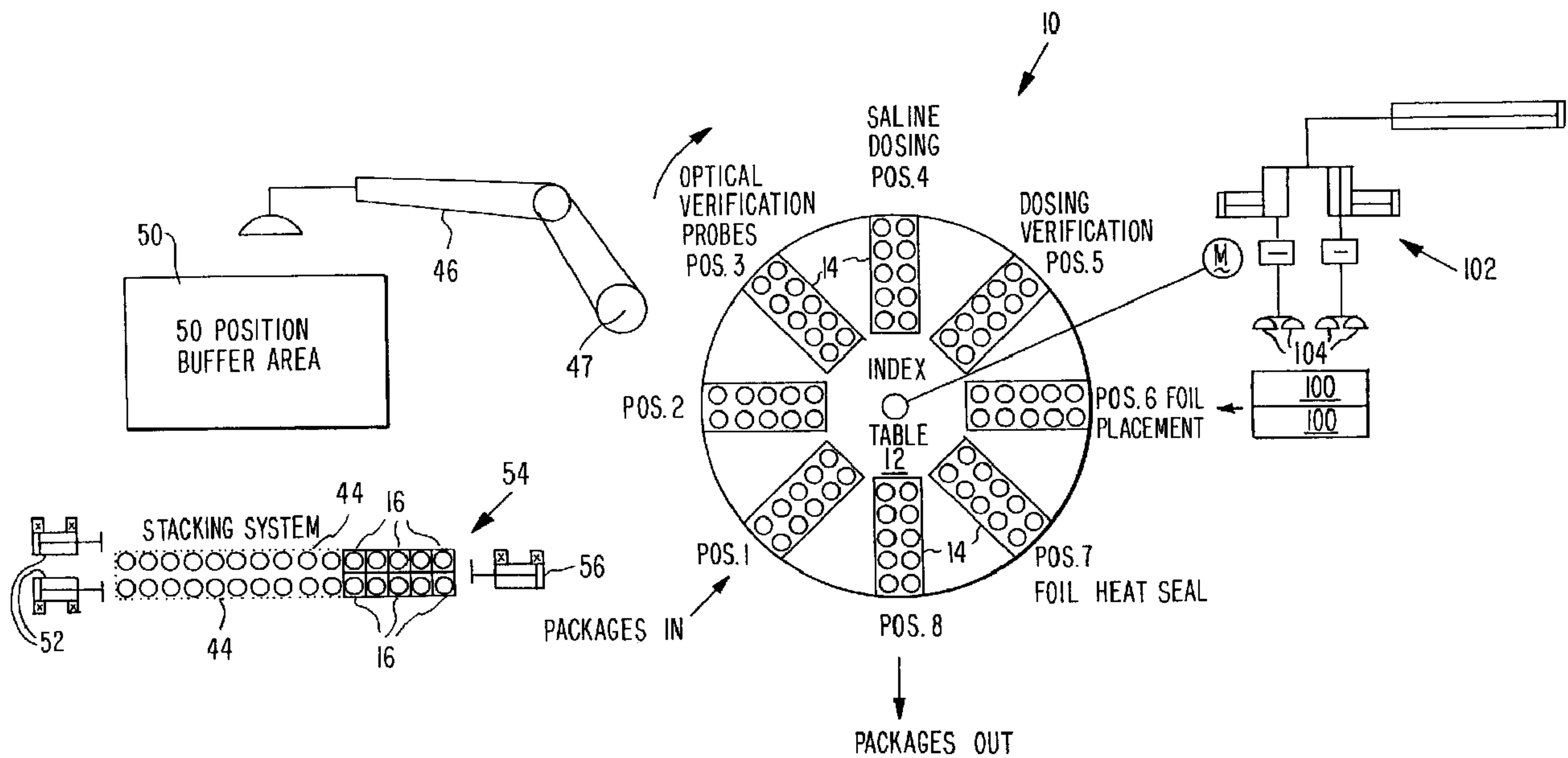




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 (54) Title: PACKAGING ARRANGEMENT



(57) **Abrégé/Abstract:**

A method and a packaging arrangement for packaging products, such as contact lenses, in packages such as blister pack. The arrangement has a movable support base having on its upper surface a plurality of substantially identical support pallets, spaced equally apart along the movable support base. Each of the pallets is particularly designed to support and align an array of individual package bases. The support base is sequentially moved through substantially equal incremental movements, with stops between each sequential movement, such that each support pallet with an array of individual package bases thereon is sequentially stopped at spaced stations in the packaging arrangement. At a first station, a loader loads an array of package bases in the support pallet then at the first station. At a subsequent foil placement station, a placer unit places a sheet of laminated covers over the array of package bases. At a still subsequent heat sealing station, a heated seal head heat seals the laminated covers to the package bases. At a subsequent unloading station, an unloader unloads the sealed packages from the packaging arrangement for subsequent processing.

ABSTRACT OF THE DISCLOSURE

A method and a packaging arrangement for packaging products, such as contact lenses, in packages such as blister pack. The arrangement has a movable support base having on its upper surface a plurality of substantially identical support pallets, spaced equally apart along the movable support base. Each of the pallets is particularly designed to support and align an array of individual package bases. The support base is sequentially moved through substantially equal incremental movements, with stops between each sequential movement, such that each support pallet with an array of individual package bases thereon is sequentially stopped at spaced stations in the packaging arrangement. At a first station, a loader loads an array of package bases in the support pallet then at the first station. At a subsequent foil placement station, a placer unit places a sheet of laminated covers over the array of package bases. At a still subsequent heat sealing station, a heated seal head heat seals the laminated covers to the package bases. At a subsequent unloading station, an unloader unloads the sealed packages from the packaging arrangement for subsequent processing.

PACKAGING ARRANGEMENT

Filed as a divisional patent application of Canadian patent application 2,151,345.

5

BACKGROUND OF THE INVENTION1. Field of the Invention

The present invention relates generally to a packaging arrangement for packaging products, such as contact lenses, in packages such as blister packs. More particularly, the subject invention pertains to a packaging arrangement having a movable support base, such as a rotary index table, defining on its upper surface a plurality of identical support pallets, equally spaced apart along the movable support base. Each support pallet is designed to support an array of individual package bases thereon, and is sequentially stopped at space positions in the packaging arrangement. At a first position, the packaging arrangement receives blister package bases, each having a product deposited therein, and places the package bases in the support pallet then at the first position. At subsequent positions, the packaging arrangement verifies the presence and alignment of each package base, deposits a fixed dosage of saline solution into each package base, optionally verifies that a fixed dosage of saline solution has been deposited in each package base, places a marked laminated cover over the package bases, heat seals the laminated cover to the package bases, and finally unloads the completed blister packs from the packaging arrangement, for subsequent processing such as sterilization and secondary packaging.

1           2. Discussion of the Prior Art

The prior art discloses the use of rotary index tables and also linear conveyor arrangements in packaging equipment, the packaging of contact lens in 5 saline solution, and the checking of various packages by a variety of optical probes. Moreover, the prior art also discloses heat sealing lids or covers to container bases, but in the prior art methods of heat sealing, the temperature of the sealing heads are generally 10 maintained at lower temperatures, and the sealing heads are generally applied for longer periods of time as compared with the present invention. In one prior art approach, a pneumatic cylinder presses a heated sealing head against the covers being applied to package bases 15 on a rotary index table, and a microswitch measures when the pneumatic cylinder is at the end of its power stroke, which starts a measured heater timing period. This approach is very inaccurate as the tolerances of all of the components, including the rotary index table, 20 the pneumatic cylinder, and the height of the package and foil in the pallet creates timing problems.

Rather than detecting a particular physical position of the pneumatic press as in the prior art, the present invention measures the force applied by a 25 pneumatic cylinder, and activates a timer when the measured force reaches a threshold force, which is approximately 75% of the maximum force generated by the pneumatic cylinder. Moreover, the present invention positions a support below the rotary index table to

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1 ensure that deflections under the pneumatic press are  
minimized.

SUMMARY OF THE INVENTION

Accordingly, it is a primary object of the  
5 present invention to provide a packaging arrangement for  
packaging products, such as contact lenses, in packages  
such as blister packs.

A further object of the subject invention is  
the provision of a packaging arrangement having a  
10 movable support base, such as a rotary index table,  
defining on its upper surface a plurality of identical  
support pallets, equally spaced apart along the movable  
support base. Each support pallet is designed to  
support an array of individual blister package bases  
15 thereon, and is sequentially rotated to stop at spaced  
positions in the lens packaging arrangement, at which a  
sequence of packaging operations are performed thereon.

In accordance with the teachings herein, the  
present invention provides a packaging arrangement for  
20 packaging products such as contact lenses in packages  
such as blister packs. The packaging arrangement  
includes a movable support base having on its upper  
surface a plurality of identical support pallets,  
equally spaced apart along the movable support base.  
25 Each support pallet is particularly designed to support  
and align an array of individual package bases. The  
movable support base is sequentially moved through  
substantially equal increments, with stops between each  
sequential movement. The arrangement is such that each  
30 support pallet with an array of individual package bases

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1 thereon is sequentially stopped at a plurality of spaced  
stations in the packaging arrangement. At a first  
station, a robotic handling arm loads an array of  
package bases into a support pallet then at the first  
5 station. At a subsequent verification station, probes  
verify the presence and alignment of each package base  
in the support pallet. At a subsequent saline dosing  
station, dosers deposit a given dosage of saline  
solution in each package base. At a subsequent foil  
10 placement station, a pick and place unit places a pair  
of sheets of laminated covers over the array of package  
bases. At a subsequent heat sealing station, a heated  
seal head heat seals the laminated covers to the package  
bases. Finally, at an unloading station, an unloader  
15 arm unloads the sealed packages from the packaging  
arrangement for subsequent processing.

In greater detail, at the first station, the  
packaging arrangement receives individual blister  
package bases, each of which has a contact lens therein,  
20 and the packaging arrangement packages the contact  
lenses into blister packs.

In a preferred embodiment, the movable support  
base comprises a rotary index table having on its upper  
surface eight identical, radially-spaced support  
25 pallets, positioned 45° apart around the table, each of  
which is particularly designed to support an array of  
2x5 package bases.

The packaging arrangement receives individual  
package bases, each of which has a product therein,  
30 which are lined up and queued for packaging on side by

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1 side accumulator rails. The package bases are precisely positioned on the side by side accumulator rails such that a robotic handling arm, having an array of vacuum handling cups, one for each individual package base, can  
5 pick up an array of package bases from the accumulator rails and deposit them onto a support pallet at the first station on the movable support base. Also, when the packaging arrangement is temporarily not operating, the robotic handling arm also transfers package bases  
10 from the accumulator rails to a buffer area. After the package bases are deposited onto one end of the side by side accumulator rails, first and second pneumatic cylinders advance the package bases to the second opposite end of the accumulator rails. A third  
15 pneumatic cylinder at the second end of the accumulator rails then pushes the package bases back slightly towards the first end to precisely position the package bases at the second end of the accumulator rails to allow the robotic handling arm to pick up an array of  
20 package bases.

The support pallet spaces the side of each package base a nominal distance, in a range of 200 to 400  $\mu$ meters, from the side of each adjacent package base in the support pallet, to prevent overlapping sides of  
25 adjacent product bases. The side by side accumulator rails accumulate package bases in positions in which package bases directly touch adjacent package bases. To compensate for the slight difference from the nominal distance between adjacent package bases in the pallet,  
30 the robotic arm, after positioning an array of package

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1 bases over a pallet, releases the vacuum in each vacuum  
cup to allow the package bases to fall into the support  
pallet. The robotic arm then raises and lowers the  
array of suction cups slightly to tap each package base  
5 into a properly aligned position in the support pallet.  
Each package base includes a rounded product cavity and  
alignment notches on opposite sides thereof. The  
support pallet defines a rounded cavity for receiving  
each product cavity of each package base and alignment  
10 rods which fit into the alignment notches on the package  
base.

