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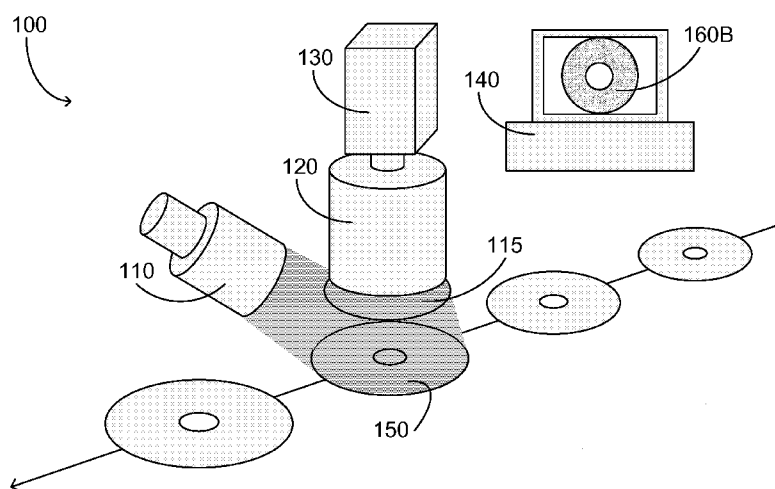


FIG. 1B

(57) **Abstract:** Provided herein is an apparatus, including an optical characterization device; a photon detector array configured to sequentially receive a first set of photons scattered from surface features of an article and a second set of photons scattered from surface features of the article and subsequently processed by the optical characterization device; and a chemical characterization means for chemically characterizing the surface features of the article, wherein the chemical characterization means is configured for processing the first set of photons received by the photon detector array and the second set of photons received by the photon detector array.



CHEMICAL CHARACTERIZATION OF SURFACE FEATURES

CROSS REFERENCE

[0001] This application claims the benefit of U.S. Provisional Patent Application No. 61/710,350, filed October 5, 2012.

BACKGROUND

[0002] An article fabricated on a production line may be inspected for certain features, including defects that might degrade the performance of the article or a system comprising the article. For example, a hard disk for a hard disk drive may be fabricated on a production line and inspected for certain surface features, including surface and subsurface defects that might degrade the performance of the disk or the hard disk drive. Accordingly, apparatuses and methods operable to inspect articles for features such as defects are merited.

SUMMARY

[0003] Provided herein is an apparatus, including an optical characterization device; a photon detector array configured to sequentially receive a first set of photons scattered from surface features of an article and a second set of photons scattered from surface features of the article and subsequently processed by the optical characterization device; and a chemical characterization means for chemically characterizing the surface features of the article, wherein the chemical characterization means is configured for processing the first set of photons received by the photon detector array and the second set of photons received by the photon detector array.

[0004] These and other features and aspects of the concepts presented herein may be better understood with reference to the following drawings, description, and appended claims.

DRAWINGS

[0005] Fig. 1A provides a schematic illustrating detection of surface features of articles in accordance with an embodiment.

[0006] Fig. 1B provides a schematic illustrating detection of surface features of articles in accordance with an embodiment.

[0007] Fig. 2 provides a schematic illustrating photon scattering from a surface feature of an article in accordance with an embodiment.

[0008] Fig. 3 provides a schematic illustrating photons scattering from a surface feature of an article, through an optical component, and onto a photon detector array in accordance with an embodiment.

[0009] Fig. 4 provides an image of a surface features map of an article in accordance with an embodiment.

[0010] Fig. 5 provides a close-up image of the surface features map provided in Fig. 4.

[0011] Fig. 6A (top) provides a close-up image of the surface feature from the map provided in Fig. 5, and Fig. 6A (bottom) provides a photon scattering intensity distribution of the surface feature.

[0012] Fig. 6B (top) provides a pixel-interpolated image of the surface feature from Fig. 6A, and Fig. 6B (bottom) provides a pixel-interpolated photon scattering intensity distribution of the surface feature.

DESCRIPTION

[0013] Before some particular embodiments are described in greater detail, it should be understood by persons having ordinary skill in the art that the particular embodiments described and/or illustrated herein do not limit the concepts presented herein, as elements in such particular embodiments may vary. It should likewise be understood that a particular embodiment described and/or illustrated herein has elements which may be readily separated from the particular embodiment and optionally combined with any of several other embodiments or substituted for elements in any of several other embodiments described herein.

[0014] It should also be understood by persons having ordinary skill in the art that the terminology used herein is for the purpose of describing some particular embodiments, and the terminology does not limit the concepts presented herein. Unless indicated otherwise, ordinal numbers (e.g., first, second, third, etc.) are used to distinguish or identify different elements or steps in a group of elements or steps, and do not supply a serial or numerical limitation. For example, "first," "second," and "third" elements or steps of embodiments need not necessarily appear in that order, and embodiments need not necessarily be limited to the three elements or steps. It should also be understood that, unless indicated otherwise, any labels such as "left," "right," "front," "back," "top," "bottom," "forward," "reverse," "clockwise," "counter clockwise," "up," "down," or other similar terms such as "upper," "lower," "aft," "fore," "vertical," "horizontal," "proximal," "distal," and the like are used for convenience and are not intended to imply, for example, any particular fixed location, orientation, or direction. Instead, such labels are used to reflect, for example, relative location, orientation, or directions. It should also be understood that the singular forms of "a," "an," and "the" include plural references unless the context clearly dictates otherwise.

[0015] Unless defined otherwise, all technical and scientific terms used herein have the same meaning as commonly understood by persons of ordinary skill in the art.

[0016] An article fabricated on a production line may be inspected for certain features, including defects that might degrade the performance of the article or a system comprising the article. For example, a hard disk for a hard disk drive may be fabricated on a production line and inspected for certain surface features, including surface and subsurface defects that might degrade the performance of the disk or the hard disk drive. Provided herein are apparatuses and methods for inspecting articles to detect, map, and/or characterize certain surface features such as surface and/or subsurface defects. Some embodiments will now be described in greater detail.

[0017] With respect to articles that may be inspected with apparatuses and methods herein, such articles include any article of manufacture or a workpiece thereof in any stage of manufacture having one or more optically smooth surfaces, examples of which include, but are not limited to, semiconductor wafers, magnetic

recording media (e.g., hard disks for hard disk drives), and workpieces thereof in any stage of manufacture. Such articles may be inspected for certain surface features, including surface and/or subsurface defects that might degrade the performance of the article, which surface and/or subsurface defects include particle and stain contamination, as well as defects including scratches and voids. In order to characterize the foregoing features, which is an important step in root cause failure analysis, a number of analyses on different analytical apparatuses is typically required, including optical analysis and subsequent analysis using, for example, one or more of atomic force microscopy (AFM), scanning electron microscopy (SEM)/Energy Dispersive X-Ray (EDX); and Raman spectroscopy. The number of analyses on different analytical apparatuses, and the time required for each analysis can be very time consuming, which limits throughput in root cause failure analysis. The apparatuses and methods provided herein for inspecting articles to detect, map, and/or characterize certain surface features reduces the number of different analytical apparatuses and the time required for each analysis, which increases throughput for root cause failure analysis.

[0018] Figs. 1A and 1B, in combination, provide schematics for detecting, mapping, and/or characterizing surface features of articles, illustrating an apparatus 100 comprising a photon emitter 110, an optical characterization device 115, an optical setup 120, a photon detector array 130, and a computer or equivalent device 140, as well as an article 150 and a pair of differential surface features maps 160A and 160B of a surface of the article 150 in accordance with an embodiment. In such an embodiment, the photon detector array 130 may be positioned to receive a first set of photons (originally emitted from the photon emitter 110) scattered from surface features of the article for surface features map 160A, and the photon detector array 130 may be positioned to receive a second set of photons (originally emitted from the photon emitter 110B) scattered from surface features of the article and subsequently processed by the optical characterization device 115 for surface features map 160B. Differential surface features maps 160A and 160B, or the information sufficient to produce surface features maps 160A and 160B, may be used to chemically characterize surface features of articles and differentiate such surface features. Articles and apparatuses, as well as methods, are not limited to the

embodiments in Figs. 1A and 1B, as additional embodiments may be realized by the features described in more detail herein.

[0019] An apparatus for detecting, mapping, and/or characterizing surface features of articles may comprise a single photon emitter (e.g., see photon emitters 110) or a plurality of photon emitters. In some embodiments, for example, the apparatus may comprise at least 1, 2, 3, 4, 5, 6, 7, 8, 9, or 10 photon emitter(s). In some embodiments, for example, the apparatus may comprise no more than 10, 9, 8, 7, 6, 5, 4, 3, 2, or 1 photon emitter(s). Combinations of the foregoing may also be used to describe the number of photon emitters of the apparatus. In some embodiments, for example, the apparatus may comprise at least 2 photon emitters and no more than 10 photon emitters (e.g., between 2 and 10 photon emitters), such as at least 2 photon emitters and no more than 6 photon emitters (e.g., between 2 and 6 photon emitters), including at least 2 photon emitters and no more than 4 photon emitters (e.g., between 2 and 4 photon emitters). A single photon emitter may be used to emit photons onto a surface of an article, such as the entire surface of the article or some predetermined portion of the surface of the article (e.g., for gradational rotation of the article for piecewise inspection, if desired); each photon emitter of a plurality of photon emitters may be used to emit photons onto the surface of the article, such as the entire surface of the article or some predetermined portion of the surface of the article, at different times and/or at the same time in any collection. Further with respect to the plurality of photon emitters, each photon emitter of a plurality of photon emitters may be the same or different, or some combination thereof (e.g., at least 2 of the same photon emitter, with the remainder of photon emitters being different; at least 4 of the same photon emitter, with the remainder of photon emitters being different; etc.).

[0020] Whether the apparatus comprises a single photon emitter or a plurality of photon emitters, each photon emitter may emit photons onto a surface of an article at a distance and/or an angle optimized for one or more types of features, which types of features are described in more detail herein. The angle optimized for one or more types of features may be equal to the glancing angle, which glancing angle is the complement of the angle of incidence, and which angle of incidence is the angle between a ray comprising the emitted photons incident on the surface of the article and the normal (i.e., a line perpendicular to the surface of the article) at the point at

which the ray is incident. The glancing angle may also be described as the angle between a ray comprising the emitted photons incident on the surface of the article and the surface at the point at which the ray is incident.

[0021] Fig. 2 provides a number of rays comprising emitted photons incident on a surface 152 of an article 150 that form a glancing angle with the surface 152. Fig. 2 further provides a number of rays comprising reflected photons that form an angle of reflection with the normal to the surface, which angle of reflection is equal to the angle of incidence, as well as a number of rays comprising scattered photons from a feature 154 on the surface 152 of the article 150, which rays comprising scattered photons form various scatter angles. A photon emitter may emit photons at a glancing angle ranging from 0° to 90° , wherein a glancing angle of 0° represents the photon emitter emitting photons onto the surface of the article from a side of the article, and wherein a glancing angle of 90° represents the photon emitter emitting photons onto the surface of the article from directly above the article. In some embodiments, for example, a photon emitter may emit photons onto a surface of an article such that the glancing angle is at least 0° , 5° , 10° , 15° , 20° , 25° , 30° , 35° , 40° , 45° , 50° , 55° , 60° , 65° , 70° , 75° , 80° , 85° , or 90° . In some embodiments, for example, a photon emitter may emit photons onto a surface of an article such that the glancing angle is no more than 90° , 85° , 80° , 75° , 70° , 65° , 60° , 55° , 50° , 45° , 40° , 35° , 30° , 25° , 20° , 15° , 10° , 5° , or 0° . Combinations of the foregoing may also be used to describe the glancing angle at which a photon emitter may emit photons onto a surface of an article. In some embodiments, for example, a photon emitter may emit photons onto a surface of an article such that the glancing angle is at least a 0° and no more than 90° (i.e., between 0° and 90°), such as least 0° and no more than 45° (i.e., between 0° and 45°), including at least 45° and no more than 90° (i.e., between 45° and 90°).

