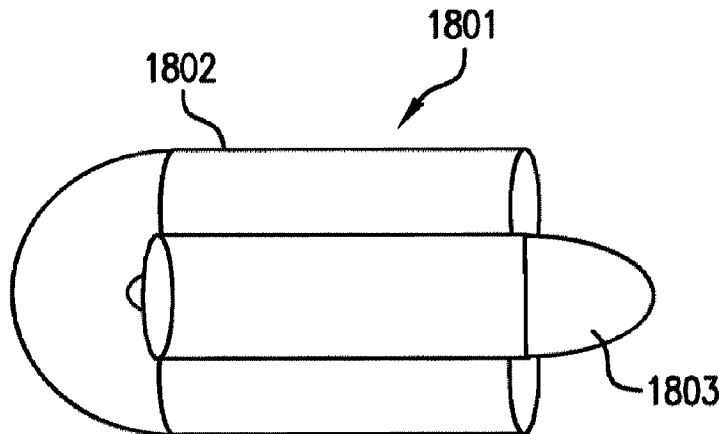




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(54) **Titre : MATERIAUX ET FORMES DE MARQUEUR POUR LOCALISATION A MARQUEUR MAGNETIQUE (MML)**
(54) **Title: MARKER MATERIALS AND FORMS FOR MAGNETIC MARKER LOCALIZATION (MML)**



(57) **Abrégé/Abstract:**

Various embodiments of magnetic marker for marking a site in a tissue in a body comprise a solid material characterized by specific magnetic coercitivity, specific magnetic mass susceptibility, and specific magnetic anisotropy of susceptibility. In some embodiments, the magnetic marker is deployable, comprising a multi-stranded cable or a wire formed of the magnetically soft material, the magnetic marker having a structure comprising a cylindrical coil, helix, conical coil, spherical coil, random "ball of yarn" and a polyhedron. The deployable magnetic marker may comprise a plurality of elements of magnetically soft material, the elements being joined with collapsible links between them such that the elements collapse together to form an amorphous region when deployed. A needle or cannula-based delivery device may contain the magnetic marker, the delivery device constraining the marker in a packed configuration, the marker expanding to an unpacked configuration upon deployment from the delivery device.



ABSTRACT

Various embodiments of magnetic marker for marking a site in a tissue in a body comprise a solid material characterized by specific magnetic coercitivity, specific magnetic mass susceptibility, and specific magnetic anisotropy of susceptibility. In some embodiments, the magnetic marker is deployable, comprising a multi-stranded cable or a wire formed of the magnetically soft material, the magnetic marker having a structure comprising a cylindrical coil, helix, conical coil, spherical coil, random “ball of yarn” and a polyhedron. The deployable magnetic marker may comprise a plurality of elements of magnetically soft material, the elements being joined with collapsible links between them such that the elements collapse together to form an amorphous region when deployed. A needle or cannula-based delivery device may contain the magnetic marker, the delivery device constraining the marker in a packed configuration, the marker expanding to an unpacked configuration upon deployment from the delivery device.

MARKER MATERIALS AND FORMS FOR MAGNETIC MARKER LOCALIZATION (MML)

RELATED APPLICATIONS

[0001] This application claims priority from US Provisional Patent Application 62/170,768 filed on June 4, 2015.

FIELD OF THE INVENTION

[0002] The invention relates generally to the field of markers for medical detection and more specifically to magnetic medical markers.

BACKGROUND OF THE INVENTION

[0003] With the increasing prevalence of mammography screening programs, the majority of breast cancers are detected as small, non-palpable (or occult) lesions that are amenable to breast conserving treatment. Accurate localization of non-palpable breast cancers is key to allowing surgical removal of the complete tumor with adequate margins. If the tumor is not completely excised, patients need to undergo a further operation to remove any remaining cancerous tissue. Accurate localization also helps to avoid excision of excess breast tissue that could result in adverse cosmetic results. Accurate localization is required by other cancers such as colorectal, prostate and lung, as well as other conditions known by those of ordinary skill in this art.

[0004] The current gold standard for localization of non-palpable lesions during surgery is wire-guided localization (WGL). Although this technique is widely used, WGL has a number of disadvantages. First, it involves two separate procedures, and can present logistical and scheduling difficulties between radiology and surgery departments. Second, the positioning of the guidewire may not be optimal for achieving the desired cosmetic result in the subsequent surgery. Third, the hook wire can migrate away from the site of the lesion or become displaced during mammography or moving the patient. Fourth, the insertion of the wire can be painful for patients and finally, the risk of infection means that surgery usually needs to take place the same day as the wire insertion.

[0005] In order to overcome these disadvantages, other localization techniques have been developed. One such technique is Radioguided Occult Lesion Localization (ROLL) using a radiotracer injected into the tumor and detected by a handheld gamma probe. Although this removes the logistical complexity of WGL, the technique introduces the drawback of the use of radioactive materials, which require special handling and disposal procedures.

[0006] Magnetic markers are also used, and they overcome the inconvenience and logistical challenges that arise by using a radioactive material as a marker, and they also avoid the drawbacks of guide-wires. However, magnetic markers are relatively complex to manufacture compared with guide-wires.

[0007] All known marking devices, including wire guides and magnetic markers, are introduced through a hollow needle or cannula. To minimize patient discomfort, this needle is typically narrow in diameter. The small diameter of the needle constrains the marker cross section. For conventional biopsy needles this dimension is generally 14 to 18 gauge. This means that the needle has an internal diameter generally of 0.8mm to 1.5mm but may possibly be as large as 1.8mm for certain needle designs. If a vacuum-assisted needle is used, the needle size is typically 11 gauge, with an internal diameter of 2.3 to 2.5 mm. Thus, the magnetic markers are typically constrained to be less than 1.5mm in diameter. In practice, these size constraints limit the magnetic response and in turn the ease with which the marker can be localised with a magnetic probe. Therefore, a stronger magnetic response is desired.

[0008] Another challenge for magnetic biopsy markers is that to achieve an effective magnetic response, the volume of material needs to be maximised. This volume requirement results in a typically shaped marker having a length significantly greater than its diameter. Such markers are in the region of 1mm to 12mm, with an aspect, length to diameter ratio greater than 4 or greater than 5. This aspect ratio results in a non-uniform magnetic response with a much stronger signal being obtained when the marker major axis

is in line with a probe, and a weaker signal when the marker major axis is transverse to the probe. A more uniform response is generally desired.

[0009] Further, the marker is generally guided to its position and confirmed to be in place under ultrasound or stereotactic x-ray imaging. This means that it is desirable for the marker to be clearly visible under X-ray and ultrasound imaging, and preferably under MRI, which can also be used for this purpose.

[0010] What is needed is a marker that has a small amount of material without reducing the intensity of the detectable signal, and provides a more uniform response from any direction relative to the magnetic probe.

[0011] The present invention addresses this need.

SUMMARY OF THE INVENTION

[0012] The invention relates to magnetic markers for surgical use. In particular, it relates to magnetic markers with a more uniform magnetic response once deployed than would be expected from their geometry prior to deployment.

[0013] In one aspect, markers are provided whose shape is chosen such that they give a more uniform magnetic response.

[0014] In another aspect, markers are provided whose geometrical configuration changes once deployed such that they give a more uniform magnetic response.

[0015] In another aspect, markers are provided whose material composition is chosen such that they give a more uniform magnetic response than would be expected from their geometry prior to deployment.

[0016] In one aspect, the marker is in a non-spherical configuration having a ratio of anisotropy of magnetic susceptibility of less than 9. In yet another embodiment, the marker is in a non-spherical configuration having a ratio of anisotropy of magnetic susceptibility of less than 6. In still yet another embodiment, the marker is in a non-

spherical configuration having a ratio of anisotropy of magnetic susceptibility of less than 3. In one embodiment, the non-spherical marker configuration is of the shape selected from the group comprising a cylinder, a cable, a “dumbbell-like” form, a bead and a ball of yarn. In another embodiment, the cylinder bends upon placement in tissue. In yet another embodiment, the non-spherical configuration is faceted.

[0017] In one embodiment, the marker is a magnetic marker for marking a site in tissue in the body comprising: a plurality of magnetic components linked by flexible non-magnetic components that compact upon placement in the site. In another embodiment, the magnetic marker for marking a site in tissue in the body includes a magnetic component of a first shape located within a non-magnetic matrix of a second shape. In yet another embodiment, the magnetic marker for marking a site in tissue in the body includes a magnetic material core within a magnetic material sheath. In still another embodiment, one of the core and the sheath is a soft-magnetic material.

[0018] In one embodiment, the magnetic marker for marking a site in tissue in the body includes a plurality of magnetic components which self assemble into the magnetic marker following placement of the markers into the body. In another embodiment, the magnetic components are each encased within a super-hydrophobic coating. In still yet another embodiment, the magnetic marker for marking a site in tissue in the body includes a magnetic metallic glass.

[0019] According to different implementations of the magnetic marker, there is provided:

- A magnetic marker for marking a site in a tissue in a body, the marker comprising a first solid material having a first length and a first width, the first solid material having a magnetic coercivity of less than 100 Oe with a magnetic mass susceptibility of $>0.05 \text{ m}^3 \text{ kg}^{-1}$ and wherein the marker has a first ratio of magnetic anisotropy of susceptibility of less than about 9.

- A deployable magnetic marker for marking a site in a tissue; the magnetic marker being formed of a solid, magnetically soft material having a magnetic coercivity of less than or equal to 79.6 kAm^{-1} and a magnetic mass susceptibility of at least $0.05 \text{ m}^3 \text{ kg}^{-1}$; wherein the magnetic marker comprises a multi-stranded cable, the marker having a non-spherical shape and a ratio of anisotropy of magnetic susceptibility of less than 9 when deployed.
- A deployable magnetic marker for marking a site in a tissue comprising a wire formed of a magnetically soft material having a magnetic coercivity of less than or equal to 1000 Oe and a magnetic mass susceptibility of at least $0.05 \text{ m}^3 \text{ kg}^{-1}$; wherein the magnetic marker has a structure selected from the group comprising a cylindrical coil, helix, conical coil, spherical coil, random “ball of yarn” and a polyhedron when deployed, having a ratio of anisotropy of magnetic susceptibility of less than 9.
- A deployable magnetic marker; the magnetic marker being formed of a solid, magnetically soft material having a magnetic coercivity of less than or equal to 79.6 kAm^{-1} ; wherein the magnetic marker comprises a plurality of elements of said magnetically soft material, the elements joined with collapsible links between them such that on deployment the elements collapse together to form an amorphous region having a ratio of anisotropy of magnetic susceptibility of less than 9 when deployed..

BRIEF DESCRIPTION OF THE DRAWINGS

[0020] The structure and function of the invention can be best understood from the description herein in conjunction with the accompanying figures. The figures are not necessarily to scale, emphasis instead generally being placed upon illustrative principles. The figures are to be considered illustrative in all aspects and are not intended to limit the invention, the scope of which is defined only by the claims.

[0021] Figs. 1(A) and (B) are magnetization curves for soft and hard magnetic material respectively;

[0022] Fig. 2(A) is a graph of the influence of marker bend angle on anisotropy of susceptibility of a marker;

[0023] Fig. 2(B) is a diagram of an embodiment of a test arrangement for measuring magnetic anisotropy of a marker;

[0024] Fig.2(C) is a signal at a constant distance from 5mm Iron (99.5%) markers with various inclusive angles, where 180-degrees is a straight cylinder and 0-degrees is U-shaped;

[0025] Fig. 2(D) is a graph of a signal at a constant distance from 7mm multi-stand stainless steel markers with various inclusive angles, where 180-degrees is a straight cylinder and 0-degrees is U-shaped;

[0026] Fig. 3(A) is a diagram of an embodiment of the invention in the form of a “lozenge” or a “bead”;

[0027] Figs. 3(B) and (C) are cross-sections of magnetic beads with shaped ends;

[0028] Figs. 4(A)-(D) are diagrams of embodiments of the invention in the form of “dumbbell” shapes;

[0029] Figs. 5(A) and (B) are diagrams of cross-sections of embodiments of the invention in cable form;

[0030] Figs. 6(A) and 6(B) are diagrams of an embodiment of the invention in the shape of a “ball of yarn”;

[0031] Fig. 7 is a diagram of an embodiment of the invention in the shape of a “Chinese lantern”;

[0032] Figs. 8 (A)-(G) are diagrams of embodiments of the invention with hinged linkages;

[0033] Fig. 9 is a collection of diagrams of cross-sections of embodiments of markers of the invention with increased numbers of faces;

[0034] Fig. 10 is a diagram of the cross-section of an embodiment of the invention in the form of core and sheath;

[0035] Fig. 11 is a diagram of the drawing of an embodiment of the invention having a sheath and multiple cores;

[0036] Figs. 12(A) and (B) are diagrams of embodiments of the invention as segmented markers;

[0037] Figs. 13 (A), (B) and (C) are diagrams of embodiments of the invention in which the shape of the magnetic material and the external shape of the marker are different;

[0038] Figs. 14 (A)-(E) are diagrams of embodiments of the invention in the form of shaped markers with hinges made of various materials;

[0039] Fig. 15 is a diagram of an embodiment of the invention constructed by self assembly;

[0040] Fig. 16 is a diagram of an embodiment of the invention constructed by hydrophobic self-assembly;

[0041] Figs. 17 (A) and (B) are diagrams of other embodiments of the invention constructed by self-assembly;

[0042] Fig. 18 is a diagram of an embodiment of two interlocking U shaped markers.

DESCRIPTION OF PREFERRED EMBODIMENTS

[0043] A method for making magnetic markers as permanent magnets is described in US Patent No. 6,173,715. Permanent magnet implants have the drawback that they will attract any magnetic material in the vicinity and therefore could interact undesirably with other implants, or move in the tissue, for example, when a surgical tool made from magnetic material is nearby.

[0044] A method for making markers formed from superparamagnetic iron oxide (SPIO) nanoparticles in bioabsorbable form is described in US Publication No. 2014/0314679. SPIO particles avoid the concerns that occur for permanent magnetic markers because such materials have no magnetic remanence, and are not magnetic in themselves, but only become magnetized when in the presence of a magnetic field. The detection and localization of these SPIO magnetic markers can be performed with a sensitive magnetometer (or susceptometer) that generates an alternating magnetic field to excite the marker magnetically, and detects the magnetic field signature generated by the marker, as disclosed in US Publication No. 2011/0133730.

[0045] Another challenge for magnetic biopsy markers is that to achieve an effective magnetic response, the volume of material needs to be maximised. These requirements result in a typical marker having length significantly greater than the diameter because the marker must be delivered through a needle and smaller needle gauges (diameters) are less painful for patients. Such markers are in the region of 1mm to 12mm, with length to diameter ratio greater than 4 or greater than 5. In practice, these size constraints limit the magnetic response and in turn the ease with which the marker can be localised with a magnetic probe. Therefore a stronger response is desired.

[0046] Further, the marker is generally guided to its position and confirmed to be in place under ultrasound or stereotactic x-ray imaging. This means that it is desirable for the marker to be clearly visible under X-ray and ultrasound imaging, and preferably under MRI, which can also be used for this purpose. SPIO particles have limited visibility under X-ray imaging but can be made ultrasound visible by combining them in a matrix of

echogenic material, for example a polymer. Although magnetic markers overcome the drawbacks of guide-wires and radioactive approaches, there remains a need for a magnetic marker that can be introduced through a narrow needle, gives a strong magnetic response, is visible under X-ray and ultrasound imaging, and can be manufactured simply.

