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# DESCRIPTION

## CLAIM FOR PRIORITY

[0001] This application claims priority to U.S. Patent Application No. 11/768,056, filed June 25, 2007.

## TECHNICAL FIELD

[0002] The present invention relates generally to a system and method for monitoring driver behavior and vehicle driving conditions and, more particularly, to a system and method for monitoring driving against minimum standards and for improving driver behavior.

## BACKGROUND

[0003] Currently there are systems that allow a fleet manager or vehicle owner to track the location of their vehicle(s) such as by using a GPS reporting capability of a cellular phone or other wireless device. These devices may provide additional notification, such as when a vehicle leaves or enters a predefined area (i.e. a geofence) or when the vehicle exceeds a certain speed. However, other than providing such warnings or notifications to a fleet manager, vehicle owner, parent or other supervisor, the current systems provide little or no real-time feedback to the driver to correct their behavior.

[0004] Without having a driving instructor or other operator in the vehicle, there is currently no system or method available for providing real-time feedback, training and mentoring to drivers based upon the actual operation of the vehicle (i.e. based upon the driver's behavior while driving). Accordingly, aggressive driver behavior and driver inattention may not be detected and/or corrected, thereby reducing driver and vehicle safety. The absence of feedback as a means to identify unsatisfactory driving behavior dissociates the driver from the infraction; denial is the likely result. However, immediate feedback to infractions or undesirable driving behavior has enormous benefit in mentoring the driver and delineating acceptable from unacceptable driving behavior.

[0005] US Publication No. 2002/0019703 discloses a safety system for automotive vehicles to automatically detect and monitor various movements of a driven vehicle and automatically communicate such movements to others and to the police.

[0006] CA Publication No. 2 307 259 discloses an apparatus for monitoring vehicle speed and detecting episodes of vehicle speed in excess of predetermined speed thresholds and recording those episodes to a non-volatile memory system.

**BRIEF SUMMARY**

**[0007]** There exists a need in the art for a driver mentoring system that is adaptable for use in various settings, including commercial fleet operators, teen drivers, and new drivers, that monitors at-risk and/or unsafe driver behavior and provides mentoring to the driver in order to reduce adverse driver actions and inactions that may lead to accidents. The present invention relates to a system and method for monitoring driver behavior for use by companies, government agencies, consumers, or the general public. For example, the present invention allows parents to remotely mentor the driving habits of their teen children as well as allow for monitoring of geographic areas into which their children may enter. Moreover, the present invention may also be used by fleet operators to monitor and mentor the driving behavior of experienced drivers.

**[0008]** The vehicle behavior monitoring system disclosed herein provides for real-time reconfiguration of driver performance and vehicle operation parameters and which allows for reporting of such data in order to generate driver profiles and trends. The present invention provides a unique vehicle monitoring system specifically adapted to mentor driver performance in order to improve driver safety and reduce accident rates and formulate various methods to establish and/or delineate "good" driving behavior from "bad" driving behavior.

**[0009]** The invention is directed to a system and method for providing feedback to drivers according to the independent claims. The system monitors selected vehicle parameters while a vehicle is being driven, and detects one or more vehicle operation violations by comparing the selected vehicle parameters to predetermined thresholds. A mentoring message is provided to the driver if the threshold is exceeded. The system also filters gravitational effects out of longitudinal, lateral and vertical acceleration measurements when the vehicle is on an incline or changes its horizontal surface orientation. If a vehicle operation violation has not been corrected within a preselected time period, then a violation report may be sent to a third party or a central server. If a vehicle operation violation has not been corrected within a preselected time period, then a different mentoring message may be provided to the driver. Vehicle parameter data may be monitored from an on-board vehicle diagnostic system. The mentoring message may be an audible warning, such as a spoken message, or a visual warning, such as a text message. The selected vehicle parameters may be a vehicle speed, a vehicle speed for the specific road conditions, a vehicle acceleration, an errant lane departure, following too close to a subsequent vehicle, a vehicle seatbelt use, the use of a mobile phone, the detection of unlawful ethanol concentrations, the detection of fatigue (blink rate) and/or other traceable, detectable activities, elements, and/or behaviors.

**[0010]** In another non claimed embodiment, a system and method for monitoring vehicle operation, comprises installing a monitoring device in a vehicle, wherein the monitoring device monitors vehicle operation parameters, and wherein the vehicle monitoring device is capable of providing mentoring feedback to a driver. The vehicle operation is monitored without

providing the mentoring feedback during a baseline period and baseline vehicle operation data is collected for the baseline period. Baseline vehicle operation data may be collected for multiple vehicles.

**[0011]** After the baseline period, vehicle operation is monitored and mentoring feedback is provided to the driver. Mentored vehicle operation data is collected after the baseline period. The mentored vehicle operation data is compared to the baseline vehicle operation data to determine driving improvement. The vehicle operation parameters for monitoring during the baseline period may be selected by the user. The baseline vehicle operation data and/or mentored vehicle operation data can be transmitted to a central server.

**[0012]** A system and method for establishing a vehicle operation profile, comprises installing a monitoring device in a vehicle, wherein the monitoring device monitors vehicle operation parameters, monitoring vehicle operation during a training period, collecting vehicle operation training data for the training period, and creating the vehicle operation profile based upon the vehicle operation training data. The vehicle operation is then monitored during a monitoring period; and vehicle operation data during the monitoring period is compared to the vehicle operation profile.

**[0013]** Mentoring messages can be provided to a driver based upon differences between the vehicle operation data and the vehicle operation profile. The vehicle operation profile comprises thresholds for the vehicle operation parameters, and vehicle operation data observed during the monitoring period is compared to the thresholds. The vehicle operation parameters to be monitored during the training period and/or during the mentoring period may be selected by a user.

