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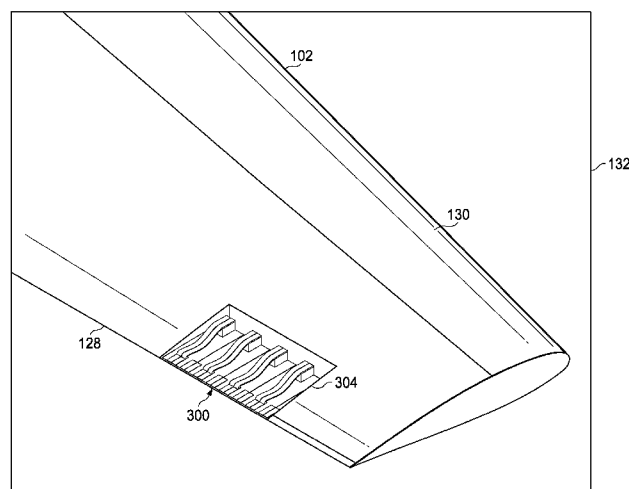


FIG. 3

(57) Abstract: Method and apparatus for controlling a shape of a composite structure. A shape memory structure associated with the composite structure is activated. The shape memory structure changes from a buckled shape to an original shape and causes the composite structure to change from an undeformed shape to a deployed shape. The shape memory structure is deactivated. The shape memory structure changes from the original shape to the buckled shape in response to a load from the composite structure and causes the composite structure to change from the deployed shape to the undeformed shape.



SHAPE MEMORY ALLOY ACTUATOR SYSTEM FOR COMPOSITE AIRCRAFT STRUCTURES

BACKGROUND INFORMATION

1. Field:

The present disclosure relates generally to aircraft and, in particular, to actuators for aircraft. Still more particularly, the present disclosure relates to a method and apparatus for controlling the shape of a composite structure with a shape memory alloy actuator.

2. Background:

The flight of an aircraft is controlled by airfoil structures. An airfoil structure is a part of an aircraft that may provide aerodynamic performance for the aircraft. An airfoil structure may be, for example, a wing or blade. The design and shape of airfoils may generate lift, control stability, change direction, change drag, or change other suitable aerodynamic parameters for an aircraft.

Flight control surfaces on an airfoil structure of an aircraft may be used to change the direction of an aircraft. Different control surfaces such as, for example, an aileron, an elevator, a rotor, a trim, a rudder, a spoiler, a flap, a slat, or other suitable control surfaces may be moved to change the shape of an airfoil structure to provide for different axes of motion for the aircraft. These control surfaces may be used to optimize the aerodynamic surfaces of an airfoil structure.

For example, a slat may be located at a leading edge of an airfoil structure in the form of a wing. A slat is an extension to the front of a wing to provide lift augmentation. Further, a slat may reduce a stalling speed by altering airflow over the wing.

Movement of this type of control surface, as well as other control surfaces, during flight may be performed to maximize the handling and performance of the aircraft. For example, a wing may be configured to have a sleek leading edge for high-speed flight. The wing may be reconfigured to have a blunt leading edge for low-speed flight.

When modifying the shape of an airfoil structure, it is desirable to maintain aerodynamic flow, while minimizing drag and turbulence over the airfoil structure. One manner in which this characteristic may be achieved is to maintain a contiguous surface

on the skin of the airfoil structure without disruptions around the airfoil structure in the form of gaps. Current airfoil structure changing systems for leading edge wings include extension or unfolding mechanisms that protrude into the airstream to modify aerodynamic characteristics. These types of systems, however, create voids in the continuity of the skin on the airfoil structure that can generate turbulence.

Further, other airfoil structure shape changing systems may allow the changing of the shape of the leading edge. These types of systems, however, use complicated actuator systems and often take more room than desired and weigh more than desired. In some cases, the size and complexity of the actuator system preclude their use with wings that are too thin to provide the room needed for the actuator systems. Therefore, it would be desirable to have a method and apparatus that take into account at least some of the issues discussed above, as well as other possible issues.

SUMMARY

An embodiment of the present disclosure provides an apparatus comprising a composite structure for an airframe of an aircraft and a shape memory structure associated with the composite structure. The shape memory structure has a buckled shape in a deactivated state such that the composite structure has an undeployed shape. The shape memory structure has an original shape when in an activated state such that the composite structure has a deployed shape. The composite structure applies a load against the shape memory structure.

Another embodiment of the present disclosure provides an aerodynamic control system comprising a composite structure on an airfoil structure of an aircraft and a shape memory structure associated with the composite structure. The shape memory structure has a buckled shape when in a deactivated state such that the composite structure is in an undeployed shape. The shape memory structure has an original shape when in an activated state such that the composite structure has a deployed shape. The composite structure applies a load against the shape memory structure.

In yet another illustrative embodiment, a method for controlling a shape of a composite structure is presented. A shape memory structure associated with the composite structure is activated. The shape memory structure changes from a buckled shape to an original shape and causes the composite structure to change from an undeployed shape to a deployed shape. The shape memory structure is deactivated.

The shape memory structure changes from the original shape to the buckled shape in response to a load from the composite structure and causes the composite structure to change from the deployed shape to the undeployed shape.

The features and functions can be achieved independently in various
5 embodiments of the present disclosure or may be combined in yet other embodiments in which further details can be seen with reference to the following description and drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

10 The novel features believed characteristic of the illustrative embodiments are set forth in the appended claims. The illustrative embodiments, however, as well as a preferred mode of use, further objectives and features thereof, will best be understood by reference to the following detailed description of an illustrative embodiment of the present disclosure when read in conjunction with the accompanying drawings, wherein:

15 **Figure 1** is an illustration of an aircraft in accordance with an illustrative embodiment;

Figure 2 is an illustration of a block diagram of an aerodynamic environment in accordance with an illustrative embodiment;

20 **Figure 3** is a detailed illustration of a section of a trailing edge of a wing of an aircraft in accordance with an illustrative embodiment;

Figure 4 is an illustration of an aerodynamic control system in accordance with an illustrative embodiment;

Figure 5 is another illustration of an aerodynamic control system in accordance with an illustrative embodiment;

25 **Figure 6** is an illustration of a cross-section of an aerodynamic control system in accordance with an illustrative embodiment;

Figure 7 is an illustration of a cross-section of an aerodynamic control system in accordance with an illustrative embodiment;

30 **Figure 8** is an illustration of a flowchart of a process for controlling a shape of a composite structure in accordance with an illustrative embodiment;

Figure 9 is an illustration of an aircraft manufacturing and service method in the form of a block diagram in accordance with an illustrative embodiment; and

Figure 10 is an illustration of an aircraft in the form of a block diagram in which an illustrative embodiment may be implemented.

DETAILED DESCRIPTION

5 The illustrative embodiments recognize and take into account one or more different considerations. For example, the illustrative embodiments recognize and take into account that current actuator systems often take more room than desired due to the complexity of these systems. For example, wires, linkages, connectors, motors and other components may be used to cause the shape of an airfoil structure to change
10 such that control surfaces for the airfoil structure do not need to be separate structures. These systems, however, often take more room than desired. In some cases, the systems may take more room than is available within the airfoil structure. This situation precludes the use of these systems. The illustrative embodiments recognize and take into account that it would be desirable to have an actuator system that can be used in
15 airfoil structures that are thin in shape or have slim profiles, such as aircraft wings or the trailing edge of an aircraft wing.

Thus, the illustrative embodiments provide a method and apparatus for controlling the shape of an airfoil structure. An apparatus comprises a composite structure and a shape memory structure. The composite structure is for an airframe of
20 an aircraft. The shape memory structure is associated with the composite structure. The shape memory structure has a buckled shape in a deactivated state such that the composite structure has an undeployed shape. The shape memory structure has an original shape when in an activated state such that the composite structure has a deployed shape. The composite structure applies a load against the shape memory
25 structure.

With reference now to the figures, and in particular, with reference to **Figure 1**, an illustration of an aircraft is depicted in accordance with an illustrative embodiment. In this illustrative example, aircraft **100** has wing **102** and wing **104** attached to body **106**. Aircraft **100** includes engine **108** attached to wing **102** and engine **110** attached to wing
30 **104**.

Body **106** has tail section **112**. Horizontal stabilizer **114**, horizontal stabilizer **116**, and vertical stabilizer **118** are attached to tail section **112** of body **106**.

Aircraft **100** is an example of an aircraft in which an aerodynamic control system with shape memory structures may be implemented in accordance with an illustrative embodiment. In particular, an aerodynamic control system may use shape memory structures in the form of shape memory alloy structures.

For example, the system may be implemented in control surfaces such as flap **120** on wing **102**, elevator **122** on horizontal stabilizer **116**, rudder **124** on vertical stabilizer **118**, slat **126** on wing **104**, as well as other flight control surfaces on aircraft **100**. In this type of implementation, the actuation system may be used to change the shape of a control surface. This change in the shape of a control surface is separate from movement of the control surface as a separate structure relative to aircraft **100**.

Additionally, the actuation system may be implemented in airfoil structures in aircraft **100**, such as wing **102**, wing **104**, horizontal stabilizer **114**, horizontal stabilizer **116**, and vertical stabilizer **118**. In this type of implementation, the actuation system may be used to change the shape of the airfoil structure separately from the control surface.

