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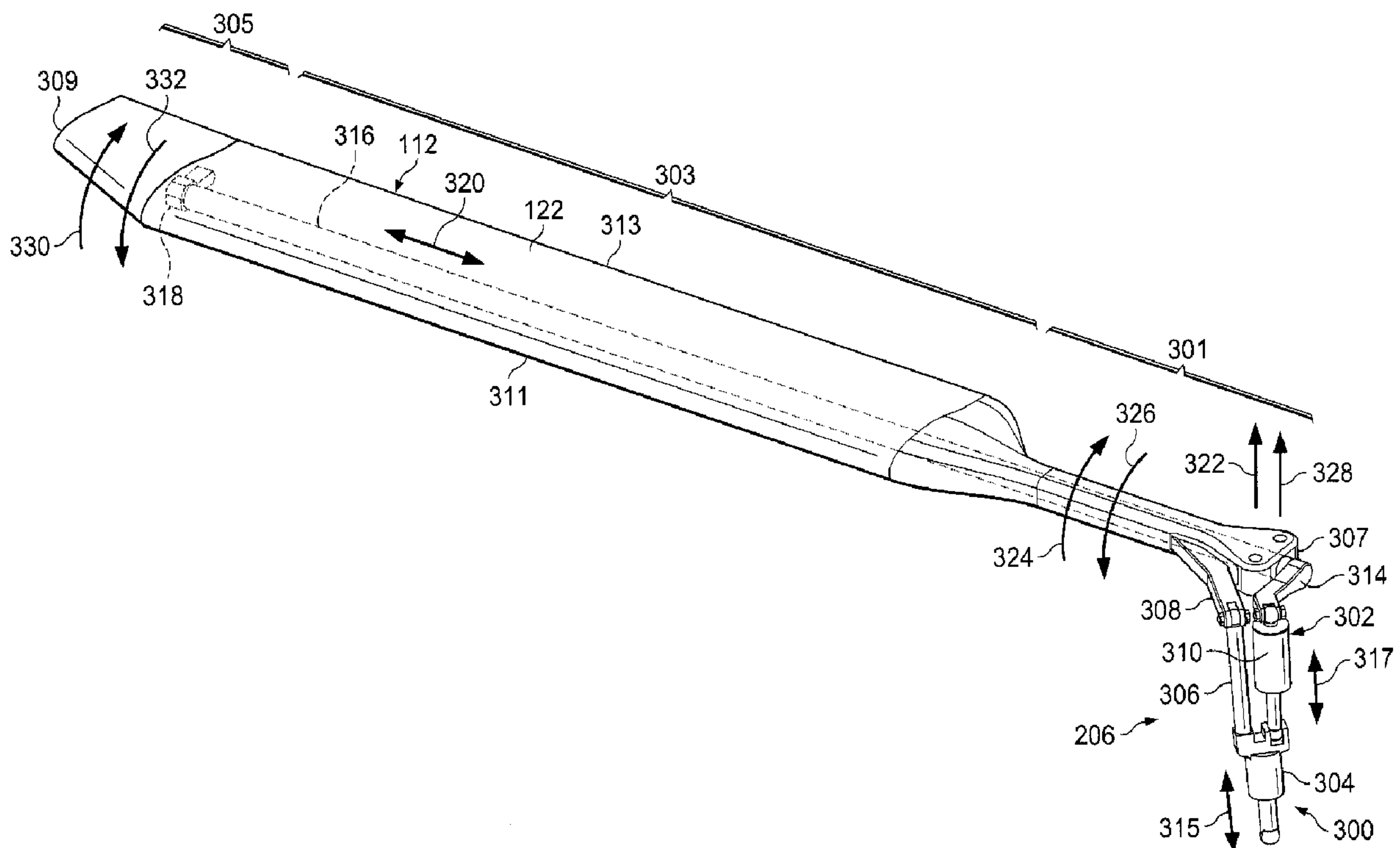
(71) Demandeur/Applicant:
THE BOEING COMPANY, US

(72) Inventeurs/Inventors:
ZIENTEK, THOMAS A., US;
BIRCHETTE, TERRENCE S., US;
STRAUB, FRIEDRICH K., US

(74) Agent: SIM & MCBURNEY

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(54) Title: APPARATUS, SYSTEM, AND METHOD FOR PITCHING AND TWISTING A BLADE OF A ROTORCRAFT



(57) Abrégé/Abstract:

A method and apparatus for moving a blade of a rotorcraft. The method comprises operating the rotorcraft and applying a torque to an elongate member connected to a tip portion of the blade during operation of the rotorcraft using a tip actuation mechanism that is external to the blade and associated with the elongate member such that the tip portion of the blade rotates about an axis through the blade.



ABSTRACT

A method and apparatus for moving a blade of a rotorcraft. The method comprises operating the rotorcraft and applying a torque to an elongate member connected to a tip portion of the blade during operation of the rotorcraft using a tip actuation mechanism that is external to the blade and associated with the elongate member such that the tip portion of the blade rotates about an axis through the blade.

APPARATUS, SYSTEM, AND METHOD FOR PITCHING AND TWISTING A BLADE OF A ROTORCRAFT

BACKGROUND INFORMATION

1. Field:

[0001] The present disclosure relates generally to the blades of a rotorcraft and, in particular, to a system for moving the blade of a rotorcraft. Still more particularly, the present disclosure relates to an apparatus, system, and method for pitching and twisting the blade of a rotorcraft using an actuation system that is external to the blade and located at a root portion of the blade.

2. Background:

[0002] A rotorcraft is a type of aircraft that operates using the lift generated by blades revolving around a mast. A helicopter is an example of a rotorcraft. The blades of a rotorcraft may be part of a rotor system. In some cases, these blades are referred to as rotor blades. The blades of a rotorcraft may be pitched and/or twisted during operation to generate the lift needed to allow the rotorcraft to hover and/or fly.

[0003] Pitching a blade means rotating the blade about an axis through the length of the blade. Pitching may be used to control the direction in which the maximum amount of thrust is generated by the rotorcraft. Twisting a blade means twisting the blade about an axis extending from one end of the blade to another end of the blade. Typically, a blade is twisted with respect to the axis about which the blade rotates or pitches. Changing the amount of twisting of the blades of a rotorcraft in different flight regimes may improve the efficiency of

the rotorcraft. The different flight regimes for a rotorcraft may include hover, climb, descent, and forward flight. Further, the rotorcraft may perform maneuvers that may include some combination of the above regimes.

[0004] Some currently available systems for twisting a blade use piezoelectric actuators mounted to the blade. However, these types of actuators may require a higher voltage to be supplied to the actuators than desired. Further, supplying voltage to these actuators may require that power lines be run along the length of the blade to reach the actuators mounted on the blade.

[0005] Other currently available systems for twisting a blade use shape memory alloys. However, shape memory alloys may have slower actuation times than desired. Consequently, changing the degree of twisting of a blade may take longer than desired.

[0006] Further, some currently available systems for twisting a blade may use actuators that are heavier than desired and/or that change the overall contour of the blade when mounted to the blade more than desired. This increased weight and/or change in contour may reduce the performance of the blade during operation of the rotorcraft more than desired. Therefore, it would be desirable to have an apparatus, system, and method that take into account at least some of the issues discussed above, as well as other possible issues.

SUMMARY

[0007] In one illustrative embodiment, an apparatus comprises a blade of a rotorcraft and a tip actuation mechanism that is external to the blade and associated with an elongate member that is connected to a tip portion of the blade. The tip actuation mechanism is

configured to apply a torque to the elongate member such that the tip portion of the blade rotates about an axis through the blade.

[0008] In another illustrative embodiment, a rotor system comprises a plurality of blades and a pitch and twist system comprising a plurality of actuation systems. Each of the plurality of actuation systems is associated with a corresponding one of the plurality of blades and comprises a root actuation and a tip actuation mechanism that are external to a blade. The root actuation mechanism is associated with a root portion of the blade and is configured to apply a first torque to the root portion of the blade such that the root portion of the blade rotates about an axis. The tip actuation mechanism is associated with an elongate member that is connected to a tip portion of the blade. The tip actuation mechanism is configured to apply a second torque to the elongate member such that the tip portion of the blade rotates about the axis.

[0009] In still yet another illustrative embodiment, a method for moving a blade of a rotorcraft is provided. The method comprises operating the rotorcraft and applying a torque to an elongate member connected to a tip portion of the blade during operation of the rotorcraft using a tip actuation mechanism that is external to the blade and associated with the elongate member such that the tip portion of the blade rotates about an axis through the blade.

[0010] The features and functions can be achieved independently in various embodiments of the present disclosure or may be combined in yet other embodiments in which further details can be seen with reference to the following description and drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

[0011] The novel features believed characteristic of the illustrative embodiments are set forth in the appended claims. The illustrative embodiments, however, as well as a preferred mode of use, further objectives and features thereof, will best be understood by reference to the following detailed description of an illustrative embodiment of the present disclosure when read in conjunction with the accompanying drawings, wherein:

[0012] **Figure 1** is an illustration of an isometric view of a rotorcraft in accordance with an illustrative embodiment;

[0013] **Figure 2** is an illustration of an enlarged isometric view of a portion of main rotor system in accordance with an illustrative embodiment;

[0014] **Figure 3** is an illustration of an isometric view of an actuation system associated with a blade in accordance with an illustrative embodiment;

[0015] **Figure 4** is an illustration of a side view of a portion of a rotor system in accordance with an illustrative embodiment;

[0016] **Figure 5** is an illustration of a top view of a portion of a rotor system in accordance with an illustrative embodiment;

[0017] **Figure 6** is an illustration of various potential configurations for an actuation system in accordance with an illustrative embodiment;

[0018] **Figure 7** is an illustration of a portion of a rotor system in accordance with an illustrative embodiment;

[0019] **Figure 8** is an illustration of a process for moving a blade of a rotorcraft in the form of a flowchart in accordance with an illustrative embodiment; and

[0020] **Figure 9** is an illustration of a process for improving the performance of a rotorcraft during flight in the form of a flowchart in accordance with an illustrative embodiment.