At the verification station, probes verify the  
presence of each package base in the array of package  
bases supported by the pallet. The verifying probes  
15 include an array of fiber optic probes positioned above  
the array of package bases, with each fiber optic probe  
illuminating a package base, and then detecting  
radiation reflected therefrom to verify the presence of  
a package base in the support pallet. In greater  
20 detail, each fiber optic probe comprises a dual optical  
fiber arrangement in which one optical fiber carries  
light to illuminate the package base, and a second  
optical fiber carries light reflected from the package  
base to a photodetector. Moreover, at least one  
25 alignment probe verifies the alignment of the packaging  
bases in the support pallet to check that no package  
bases are skewed or tilted in the support pallet. Each  
alignment probe includes a through-beam detector which  
directs a beam of light along the length of and just  
30 above a column of package bases supported in the pallet



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1 to a detector at the other end of the column, such that a package base which is skewed or tilted in the pallet interrupts the through beam, and the photodetector at the other end of the through beam so indicates.

5 At the saline dosing station, a pivotable arm supports an array of dosing tubes, each of which is supplied by a separate dosing pump to deposit a precise dosage of saline solution into each package base, such that each contact lens is immersed in saline solution.

10 A pump cart is positioned adjacent to the saline dosing station and mounts thereon the dosing pumps and a reservoir of saline solution for the dosing pumps. Periodically, the support arm is rotated to one side to position the dosing tubes over a collection pan, and the

15 reservoir in the pump cart is refilled. Each pump is cycled several times, with the discharge from the dosing tubes being collected in the collection pan, to compensate for evaporation of saline solution and to ensure that the proper dosage amount is provided.

20 Moreover, optionally after the saline dosing station, at a subsequent dosing verification station, an array of sensors verifies that a given dosage (level of solution) of saline solution has been deposited into each package base.

25 At the foil placement station, a foil pick and place unit, having an array of suction cups, lifts and places a pair of sheets of laminated covers over the array of package bases.

30 At the heat sealing station, an electrically heated seal head is pressed by a pneumatic cylinder

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1 against the laminated covers on the package bases. A  
thermal transducer measures the temperature of the seal  
head to maintain the temperature in a range from  
210-265°C. An in-line load cell measures the force  
5 generated by the pneumatic cylinder, and when a  
predetermined force is reached, which is a percentage of  
a possible maximum force, a timer is initiated. The  
timer times a relatively short time period of  
approximately 0.4 to 1.4 seconds, after which the  
10 pressure in the pneumatic cylinder is released, thereby  
forming a seal between each laminated cover and package  
base which is both detachable and consumer friendly.  
The predetermined force is a given percentage, e.g.,  
60-75%, of a maximum force that the pneumatic cylinder  
15 is capable of generating.

The rotary index table must be maintained in a  
substantially level position for the operations  
performed thereon, and is reinforced under the heat  
sealing station to withstand the forces imparted thereto  
20 by the pneumatic sealing cylinder. The reinforcement is  
provided by a block of durable plastic material, such as  
a Teflon® type of plastic, placed on top of a support  
positioned beneath the rotary index table at the  
pneumatic cylinder. The support block is in constant  
25 contact with the bottom of the rotary index table to  
ensure that the deflection of the rotary index table by  
the pneumatic cylinder is minimal. Alternatively, a  
pneumatically actuated movable support can be positioned  
in contact with the bottom of the rotary index table  
30 prior to actuation of the pneumatic cylinder driving the

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1 heated seal head, and be removed from contact with the  
bottom of the rotary index table subsequent to actuation  
of the pneumatic cylinder.

At the unloading station, a pneumatically  
5 driven handling arm, having a vacuum suction cup for  
each individual package, lifts the array of packages  
from the support pallet, and deposits the array of  
packages at an output position. The handling arm  
incorporates thereon a precision sensor plate having a  
10 plurality of photoelectric sensors which examine the  
outer edges of each sheet of laminated covers on the  
array of packages to determine if a sheet of laminated  
covers is skewed relative to the array of packages. The  
photoelectric sensors are preferably positioned at the  
15 corners of the expected position of the sheet of  
laminated covers on the array.

The present invention also provides a method  
of heat sealing a laminated top cover to a plurality of  
individual package bases to create a sealed package with  
20 a seal which is durable, to survive subsequent packaging  
operations such as sterilization, and yet consumer  
friendly in that a consumer can easily separate and open  
the sealed package. Pursuant to the method, a laminated  
sealing cover is placed over an array of individual,  
25 unconnected package bases. A seal head is heated to  
maintain the temperature thereof in a range from 210-  
265°C, and the heated seal head is pressed by a  
pneumatic cylinder against the laminated covers on the  
package bases. In greater detail, the force generated  
30 by the pneumatic cylinder is measured by an in-line load

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cell, and a timer is initiated when a predetermined force is reached. The timer times a given period of time, which may be a relatively short time period of approximately 0.4 to 1.4 seconds, after which the pressure in the pneumatic cylinder is released, thereby forming a seal between each laminated cover and package base which is both detachable and consumer friendly. The array of individual package bases is supported in a pallet, wherein the support pallet spaces the side of each package base a nominal distance, in the range of 200 to 400  $\mu$ meters, from the side of each adjacent package base in the support pallet, to prevent overlapping sides of adjacent product bases, and to provide for each separation of individual packages. Each package base is provided with a rounded product cavity and alignment notches on opposite sides thereof, and the support pallet is provided with a rounded cavity for receiving each product cavity of each package base and alignment rods which fit into the alignment notches on each package base.

20

The present invention provides a packaging arrangement for packaging products, comprising:

a. a movable support base having on its upper surface a plurality of substantially identical support pallets, spaced equally apart along the movable support base, each of which is particularly designed to support and align an array of individual package bases;

b. means for sequentially moving the support base through substantially equal incremental

30

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movements, with stops between each sequential movement, such that each support pallet with an array of individual package bases thereon is sequentially stopped at spaced stations in the packaging arrangement;

5 c. at a first station, a loader loads an array of package bases in the support pallet then at the first station;

10 d. at a subsequent foil placement station, a placer unit places a sheet of laminated covers over the array of package bases;

e. at a subsequent heat sealing station, a heated seal head heat seals the laminated covers to the package bases; and

15 f. at a subsequent unloading station, an unloader unloads the sealed packages from the packaging arrangement for subsequent processing.

The present invention also provides a method of  
20 packaging in which an array of individual, unconnected package bases is placed in a support pallet by a robotic handling arm, having a suction cup for each package base. The support pallet spaces the side of each package base a nominal distance, in the range of 200 to 400  $\mu$ meters, from  
25 the side of each adjacent package base in the support pallet, to prevent overlapping sides of adjacent product bases, and to provide for easy separation of individual packages. A sheet of laminated top covers is placed over the array

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1 of individual package base, and the laminated top covers  
are sealed to the array of individual package bases. In  
greater detail, the package bases are initially in  
positions in which they directly touch adjacent package  
5 bases. To compensate for the slight difference in  
spacing from the nominal distance between adjacent  
package bases in the support pallet, the robotic arm,  
after positioning an array of package bases over a  
pallet, releases the vacuum in each vacuum cup to allow  
10 the package bases to fall into the support pallet. The  
robotic arm then raises and lowers the array of suction  
cups slightly to tap each package base into a properly  
aligned position in the support pallet.

BRIEF DESCRIPTION OF THE DRAWINGS

15           The foregoing objects and advantages of the  
present invention for a packaging arrangement may be  
more readily understood by one skilled in the art with  
reference being had to the following detailed  
description of several preferred embodiments thereof,  
20 taken in conjunction with the accompanying drawings  
wherein like elements are designated by identical  
reference numerals throughout the several views, and in  
which:

          Figure 1 is a schematic top plan view of a  
25 rotary packaging arrangement constructed pursuant to the  
teachings of the present invention;

          Figure 2 is a top plan view, similar to Figure  
1, of one designed embodiment of a rotary packaging  
arrangement constructed pursuant to the teachings of the  
30 subject invention;

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1           Figure 3 is a front elevational view of the  
designed embodiment of a rotary packaging arrangement  
illustrated in Figure 2;

          Figure 4 is a left elevational view of the  
5 designed embodiment of Figures 2 and 3;

          Figure 5 is a top plan view of one support  
pallet for supporting a 2x5 array of package bases on  
the rotary index table of the rotary packaging  
arrangement;

10           Figure 6 is a fragmentary end view of one half  
of the support pallet illustrated in Figure 5;

          Figures 7 and 8 are respectively perspective  
and top planar views of a representative blister package  
base;

15           Figure 9 is an elevational view of optical  
probes for verifying the presence of a packet base at  
each location in the 2x5 array, and also for checking  
the alignment of the packet bases in the 2x5 array to  
ensure that no packet bases are skewed or tilted in the  
20 support pallet;

          Figures 10 and 11 are respectively front and  
side elevational views of the heat sealing head and the  
pneumatic press therefor;

          Figures 12 and 13 are respectively a bottom  
25 plan view and a side elevational view of the heat  
sealing head and an electrical heater therefor;

          Figure 14 is an elevational view of the pick  
and place unit at the package unloading station; and

30

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1           Figure 15 is a plan view of the sensor mounting arrangement for a skew foil detector mounted in the pick and place unit of Figure 14.

DETAILED DESCRIPTION OF THE DRAWINGS

5           Referring to the drawings in detail, Figure 1 is a schematic plan view of a packaging arrangement 10 constructed pursuant to the teachings of the present invention, for packaging products, such as contact lenses, into packages such as blister packs. The 10 packaging arrangement is illustrated as a rotary packaging machine having a plurality of radially spaced stations therearound. However, linear packaging arrangements having linear conveyor lines with linearly spaced stations therealong are also contemplated in 15 alternative embodiments of the present invention.

The rotary packaging station 10 includes a rotary index table 12 which has on its upper surface eight identical, radially-oriented support pallets 14, positioned 45° apart around the table, each of which is 20 particularly designed to support an array of individual blister pack bases 16. Each support pallet 14 with an array of individual blister pack bases thereon is sequentially rotated to stop at eight angularly spaced radial positions in the lens packaging machine, 25 illustrated in Figure 1 as POS.1 through POS.8.

Each blister package base 16, as represented in further detail in Figures 6, 7 and 8 of the drawings, includes a planar, essentially rectangularly shaped flange 18 having an integral angularly depending wall 30 portion 20 at one end thereof. A cavity 24 is formed



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offset towards an opposite edge 22 of the flange 18, which is of an essentially semispherical configuration, generally in conformance with the curvilinear shape of a contact lens 26, Figure 8, adapted to be stored therein in a sealed  
5 condition while immersed in a suitable sterile aqueous solution. The height of the angled wall portion 20 depending from the planar flange 18 is somewhat analogous to the height or depth of the cavity 24 containing the contact lens, as can be ascertained more clearly from  
10 Figures. 6 and 7 of the drawings. Each package base further includes depending legs 28 at each corner of side 22, opposite to the side with depending wall portion 20, and alignment notches 30 on opposite sides of the planar flange 18. Each support pallet 14 defines a rounded cavity 32 for  
15 receiving each product cavity 24 of each package base, alignment rods 34 which fit into the alignment notches 30 and insets 36 which receive the depending legs 28 of adjacent package bases 26, as illustrated best in Figure 5.

Each blister pack base 16 may be a shaped  
20 injection-molded plastic structure, which may be constituted of polypropylene, of generally rigid or semi-rigid configuration. A lid is adapted to be secured or bonded, such as by heat sealing to the flange 18 surfaces around the product-receiving cavity. Each lid may comprise  
25 a multi-layered foil laminate, as disclosed in U.S. Patent No. 5,653,844. The metallic foil laminate preferably includes a polypropylene bottom layer which is adapted to be bonded to contiguous

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1 sealing surfaces on the injection-molded shaped plastic  
package base, as by heat sealing or the like, to form a  
complete packaging structure as is well known in the  
packaging technology. A "blister package" of this type  
5 is disclosed, for example, in U.S. Patent 4,691,820,  
commonly assigned to the assignee of this application.  
Through the intermediary of thermal transfer printing,  
appropriately variable and changeable printed data are  
imparted to an exterior surface of the foil laminate.  
10 When the laminate is severed into lid-forming labels for  
respective packages, the data may consist of suitable  
changeable lot numbers, expiration dates, and other  
physical data representative of the specific product  
housed in the package, for instance, data with regard to  
15 the power of a contact lens which is packaged in a  
cavity of the blister pack while immersed in a suitable  
protective sterilized saline solution.

Referring to Figure 1, at a first radial  
position designated POS 1, the rotary packaging station  
20 receives blister package bases 16, each having a contact  
lens 26 deposited therein, and places the package bases  
in the support pallet 14 then at the first position.

