



US011253369B2

(12) **United States Patent**  
**Tseng et al.**

(10) **Patent No.:** **US 11,253,369 B2**

(45) **Date of Patent:** **Feb. 22, 2022**

(54) **SPINAL IMPLANT STRUCTURE AND KIT THEREOF**

(71) Applicants: **GROUP INNOMED BIOTECH CO., LTD.**, Taipei (TW); **WILTROM CO., LTD.**, Zhubei (TW)

(72) Inventors: **Chang-Ho Tseng**, Taipei (TW); **Meng-Yuan Tsai**, Taipei (TW); **Huang-Chien Liang**, Zhubei (TW); **Chieh-Feng Lu**, Zhubei (TW); **Wan-Chun Chen**, Zhubei (TW); **Huang-Chi Chen**, Zhubei (TW)

(73) Assignee: **WILTROM CO., LTD.**, Zhubei (TW)

(\* ) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 188 days.

(21) Appl. No.: **16/703,126**

(22) Filed: **Dec. 4, 2019**

(65) **Prior Publication Data**

US 2020/0100819 A1 Apr. 2, 2020

**Related U.S. Application Data**

(63) Continuation-in-part of application No. 15/457,020, filed on Mar. 13, 2017, now Pat. No. 10,555,820.

(30) **Foreign Application Priority Data**

Mar. 14, 2016 (TW) ..... 105107739

(51) **Int. Cl.**  
**A61F 2/44** (2006.01)  
**A61B 17/70** (2006.01)

(Continued)

(52) **U.S. Cl.**  
CPC ..... **A61F 2/44** (2013.01); **A61B 17/7094** (2013.01); **A61F 2/4611** (2013.01);

(Continued)

(58) **Field of Classification Search**  
CPC ..... A61F 2/44; A61F 2/4455; A61F 2/446; A61F 2002/4475; A61F 2002/4495  
See application file for complete search history.

(56) **References Cited**

U.S. PATENT DOCUMENTS

5,554,191 A \* 9/1996 Lahille ..... A61B 17/1757 623/17.11  
6,129,763 A \* 10/2000 Chauvin ..... A61F 2/30744 623/17.11

(Continued)

FOREIGN PATENT DOCUMENTS

CN 102274066 A 12/2011  
CN 102413777 A 4/2012

(Continued)

OTHER PUBLICATIONS

European Search Report dated Aug. 16, 2017 in European Patent Application No. 17160573.

(Continued)

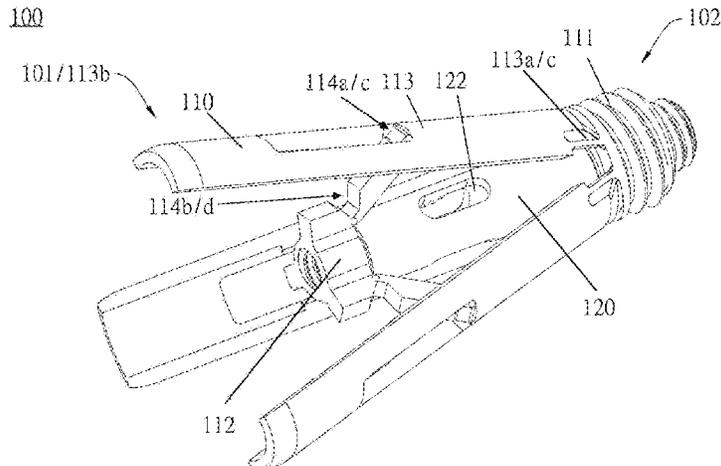
*Primary Examiner* — Eric S Gibson

(74) *Attorney, Agent, or Firm* — Muncy, Geissler, Olds & Lowe, P.C.

(57) **ABSTRACT**

The present invention provides a spinal implant structure. The spinal implant structure comprises a first part, a second part and at least one expansion arm. The second part is disposed on the horizontal orientation of the first part and does not overlap with the first part. The diameter of the first part is larger than that of the second part. One end of the expansion arm is connected to the first part, and the other end of the expansion arm is free end. The expansion arm includes a supporting arm. One end of the supporting arm is connected to the expansion arm, and the other end is connected the second part. The support arm includes a plurality of structure weakness. When the distance between the first part and the second part changes, the support arm

(Continued)



bends from the structure weakness, thereby the spinal implant structure is expanded.

**19 Claims, 58 Drawing Sheets**

(51) **Int. Cl.**

*A61F 2/46* (2006.01)  
*A61F 2/28* (2006.01)  
*A61F 2/30* (2006.01)  
*A61B 17/88* (2006.01)

(52) **U.S. Cl.**

CPC ... *A61B 17/8802* (2013.01); *A61F 2002/2835* (2013.01); *A61F 2002/30235* (2013.01); *A61F 2002/30579* (2013.01); *A61F 2002/30593* (2013.01); *A61F 2002/30912* (2013.01)

(56)

**References Cited**

U.S. PATENT DOCUMENTS

6,443,989 B1 \* 9/2002 Jackson ..... A61F 2/447  
 623/17.15  
 6,652,584 B2 \* 11/2003 Michelson ..... A61F 2/4455  
 623/17.11  
 6,773,460 B2 \* 8/2004 Jackson ..... A61F 2/4455  
 623/17.15  
 6,952,584 B2 10/2005 Adamany et al.  
 6,955,691 B2 \* 10/2005 Chae ..... A61F 2/446  
 623/17.16  
 7,128,760 B2 \* 10/2006 Michelson ..... A61F 2/446  
 623/17.15  
 7,410,501 B2 \* 8/2008 Michelson ..... A61F 2/4611  
 623/17.15  
 7,445,636 B2 \* 11/2008 Michelson ..... A61F 2/446  
 623/17.15  
 7,655,046 B2 \* 2/2010 Dryer ..... A61F 2/4611  
 623/17.15  
 7,678,148 B2 \* 3/2010 Peterman ..... A61F 2/4455  
 623/17.11  
 7,879,098 B1 \* 2/2011 Simmons, Jr. .... A61F 2/4465  
 623/17.11  
 8,267,939 B2 9/2012 Cipoletti et al.

8,685,095 B2 \* 4/2014 Miller ..... A61F 2/447  
 623/17.11  
 9,801,733 B2 \* 10/2017 Wolters ..... A61F 2/447  
 9,814,602 B2 \* 11/2017 Faulhaber ..... A61F 2/4611  
 9,907,671 B2 \* 3/2018 Fessler ..... A61F 2/447  
 10,039,650 B2 \* 8/2018 Lamborne ..... A61F 2/4455  
 10,555,820 B2 \* 2/2020 Tseng ..... A61B 17/8858  
 2002/0068939 A1 6/2002 Levy et al.  
 2002/0143401 A1 \* 10/2002 Michelson ..... A61F 2/4611  
 623/17.16  
 2003/0220650 A1 11/2003 Major et al.  
 2005/0021041 A1 \* 1/2005 Michelson ..... A61F 2/4611  
 606/90  
 2005/0113917 A1 \* 5/2005 Chae ..... A61F 2/447  
 623/17.11  
 2005/0278036 A1 \* 12/2005 Leonard ..... A61B 17/8858  
 623/23.47  
 2008/0177259 A1 7/2008 Wu  
 2009/0163918 A1 6/2009 Levy et al.  
 2009/0181628 A1 11/2009 Oglaza et al.  
 2009/0281628 A1 \* 11/2009 Oglaza ..... A61B 17/7065  
 623/17.15  
 2010/0185291 A1 \* 7/2010 Jimenez ..... A61F 2/4611  
 623/17.16  
 2012/0226357 A1 \* 9/2012 Varela ..... A61F 2/447  
 623/17.16  
 2015/0012098 A1 \* 1/2015 Eastlack ..... A61F 2/447  
 623/17.15  
 2016/0135960 A1 \* 5/2016 Grotz ..... A61F 2/4425  
 623/17.16  
 2017/0095349 A1 \* 4/2017 Asfora ..... A61F 2/4455  
 2017/0258600 A1 \* 9/2017 Tseng ..... A61B 17/8852  
 2019/0328406 A1 10/2019 Lu et al.  
 2020/0100819 A1 \* 4/2020 Tseng ..... A61B 17/7097

FOREIGN PATENT DOCUMENTS

CN 105011993 A 11/2015  
 EP 3219273 A1 9/2017

OTHER PUBLICATIONS

Office Action dated Jul. 23, 2019 in European Application No. 17160573.

\* cited by examiner

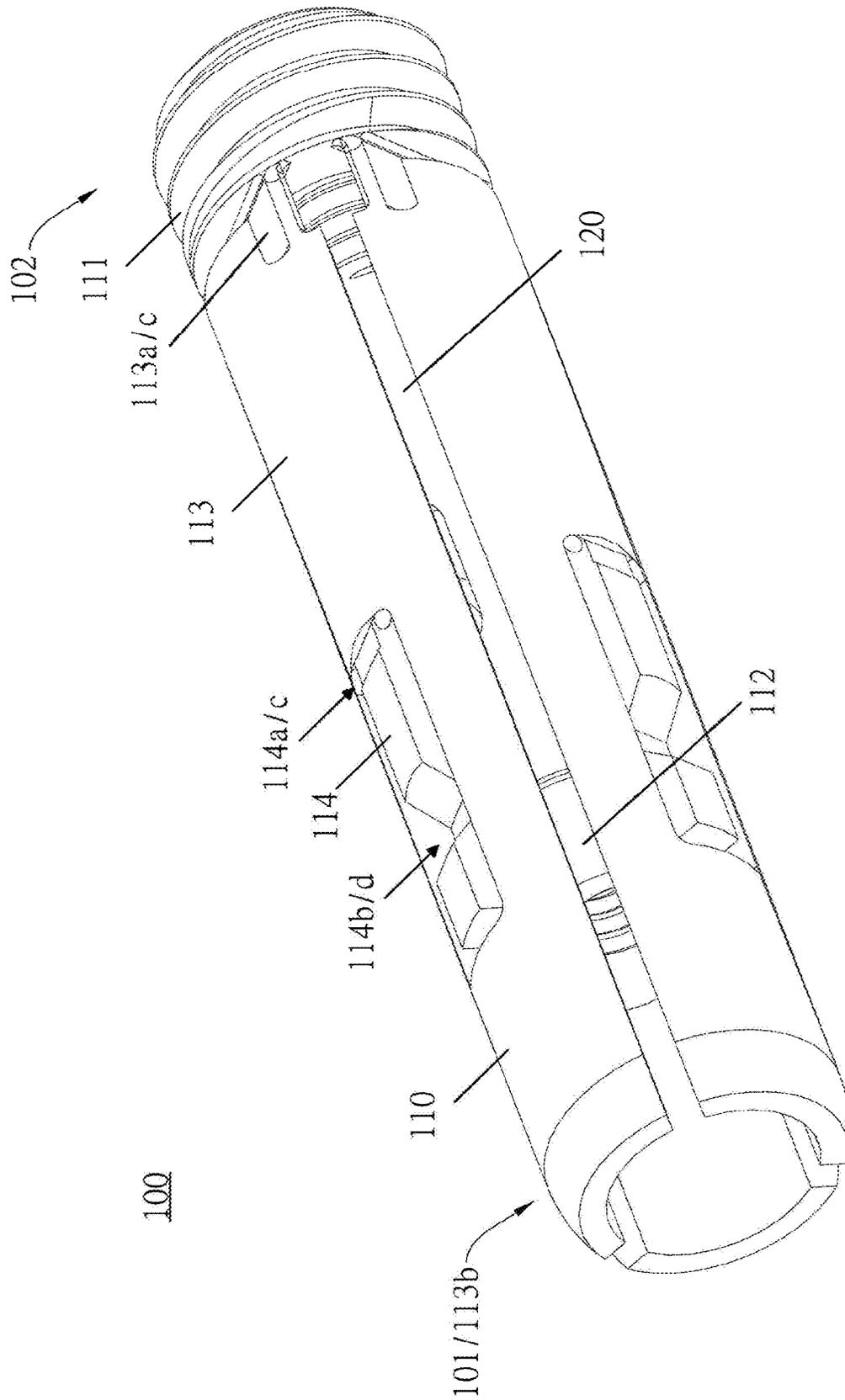


Fig.1A

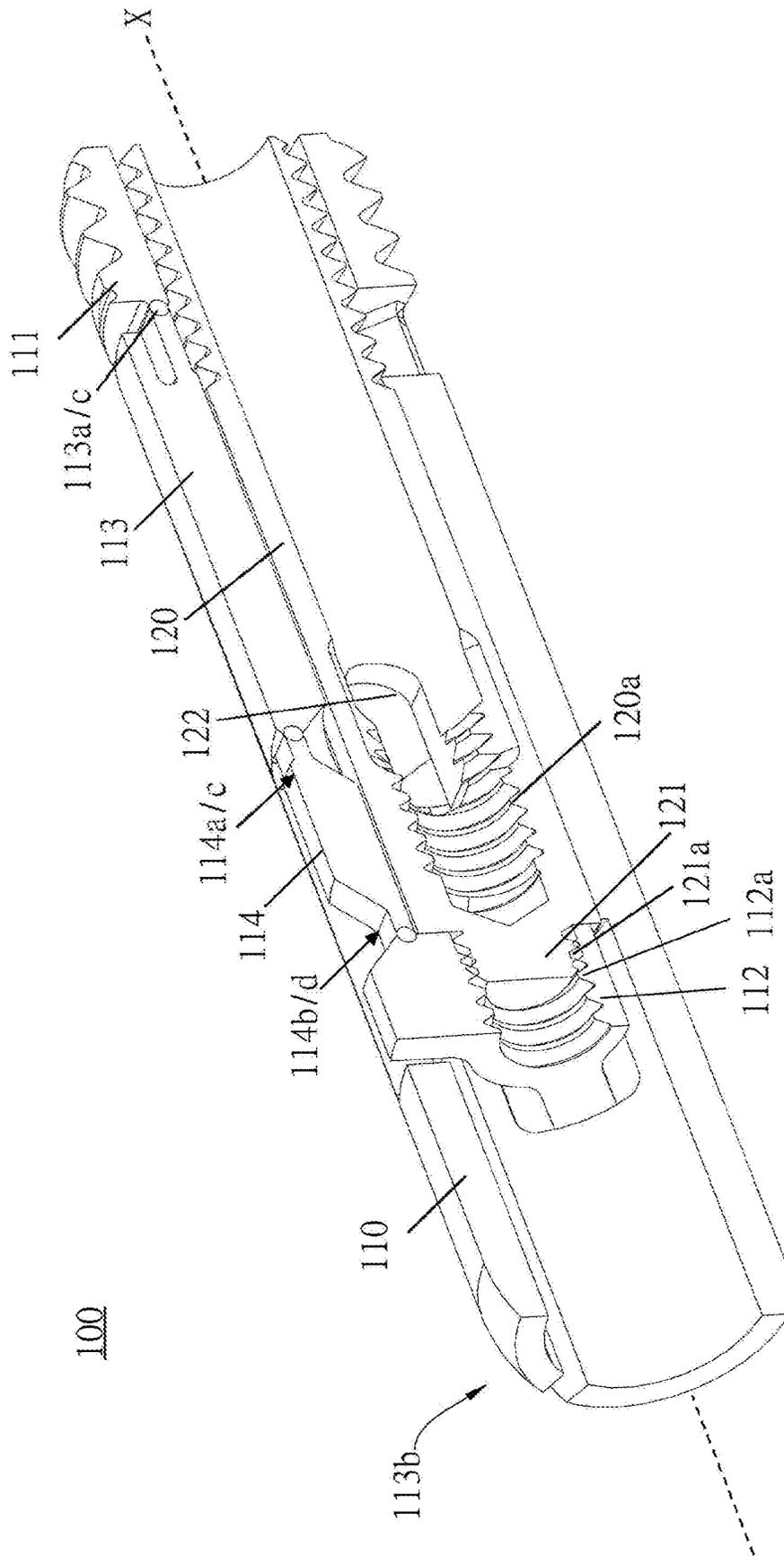


Fig.1B

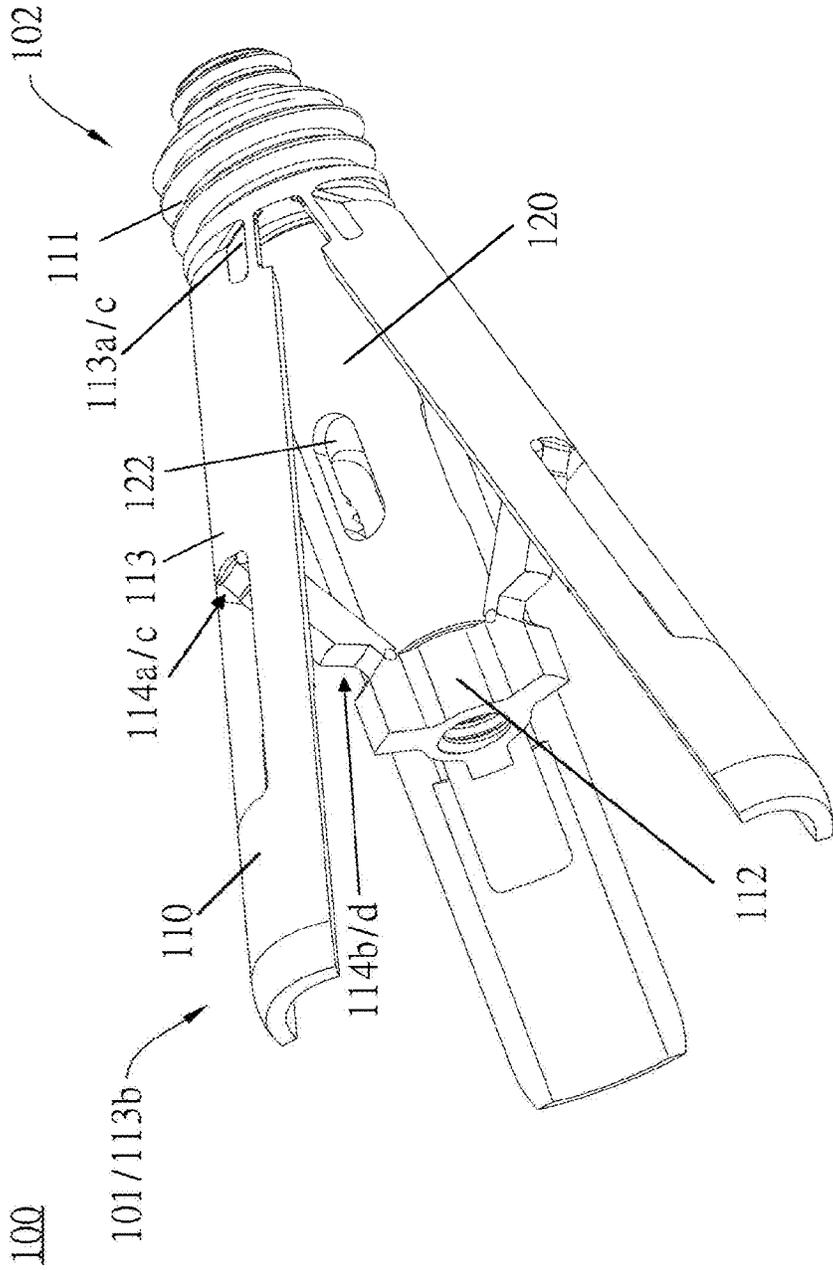


Fig.2A

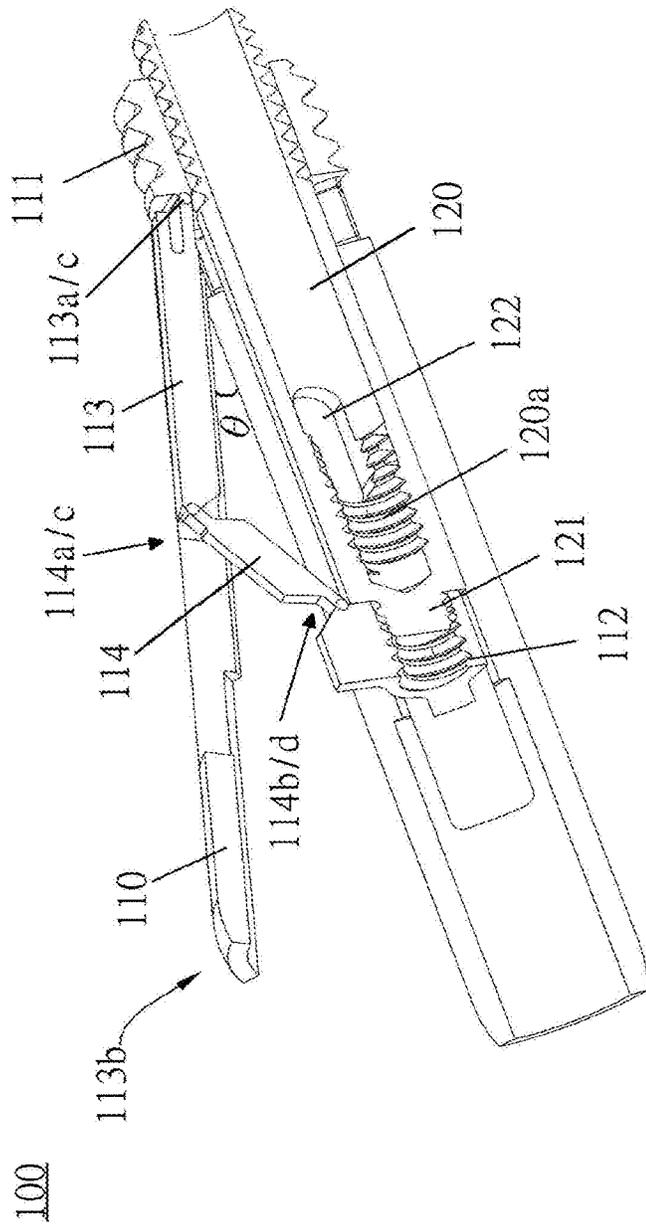
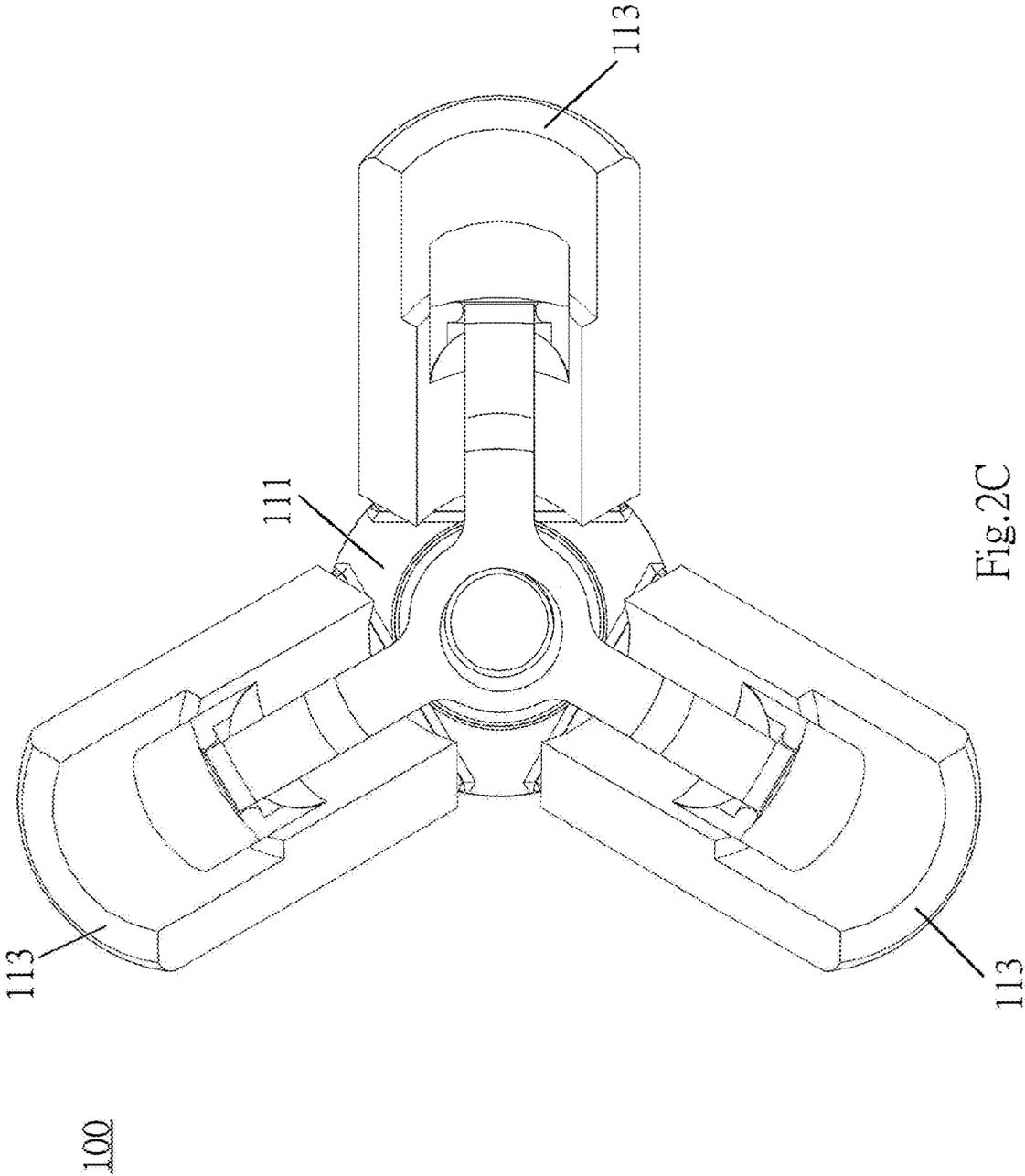