DETAILED DESCRIPTION

[0021] The illustrative embodiments provide a pitch and twist system that may be used to control the pitching and twisting of the rotor blades of a rotorcraft. The pitch and twist system includes actuation systems, each of which may be configured to control the motion of a corresponding rotor blade of the rotorcraft. The pitch and twist system provided by the different illustrative embodiments takes into account various considerations.

[0022] For example, an actuation system in this pitch and twist system may be used to pitch a rotor blade at higher pitch frequencies than is allowed with some currently available actuation systems. A rotor blade may be configured to pitch within a selected range. The "pitch frequency" of the rotor blade may be the number of cycles through this selected range that the rotor blade completes per revolution of the rotor blade about the mast of the rotor system.

[0023] Further, the actuation system may be used to change the amount of twisting of the rotor blade during any one of or any combination of flight regimes for the rotorcraft. The illustrative embodiments recognize and take into account that some currently available actuation systems may be unable to change the amount of twisting of

a rotor blade during flight regimes such as, for example, without limitation, forward flight.

[0024] However, the actuation system provided by the illustrative embodiments allows changes to the twisting of the rotor blade during flight such that the performance of the rotorcraft may be improved during flight. For example, vibrations and/or noise generated during flight of the rotorcraft may be reduced by changing the amount of twisting of the rotor blades of the rotorcraft during flight.

[0025] Referring now to the figures and, in particular, with reference to **Figure 1**, an illustration of an isometric view of a rotorcraft is depicted in accordance with an illustrative embodiment. Rotorcraft **100** may be an example of a vehicle in which the different illustrative embodiments may be implemented. Rotorcraft **100** is a helicopter in this illustrative example. As depicted, rotorcraft **100** has body **102** with main section **104** and tail section **106**. Further, rotorcraft **100** includes main rotor system **108** and tail rotor system **110**.

[0026] In this illustrative example, main rotor system **108** includes plurality of blades **112**, swashplate assembly **114**, pitch and twist system **116**, hub **118**, and mast **120**. Plurality of blades **112** includes blades **122**, **124**, **126**, and **128**. These blades may also be referred to as rotor blades in some cases. As depicted, blades **122**, **124**, **126**, and **128** are attached to hub **118**. Hub **118**, in turn, is attached to mast **120**.

[0027] Mast **120** may extend from a transmission system (not shown in this view) in rotorcraft **100**. This transmission system is configured to rotate mast **120** about center axis **130** through mast **120** in one of the directions along arrow **132** during operation of rotorcraft **100**. Rotation of mast **120**, in turn, causes rotation of

hub **118** and thereby, plurality of blades **112**, about center axis **130**.

[0028] One or more of plurality of blades **112** may be pitched during rotation of plurality of blades **112** about center axis **130**. As used herein, "pitching" a blade means rotating an entirety of the blade about an axis through the length of the blade by a same amount and in a same direction. The pitching of plurality of blades **112** may occur cyclically during operation of rotorcraft **100**. In this illustrative example, pitching may be used to control the direction in which the maximum amount of thrust is generated by rotorcraft **100**.

[0029] Further, one or more of plurality of blades **112** may be twisted during operation of rotorcraft **100**. As used herein, "twisting" a blade may mean twisting the blade about an axis extending from one end of the blade to another end of the blade. In other words, one portion of the blade may be rotated about this axis differently from at least one other portion of the blade. Twisting may be used to control the lift generated by rotorcraft **100** during flight. In particular, increasing the amount of twisting of each of plurality of blades **112** may increase the lift generated by rotorcraft **100**.

[0030] In this illustrative example, swashplate assembly **114** and pitch and twist system **116** may be used to control the movement of plurality of blades **112**. Pitch and twist system **116** is associated with plurality of blades **112** and swashplate assembly **114** in this illustrative example.

[0031] As used herein, when one component is "associated" with another component, the association is a physical association in the depicted examples. For example, a first component, such as pitch and twist system **116**, may be considered to be associated with a

second component, such as a blade in plurality of blades **112**, by being secured to the second component, bonded to the second component, mounted to the second component, welded to the second component, fastened to the second component, and/or connected to the second component in some other suitable manner.

[0032] Further, the first component also may be connected to the second component using a third component. The first component may also be considered to be associated with the second component by being formed as part of and/or an extension of the second component.

[0033] With reference now to **Figure 2**, an illustration of an enlarged isometric view of a portion of main rotor system **108** from **Figure 1** is depicted in accordance with an illustrative embodiment. In **Figure 2**, an enlarged view of a portion of main rotor system **108** from **Figure 1** is depicted such that swashplate assembly **114** and pitch and twist system **116** may be more clearly seen.

[0034] As depicted, swashplate assembly **114** includes first swashplate **202** and second swashplate **204**. In this illustrative example, first swashplate **202** is configured to rotate about center axis **130** as mast **120** rotates about center axis **130**. However, second swashplate **204** may not be configured to rotate about center axis **130** in this illustrative example.

[0035] Pitch and twist system **116** is associated with first swashplate **202**. As depicted, pitch and twist system **116** includes actuation systems **206**, **208**, **210**, and **212**. These actuation systems are associated with first swashplate **202** in this illustrative example. Further, these actuation systems are movably connected to first swashplate **202**.

[0036] As used herein, when a first component, such as actuation system **206**, is "movably connected" to a second

component, such as first swashplate **202**, each of the first component and the second component may be moved relative to the other. In this manner, each of actuation systems **206**, **208**, **210**, and **212** may be connected to first swashplate **202** in a manner that allows the actuation system to be moved relative to first swashplate **202**.

[0037] Actuation systems **206**, **208**, **210**, and **212** are also associated with blades **122**, **124**, **126**, and **128** respectively. Each of actuation systems **206**, **208**, **210**, and **212** is externally located with respect to the corresponding blade. In this manner, these actuations systems do not change the shape or contour of the corresponding blades and do not add additional weight to the corresponding blades. Each of actuation systems **206**, **208**, **210**, and **212** may be used to pitch and/or twist the corresponding blade with which the actuation system is associated.

[0038] With reference now to **Figure 3**, an illustration of an isometric view of actuation system **206** associated with blade **122** from **Figure 2** is depicted in accordance with an illustrative embodiment. As depicted, blade **122** has root portion **301**, middle portion **303**, and tip portion **305**. Further, blade **122** has leading edge **311** and trailing edge **313**.

[0039] Root portion **301** of blade **122** is the portion of blade **122** between first end **307** of blade **122** and a location on blade **122** near first end **307**. Middle portion **303** of blade **122** is located between root portion **301** of blade **122** and tip portion **305** of blade **122**. Tip portion **305** of blade **122** is the portion of blade **122** between second end **309** of blade **122** and a location on blade **122** near second end **309** of blade **122**. In this illustrative example, first end **307** of blade **122** may be referred to as

the "root" of blade **122**, while second end **309** of blade **122** may be referred to as the "tip" of blade **122**.

[0040] As depicted, actuation system **206** is associated with root portion **301** of blade **122**. In other words, actuation system **206** is located near first end **307** of blade **122**. In this illustrative example, actuation system **206** includes root actuation mechanism **300**, tip actuation mechanism **302**, and member **306**. Root actuation mechanism **300**, tip actuation mechanism **302**, and member **306** are located outside of blade **122**. In this manner, actuation system **206** is external to blade **122**.

[0041] Root actuation mechanism **300** takes the form of linear actuator **304** in this illustrative example. Linear actuator **304** is configured to create a force in a direction along axis **315**. In particular, linear actuator **304** is configured to lengthen and shorten with respect to axis **315**. The lengthening or shortening of linear actuator **304** creates a force in a direction along axis **315**.

[0042] Linear actuator **304** may take various forms. For example, linear actuator **304** may take the form of a hydraulic linear actuator, an electromechanical linear actuator, a pneumatic linear actuator, a piezoelectric linear actuator, or some other type of linear actuator.

[0043] In this illustrative example, linear actuator **304** is rigidly connected to member **306**. As used herein, when a first component, such as linear actuator **304**, is "rigidly connected" to a second component, such as member **306**, these components are unable to move relative to each other. In other words, movement of one of the components may cause a similar type of movement in the other component. In other words, the connection is a fixed connection. In one illustrative example, movement of linear actuator **304** in a particular direction along axis

315 causes a substantially equal amount of movement of member **306** in the same direction along axis **315**.

[0044] Member **306** takes the form of a structural link in this example. As depicted, member **306** is movably connected to part **308** of blade **122** at root portion **301** of blade **122**. Part **308** is monolithic with blade **122** in this illustrative example. However, in other illustrative examples, part **308** may be a separate member that is rigidly connected to blade **122**.

[0045] Tip actuation mechanism **302** takes the form of linear actuator **310**. Linear actuator **310** is configured to also create a force in a direction along axis **317**. In particular, linear actuator **310** is configured to lengthen and shorten with respect to axis **317**. The lengthening or shortening of linear actuator **310** creates a force in a direction along axis **317**.

[0046] Linear actuator **310** may take various forms. For example, similar to linear actuator **304**, linear actuator **310** may take the form of a hydraulic linear actuator, an electromechanical linear actuator, a pneumatic linear actuator, a piezoelectric linear actuator, or some other type of linear actuator.

[0047] Linear actuator **310** is movably connected to linear actuator **304**. Further, linear actuator **310** is movably connected to part **314** of elongate member **316** in this illustrative example. Part **314** is monolithic with elongate member **316** in this illustrative example. However, in other illustrative examples, part **314** may be a separate component that is rigidly connected to elongate member **316**.

