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PREDICTIVE SENSOR TRACKING OPTIMIZATION IN MULTI- SENSOR SENSING APPLICATIONS

FIELD OF DISCLOSURE

5 The present disclosure relates in general to electronic devices with user interfaces, (e.g., mobile devices, game controllers, instrument panels, etc.), and more particularly, resonant phase sensing of resistive-inductive-capacitive sensors for use in a system for mechanical button replacement in a mobile device, and/or other suitable applications.

BACKGROUND

Many traditional mobile devices (e.g., mobile phones, personal digital assistants, video game controllers, etc.) include mechanical buttons to allow for interaction between a user of a mobile device and the mobile device itself. However, such mechanical buttons are susceptible to aging, wear, and tear that may reduce the useful life of a mobile device and/or may require significant repair if malfunction occurs. Also, the presence of mechanical buttons may render it difficult to manufacture mobile devices to be waterproof. Accordingly, mobile device manufacturers are increasingly looking to equip mobile devices with virtual buttons that act as a human-machine interface allowing for interaction between a user of a mobile device and the mobile device itself. Similarly, mobile device manufacturers are increasingly looking to equip mobile devices with other virtual interface areas (e.g., a virtual slider, interface areas of a body of the mobile device other than a touch screen, etc.). Ideally, for best user experience, such virtual interface areas should look and feel to a user as if a mechanical button or other mechanical interface were present instead of a virtual button or virtual interface area.

25 Presently, linear resonant actuators (LRAs) and other vibrational actuators (e.g., rotational actuators, vibrating motors, etc.) are increasingly being used in mobile devices to generate vibrational feedback in response to user interaction with human-machine interfaces of such devices. Typically, a sensor (traditionally a force or pressure sensor) detects user interaction with the device (e.g., a finger press on a virtual button of the device) and in response thereto, the linear resonant actuator may vibrate to provide feedback to the user. For example, a linear resonant actuator may vibrate in response to user interaction

with the human-machine interface to mimic to the user the feel of a mechanical button click.

However, there is a need in the industry for sensors to detect user interaction with a human-machine interface, wherein such sensors provide acceptable levels of sensor
5 sensitivity, power consumption, and size.

SUMMARY

In accordance with the teachings of the present disclosure, the disadvantages and problems associated with sensing of human-machine interface interactions in a mobile
10 device may be reduced or eliminated.

In accordance with embodiments of the present disclosure, a system may include a plurality of sensors, a measurement circuit communicatively coupled to the plurality of sensors and configured to measure one or more physical quantities associated with the plurality of sensors, and a predictive optimization subsystem configured to detect an event
15 associated with a first sensor of the plurality of sensors and responsive to the event, execute a predictive action with respect to one or more of the other sensors of the plurality of sensors.

In accordance with these and other embodiments of the present disclosure, a method may include, in a system having a plurality of sensors and a measurement circuit
20 communicatively coupled to the plurality of sensors and configured to measure one or more physical quantities associated with the plurality of sensors, detecting an event associated with a first sensor of the plurality of sensors and responsive to the event, executing a predictive action with respect to one or more of the other sensors of the plurality of sensors.

In accordance with these and other embodiments of the present disclosure, a mobile
25 device may include a housing, a plurality of sensors housed within or upon the housing, a measurement circuit communicatively coupled to the plurality of sensors and configured to measure one or more physical quantities associated with the plurality of sensors, and a predictive optimization subsystem configured to detect an event associated with a first sensor of the plurality of sensors; and responsive to the event, execute a predictive action
30 with respect to one or more of the other sensors of the plurality of sensors.

Technical advantages of the present disclosure may be readily apparent to one having ordinary skill in the art from the figures, description and claims included herein. The objects and advantages of the embodiments will be realized and achieved at least by the elements, features, and combinations particularly pointed out in the claims.

5 It is to be understood that both the foregoing general description and the following detailed description are examples and explanatory and are not restrictive of the claims set forth in this disclosure.

BRIEF DESCRIPTION OF THE DRAWINGS

10 A more complete understanding of the present embodiments and advantages thereof may be acquired by referring to the following description taken in conjunction with the accompanying drawings, in which like reference numbers indicate like features, and wherein:

FIGURE 1 illustrates a block diagram of selected components of an example mobile
15 device, in accordance with embodiments of the present disclosure;

FIGURE 2 illustrates a mechanical member separated by a distance from an inductive coil, in accordance with embodiments of the present disclosure;

FIGURE 3 illustrates selected components of an inductive sensing system that may be implemented by a resonant phase sensing system, in accordance with embodiments of
20 the present disclosure;

Each of FIGURES 4A-4C illustrates a diagram of selected components of an example resonant phase sensing system, in accordance with embodiments of the present disclosure;

FIGURE 5 illustrates a diagram of selected components of an example resonant
25 phase sensing system implementing time-division multiplexed processing of multiple resistive-inductive-capacitive sensors, in accordance with embodiments of the present disclosure; and

FIGURE 6 illustrates a flow chart of an example method for predictive optimization, in accordance with embodiments of the present disclosure.

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DETAILED DESCRIPTION

FIGURE 1 illustrates a block diagram of selected components of an example mobile device 102, in accordance with embodiments of the present disclosure. As shown in FIGURE 1, mobile device 102 may comprise an enclosure 101, a controller 103, a memory 104, a mechanical member 105, a microphone 106, a linear resonant actuator 107, a radio transmitter/receiver 108, a speaker 110, and a resonant phase sensing system 112.

Enclosure 101 may comprise any suitable housing, casing, or other enclosure for housing the various components of mobile device 102. Enclosure 101 may be constructed from plastic, metal, and/or any other suitable materials. In addition, enclosure 101 may be adapted (e.g., sized and shaped) such that mobile device 102 is readily transported on a person of a user of mobile device 102. Accordingly, mobile device 102 may include but is not limited to a smart phone, a tablet computing device, a handheld computing device, a personal digital assistant, a notebook computer, a video game controller, or any other device that may be readily transported on a person of a user of mobile device 102.

Controller 103 may be housed within enclosure 101 and may include any system, device, or apparatus configured to interpret and/or execute program instructions and/or process data, and may include, without limitation a microprocessor, microcontroller, digital signal processor (DSP), application specific integrated circuit (ASIC), or any other digital or analog circuitry configured to interpret and/or execute program instructions and/or process data. In some embodiments, controller 103 may interpret and/or execute program instructions and/or process data stored in memory 104 and/or other computer-readable media accessible to controller 103.

Memory 104 may be housed within enclosure 101, may be communicatively coupled to controller 103, and may include any system, device, or apparatus configured to retain program instructions and/or data for a period of time (e.g., computer-readable media). Memory 104 may include random access memory (RAM), electrically erasable programmable read-only memory (EEPROM), a Personal Computer Memory Card International Association (PCMCIA) card, flash memory, magnetic storage, opto-magnetic storage, or any suitable selection and/or array of volatile or non-volatile memory that retains data after power to mobile device 102 is turned off.

Microphone 106 may be housed at least partially within enclosure 101, may be communicatively coupled to controller 103, and may comprise any system, device, or apparatus configured to convert sound incident at microphone 106 to an electrical signal that may be processed by controller 103, wherein such sound is converted to an electrical
5 signal using a diaphragm or membrane having an electrical capacitance that varies based on sonic vibrations received at the diaphragm or membrane. Microphone 106 may include an electrostatic microphone, a condenser microphone, an electret microphone, a microelectromechanical systems (MEMS) microphone, or any other suitable capacitive microphone.

10 Radio transmitter/receiver 108 may be housed within enclosure 101, may be communicatively coupled to controller 103, and may include any system, device, or apparatus configured to, with the aid of an antenna, generate and transmit radio-frequency signals as well as receive radio-frequency signals and convert the information carried by such received signals into a form usable by controller 103. Radio transmitter/receiver 108
15 may be configured to transmit and/or receive various types of radio-frequency signals, including without limitation, cellular communications (e.g., 2G, 3G, 4G, LTE, etc.), short-range wireless communications (e.g., BLUETOOTH), commercial radio signals, television signals, satellite radio signals (e.g., GPS), Wireless Fidelity, etc.

A speaker 110 may be housed at least partially within enclosure 101 or may be
20 external to enclosure 101, may be communicatively coupled to controller 103, and may comprise any system, device, or apparatus configured to produce sound in response to electrical audio signal input. In some embodiments, a speaker may comprise a dynamic loudspeaker, which employs a lightweight diaphragm mechanically coupled to a rigid frame via a flexible suspension that constrains a voice coil to move axially through a
25 cylindrical magnetic gap. When an electrical signal is applied to the voice coil, a magnetic field is created by the electric current in the voice coil, making it a variable electromagnet. The voice coil and the driver's magnetic system interact, generating a mechanical force that causes the voice coil (and thus, the attached cone) to move back and forth, thereby reproducing sound under the control of the applied electrical signal coming from the
30 amplifier.

Mechanical member 105 may be housed within or upon enclosure 101, and may include any suitable system, device, or apparatus configured such that all or a portion of mechanical member 105 displaces in position responsive to a force, a pressure, or a touch applied upon or proximately to mechanical member 105. In some embodiments, 5 mechanical member 105 may be designed to appear as a mechanical button on the exterior of enclosure 101.

Linear resonant actuator 107 may be housed within enclosure 101, and may include any suitable system, device, or apparatus for producing an oscillating mechanical force across a single axis. For example, in some embodiments, linear resonant actuator 107 may 10 rely on an alternating current voltage to drive a voice coil pressed against a moving mass connected to a spring. When the voice coil is driven at the resonant frequency of the spring, linear resonant actuator 107 may vibrate with a perceptible force. Thus, linear resonant actuator 107 may be useful in haptic applications within a specific frequency range. While, for the purposes of clarity and exposition, this disclosure is described in relation to the use 15 of linear resonant actuator 107, it is understood that any other type or types of vibrational actuators (e.g., eccentric rotating mass actuators) may be used in lieu of or in addition to linear resonant actuator 107. In addition, it is also understood that actuators arranged to produce an oscillating mechanical force across multiple axes may be used in lieu of or in addition to linear resonant actuator 107. As described elsewhere in this disclosure, a linear 20 resonant actuator 107, based on a signal received from resonant phase sensing system 112, may render haptic feedback to a user of mobile device 102 for at least one of mechanical button replacement and capacitive sensor feedback.

