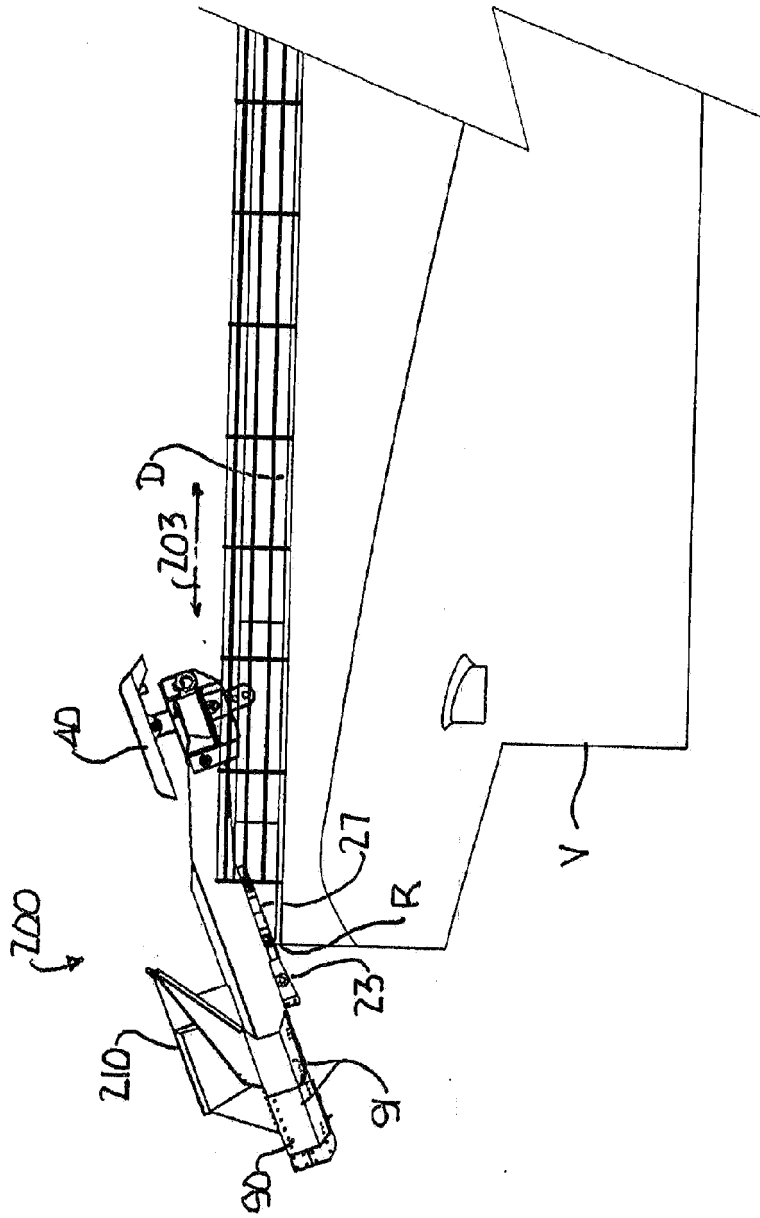


Fig. 35

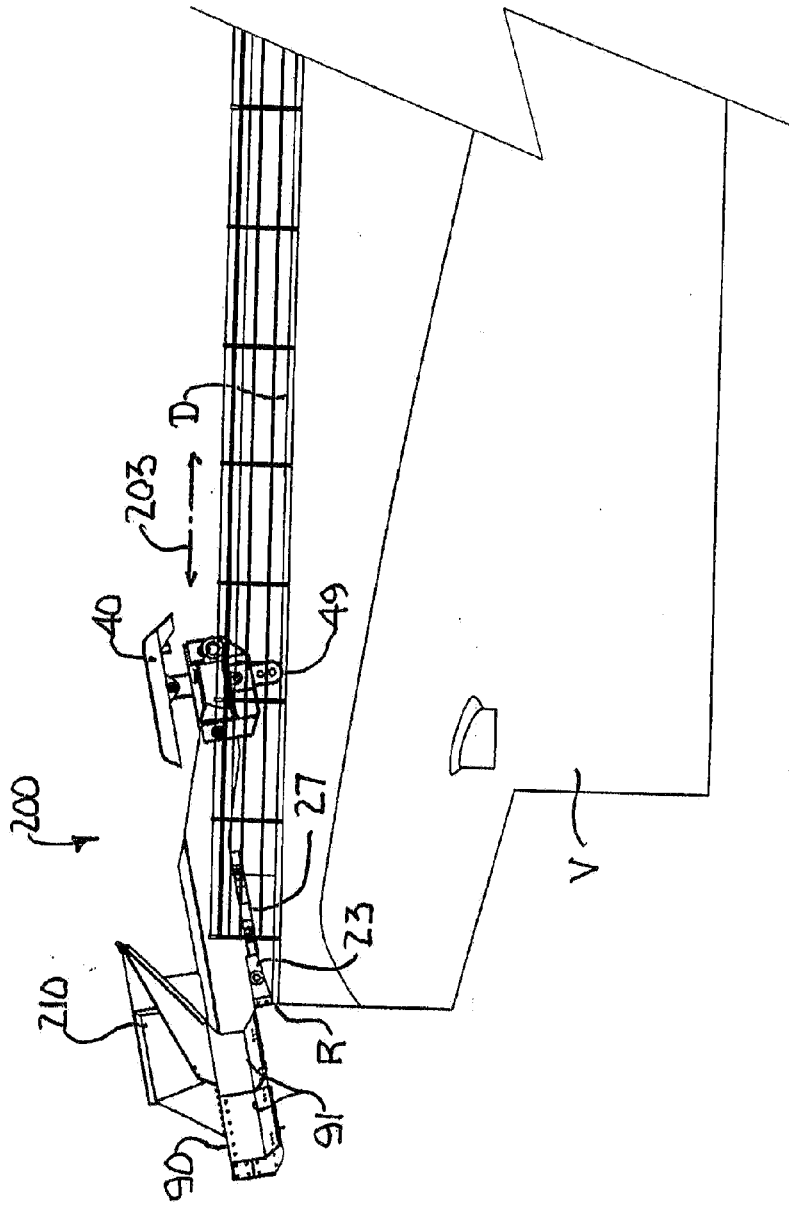


