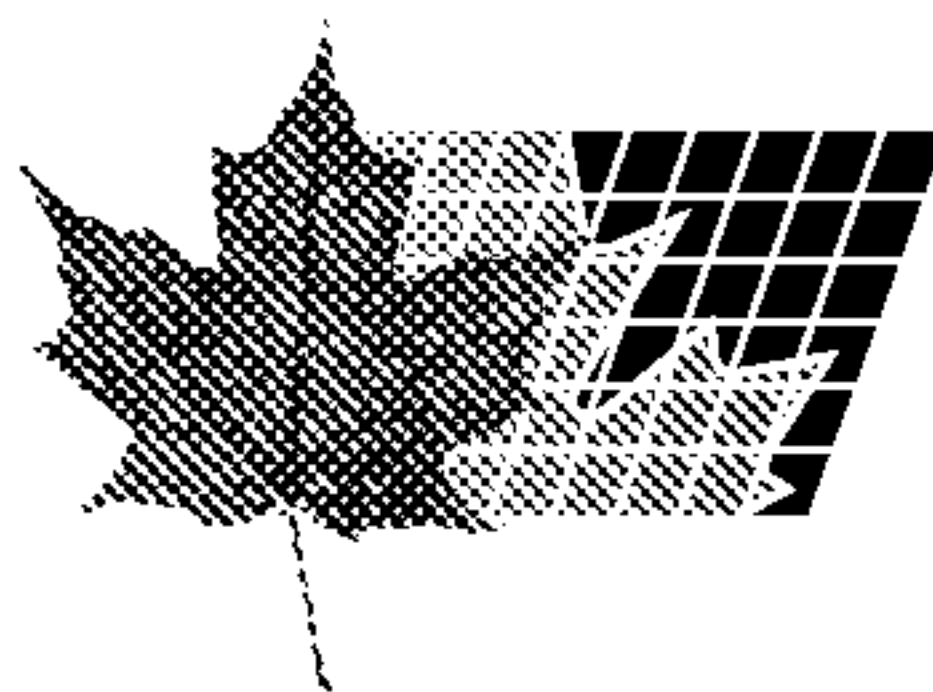




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(54) **DISPOSITIF DE COMMANDE ET DE REGULATION**