[0047] The requirement for the marker to be magnetically localisable requires a certain magnetic response from the implanted material, and for this response to be measurable at a distance removed from the material. This response is related to the magnetic susceptibility parameter. In SI units the magnetic susceptibility is a dimensionless proportionality constant that indicates the degree of magnetization induced in a material in response to an applied magnetic field, and is defined by:

$$\mathbf{M} = \chi \mathbf{H}$$

where \mathbf{M} is the magnetisation of the material (the magnetic dipole moment per unit volume), measured in amperes per meter, \mathbf{H} is the magnetic field strength, also measured in amperes per meter, and χ is the dimensionless proportionality constant, the magnetic susceptibility. Strictly speaking, χ is only constant for paramagnetic or diamagnetic materials, however, in soft magnetic or superparamagnetic materials where the magnetic hysteresis effect is small, and for applied fields \mathbf{H} that are much less than the field required to magnetically saturate the materials, the linear relationship $\mathbf{M} = \chi \mathbf{H}$ is a good approximation.

[0048] Magnetic susceptibility can be measured by a range of known methods including the Faraday balance, Gouy balance, the magnetic resonance method, and the inductive method with SQUID magnetometer. Magnetic susceptibility can also be calculated using computer-based finite element magnetic modelling packages such as ANSYS Maxwell (ANSYS Inc., Canonsburg, PA), by modelling the marker in a homogenous field and measuring the distortions caused by the marker which correspond to the magnetic susceptibility. See for example the method described in: "Magnetic Susceptibility Modelling Using ANSYS", K. Bartusek et al., Progress In Electromagnetics Research Symposium Proceedings, Marrakesh, Morocco, Mar. 20–23, 2011.

[0049] For a given material, a magnetic mass susceptibility can be defined which is the induced magnetic response per unit mass of the material. Magnetic mass susceptibility, $\chi_p = k/\rho$ where ρ is the density of the material and χ_p has units of m^3/kg . This is a normalized susceptibility and allows the relative susceptibilities of different materials to be compared. For example, the magnetic mass susceptibility of 316 stainless steel, a standard material for biopsy markers, has a range of approximately 3.80×10^{-7} to 1.27×10^{-6} , a permanent Neodymium magnet has a value approximately of 6.67×10^{-6} , Super Paramagnetic Iron Oxide (SPIO) based markers have a value of approximately 2.5×10^{-5} - 1.0×10^{-3} depending on the density of particles in a matrix, while NiZn-ferrites have a range of approximately 3×10^{-3} to 1.22×10^{-1} . Therefore, the NiZn-ferrites require less material to be detected than SPIO which in turn require less material than permanent Neodymium magnetic material or 316 stainless steel.

[0050] For a magnetically soft marker of volume V , subject to a field \mathbf{H} in the linear susceptibility region, the total induced moment on the marker will be $\mathbf{m} = \mathbf{M} V = \chi V \mathbf{H}$. This moment will give rise to its own magnetic field $\mathbf{H}_{\text{marker}}$, which at a distance removed from the marker may be approximated as that due to an equivalent point dipole moment, namely:

$$\mathbf{H}_{\text{marker}}(\mathbf{r}) \cong \frac{1}{4\pi} \left(\frac{3\mathbf{r}(\mathbf{m} \cdot \mathbf{r})}{r^5} - \frac{\mathbf{m}}{r^3} \right)$$

where \mathbf{r} is the unit vector. It is this induced field, $\mathbf{H}_{\text{marker}}$, that is measurable and which makes the magnetic marker localizable.

[0051] However, there are other factors that may affect the ease with which a given marker may be located – or in other words, affect the strength of the induced field, $\mathbf{H}_{\text{marker}}$, at a given \mathbf{r} . One of these is known as ‘demagnetization’. This is a phenomenon that occurs in objects of finite size, where the induced field due to the magnetization in one part of the body acts to demagnetize another part of the same body. The effect is very complex to predict in other than the most simple geometries, and is therefore most often described, as here, for the special case of the object being an ellipsoid of revolution (e.g. a sphere,

cylinder or disk). In such a case, the induced magnetization within the object is uniform, and the local magnetic field is commonly written:

$$\mathbf{H}_{\text{local}} = \mathbf{H} - \mathbf{H}_{\text{demag}} = \mathbf{H} - N \mathbf{M}$$

where $\mathbf{H}_{\text{demag}}$ is the ‘demagnetisation field’ and N is the ‘demagnetisation factor’, although more accurately $\mathbf{H}_{\text{demag}}$ should be defined along the x,y,z principal axes of the ellipsoid, as:

$$H_{\text{demag}}^x = N_x M_x, \quad H_{\text{demag}}^y = N_y M_y, \quad \text{and} \quad H_{\text{demag}}^z = N_z M_z.$$

[0052] In SI units $N_x + N_y + N_z = 1$. For the case of a sphere, $N_x = N_y = N_z = 1/3$. For the case of a long z-axis cylinder, $N_x = N_y = 1/2$ and $N_z = 0$. For the case of a thin xy-plane disk, $N_x = N_y = 0$ and $N_z = 1$. In the case of a marker made from a given single material of a given mass, the shape of that marker will affect the ease with which it may be localized.

[0053] For example: if the marker is made into a sphere, it will experience $\mathbf{H}_{\text{local}} = \mathbf{H} - 1/3 \mathbf{M}$, irrespective of the orientation of the marker to the applied field. The induced moment will therefore be:

$$\mathbf{m} = \chi V \mathbf{H}_{\text{local}} = \chi V \mathbf{H} - 1/3 \chi \mathbf{m}, \quad \text{or} \quad \mathbf{m} = \chi V \mathbf{H} / (1 + 1/3 \chi)$$

[0054] The induced field, $\mathbf{H}_{\text{marker}}$, will therefore also be reduced by a factor of $(1 + 1/3 \chi)$ at any given r , but this reduction will be present irrespective of the orientation of the marker to the magnetizing field \mathbf{H} .

[0055] In contrast: if the marker were made into a cylinder, then if \mathbf{H} was directed perpendicular to the long axis of the cylinder, then $\mathbf{H}_{\text{marker}}$ would be reduced by a factor of $(1 + 1/2 \chi)$, whereas if \mathbf{H} was directed along the long axis, $\mathbf{H}_{\text{marker}}$ would not be reduced at all. In this case the ratio $\xi = (1 + 1/2 \chi) / 1$ represents the anisotropic localization signal that the cylinder would present to any method dependent on the magnitude of $\mathbf{H}_{\text{marker}}$ for its signal strength.

[0056] In the case of a cylinder of finite length, this ratio may be approximated as:

$$\xi = \frac{1 + N_{\perp} \chi}{1 + N_{\parallel} \chi}$$

where $N_{\perp} = N_x = N_y$, and $N_{\parallel} = N_z = 1 - 2 N_{\perp}$. For example, in the case of the ferritic stainless steel samples listed in Table 2, for which χ is approximately 140, the measured ξ ratio of 10.3:1 for a cylinder of aspect ratio 7:1 corresponds to an N_{\perp} of approximately 0.48; while the same material in a cylinder of aspect ratio 3.7:1 exhibited an anisotropy ratio ξ of approximately 4.7:1, corresponding to an N_{\perp} of approximately 0.44.

[0057] Thus, for a magnetic marker, the magnetic response depends partly on the mass susceptibility of its constituent material or materials, and partly on the shape of the marker, and for a given shape, the response can change with orientation of the marker. The anisotropy of the magnetic response can be calculated by using demagnetization factors as outlined above. However, as demagnetization factors are very difficult to calculate for real shapes, a more practical approach is needed to define the anisotropy of the response. The change in magnetic response with orientation for a given marker can be thought of as a change in the 'effective susceptibility' of the marker. The underlying susceptibility of the marker material does not change, but the change in magnetic response due to the combination of material, shape and orientation can be defined as if the susceptibility were varying.

[0058] Thus, for any given marker, a ratio can be defined of the maximum (effective) magnetic susceptibility to the minimum (effective) magnetic susceptibility. This ratio can be referred to as the anisotropy of the magnetic susceptibility and gives an indication of the uniformity of the magnetic susceptibility response along different axes of the marker or from different directions.

$$\text{Anisotropy of magnetic susceptibility} = \frac{\text{Maximum magnetic susceptibility}}{\text{Minimum magnetic susceptibility}}$$

[0059] As magnetic susceptibility is dimensionless, the anisotropy of magnetic susceptibility, being a ratio of two dimensionless quantities, is also dimensionless. If the

anisotropy is 1, the susceptibility is the same from any direction. If the anisotropy is high, the susceptibility is very non-uniform with respect to the orientation of the marker.

[0060] The concept of anisotropy of magnetic susceptibility is described in the art and can be measured by a number of methods. For example, two types of directional susceptibility meter are described in A. K. Dubey, "*Understanding an Orogenic Belt*", Springer Geology: An equal-impedance bridge where the specimen can be inserted into a coil; and a balanced-transformer system where the specimen is placed inside a ferrite ring. A further method called a three dimensional magnetic anisotropic susceptibility meter is described in US Patent No. 3,492,566. In each case, a consistent magnetic field is applied to the sample, and the variation in the induced magnetic response is measured as the sample orientation is varied. A further such method is shown in Figure 2(C) in which a susceptometry probe is used to measure the induced magnetic response. Using a magnetic susceptometer system, similar to that described in US Publication No. 2011/0133730, markers produced from various materials and in various forms had their maximum and minimum signals measured at a fixed distance. Results are shown in Table 3.

[0061] Measuring the anisotropy of magnetic susceptibility using a magnetic susceptibility probe or meter is the ideal approach to defining the uniformity of the magnetic response of a marker. However, there are alternative approaches to determining the level of anisotropy of magnetic susceptibility. For example, the projected area of the marker in any direction can be measured and maximum and minimum projected areas determined. For a given volume of marker material, a lower projected area indicates a greater focussing effect of the field and visa versa. As the focussing effect is inversely proportional to the projected area, the uniformity of response can thus be defined by the ratio of the *minimum* projected area to the *maximum* projected area of the marker out of all the available viewpoints or directions. This is the projected area anisotropy ratio of the magnetic marker, and provides a useful approximation to the anisotropy of magnetic susceptibility. A spherical marker would have a ratio of the *minimum* projected area to the *maximum* projected area = 1. A rod shaped marker of diameter, $d = 0.75$ and length, $l = 7.5$ would have a ratio of $d \times l / (\pi \times d^2/4) = 12.7$.

[0062] It can also be seen that this ratio of projected areas is approximately equal to the shape factor of the marker, which is defined as the ratio of the largest dimension of the marker to its smallest dimension and this too can be used as an approximation to the anisotropy of magnetic susceptibility. Both these geometric methods do not account for variations in the magnetic properties within the marker.

[0063] Where the term 'anisotropy of magnetic susceptibility' or magnetic anisotropy is used throughout, the term 'projected area anisotropy' or 'ratio of largest to smallest dimension' are understood as alternative interchangeable measures of the uniformity of the magnetic response.

[0064] The anisotropy of magnetic susceptibility can be determined for the marker both before deployment when in the delivery device and after deployment. Where the marker configuration changes, the anisotropy of magnetic susceptibility may have a different value before and after deployment.

[0065] From a practical perspective, during surgery to detect the marker using a magnetic probe as described in WO2014/013235, high anisotropy is undesirable: the magnetic signal at a constant distance will vary depending on the orientation of the marker relative to the probe and make the marker appear to be closer when approaching from some orientations and further away from others. Minimising the anisotropy for the implanted marker improves the surgeons' ability to localise the marker by making it more intuitive and increases the surgeons' ability to remove a safe margin of tissue around a lesion. An anisotropy ratio of 1 is the ideal, giving a uniform response from any direction. However, in practice this is challenging to achieve within the geometric constraints of delivery through a small needle as outlined herein. An anisotropy ratio of less than 7 (i.e. between 1 and 7), preferably less than 5 and more preferably less than 3 is desirable. Because the magnetic response reduces with distance exponentially, an anisotropy ratio of less than 2 is close enough to the ideal for practical use.

[0066] An ideal magnetic marker becomes magnetized in the presence of a magnetic field and exhibits no permanent magnetic remanence (retained magnetisation) when the

field is removed, or in other words, an ideal marker is magnetically soft, i.e. formed from magnetically soft material or behaving as if it is magnetically soft. Magnetically soft is here defined as having a magnetic coercivity, H_c , of less than or equal to 1000 Oe, or preferably less than or equal to 100 Oe or more preferably less than or equal to 50 Oe is desired in various embodiments. During detection, the marker is magnetised and follows the dotted curve 101 shown in Fig. 1, returning via the solid line 102 when the magnetic field is removed or reversed. When an alternating magnetic field is applied, the magnetizing drive field (H) pushes the material along the solid magnetisation curve 102 around the loop once for each cycle. The induced field in the material (termed the magnetization, M) is detected by the susceptometer probe, for example the probe of US Publication No. 2011/0133730. Ideal marker materials are soft and have a magnetization curve similar to that in Fig. 1A.

[0067] It should be noted that permanent magnets are magnetically hard, having both a high magnetic remanence and a high magnetic coercivity (Fig. 1(B)). They are generally unsuitable for use as a magnetic marker in this application because they can attract or be attracted by other ferromagnetic objects such as surgical tools and because they typically have very low magnetic susceptibility.

[0068] The amount of material required to be implanted to make a magnetic marker detectable depends upon the magnetic susceptibility (χ_v) of the material, more specifically the magnetic mass susceptibility ($\chi_p = \chi_v/\rho$), which can be expressed as:

$$\chi_p = (\mu_r - 1)/\rho$$

where μ_r is the relative magnetic permeability and ρ is the material density.

[0069] The material used in the magnetic marker should have a relative permeability greater than 100, and preferably greater than 500. When specialist magnetic materials such as high purity iron or amorphous materials such as metallic glasses are used, relative permeability is greater than 1000 and preferably greater than 5000. The marker should have a high magnetic mass susceptibility, χ_p . For conventional magnetic materials such as

irons, steels and ferrites, χ_p should be greater than or equal to $0.05 \text{ m}^3\text{kg}^{-1}$, preferably greater than or equal to $0.1 \text{ m}^3\text{kg}^{-1}$ and more preferably greater than or equal to $1 \text{ m}^3\text{kg}^{-1}$. The use of specialist magnetic materials such as high purity iron or amorphous materials such as metallic glasses allows even higher magnetic mass susceptibilities, and χ_p is preferably greater than $5 \text{ m}^3\text{kg}^{-1}$ and more preferably greater than $10 \text{ m}^3\text{kg}^{-1}$.

[0070] If material magnetic mass susceptibility is high enough, a spherical marker, which is capable of being deployed from the conventional needle described, would be capable of being magnetically localised and provide a perfectly isotropic signal. Table 1 shows mass susceptibilities for a number of magnetic materials.

