

(19)



(11)

EP 1 083 832 B1

(12)

EUROPEAN PATENT SPECIFICATION

(45) Date of publication and mention
of the grant of the patent:
14.01.2009 Bulletin 2009/03

(21) Application number: **99928396.3**

(22) Date of filing: **03.06.1999**

(51) Int Cl.:
A61B 17/08 ^(2006.01)

(86) International application number:
PCT/US1999/012563

(87) International publication number:
WO 1999/062409 (09.12.1999 Gazette 1999/49)

(54) **TISSUE CONNECTOR APPARATUS**

VORRICHTUNG ZUR VERBINDUNG VON GEWEBEN

APPAREIL DE JONCTION DE TISSUS

(84) Designated Contracting States:
**AT BE CH CY DE DK ES FI FR GB GR IE IT LI LU
MC NL PT SE**

(30) Priority: **03.06.1998 US 90305**
01.03.1999 US 259705

(43) Date of publication of application:
21.03.2001 Bulletin 2001/12

(60) Divisional application:
08016505.3 / 1 997 441

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Description

TECHNICAL FIELD

[0001] The present invention relates to instruments for connecting body tissues, or body tissue to prostheses.

BACKGROUND ART

[0002] Minimally invasive surgery has allowed physicians to carry out many surgical procedures with less pain and disability than conventional, open surgery. In performing minimally invasive surgery, the surgeon makes a number of small incisions through the body wall to obtain access to the tissues requiring treatment. Typically, a trocar, which is a pointed, piercing device, is delivered into the body with a cannula. After the trocar pierces the abdominal or thoracic wall, it is removed and the cannula is left with one end in the body cavity, where the operation is to take place, and the other end opening to the outside. A cannula has a small inside diameter, typically 5-10 millimeters, and sometimes up to as much as 20 millimeters. A number of such cannulas are inserted for any given operation.

[0003] A viewing instrument, typically including a miniature video camera, or optical telescope is inserted through one of these cannulas and a variety of surgical instruments and refractors are inserted through others. The image provided by the viewing device may be displayed on a video screen or television monitor, affording the surgeon enhanced visual control over the instruments. Because a commonly used viewing instrument is called an "endoscope," this type of surgery is often referred to as "endoscopic surgery." In the abdomen, endoscopic procedures are commonly referred to as laparoscopic surgery, and in the chest, as thoracoscopic surgery. Abdominal procedures may take place either inside the abdominal cavity (in the intraperitoneal space) or in a space created behind the abdominal cavity (in the retroperitoneal space). The retroperitoneal space is particularly useful for operations on the aorta and spine or abdominal wall hernia.

[0004] Minimally invasive surgery has virtually replaced open surgical techniques for operations such as cholecystectomy and anti-reflux surgery of the esophagus and stomach. This has not occurred in either peripheral vascular surgery or cardiovascular surgery. An important type of vascular surgery is to replace or bypass a diseased, occluded or injured artery. Arterial replacement or bypass grafting has been performed for many years using open surgical techniques and a variety of prosthetic grafts. These grafts are manufactured as fabrics (often from DACRON® (polyester fibers) or TEFLON® (fluorocarbon fibers)) or are prepared as autografts (from the patient's own tissues) or heterografts (from the tissues of animals) or a combination of tissues, semi-synthetic tissues and or alloplastic materials. A graft can be joined to the involved artery in a number of differ-

ent positions, including end-to-end, end-to-side, and side-to-side. This attachment between artery and graft is known as an anastomosis. Constructing an arterial anastomosis is technically challenging for a surgeon in open surgical procedures, and is almost a technical impossibility using endoscopically minimally invasive techniques.

[0005] Many factors contribute to the difficulty of performing arterial replacement or bypass grafting. See generally, Wylie, Edwin J. et al., Manual of Vascular Surgery, (Springer-Verlag New York), 1980. One such factor is that the tissues to be joined must be precisely maligned with respect to each other to ensure the integrity and patency of the anastomosis. If one of the tissues is affixed too close to its edge, the suture can rip through the tissue and impair both the tissue and the anastomosis. Another factor is that, even after the tissues are properly aligned, it is difficult and time consuming to pass the needle through the tissues, form the knot in the suture material, and ensure that the suture material does not become tangled. These difficulties are exacerbated by the small size of the artery and graft. The arteries subject to peripheral vascular and cardiovascular surgery typically range in diameter from several millimeters to several centimeters. A graft is typically about the same size as the artery to which it is being attached. Another factor contributing to the difficulty of such procedures is the limited time available to complete the procedure. The time the surgeon has to complete an arterial replacement or bypass graft is limited because there is no blood flowing through the artery while the procedure is being done. If blood flow is not promptly restored, sometimes in as little as thirty minutes, the tissue the artery supplies may experience significant damage, or even death (tissue necrosis). In addition, arterial replacement or bypass grafting is made more difficult by the need to accurately place and space many sutures to achieve a permanent hemostatic seal. Precise placement and spacing of sutures is also required to achieve an anastomosis with long-term patency.

[0006] Highly trained and experienced surgeons are able to perform arterial replacement and bypass grafting in open surgery using conventional sutures and suturing techniques. A suture has a suture needle that is attached or "wedged on" to a long, trailing suture material. The needle must be precisely controlled and accurately placed through both graft and artery. The trailing suture material must be held with proper tension to keep the graft and artery together, and must be carefully manipulated to prevent the suture material from tangling. In open surgery, these maneuvers can usually be accomplished within the necessary time frame, thus avoiding the subsequent tissue damage (or tissue death) that can result from prolonged occlusion of arterial blood flow.

[0007] The difficulty of suturing a graft to an artery using minimally invasive surgical techniques has effectively prevented the safe use of this technology in both peripheral vascular and cardiovascular surgical procedures.

When a minimally invasive procedure is done in the abdominal cavity, the retroperitoneal space, or chest, the space in which the operation is performed is more limited, and the exposure to the involved organs is more restricted, than with open surgery. Moreover, in a minimally invasive procedure, the instruments used to assist with the operation are passed into the surgical field through cannulas. When manipulating instruments through cannulas, it is extremely difficult to position tissues in their proper alignment with respect to each other, pass a needle through the tissues, form a knot in the suture material once the tissues are aligned, and prevent the suture material from becoming tangled. Therefore, although there have been isolated reports of vascular anastomoses being formed by minimally invasive surgery, no system has been provided for wide-spread surgical use which would allow such procedures to be performed safely within the prescribed time limits.

[0008] As explained above, anastomoses are commonly formed in open surgery by suturing together the tissues to be joined. However, one known system for applying a clip around tissues to be joined in an anastomosis is disclosed in a brochure entitled, "VCS Clip Applier System", published in 1995 by Auto Suture Company, a Division of U.S. Surgical Corporation. A clip is applied by applying an instrument about the tissue in a non-penetrating manner. i.e., the clip does not penetrate through the tissues, but rather is clamped down around the tissues. As previously explained, it is imperative in forming an anastomosis that tissues to be joined are properly aligned with respect to each other. The disclosed VCS clip applier has no means for positioning tissues. Before the clip can be applied, the tissues must first be properly positioned with respect to each other, for example by skewering the tissues with a needle as discussed above in common suturing techniques or with forceps to bring the tissues together. It is extremely difficult to perform such positioning techniques in minimally invasive procedures.

[0009] WO-A-97/32526 discloses a guide that is used to position a suture spring device in anatomical tissue in an elastically deformed, expanded state. The guide is subsequently removed to permit the suture spring device to move from the elastically deformed, expanded state toward a relaxed, contracted state to apply a predetermined compression to the tissue engaged by the device. In one embodiment, the guide includes a hollow, tubular body of coiled configuration defining a plurality of connected coils or rings with a predetermined radius of curvature and a predetermined axial spacing therebetween. The suture spring device includes an elastic body which is of coiled configuration in the contracted state to define a single ring, a portion of a ring or a plurality of connected rings having a radius of curvature and/or axial spacing in the relaxed, contracted state which is smaller than the predetermined radius of curvature and/or axial spacing of the guide so that, when the suture spring device is disposed within the guide, it is maintained in an elastically

deformed, expanded state for positioning in anatomical tissue.

[0010] US-A-4 345 601 discloses a suturing apparatus for continuous suturing of incised or ruptured tissues. The preferred form includes a curved or arcuate suturing needle and an appendage at the nonpointed end protruding from the needle in a direction opposite the needle tip. A slotted, arcuate sleeve with flanged ends partially encases the needle while permitting internal sliding arcuate movement, the extent of which is dictated by the length of the slot through which the needle appendage slides. A pointed needle cap having suturing thread attached thereto is placed on the tip of the suturing needle. During suturing, the needle cap with attached suturing thread is pushed through the tissues moving in an arcuate path. A grasping device in the needle sleeve retains the needle cap after the needle passes through the tissue and as the suturing needle is withdrawn from the tissue. The suturing needle extends beyond the suture into the needle sleeve end holding the needle cap and engages the needle cap, whereupon the grasping device releases the needle cap, and the suturing needle is retracted, preparing the apparatus for the next suture.

[0011] US-A-4 899 744 discloses an apparatus for anastomosing a digestive tract including a plurality of substantially U-shaped retainers that are disposed around an annular groove in the outer periphery of a support tube formed of a soluble material. The annular groove has inner side and bottom surfaces and the retainers are disposed in the tube at a plurality of locations along both the inner side surfaces and the inner bottom surface of the groove in a radial array. The retainers have spaced apart ends and are each made of a shape memory alloy or resin endowed with a property of moving the spaced apart ends to a closed state at a predetermined temperature, or made using a spring member, or provided at the spaced apart ends with magnets that will attract each other. In use, the retainers are released from the support tube when the soluble material of the support tube is dissolved and assume closed state when they reach the predetermined temperatures to clamp the digestive tract therebetween.

DISCLOSURE OF THE INVENTION

[0012] According to the present invention there is provided a tissue connector assembly comprising a clip moveable between an open configuration and a closed configuration, said clip having a mechanical restraining device coupled to said clip for restraining said clip in said open configuration, characterized in that:

said mechanical restraining device comprises a coil surrounding at least a portion of said clip.

[0013] A tissue connector assembly is provided with a clip moveable between an open configuration and a closed configuration, and a mechanical restraining de-

vice attached to the clip for restraining the clip in its open configuration.

[0014] In one embodiment a plurality of strands are releasably coupled to the clip to restrain it. The mechanical restraining device includes a release mechanism having a plurality of strands which may be releasably coupled to an enlarged portion of the clip.

[0015] The clip may have a generally U-shaped configuration when in its open configuration. Alternatively, the clip may have equivalent structure when in the open configuration, e.g., C-shaped, V-shaped, J-shaped, and other similarly shaped configurations.

[0016] The mechanical restraining device may include a coil for biasing the clip in its Open configuration. Alternatively, the clip may include a tubular wire and the mechanical restraining device may include an elongated member that is positionable within the tubular wire.

[0017] According to another aspect of the present invention, a tissue connector assembly generally comprises a clip having a spiral shaped configuration when in a closed configuration and an open configuration wherein the clip is configured to form less than a full 360 degree turn. The spiral may be formed in one plane or may extend from a plane of a first loop of the spiral to form a generally conical shaped helical clip. The spiral shaped configuration of the clip generally provides for tight compression of the connecting tissue and may reduce the amount of surface area of the clip exposed to blood flow in an anastomosis, for example.

[0018] A needle may be attached to the clip for piercing tissue/graft material, and may be releasably attached to facilitate removal of the needle after insertion of the clip. The clip is generally small enough to prevent obstruction of a surgeon's view of the tissue being connected and allow for precise control of the clip by the surgeon.

[0019] In another aspect of the invention, a locking device is provided for releasably locking the clip in its open configuration. Upon release of the locking device a restraining force is removed from the clip to allow the clip to move to its unbiased, closed position. Advantageously, the locking device may also be arranged to removably connect a needle to the clip. Upon release of the locking device, the needle is disconnected from the clip. Both removal of the needle and release of the biasing force from the clip may occur simultaneously.

[0020] The present invention generally includes inserting a clip through tissue with the clip biased in an open position by a restraining device coupled to the clip, and removing the restraining force on the clip to allow the clip to close.

[0021] Another aspect of the present invention generally includes inserting a needle and a clip attached to the needle through tissue with an instrument, with the ability to remove the needle from the clip with the same instrument. The present invention may allow a surgeon to single handedly insert and close the clip to connect tissue using a minimum amount of instruments.

[0022] The present invention involves improvements

to devices for connecting tissues or tissue(s) and grafts, such as in a vascular anastomosis. The invention generally involves a surgical fastener which has an end portion that is releasably coupled to a plurality of strands that function as a release mechanism. One advantage of this release mechanism is that a needle or other piercing or penetrating member may be coupled to it to thereby releasably couple the needle, piercing member or penetrating member to the fastener.

[0023] According to one aspect of the invention, a tissue connector assembly is provided with a clip movable between an open configuration and a closed configuration, and a mechanical restraining device coupled to the clip for restraining the clip in the open configuration. The mechanical restraining device may include a coil surrounding at least a portion of the clip. The mechanical restraining device may further include a clip retainer fixed at an end portion of the clip opposite the enlarged end portion. Preferably, the clip retainer has a cross-sectional area greater than a cross-sectional area on the coil.

[0024] The coil includes a plurality of adjacent loops and is compressible with the plurality of adjacent loops being spaced closer to one another along one side of the coil than along an opposite side of the coil. Coupling of the release mechanism to the enlarged portion compresses the coil between the release mechanism and the retainer clip thereby biasing the clip in the open position.

[0025] The strands of the release mechanism may comprise substantially rigid wires. Alternatively, the strands may comprise substantially rigid cables. Each strand may include a notch for receiving part of the enlarged portion of the clip during releasable engagement.

[0026] The clip may have a generally U-shaped configuration when in the open configuration. A needle may be releasably attached to the clip to facilitate removal of the needle after insertion of the clip through the tissues/grafts. At least a portion of the mechanical restraining device may remain on the clip when the needle is released from the clip.

[0027] According to another aspect of the invention, the release mechanism of the tissue assembly may include a plurality of strands arranged in a circle and substantially parallel to one another to form a tube-like configuration, with proximal end portions of the strands being coupled to a needle. Alternatively, the proximal end portions may be coupled to a transition element which is connected to a needle by a flexible element, preferably a suture.

[0028] The distal end portions of the strands may include notches configured to receive and lock the enlarged portion of the clip within a chamber defined by the notches. A shrink wrap layer may be provided to surround at least the distal end portions of the strands, and is heat shrunk against the strands to compress the notches against the enlarged portion of the clip to more securely retain the enlarged portion. The shrink wrap layer may be a shrink tubing.

[0029] Compression of the plurality of strands in a lo-

cation between the notches and the coupled proximal end portions, deforms the chamber to enable removal of the enlarged portion from the chamber. Removal of the enlarged portion from the chamber initiates closing of the clip. The clip is in a relaxed state when in the closed configuration. The clip may assume a spiral configuration in the closed configuration.

[0030] The tissue connector assembly is provided with a clip adapted to assume an open configuration and a closed configuration and may also be provided with a release mechanism comprising a plurality of strands releasably coupled to the clip, and a needle coupled to the release mechanism.

[0031] The tissue connector assembly is provided with a clip adapted to assume an open configuration and a closed configuration and a coil coupled to the clip and may also be provided with a release mechanism comprising a plurality of strands releasably coupled to the clip. The coil of this aspect biases the clip in the open configuration when the release mechanism is coupled to the clip.

[0032] The tissue connector assembly is provided with a surgical clip having a relaxed state, and may also be provided with a needle, a release mechanism comprising a plurality of strands releasably coupling the needle to the clip, and a biasing member associated with the surgical clip. The plurality of strands, when coupling the needle to the clip, urges the biasing member to bias the clip away from the relaxed state.

[0033] The tissue connector assembly provides a needle, a clip, and a releasing mechanism releasably connecting the needle to the clip. The releasing mechanism may also include a plurality of strands configured to surround and retain an enlarged portion of the clip, and compression of the configuration of the plurality of strands adjacent the enlarged portion distorts the configuration to release the enlarged portion.

[0034] The tissue connector assembly is provided with a clip adapted to assume an open configuration and a closed configuration and a coil coupled to the clip. The coil is adapted to provide a biasing force to bias the clip in the open configuration.

[0035] The tissue connector assembly is provided with a clip having an open configuration and a closed configuration and a restraint coupled to the clip when in the open configuration.

[0036] The tissue connector assembly is provided with a clip movable between an open configuration and a closed configuration. The clip has a spiral shaped configuration when in the closed configuration, and an open configuration in which the clip is configured to form less than a full 360 degree turn.

[0037] The tissue connector assembly is provided with a surgical clip having a relaxed state, a needle, a connector releasably coupling said needle to the clip, and a biasing member associated with the surgical clip. The connector, when coupling the needle to the clip, urges the biasing member to bias the clip away from the relaxed

state.

[0038] The tissue connector assembly is provided with a needle, a clip, and a locking device releasably connecting the needle to the clip. The locking device is movable between an open position for insertion and removal of the needle and a closed position for coupling said needle to the clip and biasing the clip in an open configuration.

[0039] The above is a brief description of some deficiencies in the prior art and advantages of the present invention. Other features, advantages, and embodiments of the invention will be apparent to those skilled in the art from the following description, accompanying drawings, and claims.

15 BRIEF DESCRIPTION OF THE DRAWINGS

[0040]

Fig. 1 is a front view of a tissue connector assembly of the present invention:

Fig. 2A shows a graft vessel connected to a target vessel with tissue connector assemblies of Fig. 1; Fig. 2B is a front view of the connected graft and target vessels of Fig. 2A, with portions broken away to show detail;

Fig. 2C is an enlarged view of the tissue connection shown in Fig. 2B:

Fig. 3A is an enlarged view of a fastener of the tissue connector assembly of Fig. 1 shown in a closed position:

Fig. 3B is a side view of the fastener of Fig. 3A:

Fig. 3C is an enlarged view of the fastener in an open position:

Fig. 3D is an enlarged view of an alternate configuration of the fastener shown in a closed position;

Fig. 3E is an enlarged view of an alternate configuration of the fastener shown in a closed position:

Fig. 3F is a side view of the fastener of Fig. 3E:

Fig. 3G is an enlarged view of an alternate configuration of the fastener shown in a closed position:

Fig. 3H is an enlarged view of an alternate configuration of the fastener shown in a closed position:

Fig. 3I is an enlarged view of an alternate configuration of the fastener shown in a closed position:

Fig. 3J is a sectional, diagrammatic view of the fastener of Fig. 3I *in situ* in an anastomosis:

Fig. 4A is a cross-sectional view of a restraining device of the tissue connector assembly of Fig. 1 in a locked position;

Fig. 4B is a cross-sectional view of the restraining device of Fig. 4A taken in the plane including line 4B--4B.

Fig. 4C is a cross-sectional view of the restraining device of Fig. 4A in an unlocked position;

Fig. 5 is a restraining device shown with an elongated member inserted into a tubular wire or tube;

Fig. 6 is a perspective view of a second embodiment of a tissue connector assembly of the present inven-

tion;

Fig. 7A is a front view of another embodiment of a tissue connector assembly of the present invention; Fig. 7B is a partial enlarged view of the assembly of Fig. 7A taken along lines 77B and 7B'-7B' ;

Fig. 7C is a partial sectional view of Fig. 7B taken along the longitudinal axis of the assembly;

Fig. 7D is a cross-sectional view of the assembly of Fig. 7B taken along line 7D-7D;

Fig. 7E is a view of the release mechanism of Figs. 7A-7D, showing application of force to move the release mechanism to an open position;

Fig. 7F is a sectional view of the release mechanism being forced into an open position with the end of the clip being released therefrom;

Fig. 8 is a perspective another embodiment of a tissue connector assembly of the present invention;

Fig. 9 shows two tissue connector assemblies of Fig. 6 in a first step for connecting a graft vessel to a target vessel;

Fig. 10 shows a second step for connecting the graft vessel to the target vessel;

Fig. 11 shows a third step for connecting the graft vessel to the target vessel ;

Fig. 12 shows an alternate method for connecting the graft vessel to the target vessel with the tissue connector assemblies of Fig. 6;

Figs. 13A-13D diagrammatically illustrate a method of aligning and connecting graft and target vessels with the tissue connector assemblies of Figs. 7A and 14, where Fig. 13A shows two such tissue connector assemblies threaded through a graft and target vessel, Fig. 13B shows a further step in connecting the graft and target vessel with the tissue connector assembly fastener is positioned in the target vessel, Fig. 13C shows yet a further step where the graft has been brought into position over the opening formed in the target vessel and the tissue connector assembly fastener positioned through the walls of the graft and target vessel and Fig. 13D shows the fasteners released from the tissue connector assemblies of Figs. 7A and 14 and securing the graft and target vessel together with additional laterally disposed fasteners;

Fig. 13E is a partial sectional view of the graft and target vessels with the tissue connector assembly fasteners of Fig. 14 in place prior to placement of additional lateral fasteners;

Fig. 13F is an enlarged view of the tissue connection within line 13F of Fig. 13E; and

Fig. 14 is a perspective of a tissue connector assembly, constructed with a connector in accordance with the principles of the present invention, for use in a preferred method of anastomosis.

