



(51) International Patent Classification:

B62D 53/00 (2006.01) B62D 53/08 (2006.01)

(21) International Application Number:

PCT/US2015/058381

(22) International Filing Date:

30 October 2015 (30.10.2015)

(25) Filing Language:

English

(26) Publication Language:

English

(30) Priority Data:

62/072,543 30 October 2014 (30.10.2014) US

(71) Applicant: CROSS ROAD CENTERS, INC. [US/US];

32 East Airline Highway, Kenner, Louisiana 70062 (US).

(72) Inventor: MAINS, Ronald H.; 32 East Airline Highway,

Kenner, Louisiana 70062 (US).

(74) Agent: MUELLER, Jason P.; 701 Poydras Street, Suite

4500, New Orleans, Louisiana 70139 (US).

(81) Designated States (unless otherwise indicated, for every

kind of national protection available): AE, AG, AL, AM, AO, AT, AU, AZ, BA, BB, BG, BH, BN, BR, BW, BY, BZ, CA, CH, CL, CN, CO, CR, CU, CZ, DE, DK, DM, DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IR, IS, JP, KE, KG, KN, KP, KR,

KZ, LA, LC, LK, LR, LS, LU, LY, MA, MD, ME, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PA, PE, PG, PH, PL, PT, QA, RO, RS, RU, RW, SA, SC, SD, SE, SG, SK, SL, SM, ST, SV, SY, TH, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.

(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LR, LS, MW, MZ, NA, RW, SD, SL, ST, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, RU, TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV, MC, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK, SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, KM, ML, MR, NE, SN, TD, TG).

Declarations under Rule 4.17:

- as to the identity of the inventor (Rule 4.17(i))
- as to applicant's entitlement to apply for and be granted a patent (Rule 4.17(ii))
- as to the applicant's entitlement to claim the priority of the earlier application (Rule 4.17(iii))

Published:

- with international search report (Art. 21(3))

(54) Title: METHODS, APPARATUSES, AND SYSTEMS FOR TRANSPORTATION

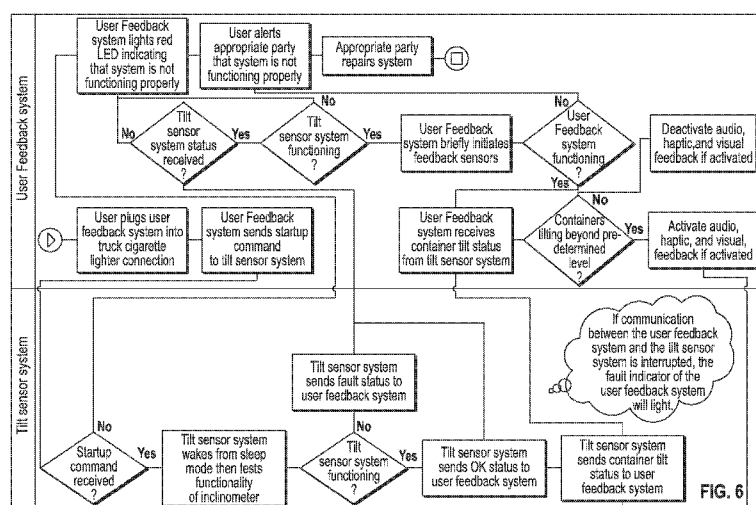


FIG. 6

(57) **Abstract:** Embodiments of the present disclosure include methods, apparatuses, and systems for receiving feedback during transport. Embodiments include a transportation system comprising a tractor, a dolly attached to opposing ends of a first and second trailer, and a sensor feedback system. Sensor feedback system may include a tilt sensor system mounted on at least one of the dolly, the first trailer, and the second trailer, and a user feedback system mounted within the tractor. Tilt sensor system may measure tilt of at least one of the dolly, first and second trailers, and first and second containers attached to the first and second trailers, to obtain tilt information, and send tilt information to the user feedback system via a communication system. User feedback system may receive the tilt information and alert a driver of the tractor if the tilt information is above a predetermined level.

METHODS, APPARATUSES, AND SYSTEMS FOR TRANSPORTATION

This application claims the benefit of U.S. Provisional Patent Application No. 62/072,543, filed on October 30, 2014, which is incorporated herein by reference.

5 Efficient tractor transport of heavy and/or bulky loads has been hindered in the trucking industry by inefficient axel loading. Hauling heavy loads in single trailers and containers has not been possible because of the weight such loads place on individual axles. Large individual axle loads have been known to cause damage to roadways and have been banned by various local, state, and federal governments.

10 Indeed, loads that exceed legal limits for maximum axle weight have often been broken down into smaller loads that are transported by multiple tractors. Bulky loads have posed similar issues. Trailers may only be partially loaded because of the shape and configuration of the containers they are transporting, for example, plane, shipping and/or train containers. For example, a single shipping/train container is often pulled

15 by a single tractor well below axle weight maximums.

Another issue with tractor transport of freight using trailers and/or containers involves the tilt that occurs when making a turn using the tractor. When a driver makes a turn, it is usually normal for the trailers and/or containers to tilt along the roll axis. However, if the driver turns at an excessive speed or if the turn itself is

20 hazardously sharp, the trailers and/or containers may tilt excessively, which may damage the freight inside the containers. In some instances, the containers may overturn, potentially injuring the driver and/or other drivers and pedestrians.

BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1 is an isometric view of a freight transportation system, according to an

25 exemplary embodiment of the present disclosure;

Figure 2 is a side view of a two axle dolly, according to an exemplary embodiment of the present disclosure;

Figure 3 is a top view of the two axle dolly shown in Figure 2;

Figure 4 is an isometric view of the two axle dolly shown in Figure 2;

Figure 5 is a schematic of a sensor feedback system, according to an exemplary embodiment of the present disclosure.

- 5 **Figure 6** is a flowchart of a sensor feedback system, according to an exemplary embodiment of the present disclosure.

DESCRIPTION OF EMBODIMENTS

Methods, apparatuses, and systems are provided for transporting multiple trailers and containers via a dolly system. Embodiments provide a freight
10 transportation system having a dolly system. In embodiments, a two axle dolly system may be secured to multiple trailers and/or containers. Dolly system may be used to safely and securely distribute axle weights and allow for maneuverability of the overall freight transportation system.

Embodiments provide for methods, apparatuses, and systems for receiving
15 feedback regarding the degree of tilt of a dolly and/or trailers, and/or attached containers. In some embodiments, a sensor feedback system may be integrated into a freight transportation system as described herein. In an embodiment, the sensor feedback system may include a tilt sensor system mounted on a frame of the dolly or trailers attached to the dolly, and a user feedback system located within a cabin of a
20 tractor attached to the dolly. Tilt sensor system may measure the tilt of the dolly and/or trailers, as well as attached containers, to obtain related tilt information, and continuously send the tilt information to the user feedback system. User feedback system may then vibrate / alert a driver of the tractor if the tilt information is above a predetermined / dangerous level. User feedback system may be a haptic feedback

system, audio feedback system, visual feedback system, and/or audiovisual feedback system.

Referring to Figure 1, a freight transportation system (10) is shown. Tractor (101) is coupled to a first trailer (105). First container (115) is secured to top of first trailer (105). Two axle dolly (125) is coupled to the first trailer (105) and a second trailer (110). Second container (120) is secured to top of second trailer (110). Two axle dolly (125) distributes the weight of the first and second trailer (105, 110) across its tandem axles.

Tractor (101) may refer to a heavy-duty commercial vehicle. In embodiments, tractor (101) may have two load axles (e.g., as seen in Figure 1) or three load axles. In various instances, the load axles of tractor (101) may include single, tandem, or tridem tires. Examples of commercially available tractors (101) include Volvo™ VNL and VNM series trucks. However, other types of tractors (101) commonly used to transport freight may also be used.

