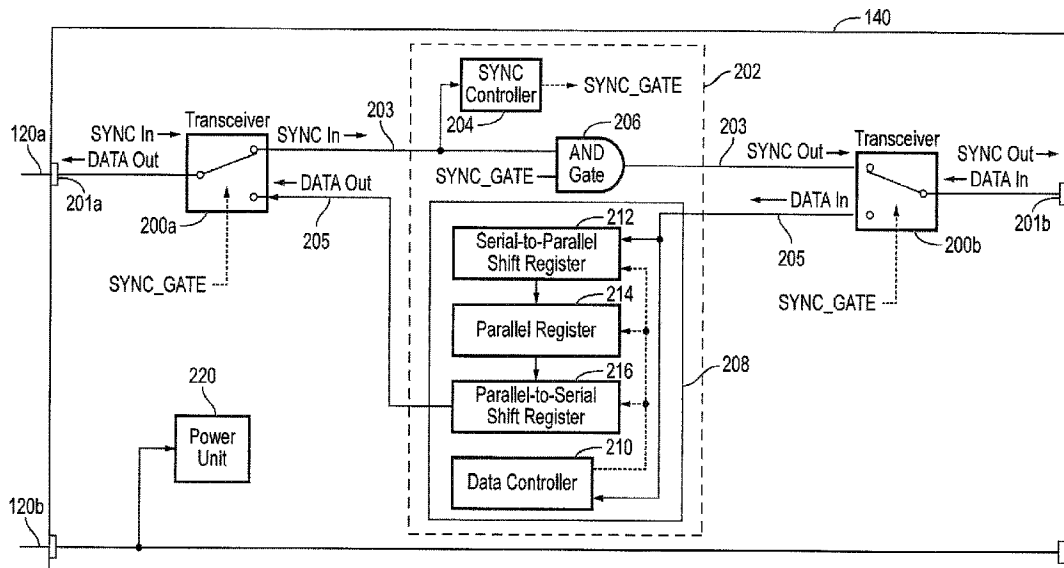




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(54) **Titre : SYSTEME TELEMETRIQUE BASSE PUISSANCE SYNCHRONES EXTENSIBLE POUR CAPTEURS DISTRIBUES**
(54) **Title: EXTENDABLE SYNCHRONOUS LOW POWER TELEMETRY SYSTEM FOR DISTRIBUTED SENSORS**



(57) **Abrégé/Abstract:**

A bidirectional repeater for repeating an electrical signal traversing a conductive line coupled between a gateway node and a sensor, the bidirectional repeater comprising a first input-output port coupled to the gateway node, a second input-output port coupled to the sensor, a first transceiver configured to receive a synchronization signal from the first input-output port and to transmit a re synchronized data signal to the first input-output port, a second transceiver configured to transmit the synchronization signal to the second input-output port and to receive a data signal from the second input-output port, and a repeater circuit coupled to the first and second transceivers and configured to pass through the synchronization signal, and to resynchronize the data signal to generate the resynchronized data signal.

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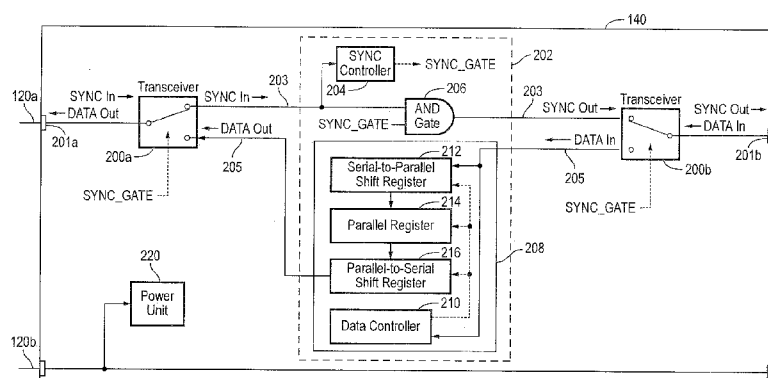


FIG. 2A

(57) Abstract: A bidirectional repeater for repeating an electrical signal traversing a conductive line coupled between a gateway node and a sensor, the bidirectional repeater comprising a first input-output port coupled to the gateway node, a second input-output port coupled to the sensor, a first transceiver configured to receive a synchronization signal from the first input-output port and to transmit a re synchronized data signal to the first input-output port, a second transceiver configured to transmit the synchronization signal to the second input-output port and to receive a data signal from the second input-output port, and a repeater circuit coupled to the first and second transceivers and configured to pass through the synchronization signal, and to resynchronize the data signal to generate the resynchronized data signal.

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EXTENDABLE SYNCHRONOUS LOW POWER TELEMTRY SYSTEM FOR DISTRIBUTED SENSORS

FIELD

- 5 This disclosure relates to telemetry systems, and more particularly, to an extendable synchronous telemetry system having distributed sensors.

BACKGROUND

- Distributed sensor networks use a set of spatially scattered sensors designed to obtain
10 measurements from the environment. A central node connected to the sensors collects the data, which is used to extract relevant information about the environment. Conventional network types, such as the RS-485 network, allow the implementation of linear bus topologies (e.g., in-line serial drop communication links). However, such networks have bandwidth/data rate limitations that constrain the quantity of and the
15 physical spacing between sensors employed. Data rates (baud rates) are typically governed by cable length and physical signaling protocols. Electrical cables have an inherent low-pass filtration characteristic (due to intrinsic inductance, resistance, and capacitance), which leads to lower data rates for longer spans of the electrical cable. Data protocols attempt to optimize signal integrity and may limit the bit error rate for a
20 given design parameter. Extending length and number of distributed sensors may require additional busses or cables running at slower baud rates. Manufacturability may become increasingly more expensive as additional cables are added to accommodate sensor bandwidth, which can lead to solutions that may not be realistic in terms of cost.
- 25 Some semiconductor manufacturers have developed RS-485 transceiver devices with built-in cable equalization (e.g., high-frequency gain circuits) that extends the range of an RS-485 network. While these devices may succeed in lengthening the range of such networks, they still have a limit to their maximum range. Further, these devices do not attempt to address the concept of synchronization.

Other network types such as Ethernet and USB have existing methods for extending their range; however, these methods often impose high power consumption, cost, and even size making them unsuitable for many applications, such as long-distance sub-sea surveillance.

- 5 What is desired is an extendable synchronous low power telemetry system for distributed sensor networks that is low cost, reliable, and readily scalable.

SUMMARY

Aspects of embodiments of the teachings herein are directed toward a method for connecting a large number of distributed synchronized sensors and a telemetry
10 system implementing the same. Aspects of embodiments of the teachings herein permit the product of data transmission length multiplied by bandwidth to be extended to significantly higher values than previously attainable while maintaining precise timing synchronization between sensors. Thus, embodiments of the present teachings herein allow both the physical spacing and quantity of sensors to
15 be extended beyond the typical limits of standard distributed sensor networks (DSNs) and to be arbitrarily scalable.

Aspects of embodiments of the teachings herein are directed toward a low power, low-cost telemetry system architecture that couples multiple distributed sensors to a common node using off-the-shelf transceiver devices. The system comprises a
20 gateway node, a multi-wire cable, one or more repeaters, and a common digital interface on each sensor. Sensors are placed along the cable and receive the synchronization signal which allows them to sample their measurements simultaneously. The sensors then transmit their data samples to the gateway node using time division multiplexing (TDM). The repeaters capture and retransmit the
25 uplink data samples to the gateway node.

According to an embodiment, there is provided a bidirectional repeater for repeating an electrical signal traversing a conductive line coupled between a gateway node and a sensor, the bidirectional repeater comprising: a first input-output port coupled to the gateway node; a second input-output port coupled to the
30 sensor; a first transceiver configured to receive from the gateway node, via the first input-output port, a synchronization signal of a plurality of synchronization signals

- and to transmit a resynchronized data signal via the first input-output port to the gateway node; a second transceiver configured to transmit the synchronization signal to the sensor via the second input-output port and to receive a data signal via the second input-output port, from the sensor; and a repeater circuit coupled to
- 5 the first and second transceivers and configured to pass through the synchronization signal without re-clocking the synchronization signal, and to resynchronize the data signal to generate the resynchronized data signal. An entirety of the resynchronized data signal occupies a time period between consecutive ones of the plurality of synchronization signals .
- 10 In an embodiment, the repeater circuit comprises a timing control circuit that is configured to lock into a phase of the synchronization signal.
- In an embodiment, the repeater circuit is configured to resynchronize the data signal by re-clocking and regenerating the data signal.
- In an embodiment, re-clocking the data signal comprises shifting the data signal in
- 15 time to start at a beginning of a next time slot.
- In an embodiment, the data signal comprises a serial, bidirectional, time division multiplexed data and is divided into a number of frames, each frame having a plurality of time slots.
- In an embodiment, a time slot of the plurality of time slots comprises a data bit.
- 20 In an embodiment, regenerating the data signal comprises recreating the data bit to correct for noise and signal distortion.
- In an embodiment, the synchronization signal comprises a single pulse.
- In an embodiment, the repeater circuit is configured to pass through the synchronization signal without regenerating the synchronization signal.
- 25 In an embodiment, the repeater circuit is further configured to lock into a phase of the synchronization signal.
- In an embodiment, the repeater is coupled to a plurality of sensors comprising the sensor, wherein the first input-output port is coupled to the gateway node through one or more sensors of the plurality of sensors.