Fig.2B



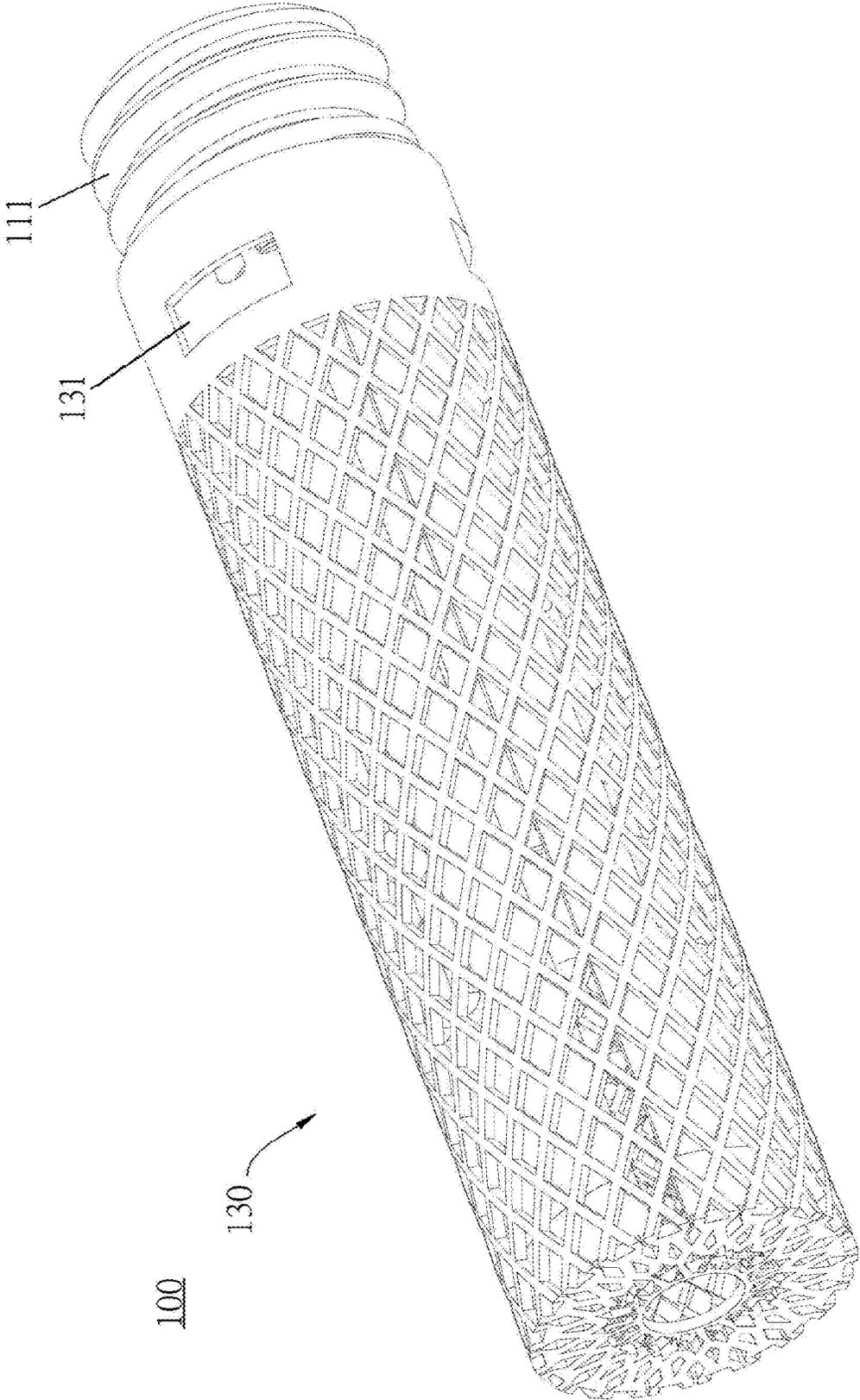


Fig.3A

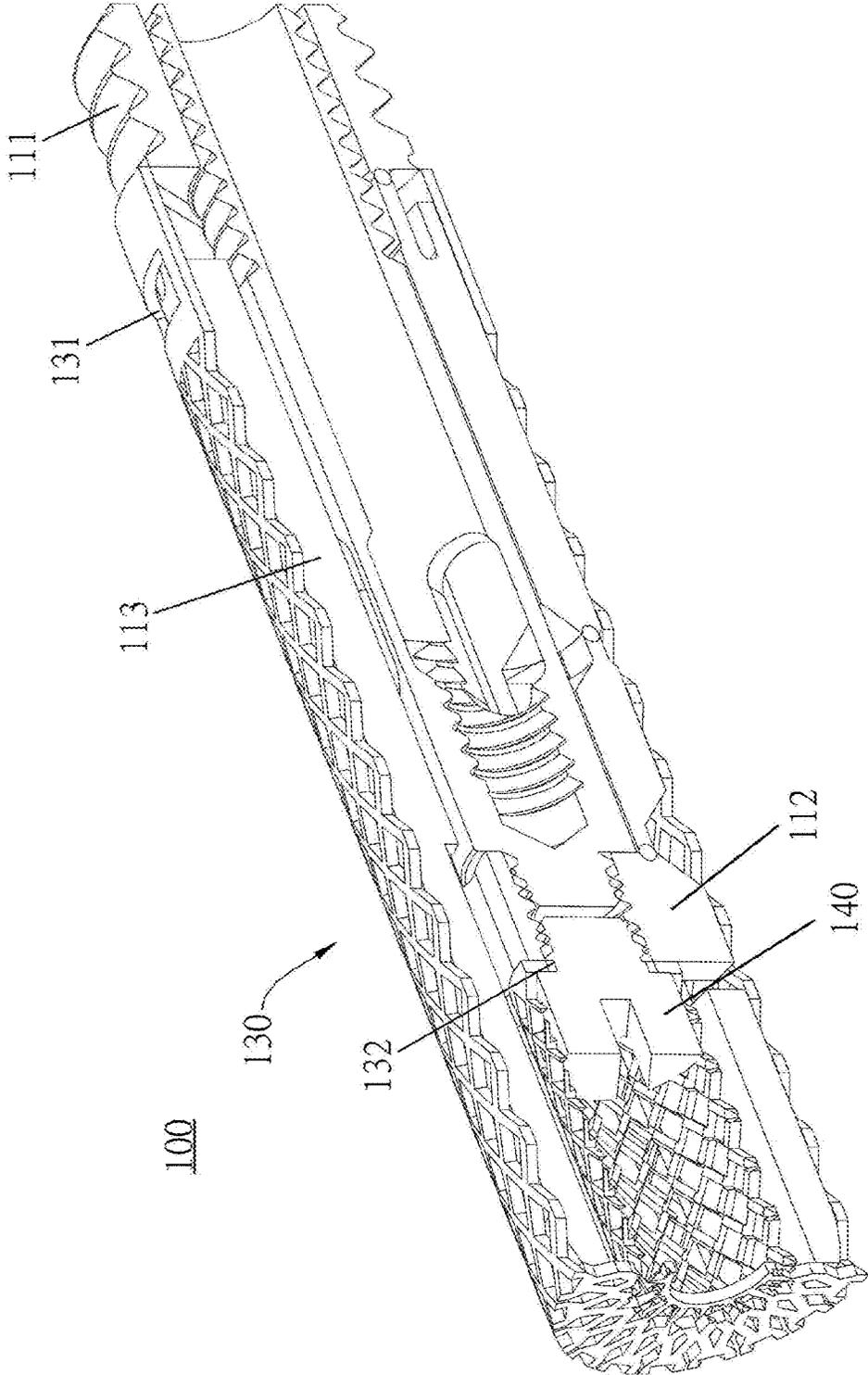


Fig.3B

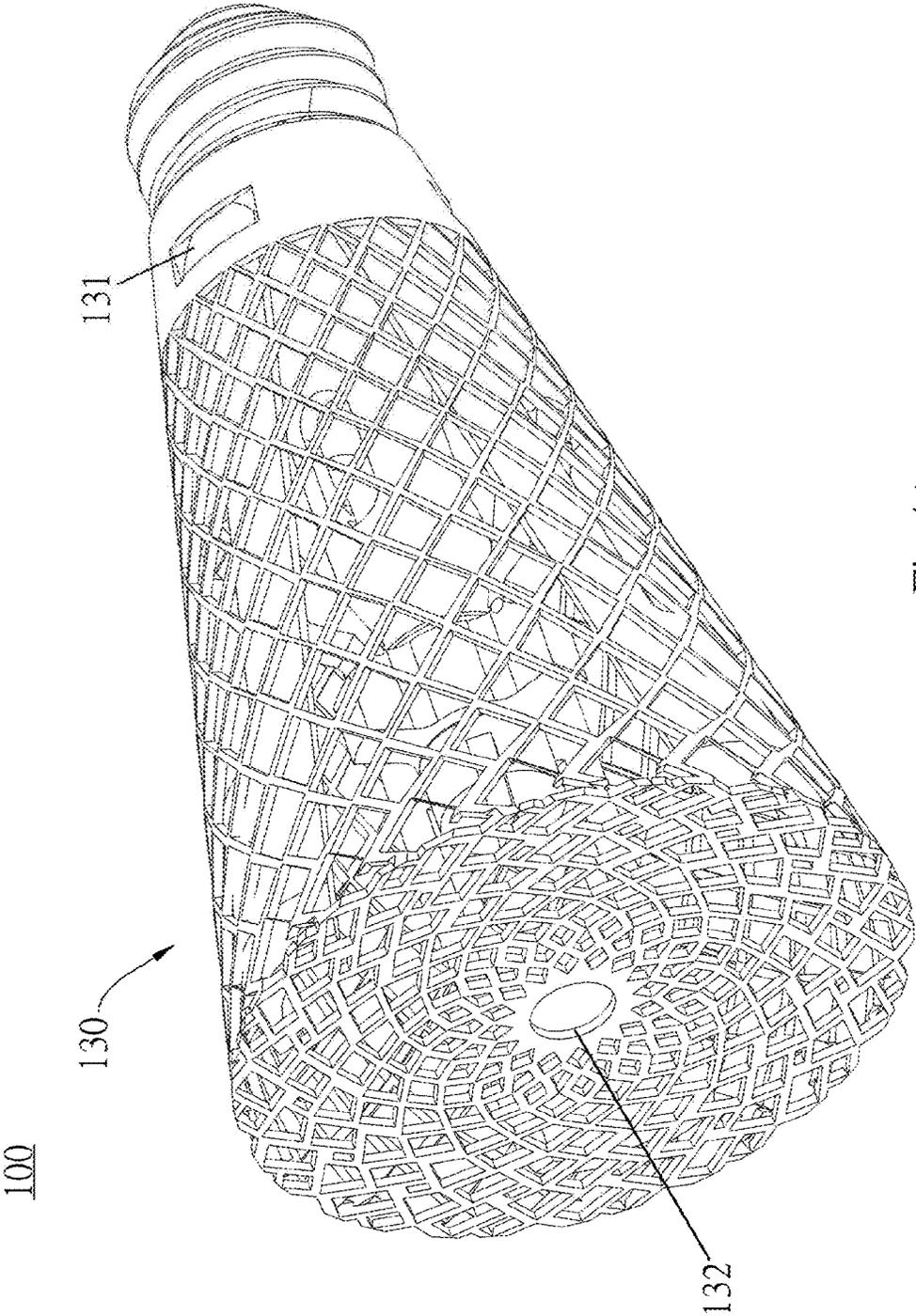


Fig. 4A

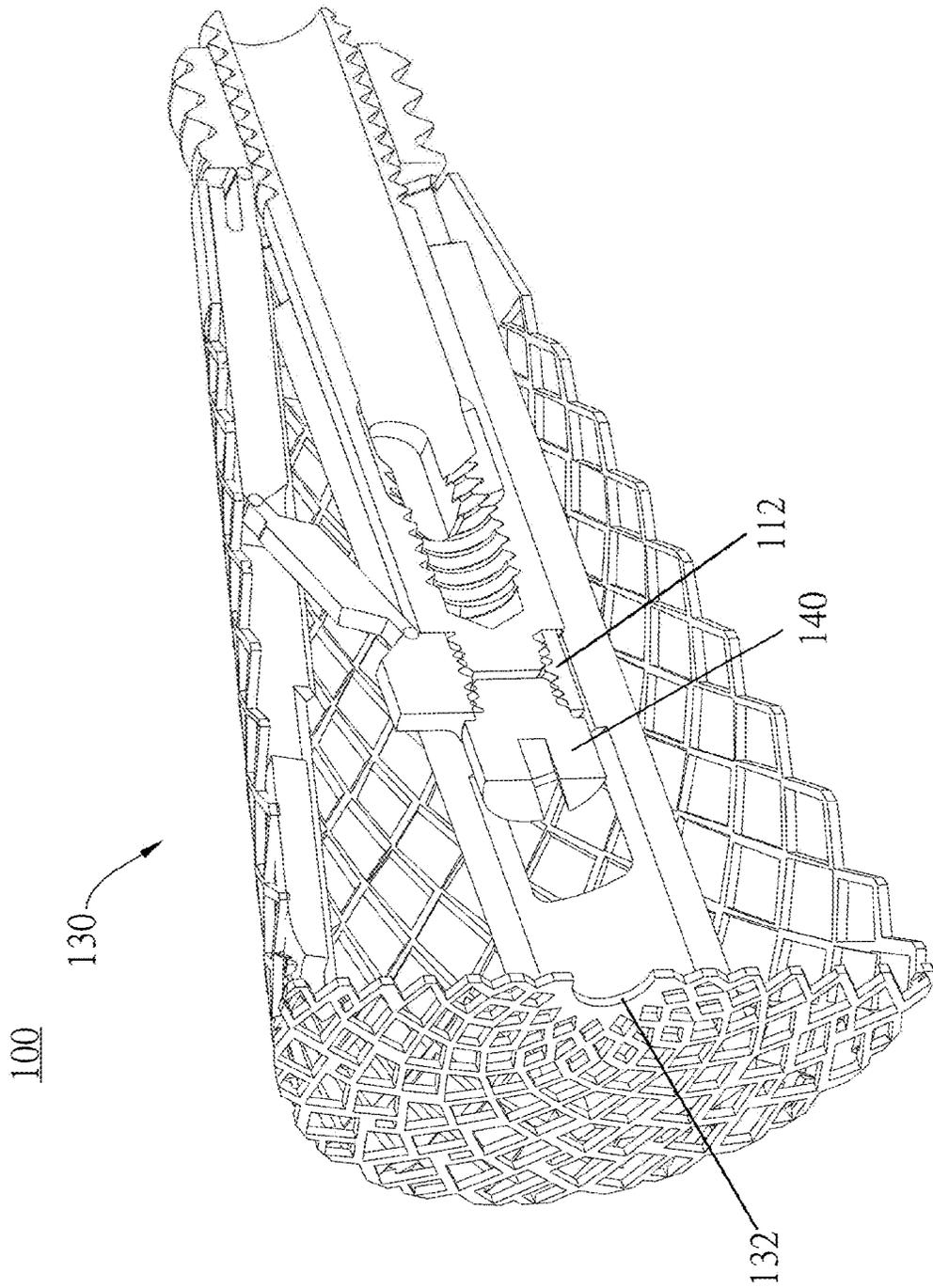


Fig.4B

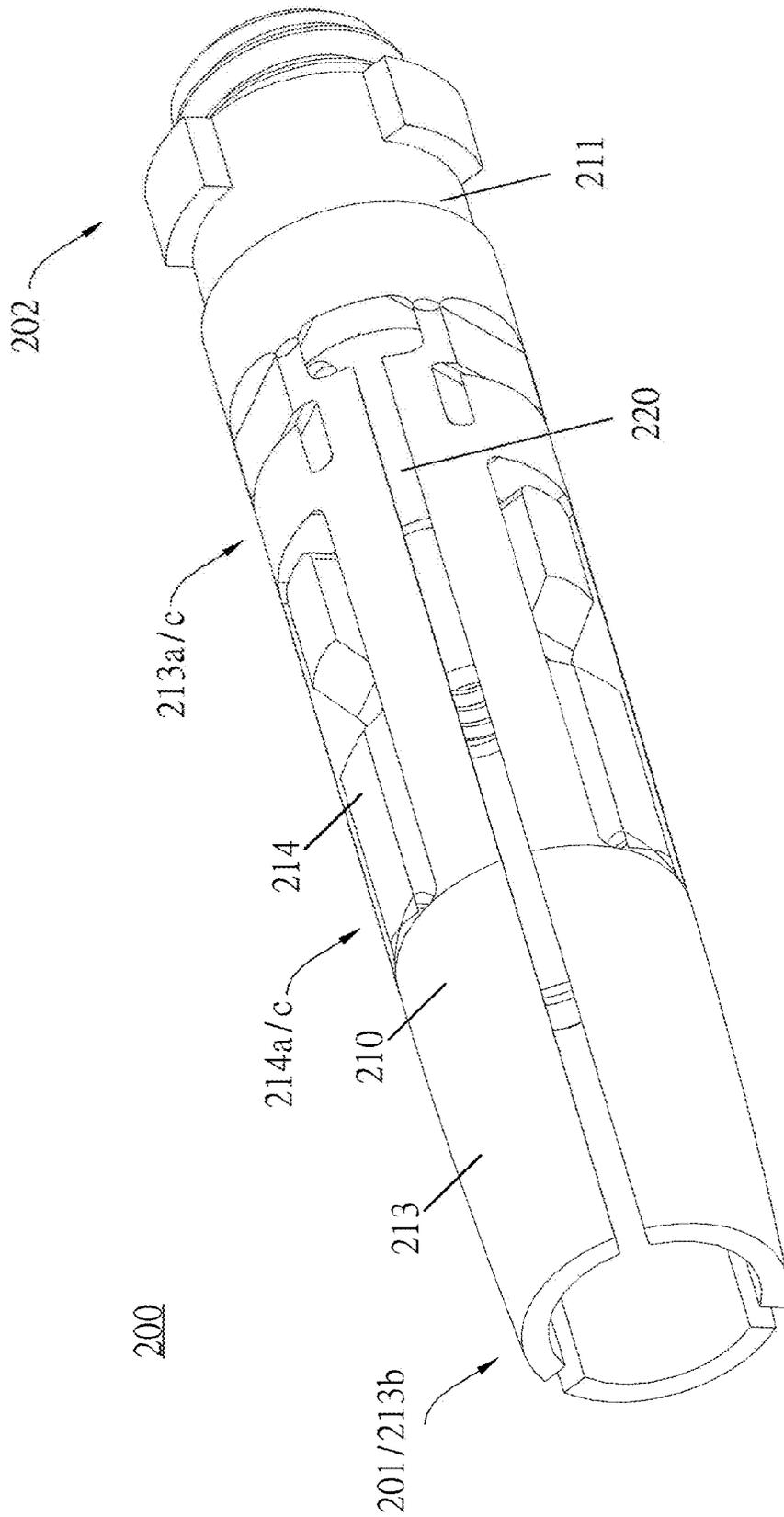


Fig.5A

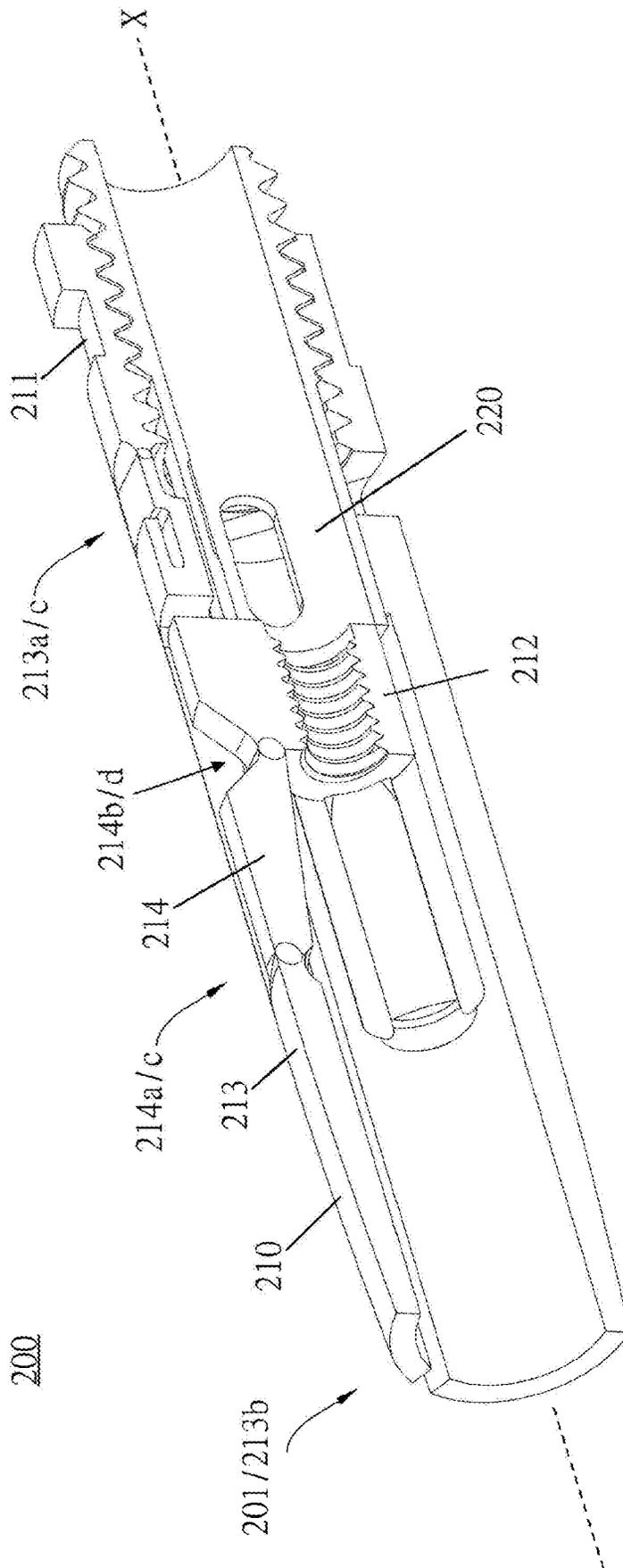


Fig. 5B

200

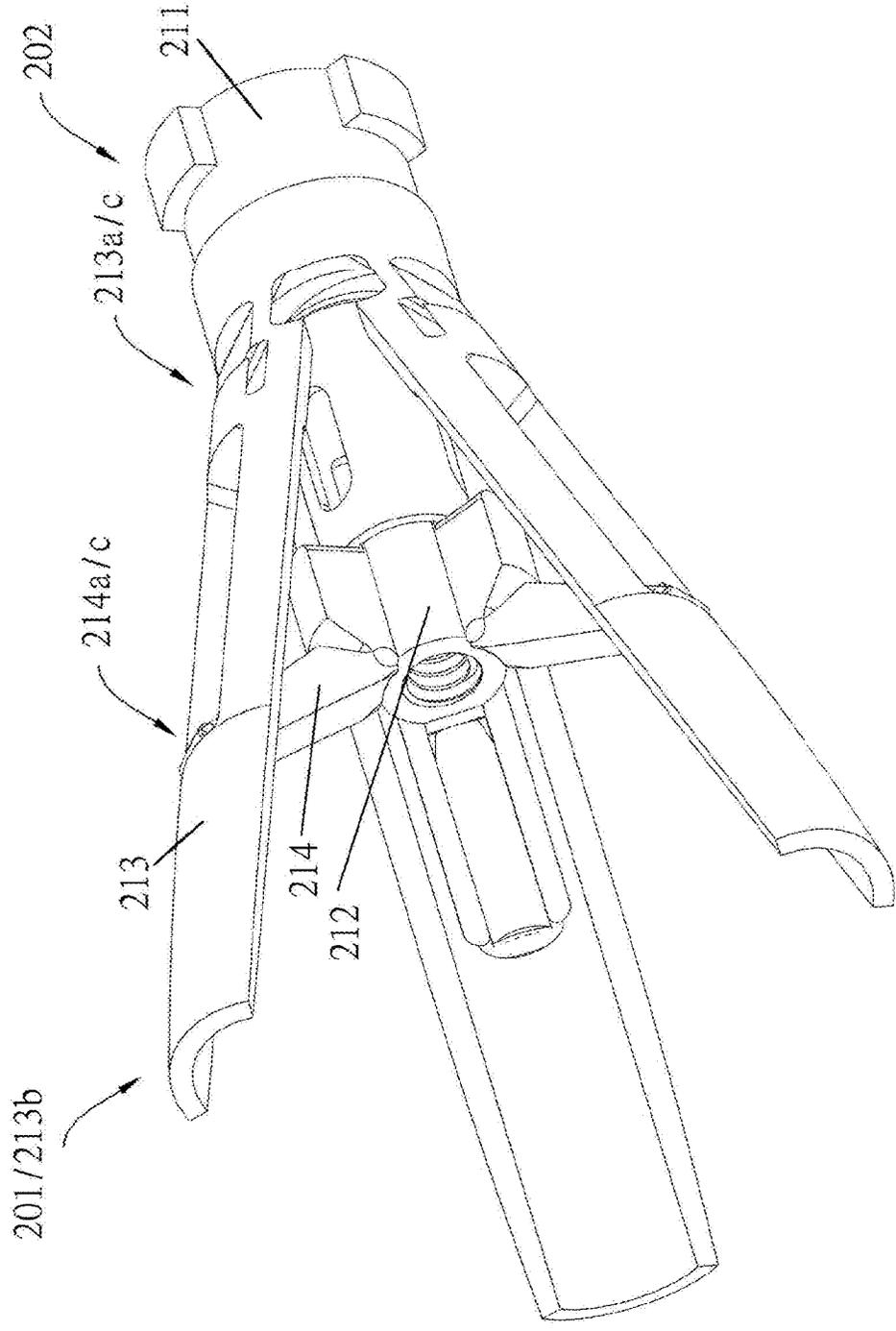


Fig.6A

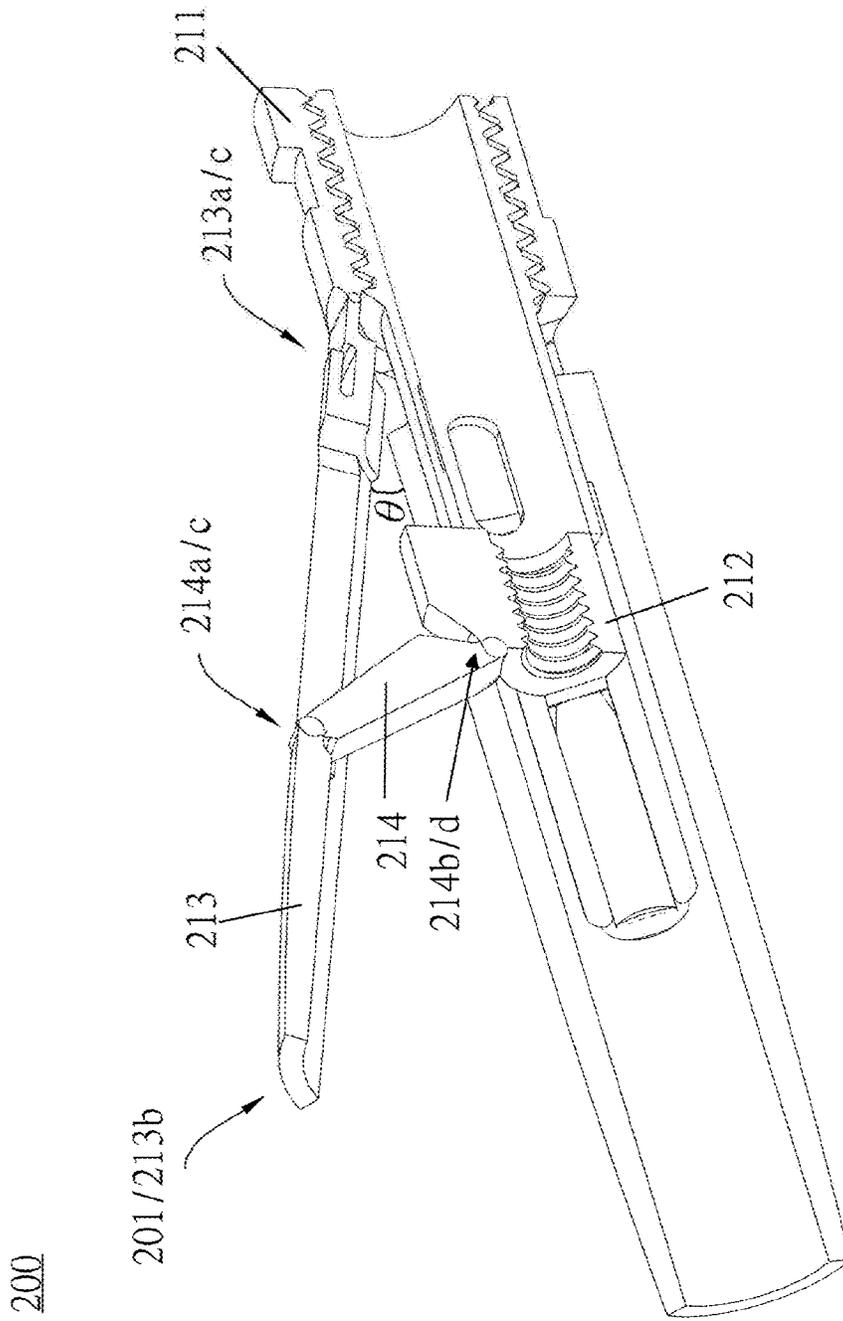


Fig.6B

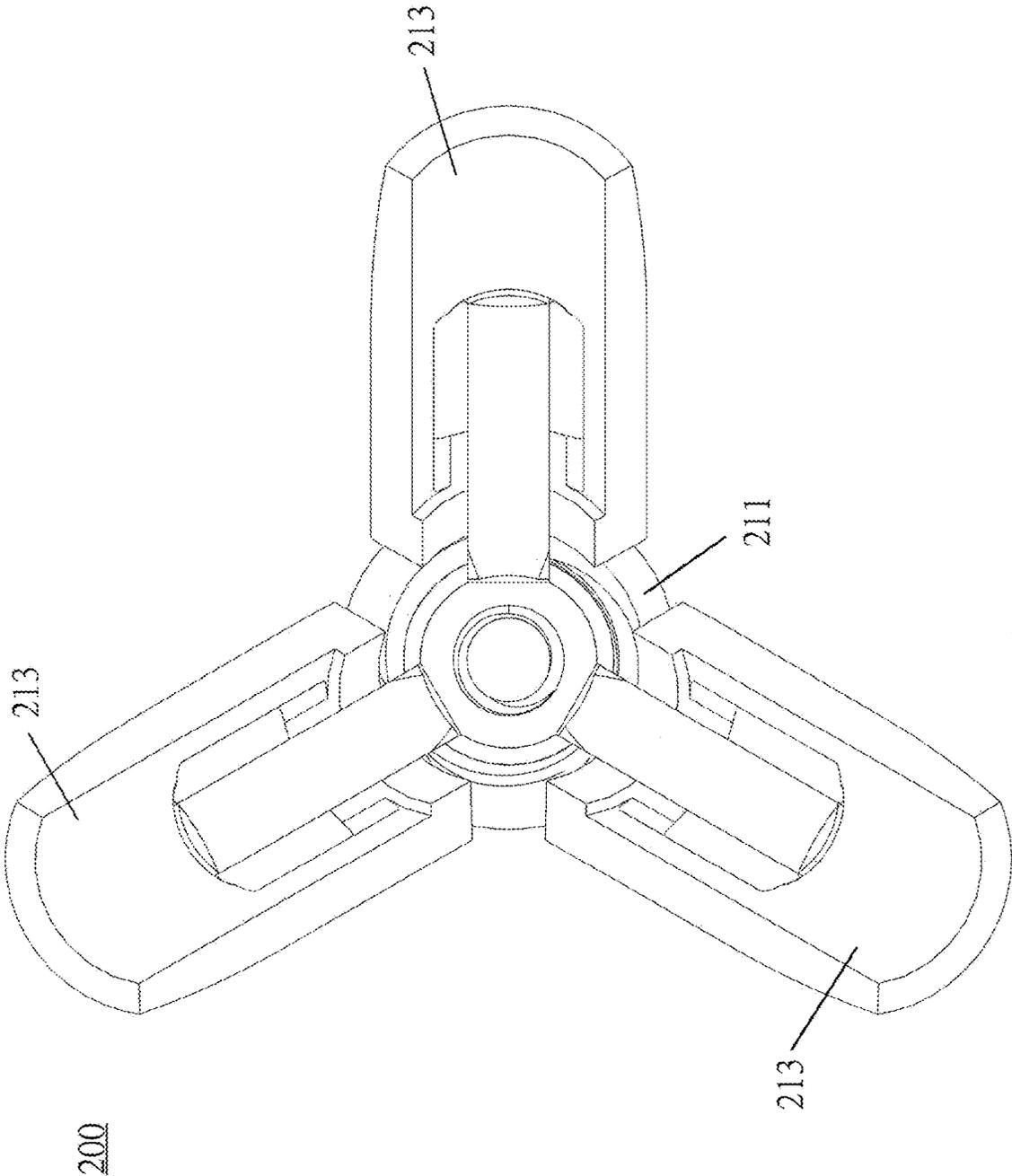


Fig.6C

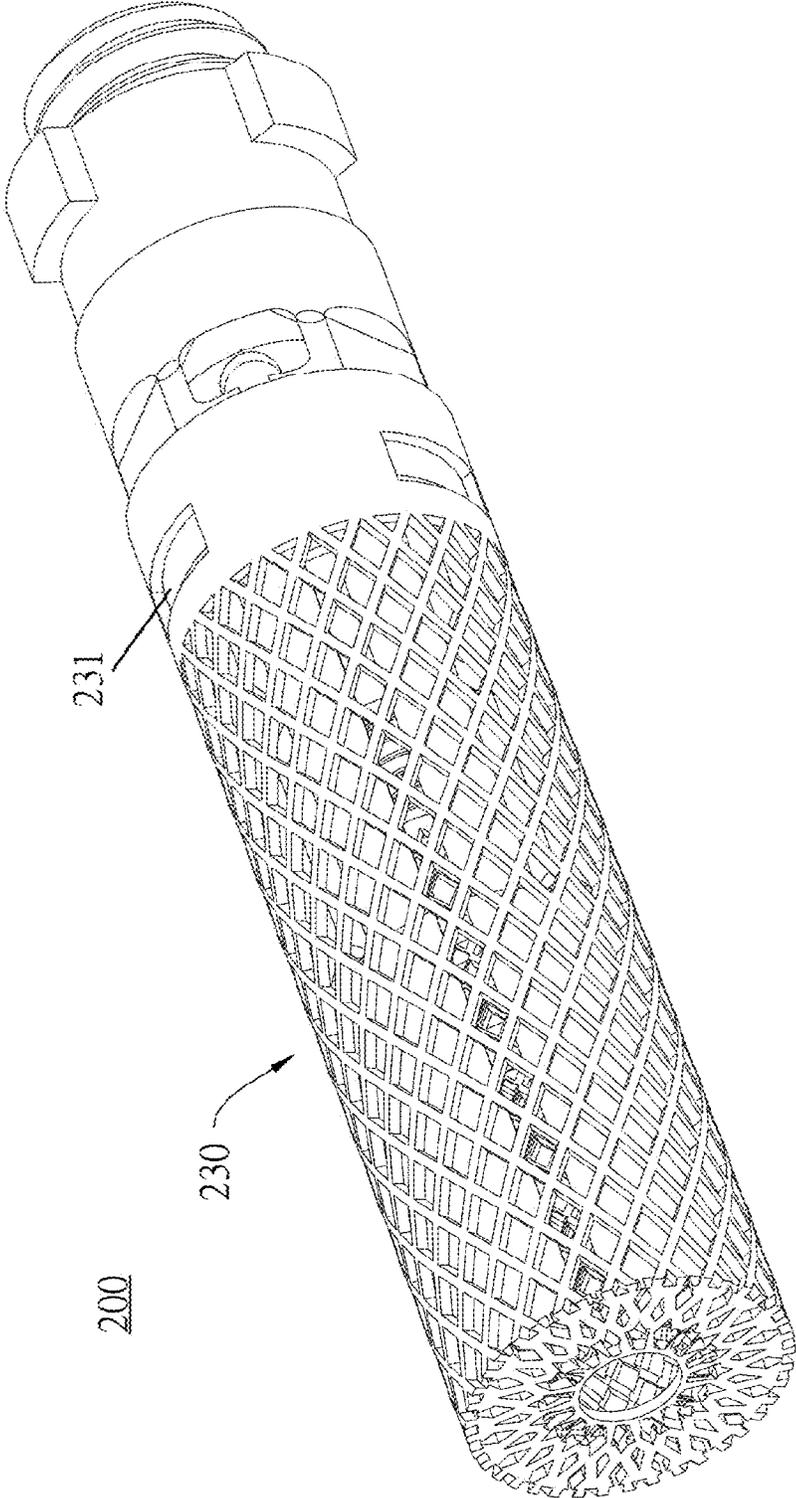