[0022] A photon emitter may emit photons onto a surface of an article, such as the entire surface or some predetermined portion of the surface (e.g., for gradational rotation of the article for piecewise inspection, if desired). The photon emitter may further emit photons onto the entire surface of the article or some predetermined portion of the surface such that the entire surface or the predetermined portion of the surface is uniformly or homogeneously illuminated. Uniformly illuminating the entire surface of the article or some predetermined portion of the surface includes, but is

not limited to, subjecting the entire surface of the article or some predetermined portion of the surface of the article to the same or about the same photon energy per unit time (e.g., photon power or photon flux) and/or photon power per unit area (e.g., photon flux density). In radiometric terms, uniformly illuminating includes, but is not limited to, subjecting the entire surface of the article or some predetermined portion of the surface of the article to the same or about the same radiant energy per unit time (e.g., radiant power or radiant flux) and/or radiant power per unit area (e.g., irradiance or radiant flux density).

[0023] With the appreciation that photons are the elementary particles of electromagnetic radiation or light, a photon emitter or light source may provide light comprising a relatively wide range of wavelengths (e.g., whole spectrum, ultraviolet-visible, visible, infrared, etc.), a relatively narrow range of wavelengths (e.g., a subdivision of ultraviolet such as UVA, UVB, UVC, etc.; a subdivision of visible such as red, green, blue, etc.; a subdivision of infrared such as near infrared, mid-infrared; etc.), or a particular wavelength (e.g., monochromatic); light comprising a relatively wide range of frequencies (e.g., whole spectrum, ultraviolet-visible, visible, infrared, etc.), a relatively narrow range of frequencies (e.g., a subdivision of ultraviolet such as UVA, UVB, UVC, etc.; a subdivision of visible such as red, green, blue, etc.; a subdivision of infrared such as near infrared, mid-infrared; etc.), or a particular frequency (e.g., monochromatic); polarized (e.g., linear polarization, circular polarization, etc.) light, partially polarized light, or nonpolarized light; and/or light with different degrees of temporal and/or spatial coherence ranging from coherent light (e.g., laser) to noncoherent light. A photon emitter or light source may be used in conjunction with one or more optical components of an optical setup to provide light having any of the foregoing qualities. Wavelength filters, for example, may be used in conjunction with a photon emitter or light source to provide light comprising a relatively wide range of wavelengths or frequencies, a relatively narrow range of wavelengths or frequencies, or a particular wavelength or frequency. Polarization filters, for example, may also be used in conjunction with a photon emitter or light source to provide light of a desired polarization including polarized light, partially polarized light, or nonpolarized light.

[0024] In view of the foregoing, a photon emitter or light source may comprise a lamp such as a flash lamp, including a high-speed flash lamp, configured to minimize

vibration while detecting photons scattered from surface features of an article with a photon detector array. In some embodiments, for example, a photon emitter or light source may comprise a high-speed Xe flash lamp such as a 500 W Xe flash lamp to minimize vibration while detecting photons scattered from surface features of an article with a photon detector array.

[0025] Also in view of the foregoing, a photon emitter or light source may comprise a collimated light source such as a laser, including a combination of lasers, configured to emit photons onto a surface of an article at one or more angles. In some embodiments, for example, a combination of lasers may be provided to a laser beam shaper such that the combination of lasers emits photons onto a surface of an article at one angle. In some embodiments, for example, a combination of lasers may be provided to a laser beam shaper such that the combination of lasers emits photons onto a surface of an article at multiple angles. In some embodiments, for example, at least 2, 4, 6, 8, 10, 12, 14, 16, 18, 20, 22, 24, 26, 28, or 30 lasers, or even more than 30 lasers, may be provided to a laser beam shaper such that the combination of lasers emits photons onto a surface of an article at one or more angles. In some embodiments, for example, no more than 30, 28, 26, 24, 22, 20, 18, 16, 14, 12, 10, 8, 6, 4, or 2 lasers may be provided to a laser beam shaper such that the combination of lasers emits photons onto a surface of an article at one or more angles. Combinations of the foregoing may also be used to describe combinations of lasers provided to a laser beam shaper. In some embodiments, for example, at least 2 lasers and no more than 30 lasers (e.g., between 2 and 30 lasers), such as at least 10 lasers and no more than 30 lasers (e.g., between 10 and 30 lasers), including at least 20 lasers and no more than 30 lasers (e.g., between 20 and 30 lasers), and further including at least 24 lasers and no more than 28 lasers (e.g., between 24 and 28 lasers) may be provided to a laser beam shaper such that the combination of lasers emits photons onto a surface of an article of an article at one or more angles.

[0026] Further in view of the foregoing, a photon emitter or light source may comprise a two-dimensional light source such as a combination of point light sources, including a linear combination, an arcuate combination, etc. of point light sources configured to emit photons onto a surface of an article. In some embodiments, for example, a two-dimensional light source may comprise a combination of at least 10, 20, 40, 60, 80, 100, 110, 120, 140, 160, 180, or 200 point

light sources, or even more than 200 point sources. In some embodiments, for example, a two-dimensional light source may comprise a combination of no more than 200, 180, 160, 140, 120, 100, 80, 60, 40, 20, or 10 point light sources. Combinations of the foregoing may also be used to describe two-dimensional light sources comprising combinations of point light sources. In some embodiments, for example, a two-dimensional light source may comprise a combination of at least 10 and no more than 200 (e.g., between 10 and 200) point light sources, such as at least 40 and no more than 160 (e.g., between 40 and 160) point light sources, including at least 60 and no more than 140 (e.g., between 60 and 140) point light sources, and further including at least 80 and no more than 120 (e.g., between 80 and 120) point light sources. Such point light sources may be linearly combined to form a two-dimensional light source such as a strip light. Such point light sources may be arcuately combined to form a two-dimensional light source such as a ring light. In some embodiments, for example, a photon emitter or light source may comprise a two-dimensional light source comprising at least 60 point light sources, such as a ring light comprising at least 60 point light sources, including a ring light comprising at least 60 light-emitting diodes ("LEDs"), and further including a ring light comprising at least 100 LEDs. A two-dimensional light source comprising LEDs may comprise white LEDs, wherein each LED has a power of at least 10 mW. An LED-based ring light may enhance features such as scratches (e.g., circumferential scratches) and/or voids in surfaces of articles, especially when the LED-based ring light is configured to emit photons onto the surfaces of the articles with lower angles (e.g., glancing angle equal to or less than 45°).

[0027] The apparatus may further comprise an optical setup (e.g., see optical setup 120 of Figs. 1A and 1B), which optical setup may manipulate photons emitted from one or more photon emitters and/or photons scattered from surface features of articles. With the appreciation that photons are the elementary particles of electromagnetic radiation or light, the optical setup may manipulate light emitted from one or more photon emitters and/or light scattered from surface features of articles. The optical setup up may comprise any of a number of optical components placed in the optical path before an article such that the optical components may be used to manipulate photons emitted from one or more photon emitters before uniformly or homogenously illuminating the entire surface or the predetermined portion of the

surface of the article. Alternatively, or in addition, the optical setup up may comprise any of a number of optical components placed in the optical path after an article such that the optical components may be used to manipulate photons scattered from surface features of the article. When any of a number of optical components is placed in the optical path after an article to manipulate photons scattered from surface features of the article, the optical components may be further used to characterize surface features of the article, such as chemically characterize surface features of the article. Optical components used to characterize surface features of an article may be further described herein as optical characterization devices. The forgoing optical components, including optical characterization devices, may include, but are not limited to, optical components such as lenses, filters, gratings, and mirrors.

[0028] With respect to optical components such as lenses, the optical setup may comprise a single lens or a plurality of lenses, including, but not limited to, a combination of a lens coupled to a photon detector array (e.g., photon detector array 130 of Figs. 1A and 1B) for collecting and detecting photons scattered from surface features of an article. The lens coupled to the photon detector array may be an objective lens, such as a telecentric lens, including an object-space telecentric lens (i.e., entrance pupil at infinity), an image-space telecentric lens (i.e., exit pupil at infinity), or a double telecentric lens (i.e., both pupils at infinity). Coupling a telecentric lens to a photon detector array reduces errors with respect to the position of surface features of articles, reduces distortion of surface features of articles, and/or enables quantitative analysis of photons scattered from surface features of articles, which quantitative analysis includes integration of photon scattering intensity distribution for size determination of surface features of articles. Additional optical components, including optical characterization devices, such as lenses, filters, gratings, and mirrors may be placed in any combination of one or more optical components at or near the entrance pupil of the lens coupled to the photon detector array, at or near the exit pupil of the lens coupled to the photon detector array (i.e., inbetween the exit pupil of the lens and the photon detector array), or some combination thereof. In some embodiments, for example, an optical characterization filter may be placed at or near the entrance pupil of a telecentric lens coupled to the photon detector array. In some embodiments, for example, an optical

characterization filter may be placed at or near the exit pupil of a telecentric lens coupled to the photon detector array.

[0029] With respect to optical components such as filters, the optical setup may comprise a filter or a plurality of filters including, but not limited to, wavelength filters, band-pass filters, polarization filters, coherence filters, and phase filters. When one or more of such filters is placed in the optical path after an article to manipulate photons scattered from surface features of the article, the one or more filters may be further used to extract chemical signatures from surface features of the article and/or to characterize surface features of the article, such as chemically characterize surface features of the article. As described herein with reference to Figs. 1A and 1B, surface features map 160A may be produced from a first set of photons scattered from surface features of the article, and surface features map 160B may be produced from a second set of photons scattered from surface features of the article and subsequently processed by an optical characterization device 115 such as actively filtered by a wavelength filter, a band-pass filter, a polarization filter, a coherence filter, and/or a phase filter. Differential surface features maps 160A and 160B, or the information sufficient to produce surface features maps 160A and 160B, may be used (e.g., contrasted) to characterize (e.g., chemically characterize) surface features of articles and differentiate such surface features. Optionally, a surface features map comprising chemically characterized surface features of articles may be subsequently produced from surface features maps 160A and 160B, or the information sufficient to produce surface features maps 160A and 160B. In practice, any of a number of differential surface features maps (e.g., 160A, 160B, 160C...160 n , wherein the index n indicates the n^{th} surface features map) or the information sufficient to produce such surface features maps may be used to effect the foregoing, and the filters may be used in any serial combination to do so.