With using an actuation system in airfoil structures in accordance with an illustrative embodiment, the use of control surfaces as separate structures may be reduced or eliminated for aircraft **100**. For example, the actuation system may be used to change the shape of trailing edge **128** of wing **102**. In other illustrative examples, the actuation system may be used to cause a bump, ridge, or other change in shape on surface **130** of wing **102**. These and other types of changes may be made to airfoil structures on aircraft **100**, as well as on any part of aircraft **100** during operation of aircraft **100**.

A more detailed illustration of section **132** on wing **102** is shown in **Figure 3**. The description of this section below in **Figure 3** is an illustrative example of one implementation of an aerodynamic control system in accordance with an illustrative embodiment.

Turning next to **Figure 2**, an illustration of a block diagram of an aerodynamic environment is depicted in accordance with an illustrative embodiment. In aerodynamic environment **200**, aerodynamics **201** of vehicle **202** is controlled by aerodynamic control system **204**. In this illustrative example, vehicle **202** takes the form of aircraft **206**.

In the illustrative example, aerodynamic control system **204** includes a number of different components. As depicted, aerodynamic control system **204** includes

composite structure **208**, shape memory structure **210**, and activation system **212**. In this example, shape memory structure **210** is an example of an actuator system.

Composite structure **208** is aerodynamic composite structure **214**. For example, composite structure **208** may be selected from one of an airfoil, a control surface, a skin panel, a flap, an aileron, a wing tip, a trailing edge of the wing, a leading edge of the wing, a horizontal or vertical stabilizer, an engine nacelle, engine nozzles, spoilers, vortex generators, a winglet, or some other suitable composite structure. In the illustrative example, these composite structures may be thin composite materials. In the illustrative example, a thin composite material is a material forming a structure that has a form that is sufficiently thin to allow deformation of the structure between the original shape and the deformed shape without damage to the composite material. The thickness of these materials also may be sufficiently thin that connection to the composite material cannot be achieved using discrete fastener features. Further, the material may be too thin for using fasteners because the material is unable to handle the concentrated loading of the individual fasteners or the material is not sufficiently thick to allow countersinking to maintain a smooth airflow surface.

In this illustrative example, shape memory structure **210** is a structure that remembers original shape **220** for shape memory structure **210** such that shape memory structure **210** returns to original shape **220** from deformed shape **219** when not heated by a sufficient amount. As depicted, shape memory structure **210** is associated with composite structure **208**.

When one component is “associated” with another component in the illustrative examples, the association is a physical association in the depicted examples. For example, a first component, shape memory structure **210**, may be considered to be physically associated with a second component, composite structure **208**, by at least one of being secured to the second component, bonded to the second component, mounted to the second component, welded to the second component, fastened to the second component, or connected to the second component in some other suitable manner. The first component also may be connected to the second component using a third component. The first component may also be considered to be physically associated with the second component by being formed as part of the second component, extension of the second component, or both.

In this illustrative example, shape memory structure **210** is associated with composite structure **208** by being at least one of bonded to composite structure, fastened to composite structure **208**, or formed as part of composite structure **208**. For example, shape memory structure **210** may be formed as part of composite structure **208** by being placed within layers of composite material that are then cured to form composite structure **208**.

Also, composite structure **208** may take different forms depending on the particular implementation. For example, composite structure **208** may be a carbon fiber composite, a fiberglass composite, or some other suitable type of composite suitable for use in vehicle **202**.

In this illustrative example, shape memory structure **210** is elongate member **215** and has shape **216**. Shape **216** for shape memory structure **210** may be buckled shape **218** and original shape **220**. In these illustrative examples, shape **216** may transition or move between these two shapes. Buckled shape **218** is deformed shape **219** for shape memory structure **210**.

As depicted, shape memory structure **210** has buckled shape **218** when shape memory structure **210** is in deactivated state **222**. Shape memory structure **210** has original shape **220** when shape memory structure **210** is in activated state **224**.

As depicted, shape memory structure **210** in the form of elongate member **215** may have various forms of shape **216** when in original shape **220**. For example, elongate member **215** may be a rod, a sheet, or some other suitable form that may be deformed into buckled shape **218** when in deactivated state **222** and may return to original shape **220** when in activated state **224**. For example, elongate member **215** may have a shape selected to allow a controlled and reversible transition between original shape **220** and buckled shape **218**. In this example, the deformation is a bending of shape memory structure **210**.

In this illustrative example, when shape memory structure **210** has buckled shape **218** in deactivated state **222**, composite structure **208** has undeployed shape **226**. When shape memory structure **210** has original shape **220** in activated state **224**, composite structure **208** has deployed shape **228**.

In these illustrative examples, composite structure **208** applies load **230** against shape memory structure **210**. Load **230** may take various forms such as compressive load **232** and bending load **234**.

As depicted, composite structure **208** applies load **230** on shape memory structure **210** as compressive load **232** when shape memory structure **210** is in activated state **224** and has original shape **220**. Compressive load **232** occurs when shape memory structure **210** is in activated state **224** and returns to original shape **220**.

5 Activated state **224** may occur when shape memory structure is heated to or above a transition temperature for shape memory structure **210**.

Composite structure **208** applies load **230** on shape memory structure **210** as bending load **234** when shape memory structure **210** is in deactivated state **222**. For example, when shape memory structure **210** cools below a transition temperature,
10 shape memory structure **210** may be deformed. In other words, load **230** applied by composite structure **208** against shape memory structure **210** causes shape memory structure **210** to bend. As a result, load **230** is bending load **234** that may cause the bending of shape memory structure **210** into buckled shape **218**.

Shape memory structure **210** may take various forms. Further, shape memory
15 structure **210** may be comprised of different types of materials. For example, shape memory structure **210** may be comprised of a material selected from a shape memory metal alloy, a shape memory polymer, copper-aluminum-nickel, nickel-titanium, or some other suitable material. The material selected may depend on the particular application or implementation and is selected as one that allows shape memory structure **210** to be
20 deformed when in deactivated state **222** and return to original shape **220** when in activated state **224**.

In this illustrative example, shape memory structure **210** is unitary structure **236**. In other words, shape memory structure **210** may be a single piece or component.

In an illustrative example, shape memory structure **210** may aid in controlling
25 movement of aircraft **206** when in original shape **220** such that composite structure **208** moves from undeployed shape **226** to deployed shape **228**. For example, shape memory structure **210** in original shape **220** causes composite structure **208** to have a group of desired values **238** for a group of parameters **240** in deployed shape **228**. As depicted, the group of parameters **240** is selected from at least one of rigidity, stability,
30 airflow, noise, vibration, lift, drag, angle of attack, or other suitable parameters.

In this illustrative example, activation system **212** is a component in aerodynamic control system **204** that controls the state of shape memory structure **210**. For

example, activation system **212** causes shape memory structure **210** to shift from deactivated state **222** to activated state **224**.

This change in state is caused by activation system **212** applying heat to shape memory structure **210**. In other words, activation system **212** includes one or more heat sources. As depicted, activation system **212** includes at least one of a wire, a resistive element, a heating unit, a bleed air system, an electromagnetic induction unit, an infrared emitter, a bleed air conduit from an aircraft engine, a laser unit, or some other suitable component that may generate heat in shape memory structure **210** sufficient to cause a change in state.

The illustration of an aerodynamic environment **200** in **Figure 2** is not meant to imply physical or architectural limitations to the manner in which an illustrative embodiment may be implemented. Other components in addition to or in place of the ones illustrated may be used. Some components may be unnecessary. Also, the blocks are presented to illustrate some functional components. One or more of these blocks may be combined, divided, or combined and divided into different blocks when implemented in an illustrative embodiment.

For example, although vehicle **202** has been described with respect to aircraft **206**, vehicle **202** may take other forms. For example, vehicle **202** may be selected from one of a mobile platform, an aircraft, a surface ship, a tank, a personnel carrier, a train, a spacecraft, a submarine, a bus, an automobile, or some other suitable type of vehicle.

As another example, activation system **212** may be omitted or may not be part of aircraft **206**. For example, the activation and deactivation of shape memory structure **210** may occur as a result of changes in the temperature in the environment to which shape memory structure **210** is exposed. For example, the temperature may change during different phases of flight.

For example, original shape **220** is present during a first phase of flight for aircraft **206** and buckled shape **218** is present during a second phase of flight for aircraft **206**. In one illustrative example, the first phase of flight is take-off of aircraft **206** and the second phase of flight is cruising of aircraft **206**. In this example, the activation of shape memory structure **210** occurs during take-off and the deactivating of shape memory structure **210** occurs during cruising of aircraft **206**. Additionally, original shape **220** is present during a third phase of flight, such as landing of aircraft **206**.

With reference to **Figure 3**, a detailed illustration of a section of a trailing edge of a wing of an aircraft is depicted in accordance with an illustrative embodiment. As depicted, a more detailed illustration of section **132** of wing **102** is shown in this figure. As depicted, aerodynamic control system **300** is shown as being implemented in trailing edge **128** of wing **102** in this exposed view of wing **102**. In this example, trailing edge **128** in wing **102** is shown in an undeployed shape.

As depicted, aerodynamic control system **300** may be used to change the shape of trailing edge **128** and wing **102**. A more detailed view of aerodynamic control system **300** in section **304** is shown in **Figure 4** below.