**[0014]** Thresholds are established for vehicle operation parameters based upon the vehicle operation training data. The thresholds correspond to an average observed value of the vehicle operation parameters, a maximum observed value of the vehicle operation parameters, or a selected percentage above a value of the vehicle operation parameters. The user may adjust the thresholds for vehicle operation parameters from an observed value. Alternatively, a user may adjust the thresholds for vehicle operation parameters from value established by the vehicle monitoring system.

**[0015]** In an additional aspect, it is disclosed a vehicle monitoring system for providing feedback to a driver, comprising a vehicle information interface; an output interface; and a processor in communication with the vehicle information interface and the output interface, such that the processor is operable to monitor data collected while a vehicle is being driven using the vehicle information interface, to detect one or more vehicle operation violations by comparing the collected data to a predetermined threshold, and to alert the driver if the predetermined threshold is exceeded using the output interface, wherein the vehicle information interface includes one or more of the group consisting of an on-board diagnostic system; an accelerometer; a geolocation device; and a tire pressure sensor.

**BRIEF DESCRIPTION OF THE DRAWINGS**

**[0016]** For a more complete understanding of the present invention, and the advantages thereof, reference is now made to the following descriptions taken in conjunction with the accompanying drawings, in which:

Figure 1 is a diagram of a system incorporating embodiments of the invention mounted in a vehicle;

Figure 2 is a diagram of possible locations of cameras and/or other technologies used in embodiments of the invention;

Figure 3 is a flowchart illustrating one process for implementing the present invention;

Figure 4 illustrates a process for measuring baseline data; and

Figure 5 illustrates a process for creating an acceptable driving profile.

**DETAILED DESCRIPTION**

**[0017]** The present invention provides many applicable inventive concepts that can be embodied in a wide variety of specific contexts. The specific embodiments discussed are merely illustrative of specific ways to make and use the invention, and do not limit the scope of the invention.

**[0018]** With reference now to Figure 1, there is shown a vehicle 101 in which a vehicle monitoring device is installed. The monitoring device may be self contained, such as a single unit mounted on a windshield 105 or dashboard 106. Alternatively, the monitoring device may include multiple components, such as a processor or central unit mounted under a car seat 103 or in a trunk 104. Similarly, the monitoring device may have a self-contained antenna in the unit (105), or may be connected to remotely mounted antennas 107. The vehicle monitoring units may be connected to an on-board diagnostic (OBD) system or bus in the vehicle. Information and data associated with the operation of the vehicle may be collected from the OBD system, such as engine operating parameters, vehicle identification, seatbelt use, door position, etc. The OBD system may also be used to power the vehicle monitoring device.

**[0019]** Information may be exchanged between the vehicle monitoring system and a central monitoring system or server in real-time or at intervals. For example, the vehicle operation parameters may be transmitted to server 109 via communication network 108, which may be a cellular, satellite, WiFi, Bluetooth, infrared, ultrasound, short wave, microwave or any other

suitable network. Server 109 may process the parameters and/or store the data to database 110, which may be part of server 109 or a separate device located nearby or at a remote location. Users can access the data on server 109 and database 110 using terminal 111, which maybe co-located with server 109 and database 110 or coupled via the Internet or other network connection. In some embodiments, the data captured by the monitoring system in vehicle 101 may be transmitted via a hardwired communication connection, such as an Ethernet connection that is attached to vehicle 101 when the vehicle is within a service yard or at a base station. Alternatively, the data may be transferred via a flash memory, diskette, or other memory device that can be directly connected to server 109 or terminal 111. Data, such as driving performance or warning thresholds, may also be uploaded from the central server to the vehicle monitoring device in a similar manner.

**[0020]** In one embodiment of the invention, the data captured by the vehicle monitoring system is used to monitor, mentor or otherwise analyze a driver's behavior during certain events. For example, if the vehicle is operated improperly, such as speeding, taking turns too fast, colliding with another vehicle, or driving in an unapproved area, then a supervisor may want to review the data recorded during those events to determine what the driver was doing at that time and if the driver's behavior can be improved. Additionally, if the driver's behavior is inappropriate or illegal, such as not wearing a seatbelt or using a cell phone while driving, but does not cause the vehicle to operate improperly, a supervisor may also want to review the data recorded during those events.

**[0021]** Referring to Figure 2, exemplary mounted locations for the vehicle monitoring system are illustrated, such as on a dashboard 201, windshield 202, or headliner 203. It will be understood that all or parts of the vehicle monitoring system may be mounted in any other location that allows for audio and/or visual feedback to the driver of the vehicle while the vehicle is in operation. Monitoring device 201 is illustrated as being coupled to OBD 102, from which it may receive inputs associated with vehicle operating parameters. Monitoring devices 202 and 203 may be similarly coupled to OBD 102 (connections not shown). Moreover, the vehicle monitoring system may be coupled to other sensors, such as a sensor for detecting the operation and use of a cellular or wireless device in the vehicle.

**[0022]** In one aspect of the invention, the vehicle monitoring system includes an accelerometer module (XLM) that includes at least one accelerometer for measuring at least one of lateral (sideways), longitudinal (forward and aft) and vertical acceleration in order to determine whether the driver is operating the vehicle in an unsafe or aggressive manner. For example, excessive lateral acceleration may be an indication that the driver is operating the vehicle at an excessive speed around a turn along a roadway. Furthermore, it is possible that the driver may be traveling at a speed well within the posted speed limit for that area of roadway. However, excessive lateral acceleration, defined herein as "hard turns," may be indicative of aggressive driving by the driver and may contribute to excessive wear on tires and steering components as well as potentially causing the load such as a trailer to shift and potentially overturn.

**[0023]** As such, it can be seen that monitoring and mentoring such driver behavior by

providing warnings to the driver during the occurrence of aggressive driving such as hard turns can improve safety and reduce accidents. In addition, mentoring such aggressive driver behavior can reduce wear and tear on the vehicle and ultimately reduce fleet maintenance costs as well as reduce insurance costs and identify at risk drivers and driving behavior to fleet managers.