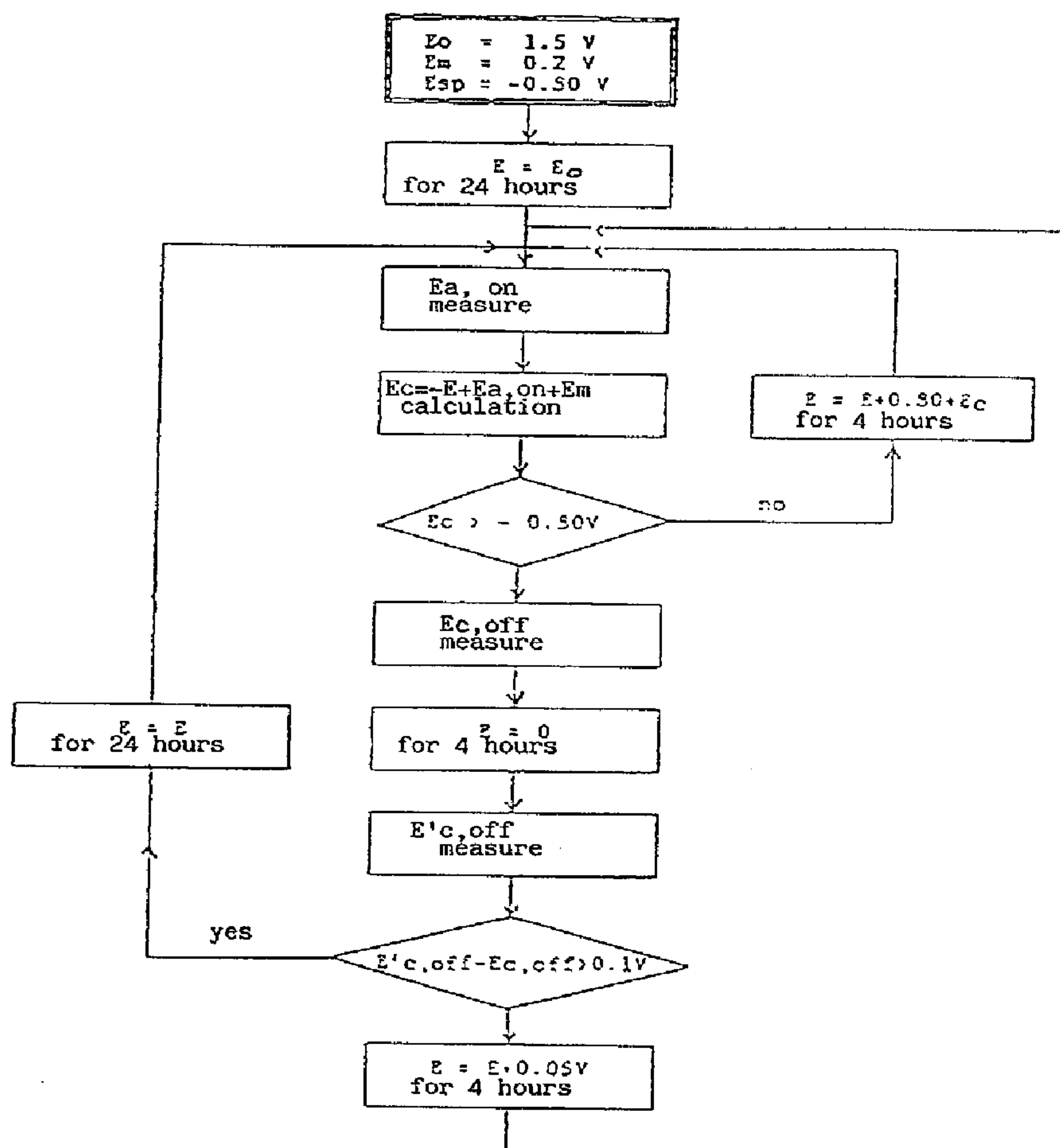
AUTOMATIQUE POUR SYSTEMES DE PROTECTION

CATHODIQUE DANS DES OUVRAGES EN BETON ARME

(54) **CONTROL AND AUTOMATIC REGULATION DEVICE FOR**

CATHODIC PROTECTION SYSTEMS IN REINFORCED

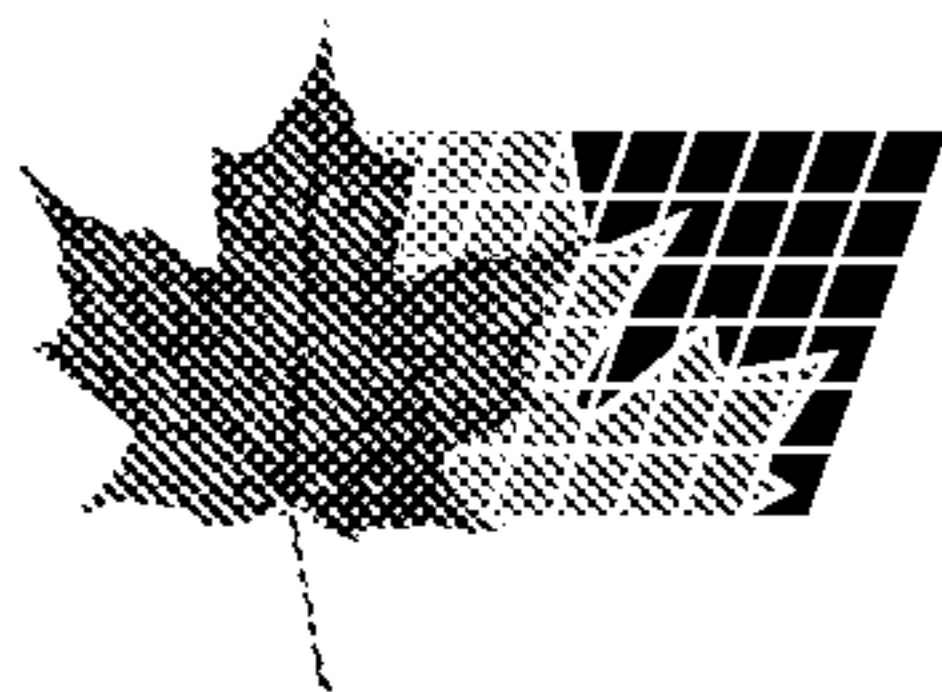
CONCRETE STRUCTURES



$E_{c, off}$ = E_c open circuit

$E'c, off$ = E_c open circuit after 4 hours





(11) (21) (C) **2,036,863**
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(57) Device for the control and regulation of the feeding unit (60), as well as for monitoring of impressed current cathodic protection systems in reinforced concrete in order to avoid any risks of reinforcement (10) over-protection and to prevent hydrogen embrittlement problems, while assuring full protection of reinforcements.

Abstract:CONTROL AND AUTOMATIC REGULATION DEVICE FOR CATHODIC
PROTECTION SYSTEMS IN REINFORCED CONCRETE STRUCTURES

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CONTROL AND AUTOMATIC REGULATION DEVICE FOR CATHODIC
PROTECTION SYSTEMS IN REINFORCED CONCRETE STRUCTURES

FIELD OF THE INVENTION

The present invention finds its application in the field of impressed current cathodic protection of reinforced concrete structures.

5 Cathodic protection of reinforced concrete is used to prevent or to stop corrosion of metallic reinforcements.

The most typical application field is in bridges, slabs, beams, piers, multi-store parkings, garages,
10 etc, - situated in cold regions, where corrosion is caused by de-icing salts, as well as in structures exposed to marine environment.

This kind of systems is realized either using an anode structure typically having a net arrangement
15 (i.e. titanium activated by noble metal oxides) or applying conductive coatings.

The main characteristic of any cathodic protection system in reinforced concrete structures is to guarantee that the protection conditions be extended to
20 the whole surface of reinforcements, without reaching over-protection conditions.

The former condition obviously applies to any kind of structures; the latter, though being important in the protection of standard reinforced concrete
25 structures, becomes mandatory where pre-stressed or post-tensioned concrete elements are present and have to be protected. In fact, steels used for this type of structures exhibit very high mechanical characteristics,

generally not lower than 1400 MPa, making them extremely exposed to the risk of hydrogen embrittlement phenomena.

5 This means that, in a cathodic protection system applied to a pre-stressed or post-tensioned reinforced concrete structure, if the potential of these steels gets below the threshold value, in correspondence of which the hydrogen evolution reaction becomes appreciable, hydrogen embrittlement may occur.

10 For the steels generally used in these structures, this threshold value ranges around -0.9 V with respect to Ag/AgCl electrode (W.H.Hartt, P.K.Narayanan, T.Y.Chen, C.C.Kumira, "Cathodic Protection and Environmental Cracking of Prestressing Steel",
15 CORROSION/89, paper n. 382, NACE, New Orleans, Aprile 1989; R.N.Parkins et al., "Environmental Sensitive Cracking of Prestressing Steels", Corrosion Science 22, p. 379, 1982).