[0030] One or more wavelength filters or band-pass filters may be used to filter photons scattered from surface features of an article by wavelength in order to differentiate surface features known to differentially scatter photons with respect to wavelength. A wavelength filter or band-pass filter may be absent from an optical setup for a first run of an optical analysis (e.g., used to produce surface features map 160A) of an article, and the wavelength filter or band-pass filter may be placed at or near the entrance pupil or exit pupil of a telecentric lens coupled to a photon detector

array for actively filtering by wavelength for a second run of the optical analysis (e.g., used to produce surface features map 160B) of the article. For any subsequent runs of the optical analysis (e.g., used to produce surface features maps 160C...160 n , wherein the index n indicates the n^{th} surface features map) of the article, the wavelength filter or band-pass filter from the previous run may be removed and a different wavelength filter may be placed at or near the entrance pupil or exit pupil of a telecentric lens coupled to the photon detector array for actively filtering by wavelength. Alternatively, a piezoelectric-tunable wavelength filter may be placed at or near the entrance pupil or exit pupil of a telecentric lens coupled to a photon detector array for each run of the optical analysis of the article. While photons scattered from surface features of the article may pass through the piezoelectric-tunable wavelength filter for the first run of the optical analysis (e.g., used to produce surface features map 160A) of the article, the piezoelectric-tunable wavelength filter may be configured to allow all wavelengths of light, most wavelengths of light, or all wavelengths of light pertinent to the immediate optical analysis to pass through. For any subsequent runs of the optical analysis (e.g., used to produce surface features maps 160B...160 n , wherein the index n indicates the n^{th} surface features map) of the article, the piezoelectric-tunable wavelength filter may be tuned to one or more different wavelengths for actively filtering by wavelength.

[0031] In view of the foregoing, for example, a first run of an optical analysis of an article may be performed using a relatively wide range of wavelengths to provide surface features map 160A, which provides positional information for each of the surface features of the article. A second run of the optical analysis of the article may be performed using the same relatively wide range of wavelengths, a relatively narrow range of wavelengths (e.g., 488-514.5 nm), or a particular wavelength (e.g., 488 nm), as described herein with respect to photon emitters, but a wavelength filter may be tuned or placed at or near the entrance pupil or exit pupil of the telecentric lens coupled to the photon detector array for actively filtering by a chosen wavelength to provide surface features map 160B. To distinguish between crystalline silicon and diamond-like carbon in the second run of the optical analysis, for example, a wavelength filter that blocks wavelengths below 1400 nm may be used, which wavelength filter would block Raman scattering by crystalline silicon, leaving Raman scattering by diamond-like carbon. Any subsequent runs of the optical

analysis of the article to chemically characterize additional species may be performed using the same relatively wide range of wavelengths, the same relatively narrow range of wavelengths (e.g., 488-514.5 nm), or the same particular wavelength (e.g., 488 nm) as the second run of the optical analysis, but the wavelength filter may be tuned again or another wavelength filter may be placed at or near the entrance pupil or exit pupil of the telecentric lens coupled to the photon detector array for actively filtering by a different chosen wavelength to provide additional surface features maps (e.g., 160C...160 n , wherein the index n indicates the n^{th} surface features map). Differential surface features maps from three different runs of the optical analysis of the article may be used, for example, to distinguish between crystalline silicon, diamond-like carbon, and magnesium oxide.

[0032] One or more polarization filters may be used to filter photons scattered from surface features of an article by polarization in order to differentiate surface features known to differentially scatter photons with respect to polarization. A polarization filter may be absent from an optical setup for a first run of an optical analysis (e.g., used to produce surface features map 160A) of an article, and the polarization filter (e.g., quartz crystal polarization filter having different thicknesses) may be placed at or near the entrance pupil or exit pupil of a telecentric lens coupled to a photon detector array for actively filtering by polarization for a second run of the optical analysis (e.g., used to produce surface features map 160B) of the article. For any subsequent runs of the optical analysis (e.g., used to produce surface features maps 160C...160 n , wherein the index n indicates the n^{th} surface features map) of the article, the polarization filter from the previous run may be removed and a different polarization filter may be placed at or near the entrance pupil or exit pupil of a telecentric lens coupled to the photon detector array for actively filtering by wavelength. Alternatively, a piezoelectric-tunable polarization filter (e.g., polarization filter having liquid crystal-based technology) may be placed at or near the entrance pupil or exit pupil of a telecentric lens coupled to a photon detector array for each run of the optical analysis of the article. While photons scattered from surface features of the article may pass through the piezoelectric-tunable polarization filter for the first run of the optical analysis (e.g., used to produce surface features map 160A) of the article, the piezoelectric-tunable polarization filter may be configured to allow nonpolarized light, linearly polarized light, circularly polarized light, or polarized light

of a particular orientation to pass through. For any subsequent runs of the optical analysis (e.g., used to produce surface features maps 160B...160n, wherein the index n indicates the n^{th} surface features map) of the article, the piezoelectric-tunable polarization filter may be tuned to one or more different wavelengths for actively filtering by wavelength.

[0033] In view of the foregoing, for example, a first run of an optical analysis of an article may be performed using nonpolarized light to provide surface features map 160A, which provides positional information for each of the surface features of the article. A second run of the optical analysis of the article may be performed using the same nonpolarized light, but a polarization filter may be tuned or placed at or near the entrance pupil or exit pupil of the telecentric lens coupled to the photon detector array for actively filtering by polarization to provide surface features map 160B. To determine the presence of magnesium oxide in the second run of the optical analysis, for example, a polarization filter that either allows or blocks light polarized in a certain orientation may be used. Any subsequent runs of the optical analysis of the article to determine the presence of a chemical species or distinguish between chemical species (e.g., diamond-like carbon and magnesium oxide) may be performed using the same nonpolarized light, but the polarization filter may be tuned again or another polarization filter may be placed at or near the entrance pupil or exit pupil of the telecentric lens coupled to the photon detector array for actively filtering by a different chosen polarization to provide additional surface features maps (e.g., 160C...160n, wherein the index n indicates the n^{th} surface features map). Actively filtering by the different chosen polarization may include rotating the polarization field a set number of degrees (e.g., every 1°, 2°, 3°, 5°, 10°, etc.) to provide additional surface features maps, which may be used to determine various surface features comprising oxides, higher oxides, ferroelectric materials, small metal particles, and/or materials having high dipole moments or high polarizability.

[0034] One or more coherence filters may be used to filter photons scattered from surface features of an article by coherence in order to differentiate surface features known to differentially scatter photons with respect to coherence. A coherence filter may be absent from an optical setup for a first run of an optical analysis (e.g., used to produce surface features map 160A with noncoherent photons/light) of an article, and the coherence filter may be placed at or near the entrance pupil or exit pupil of a

telecentric lens coupled to a photon detector array for actively filtering by coherence for a second run of the optical analysis (e.g., used to produce surface features map 160B with noncoherent or coherent photons/light) of the article. For any subsequent runs of the optical analysis (e.g., used to produce surface features maps 160C...160 n , wherein the index n indicates the n^{th} surface features map) of the article, the coherence filter from the previous run may be removed and a different coherence filter may be placed at or near the entrance pupil or exit pupil of a telecentric lens coupled to the photon detector array for actively filtering by coherence. Actively filtering by coherence may be used to determine between organic and inorganic surface features, as organic surface features exhibit noncoherent scattering of photons while inorganic surface features exhibit either noncoherent or coherent scattering of photons. Actively filtering by coherence may be further used to determine between various inorganic surface features, as various inorganic surface features differentially scatter photons with respect to coherence.

[0035] One or more phase filters or waveplates may be used to filter photons scattered from surface features of an article by phase in order to differentiate surface features known to differentially scatter photons with respect to phase. Such one or more phase filters or waveplates, optionally with one or more additional optical components as described herein, may be used to contrast photons/light scattered from surface features of the article with incident photons/light to determine any phase shifts, which phase shifts may subsequently be used in conjunction with other, known properties (e.g., wavelength, period, etc.) of the incident photons/light to determine time constants for retransmission of the photons/light for surface features of the article. A phase filter or waveplate may be absent from an optical setup for a first run of an optical analysis (e.g., used to produce surface features map 160A with noncoherent photons/light) of an article, and the phase filter or waveplate may be placed at or near the entrance pupil or exit pupil of a telecentric lens coupled to a photon detector array for actively filtering by phase for a second run of the optical analysis (e.g., used to produce surface features map 160B with noncoherent photons/light) of the article. For any subsequent runs of the optical analysis (e.g., used to produce surface features maps 160C...160 n , wherein the index n indicates the n^{th} surface features map) of the article, the phase filter or waveplate from the previous run may be removed and a different phase filter or waveplate may be

placed at or near the entrance pupil or exit pupil of a telecentric lens coupled to the photon detector array for actively filtering by phase.

[0036] To detect photons scattered from surface features of articles, an apparatus may further comprise a single photon detector array (e.g., see photon detector array 130 of Figs. 1A and 1B) comprising a plurality of photon detectors or a plurality of photon detector arrays, each comprising a plurality of photon detectors. In some embodiments, for example, the plurality of photon detector arrays may comprise at least 2, 3, 4, 5, 6, 7, 8, 9, or 10 photon detector arrays. In some embodiments, for example, the plurality of photon detector arrays may comprise no more than 10, 9, 8, 7, 6, 5, 4, 3, or 2 photon detector arrays. Combinations of the foregoing may also be used to describe the plurality of photon detector arrays. In some embodiments, for example, the plurality of photon detector arrays may comprise at least 2 photon detector arrays and no more than 10 photon detector arrays (e.g., between 2 and 10 photon detector arrays), such as at least 2 photon detector arrays and no more than 5 photon detector arrays (e.g., between 2 and 5 photon detector arrays). Further with respect to the plurality of photon detector arrays, each photon detector array of the plurality of photon detector arrays may be the same or different, or some combination thereof (e.g., at least 2 of the same photon detector array, with the remainder of photon detector arrays being different; at least 3 of the same photon detector array, with the remainder of photon detector arrays being different; etc.).

[0037] Whether the apparatus comprises a single photon detector array or a plurality of photon detector arrays, each photon detector array may be oriented to detect photons scattered from surface features of an article at a distance and/or an angle for an optimum acceptance of photons (e.g., maximum acceptance of photons with minimum background noise) scattered from one or more types of features, which types of features are described in more detail herein. Likewise, a photon detector array and lens (e.g., telecentric lens) combination may be oriented to collect and detect photons scattered from surface features of an article at a distance and/or an angle for an optimum acceptance of photons scattered from one or more types of features. Such an angle may be the angle between a ray comprising the center line axis of the photon detector array and/or the lens extended to the surface of the article and the normal (i.e., a line perpendicular to the surface of the article) at the point at which the ray is extended. The angle, optionally in combination with an

aperture that may be optimally sized for maximum acceptance of photons with minimum background noise, may allow for acceptance of scattered photons having a plurality of scatter angles, which scattered photons may be scattered from one or more types of features. A scatter angle may be different than the angle of reflection, which angle of reflection is equal to the angle of incidence as described herein. Fig. 2 provides a number of rays comprising photons scattered from a feature 154 on a surface 152 of an article 150, which rays represent various scatter angles.

[0038] Further with respect to the foregoing aperture, the aperture of a photon detector array may be used to filter photons scattered from surface features of an article by varying the size of the aperture to accept a larger or smaller angle of scattered photons. The aperture may be sized for maximum acceptance of photons for a first run of an optical analysis (e.g., used to produce surface features map 160A) of an article, and the aperture may be more narrowly sized for a second run of the optical analysis (e.g., used to produce surface features map 160B) of the article. For any subsequent runs of the optical analysis (e.g., used to produce surface features maps 160C...160 n , wherein the index n indicates the n^{th} surface features map) of the article, the aperture may be successively narrowed for actively filtering by scatter angle of photons scattered from surface features of the article.