**[0024]** The vehicle monitoring system may further include a self-contained and tamper-resistant event data recorder or crash data recorder (CDR), such as, for example, the CDR which is shown and disclosed in U.S. Patent Nos. 6,266,588 and 6,549,834 issued to McClellan et al., and which is commercially known as "Witness" and commercially available from Independent Witness, Inc. of Salt Lake City, Utah. The CDR is adapted to continuously monitor vehicle motion and begin recording upon supra-threshold impacts whereupon it records the magnitude and direction of accelerations or G-forces experienced by the vehicle as well as recording an acceleration time-history of the impact event and velocity change between pre- and post-impact for a configurable duration following the impact. The CDR may be separate from the accelerometer module (XLM) or may be the same device.

**[0025]** In one aspect, the vehicle monitoring system may be in data communication with an on board diagnostic (OBD) II system of the vehicle such as via a port. In some vehicle models, the vehicle monitoring system is in data communication with a controller area network (CAN) system (bus) to allow acquisition of certain vehicle operating parameters including, but not limited to, vehicle speed such as via the speedometer, engine speed or throttle position such as via the tachometer, mileage such as via the odometer reading, seat belt status, condition of various vehicle systems including anti-lock-braking (ABS), turn signal, headlight, cruise control activation and a multitude of various other diagnostic parameters such as engine temperature, brake wear, and the like. The OBD or CAN allows for acquisition of the above-mentioned vehicle parameters for processing thereby and/or for subsequent transmission to the central server 109.

**[0026]** The vehicle monitoring system may also include a GPS receiver (or other similar technology designed to track location) configured to track the location and directional movement of the vehicle in either real-time or over-time modes. As is well known in the art, GPS signals may be used to calculate the latitude and longitude of a vehicle as well as allowing for tracking of vehicle movement by inferring speed and direction from positional changes. Signals from GPS satellites also allow for calculating the elevation and, hence, vertical movement, of the vehicle.

**[0027]** Embodiments of the vehicle monitoring system may further include a mobile data terminal (MDT) mounted for observation and manipulation by the driver, such as near the vehicle dash. The MDT preferably has an operator interface such as a keypad, keyboard, touch screen, display screen or any suitable user input device and may further include audio input capability such as a microphone to allow voice communications. The MDT may include at least one warning mechanism such as a speaker and/or a warning light for warning the driver of violation of posted speed limits and/or exceeding acceleration thresholds in lateral,

longitudinal and vertical directions as an indication of hard turns, hard braking or hard vertical, respectively.

**[0028]** The vehicle monitoring system receives inputs from a number of internal and external sources. The OBD II/CAN bus, which provides data from the vehicle's on-board diagnostic system, including engine performance data and system status information. A GPS receiver provides location information. The CDR, XLM, or accelerometers provide information regarding the vehicle's movement and driving conditions. Any number of other sensors, such as but not limited to, a seat belt sensor, proximity sensor, driver monitoring sensors, or cellular phone use sensors, also provide inputs to the vehicle monitoring system.

**[0029]** The vehicle monitoring system compares these inputs to preset thresholds and determines when an exception condition occurs or when a threshold is exceeded that requires an alarm to be generated in the vehicle. The alarm may be an audible and/or visual warning for the vehicle occupants. Additionally, any of the data collected may be passed on to server 109 or database 110 where it may be further processed or accessed. The vehicle operation thresholds may be entered directly into the vehicle monitoring system or may be received as updated, revised, or corrected rule sets, commands or logic from server 109.

**[0030]** The vehicle monitoring system may have any type of user interface, such as a screen capable of displaying messages to the vehicle's driver or passengers, and a keyboard, buttons or switches that allow for user input. The system or the user interface may have one or more status LEDs or other indicators to provide information regarding the status of the device's operation, power, communications, GPS lock, and the like. Additionally, the LEDs or other indicators may provide feedback to the driver when a driving violation occurs. Additionally, monitoring system may have a speaker and microphone integral to the device.

**[0031]** The monitoring system may be self-powered, such as by a battery, or powered by the vehicle's battery and/or power generating circuitry. Access to the vehicle's battery power may be by accessing the power available on the vehicle's OBD and/or CAN bus.

**[0032]** The vehicle monitoring system may be self-orienting, which allows it to be mounted in any position, angle or orientation in the vehicle or on the dashboard. In embodiments of the invention, the vehicle monitoring system determines a direction of gravity and a direction of vehicle movement and determines its orientation within the vehicle using this information. In order to provide more accurate measurements of driver behavior, the present invention filters gravitational effects out of the longitudinal, lateral and vertical acceleration measurements when the vehicle is on an incline or changes its horizontal surface orientation. Driver performance is monitored and mentored using the accelerometer module, which preferably will be a tri-axial accelerometer. Acceleration is measured in at least one of lateral, longitudinal and/or vertical directions over a predetermined time period, which may be a period of seconds or minutes. An acceleration input signal is generated when a measured acceleration exceeds a predetermined threshold.

**[0033]** It will be understood that the present invention may be used for both fleets of vehicles and for individual drivers. For example, the vehicle monitoring system described herein may be used by insurance providers to monitor and/or mentor the driving behavior of customers and to use collected data to set insurance rates. A private vehicle owner may also use the present invention to monitor the use of the vehicle. For example, a parent may use the system described herein to monitor a new driver or a teenaged driver.

**[0034]** An embodiment of the invention provides real-time mentoring, training, or other feedback to a driver while operating the vehicle. The mentoring is based upon observed operation of the vehicle and is intended to change and improve driver behavior by identifying improper or illegal operation of the vehicle. Using preset criteria or thresholds, the vehicle monitoring system identifies when the vehicle is operated outside the criteria or beyond the preset thresholds to determine that a violation has occurred.

