

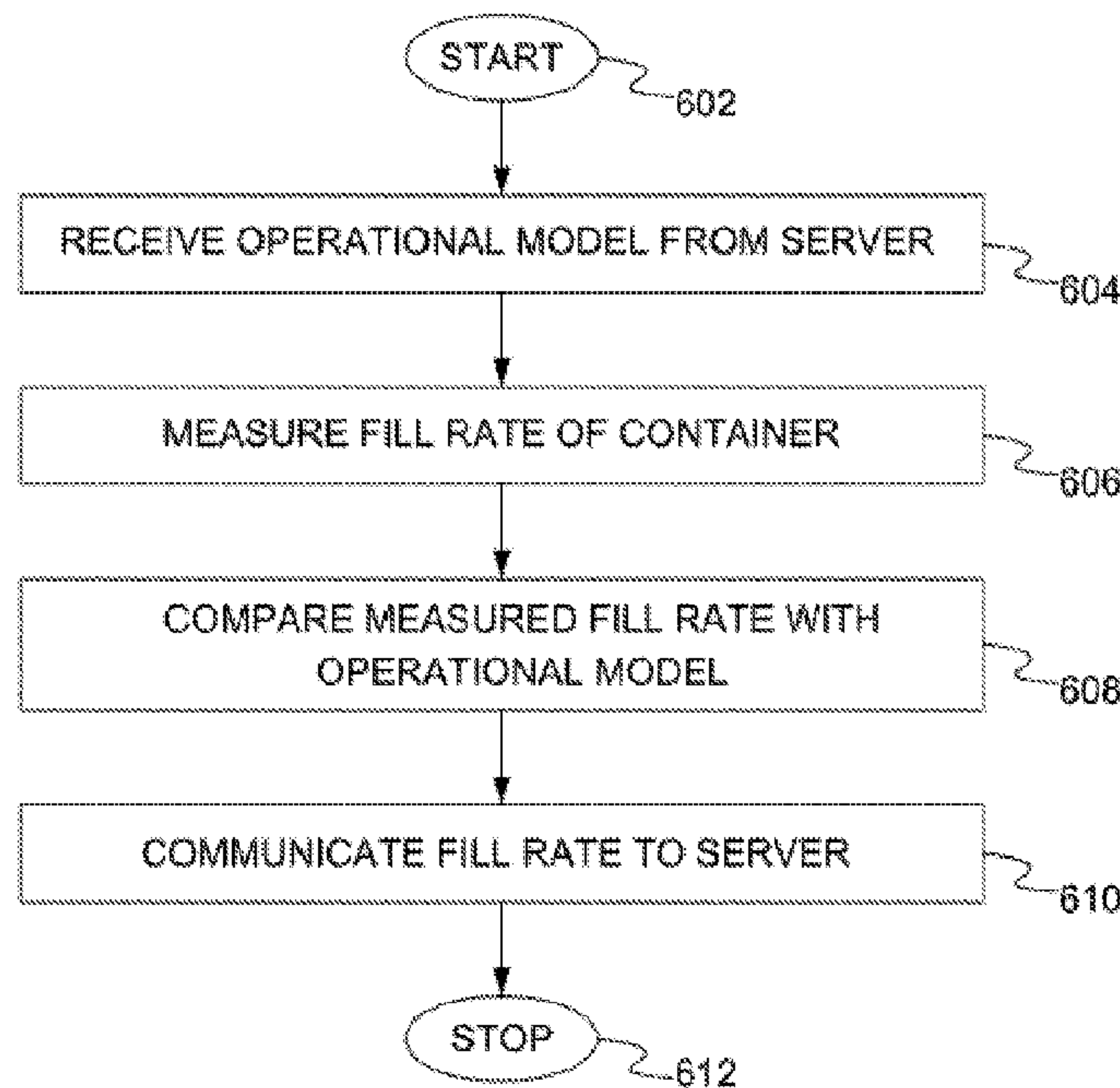


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(54) Title: METHOD AND SYSTEM FOR MONITORING AND COMMUNICATING FILL RATE OF CONTAINER



(57) **Abrégé/Abstract:**

Disclosed is a method for monitoring a fill rate of a container and communicating the monitored fill rate to a server, the container comprising at least a first sensor which is a fill rate sensor in a normally non-active mode. The method comprises receiving an

(57) Abrégé(suite)/Abstract(continued):

operational model from a server, the operational model defining a wake-up signal to determine whether to initiate communication between the fill rate sensor and the server, the operational model also defining a pre-determined fill rate level comprising a predefined maximum value of the fill rate and/or a predefined minimum value of the fill rate, wherein communication between the fill rate sensor and the server only occurs when the pre-determined fill rate level is not met; detecting the wake-up signal; measuring the fill rate of the container with the fill rate sensor; comparing a measured fill rate with the pre-determined fill rate level defined in the operational model; and communicating the measured fill rate to the server only if the measured fill rate is equal to or above the predefined maximum value of the fill rate, and/or the measured fill rate is equal to or below the predefined minimum value of the fill rate.

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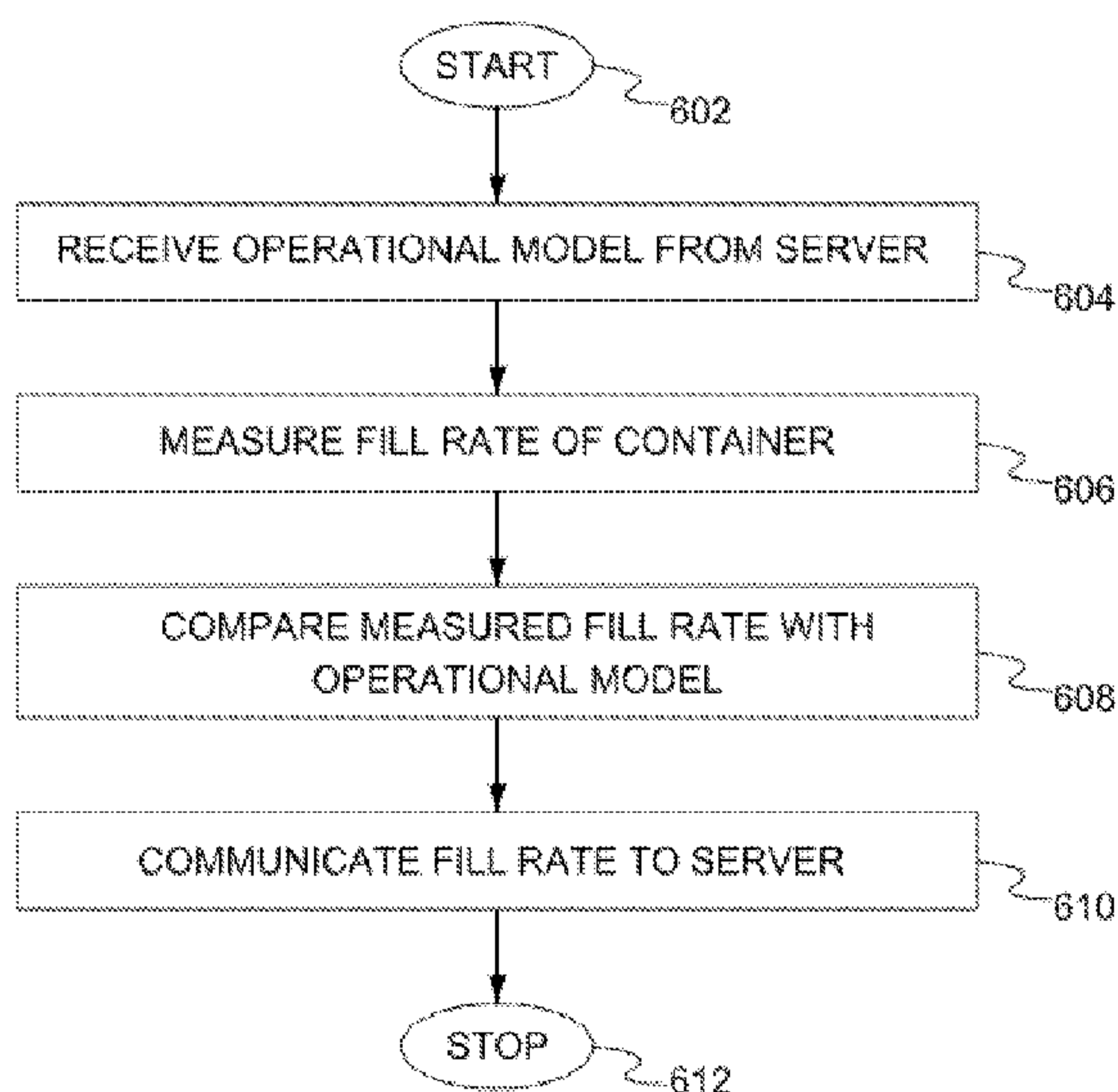


FIG. 6

(57) Abstract: Disclosed is a method for monitoring a fill rate of a container and communicating the monitored fill rate to a server, the container comprising at least a first sensor which is a fill rate sensor in a normally non-active mode. The method comprises receiving an operational model from a server, the operational model defining a wake-up signal to determine whether to initiate communication between the fill rate sensor and the server, the operational model also defining a pre-determined fill rate level comprising a predefined maximum value of the fill rate and/or a predefined minimum value of the fill rate, wherein communication between the fill rate sensor and the server only occurs when the pre-determined fill rate level is not met; detecting the wake-up signal; measuring the fill rate of the container with the fill rate sensor; comparing a measured fill rate with the pre-determined fill rate level defined in the operational model; and communicating the measured fill rate to the server only if the measured fill rate is equal to or above the predefined maximum value of the fill rate, and/or the measured fill rate is equal to or below the predefined minimum value of the fill rate.

