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(54) Title: IMAGING SYSTEM FOR A MOTOR VEHICLE

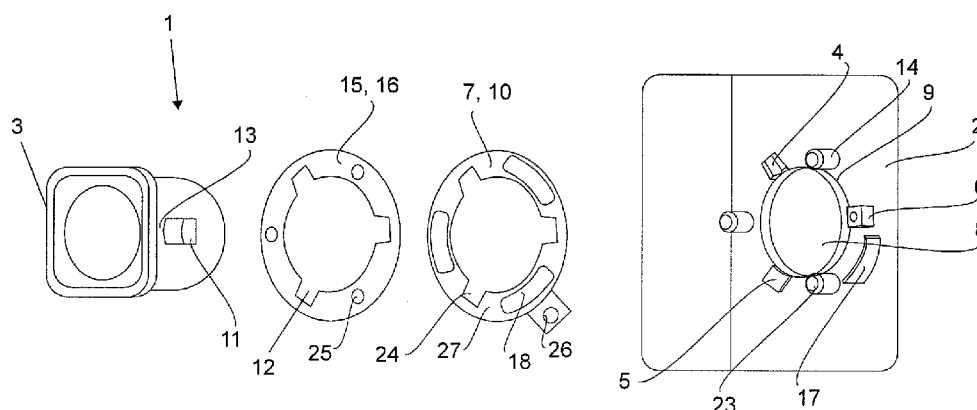


Fig. 2

(57) Abstract: The present invention relates to an imaging system (1) for a motor vehicle, comprising a camera housing (2) and at least one camera module (3) to be mounted to said camera housing (2) wherein the camera housing (2) is provided with an arrangement of at least two first abutments (4,5,6) with a defined geometry and orientation at which the camera module (2) abuts, wherein the camera module (3) is spring loaded against the first abutments (4,5,6) with at least one spring element (7).



Imaging system for a motor vehicle

5 The invention relates to an imaging system for a motor vehicle comprising the features of the preamble of claim 1.

In the assembly process of an imaging system for a motor vehicle, the lens objective is usually aligned relative to the image sensor in order to compensate for manufacturing tolerances of the lens objective and tilt or misalignment of the image sensor, which would otherwise lead to a deterioration of the image quality. Once the optimal position and orientation of the lens objective has been determined, it is conventionally
15 fixed relative to the image sensor by a glue joint between the lens objective and the front of the lens holder. However, since the lens objective is usually rotationally symmetrical around the optical axis, a roll angle displacement of the image sensor cannot be corrected by rotating the lens objective relative to the image sensor in the alignment process. Therefore, in particular for stereo systems but also for mono systems, a laborious roll alignment has to be performed during mounting of the camera modules into an external camera housing part by rotating one camera module around its optical axis.

25

Generally, in order to handle both mono and stereo camera systems, it is desired to share common production processes as much as possible in order to gain efficiency and throughput, hence a modular approach for the camera eyes. It is also critical to maintain focus over the temperature envelope for any
30 automotive camera.

In the EP 2 942 939 A1 it is suggested that first and second rotation locking means are provided at the camera unit and the camera housing part, which cooperate to lock the camera module against rotation relative to the camera housing part. The advantage of the suggested solution is that the camera module is suited to be used both in mono and stereo systems without any modifications, and a laborious roll alignment during mounting of the camera modules into the camera housing part can be avoided. Therefore a simple passive alignment of the camera module relative to the camera housing part is provided.

Furthermore it is known to provide several, preferably three abutments at the camera housing having a defined geometry and orientation at which the camera module of the imaging systems abuts to align the camera module in a predefined direction. The abutments may have for example conical or spherical surfaces to center the camera module. Furthermore the abutments define a plane having a predefined orientation to adjust the camera module in the predefined direction.

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The problem underlying the present invention is to provide an imaging system with an improved attachment of the camera module at the camera housing.

The invention solves this object with the features of the independent claims. According to the invention it is suggested that the camera module is spring loaded against the first abutments with at least one spring element.

In the known attachment the camera module is attached via screws or the like after the camera module is positioned at the first abutments. This attachment may cause small deviations of the position and orientation of the camera module

from the predefined position and orientation defined by the first abutments, because the attachment may oblige the camera module because of the attachment forces into a different position. In this case the accuracy of the attachment does not only depend on the position and geometry of the first abutments but also on the position of final attachment for example of the screws. Furthermore it is possible that the attachment causes tensions in den camera module or in the camera housing, when the position of the camera module defined by the abutments and defined by the attachment are deviating from each other.