Fig. 36

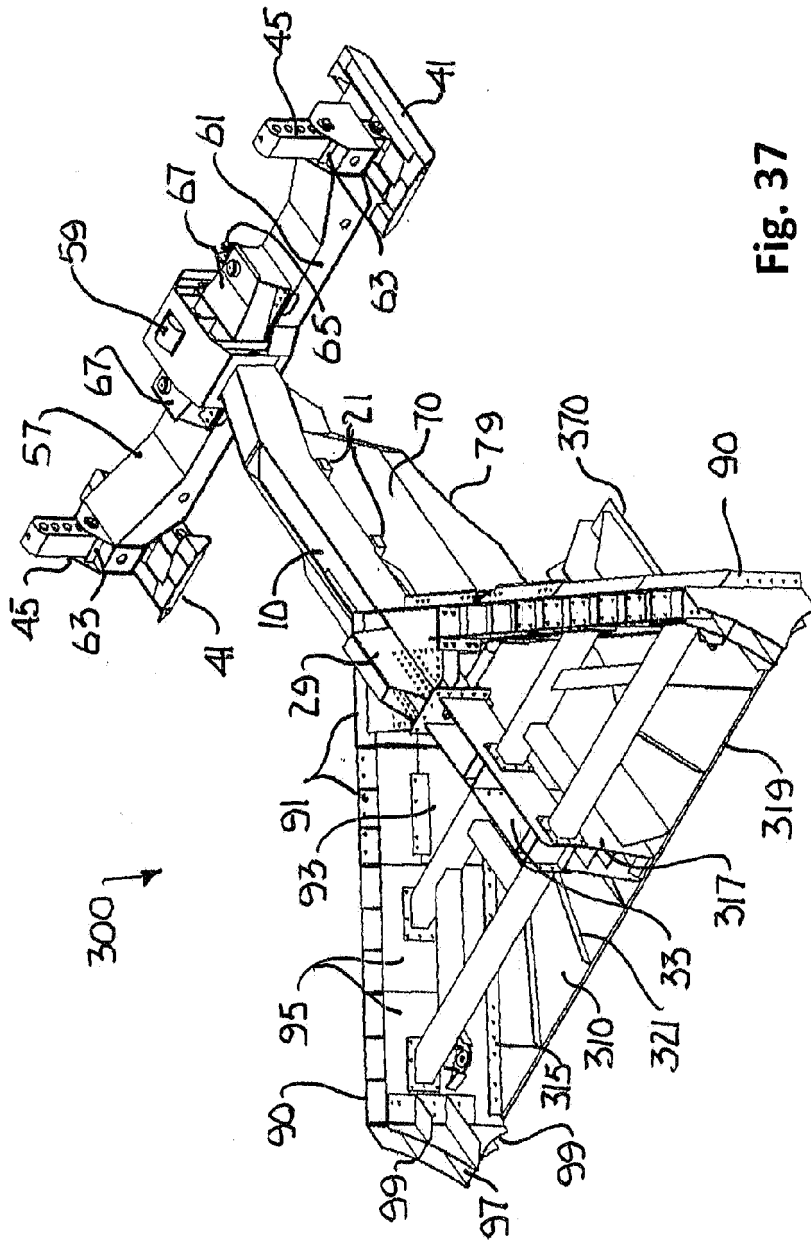


Fig. 37

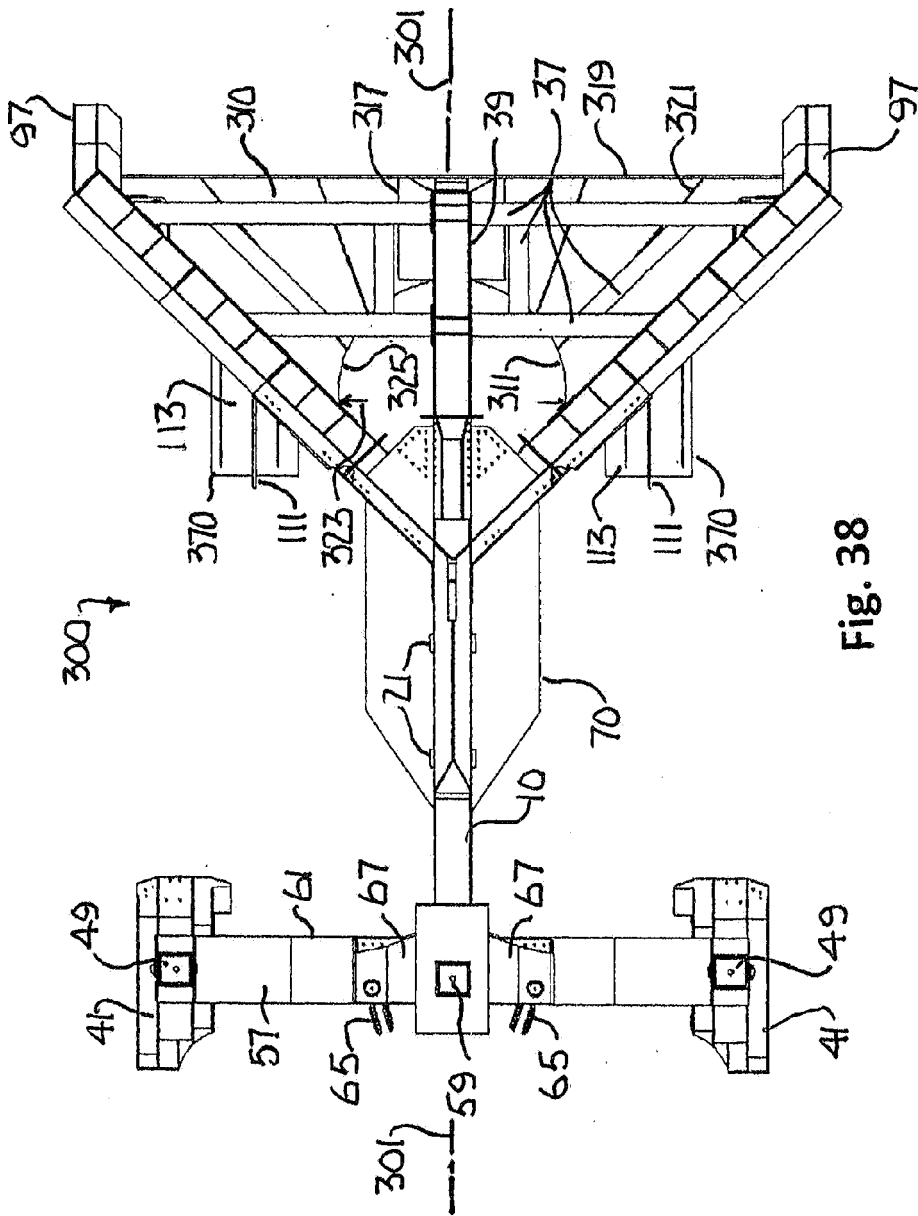


