



(19)

Europäisches Patentamt  
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(11)

EP 1 208 032 B1

(12)

## EUROPEAN PATENT SPECIFICATION

(45) Date of publication and mention  
of the grant of the patent:

23.11.2005 Bulletin 2005/47

(21) Application number: 00971072.4

(22) Date of filing: 29.08.2000

(51) Int Cl.<sup>7</sup>: B62K 1/00, A61G 5/06

(86) International application number:  
PCT/US2000/040770

(87) International publication number:  
WO 2001/015962 (08.03.2001 Gazette 2001/10)

### (54) VEHICLE STABILIZING SYSTEM HAVING PIVOTAL SUPPORT

FAHRZEUGSTABILISIERUNGSSYSTEM MIT SCHWENKBARER LAGERUNG

SYSTEME STABILISATEUR D'UN VEHICULE A SUPPORT PIVOTANT

(84) Designated Contracting States:  
AT BE CH CY DE DK ES FI FR GB GR IE IT LI LU  
MC NL PT SE

(30) Priority: 31.08.1999 US 386686

(43) Date of publication of application:  
29.05.2002 Bulletin 2002/22

(73) Proprietor: DEKA PRODUCTS LIMITED  
PARTNERSHIP  
Manchester, NH 03101 (US)

(72) Inventors:  
• KAMEN, Dean, L.  
Bedford, NH 03110 (US)  
• AMBROGI, Robert, R.  
Manchester, NH 03104 (US)

- DUGGAN, Robert  
Strafford, NH 03884 (US)
- FIELD, Douglas  
Bedford, NH 03110 (US)
- HEINZMANN, Richard, Kurt  
Francesstown, NH 03043 (US)

(74) Representative: Greene, Simon Kenneth et al  
Elkington and Fife LLP,  
Prospect House,  
8 Pembroke Road  
Sevenoaks, Kent TN13 1XR (GB)

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**Description****Technical Field**

**[0001]** The present invention pertains to a balancing personal vehicle having a support for a human subject, the support being pivotable in order to allow the subject to be supported at a desired angle with respect to ground contacting elements of the vehicle.

**Background of the Invention**

**[0002]** Personal vehicles may be self-propelled and user-guidable, and, further, may entail stabilization in one or both of the fore-aft or left-right planes, such as when no more than two wheels are in ground contact at a time. Vehicles of this sort may be operated in a mode in which motion of the vehicle, including acceleration (both linear and turning), is controlled partially or entirely by leaning of the vehicle as caused by a subject riding the vehicle. Several such vehicles are described in U. S. Patent no. 5,971,091.

**[0003]** Such balancing vehicles may lack static stability. Referring, for example, to Fig. 1A, wherein a prior art personal transporter is shown and designated generally by numeral 18, a subject 10 stands on a support platform 12 and holds a grip 14 on a handle 16 attached to the platform 12, so that the vehicle 18 of this embodiment may be operated in a manner analogous to a scooter. A control loop may be provided so that leaning of the subject results in the application of torque to wheel 20 about axle 22 thereby causing an acceleration of the vehicle. Vehicle 18, however, is statically unstable, and, absent operation of the control loop to maintain dynamic stability, subject 10 will no longer be supported in a standing position and will fall from platform 12. Another prior art balancing vehicle is shown in Fig. 1B and designated generally by numeral 24. Personal vehicle 24 shares the characteristics of vehicle 12 of Fig. 1A, namely a support platform 12 for supporting subject 10 and grip 14 on handle 16 attached to platform 12, so that the vehicle 18 of this embodiment may also be operated in a manner analogous to a scooter. Fig. 2 shows that while vehicle 24 may have clusters 26 each having a plurality of wheels 28, vehicle 24 remains statically unstable and, absent operation of a control loop to maintain dynamic stability, subject 10 will no longer be supported in a standing position and may fall from platform 12.

**Summary of the Invention**

**[0004]** In accordance with a preferred embodiment of the invention, there is provided a device for transporting a human subject over a surface as set out in claim 1. The device has a platform defining a fore-aft plane that supports a payload including the human subject. The device also has a ground-contacting module that in-

cludes a ground-contacting member movably coupled to the platform. The platform and the ground-contacting module are components of an assembly, and the position of the center of gravity of the assembly is defined

5 with respect to the ground-contacting member. The device also has a support for supporting the subject, where the support is coupled to the platform in such a manner as to permit variation in the fore-aft plane of the position of the center of gravity.