**[0035]** Numerous parameters may be measured by the vehicle monitoring system and used to provide driver mentoring. Speeding criteria, such as driving above a maximum speed limit, violation of a posted speed limit in a speed-by-street database, or violating a speed limit in a designated zone, may cause the vehicle monitoring system to warn the driver. U.S. Patent Application No. 11/805,238, filed May 22, 2007, entitled "System and Method for Monitoring and Updating Speed-By-Street Data," describes the use of speed-by-street information by a vehicle monitoring system. Upon detection of the speeding violation, the monitoring system will provide an audible and/or visual warning to the driver. For example, a spoken message identifying the speeding condition or a spoken message instructing the driver to slow down may be played to the driver. Alternatively, a selected tone or buzzer may sound when a speeding violation occurs. A visual warning, such as an LED warning light may illuminate or flash to notify the driver of a violation.

**[0036]** The vehicle monitoring system may identify aggressive driving violations. For example, based upon the inputs from an acceleration module or CDR, aggressive driving events may be detected, such as exceeding acceleration thresholds in a lateral, longitudinal, or vertical direction, hard turns, hard acceleration or jackrabbit starts, hard braking, and/or hard vertical movement of the vehicle. Visual and/or audible warnings may be played or displayed to the driver upon a violation of an acceleration threshold.

**[0037]** Other violations, such as operating the vehicle outside or inside a specific area or off of a specific route can trigger a visual or audible mentoring message to the driver. Areas and routes may be defined, for example, using a geofence that is compared to the vehicle's current location as determined by the GPS system. Seat belt use violation, such as failing to use a seatbelt while driving, may be detected, for example, via the OBD bus and may trigger a mentoring message to use the seatbelt. Sensors that detect exposure to ethanol (EtOH) vapor and/or detect blood EtOH levels, may be used to determine if a driver has been drinking and may have a blood alcohol level that is illegal. Based upon inputs from an EtOH sensor, the vehicle monitoring device may provide mentoring feedback to the driver or may disable the vehicle. Other sensors may detect the use of wireless devices, such as cell phones, in the

vehicle. Upon detecting cell phone use, the vehicle monitoring system may issue a warning to the driver to stop using the cell phone.

**[0038]** In one embodiment, the present invention provides real-time automatic exception alerts and reporting in the form of e-mail, phone calls, or pages to facilitate intervention and to change driver behavior. Such reporting, such as to a parent, fleet manager, supervisor, or other authority, may be made immediately upon detection of the violation or may occur if the violation is not corrected within a predetermined period of time. The alerts may contain, for example, driver performance reports such as a speeding index, "harsh" driving (e.g. acceleration, braking, turning, vertical indices) conditions, a seatbelt index and the like. The vehicle monitoring system may be configured to provide an immediate alert, or a grace period may be configured to allow the driver to correct the violation. If the violation is corrected by the driver, then no alert is sent to report the violation, thereby allowing the vehicle monitoring system to mentor the driver without human intervention.

**[0039]** The present invention to combines triggering events with visual and/or audible warning to change driver behavior. The mentoring messages may be configured by event or violation. For a selected parameter, such as vehicle speed, a user may configure one or more thresholds that, when exceeded, trigger a mentoring message. The type and content of the mentoring messages are also configurable. For example, audible and/or visual warnings may be assigned to each threshold criteria so that, upon reaching the threshold speed, for example, a selected warning is played or displayed. The warnings may be further configured to change over time. For example, audible warnings, such as tones or buzzers, may increase in volume or frequency or may change to different sound if the triggering violation is not corrected. A spoken message warning, such as "speeding violation" or "slow down," may be repeated more frequently and/or louder if the speeding violation is not corrected. Alternatively, the spoken message may change to a different message and/or a different voice if the triggering event is not stopped. Visual messages, such as warning lights, may change from flashing to steady (or visa versa) if the violation continues. Text warning messages may also be displayed to the user and may change over time.

**[0040]** Figure 3 is a flowchart illustrating one process for implementing the present invention. In step 301, a user selects and configures one or more threshold levels for parameters associated with vehicle operation and driver behavior. As noted above, these parameters may be a speeding parameter, an acceleration parameter, a seatbelt notice parameter, or any other parameter that may be measured by the vehicle monitoring system. Multiple thresholds may be assigned to a parameter, such as multiple levels of speeding thresholds to detect progressively worse speeding violations. In step 302, the user assigns audible and visual mentoring messages to each threshold level that was selected in step 301. For example, a visual mentoring message, such as a warning light, may be assigned to a first speeding threshold, the warning light may be assigned to flash if a second speeding threshold is exceeded, and an audible message may be played if a third speeding threshold is exceeded.

**[0041]** For thresholds assigned in step 301, a grace period is assigned in step 303. The grace

period may be a number of seconds or minutes. The grace period corresponds to a period of time in which the driver is allowed to correct a violation without triggering a report to a third party. The grace period may also be zero (i.e. no time for correction of the violation). In step 304, alerts are selected for the thresholds assigned in step 301. The alerts are messages or reports to be sent to third parties, such as a fleet manager, parent or supervisor, if the grace period expires and the violation has not been corrected.

**[0042]** In step 305, the vehicle monitoring device monitors vehicle parameters and thereby monitors the driver's performance while operating the vehicle. When a vehicle parameter exceeds the corresponding threshold set in step 301, the violation is detected in step 306. The vehicle monitoring system broadcasts the selected mentoring message to the driver. The mentoring message may be played and/or displayed one time or may be configured to repeat. If the violation has not been corrected, and the parameter is not back within the threshold criteria upon expiration of the grace period, then the selected alert is sent to the designated recipient in step 308.

**[0043]** The threshold criteria, mentoring messages, grace periods, and alerts selected and configured in steps 301-304 may be specific to a particular vehicle or driver. Alternatively, the variables may be selected for a group of drivers based on employer, age, experience or other criteria, for a type of vehicle, for an entire fleet of drivers or vehicles, or for any other group of one or more vehicles or drivers. The threshold criteria may be manually entered into the monitoring system on a vehicle-by-vehicle basis. Alternatively, an operator may select the threshold criteria on terminal 111, for example, and then transmit the criteria wirelessly or by wireline connection to the monitoring system in one or more vehicles.

