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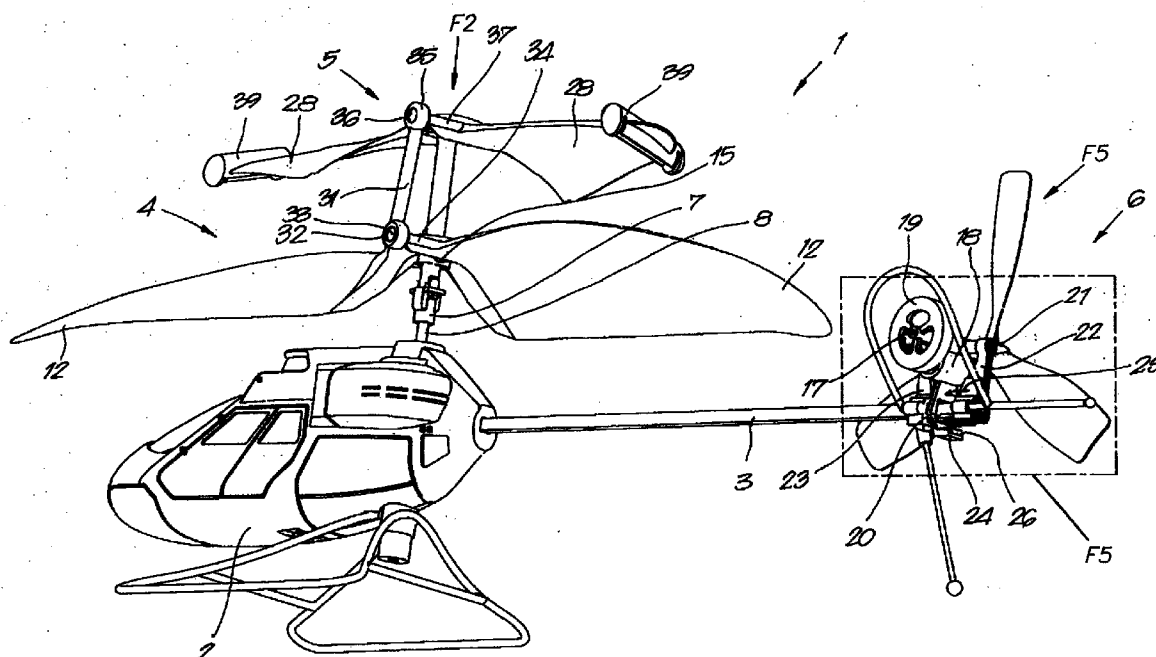
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Hong Kong (HK)(21) Appl. No.: **11/462,177**(22) Filed: **Aug. 3, 2006**(30) **Foreign Application Priority Data**

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(57) **ABSTRACT**

A helicopter has a main rotor with propeller blades which is driven by a rotor shaft and which is hinge-mounted to this rotor shaft. The angle between the surface of rotation of the main rotor and the rotor shaft may vary. A swinging member on an oscillatory shaft is essentially transverse to the rotor shaft of the main rotor and is directed transversally to the longitudinal axis of the vanes. The main rotor and the auxiliary rotor are connected to each other by a mechanical link. The swinging motions of the auxiliary rotor controls the angle of incidence (A) of at least one of the propeller blades of the main rotor.



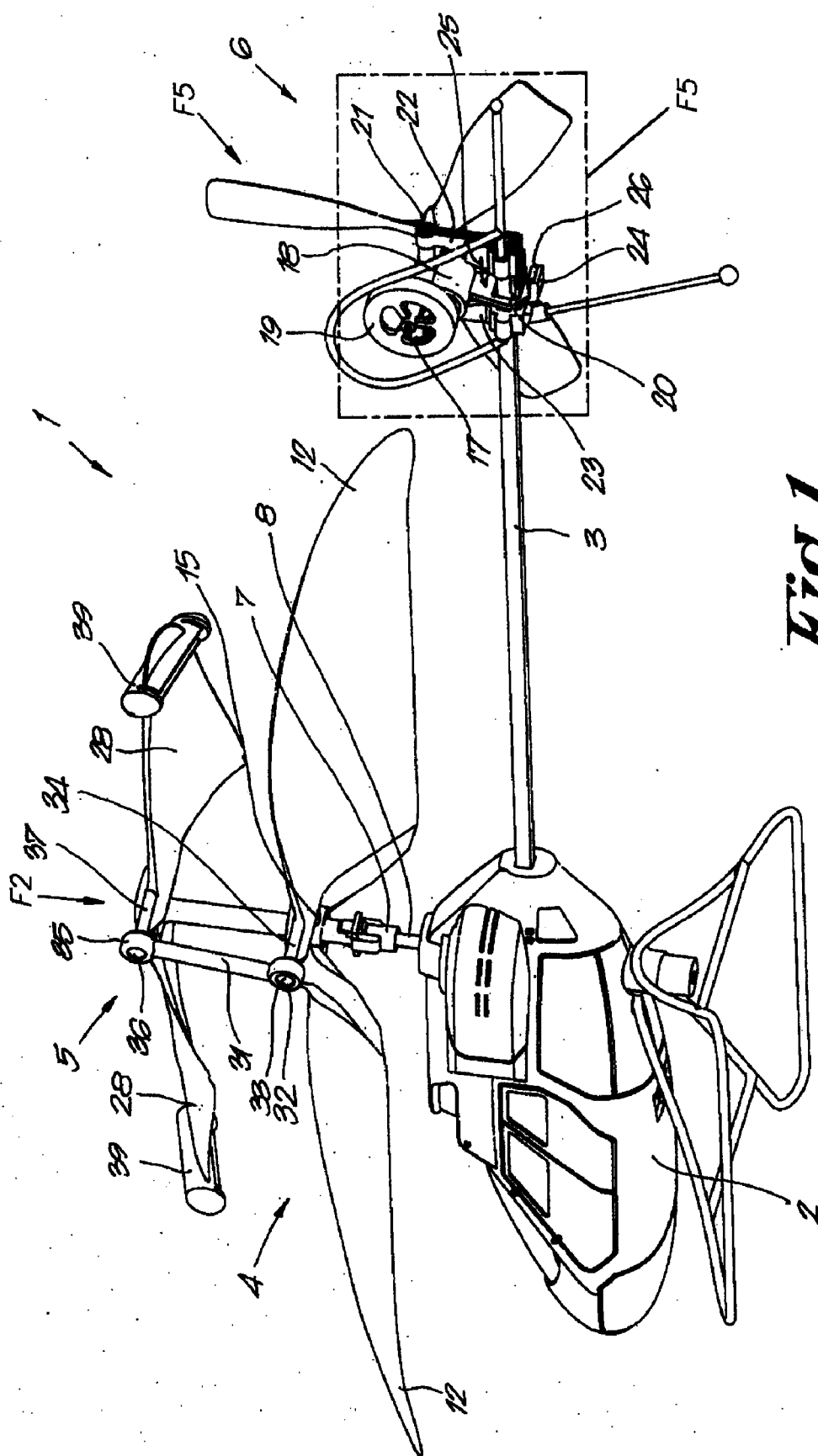
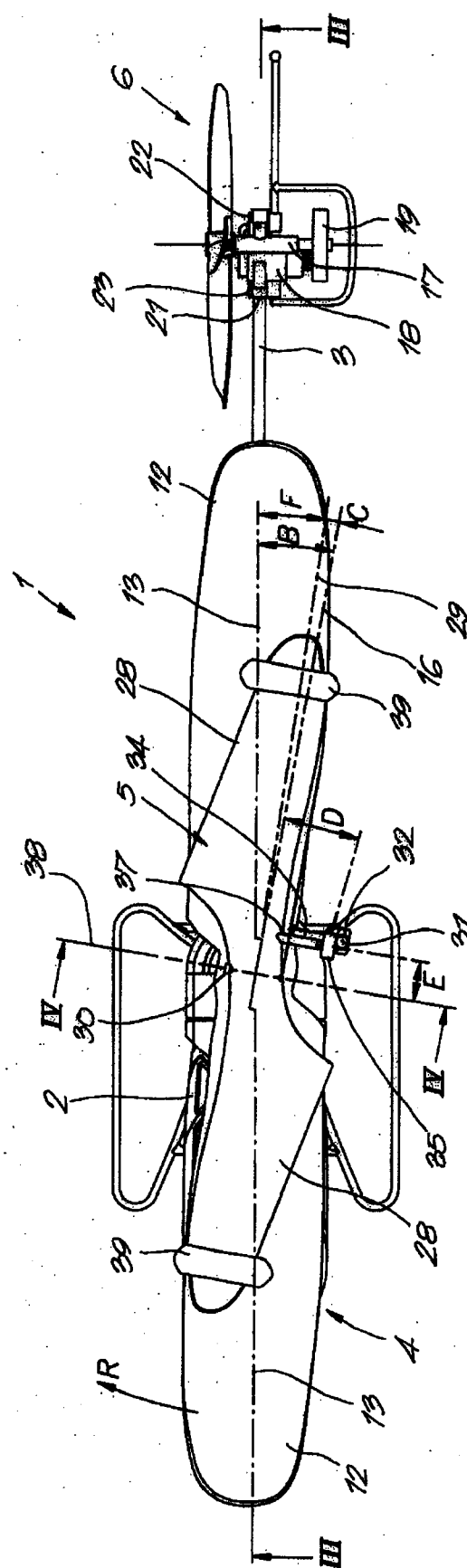