METHOD AND SYSTEM FOR MONITORING AND COMMUNICATING FILL RATE OF CONTAINER

TECHNICAL FIELD

The present disclosure relates generally to a wireless monitoring and communication
5 methods and systems; and more specifically, to methods and systems for monitoring and
communicating a fill rate of a container in a power efficient manner.

BACKGROUND

Use of garbage containers can be seen in almost all commercial and residential places.
Such garbage containers are required to be periodically emptied or cleaned. Typically,
10 maintenance personnel associated with such cleaning or emptying job use trucks for
emptying such garbage containers. The maintenance personnel have scheduled routes
and limited time to run the trucks for emptying garbage containers of various localities.
In order to make the entire process of garbage collection efficient, it is desirable to know
fill levels of the garbage containers so as to ensure timely cleanliness of such garbage
15 containers. For example, the fill level information can help in designing a route and
scheduling time for emptying garbage containers of a particular locality. Also, having the
ability to predict a proper emptying time for a garbage container helps the garbage
collector to plan the route of the garbage collector truck to reduce costs related to the
whole garbage collection process.

20 In order to address such issues, nowadays garbage containers are often equipped with a
gauge that is configured to monitor a fill level of the garbage container and communicate
the same to a remote server. The server receives and processes the fill level data to design
an efficient route and schedules time for emptying garbage container of a particular
locality. However, such gauges require continuous monitor of the fill level and
25 communication of the same to the server. For example, at least one communication is
scheduled between the gauge and the server every day for sending the fill level data to
the server. Typically, such communications are made irrespective of the fill level of the
container, i.e. the gauge communicates with the server even if the container is half filled.
Therefore, such communications are undesirable as they consume a substantial amount

of battery power of the gauge and do not provide any critical data. As a result, the battery of the gauge is either required to be replaced in quick succession due to such undesirable communications or requires employment of heavier duty battery for a longer operation of such gauges.

- 5 Therefore, in light of the foregoing discussion, there exists a need to overcome the aforementioned drawbacks of undesirable communications generally performed between a gauge and a server in the process of determining a fill level of a container.

SUMMARY

The present disclosure seeks to provide a method for monitoring and communicating a
10 fill rate of a container.

The present disclosure also seeks to provide a system for monitoring and communicating a fill rate of a container.

In one aspect, an embodiment of the present disclosure provides a method for monitoring a fill rate of a container and communicating the monitored fill rate to a server, the
15 container comprising at least a first sensor which is a fill rate sensor in a normally non-active mode. The method comprises

- receiving an operational model from a server, the operational model defining a wake-up signal to determine whether to initiate communication between the fill rate sensor and the server, the operational model also defining a pre-determined fill rate level comprising
20 a predefined maximum value of the fill rate and/or a predefined minimum value of the fill rate, wherein communication between the fill rate sensor and the server only occurs when the pre-determined fill rate level is not met;
- detecting the wake-up signal;
- measuring the fill rate of the container with the fill rate sensor;
- 25 - comparing a measured fill rate with the pre-determined fill rate level defined in the operational model; and
- communicating the measured fill rate to the server only if
 - the measured fill rate is equal to or above the predefined maximum value of the fill rate, and/or

- the measured fill rate is equal to or below the pre-defined minimum value of the fill rate.

In another aspect, an embodiment of the present disclosure provides a system for monitoring a
5 fill rate of a container and communicating it. The system comprises a gauge mounted on the
container, the gauge comprises at least a first sensor which is a fill rate sensor in a normally
non-active mode; and a server communicably coupled to the gauge to provide an operational
model to the gauge, the operational model defining a wake-up signal to determine whether to
10 initiate communication between the fill rate sensor and the server, the operational model also
defining a pre-determined fill rate level having a pre-defined maximum value of the fill rate
and/or a pre-defined minimum value of the fill rate, wherein communication between the fill
rate sensor and the server only occurs when the pre-determined fill rate level is not met,
wherein, based on the operational model the gauge is configured to measure a fill rate of the
15 container with the fill rate sensor, compare the measured fill rate with the pre-determined fill
rate level defined in the operational model, and communicate the measured fill rate to the
server only if the measured fill rate is equal to or above the pre-defined maximum value of the
fill rate, and/or the measured fill rate is equal to or below the pre-defined minimum value of
the fill rate.

20 In another aspect, there is provided a method for measuring a fill rate of a container and
communicating the measured fill rate to a server, the container comprising a gauge affixed to
the container, the gauge comprising a fill rate sensor configured to measure the fill rate of the
container, a microcontroller communicatively coupled to the fill rate sensor and a transceiver
device, the microcontroller and the transceiver device being in a normally non-active mode,
25 the method comprising: the gauge receiving and storing an operational model from the server,
the operational model defining in the gauge: a communication schedule for communication
from the gauge to the server; a pre-determined fill rate level for the container, the pre-
determined fill rate level defining a pre-defined maximum value of the fill rate and a pre-
defined minimum value of the fill rate; and a wake-up signal for the gauge, the wake-up signal
30 configured to initiate a communication comprising the measured fill rate from the gauge to the
server outside of the communication schedule, wherein the wake-up signal is generated when
the measured fill rate is equal to or above the pre-defined maximum value of the fill rate or is
equal to or below the pre-defined minimum value of the fill rate; the method further comprising

the fill rate sensor: measuring the fill rate of the container; comparing the measured fill rate with the pre-determined fill rate level defined in the operational model; and generating the wake-up signal to switch on the microcontroller and the transceiver device from the normally non-active mode to a transmitting mode in order to cause the gauge to transmit the communication comprising the measured fill rate to the server only if: the measured fill rate is equal to or above the pre-defined maximum value of the fill rate defined in the operational model, or the measured fill rate is equal to or below the pre-defined minimum value of the fill rate defined in the operational model; and receiving an updated operational model from the server in response to the transmitted communication comprising the measured fill rate, the updated operational model being used as the operational model for the gauge.

In another aspect, there is provided a system for measuring and communicating a fill rate of a container, the system comprising: a gauge mounted on the container, the gauge comprising a fill rate sensor configured to measure the fill rate of the container, a microcontroller communicative coupled to the fill rate sensor and a transceiver, the microcontroller and the transceiver being in a normally non-active mode; and a server communicably coupled to the gauge to provide an operational model to the gauge, the operational model defining in the gauge: a communication schedule for communication from the gauge to the server; a pre-determined fill rate level for the container, the pre-determined fill rate level defining a pre-defined maximum value of the fill rate and a pre-defined minimum value of the fill rate; a wake-up signal for the gauge, the wake-up signal configured to initiate a communication comprising the measured fill rate from the gauge to the server outside of the communication schedule, wherein the wake-up signal is generated when the measured fill rate is equal to or above the pre-defined maximum value of the fill rate or is equal to or below the pre-defined minimum value of the fill rate; wherein, based on the operational model the gauge is configured to measure the fill rate of the container with the fill rate sensor, compare the measured fill rate with the pre-determined fill rate level defined in the operational model, and generate the wake-up signal to cause the microcontroller and the transceiver to switch from the normally non-active mode to an active state in order for the gauge to transmit the communication comprising the measured fill rate to the server only if: the measured fill rate is equal to or above the pre-defined maximum value of the fill rate defined in the operational model, or the measured fill rate is equal to or below the pre-defined minimum value of the fill rate defined in the operational model; and receiving an updated operational model from the server in response to

the transmitted communication comprising the measured fill rate, the updated operational being used as the operational model for the gauge.

5 Embodiments of the present disclosure substantially eliminate or at least partially address the aforementioned problems in the prior art, and enable monitoring and communicating a fill rate of a container by a gauge in a power efficient manner.

10 Additional aspects, advantages, features and objects of the present disclosure would be made apparent from the drawings and the detailed description of the illustrative embodiments construed in conjunction with the appended claims that follow.

It will be appreciated that features of the present disclosure are susceptible to being combined in various combinations without departing from the scope of the present disclosure as defined by the appended claims.

BRIEF DESCRIPTION OF THE DRAWINGS

5 The summary above, as well as the following detailed description of illustrative embodiments, is better understood when read in conjunction with the appended drawings. For the purpose of illustrating the present disclosure, exemplary constructions of the disclosure are shown in the drawings. However, the present disclosure is not limited to specific methods and instrumentalities disclosed herein. Moreover, those in the art will
10 understand that the drawings are not to scale. Wherever possible, like elements have been indicated by identical numbers.