20 When using carbon or low alloy steels showing ordinary mechanical characteristics, no embrittlement is observed. A threshold value is however set around -1.1 V (The Concrete Society Tech. Report N, 36 "Cathodic Protection of Reinforced Concrete", London 1988). In fact, beyond this potential value, it is not
25 advisable to operate, not only due to economic reasons, but also to avoid possible occurrence of reduced bond between concrete and reinforcement.

Traditional monitoring technique for cathodic protection is based on the following check operations:

30 1. protection conditions are reached (i.e. by means of the so-called 100 mV decay method, that consists in

checking that the cathodic potential variation, in the first four hours after opening the circuit, exceeds 100 mV) and,

2. potential of reinforcements is always nobler than the above mentioned critical value so as to exclude any over-protection risks.

That criteria are not suitable for pre-stressed concrete and, in any case, also for ordinary concrete, cannot avoid over-protection condition in some points (for instance, where rebars are very close to the anode, in correspondence of zone of concrete where the resistivity becomes unexpectedly very low due to chloride contamination). In fact, the detection of possible over-protection conditions is strongly dependent on the location of reference electrodes (portable or fixed); it follows that only monitored zones (i.e. presence of reference electrode) are controlled, that means a few percent of the protected area, and are not representative of the map of the potentials on the whole surface of reinforcements. In effect, the potential of the surface of reinforcements is not uniform, but varies from one to another point, depending on the position with respect to the anode surface and to surrounding reinforcements. The amount of the variations changes with operating and environmental conditions. For instance, during winter or in high atmospheric humidity conditions, for which the oxygen diffusion within concrete results difficult, such local variations may be very high.

DESCRIPTION OF THE INVENTION

In accordance with one aspect of the present invention there is provided a device for control and automatic regulation of the feeding unit of impressed

3a

current cathodic protection systems in a metallic structure reinforced concrete structure, including a metallic reinforcement behaving as cathode to which an anode structure is associated, characterized in that
5 said device is able to measure the feed voltage and the anode potential by means of at least one reference electrode, in order to perform automatic regulation of the feeder so as to keep the cathodic potential to such values that guarantee the protection of the metallic
10 structure, without any over-protection risks.

In accordance with another aspect of the present invention there is provided an impressed current protection system, comprising a feeding unit, able to generate a potential difference between the cathodic
15 reinforcement and an anode structure of a reinforced concrete structure, said system being characterized by a device for the control and regulation of the feeding unit, as claimed in any of the claims from 1 to 9, in order to assure adequate protection of the cathodic
20 structure, without any over-protection risks.

In accordance with yet another aspect of the present invention there is provided a procedure for the control and automatic regulation of feeding of impressed current cathodic protection systems in
25 reinforced concrete structures, comprising an indirect measurement of the cathodic voltage, based on which necessary adjustments can be made on the feeding in order to assure adequate protection of the metallic structure, while preventing any over-protection risks.

30 The present invention consists in a device able to

check that protection conditions are reached (i.e. using the well-known 100 mV decay method) and to ensure that no over-protection conditions are achieved.

5 The innovative idea has its base on the measurement of the potential of the anode, instead of the measurement of the potential of the protected structure (i.e. reinforcements) as it has been done up to now for the concrete cathodic protection applications.

10 Moreover the present invention is based on some peculiar features regarding voltages involved in cathodic protection systems for concrete.

The feeding voltage, E , can be considered as the sum of: anode voltage, E_a , cathodic voltage E_c , ohmic drops in metallic conductors, E_m , and ohmic drops in concrete, E_{ohm} :

$$E = E_a - E_c + E_{ohm} + E_m \quad (1)$$

20 As far as E_c is concerned, it should be ranged within an interval limited, on its lower side, by the above mentioned minimum value, that is in case of high strength steels, for pre-stressed or post-stressed reinforced concrete -0.90 V, whereas for standard steels used in reinforced concrete -1.1 V (all potential values are referred to Ag/AgCl electrode).

25 As far as E_a is concerned, it slowly rises in time, at least in the first years operation. In case of activated titanium, it passes, from an initial value of about 0.4 V to $0.7-0.9$ V, or higher, a few years after (P. Pedferri et al. "Cathodic protection of Steel in Concrete with Expanded Titanium Anode Net System", UK
30 Corrosion Conference, Blackpool, England, 8-10

November). It can also vary with environmental conditions, particularly with temperature and therefore with seasons. However, unlike cathodic potential, E_a is generally uniform on all the anode surface. This
5 uniformity depends on the use of the special distributors that reduce attenuation as well as on the particular electrocatalytic characteristics of the materials used.

The ohmic drop E_{ohm} has very low values, because
10 of the low currents involved, except for in particularly dry concrete. It is mainly localized in close proximity of the anode, where current density is greater. The term of any ohmic drop different from the ohmic drop in proximity of the anode can therefore be
15 disregarded (and this makes the whole system more conservative). The ohmic contribution localized on the anode is determined along with the anode potential by means of reference electrode placed between anode and cathode (i.e. the same electrode used to check that
20 protection conditions are reached by means of 100 mV decay method can be utilized). Actually, the meaning of anode potential here considered, E_a , on results to be equal to $E_a \text{ true} + E_{ohm}$ (see equation 1).

The term E_m ohmic drop in metallic conductors,
25 includes ohmic drops in the anodic feeding cables (ohmic drops in the rebars are negligible) and ohmic drops in anodic structures, i.e. the net and the relevant distribution strips. It depends on the flowing current.

30 Therefore equation (1) can be rewritten as follows:

$$E = E_{a,on} - E_c + E_m \quad (2)$$

The present invention consists in a device for the control and regulation of the feeding unit in cathodic protection systems for reinforced concrete, that is based on the measurement of the feed voltage and of the anode potential instead of the cathodic potential, as it happens in traditional cathodic protection systems.