First and second trailers (105, 110) may include one, two, or more front axles and one, two, or more rear axles. First and second trailers (105, 110) may be 102 inches wide. In various instances, the axles of first and second trailers (105, 110) may include single, tandem, or tridem tires. First and second trailers (105, 110) as used herein may refer to a box, van, or flatdeck. An example of a commercially available trailer (105, 110) that may be used is a Transcraft™ flat deck trailer. However, other types of trailers (105, 110) commonly used to transport freight and/or house a container may also be used.

First and second trailers (105, 110) may support the first and second containers (115, 120). First and second containers (115, 120) may be "Intermodal" and designed to be moved from one mode of transport to another (e.g. from ship, to

rail, to truck). First and second containers (115, 120) may be slid into a box trailer or placed onto a flatdeck trailer. First and second containers (115, 120) may be shipping containers.

As shown in Figures 2, 3, and 4, the dolly (125) includes a cart assembly (201) and first and second axles (205, 210). Second axle (210) may be parallel to the first axle (205). Dolly (125) may be configured to distribute weight from the first and second trailers (105, 110) across the first and second axles (205, 210) to permit legal hauling of large loads. The length of the first and second axles (205, 210) may be greater than the length of the axles of the tractor (101) and/or first and second trailers (105, 110). In this embodiment, the extended axle length may provide for enhanced stability and distribution of load weight. First and second axles (205, 210) may have a length of approximately 70 to approximately 90 inches. In embodiments, the length of the first and second axles (205, 210) is approximately 77.5 inches. In these embodiments, the extended first and second axles (205, 210) may be coupled with high quality tire configurations to further distribute axle weight. First and second axles (205, 210) may include, at the termini, tandem (301, 305, 310, 315) or tridem tire configurations. Particularly, first axle (205) may include a first tandem tire set (301, 310), and second axle (210) may include a second tandem tire set (305, 315) parallel to the first tandem tire set (301, 310). See Figure 3. In an exemplary embodiment, tires may be 295/75R22.5 DCOIN TR100 steel belted radial tires. Tires may be configured to maximize contact surface area with the road. Position of the tires may be optimized along the elongated axle length for stability and maneuverability. At the same time, the overall dolly (125) size may be optimized for maneuverability of the overall system (10). In an exemplary embodiment, tires of first and second trailers (105, 110) are the same size as tires of dolly (125). However, tires

of first and second trailers (105, 110) and/or dolly (125) may have varying sizes and configurations. In other embodiments, length of the first and second axles (205, 210) may be lesser than or equal to the length of the axles of the tractor (101) and/or first and second trailers (105, 110). Length and width of the dolly (125) may be varied as
5 needed to support particular applications, including measurement of tilt of dolly (125) described herein.

Dolly cart assembly (201) of the two axle dolly (125) may be manufactured from a variety of materials such as, for e.g., steel and aluminum. In various examples, the cart assembly (201) may include two side rails (320, 325) placed on a plurality of
10 orthogonal cross support members (379, 380), the support members (379, 380) attached to the two tandem first and second axles (205, 210), respectively. See, e.g., Figures 2 and 3. Two pedestal josts (215, 340) may be secured to the top of the two side rails (320, 325). Josts (215, 340) may be configured to attach to a fifth wheel jost (330) in a rotatable manner.

15 Two corresponding hinges (345, 350) and two cable attachment points (355, 360) may be secured to a first end of the two side rails (320, 325) of cart assembly (201). See Figure 3. Hinges (345, 350) may be secured to a V-shaped assembly (365) with an eye and shank installation (335). However, hinges (345, 350) may be secured to V-shaped assembly via any other attachment mechanisms. V-shaped assembly
20 (365) may have any other shape for attachment to hinges (345, 350). First suspension faculty (370) for the first axel (205) may be secured to the first end of the two side rails (320, 325) of cart assembly (201). See Figure 3. Second suspension faculty (401) for the second axel (210) may be secured to the middle of the two side rails (320, 325) of cart assembly (201). See Figure 4. First and second suspension faculties (370, 401)
25 may include respective air suspension hangers with independent arms (405, 410, 435,

440) for each of the tandem tire pairs (301, 305, 310, 315), respectively. See Figures 3 and 4.

The components of the dolly cart (125) may be configured in a variety of shapes and sizes depending on the application. In some embodiments, the height of the two side rails (320, 325) from the center of the first and second axles (205, 210) may range from about 10 to about 20 inches. In particular embodiments, the height of the two side rails (320, 325) from the center of the first and second axles (205, 210) is about 14 inches. The distance from the center of the fifth wheel jost (330) to the eye and shank installation (335) may vary depending on the separation distance desired between the first trailer. In some embodiments, this distance is about 98 inches. Depending on factors such as road width, the width of the cart assembly (201) may also be varied. In some instances, the cart assembly (201) may have a width of about 40 to about 70 inches. In a specific embodiment, the cart assembly (201) has a width of about 44 inches.

Tractor (101), first and second trailers (105, 110), first and second containers (115, 120), and/or two axle dolly (125) of the present disclosure may be used in a variety of methods. In embodiments of the present disclosure, tractor (101), first and second trailers (105, 110), first and second containers (115, 120), and/or two axle dolly (125) may be selected based on the volume/weight requirements of a given load.

A trailer length exception, if necessary, may be filed with the appropriate state authority and approved. Tractor (101), first and second trailers (105, 110), and/or first and second containers (115, 120) may be loaded and balanced across the dolly (125) such that the weight at the dolly tandem axles (205, 210) may not exceed the legal tandem axle weight limit. Optionally, the load may be additionally balanced as to not exceed any legal axle weight limits.

Referring to Figure 5, a schematic of a sensor feedback system (20) is shown. Sensor feedback system (20) includes a tilt sensor system (200) and a user feedback system (300). As shown, user feedback system (300) is a haptic feedback system. However, user feedback system (300) may also be an audio feedback system, visual feedback system, and/or audiovisual feedback system. Sensor feedback system (20) alerts / provides feedback to a driver of a tractor (101) of dangerous situations such as when containers (for e.g., first and second containers (115, 120)) attached to tractor (101) may be tilting excessively during transportation of freight, thereby allowing the driver to take appropriate corrective action to reduce the excessive tilt.

In embodiments, tilt sensor system (200) may include a housing having at least one tilt sensor and a first communication module / system, both connected to a first microcontroller. Housing of tilt sensor system (200) may be dust-proof, water-proof, and/or shock-proof. The connections between each component in the tilt sensor system (200) may be wireless or wired connections. At least one tilt sensor may be a known inclinometer and/or accelerometer system that measures and obtains tilt information of the dolly (125), first and/or second trailers (105, 110) attached to dolly (125), and/or first and/or second containers (115, 120) attached to first and/or second trailers (105, 110). In an exemplary embodiment, the at least one tilt sensor is the ADIS16210 *iSensor*[®] by Analog Devices[®]. The ADIS16210 *iSensor*[®] is a digital inclinometer system that provides precise measurements for both pitch and roll angles over a full orientation range of $\pm 180^\circ$. At least one tilt sensor may combine a MEMS (Micro-Electro-Mechanical System) tri-axial acceleration sensor with signal processing, addressable user registers for data collection/programming, and a Serial Peripheral Interphase (SPI)-compatible serial interface. At least one tilt sensor may include unit specific calibration for optimal accuracy performance. It may also offer

digital temperature sensor and power supply measurements together with configuration controls for in-system calibration, sample rate, filtering, alarms, I/O configuration, and power management. The MEMS sensor elements may be bound to an aluminum core for tight platform coupling and mechanical stability. An internal
5 clock may drive the data sampling system, which may eliminate the need for an external clock source. The SPI and data buffer structure may provide convenient access to accurate sensor data and configuration controls. In exemplary embodiments, the at least one tilt sensor may be available in a 15 mm × 24 mm × 15 mm module that provides mounting tabs with M2-sized mounting holes and a flexible, edge
10 terminated connector interface. At least one tilt sensor may also have an extended operating temperature range of about −40°C to about +125°C. In other embodiments, the tilt sensor(s) may be an inclinometer and/or accelerometer that may interface with microcontrollers and/or wireless or wired communication systems to provide feedback to a user. Other types of sensors may also be used, such as for e.g., lasers.