Embodiments of the present disclosure will now be described, by way of example only, with reference to the following diagrams wherein:

15 FIG. 1 is a schematic illustration of a garbage container; in accordance with an embodiment of the present disclosure;

FIG. 2 is a schematic illustration of a gauge architecture; in accordance with an embodiment of the present disclosure;

20 FIG. 3 is a schematic illustration of a system for monitoring and communicating a fill rate of garbage containers, in accordance with an embodiment of the present disclosure;

FIG. 4 is an illustration of steps of a method of a server operation, in accordance with an embodiment of the present disclosure;

FIG. 5 is an illustration of steps of a method of a gauge operation, in accordance with an embodiment of the present disclosure; and

25 FIG. 6 is an illustration of steps of a method for monitoring and communicating a fill rate of a container, in accordance with an embodiment of the present disclosure.

In the accompanying drawings, an underlined number is employed to represent an item over which the underlined number is positioned or an item to which the underlined number is adjacent. A non-underlined number relates to an item identified by a line linking the non-underlined number to the item. When a number is non-underlined and accompanied by an associated arrow, the non-underlined number is used to identify a general item at which the arrow is pointing.

DETAILED DESCRIPTION OF EMBODIMENTS

The following detailed description illustrates embodiments of the present disclosure and ways in which they can be implemented. Although some modes of carrying out the present disclosure have been disclosed, those skilled in the art would recognize that other embodiments for carrying out or practicing the present disclosure are also possible.

In an aspect, an embodiment of the present disclosure provides a method for monitoring a fill rate of a container and communicating the monitored fill rate to a server, the container comprising at least a first sensor which is a fill rate sensor in a normally non-active mode. The method comprises

- receiving an operational model from a server, the operational model defining a wake-up signal to determine whether to initiate communication between the fill rate sensor and the server, the operational model also defining a pre-determined fill rate level comprising a predefined maximum value of the fill rate and/or a predefined minimum value of the fill rate, wherein communication between the fill rate sensor and the server only occurs when the pre-determined fill rate level is not met;
- detecting the wake-up signal;
- measuring the fill rate of the container with the fill rate sensor;
- comparing a measured fill rate with the pre-determined fill rate level defined in the operational model; and
- communicating the measured fill rate to the server only if
 - the measured fill rate is equal to or above the predefined maximum value of the fill rate, and/or
 - the measured fill rate is equal to or below the predefined minimum value of the fill rate.

In another aspect, an embodiment of the present disclosure provides a system for monitoring and communicating a fill rate of a container. The system comprises

- a gauge mounted on the container, the gauge comprises at least a first sensor which is a fill rate sensor in a normally non-active mode; and
- a server communicably coupled to the gauge to provide an operational model to the gauge, the operational model defining a wake-up signal to determine whether to initiate communication between the fill rate sensor and the server, the operational model also defining a pre-determined fill rate level having a predefined maximum value of the fill rate and/or a predefined minimum value of the fill rate, wherein communication between the fill rate sensor and the server only occurs when the pre-determined fill rate level is not met,

wherein, based on the operational model the gauge is configured to

- measure a fill rate of the container with the fill rate sensor,
- compare the measured fill rate with the pre-determined fill rate level defined in the operational model, and
- communicate the measured fill rate to the server only if
 - the measured fill rate is equal to or above the predefined maximum value of the fill rate, and/or
 - the measured fill rate is equal to or below the predefined minimum value of the fill rate.

In one embodiment, the container is a garbage container used for temporarily collecting garbage or trash therein. The garbage container can be assigned to a particular locality for collecting the garbage in and around that locality. The garbage container includes a hollow body for collecting garbage therein and a lid for closing the body. The garbage container can be a garbage bin (having various sizes of about 20 to 100 Gallon (about 75 to 380 litres)) or a garbage cart (having various sizes of about 2 to 8 yards (about 1.8 to 7.3 meters)). The garbage container is periodically emptied or cleaned by maintenance personnel. For example, the garbage container may be associated with a specific route and scheduled time defined for emptying thereof.

In one embodiment, the container comprises the gauge mounted on the lid thereof. Alternatively, the gauge may be mounted on a substantially upper portion of the body of the container. Further, the gauge is preferably mounted in a non-obstructive manner, such that the gauge does not obstruct garbage from being collected into the body.

- 5 As explained above, the gauge comprises at least a first sensor, which is the fill rate sensor. According to an embodiment, the fill rate sensor is selected from the group consisting of ultrasonic sensor, infrared sensor, pressure sensor, weight sensor, ultra wideband radar sensor, CCD camera sensor and laser sensor.

10 According to an embodiment, the gauge also comprises other sensors in addition to the fill rate sensor. For example, the gauge comprises at least a second sensor. The second sensor can be selected from a group consisting of ultrasonic sensor, accelerometer, humidity sensor, gas sensor, ambient light sensor and temperature sensor.

15 In addition to above, the gauge may also comprise a microcontroller with embedded memory for a program data and data storage, a wireless transceiver and antenna typically operating on Global System for Mobile communication (GSM) or similar cellular standard. The gauge preferably also comprises a battery for powering the sensors, the microcontroller and the wireless transceiver. The battery can be an industrial grade Li-Ion battery. Further, the gauge, particularly the microcontroller, preferably includes a clock function, i.e. a real time clock.

20 In one embodiment, the gauge is a sealed device, such that, the gauge cannot be opened for tampering. Further, in case of any malfunction, the damaged gauge may be replaced with a new gauge.

The system of present disclosure preferably comprises a plurality of such gauges adapted to be mounted on various garbage containers belonging to different localities.

25 The plurality of gauges may be coupled to the server via one or more communication networks. The communication network can be a wired, wireless, or a combination thereof. Examples of such communication network includes, but are not limited to, Local Area Networks (LANs), Wide Area Networks (WANs), Metropolitan Area Networks (MANs), Wireless LANs (WLANs), Wireless WANs (WWANs), Wireless MANs

(WMANs), the Internet, second generation (2G) telecommunication networks, third generation (3G) telecommunication networks, fourth generation (4G) telecommunication networks, and Worldwide Interoperability for Microwave Access (WiMAX) networks.

According to an embodiment, the server is operable to provide operational models to the gauges. The server may comprise a program code that makes the server to connect with the gauges for providing the operational models. The program code also makes the server operable to exchange data with the gauges and design operational models for the gauges, which is explained in greater detail herein later. Additionally, the server may be operable to store received data from the gauges, i.e. the server may include a database for storing the received data.

The system of the present disclosure also preferably comprises a user device operatively coupled to the server. The user device is operable to control the server and exchange data with the server. The server provides a user interface on the user device for controlling and monitoring the operation of the server. In an example, the user device may be a computing device which includes but is not limited to a laptop or a desktop.

The operational models provided to the gauges may be different from each other. Specifically, each operational model typically contains different set of instructions defining different patterns of operation for the gauges.

According to an embodiment, an operational model is calculated or designed based on various external parameters (independent of gauge measurement data). The parameters include but are not limited to a gauge type and capabilities, physical coordinates of the installation of the gauge and customer agreement related the container use.

Additionally, an operational model may be calculated by analyzing gauge measurement data over a period of time, which is explained in detail herein later.

Optionally, an operational model is calculated based on both external parameters and analyzed data collected from the gauge.

The gauges of the present disclosure are designed for low power operation, i. e. the microcontrollers thereof typically stay in sleep mode (i.e. not in communication with the

server) until they receive a wake-up signal from at least one of the sensor or the clock function as defined in the operational model.

According to an embodiment, the sensors of the gauges measure data and transmit the measurement data to the server only when one or more measured data is out of allowed
5 ranges (as defined in the operational model). The allowed ranges of sensor data that generate wake-up signals are defined in the operational model. For example, when a gauge is mounted on a lid of a residential single-house garbage container, in such instance, a wake-up signal can be set to 3G, which in this case is a minimum acceleration when the lid is closed. Alternatively, a more complex definition of wake-up signal can
10 be defined, such as, temperature above a threshold for a certain time period and the like, which will be explained in detail herein later.

According to an embodiment, the operational model comprises a predicted fill rate of the container as a function of time. The predicted fill rate may be expressed in number of days, i.e. the garbage container is expected to be filled as per the defined number of days.
15 For example, if a garbage container generally fills at a rate of 10 % every day, then the predicted fill rate of the container would be 10 days, when the container is expected to be completely filled. Therefore, the operational model can include a predicted fill rate of 8 days or 9 days, when the container is expected to be filled by 80 % or 90 %, respectively. Accordingly, the gauge would communicate with the server after 8 or 9
20 days based on such operational model.

Based on above operational model, the clock function of the gauge wakes up the microcontroller from the sleep mode after 8 or 9 days. This would instruct the transceiver of the gauge to transmit a fill rate data to the server.

According to an embodiment, the operational model further comprises a predefined
25 measurement schedule and a predefined communication schedule. The predefined measurement schedule and the predefined communication schedule are also a function of time, however, such schedules may be associated with an uneven time line instead of an even time line.