Fig. 38

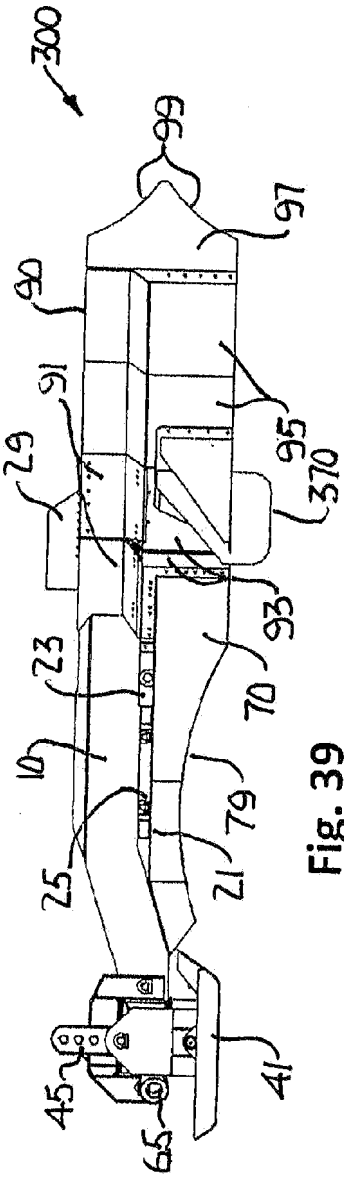
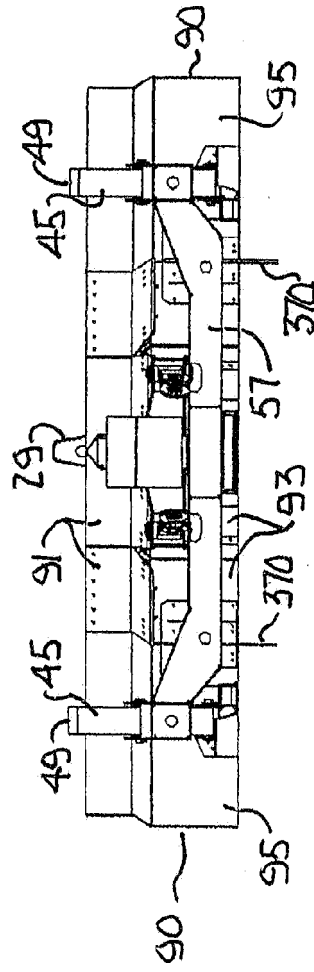


