

GM, KE, LR, LS, MW, MZ, NA, RW, SD, SL, ST, SZ, TZ,
UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, RU, TJ,
TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK,
EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV,
MC, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK, SM,
TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW,
KM, ML, MR, NE, SN, TD, TG).

Published:

— *with international search report (Art. 21(3))*

PROTECTION APPARATUS

This invention relates to a protection apparatus, and to a method of operating a protection apparatus.

It is known to use protection devices, such as circuit breakers and relays, which are
5 operated in the event of a fault in order to protect an electrical network from the fault.

According to a first aspect of the invention, there is provided a protection apparatus for protecting an electrical network, the protection apparatus comprising:

at least one protection device configured to protect the electrical network from a fault in response to a or a respective protection criterion being met; and

10 a controller configured to: receive real-time information on a change in topological structure of the electrical network; perform an online determination of the real-time impedance or admittance matrix of the electrical network based on the change in topological structure of the electrical network; and adapt the or each protection criterion based on the real-time impedance or admittance matrix.

15 During the operation of the electrical network, the topological structure of the electrical network may change as a result of a change in condition of one or more components of the electrical network, such as an in-operation connection or disconnection of a component to or from the electrical network, a temporary or permanent removal of a component from the electrical network, and a temporary or permanent addition of a
20 new component to or from the electrical network.

For example, the change in topological structure of the electrical network may include at least one of:

a connection of at least one electrical source into the electrical network;

a disconnection of at least one electrical source from the electrical network;

25 a connection of at least one electrical load into the electrical network;

a disconnection of at least one electrical load from the electrical network;

a connection of at least one previously open electrical link of the electrical network;

5 a disconnection of at least one previously closed electrical link of the electrical network;

an increase or decrease in power of at least one connected electrical load or at least one connected electrical source of the electrical network.

An example of an electrical source is, but is not limited to, a distributed generator. An example of an electrical load is, but is not limited to, a bus or a feeder. The connection
10 or disconnection of a previously open or closed electrical link may arise as a result of a change in switching state of an associated switching device (such as a relay, circuit breaker, and the like).

The controller may receive the real-time information on the change in topological structure of the electrical network from, for example, another controller, one or more
15 sensors, and one or more components of the electrical network. The real-time information may relate to, for example, at least one electrical property of the electrical network, at least one electrical property of one or more components of the electrical network, and a switching state of at least one switching device.

Since the protection criterion of the or each protection device is designed on the basis
20 of the previous topological structure of the electrical network prior to the occurrence of the change in topological structure of the electrical network, the change in the topological structure of the electrical network may lead to mal-operation or loss of the protection of the or each protection device as a result of the or each protection criterion not matching up with the new topological structure of the electrical network.
25 Consequently the ability of the or each protection device to react appropriately to a fault would be adversely affected. For example, under such circumstances, the protection ability of the or each protection device may become active when it is not required to do so, or may remain inactive when it is required to do so.

In order to avoid the aforementioned mal-operation or loss of protection, the protection apparatus of the invention is designed to enable the dynamic and automatic adaptation of the protection criterion of the or each protection device in accordance with the change in the topological structure of the electrical network, which is particularly crucial when
5 the topological structure of the electrical network changes frequently and/or unexpectedly. This in turn eliminates or minimises the exposure of the electrical network to the risk of mal-operation or loss of protection of the or each protection device.

In contrast, relying on an offline determination of the or each new protection criterion
10 and manually updating the or each protection criterion may not match the variation of the topological structure of the electrical network or may not match the powers of the electrical loads and electrical sources and thereby runs a high risk of exposing the electrical network to mal-operation or loss of protection of the or each protection device. Also, it is impossible to perform the offline determination of the real-time
15 impedance or admittance matrix and manual updating of the or each protection criterion for an electrical network with a topological structure that changes frequently and/or unexpectedly. This is because the or each protection criterion for an electrical network would normally be calculated offline based on a worst case scenario, and the or each offline-calculated protection criterion would then be fixed regardless of any change in
20 the topological structure of the electrical network.

In addition the ability to dynamically and automatically adapt the protection criterion of the or each protection device in response to the change in the topological structure of the electrical network obviates the need to bring the or each protection device offline (which leaves the electrical network vulnerable to faults) in order to prevent mal-
25 operation or loss of protection of the or each protection device.

Furthermore the use of the real-time impedance or admittance matrix conveys information about the new topological structure of the electrical network that permits determination of the or each new protection criterion in a time-efficient manner.

The provision of the controller in the protection apparatus of the invention therefore
30 results in reliable and accurate protection for the electrical network.

In embodiments of the invention, the controller may be configured to adapt the or each protection criterion by determining an equivalent source voltage and/or an equivalent impedance or admittance seen by the or each protection device based on the real-time impedance or admittance matrix, and by determining the or each protection criterion
5 based on the determined equivalent source voltage and/or equivalent impedance or admittance.

In such embodiments, the controller may be configured to adapt the or each protection criterion by determining an equivalent source voltage and/or an equivalent impedance or admittance seen by the or each protection device based on the real-time impedance
10 or admittance matrix and on measured voltage and current of a part (e.g. a node) of the electrical network corresponding to the or each protection device, and by determining the or each protection criterion based on the determined equivalent source voltage and/or equivalent impedance or admittance.

Information about the new topological structure of the electrical network conveyed in
15 the form of the equivalent source voltage and/or the equivalent impedance or admittance seen by the or each protection device enables ready determination of the or each new protection criterion.

Preferably the equivalent source voltage and the equivalent impedance or admittance are respectively the Thevenin equivalent source voltage and the Thevenin equivalent
20 impedance or admittance.

In further embodiments of the invention, the controller may be configured to perform the online determination of the real-time impedance or admittance matrix of the electrical network by modifying a reference impedance or admittance matrix of the electrical network based on the change in topological structure of the electrical network
25 so as to determine the real-time impedance or admittance matrix.

Modifying the reference impedance or admittance matrix results in a more time-efficient determination of the real-time impedance or admittance matrix, especially when the topological structure of the electrical network changes frequently and/or

unexpectedly, when compared to determining the real-time impedance or admittance matrix without using a reference starting point.

The controller may be configured to receive information on the topological structure of the electrical network and to perform a determination of the reference impedance or admittance matrix prior to the change in topological structure of the electrical network.
5 Configuring the controller in this manner permits automatic determination of the reference impedance or admittance matrix.

One way of determining the reference impedance or admittance matrix may be or may include the use of the branch addition method.

