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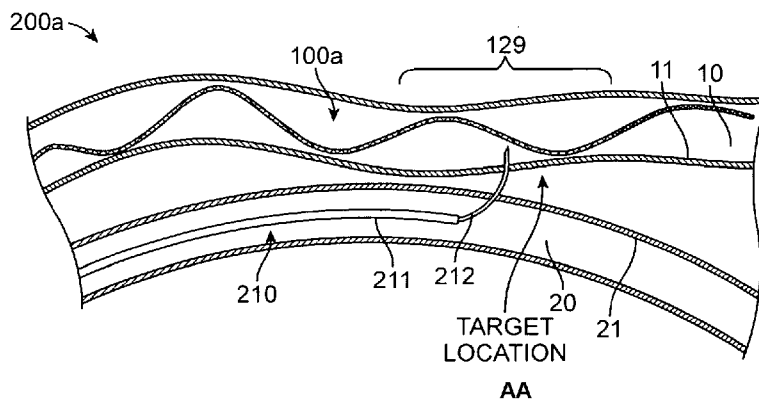


FIG. 2b

(57) Abstract: Devices, systems and methods are described for visualizing the anatomy of a patient. An expanding portion is configured to expand towards the tissue walls of a body space and be visible with one or more visualization instruments. Systems and methods are described which advance a probe from a first vessel toward a target in a second vessel.

DEVICES, SYSTEMS AND METHODS FOR ENHANCED VISUALIZATION OF THE ANATOMY OF A PATIENT

BACKGROUND OF THE INVENTION

5 [0001] Field of the Invention. The present invention relates to devices, systems and methods for enhancing the visualization of a location within a patient's body that is surrounded by one or more tissue walls, hereinafter a "body space". Devices with expanding portions locate tissue walls and are visualized with standard imaging equipment. More particularly, the present invention relates to a system for advancing a probe from a first body
10 space, such as a first vessel, toward a second body space, such as a second vessel. Patients include human beings as well as other mammalian species.

[0002] Numerous medical procedures require the visualization and/or measurement of a body space such as the space inside the stomach, a chamber of the heart or the lumen of a blood vessel. Imaging systems such as those using X-ray or ultrasound may be insufficient
15 by themselves in providing accurate size and relative position information to a clinician performing a medical procedure.

[0003] Procedures including the implantation of a medical device often require three-dimensional body space information in order to properly select or size the implant. Procedures involving the access of a body space, such as the accessing of a lumen of a blood
20 vessel from another blood vessel, require information regarding the specific location and orientation of the target vessel walls and lumen.

[0004] For these and other reasons, there is a need for devices, systems and methods which provide enhanced visualization of body spaces of a patient. Desirably the devices will be minimally invasive and have little or no side effects for the patient.

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BRIEF SUMMARY OF THE INVENTION

[0005] According to a first aspect of the invention, an anatomy visualization device is disclosed. The device includes an elongate filament with an expandable portion. The expandable portion is configured for insertion into a body space of a patient, such as an artery
30 or vein of a patient. The body space is surrounded by one or more tissue walls. The expandable portion is further configured to radially expand to the one or more tissue walls.

The expandable portion includes one or more markers, and/or is constructed of material that can be visualized by a visualization instrument such as a fluoroscope or other x-ray visualization apparatus; an ultrasound visualization apparatus; a CT-scanner; a magnetic resonance imaging apparatus (MRI); a positron emission tomography (PET) scanner; an electromagnetic (EM) field detection apparatus; and combinations of these. The expanded portion material and/or markers may include one or more of: radiopaque material; electromagnetic components; magnets; ultrasonically reflective material; and/or other material configured to be visualized with one or more visualization instruments configured to visualize material within a body of a patient. A predetermined visualizable portion or marker size may be used to allow a clinician a reference to measure one or more structures in images taken. The one or more structures to be measured may be device structures and/or anatomical structures. Two or more markers may be placed on the visualization device with a known distance of separation.

[0006] The anatomy visualization device can be used to provide real time anatomical information, such as the location, shape, size and other geometric information related to a body space or the tissue walls of a body space. These types of information can be useful in numerous clinical procedures performed on a patient, such as information including but not limited to: vessel geometry information such as diameter, curvilinear shape and other vessel geometry information useful in an angioplasty, stenting, atherectomy and other vessel diagnostic or therapeutic procedures; fistula and intended fistula site information such as information regarding a preferred location for a fistula to be created and/or a needle or other probe to be advanced from a first vessel to a second vessel such as to create a fistula during a TIPS procedure or a cardiopulmonary therapy procedure. A visualization instrument may be included to visualize the expanded portion. The visualization instrument may be selected from the group consisting of: a fluoroscope or other x-ray visualization apparatus; an ultrasound visualization apparatus; a Ct-scanner; a magnetic resonance imaging apparatus (MRI); a PET scanner; an electromagnetic (EM) field detection apparatus; and combinations of these.

[0007] The elongate filament may have a flexible construction such as a guidewire construction configured to navigate the vasculature of a patient. The elongate filament may be constructed of one or more biocompatible materials, such as Nitinol, stainless steel, and/or one or more polymers, and may include a coating or covering such as a hydrophobic, hydrophilic or polytetrafluoroethylene (PTFE) coating and/or a PTFE covering. The elongate filament may include a lumen from its proximal end to its distal end, such as to allow a

guidewire, mandrel or other device to be inserted therethrough. A spiral or otherwise curved mandrel can be used to cause the expandable portion of the elongate filament to expand toward one or more of the patient's body space tissue walls. A sheath, including a distal end, may surround the expandable portion, such that longitudinal advancement of the expanded portion or retraction of the sheath causes the expandable portion to exit the distal end of the sheath. The expandable portion may be resiliently biased such that as exiting the distal end of the sheath, the expandable portion transitions from a constrained condition to an expanded condition. The expandable portion may include a single filament, such as a filament which is in a helical spiral when expanded. The expandable portion may include two or more filaments, such as multiple tines which are configured to radially expand, such as when a surrounding sheath is manipulated to expose the multiple tines.

[0008] The expandable portion expands to one or more tissue walls of a body space of a patient. A clinician may visualize the expanded portion and use the image as a target for advancing a probe, or for performing one or more other medical events or diagnostic assessments. The expandable portion may include one or more shape memory materials. The shape memory materials may be configured to expand due to a temperature change, such as a change from room temperature to body temperature. The shape memory materials may expand when heated, such as by passing a current through a resistive shape memory material. The expandable portion may be configured to be mechanically activated, such as via contraction by a pull wire, or insertion of a shaped mandrel such as a mandrel elastically biased in a helical spiral shape that is inserted into a linear elongate filament. The expandable portion may be magnetically or electromagnetically expanded.

[0009] The anatomy visualization device may be configured to provide structural support to one or more tissue walls, such as the expandable portion providing radial support configured to prevent collapse of the tissue walls. The expandable portion may be configured to be constrained, compacted or otherwise unexpanded, such as to allow removal from the patient's anatomy. The anatomy visualization device may be configured to enter arteries and/or veins of the patient, as well as other body spaces including but not limited to: a chamber of the heart; the stomach; the urethra; the biliary duct; and other body cavities.

[0010] The anatomy visualization device may include a handle on its proximal end, such as a handle with one or more controls. A control may be configured to perform one or more operations, such as an operation selected from the group consisting of: advance or retract a filament; cause radial expansion or contraction; deliver energy such as energy delivered to a fistula site; apply positive pressure or vacuum; and combinations of these. The handle may

include one or more markings. The markings may be visual and/or tactile markings. The markings may provide information to the operator such as information related to: advancement or retraction of a filament; amount of expansion of a visualization device expandable portion such as the amount of radial expansion; amount of force applied to tissue walls by a visualization device; amount of advancement or retraction of a probe such as a needle; and combinations of these.

[0011] According to another aspect of the invention, a system for advancing a probe from a first vessel into a second vessel at a target location in a patient is disclosed. The system includes a probe advancement device and an anatomy visualization device. The probe advancement device includes an elongate tube with a proximal end and a distal end, and an advanceable probe. The probe advancement device is configured to be placed intraluminally in a first vessel. The anatomy visualization device includes a target portion and is configured to be placed intraluminally in a second vessel. The probe of the probe advancement device is configured to be advanced from the first vessel toward the target portion of the anatomy visualization device, and into the second vessel. The probe may exit the distal end of the elongate tube or through a side hole proximal to the distal end. The probe may comprise a needle or other hollow tube configured to penetrate through tissue toward a target. The probe may deliver a separate device, such as a guidewire, or may deliver a therapeutic agent such as a pharmaceutical agent.

[0012] The first vessel and second vessel may be arteries or veins. In a preferred embodiment, one of the vessels is an artery selected from the group consisting of: femoral artery; internal iliac artery; external iliac artery; subclavian artery; and the aorta. In another preferred embodiment, one of the vessels is a vein selected from the group consisting of: femoral vein; internal iliac vein; external iliac vein; subclavian vein; and the inferior vena cava. The target location may be an intended location for a fistula to be created, such as a fistula created over a guidewire placed through the probe of the probe advancement device. The fistula may be a therapeutic fistula, such as a fistula created to treat one or more of: chronic obstructive pulmonary disease (COPD); congestive heart failure; heart failure; hypertension; hypotension; coronary artery disease; respiratory failure; lung fibrosis; adult respiratory distress syndrome (ARDS); chronic bronchitis; emphysema; cystic fibrosis; cystic lung disease; and chronic asthma. Alternatively or additionally, the fistula may be created to allow continued removal or administration of blood, such as is needed in a dialysis procedure. Alternatively or additionally, the fistula may be used to deliver a drug or other agent from one vessel to another vessel.