10 Furthermore, the device has a drive, coupled to the ground contacting module, for delivering power to the ground-contacting module in a manner responsive to the position of the center of gravity. The support includes a seat.

15 **[0005]** The support may be coupled to the platform at a pivot oriented to allow motion of the support about an axis substantially transverse to the fore-aft plane. The device may have a handle, affixed to the platform, having a grip at approximately waist height of the subject,

20 so that the device may be operated in a manner analogous to a scooter. The ground- contacting module may be characterized by a region of contact with the ground and the support may have an articulated member, biased for supporting a portion of the weight of the subject, 25 and the support may have a region of local stability substantially above the region of contact with the ground of the ground-contacting module.

**[0006]** In accordance with a further embodiment of the invention, there is provided a device for carrying a user, 30 wherein the device has a platform and a user support having a position defined with respect to the platform and coupled to the platform in such a manner that the user may vary the position of the support with respect to the platform in the course of normal operation of the device. The device also has a motorized drive that propels the platform over an underlying surface through motion of at least one ground-contacting member and a controller, coupled to the motorized drive, for governing the operation of the motorized drive at least in response to the position of the user support.

**[0007]** In accordance with yet a further embodiment of the invention there is provided a device for conveying a seated user. The device has a platform for supporting a payload including the seated user, a ground-contacting module mounted to the platform that propels the platform with respect to an underlying surface, and a drive, coupled to the ground-contacting module, for delivering power to the ground-contacting module in a manner controlled solely by leaning of the user.

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**Brief Description of the Drawings**

**[0008]** The invention will be more readily understood by reference to the following description, taken with the 55 accompanying drawings, in which:

FIG. 1A is a side view of a prior art dynamically balancing vehicle of the type in which an embodiment

of the invention may be advantageously employed; FIG. 1B is a side view of a further prior art dynamically balancing vehicle of the type in which an embodiment of the invention may be advantageously employed;

FIG. 2 is a side view of a dynamically balancing vehicle having an articulated pivotable support in accordance with an embodiment of the invention;

FIG. 3 is a side view of the dynamically balancing vehicle of Fig. 2 showing the articulated pivotable support in a partially folded configuration; and

FIG. 4A is a side view of a dynamically balancing vehicle showing an articulated pivotable support in a further embodiment of the present invention;

FIG. 4B is a further side view of the embodiment of Fig. 4A showing two positions of the pivotable support;

FIG. 5A is a side view of a pivotable support having a central equilibrium position in accordance with a further embodiment of the present invention; and

FIG. 5B is a further side view of the embodiment of Fig. 5A showing detail of a cam-follower arrangement.

#### Detailed Description of Preferred Embodiments

**[0009]** Referring to Fig. 1A, prior art balancing vehicle 18 does not provide a seat for the subject 10 using the vehicle. The subject stands on a platform 12 and holds a grip 14 on handle 16 attached to platform 12, so that the vehicle of this embodiment may be operated in a manner analogous to a scooter. The pitch of the vehicle may be sensed and compensated for in the control loop, so that if the subject leans forward, the vehicle will move forward, and similarly, leaning in other directions may cause corresponding motion of the vehicle. Accordingly, a forward lean will cause forward movement; a backward lean will cause backward movement. Appropriate force transducers may be provided to sense leftward and rightward leaning and related controls provided to cause left and right turning as a result of the sensed leaning. The leaning may also be detected using proximity sensors. Similarly, the vehicle of this embodiment may be equipped with a foot- (or force-) actuated switch to activate the vehicle, in such a manner that the switch is closed so as to power the vehicle automatically when the subject stands on the platform 12.

**[0010]** Referring now to Fig. 2, a personal vehicle 30 is shown of the type in which pitch of the vehicle may be sensed and compensated for by application of torque to one or more wheel 32 (or other ground-contacting members) by operation of a control loop (not shown) and wheel actuator (not shown), so that if subject 10 leans forward, the vehicle is caused to move forward. It is to be understood that platform 12 is not necessarily coupled directly to wheel 32. Tilting of the vehicle is not necessarily canceled during ordinary operation of the vehicle, so that sustained motion and sustained acceleration

may be achieved. In accordance with an embodiment of the present invention, a seat 34 is provided for supporting a portion of the weight of subject 10. Subject 10 may still vary the position of his center of gravity, and

5 the position of the center of gravity 36 of the combination of vehicle 30 and subject 10 while seat 34 continues to support a portion of the weight of the subject by virtue of the pivotability of seat 34 with respect to platform 12.

