



US00D882659S

(12) **United States Design Patent**
Kawaguchi et al.

(10) **Patent No.:** **US D882,659 S**
(45) **Date of Patent:** **** Apr. 28, 2020**

(54) **JOINT DRIVING MEMBER FOR ROBOT**

(71) Applicant: **MITSUBISHI ELECTRIC CORPORATION**, Tokyo (JP)

(72) Inventors: **Noboru Kawaguchi**, Tokyo (JP); **Tomoya Hattori**, Tokyo (JP); **Masaki Haruna**, Tokyo (JP); **Koji Hirose**, Tokyo (JP); **Ken Ueda**, Tokyo (JP); **Shingo Kimura**, Tokyo (JP)

(73) Assignee: **Mitsubishi Electric Corporation**, Tokyo (JP)

(**) Term: **15 Years**

(21) Appl. No.: **29/664,938**

(22) Filed: **Sep. 28, 2018**

(30) **Foreign Application Priority Data**

Mar. 29, 2018 (JP) 2018-006785

(51) **LOC (12) Cl.** **15-99**

(52) **U.S. Cl.** **D15/199**
USPC

(58) **Field of Classification Search**
USPC D15/199; D21/369, 578-583, 621, 622
CPC B25J 9/102; B25J 9/104; B25J 17/0241;
Y10T 74/20317; Y10T 74/20323
See application file for complete search history.

(56) **References Cited**

U.S. PATENT DOCUMENTS

5,002,242 A * 3/1991 Nagai B25J 17/0241
248/49
5,099,707 A * 3/1992 Tori B25J 9/02
384/296
5,107,716 A * 4/1992 Torii B25J 9/02
384/296
5,119,753 A * 6/1992 Milad B23Q 1/5406
114/338

5,342,254 A * 8/1994 Sula B25J 9/102
475/223
5,593,293 A * 1/1997 Machino B25J 9/0009
414/729
5,740,699 A * 4/1998 Ballantyne B25J 17/0266
403/120
5,893,296 A * 4/1999 Rosheim G05G 5/03
74/490.03
6,151,981 A * 11/2000 Costa B25J 9/023
74/490.03
6,220,813 B1 * 4/2001 Launiere B23Q 1/50
198/468.6

(Continued)

Primary Examiner — Patricia A Palasik

(74) *Attorney, Agent, or Firm* — Studebaker & Brackett
PC

(57) **CLAIM**

The ornamental design for a joint driving member for robot, as shown and described.

DESCRIPTION

FIG. 1 is a first perspective view of the front, left, and top sides of a joint driving member for robot showing our new design;

FIG. 2 is a second perspective view of the rear, right, and bottom sides thereof;

FIG. 3 is a third perspective view of the front, left, and bottom sides thereof;

FIG. 4 is a front view thereof;

FIG. 5 is a rear view thereof;

FIG. 6 is a left side view thereof;

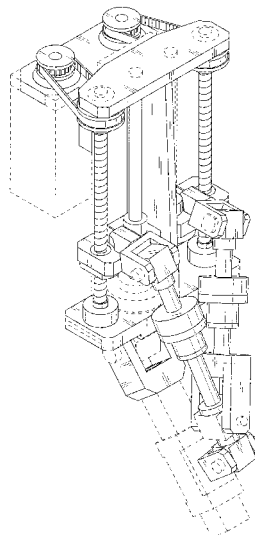
FIG. 7 is a right side view thereof;

FIG. 8 is a top plan view thereof; and,

FIG. 9 is a bottom plan view thereof.

The broken lines in the drawings represent portions of the joint driving member for robot and form no part of the claimed design. The dash-dot lines represent the boundary between the claimed design and unclaimed design and form no part of the claimed design.

1 Claim, 9 Drawing Sheets



US D882,659 S

Page 2

(56)