[0013] The system may include a dilation device, such as a balloon integral to the probe advancement device. The system may include an anastomotic clip, such as an anastomotic clip delivered by a delivery catheter or the probe advancement device. The system may include a device configured to snare or otherwise capture the probe advancement device probe, once the probe has been advanced into the second vessel. The probe capture device may be integral to the anatomy visualization device, such as when the anatomy visualization device includes a collapsible cage configured to capture the advanced probe. The capture device can be configured to retract the advanced probe, or a guidewire or other filament advanced through the probe, proximal in the second vessel, distal in the second vessel, or both proximal and distal.

[0014] According to yet another aspect of the invention, a method of advancing a probe from a first vessel to a second vessel at a target location in a patient is disclosed. A probe advancement device is placed into the first vessel. The probe advancement device includes an elongate tube with a proximal end and a distal end, and an advanceable probe. An anatomy visualization device, including a target portion, is placed into the second vessel. The target portion of the anatomy visualization device is advanced intraluminally to a target location of the patient's anatomy. The probe of the probe advancement device is transluminally advanced toward the target portion and into the second vessel. The probe advancement device may be intraluminally advanced in the first vessel, prior to advancing the probe into the second vessel. After the probe is advanced into the second vessel, the visualization device can be removed, while maintaining access of the probe into the second vessel. Alternatively or additionally, a guidewire or other filament can be placed through the probe into the second vessel, and the visualization device removed while maintaining access to the second vessel by the guidewire or other filament. The anatomy visualization device may be configured to capture the advanced probe, or a device advanced through the probe. The capturing portion may include a collapsible basket configured to snare the probe or other filament passing from the first vessel into the second vessel.

BRIEF DESCRIPTION OF THE DRAWINGS

[0015] The accompanying drawings, which are incorporated in and constitute a part of this specification, illustrate various embodiments of the present invention, and together with the description, serve to explain the principles of the invention. In the drawings:

[0016] Fig. 1a illustrates a side sectional view of an anatomy visualization device in an unexpanded state and inserted into a body space, consistent with the present invention;

[0017] Fig. 1b illustrates the anatomy visualization device of Fig. 1a in an expanded state;

[0018] Fig. 2a illustrates a side sectional view of a probe advancement system including an anatomy visualization device including a spiral portion and inserted into an artery, and a probe advancement device inserted into a neighboring vein, consistent with the present invention;

[0019] Fig. 2b illustrates the system of Fig. 2a with a probe advanced into the artery;

[0020] Fig. 2c illustrates the system of Figs. 2a and 2b, with a guidewire advanced through the probe and down the lumen of the artery;

[0021] Fig. 3 illustrates a side sectional view of a probe advancement system including an anatomy visualization device including an expandable cage and inserted into an artery, and a probe advancement device inserted into a neighboring vein, consistent with the present invention;

[0022] Fig. 4a illustrates a side sectional view of a probe advancement system including an anatomy visualization device including a lumen and inserted into an artery, and a probe advancement device inserted into a neighboring vein, consistent with the present invention;

[0023] Fig 4b illustrates the system of Fig. 4a further including an imaging apparatus and a spiral mandrel that has been inserted into the lumen of the anatomy visualization device;

[0024] Fig. 5 illustrates a side sectional view of a probe advancement system including the anatomy visualization device of Fig. 2a inserted into an artery; and a probe advancement device including a catheter and advanced from the neighboring vein into the artery, consistent with the present invention;

[0025] Fig. 6 illustrates a side sectional view of a probe advancement system including the anatomy visualization device of Fig. 2a inserted into an artery; and a probe advancement device including a radiation delivery device and advanced from the neighboring vein into the artery, consistent with the present invention.

[0026] Fig. 7 illustrates a perspective view of an anatomy visualization device with an open cell design, consistent with the present invention.

DETAILED DESCRIPTION OF THE INVENTION

[0027] Reference will now be made in detail to the present embodiments of the invention, examples of which are illustrated in the accompanying drawings. Wherever possible, the

same reference numbers will be used throughout the drawings to refer to the same or like parts.

[0028] Visualization Instruments such as X-Ray units, fluoroscopes, ultrasound imagers, CT-scanners, PET scanners, and magnetic resonance imagers (MRIs) provide historic and real time imaging of a patient's anatomy. These images are used by a clinician performing one or more medical procedures on the patient. In addition to use in patient diagnosis, these images are often used to size a medical device such as a tool or an implant, or to navigate the patient's anatomy, such as in an interventional or surgical procedure. The anatomy visualization devices of the present invention provide additional information to those images.

The devices of the present invention may be used to measure the diameter of a vessel, such as for an angioplasty or stenting procedure. The devices of the present invention can be used to enhance navigation through the body, such as with real-time visualization information used to manipulate a needle or other probe to penetrate a vessel, preferably toward the visualization device. Such procedures include percutaneous fistula creation procedures and transjugular intrahepatic portosystemic shunt (TIPS) procedures. The devices of the present invention can be used in percutaneous procedures, such as procedures which enter the body through an access sheath, or a surgical procedure such as a minimally invasive or laparoscopic surgical procedure.

[0029] The systems and methods of the present invention are used to visualize a body space, and also to access that body space from another location such as a second body space. In a preferred embodiment, the first body space is a blood vessel such as an artery, and the second body space is second blood vessel such as a vein. Such access can be used to place a guidewire, over which one or more tools can be placed. These tools may include a needle or catheter such as to deliver agents such as drugs. These tools may include a therapeutic probe, such as a flexible probe with a radiation delivery element at its tip. These tools may also include dilation devices and/or anastomosis devices such as to create a fistula between the two body spaces. The fistula may be created to provide a dialysis access site, or the fistula may provide the therapy. Methods and devices for performing arteriovenous fistula therapy (AVF), are described in the following co-pending applications, each of which is incorporated in its entirety herein by reference: 10/820,169; 11/961,731; 11/152,284; 11/013,981; 11/152,621; 11/151,802; 11/282,341; 11/356,876; 11/696,635; 11/946,454; and 12/017,437.

[0030] Referring to Fig. 1a, an anatomy visualization device of the present invention is illustrated. Visualization device 100 is inserted into body space 50, such as the stomach cavity, a chamber of the heart, a lumen of a blood vessel, the urethra, the esophagus, or the

biliary duct. Body space 50 includes first wall 51 and second wall 52. One or more portions of visualization device 100 are visible in the images provided by a visualization instrument. Visualization instruments commonly found in hospitals and other health care centers include but are not limited to: X-rays and fluoroscopes; ultrasound imagers; CT-scanners; PET
5 scanners; and other non-invasive or minimally invasive visualization instruments.

Visualization device 100 includes sheath 101 which is in an advanced position such that distal end of helical filament 124 is constrained within sheath 101. Filament 124 is flexible, preferably of guidewire construction well known to those of skill in the art, and includes distal portion 121. Filament 124 is made of a biocompatible material such as Nitinol,
10 stainless steel, cobalt chrome and/or a polymer or a polymer blend. Filament 124 may include one or more coatings or coverings, such as a hydrophilic or hydrophobic coating, or a polytetrafluoroethylene (PTFE) coating or covering. Filament 124 includes two markers, 126a and 126b, preferably radiopaque markers but alternatively markers such as ultrasonically reflective and/or magnetic markers. In a preferred embodiment, distal portion
15 121 is radiopaque and markers 126a and 126b provide a darker image than distal portion 121 in an X-ray. Alternatively or additionally, one or more portions or the entirety of device 100 may be covered by a radiopaque coil or material, such as coverings of different radiopacity which are used to distinguish different portions of device 100.

[0031] Referring now to Fig. 1b, the visualization device 100 of Fig. 1a is shown with
20 sheath 101 retracted such as via a control on a handle, control and handle not shown but preferably on the proximal end of visualization device 100. After sheath 101 is retracted, distal portion 121 radially expands. In a preferred embodiment, distal portion 121 is elastically biased in the helical spiral shown, such that retraction of sheath 101 causes distal portion 121 to transition from its near linear constrained condition shown in Fig. 1a, to the
25 expanded helical geometry shown in Fig. 1b. In an alternative embodiment, distal portion 121 may be temperature activated, such as via a body temperature activated shaped memory alloy. In another alternative embodiment, distal portion 121 is activated by a mechanical mechanism such as an internal pullwire or inserted shaped mandrel. Distal portion 121 has expanded sufficiently to engage wall 51 and wall 52 of body space 50, such that an image of
30 distal portion 121 will indicate the position of walls 51 and 52, which may be invisible or difficult to visualize with the imaging technology used. As shown in Fig. 1b, markers 126a and 126b are positioned such as to contact opposing walls, such as opposing points along the wall of a blood vessel. The length of marker 126a and/or 126b can be used to measure a part of the patient's anatomy, such as via a comparative measurement. Alternatively or

additionally, the distance between marker 126a and 126b may be used as a measuring tool.

Distal portion 121 is shown with a multiple turn helix. In alternative embodiments, a partial helix (i.e. less than 360 degrees) may be employed. Distal portion 121 is configured to radially collapse, such as through advancement of sheath 101, and be atraumatically

5 withdrawn from the patient. The diameter of the helix of distal portion 121 is sized based on the anatomy in which visualization device 100 is intended to visualize. The spiral section 121 is typically oversized 1-2 mm over the body space where the device is intended to be deployed. For a device intended to be placed in the iliac artery its expanded size is preferably between 8 and 10 mm. However, the diameter could be any size, typically from 2 to 25mm.

10 The length of the helix of distal portion 121 is typically 30 mm, preferably between 10 and 60 mm. Distal to target portion 129 is straight portion 132. In one embodiment, straight portion 132 is of similar diameter and construction to target portion 129. In an alternative embodiment, target portion has a smaller diameter than straight portion 132, such as to reduce the radial force exerted by target portion 129 upon walls 51 and 52, while maintaining the trackability of visualization device 100. Straight portion 132 typically has a length of 1 to 10
15 cm, preferably 4 to 7 cm and may be constructed similar to an interventional guidewire.