Fig. 7A

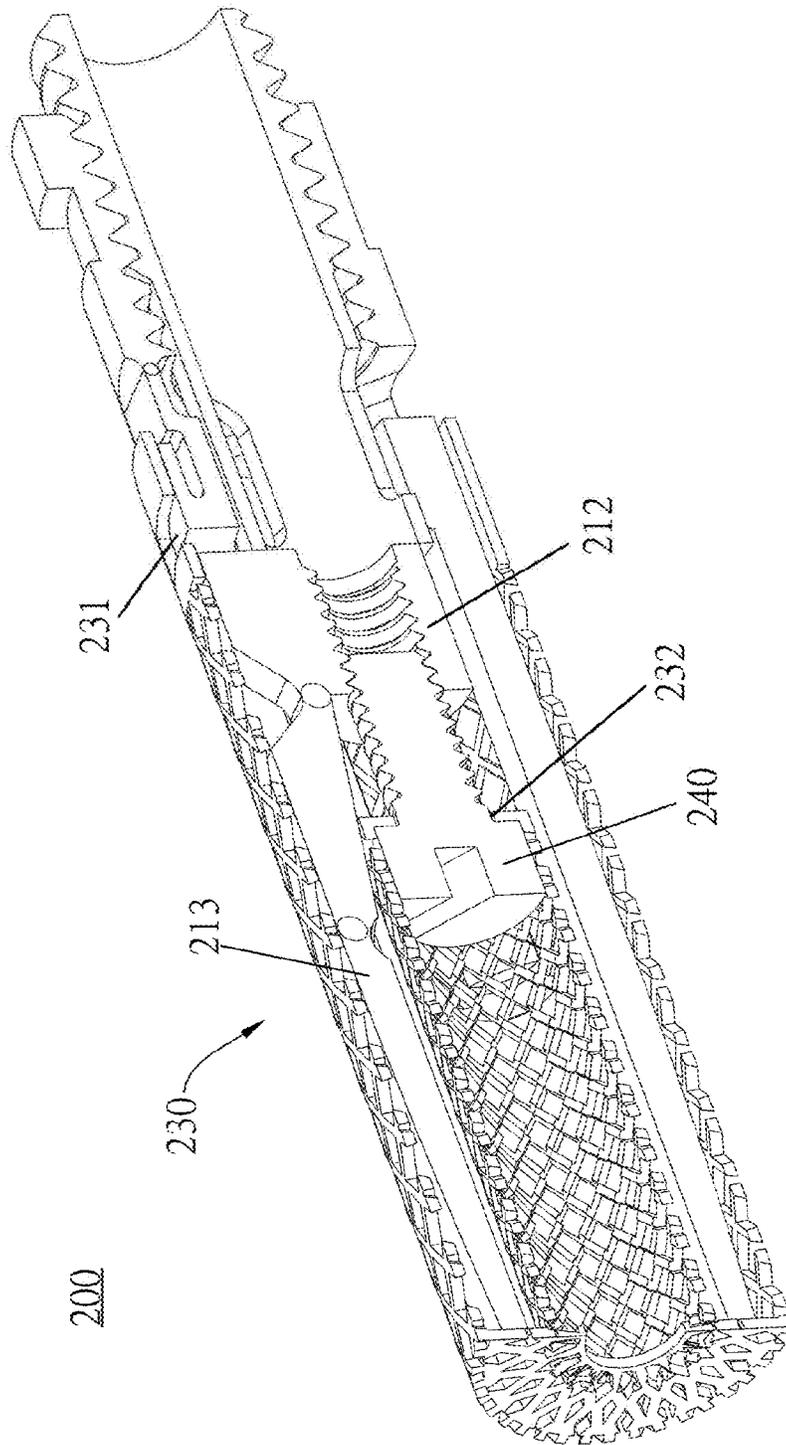


Fig. 7B

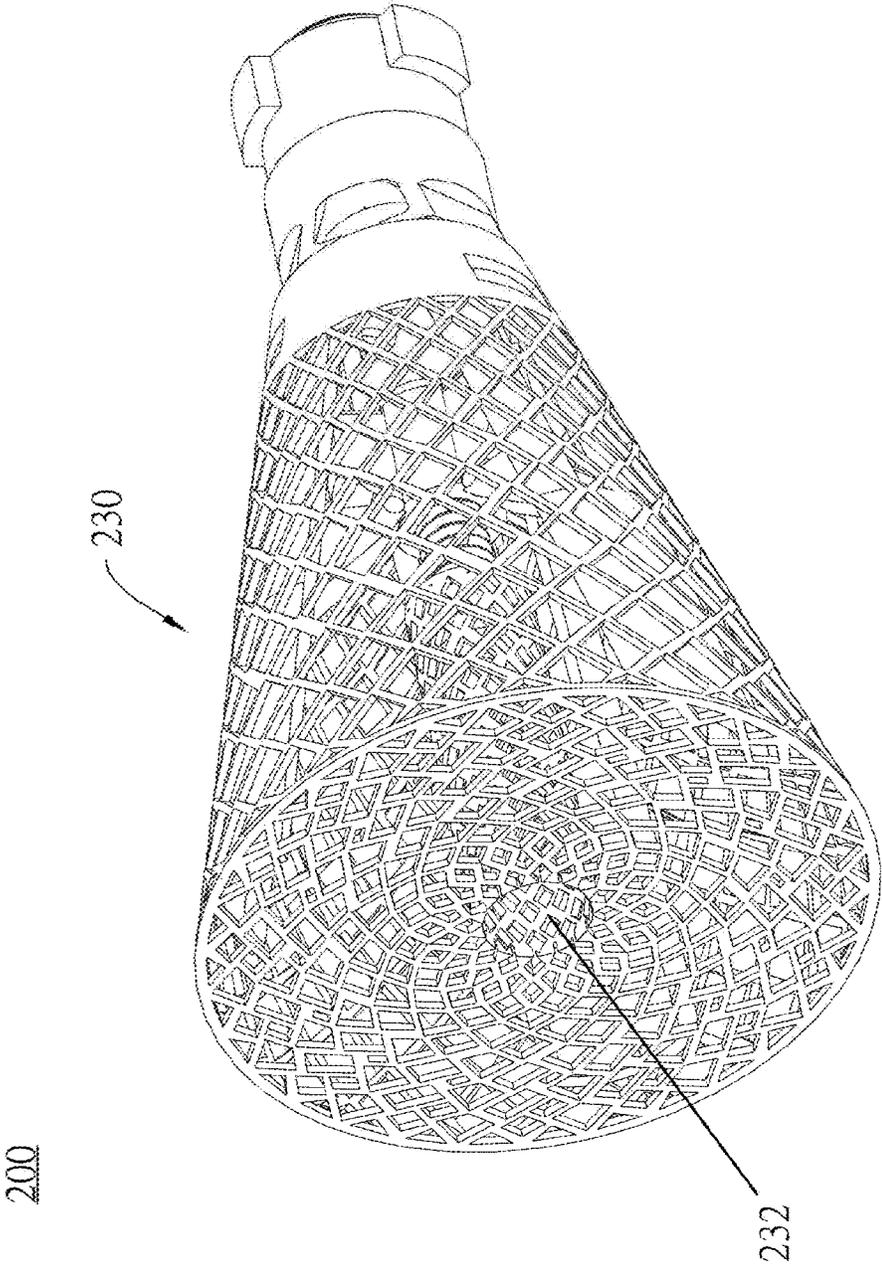


Fig.8A

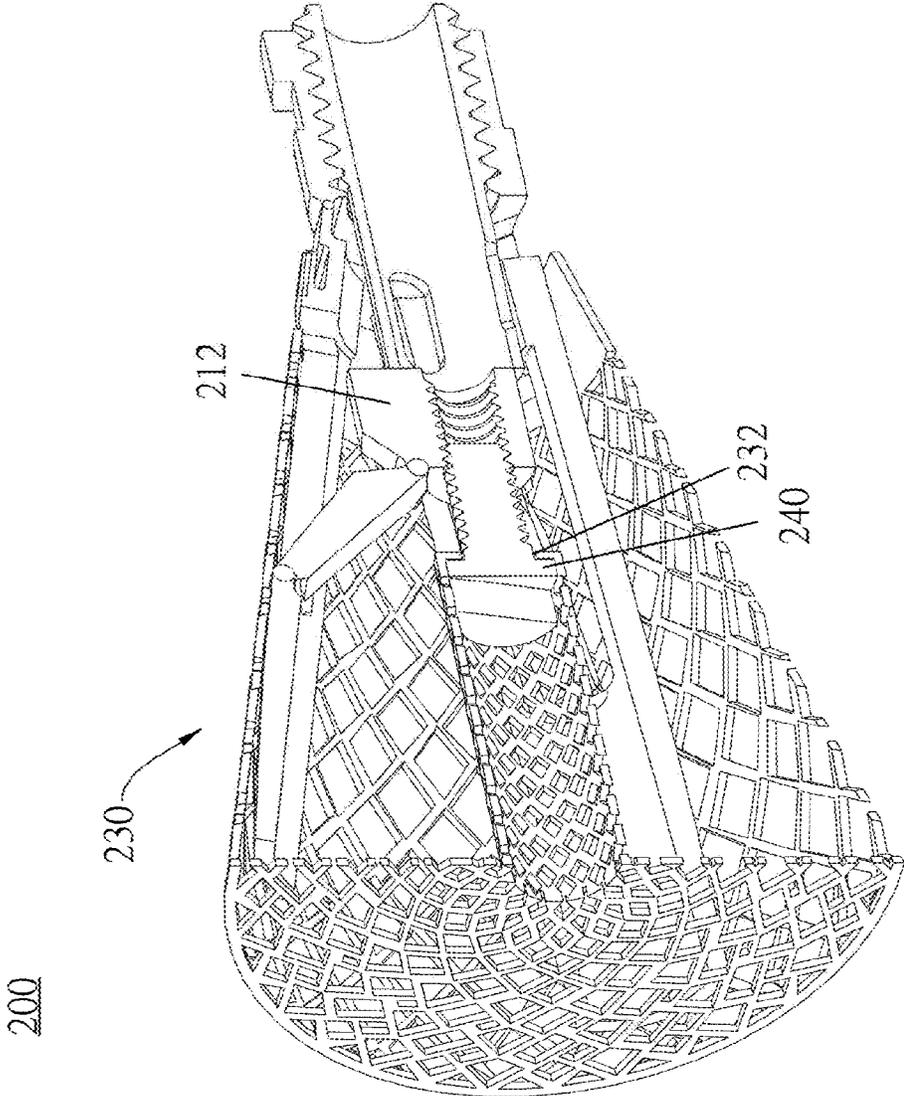


Fig. 8B

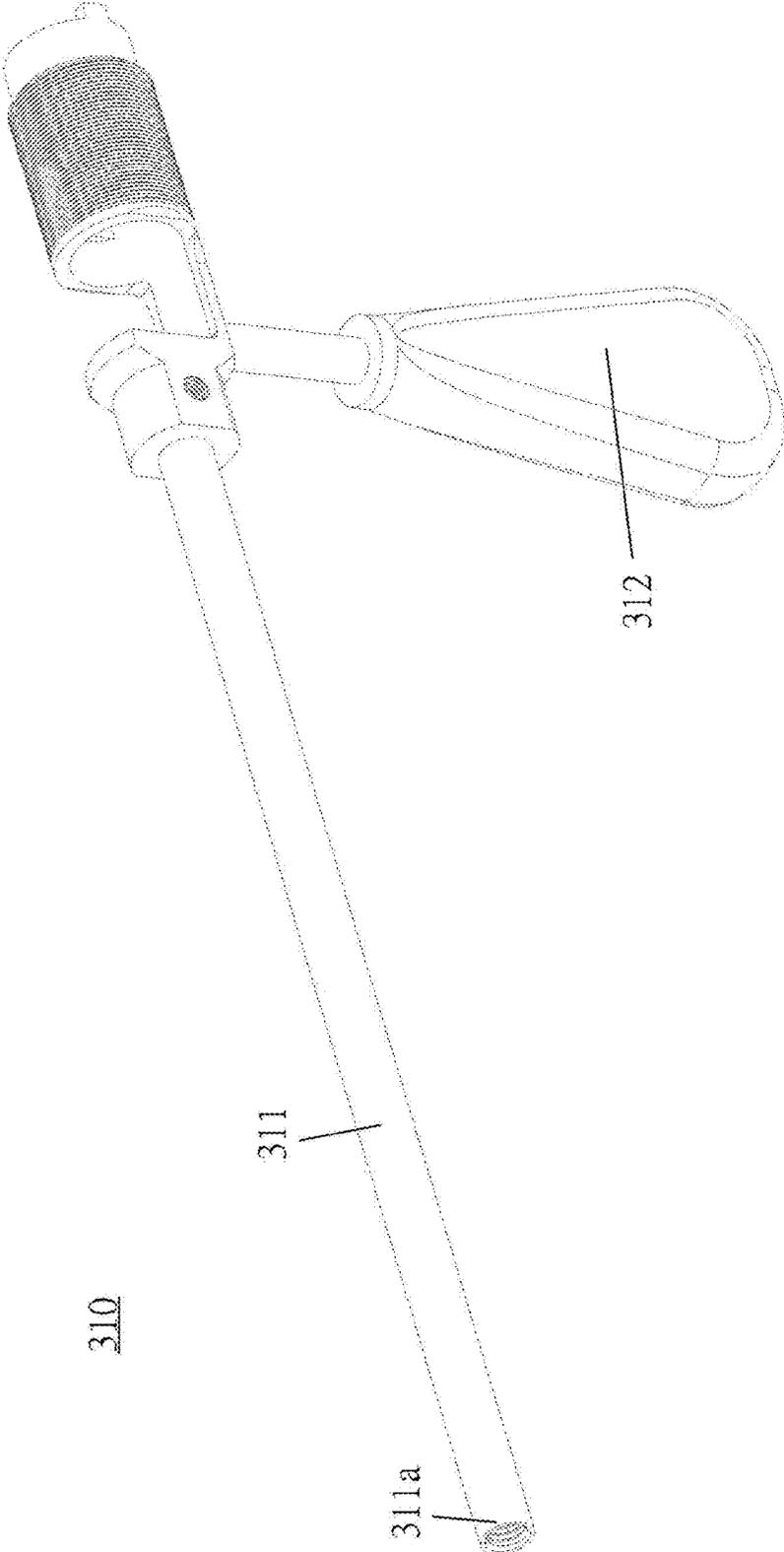


Fig.9A

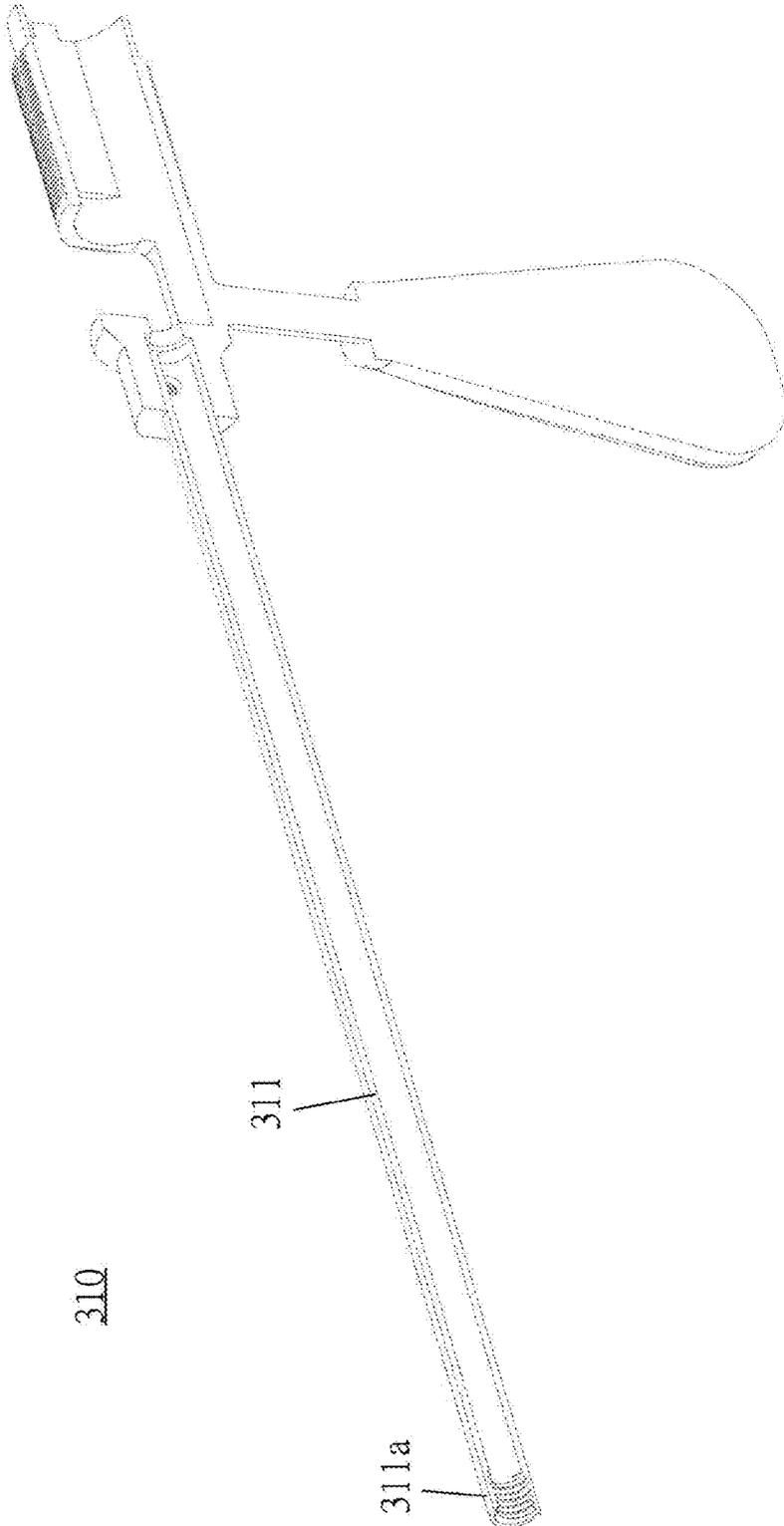


Fig.9B

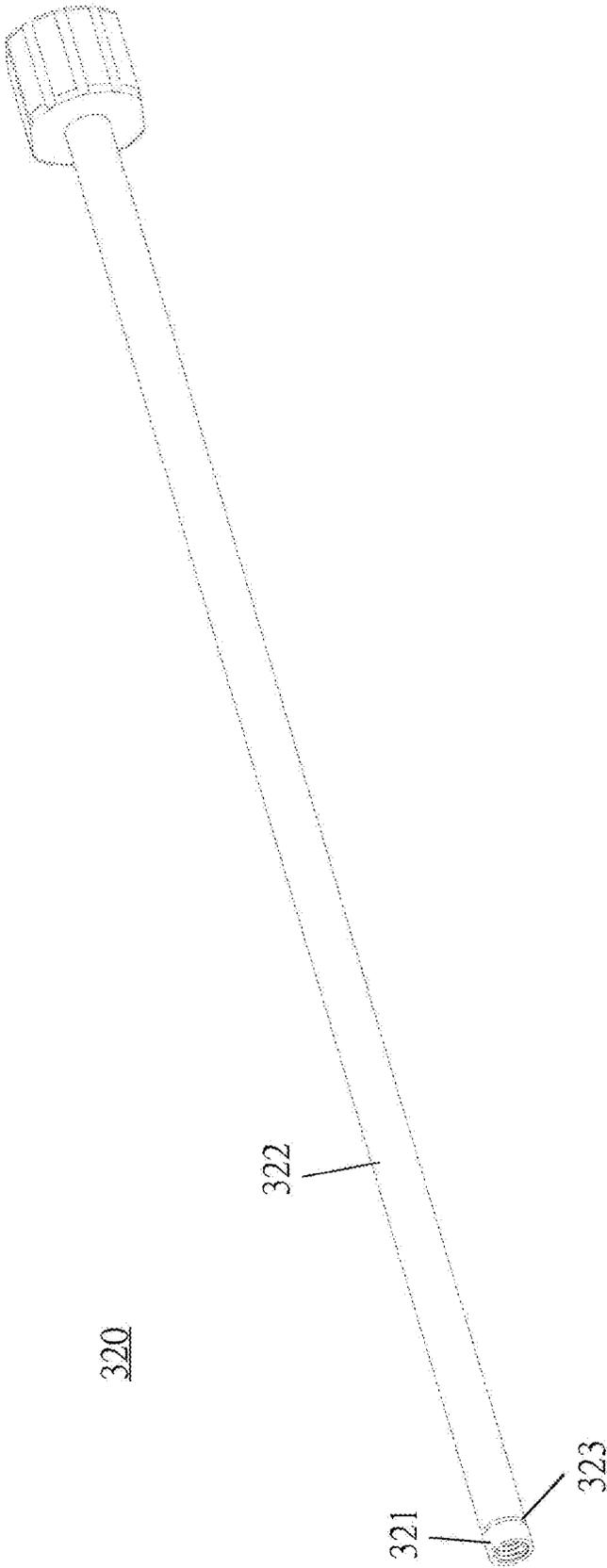


Fig. 10A



Fig.10B

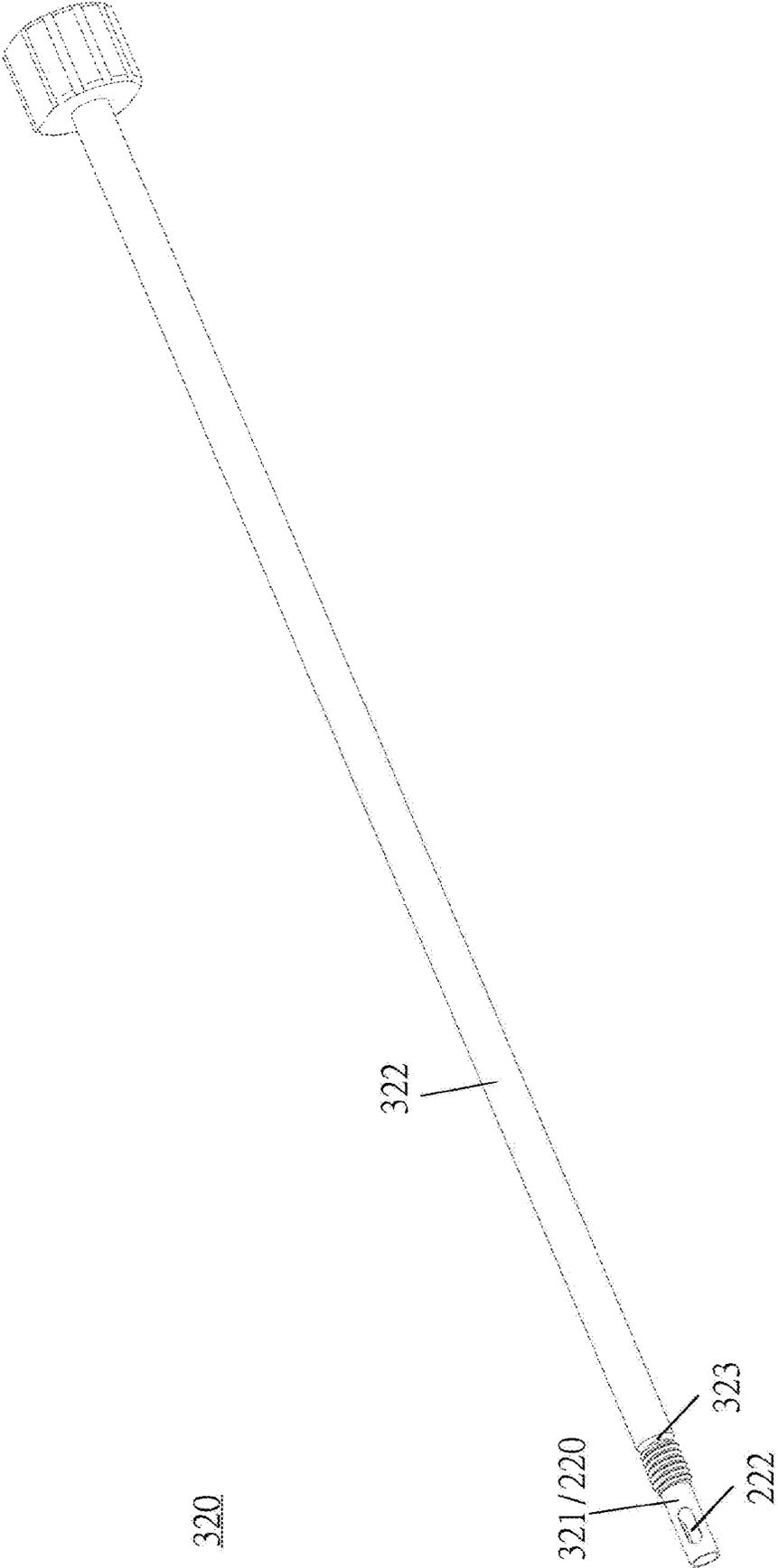


Fig.10C



Fig.11A

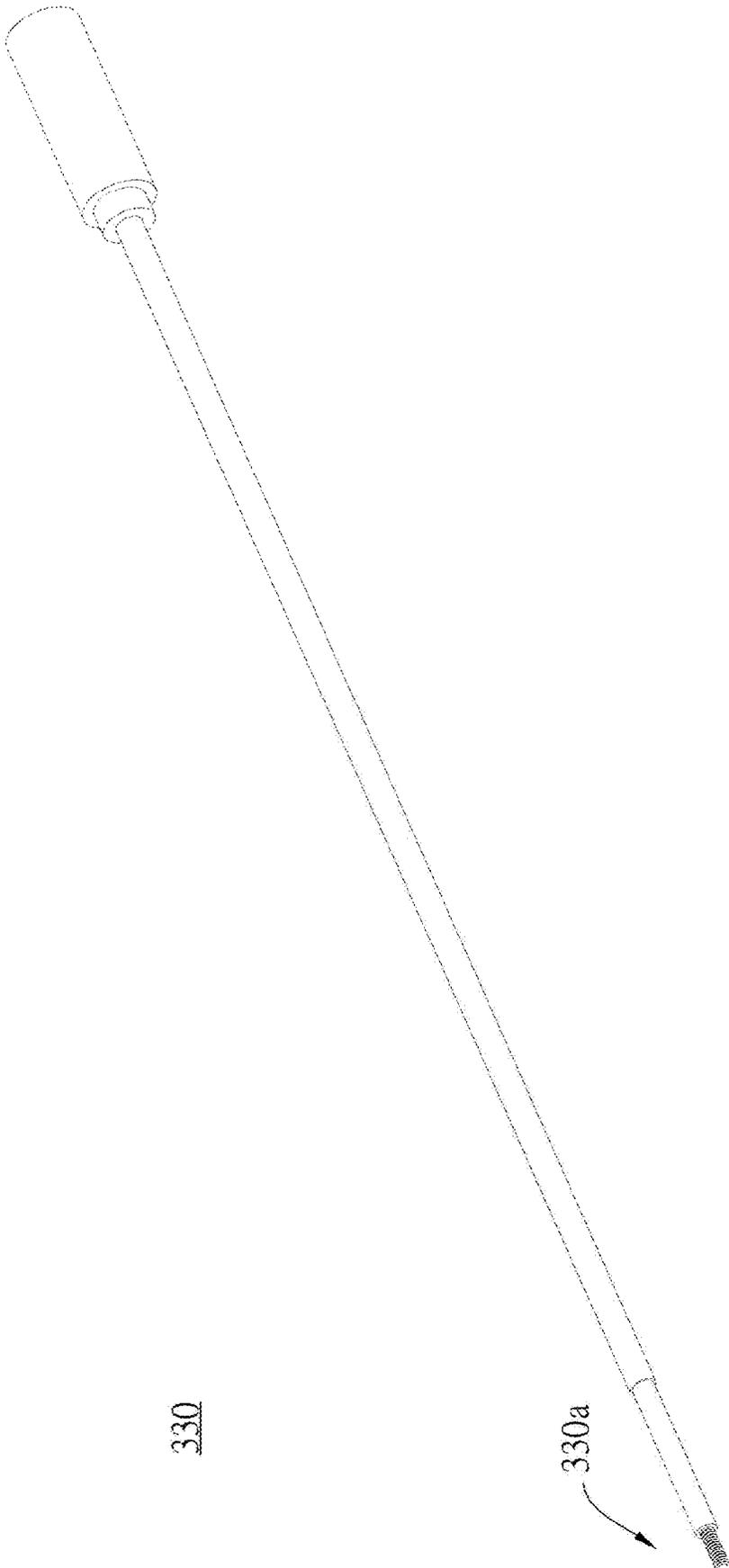
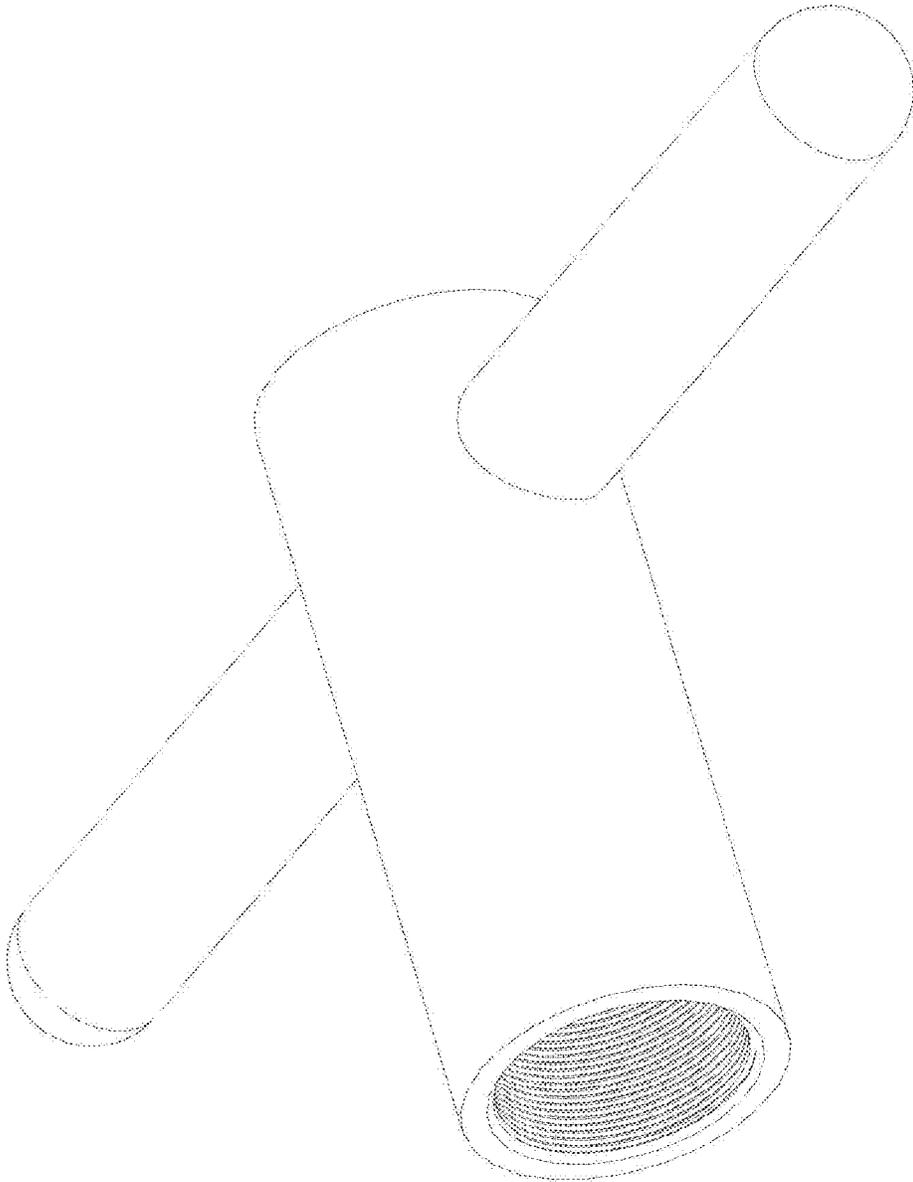