Fig. 39

Fig. 40

300



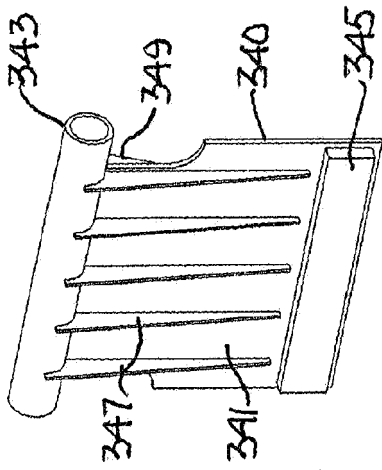


Fig. 42

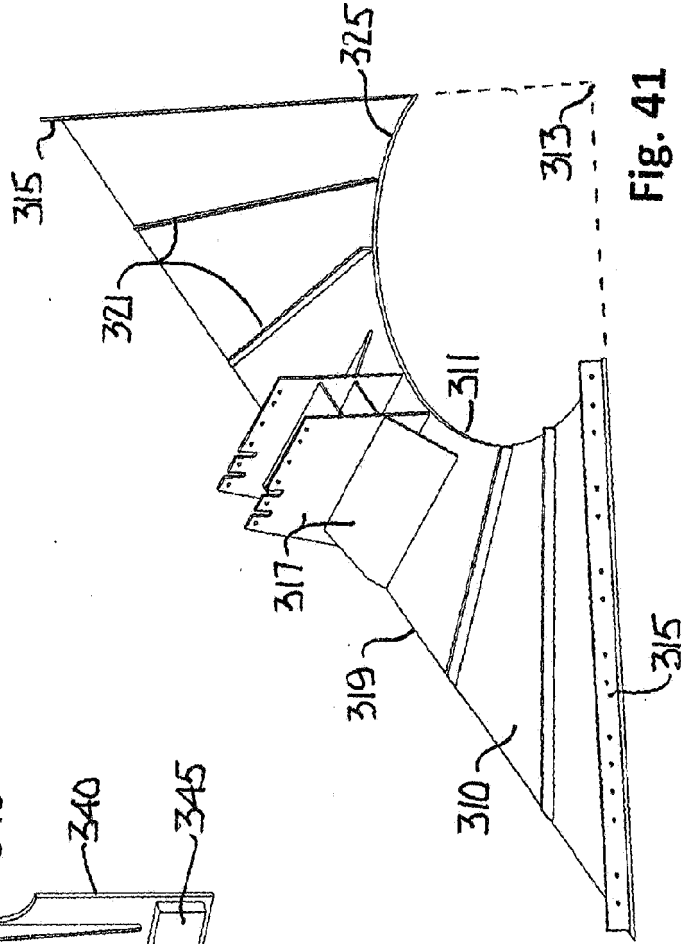