The lens packaging station receives individual  
blister package bases, each of which has a contact lens  
25 therein, which are lined up and queued for packaging on  
two side by side accumulator rails 44. In order to  
successfully accumulate the package bases on the  
accumulator rails, the packages are held down by a  
vacuum supplied by a vacuum pump with a pressure down to  
30 300 mbar. The blister pack bases are initially

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1 deposited onto the left end of the side by side  
accumulator rails 44 by a further good/bad robotic arm,  
not illustrated. The package bases are precisely  
positioned on the accumulator rails 44 such that a  
5 robotic handling arm 46, having a 2x5 array of vacuum  
handling cups 48, one for each individual blister pack  
base, can pick up a 2x5 array of individual blister pack  
bases 16 and load the blister pack bases onto a pallet  
14 on the rotary packaging machine. Each pallet 14 is  
10 particularly designed to support and align the 2x5 array  
of blister packs, as described in greater detail  
hereinabove. Also, when the rotary packaging station 10  
is temporarily shut down, as for changing foil rolls in  
an adjacent foil machine, the robotic handling arm 46  
15 also transfers package bases 16 from the accumulator  
rails 44 to a buffer area 50. After the package bases  
are deposited onto one end of the side by side  
accumulator rails 44, two pneumatic cylinders 52 advance  
the package bases 16 to the second opposite end 54 of  
20 the accumulator rails. A third pneumatic cylinder 56 at  
the second end of the accumulator rails then pushes the  
package bases back slightly to the left to precisely  
position the package bases at the second end of the  
accumulator rails to allow the robotic handling arm 46  
25 to pick up an array of package bases.

Each support pallet 14 has a unique design  
relative to prior art support pallets, in that the  
package bases are nominally positioned in the support  
pallet with a greater separation, in the range of 200 to  
30 400  $\mu$ meters, between the shoulders of adjacent package

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1 bases, with the separation being provided to prevent a  
"shingling" effect in which a shoulder of one package  
base overlies a shoulder of an adjacent package base.  
The greater separation also aids in subsequent  
5 separation of the resultant adjacent blister packs. The  
support pallet 14 spaces the side of each package base  
16 a nominal distance, in the range of 200 to 400  
µmeters, from the side of each adjacent package base in  
the support pallet, to prevent overlapping edges of  
10 adjacent product bases. However, the side by side  
accumulator rails 44 accumulate package bases 16 in  
positions in which package bases directly touch adjacent  
package bases 16, as illustrated in Figure 1. To  
compensate for the slight difference from the nominal  
15 distance between adjacent package bases in the pallet,  
the robotic arm 46, after positioning an array of  
package bases over a pallet 14, initially releases the  
vacuum in each vacuum cup 48 to allow the package bases  
to fall into the support pallet 14. The robotic arm 46  
20 then raises and lowers the array of suction cups 48  
slightly to tap each package base 16 into a properly  
aligned position in the support pallet 14, as provided  
for by the rounded product cavity aligning with respect  
to the cavity 32, the alignment notches 30 aligning with  
25 respect to the alignment rods 34, and the legs 28  
aligning with respect to the inserts 36.

The rotary index table is then sequentially  
rotated through the successive angular positions,  
stopping for approximately 10 seconds at each radial  
30 station, such that all the operations as described

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1 herein can be performed simultaneously at the successive  
radial stations. At the second angular position, a  
vacuum is applied beneath each cavity 32 in the support  
pallet 14 to ensure that each package base 16 is  
5 properly positioned therein.

At the third angular position, a 2x5 array of  
fiber optic probes 60, Figures 2 and 9, are positioned  
above the 2x5 array of package bases to verify the  
presence of each package base in the array of package  
10 bases supported by the pallet. Each fiber optic probe  
60 is positioned centrally over the open flange 18 area  
illustrated on the right side of Figure 8 of each  
blister package base 16, and the fiber optic probe 60  
illuminates each package base 16, and then detects the  
15 radiation reflected therefrom to verify the presence of  
each blister pack base 16. The fiber optic probes 60  
can be of a type available commercially from Keyence,  
model FU-35f, utilized with an amplifier 62, model  
FS2-60. Each such fiber optic detector probe 60  
20 comprises a dual optical fiber arrangement in which one  
optical fiber carries light to illuminate the flange 18  
of each package base 16 and a second optical fiber  
carries light reflected from the package base to a  
photodetector. Each fiber optic probe 60 is positioned  
25 in a support plate 64 which is pivotally supported on a  
column 66, such that the support plate 64 may be placed  
in an operative position as illustrated in Figures 2 and  
9, or pivoted to a position not over the rotary index  
table 12. The amplifiers 62 can be mounted on the  
30 column 68 as illustrated in Figure 9.

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1 An alignment check is also made at the third  
angular position to check that no package bases 16 are  
skewed or tilted in the support pallet 14. The  
alignment check is performed by two through-beam  
5 detectors, as are available commercially from Keyence,  
each of which includes a light source 70, Figure 9,  
which directs a beam of light along the length of and  
just above a 1x5 column of package bases 16 supported in  
the pallet 14 to a detector 72 at the other end of the  
10 column. If a package base 16 is skewed or tilted in the  
pallet 14, it will interrupt the through beam, and the  
photodetector 72 at the other end of the through beam  
will so indicate.

At the fourth angular position, referring to  
15 Figures 2, 3 and 4, a pivotable arm 74, pivotally  
supported by a column 76, supports a plate 78 which  
holds a 2x5 array of dosing tubes 80, each of which is  
supplied by a separate dosing pump 82. Each dosing tube  
80 deposits a precise dosage of saline solution into the  
20 cavity 24 in each blister pack base 16, such that each  
contact lens 26 is completely immersed in saline  
solution. The rate of pumping of saline solution and  
the diameter of each dosing tube 80 is chosen such that  
no saline solution splashes from any of the cavities of  
25 any of the blister packs, which is very important as any  
saline solution splashed onto any sealing flange 18  
surfaces would interfere with subsequent sealing and  
packaging operations.

Periodically, such as every four minutes, the  
30 pivotal arm 74 carrying the array of dosing tubes 80

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1 swings away and a reservoir 82, shown schematically with  
dosing pumps 82 in Figure 2, is resupplied with saline  
dosing solution. The diameter of each dosing tube 80,  
Figure 4, and the pumping rate therethrough have been  
5 determined empirically, with the internal diameter of  
each dosing tube 80 being approximately 1/8 inch, and  
the pumps 84 being positive displacement 3/8 or 1/2 inch  
diameter piston metering pumps, as are available from  
Oyster Bay Pump Works. The amount of saline solution  
10 pumped into each package base is 950  $\mu$ liters  $\pm$  50  
 $\mu$ liters.

The reservoir 82 of saline solution for all  
ten pumps and the ten pumps 84 are mounted on a pump  
cart 86 which is normally positioned adjacent to the  
15 position 4 station, and the pumps 84 are connected to  
the dosing tubes 80 by a plurality of ten flexible  
plastic tubes 88. Saline solution is available in the  
plumbing of the building in which the rotary packaging  
station is located to refill the reservoir. After  
20 approximately every four minutes of inactivity, the  
support arm 74 is manually rotated to one side to  
position the dosing tubes 80 over a collection pan 90 in  
the rotary packaging station, and each pump 84 is cycled  
a number (e.g., five) of times, with the discharge from  
25 the tubes being collected in the collection pan 90. The  
five cycles prime each pump to compensate for  
evaporation of saline solution and to ensure that the  
proper dosage amount is provided. The frequency at  
which the pumps are primed depends to an extent upon the

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particular industrial environment and temperature in which the rotary packaging station is located.

At the fifth angular position, referring to Figures. 2 and 3, the presence of a measured dose (given level) of saline solution in each blister pack base is verified by a 2x5 array of liquid level detectors 92 positioned above the 2x5 array of blister pack bases. The detectors 92 are supported by a plate 94 which is pivotally supported on a column 96, such that the plate 94 and detectors 96 can be pivoted to a position not over the rotating index table 112. Each detector can be a reflective sensor as is commercially available from Omron, or could be an ultrasonic detector, or could be a proximity sensor or could be a fiber optic probe, as commercially available from Keyence as model 24W-V25R used with a amplifier model 24W-AA1C. Each detector checks and verifies for a proper height of saline solution in each blister pack base. The verification of a measured dosage of saline solution at the fifth angular position can be considered to be optional, particularly if the reliability of the dosing equipment at the fourth angular position is high.

At the sixth angular position, a pair of laminar top sheets 100, Figure 1, is placed over the 2x5 array of package bases. Each laminar top sheet covers a 1x5 column of bases, and has printed thereon all identification indicia required for the final package. The laminar top sheet is prepared pursuant to the disclosure of U.S. Patent No. 5,653,844. The laminar top



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1 sheet is produced by a labeling machine which extends to the right of the rotary packaging machine as illustrated in Figures 1 and 2. The laminar top output sheet 100 of the labeling machine is placed by a foil pick and place unit 102, illustrated schematically in Figure 1, having an array of suction cups 104 to lift and place the laminar top sheet 100 over the top of the 2x5 array of package bases.

At the seventh angular position, referring to Figures 10, 11, 12 and 13, the top sheet is heat sealed to the base containers of the blister packs. A heated seal head 110, Figures 12 and 13, heated by a plurality of electric heaters 112 (illustrated as five in the embodiment of Figure 13 and as two in the embodiment of Figure 13) mounted in a heating plate 114. The heating plate 114 is secured to the back of the seal head 110, and is supported by a pneumatic cylinder or press 116 which presses the heated seal head 110 against the laminar top sheets 100 on the package bases 16, which are supported by the pallet such that the foil laminate and base container flanges are squeezed between the heated seal head and the pallet as supported by the rotary index table. The heated seal head is electrically heated, and the temperature thereof is measured by thermal transducers 118 on each side of the seal head 110 to maintain the temperature at a high temperature, when compared to similar prior art arrangements. The temperature is maintained in a range from 210°-265°C.

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1           The heated seal head comprises a 2x5 array of  
cylindrical sealing elements 120, each of which secures  
the top laminar sheet to each package base 16 with an  
annular seal around the cavity 24 in the package base  
5 16. The pneumatic cylinder is coupled to the heated  
seal head by a mount jack bolt 122 and cylindrical  
support struts 124. The support struts 124 are biased  
upwardly by springs 126, such that the heated seal head  
is raised and normally biased to the upper position  
10 illustrated in Figure 10, unless the pneumatic cylinder  
116 forces it down for a sealing operation.

In operation, the back force generated by the  
pneumatic cylinder is measured by an in-line load cell  
128, and a solid state timer is initiated when a force  
15 is reached of a given percentage, e.g., 60-75%, of the  
peak force of which the pneumatic cylinder is capable.  
The solid state timer times a relatively short time  
period of approximately 0.4 to 1.4 seconds, after which  
the pressure in the pneumatic cylinder 116 is released.  
20 This approach, when compared with similar prior art  
approaches, is very hot, very hard and very short, which  
creates a seal which is both detachable and consumer  
friendly.

The rotary index table 12 is preferably  
25 reinforced under the seventh angular position to  
withstand the heat sealing forces imparted thereto by  
the pneumatic cylinder 116. The rotary index table 12  
must be maintained in a substantially level position for  
the operations described herein. The pneumatic cylinder  
30 116 at the seventh position applies a substantial force

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1 to the index table, and accordingly to maintain the  
index table level, an approximately  $2\frac{1}{2}$  x  $3\frac{1}{2}$  inch support  
block 130 of a durable plastic material, similar to  
Teflon®, is placed on top a central support 132 and  
5 surrounding supports 134 positioned beneath the  
pneumatic press. The support block 130 is in constant  
contact with the rotary index table 12 to ensure that  
the deflection of the rotary index table 12 under the  
pneumatic cylinder 116 is minimal. Alternatively, a  
10 pneumatically actuable movable support could be  
positioned in contact with the bottom of the rotary  
index table prior to operation of the pneumatic cylinder  
driving the heated seal head, and be repositioned out of  
contact with the bottom of the rotary index table after  
15 operation of the pneumatic cylinder.