**[0011]** It is to be understood that within the scope of 10 the present invention, as described herein and as claimed in any appended claims, wheel 32 may rotate about a single axle, or, alternatively, about an axis that may vary in orientation, in the manner of a uniball.

**[0012]** Seat 34 may be coupled to platform 12 by any 15 of a variety of mechanisms. In accordance with a preferred embodiment of the present invention, seat 34 is coupled to platform 12 via link 38, itself pivotally coupled to platform 12, and coupled to seat 34 at knee joint 40. The articulated support comprising seat 34 and link 38

20 may be biased by a spring arrangement (not shown) or its equivalent so as to counter the weight of the subject. Figure 3 shows seat 34 depressed at knee joint 40 with respect to link 38. Additionally, pivot 42 is shown coupling link 38 to support platform 12 in a manner as to 25 constrain link 38 to fore-aft motion about an axis substantially transverse to the fore-aft plane. The spring arrangement (not shown) may include any means, such as a coil spring or a gas spring, known for biasing the support mechanism for supporting some fraction of the 30 weight of the subject. Additionally, mechanisms known in the art for providing for translation of seat 34 in a fore-aft direction for shifting the weight of subject 10 with respect to ground-contacting member 32 are within the scope of the present invention.

**[0013]** An alternative to the articulating folding seat of 35 the embodiment of Fig. 3 is described with reference to Fig. 4A. A balancing personal vehicle 44 is shown in which seat 34 may be pivoted with respect to support platform 12 by means of a seat support mechanism designated generally by numeral 46. Seat support 46 has two substantially linear members 48 which pivot in about

40 pivots 50 through which linear members 48 are coupled to platform 12. Linear members 48 are coupled to seat 34 at pivots 52. A subject seated on seat 34 may shift 45 her weight, and thereby the center of gravity of the combination of vehicle and subject, by moving seat 34 in a fore-aft direction. Fig. 4B shows the articulating folding seat of Fig. 4A in two positions: the position designated 50 54 places the center of gravity of the vehicle, including the rider, substantially above the region of contact of the ground-contacting member 20 (shown in Fig. 4A) with the ground. Seat 34 may also be folded up toward handle 16 as in the position designated by numeral 56. In the embodiment shown in Figs. 4A and 4B, seat 34 is 55 highest, and thus possesses the greatest potential energy, in central position 54.

**[0014]** Referring now to Fig. 5A, in accordance with other embodiments of the present invention, stability is

provided by ensuring that the central position of the seated user, substantially above axle **22**, is a stable position, i.e., a position characterized by a local minimum of potential energy. Thus, with respect to the central position designated by numeral **54**, seat **34** is displaced further from platform **12**, and thus higher above level ground, as seat **34** is moved by virtue of the rider moving in either a forward direction **60** or an aft direction **62**. In accordance with the embodiment depicted in Fig. 5A, seat **34** is supported by a substantially trilateral arrangement **64** of links. Arm **66** pivots about a pivot point **68** fixed with respect to platform **12**, while link **70** couples arm **66** to seat **34**. Link **72**, substantially parallel to link **70**, supports seat **34** in a substantially horizontal orientation in its central position **54**. The third side of trilateral arrangement **64** is formed by link **74**. Link **74**, as shown in greater detail in Fig. 5B, may be a rigid member or a suspension member, as shown, containing a gas spring **76** which serves to cushion seat **34** with respect to vibration transmitted from the road surface through platform **12**. Link **74** is coupled to cam follower **78** which rides on cam surface **80** in such a manner as to provide a well **82** of stability at the center of motion of seat **34**. If seat **34** moves fore or aft, cam follower **78** is driven up cam **80**, thereby increasing the height of seat **34** relative to platform **12** relative to its position of stability at the center. This reduces the effort required of the rider to maintain a centered body position, thereby advantageously allowing the rider to maintain a more relaxed position and momentarily to remove his/her hands from the handlebar.

**[0015]** It is to be understood that other mechanical configurations providing for seat 34 to rise as seat 34 is moved either forward or aft of its central position 54 wherein the center of gravity of the vehicle and rider is substantially over the region of contact of the vehicle with the ground are within the scope of the present invention as claimed in the appended claims.