[0048] Elongate member **316** may be referred to as a torque tube in this illustrative example. Elongate member **316** is connected to tip portion **305** of blade **122**. In particular, part **318** of elongate member **316** is

connected to tip portion **305** of blade **122**. Part **318** is monolithic with elongate member **316** in this illustrative example. However, in other illustrative examples, part **318** may be a separate component that is rigidly connected to elongate member **316**. In this illustrative example, elongate member **316** may not be connected to any other portion of blade **122**.

[0049] When linear actuator **304** lengthens, force **322** is generated. Force **322** may be transferred to part **308** of blade **122** at root portion **301** of blade **122**. The transferring of force **322** to part **308** applies torque **324** to root portion **301**, which rotates root portion **301** about pitch axis **320** through blade **122**.

[0050] When linear actuator **304** shortens, a force that is opposite to force **322** is generated. The transfer of this opposite force to part **308** applies torque **326** to root portion **301**, which rotates root portion **301** about pitch axis **320**. As depicted, torque **326** is opposite to torque **324**. In this manner, the rotation of root portion **301** about pitch axis **320** caused by torque **326** may be in a direction opposite to the rotation of root portion **301** caused by torque **324**.

[0051] Additionally, when linear actuator **310** lengthens, force **328** is generated. Force **328** may be transferred to part **314** of elongate member **316**. The transfer of force **328** to part **314** applies torque **330** to elongate member **316**, and thereby, tip portion **305** of blade **122** connected to elongate member **316**. Torque **330** causes tip portion **305** to rotate about pitch axis **320**.

[0052] When linear actuator **310** shortens, a force that is opposite to force **328** is generated. The transfer of this opposite force to part **314** applies torque **332** to elongate member **316**, and thereby, tip portion **305**, which rotates tip portion **305** about pitch axis **320**. As

depicted, torque **332** is opposite to torque **330**. In this manner, the rotation of tip portion **305** about pitch axis **320** caused by torque **332** may be in a direction opposite to the rotation of tip portion **305** caused by torque **330**.

[0053] Further, in this illustrative example, linear actuator **310** may move when linear actuator **304** lengthens or shortens. The movement of linear actuator **310** generates a force that may be transferred to part **314** of blade **122**. The transfer of this force may apply torque **324** or torque **326** to elongate member **316**, and thereby, tip portion **305** of blade **122**, depending on the movement of linear actuator **310**.

[0054] In this manner, a first torque may be applied to root portion **301** of blade **122** by root actuation mechanism **300**. A second torque may be applied to tip portion **305** of blade **122** by tip actuation mechanism **302**. The second torque may be caused by the lengthening or shortening of tip actuation mechanism **302** and/or the movement of tip actuation mechanism **302** in response to the lengthening or shortening of root actuation mechanism **300**.

[0055] When the first torque applied to root portion **301** of blade **122** and the second torque applied to tip portion **305** of blade **122** are substantially equal and in the same direction, the entirety of blade **122** rotates about pitch axis **320** by the same amount. In other words, when the first torque and the second torque are substantially equal and in the same direction, the entirety of blade **122** pitches by the same amount. The entirety of blade **122** includes root portion **301**, middle portion **303**, and tip portion **305**.

[0056] However, when the first torque applied to root portion **301** of blade **122** and the second torque applied to tip portion **305** of blade **122** are not substantially equal

and/or are not in the same direction, root portion **301** of blade **122** rotates about pitch axis **320** of blade **122** differently from tip portion **305** of blade **122**. In other words, blade **122** twists. The degree of twisting of blade **122** depends on the magnitude and direction of the first torque and the second torque.

[0057] In this illustrative example, actuation system **206** may be used to change the amount of twisting of blade **122** during different flight regimes of rotorcraft **100**. This type of twisting of blade **122** may be referred to as dynamic twisting.

[0058] Further, actuation system **206** may be used to pitch blade **122** at a pitch frequency within a selected range. In some cases, blade **122** may be pitched at a pitch frequency greater than about once per revolution. Of course, in other illustrative examples, blade **122** may be configured to be pitched at some other pitch frequency.

[0059] Actuation system **206** may be operated such that blade **122** cycles through this selected range more than once per revolution. For example, during flight of rotorcraft **100**, actuation system **206** may be operated such that the pitch frequency for blade **122** is twice per revolution about mast **120**, three times per revolution about mast **120**, five times per revolution about mast **120**, ten times per revolution about mast **120**, or some other pitch frequency above once per revolution about mast **120**.

[0060] In this illustrative example, actuation systems **206**, **208**, **210**, and **212** in **Figure 2** may be used to pitch and/or twist blades **122**, **124**, **126**, and **128**, respectively, together or independently of each other. For example, blade **122** and **126** may be pitched at higher frequencies than blade **124** and blade **128** during forward flight. As another example, the amount of twisting of blade **122** and

blade **126** may be changed during forward flight while the amount of twisting of blade **124** and blade **128** is left unchanged.

[0061] The illustrations of rotorcraft **100** in **Figure 1**, main rotor system **108** in **Figure 2**, and actuation system **206** in **Figure 3** are not meant to imply physical or architectural limitations to the manner in which an illustrative embodiment may be implemented. Other components in addition to or in place of the ones illustrated may be used. Some components may be optional. Another configuration for an actuation system is depicted in **Figures 4-5**.

[0062] With reference now to **Figure 4**, an illustration of a side view of a portion of a rotor system is depicted in accordance with an illustrative embodiment. In this illustrative example, rotor system **400** includes swashplate assembly **402**, mast **404**, hub **406**, and blade **408**. Blade **408** is connected to hub **406** and configured to revolve around mast **404**. Blade **408** may be described as having root portion **409**, tip portion **411**, and middle portion **413** located between root portion **409** and tip portion **411**.

[0063] As depicted, swashplate assembly **402** includes first swashplate **410** and second swashplate **412**. First swashplate **410** is associated with second swashplate **412** through ball bearings **414**. Ball bearings **414** allow first swashplate **410** to rotate relative to second swashplate **412**.

[0064] In this illustrative example, set of linear actuators **416** are associated with second swashplate **412**. Set of linear actuators **416** may be used to move swashplate assembly **402** vertically and/or tilt swashplate assembly **402**.

[0065] Actuation system **418** is associated with both swashplate assembly **402** and blade **408**. Actuation system **418** is external to blade **408**. Actuation system **418** may have a configuration different from actuation system **206** in **Figures 2-3**.

[0066] As depicted, actuation system **418** includes root actuation mechanism **420**, tip actuation mechanism **422**, and member **424**. In this illustrative example, root actuation mechanism **420** takes the form of linear actuator **421** and tip actuation mechanism **422** takes the form of linear actuator **423**.

[0067] Linear actuator **421** and linear actuator **423** are both movably connected to member **424**. Member **424** is rigidly connected to first swashplate **410**.

[0068] Linear actuator **421** is associated with root portion **409** of blade **408**. Linear actuator **421** is configured to generate a first force that may be used to apply a first torque to the entirety of blade **408**. Linear actuator **423** is associated with elongate member **426** within blade **408**. Elongate member **426** is connected to tip portion **411** of blade **408**. Linear actuator **423** is configured to generate a second force that may be used to apply a second torque to elongate member **426**, and thereby, tip portion **411** of blade **408**.

[0069] Root actuation mechanism **420** and tip actuation mechanism **422** may not be coupled in this illustrative example. In other words, the lengthening or shortening of one of linear actuator **421** and linear actuator **423** may not cause movement of the other linear actuator.

[0070] Blade **408** may be pitched by lengthening linear actuator **421** and linear actuator **423** by the same amount or shortening linear actuator **421** and linear actuator **423** by the same amount. In other words, blade **408** may be

pitched by operating linear actuator **421** and linear actuator **423** in the same manner.

[0071] Blade **408** may be twisted by operating these linear actuators differently. For example, blade **408** may be twisted by lengthening one of linear actuator **421** and linear actuator **423** and shortening or not operating the other linear actuator.

[0072] As another example, blade **408** may be twisted by shortening one of linear actuator **421** and linear actuator **423** and lengthening or not operating the other linear actuator. As yet another example, blade **408** may be twisted by lengthening linear actuator **421** and linear actuator **423** by different amounts or shortening linear actuator **421** and linear actuator **423** by different amounts.

[0073] Turning now to **Figure 5**, an illustration of a top view of rotor system **400** from **Figure 4** is depicted in accordance with an illustrative embodiment. As depicted, linear actuator **421** may be connected to blade **408** by member **500**. Linear actuator **423** may be connected to elongate member **426** by member **502**.

[0074] With reference now to **Figure 6**, an illustration of various potential configurations for an actuation system is depicted in accordance with an illustrative embodiment. Configurations **600** represent potential configurations for an actuation system for a blade. In particular, configurations **600** may be schematic representations of actuation systems.

[0075] As depicted, configurations **600** include configuration **602**, configuration **604**, configuration **608**, and configuration **610**. Each of these configurations for an actuation system includes a first actuation mechanism and a second actuation mechanism.

[0076] The first actuation mechanism may be associated with a root portion of a blade, while the second actuation mechanism may be associated with a tip portion of a blade through an elongate member. In this manner, the first actuation mechanism and the second actuation mechanism may be referred to as a root actuation mechanism and a tip actuation mechanism, respectively. The root actuation mechanism and the tip actuation mechanism may each be implemented using one or more actuators. For example, each of these actuation mechanisms may be implemented using a linear actuator or a rotary actuator.

[0077] Further, the members described in the configurations below may be rigid members of fixed length and size. Each of these members may be selected from one of, for example, without limitation, a structural link, a rod, a beam, a tube, or some other type of structural member.

[0078] Configuration **602** represents the same configuration used for actuation system **206** in **Figures 2-3**. The actuation system represented by configuration **602** includes swashplate assembly **612**, first linear actuator **614**, second linear actuator **616**, member **615**, and member **618**. As depicted, swashplate assembly **612** includes first swashplate **620** and second swashplate **622**. First swashplate **620** is associated with second swashplate **622** through ball bearings **624**. Ball bearings **624** allow first swashplate **620** to rotate relative to second swashplate **622**.