According to the invention it is suggested that the camera module is spring loaded against the first abutments. The advantage of the suggested solution can be seen therein that because of the spring loading a degree of freedom is introduced. Because of this degree of freedom an attachment of the camera module is enabled in which the final position and orientation of the camera module is only determined by the orientation and geometry of the first abutments. Therefore the camera module can be positioned and adjusted by the first abutments without or at least with less influence of the attachment into the predefined direction. Furthermore the fixation can be therefore realized with less tension in the camera module and in the camera housing. Furthermore the fixation may be handled much easier by applying the spring load manually or with a suitable tensioning device without any tools or additional attachment means. The spring element is designed regarding the spring forces to fix the camera module in all possible driving situations, wherein it is further possible to compensate small vibrations and to reduce therefore negative effects on the camera module and the signal generated therein resulting from for example off road driving or bad street conditions.

According to a preferred embodiment it is suggested that the camera housing comprises an opening through which the camera module extends, and the first abutments are arranged in a rim section of the camera housing adjacent to the opening, and the
5 spring element is designed as a first ring, overlapping the first abutments. The camera module is therefore enclosed by the spring element pressing the camera module onto the first abutments. Furthermore the spring forces may act at the outer
10 circumferences of the camera module enclosing the camera module so that the camera module may be pressed with a centering effect onto the abutments. By applying the spring forces with the first ring it is possible to apply the spring forces in an equal distribution and the spring element can be designed,
15 manufactured and assembled in the imaging system in a very easy manner.

The camera module may be provided with at least one first projection directed into radial direction. The first projection
20 is directed in radial direction so that it may be preferably used to apply the necessary spring loading in axial direction onto the camera module and finally onto the first abutments. The axial direction is the length direction of the camera module and is identical with the mounting direction of the camera
25 module.

In this case the camera module may engage preferably with the first projection into a recess of the camera housing or of a part fixed at the camera housing, wherein the recess is in axial direction of the camera module open and enables a relative
30 movement of the camera module in axial direction while it blocks a relative movement of the camera module in circumferential direction at least in one step of the assembly process.

The purpose of the first projection engaging in the recess is to fix the camera in a predetermined angular orientation with respect to the axial direction when mounting the camera module at the camera housing. Furthermore the recess is in axial direction open, so that the camera module may perform a relative movement in axial direction into the attachment position, while the recess may act in this case additionally as guidance for the camera module.

10 The first projections of the camera module may comprise at a side facing to the spring element an oblique surface which comprise an angled orientation with respect to a plane defined by the first abutments of the camera housing, and the spring element is abutting at the oblique surface and is adapted to perform a relative movement versus the first projections with pressing the camera module against the first abutments. The advantage of the suggested solution is that the first projection is also used to initiate the movement towards the first abutments, by the spring element performing the relative movement and using the oblique surface to transfer the relative movement into an axial movement. In this case it is important, that the surfaces are directed oblique or angled versus the plane defined by the abutments, so that the relative movement of the spring versus the first projection is transformed to an axial movement towards the first abutments.

Furthermore it is suggested that the camera housing is provided with at least one second projection with a second abutment. The second projection with the second abutment is used as an abutment for the spring element when the camera module is spring loaded into the attachment position. The second projection and second abutment is fixed at the camera housing or at a part connected with the camera housing and serve therefore

to take up the reaction forces of the spring element which is necessary to apply the spring load to the camera module for the attachment.

5 Therefore the first projection of the camera module is arranged preferably between the first and the second abutment, wherein the spring element is arranged between the second abutment of the second projection and the first projection pressing the camera module towards the first abutment.

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Furthermore several, preferably three second projections are provided at the camera housing, and the second abutment is designed as a second ring attached at each of the second projections, wherein the first ring (the spring element) and the
15 second ring comprise a corresponding shape. The second abutment in form of the second ring provides an abutment which encloses the camera module completely in circumferential direction, so that the spring element can be supported at several points which are arranged preferably in identical distances in
20 circumferential direction, so that the camera module is loaded with an equal distributed spring load. As the first and the second ring comprise a corresponding shape both parts can be used over their complete surfaces to apply the spring load and to take up the corresponding reaction forces.

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The first ring (the spring element) is arranged rotatable with respect to the axial direction of the camera module to be rotated into an attachment position. The suggested solution enables a very easy mounting process, by inserting the camera
30 module in a first step and rotating the first ring or spring element in a second step into the attachment position, wherein both steps can be performed without any additional tools or attachment means.

Furthermore it is suggested that the camera housing comprises a blocking structure which prevents a rotation of the first ring out of the attachment position. The blocking structure
5 acts as a lock to prevent a movement of the first ring and therefore also of the camera module out of the attachment position.

The first ring may comprise furthermore several arc shaped
10 openings which are arranged concentrically to the rotation axis through which the first projections of the camera housing are extending. The ring is therefore additionally fixed in a predefined position and can be arranged between the second and the first abutments.