References Cited

U.S. PATENT DOCUMENTS

6,240,799	B1 *	6/2001	Yau	B23Q 1/5462	2012/0011956	A1 *	1/2012	Lundberg	B25J 9/04
				74/479.01					74/490.03
7,013,750	B1 *	3/2006	Kazami	B25J 9/08	2012/0048047	A1 *	3/2012	Zhang	B25J 9/046
				74/490.03					74/425
9,512,912	B1 *	12/2016	Edsinger	F16H 48/12	2012/0067150	A1 *	3/2012	Zhang	B25J 9/102
9,568,074	B2 *	2/2017	Gosselin	B25J 9/102					74/423
9,849,925	B2 *	12/2017	Outa	B62D 53/02	2012/0204670	A1 *	8/2012	Ryland	B08B 9/045
10,040,206	B2 *	1/2018	Jeong et al.						74/490.03
D810,801	S *	2/2018	Hsu et al.		2012/0271207	A1 *	10/2012	Schoen	A61F 5/0102
10,144,464	B1 *	12/2018	Buerger et al.						601/34
D847,238	S *	4/2019	Kawaguchi	D15/199	2012/0291582	A1 *	11/2012	Kang	B25J 19/0016
D847,239	S *	4/2019	Kawaguchi	D15/199					74/490.03
D847,240	S *	4/2019	Kawaguchi	D15/199	2013/0104676	A1 *	5/2013	Yang	B25J 9/06
D847,241	S *	4/2019	Kawaguchi	D15/199					73/865.8
D847,242	S *	4/2019	Kawaguchi	D15/199	2013/0282174	A1 *	10/2013	Xi	B25J 9/1682
2002/0078778	A1 *	6/2002	Grover	B25J 9/042					700/248
				74/490.03	2013/0296746	A1 *	11/2013	Herr	A61H 3/00
2005/0275367	A1 *	12/2005	Buehler	B25J 9/102					601/34
				318/568.12	2014/0007730	A1 *	1/2014	DeLouis	B25J 15/0009
2007/0062321	A1 *	3/2007	Chablat	B23Q 1/5462					74/490.03
				74/479.01	2014/0123800	A1 *	5/2014	Choi	F16H 48/10
2009/0308188	A1 *	12/2009	Yang	B25J 9/104					74/490.03
				74/89.27	2014/0213409	A1 *	7/2014	Yoon	F16H 1/203
2010/0122602	A1 *	5/2010	Marcroft	B25J 17/0216					475/343
				74/490.03	2015/0114163	A1 *	4/2015	Rosheim	B25J 9/0045
2010/0162846	A1 *	7/2010	Lee	B25J 9/1045					74/490.03
				74/490.04	2015/0122071	A1 *	5/2015	Lee	B25J 9/06
2010/0170357	A1 *	7/2010	Kim	B25J 9/102					74/490.04
				74/89.32	2015/0190246	A1 *	7/2015	Ryu	G06F 3/011
2011/0048158	A1 *	3/2011	Maisonnier	B25J 17/0275					74/89.22
				74/490.03	2015/0272811	A1 *	10/2015	Choi	B25J 17/00
2011/0056321	A1 *	3/2011	Sim	B25J 9/1025					623/27
				74/490.04	2016/0038313	A1 *	2/2016	Kim	B25J 9/102
2011/0067518	A1 *	3/2011	Park	B25J 9/102					623/24
				74/490.04	2016/0114479	A1 *	4/2016	Rosheim	B25J 9/0075
2011/0113914	A1 *	5/2011	Zhang	B25J 9/107					74/490.03
				74/490.01	2016/0288319	A1 *	10/2016	Kfoury	B25J 9/104
2011/0126651	A1 *	6/2011	Pan	B25J 9/102					5/2017
				74/89.2	2017/0120453	A1 *	5/2017	Roy	B25J 5/04
2011/0137423	A1 *	6/2011	Ouyang	B25J 9/102					10/2017
				623/18.11	2017/0297197	A1 *	10/2017	King	B25J 9/126
2011/0214524	A1 *	9/2011	Jacobsen	A61F 2/68					11/2017
				74/490.04	2017/0319421	A1 *	11/2017	Julin	A61H 3/00
2011/0314949	A1 *	12/2011	Long	B25J 19/0029					12/2017
				74/490.04	2017/0348852	A1 *	12/2017	Sarh	B25J 9/106
					2018/0009116	A1 *	1/2018	Jeong et al.	
					2018/0079084	A1 *	3/2018	Woo et al.	
					2018/0133894	A1 *	5/2018	Choi et al.	
					2018/0140441	A1 *	5/2018	Poirters	
					2018/0193172	A1 *	7/2018	Smith et al.	
					2018/0236655	A1 *	8/2018	Nakanishi	