[0041] Corresponding reference characters indicate corresponding parts throughout the several views of the drawings.

BEST MODE FOR CARRYING OUT THE INVENTION

[0042] The present invention generally involves devices for manipulating, aligning and/or connecting tissues, tissue and prosthesis, tissue and graft, or any combination thereof. As used herein, the term graft includes any of the following: homografts, xenografts, allografts, alloplastic materials, and combinations of the foregoing. Tissue connector assemblies are disclosed, which, for example, may be used in vascular surgery to replace or bypass a diseased, occluded, or injured artery by connecting a graft vessel to a coronary artery or vein in an anastomosis. Assemblies constructed in accordance with the invention may be used in open surgical procedures or in minimally invasive or Assemblies constructed in accordance with the invention may be used in open surgical procedures or in minimally invasive or endoscopic procedures for attaching tissue located in the chest, abdominal cavity, or retroperitoneal space. It should be understood, however, that these examples are provided for illustration and are not intended to limit the scope of the invention.

[0043] Tissue connecting assemblies and methods are disclosed in copending U.S. Patent Application Serial No. 09/089,884 entitled Tissue Connector Apparatus and Methods and having a filing date of June 3, 1998.

[0044] Referring now to the drawings, and first to Fig. 1, a tissue connector assembly constructed according to the principles of the present invention is shown and generally indicated with reference numeral 1. The tissue connector assembly 1 may be used to manipulate and align tissues, or tissue and graft with respect to each other and thereafter connect the tissues together (Figs. 2A-2C). As used herein, the term graft includes any of the following: homografts, xenografts, allografts, alloplastic materials, and combinations of the foregoing. The tissue connector assembly 1 may be used in vascular surgery to replace or bypass a diseased, occluded, or injured artery by connecting a graft vessel 12 to a coronary artery 14 or vein in an anastomosis, for example. The tissue connector assembly 1 may be used in open surgical procedures or in minimally invasive or endoscopic procedures for attaching tissue located in the chest, abdominal cavity, or retroperitoneal space. These examples, however, are provided for illustration and are not meant to be limiting.

[0045] In the embodiment shown in Fig. 1, the tissue connector assembly 1 generally comprises a penetrating member 2, and fastener or surgical clip 10 (Fig. 1). A restraining device, generally indicated at 8 and comprising a spring (or coil) 26 and a locking device generally indicated at 4, is connected to the fastener 10 for holding the fastener in a deformed configuration as further described below.

[0046] The penetrating member or needle 2 has a sharp pointed tip 30 at its distal end for penetrating tissue. The needle 2 may be bent as shown in Fig. 1, for example. The distal end of the needle 2 is preferably rigid to facilitate penetration of tissue. The remaining length of the

needle 2 may be rigid or flexible to facilitate movement of the needle through the tissue as further described below. The tip 30 of the needle 2 may be conical, tapered, or grounded to attain a three or four facet tip, for example. The needle 2 may be made from stainless steel or any other suitable material, such as a polymeric material. It is to be understood that the needle 2 may have a shape or radius of curvature other than the one shown, without departing from the scope of the invention. The needle 2 may be integrally formed with the locking device 4 or may be swaged, welded, threadably attached, or attached by any other suitable means to the locking device.

[0047] As shown in Fig. 3A, one embodiment of a fastener 10 comprises a deformable wire 34 made of a shape memory alloy. A nickel titanium (Nitinol) based alloy may be used, for example. The Nitinol may include additional elements which affect the yield strength of the material or the temperature at which particular pseudoelastic or shape transformation characteristics occur. The transformation temperature may be defined as the temperature at which a shape memory alloy finishes transforming from martensite to austenite upon heating (i.e., A_f temperature). The shape memory alloy preferably exhibits pseudoelastic (superelastic) behavior when deformed at a temperature slightly above its transformation temperature. At least a portion of the shape memory alloy is converted from its austenitic phase to its martensitic phase when the wire is in its deformed configuration. As the stress is removed, the material undergoes a martensitic to austenitic conversion and springs back to its original undeformed configuration. When the wire 34 is positioned within the tissue in its undeformed configuration, a residual stress is present to maintain the tissue tightly together (Fig. 2C). In order for the pseudoelastic wire 34 to retain sufficient compression force in its undeformed configuration, the wire should not be stressed past its yield point in its deformed configuration to allow complete recovery of the wire to its undeformed configuration. The shape memory alloy is preferably selected with a transformation temperature suitable for use with a stopped heart condition where cold cardioplegia has been injected for temporary paralysis of the heart tissue (e.g., temperatures as low as 8-10 degrees Celsius).

[0048] It is to be understood that the shape memory alloy may also be heat activated, or a combination of heat activation and pseudoelastic properties may be used, as is well known by those skilled in the art.

[0049] The cross-sectional diameter of the wire 34 and length of the wire will vary depending on the specific application. The diameter "d" of the wire 34 may be, for example, between 0.00254 and 0.0381 cm (0.001 and 0.015 inch). For coronary bypass applications the diameter is preferably between 0.00254 and 0.02032 cm (0.001 and 0.008 inch) with a diameter "D" of the loop being between 0.03175 and 0.22225 cm (0.0125 and 0.0875 inch) (Fig. 3A). The diameter "D" of the loop of the fastener 10 in its closed position is preferably sized to prevent movement between adjacent tissues. As

shown in Fig. 3A, the wire 34 has a circular cross-sectional shape. It is to be understood that the wire may have other cross-sectional shapes such as rectangular, or may be formed from multiple strands without departing from the scope of the invention.

[0050] The proximal end of the wire 34 may include a stop 36 having a cross-sectional area greater than the cross-sectional area of the wire and coil 26 to prevent the wire and coil from passing through the tissue (Fig. 3C). The stop 36 may be attached to the end of the wire 34 by welding, gluing or other suitable attachment means or may be formed integrally with the wire by deforming the end of the wire. The stop 36 may also be eliminated to facilitate pulling the fastener completely through the tissue, if, for example, the entire fastener needs to be removed from the vessel during the insertion procedure. The distal end of the wire 34 includes an enlarged portion 38 for engagement with the restraining device 8 as further described below (Fig. 4A). The enlarged portion 38 may be formed by deforming the end of the wire 34 by swaging or arc welding, or attaching by welding, swaging, or other suitable means to form an enlarged portion at the end of the wire.

[0051] The wire 34 has an undeformed or closed position (state or configuration) (Fig. 3A) for keeping or connecting tissue together, and a deformed or open position (state or configuration) (Fig. 3C) for insertion of the wire into tissue. The wire 34 is preferably not deformed past its yield point in its open position. Accordingly, it may have a U-shaped configuration in its open position to facilitate insertion of the wire 34 through the tissue. It is to be understood that a U-shaped configuration may be alternatively substituted by an equivalent structure such as C-shaped, V-shaped, J-shaped, and other similarly shaped configurations. The wire 34 is moved from its closed position to its open position by the restraining device 8, as further described below. When in its closed position, the wire 34 forms a loop with the ends of the wire in a generally side-by-side or overlapping orientation (Fig. 3B).

[0052] The wire 34 may be formed in the above described shape by first wrapping the wire onto a mandrel and heat treating the wire at approximately 400-500 degrees Celsius for approximately 5 to 30 minutes. The wire 34 is then air quenched at room temperature. The mandrel may have a constant diameter or may be conical in shape.

[0053] An alternate configuration of the surgical clip 10 in its closed position is shown in Fig. 3D, and generally indicated at 40. The fastener 40 forms a spiral configuration in its closed position for trapping tissue within a loop formed by the spiral. In its open position, the fastener 40 is configured to form less than a full 360 degree turn.

[0054] Another alternate configuration of the surgical clip 10 is shown in Figs. 3E and 3F in its closed position, and is generally indicated at 41. The fastener 41 is formed in a spiral about a central longitudinal axis A. As shown in Fig. 3F, the fastener 41 has a generally conical shape

along the longitudinal axis A, with a decreasing diameter as the radius of curvature of the fastener 41 decreases. The fastener 41 has an inner end portion 45 and an outer end portion 47 with the enlarged portion 38 of the wire being disposed at the outer end portion for engagement with the restraining device 8 (Fig. 3E).

[0055] A modification of the fastener is shown in Fig. 3G, and generally indicated at 43. The fastener 43 is same as the fastener 41 described above, except that the enlarged portion 38, which is adapted for engaging a restraining device or releasable mechanism, is positioned at the inner end portion 45 of the fastener. Placement of the restraining device 8 at the inner end portion 45 of the fastener 43 increases the compression force of the wire in its undeformed position on the tissue and decreases the surface area of the fastener exposed to blood flow. Additionally, one or both ends of the fastener may extend in a substantially straight direction from the curved form of the wire 34, as shown in Figure 3H. In this embodiment, the curved portion of the fastener is essentially the same configuration as that shown in Figure 3G. Additionally, extensions 36' and 38' extend in substantially straight directions from where the members 36 and 38 would be located in the embodiment of Figure 3G. The extensions 36' and 38' preferably extend for a length equal to about two to three times the outside diameter of the coil 26 or about 0.0254 to 0.0508 cm (.010 to .020 inches). These extensions allow the release mechanisms to operate more efficiently and also render the fastener easier to manufacture. It is noted that this embodiment may include only one extension 36' or 38' for use with single needle embodiment such as shown in Figures 1, 4, 6, 7A and 8, for example. However, the single needle embodiments are not limited to only one extension, and may employ a two extension fastener configuration as well.

[0056] For example, this fastener design may be embodied by an 8-0 clip size (wire 34), having a cross-sectional thickness of about 0.0889 cm (0.035 inches) which, in the closed configuration shown, forms an inner loop having a diameter D_1 of about 0.04318 cm (0.017 inches) and an outer loop inner dimension D_2 of about 0.05334 cm (0.021 inches). In the open configuration the clip forms a U-shape with a depth of the U-shape being about 0.8mm (0.032 inches).

[0057] Figure 3I shows an embodiment with two extensions 36' and 38' and which further includes a stopper 37, preferably slideably mounted onto the wire 34 in the vicinity of the transition from a curved wire portion, to the relatively straight extension 38'. The stopper 37 is between discrete springs 26 and 26' and held in place thereby. This embodiment is particularly advantageous for anastomosing a relatively thin-walled vessel 14 to a relatively thick-walled vessel 15 (e.g. the aorta or other large vessel), where an extension acts to prevent the relatively thin-walled vessel from sliding into the anastomosis site and out of the preferred position where it is to be fixed, as is illustrated in Figure 3J.

[0058] For example, this fastener design may be embodied by a 6-0 clip size (wire 34) having a cross-sectional thickness of about 0.1143 cm (0.045 inches) which, in the closed configuration shown, forms an inner loop having a diameter D_1 of about 0.1524 cm (0.060 inches) and an outer loop inner dimension D_2 of about 0.1651 cm (0.065 inches). In the open configuration the clip forms a U-shape with a depth of the U-shape being about 1.5 to 2 mm (0.070 - 0.090 inches).

[0059] It is to be understood that the fasteners may have undeformed or deformed configurations different than those shown herein without departing from the scope of the invention. In addition, a locking clip (not shown) may also be attached to connect the ends of the fastener when the fastener is in its closed position to prevent possible opening of the fastener over time. The locking clip may also be integrally formed with one end of the fastener.

[0060] As shown in Fig. 3C, the wire 34 is surrounded by the spring or coil 26 which along with the locking device 4, restrains the wire in its deformed configuration. The coil 26 comprises a helical wire forming a plurality of loops which define a longitudinal opening 44 for receiving the shape memory alloy wire 34. The coil 26 may be formed from a platinum alloy wire having a cross-sectional diameter of approximately 0.0005-0.005 inch, for example. The wire may have other cross-sectional shapes and be formed of different materials. The coil 26 is preferably sized so that when in its free (uncompressed state) it extends the length of the wire 34 with one end adjacent the stop 36 at the proximal end of the wire and the other end adjacent the enlarged portion 38 at the distal end of the wire (Fig. 3B). It is to be understood that the spring 26 may not extend the full length of the wire. For example, a flange or similar device may be provided on an intermediate portion of the wire 34 to limit movement of the coil along the length of the wire.

[0061] When the coil 26 is in its free state (with the wire 34 in its undeformed configuration), loops of the coil are generally spaced from one another and do not exert any significant force on the wire 34 (Fig. 3A). When the coil 26 is compressed (with the wire 34 in its deformed configuration), loops of the coil on the inner portion 46 of the coil are squeezed together with a tight pitch so that the loops are near or contiguous with one another while loops on the outer portion 48 of the coil are spaced from one another (Fig. 3C). This is due to the compressed inner arc length of the coil 26 and the expanded outer arc length of the coil. The compression of the loops on the inner portion 46 of the coil 26 exerts a force on the inner side of the wire 34 which forces the wire to spread open (i.e., tends to straighten the wire from its closed configuration to its open configuration). The end of the coil 26 adjacent the stop 36 is held in a fixed position relative to the wire 34. The opposite end of the coil 26 is free to move along the wire 34 and is held in place when the coil is in its compressed position by the locking device 4 (Fig. 4A).

[0062] The locking device 4 shown in Figs. 1 and 4A-

4C comprises a flexible tubular member 50 having a distal end portion 52 coupled to a needle 2 and a proximal end portion 54 releasably attached to the wire 34. The tubular member 50 is movable between a locked position (Fig. 4A) for holding the coil 26 in its compressed position and the wire 34 in its deformed position, and an unlocked position (Fig. 4C) for inserting or releasing the wire and coil. Three slots 58 are formed in the tubular member 50 extending from the proximal end 54 of the member and along at least a portion of the member (Figs. 4B and 4C). The slots 58 are provided to allow the proximal end 54 of the tubular member 50 to open for insertion and removal of the wire 34 when the tubular member is in its unlocked position (Fig. 4C). It is to be understood that the number of slots 58 and configuration of the slots may vary.

[0063] The proximal end 54 of the tubular member 50 includes a bore 62 having a diameter slightly greater than the outer diameter d of the wire 34, but smaller than the diameter of the enlarged portion 38, and smaller than the outer diameter of the coil 26. The bore 62 extends into a cavity 64 sized for receiving the enlarged portion 38 of the wire 34. Member 50 may be described as having an annular flange 61 for releasably securing the enlarged portion 38. As shown in Fig. 4C, upon application of an inwardly directed radial squeezing force on the tubular member 50 the proximal end 54 of the tubular member is opened to allow for insertion or removal of the wire 34. When the force is released (Fig. 4A), the tubular member 50 moves back to its locked position and securely holds the wire 34 in place and compresses the coil 26. A disc 51 may be inserted into the tubular member 50 to act as a fulcrum and cause the proximal end 54 of the tubular member to open upon application of force on the tubular member. Alternatively, the disc 51 may be integrally formed with the tubular member 50. As shown in Fig. 4A, the length ℓ of the bore 62 or flange 61 determines the amount of compression of the coil, which in turn determines the amount of deformation of the wire 34. The greater the length ℓ of the bore 62, the greater the compression of the coil 26 and the more straightening the wire 34 will undergo. The compression of the coil 26 is preferably limited so that the wire 34 is not stressed beyond its yield point. This allows the wire 34 to revert back to its original undeformed configuration and apply sufficient pressure to hold the connected tissue together.

[0064] A restraining device is shown in Fig. 5, and is generally indicated with reference numeral 70. The restraining device 70 is used with a tubular (hollow) shape memory alloy wire or tube 72 and comprises an elongated member (or mandrel) 74 sized for insertion into the wire. The mandrel 74 is preferably formed from a material which is stiffer than the material of the wire 72 so that upon insertion of the mandrel into the wire, the wire is deformed into its open position. The restraining device 70 includes a stop 76 located at the proximal end of the wire 72. The stop operates to prevent the fastener from being pulled through the tissue, and limits axial move-

ment of the mandrel 74 in the proximal direction (to the right as viewed in Fig. 5). The distal end of the mandrel 74 is releasably attached to the needle 2.

[0065] It is to be understood that locking devices other than those described above may be used without departing from the scope of the invention. For example, a locking device (not shown) may comprise a tubular member having an opening formed in a sidewall thereof for receiving an end portion of the wire. The end of the wire may be bent so that it is biased to fit within the opening in the sidewall of the tubular member. An instrument, such as a needle holder may then be used to push the wire away from the opening in the tubular member and release the wire from the tubular member. Various other types of locking devices including a spring detent or bayonet type of device may also be used.

[0066] Another embodiment of the tissue connector assembly is shown in Fig. 6 and generally indicated with reference numeral 110. The tissue connector assembly 110 is similar to the tissue connector assembly 1 of the first embodiment, except that a flexible member 118 is inserted between a restraining device 124 and needle 116. Fig. 6 shows the tissue connector assembly 110 with a fastener 120 in an open (deformed) position. The fastener 120 may be the same as the fasteners 10, 40, 41, 43 described above and shown in Figs. 4A-4C, except that the distal end is configured for attachment to the flexible member 118.

[0067] The flexible member 118 is attached to the distal end of the locking device 128 with a tapered portion or transition sleeve 156 extending from the locking device to the flexible member 118 to facilitate insertion of the locking device through tissue. The tapered sleeve 156 is preferably sufficiently curved to facilitate movement of the tissue connector assembly 110 through connecting tissue in an anastomosis, for example. The sleeve 156 may be formed from a metal alloy such as stainless steel or a suitable polymeric material. The needle 116 may be swaged into the sleeve 156, or a heat shrink plastic covering may hold the needle in place. The locking device 128 may also be curved.

[0068] The flexible member 118 may be in the form of a suture formed from conventional filament material, metal alloy such as Nitinol, polymeric material, or any other suitable material. The material may be non-stretchable or stretchable, solid or hollow, and have various cross-sectional diameters. The suture may have a cross-sectional diameter of 0.00762cm (003 inch) for example. The diameter and length of the suture will vary depending on the specific application. The suture may be attached to the needle 116 by crimping or swaging the needle onto the suture, gluing the suture to the needle, or any other suitable attachment method. The flexible member 118 may have cross-sectional shapes other than the one shown herein.

[0069] The needle 116 may be integrally formed with the flexible member 118. The diameter of at least a portion of the needle 116 is preferably greater than the di-

ameter of the flexible member 118 so that the flexible member can easily be pulled through an opening formed in the tissue by the needle.

[0070] Another embodiment of the tissue connector assembly is shown in Fig. 7A and generally indicated with reference numeral 21. The tissue connector assembly 21 may be used to manipulate and align tissues, or tissue and graft with respect to each other and thereafter connect the tissues together in the same manner as that shown, e.g., in Figs. 2A-2C. The tissue connector assembly 21 may be used in vascular surgery to replace or bypass a diseased, occluded, or injured artery by connecting a graft vessel 12 to a coronary artery 14 or vein in an anastomosis, for example. The tissue connector assembly 21 may be used in open surgical procedures or in minimally invasive or endoscopic procedures for attaching tissue located in the chest, abdominal cavity, or retroperitoneal space. These examples, however, are provided for illustration and are not meant to be limiting.

[0071] In the embodiment shown in Fig. 7A, the tissue connector assembly 21 generally comprises a penetrating member 102, and fastener or surgical clip 210. A restraining device, generally indicated at 108 and comprising a spring (or coil) 126 and a locking device or release mechanism generally indicated at 104, is connected to the fastener 210 for holding the fastener in a deformed configuration as further described below.

[0072] The penetrating member or needle 102 has a sharp pointed tip 30 at its distal end for penetrating tissue. The needle 102 may be bent as shown in Fig. 7A, for example. The distal end of the needle 102 is preferably rigid to facilitate penetration of tissue. The remaining length of the needle 102 may be rigid or flexible to facilitate movement of the needle through the tissue as further described below. The tip 30 of the needle 102 may be conical, tapered, or grounded to attain a three or four facet tip, for example. The needle 102 may be made from stainless steel or any other suitable material, such as a polymeric material. It is to be understood that the needle 102 may have a shape or radius of curvature other than the one shown, without departing from the scope of the invention.