15

Furthermore it is suggested that the camera housing is provided with a stopper limiting the rotation movement of the first ring. The position of the stopper defines the final attachment
position of the first ring, so the handling person need to rotate the first ring just as far as possible until the relative
20 movement is stopped by the stopper during the assembly process to reach the attachment position of the first ring.

In the following the invention shall be illustrated on the basis of preferred embodiments with reference to the accompanying
25 drawings, wherein:

Fig. 1 shows an imaging system with the basic components;
and

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Fig. 2 shows the imaging system with the single components in explosive view; and

Fig. 3 shows the assembly steps of the attachment process;
and

Fig. 4 shows the spring element; and

5

Fig. 5 shows the relevant section of the camera housing for
mounting the camera module; and

10

Fig. 6 shows an enlarged section of the module in two dif-
ferent positions in view from the side.

In Figure 1 it is shown an imaging system 1 with the basic
components comprising a camera housing 2 and a camera module
3. The camera module 3 is a pre-assembled unit, which compris-
15 es a lens 20, a lens holder 21 and an optical sensor device 22
with the necessary electronic equipment to generate sensor
signals and for processing the necessary data from the sensor
signals for further processing. The camera module 3 needs to
be orientated in a pre-defined direction, which is essential
20 for the imaging system 1 to fulfill the requirements. The im-
aging system 1 may be used for example in active driver assis-
tance system of vehicles and is in this case an essential part
in the active and passive safety systems of the vehicle. Fur-
thermore the imaging system 1 may be used in park assistance
25 systems, in surveillance system and in vision systems in gen-
eral.

The imaging system 1 is shown in Figure 2 in explosive view.
The camera housing 2 is provided with a circular opening 8
30 with three first abutments 4, 5 and 6 arranged in a rim sec-
tion 9 adjacent to the opening 8. The first abutments 4, 5 and
6 are arranged equidistant to each other in angles of 120 de-
gree and on a common radius with identical distances to the

center of the opening 8. The camera module 3 comprises a cylindrical basic body which is in this case the lens holder 21 shown in Figure 1. The camera module 3 further comprises three first projections 11, which are extending from the cylindrical
5 body in radial direction to the outside perpendicular to the length axis A. The three first projections 11 are arranged also in equal distances to each other and in a common plane with identical distances to the front side of the camera module 3. Furthermore the three first projections 11 comprise an identical
10 shape and orientation with an oblique surface 13 arranged at the side facing to the front side of the camera module 3.

The camera housing 2 is further provided with second projections 14 which are also arranged in the rim section 9 of the
15 opening 8 between the first abutments 4, 5 and 6 on a common radius and with an angular distance of 120 degree. Alternatively the second projections 14 may be also arranged on different radii and/or with different angles between them for example between 110 and 130 degree in circumferential direction
20 to realize a poky yoke function. The second projections 14 are designed as from the bottom of the camera housing 2 upright standing cylindrical columns and are provided at the front sides with pins 23 having a smaller diameter. The second projections 14 may be realized for example by separated parts
25 which are connected with the camera housing 2 via riveting, screw connection or by heat staking. Furthermore a blocking structure 17 in shape of a ramp is provided. The ramp is designed as a ring section which is arranged concentric to the center of the opening 8 with in circumferential and in clock-
30 wise direction increasing height. Furthermore a spring element 7 and a second abutment 15 are provided which are realized by a first ring 10 and a second ring 16. The second abutment 15 realized by the second ring 16 comprises three openings 25 and

is attached via the openings 25 at the pins 23 of the second projections 14 for example by riveting, stamping, securing rings, gluing or the like. The second ring 16 comprise furthermore at the radial inner side three first recesses 12 and the first ring 10 comprises also at the radial inner side three second recesses 24 having an identical cross shape and arrangement with distances of 120 degree to each other and with identical cross shape and arrangement to the first projections 11 of the camera module 3. In the first ring 10 are provided furthermore three arc shaped openings 18, which are arranged equidistant to each other and concentric to the center of the first ring 10. The first ring 10 is provided additionally with a radial to the outside directed handle 26.

The camera housing 2 is preassembled with the second projections 14 or it is produced as a single part as an injection mould. In a first step the spring element 7 is mounted with the arc shaped openings 18 on the second projections 14 in a position in which the handle 26 is arranged adjacent to the lower side of the blocking structure 17. The first ring 10 is rotatable within a limited angle because of the arc shaped openings 18. In a next step the second ring 16 is mounted with the openings 25 on the pins 23 of the second projections 14. The first ring 10 and the second ring 16 are positioned with the first and second recesses 12, 24 in identical positions, so that both recesses 12, 24 creating a common recess, which is shown in the left picture of Figure 3. The common recess created by the recesses 12 and 24 is positioned over the first abutments 4, 5 and 6. The position of the recesses 12 and 24 define the orientation, in which the camera module 3 may be inserted into the camera housing 2 like shown in the second picture of Figure 3. The recesses 12, 24 are in axial direction A open, so that the camera module 3 may be inserted in