[0032] Referring now to Figs. 2a through 2c, a probe advancement system of the present invention is illustrated. Probe advancement system 200a includes visualization device 100a and probe advancement device 210. Visualization device 100a has been placed in artery 10,

20 and probe advancement device 210 has been placed in vein 20, each such as via a percutaneous vessel access sheath common to interventional medical procedures. A Target Location is chosen for advancement of a probe from vein 20 to artery 10. One reason for choosing the Target Location shown is the proximity of artery 10 to vein 11 at the target location. As is illustrated, artery 10 and vein 11 diverge from each other away from the

25 Target Location, such that the Target Location will have the shortest length fistula within the region shown. The visualization devices and probe advancement devices of the present invention, including visualization device 100a and probe advancement device 210, include one or more visualizable portions (e.g. radiopaque portions, ultrasonically reflective portions, electromagnetically visible portions, etc.), such that positioning of the appropriate portions of
30 visualization device 100a and probe advancement device 210, can be performed with standard visualization instruments such as fluoroscopy. In a preferred embodiment, an advanceable probe is radiopaque and a distal target portion of the visualization device is radiopaque, such that the probe can be advanced toward the target portion.

[0033] In an alternative embodiment, a probe is advanced from an artery to a vein. In a preferred embodiment, a fistula is to be created at the Target Location. Alternatively or additionally, the Target Location may be chosen to deliver drugs into artery 20 or deliver radiation in artery 20 at the Target Location. A fistula may be created to provide an access site for dialysis. A fistula may alternatively be created for therapeutic shunting of arterial blood into the venous system, such as to treat a cardiopulmonary disease or disorder. Cardiopulmonary conditions applicable to the devices, systems and methods of the present invention include but are not limited to: chronic obstructive pulmonary disease (COPD); congestive heart failure; heart failure; hypertension; hypotension; coronary artery disease; respiratory failure; lung fibrosis; adult respiratory distress syndrome (ARDS); chronic bronchitis; emphysema; cystic fibrosis; cystic lung disease; and chronic asthma ; and combinations of these. Visualization device 100a preferably includes a handle on its proximal end, not shown but typically including one or more controls such as to deploy the spiral at its distal end. Probe advancement device 210 also preferably includes a handle on its proximal end, not shown but typically including one or more controls such as to advance a probe at its distal end. Handles of the present invention may include multiple controls to activate or control multiple functions from outside the skin of the patient, such as to advance or retract a filament, cause radial expansion or contraction, deliver energy such as energy delivered to a fistula site; apply positive pressure or vacuum, or other functions common to interventional medical devices. Handles of the present invention may include markings or other visual, tactile or other feedback to allow an operator to precisely control one or more of: advancement or retraction of a filament; amount of expansion of a visualization device distal portion such as the amount of radial expansion; amount of force applied to tissue walls by a visualization device; and amount of advancement or retraction of a probe such as a needle.

[0034] Referring specifically to Fig. 2a, visualization device 100a has been positioned such that target portion 129 is proximate to a target location for the advancement of a probe between artery 10 and vein 20. Target portion 129, preferably a radiopaque portion of visualization device 100, is a visualizable target used by a clinician to orient an advanceable probe, needle 212, of probe advancement device 210. As shown in Fig. 2a, needle 212 is currently contained within sheath 211 (not yet advanced).

[0035] Referring specifically to Fig. 2b, needle 212 has been slidingly advanced out of sheath 211 in the curved pathway shown, such as via a control on a handle, handle and control not shown but preferably on the proximal end of probe advancement device 210. Needle 212 may be elastically biased in the curved geometry and/or a deflecting member, not

shown but within sheath 211 may deflect needle 212 in the pathway shown. Needle 212 has penetrated wall 21 of vein 20 and wall 11 of artery 10, toward target portion 129. In addition to providing a visual target for the advancement of needle 212, visualization device 100 provides measurement information such as the diameter of artery 10 via measurement of a coiled section of visualization device 100. The probe of Figs. 2a, 2b and 2c, needle 212 exits the distal end of a shaft, sheath 211. In an alternative embodiment, a probe is configured to exit proximal to the distal end of the shaft, such as via a side hole 2 - 50mm from the distal end of the shaft.

[0036] Referring specifically to Fig. 2c, guidewire 213 has been advanced through needle and into the lumen of artery 10. In subsequent steps, probe advancement device 210 can be removed leaving guidewire 213 in place, such as to act as a rail for future devices passing from vein 20 to artery 10. Such over-the-wire devices include but are not limited to: balloon catheters; anastomotic clip delivery catheters; drug deliver catheters; blood sampling catheters; radiation delivery devices; and combinations of these. In a preferred embodiment, a fistula is created and an anastomotic clip is placed, described in detail in reference to co-pending application 11/696,635 incorporated in its entirety herein by reference. Visualization device 100a and the other visualization devices of the present invention may be configured to allow one or more devices, such as needle 212, guidewire 213 and/or any device passing from vein 20 to artery 10, to remain in place when visualization device 100a is retracted and/or removed. During retraction, target portion 129 unwinds to prevent applying a force to any device passing through the spiral of target portion 129. In an alternative embodiment, a target or other distal portion of a visualization device may be configured to capture one or more devices passing through it, such as is described in reference to Fig. 3 herebelow.

[0037] Referring now to Fig. 3, yet another probe advancement system of the present invention is illustrated. Probe advancement system 200b includes visualization device 100b and probe advancement device 210. Visualization device 100b has been placed in artery 10, and probe advancement device 210 has been placed in vein 20, each such as via a percutaneous vessel access sheath common to interventional medical procedures. A target location, as has been described in reference to Figs. 2a through 2c, is chosen for advancement of a probe from vein 20 to artery 10. In an alternative embodiment, a probe is advanced from an artery to a vein, from a first chamber of the heart to a second chamber of the heart, or from any location (including locations external to the patient's body) to a body space as has been defined hereabove. In a preferred embodiment, a fistula is to be created between an artery and a vein at a target location. Alternatively or additionally, the target location may be

chosen to deliver drugs into artery 20, deliver radiation in artery 20 at or near the target location, and/or perform a medical procedure, including therapeutic and diagnostic procedures, at or near the target location. Visualization device 100c may include a handle on its proximal end, not shown but typically including one or more controls such as to advance and retract cage 123. Probe advancement device 210 also preferably includes a handle on its proximal end, not shown but typically including one or more controls such as to advance a probe at its distal end.

[0038] Visualization device 100b includes elongate, flexible sheath 122 which slidingly surrounds filament 127. Filament 127 includes distal portion 121 which comprises a basket design, expandable cage 123, resiliently biased in the expanded condition illustrated.

Expandable cage 123 may take on various forms, including but not limited to basket, cage and stent-like geometries. Retraction of filament 127 into sheath 122, such as via a control on a handle fixedly attached to the proximal end of visualization device 100b, handle and control not shown, causes cage 123 to be captured and constrained within sheath 122.

Advancement of filament 127 causes cage 123 to exit the distal end of sheath 122, radially expanding as it exits to contact luminal wall 11 of artery 10. Cage 123 is configured to be visualized under fluoroscopy or other imaging means, such that the location and geometry of the body space tissue walls, luminal walls 11 of artery 10, are clearly identified, positioned and sized. Cage 123 and other components of the present invention can have their radiopacity enhanced by placing a radiopaque coil over a portion of the device, such as over the struts of the cage. The expandable distal portions of the visualization devices of the present invention, including cage 123 of Fig. 3, may be configured to expand to a range of diameters of vessel walls, without significantly deflecting those walls or otherwise altering the normal anatomical topography. Alternatively, the distal portions may be configured to radial expand to a fixed or small range of diameters, such as to provide an enhanced radial force. Application of large radial forces may be used to assist in advancement of a probe, such as a needle, toward the distal portion (e.g. to prevent the collapse of one or more tissue walls).

[0039] Probe advancement device 210, inserted in vein 20, includes flexible sheath 211 which slidingly surrounds an advanceable probe, needle 212 shown having been advanced out of sheath 211, through venous wall 21, through arterial wall 11 and into the lumen of the artery toward cage 123. Needle 212 is advanced out of the distal end of sheath 211 in the curved geometry shown, as has been described above in reference to Figs. 2a–2c. Once advanced into the lumen of artery 10, needle 212 can be used to perform one or more medical

procedures, such as agent delivery, radiation delivery, or blood sampling, or needle 212 can be used to advance an elongate medical device, such as a guidewire, a catheter, or any therapeutic, diagnostic or other medical probe configured to pass through needle 212. In a preferred embodiment, as has been described in detail hereabove and in co-pending application 11/696,635 incorporated in its entirety herein by reference, a guidewire is introduced over which dilation and/or anastomosis forming devices are placed to create a long term fistula.

[0040] In an alternative embodiment, the distal portion of the visualization devices of the present invention, such as cage 123 of visualization device 100b, may be configured to capture an advanced probe such as an advanced needle or guidewire. Cage 123 may be partially collapsed such that a device (e.g. needle 212, a guidewire or other advanceable filament) is frictionally engaged by one or more struts of cage 123. After sufficient capture force is achieved, the advanceable probe (e.g. a guidewire) can be moved proximally or distally within artery 10 with retraction or advancement, respectively, of visualization device 100b. Capturing of an advanced probe, such as a guidewire placed from vein to artery, can be used to provide distal support when advancing a device such as a balloon catheter or anastomotic clip delivery catheter over the guidewire through tissue. In an alternative embodiment, visualization device 100b is configured to prevent capture of an advanced probe, such that visualization device 100b can be removed from the vasculature without applying force to the advanced probe. The visualization device of Fig. 7 herebelow includes an open cell design which avoids capture of a device passed there within or along the visualization device. Visualization device 100b preferably includes a handle on its proximal end, not shown but typically including one or more controls such as to advance and retract cage 123.