[0073] The locking device or release mechanism 104 shown in Figs. 7B-7F comprises a plurality of substantially rigid strands, preferably wires 106, arranged substantially parallel to one another and circularly about a longitudinal axis of the aligned strands, to form a tube-like configuration, as can be seen in the cross-section view of Fig. 7D and the perspective view in Fig. 7B. Alternatively, strands 106 may be cables or some other substantially rigid strand elements arranged in the same manner as the wires shown in Figure 7D. Upon arrangement into the circular configuration, the proximal portions 106a of the strands are coupled to a needle 102 or transition sleeve 156 (similar to the arrangement shown in Fig. 6) extending from the releasing mechanism to a flexible member to facilitate insertion of the releasing mechanism through tissue.

[0074] Preferably, a rod 162 extends from the needle or transition element to facilitate fixation of the strands. The coupling of the strands to the needle or transition element is preferably accomplished by gluing or soldering to the rod 162, although other equivalent or similar known joining techniques may be employed (e.g. welding, threadably attaching, etc). Similarly, the rod 162 is preferably glued, soldered or threaded into the needle or transition element.

[0075] The distal portions 106b of the strands contain notches 109 which are formed into the strands to a depth equal to approximately half the diameter of the strand 106. When the strands are arranged in the circular configuration described above, the notches 109 form a chamber 109' for receiving and holding a proximal end of the clip which is preferably an enlarged ball 136, but may be of an enlarged barrel shape, or other shape that may be easily grasped and easily released. The notches are preferably placed about 0.0381 cm (0.15") from the distal ends of the strands, but this distance, of course, can be modified, depending upon the amount of compression of the spring 126 that is desired when the ball 136 is inserted into and held by notches 109.

[0076] After placement of the ball 136 within the chamber formed by the notches 109, a shrink wrap layer, preferably a shrink tubing 2110 is provided over at least the distal portions 106b of the wires or strands 106, and the tubing is heated to compress against the strands 106 and hold them in place, preferably symmetrically against the ball 136. Together, the tubing 2110 and strands 106 effectively hold the ball 136 captive within the notches 109. Alternative plastic or elastic restraining members, such as various types of springs, for example, may be mounted around the distal portions of the wires or strands to aid in maintaining them in place, preferably symmetrically against the ball 136. Still further, strand members may be designed with an elastic spring force sufficient to maintain the notches in place with sufficient force to maintain the ball 136 captive in the notches 109 under the tensile forces normally experienced during a suturing procedure. Although a seven strand embodiment is illustrated in the accompanying figures, it should be understood that fewer or more than seven strands may be used. The number of strands may vary depending on, for example, the size of the clip as well as the cross-sectional size of the strands. Typically, the number of strands may range from two to ten. For use in coronary anastomosis, the number of strands preferably will range from five to seven, although other numbers may be used.

[0077] In assembling, enlarged portion 136 of wire 134 is placed in chamber 109'. Tubing 110 is wrapped around at least a portion of the strands (as shown in the drawings) and heated to maintain enlarged portion 136 captive within the cavity formed by the strands. Compression coil or spring 126 is slid over wire 134 and compressed against portions 106b such that the fastener is in its open configuration. Enlarged portion 138 may then be formed or attached to wire 134 to maintain the fastener in its open

configuration.

[0078] The release mechanism 104 is movable between a locked position (Figs. 7A-7D) and an unlocked position (Figs. 7E-7F). In the locked position the ball 136 is held within the notches 109 and consequently, the coil 126 is held in its compressed position, thereby maintaining the clip 134 in its deformed or open position. In the unlocked position, the ball 136 is released from the notches, thereby allowing the coil 126 to expand, which causes the clip 134 to close. The closure conformation of the clip may be characterized by any of those described above and shown in Figs. 2C-3G, for example.

[0079] Movement of the release mechanism to the open position is accomplished by applying a compressive force to the shrink tube 2110 and bundle of strands 106, as shown in Figs. 7E and 7F. Advantageously, the compressive force may be applied at any opposing locations around the circumference of the shrink tube as long as the implement applying the force is oriented at an angle to the strands, preferably substantially perpendicular thereto, to allow the implement to traverse the strands so as to deform the positions thereof when the force is applied. For example, the needle holder 144 could be rotated 90° (or virtually any other angle) with respect to the strands 106 as shown in the plane of the drawing, while retaining the capability of deforming the strands to an open position upon application of a compressive force. The compressive force is preferably applied using a standard needle holder 144 or forceps, although other tools could be used, preferably those with applicators narrower than the length of the shrink tube 2110. As shown, the strands or wires 106 get distorted from their circular configuration under the compression. This change in shape stretches the shrink tube 2110 from a circular configuration to a somewhat elliptical configuration, and removes some of the notches 109 from contact with the ball 136, as shown in Fig. 7E. thereby permitting removal of the ball 136 from within the chamber previously formed by notches 109 in the closed position.

[0080] The retainer 138 has a cross-sectional area less than or equal to the cross-sectional area of the coil 126, but greater than the inside diameter of the coil 126 to prevent the wire from passing through the coil. The retainer 138 may be attached to the end of the wire 134 by welding, gluing or other suitable attachment means or may be formed integrally with the wire by deforming the end of the wire, but it is preferably crimped thereon, as described above. Thus, the dimensions of the retainer 138 facilitate pulling the fastener completely through the tissue, if, for example, the entire fastener needs to be removed from the vessel during the insertion procedure. The distal end of the wire 134 includes an enlarged portion 136 for engagement with the restraining device 108 as further described below. The enlarged portion 136 may be formed by deforming the end of the wire 134 by swaging or arc welding, or attaching by welding, swaging, or other suitable means to form an enlarged portion at the end of the wire.

[0081] The wire 134 has an undeformed or closed position (state or configuration) for keeping or connecting tissue together, and a deformed or open position (state or configuration) for insertion of the wire into tissue. The wire 134 is preferably not deformed past its yield point in its open position. Accordingly, it may have a U-shaped configuration in its open position to facilitate insertion of the wire 134 through the tissue. It is to be understood that a U-shaped configuration may be alternatively substituted by an equivalent structure such as C-shaped, V-shaped, J-shaped, and other similarly shaped configurations. The wire 134 is moved from its closed position to its open position by the restraining device 108, as further described below. When in its closed position, the wire 134 forms a loop with the ends of the wire in a generally side-by-side or overlapping orientation.

[0082] The wire 134 may be formed in the above described shape in a manner similar to that described above with regard to wire 34.

[0083] It is to be understood that the fasteners may have undeformed or deformed configurations different than those shown herein without departing from the scope of the invention. In addition, a locking clip (not shown) may also be attached to connect the ends of the fastener 210, 40, 41, 43, 43', 43". 120 when the fastener is in its closed position to prevent possible opening of the fastener over time. The locking clip may also be integrally formed with one end of the fastener.

[0084] Another embodiment of the tissue connector assembly is shown in Fig. 8 and generally indicated with reference numeral 310. The tissue connector assembly 310 is similar to the tissue connector assembly 21. except that a flexible member 318 is inserted between a restraining device 108 and needle 316. Fig. 8 shows the tissue connector assembly 310 with a fastener 210 in an open (deformed) position. The fastener 210 may also be substituted by any of the fasteners 40, 41, 43, 43', 43", 120 described above and shown in Figs. 3A-3G for the previously described tissue connector assembly embodiments, for example.

[0085] As noted above, the tissue connector assemblies 1, 21, 110, 310 of this invention have many uses. They may be especially useful in minimally invasive surgical procedures including creating an anastomosis between a vascular graft 12 and an artery 14 (Figs. 2A-2C). The anastomosis may be used to replace or bypass a diseased, occluded or injured artery. A coronary bypass graft procedure requires that a source of arterial blood flow be prepared for subsequent bypass connection to a diseased artery. An arterial graft may be used to provide a source of blood flow, or a free graft may be used and connected at the proximal end to a source of blood flow. Preferably, the source of blood flow is one of any number of existing arteries which may be dissected in preparation for the bypass graft procedure. In many instances it is preferred to use the left internal mammary artery (LIMA) or the right internal mammary artery (RIMA), for example. Other vessels which may be used include the saphenous

vein, gastroepiploic artery in the abdomen, radial artery, and other arteries harvested from the patient's body as well as synthetic graft materials, such as DACRON® or GORETEX® (expanded polytetrafluoroethylene). If a free graft vessel is used, the upstream end of the dissected vessel, which is the arterial blood source, will be secured to the aorta to provide the desired bypass blood flow, as is well known by those skilled in the art. The downstream end of the graft vessel is trimmed for attachment to an artery, such as the left anterior descending coronary (1.AD). It is to be understood that the anastomosis may be formed in other vessels or tissue.

[0086] Figures 2A-2C and 9-11 show an exemplary use of the tissue connector assemblies 1, 21, 110, 310 for connecting a graft vessel 12 to an artery 14 (target vessel). In this example, two tissue connector assemblies 110 (Fig. 6) are used to make connections at generally opposite sides of the graft vessel and a plurality of tissue connector assemblies 1 (Fig. 1) are used to make connections between those made with tissue connector assemblies 110. One or more tissue connector assemblies 310 can be substituted for a like number of tissue assemblies 110 and/or one or more tissue assemblies 21 can be substituted for a like number of tissue connector assemblies 1. The procedure may be accomplished with a beating heart procedure with the use of a heart stabilizer to keep the heart stable, for example. The procedure may also be performed endoscopically.

[0087] The patient is first prepped for standard cardiac surgery. After exposure and control of artery 14, occlusion and reperfusion may be performed as required, an arteriotomy is performed on artery 14 to provide an opening 121 for receiving a graft vessel. Referring to Figs. 9-11, after the arteriotomy of the snared graft vessel 12 has been made to the appropriate length, as would be apparent to one of ordinary skill in the art, a tissue connector assembly 110,310 is attached to the free end of the graft vessel along an edge margin of the vessel. In order to attach the connector assembly 110,310, the surgeon grasps the needle 116,316 with a needle holder (e.g., surgical pliers, forceps, or any other suitable instrument) and inserts the needle 116,316 into an end margin of the graft vessel 12 in a direction from the exterior of the vessel to the interior of the vessel. The surgeon then releases the needle 116,316 and grasps a forward end of the needle which is now located inside the graft vessel 12 and pulls the needle and a portion of the suture 118,318 through the vessel. The needle 116,316 is passed through an opening 121 formed in the sidewall of the artery 14 and inserted into the tissue of the artery in a direction from the interior of the artery to the exterior of the artery. The surgeon then grasps the needle 116,316 located outside the artery 14 and pulls the needle and a portion of the suture 118,318 through the arterial wall. A second tissue connector assembly 110,310 may be inserted at a location generally 180 degrees from the location of the first tissue connector in a conventional "heel and toe" arrangement. Alternatively, a number of

tissue connectors 110,310 may be inserted generally around the location of the heel. The graft vessel 12 may then be pulled towards the artery 14 to determine whether the opening 121 formed in the sidewall of the artery is large enough before completing the anastomosis.

[0088] Once the tissue connector assemblies 110,310 are inserted, the graft vessel 12 is positioned above the opening 121 in the sidewall of the artery 14 (Fig. 9). The fasteners 120,210 and needles 116,316 are pulled generally away from the artery 14 to reduce the length of the suture 118,318 between the vessel 12 and artery and "parachute" the vessel onto the artery (Fig. 10). The needles 316 are then pulled away from the artery 14 until the fastener 120,210 is positioned within the graft vessel 12 and artery with one end of each fastener extending from the vessel and the opposite end of each fastener extending from the artery (Fig. 11). The edges of the graft vessel 12 and artery 14 are positioned adjacent one another to form a continuous interior and exterior surface along the mating portions of the vessel and artery. As shown in Fig. 2C, the tissue is compressed within the fastener 120,210.

[0089] A surgical instrument (e.g., needle holder) is used to radially squeeze each release mechanism 104/locking device 128 to release it from the fastener 210/120. Upon removal of the locking device 104,128, the coil 126 moves to its free uncompressed state which allows the wire 134 to return to its original undeformed closed position (Fig. 2A). As the wires 134 move to their closed position the adjacent tissues of the graft vessel 12 and artery 14 which were previously pulled together during the parachuting of the graft vessel onto the artery, are squeezed together to securely engage the graft vessel and artery (Figs. 2B and 2C). The edges of the graft vessel 12 and artery 14 are positioned adjacent one another to form a continuous interior and exterior surface along the mating portions of the vessel and artery. As shown in Fig. 2C, the tissue is compressed within fastener 20 where the graft and arteriotomy edges may be abutted or everted as is known in the art.

[0090] The tissue connector assemblies 1,21 are subsequently inserted at circumferentially spaced locations around the periphery of the graft vessel 12 to sealingly fasten the graft vessel to the artery 14. The needle 2,102 of the fastener 1,21 is inserted into the graft vessel 12 from the exterior surface of the graft vessel and pushed through the graft vessel and artery 14 tissue. The needle holder is then used to pull the needle 2,102 through the arterial wall. An instrument (same needle holder or other suitable instrument) is used to apply a squeezing force to the release mechanism 4,104 to release the wire 34,134 and coil 26,126 from the needle 2,102. This allows the coil 26,126 to move to its uncompressed configuration and the wire 34,134 to move to its closed position. It should be noted that the tissue connector assemblies 110,310 may remain in their open position while the tissue connector assemblies 1,21 are inserted into the tissue and moved to their closed position. The release mechanisms 4,104 of the tissue connector assemblies

110,310 may subsequently be removed from the fasteners 120,210 to allow the fasteners to move to their closed position. The number and combination of tissue connectors assemblies 1,110,21, 310 required to sealingly secure the connecting tissues together may vary. For example, only tissue connector assemblies 1 and/or 21 may be used to complete the entire anastomosis, or only tissue connector assemblies 110 and/or 310 may be used to connect tissues.

[0091] It should be noted that as the release mechanism 4,104 is squeezed two steps are accomplished. The fastener 120,210 is released from the release mechanism 4,104, thus allowing the coil 26,126 to uncompress and the wire 34,134 to move to its closed configuration, and the needle 2,102 is released from the fastener 120,210. Thus, in the embodiment shown, the release mechanism 4,104 provides for simultaneous actuating closure of the fastener 120,210 and release of the needle 2,102 from the fastener.

[0092] The graft vessel 12 may also be parachuted onto the artery 14 in the method shown in Fig. 10. The needles 116,316 are inserted into the graft vessel 12 and artery 14 as described above and the sutures 118,318 are pulled through the vessel so that the fasteners 120,210 are positioned within the vessel. The needles 116,316 are then pulled away from the artery 14 to "parachute" the graft vessel 12 onto the artery.

[0093] Figures 13A-13D diagrammatically illustrate a preferred method of aligning and connecting graft and target vessels, such as connecting a graft vessel 12 to an artery 14 (target vessel) using tissue connector assemblies 1310 as shown in Figure 14. The tissue connectors 1310 are a modification of the embodiments described above so as to include two tissue piercing or penetrating members 1316 and 1317, flexible members 1318 and 1319, and fastener or surgical clip 2310. Note also that the method described with regard to Figs. 13A-13D can also be practiced using tissue connectors having two piercing members and only one flexible member. Still further, the embodiments shown in Figure 6 and Figure 8 could be modified similarly to include two piercing members. Although these devices are not specifically shown herein, a complete description of the same, as well as the connectors having dual piercing members and flexible members, and the preferred method, can be found in copending application Serial No. 09/260,623 filed on March 1, 1999, titled "Tissue Connector Apparatus and Methods".

[0094] Connector 1310 includes restraining devices, generally indicated at 1308 and 1309 which are similar or identical to restraining device 108, and comprising a spring (or coil) 1326 and a locking device or release mechanism generally indicated at 1304 and 1305, which are similar to or the same as release mechanism 104, for holding the fastener 2310 in a deformed or open configuration as described above with regard to fastener 210. Although a particular fastener and accompanying restraining device is shown in Fig. 14, it should be under-

stood that any suitable fastener can be used for the method to be described, including but not limited to the alternate fastener configurations described above. For further example, the fastener or surgical clip may be a plastically deformable clip or may comprise two or more parts, at least one of which is movable relative to the other part, such as with a hinged clip. Further, other piercing member release mechanisms can be used with or without restraining devices depending on the fastener construction.

[0095] Each of penetrating or piercing members 1316 and 1317 may be in the form of a needle having a sharp pointed tip at its distal end for penetrating tissue. Needles 1316 and 1317 may be bent as shown in Fig. 14, for example. The diameter of at least a portion of each of needles 1316 and 1317 is preferably greater than the diameter of the respective flexible members (1318 and 1319), coupled thereto so that the flexible members can easily be pulled through an opening formed in the tissue (or other material) by the needle. The distal ends of the needles 1316 and 1317 are preferably rigid to facilitate penetration of tissue. The remaining length of the needles 1316 and 1317 may be rigid or flexible to facilitate movement of the needle through the tissue as further described below. The needle tips may have various configurations and may, for example, be conical, tapered, or grounded to attain a three or four facet tip. Needles 1316 and 1317 may be made from stainless steel or any other suitable material, such as a polymeric material. It is to be understood that the needles 1316 and 1317 may have a shape or radius of curvature other than the one shown, without departing from the scope of the invention. Needles 1316 and 1317 may also be integrally formed with the flexible member 1318 (e.g., both needle and flexible member formed of the same material.)

[0096] The flexible members 1318 and 1319 may be in the form of a suture formed from conventional filament material, metal alloy such as Nitinol, polymeric material, or any other suitable material. The material may be non-stretchable or stretchable, solid or hollow, and have various cross-sectional diameters. The flexible members or sutures may have a cross-sectional diameter of 003 inch, for example. The diameter and length of the suture will vary depending on the specific application. The sutures may be attached to the needles 1316 and 1317, respectively, by crimping or swaging the needle onto the suture, gluing the suture to the needle, or any other suitable attachment method. Flexible members 1318 and 1319 may have cross-sectional shapes other than the one shown herein.

[0097] Transition sleeves 1356 and 1357, which are similar to or the same as transition sleeve 156 described above, extend from respective releasing mechanisms 1308 and 1309 to flexible members 1318 and 1319 to facilitate insertion of the releasing mechanism through tissue.

[0098] Returning to the method in Figs. 13A-13D, two tissue connector assemblies 1310 are used to make con-

nections at generally opposite sides of the graft vessel and tissue connector assemblies 1 are used to make connections between those made with assemblies 1310. The procedure may be accomplished with a beating heart procedure with the use of a heart stabilizer to keep the heart stable, for example. The procedure may also be performed endoscopically.

[0099] The patient is first prepped for standard cardiac surgery. After exposure and control of artery 14, occlusion and reperfusion may be performed as required. An arteriotomy is performed on artery 14, as described above with regard to opening 121, to provide an opening 120 for receiving a graft vessel. After the arteriotomy of the snared graft vessel 12 has been made to the appropriate length, a tissue connector assembly 1310 is attached to the free end of the graft vessel by passing needle 1316 into the lumen of the graft and inserting the needle 1316 through the wall of the graft, along an edge margin of the vessel, from inside the lumen out through the wall. The surgeon then grasps the needle 1316 located outside the wall and pulls the needle and a portion of the suture 1318 through the graft wall. Needle 1317 is passed through the opening 120 formed in the sidewall of the artery 14 and inserted into the tissue of the artery in a direction from the interior of the artery to the exterior of the artery. The surgeon then grasps needle 1317 located outside the artery 14 and pulls the needle and a portion of suture 1319 through the arterial wall. A second tissue connector assembly 1310 may be inserted as described above at a location generally 180 degrees from the location of the first tissue connector in a conventional "heel and toe" arrangement.

[0100] Once the tissue connector assemblies 1310 are inserted, graft vessel 12 is positioned above and aligned with opening 120 in the sidewall of the artery 14 (Fig. 13A). A section of each assembly is located between graft vessel 12 and artery 14. The needles 1316 and 1317 are pulled to perform the previously described "parachuting" of the vessel onto the artery (Fig. 13B). The needles 1317 are then pulled away from the artery 14 until each fastener 2310 is positioned within the target vessel 14 as shown in Fig. 9B. Needles 1316 are then pulled away from graft 12 until the fasteners are positioned with one end of each fastener 2310 extending from the vessel and the opposite end of each fastener extending from the artery (Fig. 13C). The edges of the graft vessel 12 and artery 14 are positioned adjacent one another to form a continuous interior and exterior surface along the mating portions of the vessel and artery. As shown in Fig. 13F, the tissue is compressed within the fastener 2310.

