



- (51) **International Patent Classification:**
A61B 3/113 (2006.01) G06F 3/01 (2006.01)
- (21) **International Application Number:**
PCT/GB2010/002165
- (22) **International Filing Date:**
25 November 2010 (25.11.2010)
- (25) **Filing Language:** English
- (26) **Publication Language:** English
- (30) **Priority Data:**
0920809.1 27 November 2009 (27.11.2009) GB
- (71) **Applicant (for all designated States except US):** QINETIQ LIMITED [GB/GB]; Cody Technology Park, Ively Road, Farnborough, Hampshire GU14 0LX (GB).
- (72) **Inventors; and**
- (75) **Inventors/Applicants (for US only):** DURNELL, Laurence [GB/GB]; QinetiQ Limited, Cody Technology Park, Ively Road, Farnborough, Hampshire GU14 0LX (GB). JARRETT, Donald, Nigel [GB/GB]; 15 Sunnymead, Keynsham, Bristol BS31 1JD (GB).
- (74) **Agent:** NORTHWAY, Daniel, R.; QinetiQ Limited, Intellectual Property, Malvern Technology Centre, St Andrews Road, Malvern, Worcestershire WR14 3PS (GB).

- (81) **Designated States (unless otherwise indicated, for every kind of national protection available):** AE, AG, AL, AM, AO, AT, AU, AZ, BA, BB, BG, BH, BR, BW, BY, BZ, CA, CH, CL, CN, CO, CR, CU, CZ, DE, DK, DM, DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IS, JP, KE, KG, KM, KN, KP, KR, KZ, LA, LC, LK, LR, LS, LT, LU, LY, MA, MD, ME, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PE, PG, PH, PL, PT, RO, RS, RU, SC, SD, SE, SG, SK, SL, SM, ST, SV, SY, TH, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.
- (84) **Designated States (unless otherwise indicated, for every kind of regional protection available):** ARIPO (BW, GH, GM, KE, LR, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV, MC, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK, SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

Declarations under Rule 4.17:

— of inventorship (Rule 4.17(iv))

Published:

— with international search report (Art. 21(3))

(54) Title: EYE TRACKING

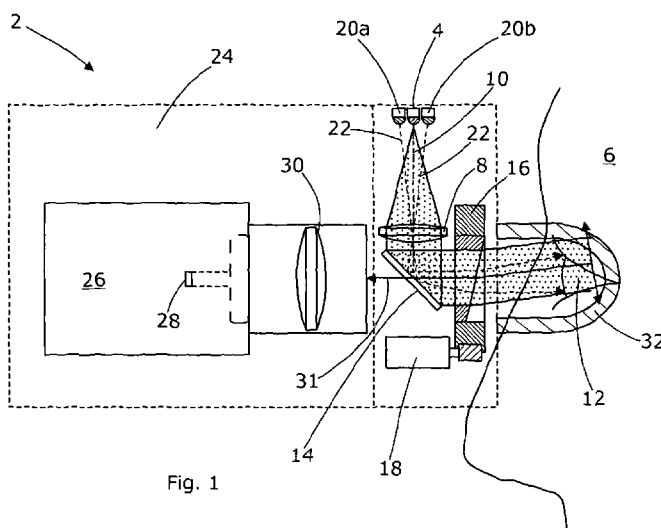


Fig. 1

(57) **Abstract:** An eye tracking apparatus (2) comprising a target display (4) adapted to project a moveable image of a target into a user's field of vision, an illumination source (20a, 20b) adapted to project a reference point onto a user's eye (12) and a sensor (26) adapted to monitor a user's eye (12), and a processor adapted to determine the position of a feature of a user's eye relative to the reference point. Calibration of the eye tracking apparatus can be avoided through an advantageous arrangement of the target display and the eye sensor within the eye tracking apparatus, such that the sensor images the user's eye along the target direction. Thus the information gathered at the sensor concerning the relative positions of the reference point and the user's eye is by itself sufficient to determine the user's eye direction relative to the target.



EYE TRACKING

The present invention relates an eye tracking apparatus and to a method of monitoring the movement of a user's eyes. Without limitation, the invention relates specifically to a
5 portable eye tracking apparatus suitable for medical applications such as assessment of neurological conditions and mild traumatic brain injury (mTBI).

Eye tracking apparatuses are used in medical and research establishments for monitoring the physiological and neurological state of subjects. For example US
10 7,384,399 describes a system and method for testing a subject for cognitive impairment. However, conventional eye tracking apparatuses and medical equipment incorporating the same are traditionally complex in construction and operation. Conventional eye tracking apparatus incorporates sophisticated display and imaging components making them expensive. Such conventional eye tracking apparatus also
15 requires calibration prior to use and can only be operated by a skilled operator or clinician.

US 2003/0123027A describes an alternative system for eye gaze tracking which does not require active calibration. Specifically, the system of US 2003/0123027A
20 determines the user's point of regard by imaging a test pattern of reference points reflected from the user's cornea. The user's point of regard is calculated indirectly by mapping or mathematically relating the reflected test pattern image to the actual test pattern in real space. Whilst active calibration is obviated, the system of US 2003/1023027A requires the mapping relationship between an image coordinate
25 system and a reference coordinate system to be defined prior to use.

It is an object of the invention to provide an eye tracking apparatus which mitigates at least one disadvantage of conventional devices.

30 According to a first aspect of the present invention, there is now proposed an eye tracking apparatus comprising a target display adapted to project a moveable image of a target into a user's field of vision, an illumination source adapted to project a reference point onto a user's eye, a sensor adapted to monitor a user's eye, and a processor adapted to determine the position of a feature of a user's eye relative to the

reference point, wherein the apparatus is arranged such that said determined position provides a direct indication of eye direction relative to the target direction.

The eye tracking apparatus provides the advantage that the information gathered at the
5 sensor concerning the relative positions of the reference point and the user's eye is by
itself sufficient to determine the user's eye direction relative to the target, and inherently
contains information concerning the target direction in the user's field of view because
of the arrangement of the system. No further information is needed, as opposed to an
indirect system where additional reference to a target direction is typically required, e.g.
10 via a calibration step or measurement. The elimination of the calibration process offers
potential benefits in terms of increasing the accuracy of eye tracking apparatuses and
enabling eye tracking apparatuses to be used by non-specialist operators.