Material	Magnetic Mass Susceptibility, $\chi_p (\text{m}^3\text{kg}^{-1})$
Metglas	127
Iron (99.95% pure Fe annealed in H)	25.3
Nanoperm	10.9
Mu-metal	2.29-5.72
Cobalt-Iron (high permeability)	2.22
Permalloy	0.917
Iron (99.8% pure)	0.633
Electrical steel	0.506
Ferrite (manganese zinc)	0.128 to 0.300
Ferritic stainless steel (annealed)	0.128 to 0.231
Ferrite (nickel zinc)	0.003 to 0.128
Martensitic stainless steel (annealed)	0.096 to 0.122
Nickel	0.0111 to 0.0673

Carbon Steel	0.0127
Martensitic stainless steel (hardened)	0.005 to 0.0121
301 (55% cold worked)	0.00165
304 (80% cold worked)	0.000380
Neodymium permanent magnet	0.00000667
Samarium Cobalt permanent magnet	0.00000602
316 (81% cold worked)	0.00000127
304 (annealed)	0.000000506
316 (annealed)	0.000000380
Nitinol	0.000000297
Platinum	0.0000000124
Titanium	0.0000000111
PET	0.000000000714
Gold	-0.000000000104
PTFE	-0.00000000182
Silicone	-0.00000000200
Water	-0.00000000800
Carbon graphite	-0.0000000190

*Various material magnetic mass susceptibilities
Note: negative values denote diamagnetic material.*

Table 1

[0071] The detection and localization of these magnetic markers can be performed with a sensitive magnetometer (or susceptometer) which generates an alternating magnetic field, to excite the marker magnetically, and detects the magnetic field signature generated

by the marker, as disclosed in US Publication No. 2011/0133730. The marker could also be detected by other techniques such as MRI, magnetic particle imaging, eddy current measurement, hall effect, or magnetotomography.

[0072] In one aspect of the invention, the marker comprises superparamagnetic particles. Superparamagnetic particles typically contain an iron oxide (magnetite and/or maghaemite) core surrounded by a biocompatible coating such as dextran, carboxydextran, other sugars, albumin, PEG, or biocompatible polymers. To exhibit superparamagnetic behaviour, the particles' magnetic cores need to be below a critical diameter, typically in the range 3-25nm depending on the material and structure.

[0073] Iron oxide is the preferred material for the superparamagnetic core because of its low toxicity, but there are other materials which could form a superparamagnetic core. The material of the core should be one that is capable of being magnetically ordered. It may be a metal, such as cobalt, iron, or nickel; a metal alloy, rare earth and transition metal alloy, M-type or spinel ferrite containing aluminium, barium, bismuth, cerium, chromium, cobalt, copper, dysprosium, erbium, europium, gadolinium, holmium, iron, lanthanum, lutetium, manganese, molybdenum, neodymium, nickel, niobium, palladium, platinum, praseodymium, promethium, samarium, strontium, terbium, thulium, titanium, vanadium, ytterbium, and yttrium or a mixture thereof.

[0074] The core can also be formed by oxidising a combination of an iron(II) salt and another metal salt. The metal salts which are beneficial include salts of aluminium, barium, bismuth, cerium, chromium, cobalt, copper, dysprosium, erbium, europium, gadolinium, holmium, iron, lanthanum, lutetium, manganese, molybdenum, neodymium, nickel, niobium, palladium, platinum, praseodymium, promethium, samarium, strontium, terbium, thulium, titanium, vanadium, ytterbium, and yttrium.

[0075] In another aspect of the invention, the marker comprises a solid, magnetically soft material to provide a significantly increased magnetic response when being localised with a magnetic susceptometry probe. Markers produced from magnetically soft materials can include various paramagnetic, ferromagnetic and ferrimagnetic materials such as iron,

nickel, cobalt and their alloys, electrical iron (including FM, consumet electrical iron), silicon-irons (including “A”, “A-FM”, “B”, “B-FM”, “C” variants) iron-phosphorous, nickel-iron (e.g. HyRa alloys, HyMu alloys, Hipernom, Parmalloy, Superalloy, Mu-metal), Heusler alloys, Fernico alloys (Iron-Nickel-Cobalt based alloys), Cunife alloys (Copper-Nickel-Iron based alloys), Alcomax alloys (Iron-Nickel-Aluminium-Cobalt-Copper based alloys) various stainless steels from the 300 series (e.g. 302, 304, 316), 400 series (e.g. 410, 416, 420, 430, 440, 446, 470) as well as specialist stainless steel alloys (e.g. chrome-iron alloys such as Chrome-Core® series (Carpenter Technology Corp, Wyomissing PA), martensitic stainless steels), ferrites such as MnZn-ferrites, NiZn-ferrites, MgZn-ferrites, Ba-ferrites, MnMgZn-ferrites, and MgZnCu-ferrites.

[0076] In a preferred aspect of the invention, the marker comprises a metallic glass with a very high magnetic mass susceptibility to provide a significantly improved magnetic response. Metallic glasses are also known as amorphous metal or bulk metallic glass and include Fe or Co based material such as those produced by Metglas Inc. (Conway, SC) or Neomax Materials Co. Ltd (Osaka, Japan); and magnetic carbon allotropes (e.g. fullerenes, highly oriented pyrolytic graphite, carbon nanofoams, nano-porous carbon). Examples of metallic glasses include but are not limited to: FINEMET, NANOPERM, HITPERM (all Hitachi Metals, Tokyo, Japan), METGLAS #2605, METGLAS #2826, METGLAS #2615, METGLAS #2714A, METGLAS #2605.

[0077] In order to ensure biocompatibility, these materials may be coated or contained within a biocompatible or inert material for example Bioglass, diamond-like-carbon (DLC), gold, hydroxyapatite, Iron, magnesium, nitinol, parylene, phosphorylcholine (PC) polymer, Poly-butyl methacrylate (PMBA) and polyethylenevinyl acetate (PEVA), polyethylene, PET, polytetrafluoroethylene (PTFE), PEBAX, PEEK, PEKK, platinum, silicone, titanium and the like.

[0078] Further a shaped material such as a spring steel or shape memory materials alloys such as Nitinol, and shape memory polymers such as PEO-PET coblock polymers

and PEEK could also provide additional function of forming a specific shape on deployment if surrounding or surrounded by a magnetically soft material.

[0079] The magnetic material could further be held within a biocompatible matrix, such as collagen, gelatin and other cellulose base materials, Polyvinyl alcohol (PVA), Polyglyconate, polyester based materials (formed by homopolymerization or copolymerization of one or more of these monomers: glycolide, L-lactide and its isomers, ϵ -caprolactone, p-dioxanone and trimethylene carbonate (TMC). These may include homopolymers such as: Poly(L-lactide) Poly(DL-lactide), Poly(TMC), Polycaprolactone (PCL), Polyglycolide (PGA), Poly(glycolide-L-lactide) (PGL), or Poly(p-dioxanone) (PDS); or co-polymers such as: L-Lactide/DL-Lactide, L-lactide/Glycolide, L-lactide/Caprolactone, DL-Lactide/Glycolide, DL-Lactide/Caprolactone, Glycolide/Caprolactone, L-lactide/Glycolide/Caprolactone, DL-Lactide/Glycolide/Caprolactone, Poly(dioxinone co-trim ethylene carbonate-co-glycolide) Glykomer 631 (marketed as Biosyn®); or copolymers of these with PDS, hydrogels (from one or more monomers of Hydroxyethyl methacrylate, Hydroxyethoxyethyl methacrylate, Hydroxydiethoxyethyl methacrylate, Methoxyethyl methacrylate, Methoxyethoxyethyl methacrylate, Methoxydiethoxyethyl methacrylate, Ethylene glycol dimethacrylate, N-vinyl-2-pyrrolidone, N-isopropyl AAm, Vinyl acetate, Acrylic acid, MAA, N-(2-hydroxypropyl) methacrylamide, Ethylene glycol, PEG acrylate, PEG methacrylate, PEG diacrylate, PEG dimethacrylate).

[0080] In one aspect of the invention the implanted marker is made from a single magnetically soft material and the marker is shaped to reduce the anisotropy of the magnetic response. This anisotropy is defined as the ratio of the maximum magnetic response to the minimum magnetic response. The anisotropy arises in shapes with a long thin aspect ratio because magnetically soft materials focus any magnetic field lines running through them. The focusing effect depends on the amount of material in the direction of the field lines. Thus, a long thin shape when its long axis is aligned with the field focuses many more field lines through the material than when its long axis is perpendicular to the

field lines. The result is that the magnetic response measured by a susceptometer is much larger in the direction of the long axis than in the direction of the short axis.

[0081] Table 2 shows anisotropy ratios for a number of cylinders of magnetic material of various sizes.


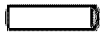

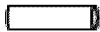
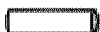
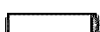







Marker	Dimensional ratio length:diameter	Volume (mm ³)	Signal Max	Signal Min	Anisotropy Ratio
Ferritic stainless steel	3.7	2.1	3885	828	4.7
Ferritic stainless steel	7	4.7	1518	148	10.3
Martensitic stainless steel	7.4	3.1	1135	147	7.7
Fe (99.99%) ϕ 1.0mm	4	3.1	860	216	4.0
Fe (99.95%) ϕ 0.5mm	12	1.2	790	74	10.7
Fe (99.5%) ϕ 1.0mm	5	3.9	2535	321	7.9
MnZn-Ferrite (ϕ 1.0mm)	3.5	5.9	981	166	5.9
Mu Metal multistrand (ϕ 0.6mm)	8.3	1.4	1118	128	8.7

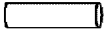



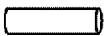






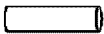
Ratios of anisotropy of magnetic susceptibility for cylinders of various sizes and materials at a constant distance.

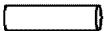
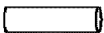






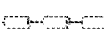


Table 2











[0082] By altering the shape to influence the focussing effect, the anisotropy can be altered. For example, by creating a bend in the marker the anisotropy ratio for a given pre-deployment dimensional ratio can be reduced significantly (Table 3). A 130° included angle surprisingly reduces the ratio from 6.7 to 4.5 and a U bend reduces it further to 2.1. In another example, a 90° bend reduces the ratio from 10.7 to 2.6, and a 60° included angle reduces the ratio further to 1.28. Referring again to Table 2, using a magnetic susceptometer system, similar to that described in US Publication No. 2011/0133730, markers produced from various materials and in various forms had their maximum and minimum signals measured at a fixed distance. The graph shows that there is an optimum angle for a uniform signal when the angle is between 0° and 90°, and more preferably











between 0° and 45°. Figure 18 shows how the signal varies with the angle of sensing relative to the marker's main axis for markers with different included angles.

	Marker	Dimensional ratio length/diameter pre-deployment	Volume (mm ³)	Signal Max	Signal Min	Anisotropy Ratio
	MnZn-Ferrite (ø0.75mm)	10	3.3	4120	202	20.4
	MnZn-Ferrite (ø1.0mm)	3.5	5.9	981	166	5.9
	Ferritic stainless steel	3.7	2.1	3885	828	4.7
	Ferritic stainless steel	7	4.7	1518	148	10.3
	Ferritic stainless steel	11.3	2.7	1070	71	15.1
	Martensitic stainless steel	7.4	3.1	1135	147	7.7
	Ferritic stainless steel multi-strand cable (ø0.91mm)	3.3	2.0	536	120	4.5
	Ferritic stainless steel multi-strand cable (ø0.91mm)	4.4	2.6	939	143	6.6
	Ferritic stainless steel multi-strand cable (ø0.91mm) (straight or 180 inclusive angle)	5.5	3.3	1722	223	7.7
	Ferritic stainless steel multi-strand cable (ø0.91mm) 135-degrees inclusive bend	5.5	3.3	1180	280	4.2
	Ferritic stainless steel multi-strand cable (ø0.91mm) with 90-degree inclusive bend	5.5	3.3	974	384	2.5
	Ferritic stainless steel multi-strand cable (ø0.91mm) with 45-degree inclusive bend	5.5	3.3	624	561	1.1
	Ferritic stainless steel multi-strand cable (ø0.91mm) in 0-degree inclusive angle (U-shape)	5.5	3.3	624	354	1.8

	Marker	Dimensional ratio length:diameter pre-deployment	Volume (mm ³)	Signal Max	Signal Min	Anisotropy Ratio
	Ferritic stainless steel multi-strand cable (ø0.91mm)	7.7	4.6	3660	356	10.3
	Ferritic stainless steel multi-strand cable (ø0.91mm x 6mm) in U-shape	6.6	3.9	846	395	2.1
	Two (2) Ferritic stainless steel multi-strand cable various configurations	6.6 (2 x 3.3)	3.9	810-1091	240-254	3.2-4.6
	Fe (99.5%) ø1.0mm straight or 180-degree inclusive angle	5	3.9	2535	321	7.9
	Fe (99.5%) ø1.0mm straight or 180-degree inclusive angle	7	5.5	3721	417	8.9
	Fe (99.5%) ø1.0mm 135-degrees inclusive bend	7	5.5	2980	594	5.0
	Fe (99.5%) ø1.0mm with 90-degree inclusive bend	7	5.5	2318	884	2.6
	Fe (99.5%) ø1.0mm with 45-degree inclusive bend	7	5.5	1499	1289	1.2
	Fe (99.5%) ø1.0mm in 0-degree inclusive angle (U-shape)	7	5.5	1502	794	1.9
	Fe (99.95%) ø0.5mm	12	1.2	790	74	10.7
	Fe (99.95%) ø0.5mm with 60-degree inclusive bend	12	1.2	458	358	1.3
	Mu Metal multistrand ø0.6mm	8.3	1.4	1118	128	8.7

	Marker	Dimensional ratio length:diameter pre-deployment	Volume (mm ³)	Signal Max	Signal Min	Anisotropy Ratio
	Mu Metal multistrand $\phi 0.6\text{mm}$	11.7	1.9	2475	180	13.7
	Mu Metal multistrand $\phi 0.6\text{mm}$	16.7	2.8	6539	229	28.5
	Mu Metal multistrand $\phi 0.6\text{mm}$ in 0-degree inclusive angle (U-shape)	8.3	1.4	433	202	2.1
	Dumbbell-like: Ferritic stainless steel multi-strand: large $\phi 1.5\text{mm}$ for 1mm, small $\phi 0.91$, overall length 5mm	3.3	4.6	1469	323	4.6
	Ball of yarn type: Metglass $\phi 0.125\text{mm}$, final dimensions loose ball of 2.5mm	41	1.0	1752	949	1.9
	Ball of yarn type: ferritic stainless steel ($\phi 0.3$ wire), final dimensions ball of 2mm x 3mm x 4mm	5.3		1338	787	1.7
	Ball of yarn type with collapsing plastic hinges: ferritic stainless steel ($\phi 0.3$ wire), overall dimensions $\phi 1.5\text{mm}$ x 12mm	8	21.2	1086	750	1.5
	Ball of yarn type with collapsing hinges: ferritic stainless steel ($\phi 0.3$ wire), overall dimensions 1.5mm x 23	11.5	30.1	2030	1501	1.4
	String of columns 3-links: MnZn- Ferrite ($\phi 1.5$)	8	21.2	2327	1769	1.3
	String of columns 4-links: MnZn- Ferrite ($\phi 1.5$)	10.7	28.3	2707	2145	1.3
	Collapsing chain 5-links: Fe 99.95% ($\phi 0.5$ wire), overall dimensions 2mm x 10mm	5	31.4	1390	1086	1.3

	Marker	Dimensional ratio length:diameter pre-deployment	Volume (mm ³)	Signal Max	Signal Min	Anisotropy Ratio
	Spring in circle: Fe 99.95% (ø0.5 wire), overall dimensions 2mm x 20mm (coil width 2mm)	10	62.8	3990	3104	1.3
	Spring in circle: Fe 99.95% (ø0.5 wire), overall dimensions 2mm x 14mm (coil width 2mm)	7	44.0	3249	2305	1.4
	Spiral in circle: Ferritic Stainless Steel (ø0.3 single wire), overall dimensions 0.91mm x 15.7mm	17.4	10.8	772	251	3.1
	Spiral in circle: Ferritic Stainless Steel (2 x ø0.3 wire), overall dimensions 0.91mm x 15.7mm	17.4	10.8	1021	292	3.5
	Spiral in circle: Ferritic Stainless Steel (2 x ø0.3 wire), overall dimensions 0.91mm x 12.6 mm	14	8.7	785	261	3.0
	Interlocked U's: Ferritic stainless steel multi-strand overall dimensions 2mm x 7mm	3.5	15.9	5012	1060	4.7
	Single U of the interlocked U's Ferritic stainless steel multi-strand, overall dimensions 2mm x 6.5mm	3.25	7.9	3253	644	5.1
	Interlocked U's: Ferritic stainless steel multi-strand, overall dimensions 2mm x 5.5mm	2.75	12.2	3159	1045	3.0
	Interlocked U's: Fe (99.95%), overall dimensions 1.5mm x 4mm	2.7	2.4	723	185	3.9
	Tetrahedron from 2-columns: Fe (99.5%) each column ø1.0 x 3mm	9	4.7	858	678	1.3

