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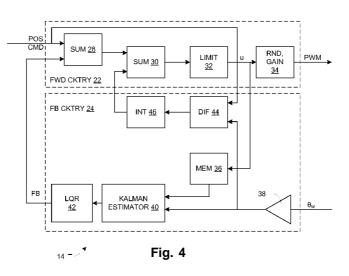
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(54) Title: CONTROLLER FOR ACTUATION SYSTEM EMPLOYING KALMAN ESTIMATOR INCORPORATING EFFECT OF SYSTEM STRUCTURAL STIFFNESS



(57) Abstract: A controller (14) for an electro-mechanical actuation system such as a missile fin (12) actuator includes a Kalman estimator circuit (40) which generates an estimate of operating state including position and velocity of motor (16), position and velocity of a position-controlled element (PCE) (10), and motor current. The estimate is generated based on a dynamic model explicitly including the effect of structural stiffness and damping in the coupling between the motor (16) and the PCE (10), for example by treating it as a mechanical oscillator having spring and damping constants. The Kalman estimator (40) operates on a motor drive control signal and a measured position signal which may be from a Hall sensor sensing motor position. A linear quadratic regulator circuit (42) generates a control effort signal by applying a state feedback gain matrix to a state vector. The state feedback gain matrix mimmizes a quadratic cost function representing variance of the control effort signal and/or the measured position signal.

A. CLASSIFICATION OF SUBJECT MATTER INV. G05B13/04 ADD.

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B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols) G05B

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C. DOCUMENTS CONSIDERED TO BE RELEVANT Citation of document, with indication, where appropriate, of the relevant passages Relevant to claim No. Category' А US 6 564 H Q BI (MAKINO KENICHI [JP] ET 1,8 AL) 13 May 2003 (2003-05-13) cited in the applicati on col umn 2, line 58 - col umn 3, line 22 ----А EP 1 298 053 A2 (COLTEC IND INC [US] 1.8 GOODRICH PUMP & ENGINE CONTROL [US]) 2 Apri I 2003 (2003-04-02) figure 1 ----А Wo 2007/092466 A2 (BAE SYS LAND & 1,8 ARMAMENTS LP $\left[\text{US} \right]$; Shoemaker JEFFREY W [US] ; LEWIS TIM0) 16 August 2007 (2007-08-16) page 7, line 18 - page 8, line 30 X See patent family annex. Further documents are listed in the continuation of Box C. Special categories of cited documents : "T" later document published after the international filing date or priority date and not in conflict with the application but "A" document defining the general state of the art which is not considered to be of particular relevance cited to understand the principle or theory underlying the invention "E" earlier document but published on or after the international "X" document of particular relevance; the claimed invention filing date cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the "O" document referring to an oral disclosure, use, exhibition or document is combined with one or more other such docu ments, such combination being obvious to a person skilled in the art. other means "P" document published prior to the international filing date but later than the priority date claimed "&" document member of the same patent family Date of the actual completion of the international search Date of mailing of the international search report 14 December 2011 21/12/2011 Name and mailing address of the ISA/ Authorized officer European Patent Office, P.B. 5818 Patentlaan 2 NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Fax: (+31-70) 340-3016 Kel peri s, K

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