[0039] In view of the foregoing, a photon detector array or photon detector array and lens combination may be oriented at an angle ranging from 0° to 90°, inclusive, wherein an angle of 0° represents orientation of the photon detector array or the photon detector array and lens combination at a side of the article, and wherein an angle of 90° represents orientation of the photon detector array or photon detector array and lens combination directly above the article. In some embodiments, for example, a photon detector array or photon detector array and lens combination may be oriented at an angle of at least 0°, 5°, 10°, 15°, 20°, 25°, 30°, 35°, 40°, 45°, 50°, 55°, 60°, 65°, 70°, 75°, 80°, 85°, or 90°. In some embodiments, for example, a photon detector array or photon detector array and lens combination may be oriented at an angle of no more than 90°, 85°, 80°, 75°, 70°, 65°, 60°, 55°, 50°, 45°, 40°, 35°, 30°, 25°, 20°, 15°, 10°, or 5°, or 0°. Combinations of the foregoing may also be used to describe the angle at which the photon detector array or photon detector array and lens combination may be oriented. In some embodiments, for example, a photon detector array or photon detector array and lens combination may be

oriented at an angle of at least a 0° and no more than a 90° (i.e., between 0° and 90°), such as least 0° and no more than 45° (i.e., between 0° and 45°) or at least 45° and no more than 90° (i.e., between 45° and 90°).

[0040] The photon detector array, optionally in combination with a lens (e.g., telecentric lens), may detect photons scattered from surface features of an article, such as the entire surface of the article or some predetermined portion of the surface of the article. The photon detector array, optionally in combination with a lens (e.g., telecentric lens), may detect photons scattered from surface features of an article, such as the entire surface of the article or some predetermined portion of the surface of the article, while oriented at a distance and/or an angle for an optimum acceptance of photons scattered from one or more types of features. As provided herein, the angle for an optimum acceptance of photons scattered from one or more types of features may allow for acceptance of scattered photons having a plurality of scatter angles, which scattered photons may be scattered from one or more types of features.

[0041] With the appreciation that photons are the elementary particles of electromagnetic radiation or light, a photon detector array or light detector array may detect light comprising a relatively wide range of wavelengths (e.g., ultraviolet-visible, visible, infrared, etc.), a relatively narrow range of wavelengths (e.g., a subdivision of ultraviolet such as UVA, UVB, UVC, etc.; a subdivision of visible such as red, green, blue, etc.; a subdivision of infrared such as near infrared, mid-infrared; etc.), or a particular wavelength (e.g., monochromatic); light comprising a relatively wide range of frequencies (e.g., ultraviolet-visible, visible, infrared, etc.), a relatively narrow range of frequencies (e.g., a subdivision of ultraviolet such as UVA, UVB, UVC, etc.; a subdivision of visible such as red, green, blue, etc.; a subdivision of infrared such as near infrared, mid-infrared; etc.), or a particular frequency (e.g., monochromatic); polarized (e.g., linear polarization, circular polarization, etc.) light, partially polarized light, or nonpolarized light; and/or light with different degrees of temporal and/or spatial coherence ranging from coherent light (e.g., laser) to noncoherent light. As discussed herein, a photon detector array or light detector array may be used in conjunction with one or more optical components of an optical setup to detect light having any of the foregoing qualities.

[0042] The photon detector array may comprise a plurality of pixel sensors, which pixel sensors, in turn, may each comprise a photon detector (e.g., a photodiode) coupled to a circuit comprising a transistor configured for amplification. Features of a photon detector array comprising such pixel sensors include, but are not limited to, low temperature operation (e.g., down to -40 °C), low electron noise (e.g., 2-10 e⁻ RMS; 1 e⁻ RMS; < 1 e⁻ RMS; etc.), wide dynamic range (e.g., 30,000:1, 8,500:1; 3,000:1; etc.), and/or decreased photon/light collection time. A photon detector array may comprise a large number of pixel sensors (e.g., ≥ 1,000,000 or ≥ 1M pixel sensors) arranged in rows and columns of a two-dimensional array, wherein each pixel sensor comprises a photon detector coupled to an amplifier. In some embodiments, for example, a photon detector array may comprise at least 1M, 2M, 3M, 4M, 5M, 6M, 7M, 8M, 9M, 10M, or more, pixel sensors arranged in rows and columns of a two-dimensional array. In some embodiments, for example, a photon detector array may comprise no more than 10M, 9M, 8M, 7M, 6M, 5M, 4M, 3M, 2M, or 1M, pixel sensors arranged in rows and columns of a two-dimensional array. Combinations of the foregoing may also be used to describe the number of pixel sensors in a photon detector array. In some embodiments, for example, a photon detector array may comprise at least 1M and no more than 10M (e.g., between 1M and 10M) pixel sensors arranged in rows and columns of a two-dimensional array, such as at least 1M and no more than 8M (e.g., between 1M and 8M) pixel sensors, including at least 1M and no more than 6M (e.g., between 1M and 8M) pixel sensors, further including at least 2M and no more than 6M (e.g., between 1M and 8M) pixel sensors, and even further including at least 2M and no more than 5M (e.g., between 2M and 5M) pixel sensors.

[0043] Due to surface reflections of surface features of articles and/or small angle scattering (e.g., 4π scattering), surface features may appear much larger in size enabling pixel sensors larger than surface features to be used. In some embodiments, for example, a photon detector array may comprise micrometer-sized (i.e., admits of μm units as measured) pixel sensors at least 1 μm, 2 μm, 3 μm, 4 μm, 5 μm, 6 μm, 7 μm, 8 μm, 9 μm, or 10 μm in their smallest dimension. In some embodiments, for example, a photon detector array may comprise micrometer-sized pixel sensors no more than 10 μm, 9 μm, 8 μm, 7 μm, 6 μm, 5 μm, 4 μm, 3 μm, 2 μm, or 1 μm in their smallest dimension. Combinations of the foregoing may also be

used to describe dimensions of micrometer-sized pixel sensors in photon detector arrays. In some embodiments, for example, a photon detector array may comprise micrometer-sized pixel sensors at least 1 μm and no more than 10 μm (e.g., between 1 μm and 10 μm) in their smallest dimension, such as at least 1 μm and no more than 7 μm (e.g., between 1 μm and 7 μm), including at least 4 μm and no more than 10 μm (e.g., between 4 μm and 10 μm), and further including at least 4 μm and no more than 7 μm (e.g., between 4 μm and 7 μm). Such micrometer-sized pixel sensors may be used in the apparatus to detect, map, and/or characterize surface features of articles that are more than 100 times smaller than the micrometer-sized pixel sensors.

[0044] In view of the foregoing, the single photon detector array or the plurality of photon detector arrays may each comprise a complementary metal-oxide semiconductor ("CMOS") or a scientific complementary metal-oxide semiconductor ("sCMOS"), each of which may optionally be part of CMOS camera or a sCMOS camera, respectively. Alternatively, the single photon detector array or the plurality of photon detector arrays may each comprise a charge-coupled device ("CCD"), which may optionally be part of CCD camera. While a CCD-based photon detector array might have a slower recording speed than a CMOS-based or sCMOS-based photon detector array, a CCD-based photon detector array may be desirable in certain applications requiring less electronic and/or image noise. Furthermore, a plurality of photon detector arrays is not limited to combinations of either CMOS/sCMOS-based photon detector arrays or CCD-based photon-detector arrays, as a plurality of photon detector arrays may comprise a combination of any of a number of CMOS/sCMOS-based photon detector arrays and CCD-based photon-detector arrays in certain applications that benefit from employing each type of technology.

[0045] Fig. 3 provides a schematic for detection of surface features of an article, illustrating a close-up, cross-sectional view of an apparatus comprising an optical setup and a photon detector array. As shown, article 150 comprises a surface 152 and at least surface feature 154. Photons emitted from a single photon emitter or a plurality of photon emitters may be scattered by the surface feature 154 and collected and detected by a combination comprising an optical setup 120 coupled to a photon detector array 130, which combination may be placed at a distance and/or an angle for an optimum acceptance of photons (e.g., maximum acceptance of

photons with minimum background noise) scattered from one or more types of features. The optical setup 120, which may comprise a telecentric lens, may collect and focus the photons scattered from the surface feature 154 onto one or more pixel sensors 132 of photon detector array 130, which one or more pixel sensors each comprises a photon detector coupled to an amplifier. The one or more pixel sensors 132, each of which corresponds to a particular, fixed area on an article's surface and a pixel in a map of the article's surface features, may provide one or more signals to a computer or equivalent device for mapping or otherwise determining the position of the surface feature 154 as shown, for example, in Fig. 6A, which is a close-up image of the map of surface features provided in Fig. 5, which, in turn, is a close-up image of the map of surface features provided in Fig. 4. The computer or equivalent device may subsequently use pixel interpolation for further mapping the surface feature 154 as shown in Fig. 6B.

[0046] The apparatus may further comprise one or more computers or equivalent devices (e.g., devices that include primary and/or secondary memory and one or more processing elements operable to carry out arithmetic and logical operations), including, but not limited to, servers, workstations, desktop computers, nettops, laptops, netbooks, and mobile devices such as tablets and smartphones, which computers or equivalent devices may contain application-specific integrated circuits ("ASIC"s), field-programmable gate arrays ("FPGA"s), etc. The computers or equivalent devices may include a computer-readable storage medium for instructions making the apparatus operable to, but not limited to, convey each article to the apparatus for inspection; position each article for inspection, optionally including gradational rotation of the article for piecewise inspection; hold or otherwise maintain the position of each article for inspection; insert optical components into the optical setup; position optical components for inspection; adjust and/or tune optical components (e.g., piezoelectric-based filters) for inspection; remove optical components from the optical setup; move each photon emitter into position for inspection, wherein the position for inspection may include a photon emitter-article distance and/or angle (e.g., glancing angle) optimized for one or more types of features; switch each photon emitter on and off, or otherwise between modes for emitting photons and not emitting photons; move each photon detector array into position for inspection, wherein the position for inspection may include a photon

detector array-article distance and/or angle (e.g., scatter angle) optimized for one or more types of features; switch each photon detector array on and off, or otherwise between modes for detecting photons and not detecting photons; process photon detector array signals, optionally including pixel interpolation for better accuracy (e.g., 10x better than pixel size) with respect to the position of surface features; map or otherwise determine the position of surface features of articles from photon detector array signals or processed photon detector array signals (e.g., photon scattering intensity distributions); quantitatively and/or qualitatively characterize surface features of articles, as described herein; catalog surface features of articles; and determine trends with respect to surface features of articles.

[0047] The apparatus may be operable to detect, map, and/or characterize surface features of articles that are nanometer-sized (i.e., admits of nm units as measured) or smaller in their smallest dimension (e.g., length, width, height, or depth, depending on the surface feature), which features may be smaller than the wavelength of photons emitted from a photon emitter of the apparatus. However, the apparatus is not limited to detecting, mapping, and/or characterizing surface features of articles that are nanometer-sized or smaller, as the apparatus may be operable to detect, map, and/or characterize surface features of articles that are micrometer-sized (i.e., admits of μm units as measured) or larger. In some embodiments, for example, the apparatus may be operable to detect, map, and/or characterize surface features of articles smaller than 500 nm, 250 nm, 200 nm, 150 nm, 125 nm, 110 nm, 100 nm, 90 nm, 80 nm, 70 nm, 60 nm, 50 nm, 40 nm, 30 nm, 20 nm, 10 nm, or 1 nm (10 Å) in their smallest dimension, or even smaller, such as surface features of articles smaller than 9 Å, 8 Å, 7 Å, 6 Å, 5 Å, 4 Å, 3 Å, 2 Å, or 1 Å in their smallest dimension. In view of the foregoing, the apparatus may be operable to, in some embodiments, for example, detect, map, and/or characterize surface features of articles between 0.1 nm and 1000 nm, such as between 0.1 nm and 500 nm, including between 0.1 nm and 250 nm, and further including between 0.1 nm and 100 nm, and even further including between 0.1 nm and 80 nm.