Fig. 1B



340

Fig. 12A

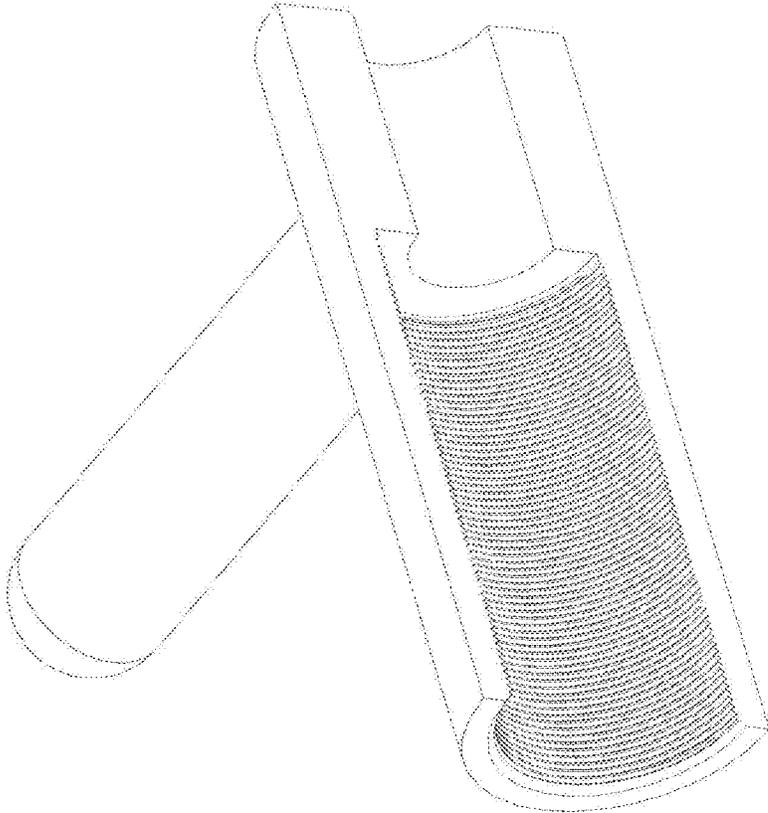


Fig.12B

340

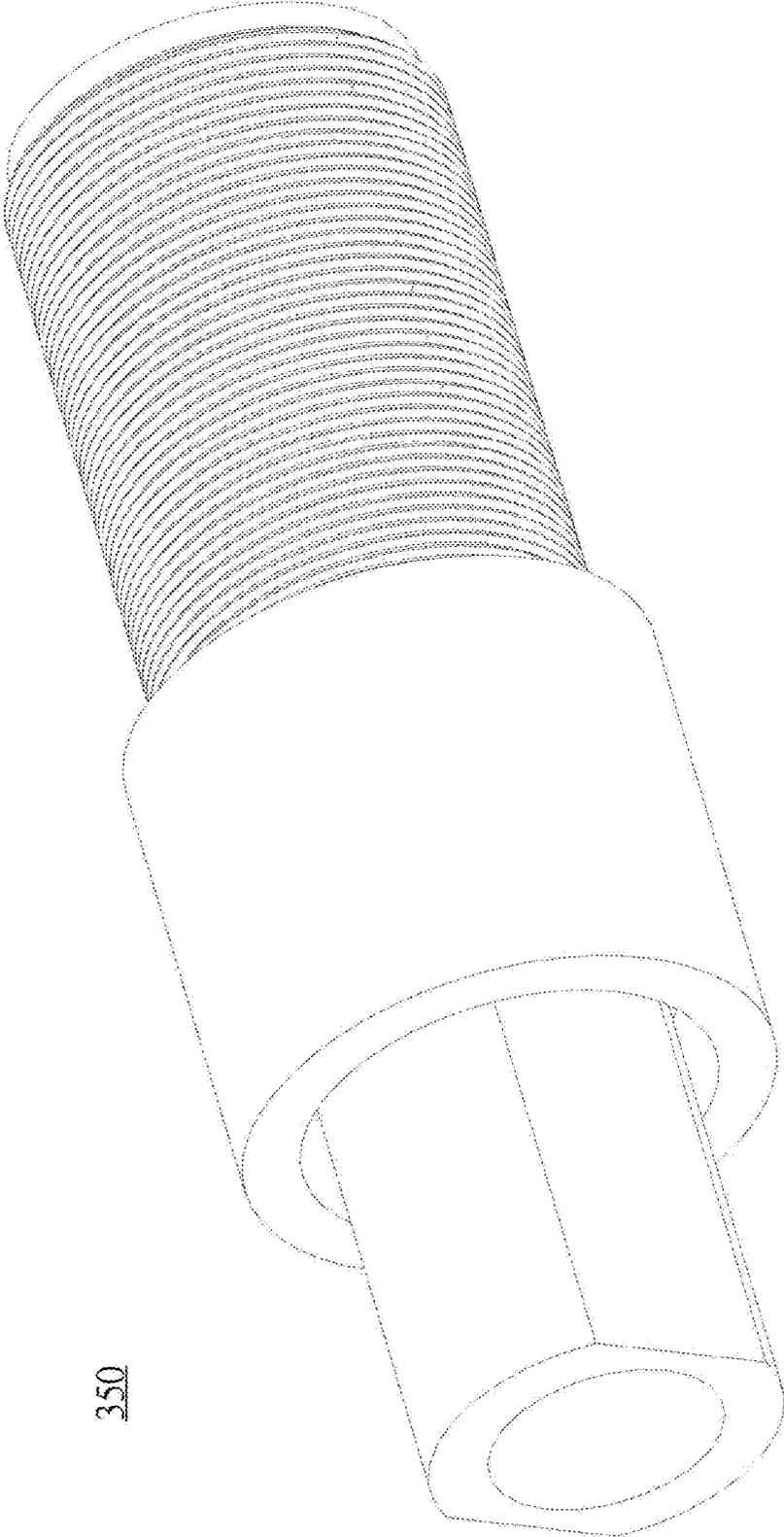


Fig.13A

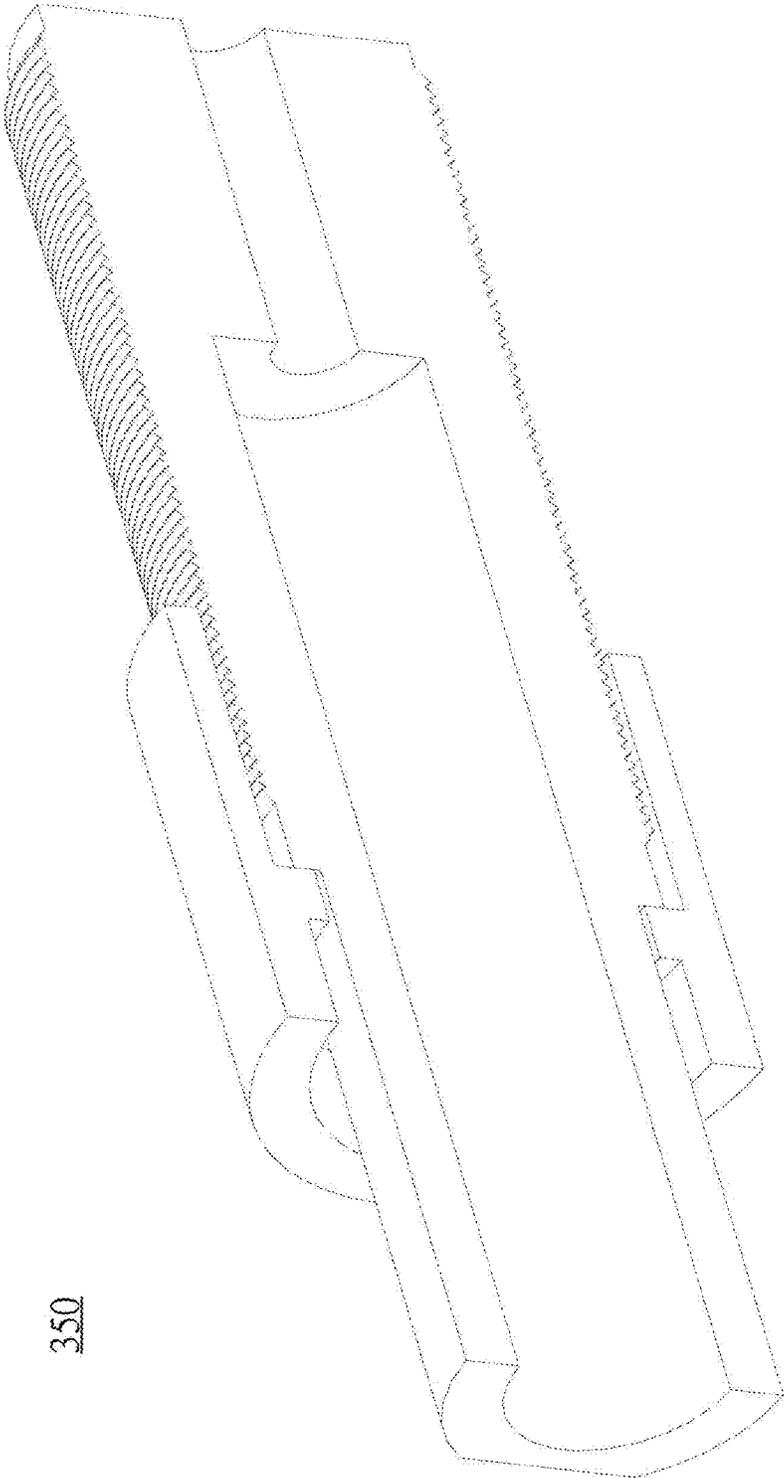
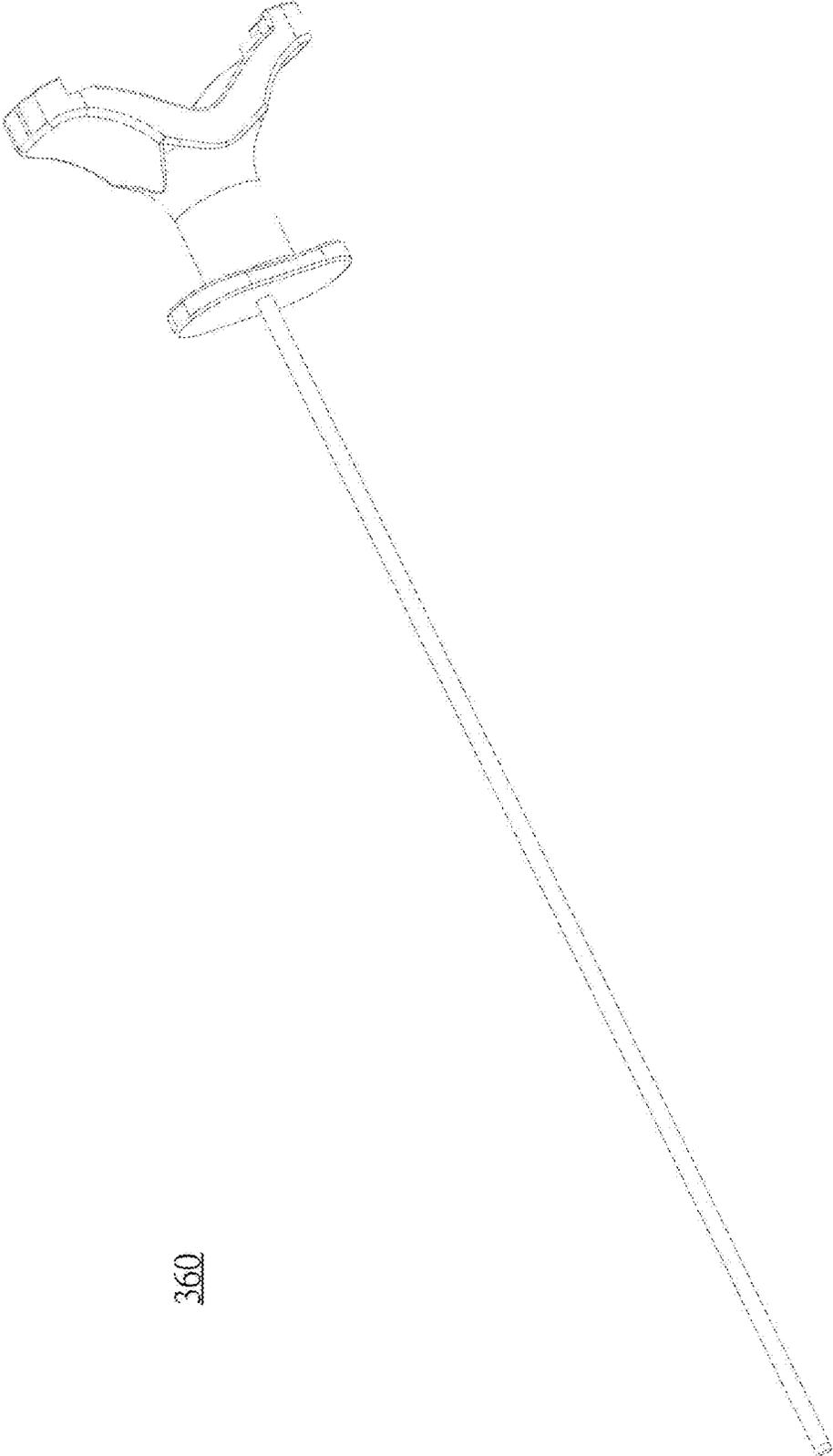
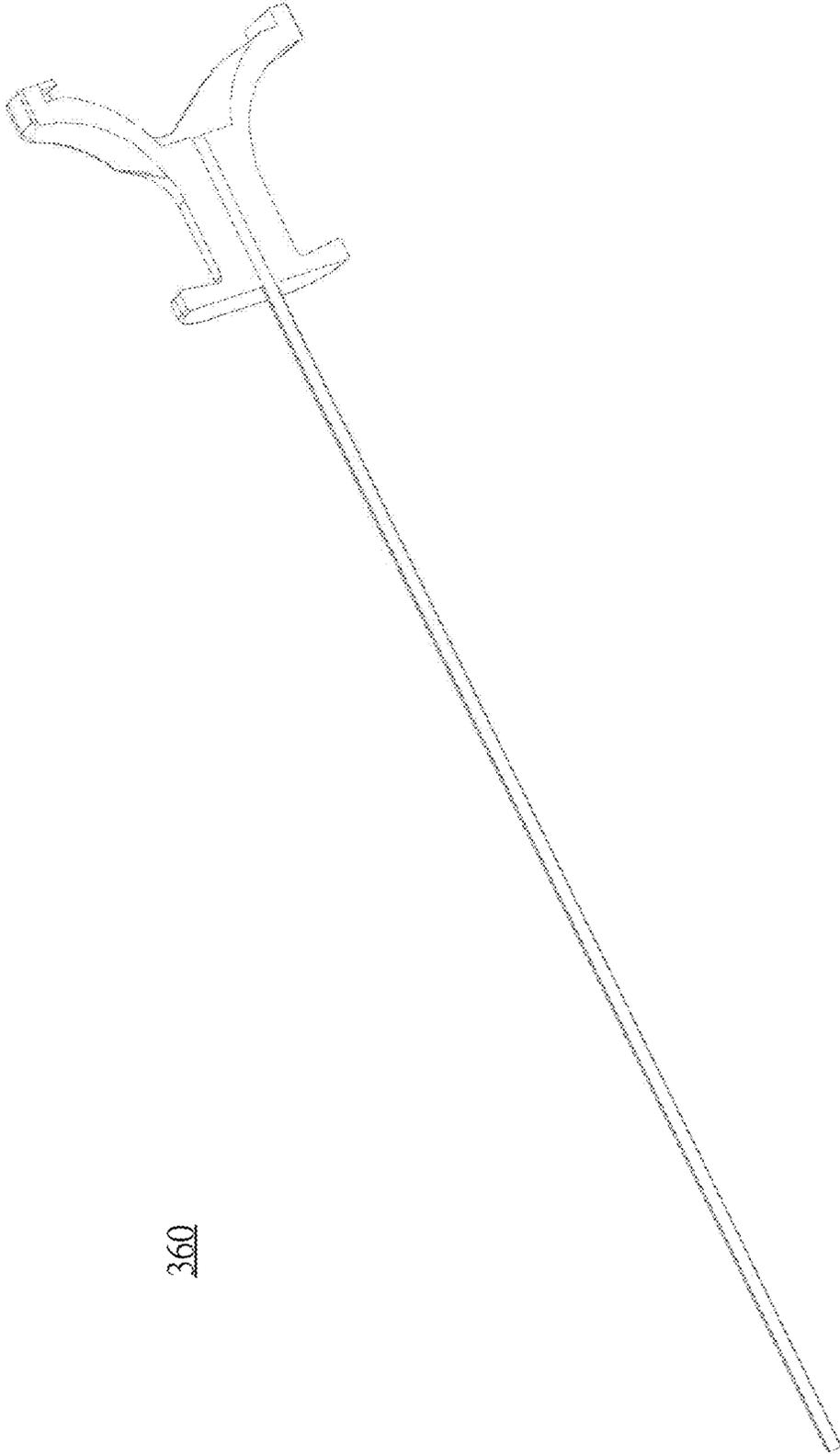