With reference now to **Figure 4**, an illustration of an aerodynamic control system is depicted in accordance with an illustrative embodiment. In this figure, a more detailed view of aerodynamic control system **300** in section **304** in trailing edge **128** is shown. In this illustration, aerodynamic control system **300** is depicted in a deactivated state with trailing edge **128** of wing **102** from **Figure 3** being in an undeployed shape.

In this illustrative example, aerodynamic control system **300** has a number of different components that can be seen in this exposed view. As depicted, shape memory structures **406** and composite structure **408** are illustrated in trailing edge **128** of wing **102**. In this illustrative example, shape memory structures **406** are comprised of nickel-titanium alloy. Shape memory structures **406** include shape memory structure **410**, shape memory structure **412**, shape memory structure **414**, and shape memory structure **416**, which are in the form of elongate members in this depicted example. Shape memory structures **406** also include shape memory structure **418**, shape memory structure **420**, shape memory structure **422**, and shape memory structure **424**.

As depicted, first end **426** of shape memory structure **410** is associated with composite structure **408**, and first end **428** of shape memory structure **412** is associated with composite structure **408**. First end **430** of shape memory structure **414** is associated with composite structure **408**, and first end **432** of shape memory structure **416** is associated with composite structure **408**.

In the illustrative example, second end **434** of shape memory structure **410** is associated with mounting base **436**, and second end **438** of shape memory structure **412** is associated with mounting base **440**. Second end **442** of shape memory structure **414** is associated with mounting base **444**, and second end **446** of shape memory structure **416** is associated with mounting base **448**.

As depicted, shape memory structure **418**, shape memory structure **420**, shape memory structure **422**, and shape memory structure **424** assist in the continuity of the deployed shape of composite structure **408**. These shape memory structures produce a local curvature in the area of composite structure **408** around these shape memory structures.

In the illustrative example, shape memory structure **418**, shape memory structure **420**, shape memory structure **422**, and shape memory structure **424** are secondary shape memory structure elements. These structures affect a shape change by generating internal stresses in the composite and shape memory structure assembly that leads to curvature of that assembly.

As shown in this deactivated state for shape memory structures **406**, composite structure **408** applies a load in the form of a bending load on shape memory structure **410**, shape memory structure **412**, shape memory structure **414**, and shape memory structure **416**. This load is shown in the direction of arrow **450**. This deformation is caused by composite structure **408** in this illustrative example.

In the deactivated state, composite structure **408** has an undeployed shape at trailing edge **128** of wing **102**. Undeployed shape of composite structure **408** is the shape of composite structure **408** that is present when shape memory structures **406** do not apply a force against composite structure **408**.

Turning next to **Figure 5**, another illustration of an aerodynamic control system of an aircraft is depicted in accordance with an illustrative embodiment. In this example, trailing edge **128** of wing **102** shown in **Figure 3** is shown in a deployed shape. In this depicted example, trailing edge **128** of wing **102** is shown as bent or curved in the direction of arrow **500** to form a shape.

With reference now to **Figure 6**, an illustration of a cross-section of an aerodynamic control system is depicted in accordance with an illustrative embodiment. In this figure, an illustration of a cross-sectional view of aerodynamic control system **300** is shown taken along lines **6-6** in **Figure 4**.

In this view, shape memory structure **412** is shown as being in a buckled shape when this structure is in a deactivated state. In this deactivated state, shape memory structure **412** is in a state in which shape memory structure **412** may be deformed. In this example, deformation is a bending of shape memory structure **412** that forms the

buckled shape of shape memory structure **412**. Further, the undeployed shape for composite structure **408** is also seen in this view.

In this view, different sections of shape memory structure **412** are illustrated. As depicted, base section **600**, middle section **602**, and attachment section **604** are shown for shape memory structure **412**.

Base section **600** is part of second end **438** and is associated with mounting base **440**. Attachment section **604** is part of first end **428**.

As can be seen in this illustrative example, middle section **602** has a buckled shape from being bent by composite structure **408**. Composite structure **408** applies a bending load when shape memory structure **412** is in a deactivated state.

In the illustrative example, base section **600** may be associated with mounting base **440** in a number of different ways. As depicted in this illustrative example, base section **600** is bonded to mounting base **440**. In other examples, base section **600** may be fastened to the composite structure, formed as part of mounting base **440**, or connected to mounting base **440** in some other manner. Further, some combination of mechanisms also may be used to associate base section **600** with mounting base **440**.

In the illustrative example, attachment section **604** is bonded to composite structure **408**. In other illustrative examples, attachment section **604** may be associated with composite structure **408** using other mechanisms. For example, attachment section **604** may also be fastened to the composite structure, formed as part of mounting base **440**, or connected to mounting base **440** in some other manner.

Further, some combination of mechanisms also may be used to associate attachment section **604** with composite structure **408**. For example, attachment section **604** may be placed between with layers in composite structure **408**. These layers may be cured such that attachment section **604** is considered to be formed as part of composite structure **408**. Additionally, adhesive also may be included to bond attachment section **604** to the layers of composite structure **408**.

In the illustrative example, the shape and thickness of base section **600** is designed to allow for a desired attachment to a structure such as mounting base **440**. In an illustrative example, base section **600** may also be designed to allow for some adjustment in the mounting to “tune” the performance of the actuator.

In the illustrative example, tuning involves adjusting the amount of compressive pre-load in the actuator by moving the end of the actuator. Increasing the pre-load can result in more shape change in the deployed state and vice versa.

As depicted in the illustrative example, the shape and thickness of middle section **602** is designed to allow for a controlled and reversible transition between the original shape and the buckled shape. Curve **606** at trailing edge **608** of middle section **602** is designed to transform the compressive loading in middle section **602** of the actuator to a moment load at trailing edge **608** at the connection to the skin, composite structure **408**, to induce additional curvature in the trailing edge **608** during actuation. In this depicted example, the actuator is shape memory structure **412**. This resultant moment also helps initiate buckling in middle section **602** during relaxation, promoting the overall buckling and “collapse” of shape memory structure **412**. The shape and thickness of attachment section **604** is designed to induce a curvature at the trailing edge of composite structure **408** through the generation of internal stresses when actuated.

In this illustrative example, composite structure **408** and attachment section **604** are formed with opposite curvatures and constrained together during bonding. Actuation and relaxation of attachment section **604** of this bonded assembly changes the internal stress distribution, leading to a straight shape when relaxed and a curved shape when actuated.

With reference now to **Figure 7**, an illustration of a cross-section of an aerodynamic control system is depicted in accordance with an illustrative embodiment. In this figure, an illustration of a cross-sectional view of aerodynamic control system **300** is shown taken along lines **7–7** in **Figure 5**.

In this view, shape memory structure **412** is shown as being in an original shape when this structure is in an activated state. In this activated state, shape memory structure **412** is in a state in which shape memory structure **412** returns to a pre-deformed shape if shape memory structure **412** has been deformed. In other words, shape memory structure **412** remembers its original shape and returns to its original shape when heated in this illustrative example. Further, the deployed shape for composite structure **408** is also seen in this view.

As shown in this view, shape memory structure **412** is straightened out in this original shape. Shape memory structure **412** in the original shape may be, for example, a beam that may create a truss-type configuration between shape memory structure

coordinates and composite structure **408**. In this manner, this arrangement may be insensitive or reduced in sensitivity to other types of loads that may be applied to this configuration.

In the illustrative embodiments, shape memory structure **412** in an activated state results in a truss configuration formed by shape memory structure **412** and composite structure **408**. This truss configuration has an increased resistance to deformation. When shape memory structure **412** is in a deactivated state, shape memory structure **412** in the truss configuration undergoes structural collapse through buckling. This change, reducing the stiffness of the shape memory structure **412**, allows shape memory structure **412** to deform to a buckled shape and allows composite structure **408** to return to its base shape. Further, when composite structure **408** is in a deployed shape when moved to the deployed shape by shape memory structure **412**, the deployed shape of composite structure **408** and the original shape of shape memory structure **412** are independent of the exterior loading on the composite structure **408**.

The illustration of the different components in the aerodynamic control system illustrated in **Figure 1** and **Figures 3–7** are not meant to limit the manner in which different illustrative embodiments may be implemented. For example, although aerodynamic control system **300** is shown as being implemented in trailing edge **128** of wing **102** for aircraft **100**, aerodynamic control system may be implemented in other locations or for other portions of aircraft **100**. For example, and aerodynamic control system may be implemented in a leading edge of wing **102**, on body **106** of aircraft **100**, in a faring, as part of the control surface, or in some other suitable manner.

In other illustrative examples, shape memory structure **418**, shape memory structure **420**, shape memory structure **422**, and shape memory structure **424** may be omitted. Also, the illustrations did not show an activation system. The activation system used depends on the particular implementation. For example, wires or traces may be formed on or within the shape memory structures. In other examples, the heat may be supplied through an infrared emitter, a bleed air conduit from an aircraft engine, or in some other manner.

The different components shown in **Figure 1** and **Figures 3-7** may be combined with components in **Figure 2**, used with components in **Figure 2**, or a combination of the two. Additionally, some of the components in **Figure 1** and **Figures 3-7** shown in block form in **Figure 2** can be implemented as physical structures.

With reference now to **Figure 8**, an illustration of a flowchart of a process for controlling a shape of a composite structure is depicted in accordance with an illustrative embodiment. The process illustrated in **Figure 8** may be implemented in aerodynamic environment **200** in **Figure 2**. For example, the process may be implemented using aerodynamic control system **204**. The process begins with the shape memory structure in a deactivated state and the composite structure in an undeployed shape in this illustrative example.