**[0044]** In one embodiment, a baseline measurement is made for driver performance before the vehicle monitoring system begins providing mentoring to the driver. The baseline data can later be used to measure improvement in driver performance. The baseline data may be specific to single driver or to individual drivers. Alternatively, the baseline data may represent information from a fleet of drivers.

**[0045]** Figure 4 illustrates a process for measuring baseline data. In step 401, vehicle monitoring systems are installed in one or more vehicles. Multiple vehicles in a fleet with many drivers or a single vehicle driven by a single driver may be used to determine the baseline data. In step 402, all driver warnings, mentoring messages and alerts are disabled or turned off so that the drivers will not receive any feedback during the baseline measurement. It is important for the drivers to operate their vehicles "normally" during the baseline measurement and for them to drive as they have historically. By turning off all feedback from the monitoring devices, the driver will be less likely to change his usually driving behavior during the baseline period. In step 403, the vehicle monitoring system monitors the driver's performance and the vehicle's parameters while the vehicle is being driven. In step 404, data is collected during the baseline period for selected vehicle parameters. Data for all of the measurable or detectable parameters may be collected during this period, or data for only selected parameters may be recorded. Finally, in step 405, the data from multiple vehicles, trips, or users is collected and

compiled to create a baseline measurement for a fleet of vehicles.

**[0046]** Following the baseline period, the monitoring system will have collected information such as an average number of seatbelt violations for a driver per day, an average number of speeding violations per day, an average amount of excess speed (MPH) per speeding violation, an average number of jackrabbit starts per trip, and similar measurements. It will be understood that the collected data may be analyzed in any number of ways depending upon the requirements of a user. For example, data such as the total number of violations per parameter, an average number of violations per time period, or an average number of violations per driver, may be determined. Additional data, such as the amount of time elapsed until a violation is corrected, may also be collected.

**[0047]** The baseline data may be collected by individual vehicle monitoring systems and then uploaded, such as wirelessly, by wireline connection or by memory device, to server 109. A user can then review and analyze the baseline data via terminal 111. By reviewing the baseline data, the user may be able to identify violations that occur most frequently, that take the longest to correct, or that are most dangerous. The baseline data can then be used to determine and set mentoring thresholds for drivers. The mentoring thresholds may be set as single standard for an entire fleet, or may be tailored to individual drivers. For example, if the baseline data shows few incidents of seatbelt violations, the user may decide not to provide mentoring feedback for seatbelt violations or that a low-key mentoring message would be used. On the other hand, if speeding violations were more common than expected, the user could set multiple speeding thresholds with progressively shrill mentoring message to focus the driver feedback on the speeding violations.

**[0048]** In another embodiment, the monitoring system or device installed in a vehicle may be placed in a training mode. While in the training mode, the vehicle monitoring device observes the operation of the vehicle over a period of time and establishes a profile of good or acceptable driving behavior. The training mode allows the vehicle monitoring system to learn how the vehicle should be operated by observing an experienced driver, for example. When the device training period is completed, the vehicle monitoring system is switched to a monitoring mode. In the monitoring mode, the vehicle monitoring system provides feedback to the driver based upon the driving profile observed and recorded while in the training mode.

**[0049]** The training mode may be used, for example, by a parent who has installed a vehicle monitoring device in a family car. After installation, the vehicle monitoring device is set to training mode and the parent drives the car for sufficient time, such as for several days or weeks, to create a profile of acceptable driving. After the device has observed sufficient vehicle use in the training mode, the vehicle monitoring system is set to monitoring mode and a new driver, teen driver, or any other family members will get feedback and mentoring from the vehicle monitoring system based upon the driving behavior observed in the training mode. Similarly, a vehicle monitoring device installed in a commercial, government, or fleet vehicle may be placed in a training mode while an experienced driver, supervisor, or driving instructor operates the vehicle. Once a driving profile has been created for the vehicle, the monitoring

system is switched to monitoring mode and other drivers will receive feedback and mentoring from the device based upon the learned profile.

**[0050]** The parameters observed during a training mode may be a default standard for all users or may be selected by individual users, thereby allowing each user to highlight particular areas of interest. While in the training mode, for example, the vehicle monitoring system may observe the experienced driver's compliance with speed limits as compared to a speed-by-street database, the average and maximum speeds driven on various types of roads, the typical starting and braking accelerations, typical lateral acceleration in turns, and occurrences seatbelt or cellular phone use. The vehicle monitoring system stores or remembers the measured parameters, such as acceleration, deceleration, signaling in lane changes, degree of aggressiveness in turns, and the like. The vehicle monitoring system collects this data and establishes thresholds for various vehicle operation parameters, such as speeding and acceleration thresholds. These thresholds establish a good or acceptable driving standard for that vehicle. There may be one or more drivers of the vehicle during the training mode, such as both parents driving a family car. The vehicle monitoring device may or may not be notified that different drivers are using the vehicle. The vehicle monitoring device may create a single acceptable driving profile based upon all users of the vehicle. Alternatively, multiple acceptable profiles may be created, such as one per driver in the training mode. One of the training profiles may then be selected for use in the monitoring mode.

**[0051]** Using the training or learning mode, the present invention allows the vehicle monitoring system to provide appropriate feedback to drivers based upon the typical use of that vehicle by experience drivers. For example, during a training mode, if a parent typically exceeds speed limits by 5 MPH, uses the seatbelt for each drive, never does jackrabbit starts, and tends to brake hard in stops, then those parameters will be applied to a teen driver in the monitoring mode. For example, the vehicle monitoring system may set a first speeding threshold at 5 MPH above posted speed limits. If the teen driver operates the vehicle in the same manner as the parent, few or no mentoring messages would be broadcast to the teen driver. However, if the teen driver does not use a seatbelt and tends to do jackrabbit starts, then those events will trigger mentoring messages or warnings from the vehicle monitoring system.