15 Sensor feedback system (20) may be integrated into the freight transportation system (10). See Figures 1 to 4. Particularly, tilt sensor system (200) may be mounted on frames of the dolly (125) and/or trailers (105, 110) attached to dolly (125), and feedback system (300) may be located within a cabin of a tractor (101) where a driver is seated. See, e.g., Figure 1. However, sensor feedback system (20) may be used in
20 other transportation or other systems where feedback to an operator / user is desired.

In some embodiments, tilt sensor system (200) is mounted directly on a frame of the dolly (125). See, e.g., Figures 1 to 4. In an embodiment, tilt sensor system (200) is mounted on side rail (325) in the middle of cart assembly (201), to obtain measurements of tilt of dolly (125) using the at least one tilt sensor. See Figures 2 to
25 4. In this embodiment, tilt information of first and second containers (115, 120) may

be calculated based on tilt information of dolly (125). Dolly (125) described herein may be further modified to obtain tilt measurements. For example, first tandem tire set (301, 310) and second tandem tire set (305, 315) of dolly (125) may be moved further inward or outward such that dolly (125) tilts along with first and/or second
5 trailers (105, 110). In other embodiments, tires (301, 310, 305, 315) of dolly (125) may be modified and/or located in other configurations so as to obtain accurate tilt measurements of dolly (125).

In other embodiments, tilt sensor system (200) may be secured to first and/or second trailers (105, 110), which may be connected to first and/or second containers
10 (115, 120), respectively. In this embodiment, tilt sensor system (200) may include at least a first tilt sensor and a second tilt sensor secured underneath the frames of the first and second trailers (105, 110), respectively. Particularly, tilt sensor system (200) may be secured underneath the frames and to the front of rear tires of first and/or second trailers (105, 110) to obtain tilt measurements of first and/or second containers
15 (115, 120) attached to first and/or second trailers (105, 110). In this embodiment, tilt information of first and/or second containers (115, 120) may be measured based on tilt information of trailers (105, 110) via direct attachment / mounting of containers (115, 120) to trailers (105, 110).

In other embodiments, tilt sensor system (200) may be located in other
20 locations on dolly (125) and/or trailers (105, 110) to account for forward, backward, and/or side-to-side tilt of dolly (125) and/or trailers (105, 110), and thereby obtain accurate tilt measurements. Tilt sensor system (200) may be mounted on the dolly (125) and/or trailers (105, 110) via fasteners, nuts, bolts, adhesives, and/or other attachment mechanisms.

Tilt sensor system (200) may continuously measure / monitor the tilt, i.e. angle of inclination, of the dolly (125), first and/or second trailers (105, 110) attached to dolly (125), and/or first and/or second containers (115, 120) attached to first and/or second trailers (105, 110), via the at least one tilt sensor to obtain tilt information regarding the same. Tilt sensor system (200) may then continuously send the tilt information to the user feedback system (300) via the first communication module. User feedback system (300) may then continuously receive tilt information from tilt sensor system (200), and may vibrate and alert a driver if the tilt information is above a predetermined /dangerous level.

First communication module / system in tilt sensor system (200) may facilitate connection between the tilt sensor system (200) and user feedback system (300). First communication module of tilt sensor system (200) may be a first wireless or wired communication module. First wireless communication module may be a first ZigBee[®] wireless module. In an exemplary embodiment, first ZigBee[®] wireless module may be the XBee Pro[®] Module.

Tilt sensor system (200) and user feedback system (300) may be in constant communication with each other via a ZigBee[®] wireless connection, shown as arrow A in Figure 5. Alternatively, tilt sensor system (200) and feedback system (300) may communicate with each other via any other known wired or wireless connections.

ZigBee[®] (also known as the ZigBee[®] protocol) was developed as an open global standard to address the unique needs of low-cost, low-power, wireless sensor networks. The protocol uses the 802.15.4 physical radio specification as a baseline and adds additional routing and networking functionality. It operates in unlicensed bands worldwide at the following frequencies: 2.400-2.484GHz, 902-928MHz and 868.0-868.6MHz. ZigBee[®] technology may be used with embodiments of dolly (125)

and/or trailers (105, 110) described herein to carry data associated with tilt of dolly (125) and/or trailers (105, 110) through hostile RF environments that routinely exist in transportation applications. Zigbee[®] may be implemented with embodiments of the present disclosure to address the needs of communication of data with simple structure like, for example, data from the at least one tilt sensor described herein. Alternatively, other types of communication modules / systems may be used to communicate with tilt sensors and/or microcontrollers to provide feedback.

First microcontroller in tilt sensor system (200) may provide power to and activate the at least one tilt sensor, obtain tilt information from the at least one tilt sensor, and determine whether the tilt information, i.e. degree of tilt, is above a predetermined / hazardous level. First microcontroller may be in constant communication with a second microcontroller in the user feedback system (300) via the first communication module and a second communication module in the user feedback system (300). In an exemplary embodiment, first microcontroller is the ATmega 48/88/168/328 AVR[®] 8-Bit Microcontroller by Atmel[®]. Alternatively, other types of microcontrollers may be used to communicate with tilt sensors and/or communication modules to provide feedback.

Tilt sensor system (200) may be powered via connections to a power source located on the dolly (125) and/or directly on the tractor (101). Power source may be a battery, direct wired connection into the dolly (125) itself, or any other form of power. In some embodiments, tilt sensor system (200) mounted on the dolly (125) may be powered by a battery. Alternatively, tilt sensor system (200) mounted on the dolly (125) may be powered via connections to a stinger port located on a tractor (101). In other embodiments, at least the first and second tilt sensors of tilt sensor system (200) secured to frames of first and second trailers (105, 110), respectively, may be powered

via connections to a stinger port located on a tractor (101). Stinger port may be connected to an external battery source, which may be recharged by the alternator of the tractor (101). In some embodiments, stinger port may be connected to an ion power pack. In this embodiment, wired connections may be connected from the stinger port on the tractor (101) to a custom designed port installed on each of the frames of the first and second trailers (105, 110). Wired connections connected to the stinger port may run along the length of the frame of the first trailer (105) and attach to a first custom port on the first trailer (105), run along the length of the dolly (125), and finally, run along the length of the second trailer (110) and attach to a second custom port on the second trailer (110).

User feedback system (300) may be located within a cabin / cab of a tractor (101). As shown in Figure 5, user feedback system (300) is a haptic feedback system (300). Haptic / tactile feedback involves the use of advanced vibration patterns and waveforms to convey information to a user. Haptic feedback may utilize a vibrating component such as a vibration motor or a linear resonant actuator which may be driven by an electronic circuit. In some instances, a microcontroller may be used that decides when to activate vibration of a haptic sensor and in what particular pattern, and a dedicated haptic driver chip may be used to control the actuator.

In exemplary embodiments, haptic feedback system (300) is secured to a driver seat (102) of tractor (101). Particularly, haptic feedback system (300), including haptic sensors (306), may be sewed into a seat cover fitted on the driver seat (102) of tractor (101). See, e.g., Figure 5. In exemplary embodiments, haptic feedback system (300) may include multiple haptic sensors (306) and a second communication module / system, both connected to a second microcontroller. Second communication system may facilitate connection between the tilt sensor system (200) and haptic

feedback system (300). Second microcontroller may receive tilt information from the first microcontroller, and when necessary, activate haptic sensors (306).

Second communication module of user feedback system (300) may be a second wireless or wired communication module. Second wireless communication
5 module may be a second ZigBee[®] wireless module. In an exemplary embodiment, second ZigBee[®] wireless module may be the XBee Pro[®] Module. Second microcontroller may be the ATmega 48/88/168/328 Microcontroller by Atmel[®]. In other embodiments, haptic feedback system (300) may utilize a single chip that includes both a wireless (e.g., ZigBee[®]) module and a microcontroller, such as for
10 example, the ATmega2564RFR2 chip by Atmel[®]. However, any other ZigBee[®] or other type of communication system/module and/or microcontroller may be used. Haptic sensor (306) may be any known industrial grade haptic sensor. In an exemplary embodiment, haptic sensor (306) may be the Uni Vibe[™] 34mm Vibration Motor by Precision Microdrives[™].