[0079] First linear actuator **614** is directly connected to first swashplate **620**. Member **615** is connected to first linear actuator **614**. Second linear actuator **616** and member **618** are connected to member **625**.

[0080] Member **618** may be associated with the root portion of a blade. Operation of first linear actuator **614** causes movement of member **618**, which in turn, causes the root portion of the blade to be rotated about a pitch axis through the blade.

[0081] Further, second linear actuator **616** may be associated with an elongate member that is connected to a tip portion of the same blade. Operation of first linear actuator **614** causes movement of second linear actuator **616**, which in turn, causes the tip portion of the blade to rotate about the pitch axis. Additionally, operation of second linear actuator **616** also causes the tip portion of the blade to rotate about the pitch axis.

[0082] With configuration **602**, pitching of the blade may require operation of both first linear actuator **614** and second linear actuator **616**. However, twisting of the blade may only require that at least one of first linear actuator **614** and second linear actuator **616** be operated.

[0083] Turning now to configuration **604**, the actuation system represented includes swashplate assembly **626**, first linear actuator **628**, second linear actuator **630**, member **632**, and member **633**. Configuration **604** represents the same configuration for actuation system **418** in **Figures 4-5**. As depicted, swashplate assembly **626** includes first swashplate **634** and second swashplate **636**, which are associated with each other through ball bearings **638**.

[0084] First linear actuator **628** and second linear actuator **630** are connected to first swashplate **634** through member **632** and member **633**. First linear actuator **628** may be associated with the root portion of a blade and used to rotate this root portion about a pitch axis through the blade. Second linear actuator **630** may be associated with an elongate member that is connected to a

tip portion of the same blade and used to rotate this tip portion about the pitch axis.

[0085] Pitching of this blade may require operation of both first linear actuator **628** and second linear actuator **630**. However, twisting of the blade may only require operation of at least one of first linear actuator **628** and second linear actuator **630**.

[0086] The actuation system represented by configuration **608** includes dual swashplate assembly **652**, root actuation mechanism **654**, tip actuation mechanism **656**, member **658**, and member **660**. Root actuation mechanism **654** includes linear actuators **662**, **664**, and **666**. Tip actuation mechanism **656** includes linear actuators **668**, **670**, and **672**.

[0087] As depicted, dual swashplate assembly **652** includes swashplates **674**, **676**, **678**, and **680**. Swashplate **674** and swashplate **676** are associated through ball bearings **682**. Swashplate **678** and swashplate **680** are associated through ball bearings **684**. Linear actuators **662**, **664**, and **666** of root actuation mechanism **654** are connected to swashplate **680**. Linear actuators **668**, **670**, and **672** of tip actuation mechanism **656** are connected to swashplate **676**. Further, member **658** is connected to swashplate **674**, while member **660** is connected to swashplate **678**.

[0088] Linear actuators **662**, **664**, and **666** may be used to move swashplate **680**, and thereby swashplate **678**, which in turn, moves member **660**. Member **660** may be associated with the root portion of a blade. Movement of member **660** may cause the root portion to be rotated about a pitch axis through the blade.

[0089] Linear actuators **668**, **670**, and **672** may be used to move swashplate **676**, and thereby swashplate **674**, which in turn, moves member **658**. Member **658** may be associated

with an elongate member that is connected to the tip portion of the blade. Movement of member **658** may cause the tip portion to be rotated about the pitch axis.

[0090] With configuration **608**, pitching of the blade may require operation of both root actuation mechanism **654** and tip actuation mechanism **656**. However, twisting of the blade may only require that at least one of root actuation mechanism **654** and tip actuation mechanism **656** be operated.

[0091] The actuation system represented by configuration **610** includes swashplate assembly **686**, linear actuator **688**, rotary actuator **690**, member **692**, member **694**, and member **695**. Swashplate assembly **686** includes first swashplate **696** and second swashplate **698** that are associated with each other by ball bearings **699**.

[0092] Linear actuator **688** is connected to first swashplate **696**. Member **695** is connected to linear actuator **688**. Member **692** and member **694** are connected to member **695**. Member **692** may be associated with a root portion of a blade. Rotary actuator **690** is connected to member **694**. Rotary actuator **690** may be associated with an elongate member that is connected to a tip portion of the blade.

[0093] Operation of linear actuator **688** causes movement of member **692** and member **694**. Movement of member **692** may cause rotation of the root portion of the blade about a pitch axis through the blade. Movement of member **694** may cause rotation of the tip portion of the blade about the pitch axis. Further, operation of rotary actuator **690** may also cause rotation of the tip portion of the blade about the pitch axis.

[0094] The illustration of configurations **600** for an actuation system in **Figure 6** is not meant to imply physical or architectural limitations to the manner in

which an illustrative embodiment may be implemented. Other components in addition to or in place of the ones illustrated may be used. Some components may be optional.

[0095] For example, in some cases, a configuration for the actuation system may include a rotary actuator associated with the root portion of the blade in addition to a rotary actuator associated with the elongate member connected to the tip portion of the blade. In this configuration, no linear actuators may be needed.

[0096] In still other illustrative examples, the actuation system may only include one actuation mechanism. For example, the single actuation mechanism may be used to twist the blade.

[0097] With reference now to **Figure 7**, an illustration of a portion of a rotor system is depicted in accordance with an illustrative embodiment. In this illustrative example, rotor system **700** includes mast **702**, hub **704**, and blade **706**. Blade **706** is connected to hub **704** and configured to revolve around mast **702**. Blade **706** may be described as having root portion **708**, tip portion **710**, and middle portion **712** located between root portion **708** and tip portion **710**.

[0098] Actuation system **713** is associated with root portion **708** of blade **706** but is external to blade **706**. Actuation system **713** comprises rotary actuator **714**. Rotary actuator **714** may be an example of one manner in which rotary actuator **690** in **Figure 6** may be implemented. However, no other actuators or actuation mechanism may be present in actuation system **713**. In other words, actuation system **713** may not include a linear actuator such as, for example, linear actuator **688** in **Figure 6**.

[0099] In this illustrative example, rotary actuator **714** is associated with elongate member **716** running

through blade **706**. Elongate member **716** may be referred to as a torque tube. Elongate member **716** may be connected to tip portion **710** of blade **706** but no other portion of blade **706**.

[00100] As depicted, rotary actuator **714** is located near root portion **708** of blade **706** but is external to blade **706**. Rotary actuator **714** may be used to rotate elongate member **716**. Rotating elongate member **716** causes tip portion **710** of blade **706** connected to elongate member **716** to rotate about pitch axis **718** through blade **706**. In particular, tip portion **710** of blade **706** may be rotated about pitch axis **718** relative to root portion **708** of blade **706**. In this manner, blade **706** may be twisted.

[00101] The illustration of rotor system **700** in **Figure 7** is not meant to imply physical or architectural limitations to the manner in which an illustrative embodiment may be implemented. Other components in addition to or in place of the ones illustrated may be used. Some components may be optional.

[00102] With reference now to **Figure 8**, an illustration of a process for moving a blade rotorcraft in the form of a flowchart is depicted in accordance with an illustrative embodiment. The process illustrated in **Figure 8** may be implemented using, for example, without limitation, pitch and twist system **116** from **Figure 1**.

[00103] The process begins by applying a first torque to a root portion of a blade using a root actuation mechanism associated with the root portion of the blade such that the root portion of the blade rotates about an axis through the blade (operation **800**). This axis may be, for example, a pitch axis through the blade.

[00104] Thereafter, a second torque is applied to an elongate member connected to a tip portion of the blade using a tip actuation mechanism associated with the

elongate member such that the elongate member and the tip portion of the blade rotate about the axis (operation **802**), with the process terminating thereafter. The elongate member may also be referred to as a torque tube. Further, the root actuation mechanism and the tip actuation mechanism may each take the form of a linear actuator, a rotary actuator, and/or one or more actuators of any number of types.

[00105] The root actuation mechanism and the tip actuation mechanism are part of an actuation system for the blade. Depending on the configuration for the actuation system, operation **800** and operation **802** may be performed simultaneously to pitch the blade. In some cases, only operation **800** may be needed to be performed to pitch the blade. Further, at least one of operation **800** and operation **802** may be performed to twist the blade.

[00106] With reference now to **Figure 9**, an illustration of a process for improving the performance of a rotorcraft during flight in the form of a flowchart is depicted in accordance with an illustrative embodiment. The process illustrated in **Figure 9** may be performed to improve the performance of a rotorcraft such as, for example, rotorcraft **100** in **Figure 1**.

[00107] The process begins by operating the rotorcraft (operation **900**). The rotorcraft may have a pitch and twist system, such as, for example, pitch and twist system **116** in **Figure 1**. The pitch and twist system may include an actuation system associated with each of the rotor blades of the rotorcraft. Each of these actuation systems may be implemented using any one of configurations **600** in **Figure 6**. Depending on the implementation, the same and/or different configurations

may be used for the different actuation systems associated with the different rotor blades.

[00108] During operation of the rotorcraft, at least one of the rotor blades of the rotorcraft is pitched at a selected pitch frequency using an actuation system associated with the at least one of the rotor blades of the rotorcraft (operation **902**). The selected pitch frequency may be, for example, a number of pitching cycles per revolution greater than, but not limited to, once per revolution. Pitching the rotor blades at a high pitch frequency may provide improved lift performance of the rotorcraft.

[00109] Further, during operation of the rotorcraft, the amount of twisting of at least one of the rotor blades of the rotorcraft is changed using an actuation system associated with the at least one of the rotor blades of the rotorcraft (operation **904**), with the process terminating thereafter. The amount of twisting of the at least one of rotor blades may be changed any number of times while the rotorcraft is any one or combination of the flight regimes of the rotorcraft.