Based on the predefined measurement schedule the gauge, particularly the sensors thereof, may measure various data (such as for example fill rate data, accelerometer data, humidity data, ambient light data, temperature data and gas data) related to a garbage level of the garbage container. Further, based on the predefined communication schedule the gauge communicates with the server to transmit such measurement data. In an example, the predefined schedules can be associated with peak hours of a day or peak days of a month or year, when the gauge should measure and communicate such data to the server.

An example operation of a gauge, having the above operational model, is configured to measure and communicate data to the server at around 10 am on 26th of December (after Christmas), when a probability of the garbage container to be filled is substantially high. Similarly, the predefined measurement and communication schedules may relate to all festive or holiday seasons when the probability of the garbage container to be filled is substantially high. In addition to this, the predefined measurement and communication schedules may be associated to weekends instead of week days.

According to an embodiment, the operational model further comprises allowed ranges for measurement data from at least one of the sensors as a function of time. The operational model thus defines allowed ranges of measurement data, for each sensors of the gauge, as a function of time. Therefore, once the measurement data of the sensors is equal to or exceeds the allowed ranges for measurement data, the gauge is instructed to communicate with the server. According to an embodiment, the data is selected from a group consisting of fill rate data, accelerometer data, humidity data, ambient light data, temperature data and gas data.

In an example, the temperature sensor may be configured to have an allowed range of 0-40 °C for an hour. The gauge accordingly would communicate with the server when the temperature sensor senses either a temperature of 40 °C or above for more than an hour, or a temperature of 0 °C or below for more than an hour. Similarly, other sensors such as the fill rate sensor, accelerometer, humidity sensor, ambient light sensor and gas sensor can include allowed ranges for measurement data as a function of time.

The allowed ranges of the measurement data (of the sensors) defined in the operational models are dependent on various factors, such as the garbage container type, location, intended use and the like. For example, a gauge mounted on bigger garbage containers may have higher allowed ranges (of measurement data for the sensors) as compared to
5 smaller garbage containers. Further, a gauge mounted on a garbage container associated with largely populated locality would have lower allowed ranges as compared to a gauge mounted on a garbage container associated with less populated locality.

According to an embodiment, the operational model further comprises at least one measurement data combination triggering communication. The measurement data
10 combination triggering communication acts as a wake-up signal for the microcontroller (that generally remains in a sleep mode) to initiate communication between the gauge and the server. The measurement data combination triggering communication is an indication when two or more sensors measurement data when combined together constitute a value (primarily associated with a fill level of the garbage container) for which a
15 communication should be established between the gauge and the server.

Therefore, according to an embodiment, the at least one measurement data combination comprises measurement data from different sensors. For example, the measurement data combination includes any combination of the fill rate data, accelerometer data, humidity data, ambient light data, temperature data and gas data acquired from fill rate sensor,
20 accelerometer, humidity sensor, ambient light sensor, temperature sensor and gas sensor, respectively.

According to an embodiment, the method further comprises the steps of:

- measuring an acceleration of the second sensor, the second sensor comprising an accelerometer and the measured acceleration comprising acceleration data;
- 25 - comparing the acceleration data to a baseline;
- measuring the fill rate of the container after a pre-defined time, when the acceleration data deviates from the baseline more than a pre-defined percentage; and
- communicating the fill rate to the server, if
 - 30 - the fill rate measured after the pre-defined time is equal to or below the predefined minimum fill rate, indicating that the container has been emptied, and/or

- the fill rate measured after the pre-defined time is equal to or above the predefined maximum value of the fill rate, indicating that the container has been filled.

According to an embodiment, the measurement data combination comprises measurement data from the accelerometer and measurement data representing the fill rate. This latter data comes from the fill rate sensor. In an example, the accelerometer measures acceleration of the lid of the garbage container. The measured acceleration data of the lid is compared with a baseline (allowed range) acceleration data of the operational model. For example, the predefined acceleration data can be set to 3G. Thereafter, the fill rate of the container is measured after a pre-defined time, when the acceleration data deviates from the allowed range. Specifically, when the measured acceleration data exceeds 3G, the fill rate of the container is measured a few minutes later. Finally, the fill rate is communicated to the server if the fill rate is equal or above the predefined minimum fill rate, indicating that the container has been filled. Otherwise, the fill rate is communicated to the server if the fill rate is equal or below the predefined maximum fill rate, indicating that the container has been emptied. Additionally, if the measured fill rate is between the predefined maximum and minimum fill rates (indicating that the container is half filled or half emptied), the fill rate is not communicated to the server. This causes the gauge to not communicate with the server.

According to an embodiment, the method comprises, in conjunction with communicating the fill rate to the server, communicating at least part of the measurement data collected since a previous communication. For example, the gauge sends the measurement data collected from the previous communications in addition to a latest fill rate data to server. Additionally, the gauge communicates previous fill rate data and other previous measurement data such as accelerometer data, humidity data, ambient light data, temperature data and gas data (measured by the other sensors of the gauge) to the server.

According to an embodiment, based on the communicated data the server iterates the operational model. Specifically, when the server receives the measurement data from the gauge, the server compares the allowed ranges defined for an existing operational model with the received measurement data. If any deviation in the measurement data and the allowed ranges are found, the server is operable to redefine the existing operational model

and generate a new operation model for the gauge based on such deviations. For example, if a delay in the fill rate data is identified, the same delay is considered while designing the new operational model. Accordingly, the new operational model is communicated to the gauge for the operation thereof.

- 5 Typically, in the process of designing a new operational model, latest and previous measurement data (associated with the sensors) from the gauge are used. Additionally, new external parameter related to agreement with customer, weather condition and the like may be also considered while designing the new operational model.

According to an embodiment, the system is also configured to monitor and communicate
10 an emptying event of the garbage container. The emptying event may be detected and recorded by the gauge and communicated to the server.

In an example, the emptying event of the garbage container is detected using multiple sensing methods as a time based sequence. For example, if a measured data of the accelerometer exceeds an allowed range as per the operational model, the fill rate sensor
15 (such as the ultrasonic sensor) starts collecting data for a predetermined time. The predetermined time can be about 60 seconds, in which the ultrasonic sensor measures data is a sequence of time intervals each separated by 0.1 to 1 seconds. If the ultrasonic sensor senses oscillations of about 20 seconds, an inference can be made that the emptying event has happened. Alternatively, if the ultrasonic sensor remains fairly static, an inference
20 can be made that the emptying event has not been performed.

The system and method of the present disclosure reduces non-critical communication between a gauge and a server. In a conventional scenario, a gauge typically operates to transmit a measured fill level data on a daily basis and in such a situation energy consumed by the communication (between the gauge and the server) constitutes as much
25 as 80 % of the daily energy consumption of the battery. Therefore, in an example scenario, by eliminating 50 % of the communication between the gauge and the server, average daily consumption of the battery can be reduced by 40 %. This can correspond to increase in a battery life of about roughly 67 %. The following calculation can be considered for the above calculated value of the battery life:

Consider,

E_b = energy in battery

E_d = daily consumption of energy

E_c = energy used in communication

5 E_o = energy used for other purposes (microcontroller and/or sensor reading)

T_b = battery lifetime in days

E_{cn} = energy used in communication in the disclosed setup

E_{dn} = daily consumption of energy in the disclosed setup

10 Therefore,

$T_b = E_b / E_d$

$E_d = E_c + E_o$

$E_{dn} = E_{cn} + E_o$

If we consider,

15 $E_{cn} = 0.5 * E_c$

$E_c = 0.8 * E_d$

The ratio of, $E_{dn} / E_d = (E_{cn} + E_o) / (E_c + E_o) = 1.667$ (showing increase in the battery life of about 67 %)

20 It is to be understood that, for the above calculation, power required for communicating an operational model to the gauge is assumed to be negligible. Further, the above calculation does not take into account any substantial increase in the microcontroller activity. However, even if the power consumption of the microcontroller is assumed to be increased by 10 %, still the battery life is expected to be increased by about 61 %.

25 According to an embodiment, the system of the present disclosure can be employed in other fields, apart from monitoring and communicating a fill rate of a garbage container. Specifically, the system of the present disclosure can be employed in general in any field where a container needs to be either filled or emptied. For example, the system can be implemented to monitor and communicate a fill rate of an oil tank of a fuel station. The gauges of the present disclosure can be attached to the oil tank and measured fill rate data
30 of the oil tank (based on the operational model) is forwarded to an oil delivery firm. This

helps the oil delivery firm to make a decision when the oil tank should be refilled and plan and execute the associated logistics efficiently.

The present disclosure provides a system and a method that reduce non-critical communication between a gauge and a server. The reduced communication helps in substantially increasing a battery life of the gauge and makes an entire process of monitoring and communicating a fill rate of a container (such as the garbage container, the oil tank and the like) power efficient. Typically, a battery life of a gauge is ten years in a conventional scenario, based on the system and method of the present disclosure an expected battery life can be increased by for example about 67 %. Therefore, a battery with smaller capacity can be used as an alternative. This further make the entire process of monitoring and communicating the fill rate of the container cost efficient. Finally, such fill rate data helps in optimizing logistics, such garbage collection truck or oil truck, used for emptying or filling such container.