15 Each sensor (306) may be sewn inside the seat cover fitted on the driver seat (102), while the other components of haptic feedback system (300), including second communication system and second microcontroller, may be located outside the seat cover. In other embodiments, all components of haptic feedback system (300) may be sewn within the seat cover. The connections may be wired connections (307) that
20 connect to each haptic sensor (306). In other embodiments, the connections may be wireless connections. In the embodiment shown in Figure 5, the second microcontroller and/or haptic feedback system (300) may be powered via wired connections (307) to, for e.g., a cigarette lighter adapter (308), which may then be inserted into a cigarette lighter connection (309) located adjacent to the driver seat

(102) of tractor (101), as shown by arrow B. However, the second microcontroller / feedback system (300) may be powered via other known mechanisms.

In exemplary embodiments, user feedback system (300) may receive continual updates from the tilt sensor system (200) regarding degree of tilt of dolly (125), first and/or second trailers (105, 110) attached to dolly (125), and/or first and/or second containers (115, 120) attached to first and/or second trailers (105, 110), respectively, via ZigBee wireless connection, A, using the first ZigBee wireless module. Haptic feedback system (300) may receive either “OK” or “hazard” signals from the tilt sensor system (200). If the haptic feedback system (300) receives an “OK” signal, it will not engage the haptic sensors (306). However, if the haptic feedback system (300) receives a “hazard” signal (for e.g., when a driver is making a turn but is doing so at an excessive speed or the turn itself is hazardously sharp), indicating excessive / dangerous tilt of the dolly (125), first and second trailers (105, 110), and/or first and second containers (115, 120), it may then energize / engage / turn on the haptic sensors (306). In an exemplary embodiment, the second microcontroller may apply a 5V signal on a voltage line connected to the haptic sensors (306), and thereby activate / energize the sensors (306). Upon engagement / being turned on, the sensors (306) may then alert a driver sitting on the driver seat (102) of tractor (101), via vibration of the seat cover fitted on the driver seat (102), that the dolly (125), first and second trailers (105, 110), and/or first and second containers (115, 120) may be experiencing excessive tilt. When the driver experiences this vibration, he/she may then know to take appropriate correction action (such as for e.g., slowing down or widening the turn of the tractor (101)).

User feedback system (300) may be a visual feedback system, audio feedback system, and/or audiovisual feedback system. The visual system and/or audio system

may be separate systems or combined audiovisual systems. In embodiments, visual, audio, and/or audiovisual feedback systems may directly receive tilt information from tilt sensor system (200) via connections to microcontrollers and communication modules, and provide appropriate feedback to a driver. Visual, audio, and/or audiovisual feedback systems may be interconnected with a separate haptic feedback system (300). For example, haptic feedback system (300) may include wired connections (307) from the second microcontroller to the visual, audio, and/or audiovisual systems. The visual, audio, and/or audiovisual feedback systems may be located anywhere within the cabin of the tractor (101).

Visual system may be mounted on a dashboard in the cabin via either permanent or non-permanent attachment mechanisms, for e.g., an adhesive. In exemplary embodiments, the visual system may be a row of green, yellow, and red LEDs (light-emitting diodes). In this embodiment, the visual system may show a green light in normal driving conditions, a yellow light when containers (115, 120) may be tilting towards a dangerous level, and a red light when first and second containers (115, 120) are tilting excessively.

Audio feedback system may be located within the housing of the haptic feedback system (300) or may be a separate system. Audio feedback system may be an audio alarm that may send a low pitched audio signal / alert in normal driving conditions and a high pitched audio signal / alert in situations where first and second containers (115, 120) are tilting excessively. The audio alarms may be horns / sirens that output an audio signal when a voltage is applied to their input power terminals. In other embodiments, audio feedback system may be piezoelectric audible sound transducers - also called tone generators or buzzers - that may deliver a high sound

output from a small (milliwatt) energy input. In an exemplary embodiment, the audio feedback system may be piezo buzzers offered by APC International, Ltd.

Figure 6 is a flowchart showing a sensor feedback system (20) using tilt sensor system (200) and user feedback system (300) described herein. Sensor feedback system (20) described in Figure 6 may be implemented using the apparatuses, systems and methods described herein, including various embodiments thereof. Sensor feedback system (20) may include the following steps. A user may first plug user feedback system (300) into a cigarette lighter adapter (308), which may be inserted into a cigarette lighter connection (309). User feedback system (300) may then send a startup command to at least one tilt sensor in tilt sensor system (200) described herein. Tilt sensor system (200) may be mounted on dolly (125) and/or first and second trailers (105, 110) described herein. If tilt sensor system (200) does not notify user feedback system (300) of receipt of startup command, user feedback system (300) may alert the user that tilt sensor system (200) is not functioning properly. In exemplary embodiments, user feedback system (300) may be a visual LED system that may show a red light to user indicating non-functioning of the tilt sensor system (200). Once user sees the red light, user may notify an appropriate party that the system (20) is not functioning properly, and repairs may be made to system (20). In other embodiments, user may receive this notification via audio, audiovisual, and/or haptic feedback.

If tilt sensor system (200) receives the startup command from user feedback system (300), the at least one tilt sensor of tilt sensor system (200) may wake up from a sleep mode and test functionality of the system (200). Particularly, tilt sensor system (200) may test functionality of the inclinometer in the system (200). If the tilt sensor system (200) is not functioning properly, the tilt sensor system (200) may send a fault

status to feedback system (300), which user feedback system (300) may alert the user as described herein, and appropriate repairs may be made to tilt sensor system (200).

If the tilt sensor system (200) is functioning properly, the tilt sensor system (200) may send an “OK” status to user feedback system (300). If user feedback system (300)

5 does not receive the fault status and/or “OK” status from tilt sensor system (200), it may then notify the appropriate party for repairs. In embodiments with a haptic feedback system (300), once it receives an “OK” status, user feedback system (300) may then briefly initiate haptic feedback sensors (306). Again, if the user feedback system (300) is not functioning properly, user feedback system (300) may alert the
10 user as described herein, and appropriate repairs may be made to user feedback system (300).

Once tilt sensor system (200) sends the “OK” status to user feedback system (300), tilt sensor system (200) may then measure tilt information of dolly (125), first and second trailers (105, 110), and/or first and second containers (115, 120) attached
15 to first and second trailers (105, 110) using the at least one tilt sensor. Tilt sensor system (200) may then send this tilt information to user feedback system (300) via a first communication system. User feedback system (300) may receive this tilt information via a second communication system. If the dolly (125), first and second trailers (105, 110), and/or first and second containers (115, 120) are tilting excessively
20 beyond a predetermined level, tilt sensor system (200) may send a warning signal to user feedback system (300). User feedback system (300) may then alert user of this dangerous tilt level via haptic, audio, and/or visual feedback. Once the user takes appropriate corrective action to fix the dangerous level of tilt, tilt sensor system (200) may send an “OK” signal to user feedback system (300), which may then deactivate
25 haptic, audio, and/or visual feedback. If the communication between the user

feedback system (300) and the tilt sensor system (200) is interrupted at any time, the tilt sensor system (200) may send a fault status to user feedback system (300), and user feedback system (300) may alert the user as described herein, and appropriate repairs may be made to fix this interrupted communication.