Fig. 1



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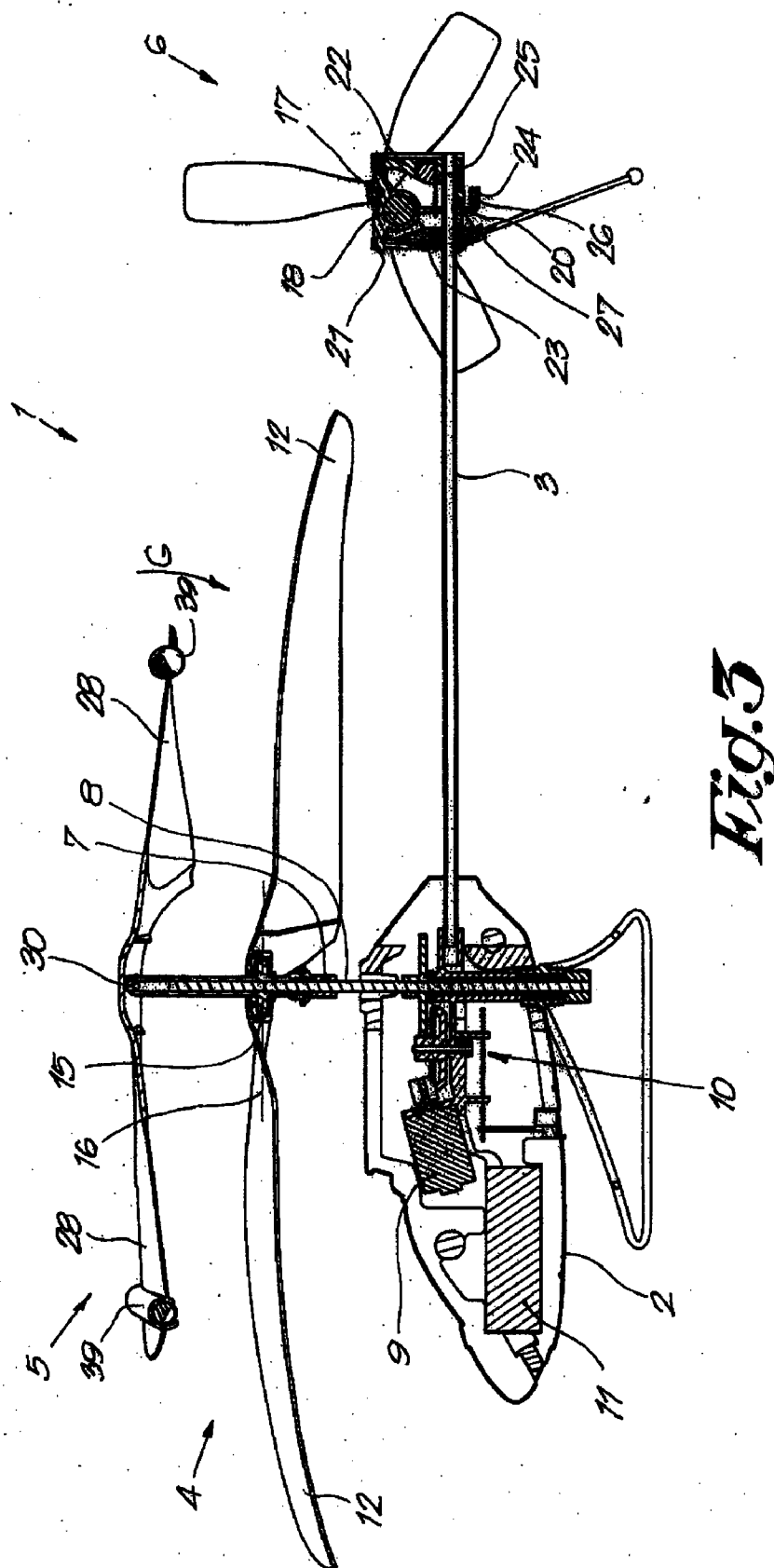