[0101] A surgical instrument (e.g., needle holder) is used to radially squeeze each release mechanism 1304, 1305 to release the release mechanisms from the fastener 2310. Upon removal of each release mechanism each coil 1326 moves to its free uncompressed state which allows fastener wire 1334 to return to its original undeformed closed position (Fig. 13D). As the wires 1334 move to their closed position the adjacent tissues of the

graft vessel 12 and artery 14 which were previously pulled together during the parachuting of the graft vessel onto the artery, are squeezed together to securely engage the graft vessel and artery (Figs. 13E and 13F). It should be noted that as each locking device 1304, 1305 is squeezed at least two steps are accomplished. The fastener 2310 is released from locking device, thus allowing coil 1326 to uncompress and the wire 1334 to move to its closed configuration, and the needle 1316, 1317 is released from the fastener. Further, radially compression of release mechanisms 1304, 1305 releases needles 1316, 1317 and sutures 1318, 1319 from the fasteners. However, a synchronous release system described in the co-pending application no. 09/260.623 may be used, wherein radial compression of a locking device will effect essentially simultaneous closure actuation of a respective fastener and release of needles 1316 and 1317 and sutures 1318 and 1319.

[0102] The tissue connector assemblies 21 are subsequently inserted at circumferentially spaced locations around the periphery of the graft vessel to scalingly fasten graft vessel 12 to artery 14. Needle 102 of fastener 21 is inserted into graft vessel 12 from the exterior surface of the graft vessel and pushed through the graft vessel and artery 14 tissue. Of course, fasteners 1 may be employed in place of fasteners 21, as noted above with regard to earlier described procedures. The needle holder is then used to pull the needle 102 through the arterial wall. An instrument (same needle holder or other suitable instrument) is used to apply a squeezing force to the locking device 104 to release fastener 210 from needle 102. This allows coil 126 to move to its uncompressed configuration and the wire to move to its closed position. It should be noted that the tissue connector assemblies 1310 may remain with their fasteners in their open position while tissue connector assemblies 1 are inserted into the tissue and moved to their closed position. The locking devices 1304, 1305 of the tissue connector assemblies 1310 may subsequently be removed from the fasteners 2310 to allow the fasteners to move to their closed position. The number and combination of tissue connectors assemblies 1310, 1/21 required to scalingly secure the connecting tissues together may vary. For example, only tissue connector assemblies 1310 may be used to complete the entire anastomosis.

[0103] As an alternative to inserting tissue connector assemblies 1310 at "heel and toe" locations described above, a number of tissue connectors 1310 may be inserted generally around the location of the heel. The graft vessel may then be pulled towards the artery to determine whether the opening formed in the sidewall of the artery is large enough before completing the anastomosis.

[0104] Although the coil 126, 1326 is shown as remaining on the wire in each of the above-described procedures, it is to be understood that the coil 126, 1326 may also be removed from the wire 134, 1334, leaving only the wire in the connected tissue.

[0105] Although the suturing procedures have been

described for an end-to-side anastomosis, it should be appreciated that the procedures are also applicable to an end-to-end and side-to-side anastomosis, connecting various tissue structures including single and multiple tissue structures, and puncture sites, and connecting tissue to a prosthetic graft or valve for example.

[0106] It will be observed from the foregoing that the tissue connector assemblies of the present invention have numerous advantages. Importantly, the assemblies are easier and faster to apply than conventional sutures which require tying multiple knots. The assemblies may be used in minimally invasive procedures including endoscopic procedures, and may be inserted single handedly.

[0107] All references cited above are incorporated herein by reference

[0108] the above is a detailed description of a particular embodiment of the invention. It is recognized that departures from the disclosed embodiment may be made within the scope of the invention and that obvious modifications will occur to a person skilled in the art. The full scope of the invention is set out in the claims that follow and their equivalents. Accordingly, the claims and specification should not be construed to unduly narrow the full scope of protection to which the invention is entitled.

Claims

1. A tissue connector assembly (1, 21, 110, 310, 1310) comprising a clip (10, 120, 210) movable between an open configuration and a closed configuration, said clip having a mechanical restraining device (8, 108, 124, 1308, 1309) coupled to said clip for restraining said clip in said open configuration, **characterized in that:**

said mechanical restraining device comprises a coil (26, 126, 1326) surrounding at least a portion of said clip.

2. The tissue connector assembly of claim 1, wherein said mechanical restraining device further comprises a plurality of strands (106) releasably coupled to said clip.
3. The tissue connector assembly of claim 1 further comprising a needle (2, 102, 116, 316, 1316, 1317) releasably attached to said clip (10, 120, 210).
4. The tissue connector assembly of claim 3 wherein at least a portion of said mechanical restraining device (8, 108, 124, 1308, 1309) remains on said clip (10, 120, 210) when said needle (2, 102, 116, 316, 1316, 1317) is released from said clip.
5. The tissue connector assembly of claim 1 wherein said clip (10, 120, 210) comprises a wire (34, 134).

6. The tissue connector assembly of claim 5 wherein said wire (34, 134) is tubular.
7. The tissue connector assembly of claim 5 wherein said wire (34, 134) has a generally circular cross-section.
8. The tissue connector assembly of claim 5 wherein said wire (34, 134) comprises shape memory material.
9. The tissue connector assembly of claim 5 wherein said wire (34, 134) has a first end portion (136), a second end portion (36, 138) and an elongated member therebetween, said first end portion being coupled to said mechanical restraining device (8; 108, 124) and, said second end portion (36, 138) having a cross-sectional area greater than a cross-sectional area of said elongated member.
10. The tissue connector assembly of claim 1 wherein said clip (10, 120, 210) is in a relaxed state when in said closed configuration.
11. The tissue connector assembly of claim 1 wherein said clip (10, 120, 210) assumes a spiral configuration in said closed configuration.
12. The tissue connector assembly of claim 1 wherein said coil (26, 126, 1326) comprises a plurality of adjacent loops, said coil being compressible with said plurality of adjacent loops being spaced closer to one another along one side (46) of said coil than along an opposite side (48) of said coil.
13. The tissue connector assembly of claim 1 wherein said mechanical restraining device (8, 108, 124, 1308, 1309) includes a lock (4, 128, 1304, 1305) releasably engaging said coil (26, 126, 1326), wherein engagement of said lock with said coil biases said clip (10, 120, 210) in said open configuration.

Patentansprüche

1. Gewebeverbindungs Vorrichtung (1, 21, 110, 310, 1310), die eine Klemme (10, 120, 210) umfasst, die zwischen einer offenen Konfiguration und einer geschlossenen Konfiguration bewegbar ist, wobei die Klemme eine mechanische Haltevorrichtung (8, 108, 124, 1308, 1309) umfasst, die mit der Klemme zum Halten der Klemme in der offenen Konfiguration gekoppelt ist, **dadurch gekennzeichnet, dass** die mechanische Haltevorrichtung eine Wendel (26, 126, 1326) umfasst, die mindestens einen Abschnitt der Klemme umgibt.
2. Gewebeverbindungs Vorrichtung nach Anspruch 1,

wobei die mechanische Haltevorrichtung ferner eine Mehrzahl von Strängen (106) umfasst, die lösbar mit der Klemme gekoppelt sind.

3. Gewebeverbindungs-
vorrichtung nach Anspruch 1,
die ferner eine Nadel (2, 102, 116, 316, 1316, 1317)
umfasst, die lösbar an der Klemme (10, 120, 210)
angebracht ist. 5
4. Gewebeverbindungs-
vorrichtung nach Anspruch 3,
bei der mindestens ein Abschnitt der mechanischen
Haltevorrichtung (8, 108, 124, 1308, 1309) an der
Klemme (10, 120, 210) verbleibt, wenn die Nadel (2,
102, 116, 316, 1316, 1317) von der Klemme gelöst
wird. 10
5. Gewebeverbindungs-
vorrichtung nach Anspruch 1,
bei der die Klemme (10, 120, 210) einen Draht (34,
134) umfasst. 15
6. Gewebeverbindungs-
vorrichtung nach Anspruch 5,
bei welcher der Draht (34, 134) röhrenförmig ist. 20
7. Gewebeverbindungs-
vorrichtung nach Anspruch 5,
bei welcher der Draht (34, 134) einen im Allgemeinen
kreisförmigen Querschnitt aufweist. 25
8. Gewebeverbindungs-
vorrichtung nach Anspruch 5,
bei welcher der Draht (34, 134) ein Formgedächtnis-
material umfasst. 30
9. Gewebeverbindungs-
vorrichtung nach Anspruch 5,
bei welcher der Draht (34, 134) einen ersten Endab-
schnitt (136), einen zweiten Endabschnitt (36, 138)
und ein längliches Element dazwischen aufweist,
wobei der erste Endabschnitt mit der mechanischen
Haltevorrichtung (8, 108, 124) verbunden ist und der
zweite Endabschnitt (36, 138) eine Querschnittsflä-
che aufweist, die größer ist als eine Querschnittsflä-
che des länglichen Elements. 35
10. Gewebeverbindungs-
vorrichtung nach Anspruch 1,
bei der die Klemme (10, 120, 210) in einem ent-
spannten Zustand vorliegt, wenn sie in der geschlos-
senen Konfiguration vorliegt. 40
11. Gewebeverbindungs-
vorrichtung nach Anspruch 1,
bei der die Klemme (10, 120, 210) in der geschlos-
senen Konfiguration eine Spiralkonfiguration ein-
nimmt. 45
12. Gewebeverbindungs-
vorrichtung nach Anspruch 1,
bei der die Wendel (26, 126, 1326) eine Mehrzahl
von angrenzenden Schleifen umfasst, wobei die
Wendel zusammendrückbar ist, wobei die Mehrzahl
von angrenzenden Schleifen entlang einer Seite (46)
der Wendel näher beieinander liegt als entlang einer
gegenüber liegenden Seite (48) der Wendel. 50

13. Gewebeverbindungs-
vorrichtung nach Anspruch 1,
bei der die mechanische Haltevorrichtung (8, 108,
124, 1308, 1309) eine Sperreinrichtung (4, 128,
1304, 1305) umfasst, welche die Wendel (26, 126,
1326) lösbar in Eingriff nimmt, wobei das Ineingriff-
nehmen der Wendel durch die Sperreinrichtung die
Klemme (10, 120, 210) in der offenen Konfiguration
verspannt.

Revendications

1. Ensemble pour la jonction de tissus (1, 21, 110, 310,
1310) comprenant une pince (10, 120, 210) mobile
entre une configuration ouverte et une configuration
fermée, ladite pince ayant un dispositif de retenue
mécanique (8, 108, 124, 1308, 1309) couplé à ladite
pince pour retenir ladite pince dans ladite configura-
tion ouverte, **caractérisé en ce que** :

ledit dispositif de retenue mécanique comprend
un boudinage (26, 126, 1326) entourant au
moins une portion de ladite pince.
2. Ensemble pour la jonction de tissus selon la reven-
dication 1, dans lequel ledit dispositif de retenue mé-
canique comprend en outre une pluralité de brins
(106) couplés de façon libérable à ladite pince.
3. Ensemble pour la jonction de tissus selon la reven-
dication 1, comprenant en outre une aiguille (2, 102,
116, 316, 1316, 1317) attachée de manière libérable
à ladite pince (10, 120, 210).
4. Ensemble pour la jonction de tissus selon la reven-
dication 3, dans lequel une portion au moins dudit
dispositif de retenue mécanique (8, 108, 124, 1308,
1309) reste sur ladite pince (10, 120, 210) quand
ladite aiguille (2, 102, 116, 316, 1316, 1317) est libé-
rée depuis ladite pince.
5. Ensemble pour la jonction de tissus selon la reven-
dication 1, dans lequel ladite pince (10, 120, 210)
comprend un fil (34, 134).
6. Ensemble pour la jonction de tissus selon la reven-
dication 5, dans lequel ledit fil (34, 134) est tubulaire.
7. Ensemble pour la jonction de tissus selon la reven-
dication 5, dans lequel ledit fil (34, 134) a une section
transversale généralement circulaire.
8. Ensemble pour la jonction de tissus selon la reven-
dication 5, dans lequel ledit fil (34, 134) comprend
un matériau à mémoire de forme.
9. Ensemble pour la jonction de tissus selon la reven-
dication 5, dans lequel ledit fil (34, 134) a une pre-

mière portion terminale (136), une seconde portion terminale (138), et un élément allongé entre elles, ladite première portion terminale étant couplée audit dispositif de retenue mécanique (8, 108, 124), et ladite seconde portion terminale (36, 138) ayant une aire de section transversale supérieure à une aire de section transversale dudit élément allongé. 5

10. Ensemble pour la jonction de tissus selon la revendication 1, dans lequel ladite pince (10, 120, 210) est dans un état relâché lorsqu'elle est dans ladite configuration fermée. 10
11. Ensemble pour la jonction de tissus selon la revendication 1, dans lequel ladite pince (10, 120, 210) adopte une configuration spiralée dans ladite configuration fermée. 15
12. Ensemble pour la jonction de tissus selon la revendication 1, dans lequel ledit boudinage (26, 126, 1326) comprend une pluralité de boucles adjacentes, ledit boudinage étant compressible de sorte que ladite pluralité de boucles adjacentes soient espacées plus proche les unes des autres le long d'un côté (46) dudit boudinage que le long d'un côté opposé (48) dudit boudinage. 20 25
13. Ensemble pour la jonction de tissus selon la revendication 1, dans lequel ledit dispositif de retenue mécanique (8, 108, 124, 1308, 1309) inclut un verrou (4, 128, 1304, 1305) qui engage ledit boudinage (26, 126, 1326) de manière libérable, et l'engagement dudit verrou avec ledit boudinage force ladite pince (10, 120, 210) dans ladite configuration ouverte. 30 35

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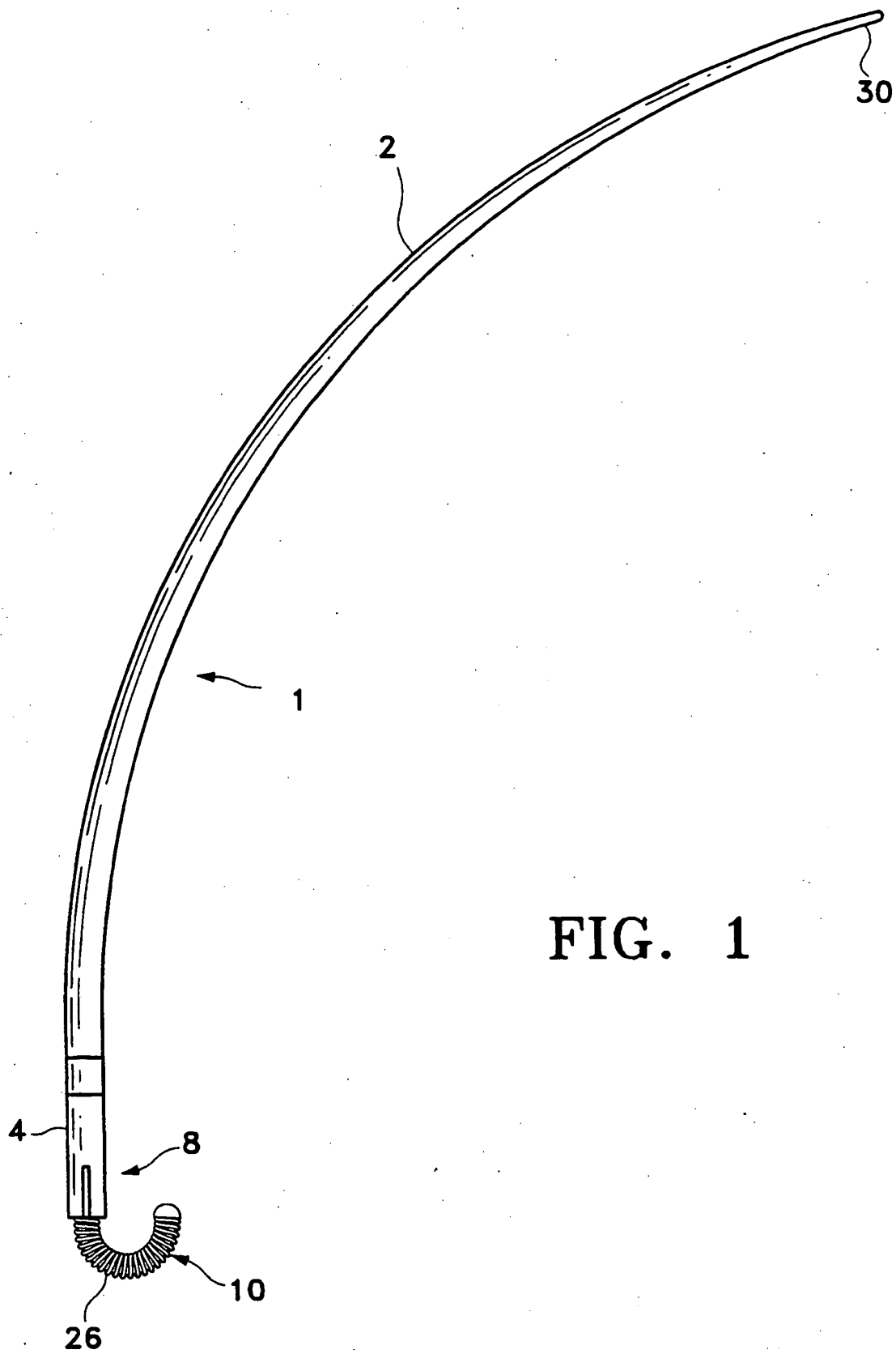