Together, mechanical member 105 and linear resonant actuator 107 may form a human-interface device, such as a virtual interface (e.g., a virtual button), which, to a user 25 of mobile device 102, has a look and feel of a mechanical button or other mechanical interface of mobile device 102.

Resonant phase sensing system 112 may be housed within enclosure 101, may be communicatively coupled to mechanical member 105 and linear resonant actuator 107, and may include any system, device, or apparatus configured to detect a displacement of 30 mechanical member 105 indicative of a physical interaction (e.g., by a user of mobile device 102) with the human-machine interface of mobile device 102 (e.g., a force applied

by a human finger to a virtual interface of mobile device 102). As described in greater detail below, resonant phase sensing system 112 may detect displacement of mechanical member 105 by performing resonant phase sensing of a resistive-inductive-capacitive sensor for which an impedance (e.g., inductance, capacitance, and/or resistance) of the
5 resistive-inductive-capacitive sensor changes in response to displacement of mechanical member 105. Thus, mechanical member 105 may comprise any suitable system, device, or apparatus which all or a portion thereof may displace, and such displacement may cause a change in an impedance of a resistive-inductive-capacitive sensor integral to resonant phase sensing system 112. Resonant phase sensing system 112 may also generate an
10 electronic signal for driving linear resonant actuator 107 in response to a physical interaction associated with a human-machine interface associated with mechanical member 105. Detail of an example resonant phase sensing system 112 in accordance with embodiments of the present disclosure is depicted in greater detail below.

Although specific example components are depicted above in FIGURE 1 as being
15 integral to mobile device 102 (e.g., controller 103, memory 104, mechanical member 105, microphone 106, radio transmitter/receiver 108, speakers(s) 110, linear resonant actuator 107, etc.), a mobile device 102 in accordance with this disclosure may comprise one or more components not specifically enumerated above. For example, although FIGURE 1 depicts certain user interface components, mobile device 102 may include one or more
20 other user interface components in addition to those depicted in FIGURE 1, including but not limited to a keypad, a touch screen, and a display, thus allowing a user to interact with and/or otherwise manipulate mobile device 102 and its associated components. In addition, although FIGURE 1 depicts only a single virtual button comprising mechanical member 105 and linear resonant actuator 107 for purposes of clarity and exposition, in
25 some embodiments a mobile device 102 may have multiple virtual interfaces each comprising a respective mechanical member 105 and linear resonant actuator 107.

Although, as stated above, resonant phase sensing system 112 may detect displacement of mechanical member 105 by performing resonant phase sensing of a resistive-inductive-capacitive sensor for which an impedance (e.g., inductance,
30 capacitance, and/or resistance) of the resistive-inductive-capacitive sensor changes in response to displacement of mechanical member 105, in some embodiments resonant phase

sensing system 112 may primarily detect displacement of mechanical member 105 by using resonant phase sensing to determine a change in an inductance of a resistive-inductive-capacitive sensor. For example, FIGURES 2 and 3 illustrate selected components of an example inductive sensing application that may be implemented by resonant phase sensing system 112, in accordance with embodiments of the present disclosure.

FIGURE 2 illustrates mechanical member 105 embodied as a metal plate separated by a distance d from an inductive coil 202, in accordance with embodiments of the present disclosure. FIGURE 3 illustrates selected components of an inductive sensing system 300 that may be implemented by resonant phase sensing system 112, in accordance with embodiments of the present disclosure. As shown in FIGURE 3, inductive sensing system 300 may include mechanical member 105, modeled as a variable electrical resistance 304 and a variable electrical inductance 306, and may include inductive coil 202 in physical proximity to mechanical member 105 such that inductive coil 202 has a mutual inductance with mechanical member 105 defined by a variable coupling coefficient k . As shown in FIGURE 3, inductive coil 202 may be modeled as a variable electrical inductance 308 and a variable electrical resistance 310.

In operation, as a current I flows through inductive coil 202, such current may induce a magnetic field which in turn may induce an eddy current inside mechanical member 105. When a force is applied to and/or removed from mechanical member 105, which alters distance d between mechanical member 105 and inductive coil 202, the coupling coefficient k , variable electrical resistance 304, and/or variable electrical inductance 306 may also change in response to the change in distance. These changes in the various electrical parameters may, in turn, modify an effective impedance Z_L of inductive coil 202.

FIGURE 4A illustrates a diagram of selected components of an example resonant phase sensing system 112A, in accordance with embodiments of the present disclosure. In some embodiments, resonant phase sensing system 112A may be used to implement resonant phase sensing system 112 of FIGURE 1. As shown FIGURE 4A, resonant phase sensing system 112A may include a resistive-inductive-capacitive sensor 402 and a processing integrated circuit (IC) 412A.

As shown in FIGURE 4A, resistive-inductive-capacitive sensor 402 may include mechanical member 105, inductive coil 202, a resistor 404, and capacitor 406, wherein mechanical member 105 and inductive coil 202 have a variable coupling coefficient k . Although shown in FIGURE 4A to be arranged in parallel with one another, it is understood that inductive coil 202, resistor 404, and capacitor 406 may be arranged in any other suitable manner that allows resistive-inductive-capacitive sensor 402 to act as a resonant tank. For example, in some embodiments, inductive coil 202, resistor 404, and capacitor 406 may be arranged in series with one another. In some embodiments, resistor 404 may not be implemented with a stand-alone resistor, but may instead be implemented by a parasitic resistance of inductive coil 202, a parasitic resistance of capacitor 406, and/or any other suitable parasitic resistance.

Processing IC 412A may be communicatively coupled to resistive-inductive-capacitive sensor 402 and may comprise any suitable system, device, or apparatus configured to implement a measurement circuit to measure phase information associated with resistive-inductive-capacitive sensor 402 and based on the phase information, determine a displacement of mechanical member 105 relative to resistive-inductive-capacitive sensor 402. Thus, processing IC 412A may be configured to determine an occurrence of a physical interaction (e.g., press or release of a virtual button) associated with a human-machine interface associated with mechanical member 105 based on the phase information.

As shown in FIGURE 4A, processing IC 412A may include a phase shifter 410, a voltage-to-current converter 408, a preamplifier 440, an intermediate frequency mixer 442, a combiner 444, a programmable gain amplifier (PGA) 414, a voltage-controlled oscillator (VCO) 416, a phase shifter 418, an amplitude and phase calculation block 431, a DSP 432, a low-pass filter 434, and a combiner 450. Processing IC 412A may also include a coherent incident/quadrature detector implemented with an incident channel comprising a mixer 420, a low-pass filter 424, and an analog-to-digital converter (ADC) 428, and a quadrature channel comprising a mixer 422, a low-pass filter 426, and an ADC 430 such that processing IC 412A is configured to measure the phase information using the coherent incident/quadrature detector.

Phase shifter 410 may include any system, device, or apparatus configured to detect an oscillation signal generated by processing IC 412A (as explained in greater detail below) and phase shift such oscillation signal (e.g., by 45 degrees) such that a normal operating frequency of resonant phase sensing system 112A, an incident component of a sensor signal ϕ generated by pre-amplifier 440, is approximately equal to a quadrature component of sensor signal ϕ , so as to provide common mode noise rejection by a phase detector implemented by processing IC 412A, as described in greater detail below.

Voltage-to-current converter 408 may receive the phase shifted oscillation signal from phase shifter 410, which may be a voltage signal, convert the voltage signal to a corresponding current signal, and drive the current signal on resistive-inductive-capacitive sensor 402 at a driving frequency with the phase-shifted oscillation signal in order to generate sensor signal ϕ which may be processed by processing IC 412A, as described in greater detail below. In some embodiments, a driving frequency of the phase-shifted oscillation signal may be selected based on a resonant frequency of resistive-inductive-capacitive sensor 402 (e.g., may be approximately equal to the resonant frequency of resistive-inductive-capacitive sensor 402).

Preamplifier 440 may receive sensor signal ϕ and condition sensor signal ϕ for frequency mixing, with mixer 442, to an intermediate frequency Δf combined by combiner 444 with an oscillation frequency generated by VCO 416, as described in greater detail below, wherein intermediate frequency Δf is significantly less than the oscillation frequency. In some embodiments, preamplifier 440, mixer 442, and combiner 444 may not be present, in which case PGA 414 may receive sensor signal ϕ directly from resistive-inductive-capacitive sensor 402. However, when present, preamplifier 440, mixer 442, and combiner 444 may allow for mixing sensor signal ϕ down to a lower intermediate frequency Δf which may allow for lower-bandwidth and more efficient ADCs (e.g., ADCs 428 and 430 of FIGURES 4A and 4B and ADC 429 of FIGURE 4C, described below) and/or which may allow for minimization of phase and/or gain mismatches in the incident and quadrature paths of the phase detector of processing IC 412A.

In operation, PGA 414 may further amplify sensor signal ϕ to condition sensor signal ϕ for processing by the coherent incident/quadrature detector. VCO 416 may generate an oscillation signal to be used as a basis for the signal driven by voltage-to-current

converter 408, as well as the oscillation signals used by mixers 420 and 422 to extract incident and quadrature components of amplified sensor signal ϕ . As shown in FIGURE 4A, mixer 420 of the incident channel may use an unshifted version of the oscillation signal generated by VCO 416, while mixer 422 of the quadrature channel may use a 90-degree shifted version of the oscillation signal phase shifted by phase shifter 418. As mentioned above, the oscillation frequency of the oscillation signal generated by VCO 416 may be selected based on a resonant frequency of resistive-inductive-capacitive sensor 402 (e.g., may be approximately equal to the resonant frequency of resistive-inductive-capacitive sensor 402).