According to another embodiment, there is provided a synchronous telemetry system comprising: a cable comprising one or more conductive elements for conducting a synchronization signal of a plurality of synchronization signals; a gateway node configured to supply the synchronization signal, and to receive a resynchronized data signal; a repeater coupled to the cable, and configured to receive and pass through the synchronization signal from the gateway node, without re-clocking the synchronization signal; a sensor coupled to the cable and configured to receive the synchronization signal, to measure a parameter in response to receiving the synchronization signal and to generate a data signal corresponding to the measured parameter and wherein the repeater is coupled between the gateway node and the sensor, and is further configured to receive and re-clock and reconstruct the data signal from the sensor to generate the resynchronized data signal, and wherein an entirety of the resynchronized data signal occupies a time period between consecutive ones of the plurality of synchronization signals.

In an embodiment, the one or more conductive elements comprise a pair of wires, and wherein the synchronization signal, the data signal, and the resynchronized data signal are differential signals transmitted over the pair of wires.

In an embodiment, the gateway node is further configured to supply electrical power to the sensor and repeater through the cable.

In an embodiment, the each of the sensor and repeater comprise a local power source.

In an embodiment, the synchronous telemetry system comprises a plurality of segments coupled in series, each segment comprising a plurality of sensors comprising the sensor and one or more repeaters comprising the repeater.

In an embodiment, the plurality of sensors concurrently measure parameters in response to receiving a synchronization signal.

In an embodiment, the sensor comprises at least one of an acoustic sensor, optical sensor, temperature sensor, and vibration sensor.

According to another embodiment, there is provided a method of repeating an electrical signal traversing a conductive line coupled between a gateway node and a sensor, the method comprising, receiving from the gateway node, by a repeater, a synchronization signal, from a plurality of synchronization signals, at a first input-output port of the repeater, the gateway being in communication with the first input-output port of the repeater; passing through, by the repeater, the synchronization signal, without re-clocking the synchronization signal, at a second input-output port of the repeater, the second input-output port being in communication with the sensor; receiving, by the repeater, a data signal from the sensor, via the second input-output port of the repeater; resynchronizing, by the repeater, the data signal to generate a resynchronized data signal; and transmitting, by the repeater, the resynchronized data signal via the first input-output port of the repeater, to the gateway node, wherein an entirety of the resynchronized data signal occupies a time period between consecutive ones of the plurality of synchronization signals.

15 In an embodiment, the method further comprises locking, by the repeater, into a phase of the synchronization signal.

BRIEF DESCRIPTION OF THE DRAWINGS

These and other features and advantages will be better understood by reference to the following detailed description when considered in conjunction with the following drawings, in which like elements are referenced with like numerals. These drawings should not be construed as limiting but are intended to be illustrative only.

FIG. 1A is a block diagram of a synchronous telemetry system utilizing a repeater **140**, according to an illustrative embodiment.

FIG. 1B is a block diagram of a synchronous telemetry system utilizing a repeater, according to an illustrative embodiment.

FIG. 2A is a schematic diagram of a repeater, according to an illustrative embodiment.

FIG 2B is a timing diagram showing the effect of the operation of the repeater on a signal carried by the cable, according to an embodiment.

FIG. 3A illustrates the timing diagram of a frame of a downlink synchronization signal

5 transmitted by a gateway node, according to an embodiment. FIG. 3B illustrates a timing diagram of a frame of both the downlink synchronization signal and the uplink data signal received by the gateway node, according to an embodiment.

FIG. 3C illustrates a timing diagram of a data sample of the uplink data signal received by the gateway node, according to an embodiment.

10 FIG. 4A is a waveform diagram illustrating waveforms of signals received and transmitted by the gateway node, repeater, sensors in a multi-sensor synchronous telemetry system, according to an embodiment.

FIG. 4B illustrates a timing diagram of data blocks transmitted from sensors to the gateway node in a multi-sensor synchronous telemetry system, according to an
15 embodiment.

FIG. 5 illustrates a graphical user interface of the processing unit including control and monitoring panels, according to an illustrative embodiment.

FIG. 6 is a block diagram of a process of repeating signals received by the repeater, according to an illustrative embodiment.

20 **DETAILED DESCRIPTION**

The detailed description set forth below in connection with the appended drawings is intended as a description of illustrative embodiments of a system and method for repeating signals in a distributed sensor network (DSN) and a synchronous telemetry system using the same in accordance with the teachings herein and is not intended to
25 represent the only forms in which the teachings herein may be implemented or utilized.

The description sets forth the features of the teachings herein in connection with the illustrated embodiments. It is to be understood, however, that the same or equivalent functions and structures may be accomplished by different embodiments that are also

intended to be encompassed within the spirit and scope of the teachings herein. As denoted elsewhere herein, like element numbers are intended to indicate like elements or features. The terms "substantially," "about," and similar terms are used as terms of approximation and not as terms of degree, and are intended to account for the inherent
5 deviations in measured or calculated values that would be recognized by those of ordinary skill in the art. Furthermore, when a component is referred to as being "coupled" to or "connected" to another component, it can be directly attached to the other component or intervening components may be present therebetween.

Some embodiments of the teachings herein are directed toward a low power, low-cost
10 synchronous telemetry system architecture that couples multiple distributed sensors to a gateway node (e.g., central node) using off-the-shelf transceiver devices (e.g., RS-485 transceiver devices such as the 8-pin RS-485 transceiver integrated chip). In an embodiment, the system comprises a gateway node, a cable (e.g., a multi-wire cable such as a 4-wire cable), one or more repeaters, and one or more sensors having a
15 common digital interface. Sensors may be placed along the cable and receive a synchronization signal, which allows them to sample their measurements simultaneously. The node, one or more repeaters, and the one or more sensors are coupled together (e.g., electrically connected in series) through the cable. In an embodiment, the downlink synchronization signal is passed down the cable through
20 one or more repeaters to the one or more sensors. The one or more sensors then may transmit their data samples to the gateway node using time division multiplexing (TDM). The one or more repeaters capture and retransmit the uplink data samples to the gateway node.

Embodiments of the teachings herein permit the cable length-bandwidth product to be
25 extended to significantly higher values than previously attainable while maintaining precise timing synchronization between sensors. For example, when the cable length reaches the physical limit for a given segment of an in-line serial drop communication link, integration of a repeater allows another segment to be added. Repeaters may be added to extend the distance to any arbitrary length.

FIG. 1A is a block diagram of a synchronous telemetry system **100** utilizing a repeater **140**, according to an illustrative embodiment of the teachings herein.

According to an embodiment of the teachings herein, the synchronous telemetry system **100** includes a gateway node (e.g., a central node or a sink node) **110** and a plurality of field nodes coupled together (e.g., electrically connected to one another) via a cable **120**. The field sensors include a plurality of sensors **130** and one or more repeaters (e.g., bidirectional repeaters) **140**, which may be distributed along the length of the cable **120** at regular or irregular intervals. The sensors **130** measure one or more parameters of interest in the environment and may be any combination of acoustic sensors, optical sensors, temperature sensors, vibration sensors, and/or the like. The sensor measurements are synchronized by way of a synchronization signal (e.g., downlink synchronization signal) provided by the gateway node **110** and carried by a telemetry bus of the cable **120** to each of the sensors **130**. Upon making a measurement, sensors **130** write their data samples to a data signal (e.g., an uplink data signal or multiplexed data signal) using time division multiplexing (TDM), which is transmitted back to the gateway node **110**. The synchronization signal and the data signal may be carried by the same telemetry bus of the cable **120**. The telemetry bus may be a single electrical conductor (e.g., single wire), or may be a differential balanced line having two electrical conductors (as in a twisted pair cable), which may offer improved signal to noise ratio as compared to a single conductor line.