**[0016]** The described embodiments of the invention are intended to be merely exemplary and numerous variations and modifications will be apparent to those skilled in the art. All such variations and modifications are intended to be within the scope of the present invention as defined in the appended claims.

## Claims

1. A device for transporting a human subject over a surface, the device comprising:
  - a. a platform (12) defining a fore-aft plane, the platform supporting a payload including the human subject;
  - b. a ground-contacting module, including a ground-contacting member (32) movably coupled to the platform, the ground contacting member **characterized by** a region of contact

with the ground, the platform (12) and the ground-contacting module being components of an assembly having a center of gravity, the center of gravity having a position defined with respect to the ground-contacting member;

c. a support (34, 38, 46, 64) including a seat (34) for supporting the subject, the support coupled to the platform in such a manner as to permit variation of the position of the center of gravity in the fore-aft plane by motion of the support both fore and aft of the region of contact with the ground; and

d. a drive, coupled to the ground-contacting module, arranged to deliver power to the ground-contacting module in a manner responsive to the position of the center of gravity, whereby a seated subject may control the device by motion of the seat in the fore-aft plane with respect to the platform.

2. A device according to claim 1, wherein the support (34, 38, 46, 64) is coupled to the platform at a pivot (42) oriented to allow motion of the support (34, 38, 46, 64) about an axis substantially transverse to the fore-aft plane.

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3. A device according to claim 1, further comprising a handle (16), affixed to the platform (12), having a grip at approximately waist height of the subject, so that the device may be operated in a manner analogous to a scooter.

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4. A device according to claim 1, wherein the support includes an articulated member (38), biased for supporting a portion of the weight of the subject.

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5. A device according to claim 1, wherein the support has a position of local stability substantially above the region of contact with the ground of the ground-contacting module.

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6. A device according to claim 1, further comprising:

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e. a controller, coupled to the motorized drive, for governing the operation of the motorized drive at least in response to the position of the user support.

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7. A device according to claim 1, wherein the position of the support with respect to the platform may be varied by leaning of the user.

## Patentansprüche

1. Vorrichtung zum Transportieren einer menschlichen Person über eine Oberfläche, wobei zu der Vorrichtung gehören:

a) eine Plattform (12), die eine Vorder-Hinter-ebene bestimmt, wobei die Plattform eine Zu-ladung einschließlich der menschlichen Person trägt;

b) ein bodenberührendes Modul, das ein bodenberührendes Bauteil (32) einschließt, das beweglich mit der Plattform verbunden ist, wo-bei das bodenberührende Bauteil durch einen Bereich mit Bodenberührung **gekennzeichnet** ist, wobei die Plattform (12) und das bodenbe-rührende Modul Bestandteile eines Aufbaus mit einem Schwerpunkt sind, wobei der Schwerpunkt eine Lage hat, die in Bezug auf das bodenberührende Bauteil bestimmt ist;

c) eine Stütze (34, 38, 46, 64), zu der ein Sitz (34) zum Stützen der Person gehört, wobei die Stütze mit der Plattform derart verbunden ist, dass eine Änderung der Lage des Schwer-punkts in der Vorder-Hinterebene durch Bewe-gung der Stütze sowohl vor als auch hinter den Bereich mit Bodenberührung möglich ist; und

d) ein Antrieb, der mit dem bodenberührenden Modul verbunden ist, durch den Energie an das bodenberührende Modul in einer Weise liefer-bar ist, die auf die Lage des Schwerpunkts rea-giert, wobei eine sitzende Person die Vorrich-tung durch eine Bewegung des Sitzes in der Vorder-Hinterebene in Bezug auf die Plattform steuern kann.

2. Vorrichtung nach Anspruch 1, wobei die Stütze (34, 38, 46, 64) mit der Plattform an einem Drehpunkt (42) verbunden ist, der für eine Bewegung der Stütze (34, 38, 46, 64) um eine Achse ausgerichtet ist, die im Wesentlichen quer zu der Vorder-Hinterebene liegt.

3. Vorrichtung nach Anspruch 1, die weiterhin einen Griff (16) aufweist, der an der Plattform (12) befestigt ist, wobei der Griff einen Handgriff ungefähr in Bauchhöhe der Person so besitzt, dass die Vorrich-tung in einer Weise analog zu einem Roller bedient werden kann.

4. Vorrichtung nach Anspruch 1, wobei zu der Stütze eine Gelenkeinrichtung gehört, die für das Tragen eines Teils des Gewichts der Person vorgespannt ist.