[0041] Referring now to Figs. 4a and 4b, yet another probe advancement system of the present invention is illustrated. Probe advancement system 200c includes visualization device 100c and probe advancement device 210. Visualization device 100c has been placed in artery 10, and probe advancement device 210 has been placed in vein 20, each such as via a percutaneous vessel access sheath common to interventional medical procedures. A target location, as has been described in reference to Figs. 2a through 2c, is chosen for advancement of a probe from vein 20 to artery 10. In an alternative embodiment, a probe is advanced from an artery to a vein, from a first chamber of the heart to a second chamber of the heart, or from any location (including locations external to the patient's body) to a body space as has been defined hereabove. In a preferred embodiment, a fistula is to be created between an artery

and a vein at a target location. Alternatively or additionally, the target location may be chosen to deliver drugs into artery 20, deliver radiation in artery 20 at or near the target location, and/or perform a medical procedure, including therapeutic and diagnostic procedures, at or near the target location.

5 [0042] Referring specifically to Fig. 4a, visualization device 100c is shown in a near linear configuration. Visualization device 100c includes an elongate filament, hollow tube 128, which includes lumen 131. The end of hollow tube 128 is closed such that a device inserted into lumen 131 will not exit the distal end of hollow tube 128. Probe advancement device 210 is shown with needle 212 contained within a lumen of sheath 211. The distal end of
10 sheath 211 is curved, and has not yet been oriented toward the target location in artery 10.

[0043] Referring specifically to Fig. 4b, mandrel 125, elastically biased in a helical spiral, has been advanced to the end of lumen 128. Mandrel 125 provides sufficient forces to radially expand distal portion 121 of tube 128 causing the exterior portion of distal portion 121 to contact walls 11 of artery 10 in a helical pattern. Distal portion 121, visualizable such
15 as with a radiopaque substance visible under X-ray or fluoroscopy, can be used to size artery 10, locate a specific target site along artery 10, and provide other measurement and/or navigation functions. Mandrel 125 includes visualizable markers 126a and 126b, such as radiopaque markers that appear under X-ray at a different darkness than the other portions of distal portion 121.

20 [0044] The systems of the present invention preferably include one or more visualization instruments and the anatomy visualization devices, probe advancement devices and other system devices and components of the present invention are configured, at least in part, to be visualized by these visualization instruments. The systems of the present invention may be configured to work with one or more visualization systems such as X-ray systems such as
25 fluoroscopes, ultrasound visualization systems, MRIs, and other visualization systems commonly found in healthcare centers such as hospitals. System 200c of Fig. 4b further includes visualization instrument 250 which includes fluoroscope 251 and monitor 252. Alternatively or additionally, instrument 250 may provide ultrasound images, CT-scans, MRI images, PET scans, and other forms of imaging found in hospitals and healthcare centers.
30 Fluoroscope 251 is pointed at the target site, through the Skin of the patient. Bi-plane fluoroscope may be used to create images at different orientations to the target site. Once an image of distal portion 121 is found, the distal, curved end of sheath 211 can be rotated such that as needle 212 is advanced toward the center of the lumen of artery 10. Fig. 4b illustrates probe advancement device having been oriented such that needle 212 will advance toward

distal portion 121, into the center of the lumen of artery 10. Visualization device 100c preferably includes a handle on its proximal end, not shown but typically including one or more controls such as to advance and retract mandrel 125. Probe advancement device 210 preferably includes a handle on its proximal end, not shown but typically including one or more controls such as to advance needle 212.

[0045] Referring now to Fig. 5, yet another probe advancement system of the present invention is illustrated. Probe advancement system 200d includes visualization device 100d and a probe advancement device, not shown but configured as has been described in reference to multiple figures hereabove. Visualization device 100d has been placed in artery 10, such as via a percutaneous vessel access sheath common to interventional medical procedures. A target location, as has been described in reference to Figs. 2a through 2c, is chosen for advancement of a probe from vein 20 to artery 10. Visualization device 100d preferably includes a handle on its proximal end, not shown but typically including one or more controls such as to advance and retract distal portion 121.

[0046] Visualization device 100d is shown in its radially expanded state, a multiple turn helical spiral. In an alternative embodiment, partial helixes (i.e. less than 360°) can be used. Distal portion 110 may be retracted into a sheath, sheath not shown but as been described in reference to multiple figures hereabove, such that distal portion 110 is restrained in a near linear geometry. Distal portion 121, visualizable such as with a radiopaque substance visible under X-ray or fluoroscopy, can be used to size artery 10, locate a specific target site along artery 10, and provide other measurement and/or navigation functions. Additional markers may be included in distal portion 121 or at another location along visualization device 110d, such as to measure and/or located diameters of artery 10 and or longitudinal distances along artery 10.

[0047] As has been described in reference to Figs. 2a-2c, a guidewire 213 has been placed from vein 20 to artery 10. A flexible probe device, catheter 230 has been advanced over guidewire 213, through lumen 231, such that the distal end of catheter 230 resides in the lumen of artery 10. Dilation of the vein wall 21, artery wall 11, and the tissue in-between, may have been performed (e.g. over guidewire 213 with a balloon or debulking catheter), to aid in advancement of catheter 230 into artery 10. Alternatively, catheter 230 may have a sharpened or otherwise penetrating tip, or may have an inserted penetrating element such as a sharp mandrel, all not shown. Agents delivered into a lumen of catheter 230 from its proximal end (proximal end not shown but preferably containing an attached handle with an infusion port in fluid communication with the lumen), pass around guidewire 213 and are

delivered into the lumen of artery 10. Guidewire 213 may be removed during the agent delivery process, and may be replaced to remove catheter 230 leaving guidewire 230 in place. Agents, such as pharmaceutical or other liquid or solid agents, may be delivered for site specific delivery at the location of distal portion 121. In an alternative embodiment, other matter such as magnetic particles or implantable medical devices may be delivered through the lumen of catheter 230. After the proper amounts of agents have been delivered, catheter 230 is removed. Guidewire 213 may also be removed at that time, or left in place for insertion of another over-the-wire device.

[0048] Referring now to Fig. 6, yet another probe advancement system of the present invention is illustrated. Probe advancement system 200e includes visualization device 100e and a probe advancement device, not shown but configured as has been described in reference to multiple figures hereabove. Visualization device 100e has been placed in artery 10, such as via a percutaneous vessel access sheath common to interventional medical procedures. A target location, as has been described in reference to Figs. 2a through 2c, is chosen for advancement of a radioactive probe from vein 20 to artery 10. Visualization device 100e preferably includes a handle on its proximal end, not shown but typically including one or more controls such as to advance and retract distal portion 121.

[0049] Visualization device 100e is shown in its radially expanded state, a multiple turn helical spiral. In alternative embodiment, partial helixes (i.e. less than 360°) can be used. Distal portion 110 may be retracted into a sheath, sheath not shown but as been described in reference to multiple figures hereabove, such that distal portion 110 is restrained in a near linear geometry. Distal portion 121, visualizable such as with a radiopaque substance visible under X-ray or fluoroscopy, can be used to size artery 10, locate a specific target site along artery 10, and provide other measurement and/or navigation functions. Additional markers may be included in distal portion 121 or at another location along visualization device 110e, such as to measure and/or located diameters of artery 10 and or longitudinal distances along artery 10.

[0050] As has been described in reference to Figs. 2a-2c, guidewire 213 has been placed from vein 20 to artery 10. A flexible probe device, radiation delivery device 240 has been advanced over guidewire 213, through lumen 241, such that the distal end of catheter 230 resides in the lumen of artery 10. Dilation of the vein wall 21, artery wall 11, and the tissue in-between, may have been performed (e.g. over guidewire 213 with a balloon or debulking catheter), to aid in advancement of radiation delivery device 240 into artery 10. Alternatively, device 240 may have a sharpened or otherwise penetrating tip, or may have an

inserted penetrating element such as a sharp mandrel, all not shown. Radiation delivery device 240 includes radioactive element 242 near its distal end, positioned within the lumen of artery 10. Radiation delivery device 240 remains in place for a time sufficient to deliver the radioactive energy, such as to treat and/or prevent neointimal proliferation or other vessel narrowing at the target location. After the proper amount of radiation has been delivered, radiation delivery device 240 is removed. Guidewire 213 may also be removed at that time, or left in place for insertion of another over-the-wire device.

[0051] Referring now to Fig. 7, another embodiment of an anatomy visualization device of the present invention is illustrated. Anatomy visualization device 100f includes distal portion 121. Distal portion 121 includes target portion 129 comprising multiple filaments, tines 133, configured in an open cell design, such as to avoid capturing one or more filaments or other devices advanced toward target portion 129. The proximal ends of tines 133 are fixedly attached to shaft 102 and distal portion 121 by band 134. Alternatively, tines 133 may be cut from a single tube integral to distal portion 121. Target portion 129 is shown having exited the distal end of sheath 101 (e.g. via retraction of sheath 101) causing the distal ends of tines 133 to extend radially outward, such as to contact the walls of a body space such as an artery or a vein. Tines 133 may be recaptured such as via retraction of shaft 102 and/or advancement of sheath 101. Tines 133 are made of a visualizable material or include one or more visualizable markers, not shown. In a preferred embodiment, tines 133 include a radiopaque material or include one or more radiopaque markers, such that tines 133 can be visualized under fluoroscopy or other x-ray equipment to assist a clinician in locating a body space or a portion of a body space.