Conventional eye tracking apparatuses typically require calibration prior to use, for
15 example in order determine the absolute position of a user's point of regard in a real or
virtual scene. Such calibration usually comprises a process in which the user is asked
to fixate their gaze on a point within the scene having a known location therein and
simultaneously measuring the position of features of the user's eye using an imaging
sensor. The calibration process typically requires a plurality of measurements be taken
20 at a series of calibration points. The user's point of regard in the scene can
subsequently be determined from a measurement of the positions of features of the
user's eye in an image thereof from the sensor. Alternatively or additionally, a
comparison with the location of a visual target then needs to be made, with the target
location and user's point of regard in compatible measurement space.

25

However, the abovementioned calibration process is time-consuming and must
normally be conducted by a trained and experienced operator in order to provide
reliable eye tracking. The requirement for a trained and experienced operator has
hitherto restricted the application of eye tracking apparatuses to medical and research
30 laboratories. This is particularly true in the case of eye tracking apparatuses used for
neurological assessments, for example for measuring a subject's cognition, and for
assessing mild traumatic brain injuries (mTBI).

The calibration process also accounts for the largest contribution towards inaccuracies
35 in conventional eye tracking apparatuses.

Hence, the elimination of the calibration process offers potential benefits in terms of increasing the accuracy of eye tracking apparatuses and enabling eye tracking apparatuses to be used by non-specialist operators.

5

Embodiments of the present invention obviate calibration of the eye tracking apparatus through an advantageous arrangement of the target display and the eye sensor within the eye tracking apparatus, such that the sensor images the user's eye along the target direction, which is to say the optical path along which the target is projected into the user's field of view. The angular error of the eye line-of-sight from the direction of the moveable target may then be determined directly by imaging the eye. Where the direction of illumination is also coincident with the target direction, a direct determination of eye direction relative to the target and hence eye-target error is obtained by measuring a distance between the reference point on the user's eye and a physical feature of the user's eye.

In a preferred embodiment, the target display is adapted to project the moveable image along a projection path, the illumination source is adapted to project the reference point along an illumination path, the sensor is adapted to monitor the user's eye along an imaging path, and wherein at least a portion of the projection path, the illumination path and the imaging path are arranged to be substantially coaxial.

It will be understood that the projection path, the illumination path and the imaging path are preferably arranged to be substantially coaxial as they enter the user's field of view. Furthermore it should be clear to the skilled person that said paths may diverge from a common optical path where said paths emanate from the target display and the illumination source and where the imaging path enters the sensor.

In a preferred embodiment, the target and illumination source are effectively coincident, and in certain embodiments the target display and the illumination source may be one and the same.

In embodiments where the target traces a moving path, the apparatus is preferably adapted so that the imaging path of the sensor is maintained in alignment along the target direction. That is, the imaging path is coupled to the target projection path.

Preferably therefore, the eye tracking apparatus is arranged to scan the illumination path, the projection path and the imaging path in synchronisation within the user's field of vision. Scanning or tracing is advantageously achieved by a mechanical moving element, such as a rotating prism, mirror or other optical element. In such
5 embodiments the projection path, the illumination path and the imaging path should preferably follow a common optical path through said optical element.

In a preferred embodiment, the sensor is configured to monitor the position of the reference point with respect to a physical feature of the user's eye using an imaging
10 sensor. Without limitation, the sensor may be a photosensitive device (PSD) or an imaging sensor adapted to image the user's eye. Conveniently, the processor is adapted to determining a distance between the position of the reference point and a physical feature of the user's eye.

15 This is advantageous because the distance between the reference point and the eye feature gives a direct indication of eye-target error due to the coaxial arrangement of reference illumination axis, target projection axis and imaging axis.

Advantageously, the processor is adapted to convert the determined distance into a
20 measurement of an angle between the target direction and the user's eye direction.

The feature of the user's eye desirably comprises at least one of the user's pupil and the user's iris.

25 For example, the feature of the user's eye may comprise the outer circumference of the pupil or iris of the user's eye. Alternatively, the feature of the user's eye may comprise the centre of the pupil, determined for example from the outer circumference thereof. Similarly, the feature of the user's eye may comprise the centre of the iris, determined
30 for example from the outer circumference thereof.

In a preferred embodiment, the indication of eye direction relative to the target is obtainable by monitoring the concentricity of the reference point and the pupil of the user's eye.

In one embodiment, the eye tracking apparatus is adapted to scan the image of the target in the user's field of vision with a substantially constant angular velocity. This enables the eye tracking apparatus to measure the ability of the user's eye pursue a smoothly moving target image.

5

Alternatively, the eye tracking apparatus is adapted to scan the image of the target in the user's field of vision with a varying angular velocity.

Preferably, the eye tracking apparatus is adapted to scan the image of the target in the user's field of vision along a controlled path that includes at least one of a point, a line, an arc, a circle, and an ellipse.

The image of the target may be scanned in the user's field of vision using an optical element moveable by at least one of a micro-electromechanical actuator, a motor, a piezo micro-positioner, a galvanometer and a manually operable lever.

In another preferred embodiment, the eye tracking apparatus comprises a modulator adapted to temporally vary at least one of the brightness, the hue, the shape and the form of the image of the target. This enables the eye tracking apparatus to move a changeable target image in a discontinuous scan in order to assess the user's anticipatory response. This is beneficial in that a wider range of cognitive functions can be assessed using the apparatus.

According to a second aspect, there is proposed a method of eye monitoring in which a moveable image of a target is projected into a user's field of vision, and an image of the user's eye is formed on an image sensor, said method comprising: projecting a reference point onto the user's eye, arranging for the selected reference point to provide, in the image, an indication of the position of the target on the user's eye, and analysing the image to determine the position of a feature of the user's eye with respect to the reference point.

Preferably, the method comprises analysing the position of the user's eye relative to the reference point in the image to measure eye tracking of said moving target.

The reference point may be projected onto the user's eye by illuminating the eye so as to produce a spot corneal reflex as said reference point.

5 The method may further comprise projecting the moveable target and the illumination generating the reference point along a common projection path and monitoring the user's eye along an imaging path, wherein at least a portion of said imaging path is substantially coaxial with said common projection path.