FIG. 1

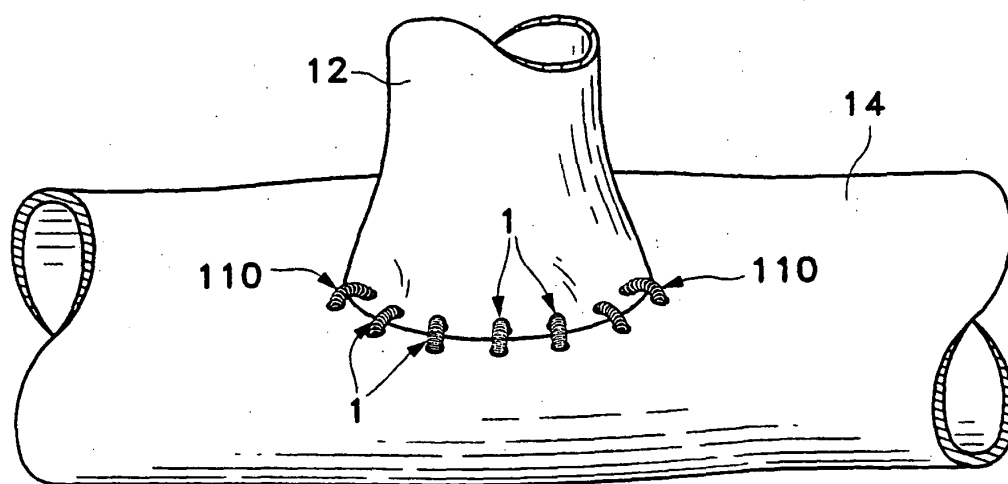


FIG. 2A

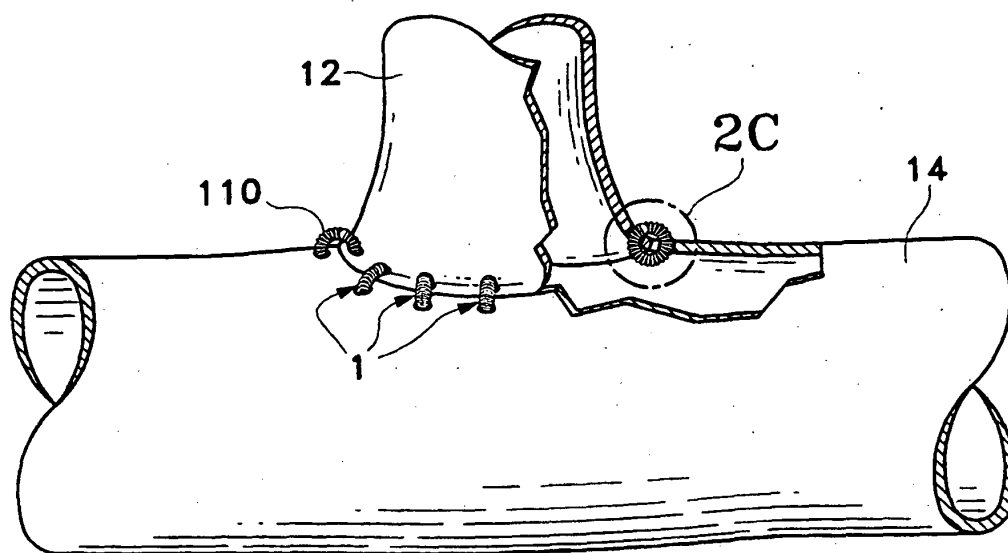


FIG. 2B

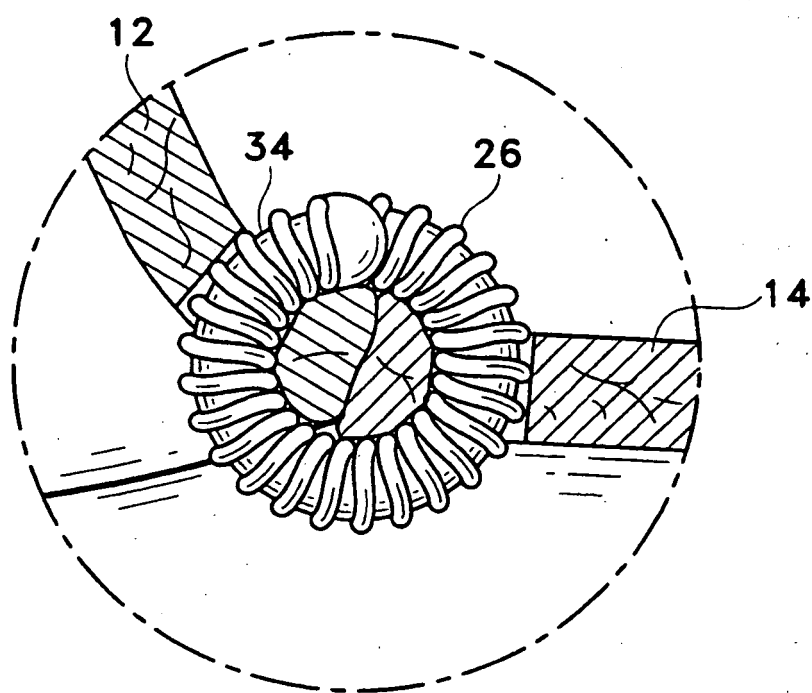


FIG. 2C

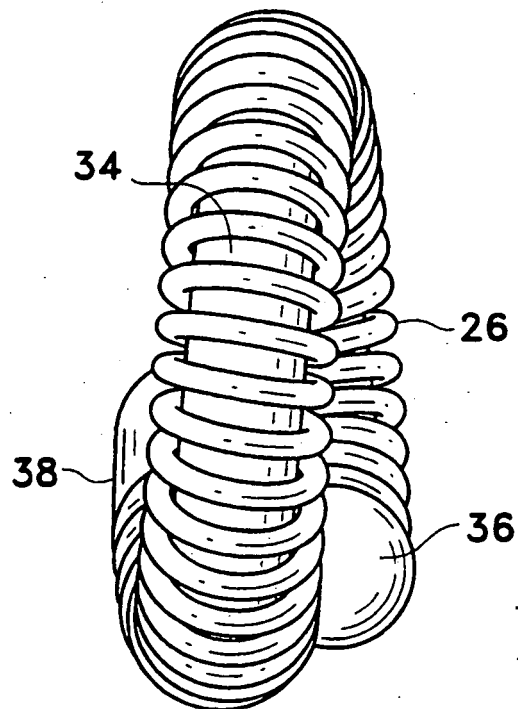
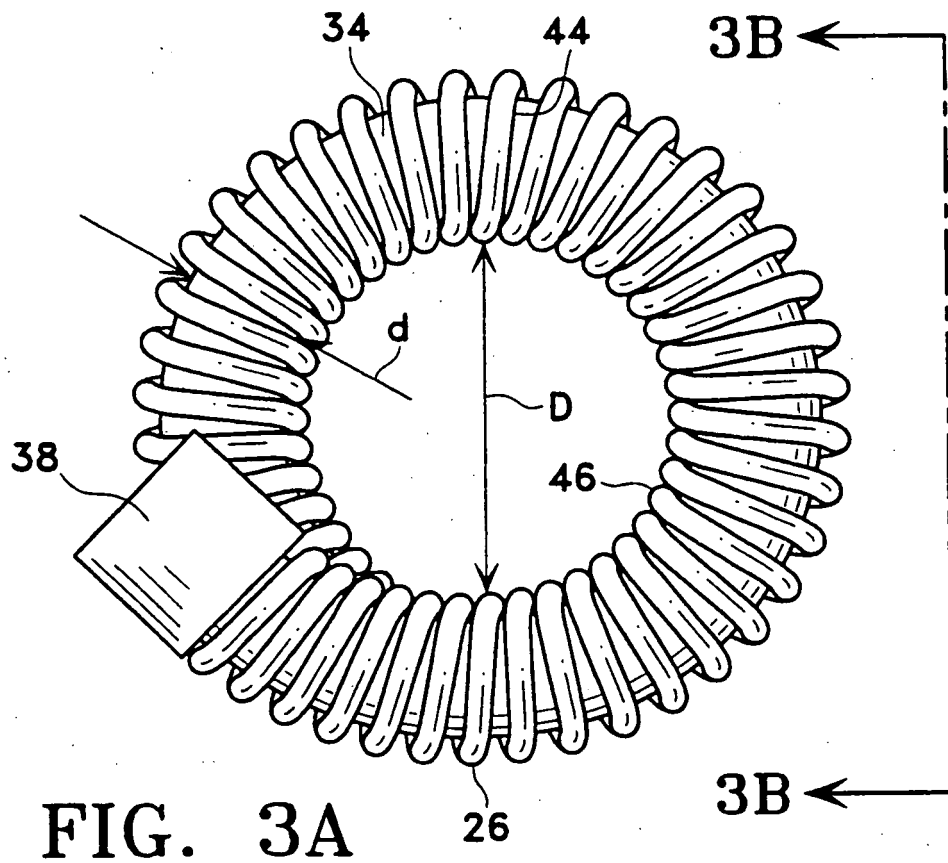


FIG. 3B

FIG. 3C

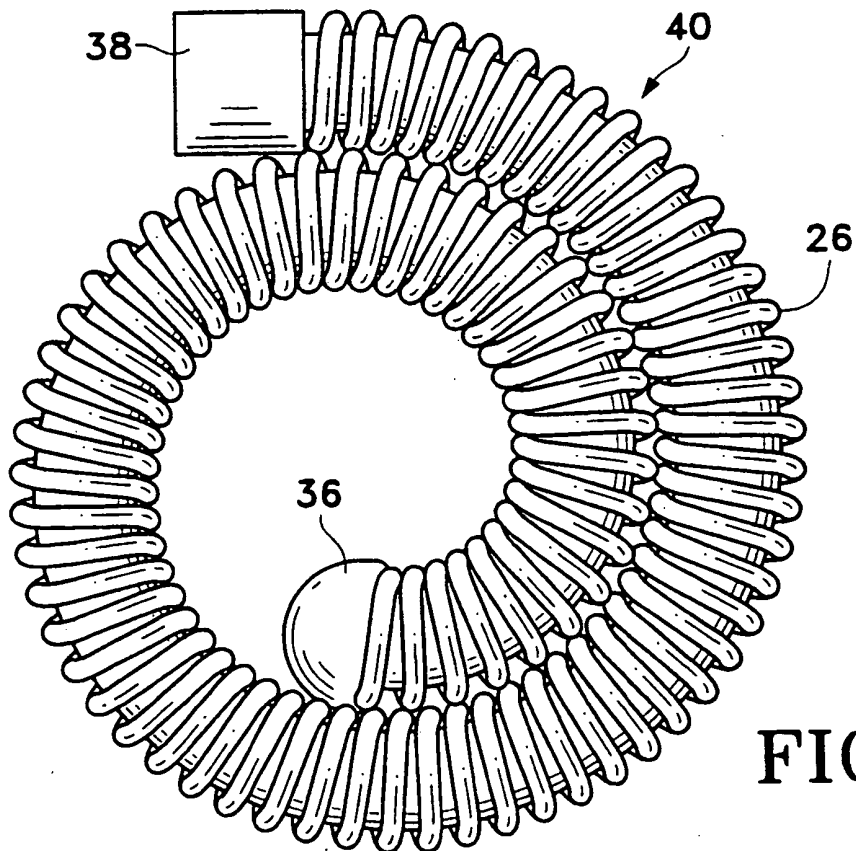
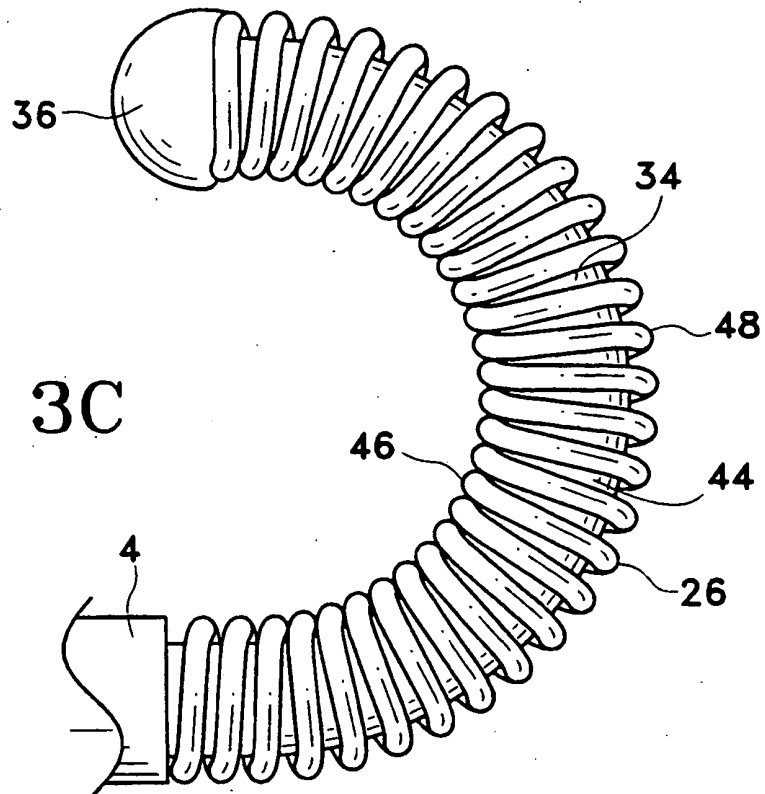