5 Embodiments provide a method for preparing a load for transport. First container (115) as described herein may be coupled onto a first trailer (105) as described herein, which first trailer (105) may then be connected to a tractor (101). First end of a two axle dolly (125) as described herein may be attached to the first trailer (105). Second trailer (110) as described herein may then be attached to a
10 second end of the two axle dolly (125). Second container (120) as described herein may be coupled onto the second trailer (110). Methods may include connecting the sensor feedback system (20) described herein, including tilt sensor system (200) and user feedback system (300), to at least one of the dolly (125) and/or trailers (105, 110), as well as tractor (101), to receive feedback regarding tilt of the dolly (125), first
15 and/or second trailers (105, 110), and/or first and/or second containers (115, 120). User feedback system (300) may be haptic, visual, audio, and/or audiovisual feedback systems.

 While the embodiments are described with reference to various implementations and exploitations, it will be understood that these embodiments are
20 illustrative and that the scope of the inventions is not limited to them. Many variations, modifications, additions, and improvements are possible. Further still, any steps described herein may be carried out in any desired order, and any desired steps may be added or deleted.

WHAT IS CLAIMED IS:

1. A transportation system, comprising:
 - a tractor;
 - a first trailer attached to the tractor;
 - a dolly having a first axle system and a second axle system, the dolly attached to the first trailer at one end and a second trailer at an opposing end such that a load carried by at least one of the first and second trailer is distributed across at least one of the first and second axle systems; and
 - a sensor feedback system,wherein the sensor feedback system includes a tilt sensor system mounted on at least one of the dolly, the first trailer, and the second trailer, and a user feedback system located on the tractor, wherein the tilt sensor system measures tilt of at least one of the dolly, first and second trailers, and first and second containers attached to the first and second trailers, respectively, to obtain tilt information, and sends the tilt information to the user feedback system via a first communication system,
 - wherein the user feedback system receives the tilt information from the first communication system via a second communication system, and alerts a driver of the tractor if the tilt information is above a predetermined level.
2. The system of claim 1, wherein the first and second communication systems communicate via at least one of a wired and wireless connection.
3. The system of claim 2, wherein the first and second communication systems communicate wirelessly via first and second ZigBee wireless modules, respectively.
4. The system of claim 3, wherein the first and second ZigBee wireless modules are XBee Pro Modules.

5. The system of claim 1, wherein the tilt sensor system includes a housing having at least one tilt sensor and the first communication system, both connected to a first microcontroller.
6. The system of claim 5, wherein the at least one tilt sensor is the ADIS16210 iSensor.
7. The system of claim 1, wherein the user feedback system is at least one of a haptic feedback system, audio feedback system, visual feedback system, and audiovisual feedback system.
8. The system of claim 7, wherein the haptic feedback system includes haptic sensors and the second communication system, both connected to a second microcontroller.
9. The system of claim 8, wherein the haptic sensors are sewed into a seat cover fitted on a driver seat in the cabin of the tractor.
10. The system of claim 9, wherein the haptic sensors vibrate and alert the driver sitting on the driver seat if the tilt is above the predetermined level.
11. The system of claim 10, wherein the tilt sensor system is powered via connections to at least one of a battery and a stinger port located on the tractor.
12. A transportation feedback system, comprising:
a dolly system comprising a cart having a first connection member configured to secure a first trailer to the dolly and a second connection member configured to secure a second trailer to the dolly, a first axle connected to the cart and having a first tandem tire set, a second axle connected to the cart and parallel to the first axle and having a second tandem tire set, wherein the cart has at least two side rails and orthogonal support members configured to distribute a load placed on at least one of the first and second trailers onto the first and second axles; and

a tilt sensor system mounted on the dolly system,

wherein the tilt sensor system measures tilt of at least one of the dolly system, first and second trailers attached to the dolly system, and first and second containers attached to the first and second trailers, respectively, to obtain tilt information, and continuously sends the tilt information via a communication system to a user feedback system located external to the dolly system,

wherein the user feedback system receives the tilt information from the communication system, and alerts a user if the tilt information is above a predetermined level.

13. The system of claim 12, wherein the first and second axles have a length of approximately 70 to approximately 90 inches.

14. The system of claim 13, wherein the first and second axles have a length of approximately 77.5 inches.

15. The system of claim 12, wherein the communication system communicates via at least one of a wired and wireless connection.

16. The system of claim 15, wherein the communication system communicates wirelessly via first and second ZigBee wireless modules.

17. The system of claim 16, wherein the first and second ZigBee wireless modules are XBee Pro Modules.

18. The system of claim 12, wherein the tilt sensor system includes a housing having at least one tilt sensor and a first communication system, both connected to a first microcontroller.

19. The system of claim 18, wherein the at least one tilt sensor is the ADIS16210 iSensor.

20. The system of claim 12, wherein the user feedback system is at least one of a haptic feedback system, audio feedback system, visual feedback system, and audiovisual feedback system.

21. The system of claim 20, wherein the haptic feedback system includes haptic sensors and a second communication system, both connected to a second microcontroller.

22. The system of claim 21, wherein the haptic sensors are sewed into a seat cover fitted on a driver seat in the cabin of the tractor.

23. The system of claim 22, wherein the haptic sensors vibrate and alert the user sitting on the driver seat if the tilt is above the predetermined level.

24. The system of claim 20, wherein the audio feedback system, visual feedback system, and audiovisual feedback system provide audio, visual, and audiovisual alerts, respectively, to the user if the tilt is above the predetermined level.

25. A method for receiving feedback during transportation, comprising:

mounting a tilt sensor system to at least one of a dolly system and first and second trailers attached to opposite ends of the dolly system;

mounting a user feedback system within a cabin of a tractor attached to at least one of the first and second trailers;

measuring tilt of at least one of the dolly system, first and second trailers, and first and second containers attached to the first and second trailers, respectively, via the tilt sensor system to obtain tilt information;

continuously sending the tilt information to the user feedback system via a first communication system;

receiving the tilt information from the first communication system via a second communication system; and

alerting a driver of the tractor if the tilt information is above a predetermined level.

26. The method of claim 25, wherein the dolly system includes a cart having a first connection member configured to secure the first trailer to the dolly system and a second connection member configured to secure the second trailer to the dolly system, a first axle connected to the cart and having a first tandem tire set, a second axle connected to the cart and parallel to the first axle and having a second tandem tire set, wherein the cart has at least two side rails and orthogonal support members configured to uniformly distribute a load placed on at least one of the first and second trailers onto the first and second axles.

27. The method of claim 25, wherein the first and second communication systems communicate wirelessly via first and second ZigBee wireless modules, respectively.

28. The method of claim 25, wherein the tilt sensor system includes a housing having at least one tilt sensor and the first communication system, both connected to a first microcontroller.

29. The method of claim 28, wherein the user feedback system is at least one of a haptic feedback system, audio feedback system, visual feedback system, and audiovisual feedback system.

30. The method of claim 29, wherein the haptic feedback system includes haptic sensors and the second communication system, both connected to a second microcontroller.

31. The method of claim 30, wherein the haptic sensors vibrate and alert the driver if the tilt is above the predetermined level.

32. The method of claim 29, wherein the audio feedback system, visual feedback system, and audiovisual feedback system provide audio, visual, and audiovisual alerts, respectively, to the user if the tilt is above the predetermined level.

33. A transportation feedback system, comprising:
a driver unit;

- a first trailer attached to the driver unit;
a dolly attached to the first trailer;
a second trailer attached to the dolly opposite the first trailer; and
a tilt sensor feedback system attached to at least one of the dolly, first trailer, and second trailer,
wherein the tilt sensor feedback system detects tilt of at least one of the dolly, first trailer, and second trailer, and alerts the driver unit if the tilt of at least one of the dolly, first trailer, and second trailer exceeds a predetermined level.
34. A tilt detection system, comprising:
a feedback system;
a dolly; and
a sensor system,
wherein the sensor system detects tilt of a load being transported by the dolly, and alerts the feedback system if the tilt of the load exceeds a predetermined level.
35. The system of claim 34, wherein the sensor system is attached to the dolly.
36. The system of claim 34, wherein the sensor system is configured to be attached to at least one of the dolly, a trailer connected to the dolly, and a container or load secured to the trailer.
37. The system of claim 34, wherein the feedback system is at least one of a haptic feedback system, audio feedback system, visual feedback system, and audiovisual feedback system.
38. The system of claim 34, wherein the feedback system includes lights that can be secured inside or outside of a driver cabin of a tractor attached to the dolly.
39. The system of claim 34, wherein the dolly includes a cart having a first connection member configured to secure the first trailer to the dolly and a second connection member configured to secure the second trailer to the dolly, a first axle connected to the cart and having a first tandem tire set, a second axle connected to the cart and parallel to the first axle and having a second tandem tire set, wherein the cart has at least two side rails and orthogonal support members configured to uniformly distribute a load placed on at least one of the first and second trailers onto the first and second axles.