the axial direction A which is in this case also the mounting direction. The recesses 12, 24 prevent a rotation of the camera module 3 and act therefore as a guidance for the camera module 3 during the attachment movement into the final position shown in the third picture of Figure 3. Because of the arrangement of the recesses 12 and 24 over the first abutments 4, 5 and 6 the first projections 11 are positioned also over the first abutments 4, 5 and 6. The final fixation of the camera module 3 is performed by turning the first ring 10 (the spring element 7) in clockwise direction into the position shown in the fourth picture of Figure 3. The first ring 10 can be turned easily by grasping the handle 26, which is moved during the rotation over the blocking structure 17. When the first ring 10 is positioned in the final attachment position it is blocked against backwards rotation by abutting at the side of the blocking structure 17 like shown in the right picture of Figure 3.

In Figure 4 and 5 it is shown another embodiment in which the first ring 10 is further provided with an in axial direction extending tongue 28 and the camera housing 2 is provided with a stopper 19 arranged in a defined position. The advantage of this solution is that the rotational movement of the first ring 10 is stopped when the tongue 28 abuts at the stopper 19, so the stopper 19 defines the final attachment position of the first ring 10.

In Figure 6 it is shown the attachment movement in view from the side on one first projection 11. The first projection 11 comprises an oblique surface 13 which encloses an angle D with the circumferential direction B. The surface 13 may comprise in an alternative 13a also a decreasing angle D in circumferential direction B which finally ends in a kind plateau with

an angle of zero degree to the circumferential direction B at the left side of the first projection 11 shown in Figure 6 by the dashed line. The advantage of this embodiment is that the axial movement of the camera module 3 is thereby non-linear and decreasing; so that the camera module 3 may perform in the end phase an adjustment movement with a very high precision in a very small ratio of the axial movement related to the rotational movement of the first ring 10.

In the top view of figure 6 it is shown the position of the first projection 11 and of the first ring 10 after the camera module 3 has been inserted and before the first ring 10 was turned, so the position corresponds to the position shown in the third picture from the left in Figure 3. The camera module 3 extends with the first projections 11 through the recesses 12 and 24. The first ring 10 and the second ring 16 are not pressed against each other. When the first ring 10 is being rotated in circumferential direction B the first ring 10 starts to overlap the oblique surface 13 with a rim section 27 at the lower side. When the first ring 10 is further rotated the first ring 10 is obliged by the oblique surface 13 against the second ring 16 (the second abutment 15), which prevents a further upwardly directed movement of the first ring 10, so that the first ring 10 presses the first projection 11 in axial direction C which corresponds to the axial direction A in Figure 2 towards the camera housing 2 and the first abutments 4, 5 and 6 arranged thereon. The first abutments 4, 5 or 6 are designed in this embodiment with a spherical surface 30, while the side of the first projections 11 facing to the first abutments 4, 5 or 6 are also designed as a spherical surface 29, wherein the spherical surface 29 of the first projection 11 is the negative surface of the spherical surface 30 of the first abutment 4, 5 or 6. The spherical surfaces 30 and 29 may be

also designed in an alternative embodiment with the spherical surface 30 having the positive cam shape being arranged at the first projections 11 and the spherical surface 29 having the negative cam shape being arranged at the first abutments 4, 5 and 6. Furthermore one or both of the spherical surfaces 29 or 30 may be also designed as cone-shaped recesses or cone-shaped cams.

The first ring 10 acts in this case as a spring element 7 which creates a spring load onto the first projection 11 and pressing the first projections 11 onto the first abutments 4, 5 or 6. The first projections 11 and the camera module 3 are adjusted by the spherical surfaces 29 and 30 in a predefined orientation and direction. Because there is no further connection by screws or rivets the adjustment of the camera module 3 is only determined by the first abutments 4, 5 and 6, the first projections 11 and the spherical surfaces 29 and 30 arranged thereon. Instead of the spherical surfaces 29 and 30 also other geometries like conical or inclined surfaces 13 may be used, wherein the different first abutments 4, 5 and 6 may have also different surfaces 13 which may result in conjunction in a centering and adjustment function of the camera module 3.

The attachment process can be performed without any tools or additional attachment means. Furthermore the spring loading of the camera module 3 got the advantage that small vibrations or shocks can be compensated. Therefore the signal or the vision generated by the camera module is much better. Furthermore the forces acting on the camera module 3 can be reduced. The spring load can be determined by dimensioning the first ring 10 and the second ring 16, wherein the spring load should be

dimensioned to hold the camera module 3 under all normal driving conditions in position.