10 It will be understood that the projection path, the illumination path and the imaging path are arranged to be substantially coaxial as they enter the user's field of view. Furthermore it should be clear to the skilled person said paths may diverge from a common optical path where said paths emanate from the target display and the illumination source and where the imaging path enters the sensor.

15 Preferably, the method comprises the step of scanning the common projection path and the imaging path in synchronisation within the user's field of vision.

Conveniently, the method comprises the step of analysing the image to determine a distance between the feature of the user's eye and the position of the reference point.
20 This is advantageous because the distance between the reference point and the eye feature gives a direct indication of eye-target error due to the coaxial arrangement of reference illumination axis, target projection axis and imaging monitoring axis.

In a preferred embodiment, the method comprises the step of converting the
25 determined distance into a measurement of an angle between the target direction and the user's eye direction.

Conveniently, the feature of the user's eye comprises at least one of the user's pupil and the user's iris.
30

As explained above, the features of the user's eye may comprise the outer circumference of the pupil or iris of the user's eye. Alternatively, the feature of the user's eye may comprise the centre of pupil, determined for example from the outer circumference thereof. Similarly, the feature of the user's eye may comprise the centre
35 of the iris, determined for example from the outer circumference thereof.

In a preferred embodiment, the indication of the user's eye direction relative to the target is obtainable by monitoring the concentricity of the reference point and the pupil of the user's eye.

5

In a preferred embodiment, the method comprises the step of scanning the image of the target in the user's field of vision with a substantially constant angular velocity. This enables the eye tracking apparatus to measure the ability of the user's eye to pursue a smoothly moving target image.

10

Alternatively, the method comprises the step of scanning the image of the target in the user's field of vision with a varying angular velocity.

The method may comprise scanning the image of the target in the user's field of vision along a controlled path that includes at least one of a point, a line, an arc, a circle, and an ellipse.

Preferably, the method comprises the step of moving the image of the target in the user's field of vision using an optical element moveable by at least one of a micro-electromechanical actuator, a motor, a piezo micro-positioner, a galvanometer, and a manually operable lever.

The method may also comprise the step of temporally varying at least one of the brightness, the hue, the shape and the form of the image of the target. This enables the method to monitor eye movement of a changeable target image in a discontinuous scan in which case the method may also comprise the step of assessing the user's anticipatory response. This is beneficial in that a wider range of cognitive functions can be assessed using the present method.

30 The invention extends to methods, apparatus and/or use substantially as herein described with reference to the accompanying drawings.

Any feature in one aspect of the invention may be applied to other aspects of the invention, in any appropriate combination. In particular, method aspects may be applied to apparatus aspects, and vice versa.

35

Preferred features of the present invention will now be described, purely by way of example, with reference to the accompanying drawings, in which:

- 5 Figure 1 shows a schematic cross-sectional view of an eye tracking apparatus according to one embodiment of the present invention incorporating a rotatable prism arranged to scan a target within a user's field of vision.

Figure 2 shows a sequence of four images of a user's eye taken from an imaging
10 sensor within the eye tracking apparatus of Figure 1 while the user is looking at a target moving in a circular path around a central axis. Specifically, figure 2a illustrates the image of the user's eye when viewing a high target; figure 2b illustrates the image of the user's eye when viewing a target arranged to one side of the user's eye; figure 2c illustrates the image of the user's eye when viewing a low target; and figure 2d
15 illustrates the image of the user's eye when viewing a target arranged to the other side of the user's eye.

Figure 3 shows a schematic cross-sectional view of an eye tracking apparatus according to a second embodiment of the present invention incorporating a rotatable
20 reflector arranged to scan a target within a user's field of vision.

Figure 4 shows schematic block diagram of a neurological monitoring apparatus having an eye tracking apparatus according to the present invention.

25 Referring now to the drawings wherein like reference numerals identify corresponding or similar elements throughout the several views, Figure 1 shows an eye tracking apparatus 2 comprising a target display 4 configured to project an image of a target into the field of vision of a user 6. The target display in the embodiment of Figure 1 comprises a light emitting diode (LED), however alternatives include a liquid crystal
30 display, a lamp or any display capable of acting as a small, source and emitting electromagnetic radiation having a wavelength in the visible spectrum. A lens 8 receives the electromagnetic radiation emitted from the target display 4 and projects said electromagnetic radiation along a projection path 10 into the user's eye 12 via a semi-reflective mirror 14 and a small angle wedge prism 16. In use, the display 4
35 appears as a distant target in the user's field of vision. The wedge prism 16 is rotatable

about the projection axis 10 by a prism rotation mechanism 18. In the embodiment shown in figure 1, the prism rotation mechanism 18 comprises a motor having a shaft mounted pinion arranged in mechanical communication with a gear disposed around the periphery of the wedge prism 16.

5

The eye tracking apparatus also comprises an illumination source comprising infrared light emitting diodes (IR LEDs) 20a, 20b arranged to illuminate the user's eye 12 along an illumination path 22 with electromagnetic radiation having a wavelength in the infrared spectrum. The lens 8 receives the infrared radiation emitted from the illumination source 20a, 20b and projects said infrared radiation along the illumination path 22 into the user's eye 12 via the semi-reflective mirror 14 and the wedge prism 16 that deviates the light by a small angle. An 8° wedge prism 16 has been used experimentally with good results.

15 Some of the infrared radiation illuminating the user's eye 12 produces a detectable bright reference point 23 thereon caused by specular reflection from the anterior surface of the user's eye 12. The illumination source is arranged at a distance from the user such that illuminating electromagnetic radiation emitted there from appears to be substantially collimated to the user. The illumination source is adapted, in use, to
20 illuminate the user's eye and provide a spot corneal reflex as the reference point on the user's eye.

A sensor 24 comprising a camera 26 having a detector 28 and a lens 30 is also provided within the eye tracking apparatus 2 to image the user's eye 12. The camera
25 26 comprises a detector having a photosensitive device (PSD) for example a position sensing photodiode. Optionally, the detector 28 comprises a two-dimensional imaging array. The sensor 24 is configured to receive visible and infrared electromagnetic radiation reflected from the user's eye 12 along an imaging path 31 via the small angle wedge prism 16 and the semi-reflective mirror 14 .

30

The eye tracking apparatus 2 also comprises an eye cup 32 arranged to shield the user's eye 12 from extraneous influences, to prohibit ambient light from interfering with the sensor 24 and to reduce unwanted movement between the eye tracking apparatus 2 and the user 6.