Fig.13B



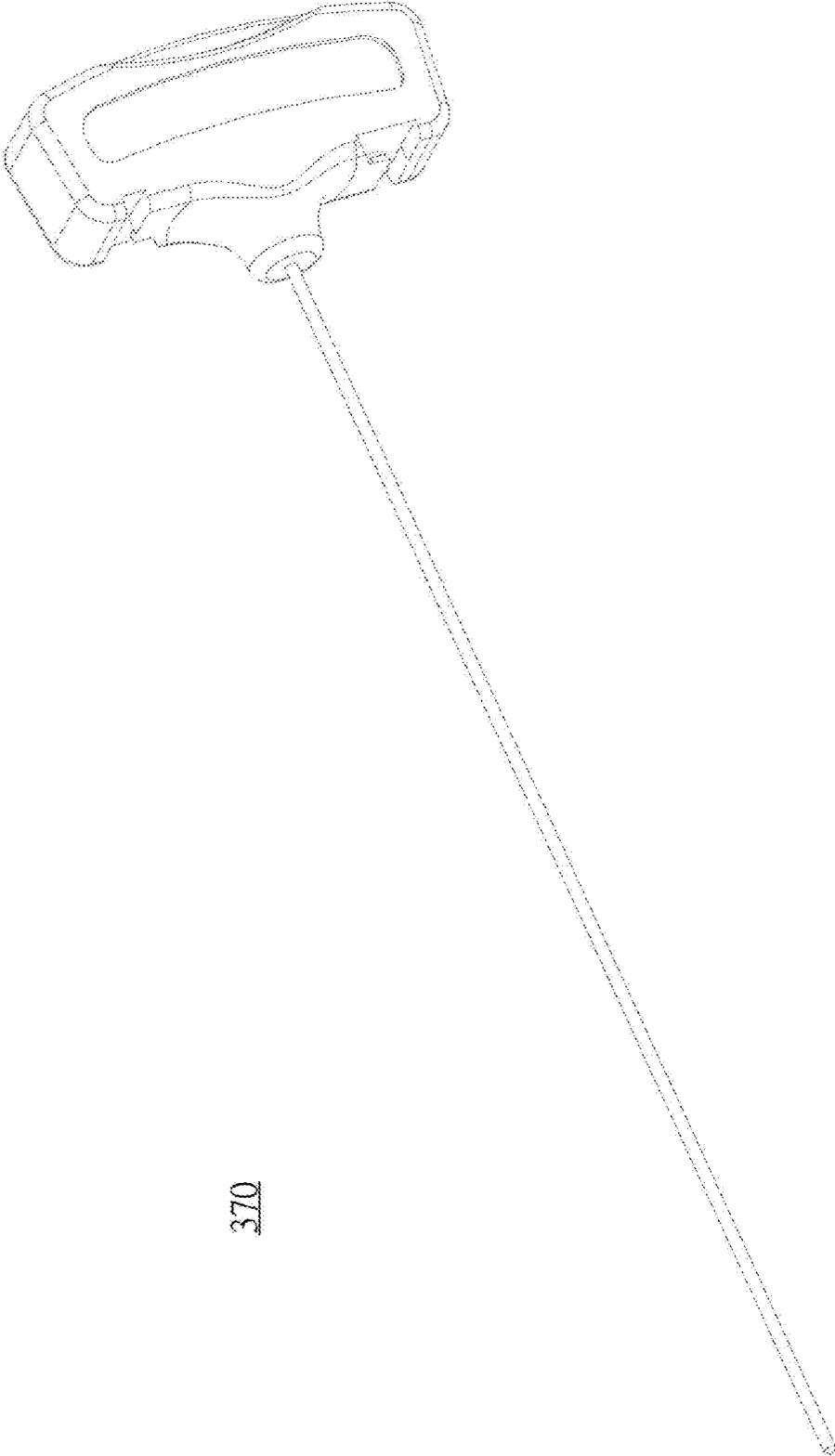
360

Fig. 14A



360

Fig.14B



370

Fig.15A

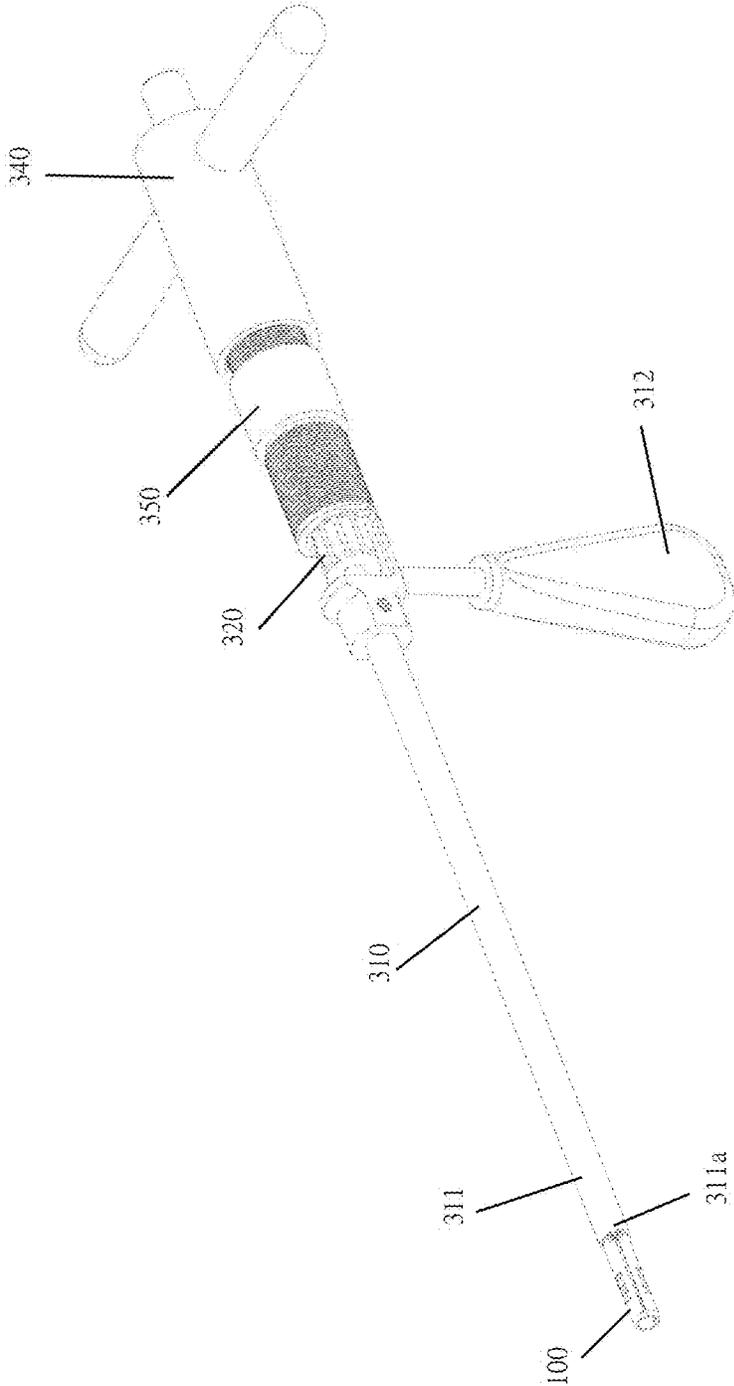


Fig. 16A

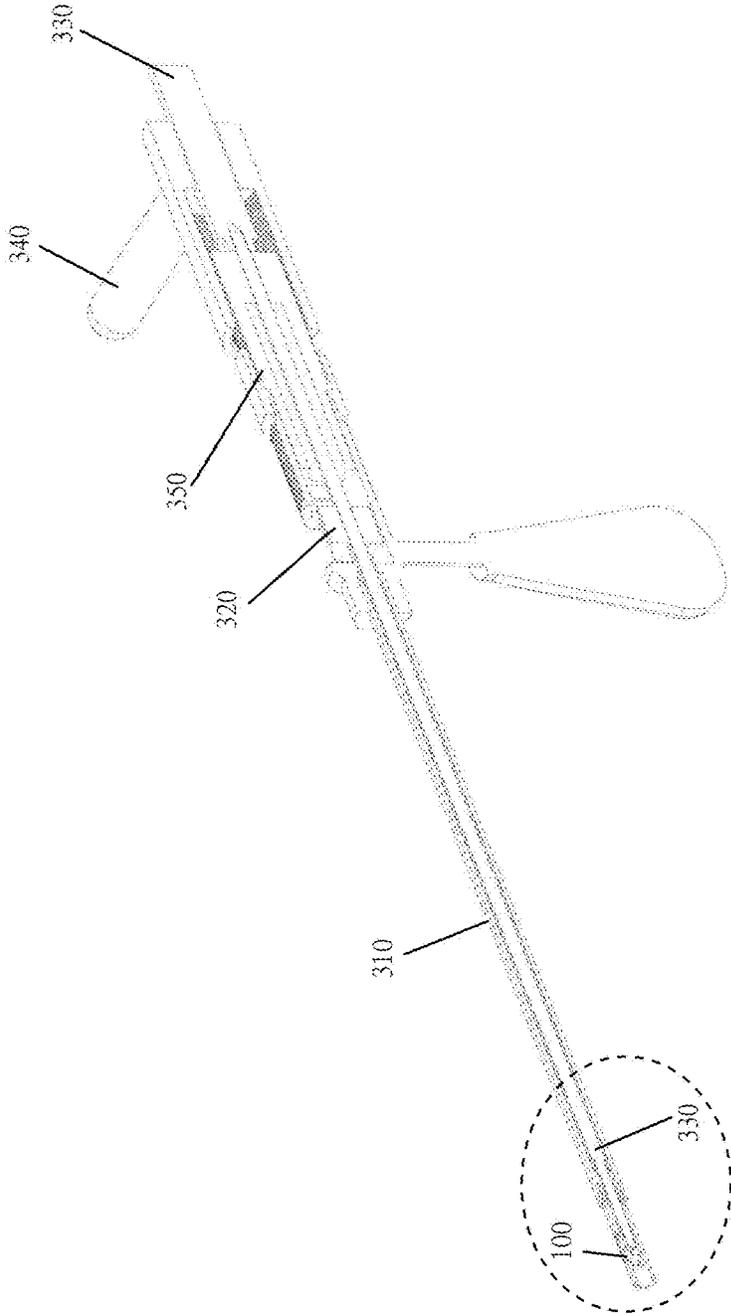


Fig. 16B

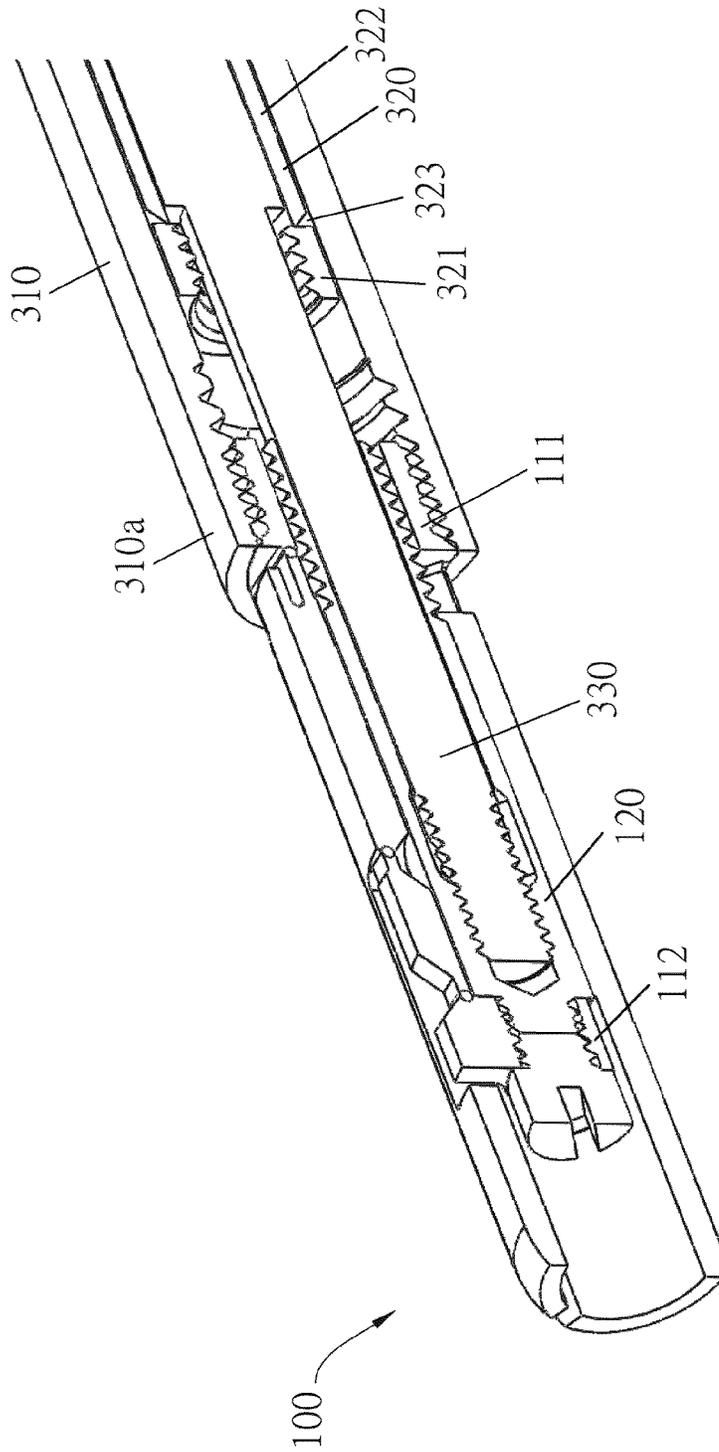


Fig.16C

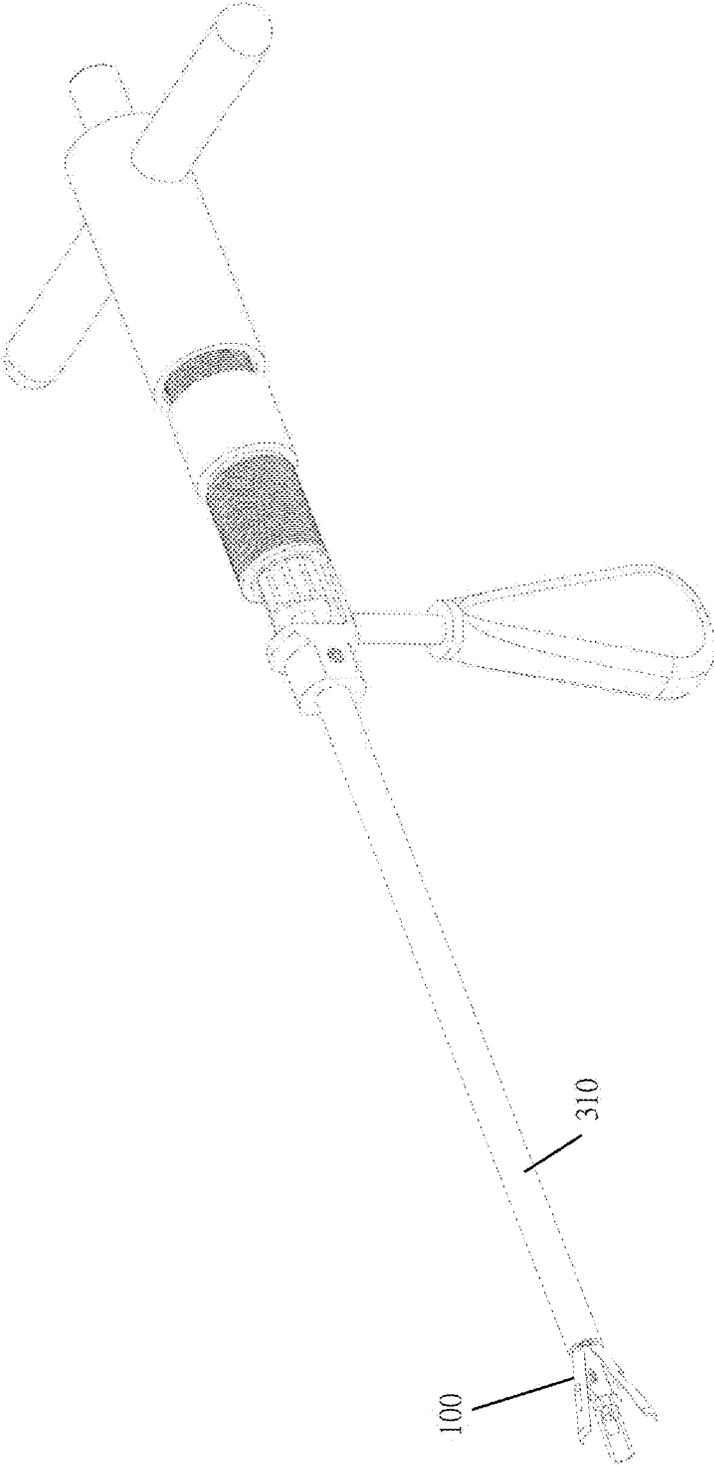


Fig. 17A

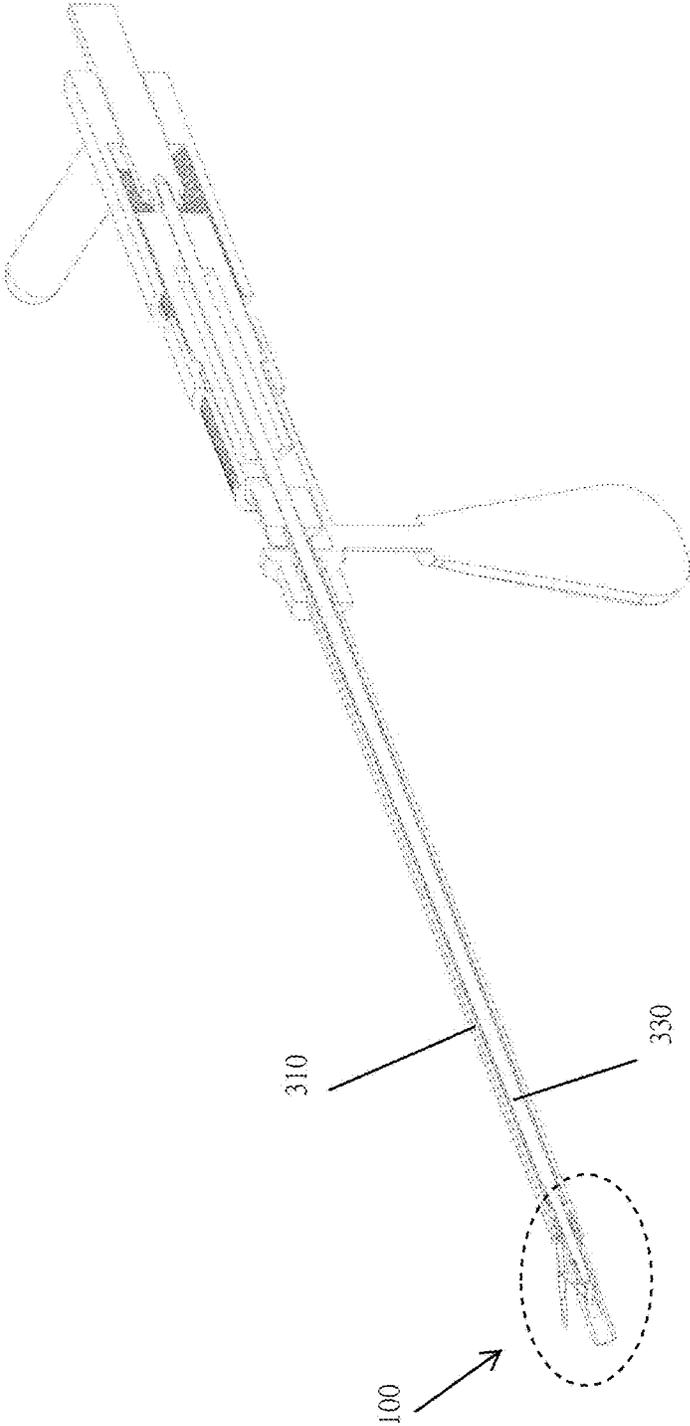


Fig. 17B

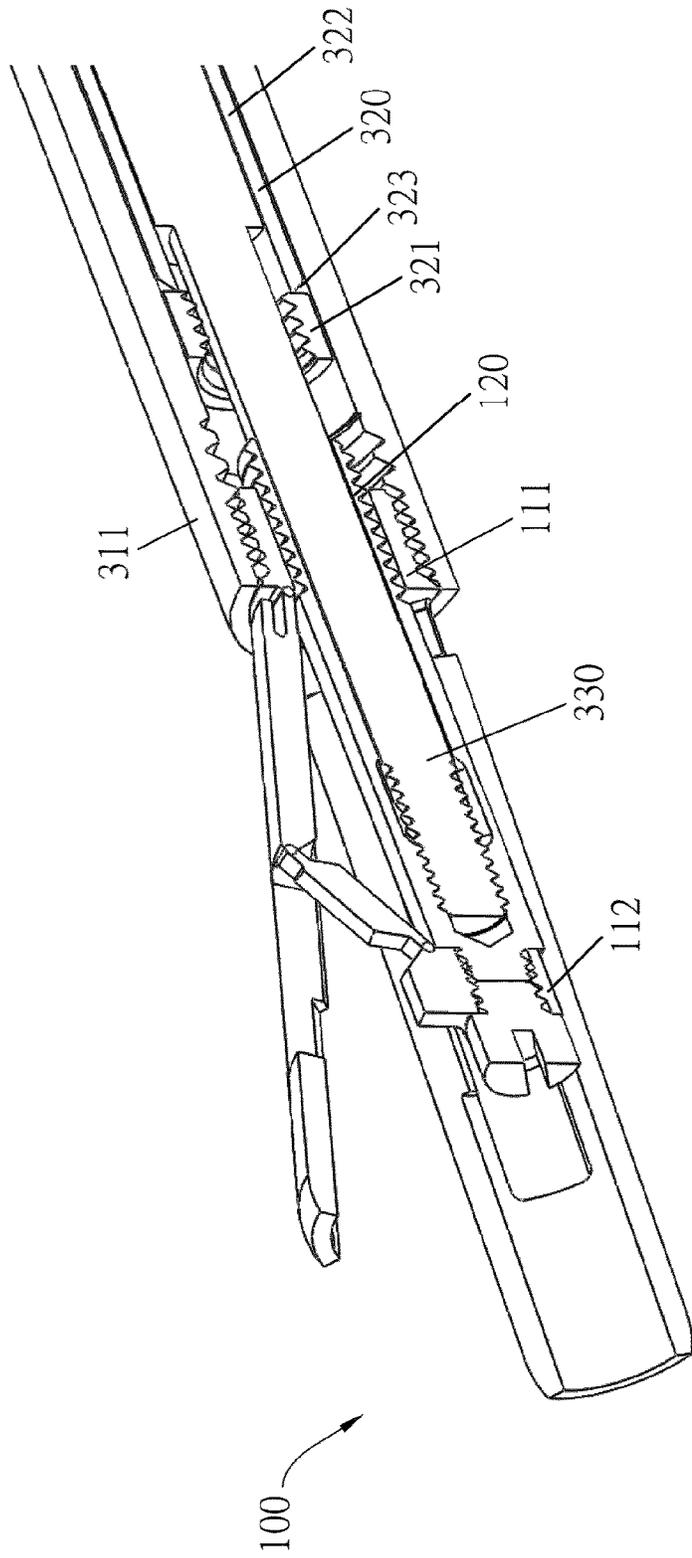


Fig.17C

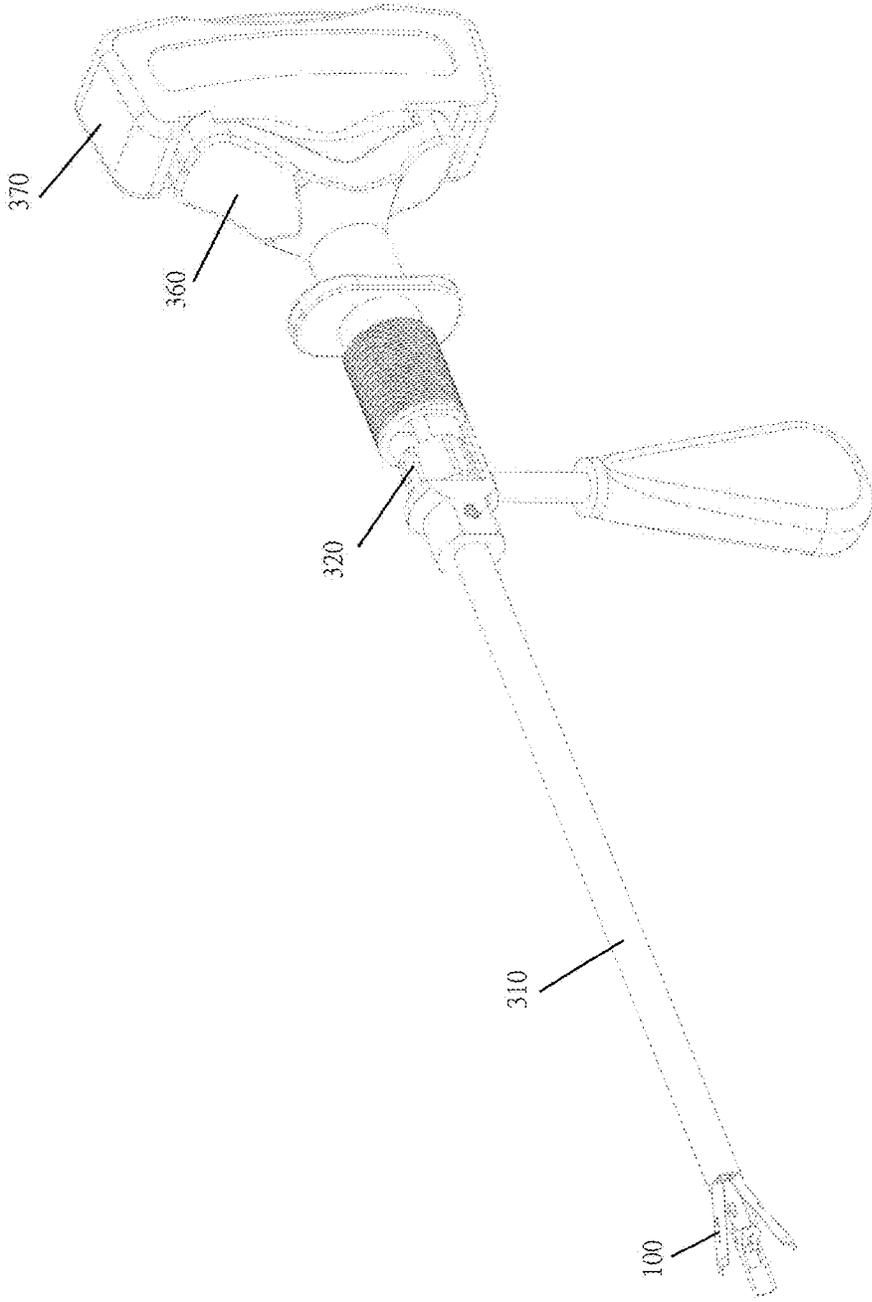


Fig. 18A

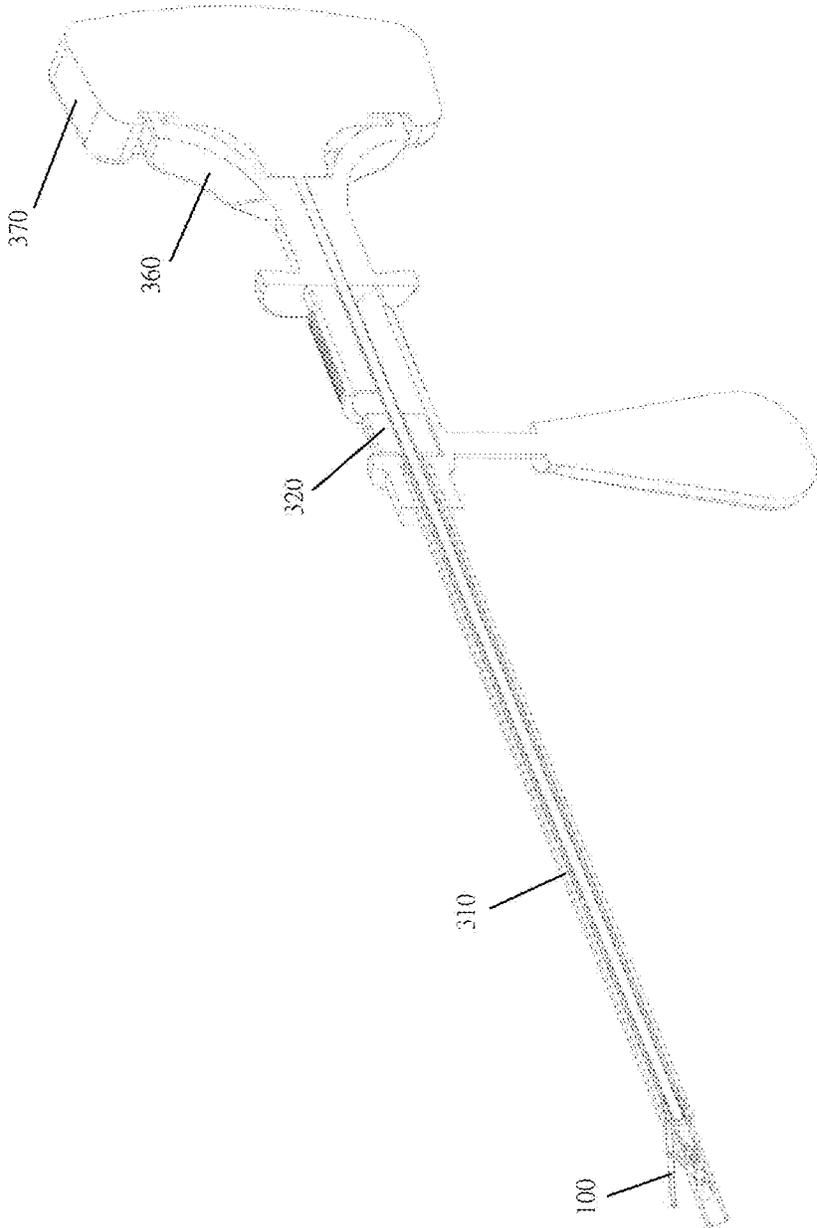


Fig. 18B

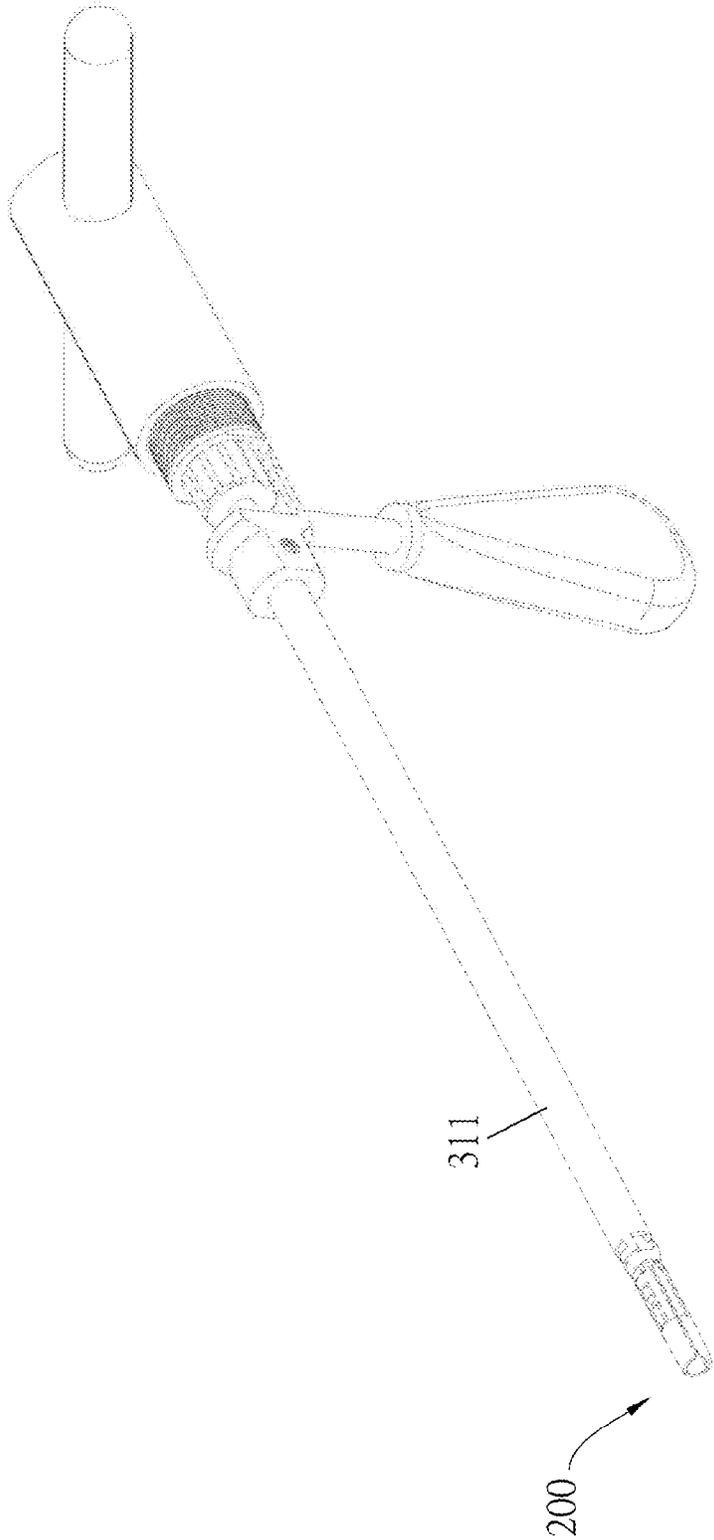


Fig.19A

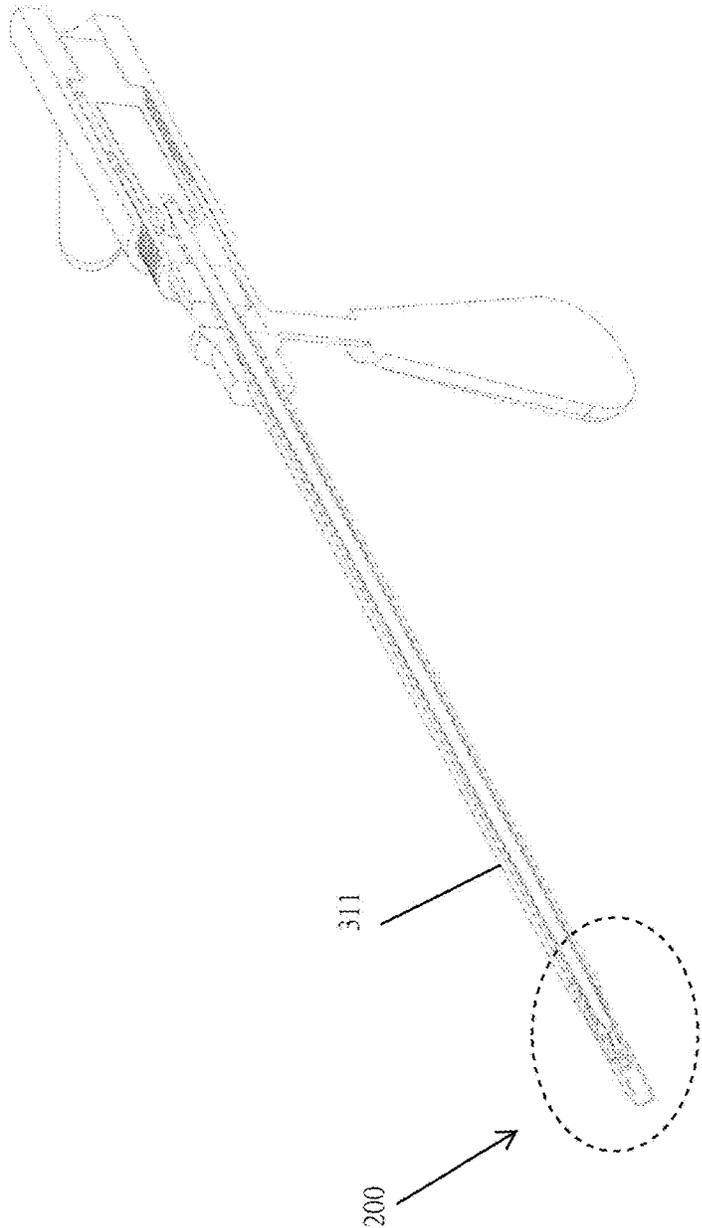


Fig. 19B

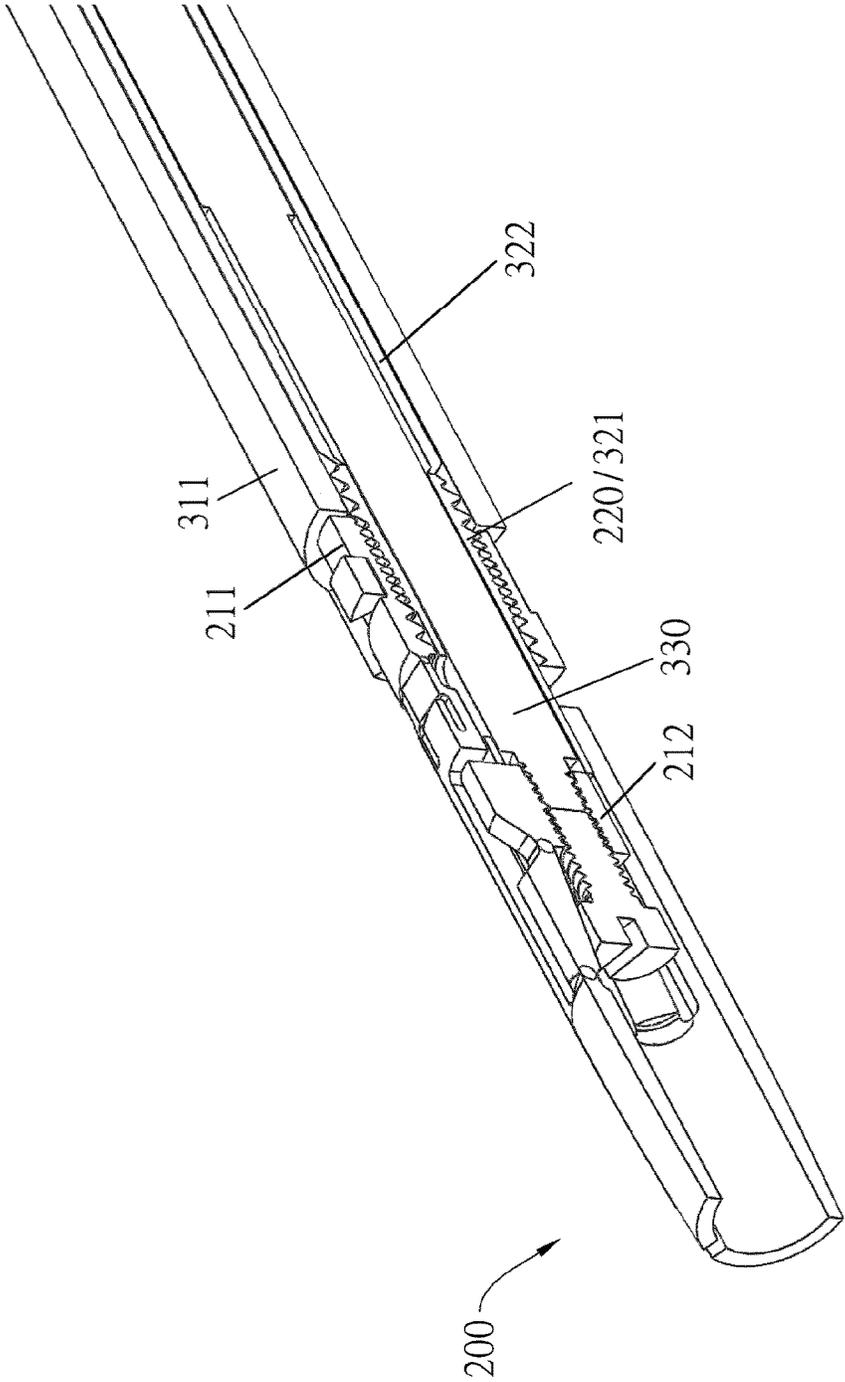


Fig.19C

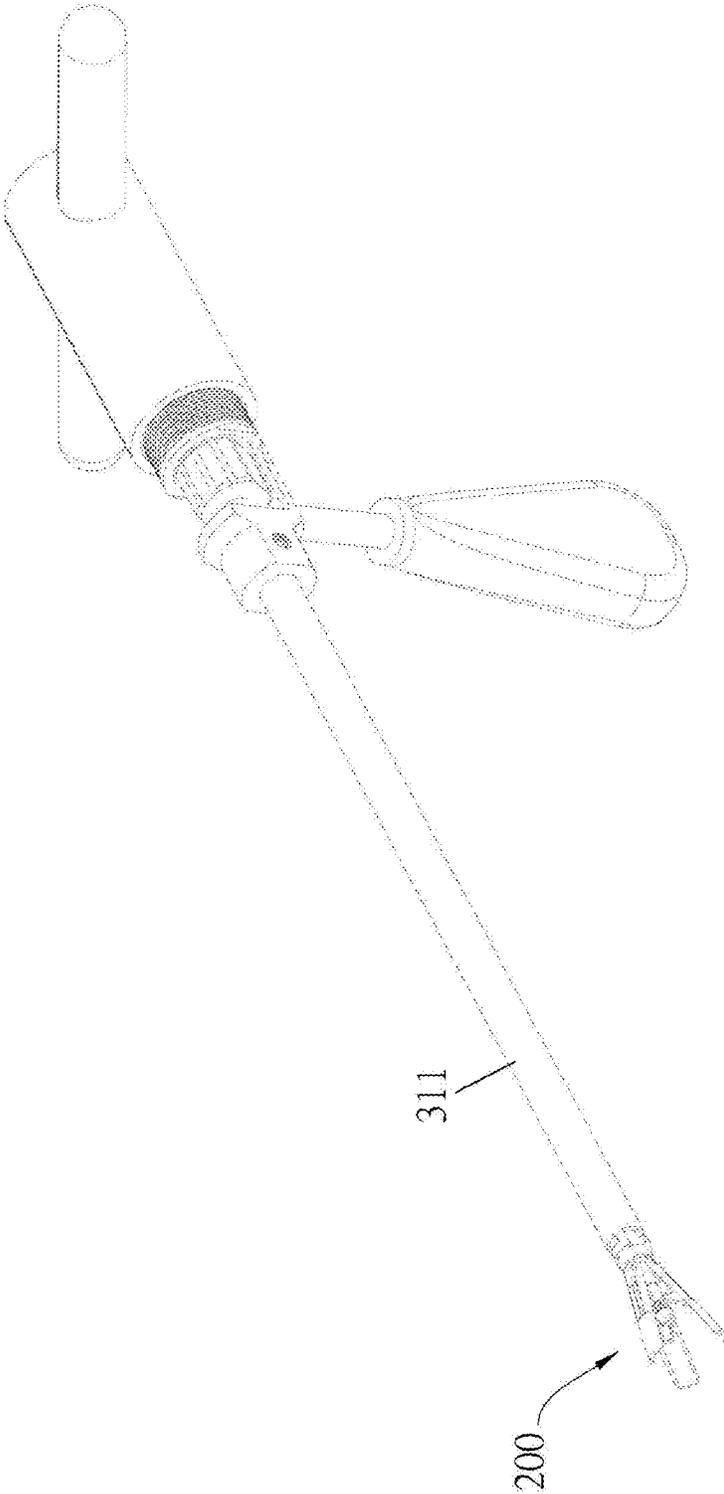


Fig. 20A

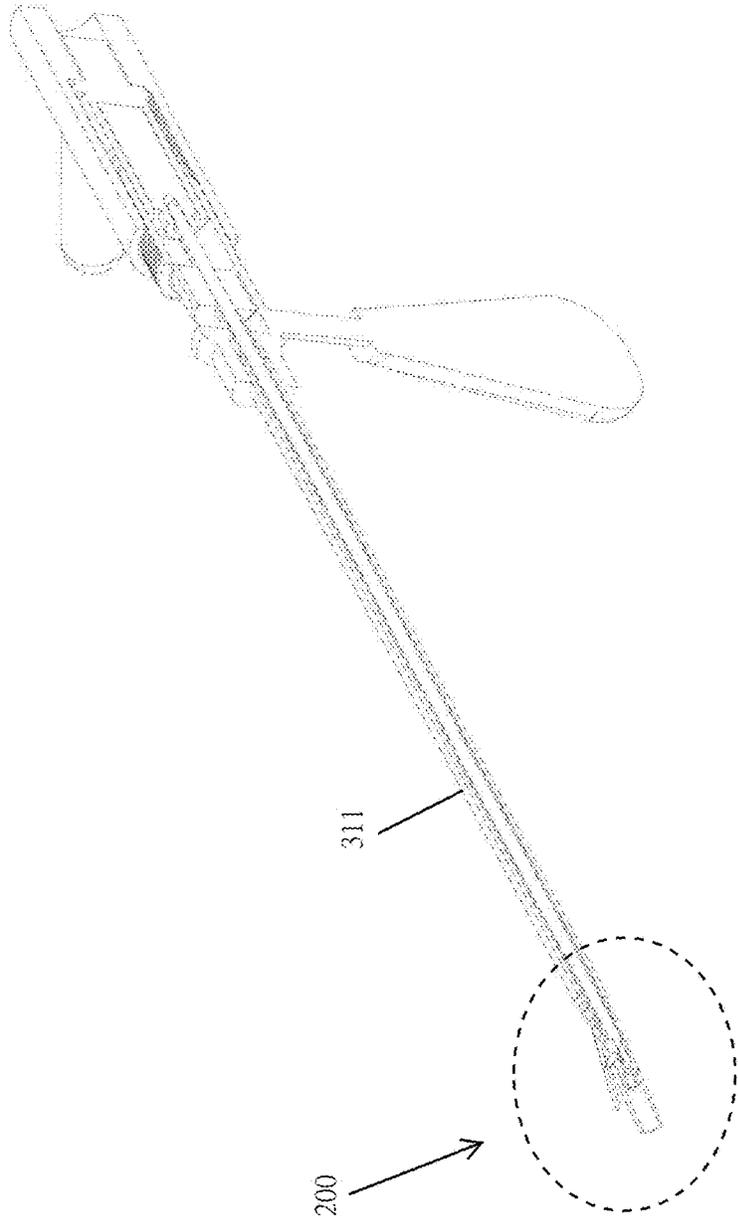


Fig. 20B

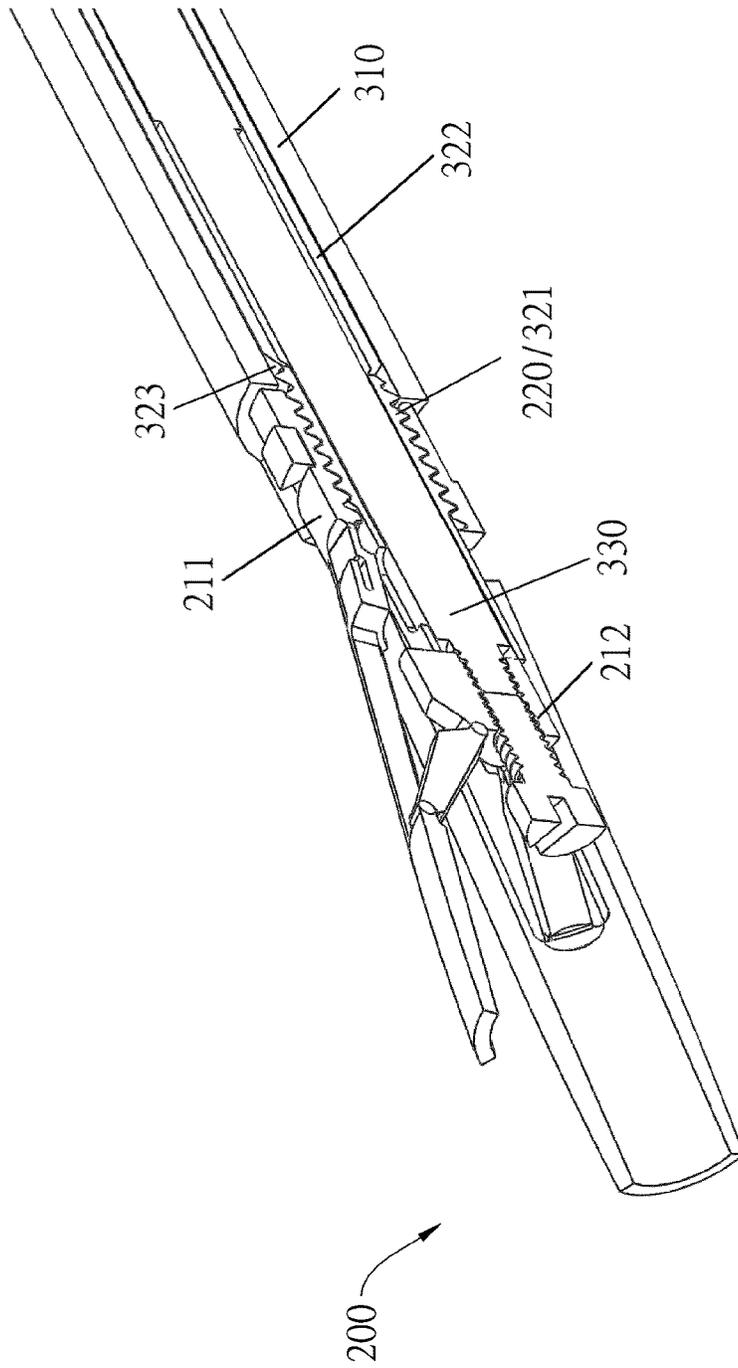


Fig.20C

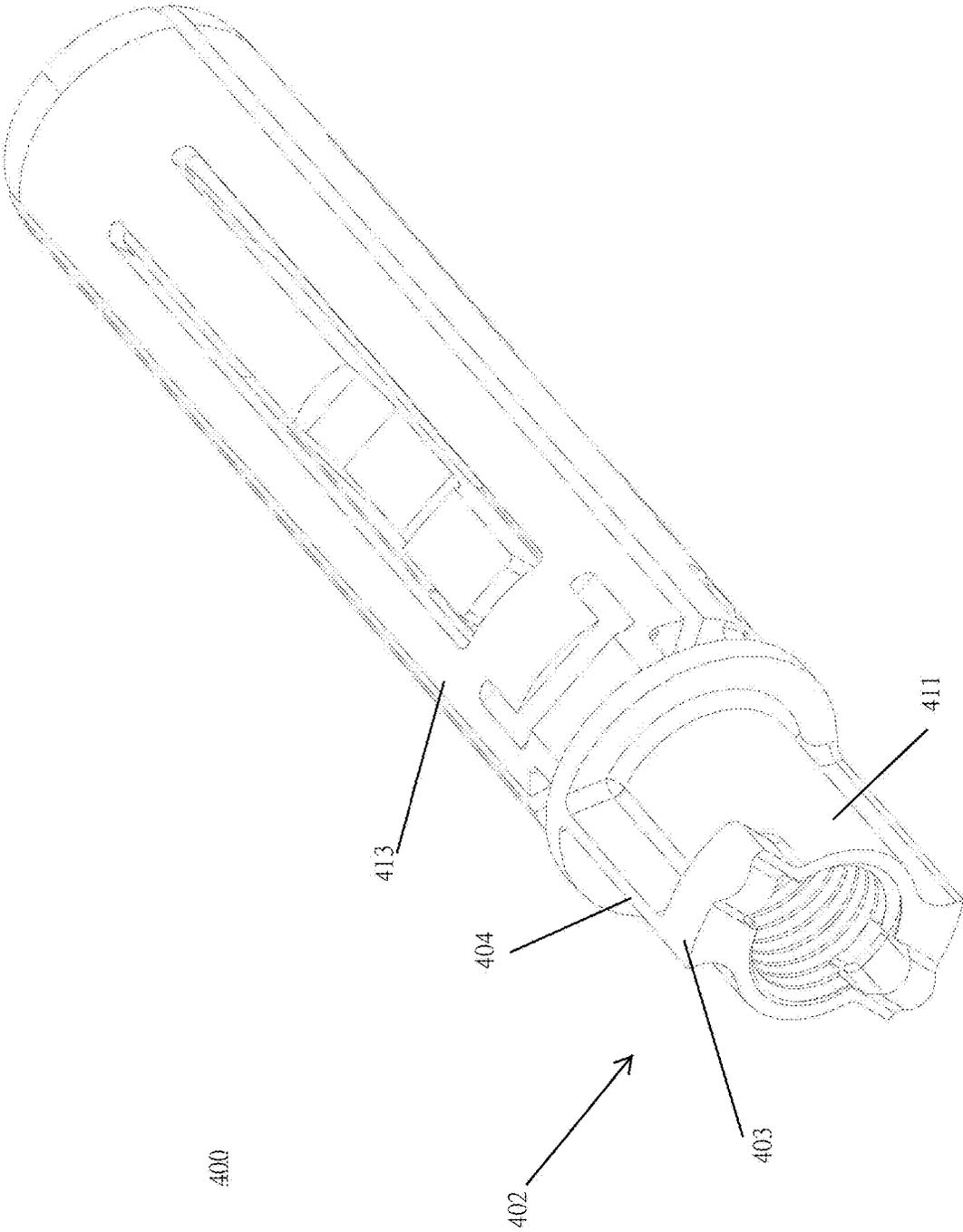


Fig. 21A

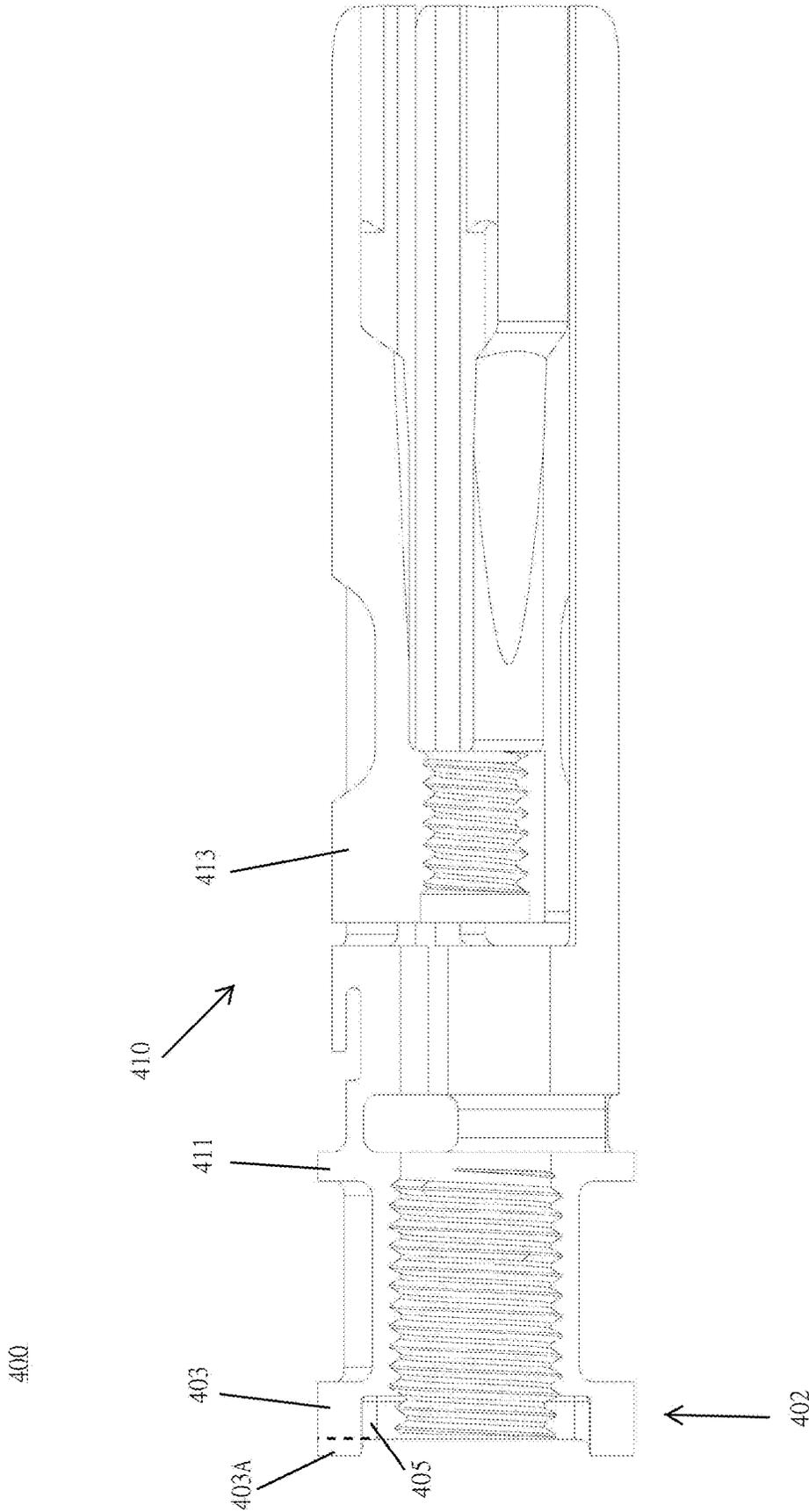


Fig. 21B

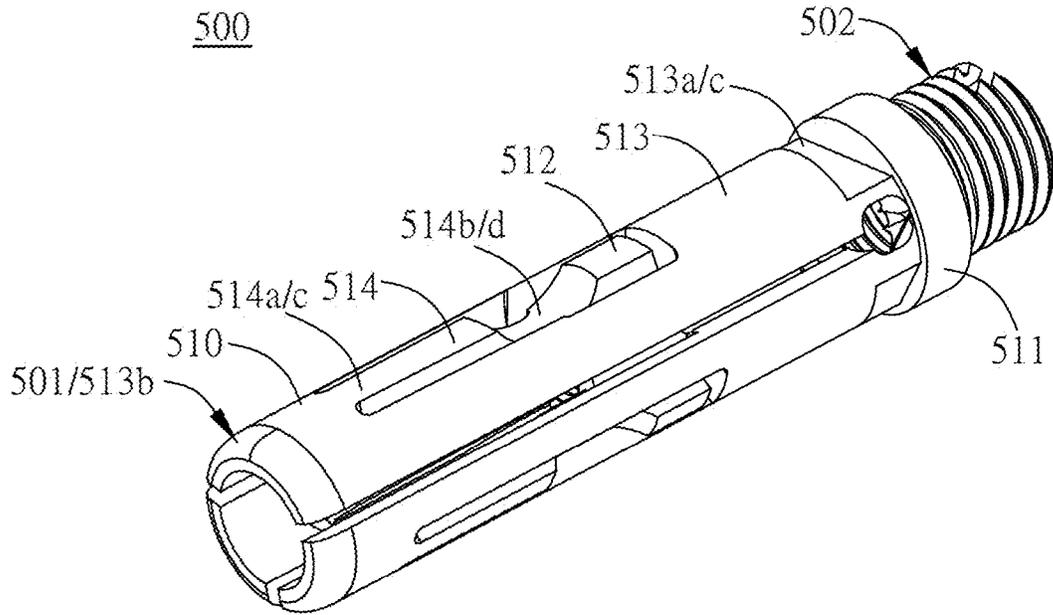


Fig. 22A

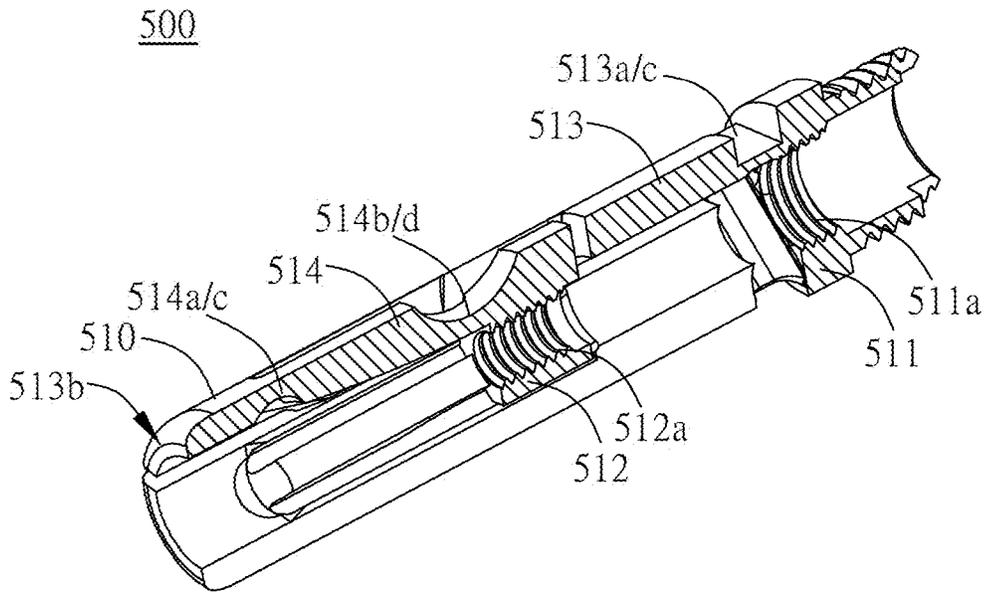


Fig. 22B

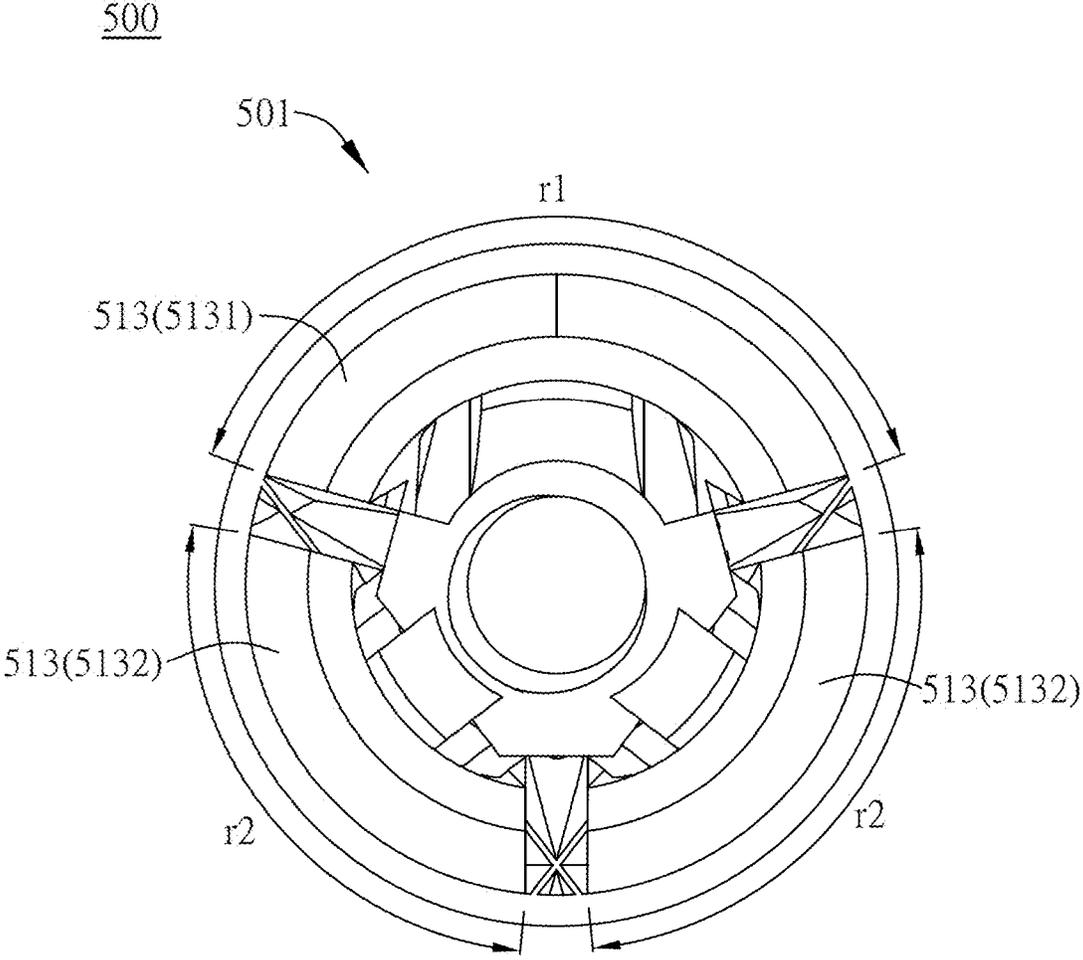


Fig. 22C