**[0052]** When the training mode is completed, and the vehicle monitoring system has created a profile of acceptable driving parameters, those parameters are stored in memory in the monitoring device. The acceptable driving parameters may be reviewed by the experienced driver, such as via a display on the vehicle monitoring system. The acceptable driving parameters may also be sent to central server 109 or other computer for review by the experienced driver or others, such as via terminal 111. The parameters and thresholds observed during the training mode may be reviewed at any time during the training period or after the training is completed. The parent, supervisor or experienced driver accept all of the parameters and thresholds established during the training period for use during the monitoring mode, or those parameters and thresholds may be used as initial values that can be further adjusted for use in the monitoring mode. For example, a parent reviewing his driving parameters captured during training period may determine that certain features of his driving

should not be emulated, such as excessive speeding violations or failure to use seatbelts. The parent may adjust the thresholds for these elements to require more strict compliance by the teen driver in the monitoring mode.

**[0053]** Figure 5 illustrates a process for creating an acceptable driving profile. In step 501, a vehicle monitoring system is installed and the training mode is started. In step 502, the vehicle is operated by a parent, driving instructor or other experienced driver in the training mode during a training period. In step 503, the vehicle monitoring system observes all or selected vehicle parameters during the training period. The observed parameters may be all of the parameters measurable by the monitoring system or a default subset of those parameters, or a user may select specific parameters to be observed. In step 504, the vehicle monitoring system creates an acceptable driving profile based upon the observed parameters. The parent or experienced driver may review the acceptable driving profile parameters and thresholds in step 505. The parent, experienced driver or other authority may change the selection of parameters to be observed during the training period. The thresholds generated by the vehicle monitoring system during the training mode may also be adjusted, if, for example, those thresholds are too strict or lenient. In step 506, the training mode ends and a profile representing acceptable driving behavior is selected. The monitoring mode is started in step 507, and from that point on, in step 508, the monitoring device provides mentoring and warning messages to the driver based upon selected acceptable driving profile.

**[0054]** In one embodiment, the vehicle monitoring system does not immediately apply the thresholds set in the training mode. Instead, when the monitoring mode starts, the vehicle monitoring device sets the mentoring and warning thresholds at values 30%, for example, above those set during the training mode. Then after some period of time, such as after one week, the thresholds are moved to 20%, for example, of the training mode values. This stair-step approach would allow the driver in the training mode to improve his or her performance over time without having to be "perfect" or having to meet the training mode criteria immediately. Ultimately, the vehicle monitoring system may set the thresholds to the values established during a training mode, or the monitoring mode thresholds may always remain at some value above the training mode, such as 5-10% higher than what was observed during the training mode.

## REFERENCES CITED IN THE DESCRIPTION

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### Patent documents cited in the description

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## Patentkrav

1. Fremgangsmåde til tilvejebringelse af feedback til førere, der omfatter:

- 5 at overvåge (305) udvalgte køretøjsparametre, medens et køretøj (101) køres, hvor de udvalgte køretøjsparametre omfatter acceleration af et køretøj i den laterale, langsgående og vertikale retning;
- at måle accelerationen af køretøjet i den laterale, langsgående  
10 og vertikale retning over et forudbestemt tidsrum;
- at bestemme en tyngdekraftretning og en retning for køretøjsbevægelse;
- at filtrere tyngdekraftvirkninger ud fra accelerationsmålingerne, når køretøjet befinder sig på en  
15 hældning eller ændrer sin vandrette overfladeorientering;
- at detektere (306) en manglende overholdelse af køretøjsdriften ved anvendelse af de udvalgte køretøjsparametre; og
- at informere (307) føreren om en manglende overholdelse af køretøjsdriften.

20

2. Fremgangsmåde ifølge krav 1, der yderligere omfatter: hvis en manglende overholdelse af køretøjsdriften ikke er blevet rettet inden for et tidsrum, så sendes (308) der en overtrædelsesrapport til en tredjepart.

25

3. Fremgangsmåde ifølge krav 1, der yderligere omfatter: hvis en manglende overholdelse af køretøjsdriften ikke er blevet rettet inden for et tidsrum, så sendes der en overtrædelsesrapport til en central server (109).

30

4. Fremgangsmåde ifølge krav 1, der yderligere omfatter: hvis en manglende overholdelse af køretøjsdriften ikke er blevet rettet inden for et tidsrum, så yderligere information til føreren.

35

5. Fremgangsmåde ifølge krav 1, hvor overvågning af udvalgte køretøjsparametre yderligere omfatter: at overvåge køretøjsparameterdata fra et indbygget

køretøjsdiagnostisk system (102).

6. Fremgangsmåde ifølge krav 1, hvor at informere føreren om en køretøjsovertrædelse indbefatter at initiere en hørbar  
5 advarsel.

7. Fremgangsmåde ifølge krav 6, hvor at informere føreren om en køretøjsovertrædelse indbefatter afspilning af en mundtlig  
10 besked.

8. Fremgangsmåde ifølge krav 1, hvor at informere føreren om en køretøjsovertrædelse indbefatter at initiere en visuel  
advarsel.

15 9. Fremgangsmåde ifølge krav 8, hvor at informere føreren om en køretøjsovertrædelse indbefatter at initiere en tekstbesked.

10. Fremgangsmåde ifølge krav 1, hvor de udvalgte køretøjsparametre yderligere omfatter en køretøjshastighed.

20 11. Fremgangsmåde ifølge krav 1, hvor de udvalgte køretøjsparametre yderligere omfatter om køretøjets sikkerhedssele er i anvendelse.