DETAILED DESCRIPTION OF THE DRAWINGS

Referring now to the drawings, particularly by their reference numbers, FIG. 1 is a schematic illustration of a garbage container **100**. The container **100** primarily includes two parts, i.e., a hollow body **102** and a lid **104** mounted on an upper portion of the hollow body **102**. The lid **104** is attached to the hollow body **102** with the help of a hinge **106**. The lid **104** includes a handle **106** for the opening and closing of the hollow body **102**. The container **100** also includes a gauge **120** attached to an underside of the lid **104**. The gauge **120** is operable to measure an amount of material **130** in the hollow body **102**, i.e. a fill level of the container **100**.

FIG. 2 is a schematic illustration of a gauge architecture, in accordance with an embodiment of the present disclosure. The gauge **120** includes a first sensor **202**, such as a fill rate sensor. The gauge **120** also includes a second sensor, such as sensors **204** and **206**. The gauge **120** further includes a microcontroller **210** with embedded memory for a program code, data storage and a clock function (typically a real time clock). The gauge **120** also includes a wireless transceiver **220** having antenna operable on GSM or similar cellular standard. The gauge **120** further includes a power source **230**, such as a battery,

for providing electrical power to the sensors **202**, **204**, **206**, the microcontroller **210** and the wireless transceiver **220**.

Referring now to FIG. 3, a schematic illustration of a system **300** for monitoring and communicating a fill rate of garbage containers is illustrated, in accordance with an embodiment of the present disclosure. The system **300** includes at least one gauge, such as the gauges **120a**, **120b** and **120c**. Those skilled in the art would recognize that the gauges **120a**, **120b** and **120c** are similar to the gauge **120** (explained in conjunction with the FIGS. 1 and 2) and attached to containers, such as the container **100**.

The system **300** also includes a server **310**. The server **310** is coupled with the gauges **120a**, **120b** and **120c** via a communication network **320**. The server **310** includes a program code **330** and a database **340**. The program code **330** makes the server **310** to connect with the gauges **120a**, **120b** and **120c** for exchanging data therebetween. The database **340** of the server **310** is configured to store received data therein.

Further, the server **310**, particularly the program code **330** thereof, makes the server **310** operable to provide operational models to the gauges **120a**, **120b** and **120c**. Those skilled in the art would recognize that the operational models provided to the gauges **120a**, **120b** and **120c** are different from each other. The server **310** is operable to start a communication session between the gauges **120a**, **120b** and **120c** and the server **310**, based on the operational models. The gauges **120a**, **120b** and **120c** of the system **100** are designed for low power operation. Specifically, the microcontrollers of the gauges **120a**, **120b** and **120c** generally stay in sleep mode until the microcontrollers receive a wake-up signal from at least one of the sensor or the clock function. The wake-up signal is primarily associated with allowed ranges of at least one of the sensor data or the clock function defined by the operational models.

The gauges **120a**, **120b** and **120c** accordingly communicate with the server **310** for transmitting the measurement data of the sensors. The measurement data is primarily associated with the fill rate of the containers. The server **310** analyzes the measurement data to make changes in the existing operational models or to design new operational models for the gauges **120a**, **120b** and **120c**.

The system **300** also includes a user device **350** operatively coupled to the server **310**. The user device **350** is operable to control the server **310** and exchange data with the server **310**. The server **310** provides a user interface on the user device **350** for controlling and monitoring the operation of the server **310**.

5 Referring now to FIG. 4, illustrated are steps of a method **400** of a server operation, in accordance with an embodiment of the present disclosure. Those skilled in the art would recognize that the method **400** illustrates steps involved in the operation of the server **310** of the FIG. 3.

The method **400** initiates at step **402**. Following step **402**, at step **404**, the server
10 calculates an operational model for a gauge.

At step **406**, the server transfers (or provides) the operational model to the gauge. The operational model instructs how the gauge should operate, i.e. to establish only required or essential communication between the gauge and the server.

At step **408**, the server receives data from the gauge. Once the communication is
15 established between the gauge and the server, the gauge transmits measurement data (of the sensors) to the server. Then at step **410**, the method **400** terminates.

Referring now to FIG. 5, illustrated are steps of a method **400** of a gauge operation, in accordance with an embodiment of the present disclosure. Those skilled in the art would recognize that the method **500** illustrates steps involved in the operation of the gauge **210**
20 explained in conjunction with the FIGS. 1-3.

The method **500** initiates at step **502**. Following step **502**, at step **504**, a gauge receives an operational model. The operational model is provided and designed by a server, operatively coupled to the gauge.

At step **506**, the gauge executes according to the operational model. The operational
25 model instructs the gauge to communicate with the server.

At step **508**, the gauge sends measurement data to the server. The measurement data includes data sensed by sensors of the gauge. Then at step **410**, the method **400** terminates.

Referring now to FIG. 6, illustration of steps of a method **600** for monitoring and communicating a fill rate of a container is shown, in accordance with an embodiment of the present disclosure. The container is configured to include at least a first sensor which is a fill rate sensor.

- 5 The method **600** initiates at step **602**. Following step **602**, at step **604**, the gauge receives an operational model from a server. The operational model includes a predefined maximum and/or minimum value of the fill rate for the fill rate sensor.

At step **606**, the fill rate sensor measures a fill rate of the container.

- At step **608**, the gauge, particularly a microcontroller thereof, compares the measured fill
10 rate calculated by the fill rate sensor with the predefined maximum and/or minimum value of the fill rate defined by the operational model.

- At step **610**, the gauge, particularly a transceiver thereof, communicates the fill rate to the server if the fill rate is equal or above the predefined maximum fill rate, and/or the fill rate is equal or below the predefined minimum fill rate. Then at step **612**, the method **600**
15 terminates.

- The steps **602** to **612** are only illustrative and other alternatives can also be provided where one or more steps are added, one or more steps are removed, or one or more steps are provided in a different sequence without departing from the scope of the claims herein. For example, in addition to communicating the fill rate to the server, at least part of the
20 measurement data collected since a previous communication is communicated to the server. Further, based at least on the communicated data the server iterates the operational model for the gauge.

- Modifications to embodiments of the present disclosure described in the foregoing are possible without departing from the scope of the present disclosure as defined by the
25 accompanying claims. Expressions such as “including”, “comprising”, “incorporating”, “have”, “is” used to describe and claim the present disclosure are intended to be construed in a non-exclusive manner, namely allowing for items, components or elements not explicitly described also to be present. Reference to the singular is also to be construed to relate to the plural.

1. A method for measuring a fill rate of a container and communicating the measured fill rate to a server, the container comprising a gauge affixed to the container, the gauge comprising a fill rate sensor configured to measure the fill rate of the container, a microcontroller communicatively coupled to the fill rate sensor and a transceiver device, the microcontroller and the transceiver device being in a normally non-active mode, the method comprising:

- the gauge receiving and storing an operational model from the server, the operational model defining in the gauge:

a communication schedule for communication from the gauge to the server;

a pre-determined fill rate level for the container, the pre-determined fill rate level defining a pre-defined maximum value of the fill rate and a pre-defined minimum value of the fill rate; and

a wake-up signal for the gauge, the wake-up signal configured to initiate a communication comprising the measured fill rate from the gauge to the server outside of the communication schedule, wherein the wake-up signal is generated when the measured fill rate is equal to or above the pre-defined maximum value of the fill rate or is equal to or below the pre-defined minimum value of the fill rate;

the method further comprising the fill rate sensor:

measuring the fill rate of the container;

comparing the measured fill rate with the pre-determined fill rate level defined in the operational model; and

generating the wake-up signal to switch on the microcontroller and the transceiver device from the normally non-active mode to a transmitting mode in order to cause the gauge to transmit the communication comprising the measured fill rate to the server only if:

- the measured fill rate is equal to or above the pre-defined maximum value of the fill rate defined in the operational model, or

- the measured fill rate is equal to or below the pre-defined minimum value of the fill rate defined in the operational model; and

receiving an updated operational model from the server in response to the transmitted communication comprising the measured fill rate, the updated operational model being used as the operational model for the gauge.

2. The method according to claim 1, wherein the fill rate sensor is selected from the group consisting of an ultrasonic sensor, an infrared sensor, a pressure sensor, a weight sensor, an ultra wideband radar sensor, a CCD camera sensor and a laser sensor.

3. The method according to claim 1, wherein the container further comprises at least a second sensor, and the method further includes:

- measuring an acceleration of the second sensor, the second sensor comprising an accelerometer and the measured acceleration comprises acceleration data;

- comparing the acceleration data to a baseline;

- measuring the fill rate of the container after a pre-defined time has elapsed from the measurement of the acceleration of the second sensor and the acceleration data deviates from the baseline by more than a pre-defined percentage value; and generating a wake-up signal to switch on the microcontroller and the transceiver device to

communicate the fill rate measured after the pre-defined time to the server, if

- the fill rate measured after the pre-defined time is equal to or below the pre-defined minimum value of the fill rate, indicating that the container has been emptied, and/or

- the fill rate measured after the pre-defined time is equal to or above the pre-defined maximum value of the fill rate, indicating that the container has been filled.