Fig. 3

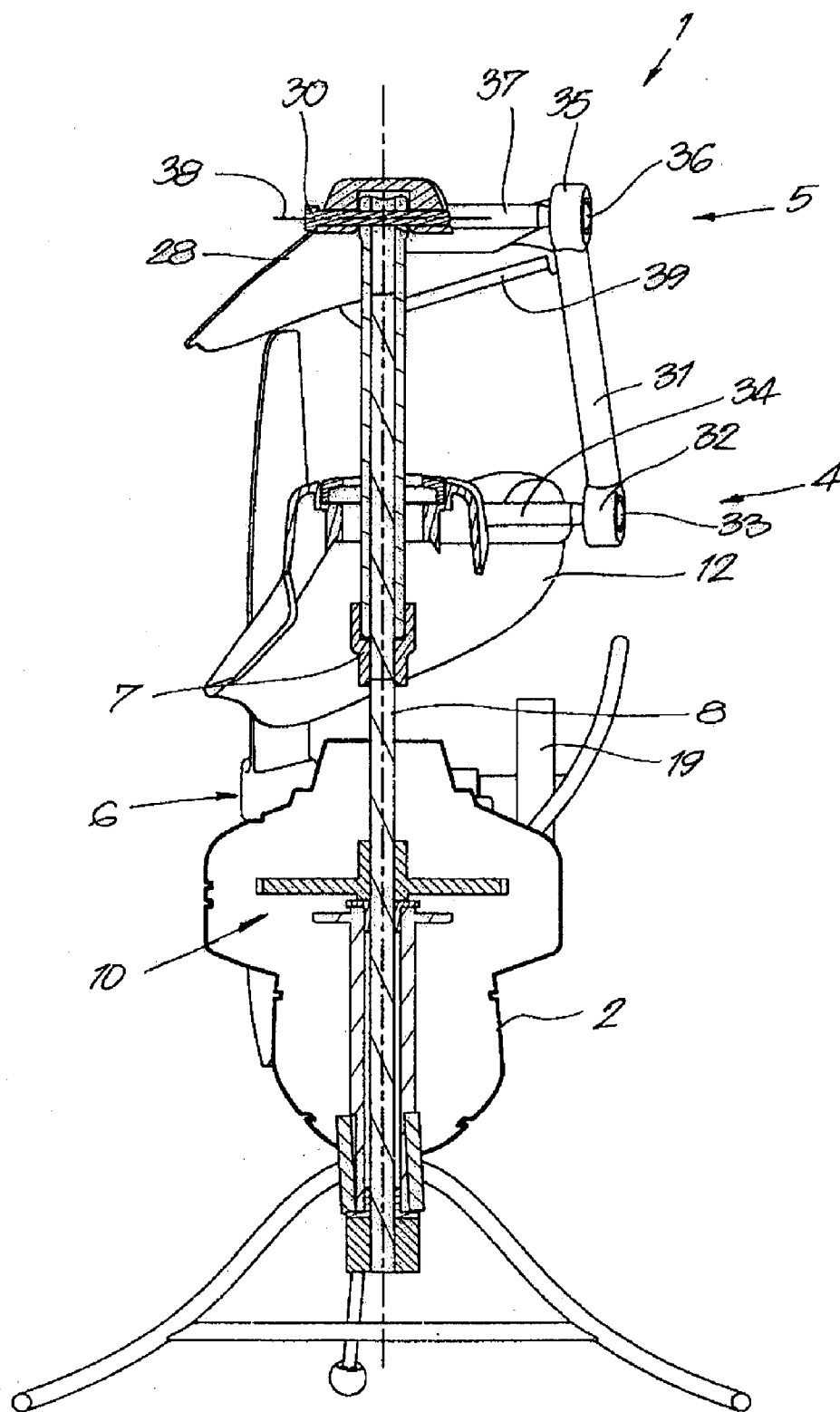


Fig. 4

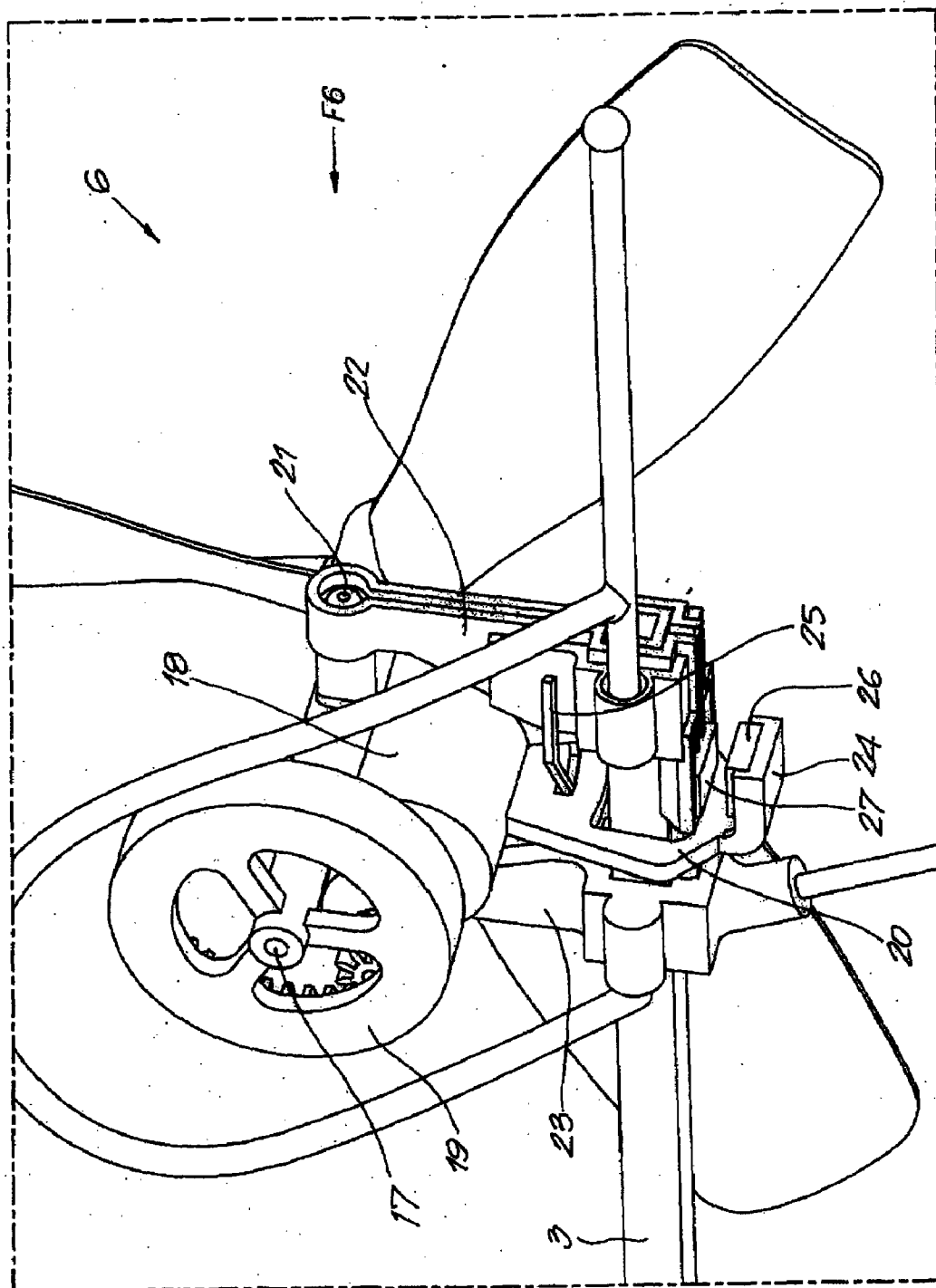


Fig. 5

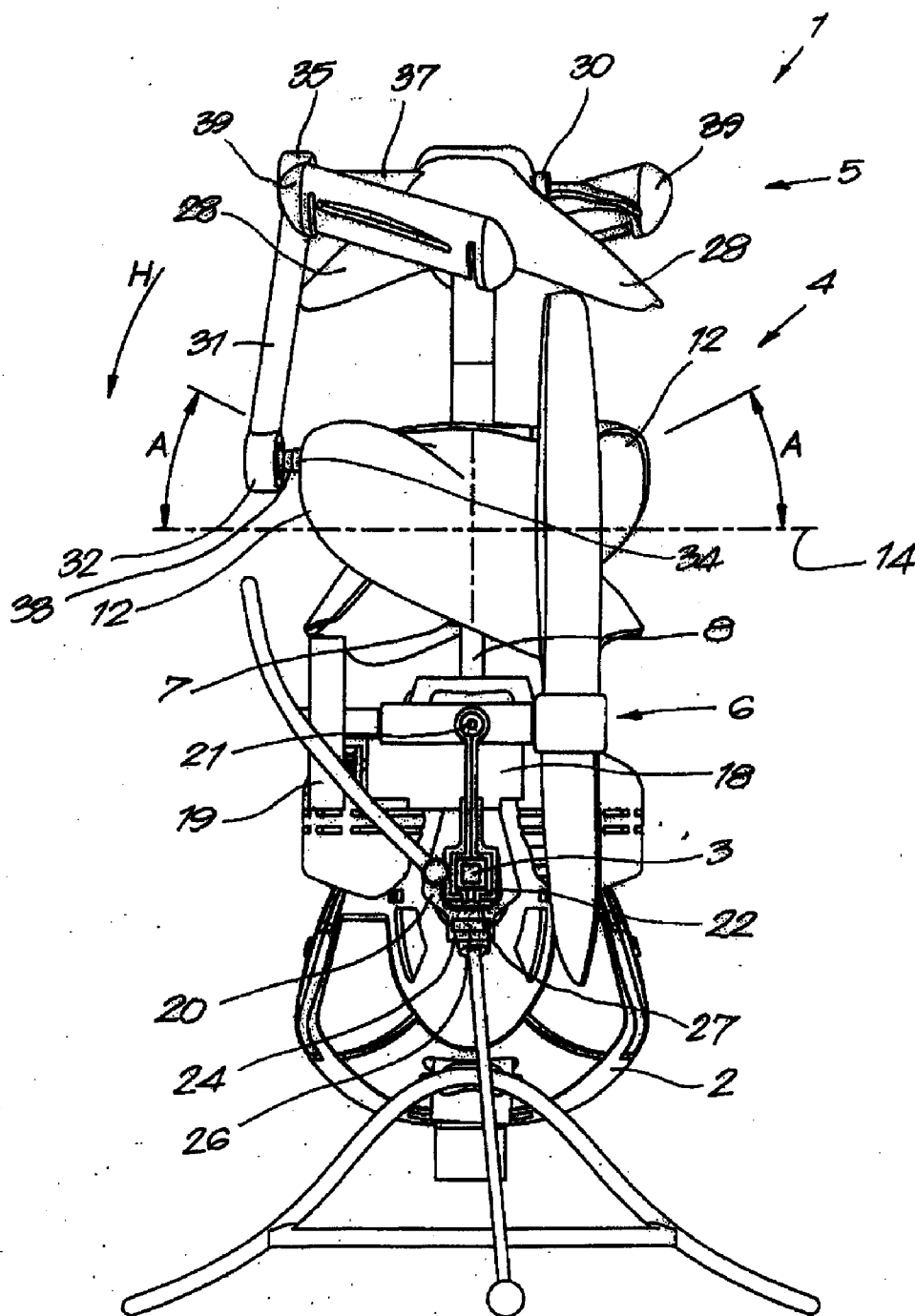


Fig. 6