This device is able to guarantee safe protection conditions of reinforcements, as far as overprotection is concerned.

This device, in its preferred embodiment, consists of a control unit where the following parameters are set: minimum protection potential (-0.90 or -1.1 V); initial voltage or current, E_o or I_o ; this control unit periodically determines: feed voltage, E , and anode potential $E_{a,on}$; the current involved and the ohmic drop contribution in metallic conductors, E_m ; moreover, it performs routine protection tests based, for instance, on 100 mV decay method.

The control unit can be applied to systems operating both at "imposed voltage" (called "constant voltage") and at "imposed current" (called "constant current").

If system operates at "constant voltage", the control unit imposes the pre-established initial voltage, checks, based on one or more measurements of the cathodic potential and following traditional principle, that protection conditions of reinforcements be reached (i.e. using the well-known 100 mV decay criteria) and, if such conditions would not be reached, it adjusts the feed voltage in order to meet this

requirement; then, it measures the anode potential, $E_{a,on}$, then it calculates the cathodic potential E_c in order to check that no overprotection conditions are achieved.

5 In case of pre-stressed concrete structures, it checks that the following inequality is verified:

$$E_c = -E + E_{a,on} + E_m > -0.90 \text{ V} \quad (3)$$

In case of standard reinforced concrete structures:

10 $E_c = -E + E_{a,on} + E_m > -1.1 \text{ V} \quad (4)$

The measurement of the anode potential E_a is therefore periodically performed, for example a few times every day, always re-calculating the operating voltage of the feeder.

15 A more accurate control can be realized if the anodic potential is taken as close as possible to the electrical connection of the power cables to the anodic structure, by means of an auxiliary, current free, electrical cable. In this case, in fact, the
20 contribution of the ohmic drop in the cables is eliminated.

In case of feeding "at constant current", the control unit imposes a pre-established initial current and checks that protection conditions be reached
25 without the occurrence of overprotection conditions. This latter control is carried out by means of a measurement of the feed voltage and the anode potential and of the calculation of the cathodic potential as per equation (2), that should be greater than the above-
30 cited threshold values. If this threshold value results to exceed the cathodic potential, the control unit

reduces the feed current so as to exclude overprotection conditions.

5 In a simplified version of the device, the feeding unit imposes a constant voltage, E , calculated as the sum of the measured anode potential $E_{a,on}$ of the cathodic potential E_c and of the ohmic contributions, E_m , where E_c and E_m contributions are pre-determined; the control and automatic regulation are performed by periodically measuring the potential of the anode
10 structure $E_{a,on}$, and then re-calculating the new feed voltage, so as to keep the structure constantly under protection conditions, avoiding any overprotection risks.

The anode potential $E_{a,on}$ can be measured using
15 several reference electrodes which are representative of zones with different concrete conductivity, when using such several electrodes, the control device should be able to properly process signals so as to obtain one value (i.e. the lowest value) to be entered
20 in the sum for E calculation.

As above discussed, the principle of the system relies mainly on the higher uniformity of the potential of the anodic structure, compared with the cathode.

On this regard, possible reasons for a non uniform
25 potential of the anode are:

- a. - ohmic drops (or attenuation) in the metallic conductors (anode net included)
- b. - non uniform current requirements on the structures

As far as the first point is concerned, the right
30 answer comes from a correct design of the anodic structure in terms of maximum allowed attenuation: for

instance net and distributors can be designed in order to keep the ohmic drops below 100 mV. Furthermore, reference electrode for reading of $E_{a,on}$ can be located close to the connection between power cable and anodic structure, where potential losses due to ohmic drops are expected to be minimal (and current density to be higher).

With reference to the second aspect, that is non-uniform current distribution all over the structure, it is often difficult to predict areas of higher current density. However relevant mistakes are limited because of the specific electrochemical behaviour of the anodic material has considered. In fact, as it results from readings taken on a real structure under protection, when the current density increases from 10 to 20 ma/m^2 (concrete surface), the anodic potential goes from +0.47 V vs Ag/AgCl to +530, which means a potential disuniformity lower than 60 mV.

As a protection against possible failures that might take place in the circuits or in reference electrodes, the device is provided with a safety system which, when the feed voltage should reach a given E_{max} value, automatically brings the voltage back to a lower value E_{min} (i.e. 1.5 V), pre-established as well, simultaneously activating an alarm signal. In this way, the cathodic protection system could operate in under protection conditions, but it would never find in the much more dangerous over-protection conditions.

Furthermore, in case the control device couldn't regulate the power unit, another protection can be foreseen which automatically switch off the transformer

rectifier.

The device is realized as an "intelligent" system, such as for instance a microprocessor or a personal computer, equipped with an adequate number of analogical inputs and outputs, able to run a program for the management of the system and of variables: input data acquisition, measurement of the anode potential, calculation of the feed voltage etc: The system is then connected to the feeding unit, to which it transmits the order for the adjustment of the voltage or feeding current, and if necessary, to a data acquisition unit for storing all systems current data or to a data transmission unit.

Example 1

A system for cathodic protection of a pre-stressed concrete bridge deck consists of several units, each one with its own transformer-rectifier feeding a mixed metal oxide activated titanium net, having a rectangular surface of 360 m^2 .

Connections between power cables and anodic structure are located at one side of the net.

A reference electrode has been placed in correspondance of the power connection side, positioned close to the titanium net. A second reference electrode of the same type has been placed at the opposite side, close to the rebar.

The anodic structure has been designed to have a maximum ohmic drop in metallic conductors lower than 100 mV at the maximum design current density, equal to 20 mA/m^2 referred to the concrete surface.