[0048] The apparatus may be operable to detect, map, and/or characterize certain features, including surface and/or subsurface defects comprising particle contamination in which the particles are nanometer-sized (i.e., admits of nm units as measured) or smaller in their smallest dimension (e.g., length, width, or height). In

some embodiments, for example, the apparatus may be operable to detect, map, and/or characterize surface and/or subsurface particles smaller than 125 nm, such as smaller than 100 nm, including smaller than 80 nm, and further including smaller than 10 nm in their smallest dimension. Detecting, mapping, and/or characterizing surface and/or subsurface particles down to the level of 10 nm in height is important for hard disks of hard disk drives, as particles greater than 10 nm in height (e.g., from the surface) may corrupt the spacing between the hard disk and the read-write head of a hard disk drive. In some embodiments, for example, the apparatus may be operable to detect, map, and/or characterize surface and/or subsurface particles as small as or smaller than 4 nm in height.

[0049] The apparatus may be operable to detect, map, and/or characterize certain features, including surface and/or subsurface defects comprising scratches (e.g., circumferential scratches) that are micrometer-sized (i.e., admits of μm units as measured) or smaller, such as nanometer-sized (i.e., admits of nm units as measured) or smaller, such as angstrom-sized (i.e., admits of $\text{\AA}$ units as measured) or smaller, in their smallest dimension (e.g., length, width, or depth). With respect to micrometer-sized scratches, the apparatus may be operable to detect, map, and/or characterize scratches from, for example, 1 μm to 1000 μm in length, which may be significantly longer than the wavelength of photons emitted from a photon emitter of the apparatus. In some embodiments, for example, the apparatus may be operable to detect, map, and/or characterize surface features such as defects comprising scratches smaller than 1000 μm , such as smaller than 500 μm , including smaller than 250 μm , further including smaller than 100 μm , and even further including smaller than 50 μm in scratch length. With respect to nanometer-sized scratches, the apparatus may be operable to detect, map, and/or characterize scratches from, for example, 1 nm to 500 nm in scratch width. In some embodiments, for example, the apparatus may be operable to detect, map, and/or characterize surface features such as defects comprising scratches smaller than 500 nm, such as smaller than 250 nm, including smaller than 100 nm, further including smaller than 50 nm, and even further including smaller than 15 nm in scratch width. Surprisingly, due to a high level of spatial coherence, the apparatus may be operable to detect, map, and/or characterize angstrom-sized scratches with respect to scratch depth. In some embodiments, for example, the apparatus may be operable to detect, map, and/or

characterize surface features such as defects comprising scratches smaller than 50 Å, such as smaller than 25 Å, including smaller than 10 Å, further including smaller than 5 Å, and even further including smaller than 1 Å (e.g., 0.5 Å) in scratch depth. For example, the apparatus may be operable to detect, map, and/or characterize surface features such as defects comprising scratches smaller than 500 μm in length, smaller than 100 nm in width, and smaller than 50 Å in depth.

[0050] The apparatus may be operable to accurately and/or precisely map or otherwise determine the position of a feature on an article's surface (e.g., Figs. 6A (top) and 6B (top)). With respect to accuracy, the apparatus may be operable to map or otherwise determine the position of a feature on an article's surface within a micrometer-sized (i.e., admits of μm units as measured) radius or better. In some embodiments, for example, the apparatus may be operable to accurately map or otherwise determine the position of a feature on an article's surface within a radius of 100 μm, 90 μm, 80 μm, 70 μm, 60 μm, 50 μm, 40 μm, 30 μm, 20 μm, 10 μm, 9 μm, 8 μm, 7 μm, 6 μm, 5 μm, 4 μm, 3 μm, 2 μm, or 1 μm, or better. Combinations of the foregoing may also be used to describe the accuracy with which the apparatus may map or otherwise determine the position of a feature on an article's surface. In some embodiments, for example, the apparatus may be operable to accurately map or otherwise determine the position of a feature on an article's surface within a radius ranging from 1 μm to 100 μm, such as from 1 μm to 50 μm, including from 1 μm to 30 μm, and further including from 5 μm to 10 μm.

[0051] In addition to accurately and/or precisely mapping or otherwise determining the position of a feature on a surface of an article, the apparatus may be operable to accurately and/or precisely determine the photon scattering intensity distribution (e.g., Figs. 6A (bottom) and 6B (bottom)) of the feature on the surface of the article. Such a photon scattering intensity distribution may be used to characterize a surface feature of an article both quantitatively and qualitatively.

[0052] With respect to quantitative characterization of a surface feature of an article, mathematical integration of a photon scattering intensity distribution provides the size (e.g., volume) of the surface feature of the article. Quantitative characterization of a surface feature of an article may further include a determination of surface feature position on the article as described herein. Quantitative characterization may even further include the total number of surface features per

article, as well as the number of each type of surface feature on the article. Such characterization information may be cataloged across a plurality of articles and be used to correct manufacturing trends should such features include surface and/or subsurface defects that might degrade the performance of the article.

[0053] With respect to qualitative characterization of a surface feature of an article, qualitative characterization may include a determination of the type of surface feature (e.g., particle, stain, scratch, void, etc.) of the article, which determination may be effected by, but is not limited to, analysis of photon scattering intensity distributions. Qualitative characterization may further include distinguishing between surface features (e.g., organic vs. inorganic) based on one or more chemical signatures and/or determining chemical types of surface features by one or more chemical signatures, wherein chemical signatures include, but are not limited to, scattering photons/light at one or more wavelengths; scattering photons/light in one or more polarization orientations; scattering photons/light noncoherently or coherently with different degrees of temporal and/or spatial coherence; and scattering photons/light in phase or out of phase with incident photons/light. The foregoing chemical signatures produced using one or more optical characterization devices may provide the information, part of the information, or otherwise be incorporated for producing differential maps described herein, such as differential surface features maps 160A and 160B of Figs. 1A and 1B. As such, in some embodiments, for example, qualitative characterization of one or more surface features of an article may comprise contrasting photon/light-scattering information in the effective absence of an optical characterization device with photon/light-scattering information using one or more optical characterization devices or contrasting a first surface features map produced in the effective absence of an optical characterization device with a second surface features map (or a plurality of surface features maps) produced using one or more optical characterization devices. Along with quantitative characterization information, such qualitative characterization information may be cataloged across a plurality of articles and be used to correct manufacturing trends should such features include surface and/or subsurface defects that might degrade the performance of the article.

[0054] Depending upon factors that may include the type of article, the type of surface features, and the like, it may be desirable at times to increase the number of

photons (e.g., photon energy) emitted from a single photon emitter or a plurality of photon emitters to provide an increased scattering signal for detecting, mapping, and/or characterizing surface features of articles. Such an increase in photon energy may be with respect to unit time for increased photon power or photon flux, or with respect to unit area for increased photon flux density. Alternately, or in addition, it may be desirable to increase detection time of a single photon detector array or a plurality of photon detector arrays to detect more photons for detecting, mapping, and/or characterizing surface features of articles. Alternately to one or both of increasing the photon energy or detection time, or in addition to increasing the photon energy and detection time, it may be desirable at times to minimize background noise including stray light from one or more photon emitters, background light, and/or background fluorescent radiation.

[0055] The apparatus described herein may be configured to process or inspect articles at a rate greater than or commensurate with the rate at which the articles or workpieces thereof are produced. In some embodiments, for example, the apparatus may be configured to process or inspect articles at a rate of at least 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 12, 14, 16, 18, or 20 article(s) per second, which rate may be commensurate with the rate at which the articles or workpieces thereof are produced. In some embodiments, for example, the apparatus may be configured to process or inspect articles at a rate of no more than 20, 18, 16, 14, 12, 10, 9, 8, 7, 6, 5, 4, 3, 2, or 1 article(s) per second, which rate may be commensurate with the rate at which the articles or workpieces thereof are produced. Combinations of the foregoing may also be used to describe the rate at which the articles or workpieces thereof are processed or inspected by the apparatus. In some embodiments, for example, the apparatus may be configured to process or inspect at least 1 and no more than 20 articles per second (e.g., between 1 and 20 articles per second), such as at least 1 and no more than 10 articles per second (e.g., between 1 and 10 articles per second), including at least 1 and no more than 5 articles per second (e.g., between 1 and 5 articles per second). Processing or inspecting articles at rates greater than or commensurate with the rate at which the articles or workpieces thereof are produced is a function of many features of the apparatus described herein, including, but not limited to, photon emitters and/or articles that need not be moved (e.g., for scanning) during processing or inspecting. For example, an article

such as a hard disk of a hard disk drive need not be rotated during processing or inspecting. As such, the apparatus may be configured to hold an article stationary while emitting photons onto the surface of the article.

[0056] The apparatus described herein may be fully automated and function in different modes, including, but not limited to, an ultrafast mode, an ultrasensitive mode, and ultrasensitive plus mode. With respect to the ultrafast mode, the apparatus may operate at least 200 times faster than other optical surface analyzers (e.g., KLA-Tencor Candela CS10 or CS20), detect surface features such as defects comprising embedded particles down to at least 100 nm, partially detect surface features such as defects comprising scratches (e.g., nanometer-sized scratches), and provide measurements of roughness. With respect to the ultrasensitive mode, the apparatus may operate at least 50 times faster than other optical surface analyzers, detect surface features such as defects comprising embedded particles down to at least 30 nm, and provide measurements of roughness. With respect to the ultrasensitive plus mode, the apparatus may operate at least 20 times faster than other optical surface analyzers, detect surface features such as defects comprising embedded particles down to at least 30 nm, fully detect surface features such as defects comprising scratches (e.g., nano-scratches), and provide measurements of roughness.

[0057] As such, provided herein is an apparatus, comprising a photon emitter configured to sequentially emit at least a first set of photons and a second set of photons onto a surface of an article; an optical characterization device; a photon detector array configured to sequentially receive the first set of photons scattered from surface features of the article and the second set of photons scattered from surface features of the article and subsequently processed by the optical characterization device; and a chemical characterization means for chemically characterizing the surface features of the article, wherein the chemical characterization means is configured for processing the first set of photons received by the photon detector array and the second set of photons received by the photon detector array. In some embodiments, the apparatus further comprises a telecentric lens coupled to the photon detector array. In some embodiments, the optical characterization device is selected from the group consisting of lenses, filters, gratings, mirrors, and combinations thereof. In some embodiments, the optical

characterization device comprises a filter. In some embodiments, the optical characterization device comprises a filter selected from the group consisting of wavelength filters, band-pass filters, polarization filters, coherence filters, and phase filters. In some embodiments, processing the first set of photons received by the photon detector array and the second set of photons received by the photon detector array comprises producing a first map from the first set of photons and producing a second map from the second set of photons. In some embodiments, the first map provides positional information for the surface features of the article, and the second map provides chemical information for the surface features of the article, optionally by contrast with the first map. In some embodiments, the chemical characterization means comprises one or more computers or equivalent devices loaded with instructions operable to chemically characterize the surface features of the article.