In the incident channel, mixer 420 may extract the incident component of amplified sensor signal ϕ , low-pass filter 424 may filter out the oscillation signal mixed with the amplified sensor signal ϕ to generate a direct current (DC) incident component, and ADC 428 may convert such DC incident component into an equivalent incident component digital signal for processing by amplitude and phase calculation block 431. Similarly, in the quadrature channel, mixer 422 may extract the quadrature component of amplified sensor signal ϕ , low-pass filter 426 may filter out the phase-shifted oscillation signal mixed with the amplified sensor signal ϕ to generate a direct current (DC) quadrature component, and ADC 430 may convert such DC quadrature component into an equivalent quadrature component digital signal for processing by amplitude and phase calculation block 431.

Amplitude and phase calculation block 431 may include any system, device, or apparatus configured to receive phase information comprising the incident component digital signal and the quadrature component digital signal and based thereon, extract amplitude and phase information.

DSP 432 may include any system, device, or apparatus configured to interpret and/or execute program instructions and/or process data. In particular, DSP 432 may receive the phase information and the amplitude information generated by amplitude and phase calculation block 431 and based thereon, determine a displacement of mechanical member 105 relative to resistive-inductive-capacitive sensor 402, which may be indicative of an occurrence of a physical interaction (e.g., press or release of a virtual button or other interaction with a virtual interface) associated with a human-machine interface associated with mechanical member 105 based on the phase information. DSP 432 may also generate

an output signal indicative of the displacement. In some embodiments, such output signal may comprise a control signal for controlling mechanical vibration of linear resonant actuator 107 in response to the displacement.

The phase information generated by amplitude and phase calculation block 431 may
5 be subtracted from a reference phase ϕ_{ref} by combiner 450 in order to generate an error signal that may be received by low-pass filter 434. Low-pass filter 434 may low-pass filter the error signal, and such filtered error signal may be applied to VCO 416 to modify the frequency of the oscillation signal generated by VCO 416, in order to drive sensor signal ϕ towards reference phase ϕ_{ref} . As a result, sensor signal ϕ may comprise a transient decaying
10 signal in response to a “press” of a virtual button (or other interaction with a virtual interface) associated with resonant phase sensing system 112A as well as another transient decaying signal in response to a subsequent “release” of the virtual button (or other interaction with a virtual interface). Accordingly, low-pass filter 434 in connection with VCO 416 may implement a feedback control loop that may track changes in operating
15 parameters of resonant phase sensing system 112A by modifying the driving frequency of VCO 416.

FIGURE 4B illustrates a diagram of selected components of an example resonant phase sensing system 112B, in accordance with embodiments of the present disclosure. In some embodiments, resonant phase sensing system 112B may be used to implement
20 resonant phase sensing system 112 of FIGURE 1. Resonant phase sensing system 112B of FIGURE 4B may be, in many respects, similar to resonant phase sensing system 112A of FIGURE 4A. Accordingly, only those differences between resonant phase sensing system 112B and resonant phase sensing system 112A may be described below. As shown
FIGURE 4B, resonant phase sensing system 112B may include processing IC 412B in lieu
25 of processing IC 412A. Processing IC 412B of FIGURE 4B may be, in many respects, similar to processing IC 412A of FIGURE 4A. Accordingly, only those differences between processing IC 412B and processing IC 412A may be described below.

Processing IC 412B may include fixed-frequency oscillator 417 and variable phase shifter 419 in lieu of VCO 416 of processing IC 412A. Thus, in operation, oscillator 417
30 may drive a fixed driving signal and oscillation signal which variable phase shifter 419 may phase shift to generate oscillation signals to be mixed by mixers 420 and 422. Similar to

that of processing IC 412A, low-pass filter 434 may low-pass filter an error signal based on phase information extracted by amplitude and phase calculation block 431, but instead such filtered error signal may be applied to variable phase shifter 419 to modify the phase offset of the oscillation signal generated by oscillator 417, in order to drive sensor signal ϕ towards indicating a phase shift of zero. As a result, sensor signal ϕ may comprise a transient decaying signal in response to a “press” of a virtual button (or other interaction with a virtual interface) associated with resonant phase sensing system 112B as well as another transient decaying signal in response to a subsequent “release” of the virtual button (or other interaction with a virtual interface). Accordingly, low-pass filter 434 in connection with variable phase shifter 419 may implement a feedback control loop that may track changes in operating parameters of resonant phase sensing system 112B by modifying the phase shift applied by variable phase shifter 419.

FIGURE 4C illustrates a diagram of selected components of an example resonant phase sensing system 112C, in accordance with embodiments of the present disclosure. In some embodiments, resonant phase sensing system 112C may be used to implement resonant phase sensing system 112 of FIGURE 1. Resonant phase sensing system 112C of FIGURE 4C may be, in many respects, similar to resonant phase sensing system 112A of FIGURE 4A. Accordingly, only those differences between resonant phase sensing system 112C and resonant phase sensing system 112A may be described below. For example, a particular difference between resonant phase sensing system 112C and resonant phase sensing system 112A is that resonant phase sensing system 112C may include ADC 429 in lieu of ADC 428 and ADC 430. Accordingly, a coherent incident/quadrature detector for resonant phase sensing system 112C may be implemented with an incident channel comprising a digital mixer 421 and a digital low-pass filter 425 (in lieu of analog mixer 420 and analog low-pass filter 424) and a quadrature channel comprising a digital mixer 423 and a low-pass filter 427 (in lieu of analog mixer 422 and analog low-pass filter 426) such that processing IC 412C is configured to measure the phase information using such coherent incident/quadrature detector. Although not explicitly shown, resonant phase sensing system 112B could be modified in a manner similar to that of how resonant phase sensing system 112A is shown to be modified to result in resonant phase sensing system 112C.

FIGURE 5 illustrates a diagram of selected components of an example resonant phase sensing system 112D implementing time-division multiplexed processing of multiple resistive-inductive-capacitive sensors 402 (e.g., resistive-inductive-capacitive sensors 402A – 402N shown in FIGURE 5), in accordance with embodiments of the present disclosure. In some embodiments, resonant phase sensing system 112D may be used to implement resonant phase sensing system 112 of FIGURE 1. Resonant phase sensing system 112D of FIGURE 5 may be, in many respects, similar to resonant phase sensing system 112A of FIGURE 4A. Accordingly, only those differences between resonant phase sensing system 112D and resonant phase sensing system 112A may be described below.

In particular, resonant phase sensing system 112D may include a plurality of resistive-inductive-capacitive sensors 402 (e.g., resistive-inductive-capacitive sensors 402A – 402N shown in FIGURE 5) in lieu of the single resistive-inductive-capacitive sensor 402 shown in FIGURE 4A. In addition, resonant phase sensing system 112D may include multiplexers 502 and 504, each of which may select an output signal from a plurality of input signals responsive to a control signal SELECT (which may be controlled by a time-division multiplexing control subsystem implemented by controller 103 or another suitable component of mobile device 102). Thus, while in some embodiments a device such as mobile device 102 may comprise a plurality of resistive-inductive-capacitive sensors 402 which may be simultaneously driven and separately processed by a respective processing IC, in other embodiments a resonant phase sensing system (e.g., resonant phase sensing system 112D) may drive resistive-inductive-capacitive sensors 402 in a time-division multiplexed manner. Such approach may reduce power consumption and device size as compared with multiple-sensor implementations in which the multiple sensors are simultaneously driven and/or sensed. Device size may be reduced by time-division multiplexing multiple sensors into a single driver and measurement circuit channel, wherein only a single driver and a single measurement circuit may be required, thus minimizing an amount of integrated circuit area needed to perform driving and measurement. In addition, by leveraging a single driver and measurement circuit, no calibration may be needed to adjust for mismatches and/or errors between different drivers and/or different measurement circuits.

For purposes of clarity and exposition, preamplifier 440, mixer 442, and combiner 444 have been excluded from FIGURE 5. However, in some embodiments, processing IC 412D may include preamplifier 440, mixer 442, and combiner 444 similar to that depicted in FIGURES 4A-4C.

5 In resonant phase sensing system 112D, when a first resistive-inductive-capacitive sensor (e.g., resistive-inductive-capacitive sensor 402A) is selected by the time-division multiplexing control subsystem for being driven by voltage-to-current converter 408 and measured by the measurement circuit implemented by processing IC 412A, other resistive-inductive-capacitive sensors (e.g., resistive-inductive-capacitive sensors 402B – 402N)
10 may each be placed in a low-impedance state. Similarly, when a second resistive-inductive-capacitive sensor (e.g., resistive-inductive-capacitive sensor 402B) is selected by the time-division multiplexing control subsystem for being driven by voltage-to-current converter 408 and measured by the measurement circuit implemented by processing IC 412A, other resistive-inductive-capacitive sensors (e.g., resistive-inductive-capacitive sensors other
15 than 402B, including 402A) may each be placed in a low-impedance state. Such an approach may minimize power consumption within unselected resistive-inductive-capacitive sensors 402.

As shown in FIGURE 5, resonant phase sensing system 112D may include a predictive optimizer 452. As described in greater detail below, predictive optimizer 452
20 may receive signals generated by PGA 414, low-pass filters 424 and 426, amplitude and phase calculation block 431, DSP 432, and/or any other signal within processing IC 412D, and based thereon, determine if an event associated with a resistive-inductive-capacitive sensor 402 has occurred that affects the ability of resonant phase sensing system 112D to accurately, precisely, and/or correctly determine displacement of a mechanical member
25 105. Further, as described in greater detail below, predictive optimizer 452 may be configured to execute a predictive action with respect to other resistive-inductive-capacitive sensors 402 in response to an event associated with a resistive-inductive-capacitive sensor 402. For the sake of simplicity in the exposition of FIGURE 5, predictive optimizer 452 is shown as outputting control signals only to DSP 432. However, in actual
30 implementation, predictive optimizer 452 may execute predictive actions by

communicating control signals to any component of processing IC 412D or resonant phase sensing system 112D.