The process begins by determining whether to change the shape of the composite structure to a deployed shape (operation **800**). If the composite structure is not to be changed to the deployed shape, the process returns to operation **800**. If the composite structure is to be changed to the deployed shape, the process activates the shape memory structure associated with the composite structure (operation **802**). In operation **802**, the shape memory structure changes from a buckled shape to an original shape and causes the composite structure to change from an undeployed shape to a deployed shape. The composite structure applies a load in the form of a compressive load on the shape memory structure when in the deployed shape. The undeployed shape is the shape of the composite structure when the shape memory structure is not applying a force on the composite structure to place the composite structure in the deployed shape.

A determination is made as to whether to change the shape of the composite structure back to the undeployed shape (operation **804**). If the composite structure is to remain in the deployed shape, the process returns to operation **804**.

Otherwise, the process then deactivates the shape memory structure (operation **806**). In operation **806**, the shape memory structure bends from the original shape to a buckled shape in response to a load from the composite structure and the composite structure changes from the deployed shape to the undeployed shape. In this example, the load applied by the composite structure is a bending load. The process then returns to operation **800** as described above.

In these illustrative examples, the activating and deactivating of the shape memory structure may be controlled by an activation system. The activation system may apply heat to the shape memory structure through a device in the aircraft. In other illustrative examples, the activation system may not be a device, but may be the environment around the shape memory structure. For example, the activating step and

the deactivating step occur during different phases of flight of the aircraft. The activating step occurs during take-off of the aircraft and the deactivating step occurs during cruising of the aircraft. This activation and deactivation may be caused by the temperature in the environment to which the shape memory structure is exposed. For example, a first temperature during a take-off causes the shape memory structure to be in the activated state and a second temperature during cruising causes the shape memory structure to be in the deactivated state.

In this manner, autonomous activation of the shape memory structure may occur through different phases of flight. In other illustrative examples, the activation and deactivation may be through controlling the operation of the activation system that applies heat to the shape memory structure.

The flowcharts and block diagrams in the different depicted embodiments illustrate the architecture, functionality, and operation of some possible implementations of apparatuses and methods in an illustrative embodiment. In this regard, each block in the flowcharts or block diagrams may represent at least one of a module, a segment, a function, or a portion of an operation or step.

In some alternative implementations of an illustrative embodiment, the function or functions noted in the blocks may occur out of the order noted in the figures. For example, in some cases, two blocks shown in succession may be executed substantially concurrently, or the blocks may sometimes be performed in the reverse order, depending upon the functionality involved. Also, other blocks may be added in addition to the illustrated blocks in a flowchart or block diagram.

Illustrative embodiments of the disclosure may be described in the context of aircraft manufacturing and service method **900** as shown in **Figure 9** and aircraft **1000** as shown in **Figure 10**. Turning first to **Figure 9**, an illustration of an aircraft manufacturing and service method is depicted in the form of a block diagram in accordance with an illustrative embodiment. During pre-production, aircraft manufacturing and service method **900** may include specification and design **902** of aircraft **1000** in **Figure 10** and material procurement **904**.

During production, component and subassembly manufacturing **906** and system integration **908** of aircraft **1000** in **Figure 10** takes place. Thereafter, aircraft **1000** in **Figure 10** may go through certification and delivery **910** in order to be placed in service **912**. While in service **912** by a customer, aircraft **1000** in **Figure 10** is scheduled for

routine maintenance and service **914**, which may include modification, reconfiguration, refurbishment, and other maintenance or service.

Each of the processes of aircraft manufacturing and service method **900** may be performed or carried out by a system integrator, a third party, an operator, or some combination thereof. In these examples, the operator may be a customer. For the purposes of this description, a system integrator may include, without limitation, any number of aircraft manufacturers and major-system subcontractors; a third party may include, without limitation, any number of vendors, subcontractors, and suppliers; and an operator may be an airline, a leasing company, a military entity, a service organization, and so on.

With reference now to **Figure 10**, an illustration of an aircraft is depicted in the form of a block diagram in which an illustrative embodiment may be implemented. In this example, aircraft **1000** is produced by aircraft manufacturing and service method **900** in **Figure 9** and may include airframe **1002** with plurality of systems **1004** and interior **1006**. Examples of systems **1004** include one or more of propulsion system **1008**, electrical system **1010**, hydraulic system **1012**, and environmental system **1014**. Any number of other systems may be included. Although an aerospace example is shown, different illustrative embodiments may be applied to other industries, such as the automotive industry.

Apparatuses and methods embodied herein may be employed during at least one of the stages of aircraft manufacturing and service method **900** in **Figure 9**. In one illustrative example, components or subassemblies produced in component and subassembly manufacturing **906** in **Figure 9** may be fabricated or manufactured in a manner similar to components or subassemblies produced while aircraft **1000** is in service **912** in **Figure 9**.

For example, aerodynamic control system in accordance with an illustrative embodiment may be manufactured during component and subassembly manufacturing **906**. The aerodynamic control system may be implemented into aircraft **1000** during system integration **908**. Further, the aerodynamic control system may be used in operation of aircraft **1000** during certification and delivery **910** and in service **912**.

As another illustrative example, aerodynamic control system may be manufactured and added to aircraft **1000** during maintenance and service **914**. For example, the aerodynamic control system may be added during upgrades, routine

maintenance, refurbishment, and other operations performed on aircraft **1000** during maintenance and service **914**.

Further, the disclosure comprises embodiments according to the following clauses:

- 5 1. An apparatus comprising:
a composite structure for an airframe of an aircraft; and
a shape memory structure associated with the composite structure, wherein the shape memory structure has a buckled shape in a deactivated state such that the composite structure has an undeployed shape, wherein the shape memory structure
10 has an original shape in an activated state such that the composite structure has a deployed shape, wherein the composite structure applies a load against the shape memory structure.
2. The apparatus of clause 1, wherein the composite structure applies the load on
15 the shape memory structure as a compressive load when the shape memory structure is in the activated state.
3. The apparatus of clause 1, wherein the composite structure applies the load on the shape memory structure as a bending load when the shape memory structure is in
20 the deactivated state.
4. The apparatus of clause 1, wherein the shape memory structure is a unitary structure.
- 25 5. The apparatus of clause 1, wherein the shape memory structure in the original shape causes the composite structure to have a group of desired values for a group of parameters.
6. The apparatus of clause 5, wherein the group of parameters is selected from at
30 least one of rigidity, stability, airflow, noise, vibration, lift, drag, or angle of attack.
7. The apparatus of clause 1 further comprising:

an activation system that causes the shape memory structure to shift from the deactivated state to the activated state.

8. The apparatus of clause 7, wherein the activation system includes at least one of a wire, a resistive element, a heating unit, a bleed air system, electromagnetic induction unit, infrared emitter, or a laser unit.

9. The apparatus of clause 1 further comprising:
a secondary shape memory structure that assists in the continuity of the deployed shape of the composite structure in the activated state.

10. The apparatus of clause 1, wherein the shape memory structure is associated with the composite structure by being at least one of bonded to the composite structure, fastened to the composite structure, or formed as part of the composite structure.

11. The apparatus of clause 1, wherein the composite structure is selected from a group consisting of an airfoil, a control surface, a skin panel, a flap, an aileron, a wing tip, a trailing edge of a wing, a leading edge of the wing, a horizontal or vertical stabilizer, an engine nacelle, engine nozzles, spoilers, vortex generators, and a winglet.

12. The apparatus of clause 1, wherein the shape memory structure is comprised of a material selected from a group consisting of a shape memory metal alloy, a shape memory polymer, copper-aluminum-nickel, and nickel-titanium.

13. An aerodynamic control system comprising:
a composite structure on an airfoil structure of an aircraft; and
a shape memory structure associated with the composite structure, wherein the shape memory structure has a buckled shape when in a deactivated state such that the composite structure is in an undeployed shape, wherein the shape memory structure has an original shape when in an activated state such that the composite structure has a deployed shape, wherein the composite structure applies a load against the shape memory structure.

14. The aerodynamic control system of clause 13, wherein the original shape is present during a first phase of flight for the aircraft and the buckled shape is present during a second phase of flight for the aircraft.

15. The aerodynamic control system of clause 13, wherein the shape memory structure in the original shape causes the composite structure to have a group of desired values for a group of parameters selected from at least one of rigidity, stability, airflow, noise, vibration, lift, drag, or angle of attack.

16. The aerodynamic control system of clause 13, wherein a first temperature during a take-off of the aircraft causes the shape memory structure to be in the activated state and a second temperature during a cruising of the aircraft causes the shape memory structure to be in the deactivated state.

17. A method for controlling a shape of a composite structure, the method comprising:

activating a shape memory structure associated with the composite structure, wherein the shape memory structure changes from a buckled shape to an original shape and causes the composite structure to change from an undeployed shape to a deployed shape; and

deactivating the shape memory structure, wherein the shape memory structure changes from the original shape to the buckled shape in response to a load from the composite structure and causes the composite structure to change from the deployed shape to the undeployed shape.

18. The method of clause 17, wherein the load is a bending load on the shape memory structure when the shape memory structure is deactivated, and wherein the load is a compressive load on the shape memory structure when the shape memory structure is activated.