10 The determination of the reference impedance or admittance matrix may be an offline determination of the reference impedance or admittance matrix. Such offline determination by the controller may be carried out, for example, during installation of the electrical network or a new component of the electrical network, or when the electrical network is brought offline.

15 Alternatively, in other embodiments, the reference impedance or admittance matrix may be determined offline through other means, such as a controller or computer external to the electrical network, before the reference impedance or admittance matrix is provided as an input to the controller.

The reference impedance or admittance matrix may omit at least one electrical source
20 of the electrical network and/or at least one electrical load of the electrical network. This simplifies the determination of the reference impedance or admittance matrix, since the electrical network may experience frequent and/or unexpected connection and disconnections of at least one electrical source and/or at least one electrical load.

In further embodiments of the invention, the controller may be configured to determine
25 an equivalent impedance or admittance value of at least one component of the electrical network and to combine the or each equivalent impedance or admittance value into the reference impedance or admittance matrix by addition or subtraction so as to determine the real-time impedance or admittance matrix.

The modification of the reference impedance or admittance matrix in this manner provides a real-time impedance or admittance matrix that accurately reflects the current state of the topological structure of the electrical network.

The or each equivalent impedance or admittance value may be selected from a group
5 including:

an equivalent load impedance or admittance of an electrical load of the electrical network;

an equivalent source impedance or admittance of an electrical source of the electrical network;

10 an equivalent impedance or admittance of an electrical link of the electrical network.

The controller may be configured in a variety of ways, examples of which are described as follows.

The controller may be a single control unit or may include a plurality of control units.

15 The controller may include a first control unit and at least one second control unit, the first control unit in communication with the or each second control unit. The or each second control unit may be associated with the or the respective protection device.

The first control unit may be a higher level controller, such as a substation level controller.

20 The first control unit and/or the or each second control unit may also be in communication with one or more other control units, for example, a global controller.

The first control unit may be configured to: receive real-time information about a part of the electrical network corresponding to the or each protection device from the or each second control unit; and perform the online determination of the real-time
25 impedance or admittance matrix based on the received real-time information from the or each second control unit. The real-time information from the or each second control

unit may relate to, for example, electrical properties of the or each protection device, such as current and voltage, and a switching state of the or each protection device.

In such embodiments, the first control unit may be configured to transmit the real-time impedance or admittance matrix to the or each second control unit, and the or each
5 second control unit may be configured to adapt the or each protection criterion based on the real-time impedance or admittance matrix.

Determining the real-time impedance or admittance matrix using the first control unit and adapt the or each protection criterion using the or each second control unit in this manner enables the determination of the real-time impedance or admittance matrix and
10 the adaptation of the or each protection criterion to be performed on different levels. This in turn permits a reduction in the dimension of the real-time impedance or admittance matrix, which improves the reliability efficiency of the controller in carrying out its various tasks.

Dividing the tasks of determining the real-time impedance or admittance matrix and
15 adapting the or each protection criterion between the first and second control units in the foregoing manner can be particularly effective when there are a high number of protection devices and therefore a high number of second control units, or when the invention is used for an electrical network with a large and/or a complex topology.

In still further embodiments of the invention, the or each protection device may be or
20 may include an overcurrent relay, and the or each protection criterion may be or may include a fault level of a circuit interruption device (e.g. a circuit breaker) associated with the overcurrent relay and/or a setting value of the overcurrent relay. The invention is particularly applicable to an overcurrent relay, since the fault level of a circuit interruption device associated with the overcurrent relay and/or a setting value of the
25 overcurrent relay can be affected by a change in topological structure of the electrical network.

In even still further embodiments of the invention, the or each protection device may be or may include a distance protection relay, and the or each protection criterion may be or may include a reach setting value of the distance protection relay. The invention

is particularly applicable to a distance protection relay, since the accuracy of the reach setting value of the distance protection relay can be affected by a change in topological structure of the electrical network.

According to a second aspect of the invention, there is provided a method of operating
5 a protection apparatus for protecting an electrical network, the protection apparatus comprising at least one protection device configured to protect the electrical network from a fault in response to a or a respective protection criterion being met, the method including the steps of:

receiving real-time information on a change in topological structure of the
10 electrical network;

performing an online determination of the real-time impedance or admittance matrix of the electrical network based on the change in topological structure of the electrical network; and

adapting the or each protection criterion based on the real-time impedance or
15 admittance matrix.

The advantages of the protection apparatus of the first aspect of the invention and its embodiments apply mutatis mutandis to the method of the second aspect of the invention and its embodiments.

In the method of the invention, the change in topological structure of the electrical
20 network may include at least one of:

a connection of at least one electrical source into the electrical network;

a disconnection of at least one electrical source from the electrical network;

a connection of at least one electrical load into the electrical network;

a disconnection of at least one electrical load from the electrical network;

a connection of at least one previously open electrical link of the electrical network;

a disconnection of at least one previously closed electrical link of the electrical network.

- 5 an increase or decrease in power of at least one connected electrical load or at least one connected electrical source of the electrical network.

The method of the invention may include the step of adapting the or each protection criterion by determining an equivalent source voltage and/or an equivalent impedance or admittance seen by the or each protection device based on the real-time impedance
10 or admittance matrix, and by determining the or each protection criterion based on the determined equivalent source voltage and/or equivalent impedance or admittance.

The method of the invention may further include the step of adapting the or each protection criterion by determining an equivalent source voltage and/or an equivalent impedance or admittance seen by the or each protection device based on the real-time
15 impedance or admittance matrix and on measured voltage and current of a part (e.g. a node) of the electrical network corresponding to the or each protection device, and by determining the or each protection criterion based on the determined equivalent source voltage and/or equivalent impedance or admittance.

In the method of the invention, the equivalent source voltage and the equivalent
20 impedance or admittance may be respectively the Thevenin equivalent source voltage and the Thevenin equivalent impedance or admittance.

The method of the invention may further include the step of performing the online determination of the real-time impedance or admittance matrix of the electrical network by modifying a reference impedance or admittance matrix of the electrical network
25 based on the change in topological structure of the electrical network so as to determine the real-time impedance or admittance matrix.

The method of the invention may further include the steps of: receiving information on the topological structure of the electrical network and performing a determination of

the reference impedance or admittance matrix prior to the change in topological structure of the electrical network.

In the method of the invention, the determination of the reference impedance or admittance matrix may be an offline determination of the reference impedance or
5 admittance matrix.

In the method of the invention, the reference impedance or admittance matrix may omit at least one electrical source of the electrical network and/or at least one electrical load of the electrical network.