Fig. 41

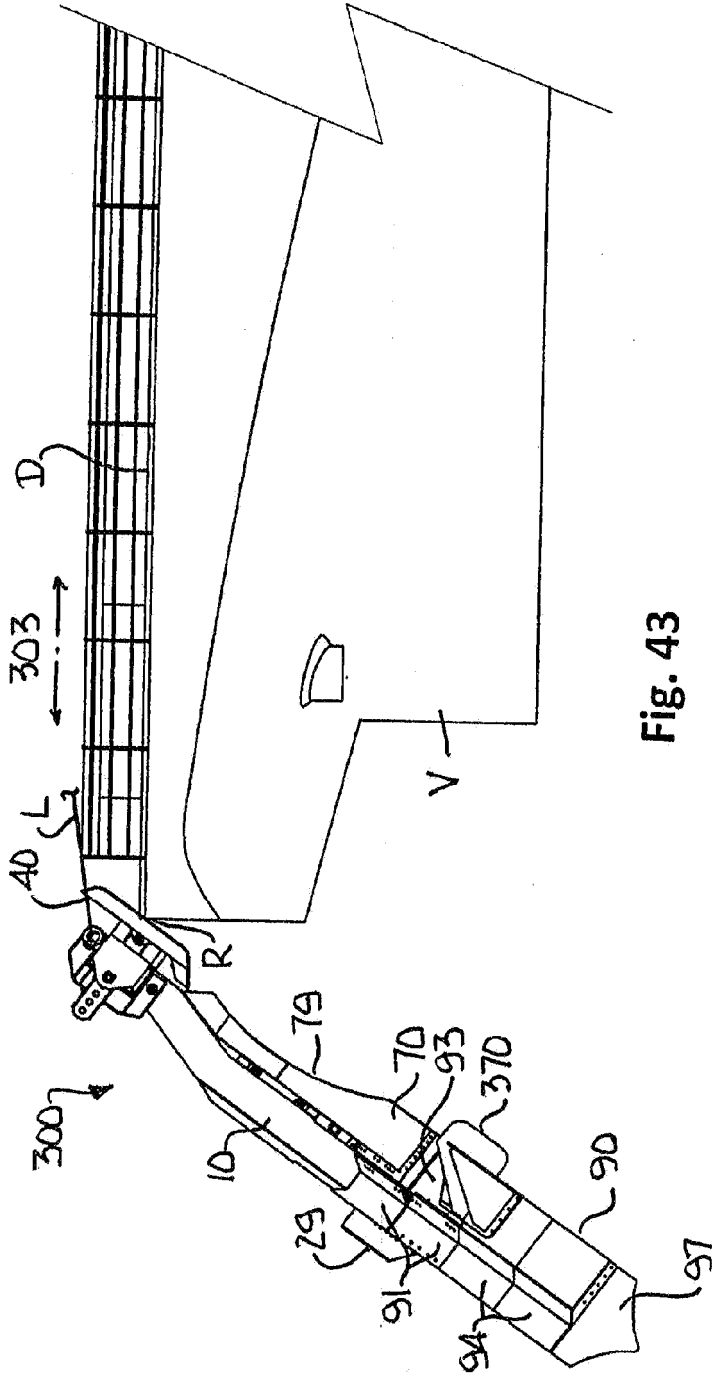


Fig. 43

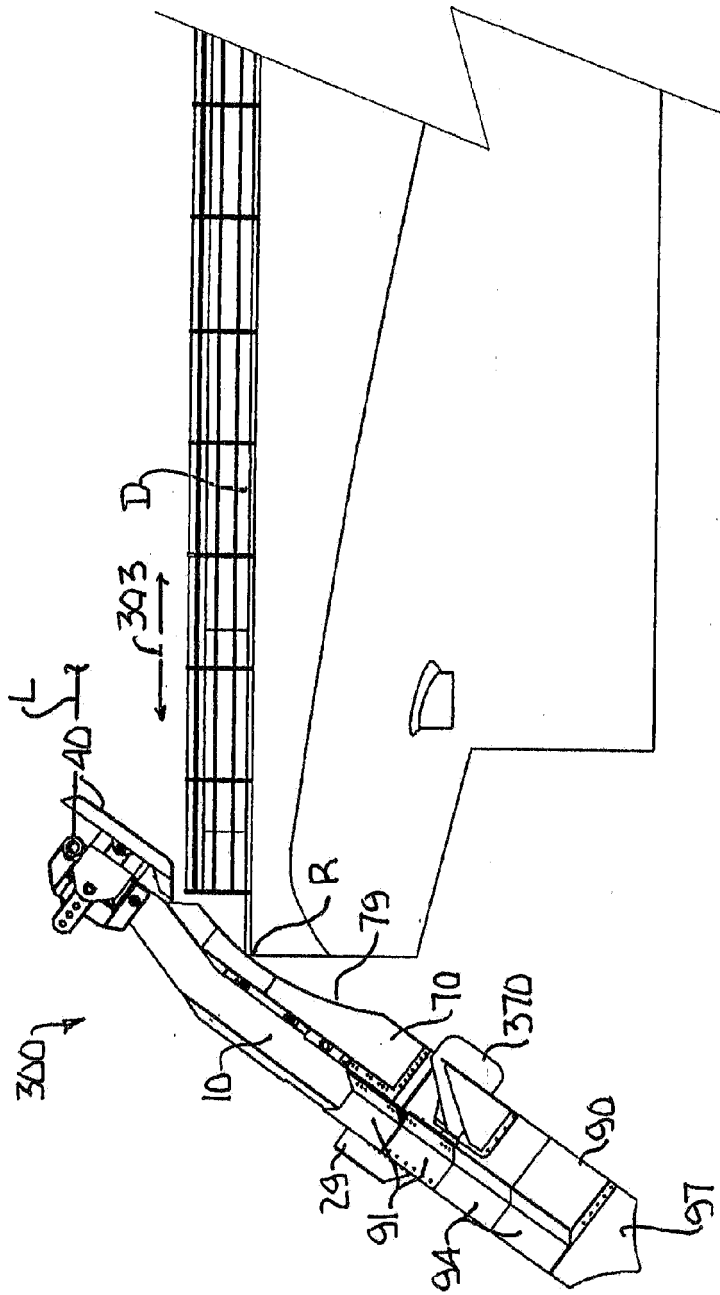


