
nig.2.


वlly

ELECTRICAL SWITCH AND CIRCUIT



## 2,831,074

## ELECTRICAL SWITCH AND CIRCUTT

Joseph Schaefer, Maywood, III.<br>Application January 11, 1954, Serial No. 403,312<br>11 Claims. (Cl. 200-9)

This invention relates to electrical circuits and more particularly to a novel impedance system wherein current at high voltages may be safely conducted across small contacts arranged to divide the current flow, and to a novel switch having a plurality of such contacts, certain of which are sequentially moveable to selectively energize devices in independent circuits associated therewith or to seiectively control the voltage and current flow in one or more electrical circuits.
A primary object of the present invention is to devise a switch, such as above described, which is of economical compact, and sturdy construction capable of long life in service, and which utilizes a minimum number of parts to achieve the desired functions.
A more specific object of the invention is to provide a plurality of moveable contacts sequentially operable to open and close circuits through any desired number of fixed contacts associated with each moveable contact.

Another object of the invention is to devise moveable contacts in the form of rollers which are spring pressed to "make" position and which are locked in each "make" position thereof until positively actuated by an operator to a different "make" position.

Still another object of the invention is to afford an unusually compact switch, such as above described, wherein each moveable contact is rotatable to its various "make" positions.

A further object of the invention is to mount the spring associated with each moveable contact in a cage or barrel which is open at both ends, one end being removeably received within slots of an actuator gear, so that the spring seats against the gear and urges the moveable contact into tight engagement with related fixed contacts.
A different object of the invention is to devise an electrical impedance system for dividing current flow and directing such flow through a plurality of resistances in such manner as to accommodate selection of any desired total resistance.
The foregoing and other objects and advantages of the invention will become apparent from a consideration of the following specification and accompanying drawings, wherein:

Figure 1 is an end elevational view of a preferred embodiment of a switch embodying my invention;

Figure 2 is a sectional view on line 2-2 of Figure 1;
Figure 3 is a sectional view on line 3-3 of Figure 2;
Figure 4 is a perspective view of a drive gear or spool for one of the moveable contacts;

Figure 5 is a perspective of a pinion gear for transmitting driving force from a drive gear to its related actuator gear for a moveable contact;

Figure 6 is a fragmentary end view similar to Figure 1, but showing a modification of the switch;

Figure 7 is a wiring diagram of a novel rheostat circuit in which the switch is used as a sequential tap switch; and

Figure 8 is a wiring diagram of another novel circuit in which the switch is utilized as a voltage regulator for a transformer.

Describing the invention in detail, the novel switch 5 comprises a plurality of insulator plates illustrated at 2, 4, 6 , and 8 , although any desired number may be utilized. These plates are mounted on side panels 10 and 12, as for example by three bolt and nut assemblies 14 having spacers 16 to maintain desired spacing between 10 the plates.

Each plate carries pairs of fixed electrical contacts 18 to 39 , respectively, in the form of cylinders anchored by screw and nut assemblies 40. Insulator cylinders 42, similarly anchored by screw and nut assemblies 44, are positioned between the pairs of fixed contacts and are preferably of larger diameter than the contacts for a purpose hereinafter discussed.

Each contact 18 to 39 is provided with a connector in or blade 46 preferably compressed between the contact and its supporting plate by the associated screw and nut assembly 40 . The blades 46 are perforated as at 48 , to afford convenient connections to associated leads as hereinafter discussed in connection with Figures 7 and 8. It may be noted in this regard that corresponding contacts of the respective plates may be interconnected by such leads, or if desired all or any desired pairs of contacts may be independently comnected to circuits which are to be separately energized and deenergized.

A moveable contact 50 is associated with the fixed contacts 18 to 39 of each plate 2, 4, 6, and 8, said contact 50 being preferably in the form of a roller rotatably mounted as at 52 on a plunger 54 received within a spring tube or cage 56 which is manually press-fitted within slots 58 of an electrically non-conductive actuator gear 60 rotatably mounted on a shaft 62. Gear 60 may be conductive if contact 50 is otherwise insulated from shaft 62 , or if the contact 50 is itself connected to a lead and is used to close a circuit with each fixed contact. A compression spring 64 is compressed between the gear 60 and the plunger 54 to urge the roller contact 50 into tight engagement with the related fixed contacts.
Each gear 60 is actuated by teeth 66 and 67 of a pinion gear 68 rotatably mounted on a shaft 70. In the illustrated embodiment of the invention, the teeth 67 are mutilated, so that all teeth 65 and 67 mesi with teeth of the related gear 60, but only the teeth 66 mesh with three pairs of teeth 72 of a drive gear or spool 74 having a flange 76 comprising notches 78 aligned with the spaces between the respective pairs of teeth 72.