19. The method of clause 17, wherein the activating step and the deactivating step occur during different phases of flight.

20. The method of clause 17, wherein the activating step occurs during take-off of an aircraft and the deactivating step occurs during cruising of the aircraft.

Thus, the illustrative examples provide a method and apparatus for controlling the shape of a composite structure. In the illustrative examples, the system used to actuate or change the shape of the composite structure is implemented using shape memory structures. The shape memory structures in the illustrative examples are designed for use in locations in a vehicle, such as an aircraft that has limited clearance. For example, an illustrative embodiment may be implemented in an area such as a trailing edge of a wing of an aircraft. In this manner, the composite structure may be implemented to allow for a change in shape that reduces or eliminates gaps. As a result, the change in shape at the trailing edge of the wing may occur without airflow disturbing features such as discrete hinges, gaps, fasteners, or other undesired features. Further, the shape memory structures may be selected with a desired stiffness to maintain the shape of the composite structure.

The description of the different illustrative embodiments has been presented for purposes of illustration and description, and is not intended to be exhaustive or limited to the embodiments in the form disclosed. Many modifications and variations will be apparent to those of ordinary skill in the art. Further, different illustrative embodiments may provide different features as compared to other desirable embodiments. The embodiment or embodiments selected are chosen and described in order to best explain the principles of the embodiments, the practical application, and to enable others of ordinary skill in the art to understand the disclosure for various embodiments with various modifications as are suited to the particular use contemplated.

CLAIMS:

What is claimed is:

- 5 1. An apparatus comprising:
a composite structure (208) for an airframe (1002) of an aircraft (206); and
a shape memory structure (210) associated with the composite structure (208),
wherein the shape memory structure (210) has a buckled shape (218) in a deactivated
state (222) such that the composite structure (208) has an undeployed shape (226),
10 wherein the shape memory structure (210) has an original shape (220) in an activated
state (224) such that the composite structure (208) has a deployed shape (228),
wherein the composite structure (208) applies a load (230) against the shape memory
structure (210).
- 15 2. The apparatus of claim 1, wherein the composite structure (208) applies the load
(230) on the shape memory structure (210) as a compressive load (232) when the
shape memory structure (210) is in the activated state (224).
3. The apparatus of claims 1 or 2, wherein the composite structure (208) applies the
20 load (230) on the shape memory structure (210) as a bending load (234) when the
shape memory structure (210) is in the deactivated state (222).
4. The apparatus of any preceding claim, wherein the shape memory structure is a
unitary structure (236).
- 25 5. The apparatus of any preceding claim, wherein the shape memory structure
(210) in the original shape (220) causes the composite structure (208) to have a group
of desired values (238) for a group of parameters (240), and wherein the group of
parameters (240) is selected from at least one of rigidity, stability, airflow, noise,
30 vibration, lift, drag, or angle of attack.
6. The apparatus of any preceding claim further comprising:

an activation system (212) that causes the shape memory structure (210) to shift from the deactivated state (222) to the activated state (224).

7. The apparatus of claim 6, wherein the activation system (212) includes at least one of a wire, a resistive element, a heating unit, a bleed air system, electromagnetic induction unit, infrared emitter, or a laser unit.

8. The apparatus of any preceding claim further comprising:
a secondary shape memory structure (210) that assists in the continuity of the deployed shape (228) of the composite structure (208) in the activated state (224).

9. The apparatus of any preceding claim, wherein the shape memory structure (210) is associated with the composite structure (208) by being at least one of bonded to the composite structure (208), fastened to the composite structure (208), or formed as part of the composite structure (208).

10. The apparatus of any preceding claim, wherein the composite structure (208) is selected from a group consisting of an airfoil, a control surface, a skin panel, a flap, an aileron, a wing tip, a trailing edge of a wing, a leading edge of the wing, a horizontal or vertical stabilizer, an engine nacelle, engine nozzles, spoilers, vortex generators, and a winglet.

11. The apparatus of any preceding claim, wherein the shape memory structure (210) is comprised of a material selected from a group consisting of a shape memory metal alloy, a shape memory polymer, copper-aluminum-nickel, and nickel-titanium.

12. A method for controlling a shape of a composite structure (208), the method comprising:

activating (802) a shape memory structure (210) associated with the composite structure (208), wherein the shape memory structure (210) changes from a buckled shape (218) to an original shape (220) and causes the composite structure (208) to change from an undeployed shape (226) to a deployed shape (228); and

deactivating (806) the shape memory structure (210), wherein the shape memory structure (210) bends from the original shape (220) to the buckled shape (218) in response to a load (230) from the composite structure (208) and causes the composite structure to change from the deployed shape (228) to the undeployed shape (226).

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13. The method of claim 12, wherein the load (230) is a bending load (234) on the shape memory structure (210) when the shape memory structure (210) is deactivated, and wherein the load (230) is a compressive load (234) on the shape memory structure (210) when the shape memory structure (210) is activated.

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14. The method of claims 12 or 13, wherein the activating step and the deactivating step occur during different phases of flight.

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15. The method of any of claims 12 to 14, wherein the activating step occurs during take-off of an aircraft (206) and the deactivating step occurs during cruising of the aircraft (206).

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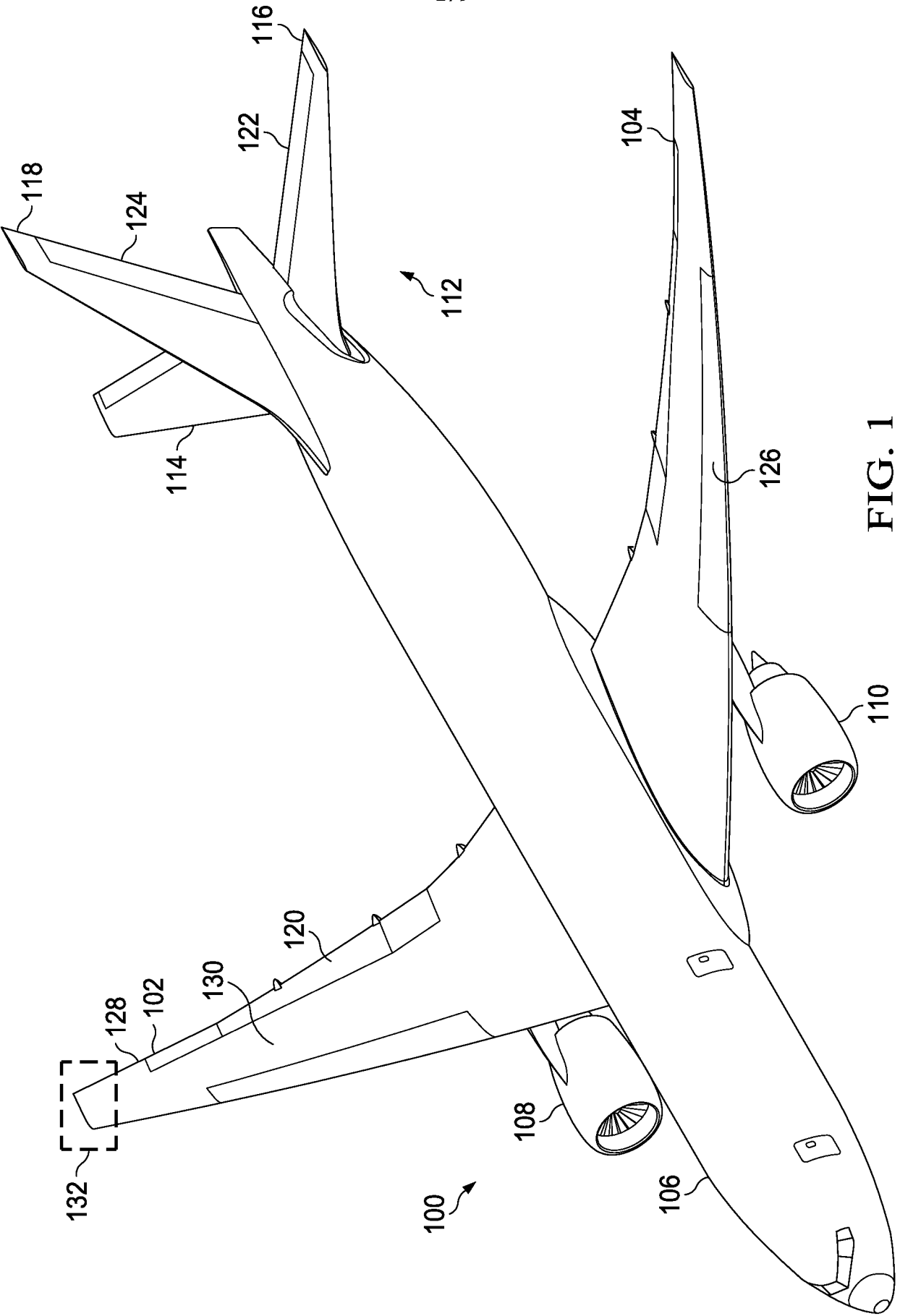