Although not explicitly shown, resonant phase sensing system 112B could be modified in a manner similar to that of how resonant phase sensing system 112A is shown to be modified to result in resonant phase sensing system 112D, such that resonant phase sensing system 112B could implement time-division multiplexed sensing on a plurality of resistive-inductive-capacitive sensors 402. Similarly, although not explicitly shown, resonant phase sensing system 112C could be modified in a manner similar to that of how resonant phase sensing system 112A is shown to be modified to result in resonant phase sensing system 112D, such that resonant phase sensing system 112C could implement time-division multiplexed sensing on a plurality of resistive-inductive-capacitive sensors 402.

FIGURE 6 illustrates a flow chart of an example method 600 for predictive optimization, in accordance with embodiments of the present disclosure. According to some embodiments, method 600 may begin at step 602. As noted above, teachings of the present disclosure may be implemented in a variety of configurations of processing IC 412D. As such, the preferred initialization point for method 600 and the order of the steps comprising method 200 may depend on the implementation chosen.

At step 602, predictive optimizer 452 may monitor for events based on signals generated by PGA 414, low-pass filter 426, amplitude and phase calculation block 431, DSP 432, and/or any other signal within processing IC 412D occurring during scanning of resistive-inductive-capacitive sensors 402. At step 604, predictive optimizer 452 may determine if an event associated with a resistive-inductive-capacitive sensor 402 has occurred. If an event has occurred, method 600 may proceed to step 606. Otherwise, method 600 may proceed to step 608.

At step 606, in response to occurrence of an event, predictive optimizer 452 may execute a predictive action with respect to other resistive-inductive-capacitive sensors 402 in response to an event associated with a resistive-inductive-capacitive sensor 402. Such predictive action may include updating one or more operating parameters associated with other resistive-inductive-capacitive sensors 402 prior to the next scan of such resistive-inductive-capacitive sensors 402, as described in greater detail below.

At step 608, processing IC 412D may resume scanning of resistive-inductive-capacitive sensors 402. After completion of step 608, method 600 may return again to step 602.

Although FIGURE 6 discloses a particular number of steps to be taken with respect to method 600, method 600 may be executed with greater or fewer steps than those depicted in FIGURE 6. In addition, although FIGURE 6 discloses a certain order of steps to be taken with respect to method 600, the steps comprising method 600 may be completed in any suitable order.

Method 600 may be implemented using a resonant phase sensing system 112, processing IC 412D, or any other system operable to implement method 600. In certain embodiments, method 600 may be implemented partially or fully in software and/or firmware embodied in computer-readable media.

The table appearing below sets forth example events occurring at a first resistive-inductive-capacitive sensor 402 and one or more predictive actions that may be taken on other resistive-inductive-capacitive sensors 402 by predictive optimizer 452 in response to such events.

Some of the various predictive actions shown in the table may be defined as follows:

Change operating frequency – first sensor detects the presence of an interfering signal and prior to scanning of other sensor(s), predictive optimizer 452 modifies the drive frequency for channel(s) of other sensor(s) by a specified amount, with a calculation based on amount of frequency change needed to attenuate the interfering signal on the other sensor(s).

Change drive amplitude – first sensor detects the presence of an interfering signal and prior to scanning of other sensor(s), predictive optimizer 452 modifies the drive amplitude for channel(s) of other sensor(s) by a specified amount, with a calculation based on amount of amplitude change needed to attenuate the interfering signal on the other sensor(s).

Change filtering corner frequency at one or more points in phase detector path to attenuate interferer – first sensor detects the presence of an interfering signal and prior to scanning of other sensor(s), predictive optimizer 452 modifies filter taps/corner frequency of filters (e.g., low-pass filters 424, 426, 434) for channel(s) of other sensor(s) by a specified

amount, with a calculation based on a frequency band needing to be attenuated for the other sensor(s).

Event at first resistive-inductive-capacitive sensor 402	Predictive action at other resistive-inductive-capacitive sensors 402
Weak faults (e.g., electrical interference) Strong faults (e.g., mechanical damage)	Change operating frequency Change driving amplitude Change filtering corner frequency at one or more points in phase detector path to attenuate interferer Change sensor parameters Change scan rate Change conversion time Temporarily disable sensor scanning Enter a fault diagnostic mode or instrumentation mode prior to scanning Gain normalization on other sensors
Sensor signal ϕ indicating initial portion of virtual button press	Change sensor scan rate
Temperature drift of first resistive-inductive-capacitive sensor 402	Update baseline tracking rate for sensor signal ϕ Begin faster sensor scanning Force temperature measurements prior to sensor scanning
Catastrophic fault detected (sensor short, sensor open, etc.)	Infer that same fault is also present on sensors and take same course of action as first sensor Determine if fault exists on other sensors before scanning Discard first sensor information and use remaining sensors to make decision Deploy backup sensor if available

5 Change sensor parameters – first sensor detects the presence of an interfering signal and prior to scanning of other sensor(s), predictive optimizer 452 modifies sensor parameters (e.g., quality factor, capacitance of capacitor 406) for other sensor(s) by a specified amount, with a calculation based on amount of frequency change needed to attenuate the interfering signal on the other sensor(s).

10 Change scan rate – first sensor detects the presence of an interfering signal and prior to scanning of other sensor(s), predictive optimizer 452 modifies a scan rate for channel(s) of other sensor(s) by a specified amount, such that other sensor(s) update(s) its/their scan

rate(s) to be faster than its/their nominal operating rate(s), thus decreasing latency in responding to the interfering signal.

Change conversion time – first sensor detects the presence of an interfering signal and prior to scanning of other sensor(s), predictive optimizer 452 modifies a conversion
5 time for channel(s) of other sensor(s) by a specified amount, with a calculation based on an amount of filtering needed to attenuate the interfering signal that would otherwise fall in band in the other sensor(s).

Gain normalization on other sensors – in the event of bending or twisting of an enclosure (e.g., enclosure 101) that may deform a sensor and affect functioning of a sensor,
10 an amount of permanent deformation onto the sensors may vary sensor to sensor thus affecting the sensitivity displacement(s) of mechanical member(s) 105. If such an event occurs, then when predictive optimizer 452 detects mechanical damage associated with a first sensor, predictive optimizer 452 may apply a gain correction term to other sensor(s) to mitigate the permanent effects of sensitivity change to a user.

15 Change sensor scan rate – when a slower sensor scan rate is used during idle situations to conserve power and a first sensor detects what can be characterized as a user interaction with a mechanical member 105, predictive optimizer 452 may update scan rate(s) on other sensor(s) to respond faster, thus potentially decreasing overall latency in user interaction.

20 Update baseline tracking rate for sensor signal ϕ – first sensor detects a change in temperature prior to another sensor scanning, predictive optimizer 452 modifies a baseline tracking rate for other sensor(s), for example as described in either or both of U.S. Patent Application Serial No. 16/866,175 filed May 4, 2020, and U.S. Patent Application Serial No. 17/080,455 filed October 20, 2020, both of which are incorporated by reference herein
25 in their entireties.

Begin faster sensor scanning – first sensor detects a change in temperature prior to other sensor(s) scanning, predictive optimizer 452 modifies scan rate(s) for other sensors(s) such that other sensor(s) update(s) its/their scan rate(s) to be faster than its/their nominal operating rate(s), thus determining an amount of baseline change other sensor(s) need(s) to
30 apply in a shorter time span than the nominal operating rate(s).

Force temperature measurements prior to sensor scanning – first sensor detects a change in temperature on its temperature sensor reading, predictive optimizer 452 forces other sensor(s) to take its/their temperature(s) and then make a decision whether to update its/their baseline tracking before taking measurements.

5 Determine if fault exists on other sensors before scanning – may involve predictive optimizer causing execution of an instrumentation sweep of a quality factor and/or resonance detection procedure to detect health of other sensor(s).

Discard first sensor information and use remaining sensors to make decision – if information from multiple sensors were being used to determine whether a user interaction
10 has occurred and a catastrophic fault is detected on a first sensor, predictive optimizer 452 may cause processing IC 412D to exclude the first sensor and use only other sensor(s) to make a determination of user interaction.

Deploy backup sensor if available – predictive optimizer 452 assumes that the catastrophic damage to a first sensor has occurred on other remaining sensor(s), and then
15 prior to scanning, swap out potentially damaged sensor(s) with backup sensor(s), if available.

In the embodiments described above, if an event associated with a first sensor occurs, predictive optimizer 452 may apply the same predictive action to all other sensors, or may apply different predictive actions to all other sensors. For example, in some
20 embodiments, predictive optimizer 452 may apply predictive action only to other sensors in close physical proximity to the first sensor. Accordingly, sensors outside an expected range of influence of an event (e.g., electrical interference) may be left unaffected. As another example, predictive optimizer 452 may apply “stronger” predictive action to other sensors in close physical proximity to the first sensor while applying “weaker” predictive
25 action to other sensors less physically proximate to the first sensor (e.g., higher gains for closer sensors, lower gains for sensors further away from first sensor).

Although the foregoing contemplates that predictive optimizer 452 may detect an event associated with an individual sensor and then apply a predictive action to other individual sensors in response thereto, in some embodiments, techniques similar to those
30 described above may be applied such that predictive optimizer 452 may detect an event

associated with a group of multiple sensors and then apply a predictive action to one or more other groups of multiple sensors in response thereto.