In an embodiment, the one or more repeaters **140** receive both the synchronization signal and the data signal (e.g., the multiplexed data signal), and regenerate one or more of the signals to correct for distortions (e.g., attenuation as a result of traversing the cable **120**) and improve their signal to noise ratio (SNR) and retransmit the signals down or up the telemetry bus of the cable **120**. As such, for a given bit rate, a series of sensors (comprising a segment) may be extended as far as allowed by the signaling protocol, and a repeater **140** may be used to serially couple the series of sensors to a further segment. In this manner, an arbitrary number of segments may be serially coupled together to form a chain **112** of an arbitrary length.

In an embodiment, the gateway node **110** provides electrical power to the field nodes through a power bus line of the cable **120**. The power bus line may include two electrical conductors for carrying a power signal and a reference (e.g., ground) signal. In an embodiment, some or all of the field nodes may each have a local power source (such as a battery) to power the corresponding node. The local power sources may be operated in tandem with, or in lieu of, a central power source at the gateway node **110**. Thus, in some embodiments, the local power source line may obviate the need for a power bus line at the cable **120**.

FIG. **1B** is a block diagram of a synchronous telemetry system **100-1** utilizing a repeater **120**, according to an illustrative embodiment of the teachings herein.

The synchronous telemetry system **100-1** utilizes a multi-chain, parallel, in-line distributed sensor architecture (also referred to as a star topology). Each chain **112** may be substantially similar to that of the synchronous telemetry system **100** of FIG. **1A**.

According to an embodiment, one or more gateway nodes **110** and/or **110-1** may be coupled together to form a telemetry system having a mesh topology.

While many of the examples and embodiments described herein may refer to the telemetry system **100** and/or the gateway node **110**, the concepts described are not topology specific and may be equally applicable to, for example, the telemetry system **100-1** and/or the gateway node **110-1**.

FIG. **2A** is a schematic diagram of a repeater **140**, according to an illustrative embodiment of the teachings herein. FIG **2B** is a timing diagram showing the effect of the operation of the repeater **140** on the signal carried by the cable **120**, according to an embodiment of the teachings herein.

According to an embodiment, the repeater (e.g., the bidirectional repeater) **140** includes first and second transceivers (e.g., bidirectional transceivers) **200a** and **200b** for receiving and transmitting the downlink and uplink signals (e.g., the downlink synchronization signal and the uplink data signal), and a repeater circuit **202** for repeating the downlink and uplink signals received by the transceivers **200a/b**. In an

embodiment, the repeater circuit **202** includes a synchronization controller **204** for locking into the periodicity of the synchronization signal, a pass-through gate **206**, and a data regenerator **208**.

In an embodiment, each of the transceivers **200a/b** may function as a switch (e.g., a
5 three-way switch) configured to couple (e.g., electrically couple or electrically connect) the cable telemetry bus **120a** to either of the downlink line **203** or the uplink line **205**. The first transceiver **200a** may be coupled to the cable telemetry bus **120a** via the first port (e.g., the first input-output port) **201a**, and the second transceiver **200b** may be coupled to the cable telemetry bus **120a** via the second port (e.g., the second input-
10 output port) **201b**. In an example, the transceivers **200a/b** couple the cable telemetry bus **120a** to the downlink line **203** when a control signal (e.g., a timing signal SYNC_GATE) is at a logical high and couple the cable telemetry bus **120a** to the uplink line **205** when the control signal (e.g., the timing signal SYNC_GATE) is at a logical low.

15 The synchronization controller **204** is configured to generate the timing signal SYNC_GATE that matches the periodicity and phase of the synchronization signal SYNC_IN. In so doing, the repeater **140** may utilize a phase lock loop (PLL) having a phase detector and a voltage control oscillator (VCO). At initial power on, the timing signal SYNC_GATE may be at a logic high, thus coupling the cable telemetry bus **120a**
20 to the downlink line **203** and allowing synchronization signal SYNC_IN to reach the synchronization controller **204**. After one or more cycles of the synchronization signal SYNC_IN, the synchronization controller **204** may lock onto (i.e., "learn" the periodicity and phase of) the synchronization signal SYNC_IN and generate the timing signal SYNC_GATE (shown in FIG. 2B), which may be slightly wider than the synchronization
25 signal SYNC_IN. The wider width may be desired to accommodate for any nominal delays at the synchronization pass-through gate **206**. In an example, this additional width may be a few nanoseconds (ns) to a few microseconds (μ s) long. In an embodiment, the width of the timing signal SYNC_GATE extends beyond the

synchronization signal SYNC_IN to cover a superframe bit and a command bit (discussed in greater detail below with reference to FIGS. 3A and 3B).

In an embodiment, the repeater **140** passes the synchronization signal SYNC_IN through without any regeneration (e.g., without any distortion), in order to reduce (e.g.,
5 minimize) delays in the downlink transmission of synchronization signal and to improve synchronicity of the telemetry system **100**. In an embodiment, the repeater **140** also passes the superframe bit and the command bit through without any regeneration. As such, the pass-through gate **206** performs a logical AND operation on the signal on the downlink line **203** (which may include a synchronization pulse and sensor data) and the
10 timing signal SYNC_GATE, ensuring that only the synchronization pulse is passed-through and outputted from the repeater **140** at the second port **201b**.

The data regenerator **208** resynchronizes, i.e., re-clocks and regenerates, the data signal (which is in the form of one or more multiplexed data blocks) from the sensors **130** that follow the repeater **140** down the chain **112**. When the timing signal
15 SYNC_GATE is low, the transceivers **200a/b** couple the cable telemetry bus **120a** to the uplink line **205** allowing the data regenerator **208** to receive sensor data blocks DATA_IN from sensors **130**. The data regenerator **208** may include two or more shift registers and a data controller **210** for controlling the operation of the shift registers. In an embodiment, the data regenerator **208** includes a first shift register (e.g., a serial-to-
20 parallel or serial-in/parallel-out shift register) **212**, a second shift register (e.g., a parallel-to-parallel shift register) **214**, and a third shift register (e.g., a parallel-to-serial or parallel-in/serial-out shift register) **216**. The data controller **210** may provide a clock signal matching the bitrate of the sensor data blocks DATA_IN. The clock signal may have a frequency that is the multiple of the frequency detected for the synchronization
25 signal SYNC_IN (or timing signal SYNC_GATE). The first shift register **212** clocks in the data bits from the sensor data blocks DATA_IN one bit at a time, the second shift register **214** copies all of the bits of the sensor data blocks DATA_IN at the same time, and the third shift register **216** sends out the bits one bit at a time, which together form the repeated data block DATA_OUT. The data controller **210** controls the timing of the

operation of the shift registers such that the repeated data block DATA_OUT is aligned with the synchronization signal SYNC_IN (or the timing signal SYNC_GATE). (Alignment will be discussed in greater detail in the description of FIGS. 3A-4B). In shifting the data bits, the shift registers (e.g., shift registers **212**, **214**, and **216**) also
5 recreate the bits, thus correcting any distortions that the data bits may have experienced as a result of noise or cable transmission characteristics. As such, the repeated data block DATA_OUT may be a delayed and regenerated version of the sensor data block DATA_IN as shown in FIG. 2B.

The repeater **140** may further include a power unit **220** for providing power to the circuit
10 blocks within the repeater **140**. In some embodiments, the power unit **220** may draw power from a cable power bus **120b** of the cable **120** (as shown in FIG. 2A) and/or draw upon a local power source (such as a battery).

FIG. 3A illustrates the waveform diagram of a frame **310** of a downlink synchronization signal **300** transmitted by the gateway node **110**, according to an illustrative
15 embodiment of the teachings herein. FIG. 3B illustrates a waveform diagram of a frame **320** of the uplink data signal **302** received by the gateway node **110**, according to an illustrative embodiment of the teachings herein. FIG. 3C illustrates a waveform of a data sample of the uplink data signal **302** received by the gateway node **110**, according to an illustrative embodiment of the teachings herein.