Fig. 44

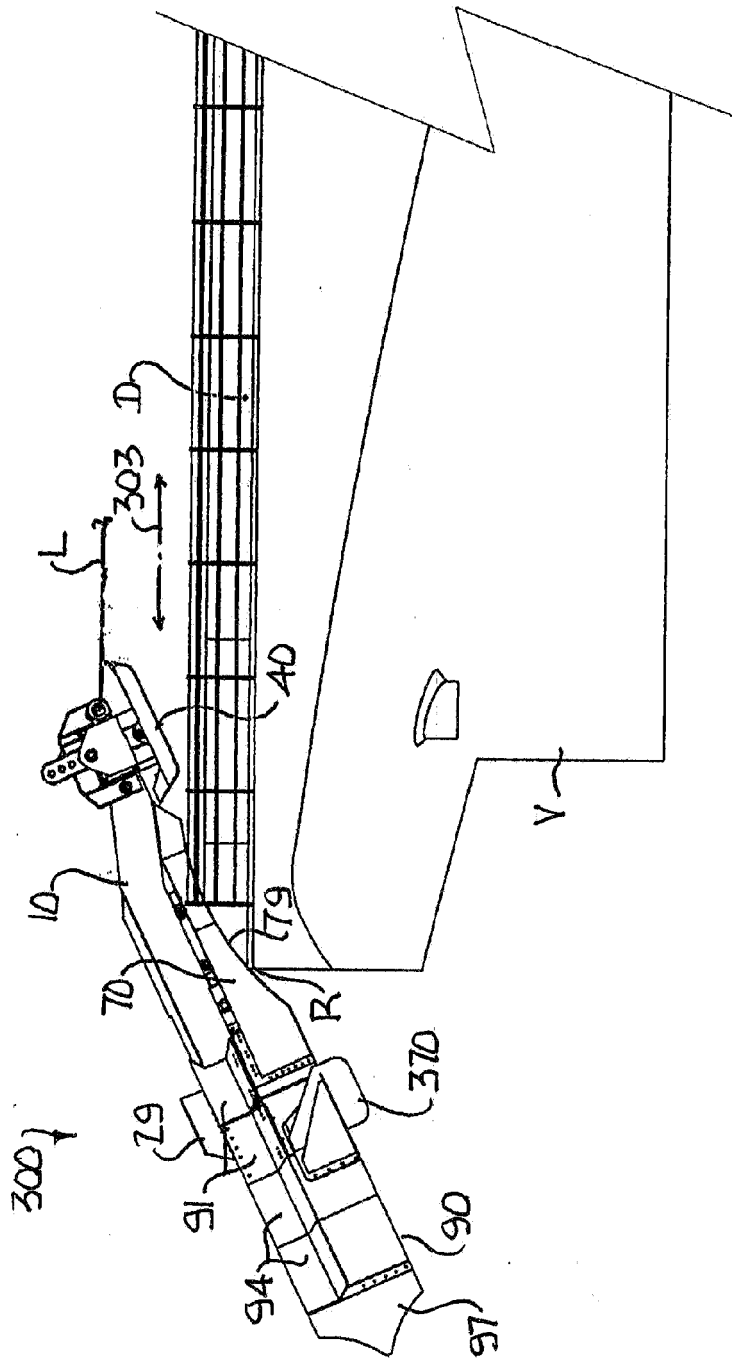


Fig. 45

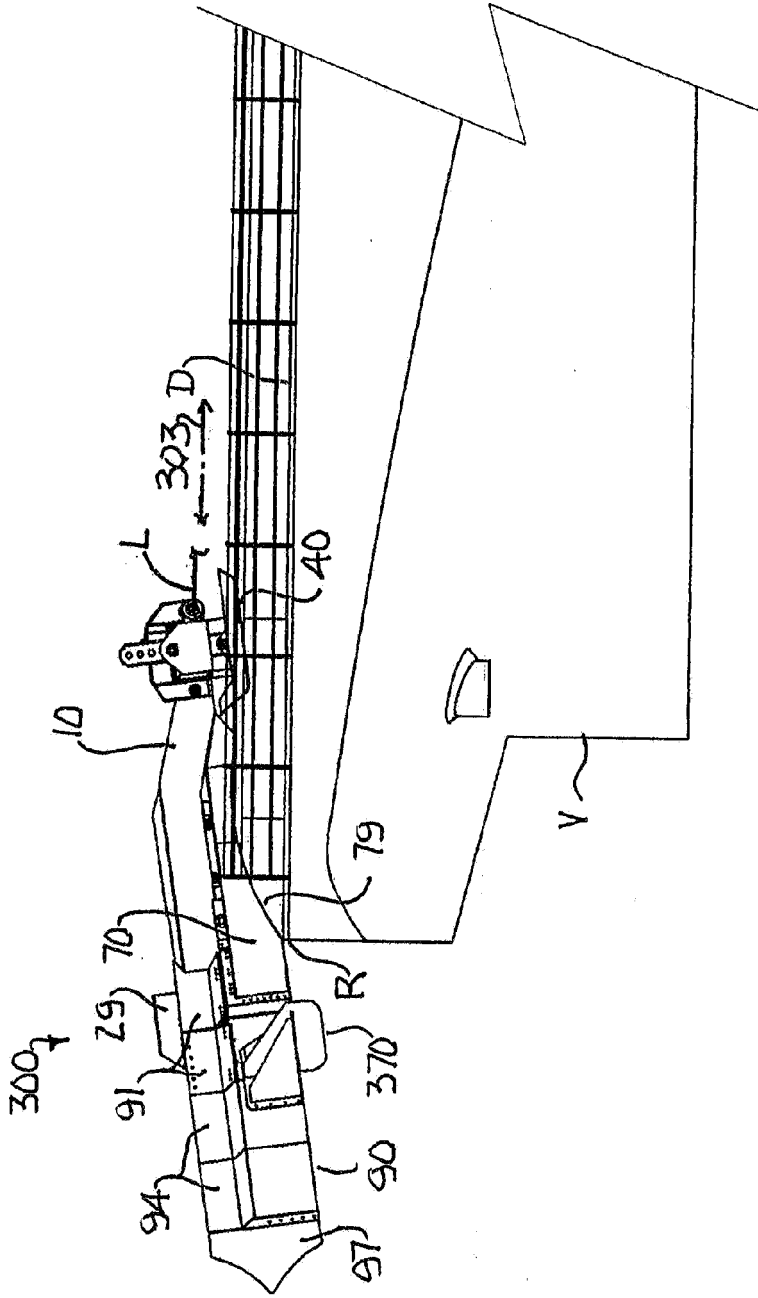