At the eighth angular position, referring to  
Figures 14 and 15, a pneumatically driven handling arm  
140, having a vacuum suction cup 142 for each individual  
blister pack, lifts the 2x5 array of blister packs from  
20 the support pallet 14 and the rotary index table, and  
deposits the array of blister packs to an output  
position. The handling arm 140 driven by a vertical  
pneumatic cylinder 144 and a horizontal pneumatic  
cylinder, not shown - positioned behind cylinder 144,  
25 and also incorporates thereon a precision sensor plate  
146 having a plurality of photoelectric sensors 148  
which look at and examine the outer edges of the foil  
cover 100 on each 1x5 array of blister packs. The  
photoelectric sensors are preferably positioned at the  
30 corners of the expected position of the sheet of

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1 laminated covers on the array. Accordingly, if the  
laminated foil is properly positioned relative to the  
2x5 array of packages, each sensor will detect the  
corner of the foil therebelow. If at least one corner  
5 detector does not detect the presence of the corner of  
the laminated foil therebelow, it means that the foil  
cover is skewed relative to the 2x5 array of packages,  
or is improperly cut short or long.

After being deposited at the output position,  
10 the packages may then be subjected to sterilization, as  
in the instance when the product housed therein is  
intended to be employed in a medical capacity, for  
example, a product such as a contact lens which is  
adapted to be packed in a sterile saline solution and  
15 sealed in a compartment or cavity of the package. The  
blister packs can then be subjected to a secondary  
packaging operation, such as one in which packages of  
1x5 blister packs are placed in a final outer package.

It is noted that the dosing verification at  
20 angularly spaced position 4 may be eliminated in some  
embodiments. Accordingly, in alternative embodiments,  
the rotary index table could be designed with fewer (or  
more) support pallets 14, positioned radially  
therearound, depending upon the number of different  
25 functions to be accomplished by the rotary packaging  
station. Moreover, linear packaging arrangements having  
linear conveyor lines with linearly spaced stations  
therealong are also contemplated in alternative  
embodiments of the present invention.

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1           While several embodiments and variations of  
the present invention for a rotary packaging station are  
described in detail herein, it should be apparent that  
the disclosure and teachings of the present invention  
5 will suggest many alternative designs to those skilled  
in the art.

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## Claims

1. A packaging arrangement for packaging products, comprising:

a. a movable support base having on its upper surface a plurality of substantially identical support pallets, spaced equally apart along the movable support base, each of which is particularly designed to support and align an array of individual package bases;

b. means for sequentially moving the support base through substantially equal incremental movements, with stops between each sequential movement, such that each support pallet with an array of individual package bases thereon is sequentially stopped at spaced stations in the packaging arrangement;

c. at a first station, a loader loads an array of package bases in the support pallet then at the first station;

d. at a subsequent foil placement station, a placer unit places a sheet of laminated covers over the array of package bases;

e. at a subsequent heat sealing station, a heated seal head heat seals the laminated covers to the package bases; and

f. at a subsequent unloading station, an unloader unloads the sealed packages from the packaging arrangement for subsequent processing.

2. A packaging arrangement as claimed in claim 1, wherein at the first station, the packaging arrangement

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receives individual blister package bases, each of which has a contact lens therein, whereby the rotary packaging arrangement packages the contact lenses into blister packages.

3. A packaging arrangement as claimed in claim 1, wherein at the heat sealing station, an electrically heated seal head is driven by a pneumatic cylinder against the laminated covers on the package bases, which are supported by the pallet and the support base.

4. A packaging arrangement as claimed in claim 3, wherein a thermal detector measures the temperature of the seal head to maintain the temperature in a range from 210-265°C.

5. A packaging arrangement as claimed in claim 3, wherein an in-line load cell measures the force generated by the pneumatic cylinder, and when a predetermined force is reached, a timer is initiated.

6. A packaging arrangement as claimed in claim 5 wherein the timer times a relatively short time period of approximately 0.4 to 1.4 seconds, after which the pressure in the pneumatic cylinder is released, thereby forming a seal between each laminated cover and package base which is both detachable and consumer friendly.

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7. A packaging arrangement as claimed in claim 1, wherein at a subsequent saline dosing station, dosers deposit a given dosage of saline solution in each package base.

8. A packaging arrangement as claimed in claim 3, wherein the movable support base is maintained in a substantially level position by a reinforcement support under the heat sealing station to withstand the forces imparted thereto by the pneumatic cylinder.

9. A packaging arrangement as claimed in claim 8, wherein the movable support base is reinforced by a support beneath the movable support base at the pneumatic cylinder, to ensure that the deflection of the movable support base by the pneumatic cylinder is minimal.

10. A packaging arrangement as claimed in claim 1, wherein at the unloading station, a pneumatically driven handling arm, having a vacuum suction cup for each individual package, lifts the array of packages from the support pallet on the movable support base, and deposits the array of packages at an output position.

11. A packaging arrangement as claimed in claim 10, wherein the handling arm incorporates thereon a precision sensor plate having a plurality of photoelectric sensors which examine the outer edges of



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the sheet of laminated covers on the array of packages to determine if the sheet of laminated covers is skewed relative to the array of packages.

12. A packaging arrangement as claimed in claim 11, wherein the photoelectric sensors are positioned at the corners of the expected position of the sheet of laminated covers on the array.

13. A packaging arrangement as claimed in claim 1, wherein the movable support base receives individual package bases, each of which has a product therein, which are lined up and queued for packaging on side by side accumulator rails.

14. A packaging arrangement as claimed in claim 13, further including means for precisely positioning the package bases on the side by side accumulator rails such that a robotic handling arm, having an array of vacuum handling cups, one for each individual package base, picks up an array of package bases and deposits the array of package bases onto a support pallet at the first station on the movable support base.

15. A packaging arrangement as claimed in claim 14, wherein the robotic handling arm transfers package bases from the accumulator rails to a support pallet positioned at the first station, and also transfers

package bases between the accumulator rails and a buffer area.

16. A packaging arrangement as claimed in claim 14, wherein after the package bases are deposited onto one end of the side by side accumulator rails, first and second pneumatic cylinders advance the package bases to the second opposite end of the accumulator rails, and a third pneumatic cylinder at the second end of the accumulator rails then precisely positions the package bases at the second end of the accumulator rails relative to the robotic handling arm to allow the robotic handling arm to pick up and place an array of package bases in a support pallet at the first station.

17. A packaging arrangement as claimed in claim 14, wherein the support pallet spaces the side of each package base a nominal distance, in the range of 200 to 400  $\mu$ meters, from the side of each adjacent package base in the support pallet, to prevent overlapping sides of adjacent product bases, and wherein the side by side accumulator rails accumulate package bases in positions in which package bases directly touch adjacent package bases, and to compensate for the slight difference in spacing from the nominal distance between adjacent package bases in the pallet, the robotic arm, after positioning an array of package bases over a pallet, releases the vacuum in each vacuum cup to allow the package bases to fall into the support pallet, and then

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raises and lowers the array of suction cups slightly to tap each package base into a properly aligned position in the support pallet.

18. A packaging arrangement as claimed in claim 1, wherein each package base includes a rounded product cavity and alignment notches on opposite sides of the package base, and the support pallet defines a rounded cavity for receiving each product cavity of each package base and alignment rods which fit into the alignment notches on opposite sides of each package base.

19. A packaging arrangement as claimed in claim 2, wherein at the saline dosing station, a pivotable arm supports an array of dosing tubes, each of which is supplied by a separate dosing pump to deposit a precise dosage of saline solution into each package base, such that each contact lens is immersed in saline solution.

20. A packaging arrangement as claimed in claim 19, wherein a pump cart is positioned adjacent to the saline dosing station and mounts thereon the dosing pumps and a reservoir of saline solution for the dosing pumps, and periodically the support arm is rotated to position the dosing tubes over a collection pan, and each pump is cycled several times, with the discharge from the dosing tubes being collected in the collection pan.

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21. A packaging arrangement as claimed in claim 1, wherein at the foil placement station, a foil pick and place unit, having an array of suction cups, lifts and places two sheets of laminated covers over the array of package bases.

22. A packaging arrangement as claimed in claim 1, wherein the movable support base comprises a rotary index table having on its upper surface a plurality of radially spaced support pallets.

23. A packaging arrangement as claimed in claim 1, wherein at a subsequent verification station after the first station, probes verify the presence of each package base in the array of package bases supported by the pallet.

24. A packaging arrangement as claimed in claim 23, wherein said verifying probes include an array of fiber optic probes positioned above the array of package bases, with each fiber optic probe illuminating each package base, and then detecting radiation reflected therefrom to verify the presence of each package base in the support pallet.

25. A packaging arrangement as claimed in claim 23, wherein the verifying probes include at least one alignment probe for verifying the alignment of the packaging bases in the support pallet to check that no

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package bases are skewed or tilted in the support pallet.

26. A packaging arrangement as claimed in claim 25, wherein said at least one alignment probe includes a through-beam detector which directs a beam of light along the length of and just above a column of package bases supported in the pallet to a detector at the other end of the column, such that a package base which is skewed or tilted in the pallet interrupts the through beam, and the photodetector at the other end of the through beam so indicates.

27. A packaging arrangement as claimed in claim 7, wherein after the saline depositing station, at a subsequent depositing verification station, an array of sensors verifies that a fixed dosage of saline solution has been deposited into each package base.