	Marker	Dimensional ratio length:diameter pre-deployment	Volume (mm ³)	Signal Max	Signal Min	Anisotropy Ratio
	Tetrahedron from 2-columns: Ferritic stainless steel multi-strand, each column $\phi 0.9 \times 5\text{mm}$	11	6.6	1308	1129	1.2
	3 edges of tetrahedron inclusive angle 45-degrees out of plane between edges: Ferritic stainless steel ($\phi 0.3$)	40	0.8	342	231	1.5
	3 edges of tetrahedron inclusive angle 45-degrees out of plane between edges: Fe (99.5%) $\phi 1.0\text{mm}$	7	5.5	875	734	1.2
	3 edges of tetrahedron inclusive angle 45-degrees out of plane between edges: Fe (99.95%) $\phi 0.5\text{mm}$	36	3.5	1608	998	1.6
	3 edges of tetrahedron inclusive angle 45-degrees out of plane between edges: Fe (99.95%) $\phi 0.5\text{mm}$	30	2.9	1072	609	1.8
	Standard Marker Material: 316 stainless steel $\phi 1.0\text{mm}$	6	4.7	0	0	No response
	Standard Marker Material: Gold $\phi 1.0\text{mm}$	3	2.4	0	0	No response
	SecurMark® (Titanium)			0	0	No response
	RFID $\phi 2.1\text{mm} \times 12\text{mm}$	5.7	41.6	4840	330	14.7
	RFID $\phi 1.4\text{mm} \times 8\text{mm}$	5.3	12.3	1858	61	30.5

Anisotropy ratio for various shapes and sizes of magnetic marker at a constant distance
Table 3

[0083] Fig. 2(A) is a graph of the relative change in anisotropy ratio as the included angle of a bend in the marker is reduced. The measurements were taken using the test

arrangement 201 in Fig. 2(B). The graph (Fig. 2A) shows that there is an optimum angle for a uniform signal when the angle is between 0° and 90°, and more preferably between 0° and 45°. Fig. 2(C) is a graph that shows how the signal varies with the angle of sensing relative to the marker's main axis for iron markers with different included angles. Fig. 2(D) is a graph that shows how the signal varies with the angle of sensing relative to the marker's main axis for iron markers 202 with different included angles.

[0084] In some cases, it may be advantageous for the marker to assume the shape only after it has been deployed so that it can be packed more efficiently into the deployment needle prior to deployment. An elastic material or a section of elastic material may be used to facilitate this.

[0085] Such shapes include, but are not limited to the following:

[0086] - “lozenge” or “bead” shapes 301 (Fig. 3(A)), that reduce the anisotropy by providing more magnetic material in the transverse axis (perpendicular to the long axis of the bead). Such markers may include shaped ends 302-305 comprising narrower sections that focus the field in a direction away from the main axis 306 (Figs. 3(B) and (C)). For example, a finite element model of the marker of Fig. 3(C) and a probe of the type described in US Publication No. 2011/0133730 with the marker at a distance of 20 mm from the probe end gave an anisotropy ratio of magnetic susceptibility of 2.5;

[0087] - “dumbbell-type” designs 401-404 as shown in Figs. 4 (A)-(D), are constructed from segments of the same material. This design similarly provides more magnetic material along the transverse axis. In various embodiments, the markers being about 5-10 mm in length, and are useful in reducing the opposing eddy currents. For example, a finite element model of the marker of Fig. 4(B) and a probe of the type described in US Publication No. 2011/0133730 with the marker at a distance of 20 mm from the probe end gave an anisotropy ratio of magnetic susceptibility of 2.6;

[0088] - cable or multi-wire strands 501 as shown in Figs. 5(A) and (B) and may be twisted. A number of stranding forms are illustrated, but other stranding forms such as

1x4, 1x5 etc. with 3, 4, 5, 6, 7 or more strands are equally viable; using strands reduces the opposing eddy current loss and having multiple facets provides superior ultrasound response. The wires could also be hollow as illustrated or include void areas between the strands;

[0089] - bent wires or tubes including acute and obtuse angles, U shapes, X shapes (Table 3);

[0090] - a single length of cylindrical marker divided into two or more small pieces of a similar size gives an improved anisotropy ratio of less than 5;

[0091] - a cylindrical marker with a larger diameter central section and smaller diameter outer sections also gives an improved anisotropy ratio;

[0092] - markers 1801 composed of two interlocked U shaped elements 1802 and 1803 (Fig. 18).

[0093] In one aspect of the invention, the implanted marker is made primarily from a magnetically soft material and the marker has a long thin aspect ratio prior to deployment but changes configuration after deployment to a shape with a low anisotropy of the magnetic susceptibility. Prior to deployment, the marker may have a length to diameter ratio or shape factor of greater than 5, and a ratio of magnetic anisotropy of susceptibility of greater than 5 or even greater than 7 or 9, such values resulting from the extended length of the marker prior to deployment and being beneficial to increase the volume of marker contained in the needle so as to maximize the magnetic response once deployed. After deployment, the ratio of magnetic anisotropy of susceptibility is less than 5 and preferably less than 3, and ideally 2 or less to provide a more uniform magnetic response.

[0094] In one aspect, the marker is elastically deformable or resiliently deformable such that it elastically or resiliently changes in shape and size from a packed or pre-deployment shape within the needle or deployment device with an associated shape factor, to a post-deployment shape and shape factor. The elasticity or resilience may, for example, derive from the use of an elastic or resilient material or from an elastic, resilient or

deployable structure or combinations thereof. Preferably, the magnetic marker is elastically or resiliently deformable between a packed configuration having a higher anisotropy of magnetic susceptibility, and a deployed / unpacked configuration having a lower anisotropy of magnetic susceptibility. Alternatively, the magnetic marker is elastically or resiliently deformable between a packed configuration having a higher projected area anisotropy ratio, and a deployed / unpacked configuration having a lower projected area anisotropy ratio.

[0095] Preferably the deployed or delivered configuration of the marker has an anisotropy of magnetic susceptibility of less than 5, more preferably less than 3 and ideally less than 2 in order to give the most uniform detection signal; while prior to deployment within the delivery device, the marker in its packed configuration has an anisotropy of magnetic susceptibility of greater than 5 and more preferably greater than 7, in order to maximize the volume of material in the marker given the constrained diameter of the delivery device. By analogy, the marker in its packed configuration has a projected area anisotropy ratio of greater than 5 and more preferably greater than 7; but in a deployed / unpacked configuration has a projected area anisotropy ratio of less than 5, more preferably less than 3 and ideally less than 2. In order to achieve this configuration change, the marker requires a degree of resilience whereby one dimension (e.g., the diameter perpendicular to the main axis) of the marker changes by a factor of, at least, 1.5 times from its packed value to its deployed value. Preferably the deployed dimension is larger than the packed dimension by a factor of greater than 2 and more preferably greater than 3 in order to provide a shape factor (ratio of maximum dimension to minimum dimension) close to 1 or 2 on deployment, while still having sufficient material to be detected.

[0096] The magnetic marker in its packed configuration is packed within a delivery device prior to use. The delivery device needs to be able to deliver the marker through the skin to mark the tissue area of interest, for example a cancerous lesion. Suitable delivery devices include any needle- or cannula-based delivery system, typically comprising a needle and means to propel the marker through the end or out of the side of the needle such

as a plunger or stylet. The needle is preferably 14 to 18 gauge. This means that the needle has an internal diameter generally of 0.8mm to 1.5mm but may possibly be as large as 1.8mm for certain needle designs. Preferably it is between 1.0 and 1.5mm in diameter. If a vacuum-assisted needle is used, the needle size is typically 11 gauge, with an internal diameter of 2.3 to 2.5 mm.

[0097] Markers that achieve the desired change in anisotropy of the magnetic susceptibility between their packed and unpacked configurations include, but are not limited to the following:

[0098] “ball of yarn” type forms 601-602 (Figs. 6(A) and (B)) that reduce the anisotropy by providing a substantially uniform amount of magnetic material in any given axis of the marker. The multiple facets provide also superior ultrasound response. A ball of yarn such as 601 and 602 is preferably formed from a material with a large magnetic response such as a metallic glass or a magnetically soft material from the list above. The ball may be formed from a fine wire of diameter for example between 10 μ m and 250 μ m and length for example of between 5 mm and 150 mm, and bent into the shape of the ball. The marker may be elastically deformable or resiliently deformable. The marker is compressed to fit inside the deployment needle or delivery device, where, prior to delivery, it may be constrained to take a more cylindrical shape. On deployment the ball such as 601 and 602 expands to close to its original size and takes a substantially spherical shape. Table 3 shows that this marker can achieve an anisotropy ratio of close to the ideal of 1.

[0099] “Chinese-lantern” forms such as 701 (Fig. 7). On deployment, this marker is arranged such that it resiliently reconfigures from a cylinder to a more compressed lantern configuration, thus increasing the uniformity of the magnetic response (reducing anisotropy) because the amount of material in the transverse axis is increased from that of a cylinder. The multiple facets also provide superior ultrasound response.

[0100] Markers comprising a plurality of magnetically soft elements such as 801-807 joined with hinges such as 811-817 as shown in Fig. 8(A)-(G) that deform into shape on deployment (either plastically, pre-stressed or through the action of a shape-memory in the

material). The greater length of the marker in this embodiment is possible because the shape of the marker in the deployment needle is linear but folds to another configuration upon injection into a site. This reduces the anisotropy by providing a substantially uniform amount of magnetic material in any given axis of the marker.

[0101] Advantageously, the multiple facets also provide superior ultrasound response. It is desirable to have at least 3 elements to obtain a uniform response, and many more may be added, although for complexity the number is preferably less than 20 and more preferably less than 10. The hinged and other flexible or resiliently deformable forms may comprise a plurality of smaller magnetic units or components joined by non-magnetic flexible or resiliently deformable links such as plastic or shape memory materials. Combinations of these forms, e.g., bent wire made from multi-strand cable, are also included. As shown in Table 3, a marker of this kind with multiple ball elements and a pre-deployment geometric length:diameter ratio of 8 can have a post-deployment magnetic anisotropy of susceptibility of less than 2.

[0102] Markers comprising a plurality of elements joined with collapsible links between them such that on deployment the elements collapse together to form an amorphous region with a low ratio of magnetic anisotropy of susceptibility. The links can be formed from a string-like material such as suture or other polymer. Preferably, the magnetically soft elements are links in a chain that can collapse on itself after deployment.

[0103] Markers comprising a springy or resiliently deformable wire, or cylindrical shape prior to deployment that on deployment forms a structure or wireframe. Such structures may include a cylindrical coil, helix, conical coil, spherical coil, random 'ball of yarn', or a polyhedron such as a tetrahedron or part thereof.

[0104] Markers comprising a resiliently deformable looped or shaped coil spring that is compressed prior to deployment and expands upon deployment to a shape with a low ratio of magnetic anisotropy of susceptibility. For example, a coil spring shaped into a circle gives a surprisingly low ratio of magnetic anisotropy of susceptibility (Table 3). Preferably,

the ratio of the circle diameter to the spring coil diameter is less than 5 in order to maintain a more uniform magnetic response.

[0105] Markers comprising two or more elements connected by a link formed from an elastic or resiliently deformable or springy material such that the elements once deployed spring into a new configuration giving a low magnetic anisotropy of susceptibility. Table 3 illustrates one such embodiment comprising two short cylindrical elements formed of magnetically soft material joined by a spring filament. In the deployment needle, the two elements are constrained to be aligned axially joined by the filament. The filament is biased such that on deployment the two elements spring back across each other to approximate a tetrahedral shape with a low ratio of magnetic anisotropy of susceptibility of less than 2. The spring filament may be formed from a spring steel, shape memory material or other elastic or resiliently deformable material. Preferably, the length of the cylindrical elements is between 2 and 5 times their diameter to provide good uniformity of response combined with a compact shape. In a further embodiment of this concept, multiple elements on a springy material are deployed from the needle and the springy material is biased such that on deployment the elements are formed into a structure. Example structures may include a cylindrical coil, helix, conical coil, spherical coil, random 'ball of yarn', or a tetrahedron or part thereof. In these designs the length of the marker when in its packed configuration may be between 2 and 5 times their diameter but could be even greater e.g. up to 10 or more times the diameter depending on the degree of elasticity of the structure of material being used, thus allowing more magnetic material to be deployed to maximize the detectability of the marker.

[0106] A further benefit of the “ball of yarn” 601 (Fig. 6) stranded or multi-faceted forms is superior visibility to such reflective imaging techniques as ultrasound, IR or ultra-wideband radar. These benefits can also be realised by revision of the external surface of the other forms mentioned, including the non-hinge sections of the hinged forms 701 (Fig. 7) from cylindrical to faceted or grooved forms such as, but not limited to, triangular 901, pentagonal 902, dodecagon 903, cog-like 904 cross sections (Fig. 9). A similar effect can be observed in ultrasound from sintered materials such as ferrites. Correct choice of soft

material in any of the forms mentioned can provide visibility to X-ray imaging. Interlocked U's 1802 and 1803 take similar space to U but with increased signal and reduced anisotropy (Fig. 18).

[0107] The above features can be combined to provide a marker with reduced anisotropy and improved imaging.

[0108] In a further aspect of the invention, the ratio of magnetic anisotropy of susceptibility of the implanted marker is modified by varying the magnetic properties of the magnetically soft material forming the marker along its length.

[0109] In another aspect of the invention, the reduction in magnetic anisotropy of susceptibility can be achieved through use of composite materials such as the formation of ferrite via sintering with two or more materials where at least one material is a soft material distributed to provide a less anisotropic response. Similar forms can be created, as previously mentioned, where multiple materials are used within the marker. One such embodiment is a single segmented marker with a constant cross section.

[0110] An additional benefit of this aspect of the invention is that the soft distribution or shape can be independent of the external form and cross sections which improve imaging visibility under ultrasound or X-ray can be created. Further examples of composite magnetic markers with decreased anisotropy include soft markers distributed on a collapsible stent-like structure specifically those that are self-expanding.

[0111] Additionally, in a cable or multi-wire strands (especially where twisted) embodiments include hollow versions where the individual wires are formed from different materials or formed from composite material, e.g., a core and a covering or sheath material where at least one or more of these are magnetically soft materials. A specific example of this is where the core 1001 or covering material is made from Nitinol or other shape memory material (including shape memory polymers) which is used to form the post deployment shape (Fig. 10). It is equally possible to create a wire 1101 where a core 1102 produced from multiple materials covered by the sheathing material 1103 is produced and

either used directly as the magnetic marker or subsequently used in cable or multi-strand forms (Fig. 11). The wires or one of the segments multi-core wires could also be used to provide improved X-ray visibility.

[0112] Figs. 12(A) and (B) are examples 1201 and 1202 of segmented marker (note: more or fewer segments are possible). The segmentation increases losses between sections in the axial direction and manages the opposing eddy current effect, reducing the anisotropy.

