XR 3,762,496

United States Patent [19]

Milb

Milberger et al.

3,762,496 Oct. 2, 1973

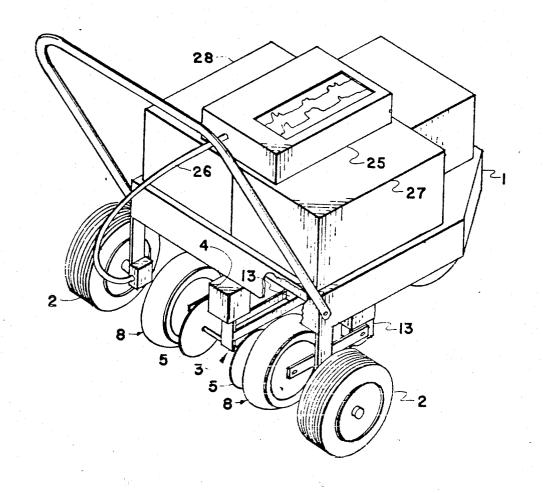
[54]	DELAMINATION DETECTOR
[75]	Inventors: Lionel J. Milberger; Gilbert Swift, both of Bryan; William M. Moore, College Station, all of Tex.
[73]	Assignee: Martin Tracker Corporation, College Station, Tex.
[22]	Filed: Sept. 1, 1971
[21]	Appl. No.: 176,906
[52]	U.S. Cl
[51]	Int. Cl. G01n 29/04
[58]	Field of Search
	181/.5 EC, .5 NP; 73/70
[56]	References Cited
	UNITED STATES PATENTS
3,361,2	25 1/1968 Nichols 73/70
3,301,3	45 1/1967 Carder 181/.5 VM

Primary Examiner—Benjamin A. Borchelt Assistant Examiner—J. V. Doramus Attorney—William M. Moore

## [57] ABSTRACT

To detect the presence of certain types of hidden flaws within a material having an exposed surface, the surface is tapped at one location to produce sonic vibrations within the material. At another location, an acoustic receiving transducer is coupled to the surface of the material being tested. A characteristic of the electrical signals produced by the transducer which is indicative of the type of flaw to be detected is utilized to denote the presence of a flaw. A mobile form of apparatus which detects flaws while traversing the surface of the material and which indicates the location as well as the existence of the flaws is described.

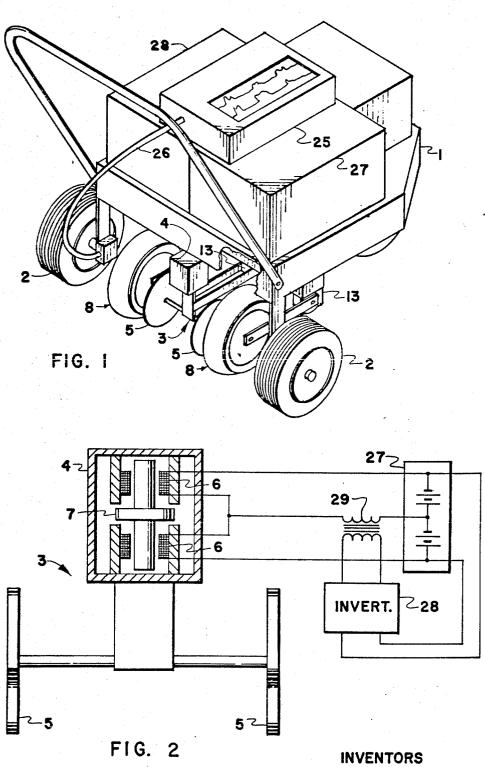
## 8 Claims, 5 Drawing Figures



Á.