20 According to an embodiment, the waveform of the signal (e.g., a downstream synchronization signal **300** or uplink data signal **302**) carried by the telemetry system **100** may be divided into a number of frames (e.g., time frames) **310**, which may be subdivided into a plurality of slots (e.g., time slots). In the examples illustrated in FIGS. 3A-3B, a frame **310** includes **45** equal slots (Slots **0-44**), a first of which contains a
25 synchronization pulse (e.g., SYNC Pulse at Slot **0**). A second slot (Slot **1**) may be partially occupied by a command bit and a superframe marker. The command bit may be used to transmit a downlink command (e.g., a command from the gateway node **110** to the sensors **130**), while the superframe marker may become active (e.g., go high) every preset number of frames (e.g., every **5000** frames) to mark the beginning of

a superframe (of, e.g., **5000** frames). The following slot (Slot **2**) may, in some examples, be reserved; however, it may also be used as a data slot. In an example, a frame **310** may represent **200** μ s of time, and a superframe of **5000** frames may have a duration of about **1** s.

- 5 A frame **310** may include a preset number of data slots (e.g., **37** data slots), each of which may contain the data imprint of either the sensor **130** or the repeater **140**. Each data slot may occupy a portion of the slot (e.g., $\frac{3}{4}$ of a slot) to leave sufficient spacing (e.g., $\frac{1}{4}$ of a slot) between data from adjacent slots. A first data slot (e.g., Slot **3**) may carry a repeater serial number, which uniquely identifies the repeater **140** among other
- 10 repeaters that may be present in the synchronous telemetry system. The serial number may allow each repeater to be uniquely programmed by the gateway node **110** at the time of system initialization. The information programmed into the repeater **140** may include a slot number. The repeater **140** may retransmit all slots up to the programmed number, then turn off its output so that upstream field sensors (e.g.,
- 15 sensors lying between the gateway node **110** and the repeater **140**) may take control of the cable telemetry bus **120a**. The repeater serial number may be retransmitted by the repeater **140**. In an embodiment in which more than one repeater are integrated onto the cable **120**, each repeater may shift the serial number of the preceding repeater by two slots, to leave two slots available to insert its own serial number. A
- 20 frame **310** may also include a preset number of unused slots (e.g., **5** unused slots) to accommodate for delays in the uplink data signal (or return signal) from the sensors **130**. Delays in the return signal will be further explained with reference to FIGS. **4A-4B**.

As shown in FIG. **3A**, when a gateway node **110** transmits a synchronization signal

25 **300**, a frame **310** of the signal may only include a synchronization pulse (e.g., Sync Pulse at Slot **0**) and a command bit and superframe marker. As the signal is returned, the data slots may be occupied by measurement data (e.g., sensor data or data blocks **320**) from the sensors **130**, as is shown in the ideal waveform FIG. **3B**.

As shown in FIG. 3C, a sensor data (or data block) **320** includes a start bit, a number of data bits (e.g., binary data bits **D0-D15**), and one or more code bits (e.g. even parity bits) for error detection. In an example, each of the start bit, data bits, and parity bits have a duration of **1/24** of the sensor data occupies **3/4** of a data slot. In an embodiment, the signal is in a high impedance state during the unoccupied portion of the data slots (e.g., $\frac{1}{4}$ of a data slot). In the data signal (e.g., the multiplexed data signal) **302**, the arrival of each successive data block is marked by a lull (e.g., a high impedance state) followed by the start bit.

FIG. 4A is a waveform diagram **400a** illustrating waveforms of signals received and transmitted by the gateway node **110**, sensors **130**, and the repeater **140** in a multi-sensor synchronous telemetry system **100**, according to an embodiment of the teachings herein.

For simplicity of illustration, it is assumed here that the synchronous telemetry system **100** includes only a single repeater **140** and N sensors (N being an even integer greater than **3**) half of which appear before the repeater **140**; however, embodiments of the teachings herein are not limited thereto and the operations described herein are equally applicable to a telemetry system including any (non-zero) number of repeaters **140** and sensors **130**.

Here, the sensor **130** furthest away from the gateway node **110** is labeled as Sensor **1** as it is the first sensor **130** in the chain of N sensors **130** to transmit data back to the gateway node **110** despite the fact that it is the last sensor in the chain to receive the synchronization signal. In the same manner, the closest sensor **130** to the gateway node **110** is labeled as Sensor N as it is the last in a chain of N sensors **130** to transmit data back to the gateway node **110**. For simplicity of illustration, it is assumed that the repeater **140** and Sensor **1** are located at distances L_1 and L_2 , respectively from the gateway node **110** (where L_2 is greater than L_1).

The gateway node **110** generates and transmits a synchronization signal to the field nodes (e.g., sensors **130** and repeater **140**) through the cable **120**. The synchronization signal arrives at the repeater **140** with a delay of Δt_1 corresponding to

the length L_1 . In an embodiment, the repeater **140** passes the synchronization signal (e.g., SYNC pulse) through without re-clocking for transmission to the sensors **130** down the line. In an embodiment, the repeater **140** also passes the superframe bit and the command bit through without any re-clocking. The signal is further delayed as it
5 arrives at Sensor **2** and then Sensor **1**. Sensor **1** receives the repeated synchronization signal with a further delay of Δt_2 corresponding to the length $L_2 - L_1$. In an example in which L_1 and L_2 are about **250** m and about **500** m, respectively, Δt_1 and Δt_2 may equal about **1.25** μ s.

In an embodiment, each of the Sensors **1-N** performs its measurements when it
10 detects the SYNC pulse of the synchronization signal. However, the Sensors **1-N** are configured to (e.g., preprogrammed to) transmit their data signals encapsulating the collected data (which appears in the form of data blocks) during preset data slots in a staggered manner (also referred to as time-division multiplexing). For example, Sensor **1** may transmit during what it perceives as Slot **2**, Sensor **2** may transmit during
15 its perceived Slot **3**, and so forth. However, due to signal transmission delays, when each of the transmitted data blocks reaches the repeater **140**, it may be misaligned (e.g., not line up with) the data slots as perceived by the repeater **140**. For example, as illustrated in FIG. 4A, the data signal (e.g., data block) **401** from Sensor **1** may occupy about one half of Slot **2** at the repeater **140** and part of Slot **3**. In an
20 embodiment, the repeater **140** re-clocks the data signals received by shifting the data signals in time to align with (e.g., begin at) the next data slot. For example, the repeater **140** may re-clock the data signal **401** from Sensor **1** to start at the beginning of Slot **4** as data signal **401'**. In so doing, the repeated data signals from Sensors **1-N/2** may be shifted by, for example, two data slots. The repeated data signals arrive
25 at the gateway node **110** after a further transmission delay of Δt_1 . The gateway node **110** differentiates the data blocks using the start bit at the beginning of each data block and the lull period that follows the end of a data block.

In addition to re-clocking (e.g., performing timing alignment) of data signals, the repeater **140** also regenerates (e.g., reconditions) the constituent bits of the data block

as appropriate to compensate for any transmission degradation and noise due to the cable **120** and/or environmental factors. In so doing, the repeater **140** extends the range that the data signals can traverse while maintaining an acceptable bit error rate. According to an embodiment, the repeater **140** may also perform a parity check using
5 the one or more parity bits of the data signal received.

FIG. 4B illustrates a waveform diagram **400b** of data blocks transmitted from sensors **130** to the gateway node **110** in a multi-sensor synchronous telemetry system **100**, according to an embodiment of the teachings herein.

In the example illustrated in FIG. 4B, the synchronous telemetry system **100** includes
10 **36** sensors **130** distributed at regular intervals along a **500** m long cable **120**, and a repeater **140** located at the middle of the cable at about **250** m. The gateway node **110** transmits a synchronization signal having a number of frames, each marked by a SYNC pulse. The SYNC signal prompts Sensors **1-36** to nearly concurrently perform measurements of one or more environmental parameters. The repeater **140** passes
15 the SYNC pulse through without re-clocking to preserve timing synchronization. Upon detecting the SYNC pulse, the Sensors **1-36** transmit data signals **411-446** corresponding to their measurements at predetermined times (e.g., at beginnings of successive data slots). For example, Sensors **1-18** may sequentially transmit data signals **401-418** during the first-time block T_1 , and Sensors **19-36** may sequentially
20 transmit data signals **419-436** during the second time block T_2 . Upon receiving each of the data signals **401-418** from Sensors **1-18**, the repeater **140** repeats (e.g., resynchronizes) the received stream Rx(Rep) by re-clocking and regenerating (e.g., reconditioning) each of the data signals **401-418** to generate data signals **401'-418'**, which make up the transmit stream Tx(Rep). The transmit stream Tx(Rep) may be
25 shifted in time from the received stream Rx(Rep) by a period of time greater than a data slot and less than two data slots. The transmission time of Sensor **19** may be set (or configured) such that data signal **429** occupies the data slot immediately following that of the last data signal of the transmit stream Tx(Rep), that is, data signal **418'**. Sensors **20-36** may sequentially transmit data signals **420-436**, as show in FIG. 4B.