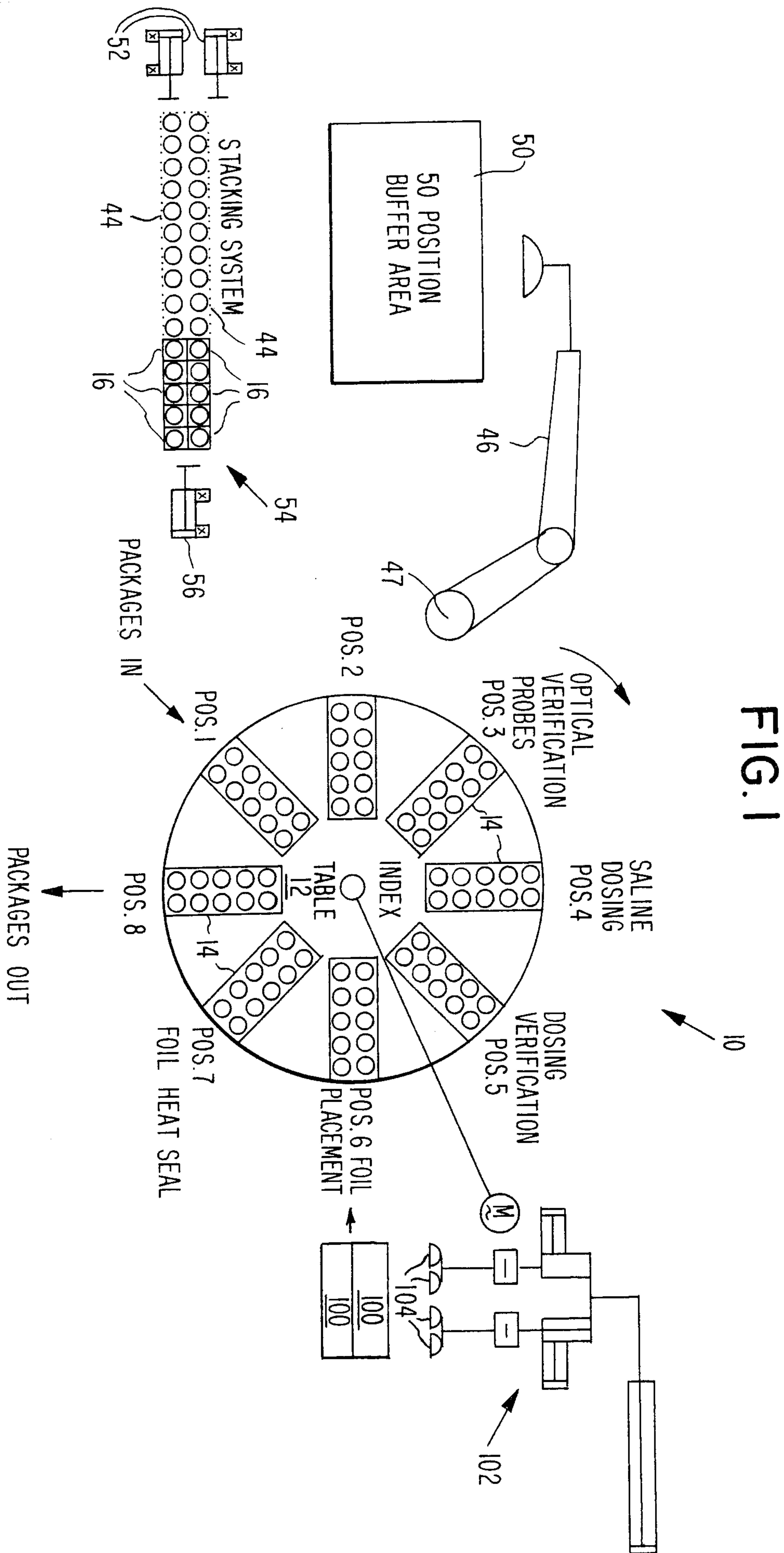


FIG. 2

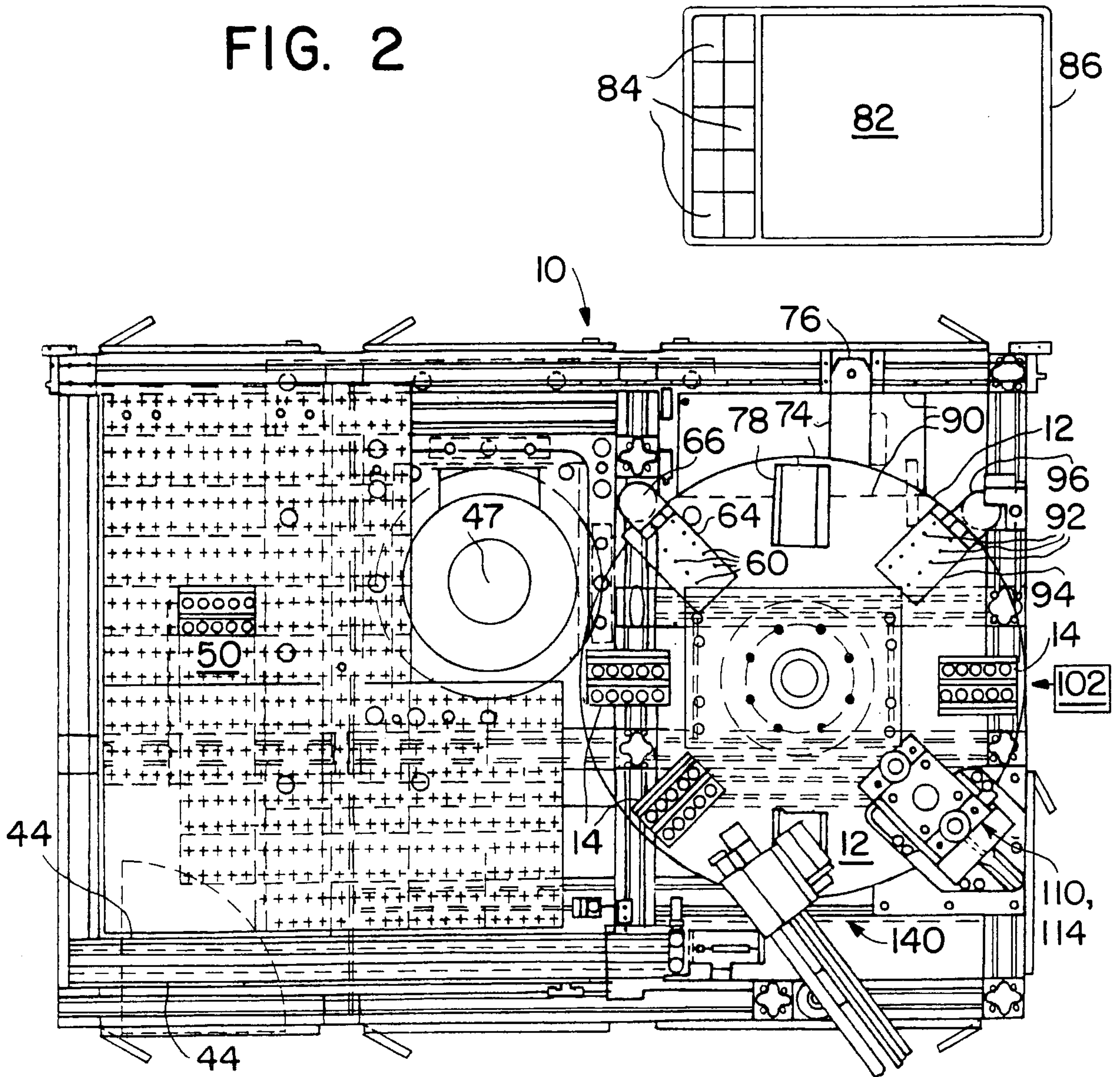


FIG. 3

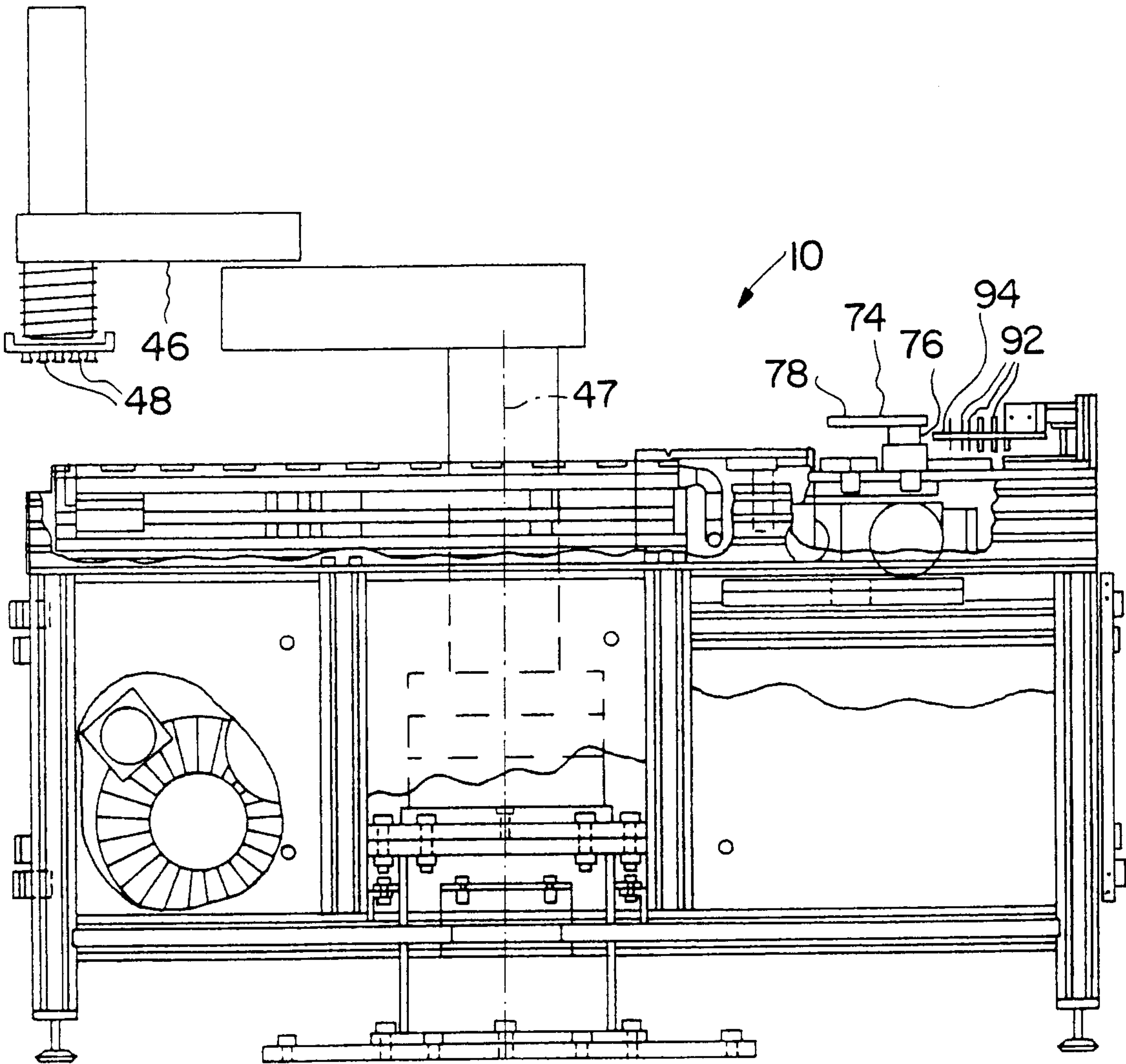




FIG. 4

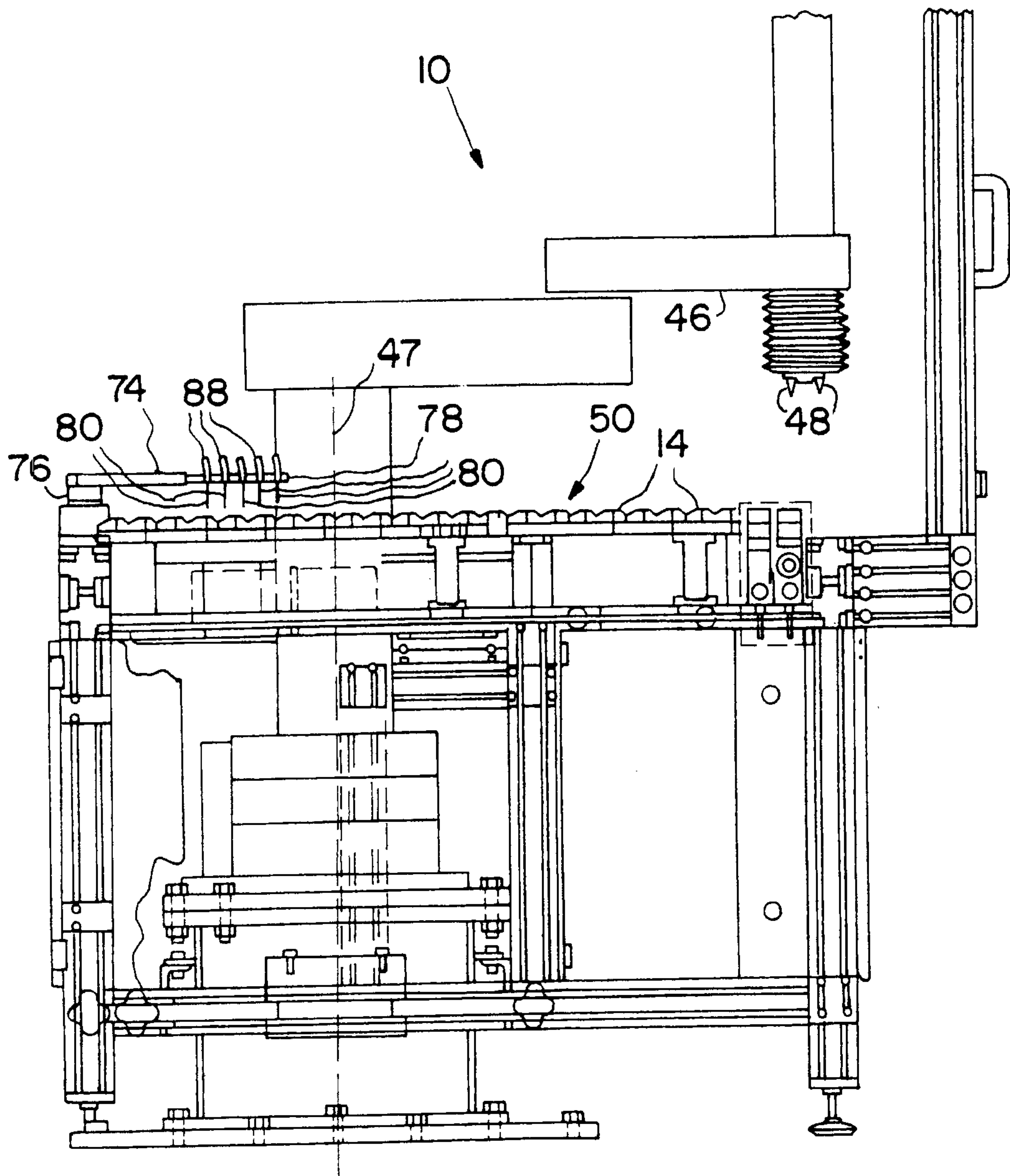