FIG. 1

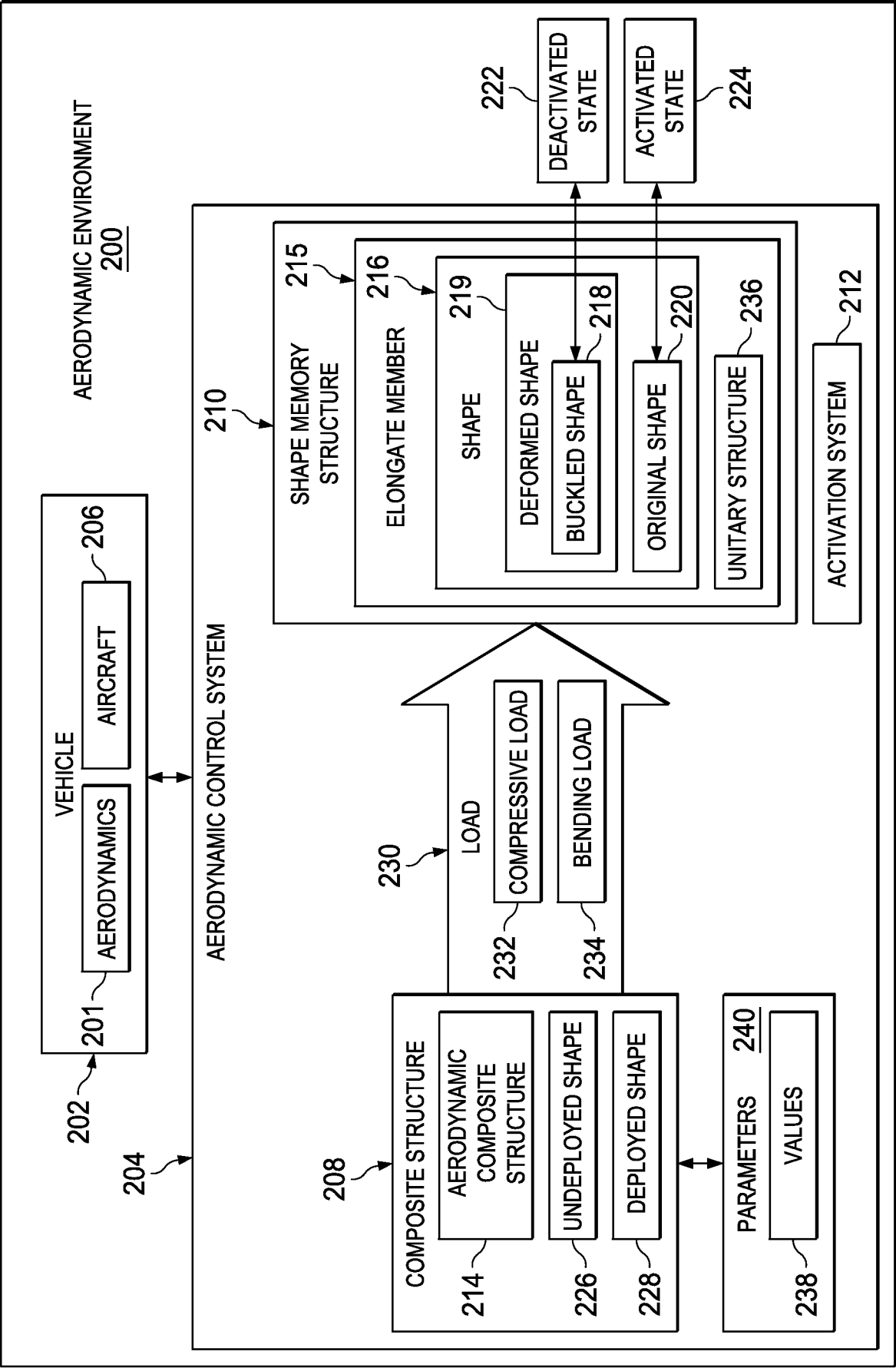
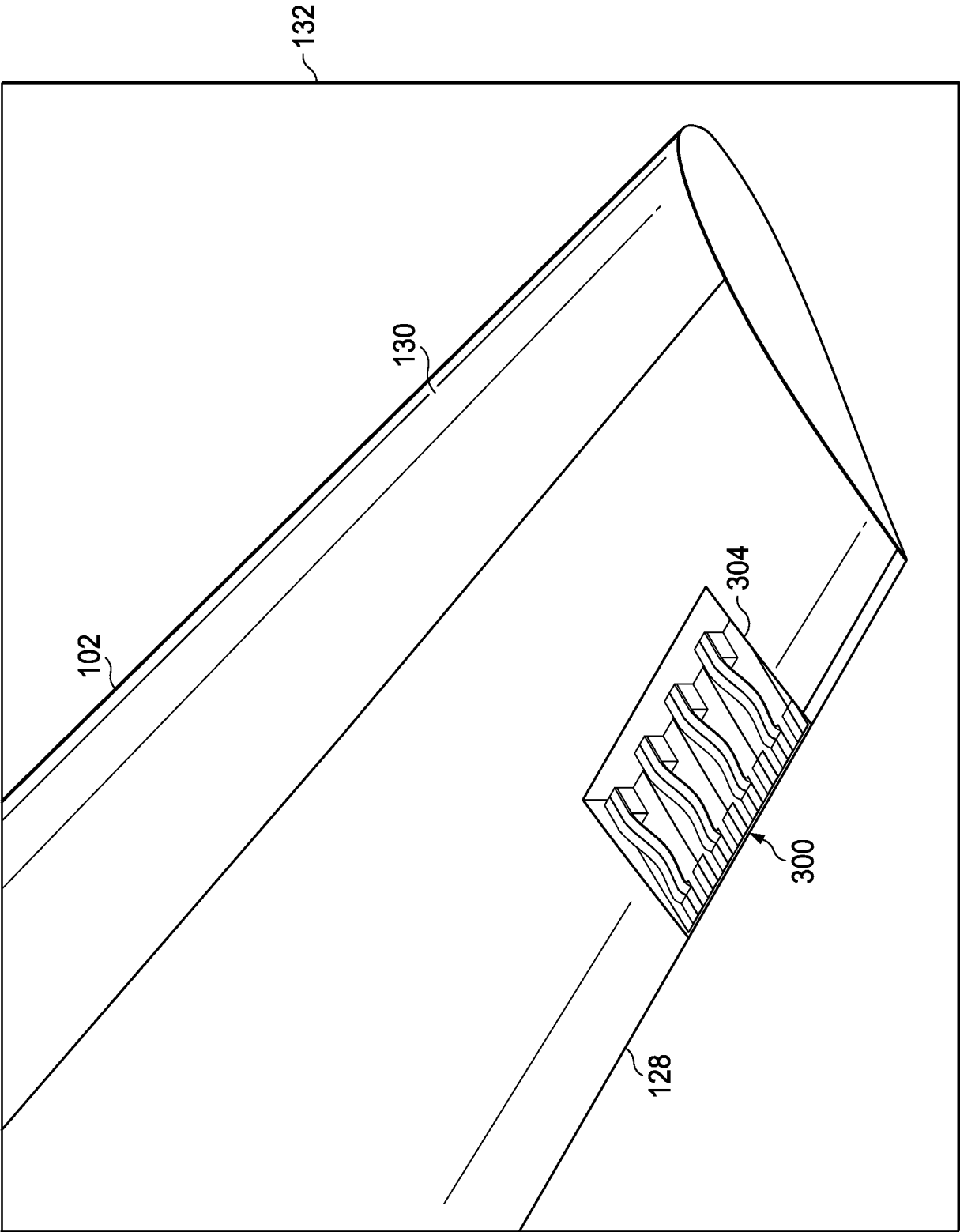