FIG. 3D

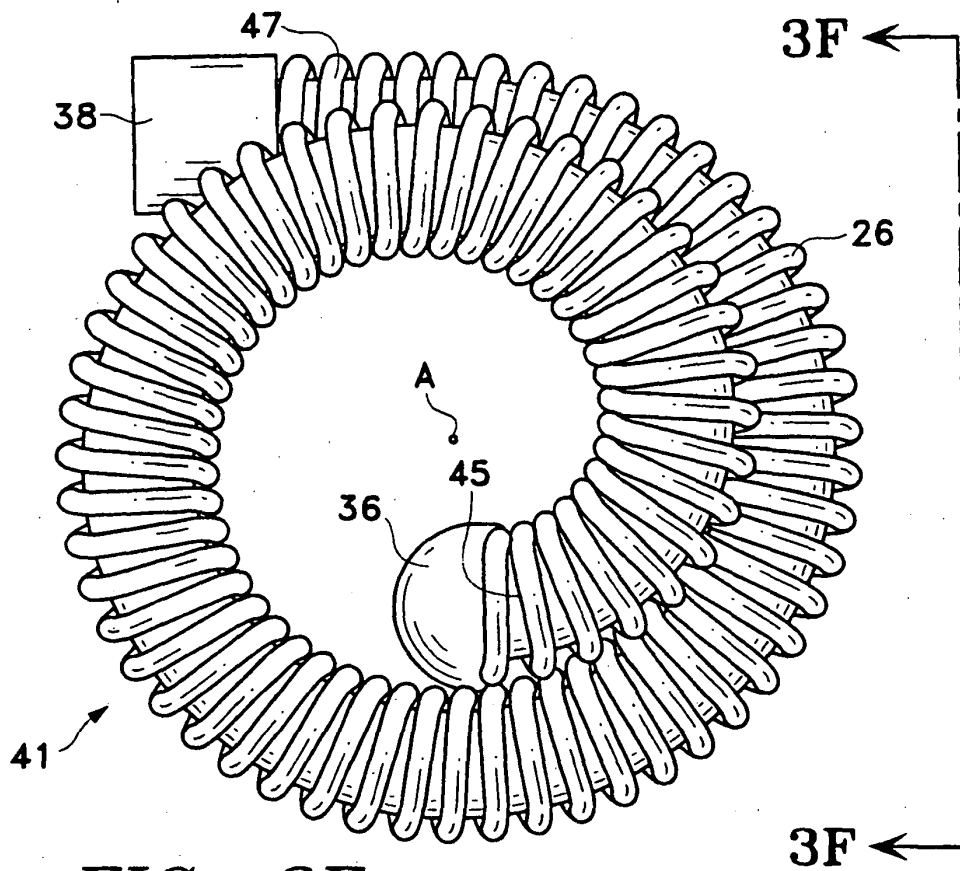


FIG. 3E

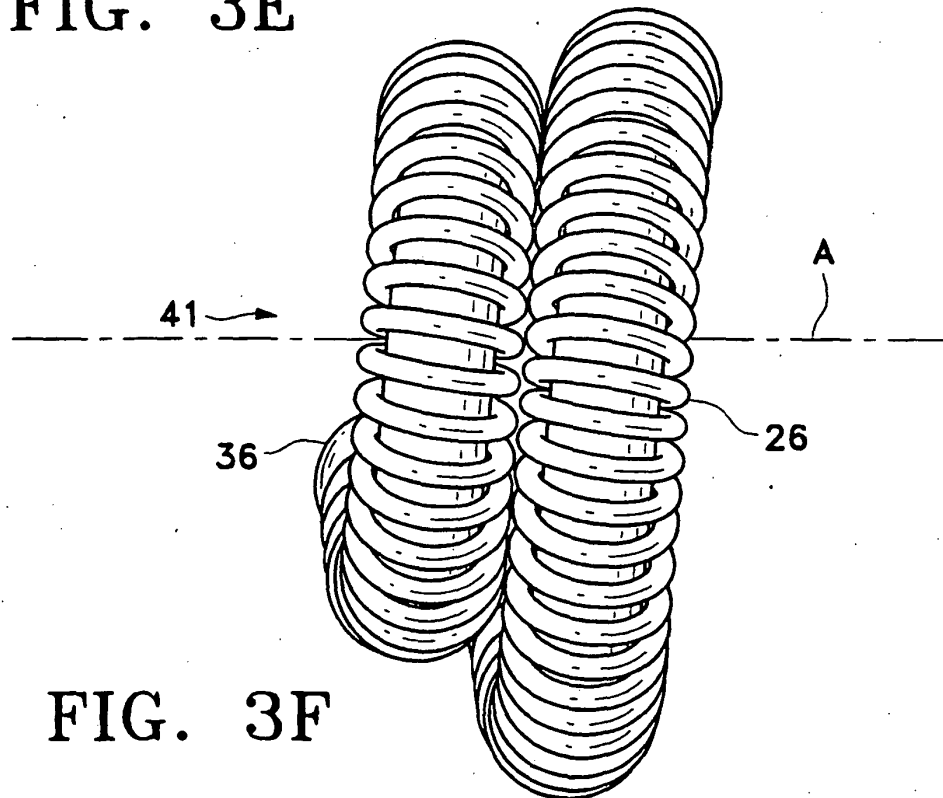


FIG. 3F

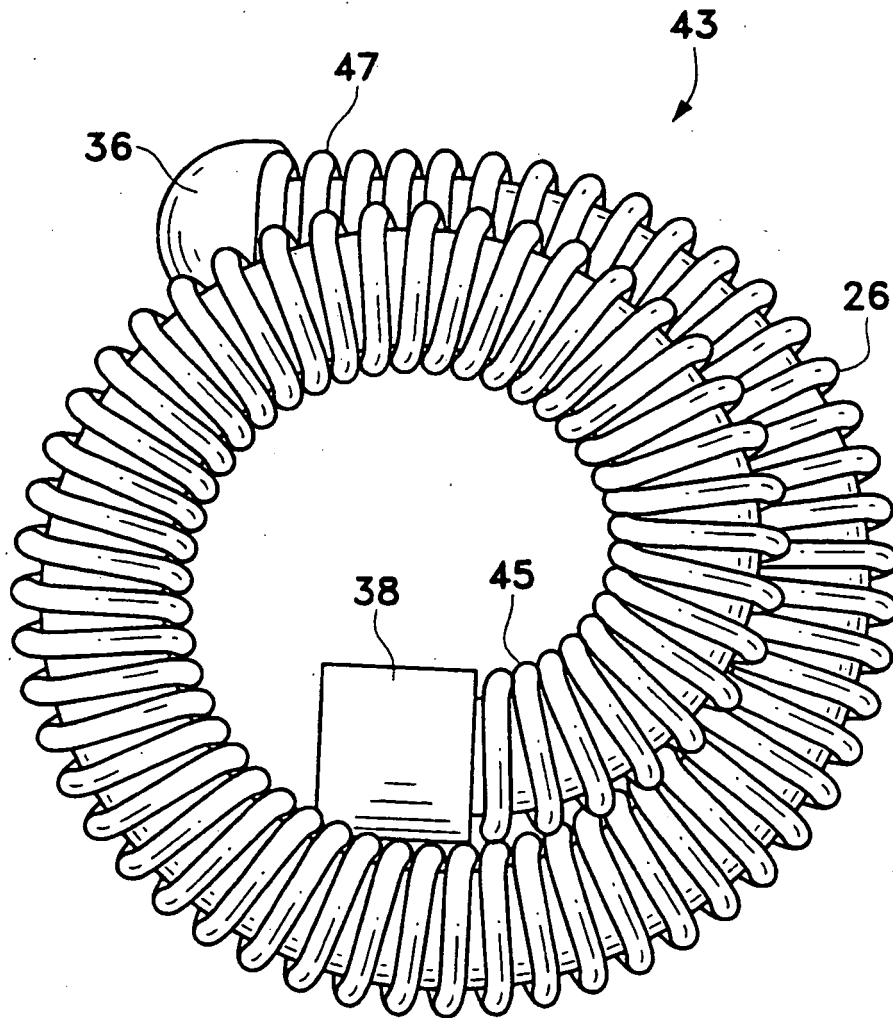


FIG. 3G

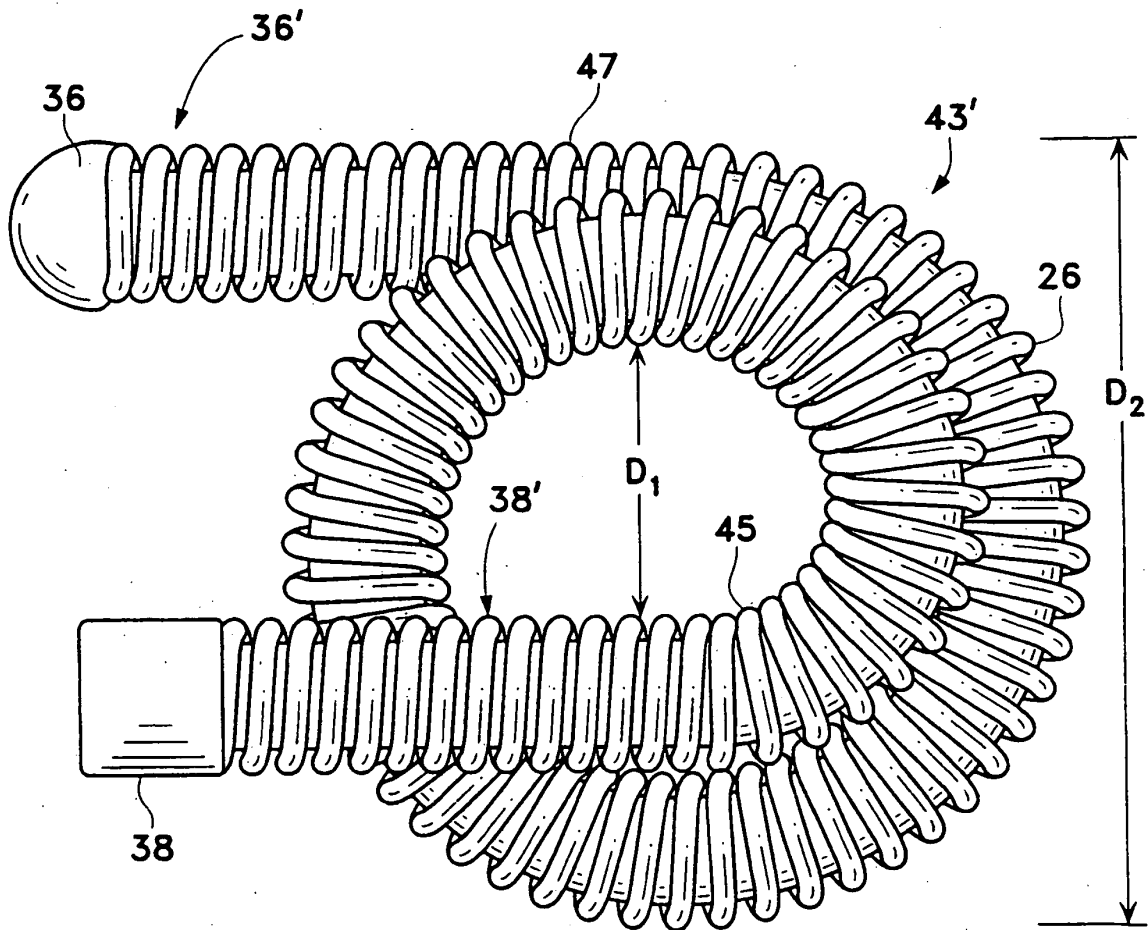


FIG. 3H

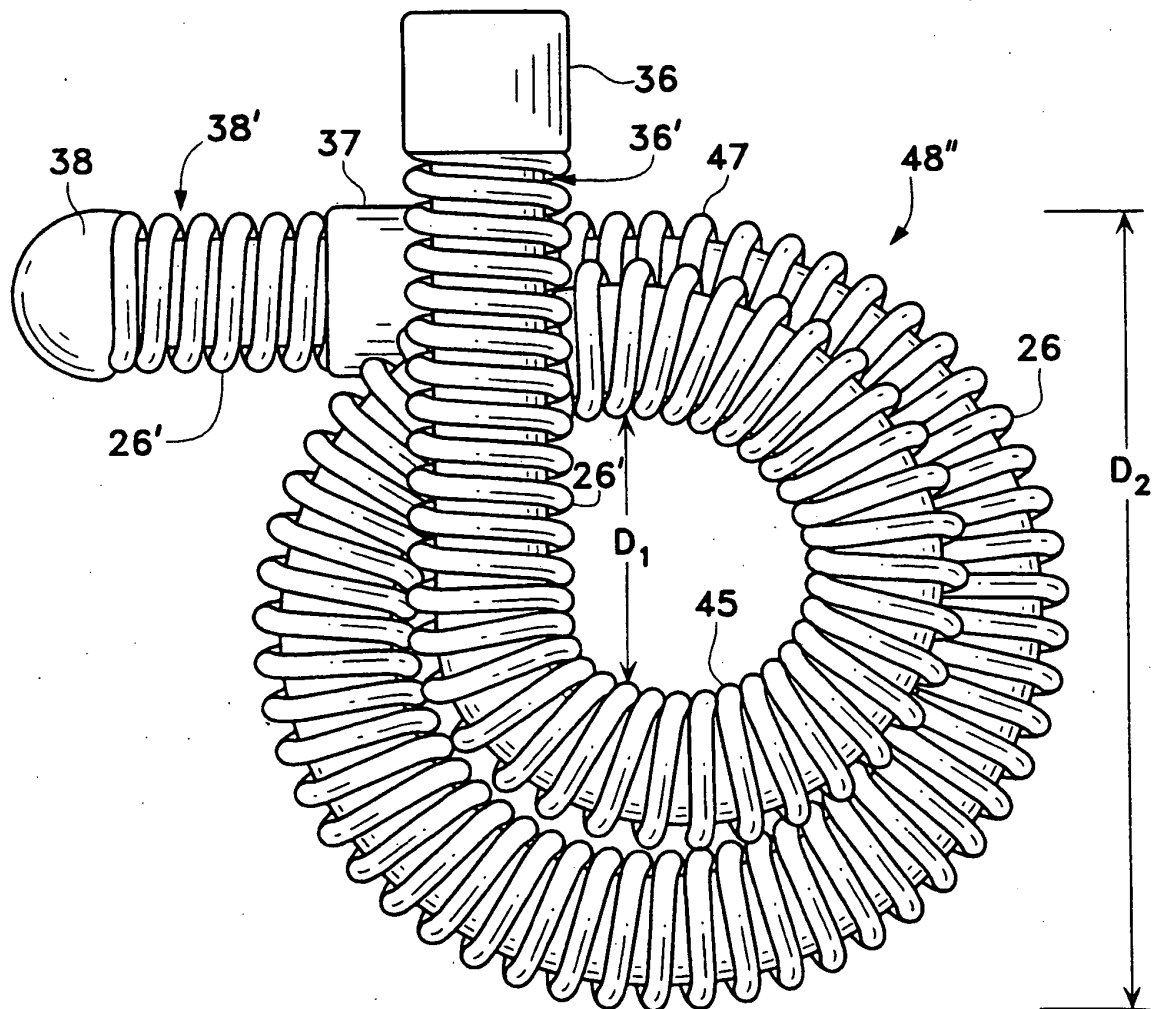


FIG. 3I

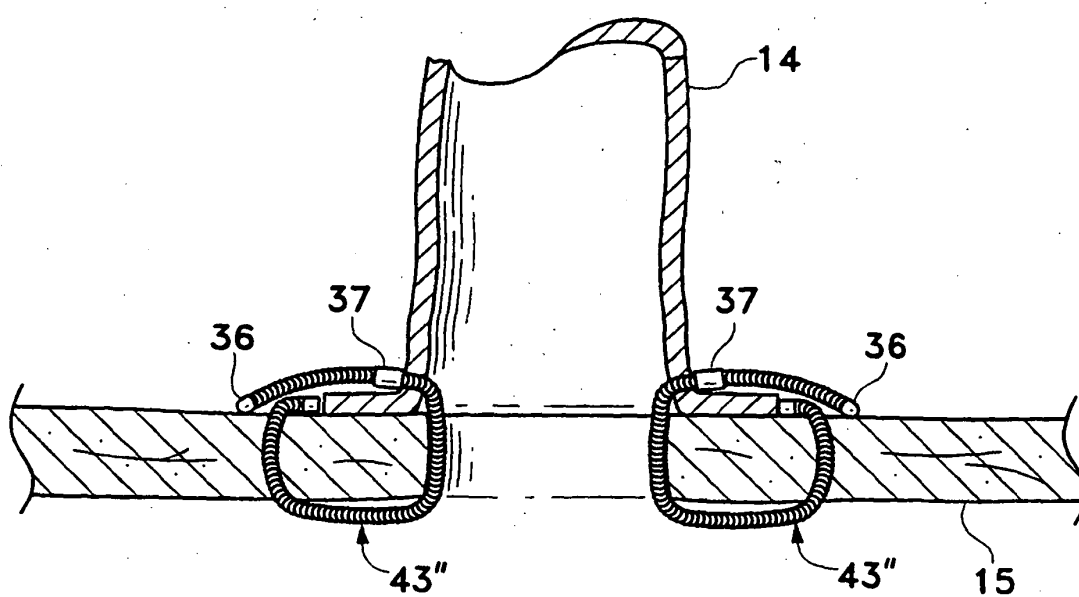
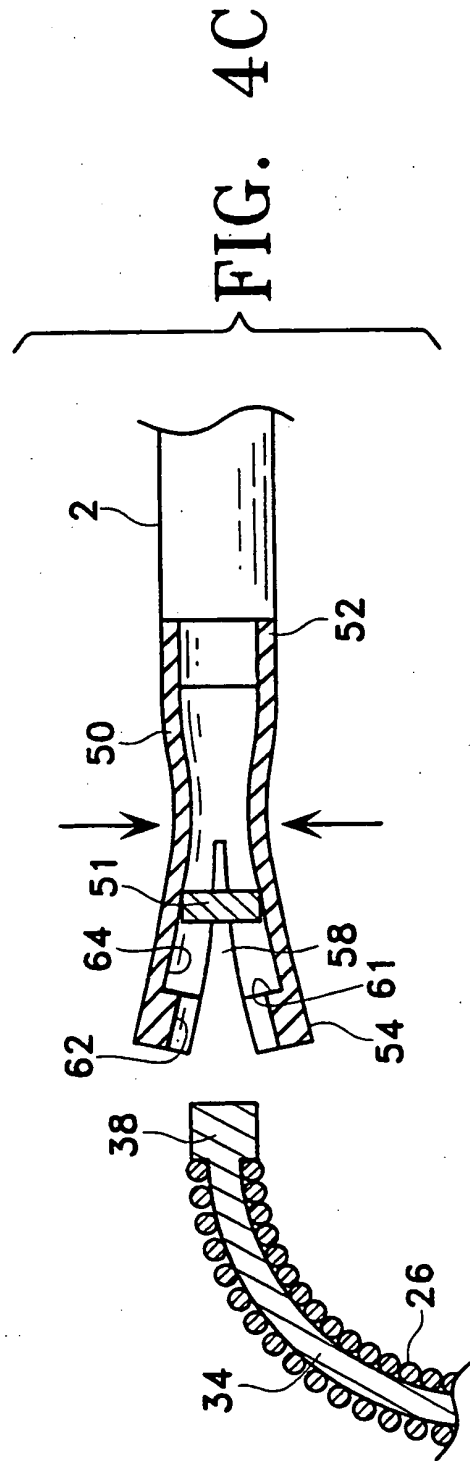
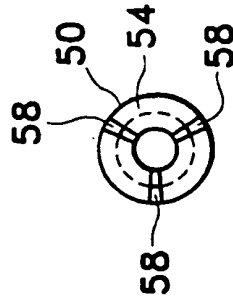
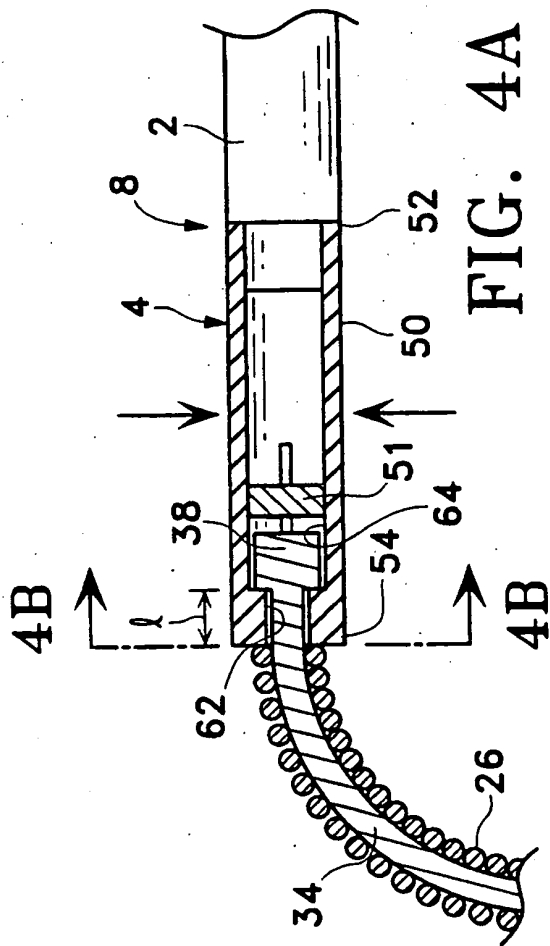


FIG. 3J



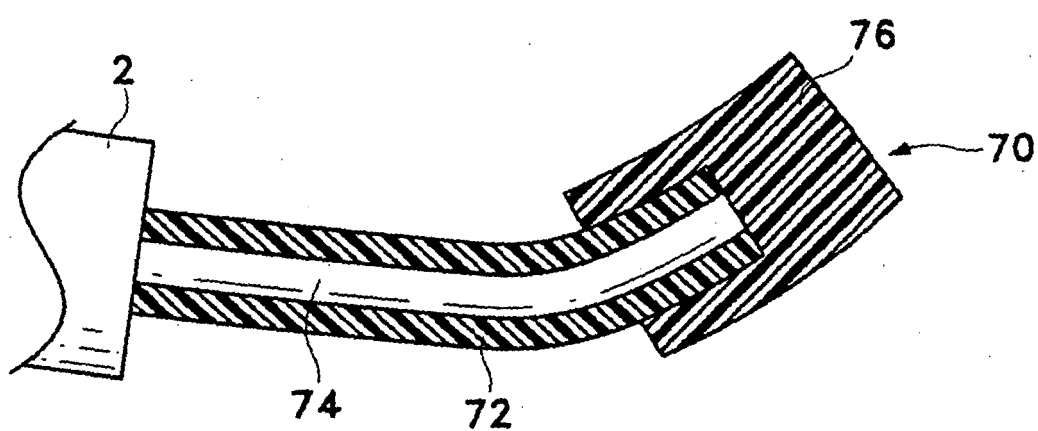
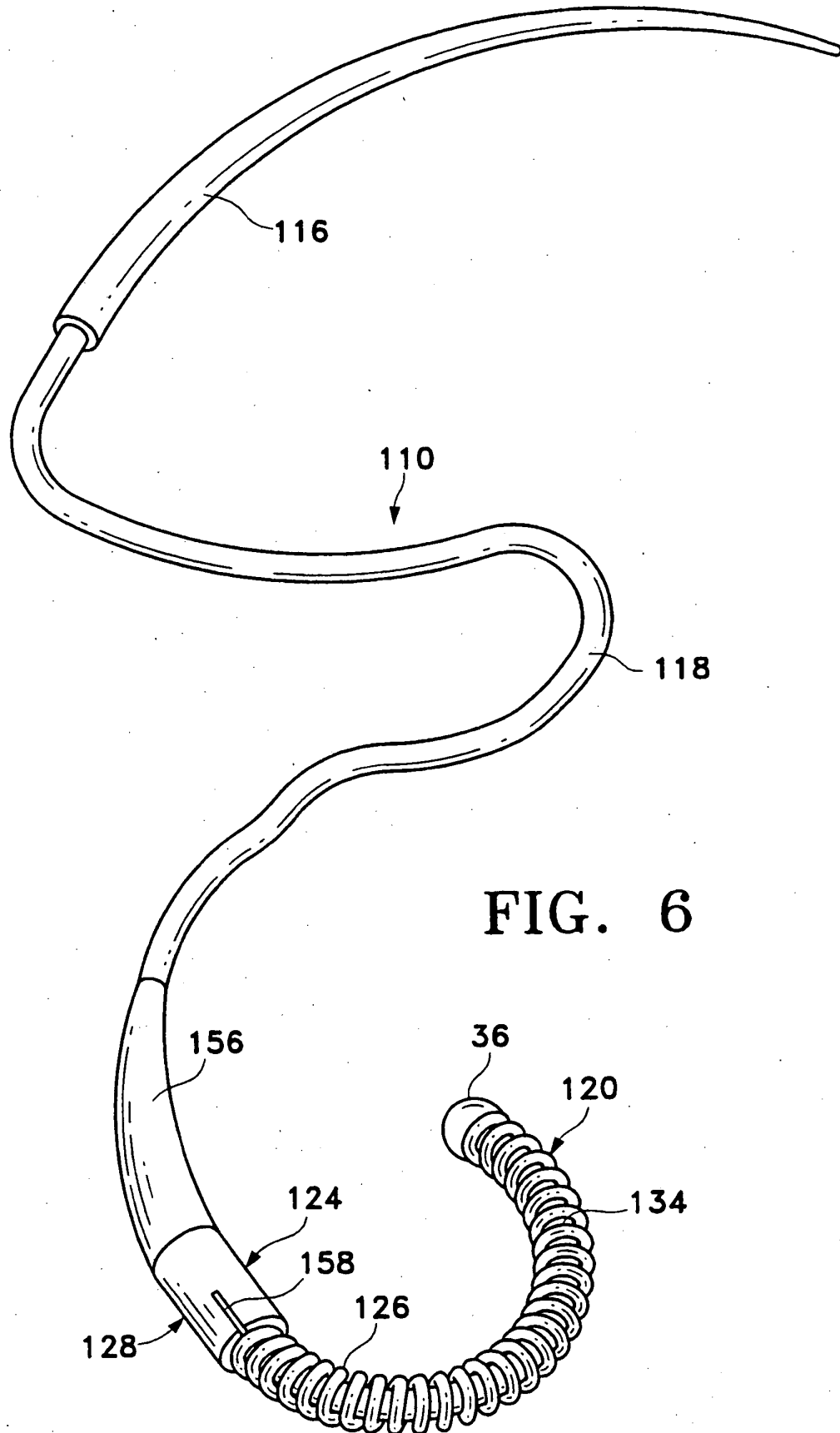