* cited by examiner

FIG. 1

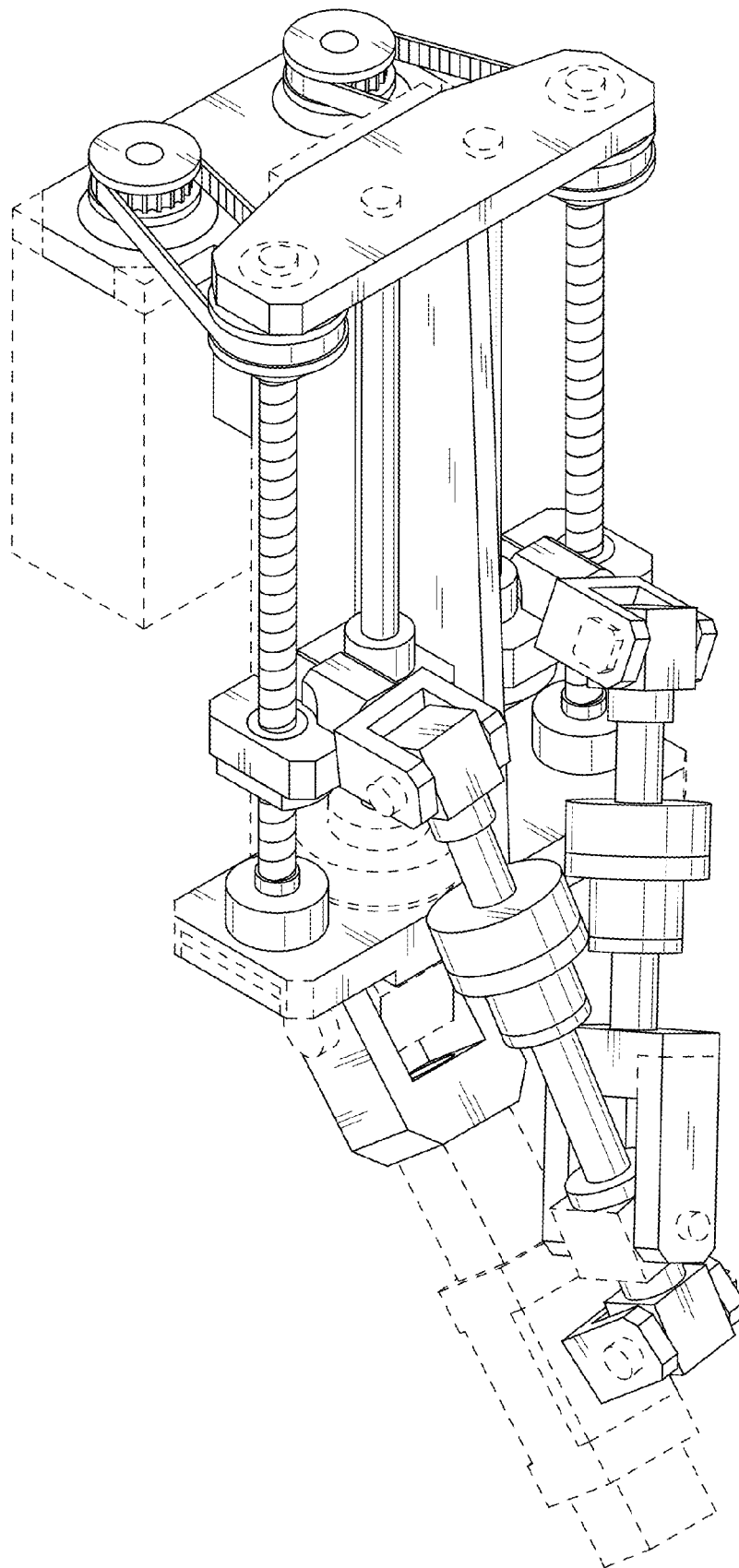