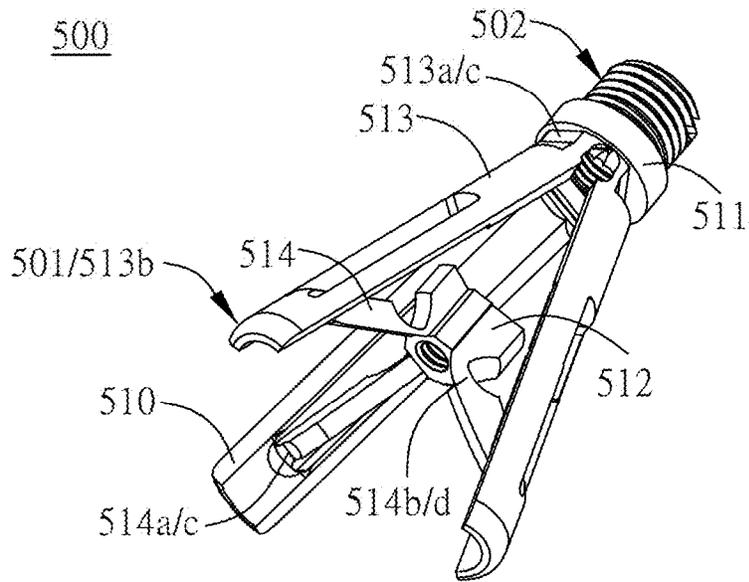


Fig. 23A

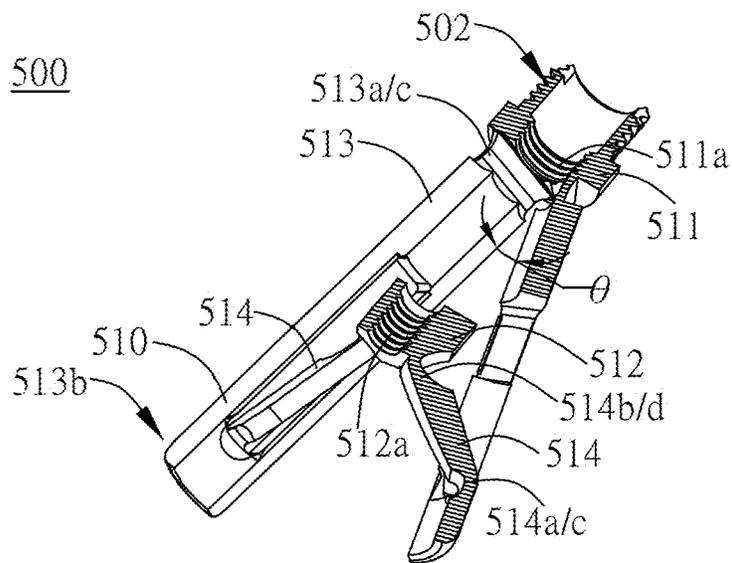


Fig. 23B

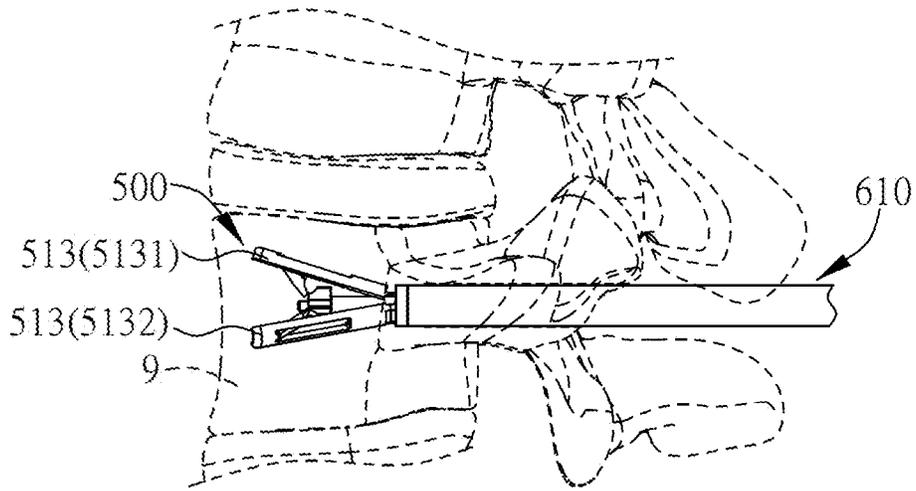


Fig. 24

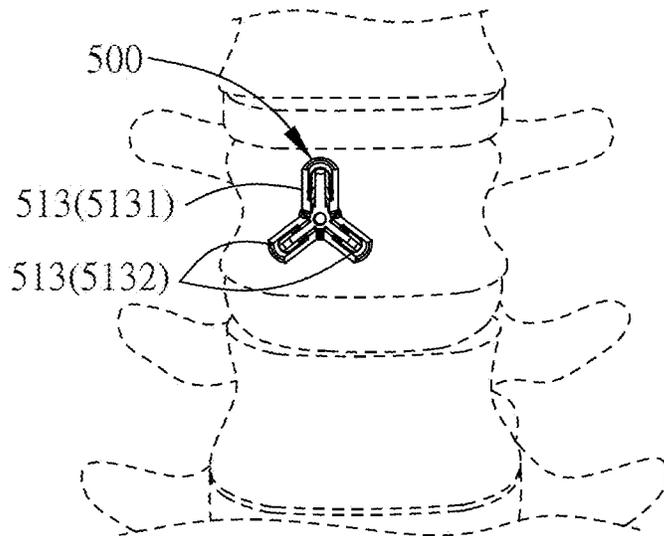


Fig. 25

Fig. 26A

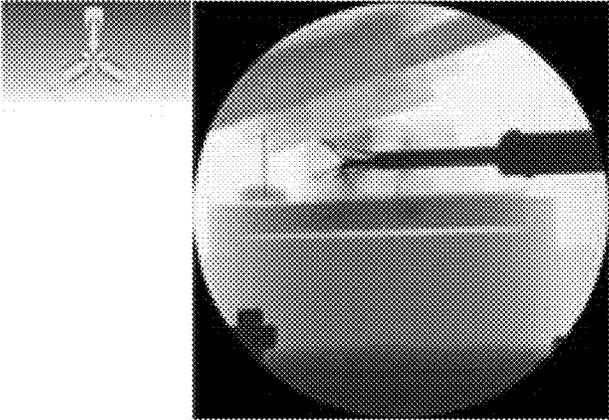


Fig. 26B

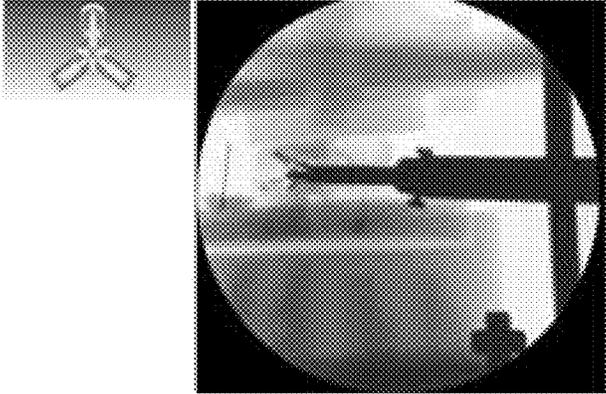
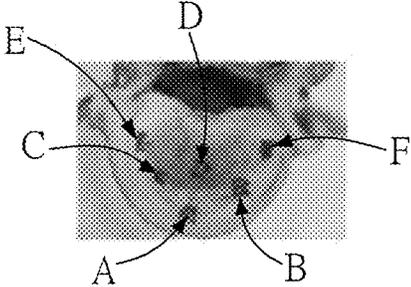


Fig. 26C



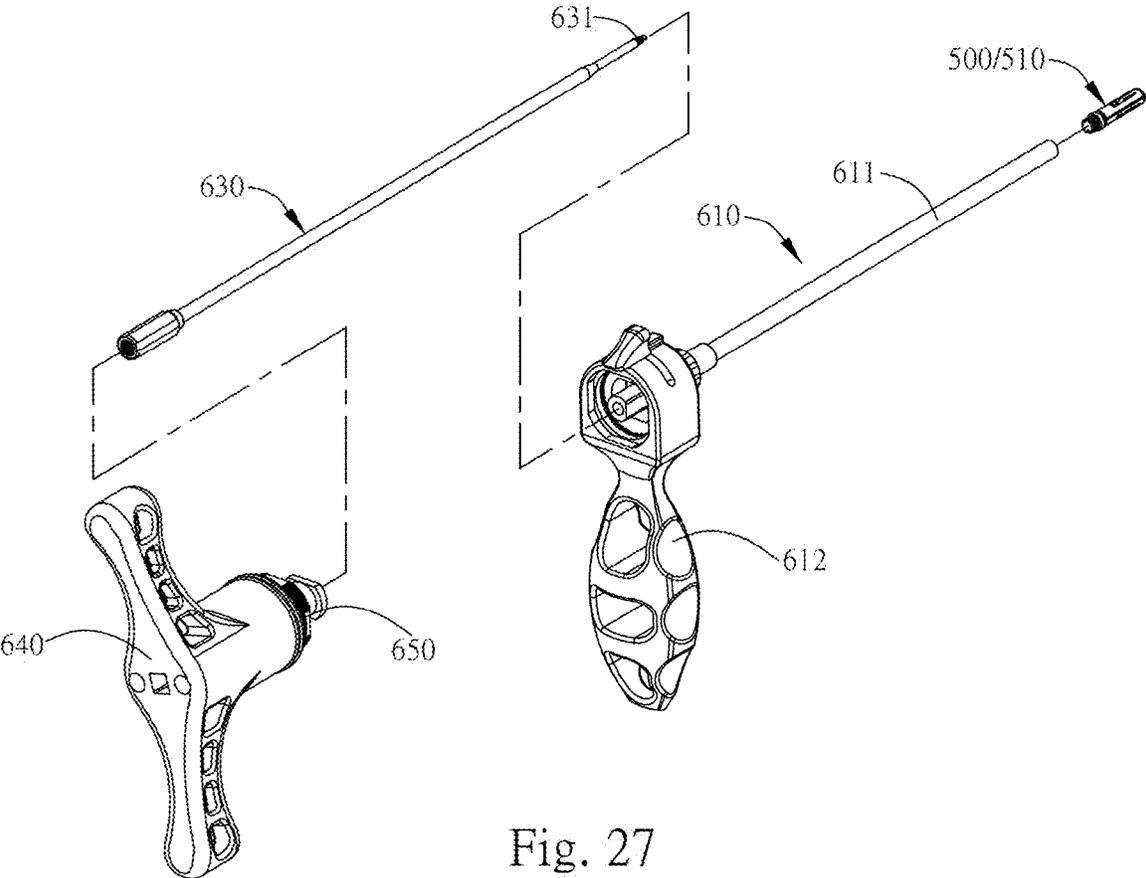


Fig. 27

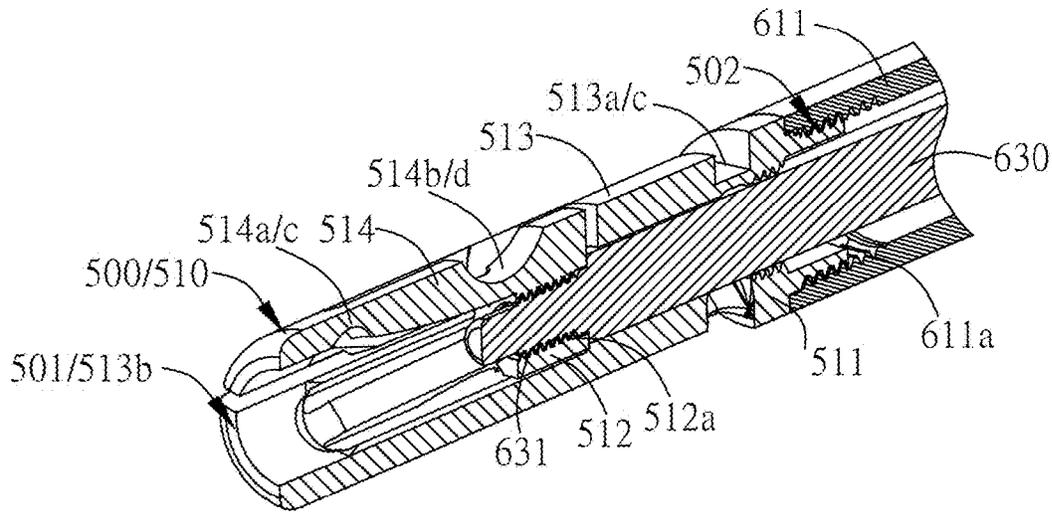


Fig. 28A

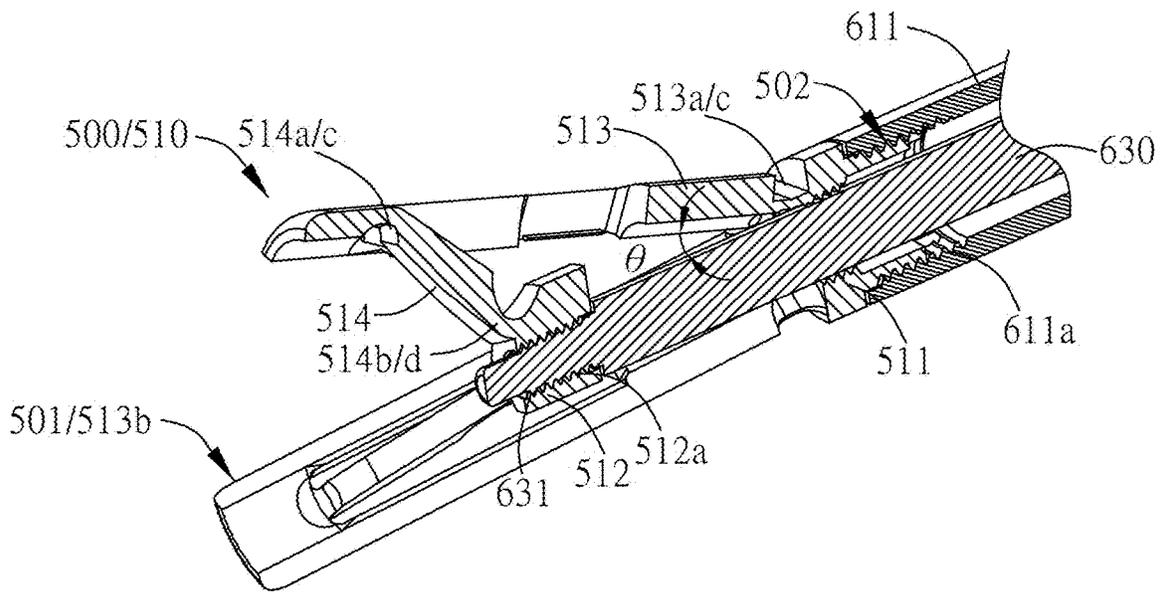


Fig. 28B

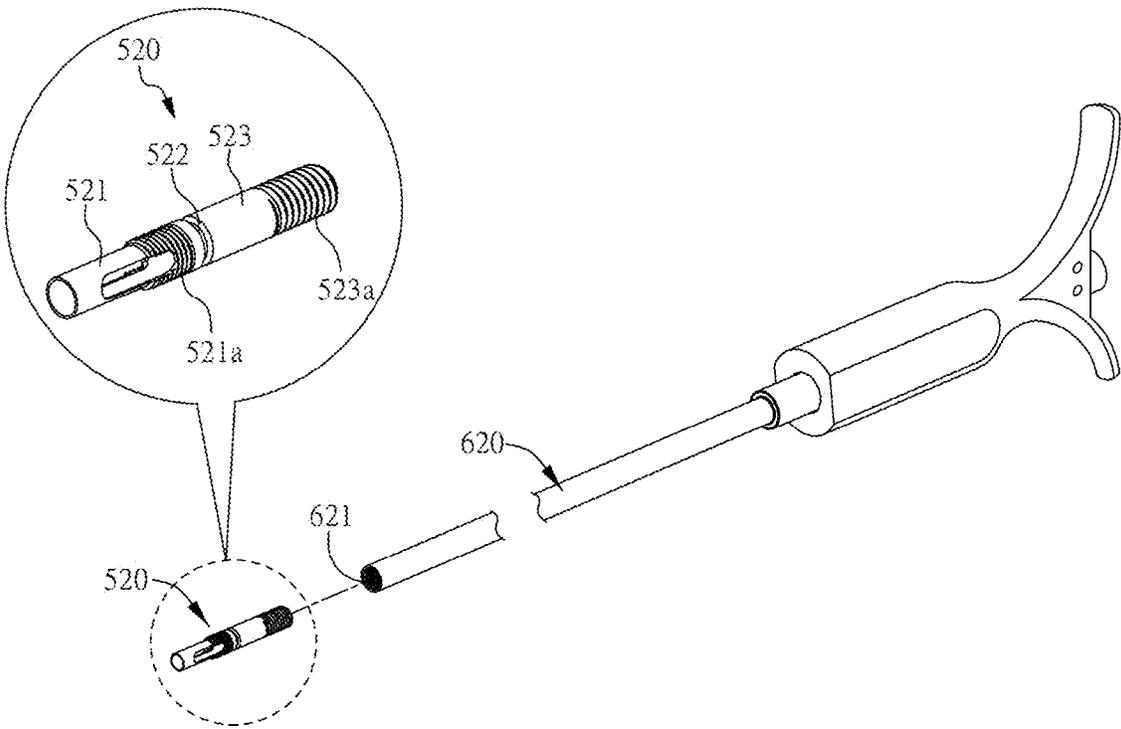


Fig. 29

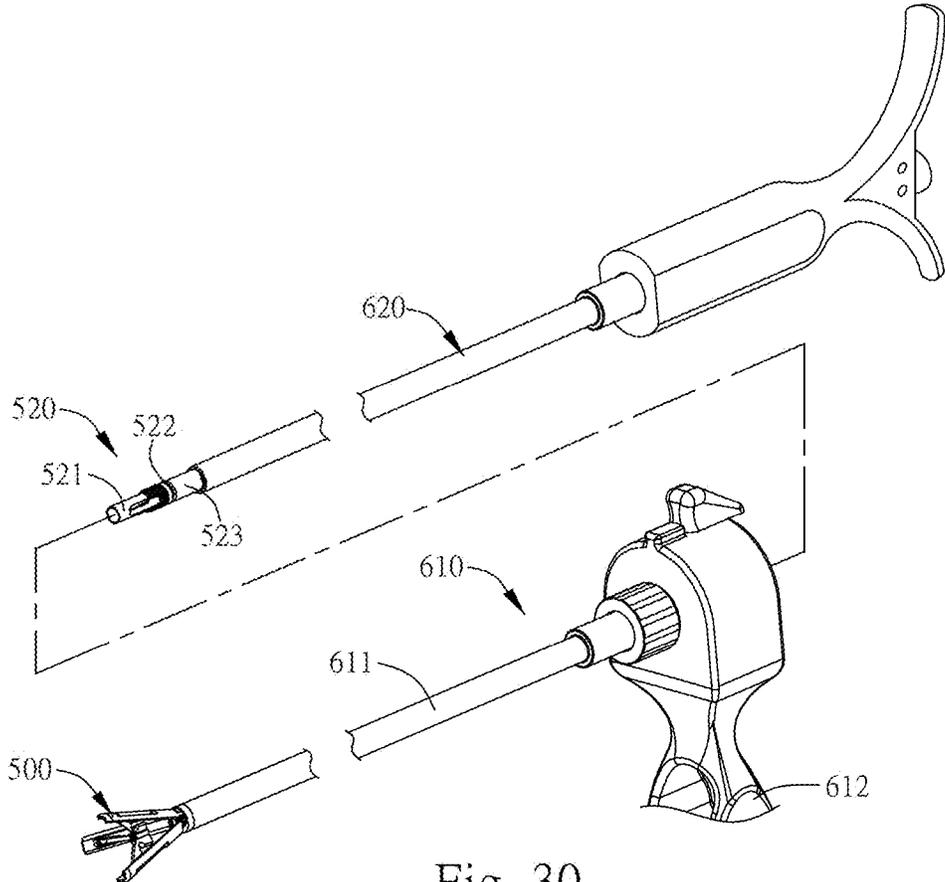


Fig. 30

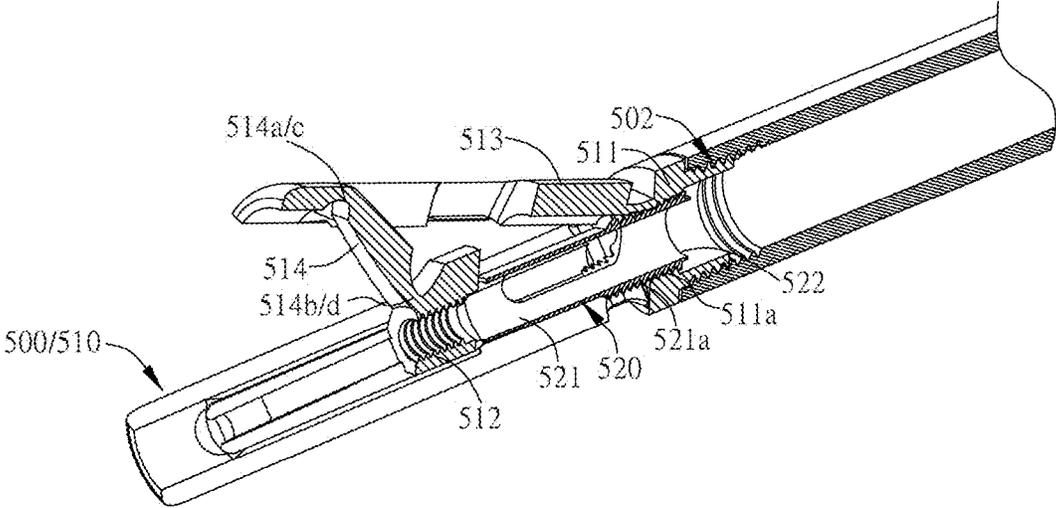


Fig. 31

## SPINAL IMPLANT STRUCTURE AND KIT THEREOF

### CROSS REFERENCE TO RELATED APPLICATIONS

This application is a Continuation-in-Part of co-pending application Ser. No. 15/457,020 filed on Mar. 13, 2017, for which priority is claimed under 35 U.S.C. § 120; and this application claims priority of Application No. 105107739 filed in TAIWAN on Mar. 14, 2016 under 35 U.S.C. § 119, the entire contents of all of which are hereby incorporated by reference.