4. The method according to claim 1, wherein the operational model further defines a predicted fill rate of the container as a function of time.
5. The method according to claim 4, wherein the operational model further defines allowed ranges for measurement data from at least one other sensor as a function of time.
6. The method according to claim 5, wherein the measurement data from the at least one other sensor is selected from a group consisting of accelerometer data, humidity data, ambient light data, temperature data and gas data.
7. The method according to claim 1, wherein the operational model further defines at least one measurement data combination configured to generate the wake-up signal, wherein at least one measurement data combination comprises measurement data from different sensors.
8. The method according to claim 7, wherein the at least one measurement data combination comprises measurement data from an accelerometer and measurement data representing the fill rate.
9. The method according to claim 1, comprising, in conjunction with transmitting the communication comprising measured fill rate to the server, communicating at least part of measured fill rate data collected since a previous communication.
10. The method according to claim 9, wherein the server updates the current operational model based at least on the measured fill rate and the measured fill rate data collected since the previous communication that is communicated to the server.

11. A system for measuring and communicating a fill rate of a container, the system comprising:
-a gauge mounted on the container, the gauge comprising a fill rate sensor configured to measure the fill rate of the container, a microcontroller communicative coupled to the fill rate sensor and a transceiver, the microcontroller and the transceiver being in a normally non-active mode; and
-a server communicably coupled to the gauge to provide an operational model to the gauge, the operational model defining in the gauge:

a communication schedule for communication from the gauge to the server;

a pre-determined fill rate level for the container, the pre-determined fill rate level defining a pre-defined maximum value of the fill rate and a pre-defined minimum value of the fill rate;

a wake-up signal for the gauge, the wake-up signal configured to initiate a communication comprising the measured fill rate from the gauge to the server outside of the communication schedule, wherein the wake-up signal is generated when the measured fill rate is equal to or above the pre-defined maximum value of the fill rate or is equal to or below the pre-defined minimum value of the fill rate;

wherein, based on the operational model the gauge is configured to

measure the fill rate of the container with the fill rate sensor,

compare the measured fill rate with the pre-determined fill rate level defined in the operational model, and

generate the wake-up signal to cause the microcontroller and the transceiver to switch from the normally non-active mode to an active state in order for the gauge to transmit the communication comprising the measured fill rate to the server only if:

- the measured fill rate is equal to or above the pre-defined maximum value of the fill rate defined in the operational model, or

- the measured fill rate is equal to or below the pre-defined minimum value of the fill rate defined in the operational model; and

receiving an updated operational model from the server in response to the transmitted communication comprising the measured fill rate, the updated operational being used as the operational model for the gauge.

12. The system according to claim 11, wherein the fill rate sensor is selected from the group consisting of an ultrasonic sensor, an infrared sensor, a pressure sensor, a weight sensor, an ultra wideband radar sensor, a CCD camera sensor and a laser sensor.

13. The system according to claim 11, wherein the container further comprises at least a second sensor, the second sensor comprising an accelerometer and measured acceleration comprises acceleration data;

wherein the second sensor is configured to:

compare the acceleration data to a baseline and cause the fill rate sensor to measure the fill rate of the container after a pre-defined time has elapsed from the measurement of the acceleration of the second sensor and the acceleration data deviates from the baseline by more than a pre-defined percentage value; and

generate a wake up signal to cause the microcontroller and the transceiver to enable the gauge communicate the fill rate measured after the pre-defined time to the server, if the fill rate measured after the pre-defined time is equal to or below the pre-defined minimum value of the fill rate, indicating that the container has been emptied, and/or the fill rate measured after the pre-defined time is equal to or above the pre-defined maximum value of the fill rate, indicating that the container has been filled.

14. The system according to claim 11, wherein the operational model further defines a predicted fill rate of the container as a function of time.

15. The system according to claim 14, wherein the operational model further defines allowed ranges for measurement data from at least one other sensor as a function of time.

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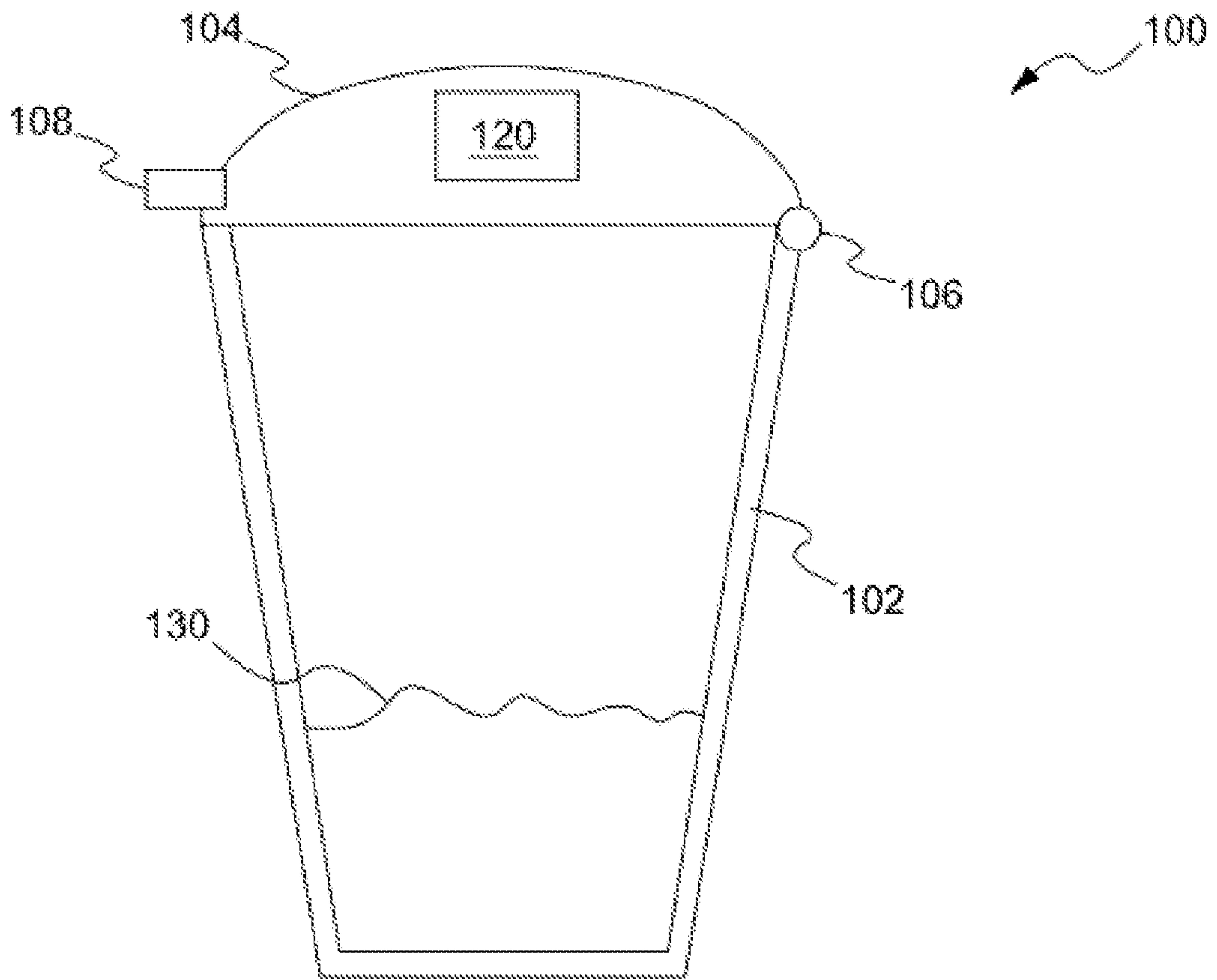