Claims:

1. An imaging system (1) for a motor vehicle, comprising
 - a camera housing (2) and
 - 5 -at least one camera module (3) to be mounted to said camera housing (2) wherein
 - the camera housing (2) is provided with an arrangement of at least two first abutments (4,5,6) with a defined geometry and orientation at which the camera module (2)
 - 10 abuts, characterized in that
 - the camera module (3) is spring loaded against the first abutments (4,5,6) with at least one spring element (7).
2. An imaging system (1) as claimed in claim 1, characterized
 - 15 in that
 - the camera housing (2) comprises an opening (8) through which the camera module (3) extends, and
 - the first abutments (4,5,6) are arranged in a rim section (9) of the camera housing (2) adjacent to the opening (8), and
 - 20 -the spring element (7) is designed as a first ring (10), overlapping the rim section (9).
3. An imaging system (1) as claimed in claim 1 or claim 2,
 - 25 characterized in that
 - the camera module (3) is provided with at least one first projection (11) directed into radial direction.
4. An imaging system (1) as claimed in claim 3, characterized
 - 30 in that
 - the camera module (3) engages with the first projection (11) into a first recess (12) of the camera housing (2) or of a part fixed at the camera housing (2), wherein

5 -the first recess (12) is in axial direction (A) of the camera module (3) open and enables a relative movement of the camera module (3) in axial direction (A) while it blocks a relative movement of the camera module (3) in circumferential direction at least in one step of the assembly process.

5. An imaging system (1) as claimed in one of the claims 3 or 4, characterized in that

10 -the first projections (11) of the camera module (3) comprise at a side facing to the spring element (7) an oblique surface (13) which comprise an angled orientation with respect to a plane defined by the first abutments (4,5,6) of the camera housing (2), and
15 -the spring element (7) is abutting at the oblique surface (13) and is adapted to perform a relative movement versus the first projections (11) with pressing the camera module (3) against the first abutments (4,5,6).

20 6. An imaging system (1) as claimed in any one of the preceding claims, characterized in that
 -the camera housing (2) is provided with at least one second projection (14) with a second abutment (15).

25 7. An imaging system (1) as claimed in one of the claims 3 to 5 and in claim 6, characterized in that
 -the first projection (11) of the camera module (3) is arranged between the first and the second abutment (4,5,6,15), wherein
30 -the spring element (7) is arranged between the second abutment (15) of the second projection (14) and the first projection (11) pressing the camera module (3) towards

the first abutment (4,5,6).

8. An imaging system (1) as claimed in claim 6 or 7, characterized in that

5 -several, preferably three second projections (14) are provided at the camera housing (2), and the second abutment (15) is designed as a second ring (16) which is attached at each of the second projections (14).

10 9. An imaging system (1) as claimed in claim 2 and in claim 8, characterized in that

-the first ring (10) and the second ring (16) comprise a corresponding shape.

15 10. An imaging system (1) as claimed in claim 2 or any one of the preceding claims referring to claim 2, characterized in that the

-first ring (10) is arranged rotatable with respect to the axial direction (A) of the camera module (3) to be
20 rotated into an attachment position.

11. An imaging system (1) as claimed in claim 10, characterized in that

25 -the camera housing (2) comprises a blocking structure (17) which prevents a rotation of the first ring (10) out of the attachment position.

12. An imaging system (1) as claimed in one of the claims 10 or 11 and in claim 8, characterized in that

30 -the first ring (10) comprises several arc shaped openings (18) which are arranged concentrically to the rotation axis through which the first projections (11) of the

camera housing (2) are extending.

13. An imaging system (1) as claimed in one of the claims 10 to 12, characterized in that

5 -the camera housing (2) is provided with a stopper (19) limiting the rotation movement of the first ring (10).

