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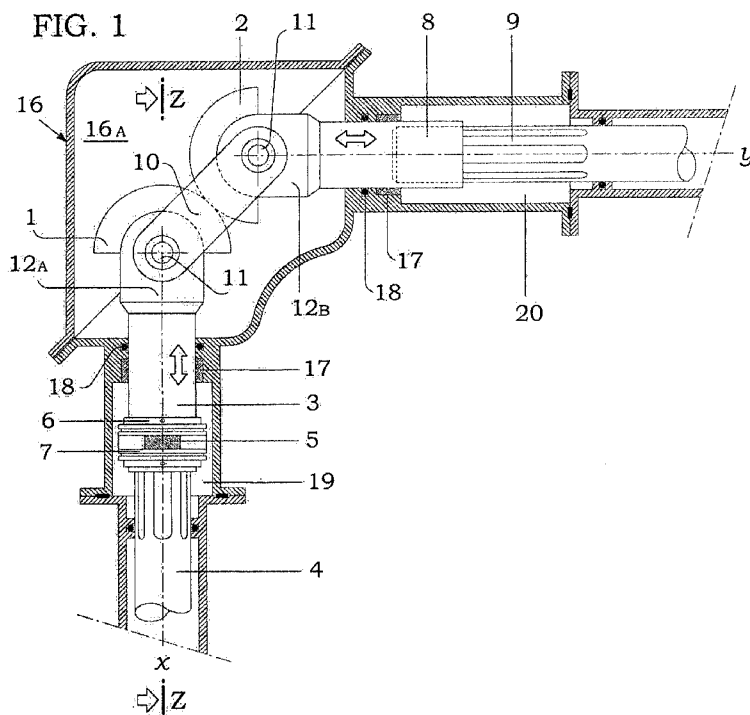
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**Declarations under Rule 4.17:**

— as to applicant's entitlement to apply for and be granted a patent (Rule 4.17(ii))

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(54) Title: STEPLESS GEAR RATIO VARIATOR



(57) Abstract: A stepless gear ratio variator for wind generators wherein the transmission of motion between a driving member (1) and a driven member (2) takes place through friction of the respective convex contact surfaces translating simultaneously along respective incident axes of rotation (X and Y); these surfaces being constrained, in use, to remain constantly in contact by means of a pair of support brackets (12) mutually connected in an articulated manner by means of a pair of plates (10), pivoted to the same support brackets (12) according to axes passing through the centre of the contact surfaces of the driven and driving members (2 and 1).



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- *as to the applicant's entitlement to claim the priority of the earlier application (Rule 4.17(iii))*
- Published:**
- *without international search report and to be republished upon receipt of that report (Rule 48.2(g))*

## STEPLESS GEAR RATIO VARIATOR

DESCRIPTION

The present invention relates to a new system to obtain, in wind generators and in many other applications, variation of the gear ratio in a stepless manner through the relative displacement of half-balls in contact while the torques involved are transmitted through friction.

Some examples of stepless gear ratio variators in which motion is transmitted by friction already exist in the market. Operation of said variators is obtained in two ways: either by increasing the number of members involved in the transfer of torque or by increasing the single surface in contact with respect to that guaranteed by punctiform contact.

However, said solutions are particularly complicated and bulky from a constructional point of view and also entail considerable production costs.

In a further solution of embodiment, transmission of motion between the driving member and the driven member takes place through the friction of a pair of elements with contact surfaces both convex or also only one convex and the other concave, preferably coated with suitable composite materials (ceramic or of other type) and translating simultaneously along the respective incident axes of rotation, in order to remain constantly in contact. Examples of this technical solution are described in the international patent application WO2008/102167 by the English company TOROTRAK DEV LTD or in the European patent application n. 1026424 by the Japanese company Isuzu Motors LTD. However, it should be noted that also the technical solutions described in these patent documents are somewhat complicated from the point of view of production, as in order to maintain the elements permanently in contact, it is necessary to act on both by means of a hydraulic pump

which requires a specific circuit.

Therefore, the object of the present invention is to offer a stepless gear ratio variator for the transmission of motion through friction which is easy to assemble and presents limited production and maintenance costs.

Said variator is described below with reference to two drawings representing, purely by way of non-limiting example:

- FIG. 1, which shows the sectional view of a stepless variator produced according to the invention and in which the driving element and the driven element have equal and hemispherical coupling surfaces;
- FIG. 2, which shows a cutaway view referred to FIG. 1;
- FIG. 3, which shows an enlargement of the section ZZ referred to FIG. 1.

From the accompanying drawings it can be seen that motion is transmitted from the drive shaft 4 to the driven shaft 9 through a pair of members 1 and 2 which, preferably constructed in steel, have curved coupling surfaces in order to obtain a variation of the gear ratio which is as smooth and large as possible.

In particular, the driving element 1, provided with rotational-translational motion along the axis X, is hemispherical and is coupled with the driven element 2, also hemispherical and with the same radius as that of the element 1, and provided with rotational-translational motion along the axis Y.