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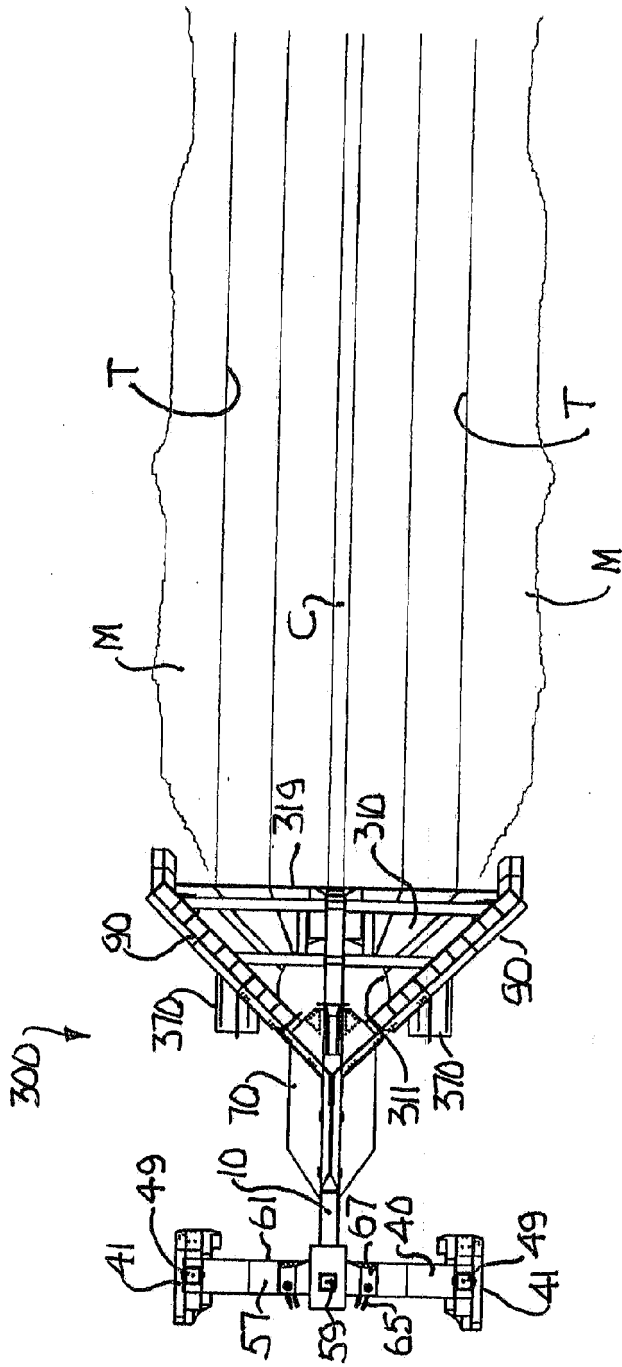