FIG. 5

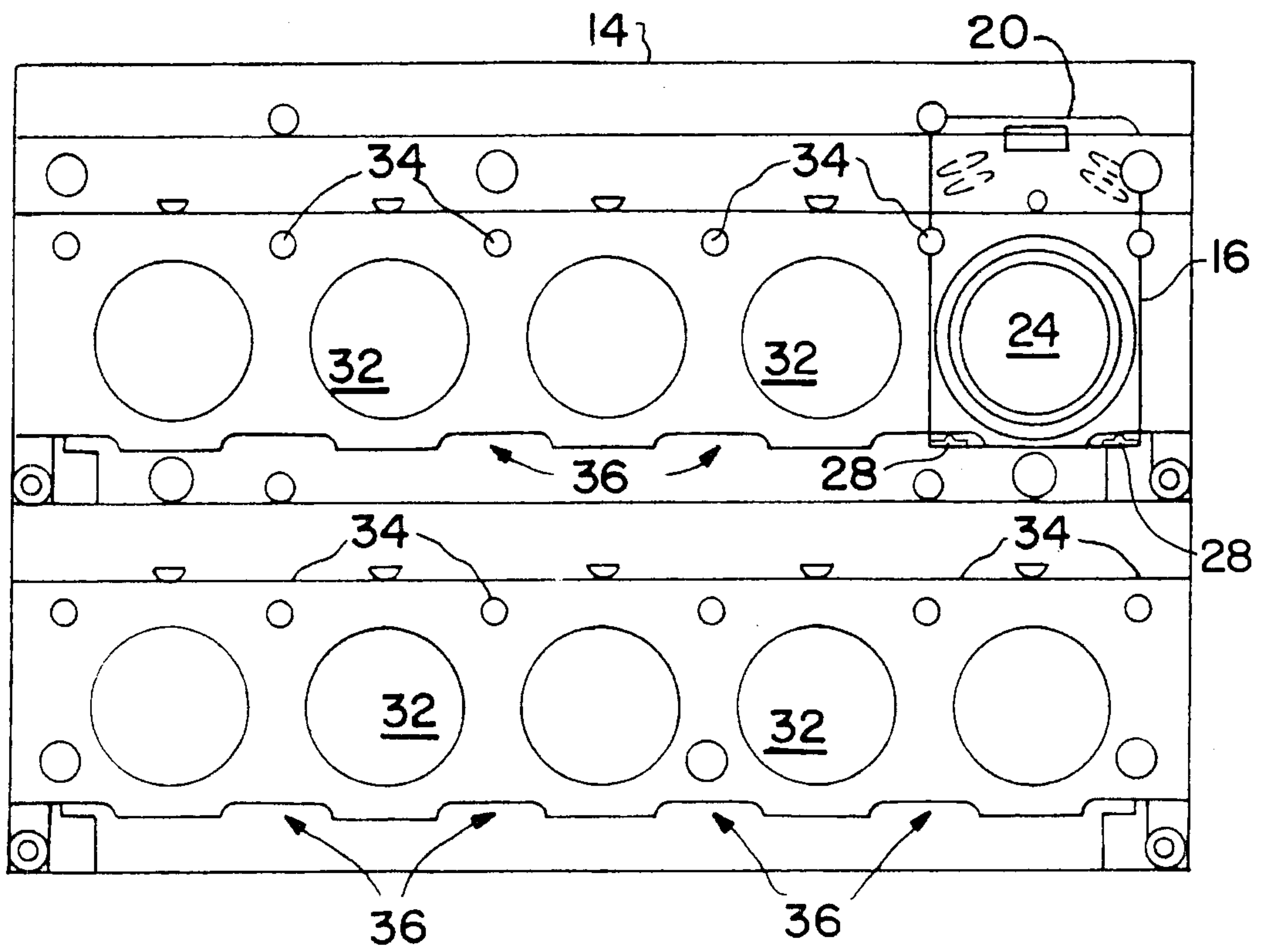


FIG. 6

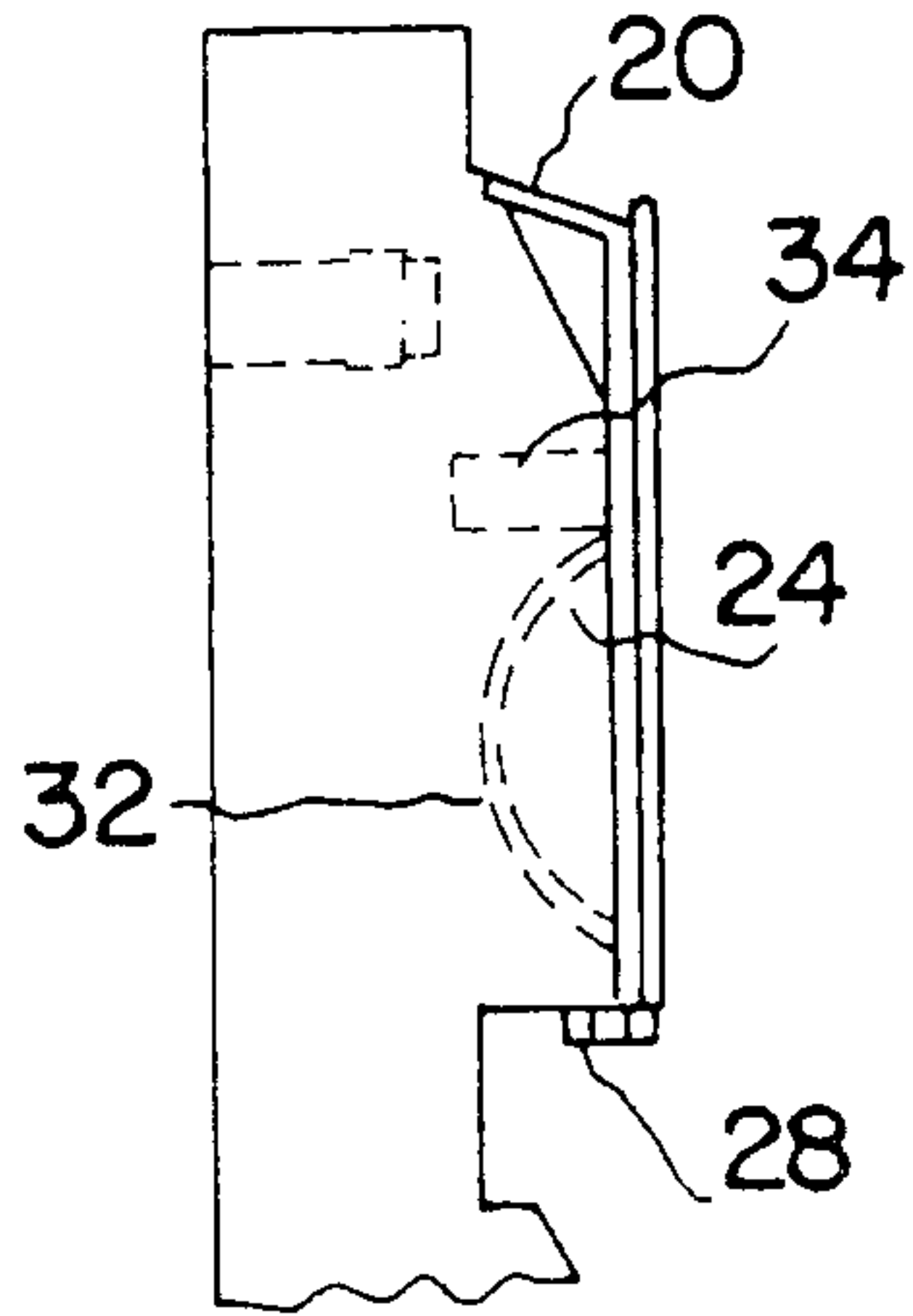


FIG. 7

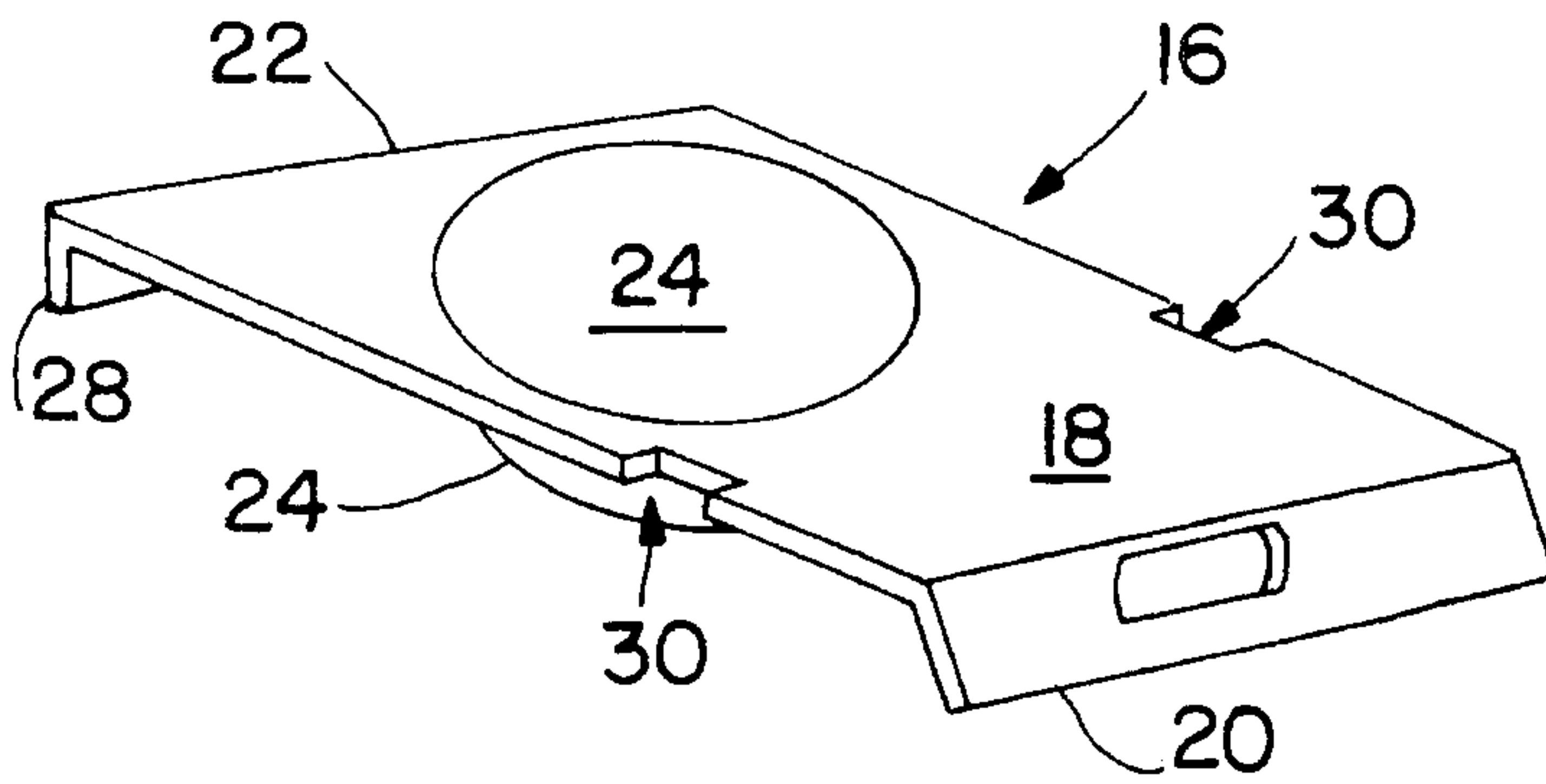


FIG. 8