After a period of time corresponding to a transmission delay of **250 m**, the gateway node **110** receives the data signals **401'-418'** and **419-436**, which together form the received stream Rx(GN). The received stream Rx(GN) represents the uplink data signal as detected by the gateway node **110**.

- 5 The gateway node **110** may be coupled to the processing unit for analyzing the sensor data from the received stream Rx(GN). The processing unit may further control the operation of the gateway node **110**. A user may interact with the processing unit through a graphical user interface (GUI).

FIG. **5** illustrates a graphical user interface (GUI) **500** of the processing unit including
10 control and monitoring panels, according to an embodiment of the teachings herein.

The GUI **500** may include a control panel **502** for controlling various aspects of the synchronous telemetry system **100**, such as toggling the system power, operating in diagnostic mode, etc. The GUI may further include a monitor panel **504** for monitoring various aspects of the data received from the each of the sensors **130**. In the example
15 of FIG. **5**, the monitor panel depicts the power levels of signals received from a synchronous telemetry system **100** having **144** sensors **130**. An alarm panel **506** may provide a running tally of warnings or errors generated during the course of operation of the synchronous telemetry system **100**.

FIG. **6** is a block diagram of a process **600** of repeating signals received by the
20 repeater **140**, according to an embodiment of the teachings herein.

In block **602**, the repeater **140** receives a synchronization signal at the first input-output port **201a** of the repeater **140**. The first transceiver **200a** passes the synchronization signal to the synchronization controller **204**, which locks into the periodicity and phase of the synchronization signal and generates a timing signal SYNC_GATE for controlling
25 the timing operation of the internal components of the repeater **140**.

In block **604**, the repeater **140** passes the synchronization signal through to the second input-output port **201b** of the repeater **140** for downlink transmission to one or more sensors **130**. The repeater **140** (e.g., the pass-through gate **206**) may pass through the synchronization signal without regenerating the signal.

In block **606**, the repeater **140** receives a multiplexed data signal at the second input-output port **201b** of the repeater **140**. The second transceiver **200b** passes the multiplexed data signal, which due to line delays may be out of sync with the synchronization signal, to the data regenerator **208** for resynchronization.

- 5 In block **608**, the data regenerator **208** resynchronizes the multiplexed data signal to generate a resynchronized multiplexed data. The data generator **208** may utilize a number of shift registers to resynchronize the multiplexed data signal by re-clocking (e.g., delaying by an appropriate amount to align with a next time slot) and regenerating the data bits of the multiplexed data signal.
- 10 In block **610**, the repeater **140** transmits the resynchronized multiplexed data signal through the first input-output port **201a** to the gateway node **110**. In an example, the resynchronized multiplexed data signal may pass through one or more sensors **130** that may be coupled between repeater **140** and the gateway node **110**.

The embodiments described herein have employed active-high signals, however, as
15 will be understood by a person of ordinary skill in the art, the embodiments of the teachings herein may also operate using active-low signals without departing from the spirit and scope of the teachings herein. For example, with suitable changes to their circuitry, the gateway node **110**, sensors **130**, and repeater **140** can operate based on signals that are the inverse of the signals shown in FIGS. 2B, 3A-3C, and 4A-4B.

- 20 While the teachings herein have been described in detail with particular references to illustrative embodiments thereof, the embodiments described herein are not intended to be exhaustive or to limit the scope of the teachings herein to the exact forms disclosed. Persons skilled in the art and technology to which this patent pertains will appreciate that alterations and changes in the described structures and methods of
25 operation can be practiced without meaningfully departing from the principles, spirit, and scope of the teachings herein.

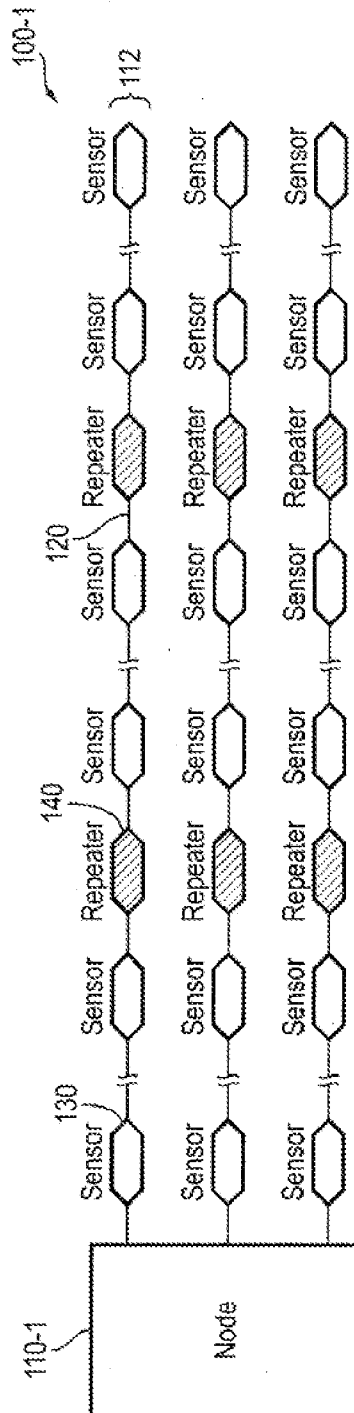
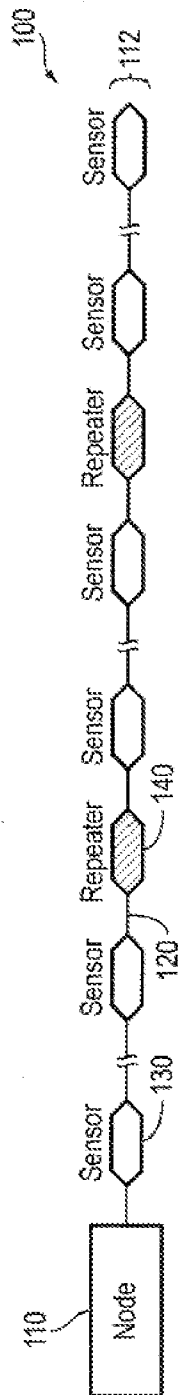
EMBODIMENTS IN WHICH AN EXCLUSIVE PROPERTY OR PRIVILEGE IS CLAIMED ARE DEFINED AS FOLLOWS:

1. A bidirectional repeater for repeating an electrical signal traversing a conductive line coupled between a gateway node and a sensor, the bidirectional repeater comprising:
 - a first input-output port coupled to the gateway node;
 - a second input-output port coupled to the sensor;
 - a first transceiver configured to receive from the gateway node, via the first input-output port, a synchronization signal of a plurality of synchronization signals and to transmit a resynchronized data signal via the first input-output port to the gateway node;
 - a second transceiver configured to transmit the synchronization signal to the sensor via the second input-output port and to receive a data signal via the second input-output port, from the sensor; and
 - a repeater circuit coupled to the first and second transceivers and configured to pass through the synchronization signal without re-clocking the synchronization signal, and to resynchronize the data signal to generate the resynchronized data signal,wherein an entirety of the resynchronized data signal occupies a time period between consecutive ones of the plurality of synchronization signals.
2. The bidirectional repeater of claim 1, wherein the repeater circuit comprises a timing control circuit that is configured to lock into a phase of the synchronization signal.
3. The bidirectional repeater of claim 1 or 2, wherein the repeater circuit is configured to resynchronize the data signal by re-clocking and regenerating the data signal.