[0058] Also provided herein is an apparatus, comprising a photon emitter configured to sequentially emit at least a first set of photons and a second set of photons onto a surface of an article; a filter; a photon detector array configured to sequentially receive the first set of photons scattered from surface features of the article and the second set of photons scattered from surface features of the article and subsequently filtered by the filter; and a chemical characterization means for chemically characterizing the surface features of the article, wherein the chemical characterization means is configured for analyzing a first map produced from the first set of photons received by the photon detector array and a second map produced from the second set of photons received by the photon detector array. In some embodiments, the apparatus further comprises a telecentric lens coupled to the photon detector array. In some embodiments, the filter is selected from the group consisting of wavelength filters, band-pass filters, polarization filters, coherence filters, and phase filters. In some embodiments, the first map provides positional information for the surface features of the article, and the second map provides chemical information for the surface features of the article, optionally by contrast with the first map. In some embodiments, the chemical characterization means comprises one or more computers or equivalent devices loaded with instructions operable to chemically characterize the surface features of the article.

[0059] Also provided herein is an apparatus, comprising an optical characterization device; a photon detector array configured to sequentially receive a

first set of photons scattered from surface features of an article and a second set of photons scattered from surface features of the article and subsequently processed by the optical characterization device; and a chemical characterization means for chemically characterizing the surface features of the article, wherein the chemical characterization means is configured for processing the first set of photons received by the photon detector array and the second set of photons received by the photon detector array. In some embodiments, the apparatus further comprises one or more photon emitters configured to sequentially emit the first set of photons and the second set of photons onto the surface of the article. In some embodiments, the apparatus further comprises a telecentric lens coupled to the photon detector array. In some embodiments, the optical characterization device is selected from the group consisting of lenses, filters, gratings, mirrors, and combinations thereof. In some embodiments, the optical characterization device comprises a filter selected from the group consisting of wavelength filters, band-pass filters, polarization filters, coherence filters, and phase filters. In some embodiments, processing the first set of photons received by the photon detector array and the second set of photons received by the photon detector array provides positional information for the surface features of the article with chemical information for the surface features of the article, respectively. In some embodiments, the chemical characterization means comprises one or more computers or equivalent devices loaded with instructions operable to chemically characterize the surface features of the article.

[0060] While some particular embodiments have been described and/or illustrated herein, and while these particular embodiments have been described and/or illustrated in considerable detail, it is not the intention of the applicant(s) for these particular embodiments to limit the concepts presented herein. Additional adaptations and/or modifications may readily appear to persons having ordinary skill in the art, and, in broader aspects, these adaptations and/or modifications may be encompassed as well. Accordingly, departures may be made from the foregoing embodiments without departing from the scope of the concepts presented herein, which scope is limited only by the following claims when appropriately construed.

CLAIMS

What is claimed is:

1. An apparatus, comprising:

a photon emitter configured to sequentially emit at least a first set of photons
5 and a second set of photons onto a surface of an article;

an optical characterization device;

a photon detector array configured to sequentially receive
the first set of photons scattered from surface features of the article
and

10 the second set of photons scattered from surface features of the article
and subsequently processed by the optical characterization device; and

a chemical characterization means for chemically characterizing the surface
features of the article,

wherein the chemical characterization means is configured for
15 processing the first set of photons received by the photon detector array and the
second set of photons received by the photon detector array.

2. The apparatus of Claim 1, further comprising a telecentric lens coupled to the
photon detector array.

3. The apparatus of either one of Claim 1 or Claim 2, wherein the optical
20 characterization device is selected from a group consisting of lenses, filters, gratings,
mirrors, and combinations thereof.

4. The apparatus of any one of Claims 1-3, wherein the optical characterization
device comprises a filter.

5. The apparatus of any one of Claims 1-4, wherein the optical characterization
25 device comprises a filter selected from a group consisting of wavelength filters,
band-pass filters, polarization filters, coherence filters, and phase filters.

6. The apparatus of any one of Claims 1-5, wherein processing the first set of
photons received by the photon detector array and the second set of photons

received by the photon detector array comprises producing a first map from the first set of photons and producing a second map from the second set of photons.

7. The apparatus of Claim 6, wherein the first map provides positional information for the surface features of the article, and wherein the second map provides chemical information for the surface features of the article, optionally by contrast with the first map.

8. The apparatus of any one of Claims 1-7, wherein the chemical characterization means comprises one or more computers or equivalent devices loaded with instructions operable to chemically characterize the surface features of the article.

9. An apparatus, comprising:

a photon emitter configured to sequentially emit at least a first set of photons and a second set of photons onto a surface of an article;

a filter;

a photon detector array configured to sequentially receive

the first set of photons scattered from surface features of the article and

the second set of photons scattered from surface features of the article and subsequently filtered by the filter; and

a chemical characterization means for chemically characterizing the surface features of the article,

wherein the chemical characterization means is configured for analyzing a first map produced from the first set of photons received by the photon detector array and a second map produced from the second set of photons received by the photon detector array.

10. The apparatus of Claim 9, further comprising a telecentric lens coupled to the photon detector array.

11. The apparatus of either one of Claim 9 or Claim 10, wherein the filter is selected from a group consisting of wavelength filters, band-pass filters, polarization filters, coherence filters, and phase filters.

12. The apparatus of any one of Claims 9-11, wherein the first map provides positional information for the surface features of the article, and wherein the second map provides chemical information for the surface features of the article, optionally by contrast with the first map.

13. The apparatus of any one of Claims 9-12, wherein the chemical characterization means comprises one or more computers or equivalent devices loaded with instructions operable to chemically characterize the surface features of the article.

14. An apparatus, comprising:

an optical characterization device;

a photon detector array configured to sequentially receive

a first set of photons scattered from surface features of an article and

a second set of photons scattered from surface features of the article

and subsequently processed by the optical characterization device; and

a chemical characterization means for chemically characterizing the surface

features of the article,

wherein the chemical characterization means is configured for processing the first set of photons received by the photon detector array and the second set of photons received by the photon detector array.

15. The apparatus of Claim 14, further comprising one or more photon emitters configured to sequentially emit the first set of photons and the second set of photons onto the surface of the article.

16. The apparatus of either one of Claim 14 or Claim 15, further comprising a telecentric lens coupled to the photon detector array.

17. The apparatus of any one of Claims 14-16, wherein the optical characterization device is selected from a group consisting of lenses, filters, gratings, mirrors, and combinations thereof.

18. The apparatus of any one of Claims 14-17, wherein the optical characterization device comprises a filter selected from a group consisting of wavelength filters, band-pass filters, polarization filters, coherence filters, and phase filters.

19. The apparatus of any one of Claims 14-18, wherein processing the first set of photons received by the photon detector array and the second set of photons received by the photon detector array provides positional information for the surface features of the article with chemical information for the surface features of the article, respectively.

20. The apparatus of any one of Claims 14-19, wherein the chemical characterization means comprises one or more computers or equivalent devices loaded with instructions operable to chemically characterize the surface features of the article.