By means of this novel construction, two of the unmutilated teeth 66 of pinion gear 68 ride on the flange 76 locking the gear 68 against accidental rotation until one of the teeth 72 engages a mutilated tooth 67 whereupon pinion gear 68 is rotated $90^{\circ}$ to actuate its roller contact 50 from a closed or "make" position with respect to one pair of fixed contacts 18 to 39 to a closed or "make" position with respect to the next adjacent pair of fixed contacts 18 to 39.

The gears 74 are keyed to a rotatable shaft $\mathbf{8 0}$ and are arranged, as best seen in Figure 1, so that the roller contacts 50 are preferably sequentially actuated. In the illustrated embodiment, $30^{\circ}$ rotation of the shaft 80 actuates the roller contact 50 associated with one of the plates, for example plate 2. Rotation of the shaft 80 through another $30^{\circ}$ increment in the same direction actuates the roller contact 50 of plate 4. Rotation of the shaft 80 through a third increment of $30^{\circ}$ in the same direction actuates roller contact 50 of plate 6 . Rotation of the shaft 80 through a fourth increment of
$30^{\circ}$ in the same direction actuates the roller contact 50 of plate 8, etc.

Thus it will be understood that the shaft $\mathbf{8 0}$ is geared to each pinion gear 68 at a 3 to 1 ratio in the illustrated embodiment, so that one complete rotation of shaft 78 actuates each of the roller contacts 50 three times in a sequential relationship with respect to the other roller contacts 50, although it will be understood that any desired ratio may be utilized.

The shaft 30 may be provided with a handle 82 or any other suitable actuating means (not shown) for manual or powered rotation of shaft 80 in both directions.

It may also be noted that as each roller contact 50 is actuated it rolls across one of the insulator cylinders 42 which separate the pairs of fixed contacts. For example, as shown in Figure 2, roller 50 has moved from its closed or "make" position relative to a pair of contacts 28 and 29 toward a closed or "make" position with respect to another pair of contacts 30 and 31 . However, the insulator cylinder 42 between contacts 29 and 39 positively prevents any possibility of a short circuit therebetween. This action may be accomplished, as illustrated, by providing insulators 42 of larger diameter than contacts 18 to 39 or by any other construction wherein the insulators 42 are closer than the contacts to the rotational axis of gears 60.

The contacts of each plate 2, 4, 6, and 8 may be regarded as a bank of contacts, with insulators 42 between the pairs of contacts in each bank.

Figure 6 shows a modification wherein one contact of each pair is integral with corresponding contacts of adjacent insulator plates. For example, a continuous contact rod 84 is substituted for the contacts 18 of Figures 1 and 2 , and similar rods are substituted for contacts 20 , $22,24,26,28,30,32,34,35$, and 38 of the previous embodiment shown in Figures 1 and 2. The ends of these rods 84 are secured to a pair of insulator plates 86 and 88 as by nuts 90 , and one end of each rod 84 is provided with an additional nut 92 afording convenient means for attaching a lead 94. Also in Figure 6, the insulator cylinders 42 are replaced by continuous insulator rods 96, one of which is shown in this figure. All other paits of Figure 6 are identical with those of Figures $1-5$ and are identified by corresponding numerals, although Figure 6 is fragmentary to illustrate the above described modifications of the switch shown in Figures 1-5.

The modification of Figure 6 is particularly adapted to the novel rheostat system shown in Figure 7, wherein it will be seen that the contact rods 34 are connected to resistances $\mathbb{Z}-1$ to $Z-9$ arranged in series. These are preferably the main resistances and should be able to carry the full current in the rheostat.

In the diagram of Figure 7, the insulator plates are shown at 2, 4, 6, and 8, and two additional plates are shown at $2 a$ and $\& a$. Dividing resistors $D-1$ to $D-6$ are connected in parallel with each other, each dividing resistor being connected to the fixed contacts 19, 21, 23, $25,27,23,34,33,35$, and 37 of one insulator plate. The resistors $\mathrm{Z}-1$ to $\mathrm{Z}-9$ and resistors $\mathrm{D}-1$ to $\mathrm{D}-6$ are shown conventionally and may be simple resistors having fixed resistance values or may be conventional adjustable resistors which may be adjusted to any predetermined value. Within alternating current, reactors may be substituted for resistors to provided voltage or current regulation.

The system shown in Figure 7 depicts a 250 ampere load rheostat ( $25-250$ velts) that uses a six plate sequential switch such as those shown in Figures 1-6. Resistance values are shown in the diagram by way of example, and it will be noted that in order to stay within the current rating of the contacts (nominally 50 amperes) it is preferable to taper the resistance values of the dividing resistors D-1 to D-6, as for example in the manner indicated in Figure 7.