FIG. 2

FIG. 3



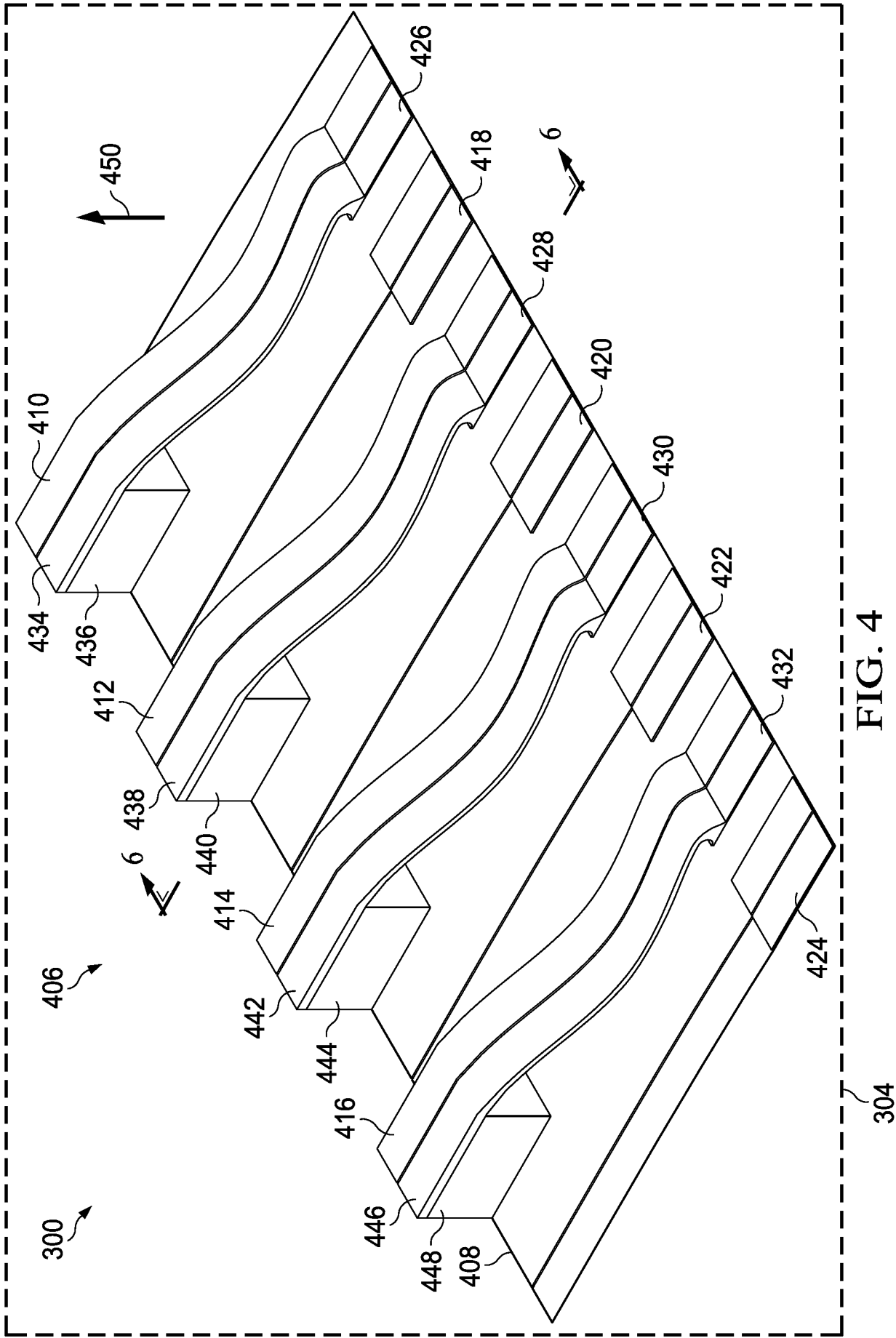
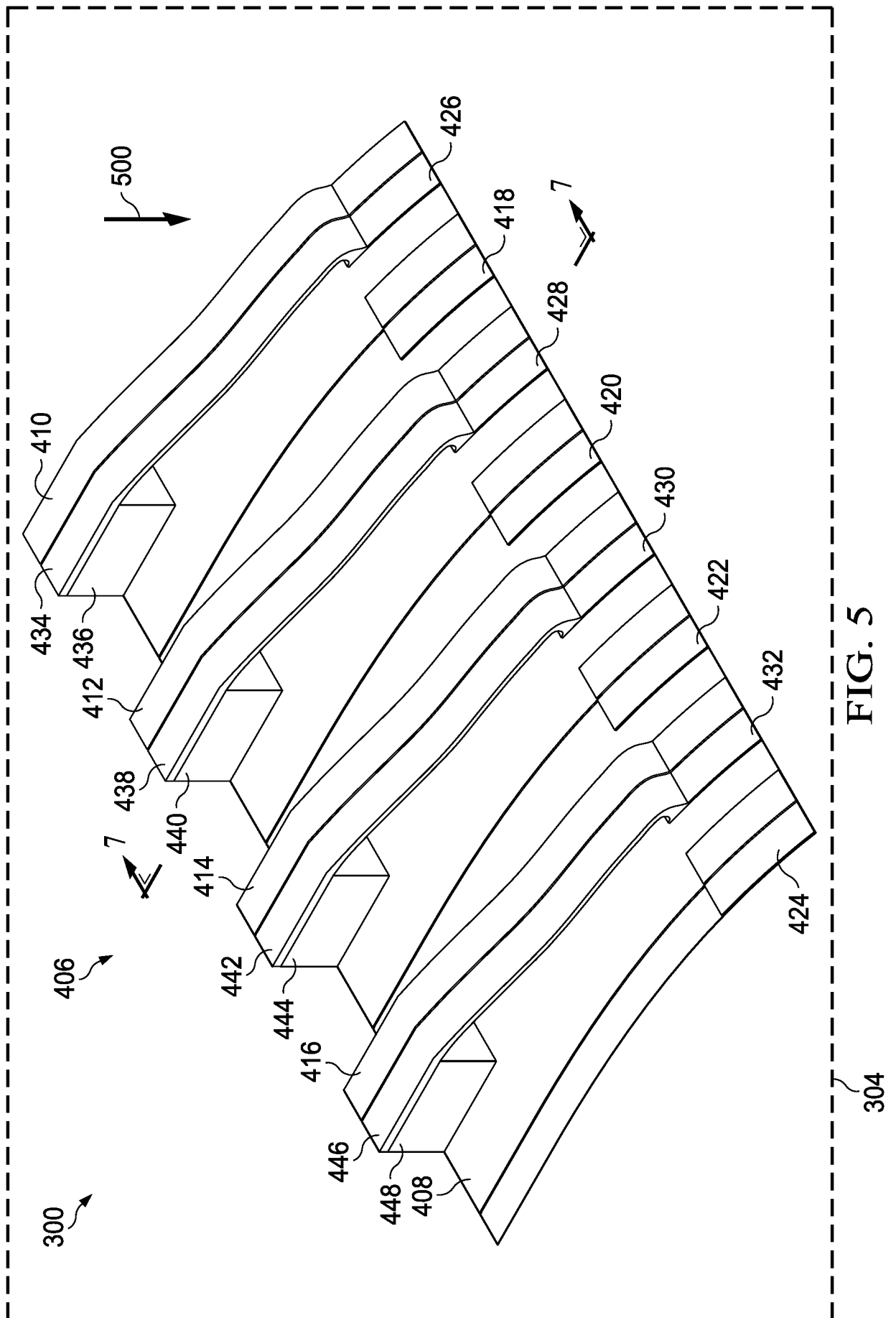


FIG. 4



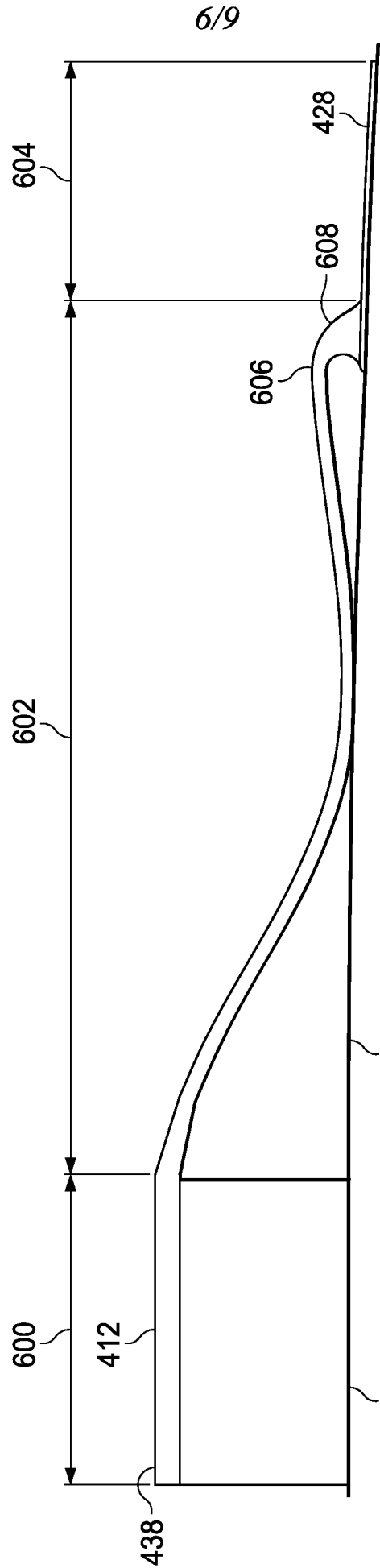
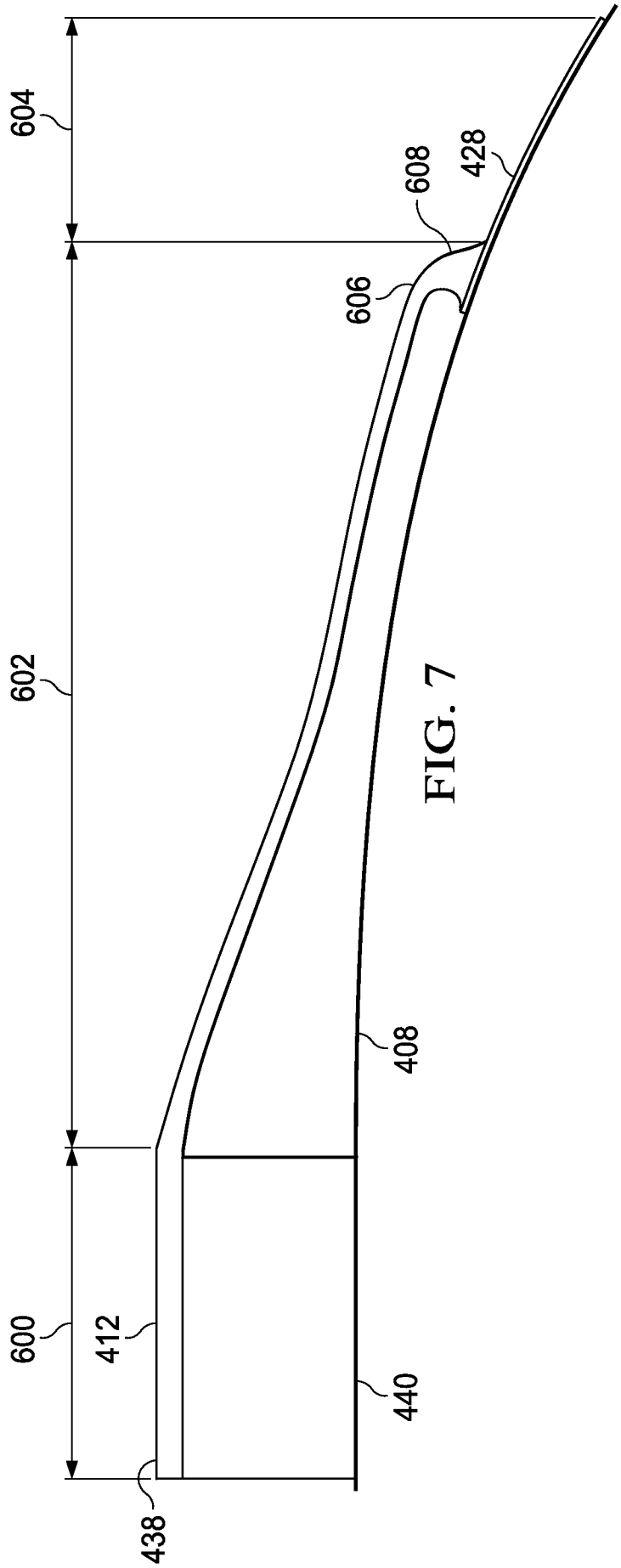