[0113] Figs 13(A) and (B) show examples 1301 and 1302 of soft material (dark grey) that may be moulded into a shape that is independent of the external shape of the marker (note: more than two materials could be used within the construction). Anisotropy is improved by providing more magnetic material in the transverse axis and reducing the opposing eddy current through combination of the materials selected. In one embodiment 1303 shown in Fig. 13(C), the magnetically soft core 1304 is formed from a material with a very high magnetic response such as a metallic glass such that sufficient magnetic response can be obtained from only a very small sphere of the material. The core 1304 is encased in a protective layer 1305 comprising a biocompatible coating or capsule, for example a titanium shell or a biocompatible polymer coating. Because the core 1304 is spherical, the ratio of magnetic anisotropy of susceptibility is close to 1.

[0114] Shaped markers 1401-1405 with hinges such as 1412, 1414 and 1415 of plastic/pre-stressed/shape memory in multiple materials with different magnetic properties are shown in Figs. 14(A-E). These configurations improve the tailoring of the response in order to reduce the anisotropy by providing a substantially uniform response in any given axis of the marker. The multiple facets also provide superior ultrasound response.

[0115] In another aspect of the invention, a long thin marker is divided into a number of smaller markers. The multiple markers that are packed together prior to deployment have the same overall dimensions and material, and can be used to decrease the anisotropy relative to the overall dimensions of the material. For example, 3 x 2mm long or 2 x 3mm long or 6 x 1mm long marker pieces have decreased anisotropy in comparison to 1 x 6mm

long marker of the same outer diameter. Surprisingly, this reduction in anisotropy occurs even when the segments align one behind each other in the same shape as an individual marker of the combined dimensions. (Table 4) For example, a single marker of dimension 5mm in ferritic stainless steel gives an anisotropy ratio of 6.7. Two markers of the 3mm markers in the same material give an anisotropy ratio of between 3.2 and 4.6 depending on relative orientations.

Marker	Pre-deployment dimensional ratio	Volume (mm ³)	Signal Max	Signal Min	Anisotropy Ratio	Relative Limit of detection
Ferritic stainless steel multi-strand cable (0.91mm in diameter)	3.3	2.0	536	120	4.5	1.6
Ferritic stainless steel multi-strand cable (0.91mm in diameter)	4.4	2.6	939	143	6.6	1.7
Ferritic stainless steel multi-strand cable (0.91mm in diameter)	5.5	3.2	1212	182	6.7	2.0
Two (2) Ferritic stainless steel multi-strand cable various configurations	6.6	3.9	810-1091	240-254	3.2-4.6	1.7-1.9

Table 4

[0116] In a further specific example of this, a set of markers or magnetic particles produced from magnetically soft material can retain a small amount of magnetism. Once deployed into the patient, these magnetic particles can then self-assemble into an associated magnetic marker which possesses lower magnetic anisotropy of susceptibility. Multiple magnetically soft markers 1501 with a small magnetic remanence will self-assemble into an associated magnetic marker 1502 with a substantially uniform amount of material in every direction, thereby minimising anisotropy (Fig. 15). This small magnetic remanence can be overcome by the magnetic excitation of the exciting field of the magnetometer (or susceptometer) as described above. Table 5 shows the parameters of particles assembled by two types of magnetic compositions.

Marker	Pre-deployment dimensional ratio	Volume (mm ³)	Signal Max	Signal Min	Anisotropy Ratio
MnZn-Ferrite (1.0mm in diameter)	3.5	5.9	981	166	5.9
MnZn-Ferrite (0.75mm in diameter)	10	3.3	4120	202	20.4
Assembly of small markers as per Fig. 15 (0.75mm in diameter MnZn-Ferrite)	8.7	2.9	583	448	1.3

Table 5

[0117] In a further example of this, magnetically soft markers or particles encased within hydrophobic surfaces (nano-texturing via lotus effect, silica nano-coatings, EnBio CoBlast PTFE, Hydroxyapatite, carbon nanotube coatings, precipitate calcium carbide & fatty acid coating with polymer latex, manganese oxide polystyrene or zinc oxide polystyrene nano-composites) or spheres will pull together (self-assemble) on deployment into the patient. To minimise surface energy, this embodiment will form a close-packed shape such as a sphere or ellipsoid system which will have an improved magnetic anisotropy of susceptibility relative to the particles within the delivery system which will constrain in an elongated shape to be elongated. Fig. 16 depicts hydrophobic coated markers or particles 1601 which self-assemble, to minimise surface energy, into an associated magnetic marker 1602 with a substantially uniform amount of material in every direction minimising anisotropy.

[0118] In another aspect of the invention, small micromarkers or microparticles 1701, 1702 of a soft material can be suspended within a biocompatible matrix 1703, 1704 (Figs. 17(A) and (B)). Control of the magnetic particle distribution, in a similar manner as discussed with respect to Figs. 10-12, allows a decreased magnetic anisotropy of susceptibility as well as the independence from the outer form. It can also be used to ensure a set location and orientation between the magnetic markers.

[0119] In a further example of this for the case, by using a gel matrix 1704 with a suspension of magnetically soft particles 1702 and by sizing these particles appropriately,

the gel and particles can be deployed through the deployment needle 1705 (Fig. 17(B)). The shape of the deployed gel 1704 and particles 1702 will be constrained only by the injection site (i.e. the tissue of a lesion) which is less in comparison to that of the needle 1705. This gel 1704 can also set on injection making it less likely to migrate from its deployed location and easier to remove surgically if the tissue is being removed. The addition of other particles such as gold to provide additional radiopaque response for x-ray visualisation could be performed if required. For marker localization, the anisotropy should be less than or equal to 9, preferably less than or equal to 6, more preferably less than or equal to 3.

[0120] The present invention provides various ways of making magnetic markers with acceptable anisotropy while not affecting the ease of delivery of the particles.

[0121] In another aspect of the invention, a method is provided for marking a soft tissue site of interest, such as the site of a tumor or benign lesion for example within the breast, lung, bowel/colon, rectum, prostate or other cancer affected organ, or a lymph node within the axilla or other nodal basin within the body. The method includes the steps of (i) inserting such a magnetic marker into tissue near the target lesion or site, and (ii) detecting such a marker using a susceptometer, and optionally (iii) surgically excising the target tissue around the marker. Preferably, the susceptometer detects the marker by providing a magnetic field in the region of the marker and measuring the induced magnetization in the marker.

[0122] Unless otherwise indicated, all numbers expressing lengths, widths, depths, or other dimensions, and so forth used in the specification and claims are to be understood in all instances as indicating both the exact values as shown and as being modified by the term “about.” Accordingly, unless indicated to the contrary, the numerical parameters set forth in the specification and attached claims are approximations that may vary depending upon the desired properties sought to be obtained. At the very least, and not as an attempt to limit the application of the doctrine of equivalents to the scope of the claims, each numerical parameter should at least be construed in light of the number of reported

significant digits and by applying ordinary rounding techniques. Any specific value may vary by 20%.

[0123] The terms “a,” “an,” “the,” and similar referents used in the context of describing the invention (especially in the context of the following claims) are to be construed to cover both the singular and the plural, unless otherwise indicated herein or clearly contradicted by context. All methods described herein can be performed in any suitable order unless otherwise indicated herein or otherwise clearly contradicted by context. The use of any and all examples, or exemplary language (e.g., “such as”) provided herein is intended merely to better illuminate the invention and does not pose a limitation on the scope of any claim. No language in the specification should be construed as indicating any non-claimed element essential to the practice of the invention.

[0124] Groupings of alternative elements or embodiments disclosed herein are not to be construed as limitations. Each group member may be referred to and claimed individually or in any combination with other members of the group or other elements found herein. It is anticipated that one or more members of a group may be included in, or deleted from, a group for reasons of convenience and/or patentability. When any such inclusion or deletion occurs, the specification is deemed to contain the group as modified thus fulfilling the written description of all Markush groups used in the appended claims.

[0125] Certain embodiments are described herein, including the best mode known to the inventor for carrying out the spirit of the present disclosure. Of course, variations on these described embodiments will become apparent to those of ordinary skill in the art upon reading the foregoing description. The inventor expects skilled artisans to employ such variations as appropriate, and the inventor intends for the invention to be practiced otherwise than specifically described herein. Accordingly, the claims include all modifications and equivalents of the subject matter recited in the claims as permitted by applicable law. Moreover, any combination of the above-described elements in all possible variations thereof is contemplated unless otherwise indicated herein or otherwise clearly contradicted by context.

[0126] In closing, it is to be understood that the embodiments disclosed herein are illustrative of the principles of the claims. Other modifications that may be employed are within the scope of the claims. Thus, by way of example, but not of limitation, alternative embodiments may be utilized in accordance with the teachings herein. Accordingly, the claims are not limited to embodiments precisely as shown and described.

CLAIMS

1. A magnetic marker for marking a site in a tissue in a body, the marker comprising a first solid material having a first length and a first width, the first solid material having a magnetic coercivity of less than 100 Oe with a magnetic mass susceptibility of $>0.05 \text{ m}^3\text{kg}^{-1}$ and wherein the marker has a first ratio of magnetic anisotropy of susceptibility of less than about 9.
2. The marker of claim 1, the marker having a ratio of magnetic anisotropy of susceptibility of less than 5.
3. The marker of claim 1 or 2, wherein the marker being deformable between a packed non-spherical configuration prior to deployment having a second ratio of magnetic anisotropy of susceptibility higher than the first ratio and a deployed/unpacked configuration after deployment.
4. A deployable magnetic marker for marking a site in a tissue; the magnetic marker being formed of a solid, magnetically soft material having a magnetic coercivity of less than or equal to 79.6 kAm^{-1} and a magnetic mass susceptibility of at least $0.05 \text{ m}^3\text{kg}^{-1}$; wherein the magnetic marker comprises a multi-stranded cable, the marker having a non-spherical shape and a ratio of anisotropy of magnetic susceptibility of less than 9 when deployed.
5. A deployable magnetic marker for marking a site in a tissue comprising a wire formed of a magnetically soft material having a magnetic coercivity of less than or equal to 1000 Oe and a magnetic mass susceptibility of at least $0.05 \text{ m}^3\text{kg}^{-1}$; wherein the magnetic marker has a structure selected from the group comprising a cylindrical coil, helix, conical coil, spherical coil, random “ball of yarn” and a polyhedron, having a ratio of anisotropy of magnetic susceptibility of less than 9.
6. A deployable magnetic marker; the magnetic marker being formed of a solid, magnetically soft material having a magnetic coercivity of less than or equal to 79.6 kAm^{-1} and a magnetic mass susceptibility of at least $0.05 \text{ m}^3\text{kg}^{-1}$; wherein the magnetic marker

comprises a plurality of elements of said magnetically soft material, the elements joined with collapsible links between them such that on deployment the elements collapse together to form an amorphous region having a ratio of anisotropy of magnetic susceptibility of less than 9 when deployed.

7. The magnetic marker of claim 3, wherein an aspect, length to diameter ratio of the marker before deployment is greater than 4.

8. The magnetic marker of claim 3, wherein the packed non-spherical configuration prior to deployment has a ratio of magnetic anisotropy of susceptibility greater than 5.

9. The magnetic marker of any one of claims 3, 7 and 8, wherein the marker is elastically or resiliently deformable between the packed non-spherical configuration prior to deployment and deployed/unpacked configuration after deployment.

10. The magnetic marker of claim 9, wherein the marker is selected from the group comprising an elastically deformable bent wire and a resiliently deformable bent wire which changes in shape and size from a pre-deployment shape with an associated shape factor having a long thin aspect ratio within a needle or deployment device, to a different post-deployment shape and shape factor having a ratio of magnetic anisotropy of susceptibility of less than 5.

11. The magnetic marker of claim 9, wherein the marker is selected from the group comprising an elastically deformable wire, a resiliently deformable wire, an elastically deformable cylindrical shape, and a resiliently deformable cylindrical shape that on deployment forms a structure or wire frame.

12. The magnetic marker of any one of claims 3 and 7 to 11, wherein the marker comprises a magnetic amorphous material.

13. The magnetic marker of claim 3, wherein the marker is resiliently deformable between the packed non-spherical configuration prior to deployment having a first projected area anisotropy ratio, and the deployed/unpacked configuration after deployment having a second

projected area anisotropy ratio lower than the first projected area anisotropy ratio, said projected area anisotropy ratio being a ratio of minimum projected area to a maximum projected area of the marker in all directions, wherein a marker having a uniform projected area in all directions has a ratio of 1.

14. The magnetic marker of claim 3, wherein the packed non-spherical configuration prior to deployment has a shape selected from the group comprising a cylinder, a cable, a bead, a "dumbbell-like" form, and a ball of yarn.

15. The magnetic marker of claim 3, wherein the packed non-spherical configuration prior to deployment has a shape selected from the group comprising a cylinder and a cable, and wherein the cylinder or cable bends upon placement in the tissue.

16. The magnetic marker of claim 3, wherein the packed non-spherical configuration prior to deployment has a shape selected from the group comprising a cylinder and a cable, wherein the shape bends upon placement into the tissue into the form of edges of a tetrahedron or part thereof.

17. The magnetic marker of claim 3, comprising a plurality of magnetically soft material elements joined with hinges that deform on deployment.

18. The magnetic marker of claim 3, wherein the marker comprises two or more elements connected by a link formed from an elastic or resiliently deformable material such that on deployment the two or more elements are formed into a structure including at least a part of a tetrahedron having the first ratio of magnetic anisotropy of susceptibility.

19. The magnetic marker of claim 3, wherein the deployed/unpacked configuration after deployment has a ratio of magnetic anisotropy of susceptibility less than 3.

20. The magnetic marker of claim 3, comprising one or more magnetic materials, the one or more magnetic materials having a coercivity of less than 50 Oe.

21. The magnetic marker of claim 3, comprising a magnetic component made of one or more materials of a first shape located within a non-magnetic matrix of a second shape.
22. The marker of claim 1, wherein the marker has an aspect ratio greater than 2.7, the aspect ratio being a maximum length of the marker before deployment divided by a maximum orthogonal dimension of the marker before deployment.
23. The marker of claim 1, wherein the first solid material has an elongate shape that is divided into a plurality of segments.
24. A needle or cannula-based delivery device containing a magnetic marker according to any one of claims 1 to 23, wherein the delivery device constrains the marker in a packed configuration, the marker expanding to an unpacked configuration upon deployment thereof from the delivery device.