The method of the invention may further include the steps of: determining an equivalent
10 impedance or admittance value of at least one component of the electrical network; and combining the or each equivalent impedance or admittance value into the reference impedance or admittance matrix by addition or subtraction so as to determine the real-time impedance or admittance matrix.

The or each equivalent impedance or admittance value may be selected from a group
15 including:

an equivalent load impedance or admittance of an electrical load of the electrical network;

an equivalent source impedance or admittance of an electrical source of the electrical network;

20 an equivalent impedance or admittance of an electrical link of the electrical network.

In the method of the invention, the or each protection device may be or may include an overcurrent relay, and the or each protection criterion may be or may include a fault level of a circuit interruption device (e.g. a circuit breaker) associated with the
25 overcurrent relay and/or a setting value of the overcurrent relay.

In the method of the invention, the or each protection device may be or may include a distance protection relay, and the or each protection criterion may be or may include a reach setting value of the distance protection relay.

5 A preferred embodiment of the invention will now be described, by way of a non-limiting example, with reference to the accompanying figures in which:

Figure 1 schematically shows an electrical network which includes a protection apparatus according to an embodiment of the invention;

Figure 2 schematically shows the equivalent source voltage and the equivalent impedance seen by a protection device of the electrical network of Figure 1.

10 Figure 3 schematically show a layout of a controller of the protection apparatus of Figure 1;

Figure 4 illustrates the determination of a reference impedance matrix of the electrical network of Figure 1 using the branch addition method; and

15 Figures 5 and 6 illustrates the determination of a real-time impedance matrix of the electrical network of Figure 1.

The figures are not necessarily to scale, and certain features and certain views of the figures may be shown exaggerated in scale or in schematic form in the interests of clarity and conciseness.

20 An electrical network 20 is shown in Figure 1 and is designated generally by the reference numeral 20.

The electrical network 20 includes a substation with first, second and third buses 22, 24, 26. The first bus 22 is connected to a higher level section of the electrical network 20 (such as a power transmission section) which is depicted by an equivalent source voltage and system impedance Z_s . The first bus 22 is connected to the second bus 24 via a transformer, and the first bus 22 is also connected to the third bus 26 via another transformer. Respective breakers are connected on both sides of each transformer. The

25

second and third buses 24, 26 are interconnected via an electrical link that includes a breaker.

A plurality of feeders 30 extends from the second bus 24, and a distributed generator 32 is connected to one of the feeders 30 extending from the second bus 24. Another
 5 plurality of feeders 30 extends from the third bus 26, and another distributed generator 32 is connected via a breaker to the third bus 26.

A respective protection device is connected in each feeder 30. In the embodiment shown, each protection device is in the form of an overcurrent relay, which is configured to operate an associated breaker to switch to an open state to disconnect the
 10 corresponding feeder 30 in the event of an overcurrent resulting in its protection criterion being met. The configuration of each overcurrent relay in this way enables it to protect the corresponding feeder 30 from the overcurrent.

Each protection criterion, i.e. the fault level of the breaker associated with each overcurrent relay and the setting value of each overcurrent relay, is calculated from the
 15 equivalent source voltage E_{TH} and the equivalent impedance Z_{TH} of the electrical network 20 as seen by each overcurrent relay. Figure 2 schematically shows the Thevenin equivalent source voltage E_{TH} and the Thevenin equivalent impedance Z_{TH} seen by a protection device of the electrical network 20 of Figure 1.

For each feeder 30, the fault level I_{FL} of each breaker associated with a respective
 20 overcurrent relay is calculated as $I_{FL} = E_{TH}/Z_{TH}$, while the setting value I_{set} of each overcurrent relay is calculated as $I_{set} = 1.2 * E_{th}/(Z_{TH} + Z_L)$, where Z_L is the overall impedance of the corresponding feeder 30. It will be appreciated that the coefficient of 1.2 for the setting value I_{set} calculation may be replaced by another coefficient of a different value.

25 However, during the operation of the electrical network 20, the equivalent source voltage and the equivalent impedance of the electrical network 20 as seen by each overcurrent relay may change due to a change in topological structure of the electrical network 20. For example, the change in topological structure of the electrical network 20 may include at least one of: a connection or disconnection of at least one distributed

generator 32 into or from the electrical network 20; a connection or disconnection of at least one feeder 30 into or from the electrical network 20; a connection of at least one previously open electrical link of the electrical network 20 due to the closing of an associated breaker; a disconnection of at least one previously closed electrical link of the electrical network 20 due to the opening of an associated breaker; an increase or decrease in power of at least one connected feeder 30 or at least one connected distributed generator 32 of the electrical network 20.

The change in the equivalent source voltage E_{TH} and the equivalent impedance Z_{TH} of the electrical network 20 as seen by a given overcurrent relay means that the corresponding protection criterion no longer matches the new topological structure of the electrical network 20, which could lead to mal-operation or loss of protection of the or each protection device. This in turn leaves the electrical network 20 vulnerable to overcurrents, and adversely affects the performance of each protection device.

The protection apparatus further includes a controller. The controller includes a first control unit, which is in the form of a central control unit 34, and a plurality of second control units, which is in the form of a distributed control unit 36. Each distributed control unit 36 is associated with a respective one of the overcurrent relays.

As shown in Figure 3, the central control unit 34 is in communication with each of the distributed control units 36. In this way the central control unit 34 can obtain real-time information from each distributed control unit 36 and transmit information back to each distributed control unit 36, while each distributed control unit 36 can obtain real-time information about the corresponding overcurrent relay and feeder 30 and provide the obtained real-time information to the central control unit 34. Each distributed control unit 36 is configured to set the protection criterion of the corresponding overcurrent relay.

The controller is configured to enable the dynamic and automatic adaptation of each protection criterion in response to the change in topological structure of the electrical network 20. Such configuration of the controller is described as follows, with reference to Figures 3 to 6.

Initially a reference impedance matrix Z_{M0} is formulated using the branch addition method. The loads and the distributed generators 32 connected on the buses 24, 26 are accounted in the formulation of the reference impedance matrix Z_{M0} . Preferably the formulation of the reference impedance matrix Z_{M0} is performed offline, and then
 5 provided as an input to the central control unit 34.

Figure 4 illustrates the determination of a reference impedance matrix Z_{M0} of the electrical network 20 of Figure 1 using the branch addition method.

The buses 22, 24, 26 in the electrical network 20 are numbered as 1, 2 and 3.

The branch impedance of an arbitrary grounded branch connected to the 1st bus 22 is
 10 added to the reference impedance matrix Z_{M0} so that $Z_{M0} = [Z_S]$. k is then set as 1.