5. Vorrichtung nach Anspruch 1, wobei die Stütze im Wesentlichen oberhalb des Bereichs des Boden-kontakts des bodenberührenden Moduls eine örtli-che Stabilitätsstellung aufweist.

6. Vorrichtung nach Anspruch 1, weiterhin aufwei-

5 send:

10 e) eine Kontrolleinrichtung, die mit dem moto-risierten Antrieb zur Regelung des Betriebs des motorisierten Antriebs, zumindest abhängig von der Stellung der Benutzerstütze verbunden ist.

15 7. Vorrichtung nach Anspruch 1, wobei die Stellung der Stütze bezüglich der Plattform durch Neigen des Anwenders verändert werden kann.

20 **Revendications**

15 1. Dispositif destiné à transporter une personne sur une surface, le dispositif comprenant :

20 a. une plate-forme (12) définissant un plan lon-gitudinal, la plate-forme supportant une charge utile comprenant la personne ;

25 b. un module de contact avec le sol, compre-nant un élément de contact avec le sol (32) couplé de façon mobile à la plate-forme, l'élément de contact avec le sol étant **caractérisé par** une région de contact avec le sol, la plate-for-me (12) et le module de contact avec le sol étant des composants d'un ensemble ayant un centre de gravité, le centre de gravité ayant une position définie par rapport à l'élément de con-tact avec le sol ;

30 c. un support (34, 38, 46, 64) comprenant un siège (34) destiné à supporter la personne, le support étant couplé à la plate-forme de maniè-re à permettre une variation de la position du centre de gravité dans le plan longitudinal par le mouvement du support vers l'avant et vers l'arrière de la région de contact avec le sol ; et

35 d. un dispositif d'entraînement, couplé au module de contact avec le sol, agencé pour déli-vrer de la puissance au module de contact avec le sol d'une manière répondant à la position du centre de gravité, moyennant quoi une person-ne assise peut commander le dispositif par le mouvement du siège dans le plan longitudinal par rapport à la plate-forme.

40 2. Dispositif selon la revendication 1, dans lequel le support (34, 38, 46, 64) est couplé à la plate-forme au niveau d'un pivot (42) orienté pour permettre le mouvement du support (34, 38, 46, 64) autour d'un axe sensiblement transversal au plan longitudinal.

45 3. Dispositif selon la revendication 1, comprenant en outre un manche (26), relié à la plate-forme (12), comportant une poignée à approximativement hau-teur de taille de la personne, de sorte que le dispo-sitif puisse être actionné d'une manière analogue à

un scooter.

4. Dispositif selon la revendication 1, dans lequel le support comprend un élément articulé (38), sollicité pour supporter une partie du poids de la personne. 5
5. Dispositif selon la revendication 1, dans lequel le support a une position de stabilité locale sensiblement au-dessus de la région de contact avec le sol du module de contact avec le sol. 10
6. Dispositif selon la revendication 1, comprenant en outre :
  - e. un dispositif de commande, couplé au dispositif d'entraînement motorisé, destiné à gouverner le fonctionnement du dispositif d'entraînement motorisé au moins en réponse à la position du support d'utilisateur. 15
7. Dispositif selon la revendication 1, dans lequel la position du support par rapport à la plate-forme peut varier par l'inclinaison de l'utilisateur. 20

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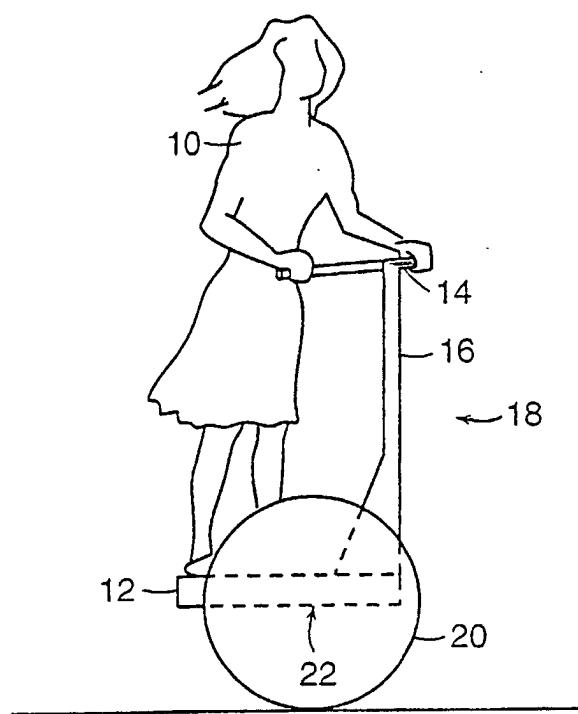