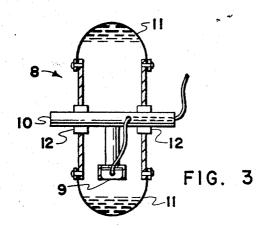
Amount the real

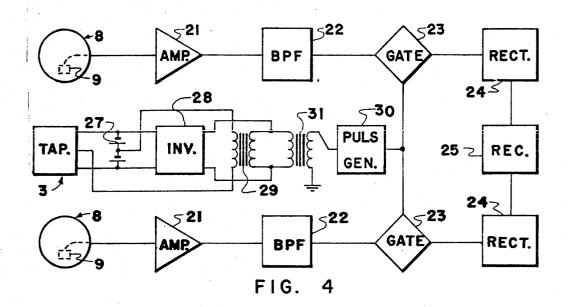
SHEET 1 OF 2



LIONEL J. MILBERGER
GILBERT SWIFT
WILLIAM M. MOORE

## SHEET 2 OF 2





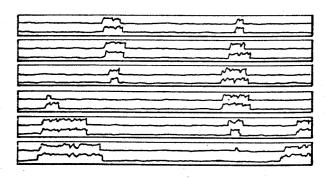


FIG. 5

INVENTORS
LIONEL J. MILBERGER
GILBERT SWIFT
WILLIAM M. MOORE

## **DELAMINATION DETECTOR**

The present invention relates to a method and apparatus for detecting the presence of hidden flaws within a concrete bridge deck or other mass of material. The type of flaw which it is desired to detect consists of a 5 separation of the material beneath the surface into two or more layers, or the presence of a lack of bond between two or more layers of a laminated material. Such separations are commonly called delaminations and the called delaminated areas. Delamination is one of the more commonly occurring defects in concrete bridge decks. It is encountered most frequently in localities where freeze-thaw conditions prevail during some portion of the year. As a consequence of becoming delaminated the concrete bridge deck deteriorates rapidly to the point of requiring extensive repair or replacement. Early detection of the delaminated areas permits remedial action to be applied at these areas in time to prevent the further progress of the deterioration and thus 20 contributes to more economical bridge maintenance.

A similar form of separation occurs in rocks which form the ceiling of mine passages and tunnels. The safety of persons within these spaces is endangered by the presence of such flaws since the flaws tend to grow larger and eventually result in a fall of rock from overhead. Accordingly, it is desirable both on bridge decks and tunnel ceilings to detect and to map out the delamiin order to evaluate the growth, if any, of these areas.

Another similar form of delamination occurs in laminated structural forms like the honeycomb panels often used in aircraft construction and in plywood. A fabrication problem in such laminates is that of securely bond- 35 ing the layers. Lack of bonding produces weak points in the laminates and can result in serious structural failure:

In the past, detection of delamination has been accomplished by tapping the exposed surface of the sus- 40 pected material with a rod, hammer, or similar striking object while listening with the ear for a distinctive type of sound which has been found to occur when the material is delaminated beneath the tapped area. This characteristic sound is generally described as a "hol- 45" low" sound. The reliability of this subjective method of detection leaves much to be desired since it depends greatly upon the experience and judgement of the observer and is also highly dependent upon the characteristics of the object used to perform the tapping. Sticks 50and rods, for example produce a sound related to their own mass and length regardless of what material they are tapped against and this sound often overshadows the sound produced by the delaminated material. A steel ball-like mass tied at the end of a soft rope has 55 been found to produce very little sound when struck against a solid deck but to produce a loud distinctive sound when struck against a delaminated area. A mobile device, developed by the Research Department of the Kansas State Highway Commission, strikes the 60 deck at regular intervals with small wooden blocks. This device permits surveying large areas quickly; however, the wooden blocks are somewhat resonant which impairs interpretation. Nichols, U.S. Pat. No. 65 3,361,225 describes a metal pegged wheel, an acoustic pickup on the handle eliminates subjective judgment; however, this type of mechanism generates a large

amount of signal on bonded panels and hence has poor contrast between bonded and unbonded areas.

Accordingly, with these difficulties and shortcomings in mind the present invention was conceived. Basically, the invention operates by repetitively tapping the surface of the material in a controlled uniform manner and by coupling an acoustic receiving transducer to the surface of the material a small fixed distance away from the point at which it is being tapped. This distance is zones on the surface beneath which they occur are 10 chosen in relation to the minimum size of the delaminated area which it is desired to detect, since, for most reliable detection, both the tapping point and the receiving point should be within the surface area beneath which the delamination extends. A certain finite spacing is important to eliminate from the receiving transducer output a large component of signal which would be present if the receiving transducer were to be directly coupled to the tapping mechanism. This large component of signal would exist whether or not the material were delaminated and would impair, if not overshadow, the response of the receiving transducer to the presence of the delamination. Accordingly, spacings from as close together as two separate mechanisms can be put into contact with the surface without touching one another, which spacings are of the order of 1 or 2 inches, up to spacings of several feet may be used. With a spacing of 2 inches the device can detect delaminated areas as small as 2 inches in width. If a spacing of two nated areas and to repeat this process from time to time across a width of 2 feet or more. Provisions are also feet is used the detected areas will in general extend made in the design of the apparatus to minimize the response of the receiving transducer to sound waves arriving through the air or through the framework of the apparatus which supports and maintains the tapping mechanism and the receiving transducer in contact with the surface being tested. The apparatus is designed to maintain contact with the surface and to operate continuously while progressing along the surface of the material being tested.