[00110] In some cases, the twisting of a blade may be changed within a single revolution of the blade. The twisting of the rotor blades of the rotorcraft may be used to reduce the vibrations generated by the rotor blades and/or noise. In this manner, the aerodynamic performance of the rotorcraft may be improved.

[00111] The flowcharts and block diagrams in the different depicted embodiments illustrate the architecture, functionality, and operation of some possible implementations of apparatus and methods in an illustrative embodiment. In this regard, each block in the flowcharts or block diagrams may represent a module,

a segment, a function, and/or a portion of an operation or step.

[00112] In some alternative implementations of an illustrative embodiment, the function or functions noted in the blocks may occur out of the order noted in the figures. For example, in some cases, two blocks shown in succession may be executed substantially concurrently, or the blocks may sometimes be performed in the reverse order, depending upon the functionality involved. Also, other blocks may be added in addition to the illustrated blocks in a flowchart or block diagram.

[00113] Thus, the illustrative embodiments provide an actuation system that may be associated with a blade for a rotorcraft and used to pitch and/or twist the blade. In one illustrative embodiment, an actuation system comprises a root actuation mechanism and a tip actuation mechanism.

[00114] The root actuation mechanism is associated with a root portion of a blade and is configured to transfer a first force to the root portion of the blade. The transferring of this first force to the root portion of the blade applies a first torque to the root portion of the blade that moves the root portion of the blade. In particular, application of the first torque to the root portion of the blade causes the root portion of the blade to rotate about a pitch axis through the blade.

[00115] The tip actuation mechanism is associated with an elongate member at the root portion of the blade. The elongate member is associated with a tip portion of the blade. The portion of the elongate member at the root portion of the blade may be considered "free-floating" with respect to the root portion of the blade.

[00116] The tip actuation mechanism is configured to transfer a second force to the elongate member.

Transferring this first force to the elongate member applies a second torque to the elongate member and the tip portion of the blade associated with the elongate member that causes the tip portion of the blade to move about the pitch axis through the blade. In particular, application of the second torque to the tip portion of the blade causes the tip portion of the blade to rotate about the pitch axis.

[00117] The illustrative embodiments recognize and take into account that this type of actuation system does not require the use of any actuators integrated into the blade. In this manner, the actuation system provided by the illustrative embodiments may not increase the weight of the blade more than desired. Further, power may not need to be delivered to the blade itself. In other words, additional power lines and/or other components may not need to be added to the blade to deliver power to the blade.

[00118] Additionally, by using an actuation system that is associated with the root portion of the blade, the overall contour of the blade may not be affected. Thus, performance of the blade may not be reduced beyond selected tolerances with this type of root-mounted actuation system.

[00119] Further, the configuration for the actuation system described above allows actuation mechanisms having shorter response times than thermo-electric based actuators or piezoelectric actuators to be used. In this manner, twisting of the blade may be achieved more quickly and efficiently using the actuation system described by the illustrative embodiments as compared to some currently available actuation systems.

[00120] The description of the different illustrative embodiments has been presented for purposes of

illustration and description, and is not intended to be exhaustive or limited to the embodiments in the form disclosed. Many modifications and variations will be apparent to those of ordinary skill in the art.

[00121] Further, different illustrative embodiments may provide different features as compared to other illustrative embodiments. The embodiment or embodiments selected are chosen and described in order to best explain the principles of the embodiments, the practical application, and to enable others of ordinary skill in the art to understand the disclosure for various embodiments with various modifications as are suited to the particular use contemplated.

CLAIMS:

What is claimed is:

1. An apparatus comprising:

a blade of a rotorcraft; and

a tip actuation mechanism that is external to the blade and associated with an elongate member that is connected to a tip portion of the blade, wherein the tip actuation mechanism is configured to apply a torque to the elongate member such that the tip portion of the blade rotates about an axis through the blade.

2. The apparatus of claim 1 further comprising:

a root actuation mechanism external to the blade and associated with a root portion of the blade, wherein the root actuation mechanism is configured to apply a torque to the root portion of the blade such that the root portion of the blade rotates about the axis.

3. The apparatus of claim 2, wherein the tip actuation mechanism and the root actuation mechanism are part of an actuation system configured to at least one of pitch and twist the blade.

4. The apparatus of claim 3, wherein the actuation system is configured to pitch the blade at a selected pitch frequency greater than once per revolution during operation of the rotorcraft.

5. The apparatus of claim 3, wherein the actuation system is configured to change an amount of twisting of the blade while the rotorcraft is in a flight regime during operation of the rotorcraft.

6. The apparatus of claim 2, wherein the torque applied to the root portion of the blade is a first torque applied by transferring a first force generated by the root actuation mechanism to the root portion of the blade and wherein the torque applied to the elongate member is a second torque applied by transferring a second force generated by the tip actuation mechanism to the tip portion of the blade through the elongate member.

7. The apparatus of claim 6, wherein the blade pitches when the first torque and the second torque are substantially equal and in a same direction.

8. The apparatus of claim 6, wherein the blade twists when the first torque and the second torque are at least one of not substantially equal and not in a same direction.

9. The apparatus of claim 6, wherein the root actuation mechanism comprises:

an actuator configured to generate the first force, wherein the actuator is selected from one of a linear actuator and a rotary actuator.

10. The apparatus of claim 6, wherein the tip actuation mechanism comprises:

an actuator configured to generate the second force, wherein the actuator is selected from one of a linear actuator and a rotary actuator.

11. The apparatus of claim 2, wherein the root actuation mechanism and the tip actuation mechanism are associated with a swashplate assembly.

12. The apparatus of claim 1, wherein the elongate member is a torque tube.

13. A rotor system comprising:

a plurality of blades; and

a pitch and twist system comprising a plurality of actuation systems in which each of the plurality of actuation systems is associated with a corresponding one of the plurality of blades and comprises:

a root actuation mechanism that is external to a blade and associated with a root portion of the blade, wherein the root actuation mechanism is configured to apply a first torque to the root portion of the blade such that the root portion of the blade rotates about an axis through the blade; and

a tip actuation mechanism that is external to the blade and associated with an elongate member that is connected to a tip portion of the blade, wherein the tip actuation mechanism is configured to apply a second torque to the elongate member such that the tip portion of the blade rotates about the axis.

14. The rotor system of claim 13, wherein the blade pitches when the first torque and the second torque are substantially equal and in a same direction.

15. The rotor system of claim 13, wherein the blade twists when the first torque and the second torque are at least one of not substantially equal and not in a same direction.

16. A method for moving a blade of a rotorcraft, the method comprising:

operating the rotorcraft; and

applying a torque to an elongate member connected to a tip portion of the blade during operation of the rotorcraft using a tip actuation mechanism that is external to the blade and associated with the elongate member such that the tip portion of the blade rotates about an axis through the blade.

17. The method of claim 16 further comprising:

applying a torque to a root portion of the blade using a root actuation mechanism external to the blade and associated with the root portion of the blade such that root portion of the blade rotates about the axis, wherein the torque applied to the root portion is a first torque and wherein the torque applied to the elongate member is a second torque.

18. The method of claim 17 further comprising:

performing at least one of applying the first torque to the root portion of the blade and applying the second torque to the elongate member to pitch the blade at a selected pitch frequency greater than once per revolution during operation of the rotorcraft.

19. The method of claim 17 further comprising:

performing at least one of applying the first torque to the root portion of the blade and applying the second torque to the elongate member to change an amount of twisting of the blade while the rotorcraft is in a flight regime during operation of the rotorcraft.

20. The method of claim 19, wherein the step of performing the at least one of applying the first torque to the root portion of the blade and applying the second torque to the elongate member comprises:

performing the at least one of applying the first torque to the root portion of the blade and applying the second torque to the elongate member to change the amount of twisting of the blade while the rotorcraft is in the flight regime during operation of the rotorcraft such that at least one of vibrations generated by the blade and noise is reduced and such that aerodynamic performance is improved.