FIG. 1A  
PRIOR ART

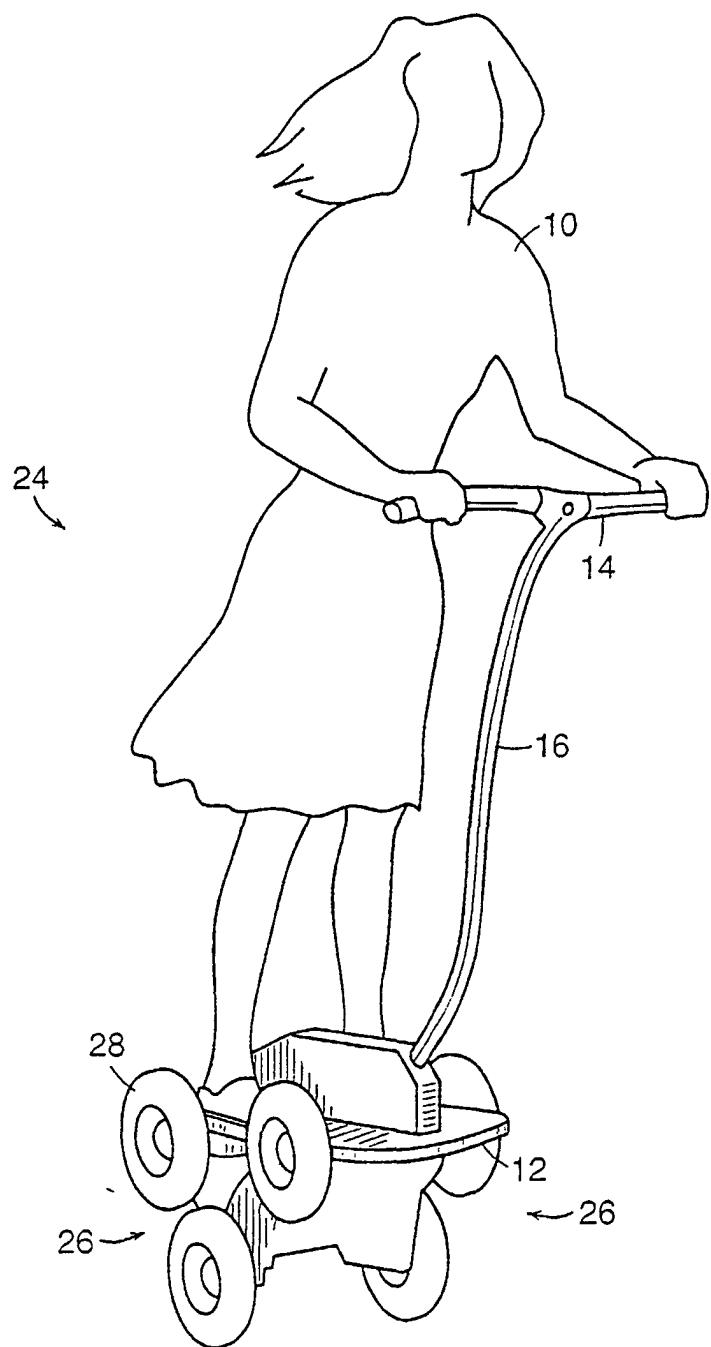


FIG. 1B  
PRIOR ART

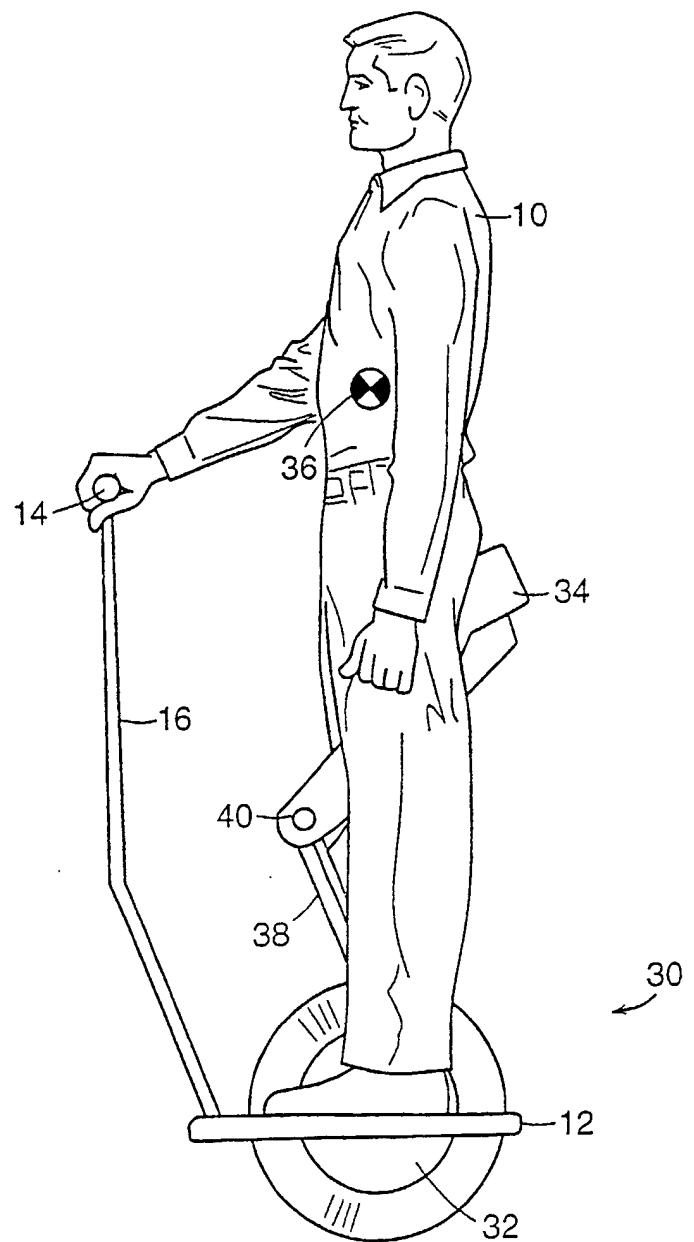