It is an object of the invention to provide an improved method and apparatus for detecting and automatically indicating the presence of delamination beneath the surface of a material.

It is another object to automatically record the relative magnitude and the position of delaminated areas along a path of travel along a surface.

It is a further object to provide a method and apparatus which responds to delamination without having appreciable response to external noise, or to other surface effects such as the roughness of the surface of the mate-

It is a still further object to provide an improved method and apparatus for the detection of delamination in a mobile manner while traversing the surface of

How these various objects are achieved by the method and apparatus of the present invention will become apparent when the following description is read in conjunction with the drawings in which

FIG. 1 is a pictorial view of one embodiment of the present invention.

FIG. 2 is a diagrammatic view illustrating the details of the tapping assembly.

FIG. 3 is a sectional view showing the construction of the acoustic receiver wheel.

FIG. 4 is a block schematic diagram of the electronic signal processing portions of the apparatus.

FIG. 5 is a typical set of successive recordings, made along parallel paths, placed side by side to form a visual map of the delaminated areas detected by the appara-

The device, as shown in FIG. 1, comprises a small 5 three-wheeled cart 1, which forms a support and carriage for the other portions of the apparatus. Beneath the cart 1, in line with its rear support wheels 2, a tapping assembly 3 having two steel wheels 5 is supported tested. An electrically operated vibrator mechanism 4 causes the two steel wheels 5 of the tapping assembly 3 to chatter against the surface of the material being tested. The vibrator mechanism 4, as shown in FIG. 2, raise and lower a magnetic core 7 which strikes violently against a stop at each end of its travel. The solenoid coils 6 are biased with direct current from battery 27 and are energized with 60 cycles per second alterto maintain the oscillatory hammer-like action of the magnetic core 7. As a result of this repetitive vibration the entire tapping assembly 3 is lifted out of contact with the surface sixty times each second. It returns each time to strike the surface at the points of contact of its 25 steel wheels 5 with the surface of the material being tested. Although other types of tapping mechanisms were found to be satisfactory, for example, a motor driven tapper, or even a rolling spur gear, the above described mechanism was found to best excite the charac- 30 teristic hollow sound.

Two acoustic receiver wheels 8 are also supported from the cart, in line with rear support wheels 2, each wheel spaced a few inches away from one of the tapping wheels 5. Referring now to FIG. 3, the acoustic receiving wheels 8 each contain an acoustic receiving transducer 9 which is mounted to a fixed axle 10 and thereby held at a substantially fixed height above the surface. The receiving wheels 8 are liquid-filled to provide good acoustic coupling between the transducer 9  $^{\,40}$ and the surface being tested and are equipped with thin inner-tube like rubber tires 11 which conform to any surface irregularities and maintain good acoustic coupling. The wheel 8 is free to rotate while the axle 10, which passes through sealed bearings 12, is maintained in fixed orientation so that the transducer 9 is always in close proximity to the surface. A transducer mounted directly on the axle of a solid aluminum wheel having a thin rubber tread was also found to make a satisfactory receiving wheel; however, it did not minimize 50 the surface texture noise effects as well as the liquid filled receiving wheel described.

It will be apparent that acoustic vibrations introduced into the material by the tapping action of wheels 5 will be received from the material by the transducers 9. However, it is also apparent that vibrations might travel through the frame and supporting members of the cart 1 from the tapping assembly 3 to the transducers 9 within the receiving wheels 8. Coupling of this nature is avoided by isolating the tapping assembly 3 from the cart I and separately isolating the receiving wheels 8 from the cart 1 by means of vibration isolators 13. Acoustic coupling through the air between the tapping assembly 3 and the receiving transducers 9 is minimized by having transducers 9 immersed in liquid which, through the thin rubber tire 11, is well coupled to the surface of the material being tested.

Response of the transducers 9 to surface roughness and to motion of the apparatus along the surface is minimized with respect to their response to the presence of delamination by accepting only those portions of the electrical signals produced by the receiving transducers 9 which meet specific criteria. These criteria are adjustable, but it has been found optimum, when using the apparatus on concrete bridge decks, to accept only signals which occur during the first 3 milliseconds after in rolling contact with the surface of the material to be 10 the surface has been tapped, and of these signals only those frequency components which fall between 300 and 1,200 Hertz.