FIG. 2

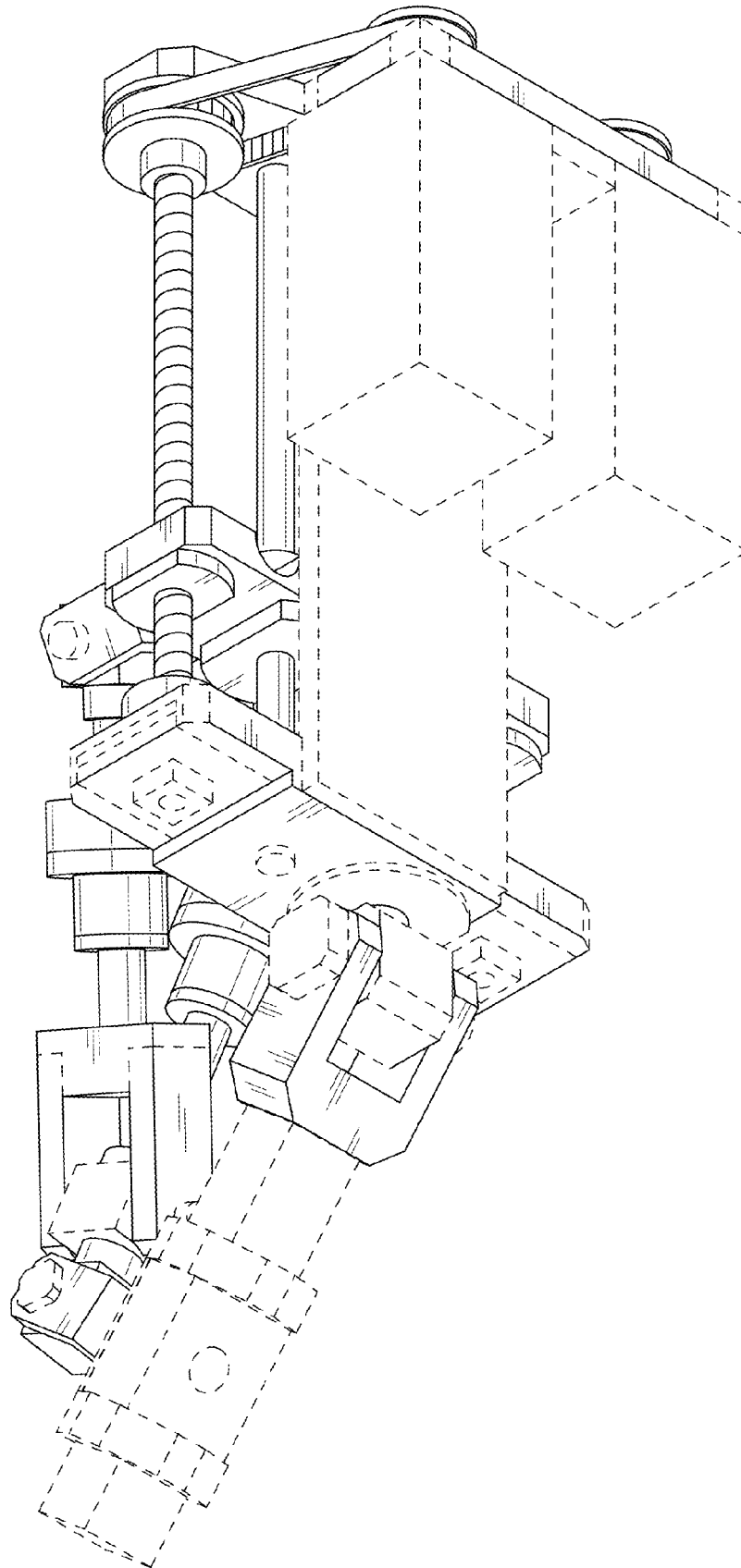


FIG. 3