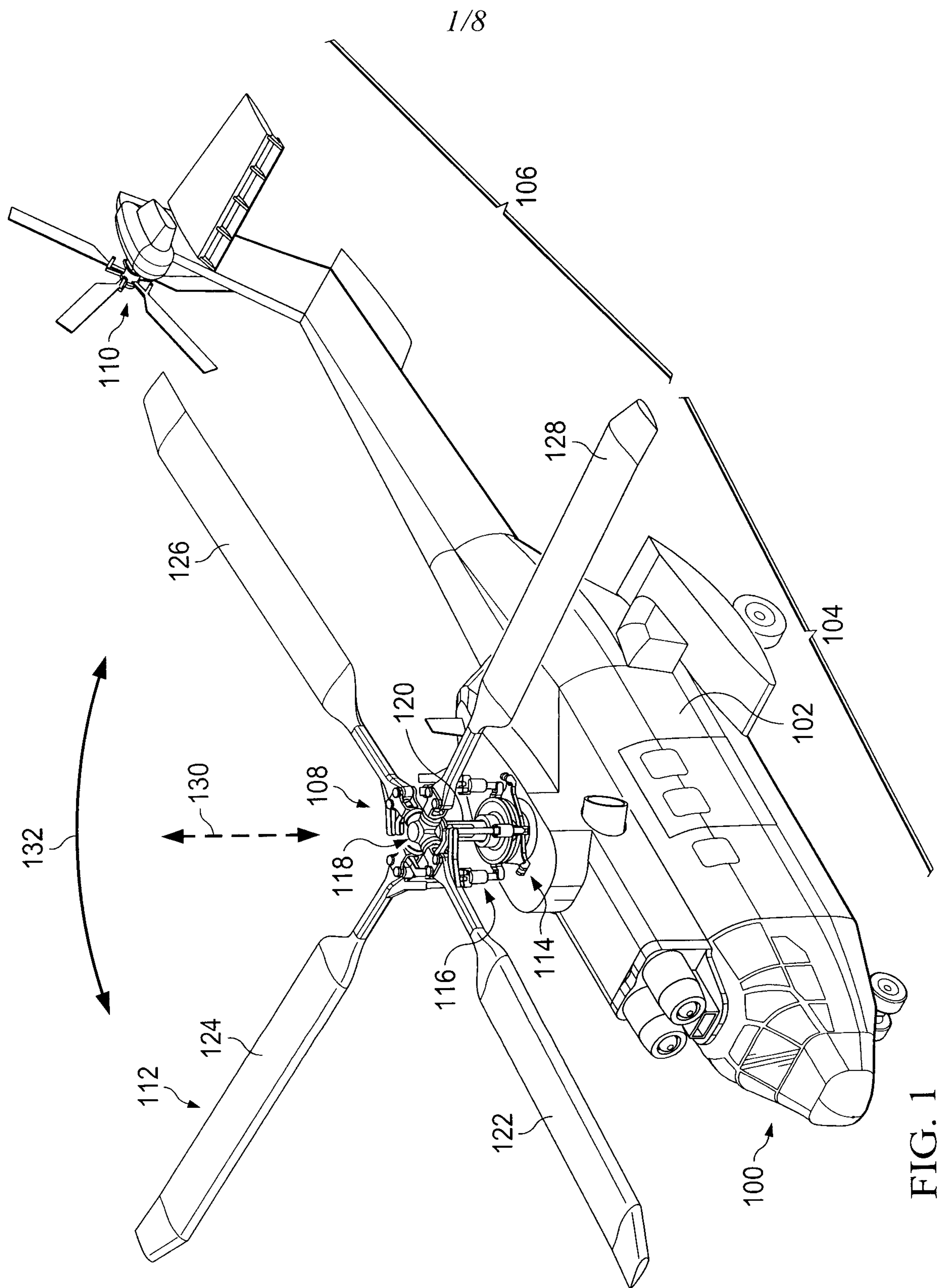


FIG. 1

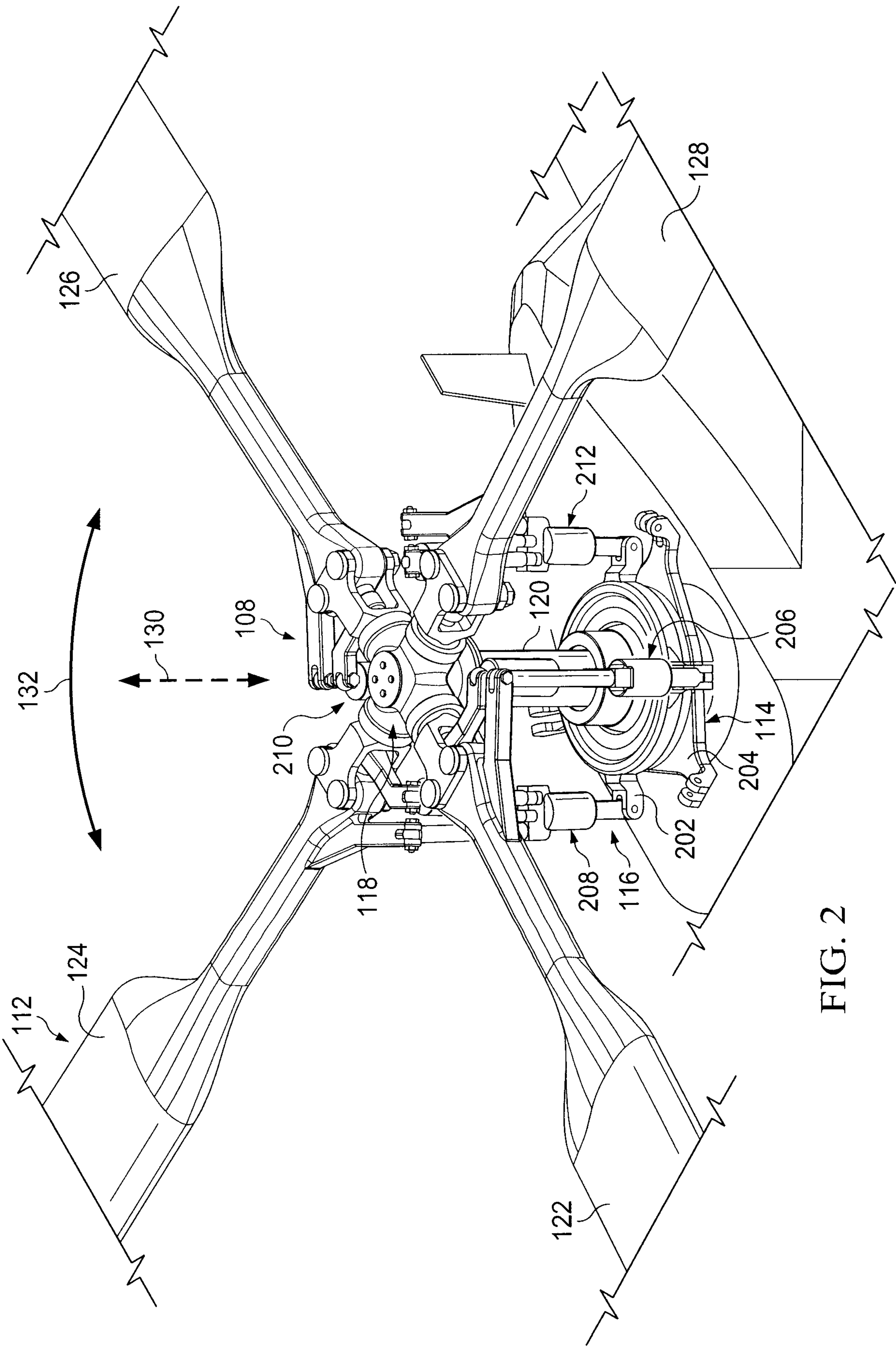
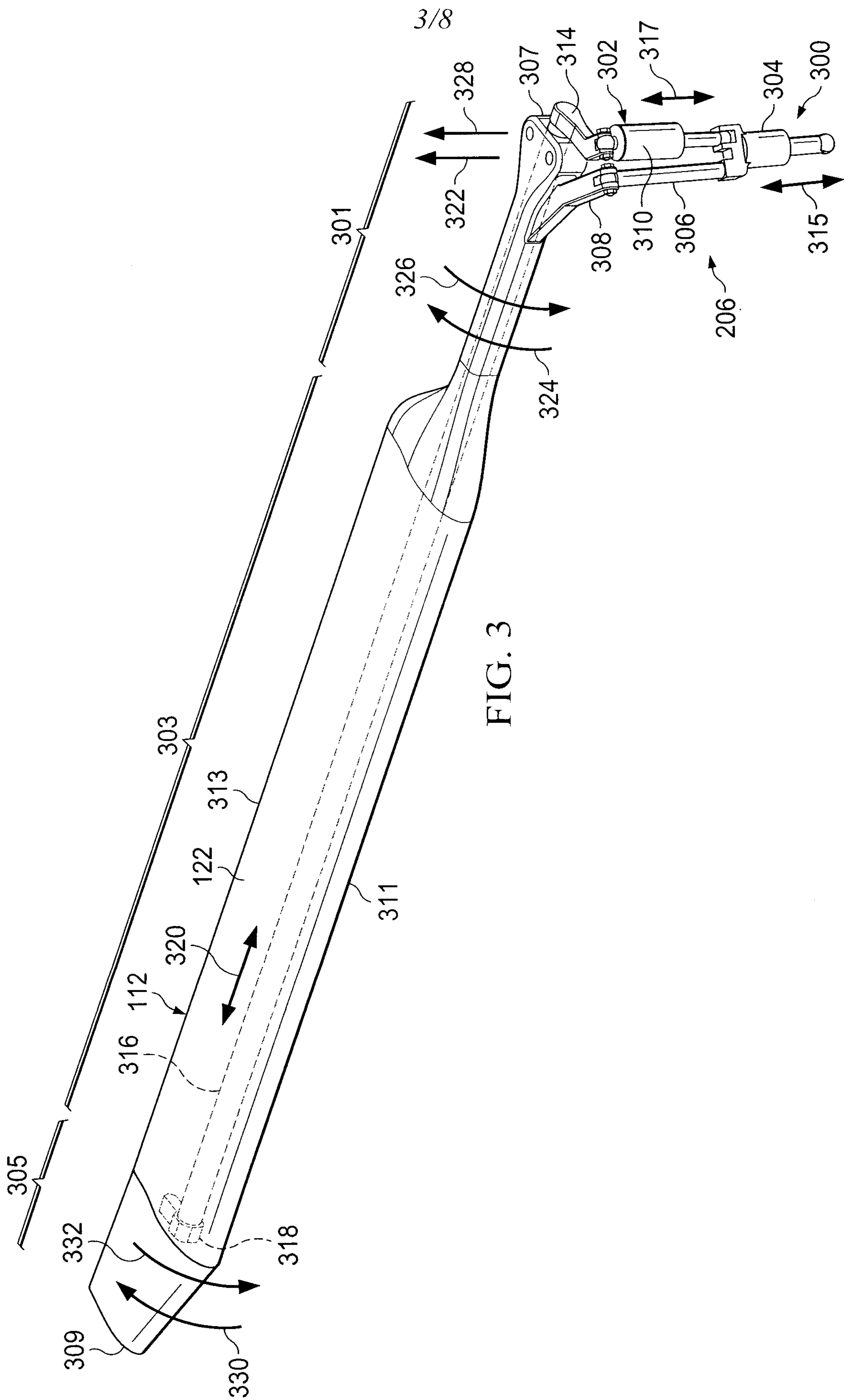