### BACKGROUND OF THE INVENTION

#### Field of the Invention

The present invention relates to spinal implant structures and, more particularly, to an intervertebral and intravertebral implant and a tool kit thereof.

#### Description of the Prior Art

The spine, also known as the vertebral column, essentially comprises four types of elements, namely the spinal cord, vertebrae, ligaments, and intervertebral discs. Severe osteoporosis, intervertebral disc degeneration, ligament degeneration, joint dislocation, and joint compression may bring mechanical damage to the spine (such as a spinal compression fracture) and thus destabilize the spine. Spinal instability is accompanied by extreme discomfort and pain, thereby predisposing the patient to chronic back pain, spine curvature disorders, and walking disability.

Among the ways to cure spinal instability is vertebroplasty, which entails placing an implant in a collapsed vertebral body. The implant in the collapsed vertebral body expands and thereby restores the collapsed vertebral body to its normal height. The implant is filled with a bone autograft or a bone substitute (bone cement) to enhance the stability of the spine with a view to curing spinal instability.

A conventional spinal implant structure requires an implanting tool in order to be placed in the collapsed vertebral body and then expands. There is a wide variety of commercially available spinal implant structures and implanting tools. However, the prior art is unsatisfactory and thus still has room for improvement.

#### SUMMARY OF THE INVENTION

The present invention provides a spinal implant structure kit, comprising a spinal implant structure and an operating tool for use with the spinal implant structure. The spinal implant structure structurally matches the operating tool so that vertebroplasty can be performed efficiently and easily in terms of the adjustment of the position of the spinal implant structure, expansion of the vertebral body, and perfusion of a bone cement, etc.

According to an embodiment of the present invention, a spinal implant structure is provided. The spinal implant structure comprises a first part, a second part, and at least one expansion arm. The second part is disposed along the lengthwise direction of the first part without overlapping the first part. The first part has a larger diameter than the second part. The at least one expansion arm has one end connecting with the first part and forming an included angle with the first part and the other end being a free end. The at least one

expansion arm has a support arm. The support arm has one end connecting with the expansion arm and the other end connecting with the second part. The support arm comprises a plurality of weakened regions. In response to a change in the distance between the first part and the second part, the support arm bends at the weakened regions and thus drives the expansion arm to move, so as to increase the included angle and expand the spinal implant structure. The first part, second part, expansion arm, and support arm are formed integrally.

In another embodiment of the present invention, a spinal implant kit comprises the spinal implant structure and the operating tool. The operating tool comprises a tool body, a fixing sleeve, a central rod, and an operating handle. The tool body has a connecting portion and a gripping portion. The connecting portion has a tail provided with a jointing structure for connecting with the spinal implant structure. The fixing sleeve fits inside the tool body to fix the distance between a first part and a second part of the spinal implant structure. The central rod fits inside the fixing sleeve to connect with the second part directly or connect with the second part through the fixing sleeve. The operating handle connects with the central rod and rotates to drive the central rod to move in the lengthwise direction of the first part.

To render the above and other aspects of the present invention comprehensible, the present invention is hereunder illustrated by embodiments and accompanying drawings.

#### BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1A is a lateral view of a spinal implant structure according to an embodiment (first embodiment) of the present invention, and shows that the spinal implant structure is folded (i.e., not netted).

FIG. 1B is a cross-sectional view of a spinal implant structure according to an embodiment (first embodiment) of the present invention, and shows that the spinal implant structure is folded (i.e., not netted).

FIG. 2A is a lateral view showing that the spinal implant structure (i.e., not netted) has been expanded.

FIG. 2B is a cross-sectional view showing that the spinal implant structure (i.e., not netted) has been expanded.

FIG. 2C is a front view showing that the spinal implant structure (i.e., not netted) has been expanded.

FIG. 3A is a lateral view showing that the spinal implant structure (i.e., netted) is folded.

FIG. 3B is a cross-sectional view showing that the spinal implant structure (i.e., netted) is folded.

FIG. 4A is a lateral view showing that the spinal implant structure (i.e., netted) has been expanded.

FIG. 4B is a cross-sectional view showing that the spinal implant structure (i.e., netted) has been expanded.

FIG. 5A is a lateral view of the spinal implant structure according to another embodiment (second embodiment) of the present invention showing that the spinal implant structure (i.e., not netted) is folded.

FIG. 5B is a cross-sectional view of the spinal implant structure according to another embodiment (second embodiment) of the present invention showing that the spinal implant structure (i.e., not netted) is folded.

FIG. 6A is a lateral view of the spinal implant structure according to another embodiment (second embodiment) of the present invention showing that the spinal implant structure (i.e., not netted) has been expanded.

FIG. 6B is a cross-section view of the spinal implant structure according to another embodiment (second embodi-

ment) of the present invention showing that the spinal implant structure (i.e., not netted) has been expanded.

FIG. 6C is a front view of the spinal implant structure according to another embodiment (second embodiment) of the present invention showing that the spinal implant structure (i.e., not netted) has been expanded.

FIG. 7A is a lateral view of the spinal implant structure according to another embodiment (second embodiment) of the present invention showing that the spinal implant structure (i.e., netted) is folded.

FIG. 7B is a cross-section view of the spinal implant structure according to another embodiment (second embodiment) of the present invention showing that the spinal implant structure (i.e., netted) is folded.

FIG. 8A is a lateral view of the spinal implant structure according to another embodiment (second embodiment) of the present invention showing that the spinal implant structure (i.e., netted) has been expanded.

FIG. 8B is a cross-sectional view of the spinal implant structure according to another embodiment (second embodiment) of the present invention showing that the spinal implant structure (i.e., netted) has been expanded.

FIG. 9A is a lateral view of the operating tool.

FIG. 9B is a cross-sectional view of the operating tool.

FIG. 10A is a lateral view of the operating tool.

FIG. 10B is a cross-sectional view of the operating tool.

FIG. 10C is a lateral view of the operating tool.

FIG. 11A is a lateral view of the operating tool.

FIG. 11B is a cross-sectional view of the operating tool.

FIG. 12A is a lateral view of the operating tool.

FIG. 12B is a cross-sectional view of the operating tool.

FIG. 13A is a lateral view of the operating tool.

FIG. 13B is a cross-sectional view of the operating tool.

FIG. 14A is a lateral view of the operating tool.

FIG. 14B is a cross-sectional view of the operating tool.

FIG. 15A is a lateral view of the operating tool.

FIG. 16A is a lateral view of the spinal implant structure and the operating tool coupled thereto according to the first embodiment of the present invention.

FIG. 16B is a cross-sectional view of the spinal implant structure and the operating tool coupled thereto according to the first embodiment of the present invention.

FIG. 16C is a partially enlarged cross-sectional view of the spinal implant structure and the operating tool coupled thereto according to the first embodiment of the present invention.

FIG. 17A is a lateral view of the spinal implant structure and the operating tool coupled thereto according to the first embodiment of the present invention.

FIG. 17B is a cross-sectional view of the spinal implant structure and the operating tool coupled thereto according to the first embodiment of the present invention.

FIG. 17C is a partially enlarged cross-sectional view of the spinal implant structure and the operating tool coupled thereto according to the first embodiment of the present invention.

FIG. 18A is a lateral view of the spinal implant structure and the operating tool coupled thereto according to the first embodiment of the present invention.

FIG. 18B is a cross-sectional view of the spinal implant structure and the operating tool coupled thereto according to the first embodiment of the present invention.

FIG. 19A is a lateral view of the spinal implant structure and the operating tool coupled thereto according to the second embodiment of the present invention.

FIG. 19B is a cross-sectional view of the spinal implant structure and the operating tool coupled thereto according to the second embodiment of the present invention.

FIG. 19C is a partially enlarged cross-sectional view of the spinal implant structure and the operating tool coupled thereto according to the second embodiment of the present invention.

FIG. 20A is a lateral view of the spinal implant structure and the operating tool coupled thereto according to the second embodiment of the present invention.

FIG. 20B is a cross-sectional view of the spinal implant structure and the operating tool coupled thereto according to the second embodiment of the present invention.

FIG. 20C is a partially enlarged cross-sectional view of the spinal implant structure and the operating tool coupled thereto according to the second embodiment of the present invention.

FIG. 21A is a lateral view of the spinal implant structure according to yet another embodiment of the present invention.

FIG. 21B is a cross-sectional view of the spinal implant structure according to yet another embodiment of the present invention.

FIG. 22A is a side view of the spinal implant structure in the folded position showing a spinal implant structure according to still another embodiment (third embodiment) of the present invention.

FIG. 22B is a cross-sectional view of the spinal implant structure in the folded position showing a spinal implant structure according to still another embodiment (third embodiment) of the present invention.

FIG. 22C is a view of the spinal implant structure of FIG. 22A at the side of the expansion end showing a spinal implant structure according to still another embodiment (third embodiment) of the present invention.

FIG. 23A is a side view showing the spinal implant structure according to still another embodiment (third embodiment) of the present invention in the expansion position.

FIG. 23B is a cross-sectional view showing the spinal implant structure according to still another embodiment (third embodiment) of the present invention in the expansion position.

FIG. 24 is a side view of the spinal implant structure 500 implanted in the vertebral body shown in FIG. 23A.

FIG. 25 is a front view of the spinal implant structure 500 implanted in the vertebral body shown in FIG. 23A.

FIG. 26A is a diagram showing the results of an efficacy test of the spinal implant structure.

FIG. 26B is a diagram showing the results of an efficacy test of the spinal implant structure.

FIG. 26C is a schematic view of the various locations within the vertebral body listed in Table 1.

FIG. 27 is an explosive view of the operating tool for expanding the spinal implant structure 500.

FIG. 28A is a schematic view of the spinal implant structure 500 and the operating tool coupled thereto.

FIG. 28B is a schematic view of the spinal implant structure 500 and the operating tool coupled thereto.

FIG. 29 is an explosive view of the fixing screw barrel 520 and the fixed sleeve 620 for securing the spinal implant structure 500.

FIG. 30 is a schematic view of applying the fixing screw barrel 520 and the fixing sleeve 620 coupled thereto to the tool body 610.

FIG. 31 is a schematic view of the fixing screw barrel 520 assembled to a body 510 of the spinal implant structure 500.

The aforesaid diagrams, which merely serve exemplary purposes to illustrate the shapes and relative positions of the constituent elements of the present invention, are not drawn to scale.

Due to the limits of drawing software, a mark, for example, indicative of an anchor A or contact, may be shown in the aforesaid diagrams, but the anchor A or contact is optional rather than required.

#### DETAILED DESCRIPTION OF THE EMBODIMENTS

The present invention provides a spinal implant kit which comprises a spinal implant structure and an operating tool. The spinal implant structure is made of a metal or a biocompatible polymer. The metal includes a titanium alloy, whereas the biocompatible polymer includes poly(ether-ether-ketone) (PEEK) and its derivatives. PEEK and cancellous bone are equal in hardness. Furthermore, carbon fiber reinforced PEEK, which is as hard as cortical bone, is applicable to the spinal implant kit of the present invention. However, the present invention is not restrictive of the materials which the spinal implant kit of the present invention is made of, and thus the spinal implant kit of the present invention may also be made of the other biocompatible materials.

##### Spinal Implant Structure

FIG. 1A through FIG. 8C illustrate two different embodiments of a spinal implant structure of the present invention. FIG. 1A through FIG. 4B show a spinal implant structure 100 of the first embodiment of the present invention. FIG. 5A through FIG. 8C show a spinal implant structure 200 of the second embodiment of the present invention.

##### First Embodiment

The spinal implant structure 100, which is not netted, is illustrated by FIG. 1A through FIG. 2C. Referring to FIG. 1A and FIG. 1B, there are shown a lateral view and a cross-sectional view of the spinal implant structure 100 which is folded, respectively. FIG. 2A through FIG. 2C are a lateral view, a cross-sectional view, and a front view of the spinal implant structure 100 which has been expanded, respectively. Referring to FIGS. 1A, 1B, 2A, 2B, the spinal implant structure 100 comprises a body 110 and a fixing screw barrel 120. When the spinal implant structure 100 is folded, the body 110 becomes a hollow-cored cylinder, and the fixing screw barrel 120 also becomes a hollow-cored cylinder. The spinal implant structure 100 has an expansion end 101 (left end) and a fixing end 102 (right end). The expansion end 101 is expanded with the operating tool (referring to FIG. 1A and FIG. 2A), and the degree of expansion can be adjusted as needed.

[Body]

The body 110 of the spinal implant structure 100 comprises a first part 111, a second part 112, an expansion arm 113, and a support arm 114, and the four parts are formed integrally. Both the first part 111 and the second part 112 are hollow-cored cylinders. The first part 111 and the second part 112, which are separated and do not overlap (engage), are arranged along the same horizontal axis (X-axis, FIG. 1B). That is, the first part 111 and the second part 112 are two smaller independent tubes (which may also be called the first tube 111 and the second tube 112) split from the body 110, and the two parts are connected by the expansion arm 113 and the support arm 114. The first part 111 contains the fixing screw barrel 120. The second part 112 contains a

fixing component and a netting (to be described later.) The first part 111 has an inner diameter slightly larger than the second part 112 and a length slightly larger than the length of the second part 112. The degree of the expansion of the spinal implant structure 100 can be changed by adjusting the distance between the first part 111 and the second part 112. In this embodiment, the degree of the expansion of the spinal implant structure 100 increases, as the first part 111 and the second part 112 get closer to thereby reduce the distance therebetween along the horizontal axis (X-axis). Hence, an operating tool (a central rod, to be described later) is required to draw the second part 112 closer to the first part 111 (i.e., rightward) in order for the spinal implant structure 100 to expand.

The bending of the expansion arm 113 enables the spinal implant structure 100 to expand. An end 113a (first end) of the expansion arm 113 connects with the first part 111 and extends outward from the first part 111. The other end 113b (second end) of the expansion arm 113 is a free end which does not connect with any other component. A stress weakening portion (weakened section) is defined at a junction 113c of the expansion arm 113 and the first part 111. The stress weakening portion is, for example, made thin or hollowed out so that the stress weakening portion (weakened section) is weaker than its surroundings. When subjected to an applied force, the expansion arm 113 bends outward from the stress weakening portion to effectuate expansion. The stress weakening portion is a notch which may have a valley, a concave, a V-, or a U-shape. An included angle  $\theta$  (shown in FIG. 2B) smaller than 90 degrees is formed between the expansion arm 113 and the extension line of the first part 111. The included angle  $\theta$  indicates the degree of the expansion of the spinal implant structure 100. The included angle  $\theta$  equals 0 degree when the spinal implant structure 100 is folded (FIG. 1A and FIG. 1B). The included angle  $\theta$  is larger than 0 degree but smaller than 90 degrees when the spinal implant structure 100 has been expanded (FIG. 2A and FIG. 2B). The expansion arm 113 is in the number of one or more. If the expansion arm 113 is in the number of two or more, the expansion arms 113 connected to the first part 111 are equally spaced apart. As shown in FIG. 2C, in this embodiment, the spinal implant structure 100 comprises three expansion arms 113 spaced apart by 120 degrees. In another embodiment of the present invention, the expansion arms are in the number of two (and thus spaced apart by 180 degrees), four (and thus spaced apart by 90 degrees) or more. The more the expansion arms are provided, the more uniform the distribution of forces required to effectuate expansion is, the smaller each expansion arm is, and the stricter the requirement for product precision is.

The expansion arm 113 (expansion arm body) has therein a support arm 114. The support arm 114 is tongue-like in shape and can be considered as split from the expansion arm 113; in other words, the support arm 114 and the expansion arm 113 are formed integrally. Or, the expansion arm 113 and the support arm 114 can both be considered as split from the body 110. When the support arm 114 and the expansion arm 113 are integrally formed and split from the body 110, the manufacturing process of the spinal implant structure 100 can be further simplified. An end 114a (first end) of the support arm 114 is not only connected to the inner side of the expansion arm 113, but also connected to the expansion arm 113 in a manner to be positioned proximate to the first part 111. The other end 114b (second end) of the support arm 114 is connected to the second part 112 in a manner to be positioned proximate to the first part 111. At least one stress weakening portion (weakened section) is defined at the

support arm 114. This embodiment is exemplified by two stress weakening portions located at a junction 114c of the support arm 114 and the expansion arm 113 and a junction 114d of the support arm 114 and the second part 112, respectively. In response to a reduction in the distance between the first part 111 and the second part 112, the support arm 114 bends at the stress weakening portions under a force. As shown in FIG. 2B, at the stress weakening portion 114c, the support arm bends toward the inner side of the spinal implant structure 100, whereas, at the stress weakening portion 114d, the support arm 114 bends toward the outer side of the spinal implant structure 100, thereby driving the expansion arm 113 to bend toward the outer side of the spinal implant structure 100 and thus increasing the included angle  $\theta$ , so as for the spinal implant structure 100 to expand. The stress weakening portions are, for example, made thin or hollowed out so that the stress weakening portions are weaker than their surroundings; hence, when the support arm 114 is subjected to an applied force, the resultant stress is concentrated on the stress weakening portions, thereby causing structural deformation of the support arm 114 (i.e., the bending of the support arm 114). In the expansion process of the spinal implant structure 100, the distance between the first part 111 and the second part 112 decreases until the both parts meet. However, the first part 111 and the second part 112 do not overlap with or engage each other.

The body 110 of the spinal implant structure 100 is preferably formed integrally, for example, by molding, lathing, milling, electrical discharge machining (EDM), 3D printing, or pressing, to form the first part 111, the second part 112, the expansion arm 113, and the support arm 114 by a one-off process.

[Fixing Screw Barrel]

Like the body 110, the fixing screw barrel 120 is a hollow-cored cylinder. The fixing screw barrel 120 fixes the distance between the first part 111 and the second part 112 upon completion of the expansion of the spinal implant structure 100. The fixing screw barrel 120 has a smaller diameter than the first part 111 so as to fit inside the first part 111. The fixing screw barrel 120 has an end positioned proximate to the second part 112, and the end has a protruding portion 121. The diameter of the protruding portion 121 substantially equals the inner diameter of the second part 112. The outer surface of the protruding portion 121 has a first outer thread 121a. The first outer thread 121a matches a first inner thread 112a disposed on the inner surface of the second part 112; hence, the protruding portion 121 can be rotated and inserted into the second part 112 so as to be fixed thereto, allowing the fixing screw barrel 120 to abuttingly connect with the second part 112. A second inner thread 120a is disposed on the inner surface of the fixing screw barrel 120. The second inner thread 120a matches the outer thread (to be described later) of the central rod of the operating tool. After rotating and inserting the central rod into the fixing screw barrel, the user can pull the central rod and thereby drive the fixing screw barrel 120 and the second part 112 to move, allowing the second part 112 to get closer to the first part 111, so as to effectuate the expansion of the spinal implant structure 100.

Referring to FIG. 1B, when the spinal implant structure 100 is folded, the tail (right end) of the fixing screw barrel 120 is contained in the first part 111. Referring to FIG. 2B, when the spinal implant structure 100 has been expanded, the second part 112 moves toward the first part 111, and the tail of the fixing screw barrel 120 protrudes from the first part 111. Another screw nut (not shown, derived from the

operating tool) fits around the protruding part of the tail of the fixing screw barrel 120 to prevent the fixing screw barrel 120 from moving toward the second part 112, thereby fixing the distance between the first part 111 and the second part 112. To fit the fixing screw barrel 120 inside the other screw nut, an outer thread is disposed on a portion of the outer surface (tail) of the fixing screw barrel 120.

The wall of the fixing screw barrel 120 has one or at least two through holes 122 whereby a bone cement enters the vertebral body during the bone cement perfusion step (to be described later).

When the spinal implant structure 100 is in an expansion position (FIG. 2A), it has a larger internal volume than when it is folded (FIG. 1A), and can therefore support and restore a damaged/collapsed vertebral body; also, a large amount of bone cement can be filled in the spinal implant structure 100 to reinforce the support.

[Netting]

FIG. 3A through FIG. 4B show that the spinal implant structure 100 has a netting 130 mounted thereon. FIG. 3A and FIG. 3B show that the spinal implant structure 100 is folded. FIG. 4A and FIG. 4B show that the spinal implant structure 100 has been expanded. The netting 130 restricts the range of flow of the bone cement being perfused into the spinal implant structure 100, so as to prevent the bone cement from spilling from the vertebral body, allow the spinal implant structure 100 to be uniformly expanded, and reinforce the vertebral body.

The netting 130 is hollow-cored and cylindrical in shape. The netting 130 fits around the expansion arm 113 of the spinal implant structure 100 and can unfold as a result of the expansion of the spinal implant structure 100 (FIG. 4B). The openings at the two ends of the netting 130 differ in size. The sidewall of the end with a larger opening has at least one engaging hole 131. The end is engaged with a first part-facing end of the expansion arm 113. The other end of the netting 130 has a fixing hole 132 of a smaller diameter (FIG. 4A). When the spinal implant structure 100 is folded (FIG. 3B), one end of the netting 130 is fixed to the expansion arm 113 through the engaging hole 131, whereas the other end of the netting 130 is bent to be inserted into the spinal implant structure 100, and in consequence a fixing component 140 is fixed to the second part 112 through the fixing hole 132. The fixing component 140 is, for example, a screw whose thread enables it to be rotated and inserted into the second part 112. The outer diameter of the screw's head is slightly larger than the diameter of the fixing hole 132 of the netting 130. Hence, the netting 130 is fixed in place between the screw's head and thread; in other words, the netting 130 is fixed in place at the junction of the fixing component 140 and the second part 112. In this embodiment, the netting 130 is disconnectably engaged between the fixing component 140 and the second part 112; hence, when the spinal implant structure 100 is expanded (FIGS. 4A, 4B), that is, at the time when the second part 112 moves toward the first part 111 under a pulling force, the netting 130 is disconnected from the fixing component 140 under the pulling force, thereby allowing the netting 130 to unfold as a result of the expansion of the spinal implant structure 100. There are plenty of ways to disconnect the netting 130 from the fixing component 140, including making the screw head of the fixing component 140 slightly larger than the fixing hole 132 and defining it with a lead angle, or providing several notches on the fixing hole 132, but the present invention is not limited thereto. Therefore, when the second part 112 moves toward the first

part **111** under a pulling force, the netting **130** can be easily disconnected from the fixing component **140** under a reverse pulling force.

#### Second Embodiment

FIG. 5A through FIG. 6C show that the spinal implant structure **200** is not netted. The spinal implant structure **200** of the second embodiment is identical to the spinal implant structure **100** of the first embodiment in terms of most technical features. For the sake of brevity, the identical technical features are not described herein.

FIG. 5A and FIG. 5B are a lateral view and a cross-sectional view of the spinal implant structure **200** which is folded, respectively. FIG. 6A through FIG. 6C are a lateral view, a cross-sectional view, and a front view of the spinal implant structure **200** which has been expanded, respectively. Referring to FIGS. 5A, 5B, 6A, 6B, the spinal implant structure **200** comprises a body **210** and a fixing screw barrel **220**. When the spinal implant structure **200** is folded, the body **210** is a hollow-cored cylinder, and the fixing screw barrel **220** is also a hollow-cored cylinder. The spinal implant structure **200** has an expansion end **201** (left end) and a fixing end **202** (right end). The expansion end **201** is expanded with the operating tool (shown in FIG. 5A and FIG. 6A), and the degree of expansion can be adjusted as needed.

[Body]

The body **210** of the spinal implant structure **200** comprises a first part **211**, a second part **212**, an expansion arm **213** and a support wall **214**, and the four parts are integrally formed. Both the first part **211** and the second part **212** are hollow-cored cylinders. The first part **211** and the second part **212**, which are separated and do not overlap, are arranged along the same horizontal axis (X-axis). That is, the first part **211** and the second part **212** can be considered as two smaller independent tubes split from the body **210**, and the two parts are connected by the expansion arm **213** and the support arm **214**. The first part **211** contains the fixing screw barrel **220**. The second part **212** contains a netting **230** and a fixing component **240** (FIG. 6A through FIG. 8B). The first part **211** has an internal diameter slightly larger than that of the second part **212**. When the spinal implant structure **200** is folded, the distance between the first part **211** and the second part **212** is very short or the two parts even meet each other. The degree of the expansion of the spinal implant structure **200** can be changed by adjusting the distance between the first part **211** and the second part **212**. The second embodiment differs from the first embodiment in that when the first part **211** and the second part **212** move away from each other, that is, the distance between the first part **211** and the second part **212** along the horizontal axis (X-axis) increases, the degree of expansion increases. In view of this, an operating tool (a central rod, to be described later) is required to move the second part **212** toward the expansion end **201** (i.e., leftward), so as to expand the spinal implant structure **200**.

The spinal implant structure **200** is expanded because of the bending of the expansion arm **213**. The expansion arm **213** has an end **213a** (first end) which connects with the first part **211** and extends outward from the first part **211**. The other end **213b** (second end) of the expansion arm **213** is a free end which does not connect with any other component. A stress weakening portion (weakened section) is defined at a junction **213c** of the expansion arm **213** and the first part **211**. The stress weakening portion is, for example, made thin or hollowed out so that the stress weakening portion (weak-

ened section) is weaker than its surroundings. When subjected to an applied force, the expansion arm **213** bends outward from the stress weakening portion to effectuate expansion. An included angle  $\theta$  (FIG. 6B) smaller than 90 degrees is formed between the expansion arm **213** and the extension line of the first part **211**. The included angle  $\theta$  indicates the degree of the expansion of the spinal implant structure **200**. The included angle  $\theta$  equals 0 degree when the spinal implant structure **200** is folded (FIG. 5A and FIG. 5B). The included angle  $\theta$  is larger than 0 degree but smaller than 90 degrees when the spinal implant structure **200** has been expanded (FIG. 6A and FIG. 6B). The expansion arm **213** is in the number of one or more. If the expansion arm **213** is in the number of two or more, the expansion arms **213** connected to the first part **211** are equally spaced apart. As shown in FIG. 6C, the spinal implant structure **200** comprises three expansion arms **213** spaced apart by 120 degrees. In another embodiment of the present invention, the expansion arms are in the number of two (and thus spaced apart by 180 degrees), four (and thus spaced apart by 90 degrees) or more. The more the expansion arms are provided, the more uniform the distribution of forces required to effectuate expansion is, the smaller each expansion arm is, and the stricter the requirement for product precision is.

The expansion arm **213** has therein a support arm **214**. The support arm **214** is tongue-like in shape and can be considered as formed by being split from the expansion arm **213**; in other words, the support arm **214** and the expansion arm **213** are formed integrally. On the other hand, the expansion arm **213** and the support arm **214** can both be considered as being split from the body **210**. An end **214a** (first end) of the support arm **214** is not only connected to the inner side of the expansion arm **213**, but also connected to the expansion arm **213** in a manner to be positioned proximate to the free end **213b**. The other end **214b** (second end) of the support arm **214** is connected to the second part **212** in a manner to be positioned distal to the first part **211**. At least one stress weakening portion (weakened region) is defined at the support arm **214**. This embodiment is exemplified by two stress weakening portions located at a junction **214c** of the support arm **214** and the expansion arm **213** and a junction **214d** of the support arm **214** and the second part **212**, respectively. In response to an increase in the distance between the first part **211** and the second part **212**, the support arm **214** bends at the stress weakening portions under a force. As shown in FIG. 6B, at the stress weakening portion **214c**, the support arm **214** bends toward the inner side of the spinal implant structure **200**, whereas, at the stress weakening portion **214d**, the support arm **214** bends toward the outer side of the spinal implant structure **200**, thereby driving the expansion arm **213** to bend toward the outer side of the spinal implant structure **200** and thus increasing the included angle  $\theta$ , so as for the spinal implant structure **200** to expand. The stress weakening portions are, for example, made thin or hollowed out so that the stress weakening portions are weaker than their surroundings; hence, when the support arm **214** is subjected to an applied force, the resultant stress is concentrated on the stress weakening portions, thereby causing structural deformation of the support arm **214** (i.e., the bending of the support arm **214**).

[Derivative Design of the Body]

Referring to FIG. 21A and FIG. 21B, which illustrate a spinal implant structure **400** according to yet another embodiment of this invention. The difference between the spinal implant structure **400** and the above-described spinal implant structure **200** lies in the design of a fixing end **402**.

As shown in FIG. 21A, an engagement positioning block 403 (the same design as in the spinal implant structure 200) is provided at the fixing end 402 (the left end) of the spinal implant structure 400, and is used to engage an operating tool described below. A corresponding engaging slot is provided at an engaging end of the operating tool for engaging the spinal implant structure 400. An extension rib 404 is also provided on the spinal implant structure 400 and extends from the engagement positioning block 403 toward the inner side of the spinal implant structure 400 (i.e., toward the expansion arm 413). The extension rib 404 is used for enhancing the strength of the first part 411 of the spinal implant structure 400, so that structural distortion or fracture can be avoided during the implanting process. Besides, as shown in FIG. 21B, the engagement positioning block 403 can extend slightly more toward the outer (left) side of the spinal implant structure 400 and have an extra outer protruding block 403A extending out from the fixing end 402 of the spinal implant structure 400. When the spinal implant structure 400 comprises the outer protruding block 403A, it can more steadily connect with or engage an operating tool (as will be described later) having a corresponding slot or recess structure, and the occurrence of sliding or displacement in the implanting process can be reduced. In yet another embodiment of this invention, a recess 405 can be arranged at the inner side of a body 410 of the spinal implant structure 400. The recess 405 connects to the outside of the body 410, and has an opening in a horizontal direction (X-axis) of the first part 411. The recess 405 can be a long concaved slot or groove, and as the recess 405 has one opening end and another closed end, an auxiliary tool (such as a long and thin rod or needle) can be used to reach into the recess 405 from the outside of the body 410 to further apply a force by pressing against the recess 405. As such, when withdrawing the operating tool, the force applying thereto can be increased without causing displacement of the spinal implant structure 400, thereby solving the problem of distortion during the implanting process that hampers withdrawal of the operating tool.

[Fixing Screw Barrel]

Like the body 210, the fixing screw barrel 220 is a hollow-cored cylinder. The fixing screw barrel 220 fixes the distance between the first part 211 and the second part 212 upon completion of the expansion of the spinal implant structure 200. The fixing screw barrel 220 has a smaller diameter than the first part 211 so as to fit inside the first part 211. A third outer thread is disposed on a portion of the outer surface of the fixing screw barrel 220. The third outer thread matches a third inner thread disposed on the inner surface of the first part 211. Hence, the fixing screw barrel 220 can be rotated and inserted into the first part 211, so as to be adjustably moved forward and backward by the threads and fixed in place. Since the position of the fixing screw barrel 220 is adjustable, the front end of the fixing screw barrel 220 can abuttingly connect with the second part 212 so that the second part 212 is fixed in place, thereby fixing the distance between the first part 211 and the second part 212. Since the fixing screw barrel 220 is adjustably moved forward and backward by the threads, it generates a torque. As a result, the spinal implant structure 200 in operation does not require the fixing screw barrel 220 to move the second part 212; instead, a central rod (to be described later) of the operating tool moves the second part 212 horizontally away from the first part 211 and thus effectuates the expansion of the spinal implant structure 200, and then the fixing screw barrel 220 is moved forward to abuttingly connect with the second part 212, thereby fixing the second part 212 in place.

Referring to FIG. 5B, when the spinal implant structure 200 is folded, the tail of the fixing screw barrel 220 protrudes from the first part 211 slightly. Referring to FIG. 6B, when the spinal implant structure 200 has been expanded, the second part 212 separates from the first part 211 to allow the tail of the fixing screw barrel 220 to enter the first part 211 completely and allow the front end of the fixing screw barrel 220 to abuttingly connect with the second part 211, thereby fixing the distance between the first part 211 and the second part 212.

The wall of the fixing screw barrel 220 has one or at least two through holes 222 whereby the bone cement enters the vertebral body during the bone cement perfusion step (to be described later).

[Netting]

FIG. 7A through FIG. 8B show that the spinal implant structure 200 has a netting 230 mounted thereon. FIG. 7A and FIG. 7B show that the spinal implant structure 200 is folded. FIG. 8A and FIG. 8B show that the spinal implant structure 200 has been expanded. The netting 230 restricts the range of flow of the bone cement being perfused into the spinal implant structure 200, so as to prevent the bone cement from spilling from the vertebral body, allow the spinal implant structure 200 to be uniformly expanded, and reinforce the vertebral body.