4. The bidirectional repeater of claim 3, wherein re-clocking the data signal comprises shifting the data signal in time to start at a beginning of a next time slot.
5. The bidirectional repeater of any one of claims 1-4, wherein the data signal comprises a serial, bidirectional, time division multiplexed data and is divided into a number of frames, each frame having a plurality of time slots.
6. The bidirectional repeater of claim 5, wherein a time slot of the plurality of time slots comprises a data bit.
10. 7. The bidirectional repeater of claim 6, wherein regenerating the data signal comprises recreating the data bit to correct for noise and signal distortion.
8. The bidirectional repeater of claim 1, wherein the synchronization signal comprises a single pulse.
15. 9. The bidirectional repeater of claim 1, wherein the repeater circuit is configured to pass through the synchronization signal without regenerating the synchronization signal.
10. The bidirectional repeater of claim 1, wherein the repeater circuit is further configured to lock into a phase of the synchronization signal.
20. 11. The bidirectional repeater of any one of claims 1-10, wherein the repeater is coupled to a plurality of sensors comprising the sensor, wherein the first input-output port is coupled to the gateway node through one or more sensors of the plurality of sensors.
12. A synchronous telemetry system comprising:
 - a cable comprising one or more conductive elements for conducting a synchronization signal of a plurality of synchronization signals;
 25. a gateway node configured to supply the synchronization signal, and to receive a resynchronized data signal;

- a repeater coupled to the cable, and configured to receive and pass through the synchronization signal from the gateway node, without re-clocking the synchronization signal; and
- 5 a sensor coupled to the cable and configured to receive the synchronization signal, to measure a parameter in response to receiving the synchronization signal and to generate a data signal corresponding to the measured parameter;
- 10 wherein the repeater is coupled between the gateway node and the sensor, and is further configured to receive and re-clock and reconstruct the data signal from the sensor to generate the resynchronized data signal,
- wherein an entirety of the resynchronized data signal occupies a time period between consecutive ones of the plurality of synchronization signals.
13. The synchronous telemetry system of claim **12**, wherein the one or more
- 15 conductive elements comprise a pair of wires, and wherein the synchronization signal, the data signal, and the resynchronized data signal are differential signals transmitted over the pair of wires.
14. The synchronous telemetry system of claim **12** or **13**, wherein the gateway node is further configured to supply electrical power to the sensor and repeater
- 20 through the cable.
15. The synchronous telemetry system of any one of claims **12-14**, wherein each of the sensor and repeater comprise a local power source.
16. The synchronous telemetry system of any one of claims **12-15**, wherein the synchronous telemetry system comprises a plurality of segments coupled in
- 25 series, each segment comprising a plurality of sensors comprising the sensor and one or more repeaters comprising the repeater.

17. The synchronous telemetry system of claim **16**, wherein the plurality of sensors concurrently measure parameters in response to receiving a synchronization signal.
18. The synchronous telemetry system of any one of claims **12-17**, wherein the
5 sensor comprises at least one of an acoustic sensor, optical sensor, temperature sensor, and vibration sensor.
19. A method of repeating an electrical signal traversing a conductive line coupled between a gateway node and a sensor, the method comprising:
- 10 receiving from the gateway node, by a repeater, a synchronization signal, from a plurality of synchronization signals, at a first input-output port of the repeater, the gateway being in communication with the first input-output port of the repeater;
- 15 passing through, by the repeater, the synchronization signal, without re-clocking the synchronization signal, at a second input-output port of the repeater, the second input-output port being in communication with the sensor;
- receiving, by the repeater, a data signal from the sensor, via the second input-output port of the repeater;
- 20 resynchronizing, by the repeater, the data signal to generate a resynchronized data signal; and
- transmitting, by the repeater, the resynchronized data signal via the first input-output port of the repeater, to the gateway node;
- 25 wherein an entirety of the resynchronized data signal occupies a time period between consecutive ones of the plurality of synchronization signals.
20. The method of claim **19**, further comprising:
- locking, by the repeater, into a phase of the synchronization signal.