FIG. 1

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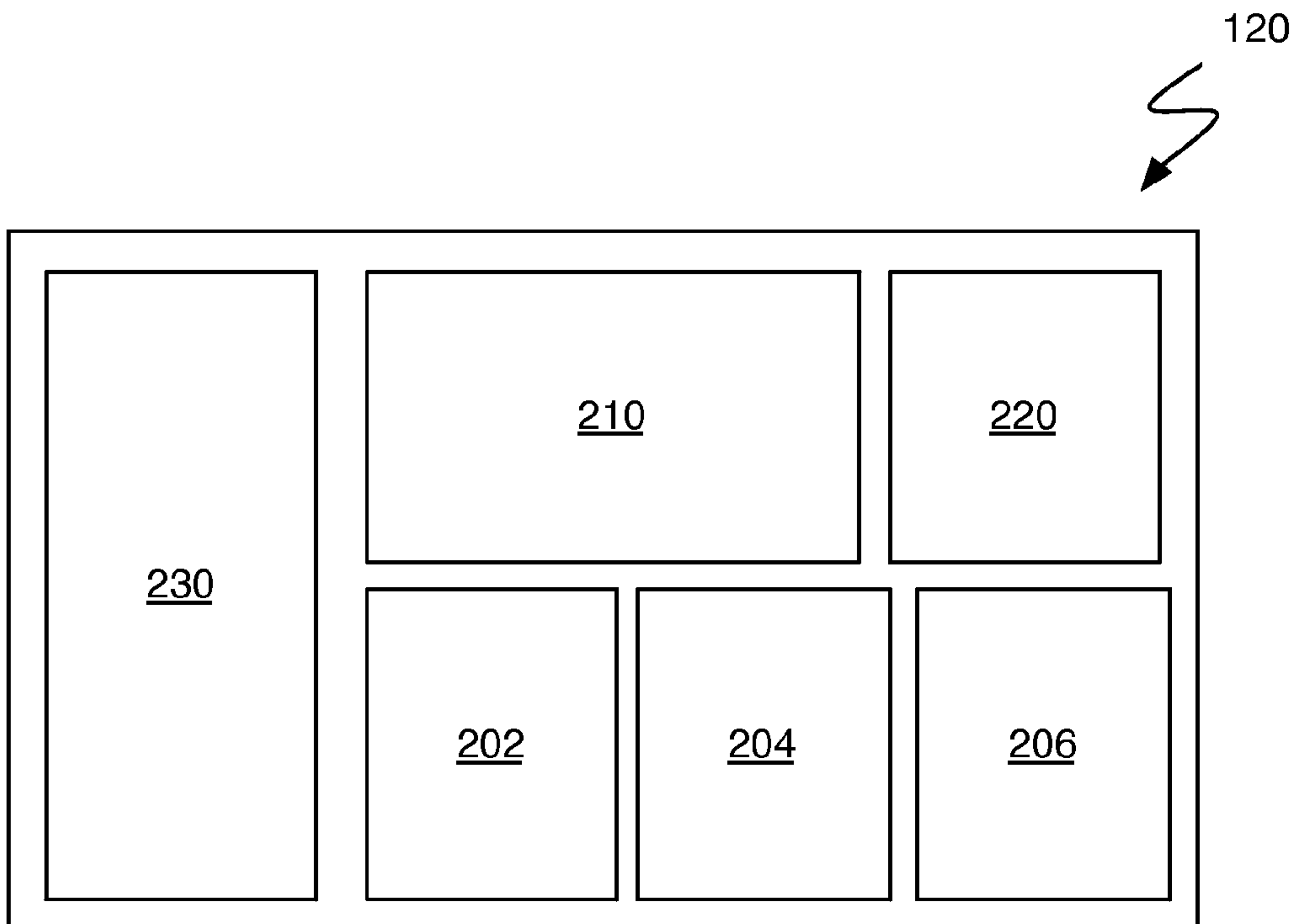


FIG. 2

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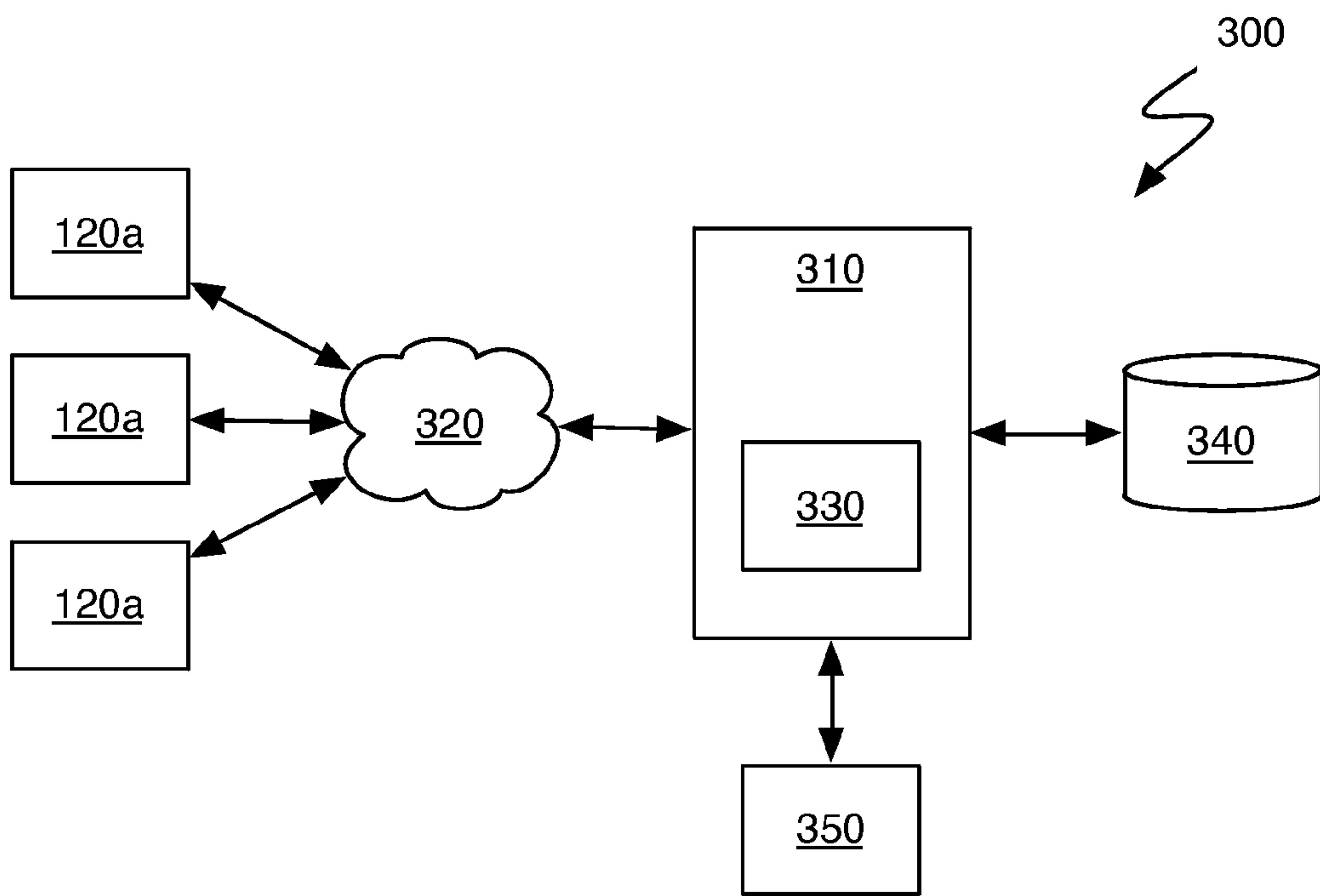


FIG. 3

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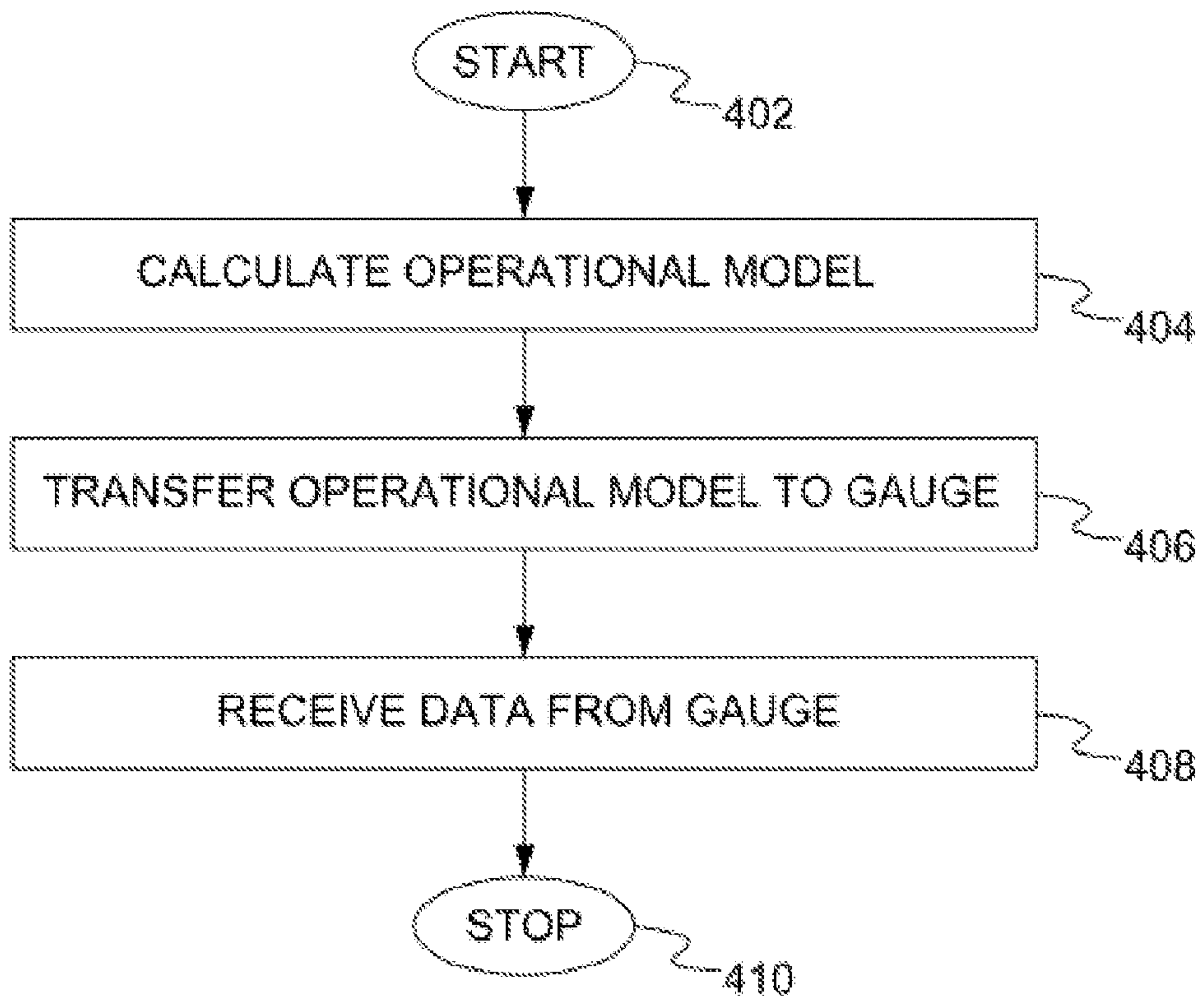