25 12. Køretøjsovervågningssystem til tilvejebringelse af et feedback til en fører, mens køretøjet betjenes (102, 103, 104, 105, 106, 107, 108, 109, 110, 111, 201, 202, 203), der omfatter: en køretøjsinformationsgrænseflade (102);

30 en output grænseflade;  
en overvågningsanordning, der overvåger en eller flere køretøjsdriftsparametre;

et accelerometermodul, der indbefatter i det mindste et accelerometer til at måle accelerationen i de laterale, langsgående og vertikale retninger; og:

35 en processor (103, 104), der er i forbindelse med køretøjsinformationsgrænsefladen og output grænsefladen, hvor processoren er konfigureret til at modtage data, der er baseret på den ene eller de flere overvågede driftsparametre og

de målte accelerationer over et forudbestemt tidsrum, og kan betjenes til:

at bestemme en tyngdekraftretning og en retning for køretøjsbevægelse, der er baseret på det overvågede ene eller  
5 de flere køretøjsdriftsparametre; og

at filtrere tyngdekraftvirkninger ud fra de langsgående, laterale og vertikale accelerationsmålinger, når køretøjet befinder sig på en hældning eller ændrer sin vandrette overfladeorientering;

10 at detektere en eller flere manglende overholdelser af køretøjsdriften ved at sammenligne køretøjsparametrene med en forudbestemt tærskelværdi; og

at alarmere føreren hvis den forudbestemte tærskelværdi overskrides ved anvendelse af output grænsefladen.

15

13. Køretøjsovervågningssystem ifølge krav 12, hvor køretøjsinformationsgrænsefladen indbefatter en eller flere af gruppen, der består af:

et indbygget diagnostisk system (102);

20 accelerometeret;

en geolokaliseringsanordning; og:

en dæktrykssensor.

14. Køretøjsovervågningssystem ifølge krav 12, hvor output grænsefladen muliggør output til en eller flere fra gruppen, der består af:

25 en audioudgangsanordning;

en videoudgangsanordning; og:

en haptisk udgangsanordning.

30

15. Køretøjsovervågningssystem ifølge krav 12, der yderligere omfatter en datakommunikationsgrænseflade (107), der er i forbindelse med processoren, hvor processoren er yderligere konfigureret til at overføre en alarm ved anvendelse af  
35 datakommunikationsgrænsefladen.

16. Køretøjsovervågningssystem ifølge krav 15, hvor processoren er konfigureret til at overføre en alarm ved anvendelse af

datakommunikationsgrænsefladen ved detektion af en eller flere manglende overholdelser af køretøjsdriften.

5 17. Køretøjsovervågningssystem ifølge krav 15, hvor processoren er konfigureret til at overføre en alarm ved anvendelse af datakommunikationsgrænsefladen ved detektion af en eller flere manglende overholdelser af køretøjsdriften, der forekommer i i det mindste et forudbestemt tidsrum.