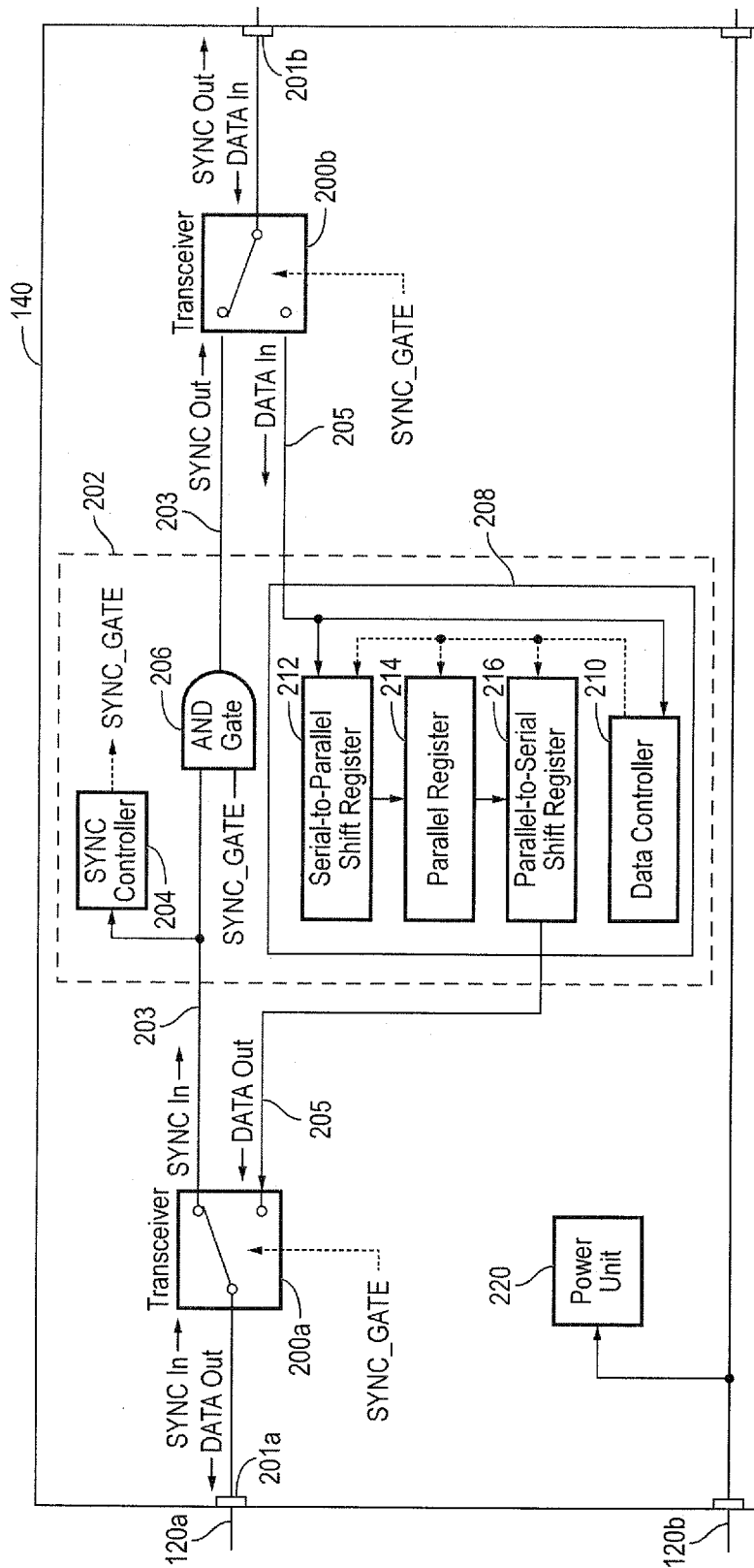


FIG. 2A

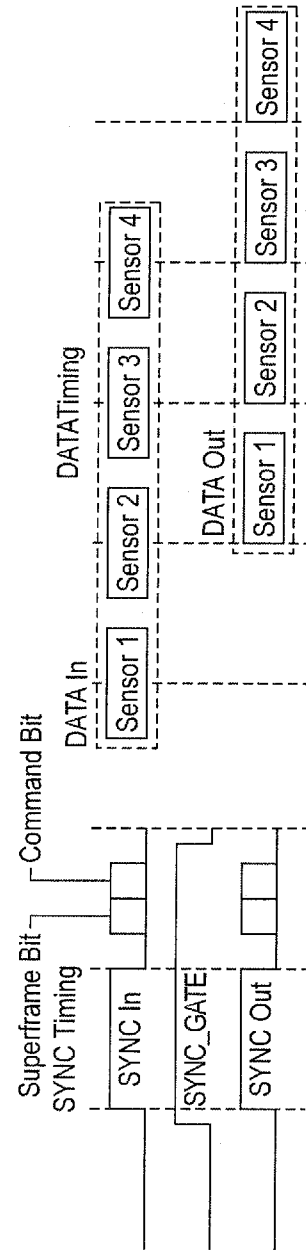


FIG. 2B

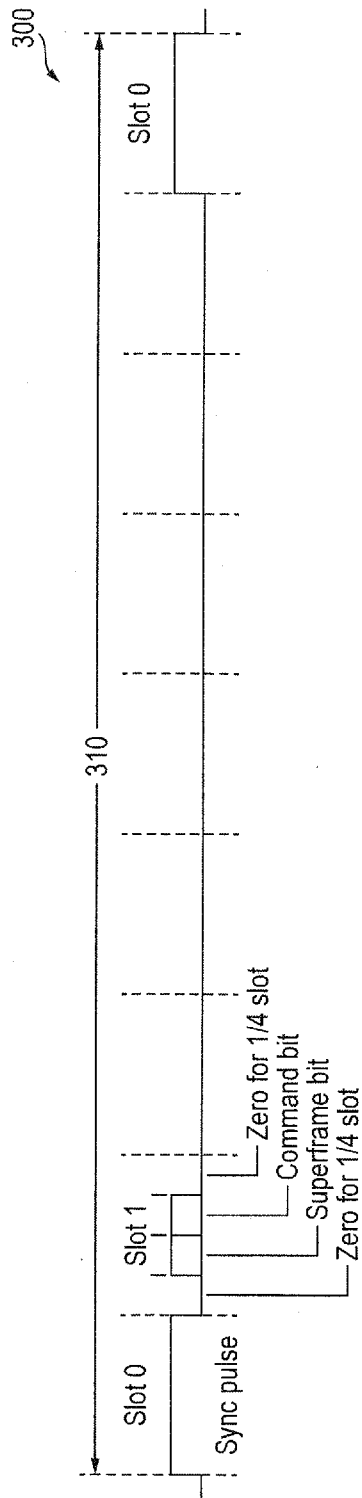


FIG. 3A

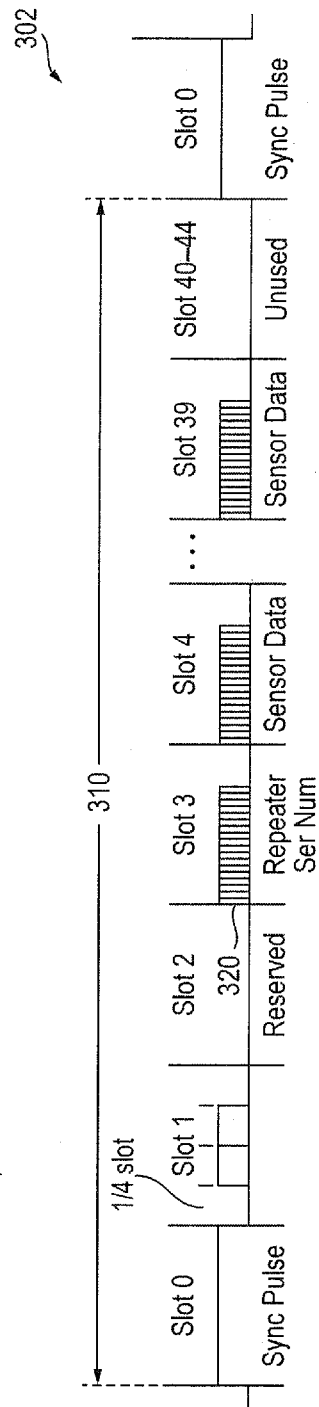


FIG. 3B



FIG. 3C

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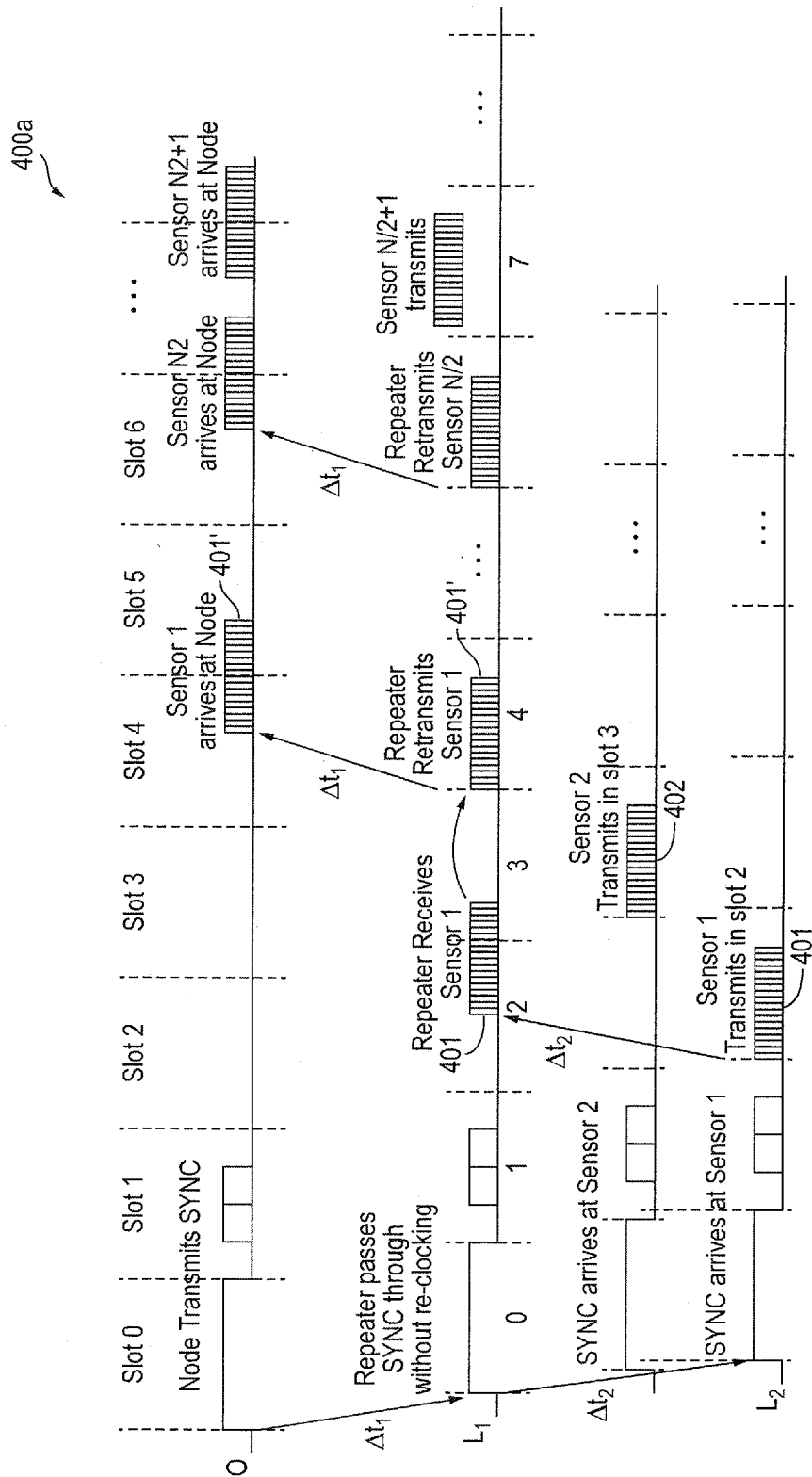