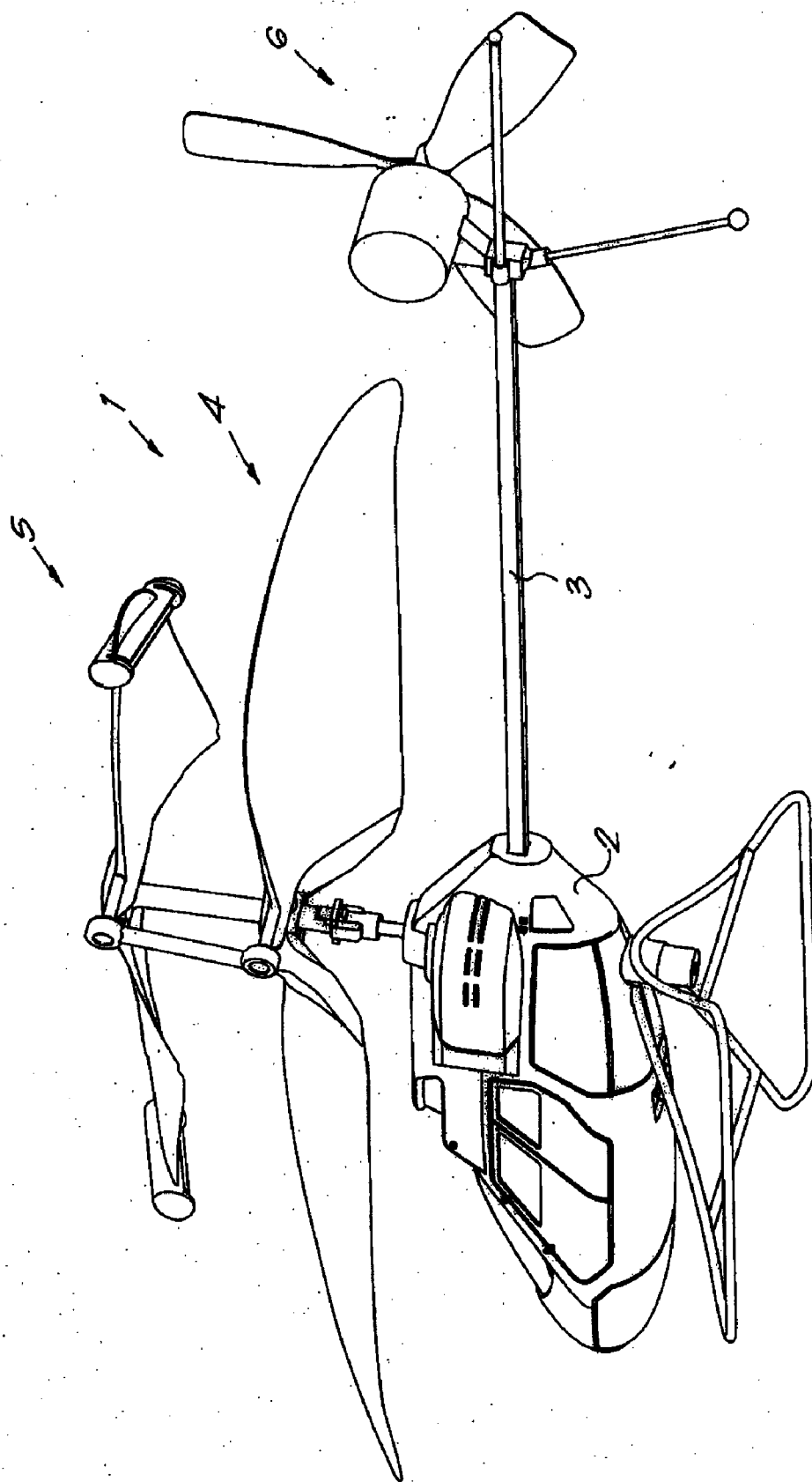


Fig. 7

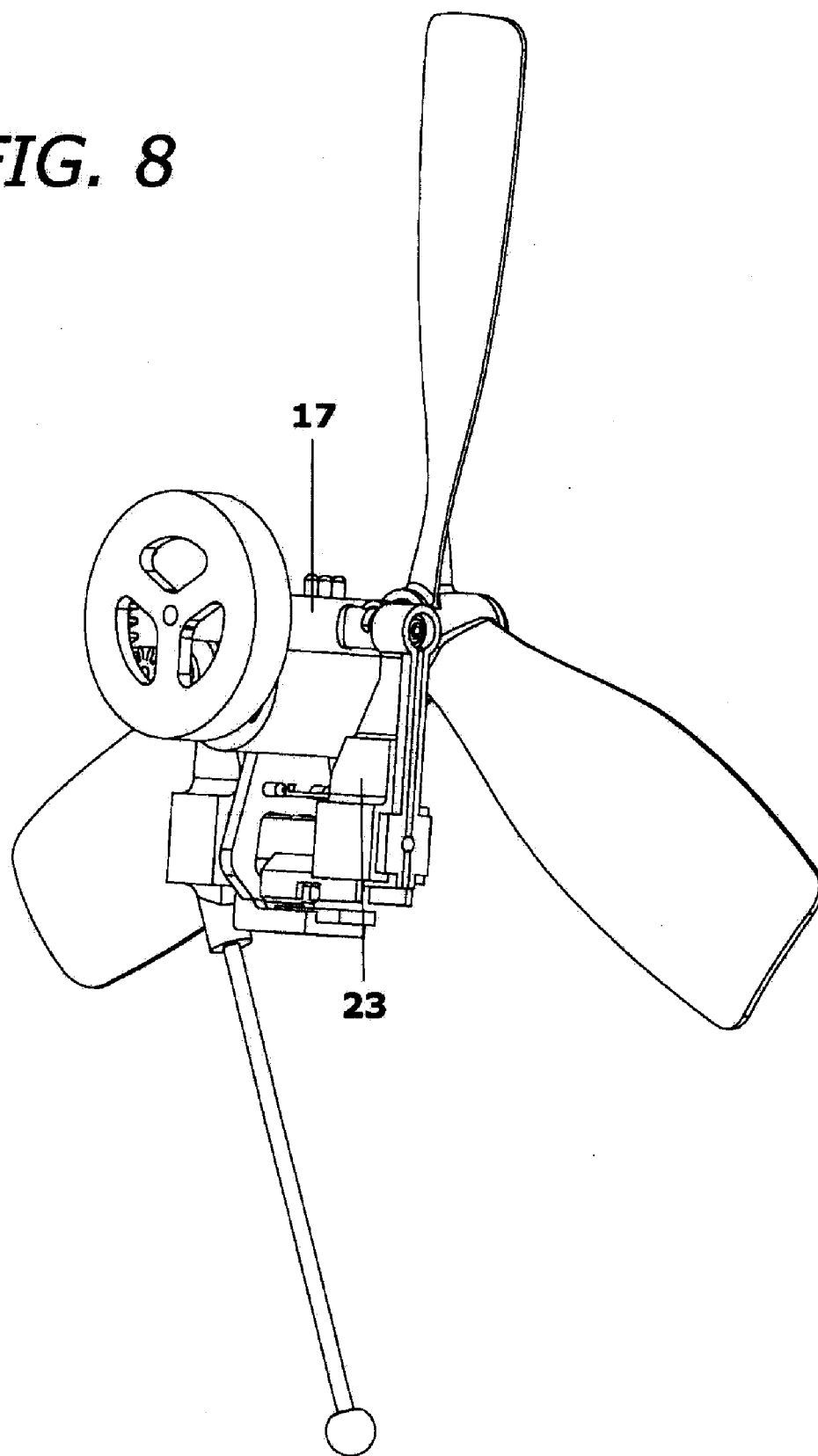
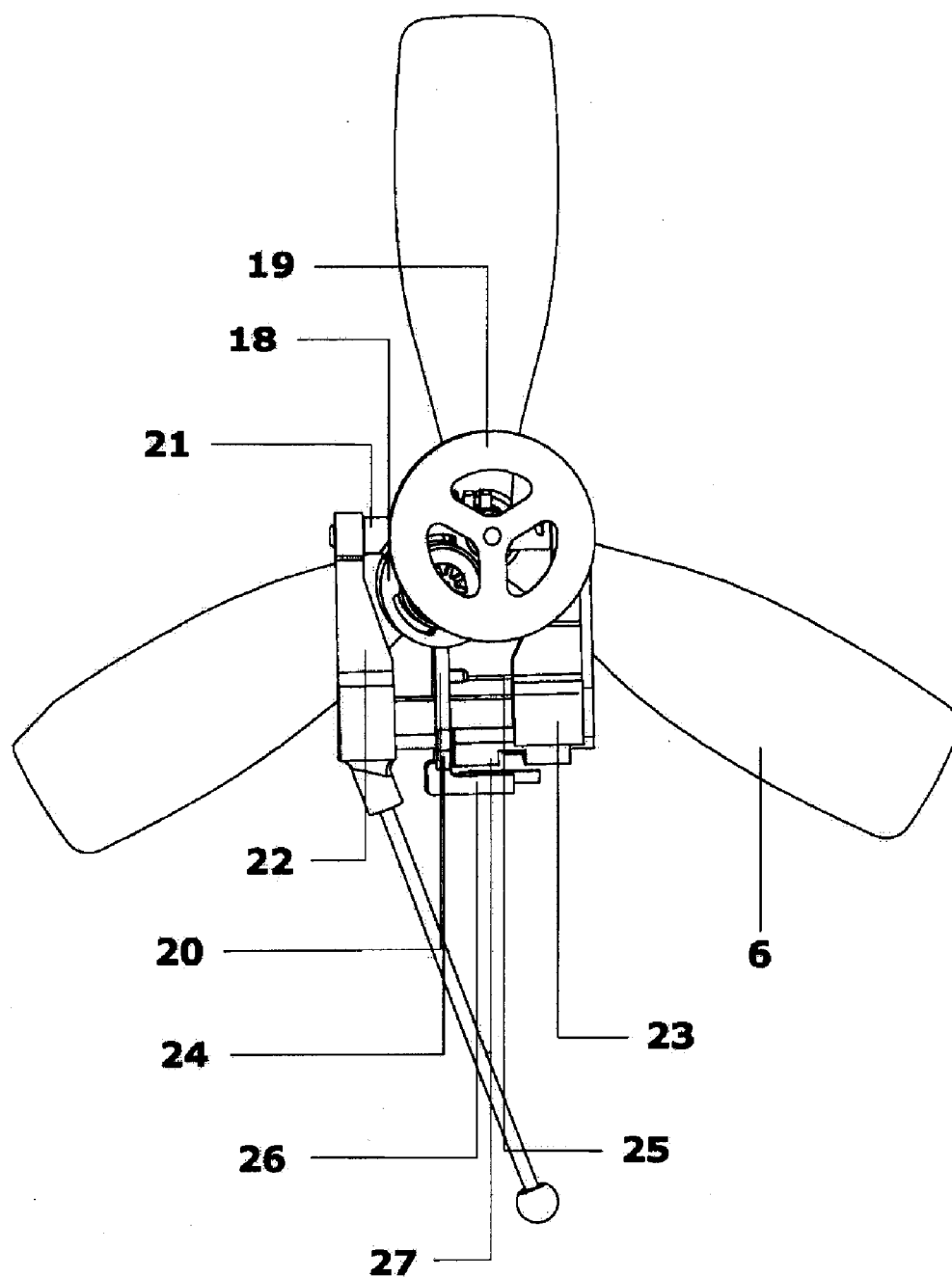
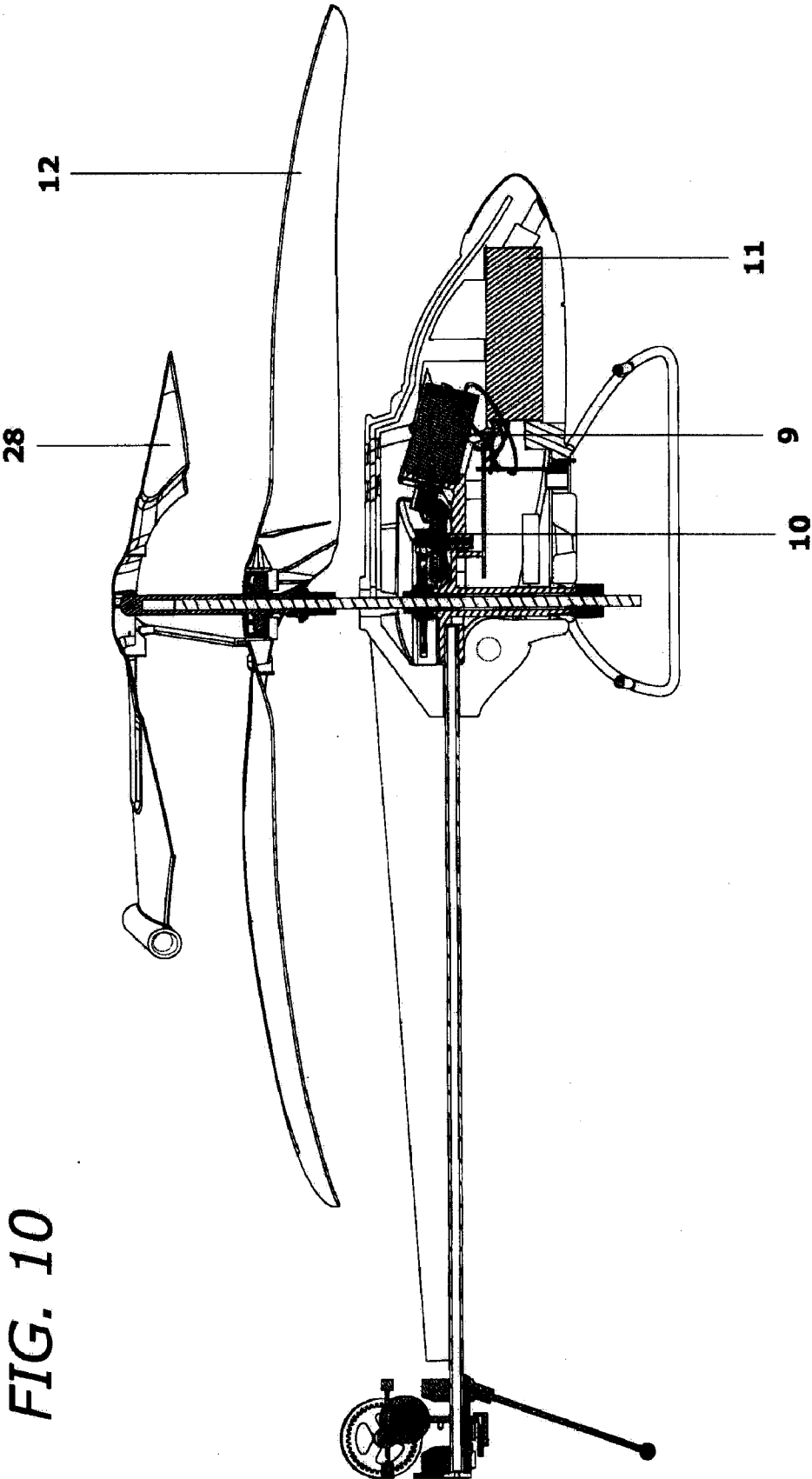
FIG. 8