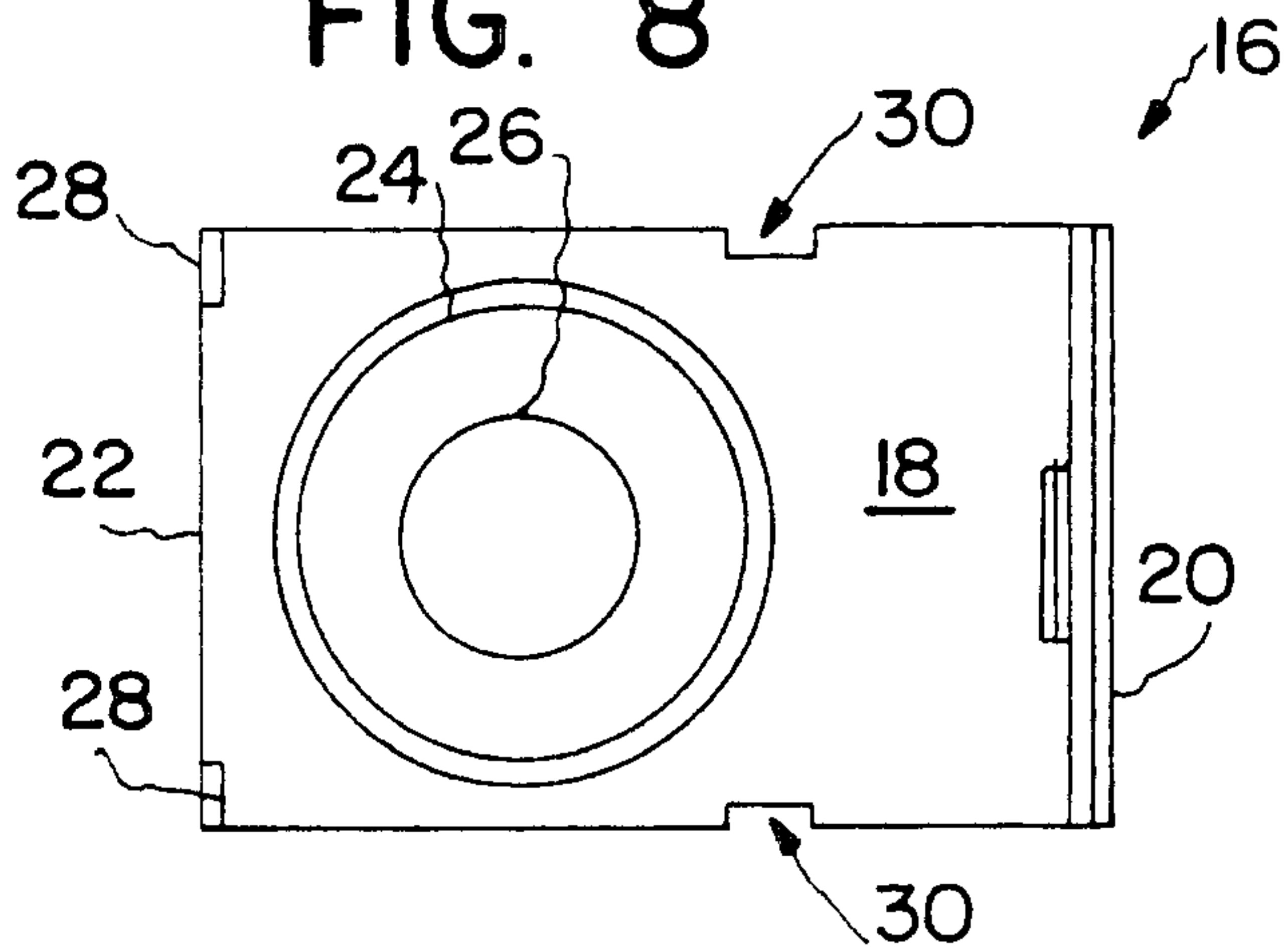


FIG. 9

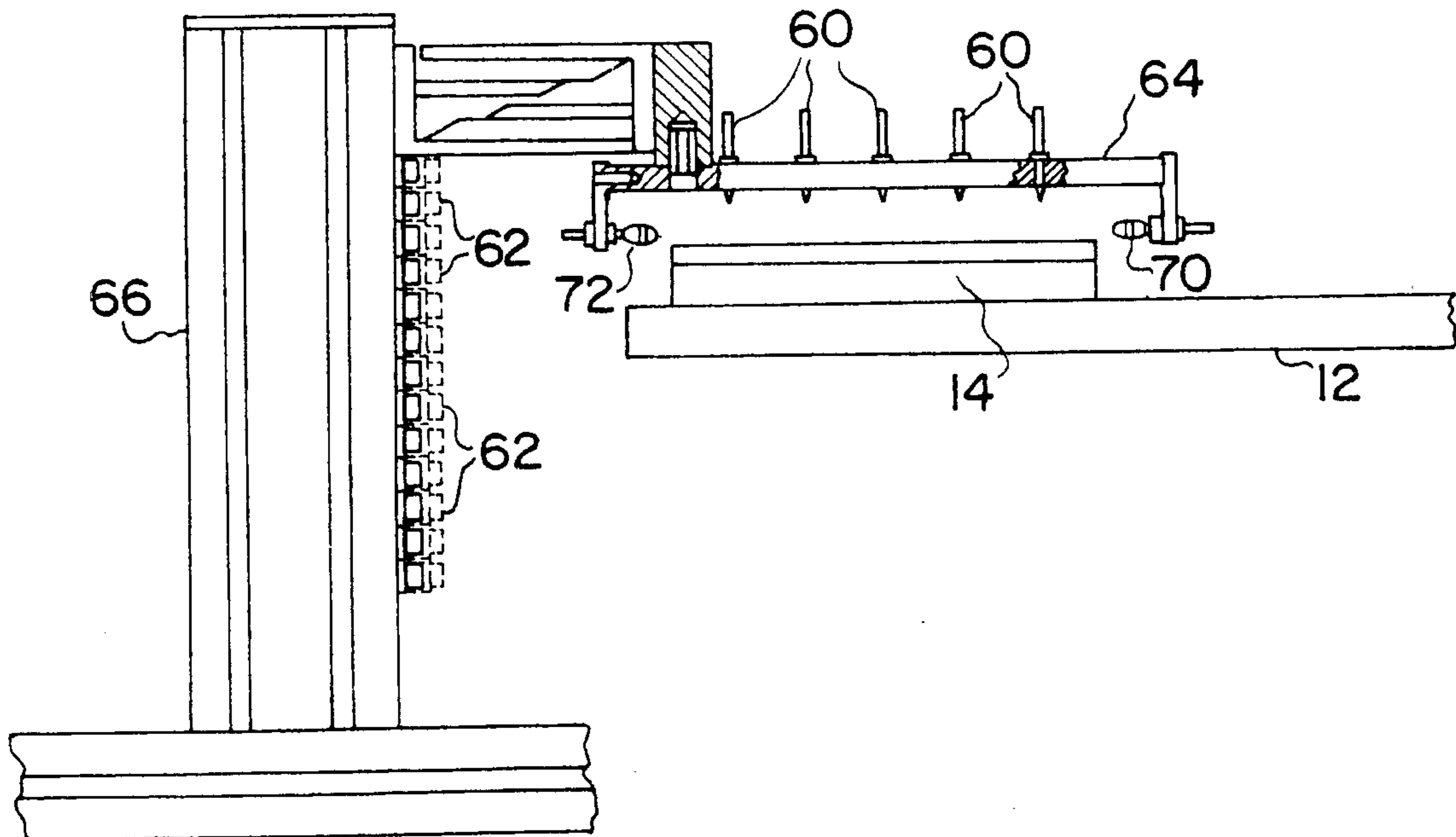


FIG. 10

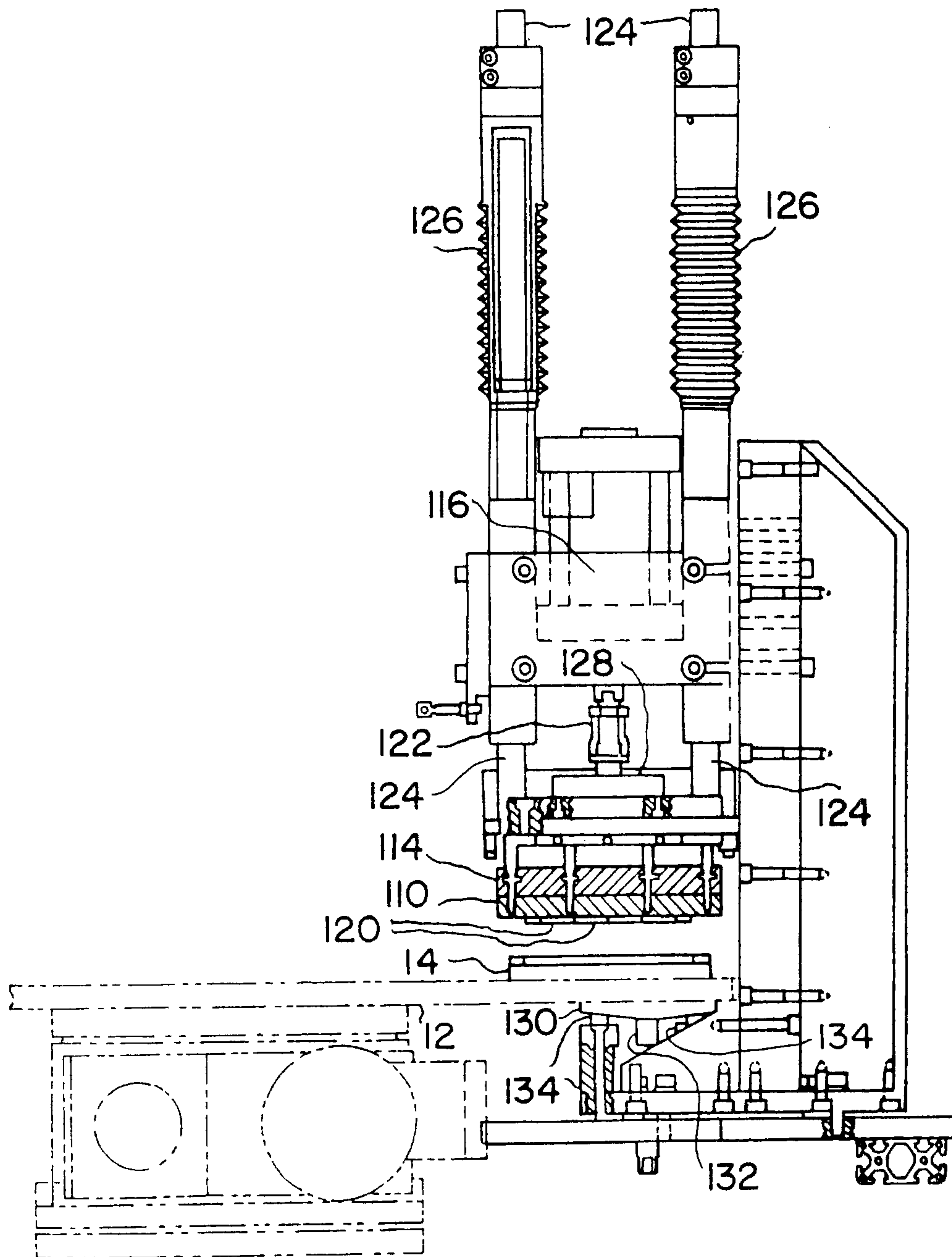


FIG. II

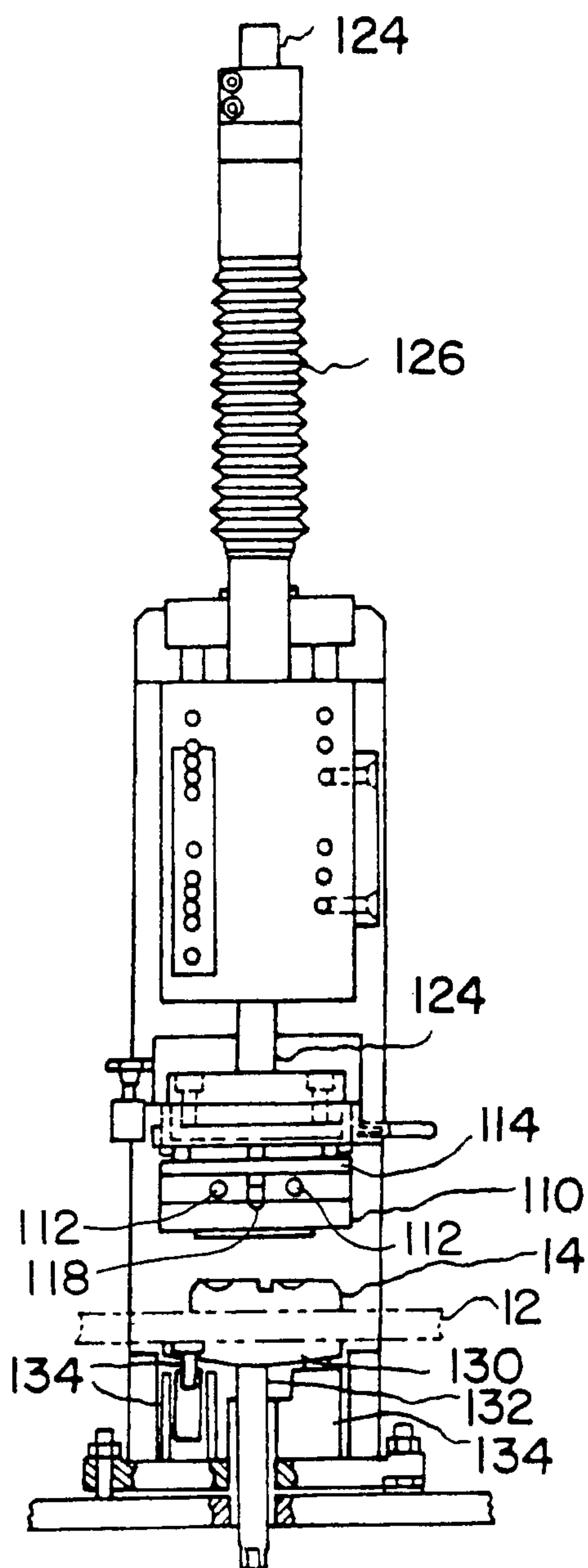