Although the foregoing contemplates that predictive optimizer 452 may detect an event associated with a resistive-inductive-capacitive sensor and then apply a predictive
5 action to one or more other resistive-inductive-capacitive sensors in response thereto, techniques similar to those described above may be applied such that predictive optimizer 452 (or a similar component) may detect an event in any type of sensor (e.g., resistive-inductive-capacitive sensor, resistive sensor, inductive sensor, capacitive sensor, temperature sensor, gyroscopic sensor, accelerometer, barometer, pressure sensor,
10 ultrasonic sensor, magnetic sensor, etc.), and in response to such event, apply a predictive action to one or more other sensors, regardless of whether such one or more other sensors are of the same type of sensor as the sensor associated with the detected event.

Although the foregoing contemplates use of closed-loop feedback for sensing of displacement, the various embodiments represented by FIGURES 4A-5 may be modified
15 to implement an open-loop system for sensing of displacement. In such an open-loop system, a processing IC may include no feedback path from amplitude and phase calculation block 431 to VCO 416 or variable phase shifter 419 and thus may also lack a feedback low-pass filter 434. Thus, a phase measurement may still be made by comparing a change in phase to a reference phase value, but the oscillation frequency driven by VCO
20 416 may not be modified or the phase shifted by variable phase shifter 419 may not be shifted.

Although the foregoing contemplates use of a coherent incident/quadrature detector as a phase detector for determining phase information associated with resistive-inductive-capacitive sensor 402, a resonant phase sensing system 112 may perform phase detection
25 and/or otherwise determine phase information associated with resistive-inductive-capacitive sensor 402 in any suitable manner, including, without limitation, using only one of the incident path or quadrature path to determine phase information.

In some embodiments, an incident/quadrature detector as disclosed herein may include one or more frequency translation stages that translate the sensor signal into direct-
30 current signal directly or into an intermediate frequency signal and then into a direct-current

signal. Any of such frequency translation stages may be implemented either digitally after an analog-to-digital converter stage or in analog before an analog-to-digital converter stage.

In addition, although the foregoing contemplates measuring changes in resistance and inductance in resistive-inductive-capacitive sensor 402 caused by displacement of mechanical member 105, other embodiments may operate based on a principle that any change in impedance based on displacement of mechanical member 105 may be used to sense displacement. For example, in some embodiments, displacement of mechanical member 105 may cause a change in a capacitance of resistive-inductive-capacitive sensor 402, such as if mechanical member 105 included a metal plate implementing one of the capacitive plates of capacitor 406.

Although DSP 432 may be capable of processing phase information to make a binary determination of whether physical interaction associated with a human-machine interface associated with mechanical member 105 has occurred and/or ceased to occur, in some embodiments, DSP 432 may quantify a duration of a displacement of mechanical member 105 to more than one detection threshold, for example to detect different types of physical interactions (e.g., a short press of a virtual button versus a long press of the virtual button). In these and other embodiments, DSP 432 may quantify a magnitude of the displacement to more than one detection threshold, for example to detect different types of physical interactions (e.g., a light press of a virtual button versus a quick and hard press of the virtual button).

As used herein, when two or more elements are referred to as “coupled” to one another, such term indicates that such two or more elements are in electronic communication or mechanical communication, as applicable, whether connected indirectly or directly, with or without intervening elements.

This disclosure encompasses all changes, substitutions, variations, alterations, and modifications to the example embodiments herein that a person having ordinary skill in the art would comprehend. Similarly, where appropriate, the appended claims encompass all changes, substitutions, variations, alterations, and modifications to the example embodiments herein that a person having ordinary skill in the art would comprehend. Moreover, reference in the appended claims to an apparatus or system or a component of an apparatus or system being adapted to, arranged to, capable of, configured to, enabled to,

operable to, or operative to perform a particular function encompasses that apparatus, system, or component, whether or not it or that particular function is activated, turned on, or unlocked, as long as that apparatus, system, or component is so adapted, arranged, capable, configured, enabled, operable, or operative. Accordingly, modifications, additions, or omissions may be made to the systems, apparatuses, and methods described herein without departing from the scope of the disclosure. For example, the components of the systems and apparatuses may be integrated or separated. Moreover, the operations of the systems and apparatuses disclosed herein may be performed by more, fewer, or other components and the methods described may include more, fewer, or other steps. Additionally, steps may be performed in any suitable order. As used in this document, “each” refers to each member of a set or each member of a subset of a set.

Although exemplary embodiments are illustrated in the figures and described below, the principles of the present disclosure may be implemented using any number of techniques, whether currently known or not. The present disclosure should in no way be limited to the exemplary implementations and techniques illustrated in the drawings and described above.

Unless otherwise specifically noted, articles depicted in the drawings are not necessarily drawn to scale.

All examples and conditional language recited herein are intended for pedagogical objects to aid the reader in understanding the disclosure and the concepts contributed by the inventor to furthering the art, and are construed as being without limitation to such specifically recited examples and conditions. Although embodiments of the present disclosure have been described in detail, it should be understood that various changes, substitutions, and alterations could be made hereto without departing from the spirit and scope of the disclosure.

Although specific advantages have been enumerated above, various embodiments may include some, none, or all of the enumerated advantages. Additionally, other technical advantages may become readily apparent to one of ordinary skill in the art after review of the foregoing figures and description.

To aid the Patent Office and any readers of any patent issued on this application in interpreting the claims appended hereto, applicants wish to note that they do not intend any

of the appended claims or claim elements to invoke 35 U.S.C. § 112(f) unless the words “means for” or “step for” are explicitly used in the particular claim.

WHAT IS CLAIMED IS:

1. A system comprising:
a plurality of sensors;
a measurement circuit communicatively coupled to the plurality of sensors and
5 configured to measure one or more physical quantities associated with the plurality of
sensors; and
a predictive optimization subsystem configured to:
detect an event associated with a first sensor of the plurality of sensors; and
responsive to the event, execute a predictive action with respect to one or
10 more of the other sensors of the plurality of sensors.
2. The system of Claim 1, wherein:
the plurality of sensors includes resistive-inductive-capacitive sensors;
the one or more physical quantities comprise phase information associated with the
15 resistive-inductive-capacitive sensor; and
the measurement circuit is further configured to, based on the phase information,
determine a displacement of a mechanical member relative to at least one of the resistive-
inductive-capacitive sensors, wherein the displacement of the mechanical member causes
a change in an impedance of one or more of the resistive-inductive-capacitive sensors.
20
3. The system of any of Claims 1 and 2, wherein executing the predictive
action comprises updating one or more operating parameters associated with the one or
more of the other sensors of the plurality of sensors.
- 25 4. The system of any of Claims 1-3, wherein the event comprises one of
electrical interference and mechanical damage occurring at the first sensor.
5. The system of Claim 4, wherein the predictive action comprises changing
an operating frequency associated with the one or more of the other sensors.
30

6. The system of Claim 4, wherein the predictive action comprises changing a driving amplitude associated with the one or more of the other sensors.

7. The system of Claim 4, wherein the predictive action comprises changing a
5 corner frequency of a filter associated with the one or more of the other sensors.

8. The system of Claim 4, wherein the predictive action comprises changing one or more of a quality factor and an impedance associated with the one or more of the other sensors.

10

9. The system of Claim 4, wherein the predictive action comprises changing a sensor scan rate associated with the one or more of the other sensors.

10. The system of Claim 4, wherein the predictive action comprises changing a
15 sensor conversion time associated with the one or more of the other sensors.

11. The system of Claim 4, wherein the predictive action comprises temporarily disabling scanning of the one or more of the other sensors.

12. The system of Claim 4, wherein the predictive action comprises entering at
20 least one of a fault diagnostic mode or instrumentation mode prior to scanning the one or more of the other sensors.

13. The system of Claim 4, wherein the predictive action comprises performing
25 gain normalization of the one or more of the other sensors.

14. The system of any of Claims 1-3, wherein the event comprises an indication of human interaction with a human-machine interface associated with the first sensor.

15. The system of Claim 14, wherein the predictive action comprises increasing
30 a sensor scan rate associated with the one or more of the other sensors.

16. The system of Claims 1-3, wherein the event comprises an indication of a temperature drift associated with the first sensor.

5 17. The system of Claim 16, wherein the predictive action comprises updating a baseline tracking rate associated with the one or more of the other sensors.

18. The system of Claim 16, wherein the predictive action comprises increasing a sensor scan rate associated with the one or more of the other sensors.

10

19. The system of Claim 16, wherein the predictive action comprises forcing measurements of temperatures associated with the one or more of the other sensors before sensor scanning of the one or more of the other sensors.

15 20. The system of any of Claims 1-3, wherein the event comprises an indication of a catastrophic fault associated with the first sensor.

21. The system of Claim 20, wherein the predictive action comprises inferring that the same catastrophic fault exists at the one or more of the other sensors.

20

22. The system of Claim 20, wherein the predictive action comprises determining if the catastrophic fault exists at the one or more of the other sensors before sensor scanning of the one or more of the other sensors.

25 23. The system of Claim 20, wherein the predictive action comprises discarding measurement of the first sensor and using the one or more of the other sensors to determine the one or more physical quantities.

24. The system of Claim 20, wherein the predictive action comprises deploying
30 a backup sensor to the first sensor.

25. The system of any of Claims 1-3, wherein the predictive action for a second sensor of the one or more of the other sensors is based on a physical proximity of the second sensor to the first sensor.

26. A method comprising, in a system having a plurality of sensors and a measurement circuit communicatively coupled to the plurality of sensors and configured to measure one or more physical quantities associated with the plurality of sensors:

detecting an event associated with a first sensor of the plurality of sensors; and
5 responsive to the event, executing a predictive action with respect to one or more of the other sensors of the plurality of sensors.

27. The method of Claim 26, wherein:
the plurality of sensors includes resistive-inductive-capacitive sensors;
10 the one or more physical quantities comprise phase information associated with the resistive-inductive-capacitive sensor; and
the measurement circuit is further configured to, based on the phase information, determine a displacement of a mechanical member relative to at least one of the resistive-inductive-capacitive sensors, wherein the displacement of the mechanical member causes
15 a change in an impedance of one or more of the resistive-inductive-capacitive sensors.