[0052] It should be understood that numerous other configurations of the devices, systems and methods described herein can be employed without departing from the spirit and scope of this application. Numerous figures have illustrated typical dimensions, but it should be understood that other dimensions can be employed which result in similar functionality and performance. The devices and systems of the present invention may be used to perform various procedures including medical procedures such as the creation of an arteriovenous fistula.

[0053] The anatomy visualization devices of the present invention include a target portion which is used to direct the advancement of an advanceable probe such as an advanceable needle and/or a guidewire. The target portion may be located at any location along the device, typically near the distal end. Target portion may be self-expanding, or may be expanded by mechanical or other means, such as via introduction of a shaped mandrel. The

anatomy visualization devices of the present invention may be configured to be removed while the advanceable probe is located within or alongside the target portion, such as to leave the probe in place for a subsequent action or procedural step. Alternatively, the anatomy visualization devices of the present invention may be configured to capture or otherwise
5 apply a retaining force to a probe advanced near or through the anatomy visualization device, such as to maintain position of the advanceable probe during a subsequent action or procedural step.

[0054] The devices described above may include one or more markers, such as radiopaque, ultrasonic, magnetic or other visualizable markers, to assist in visualizing the device during
10 use. The entire device may be radiopaque or one or more portions, such as the target portion, are radiopaque. The device may include one portion with a first radiopacity, and a second portion with a radiopacity different than the first radiopacity, such as to distinguish one portion from another during a medical procedure. Radiopaque coatings or coils may include materials such as tungsten, platinum, gold, and/or a doped polymer such as a polymer
15 including barium sulfate. The devices described above may be provided with coatings or additional structures which serve as matrices for various therapeutic compounds. Drug eluting coatings, additional drug eluting members, drug eluting membranes surrounding tubular sections or drug eluting masses that fill integrated chambers or wells may be added to the devices.

[0055] While the preferred embodiments of the devices and methods have been described
20 in reference to the environment in which they were developed, they are merely illustrative of the principles of the inventions. Modification or combinations of the above-described assemblies, other embodiments, configurations, and methods for carrying out the invention, and variations of aspects of the invention that are obvious to those of skill in the art are
25 intended to be within the scope of the claims.

WHAT IS CLAIMED IS:

1 1. An anatomy visualization device comprising:
2 an elongate filament with a proximal end, a distal end, and an expandable
3 portion, said expandable portion configured for insertion into a body space of a patient;
4 wherein the body space is surrounded by one or more tissue walls; and
5 wherein the expandable portion is configured to radially expand toward the
6 one or more tissue walls, said expandable portion further configured to be visualized while
7 expanded toward the one or more tissue walls.

1 2. The device of claim 1 wherein the device provides real time
2 visualization of the body space.

1 3. The device of claim 1 wherein the device is configured to provide
2 information selected from the group consisting of: vessel geometry information such as
3 diameter, curvilinear shape and other vessel geometry information useful in an angioplasty,
4 stenting, atherectomy and other vessel diagnostic or therapeutic procedures; fistula and
5 intended fistula site information such as information regarding a preferred location for a
6 fistula to be created and/or a needle or other probe to be advanced from a first vessel to a
7 second vessel such as to create a fistula during a TIPS procedure or a cardiopulmonary
8 therapy procedure.

1 4. The device of claim 1 further comprising a visualization instrument
2 configured to visualize the expanded portion and selected from the group consisting of: a
3 fluoroscope or other x-ray visualization apparatus; an ultrasound visualization apparatus; a
4 Ct-scanner; a magnetic resonance imaging apparatus (MRI); a PET scanner; an
5 electromagnetic (EM) field detection apparatus; and combinations thereof.

1 5. The device of claim 1 wherein the elongate filament is a flexible
2 filament.

1 6. The device of claim 1 wherein the elongate filament has a guidewire
2 construction.

1 7. The device of claim 1 wherein the elongate filament is constructed of
2 materials selected from the group consisting of: Nitinol; stainless steel; Tungsten, CoCr a
3 polymer or polymer blend; and combinations thereof.

1 8. The device of claim 1 wherein the elongate filament includes one or
2 more of a hydrophobic coating; a hydrophilic coating; a PTFE coating; a PTFE covering; and
3 combinations thereof.

1 9. The device of claim 1 wherein the elongate filament includes a
2 proximal end and a distal end with a lumen from said proximal end to a location at or near
3 said distal end.

1 10. The device of claim 9 further comprising a mandrel configured to be
2 inserted in the lumen.

1 11. The device of claim 10 wherein expandable portion is configured to
2 radially expand when the mandrel is inserted into the lumen.

1 12. The device of claim 1 wherein the expandable portion includes a target
2 portion, said target portion configured to be placed at a target location.

1 13. The device of claim 12 wherein the target location in an anatomical
2 location selected for a penetrating probe to advance into.

1 14. The device of claim 12 wherein the target portion radially expands
2 toward the tissue walls.

1 15. The device of claim 12 wherein the target portion is a spiral geometry.

1 16. The device of claim 15 wherein the spiral has a diameter range of
2 approximately 2mm to 25mm.

1 17. The device of claim 16 wherein the spiral has a diameter range of 8mm
2 to 10mm.

1 18. The device of claim 15 wherein the filament includes a straight portion
2 distal to the target portion.

1 19. The device of claim 18 wherein the straight portion has a length of
2 4cm to 7cm.

1 20. The device of claim 1 wherein the expandable portion is configured to
2 transition from a constrained condition to a radially expanded condition.

1 21. The device of claim 20 further comprising a sheath with a distal end;
2 wherein the sheath is configured to slidingly receive the expandable portion;
3 and
4 wherein the expandable portion transitions from the constrained condition to
5 the radially expanded condition as it exits the distal end of the sheath.

1 22. The device of claim 21 wherein the expandable portion comprises a
2 single filament which radially expands to a helical geometry.

1 23. The device of claim 21 wherein the expandable portion comprises at
2 least two filaments, each comprising a proximal end and a distal end, wherein said filament
3 distal ends extend radially out when exiting the sheath distal end.

1 24. The device of claim 23 wherein the expandable portion further
2 comprises a band surrounding said filament proximal ends.

1 25. The device of claim 23 wherein the tines are cut from a cylindrical
2 tube shaped into the expandable portion.

1 26. The device of claim 1 wherein the expandable portion is configured to
2 approximate the tissue walls of the body space when radially expanded.

1 27. The device of claim 1 wherein the expandable portion is elastically
2 biased in the radially expanded condition.

1 28. The device of claim 1 wherein the expandable portion is temperature
2 activated to radially expand.

1 29. The device of claim 28 wherein the temperature activation occurs at
2 body temperature.

1 30. The device of claim 1 wherein the expandable portion is mechanically
2 activated to radially expand.

1 31. The device of claim 30 further comprising a mandrel, wherein the
2 mechanical activation is achieved when the mandrel is inserted within the expandable
3 portion.

1 32. The device of claim 1 wherein the expandable portion is in a helical
2 geometry when radially expanded.

1 33. The device of claim 32 wherein the expandable portion transitions
2 from a linear or near linear geometry to said helical geometry.

1 34. The device of claim 32 wherein the helical geometry includes more
2 than 360° of helix.

1 35. The device of claim 32 wherein the helical geometry has a diameter of
2 at least 2mm.

1 36. The device of claim 35 wherein the helical geometry has a diameter of
2 approximately 8mm to 10mm.

1 37. The device of claim 32 wherein the helical geometry has a diameter
2 between 2mm and 25mm.

1 38. The device of claim 32 wherein the helical geometry has a length of
2 10mm to 60mm.

1 39. The device of claim 32 wherein the helical geometry has a length of
2 approximately 30mm.

1 40. The device of claim 1 wherein the expandable portion is configured to
2 transform from an approximately linear geometry to a helical geometry.

1 41. The device of claim 40 further comprising a sheath with a distal end;
2
3 wherein the sheath is configured to slidably receive the expandable portion;
4 and
5 wherein the expandable portion transitions from the approximately linear
6 geometry to the helical geometry as it exits the distal end of the sheath.

1 42. The device of claim 1 wherein the expandable portion comprises an
2 expandable basket or an expandable cage.

1 43. The device of claim 1 wherein the expandable portion is
2 electromagnetically expandable.

- 1 44. The device of claim 1 wherein the expandable portion is radiopaque.
- 1 45. The device of claim 1 wherein the expandable portion includes a
2 marker selected from the group consisting of: a radiopaque marker; an electromagnetic
3 marker; a magnetic marker; an ultrasonically reflective marker; and combinations thereof.
- 1 46. The device of claim 1 wherein said device is further configured to
2 provide radial force at the expandable portion.
- 1 47. The device of claim 46 wherein the expandable portion is configured
2 to prevent collapse of the tissue walls.
- 1 48. The device of claim 1 wherein the expandable portion is configured to
2 radially collapse.
- 1 49. The device of claim 48 wherein the expandable portion is configured
2 to be removed from the patient after said radial collapse.
- 1 50. The device of claim 1 wherein the tissue walls are vessel walls.
- 1 51. The device of claim 50 wherein the vessel walls are walls of an artery
2 or vein.
- 1 52. The device of claim 1 wherein the elongate filament is configured to be
2 inserted percutaneously.
- 1 53. The device of claim 52 wherein the insertion is performed through a
2 guide catheter.
- 1 54. The device of claim 1 wherein the elongate filament is configured to be
2 inserted in a surgical procedure.
- 1 55. The device of claim 54 wherein the surgical procedure is a minimally
2 invasive surgical procedure.
- 1 56. The device of claim 1 wherein the filament is configured for insertion
2 into a body space selected from the group consisting of: blood vessel lumen; chamber of the
3 heart; stomach; urethra; body cavity; and biliary duct.
- 1 57. The device of claim 1 further comprising at least one marker.