FIG. 6



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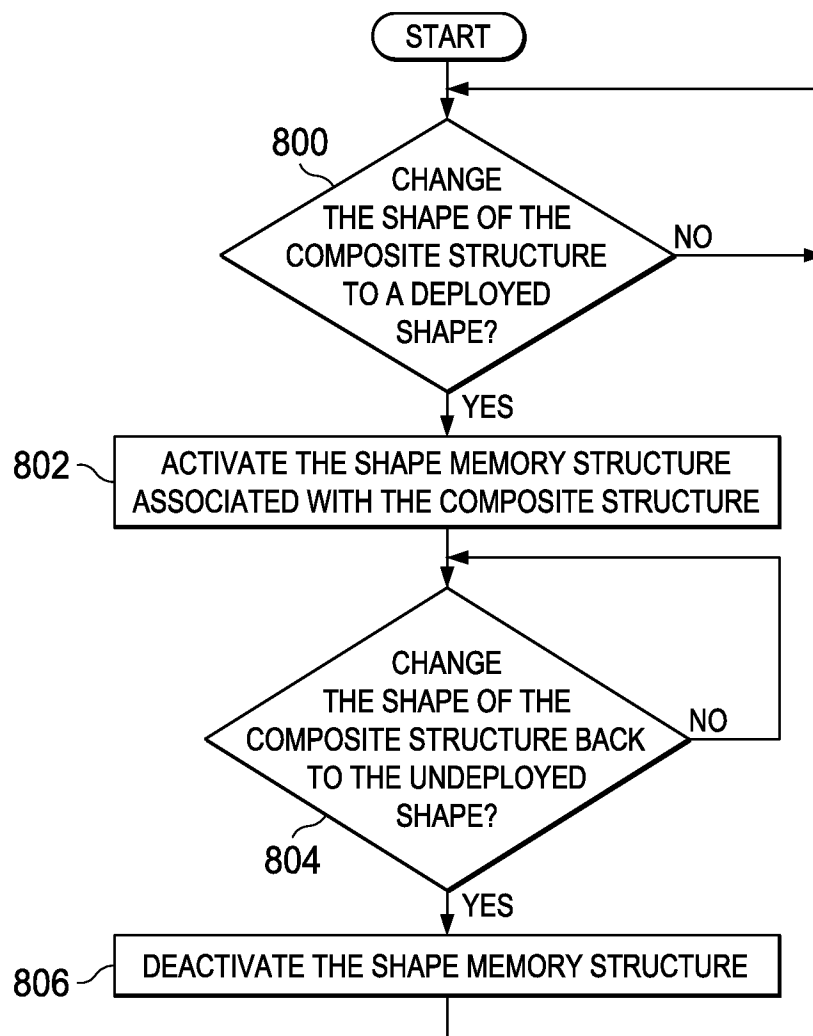


FIG. 8

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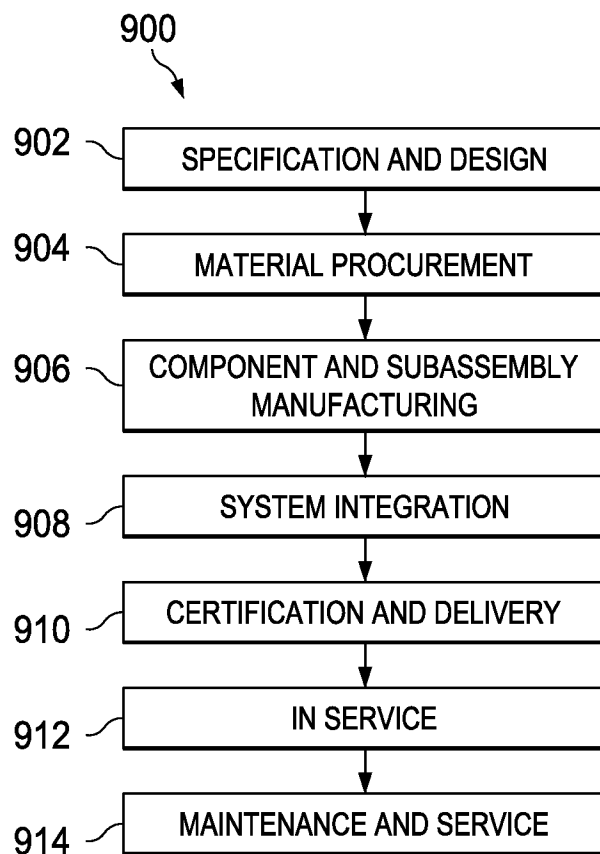


FIG. 9

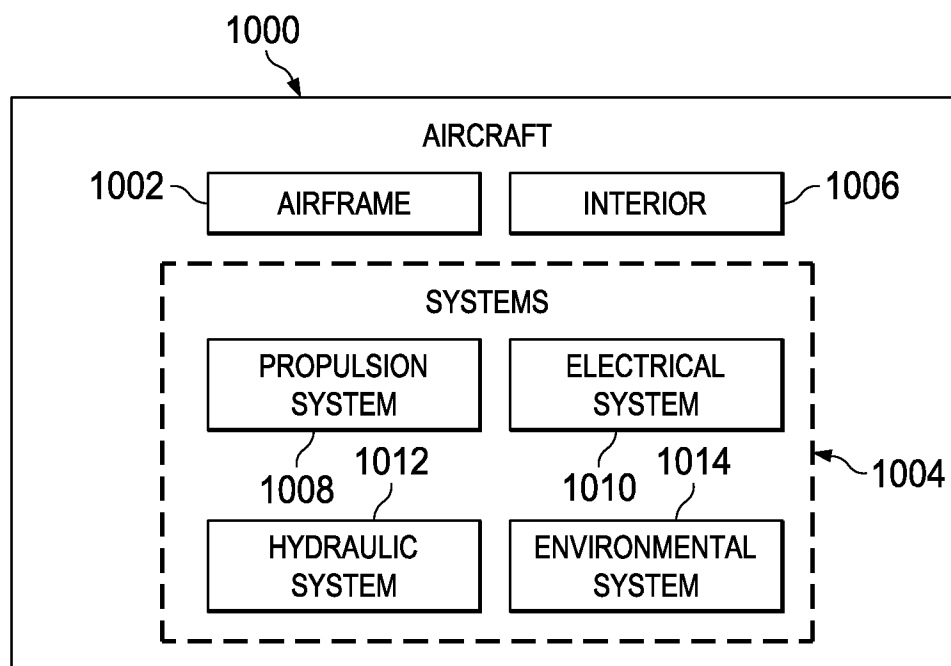


FIG. 10

INTERNATIONAL SEARCH REPORT

International application No
PCT/US2015/024070

A. CLASSIFICATION OF SUBJECT MATTER		
INV. B64C3/48	B64C3/44	B64C9/02 B64C9/16 B64C13/50
ADD.		
According to International Patent Classification (IPC) or to both national classification and IPC		
B. FIELDS SEARCHED		
Minimum documentation searched (classification system followed by classification symbols) B64C F42B F02K F03G		
Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched		
Electronic data base consulted during the international search (name of data base and, where practicable, search terms used) EPO-Internal, WPI Data		
C. DOCUMENTS CONSIDERED TO BE RELEVANT		
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☒ Further documents are listed in the continuation of Box C. ☒ See patent family annex.		
* Special categories of cited documents : "A" document defining the general state of the art which is not considered to be of particular relevance "E" earlier application or patent but published on or after the international filing date "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "O" document referring to an oral disclosure, use, exhibition or other means "P" document published prior to the international filing date but later than the priority date claimed "T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art "&" document member of the same patent family		
Date of the actual completion of the international search 7 December 2015		Date of mailing of the international search report 16/12/2015
Name and mailing address of the ISA/ European Patent Office, P.B. 5818 Patentlaan 2 NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Fax: (+31-70) 340-3016		Authorized officer Cesaro, Ennio

INTERNATIONAL SEARCH REPORT

International application No
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