Thus, there is only a brief period after each tap during which the transducers 9 are allowed to influence comprises a pair of solenoid coils 6 which alternately 15 the indications derived from their response. This fact tends to greatly suppress all unwanted types of response which are of a sustained nature. As shown in FIG. 4, the signals from the receiving transducers 9 are processed in conformance with the foregoing requirenating current from inverter 28 through transformer 29:20 ments by passing them separately through individual electronic amplifiers 21. Each amplifier 21 is associated with a filter 22 which passes only frequencies between 300 and 1,200 Hz. The output of each filter 22 is blocked by a gate 23 which is opened by a pulse from pulse generator 30 for a brief interval synchronized with the action of the tapper 3 by a voltage from transformer 31. Transformer 31 is energized along with transformer 29 by inverter 28. The signals passing through gates 23 are rectified by rectifiers 24 to produce two uni-polar output voltages proportional to the respective magnitudes of the processed transducer signais. These two output voltages can be displayed on indicating meters to signify the presence and magnitude of any detected delamination, but in the more customary apparatus a pen-recorder 25 having right and left recording channels is used to produce a permanent record of these voltages. The chart paper of the recorder 25 is driven in proportion to distance traversed by the cart through an odometer mechanism 26 driven by one of the supporting wheels 2. Thus, upon traversing a bridge-deck with the cart 1, a strip-map showing any delaminated areas encountered along this particular traverse is produced on the chart of recorder 25. As shown in FIG. 5, a succession of such records, with each traverse offset laterally a given distance, may be placed side by side to provide a visual map of the deck indicative of the size and position of the detected areas.

Power for operating the apparatus is obtained from a storage battery 27 and an inverter 28 which converts the 12 volt direct current of the battery to alternating current of 115 volts at 60 Hz. Thus, the entire apparatus is selfcontained and is operable in remote locations while moving as well as while standing still.

What is claimed is:

1. In an apparatus for detecting subsurface delaminations and flaws in a material, the improvement compris-

force applying means delivering to the surface of the material sharp, short duration, repetitive, force impulses having sufficient energy to excite therein vibrations between 300 and 1,200 Hz which are characteristic of the separation of the material into two or more unbonded layers;

vibration receiving transducer means acoustically coupled to the surface of the material for receiving said vibrations and producing therefrom electrical signals characteristically related to said vibrations,

said coupling being at a location spaced from the location at which the force applying means acts upon the material, said spacing being comparable with the dimension of the minimum area of a delamination or flaw which it is desired to detect; and indicating devices responsive to a characteristic of said electrical signals.

2. The apparatus set forth in claim 1 including an electrical circuit for time-gating, frequency-filtering, rectifying and integrating the electrical signals.

3. The apparatus set forth in claim 1 mounted in a mobile vehicle.

4. The apparatus set forth in claim 3 including acoustic isolating means interposed between the force applying means and the receiving transducer means whereby 15 vibrations produced by the force applying means are prevented from reaching the transducer means except by travelling through the material.

5. The apparatus set forth in claim 3 wherein the indicating devices include a chart recorder having a drive 20 which is connected to the mobile vehicle to indicate the travel thereof.

6. In a mobile vehicle for detecting subsurface delaminations and flaws in a material, the improvement comprising:

force applying means acting upon the surface of the material through a rigid wheel, said means delivering sharp, short-duration, repetitive, force impulses having sufficient energy to excite within the material vibrations between 300 to 1,200 Hz which are characteristic of the separation of the material into two or more unbonded layers;

vibration receiving transducer means acoustically cating devices coupled to the surface of the material for receiving which is conne said vibrations and producing therefrom electrical 35 travel thereof. signals characteristically related to said vibrations,

said transducer means being acoustically coupled to the material through a liquid-filled wheel at a location spaced from the location at which the force applying means acts upon the material, said spacing being comparable with the dimension of the minimum area of a delamination or flaw which it is desired to detect;

indicating devices responsive to a characteristic of said signals;

signal processing means containing electrical circuits for time-gating whereby only those portions of the electrical signals which occur during the first three millisecond time interval following the application of the force to the material are permitted to affect the indicating devices;

electrical circuits for frequency-filtering whereby only those portions of the electrical signals which fall within the band 300 to 1,200 Hz are permitted to affect said indicating devices; and

electrical rectifying and integrating circuits which develop a uni-polar sustained output signal related to those portions of the electrical signals which are permitted to affect said indicating devices.

7. The apparatus set forth in claim 6 including at least 25 two separate acoustic isolating devices at least one of which is interposed between the force applying means and the vehicle and at least one other of which is interposed between the vehicle and the receiving transducer means, whereby vibrations produced by the force applying means are prevented from reaching the transducer means except by travelling through the material.

8. The apparatus set forth in claim 6 wherein the indicating devices include a chart recorder having a drive which is connected to the mobile vehicle to indicate the travel thereof.

40

45

50

55

60