Said element 1 is integral with the hollow shaft 3 with respect to which it can be subject to brief regulating axial sliding movements.

Said shaft 3, through grooved coupling receives rotational motion from the drive shaft 4 on which it can slide longitudinally moved by an electric or hydraulic

actuator to which it is connected by the bracket 5. This bracket is constrained to the hollow shaft 3 by two thrust elements 6 and by two needle cages 7, located at the two sides of the bracket to isolate it from the rotation  
5 imparted on the hollow shaft 3 by the drive shaft 4.

The driven element 2 is in turn integral with the hollow shaft 8 with respect to which it can be subject to brief regulating axial sliding movements.

Said hollow shaft 8, through grooved coupling  
10 transmits the rotational motion from the driven shaft 9, on which it can slide longitudinally when driven by the driving element 1 to which it is permanently constrained.

In fact, the two hemispherical transmission members 1 and 2 are maintained in direct contact with each other by a  
15 pair of plates 10, preferably pivoted in the point indicated with the reference number 11, on the outside of the same number of support brackets 12A and 12B and according to axes passing through the centre of the hemispherical portions 1 and 2.

20 The assembly of plates 10 and brackets 12, supported by the two shafts 3 and 8, ensures articulated connection of the same shafts, for the purpose of maintaining the two members 1 and 2 in constant contact, necessary for variation of the gear ratio through friction. Said  
25 transmission through friction is also ensured by an appropriate preload imparted, during mounting, to the same members 1 and 2 with a predetermined contact tension and necessary for correct operation of the assembly. Said preload is obtained by means of threaded ring nuts 13  
30 screwed, with specific torque wrenches, onto the threaded portions specifically provided in each of the shafts 3 and 8 close to the elements 1 and 2.

Each of said shafts 3 and 8 is also provided with a ball cage 14 or other equivalent anti-friction element

which, mounted inside the corresponding bracket 12A and 12B, isolates it from the rotation of the corresponding shaft, among other things provided, in correspondence of its bracket 12, with an appropriate bushing 15.

5 All this is mounted inside the chamber 16A of a box-shaped casing 16, in a traction fluid bath which, besides possessing the characteristics of normal lubricating fluids (lubricating capacity, anti-wear and heat dissipation), also has the special capacity of increasing its coefficient  
10 of friction if subjected to high pressures, thereby improving the mechanical efficiency of the transmission.

Also in the chambers 19 and 20 the shafts 3 and 8 are maintained in an oil bath and, notwithstanding the combined movements of rotation and linear translation of the  
15 aforesaid shafts, each supported by a bushing 17 with internal helical groove, appropriate gaskets 18 of known type prevent the passage of oil from the aforesaid chambers 19 and 20 to the chamber 16A where the transmission members 1 and 2 operate through friction immersed in the traction  
20 fluid described above.

Finally, without prejudice to the general characteristics of the variator illustrated and described, it could also be susceptible to modifications and variants, all however falling within the scope of the present patent.

CLAIMS

1) A stepless gear ratio variator for wind generators wherein the transmission of motion between a driving member (1) and a driven member (2) takes place through friction of the respective convex contact surfaces translating simultaneously along respective incident axes of rotation (X and Y); said surfaces being constrained, in use, to remain constantly in contact; characterised in that said contact surfaces are constrained to remain permanently in contact by means of a pair of support brackets (12), and in that said support brackets (12) are mutually connected in an articulated manner by means of a pair of plates (10), pivoted to said same support brackets (12) according to axes passing through the centre of said contact surfaces of said driven and driving members (2 and 1).

2) A stepless variator as claimed in claim 1, characterised in that each of the two said members (1 and 2), responsible for the transmission of motion through friction, is integral with the end of a respective hollow shaft (3 and 8) with respect to which it can be subjected to brief regulating axial sliding movements.

3) A stepless variator as claimed in claim 2, characterised in that said regulating axial sliding movements, necessary to ensure an appropriate preload of the two members (1 and 2) during mounting, take place by means of threaded ring nuts (13) screwed close to the elements (1 and 2) to obtain the necessary contact tension for correct operation of the assembly.

4) A stepless variator as claimed in claim 1, characterised in that the contact surfaces of said driven and driving members (2 and 1) are both hemispherical and of equal dimensions.

5) A stepless variator as claimed in the preceding claims, characterised in that transmission of motion through

friction between said members (1 and 2) takes place said members being immersed in a traction fluid which presents the capacity of increasing its coefficient of friction if subjected to high pressures, thereby improving the mechanical efficiency of the transmission.

6) A stepless variator as claimed in claim 2, characterised in that the two said hollow shafts (3 and 8) are coupled respectively to the drive shaft (4) and to the driven shaft (9), with respect to which said hollow shafts (3 and 8) translate axially to vary the gear ratio.

7) A stepless variator as claimed in claim 6, characterised in that each of said hollow shafts (3 and 8) is provided with a respective anti-friction element (14) which is mounted inside the corresponding said support bracket (12) to isolate it from the rotation of the corresponding shaft.