FIG. 2



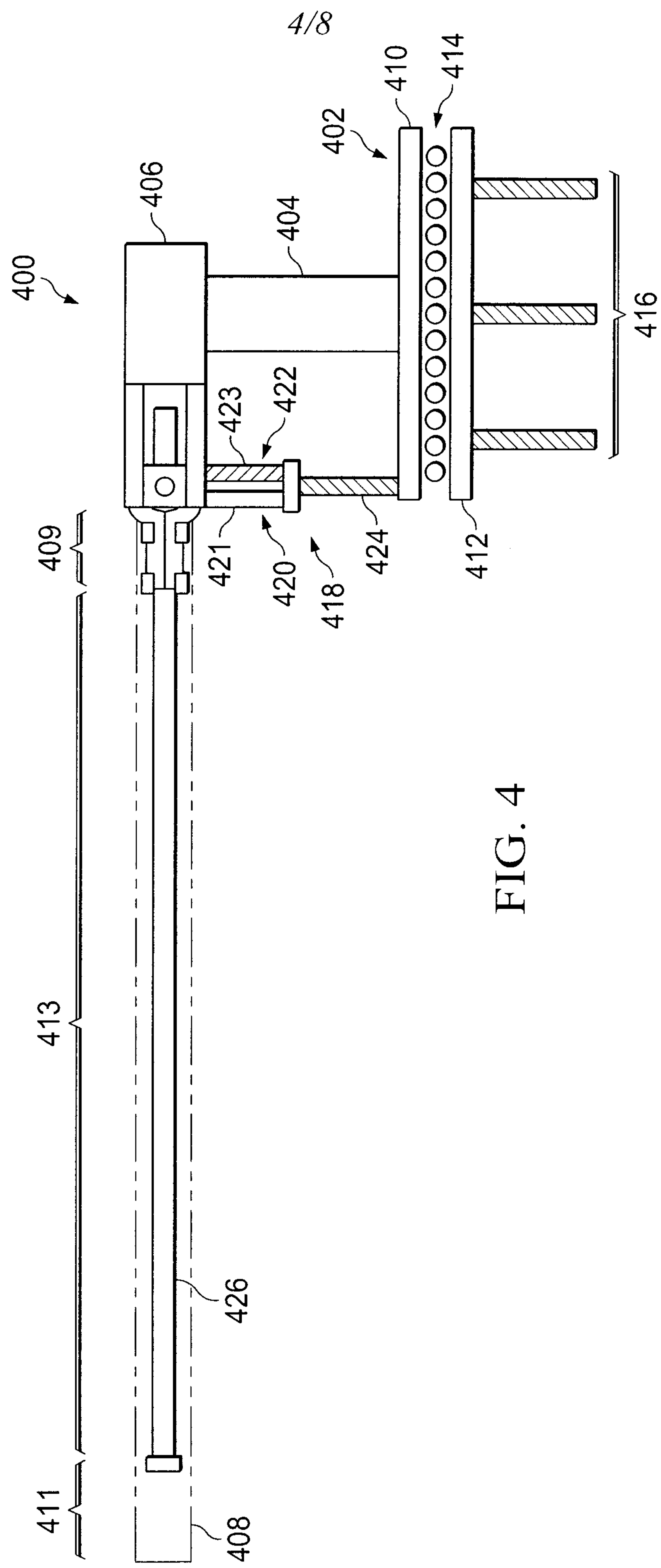


FIG. 4

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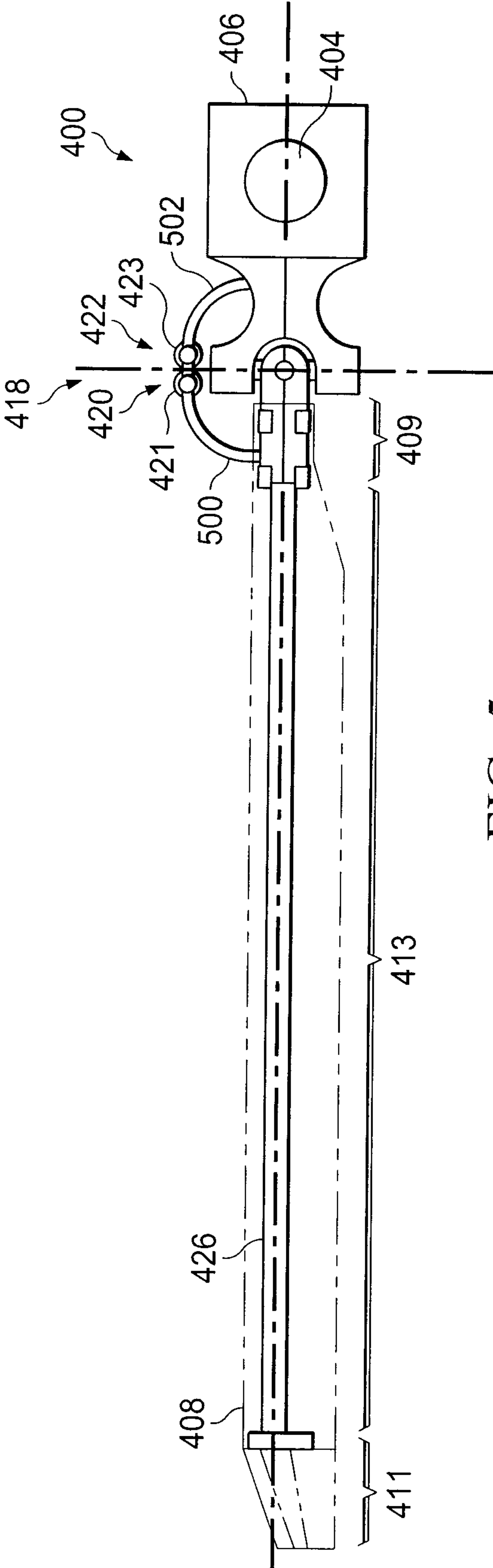


FIG. 5

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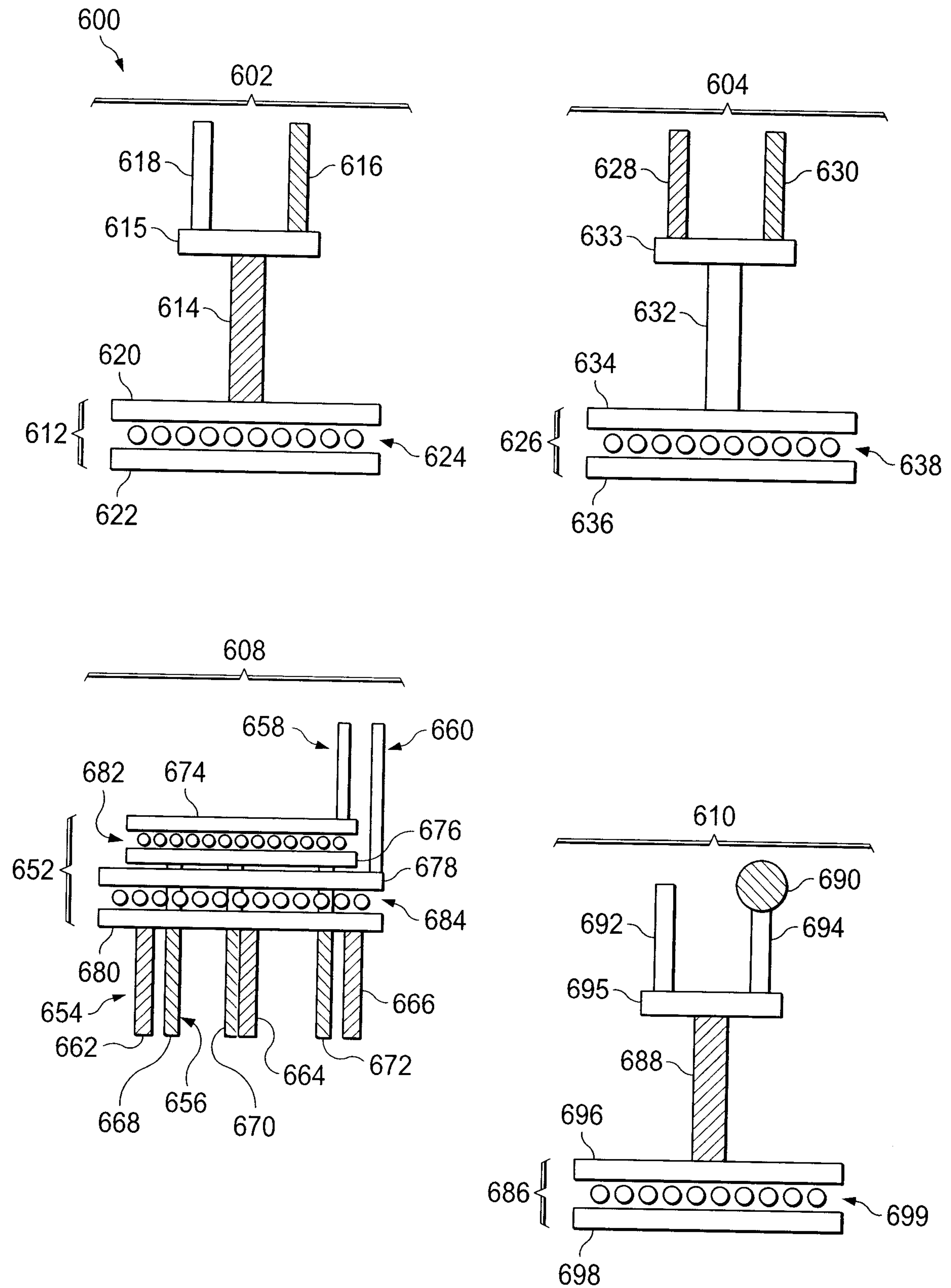