1 58. The device of claim 57 wherein the marker is selected from the group
2 consisting of: radiopaque; ultrasonic; electromagnetic; and combinations thereof.

1 59. The device of claim 57 wherein the marker is included in the
2 expandable portion.

1 60. The device of claim 57 wherein the length of the marker is used to
2 measure a portion of the patient's anatomy.

1 61. The device of claim 57 comprising a first marker and a second marker,
2 wherein the distance between the first marker and second marker is used to measure a portion
3 of the patient's anatomy.

1 62. The device of claim 1 wherein said device includes a proximal end, a
2 distal end, and a handle attached to the proximal end, said handle including at least one
3 control.

1 63. The device of claim 62 wherein the at least one control is configured
2 to: advance or retract a filament; cause radial expansion or contraction; deliver energy such as
3 energy delivered to a fistula site; apply positive pressure or vacuum; and combinations
4 thereof

1 64. The device of claim 62 where the handle includes one or more
2 markings.

1 65. The device of claim 64 wherein the markings are selected from the
2 group consisting of: visual markings; tactile markings; and combinations thereof.

1 66. The device of claim 64 wherein the markings are configured to provide
2 information related to: advancement or retraction of a filament; amount of expansion of a
3 visualization device expandable portion such as the amount of radial expansion; amount of
4 force applied to tissue walls by a visualization device; amount of advancement or retraction
5 of a probe such as a needle; and combinations thereof.

1 67. A system for advancing a probe from a first vessel into a second vessel
2 at a target location in a patient comprising:
3 a probe advancement device comprising:
4 an elongate tube with a proximal end and a distal end; and

5 an advanceable probe;

6 wherein the distal end is configured to be placed intraluminally in a first
7 vessel;

8 an anatomy visualization device of any of claims 1 through 66 configured to
9 be placed intraluminally in a second vessel;

10 wherein the probe is configured to be advanced from the first vessel toward
11 the target portion of the anatomy visualization device and into the second vessel.

1 68. The system of claim 67 wherein the probe is configured to exit the
2 distal end of the elongate tube.

1 69. The system of claim 67 wherein the probe is configured to exit at a
2 location proximal to the distal end of the elongate tube.

1 70. The system of claim 67 wherein the elongate tube includes a lumen
2 from the proximal end to distal end, and the probe is slidably received by said lumen.

1 71. The system of claim 67 wherein the probe is a hollow core needle.

1 72. The system of claim 71 further comprising a guidewire with a distal
2 end, said system configured to advance said distal end through the probe into the second
3 vessel.

1 73. The system of claim 72 wherein the probe advancement device is
2 configured to be removed leaving the guidewire traversing the first vessel into the second
3 vessel.

1 74. The system of claim 73 wherein the guidewire is configured to allow a
2 fistula creation device pass over said guidewire and expand to create a fistula between the
3 first vessel and the second vessel.

1 75. The system of claim 71 further comprising a catheter with a distal end,
2 said catheter distal end configured to be advanced through the probe into the second vessel.

1 76. The system of claim 71 further comprising an agent, said system
2 configured to deliver the agent through the probe into the second vessel.

1 77. The system of claim 67 wherein the probe includes a radiation delivery
2 element.

- 1 78. The system of claim 67 wherein the probe comprises a guidewire.
- 1 79. The system of claim 67 wherein the probe comprises a catheter.
- 1 80. The system of claim 79 wherein the probe further comprises a mandrel
2 slidingly received by the catheter, said probe including a tip sharpened to penetrate from the
3 first vessel to the second vessel.
- 1 81. The system of claim 67 wherein the probe advancement device further
2 comprises a handle on the proximal end of the elongate tube.
- 1 82. The system of claim 81 wherein the handle includes a control
2 configured to advance the probe.
- 1 83. The system of claim 81 wherein the handle includes one or more
2 markings configured to illustrate the position of the probe.
- 1 84. The system of claim 67 wherein the first vessel is an artery.
- 1 85. The system of claim 84 wherein the second vessel is a vein.
- 1 86. The system of claim 67 wherein the second vessel is an artery.
- 1 87. The system of claim 86 wherein the first vessel is a vein.
- 1 88. The system of claim 67 wherein the first and second vessels are
2 arteries.
- 1 89. The system of claim 67 wherein the first and second vessels are veins.
- 1 90. The system of claim 67 wherein the first vessel or the second vessel is
2 an artery selected from the group consisting of: femoral artery; internal iliac artery; external
3 iliac artery; subclavian artery; and the aorta.
- 1 91. The system of claim 67 wherein the first vessel or the second vessel is
2 a vein selected from the group consisting of: femoral vein; internal iliac vein; external iliac
3 vein; subclavian vein; and the inferior vena cava.
- 1 92. The system of claim 67 wherein the target location is an intended
2 anatomical location for a fistula to be created.

1 93. The system of claim 92 wherein the fistula is a therapeutic fistula.

1 94. The system of claim 93 wherein the therapy is tended to treat a patient
2 condition selected from the group consisting of: COPD; congestive heart failure; heart
3 failure; hypertension; hypotension; coronary artery disease; respiratory failure; lung fibrosis;
4 adult respiratory distress syndrome (ARDS); chronic bronchitis; emphysema; cystic fibrosis;
5 cystic lung disease; chronic asthma; and combinations thereof.

1 95. The system of claim 92 wherein the fistula is created to support
2 dialysis therapy.

1 96. The system of claim 67 wherein the target location is an intended
2 anatomical location for drug to be delivered.

1 97. The system of claim 96 wherein the drug is to be delivered into the
2 second vessel.

1 98. The system of claim 67 further comprising a dilation device configured
2 to expand tissue at the target location.

1 99. The system of claim 98 wherein the dilation device is integral to the
2 needle advancement assembly.

1 100. The system of claim 67 further comprising an anastomotic clip to be
2 deployed at the target location.

1 101. The system of claim 100 wherein the probe advancement device is
2 configured to deliver the anastomotic clip.

1 102. The system of claim 67 further comprising a probe capture device
2 configured to mechanically attach to at least a portion of the probe when said portion is in the
3 second vessel.

1 103. The system of claim 102 wherein the probe is a guidewire.

1 104. The system of claim 102 wherein the probe capture device can move
2 the probe proximally in the second vessel.

1 105. The system of claim 102 wherein the probe capture device can move
2 the probe distally in the second vessel.

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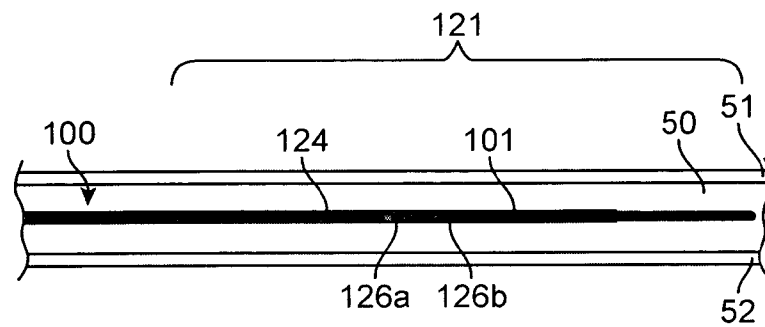


FIG. 1a

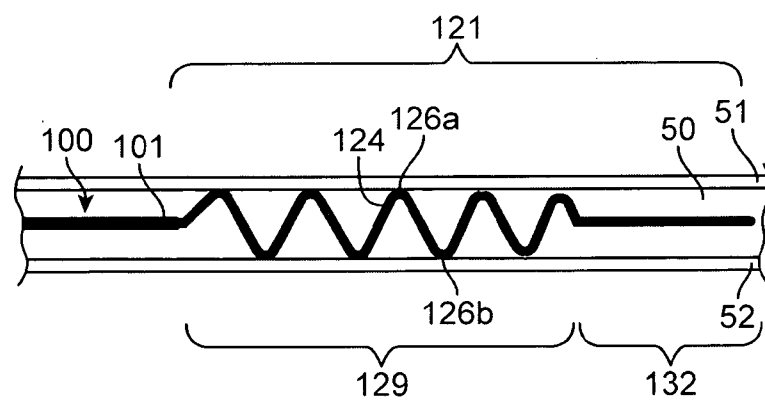


FIG. 1b

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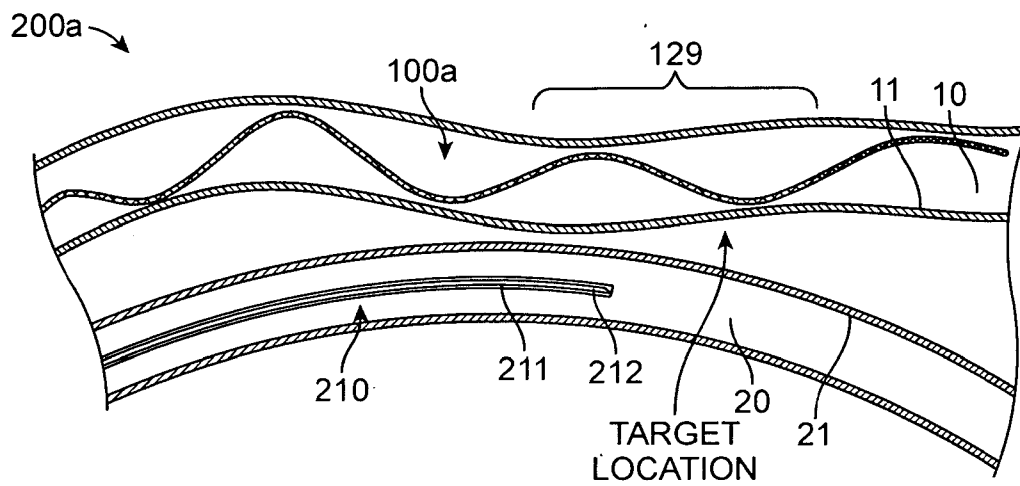