This is followed by a so-called “branch addition” step of adding another branch connected with the k^{th} bus and the n^{th} bus (assuming that the branch impedance is z_{kn}) into the previous reference impedance matrix Z_{M0} .

If the n^{th} bus is a new bus, then the reference impedance matrix Z_{M0} will increase by a
 15 row and a column (assume that the dimension of the reference impedance matrix Z_{M0} is $(n-1)*(n-1)$), in which:

the elements of the n^{th} column are given by:

$$Z_{M0}[i][n] = Z_{M0}[i][k] \quad (i=1,2,\dots,n-1) \quad [1]$$

the elements of the n^{th} row are given by:

$$20 \quad Z_{M0}[n][i] = Z_{M0}[k][i] \quad (i=1,2,\dots,n-1) \quad [2]$$

the element of the n^{th} row and n^{th} column is given by:

$$Z_{M0}[n][n] = Z_{M0}[k][k] + z_{kn} \quad [3]$$

When adding the branch between the 1st and 2nd buses 22, 24 to the reference impedance matrix Z_{M0} in [2], in which the branch impedance of branch between the 1st and 2nd buses 22, 24 is Z_{T1} , the reference impedance matrix Z_{M0} becomes:

$$Z_{M0} = \begin{bmatrix} z_0 & z_0 \\ z_0 & z_0 + z_{T1} \end{bmatrix} \quad [4]$$

- 5 When adding the branch between the 2nd and 3rd buses 24, 26 to the reference impedance matrix Z_{M0} in [4], in which the branch impedance of branch between the 2nd and 3rd buses 24, 26 is Z_{T2} , the reference impedance matrix Z_{M0} becomes:

$$Z_{M0} = \begin{bmatrix} z_0 & z_0 & z_0 \\ z_0 & z_0 + z_{T1} & z_0 \\ z_0 & z_0 & z_0 + z_{T2} \end{bmatrix} \quad [5]$$

- If the kth bus and the nth bus are existing buses in the prior reference impedance matrix Z_{M0} , it means that the corresponding branch is an electrical link. Hence, the dimension of the new reference impedance matrix Z_{M0} is the same as the prior reference impedance matrix Z_{M0} . The elements of the new reference impedance matrix Z_{M0} will be given by:

$$Z_{M0New}[i][j] = Z_{m0}[i][j] + \frac{(Z_{M0}[i][n] - Z_{M0}[i][k])(Z_{M0}[k][j] - Z_{M0}[n][j])}{Z_{M0}[k][k] + Z_{M0}[n][n] - 2Z_{M0}[k][n] + z_{kn}} \quad [6]$$

- 15 If one bus of the branch is an existing bus, and another bus of the branch is ground, then the branch is a grounded electrical link. This means that the dimension of the new reference impedance matrix Z_{M0} is the same as the prior reference impedance matrix Z_{M0} . The elements of the new reference impedance matrix Z_{M0} will be given by:

$$Z_{M0New}[i][j] = Z_{M0}[i][j] - \frac{Z_{M0}[i][k]Z_{M0}[k][j]}{Z_{M0}[k][k] + z_{kn}} \quad [7]$$

The above “branch addition” step is repeated until all of the branches of the electrical network 20 are added to the reference impedance matrix Z_{M0} .

Next, the central unit receives the reference impedance matrix Z_{M0} and uses the reference impedance matrix Z_{M0} to perform an online determination of a real-time impedance matrix Z_{MD} of the electrical network 20 based on the change in topological structure of the electrical network 20. In particular, the online determination of the real-time impedance matrix Z_{MD} involves the modification of the reference impedance matrix Z_{M0} to take into account based on the change in topological structure of the electrical network 20.

The modification of the reference impedance matrix Z_{M0} to determine the real-time impedance matrix Z_{MD} is performed as follows:

a. The equivalent load impedance of the electrical load at each of the second and third buses 24, 26 is calculated (shown by block A of the central control unit 34 in Figure 6). The equivalent load impedance of the k^{th} bus equals the voltage phasor of the k^{th} bus divided by all the current phasors flowing out from the k^{th} bus, and is given by:

$$Z_L[k] = \frac{U[k]}{\sum_{j \in k} I[j]} \quad [8]$$

The voltage and current phasors are based on the voltages and currents measured by the distributed control units 36 and sent to the central control unit 34.

b. Then the equivalent load impedance of the k^{th} bus is added to the reference impedance matrix Z_{M0} as follows (shown by block B of the central control unit 34 in Figure 6):

$$Z_{MNew}[i][j] = Z_{M0}[i][j] - \frac{Z_{M0}[i][k]Z_{M0}[k][j]}{Z_{M0}[k][k] + z_L[k]} \quad [9]$$

- c. If an electrical link is disconnected from the electrical network 20, the information about the disconnection of the electrical link can be obtained from the status of the corresponding breaker(s). For example, if the branch between the first and second buses 22, 24 is disconnected (where the impedance of this branch is Z_{T1}), such
 5 disconnection means that an equivalent impedance value of $-Z_{T1}$ is effectively added between the first and second buses. So, if the branch between the k^{th} and n^{th} buses is disconnected, the modification of the reference impedance matrix Z_{M0} is given by:

$$Z_{MNew}[i][j] = Z_{M0}[i][j] + \frac{(Z_{M0}[i][n] - Z_{M0}[i][k])(Z_{M0}[k][j] - Z_{M0}[n][j])}{Z_{M0}[k][k] + Z_{M0}[n][n] - 2Z_{M0}[k][n] - z_{kn}} \quad [10]$$

- After the online determination of the real-time impedance matrix Z_{MD} , the central
 10 control unit 34 then transmits the real-time impedance matrix Z_{MD} to each distributed control unit 36. Thereafter, each distributed control calculates the equivalent source voltage E_{TH} and the equivalent impedance Z_{TH} seen by the corresponding overcurrent relay using the real-time impedance matrix and the measured voltage and current of the corresponding feeder 30.
- 15 The calculation of the equivalent source voltage E_{TH} and the equivalent impedance Z_{TH} seen by the corresponding overcurrent relay can be performed using two methods, which are shown as follows.

Method I:

Firstly the equivalent load impedance of the feeder 30 is given by:

$$20 \quad Z_{Feeder} = \frac{V_R}{I_R} \quad [11]$$

Wherein V_R and I_R are the measured voltage and current of the corresponding feeder 30.