28. The method of any of Claims 26 and 27, wherein executing the predictive action comprises updating one or more operating parameters associated with the one or more of the other sensors of the plurality of sensors.
20

29. The method of any of Claims 26-28, wherein the event comprises one of electrical interference and mechanical damage occurring at the first sensor.

30. The method of Claim 29, wherein the predictive action comprises changing
25 an operating frequency associated with the one or more of the other sensors.

31. The method of Claim 29, wherein the predictive action comprises changing a driving amplitude associated with the one or more of the other sensors.

32. The method of Claim 29, wherein the predictive action comprises changing
30 a corner frequency of a filter associated with the one or more of the other sensors.

33. The method of Claim 29, wherein the predictive action comprises changing one or more of a quality factor and an impedance associated with the one or more of the other sensors.

5

34. The method of Claim 29, wherein the predictive action comprises changing a sensor scan rate associated with the one or more of the other sensors.

35. The method of Claim 29, wherein the predictive action comprises changing
10 a sensor conversion time associated with the one or more of the other sensors.

36. The method of Claim 29, wherein the predictive action comprises temporarily disabling scanning of the one or more of the other sensors.

37. The method of Claim 29, wherein the predictive action comprises entering
15 at least one of a fault diagnostic mode or instrumentation mode prior to scanning the one or more of the other sensors.

38. The method of Claim 29, wherein the predictive action comprises
20 performing gain normalization of the one or more of the other sensors.

39. The method of any of Claims 26-28, wherein the event comprises an indication of human interaction with a human-machine interface associated with the first sensor.

25

40. The method of Claim 39, wherein the predictive action comprises increasing a sensor scan rate associated with the one or more of the other sensors.

41. The method of any of Claims 26-28, wherein the event comprises an
30 indication of a temperature drift associated with the first sensor.

42. The method of Claim 41, wherein the predictive action comprises updating a baseline tracking rate associated with the one or more of the other sensors.

43. The method of Claim 41, wherein the predictive action comprises increasing
5 a sensor scan rate associated with the one or more of the other sensors.

44. The method of Claim 41, wherein the predictive action comprises forcing measurements of temperatures associated with the one or more of the other sensors before sensor scanning of the one or more of the other sensors.

10

45. The method of any of Claims 26-28, wherein the event comprises an indication of a catastrophic fault associated with the first sensor.

46. The method of Claim 45, wherein the predictive action comprises inferring
15 that the same catastrophic fault exists at the one or more of the other sensors.

47. The method of Claim 45, wherein the predictive action comprises determining if the catastrophic fault exists at the one or more of the other sensors before sensor scanning of the one or more of the other sensors.

20

48. The method of Claim 45, wherein the predictive action comprises discarding measurement of the first sensor and using the one or more of the other sensors to determine the one or more physical quantities.

25 49. The method of Claim 45, wherein the predictive action comprises deploying a backup sensor to the first sensor.

50. The method of any of Claims 26-28, wherein the predictive action for a second sensor of the one or more of the other sensors is based on a physical proximity of
30 the second sensor to the first sensor.

51. A mobile device comprising:
- a housing;
 - a plurality of sensors housed within or upon the housing;
 - a measurement circuit communicatively coupled to the plurality of sensors and
- 5 configured to measure one or more physical quantities associated with the plurality of sensors; and
- a predictive optimization subsystem configured to:
 - detect an event associated with a first sensor of the plurality of sensors; and
 - responsive to the event, execute a predictive action with respect to one or
- 10 more of the other sensors of the plurality of sensors.

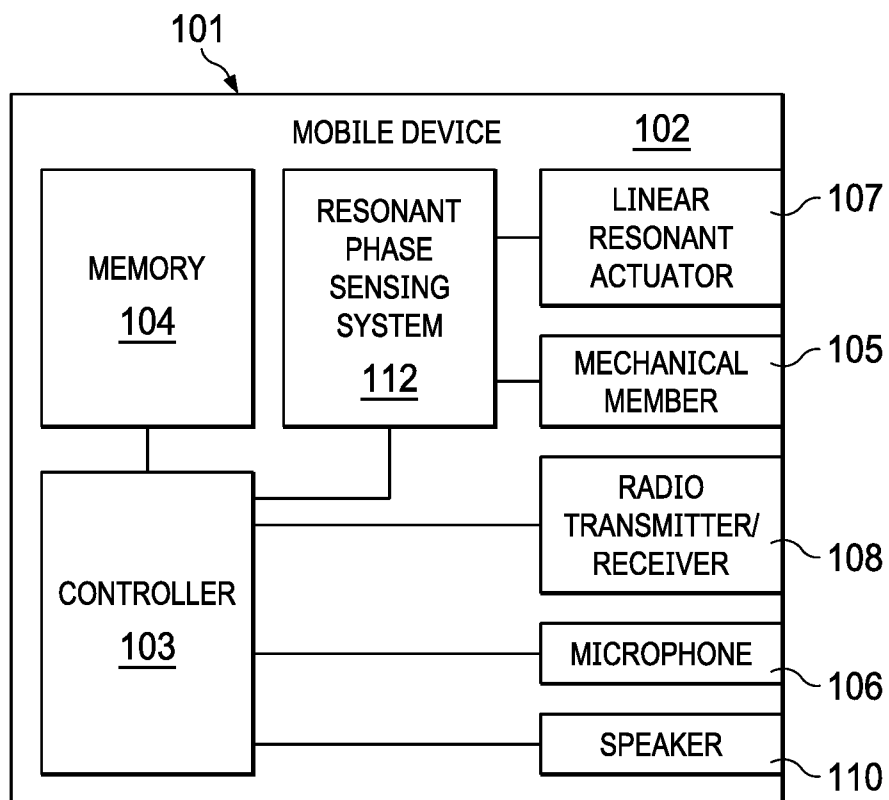


FIG. 1

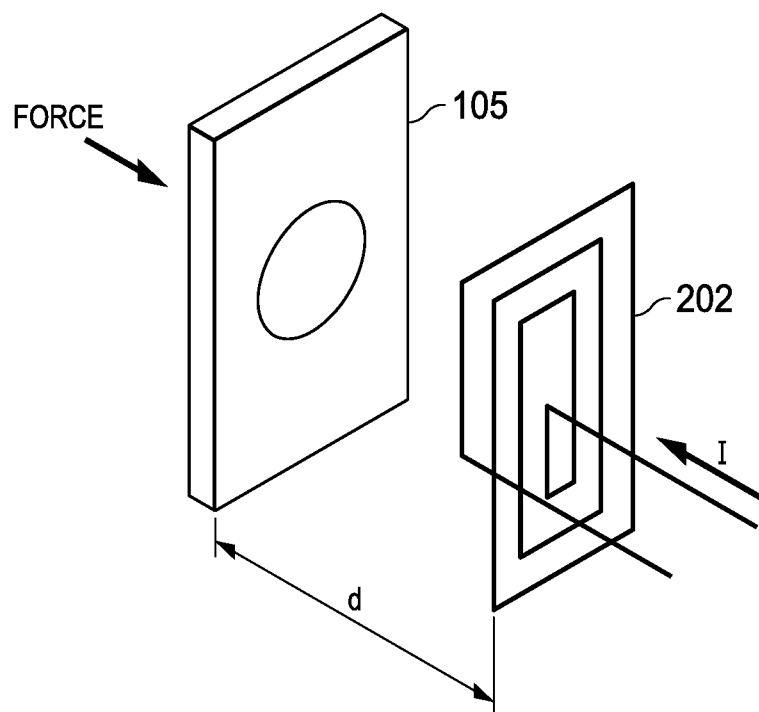
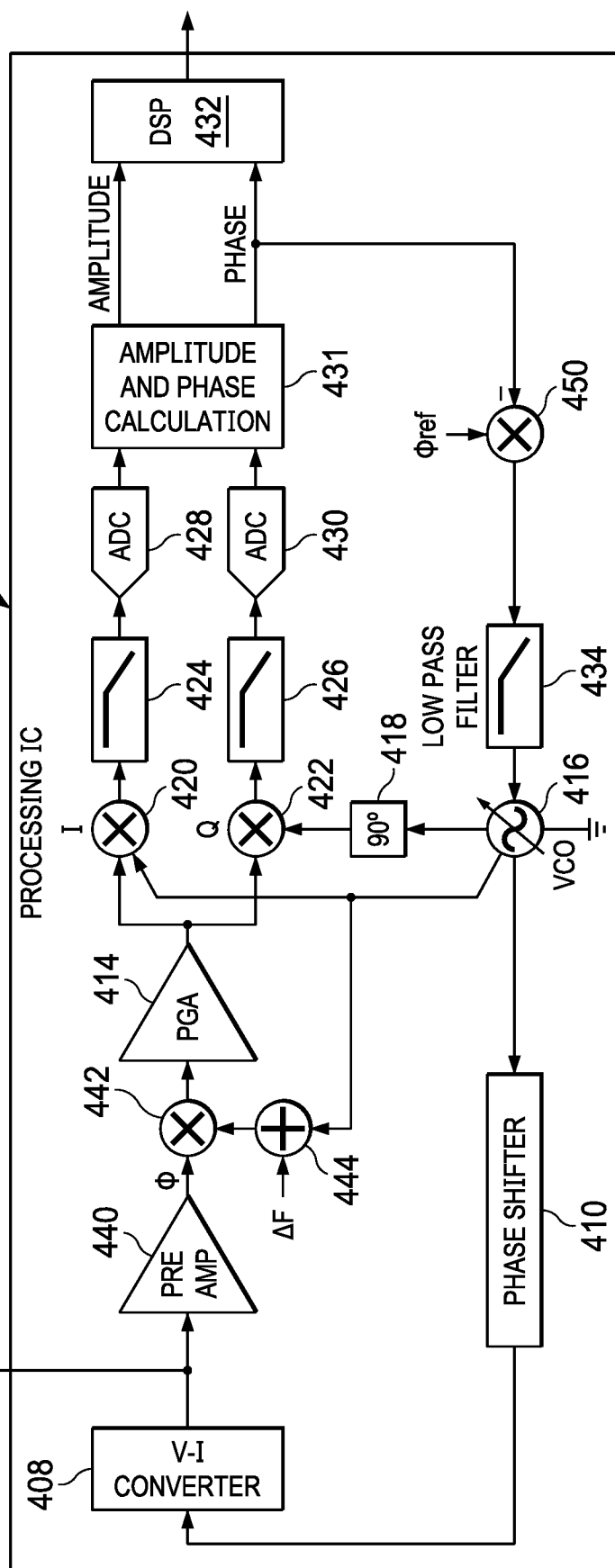
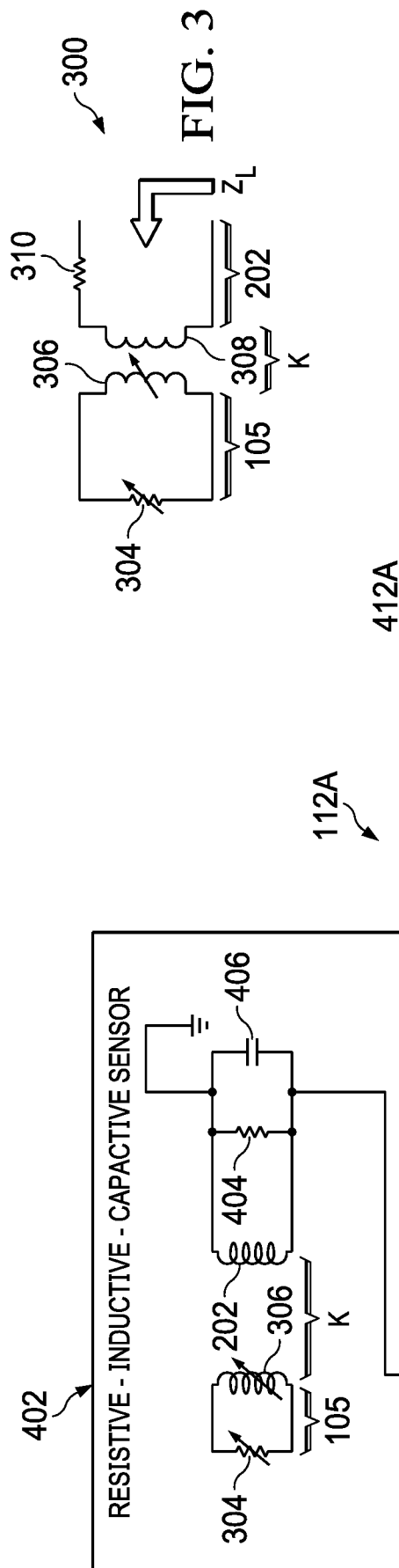