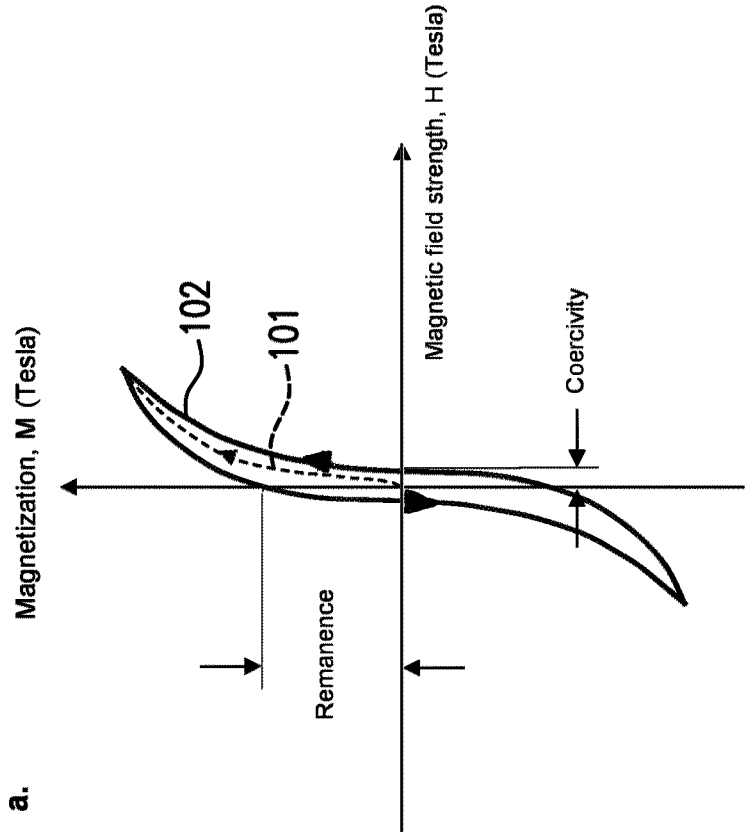


Fig 1(A)

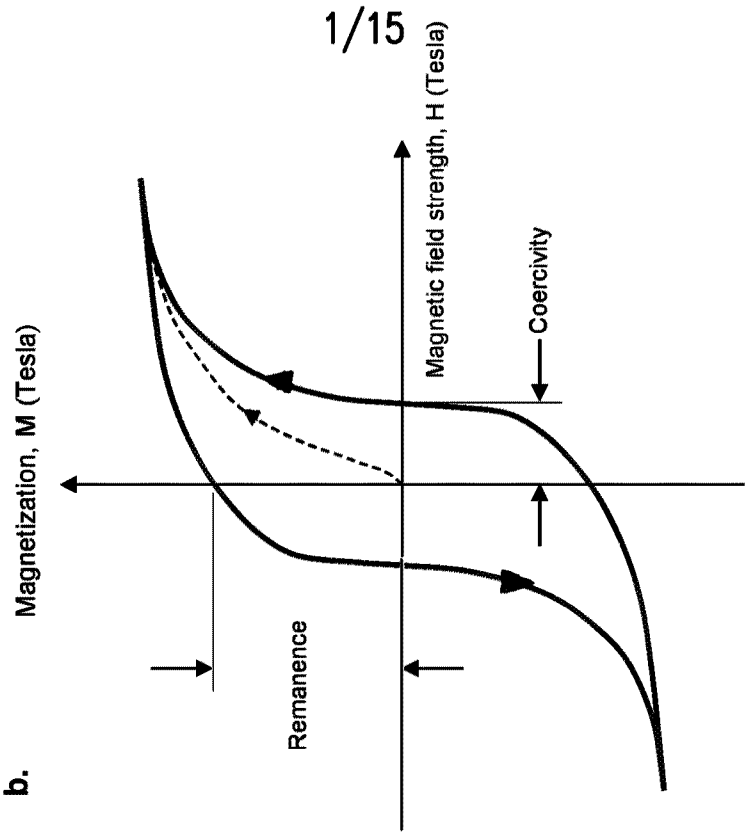


Fig. 1(B)

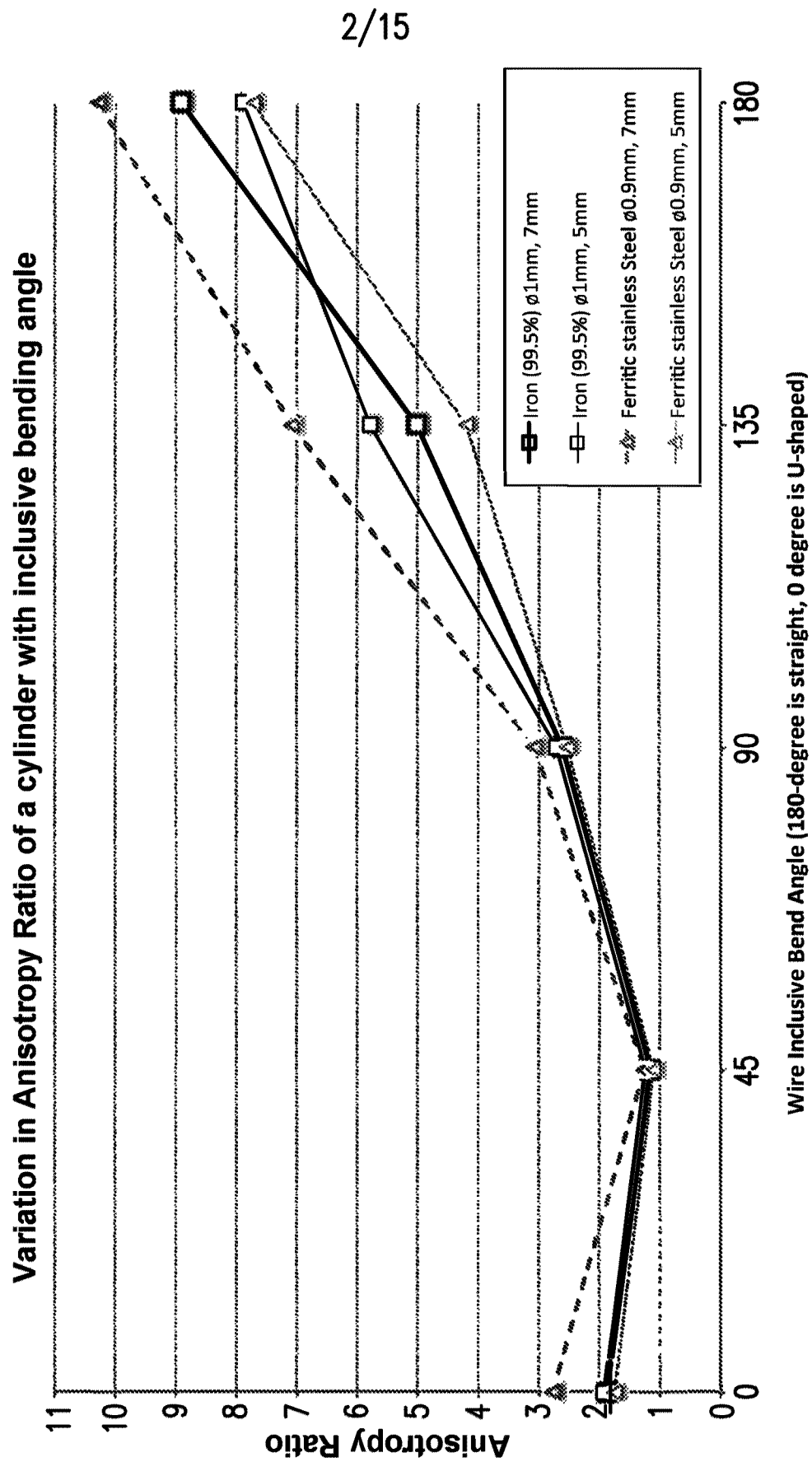


Fig. 2(A)

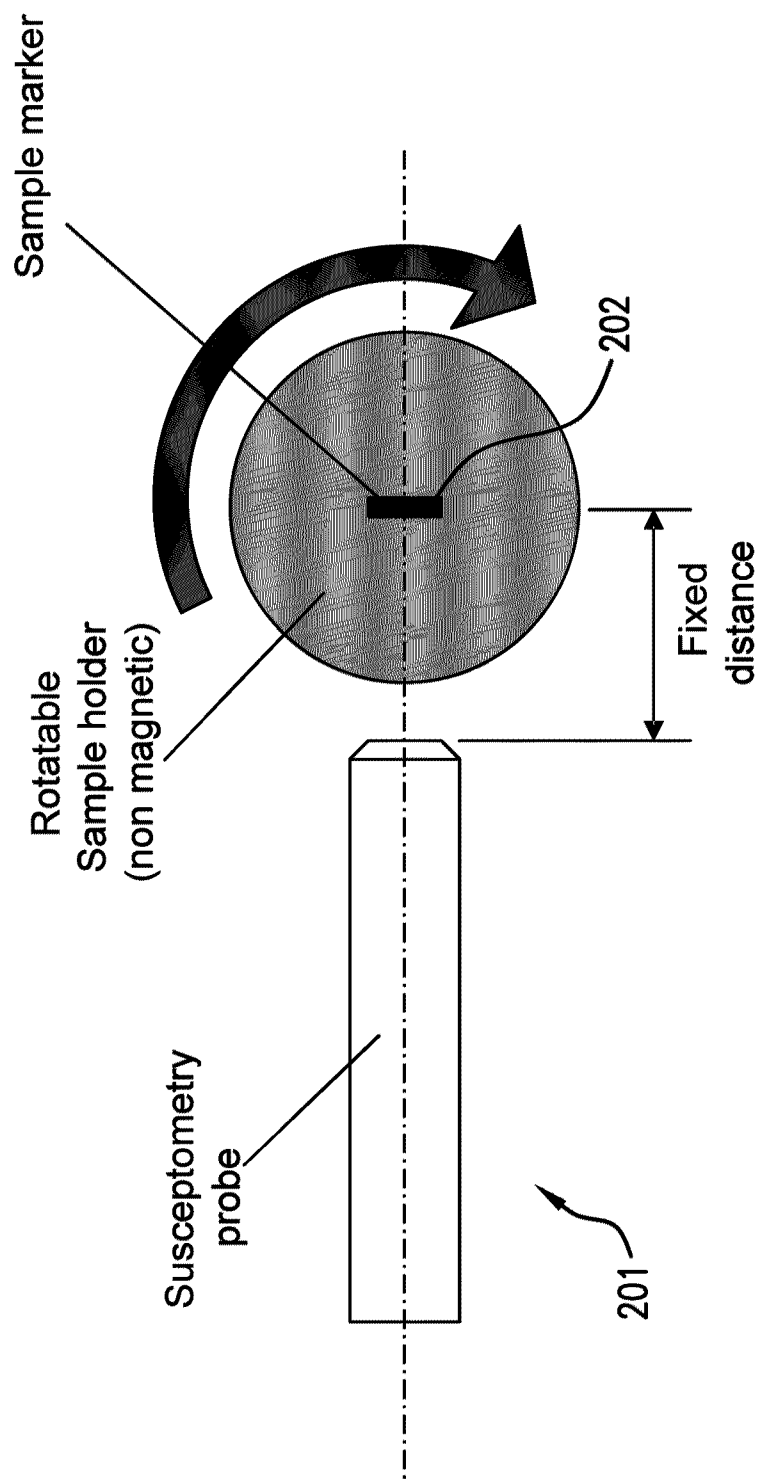


Fig. 2(B)

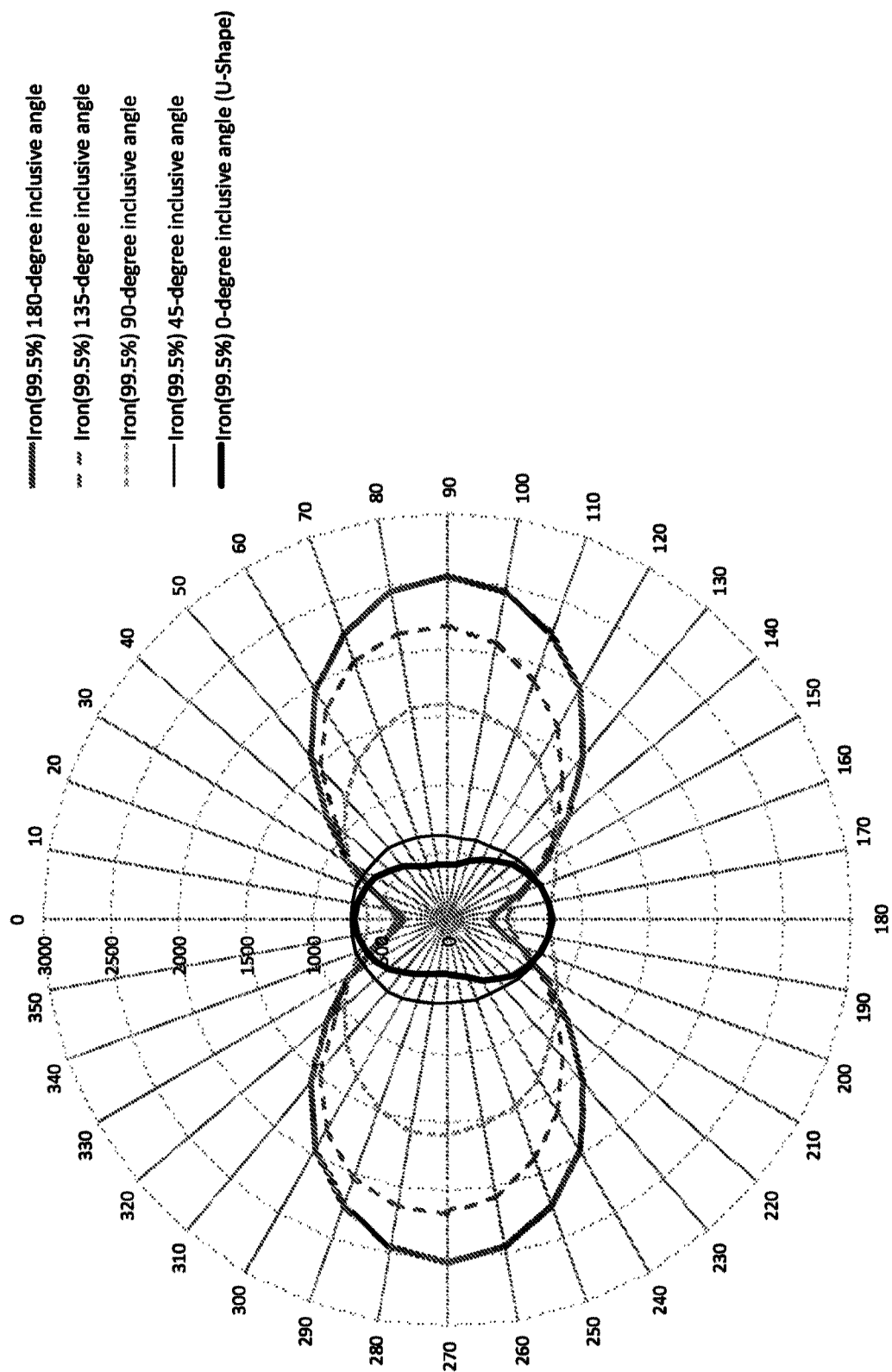


Fig. 2(C)