35

The method of operation of the eye tracking apparatus of figure 1 is now described by way of example only. The eye tracking apparatus is firstly arranged in optical communication with the user's eye 12, for example by positioning the eye cup 32 around the user's eye 12. The user's eye 12 is monitored by producing a target image
5 from the target display 4 and projecting said target image into the user's eye 12 along a projection path 10 via the lens 8, the semi-reflective mirror 14 and the small angle wedge prism 16. At the same time, the user's eye 12 is illuminated with infrared radiation from illumination source 20a, 20b along an illumination path 22 via the lens 8, the semi-reflective mirror 14 and the wedge prism 16.

10

The wedge prism 16 is rotated by the prism rotation mechanism 18 at approximately 0.4 Hz about an axis which corresponds approximately to the user's line of sight in a 'straight ahead' position. The projection path 10 enters prism 16 coaxial with the rotation axis, thereby scanning the image of the target through an 8° radius circle in the
15 user's field of vision. The reference point 23 (see Figure 2) caused by reflection of infrared radiation from the anterior surface of the user's eye 12 also moves in synchronisation with projected target image due to the rotation of the wedge prism 16, by virtue of the common optical path through the prism 16.

20 The user's eye 12 tracks the distant target image as it moves through the 8° radius circle. The camera 26 is arranged to image the user's eye 12 along the same imaging path 31 as the target image is scanned in the user's field of vision. Since the imaging path 31 is also arranged along the common optical axis said imaging path passes through the wedge prism 16 and moves in synchronisation with the projected target
25 image and the infrared illumination due to the rotation of the wedge prism 16.

The target display 4, the illumination source 20a, 20b and the sensor 24 are therefore arranged such that the projection path 10, the illumination path 22 and the imaging path all share a common path through the wedge prism 16 to the user's eye. Arranging
30 the projection path 10, the illumination path 22 and the imaging path 31 along a common optical axis in this way ensures that, in use, the sensor 24 views the user's eye 12 along the target direction.

If the user's eye 12 tracks the target image perfectly then the user's eye 12 is directed along the imaging path 31 and the reference point 23 is centred on the user's eye throughout the 8° circular scan.

- 5 A direct determination of eye direction relative to the target and hence eye-target error is obtained by measuring a distance between reference point 23 on the user's eye and a physical feature of the user's eye 12, for example the centre or circumference of the pupil or iris of the user's eye 12.
- 10 Hence, an angular difference between the eye direction and the target direction is obtainable from the measured distance between the reference point 23 on the user's eye and the physical feature of the user's eye 12. Said angular difference is a quantitative assessment of how accurately the user's eye followed the image of the target as it was scanned through the user's field of vision.
- 15 The difference between the eye direction and target direction provides an eye tracking error assessment which may be subsequently used to assess the user's cognitive abilities, neurological deficiencies or cognitive impairment due to illness and / or brain injury.
- 20 The eye tracking apparatus is arranged to measure the distance between the reference point and the feature of the eye at a plurality of locations forming a locus of the target image scan. Eye direction relative to the target and hence eye-target error is therefore obtained at said plurality of locations. In an embodiment intended for medical
- 25 diagnostic purposes, the measurements are made and stored at 250Hz or more.
- The accuracy of the eye tracking apparatus of Figure 1 is principally governed by the accuracy with which the projection path 10, illumination path 22 and imaging path 31 are aligned along the common optical axis in the apparatus. In contrast, the accuracy
- 30 of conventional eye tracking apparatuses is related to the accuracy of the calibration process. The present eye tracking apparatus and method therefore enable the angle between the target direction and the user's eye direction to be measured with high resolution (less than 0.05 degree r.m.s. noise) and high accuracy (less than 0.2 degree r.m.s. error).

- 12 -

Figure 2 shows a sequence of four images of a user's eye 12 taken from the camera 26 within the eye tracking apparatus of Figure 1 while the user 6 is looking at the moving image of the target from the display 4.

5 Specifically, figure 2a illustrates the position of the user's eye 12 when viewing the image of the target at the start of the scan. In figure 2a the target is arranged in a position above the scan centre. The reference point 23 is clearly seen as a bright reflection located substantially in the centre of the pupil 34 of the user's eye 12 indicating that the user is looking directly at the image of the target. Figure 2b illustrates
10 the position of the user's eye 12 when the target is arranged in a position to one side of the scan centre. Although eye 12 and the bright reference point 23 have both moved within the image, the reference point 23 remains in the centre of the pupil 34 of the user's eye 12 indicating that the user is still looking directly at the image of the target. In figure 2c the image of the target is arranged in a position below the scan centre. In
15 figure 2c, the reference point 23 is once again concentric with the pupil 34 of the user's eye 12. Finally, figure 2d illustrates the position of the user's eye 12 when the image of the target is arranged in a position to the other side of the scan centre. The eye 12 and the reference point 23 have both moved within the image, but once again the reference point 23 remains in the centre of the pupil 34 of the user's eye 12 indicating that the
20 user is still looking directly at the image of the target.

In the foregoing embodiments the infrared light emitting diodes (IR LEDs) 20a, 20b comprising the illumination source are located in close proximity to the target display 4 so as to produce a single reference point 23 on the user's eye 12. In this way and for
25 the purposes of the embodiment of Figure 1, the target and illumination source are effectively coincident. However, if the infrared light emitting diodes (IR LEDs) 20a, 20b are arranged in spaced relationship to target display 4 then a plurality of reference points 23 are formed by specular reflections from the anterior surface of the user's eye 12. For example, two infrared light emitting diodes (IR LEDs) 20a, 20b arranged in a
30 spaced relationship would produce a pair of reflections; three light emitting diodes (IR LEDs) 20a, 20b arranged in a spaced relationship would produce a triad of reflections etc. The principle of operation of the eye tracking apparatus is the same as if a single reference point 23 is used, however in the case of a plurality of reflections a virtual reference point 23 may be employed which is, for example, equidistant from the actual
35 reflections detectable on the user's eye.

In order to obtain coaxial alignment of the projection path 10 and the illumination path 22, the infrared light emitting diodes (IR LEDs) 20a, 20b and the display 4 are optionally arranged along the common optical axis using a beam splitter comprising
5 one of a partially reflective mirror and a prism.