The minimum resistance of the rheostat shown in Figure 7 is 0.1 ohm at step 1 whereat moveable contacts 50 connect the fixed contacts 10 to the related contact rod 8s. Under these conditions current flow across resistors D- 1 to D-6 is respectively, $50 \mathrm{amps} ., 48 \mathrm{amps}$., 44 amps., 40 amps., 34 amps ., and 29 amps.
At step 2 the moveable contact 50 of plate 2 connects the fixed contact 21 there of to the related contact rod 84 , so that the total resistance in the rheostat is about .105 chm which is the value of $D-1$ and $Z-1$ in series and in paraliel with the value of D-2 to D-6 in parallel. Under these conditions current flow across $\mathrm{Z}-1$ is 44 amps. and current flow across $D-1$ to $D-6$ is, respectively, 44 amps., 50 amps., 46 amps., 42 amps., 36 amps., and 31 amps.
At step 3 the moveable contact of plate 4 connects its fixed contact 21 to the related contact rod 84, so that the total resistance in the rheostat is about .114 ohm which is the value of D-1 and D-2 in parallel and in series with Z-1, in parallel with the value of D-3 to D-6 in parallel. Under these conditions, current flow across Z-1 is 81 amps ., and current flow across D-1 to D-6 is, respectively, 41 amps ., 40 amps ., 50 amps ., 46 amps ., 39 amps., and 34 amps .
At step 4 the moveable contact 50 of plate 6 connects its fixed contact 21 to the related contact rod 84, so that the total resistance in the rheostat is .129 ohm which is the value of D-1 to D-3 in parallel and in series with Z-1, in parallel with the value of $D-6$ to $D-6$ in parallel. Under these conditions, current flow across Z-1 is 119 amps., and current flow acress $D-1$ to $D-6$ is, respectively, 42 amps., 40 amps., 37 amps., 51 amps., 46 amps., and 38 amps.
At step 5 , the moveable contact 50 of plate 8 connects its fixed contact 21 to the related contact rod 84, so that the total resistance in the rheostat is .148 ohm , which is the value of D-1 to D-4 in parallel and in series with Z-1, in parallel with the value of D-5 and D-6 in parallel. Under these conditions, current flow across Z-1 is $157 \mathrm{amps} .$, and current flow across $\mathrm{D}-\mathbf{1}$ to D-6 is, respectively, 43 amps., 42 amps., 38 amps ., 34 amps., 51 amps., and 44 amps .

At step 6, the moveable contact 50 of plate $2 a$ connects its fixed contact 21 with the related contact rod 84 , so that the total resistance in the rheostat is .172 ohm, which is the value of D-1 to D-5 in parallel and in series with Z-1, in parallel with D-6. Under these conditions, current flow across Z-1 is 199 amps ., and current flow across D-1 to D-6 is, respectively, 46 amps., 45 amps., 41 amps., $37 \mathrm{amps} ., 32 \mathrm{amps}$., and 51 amps .
At step 7, the moveable contact of insulator plate $4 a$ connects its fixed contact 21 , with the related control rod 84 , so that the total resistance in the rheostat is .20 ohm , the value of D-1 to D-6 in parallel and in series with Z-1. Under these conditions, current fiow across Z-1 is 250 amps., and current flow across $D-1$ to $D-6$ is, respectively, $50 \mathrm{amps} ., 48 \mathrm{amps} ., 44 \mathrm{amps} ., 40 \mathrm{amps}$., 34 amps., and 29 amps.
The above values are approximate, and successive steps in the rheostat would have the same current division and voltage values if the current is maintained at 250 amps.

The maximum total resistance value in the system of Figure 7 is reached when the sequential operation of contacts 59 finally engages all contacts 50 with the fixed contacts 37 and the related contact rod 84 , so that the total resistance value is 1.0 ohm , which is the value of D-1 to D-6 in parallel and in series with the value of Z-1 to Z-9 in series.

By proper adjustment of the resistance values and ratios of Z-1 to Z-9 and D-1 to D-6, the current in the contacts can be held to a maximum permissible value that they can safely make and break. The voltage across resistors $\mathrm{D}-\mathbf{1}$ to $\mathrm{D}-6$ is the voltage which is broken by the contacts. Increasing the number of series resistors Z-1 to Z-6 (as for example by using all of the odd numbered contacts of Figures 1 and 2), and decreasing values
of $\mathrm{D}-1$ to $\mathrm{D}-6$ results in smaller voltage drop that the contacts must break.
In this manner, a heavy current rheostat may be provided with small contacts by subdividing the heavy current into a larger number of smaller parallel currents.
Figure 8 is similar to Figure 7, and corresponding parts are identified by corresponding numerals; however in the circuit of Figure 8, the resistors are replaced by transformer taps Z-1 to Z-6 of a conventional insulating or potential transformer 100 to produce a voltage regulator therefor. In this arrangement, four insulator plates and four dividing resistors D-1 to D-4 are used; however more may be added if desired. Similarly, the novel system may be utilized as a voltage regulator for an auto transformer.