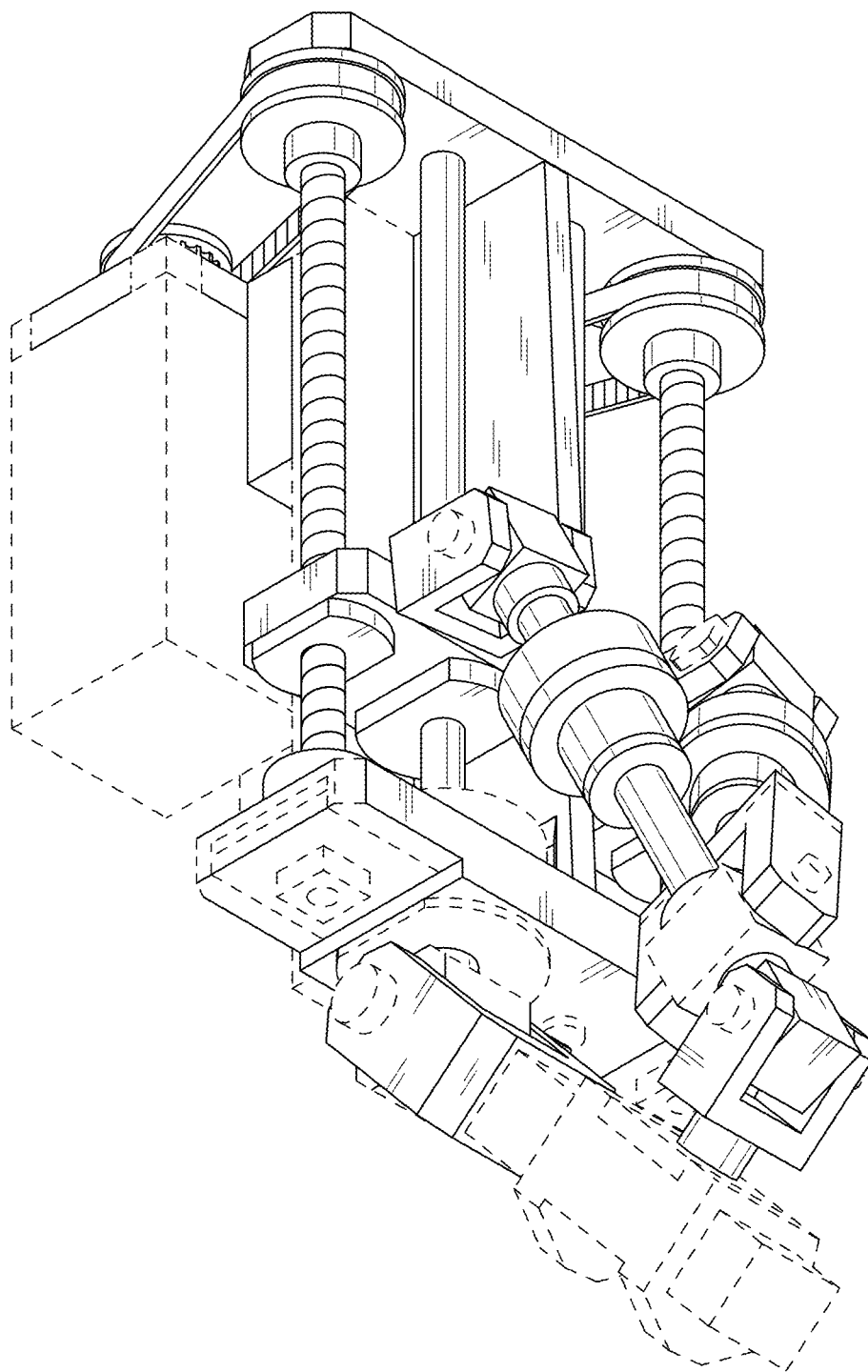


FIG. 4

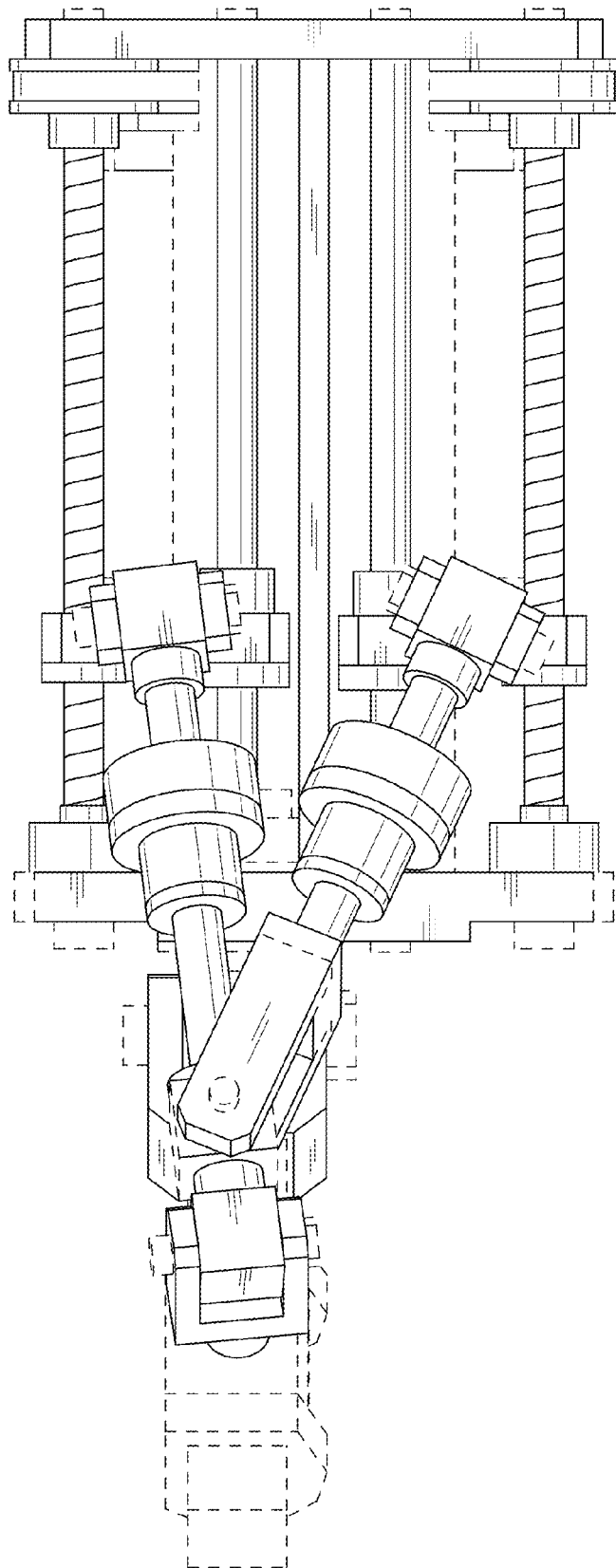