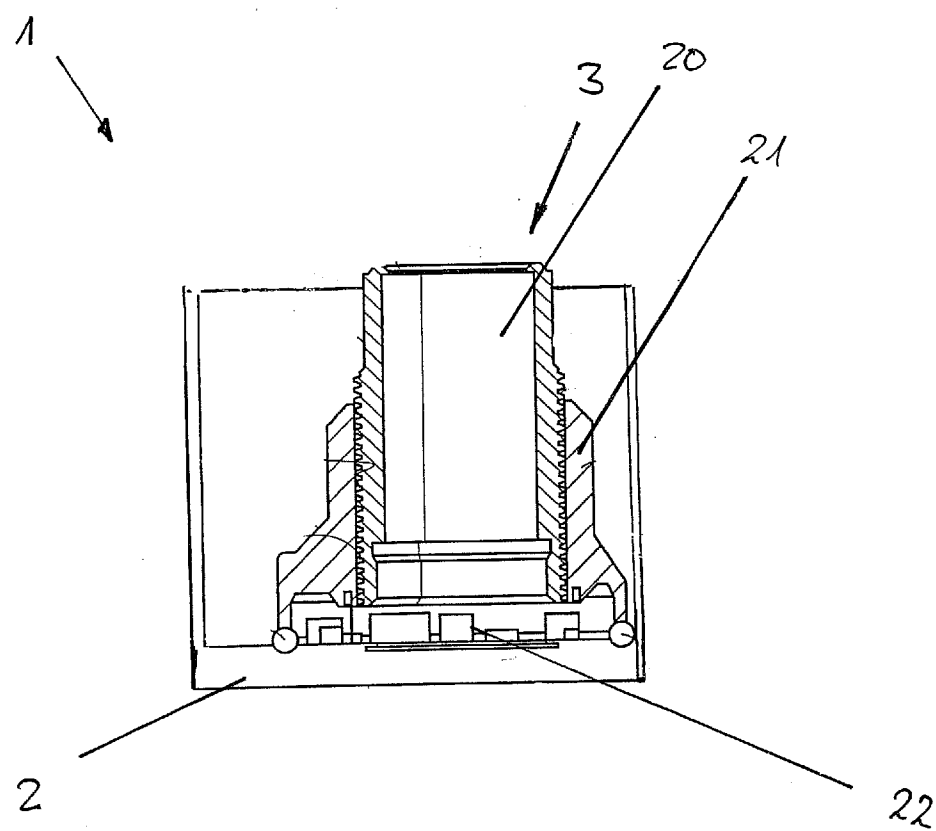


Fig. 1

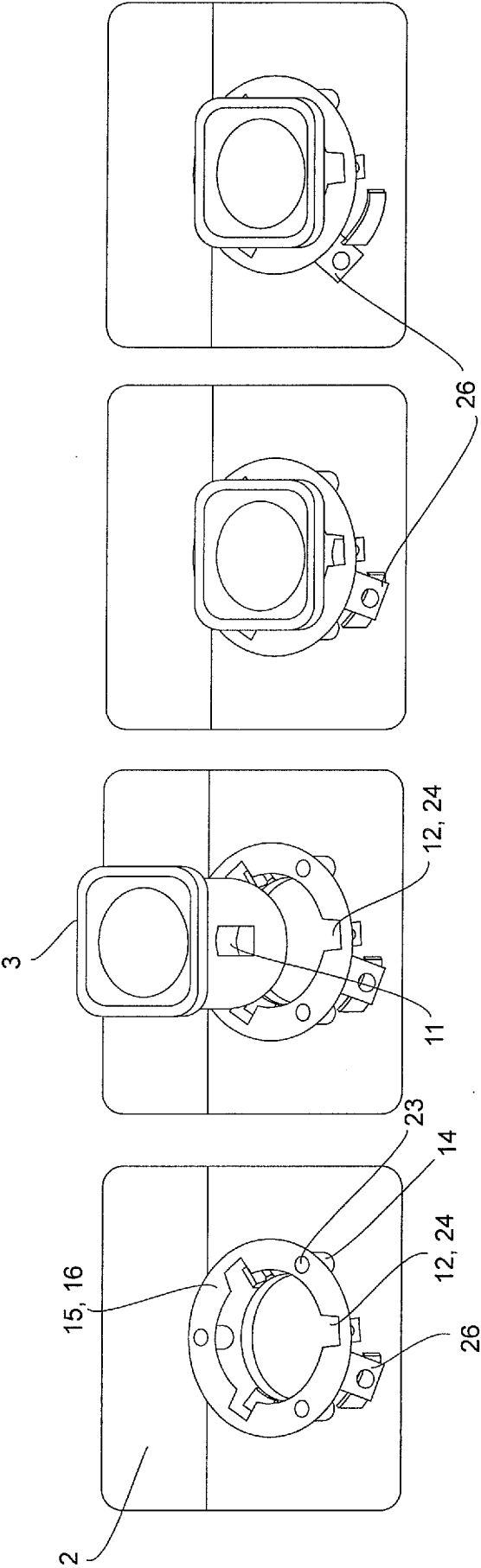


Fig. 3

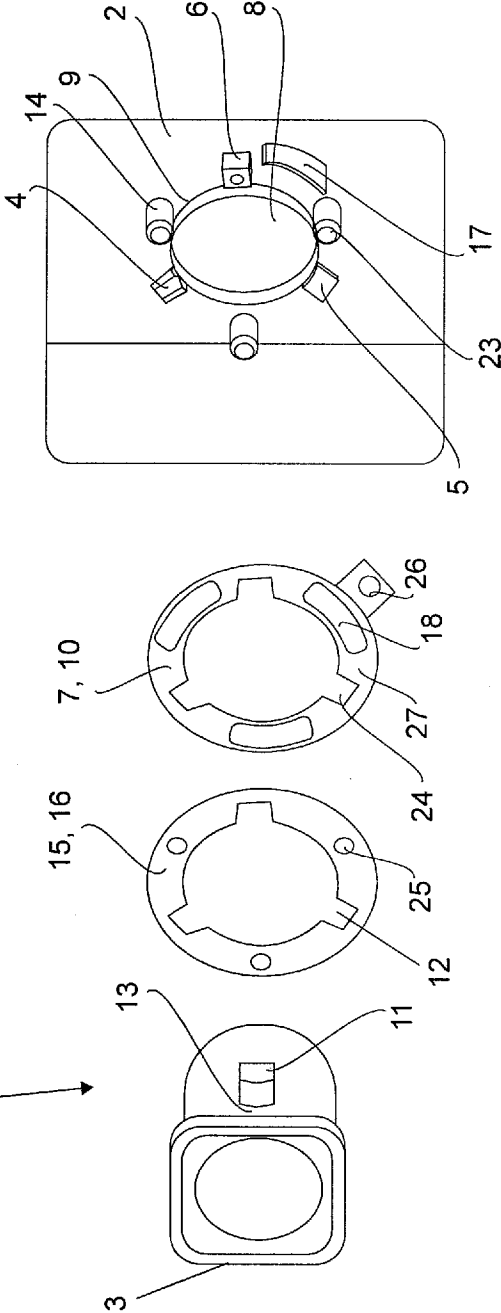


Fig. 2

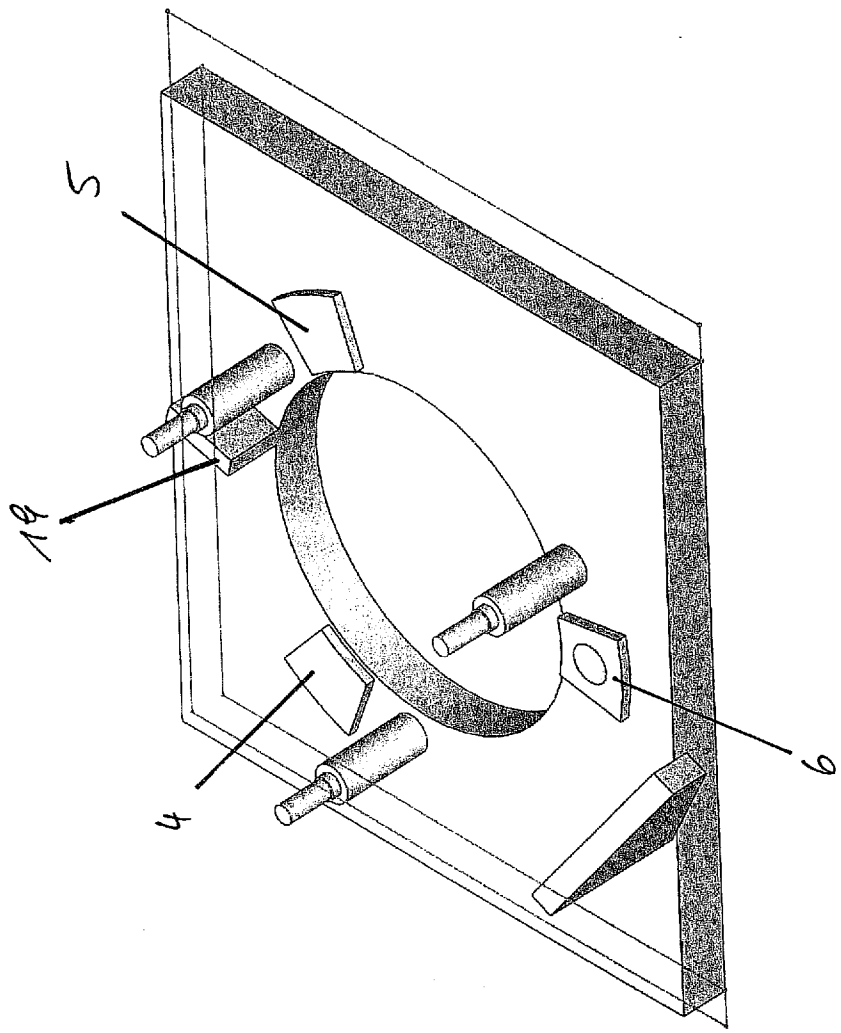


Fig. 5

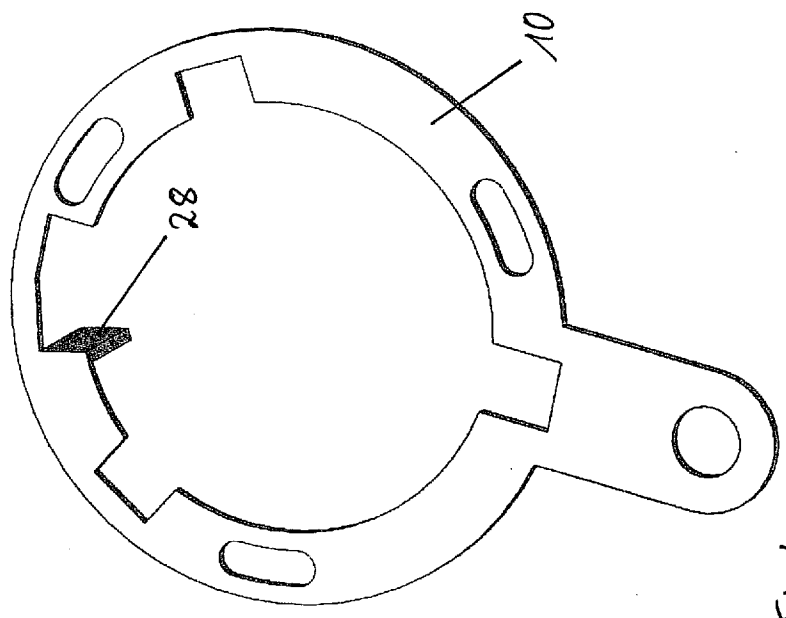


Fig. 4

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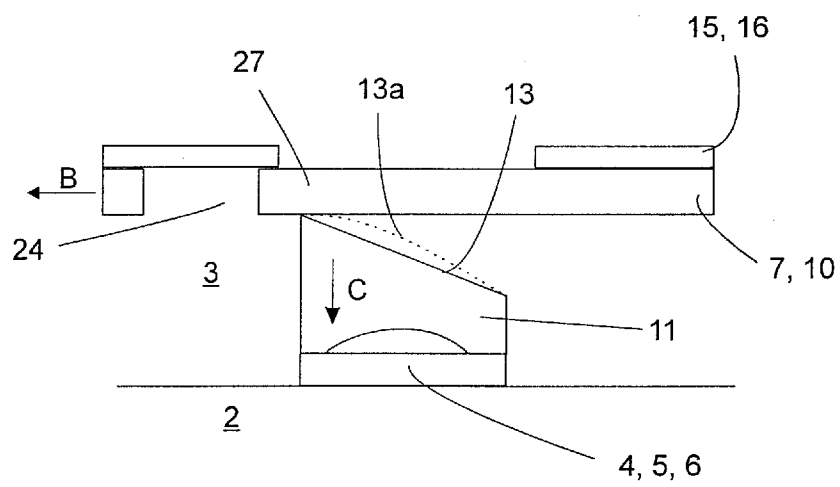
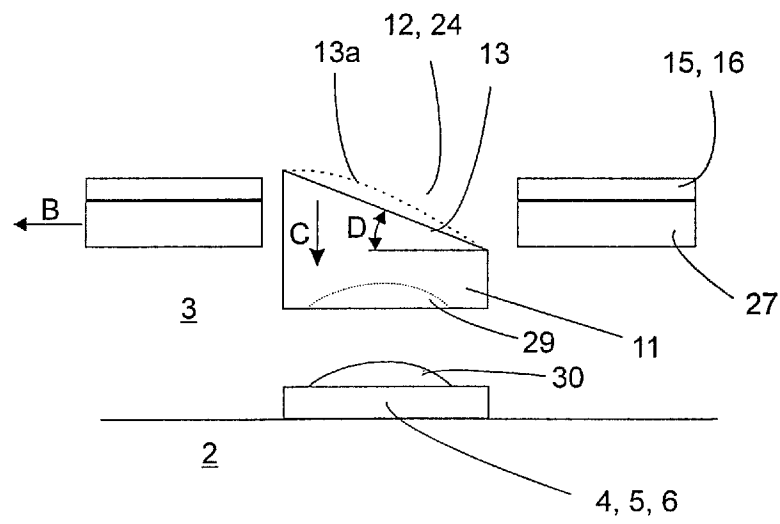


Fig. 6

INTERNATIONAL SEARCH REPORT

International application No
PCT/EP2017/071825

A. CLASSIFICATION OF SUBJECT MATTER
INV. B60R11/04 G03B17/00 H04N5/225 H04N17/02
ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
B60R G03B H04N

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 2014/375809 A1 (SONG JIN-KYU [KR] ET AL) 25 December 2014 (2014-12-25)	1-4,6-9
A	abstract figures 1,2,3 paragraphs [0003], [0009], [0021] - [0032]	5,10-13
A	----- DE 10 2011 108594 A1 (DAIMLER AG [DE]) 31 January 2013 (2013-01-31) abstract paragraphs [0006] - [0013], [0019], [0033] - [0038] figures 1-4,6 ----- -/-	1-13



Further documents are listed in the continuation of Box C.



See patent family annex.

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Date of the actual completion of the international search

5 October 2017

Date of mailing of the international search report

13/10/2017

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INTERNATIONAL SEARCH REPORT

International application No
PCT/EP2017/071825

C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
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