FIG. 6

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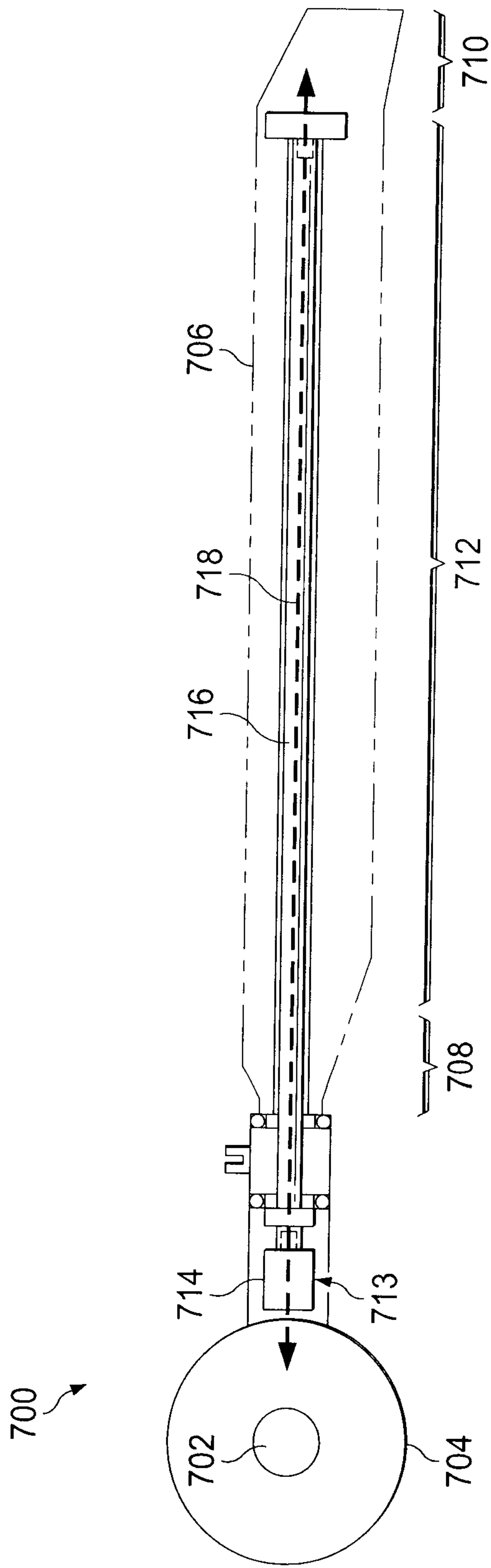


FIG. 7

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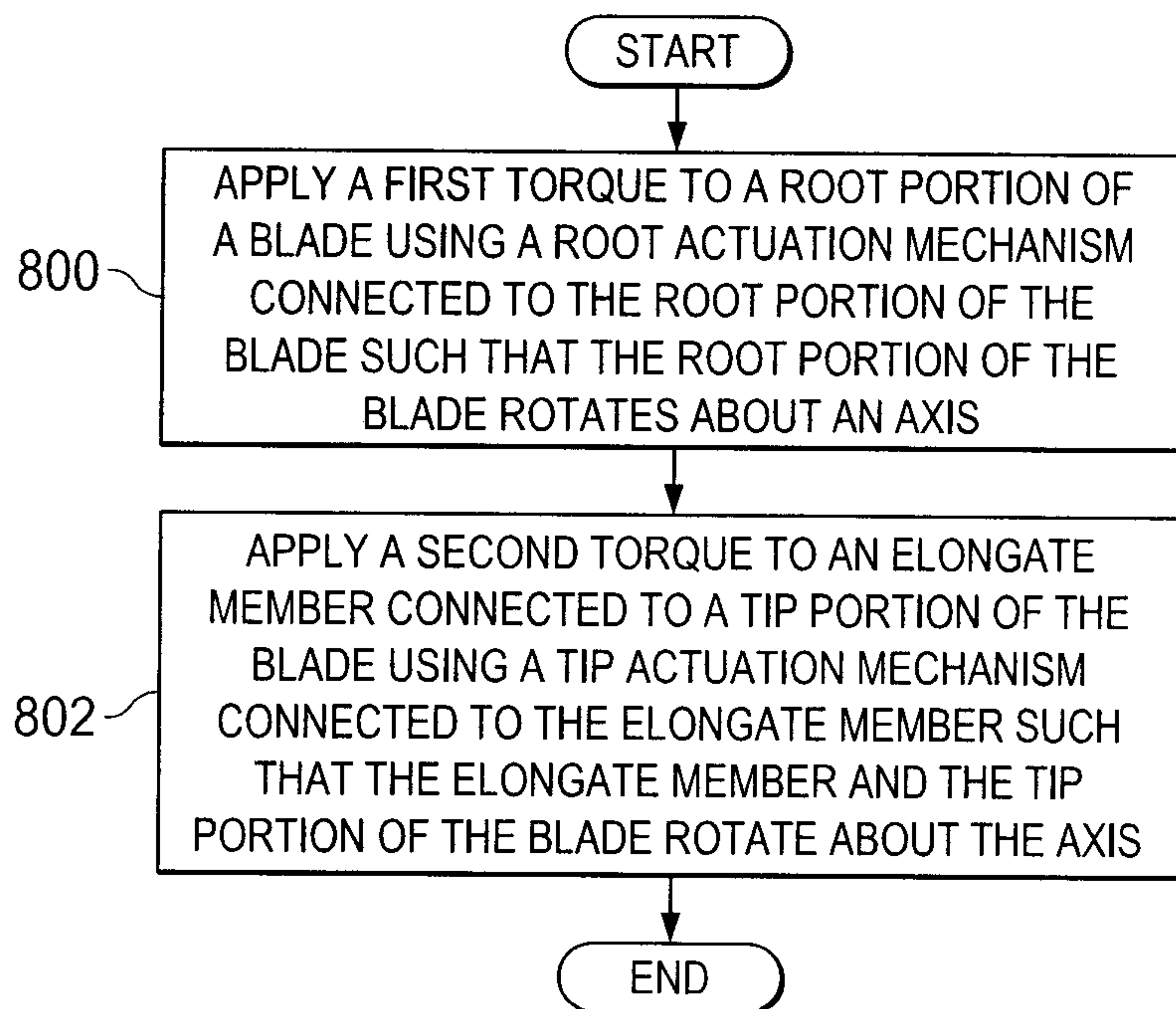


FIG. 8

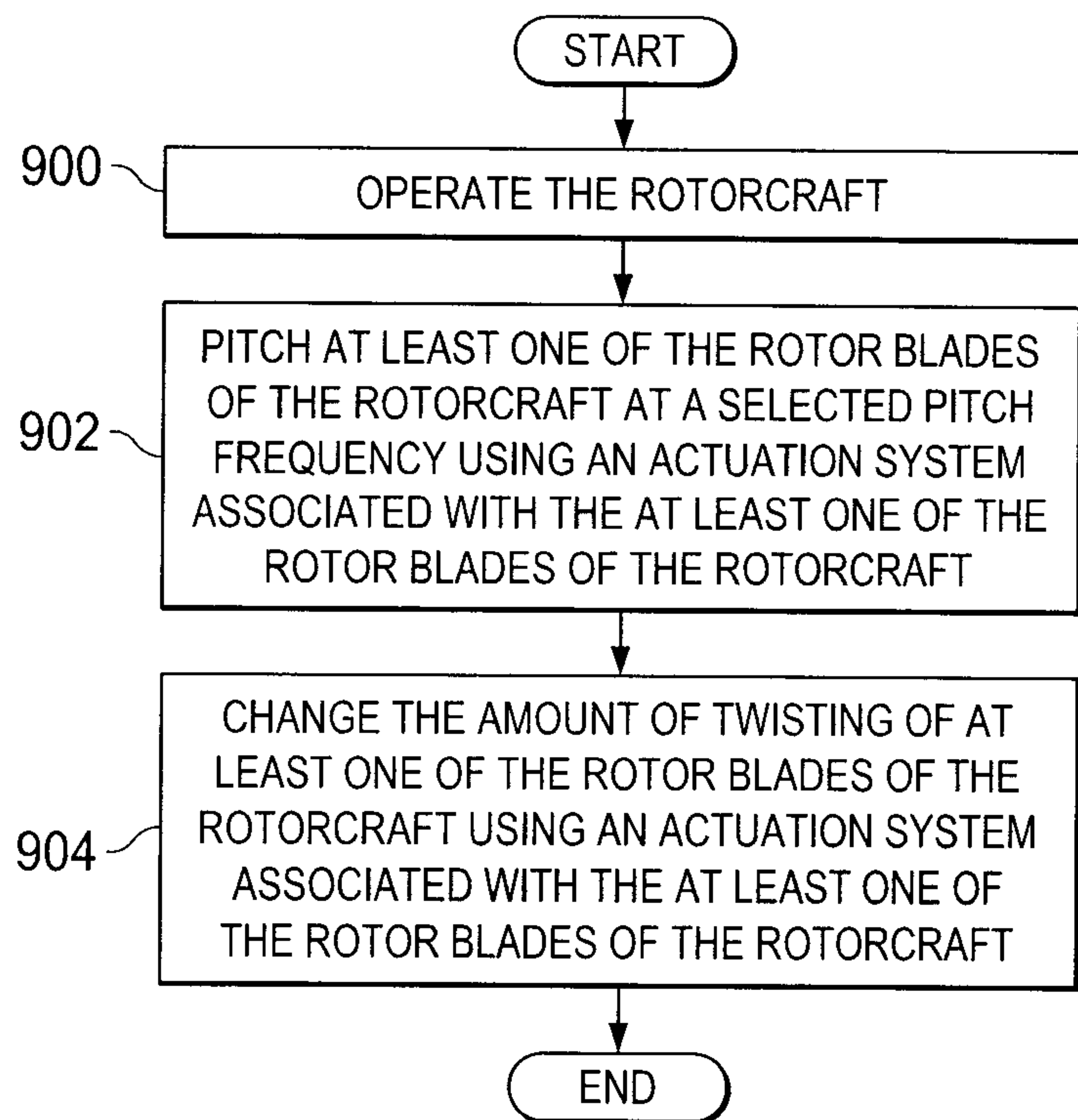


FIG. 9