FIG. 5

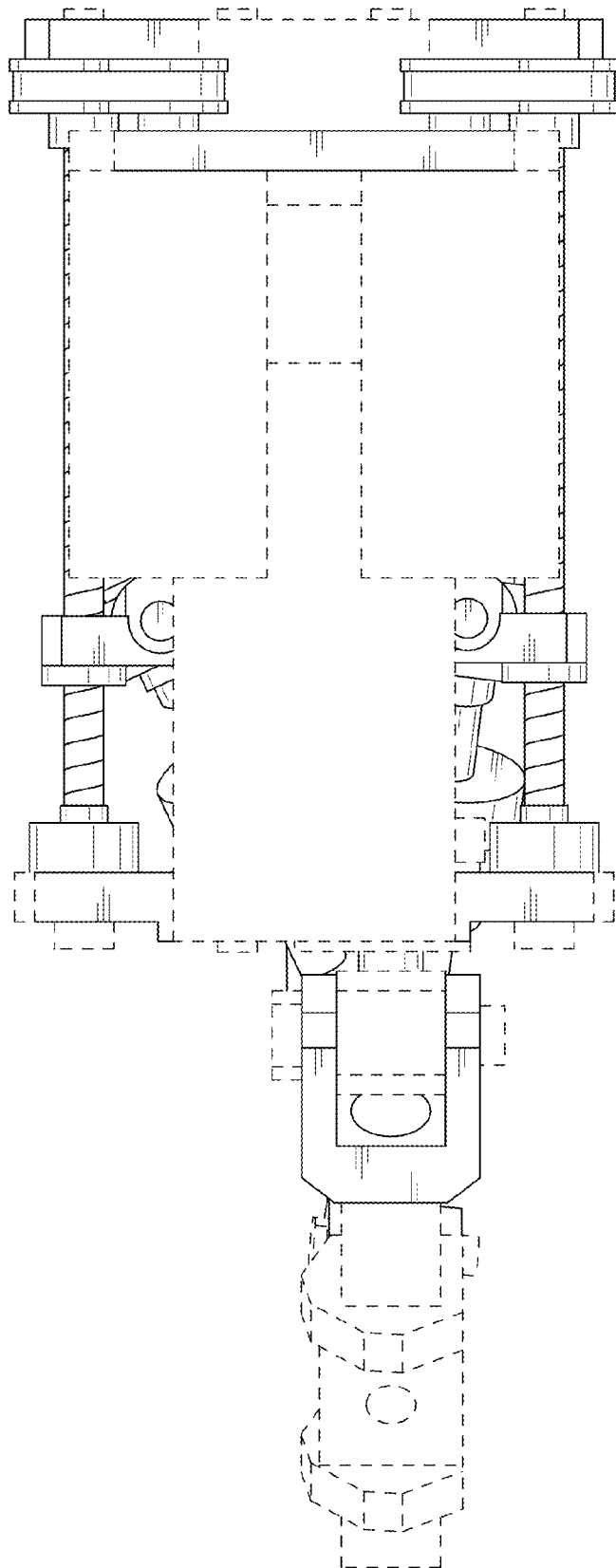


FIG. 6