FIG. 9





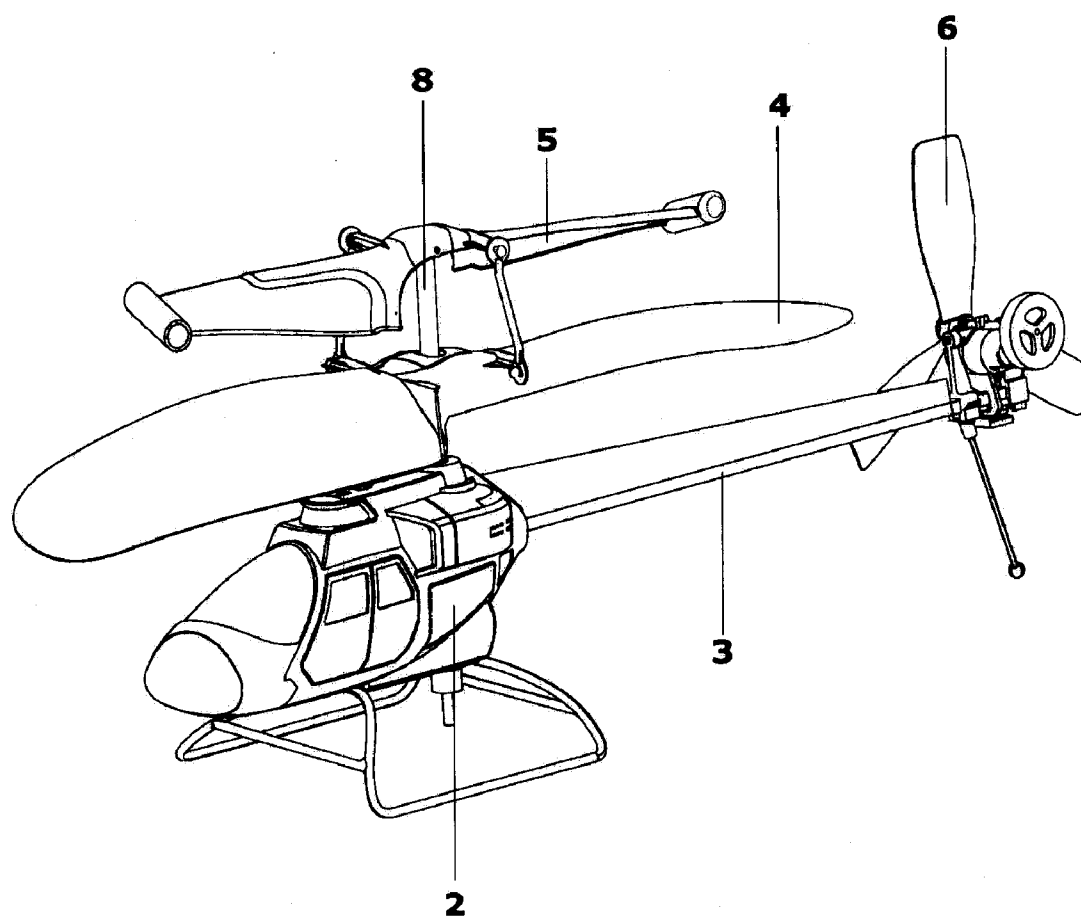


FIG. 11

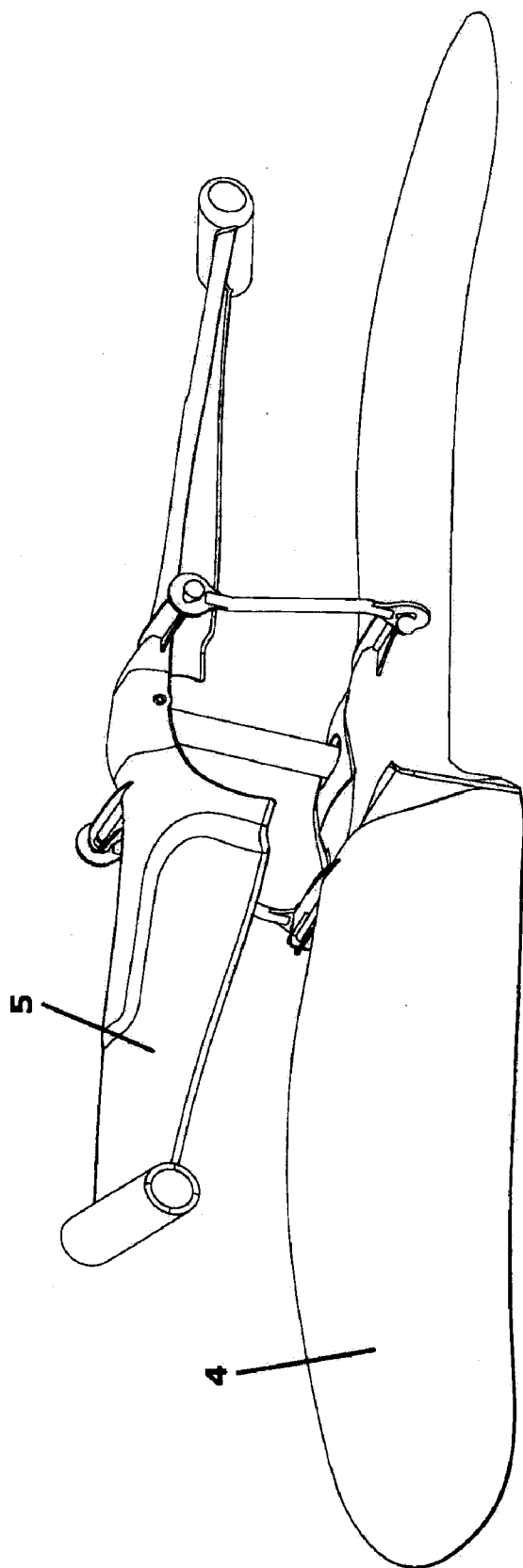


FIG. 12

HELICOPTER

RELATED APPLICATION

[0001] This application claims priority to Belgian Patent Application No. 2006/0043 entitled AUTOSTABIELE HELICOPTER by Alexander VAN DE ROSTYNE, which was filed on Jan. 19, 2006. The contents of that application are incorporated by reference herein.