Free corrosion potential of rebar, measured by

means of fixed reference electrodes as well as by portable ones, ranges between -0.1 and -0.25 V vs Ag/AgCl, while the potential of the anodic structures in same conditions is equal to -0.18 V.

5 Power unit is a "constant voltage" type and it is controlled by an automatic regulation device which operates as follows. The control unit informs the power unit to start with an initial voltage E_0 equal to 1.0 V, calculated by the operator assuming $E_c = -0.5$ V,
10 $E_{a,on} = 0.45$ V and $E_m = 0.05$ V. Current output is equal to 3.2 A, corresponding to a current density of 9 mA/m². The control unit checks that protection conditions are reached, in accordance with the 100 mV decay criteria, and it takes the reading of $E_{a,on}$. Then
15 it verifies that the following inequality is verified:

$$E_c = -E_0 + E_{a,on} + E_m > -0.90 \text{ V}$$

where -0.90 V represents the more negative allowed potential for the cathode, i.e. the rebar.

At start up, with 1.0 V applied, protection
20 conditions are satisfied (about 150 mV of polarization are measured in the off status), and the measured potential of the anode, $E_{a,on}$, is equal to + 0.43 V. From these figures, assuming as stated above 50 mV as maximum allowed contribution for ohmic drops, the
25 calculated value for E_c is equal to -0.52 V, more positive than the minimum allowed.

After almost two years the anodic potential increased to +0.75 V and in the mean time polarization of the rebar falls below 100 mV. In accordance to these
30 data, the control unit automatically increased the applied potential from 1.0 to 1.2 V, step by step,

recalculating the cathode potential, E_c , equal to -0.45 V, and verifying the compliance with above written inequality, which again is verified.

5 If this would not be achieved, the device reduces the applied voltage and repeats control operations.

Fig. 1 reports the flux diagram of the operation carried out by the control unit.

Example 2

Reinforced concrete slab protected using a
10 "constant current" feeding system. No high strength steel is present. The system imposes an initial current density of 10 mA/m^2 (based on experience, the initial current required is ranged between 10 and 20 mA/m^2) and calculates circulating current and ohmic drops in
15 wires. The system adjusts current so that the protection conditions are reached, based in 100 mV decay method; in the negative, it adjusts current until reaching protection conditions.

At the same time, it measures E_0 and E_a , on and
20 verified the inequality

$$E_c = -E_0 + E_{a,on} + E_m > -1.1 \text{ V}$$

If this would not be achieved, it reduces current by 20% and repeats the control.

Fig. 2 reports the diagram of the device.

25 Figs. 3 and 4 illustrate the main elements of a cathodic protection system for reinforced concrete structure, following the present invention.

Fig. 3 is a plan view of a cathodically protected bridge slab, showing the anode net structure; fig. 4 is
30 a sectional view along the line IV-IV of fig. 3.

The slab consists in a metallic reinforcement 10,

behaving as cathode, buried in concrete 20, above which an anode net structure is laid. The anode net 30 is covered by a layer of cement 40, over which the asphalt 50 is then laid.

5 The necessary potential difference between anode and cathode 10 is maintained by means of a feeder 60 able to operate at both constant voltage and constant current.

10 Between anode 30 and cathode 10, at least one reference electrode 70 is installed, connected to a control unit 80, that intervenes on the feeder 60 for necessary adjustments, in order to keep the system in proper protection conditions, avoiding any overprotection risks.

CLAIMS

1. A device for control and automatic regulation of the feeding unit of impressed current cathodic protection systems in a metallic structure reinforced concrete structure, including a metallic reinforcement behaving as cathode to which an anode structure is associated, characterized in that said device is able to measure the feed voltage and the anode potential by means of at least one reference electrode, in order to perform automatic regulation of the feeder so as to keep the cathodic potential to such values that guarantee the protection of the metallic structure, without any over-protection risks.
2. A device as claimed in claim 1, where said feeding unit operates at constant voltage or at constant current.
3. A device as claimed in claim 1 or 2, where the regulation of the feeding unit is performed by calculating the cathodic potential, E_c as the difference among the feed voltage E , the measured anode potential, $E_{a,on}$ and ohmic drops in metallic conductors, E_m , and by periodically checking that the potential E_c is greater than a given threshold value for over-protection potential; in the negative, the device automatically adjusts the feeding unit, by reducing applied voltage or current, repeating said operation until this inequality is verified.
4. A device as claimed in claim 1, where said reference electrode is buried in the reinforced concrete structure and is placed between the cathodic and the anodic structure.

5. A device as claimed in claim 1, where the anode structure is a net structure, buried in reinforced concrete.

6. A device as claimed in any one of claims 1 to 5, where the control device is connected to several reference electrodes and is able to properly process signals, for instance to calculate the mean, root-mean-square deviation, to select a part of measurement, to assess the reliability of measurements.

7. A device as claimed in any one of claims 1 to 6, characterized in that when the feed voltage or current reaches a pre-established threshold value, the control device automatically activates an alarm signal, and brings the voltage or current back to a pre-established minimum value.

8. A device as claimed in any one of claims 1 to 7, comprising a memory unit onto which the device periodically transfers all systems operating parameters.

9. A device as claimed in any one of claims 1 to 8, where the control and regulation device consists of an "intelligent system" such as a microprocessor or a personal computer provided with an adequate number of inputs and outputs, able to run a program of data management and processing, to acquire one or more voltage measurements by means of the reference electrodes connected, and to supply the feeder of the cathodic protection system with operating parameters, duly processed.