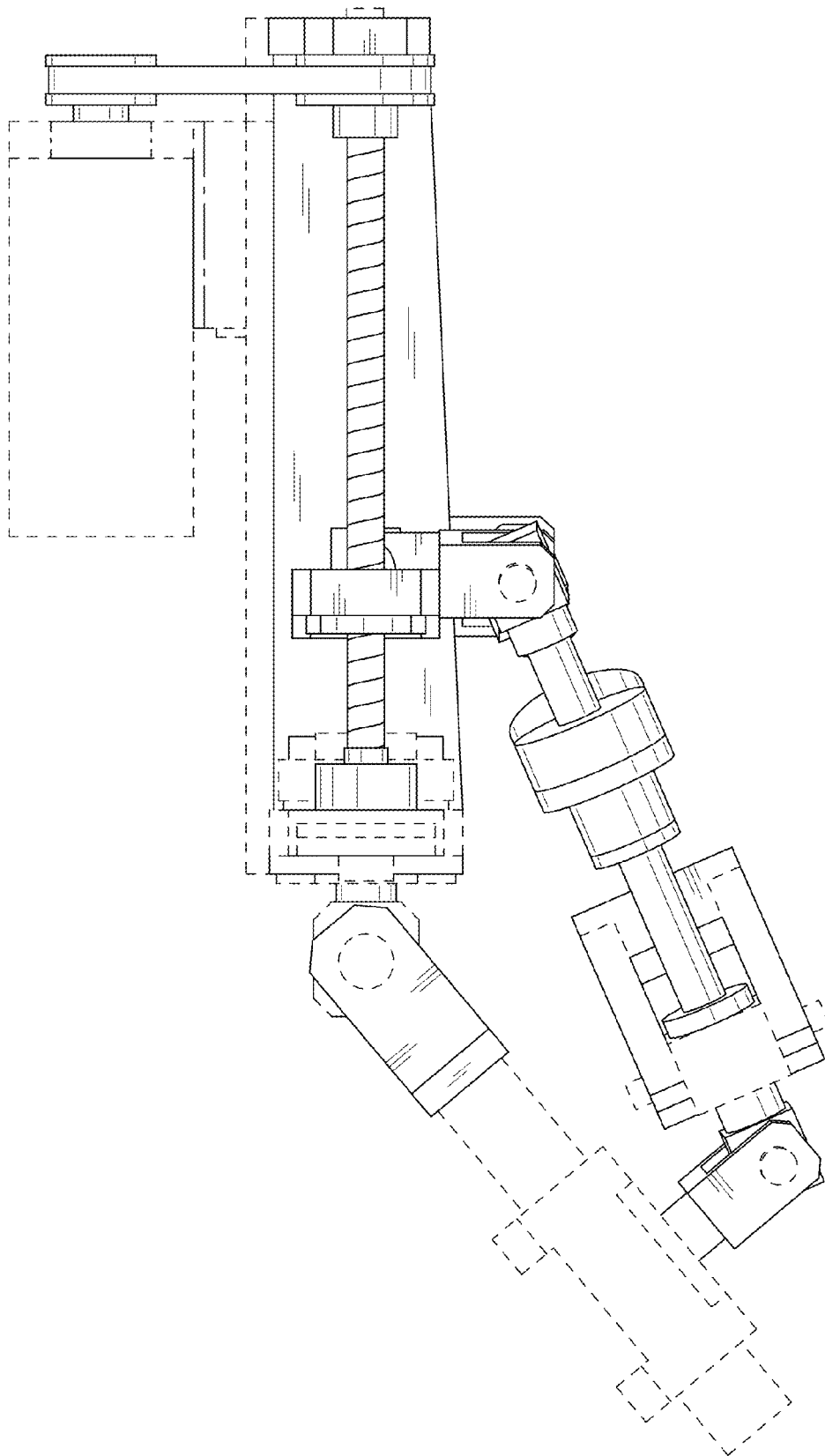


FIG. 7

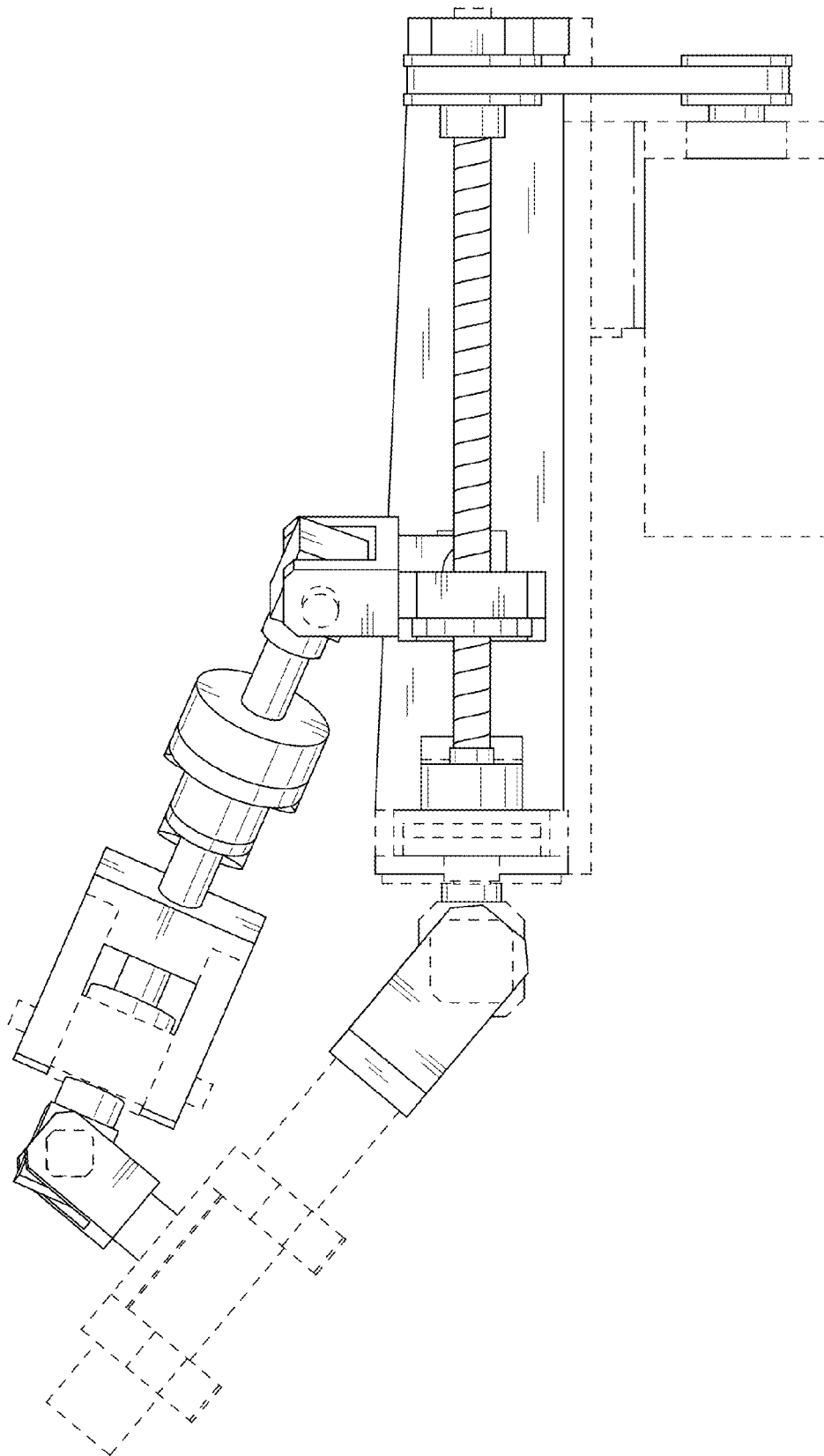