FIG. 2



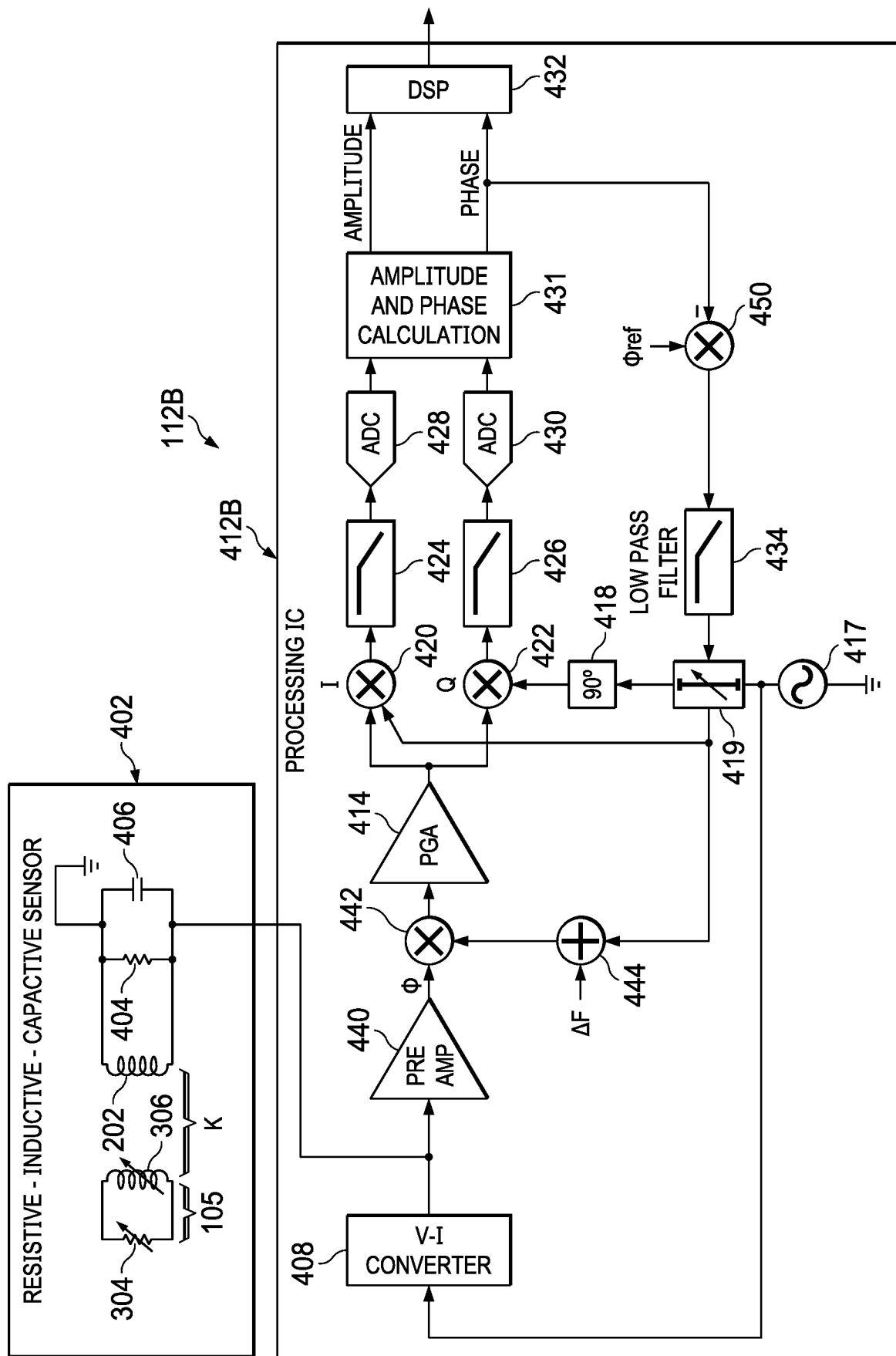


FIG. 4B

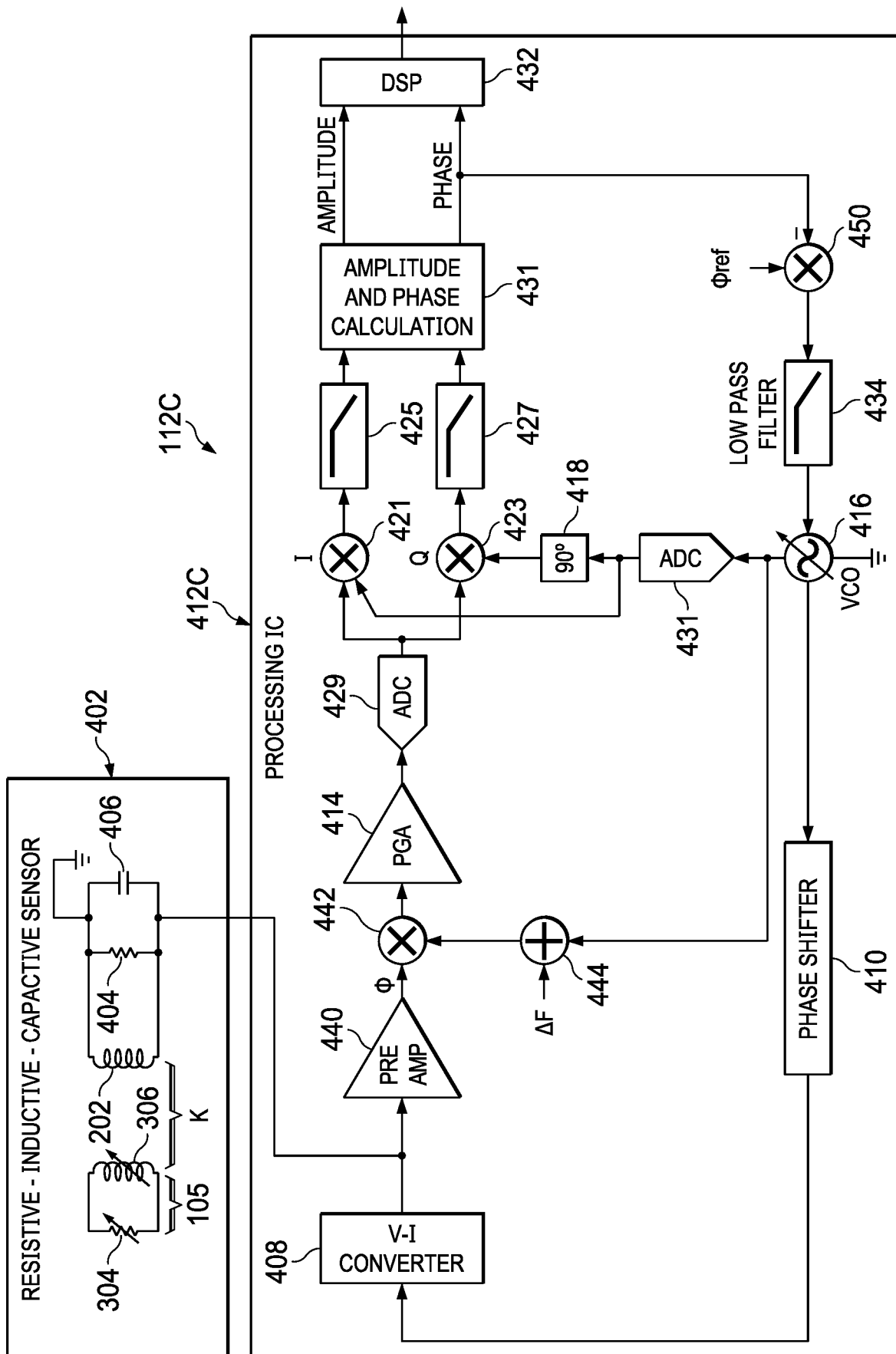


FIG. 4C

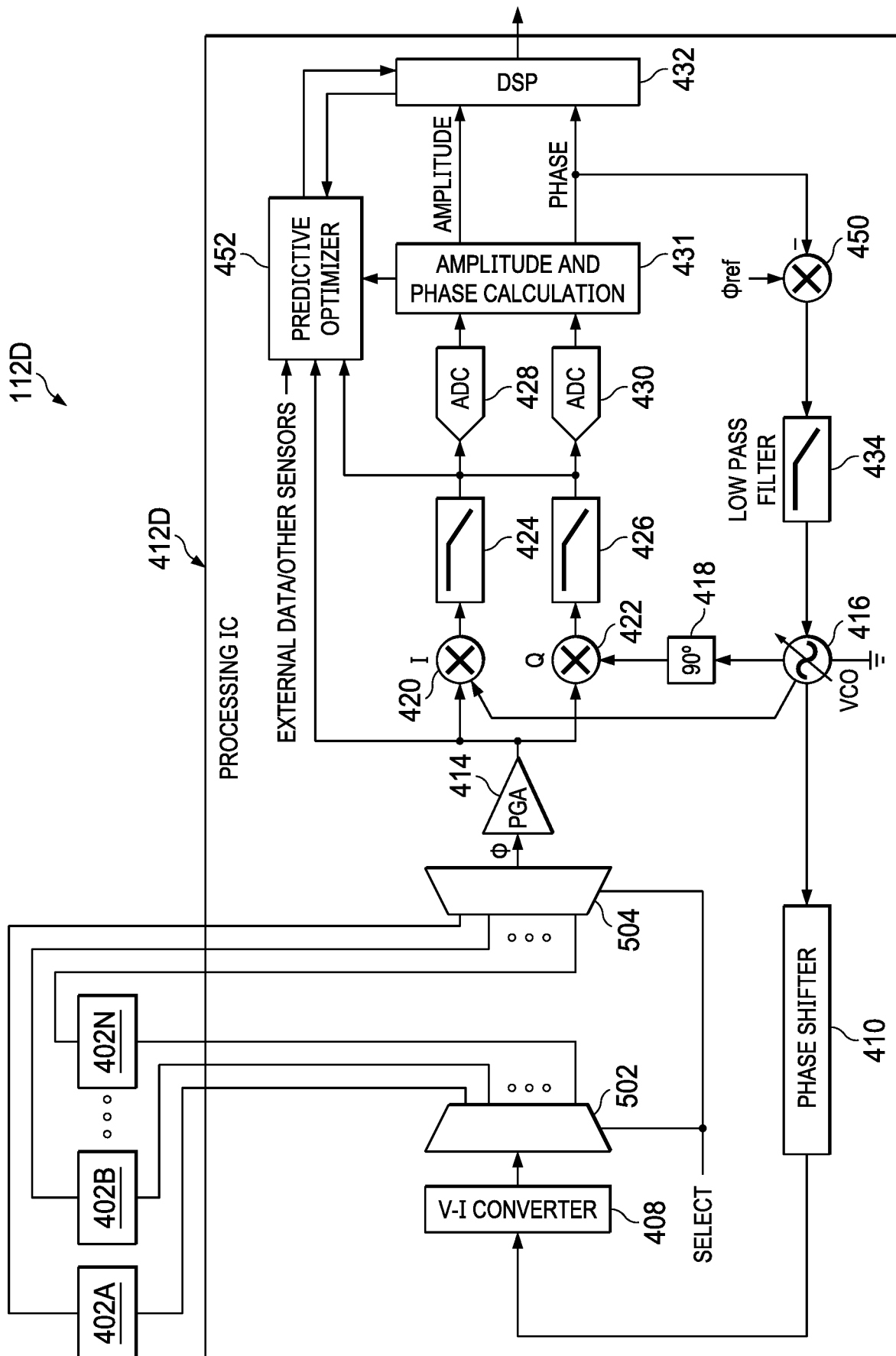


FIG. 5

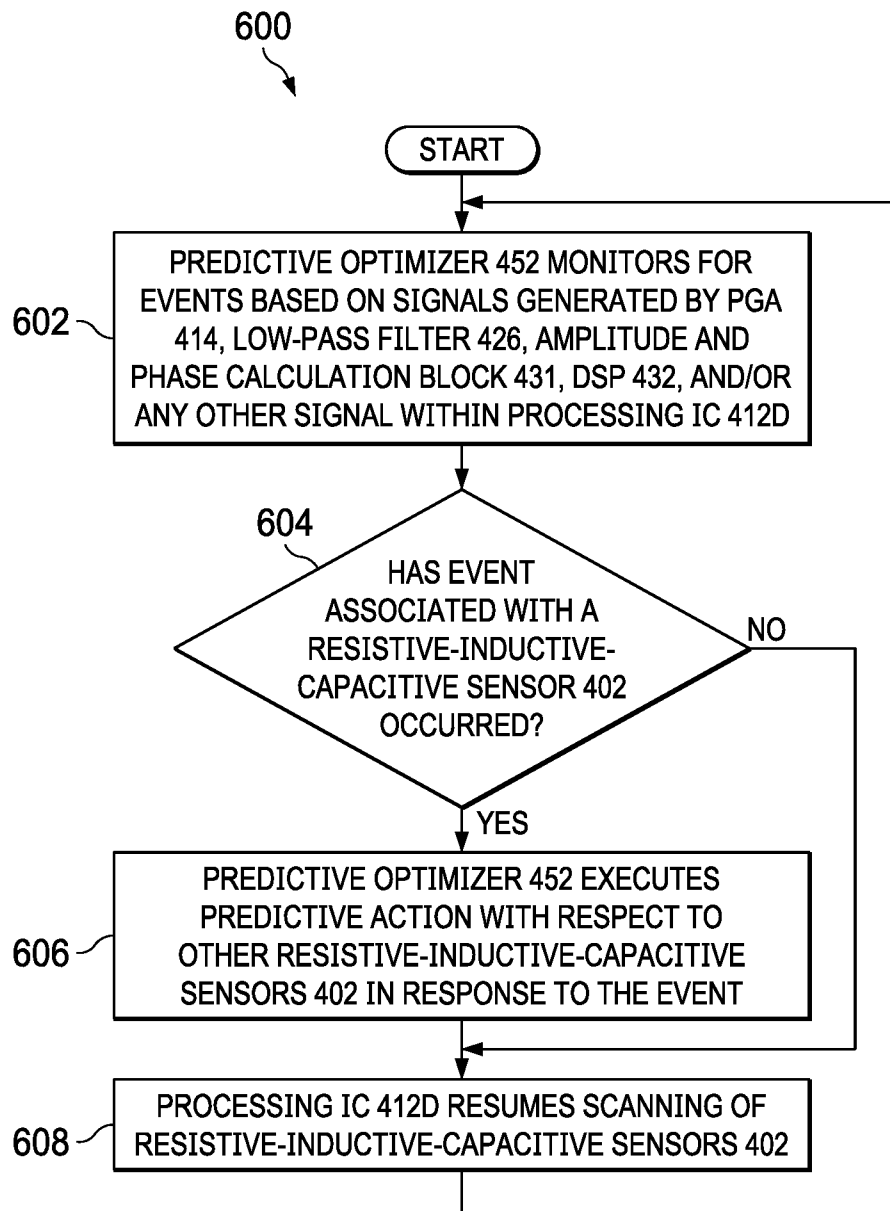


FIG. 6

INTERNATIONAL SEARCH REPORT

International application No
PCT/US2022/012721

A. CLASSIFICATION OF SUBJECT MATTER

INV. G01D5/20 G01D18/00 G01D21/02
ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

G01D

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 2020/064160 A1 (MARU SIDDHARTH [US] ET AL) 27 February 2020 (2020-02-27) Abstract, Desc. [0020]-[0058], Figs. 1-6 -----	1-51
X	US 2006/293864 A1 (SOSS DAVID A [US]) 28 December 2006 (2006-12-28) Abstract, Desc. [0002], [0038]-[0040], Fig. 5 -----	1, 3, 4, 13, 20, 21, 26, 28, 29, 38, 45, 46
X	CN 209 069 345 U (NANNING COLLEGE VOCATIONAL TECH) 5 July 2019 (2019-07-05) Abstract ----- -/-	1, 16, 20, 21, 26, 41, 45, 46



Further documents are listed in the continuation of Box C.



See patent family annex.

* Special categories of cited documents :

"A" document defining the general state of the art which is not considered to be of particular relevance

"E" earlier application or patent but published on or after the international filing date

"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)

"O" document referring to an oral disclosure, use, exhibition or other means

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"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

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Date of the actual completion of the international search

12 April 2022

Date of mailing of the international search report

26/04/2022

Name and mailing address of the ISA/

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Authorized officer

Reim, Klaus

INTERNATIONAL SEARCH REPORT

International application No
PCT/US2022/012721

C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 2009/308155 A1 (ZHANG WENWEI [GB]) 17 December 2009 (2009-12-17) Abstract, Desc. [0004], [0023] -----	1, 16, 17, 26, 41, 42

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No

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