FIG. 5



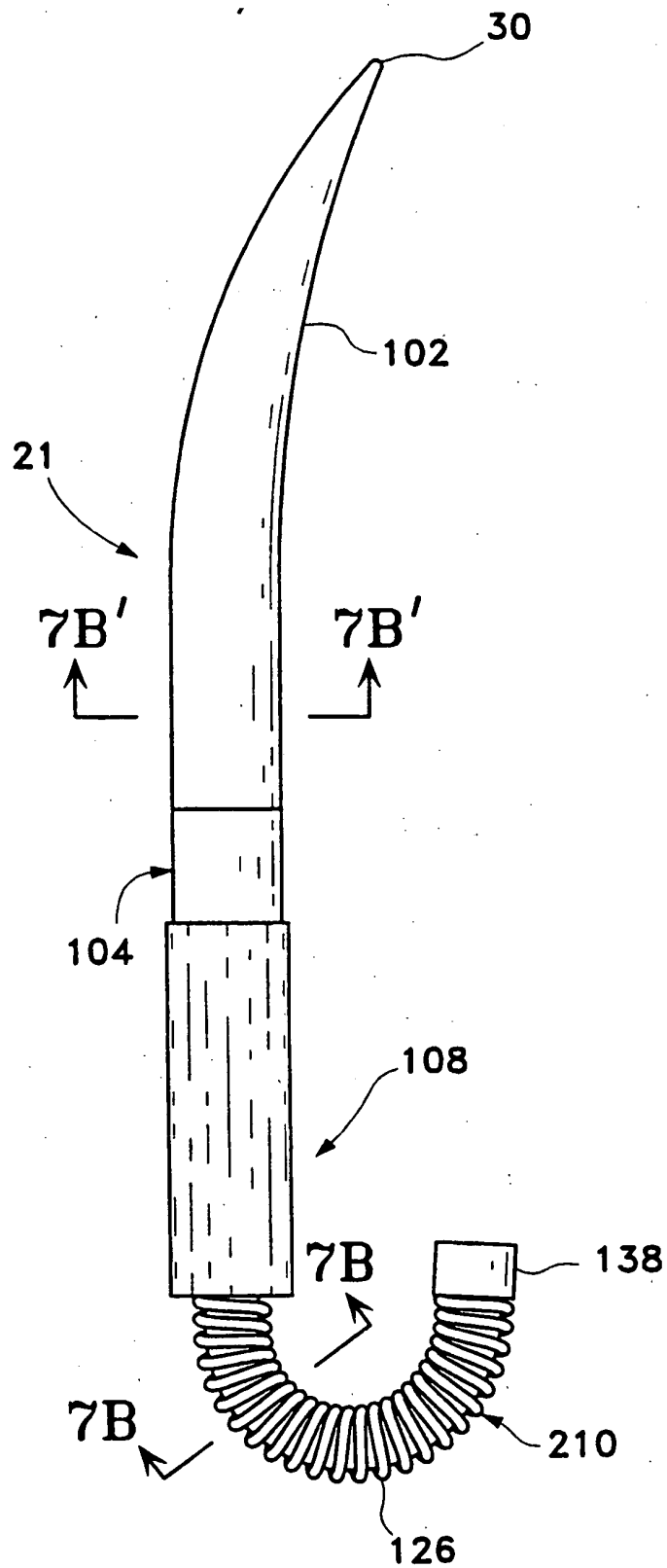


FIG. 7A

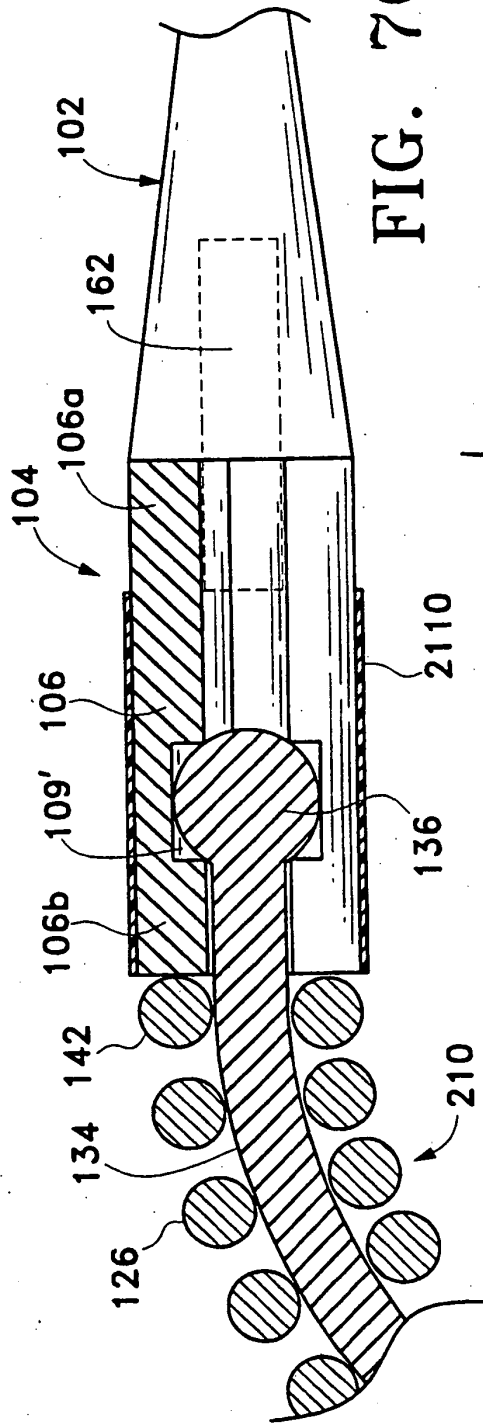


FIG. 7C

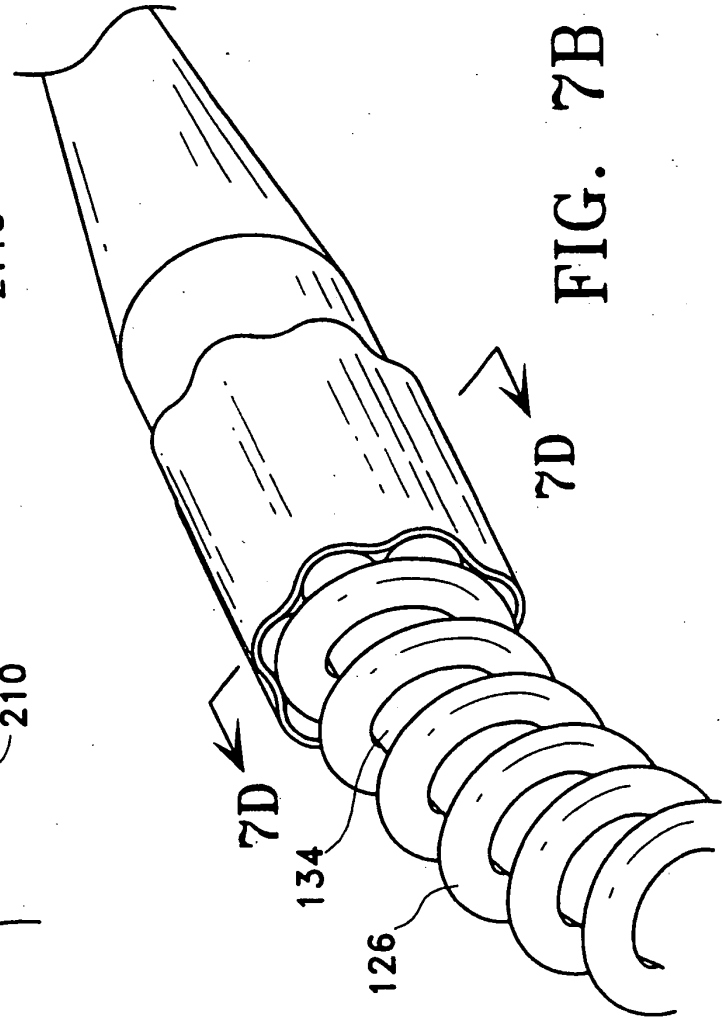


FIG. 7B

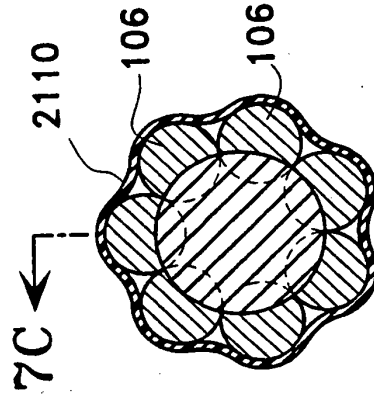
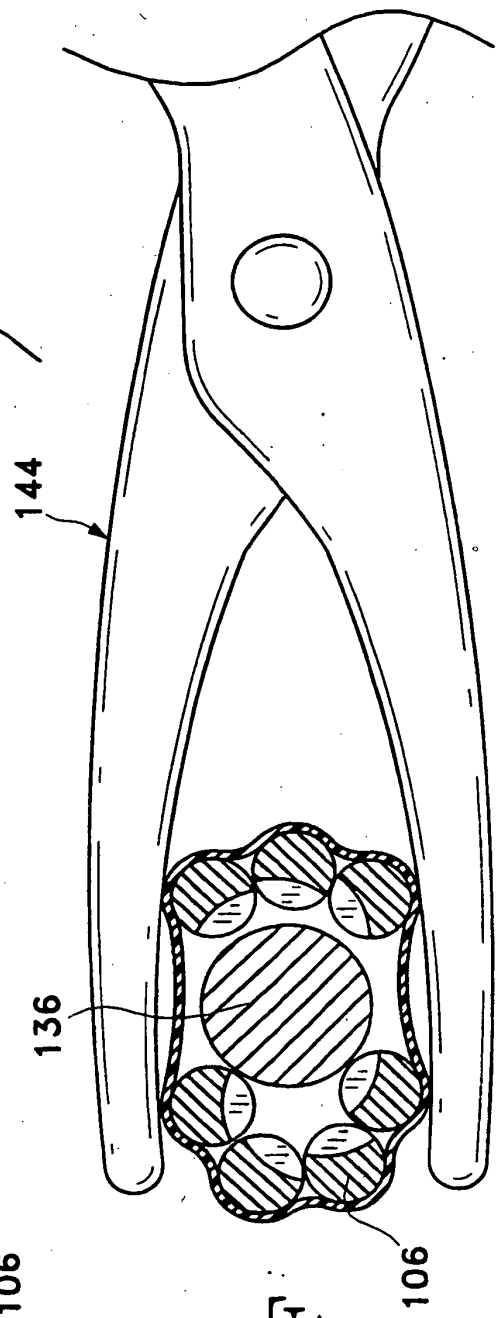
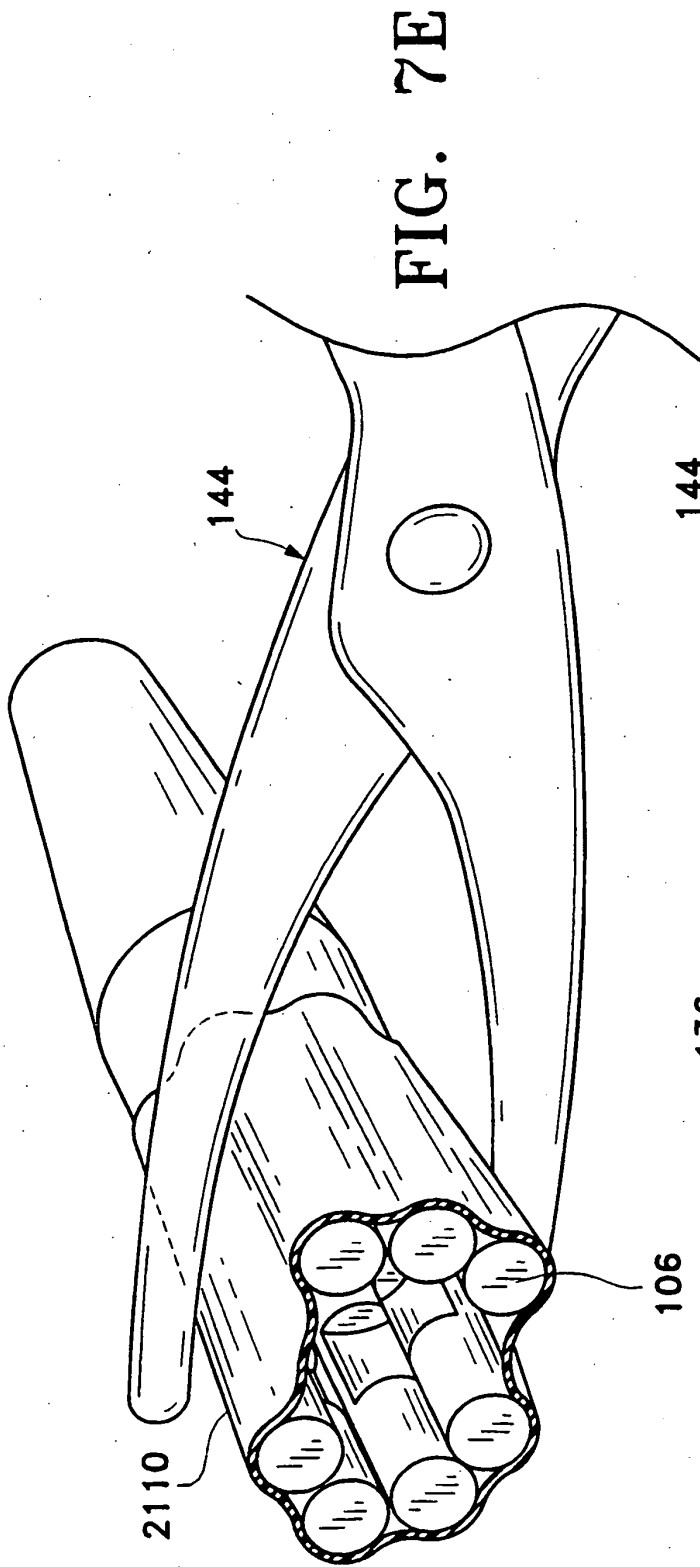