FIG. 8

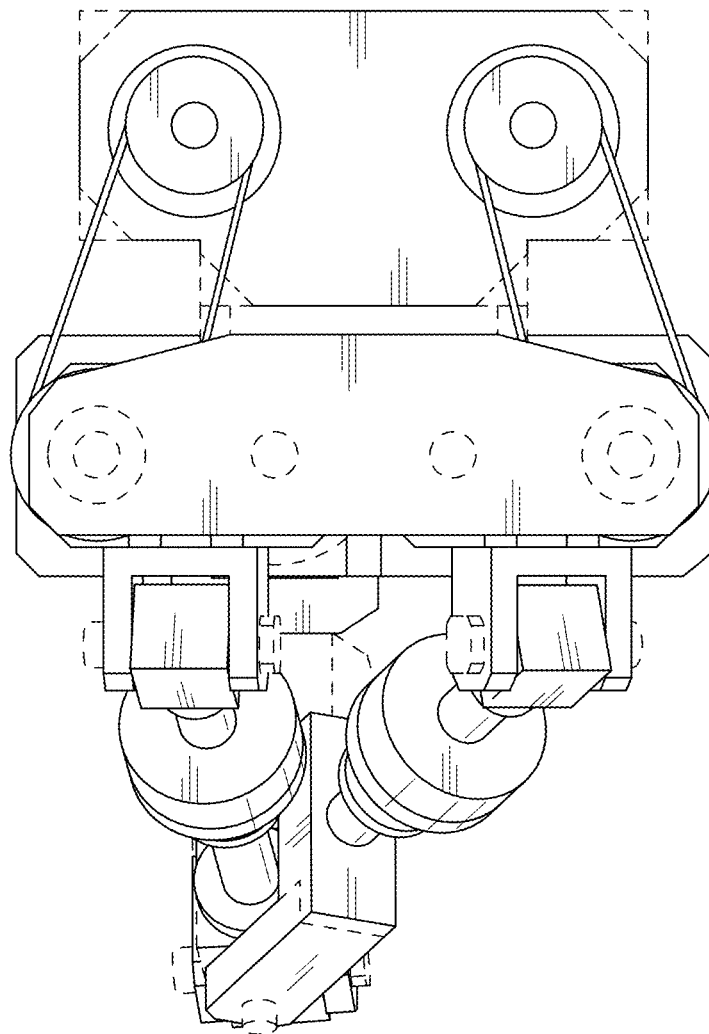


FIG. 9