FIG. 4

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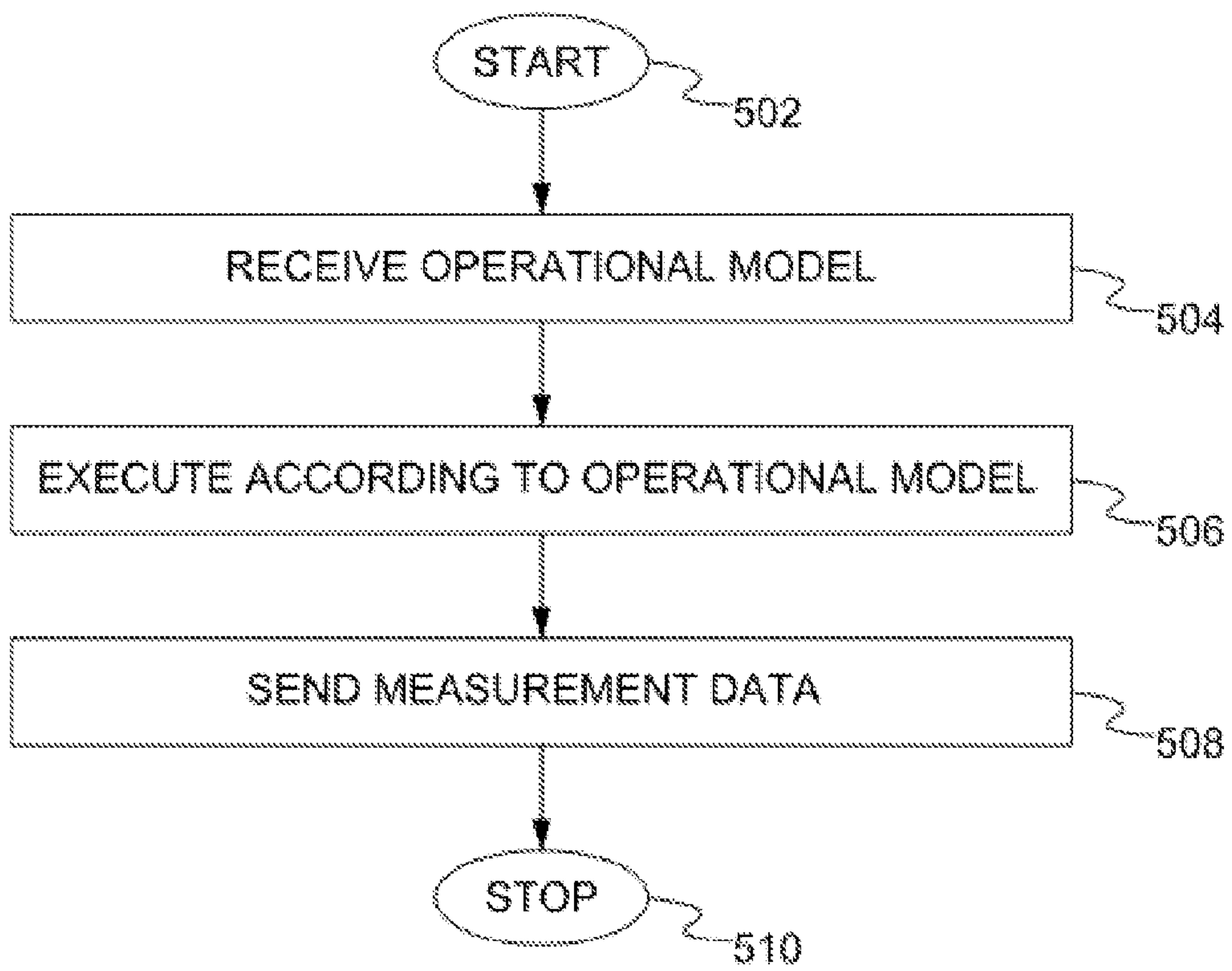


FIG. 5

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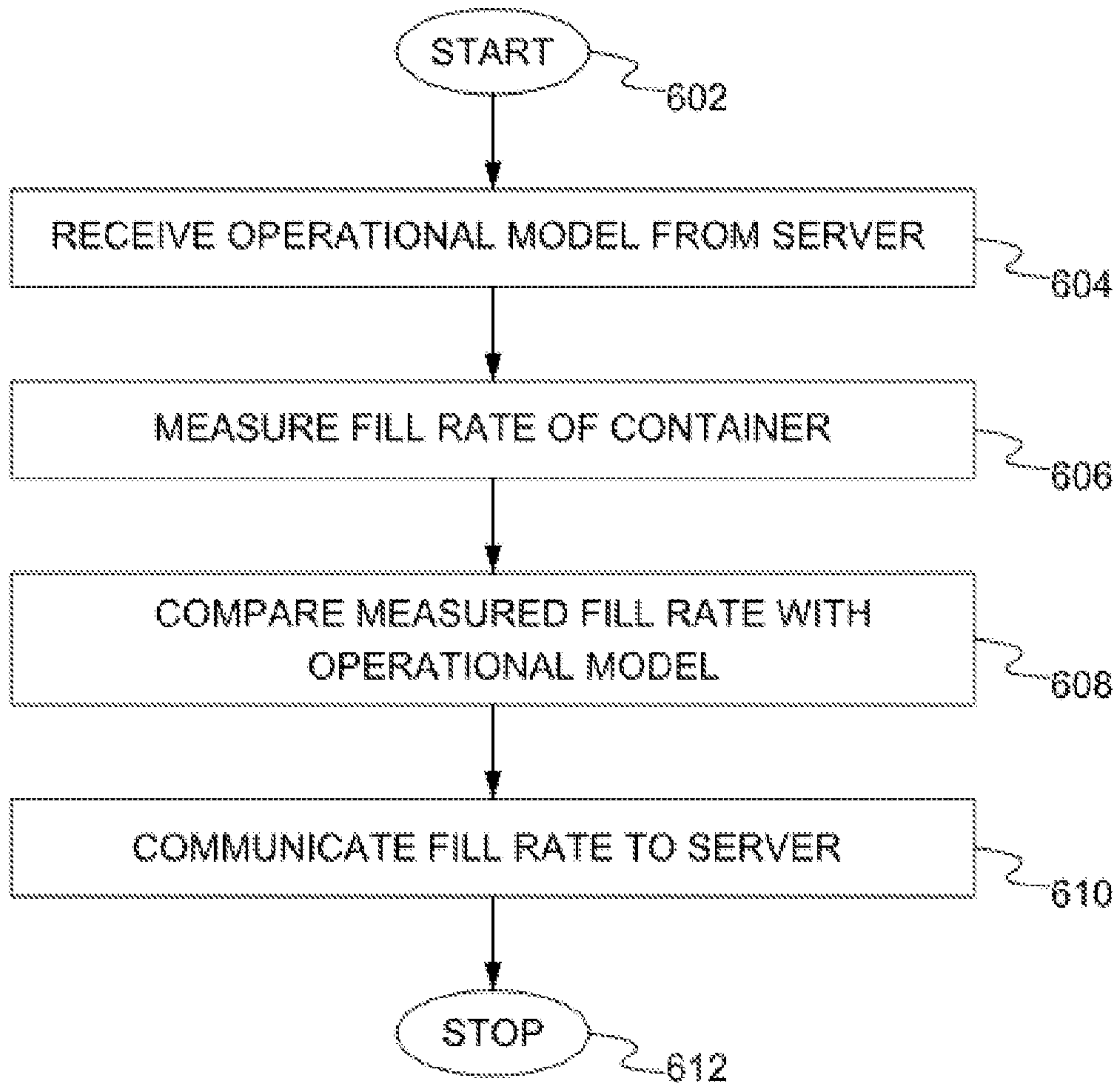


FIG. 6