FIG. 2

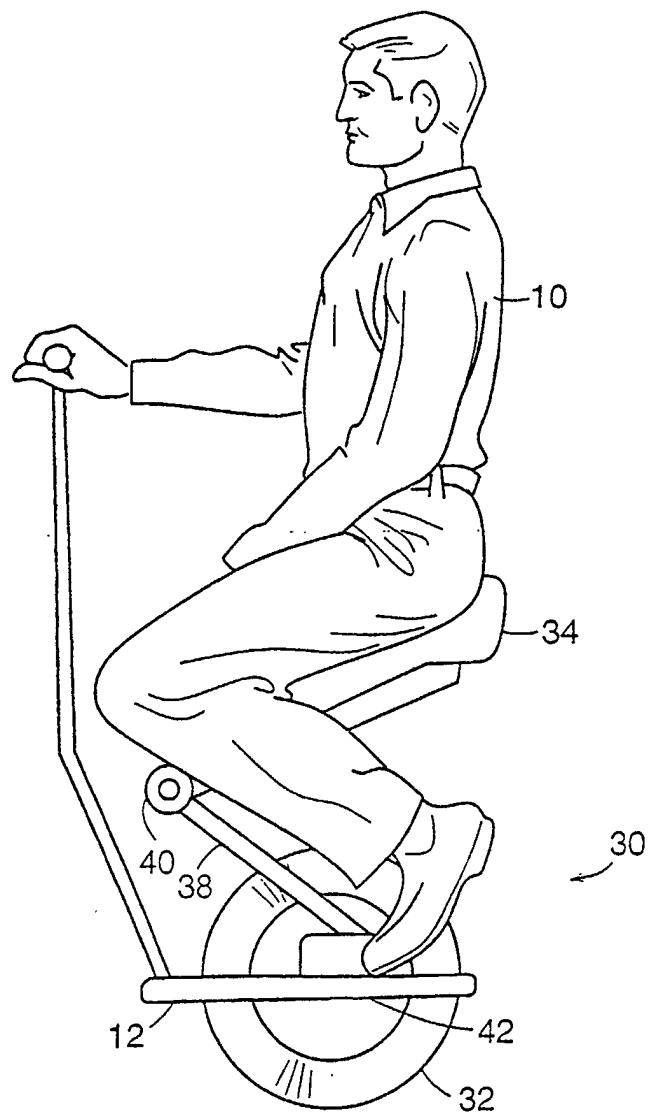


FIG. 3

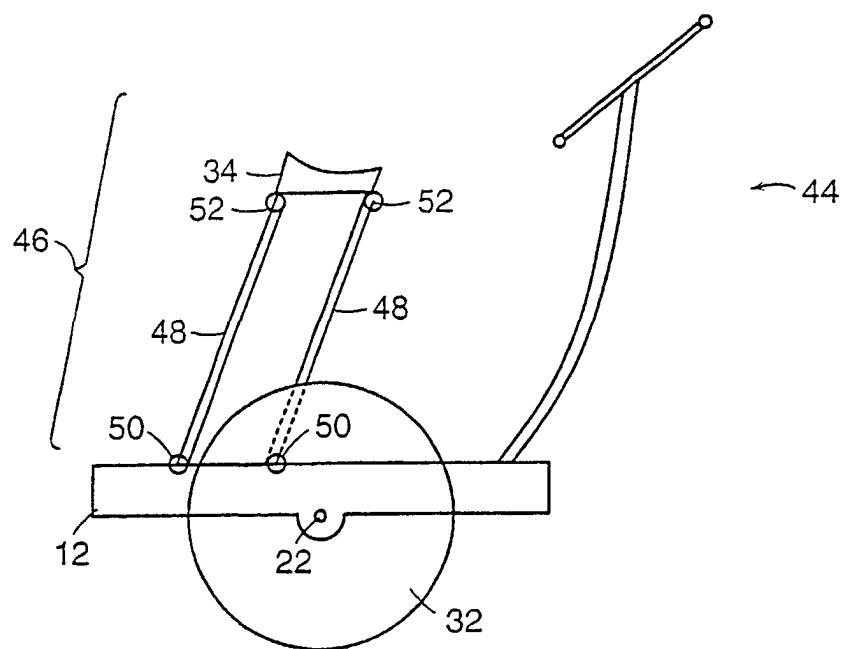


FIG. 4A

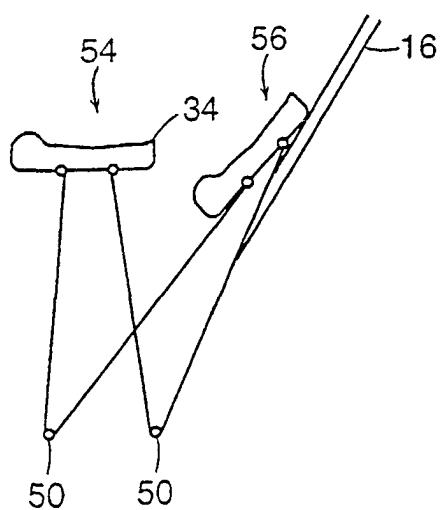