An alternative eye tracking apparatus is illustrated in Figure 3 wherein like reference numerals identify corresponding or similar elements to those of the first embodiment shown in Figure 1. The eye tracking apparatus of Figure 3 is advantageous in allowing
10 non-circular target motion and obviates a potential loss of image contrast which can occur with a wedge prism 16 due to back reflection of light there from.

In common with the embodiment of Figure 1, the eye tracking apparatus of Figure 3 comprises a target display 4 configured to project an image of a target along a
15 projection path 10 into the field of vision of a user 6, an illumination source comprising infrared light emitting diodes (IR LEDs) 20a, 20b arranged to illuminate the user's eye 12 along an illumination path 22 with electromagnetic radiation having a wavelength in the infrared spectrum, and a sensor 24 comprising a camera 26 having a detector 28 and a lens 30 configured to receive visible and infrared electromagnetic radiation
20 reflected from the user's eye 12 along an imaging path 31.

In the embodiment of Figure 3, a lens 8 receives the visible electromagnetic radiation emitted from the target display 4 and the infrared electromagnetic radiation emitted by the IR LEDs 20a, 20b and projects said electromagnetic radiation into the user's eye
25 via a semi-reflective mirror 14 and a rotatable optical reflector 36, for example a mirror. The reflector 36 has a reflective surface which is arranged at an angle of 4° to a plane normal to the shaft of a mirror rotation mechanism 38. In the case of a plane reflective mirror, the reflector 36 is canted at an angle of 4° off axis to a shaft of the mirror rotation mechanism 38.

30

In the eye tracking apparatus of Figure 3, the sensor 24 is configured to receive visible and infrared electromagnetic radiation reflected from the user's eye 12 along an imaging path 31 via the rotatable reflector 36 and the semi-reflective mirror.

The eye cup 32 is retained in this embodiment to shield the user's eye 12 from extraneous influences, to prohibit ambient light from interfering with the sensor 24 and to reduce unwanted movement between the eye tracking apparatus 2 and the user 6.

- 5 In use, the rotatable reflector 36 is rotated on the shaft of the mirror rotation mechanism 38, at approximately 0.4 Hz. The projection path 10 is incident on the rotatable reflector 36, thereby scanning the image of the target through an 8° radius circle in the user's field of vision.
- 10 The user's eye 12 tracks the distant target image as it moves through the 8° radius circle. The camera 26 is arranged to image the user's eye 12 along the same imaging path 31 as the target image is scanned in the user's field of vision. Since the imaging path 31 is also arranged along the common optical axis said imaging path is reflected from the rotatable reflector 36 and moves in synchronisation with the projected target
- 15 image and the infrared illumination due to the rotation of the reflector 36.

In common with the embodiment of Figure 1, the target display 4, the illumination source 20a, 20b and the sensor 24 are arranged such that the projection path 10, the illumination path 22 and the imaging path 31 are all substantially coaxial on arrival at

20 the moveable element, here reflector 36. Arranging the projection path 10, the illumination path 22 and the imaging path 31 along a common optical axis in this way ensures that, in use, the sensor 24 views the user's eye 12 along the target direction.

If the user's eye 12 tracks the target image perfectly then the user's eye 12 is directed

25 along the imaging path 31 and the reference point 23 is centred on the user's eye throughout the 8° circular scan.

As before, a direct determination of eye direction relative to the target and hence eye-target error is obtained by measuring a distance between reference point 23 on the

30 user's eye and a physical feature of the user's eye 12, for example the centre or circumference of the pupil or iris of the user's eye 12.

Hence, an angular difference between the eye direction and the target direction is obtainable from the measured distance between the reference point 23 on the user's

35 eye and the physical feature of the user's eye 12. Said angular difference is a

quantitative assessment of how accurately the user's eye followed the image of the target as it was scanned through the user's field of vision.

5 The difference between the eye direction and target direction provides an eye tracking error assessment which may be subsequently used to assess the user's cognitive abilities, neurological deficiencies or cognitive impairment due to illness and / or brain injury.

10 The output from the eye tracking apparatus 2 is output directly as a measure of the distance between the reference point and the feature of the eye or optionally as a measure of eye direction relative to the target. The output may be displayed directly or post processed as part of a medical apparatus.

15 In particular, a medical apparatus 40 incorporating an eye tracking apparatus 2 according to the present invention is illustrated in Figure 4. The medical apparatus 40 incorporates a processor adapted to interpret the eye measurements and to assess the cognitive state of the user. Results of the assessment are displayed on display 44 comprising a sophisticated display such as a video display or a rudimentary display such as a light emitting diode to indicate binary states (e.g. normal or impaired
20 cognition).

In the foregoing embodiments the eye tracking apparatus is described as having a separate display 4 and illumination source comprising infrared light emitting diodes (IR LEDs) 20a, 20b arranged to illuminate the user's eye. However, in an alternative
25 embodiment, the display 4 is arranged to project an image of the target and to illuminate the user's eye 12 using electromagnetic radiation in the visible waveband. In this embodiment, the IR LEDs 20a, 20b may be eliminated. Care must be taken in this embodiment not to dazzle the user 6 by using high intensity levels of illumination.

30 The eye tracking apparatus is arranged to measure the distance between the reference point and the feature of the eye at a plurality of locations forming a locus of the target image scan. Although the foregoing embodiments describe a step of scanning the image through a series of points forming a circle, other loci can be used. For example, the target image can be scanned along a scan in the user's field of vision in at least one
35 of a line, an arc, a circle, and an ellipse.

In these cases, a refractive or a reflective optical element is moved by at least one of a micro-electromechanical actuator, a motor, a piezo-micro-positioner, a galvanometer or any other suitable motive means to scan the projection axis, the illumination axis and
5 the imaging axis within the user's field of vision.

As well as measuring smooth-pursuit eye tracking, the present eye tracking apparatus is configurable to move the target image in a discontinuous scan in order to assess a wider range of cognitive functions.

10

In another embodiment, the eye tracking apparatus comprises a modulator adapted to temporally vary at least one of the brightness and the hue of the image of the image of the target.

15 In view of the foregoing description it will be evident to a person skilled in the art that various modifications may be made within the scope of the invention.

Each feature disclosed in the description, and (where appropriate) the claims and drawings may be provided independently or in any appropriate combination.