FIG. 7D



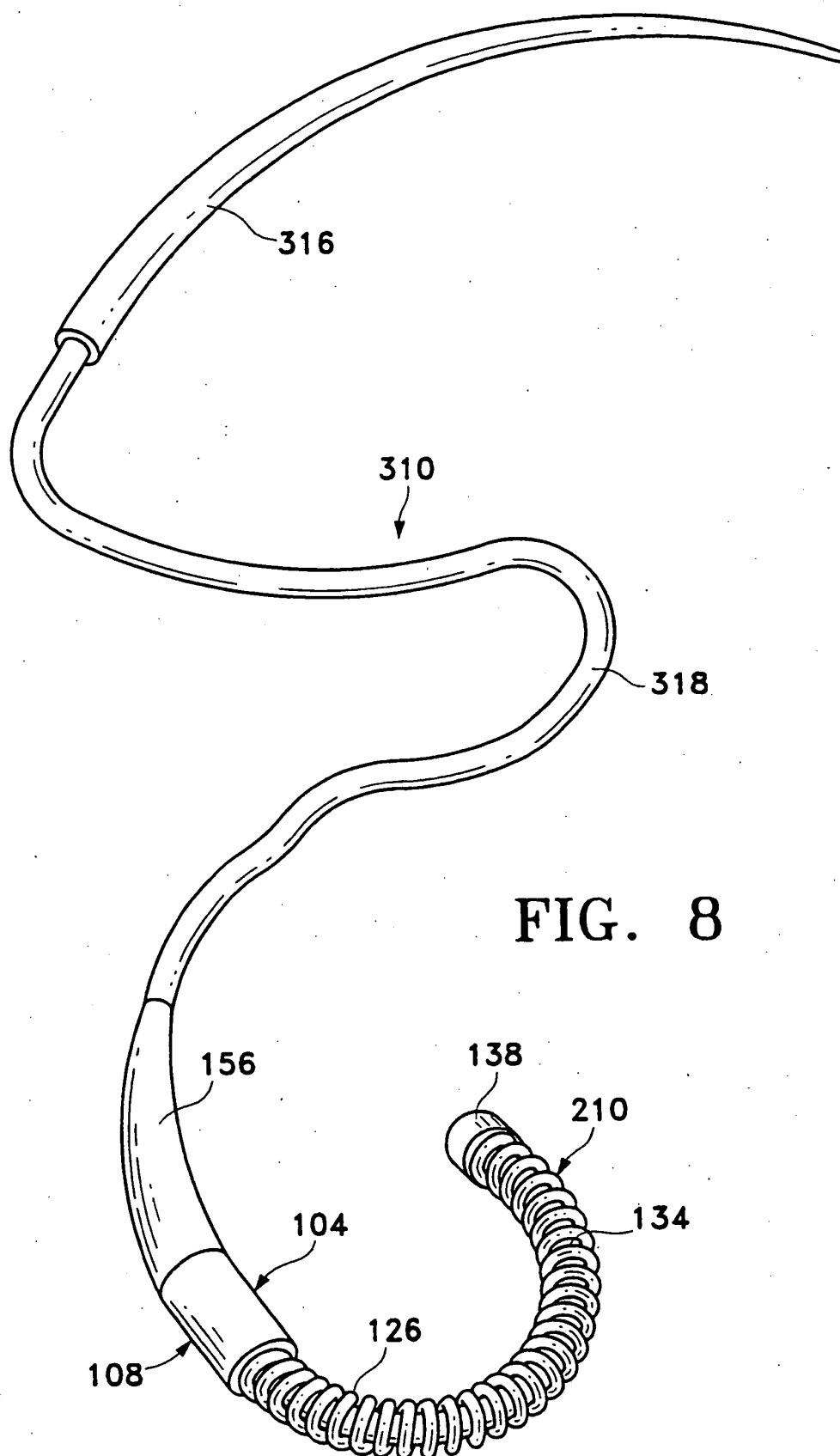


FIG. 8

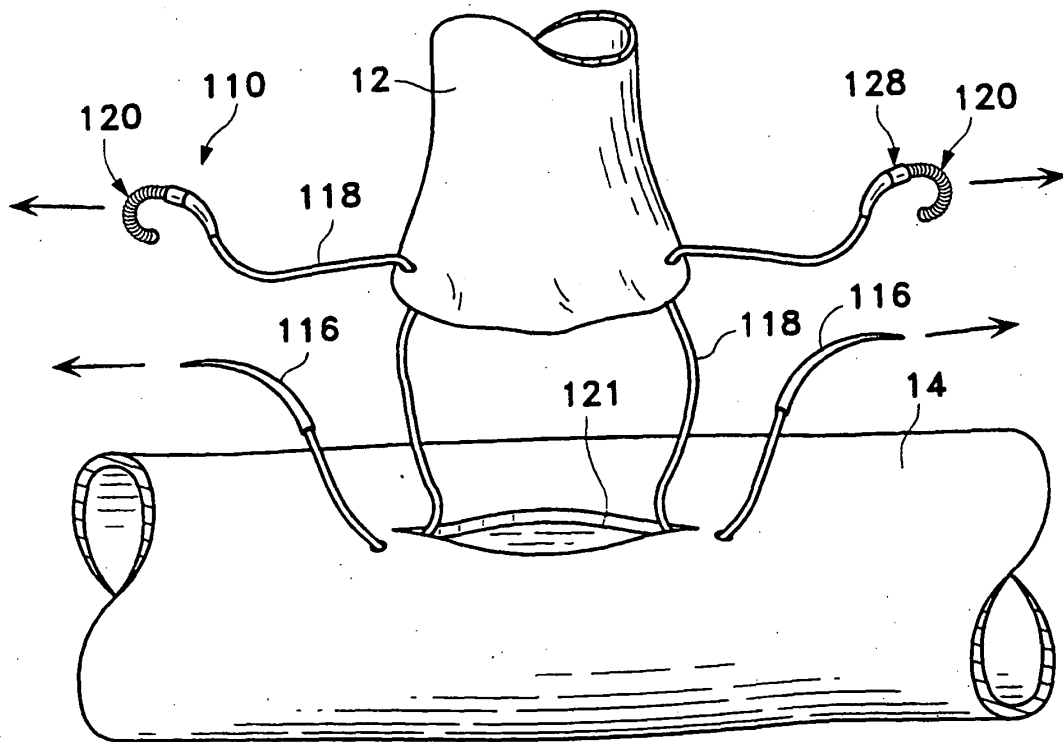


FIG. 9

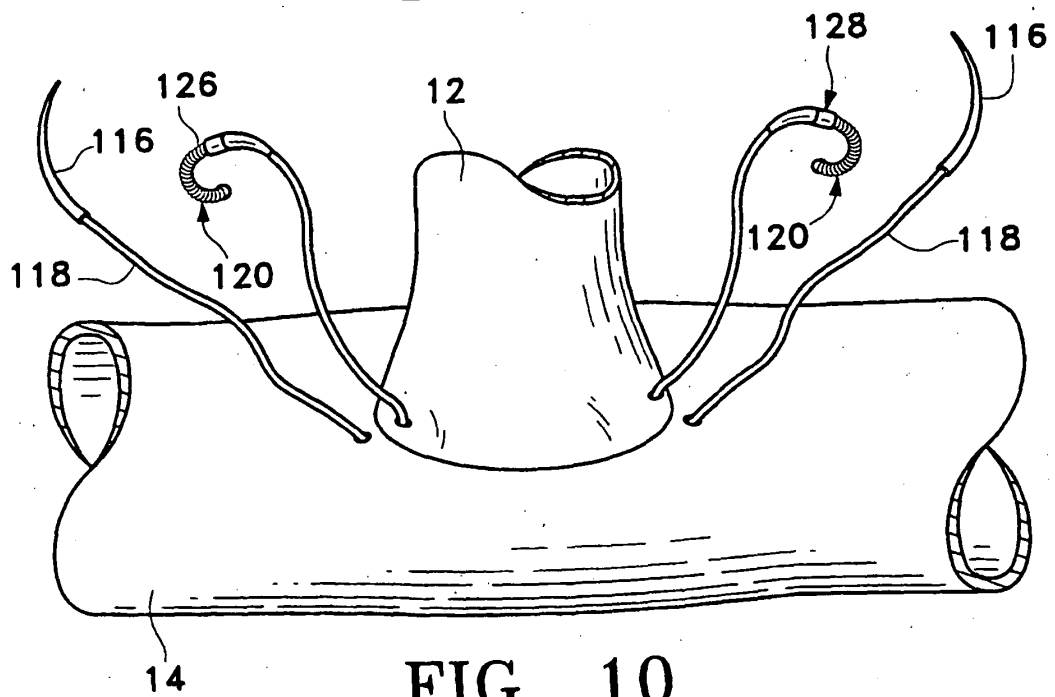
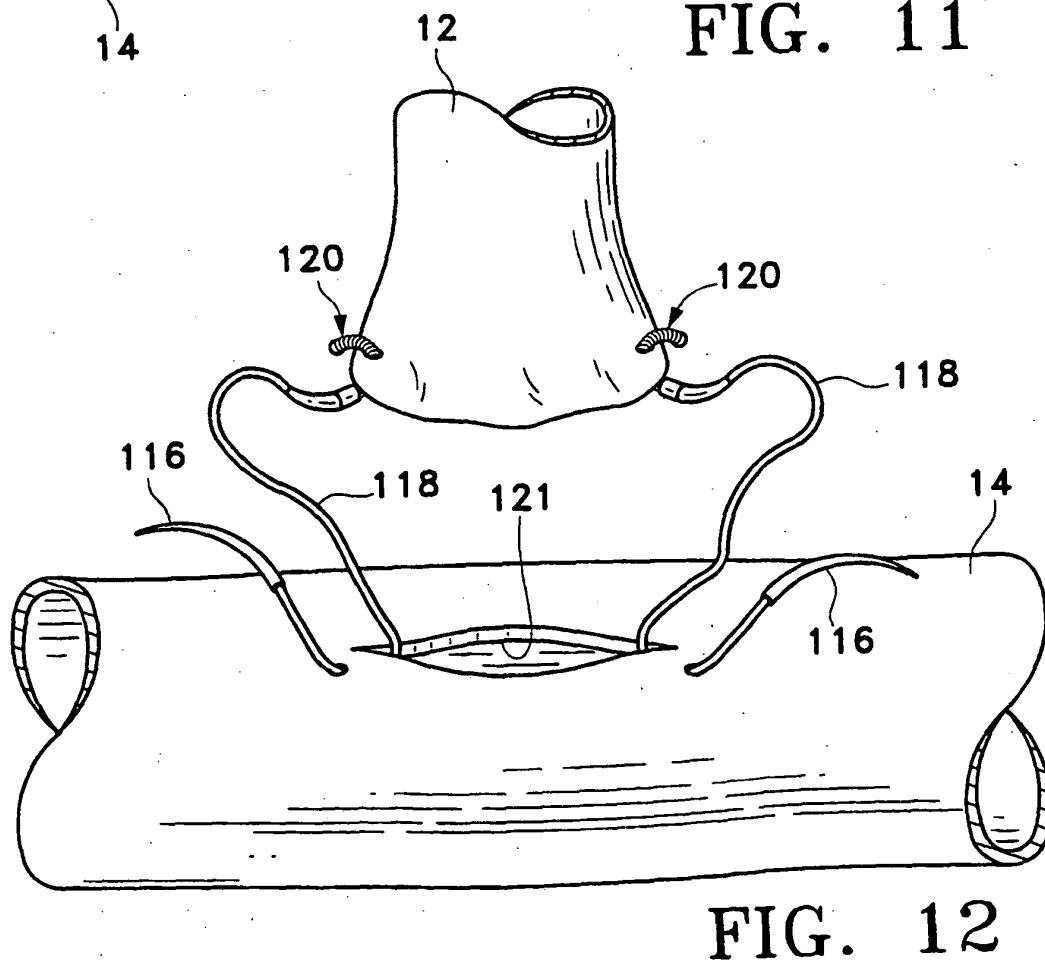
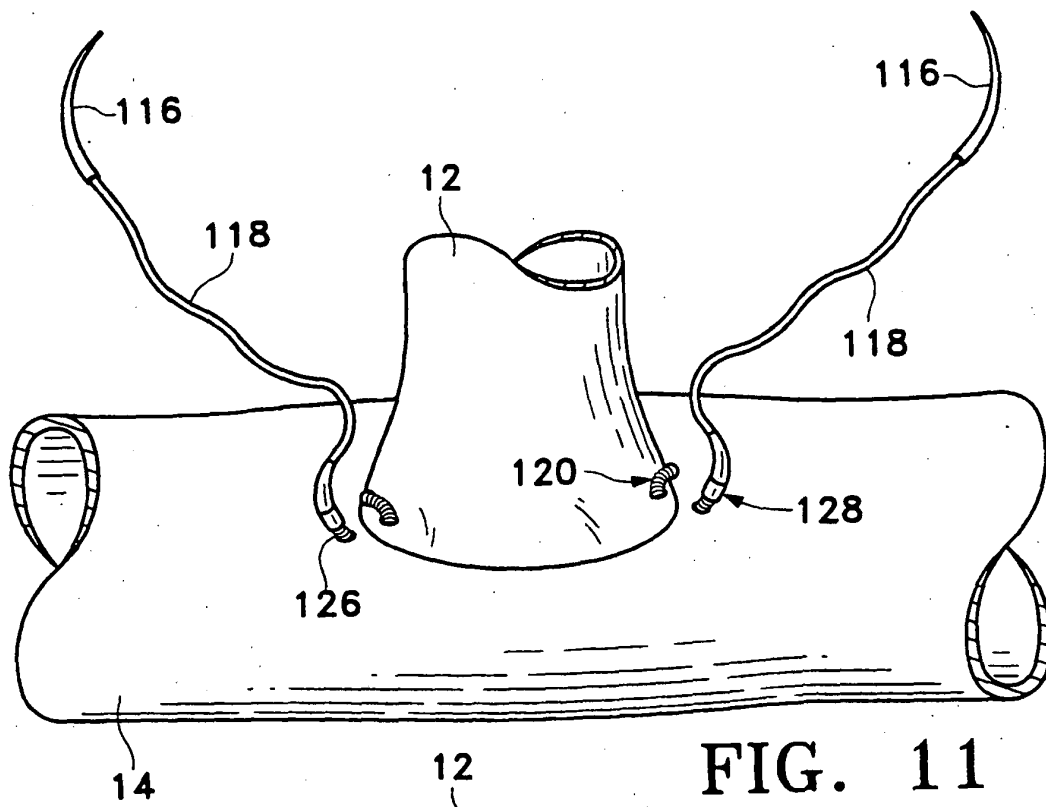
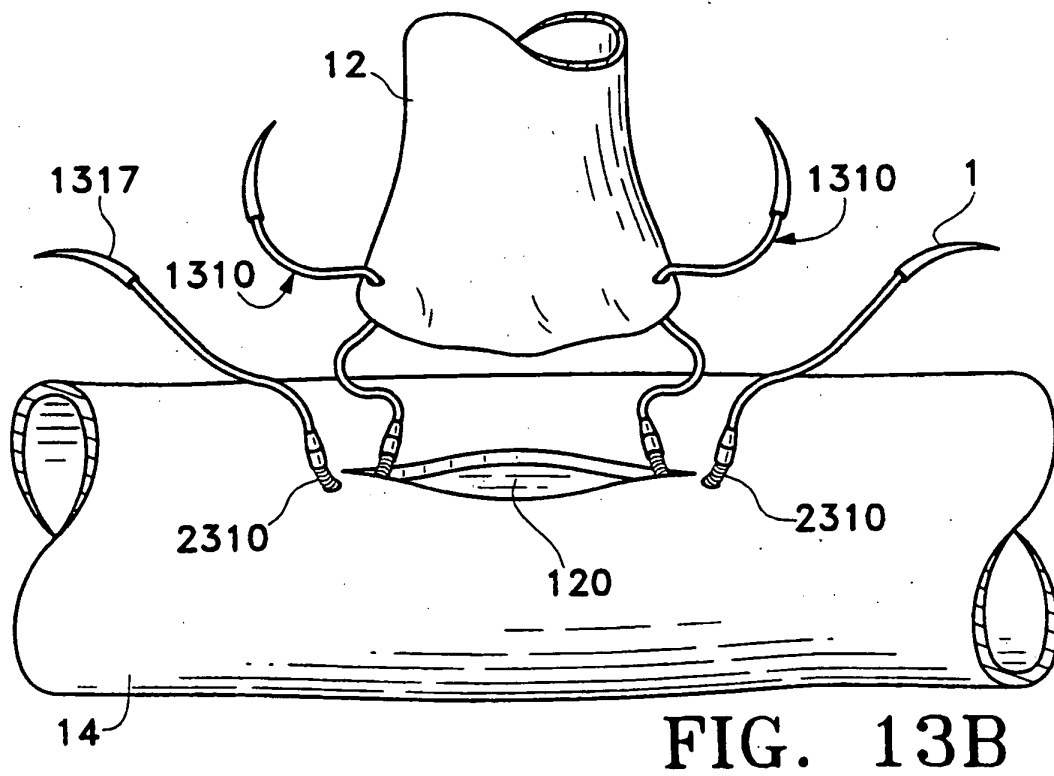
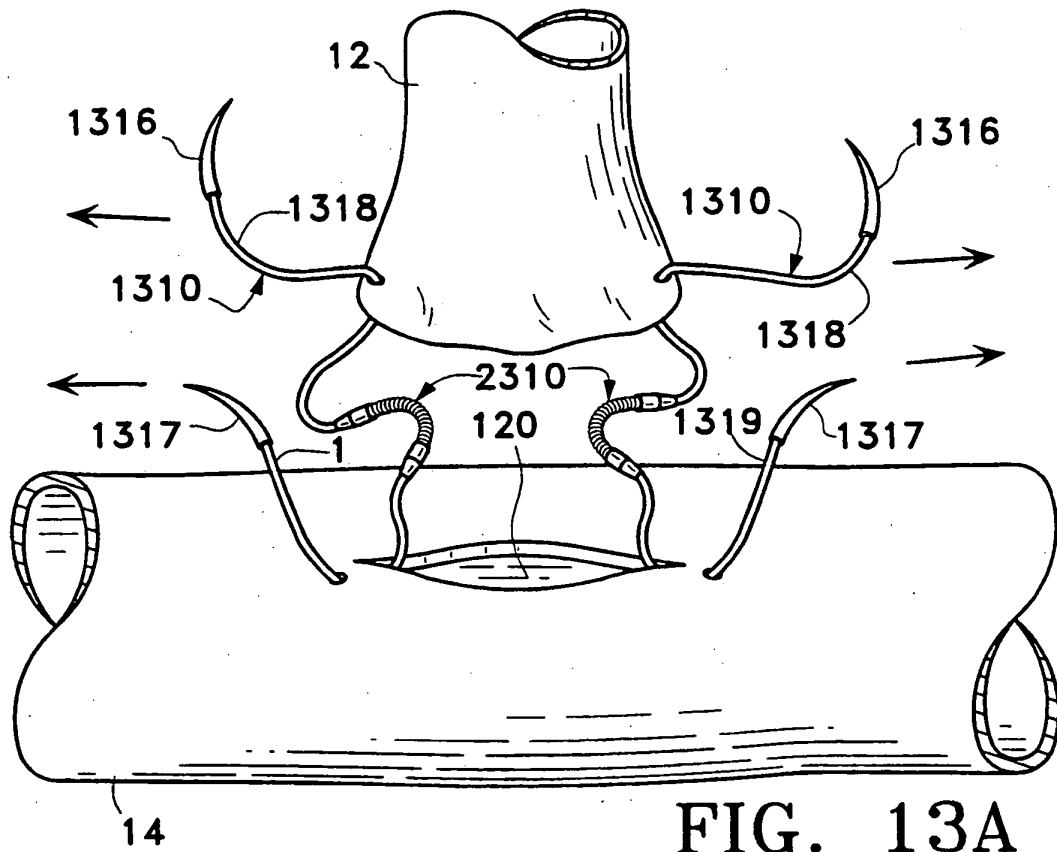
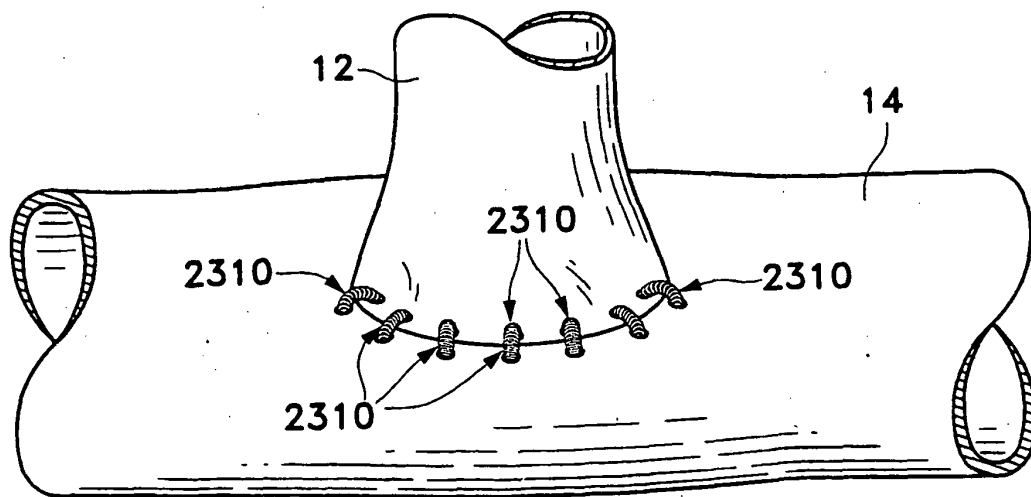
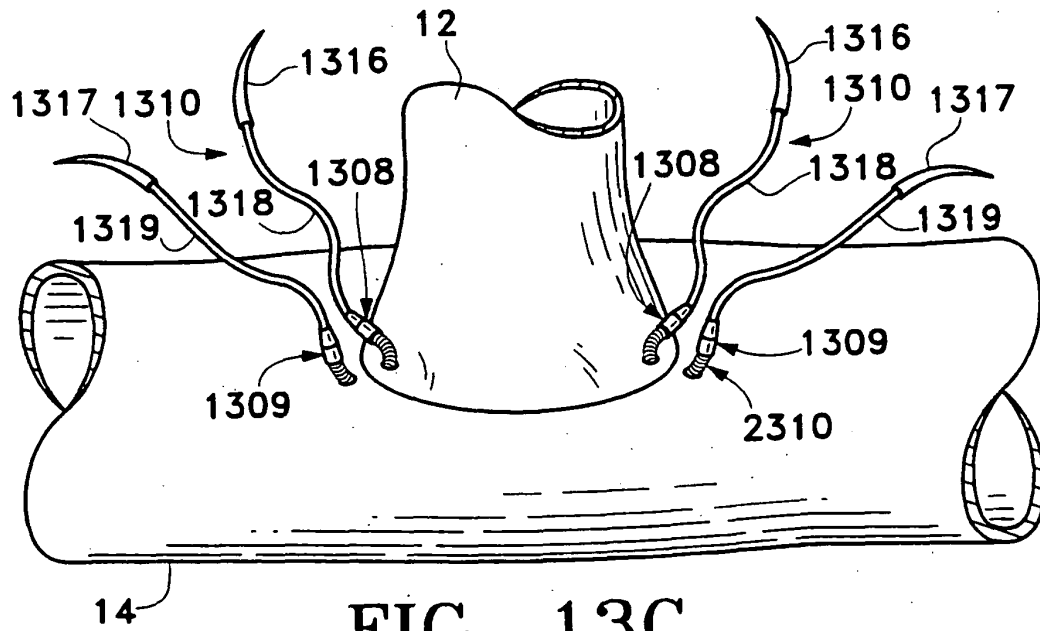


FIG. 10







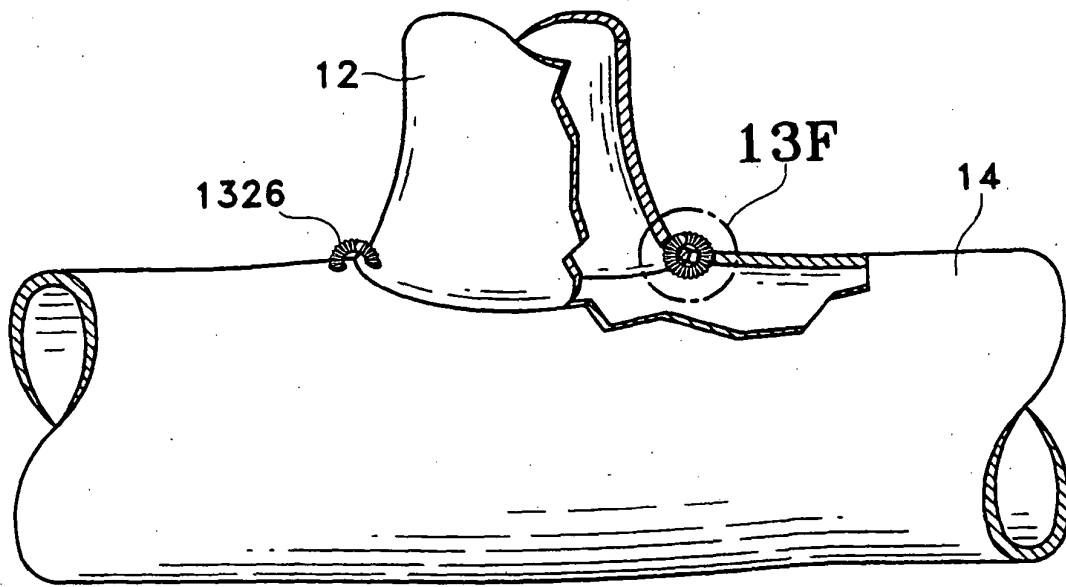


FIG. 13E

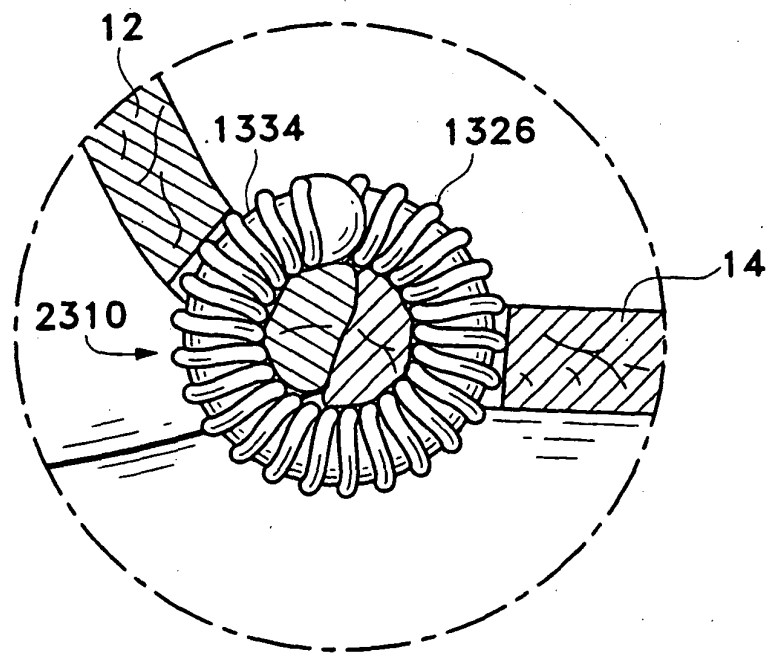


FIG. 13F

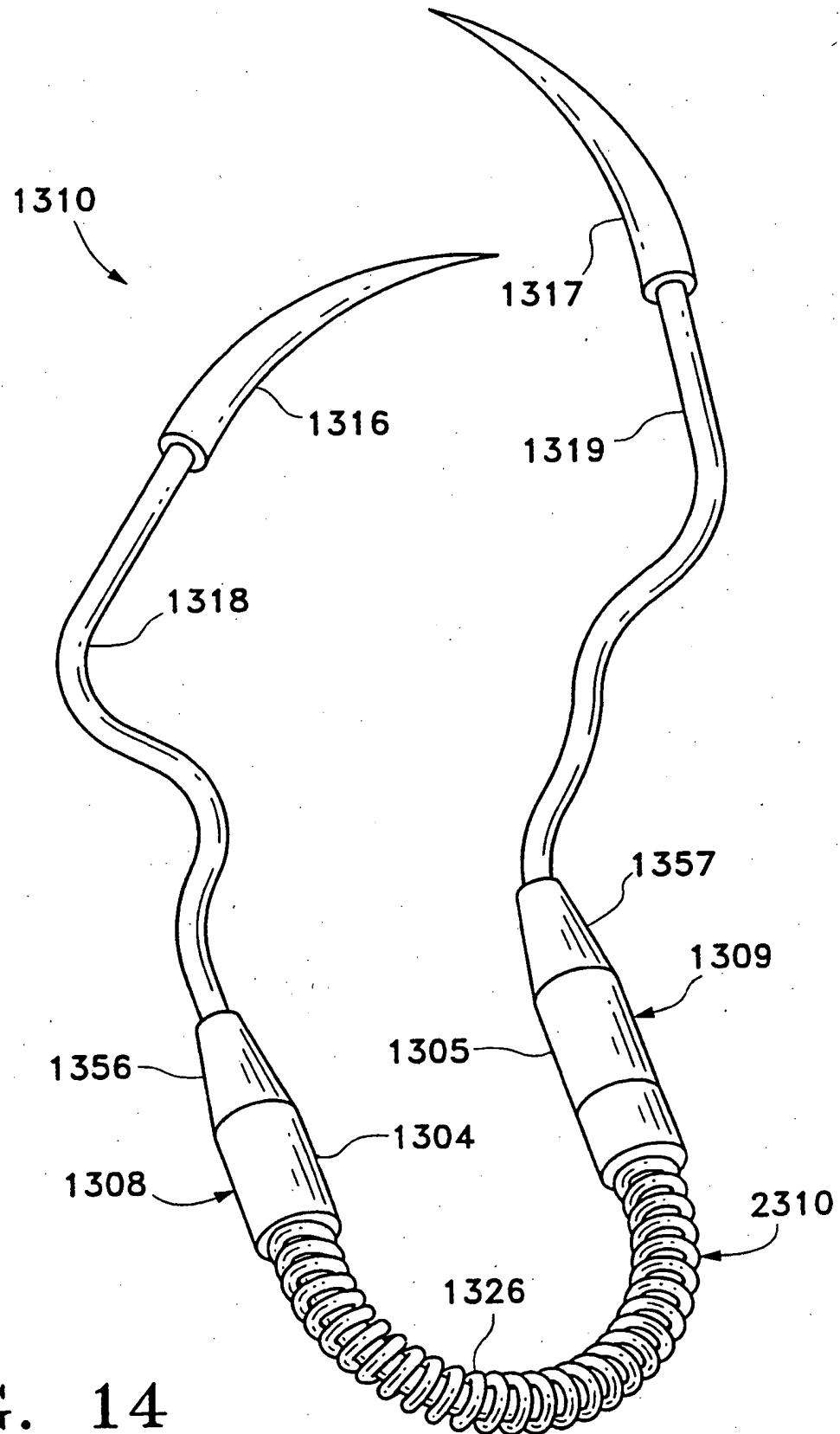


FIG. 14

REFERENCES CITED IN THE DESCRIPTION

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