Fig. 47

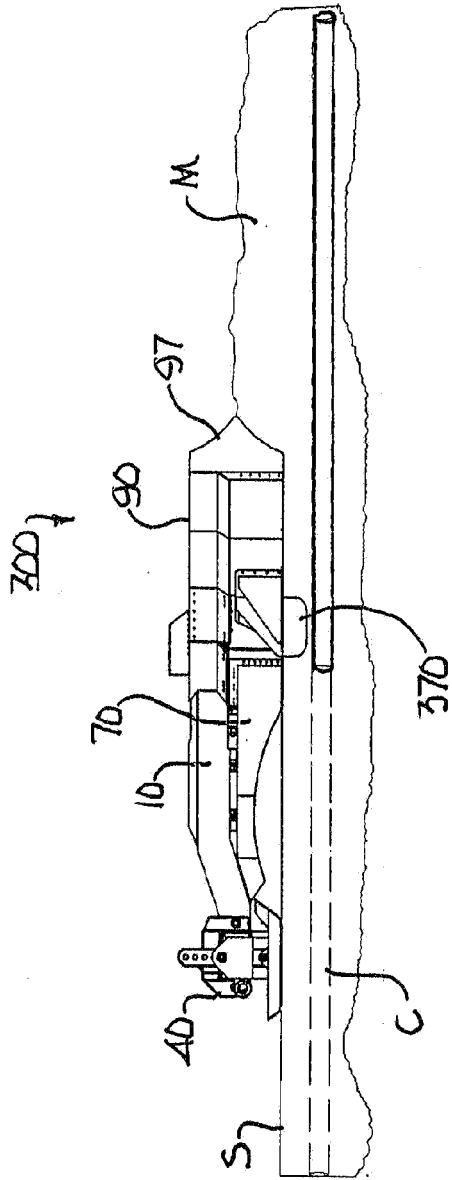


Fig. 48

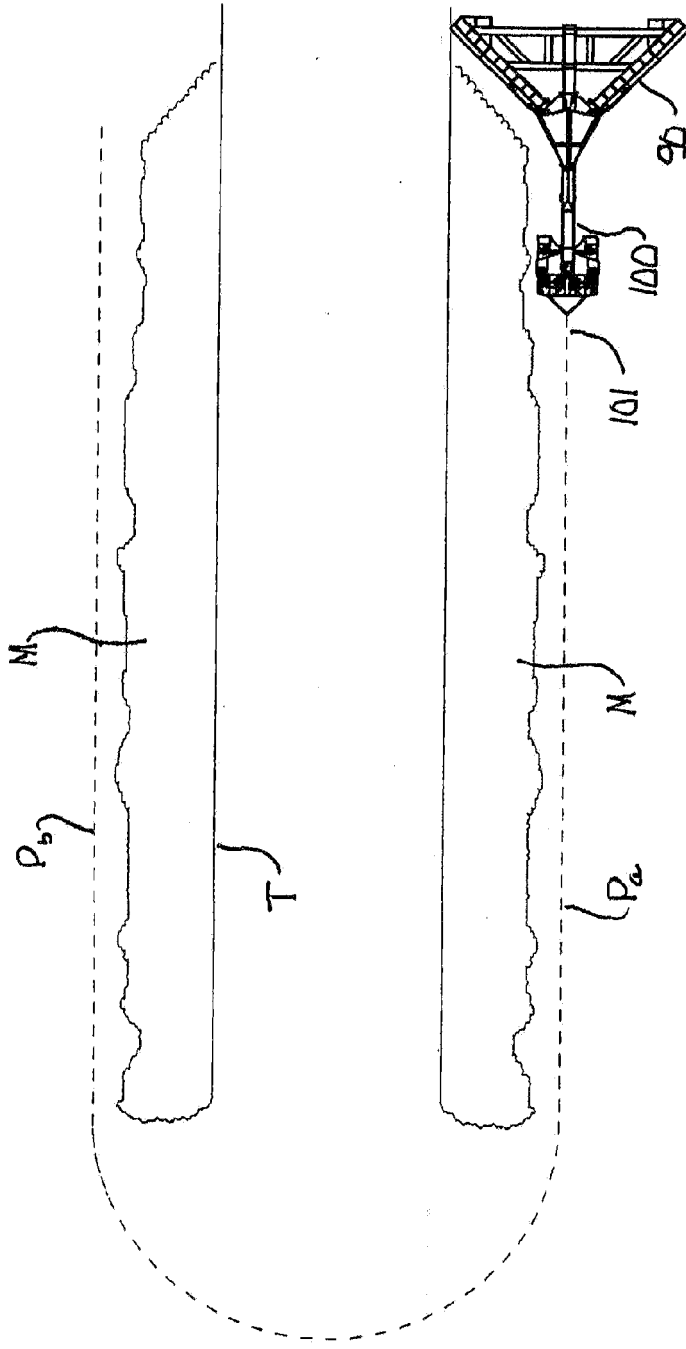


Fig. 49

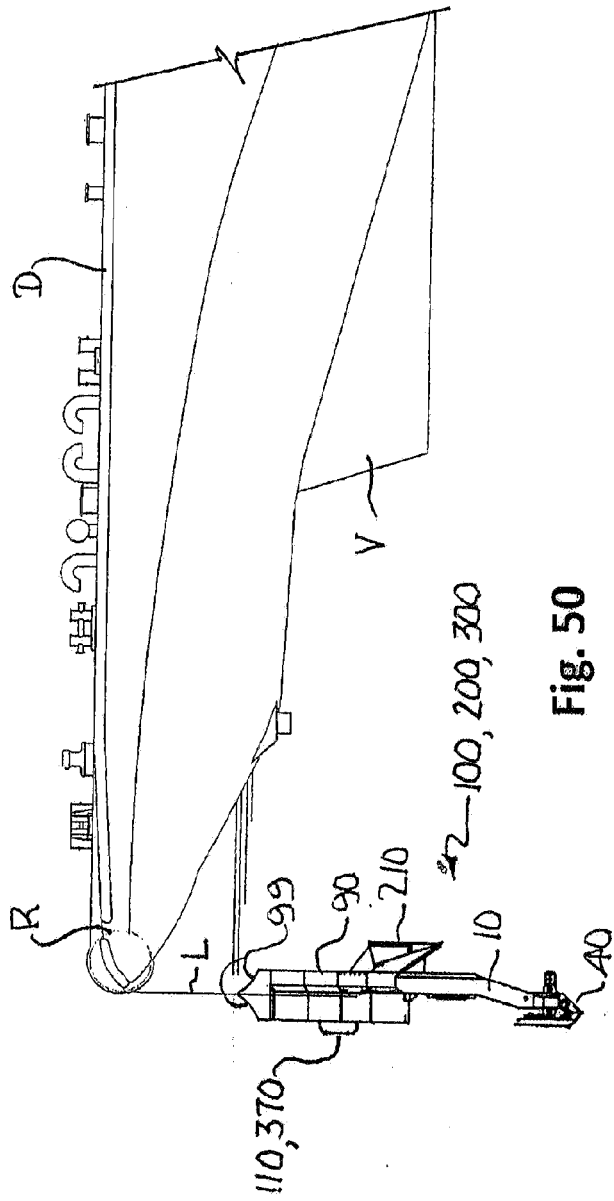


Fig. 50