BACKGROUND

[0002] The present disclosure concerns an improved helicopter.

[0003] The disclosure concerns a helicopter generally. In particular, but not exclusively it is related to a toy helicopter, and in particular to a remote-controlled model helicopter or a toy helicopter.

SUMMARY

[0004] It is known that a helicopter is a complex machine which is unstable and as a result difficult to control, so that much experience is required to safely operate such helicopters without mishaps.

[0005] Typically, a helicopter includes a body, a main rotor and a tail rotor.

[0006] The main rotor provides an upward force to keep the helicopter in the air, as well as a lateral or forward or backward force to steer the helicopter in required directions. This can be by making the angle of incidence of the propeller blades of the main rotor vary cyclically at every revolution of the main rotor.

[0007] The main rotor has a natural tendency to deviate from its position, which may lead to uncontrolled movements and to a crash of the helicopter if the pilot loses control over the steering of the helicopter.

[0008] Solutions to slow down the effect have already been provided up to now, including the application of stabilizing rods and weights at the tips of the propeller blades.

[0009] All these solutions make use of the known phenomenon of gyroscopic precession, caused by the Coriolis force and the centrifugal forces, to obtain the desired effect.

[0010] The tail rotor is not at all insensitive to this phenomenon, since it has to prevent the body to turn round the drive shaft of the rotor as a result of the resistance torque of the rotor on the body.

[0011] To this end, the tail rotor is erected such that it develops a lateral thrust which has to counteract the above-mentioned resistance torque of the rotor, and the helicopter is provided with means which have to enable the pilot to control the lateral thrust so as to determine the flight position round the vertical axis.

[0012] Since the tail of the helicopter tends to turn round the drive shaft of the main rotor, even in case of small variations in the drive torque of the main rotor, most helicopters are provided with a separate and autonomous mechanical or electromechanical system such as a gyroscope or the like, which automatically compensates the thrust of the tail rotor for the unwanted rotations.

[0013] In general, the stability of a helicopter includes the result of the interaction between:

[0014] the rotation of the rotor blades; the movements of any possible stabilizing rods; compensation of the resistance torque of the main rotor by means of the tail rotor;

[0015] the system such as a gyroscope or the like to compensate for small undesired variations in the resistance torque of the main rotor; and

[0016] control of the helicopter which controls the rotational speed of the main rotor and of the tail rotor.

[0017] When these elements are essentially in balance the pilot should be able to steer the helicopter as desired.

[0018] This does not mean, however, that the helicopter can fly by itself and can thus maintain a certain flight position or maneuver, such as for example hovering or making slow movements, without the intervention of a pilot.

[0019] Moreover, flying a helicopter usually requires intensive training and much experience of the pilot, for both a full size operational real helicopter as well as a toy helicopter or a remote-controlled model helicopter.

[0020] The present disclosure aims to minimize one or several of the above-mentioned and other disadvantages by providing a simple and cheap solution to auto stabilize the helicopter, such that operating the helicopter becomes simpler and possibly reduces the need for long-standing experience of the pilot.

[0021] The helicopter should meet the following requirements to a greater or lesser degree:

[0022] (a) it can return to a stable hovering position, in case of an unwanted disturbance of the flight conditions. Such disturbance may occur in the form of a gust of wind, turbulences, a mechanical load change of the body or the rotors, a change of position of the body as a result of an adjustment to the cyclic variation of the pitch or angle of incidence of the propeller blades of the main rotor or a steering of the tail rotor or the like with a similar effect; and

[0023] (b) the time required to return to the stable position should be relatively short and the movement of the helicopter should be relatively small.

[0024] To this end, the disclosure concerns an improved helicopter including a body with a tail; a main rotor with propeller blades which are driven by a rotor shaft and which are hinge-mounted to the rotor shaft by means of a joint. The angle between the surface of rotation of the main rotor and the rotor shaft may vary. A tail rotor is driven by a second rotor shaft which is directed transversal to the rotor shaft of the main rotor.

[0025] The helicopter is provided with an auxiliary rotor which is driven by the shaft of the main rotor and which is provided with two vanes extending essentially in line with their longitudinal axis. The 'longitudinal' axis, is seen in the sense of rotation of the main rotor, and is essentially parallel to the longitudinal axis of at least one of the propeller blades of the main rotor or is located within a relatively small acute angle with the latter propeller blade axis. This auxiliary rotor is provided in a swinging manner on an oscillatory shaft which is provided essentially transversal to the rotor shaft of the main rotor. This is directed essentially transverse to the longitudinal axis of the vanes. The main rotor and the auxiliary rotor are connected to each other through a mechanical link, such that the swinging motions of the auxiliary rotor control the angle of incidence of at least one of the propeller blades of the main rotor.

[0026] In practice, it appears that such an improved helicopter is more stable and stabilizes itself relatively quickly with or without a restricted intervention of the user.

[0027] According to different aspect of the disclosure, the helicopter is made more stable by suspending the tail rotor with its rotor shaft in a swing which can rotate round a swing

shaft. The swing shaft essentially extends in the longitudinal direction relative to the body of the helicopter.

[0028] In case of malfunction or the like, whereby the helicopter starts to turn round the rotor shaft of the main rotor in an unwanted manner, the tail rotor, as a result of the gyroscopic precession acting on the rotating tail rotor as a result of the rotation round the rotor shaft of the main rotor, should tilt round the swing shaft of the tail rotor at a certain angle.

[0029] By measuring the relative angular displacement of the swing and by using the measured signal as an input signal for a microprocessor which controls the drive of the main rotor and the drive of the tail rotor as a function of a stabilizer algorithm, the thrust of the tail rotor can be adjusted so as to counteract the unwanted effect of the disturbance and to thus automatically restore the stable flight conditions for the helicopter, with minimal or any intervention of the pilot.

[0030] In this configuration, the tail rotor is used essentially as a gyroscope, such that the gyroscope of the known helicopters can be omitted. This can also result in a lot of weight being saved.

DRAWINGS

[0031] In order to further explain the characteristics of the disclosure, the following embodiments of an improved helicopter according to the disclosure are given as an example only, without being limitative in any way, with reference to the accompanying drawings, in which:

[0032] FIG. 1 schematically represents a helicopter according to the disclosure in perspective;

[0033] FIG. 2 represents a top view according to arrow F2 in FIG. 1;

[0034] FIGS. 3 and 4 represent respective sections according to lines II-II and III-III in FIG. 2;

[0035] FIG. 5 represents a view of the rear rotor part indicated in FIG. 1 by F5 to a larger scale;

[0036] FIG. 6 is a rear view according to arrow F6 in FIG. 5;

[0037] FIG. 7 represents a variant of FIG. 1;

[0038] FIG. 8 represents a variant of FIG. 5;

[0039] FIG. 9 represents a different view of the tail rotor of FIG. 8;

[0040] FIG. 10 represents a section of the helicopter;

[0041] FIG. 11 schematically represents an alternative view of the helicopter according to the disclosure in perspective;

[0042] FIG. 12 is a perspective view of the main rotor and auxiliary rotor.

DETAILED DESCRIPTION

[0043] The helicopter 1 represented in the figures by way of example is a remote-controlled helicopter which essentially consists of a body 2 with a landing gear and a tail 3; a main rotor 4; an auxiliary rotor 5 driven synchronously with the latter and a tail rotor 6.

[0044] The main rotor 4 is provided by means of what is called a rotor head 7 on a first upward directed rotor shaft 8 which is bearing-mounted in the body 2 of the helicopter 1 in a rotating manner and which is driven by means of a motor 9 and a transmission 10, whereby the motor 9 is for example an electric motor which is powered by a battery 11.

[0045] The main rotor 4 in this case has two propeller blades 12 which are in line or practically in line, but which may just as well be composed of a larger number of propeller blades 12.

[0046] The tilt or angle of incidence A of the propeller blades 12, in other words the angle A which forms the propeller blades 12 as represented in FIG. 6 with the plane of rotation 14 of the main rotor 4, can be adjusted as, the main rotor 4 is hinge-mounted on this rotor shaft 8 by means of a joint, such that the angle between the plane of rotation of the main rotor and the rotor shaft may freely vary.