20

In particular, with reference to the appended claims, features from dependent claims may be combined with those of the independent claims and features from respective independent claims may be combined in any appropriate manner and not merely in the specific combinations enumerated in the claims.

CLAIMS

. 17 -

- 1) An eye tracking apparatus comprising:

a target display adapted to project a moveable image of a target into a user's field of vision;

an illumination source adapted to project a reference point onto a user's eye;

a sensor adapted to monitor a user's eye; and

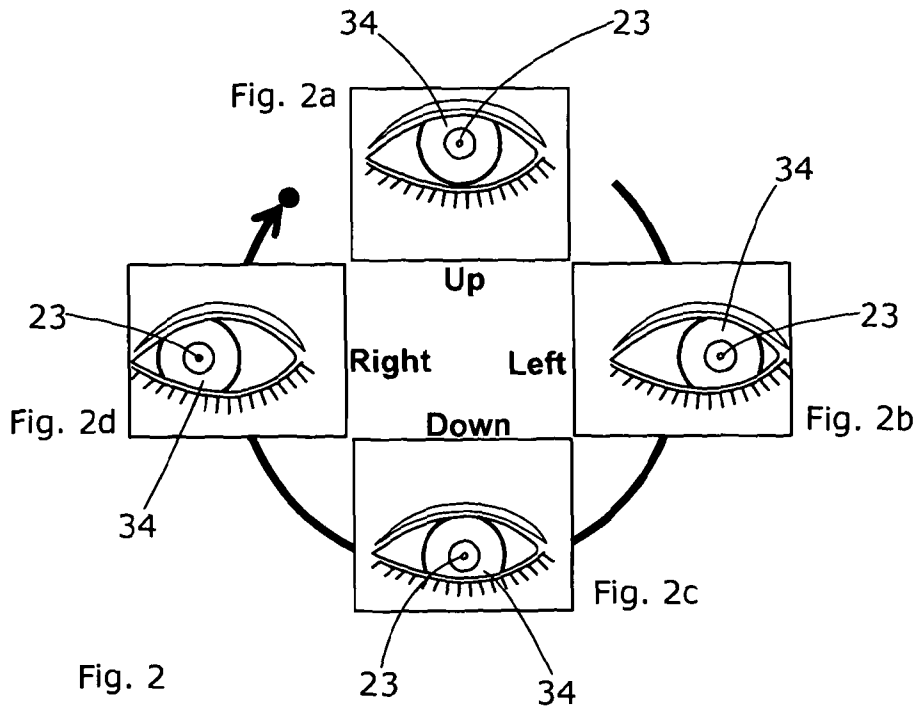
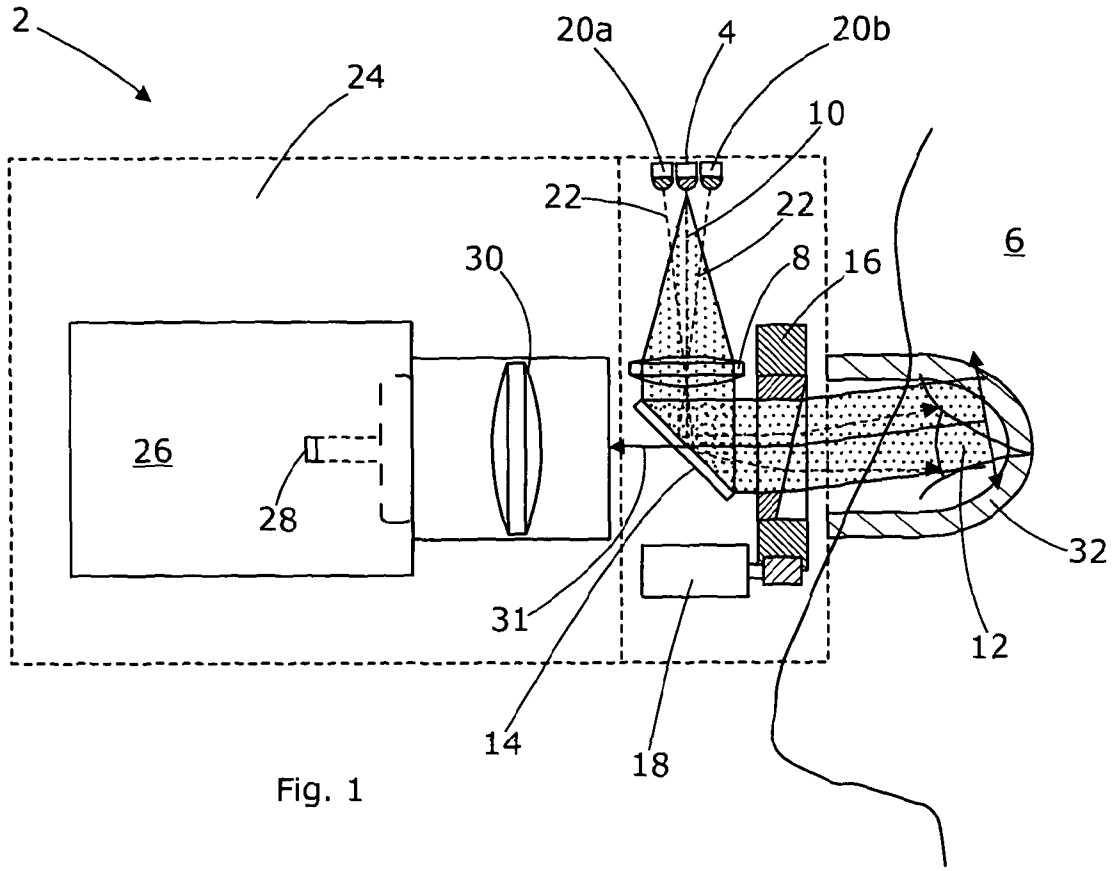
a processor adapted to determine the position of a feature of a user's eye relative to the reference point;

wherein the apparatus is arranged such that said determined position provides a direct indication of eye direction relative to the target direction.