40. The system of claim 37, wherein the haptic feedback system includes haptic sensors that vibrate and alert a driver if the tilt exceeds the predetermined level.
41. The system of claim 37, wherein the audio feedback system, visual feedback system, and audiovisual feedback system provide audio, visual, and audiovisual alerts, respectively, to the user if the tilt is above the predetermined level.
42. The system of claim 34, wherein the sensor system alerts the feedback system via a communication system.
43. The system of claim 42, wherein the communication system communicates via at least one of a wired and wireless connection.

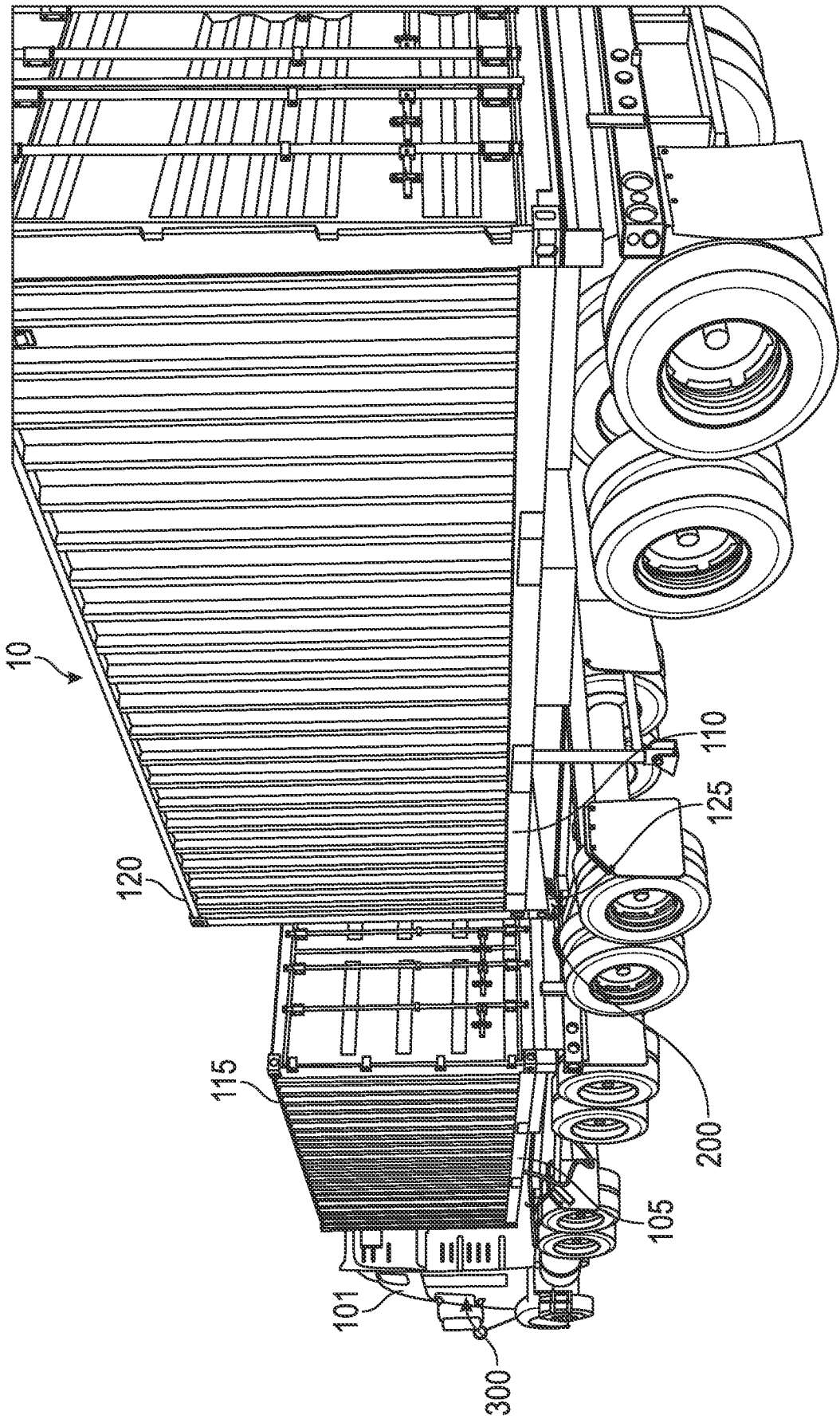


FIG. 1

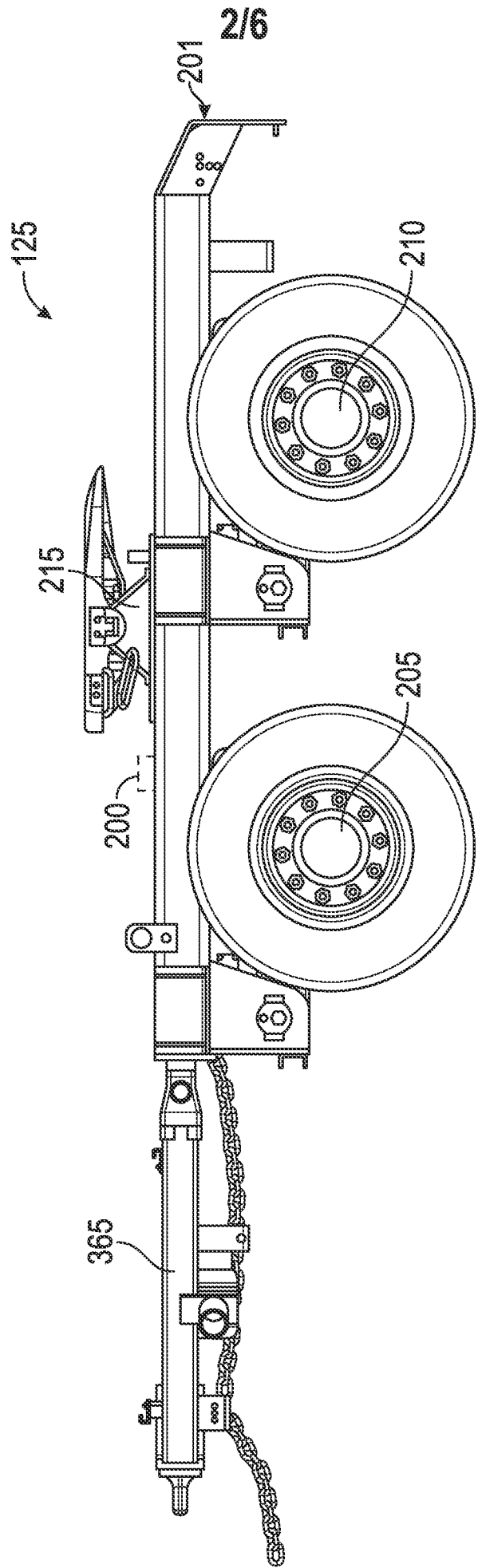


FIG. 2

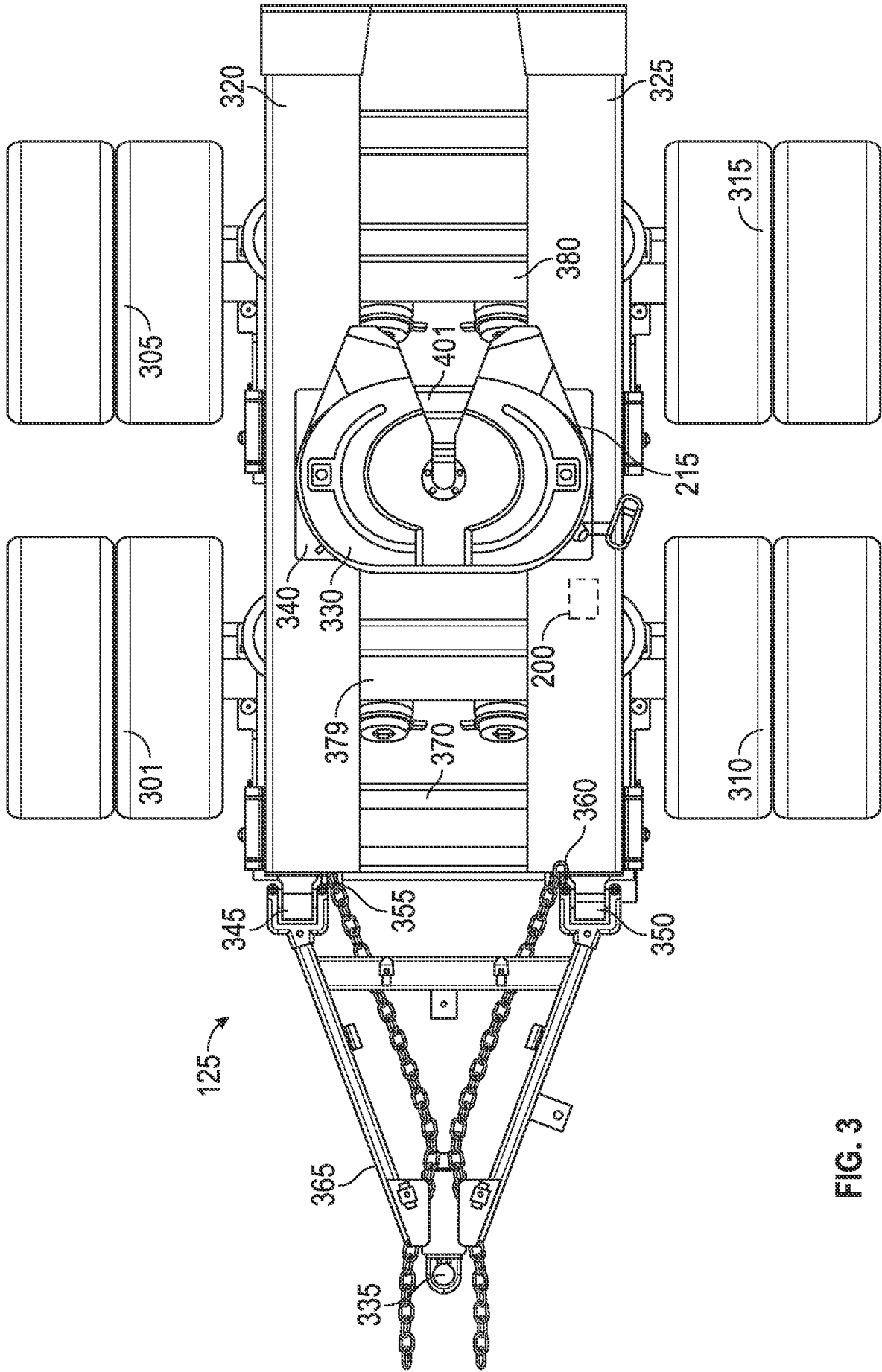


FIG. 3

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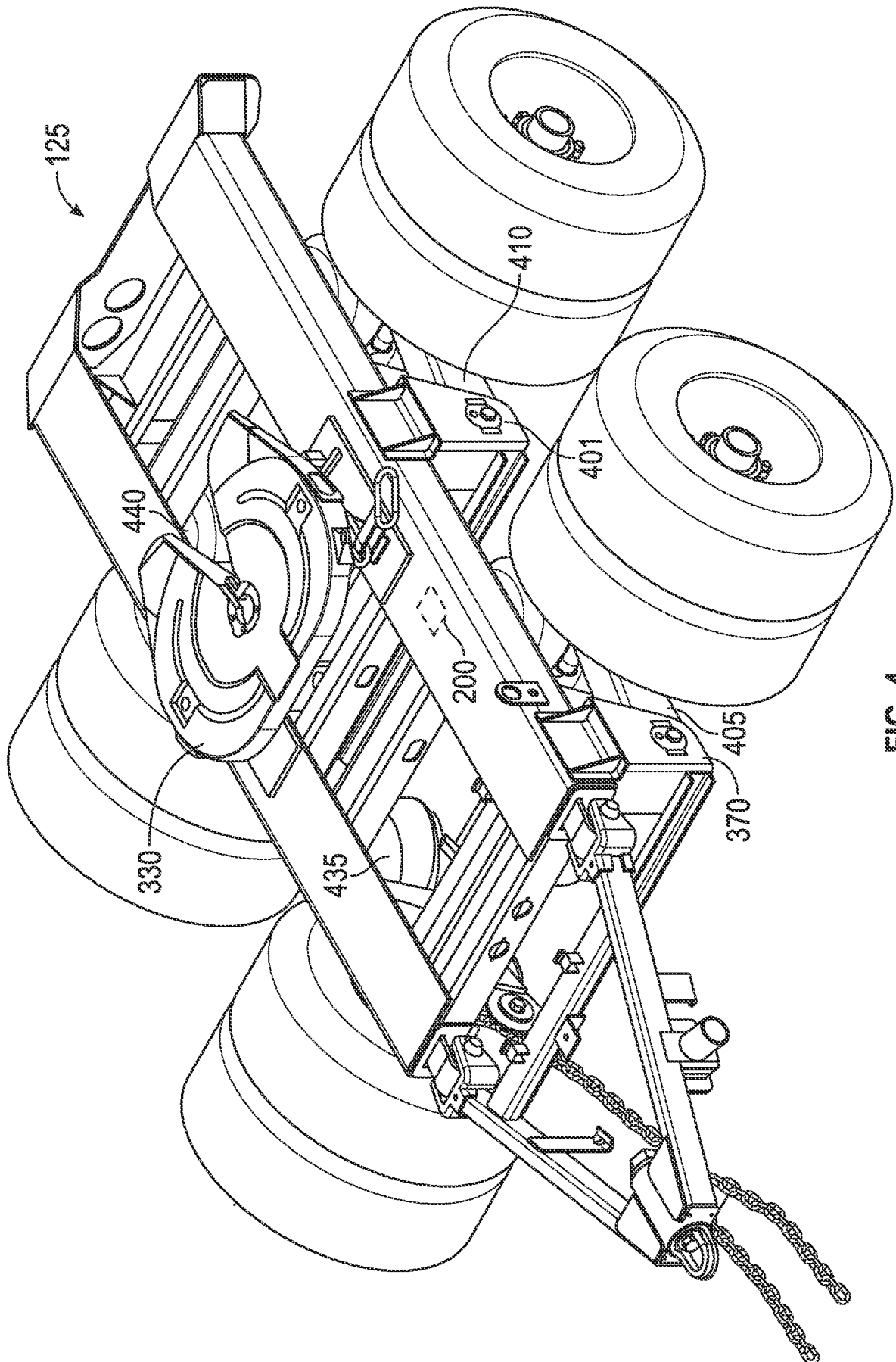