10. An impressed current protection system, comprising a feeding unit, able to generate a potential difference between the cathodic reinforcement and an anode

structure of a reinforced concrete structure, said system being characterized by a device for the control and regulation of the feeding unit, as claimed in any of the claims from 1 to 9, in order to assure adequate protection of the cathodic structure, without any over-protection risks.

11. A procedure for the control and automatic regulation of feeding of impressed current cathodic protection systems in reinforced concrete structures, comprising an indirect measurement of the cathodic voltage, based on which necessary adjustments can be made on the feeding in order to assure adequate protection of the metallic structure, while preventing any over-protection risks.

12. A procedure as claimed in claim 11, where said indirect measurement of the cathodic potential is made as the difference among the feed voltage E , the measured anode potential $E_{a,on}$ and ohmic drops in metal conductors E_m , using one or more reference electrodes.

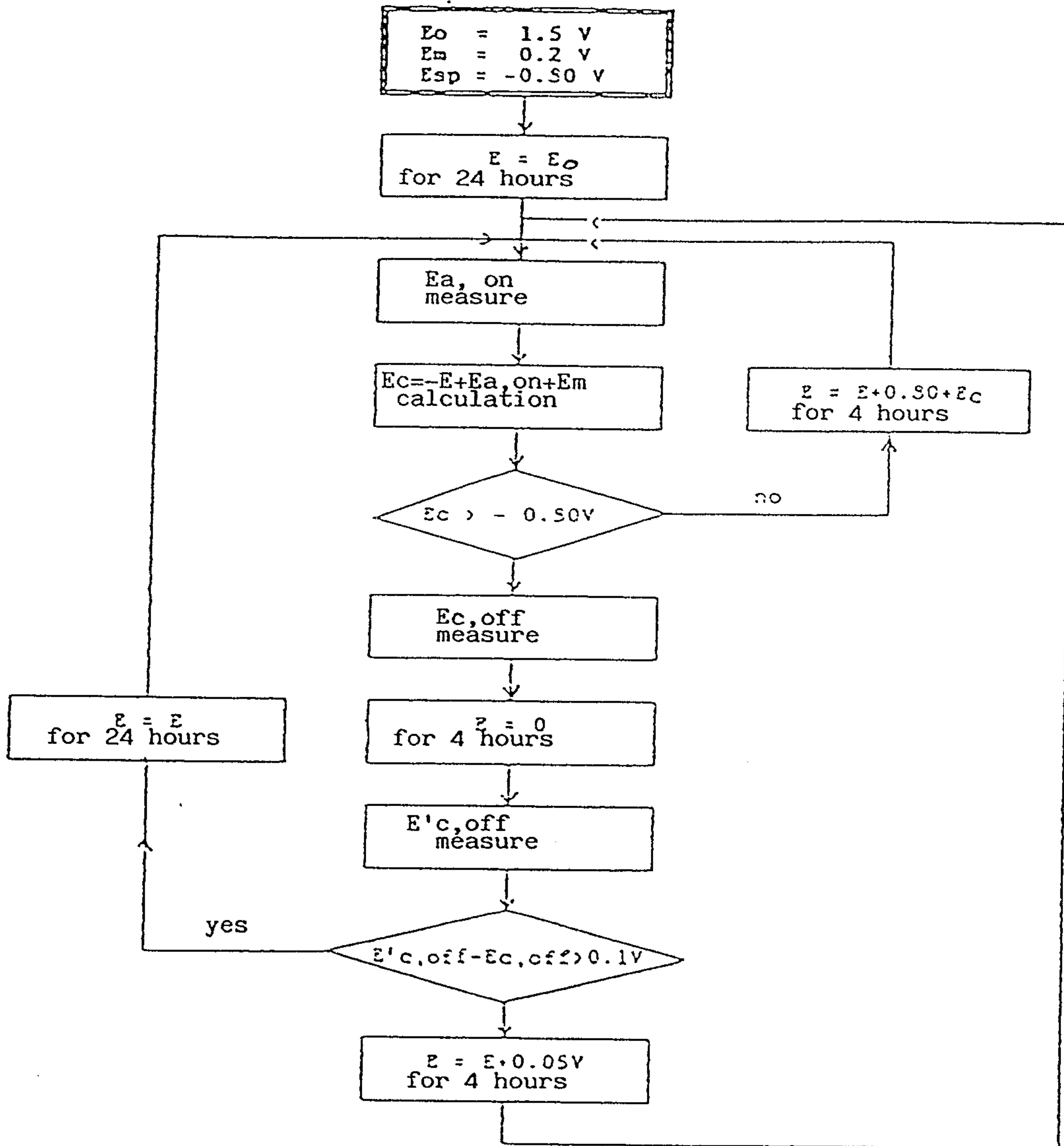