FIG. 2a

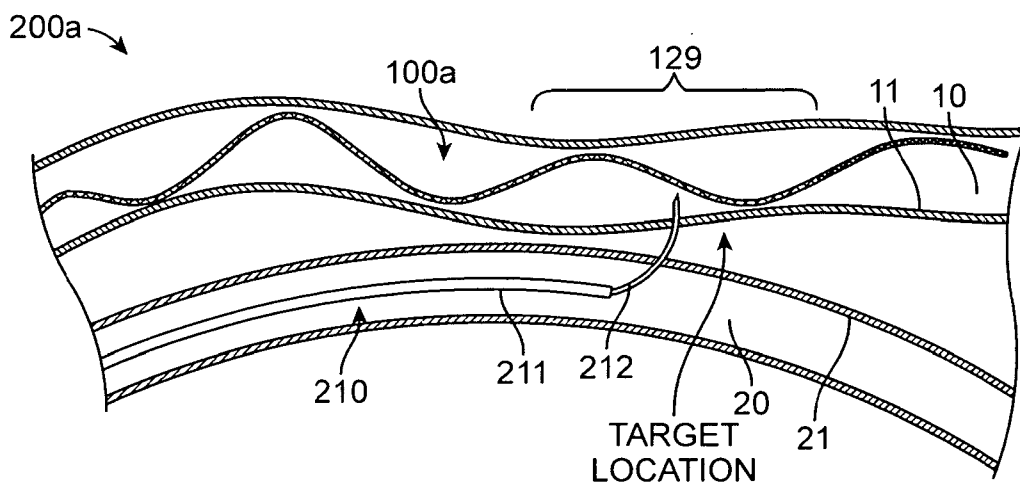


FIG. 2b

3 / 7

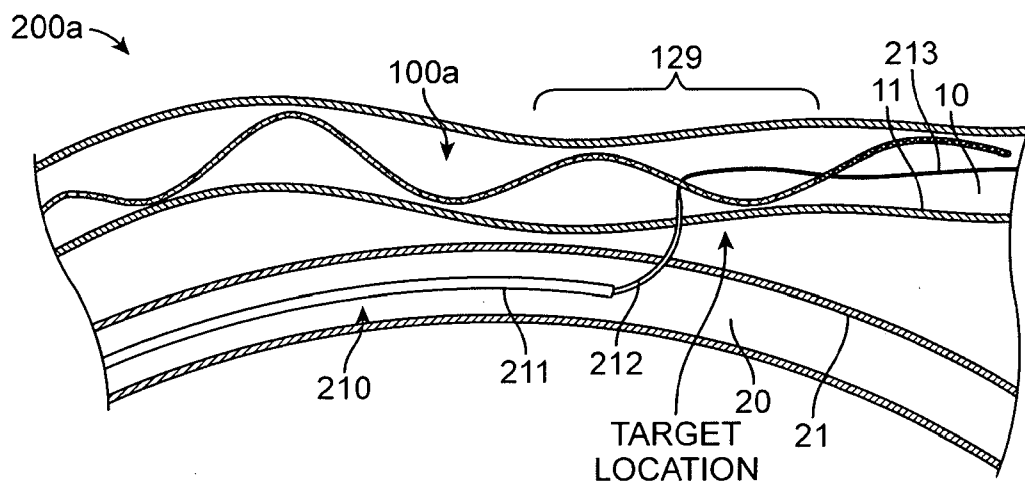


FIG. 2c

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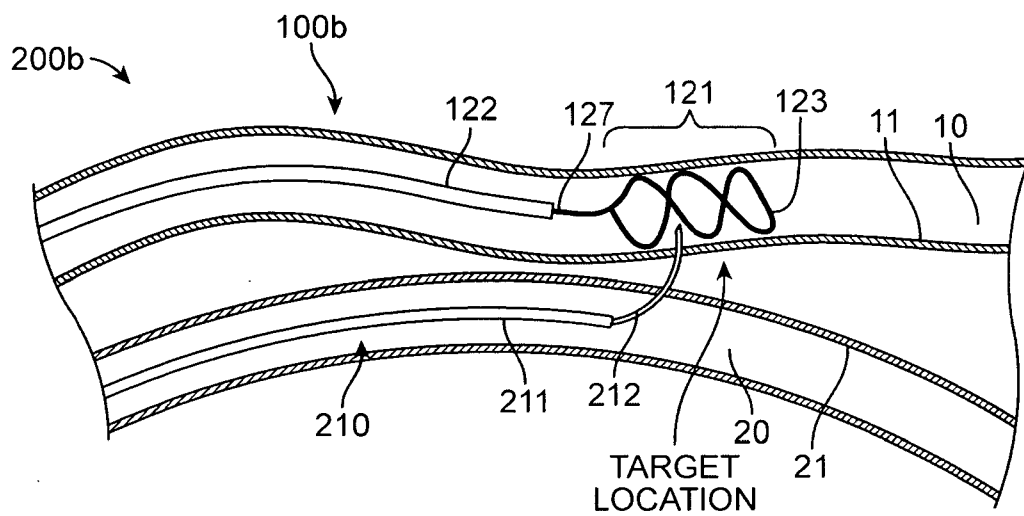


FIG. 3

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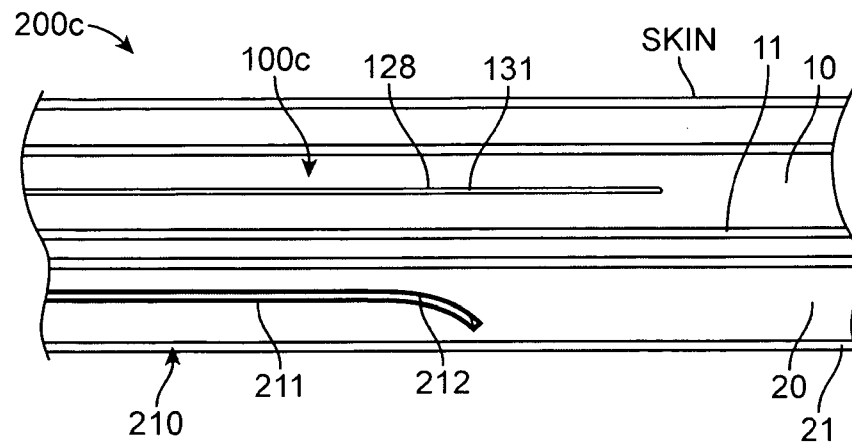


FIG. 4a

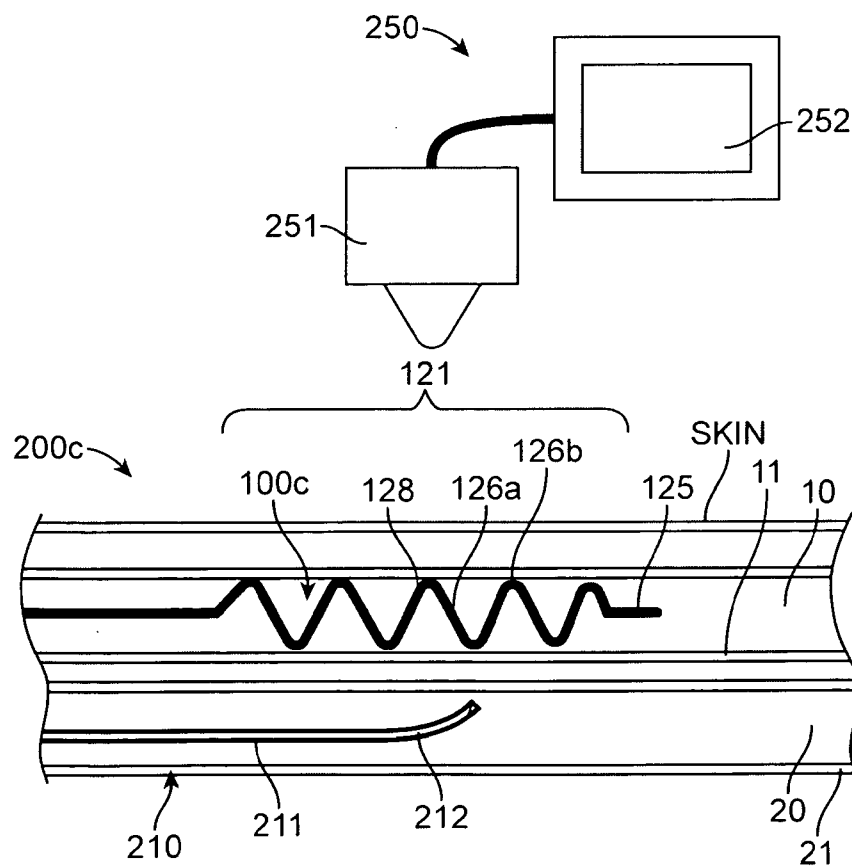


FIG. 4b

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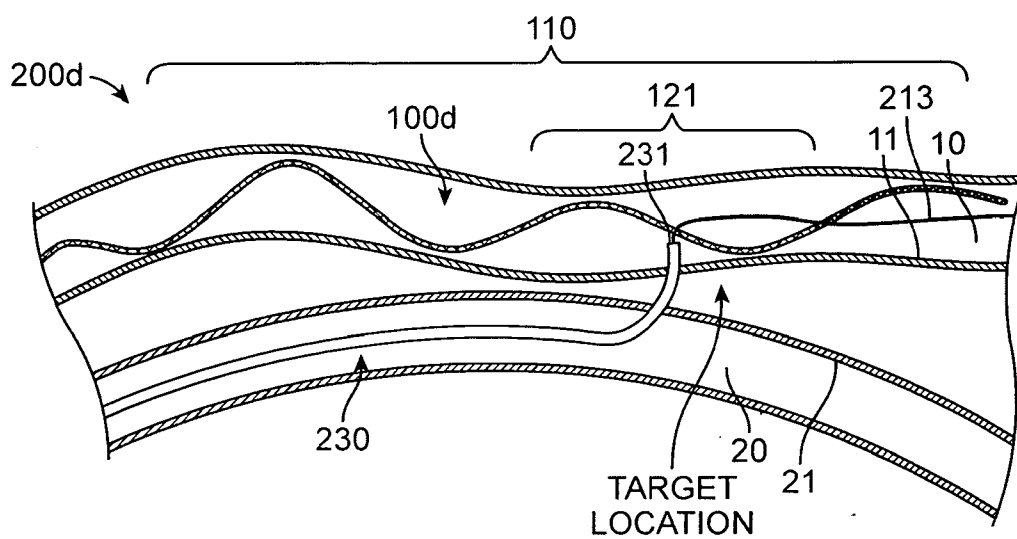