FIG. 4

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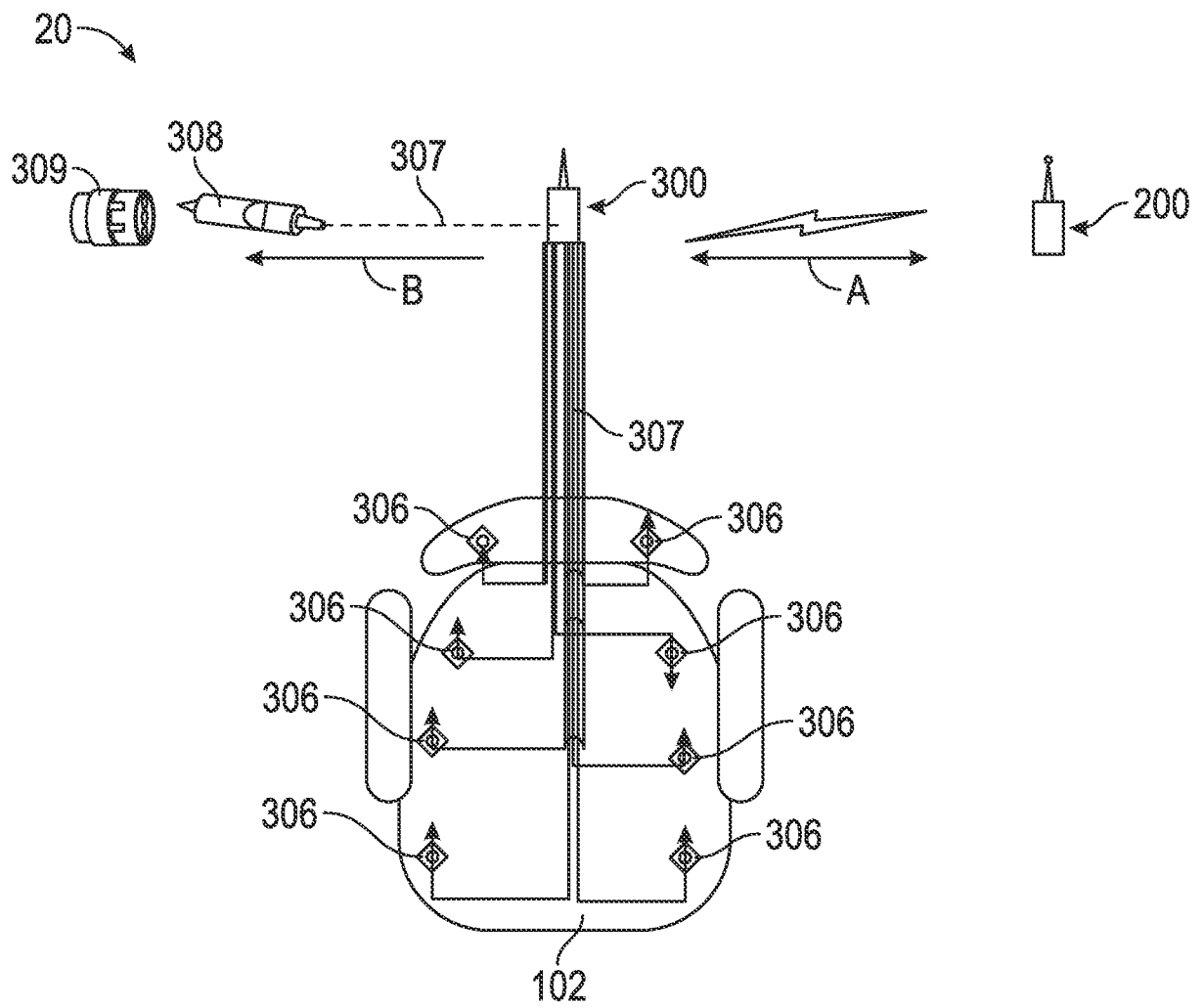
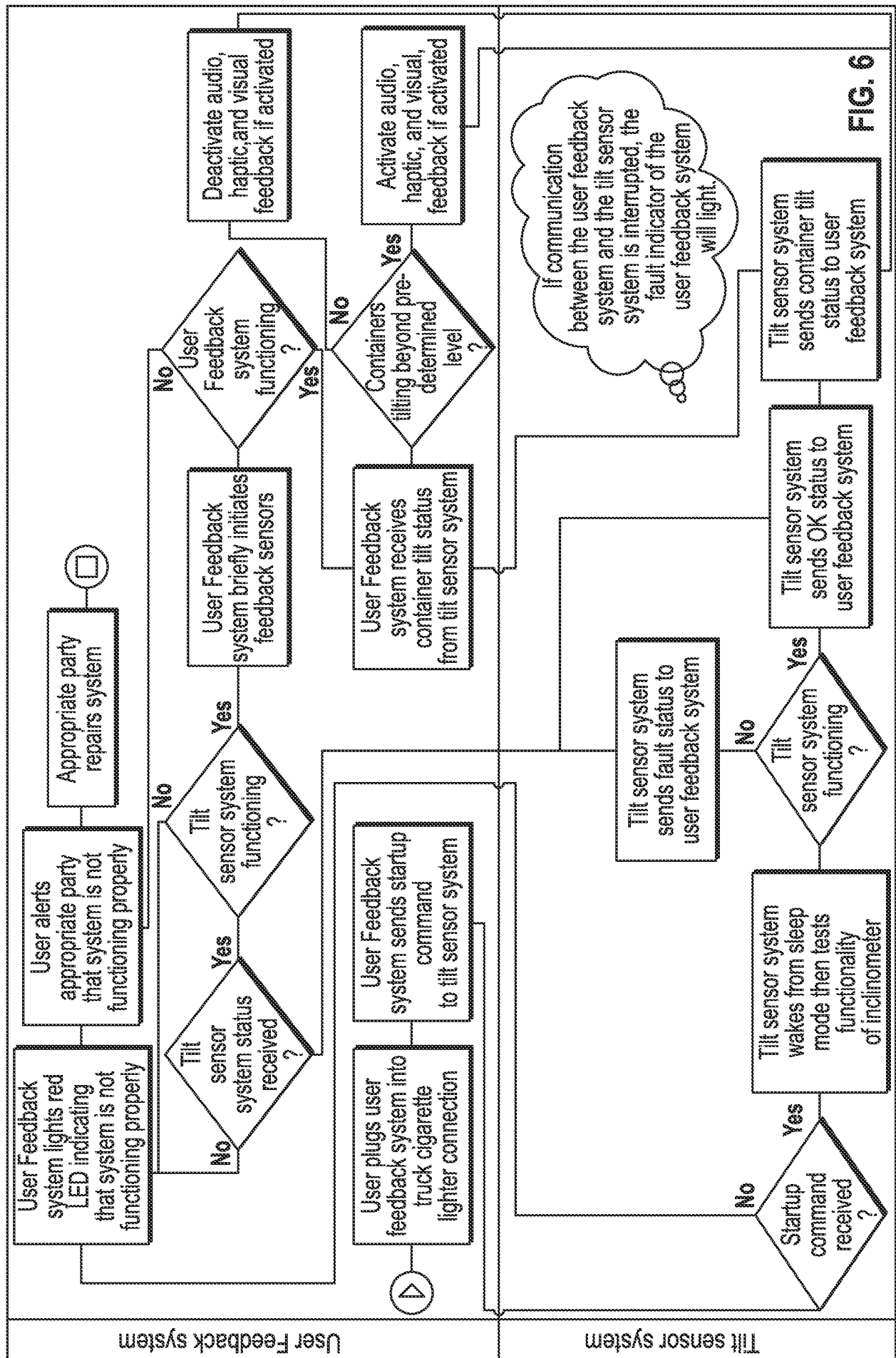


FIG. 5



INTERNATIONAL SEARCH REPORT

International application No
PCT/US2015/058381

A. CLASSIFICATION OF SUBJECT MATTER
INV. B62D53/00 B62D53/08
ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
B62D

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-Internal, PAJ

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Further documents are listed in the continuation of Box C.



See patent family annex.

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Date of the actual completion of the international search

1 February 2016

Date of mailing of the international search report

08/02/2016

Name and mailing address of the ISA/

European Patent Office, P.B. 5818 Patentlaan 2
NL - 2280 HV Rijswijk
Tel. (+31-70) 340-2040,
Fax: (+31-70) 340-3016

Authorized officer

Szaip, András

INTERNATIONAL SEARCH REPORT

International application No
PCT/US2015/058381

C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT		
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International application No

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