Next, a value of $-Z_{Feeder}$ is added to the real-time impedance matrix Z_{MD} , which was received from the central control, as shown by:

$$Z_{MDNew}[i][j] = Z_{MD}[i][j] - \frac{Z_{MD}[i][k]Z_{MD}[k][j]}{Z_{MD}[k][k] - z_{Feeder}} \quad [12]$$

In [12], the feeder 30 is connected on the k^{th} bus.

Finally the equivalent source voltage E_{TH} and the equivalent impedance Z_{TH} are given by:

$$5 \quad Z_{TH} = Z_{MDNew} [k][k] \quad [13]$$

$$E_{TH} = V_R + Z_{TH} I_R \quad [14]$$

Method II:

Firstly the equivalent load impedance of the feeder 30 is obtained using [11] of Method I above.

10 Next, an equivalent injection current into the k^{th} bus is given by:

$$I_{Ink} = \frac{V_R}{Z_{MD}[k][k] - z_{Feeder}} \quad [15]$$

In [15], the feeder 30 is connected on the k^{th} bus.

Finally the equivalent source voltage E_{TH} and the equivalent impedance Z_{TH} are given by:

$$15 \quad E_{TH} = Z_{MD} \begin{bmatrix} 0 \\ \vdots \\ -I_{Ink} \\ \vdots \\ 0 \end{bmatrix} + V_R \quad [16]$$

$$Z_{TH} = \frac{E_{TH} - V_R}{I_R} \quad [17]$$

The determination of the equivalent source voltage E_{TH} and the equivalent impedance Z_{TH} seen by the corresponding overcurrent relay allows each distributed control unit 36 to calculate the new protection criterion of the corresponding overcurrent relay and then update the protection criterion for the corresponding overcurrent relay.

- 5 In this manner the protection criterion for each overcurrent relay is adapted to correspond to the new topological structure of the electrical network 20, thus avoiding the mal-operation or loss of protection of the overcurrent relays.

It will be appreciated that the topology of the electrical network 20 of Figure 1 is merely chosen to help illustrate the working of the invention, and the invention is applicable to
10 electrical networks with other topologies.

It will also be appreciated that the overcurrent relays of the electrical network 20 of Figure 1 is merely chosen to help illustrate the working of the invention, and the invention is applicable to other types of protection devices.

- For example, a given protection device may be in the form of a distance protection relay, where the relevant protection criterion may be or may include a reach setting value of the distance protection relay. Following a change in the topological structure of the electrical network 20, the reach setting value may be updated based on the equivalent impedance Z_{TH} seen by the distance protection relay. By updating the reach setting value, this ensures that the desired distance protection zone of the distance
15 protection relay accurately corresponds to the new topological structure of the electrical network 20, and thereby avoids over-reach or under-reach of the distance protection zone of the distance protection relay. Otherwise, if the reach setting value of the distance protection relay is not updated following a change in the topological structure of the electrical network 20, the accuracy of the protection operation of the distance
20 protection relay may be adversely affected by an expansion or deflation of the actual distance protection zone.
- 25

CLAIMS:

1. A protection apparatus for protecting an electrical network (20), the protection apparatus comprising:

at least one protection device configured to protect the electrical network (20) from a fault in response to a or a respective protection criterion being met; and

a controller (34, 36) configured to: receive real-time information on a change in topological structure of the electrical network (20); perform an online determination of the real-time impedance or admittance matrix (Z_{MD}) of the electrical network (20) based on the change in topological structure of the electrical network (20); and adapt the or each protection criterion based on the real-time impedance or admittance matrix (Z_{MD}).

2. A protection apparatus according to Claim 1, wherein the change in topological structure of the electrical network (20) includes at least one of:

a connection of at least one electrical source (32) into the electrical network (20);

a disconnection of at least one electrical source (32) from the electrical network (20);

a connection of at least one electrical load (22, 24, 26, 30) into the electrical network (20);

a disconnection of at least one electrical load (22, 24, 26, 30) from the electrical network (20);

a connection of at least one previously open electrical link of the electrical network (20);

a disconnection of at least one previously closed electrical link of the electrical network (20);

an increase or decrease in power of at least one connected electrical load (22, 24, 26, 30) or at least one connected electrical source (32) of the electrical network (20).

3. A protection apparatus according to Claim 1 or Claim 2, wherein the controller (34, 36) is configured to adapt the or each protection criterion by determining an equivalent source voltage and/or an equivalent impedance or admittance seen by the or each protection device based on the real-time impedance or admittance matrix (Z_{MD}), and by determining the or each protection criterion based on the determined equivalent source voltage and/or equivalent impedance or admittance.

4. A protection apparatus according to Claim 3, wherein the controller (34, 36) is configured to adapt the or each protection criterion by determining an equivalent source voltage and/or an equivalent impedance or admittance seen by the or each protection device based on the real-time impedance or admittance matrix (Z_{MD}) and on measured voltage and current (V_R , I_R) of a part of the electrical network (20) corresponding to the or each protection device, and by determining the or each protection criterion based on the determined equivalent source voltage and/or equivalent impedance or admittance.

5. A protection apparatus according to Claim 3 or Claim 4, wherein the equivalent source voltage and the equivalent impedance or admittance are respectively the Thevenin equivalent source voltage (E_{TH}) and the Thevenin equivalent impedance or admittance (Z_{TH}).

6. A protection apparatus according to any one of the preceding claims, wherein the controller (34, 36) is configured to perform the online determination of the real-time impedance or admittance matrix (Z_{MD}) of the electrical network (20) by modifying a reference impedance or admittance matrix (Z_{M0}) of the electrical network (20) based on the change in topological structure of the electrical network so as to determine the real-time impedance or admittance matrix (Z_{MD}).

7. A protection apparatus according to Claim 6, wherein the controller (34, 36) is configured to receive information on the topological structure of the electrical network (20) and to perform a determination of the reference impedance or admittance matrix (Z_{M0}) prior to the change in topological structure of the electrical network (20).

8. A protection apparatus according to Claim 7, wherein the determination of the reference impedance or admittance matrix (Z_{M0}) is an offline determination of the reference impedance or admittance matrix (Z_{M0}).

9. A protection apparatus according to any one of Claims 6 to 8, wherein the reference impedance or admittance matrix (Z_{M0}) omits at least one electrical source (32) of the electrical network (20) and/or at least one electrical load (22, 24, 26, 30) of the electrical network (20).

10. A protection apparatus according to any one of the preceding claims, wherein the controller (34, 36) is configured to determine an equivalent impedance or admittance value of at least one component of the electrical network (20) and to combine the or each equivalent impedance or admittance value into the reference impedance or admittance matrix (Z_{M0}) by addition or subtraction so as to determine the real-time impedance or admittance matrix (Z_{MD}).