# DRAWINGS

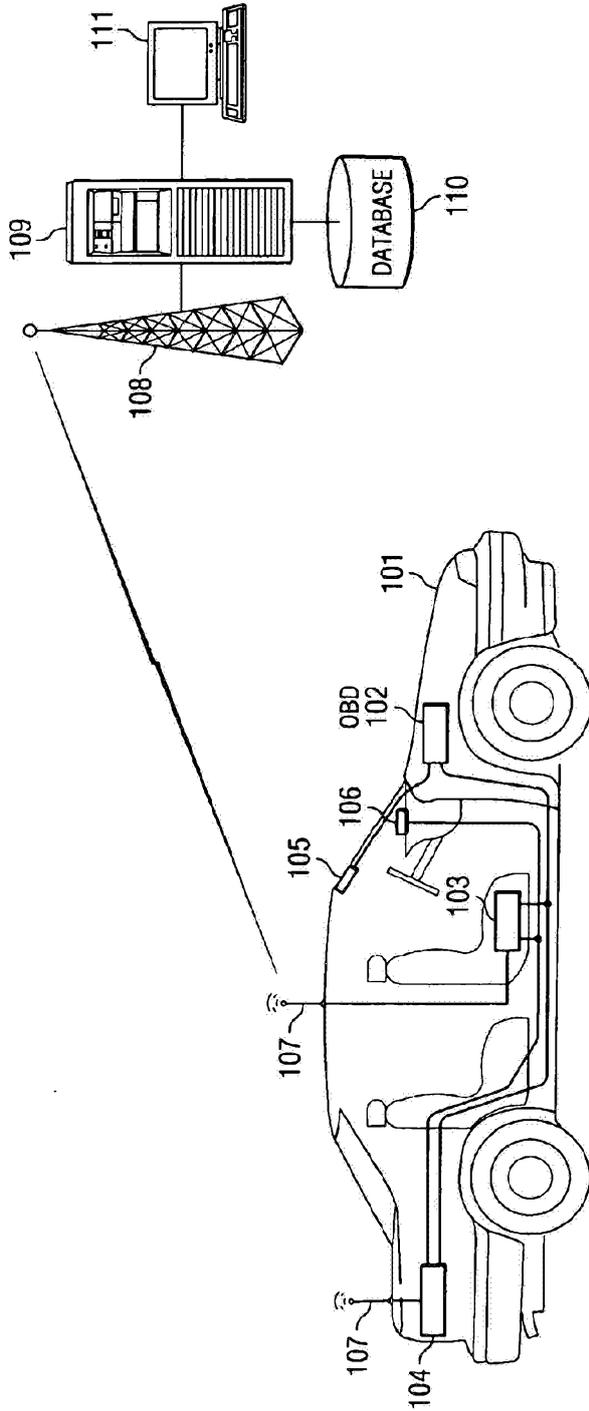


FIG. 1

FIG. 2

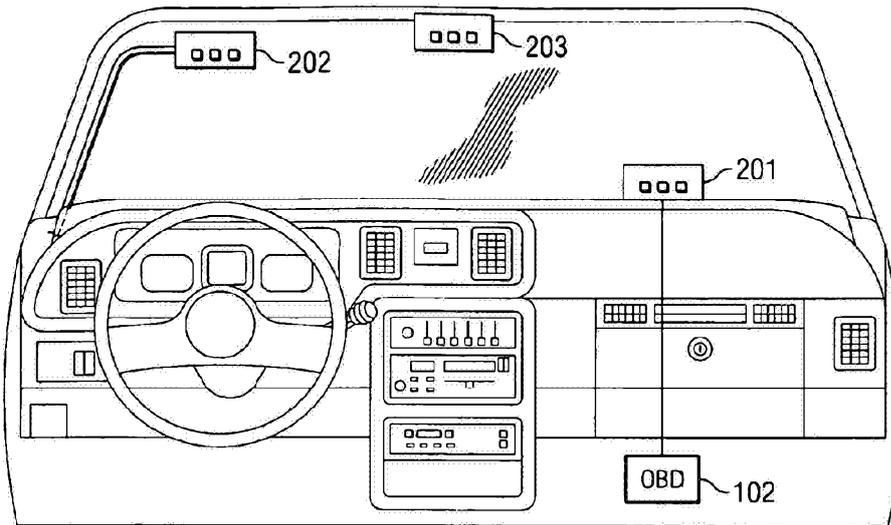
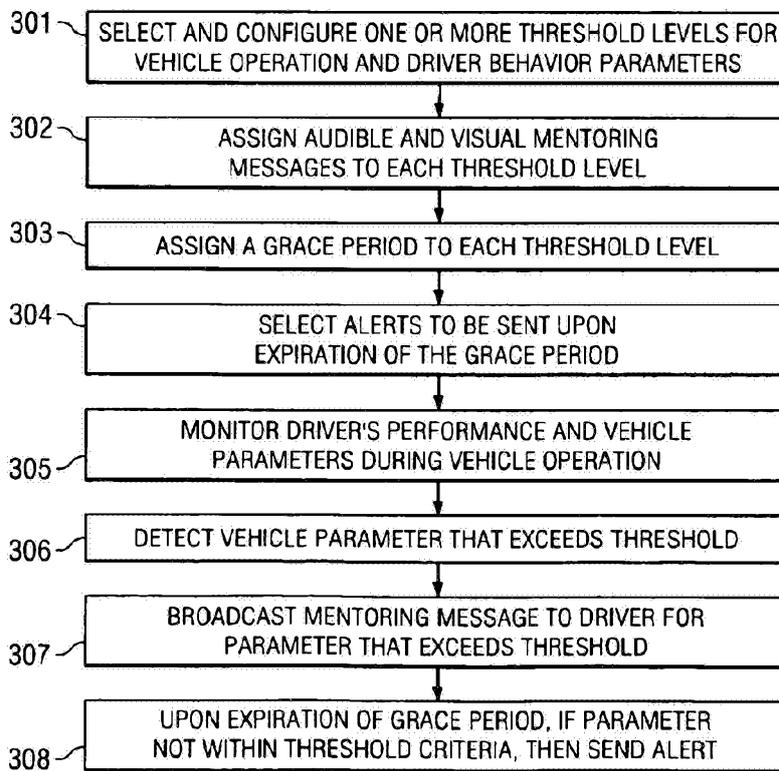


FIG. 3



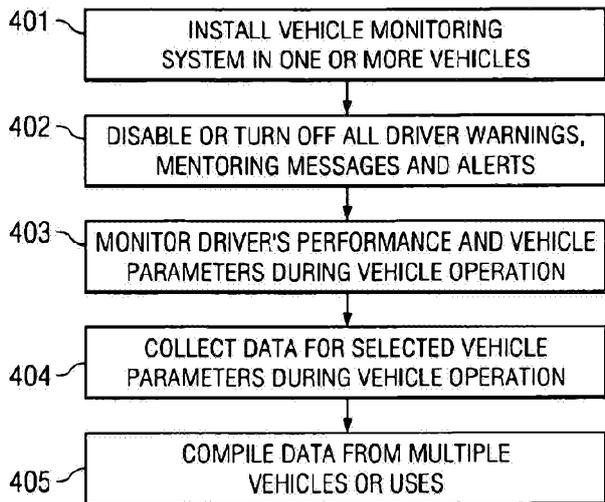


FIG. 4

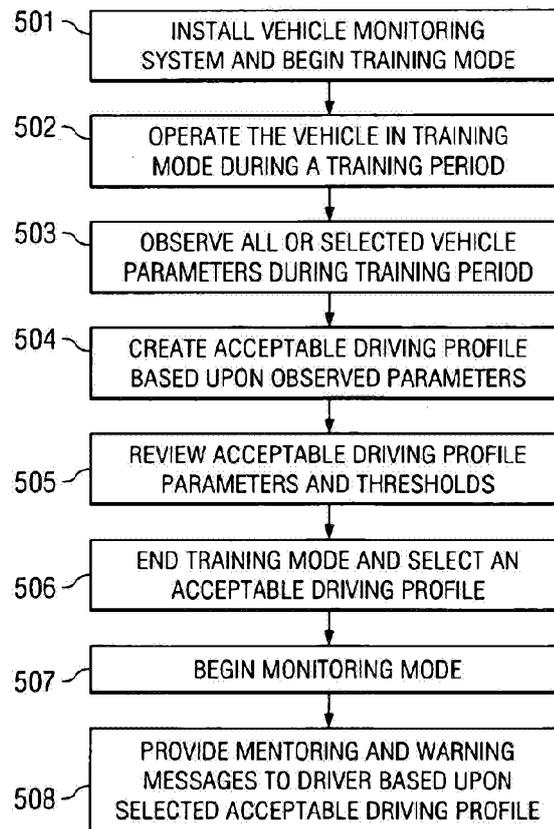


FIG. 5