The netting 230 is hollow-cored and cylindrical in shape. The netting 230 fits around the expansion arm 213 of the spinal implant structure 200 and can unfold as a result of the expansion of the spinal implant structure 200 (FIG. 8B). The openings at the two ends of the netting 230 differ in size. The sidewall of the end with a larger opening has at least one engaging hole 231. The end is engaged with a first part-facing end of the expansion arm 213. The other end of the netting 230 has a fixing hole 232 of a smaller diameter (FIG. 8A). When the spinal implant structure 200 is folded (FIG. 7B), one end of the netting 230 is fixed to the expansion arm 213 through the engaging hole 231, whereas the other end of the netting 230 is bent to be inserted into the spinal implant structure 200, and in consequence the fixing component 240 is fixed to the second part 212 through the fixing hole 232. The fixing component 240 is, for example, a screw whose thread enables it to be rotated and inserted into the second part 212. The outer diameter of the screw's head is slightly larger than the diameter of the fixing hole 232 of the netting 230. Hence, the netting 230 is fixed in place between the screw's head and thread; in other words, the netting 230 is fixed in place at the junction of the fixing component 240 and the second part 212. The second embodiment differs from the first embodiment in that the netting 230 of the spinal implant structure 200 is steadily engaged between the fixing component 240 and the second part 212 without getting disconnected, and thus when the spinal implant structure 200 is expanded (FIGS. 8A, 8B), that is, at the time when the second part 212 moves toward the expansion end 101 under a pushing force and thus moves away from the first part 211, the netting 230 unfolds as a result of the expansion of the spinal implant structure 200.

Operating Tool

The spinal implant structure of the present invention operates in conjunction with an operating tool in order to perform precise operations, such as implantation, expansion, and bone cement perfusion. Embodiments of the operating tool of the present invention are illustrated by FIG. 9A through FIG. 20C. FIG. 9A through FIG. 15A are schematic views of the operating tool. FIG. 16A through FIG. 18B are schematic views of the operating tool and the spinal implant structure coupled thereto according to the first embodiment.

## 13

FIG. 19A through FIG. 20C are schematic views of the operating tool and the spinal implant structure coupled thereto according to the second embodiment. FIG. 9A through FIG. 15A show that, although the operating tool connects with the spinal implant structure 100, the operating tool is also applicable to the spinal implant structure 200 in part or in full. Persons skilled in the art understand that although the operating tool of the present invention varies slightly in structure and shape, depending on whether it is applied to the spinal implant structure 100 or the spinal implant structure 200, the variations in structure and shape of the operating tool are designed in accordance with operational concepts and relationships disclosed according to the present invention and thus fall within the scope of the present invention.

Referring to FIG. 9A through 15A, the operating tool of the present invention comprises a tool body 310, a fixing (screw barrel/screw nut) sleeve 320, a central rod 330, an operating handle 340, a converter 350, a bone cement perfusing sleeve 360, and a bone cement ejector 370. The tool body 310, fixing (screw barrel/screw nut) sleeve 320, the central rod 330, operating handle 340, and converter 350 together constitute the operating tool whereby the spinal implant structure is expanded (FIG. 16A through FIG. 17C show how the spinal implant structure 100 is folded/expanded; FIG. 19A through FIG. 20C show how the spinal implant structure 200 is folded/expanded.) The tool body 310, fixing (screw barrel/screw nut) sleeve 320, bone cement perfusing sleeve 360, and bone cement ejector 370 together constitute the tool for perfusing the bone cement upon completion of the expansion of the spinal implant structure 100 (FIGS. 18A and 18B).

[Tool Body]

Referring to FIGS. 9A and 9B, the tool body 310 serves as a carrier/connector for the operating tool and connects with the spinal implant structure 100. The tool body 310 comprises a connecting portion 311 and a gripping portion 312. The connecting portion 311 is a hollow-cored pipe and has a tail 311a. The tail 311a has a jointing structure which can be connected to the spinal implant structure 100 and fixed thereto integrally. This embodiment is exemplified by thread securing. The ways to couple the tool body 310 and the spinal implant structure 100 together include but are not limited to engagement and thread securing; hence, whatever jointing techniques will be applicable to the present invention, provided that the jointing techniques enable the tool body 310 and the spinal implant structure 100 to be firmly connected and easily disconnected. The gripping portion 312 is, for example, a handle to be gripped by a user or placed on another table/support to fix the kit in place.

[Fixing (Screw Barrel/Screw Nut) Sleeve]

Referring to FIG. 10A through FIG. 10C, wherein FIG. 10A and FIG. 10B show the fixing (screw barrel/screw nut) sleeve 320 which operates in conjunction with the spinal implant structure 100, and FIG. 10C shows the fixing (screw barrel/screw nut) sleeve 320 which operates in conjunction with the spinal implant structure 200. The fixing (screw barrel/screw nut) sleeve 320 is a hollow-cored pipe for fitting inside the tool body 310. For example, the fixing (screw barrel/screw nut) sleeve 320 comprises a fixing screw barrel/screw nut 321 and a sleeve 322. The fixing screw barrel/screw nut 321 is specially designed (for example, its wall has an opening 323) to separate from the sleeve 322 when rotated and stay in the spinal implant structure 100, and then the sleeve 322 can be taken out of the spinal implant structure 100. Referring to FIG. 10A, the fixing screw nut 321 is disconnected from the fixing (screw barrel/

## 14

screw nut) sleeve 320 to become a screw nut (i.e., a screw nut for fitting around a protruding part of the fixing screw barrel 120, as described before and shown in FIG. 1B) of the spinal implant structure 100 in the first embodiment. Referring to FIG. 10C, the fixing screw barrel 321 is disconnected from the fixing (screw barrel/screw nut) sleeve 320 to become the fixing screw barrel 220 (FIG. 5B) of the spinal implant structure 200 in the second embodiment. The fixing (screw nut/screw barrel) 321 disconnected from the fixing (screw barrel/screw nut) sleeve 320 is adapted to fix the distance between the first part 111, 211 and the second part 112, 212 in the spinal implant structure 100, 200.

[Central Rod]

Referring to FIGS. 11A and 11B, wherein FIG. 11A shows a central rod for use with the spinal implant structure 100, and FIG. 11B shows a central rod adapted for use with the spinal implant structure 100 and equipped with a connecting end 330a (left end). The central rod 330 is a slender rod for pulling and/or pushing the second part so as to effectuate the expansion of the spinal implant structure. The front end of the central rod 330 has a thread which matches the inner thread of the fixing screw barrel 120 of the spinal implant structure 100; hence, the front end of the central rod 330 can be insertedly fastened to the fixing screw barrel 120 and thus connected to the second part 112 of the spinal implant structure 100 through the fixing screw barrel 120 (as shown in FIG. 1B). Alternatively, the thread matches the inner thread of the second part 212 of the spinal implant structure 200 and thus is directly, insertedly fastened to the second part 212 of the spinal implant structure 200 (as shown in FIG. 5B).

[Operating Handle and Converter]

Referring to FIG. 12A through 13B, the operating handle 340 and the converter 350 drive the central rod 330 to move forward/backward so that the spinal implant structures 100, 200 are expanded or folded. The operating handle 340 operates by the principle of the lever whereby the user can exert a small force on the converter 350 by means of a long effort arm of the lever. The converter 350 converts the rotational torque exerted by the user into a horizontal, linear pushing/pulling force, so as to not only render the pushing/pulling force uniform but also reduce unnecessary vibration.

[Bone Cement Perfusing Sleeve and Bone Cement Ejector]

Referring to FIG. 14A through 15A, the bone cement perfusing sleeve 360 and the bone cement ejector 370 are adapted to perfuse a bone cement, and their operation is illustrated by FIGS. (19)18B, which show that their operation entails inserting the bone cement perfusing sleeve 360 directly into the fixing screw barrel (screw nut) 320, the tool body 310, and the spinal implant structure 100, filling the bone cement perfusing sleeve 360 with the bone cement, and finally pushing the bone cement into the spinal implant structure 100 with the bone cement ejector 370. Hence, the outer diameter of the bone cement ejector 370 substantially equals the inner diameter of the bone cement perfusing sleeve 360 in order for the bone cement to be pushed into the spinal implant structure 100.

[Operation of Operating Tool and Spinal Implant Structure]

FIG. 16A through FIG. 17C are schematic views of the operating tool and the spinal implant structure 100 coupled thereto. FIG. 16A through FIG. 16C are schematic views of the operating tool and the spinal implant structure 100 coupled thereto and folded. FIG. 17A through FIG. 17C are schematic views of the operating tool and the spinal implant structure 100 coupled thereto and expanded. FIG. 16C and FIG. 17C are partial enlarged views of the junction of the operating tool and the spinal implant structure.

Referring to FIG. 16C, the tail 311a of the connecting portion 311 of the tool body 310 is operated in a manner to be jointed to the first part 111 of the spinal implant structure 100. FIG. 16C is exemplified by thread jointing. The central rod 330 (FIG. 11A) is rotated and inserted into the fixing screw barrel 120. Then, the operating handle 340 and converter 350 (FIG. 17A, 17B) are rotated, so as for the central rod 330 to be pulled backward, thereby effectuating the expansion of the spinal implant structure 100. Referring to FIG. 17C, upon completion of the expansion of the spinal implant structure 100, the fixing screw barrel 120 is at a location conducive to its operating the connecting portion 311 of the tool body 310; at this point in time, the user can move the fixing screw nut sleeve 320 (FIGS. 10A, 10B) of the operating tool leftward so that it fits around the fixing screw barrel 120 and thus gets fixed thereto. After the fixing screw nut sleeve 320 has fitted around the fixing screw barrel 120, the user rotates it again in the same direction and applies a torque thereto, so as to separate the fixing screw nut 321 and the sleeve 322 and finish the fixation process.

FIG. 19A through FIG. 20C are schematic views of the operating tool and the spinal implant structure 200 coupled thereto. FIG. 19A through FIG. 19C are schematic views of the operating tool and the spinal implant structure 200 coupled thereto and folded. FIG. 20A through FIG. 20C are schematic views of the operating tool and the spinal implant structure 200 coupled thereto and expanded. FIG. 19C and FIG. 20C are partial enlarged views of the junction of the operating tool and the spinal implant structure.

Referring to FIG. 19C, the tail 311a of the connecting portion 311 of the tool body 310 is jointed to the first part 211 of the spinal implant structure 200 by engagement for exemplary sake. The central rod 330 (FIG. 11B) is rotated and inserted into the second part 212. Then, the operating handle 340 and converter 350 (FIGS. 19A, 19B) are rotated so as to push the central rod 330 forward, thereby effectuating the expansion of the spinal implant structure 200. After the second part 212 has been pushed forward and fixed in place to effectuate the expansion of the spinal implant structure 200, as shown in FIG. 20C, the fixing screw barrel sleeve 320 (FIG. 10C) rotates and moves forward so that the front end of the fixing screw barrel sleeve 320 abuttingly connects with the second part 212 to fix it in place. At this point in time, the user rotates the fixing screw barrel sleeve 320 again in the same direction and applies a torque thereto, so as to separate the fixing screw barrel 321 and the sleeve 322, keep the fixing screw barrel 321, finish the fixation process, and remove the sleeve 322.

### Third Embodiment

The spin implant structure 500 is described below with reference to FIG. 22A through FIG. 23B, and the connection relationship and operation of the operation tool with the spinal implant structure 500 are described with reference to FIG. 24 through FIG. 28B. Most of the structure of the spinal implant structure 500 is similar to that of the first and second embodiment of the spinal implant structure 100, 200, and the similarities will not be described again.

FIG. 22A and FIG. 22B are a side view and a cross-sectional view showing the spinal implant structure 500 in the folded position, and FIG. 22C is a view of the spinal implant structure 500 of the FIG. 22A at the side of the expansion end 501. FIG. 23A and FIG. 23B are a side view and a cross-sectional view showing the spinal implant structure 500 in the expansion position. FIG. 24 and FIG. 25 are a side view and a front view of the spinal implant

structure 500 implanted in the vertebral body shown in FIG. 23A. As shown in FIG. 22A, FIG. 22B, FIG. 23A, and FIG. 23B, the body 510 of the spinal implant structure 500 of the present embodiment can be directly connected to the operating tool (central rod 630, see FIG. 28A and FIG. 28B). Similarly, the body 510 is a hollow-cored cylinder when the spinal implant structure 500 is in the folded position and can be expanded using an operating tool.  
[Body]

The body 510 of the spinal implant structure 500 comprises a first part 511, a second part 512, an expansion arm 513, and a support arm 514, and the four parts are formed integrally. Both the first part 511 and the second part 512 are separated and do not overlap each other, and both are hollow-cored cylinders. The first part 511 and the second part 512 are two smaller independent tubes split from the body 510, and the two parts are connected by the expansion arm 513 and the supporting arm 514. The degree of the expansion of the spinal implant structure 500 can be changed by adjusting the distance between the first part 511 and the second part 512. This embodiment is the same as the second embodiment described above, when the first part 511 and the second part 512 move away from each other, that is, the distance between the first part 511 and the second part 512 along the horizontal axis (X-axis) increases, the degree of expansion increases. Similarly, an operating tool (a central rod, to be described later) is required to move the second part 512 toward the expansion end 501 (i.e., leftward), so as to expand the spinal implant structure 500.

The spinal implant structure 500 is expanded because of the bending of the expansion arm 513. An end 513a (first end) of the expansion arm 513 connects with the first part 511 and extends outward from the first part 511. The other end 513b (second end) of the expansion arm 513 is a free end which does not connect with any other component. A stress weakening portion 513c is defined at a junction of the expansion arm 513 and the first part 511. When applied with a force, the expansion arm 513 bends outward from the stress weakening portion 513c to effectuate expansion. The number of expansion arms 513 may be more than one. In this embodiment, the number of expansion arms is three, and one expansion arm 513 is larger than the other two. It can be seen from the expansion end of the spin implant structure 500 that the larger size expansion arm 513 shows a larger arc (r1), while the other two expansion arms have the smaller and equal arc (r2). Preferably, a ratio of curvatures of the three expansion arms 513 (r1:r2:r2) is between 1.5:1:1 and 1.4:1:1, as shown in FIG. 22C. For clarity of illustration, the expansion arm 513 having a curvature of r1 is referred to as an upper expansion arm 5131, and the two expansion arms 513 having a curvature of r2 is referred to as lower expansion arms 5132. In this embodiment, there is no gap between the expansion arms 513. The curvature (r1) of the upper expansion arm expansion arm 5131 is 150 degrees, and the curvature (r2) of the two lower expansion arms 5132 is 105 degrees. At this time, the ratio of the curvatures of the three expansion arms 513 is 1.42:1:1. In other embodiments of the present invention, the curvature (r1) of the upper expansion arm expansion arm 5131 may be 125 degrees, 130 degrees, 135 degrees, 140 degrees or 145 degrees, and the curvature (r2) of the two lower expansion arms 5132 may be 117.5 degrees, 115 degrees, 112.5 degrees, 110 degrees or 107.5 degrees correspondingly. In brief, the ratio of the curvatures of the three expansion arms 513 may be higher than 1:1:1 but less than or equal to 1.47:1:1. For example, the ratio of

the curvatures of the three expansion arms 513 may be 1.603:1:1, 1.13:1:1, 1.2:1:1, 1.27:1:1 or 1.35:1:1 (round off to the third decimal place).

The above-mentioned unequal expansion arm design is meant to solve the problems often found in vertebroplasty. Because the spinal implant structure 500 is designed to be implanted into the vertebral body with the upper expansion arm 5131 being in contact with one side of the implantation passage (the side close to the patient's skull), and the two lower expansion arms 5132 being both in contact with the other side of the implantation passage (the side close to the patient's foot), and since the vertebral body is usually collapsed or deformed from the upper side (in the direction of the patient's head) down (to the direction of the patient's foot), when the mainly stressed expansion arm 513 (usually the expansion arm that expands toward the patient's skull when the spinal implant structure 500 is expanded, which is the upper expansion arm 5131 shown in FIG. 24 and FIG. 25) of the spinal implant structure 500 is expanded, in the initial state, it is more likely to be bent or deformed due to the higher resistance between the tissues or the expansion force failing to overcome the resistance between the tissues, so the vertebral body may fail in restoration to the desired effect due to the above mentioned problems.

In terms of bending and deformation, once the mainly stressed expansion arm 513 is bent and deformed, then the expansion of the spinal implant structure 500 is undermined and not as good as expected. Since this problem often occurs in the upper expansion arm 5131 of the spinal implant structure 500, the size of the upper expansion arm 5131 is designed to be larger for the operator to align it upward (ie, in the direction of the patient's skull) during the surgery and to implant the spinal implant structure 500 in this direction, as shown in FIG. 24 and FIG. 25. After the spinal implant structure 500 is implanted into the vertebral body 9, the three expansion arms 513 (one upper expansion arm 5131 and two lower expansion arms 5132) are in contact with the col-

placed in the position where the vertebral body is about to be expanded. However, the aperture of the passage is intended to be slightly larger than the outer diameter of the spinal implant structure 500. The diameter of the former is about 8 to 9 centimeters, and the outer diameter of the latter is about 5 to 5.8 centimeters, which is differed by 2.2 to 4 centimeters. Therefore, when the spinal implant structure 500 begins to be expanded, the three expansion arms 513 can first expand to a certain angle before they actually abut the vertebral body 9 (abutting the inner wall of the passage of the vertebral body 9). Moreover, since the size (curvature) of the upper expansion arm 5131 is larger than that of the two lower expansion arms, experiments have confirmed that it can further reduce deformation or displacement during expansion of the spinal implant structure 50.

Referring to Table 1, FIG. 26A, FIG. 26B, and FIG. 26C, FIG. 26A and FIG. 26B are diagrams showing the results of the efficacy test of the spinal implant structure, and FIG. 26C shows the positions of the vertebral body listed in Table 1.

The spinal implant structures with the upper expansion arms 5131 having different curvatures (r1) of 120 degrees and 150 degrees were implanted to the vertebral body 9 of the porcine bone respectively to perform a porcine bone implant efficacy test. Then, the height of each position (A to F) of the vertebral body 9 before and after implantation and expansion was measured, the result as shown in table 1. As shown in the results of the experiment, regarding to the height change of each position (A to F) of the vertebra body 9 before and after implantation and expansion, the 150 degree group (as shown in FIG. 26A) performed significantly better than 120 degrees group (as shown in FIG. 26B) did. Since the height change of the vertebral body before and after expansion can represent the performance of restoration, it can be seen that the upper expansion arm 5131 has a larger curvature (r1) compared with that of the equal-sized expansion arms, it tends to have a better vertebral body restoration capability.

TABLE 1

Positions in the vertebral body	r1 = 120 degrees			r1 = 150 degrees		
	Height before implantation (mm)	Height after implantation (mm)	Height change (mm)	Height before implantation (mm)	Height after implantation (mm)	Height change (mm)
A	29.00	29.45	0.45	29.08	32.10	3.02
B	30.87	32.02	1.15	30.54	32.45	1.91
C	30.67	30.86	0.19	29.92	32.09	2.17
D	31.36	31.46	0.10	31.53	31.71	0.18
E	33.08	33.03	-0.05	32.59	32.60	0.01
F	32.87	32.83	-0.04	31.22	32.73	1.51

lapsed vertebral body 9. During the operating tool is operated to expand the spinal implant structure 500, the three expansion arms 513 can be used as supporting points to restore the collapsed vertebral body 9. In addition, when using the implantation method as described, since the upper expansion arm 5131 has a larger structural size (the curvature r1 can be up to 140 degrees as viewed from the expansion end 501), it has stronger structural strength and supporting force so as to reduce the aforementioned deformation due to insufficient bearing capacity.

In other embodiments, before the spinal implant structure 500 is implanted into the vertebral body 9, the surgeon creates a passage with an awl and then use a drill and a reamer to expand the aperture of the passage, allowing the spinal implant structure 500 (in the folded position) to be

The inner side of the expansion arm 513 has a supporting arm 514. The supporting arm 514 has a tongue-like shape and is cut out from the expansion arm 513. One end (the first end 514a) of the supporting arm 514 remains connected to the inner side of the expansion arm 513, and is connected to the position of the expansion arm 513 closer to the second end 513b (free end); the other end (second end 514b) of the supporting arm 514 is connected to the second part 512, and separated from the expansion arm 513, that is, the second end 514b of the supporting arm 514 is not connected to the expansion arm 513. In this embodiment, the junction of the supporting arm 514 and the expansion arm 513 is designed with a stress weakening portion 514c, and the junction of the supporting arm 514 and the second part 512 is also designed with a stress weakening portion 514d. When the distance

between the first part **511** and the second part **512** increases, the supporting arm **514** is then stressed and bent at the stress weakening portions **514c**, **514d**. In detail, the stress weakening portion **514d** is bent toward the outer side of the spinal implant structure **500**, and the stress weakening portion **514c** is bent toward the inner side of the spinal implant structure **500**, consequently, the expansion arm **513** is bent outward, so that the angle  $\theta$  is increased, and the spinal implant structure **500** is expanded. As mentioned above, the stress weakening portion is, for example, made thin, or hollowed out, etc., so that the portion (the stress weakening portion) is weaker than the other parts, and the stress is concentrated at this portion when the force is applied, and the structure is deformed (that is, the supporting arm **514** is bent).

In this embodiment, the stress weakening portions **514c** and **514d** are formed by thinning the supporting arm **514** through different directions respectively. The stress weakening portion **514c** is a hemispherical concave structure, the stress weakening portion **514d** is a curved concave structure, and the two stress weakening portions **514c** and **514d** have opposite opening direction, so that the supporting arm **514** can form a "Z" shape when the stress is applied. Further, in this embodiment, in order to ensure that the expansion arm **513** is bent toward the outside of the spinal implant structure **500**, rather than bent inward, the thickness of the expansion arm **513** is gradually thinned from the first end **513a** to the opposite end, so the cross section of the expansion arm **513** is a wedge shape. Since the supporting arm **514** is split from the expansion arm **513**, the thickness of the supporting arm **514** is also gradually thinned from the first end **514a** to the opposite second end **514b**, and the cross section of the supporting arm **514** is also a wedge shape. However, in order to make the stress weakening portion **514c** and the stress weakening portion **514d** have the same mechanical strength and bear the same stresses during deformation, the wall thickness of the weakening portion **514c** and the stress weakening portion **514d** after thinning are designed to be identical. In other words, the weakening portion **514d** has to be removed more wall thickness than the weakening portion **514c**. Further, since the concave opening of the stress weakening portion **514d** faces toward the outside of spinal implant structure **500** (in contrast to the concave opening of the stress weakening portion **514c** faces toward the inner side of spinal implant structure **500**), and the position of the stress weakening portion **514d** is more close to the second part **512** (which the external force applied to), so that during deformation the stress weakening portion **514d** bends greater than the stress weakening portion **514c**. In other words, after bending the angle of the interior angle of the stress weakening portion **514d** is smaller than the interior angle of the stress weakening portion **514c**. The interior angle referred to herein refers to an included angle formed by the parts of the supporting arm **514** on the two sides of the stress weakening portion **514d**, and the included angle should be smaller than 180 degrees.

[Operation of Operating Tool and Spinal Implant Structure]

An embodiment in which the operating tool expands the spinal implant structure **500** is described below with reference to FIG. 27 through FIG. 28B. FIG. 27 is an explosive perspective view of an operation tool for expanding the spinal implant structure **500**, and FIG. 28A and FIG. 28B are schematic diagrams showing the spinal implant structure **500** and the operation tool coupled thereto.

Referring to FIG. 27, the operating tool of the present invention comprises a tool body **610**, a center rod **630** and an operating handle **640** for expanding the spinal implant structure **500** by the aforementioned members. First, the tool

body **610** of the embodiment further includes a connecting portion **611** and a gripping portion **612**. The connecting portion **611** is a hollow long tube, and the tail end of the connecting portion **611** has a joint structure **611a** connected to the spinal implant structure **500**. Referring to FIG. 27, in the present embodiment, the joint structure **611a** is an inner thread, and the fixing end **502** of the spinal implant structure **500** has an outer thread. The joint structure **611a** of the tool body **610** is coupled to the fixing end **502** of the spinal implant structure **500** by means of thread locking. That is, the joint structure **611a** of the connecting portion **611** is engaged with the first part **511** of the spinal implant structure **500**.

Next, the central rod **630** is inserted into the tool body **610**, and the central rod **630** is coupled with the second part **512** to push the second part **512** to drive the spinal implant structure to expand. Referring to FIG. 28A, the central rod **630** of the present embodiment is directly connected to the second part **512** of the spinal implant structure **500**. Specifically, the front end of the central rod **630** has an outer thread **631**. The outer thread **631** corresponds to the inner thread **512a** of the second part **512** of the spinal implant structure **500**, so that the front end of the central rod **630** is directly screwed into the second part **512** by rotating the central rod **630** counterclockwise.

Next, the central rod **630** is pushed forward by rotating the operating handle **640**, and the spinal implant structure **500** is expanded, as shown in FIG. 28B. In detail, the converter **650** is disposed in the operating handle **640**, and the converter **650** converts the rotational torque operation performed by a surgeon into a horizontal linear push/pull action. The operating handle **640** is coupled to the central rod **630** through the converter **650**. When the operating handle **640** is rotated, the central rod **630** can be moved forward to expand the spinal implant structure **500**.

Finally, after the operation handle **640** and the converter **650** are disassembled, the central rod **630** is reverse rotated (counterclockwise rotated) to release the connection between the outer thread **631** and the inner thread **512a** of the second part **512**. After the central rod **630** is taken out, the distance between the expanded first part **511** and the second part **512** is fixed by a fixing screw barrel **520**. An embodiment in which the operating tool fixes the spinal implant structure **500** is described below with reference to FIG. 29 through FIG. 31. FIG. 29 is an explosive view of a fixing screw barrel **520** and a fixing sleeve **620** for fixing a spinal implant structure **500**, and FIG. 30 is a schematic view of applying the fixing screw barrel **520** and the fixing sleeve **620** coupled thereto to the tool body **610**, FIG. 31 is a schematic view of the fixing screw barrel **520** assembled to the body **610** of the spinal implant structure **500**.

Referring to FIG. 29, in the present embodiment, the operating tool also includes a fixing sleeve **620**. In the present embodiment, the front end of the fixing sleeve **620** is connected to the fixing screw barrel **520**. The fixing screw barrel **520** includes a fixing portion **521**, a fracture portion **522**, and a removal portion **523**. The fracture portion **522** is also a stress weakening structure, and is located between the fixing portion **521** and the removal portion **523**.

Referring to FIG. 27 through FIG. 29, the outer surface of the removal portion **523** has an external thread outer thread **523a**, and the front end of the fixing sleeve **620** has an inner thread **621** so that the removal portion **523** can be screwed into the fixing sleeve **620** and fixed to the front end of the fixing sleeve **620**, as shown in FIG. 30. Since the diameter of the fixing screw barrel **520** is smaller than the diameter of the first part **511**, the user can insert the fixing screw barrel

520 and the fixing sleeve 620 into the tool body 610 and can have the fixing screw barrel 520 fed into the body 510. Referring to FIG. 31, the inner surface of the first part 511 of the body 510 has a first thread portion 511a, and the outer surface of the fixing portion 521 of the fixing screw barrel 520 has a second thread portion 521a that is matched with the first thread portion 511a, such that the fixing screw barrel 520 can be screwed into the first part 511 and adjusted in position and fixed by the thread. The outer diameter of the fixing portion 521 of the fixing screw barrel 520 is larger than the inner diameter of the second part 512, so that the front end of the fixing portion 521 can abut the second part 512, thereby stabilizing the distance between the first part 511 and the second part 512. Next, the fixing sleeve 620 is twisted by force, and the removal portion 523 is rotated to crack the fracture portion 522. Finally, the fixing sleeve 620 is taken out along with the removal portion 523, as shown in FIG. 31. The fixing portion 521 is retained in the body 510 to fix the distance between the first part 511 and the second part 512.

Due to the design of the expansion arm and the support arm of the spinal implant structure of the present invention, the spinal implant structure is steadily expanded within the vertebral body. Furthermore, the design of the netting of the spinal implant structure restricts the range of the flow of the bone cement, reduces the likelihood of a failure of vertebroplasty, and reinforces the vertebral body as a result of the expansion of the spinal implant structure.

Due to the design of the connection of the operating tool and the spinal implant structure of the present invention, not only are the spinal implant structure and the operating tool coupled together, but the expansion step and the bone cement perfusion step are also stable, thereby increasing the likelihood of successful vertebroplasty and reducing complications.

Although the operating tool of the present invention comprises many components, the components are not only easily put together and separated but also embody plenty practical operation-related advantages. When necessary, the user can easily disassemble the operating tool of the present invention and start to operate the spinal implant structure by hand so as to preclude any possible emergency. Therefore, the operating tool and the spinal implant structure of the present invention have advantages neither anticipated of nor achieved by conventional tools for use in vertebroplasty.

Although the present invention is disclosed above by embodiments, the embodiments are not restrictive of the present invention. Equivalent implementation of, or equivalent changes made to, the embodiments by persons skilled in the art without departing from the spirit of the present invention must be deemed falling within the scope of the present invention. Accordingly, the legal protection for the present invention should be defined by the appended claims.

What is claimed is:

1. A spinal implant structure having a folded position and an expansion position, comprising
  - a body, the body being a hollow-cored cylinder when the spinal implant structure is in the folded position, the body comprising:
    - a first part;
    - a second part; and
  - at least one expansion arm, the expansion arm having an end connecting with the first part and another end being a free end; and
  - at least one supporting arm, the supporting arm having an end connecting with the expansion arm and another end connecting with the second part,

wherein the supporting arm comprises a plurality of weakening portions so that, in response to a change in a distance between the first part and the second part, the supporting arm bends at the plurality of weakening portions and thus drives the expansion arm to move, thereby increasing an included angle between the expansion arm and the first part, expanding the spinal implant structure, and causing the spinal implant structure to turn into the expansion position;

wherein a number of expansion arms is three, and a ratio of curvatures of the three expansion arms is higher than 1:1:1 but less than or equal to 1.6:1:1.

2. The spinal implant structure of claim 1, wherein the curvature of each of the three expansion arms refer to the curvature formed by an outer surfaces of each of the three expansion arms.

3. The spinal implant structure of claim 1, wherein one of the expansion arms has a curvature of 150 degrees, and the other two of the expansion arms have a curvature of 105 degrees.

4. The spinal implant structure of claim 1, wherein one of the expansion arms has a curvature of 145 degrees, and the other two of the expansion arms have a curvature of 107.5 degrees.

5. The spinal implant structure of claim 1, wherein one of the expansion arms has a curvature of 140 degrees, and the other two of the expansion arms have a curvature of 110 degrees.

6. The spinal implant structure of claim 1, wherein one of the expansion arms has a curvature of 135 degrees, and the other two of the expansion arms have a curvature of 112.5 degrees.

7. The spinal implant structure of claim 1, wherein one of the expansion arms has a curvature of 130 degrees, and the other two of the expansion arms have a curvature of 115 degrees.

8. The spinal implant structure of claim 1, wherein one of the expansion arms has a curvature of 125 degrees, and the other two of the expansion arms have a curvature of 117.5 degrees.

9. The spinal implant structure of claim 1, wherein the spinal implant structure is configured to be implanted in an implant passage of a vertebral body, and the expansion arm with the greater curvature is used for individually contacting one side of the implant passage, the expansion arms with the smaller curvature are used for jointly contacting the other side of the implant passage.

10. The spinal implant structure of claim 1, wherein the spinal implant structure has an outer diameter configured to be smaller than an inner diameter of an implant passage in the folded position.

11. The spinal implant structure of claim 1 further comprising:

a fixing screw barrel fitting inside the first part, the fixing screw barrel has an outer diameter larger than an inner diameter of the second part, and causing an end of the fixing screw barrel abuttingly connecting with the second part to fix the distance between the first part and the second part.

12. The spinal implant structure of claim 11, wherein the fixing screw barrel comprises a fixing portion, a fracture portion, and a removal portion, the fracture portion is located between the fixing portion and the removal portion, and the fracture portion is a weakening structure.

13. The spinal implant structure of claim 11, wherein an inner surface of the first part has a first thread portion, an

outer surface of the fixing screw barrel has a second thread portion, the first thread portion matches with the second thread portion.

14. The spinal implant structure of claim 1, wherein a number of the weakening portions of the supporting arm is two, and the two weakening portions have opposite opening directions. 5

15. The spinal implant structure of claim 14, wherein an interior angle of one of the two weakening portions close to the second part is smaller than an interior angle of the other weakening portion after bending. 10

16. The spinal implant structure of claim 1, wherein a thickness of the expansion arm is gradually thinned from one end close to the first part to the other end of the expansion arm away from the first part. 15

17. The spinal implant structure of claim 1, wherein a shape of a cross section of the expansion arm in a long axis direction of the spinal implant structure is a wedge shape.

18. The spinal implant structure of claim 1, wherein a thickness of the supporting arm is gradually thinned from one end close to the first part to the other end of the supporting arm away from the first part. 20

19. The spinal implant structure of claim 1, wherein a shape of a cross section of the supporting arm in a long axis direction of the spinal implant structure is a wedge shape. 25

\* \* \* \* \*