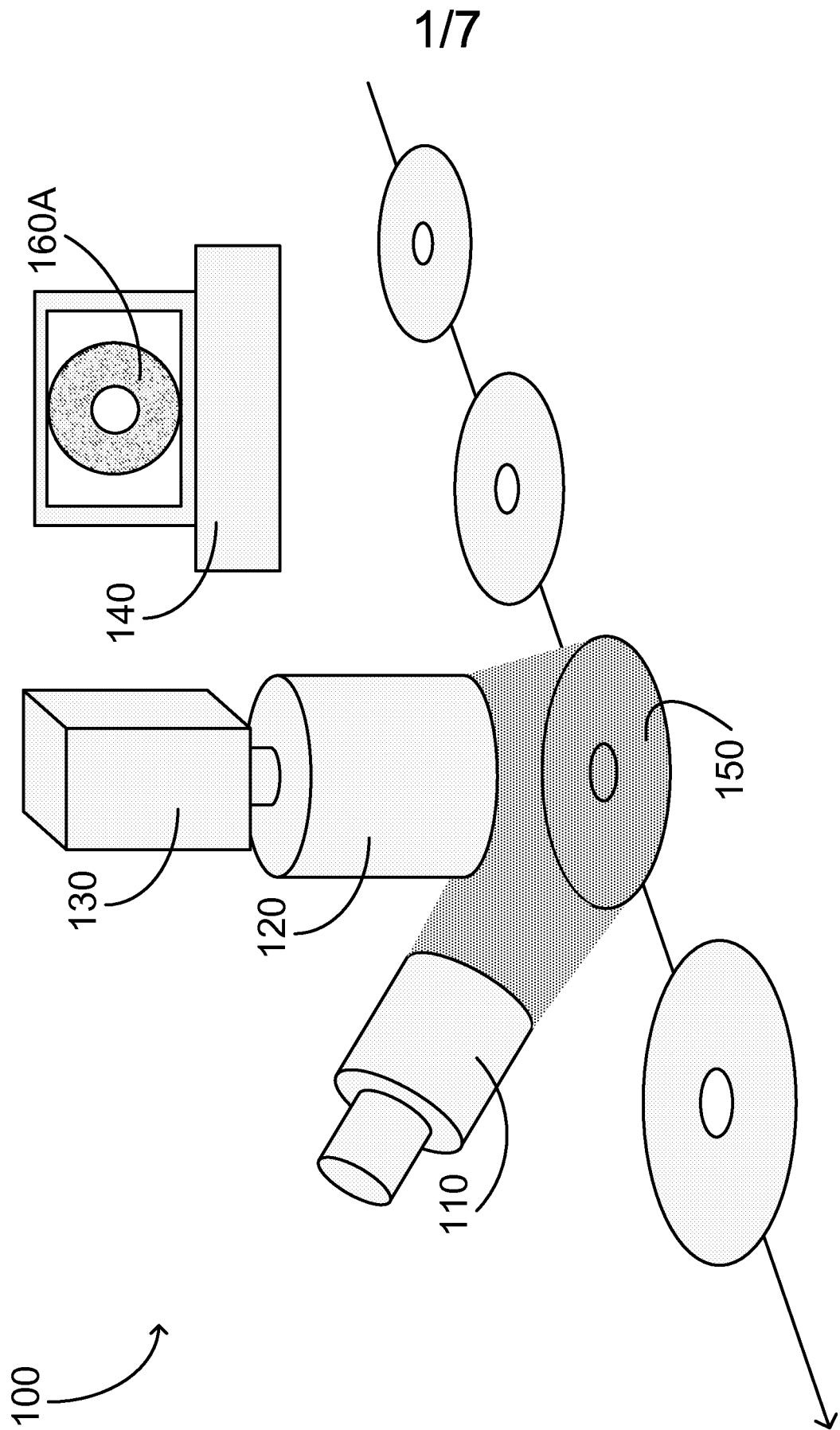


FIG. 1A

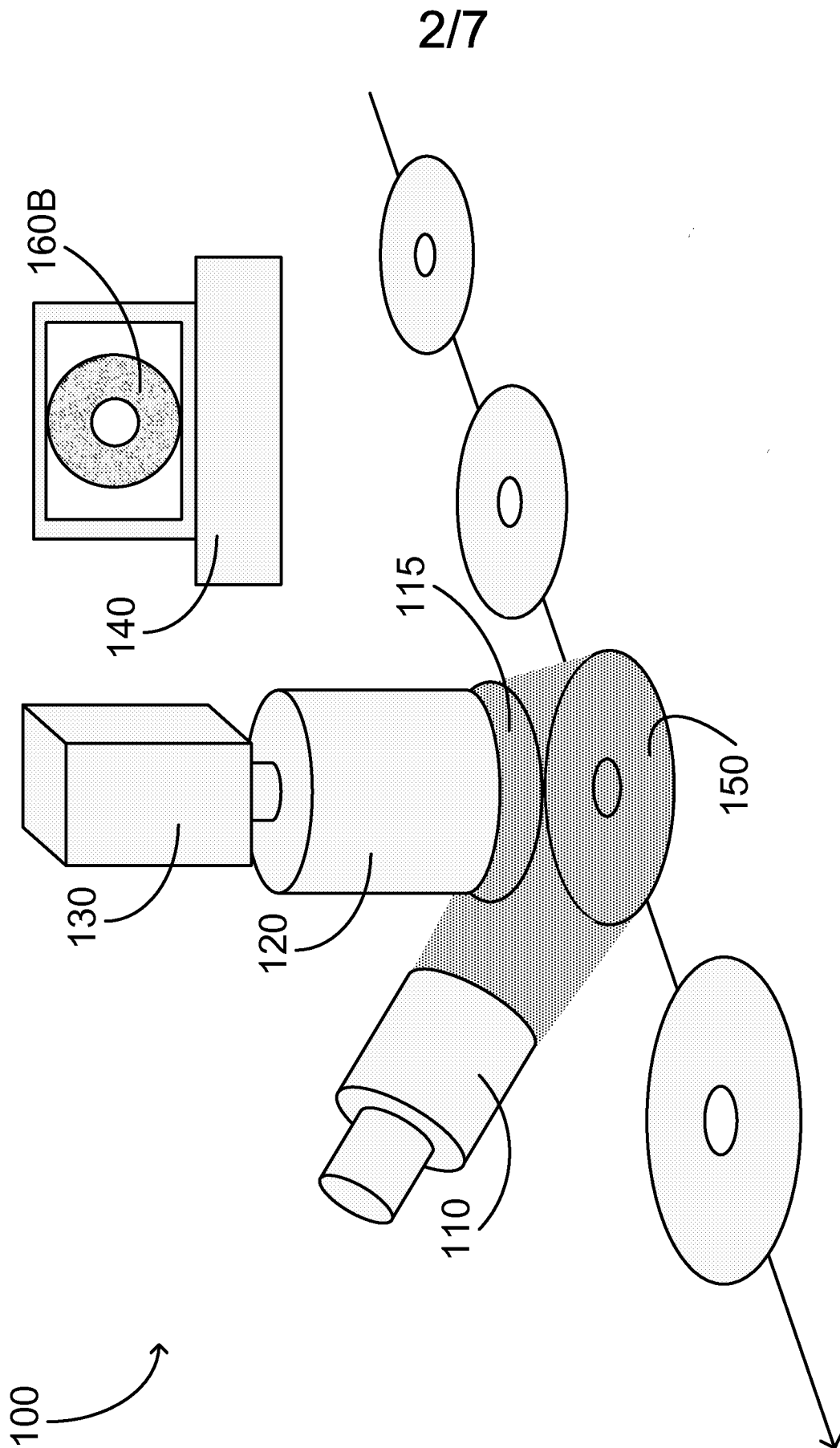


FIG. 1B

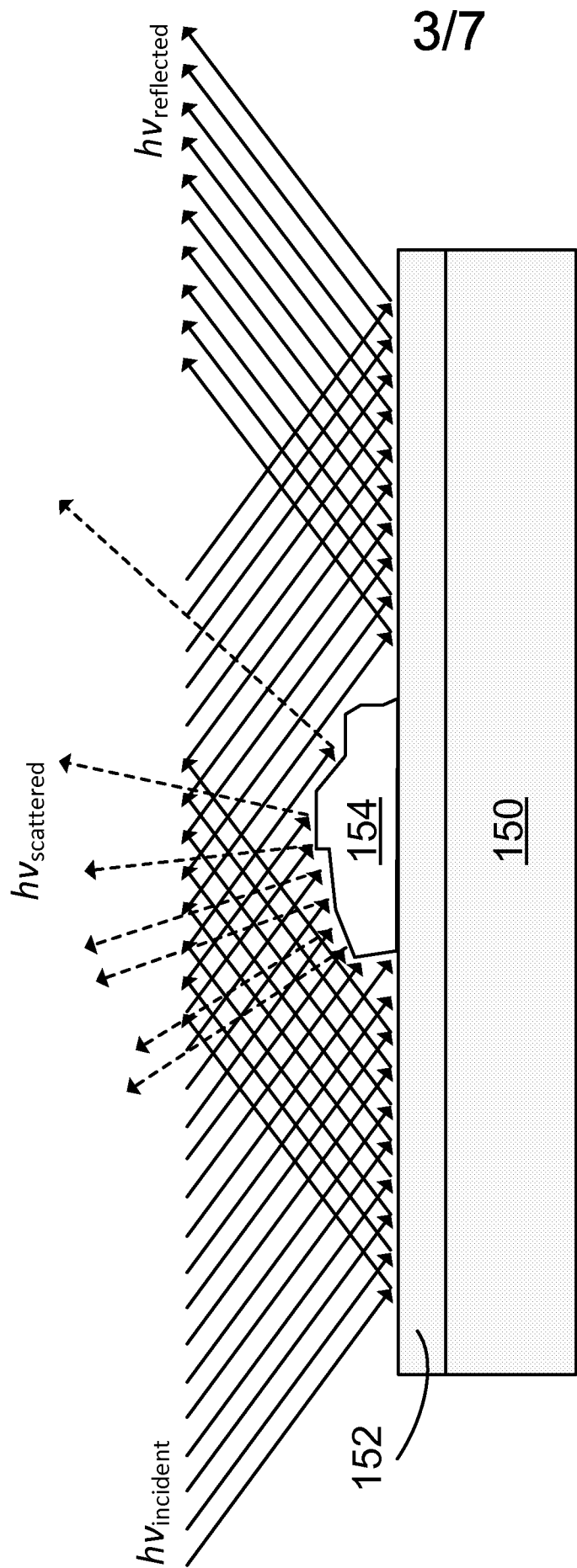


FIG. 2

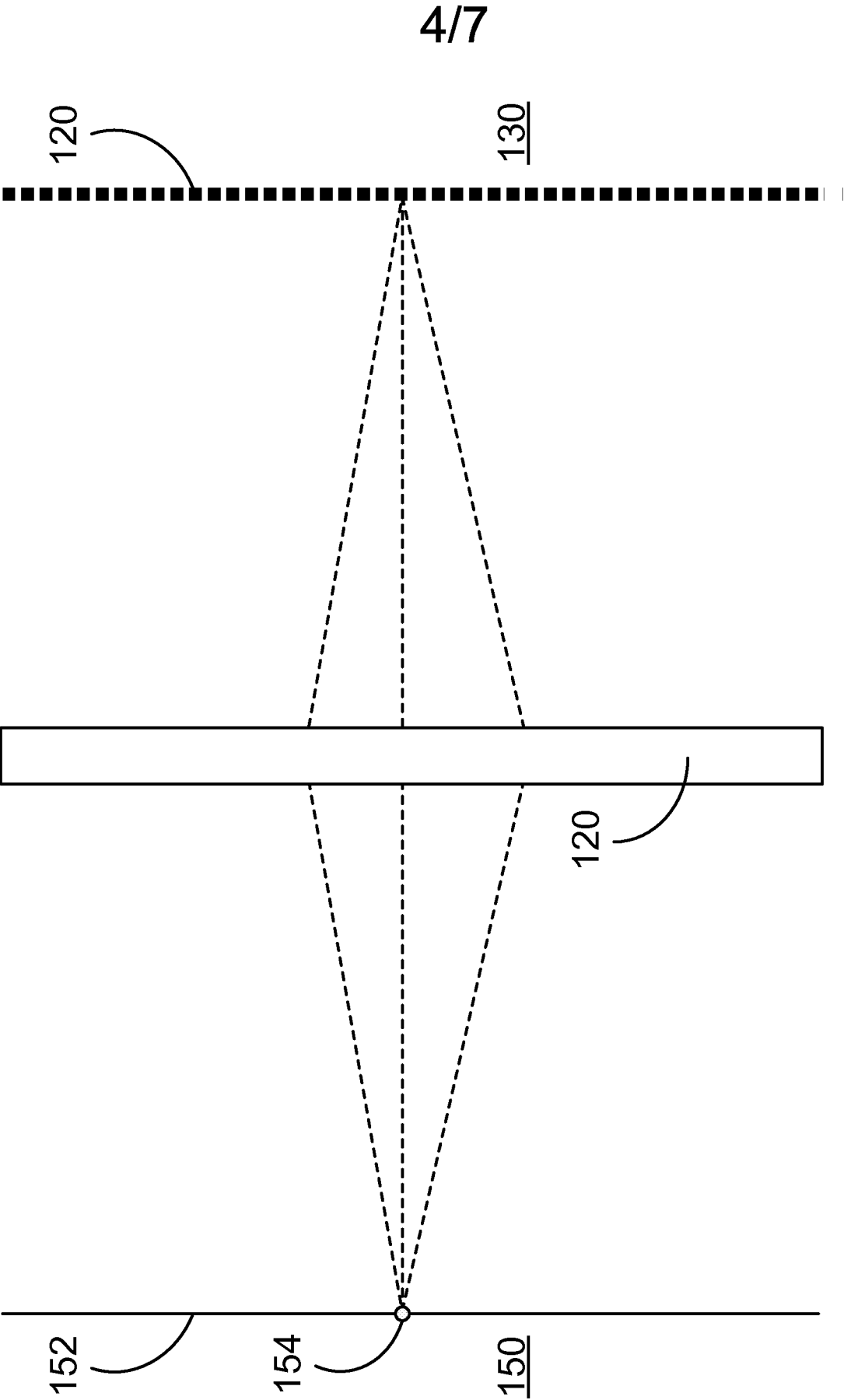


FIG. 3

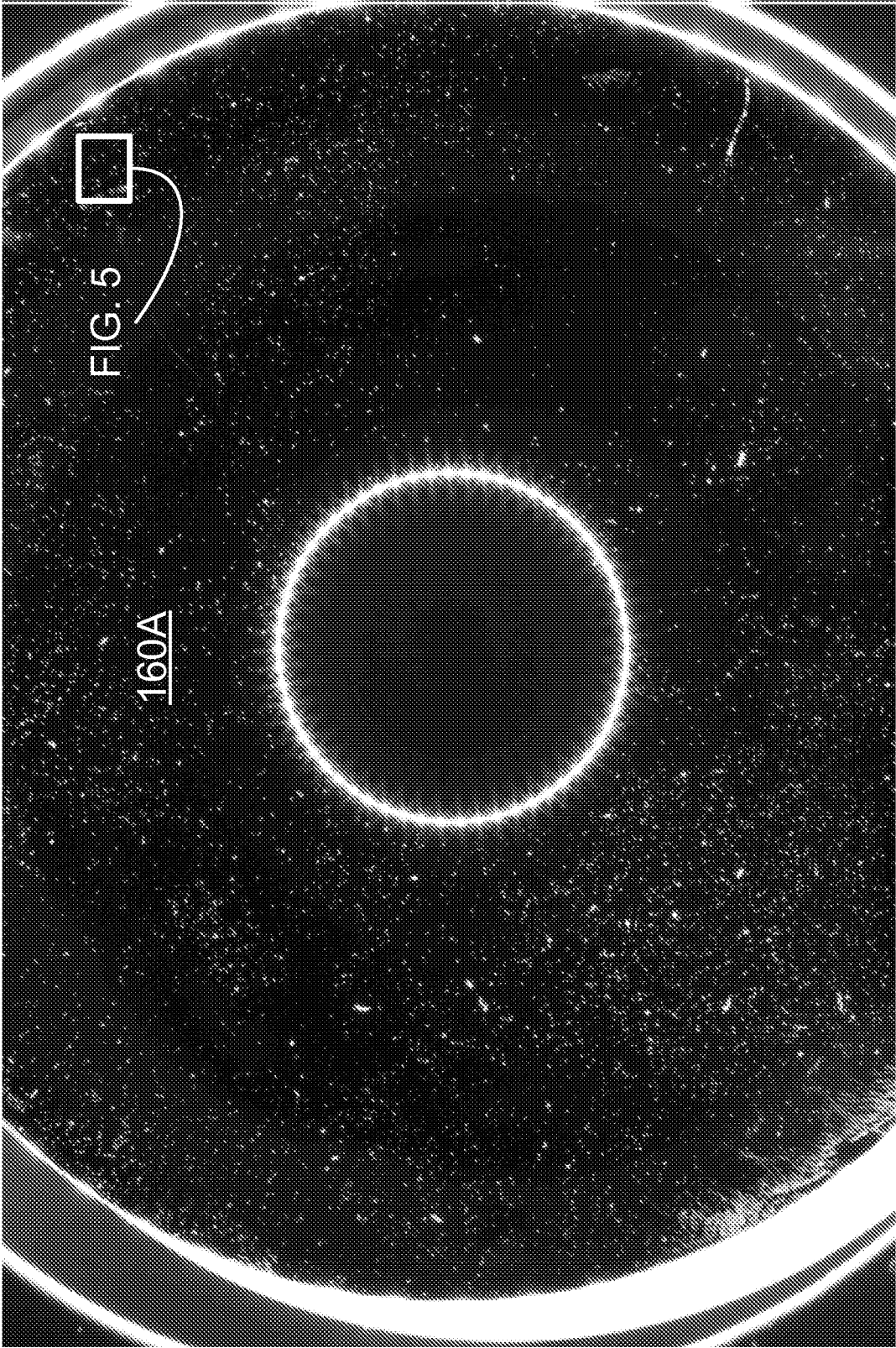


FIG. 4

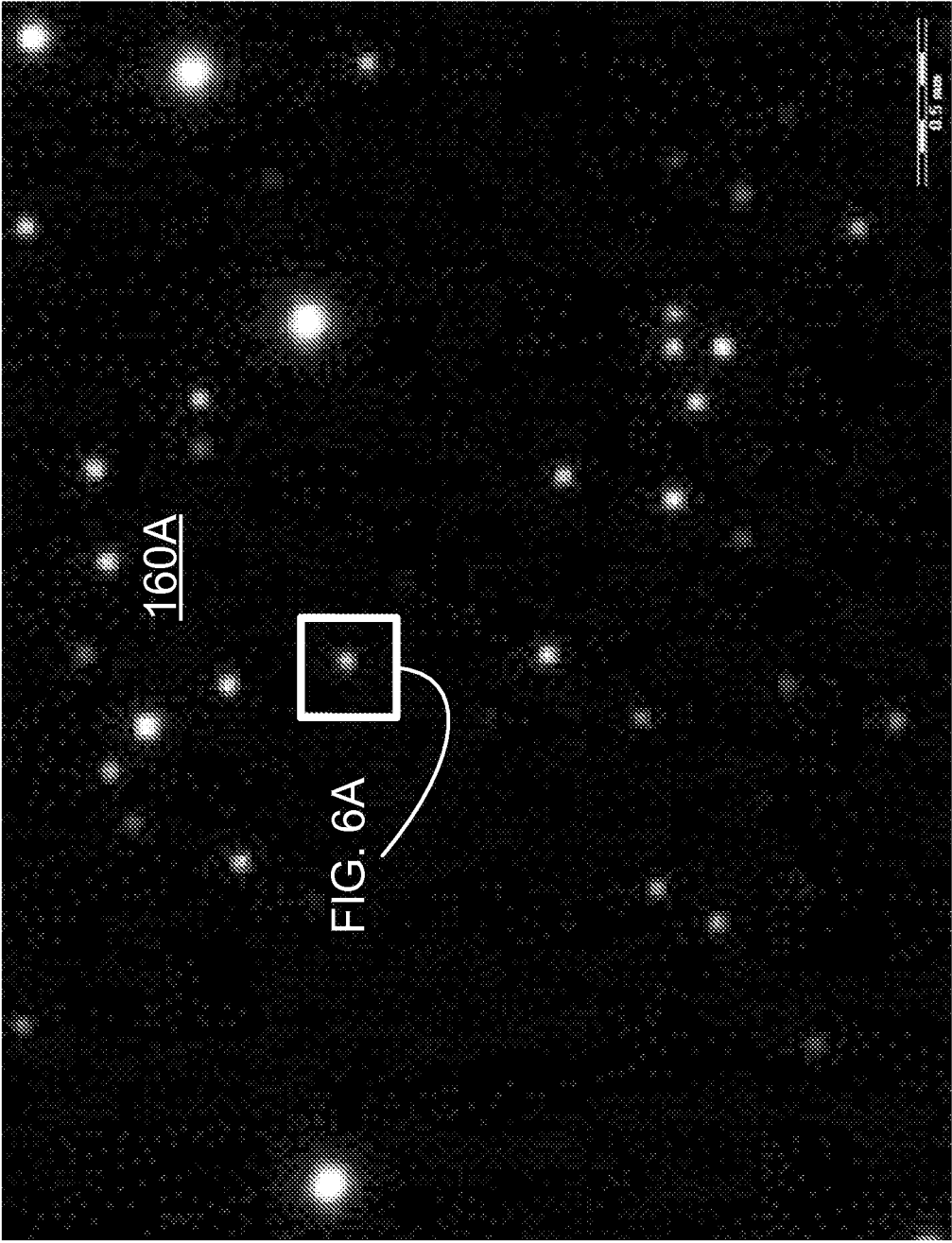


FIG. 5

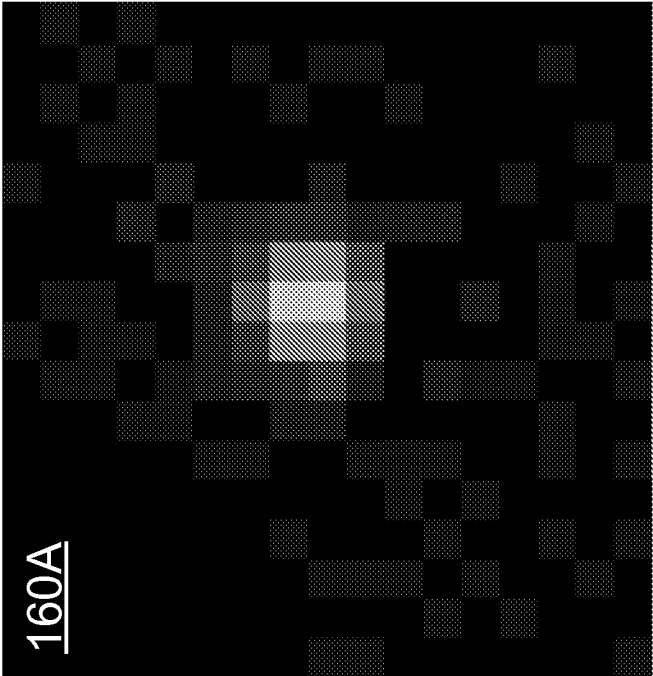
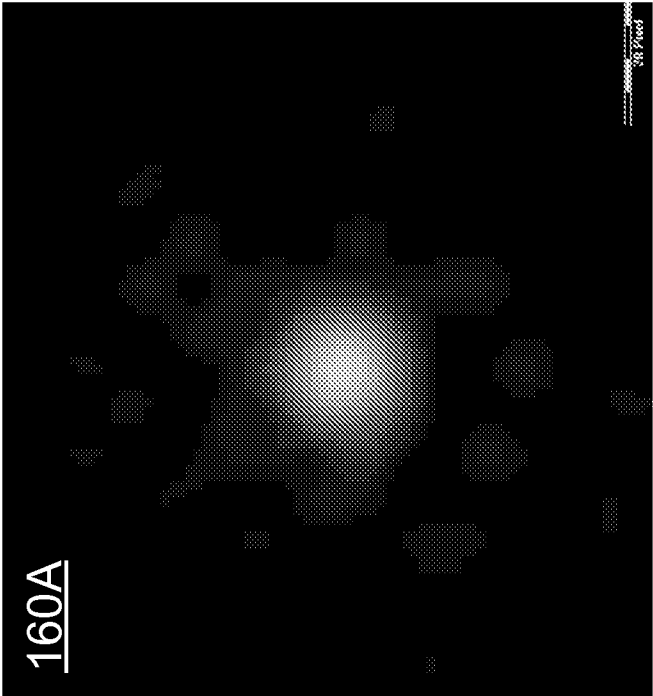


FIG. 6A

FIG. 6B

INTERNATIONAL SEARCH REPORT

International application No.
PCT/US2013/063606**A. CLASSIFICATION OF SUBJECT MATTER****G01N 21/956(2006.01)i, G01N 21/47(2006.01)i**

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

G01N 21/956; G01N 21/27; G01N 15/02; G01N 21/88; G01N 23/223; G01N 21/65; G01N 15/10; G01B 9/02; G01N 21/47

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Korean utility models and applications for utility models

Japanese utility models and applications for utility models

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

eKOMPASS(KIPO internal) & Keywords: photon, detect, particle, pulse, map, emit and reflect

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
Y	US 5,661,559 A (BREZOCZKY et al.) 26 August 1997 See abstract; column 2, lines 20-23, column 3, lines 15-30, column 5, lines 9-13; claims 1,10,28.	1-20
Y	JP 2006-308511 A (CANON INC.) 09 November 2006 See abstract; paragraph [0010]; figure 1.	1-20
Y	US 2005-0280808 A1 (BACKHAUSS et al.) 22 December 2005 See abstract; paragraphs [0011],[0015]; claim 28 and figure 3.	2,10,16
A	US 5,778,039 A (HOSSAIN et al.) 07 July 1998 See abstract; claim 1.	1-20
A	JP 2011-163872 A (NIPPON STEEL CORP.) 25 August 2011 See abstract; paragraph [0007]; claim 1.	1-20



Further documents are listed in the continuation of Box C.



See patent family annex.

* Special categories of cited documents:

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"O" document referring to an oral disclosure, use, exhibition or other means

"P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

"&" document member of the same patent family

Date of the actual completion of the international search

20 January 2014 (20.01.2014)

Date of mailing of the international search report

21 January 2014 (21.01.2014)

Name and mailing address of the ISA/KR

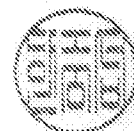
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INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No.

PCT/US2013/063606

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