11. A protection apparatus according to Claim 10, wherein the or each equivalent impedance or admittance value is selected from a group including:

an equivalent load impedance or admittance of an electrical load (22, 24, 26, 30) of the electrical network (20);

an equivalent source impedance or admittance of an electrical source (32) of the electrical network (20);

an equivalent impedance or admittance of an electrical link of the electrical network (20).

12. A protection apparatus according to any one of the preceding claims, wherein the controller (34, 36) includes a first control unit (34) and at least one second control unit (36), the first control unit (34) in communication with the or each second control unit (36), the or each second control unit (36) associated with the or the respective protection device, wherein the first control unit (34) is configured to: receive real-time information about a part of the electrical network (20) corresponding to the or each protection device from the or each second control unit (36); and perform the online

determination of the real-time impedance or admittance matrix (Z_{MD}) based on the received real-time information from the or each second control unit (36).

13. A protection apparatus according to Claim 12, wherein the first control unit (34) is configured to transmit the real-time impedance or admittance matrix (Z_{MD}) to the or each second control unit (36), and the or each second control unit (36) is configured to adapt the or each protection criterion based on the real-time impedance or admittance matrix (Z_{MD}).

14. A protection apparatus according to any one of the preceding claims, wherein the or each protection device is or includes an overcurrent relay, and the or each protection criterion is or includes a fault level of a circuit interruption device associated with the overcurrent relay and/or a setting value of the overcurrent relay, or wherein the or each protection device is or includes a distance protection relay, and the or each protection criterion is or includes a reach setting value of the distance protection relay.

15. A method of operating a protection apparatus for protecting an electrical network (20), the protection apparatus comprising at least one protection device configured to protect the electrical network (20) from a fault in response to a or a respective protection criterion being met, the method including the steps of:

receiving real-time information on a change in topological structure of the electrical network (20);

performing an online determination of the real-time impedance or admittance matrix (Z_{MD}) of the electrical network (20) based on the change in topological structure of the electrical network (20); and

adapting the or each protection criterion based on the real-time impedance or admittance matrix (Z_{MD}).