FIG. 1

$E_{c, off}$ = E_c open circuit
 $E'_{c, off}$ = E_c open circuit after 4 hours

Kirby, Eales, Gale
 Baker & Brown

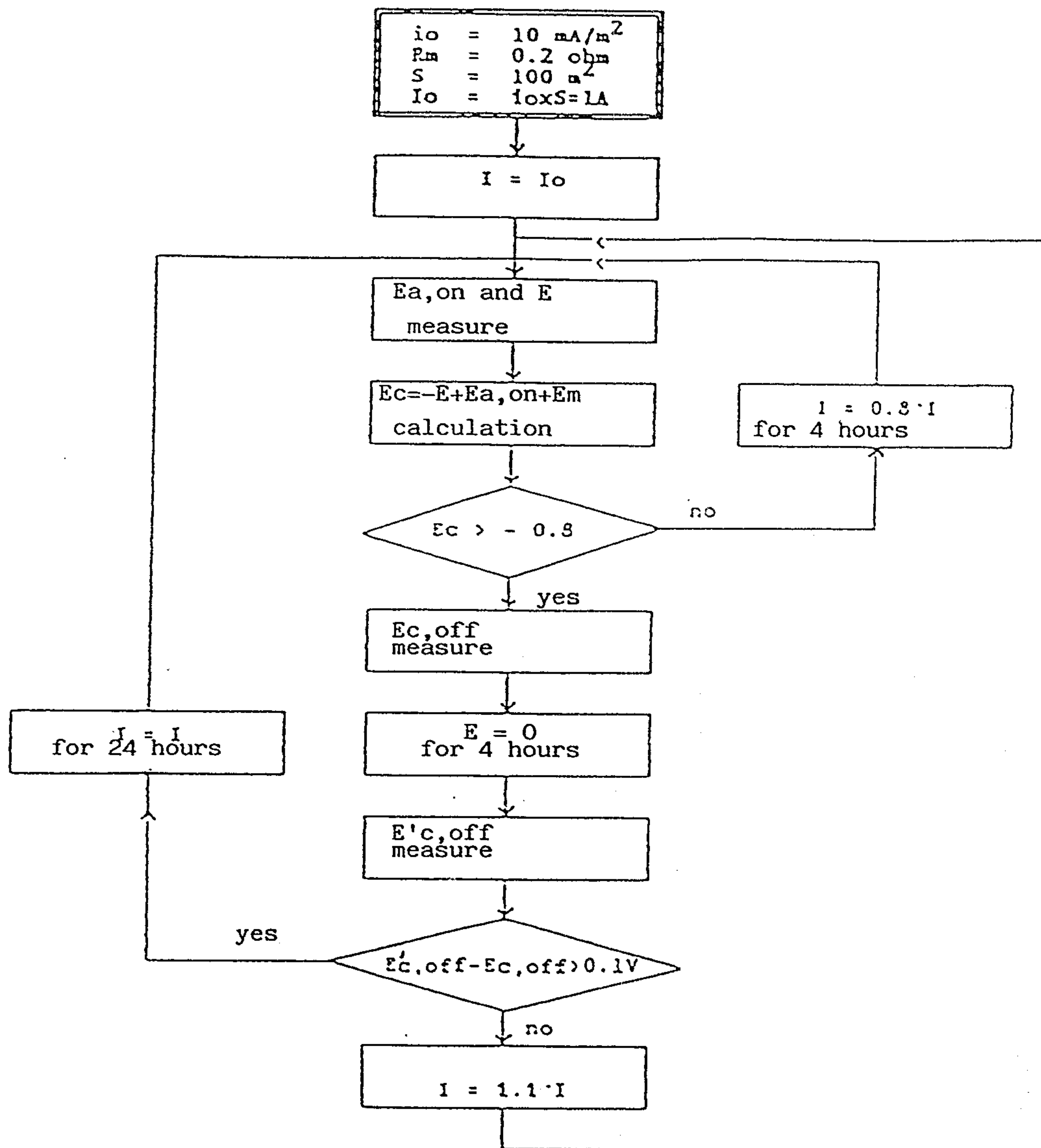


FIG. 2

R_m = wire ohmic drop

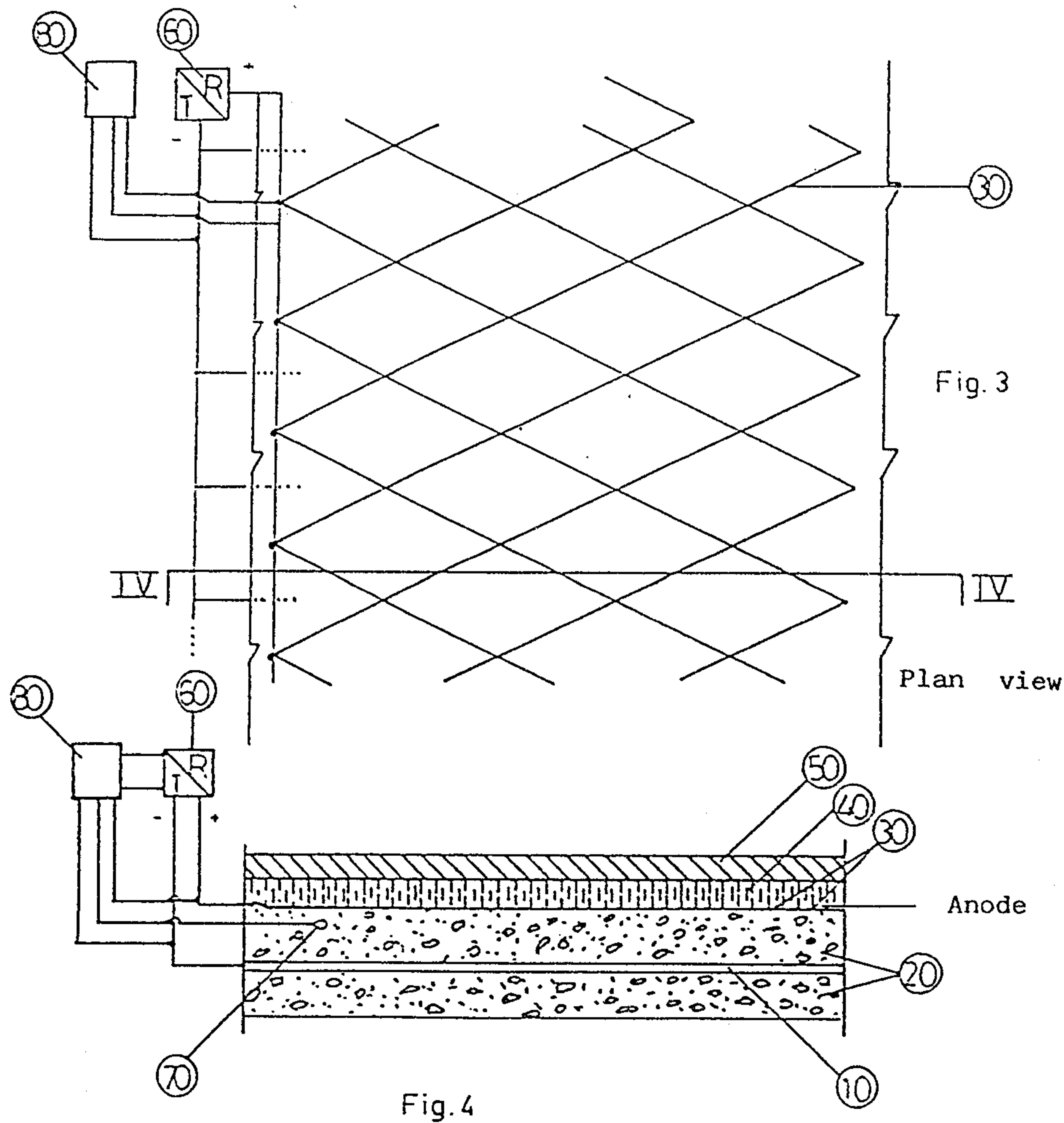
S = concrete surface

I_0 = starting current

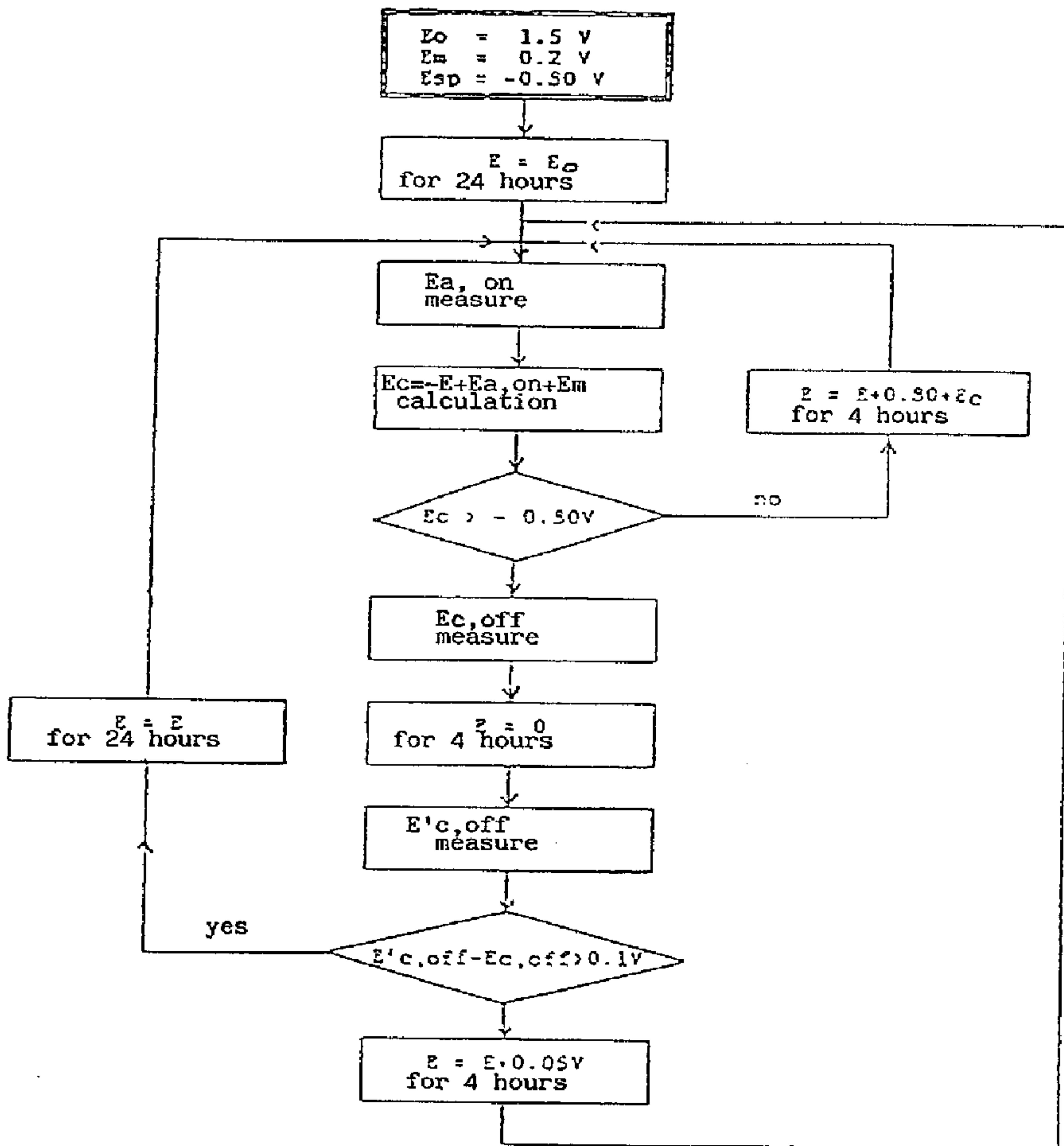
$E_{c,off}$ = E_c open circuit

$E'_{c,off}$ = E_c open circuit after 4 hours

Kirby, Eades, Gale
Baker & Brown



Kirby, Endes, Gale
Baker & Potvin



$E_{c,off}$ = E_c open circuit

$E'_{c,off}$ = E_c open circuit after 4 hours