FIG. 4A

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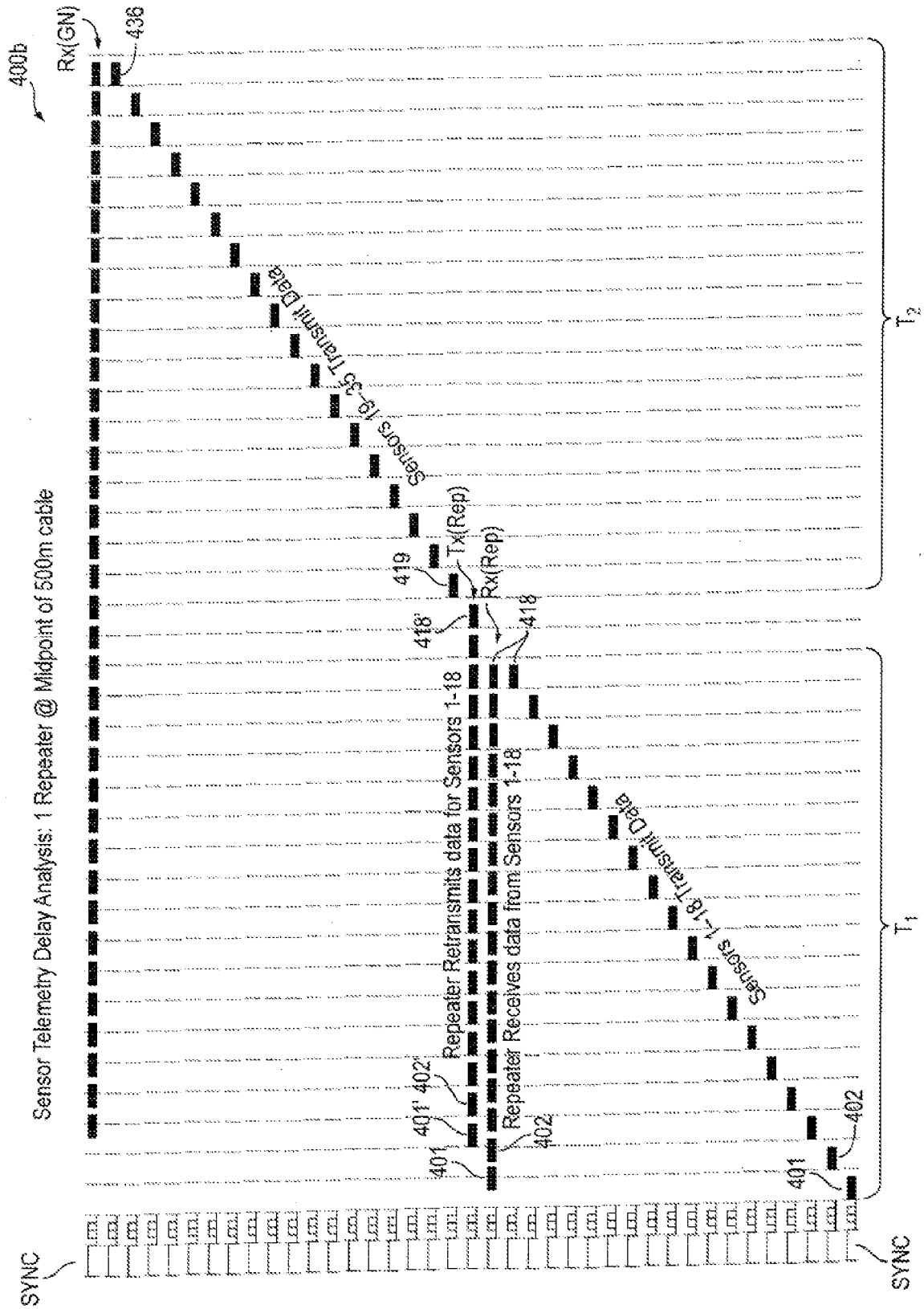


FIG.4B

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500

506

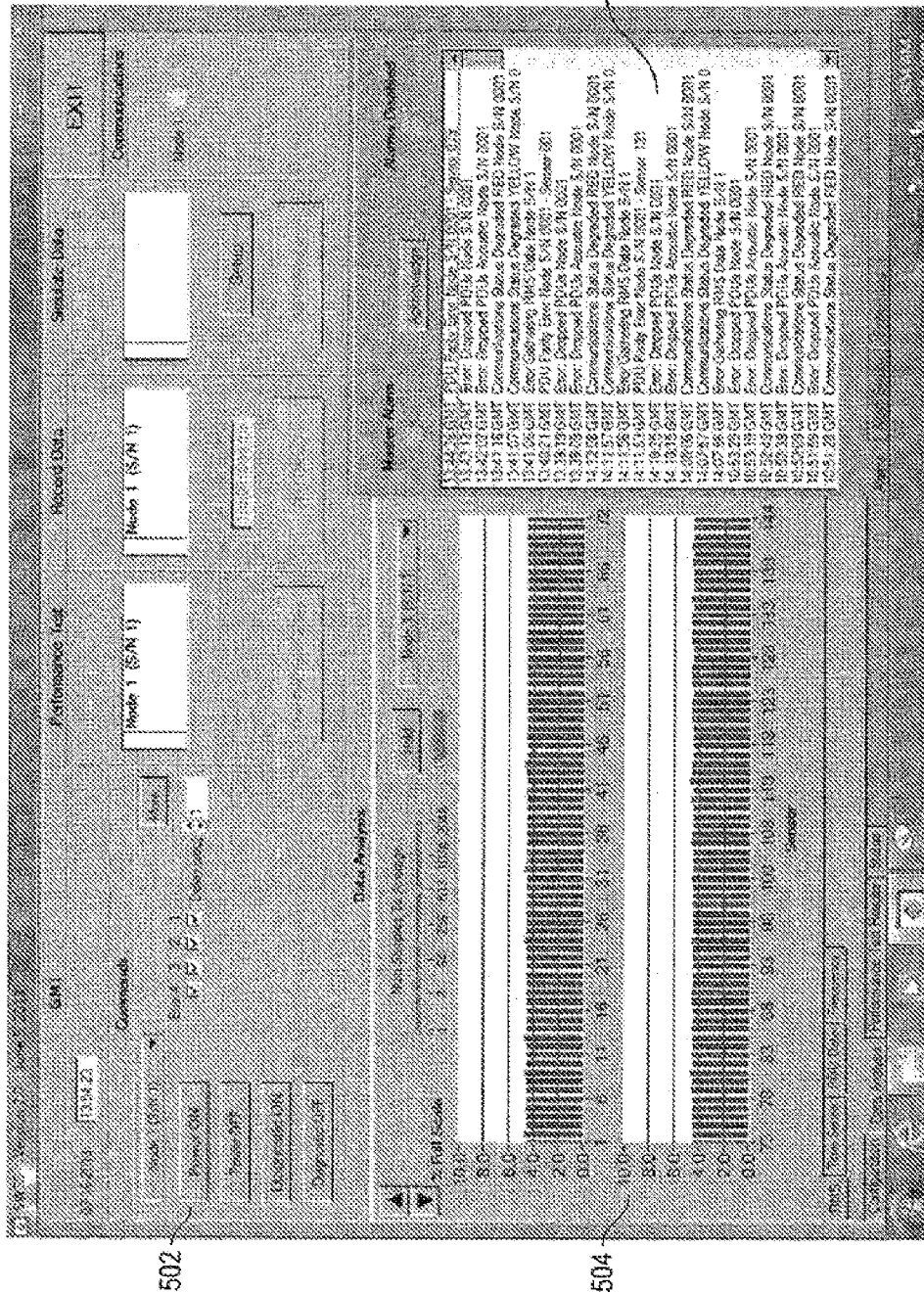


FIG. 5

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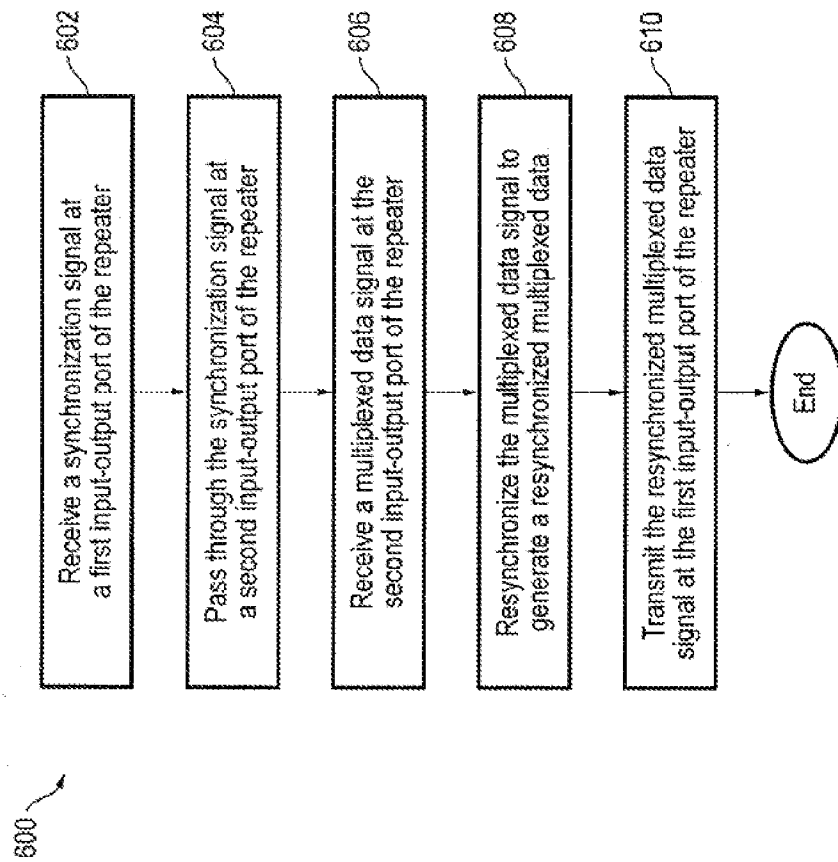


FIG. 6