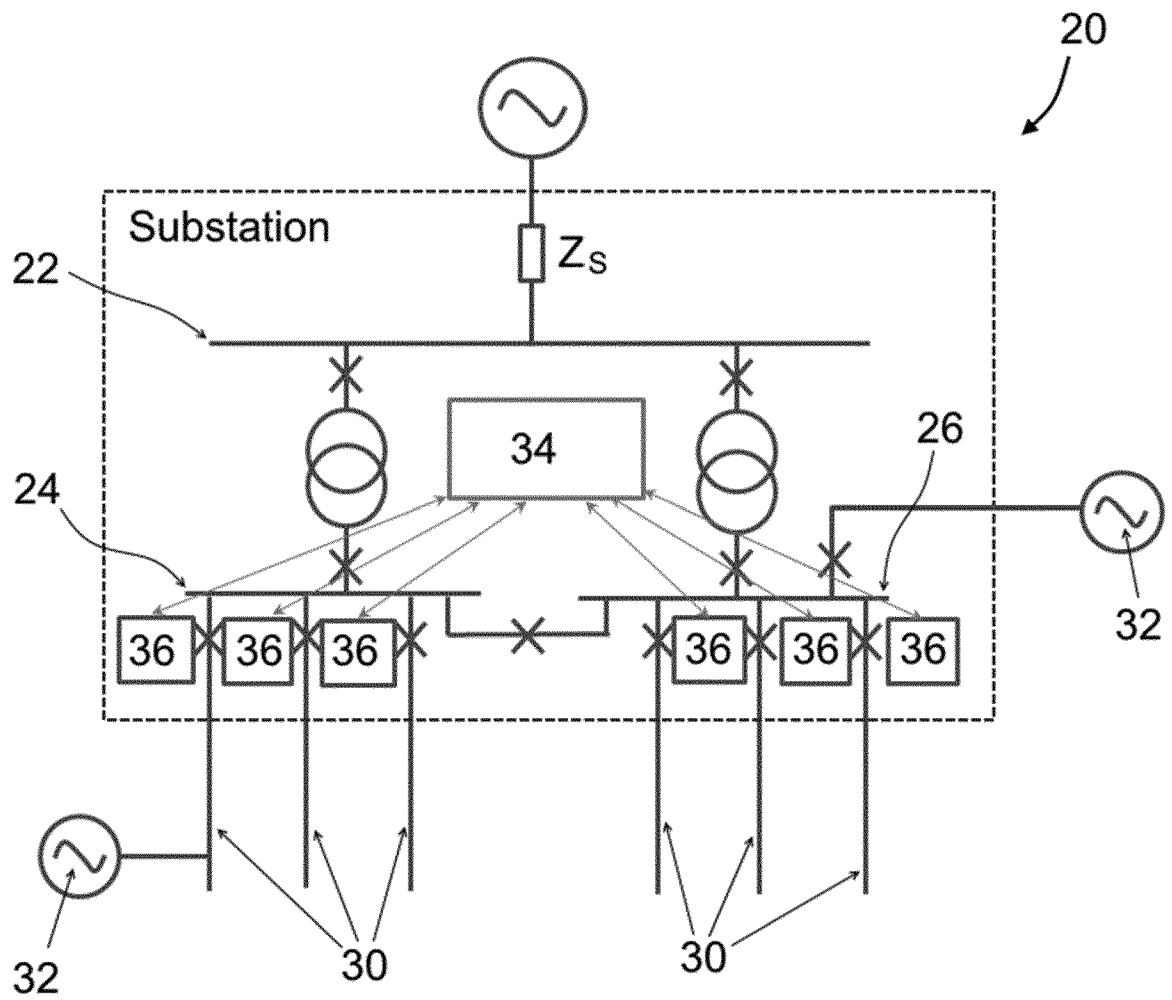


Figure 1

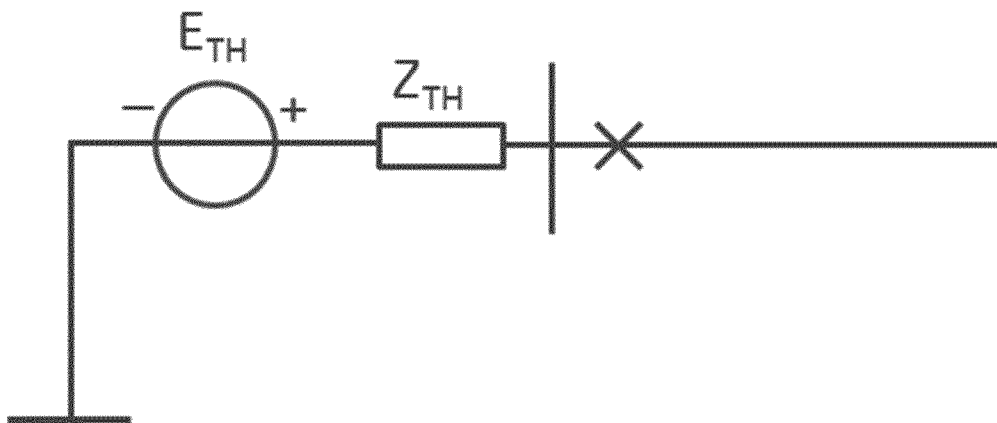


Figure 2

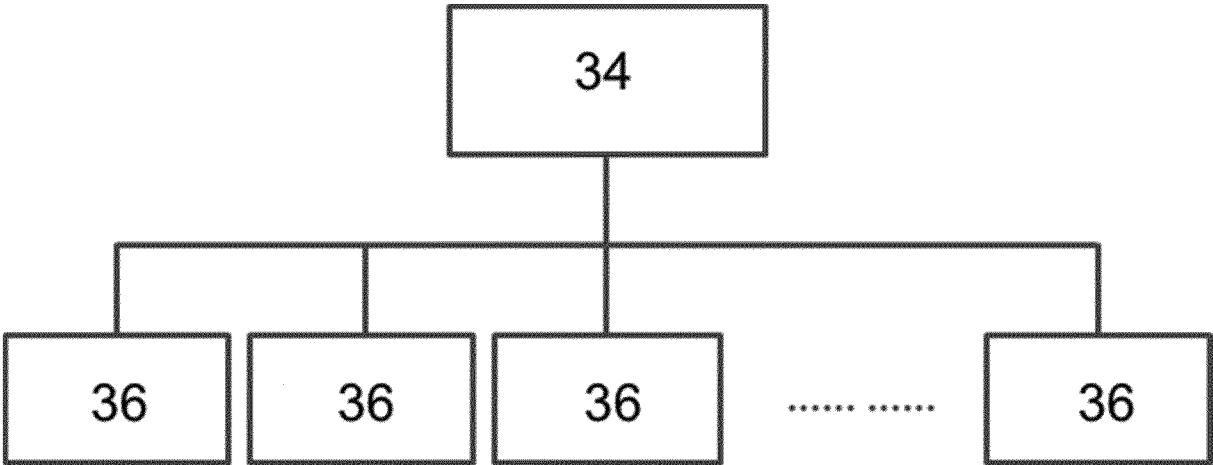


Figure 3

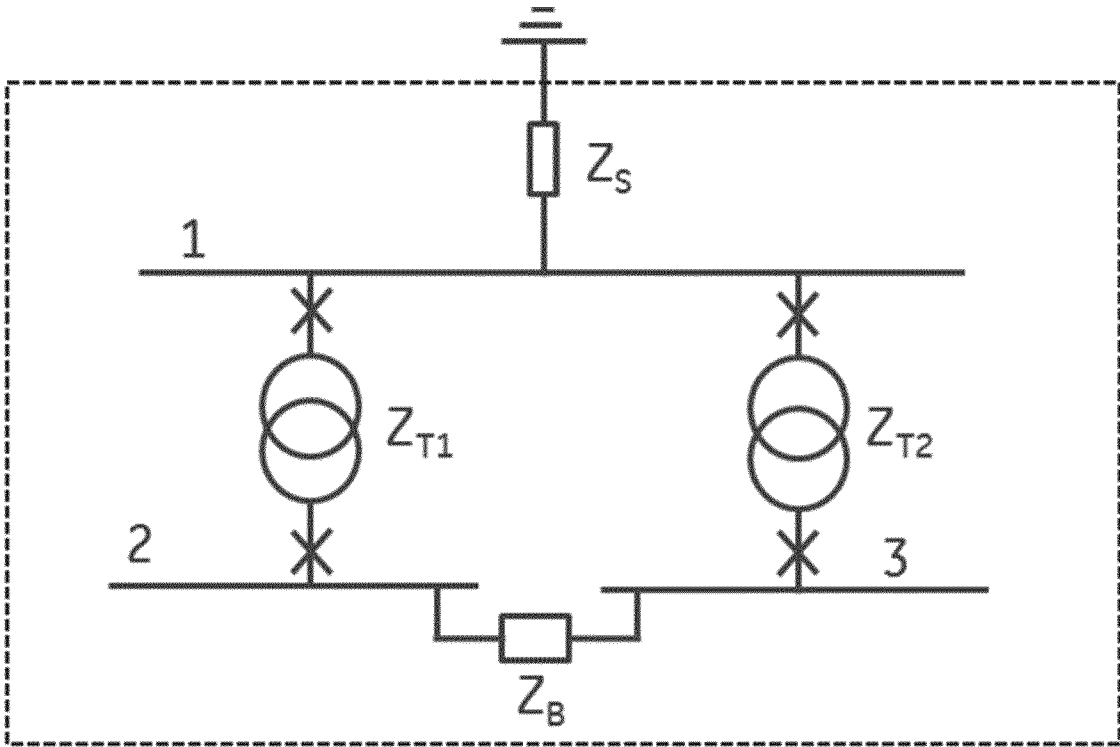


Figure 4

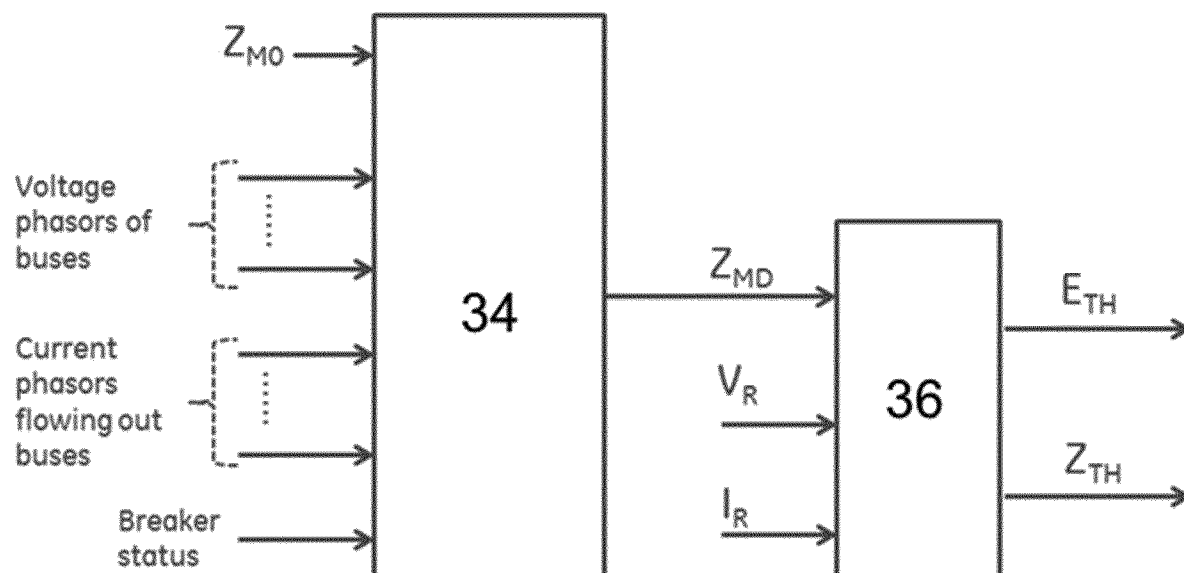


Figure 5

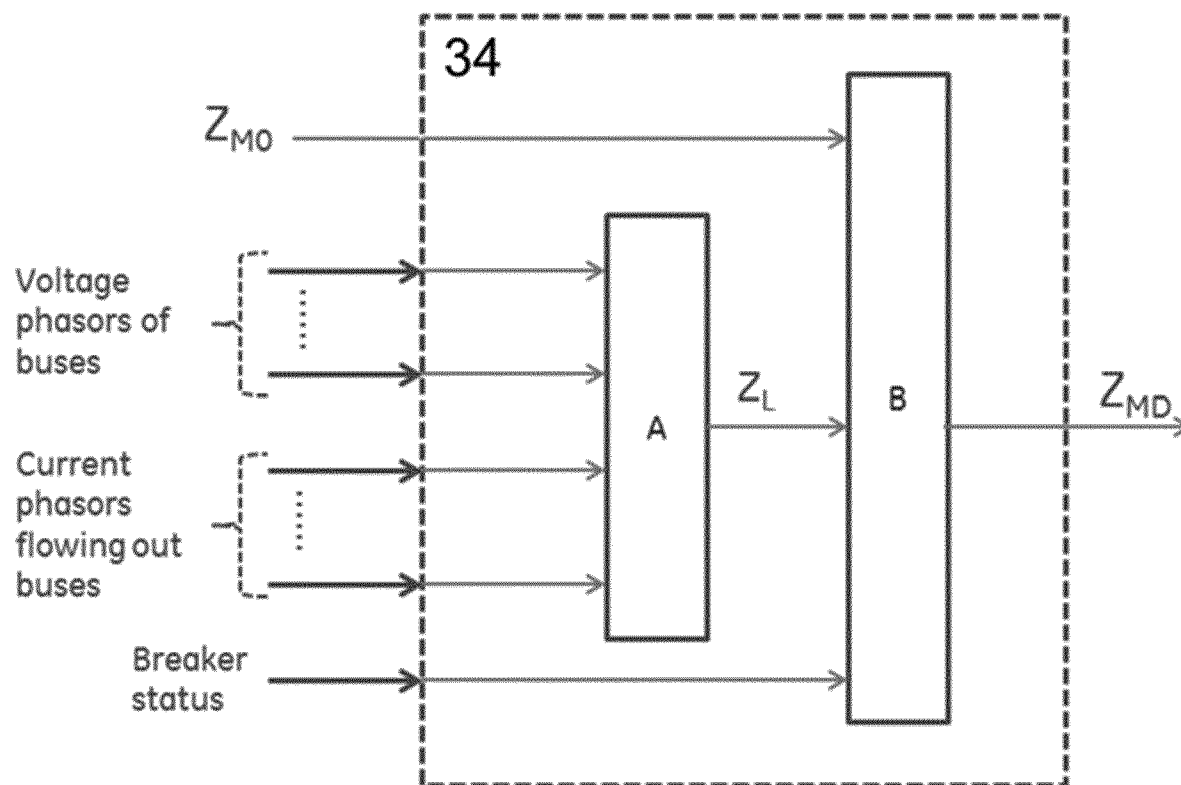


Figure 6

INTERNATIONAL SEARCH REPORT

International application No

PCT/EP2017/070328

A. CLASSIFICATION OF SUBJECT MATTER

INV. H02H3/00 H02H7/26
 ADD. H02H3/08 H02H3/40

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
 H02H

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X A	US 2015/346286 A1 (JANSSEN PIERRE [BE] ET AL) 3 December 2015 (2015-12-03) abstract; figures 1,2 paragraphs [0002], [0007] - [0022], [0051] - [0063] -----	1-9, 12-15 10,11
X	US 2016/116522 A1 (ABIDO MOHAMMAD ALI YOUSEF [SA] ET AL) 28 April 2016 (2016-04-28) abstract; figures 2,5 paragraphs [0008], [0021] - [0038] -----	1-7,14, 15
X	CN 102 403 792 A (UNIV TIANJIN TECHNOLOGY) 4 April 2012 (2012-04-04) the whole document -----	1-4,6, 12-15



Further documents are listed in the continuation of Box C.



See patent family annex.

* Special categories of cited documents :

"A" document defining the general state of the art which is not considered to be of particular relevance

"E" earlier application or patent but published on or after the international filing date

"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)

"O" document referring to an oral disclosure, use, exhibition or other means

"P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

"&" document member of the same patent family

Date of the actual completion of the international search

2 November 2017

Date of mailing of the international search report

17/11/2017

Name and mailing address of the ISA/

European Patent Office, P.B. 5818 Patentlaan 2
 NL - 2280 HV Rijswijk
 Tel. (+31-70) 340-2040,
 Fax: (+31-70) 340-3016

Authorized officer

Palukova, Mila

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No

PCT/EP2017/070328

Patent document cited in search report	Publication date	Patent family member(s)	Publication date	
US 2015346286	A1	03-12-2015	CN 104380554 A	25-02-2015
			EP 2845286 A1	11-03-2015
			RU 2014152062 A	10-08-2016
			US 2015346286 A1	03-12-2015
			WO 2014000769 A1	03-01-2014

US 2016116522	A1	28-04-2016	NONE	

CN 102403792	A	04-04-2012	NONE	