[0047] In the case of the example of a main rotor 4 with two propeller blades 12, the joint is formed by a spindle 15 of the rotor head 7.

[0048] The axis 16 of this spindle 15 is directed transversal to the rotor shaft 8 and essentially extends in the direction of the longitudinal axis 13 of one of the propeller blades 12, and it preferably forms, as represented in FIG. 2, an acute angle B with this longitudinal axis 13.

[0049] The tail rotor 6 is driven via a second rotor shaft 17 by means of a second motor 18 and a transmission 19. Motor 16 can be an electric motor. The tail rotor 6 with its rotor shaft 17 and its drive 18-19 is suspended in a swing 20 which can rotate round a swing shaft 21 which is fixed to the tail 3 of the helicopter 1 by two supports 22 and 23.

[0050] The swing 20 is provided with an extension piece 24 towards the bottom, which is kept in a central position by means of a spring 25 when in a state of rest, whereby the second rotor shaft 17 in this position is horizontal and directed crosswise to the first rotor shaft 8.

[0051] On the lower end of the extension piece 24 of the swing 20 is provided a magnet 26, whereas opposite the position of the magnet 26 in the above-mentioned state of rest of the swing 20 is fixed a magnetic sensor 27 to the tail 3 which makes it possible to measure the relative angular displacement of the swing 20 and thus of the tail rotor 6 round the swing shaft 21.

[0052] It is clear that this angular displacement of the swing 20 can also be measured in other ways, for example by means of a potentiometer.

[0053] The measured signal can be used as an input signal for a control box, which is not represented in the figures, which controls the drives of the main rotor 4 and of the tail rotor 6 and which is provided with a stabilizer algorithm which will give a counter steering command when a sudden unwanted angular displacement of the tail rotor 6 is measured round the swing shaft 21, resulting from an unwanted rotation of the helicopter 1 round the rotor shaft 8, so as to restore the position of the helicopter 1.

[0054] The helicopter 1 is also provided with an auxiliary rotor 5 which is driven substantially synchronously with the main rotor 4 by the same rotor shaft 8 and the rotor head 7.

[0055] The main rotor 4 in this case has two vanes 28 which are essentially in line with their longitudinal axis 29, whereby the longitudinal axis 29, seen in the sense of rotation R of the main rotor 4, is essentially parallel to the longitudinal axis 13 of propeller blades 12 of the main rotor 4 or encloses a relatively small acute angle C with the latter, so that both rotors 4 and 5 extend more or less parallel on top of one another with their propeller blades 12 and vanes 28 so to say.

[0056] The diameter of the auxiliary rotor 5 is preferably smaller than the diameter of the main rotor 4 as the vanes 28 have a smaller span than the propeller blades 12, and the

vanes, **28** are substantially rigidly connected to each other. This rigid whole forming the auxiliary rotor **5** is provided in a swinging manner on an oscillating shaft **30** which is fixed to the rotor head **7** of the rotor shaft **8**. This is directed transversally the longitudinal axis of the vanes **28** and transversally to the rotor shaft **8**.

[0057] The main rotor **4** and the auxiliary rotor **5** are connected to each other by a mechanical link which is such of the auxiliary rotor **5** the angle of incidence A of at least one of the propeller blades **12** of the main rotor **4**. In the given example this link is formed of a rod **31**.

[0058] This rod **31** is hinge-mounted to a propeller blade **12** of the main rotor **4** with one fastening point **32** by means of a joint **33** and a lever arm **34**, and with another second fastening point **35**, situated at a distance from the latter, it is hinge-mounted to a vane **28** of the auxiliary rotor **5** by means of a second joint **36** and a second lever arm **37**.

[0059] The fastening point **32** on the main rotor **4** is situated at a distance D from the axis **16** of the spindle **15** of the propeller blades **12** of the main rotor **4**, whereas the other fastening point **35** on the auxiliary rotor **5** is situated at a distance E from the axis **38** of the oscillatory shaft **30** of the auxiliary rotor **5**.

[0060] The distance D is preferably larger than the distance E, and about the double of this distance E, and both fastening points **32** and **35** of the rod **31** are situated, seen in the sense of rotation R, on the same side of the propeller blades **12** of the main rotor **4** or of the vanes **28** of the auxiliary rotor **5**, in other words they are both situated in front of or at the back of the propeller blades **12** and vanes **28**, seen in the sense of rotation.

[0061] Also preferably, the longitudinal axis **29** of the vanes **28** of the auxiliary rotor **5**, seen in the sense of rotation R, encloses an angle F with the longitudinal axis **13** of the propeller blades **12** of the main rotor **4**, which enclosed angle F is in the order, of magnitude of 10°, whereby the longitudinal axis **29** of the vanes **28** leads the longitudinal axis **13** of the propeller blades **12**, seen in the sense of rotation R.

[0062] The auxiliary rotor **5** is provided with two stabilizing weights **39** which are each fixed to a vane **28** at a distance from the rotor shaft **8**.

[0063] Further, the helicopter **1** is provided with a receiver, so that it can be controlled from a distance by means of a remote control which is not represented.

[0064] As a function of the type of helicopter, it is possible to search for the most appropriate values and relations of the angles B, F and G by experiment; the relation between the distances D and E; the size of the weights **39** and the relation of the diameters between the main rotor **4** and the auxiliary rotor **5** so as to guarantee a maximum auto stability.

[0065] The operation of the improved helicopter **1** according to the disclosure is as follows.

[0066] In flight, the rotors **4**, **5** and **6** are driven at a certain speed, as a result of which a relative air stream is created in relation to the rotors, as a result of which the main rotor **4** generates an upward force so as to make the helicopter **1** rise or descend or maintain it at a certain height, and the tail rotor **6** develops a laterally directed force which is used to steer the helicopter **1**.

[0067] It is impossible for the main rotor **4** to adjust itself, and it will turn in the plane **14** in which it has been started, usually the horizontal plane. Under the influence of gyro-

scopic precession, turbulence and other factors, it will take up an arbitrary undesired position if it is not controlled.

[0068] The surface of rotation of the auxiliary rotor **5** may take

[0069] up another inclination in relation to the surface of rotation **14** of the main rotor **8**, whereby both rotors **5** and **4** may take up another inclination in relation to the rotor, shaft **8**.

[0070] This difference in inclination may originate in any internal or external force or disturbance whatsoever.

[0071] In a situation whereby the helicopter **1** is hovering stable, on a spot in the air without any disturbing internal or external forces, the auxiliary rotor **5** keeps turning in a plane which is essentially perpendicular to the rotor shaft **8**.

[0072] If, however, the body **2** is pushed out of balance due to any disturbance whatsoever, and the rotor shaft **8** turns away from its position of equilibrium, the auxiliary rotor **5** does not immediately follow this movement, since the auxiliary rotor **5** can freely move round the oscillatory shaft **30**.

[0073] The main rotor **4** and the auxiliary rotor **5** are placed in relation to each other in such a manner that a swinging motion of the auxiliary rotor **5** is translated almost immediately in the pitch or angle of incidence A of the propeller blades **12** being adjusted.

[0074] For a two-bladed main rotor **4**, this means that the propeller blades **12** and the vanes **28** of both rotors **4** and **5** must be essentially parallel or, seen in the sense of rotation R, enclose an acute angle with one another of for example 10° in the case of a large main rotor **4** and a smaller auxiliary rotor **5**.

[0075] This angle can be calculated or determined by experiment for any helicopter **1** or per type of helicopter.

[0076] If the axis of rotation **8** takes up another inclination than the one which corresponds to the above-mentioned position of equilibrium in a situation whereby the helicopter **1** is hovering, the following happens:

[0077] A first effect is that the auxiliary rotor **5** will first try to preserve its absolute inclination, as a result of which the relative inclination of the surface of rotation of the auxiliary rotor **5** in relation to the rotor shaft **8** changes.

[0078] As a result, the rod **31** will adjust the angle of incidence A of the propeller blades **12**, so that the upward force of the propeller blades **12** will increase on one side of the main rotor **4** and will decrease on the diametrically opposed side of this main rotor.

[0079] Since the relative position of the main rotor **4** and the auxiliary rotor **5** are selected such that a relatively immediate effect is obtained. This change in the upward force makes sure that the rotor shaft **8** and the body **21** are forced back into their original position of equilibrium.

[0080] A second effect is that, since the distance between the far ends of the vanes **28** and the plane of rotation **14** of the main rotor **4** is no longer equal and since also the vanes **28** cause an upward force, a larger pressure is created between the main rotor **4** and the auxiliary rotor **5** on one side of the main rotor **4** than on the diametrically opposed side.

[0081] A third effect plays a role when the helicopter begins to tilt over to the front, to the back or laterally due to a disturbance. Just as in the case of a pendulum, the helicopter will be inclined to go back to its original situation. This pendulum effect does not generate any destabilizing gyroscopic forces as with the known helicopters that are

equipped with a stabilizer bar directed transversally to the propeller blades of the main rotor. It acts to reinforce the first and the second effect.

[0082] The effects have different origins but have analogous natures. They reinforce each other so as to automatically correct the position of equilibrium of the helicopter **1** without any intervention of a pilot.