FIG. 5

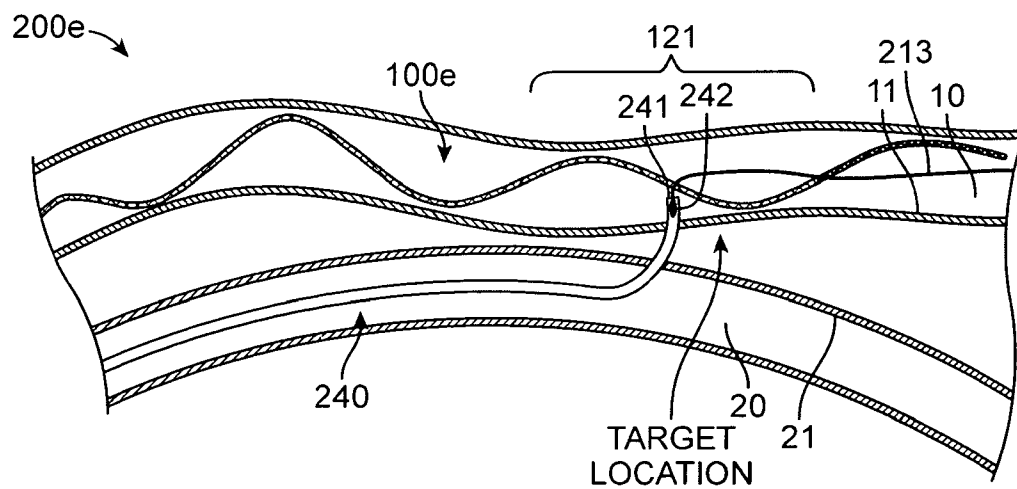


FIG. 6

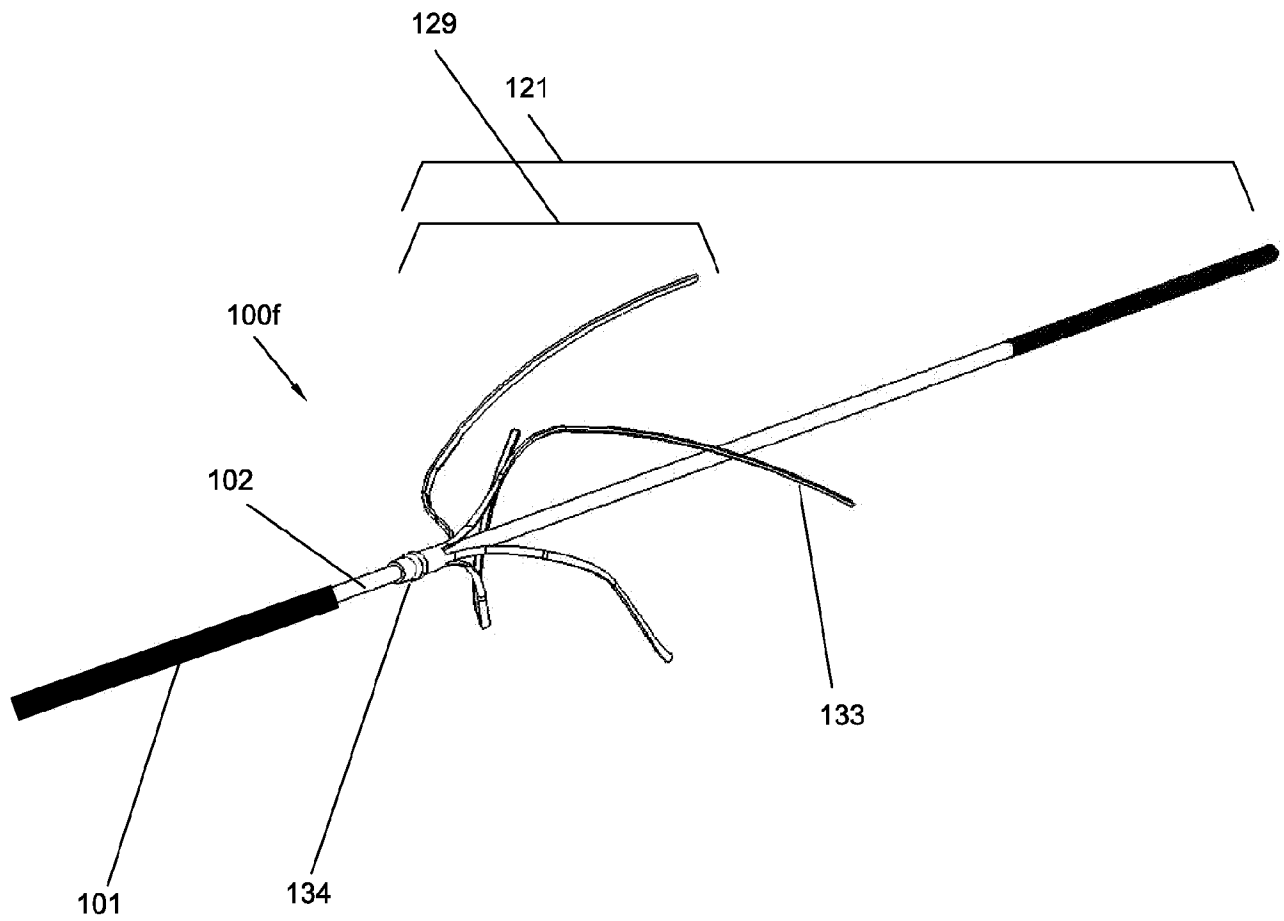


Fig. 7

INTERNATIONAL SEARCH REPORT

International application No.

PCT/US 10/54778

A. CLASSIFICATION OF SUBJECT MATTER

IPC(8) - A61M 25/09 (2010.01)

USPC - 606/194

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC8 : A61M 25/09 (2010.01)

USPC : 606/194

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

IPC8 : A61B5/05, A61B8/14, A61B17/00, A61M25/00, A61M25/01, A61M29/00 (2010.01)

USPC : 600/421, 459, 407, 410, 421, 422, 423, 424, 425, 426, 427, 437, 438, 439, 476, 459, 604/164.01, 164.13, 606/191, 192

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

PubWEST(PGPB,USPT,EPAB,JPAB) Google: arteriovenous fistula, shunt, AVF, vascular, endovascular, measur\$, estimat\$, diameter, geometry, parameter, helix, helical\$, spiral\$, expan\$, enlarg\$, inflat\$, filament, wire, guidewire, vessel, vein, artery, venous, arteriovenous, visualiz\$, approxim\$, gaug\$

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 5,919,147 A (JAIN) 6 July 1999 (06.07.1999) see especially col 2, ln 28-52, col 2 ln 61 to col 4, ln 12, figs 1-3	1-6, 9, 20-21, 23-28, 44-45, 48-61

Y		7-8, 10-19, 22, 29-43, 46, 47, 62-105
Y	US 2004/0158143 A1 (FLAHERTY et al) 12 August 2004 (12.08.2004) see especially para [0013], [0058], [0059], [0060], [0062], [0075], [0083], [0085], [0089], [0090], [0102], [0107], [0113], [0115], figs 1, 6, 8, 10-12	7-8, 28, 29, 43, 62-66, 67-105/(1-11, 20-41, 43-45, 48-66), 94-97/(12-19, 42, 46, 47)
Y	US 4,706,671 A (WEINRIB) 17 November 1987 (17.11.1987) see especially col 2, ln 64 to col 5, ln 56, col 4, ln 50-68, figs 3-4	10-11, 22, 30-41, 67-105/(10-11, 22, 30-41)
Y	US 6,464,665 B1 (HEUSER) 15 October 2002 (15.10.2002) see especially col 5, ln 3-29, col 5, ln 51 to col 7, ln 6, col 8, ln 54 to col 9, ln 9, col 9, ln 45-49, figs 1-6, 13-15	12-19, 42, 46, 47, 67-101/(12-19, 42, 46, 47), 102-105/(1-66)

☐ Further documents are listed in the continuation of Box C.

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"E" earlier application or patent but published on or after the international filing date	"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art
"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)	"&" document member of the same patent family
"O" document referring to an oral disclosure, use, exhibition or other means	
"P" document published prior to the international filing date but later than the priority date claimed	

Date of the actual completion of the international search 22 December 2010 (22.12.2010)	Date of mailing of the international search report 20 JAN 2011
Name and mailing address of the ISA/US Mail Stop PCT, Attn: ISA/US, Commissioner for Patents P.O. Box 1450, Alexandria, Virginia 22313-1450 Facsimile No. 571-273-3201	Authorized officer: Lee W. Young PCT Helpdesk: 571-272-4300 PCT OSP: 571-272-7774