FIG. 12

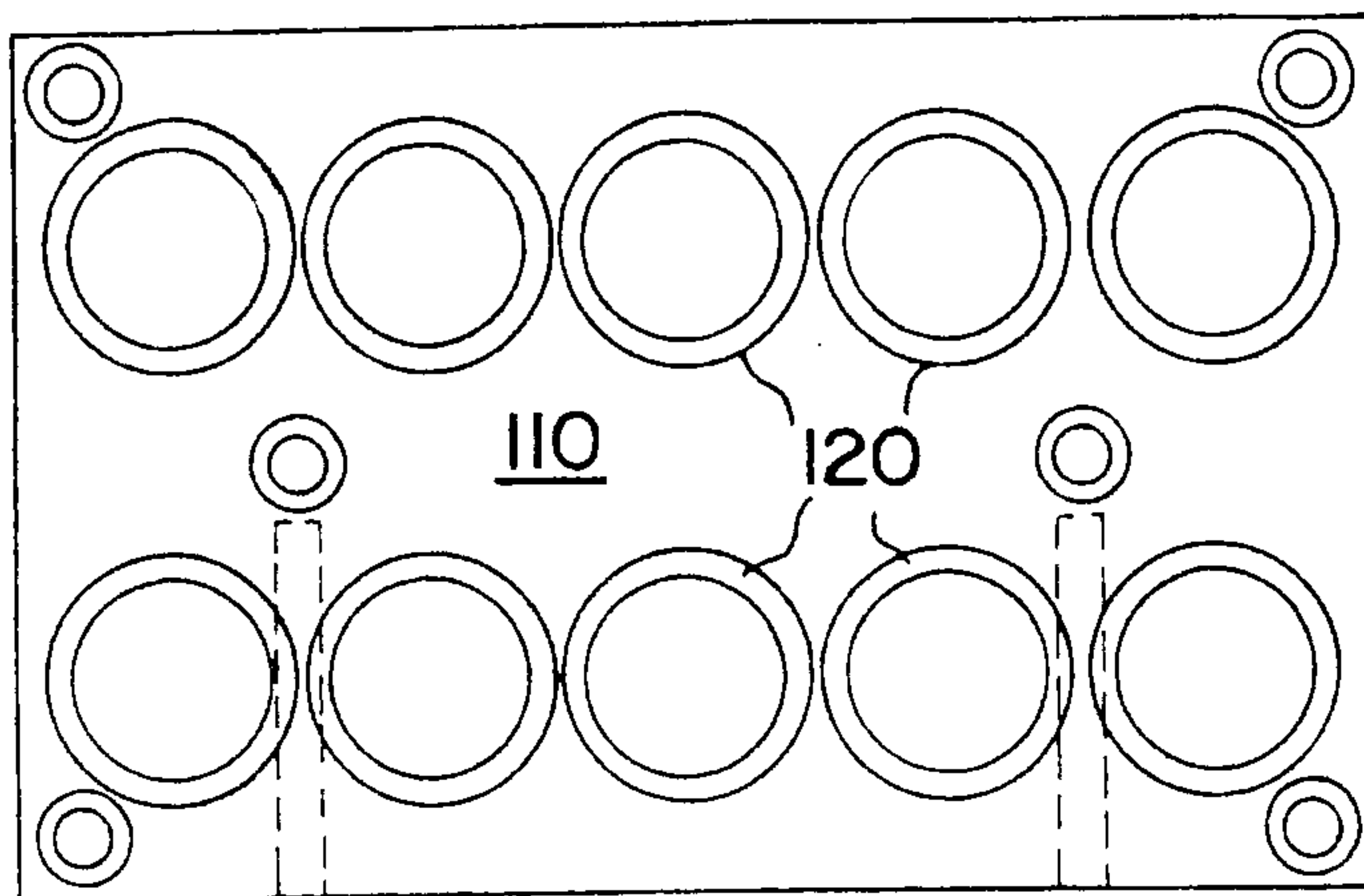


FIG. 13

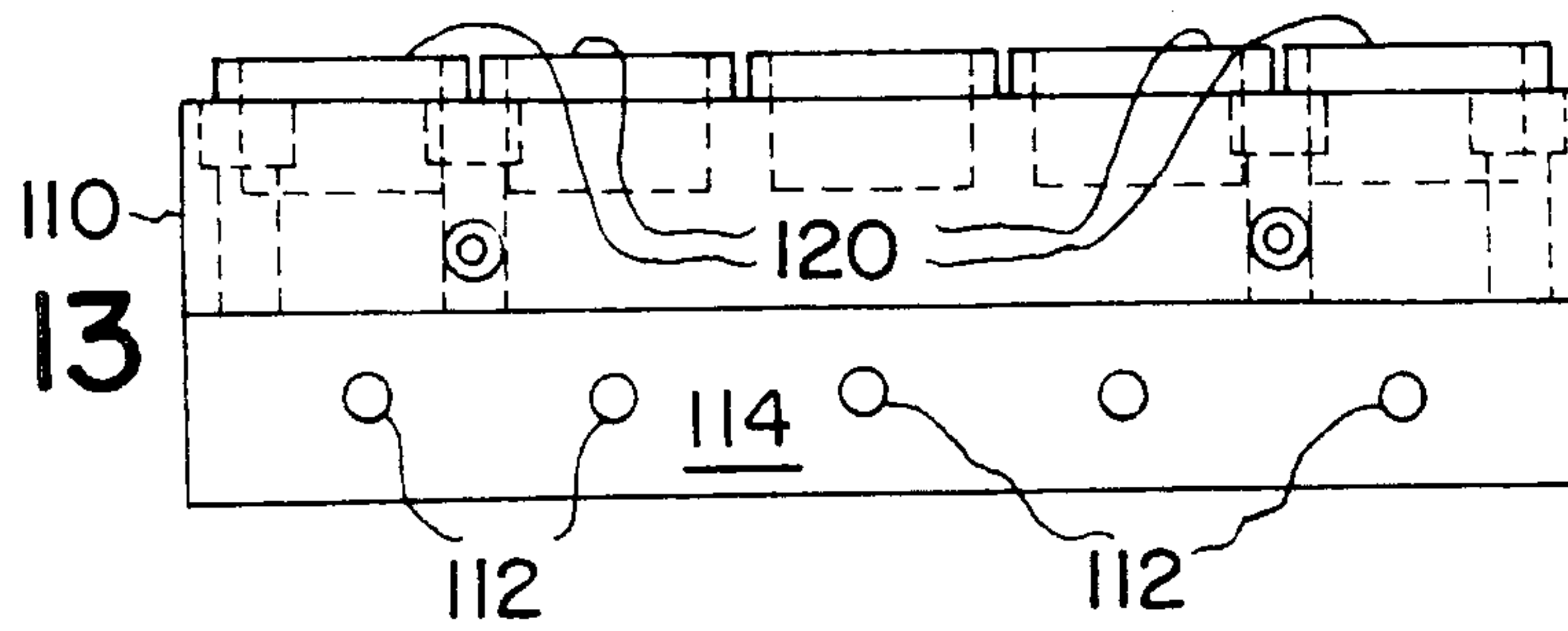


FIG. 14

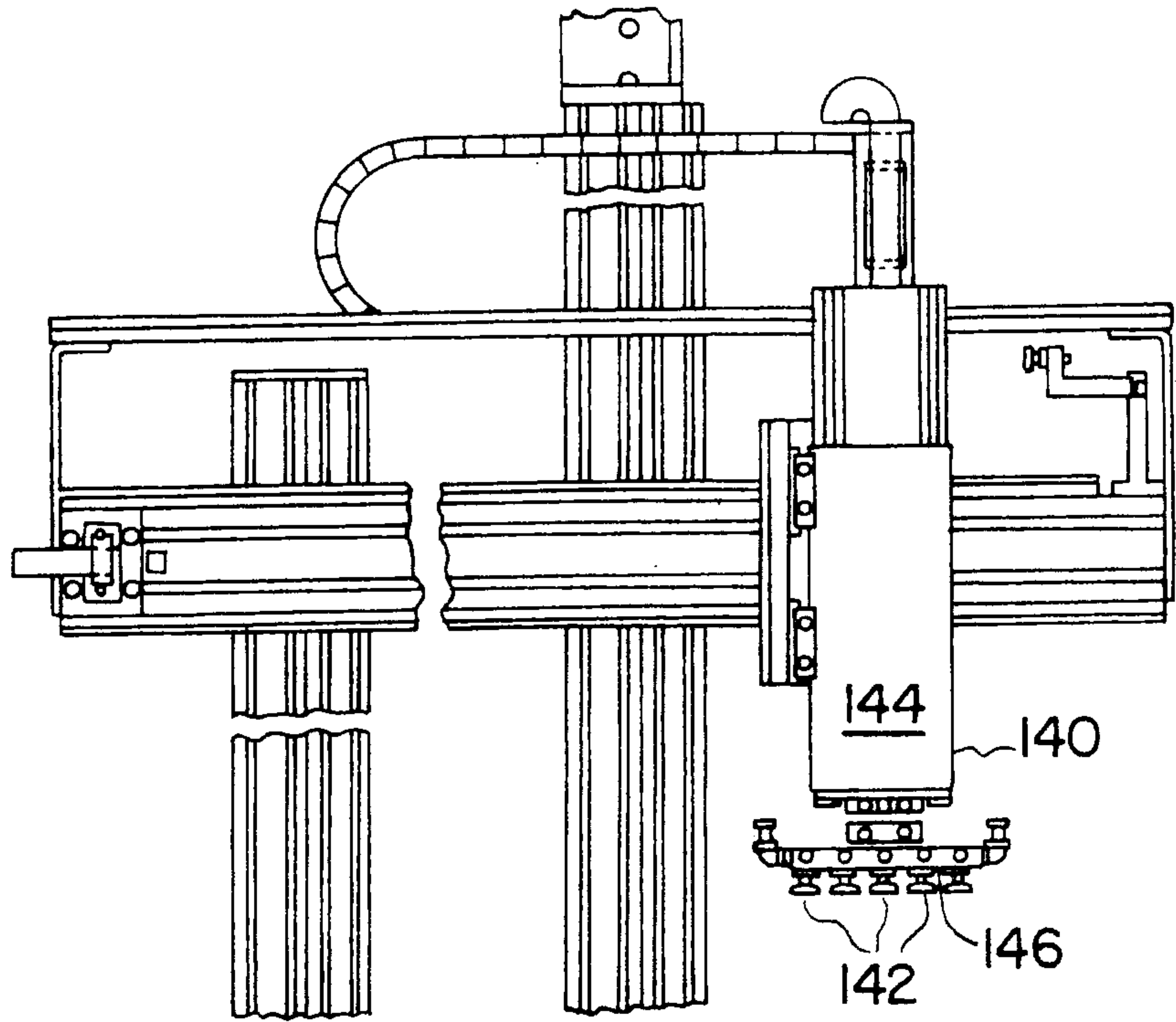


FIG. 15