[0083] The tail rotor **6** is located in a swinging manner and provides for an additional stabilization and makes it possible for the tail rotor **6** to assume the function of the gyroscope which is often used in existing helicopters, such as model helicopters.

[0084] In case of a disturbance, the body **2** may start to turn round the rotor shaft **8**. As a result, the tail rotor **6** turns at an angle in one or other sense round the swinging shaft **21**. This is due to the gyroscopic precession which acts on the rotating tail rotor **6** as a result of the rotation of the tail rotor **6** round the rotor shaft **8**. The angular displacement is a function of the amplitude of the disturbance and thus of the rotation of the body **2** round the rotor shaft **8**. This is measured by the sensor **27**.

[0085] The signal of the sensor **27** is used by a control box of a computer to counteract the failure and to adjust the thrust of the tail rotor **6** so as to annul the angular displacement of the tail rotor **6** which is due to the disturbance.

[0086] This can be done by adjusting the speed of the tail rotor **6** and/or by adjusting the angles of incidence of the propeller blades of the tail rotor **6**, depending on the type of helicopter **1**.

[0087] If necessary, this aspect of the disclosure may be applied separately, just as the aspect of the auxiliary rotor **5** can be applied separately, as is illustrated for example by means of FIG. 7, which represents a helicopter **1** according to the disclosure having a main rotor **4** combined with an auxiliary rotor **5**, but whose tail rotor **6** is of the conventional type, i.e. whose shaft cannot turn in a swing but is bearing-mounted in relation to the tail **3**.

[0088] In practice, the combination of both aspects makes it possible to produce a helicopter which is very stable in any direction and any flight situation and which is easy to control, even by persons having little or no experience.

[0089] It is clear that the main rotor **4** and the auxiliary rotor **5** must not necessarily be made as a rigid whole. The propeller blades **12** and the vanes **28** can also be provided on the rotor head **7** such that they are mounted and can rotate relatively separately. In that case, for example, two rods **31** may be applied to connect each time one propeller blade **12** to one vane **28**.

[0090] It is also clear that, if necessary, the joints and hinge joints may also be realized in other ways than the ones represented, for example by means of torsion-flexible elements.

[0091] In the case of a main rotor **4** having more than two propeller blades **12**, one should preferably be sure that at least one propeller blade **12** is essentially parallel to one of the vanes **28** of the auxiliary rotor. The joint of the main rotor **4** is preferably made as a ball joint or as a spindle **15** which is directed essentially transversely to the axis of the oscillatory shaft **30** of the auxiliary rotor **5** and which essentially extends in the longitudinal direction of the one propeller blade **12** concerned which is essentially parallel to the vanes **28**.

[0092] The present disclosure is not limited to the embodiments described as an example and represented in the

accompanying figures. Many different variations in size and scope and features are possible. For instance, instead of electrical motors being provided others forms of motorized power are possible. A different number of blades may be provided to the rotors.

[0093] A helicopter according to the disclosure can be made in all sorts of shapes and dimensions while still remaining within the scope of the disclosure. In this sense although the helicopter in some senses has been described as toy or model helicopter, the features described and illustrated can have use in part or whole in a full-scale helicopter.

1. A helicopter comprising a body with a tail; a main rotor with propeller blades which is driven by a rotor shaft and which is hinge mounted on this rotor shaft, such that the angle between the plane of rotation of the main rotor and the rotor shaft may vary; a tail rotor which is driven by a second rotor shaft directed transversally to the rotor shaft of the main rotor, an auxiliary rotor driven by the rotor shaft of the main rotor and provided with two vanes extending essentially in a line with their longitudinal axis in the sense of rotation of the main rotor is essentially parallel to the longitudinal axis of at least one of the propeller blades of the main rotor or is at a relatively small acute angle relative to the axis, the auxiliary rotor being mounted in a swinging relationship on an oscillatory shaft which is provided essentially transversally to the rotor shaft of the main rotor and being directed essentially transversally to the longitudinal axis of the vanes, and the main rotor and the auxiliary rotor are connected to each other by a mechanical link, such that the swinging motion of the auxiliary rotor controls the angle of incidence of at least one of the propeller blades of the main rotor.

2. A helicopter according to claim **1**, wherein the main rotor includes two propeller blades situated essentially in line with each other.

3. A helicopter according to claim **1** or **2**, wherein the propeller blades of the main rotor, the vanes of the auxiliary rotor respectively, are substantially rigidly connected to each other and the joint of the main rotor is formed of a spindle which is fixed transversally to the rotor shaft of the main rotor and which is directed essentially transversally to the axis of the oscillatory shaft of the auxiliary rotor.

4. A helicopter according to claim **3**, wherein the spindle of the main rotor extends essentially in the longitudinal direction of the propeller blade of the main rotor which is parallel to one of the vanes or is located at an acute angle relative to the longitudinal direction.

5. A helicopter according to claim **1** wherein the mechanical link includes a rod hinge mounted to a vane of the auxiliary rotor with one fastening point and is hinge-mounted with another fastening point to the propeller blade of the main rotor which is parallel to one of the vanes or is at an acute angle relative to the blade.

6. A helicopter according to claim **5**, wherein the fastening point of the rod is situated on the main rotor at a distance from the axis of the spindle of the propeller blades of the main rotor, and the other fastening point of the rod is situated on the auxiliary rotor at a distance from the axis of the oscillatory shaft of the auxiliary rotor.

7. A helicopter according to claim **6** wherein the distance between the fastening point of the rod on the main rotor and the axis of the spindle of the propeller blades of the main rotor is larger than the distance between the fastening point

of the rod on the auxiliary rotor and the axis of the oscillatory shaft of the auxiliary rotor.

8. A helicopter according to claim **6** or **7** wherein the distance between the fastening point of the rod on the main rotor and the axis of the spindle of the propeller blades of the main rotor is about the double the distance between the other fastening point on the auxiliary rotor and the axis of the oscillatory shaft of the auxiliary rotor.

9. A helicopter according to claim **5** wherein the rod is fixed to lever arms with its fastening point respectively part of the main rotor and of the auxiliary rotor.

10. A helicopter according to claim **1** wherein the longitudinal axis of the vanes of the auxiliary rotor in the sense of rotation is located within an angle of about 10 degrees with the longitudinal axis of one of the propeller blades of the main rotor

11. A helicopter according to claim **1** wherein the longitudinal axis of one of the propeller blades of the main rotor in the sense of rotation, is located at an acute angle with the axis of the spindle of these propeller blades.

12. A helicopter according to claim **1** wherein the diameter of the auxiliary rotor is smaller than the diameter of the main rotor.

13. A helicopter according to claim **1** wherein the auxiliary rotor is provided with stabilizing weights which are fixed respectively to a vane.

14. A helicopter according to claim **1** wherein the tail rotor is supported by a swing with its rotor shaft which can rotate round a swinging shaft which essentially extends according to the longitudinal direction of the body of the helicopter.

15. A helicopter according to claim **14** wherein a sensor determines the relative angular displacement of the swing round the swinging shaft, and this angular displacement is used as an input signal for a microprocessor which controls the drives of the main rotor and of the tail rotor as a function of a stabilizer algorithm.

16. A helicopter according to claim **15** wherein the sensor includes a magnet fixed to the swing and of a magnetic sensor which is fixed opposite the pendulum path of the magnet on the tail of the helicopter.

17. A helicopter according to any one of claims **14** to **16** wherein between the swing and the tail there is provided a spring which keeps the swing in rest in a central position.

18. A helicopter comprising a body with a tail; a rotor with propeller blades which is driven by a rotor shaft and which is mounted on this rotor shaft, such that the angle between the plane of rotation of the rotor and the rotor shaft may vary; a tail rotor which is driven by a second rotor shaft directed transversally to the rotor shaft of the main rotor, wherein the tail rotor is supported by a swing with its rotor shaft which can rotate round a swinging shaft which essentially extends according to the longitudinal direction of the body of the helicopter.

19. A helicopter according to claim **18** wherein a sensor determines the relative angular displacement of the swing round the swinging shaft, and this angular displacement is used as an input signal for a microprocessor which controls the drives of the main rotor and of the tail rotor as a function of a stabilizer algorithm.

20. A helicopter according to claim **19** wherein the sensor includes a magnet fixed to the swing and of a magnetic sensor which is fixed opposite the pendulum path of the magnet on the tail of the helicopter.

21. A helicopter according to any one of claims **18** to **20** wherein between the swing and the tail there is provided a spring which keeps the swing in rest in a central position.

22. A helicopter comprising a body with a tail; a main rotor with propeller blades which is driven by a rotor shaft and which is mounted on this rotor shaft, such that the angle between the plane of rotation of the main rotor and the rotor shaft may vary; a tail rotor which is driven by a second rotor shaft directed transversally to the rotor shaft of the main rotor, an auxiliary rotor driven by the rotor shaft of the main rotor and provided with two vanes, and the main rotor and the auxiliary rotor being connected to each other by a mechanical link, such that the motion of the auxiliary rotor controls the angle of incidence of at least one of the propeller blades of the main rotor.

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