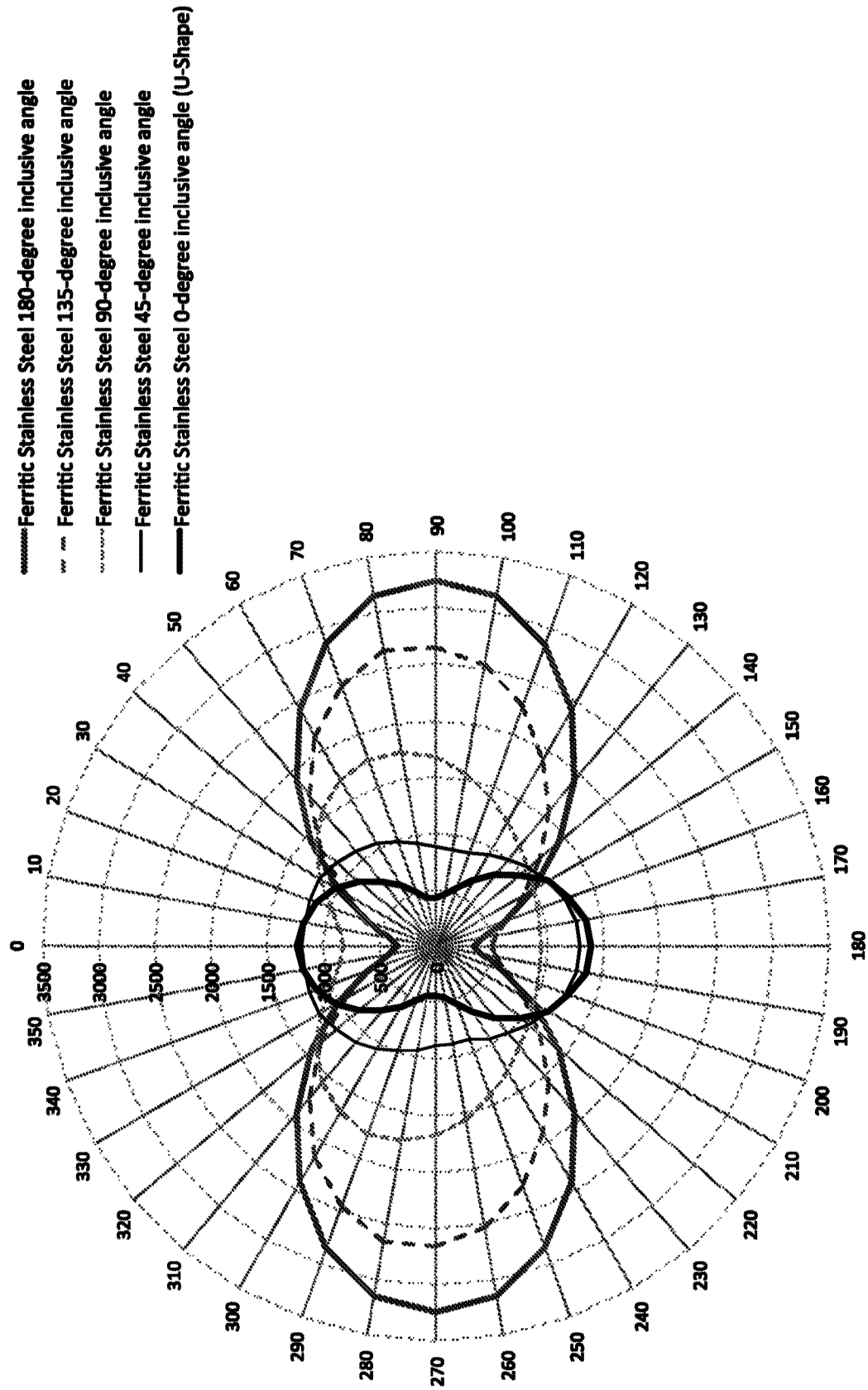


Fig. 2(D)

Fig. 3(A)

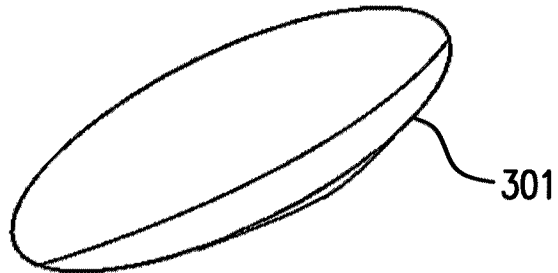


Fig. 3(B)

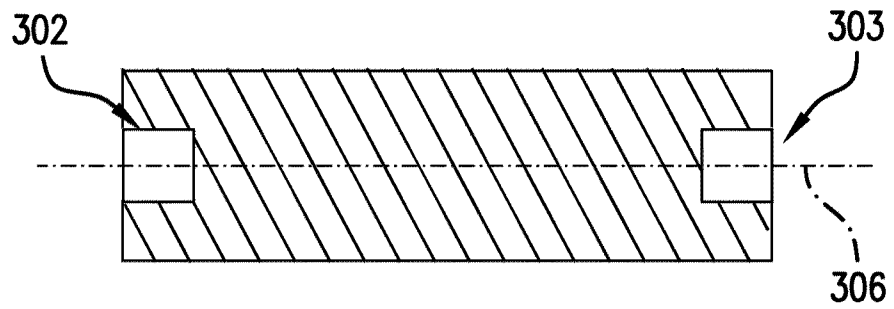
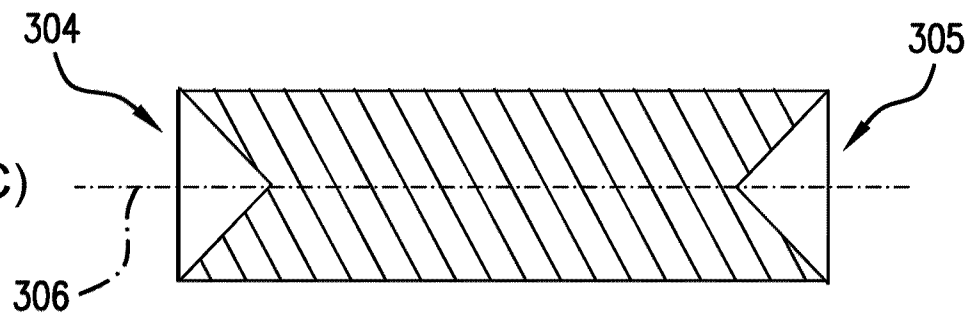
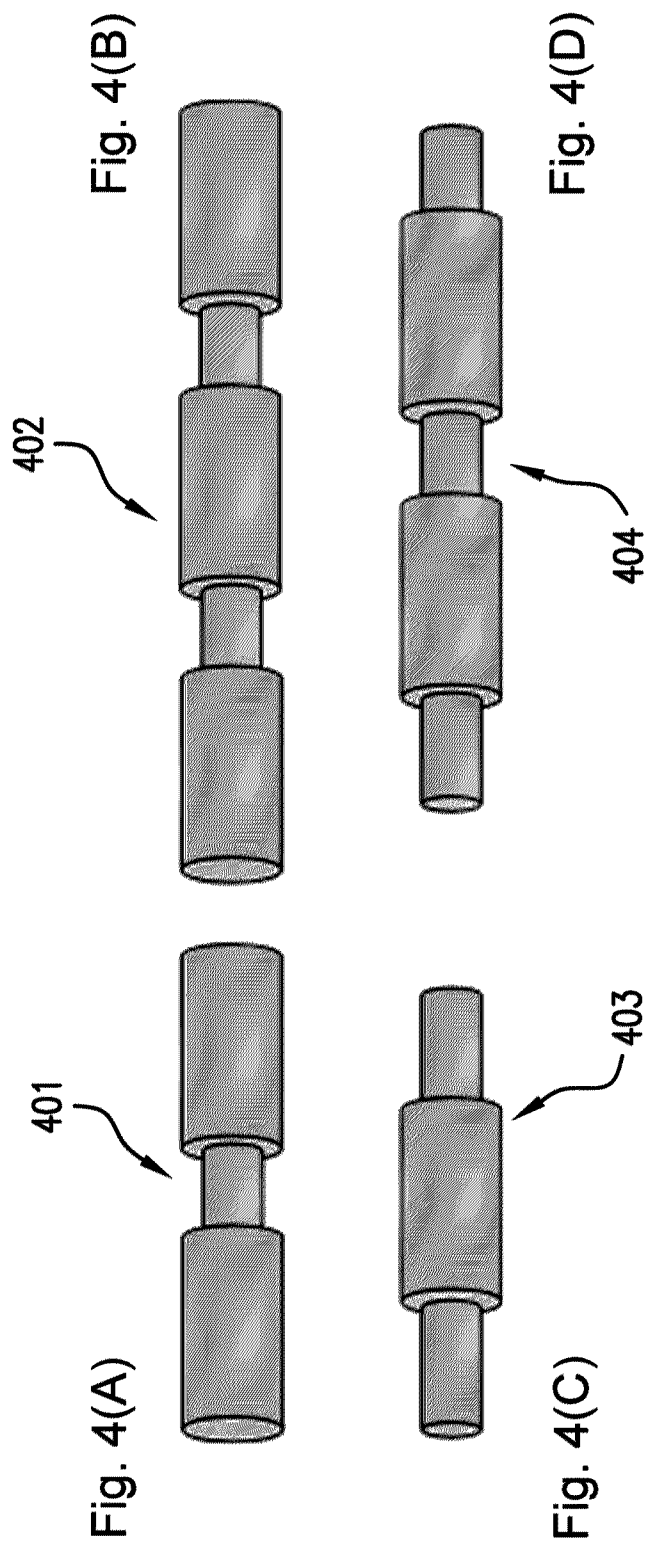


Fig. 3(C)





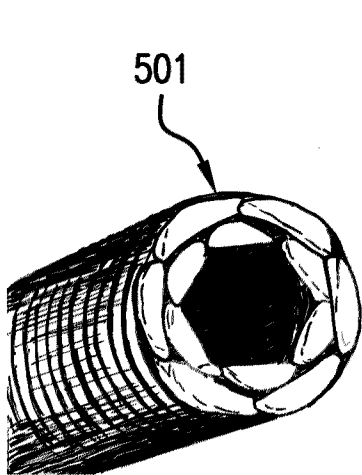


Fig. 5(A)

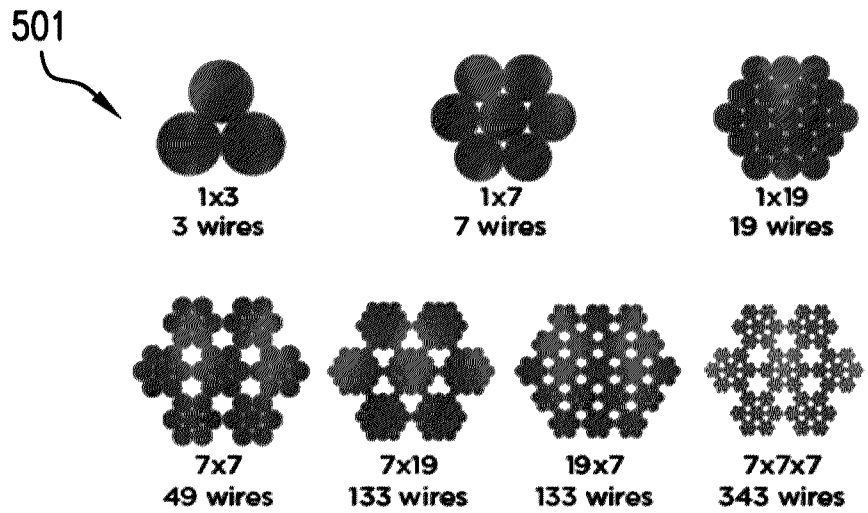


Fig. 5(B)

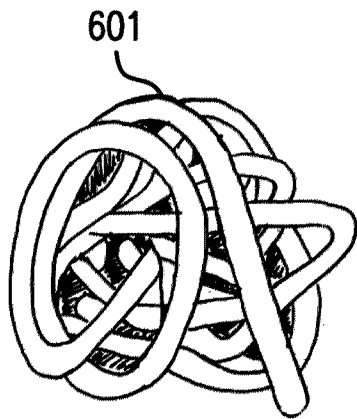


Fig. 6(A)

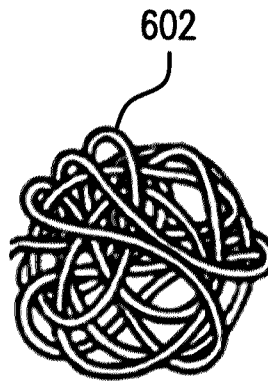


Fig. 6(B)



Fig. 7

Fig. 8(A)

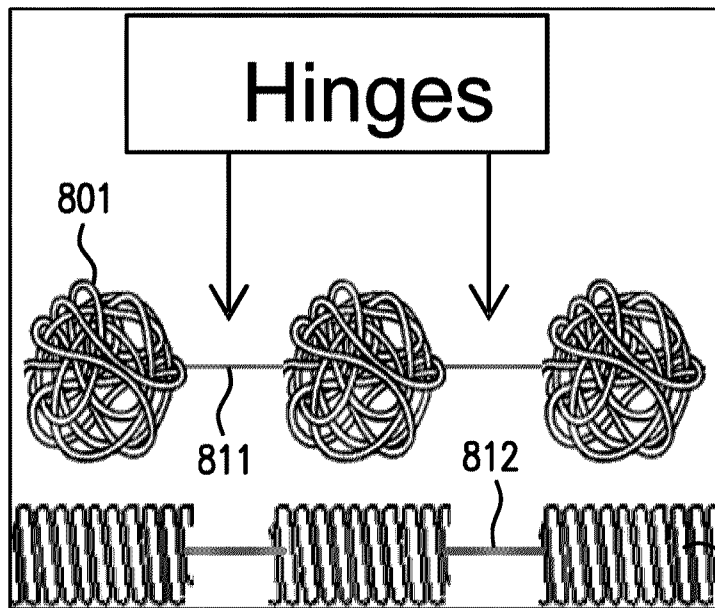


Fig. 8(B)

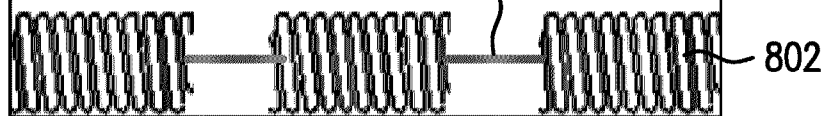


Fig. 8(C)

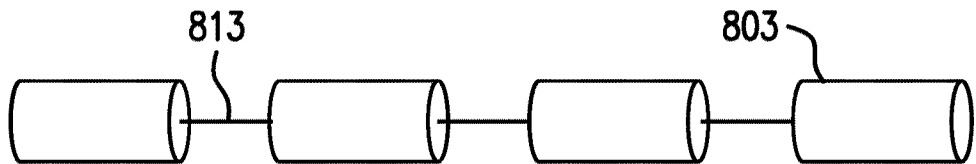


Fig. 8(D)

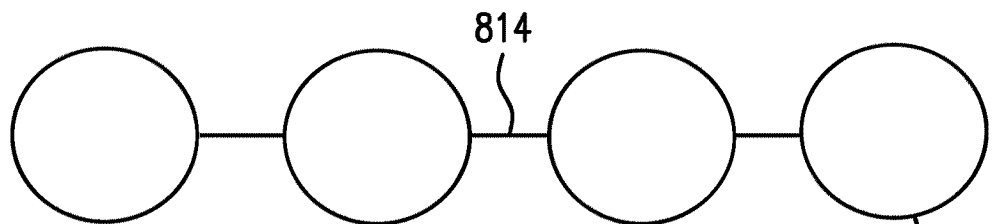


Fig. 8(E)

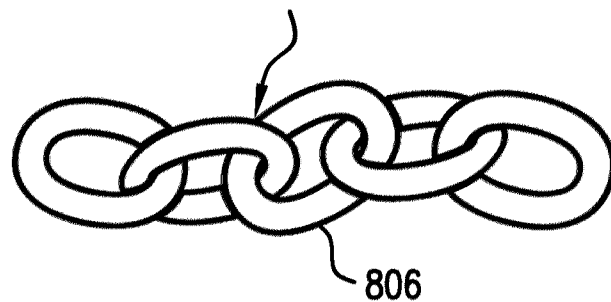
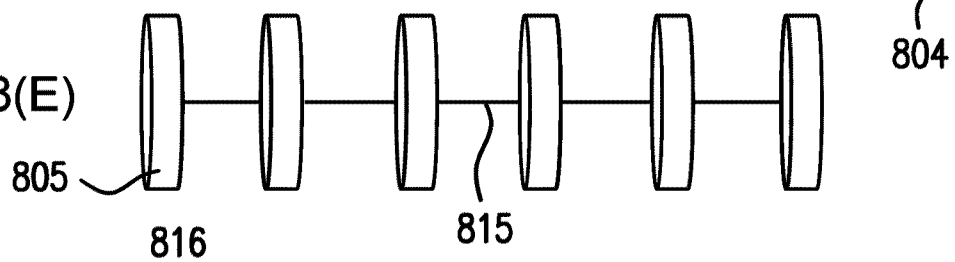