- 2) An eye tracking apparatus according to claim 1, the target display being adapted to project the moveable image along a projection path, the illumination source being adapted to project a reference point along an illumination path, the sensor being adapted to monitor the user's eye along an imaging path, and wherein at least a portion of the projection path, the illumination path and the imaging path are arranged to be substantially coaxial.
- 3) An eye tracking apparatus according to claim 2 adapted to scan the illumination path, the projection path and the imaging path in synchronisation within the user's field of vision.
- 4) An eye tracking apparatus according to any of the preceding claims wherein the processor is adapted to determine a distance between the position of the reference point and a physical feature of the user's eye.
- 5) An eye tracking apparatus according to claim 4 wherein the processor is adapted to convert the determined distance into a measurement of an angle between the target direction and the user's eye direction.
- 6) An eye tracking apparatus according to any of the preceding claims wherein the feature of the user's eye comprises at least one of the user's pupil and the user's iris.

- 7) An eye tracking apparatus according to any of the preceding claims adapted to scan the image of the target in the user's field of vision with a substantially constant angular velocity.
- 8) An eye tracking apparatus according to any one of claims 1 to 6 adapted to scan the image of the target in the user's field of vision with a varying angular velocity.
- 9) An eye tracking apparatus according to any of the preceding claims adapted to scan the image of the target in the user's field of vision along a controlled path that includes at least one of a point, a line, an arc, a circle, and an ellipse.
- 10) An eye tracking apparatus according to any of the preceding claims comprising a modulator adapted to temporally vary at least one of the brightness, the hue, the shape and the form of the image of the target.
- 11) A method of eye monitoring, in which a moveable image of a target is projected into a user's field of vision, and an image of the user's eye is formed on an image sensor, said method comprising:
 - projecting a reference point onto the user's eye;
 - arranging for the selected reference point to provide, in the image, an indication of the position of the target on the user's eye;
 - analysing the image to determine the position of a feature of the user's eye with respect to the reference point.
- 12) A method of eye monitoring according to claim 11 comprising projecting the moveable target and the reference point along a common projection path and monitoring the user's eye along an imaging path, wherein at least a portion of said imaging path is substantially coaxial with said common projection path.
- 13) A method of eye monitoring according to claim 11 or 12 comprising the step of scanning the common projection path and the imaging path in synchronisation within the user's field of vision.
- 14) A method of eye monitoring according to any one of claims 11 to 13 comprising the step of analysing the image to determine a distance between the feature of the user's eye and the position of the reference point.

- 15) A method of eye monitoring according to claim 14 comprising the further step of converting the determined distance into a measurement of an angle between the target direction and the user's eye direction.
- 16) A method of eye monitoring according to any one of claims 11 to 15 wherein the feature of the user's eye comprises at least one of the user's pupil and the user's iris.
- 17) A method of eye monitoring according to any one of claims 11 to 16 comprising the step of scanning the image of the target in the user's field of vision with a substantially constant angular velocity.
- 18) A method of eye monitoring according to any one of claims 11 to 16 comprising the step of scanning the image of the target in the user's field of vision with a varying angular velocity.
- 19) A method of eye tracking according to any one of claims 11 to 18 comprising scanning the image of the target in the user's field of vision along a controlled path that includes at least one of a point, a line, an arc, a circle, and an ellipse.
- 20) A method of eye tracking according to any one of claims 11 to 19 comprising the step of temporally varying at least one of the brightness, the hue, the shape and the form of the image of the target.