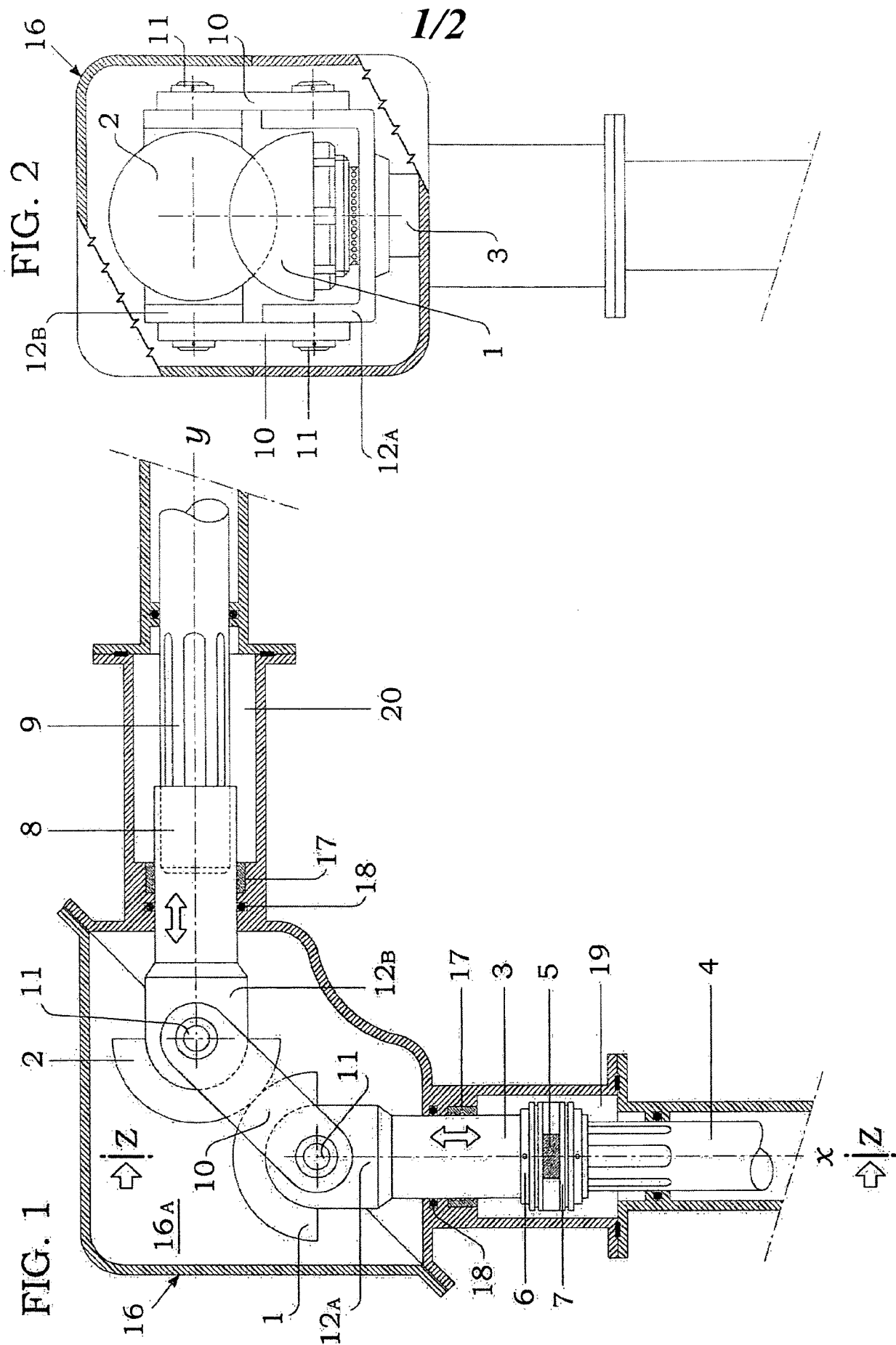
8) A stepless variator as claimed in one or more of the preceding claims, characterised in that the axial translations of the two members (1 and 2) are obtained by means of an electric or hydraulic actuator appropriately connected, by means of a bracket (5), to said hollow shaft (3) carrying said driving member (1) and coupled to the drive shaft (4).

9) A stepless variator as claimed in claim 8, characterised in that the bracket (5) is isolated from the rotations of said hollow shaft (3) by means of known means, such as needle cages (7) and/or thrust elements (6).

10) A stepless variator as claimed in claim 6, characterised in that said hollow shafts (3 and 8) are maintained in an oil bath in the chambers (19 and 20) and each supported by a bushing (17) with internal helical groove while appropriate gaskets (18) of known type prevent the passage of oil from the aforesaid chambers (19 and 20) to the chamber (16A) where said transmission members (1 and



2) operate through friction immersed in specific traction fluid.



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FIG. 3