What is claimed is:

1. A switch comprising a plurality of substantially cylindrical contacts having substantially parallel axes, said contacts being arranged in pairs, a movable substantially cylindrical roller contact simultaneously engageable at points spaced angularly about its rolling axis with the contacts of each pair, spring means for urging said roller contact against said first mentioned contacts, and means for moving said roller contact from pair to pair of said first mentioned contacts, said moving means insulating the roller contact against electrical conduction other than between said cylindrical contacts, the rolling axis of said roller contact being substantially parallel to said axes, whereby the roller contact is releasably locked in line contact with the cylindrical contacts of one pair by the action of said spring means.
2. A switch of the class described comprising a plurality of banks of fixed electrical contacts, the contacts of each bank being substantially cylindrical and being arranged in a plurality of pairs, moveable contacts associated with respective banks for selectively closing electrical circuits across the pairs of fixed contacts, each movable contact comprising a substantially cylindrical roller surface simultaneously engageable with the contacts of each related pair at points spaced angularly about the rolling axis of said surface, and means for sequentially actuating said movable contacts and for insulating them against electrical conduction other than between the related fixed contacts, the rolling axis of each movable contact being substantially parallel to the axes of its related fixed contacts, and spring means for urging each movable contact against its related fixed contacts, whereby each movable contact is releasably locked in line engagement with the fixed contacts of the related pair by the action of said spring means.
3. A switch of the class described comprising a plurality of spaced insulator plates, a plurality of pairs of fixed cylindrical contacts carried by each insulator plate, a movable contact having a substantially cylindrical surface associated with each insulator plate for interconnecting the fixed cylindrical contacts of each pair of contacts carried by said insulator plate, and means for sequentially actuating the moveable contacts of respective insulators and for insulating the movable contacts against electrical conduction other than between the related fixed contacts, the rolling axis of each movable contact being substantially parallel to the axes of its related fixed contacts, and spring means for urging each movable contact against its related fixed contacts, whereby each movable contact is releasably locked in line engagement with the fixed contacts of the related pair by the action of said spring means.
4. A switch of the class described, comprising an insulator carrying a plurality of fixed, substantially cylindrical contacts spaced from each other and arranged in pairs, a plurality of substantially cylindrical insulators carried by the first mentioned insulator and arranged one between each pair of said fixed contacts, a movable contact having a substantially cylindrical roller with its rolling axis approximately parallel to the axes of said fixed contacts and to the axes of said cylindrical insulators, the axis of each cylindrical insulator being closer to said解酸 means for urging each roller contact against its related cylindrical contact, whereby each roller contact is releasably locked in line contact with the cylindrical con5 tacts of a pair by the action of said spring means.

8
10. In a switch of the class described, a plurality of fixed contacts arranged in a plurality of series, an actuator gear associated with each series, a movable contact actuated by each gear to engage the contacts of the related series, and means for sequentially operating said gears comprising pinion gears having teeth, all of which are meshed with those of the respective actuator gears, alternate teeth of each pinion gear being mutilated, and a drive gear having at least one pair of teeth adapted to mesh with the other teeth of said pinion gear, the drive gear teeth asscciated with each pinion gear being misaligned with the drive gear teeth associated with the other pinion gears, whereby said actuator gears are sequentially actuated.
11. A switch according to claim 10 , wherein each drive 1 gear comprises a collar engageable with said other teeth of the related pinion gear to lock the latter against accidental rotation.
$\qquad$
$\qquad$


1,248,624 1,285,786 1,496,874 1,511,329 ,511,329 1,649,136 1,753,854

## References Cited in the file of this patent

UNITED STATES PATENTS
Creveling ---...............-



Smith et al. ...-.-.-.-....... Nov. 15, 1927
Fischer ---------------- Apr. 8, 1930
Meuer _---....-.---....-. June 30, 1931
Brand et al. _---.-.-.----- June 14, 1932
Wilhelm _-.................... Nov. 11, 1947
McKenney -------------- Aug. 30, 1949 Dec. 4, 1917

FOREIGN PATENTS
548,071 Germany Apr. 5, 1932