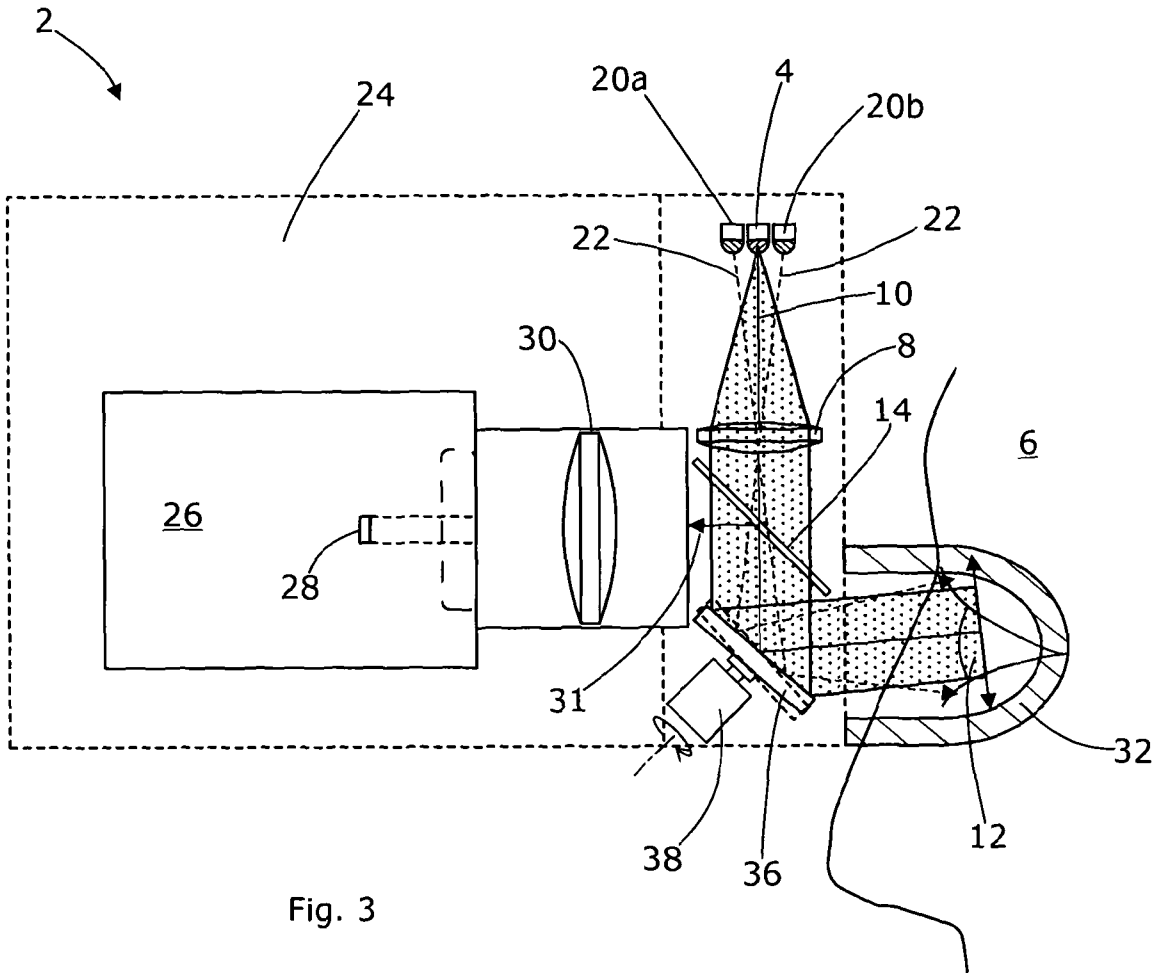


Fig. 3

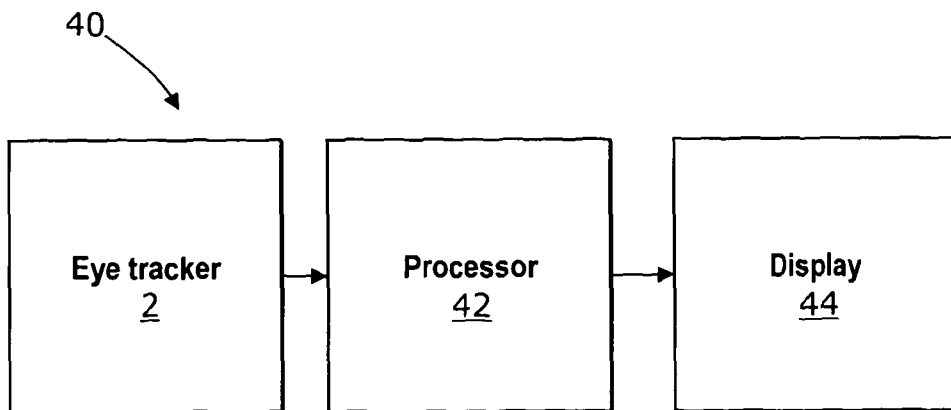


Fig. 4

INTERNATIONAL SEARCH REPORT

International application No PCT/GB2010/002165

A. CLASSIFICATION OF SUBJECT MATTER
 INV. A61B3/113 G06F3/01
 ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED
 Minimum documentation searched (classification system followed by classification symbols)
 A61B G06F

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)
 EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 7 401 920 B1 (KRANZ YARON [IL] ET AL) 22 July 2008 (2008-07-22) * abstract column 5, line 16 - line 22 column 5, line 35 - line 66 column 6, line 38 - column 7, line 41 column 8, line 29 - line 59 column 11, line 62 - column 13, line 6 figures 1,4 ----- -/--	1,4-11, 15-20

Further documents are listed in the continuation of Box C. See patent family annex.

* Special categories of cited documents :

"A" document defining the general state of the art which is not considered to be of particular relevance	"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
"E" earlier document but published on or after the international filing date	"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)	"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.
"O" document referring to an oral disclosure, use, exhibition or other means	"&" document member of the same patent family
"P" document published prior to the international filing date but later than the priority date claimed	

Date of the actual completion of the international search 3 March 2011	Date of mailing of the international search report 15/03/2011
---	--

Name and mailing address of the ISA/ European Patent Office, P.B. 5818 Patentlaan 2 NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Fax: (+31-70) 340-3016	Authorized officer Tommaseo, Giovanni
--	--

INTERNATIONAL SEARCH REPORT

International application No

PCT/GB2010/002165

C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 4 836 670 A (HUTCHINSON THOMAS E [US]) 6 June 1989 (1989-06-06) * abstract column 3, line 61 - line 63 column 4, line 66 - column 5, line 34 column 16, line 25 - line 30 column 20, line 38 - line 66 column 22, line 8 - line 29 figures 10A,10B,11 -----	1,2,12, 14
X	US 2006/110008 A1 (VERTEGAAL ROEL [CA] ET AL) 25 May 2006 (2006-05-25) * abstract paragraph [0011] - paragraph [0015] paragraph [0032] paragraph [0058] - paragraph [0078] claim 1 figures 1-4 -----	1,3,11, 13
X	US 2006/093998 A1 (VERTEGAAL ROEL [CA]) 4 May 2006 (2006-05-04) * abstract paragraph [0007] - paragraph [0012] paragraph [0072] - paragraph [0075] -----	1,11
X	US 7 522 344 B1 (CURATU COSTIN E [US] ET AL) 21 April 2009 (2009-04-21) * abstract column 2, line 47 - column 3, line 38 column 4, line 47 - column 5, line 57 -----	1
A	US 6 433 760 B1 (VAISSIE LAURENT [US] ET AL) 13 August 2002 (2002-08-13) * abstract column 4, line 26 - column 6, line 29 -----	1-20
A	US 2006/256083 A1 (ROSENBERG LOUIS B [US]) 16 November 2006 (2006-11-16) * abstract paragraph [0024] - paragraph [0029] -----	1-20
A	EP 0 733 338 A1 (COMMISSARIAT ENERGIE ATOMIQUE [FR]) 25 September 1996 (1996-09-25) * abstract claims 1-8 -----	1-20
A	WO 03/017203 A1 (QINETIQ LTD [GB]; DURNELL LAURENCE [GB]) 27 February 2003 (2003-02-27) * abstract page 12 - page 16 -----	1-20

-/--

INTERNATIONAL SEARCH REPORT

International application No
PCT/GB2010/002165

C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 2003/123027 A1 (AMIR ARNON [US] ET AL) 3 July 2003 (2003-07-03) cited in the application the whole document -----	1-20

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No PCT/GB2010/002165

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
US 7401920	B1	22-07-2008	NONE

US 4836670	A	06-06-1989	NONE

US 2006110008	A1	25-05-2006	NONE

US 2006093998	A1	04-05-2006	US 2004183749 A1 23-09-2004 US 2011043617 A1 24-02-2011

US 7522344	B1	21-04-2009	NONE

US 6433760	B1	13-08-2002	NONE

US 2006256083	A1	16-11-2006	NONE

EP 0733338	A1	25-09-1996	FR 2731896 A1 27-09-1996 JP 8278134 A 22-10-1996 US 5668622 A 16-09-1997

WO 03017203	A1	27-02-2003	CA 2457090 A1 27-02-2003 EP 1417645 A1 12-05-2004 JP 4181037 B2 12-11-2008 JP 2005500630 T 06-01-2005 US 2004196433 A1 07-10-2004

US 2003123027	A1	03-07-2003	NONE