FIG. 4B

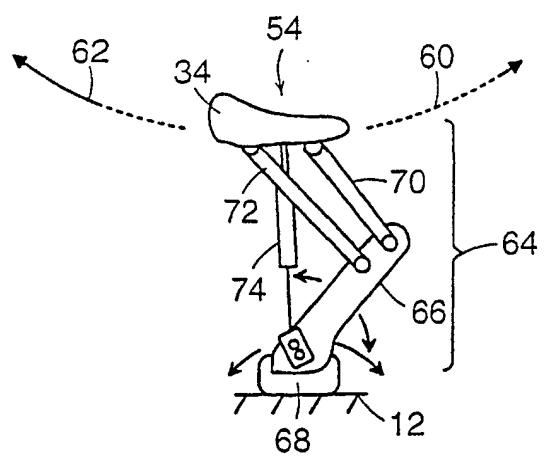


FIG. 5A

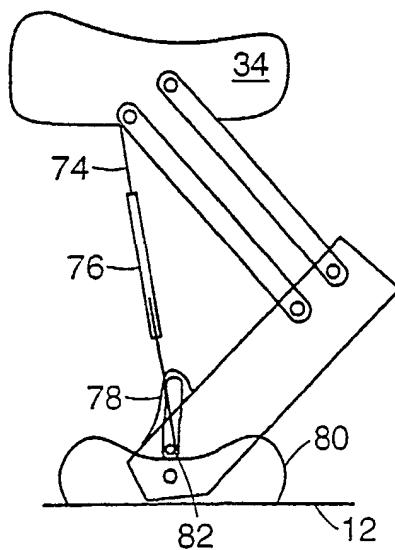


FIG. 5B