Fig. 8(F)

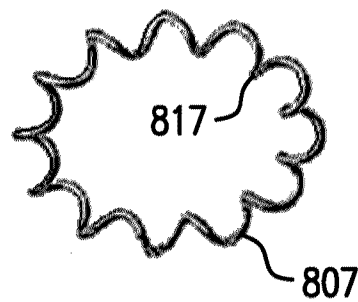
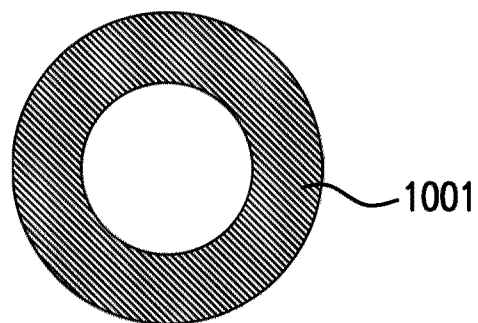
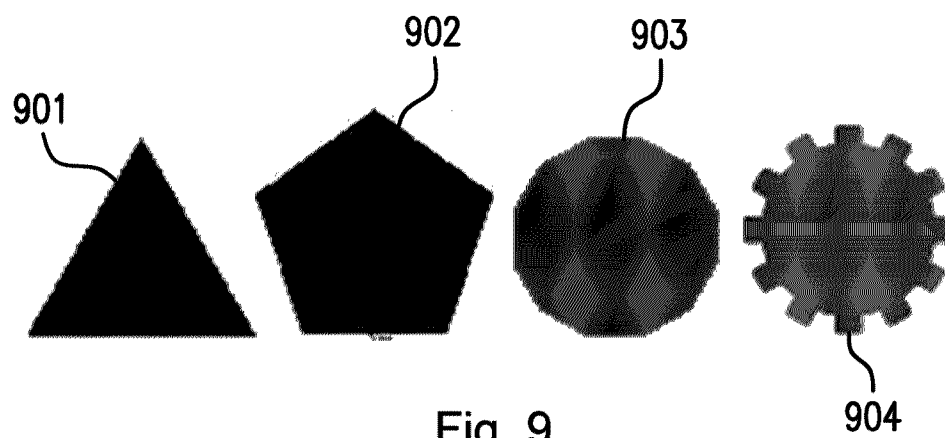


Fig. 8(G)



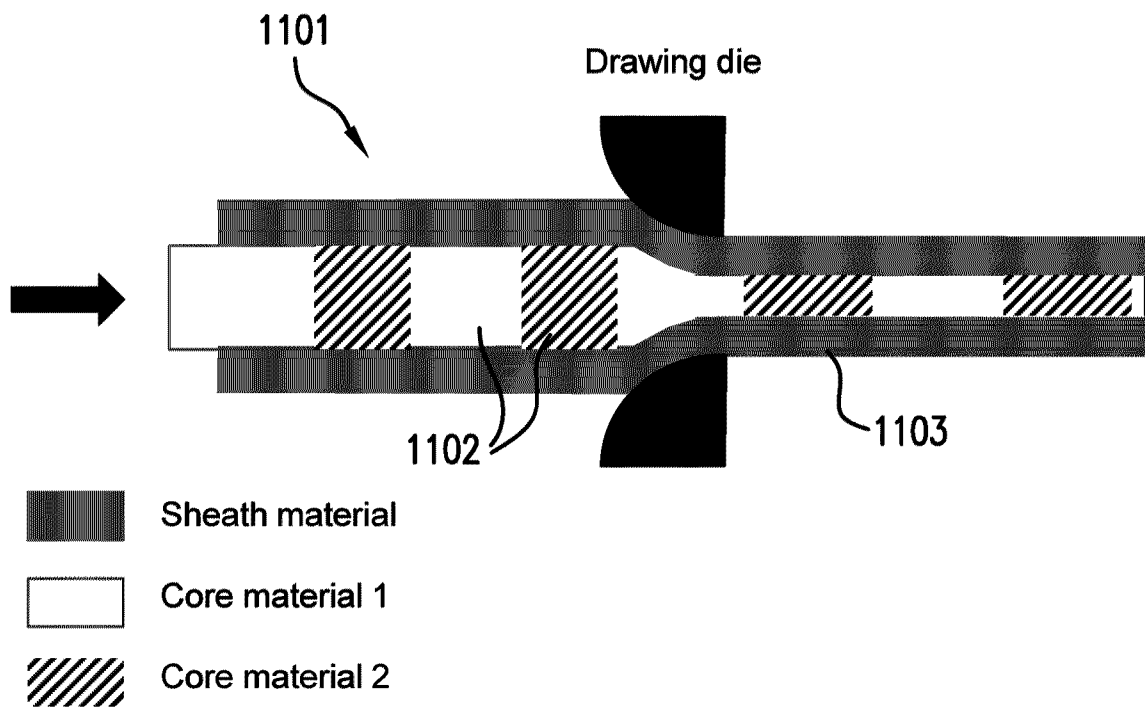


Fig. 11

Fig. 12(A)

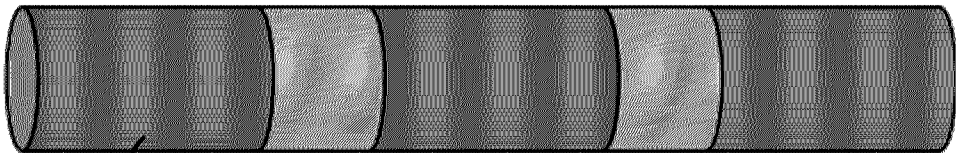


Fig. 12(B)

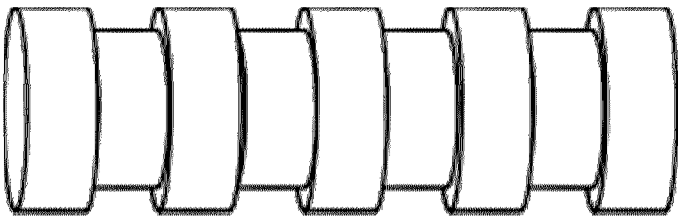


Fig. 13 (A)

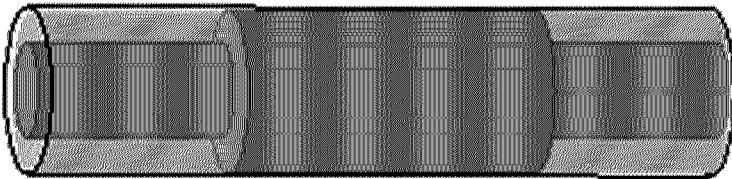


Fig. 13 (B)

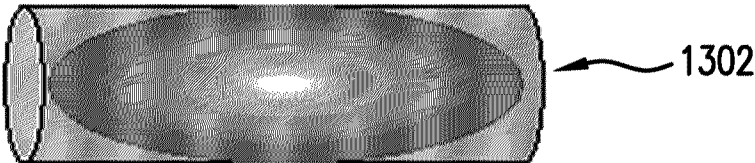


Fig. 13 (C)

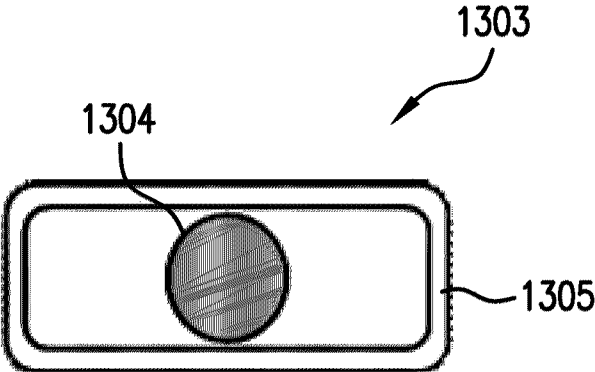


Fig. 14(C)

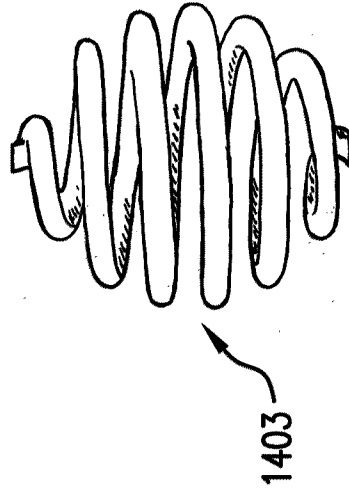


Fig. 14(B)

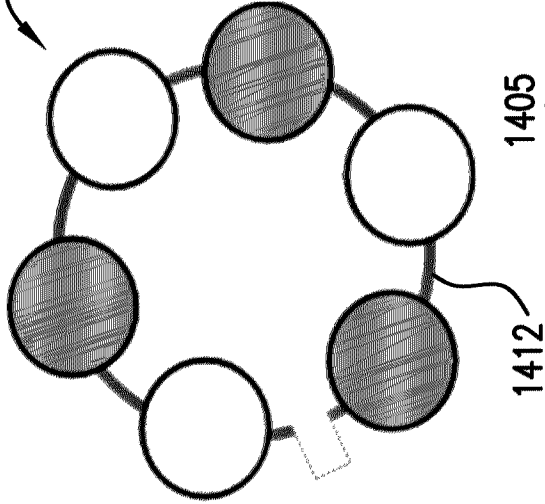


Fig. 14(E)

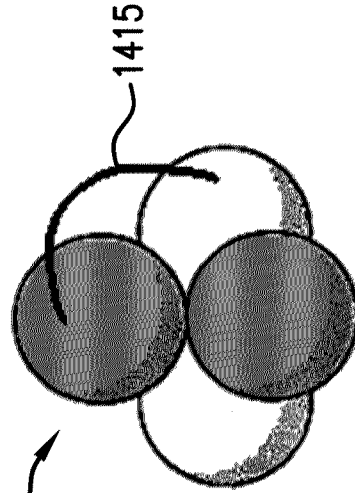


Fig. 14(A)

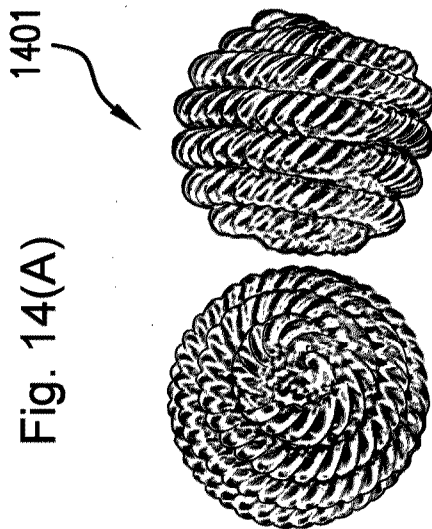
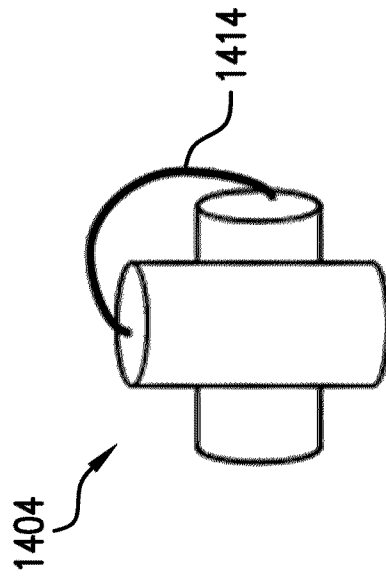
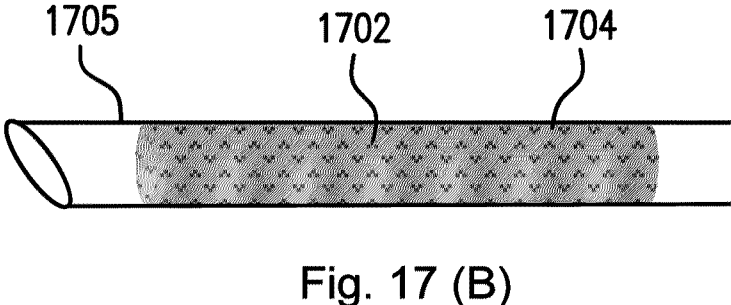
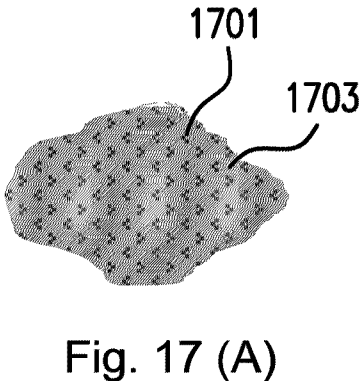
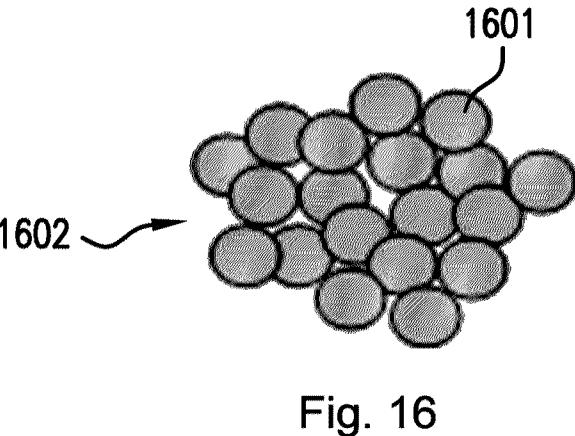
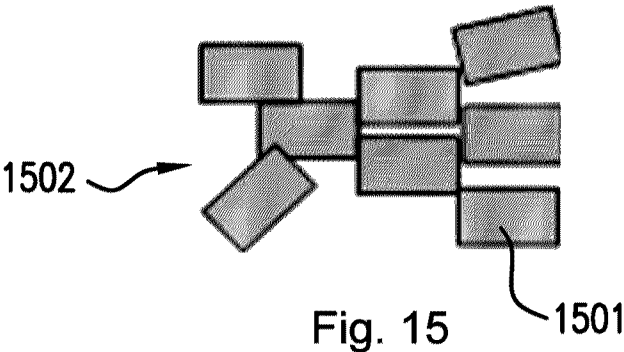


Fig. 14(D)





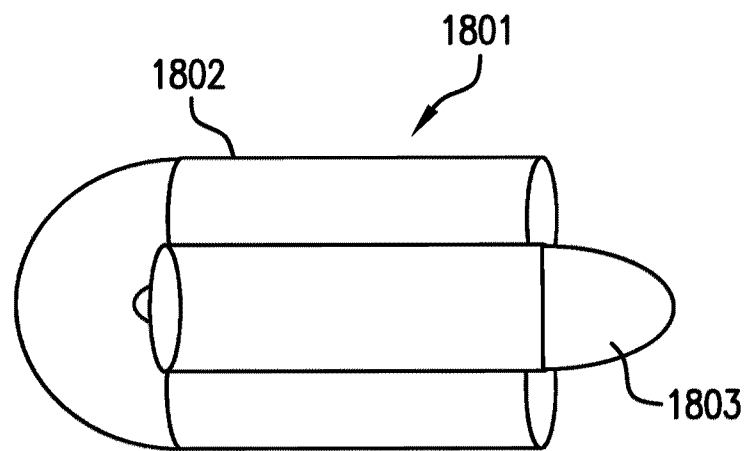


Fig. 18

